

NUCLEAR REGULATORY COMMISSION

T-1099
ORIGINAL

In the Matter of: ADVISORY COMMITTEE ON REACTOR SAFEGUARDS
SUBCOMMITTEE ON CLINCH RIVER BREEDER REACTOR
BRIEFING ON CLINCH RIVER BREEDER REACTOR
GEOLOGY AND SEISMOLOGY

DATE: June 1, 1982 PAGES: 1 - 290
AT: Washington, D. C.

ALDERSON  REPORTING

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1 UNITED STATES OF AMERICA
2 NUCLEAR REGULATORY COMMISSION
3 ADVISORY COMMITTEE ON REACTOR SAFEGUARDS
4 SUBCOMMITTEE ON CLINCH RIVER BREEDER REACTOR
5

6 BRIEFING ON CLINCH RIVER BREEDER REACTOR

7 GEOLOGY AND SEISMOLOGY

8 Nuclear Regulatory Commission
9 Room 1046
10 1717 H Street, N.W.
Washington, D.C.
Tuesday, June 1, 1982

11 The Subcommittee meeting convened at 8:40 a.m.,
12 pursuant to notice, M. Carbon, Chairman of the
13 Subcommittee, presiding.

14 PRESENT FOR THE ACRS:

15 M. CARBON
16 J. MARK

H. ETHERINGTON
J. RAY

17 ACRS CONSULTANTS PRESENT:

18 W. KASTENBERG
19 P. POMEROY
20 Z. ZUDANS

W. LIPINSKI
M. TRIFUNAC

21 NUCLEAR REGULATORY COMMISSION STAFF MAKING PRESENTATIONS:

22 R. STARK
23 J. KNIGHT
24
25

1 DEPARTMENT OF ENERGY STAFF MAKING PRESENTATIONS:

2 J. LONGENECKER

3
4 BURNS AND ROE, INC. STAFF MAKING PRESENTATIONS:

5 W.G. BRUSEY
6 A. DAJANI

7 WESTINGHOUSE STAFF MAKING PRESENTATIONS:

8 A. MORRONE
9 R. MALLET
10 T. PITTERLE
11 G. KRAEUTER

12 DESIGNATED FEDERAL EMPLOYEE:

13 P. POEHNERT

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P R O C E E D I N G S

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2 MR. CARBON: The meeting will now come to
3 order. This is a meeting of the Advisory Committee on
4 Reactor Safeguards Subcommittee on the Clinch River
5 Breeder Reactor. My name is Carbon. I am subcommittee
6 chairman.

7 The other ACRS members present today are:
8 Messrs. Etherington, Mark and Ray. And Mr. Mathis
9 probably will be here, subject to the airlines, and
10 perhaps Mr. Bender.

11 We also have in attendance ACRS consultants:
12 Mr. Kastenberg, Mr. Lipinski, Mr. Pomery, Trifunac, and
13 Zudans.

14 The purpose of this meeting is to discuss the
15 seismicity and associated seismic design for CRBR. The
16 meeting is being conducted in accordance with the
17 provisions of the Federal Advisory Committee Act and the
18 Government in the Sunshine Act. Mr. Paul Boehnert is
19 the Designated Federal Employee for this meeting.

20 The rules for participation in the meeting
21 have been announced as part of the notice of this
22 meeting previously published in the Federal Register on
23 Friday, May 14, 1982. A transcript of the meeting is
24 being kept and will be made available as stated in the
25 Federal Register notice. Everyone is requested to use a

1 microphone when speaking. We have received no written
2 statements or requests for time to make oral statements
3 from members of the public.

4 Before calling on Mr. Stark, I would make one
5 or two short comments and ask if you have any comments
6 and/or questions.

7 I know the purpose of the meeting is fully
8 announced and obvious and apparent. I would comment
9 that we have allowed adequate time to really dig in as
10 deeply as we wish and be sure we get answers to any
11 questions you might have in your minds. Simply from the
12 standpoint of time alone, I would suggest that you need
13 not be particularly inhibited.

14 Do you have any questions or comments to make
15 about the direction that we should take today?

16 (No response.)

17 MR. CARBON: I know that a fair amount of
18 review is accomplished, three or four or five or six
19 years ago, but a lot has changed since that time. And
20 as far as I am concerned, we are starting pretty much
21 from ground zero.

22 MR. MARK: I have a small comment in
23 connection with your remark that we can be leisurely and
24 take our time. We do have 45 minutes set down for
25 lunch.

1 (Laughter.)

2 MR. CARBON: I had not noticed that.

3 Well, if there are no other questions or
4 comments, we will proceed with the meeting and call on
5 Mr. Stark of the NRC.

6 MR. STARK: Good morning. The Staff review in
7 the seismic area is currently underway, and the results
8 will be formally documented in our SER which is
9 scheduled to be due next March.

10 However, the Staff and its consultants, USGS,
11 are present today, and one of the items you will find on
12 the agenda is a discussion of the Staff review status
13 and the review plans. And Mr. Jim Knight, who is also
14 here, will be giving that presentation later on. So
15 unless there are any other items, I guess we are
16 prepared to listen to the Applicant.

17 MR. MARK: Is the Staff already firm, however,
18 on its estimates of seismicity and seismic input?

19 MR. STARK: For the most part. We are
20 finalizing the site suitability report, and we are
21 currently reviewing that, which looks at the site and
22 the characteristics of the site. So we are farther
23 along on that item than we are on analysis of seismic
24 restraints of piping, where we have a lot more time to
25 complete that.

1 Are there any other items?

2 (No response.)

3 MR. CARBON: I guess I am not clear there.

4 Are you expecting to have the SSE from the Staff by the
5 end of this month?

6 MR. STARK: What we are doing is making sure
7 that the characteristics of that site are reasonably
8 well known so that we feel that the site is not a
9 mismatch in that respect. So we have a section that
10 addresses seismic considerations in the site suitability
11 report. It is a general discussion that looks at that
12 particular site.

13 MR. CARBON: Will it say anything firm about
14 your belief on the OBE in the SSE?

15 MR. STARK: I have to take a look. I have a
16 copy of it right now that I am reviewing, and I can show
17 it to you later on this morning, and its present
18 status. I will look and see what the words are.

19 MR. CARBON: Sometime today we would welcome
20 that.

21 MR. STARK: Okay.

22 MR. LONGENECKER: Mr. Chairman and
23 subcommittee members, good morning. I am John
24 Longenecker from the Department of Energy, the Applicant
25 in this proceeding. I am pleased to be here today to

1 present to you the details that you have requested on
2 the seismic design for the Clinch River Breeder Reactor
3 Plant Project.

4 I would like to begin by saying a few words
5 about the agenda, if I may. As I believe you are aware,
6 we have requested some modification to the agenda as
7 originally transmitted. Specifically, I would like to
8 review the agenda and identify for you who the
9 presenters will be today, at the same time identifying a
10 few small changes.

11 As noted in the handout, we will begin with a
12 review of the geology and seismology by Walter Brusey of
13 Burns and Roe. We will then proceed with the seismic
14 Category 1 structural design description by Ash Dajani,
15 also of Burns and Roe.

16 After the lunch break then we will proceed
17 with the description from four Westinghouse presenters
18 of the seismic design of the mechanical systems and
19 components. The presenters there, the first will be
20 Tony Morrone, as shown on the original agenda.

21 We would propose reordering the first three
22 presentations such that the one currently noticed as
23 V.d, Electrical Equipment by George Macrae, would be
24 proceed; second, item V.c by Tom Pitterle on Shutdown
25 System Equipment would proceed third; and the final

1 presentation under Seismic Design of Systems and
2 Components, Heat Transport Systems Equipment, would be
3 presented by Bob Mullett of Westinghouse.

4 We would then proceed, omitting item V on the
5 agenda. We believe that the summary and conclusions
6 will have been given by each of the individual
7 presenters.

8 The next item then, VII, will be reviewed;
9 that is, the NRC presentation as scheduled there. We
10 would propose at this time deleting item VIII, which is
11 the Response to two previous questions you had asked,
12 one on containment margin and the other on off-site
13 power and defer those until the next presentation we
14 have on site suitability, if that is acceptable.

15 Okay, any questions on the changes in the
16 agenda?

17 (No response.)

18 MR. LONGENECKER: Having said that, I would
19 like to give you a brief overview of what we hope to
20 present to you today. We will plan to show as the day
21 progresses in the two key areas that the seismic design
22 approach that we have used for the Clinch River Breeder
23 Reactor Project is appropriate for this use and is, in
24 fact, quite conservative.

25 In most cases, you will see that it is quite

1 similar to or identical to that used for light-water
2 reactors. The methodology, criteria, and design results
3 that we have used will demonstrate, we believe,
4 substantial conservatism. And in several important
5 design areas you will note that the SSE is the
6 controlling loading condition.

7 Again, just as with light-water reactors, we
8 have a substantial margin to accommodate seismic events
9 beyond the SSE. For your information, as we go through
10 today we will try to point out in which cases we are
11 using standard LWR criteria and in others where we are
12 departing from those due to the unique nature of the
13 LMFBR, and we will describe what criteria we have used
14 there.

15 So having said that, I would recommend that we
16 proceed with the first detailed presentation by Walter
17 Brusey of Burns and Roe.

18 (Slide.)

19 MR. BRUSEY: As you have heard, my name is
20 Walter Brusey, and I will be presenting the geology and
21 seismology section of this presentation.

22 (Slide.)

23 During this presentation I will be covering
24 the development of the more significant parameters that
25 have been used in the design of the Clinch River

1 project. I will be covering essentially how we got to
2 the location of the Clinch River site, which is shown on
3 Figure Number 1.

4 Did you all get copies of the vuegraphs?

5 And I will do that by basically covering this
6 outline. There have been rather extensive investigation
7 programs conducted over a number of years at the Clinch
8 River site.

9 I will briefly outline what we did in these
10 programs and how we got to arriving at the foundation
11 design parameters of this program. Also I will also
12 cover the earthquake history and then the selection of
13 the SSE and the OBE.

14 (Slide.)

15 This is a regional physiographic map of the
16 area. As you can see, the site is located in the valley
17 and ridge physiographic province here (indicating).
18 This particular province is roughly 25 to 55 miles in
19 width and about 500 miles in length.

20 It is characterized by northeasterly trending
21 boundaries and ridges. Topographic elevations range
22 from about 800 to 1000 feet. Rock formations that have
23 been identified in this province include the Rome
24 formation, the Conasauga, the Knox, and the
25 Chickamauga. The Knox and the Chickamauga formations

1 have been identified at the site.

2 MR. MARK: Those different areas have
3 different names.

4 MR. BRUSEY: Yes.

5 MR. MARK: Those have to do with geologic
6 characteristics? Or is it thought that those are
7 seismic provinces?

8 MR. BRUSEY: These are just geologic
9 formations, similar stratigraphy and orthology.

10 MR. ETHERINGTON: What was the radius of the
11 circle?

12 MR. BRUSEY: The province is roughly about 500
13 miles in length and about 25 to 50 miles in width.

14 MR. MARK: No, but on your chart there was a
15 circle which reached out into West Virginia and so
16 forth. That was a 200-mile, 300-mile --

17 MR. BRUSEY: This slide here?

18 MR. MARK: The radius of that bit circle.

19 MR. BRUSEY: That is only about 20 miles.

20 MR. MARK: No, no --

21 MR. BRUSEY: Oh, I'm sorry. This is roughly
22 about 200 miles.

23 (Slide.)

24 This is a site geologic map which we have
25 obtained from doing a number of site studies. Included

1 in these investigation activities are literate studies,
2 geological reconnaissance and mapping, aerial
3 photographic studies, fairly extensive boring coverage,
4 a number of observation wells that have been located in
5 this general site vicinity, and also extensive
6 geophysical investigations, including refraction and
7 cross-hole.

8 From this data it is possible to come out with
9 a geologic map of the site. As you can see, we are on a
10 peninsula of the Clinch River. This is actually a Watts
11 Bar lake. There are more levels of course, and the
12 Clinch River on Watts Bar Lake are controlled by dams
13 Lake upstream and downstream of the site.

14 The dams upstream are Meltons Hill and Norris
15 Dam, and the controlling dam downstream would be Watts
16 Bar Dam. The Knox and Chickamauga formations I
17 identified earlier. You can see the general extent of
18 these formations here. The Chickamauga formations are
19 located in this (indicating) band and, generally
20 speaking we are dealing with interbedded siltstones and
21 limestones, dipping at an angle of about 30 degrees.
22 These identified nonconformities occurred many years ago
23 towards the end of the Paleozoic era, about 280 million
24 years ago.

25 The site is located roughly here

1 (indicating). There are some other significant features
2 that probably should be identified. We were a little
3 bit concerned about potential solutioning in the
4 limestone formations, and the Knox of course is quite
5 well known in Tennessee for solutionings.

6 There are a number of sinkholes and so on that
7 have been identified in this formation. Similarly, in
8 the Chickamauga formation we have other sinkholes and
9 solutioning activity.

10 The overall thrust of the investigation was for
11 economic reasons, certainly, to try and locate the plant
12 in an area where we would have minimum solutioning. And
13 this generally meant the upper siltstone stratum in the
14 Chickamauga formations.

15 We found in our boring investigations that
16 this particular stratum had minimum solutioning. Other
17 features I might want to just point out are the terrace
18 deposits here, which of course are reasonably extensive
19 also on this branch of the river.

20 (Slide.)

21 On figure 4 we have just a brief outline of
22 the major investigation programs that are being
23 conducted. Starting in 1972 some initial work was done
24 by TVA to locate the site. And ongoing 1973 and 1974,
25 when fairly detailed work was done to prepare for the

1 PSAR. In 1975 and 1976-77, some localized
2 investigations were done not necessarily Category
3 1-related, primarily for balance-of-plant and other
4 problems related to excavation.

5 We are presently involved in a bedrock
6 verification program which is ongoing. And results, in
7 fact, preliminary results, just arrived recently.

8 As I mentioned previously, the main thrust of
9 the investigation was to define the interbedded
10 siltstone and limestone strata, the depth of the
11 weathering, to define the depths of the residual soils
12 and terrace deposits; to actually locate the nuclear
13 plant island structures in the area where we had minimum
14 solutioning; and then to carry out a detailed evaluation
15 of the foundations for the Category 1 structures.

16 MR. MARK: When you speak of borings, are we
17 thinking of 200 feet or 2000 or any particular amount?

18 MR. BRUSEY: No. Generally speaking, the
19 depths of the borings range from about 100 feet to 400
20 feet. Most of them are on the order of 200 to 300, but
21 we had a few that extended down to 400 feet.

22 MR. CARBON: I am curious as to the timing on
23 the bedrock verification program.

24 MR. BRUSEY: Sure.

25 MR. CARBON: What is the significance, if any,

1 of that being in the last year or two in contrast to
2 earlier there?

3 MR. BRUSEY: Primarily schedule. We could
4 have actually conducted this program after we had
5 excavated, but it was felt that by doing it now we might
6 save some time while we are on schedule. In other
7 words, it could be done after excavation, but that would
8 obviously mean a halt in the placement of concrete for
9 mats and so on while we continued the program. But by
10 going ahead now we can hopefully eliminate that gap in
11 the schedule within a 2-or-3-month allowance for that in
12 the original schedule.

13 (Slide.)

14 On figure 5 there is an outline of where these
15 borings are located. This is up to the end of 1974. We
16 had about 106 borings completed at that stage. As I
17 mentioned earlier, the main thrust was to identify the
18 area where we had minimum solutioning. Also, there are
19 other investigations conducted primarily to evaluate the
20 sinkholes in the Knox and also for the emergency cooling
21 tower, which is also located on this same band of
22 siltstone.

23 Also, we did some rather detailed work on this
24 portion of the nuclear plant island, primarily to find
25 out if solutioning, which you will see when I identify

1 the cross-section, any possibility of an encroachment of
2 solutioning below the major nuclear island structures.

3 The actual investigations of course consisted
4 of borings and the core from these borings were
5 evaluated, and the core recoveries were estimated using
6 of course an RQD determination; and geophysical studies
7 were conducted, extensive studies, by Western
8 Geophysical Company.

9 And as a result of this work, it was concluded
10 that the optimum location of the structure should be on
11 a band of siltstone which is roughly 400 feet wide. The
12 width of the structures is pretty close to 400, 380 or
13 so, so it was possible to place the structures entirely
14 on the siltstone stratum.

15 MR. TRIFUNAC: A question. What are the shear
16 wave velocities in the siltstone?

17 MR. BRUSEY: I am coming to that. That will
18 be part of the design parameters.

19 (Slide.)

20 On figure 6 we have a cross-section through
21 the nuclear plant island and the foundation-bearing
22 strata. You can see that the upper siltstone stratum,
23 which is roughly 400 foot wide at this section,
24 essentially supports the nuclear plant island.

25 We do have limestones, Unit A. limestone and

1 Unit B limestone bordering the upper siltstone. We were
2 concerned with respect to potential solutioning in these
3 limestones, particularly with the possibility of an
4 encroachment below the nuclear plant islands.

5 Grade elevation was established at 815; and in
6 reviewing the RQD determinations of the rock, it was
7 concluded that elevation 715 was a reasonable elevation
8 with respect to the finding of the consistent properties
9 of the foundation stratum. So that particular elevation
10 was selected as the bearing elevation for these
11 structures.

12 MR. ZUDANS: Could you help me understand what
13 RQD is?

14 MR. BRUSEY: That is the Rock Quality Index.

15 MR. ZUDANS: Fine.

16 MR. BRUSEY: That is basically the sum of all
17 the 4-inch segments of rock core occurring at any 5-foot
18 round or 10-foot round.

19 MR. ZUDANS: And this question of solutioning,
20 can you point with your pointer where these things
21 potentially might exist?

22 MR. BRUSEY: We were concerned here
23 (indicating), this is unit A limestone, the possibility
24 of solutioning extending down below the structures in
25 this zone here. The same rationale of course would

1 apply to the Unit B limestone with potential
2 encroachment here (indicating). In fact, in the bedrock
3 verification program we are presently checking this
4 limestone layer roughly 100 feet or so into the
5 limestone area to determine whether or not we have any
6 solutioning.

7 We also conducted an extensive test grouting
8 program in this area to demonstrate that this problem
9 will not occur in any reasonable time frame.

10 MR. ZUDANS: What are the consequences if you
11 cannot prove that this problem does not exist?

12 MR. BRUSEY: There are no major problems;
13 strictly one of economics. Obviously if you do find
14 this problem, then you have to go through a rather
15 extensive grouting program. But obviously, it can mean
16 a delay in schedule and so on and it also can be rather
17 expensive.

18 MR. ZUDANS: In other words, the potential
19 solutioning volumes are not too large not to be able to
20 be handled by grouting?

21 MR. BRUSEY: That is right. That is right.

22 (Slide.)

23 Figure 7 shows the location of a fairly
24 extensive test grouting program that was conducted in
25 this area to demonstrate that this particular limestone

1 layer had essentially no solutioning. This program
2 consisted of about 13 borings around boring 55. The
3 intent of the program was to check the representivity of
4 these borings.

5 Initially, the borings were placed at 20 feet,
6 and water pressure tests were conducted and then
7 grouted. And then we went inside the 20-foot spacing
8 with borings of 10 foot spacing. The overall
9 conclusions were that, based on negligible grout take,
10 foundation treatment would not be required in this zone.

11 It was also decided to extend the verification
12 program, which we are doing right now, to establish that
13 we do not have a problem across the full length of the
14 structures.

15 (Slide.)

16 As I explained, this is just a brief outline
17 of the verification program consisting of about 34
18 borings. This is an outline of the nuclear plant island
19 excavation. If you will remember the cross-section, we
20 were primarily interested in the first unit, the
21 limestone that dips under the siltstone stratum. So we
22 are extending these borings down roughly 100 feet into
23 the limestone to check that.

24 The results that I got last week indicates a
25 minimum amount of solutioning. So it looks like we are

1 able to demonstrate that the results of the test
2 grouting programs are confirmed. That is a limiting
3 conclusion, by the way, but we expect it to hold out.

4 MR. MARK: You have used the phrase "minimum
5 solutioning" several times. What does that
6 approximately mean? That you have not found any caverns
7 bigger than 20 feet across, or what?

8 MR. BRUSEY: That is right. Generally speak,
9 a small one, 1 foot, 2 foot. If my memory serves me
10 correctly, there are none at all below elevation 715,
11 below the actual bearing elevation we selected for the
12 nuclear plant island.

13 MR. MARK: But the biggest cavern that you
14 would include in your expression "minimum solutioning"
15 would be perhaps bigger than 2 feet but not as big as 10
16 or something?

17 MR. BRUSEY: That is right. That is right.
18 As you get closer to the top of the weathered rock, the
19 voids do become rather significant up to -- I think our
20 maximum size void is about 26 feet. But that is,
21 generally speaking, fairly close to the top of the
22 weathered rock, and it obviously does not affect the
23 bearing capability of the nuclear plant island
24 structures.

25 But there is obviously a fair amount of

1 solutioning at the site, and it is not too unusual to
2 find a major sign of voids in the highly weathered
3 portion of the rock.

4 MR. ZUDANS: On the other cross-section that
5 you showed, I thought you indicated some potential for
6 the other coordinate as well.

7 MR. BRUSEY: That is right. Yes.

8 MR. ZUDANS: Now you are exploring this corner
9 and the other corner. What is in between? What makes
10 you sure there are no problems in between?

11 MR. BRUSEY: We have done some rather detailed
12 work in the siltstone, and as I say below elevation 715
13 we just have not got a problem. In the unit B siltstone
14 also below elevation 715, no problem. As I say, as you
15 approach the top of the weathered rock of that unit B
16 limestone, you do find rather extensive voids and
17 cavities, but nothing below 715.

18 MR. MARK: Excuse me. If you have a couple of
19 bore holes of four bore holes on the 30-foot -- these
20 things are roughly 30-40-foot spaces?

21 MR. BRUSEY: Yes.

22 MR. MARK: Supposing you have those. It is
23 possible to imagine that all of the middle where you did
24 not bar is empty.

25 MR. LONGENECKER: Yes. Yes. .

1 MR. MARK: Is there a technique whereby you
2 can use some signals to ascertain that there are not any
3 big holes between this drilling and that drilling?

4 MR. BRUSEY: Yes. We can use cross-holes
5 techniques to establish whether there are or not.

6 MR. MARK: Are those used?

7 MR. BRUSEY: Yes. In the foundation stratum
8 below the nuclear plant island, we did cross-hole work
9 to establish the dynamic properties to be used in the
10 seismic design and the engineering properties, as I
11 mentioned before, were consistent, and the velocities
12 were consistent -- in other words, there was no evidence
13 of solutioning below the structures.

14 It is quite likely that if cross-hole work was
15 conducted in the unit B limestone above elevation 715,
16 the velocity pattern might be rather erratic and could
17 demonstrate that solutioning did exist between borings.
18 But that is not really of concern with respect to the
19 foundation integrity of the nuclear plant island.

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1 (Slide.)

2 In addition to borings, there were also some
3 other investigations conducted primarily in the faulting
4 area to check on the possibility of capable faulting.
5 Of course the two major fault lines in this area are the
6 White Oak Mountain fault and the Copper Creek fault.
7 The White Oak Mountain fault is about 1.7 miles from the
8 site. The Copper Creek fault outcrops about something
9 on the order of 1,500 to 2,000 feet from the site.

10 These faults were investigated. On the Copper
11 Creek fault, extensive work was done, including borings
12 and mapping of outcrops, and samples were recovered
13 which were possible to date. Dr. Wampler of Georgia
14 Tech did the dating, and he found by radiometric methods
15 of testing argon methods, that the age of the Copper
16 Creek fault was on the order of 280 million years old.

17 This confirms other geological consensus on
18 the age of faults in the area.

19 (Slide.)

20 We were also a little bit concerned about
21 localized faulting occurring in the substratum,
22 particularly below the nuclear plant island structure,
23 and from the borings a shear zone was noted. This
24 plane, generally speaking, occurs throughout the length
25 of the nuclear plant island in the Unit A limestone.

1 Extensive investigations were conducted to establish
2 whether or not there would be any potential for movement
3 of the zone. It was concluded, based on a consensus of
4 geological opinion once again that this is an ancient
5 and rehealed yield zone, and no possibility of
6 movement.

7 (Slide.)

8 Another investigation was conducted at the
9 request of the NRC on some injection wells which are
10 located at the ONL site about four miles from the Clinch
11 River site. This is the method that ONL had elected to
12 dispose of radioactive waste. This is mixing
13 radioactive waste with grout and injecting under
14 pressure at depths on the order of 800 feet by
15 hydraulically fracturing the shale formations. It was
16 suggested perhaps by the NRC that the so-called Denver
17 analogium could be applied. Apparently, this particular
18 problem did crop up in Denver when they were disposing
19 of waste, and this created a triggering mechanism which
20 resulted in seismic activity.

21 The same rationale is applied here, and it was
22 thought that perhaps by injecting this waste, we might
23 be able to lubricate an existing fault plane, thereby
24 triggering activity. Once again, extensive
25 investigations were conducted to establish whether this

1 problem just could not occur. The magnitude of both the
2 pressures and the amount of waste that was being
3 deposited in this area was such that it would just not
4 be possible to lubricate a fault plane and create
5 seismic activity.

6 (Slide.)

7 Going to the development of the foundation
8 design parameters that were used for both the static and
9 dynamic design of the structures, as I mentioned earlier
10 we had a rather extensive boring program, and of course
11 the static properties are derived from testing
12 representative samples of the core in the lab, and
13 design compression tests were conducted.

14 In situ pressure meter tests were also done to
15 establish a range for the static properties. From these
16 properties calculations were done to determine what the
17 acceptable bearing capacity would be, and also what the
18 likely settlement might be. These numbers were more
19 than adequate. In fact, the actual depth of excavation
20 is considerably in excess of the estimated static wave
21 of the plant structures.

22 It is quite likely that the settlement, which
23 may be on the order of a half inch, may be primarily due
24 to recompression as a result of minor or potential
25 elastic rebound after the excavation has been completed,

1 but of course installing some geotechnical
2 instrumentations, these are electrical extensometers to
3 monitor potential heave and settlement, both during the
4 excavation and also during the actual placement of
5 concrete and the construction of the nuclear plant
6 island.

7 As outlined here, it is anticipated that the
8 movements will be negligible, something of less than a
9 half inch. As far as the dynamic properties are
10 concerned, as I mentioned earlier, geophysical
11 investigations were conducted by Western Geophysical.
12 This included refraction lines, also cross hole, up
13 hole, and down hole, and also some continuous velocity
14 measurements by Birdwell.

15 As a result of these investigations,
16 properties were established for the siltstone and
17 limestone strata. In situ velocity measurements
18 generally resulted in a number like 6,200 feet per
19 second as the shear wave velocity for the siltstone.
20 Based on some work that Dr. Hendron had done, who is our
21 rock mechanic consultant, a rock reduction factor was
22 applied to these in situ velocity measurements,
23 resulting in a modulus of approximately 1.5 million psi
24 and a plus or minus 25 percent variation was placed on
25 the modulus. That was the number that is being used for

1 seismic design.

2 MR. MARK: I believe you said 6,200 fps for
3 the siltstone?

4 MR. BRUSEY: Right.

5 MR. MARK: What is the corresponding number in
6 the limestone that seems to also be part of the
7 immediate environment?

8 MR. BRUSEY: Around 9,000 or so.

9 MR. MARK: 9,000 in the limestone?

10 MR. BRUSEY: Yes. And that is by applying a
11 reduction factor and so on. The modulus corresponding
12 dynamic modulus was on the order of 3 million. So there
13 are two numbers that have been used for seismic design:
14 1.5 million for siltstone and 3 million for limestone.

15 MR. MARK: Another question. You are only
16 three miles from the K25 plant, I think?

17 MR. BRUSEY: Right. Three or four miles.

18 MR. MARK: Is the local geology similar enough
19 that its experience in settlement has any relevance to
20 your estimates here?

21 MR. BRUSEY: We are pretty sure of our
22 foundation properties, so we are pretty sure basically
23 of our orders of deformation for both rebound and
24 resulting settlement. I can't really say the same for
25 the K25. I am not sure of the order of magnitude you

1 are talking about.

2 MR. MARK: I am believing they had no trouble
3 at all, and I was supposing you could use that as a
4 parallel statement if the geology had a resemblance.

5 MR. BRUSEY: That's right, yes.

6 MR. MARK: But you haven't done that?

7 MR. BRUSEY: No, we have not checked the
8 actual records of the K25 plant.

9 (Slide.)

10 Going on to seismology and the derivation of
11 the values to be used for the SSE and OBE, of course, on
12 Figure 13 is the regional earthquake map. Outlined
13 here, we have seismic events that have occurred in the
14 50-mile radius and also in the 25-mile radius. Of
15 course, there is the major earthquakes that control
16 seismicity for the site.

17 The three that are significant are, of course,
18 the New Madrid, the Charleston, and the Giles County
19 earthquake. The New Madrid and Charleston are roughly
20 300 miles from the site, and of course, based on the
21 attenuation relationships for both New Madrid and
22 Charleston, it was established that New Madrid would
23 have an intensity 6, 7 at the site, and Charleston would
24 have an intensity 6 at the site. These are the maximum
25 historical earthquakes that have occurred at the Clinch

1 River site.

2 The controlling earthquake is the Giles County
3 earthquake, which occurred in 1897. That is roughly 220
4 miles from the site, and this area here, this, of
5 course, is New Madrid, and this is Charleston
6 (indicating).

7 MR. CARBON: Where again was the Giles County?

8 MR. BRUSEY: Giles is up here. There is a
9 more detailed vu-graph coming showing the actual
10 location of Giles.

11 MR. TRIFUNAC: Could I ask a question
12 regarding the preceding vu-graph that had a 50-mile
13 radius?

14 MR. BRUSEY: Yes.

15 MR. TRIFUNAC: Are you going later on at some
16 time to tell us what are the recurrence relationships
17 for the earthquakes within this 50-mile radius? What
18 are the A and B parameters for the number of earthquakes
19 with this intensity?

20 MR. BRUSEY: We are presently not doing any
21 studies in the probabilistic area.

22 MR. TRIFUNAC: I didn't imply probabilistic.
23 I just asked whether you had A and B's in the
24 relationships.

25 MR. BRUSEY: We do have them, right. I don't

1 have them with me, but I could get them for you.

2 MR. TRIFUNAC: Would you get them, please?

3 MR. BRUSEY: Right.

4 (Slide.)

5 This is a tectonic province map of the general
6 area. This particular map was developed by Law
7 Engineering Company. It is quite similar to some of the
8 other maps that have been developed in recent years by
9 USGS and others. The Giles County earthquake, as I
10 mentioned earlier, is roughly here (indicating), the
11 epicenter, about 220 miles from the site, which of
12 course is here (indicating). We, of course, have
13 adopted the tectonic province approach to defining the
14 SSE, which is to define the intensity of the maximum
15 historical earthquake in that province, which of course
16 is the Giles County, and you can move that earthquake to
17 the site. Then, having done that, to define an
18 acceptable intensity acceleration and core acceleration
19 correlation.

20 There is a reasonable amount of controversy on
21 the intensity for the Giles County earthquake.

22 (Slide.)

23 Figure 15 is an isoseismic map of the Giles
24 County earthquake. This map was developed by a combined
25 study of Law Engineering and Burns and Roe to establish,

1 based on felt observational effects, what the intensity
2 should be. As a result of this extensive study, it was
3 concluded that the intensity of the Giles earthquake
4 should be classified as an intensity 7-8. In completing
5 the study, we consulted with a number of recognized
6 authorities on southeastern U.S. seismicity. At the
7 same time, other studies were being conducted by the
8 NRC.

9 MR. POMEROY: Before we leave that, could I
10 ask you what the consensus is that you managed to arrive
11 at there? It seems to me that there has been a rather
12 definitive study in the literature by Ballenger where he
13 has defined the epicentral intensity as definitely 8.
14 And I noticed in your PSAR also that you use 7 to 8,
15 based on this work, I assume.

16 MR. BRUSEY: Right; yes.

17 MR. POMEROY: And I would like to ask you what
18 consensus you developed, because most of the people that
19 I know classify that as intensity 8.

20 MR. BRUSEY: We consulted with Dr. Ballenger.
21 He was one of the consultants on that study. He
22 originally had written -- classified that as a 7-8. His
23 opinion today may be an 8, but at that time it was a
24 7-8. We also consulted with Dr. Timothy Long of Georgia
25 Tech, who also did an independent assessment; and a

1 number of other consultants, particularly TVA, who had
2 been involved in many studies in the area. But as I
3 say, it is quite likely that Dr. Ballenger has perhaps
4 changed his opinion now.

5 MR. CARBON: I am sorry. I can't hear you.
6 Would you repeat your last statement?

7 MR. BRUSEY: That Dr. Ballenger may have
8 changed his mind relative to the time when we did this
9 study, which was back in '75, '76.

10 MR. CARBON: And you are saying he may now
11 believe it was an intensity 8?

12 MR. BRUSEY: Well, I am just assuming from
13 what you just said.

14 MR. POMEROY: I believe he has published in
15 the Seismological Society of America to that effect.
16 Can I make another comment here?

17 MR. BRUSEY: Sure.

18 MR. POMEROY: I also noticed in your listing
19 of earthquakes that you list the Charleston earthquake
20 as an intensity 9 event; and that is based, according to
21 the references in the PSAR, on a telephone conversation
22 with Leonard Murphy who at that time was at NOAA, who is
23 now deceased of course; yet everything that is published
24 on that particular earthquake indicates that the
25 intensities were intensity 10. Would you comment on

1 that, please?

2 MR. BRUSEY: We have used intensity 10 in our
3 computations for determining what the historical
4 intensity would be for the Charleston at the site; but
5 intensity 10 was used.

6 MR. POMEROY: So then you don't believe what
7 is written in the PSAR?

8 MR. BRUSEY: Well, that will be modified.

9 (Slide.)

10 On this vu-graph, we have a number of
11 acceleration intensity relationships which were reviewed
12 in order to establish the basis for defining the SSE and
13 the resulting accelerations. As I mentioned earlier,
14 based on our studies, we had concluded that an intensity
15 7-8 would be satisfactory for the Giles County; and the
16 NRC indicated that in their opinion an 8 was the correct
17 classification. So that is the number we have used in
18 order to come up with an SSE, and also the resulting
19 acceleration value.

20 Also looking at the various relationships, one
21 can see that a number of them -- these have been used
22 for licensing of other nuclear power plants, including
23 Goltavor on the Rhine and Guttenberg-Richter, and
24 others-- however, the most conservative relationship has
25 been selected, which is Trifunac-Brady, or also Coulter,

1 Waldron and Devine, or Neumann. And based on this
2 relationship here on intensity 8, the maximum
3 acceleration was defined at .25.

4 Initially of course .18 G is the number that
5 had been selected originally, and this was raised of
6 course to the .25.

7 MR. ZUDANS: In terms of calendar time, when
8 was this changeover made from .18 to .25?

9 MR. BRUSEY: I would say around '76.

10 MR. ZUDANS: That was prior to completion of
11 the design of the structure and components?

12 MR. BRUSEY: Right. But the .25 was
13 incorporated in the actual seismic design and in fact
14 the OBE controls in many cases, particularly with
15 respect to structural design. And as I point out here,
16 we did select the OBE of approximately a one-half SSE,
17 which is of course a very conservative approach. There
18 have been a number of sites licensed that were evaluated
19 less than one-half SSE. The OBE has selected at less
20 than half the SSE. We could have adopted that approach
21 also I believe in the Clinch River project, but it was
22 decided to stay with the conservative approach of
23 one-half SSE.

24 MR. ZUDANS: So if I read your comment
25 correctly, the basic design of all the components was

1 done at .25?

2 MR. BRUSEY: Right.

3 MR. ZUDANS: In other words, you did not have
4 the design completed already before the change was
5 discussed?

6 MR. BRUSEY: That's right.

7 MR. MARK: In '76, when you say the number was
8 chosen, you indicated on the slide you had up that it
9 was done in collaboration to some extent at least or in
10 antagonism with the NRC?

11 MR. BRUSEY: Yes, right.

12 MR. MARK: Is that to be taken that the people
13 in the NRC in 1976 agreed that .25 was big enough?

14 MR. BRUSEY: Yes, yes. That is also the value
15 that has been used on a number of other nuclear power
16 plants in the area, primarily plants presently being
17 constructed by TVA and in fact in operation by TVA.
18 That .25 is the number that is actually being used.

19 So, just to sum up then, we have done
20 extensive geologic, geotechnical, and seismologic
21 investigations over the past ten years, in order to
22 arrive at the data that you have seen here today. It is
23 believed that there is inherent conservatism because we
24 still feel that intensity 7-8 is appropriate for Giles
25 County. We have elected to use a rather intensive

1 acceleration relationship, and of course the OEE has
2 also been selected at one-half SSE.

3 That more or less completes the presentation,
4 if there are no more questions.

5 MR. TRIFUNAC: There are some questions. What
6 is the conservative intensity acceleration relationship?

7 MR. BRUSEY: I think one has to go over the
8 background and precedent, in that a number of nuclear
9 power plants have been licensed with extensive
10 acceleration relationships, not quite as conservative as
11 the ones that I showed on the vu-graph, such as the
12 Coulter, Waldron and Devine upper rock line.

13 MR. TRIFUNAC: How conservative is that
14 relationship?

15 MR. CARBON: Excuse me, Mr. Brusey. Could you
16 move your microphone up closer? I am having great
17 difficulty hearing you.

18 MR. BRUSEY: Basically on background and
19 precedent, as I mentioned, you are probably familiar
20 with a number of these relationships that have been used
21 in the past. Plants have been licensed successfully
22 using these relationships.

23 MR. TRIFUNAC: I don't disagree that they have
24 not been using those relationships. You made the
25 statement that they are conservative, and I would like

1 to know how much. Can you tell, for example, what data
2 have been used by Coulter, Waldron and Devine? What is
3 the data base for that relationship?

4 MR. BRUSEY: They did establish three curves
5 related to rock conditions at the site. Basically, low
6 strength, medium strength, high strength rock. So data
7 obviously --

8 MR. TRIFUNAC: They have established the
9 curves, but have they demonstrated where the data for
10 those curves came from?

11 MR. BRUSEY: I am not sure. I would have to
12 check on that.

13 MR. TRIFUNAC: I am not sure either. That is
14 why I would like to know, because in all the years I
15 have never seen the data, and if you say those are
16 conservative, I think we should be able to demonstrate
17 that. I have not seen the data ever before, so I think
18 we should look at that. You have used the curve by
19 Trifunac and Brady. Have you read his paper?

20 MR. BRUSEY: Yes.

21 MR. TRIFUNAC: Did you read the statement that
22 the authors suggest that this curve should not be used
23 in this work?

24 MR. BRUSEY: Yes.

25 MR. TRIFUNAC: And you think it should still

1 be used?

2 (Laughter.)

3 MR. BRUSEY: As you probably saw, there are
4 three curves. They all happen to fall on the same line,
5 the Trifunac, Brady, and Neumann, and also the Coulter,
6 Waldron and Devine. So all three curves indicated that
7 a conservative approach could be taken.

8 MR. TRIFUNAC: What is the conservative
9 approach, then?

10 MR. BRUSEY: Well --

11 MR. TRIFUNAC: If at least one of the three
12 authors suggest that this curve should not be cited, if
13 Neumann's curves recognize that virtually no data was
14 available and Coulter, Waldron, and Devine being a set
15 of curves for which the data was never published, what
16 is so conservative about this kind of procedure?

17 MR. BRUSEY: Well, obviously, there may be
18 some scarceness of data, particularly for rock site. We
19 obviously have to do a little bit of checking to
20 establish what Coulter, Waldron, and Devine used to
21 develop those curves. I'm not sure, but we can
22 obviously check on that.

23 MR. TRIFUNAC: Don't you think we should
24 actually check if we are going to base our judgment on
25 that?

1 MR. BRUSEY: Yes, sure.

2 MR. TRIFUNAC: Could we see some of the data?
3 Could you check into that?

4 MR. BRUSEY: Yes, we will check into that and
5 let you know.

6 MR. TRIFUNAC: You do remember reading the
7 statement that the Trifunac Brady should not be used in
8 this work? You do remember that? So that is assumed
9 not to be conservative, right?

10 MR. BRUSEY: Well, the data that was used, of
11 course, was soil data primarily, as to how that is
12 applied to the rock site, but based on, as I say, the
13 hard rock data that presumably Coulter, Waldron and
14 Devine has, this curve could be used.

15 Are there any more questions?

16 MR. POMEROY: Yes. Could I ask a question
17 with regard to -- there is a statement in the PSAR work
18 that I read having to do with the depth of some of the
19 earthquakes in the area, which establishes the depths at
20 49,000 to 69,000 feet. Could you give us some idea of
21 the uncertainty that is associated with those depths?
22 For example, because you have used that as an argument,
23 that that seismicity could not be associated with the
24 nearer surface faulting?

25 MR. BRUSEY: Well, there has been a lot of

1 speculation as to whether or not some of the seismic
2 activity has occurred in the sedimentary rocks rather
3 than the basement rocks, but my understanding is that no
4 legitimate data has been presented that one would reach
5 the conclusion that this seismic activity is occurring
6 at the shallow depths. In fact, the preponderance of
7 evidence is that it is a suppression peak in the
8 basement. I think that is still the present consensus
9 of opinion for that area.

10 MR. POMEROY: Could you outline what that
11 preponderance of evidence is?

12 MR. BRUSEY: Primarily geologic opinions by
13 consultants who have worked in the area for many, many
14 years, people like, I believe, Dr. Malichi and others.

15 MR. POMEROY: There are some other seismic
16 networks operating in the area. There have been some
17 recent instrumentally located events, and those events
18 have a certain depth associated with them and some
19 uncertainty. And what I am trying to explore is the
20 amount of uncertainty and whether some of that activity
21 could have been occurring at shallower depths.

22 MR. BRUSEY: I believe it is still in the
23 speculation stage. I don't believe any data have
24 actually been produced to demonstrate activity, as I
25 say, at the shallow depths.

1 MR. POMEROY: And they have been produced at
2 deeper depths by definition. Is that correct?

3 MR. BRUSEY: Well, that is still the
4 prevailing opinion, certainly, that all activity is
5 occurring in the basement.

6 MR. POMEROY: Again, and I do have a question
7 about prevailing opinion, because I do not know that
8 that is necessarily the prevailing opinion of the entire
9 community, in view of the fact that there is really --
10 you are correct, there is very little data, and given
11 that lack of data, there is a great uncertainty as to
12 the actual depth of occurrence.

13 MR. BRUSEY: Yes. Obviously, the answer is,
14 more data on microseismic networks would help in this
15 area.

16 MR. POMEROY: Are there any plans to do that
17 at all in this area?

18 MR. BRUSEY: Nothing definitive. This is
19 still a subject for discussion amongst ourselves. It is
20 quite likely that something like this might evolve in
21 the near future.

22 MR. MARK: I would like to ask, Pomeroy, would
23 you educate me just a little bit on this possible
24 significance of these things really being at 25,000 feet
25 instead of 60?

1 MR. POMEROY: Well, yes. There is a statement
2 in the PSAR that it is generally accepted that there is
3 a so-called thin-skinned tectonics in this area, and
4 that most of the ancient faulting that we are observing
5 here, such as the thrust faults that were described, are
6 associated with or are what they call listric faults,
7 that are associated with a large-scale structure at a
8 rather shallow depth.

9 If all the earthquakes are occurring deeper
10 than that, then they are not associated probably with
11 these nearer surface faults; that they could have
12 occurred at shallower depths, and they may be associated
13 with these nearer surface faults, and there may be some
14 movement occurring on these faults, which then has some
15 implications for what we are talking about here.

16 MR. MARK: Thank you.

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1 MR. POMEROY: Speaking of that, though, can I
2 then ask a question of where that statement came from,
3 again, that it is generally accepted that that
4 thin-skinned tectonic approach is the correct approach?
5 Again, I know people that are violently opposed to
6 that.

7 MR. BRUSEY: Well, we have used a number of
8 consultants in this area. I believe, Law Engineering
9 and their geologists were in consultation with people
10 like Dr. Kouchi, and that was based on discussions with
11 someone like Kouchi that this conclusion was reached.
12 And also, of course, TVA has done extensive work in this
13 area, and their geologists also have reached similar
14 conclusions.

15 MR. KASTENBERG: I have a general question.

16 MR. BRUSEY: Sure.

17 MR. KASTENBERG: If Burns & Roe were to
18 construct a plant on this site which did not require an
19 NRC license such as a chemical plant or an oil-fired
20 plant, what would be your design parameters in terms of
21 accelerations? How would you arrive at them?

22 MR. BRUSEY: Well, we would probably use the
23 Uniform Building Code approach which may result in
24 values perhaps on the order of .1g or .12 g, that kind
25 of number.

1 MR. KASTENBERG: And that would be sufficient
2 to protect the investment in the plant?

3 MR. BRUSEY: Right. This would be an approach
4 used at, say, for fossile plant design or industrial
5 plants where you are generally speaking on a different
6 order of magnitude when we have to design for a nuclear
7 plant.

8 MR. POMEROY: I have another question related
9 to that. I am not sure you are the proper person to
10 address it to, but I will. You mentioned the upstream
11 dams. Could you tell us what the design of the seismic
12 design criteria for those dams is?

13 MR. BRUSEY: I believe analyses were conducted
14 by TVA. They really handled that particular aspect of
15 the work. I understand that they did the analysis for
16 both OBE and SSE, combined with the various flood
17 stages, but I am not really familiar with the details of
18 the analysis.

19 MR. POMEROY: Could we ask, Mr. Chairman, to
20 have somebody from the TVA to give us that information,
21 as to the design criteria that went into those?

22 MR. CARBON: Yes, we certainly can. I suspect
23 that information will be presented to us at the
24 so-called site suitability meeting which is later this
25 month. But I see no reason why we cannot ask for it

1 earlier, if you have the information. Is it available
2 at this time?

3 MR. BRUSEY: I think the information is
4 available I think it is just a matter of content.

5 MR. GAESER: We would have to get hold of
6 that. I don't know whether we could have it today or
7 not, but we will try to get it and get back to you.

8 MR. POMEROY: Would it be correct to assume
9 that at the site suitability hearing that we would also
10 hear about possible effects of a failure of that
11 structure, if indeed there were more criteria applied to
12 that structure?

13 MR. BRUSEY: That is right, yes.

14 MR. TRIFUNAC: Could I ask one more question,
15 please? Could you put on the viewgraph, I believe,
16 number 13? It is the one that has regional earthquakes
17 with intensity exceeded for MMI. It has a 50-mile
18 radius and a 200-mile radius.

19 (Slide.)

20 I think the copy I have is a little bit better
21 than the viewgraph, but working with that difficult, is
22 it reasonable to say that the 50-mile radius over there
23 of the first site appears to have more circles in it
24 than some areas, meaning that more earthquakes have
25 occurred there?

1 MR. BRUSEY: Intuitively, perhaps, yes. The
2 actual rate is a little bit --

3 MR. TRIFUNAC: It is a little bit higher?

4 MR. BRUSEY: Yes.

5 MR. TRIFUNAC: Would it be reasonable to say
6 that it is higher than perhaps the region where the
7 Giles County earthquake occurred?

8 MR. BRUSEY: Probably.

9 MR. TRIFUNAC: I am sorry?

10 MR. BRUSEY: Probably, I think, yes.

11 MR. TRIFUNAC: Now, if you ask -- how many
12 years did we have the historic record for, 100, 200, 300?

13 MR. BRUSEY: Roughly 150, 200 years, yes.

14 MR. TRIFUNAC: If we have, by some miracle,
15 500 years, would you still think that 7 to 8 would be a
16 good number?

17 MR. BRUSEY: Most of the events that have
18 occurred in that area have been very small.

19 MR. TRIFUNAC: I am aware of that, I agree.
20 But I am asking about your judgment.

21 MR. BRUSEY: Yes. Obviously, a design basis
22 has to be arrived at, and the approach that has been
23 suggested and the one we followed that is obviously in
24 the Reg Guides and so on, is to select the maximum
25 historical earthquake in the province, and the

1 historical record, of course, was known when that
2 particular approach was suggested.

3 MR. TRIFUNAC: Does Appendix A say that the
4 largest historical earthquake should be taken as the
5 maximum earthquake to be considered at a site? Or does
6 it say that it should be considered in the selection of
7 the largest earthquake?

8 MR. BRUSEY: Considered is the word, but in
9 actual practice that is what has been used in nuclear
10 power plant design.

11 MR. TRIFUNAC: Do you believe this is a good
12 approach?

13 MR. BRUSEY: Yes.

14 MR. TRIFUNAC: And you are not disturbed by
15 the fact that this 50-mile radius appears to have a
16 higher seismicity than some other regions on the map?

17 MR. BRUSEY: No. As I mentioned earlier, the
18 number of events are quite small, and there are
19 obviously many areas where you can have a considerable
20 amount of microseismic activity and get design values
21 less than the SSE that are still lower than the values
22 that we are --

23 MR. TRIFUNAC: Is this some microseismic
24 activity on the map?

25 MR. BRUSEY: No, this is obviously not. But

1 it is in the range of low values, 3's, 4's and 5's.

2 MR. TRIFUNAC: Does that exclude the
3 possibility?

4 MR. BRUSEY: No, it doesn't exclude it, no.
5 Then you are getting into the probability area, and
6 right now we have we have not done any studies in that
7 particular area that particularly relate to the SSE.

8 MR. TRIFUNAC: Are you suggesting that taking
9 the largest historical earthquake is not the
10 probabilistic statement? I mean, the way you put it, it
11 appears as though I am not supposed to get into the
12 probabilistic area. Are you saying that taking the
13 largest historic accident for the design basis is not a
14 probabilistic approach?

15 MR. BRUSEY: Well, it is an approach that as I
16 mentioned before, background and precedence indicates
17 that people should follow, and that is what we have
18 done. Are you indicating that we should arbitrarily go
19 higher because we have some seismic activity that
20 indicates a number of events, small events perhaps, a
21 little more frequently than in another area?

22 MR. TRIFUNAC: I am not trying to suggest
23 anything in particular. I am trying to understand the
24 distinction between the precedent, historic approach and
25 to me what appears to be the physics of the problem, and

1 I am trying to see how you reconcile the two. You do
2 feel comfortable with the 7 to 8?

3 MR. BRUSEY: Yes, yes.

4 MR. TRIFUNAC: If you do take a probabilistic
5 approach, if you have a pesallia sequence of
6 earthquakes, what is the expected value of the largest
7 number, if you have the largest historical value? Would
8 it be still 8?

9 MR. BRUSEY: Right. Well, you get into a
10 whole historical area: how many events constitute a
11 data base.

12 MR. TRIFUNAC: Have you done this?

13 MR. BRUSEY: No, we have not done any
14 probabilistic studies to the SSE.

15 MR. TRIFUNAC: Thank you.

16 MR. CARBON: I would like to ask a couple more
17 questions along that same line.

18 MR. MARK: I have a very simple one. An
19 earthquake of intensity 4 to 5 -- at what distance can
20 that thing be imagined to be recorded in the last 150
21 years, or is it only with instruments that you can pick
22 those up anyway, intensity 4 to 5?

23 MR. TRIFUNAC: Four to five is at the limit of
24 perceptibility. Level 4 is near perceptibility for
25 California; I guess for this part of the country, 3 is

1 nearer that level.

2 MR. MARK: I am imagining that part of the
3 lack of earthquakes in western Tennessee across the last
4 150 years is that there was nobody that close to a
5 magnitude, or an intensity 4.

6 MR. TRIFUNAC: That could be.

7 MR. MARK: This is Oak Ridge and Knoxville
8 that is in that 50-mile area, and there we will know
9 everything that happened for the last 40 years.

10 MR. TRIFUNAC: That is quite possible, yes.

11 MR. CARBON: I would like to inquire a little
12 further on Dr. Trifunac's question of probability. You
13 pointed out that we do certain things a certain way with
14 LWR's and we do something there that I would like to
15 inquire if we are already doing it here.

16 We do not design on the basis of probability,
17 but nevertheless, there is some consideration that if
18 the return frequency leads us to some acceleration value
19 and then something quite a bit less likely gives us
20 quite a bit higher acceleration, we can take some
21 comfort in the fact that we have a fair amount of safety
22 built into the structure, perhaps, of an LWR plant.

23 I think it would be appropriate for us to be
24 taking somewhat the same kind of view here, the same
25 kind of question, and then this question of return

1 frequency becomes of importance in that.

2 Can you -- maybe this is the same question Dr.
3 Trifunac asked you to reply to -- can you give me any
4 feeling at all for what sort of return frequencies we
5 might get into with the magnitude of the acceleration
6 you have assumed here, and then how it would vary as we
7 go to higher intensity or higher acceleration?

8 MR. BRUSEY: I can't really because as I
9 mentioned, we have not really done any probabilistic
10 studies at all related to the SSE. So I really cannot
11 answer your question.

12 MR. CARBON: You stated on many of the other
13 things that it has been a matter of people's judgment
14 and beliefs. Would you have any judgment on this
15 question?

16 MR. BRUSEY: Well, numbers like one times
17 10 return period, on that order would perhaps be a
18 number that one might arrive at, going through the
19 probabilistic analysis. But as I say, that is just
20 speculation. We have not done the work ourselves yet,
21 and there has been some discussion about doing some
22 study like that but we have not reached any firm
23 conclusion on that.

24 MR. CARBON: Would your judgment give you any
25 suspicion as to what accelerations you might have with a

1 -5 -6
2 return frequency of 10 or 10 ? How much more
3 severe would it be?

4 MR. BRUSEY: Well, probably higher, but I
5 cannot give you any numbers on that.

6 MR. CARBON: May I ask, Dr. Trifunac, when you
7 were asking for the As and Bs in the equation, which I
8 do not appreciate, was that aimed at that question?

9 MR. TRIFUNAC: That would be included there,
10 but this is the basic information on the seismicity of
11 an area. From A and B I can calculate what the return
12 period is, I can calculate how many earthquakes of
13 different sizes one can expect through a given period of
14 time.

15 It is not really only a probabilistic
16 question; it is a general question of seismicity in the
17 area, and I think this will be very valuable
18 information, especially because usually, intuitively, I
19 do see a lot of little circles in there, perhaps more
20 than in some other places. So it would be good to see
21 how much larger seismicity may be there than the overall
22 uniform average over the entire 200 mile radius.

23 But yes, you could answer your question if you
24 had As and Bs, definitely.

25 MR. CARBON: And I guess you indicated you
26 would provide those?

1 MR. BRUSEY: Yes.

2 MR. CARBON: What kind of timescale did you
3 mean? Did you mean today?

4 MR. BRUSEY: I am sure for the site
5 suitability meeting. What date is that particular
6 meeting?

7 MR. BOEHNERT: The 24th and 25th of June.

8 MR. BRUSEY: Is that an acceptable date?

9 MR. CARBON: Yes.

10 MR. POMEROY: Can I bring up one other
11 question, just following along your question? I would
12 like to see some statement of the amount of uncertainty
13 associated with those determinations, because of the
14 questions regarding the intensities and the basic
15 seismicity information that goes into the calculation of
16 those values.

17 MR. BRUSEY: Okay, okay.

18 MR. CARBON: Any other questions? Bill?

19 MR. KASTENBERG: Yes. In the PRA that is
20 going to be done for the plant, will you be considering
21 the earthquake as an accident initiator in a
22 probabilistic sense?

23 MR. BRUSEY: I think perhaps I could give this
24 to DOE to answer.

25 MR. GROSS: We are in the process of

1 establishing what scope we will have for that PRA right
2 now. We haven't finalized that, but certainly that is
3 one of the things we would consider in seismic as an
4 initiator, obviously.

5 MR. CARBON: It was my understanding in
6 something that I read that perhaps your PRA study would
7 be broken into maybe three or four phases, and that you
8 have committed to phase one, and perhaps it did not
9 include in phase one anything on seismicity. Am I
10 correct, or do I have things mixed up?

11 MR. GROSS: We have broken it into several
12 phases, if only from a contractual standpoint. Phase
13 one is preparation based on fault trees and event
14 trees. Seismic is part of that. But phase two is more
15 detailed analysis of the detailed scope for that.

16 MR. CARBON: And will the seismicity aspect be
17 part of phase two?

18 MR. GROSS: We haven't finalized that yet. I
19 am sure it would be considered.

20 MR. CARBON: I guess you're saying you don't
21 know at this time?

22 MR. GROSS: At this time I don't know. I feel
23 confident that seismic analysis will be a part of the
24 PRA. To what extent we have not finalized yet.

25 MR. CARBON: Are there any other questions?

1 (No response.)

2 Thank you, Mr. Brusey. Mr. Dajani?

3 MR. DAJANI: Good morning, my name is Ash
4 Dajani, I am with Burns & Roe. I will describe this
5 morning the procedures that we used in the seismic
6 analysis and the design of the Clinch River plant.

7 (Slide.)

8 First, let me describe to you the outline of
9 the presentation. I will first recap some of the
10 pertinent site characteristics that influence the
11 seismic analysis, the applicable codes and standards
12 that we used in the seismic analysis and design, the
13 seismic classifications for the various structures
14 within the plant, then a description of the seismic
15 analysis of the nuclear island, the category 1
16 structures and the category 3 structures as well. Then
17 an overall summary of conservatisms or margins in the
18 overall situation.

19 (Slide.)

20 You saw a viewgraph earlier of the site that
21 showed we have inclined layers of siltstone and
22 limestone. We described on this occasion as well as
23 last week that the finished grade elevation is 815 feet,
24 and the sound rock elevation varies. However, the
25 deepest point is approximately 80 feet below grade.

1 The nuclear island is founded on a mat that is
2 on elevation 715. The SSE zero period acceleration as
3 we have heard earlier was selected at .25g and the OBE
4 at .125g, half the SSE.

5 (Slide.)

6 The codes and regulatory guides that are used
7 are things that you have seen before, I am sure. We
8 used the design spectra from Reg Guides 1.60 damping
9 values, the combination of modes and the rules for that
10 in the response analysis, and the development of the
11 response spectra to be used by equipment from Reg Guide
12 1.122, NUREG-75-087. Sections 3.7.1 and 3.7.2 are also
13 applicable in this area, as well as Appendix 3.7(a) of
14 the PSAR.

15 (Slide.)

16 First, so that we get our definitions in line,
17 just let me describe to you briefly the seismic
18 classifications, seismic category classifications.
19 Seismic category 1 are those structures that either
20 contain and perform a safety function and they are
21 designed for both SSE and OBE. Seismic category 2 are
22 primarily designed for OBE to protect plant investment,
23 and category 3 are those that do not perform a safety
24 function. However, a part of those category 3
25 structures that are adjacent to category 1 structures

1 and whose failure could jeopardize the integrity of
2 category 1 structures are analyzed and designed for the
3 SSE, and I will describe that a little bit later.

4 (Slide.)

5 The main structure that I will cover is first,
6 the nuclear island. I will be coming to that very
7 shortly to describe to you what the nuclear island is
8 comprised of. The other category 1 structures are the
9 emergency cooling tower and the diesel generator
10 building.

11 The category 3 structures that I will address
12 that are adjacent to the category 1 structures are the
13 turbine generator building and the radwaste building.

14 (Slide.)

15 First, a description of the nuclear island.
16 The nuclear island is the one that I will be passing
17 this marker on. It is the reactor service building, the
18 containment building, the steam generator building, the
19 control room building, and the electrical equipment
20 building as well as the steam generator building. This
21 is the nuclear island.

22 (Slide.)

23 A cross-section. This would be the nuclear
24 island (indicating). As you can see, the nuclear island
25 is founded on a common foundation mat, and the mat width

1 and length are as shown here, and the mat thickness is
2 as we described last week, about 15 feet.

3 (Slide.)

4 MR. KASTENBERG: Before you go on, where do
5 the steam lines come through?

6 MR. DAJANI: I beg your pardon?

7 MR. KASTENBERG: The steam lines from the
8 intermediate heat exchanger, from the steam generator.

9 MR. DAJANI: In this cross-section we show one
10 of the evaporators and a super heater, so it goes from
11 what is not shown here -- here is the steam drum. So
12 the steam flow goes through the evaporator into the
13 steam drum, back into the super heater, from the super
14 heater to the turbine generator.

15 MR. KASTENBERG: When you say the turbine
16 generator building is seismic 3 and you have a pipe that
17 runs through that building, how do you characterize --

18 MR. DAJANI: The pipe is anchored at the
19 interface between the two buildings.

20 MR. KASTENBERG: How do you characterize that,
21 seismic 1 or 3?

22 MR. DAJANI: The steam line itself, there is
23 an isolation valve that is seismic category 1 up to the
24 first isolation valve; seismic category 3 beyond that;
25 similar to the pressurized water reactor where you have

1 an isolation valve right outside containment.

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1 MR. KASTENBERG: Then where do you find the
2 aux feedwater system?

3 MR. DAJANI: The aux feedwater system is in
4 this area, I think, on the other side, and there is a
5 tank, protective water storage tank, and three pumps
6 that pump the water into the steam drum. Then you have
7 lines between it and the auxiliary heat removal
8 equipment, which is the protective air cooler condenser
9 and the return line to the pumps.

10 MR. KASTENBERG: What would that seismic
11 category be?

12 MR. DAJANI: One. All this equipment in this
13 nuclear island is all seismic category 1.

14 (Slide.)

15 The input motions that were used for the
16 seismic analysis are three; three statistically
17 independent artificial accelerations that were
18 synthesized to envelope the design response spectra that
19 is found in Reg Guides 1.16, normalized at the zero
20 period to .25g for the SSE.

21 The overall duration of the input motion --
22 and this is just an example of what it looks like --

23 (Slide.)

24 -- is 20 seconds digitized at the .01 second
25 intervals. There is a one-second buildup for strong

1 motion, to get to the strong motion, and three seconds
2 for decay.

3 I have said before that the time histories are
4 such that when you get a response spectrum out of it, it
5 envelopes the NRC response spectrum, and as you can see,
6 generally does that. I will describe now the methods of
7 seismic analysis in the various buildings.

8 (Slide.)

9 First, the nuclear island. We used the lumped
10 mass method for direct integration of equations of
11 motion. We characterized the foundation springs and
12 dampers through an analysis first of a static finite
13 element analysis of the rock/soil characteristics. We
14 used the finite element analysis as well as we checked
15 it against the half-space theory and the results were
16 very much in agreement. The reason we used the static
17 finite element analysis was primarily to take into
18 consideration the inclined layering underneath the
19 plant.

20 The directional effects were combined by the
21 square root of the sum of the squares, and the degrees
22 of freedom at the response points included translations
23 and rotations in all three directions.

24 MR. TRIFUNAC: Question. If I understand
25 correctly, you used the finite element program to get

1 the compliances for the foundation materials because
2 there is this inclination of the layers going down,
3 right?

4 MR. DAJANI: Yes. And --

5 MR. TRIFUNAC: How was the inclination
6 included in the arrival of seismic waves' program? Was
7 that considered?

8 MR. DAJANI: How were the waves included?

9 MR. TRIFUNAC: Let me repeat: How was this
10 inclination of the layering included in the analysis of
11 the wave arrival?

12 MR. DAJANI: It was not. As I said, what we
13 did was to characterize the -- to get the compliance
14 functions, we used the static finite element analysis.
15 That was, in turn, coupled with the lumped mass model.

16 MR. TRIFUNAC: I understand. That was quite
17 clear to me. But that tells us what the reasonable
18 values are, numerical values, for compliances.

19 MR. DAJANI: Yes.

20 MR. TRIFUNAC: But what I am getting at is the
21 input motion. The input ground motion is obviously also
22 influenced by the fact that these layers are not
23 horizontal, that they are at some angle. What I was
24 trying to find out was whether this was included in the
25 analysis.

1 MR. DAJANI: No, it was not.

2 MR. TRIFUNAC: Do you think this might be an
3 important thing? You obviously considered it for
4 compliances. Why didn't you consider it for input
5 motion?

6 MR. DAJANI: Primarily because the tools and
7 the methods available to us were available to come up
8 with a characterization of the soil characteristics,
9 including the inclination through the static finite
10 element analysis. We did not have the tools to go any
11 further in the area that you are commenting on.

12 MR. TRIFUNAC: Well, I understand the
13 limitation of the tools, but do you think that this
14 should be considered? Do you think it may be important?

15 MR. DAJANI: Well, I can say this. We have,
16 in addition to having done it with the lumped mass
17 approach, analyzed in response to one of the staff's
18 questions the entire nuclear island through the finite
19 element analysis using FLUSH, in which we did include
20 the layering -- not at an inclined angling; as you know,
21 the code does not allow for inclusion of
22 inclinations -- but we did include the layering, and the
23 results were shown to be very much in agreement; and in
24 fact, the lumped mass approach was a little bit more
25 conservative.

1 MR. TRIFUNAC: Well, recognizing the
2 limitation of the tools, LUSH is also limited in telling
3 you a number of other things as well. You are still not
4 answering my question, but perhaps it is not possible.

5 MR. DAJANI: It is not possible. We haven't
6 done it. You asked me the question how do I feel about
7 it. I do not think it is sensitive, because we have
8 done it through a completely different method and the
9 results were quite close.

10 MR. TRIFUNAC: Which other method?

11 MR. DAJANI: The FLUSH.

12 MR. TRIFUNAC: The FLUSH cannot handle that
13 either. How does FLUSH handle that?

14 MR. DAJANI: We included the layering of the
15 soil. We included the horizontal. Instead of inclined,
16 we included them as horizontal layers for the different
17 soil properties, so that was included.

