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## INTERNAL TECHNICAL REPORT

Title: JET PUMP COMPLETION REPORT

Organization: CODE DEVELOPMENT DIVISION

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JET PUMP COMPLETION REPORT

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## ABSTRACT

This report describes the development and testing of a jet mixing component, JETMIXER, for RELAP5. When the jet mixing component is used the momentum equations are modified to reflect the additional momentum flux terms that result from the one-dimensional mixing of two parallel fluid streams. The JETMIXER component is primarily intended to be the basic building block used to model the jet pumps present in boiling water. It could also be used to model the momentum mixing that takes place at ECC injection points or for aspirators in steam generators.

For check out, the new JETMIXER component is used, along with standard RELAP5 components, to model the 1/6-scale jet pump from the General Electric single loop test apparatus that was tested at the Idaho National Engineering Laboratory.

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## Section 1

### INTRODUCTION-JET PUMP PERFORMANCE

There are several components in a typical reactor plant where the momentum effects due to the mixing of two parallel streams of fluid at different velocities may be important. The primary component being the jet pump in a BWR. In this component the pumping action is caused by the momentum mixing of two fluid streams. Momentum mixing effects may also be important at ECC injection points or for the aspirators present in some steam generators. A new JETMIXER component was developed for these cases and tested out for a jet pump. The remainder of this report documents the jet pump application of the JETMIXER component.

#### 1A. JET PUMP FLOW CHARACTERISTICS

Jet pumps are an important component in the design of boiling water reactors-BWR (Figure 1). Jet pumps provide a simple virtually maintenance free efficient primary pumping system.

Under normal operating conditions, a jet pump operates with a high fluid momentum in the drive line (Figure 2) generated by the auxiliary recirculation pump. This momentum creates the necessary suction at the nozzle exit plane to draw fluid from the suction region (the downcomer region in a BWR) into the jet pump. This suction flow then mixes with the high speed drive flow in the mixing region. The high momentum flow leaving the mixing section is converted to a pressure head in the diffuser section.

Figure 3 shows flow directions under normal operating conditions (first quadrant) and the five additional steady state flow regimes that could exist within the jet pump under abnormal conditions. (Two other possible flow regimes exist but they violate continuity assumptions for incompressible steady flow.)

It has been customary to identify jet pump operations in terms of two dimensionless parameters. These are the M and N parameters defined

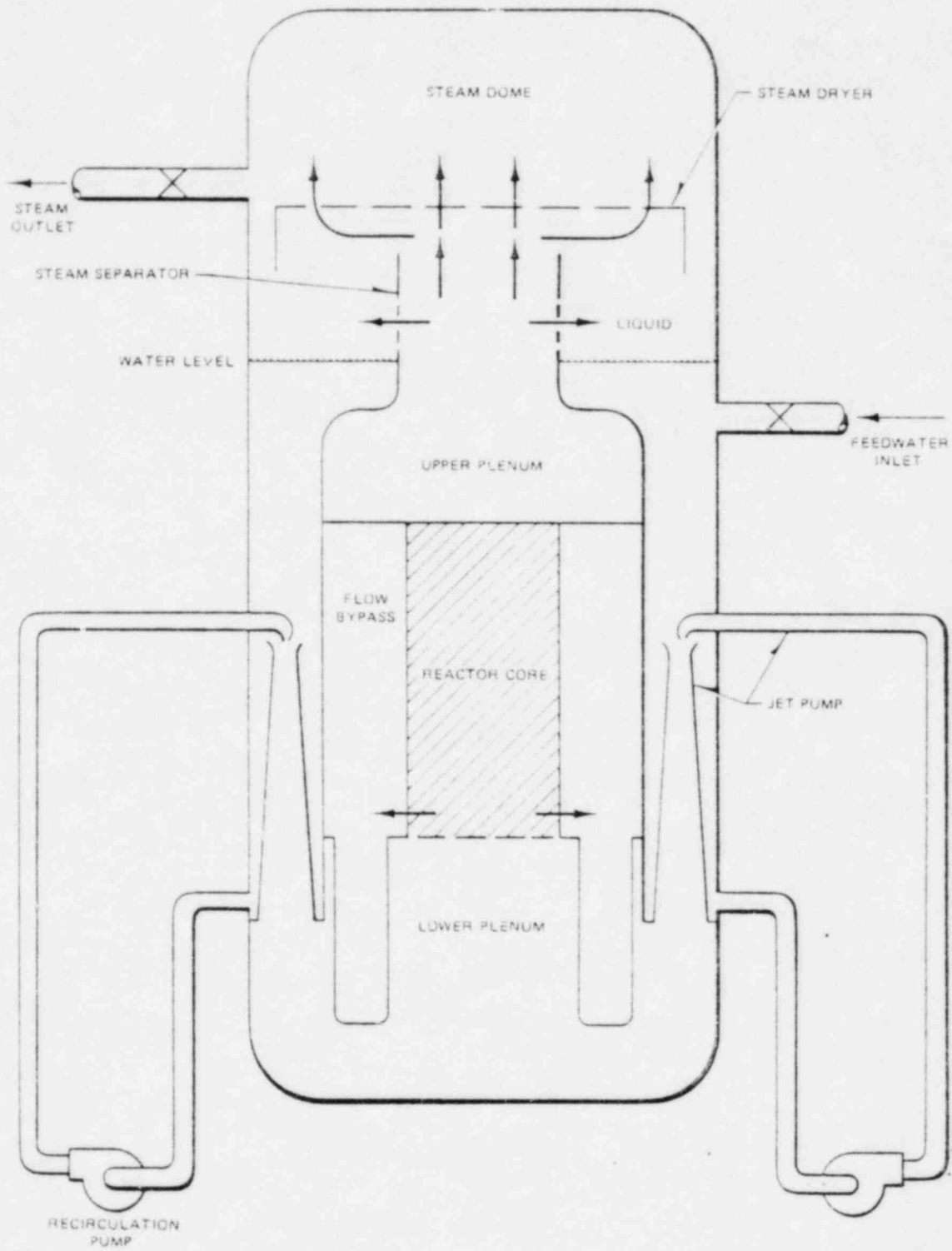


Figure 1. Typical BWR Structure

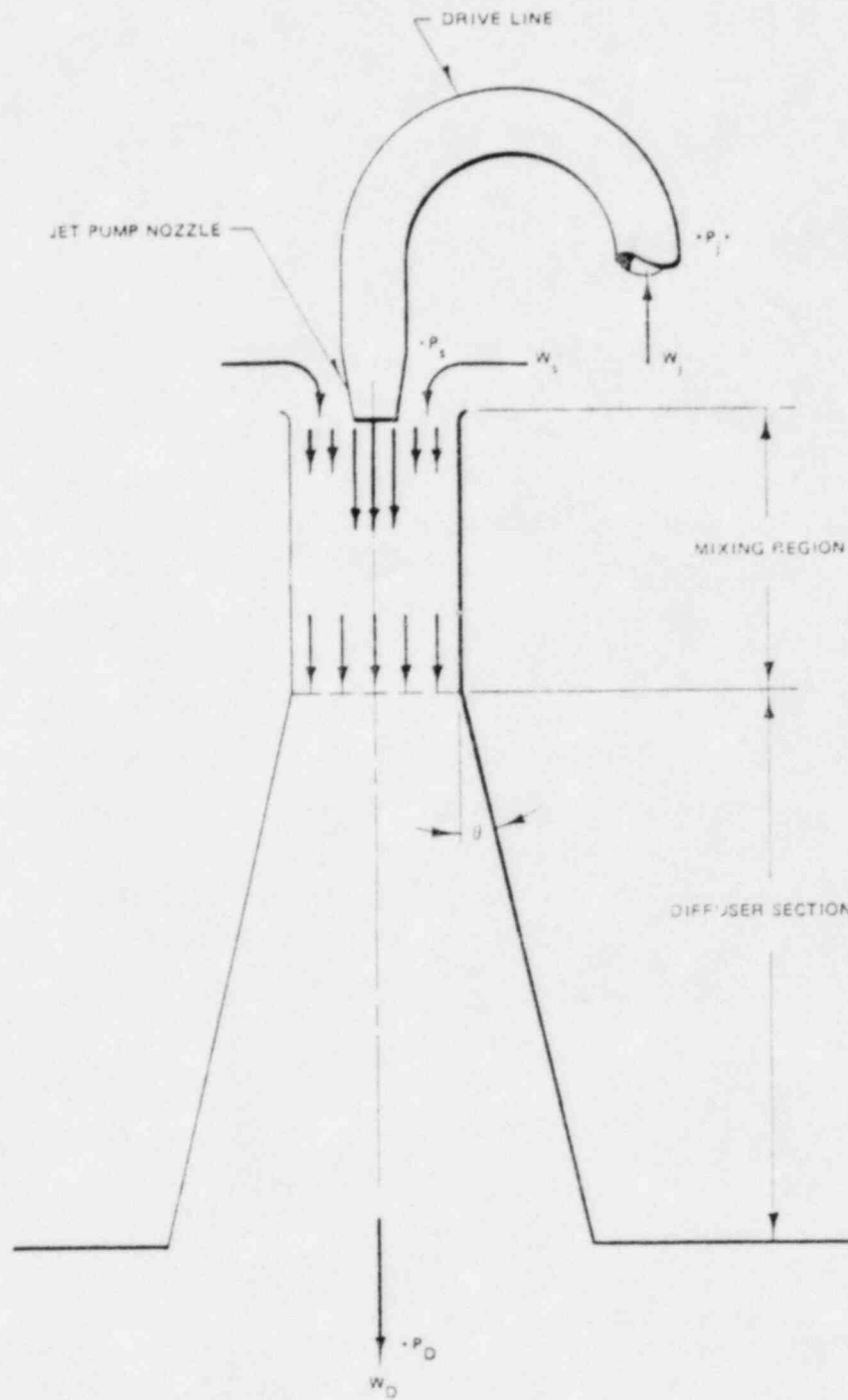


Figure 2. Normal Jet Pump Operation

as follows:

- (1) The M - Ratio is the suction flow rate,  $W_S$ , divided by the drive flow rate  $W_j$ ,<sup>1</sup>

$$M = W_S/W_j, \quad (1.1)$$

- (2) The N - Ratio (head ratio) is the increase in dynamic pressure for the suction-discharge path divided by the loss of dynamic pressure for the drive-discharge path,

$$N = \frac{(P + \frac{1}{2}\rho v^2 + \rho gh)_D - (P + \frac{1}{2}\rho v^2 + \rho gh)_S}{(P + \frac{1}{2}\rho v^2 + \rho gh)_j - (P + \frac{1}{2}\rho v^2 + \rho gh)_D}. \quad (1.2)$$

## 1B. EXPERIMENTAL RESULTS

Figure 3 shows typical jet pump data in terms of the M-N parameters and the associated flow regimes. This data is for the 1/6-scale jet pump from the General Electric single loop test apparatus that was tested at INEL [1].

Data was collected in all six of the operating regimes shown in Figure 3 but the data scatter was excessive for the positive drive/negative discharge case. The experimental data analysis report [1] indicated that it would be inadvisable to use the M-N data base for positive drive with M less than -0.8 for the development and assessment of analytic models. We have therefore not plotted this data in Figure 3. The data in Figure 3 will be used to test the JETMIXER component developed in Section 2.

---

<sup>1</sup> Subscripts j, S, D, are used to indicate variables defined at the drive nozzle jet, the suction entrance, and the discharge at the exit of the diffuser section respectively. If the intended application of the JETMIXER component is not a jet pump then the drive flow should be the high speed stream and the suction the low speed stream. For example, at an ECC injection point the injected fluid is the drive flow and the main upstream flow is the suction flow.



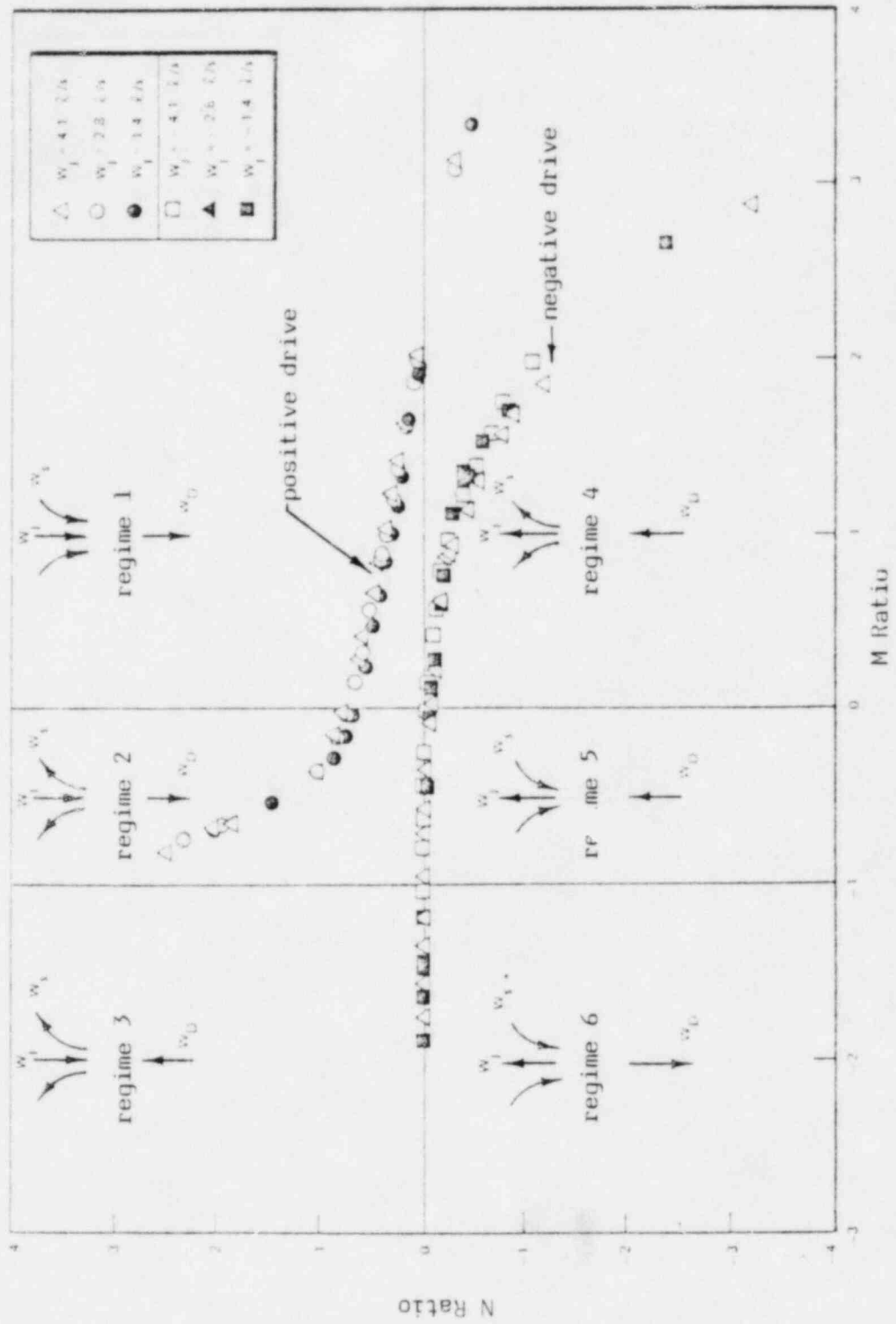


Figure 3. N-M Performance Characteristics of INEL Jet Pump

Section 2

BASIC JET MIXING MODEL

2A. MOMENTUM ANALYSIS FOR JET MIXING IN SINGLE PHASE FLOWS

To develop the momentum equations needed to model a jet pump we will consider the schematic of the drive and suction junctions<sup>1</sup> shown in Figure 4.

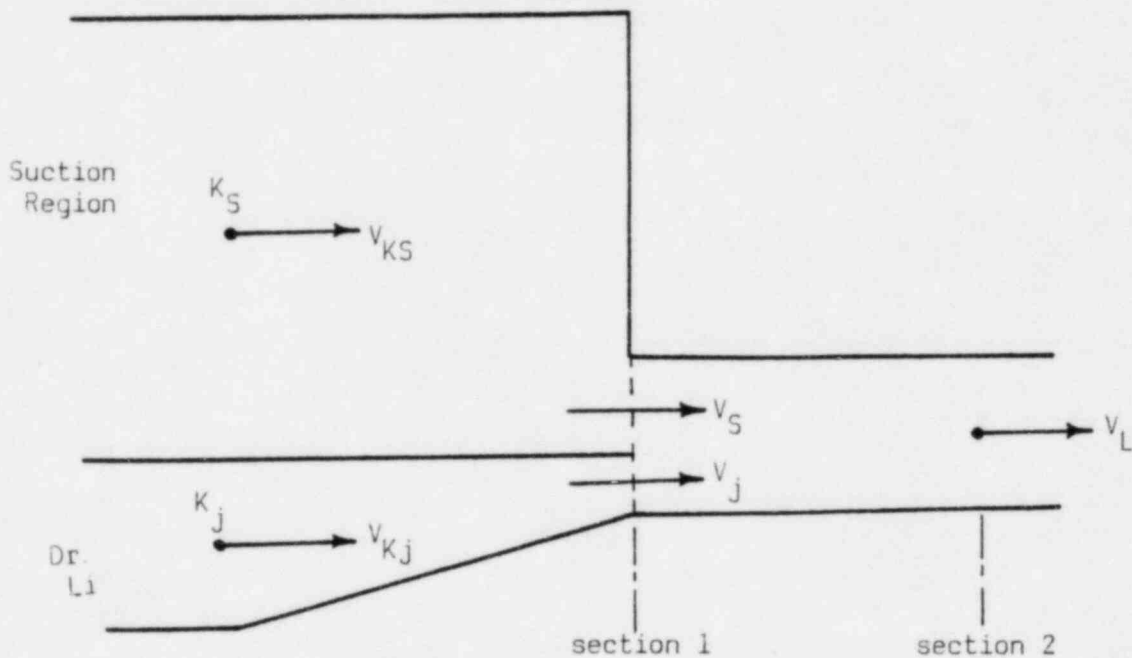


Figure 4. Schematic of Mixing Junctions

<sup>1</sup> The drive and suction junctions should be the high speed and low speed junctions respectively with the JETMIXER component is used for other than jet pump applications.

