NEDO-30641A REVISION 1 CLASS I SEPTEMBER 1984

CONCEPTUAL DESIGN DESCRIPTION
FOR THE PILGRIM NUCLEAR POWER STATION
EMERGENCY AND PLANT INFORMATION
COMPUTER (EPIC) SAFETY PARAMETER
DISPLAY SYSTEM (SPDS)

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GENERAL ELECTRIC COMPANY

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SAFETY PARAMETER DISPLAY SYSTEM (SPDS)

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ACRONYMS AND ABBREVIATIONS

20	- Two-Dimensional
APRM	- Average Power Range Monitor
BECO	- Boston Edison Company
BPV	- Bypass Valve
BRKR	- Breaker
BWR	- Boiling Water Reactor
BWROG	- BWR Owners Group
C1	
	 Contingency for Level Restoration Contingency for Emergency RPV Depressurization
C2 C3	0 11 0 0 0 11
C4	C. C. C. C. Italian debaut Lauri Destauation
C5	- Contingency for Core Cooling without Level Restoration
	- Contingency for Alternate Shutdown Cooling
C6	- Contingency for RPV Flooding
C7	- Contingency for Level/Power Control
CAP	- Capacity
CMD	- Command
CNTMT	- Containment
CRD	- Control Rod Drive
CRT	- Cathode Ray Tube
DA	- Data Acquisition
DEC	- Digital Equipment Corporation
DG	- Diesel Generator
DNSCL	- Downscale
DW	- Drywell
EMERG	- Emergency
EOF	- Emergency Offsite Facility
EOP	- Emergency Operating Procedure
EPG	- Emergency Procedure Guideline
EPIC	- Emergency and Plant Information Computer
ERIS	- Emergency Response Information System
FAC	- Facility
GDC	- Graphics Display Console
GE	- General Electric Co.
GEDAC	- General Electric Data Acquisition
GEPAC	- General Electric Existing Process Computer System
HFE	- Human Factors Engineering
HI	- High
HPCI	- High Pressure Coolant Injection
IOM	- Input/Output Module
LCO	- Limiting Condition for Operation
LD	- Load
LO	- Low
LPCI	- Low Pressure Coolant Injection
LPCS	- Low Pressure Core Spray
MMI	- Man Machine Interface
MSIV	- Main Steam Isolation Valve
NRC	- Nuclear Regulatory Commission
OPER	- Operating

ACRONYMS AND ABBREVIATIONS (Continued)

- Performance Monitoring PNPS - Pilgrim Nuclear Fower Station PR - Pressure QAP - Quality Audit Points RCIC - Reactor Core Isolation Coolant RPV - Reactor Pressure Vessel RTAD - Real Time Analysis and Display RWCU - Reactor Water Clean Up

- Reactor RX SAT - Saturation

SBGT - Standby Gas Treatment

SCRM - Scram

SLC - Standby Liquid Control

SPDS

- Safety Parameter Display System - Safety Relief Valve - Top of Active Fuel SRV TAF

TEMP - Temperature

TRA - Transient Recording and Analysis

TSC - Technical Support Center Validation and Verification
 Vacuum
 Wetwell V&V

VAC WW

1.0 INTRODUCTION

As a result of the accident at Three Mile Island, the Nuclear Regulatory Commission (NRC) has determined the need for a Safety Parameter Display System (SPDS) which provides a concise display of critical plant operating variables. Its intended role is to provide vital plant data to aid control room personnel in determining the safety status of the plant during emergency conditions. The NRC requirements for the SPDS are contained in Supplement 1 to NUREG 0737 "Requirements for Emergency Response Capability" (Reference 1).

The SPDS portion of the Pilgrim Nuclear Power Station (PNPS) Emergency and Plant Information Computer (EPIC) meets the NRC requirements for an SPDS, in that, it provides aid to the operator in determining the safety status of the plant during abnormal or emergency conditions. The graphic displays available to the control room operator are based on the Emergency Procedure Guidelines (EPGs) Revision 2 and are formatted to give maximum assistance in following the Pilgrim Nuclear Power Station Emergency Operating Procedures (EOPs). Human factors engineering has also been taken into account during development of the Pilgrim SPDS to maximize the operators abilities to readily determine plant status and to minimize errors by the operator during its use.

The PNPS SPDS is being added as an aid to plant operators. It is not intended as a substitute for other safety-related equipment or instrumentation, but rather as an adjunct to such equipment. The PNPS SPDS is not essential to the safe operation of the plant, it is not essential to the prevention of events inimical to the public health and safety, nor is it essential to the mitigation of the consequences of an accident. Further, PNPS SPDS does not constitute a significant hazard as defined by the criteria of 10CFR50.92 and as exampled in 48FR14870. This means that the operation of Pilgrim Station after the incorporation of PNPS SPDS will not: (1) involve a significant increase in the probability or consequences of an accident previously evaluated; or (2) create the possibility of a new or different kind of accident from any accident previously evaluated; or (3) involve a significant reduction in a margin of safety.

This report addresses the requirements of Supplement 1, Section 4, NUREG 0737, by including the bases on which the selected parameters were judged to be sufficient to assess the safety status of the Pilgrim Nuclear Power Station (PNPS). As such, this report constitutes the safety analysis report required by the NRC to satisfy the SPDS documentation requirements of Supplement 1 to NUREG 0737.

In addition to the basis for parameter selection, this report discusses other aspects of the PNPS SPDS in relation to the NRC requirements. Among these are general descriptions of the system which provides the PNPS SPDS function, general descriptions of the various displays available to the PNPS SPDS users, the bases for those displays, the human factors implementation plan and the verification and validation features used in the development of the PNPS SPDS.

2.0 EPIC SYSTEM DESCRIPTION

2.1 GENERAL

The Pilgrim Nuclear Power Station (PNPS) Emergency and Plant Information Computer (EPIC) is a centralized, integrated system which performs the process monitoring and calculations defined as being necessary for the effective evaluation of normal and emergency power plant operation. The EPIC acquires and records process data including temperatures, pressure, flows, and status. This data is then processed by the EPIC to produce meaningful displays, logs, and plots of current or historical plant performance and presented to plant personnel in the plant main control room or other user definable locations. A system hardware diagram is provided as Figure 2-1. This diagram shows Man Machine Interface (MMI) hardware in the various plant locations, as well as a basic hardware configuration.