18 MR. TRIFUNAC: Could you please explain?

19 MR. DAJANI: In the FLUSH analysis, let me see
20 if I can find a backup Vu-graph.

21 MR. TRIFUNAC: If this is coming later, maybe
22 we can postpone that.

23 MR. DAJANI: No, it is not coming later. It
24 is just that in order to answer your question, I said in
25 the case of the lumped mass we did not consider the

1 effect of the inclined layers on the response, so I
2 cannot give you a direct answer.

3 You asked me whether I felt it would be
4 significant or not and I said I don't believe it would
5 be significant, and the reason I say that is because we
6 did model the nuclear island through a finite element
7 analysis using a completely independent method which
8 included the layering effect of the substructure
9 although not the inclination, and the results were very
10 much in agreement in the responses between the two
11 methods.

12 That is the basis for my saying that I do not
13 believe the inclinations inherently or intuitively would
14 have a big effect.

15 MR. TRIFUNAC: I understood that perfectly.
16 My question is this: How do you know that they do not
17 have an effect, given the limitations of the tools that
18 you have? That is really what I am getting at.

19 MR. DAJANI: I do not know.

20 MR. TRIFUNAC: Does FLUSH handle that?

21 MR. DAJANI: No, it does not handle inclined
22 layers.

23 MR. TRIFUNAC: So how do we then conclude that
24 they are not important in determinating the input
25 motion?

1 MR. DAJANI: You asked for my opinion. I gave
2 you my opinion. You apparently disagree with the way I
3 arrived at the conclusion.

4 MR. TRIFUNAC: No, I don't. I am just trying
5 to see what the logic is.

6 MR. DAJANI: That is the logic.

7 MR. TRIFUNAC: So then, is it reasonable to
8 say that we can't tell, because the tools don't let us
9 decide?

10 MR. DAJANI: We can't tell but I hate to leave
11 it like that. We can't tell but we don't believe it is
12 sensitive is my judgment.

13 MR. TRIFUNAC: Can we make judgments about
14 sensitivity if the tools are not capable of telling us
15 whether this is important or not?

16 MR. DAJANI: I understand you can't.

17 MR. TRIFUNAC: Thank you.

18 MR. ZUDANS: Could I bother you with a few
19 more?

20 MR. DAJANI: Sure.

21 MR. ZUDANS: You said that the static finite
22 elements analysis was done. Was that a two-dimensional
23 model?

24 MR. DAJANI: Correct.

25 MR. ZUDANS: That included the layers. And

1 how did you orient the two-dimensional model on this
2 one, relative to the layers?

3 MR. DAJANI: The same angle as the 30 degree
4 dip, basically.

5 MR. ZUDANS: In other words, you made the
6 plane perpendicular to the layer?

7 MR. DAJANI: Perhaps I can show you a picture
8 of it.

9 MR. ZUDANS: Yes, because those layers are
10 very steep inclinations, not negligible.

11 MR. DAJANI: They were at basically a 30
12 degree dip, if I am not mistaken. Walter, you mentioned
13 that earlier.

14 (Slide.)

15 MR. ZUDANS: This is the model, right?

16 MR. DAJANI: Yes, this is the one direction.
17 The other direction, we have a similar configuration
18 although the reason I picked this one is to hopefully
19 respond to your question of how we modeled the area
20 which has the inclinations. In the other direction, you
21 don't have this kind of an effect.

22 MR. ZUDANS: Did you have another model
23 transverse to this model?

24 MR. DAJANI: I beg your pardon?

25 MR. ZUDANS: Did you have another model that

1 was 90 degrees to this model?

2 MR. DAJANI: Yes. Would you like to see that?

3 MR. ZUDANS: No. Just yes or no.

4 MR. DAJANI: Yes. And we have another one for
5 the torsion.

6 MR. ZUDANS: Do you have another model that
7 does not include inclination on the static analysis?

8 MR. DAJANI: Not with the static analysis.

9 MR. ZUDANS: Just layers? That is what would
10 have given at least some support for your intuition.

11 MR. DAJANI: I am going to perhaps give you
12 something that is equivalent. While we did not do it
13 with the static finite element analysis, we did another
14 check by assuming homogeneous material, removing the
15 area above the foundation, in other words assuming a
16 half space, and calculated the compliances, and checked
17 those against a half space approach, and the answers
18 were very close and in fact not that different from the
19 one that resulted from the inclined layers.

20 MR. ZUDANS: Now are these materials
21 properties differences in layers between 6, 7 and 11
22 great, the differences?

23 MR. DAJANI: Well, the 11 I believe is
24 siltstone which had a modulus of elasticity of 1 1/2
25 million. Which other layers?

1 MR. ZUDANS: Six or seven.

2 MR. DAJANI: Seven is the limestone unit A
3 which had a modulus of elasticity of 3 or thereabouts.

4 MR. ZUDANS: Three?

5 MR. DAJANI: And I am not sure about 6. It is
6 siltstone, the same.

7 MR. ZUDANS: What about the 5?

8 MR. DAJANI: The 5 is 3 million.

9 MR. ZUDANS: So you have a siltstone 6 and
10 11, connected by a stiffer layer which is 7?

11 MR. DAJANI: Slightly stiffer, although as we
12 found, the primary compliance really came from the
13 effect of the siltstone, which is intuitively obvious
14 since it is sitting on it.

15 MR. ZUDANS: Now, the portion 10 probably
16 wouldn't affect you anyway. That is outside the scope.

17 MR. DAJANI: That is right.

18 MR. ZUDANS: So there might be a way to
19 conclude what you concluded intuitively.

20 Now the other direction -- there is another
21 question. You said you had three statistical
22 independent artificial earthquake time histories,
23 north-south, east-west, and vertical.

24 MR. DAJANI: Yes.

25 MR. ZUDANS: How are those oriented to this

1 cross-section? What is the east-west here? How is this
2 cross-section oriented to east-west?

3 MR. DAJANI: It is east-west.

4 MR. ZUDANS: Exactly east-west?

5 MR. DAJANI: Yes.

6 MR. ZUDANS: This is how you will apply these?

7 MR. DAJANI: Yes.

8 MR. ZUDANS: What would happen if you rotated
9 the earthquake input at different angles?

10 MR. DAJANI: Well, what we do is we input the
11 motion individually to each of the three models. Then
12 we would calculate the responses and add them up by the
13 square root of the sum of the squares.

14 MR. ZUDANS: I guess the way you did it
15 wouldn't matter because you assume a homogeneous
16 foundation in this instance.

17 MR. DAJANI: For this area, right.

18 MR. ZUDANS: So in reality, it would be
19 different because the layers were affected.

20 MR. DAJANI: But as I said earlier, it seemed
21 from the calculations and from the results the basic
22 effect is from the siltstone layer which is directly
23 underneath, and the others modify very slightly those
24 results.

25 MR. ZUDANS: Thank you.

1 MR. TRIFUNAC: Could I have the same viewgraph
2 back?

3 MR. DAJANI: This one?

4 MR. TRIFUNAC: Yes.

5 (Slide.)

6 Just so that we don't take the static analysis
7 too far, the dynamics perhaps, you would have the
8 earthquake waves coming from east towards the site.

9 MR. DAJANI: Yes.

10 MR. TRIFUNAC: We have made earthquake waves
11 coming from the west over the site. Would the motion be
12 qualitatively the same, do you think?

13 MR. DAJANI: The motion I would think would
14 not be qualitatively the same because the angle of
15 incidence is different depending on the direction. If
16 we are coming down from this direction it is hitting an
17 oblique line; if you are coming from this direction
18 (indicating), so I would expect reflections and
19 transmission would be somewhat different. But whether
20 or not the results -- which is what we are really
21 after -- after all, the responses would be that
22 different I really cannot tell -- all I am saying is that
23 based on the fact that we did it through two different
24 ways, we came up with generally the FLUSH analysis now I
25 am talking about, and the lumped mass approach, we

1 generally came out with the similar responses, very
2 similar responses. In fact, lumped mass was a little
3 bit more conservative.

4 So I think the effect of the inclination is
5 not that significant. I don't think we are going to
6 necessarily reach a convergence on the answer, because
7 we have not done it; therefore, we don't really know.

8 MR. TRIFUNAC: Well, using your good
9 engineering judgment, would you be concerned if you
10 looked at this picture and saw that there is a
11 possibility that the incident seismic waves might be
12 focused by the geometry that you have? Wouldn't you be
13 concerned? Wouldn't you want to find out about this?

14 MR. DAJANI: It depends. To be honest with
15 you, I think, using my good engineering judgment, as you
16 said, I think the approach from A to Z is so full of
17 conservatisms including the analysis and design of the
18 structures that things like that may be nice to find out
19 what the effect would be, but I do not believe that it
20 will affect the final answer in any way, form or fashion.

21 I will be describing later on some of these
22 conservatisms that are not only found, as you heard
23 previously, in the selection of the earthquakes, but
24 also in the approach of the design of the nuclear
25 structure.

1 MR. TRIFUNAC: Let me ask you a question about
2 conservatism. I think we are using that word too
3 frequently and in a too liberal way. Do I understand
4 that something is conservative if something is a little
5 bit larger than perhaps it should be?

6 MR. DAJANI: A little bit larger?

7 MR. TRIFUNAC: A little bit larger than
8 perhaps it is.

9 MR. DAJANI: Not a little bit larger; quite a
10 bit larger, I would say.

11 MR. TRIFUNAC: Is it conservative not to
12 consider something at all? How conservative is
13 something that I do not consider at all?

14 MR. DAJANI: I really can't answer that
15 question. It becomes very philosophical. I think you
16 cannot draw a conclusion whether it would be
17 conservative if you do not consider it. For example,
18 simplified methods tend to be conservative.

19 MR. TRIFUNAC: Let me ask a question. You
20 have an engineering structure. Is it conservative not
21 to analyze the stresses or deformations of the forces in
22 that structure that may be physically there? You
23 totally exclude the forces. Is that a conservative
24 action from an engineering point of view?

25 MR. DAJANI: If your general approach has

1 enough conservatism in other areas, such that such
2 things will not be important, I think we won't
3 categorize it as conservative, but does it make a
4 difference becomes the question. As I said before, we
5 did not analyze the situation. I really do not wish to
6 give you an answer beyond what I just said. You asked
7 me for my opinion and I just gave you my opinion.

8 MR. TRIFUNAC: I am not looking at this
9 picture at all; I am just trying to find out: is it
10 conservative not to consider something and then argue
11 that because other things are conservative, that
12 something we have not considered is not going to be
13 importnat. Is that a conservative factor?

14 MR. DAJANI: I can think of many situations
15 where what you said would not mean it is conservative.
16 I can think of other situations where what you said does
17 mean it is conservative. I don't think there is a
18 general answer to that kind of a question.

19 MR. TRIFUNAC: So then we cannot conclude that
20 this might be conservative, right?

21 MR. DAJANI: Maybe yes.

22 MR. TRIFUNAC: Would you agree with that?

23 MR. DAJANI: I cannot conclude positively that
24 this is conservative or unconservative. I cannot
25 conclude either.

1 MR. TRIFUNAC: Thank you.

2 MR. ZUDANS: I am sorry, you won't get away
3 that quickly.

4 (Laughter.)

5 MR. DAJANI: Go ahead, Dr. Zudans.

6 MR. ZUDANS: If you now would have been able
7 to represent this foundation as a continuous foundation,
8 I assume that when you talk about lumped structure
9 analysis, you have just lumped the point of support to
10 the soil. That single point of support for the soil
11 assumes the mat is rigid, and therefore it has its
12 compliances derived from this analysis.

13 Now if you look from the left corner to the
14 right corner, because of the proximity of this layer
15 number 7, that big piece of foundation might be stiffer
16 than the other corner which is strictly on the
17 siltstone.

18 Now are you concerned in any way whatsoever
19 about the fact that the mat sees different stiffness
20 foundations that are along the plans?

21 MR. DAJANI: I don't think that we found that
22 there is a difference, but I can ask the question of
23 George Siegal, from Burns & Roe. Do you know the answer
24 to that?

25 MR. SIEGAL: When we calculated the functions

1 we considered the properties of all the layers. We
2 found that the effect of the limestone was not
3 significant. The predominant difference was the
4 stiltstone that is immediately under the foundation.

5 MR. DAJANI: So whether it was here or there
6 (indicating) --

7 MR. ZUDANS: Looking at your model that you
8 are showing there and seeing that you only have a single
9 element at that corner, or at least I assume that is the
10 finite element layouts that you are showing me?

11 MR. DAJANI: Right.

12 MR. ZUDANS: You couldn't really have any
13 decent resolution. If you go steeper in the left corner
14 you only have a single element through layer 7; right?

15 MR. DAJANI: I am not really sure if this
16 viewgraph --

17 MR. SIEGAL: Yes, that represents that.

18 MR. ZUDANS: Okay, so you really do not have
19 any detailed resolution around that corner.

20 MR. SIEGAL: You are not looking for detailed
21 stresses. What you want is the overall stiffness.

22 MR. ZUDANS: That is exactly what I am talking
23 about. The 6 and 11 are essentially the same. You have
24 a single element that is much more rigid which connects
25 these. Maybe you get good enough information for all

1 the response. I am not so sure. We will have to look
2 at your numbers.

3 What you are trying to tell me is there was no
4 variability of foundation conditions from left to right.

5 MR. DAJANI: To my knowledge, that is right.

6 MR. ZUDANS: I still have to say that Dr.
7 Trifunac is right. Things that you did not investigate
8 you cannot talk about as being conservatisms.

9 MR. CARBON: Let's pause at this point and
10 take a break, and at the end of the break, let's
11 interrupt Mr. Dajani's presentation. The staff has
12 seismology and geology people here, both from the staff
13 and from the USGS. Let's address any questions that we
14 have to them at that time, and then they probably will
15 leave by noon and will not be available this afternoon.

16 So if you would, be thinking of your questions
17 during the break.

18 (A short recess was taken.)

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1 MR. CARBON: Mr. Stark, I wonder if you could
2 comment on who of your people you have here.

3 MR. MARK: What would be fair questions?

4 MR. STARK: We have representatives of the
5 geolog" and seismology review, Mr. Rothman, and
6 McMullen, and I guess they both can kind of make a
7 status report right now very briefly, and then also
8 speak very briefly, Mr. McMullen first.

9 MR. MC MULLEN: My name is Dick McMullen. I
10 am a staff geologist. I am responsible for reviewing
11 the geology of the Clinch River site. Also here is Mr.
12 Delvicki and Mr. Robert Dowl of the U.S. Geological
13 Survey. We are right in the middle of our review right
14 now, and as part of that review, we are making a site
15 visit tomorrow and for the rest of the week, focusing on
16 during that site visit looking at some of the features
17 in the subregion, looking at some of the core from the
18 site and reviewing the status of the solution
19 verification program around the site.

20 We will also be looking at some of the high
21 level terraces which may show some sort of relationship
22 with the sheer zones and faults in the area. We have a
23 number of questions which are still outstanding which
24 the applicant is preparing answers to now. These
25 questions mainly are about some of the things Dr.

1 Pomeroy brought up a while ago updating the PSAR to
2 reflect some of the geologic and seismic work that has
3 been going on in the southeast since publication of the
4 PSAR.

5 The Geosciences Branch has a great deal of
6 experience in this part of the southeast in the valley
7 and ridge province. We have reviewed at least four
8 other sites there, Phipps Bend, Sequoyah, Watts Bar, and
9 Belafonte. Back in the middle seventies, the staff
10 wrote a limited work authorization report for site
11 suitability report, and we have just completed updating
12 that in the last few weeks. There is still a lot of
13 information out, but based on what we know now there is
14 no reason to believe that the site is not suitable at
15 the present time.

16 MR. CARBON: Questions?

17 MR. MARK: In connection with reviews of
18 Sequoyah, I believe the governing earthquake would again
19 have been the Giles County?

20 MR. ROTHMAN: I am Robert Rothman. I am the
21 staff seismologist reviewing the site. We also have Mr.
22 David Berkens of the U.S.G.S. here to answer questions.
23 We are very early on in our review, but you asked the
24 question about the Sequoyah site.

25 MR. MARK: I am thinking, not early on the

1 Sequoyah review.

2 MR. ROTHMAN: No, we are early on now on the
3 Clinch River.

4 MR. MARK: But was Giles County not the
5 governing earthquake for Sequoyah?

6 MR. ROTHMAN: Yes, that was.

7 MR. MARK: What is its intensity?

8 MR. ROTHMAN: Intensity 8. During the
9 Sequoyah review, the earthquake was also characterized
10 as a magnitude of 5.8 body wave magnitude and a site
11 specific spectra were used for the Sequoyah site, rather
12 than using the intensity 8 as the design for the site.
13 Actual records were obtained from a magnitude 5.8
14 earthquake, plus or minus a half a magnitude unit, and
15 these were -- the actual strong motion records were used
16 to compare the design of the site with the ground motion
17 which we believe is expected from an earthquake of that
18 size.

19 MR. MARK: So it would be consistent with what
20 has happened at Sequoyah and perhaps at a couple of the
21 other plants we mentioned, to define Giles County as an
22 intensity 8?

23 MR. ROTHMAN: Yes, that's right.

24 MR. POMEROY: Then would you comment on the
25 question of what the effective design acceleration was

1 for Sequoyah, given the fact that it is a site specific
2 spectrum?

3 MR. ROTHMAN: The staff compared the design
4 spectra for Sequoyah with the site specific spectra that
5 was obtained, and although there was some exceedence at
6 certain frequencies of the design spectra, the staff
7 made a judgment that it was acceptable, and the Sequoyah
8 design was accepted. I believe the Sequoyah spectra was
9 a -- I don't remember the spectrum, but it was less than
10 the Reg. Guide spectrum and it was anchored at at .18
11 G. It was a modified neumark spectrum, and it was
12 anchored at .18 G, and that was almost equivalent to the
13 site specific spectra as .18 as determined by the TVA.

14 MR. POMEROY: Could you comment on whether the
15 staff has done any of the calculations that Dr. Trifunac
16 was talking about earlier, specifically return periods
17 and that sort of thing?

18 MR. ROTHMAN: The staff has not done
19 anything. There was a probability study done during the
20 Sequoyah review, and I am not totally familiar with that
21 because we just don't use probability for determining
22 SSE's. We do use them in a confirmatory manner, but we
23 do not use the probability itself. But I believe, if I
24 remember rightly, the results of the probability study
25 showed that the Sequoyah spectrum was somewhere on the

-3 -4

1 order of 10⁻³ to 10⁻⁴ . In that range, we looked at
2 it plotted on the same curve with the uniform hazard
3 spectra that was developed under the probabilities.
4 Those are the kind of numbers that stick in my mind.

5 MR. POMEROY: Is the staff generally in
6 agreement with the listings of earthquakes? Has the
7 staff reviewed those earthquake listings in the PSAR,
8 and are they in agreement with the intensities and
9 completeness of the list?

10 MR. ROTHMAN: No, the staff has a question
11 outstanding right now about the seismicity to the
12 applicant. We have asked them to update it and look at
13 more recent studies that have been done. We have also
14 asked them to look at some recent work that was done by
15 Professor Ballenger on the Giles County earthquake, and
16 those are still outstanding.

17 MR. POMEROY: Perhaps this is a question for
18 Dick McMullen, but is the staff in agreement with the
19 structural interpretation that is presented in the PSAR
20 as it is at this time?

21 MR. MC MULLEN: Yes, generally. Of course,
22 the PSAR has not been updated to reflect the latest
23 information there, including the studies that went on
24 around Charleston, but it essentially comes to the same
25 bottom line.

1 MR. POMEROY: And would they be in agreement
2 then with regard to the depths of earthquake occurrence
3 and the possible significance of those depths of
4 occurrence as they are outlined in the PSAR? That is
5 probably a question for Bob Rothman.

6 MR. ROTHMAN: I am not convinced how good the
7 depths are of the earthquakes in that region. I have
8 been talking to some of the people at the U.S.G.S. who
9 have been relocating some of those events, and there is
10 not a local network in that area, so they do not have
11 very much control on the depth. They don't have very
12 much confidence in their depth, so that is the way it
13 stands right now.

14 MR. POMEROY: So how are you proposing they
15 pursue that question of whether or not the earthquakes
16 maybe associated with the shallower structures on such
17 sonambulistic faults that are drawn in the cross
18 section, or are you questioning that?

19 MR. ROTHMAN: I haven't raised a question on
20 that. What we have done is asked them to update their
21 seismicity, providing all the information they can,
22 including the best depth estimates on that, but we
23 haven't particularly addressed the thin skin tectonics.

24 MR. POMEROY: Would you think that association
25 might be significant, though, Bob?

1 MR. ROTHMAN: Yes, I think it would be, but I
2 am not convinced that we can tie it down just on the
3 data that is currently available. I think we will have
4 to wait until we see the latest relocations to see if
5 they are that way. If we are getting depths on the
6 order of tens of kilometers, then it is on the order of
7 two or three kilometers. It is not clear yet what we
8 are going to see.

9 MR. MC MULLEN: It might be helpful to add
10 that many of these faults which you are talking about
11 which come to the surface of the valley and ridge
12 province have been dated radiometrically, and at least
13 at the surface where the outcrop there doesn't seem to
14 be evidence of movement, at least since the late
15 paleozoic.

16 MR. POMEROY: In general, I am aware of that,
17 that there is no surface faulting observed anywhere in
18 this area, but of course we have examples of large
19 earthquakes with significant ground motion, without
20 significant breakage.

21 Does the staff have any information with
22 regard to another question I raised earlier, with regard
23 to the Norris Dam site, the design criteria for that?

24 MR. MC MULLEN: No, not directly. I
25 understand that those dams were looked at during the CP

1 review for Watts Bar. The hydrological engineering
2 group, I believe, did an evaluation for the staff, not
3 on the seismic integrity, but on what would happen if it
4 would fail.

5 MR. POMEROY: Again, could we ask the staff to
6 provide us some further information with regard to what
7 has been done, if there are -- if there is any
8 information on the seismic design? Could that be made
9 available to us?

10 MR. MARK: Is Norris Dam actually relevant?
11 It is on the Tennessee River not on the Clinch.

12 MR. KNIGHT: Just as a general answer, my
13 recollection is a little foggy. We may well, as we have
14 sometimes, simply assume that the dam failed and looked
15 at flood protection at the plant. I don't know if that
16 is the case. I will check, however. If the information
17 is available to use, we will see that it is made
18 available to the committee.

19 MR. MARK: Isn't the dam upstream of the site?

20 MR. GROSS: Yes, it is.

21 MR. MARK: There was reference to the
22 Charleston. Now, I don't think there has been much
23 change in the estimate of the intensity of the
24 Charleston earthquake, but there has been a new question
25 of whether it should not be cut loose from its moorings

1 and be allowed to wander around the province. That
2 still does not bring it within much closer distance of
3 the site than where it is now, does it?

4 MR. MC MULLEN: Well, one of the theories
5 about the cause of that earthquake 's that it was
6 related to the measure of the sole thrust which there is
7 no evidence that it goes under the Charleston area yet,
8 and these faults that outcrop in the valley and ridge
9 province are related to that master thrust, but that is
10 where the interest with regard to the Clinch River comes
11 in.

12 MR. MARK: So it is not just that it will
13 wander up and down the coast and plague New Jersey, but
14 it might also run inland?

15 MR. MC MULLEN: That's right.

16 MR. MARK: Wow.

17 (General laughter.)

18 MR. KNIGHT: This is Jim Knight again. In
19 some additional response to Dr. Pomeroy's question, I
20 have just been handed a page out of the site suitability
21 report. Just for your information, the design basis
22 flood for the proposed site has been determined by the
23 applicant to be caused by the assumed partial seismic
24 failure of the Norris Dam of 62 miles upstream from the
25 site coincident with the standard project flood with

1 attendant failure of the Milton Hill and Watts Bar
2 dams. So, as I say, as many times it is the case we
3 have assumed -- in this case, I am not sure what the
4 word "partial" means. We will have to explore that more
5 fully with the hydrologic folks.

6 MR. POMEROY: I guess that would be my
7 immediate question, because I have heard that before,
8 and I was concerned about the question of partial
9 failure. Oftentimes structures don't do exactly what
10 you want them to do, and I am curious as to how the
11 partial failure might occur and what happens if a full
12 failure should occur, because of the quirks of nature.

13 MR. KNIGHT: Yes. That is something we will
14 have to explore.

15 MR. LIPINKSI: Let me amplify on that. I
16 believe it was about 1977 or so, there was an ACRS
17 subcommittee meeting down at the site, and the
18 presentation was made on the failure of Norris Dam, and
19 the assumption at that time was that the central section
20 for the dam failed, and it simply toppled forward, so
21 that the face of the dam became the base and the base of
22 the dam became an interface, and then Lake Norris went
23 past the structure and ended up downstream, but it was a
24 large segment failure of the dam that just toppled
25 forward.

1 The gentleman making the presentation said he
2 thought he was being overly conservative in assuming
3 that type of a failure of the dam structure.

4 MR. CARBON: I would like to go back to the
5 Sequoyah question for a second. The return frequency, I
6 think you are saying there, as best your memory served
7 you, was 10^{-3} , 10^{-4} ?

8 MR. ROTHMAN: That is back in my memory. I
9 wasn't the reviewer for Sequoyah. I just happened to
10 look over some of the work that was done on it briefly,
11 but it seems to me if I remember seeing the Sequoyah
12 spectra plotted on a probabilistic curve with the
13 uniform hazard spectra, it fell somewhere between 10^{-3}
14 and 10^{-4} . That was the best of my memory.

15 MR. CARBON: Just offhand, could you venture
16 an estimate? Would it be about the same as you expected
17 in the CRBR site, or higher, or lower?

18 MR. ROTHMAN: The .25 G Reg. Guide, which is
19 the SSE for Clinch River, is higher than the Sequoyah
20 spectrum, so it would have a -- it would be a more
21 conservative or longer return period for Clinch River
22 than Sequoyah.

23 MR. CARBON: A longer period of time between
24 the recurrence?

25 MR. ROTHMAN: Yes.

1 MR. CARBON: Any other questions of the staff
2 people? I think it is appropriate for us to agree for
3 them to leave when we get our questions out of the way.

4 (No response.)

5 MR. CARBON: Well, I am sure we will have some
6 about five minutes from now, but I guess that does it.
7 We thank you.

8 I guess then we will return to Mr. Dajani.

9 MR. DAJANI: Okay. To continue in the
10 discussion of the method of analysis for the nuclear
11 island, seismic analysis, that is.

12 (Slide.)

13 MR. DAJANI: We did an independent analysis
14 for each of the three directional earthquakes. We had
15 four main sticks in the lumpe mass model. There is a
16 picture of it in your handout. We also presented major
17 equipment such as polar crane and the reactor vessel
18 model, and we have accounted for the flexible ties
19 between the confinement building and the adjacent
20 reactor service and steam generator building at all the
21 elevations. We did that. We came up with the
22 compliance matrix, if you will, through a separate
23 finite element analysis to determine what those
24 flexibility springs are, and we included them in the
25 lumpe mass analysis.

1 The mass points were located at the centers of
2 mass. The massless members were located at the center
3 of rigidity. We did two separate analyses. The first
4 analyses considered the upper bound rock properties. We
5 got the responses. We also did another analysis using
6 lower bound rock properties, and we got another set of
7 responses, and we then enveloped the two. We also
8 generated time histories at the various mass points, and
9 the spectrum, the design spectrum were then widened by
10 plus or minus 10 percent at the peaks, in accordance
11 with the applicable Regulatory Guide.

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1 I guess then we return to Mr. Dajani.

2 MR. DAJANI: To continue with the discussion
3 of the method of analysis for the nuclear island seismic
4 analysis, we did an independent analysis for each of the
5 three directional earthquakes. We had four sticks, main
6 sticks in the lumped mass model. I think there is a
7 picture of it in your handout.

8 We also represented major equipment such as
9 the polar crane and the reactor vessel in the model.
10 And we have accounted for the flexible ties between the
11 confinement building and the adjacent reactor service
12 and steam generator buildings at all the elevations.

13 We did that. We came up with a compliance
14 matrix, if you will, through a separate finite element
15 analysis to determine what those flexibility springs
16 are, and we included them in the lumped mass analysis.

17 The mass points were force located at the
18 centers of mass. The massless members were located at
19 the center of rigidity. We did two separate analyses.
20 The first analysis considered the upper bound drop
21 properties, and we got the responses.

22 We also did another analysis using lower bound
23 properties, and we got another set of responses. We
24 then enveloped the two. We also generated time
25 histories at the various mass points. The design

1 spectra were then widened by plus or minus 10 percent at
2 the peaks in accordance with the applicable regulatory
3 guides.

4 To account for the further moment arm for
5 components that are located away from the center of
6 mass, we have a procedure to account for the additional
7 translations that result from that eccentricity.

8 (Slide.)

9 MR. TRIFUNAC: Would you describe upper bound
10 and lower bound drop properties?

11 MR. DAJANI: Yes. Earlier you heard in the
12 presentation that we boiled down the various data to
13 characterize the site in terms of the modulae of
14 elasticity, and there was a recommendation that we use a
15 certain number of, for example, the siltstone 1.5
16 million p.s.i. and that we consider a plus or minus 25
17 percent variation on that. The 25 percent variation is
18 what I am talking about here for the upper bound and
19 lower bound.

20 In the evaluation of the nuclear island
21 structures we find that, first of all, the load
22 combinations are in accordance with the applicable code
23 for steel and for concrete. We find that, in general,
24 the structures are controlled not by the SSE but rather
25 by the OBE.

1 We also further find that many of the
2 structural elements of the various buildings are
3 controlled by conditions other than seismic. Last week
4 we talked about the thermal margin beyond the design
5 base. That in many areas controls the design of the
6 rebar. The amount of concrete shielding is another one
7 that controls the thickness of walls, not seismic, as
8 well as the sodium spills, what I call the design-basis
9 accidents in the various cells that contain radioactive
10 sodium.

11 MR. TRIFUNAC: A question. Was the OBE
12 selected as one-half of SSE on a conditional basis, or
13 was there some kind of probabilistic loss assessments
14 included to see that this is a good number to take?

15 MR. DAJANI: As was described earlier, it was
16 selected at one-half of SSE based on precedents, but I
17 think the statement was made that we believe that was on
18 the conservative side.

19 Walter, maybe you want to elaborate on that
20 point.

21 MR. BRUSEY: Probabilistic analyses were
22 conducted but were not submitted to the NRC. The
23 conclusion was reached that the designer reached the
24 stage at that time that really it was not feasible to
25 change and it was decided to proceed with a half SSE

1 value, which was, of course, .125 g.

2 MR. ZUDANS: Were you going to plan to show us
3 this model or not?

4 MR. DAJANI: I had it out of phase in my
5 vuegraphs since we left, so I did not show it.

6 MR. ZUDANS: Maybe that is the beginning of
7 it.

8 MR. DAJANI: This is just an example of the--
9 I have mentioned that there were four sticks and I
10 mentioned that the confinement is connected through
11 flexible ties to the reactor service building and the
12 steam generator building.

13 This shaded area represents that kind of tie
14 between the appropriate nodes at all elevations. Both
15 the polar crane and the reactor vessel were modeled.

16 MR. ZUDANS: Where is the polar crane on this
17 one?

18 MR. DAJANI: It is not shown on this section.
19 I think it is shown -- No, I am sorry, the polar
20 crane -- the polar crane, George Siegal, do we have the
21 polar crane on this one? I'm not sure which nodes are
22 represented, but I think the reactor vessel is this one
23 here (indicating).

24 MR. ZUDANS: That is a good substitute for the
25 polar crane.

1 MR. SIEGAL: The polar crane in one direction
2 was rigid in that particular model. In the other
3 direction, the polar crane was flexible and was
4 represented by a mass on the spring that was equivalent
5 to the first moment.

6 MR. ZUDANS: The way that you support the
7 interpolar crane, since you have a stick model, in the
8 other direction how did you model the polar crane in
9 terms of where the wheels sit on the rail? It is
10 supported at the ends? It spans the entire containment
11 building. How do you --

12 MR. SIEGAL: We have a simplified
13 representation of the polar crane. We have a complete
14 model of the polar crane, and we found that there was
15 one mode that was predominant, the first mode. So we
16 determined the generalized mass stiffness for that mode
17 and we represented the crane with one mass and one
18 spring attached to the node that represents the polar
19 crane support.

20 MR. ZUDANS: Okay. Actually, all you
21 considered in this model for the polar crane was its
22 mass.

23 MR. DAJANI: That is correct.

24 MR. SIEGAL: Stiffness, too.

25 MR. DAJANI: It was not intended for the

1 design of the polar crane; it was simply intended to
2 include the major equipment as it may affect the
3 response of the nuclear island. I believe the effect
4 was very small in either case.

5 MR. SIEGAL: In addition, there was an
6 analysis of the polar crane by itself.

7 MR. ZUDANS: I would believe that.

8 MR. SIEGAL: We determined those weir
9 reactions and those weir reactions were imposed in the
10 crane to find the stresses.

11 MR. ZUDANS: Now I would like to understand
12 this cross-hatched area. In terms of what you said, a
13 separate finite elemental model was made for those
14 buildings and there were appropriate stiffnesses
15 developed between different nodal points. Would then in
16 this model the cross-hatched area be an equivalent
17 super-element? Are there cross-couplings between all
18 the nodal points listed on the boundary?

19 MR. DAJANI: I am getting a nod that that is
20 yes.

21 MR. ZUDANS: So this is a fully developed
22 matrix between all those nodes connecting the
23 cross-hatched area?

24 MR. DAJANI: Right. That is why we didn't
25 show them exclusively, but we showed it shaded.

1 MR. ZUDANS: And that is the mat matter is
2 rigid; right?

3 MR. DAJANI: Right. And the foundation spring
4 is not shown.

5 MR. ZUDANS: 326-foot long mat, 15 foot thick;
6 right?

7 MR. DAJANI: Something like that. 15 foot,
8 yes. I am not sure about the other number.

9 MR. ZUDANS: That is about a ratio of length
10 to thickness of 20. Now are these stick models attached
11 to the mat at different proper locations where they
12 are?

13 MR. DAJANI: Correct.

14 MR. ZUDANS: Well, I guess I understand what
15 you did.

16 MR. TRIFUNAC: A question on the mat.

17 MR. DAJANI: Yes.

18 MR. TRIFUNAC: This was a two-dimensional
19 slice? Or a three-dimensional mat plate? Or what?

20 MR. DAJANI: For the lumped mass, George, how
21 did we eventually lump the mat in the model here?

22 MR. SIEGAL: It is three-dimensional. The
23 actual coordinates of the mass points and of the members
24 were taken into consideration.

25 MR. TRIFUNAC: Okay. And then at the points

1 indicated in the sketch about structural four stick
2 models were attached to the mat?

3 MR. SIEGAL: As Mr. Dajani said, the location
4 of those members that are supported from the mat
5 coincide with the center of the rigidity.

6 MR. TRIFUNAC: Then the stiffness matrix of
7 this entire package on this picture included what
8 degrees of freedom?

9 MR. SIEGAL: The stiffness matrix included the
10 cross-cut between the different nodes for 60 degrees of
11 freedom.

12 MR. TRIFUNAC: My question was for the mat and
13 for everything above.

14 MR. SIEGAL: Well, the mat is rigid. So on
15 the mat there was not such a problem.

16 MR. TRIFUNAC: I thought the mat was
17 flexible.

18 MR. DAJANI: No, the mat is rigid.

19 MR. TRIFUNAC: So that means, for example,
20 that in reality part of the foundation under stick-1
21 moves differently than the part of the foundation of the
22 stick-2. So this is not included in the analysis;
23 right?

24 MR. SIEGAL: We do not believe that will
25 happen, because first of all --

1 MR. TRIFUNAC: I am not suggesting it would
2 happen. I am asking, if it were to happen.

3 MR. SIEGAL: In the model it is assumed it is
4 rigid, so they move the same.

5 MR. ZUDANS: Now, hold on. I thought that you
6 had one spring constant attached, say, to node 59. Is
7 that a correct statement for soil?

8 MR. DAJANI: That was soil, but the question
9 was relative to the mat.

10 MR. ZUDANS: That means the mat rotates and
11 translates; and therefore, the points that are different
12 distances from node 59 moves differently. Was that the
13 assumption?

14 MR. SIEGAL: Well, they move differently, but
15 consistent with the assumption of a rigid plate for the
16 foundation.

17 MR. DAJANI: Well, that is all right. In
18 other words, the points of the --

19 MR. SIEGAL: Obviously if you have a torsion
20 they will not move exactly the same. But if you make
21 the assumption that the plate is rigid, then you would
22 have consistency.

23 MR. DAJANI: They move consistent with the
24 rigid foundations.

25 MR. ZUDANS: And the mass and moments of

1 inertia at the foundation were all lumped at point 59?

2 MR. DAJANI: For the mat?

3 MR. ZUDANS: For the mat, yes.

4 MR. SIEGAL: Yes. All that was lumped at
5 point node 59.

6 MR. TRIFUNAC: What is the horizontal extent
7 of the mat, the horizontal size?

8 MR. SIEGAL: The dimensions of the mat? I
9 think that is on one of the vuegraphs.

10 MR. DAJANI: 320 feet, I think. Dr. Zudans
11 just mentioned that.

12 MR. KASTENBERG: Before you leave that
13 vuegraph, how do you account for damping in the
14 structure?

15 MR. DAJANI: We have a damping matrix for each
16 of the elements.

17 George, maybe you can elaborate on that.

18 MR. SIEGAL: The damping of the structures are
19 in accordance with Reg Guide 1.61. That means for the
20 SSE in concrete it is 7 percent and for the OBF the
21 concrete is 4 percent. Now, on that basis, the
22 structural damping is considered.

23 MR. TRIFUNAC: These are the largest
24 allowables. 161 gives the largest allowable for
25 damping; it does not give the recommended highest for

1 the damping. You are to determine the best engineering
2 judgment what the best values are but not to exceed
3 those. Is that correct?

4 MR. SIEGAL: It says the SSE values are
5 associated with stresses or strains and yields and the
6 OBE values are associated with stresses and strains
7 about one-half of that.

8 MR. TRIFUNAC: Yes.

9 MR. DAJANI: These are the values that we
10 believe. Therefore, I believe what George is saying is
11 that they are the reasonable values to be used.

12 MR. TRIFUNAC: So you are using the largest
13 values allowed?

14 MR. SIEGAL: We are using the values that we
15 thought were appropriate for our problem.

16 MR. TRIFUNAC: If you allow me just one brief
17 question, coming back to the mat question, what is the
18 -- for the metal frequency of either of the four stick
19 models?

20 MR. DAJANI: I don't remember.

21 George, do you remember the fundamental
22 frequencies of the four stick models, or any of them?

23 MR. SIEGAL: The fundamental frequency, I
24 would say, is about 5 Hz.

25 MR. TRIFUNAC: In the range of 5 Hz.

1 MR. SIEGAL: In the range of 5 Hz.

2 MR. KASTENBERG: I just wanted to ask one more
3 question on this.

4 MR. DAJANI: Yes.

5 MR. KASTENBERG: Please excuse me, I am not a
6 structural engineer; I just want to learn something.

7 Basically, when you go to solve for the
8 motion, you are solving a typical matrix equation, like
9 an RLC circuit analog, presumably?

10 MR. DAJANI: It is not within -- we employ the
11 method of direct integration. We just directly
12 integrate the equations of motion, which include both
13 stiffness and damping.

14 MR. KASTENBERG: Stiffness and the damping and
15 the mass measures.

16 MR. DAJANI: Correct.

17 MR. ZUDANS: Your assumption was right.

18 MR. KASTENBERG: I see. And you do not use
19 some kind of an IGAN vector modal analysis to do this?

20 MR. DAJANI: No.

21 MR. ZUDANS: I think you just misstated your
22 answer.

23 MR. DAJANI: Tell me how I should have stated
24 it.

25 MR. ZUDANS: You have your model set up. You

1 ignore the damping, you compute natural frequencies in
2 what shapes, which is an analysis.

3 MR. DAJANI: Oh, I see. You are right.

4 MR. ZUDANS: Then you go back and combine your
5 IGAN values and get the approximate response.

6 MR. DAJANI: In the method of direct
7 integration there is a part where you look at the modes
8 and use the modes rather than as the primary way of
9 heading your responses. But the reason I said what I
10 said, Dr. Zudans, is because there is something else,
11 called, of course as you know, the modal analysis
12 technique, which uses --

13 MR. ZUDANS: Also uses the natural frequency
14 mod shapes because you have to the chart and pick up the
15 accelerations.

16 MR. DAJANI: True.

17 MR. ZUDANS: So I would like to ask one more
18 question on this node 59 that seems to be the item that
19 everything else hinges on. You had some damping values
20 for the soil, too. I did not get those.

21 MR. DAJANI: I mentioned earlier we did the
22 static finite element analysis, which established the
23 compliance values, the stiffness values. We then used
24 the relationships we derive from that the shear modulus
25 which then, an equivalent shear modulus, which then used

1 the half-space equations to derive the damping values.

2 MR. ZUDANS: I was just going to knock you
3 down on static analysis using damping values, but you
4 have got just the soil property from that analysis.

5 MR. DAJANI: That is correct.

6 MR. ZUDANS: Then you went back to half-space
7 and computed your damping values.

8 MR. DAJANI: Correct.

9 MR. ZUDANS: That would be correct. How did
10 you derive the damping values for each of the mode
11 shapes that you analyzed for, because your different
12 structures have different damping levels. Steel
13 structures have certain and concrete others and soils
14 other ones. Which would you use for mode shape in the
15 analysis?

16 MR. DAJANI: Do you know the answer to that?

17 MR. SIEGAL: To determine the damping matrix
18 for the structural feet space we used a weighted average
19 by the strain energy. That means for the different
20 fixed modes, thick-spaced modes, we determine an average
21 damping considering the different elements in the
22 structure. And that way we formulated the damping
23 matrix for the fixed-base structure. Then we combine
24 that with the damping coefficients for the soil
25 dampers. And in that way the complete damping matrix

1 was formulated.

2 MR. ZUDANS: How did you "combine"? How did
3 you do the last combination soil damping matrices with a
4 fixed-base structure?

5 MR. SIEGAL: We have a complete formulation of
6 the model. The placement of a node, in general, is a
7 summation of two displacements: one, of the structure
8 by itself, assuming the base is fixed; and plus those
9 displacements that come from the action of the soil in
10 the dampers.

11 So the whole formulation of the equation of
12 motion was based on that assumption. Based on that
13 assumption, you could formulate the complete mass
14 stiffness damping matrix for the structure with the soil
15 effects. And that was integrated directly.

16 MR. ZUDANS: Now you are telling me you did
17 two analyses: one was a foundation with everything
18 assumed to be rigid sitting on it, and that determined
19 certain rigid-body motion on the foundation; then you
20 did another analysis where you fixed the foundation
21 plate and computed the frequencies and watched for the
22 rest of the structure. Is that a correct statement?

23 MR. SIEGAL: I am saying we did one analysis,
24 but in formulating the model of the structure for the
25 structure itself we developed the fixed-base mode.

1 MR. ZUDANS: Okay.

2 MR. SIEGAL: And that way we could represent
3 the structure by the modes instead of in the degree of
4 freedom in the particular modes which is what is
5 normally used to save a lot of computational time.

6 MR. ZUDANS: That is okay. Yes.

7 MR. SIEGAL: In addition to that, we coupled
8 the effects that come from the rotation and translation
9 of the base.

10 MR. ZUDANS: But you had then another model
11 which consisted of rigid-body modes for the base plus
12 the more flexible structure relative to the base.

13 MR. SIEGAL: We developed the questions
14 accounting for this.

15 MR. ZUDANS: This is where you had to combine
16 this coming from soils and structures.

17 MR. SIEGAL: Yes.

18 MR. ZUDANS: Did you use something referred to
19 as "equivalent modal damping technique"?

20 MR. SIEGAL: Modal damping was only for the
21 fixed-base structure. For the other it would be the
22 damping coefficients as calculated by the half-space
23 theory.

24 MR. DAJANI: So we had one matrix that
25 included the damping coefficient for the structures as

1 well as the soil.

2 MR. SIEGAL: We have the equations available.
3 That is a method that was proposed for the first time to
4 discuss that formulation.

5 MR. ZUDANS: I am not trying to discredit what
6 you did. I am just trying to understand it.

7 MR. DAJANI: For the other nuclear Category 1
8 structures -- we have not completed this analysis, by
9 the way yet -- but for the emergency cooling tower we
10 intend to use the lumped-mass analysis and use the same
11 approach of providing for a range of rock and soil
12 properties. And since there is a basin within that
13 emergency cooling tower with water in it, we will
14 include the effect of the fluid within that basin using
15 Hausner's theory.

16 The diesel generator building is another
17 Category 1 structure. It is supported on soil. And we
18 will utilize FLUSH to determine the response of that
19 structure. And we will also use a range of soil
20 properties.

21 (Slide.)

22 I mentioned earlier that --

23 MR. TRIFUNAC: Can I ask a question? How is
24 the ground motion coming into FLUSH or the other model?

25 MR. DAJANI: Which other model?

1 MR. TRIFUNAC: I thought you were going to do
2 this calculation using FLUSH and also a lumped
3 three-dimensional analysis. Am I incorrect in that?

4 MR. DAJANI: Yes. To find the foundation
5 response, we will use FLUSH, and then after that we will
6 take that foundation input motion that we would
7 calculate from FLUSH and apply it to a
8 three-dimensional, detailed three-dimensional lumped
9 model, which is a standard way of doing it.

10 MR. TRIFUNAC: But then for FLUSH you are
11 going to get only the translational out of the surface
12 motions where surface is in the plane of the
13 two-dimensionality of the FLUSH. What are you going to
14 do about the other components of FLUSH? How do you get
15 torsion into the FLUSH?

16 MR. DAJANI: That will be included in -- how
17 do we get specifically the torsion from FLUSH?

18 MR. SIEGAL: FLUSH does not give torsion. We
19 determine rocking motion, and we get translation motion
20 for FLUSH. But torsional effects will be just
21 considered by representing the masses, the proper center
22 of mass, and the members of the model at the center of
23 the rigidity.

24 MR. TRIFUNAC: I suppose what you are
25 referring to is accidental-type percentage-type

1 eccentricities?

2 MR. SIEGAL: Not percentage. Actual.

3 MR. TRIFUNAC: 5 percent, 7 percent, so-called
4 accidental eccentricities. So you are going to ignore
5 torsion, essentially.

6 MR. SIEGAL: There will be torsional degree of
7 freedom, but there will be no torsional inputs.

8 MR. TRIFUNAC: Exactly. That is what I
9 meant. Thank you.

10 MR. ZUDANS: One more question. The
11 soils/structure interaction by FLUSH, is that a
12 time-history analysis or -- and what do you use? Do you
13 use the synthetic time histories?

14 MR. DAJANI: Correct. We go through the
15 deconvolution process, and then the convulsion.

16 MR. TRIFUNAC: This input comes from where?

17 MR. DAJANI: Which input?

18 MR. TRIFUNAC: The ground motion. Where does
19 it get into the FLUSH?

20 MR. DAJANI: In the FLUSH we are going to put
21 it at the -- for which question? For which building,
22 first of all?

23 MR. TRIFUNAC: For all of them. I thought
24 that this is rigid; so the question applies to all of
25 them.

1 MR. DAJANI: No, but I mentioned that FLUSH
2 will be used for the diesel generator building, which is
3 on soil properties. I am not sure, where do we start
4 our input motion, at the surface or at the top of the
5 rock, George? For that we have not done it, so I am not
6 really sure.

7 MR. SIEGAL: We are going to put the input
8 motion in this particular analysis at the foundation
9 layer. It is near the surface. There is no embedment.

10 MR. DAJANI: There is a requirement in the new
11 Standard Review PDA, NUREG-0800, which we intend to
12 follow for this analysis, that the input at the
13 foundation level envelope the design response spectra in
14 the reg guide. So that is what we will eventually have
15 to do.

16 MR. TRIFUNAC: I understand that. But FLUSH
17 needs to get input somewhere. Where is it going to be
18 put in if you are going to use it?

19 MR. DAJANI: I am not sure the criterion is to
20 put it at the position at the control point such that we
21 will envelope the design response spectra at the
22 foundation level of that building, which is not yet
23 designed.

24 MR. TRIFUNAC: Can you answer that question?

25 MR. SIEGAL: We are planning to put it at the

1 foundation level. That is, we are going to put the
2 input motion at the foundation level.

3 MR. TRIFUNAC: Does that mean that you are
4 going to take that motion back down to the bottom of the
5 box in which FLUSH is sitting and calculate the motion
6 there and send it back up?

7 MR. SIEGAL: Yes.

8 MR. DAJANI: And it has to be at the
9 foundation level such that it envelopes the design
10 response spectra.

11 MR. TRIFUNAC: That is a consequence of the
12 requirement. But I am trying to understand the physics
13 of the calculation. Are you going to consider the
14 motion coming from one side of the box of the FLUSH?
15 Are you going to consider the input motion coming from
16 one side of the box of the FLUSH?

17 MR. SIEGAL: No. FLUSH does not allow for
18 that. FLUSH considers vertically propagating motion, so
19 they are going to put the motion -- we will start with
20 the control motion at the foundation level. It will go
21 to the base of the model to the horizontal boundary, and
22 it will solve the problem with that motion. That means
23 that at the site we are going to have energy absorption
24 bounds at both sides of the model.

25 MR. TRIFUNAC: So you are going to consider

1 only vertically inputting seismic energy?

2 MR. SIEGAL: Yes.

3 MR. TRIFUNAC: Do you feel comfortable with
4 that in light of the layers we were talking about
5 earlier?

6 MR. SIEGAL: I think in this particular case,
7 where we have a rather deep layer of soil, it is very
8 adequate in this case.

9 MR. TRIFUNAC: Is it possible that the waves
10 coming from below would show up smaller on the surfaces
11 because of the layering? Is it impossible that this
12 inclined layering would scatter a lot of energy out of
13 the structure?

14 MR. SIEGAL: I would say there are a lot of
15 possible variables. It is a very complex topography,
16 and I do not think you will be able to model perfectly
17 regardless of the method of calculations that you use.
18 So I think we have to try to do a simplified analysis,
19 as simple as we can, but try to create a seismic
20 environment that would be consistent with the area that
21 we have. And we believe that using this method, we will
22 be able to achieve that.

23 MR. TRIFUNAC: I thought that there were some
24 other later generations of FLUSH. Some of them are
25 called LUSHs and PLUSHs.

1 MR. SIEGAL: I do not think that they have
2 been introduced or released yet.

3 MR. TRIFUNAC: They have been released for
4 years. Do either of these allow other types of input so
5 that you might get a better view of the effect of these
6 inclined layers?

7 MR. SIEGAL: I understand there is a new
8 version of that type of program that considers wave
9 propagation in direction, but I understand they have not
10 been officially released.

11 MR. DAJANI: For the seismic Category 3
12 structures adjoining Category 1 structure and whose
13 failure could challenge the integrity of the Category 1
14 structure, the turbine generator building and the rad
15 waste building, we also did a pretty detailed seismic
16 analysis on those two buildings for the SSE.

17 (Slide.)

18 In summary, I will go over the points of
19 conservatism that we have in the seismic analysis. The
20 first two were discussed earlier. The third bullet
21 relates to the fact that the design response spectrum
22 covers a wide band of frequencies, that the fourth
23 bullet relates to the time that the artificial
24 earthquake in general is higher than the design response
25 spectrum when you put it in the frequency domain.

1 The fifth bullet relates to the fact that the
2 seismic analysis considers linear properties and does
3 not take into consideration or account the nonlinear
4 properties of the structural elements. The fifth bullet
5 is that there are pretty conservative safety factors
6 required by the codes.

7 The sixth bullet relates to the fact that we
8 are using minimum material properties and as strength
9 properties. And we find that the actual yield strength
10 is actually higher. The second sub-bullet relates to
11 the fact that we use the strength properties of young
12 concrete, 28 days, and we do not take into consideration
13 the substantial increase of that strength with time.

14 (Slide.)

15 We also know the dynamic properties, the
16 response of the properties under dynamic conditions
17 yield higher strengths than the ones that we used, which
18 are based on static strength properties. We typically
19 have simplifications in the design itself, the
20 structural design itself, such that we would use similar
21 configurations, equal member sizes even though they are
22 not absolutely needed. Something smaller would be
23 sufficient, but we do that as part of the prudent
24 engineering and standardization of the design.

25 The next bullet talks about the fact that, in

1 general, the structural sections are controlled by the
2 OBE and not the SSE. And many other sections, as I
3 mentioned earlier, are controlled by things other than
4 seismic altogether. The difference is quite
5 significant.

6 The last bullet relates to the picture I
7 showed last week. In the containment, for example,
8 below 816 where the cells underneath the operating floor
9 are all interconnected, you have many redundant paths to
10 transmit the loads, and it is not conditional or
11 dependent on one particular load path.

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1 That is the end of the summary and the
2 presentation I have.

3 MR. ZUDANS: I thought this last statement,
4 that you already told us in the model that all these
5 structures were analyzed by a separate model, and the
6 conductivity of various degrees of freedom was included
7 in the basic structure. So that should not as a
8 consequence represent any other hidden conservatism.

9 MR. DAJANI: What I am referring to here, Dr.
10 Zudans, is, since you have many paths for the loads, if
11 one of those walls, for example, cracks or gives way, it
12 does not mean a catastrophic consequence. You have many
13 other load paths that will transmit that load.

14 MR. ZUDANS: That is, of course, correct. I
15 would like to return back to the cooling tower. You
16 said that you would model it as a stick. What kind of a
17 structure is it? Is it a cylindrical vessel?

18 MR. DAJANI: It is cylindrical. The
19 superstructure is, I think, rectangular, because the
20 fill has to fit, and the basin is the volume that has
21 the inventory water that is required.

22 MR. ZUDANS: And the superstructure is
23 rectangular?

24 MR. DAJANI: Yes.

25 MR. ZUDANS: The crane type structure?

1 MR. DAJANI: I really don't recall. I thought
2 the outside walls were concrete; inside it is framing, I
3 believe.

4 MR. SIEGEL: It is more of a shear wall type
5 of concrete structure.

6 MR. CARBON: Bill

7 MR. KASTENBERG: I just have a question. Do
8 you ever find that you have conflicting requirements in
9 your bullet? You say many structural elements are
10 controlled by other than seismic, such as the TMBDB or
11 the structural margin beyond the design basis. Do you
12 ever come into conflict where you have a problem
13 satisfying two different requirements, or does one
14 always subsume the other?

15 MR. DAJANI: It is more the latter than the
16 former. I cannot think offhand of something that says,
17 because of the thermal margin here is what you should
18 do; because of something else here is what you should
19 do, and that those two things are in conflict.
20 Typically, one envelopes the other, and you just have to
21 design for the response that is coming out from the more
22 severe environment, which in many of the cases, as I
23 mentioned here, is not coming from an earthquake from a
24 seismic event. We are talking about a substantial
25 amount of difference between the two. .

1 MR. KASTENBERG: What is the thing that is
2 always controlling in some of these other areas, such as
3 in the thermal margin, that would subsume the earthquake
4 as the seismic consideration?

5 MR. DAJANI: The thermal moments that are
6 generated that affect the cavity wall, for example,
7 determine how much rebar you are going to have in there,
8 and not the seismic.

9 MR. KASTENBERG: And questions relating to
10 your ability to take up thermal capacity due to
11 expansion is never in conflict, say, with trying to make
12 a system more stiff or thicker to meet a seismic
13 requirement?

14 MR. DAJANI: I think the way I will answer
15 that is to say that we have to factor in any
16 requirements for thermal expansion within the range or
17 within the domain, the regime of me trying to design the
18 structure to satisfy several conditions. In that sense,
19 yes, there will be requirements that are perhaps
20 apparently in conflict or one thing requires expansion,
21 the other thing requires rigidity.

22 A perfect example of that is, of course, the
23 seismic snubbers, but I would not consider those as
24 being fundamentally any different than any other
25 situation we have on any other design. In this case, if

1 you are asking me, does one set of accidents result in
2 configurations that are required that are in direct
3 conflict, that degrade the effectiveness of that
4 structure for another load combination, the answer is no.

5 MR. ZUDANS: I think it is probably too strong
6 an answer, because I think I could think of a couple of
7 ways you have a definitive conflict. Let's take the
8 containment shell coming into concrete at a certain
9 level. It sits on the concrete there. Whatever the
10 upper part of the shell wants to do the concrete stops
11 it from doing. Suppose you heat up the upper shell.
12 You have a definite conflict. You go deeper where the
13 shell is embedded in the concrete. Then you heat up the
14 compartments and you start pushing the cell out or
15 preventing it from expansion. That is another
16 conflict. There are many places where you do have a
17 compromise solution.

18 MR. DAJANI: I thought I answered that in
19 terms of this is the normal stuff, is there anything in
20 this particular situation that is coming uniquely out of
21 TMBDB? That is what I was trying to address. The
22 answer is no.

23 MR. ZUDANS: I would like for you to qualify
24 also that in general structures are controlled by OBE.
25 It is not the OBE by itself, but it is the way you have

1 to combine it with the other loads.

2 MR. DAJANI: And the allowable.

3 MR. ZUDANS: That is right. So it really
4 creates a misconception that OBE is more dangerous than
5 the SSE. That is not the case. It is a code
6 requirement as to how to combine that result and the
7 allowables associated with it.

8 MR. DAJANI: Let me clarify what I meant. If
9 you designed a structure, you find that the rebar or the
10 amount of concrete you must have is controlled by the
11 OBE requirements, because it has lower allowables and it
12 is combined with other conditions. If you took that
13 structure and challenged it with the SSE, you would find
14 that it has a substantial amount of margin because that
15 design was controlled by the OBE.

16 MR. ZUDANS: Because the SSE allows you to go
17 higher with stress levels.

18 MR. DAJANI: Yes.

19 MR. ZUDANS: That is why a higher stress
20 level, of why the OBE controls, and that is not
21 unusual. That is pretty much just a standard type of
22 view.

23 MR. DAJANI: Right.

24 MR. POMEROY: I had one further question.
25 Perhaps I misunderstood your last two slides, but I have

1 always had this question, I think. We have often been
2 told that the earthquakes do not need to have additional
3 conservatism built into them because of the additional
4 conservatisms that are built into the structural
5 analysis and structural elements. Not here, other
6 places. Would I interpret your last two slides to tell
7 me that in fact you believe that the analyses that you
8 have done would allow the structure -- or that the
9 resultant structure would actually withstand a greater
10 acceleration spectrum than the one that the design
11 spectrum is made up of?

12 MR. DAJANI: Yes.

13 MR. POMEROY: By what kind of a factor?

14 MR. DAJANI: It is very hard to tell or to
15 generalize, because as you know, some of these apply in
16 certain areas, others apply in different areas, but I
17 would say it is by a substantial factor. If you look at
18 -- one of the elements I mentioned before is, the design
19 basis accident controls the rebar in many areas, and
20 there is a significant difference between the density of
21 that rebar and the density of rebar found in other areas
22 where you don't have that condition.

23 MR. POMEROY: Could you give me an order of
24 magnitude perhaps?

25 MR. DAJANI: Only if you will not quote me on

1 it.

2 (General laughter.)

3 MR. ZUDANS: You could answer the question
4 differently in a critical combination where the SSE was
5 the most significant contributor. What fraction of the
6 total allowable did it take?

7 MR. DAJANI: I think I would rather answer it
8 the first way.

9 MR. POMEROY: I think I would like to hear the
10 answer to the second one.

11 MR. DAJANI: I don't really know.

12 MR. ZUDANS: Maybe Mr. Siegel knows, or he
13 should know.

14 MR. SIEGEL: I would say that probably the
15 structures will stay standing at least for twice the
16 value we use for the SSE of .15.

17 MR. ZUDANS: Because of the fact that they
18 take just a little fraction of the total available
19 stress?

20 MR. SIEGEL: No, because once you consider
21 that they will be cracking and you have some inelastic
22 action, then you see the structure can take a much
23 higher value than you normally assign when you do your
24 analysis, because you have to have the number of
25 redundancies.

1 MR. DAJANI: George, let's not digress. I
2 just want to try and answer the question to the best of
3 my ability.

4 MR. CARBON: We weren't digressing, Mr.
5 Dajani. Go ahead, Mr. Siegel.

6 MR. ZUDANS: I would like to ask a further
7 question. You are giving the right answer. That's the
8 way it is. You do have the margin at that point, but do
9 you offhand remember the worst case where an SSE's
10 contribution was identified quantitatively compared with
11 other loads if you applied the same thing?

12 MR. SIEGEL: I would say that perhaps the
13 containment vessel would be one case.

14 MR. ZUDANS: The buckling mode was a key
15 contributor?

16 MR. SIEGEL: Yes. Even so, I think the OBE
17 was the controlling mode, but that margin was less for
18 the SSE, if I remember.

19 MR. ZUDANS: When you calculate the free
20 standing shell buckling mode, what other loads induced
21 the compression that you had to live with? Was it
22 seismic alone?

23 MR. SIEGEL: It was seismic plus the dead load
24 and the external pressure.

25 MR. ZUDANS: That is three. .

1 MR. SIEGEL: Point five psi.

2 MR. ZUDANS: Then I guess in this condition
3 seismic probably dominated, right?

4 MR. SIEGEL: Yes.

5 MR. ZUDANS: So if you look at that
6 containment --

7 MR. SIEGEL: I think the containment pressure
8 is a significant factor, considering the buckling
9 strengths of the shell. Perhaps it is not as
10 significant as the SSE, but it is not negligible. I
11 think it is an important parameter.

12 MR. ZUDANS: So at any rate an SSE produced
13 compressive stress because of the bending mode.

14 MR. SIEGEL: And also due to the actual load.

15 MR. ZUDANS: That was significantly higher for
16 any other load than this failure mode.

17 MR. SIEGEL: Yes, except for the external
18 pressure.

19 MR. ZUDANS: But that also means that your
20 margin is based on inelastic behavior code by concrete
21 cracking disappeared in this failure mode, and therefore
22 you would be in a worse position in terms of allowing
23 higher SSE accelerations, right?

24 MR. SIEGEL: Well, but then we can go into the
25 conservatisms that are involved in the design analysis

1 of the containment vessel.

2 MR. ZUDANS: But that is a different
3 conservatism. I think the key conservatism in the SSE
4 is that in most locations it is not a dominating load,
5 but you can single out few structures and few failure
6 modes which are really dominated by SSE, such as this
7 containment buckling mode, and that kind of
8 determinants, how far you can go, because it doesn't
9 matter how much you can have elsewhere. It matters how
10 much you can have in the weakest link, so to speak.

11 MR. SIEGEL: But even under the SSE we have
12 conservatisms in the containment vessel. That means we
13 can have an SSE, and even when we meet the allowable
14 limits under SSE, I would say we still have plenty of
15 conservatism in the containment vessel.

16 MR. ZUDANS: Are we going to hear more
17 specific detail from Bob maybe on how the containment
18 was analyzed, or from somebody else? Have you planned a
19 discussion of this particular buckling mode of the
20 containment today?

21 MR. DAJANI: Not in my presentation.

22 MR. GROSS: No, we don't plan on covering
23 that.

24 MR. ZUDANS: I think the containment shell in
25 my opinion is what I would like to hear about. How did

1 you handle the buckling? What are your allowables
2 there? What design criteria did you use? And what are
3 your so-called design values? Not necessarily going
4 into how much conservatism you have. What safety
5 factors do you use? How do you do the calculation?
6 This is what I would like to hear if it is possible at
7 all.

8 MR. GROSS: We covered the containment design
9 last week.

10 MR. ZUDANS: We said we would discuss the
11 details today, because it was seismic. We didn't really
12 discuss the calculations of the containment
13 free-standing steel shell. I don't know who on your
14 team analyzed it.

15 MR. DAJANI: That's correct. We did not
16 discuss the structural analysis of the containment
17 vessel.

18 MR. LONGENECKER: We will attempt to treat
19 that on June 24th.

20 MR. ZUDANS: Who did that analysis? Did Burns
21 and Roe do it?

22 MR. DAJANI: Chicago Bridge and Iron.

23 MR. ZUDANS: I would like to hear that,
24 because I think this is a weak link in terms of the SSE.

25 MR. CARBON: Let's do, Mr. Longenecker.

1 Harold?

2 MR. ETHERINGTON: I have often heard that
3 argument that there is conservatism because the strength
4 of the material exceeds the specification. I think that
5 advantage is far more than offset by the defects we
6 expect to find in a gross product which you do not have
7 in the test specimen. I think that is a spurious
8 argument, although it is a very common one.

9 MR. CARBON: Yes?

10 MR. TRIFUNAC: I have a question that deals
11 with this dilemma of exceeding SSE. I thought we just
12 heard that not speaking about general modes of failure,
13 but in general that we might be able qualitatively to
14 support forces perhaps a factor of two larger than SSE.
15 Was that what you were saying essentially, not in detail?

16 MR. SIEGEL: Well, rather than force this, I
17 would say if you do an analysis for a .5 G and consider
18 those effects that are not included in our analysis,
19 non-linearities, things like that, I think you would
20 prove that the structures will not collapse, they will
21 keep the structural integrity at that level.

22 MR. TRIFUNAC: Yes. Now, in light of that, I
23 think we were talking a little earlier about damping.
24 How do we then justify using the largest allowables,
25 just for the sake of discussion now, 25 percent G,

1 rather than maybe considering 7 percent damping for 50
2 percent G, and perhaps 5 percent G for 25 G?