The suction junction (with velocity  $v_S$  and area  $A_S$ ) connects the last upstream suction region volume,  $K_S$ , to the mixing volume,  $L$ . The drive junction (with velocity  $v_j$  and area  $A_j$ ) connects the last upstream drive line volume,  $K_j$ , to the mixing volume,  $L$ . Figure 4 shows the drive junction as a smooth junction and the suction junction as abrupt. The user can model either junction either way if the appropriate loss factors are included (see discussion in Section 5). Void fractions and densities at junctions  $j$  or  $S$  when subscripted by a  $j$  or  $S$  are denoted values. If the subscript  $a$  is used they are then volume averaged values.

The mixing of the drive and suction flows between section 1 and 2 requires a re-evaluation of the momentum flux terms. The wall drag, interphase drag, temporal acceleration, momentum exchange due to mass transfer, and gravity head terms for the drive and suction junctions are treated exactly as they are at any other junction. Only the pressure and momentum flux terms will be examined in the following momentum equation development.

Consider a control volume in the mixing region between sections 1 and 2. If we apply the conservation of momentum principle for this control volume with the following assumptions:

- (1) steady single phase flow,
- (2) one-dimensional flow at sections 1 and 2,
- (3) pressures at junctions  $j$  and  $S$  are equal, we obtain

$$(P_L - P_1) A_L + \rho v_L^2 A_L - \rho_S v_S^2 A_S - \rho_j v_j^2 A_j = 0. \quad (2.1)$$

Conservation of mass applied with these same assumptions gives

$$\rho_L v_L A_L - \rho_S v_S A_S - \rho_j v_j A_j = 0. \quad (2.2)$$

We now use Equation (2.2) to write Equation (2.1) in its "nonconservative" form, obtaining

$$(P_L - P_1) + \rho_S v_S A_S (v_L - v_S) / A_L + \rho_j v_j A_j (v_L - v_j) / A_L = 0. \quad (2.3)$$

Equation (2.3) gives the momentum equation (pressure and flux terms, that is) for the mixing volume. To develop the momentum equation for the suction junction we write a normal half cell momentum equation from  $K_S$  to section 1 i.e.

$$(P_1 - P_{KS}) + \frac{1}{2} \rho_{KS} (v_S^2 - v_{KS}^2) = 0. \quad (2.4)$$

and add this to the half cell momentum Equation (2.3) for section 1 to L. This gives

$$\begin{aligned} & (P_L - P_{KS}) + \frac{1}{2} \rho_{KS} (v_S^2 - v_{KS}^2) \\ & + \rho_S v_S A_S (v_L - v_S) / A_L + \rho_j v_j A_j (v_L - v_j) / A_L = 0. \end{aligned} \quad (2.5)$$

If the suction junction were a normal junction its momentum equation would be

$$(P_L - P_{KS}) + \frac{1}{2} \rho_{Sa} (v_L^2 - v_{KS}^2) = 0. \quad (2.6)$$

A completely parallel development is obtained for the drive junction equations. Comparing Equations (2.6) and (2.5) shows how the convective terms are modified at a suction or drive junction due to the mixing that is taking place there.

## 2B. MOMENTUM ANALYSIS FOR JET MIXING IN TWO-PHASE FLOWS

If a similar development is carried out for the pressure and momentum flux terms in the two-phase case the following equations are obtained for the liquid phase in the mixing region:

- (1) Conservation of momentum (for section 1 to L)

$$\begin{aligned} & \alpha_{fL} A_L (P_L - P_1) + \alpha_{fL} \rho_{fL} v_{fL}^2 A_L \\ & - \alpha_{fS} \rho_{fS} v_{fS}^2 A_S - \alpha_{fj} \rho_{fj} v_{fj}^2 A_j = 0, \end{aligned} \quad (2.7)$$

(2) Conservation of mass<sup>1</sup> (for section 1 to L)

$$\alpha_{fL} \rho_{fL} v_{fL} A_L - \alpha_{fS} \rho_{fS} v_{fS} A_S - \alpha_{fj} \rho_{fj} v_{fj} A_j = 0. \quad (2.8)$$

We now use Equation (2.8) to rewrite Equation (2.7) in its nonconservative form

$$\begin{aligned} & \alpha_{fL} (P_L - P_1) + \alpha_{fS} \rho_{fS} v_{fS} A_S (v_{fL} - v_{fS}) / A_L \\ & + \alpha_{fj} \rho_{fj} v_{fj} A_j (v_{fL} - v_{fj}) / A_L = 0. \end{aligned} \quad (2.9)$$

Equation (2.9) could now be combined with the appropriate half cell momentum equation for the upstream volume to obtain the final momentum equation for the liquid flow at the suction junction. In RELAP5 the phasic momentum equations are used as a sum momentum equation and a difference momentum equation. We will derive these equations directly from Equation (2.9).

To derive the sum momentum equation for the suction junction we add Equation (2.9) for the liquid phase and the parallel equation for the gas phase to obtain

$$\begin{aligned} & (P_L - P_1) + \alpha_{fS} \rho_{fS} v_{fS} A_S (v_{fL} - v_{fS}) / A_L + \alpha_{vj} \rho_{vj} v_{vj} A_j (v_{fL} - v_{vj}) / A_L \\ & + \alpha_{gS} \rho_{gS} v_{gS} A_S (v_{gL} - v_{gS}) / A_L + \alpha_{gj} \rho_{gj} v_{gj} A_j (v_{gL} - v_{gj}) / A_L = 0. \end{aligned} \quad (2.10)$$

<sup>1</sup> As stated before, the momentum equation terms due to mass exchange are not being changed by this model addition, so the mass transfer terms in Equation (2.8) are not shown.

The normal half cell sum momentum equation for the upstream suction volume can then be added to Equation (2.10) giving

$$\begin{aligned}
 (P_L - P_{KS}) + \alpha_{fS} \rho_{fS} v_{fS} A_S (v_{fL} - v_{fS}) / A_L + \alpha_{fj} \rho_{fj} v_{fj} A_j (v_{fL} - v_{fj}) / A_L \\
 + \alpha_{gS} \rho_{gS} v_{gS} A_S (v_{gL} - v_{gS}) / A_L + \alpha_{gj} \rho_{gj} v_{gj} A_j (v_{gL} - v_{gj}) / A_L \\
 + \frac{1}{2} \alpha_{fKS} \rho_{fKS} (v_{fS}^2 - v_{fKS}^2) + \frac{1}{2} \alpha_{gKS} \rho_{gKS} (v_{gS}^2 - v_{gKS}^2) = 0. \quad (2.11)
 \end{aligned}$$

as the final form of the pressure and momentum flux terms in the new sum momentum equation to be used at junction S. A parallel equation must be used at the drive junction j. The pressure term in this equation is in exactly the same form as the pressure term in the normal sum momentum equation. Hence at the drive and suction mixing junctions we must replace the normal momentum flux terms by those in Equation (2.11).

To derive the difference momentum equation for the suction junction we divide the liquid mixing Equation (2.9) by  $\alpha_{fL}$  and add it to the half cell liquid equation for the upstream suction volume (also divided by the appropriate void fraction,  $\alpha_{fKS}$ ) to obtain

$$\begin{aligned}
 (P_L - P_{KS}) + \alpha_{fS} \rho_{fS} v_{fS} A_S (v_{fL} - v_{fS}) / \alpha_{fL} A_L + \alpha_{fj} \rho_{fj} v_{fj} A_j (v_{fL} - v_{fj}) / \alpha_{fL} A_L \\
 + \frac{1}{2} \rho_{fKS} (v_{fS}^2 - v_{fKS}^2) = 0. \quad (2.12)
 \end{aligned}$$

We now divide Equation (2.12) by the average junction liquid density,  $\rho_f$ , and subtract it from the corresponding gas equation to obtain

$$\begin{aligned}
& \frac{\rho_f - \rho_g}{\rho_f \rho_g} (P_L - P_{KS}) + \alpha_{gS} \rho_{gS} v_{gS} A_S (v_{gL} - v_{gS}) / \alpha_{gL} \rho_g A_L \\
& + \alpha_{gJ} \rho_{gJ} v_{gJ} A_J (v_{gL} - v_{gJ}) / \alpha_{gL} \rho_g A_L + \frac{1}{2} \rho_{gKS} (v_{gS}^2 - v_{gKS}^2) / \rho_g \\
& - \alpha_{fS} \rho_{fS} v_{fS} A_S (v_{fL} - v_{fS}) / \alpha_{fL} \rho_f A_L - \alpha_{fJ} \rho_{fJ} v_{fJ} A_J (v_{fJ} - v_{fL}) / \alpha_{fL} \rho_f A_L \\
& - \frac{1}{2} \rho_{fKS} (v_{fS}^2 - v_{fKS}^2) / \rho_f = 0. \tag{2.13}
\end{aligned}$$

as the final difference momentum equation to be used at junction S. A parallel equation must be used at the drive junction. The pressure term in Equation (2.13) is in exactly the same form as the pressure term in the normal difference momentum equation. Hence we must replace the normal momentum flux at these junctions by the momentum flux terms in Equation (2.13).