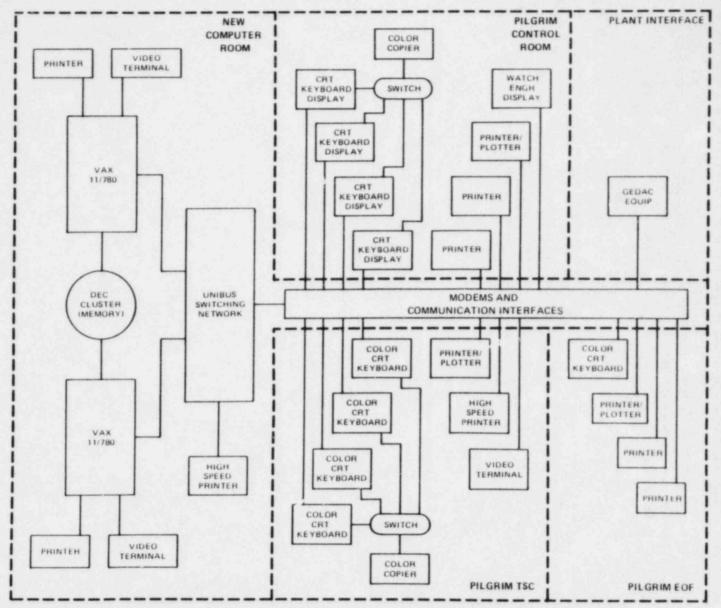
The major functions of the EPIC System are described below:

- Main Processing Functions performs functions entailing basic data manipulations and preprocessing.
- Man Machine Interface performs the function of interfacing the human with the EPIC system.
- Data Acquisition Functions performs data acquisition and plant process instrumentation interface.
- d. Performance Monitoring Functions performs all functions necessary to evaluate the performance of the Nuclear Steam Supply System and Balance of Plant.
- e. Transient, and Recording and Analysis Functions performs analysis logging, plotting and recording functions.
- f. Real-Time Analysis and Display Functions performs all functions required to produce displays including display building and dynamic display processing functions.

A brief description of each major function is provided below.

2.2 MAIN PROCESSING FUNCTIONS

Main processing functions are those functions which are generic in nature and perform basic data preparation functions. Included in these functions are conversions, evaluation, alarming and data definition functions. This function of the EPIC performs any generic calculations and processing of data for display or further analysis. These functions include point compositions



w

Figure 2-1. EPIC Hardware Configuration

(generation of a point from 2 or more other points), limit checking, complex algorithm processing, and engineering unit conversions. In addition many system level functions such as database building and security control (password, key lock, etc.) are a part of this EPIC function.

2.3 MAN-MACHINE INTERFACE

The Man-Machine Interface (MMI) performs the function of interfacing the EPIC with plant personnel. Using the interface, the user can place demands on the system or acknowledge information received by the system. The interface also presents the results of monitoring, calculations, and control actions taken to the user. MMI hardware consists of keyboards, function keys, CRT's, printers and typers.

2.4 DATA ACQUISITION (DA)

The Data Acquisition functions will perform the function of interfacing the EPIC with process variable instrumentation. This interface function is able to acquire real-time analog, digital, and pulse data simultaneously from the process instrumentation and make that data available to the EPIC. The Data Acquisition function has the ability to gather data at specified rates and is capable of accommodating user specific requirements for the gathering and transmitting of that process data.

The Data Acquisition function is provided by a modular set of solid state components. The data acquisition function samples the plant signals at rates of up to 250 samples/second for analog signals and 500 samples/second for digital signals. The data acquisition portion of the EPIC has provisions for checking, signal loop calibration, signal conditioning and self-testing. In addition, incoming data is provided with "time tags" in order to provide Sequence of Events determination. The data is interfaced with plant sensors via Input/Output modules (IOMs) and transmitted by fibre-optic cable in order to provide a means to isolate the EPIC from existing plant equipment. Transmission via wire cable is also provided where isolation is not required.

2.5 PERFORMANCE MONITORING (PM)

The Performance Monitoring (PM) functions provide monitoring of total plant performance. The PM, in addition to being an evaluation tool, also aids in providing efficiency of plant operation. Evaluations are performed including, but not limited to, thermal power distribution, thermal limit margins, energy summaries, exposure accumulations, enthalpies, data summaries, calibration and diagnostics for analysis of the nuclear steam supply. In addition, provisions are available to include Balance of Plant performance calculation capabilities for turbine cycle, condenser, electrical, and feedwater heater performance analysis.

2.6 TRANSIENT RECORDING AND ANALYSIS (TRA)

The Transient Recording and Analysis (TRA) functions provide a real-time and historial perspective for the operation of the power plant. The purpose of the TRA functions is to provide high resolution recording capabilities for various plant parameters and means for event monitoring, data archival, plotting, trending, analyses, automatic and on-demand logging.

The TRA portion of the EPIC provides a means of data recording, archiving and analysis in order to support the determination and analysis of plant transients. Data recording and archiving capabilities can record changing plant parameters for up to 2-hours of pre-event data and 12-hours of post-event data. Data is then available for various outputs such as alarm logs, sequence of events report, trending, post trip logs, significant change reporting and plotting. In addition analysis routines are available to provide statistical evaluation (such as means minimums, maximums, standard deviations) and time series analysis.

2.7 REAL-TIME ANALYSIS AND DISPLAY (RTAD)

The Real-Time Analysis and Display (RTAD) functions provide automatic reporting and display updating of plant parameters for current user requests. The RTAD shows critical plant parameters such as water levels, temperatures, pressures, flows, and status of pumps, valves, and other equipment. The RTAD is also capable of showing plant operational parameters.

The Real-Time Analysis and Display (RTAD) function of the EPIC provides real-time color graphic displays to provide a medium for the SPDS requirements of NUREG 0737, Supplement 1. The Real-Time Analysis and Display function provides the capability to display sampled data, status indications, synthesized data and trends. Displays on the RTAD hardware are updated at least every 2 seconds. Trend information an also be provided for up to 60 minutes of data. In addition to display capability, the RTAD function provides display creation functions.

The specific displays which are provided by the Emergency Plant and Information Computer (EPIC) in order to meet the requirements of NUREG 0737, Supplement 1 and the design basis for these displays, are described in more detail in the following sections.

3.0 DISPLAY BASIS

The basis for each PNPS SPDS color-graphic display is the display user's emergency response information requirements. These requirements are determined by the user's emergency response functions, which are defined by the Pilgrim Nuclear Power Station (PNPS) Emergency Operating Procedures (EOPs) (Reference 2) as developed from the generic Emergency Procedure Guidelines (EPGs) (Reference 3).