3 MR. SIEGEL: If we had 25 G, we would go much
4 higher than 7 percent and 4 percent damping, because you
5 would be well into the plastic trends. You would have
6 substantial cracking of the concrete and I think the
7 losses of energy under those conditions would be much
8 higher, so I would say 7 percent damping would be quite
9 low.

10 MR. TRIFUNAC: Well, would you expect that the
11 damping is a -- how can I ask this? -- a linearly or
12 monotonically linearly light increasing of the
13 non-linear response, or would you expect it to be
14 changing slowly while you are in the linear range and
15 then going up around the non-linear range?

16 MR. SIEGEL: Yes. I think once you get into
17 the non-linear range, you will have a sharp increase.

18 MR. TRIFUNAC: Now, if you take this list from
19 the summary of conservatisms here, a lot of things are
20 stronger than they are calculated for. Would that not
21 suggest the possibility that we will never reach the
22 strains that would support our selection of damping,
23 like 7 percent? If everything were right, we would
24 perhaps reach 7 percent, but because everything is so
25 much better, we say, are we not having too much damping

1 in the system?

2 MR. SIEGEL: I think the numbers you have in
3 the Regulatory Guide for damping are quite
4 conservative. At that level, you probably can expect
5 more than 7 percent even in the linear analysis.

6 MR. TRIFUNAC: What is the basis of that
7 statement? Is this a hypothesis, or is this
8 experimental, or a factual observation?

9 MR. SIEGEL: Well, I don't have any data
10 readily available, but in general I understand the
11 values specified by the NRC are conservative values.

12 MR. TRIFUNAC: So you are actually working on
13 the confidence that their numbers are good? You don't
14 want to explore that a little bit further, the
15 engineering practice of whether those numbers are too
16 large?

17 MR. DICKSON: Excuse me, Dr. Trifunac. We are
18 going to get into that, the damping values on some of
19 the components, during Mr. Moroni's classification of
20 criteria a little later.

21 MR. TRIFUNAC: That is fine. Thank you.

22 MR. CARBON: Are there any other questions of
23 either of the gentlemen?

24 (No response.)

25 MR. CARBON: I guess the agenda calls for our

1 break at noon, and we might as well take it at this
2 time, in deference to Dr. Mark. We will come back at
3 1:00 o'clock.

4 (General laughter.)

5 (Whereupon, at 12:00 noon, the meeting was
6 recessed, to reconvene at 1:00 p.m. of the same day.)

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1 AFTERNOON SESSION

2 (1:00 p.m.)

3 MR. CARBON: Mr. Dickson, are you all set?

4 MR. DICKSON: Yes. Tony?

5 MR. MORRONE: Good afternoon. My name is Tony
6 Morrone, from the Westinghouse Advanced Reactor
7 Division, and I will be discussing the seismic design
8 criteria for systems and components.

9 (Slide.)

10 MR. MORRONE: This consists of the seismic
11 classification and qualification, the seismic input
12 development from the building to the system, and from
13 the system to components, damping valves, basic load
14 combinations, and seismic test requirements and
15 procedures.

16 (Slide.)

17 MR. MORRONE: For seismic classification --

18 MR. CARBON: Mr. Morrone, could you step back,
19 please, so we can see?

20 MR. MORRONE: For seismic classification, we
21 classify the systems and components in accordance with
22 the importance of their function. These are seismic
23 category 1, seismic category 2, and seismic category 3.

24 Seismic category 1 system and components are
25 designed for both the SSE and OBE and consists of those

1 safety related systems and components necessary to
2 ensure the integrity of the reactor coolant pressure
3 boundary, provide capability for reactor shutdown, and
4 provide capability to prevent or mitigate consequences
5 of accidents.

6 Seismic category 2 systems and components are
7 designed only for the OBE, and they are required to
8 permit continued reactor operation and to protect plant
9 investment. Actually, this is an optional
10 classification, and these components may be put with the
11 seismic category 1 safety related components or in the
12 seismic category 3.

13 The seismic category 3 components are designed
14 to meet local design criteria, standard building codes,
15 and they are required to maintain support of normal
16 operations. Actually, the seismic category 2 and 3
17 components are comparable to the non-seismic category
18 use in LWR plants.

19 Additionally, these components must be
20 designed for no gross structural failure under SSE loads
21 to protect the seismic category 1 components.

22 MR. ZUDANS: Are you sure that that applies in
23 all the cases, or in some cases that you may just
24 separate them from the others?

25 MR. MORRONE: When applicable.

1 MR. ZUDANS: So if you design them to a
2 standard, you will be category 1 then.

3 MR. MORRONE: Not category 1, but with the
4 loads for category 1, not to the criteria category 1.

5 (Slide.)

6 MR. MORRONE: Okay. The seismic qualification,
7 is performed by either or both analyses and testing.
8 For seismic category 1 and 2 components, a detailed
9 dynamic analysis is required. This consists of either
10 response spectrum method or the time history method of
11 analysis, and also with conservative simplified
12 methods. This would include designing for a constant
13 acceleration of one and a half times the peak on this
14 response spectrum, which is quite conservative. For
15 seismic category 3, it is only a static analysis,
16 although in many cases they are also designed with
17 response spectra.

18 For qualification by testing, we have multiple
19 frequency tests, single frequency tests at resonance.
20 We can use either one or both, and I will discuss later
21 how we qualify our components for testing, and the basic
22 criteria is that the test response spectrum must
23 envelope the required response spectrum. Now, the test
24 response spectrum is the spectrum of the shake table
25 motion that is input to the item during testing and the

1 required response spectrum is the spectrum of the motion
2 calculated at the mounting of the equipment.

3 (Slide.)

4 MR. MORRONE: I would like to -- I don't know
5 which way to stand here, but I would like to discuss the
6 seismic input that is used for the design of our
7 components. This is obtained from the building analysis
8 which gives responses at nodes located at the center
9 mass of the applicable floor. This figure shows a
10 typical plan view of the nuclear island buildings. Of
11 course, these nodes are not at the same elevation. The
12 responses are obtained from the building analysis in
13 three independent directions.

14 Now, each node in the building model has three
15 degrees of freedom in the horizontal direction, that is,
16 translation, torsion, and rotation, and in the vertical
17 direction each node has one degree of freedom,
18 translation. Therefore, we obtain seven responses,
19 spectra, and time histories for each node, three
20 translation, two torsion, and two rotation.

21 Now, when we consider the OBE and the SSE and
22 the upper and lower bounds of soil moduli, we will end
23 up with 28 responses. Now, in accordance with combining
24 the directional effects by the square root of the sum of
25 the square, we must apply for a response spectrum

1 analysis these spectra individually in each of the three
2 directions, apply two spectra in each of the two
3 horizontal, and three spectra in the vertical direction,
4 and basically they consist of direct and cross spectra,
5 so we can keep track of which earthquake causes which
6 effect, and then we can combine the effects by the
7 square root of the sum of the square.

8 MR. ZUDANS: Could I ask a couple of questions
9 at this point? I assume then that your models for each
10 of the directions in the horizontal direction are
11 two-dimensional or are they three-dimensional?

12 MR. MORRONE: They can be either two or three.
13 For example, our reactor system model is
14 three-dimensional, but we perform three separate
15 analyses.

16 MR. ZUDANS: And you perform these three
17 analyses on the same model?

18 MR. MORRONE: They are different models. In
19 the horizontal direction they are basically the same
20 model. The vertical model would be different.

21 MR. ZUDANS: So you don't really have a
22 three-dimensional model, even -- if you had a
23 three-dimensional stick model for this system sitting on
24 the map, you can analyze it for a three-dimensional
25 earthquake, but it would remain the same, and you would

1 have in that case still six degrees of freedom per node
2 in principle, but what you are telling me now is that in
3 each of these planar analyses, in essence, you only have
4 two translations, not upper plane, and you also have
5 rocking and the other rotation.

6 MR. MORRONE: That is the building model that
7 has these freedoms. Our system model has six degrees of
8 freedom. They are basically the same models, except
9 some little variation where we model an important
10 element, a response more in a vertical direction than in
11 a horizontal direction. This is the only basic
12 difference between, in this case, for the reactor system
13 model.

14 You see, I was going to show you this model
15 later on, and I will tell you that in that case, we
16 would have to input eleven time histories. We have
17 these seven spectra, plus then we have pure rotation and
18 translation, so we have eleven histories input.

19 MR. TRIFUNAC: Excuse me. But you are
20 essentially ignoring the coupling, right? You are
21 assuming there is no coupling?

22 MR. MORRONE: Coupling between what?

23 MR. TRIFUNAC: Say, two horizontal components
24 of excitation. You are assuming that coupling is not
25 there.

1 MR. MORRONE: Yes, but this will be taken care
2 of by the square root of the sum of the square.

3 MR. TRIFUNAC: Not entirely, because the
4 coupling would equal the differential equation.

5 MR. MORRONE: Perhaps, but this is the
6 standard methodology to input one earthquake at a time.

7 MR. TRIFUNAC: Yes.

8 MR. MORRONE: We can also do it the other
9 way. Our criteria stipulates you can do either, and
10 this is also in accordance with Standard Review Plan and
11 Regulatory Guides.

12 MR. ZUDANS: That is why I asked you if you
13 used the same model. If you use the same model, you are
14 doing linear analysis, so you can take individual loads
15 seismic in one direction, analyze the results, take the
16 other individual load seismic in the other direction,
17 and then end up with the results either way you want,
18 whether SSR or some other method. But you told me that
19 the models are not quite identical, so I am just
20 wondering how you can combine models that are not
21 identical if they don't represent the same constant
22 system necessarily and they do not represent the same
23 structure.

24 So, I guess we will have to see your models to
25 have a better understanding.

1 MR. MORRONE: As I mentioned before, the
2 difference is very small. For example, in the vertical
3 model, the sodium mass is treated a bit differently than
4 in the horizontal model, but we still have the same
5 elements, so that we can combine the effects on a
6 particular element.

7 MR. ZUDANS: Supposing you modeled sodium in
8 one case with the capability to perform slashing motion,
9 and in the other case you ignored that, and as the
10 vertical motion you took it as the mass and simply
11 anchored it at that nodal point. I don't know. Did you
12 model sodium with a slashing degree of freedom in this
13 system or not?

14 MR. MORRONE: We have fluid coupling elements.

15 MR. ZUDANS: Of some kind.

16 MR. MORRONE: In the model, yes. The elements
17 are given in the answers to the computer program.

18 MR. ZUDANS: But you did not model sodium as a
19 finite element, not in this model.

20 MR. MORRONE: Not with finite elements, no.

21 MR. ZUDANS: Perhaps we will get a clearer
22 picture as time goes on.

23 (Slide.)

24 MR. MORRONE: Since it is difficult to have to
25 perform seven spectra analyses, we give the analyst an

1 option to use a more practical, simplified, and
2 conservative method whereby the seven spectra are
3 reduced to three spectra. Now, this is done by
4 initially combining the spectra by the square root of
5 the sum of the square. We combine the two horizontal by
6 the square root of the sum of the square to give us a
7 combined translational and torsional. When we do this,
8 of course, we have to combine the resulting responses by
9 the absolute sum, since we have used up the square root
10 of the sum of the square.

11 This method has been proved mathematically to
12 be always conservative, and the conservative sum, of
13 course, depends on the effect of the cross coupling
14 concerns. If they are very small, the conservatism
15 would be that which is obtained if we were to add the
16 directional effects absolutely instead of the square
17 root of the sum of the square.

18 MR. TRIFUNAC: Could you explain this,
19 please? Could you explain the second and the third
20 steps? You have seven spectra. You combine what?

21 MR. MORRONE: Perhaps I can show you on
22 another vu-graph here. I know it is sometimes difficult
23 using words.

24 (Slide.)

25 MR. MORRONE: Okay. First of all, here we

1 have the translation. This --

2 MR. CARBON: The superscript represents the
3 direction of the earthquake, the subscript represents
4 the direction of the spectrum input as you see here.
5 This is a node, the center of mass. This is the
6 location of our equipment (indicating). In the next
7 direction we have input the translational component plus
8 the torsion times the distance Y. Then we also input
9 the torsional component given by the Y earthquake, okay,
10 and we go through this.

11 Now, as far as the combination.

12 (Slide.)

13 MR. MORRONE: Here we go. We take this here,
14 which is given by the X earthquake, as you have seen
15 before (indicating), added directly, because they are
16 both given by the same earthquake, and then add to that
17 the horizontal component given by the torsion. Now,
18 since this is given by the Y earthquake, then we add
19 them by the square root of the sum of the square.
20 Similarly for the Y and the Z. So --

21 MR. TRIFUNAC: What then do you operate on
22 with the absolute sum? That is what I do not
23 understand.

24 MR. MORRONE: When we apply these spectra to a
25 component, you see, now, these are pseudo-earthquakes,

1 okay, so we apply the X earthquake and get responses,
2 accelerations, displacements, whatever. We do each, X,
3 Y, and Z, and then we add them absolutely. Rather, now
4 by the square root of the sum of the square again.

5 MR. TRIFUNAC: A , , is now your
6 X Y Z
7 condensed representation of the X, Y, and Z components
8 of spectral acceleration at the point where you want to
9 analyze something.

10 MR. MORRONE: Yes.

11 MR. TRIFUNAC: And then you analyze that
12 something for the absolute sum of these? Is that what
13 you are saying?

14 MR. MORRONE: We analyze the something with
15 the spectrum input. Let's say we do an analysis in the
16 east-west direction of the component. We input this
17 response spectrum. Then we do an analysis north-south
18 input, vertical, we input this. Now, the response
19 accelerations or whatever that we get from each of these
20 three spectra at a particular node are combined
21 absolutely. You see, this is a conservative method, but
22 it results in three analyses rather than seven.

23 MR. TRIFUNAC: I understand. Thank you.

24 MR. ZUDANS: I would like to ask a little bit
25 more. Now I see. What happened to the rotation of
inputs at that particular point where this is

1 connected? You just lift them out completely?

2 MR. MORRONE: The rotation goes into the
3 vertical.

4 MR. ZUDANS: What you have generated here are
5 the linear accelerations on that point. It is at that
6 point they were connected by a rigid link to your node.
7 The translations are computed correctly this way, but
8 the node or the connecting point also sees the
9 rotations. They transfer in space without any
10 transformation, so you would have to have another three
11 spectra for three rotations identical to the rotations
12 at that particular node, and those seem to be ignored.

13 Now if you have a flexible joint connection,
14 that would be all right. In other words, this accounts
15 for motion, but it doesn't account for point rotation of
16 the attachment and that could be significant.

17 MR. MORRONE: You can't input a rotational
18 spectrum.

19 MR. ZUDANS: Why not?

20 MR. TRIFUNAC: You have it right there.

21 MR. ZUDANS: You are using it here to generate
22 that translation. The rotation moves directly to that
23 point. The rotational vector is unchanged. You can
24 move it in space. So at that point you have thetas of
25 X, thetas of Y, and thetas of Z computed, which you

1 didn't. Those rotations are ignored.

2 MR. MORRONE: They are put in here by
3 multiplying by the moment arm.

4 MR. ZUDANS: That's correct, but that
5 generates only linear motion. I have a rotation here in
6 a translation (drawing on the chalkboard). This
7 rotation creates additional translation in here.

8 MR. CARBON: Better use white chalk.

9 MR. ETHERINGTON: Is that green chalk he is
10 using?

11 (Laughter.)

12 MR. ZUDANS: I have a rotation here and a
13 translation. This translation, see, moves this point
14 like that, and the rotation brings it back a little
15 bit. You accounted for this. That is your A, but
16 you forgot the fact that this is identical to that
17 rotation at that point. So that point of conductivity
18 sees the same rotation, and that vector moves in space.
19 It is unchanged. If you go back to your cartoon that
20 you had before.

21 MR. MORRONE: I don't see how you can put a
22 pure rotational spectrum input unless --

23 MR. ZUDANS: It is a boundary condition, if
24 you analyze it after that.

25 MR. MORRONE: It is a time history. Let me

1 show you. Perhaps this might explain.

2 MR. DICKSON: Mr. Morrone, did you not state
3 at the outset that it has been proven mathematically
4 that the resultants of doing it this way are greater,
5 always conservative accelerations and always
6 conservative displacements?

7 MR. MORRONE: Yes.

8 MR. DICKSON: If so, I don't think we want to
9 go through that derivation today.

10 MR. ZUDANS: We do not have to go through the
11 derivation. You cannot prove it mathematically, because
12 you are missing components of motion. It depends upon
13 what you hang on that point. If your equipment is
14 flexible, you don't care. If you have something large
15 and rigid, that rotation might be the critical one.
16 Your displacements may be very small. You just ignore
17 certain components of relative motion.

18 MR. DICKSON: Could you refer us to the paper
19 in which that is proven?

20 MR. MORRONE: Certainly.

21 MR. CARBON: I think we will go ahead with the
22 questions that Dr. Zudans is raising. We would like to
23 understand the physical aspects of this.

24 MR. DICKSON: I think they are valuable
25 questions, and we need to provide him with the

1 information he needs. I just thought it was a direction
2 where Tony was not going to be able to explain it and
3 derive it this afternoon. It was far too deep.

4 MR. CARBON: It is not a matter of derivation
5 at the moment, however.

6 MR. MORRONE: The paper, for the record, is
7 Combination of Torsional, Rotational, and Translational
8 Responses in The Seismic Analysis of A Nuclear Power
9 Plant. This is by me and Mr. Siegel.

10 MR. ZUDANS: If you, being one author, and the
11 other author, being here, cannot explain it successfully
12 to me now, then it just --

13 MR. MORRONE: Sir, there is no torsional
14 spectrum as such. Now, for time histories, I think this
15 is what you are talking about, isn't it, the pure
16 torsion and rotation? You see, for the time history
17 analysis, then we do input the three equivalent
18 translations plus now a pure torsion and a pure rotation.

19 MR. ZUDANS: Supposing my rigid arm to that
20 point was zero lens and I had equipment that touched
21 right to that node. Would you ignore rotations of that
22 node to calculate equipment stresses?

23 MR. MORRONE: Then if I were concerned about
24 that, then I would ask for different spectra from the
25 building analyst, but because the way they are

1 designed --

2 MR. ZUDANS: Wait. You have the translations
3 or a rotation in the translation. You use them in the
4 model. I am trying to make sure that you understand
5 what I am asking.

6 MR. MORRONE: The torsional and rotational
7 spectra are G's per foot of length. Now, if I have zero
8 I cannot use those spectra.

9 MR. ZUDANS: The thetas are the angles of
10 acceleration at that point.

11 MR. MORRONE: Yes.

12 MR. ZUDANS: They are angles of
13 accelerations. And As are linear accelerations. You
14 now connect something by a rigid link to that point
15 where you have thetas and As computed. If you multiply
16 what are the lens of rigid link the thetas which are
17 angles of accelerations, you get linear accelerations at
18 that point.

19 The problem is that that point still sees the
20 same rotations, the same angle of rotations. Physically
21 if I have a node here, a node like this, and I have a
22 spectra for this point which consists of angle of
23 accelerations and linear accelerations, that point will
24 see that rotation. That is a moment input rather than a
25 force input at that point. It is a bending moment input

1 that will result from it, and it is not necessarily --
2 it may not be significant in these structures, but you
3 cannot a priori ignore it and tell me that this is
4 always conservative.

5 MR. MORRONE: I can. I can, because, first of
6 all, the effect of rotation and torsion is extremely
7 small.

8 MR. ZUDANS: That is different.

9 MR. MORRONE: Very small. One percent, one
10 and a half percent, based on that.

11 MR. ZUDANS: That is a different argument. I
12 am not going to contest that argument until I see the
13 numbers, but the other one is not.

14 MR. MORRONE: Number Two, the way the building
15 analysis is performed, we cannot input the pure
16 rotational spectrum, because they are given in per foot
17 of length, but for the time history analysis we do
18 consider it.

19 MR. TRIFUNAC: Excuse me just a minute. How
20 do you mean, you cannot when they are right there? You
21 have included them already. The question that Mr.
22 Zudans is asking you is simply what do you do about the
23 dynamic equilibrium equation for a rigid body which has
24 the forces equal to a mass times linear acceleration,
25 but which also has the moment is equal to the mass

1 moment of the inertia times angular acceleration. That
2 is what he is asking you.

3 MR. ZUDANS: That is exactly correct.

4 MR. MORRONE: Did you understand or did I
5 explain what these spectra looked like, the ordinates?
6 They are in G's per foot, okay? These are the spectra
7 that are produced from the building analysis.

8 MR. ZUDANS: That is a correct dimension.

9 MR. MORRONE: Okay. Now, if I have a certain
10 distance Y. So I multiply that spectrum by this Y to
11 get an equivalent translation. Now, how can I input a
12 pure rotational spectra that is given in G per foot
13 without a length? How can I convert it?

14 MR. ZUDANS: Well, I think your difficulty I
15 think I do understand, but my difficulty is as follows:
16 If you analyze the structure and you have a
17 two-dimensional model, sometimes you say that model is
18 three-dimensional, but you input one directional
19 earthquake. That is all fine. As a result of that
20 calculation, you came up with the time history of
21 displacements and rotations at different nodes.
22 Wherever you allowed for in-plant rotation, that
23 rotation showed up as a time history. If you take those
24 rotations, they are really physical rotations. The
25 things move, and get rotating. That is what you

1 compute, and you just cannot ignore that, unless you can
2 prove that they are 1 percent or so.

3 MR. MORRONE: You see, even when we multiply
4 these rotational spectra by the distance, the
5 eccentricity, even so, the increase in the combined
6 spectrum is very, very small, 1, 2 percent. Really, the
7 contribution of these torsional and rotational spectra
8 is not great until you get, for example, in reactor
9 service building or the steam generator building where
10 you have a moment arm of about 100 feet. Then it
11 becomes quite important.

12 MR. ZUDANS: I don't see how you can have 100
13 feet moment arm and assume it to be rigid.

14 MR. MORRONE: No, the equipment is located,
15 for example, on the floor 100 feet away from the node at
16 the center of the mass of the floor, okay? Then we say,
17 since it is not right at the node, we have to give a
18 component of translational motion which results from the
19 torsion.

20 MR. ZUDANS: Mr. Chairman, may I remark? I
21 think this is such detail that we should have done it in
22 Dr. Shewmon's subcommittee, which is supposed to be
23 structures and components, because this is not a
24 satisfactory -- at least not a completely satisfactory
25 answer. At any rate, one more question along these same

1 lines. When you turned around and did the component
2 analysis, did you consider relative motions of different
3 support points and different spectra --

4 MR. MORRONE: Yes, sir. Yes, sir.

5 MR. ZUDANS: You did? Would you explain what
6 you did then?

7 MR. MORRONE: We do a response spectrum
8 analysis, and then we superimpose on the results of the
9 response spectrum analysis those obtained from the
10 differential motion between the two spectra. We add
11 them absolutely.

12 MR. ZUDANS: And then that means that you took
13 the time history results and scanned through the entire
14 time history to analyze for differential motions, or did
15 you just take the peak?

16 MR. MORRONE: Sometimes we just take the
17 absolute sum of the peaks. You can't get any worse than
18 that.

19 MR. ZUDANS: That would be all right, then.
20 That is okay.

21 MR. MORRONE: As a matter of fact, this is
22 part of our criteria in our criteria document.

23 MR. ETHERINGTON: May I clarify my own
24 thinking a little bit here? From a simple mechanics
25 point of view, a motion of a point in space is

1 determined by three components of translation, and three
2 components of rotation. That is correct, isn't it?

3 MR. MORRONE: Yes, sir.

4 MR. ETHERINGTON: And for purposes of
5 analysis, these three components of rotation get divided
6 up into two torsional and two rotational components? Is
7 that how it stacks up?

8 MR. MORRONE: Yes, sir, because in building a
9 model, each node has three degrees of freedom in the
10 horizontal direction: translation, torsion, and
11 rotation. You see, there are three different
12 independent analyses.

13 MR. ETHERINGTON: You get one extra component
14 of motion. From a mechanical point of view, there are
15 just six components of motion, aren't there?

16 MR. MORRONE: Seven all together.

17 MR. ETHERINGTON: A point in space. Isn't
18 this motion governed by three dimensional?

19 MR. MORRONE: A three-dimensional point in
20 space, yes.

21 MR. ETHERINGTON: Three translations and three
22 rotations.

23 MR. MORRONE: Yes.

24 MR. ETHERINGTON: So we get an extra one in
25 the analysis.

1 MR. MORRONE: Well, you could look at it this
2 way, because we have three planar models, you see.

3 MR. ETHERINGTON: Oh, I see.

4 MR. MORRONE: And we have a torsion and a
5 rotation along with the translation with each of the two
6 horizontal models. If they were fully
7 three-dimensional, then yes, we would get six.

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1 MR. CARBON: Dr. Trifunac, did you get your
2 questions answered a while ago?

3 MR. TRIFUNAC: Yes.

4 (Slide.)

5 MR. MORRONE: Additional conservatism is
6 employed by driving design spectra from the computer
7 developed spectra that we have been discussing. This is
8 done, of course, by enveloping the upper and lower
9 bounds of soil moduli by widening the peaks for
10 uncertainties and frequencies of the building, and by
11 smoothing the spectra to eliminate valleys and various
12 spectral fluctuations.

13 These now are the spectra that we use for
14 design and result in conservative design spectra. I
15 will show you an example of how these design spectra are
16 derived. We see the lower bound soil modulus spectrum,
17 the upper bound and then the design curve. This valley
18 disappears altogether with this line, and just as an
19 example, at 4 1/2 hertz will have over 15 percent
20 conservatism by using the design spectrum.

21 (Slide.)

22 Now for time histories, we also believe we
23 have to do something rather than just using the raw
24 computer drive time history, because of any
25 uncertainties in the frequencies of the building. So

1 one way of doing this is to vary the delta t, the time
2 at which the accelerations are given in the time
3 history. That would be analogous to compressing and
4 expanding the history.

5 The question here is how much: $\pm$ or 10
6 percent, and is the time history at ± 10 percent, -10
7 percent the optimum, or we may have to search within a
8 10 percent variation to find an optimum time interval.
9 But with any of these methods here given by this bullet,
10 you can understand that this would result in many time
11 history analyses which, as you know, are very costly.

12 So to eliminate the need to perform all these
13 time history analyses, we developed spectra-consistent
14 synthetic histories. What this means is we produce a
15 motion whose response spectrum envelops the design
16 response spectrum, a synthetic history.

17 These next two figures will show you the
18 derivation of this design history. First, this happens
19 to be the spectrum at the reactor vessel supports SSE,
20 east-west horizontal. This is the response spectrum the
21 the original time history by Burns and Roe shown
22 superimposed on a design spectrum. You can see right
23 now how much margin we have between the raw spectrum and
24 the design spectrum.

25 Then we take the history that gives this

1 spectrum and input it to computer programs, and by a
2 process of amplification and suppression, we obtain a
3 time history which envelopes even this design response
4 spectrum, as shown on this next figure.

5 (Slide.)

6 You see, we necessarily have to increase the
7 DBA, increase the peak and the various frequencies. We
8 have quite a bit more.

9 (Slide.)

10 Okay. So far we have been discussing the
11 input, the seismic input, for systems or components
12 supported on buildings. For components supported on a
13 system, for example, the drive line, not supported on
14 the reactor system, then we have to go through the same
15 process that is done with the building. We have to make
16 a model and analysis of the system, input the design
17 histories and then output response histories and
18 response spectra for a dynamic analysis of confidence.
19 Then, the resulting spectra are again widened and
20 smoothed to give component spectra another 15 percent or
21 so of valleys eliminated and so forth.

22 We also do response spectrum analysis on the
23 system model for those components which can be modeled
24 in sufficient detail so that we get seismic loads such
25 as forces and moments, such that we can design the

1 components.

2 (Slide.)

3 This is just an example of our system model.

4 As I was mentioning before, it is a three-dimensional

5 model, 6 degrees freedom of movement per node, and

6 consists of many parts, the vessel, the core assemblies,

7 primary control rod system. The response time histories

8 from this system analysis for the primary control rod.

9 Six of them are used as input to a drive line model to
10 perform the scram analysis for that system.

11 (Slide.)

12 I would like to discuss damping values.

13 MR. ZUDANS: Could I ask you to go back to
14 that model a little bit?

15 MR. MORRONE: Yes, sir.

16 (Slide.)

17 MR. ZUDANS: In this model, where do you apply
18 your inputs?

19 MR. MORRONE: At the reactor vessel support.

20 MR. ZUDANS: That is the support?

21 MR. MORRONE: Yes.

22 MR. ZUDANS: And you only have now three
23 translations there.

24 MR. MORRONE: That depends upon which
25 histories we put in. If we put the design histories in,

1 then we have those 11 that I have shown.

2 MR. ZUDANS: Don't look them up; I remember
3 them.

4 MR. MORRONE: All the 11 histories that are
5 synthetic that envelop this.

6 MR. ZUDANS: This model is actually -- the
7 reactor vessel is a cylindrical shell, in essence?

8 MR. MORRONE: It is a stick. These are all
9 stick models.

10 MR. ZUDANS: The others are -- ?

11 MR. MORRONE: They are all represented by
12 sticks and springs like for the plugs, mass springs.

13 MR. ZUDANS: They all end up being supported
14 against the vessel node?

15 MR. MORRONE: Yes, sir.

16 MR. ZUDANS: Did you verify in your own mind
17 that the stick model for a reactor vessel is adequate?

18 MR. MORRONE: It is adequate for a system
19 model. Now, for the vessel itself, then, the vendor
20 does a full-blown finite element analysis. This is a
21 system model to obtain -- mainly to obtain spectra and
22 histories to design the components. You see, now for
23 the vessel itself I believe Babcock & Wilcox has the
24 vessel analysis and they take the input that we provide
25 them and do a full finite element analysis of the vessel

1 with their own computer program.

2 MR. ZUDANS: That would be all right if your
3 attachment points were with some kind of a radial stiff
4 member that prevents the point attachment to the vessel
5 wall which can deflect locally. I would assume you
6 have, of course, a work plate that stretches across the
7 entire vessel. That is a reasonable point of support.
8 Is everything that is attached to the vessel here --
9 those are the dashed lines you have here, right? You
10 have two of them. One dashed line attaches the core
11 support and the other one higher up attaches the thermal
12 liner.

13 MR. MORRONE: Yes.

14 MR. ZUDANS: How is the thermal liner attached
15 on the upper node? It is not attached.

16 MR. MORRONE: Over here?

17 MR. ZUDANS: Yes.

18 MR. MORRONE: No.

19 MR. ZUDANS: Where is the sodium? Is the
20 sodium represented in here?

21 MR. MORRONE: Yes, it is. It is represented
22 -- I don't have a viewgraph to show you all of that. I
23 didn't come prepared to go through this presentation,
24 but basically, we use trapped sodium and non-trapped
25 sodium with fluid coupling elements to take care of the

1 hydrodynamic mass effect.

2 MR. ZUDANS: This model is simply added to the
3 vessel as a mass?

4 MR. MORRONE: As mass for the non-trapped
5 sodium. For the trapped sodium, there is a fluid
6 coupling element along with the mass.

7 MR. ZUDANS: You don't show it here?

8 MR. MORRONE: No, because this is just the
9 schematic of the reason for -- the reason for showing
10 you this is to show that we have a system that we do an
11 analysis to get the load spectra and histories. If I
12 wanted to go through a presentation on our system
13 analysis, I would have much better viewgraphs that would
14 show all these details.

15 MR. ZUDANS: But at any rate, you do have
16 sodium included in this model in some fashion?

17 MR. MORRONE: Oh, yes, sir. Yes, sir.

18 (Slide.)

19 Okay. Damping values. Remember, there was a
20 quite a bit of discussion earlier. These are the values
21 that we used for our equipment; 2 percent OBE, 3 percent
22 SSE for our system model. Now, these values are quite
23 conservative. They are not maximum permissible; they
24 are values that we can use without justification.
25 Besides, if we have test data that shows higher damping

1 values, we will use the higher damping values. The 4
2 and 7 percent for the structure are also quite
3 conservative. I have test data that show that these
4 values are smaller than they should be.

5 Our Westinghouse Water Reactor Division, for
6 example, they use 4 percent for the damping for the SSE
7 for their equipment. Why? Because we wrote a report, a
8 Westinghouse report, on damping values of nuclear power
9 plants' components, and this report justified this 4
10 percent of critical damping as being a very conservative
11 value. But we still use 3 percent.

12 This mode says reduced damping value should be
13 used when combined stresses are below one-half yield.
14 We pay quite a bit of attention to that. Also, we use
15 the OBE damping values for the SSE for active
16 components. But these are not maximum, but we believe
17 they are very conservative.

18 (Slide.)

19 Just to give you -- you all know this, but
20 just to show the effect on our system design if we were
21 to use 4 percent instead of 3 percent. This is over a
22 15 percent increase on peak that we are using now.

23 (Slide.)

24 I would like to discuss very briefly the basic
25 seismic load combinations. Of course, the seismic loads

1 or stresses must be combined with all of the other
2 applicable loadings. Generally, the OBE is classified
3 as an upset condition or service level feed condition,
4 and the SSE is classified as a faulted or service level
5 D condition.

6 For seismic category 1 vessel piping and
7 inactive pumps and valves, the OBE load combination
8 basically consists of dead load, plus live, plus
9 operating, plus thermal, plus upsets and normal
10 transients, plus the OBE.

11 For fatigue evaluation, we would consider 5
12 OBEs during the life of the plant; each OBE producing 10
13 maximum peak stress cycles. The SSE load combination
14 includes basically the same loads, except the faulted
15 transients and also a dynamic system loading.

16 Then, for the active components, we upgrade
17 the faulted condition to an upset condition to allow for
18 more margin.

19 (Slide.)

20 Now we come to seismic testing. We are
21 through with analysis. Of course, testing is performed
22 for complex equipment which cannot be analyzed, but most
23 important for that equipment whose function cannot be
24 assured by structural integrity alone. Now, this
25 basically consists of instrumentation and electrical

1 equipment. The qualification is to the IEEE standard
2 344-1975. We are preparing a new version of this.
3 Basically, the same criteria are given.

4 Again, the main criteria is a comparison
5 between the test motion and the required motion, which
6 is defined by a response spectra, required response
7 spectra, and test response spectra. There are two main
8 categories of test: single frequency test and multiple
9 frequency test.

10 As the name implies, in the single frequency
11 test there is a wave form containing one frequency, but
12 this is the frequency of a component. I will explain
13 later on resonant testing. Whereas, with the multiple
14 frequency test, the wave form has many frequencies
15 reproduced.

16 Now, the single frequency tests are very much
17 applicable when the seismic motion has been filtered by
18 the building soil system. And since these tests are
19 performed at resonance, I believe that they constitute a
20 very severe test where the equipment is most vulnerable
21 at its natural frequency.

22 Multiple frequency tests are applicable when
23 the seismic ground motion has not been strongly filtered
24 such that it retains its broad band characteristics.
25 However, our criteria on the CRBR stipulates that when

1 single frequency testing is used, we must also test with
2 the multiple frequency motions basically to satisfy the
3 IEEE 344 criterion on full spectrum enveloping; whereas,
4 the single frequency does not develop over the whole
5 spectrum.

6 When multiple frequency testing is used, it is
7 recommended that it be followed by single frequency
8 testing, but it is not a requirement since the multiple
9 frequency testing fully satisfies IEEE 344.

10 (Slide.)

11 Okay. For single frequency testing, we use
12 sine beat motion. This is to limit the resonance
13 amplifications to reasonable values as opposed to
14 sinusoidal or steady state motion. We usually use a
15 trail of five beats with a time between beats, typically
16 two seconds, so that there is no super-position between
17 one beat and the other. The cycles within the beat are
18 10, and the frequency is made to coincide with the
19 frequency of the equipment to be tested. This happens
20 to be the ZPA on the response spectrum, which is the
21 peak sine beat acceleration. The basic seismic test
22 procedure is shown here.

23 (Slide.)

24 The single frequency sine beat tests perform a
25 frequency search from one to 33 hz. Then we do SSE sine

1 beat tests at each natural frequency, and from the
2 frequency search, and also at one-half octave intervals
3 in case we missed a frequency. We use five beats of
4 motion with ten cycles per beat. The shaketable motion
5 maximum acceleration should be equal to the ZPA of the
6 required response spectrum, but in practice, it is
7 usually two or three times as big.

8 The test response spectra maximum response
9 acceleration is greater than that on the RRS. As a
10 matter of fact, it is one and a half times as large. We
11 performed one OBE test preceding the SSE test at each
12 frequency, and we used independent direction input.
13 Sometimes an item will respond more vigorously to one
14 direction input than three.

15 Then we follow up with the multiple frequency
16 tests. The procedure for those is basically the IEEE
17 standard 344 with five OBEs preceding one SSE random
18 motion biaxial direction input, horizontal-vertical, and
19 the criteria to envelop the RRS with the TRS.

20 MR. TRIFUNAC: Could I ask a question?

21 MR. MORRONE: Yes, sir.

22 MR. TRIFUNAC: This is sort of a general
23 question based on some past experience. Where, for
24 example, we have a plant designed for maybe 15 percent g
25 or 20 percent g and it turns out we have a very small

1 type earthquake in here of very short duration, the
2 small magnitude maybe has a 30 percent g acceleration,
3 so it would be like a very high frequency burst of
4 energy, having frequencies in excess of 30, maybe even
5 40 hertz, but only one excursion.

6 Now, do we have here a test that would
7 possibly model that type of an environment?

8 MR. MORRONE: First of all, this high
9 frequency will be filtered by the building so you do not
10 see it at the location of the equipment.

11 MR. TRIFUNAC: Well, yes. If the equipment
12 were high up in the building. But if the equipment were
13 somewhere on the foundation.

14 MR. MORRONE: Well, if it were on the
15 foundation, no, but as I will show you later on, we do,
16 because it is very difficult to synthesize a shaketable
17 motion that envelopes the required response spectrum
18 without increasing the ZPA two or three times. In that
19 case, you see, it would take care of this particular
20 example.

21 Of course, our earthquake is designed --

22 MR. TRIFUNAC: Try to bear with me. I am not
23 trying to talk within the defined earthquake. I am
24 trying to go beyond that. I am saying what if we had a
25 number of cases where we saw a type of a small

1 earthquake that is not of concern to the civil
2 engineering part of the system? It is a very short
3 length of high acceleration type of event, and from the
4 structural point of view, it really doesn't contribute
5 much.

6 But I am asking about a piece of equipment
7 that may be founded in such a fashion that it will not
8 be filtered through the building.

9 MR. MORRONE: If this equipment is mounted on
10 a foundation and you have this type of earthquake that
11 you described, first of all, this is a non-damaging
12 earthquake. It is just an impulse.

13 MR. TRIFUNAC: It is not damaging from, say,
14 the point of view of a containment structure, but it has
15 maybe like five or six or maybe 20 cycles of 40 hertz
16 type of --

17 MR. MORRONE: Not much amplification if you
18 were to derive a response spectrum.

19 MR. TRIFUNAC: Right. But it might have a
20 peak acceleration of 20 percent g.

21 MR. MORRONE: What we are concerned with there
22 is the ZPA, the peak acceleration.

23 MR. TRIFUNAC: Well, maybe there is a piece of
24 equipment that has a natural of 45 hertz, say, and it
25 would be in the frequency range of that, shortlived

1 earthquake from the civil engineering point of view, but
2 maybe not shortlived from the equipment point of view.

3 MR. MORRONE: Of course, for this non-linear
4 equipment this would be important because the ZPA is
5 important for non-linear equipment. Now you see that
6 the frequency search is done only from one to 33 hertz,
7 but I believe that -- I want to show you some
8 comparisons of TRS and RRS. I believe from that
9 comparison I hope -- to answer your question -- to show
10 you how much bigger the ZPA of the test response
11 spectrum is.

12 MR. TRIFUNAC: So this is coming out a little
13 bit later?

14 MR. RAY: Before you leave that diagram, what
15 determines the span of the frequency from 1 to 3 hertz?

16 MR. MORRONE: That's the magic number here,
17 but I believe the genesis came with the period of .03
18 gives you 33 hertz -- that is really the frequency, the
19 amplifying power of the earthquake, that beyond 33 hertz
20 it does not produce any amplification.

21 Now you can see this from the regulatory guide
22 response spectrum, from the criteria response spectrum
23 that goes to 33 hertz and that is ZPA which is the peak
24 in the time history. So the typical earthquakes do not
25 have amplifying power beyond 33 hertz. But 33 seems to

1 be a magic number and it came from the .03.

2 MR. RAY: What you are saying is this is a
3 natural law, is that what you're saying, a natural
4 phenomenon?

5 MR. MORRONE: Well, more or less, because a
6 lot of earthquake motions have been analyzed and have
7 shown that beyond 33 hertz they do not have any
8 amplifying power, yes. I guess you could consider it as
9 a natural law.

10 MR. ZUDANS: It is not the earthquakes that
11 don't have the natural power; it is the structures that
12 do not respond to those high expectations. The
13 structure determines what gets amplified and what
14 doesn't get amplified, not the earthquake.

15 MR. MORRONE: You wouldn't see very high
16 frequencies above 33 hertz.

17 MR. ZUDANS: That is correct, because if you
18 don't have the frequencies in that, then there is
19 nothing to respond to.

20 MR. MORRONE: There are usually not high
21 frequencies in ground motion.

22 MR. TRUFUNAC: Could I comment on this,
23 because you ask the question I was sort of -- there is
24 no physical law here. Historically, we did not have
25 instruments that were able to record much beyond 20 to

1 25 hertz. The instrument properties themselves were
2 filtering out the input motion, number one.

3 Number two, for years, we did not have the
4 ability to digitize those data beyond those
5 frequencies. We had techniques that were, by their very
6 nature, filtering out the motion that may have been
7 there. Thirdly, we never had enough instruments to be
8 really very close to a small earthquake; therefore, just
9 by statistical fact of observation, we didn't record
10 small earthquakes or large earthquakes at close distance.

11 But nowadays that we can do all of these
12 things, we are discovering that there are very high
13 frequencies with high accelerations for even small
14 earthquakes if we come very close to the source. It is
15 not a physical law; it is just a traditional coincidence
16 of facts.

17 (Slide.)

18 MR. ETHERINGTON: Are these very high
19 frequencies of concern from a practical point of view?

20 MR. TRIFUNAC: Are you asking me a question?

21 MR. ETHERINGTON: I said are these very high
22 frequencies important in actual structures and
23 instrumentations.

24 MR. TRIFUNAC: I guess they are not really
25 important for the structures. They are important in the

1 way that they do suggest that the shape of Regulatory
2 Guide 1.60 spectra is not capable to handle that
3 situation. We have had a number of cases in the past
4 that clearly pointed that out. The shake that we are
5 using for 1.60 is not capable of handling that situation
6 from the damage point of view. It may not be important
7 for structures but it may be very important for certain
8 types of equipment, high frequency equipment.

9 MR. ZUDANS: The kind of building and
10 containment structures we have where all of this
11 equipment is attached do not amplify frequencies beyond,
12 say, 33 hertz roughly. Therefore, you get whatever the
13 rigid body motion of the seismic event is. And if there
14 is equipment like -- I guess that is what Mike is trying
15 to say -- that has natural frequencies, maybe 60 cycles,
16 and gets that excitation, that may be significant.

17 MR. ETHERINGTON: Yes, I understand that. I
18 was asking really whether there is any such equipment
19 that is important.

20 MR. ZUDANS: There is lots of equipment that
21 has that natural frequency, but ZPA amplitudes are so
22 small that you don't really care, because what is .25g?
23 It kind of disappears in the noise.

24 MR. CARLON: Go ahead.

25

1 MR. MORRONE: I would like to show an example
2 of a comparison of the TRS, the RRS for tested
3 equipment. This is reactor shutdown on isolation
4 equipment, such as comparators, buffers. These items
5 are housed in cabinets and the whole cabinet is
6 shake-table tested both sine beat unidirectional. And
7 multiple-frequency biaxial motion was employed in these
8 tests. After the test was made in one direction, the
9 cabinet was rotated 90 degrees and rotated in that
10 direction.

11 The function, the items is a function properly
12 during and after testing, and the test response spectrum
13 conservatively enveloped the required response
14 spectrum. Plus, there was additional conservatism by
15 enveloping the horizontal part of the response spectra.
16 What I mean here is that we have a north-south and
17 east-west required response spectra, so we envelop both
18 of them to provide one horizontal spectrum.

19 Then there is an additional conservatism given
20 by horizontal RRS 10 percent IEEE 323. And, of course,
21 use of the design spectra.

22 (Slide.)

23 The plots are shown on the next two figures.
24 First, for the horizontal motion the solid lines is the
25 required response spectrum; the dashed line the test

1 response spectrum. You can see that the ZPA of the
2 response test spectrum is three times as much as the ZPA
3 of the required response spectrum. And it goes along
4 the peaks, 4.4, for example, versus 2.85 Gs, the same
5 comparison shown for the vertical motion here, where the
6 ZPA again is three times as much.

7 I think this should take care of that small
8 earthquake, Dr. Trifunac, that you were talking about.
9 Peak, this is more than twice as much.

10 So these are very conservative tests, and
11 besides, they were done at resonance and with
12 multiple-frequency motion.

13 MR. ZUDANS: Except for in the case of
14 resonance, you did not look at frequencies beyond 30
15 cycles.

16 MR. MORRONE: No, sir.

17 MR. ZUDANS: That means any frequencies beyond
18 30 Hz, as you show here, might be different than you
19 would with your PRS.

20 MR. MORRONE: For sine B, right. But we take
21 care of this with the multiple-frequency motion. So we
22 really catch it both ways.

23 I would just like to summarize our
24 presentation by showing the conservatism on our seismic
25 criteria. Under simplified spectra we have a

1 conservatism which approaches that given by the absolute
2 sum versus the square root of the sum of the square of
3 directional effects. We have conservatism when we do
4 simplified analysis of 1.5 times the maximum peak.

5 Under the design spectra we develop the upper
6 and lower bounds of the sound moduli. We eliminate
7 valleys, we widen and smooth the spectra. For design
8 histories we develop the design spectra consistent
9 histories. We conservatively envelop the design
10 spectra, and we combine the translational and torsional
11 design spectra even before we synthesize this design
12 history.

13 (Slide.)

14 For a component spectra we additionally widen
15 and smooth the component spectra which were derived with
16 conservative input to begin with. Also, in most cases,
17 we envelop three operating conditions: the normal;
18 preparation for refueling; and refueling conditions.

19 Under damping we have quite conservative
20 damping values of systems and components. We believe 3
21 to 4 percent should be more applicable than the 3
22 percent we are using for seismic testing. We use both
23 single-frequency and multiple-frequency testing, both
24 unidirectional and biaxial, ZPA and peak responses of
25 TRS higher than that of the RRS, as a matter of fact,

1 much higher in the case of the ZPA.

2 We use the design spectra RRS broadband
3 spectra. We envelop the north-south and east-west RRS,
4 and we have the 10 percent IEEE 323 margins.

5 Thank you.

6 MR. ZUDANS: You stated in answer to my
7 question, but I did not see here any place the treatment
8 of relative attachment point displacements. I also did
9 not see what you do if you have piping or something like
10 that that has two points of attachment in different
11 spectra.

12 MR. MORRONE: We envelop those two spectra.

13 MR. ZUDANS: Then you do take into account the
14 differential?

15 MR. MORRONE: Yes. This is part of our
16 criteria in the PSAR.

17 MR. DICKSON: Most of those are coming later.

18 MR. CARBON: Are there other questions of Mr.
19 Morrone?

20 MR. ETHERINGTON: Is there any class of
21 component that comes close to the design limit of the
22 other classes?

23 MR. MORRONE: Could you repeat that, please?

24 MR. ETHERINGTON: Is there any class of
25 component that comes closer to the design limit than

1 others?

2 MR. MORRONE: I do not know. You are giving a
3 margin?

4 MR. ETHERINGTON: The margin, yes. Is there
5 some that gives no problem at all and others --

6 MR. MORRONE: Well, yes, but I cannot give you
7 a specific example. There are some components that are
8 so structurally sound that we do not even bother doing a
9 dynamic analysis. We take 1.5 times the maximum peak.

10 MR. ETHERINGTON: What about the components
11 that are sine beat tested, the cabinets and so on, do
12 some of those create a problem?

13 MR. MORRONE: To my knowledge, none of them
14 have created a problem. They have all passed the tests
15 with flying colors.

16 But perhaps Mr. Kraueter, who is going to give
17 the next presentation, can give you some information on
18 that.

19 MR. CARBON: Thank you, Mr. Morrone.

20 (Pause.)

21 MR. KRAEUTER: My name is Gary Kraeuter. I am
22 here this afternoon in the place of George Macrae, who
23 was unable to attend. I would like to give you a little
24 elaboration on how the electrical equipment was tested.

25 (Slide.)

1 Essentially, we are governed by IEEE 344. It
2 simply says that we have to demonstrate an equipment's
3 ability to perform its required safety performance
4 during and after an SSE.

5 How did we relate that to our equipment
6 specification. As Tony pointed out to you a little bit
7 earlier, the equipment specifications allow us through
8 the IEEE 344 to do testing, and we have used both sine
9 beat and random multiple-frequency. We are allowed to
10 use analysis plus some testing, or analysis.

11 (Slide.)

12 A typical list of the equipment that has to be
13 tested looks something like that. We have various
14 sensors out throughout the equipment. We have various
15 signal conditioning electronics, logic components, and
16 actuators.

17 To date, some of this equipment has been
18 tested. That equipment that has been tested appears on
19 that list.

20 (Slide.)

21 We have elected to do type-testing or
22 proof-testing on all of it. To give you an example of
23 what that kind of looks like --

24 MR. CARBON: Excuse me. What does it mean,
25 "type-testing," again?

1 MR. KRAEUTER: Proof-testing. We have taken
2 it up and provided it to the required test spectrums as
3 opposed to fragility testing where you might take it out
4 and destroy it. We have only taken it to a given
5 limit.

6 MR. ZUDANS: When you say that, that means you plan to
7 use the same tested components in the plant?

8 MR. KRAEUTER: By and large; I will not say
9 all across the board. We have used prototype equipment
10 for this.

11 MR. ZUDANS: And that component, after having
12 been subjected to this test, will be used in the plant?

13 MR. KRAEUTER: In most cases, no. In some
14 cases, that will be.

15 (Slide.)

16 The next piece of equipment, which is the
17 primary reactor shutdown system equipment, that is
18 prototype equipment. Okay. It was mounted on its base
19 and then that base was mountd on sort of a steel
20 channel. It was bolted to itin the same fashion it
21 would be used in teh plant, and then that steel channel
22 was welded to the shake table and then the test
23 proceeded from there.

24 In this case it was oriented to it was a
25 front-to-back motion and vertical motiop. Then it was

1 turned 90 degrees, and that was repeated.

2 MR. ZUDANS: And this cabinet will be used in
3 the plant?

4 MR. KRAEUTER: These will not. These have
5 since been shipped to storage. In the case of one, for
6 instance, that was done that way, it is a containment
7 isolation system --

8 (Slide.)

9 -- which is that one. This is plant
10 equipment. It was mounted in much the same fashion,
11 however. Everything is much the same way.

12 MR. ZUDANS: During this test you monitored the
13 functionality of all the pieces that are in this box?

14 MR. KRAEUTER: During this testing or just
15 before this equipment was fired up electrically, it was
16 tested. Then during each phase of that test, both the
17 sine beats and the random multiple-frequency, it was
18 functionally tested.

19 This has a scram breaker on it, for instance,
20 logic circuits. Those were functionally operated during
21 that time.

22 Now, as the sine beats progressed, the number
23 of sine waves that you got in the beat, the time frames
24 kept getting a little bit smaller and smaller. So we
25 ran out of being able to do this switch, to do that.

1 But essentially, every sine beat and
2 throughout the entire random multiple-frequency they
3 were tested electrically.

4 MR. ZUDANS: Your sine beat test really tests
5 the structure of this cabinet nicely. It tests the
6 relative motion of different pieces of your hardware
7 within it.

8 But when it comes to the natural frequencies
9 of individual components mounted in it, those 33 Hz are
10 probably far and away from their natural frequencies.
11 So your multiple-frequency load testing becomes very,
12 very important for its functionality.

13 Are you also testing functionality during that
14 portion of the test?

15 MR. KRAEUTER: Yes. We ran five OBEs and one
16 SSE on this equipment during the random multi, and
17 during each one of those it was functionally tested.

18 We also monitored and recorded all of the
19 outputs that are associated with this relay contact
20 voltages, state of the breakers, things like that.

21 MR. RAY: Can you tell me how closely the
22 equipment was welded to the shake table and conforms
23 with the way it is going to be welded to the channels of
24 the floor of the plant?

25 MR. KRAEUTER: I think the other slide shows

1 it to you a little better. In the plant this surface
2 right through here is where it will be bolted to the
3 floor in the plant. There are embedments on the floor in
4 the floor. This particular channel that we welded on,
5 it only actually adds a little bit more to the height of
6 this thing, which, in effect, makes it just a hair more
7 conservative.

8 MR. RAY: How is the cabinet fastened to those
9 channels, relative to the table?

10 MR. KRAEUTER: It was bolted to it in the
11 same fashion in the plant.

12 MR. RAY: So you are really checking the
13 installed condition -- the anticipated installed
14 condition of the cabinet?

15 MR. KRAEUTER: That is correct. They were
16 torqued to that same value. The manufacturer's
17 specified value.

18 MR. CARBON: Mr. Kraeuter, what are your
19 criteria for using some of the equipment in plant and
20 some of it just testing prototypes and not using it
21 further?

22 MR. KRAEUTER: This one was a prototype
23 equipment. At the time it was decided, I cannot tell
24 you that I know who made the decision on that. I was
25 not a part of that decision. I really cannot answer

1 that question, I guess.

2 MR. CARBON: Is there any general type
3 criteria that you are aware of?

4 MR. KRAEUTER: No, there are none, as far as I
5 know of.

6 MR. ETHERINGTON: In sine beat testing, you
7 tested the frequency of the most vulnerable component;
8 is that right?

9 MR. KRAEUTER: In the sine beat testing?

10 MR. ETHERINGTON: Yes.

11 MR. KRAEUTER: I guess I do not understand
12 your question. What we did was we --

13 MR. ETHERINGTON: How do you pick your
14 frequency?

15 MR. KRAEUTER: We ran a resonance search on
16 this equipment, found several points that for instance
17 that one had two on it, that were other than the octave
18 points, the partial octave points that are normally done
19 in sine beat, added those to it, and then ran the sine
20 beats including those.

21 MR. ETHERINGTON: Do you run the sine beat
22 test frequency at two different frequencies to
23 correspond to the two that you found?

24 MR. KRAEUTER: Yes.

25 MR. ZUDANS: But those were actually below 33

1 Hz?

2 MR. KRAEUTER: Yes. All of the testing was
3 below.

4 MR. ZUDANS: These are the frequencies of the
5 testing rather than the octave?

6 MR. KRAEUTER: I can't remember the exact
7 number, but there is on the order of 15 accelerometers
8 throughout this cabinet structure on various shelves and
9 other points. If any of those showed a resonance point
10 above an amplification factor of 2, it was added. That
11 point was added if it was a point other than what was
12 ordinarily planned for, we ran it.

13 MR. ZUDANS: Those accelerometers were mounted
14 on the cabinet?

15 MR. KRAEUTER: Yes. That is one there, and
16 there were others throughout the interior of the cabinet
17 also.

18 MR. ETHERINGTON: What I was getting at, in
19 the sine beat testing, is there any chance that you
20 undertest some component which has a frequency widely
21 different from the test frequency?

22 MR. KRAEUTER: I do not think so, not to the
23 33. Not to the 33 Hz.

24 MR. LIPINSKI: On relay system, do you ever
25 analyze a relay independently for its maximum G forces

1 and resonance frequency with respect to the preferred
2 direction for the armature and the holding force?

3 MR. KRAEUTER: No, I have not.

4 MR. LIPINSKI: So you do not really know how
5 far the relay could go or what the resonance forces
6 would be. Two cases: One, energized where I could pull
7 the thing open and reclose it; the other one where it
8 was deenergized, and I could bounce it and cause those
9 contacts to close.

10 MR. KRAEUTER: In this case, two of the
11 frequencies we tested and to the amplitudes we tested,
12 we had relays that were both energized and deenergized.
13 And because of the nature of the way it was turned, they
14 were at least changed in both horizontal directions.

15 MR. LIPINSKI: You get your choice of the X,
16 Y, and Z, but that depends on the way your seismic
17 excitation hits those cabinets. But it certainly seems
18 like it would be nice to know what the limits are for
19 these components independently such that you know
20 whether you are a factor of 10 away or you are only 25
21 percent off.

22 MR. KRAEUTER: I suppose that would be true.
23 I cannot answer that.

24 MR. LIPINSKI: Do you propose to do anything
25 to evaluate the relay independently? .

1 MR. KRAEUTER: There are no plans to do that
2 as far as I know.

3 MR. LIPINSKI: So you do not know what your
4 margins are, you only know that during these tests your
5 tests were satisfactory but what the margin may be as to
6 whether you have an error in the test or not?

7 MR. KRAEUTER: No, we did not take any of this
8 equipment to a failure mode.

9 MR. LIPINSKI: What about the big scram
10 circuit breakers? You have to trigger those to
11 deenergized and then have them drop open; right?

12 MR. KRAEUTER: Yes.

13 MR. LIPINSKI: And those operate in the
14 vertical direction?

15 MR. KRAEUTER: Yes.

16 MR. LIPINSKI: And what do they do when they
17 are excited with a vertical excitation? How much do
18 they dance? At what particular frequency?

19 MR. KRAEUTER: Again, to the frequencies we
20 tested them, there was no vibration or no contact
21 shatter associated with those scram breakers.

22 MR. LIPINSKI: They did not reclose once they
23 were there?

24 MR. KRAEUTER: No.

25 MR. LIPINSKI: Do you card how much they move

1 or do you just observe them electrically or just
2 observe?

3 MR. KRAEUTER: We do not record the vertical
4 motion of that contact opening. We only know it
5 opened.

6 MR. ETHERINGTON: Is sine beat testing
7 proprietary Westinghouse procedure?

8 MR. KRAEUTER: Not that I know of.

9 MR. ETHERINGTON: It was developed by
10 Westinghouse, was it not?

11 MR. KRAEUTER: I cannot answer that question.

12 MR. MORRONE: It is the method given in IEEE
13 344. It is a recognized method.

14 MR. LIPINSKI: Getting back to the scram
15 circuit breakers, you could do an analysis without
16 necessarily a test to try to get some feeling for what
17 that mass spraying system takes in order to get the
18 thing to bounce enough for a reclosure. Have you done
19 an analysis to try to fit it?

20 MR. KRAEUTER: Not to my knowledge.

21 MR. LIPINSKI: Do you plan to do it?

22 MR. KRAEUTER: Not to my knowledge.

23 MR. LIPINSKI: You do not know what your
24 margin is.

25 MR. KRAEUTER: As I said before, we did not do

1 any testing to failure or, in this case, a closure that
2 would constitute a failure.

3 MR. LIPINSKI: It seems like that analysis
4 would be relatively simple for that type of a
5 structure.

6 MR. ZUDANS: And the test is even simpler.

7 MR. LIPINSKI: These scram breakers they have
8 for their control rods fit in cabinets of that size are
9 relatively large masses.

10 MR. ZUDANS: Well, unfortunately, the sine
11 beat does not go beyond 33 cycles. And if the
12 frequencies go higher than that --

13 MR. TRIFUNAC: What is the frequency if you
14 take the mass and frequency? What are we talking
15 about?

16 MR. LIPINSKI: That is what I am asking, and
17 they do not know. That would be relatively simple. You
18 know what the masses are, you know what the springs
19 are. You could get a relatively quick determination.

20 MR. TRIFUNAC: Do we need to know the range?
21 Is it 50, 150 Hz?

22 MR. KRAEUTER: I do not know.

23 MR. LIPINSKI: And then with the small relays,
24 that is another question. They have their orientation.
25 That is why the clabbers are going to have to --

1 MR. DICKSON: Could we add something from back
2 here, please?

3 MR. MORRONE: Tony Morrone from Westinghouse.

4 We do not have frequencies of the floor motion
5 in excess of 33 Hz where these devices are located.
6 There is none of that high frequency.

7 And I must also add that sine beat testing is
8 only done by Westinghouse as an additional test. I do
9 not know other organizations that have performed this
10 test. Sine beat testing was developed by Westinghouse,
11 and we believe that it really proves the capability of
12 our equipment because we test the resonance. But it is
13 not required by IEEE 344. Other organizations do not
14 perform it. So it is something additional to give us
15 more margin, and there are no frequencies beyond 33 Hz
16 on the top floor of the control building where most of
17 this equipment is located.

18 MR. ETHERINGTON: Is it in all cases
19 additional?

20 MR. MORRONE: Yes, sir, it is always
21 additional, just to prove the capability of our
22 equipment even more so.

23 MR. ZUDANS: The statement then that there are
24 no frequencies higher than that floor, of course, has to
25 be qualified with a level of acceleration of amplitude.

1 There are low amplitudes; whatever comes up from the
2 foundation gets transmitted as a rigid body except it
3 does not get magnified.

4 MR. MORRONE: It is nonconsequential.

5 MR. ZUDANS: If you run the sine beat at 150
6 or 200 Hz with nonconsequential amplitude, prove to
7 yourself that the relay context stay there nicely, then
8 that is it, you would have proven your point.

9 MR. MORRONE: We basically do that by
10 inputting the very high ZPA.

11 MR. ZUDANS: Talking about that, the sketches
12 that you showed on the spectra TRS and RRS, you broke
13 them off at some frequency of 100 Hz or so. That is
14 because you just did not plot them further. Were these
15 components excited by higher frequencies?

16 MR. MORRONE: We were not even required to go
17 to 100 Hz.

18 MR. ZUDANS: If you had drawn the actual
19 input, analyzed it for higher frequencies, would you
20 have excitations higher than ZPA?

21 MR. MORRONE: The ZPA would start at
22 approximately 33.

23 MR. ZUDANS: Not on these that you showed.
24 There is a tremendous amplification on the ones that you
25 showed.

1 MR. MORRONE: Well, there is not that much.
2 What is it, RRS, 50? That is where the ZPA starts.

3 MR. ZUDANS: Well, look at your
4 beyond-100-Hz. You have three times your ZPA; right?

5 MR. MORRONE: Yes. But you have to look at
6 what frequency the ZPA begins. 33 or so, you see for
7 the horizontal motion, so you can draw that to infinity,
8 if you want.

9 MR. ZUDANS: That is not what I am trying to
10 say. I am trying to help you. Let me just see whether
11 I can manage it. I am saying that if you run your tests
12 and took the input motion and analyzed that input motion
13 for the spectrum beyond 100 or 200 Hz, what level
14 acceleration would you find in that test?

15 MR. MORRONE: The ZPA.

16 MR. ZUDANS: It would exist there?

17 MR. MORRONE: Yes. There is no -- it is
18 beyond amplification.

19 MR. ZUDANS: That ZPA depends on your input.

20 MR. MORRONE: And exactly at the input, let us
21 say, there is a not very high frequency content that
22 would cause any amplification.

23 MR. ZUDANS: Okay. Would that mean that your
24 test was actually performed at ZPA level of acceleration
25 for very high frequencies?

1 MR. MORRONE: Yes. You could say that, yes,
2 sir.

3 MR. ZUDANS: So then if you could say that,
4 you test the equipment.

5 MR. DICKSON: This takes away from the curve
6 you are talking about.

7 MR. MORRONE: When the motion is synthesized,
8 they do not try to put in very high frequencies, to
9 begin with. So the ZPA ten is constant.

10 MR. TRIFUNAC: That is right. But I think
11 that the discussion is beyond the present regulations.
12 The present regulations only go beyond 33. I think the
13 question is what if there is an excitation that has
14 frequencies up to 40 or 50 Hz; I think that is the
15 question.

16 Obviously -- obviously -- if low-pass filter
17 your excitation function, there is no doubt that they
18 should look like this, because the energy is not
19 available for frequencies higher than 33 Hz. But the
20 question is, as I understand it, what if there was an
21 excitation that did have frequencies maybe 40 to 50 Hz?

22 MR. MORRONE: Then the RRS would not be
23 correct.

24 MR. TRIFUNAC: Absolutely. There is no
25 question about that. But the question is what can you

1 say about the equipment using these tests?

2 MR. MORRONE: What I could say in that case is
3 due to the high level of the ZPA, that would take care
4 of the high frequency.

5 MR. TRIFUNAC: If the ZPA were representative
6 of the high frequency. But the ZPA is very much
7 dependent on the high-frequency spectrum. So if you
8 low-pass filter the function, you decrease the ZPA;
9 right?

10 MR. MORRONE: Right.

11 MR. TRIFUNAC: So the ZPA that you have is not
12 really representative of the hypothetical case we are
13 talking about.

14 MR. MORRONE: If there is that case, then as I
15 said, the RRS would be incorrect. But I still believe
16 the test would be a good test.

17 MR. TRIFUNAC: Well, the test is good only as
18 long as it contains frequencies of excitation that are
19 in the pass band of the system you are testing; right?

20 MR. MORRONE: You are saying if the motion at
21 the floor level of the mounting of the equipment has
22 high frequency and besides if this high frequency
23 matches the frequency of an item --

24 MR. TRIFUNAC: Yes.

25 MR. MORRONE: -- then you are saying you may

1 be missing it.

2 MR. TRIFUNAC: That is right.

3 MR. MORRONE: If that were the case. But I do
4 not see the case as being very probable, because that
5 motion is highly filtered when it gets to those levels.

