

CALCULATION CONTROL SHEET

Calculation No. JAF-CALC-HPCI-02094
Mod./Task No. N/A

Revision 0

IP3 JAF

QA Category of Calculation: I Calculation Type: Preliminary Final

Project/Task: Generic Letter 89-10 MOV Analysis - Available Voltage/ Motor Torque
System No./Name: 23/ High Pressure Coolant Injection
Title: Reduced Voltage Analysis for 23MOV-19

	Name	Signature	Date
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PROBLEM / OBJECTIVE / METHOD See Page 1
DESIGN BASIS / ASSUMPTIONS See Page 1
SUMMARY / CONCLUSION Minimum motor terminal voltage = 81.036 volts. However, with the Limitorque Maintenance Update 88-1 technique, available motor torque at minimum voltage was calculated as greater than or equal to the rated start torque, therefore the reduced voltage factor (RVF) may be considered as equal to 1.0 (no credit for more than rated start torque). See page 4 for additional discussion.
REFERENCES See Page 1
AFFECTED SYSTEMS / COMPONENTS / DOCUMENTS MOV analysis performed in accordance with MES-6; the alternate reduced voltage factor may be used to assess MOV capability.
<p><input type="checkbox"/> VOIDED OR</p> <p><input type="checkbox"/> SUPERSEDED BY: _____</p> <p align="center">(Calc. No.)</p> <p align="center">FOR REFERENCE ONLY</p>

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Calculation No. JAF-CALC-HPCI-02094 Revision 0 Page 1 of 4
Subject: Reduced Voltage Analysis for 23MOV-19

Prepared by: Paul Swinburne *PS*

Date: June 9, 1995

Checked by: F.A. Mulcahy *FM*

Date: 6-9-95

OBJECTIVE:

Determine motor terminal voltage and available motor torque under design basis degraded voltage conditions.

METHOD:

Determine minimum motor terminal voltage with the simple voltage divider analysis of the circuit model shown in the Figure 1 one line diagram. If the calculated motor terminal voltage is less than 90% of rated voltage then determine the reduced voltage factor (RVF). Calculate available motor torque from motor performance curve as described in Limitorque Maintenance Update 88-1 (ref. 13). This technique may be used to justify a higher RVF.

ASSUMPTIONS:

1. Assume cable temperature outside containment is 75°C (this assumption was used for the General Physics Generic Letter 89-10 analyses).
2. Assume EQ qualified BMCC temperatures for the thermal overload relay heaters (for BMCC-6: 131°F or 55°C).
3. Assume cable resistance from the National Electric Code (NEC).
4. Assume locked rotor current at rated voltage from motor nameplate or motor actuator data sheet.
5. Assume bus or BMCC source voltages from the battery duty cycle calculations (ref. 6) for MOVs in the battery duty cycle. Assume end of duty cycle battery voltage for MOVs which do not operate as part of the battery duty cycle (ref. 7).
6. Assume negligible effect from parallel current flow through high resistance shunt field winding.
7. Assume 10 ft length for unnumbered cable from junction box to MOV.

REFERENCES:

1. JAF Electrical Cable and Raceway Information System, Cable Schedule Report, Feb. 1, 1994.
2. Wiring Diagram Drawing SE-10AJ.
3. PEDB for Motor Controller, Equipment Name Plate Inquiry (overload heater number).
4. Earley, M.W. et al, Ed., *National Electric Code 1990 Handbook*, Chapter 9, Tables 8 and 9, National Fire Protection Association.
5. Marks, L.S., *Standard Handbook for Mechanical Engineers*, eighth edition, 1979.
6. Calculations JAF-CALC-ELEC-00426, Rev. 1 and JAF-CALC-ELEC-00427, Battery "A" and "B" 125 VDC Voltage Drop Analyses, approved 10/16/92 and 6/4/92.
7. NYPA Memorandum to P. Swinburne from T. Klein, NED-E-TK-92-162, DC MOV Degraded Voltage, dated August 25, 1992.
8. Limitorque Technical Update #92-02, Recommended Spring Pack Replacement Procedures for Limitorque SMB Actuators, issued October 9, 1992.
9. Fax Transmittal, C. Shirley (GE) to P. Swinburne (NYPA), CR123C,F,K,L size 1,2,3&4 Heater Resistances, March 22, 1993.
10. Limitorque Data Sheets for O/N 110119.01 (M1-87-026).
11. Peerless-Winsmith DC Motor Performance curves provided under P.O. S-91-12145.
12. JAF EQ Program, Environmental Parameters after Postulated LOCA and HELB Accidents, Rev. 3, October 1992, EQ Ref. #349.
13. Limitorque Maintenance Update 88-1, "Notes from the Field", DC Motors, dated Aug. 17, 1988.