3.1 PLANT CHARACTERISTICS

The direct cycle Boiling Water Reactor (BWR) exhibits a number of features which facilitate emergency operation. Because of the large passive heat sink in the containment and suppression pool, the operator can initially concentrate his attention during an emergency on the primary objective of maintaining reactor water level. Following actions to stabilize reactor parameters, containment control actions are taken. Other features of BWRs include a strong natural circulation combined with low power density so that core coverage assures adequate cooling, diverse and redundant water delivery systems, and complete Reactor Pressure Vessel (RPV) depressurization capability. In addition, operation of a BWR during an emergency has important similarities to normal operation. These similarities include use of normal plant systems as the first line of defense, and emergency operation with boiling in the reactor core which is familiar to plant operators.

The mechanisms by which a BWR may get into a nonsafe condition are by inadequate makeup of coolant to the RPV and inadequate long term heat removal. Adequate liquid makeup to the RPV may be monitored using RPV water level. Water level control is a function of reactor power, since as power varies the boil off rate varies which will influence the amount of water makeup required. Note that reactor power also impacts the long term heat removal capability. A plant which is isolated from the main condenser, and is putting heat into the containment, could exceed the containment heat capacity within a moderately short time period (less than an hour) if the reactor power is not reduced or the plant shutdown.

PNPS has many diverse and redundant injection systems that operate over various pressure ranges to provide RPV water level makeup. The majority of the emergency core cooling systems (spray and injection) operate over low RPV pressure ranges. Hence, reactor pressure control is important to assure that RPV water level can be maintained.

The most effective long term heat removal is provided by the main condenser. However, when the plant is isolated, the suppression pool serves both as a heat sink and as an emergency water source. The suppression pool's ability to perform both these functions can be monitored using suppression pool temperature and water level.

The primary containment pressure suppression design works to prevent releases of radioactivity to the outside environment which may be caused by primary system leaks or breaks. The pressure suppression function efficiency

can be monitored using containment pressure. If the pressure is maintained low, containment integrity is maintained with the associated ability to quench steam discharges from the RPV or containment and to serve as a boundary to protect the public health and safety.

Drywell temperature is another measure of the ability to maintain the plant in a safe stable condition. Equipment in the drywell which is important to maintaining RPV water level (e.g., injection valves, water level monitoring instrument lines, safety/relief valves) may be adversely affected by its environmental temperature. In addition, the containment pressure will be influenced by the airspace temperature. Therefore drywell temperature is another important parameter for monitoring and display.

In summary, the EPG Control parameters important to plant safety are

- RPV water level.
- RPV pressure,
- reactor power,
- suppression pool temperature,
- suppression pool water level,
- containment pressure (drywell and suppression chamber), and
- drywell temperature.

The operator response in a BWR is basically the same for all events. Simplistically, this two-part response consists first of maintaining reactor water level, and second of establishing long-term heat removal after reactor water level is stabilized. The monitoring and control of the above parameters will assure the plant is maintained in a safe stable condition.

3.2 EMERGENCY PROCEDURE GUIDELINES (EPG's)

The common operator response to all inventory threatening events facilitated the development of generic EPGs which are symptom based as opposed to event based. The operator does not need to diagnose what off-normal event is occurring in the plant in order to decide what actions to take. Rather, he observes the symptoms which exist and takes actions based on controlling those symptoms.

The generic symptomatic EPGs which have been developed (Revision 2) are:

- RPV Control Guideline
- Primary Containment Control Guideline

The guideline structure is illustrated in Figure 3-1. The RPV Centrol Guideline provides instructions to maintain adequate core cooling, shut down the reactor, and cool down the RPV to cold shutdown conditions. The entry conditions to the RPV Control Guideline are any of the following:

- RPV water level below the low level scram setpoint
- RPV pressure above the high pressure scram setpoint

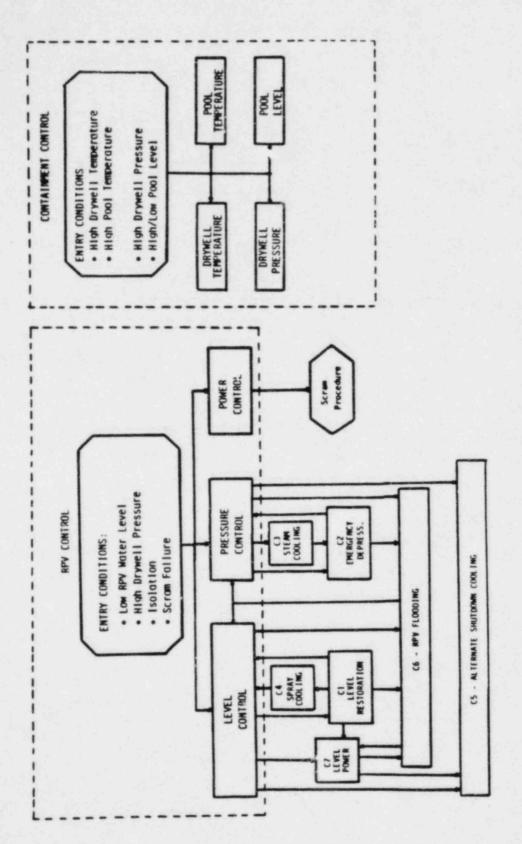


Figure 3-1.

- Drywell pressure above the scram setpoint
- An isolation which requires or initiates reactor scr_1
- A condition which requires reactor scram, and reactor power above the APRM downscale trip or reactor power cannot be determined.

The RPV Control Guideline provides instructions to control the key parameters of RPV water level, RPV pressure, and reactor power in parallel. The actions specified are designed to maintain the RPV water level in a satisfactory range, assure the reactor is shutdown, control reactor pressure to limit Safety Relief Valve (SRV) cycling and cooldown the reactor as necessary. Note that reactor power and cooldown rate will not be important at the same time. During the initial transient, reactor water level, reactor pressure and reactor power will be the key control parameters. Once the reactor is shutdown, RPV water level, pressure, and temperature/cooldown rate will be the key control parameters.

The Primary Containment Control Guideline provides instructions to maintain primary containment integrity and protect equipment in the primary containment. The entry conditions for the Containment Control Guideline are any of the following:

- Suppression pool temperature above its normal operating Limiting Condition for Operation (LCO)
- Suppression pool water level above its maximum LCO
- Suppression pool water level below its minimum LCO
- Drywell temperature above its LCO
- Drywell pressure above the scram setpoint.