6 MR. TRIFUNAC: That is a hypothesis.

7 MR. MORRONE: Analysis hypothesis plus some
8 test analysis data shows that.

9 MR. LIPINSKI: What is missing in this
10 discussion is the components, the relays and the
11 breakers that have spring mass systems that can be
12 bounced around, should be qualified in their own right
13 so you would know what their limits are in terms of
14 frequency and acceleration along that path that would
15 cause them to activate.

16 Unless we know those numbers, there is no way
17 to tell whether you are equipment-sensitive to the
18 assumptions that we are hearing.

19 MR. TRIFUNAC: And I think it is not a
20 question of that equipment being damaged; is it a
21 question of whether that equipment would perform what it
22 is designed to do, because it might close or open in a
23 completely elastic response range so the function would
24 be interrupted and there is no damage involved at all.

25 MR. LIPINSKI: In certain cases, you want to

1 drop a relay out, but if it is bouncing around it may be
2 making intermittently. In other cases, you call for a
3 breaker to go in, and once it is pulled in and locked,
4 and also if the seismic event is in place and you call
5 for it to go, the thing may not want to lock in, it may
6 want to just sit in there and bounce for you.

7 MR. MORRONE: In all those cases that it was
8 tested, all the relays and that breaker --

9 MR. LIPINSKI: Yes, based on the assumptions
10 for your excitation. But I don't know what the limits
11 are for the device and what your margin was, whether if
12 you went to 50 cycles you would run into trouble.

13 MR. MORRONE: But I did the required response
14 spectra.

15 MR. LIPINSKI: Yes, based on what somebody
16 else told you. Okay. And if what they told you is
17 wrong, you may find you are in trouble when the real
18 event comes along.

19 MR. TRIFUNAC: That is right.

20 MR. ZUDANS: Besides, you told yourself when
21 you did the sine beat and you increased the frequency
22 there was not enough time for you to check the
23 functionality.

24 MR. MORRONE: That is true.

25 MR. ZUDANS: So you may not even know in this

1 test range that your contacts are closing or opening.

2 MR. CARBON: I wonder at this point whether we
3 may want to hear from the Staff. Can I ask -- I do not
4 want to break up your caucus, but I think we have
5 carried our point through, and I guess you have heard
6 all of our discussion on it. And I would like to sort
7 of refer to you in the future.

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1 MR. ETHERINGTON: I expect these concerns are
2 not unique to the fast breeder reactor. I think they
3 apply equally to lightwater reactors. I do not know
4 whether they are valid or not.

5 MR. LIPINSKI: Let me make a comment. There
6 is a big discussion on qualification of Class 1.E
7 equipment, but the seismic testing got divorced from
8 that particular specification so it did not come up in
9 any of our subcommittee meetings until today.

10 MR. RAY: That is to be developed later as a
11 separate requirement. And the seismic electric
12 qualification Class 1.E mechanical or electrical.

13 MR. CARBON: Well, I guess we can move ahead
14 here, can we not?

15 MR. STARK: I guess I was going to make a
16 quick comment. We are certainly aware of some of the
17 conversation that is taking place, and I am not sure we
18 can answer all the questions here today. But the items
19 that the Applicant is talking about in the requirements
20 are the current Staff requirements right now.

21 What they have presented satisfies the Staff
22 requirements. The Staff requirements are always being
23 looked at, and I cannot shed any light on that right
24 now.

25 MR. CARBON: Yes. We do not ask it right

1 now. But we would ask you to take a look at it.

2 Go ahead then, Mr. Kraeuter.

3 (Slide.)

4 MR. KRAEUTER: Just quickly, Tony showed you
5 one of these curves earlier. We will show you a couple
6 of ther. These were taken from the actual test report
7 from the vendor showing you the required response
8 spectrum in the test response. That is for one piece of
9 equipment.

10 (Slide.)

11 For its redundant second part, secondary
12 system --

13 MR. ZUDANS: The TRS is the table motion?

14 MR. KRAEUTER: Yes. This is the table motion
15 located at the base of the cabinet. And then we have
16 another one for the containment isolation system.

17 And then finally just to wrap it up, all of
18 the equipment that has been tested to this date that we
19 know of has passed its seismic test and has been able to
20 perform its function during that test to the
21 requirements that we have imposed on it. And it has
22 also retained its structural integrity.

23 That concludes my presentation.

24 MR. DICKSON: Could I ask a question for
25 clarity, because I am not sure what was going on fully.

1 It seems to me we did this testing of, I guess, light
2 noise out to about 300 Hz. Are the consultants to the
3 ACRS suggesting that it requires a test of a sinusoidal
4 motion out beyond 300 Hz as opposed to a white noise
5 motion?

6 MR. ZUDANS: I do not think we are asking
7 that. I think the simplest answer to whatever questions
8 we asked is you have to know the limitations of the
9 pieces of equipment that came out in that cabinet. If
10 they are critical at high frequencies, I do not know
11 that -- I am certainly not asking you to modify any of
12 the tests. I am trying to find out whether your tests
13 adequately test the piece of equipment as Dr. Lipinski
14 described, the relays closing and opening at high
15 frequencies.

16 I am sure you adequately tested the cabinet.
17 I am sure that you adequately tested the functionaoity
18 where you had time to switch on and off.

19 MR. TRIFUNAC: Just a comment along the same
20 lines. As far as I can see, there is no question that
21 you have performed the tests that were required. There
22 is no question about that. The question is really are
23 the regulations that we are living with adequate to look
24 at all the possibilities?

25 Basically, I think, what you find is that

1 those of you who work with equipment sometimes have your
2 hands tied by the methodology that is imposed on you by
3 the structural engineers, and the methodology for
4 structural engineers may be adequate as far as
5 structures are concerned, but because of some low-pass
6 filtering equipment for the equipment excitation, it may
7 not be realistic in all cases.

8 So this sort of goes beyond, I think, the
9 present requirements.

10 MR. DICKSON: Thank you both for that
11 clarification.

12 MR. ZUDANS: It is certainly not unique to
13 CRBR.

14 MR. ZUDANS: Thank you, Mr. Kraeuter.

15 This might be a good time to take a break
16 before we start the next presentation.

17 (Brief recess.)

18 MR. PITTERLE: I am Tom Pitterle. I will be
19 describing the testing being performed in support of a
20 control rod system that is seismically related. In
21 particular, the emphasis in the testing is that in
22 support of scram insertion.

23 (Slide.)

24 To help a little bit in understanding the type
25 of tests, it is probably best to visualize the scram

1 functioning in terms of the unlatch function or the
2 mechanism releasing the translating assembly and then
3 followed by the insertion function or the motion of the
4 translating assembly and the control rod into the core.

5 In particular, in the insertion function, an
6 area of particular concern that the testing is
7 emphasizing is the ability to predict the normal forces
8 of the drag forces that would retard the insertion
9 motion in the seismic event.

10 So the testing that has been done and future
11 testing in support of the control rod systems is a
12 dynamic friction tests, the PCRS seismic tests, and an
13 SCRS scram valve and cylinder assembly test.

14 The dynamic friction test is the specific
15 objective of obtaining the effective coefficient of
16 friction in the seismic impact type condition. The test
17 was conducted by dropping a simple rod in three bushings
18 under a vibrational input by measuring the impact forces
19 at the bushings, the normal forces measuring the drop
20 times, and there is very little hydraulic resistance in
21 this particular test. We are able to extract then an
22 effective coefficient of friction as a combination of
23 the drop times and the normal forces.

24 The testing was done in air, argonne, water,
25 and sodium. We looked at material couples 304 to 718

1 The primary emphasis in the testing was done with 718 to
2 316, and 718 to 718. Inconel 718 and 316 stainless
3 steel.

4 Cylindrical and hexagonal test rods were
5 tested with the emphasis being on the cylindrical test
6 rods for the efficiency of testing. The result of the
7 testing gave us the design coefficient of friction that
8 envelopes all the data at a two-sigma level of about
9 .45 for all the materials. I will describe the results
10 of this test in considerable detail.

11 Our specifications would have said we used a
12 value of 1 in the absence of any test data and to use
13 test data that was basic objective was to obtain the
14 test data to be the friction coefficient of unity.

15 The dynamic friction test also helps us to
16 develop test experience for our more complex seismic
17 testing, which I will describe. The friction
18 coefficients, the dynamic friction test provides
19 friction coefficient for use by both the primary and the
20 secondary control rod systems. So it is supporting both
21 of the Clinch River shutdown systems.

22 The PCRS seismic test is to test the scram
23 performance under dynamic input conditions. The primary
24 objective is to validate the seismic scram analysis
25 methods. It uses completely prototypic hardware, full

1 control rod drive mechanism, control drive line, and
2 control assembly. We use water as a test medium. And
3 the testing will be starting in calendar year 1983. In
4 particular, this test helps to support the unlatch
5 function of the primary control rod drive mechanism.

6 The validation of the insertion methods helps
7 to support both the primary and the secondary system
8 because we both key off of the finite element analysis
9 of the normal forces, and that will be validated by
10 comparisons of predictions with this test.

11 The secondary seismic testing is the testing
12 of the scram valve and cylinder assembly as done per
13 IEEE 344.

14 (Slide.)

15 To describe the facility, this is a picture of
16 the facility for the dynamic friction test. It shows
17 the test vessel and the support structure, big I-beams,
18 a single lateral shaker applied to the I-beams,
19 vibrating the whole structure, media bearings which are
20 barely visible at the bottom of the picture.

21 You can see at least a little bit in the
22 picture of the three bushings, the strain bolt locations
23 for the three bushings, release of the drop rod occurred
24 in the upper end of this test vessel, and that released
25 the rod to drop down through the bushings while it is

1 vibrating back and forth and impacting the bushings.

2 The drop, in addition to measuring the normal
3 forces, we have position versus time displacements and
4 accelerometers to measure impact levels and give us any
5 indications of abnormal behavior.

6 MR. LIPINSKI: Are the scram valves electrical
7 solenoids?

8 MR. PITTERLE: The scram valves were not a
9 part of this test. The scram valves for the secondary,
10 which I will describe a little bit later, are on the mag
11 electrically solenoid.

12 MR. LIPINSKI: There is an electrical solenoid
13 valve?

14 MR. PITTERLE: Yes.

15 MR. LIPINSKI: That is to be seismically
16 qualified?

17 MR. PITTERLE: That is correct.

18 MR. LIPINSKI: That is another spring mass
19 friction with some damping coefficient?

20 MR. PITTERLE: Yes.

21 MR. LIPINSKI: So you would know basically
22 what that valve had for its own resonance frequency?

23 MR. PITTERLE: Some work was done to locate
24 the frequencies, but the testing did emphasize the
25 similar response spectra-type testing that was

1 previously identified.

2 (Slide.)

3 In addition to obtaining friction coefficients
4 from the dynamic friction test, it also provides us with
5 some preliminary verification of the scram analysis
6 methods. Again, the scram analysis methods are the
7 scram insertion part of the scram analysis.

8 The key, as I mentioned, is calculating the
9 normal forces. Given the normal forces, the friction
10 coefficient attains a drag force, and we can calculate
11 the hydraulic resistance to motion off of codes and then
12 verify it substantially against nonseismic testing.

13 So we use the ANSYS code for the finite
14 element analysis for the primary control rod system. We
15 are using three withdrawal elevations in the plan
16 modeling as well as this test so that we can account for
17 the effects of normal forces on heights and shifting
18 from one model to another at midpoints between the
19 elevations for which they are calculated.

20 Impact stiffnesses are calculated with the
21 Herztzian contact method. We found impact damping to be
22 not particularly important. Structural damping was
23 taken at .3 percent based on some general survey work
24 done in the testing for the very rigid test facility for
25 this test.

1 Fluid coupling is accounted for in the water
2 and sodium testing using the concentric cylinder model
3 of the ANSYS code.

4 Applying this modeling to the dynamic friction
5 test, we can verify it again and look at the checks
6 against tests in two ways. One is to analytically
7 calculate the normal forces, use those calculated normal
8 forces and contrast it to the test normal forces to
9 extract an effective coefficient of friction. Or we
10 could use those normal forces to calculate an effective
11 coefficient of friction.

12 So we have really looked at it both ways. We
13 can correct for the hydraulic forces by normalizing
14 through zero G test data so that we are confident of
15 making reasonable corrections for the very small
16 hydraulic forces that existed.

17 Then we did obtain U by adjusting the
18 calculated normal force calculations against drop times
19 and compared that with the U derived from measured
20 normal forces. We have also compared the average normal
21 force between the analysis and the test.

22 (Slide.)

23 This shows some of the comparisons that we
24 have obtained from this test in terms of the friction
25 coefficient and the average normal force analysis and

1 tests. For the three test conditions which we have
2 emphasized, this particular type of comparison.

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1 This was a test in air, inconnel 718 bushings,
2 this should be 22.8 Hz rather than 28 Hz, 1.5 Gs, .5 Gs,
3 then compare it in a water medium in the same conditions
4 as 1.5.

5 Using the calculated normal forces, you
6 measure drop times. We have obtained what I call the
7 anaylsis, and that yields a .32 coefficient of friction
8 which shows excellent agreement with that derived from
9 the measured normal forces.

10 We went down to half a G. The analysis of
11 fitting the drop times was very insensitive because
12 there was not enough load to particularly retard the rod
13 motion. You can fit off of a wide range, and we really
14 cannot do an adequate fit in that case.

15 Under test conditions, we could fit over
16 areas, local areas of the drop time to get an estimate,
17 but with a considerable higher error. We also obtained
18 good agreeement with test in the water medium and as
19 typical of some of the other data I will show you for
20 the impact friction, you find that there is very little
21 difference in the coefficients of friction between air
22 and water.

23 Comparing the average normal forces, we
24 obtained relatively good agreement at 1.5 G. We did
25 slightly underestimate at .5 G in this particular case.

1 The instrumentation sensitivity is not as good, and
2 there may be somewhat higher errors in the test value.

3 MR. ZUDANS: A couple of questions. How did
4 you measure normal forces?

5 MR. PITTERLE: The strain bolts, three strain
6 bolts, mounted on cylindrical bushings.

7 MR. ZUDANS: Did I hear you correctly, they
8 had three bushings?

9 MR. PITTERLE: Yes. Three vertically located
10 bushings..

11 MR. ZUDANS: How accurate was the alignment of
12 these bushings, or how sensitive would the results be to
13 the alignment of the bushings?

14 MR. PITTERLE: We looked at it in the early
15 phases of the test. We looked at the alignment of the
16 bushings and even a complete tilt of the vessel with the
17 dynamic conditions, it was not found to be that
18 particularly sensitive.

19 We looked at it. Compared drop times, for
20 instance, were not very sensitive to that alignment. We
21 did optically align the bushings at the start of testing
22 for this particular test. We knew where they were. But
23 it just has been found experimentally and analytically
24 that this was not very sensitive.

25 MR. ZUDANS: Was this rods relatively flexible

1 and bending?

2 MR. PITTERLE: This rod the test rod in here,
3 was -- yes, relatively a little more stiff than a normal
4 drive line would be because we had done some work to
5 embed it with additional instrumentation. But yes,
6 basically, in the plant the drive line is long and very
7 easily moved.

8 In the test it was easily moved, but we could
9 get some indications of the top part. There was a mass
10 at the top for the coupling, and that was wavering more
11 than the bottom parts.

12 (Slide.)

13 So what we have concluded as this preliminary
14 check of the scram analysis methods has emphasized that
15 the complete scram test of the control rod system will
16 provide us with some overall and more complete
17 verification of our methods. We did obtain good
18 agreement on the analytical and test Mu or the drop
19 times.

20 If we use the test Mu in the analysis, we get
21 a good agreement on the average normal forces. When we
22 looked at it in more detail, we found that the force and
23 impact frequency dependence on rod position. We used an
24 R-3 model; also gave the general behavior of the test as
25 a function of axial height.

1 So we did feel that the three-elevation
2 modeling disposition for the test was anticipated to be
3 sufficient for the plant. The test, in fact, should
4 have been more sensitive to axial position because of
5 the mass at the top of the rod than we had anticipated
6 the plant performance supports. We have general support
7 for the methods and the three-elevation model.

8 We did not see -- and I will show the more
9 direct data in a minute -- but we did not see any strong
10 difference between fluids, air, argonne, and water. And
11 to some extent, we found something in sodium.

12 Looking at it analytically, with the fluid
13 coupling model, ANSYS, we did not see much difference on
14 the normal forces, and the test did not show much
15 difference.

16 So what we have recommended from the test is
17 they use μ of .45 for fluids and .41 for gas. And the
18 seismic scram insertion analysis.

19 To show you more directly the type of test
20 data that we have obtained, this shows each of the data
21 points in this case is an average of 10 drops. We fit
22 each drop to fit a μ versus -- based on the normal
23 forces versus position curve average that obtained drop
24 feature of the data point represents an average of 10
25 drops.

1 We have looked at in this particular case,
2 comparing the effective rod environment and rod
3 velocity. To get the rod velocity effect, we ran with
4 and without a spring assist. So the speed of the rod
5 going through the bushings would be somewhat different.
6 So the spring/no spring is to look at the velocity
7 effect.

8 But in general, we found the data was more
9 accurate at 1.5 G and, in fact, tends to show by
10 drooping of the spread of the data there is no
11 identifiable effect of G level insertion of the G level
12 of the excitation when we consider that the standard
13 typical deviation of this data is on the order of about
14 .04 and friction coefficient which would flip us
15 essentially almost one of these lines would be one
16 standard deviation to the test.

17 We found no identifiable difference between
18 water and air, although the average does tend to be like
19 that .04 identified. We did find in our sodium testing
20 that we found consistently lower coefficients of
21 friction. What we believe part of that is, as much as
22 the medium, is the peculiarity of the way we had to
23 instrument the rod or had some guide rods along the rod
24 so that the top of the rod would not break off of the
25 instrumentation. That limited the top rod motion.

1 When we ran the sodium, we took the bushing
2 out of that rod, and that allowed somewhat more motion
3 without impacting the guide rod. So if you did not
4 impact the guide rod in this type of testing, you get
5 more normal force at the bushings and, in fact, that
6 increased normal force has led, we believe, to the lower
7 coefficient of friction rather than the sodium effects.

8 In fact, most likely, although we are not
9 trying to develop the argument to lower the coefficient,
10 the friction at this time, that the guide rod effect is
11 probably the reason that these values are much higher
12 than the sodium values.

13 We also looked at the effect of bushing
14 material and frequency of impact.

15 (Slide.)

16 We again found no difference. 22.8 Hz and 15
17 Hz, stainless-steel and inconel bushings, again within 1
18 standard deviation. We could not distinguish any effect
19 of the bushing material or environment.

20 MR. ZUDANS: Did you establish what were the
21 natural frequencies of this rod in different positions?

22 MR. PITTERLE: Yes, we did, at the start of
23 the test. A series of sine sweeps. We did some sine
24 sweeps at, I believe, three vertical elevations similar
25 to the three that we have looked at. These two

1 frequencies were picked to give us substantial
2 response.

3 MR. ZUDANS: So these are close to free-free?

4 MR. PITTERLE: Away from the rod and away from
5 the structure of the facility.

6 MR. POMEROY: Again, another question on that
7 same line. What would happen if you had 40 Hz and 10
8 Hz, say?

9 MR. PITTERLE: Keep in mind for this test the
10 rod is not prototypic for this test. It is not plant
11 hardware. It is just a rod to give us the effective
12 drive of coefficient of friction. The question may
13 apply validly to the other testing where we tested the
14 complete system and prototypes other than beyond the
15 sine sweep, where plans are to sweep up to the order of
16 about 33 Hz.

17 (Slide.)

18 Now I would like to describe the control rod
19 system or the primary control rod system prototype
20 seismic test. This is a picture of the facility.
21 Basically, we are using the silo to keep the weather
22 out.

23 But then we mount the shakers and control rod
24 to a reaction mass, which is 140 tons, 50-foot
25 elevation. We are using a triaxial shaker table, shown

1 here, which simluates the closure head of the reactor
2 vessel for purposes of the test. That has two
3 directions, X, Y, and vertical input capability. And
4 the control rod drive mechanism is mounted on that much
5 like it would be mounted on the closure head in Clinch
6 River.

7 The three different triaxial shaker table was
8 emphasized to test the unlatch or scram release part of
9 the mechanism. It is a collapsable rotor roller
10 mechanism, so the rollers are relaxed out, pushed out
11 away from the lead scoon, and you drop the lead scoon in
12 the control rod system.

13 That permits us to test our design basis for
14 designing that release function against triaxial input.
15 For the insertion function, the scram motion is
16 dominantly a one-dimensional effect. And that would be
17 -- the testing for that would emphasize one-dimensional
18 effects, and that is for these additional five shakers
19 here together with the one shaker as a part of the
20 triaxial table, which gives us a total of six shakers to
21 input for the scram insertion function.

22 Now, we can get some idea of coupling between
23 X and Y directions in a limited sense when we change
24 from X to X and Y on the table. So at some low level of
25 excitation we will get some checks on the additional

1 summations of the X and Y direction effects.

2 Basically, it does test the mechanism control
3 rod drive line, and the in-core control assembly. The
4 location of the shakers are such that they represent
5 typical locations for input from the balance of the
6 reactor system. For example, the control assembly has
7 an input through the core support structure at the inlet
8 nozzle through the core restraint system through the
9 load path and the top load path. The drive line, the
10 shroud tube which envelopes the drive line, the
11 excitation comes through the upper internal structure,
12 and these two shakers simulate that type of input, and
13 the triaxial shaker mocks up the closure head input.

14 (Slide.)

15 So in the testing we will do sinusoidal and
16 time-history input at acceleration levels which are
17 typical of OBE and SSE levels. But I do want to
18 emphasize that the purpose, the primary objective of the
19 test is verification of the design and analysis method.

20 This shows a picture of the triaxial shaker
21 table partially assembled. Here is the shaker. This
22 shows the X direction motion. You can clearly see
23 across here one of the Y directional shakers. The
24 mechanism then is mounted on this table. It does not
25 show the vertical direction in this .

1 particular picture.

2 Now I would like to describe the secondary
3 control rod system, scram valve testing. In testing the
4 scram valve for the pilot valve part of that is part of
5 the plant protection system falling within the IEEE
6 Class 1.E definition.

7 The applicable reg guide IEEE requirements are
8 here (indicating). The reactor system seismic analysis,
9 as previously described, provides a response spectrum
10 input, and it is obtained at the location of the scram
11 valve.

12 MR. LIPINSKI: This is the electrical solenoid
13 you are talking about now?

14 MR. PITTERLE: Yes.

15 MR. LIPINSKI: I would like to emphasize again
16 you do not know its basic characteristics based on its
17 spring mass damping.

18 MR. PITTERLE: To a complete extent, that is
19 true. There have been in prototype some sine sweep
20 type-testing done to look at the response frequencies up
21 to 100 Hz, and there has not been anything particularly
22 alarming from that. But the predominant part of the
23 verification testing is still consistent with that which
24 you have heard today.

25 MR. LIPINSKI: Because you did actually take

1 the single component and subject it to a test?

2 MR. PITTERLE: And the prototype.

3 MR. LIPINSKI: Okay. But as a component
4 alone?

5 MR. PITTERLE: As a component of a valve
6 assembly.

7 MR. LIPINSKI: But you did not put this as a
8 component on the shaker table and excite it and its
9 vulnerable axis to determine what it could take.

10 MR. PITTERLE: No, not to the limits, no. No
11 test to failure.

12 (Slide.)

13 The scram valve seismic test, I will show a
14 picture of what was actually the typical hardware
15 tested. The valve and cylinder subject to the
16 requirement of five OBEs and one SSE simulation
17 multi-axis excitation. I will describe that in more
18 detail. It was functionally tested during and after
19 each OBE and SSE simulation, and I will describe the
20 test results in more detail, that basically it has met
21 all functional and structural requirements.

22 (Slide.)

23 To give you an idea of what is meant by the
24 scram valve and cylinder, this shows a picture of one of
25 the prototype units. The cylinder is shown at one end

1 which is a pressure pneumatic piston. The tension rod
2 shown coming out of the cylinder comes across here,
3 actually connects with the latch and the control
4 assembly part of the reactor that releases the rod for
5 scram.

6 So the solenoid and pilot valves are the part
7 that trigger the release of the pressure that permits a
8 tension rod which is downward-loaded to release by
9 venting the pressure from the piston.

10 Three solenoids can be approximately
11 visualized as one here, one here, and one behind
12 (indicating). The pilot valves, pocket valves are shown
13 here (indicating), as well as opening and close
14 instrumentation for the pocket valve.

15 That was just meant to give you some idea of
16 what we are talking about with this type of testing.

17 (Slide.)

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1 To give somewhat more detail on that test, the
2 methods are pretty straightforward. Let me emphasize
3 the test sequence. The preseismic test was functionally
4 tested before the event. Then given five OBEs -- and,
5 in fact, the way the prototype was tested was really ten
6 OBEs -- five and then it was rotated 90 degrees and
7 given five more OBEs.

8 This statement is slightly misleading in the
9 sense that it was really repeated twice. So there are a
10 total of ten OBEs, counting the rotation of the
11 equipment. There is going to be scram during and scram
12 after each OBE.

13 The SSE was then simulated in a manner with
14 three earthquakes, three SSE inputs. The first one was
15 30 seconds followed by two five-second SSE simulations.

16 During each of these simulations, two out of
17 the three logic trains of the cylinder was tested in
18 different sequences. This particular bullet here
19 (indicating) should really be above this post-seismic
20 test. So two SSEs then were done in one reference
21 equipment on a biaxial shaker vertical and horizontal
22 shaker, and the third one had the equipment rotated 90
23 degrees.

24 Then again after the seismic testing, another
25 functional verification test was performed.

1 (Slide.)

2 The criteria for this test was that the scram
3 time for the control rod movement occurred within the
4 control rod release delay time of .1 seconds. And there
5 would be no visible or functional damage to the
6 component. The results of the prototype test showed no
7 damage. The actual test values range between a minimum
8 of 50 milliseconds to 62 milliseconds, and exceeded the
9 criteria and were not really significantly different
10 from nonseismic earthquake times that had been
11 measured.

12 (Slide.)

13 So just to summarize a little bit what I have
14 said and what we use this type of data for and the
15 application of these results, the dynamic friction test
16 provides the friction coefficient for use in the primary
17 control rod system and the secondary control rod system
18 seismic scram insertion analysis. So it is supporting
19 both systems in the use of that dynamic friction
20 coefficient.

21 Similarly, the preliminary verification of the
22 scram insertion analysis methods that I described
23 supports both systems. This is the key to the finite
24 element analysis. The overall PCRS seismic test
25 provides a confirmation of the unlatch basis for the

1 mechanism and also will be used to validate the
2 insertion times against prediction. And that again is
3 time-history type methodology that is used for both the
4 primary and the secondary control rod systems in terms
5 of its validation.

6 The secondary scram valve test is unique to
7 the verification of that scram actuator and is
8 qualitatively in general terms roughly equivalent to the
9 unlatch test function of the primary control rod
10 system.

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1 (Slide.)

2 For conclusions from what we have done to date
3 in terms of the completed tests, they show that we have
4 satisfied all of our design requirements for what has
5 been completed to date. In the dynamic friction test we
6 take the test coefficients of friction, perform the
7 seismic scram insertion analysis, and the seismic scram
8 speed requirements would be met for both the primary and
9 secondary control rod system.

10 For the secondary prototype scram valve test,
11 the functional requirements have been satisfied, and in
12 place for plant testing in the primary total prototype
13 system, plus the test of one of the valves of the
14 secondary -- the plant's unit group -- we feel that we
15 do have the tests plans in place to define confirmation
16 for both the primary and secondary seismic scram
17 capability.

18 MR. LIPINSKI: I have a question on your
19 primary systems. It's a roller nut design, right?

20 MR. PITTERLE: Yes.

21 MR. LIPLINSKI: What drives the nut apart when
22 you take the power off? Are the springs internal?

23 MR. PITTERLE: Yes. There are segment arm
24 springs. It's very similar to -- it's virtually
25 identical to the FFTF and very similar to the Naval

1 reactor program.

2 The segment arm springs force the segment arms
3 out from the -- the rollers of the segment arms out from
4 the lead screw.

5 MR. LIPINSKI: There is a pair?

6 MR. PITTERLE: There are four pairs. Upper
7 and lower pair on each side of the lead screw.

8 MR. LIPINSKI: Are they all all on the same
9 axis, or are they rotated 90 degrees with respect to
10 each other?

11 MR. PITTERLE: They are all driving two
12 segment arms, all on the same planes.

13 MR. LIPINSKI: They may have a spring mass
14 system. What's the resonance frequency for those
15 segment arms with their springs?

16 MR. PITTERLE: We will in the test, through a
17 sweep of -- we haven't defined the upper magnitude yet,
18 but I am thinking in terms of 50 hertz. We are going to
19 have an accelerometer mounted on the segment arms.

20 MR. LIPINSKI: This is a paper exercise I'm
21 talking about. You know what those nuts weigh, you know
22 what those spring forces are and you can come up with
23 the resonance frequency rather quickly.

24 MR. PITTERLE: I am not sure whether it has or
25 has not been done. I think it may have been done but I

1 can't cite any values.

2 MR. LIPINSKI: Once again, if that comes out
3 to be a couple of kilohertz you know you are well out
4 there, and your testing would just verify statistically
5 what you want to observe.

6 MR. PITTERLE: That is basically -- we do not
7 have a strong reservation on it, but I don't recall
8 whether we have calculated the natural frequency of the
9 segment arms by its support. I suspect so.

10 MR. LIPINSKI: It would be nice to have that
11 number.

12 MR. PITTERLE: We can look.

13 MR. KASTENBERG: Do you worry at all about the
14 core itself being distorted in an earthquake so that the
15 rod can't go in, in terms of any of these tests?

16 MR. PITTERLE: Not in terms of any of these
17 tests. There have been separate tests done in support
18 of the core assembly designs where there have been
19 looked at the loads required to deflect and to form
20 ducts.

21 For this type of testing I think the only
22 thing that would be relatively relevant would be if
23 there was significant deformation that could add to the
24 misalignment. We can simulate in this test facility
25 moving the components laterally analytically, and in a

1 few scoping analyses it really does not make a whole of
2 differences. You have a less sensitive scoping analysis
3 and then you are in the normal scrams just because the
4 thing is flopping back and forth as you go in.

5 But the core assemblies are designed for
6 sufficient margin. They really lock themselves up.
7 They really can't deflect very much. You push them over
8 to one side, you've got a solid mass of hex assemblies,
9 so that deflection is pretty small.

10 MR. KASTENBERG: I notice that so far in none
11 of the presentations, and I guess not on the agenda, a
12 discussion of the core and reactor internals with regard
13 to seismic. Is that to be covered somewhere else, or is
14 that not important or -- ?

15 MR. PITTERLE: The modeling is similar to that
16 of -- well, at least for the internals -- to that of
17 Tony Morrone, using a combination of time history and
18 response spectra. That is used on many components,
19 both, but no, there has been no planned specific agenda
20 item because we felt it fell under the general
21 methodology that was talked to by Morrone before.

22 MR. KASTENBERG: Is it something we should be
23 looking at in detail under seismic?

24 MR. PITTERLE: Are you addressing that to me?

25 MR. KASTENBERG: Yes. I guess going back to

1 one of our earlier meetings, we were talking about
2 design basis and events beyond the design basis, and one
3 was a reactivity excursion caused by a seismic event in
4 which you have 60 step reactivity.

5 MR. PITTERLE: And that dictates feed of
6 response.

7 MR. KASTENBERG: And somewhere along the line
8 we would hear about how one arrives at reactivity
9 insertions as a result of core motion due to the
10 earthquake. And I thought today was the place we would
11 hear it and I have been waiting to --

12 MR. DICKSON: This is Paul Dickson of
13 Westinghouse. I believe we are planning to do that as
14 the core restraint design, and I don't know when it is
15 scheduled. But Tom is not prepared to talk to it. Do
16 you recall when it's scheduled? I don't recall, but I
17 do think we discussed having a meeting at sometime in
18 which we would discuss the reactivity input as a result
19 of seismic and other events as part of a core restraint
20 meeting.

21 We certainly cover it if you wish. We are
22 prepared to do so. It was just not a part of this
23 meeting.

24 MR. CARBON: You mean you're prepared to cover
25 it some other time?

1 MR. DICKSON: Yes.

2 MR. CARBON: Well, I'm not sure where it fits
3 in our schedule. I guess we are going to have to get
4 back to you on that because we are very much interested
5 in that.

6 MR. DICKSON: That was my understanding, that
7 it was planned to be inserted.

8 MR. CARBON: Let's be sure to do that.

9 MR. DICKSON: It was suggested that I should
10 give you the bottom line, that it is physically designed
11 so that it cannot input more than 60 cents, which is the
12 design basis event. But that's a whole day's story
13 before you believe that.

14 (Laughter.)

15 MR. CARBON: We will welcome that whole day's
16 story.

17 (Laughter.)

18 MR. LIPINSKI: Your roller nut system operates
19 in a gas, is that right?

20 MR. PITTERLE: Yes. It's an argonne fill gas,
21 not separated from the cover gas by bellows.

22 MR. LIPINSKI: The point I would like to make
23 is the spring mass system has very little. All I have
24 to do is hit the excitation frequency and I get full
25 amplitude of that response. That goes back to the

1 conversation before. All you have to do is find out
2 what the excitation force is.

3 MR. ZUDANS: I would like to continue that
4 line. I do not visualize exactly how the details fit
5 together, but I assume those springs preload the balls,
6 right?

7 MR. PITTERLE: The springs will push it apart
8 upon loss of magnetic field.

9 MR. ZUDANS: The magnetic field pretty well
10 loads the balls against the magnetic springs.

11 MR. PITTERLE: The preload collapses the
12 springs.

13 (Slide.)

14 This is a picture of the basic features.
15 Mounted externally to the rotor part of the mechanism is
16 the motor tube and then the stator outside that. You
17 have the picture right there. A motor tube and a
18 stator. You apply electrical power to the stator,
19 providing that magnetic pull that is pulling the upper
20 end of these two segment arms, pivoting about these
21 pivot pins and engaging these rollers into the lead
22 screw.

23 The segment on springs that we are talking
24 about are shown here. There are two pairs, then there
25 are another two pairs on the back side, so that you have

1 the -- and each of them is a pair of springs so there is
2 a total of eight springs capable of pulling it apart.
3 It will, in fact, not seismically test it, but in the
4 normal scram it will scram even without the segment on
5 the springs.

6 MR. ZUDANS: So there is actually a positive
7 compression because of the magnetic item?

8 MR. PITTERLE: Yes. If you lose power, you
9 will push the lower ends of the segment arms and you
10 push the rollers out from the lead screw.

11 MR. ZUDANS: You actually then could not
12 develop anything like a free vibration if it is not
13 free. You would have to overcome the compressive force
14 before it gets free to begin with.

15 MR. PITTERLE: Right.

16 MR. ZUDANS: Except that for the upper portion
17 of those arms that have some elasticity about the pivot
18 point.

19 MR. PITTERLE: Not really very much. They are
20 pretty massive. I don't know exactly the size. This is
21 pretty rigid about these pivot points. I agree with you
22 in principle but I do not think they are very sensitive.

23 MR. ZUDANS: It is not a high frequency?

24 MR. PITTERLE: It is pretty well a hollow
25 cylinder of some five inches in diameter hollowed out,

1 and it is a pretty massive structure.

2 MR. ZUDANS: At any rate, the arms don't touch
3 anything; they are sitting in a magnetic field free, so
4 that is your spring mass system. And the other is
5 essentially rigid at that point in time.

6 MR. PITTERLE: That is correct, with this
7 being a very stiff member and held out against -- there
8 are some stops. It is pulled out as -- I forget the
9 terminology for it, but there is like guides that will
10 bring the two segment arms into synchronous positions so
11 that they do collapse and move out synchronously with
12 each other.

13 So you are really holding them out against the
14 flange and the stop up at the upper end, and you are
15 holding it against that. It is not really hanging there
16 loose to flap around. You are pulling it out until you
17 engage in that synchronous bearing at the top, so it is
18 not free to flap per se.

19 MR. LIPINSKI: What happens if you have a
20 porous excitation in the direction of the axis label
21 magnetic pull? One-half goes out and one-half goes in?
22 Are they mechanically interlocked so that they have to
23 be out and in together, or can I have them synchronously?

24 MR. PITTERLE: That is the purpose of the
25 synchronous bearing. They are free to rotate if I

1 release a field.

2 MR. LIPINSKI: What you just described was a
3 limit stop of out and in. When they come in, they are
4 touching each other effectively. When they go out they
5 are separating, so you don't have that mechanically
6 interlocked to synchronize them, to separate and come in
7 together.

8 MR. PITTERLE: I am not sure we are quite
9 picturing it the same way.

10 MR. LIPINSKI: Can I have one pushed in and
11 one out simultaneously?

12 MR. PITTERLE: No.

13 MR. LIPINSKI: How do you prevent one from
14 going in while the other is coming out?

15 MR. PITTERLE: Well -- okay. I guess in
16 theory it is possible, yes. But the fact is the springs
17 are tending to push both of them out, and then they are
18 both guided so that they come in. I can't quite see the
19 failure mode that would have coming in and one going out.

20 MR. LIPINSKI: The excitation along that
21 magnetic pull axis.

22 MR. PITTERLE: I don't believe if the design
23 basis is right, this is going to overcome this
24 excitation, even if it were along this direction. You
25 are saying along this direction?

1 MR. LIPINSKI: Right.

2 MR. PITTERLE: The springs are design basis so
3 that they will take account of any of that excitation
4 and then force them out with time to spare.

5 MR. LIPINSKI: At what frequency?

6 MR. PITTERLE: That I don't have the answer to
7 right off, as to what frequencies have been looked at.

8 MR. LIPINSKI: Because again, you don't have
9 any damping in that system. It is strictly spring mass.
10 If I get the excitation frequency it will take very
11 little force to get those halves to slam back and forth,
12 unless there is something in there that prevents them
13 from being non-synchronized. And I don't know what is
14 in your mechanism that would cause them to have to be
15 synchronized or separated or pulled in together.

16 MR. PITTERLE: Yes, except that with that
17 force -- it is a pretty rigid system. I don't know the
18 answer, but I suspect the frequency is high enough that
19 it is not of concern. But I am speculating.

20 MR. TRIFUNAC: What is the strength of the
21 magnetic pull? Do you know the force level?

22 MR. PITTERLE: No, I don't know offhand. I
23 don't have that number.

24 MR. ZUDANS: Could you describe how it
25 functions normally? What drops? The lead screw drops?

1 MR. PITTERLE: Yes. When you scram, you are
2 pushing the rollers out from this lead screw. The lead,
3 screw, which is in this point, is located above the top
4 of the reactor head. The lead screw of that drive line
5 connects it to the in-core control rod, and all of that
6 is scrambled in the primary system.

7 MR. ZUDANS: When you want to move it out,
8 what do you do?

9 MR. PITTERLE: You engage the rollers and then
10 you pulse the fields of the stator.

11 MR. ZUDANS: This is what rotates them?

12 MR. PITTERLE: Yes. The lead screwup, and
13 that is key to the that is it is all rigidly modeled
14 into the mechanism part. I will briefly give you a
15 picture of the overall part of the mechanism.

16 The upper mechanism -- what we were looking at
17 before is essentially just this bronze-colored section
18 (indicating).

19 (Slide.)

20 This extension nozzle is mounted rigidly to
21 the closure head. The motor tube shown coming down in
22 here is mounted by a hold-down ring. The nozzle and the
23 stator is mounted over that, and clamped to the nozzle
24 with the hold-down clamp. So this is the part you are
25 releasing when you are reacting your forces through the

1 nozzle.

2 MR. ZUDANS: That means that the flat part can
3 go in in any position when it is rotated? It can stay
4 in any unknown position?

5 MR. PITTERLE: Yes. It is 15 degrees, I think
6 15 degrees position is possible to get the time to steps
7 that we are trying to get. It is a very small step,
8 .025 inches per step vertical motion. I think it
9 corresponds to 15 degrees stator rotation. Field
10 rotation.

11 Are there any other questions?

12 MR. ZUDANS: Do you have similar pictures for
13 the other systems?

14 MR. PITTERLE: Only to show how the -- well,
15 let me perhaps give you a general schematic of the other
16 system first.

17 (Slide.)

18 Although it is in the cartoon type pictorial.
19 This is a core assembly, the reactor closure head. Then
20 everything that is between the reactor closure head and
21 the bottom of the upper internal structure is cut away.
22 It is a twin ball-nut drive mechanism. The carriage and
23 then the solenoid that we just pictured, the piston and
24 valve solenoid is shown schematically here, mounted to
25 that carriage. We have over-simplified it here.

1 There is a very slight motion of this piston,
2 about a quarter inch motion of this piston where the rod
3 releases the latch in the secondary system which is
4 located within the control assembly itself. It is
5 contrasted to the primary, where the whole translating
6 assembly is going its full 36 inches.

7 During the scram the latch function here
8 releases the latch and the whole control assembly
9 travels 36 inches. The assembly is designed to give a
10 fluid or hydraulic assist to the downward motion to
11 assist the scram insertion into the core. The latch is
12 shown in somewhat more detail over here. It shows the
13 tension rod coming down the middle. A sensing tube that
14 indicates coupling to the structural member of the drive
15 shift.

16 This piston then permits loss of pressure to
17 the piston and permits this latch to open up and release
18 the control rod coupling head and lets the assembly
19 scram into the core. So all the 36-inch stroke of the
20 core is within the core region itself.

21 Just to orient you a little bit now with that
22 upper mechanism part, the scram valve cylinder -- this
23 elevation here --

24 (Slide.)

25 -- is about elevation 80 above the top of the

1 head. We have the shielded seismic support that comes
2 in, gives the general location would go up to on the
3 order of 70-some inches. The cylinder is located here
4 (indicating). The three solenoid valves. And this
5 shows the tension rod. This piece through here is what
6 we had the actual picture of, previously shown. It is
7 supported off the carrier rod, rotor tube, and the
8 support rods are shown here. It is off the support tube
9 from the carriage up to the location of the cell.

10 That is about all I have in terms of detail.
11 This at least gives you a general orientation of where
12 it is in the reactor.

13 MR. ZUDANS: It gives an idea of the level of
14 complexity.

15 MR. PITTERLE: Any other questions?

16 MR. SWITICK: Thank you, Dr. Pitterle.

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1 MR. MALLET: Mr. Pitterle has talked. I am
2 Bob Mallett. I am going to address that same topic more
3 specifically for the case of the heat transport system
4 components.

5 These are the questions that I will address.

6 (Slide.)

7 The first is: what is the arrangement of the
8 HDS? Here I will remind you of what it contains and
9 mention some of the parameters of the heat transport
10 system. Then I will identify some of the conventional
11 conservatisms that are in the seismic design process
12 that Mr. Morrone spoke about earlier today. Then we
13 will consider a review of a portion of the information
14 that is on the docket on seismic margin capability.
15 Then I will turn to the two most important ones here, I
16 believe. We will consider some of the differences, some
17 of the specific attributes of the CRBR plant. And
18 last, the development, the verification, the
19 coordination that has been done to be sure that there
20 are no oversights.

21 Based on the review of this material, it is
22 our judgment then that the seismic safety levels for the
23 Clinch River plant and the light-water reactor
24 components are comparable. This is based on the
25 observation that where things are commop, they are

1 handled similarly, and where things are different, that
2 difference tends to be one of strength rather than of
3 weakness.

4 (Slide.)

5 This is from the design lab showing of the
6 plant. It shows a plant inside the three-loop for
7 containment. This is the reactor vessel with a 36-inch
8 diameter pipe that goes around the loop to the primary
9 pump in the hot leg.

10 Here is what we call the crossover leg that
11 goes from the pump to the IHX and the cold leg then
12 returns the coolant back through a check valve in the
13 cold leg back through the reactor vessel.

14 Two additional runs of ppe that you see here
15 are the cold leg, which brings the coolant in through
16 the IHX and the hot leg, which takes it back through
17 containment penetration.

18 (Slide.)

19 The equipment that is inside containment is an
20 inerted cell. I have included this vuegraph because it
21 gives a clear indication of one of the principal effects
22 of temperature on the arrangement of the plant. What
23 you see here along the edge is where the coolant exit
24 containments in the hot leg, it comes down here, it has
25 one expansion loops, three expansion loops, goes into

1 the steam generator building, and another expansion loop
2 there where the corresponding cold leg which is bringing
3 the coolant back to containment has a single expansion
4 loop.

5 So there is, as I say, a clear indication of
6 an effect of temperature of the plant where the
7 temperature ranges are large pipe thermal piping
8 expansion loops are long.

9 These are parameters for a typical loop in the
10 plant.

11 (Slide.)

12 Temperature is about 1000 degrees for
13 structural evaluation. This is about a temperature that
14 brings creep into play in a substantial way. Creep
15 begins to play a very important role.

16 You can also see a 24-inch diameter
17 half-thickness is the size of the pipe. In fact, the
18 size of much of the pipe that we have in the main heat
19 transport system is 24-inch diameter pipe with about a
20 half-inch wall.

21 That half-inch wall is thin. It is permitted
22 to be thin by the fact that the plant is a low-pressure
23 plant. That again is a key attribute or characteristic
24 of this plant relative to, say, a light-water plant.

25 (Slide.)

1 The low-pressure condition gives us a low
2 sustained primary stress. Low pressure comes into play
3 also in connection with the components, not just the
4 piping. Here is a long, slender component about 12 feet
5 in diameter and about 50 feet long. Normally, the wall
6 thickness in this component is about an inch and a
7 half.

8 The component is top-supported type supports
9 to the building, carefully engineered, down through this
10 cone to the shell. The design of the support is for
11 stiffness, and one thinks of the available margins for a
12 strength-type loading.

13 It is useful to observe here the nature of the
14 seismic-induced response under seismic loading. One can
15 imagine a wag-type motion of this component. When that
16 happens, two things come to mind. One is that the way
17 the component is challenged is by a buckling, bending,
18 buckling type load in this upper cone. In this
19 particular configuration, it is a failure mode that is
20 not particularly catastrophic.

21 Another noteworthy aspect of that wagging-type
22 behavior would be the nozzle motion. So you have
23 displacement imparted from the nozzle to the piping
24 characteristic of the top-mounted component.

25 (Slide.)

1 Let us look more at the piping. One's
2 reaction in looking at this piping as it, say, exits the
3 reactor vessel here for the pump, it is not a short
4 straight run, it is a long and circuitous run. In order
5 to provide the thermal expansion loop.

6 Given that the piping is 24 inches in diameter
7 and a half-inch thick and it is relatively long, one's
8 first impression can be that the piping is a vulnerable
9 component in this type of a plant. Because of that
10 first impression, in going through here, I will use
11 piping principally as the example in illustrating that,
12 in fact, that is not the case, that the flexibility in
13 that piping is a beneficial attribute because it is
14 long, though the supports of the piping become very
15 important. We have more of them because the piping is
16 long, and the response of the piping system is very much
17 an integral response of the supports in the pipe.

18 In view of that importance of the supports,
19 they very carefully engineered items on this type of a
20 plant. You can see here a typical support configuration
21 for main piping. The pipe itself is a cross-hatch
22 part.

23 The green I colored in is a load-bearing
24 installation. It is kind of a pad between the pipe and
25 the clamp. The clamp itself runs cold.. The two halves

1 of the clamp are held together by Bellville washers.
2 They are springs essentially to hold the two halves
3 together.

4 So the stiffness design component and it, too,
5 has reserve strength.

6 One of the aspects that is interesting is
7 illustrated by this load displacement plot in this upper
8 corner under extreme loadings, one can see that this
9 curve bends over at events beyond the design basis.
10 There is a softening here that corresponds to a pulling
11 away of one clamp half of the other under extreme
12 loading. Under all design bases conditions, the pipe
13 clamp stays snug to the pipe. Actually, we have gotten
14 pretty good at designing clamps like that.

15 We then tested them to the point where the
16 German reactor were designed here in this country.

17 Based on that overview, a reminder of what the
18 components in the plant look like. It is our conclusion
19 that the seismic design problem is essentially the same
20 except for the differences due to higher temperature and
21 pressure. Due to higher temperature we see longer
22 piping runs. We see top-mounted components. Due to
23 lower pressure we see thin wall.

24 (Slide.)

25 Let us move to the second question that I

1 indicated we would address; that is, do the seismic
2 methods and criteria that we use include the
3 conventional conservatisms? To illustrate that they do,
4 we will look at models. We will look at the methods and
5 at the criteria.

6 MR. ZUDANS: Bob, before you finish the talk,
7 may I ask you a question? You showed those clamps. You
8 said they showed the load displacement diagram. That
9 was intended to be for the clamp motion, the
10 displacement diagram, where it gets softer as it goes
11 by?

12 MR. MALLETT: Yes.

13 MR. ZUDANS: At what point will the pipe wall
14 collapse?

15 MR. MALLETT: Pipe wall will not ever
16 collapse.

17 MR. ZUDANS: It probably will buckle it, say?

18 MR. MALLETT: Well, we can overload it,
19 certainly. What we do is we design the wall of the pipe
20 like we were designing a vessel. We take care of the
21 detailed stress distribution under that clamp. And it
22 is that detailed design according to the stresses and
23 strains under the clamp that set the load gradient for
24 the plant.

25 So we have designed it essentially like it was

1 a vessel wall, and then we go test it at SSE levels.

2 MR. ZUDANS: So you have tested it at SSE
3 levels?

4 MR. MALLET: Yes.

5 MR. ZUDANS: So your plant would be the one
6 that would open -- reach the design limit before the
7 pipe begins to collapse inward?

8 MR. MALLET: That is true. Beyond the SSE,
9 beyond clamp load ratings, what you would find is the
10 forgiveness of the springs and bolts, yes.

11 (Slide.)

12 This is the portion on the conventional
13 conservatisms. What I have shown here is the seismic
14 model. What you see when you look at this one is one
15 just like every other one you ever looked at for
16 piping. The piping model is constructed of a string of
17 finite elements, straight and elbow elements, that make
18 up the piping system itself. It is connected on its
19 ends to STIKK model, the components, and it is supported
20 along its length by seismic snubbers or elastic rods at
21 various locations.

22 In fact, we use the same computer program for
23 Westinghouse that is used in the design of our
24 light-water plant. So the differences in the number of
25 elbows that you see and the thermal expansion loop in

1 the pipe perhaps and the number of supports.

2 MR. ZUDANS: Bob, on this model, where the V
3 model, the pipe connects the RV model. What do you do
4 for that local load? This is relatively hard pipe in
5 that direction.

6 MR. MALLETT: That is right. We have a local
7 flexibility for the shell.

8 MR. ZUDANS: You have it?

9 MR. MALLETT: Yes, we do. We pay a lot of
10 attention, Dr. Zudans, to the supports in this piping.
11 These are springs and local shell flexibilities. There
12 are other things because it is such an integral part of
13 the response.

14 MR. ZUDANS: So it is really not necessarily a
15 linear model completely? Or is it linear? Or you do
16 not go to high deformations?

17 MR. MALLETT: Generally, it is linear.

18 MR. ZUDANS: I presume that this pipe goes
19 into a vessel. The vessel is what is threatened, not
20 the pipe.

21 MR. MALLETT: Oh, no, no.

22 MR. ZUDANS: Not so?

23 MR. MALLETT: No.

24 (Slide.)

25 Elbows in the pipe do not permit you to

1 exercise a vessel nozzle.

2 MR. ZUDANS: And supports do not stop the pipe
3 from moving, right? At least that is an assumption that
4 the support allows the pipe to move axially at that
5 point?

6 MR. MALLETT: That is true. It is engineered
7 that way, and there are things like guard vessels around
8 many of the components that require that the supports be
9 backed off behind an elbow.

10 MR. ZUDANS: And these legs are short, the
11 legs next to the vessel are short?

12 MR. MALLETT: Yes. Especially in the primary
13 system where there is a guard vessel, you have to come
14 out and go up.

15 Continuing on the conventional conservatisms
16 motion, here is one I call to your mind. The actual
17 data carries you around a curve such as is indicated in
18 green here, and the area inside that curve is a measure
19 of the damping in the design of the piping we wish that
20 damping out in design and neglect that damping, adding
21 then into the process a conservatism that is especially
22 important for the LMFBR plant where we tend to have a
23 lot of snubbers on the run of pipe.

24 (Slide.)

25 That was a review of the models. This looks

1 at loads. Here again it is a very familiar process.
2 There is a calculated response spectra, say, at the
3 center of the building up at the support elevation.

4 Now, in the case of piping where the supports
5 for that piping are at different elevations and at
6 different locations from the center of the building, we
7 would superimpose on a plot like this the spectrum that
8 applies at each of those snubber supports and then the
9 spectrum used in the design and applied at every support
10 is the envelope spectrum. So there is another
11 conservatism that is customarily embedded into the
12 piping design analysis.

13 MR. ZUDANS: Do you really believe that that
14 is strictly conservative? I do not know the answer, so
15 do not be too hesitant. If you take different point
16 supports and have their own spectrum generated, do you
17 turn around and say, I am going to use single-input
18 spectrum now for all support points because that is what
19 is simpler to do in terms of analysis? And even if you
20 took the envelope, I am wondering whether that would be
21 a conservative result. It has never really been proven,
22 but that is the way it has always been done. And it is
23 bigger, but it is the same at every point.

24 MR. MALLETT: Yes. But you are not using time
25 phasing in the sense that you took a time-history

1 analysis and made them all the same in phase. Then
2 perhaps this might not be conservative.

3 MR. ZUDANS: Maybe we will talk about that
4 some other day.

5 MR. MALLET: Yes. We worry some about that.
6 There are various things a person does from the
7 selection of the snubber down through preoperational
8 testing, in-service testing, and additionally at this
9 stage, some evaluations. And we have done some. What
10 we find is some snubber failures can be postulated
11 fail-free.

12 The integrity of the pressure boundary is not
13 really challenged. That is a beyond-design base
14 condition using nominal limits rather than lower-bound
15 allowables. But for a nominal evaluation for that
16 nominal condition, it is not catastrophic; we can
17 accommodate it. I will show some things a little later
18 that will tend to explain why that is the case.

19 (Slide.)

20 In addition to those things on loading, we
21 followed the practices mentioned by Mr. Morrone for
22 accumulation of the various modal contributions and
23 accumulation of the directional responses as well. This
24 is the third leg of the thing of the things to review
25 under the conventional conservatism's notion.

1 This is one that was mentioned this morning
2 that is worthwhile repeating here. What we are looking
3 at here is a table where for the OBE limit enough
4 snubbers have been placed on the pipe to bring the
5 primary stress on this 36-inch hot leg in under the
6 allowable. Here is the allowable 19.44. Enough
7 snubbers are in place to bring it down to 5 percent
8 below its allowable.

9 Once you have done that, in satisfying the OBE
10 stress limit condition, you can look across here on the
11 other pair of columns and see what that has done for you
12 regarding the SSE. A 5 percent margin embedded in the
13 design here results in a 45 percent margin for the SSE
14 level of earthquake. So here is the specific numerical
15 illustration.

16 MR. ZUDANS: Is that 15? Is that a yield
17 point at that temperature?

18 MR. MALLETT: No, that is above. That is
19 above. That would be room temperature.

20 MR. ZUDANS: Room temperature.

21 MR. MALLETT: But this is not a room
22 temperature calculation.

23 MR. ZUDANS: It is above the fuel point?

24 MR. MALLETT: It is above the fuel point.

25 This is where we have come to, with the

1 conservatism. We have said components. We have had
2 components that were not strange. We have used methods
3 that were customarily used, and here the methods and
4 criteria include the conventional conservatisms to the
5 point of using the same computer programs.

6 Now, the next area that I would like to
7 suggest that we step past, what it says is this. The
8 question is: do we have inherent size margin
9 capability? The components are familiar, the methods
10 are the same.

11 What we have on the docket is a generic type
12 of evaluation that says nominal yield stress is 25
13 percent above minimum yield stress, and considerations
14 such as that lead us to a -- we step to a process that
15 leads us to a conclusion that we should have about the
16 same margin from this type of evaluation that any other
17 structure designed using the same methods and criteria
18 would have.

19 (Slide.)

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1 If I do step past that question, because it
2 really does not add any light on what has been said here
3 previously today or add any information on the docket
4 either, then that will bring me down to the question
5 what are some of the things that are peculiar to the
6 LMFBR type of plants that warrant mentioning in
7 considering the tolerance of this plant for extreme
8 seismic events?

9 Here I would like to look at three things,
10 look at loadings, flexibility, and consequences.

11 (Slide.)

12 MR. MALLETT: This is a viewgraph that I have
13 included to make the point with respect to loading. The
14 point is that there are other loads in the plant that
15 often are the determining basis for design. In the case
16 of the piping, we look here at the intermediate heat
17 transport system piping. The basis for design of this
18 piping for this type of a dynamic event is more the
19 sodium-water reaction, SWR, than it is the SSE. To
20 illustrate that, what I show here is a number of support
21 loads on the intermediate heat transfer system, hot leg
22 piping. What is noteworthy here is this: at the -- in
23 the first row, a snubber which happens to have a 201 has
24 the maximum reaction of any support location on that
25 piping, 60,000 pounds. At that location the

1 corresponding SSE load is 21,000 pounds.

2 If we look down at a different point along
3 that same leg of pipe, the maximum SSE load that occurs
4 anywhere is, say, 30 pound load at that point, the
5 sodium-water reaction load is 45,000 pounds. So it is
6 the nature of the plant and its conditions that lead to
7 loadings other than the SSE to be the determining factor
8 in the design of much of the equipment.

9 Now, this happens to be the intermediate heat
10 transport system. Essentially the same thing is true in
11 the primary heat transport system where in that case the
12 water hammer type of event that is evaluated is the
13 HCDA, or water we call the SMBDB. The water hammer
14 event meets the larger loads than does the SSE.

15 (Slide.)

16 MR. MALLET: Now, this is the point that I
17 found difficult to say, but it is a very important one
18 and it is worthwhile, my having a go at it. It has to
19 do with the flexibility that is inherent in this piping
20 and the capacity of that piping to accommodate
21 deformation. I have to begin here. Remember, in the
22 ASME code we had what is called a primary stress which
23 is the type of stress that can fail with one application
24 of the load. And we often also talk about the secondary
25 stress where it is not a single application but it is

1 cyclic loading that causes a problem.

2 I have illustrated that here below. Here is
3 the primary stress case on the left. Suppose we have a
4 beam. Suppose that stress on that beam is about the
5 yield stress. So there is a primary load situation.
6 The secondary load situation would be where you push the
7 tip of the beam down one inch. You do the same
8 analysis, you calculate that you have a reaction that
9 would rise. It would be ten kips, and the stresses here
10 on the beam would be the same. This is a load control
11 situation. It is a dead weight. It leads to a primary
12 stress. It is just a displacement control situation
13 that leads to a secondary stress.

14 The difference is when you are asked the
15 question what if you are wrong? Suppose you are 50
16 percent wrong? If you are 50 percent wrong in this
17 case, the load is actually 15, then you can go to
18 collapse. If you can go to immediate collapse of this
19 beam.

20 Over here, if you are 50 percent wrong in what
21 that displacement was and it is actually down an inch
22 and a half, the reaction is up a little bit, but you
23 really have not failed the beam.

24 Inelastic deformation in the structure does
25 not relieve a primary stress. It does relieve the

1 secondary stress. The significance of this is that the
2 seismic stress limits that we design to in the ASME code
3 are set assuming seismic stresses are primary stresses.
4 You see, the stress limit, you can go to collapse in a
5 single application. The fact of the matter is it does
6 not really work that way, especially in the LMFBR case
7 where the piping is a very highly redundant structure.

8 (Slide.)

9 MR. MALLETT: This kind of illustrates the
10 same point. I think it is worth showing it also. This
11 says this is a load versus displacement type plot, but
12 you could think of it as stress versus strain. Let's
13 say the material is initially elastic. We will take it
14 right past the elastic limit, and we come up here. Once
15 we arrive at this point, then we can see this is due to
16 the fact that the material is really nonelastic. It
17 exhibits inelastic behavior, plasticity.

18 We could move off in this direction, then we
19 see it is very important to provide a substantial margin
20 here because the primary stress would be carried to
21 failure. If we admit to plasticity, we come down that
22 line, that is what happens if it is a displacement
23 control situation or secondary stress.

24 This is the kind of thing that happens in the
25 LMFBR pipe. It tends to come down in this direction due

1 to an inelastic deformation in the piping. Don Landers
2 of Taledyne mentioned in a report recently that in his
3 experience he has seen cases where elastic calculations
4 would carry you to five times the design limit and yet
5 on inspection of the pipe, after the event, there is
6 only moderate inelastic deformation. The redundancy of
7 the pipe and its flexibility gives it a remarkable
8 capacity for shedding load from the high load region to
9 the low load region.

10 Let me carry this a little bit further. This
11 is test data for an elbow of the type that we used.

12 (Slide.)

13 MR. MALLETT: In our piping, an elbow is about
14 20 times more flexible -- that's not always the case.
15 Let me take a specific leg. The 36 inch hot leg out of
16 the reactor vessel, the length of the pipe and the
17 elbow, what that means is that all of the deformation
18 occurs -- all of the deformation occurs essentially in
19 the elbows. The straight sections aren't challenged.
20 They are not severely stressed. So the way the
21 deformation takes place, then, we collapse a single
22 elbow in the test here, versus a change in the angle of
23 the elbow.

24 Here is the OBE limit. Here is the SSE
25 limit. Up here is the actual collapse load. So there

1 is this enormous margin that is built into the process
2 because it is a primary stress.

3 If you look up here at the collapse load, what
4 you find is the strain, even at that level, is only
5 about a 1 percent strain. The nature of the deformation
6 is a relatively benign deformation. Here we have taken
7 an elbow that we have collapsed. This is a 16 inch
8 diameter, I think. We have collapsed this elbow.

9 (Slide.)

10 MR. MALLETT: You can see the way the piping
11 system performs is that the cross section of the elbow
12 is ovalized. The straight pipe really doesn't get bent
13 a lot. The flexibility is in the elbows.

14 (Slide.)

15 MR. MALLETT: The important thing is that an
16 elbow like that be able to accommodate a lot of strain,
17 and in fact, it can. As I said, here at the peak this
18 is only about 1.2 percent strain. It is already at a
19 change in angle of 4 degrees, so you must imagine you
20 have two long straight sections of pipe. The elbow is
21 changing four degrees, or out to the right 8 degrees.
22 There is implied in that enormous motion down at the
23 other end of the straight section, and it really can't
24 happen that way.

25 When you get into large motions like that and

1 these beyond design basis accidents I am imagining here,
2 you will run to the limit on travel in snubbers and
3 hangers and such things. So for the beyond the design
4 basis accident, there are mechanisms there that provide
5 for shedding of loads.

6 MR. CARBON: Would you put the other elbow
7 back up there?

8 I didn't have time to really study that.

9 Would you go through again what I should get
10 out of that picture?

11 (Slide.)

12 MR. NALLETT: What I would like to have you
13 understand from this is that the fairly benign nature of
14 the deformation that has to take place in the piping
15 system, it is not a question of bending the straight
16 piping section. What large displacement of this piping
17 system leads to are simply polarization of the cross
18 section, and in this case it is a complete collapse,
19 ovalization for purposes of illustration, but even at
20 OBE levels for dead weight stress, the nature of the
21 deformation of these piping systems is one of
22 essentially ovalization of the elbows in order to
23 accommodate the motion from straight pipe.

24 MR. ZUDANS: Bob, the other picture that you
25 showed, the low angle curve, it really didn't mean that

1 the walls collapsed, just that the load capability in
2 bending reduced because of the ovalized cross section.

3 MR. MALLET: Yes.

4 MR. ZUDANS: You still had the low passage in
5 the elbow. It wasn't closed off.

6 MR. MALLET: Oh, yes. This is after the test
7 of what we call an elbow collapse. This is what it
8 looks like. This is far removed from any actual design
9 basis type load.

10 MR. KASTENBERG: I have a question.

11 The comment you made before about the long run
12 of pipe, does that argue then for having a more flexible
13 piping system with less snubbers in it and letting
14 piping take up in a large earthquake, taking up energy
15 via an elastic deformation?

16 MR. MALLET: We have a very flexible piping
17 system here, and the nature of the behavior is one which
18 shedding loads to snubbers which are down in the
19 straight sections and that works well. I think that is
20 a beneficial process.

21 MR. ZUDANS: I think your advantage is derived
22 from the fact that you have large diameter, thin wall
23 pipe. If you took the large diameter PWR pipe, there
24 are much thicker diameters. While they still have the
25 same tendency to ovalize, but they are much thicker, so

1 in response to your question, this is correct. It is
2 reasonable for more flexible piping, and it is not
3 unreasonable to think of that for LWRs as well.

4 MR. MALLETT: I had some points I wanted to
5 make here on special attributes. The load
6 flexibility -- this was one I have called consequences.
7 Here the attribute I want to talk about here for a
8 minute is the failure of the piping is not
9 catastrophic. We have done testing such as that
10 indicated here. This is a straight section, an elbow
11 and a straight section. We have applied a moment to
12 that elbow by changing the length here, and we got an
13 initial defect in that elbow, and then we pump up the
14 internal pressure to cause a failure to occur.

15 Now, I will show you next the figure for the
16 failure looks like for the case of the 16-inch diameter
17 elbow. This is the most highly stressed region. We cut
18 a through-wall crack there equal to the length of about
19 the diameter of the pipe, a 16-inch diameter pipe, a
20 16-inch through-wall pipe. We put a bladder through
21 that pipe and then pressurized it up to a pressure that
22 is twice the design pressure present, and the cross-over
23 leg in this piping, this is what the failure looks
24 like.