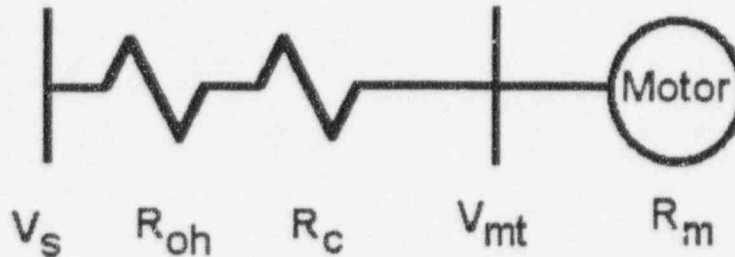


Figure 1 - DC Motor Circuit One-Line Diagram

Motor Data (references 10 and 11):

Rated Voltage: $V_r = 125$ volt Frame: D225 RPM: 1900
 Locked Rotor Amps: $I_{lr} = 810$ amp Rated run amps: $I_{run} = 80$ amp
 Rated Start Torque: $T_{st} = 150$ ft lbf Curve: K-11216A

Cable Data (references 1, 2 and 4):

	Length	DC Resistance at 75°C
1HPIBBK042 (NFF-51, 1 cond. 750 MCM Al)	$L_1 = 110$ ft	$SR_1 = 0.0282 \cdot \frac{\text{ohm}}{\text{ft} \cdot 10^3}$
1HPIBBK041 (NFE-25, 3 cond. 500 MCM Al)	$L_2 = 120$ ft	$SR_2 = 0.0424 \cdot \frac{\text{ohm}}{\text{ft} \cdot 10^3}$
JB to MOV (2 NFE-08, 4 cond. 8 AWG Cu)	$L_3 = 10$ ft	$SR_3 = 0.786 \cdot \frac{\text{ohm}}{\text{ft} \cdot 10^3}$

Outside Containment Cable Temperature: $Temp_c = 75$

BMCC Minimum Voltage: $V_s = 107.44$ volt

Calculation JAF-CALC-ELEC-00427 determined the above BMCC voltage for 23MOV-19 based on operation at the 19th second of the two hour duty cycle.

Overload Heater Data (references 3, 5, 9 and 12):

Number: F104C Resistance: $R_{25} = 9.49 \cdot 10^{-4}$ ohm (at 25°C)
 Temperature Coefficient: $TC_{oh} = 0.17 \cdot 10^{-3}$ (from Marks' for nichrome)
 Ambient Temperature (°C): $Temp_{oh} = 55$ (EQ temperature for BMCC-6)

Total cable resistance (for four runs for armature and series field):

$$R_c = SR_1 \cdot L_1 + 3 \cdot SR_2 \cdot L_2 + 4 \cdot SR_3 \cdot L_3 \quad R_c = 0.0498 \cdot \text{ohm}$$

Overload heater resistance (two heaters in parallel) corrected for temperature:

$$R_{oh} = \frac{R_{25}}{2} \cdot [1 + TC_{oh} \cdot (\text{Temp}_{oh} - 25)] \quad R_{oh} = 4.769 \cdot 10^{-4} \cdot \text{ohm}$$

Motor equivalent resistance:

$$R_m = \frac{V_r}{I_{lr}} \quad R_m = 0.154 \cdot \text{ohm}$$

Maximum current:

$$I_{max} = \frac{V_s}{R_m + R_c + R_{oh}} \quad I_{max} = 525.1 \cdot \text{amp}$$

Minimum motor terminal voltage:

$$V_{mt} = I_{max} \cdot R_m \quad V_{mt} = 81.036 \cdot \text{volt}$$

Percent rated voltage available:

$$\text{Percent}_{rated} = \frac{V_{mt}}{V_r} \quad \text{Percent}_{rated} = 64.829 \cdot \%$$

Because percent rated voltage is less than 90%, we need calculate a reduced voltage factor (RVF).
For DC motors the RVF is simply the percent of rated voltage expressed as a fraction (ref. 8).