This guideline provides instruction to control the key parameters of suppression pool temperature and water level, drywell temperature, and containment pressure in parallel. The actions are designed to mitigate the containment response to any event and restore and maintain these parameters in their normal ranges. Since containment response may be impacted by reactor conditions (e.g., cycling SRVs causing pool heatup), this guideline contains separate instructions to scram and depressurize the reactor when the containment control parameters reach specific values.

The EPG also contains seven contingencies as follows

- C1 Level Restoration
- C2 Emergency RPV Depressurization
- C3 Steam Cooling

- C4 Core Cooling Without Level Restoration (Spray Cooling)
- C5 Alternate Shutdown Cooling
- C6 = RPV Flooding
- C7 Level/Power Control.

The contingencies all provide instructions to control RPV water level and/or pressure. They are entered from the RPV Control Guideline or from each other whenever conditions defined in the guidelines dictate. For example, if water level is not being restored and maintained above the top-of-active fuel with the general actions specified in the RPV Control Guideline, the operator shifts to Contingency 1 (C1) where more explicit instructions are given in water level control. If the symptoms of water level, water level trend, reactor pressure range, and system availability evaluated in C1 dictate that emergency RPV depressurization is required, then the operator shifts from the pressure control section of the RPV Control Guideline to C2.

The NRC has written a later Evaluation Report (Reference 4) which approves Revision 2 of the generic BWR EPG's for implementation. The Pilgim EOPs are based upon and consistent with this revision and incorporate all the features of the generic EPGs which apply to the Pilgrim Nuclear Power Station. The PNPS EOPs utilize PNPS specific systems, curves, and values. The RPV Control Guideline and Contingencies have been combined as appropriate to integrate the new symptom based EOPs into the plant procedures.

3.3 REQUIRED INFORMATION

The displays given in Table 3-1 are designed to provide the specific information needed by each class of personnel in order for them to fulfill their assigned responsibilities. Though this information is generally available throughout the control room for the personnel located there, the SPDS function of the EPIC supplies this information accurately and concisely in a unified and centralized display of emergency response information. The EPIC is also capable of providing this full range of information to personnel in the Technical Support Center (TSC) and Emergency Offsite Facility (EOF). The displays listed in Table 3-1 provide sufficient information for each member of the emergency response team to perform his specific function. The basis for the information provided on each display is provided in the following paragraphs.

3.3.1 RPV Control Display

This display is based on the RPV Control Guideline and related contingencies in the EPGs.

^{*}General Electric Company Proprietary Information.

Table 3-1

SUMMARY OF SPDS DISPLAYS WITH RESPECT TO INTENDED USERS*

3.3.2 Containment Control Display

This display is based on the Containment Control Guideline in the EPGs.

3.3.3 Critical Plant Variables Display

This display is based on the entry conditions and control parameters in the EPGs. It is the top level safety parameter display.

3.3.4 Two-Dimensional Plots

Certain parameter levels and specific limits which indicate the need for action in the PNPS EOPs are two-dimensional plots (curves) which relate separate control parameters

3.3.5 Trend Plots

They are described in detail in

Section 4.

3.3.6 Validation Status Displays

Validation Status Displays are described in detail in Section 4.

3.4 SPDS REQUIREMENTS

NUREG 0737 Supplement 1 specifies the requirements for the information displayed by SPDS. These requirements are met by providing displays consistent with the EPGs/EOPs since the fundamental actions required to restore and maintain the plant in a safe stable condition are defined in the EPGs/EOPs.

The information display requirements extracted from NUREG 0737 Supplement 1 and the PNPS SPDS implementation which satisfies the requirements follows.

- "4.1.a provide a concise display of critical variables"
- "4.1.f The minimum information to be provided shall be sufficient to provide information to plant operators about:"

"(i)	Reactivity control"
"(11)	Reactor core cooling and heat removal from the primary system"
"(111)	Reactor coolant system integrity"
"(iv)	Radioactivity Control"

"(v) Containment conditions"

NUREG 0737 Supplement 1 Section 4.1.d further states that "The selection of specific information that should be provided for a particular plant shall be based on engineering judgment of individual plant licensees, taking into account the importance of prompt implementation." It is the judgment of the Boston Edison Company (BECO) that the displays defined herein provide sufficient information such that the PNPS SPDS together with the upgraded EOPs will provide a significant enhancement to plant safety.

4.0 DISPLAY DESCRIPTION

The displays presented in this section represent the mechanism through which the Boston Edison Company (BECO) will satisfy the SPDS requirements for the Pilgrim Nuclear Power Station (PNPS). The PNPS SPDS control room displays present the fundamental information needed by nuclear power plant personnel to respond to an emergency. Using standard alphanumeric keys, function keys and poke points at the graphic display console (GDC), the user can manually select displays for viewing on the cathode ray tube (CRT).

The displays available at each GDC consist of:

- a. Reactor Pressure Vessel (RPV) control displays,
- b. Containment control displays.
- c. Critical plant variables
- d. Two-dimensional (2D) plots
- e. Trend plots, and
- f. Validation status displays.

These displays provide real time data with emphasis on showing the current plant status and recent trend history. RPV control and containment control displays are keyed to the appropriate PNPS EOP's as described in Section 3.2. The critical plant variables display shows all of the PNPS EOP entry conditions. Trend plot displays contain real-time digital information, but their overall emphasis is to show the most recent trends. 2D plots present the limits defined in the PNPS EOPs which are curves showing the relationship between two parameters. Validation status displays supply an evaluation of plant control parameter signals.

Figures 4-1 through 4-8 are black and white copies of representative displays. Each display shows the color gun status, date and time, and the RPV/containment alarm indications. The status of the three color guns--red, blue, and green--are shown next to the plant name in the lower right-hand corner of each display. The current calendar date and time of day (expressed to the nearest second) are shown next to the color gun status indication.

4.1 RPV CONTROL DISPLAY

The display presents information using the criteria listed in Section 3.1. RPV Control Displays are shown in Figures 4-1 and 4-2.

4.1.1 System Status

As an operator proceeds through the PNPS EOP's, he is directed to access the status of systems necessary to perform certain actions. These systems are included in the system status section of the display.