## 2C. ASSOCIATED FLOW LOSSES

The flow taking place in the "mixing" region of volume L can in reality be either a true jet mixing, corresponding to regime 1 in Figure 3, or a flow split corresponding to regime 4 in Figure 3. The flow separation case is governed by different physics than the jet mixing case considered in the previous discussions. The redistribution taking place when the flow splits is primarily determined by the effective resistances downstream of the separation point in the suction and drive flow paths. The mixing terms derived above do not apply. For this reason and to preserve continuity on the respective performance curves in Figure 3 we apply the additional mixing terms only for the positive drive flow regimes. We use the normal momentum flux calculations for the negative drive flow regimes.

The junctions associated with the JETMIXER component can be modeled as smooth or abrupt. If the junctions are input as smooth then the appropriate flow resistances should be calculated in a standard fashion (see Reference [2]) and input as form loss coefficients at the appropriate junctions by

the user. The junctions in the test calculation were modeled in this manner. (See the detailed discussion and user guidelines in Section 5). If the junctions in the JETMIXER component are input as abrupt then the code will calculate form loss coefficients as usual except that (1) the forward loss coefficients at the drive and suction junctions are set to zero. The forward losses at these junctions are really associated with the expansion from the vena contracta to the downstream mixing volume flow area. Because of the parallel mixing streams this loss is no longer appropriate. (2) The reverse loss coefficients for the suction and drive junctions are those associated with the expansions from the junction areas to the suction or drive inlet volume areas. The losses associated with any contraction from the mixing volume to the suction or drive junctions is also neglected for the same reason.

If one considers a typical BWR configuration (Figure 1) then two jet pump related accidents that must be considered are (1) loss of power for a recirculation pump and the resulting pump coastdown and (2) blowdown resulting from the rupture of a drive line. In the first case as the drive flow declines, so does the head developed by the pump and eventually the suction flow reverses. The pump is then operating in flow regime 2. In case 2 the jet pump will be operating in flow regime 5.

If normal flow losses are used in these two cases (as described above for smooth or abrupt area changes) it will be found that the jet pump performance in regime 5 is accurately modeled but that the N Ratio in flow regime 2 is significantly below the experimental data. The reverse flow loss coefficient applied in the suction junction has a significant effect on the jet pump performance in flow regimes 2 and 3. This loss coefficient (in addition to the normal loss coefficient associated with the expansion from  $A_S$  to area  $A_{KS}$ ) represents all the irreversible losses associated with the turning and expansion of the flow from the drive junction. Because this flow regime is an important regime in the accident analysis of a BWR it was decided to include an approximation for this flow dependent loss in the jet mixing model.

This reverse suction flow loss was based upon the expansion losses



experienced by the flow as it moves from the drive to the suction junction (Figure 5). In regime 2 the expansion loss associated with the area change  $A_j$  to  $A_S$  i.e.

$$K = (A_S/A_j - 1)^2 \quad (2.14)$$

is added to the user input reverse loss coefficient (or the standard abrupt area change loss factor if the junction is input as abrupt) for the suction junction.<sup>1</sup> In regime 3 the effective area for the suction flow that comes from the drive junction is less than  $A_S$  because the discharge flow has reversed. In this regime the effective areas for the expansion loss are  $A_j$  and  $A_S (|W_j/W_S|)$ . Hence for regime 3 the loss coefficient

$$K = \left( \frac{A_S |W_j/W_S|}{A_j} - 1 \right)^2 \quad (2.15)$$

is added to the user input reverse loss coefficient (or the abrupt area loss factor if the junction input is abrupt) at the suction junction

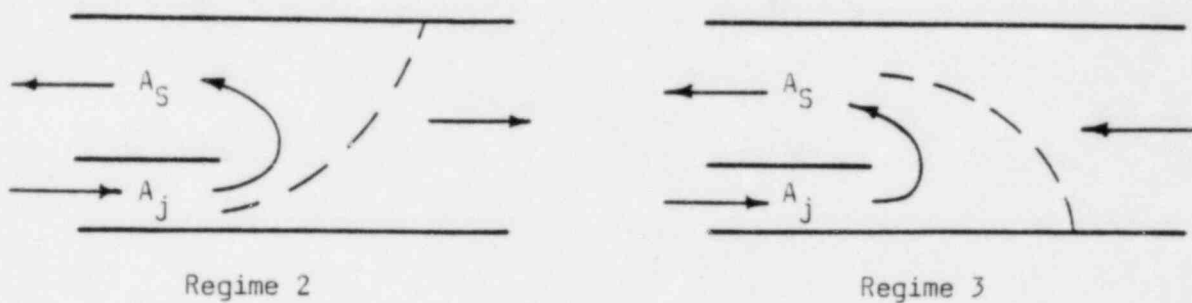


Figure 5. Flow Regimes and Dividing Streamline

<sup>1</sup> In reality the expansion loss should be based upon the effective area change  $A_j (W_S/W_j)$  to  $A_S$ . This form gives an infinitely large loss coefficient when  $W_j = 0$  and approaches Equation (2.14) when  $W_S$  and  $W_j$  are the same order. A kink in the performance curve at  $M = 0$  was removed using Equation (2.14).

so long as  $A_S |W_j/W_S|$  is greater than  $A_j$ . If  $A_j |W_j/W_S|$  is less than  $A_j$  the drive to suction flow is effectively a contraction and the additional loss coefficient is set to zero.

Since the jet mixing and effective resistances are handled with special terms in the suction and drive junction equations the normal losses associated with the partitioning of volume  $L$  are not included in these junction equations. The normal losses associated with the area ratios experienced by the flow upstream of the suction and drive junctions are retained in the junction momentum equations.

### Section 3

#### NUMERICAL IMPLEMENTATION AND CODING CHANGES

The basic numerical algorithm used to evaluate the new momentum flux terms in Equations (2.11) and (2.13) is exactly parallel to the numerical evaluation of the normal momentum flux terms. The present momentum flux terms are calculated explicitly at time level  $n$  in the subroutine VEXPLT. The new momentum flux terms in Equation (2.11) and (2.13) are also explicitly evaluated in VEXPLT. The spatial location of each variable is indicated by its subscript.

When Equations (2.11) and (2.13) are examined it is found that the momentum equations for the suction junction  $S$  require a knowledge of the drive junction properties and velocities (a parallel statement holds for the drive junction momentum equations). In the present VEXPLT, when we are calculating the momentum terms for junction  $i$ , we have no available indices to obtain the properties at any other junction. For this reason it was necessary to define a new component, JETMIXER, and to require the user to input the drive and suction junctions in this component in a pre-assigned order (for details of the input preparation see section 5).<sup>1</sup> Because VEXPLT already contains an outer component loop (with an inner junction loop) no new structuring of the loops in VEXPLT was required. The special terms in Equations (2.11) and (2.13) are then easily built in VEXPLT when the component being processed is a JETMIXER and we know that the first junction in this component is the drive and the second is the suction.

The additional loss coefficients in Equations (2.14) and (2.15) are calculated in VEXPLT immediately following the special momentum flux calculations.

The added mass terms and any stratified flow forces that could be inadvertently included in the drive or suction junctions are set to

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<sup>1</sup> The drive junction must be the first junction input for a JETMIXER component and the suction junction input must be the second junction data input.

zero in the same section of coding. A Fortran listing of the appropriate section of VEXPLT showing these changes is included in Appendix A.

The only other routines modified are listed below with the appropriate changes noted:

HLOSS - several lines were added to flag a JETMIXER component and in this case to skip the normal loss calculation. See Appendix B for Fortran listing of appropriate changes.

RBRANCH - input checking and messages were added to see that the drive, suction and discharge junctions of the special JETMIXER branch component are properly connected by the user. Section 4 gives the input requirements and input error messages.

No new array variables were added to the code. Several local variables are used in the special section of coding for a JETMIXER component in VEXPLT. The only local variable used outside of this region of coding is FJET which contains the special JETMIXER resistance coefficient for reverse suction flow.