25 (Slide.)

1 MR. MALLETT: That is, it is such a low energy
2 system that it is just not possible even for these thin
3 wall pipes to open up the crack. This is the initial
4 crack. No extension of the crack occurred, and we could
5 not get it open more than about that much and still keep
6 it sealed at twice the design pressure.

7 So the low energy system does not give a
8 violent destruction with the failure and of course does
9 not leave any system dryout because it is below the
10 flash point of the coolant.

11 (Slide.)

12 MR. MALLETT: We have studied that process a
13 good bit. We have been here before and presented what
14 we called our piping integrity activity. It included
15 the tests I just showed you, and it included the three
16 tier process. First we looked at ASME type evaluation
17 of the piping. Then we postulated flaws in the piping,
18 worse case location, orientation, such things. We tried
19 to see what would happen to that flow when the duty
20 cycle was applied to the plant. The answer is almost
21 nothing. The cracks don't grow for the combination of
22 conditions that we have and the material that we use,
23 almost negligible cracks.

24 Then we add a third layer on this evaluation
25 of the integrity of the piping where we set aside the

1 duty cycle of the plant and force the crack to grow.
2 When we did that we found that the crack penetrated the
3 wall at a fairly short length of pipe. A part of this
4 last activity here was a test that I just showed you.
5 Even when we took the pipe, put a very long crack in it,
6 tried to open up an abrupt, large hole, it just does not
7 happen. The energy is just not there.

8 So from the picture that I showed you and your
9 arguments that are on the docket with respect to these
10 activities, we conclude that abrupt gross failure of
11 this piping is not credible, and that is a noteworthy
12 attribute of this type of system.

13 (Slide)

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1 For this segment, then, I conclude that the
2 Clinch River plant is designed to beyond the design
3 basis.

4 MR. ZUDANS: Bob, did you ever experience an
5 indication of buckling collapse in the compression zone?

6 MR. MALLET: The pipe is not that thick. It
7 is thin compared to the light-water plant, but if I
8 would bring a piece here --

9 MR. ZUDANS: It is half an inch thick. We can
10 visualize it, right? So it is not paper thin.

11 MR. MALLET: That's right. It is heavy. You
12 saw reaction loads of 60,000 pounds of pipe out of this
13 strong pipe.

14 MR. ZUDANS: You do have strong relative
15 motion. Supposing you just inconveniently selected
16 support that froze up on you, and you had to go several
17 inches. Did your test reach that kind of arrangements,
18 or do you have such geometric configurations?

19 MR. MALLET: We tested the geometry, both
20 short-term loads and in fact creep tests. The only
21 buckling that occurs for the parameters that are
22 relevant here is the ovalization. That is all we see.
23 They are just not thin enough to get us down to the
24 interesting piping problems.

25 (Slide.)

1 MR. MALLET: What special things have we done
2 in view of the fact that this does not have the
3 extensive prior operating history of a reactor? Well,
4 we have done a number of things. We have done things in
5 the development area, in the verification area, and in
6 the coordination area, and let me mention some of
7 those. I have come back here to the clamp case again
8 because supports are so important. This is a plan view
9 of the section of pipe. This is a 24-inch diameter
10 pipe. It is full scale tests where we put a piece of
11 clamp on the pipe. We insulate the pipe. We snub it to
12 ground, and put three thrusters against it. This is
13 really all the horsepower we had to put against that.

14 We took that to temperature and seismic
15 loadings, and simultaneously we took it through
16 temperature changes and seismic loading. This is an end
17 on view of essentially what the plant looks like. I
18 have a photograph of the test setup that takes this
19 view. From such developmental programs as this, various
20 kinds and many in number in this program, we have
21 established the integrity of the important pieces. This
22 we took through a number of SSE's. We took it apart,
23 inspected it for damage, and it wasn't damaged, and that
24 has helped us to qualify the clamp. This is looking
25 back over the three thrusters. This is a pipe and here

1 is the plan.

2 (Slide.)

3 MR. MALLET: This is an example of the type
4 of developmental testing that had been done as a part of
5 this program. It has been done not only on the large
6 clamp, but also on the small clamps.

7 (Slide.)

8 MR. MALLET: This is more of the same
9 development type confirmation of what we are doing.
10 This is representative of a one scale third of the cross
11 over pipe between the pump and the IHX. We have been
12 very careful in this test to design prototypic supports
13 along this piping, and have a prototypic thinness in the
14 pipe. We will be subjecting this this summer to a
15 seismic load to confirm that what we are doing in
16 representing this thin wall pipe and its associated
17 piping hardware is an adequate model and an adequate
18 method.

19 Now, with respect to -- I guess the difference
20 between verification and in the actual plant, this is
21 the HDRD contamination project that led to a number of
22 seismic -- a number of vibration studies of the piping.
23 We have pulled these two results from that too as an
24 additional confirmation that the methods we are using
25 are getting the job done. If we look at frequencies for

1 one of the legs in this plant, for one of the three
2 modes I have shown here, what is measured in the field
3 is in the same ball park as what is protected, or vice
4 versa, perhaps I should say.

5 So, for these loads down at these frequencies,
6 the correlation between analysis and test is pretty
7 good. If you look in terms of peak acceleration
8 response at a place along the pipe due to this
9 excitation, this particular case was a charge set off
10 outside the reactor in the ground. We have ordered here
11 the test measurements along this piping leg from the
12 maximum value to the smallest value, but what you want
13 to look at is in this region where the response is the
14 highest. How is the correlation between the analysis
15 and the test? It is pretty good.

16 Here, where the responses are strong, the
17 correlation is good, and where the correlation is less
18 accurate, plates out here, plates out here, the analysis
19 is usually more conservative than the test. The
20 analysis is conservative relative to the test, I should
21 say, so this is a confirmation of an actual light-water
22 reactor hardware. The methods that we used are
23 reasonable.

24 Now, this is a verification that has been done
25 for the FFTF plant on the cross over pipe, that is, the

1 pipe between the pump and the IHX. The excitation in
2 this case is the pump itself. The question, of course,
3 is whether or not the natural frequencies that are
4 predicted are close to those that are observed in the
5 plant. Well, for the zone of pump speed that is shown
6 across here, one can see a peak of 12.4 and another peak
7 down here at 12.0, and 15.0.

8 The frequencies predicted for that pump are
9 very close to the frequencies actually observed in the
10 plant. This is for the FFTF.

11 MR. CARBON: These analyses were done with the
12 pipe filled with some fluid? Because you have to have
13 that.

14 MR. MALLETT: Yes, yes, you have to have
15 that. The accuracy in that case was better than you
16 would expect.

17 (Slide.)

18 MR. MALLETT: We have an extensive program of
19 technology exchange with other countries, especially the
20 Japanese. This vu-graph shows a test that is being run
21 by the Japanese. This is their Monju hot leg where it
22 comes out of the reactor here, off the ground here, up
23 around, and back into their IHX. It is a test very much
24 like the test that I showed you earlier in blue, which
25 is the test being run in this country. They have run

1 this particular piping through thermal expansion type
2 testing. They have run it through seismic testing, and
3 they are also going to be doing water hammer testing
4 with this piping. It is an example of the type of
5 program where we have stayed in touch with the Japanese
6 to follow what they are doing. They follow what we are
7 doing, because neither of us wishes to have any
8 important oversights.

9 (Slide.)

10 MR. MALLET: This is a specific quantitative
11 benefit from that exchange. They have done in situ
12 verification of Joyo piping dynamics. This is done by
13 shaker siting force in three places, X, Y, and Z, from a
14 piece of pipe that runs from their IHX out to their
15 penetration. What you see from these in situ test
16 results are here, the first four test frequencies are
17 shown here, the corresponding analysis frequencies are
18 shown here. The two differences and analysis results
19 here. One case they run with the rigid, assume a rigid
20 support. That is the way we used to do analysis in this
21 country, the way they used to do it. We don't do it
22 that way any more, we do it with spring. With springs
23 the correlations on these loads are very good for tests
24 against the installed piping in the Joyo plant.

25 I have tacked on the end here, just for your

1 information damping that has been measured in these
2 tests. They say the damping is quite high. The first
3 load is up to 17, 18 percent, down to the fourth node,
4 higher frequency. The damping is down four to five.
5 This is just an indication of our interest in what is
6 going on elsewhere in the development of these LMFBR
7 reactors. This is where I have come to from this
8 presentation.

9 (Slide.)

10 MR. MALLETT: The methods we used are the
11 conventional methods and have conventional
12 conservatisms. I didn't go through the inherent margin
13 business. It is on the docket, and there is nothing
14 special to the LMFBR. We ran through the special
15 attributes that reduce the risk associated with high
16 seismic events, and finally, I pointed to in a summary
17 fashion the number of activities that we have in place
18 to help verify the designs.

19 It is our judgment based on activities and
20 evaluations such as these that seismic safety levels for
21 LMFBR and light-water reactor components are
22 comparable. We have done them similarly where they are
23 different, we see strengths in the features of the LMFBR
24 plant.

25 MR. TRIFUNAC: I have a question regarding

1 your loop that you showed very early about the snubber
2 resisting force. If I look at, say, a complicated
3 three-dimensional regiment of the pipe I can envision a
4 situation, and if I suppose it is attached to a
5 relatively rigid structural system, I can imagine a
6 situation where the deformation of the pipe is such that
7 in one case the snubber is pushed in and in other cases
8 it is pushed out, so if I don't have the linear
9 approximation of the spring, equivalent spring for the
10 snubber, but rather look at the actual force that is in
11 the snubber, that I could have one snubber somewhere
12 lagging, and in the other case advancing relative to the
13 force that it should be experiencing from the
14 deformation of the support points. Are you with me so
15 far?

16 MR. MALLETT: I think so.

17 MR. TRIFUNAC: So with this hypothetical case,
18 then I am getting into a situation where I can envision
19 that the forces that go into that three-dimensional pipe
20 arrangement have essentially introduced phased delays by
21 virtue of the fact that not only in the area of the
22 snubber response. Do we consider that?

23 MR. MALLETT: Let me answer it this way. The
24 snubber is quite a complicated device. It differs from
25 a linear spring in several ways. One is the damping.

1 Another is, there are small gaps, and impacts in
2 snubbers. So we have undertaken to study it a great
3 deal. It continues, and we are going to carry it so far
4 as to actually run piping systems like that that I
5 showed, where we have designed a piping system with
6 prototypic supports and characteristic thinness in
7 piping to confirm what we are doing, but so far we have
8 done it analytically. We have run very careful time
9 histories with one type of model, and another we have
10 run with small gaps and we have run with different
11 stiffnesses.

12 Frankly, it doesn't turn out to be the problem
13 that we thought it might be. What we are finding is
14 confirmation that the simplified linear response motions
15 that we use are pretty good, pretty good.

16 MR. TRIFUNAC: I am not sure you can find out,
17 because, for example, in this case, the geometry is so
18 simple, and the length is relatively short. It is
19 difficult to imagine the experimental vibration that you
20 would see that would even bring what I am talking about
21 as a possibility. If you have a long pipe, a real pipe,
22 could you not get a somewhat enriched vibration spectrum
23 mode that you don't see because you impose linearity on
24 the snubbers?

25 MR. MALLET: I say again, not as significant

1 as we thought, because the pipeline I showed you there
2 really isn't terribly simple. That is a
3 three-dimensional pipeline. It will be given a complex
4 seismic excitation. We have already run complicated
5 situations and analyses, and I showed you this one from
6 the Joyo actual plant. These complexities are actually
7 there, but apparently really are not all that
8 significant.

9 MR. TRIFUNAC: How would we test that? This
10 we cannot test in the framework of my hypothetical
11 question. We would have to have the supports of the
12 snubbers moving the way they would, say, during an
13 earthquake, and creating those out of phase motions.
14 How would we test this except perhaps during the
15 computer simulation?

16 MR. MALLET: The snubbers are out of phase.
17 We use various models. I think the complexities that
18 you are interested in are already in analyses we have
19 done and test results we have, and we are pleased to
20 learn that they really are not as complex as one might
21 hypothesize as significant.

22 MR. TRIFUNAC: I think what I am getting at
23 is, I am wondering whether there are some
24 three-dimensional shapes of vibration. I am not using
25 the word "node" intentionally, but we eliminate the

1 phase of the real snubber by linearization.

2 MR. MALLETT: I can say again we have done
3 analyses of the various snubber models.

4 MR. TRIFUNAC: Non-linear models?

5 MR. MALLETT: Absolutely.

6 MR. TRIFUNAC: Not damping, gaps, theoretic
7 delay, all the complexities that we can imagine might
8 actually be there we have looked at, and it is in the
9 open literature at this point. It is published.

10 I am talking about hystioratic delay. The
11 damping is just going to be a 90 degrees out of phase
12 thing. The stoppage is going to change the stiffness.
13 I am talking about the delay with which the force of the
14 snubber responds in a non-linear fashion.

15 MR. MALLETT: We have been through that. I
16 say again, we have very complicated snubber models to
17 test the sensitivity to such things. I say again, it
18 has turned out it is not a problem.

19 MR. TRIFUNAC: You don't find a case where the
20 delay would bring about an unexpected distribution of
21 forces and an unexpected form of vibration?

22 MR. MALLETT: I can give you some general
23 comments. If the gaps get too big, they are a problem.
24 That is one of the things that happens. I can also say,
25 when you work with such things as the damping that you

1 talk about, you can change the response. Usually you do
2 not have much effect on the largest response. The
3 smaller response, the peak boundary.

4 MR. TRIFUNAC: I am not talking about
5 damping. I am talking about phasing of the forcing
6 function.

7 MR. DICKSON: Could I rephrase it, possibly,
8 Bob? I think he is worried about snubber 1 getting hit
9 with a force and snubber 2 getting hit an instant
10 later. Then when snubber 1 is coming back snubber 2 is
11 going forward on the same length of pipe. I think that
12 is what is his concern.

13 MR. TRIFUNAC: What I am looking at is a
14 situation where they are not all in phase because they
15 are non-linear, so one is pushing, one is pulling. That
16 may be 90 degrees out of phase, or 180 degrees out of
17 phase. So in linearization in the dynamic model
18 eliminates that. That is what I am looking at.

19 MR. DICKSON: Is that eliminated, or is that
20 factor accounted for?

21 MR. MALLET: Every study we have done to look
22 at these interesting aspects of how responses may be
23 replaced have indicated they are not as important as
24 they would be --

25 MR. ZUDANS: The kind of analysis you did by

1 taking all the response spectra and adding them to the
2 response supports, the kind of question Mike is asking
3 you cannot answer without analysis. It is really a
4 question of, can you really excite the motion
5 parametrically, so to speak, by this fact that they do
6 not linearly react to the portion of the ends.

7 MR. MALLET: I do not know what it takes to
8 be helpful. We do a nozzle excitation where one end
9 moves, the other doesn't. So that is a case where the
10 supports aren't all going similarly.

11 MR. TRIFUNAC: Let me explain why I am asking
12 the question. I have done analyses of bridge type
13 structures where in the response moving phase I get one
14 response, but I just slightly change the phase of the
15 support motion, then I can excite vibrations you have
16 never seen before, and I was wondering if you have ever
17 seen historical. That is why I am asking the
18 question.

19 MR. MALLET: We have excited snubbers with
20 the non-linear historical. Our time history seismic
21 analyses have all had similar motion and support. Our
22 nozzle has not.

23 MR. TRIFUNAC: That is a limiting factor.

24 MR. DICKSON: The sodium/water reaction for
25 the intermediate heat transport is time phased, so that

1 is time phased and when a nozzle is excited, that is
2 time phased.

3 MR. MALLET: The structure is very complex.
4 A bridge is more susceptible to being excited in a way
5 so that it has a response particularly to the
6 excitation. The modes in this three-dimensional piping
7 to participate from -- they all participate from any
8 directional.

9 MR. TRIFUNAC: I was thinking about that, but
10 mechanically it was the same thing.

11 I just had one other question. You had a
12 table. You showed some very long time pegs. Is that
13 like I take the pipe experimentally and I displace it
14 and I let go and I see how it dies out? How was this
15 actually done?

16 MR. MALLET: The Joyo test that showed very
17 large damping, I think it is very large pipe that was
18 excited at the location shown. The question is whether
19 that was a sinusoidal excitation or whether it was a
20 snapback. I don't know. I don't know.

21 MR. ZUDANS: That damping included all the
22 snubbers as well.

23 MR. MALLET: The supports, yes.

24 MR. TRIFUNAC: That is why I was asking the
25 question. In the first mode it is higher than the

1 higher frequency, so you are more or less structural
2 damping.

3 MR. TRIFUNAC: So perhaps the fourth or the
4 fifth mode might be representative of the damping in the
5 pipe.

6 MR. ZUDANS: Oh, yes.

7 MR. TRIFUNAC: And the second mode is
8 indicative of the energy absorption of the snubbers.

9 MR. ZUDANS: There is no question about that.

10 MR. TRIFUNAC: That is why I asked the
11 question.

12 MR. ZUDANS: It is 17 percent.

13 MR. TRIFUNAC: So using 17 percent would be
14 misleading in the analysis of the structural model of
15 the pipe.

16 MR. MALLET: Clearly, I wasn't recommending
17 that we use 17 percent.

18 MR. CARBON: Are there other questions?

19 MR. KASTENBERG: Max, I have a general
20 question for the group of speakers, but it is brought on
21 by this particular presentation. Suppose you find in
22 the PRA that you are about to do that external events
23 such as seismic is the dominant risk contributor which
24 would lead you to core disruption or core melt, and you
25 had some systems which you may rely on, and are either

1 not seismic category 1 or just seismic category 1, and
2 you want them to function in the case of this large
3 accident.

4 The one I thought of was the one we were
5 presented with at our last meeting, which was the
6 containment event and purge system, which I think goes
7 out into the auxiliary building. Would such a system
8 hold up in a large earthquake? Have you looked at
9 that? Are there other systems that you might rely on in
10 a large earthquake that might not hold up, but you would
11 like to have available?

12 MR. MALLET: I would like to ask my spokesman
13 back there.

14 MR. GAESER: If your question is, having done
15 the analysis and finding that seismic as an example is
16 the dominant risk contributor, and then finding that
17 there is some link within the chain of connection that
18 is weak against that in the higher range, particularly
19 weak, think about the draining lake analyses, you have
20 got something sticking up, then I suspect the project
21 would take some action with respect to that without
22 knowing what the weakness was, how much it was. It
23 would be difficult to predict in advance what you would
24 do about it.

25 Clearly, the PRA would provide an indicator of

1 where you are headed, and I used the term earlier, a
2 weak link in the chain of protection, and then you would
3 have to evaluate that. Right now, those features that
4 we are counting on are all designed to ride through the
5 seismic event, and all of those, one would expect to
6 have some margin beyond that, and present at least in my
7 mind, not each one individually quantified.

8 MR. KASTENBERG: Is that system we saw last
9 time seismic 1, the purge system that went out into the
10 aux building?

11 MR. GAESER: The purge system, the filters,
12 the cleanup system, and the purge system, the buildings
13 those are located in are all seismic 1.

14 MR. CARBON: Carson?

15 MR. MARK: This is totally out of ignorance.
16 I have heard that snubbers are one of the main sources
17 of snubbers. That is, they seize up or they lose their
18 fluid or something goes wrong. Inspection is a great
19 pain and not very reliable. You have spoken of needing
20 to restrain these pipes, and yet these pipes are a
21 little more something like an earthworm that I think
22 needs to be restrained at many points. What would be
23 the consequence of just slinging this thing in a hammock
24 and attaching the continuous hammock to beams at a
25 suitable number of points and letting the pipe ride away?

1 MR. MALLETT: It is true, to fail something
2 you need to tie it down some place. If it is not tied
3 down any place, you can't hardly fail it. Once you
4 begin to tie it down to a nozzle of the component and
5 then another nozzle at the component of the other end,
6 then --

7 MR. MARK: I could see that that would be true
8 for maybe the last half dozen feet or something.

9 MR. MALLETT: It is a good idea to have
10 flexible systems. You won't find snubbers like this in
11 fossil plants, old plants.

12 MR. MARK: You are saying that the snubbers
13 you are proposing to use are going to be less affected
14 by the traditional problems that you would buy from the
15 guys who now make and sell snubbers?

16 MR. MALLETT: We are going to buy mechanical
17 snubbers which are -- for this piping we talked about
18 here today, which are very well studied items in recent
19 years. That is true. I do not have some of the failure
20 modes and some of the hydraulics numbers handy. We have
21 used vendor data, and we have developed our own data.
22 We have spent a lot of time trying to engineer those
23 supports, trying to get them right, and as you know, we
24 will be involved in inspections and confirmations later.
25

1 MR. ZUDANS: Typically, what kind of thermal
2 expansion motion do the scrubbers allow, in inches?

3 MR. MALLET: You can specify what you want.

4 MR. ZUDANS: What do you need, for example, in
5 the piping that you discussed?

6 MR. MALLET: We will buy ones that are
7 frequently, say, six-inch travel.

8 MR. ZUDANS: Six inch travel for slow motion?

9 MR. MALLET: Yes.

10 MR. ZUDANS: The leg that comes up on the
11 reactor vessel goes up a couple walls and goes up.
12 Where is the first snubber located on that line? On the
13 vertical leg someplace?

14 MR. MALLET: No, we have no snubbers in the
15 reactor cavity. It is up, out, over and through the
16 wall and then it is over there (indicating).

17 MR. ZUDANS: And then you have a great number
18 of elbows, at least two more elbows before you hit the
19 first snubber. So that means the reactor vessel expands
20 six inches, you really don't care. You can fully
21 accommodate it. It is not a single support that would
22 freeze up on you and stop the wall from expanding.

23 MR. MALLET: Yes. We have done beyond design
24 basis accident analysis, so to say we can withstand
25 circumstances like that.

1 MR. ZUDANS: Does the compartment head up in
2 the case of spill? I guess you really don't care; when
3 you spill, you spill. Okay, that's a superfluous
4 question.

5 MR. CARBON: Thank you, Dr. Mallett. Mr.
6 Thornberg?

7 MR. KNIGHT: I guess the next item on the
8 agenda is the status of the staff review, and I can be
9 very succinct at this point. In addition to the -- this
10 is Jim Knight from the staff.

11 In addition to the report that we had this
12 morning from the people in geology and seismology, we
13 are in the midst of our review in our areas, and in
14 particular, the structural people will be performing an
15 audit at Burns & Roe on June 22nd and 24th, in which we
16 will be looking at a number of the areas discussed here
17 today, such as modeling and various parameters used in
18 the seismic analysis.

19 And we have the mechanical people looking at
20 piping and components that are being assisted in this
21 particular case by EG&G, partially because of the
22 shortage of personnel available to perform the review
23 and partially because we were looking at -- for
24 additional expertise. Not so much in the seismic area,
25 although we will be benefiting by the EG&G personnel

1 there, too, but also in the area of high temperature
2 technology in the application of the high temperature
3 code cases and the code.

4 There we have a subcontract that makes Dr.
5 O'Donnell available to us as the staff consultant and
6 assists us in our review. I would hope we would have a
7 draft SER on the mechanical side probably mid-July.
8 That will be the first item we will set forth as areas
9 where the staff has concerns and expand on that in the
10 question and answer process.

11 That pretty well is the status of the staff
12 review at this moment.

13 MR. CARBON: Questions of the staff?

14 MR. MARK: Will the staff probably have
15 solidified its conclusions on the acceptability of some
16 number for SSE and OBE by the site suitability meeting
17 time?

18 (Pause.)

19 MR. KNIGHT: I would characterize the staff's
20 present posture as one of working at this moment to
21 assure ourselves that the conclusion we reached some
22 years ago still holds, and I don't believe as of this
23 moment we see any strong influences that would have us
24 tend to change our mind. We may not -- by the time of
25 the site suitability meeting.

1 I would presume we would like to reserve a
2 little bit of flexibility to look at some other
3 information that might be available, but by and large, I
4 think we are already at the point where, as I said,
5 barring some unique piece of information, we are
6 satisfied with the seismic design level.

7 MR. ETHERINGTON: Does this mean that starting
8 today you would reach the same numbers?

9 MR. KNIGHT: I think that is a fair
10 characterization at this time. We do reach the same
11 numbers. We do have questions that are outstanding, and
12 I do not want to disarm the applicant. We do have
13 questions that are outstanding. They wouldn't have been
14 asked whether they were serious questions, and it is the
15 type of question I think we need to update, our
16 understanding of the geology of the area and to assure
17 ourselves and the applicant that there are not factors
18 that would cause us to change our minds. But it is an
19 attempt to give you the best feeling I can for the
20 moment.

21 I thin we are not, at this momen^t,
22 anticipating a significant change.

23 MR. MARK: A thing that could make a
24 significant change in principle would be the
25 redefinition of the locale, within which the Madrid

1 earthquake structure exists. Now, I presume that has
2 been looked at and it does not make a change, it does
3 not make Madrid controlling. The boundary of that rift
4 or fault or whatever you call it has been expanded
5 within the last, what, year or two years from what it
6 was when this was first looked at.

7 If it came far enough in the right direction,
8 then it could become controlling, and that would change
9 your SSE numbers in principle. It could potentially.
10 The same thing would happen if Charleston were allowed
11 to migrate 100 miles inland; then it would be at the
12 200-mile distance.

13 MR. KNIGHT: Yes. I guess certainly, if what
14 I would consider significant events of this type were to
15 occur -- and one might even say if we had another event,
16 significant event somewhere closer by -- it could
17 change. But we have put a fair amount of effort into
18 reviewing the work that we have done over the past, and
19 at this point, with the exceptions of the questions
20 which are now outstanding, we have not felt the need to
21 modify our position.

22 MR. MARK: That is likely to be rather a
23 central point, is it not, in site suitability
24 discussions ultimately, if not this month? Certainly it
25 is the basis of all we have heard today, that this is

1 the SSE and this is the response.

2 MR. CARBON: I don't know whether Mr. Check
3 might want to respond to that comment or not.

4 MR. CHECK: I don't know how much more can be
5 said. There is always an element of risk. If it is
6 important, do things happen, they are going to be
7 accounted for, up to an including changing the game.
8 But if things hold together, right now there is a
9 growing confidence that the conclusions we have reached
10 before about the capability of this site for a reactor
11 of this general size and type are going to hold up.

12 MR. MARK: I couldn't ask for more.

13 MR. CARBON: Are there any other questions?

14 MR. KASTENBERG: Yes. I would ask the staff:
15 in what context will the staff handle earthquakes more
16 potentially severe than the SSE?

17 MR. KNIGHT: That is a very significant and
18 difficult question. I cannot give you a prescription of
19 what the staff will do. Our response in the past -- and
20 this is a subject which is occurring with increasing
21 frequency -- has been that we believe that the process
22 that is now in place, the designation of the SSE and the
23 OBE, leads us to an adequate design basis with margin
24 that gives a significant, I believe, degree of
25 confidence in an ability to withstand an earthquake

1 greater than that for which we have explicitly designed.

2 As a matter of fact, I think everytime we look
3 at it, it is virtually impossible for us to design just
4 up to some level. We always end up with capacity
5 greater than our design. Even when we go back and
6 retrofit a plant, we end up with something greater than
7 what we retrofit for. It is just the state of the
8 engineering technology.

9 Once you decide that you want to enter this
10 question -- and this may or may not have been this type
11 of a question -- once you decide you want to enter the
12 sphere of a discussion on larger load capability of
13 greater magnitude events, the engineer has a rather
14 significant problem, and the regulator along with him,
15 in that if one were to say: I want some definitive
16 response here, it seems to me that the next thing you
17 want to do is define that larger event, define it in a
18 way that you can enter the standard methodology with it.

19 Having done that, now I should decide on
20 perhaps acceptance limits for stresses and this kind of
21 thing. So one possible avenue seems to be opening an
22 entirely new branch of progress, I might say. The other
23 is to perhaps look more closely at the question of
24 margin and where it exists and what confidence we have
25 in it.

1 There has been a suggestion, I believe, from
2 time to time that perhaps we should increase the level
3 of seismic input just to gain some of this additional
4 confidence. I have, I know, a very personal feeling and
5 it is shared by others of the members of my staff, that
6 this may be just the very wrong way to go.

7 A lot of things we are talking about here
8 today, adding stiffeners, snubbers, complicating
9 systems, it would seem to me that a very careful study
10 would be in order before we decide that we really have
11 made a net gain in safety by somewhat arbitrarily
12 increasing the level of seismic input, either because we
13 really are convinced that we have not defined an
14 adequate -- unless we are convinced that we have not
15 defined an adequate seismic basis initially.

16 MR. KASTENBERG: Let me see, does this mean
17 that during the next year before issuing the CP, you
18 will try to arrive at some resolution, or will you just
19 discuss it over coffee and let it go at that? I am not
20 asking for exactly what the answer is going to be, but
21 just in the context of how you will approach it, because
22 I am sure the question will come up again.

23 MR. KNIGHT: You are certainly right. The
24 direct answer is that the staff at this time has no
25 plans -- we have no activity underway to either redefine

1 the seismic design basis or, in some way, I suppose you
2 might say come to grips with that question, other than
3 to look at it from the standpoint of the so-called
4 traditional standpoint: are we, in fact, correct that
5 significant margin exists beyond our significant design
6 levels, and are there soft points, are there areas where
7 that thinking is faulty if something of this type is not
8 a rigorous program or misleading.

9 But there is no formal distinct plan in
10 progress, then, to address that question other than by
11 coming back to the question of margins.

12 MR. CARBON: But coming back to that, will
13 you, as an example, be asking the applicant to carry
14 through analyses to find which are the weakest points in
15 terms of added or extra capacity?

16 MR. KNIGHT: I doubt, at this time, that we
17 would be asking the applicant to do analyses to
18 specifically -- to address -- I think your direct
19 question, to do unique analyses to particularly find
20 soft spots. We would certainly, in our reviews such as
21 the audits we are performing and the reviews that we
22 would be subsequently performing with the Branch, be
23 looking at the work that has been done, with the purpose
24 of assuring ourselves that at this point, -- I suppose
25 one might call it the contention offered by the

1 applicant -- that the margins which exist in this plant
2 are comparable to those which we find in the light water
3 plants.

4 Whether or not at some point, based on what we
5 learn, it becomes useful to ask for some particular
6 piece of work is another question. I certainly do not
7 know of any at the moment.

8 MR. ETHERINGTON: Do we have adequate data on
9 the cycle fatigue, elevating temperature? You can just
10 say yes or no.

11 MR. KNIGHT: Not really.

12 MR. ETHERINGTON: Thank you.

13 MR. POMEROY: I would like to ask a quick
14 generic question not directly related to this, but I do
15 remember that at a January meeting of Dr. Okrent's
16 Subcommittee on Extreme External Phenomena, we were told
17 that the Geological Survey was in the process of
18 re-evaluating its position on the Charleston earthquake,
19 and I believe at that time we were told that there would
20 be a report out in late March having to do with that
21 determination.

22 I wondered if the staff has any late word on
23 when that determination might be available?

24 MR. KNIGHT: I don't. We have been in
25 communication with the USGS. All indications are now

1 that that report will be delayed. It is not available
2 now. It seems unlikely it will be available within
3 several weeks, extending perhaps into several months.
4 It is rather nebulous. That is the best we have.

5 MR. CARBON: Can you add anything further to
6 that? Does the reason for the delay have to do with big
7 uncertainties of a particular type, or -- ?

8 MR. KNIGHT: Well, it is still -- the matter
9 is very firmly internal to USGS, but clearly, the reason
10 for delay is that there is -- and I may be guilty of
11 giving a flavor that is somewhat personal, but it seems
12 clear that the evidence necessary to change the present
13 position is certainly not overwhelming. I don't mean to
14 demean the efforts of those involved, but it certainly
15 was not sufficiently compelling to cause a change to be
16 made quickly, and in fact, is apparently -- the question
17 is sufficiently difficult and the information is
18 sufficiently vague that attempting to develop a
19 consensus, they have really been unable to do so.

20 MR. CARBON: Is your knowledge of that
21 situation such that it would appear that when they do
22 come to a consensus, it probably will not have any
23 bearing on the CRBR, or might there be a big enough
24 change?

25 MR. KNIGHT: Either it will not have any

1 significant bearing on the CRBR, or it -- it is probably
2 not a very good answer to your question. Probably it
3 won't. I think the probabilities are reasonable that it
4 won't or there will have to be rather significant
5 reconsideration for across the board.

6 I think the trend would seem to be at the
7 moment that we would not see a large impact. That even
8 if there should be some movement, as it were, that the
9 probability of a large event would be quite low.

10 (Pause.)

11 MR. CARBON: Are there any other questions
12 anyone wishes to raise?

13 (No response..)

14 MR. CARBON: I guess if not, I would propose
15 to adjourn the meeting and ask the subcommittee members
16 and the consultants to stay and talk for a little bit.
17 We will end the recording at this point.

18 We thank the people from the DOT and the
19 project for your time and effort here today, and we
20 thank the staff likewise. I guess with that, we will
21 adjourn.

22 (Whereupon, at 5:26 p.m., the subcommittee was
23 adjourned.)

24 * * *

25

NUCLEAR REGULATORY COMMISSION

This is to certify that the attached proceedings before the
ACRS/Subcommittee on Clinch River Breeder Reactor

matter of: Briefing on Clinch River Breeder Reactor Geology and
Seismology

Date of Proceeding: June 1, 1982

Docket Number: _____

Place of Proceeding: Washington, D. C.

were held as herein appears, and that this is the original transcript
thereof for the file of the Commission.

Jane W. Beach

Official Reporter (Typed)

Jane W. Beach

Official Reporter (Signature)

BRIEFING FOR
ADVISORY COMMITTEE ON
REACTOR SAFEGUARDS (ACRS)

GEOLOGY AND SEISMOLOGY

Presented by

W.G. BRUSEY
Geotechnical Consultant
CRBRP Project

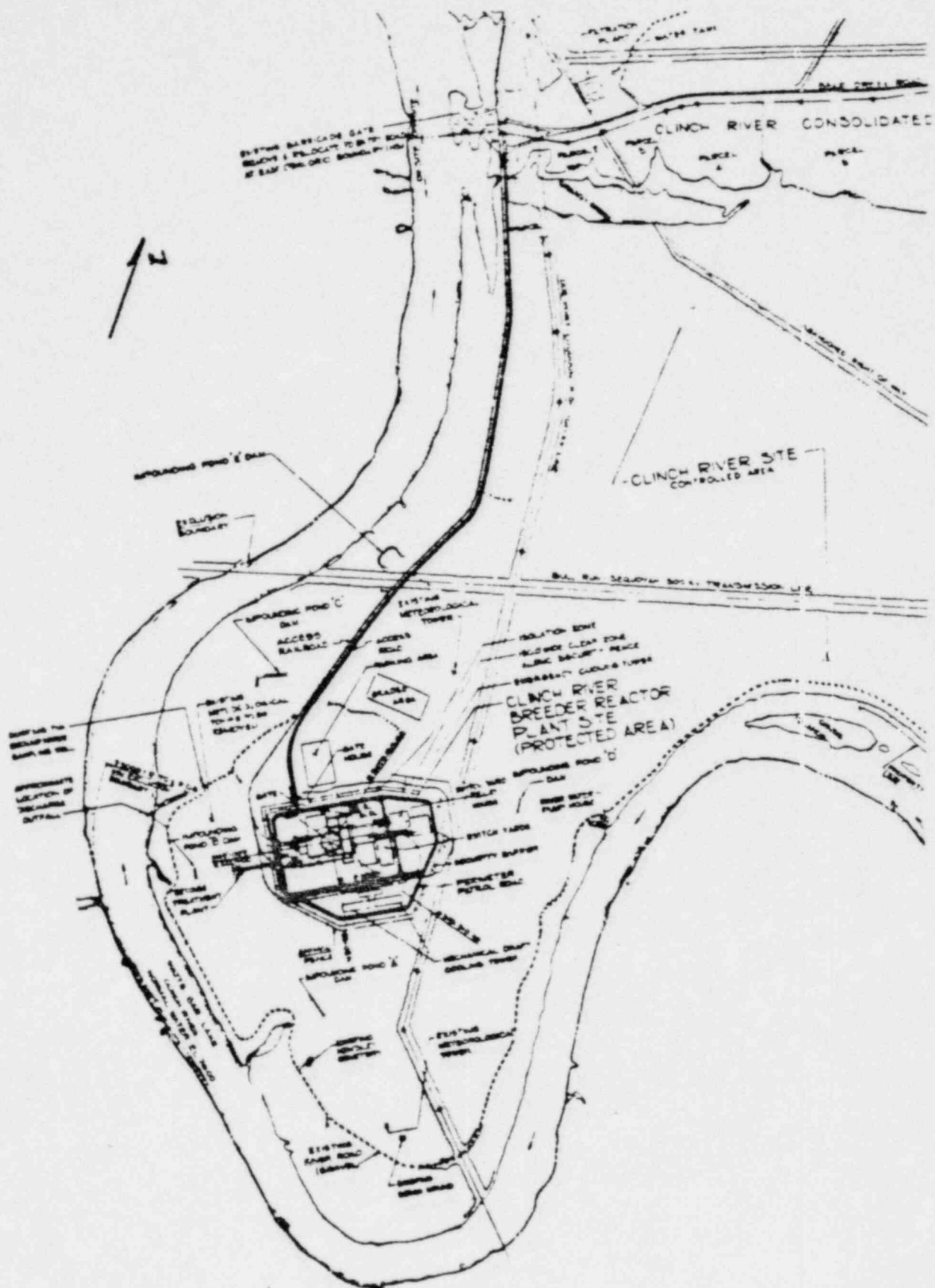


BURNS AND ROE, INC.

T1 + T2

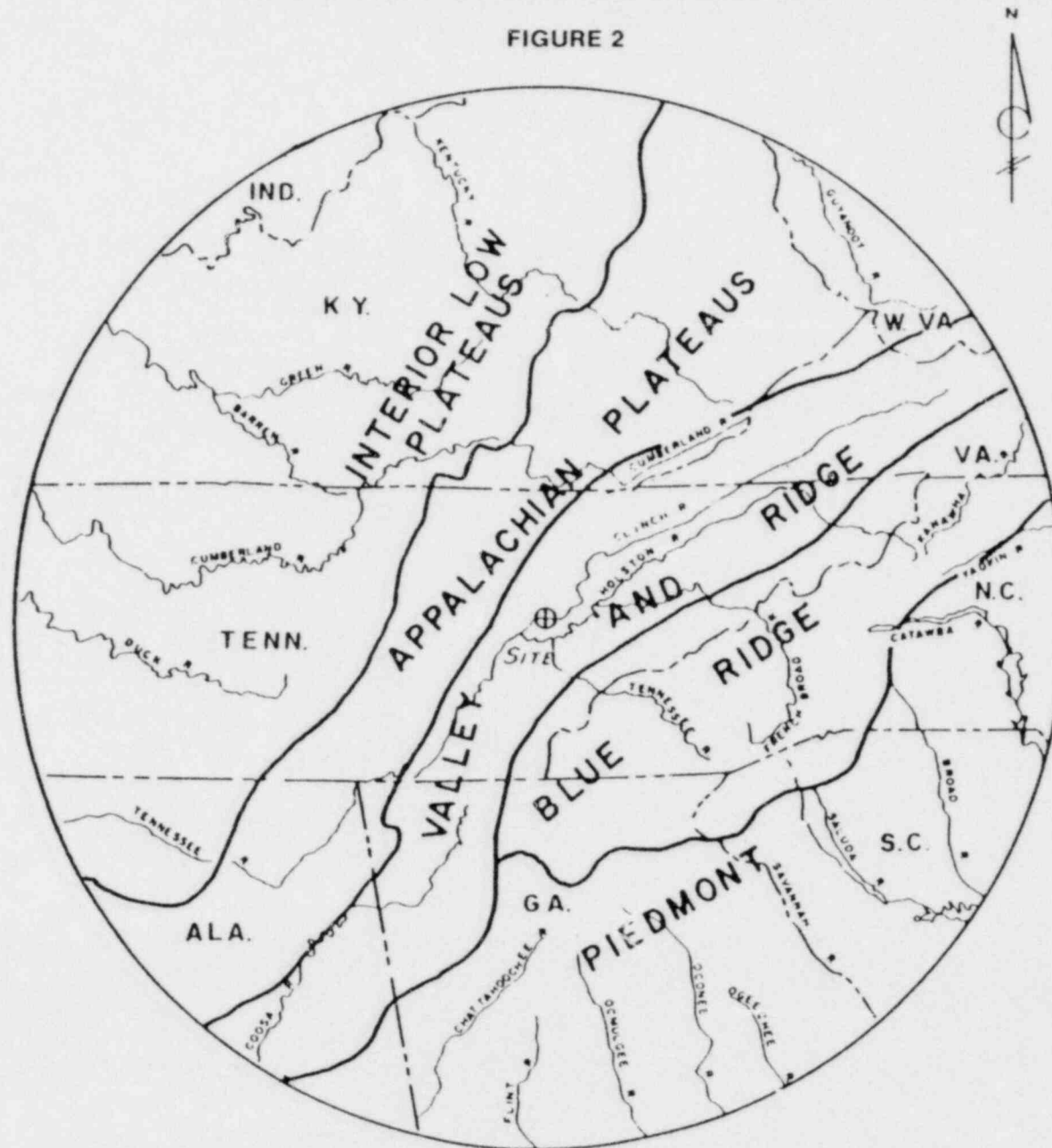
OUTLINE

- **SITE INVESTIGATION PROGRAMS**
- **DEVELOPMENT OF FOUNDATION DESIGN PARAMETERS**
- **EARTHQUAKE HISTORY**
- **SELECTION OF SSE AND OBE**



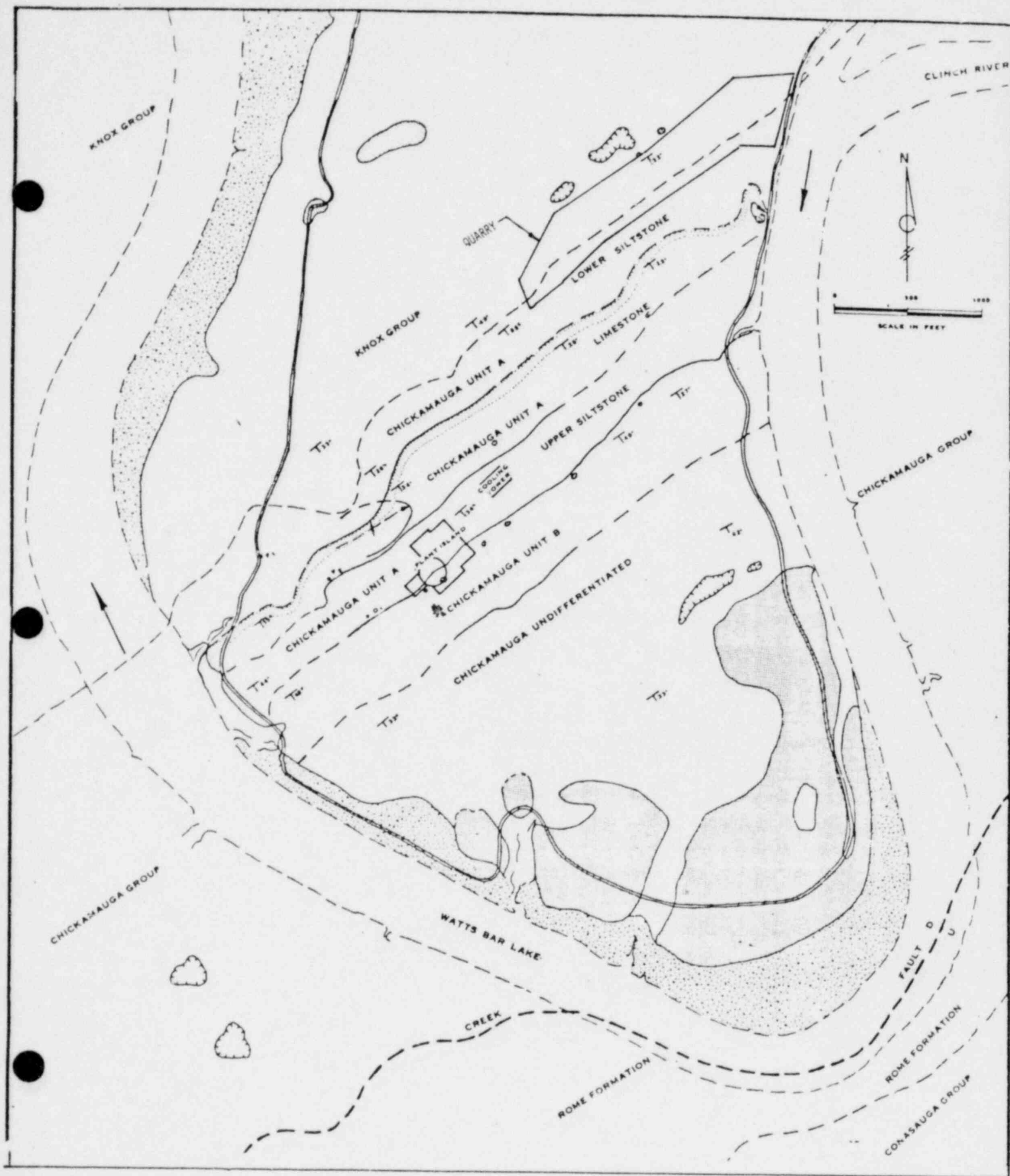
Plant Location on the Clinch River Site

FIGURE 2



SITE INVESTIGATION ACTIVITIES

- LITERATURE STUDIES
- GEOLOGIC RECONNAISSANCE
- GEOLOGIC MAPPING
- AERIAL PHOTOGRAPHIC STUDIES
- BORINGS
- MONITORING WELLS
- GEOPHYSICS



GEOLOGIC AND PHYSIOGRAPHIC MAP

FIGURE 3

OBJECTIVES OF INVESTIGATION PROGRAMS

- **DEFINE INTERBEDDED SILTSTONE AND LIMESTONE STRATA**
- **DEPTH OF WEATHERING**
- **RESIDUAL SOILS AND TERRACE DEPOSITS**
- **PREFERRED LOCATION OF NUCLEAR PLANT ISLAND STRUCTURES**
- **DETAILED EVALUATION OF FOUNDATIONS FOR CATEGORY I STRUCTURES**

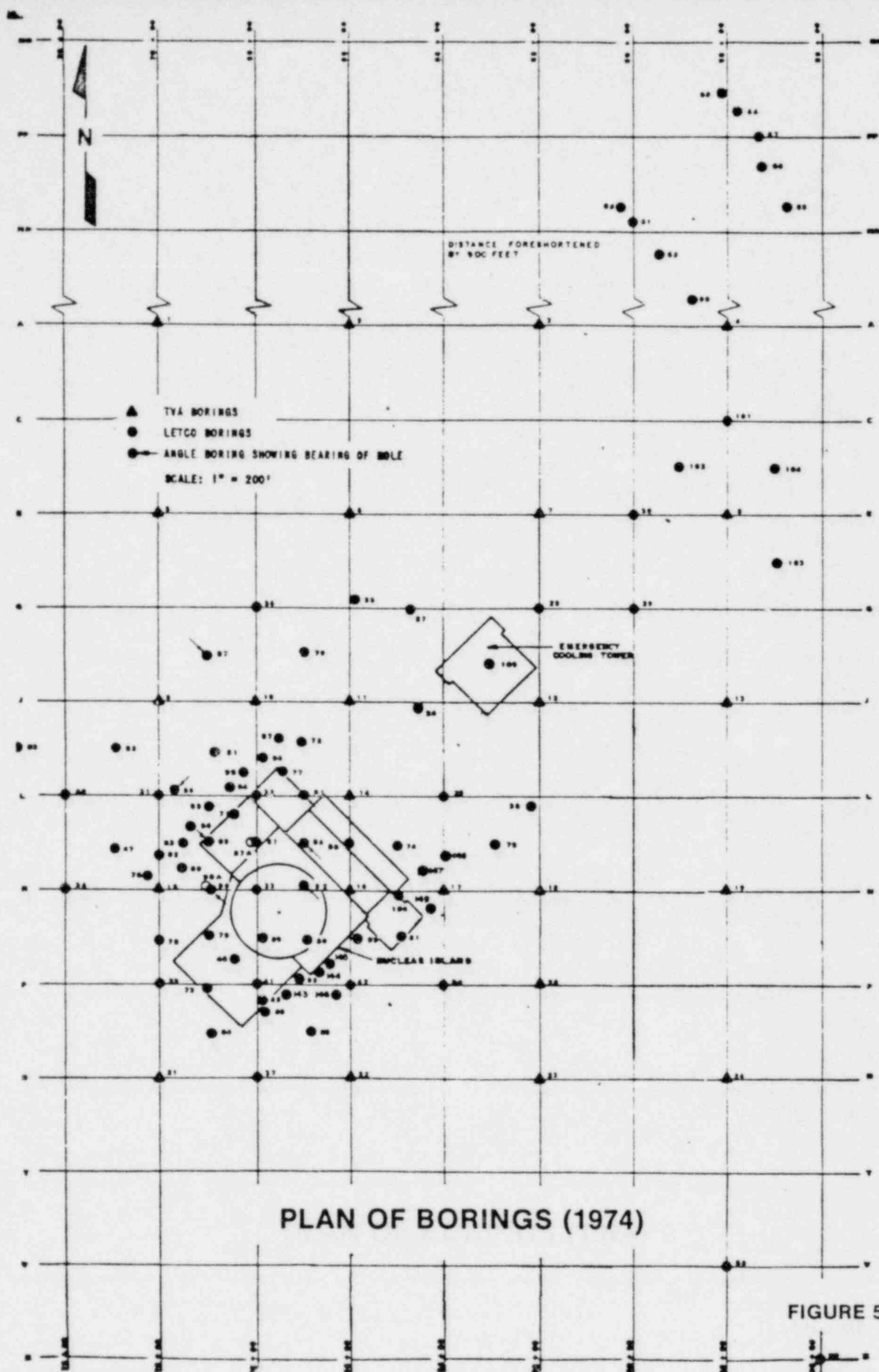
BORING PROGRAMS CONDUCTED AT SITE

<u>DATE</u>	<u>PURPOSE</u>	<u>NUMBER OF BORINGS</u>
2/72 TO 12/72	SITE EVALUATIONS	24
6/73 TO 12/73	SELECTING OPTIMUM SITE LOCATION	42
12/73 TO 4/74	DETAILED FOUNDATION EVALUATION	40
11/74 TO 2/75	BALANCE OF PLANT INVESTIGATION	95
9/76 TO 6/77	LOCALIZED INVESTIGATION OF EAST FACE SOLUTIONING	23
1/81 TO 5/82	BEDROCK VERIFICATION PROGRAM	34
		<u>258</u>

FIGURE 4

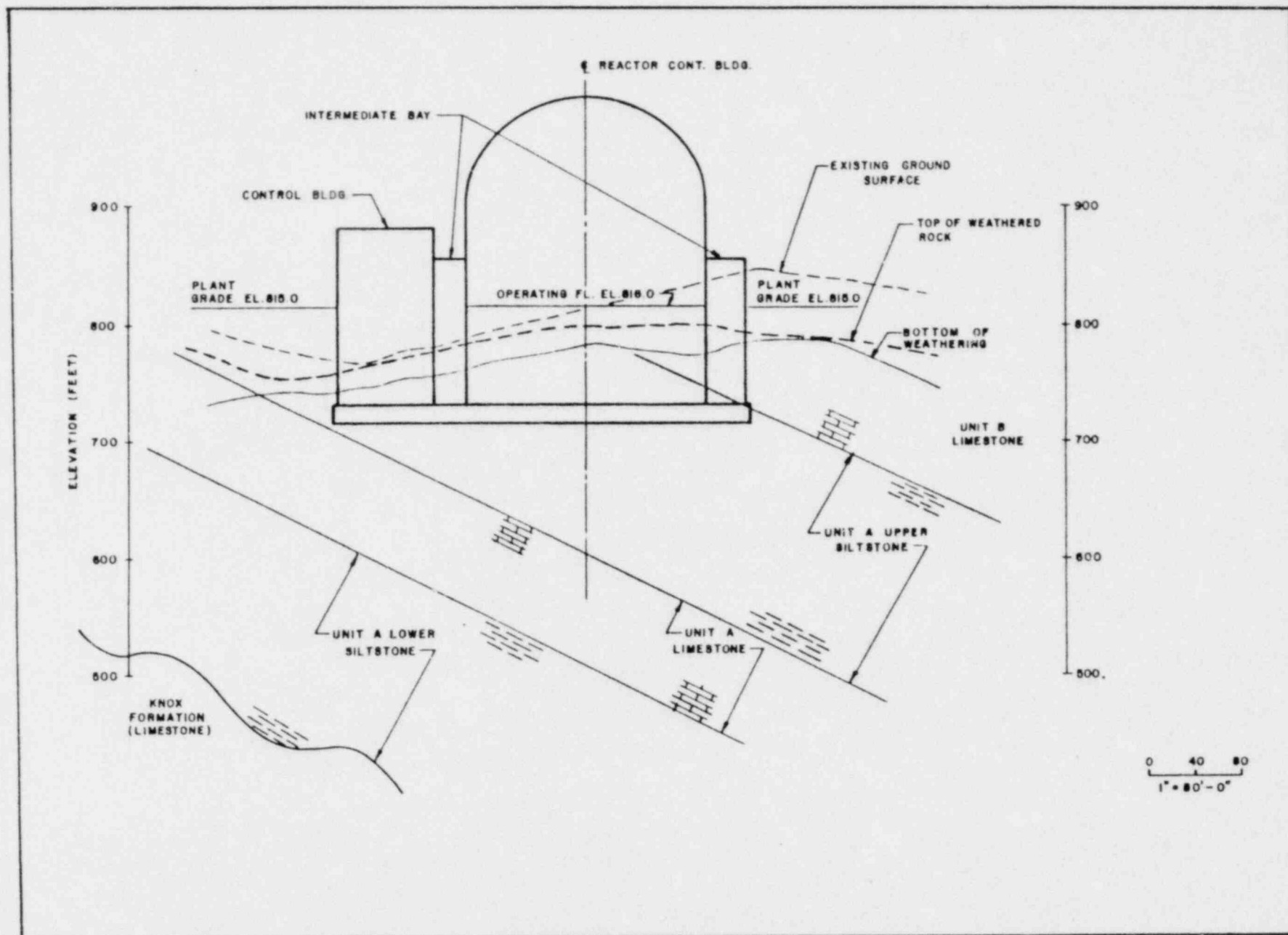
DETAILS OF BORING PROGRAMS

- DEPTH OF BORINGS RANGED FROM 100-300'
- EVALUATION OF CORE (RQD DETERMINATIONS)
- GEOPHYSICAL STUDIES
- CATEGORY I STRUCTURES LOCATED ON UNIT A UPPER SILTSTONE



SIGNIFICANT INVESTIGATION PARAMETERS

- **DEPTH OF WEATHERING**
- **INVESTIGATION OF POTENTIAL SOLUTION ZONES IN UNIT A & UNIT B LIMESTONES**
- **SELECTION OF FOUNDATION BEARING ELEVATION**

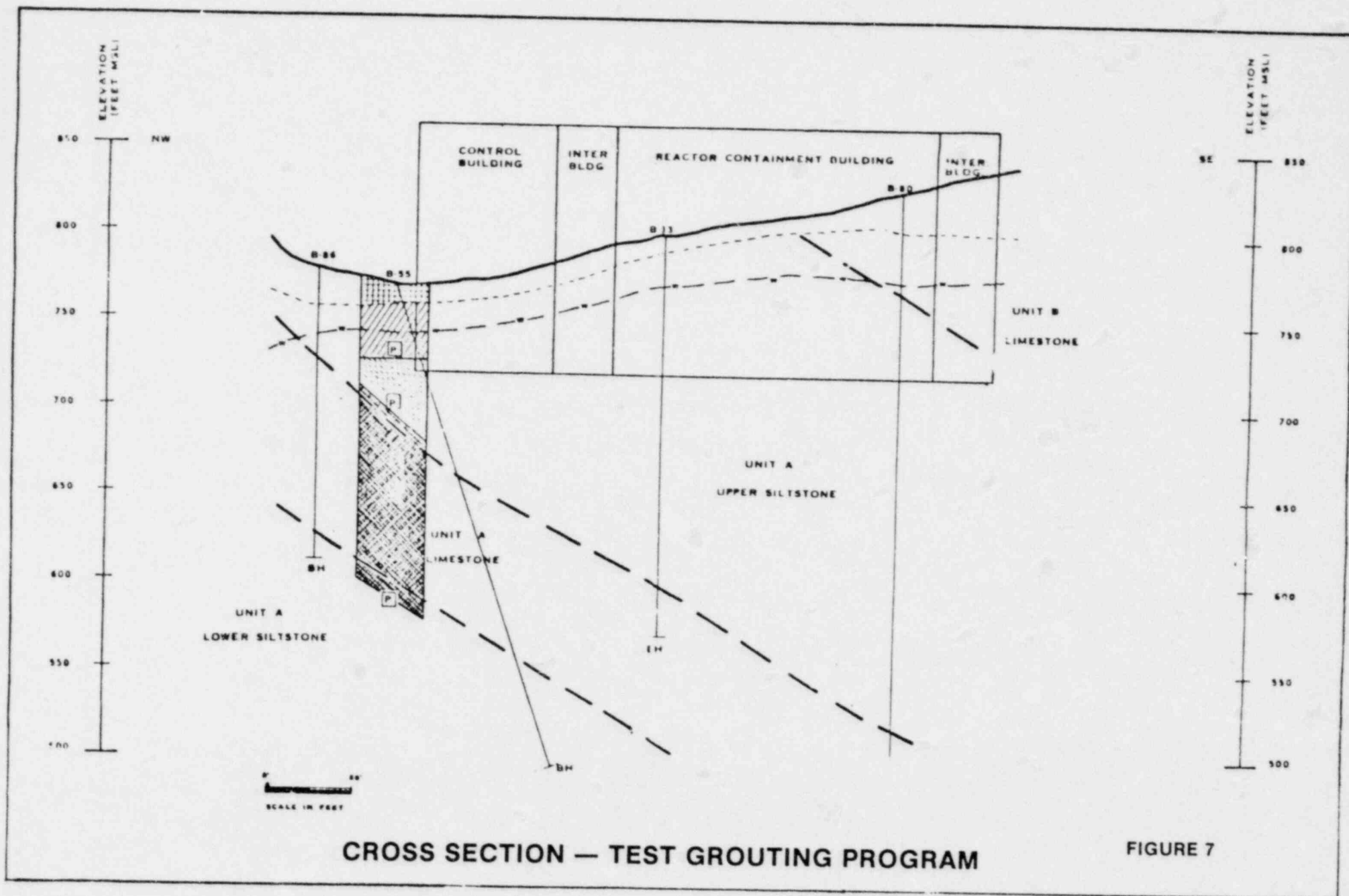


CROSS SECTION — NUCLEAR ISLAND

FIGURE 6

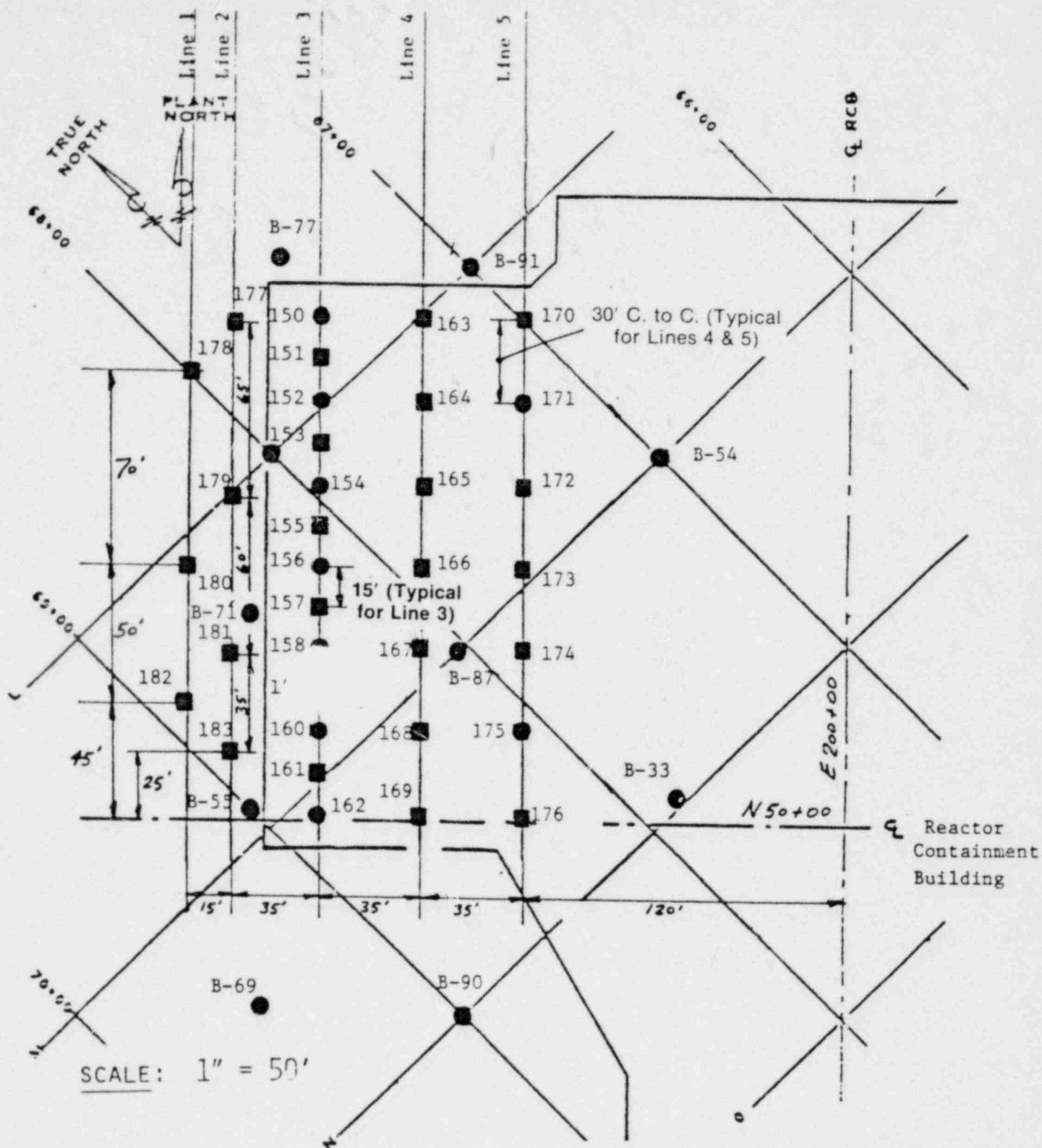
DETAILS OF TEST GROUTING PROGRAM

- CHECK REPRESENTIVITY OF BORING 55
- BORINGS SPACED AT 20' AND 10' INTERVALS
- WATER PRESSURE TESTS
- NEGLIGIBLE GROUT TAKE
- FOUNDATION TREATMENT NOT REQUIRED



DETAILS OF VERIFICATION PROGRAM

- DEPTH OF BORINGS EXTEND 100' INTO UNIT A LIMESTONE
- PROGRAM ONGOING
- RESULTS ANALYZED TO DATE INDICATE NO FOUNDATION TREATMENT REQUIRED



LEGEND:

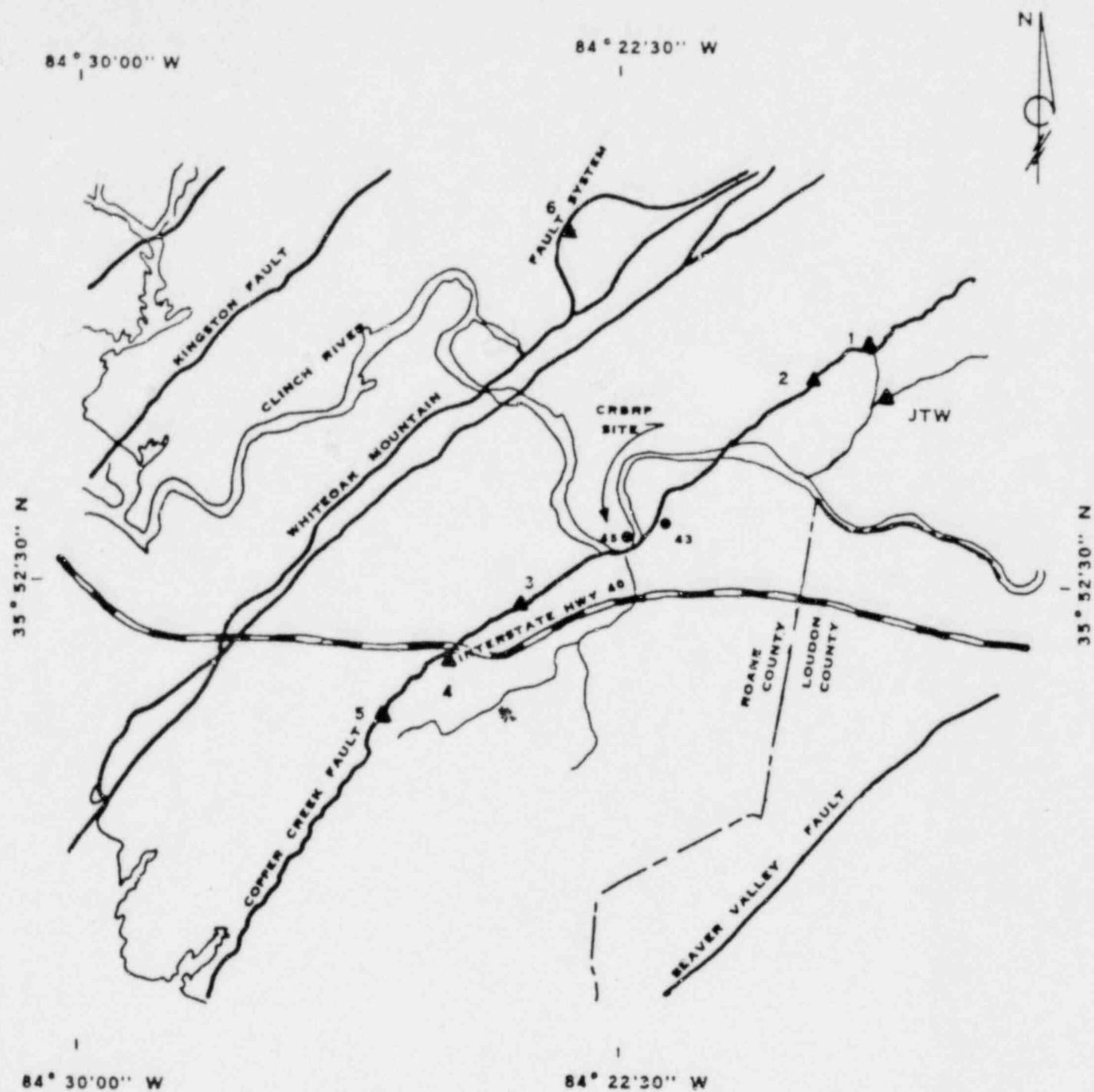
VERIFICATION PROGRAM BORINGS (1982)