The following lists the systems which are included in the system status section:

- a. Condensate/Feedwater, CRD, RCIC, HPCI, LPCS, and LPCI:
- b. Reactor Water Clean Up (RWCU):
- c. Turbine Bypass Valves:

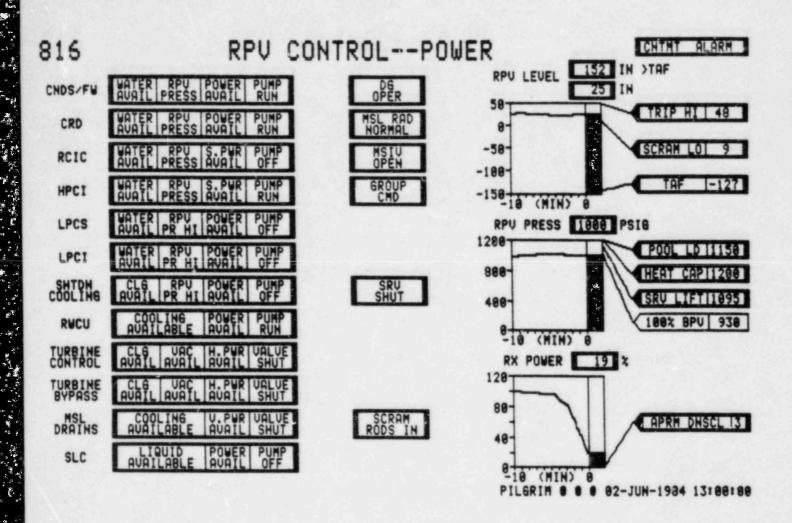


Figure 4-1. RPV Control with Power

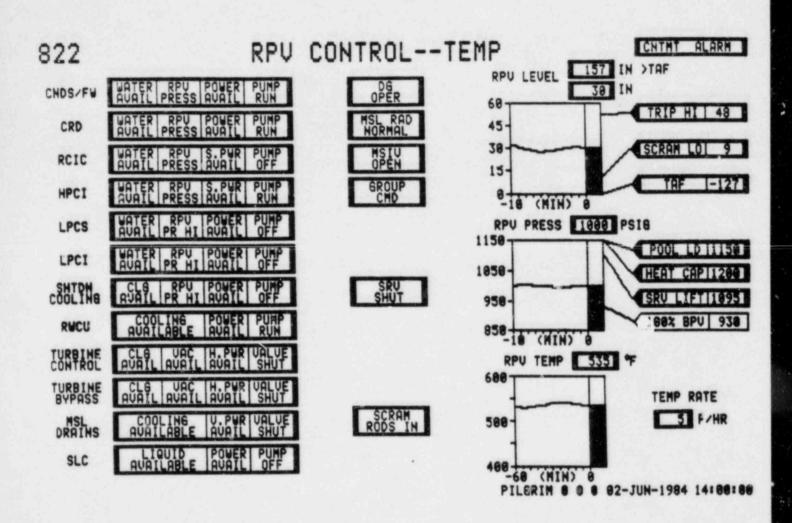


Figure 4-2. RPV Control with Temperature

d.	Turbi	ne	Control	Valv	es:
	-	STATE OF THE PERSON NAMED IN		-	Management .

- e. Main Steam Line Drain:
- f. Shutdown Cooling:
- g. Standby Liquid Control (SLC):

4.1.2 Event Targets

There are six event targets on the RPV Control Display. They give the status of the following "events".

- a. Group Isolation:
- b. Safety Relief Valve (SRV):
- c. Main Steam Isolation Valve (MSIV):
- d. Scram:
- e. Diesel Generator:
- f. Main Steam Line Radiation:

4.1.3 Control Parameter Trend Plots

Each control parameter, as defined in Section 3, is presented in a trend plot mini-display consisting of a time history data plot, bar graph, and digital readout. Control parameters for the RPV Control Display are RPV water level, pressure, and either reactor power (Figure 4-1) or RPV temperature (Figure 4-2).

All RPV control parameters are validated parameters.

The horizontal scale of the time history data plot for all control parameters is the most recent ten minutes with the exception of RPV temperature, for which the horizontal scale is the most recent sixty minutes.

4.1.4 Limit Tags

A control parameter may have up to five limit tags associated with it, each corresponding to a process limit identified by the PNPS EOPs. Table 4-1 lists the limit tags which are associated with each of the trend plots on the RPV Control Display.

Table 4-1
TREND PLOT LIMIT TAGS FOR RPV CONTROL DISPLAY

Control Parameter	Static Limits	Dynamic Limits	
RPV Water Level	Trip Hi, Scram Lo, TAF	None	
RPV Pressure	SRV Lift, 100% BPV*	Pool LD, Heat Cap	
Reactor Power	APRM DNSCL	None	
RPV Temperature	None	None	

^{*}Indicates a permissive limit

4.2 CONTAINMENT CONTROL DISPLAY

This top-level display provides control room operators with the primary plant information required to execute the PNPS EOP developed from the Containment Control Guideline. The display presents information using the criteria discussed in Section 3.1. Containment control displays are shown in Figures 4-3 and 4-4.

4.2.1 System Status

As an operator proceeds through the PNPS EOP's, he is directed to access the status of systems necessary to perform certain actions. These systems are included in the system status section of the display.

The following lists the systems which are included in the system status section:

- a. Pool Cooling:
- b. Drywell Cooling:
- c. Drywell Spray and Suppression Pool Spray:
- d. Standby Gas Treatment (SBGT):