Reduced voltage factor:

$$RVF = \text{Percent}_{rated} \quad RVF = 0.648$$

Per LMU 88-1 maximum current as
multiples of rated FLA:

$$\frac{I_{max}}{I_{run}} = 6.564$$

Cable size does meet Limitorque's
recommendation to provide 5 times
rated current (FLA)

Evaluate torque available based on motor curve K-11216A. Apply conservative +15% to current vs.
torque curve.

Motor curve K-11216A for 150 ft-lbf motor, as 3rd order polynomial:

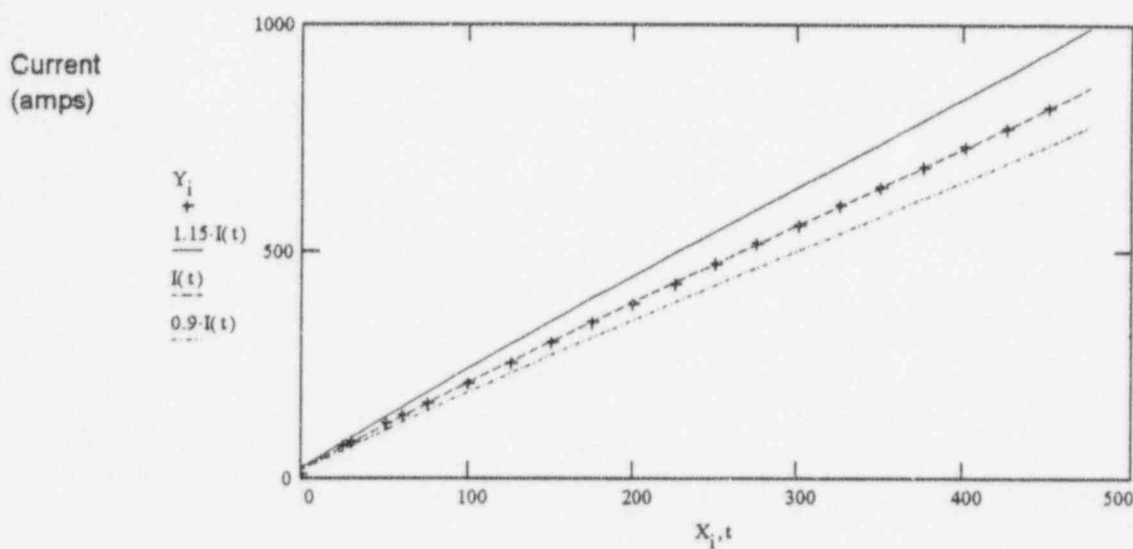
Data points from recorded data files:

$$i := 0..20 \text{ (21 data points)} \quad X := \text{READPRN}(tq150) \quad Y := \text{READPRN}(amps150)$$

Vector for curve fit: $F(x) = \begin{bmatrix} x^3 \\ x^2 \\ x \\ 1 \end{bmatrix}$ 3rd order fit function: $S = \text{linfit}(X, Y, F)$ $S = \begin{bmatrix} 1.408 \cdot 10^{-6} \\ -0.001 \\ 2.033 \\ 18.278 \end{bmatrix}$

Current from curve fit polynomial: $I(t) = F(t) \cdot S$ $t = 0, 25, \dots, 475$

Curve K-11216A showing +15%/-10% limits:



$I_{\max} = 525.1 \text{ amp}$

Motor torque (ft-lbf)

guess value: $t = 100$

Available torque at I_{\max}

(with +15% allowance) is: $\tau_{\text{avail}} = \text{root}(1.15 \cdot I(t) \cdot \text{amp} - I_{\max, t}) \cdot \text{ft} \cdot \text{lbf}$ $\tau_{\text{avail}} = 240.166 \cdot \text{ft} \cdot \text{lbf}$

The above torque is greater than the rated torque for this motor (150 ft-lbf). We should not take credit for more than rated torque capability but we need not apply an RVF.