- CORE BORINGS
- AIR TRACK (ROTARY PERCUSSION) BORINGS

FIGURE 8

FAULTING INVESTIGATIONS

- IDENTIFICATION OF MAJOR NON-CAPABLE FAULTS
- GEOLOGICAL INVESTIGATION OF COPPER CREEK FAULT
- AGE OF FAULT DATED AT 280 MILLION YEARS



▲ JTW (JOY TEST WELL) SEE SECTION 2.5.2.2.1

● LAW ENGINEERING BORINGS

▲ FIELD OBSERVATION LOCATIONS

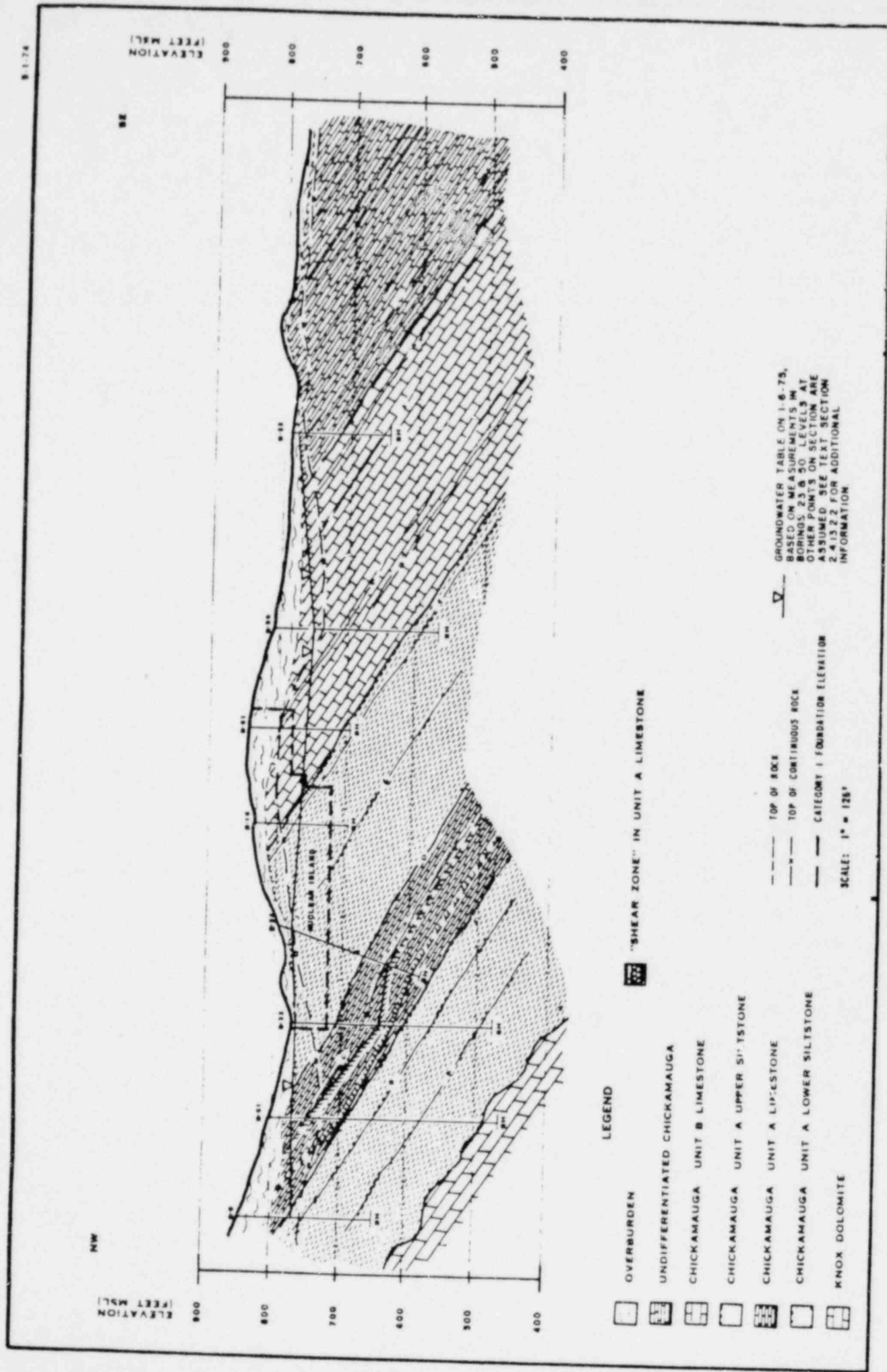
SCALE: 1" = 2 MI

AREA STRUCTURE MAP

FIGURE 9

INVESTIGATION OF SHEAR ZONE

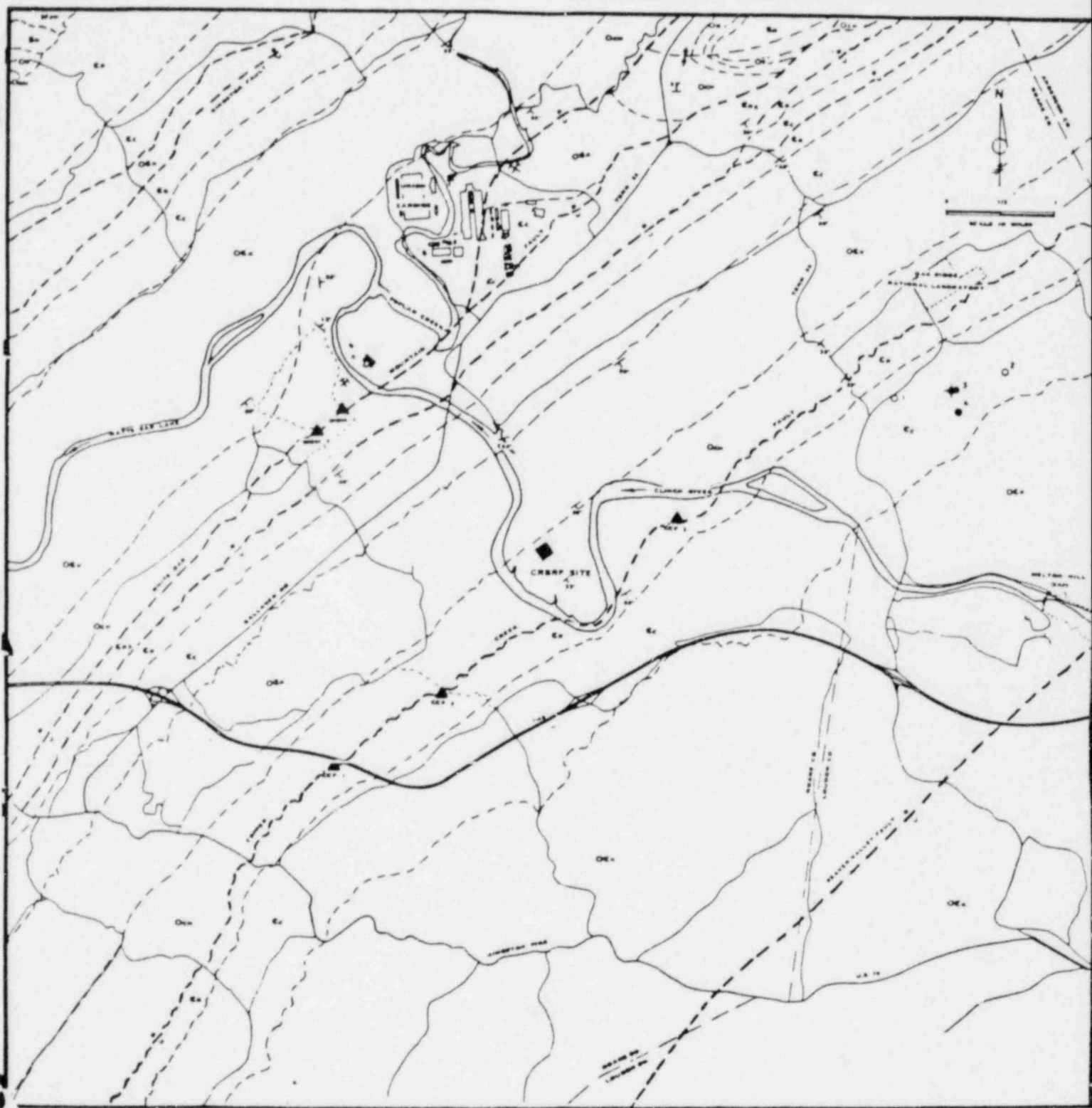
- IDENTIFICATION OF SHEAR ZONE IN UNIT A LIMESTONE
- EVALUATION OF CORE FROM BORINGS
- CONSENSUS OF GEOLOGICAL OPINION THAT SHEAR ZONE FEATURE IS ANCIENT AND REHEALED



SITE GEOLOGIC PROFILE (SHEAR ZONE)

WASTE DISPOSAL AT ORNL SITE

- LOCATION OF INJECTION WELLS
- DEPTH OF INJECTION ($\approx 800'$)
- ANALYSIS OF DATA INDICATES NO IMPACT ON SITE



AREA PLAN SHOWING INJECTION WELLS

FIGURE 11

EVALUATION OF PARAMETERS

STATIC

- BEARING CAPACITY AND SETTLEMENT
- GEOTECHNICAL INSTRUMENTATION TO MONITOR POTENTIAL HEAVE AND SETTLEMENT
- ANTICIPATED MOVEMENTS WILL BE NEGLIGIBLE

DYNAMIC

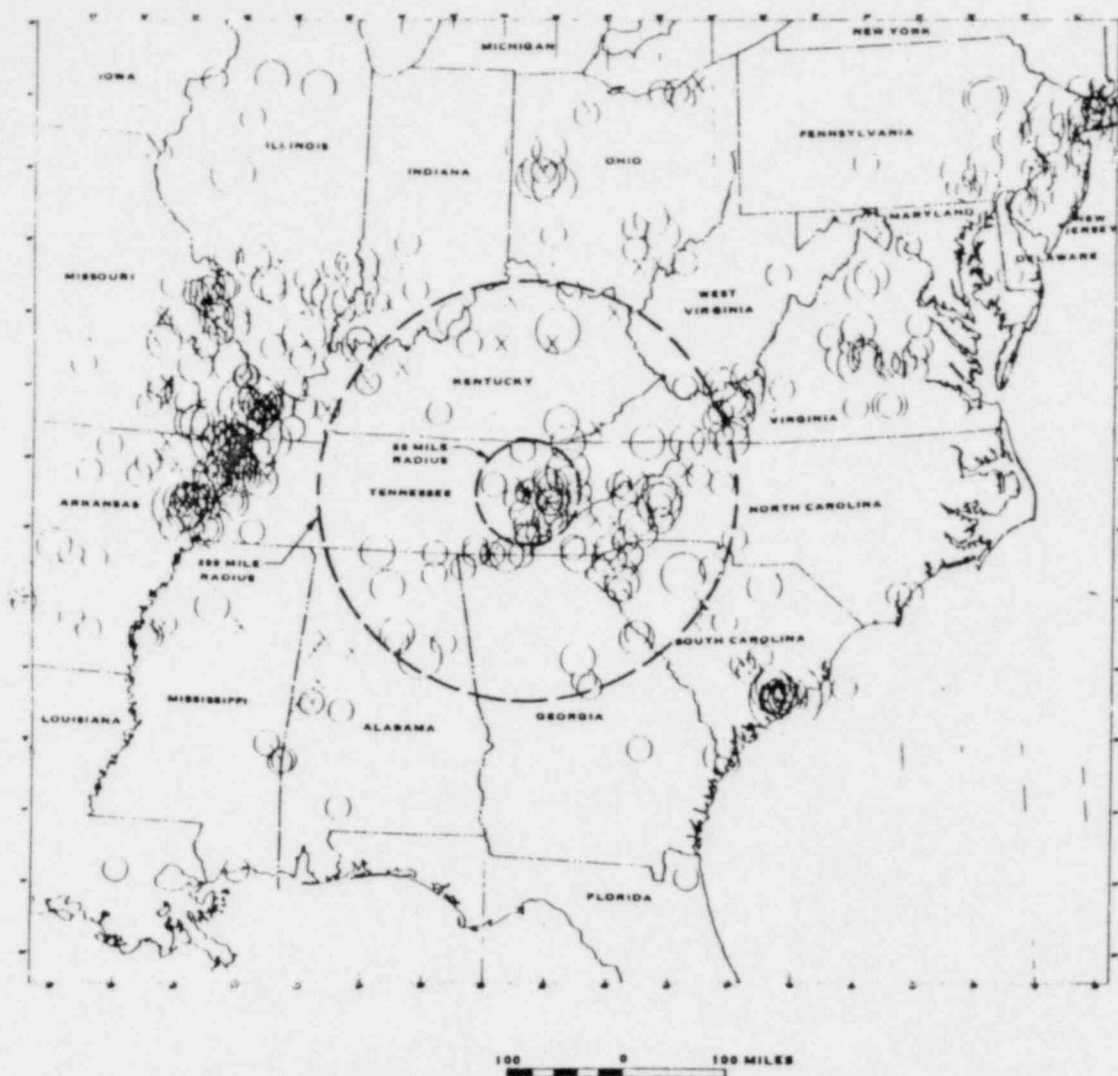
- GEOPHYSICAL INVESTIGATIONS
- IN SITU VELOCITY MEASUREMENTS
- SELECTED DESIGN VALUES

DEVELOPMENT OF FOUNDATION DESIGN PARAMETERS

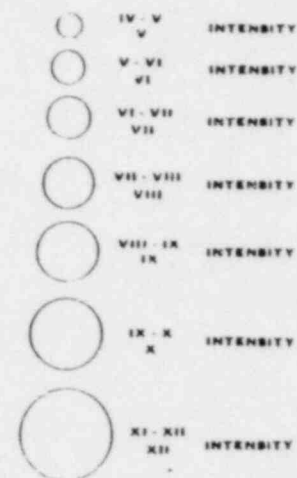
(A) STATIC

(B) DYNAMIC

FIGURE 12



LEGEND:



X 1. SIGNIFICANT EARLY HISTORICAL EARTHQUAKES WITH UNREPORTED MAGNITUDE AND INTENSITY

OR

2. EARTHQUAKES WITH MAGNITUDE GREATER THAN OR EQUAL TO 3.5 AND MAXIMUM INTENSITY IV MM OR LESS

REGIONAL EARTHQUAKES WITH MAXIMUM INTENSITY EXCEEDING IV MM

FIGURE 13

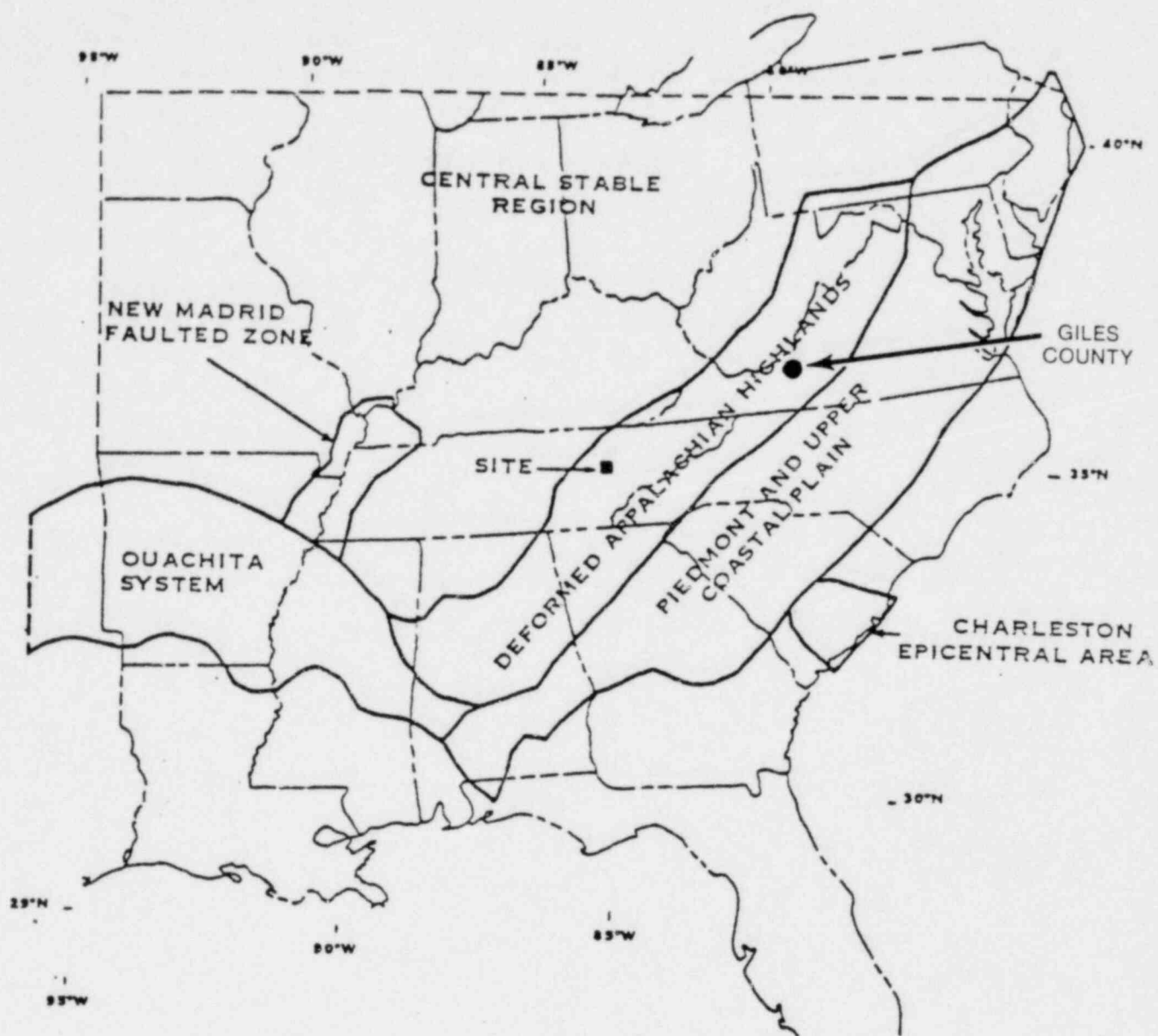
IMPACT OF REGIONAL EARTHQUAKES ON CRBRP SITE

- NEW MADRID AND CHARLESTON — ATTENUATION WILL NOT
IMPACT SITE GREATER THAN MAXIMUM HISTORICAL EARTHQUAKE
- NEW MADRID — INTENSITY VI — VII AT SITE
- CHARLESTON — INTENSITY VI AT SITE
- GILES COUNTY EARTHQUAKE

EARTHQUAKE HISTORY

TECTONIC PROVINCE APPROACH TO DEFINING SSE

- **SELECTED PROVINCIAL BOUNDARIES**
- **DEFINE INTENSITY OF MAXIMUM HISTORICAL EARTHQUAKE**
- **MAXIMUM HISTORICAL EARTHQUAKE MOVED WITHIN PROVINCE**
- **SELECT S.S.E.**
- **DEFINE INTENSITY/ACCELERATION CORRELATION**

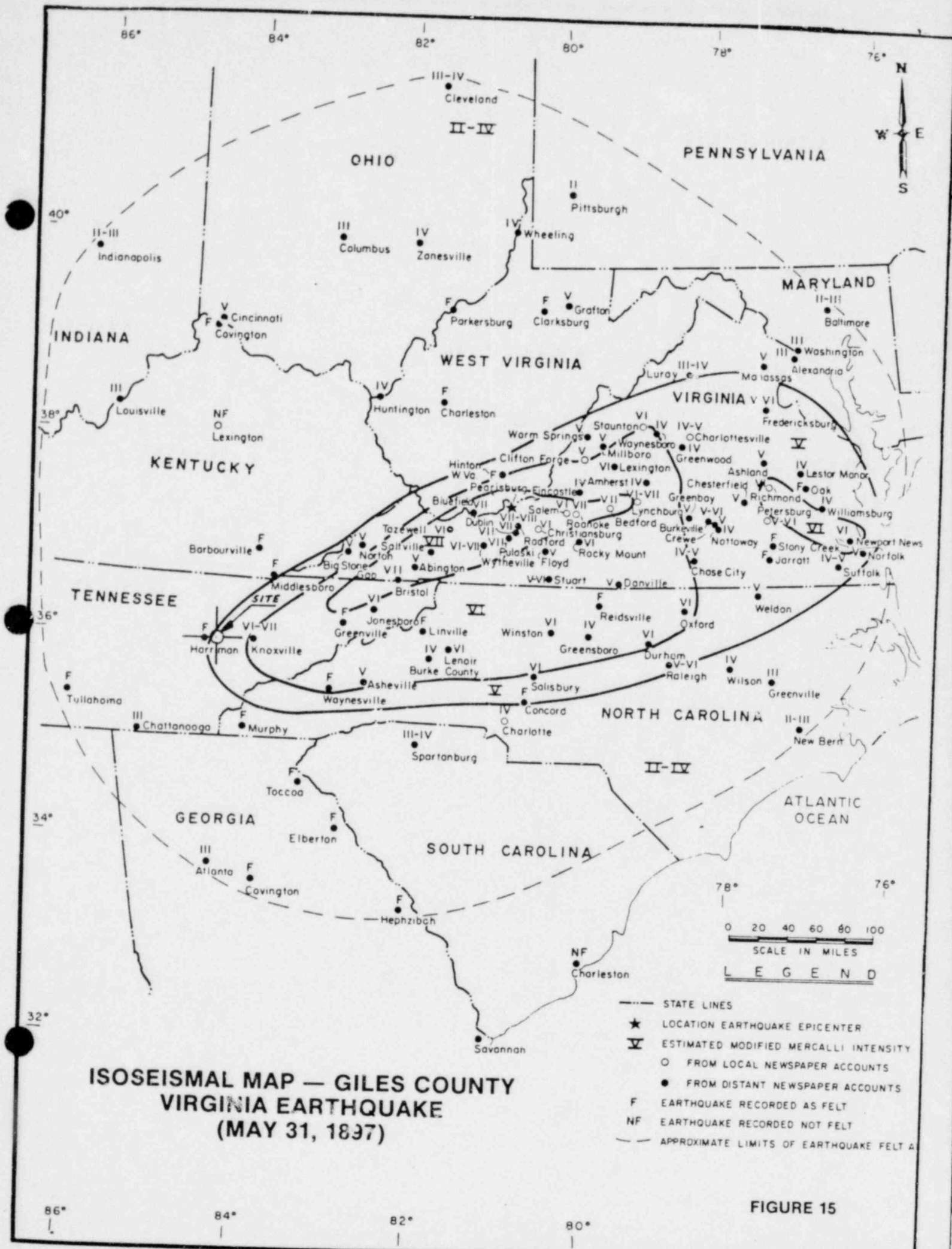


TECTONIC PROVINCE MAP

FIGURE 14

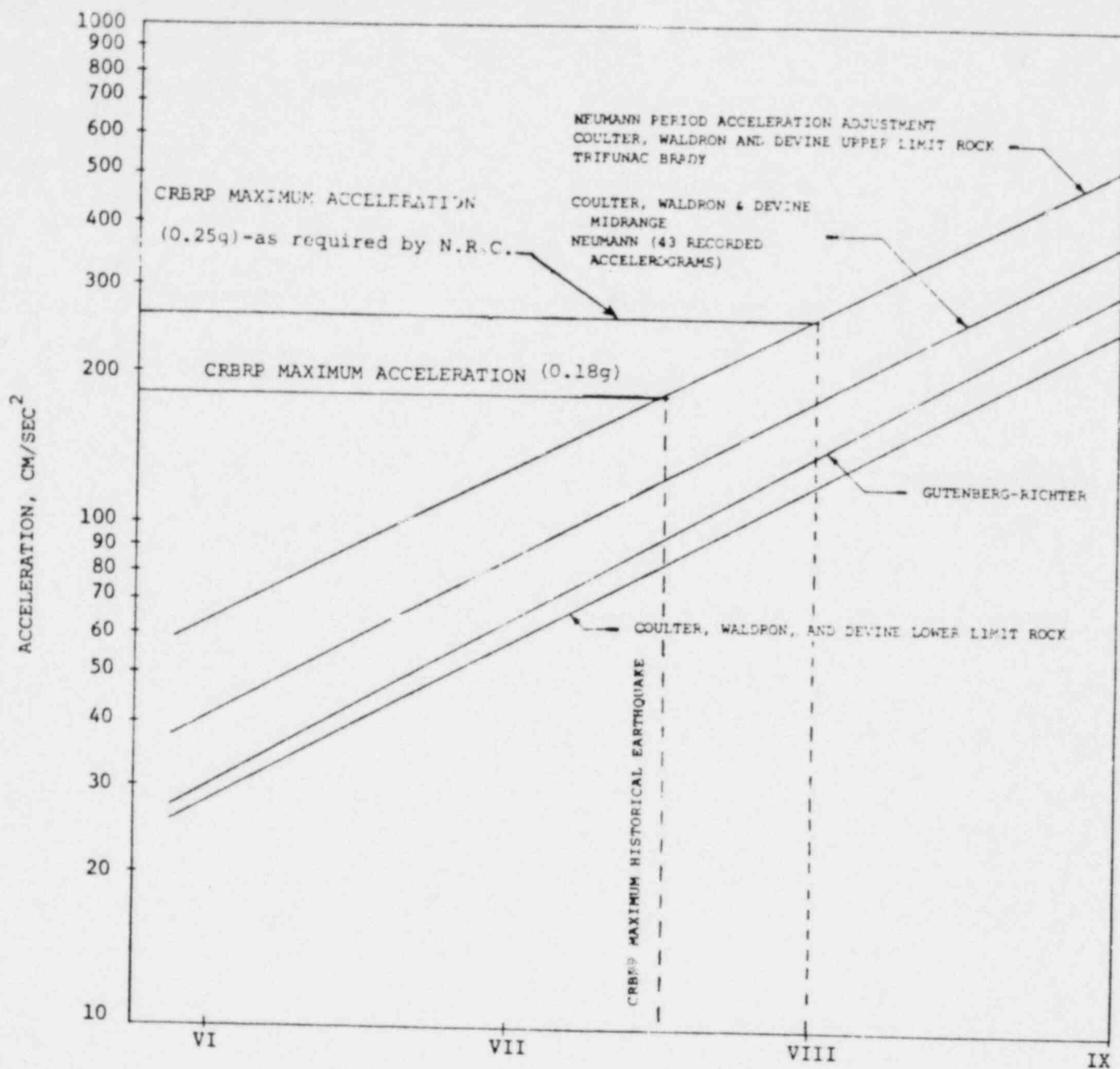
INDEPENDENT ASSESSMENT OF GILES COUNTY EARTHQUAKE

- **ISOSEISMAL MAP DEVELOPED BASED ON MODIFIED MERCALLI INTENSITY EFFECTS**
- **CONSULTATION WITH RECOGNIZED AUTHORITIES ON SOUTHEASTERN U.S. SEISMICITY**
- **CONSENSUS OF GEOLOGICAL OPINION THAT GILES COUNTY EARTHQUAKE SHOULD BE CLASSIFIED AS INTENSITY VII-VIII**



SELECTION OF SSE AND OBE

- GILES COUNTY EQ. CLASSIFIED AS INTENSITY VIII BY NRC FOR THE SITE
- SELECTION OF ACCELERATION/INTENSITY RELATIONSHIP
- MAXIMUM GROUND ACCELERATION — $0.25g$ USED IN DESIGN FOR S.S.E.
- MAXIMUM GROUND ACCELERATION — $0.125g$ USED IN DESIGN FOR O.B.E.



ACCELERATION — INTENSITY RELATIONSHIP
SELECTION OF SSE

FIGURE 16

SUMMARY

INHERENT CONSERVATISM IN DESIGN

- **EXTENSIVE GEOLOGIC, GEOTECHNICAL, AND SEISMOLOGIC INVESTIGATIONS**
- **INTENSITY VIII EARTHQUAKE USED INSTEAD OF VII-VIII**
- **CONSERVATIVE INTENSITY/ACCELERATION RELATIONSHIP USED**
- **O.B.E. SELECTED AT 1/2 (S.S.E.)**

BRIEFING FOR
ADVISORY COMMITTEE ON
REACTOR SAFEGUARDS (ACRS)

SEISMIC DESIGN

Presented by

A.T. DAJANI

Assistant Project Manager
Engineering and Design
CRBRP Project



BURNS AND ROE, INC.

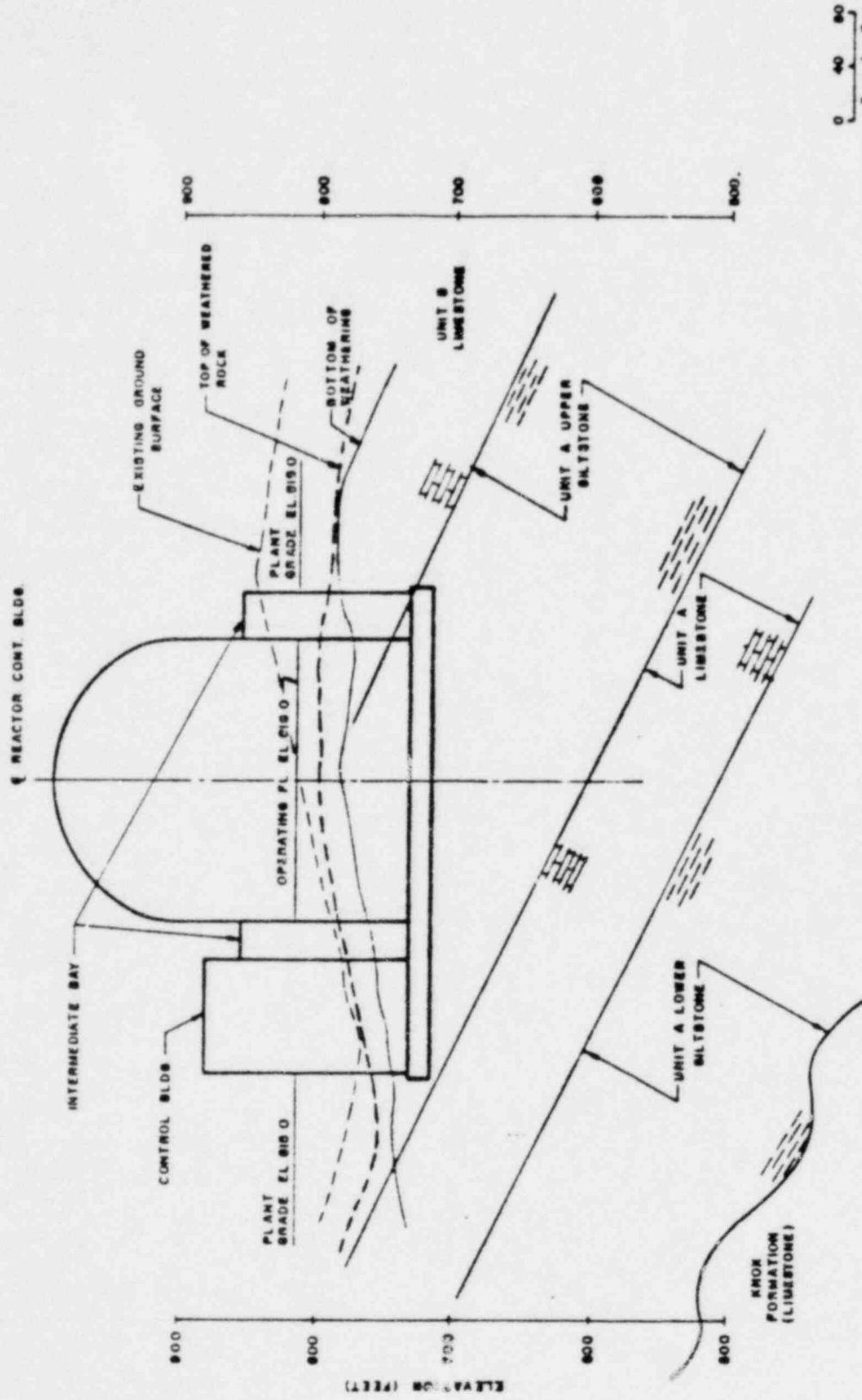
T 3, 75

OUTLINE

- **SITE CHARACTERISTICS**
- **APPLICABLE CODES AND STANDARDS**
- **SEISMIC CLASSIFICATION**
- **NUCLEAR ISLAND**
- **OTHER MAJOR CATEGORY I STRUCTURES**
- **CATEGORY III STRUCTURES**
- **SUMMARY**

SITE CHARACTERISTICS

- INCLINED LAYERS OF SILTSTONE AND LIMESTONE
- FINISHED GRADE ELEVATION 815 FEET
- TOP OF SOUND ROCK APPROXIMATELY 80 FEET BELOW GRADE
- NUCLEAR ISLAND FOUNDATION MAT BOTTOM AT ELEVATION 715
- SSE, ZERO PERIOD ACCELERATION: 0.25G
- OBE, ZERO PERIOD ACCELERATION: 0.125G



CROSS SECTION - NUCLEAR ISLAND

SEISMIC DESIGN APPLICABLE CODES AND STANDARDS

REGULATORY GUIDE 1.60

- **DESIGN RESPONSE SPECTRA FOR SEISMIC DESIGN OF
NUCLEAR POWER PLANTS**

REGULATORY GUIDE 1.61

- **DAMPING VALUE FOR SEISMIC DESIGN OF NUCLEAR POWER
PLANTS**

REGULATORY GUIDE 1.92

- **COMBINATION OF MODES AND SPATIAL COMPONENTS IN
SEISMIC RESPONSE ANALYSIS**

REGULATORY GUIDE 1.122

- **DEVELOPMENT OF FLOOR DESIGN RESPONSE SPECTRA FOR
SEISMIC DESIGN OF FLOOR SUPPORTED EQUIPMENT OR
COMPONENTS**

SRP NUREG-75/087 SECTIONS 3.7.1 AND 3.7.2

PSAR APPENDIX 3.7A — CRBRP — SEISMIC DESIGN CRITERIA

SEISMIC CLASSIFICATION OF STRUCTURES SYSTEMS AND COMPONENTS

- **SEISMIC CATEGORY I**
 - **REQUIRED TO PERFORM THEIR SAFETY FUNCTION FOR SSE MOTIONS**
 - **DESIGNED FOR OBE AND SSE**
- **SEISMIC CATEGORY II**
 - **REQUIRED TO PERMIT CONTINUED REACTOR OPERATION**
 - **TO PROTECT INVESTMENT AND ASSURE CONTINUANCE OF PRIORITY PROGRAMS**
 - **DESIGNED FOR OBE**
- **SEISMIC CATEGORY III**
 - **STANDARD BUILDING CODE, ZONE 2**
 - **TO PREVENT DAMAGE TO CATEGORY I STRUCTURES, THE ADJACENT TURBINE GENERATOR & RADWASTE BUILDINGS ANALYZED AND DESIGNED FOR SSE**

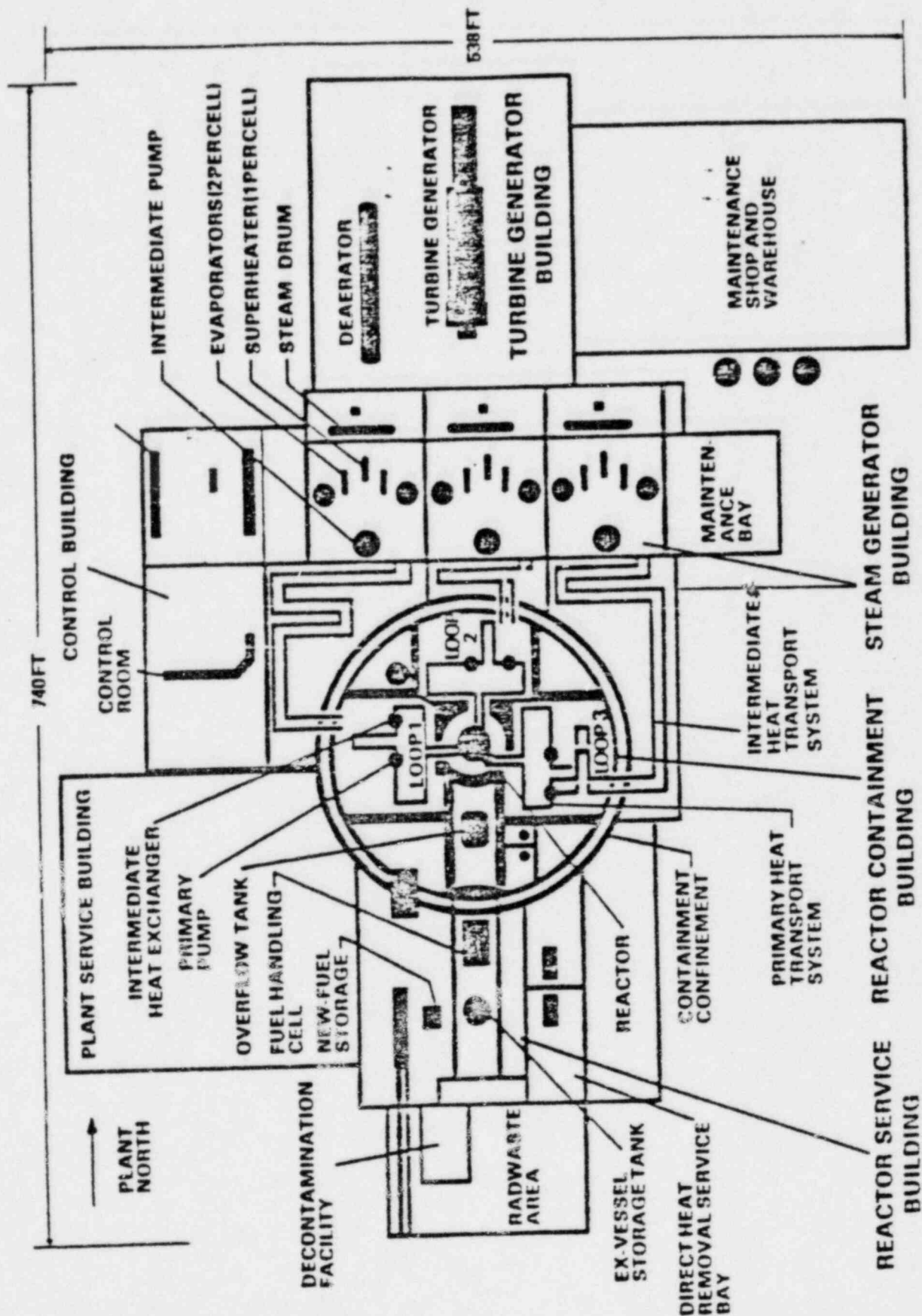
MAIN STRUCTURES

STRUCTURE	SEISMIC CATEGORY	FOUNDATION CONDITIONS
NUCLEAR ISLAND	I	ROCK
EMERGENCY COOLING TOWER	I	ROCK
DIESEL GENERATOR BUILDING	I	SOIL
TURBINE-GENERATOR BUILDING	III — ADJACENT TO CATEGORY I	SOIL
RADWASTE BUILDING	III — ADJACENT TO CATEGORY I	SOIL — ROCK

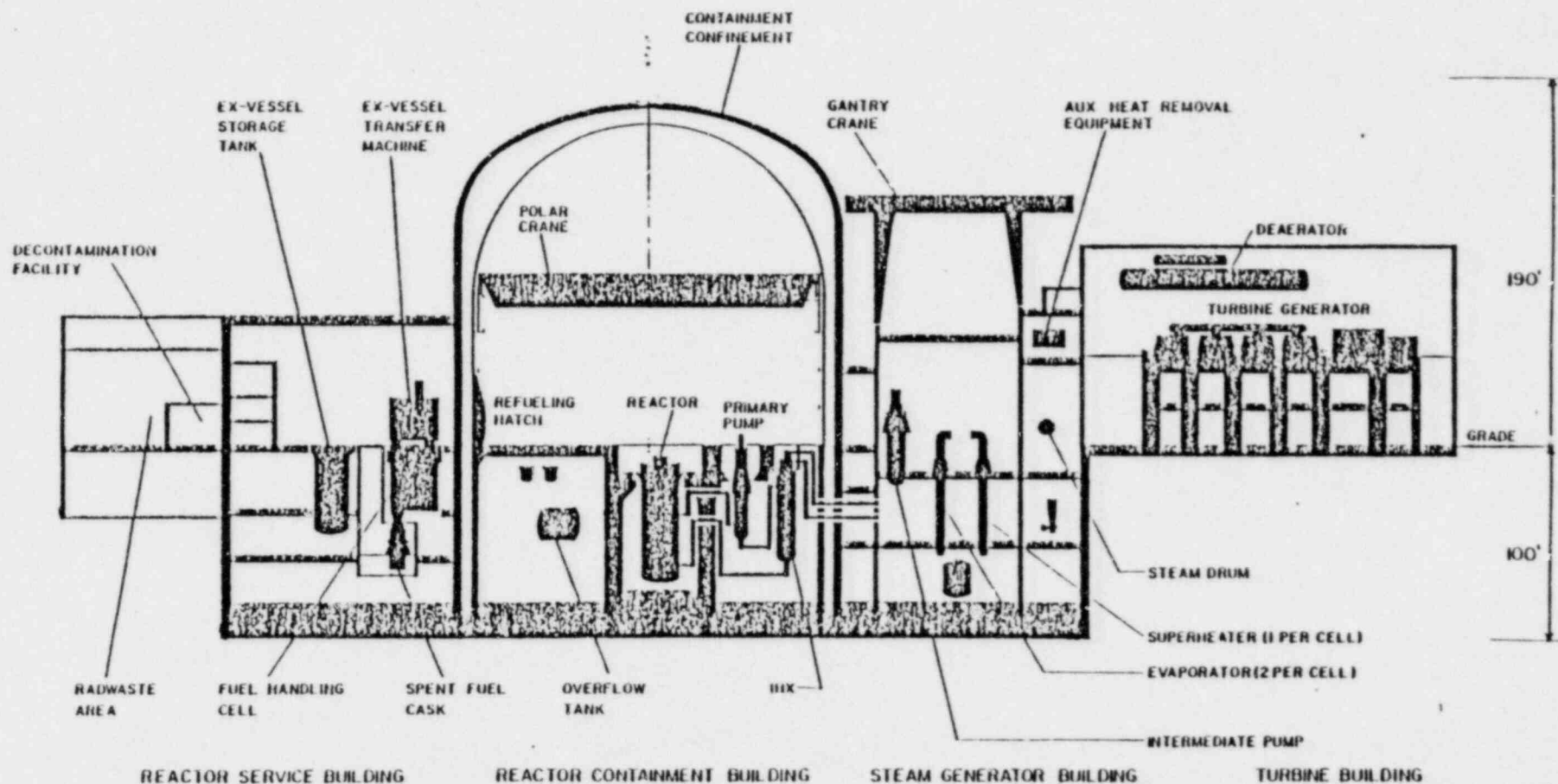
NUCLEAR ISLAND

- INTERCONNECTED STRUCTURES
- COMMON FOUNDATION MAT
- BUILDINGS IN NUCLEAR ISLAND
 - REACTOR CONTAINMENT
 - CONFINEMENT
 - STEAM GENERATOR
 - CONTROL
 - ELECTRICAL EQUIPMENT BUILDING
 - REACTOR SERVICE
- FOUNDATION MAT
 - LENGTH (MAXIMUM): 475 FEET
 - WIDTH (MAXIMUM): 360 FEET
 - THICKNESS: 15 FEET

CRBRP OVERALL LAYOUT (PLAN VIEW)

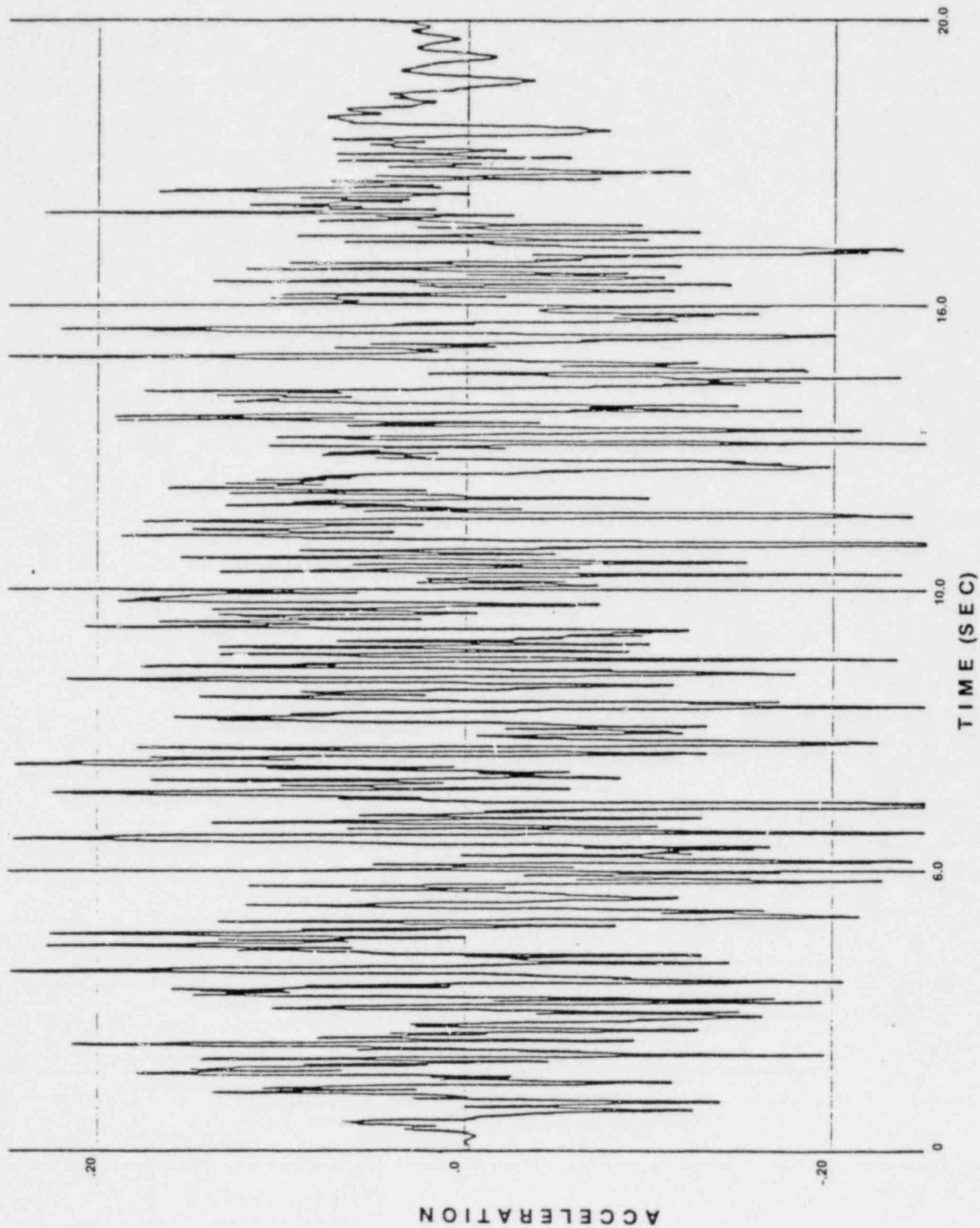


CLINCH RIVER BREEDER REACTOR PLANT (Overall Plant Layout — Section)



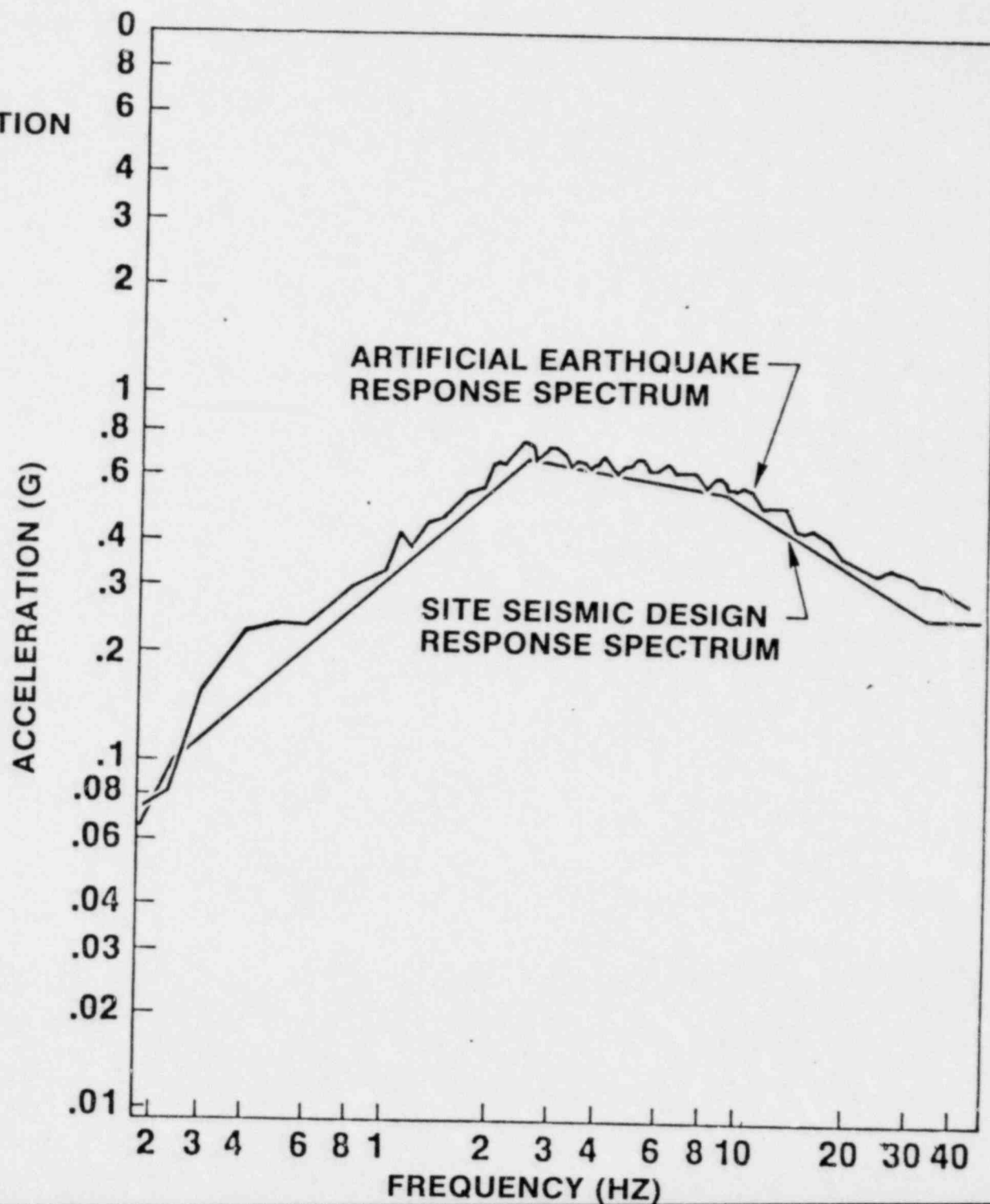
INPUT MOTIONS

- THREE STATISTICALLY INDEPENDENT ARTIFICIAL ACCELERATION TIME-HISTORIES: NORTH-SOUTH, EAST-WEST AND VERTICAL
- ARTIFICIAL ACCELERATION TIME-HISTORY SPECTRA ENVELOPE REGULATORY GUIDE 1.60 SPECTRA NORMALIZED TO A ZERO PERIOD ACCELERATION OF 0.25g FOR THE SSE
- DURATION OF TIME HISTORIES: 20 SECONDS, DIGITIZED AT 0.01 SECOND INTERVALS
- ONE SECOND BUILD-UP OF STRONG MOTION, THREE SECONDS DECAY



HORIZONTAL MOTION A SSE GROUND ACCELERATION TIME-HISTORY

GROUND ACCELERATION
DEVELOPMENT



NUCLEAR ISLAND METHOD OF ANALYSIS

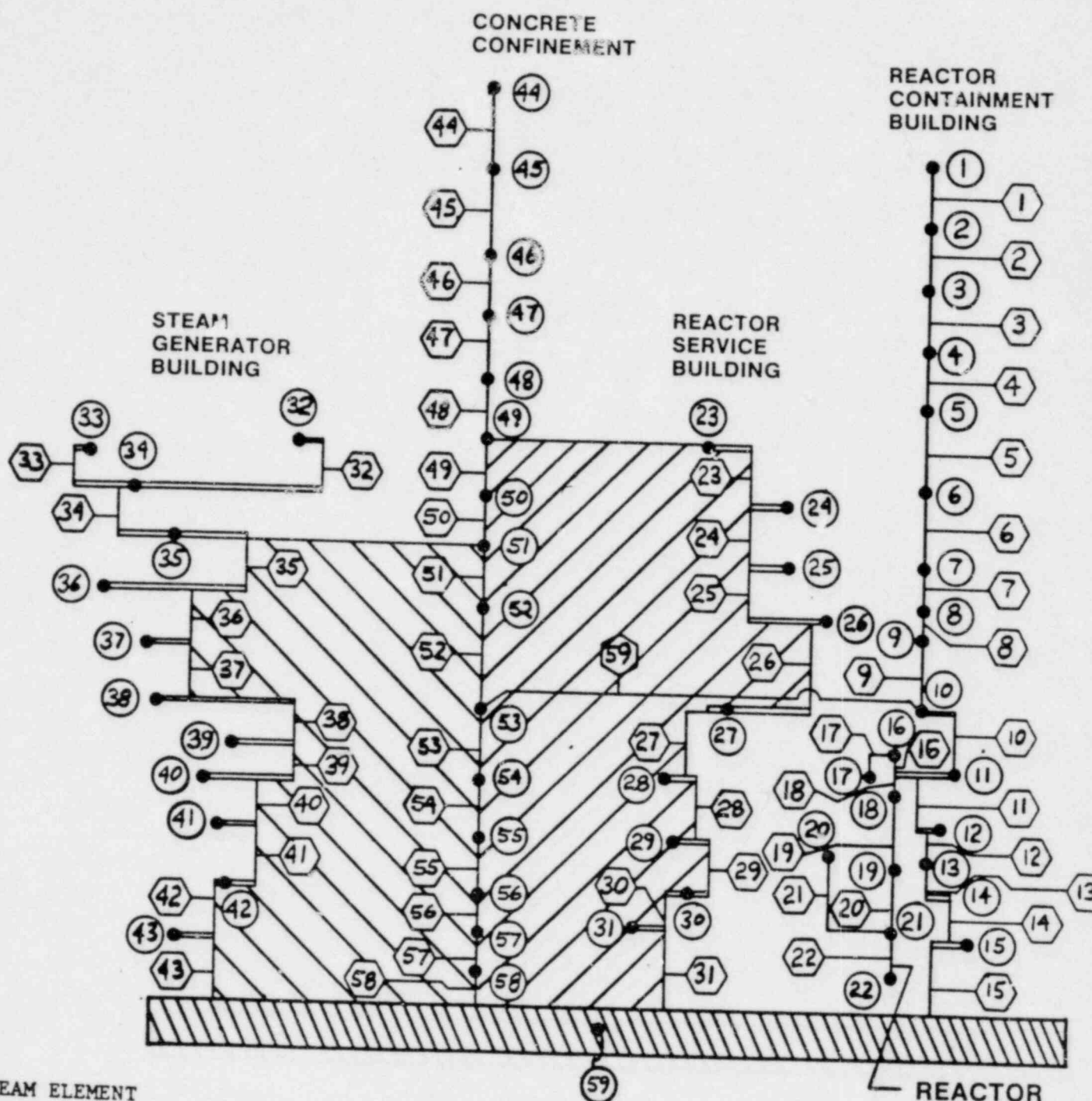
- LUMPED MASS WITH DIRECT INTEGRATION OF COUPLED EQUATIONS OF MOTION
- FOUNDATION SPRINGS AND DAMPERS CALCULATED BY A STATIC FINITE ELEMENT ANALYSIS USING THE COMPUTER PROGRAM STARDYNE AND BY HALF-SPACE THEORY
- MAXIMUM DIRECTIONAL EFFECTS COMBINED BY SQUARE ROOT OF THE SUM OF THE SQUARES
- DEGREES OF FREEDOM INCLUDE TRANSLATIONS AND ROTATIONS IN THREE DIRECTIONS

NUCLEAR ISLAND SEISMIC MATHEMATICAL MODEL

- INDEPENDENT ANALYSIS FOR EACH OF THE THREE ORTHOGONAL DIRECTIONS
- FOUR MAIN STICKS: CONTAINMENT BUILDING, CONFINEMENT, REACTOR SERVICE BUILDING AND STEAM GENERATOR BUILDINGS
- POLAR CRANE AND REACTOR VESSEL REPRESENTED IN MODEL
- FLEXIBLE TIES BETWEEN THE CONFINEMENT, REACTOR SERVICE AND STEAM GENERATOR BUILDING CANTILEVERS AT ALL ELEVATIONS, CALCULATED BY FINITE ELEMENT ANALYSIS WITH STARDYNE. REACTOR CONTAINMENT BUILDING TIED AT FOUNDATION AND OPERATING FLOOR LEVELS ONLY.
- MASS POINTS LOCATED AT CENTERS OF MASS

NUCLEAR ISLAND SEISMIC MATHEMATICAL MODEL (Cont'd.)

- **MASSLESS MEMBERS LOCATED AT CENTER OF RIGIDITY**
- **ANALYSES FOR UPPER BOUND AND LOWER BOUND OF ROCK PROPERTIES. RESULTS OF BOTH WERE ENVELOPED.**
- **RESPONSE SPECTRA AND ACCELERATION AND DISPLACEMENT TIME-HISTORIES PRODUCED AT MASS POINTS**
- **DESIGN RESPONSE SPECTRA PRODUCED BY ENVELOPING AND SMOOTHENING UPPER AND LOWER BOUND SPECTRA, WITH PEAKS WIDENED BY $\pm 10\%$**
- **TRANSLATIONAL AND ROTATIONAL SPECTRA COMBINED TO CALCULATE RESPONSE SPECTRA AT POINTS AWAY FROM MASS POINTS**



CRBRP BUILDING MATHEMATICAL MODEL
FOR THE N-S EARTHQUAKE

EVALUATION OF NUCLEAR ISLAND STRUCTURES FOR SEISMIC LOADS

- **LOAD COMBINATIONS IN ACCORDANCE WITH CODES AND GUIDELINES**
- **AISC AND ACI-349 CODES USED FOR STEEL AND CONCRETE STRUCTURES RESPECTIVELY**
- **IN GENERAL ALL STRUCTURES CONTROLLED BY OBE**
- **MANY STRUCTURAL COMPONENTS ARE CONTROLLED BY CONDITIONS OTHER THAN SEISMIC SUCH AS DBA's, SHIELDING, AND TMBDB (REACTOR CAVITY, CONFINEMENT)**

SEISMIC ANALYSIS OTHER MAJOR CATEGORY I STRUCTURES

- **EMERGENCY COOLING TOWER**
 - **SUPPORTED ON ROCK**
 - **LUMPED MASS ANALYSIS**
 - **RANGE OF ROCK/SOIL PROPERTIES**
 - **FLUID STRUCTURE INTERACTION IN ACCORDANCE WITH HAUSNER'S THEORY**
- **DIESEL GENERATOR BUILDING**
 - **SUPPORTED ON SOIL**
 - **SOIL STRUCTURE INTERACTION BY FINITE ELEMENT (FLUSH)**
 - **DETAILED IN-STRUCTURE RESPONSES BY THREE DIMENSIONAL LUMPED MASS ANALYSIS**
 - **RANGE OF SOIL PROPERTIES**

SEISMIC ANALYSIS CATEGORY III STRUCTURES ADJACENT TO CATEGORY I

- TO PROTECT ADJACENT CATEGORY I, STRUCTURES WERE ANALYZED AND DESIGNED FOR SSE
- TURBINE GENERATOR BUILDING
 - SUPPORTED ON SOIL
 - SOIL STRUCTURE INTERACTION BY FINITE ELEMENT (FLUSH)
 - FORCES IN STRUCTURE BY THREE DIMENSIONAL ANALYSIS
- RADWASTE BUILDING
 - SUPPORTED PART ON SOIL AND PART ON ROCK
 - SOIL/ROCK STRUCTURE INTERACTION BY FINITE ELEMENT (FLUSH)
 - FORCES IN STRUCTURE BY THREE DIMENSIONAL ANALYSIS

SUMMARY CONSERVATISMS IN STRUCTURES

- LARGEST HISTORICAL EARTHQUAKE IN TECTONIC PROVINCE ASSUMED TO OCCUR AT CRBRP SITE
- SSE INCREASED FROM 0.18G TO 0.25G
- DESIGN RESPONSE SPECTRA CONSISTS OF SMOOTH WIDE BAND ENVELOPE SPECTRA BASED ON STATISTICAL STUDIES OF MANY PAST EARTHQUAKE RECORDS
- ARTIFICIAL ACCELERATION TIME-HISTORIES USED IN ANALYSIS ENVELOPED AND FOR MOST FREQUENCIES ARE ABOVE THE DESIGN RESPONSE SPECTRA
- LINEAR SEISMIC ANALYSIS USED DOES NOT CONSIDER SUBSTANTIAL RESERVE STRENGTH IN THE INELASTIC RANGE
- APPLICATION OF SAFETY FACTORS REQUIRED BY CODES
- USE OF MINIMUM TEST VALUES IN STRENGTH OF STRUCTURAL MATERIALS
 - ACTUAL YIELD STRENGTH VALUES FOR STRUCTURAL AND REINFORCING STEEL ARE, IN GENERAL, HIGHER
 - COMPRESSION STRENGTH OF CONCRETE AT 28 DAYS DISREGARDING SUBSTANTIAL INCREASE OF STRENGTH WITH AGE

SUMMARY

CONSERVATISMS IN STRUCTURES (Cont'd.)