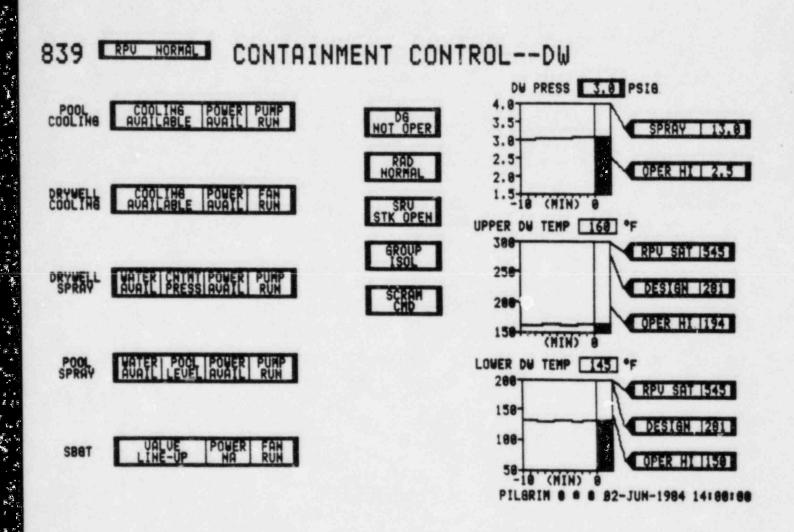


Figure 4-3. CNTMT Control, Drywell

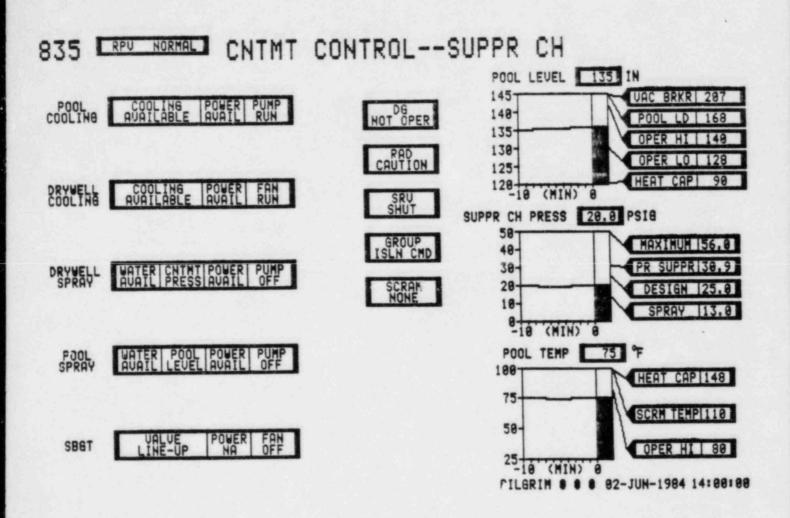


Figure 4-4. CNTNT Control, Suppression Chamber

4.2.2 Event Targets

There are five event targets on the Containment Control Display. They give the status of the following "events".

- a. Group Isolation (see Section 4.1.2)
- b. Safety Relief Valve (SRV) (see Section 4.1.2)
- c. Scram (see Section 4.1.2)
- d. Diesel Generator (see Section 4.1.2)
- e. Radiation:

4.2.3 Control Parameter Trend Plots

Control parameters plotted for the drywell containment control display are drywell pressure and upper and lower maximum drywell temperatures. Control parameters for the suppression chamber containment control display are suppression chamber pressure, suppression pool temperature, and suppression pool water level. Except for the drywell temperatures, all containment control parameters are validated parameters. The trend plot description is the same as given in Section 4.1.3.

4.2.4 Limit Tags

As on the RPV Control Display, limit tags are associated with each of the trend plots on the Containment Control Display. The limit tag description is the same as given in Section 4.1.4. Table 4-2 lists the limit tags which are associated with each of the trend plots on the containment control display.

4.3 CRITICAL PLANT VARIABLES DISPLAY

The Critical Plant Variables Display (Figure 4-5) is an image of the plant and presents two types of EOP information: control parameters and their limits, and event indications.

Table 4-2
CONTAINMENT CONTROL DISPLAY TREND PLOT LIMITS

Control Parameter	Static Limits	Dynamic Limits
DW Pressure	Oper Hi	Spray
Suppression Chamber Pressure		Maximum, Design, Pressure Suppression, Spray
DW Temperatures	Design, Oper Hi	RPV Sat
Suppression Pool Temp.	SCRM Temp, Oper Hi	Heat Cap
Suppression Pool Level	Oper Hi, Oper Lo, Vac Brkr	Pool LD, Heat Cap

4.4 TREND PLOT DISPLAYS

Trend plot displays are available for all control parameters. A typical Pilgrim trend plot display is shown in Figure 4-6.

The horizontal plot scale for all inputs is the most recent thirty minutes except RPV temperature for which the plot scale is the most recent sixty minutes.

Figure 4-6 shows the trend plot display for RPV water level. The trend plot displays include

Reactor, Pressure Vessel (RPV) Water Level

Suppression Pool Level

Reactor Pressure Vessel (RPV) Pressure

Reactor Power

Reactor Pressure Vessel (RPV) Temperature

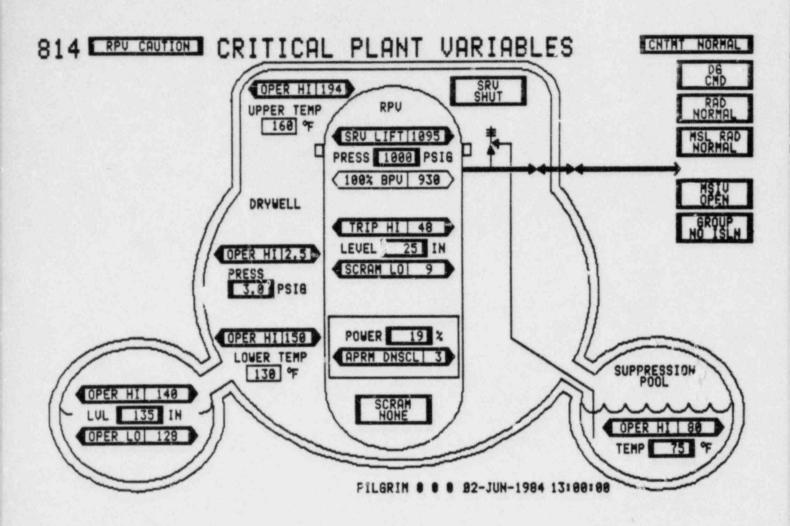


Figure 4-5. Critical Plant Variables

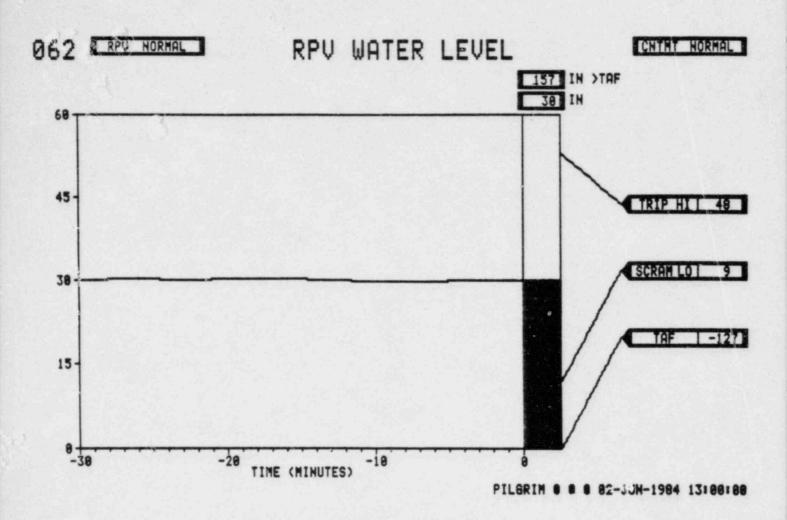


Figure 4-6. Trend Plot - RPV Water Level

Drywell Pressure

Suppression Chamber Pressure

Suppression Pool Temperature

Drywell Temperatures (Upper and Lower)

4.5 2D PLOT DISPLAYS

These lower-level displays provide operators in the control room and plant engineers in the control room and TSC with plots of the two-dimensional limits defined in the EOP's. These limits are also presented as limit tags on the RPV and containment control displays.