## Section 4

### INPUT PREPARATION AND OUTPUT CHANGES

The component name JETMIXER has been added to the component names that can be used. The input for a JETMIXER component is the same as that for a BRANCH component with the following modifications:

- (1) For a BRANCH component the junctions connected to that branch can be input with the branch or as separate components. For a JETMIXER three (and only three) junctions, representing the drive, suction and discharge, must be input with the JETMIXER component, i.e.  $NJ = 3$ . If  $NJ \neq 3$  an input error message is printed.
- (2) The three junction card sequences must be numbered as follows; cards cccl101 and cccl201 represent the drive junction, cards ccc2101 and ccc2201 represent the suction junction, and cards ccc3101 and ccc3201 represent the junction in the mixing section.
- (3) The drive and suction junctions must be "pointing" into the JETMIXER volume i.e. these junctions must have to connection codes referring to the JETMIXER volume. If this is not the case an input error message is printed. The drive and suction junctions must be connected to the inlet side of the JETMIXER volume and the mixing junction must be connected to the outlet of the JETMIXER volume. If this is not the case an input error message is printed.

Although the junction and volume areas for a JETMIXER are not restricted, the JETMIXER will properly model a jet pump only if the drive and suction flow areas sum to the mixing volume area.

There is no special output for a JETMIXER component.

## Section 5

### APPLICATION TO JET PUMP MODELING

This section will describe the use of the JETMIXER component to model the 1/6 - scale jet pump test at INEL [1].

#### 5A. MODEL DESCRIPTION

The model, as shown in Figure 6, has the following features:

- (1) the suction region is represented by two equal volumes ( $A = 5.088E-3 \text{ M}^2$ ,  $L = 1.6 \text{ M}$ ) with the suction junction modeled as smooth.
- (2) the drive line is also represented by two volumes ( $A = 7.26E-4 \text{ M}^2$ ,  $L = 1.6 \text{ M}$ ) with a smooth drive junction .
- (3) a mixing section represented by two similar volumes ( $A = 6.605E-4 \text{ M}^2$ ). The first is a JETMIXER component and the second is a normal volume.
- (4) A three volume diffuser PIPE ( $L = 4.26 \text{ M}$ ) component followed by a normal volume ( $A = 40.7E-4 \text{ M}^2$ ).

The drive and suction junctions could be modeled with smooth or abrupt area changes. If they are modeled as smooth junctions then the appropriate forward and reverse loss coefficients must be user input. Runs were made both ways with basically the same results. The use of smooth junctions gives the user more explicit control over the resistance coefficients and for this reason was used below.

The resistance coefficients used were calculated in a standard fashion from reference [2] for configurations similar to those of the jet pump. These additive resistance coefficients were taken as turning losses in the drive line ( $K = 0.42$ ) entrance ( $K = 0.02$ ) and exit ( $K = 1.0$ ) losses in the suction junction, mixing ( $K = 0.07$ ) and diffuser losses in the primary piping, and a reverse flow exit loss in the drive line. The expressions used for calculating the loss coefficient in the diffuser section were

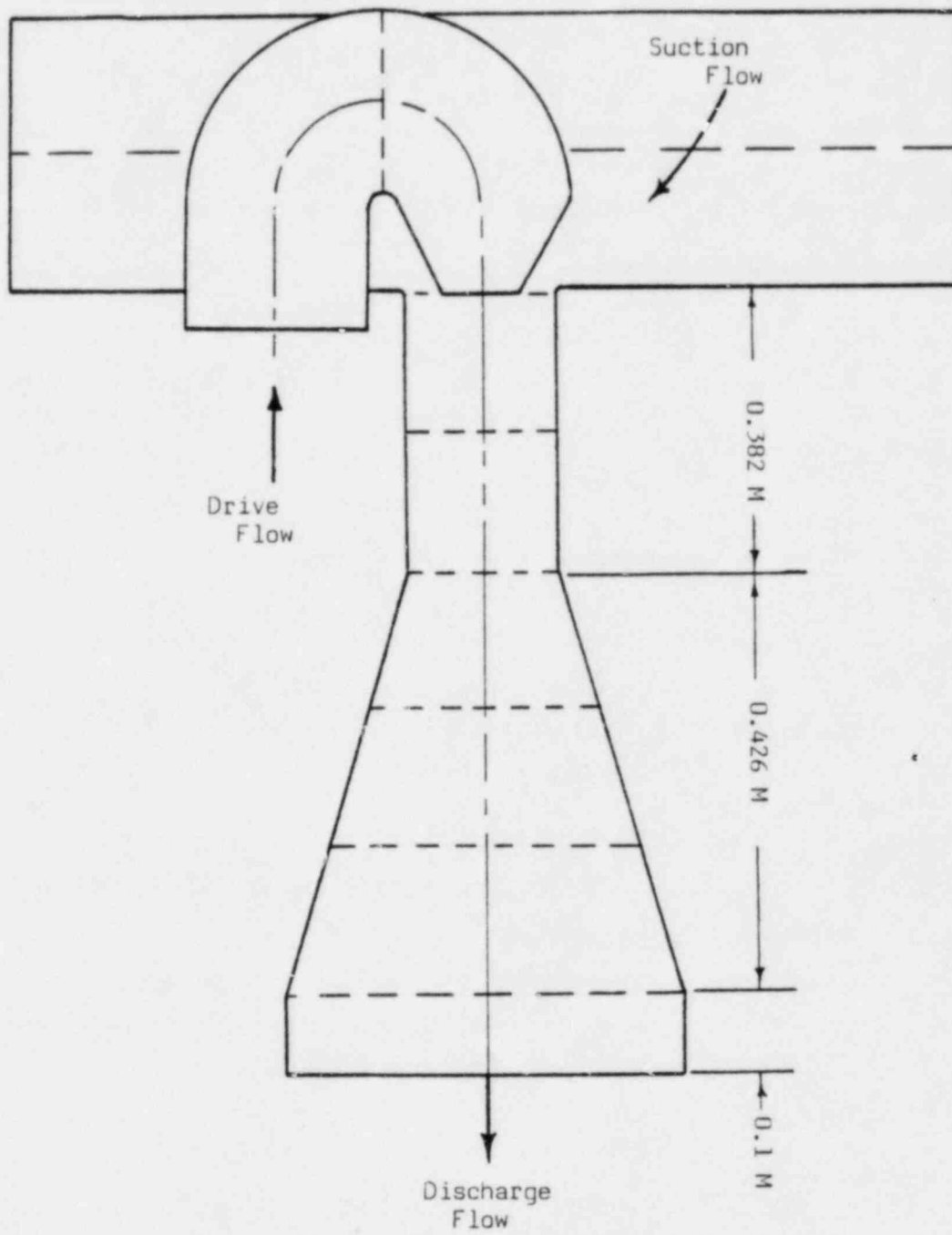


Figure 6. Schematic of Jet Pump Model

$$K_c = 0.8 \sin \theta (1 - \beta^2) \quad (\text{for contraction}) \quad (5.1)$$

and

$$K_e = 2.6 \sin \theta (1 - \beta^2)^2 \quad (\text{for expansion}), \quad (5.2)$$

where  $\beta^2$  is the area contraction ratio and  $\theta$  is the half-angle of contraction. For this specific pump these evaluate to  $K_c = 0.0337$  and  $K_e = 0.0919$ .

The contraction loss associated with the drive nozzle was set to zero.

This loss is really associated with the expansion beyond the vena-contracta point. For the merging of two streams taking place in the jet pump it was felt that this expansion loss was not really present. For reverse drive flow Equation (5.2) was used with a resulting  $K_e = 0.238$ .

#### 5B. BOUNDARY CONDITIONS

To generate a point on the performance curve a transient was run to steady state. The boundary conditions used were:

- (1) Diffuser discharge pressure,  $P = 75.85 \text{ ES Pa}$ .
- (2) Two drive mass flows  $\pm 3.0611 \text{ kg/s}$  (volumetric flow  $\pm 4.1/\text{s}$ ) with temperature  $T = 555.0^\circ \text{K}$ .
- (3) The suction inlet mass flows were varied between  $-3.048 \text{ kg/s}$  ( $M = -.986$ ) and  $9.907 \text{ kg/s}$  ( $M = 3.22$ ) with  $T = 555.0^\circ \text{K}$ . A flow rate was imposed at the suction inlet because in this way a whole performance curve could be generated with a single computer run using a time dependent inlet flow table. Several points on the M-N curve were then rerun with the appropriate pressure boundary conditions replacing the imposed suction mass flow. There was no change in the predicted results using the pressure boundary conditions.