- **USE OF STATIC STRENGTH OF STRUCTURAL MATERIALS IN LIEU OF THE GREATER DYNAMIC STRENGTH, WHEN ACTUAL SEISMIC LOAD IS DYNAMIC**
- **TO SIMPLIFY CONSTRUCTION, STRUCTURAL MEMBER SIZES ARE DUPLICATED RESULTING IN STRONGER THAN REQUIRED STRUCTURAL SHAPES OR REINFORCED CONCRETE SECTIONS IN MANY AREAS**
- **STRUCTURAL SECTIONS IN GENERAL CONTROLLED BY OBE PROVIDING ADDITIONAL MARGIN FOR THE SSE**
- **MANY STRUCTURAL ELEMENTS ARE CONTROLLED BY REQUIREMENTS OTHER THAN SEISMIC**
 - **SHIELDING, STIFFNESS, TMBDB, DBA**
 - **EXAMPLE, REACTOR CAVITY CONTROLLED BY SHIELDING AND TMBDB, CONFINEMENT BY SHIELDING, ETC.**
- **INTERCONNECTED STRUCTURES ON COMMON FOUNDATION MAT AND MULTIPLE INTERCONNECTED CELLS IN BUILDINGS TEND TO INCREASE OVERALL SEISMIC CAPACITY**
 - **REDUNDANT LOAD PATHS ARE PROVIDED**

SEISMIC DESIGN OF SYSTEMS AND COMPONENTS

Systems And Components Seismic Design Criteria

- Seismic classification and qualification
- Seismic input development
- Damping
- Load combinations
- Seismic test requirements and procedures

T8, T9

Morrone
T8

SEISMIC CLASSIFICATION

Seismic Category I:

Designed to perform safety functions for the SSE and remain functional for the OBE

- Assure integrity of reactor coolant pressure boundary
- Provide capability for reactor shutdown
- Provide capability to prevent or mitigate accident consequences

Seismic Category II*:

Designed to remain functional for the OBE

- Permit continued reactor operation
- Protect plant investment

Seismic Category III*:

Local design criteria

- Maintain support of normal operations

* Must be designed for no gross structural failure under SSE loads for protection of Seismic Category I components when applicable

SEISMIC QUALIFICATION

Analysis

Seismic Category I and II

Detailed Dynamic Analyses

- Response spectrum method
- Time history method

Conservative simplified methods

Seismic Category III

Static Analysis

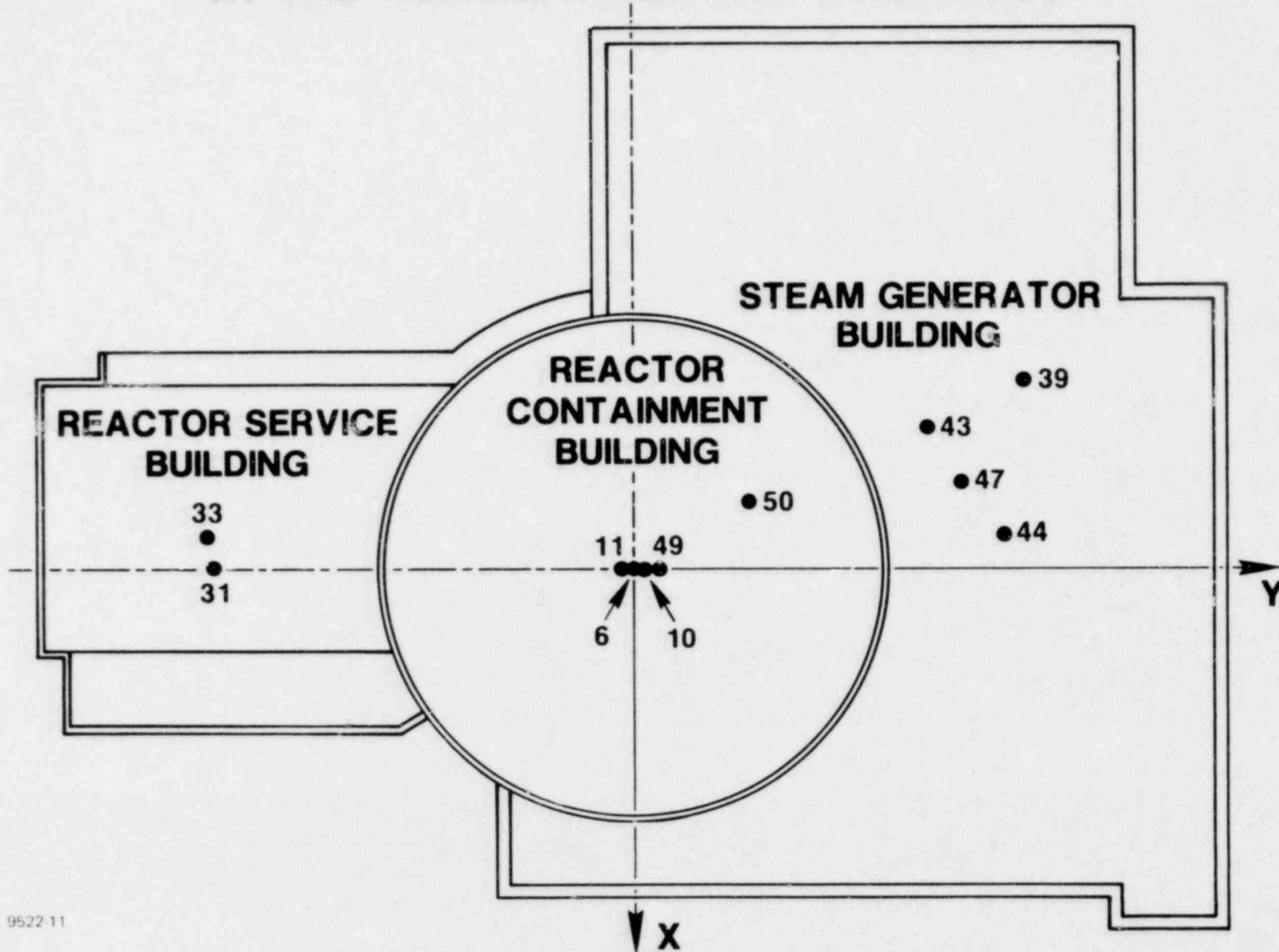
- Standard building code, zone 2
- Local codes

Testing

Seismic Category I

- Multiple frequency tests
- Single frequency tests at resonance
- Envelop required response spectrum with test response spectrum

LOCATION OF HORIZONTAL NODES IN THE NUCLEAR ISLAND BUILDINGS



SEISMIC INPUT FOR SYSTEMS AND COMPONENTS

- Responses obtained from building analysis in three independent directions
- Seven spectra and time histories for each node (3 translation, 2 torsion, 2 rotation)
- 28 spectra and time histories for OBE, SSE and upper and lower bounds of soil moduli
- Input applied individually in each direction for combining responses by SRSS

SIMPLIFIED SPECTRA PROCEDURE

- Seven spectra reduced to three spectra
- Combine translational, torsional and rotational spectra by SRSS
- Combine resulting responses by absolute sum
- Always conservative
- Results in combining directional effects absolutely instead of by SRSS when cross coupling terms are small

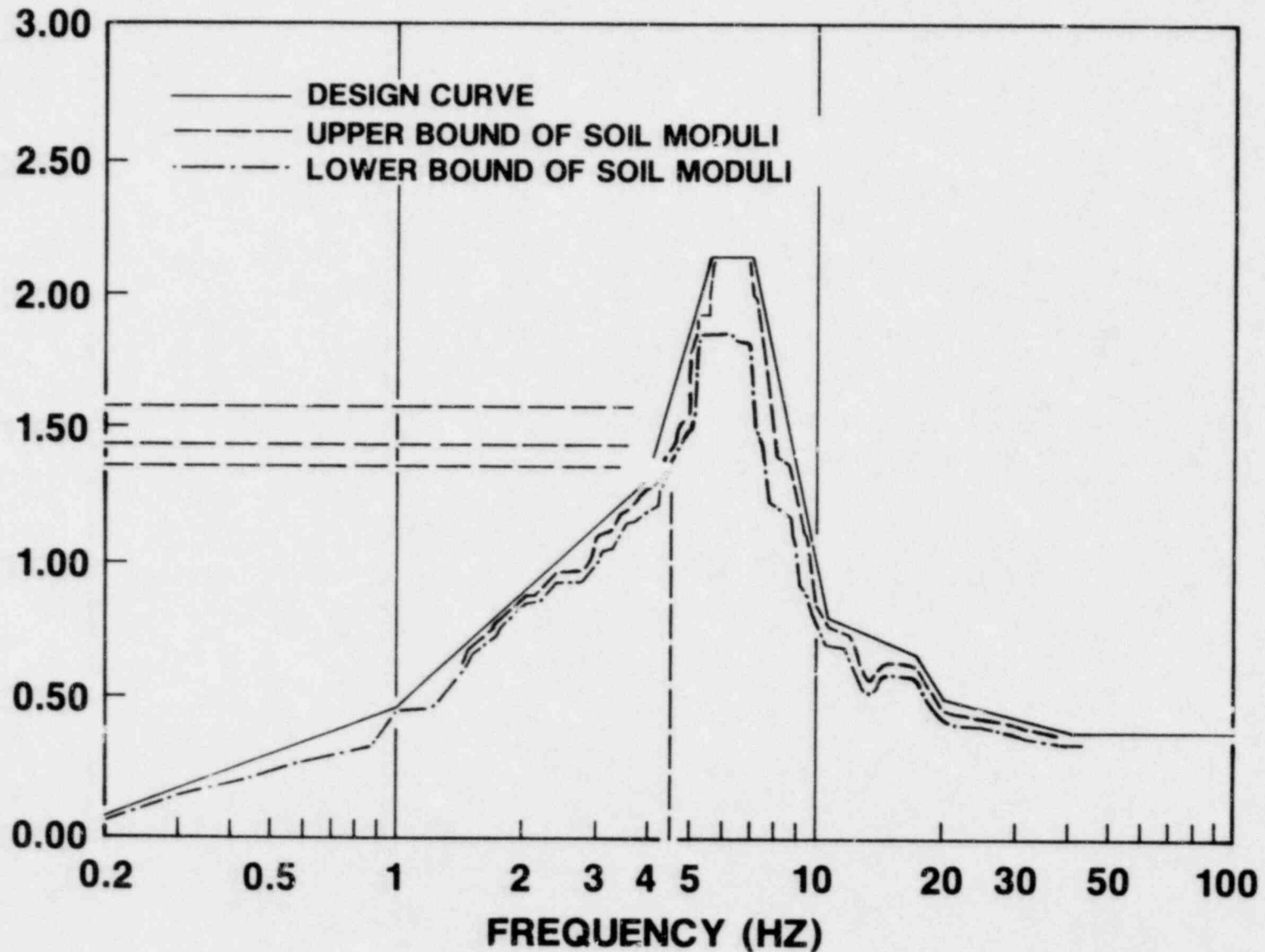
DESIGN SPECTRA

- Envelop upper and lower bounds of soil moduli
- Peaks widened for uncertainties
- Spectra smoothed to eliminate valleys and spectral fluctuations
- Results in conservative design spectra

Test
19

RESPONSE SPECTRA ENVELOPING PROCEDURE

ACCELERATION (G)



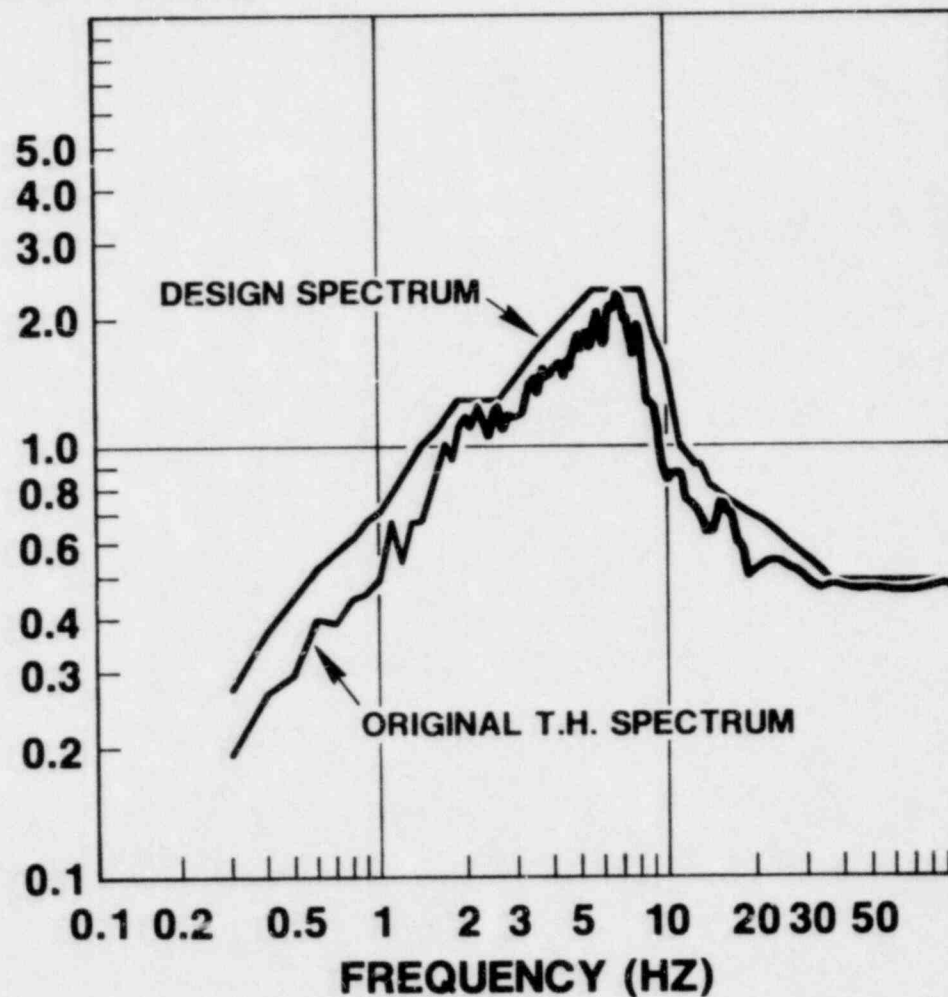
DESIGN HISTORIES

- Possible frequency variations of building
- Vary Δt , compress and expand history
- Develop spectra-consistent synthetic histories
- Results in conservative design histories

**SSE E-W HORIZONTAL + TORSIONAL
COMBINED—DESIGN AND ORIGINAL T.H.
RESPONSE SPECTRA AT R.V. SUPPORTS, EL.
800 FT.**

(3% CRITICAL DAMPING)

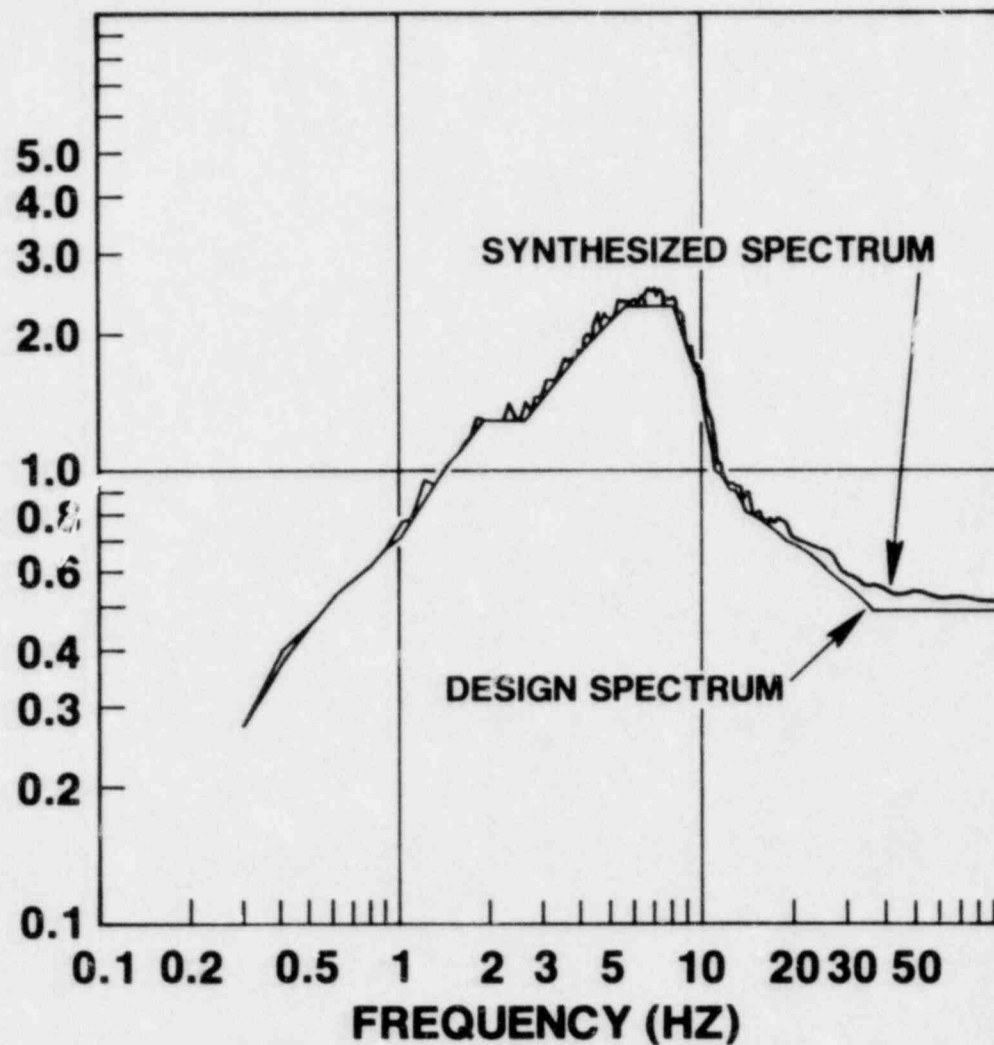
ACCELERATION (G)



SSE EW COMBINED HORIZONTAL AND TORSION- DESIGN AND SYNTHESIZED RESPONSE SPECTRA

(3% CRITICAL DAMPING)

ACCELERATION (G)



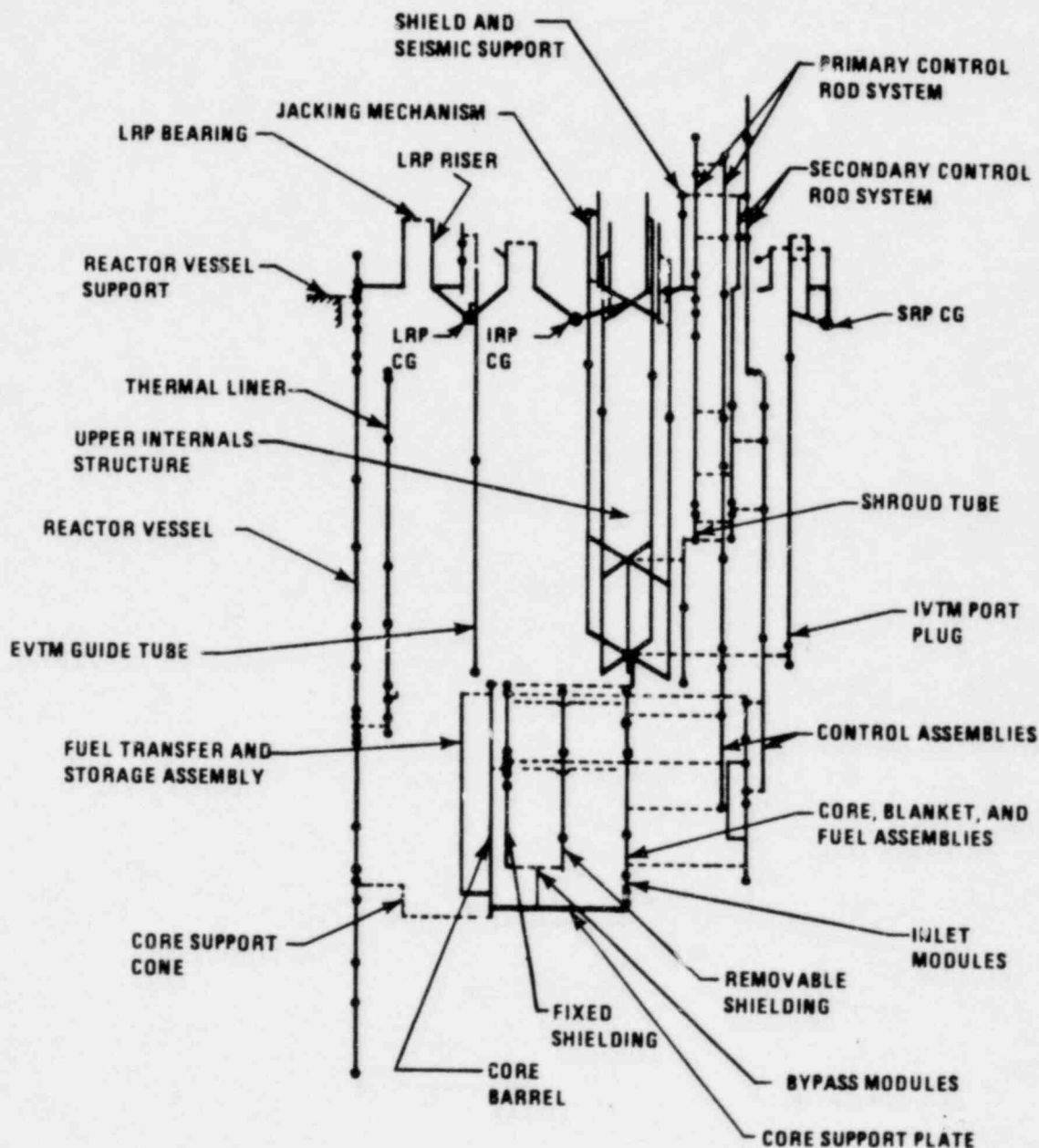
COMPONENTS SEISMIC INPUT

- Model and analysis of system
- Input design histories
- Output response histories and response spectra for dynamic analysis of components
- Again widen and smooth components spectra
- Input design spectra
- Output loads for components design

LEGEND:

SRP = SMALL ROTATING PLUG
 IRP = INTERMEDIATE ROTATING PLUG
 LRP = LARGE ROTATING PLUG

CG = CENTER OF GRAVITY
 IVTM = IN-VESSEL TRANSFER MACHINE
 EVTM = EX-VESSEL TRANSFER MACHINE



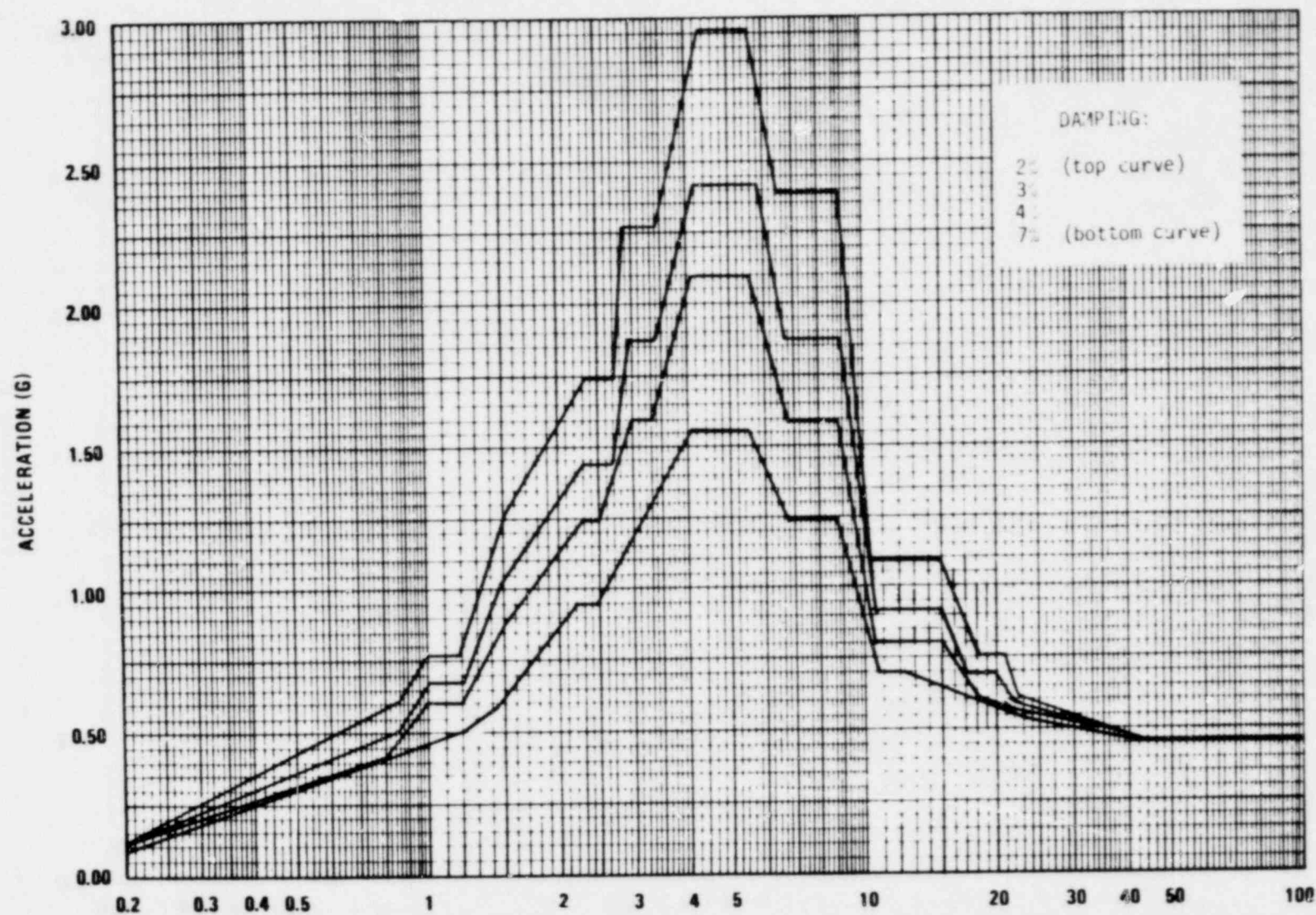
SCHEMATIC OF REACTOR SYSTEM SEISMIC MODEL

DAMPING VALUES

Structural System	Damping Values ⁽¹⁾ (Percent Of Critical)	
	Operating Basis Earthquake	Safe Shutdown Earthquake
Equipment and large diameter piping systems (> 12 in. nominal diameter)	2.0	3.0
Small diameter piping system (≤ 12 in. nominal diameter)	1.0	2.0
Welded steel structures	2.0	4.0
Bolted or riveted steel structures	4.0	7.0
Prestressed concrete structures	2.0	5.0
Reinforced concrete structures	4.0	7.0

(1) Reduced damping values should be used when combined stresses are considerably below 1/2 yield for the OBE and yield for the SSE.

CRBRP SSE HORIZONTAL E-W DESIGN RESPONSE
SPECTRA FOR REACTOR CONTAINMENT BUILDING AT EL. 816'



BASIC SEISMIC LOAD COMBINATIONS **(Seismic Category I Vessels, Piping** **And Non-Active Pumps And Valves)**

Upset (Level B) Condition:

$D + L + \text{Operating} + \text{Thermal} + \text{Transients} + \text{OBE}$

Faulted (Level D) Condition:

$D + L + \text{Operating} + \text{Thermal} + \text{Transients} + \text{SSE} + \text{DSL}^*$

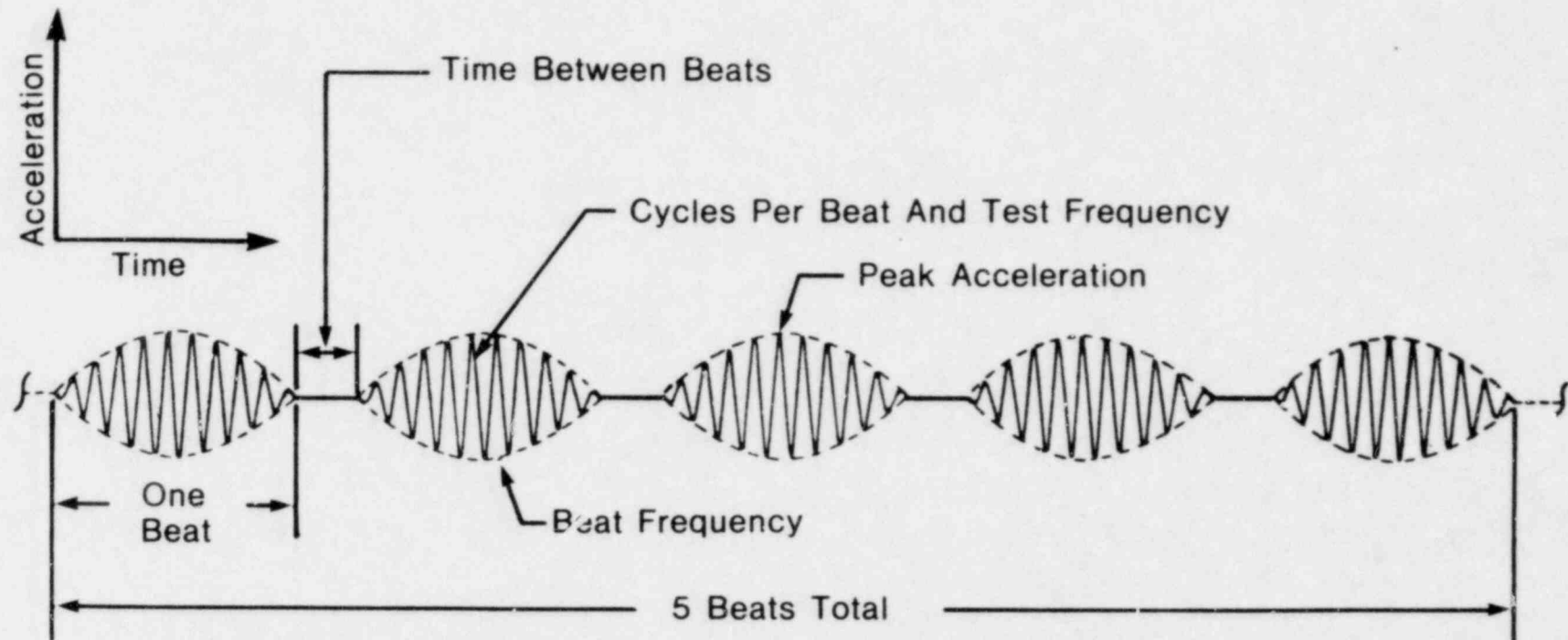
- For active pumps and valves all loadings are upset condition

*Dynamic system loadings associated with pipe leak/rupture loads

SEISMIC TESTING FOR CLASS 1E EQUIPMENT

- Qualify to IEEE std. 344-1975
- Single frequency tests
- Multiple frequency tests
- Single frequency plus multiple frequency
- Multiple frequency and recommended single frequency

SINE BEAT INPUT FOR TESTING



BASIC SEISMIC TEST PROCEDURE

Single Frequency Sine Beat Tests

- Frequency search from 1-33 Hz
- SSE sine beat tests at natural frequencies and 1/2 octave intervals
- Five beats motion with 10 cycles/beat
- Shake table motion maximum acceleration equal to ZPA of RRS
- TRS maximum response acceleration greater than RRS
- One OBE test preceding SSE test at each frequency
- Independent direction input

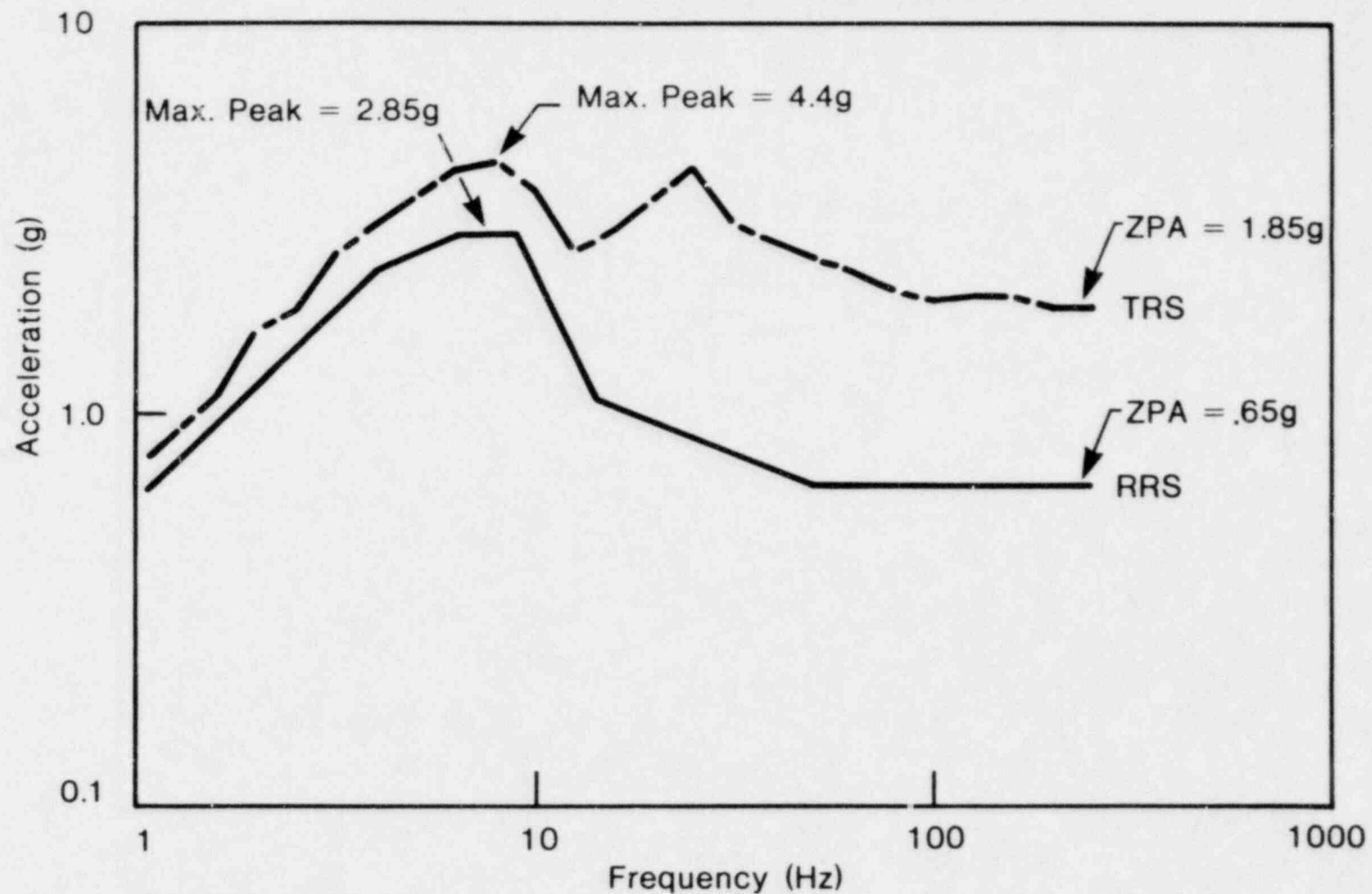
Multiple Frequency Tests

- IEEE std. 344-1975
- Five OBE and one SSE
- Random motion
- Biaxial direction input
- Envelop RRS with TRS

EXAMPLE OF COMPARISON OF TRS/RRS FOR TESTED EQUIPMENT

- Reactor shutdown and isolation equipment
- Housed in cabinets and whole cabinet shake table tested
- Both sine beat unidirectional and multiple frequency biaxial motion
- Cabinet rotated 90°
- Functioned properly during and after testing
- TRS conservatively enveloped RRS
- Additional conservatism by enveloping horizontal RRS, 10% IEEE-323 margin and use of design spectra

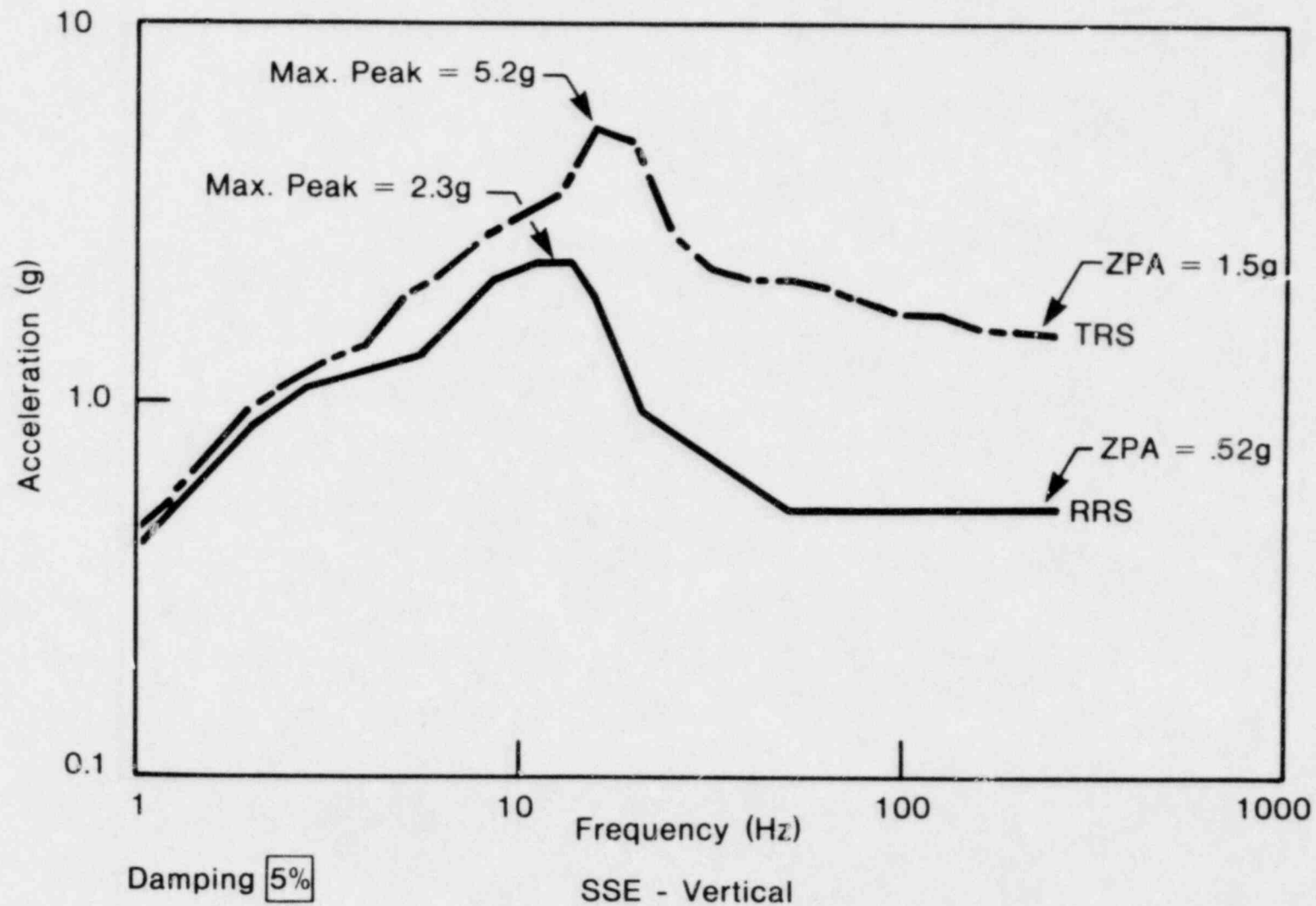
PRIMARY REACTOR SHUTDOWN SYSTEM COMPARATOR/BUFFER CABINET AND LOGIC CABINET ASSEMBLIES



SSE - Horizontal

7230-1

PRIMARY REACTOR SHUTDOWN SYSTEM COMPARATOR/BUFFER CABINET AND LOGIC CABINET ASSEMBLIES



SUMMARY OF CONSERVATISM IN SEISMIC CRITERIA

Simplified Spectra

- Conservatism approaches absolute sum versus SRSS of directional effects
- 1.5 peak for static analysis

Design Spectra

- Upper and lower bounds enveloped
- Valleys eliminated
- Spectra widened and smoothed

Design Histories

- Design spectra-consistent histories
- Conservatively envelop design spectra
- Combine translational and torsional design spectra

SUMMARY OF CONSERVATISM IN SEISMIC CRITERIA (Continued)

Components Spectra

- Spectra additionally widened and smoothed with conservative input
- Envelop three operating conditions

Damping

- Damping values of systems and components
- 3% versus 4% of critical

Seismic Testing

- Both single frequency and multiple frequency testing
- Both unidirectional and biaxial
- ZPA and peak responses of TRS higher than RRS
- Design spectra RSS
- Envelop N-S and E-W RRS
- 10% IEEE-323 margin

SEISMIC REQUIREMENTS

IEEE 344

EQUIPMENT
SPECIFICATION

DEMONSTRATE AN EQUIPMENT'S ABILITY
TO PERFORM ITS REQUIRED SAFETY
FUNCTION DURING AND AFTER AN SSE

- A. TESTING
 - 1. SINE BEATS AND
 - 2. RANDOM MULTI
FREQUENCY
- B. ANALYSIS/TESTING
- C. ANALYSIS

TYPICAL PPS INSTRUMENTATION

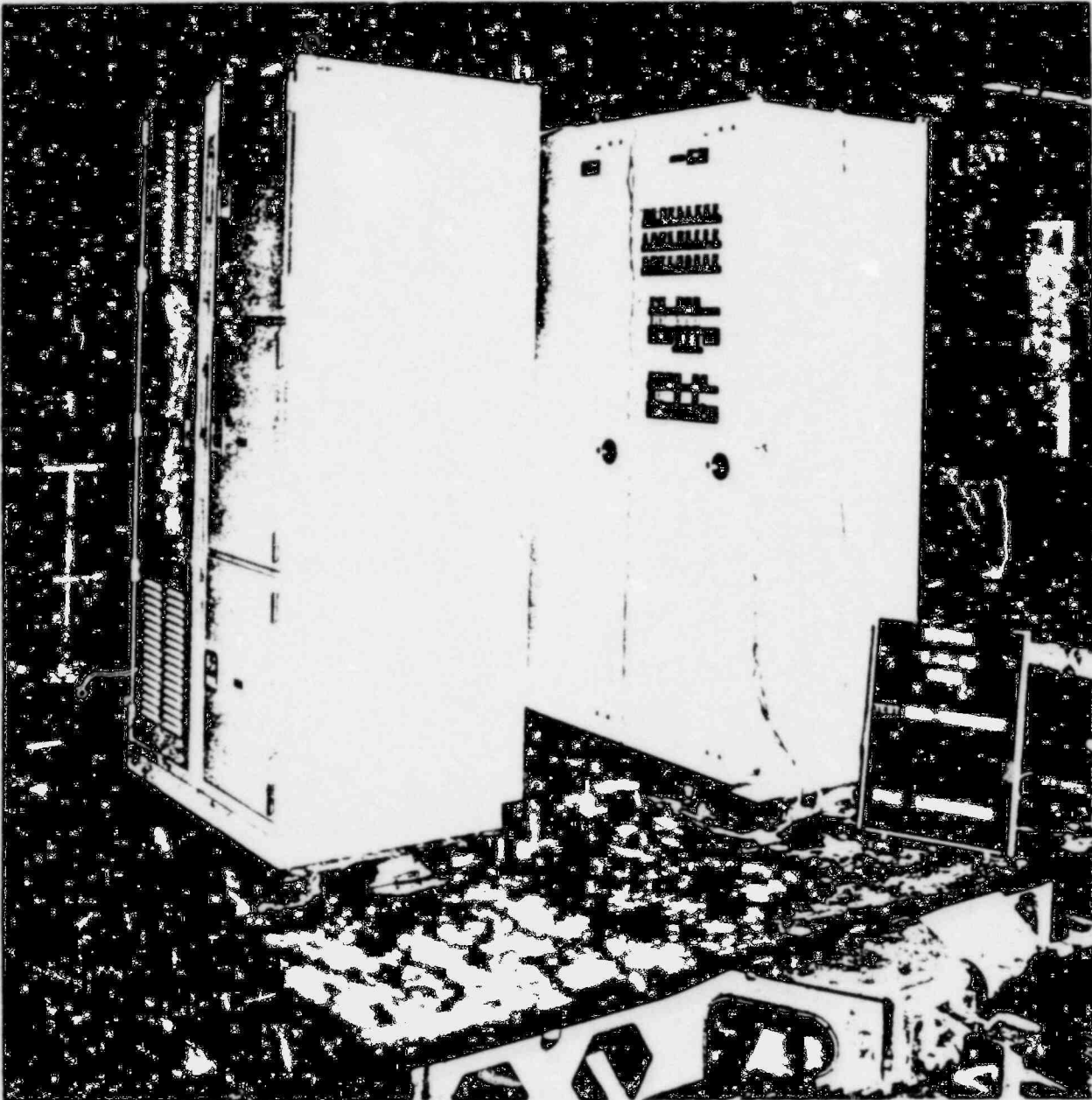
<u>SENSORS</u>	<u>SIGNAL CONDITIONERS</u>	<u>LOGIC COMPONENTS</u>	<u>ACTUATORS</u>
COMPENSATED ION CHAMBER	FLUX DRAWER	ISOLATORS	SCRAM BREAKERS
FISSION COUNTER	FLUX DRAWER	2/3 LOGIC	SCRAM SOLENOID VALVES
PRESSURE DETECTOR	PRESSURE TRANSMITTER	1/4 LOGIC	CIS BREAKERS
PM FLOWMETER	MV/I TRANSMITTER	LATCH LOGIC	
THERMOCOUPLE	MV/I TRANSMITTER		
INDUCTIVE LEVEL PROBE	LEVEL DRAWER		
TACHOMETERS	D/A CONVERTER		

SEISMICALLY QUALIFIED

(To DATE)

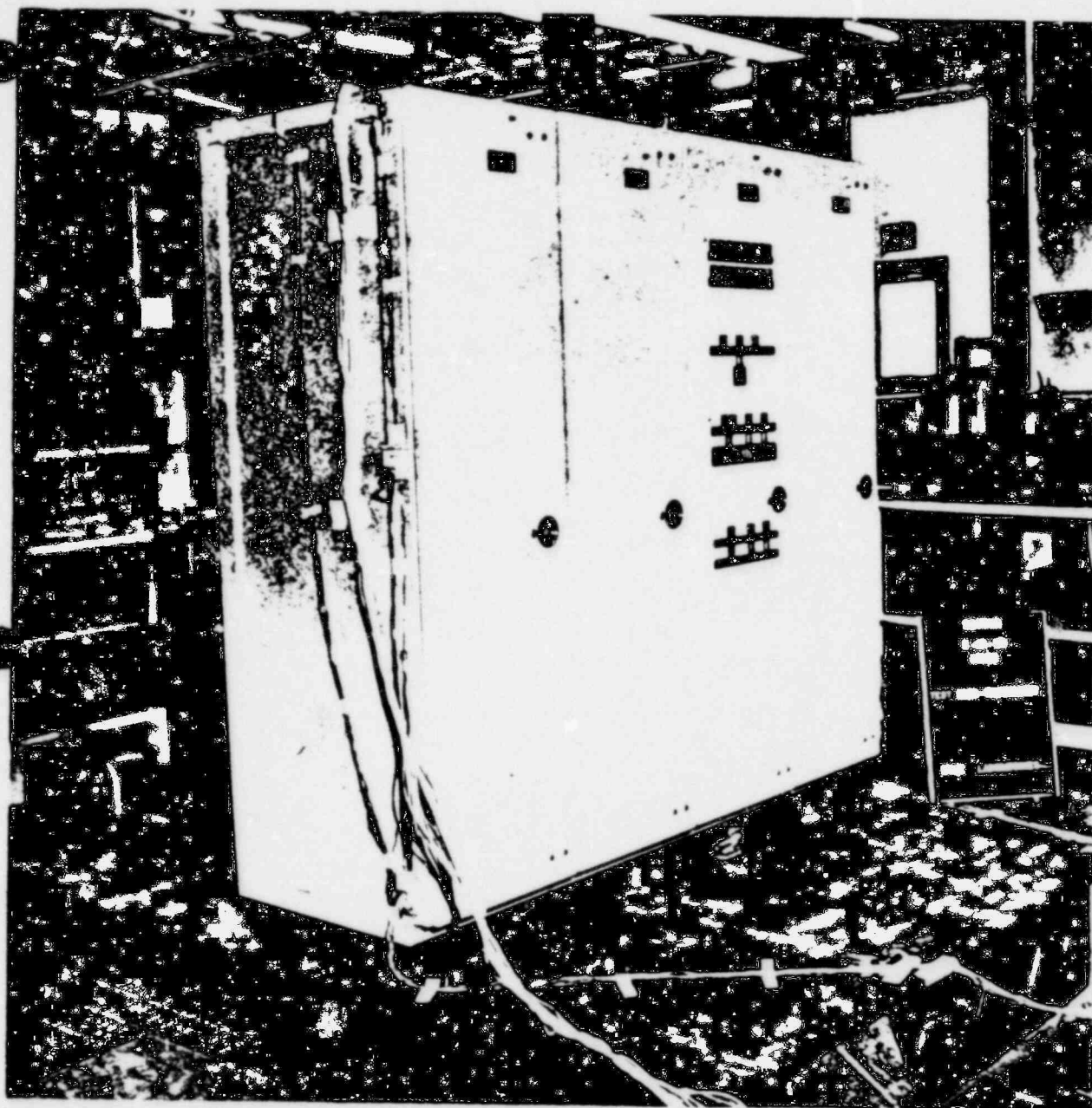
EQUIPMENT	QUALIFICATION METHOD
PRIMARY REACTOR SHUTDOWN SYSTEM	TYPE TESTING
SECONDARY REACTOR SHUTDOWN SYSTEM	TYPE TESTING
PRIMARY LINEAR FLUX DRAWERS	TYPE TESTING
SECONDARY LINEAR FLUX DRAWERS	TYPE TESTING
PRIMARY SCRAM BREAKERS	TYPE TESTING

Top



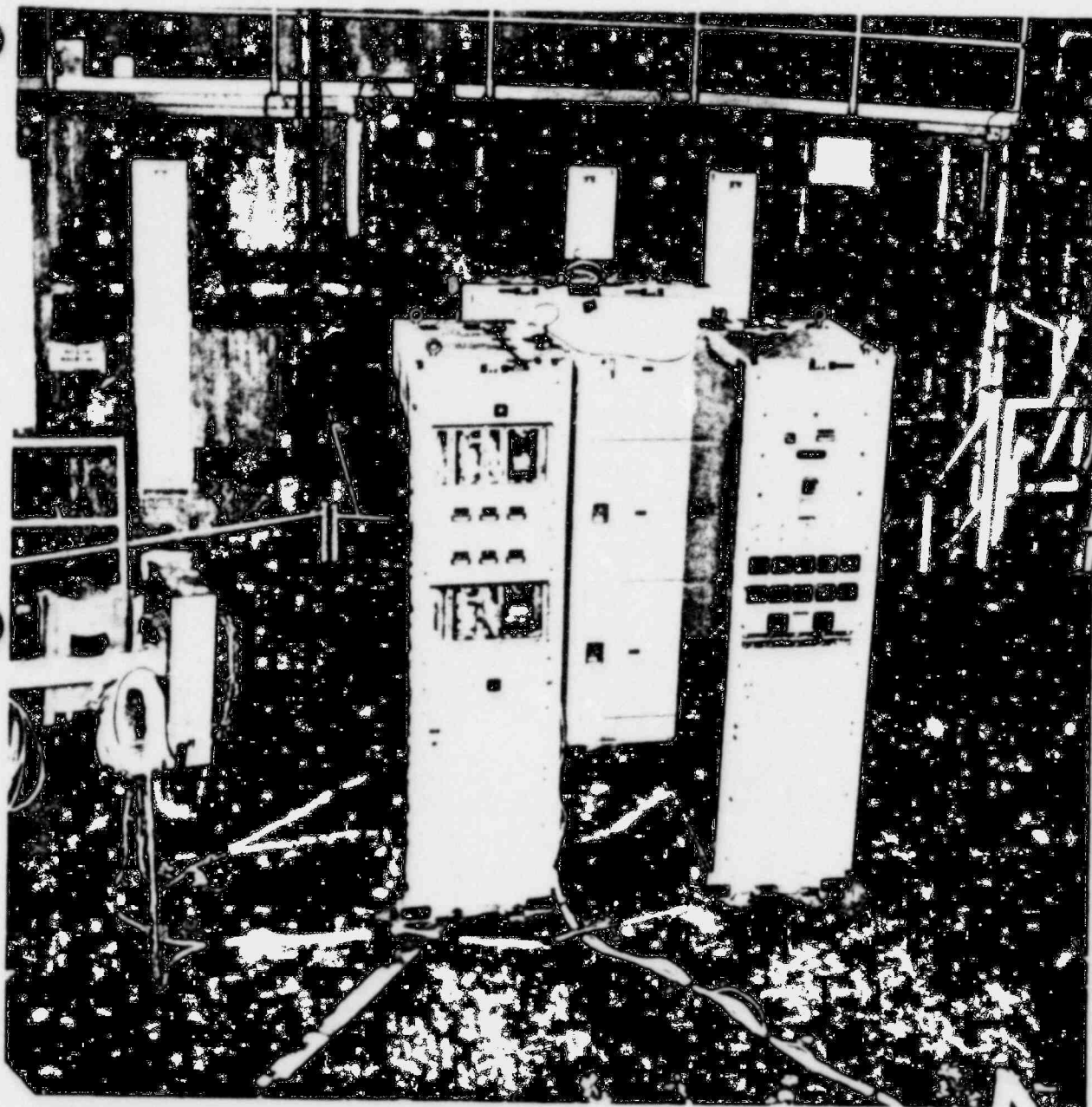
**PRIMARY REACTOR SHUTDOWN SYSTEMS
COMPARATOR/BUFFER CABINET AND
LOGIC CABINET ASSEMBLIES**

Top



**SECONDARY REACTOR SHUTDOWN SYSTEM
COMPARATOR/BUFFER CABINET ASSEMBLY**

TOP

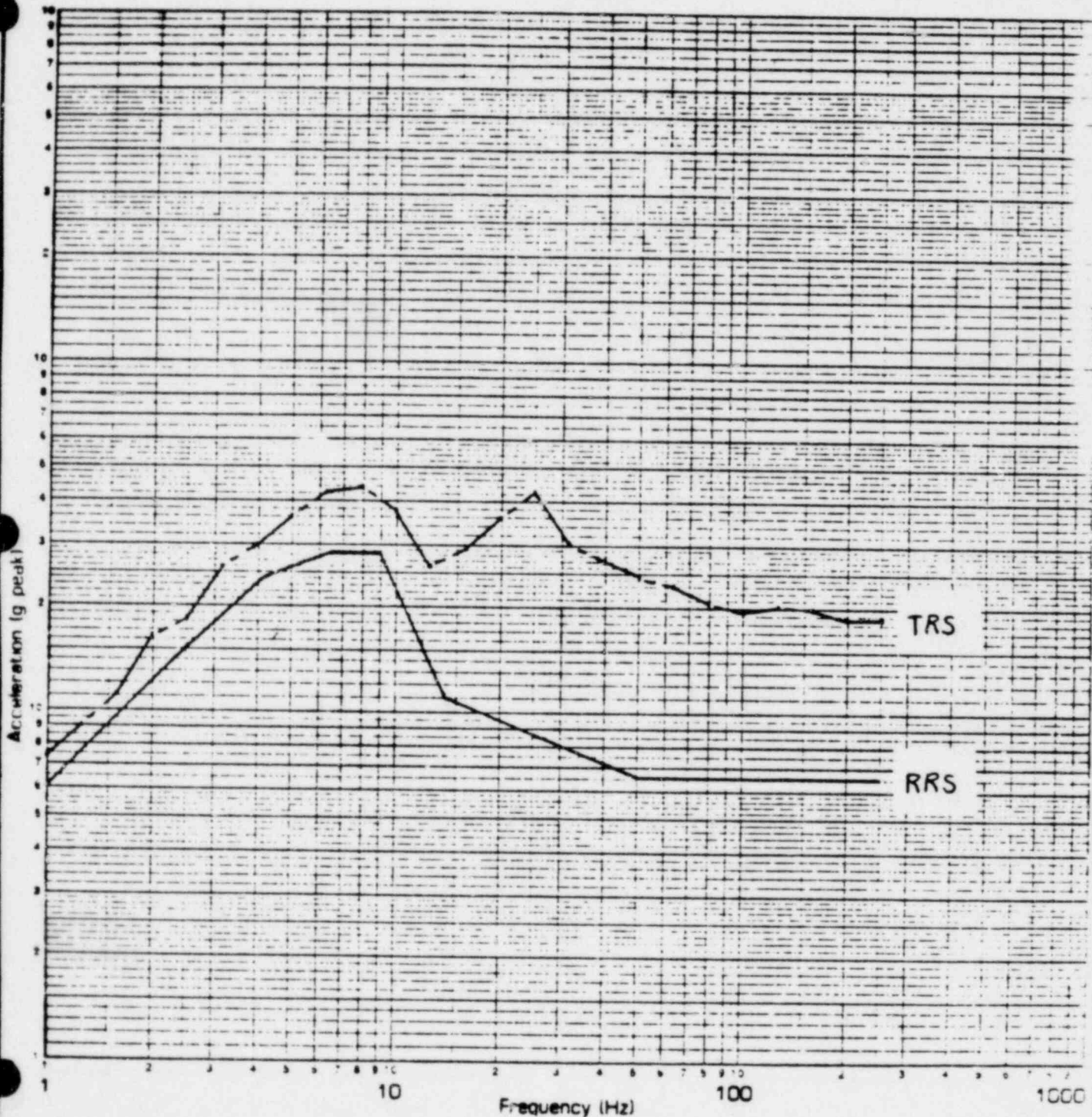


**CONTAINMENT ISOLATION SYSTEM COMPARATORS,
LOGIC AND BREAKER CABINET ASSEMBLIES**

TOP

1.0 ☐ 10 ☐ 100 ☒ 1000 ☐

DAMPING ☒ 5% ☐



PRIMARY REACTOR SHUTDOWN SYSTEM COMPARATOR/BUFFER
CABINET AND LOGIC CABINET ASSEMBLIES

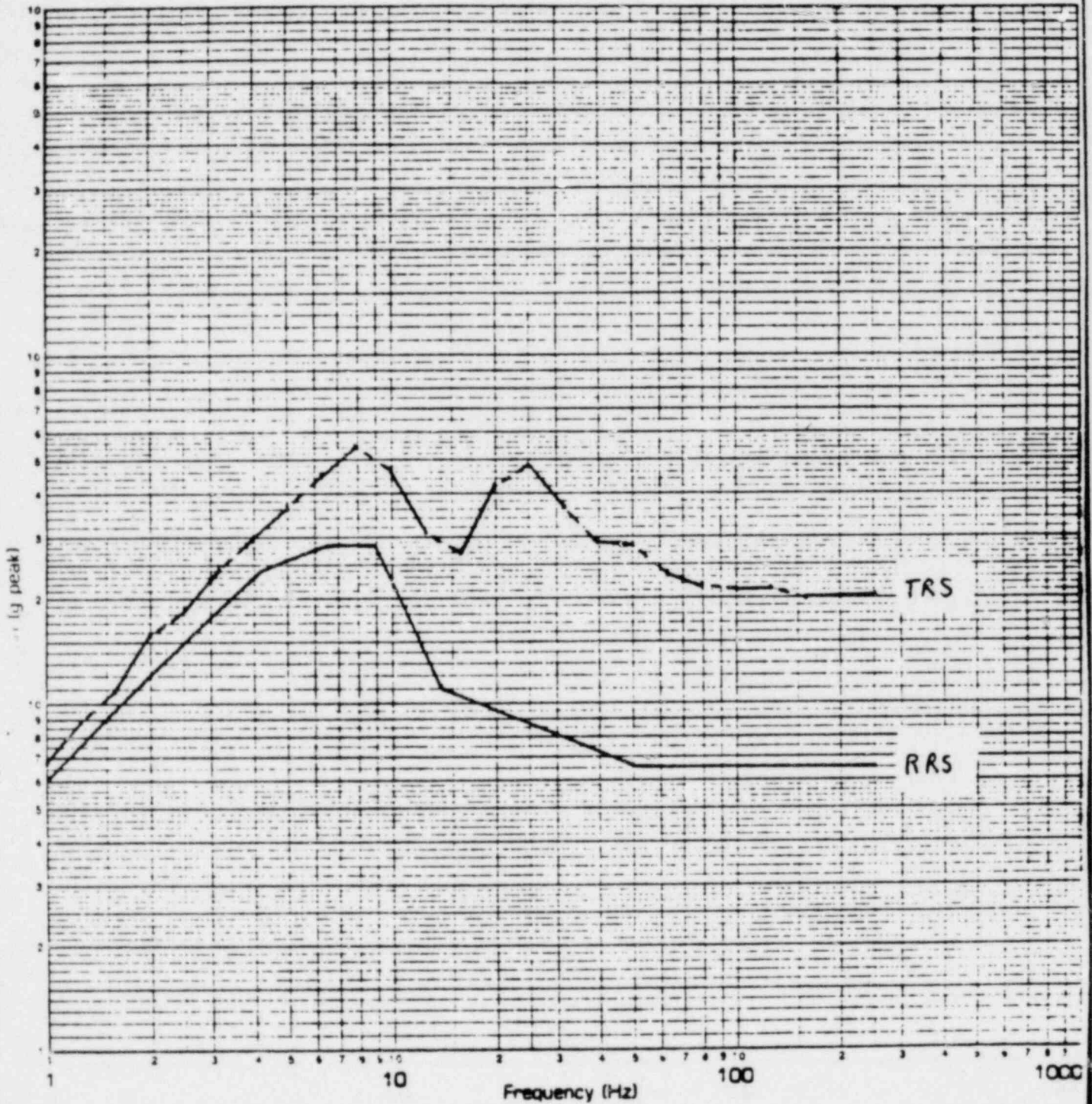
SSE-SIDE TO SIDE-HORIZONTAL

Top

FULL SCALE SHOCK SPECTRUM

1.0 ☐ 10 ☐ 100 ☒ 10000

DAMPING ☒ 5%



SECONDARY REACTOR SHUTDOWN SYSTEM
COMPARATOR/BUFFER CABINET ASSY

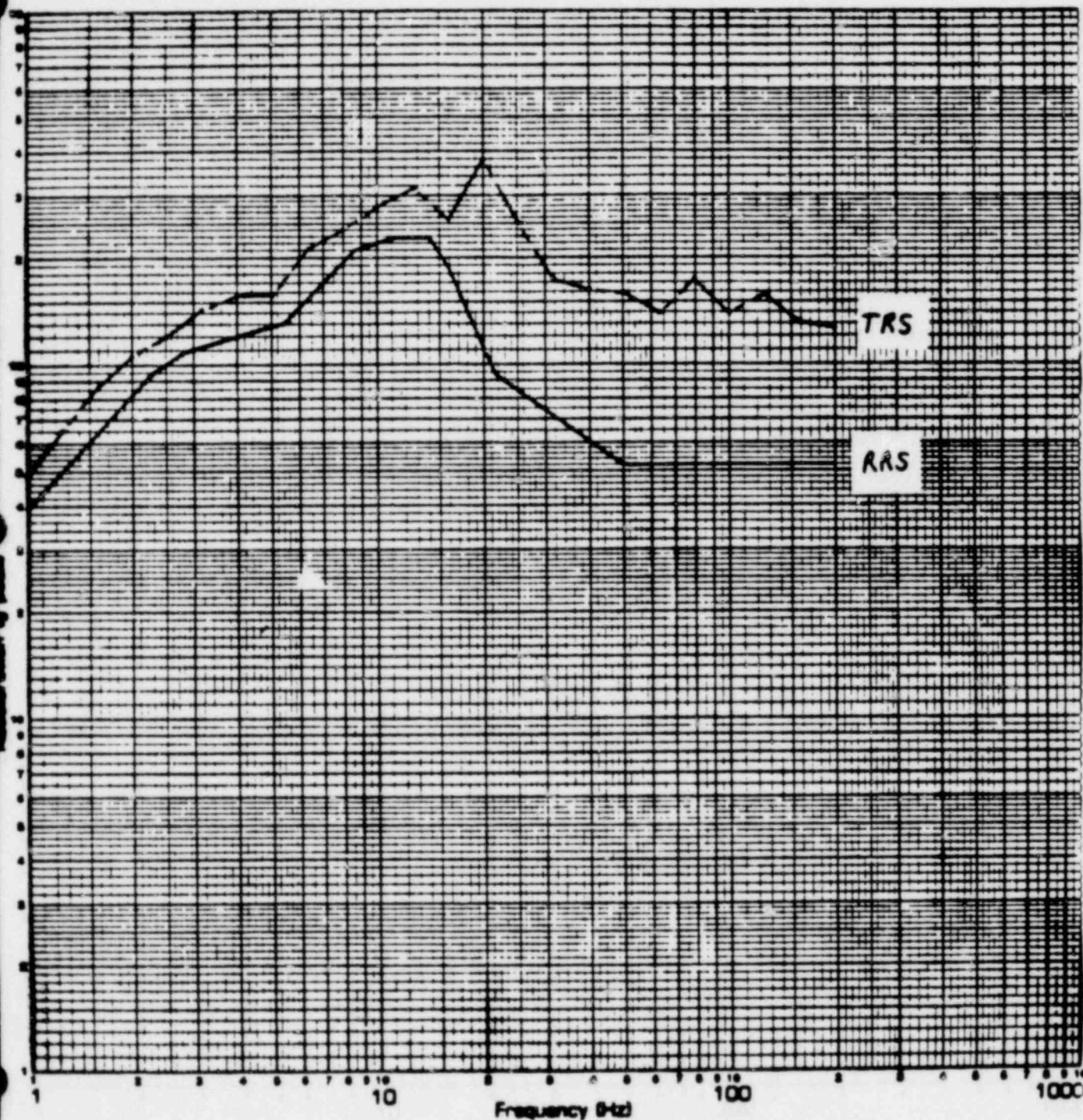
SSE-FRONT TO BACK-HORIZONTAL

TOP

FULL SCALE SHOCK SPECTRUM (g Peak)

1.0 ☐ 10 ☒ 100 ☐ 1000 ☐

DAMPING ☒ 5%



CONTAINMENT ISOLATION SYSTEM COMPARATORS,
LOGIC AND BREAKER CABINET ASSEMBLIES

SSE-SIDE TO SIDE-VERTICAL

SEISMIC TEST RESULTS

ALL OF THE EQUIPMENT TESTED
PERFORMED ITS REQUIRED SAFETY
FUNCTION DURING AND AFTER THE
MULTIPLE SEISMIC TESTS AND
RETAINED ITS STRUCTURAL INTEGRITY