There are ten dynamic and one static 2D plot displays. A typical PNPS 2D plot is shown in Figure 4-7.

The 2D plot displays include:

Suppression Pool Load Limit (dynamic)

Heat Capacity Level Limit (dynamic)

Heat Capacity Temperature Limit (dynamic)

Primary Containment Pressure Limit (dynamic)

Primary Containment Design Pressure (dynamic)

Pressure Suppression Pressure (dynamic)

Maximum Core Uncovery Time Limit (static)

Average Hot Reference Leg Temperature (dynamic)

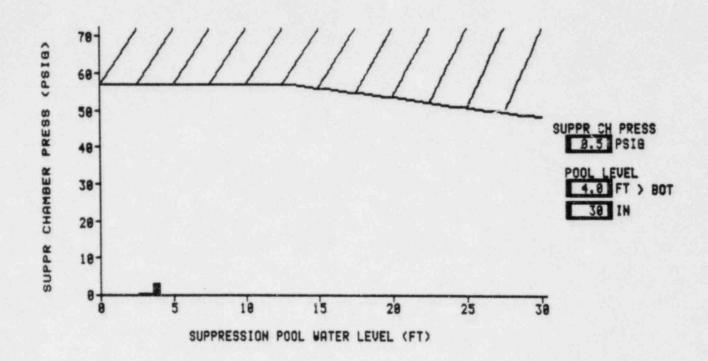
Average Cold Reference Leg Temperature (dynamic)

Drywell Spray Initiation Pressure Limit:

Drywell Parameters (dynamic)

Suppression Pool Parameters (dynamic)

852 RPU HORMAL PRI CONTAINMENT DESIGN PRESS CHIMT CAUTION



PILGRIM . . . 02-JUN-1984 11:00:00

Figure 4-7. 2D Plot - Primary CNTNT Design Pressure

4.6 VALIDATION STATUS DISPLAYS

Figure 4-8. Validation Status - Reactor Power Validation

5.0 HUMAN FACTOR ENGINEERING (HFE) IMPLEMENTATION

5.1 GENERAL

A Human Factors Engineering Implementation plan is a part of the design process for the EPIC in order to insure that the EPIC meets its intended objectives and accommodates its intended users. All activities in the HFE implementation plan are iterative in nature. Designs are developed based on Human Factors Engineering principles, then reviewed to assure that those principles have been properly implemented. Results and recommendations from reviews are then evaluated for impact and action plans are developed for incorporation into the design.

The EPIC HFE plan is an integral part of the design and review of the system as a whole as well as the design and review of the more detailed aspects of the system. The plan generally consists of activities such as definition of HFE requirements, reviews, testing, analysis and verification activities. These activities can be separated into the following specific major areas:

- a. Definition of Functional Requirements and Analysis of Tasks
- b. Man Machine Interface Development and Review
- c. Training plan development
- d. Verification and Validation

Figure 5-1 shows diagrammatically the Human Factors Engineering Plan which will be implemented as part of the EPIC design processes.

As shown, the "Definition of Functional Requirements and Analysis of Tasks" are performed first. This creates the basis by which all other HFE activity is performed. This activity defines the objectives of the system and the tasks which the system must be designed to perform.

The "Man Machine Interface Development and Review", "Training Plan Development", and certain aspects of the "Verification and Validation" activity are performed in a parallel fashion. In these activities, the system is examined to assure that it is properly designed for the intended user, a plan is set into place to train the personnel who are to use the system, and test plans are developed to insure that the requirements defined in the "Definition of Requirements" activity are met.

The final stage of the Human Factors Implementation is contained in the concluding activities of the "Verification and Validation". These activities include integrated testing and review of the system as a whole. These tests verify that the system meets the system functional requirements and is properly implemented for a human user.

Figure 5-1. Human Factor/System Integration Plan

The following sections describe in more detail the specific tasks which are performed in order to provide a comprehensive implementation of the overall HFE plan. Specific tasks consist of both plans for future implementation as well as previously performed activities which can be related specifically to the EPIC.

5.2 DEFINITION OF REQUIREMENTS AND ANALYSIS OF TASKS

5.2.1 System Functiona! Requirements

The first task in the HFE plan is the development of system level requirements. As shown in Figure 5-1 the system level requirements will be based upon

- a. Interfaces to systems outside of the EPIC
- b. Codes, standards, and regulatory requirements
- c. Assumptions and constraints
- Definition of what the EPIC is to perform and what the user is to perform (functional allocation)
- e. Purpose of the EPIC (Mission statement)

The system functional requirements define what the EPIC is to do, what performance is expected and what part of the system consists of user interaction.

These requirements provide the basis for comparison of all other activities. Any reviews performed on the EPIC are performed against the fulfillment of the requirements developed in this activity. The system level requirements is issued as a controlled document.

5.3 MAN MACHINE INTERFACES

5.3.1 General

The purpose of the man-machine interface portion of the HFE plan is to assure that the hardware used in the EPIC is consistent with the intended purpose and function of the system. This assurance results from the use of HFE principles throughout the design process as well as systematic review procedures. The following specific activities are performed in order to implement this purpose.

5.4 TRAINING DEVELOPMENT

5.4.1 General

Training plans, courses and course content are developed parallel to the other HFE activities of "Man Machine Interface Development" and "Validation and Verification". Again, training is developed based on the functional system level requirements and specific tasks with respect to the PNPS

Emergency Operating Procedures.