#### 5C. CODE PREDICTIONS

Figures 7 and 8 shows the code predictions compared to the experimental data. Figure 7 shows the basic agreement in all four quadrants. A curve



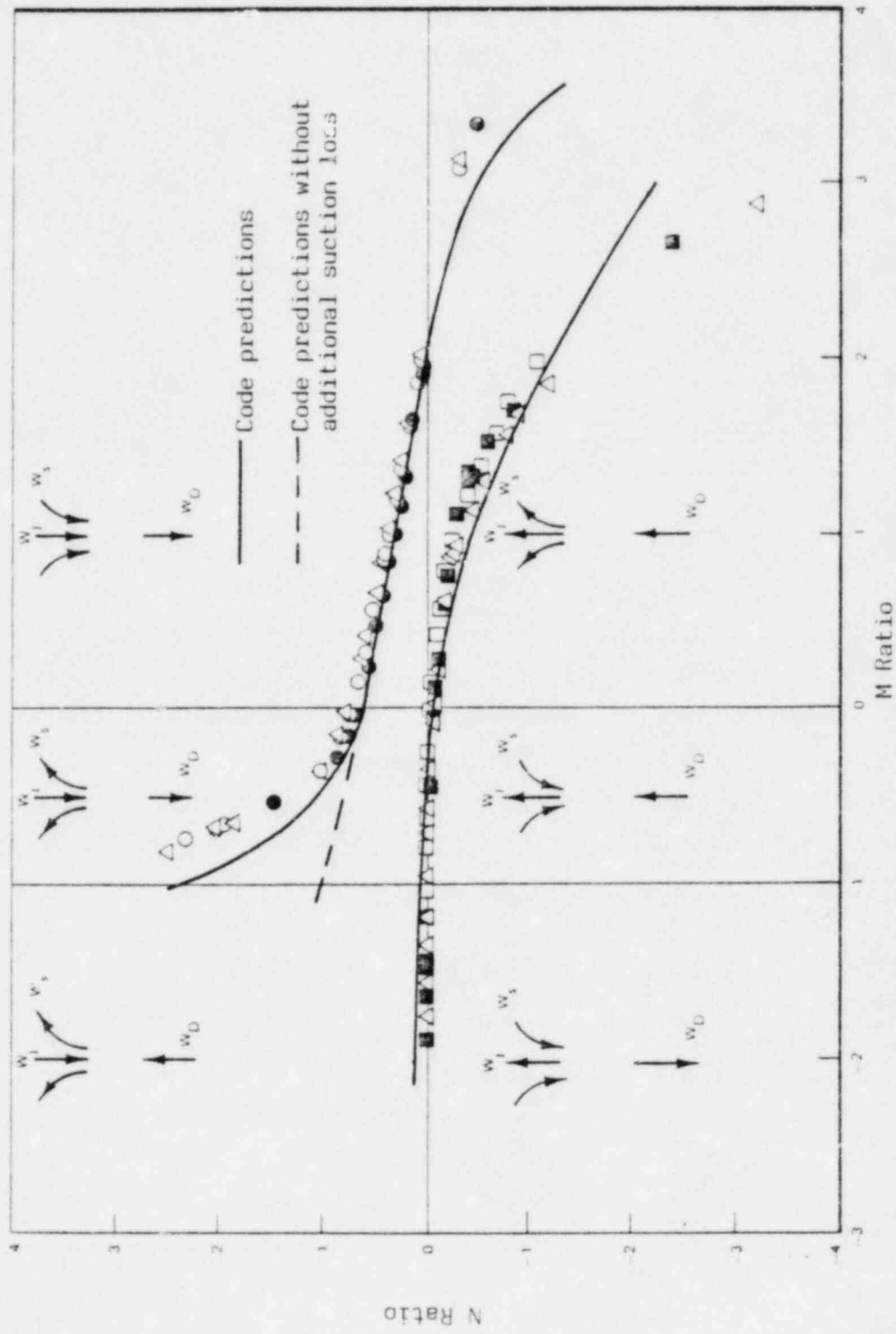


Figure 7. RELAP5 Predictions for INEL Jet Pump

is also plotted showing the disagreement that existed in regime 2 before the reverse suction loss coefficient described in section 2 was included.

Figure 8 shows an expanded view of the normal operating region with several curves representing different flow resistances. This figure can be used as a guide for modeling different jet pump geometries. Each curve shows the M-N performance generated with the loss coefficients discussed above plus a single additional loss coefficient ( $K = 0.2$ ) added to either the drive or suction or mixing junction. This figure gives an indication of the quantitative change in performance caused by the respective drive, suction or mixing losses. Using this figure, one should be able (with a few preliminary code runs) to design a code model for his specific jet pump if he has the performance data available. If no specific performance data is available it is recommended that the standard losses used above be applied.

There is no special output printed for the JETMIXER component. It is recommended that control variables be used to set up the M and N parameters for minor edit purposes and that these parameters be printed with every edit. A listing of the input cards used to generate the positive drive flow branch of the M-N curves is shown in Appendix C. This input data also shows an example of the use of the control variables to print out the M-N performance parameters.

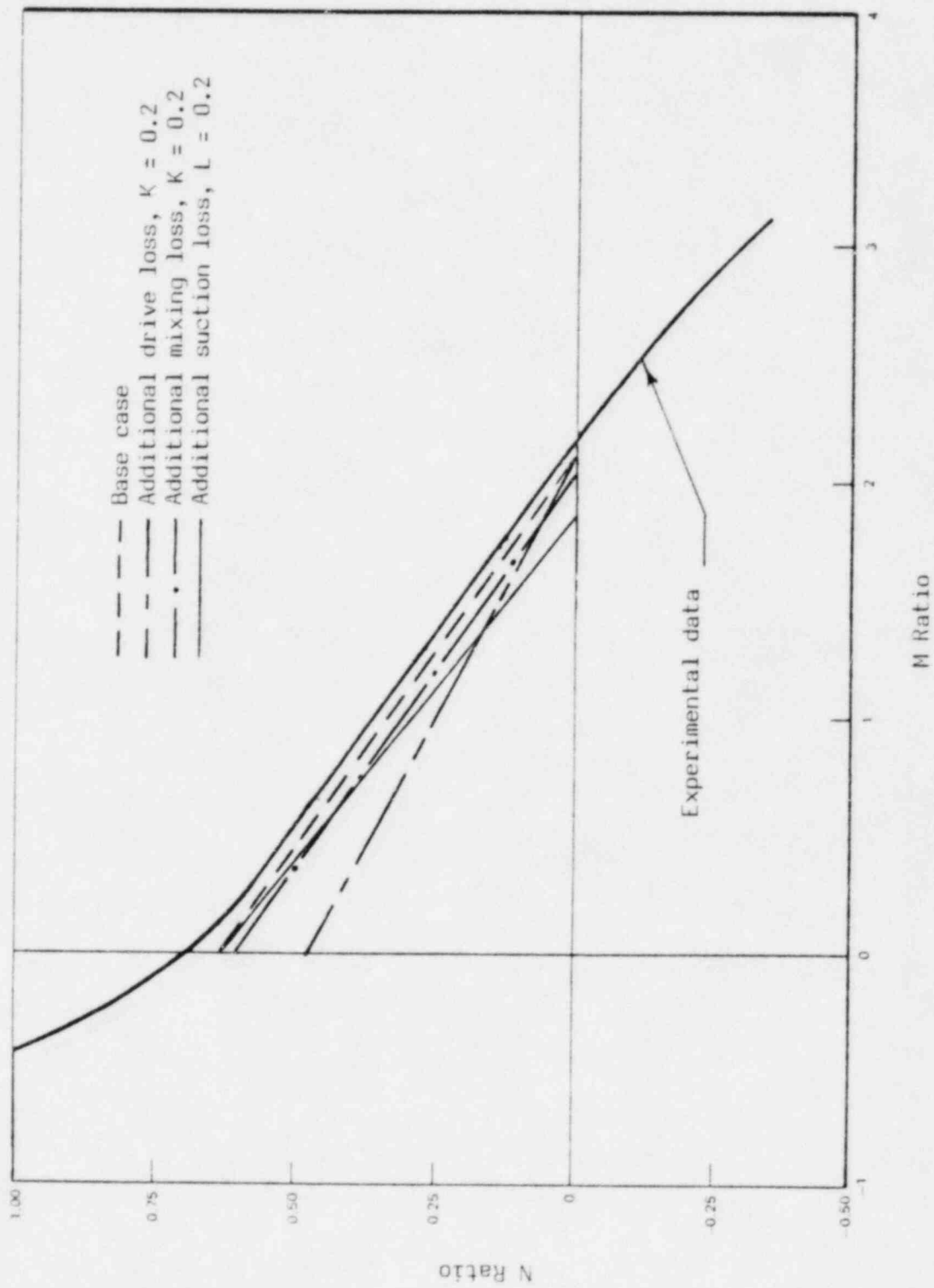


Figure 8. Jet Pump Model Design

Section 6

REFERENCES

1. G.E. Wilson, INEL One-Sixth Scale Jet Pump Data Analysis, EGG-CAAD-5357, EG&G, Idaho, Feb. 1981.
2. Flow of Fluids, Crane Company; Report No. 410, (1979).