CONCLUSION:

This analysis shows that 23MOV-19 has less than 90% of rated voltage available under degraded voltage conditions. If we consider the guidelines for motor torque capability provided in LMU 88-1 (ref. 13) and motor curve K-11216A (ref. 11) we can show more than rated torque capability at reduced voltage conditions. Therefore we can use RVF = 1.0.

**DESIGN VERIFICATION CHECKLIST
DESIGN REVIEW METHOD**

	Yes	NA
8. Have the design interface requirements been satisfied ?	<input type="checkbox"/>	<input checked="" type="checkbox"/>
9. Was an appropriate design method used ?	<input checked="" type="checkbox"/>	<input type="checkbox"/>
10. Is the output reasonable compared to inputs ?	<input checked="" type="checkbox"/>	<input type="checkbox"/>
11. Are the specified parts, equipment and processes suitable for the required application ?	<input type="checkbox"/>	<input checked="" type="checkbox"/>
12. Are the specified materials compatible with each other and the design environmental conditions to which the materials will be exposed ?	<input type="checkbox"/>	<input checked="" type="checkbox"/>
13. Have adequate maintenance features and requirements been satisfied ?	<input type="checkbox"/>	<input checked="" type="checkbox"/>
14. Are accessibility and other design provisions adequate for performance of needed maintenance and repair ?	<input type="checkbox"/>	<input checked="" type="checkbox"/>
15. Has adequate accessibility been provided to perform the in-service inspection expected to be required during the plant life ?	<input type="checkbox"/>	<input checked="" type="checkbox"/>
16. Has the design properly considered radiation exposure to the public and plant personnel ? (ALARA / Cobalt Reduction)	<input type="checkbox"/>	<input checked="" type="checkbox"/>
17. Are the acceptance criteria incorporated in the design documents sufficient to allow verification that design requirements have satisfactorily accomplished ?	<input checked="" type="checkbox"/>	<input type="checkbox"/>
18. Have adequate pre-operational and subsequent periodic test requirements been appropriately specified ?	<input type="checkbox"/>	<input checked="" type="checkbox"/>
19. Are adequate handling, storage, cleaning and shipping requirements specified ?	<input type="checkbox"/>	<input checked="" type="checkbox"/>

**DESIGN VERIFICATION CHECKLIST
DESIGN REVIEW METHOD**

	<u>Yes</u>	<u>NA</u>
20. Are adequate identification requirements specified ?	<input type="checkbox"/>	<input checked="" type="checkbox"/>
21. Are conclusions drawn in the Safety Evaluation fully supported by adequate discussion in the test or Safety Evaluation itself ?	<input type="checkbox"/>	<input checked="" type="checkbox"/>
22. Are necessary procedural changes specified, and are responsibilities for such changes clearly delineated ?	<input type="checkbox"/>	<input checked="" type="checkbox"/>
23. Are requirements for records preparation, review, approval, retention, etc., adequately specified ?	<input type="checkbox"/>	<input checked="" type="checkbox"/>
24. Have supplemental reviews by other engineering disciplines (seismic, electrical, etc.) been performed on the integrated design package.	<input type="checkbox"/>	<input checked="" type="checkbox"/>
25. Have the drawings, sketches, calculations, etc. included in the intergrated design package been reviewed ?	<input checked="" type="checkbox"/>	<input type="checkbox"/>
26. Have review been performed to identify any effect on the Check Valve Maintenance Program ?	<input type="checkbox"/>	<input checked="" type="checkbox"/>
27. Does the design for check valves meet the intents of INPO SOER 86-03 ?	<input type="checkbox"/>	<input checked="" type="checkbox"/>
28. Is the plant reference simulator physical and functional fidelity affected and it's design change been factored into the cost ?	<input type="checkbox"/>	<input checked="" type="checkbox"/>
29. References used as part of the design review which are not listed as part of the design calculation / analysis ?	<input type="checkbox"/>	<input checked="" type="checkbox"/>