5.5 HUMAN FACTORS ENGINEERING VERIFICATION AND VALIDATION

5.5.1 General

The "Verification and Validation" activities of the HFE plan are an ongoing part of the entire design process for the EPIC. Some of the activities in verification and validation must be completed in the early stages of the design process whereas others are completed only in the final stages of the project. The general aspects of the Verification and Validation process for the entire EPIC design are described in Section 6.0. The major features of the HFE portion of Verification and Validation are described below. They include:

- a. Test Requirements Development
- b. Static HFE Review
- c. Dynamic Review
- d. Integrated Hardware/Software Validation Test

5.5.2 Test Requirements Generation

The system functional requirements are used as the basis for the development of tests and procedures which verify and validate, in general, the EPIC functions, and specifically the PNPS SPDS displays.

5.5.3 Static HFE Review

The PNPS SPDS displays are examined in a specific HFE review for comparison to basic human factors principles (such as those defined in NUREG 0700) and a determination of usefulness to the operator by using the tasks from the Control Room Design Review. This type of review was previously performed on the General Electric generic Emergency Response Information System (ERIS) displays (see reference 6) using the BWROG Emergency Procedures Guidelines. The results of the generic study were favorable and useful display improvements are being incorporated into the PNPS SPDS displays. The EPIC static review will be documented in a report form similar to that of reference 6.

5.5.4 Dynamic Review

An extensive dynamic review was performed on the General Electric generic ERIS displays at the BWR/6 simulator in Tulsa, Oklahoma. This review consisted of a HFE check using a checklist approach similar to that described in Section 5.5.3, the administration of 12 unique simulated transients, operator/system performance evaluations during the transients using the Perry Nuclear Power Plant EOPs and data collection for the measurement of the usefulness of the ERIS SPDS related displays.

The results of this review are documented in reference 7. In general the ERIS was perceived by the operators as a significant aid in plant control during emergencies and was judged as presenting an exceptional source of synthesized/centralized information with regards to plant performance. In addition, recommendations from the dynamic review are being incorporated into the EPIC displays. A report similar to the generic dynamic review report will be generated to address the EPIC displays.

5.5.5 Final Integration Testing

The final activity in completing the EPIC design is the integration of hardware/software and the user in a final test scenario. This test also called "Factory Acceptance Test", verifies that the system has been correctly designed for the user and that the EPIC has met its intended purpose. This

test is based on the functional system requirements and the previously developed test plans and procedures. The results of this test will be fully documented in a report.

The Human Factors Plan for the EPIC is developed to fully consider the user as a part of the system as a whole. By assuring that the individual components of the system have been reviewed for HFE considerations and the components have been integrated on the system level, the EPIC will be a functional and useful system.

6.0 VERIFICATION AND VALIDATION (V&V)

The methods employed in the V&V procedures ensure that the PNPS SPDS supplies the functions and characteristics that it is required to provide and that the functions perform correctly. The review and testing processes are designed to identify problems or weaknesses in the design requirements, the design, and the implementation of the design, and to correct those problems and weaknesses.

The specific V&V plan identifies quality audit points (QAPs) along the PNPS SPDS development path. These QAPs range from performing specification reviews to code walkthroughs to several levels of software and system testing. Heavy emphasis is placed on achieving independent V&V, that is, employing reviewers and testers who have not been directly involved in the design.

Figure 6-1 hows the Quality Audit Points throughout the design process of the EPIC system.

By performing the V&V procedures depicted in Figure 6-1 a systematic and structured method is implemented to insure that the correct functions are provided and that the functions provided are correct.

Figure 6-1. Major Milestones of Verification and Validation

7.0 CONCLUSION

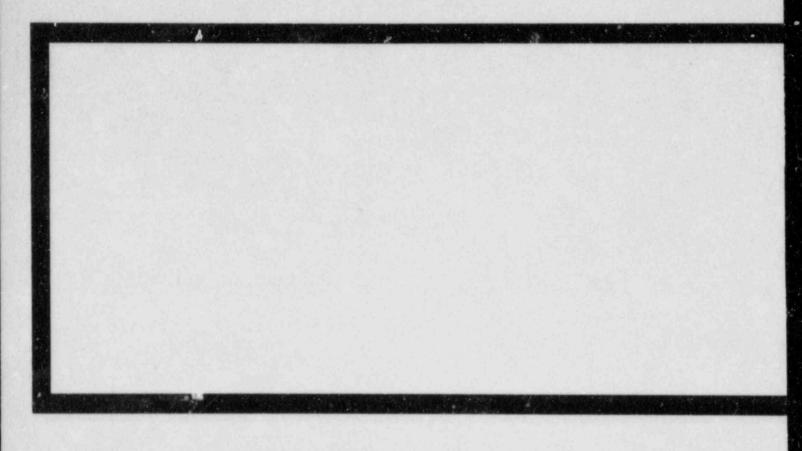
The PNPS portion of the Pilgrim Nuclear Power Station (PNPS) Emergency and Plant Information Computer represents an integrated data system which provides a concise amount of pertinent plant data sufficient to evaluate the safety status of the plant. In addition, it allows for an evaluation of the response of the plant to any automatic or operator initiated actions. The PNPS SPDS gathers plant data, stores and processes the data, generates visual humanengineered displays, and provides printed records to aid the control room operators during emergency conditions. The PNPS SPDS design is based upon sound design goals and good human factors engineering which are intended to ensure a highly reliable information system which will provide consistent and accurate data.

The PNPS SPDS displays are based upon the symptom-based EPGs. The operator uses the PNPS SPDS as an aid in entering and following the PNPS Emergency Operating Procedures. The PNPS SPDS is not meant to be a control device; it is simply a source of significant information on plant safety to supplement displays already provided in the control room. The use of the PNPS SPDS assists the control room personnel in performing their emergency response functions.

In summary, the PNPS SPDS is a capable and effective data system for improving responses to emergency situations. As demonstrated above, the PNPS SPDS complies with all the NRC requirements for the SPDS as set forth in Supplement 1 to NUREG-0737 (Requirements for Emergency Response Capability).

8.0 REFERENCES

- U.S. Nuclear Regulatory Commission, "Requirements for Emergency Response Capability" Supplement to USNRC Report NUREG 0737, December 1982.
- Nuclear Operations Dept. Pilgrim Nuclear Power Station (PNPS) Emergency Operating Procedures, Draft.
- 3) BWR Owner's Group Emergency Procedure Guidelines, Revision 2
- 4) "Safety Evaluation Report on the Emegency Procedure Guidelines Revision 2," letter D.G. Eisenhurt, NRC, to T. Dente, Chairman BWR Owners Group, February 4 1983
- U.S. Nuclear Regulatory Commission, "Guidelines for Control Room Design Reviews," USNRC Report NUREG 0700, September 1981.



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