New Coding

```

C
C      GO TO 116
C      SMOOTH PIPE
112  AVK=AJUN(I)/AVOL(K)
    AVL=AJUN(I)/AVOL(L)
    FJFG=0.0
C
C      116  DXK=DXK*AVK
    DXL=DXL*AVL
    DX=DXL+DXK
    AVKJ=AVOL(K)/AJUN(I)
    AVLJ=AVOL(L)/AJUN(I)
C
C      JUNCTION WALL FRICTIONS
    FRICFJ=(DXK*FWALF(K)+DXL*FWALF(L))*RFVFI
    FRICGJ=(DXK*FWALG(K)+DXL*FWALG(L))*RGVGJ
C
    RFVFI = RFVFI*0.5
    RGVGJ = RGVGJ*0.5
C
    CONVECTIVE TERMS FOR LIQUID AND GAS PHASES
C
    CHECK FOR SPECIAL JETPUMP MOMENTUM FLUX CALCULATIONS IN DRIVE
    OR SUCTION JUNCTIONS
    FJET = 0.0
    IF (ITYPE.NE.6 .OR. JX.EQ.3) GO TO 119
    IJET = I+(3-2*JX)*IJSKP
    IF (JX.EQ.2) GO TO 118
117  DRIVEW = AJUN(I)*(VVIDF(K)*RHOF(K)*VELFJO(I)
    * + VVIDG(K)*RHOG(K)*VELGJO(I))
    * SUCTW = AJUN(IJET)*(VVIDF(K)*RHOF(K)*VELFJO(IJET)
    * + VVIDG(K)*RHOG(K)*VELGJO(IJET))
118  IF (DRIVEW) 119,119,140
C
119  CONVE=VELF(L)**2-VELF(K)**2
    CONVG=VELG(L)**2-VELG(K)**2
    IF (VCTRL(L).LT.0) GO TO 120
    L4=.NOT.MASK(48).AND.SHIFT(IJ2(I),30)
    L4=IXPC+(L4-1)*4
    CONVE=CONVE+ARS(VELF(L))*DIFVF(L4)*AVLJ
    CONVG=CONVG+ARS(VELG(L))*DIFVG(L4)*AVLJ
120  IF (VCTRL(K).LT.0) GO TO 130
    K4=.NOT.MASK(48).AND.SHIFT(IJ1(I),30)
    K4=IXPC+(K4-1)*4
    CONVE=CONVE-ARS(VELF(K))*DIFVF(K4)*AVKJ
    CONVG=CONVG-ARS(VELG(K))*DIFVG(K4)*AVKJ
130  CONVE=CONVE+RFVFI
    CONVG=CONVG+RGVGJ
    CONVES=AVRF*CONVE
    CONVGS=AVRC*CONVG
    GO TO 144
    
```

VEXPLT	129
VEXPLT	130
VEXPLT	131
VEXPLT	132
VEXPLT	133
VEXPLT	134
VEXPLT	135
VEXPLT	136
VEXPLT	137
VEXPLT	138
VEXPLT	139
VEXPLT	140
VEXPLT	141
HXCX205	4
HXCX205	5
HXCX205	6
HXCX205	7
HXCX205	8
HXCX205	9
HXCX205	10
VEXPLT	142
VEXPLT	143
VEXPLT	144
JATX212	9
JATX212	10
JATX212	11
JATX213	7
JATX212	13
JATX213	8
JATX213	9
JATX213	10
JATX213	11
JATX213	12
JATX213	13
JATX212	16
JATX213	14
VEXPLT	150
VEXPLT	151
JATX210	166
VEXPLT	153
VEXPLT	154
VEXPLT	155
VEXPLT	156
JATX210	167
VEXPLT	158
VEXPLT	159
VEXPLT	160
VEXPLT	161
VEXPLT	162
VEXPLT	163
VEXPLT	164
JATX212	17
VEXPLT	160

Appendix A - VEXPLT

```

C *** SPECIAL CONVECTIVE TERMS FOR A JETPUMP
C
C
C 140 HALF CELL FLUX TERMS UNAFFECTED BY THE JETPUMP MIXING
AJUNT = AJUN(I)*ATHROT(I)
AJUNIJ = AJUN(IJET)*ATHROT(IJET)
SCRACH = VELFJO(I)/ATHROT(I)
CONVE = 0.5*(SCRACH**2 - VELF(K)**2)
CONVES = 0.5*VOIDF(K)*RHOF(K)*(SCRACH**2 - VELF(K)**2)
CONVF = CONVE*RHOF(K)/RHOF(A)
SCRACH = VELGJO(I)/ATHROT(I)
CONVG = 0.5*(SCRACH**2 - VELG(K)**2)
CONVGS = 0.5*VOIDG(K)*RHOG(K)*(SCRACH**2 - VELG(K)**2)
CONVG = CONVG*RHOG(K)/RHOG(A)
C
C
C ADDITIONAL FLUX TERMS FOR HALF CELL CONTAINING THE JETPUMP MIXING
RAVOL = 1.0/AVOL(L)
FLUX = VOIDFJ(I)*RHOFJ(I)*VELFJO(I)*AJUN(I)
FLUXJT = VOIDFJ(IJET)*RHOFJ(IJET)*VELFJO(IJET)*AJUN(IJET)
FLUX = FLUX*(VELF(L)-VELFJO(I)/ATHROT(I))
* FLUXJT*(VELF(L)-VELFJO(IJET)/ATHROT(IJET))
FLUX = FLUX*RAVOL
CONVE = CONVE + FLUX/(AMAX1(VOIDF(L),1.0E-5)*RHOF(A))
CONVES = CONVES + FLUX
FLUX = VOIDGJ(I)*RHOGJ(I)*VELGJO(I)*AJUN(I)
FLUXJT = VOIDGJ(IJET)*RHOGJ(IJET)*VELGJO(IJET)*AJUN(IJET)
FLUX = FLUX*(VELG(L)-VELGJO(I)/ATHROT(I))
* FLUXJT*(VELG(L)-VELGJO(IJET)/ATHROT(IJET))
FLUX = FLUX*RAVOL
CONVG = CONVG + FLUX/(AMAX1(VOIDG(L),1.0E-5)*RHOG(A))
CONVGS = CONVGS + FLUX
C
C
C STRATIFIED FLOW FORCES AND ADDED MASS REMOVED FOR JETPUMP
DIFSTF(IX+1)=0.0
FAAJ(I)=0.0
C
C
C ADDITIONAL BUILT IN FORM LOSS FOR POSITIVE DRIVE REVERSE SUCTION
IF (JX.NE.2 .OR. DRIVEW*SUCTW.GE.0.0) GO TO 144
RATON = AMIN1(SUCTW/DRIVEW,-1.0)
FJET = AMIN1(1.0+AJUNT/(AJUNIJ*RATON),0.0)**2
144 CONTINUE
C
C *** HEAD LOSS TERMS
C
C
C USER INPUTTED FORM LOSSES
SCRACH = 0.01*ATHROT(I)
FLJSS = 0.0
IF ((FJUNF(I) .EQ. 0.0) .AND. (FJUNR(I) .EQ. 0.0)) GO TO 453
IF (AVRF*VELFJO(I)+AVRG*VELGJO(I) )451,450,452
C REVERSE LOSSES
451 FLJSS = FJUNR(I)
GO TO 453
452 FLJSS = FJUNF(I)
GO TO 453

```

```

VEXPLT 167
VEXPLT 168
VEXPLT 169
JATX212 18
JATX212 19
JATX212 20
JATX212 21
JATX212 22
JATX213 15
JATX212 23
JATX212 24
JATX212 25
JATX213 16
VEXPLT 174
VEXPLT 175
JATX213 17
JATX213 18
JATX213 19
JATX213 20
JATX213 21
JATX213 22
JATX213 23
JATX213 24
JATX213 25
JATX213 26
JATX213 27
JATX213 28
JATX213 29
JATX213 30
JATX213 31
VEXPLT 192
JATX212 36
VEXPLT 194
VEXPLT 195
JATX212 37
JATX212 38
JATX213 32
JATX213 33
JATX213 34
JATX212 42
VEXPLT 197
VEXPLT 198
VEXPLT 199
VEXPLT 200
VEXPLT 201
VEXPLT 202
VEXPLT 203
VEXPLT 204
VEXPLT 205
VEXPLT 206
VEXPLT 207
VEXPLT 208
VEXPLT 209

```

New Coding  
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LISTING OF INPUT DATA FOR CASE 1

```

1 *JET PUMP TEST CASE
2 0000100 NEW TRANSNT
3 0000104 NGNE
4 0000201 0C.0 1.E-6 .05 00001 00 00 4000
5 *
6 * MINOR EDIT VARIABLES
7 0000301 CNTRLVAR C15
8 0000302 CNTRLVAR C12
9 0000303 P 020010000
10 0000304 P 040010000
11 0000305 P 070010000
12 0000306 VELFJ 012000000
13 0000307 VELFJ 032000000
14 0000308 VELFJ 072000000
15 *
16 * VOLUME CELLS
17 0100000 DIM TMDPVCL
18 0100101 7.26E-4 0.16 0.0 0.0 0.0 0.0 0.0 0.0 00
19 0100200 3
20 0100201 0.0 75.85E+5 555.
21 0200000 01 SNGLVCL
22 0200101 7.26E-4 0.16 0.0 0.0 0.0 0.0 0.0 00
23 0200200 3 75.85E+5 555.
24 0210000 02 SNGLVCL
25 0210101 7.26E-4 0.16 0.0 0.0 0.0 0.0 0.0 00
26 0210200 3 75.85E+5 555.
27 0300000 03 SNGLVCL
28 0300101 5.088E-3 0.16 0.0 0.0 0.0 0.0 0.0 00
29 0300200 3
30 0300201 0.0 75.85E+5 555.
31 0400000 01 SNGLVCL
32 0400101 5.088E-3 0.16 0.0 0.0 0.0 0.0 0.0 00
33 0400200 3 75.85E+5 555.
34 0410000 02 SNGLVCL
35 0410101 5.088E-3 0.16 0.0 0.0 0.0 0.0 0.0 00
36 0410200 3 75.85E+5 555.
37 0500000 MIX1 JETMIXER
38 0500001 3
39 0500101 6.605E-4 0.181 0.0 0.0 -90.0 -0.181 0.0 00
40 0500200 3 75.85E+5 555.
41 0501101 021010000 050000000 1.517E-4 0.000 0.236 0000
42 0501201 0.0 0.0 0.0
43 0502101 041010000 050000000 5.088E-4 0.02 1.0 0000
44 0502201 0.0 0.0 0.0
45 0503101 050010000 050000000 6.605E-4 0.07 0.07 0000
46 0503201 0.0 0.0 0.0
47 0550000 MIX2 SNGLVCL
48 0550101 6.605E-4 0.181 0.0 0.0 -90.0 -0.181 0.0 00
49 0550200 3 75.85E+5 555.
50 0600000 DIFF PIPE
51 0600001 3
52 0600101 10.277E-4 1 20.028E-4 2 33.004E-4 3
53 0600201 14.75E-4 1 26.11E-4 2
54 0600301 0.142 3
55 0600401 0.0 3
56 0600601 -90.0 3

```

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Appendix C - JET PUMP INPUT LISTING



57	0600701	-0.142	3										
58	0600801	0.0	0.0	3									
59	0601001	00	3										
60	0601101	0000	2										
61	0601201	3	75.85E+5	555.	0.0	0.0	3						
62	0501301	0.0	0.0	0.0	2								
63	0700000	DISCH	INGLVCL										
64	0700101	40.7E-4	0.1	0.0	0.0	-90.0	-1.0	0.0	0.0	0.0	0.0	0.0	0.0
65	0700200	3	75.85E+5	555.									
66	0800000	DISCH	TMDFVCL										
67	0800101	40.7E-4	0.1	0.0	0.0	-90.0	-1.0	0.0	0.0	0.0	0.0	0.0	0.0
68	0800200	3											
69	0800201	0.0	75.85E+5	555.									
70	*												
71	* JUNCTIONS												
72	0120000	JDIN	TMDFJUN										
73	0120101	01000000	02000000	7.26E-4									
74	0120200	0											
75	0120201	0.0	0.0	0.0	0.0								
76	0120202	2.0	5.63	5.63	0.0								
77	0320000	JSIN	TMDFJUN										
78	0320101	03000000	04000000	5.088E-3									
79	0320200	0											
80	0320201	5.0	-0.80	-0.80	0.0								
81	0320202	6.0	-0.80	-0.80	0.0								
82	0320203	8.0	-0.60	-0.60	0.0								
83	0320204	9.0	-0.60	-0.60	0.0								
84	0320205	11.0	-0.40	-0.40	0.0								
85	0320206	12.0	-0.40	-0.40	0.0								
86	0320207	14.0	-0.20	-0.20	0.0								
87	0320206	15.0	-0.20	-0.20	0.0								
88	0320209	17.0	0.00	0.00	0.0								
89	0320210	18.0	0.00	0.00	0.0								
90	0320211	20.0	0.20	0.20	0.0								
91	0320212	21.0	0.20	0.20	0.0								
92	0320213	23.0	0.40	0.40	0.0								
93	0320214	24.0	0.40	0.40	0.0								
94	0320215	26.0	0.60	0.60	0.0								
95	0320216	27.0	0.60	0.60	0.0								
96	0320217	29.0	0.80	0.80	0.0								
97	0320218	30.0	0.80	0.80	0.0								
98	0320219	32.0	1.00	1.00	0.0								
99	0320220	33.0	1.00	1.00	0.0								
100	0320221	35.0	1.20	1.20	0.0								
101	0320222	36.0	1.20	1.20	0.0								
102	0320223	38.0	1.40	1.40	0.0								
103	0320224	39.0	1.40	1.40	0.0								
104	0320225	41.0	1.60	1.60	0.0								
105	0320226	42.0	1.60	1.60	0.0								
106	0320227	44.0	1.80	1.80	0.0								
107	0320228	45.0	1.80	1.80	0.0								
108	0320229	47.0	2.00	2.00	0.0								
109	0320230	48.0	2.00	2.00	0.0								
110	0320231	50.0	2.20	2.20	0.0								
111	0320232	51.0	2.20	2.20	0.0								
112	0320233	53.0	2.40	2.40	0.0								
113	0320234	54.0	2.40	2.40	0.0								
114	0320235	56.0	2.60	2.60	0.0								

```

115 0320236 17.0 2.60 2.60 0.0
116 0320237 29.0 2.80 2.80 0.0
117 0320238 60.0 2.80 2.80 0.0
118 0220000 JU SNGLJUN
119 0220101 020010000 021000000 7.26E-4 0.42 0.42 0000
120 0220201 0 0.0 0.0 0.0
121 0420000 JS SNGLJUN
122 0420101 040010000 041000000 5.088E-3 0.0 0.0 0000
123 0420201 0 0.0 0.0 0.0
124 0520000 JMIK SNGLJUN
125 0520101 055010000 060000000 6.609E-4 0.0419 0.0337 0000
126 0520201 0 0.0 0.0 0.0
127 0620000 JDIFF SNGLJUN
128 0620101 060010000 070000000 40.7E-4 0.0 0.0 0000
129 0620201 0 0.0 0.0 0.0
130 0720000 JDISCH SNGLJUN
131 0720101 070010000 080000000 40.7E-4 0.0 0.0 0000
132 0720201 0 0.0 0.0 0.0
133 *
134 * CONTROL VARIABLES FOR PLOT PURPOSES
135 20500100 VDE SUM 1.0 0.0 1
136 20500101 1.E-10 1.0 VELFJ 012000000
137 20500200 VSE SUM 1.0 0.0 1
138 20500201 1.E-10 1.0 VELFJ 042000000
139 20500300 VDSE SUM 1.0 0.0 1
140 20500301 1.E-10 1.0 VELFJ 072000000
141 20500400 KVVU MULT 0.5 0.0 1
142 20500401 KHUF 020010000 CNTRLVAR 001 CNTRLVAR 001
143 20500500 KVVU MULT 0.5 0.0 1
144 20500501 KHUF 040010000 CNTRLVAR 002 CNTRLVAR 002
145 20500600 KVVU MULT 0.5 0.0 1
146 20500601 RHDF 070010000 CNTRLVAR 003 CNTRLVAR 003
147 20500700 HEADD SUM 1.0 0.0 1
148 20500701 0.0 1.0 P 020010000 1.0 CNTRLVAR 004 8.38 RHDF 055010000
149 20500800 HEADS SLM 1.0 0.0 1
150 20500801 0.0 1.0 P 040010000 1.0 CNTRLVAR 005 8.38 RHDF 055010000
151 20500900 HEADDS SUM 1.0 0.0 1
152 20500901 0.0 1.0 P 070010000 1.0 CNTRLVAR 006
153 20501000 TOP SUM 1.0 0.0 1
154 20501001 0.0 1.0 CNTRLVAR 008 -1.0 CNTRLVAR 009
155 20501100 BOT SUM 1.0 0.0 1
156 20501101 0.0 1.0 CNTRLVAR 007 -1.0 CNTRLVAR 009
157 20501200 N DIV -1.0 0.0 1
158 20501201 CNTRLVAR 011 CNTRLVAR 010
159 20501300 WD MULT 7.26E-4 0.0 1
160 20501301 RHUF 020010000 CNTRLVAR 001
161 20501400 WS MULT 5.088E-3 0.0 1
162 20501401 KHUF 040010000 CNTRLVAR 002
163 20501500 M DIV 1.0 0.0 1
164 20501501 CNTRLVAR 013 CNTRLVAR 014
165 * *****END OF INPUT *****

```

Example of control variables used to give minor edit of M, N performance curves