MECHANICAL CONTROL ROD SYSTEMS DYNAMIC/SEISMIC TESTS

Dynamic Friction

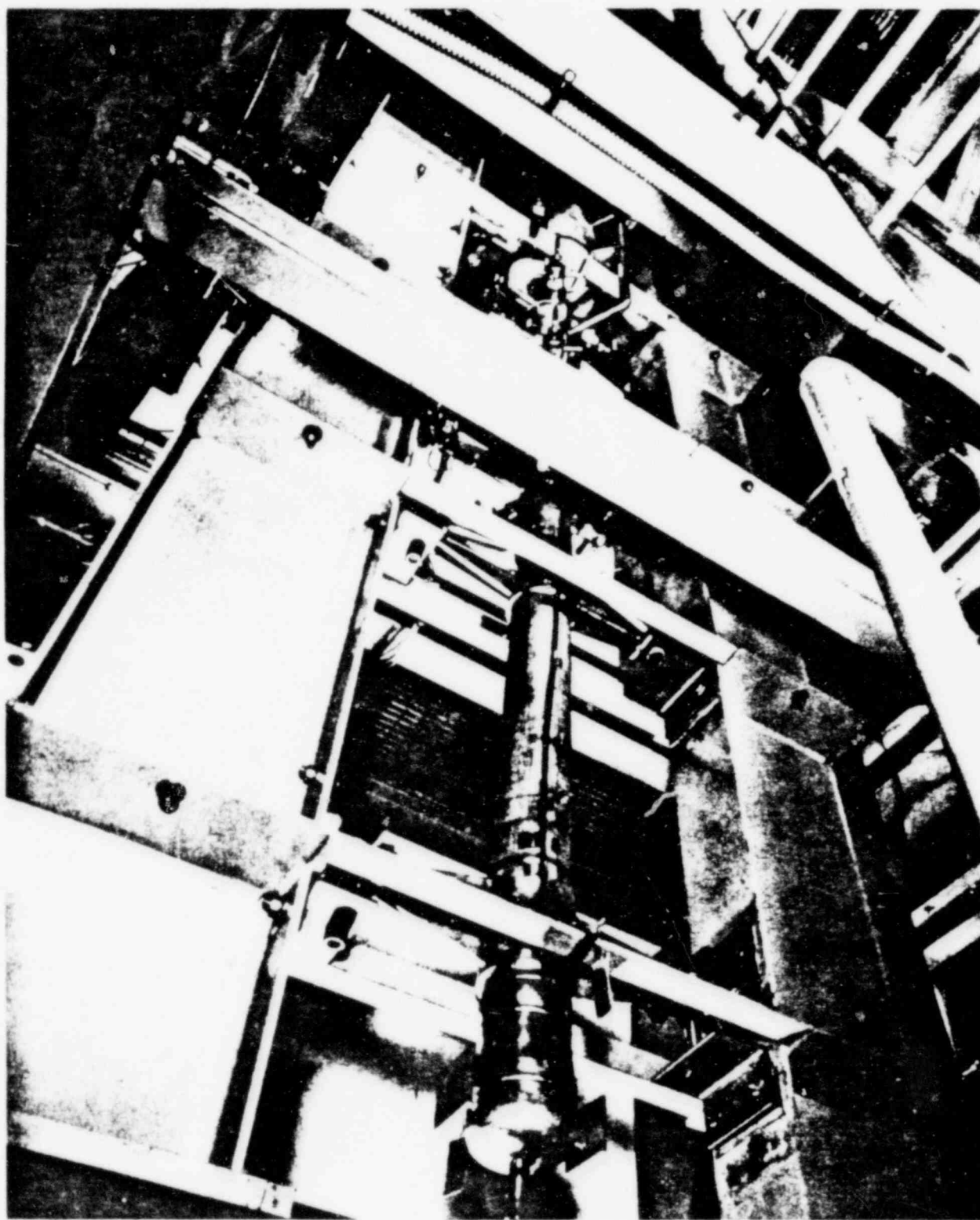
- Determine "Effective Coefficient of Friction" for seismic scram analysis
- Simple rod in bushings, sinusoidal input
- Test media - air, Argon, H₂O, Na
- Material couples - 304/718, 718/316, 718/718
- Cylindrical and hex test rods
- Coefficient of friction for design at 2σ level = 0.45 for all materials
 - design requirement is 1.0 except as supported by data
- Develop test experience for more complex seismic test

PCRS Seismic Test

- Scram performance under dynamic input conditions
- Validate seismic scram analysis methods
- Prototype test hardware
- Water test medium
- Scram testing to start by early CY83

SCRS Seismic Test

- Scram valve/cylinder assembly
- Seismic response spectra test per IEEE-344



PRELIMINARY CHECK OF SCRAM ANALYSIS METHODS

(Dynamic Friction Test Data)

Methods For Scram Retarding Normal Forces

- ANSYS finite element analysis with interface gaps (type 5-2D)
- Three rod withdrawal elevations—6, 18, 36 inch
- Impact stiffnesses—hertzian contact method
- Impact damping—ignored as shown negligible effect by sensitivity analysis
- Structural damping—.3% for test
- Fluid coupling—concentric cylinder model (ANSYS element S11F38)

Application To Dynamic Friction Tests

- Analytically calculate normal forces
- Analytical correction for hydraulic forces normalized by Og test data
- Obtain μ by adjustment to test drop time
 - Compare with μ from measured normal forces
- Compare average normal force between analysis and test

PRELIMINARY CHECK OF SCRAM ANALYSIS METHODS

(Dynamic Friction Test Data)

Analysis vs Test	Friction Coefficient		Average Normal Force	
	Analysis	Test	Analysis	Test
Air, I-718, 228 Hz, 1.5G	0.32	0.30±.04 (0.32±.02)	84.7	82.7
Air, I-718, 228 Hz, 0.5G	Insensitive	0.28±.07	20.2	37.0
Water, I-718, 228 Hz, 1.5G	0.32	0.31±.02 (0.36±.04)	~81	86.2

Note: Test values are average of 10 drops. values in parenthesis are repeat tests

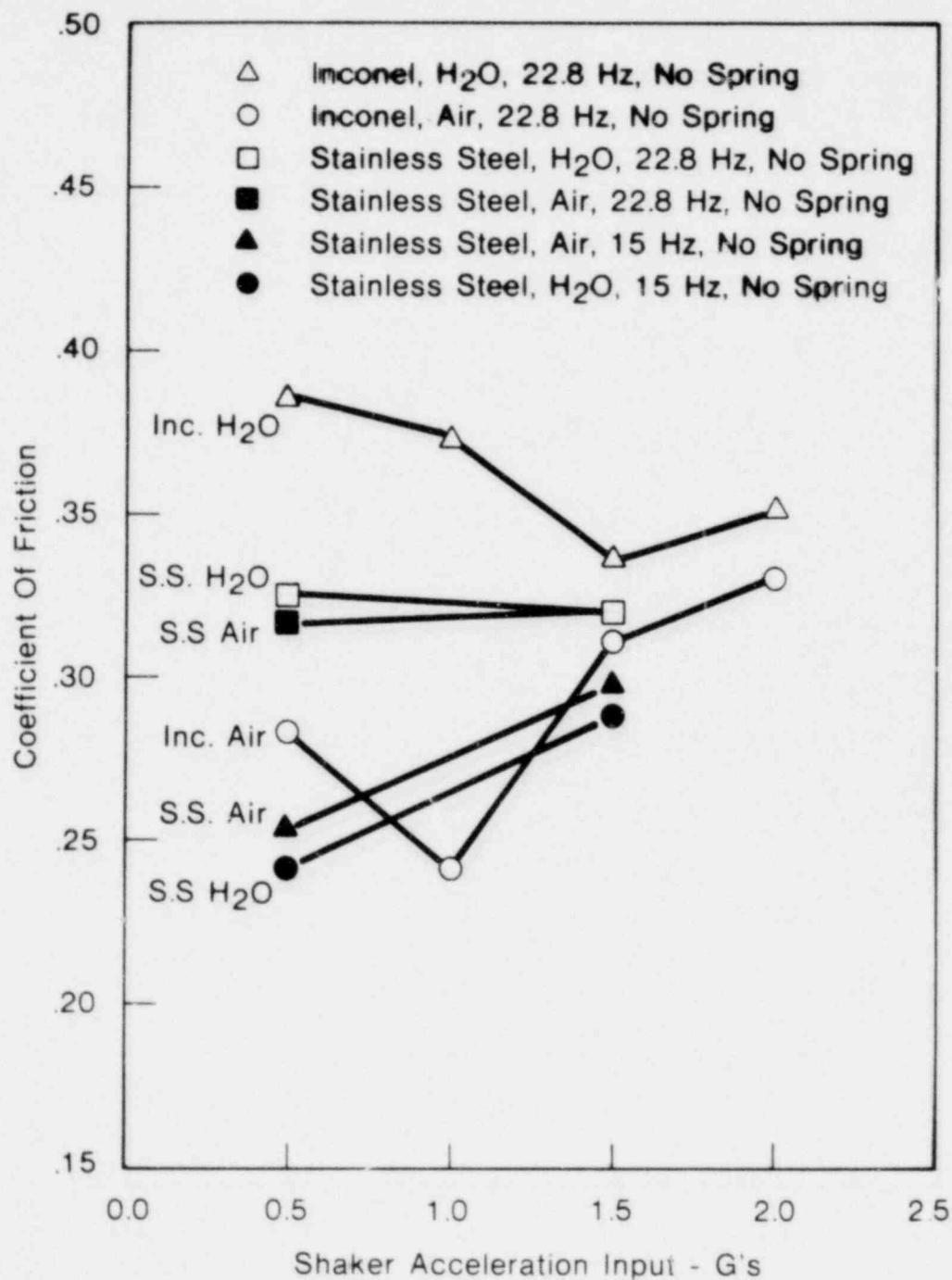
PRELIMINARY CHECK OF SCRAM ANALYSIS METHODS

(Dynamic Friction Test Data)

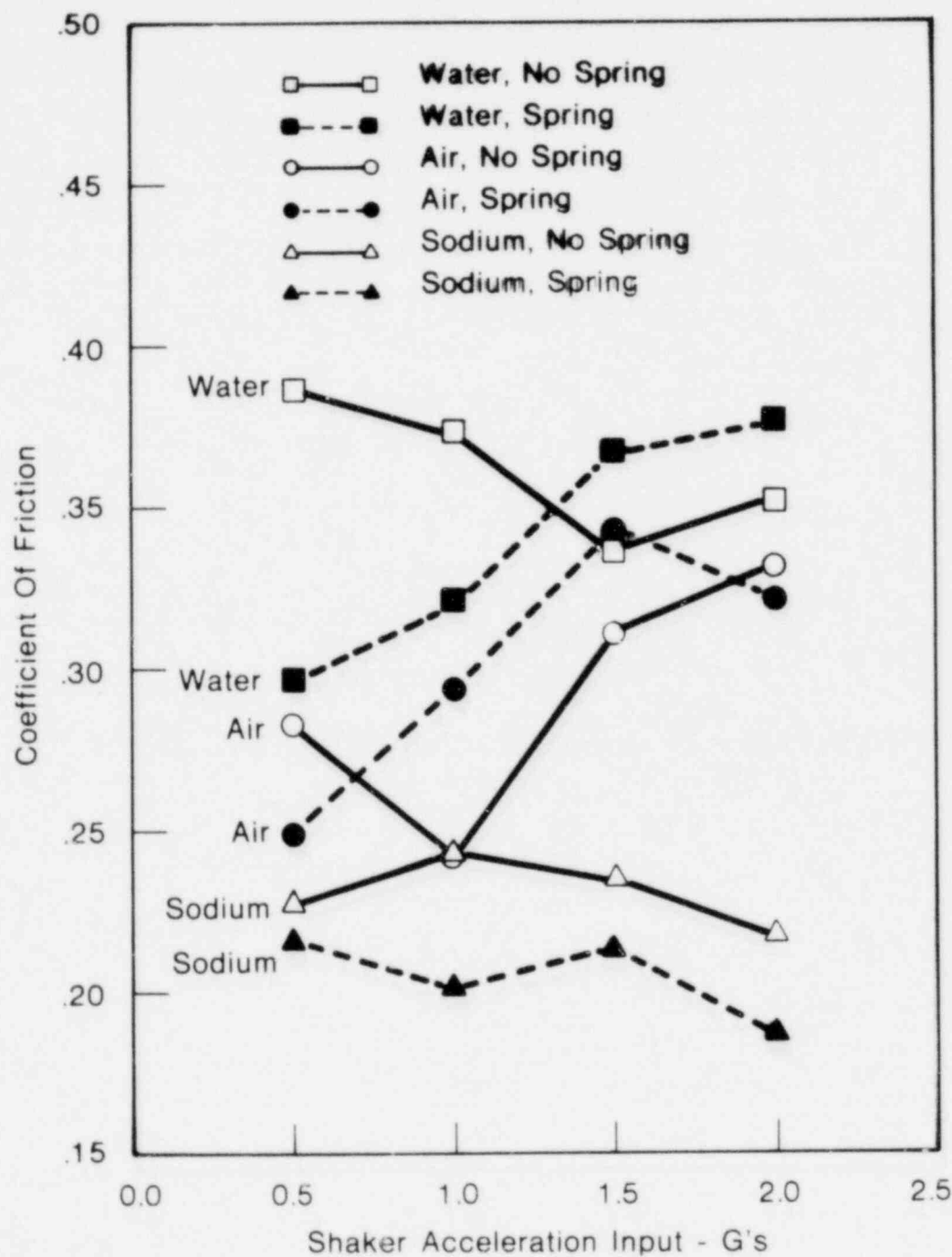
General Conclusions - Test vs Analysis

- Good agreement on analytical and test μ or drop times using test μ in analysis
- Good agreement on average normal forces
 - Force and impact frequency dependence on rod position also generally predicted
 - Supports general methods and 3 elevation model assumptions
- Test and analysis do not show significant fluid coupling effect
- Analysis not strongly sensitive to impact stiffness
 - Factor of 10 reduction in stiffness increases test drop time by 8%
- Recommend design values of $\mu = 0.45$ for fluid and $\mu = 0.41$ for gas

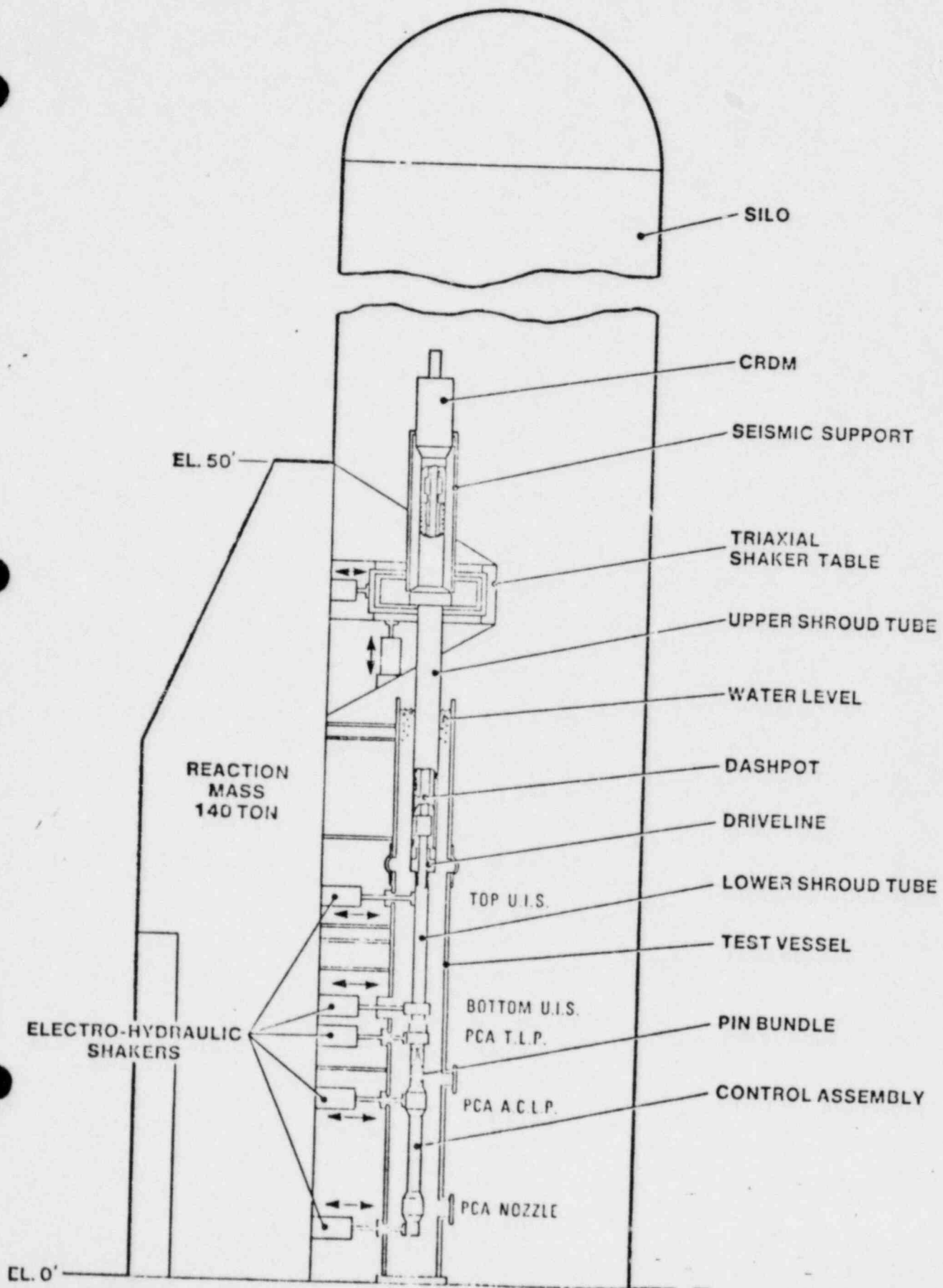
DYNAMIC FRICTION TEST COEFFICIENT OF FRICTION EFFECTS OF BUSHING MATERIAL AND FREQUENCY

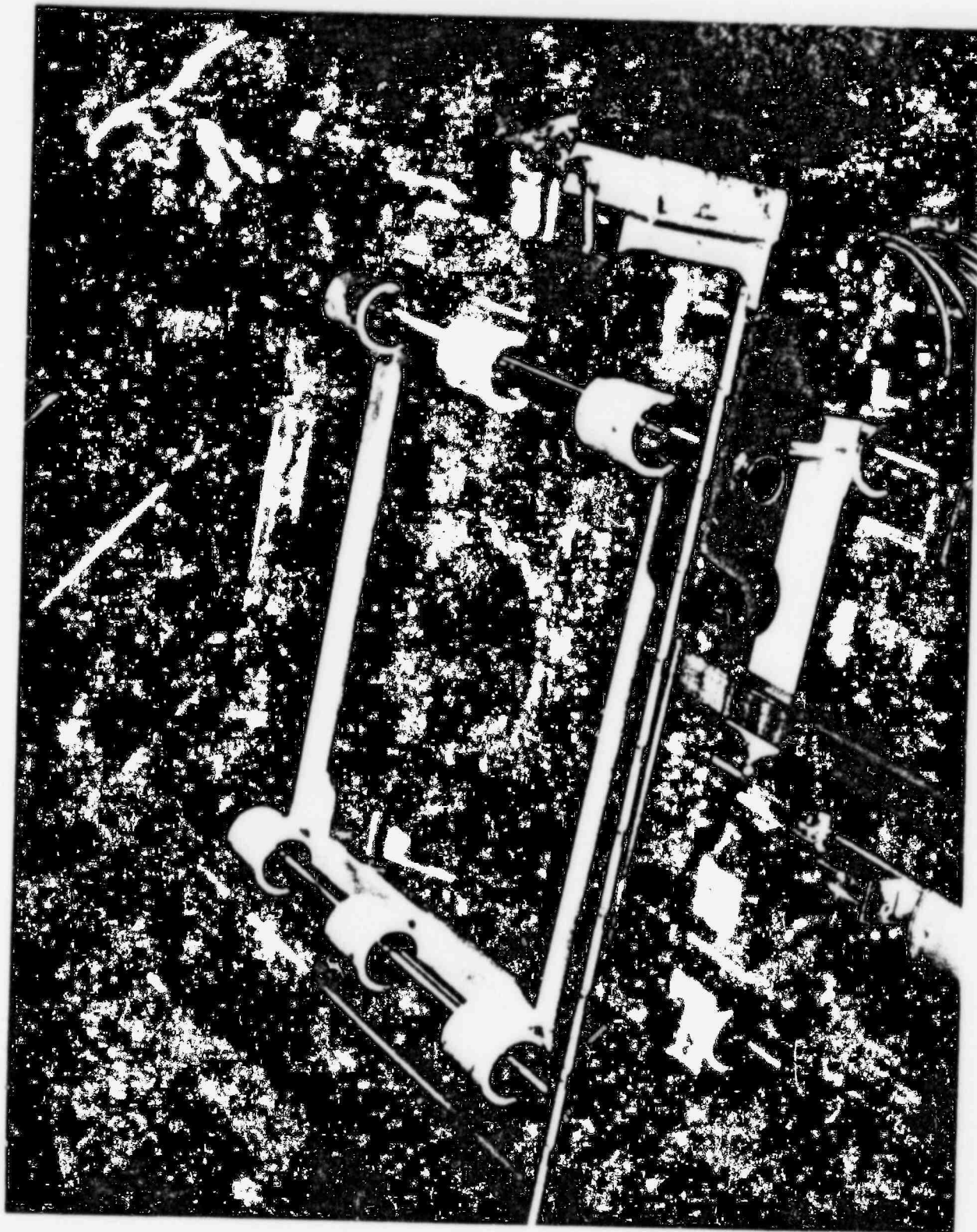


DYNAMIC FRICTION TEST COEFFICIENT OF FRICTION EFFECTS OF ENVIRONMENT AND ROD VELOCITY FOR ALLOY 718 ROD & BUSHINGS (22.8 Hz)



DYNAMIC AND SEISMIC TEST FACILITY





SCRS SCRAM VALVE SEISMIC TEST

Requirements

- Scram valve (pilot valve portion) is part of the plant protection system and falls within IEEE class 1E definition
- Reg. Guide 1.89 and IEEE-323 require seismic qualification of class 1E components
- Reg. Guide 1.100 and IEEE-344 specify seismic qualification requirements
- Reactor system seismic analysis results provide required response spectra

SCRS SCRAM VALVE SEISMIC TEST (Continued)

Seismic Test Description

- Complete valve/cylinder assembly tested
- Subjected to 5 OBE and 1 SSE simulations (multi-axis excitation)
- Functional test during each simulation and after OBE and SSE simulations

Test Results To Date

- Completed seismic test of prototype valve/cylinder assembly
- Met all requirements

SCRS SCRAM VALVE/CYLINDER SEISMIC TEST

Method

- IEEE-344
- Response spectra based on 1% damping and for location within SCRDM
- Bi-axial, verticle and horizontal
- 90° equipment rotation for each OBE and the SSE
- 30 second minimum duration at each position
- Axial load applied to tension rod
- Tenson rod movement instrumented
- Each scram performed during seismic vibration with a single valve logic train (2 of 3) non-operational
- Room temperature in air

Sequence

- Pre-seismic test
 - 5 OBE, with 90° equipment rotation
 - Two at reference position, three at 90°
 - Scram after each OBE
 - Three SSE, with 90° equipment rotation
 - One SSE for each logic train
 - Duration: 30 sec., 5 sec., 5 sec.
 - Post-seismic test
 - Two SSE's at reference position, 1 at 90° rotation
- 

SCRS SCRAM VALVE/CYLINDER SEISMIC TEST (Continued)

Criteria

- Scram time (tension rod movement) occurs within control rod release delay time (.1 sec.)
- No visible or functional damage

Prototype Test Results

- No damage
- Tension rod movement time limit

Criteria: $\leq$.1 sec.

Test values: .062 sec. max.

.050 sec. min.

CONTROL ROD SYSTEMS DYNAMIC/SEISMIC TESTS

Application Of Seismic Test Results To Design Support

- **Dynamic friction test**
 - Friction coefficients used in PCRS and SCRS seismic scram analysis
 - Preliminary verification of scram insertion analysis methods
- **PCRS seismic test**
 - Confirmation of PCRDM unlatch design basis
 - Validate methods used for PCRS and SCRS seismic scram insertion analyses
- **SCRS scram valve test**
 - Verification of scram actuator performance under seismic conditions

CONTROL ROD SYSTEMS DYNAMIC/SEISMIC TESTS (Continued)

Conclusions

- Completed tests show satisfaction of design requirements
 - Dynamic friction test
 - Seismic scram speed requirements met using test friction coefficients in scram analyses
 - SCRS prototype scram valve test
 - Functional requirements satisfied
- Tests plans defined for confirmation of PCRS and SCRS seismic scram capability

SEISMIC DESIGN OF HTS COMPONENTS

QUESTIONS ADDRESSED

- WHAT IS THE ARCHITECTURE OF HTS COMPONENTS?
- DO THE CDDOP SEISMIC METHODS AND CRITERIA INCLUDE THE CONVENTIONAL CONSERVATISM?
- DO THE MAJOR COMPONENTS HAVE INHERENT SEISMIC MARGIN CAPABILITY?
- WHAT ARE SOME OF THE SPECIAL ATTRIBUTES CONSIDERED IN DESIGN OF CDDOP COMPONENTS?
- WHAT SPECIAL ACTIONS HAVE BEEN TAKEN IN VIEW OF THE LIMITED PRIOR OPER EXPERIENCE?

CONCLUSION

- SEISMIC SAFETY LEVELS FOR CDDOP AND LAR COMPONENTS ARE OUTSTANDING.

Mallett

T14

ACRS CRSP SUBJECT MATTER MEETING

ON

SEISMIC DESIGN

JUNE 1 & 2, 1982

AGENDA

ITEM

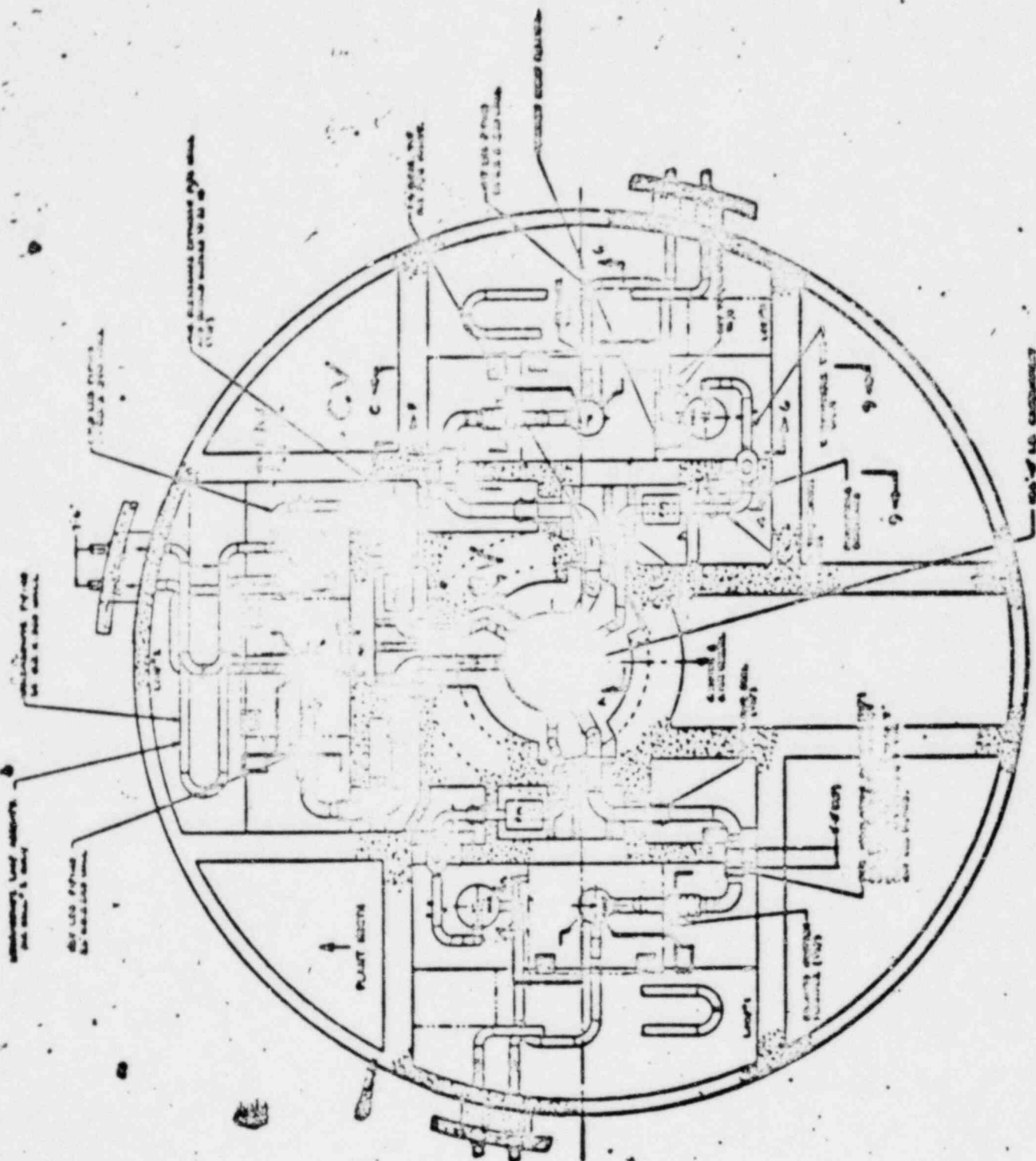
TOPIC

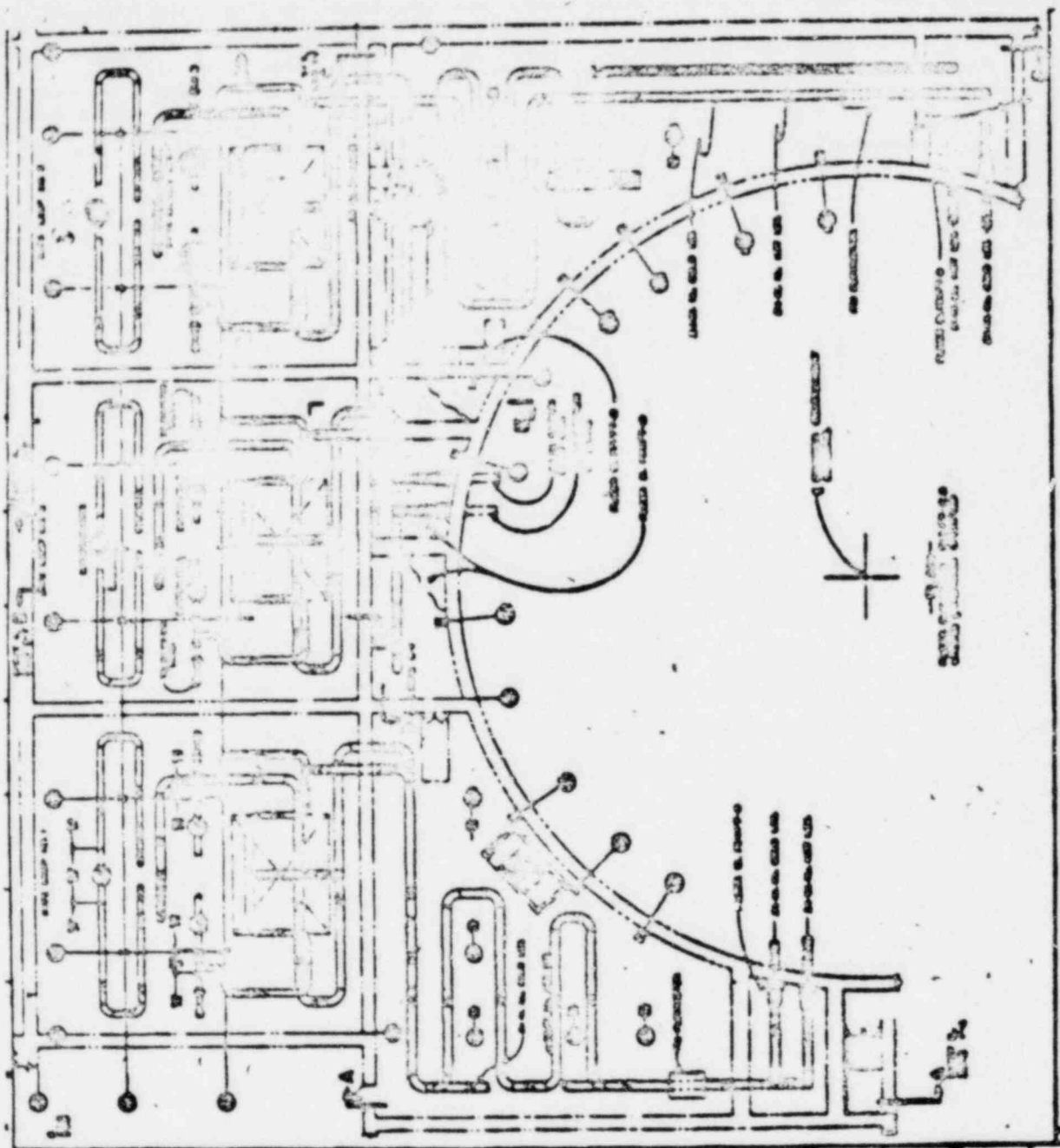
IV.B

SEISMIC DESIGN OF

HEAT TRANSPORT SYSTEM COMPONENTS

ROBERT H. HILLET
PLANNING, ENGINEERING &
PIPING DESIGN
CONSULTANTS
ADVANCED REACTORS DIVISION

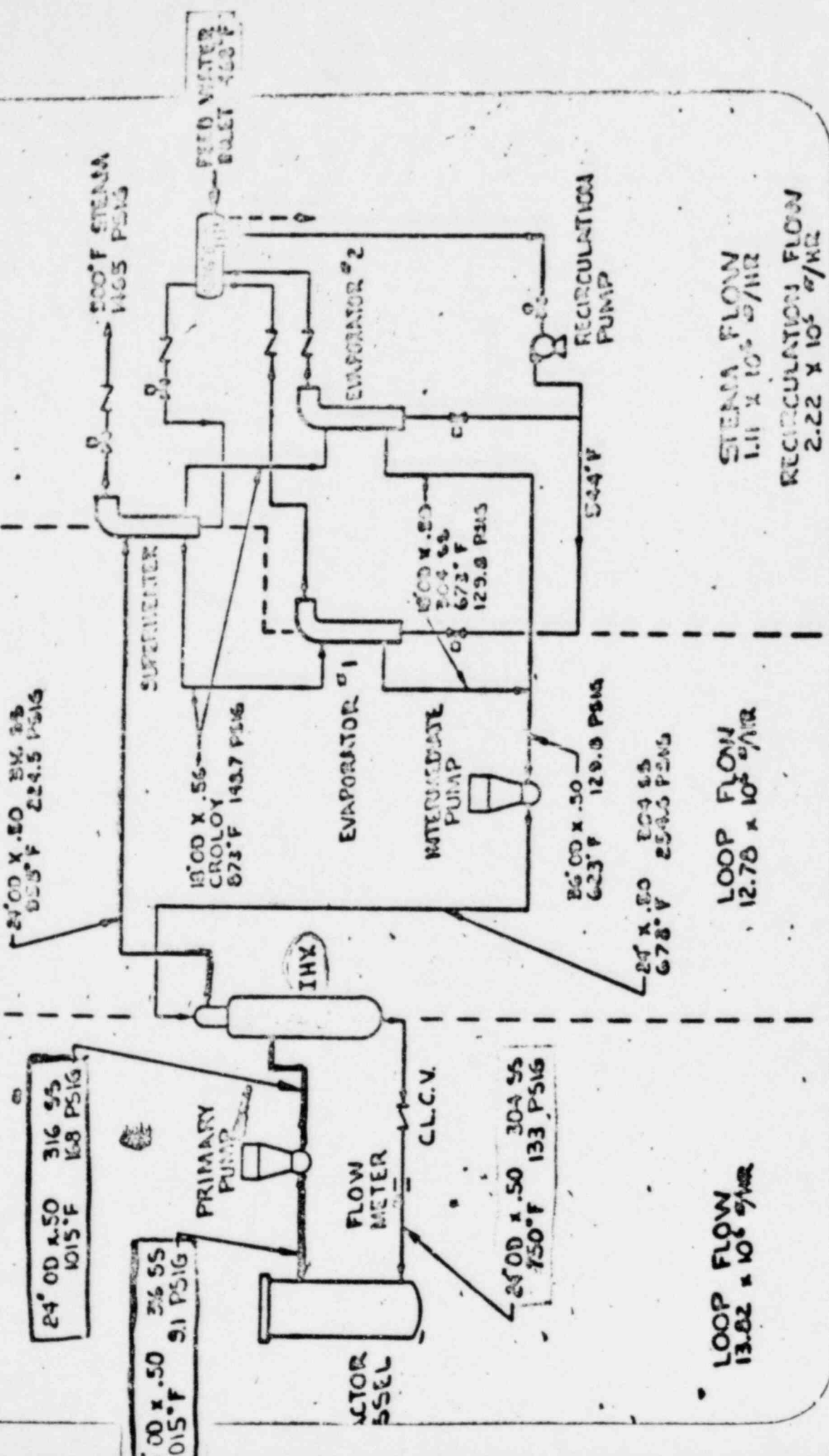




PRIMARY SYSTEM

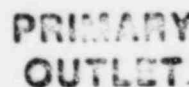
INTERMEDIATE SYSTEM

STEAM GENERATOR SYS



X

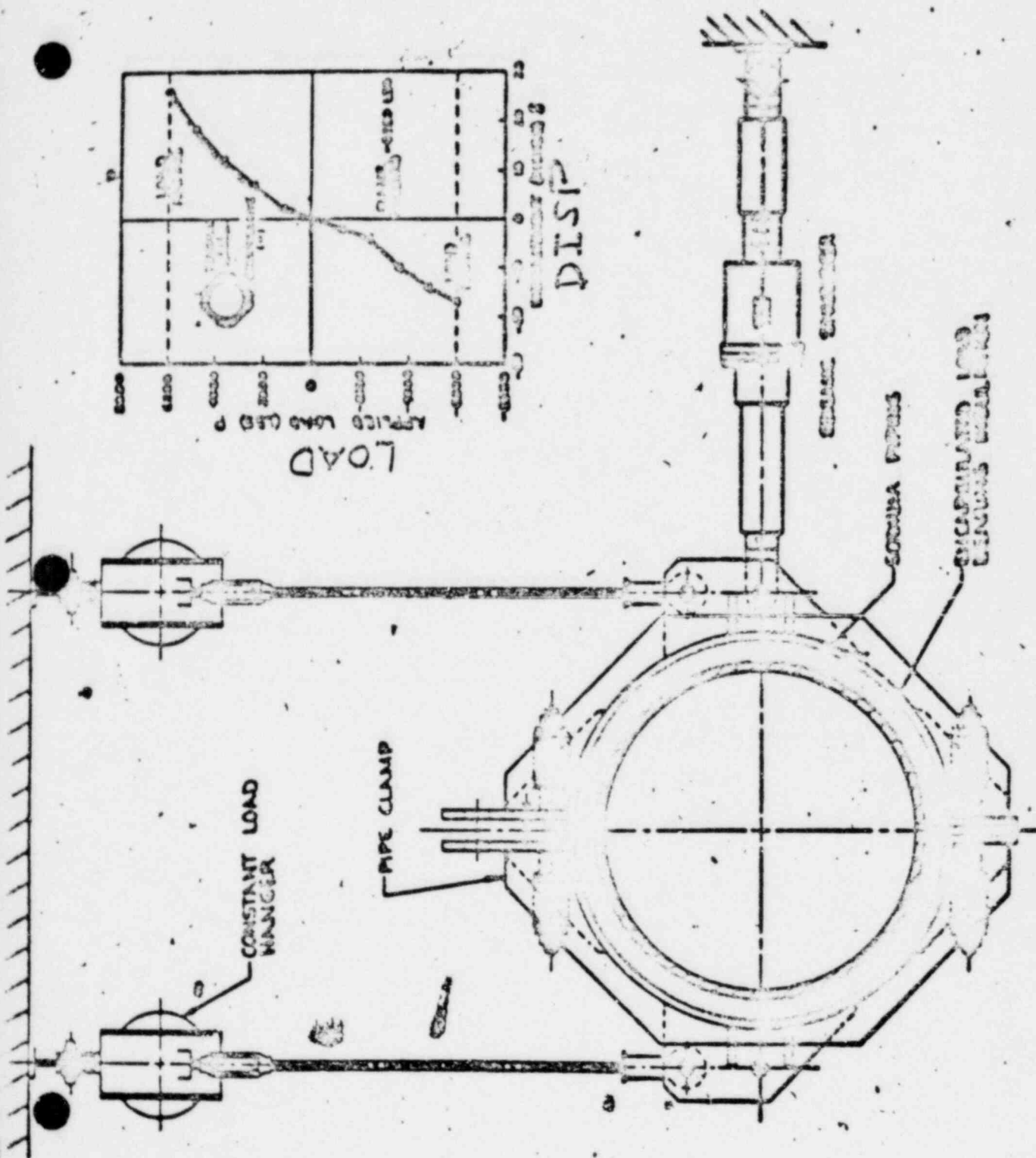
INTERMEDIATE HEAT EXCHANGER



CRISP
R.H. GALLATT
L.S.

(4) Under Seismic $\rightarrow$ WAG $\rightarrow$ Cone buckling
No side motion

GENERAL HANGER/LOAD CLAMP / SHOCKER PIPE CLAMP ASSEMBLY



6

SEISMIC DESIGN OF ITS COMPONENTS

CONCLUSION

THE SEISMIC DESIGN PROBLEM IS ESSENTIALLY THE SAME EXCEPT FOR DIFFERENCES DUE TO HIGHER TEMPERATURE AND LOWER PRESSURE.

10

SEISMIC DESIGN OF HTS COMPONENTS

QUESTION

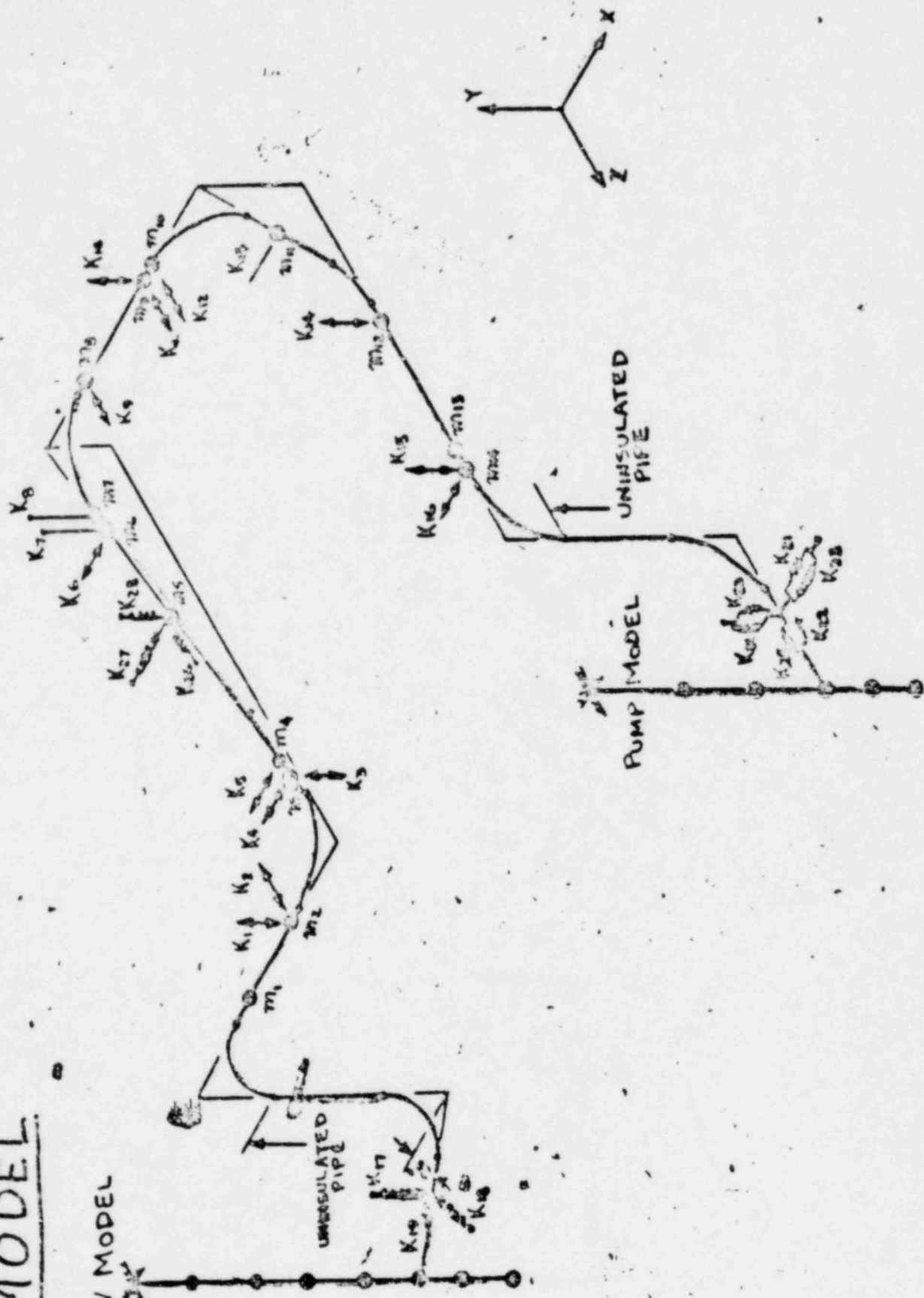
DO THE CHEAP SEISMIC METHODS AND CRITERIA INCLUDE THE CONVENTIONAL

CONSERVATIVES?

- MODELS
- METHODS
- CRITERIA

MODEL

RV MODEL

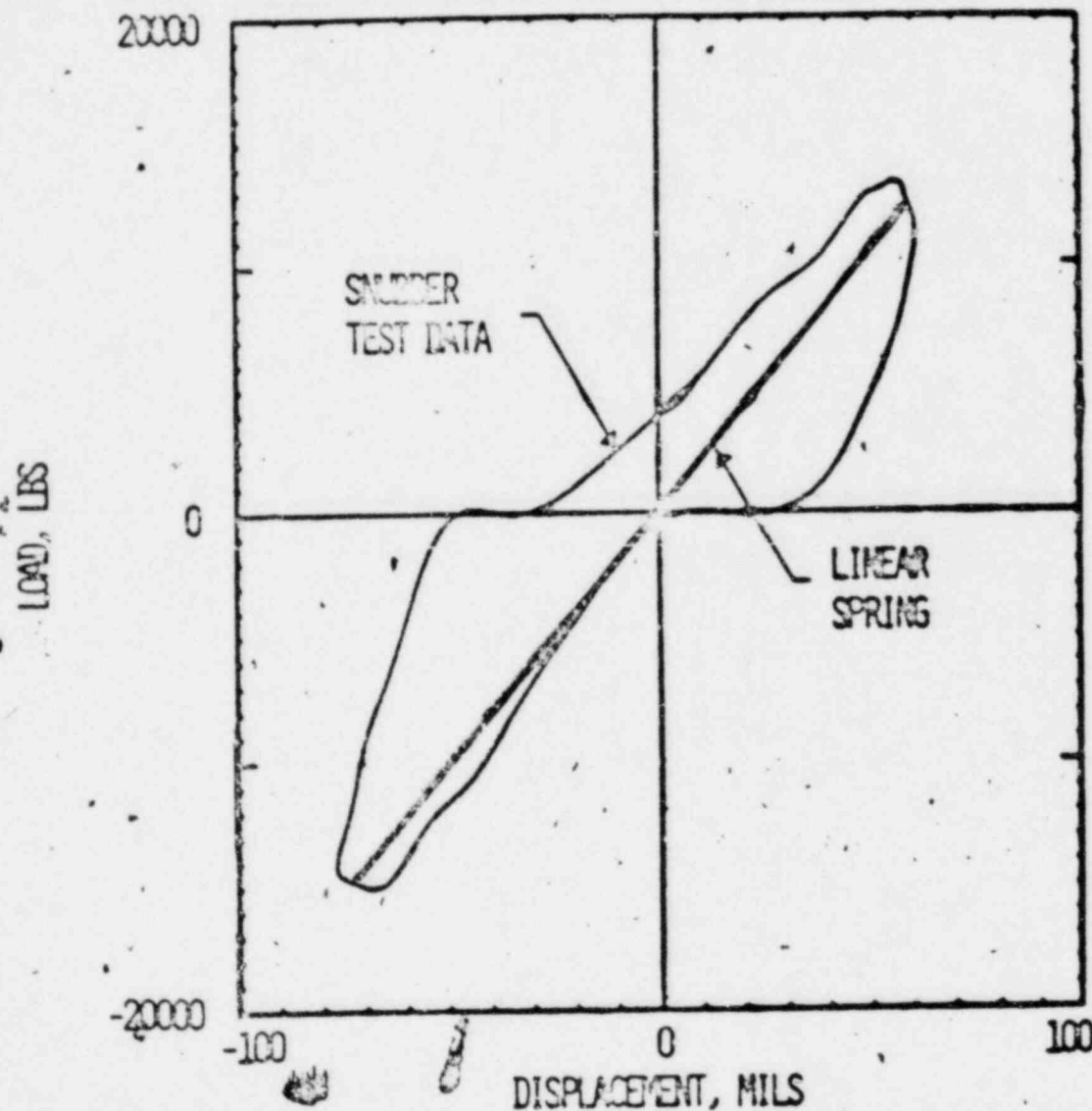


Difference is: — number of ELBOWS

② Example of conventional conservatism
③ Somewhat greater for LMFB

SEISMIC DESIGN OF HTS COMPONENTS

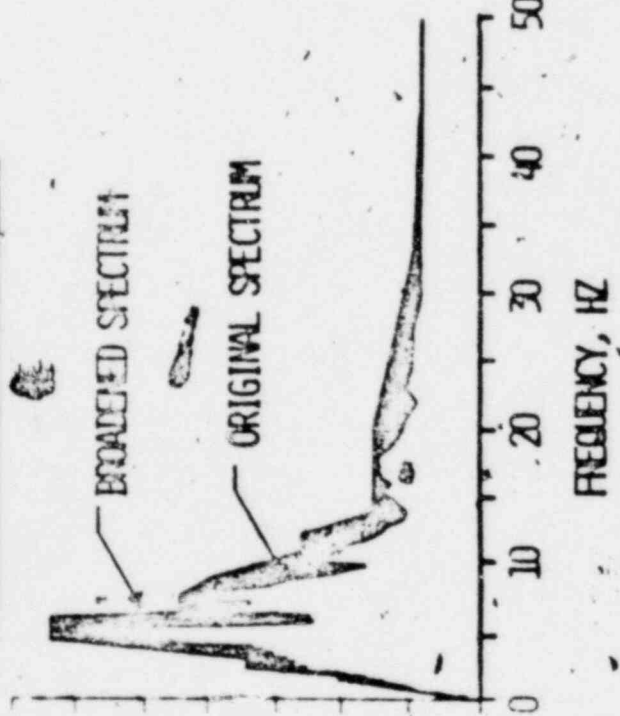
SLUDDER MODEL CONSERVATISM



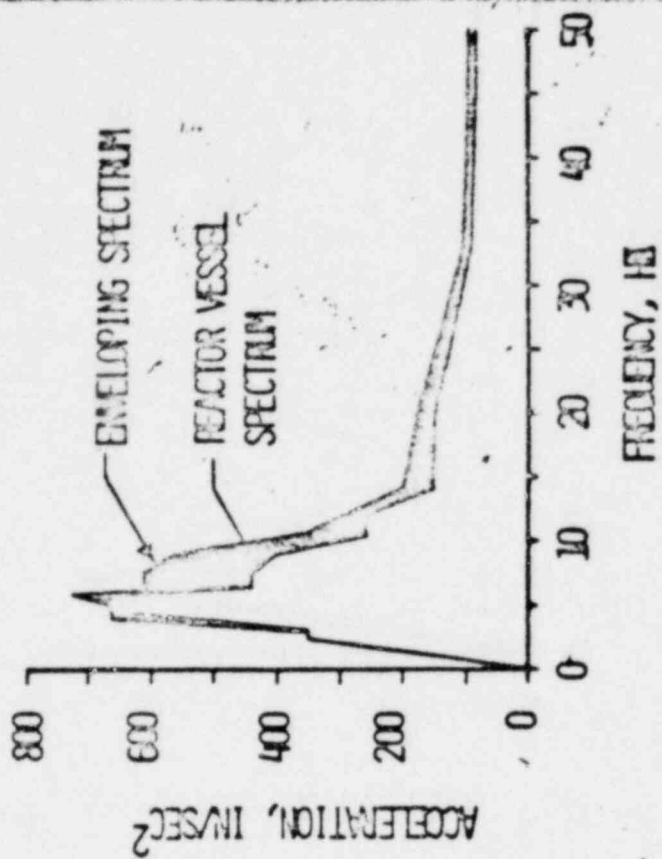
COMPARISON OF LINEAR SPRING MODEL RESPONSE AND
SLUDDER TEST DATA

SEISMIC DESIGN OF HTS COMPONENTS

RESPONSE SPECTRA CONSERVATISM



SPECTRUM ENVELOPING FOR FREQUENCY UNCERTAINTY



SPECTRUM ENVELOPING FOR UNIFORM BASE MOTION

SEISMIC DESIGN OF JOINT COMPONENTS

CRITERIA:
SEISMIC ANALYSIS RESULTS

EL. NO.	OBE CONDITION		SSE CONDITION	
	MAXIMUM STRESS	ALLOWABLE STRESS	MAXIMUM STRESS	ALLOWABLE STRESS
1	18.41	5% --- 19.44	31.81	75% --- 45.93
2	15.67	19.44	27.33	45.93
3	10.14	19.44	17.78	45.93
4	9.56	19.44	16.26	45.93
5	6.85	19.44	11.43	45.93
6	8.42	19.44	14.51	45.93
7	7.11	19.44	12.04	45.93
8	7.21	19.44	12.12	45.93

($P_L + P_B$) 36" HOT LEG

15

SEISMIC DESIGN OF HTS COMPONENTS

CONCLUSION

• CRITICAL SEISMIC DESIGN METHODS AND CRITERIA INCLUDE THE CONVENTIONAL

CONSERVATISM

16

SEISMIC DESIGN OF ITS COMPONENTS

QUESTION

Q DO THE MAJOR COMPONENTS HAVE INHERENT SEISMIC MARGIN CAPABILITY?

- REFERENCE LETTER

PSL:L:77-286, APRIL 21, 1977

X

SEISMIC DESIGN OF HTS COMPONENTS

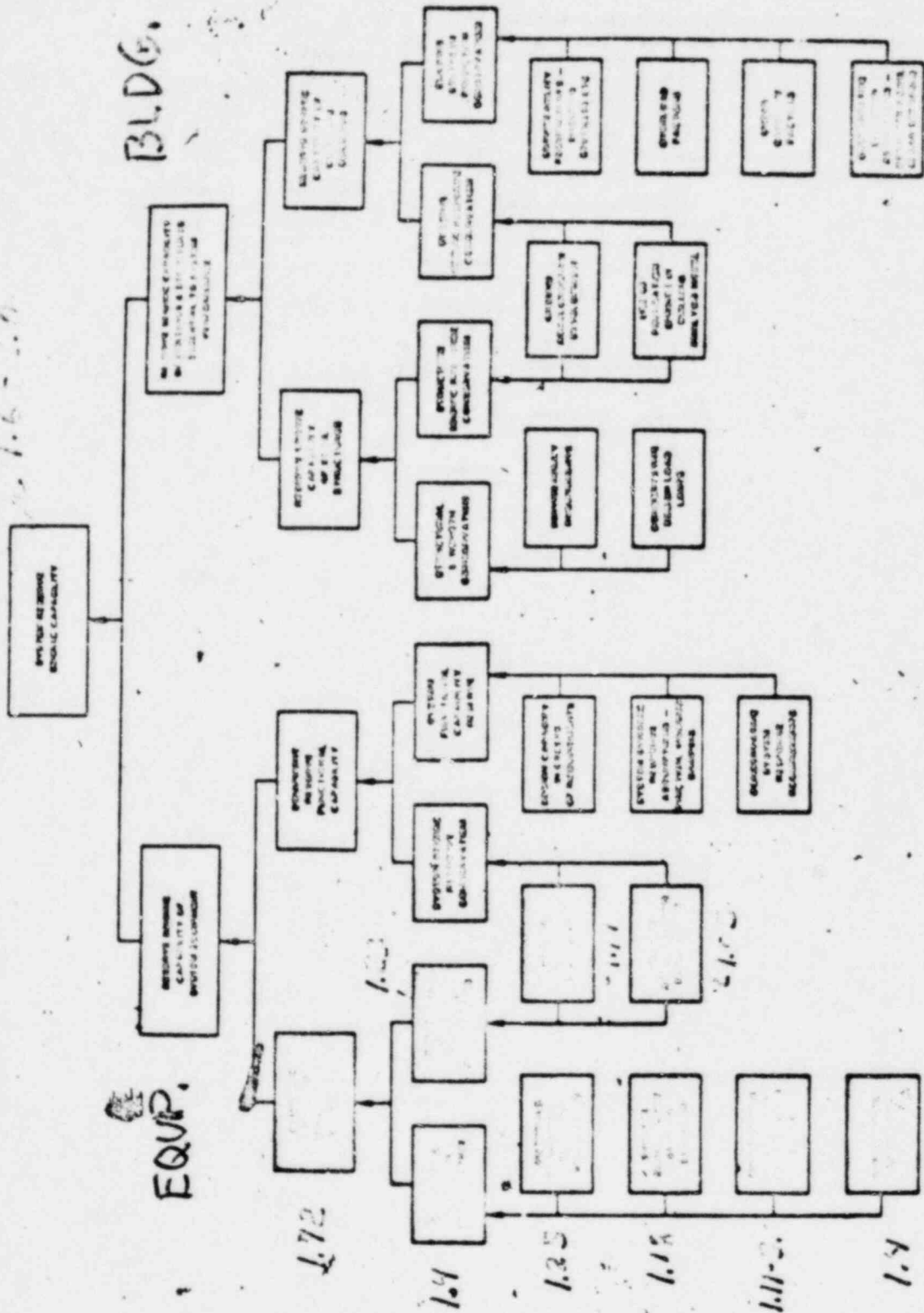
SOURCES OF MARGIN

- CONSERVATIVE PREDICTIONS OF RESPONSE.
- CONSERVATIVE DEFINITIONS OF STRUCTURAL AND PERFORMANCE LIMITS.
- CONSERVATISM INCORPORATED BY DESIGNER.

SEISMIC DESIGN OF HTS COMPONENTS

SYSTEM EVALUATION PROCEDURE FOR SEISMIC MARGIN

(Nominal Allowable)
(Design Limit)



19

SEISMIC DESIGN OF HTS COMPONENTS

LIMIT MARGIN SOURCE

STRENGTH MARGIN

• ASSUMPTION OF MINIMUM STRENGTH MATERIALS PROPERTIES

25%

• DYNAMIC ENHANCEMENT OF MATERIALS YIELD STRENGTH

18%

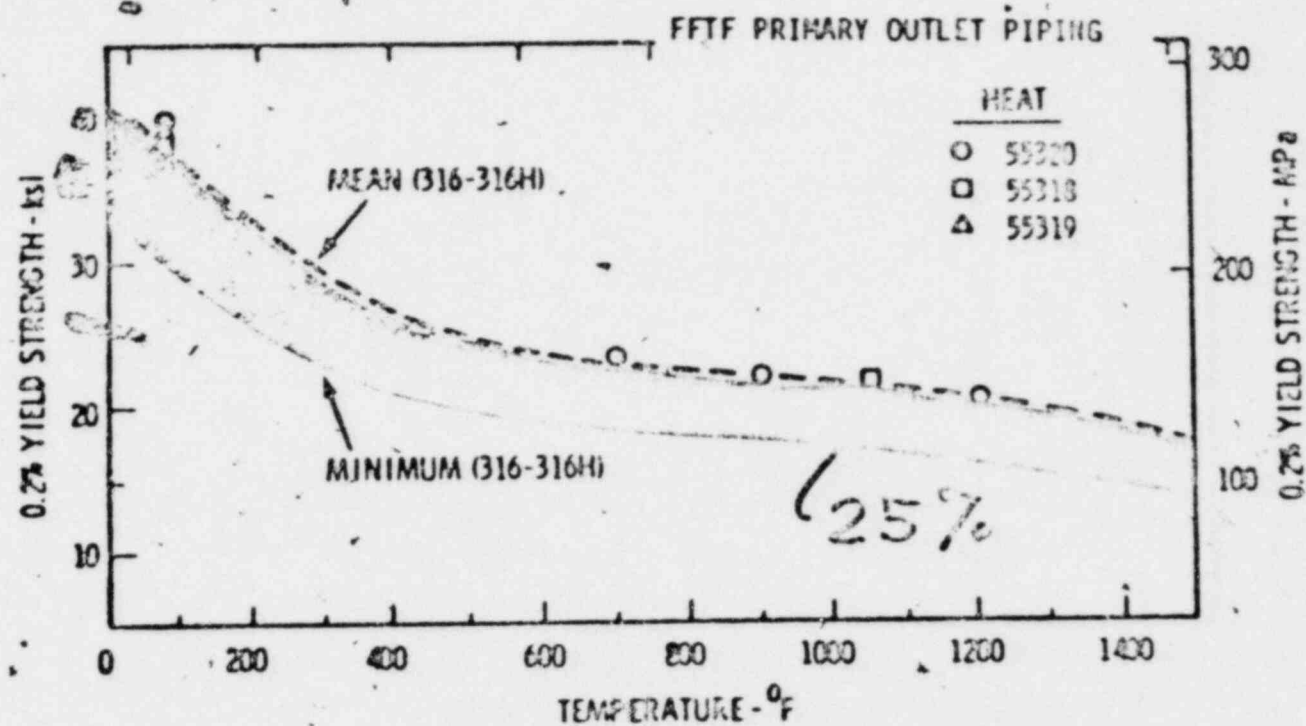
• CONSERVATIVE SAFETY FACTORS BUILT INTO THE DESIGN LOAD &

11% - 300%

STRESS LIMITS

EQUIVALENT STRENGTH MARGIN ≈ 1.4

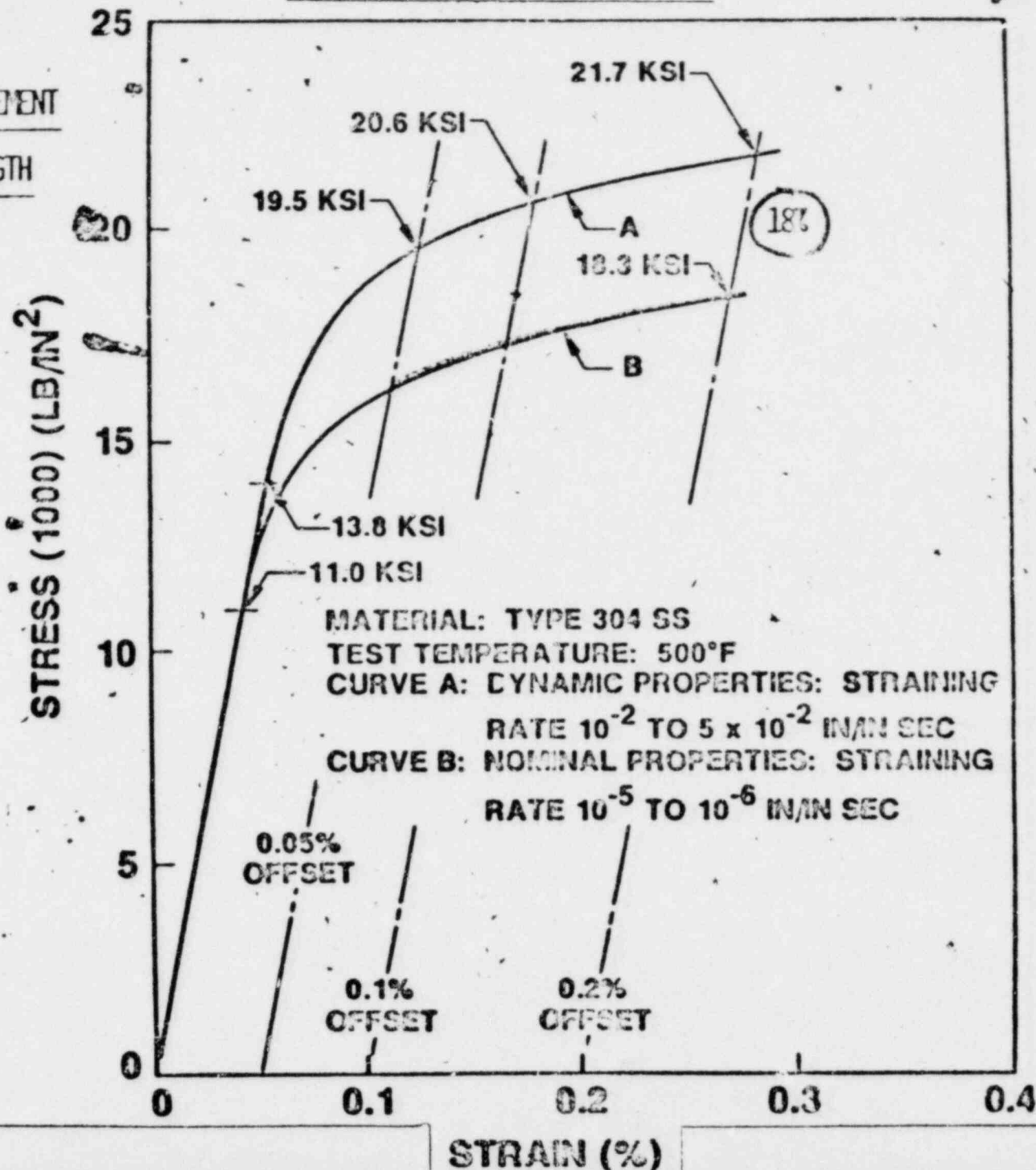
$2 \frac{\text{Nominal Allowable}}{\text{Design Limit}}$



Temperature Dependence of Strength of Type 316H Stainless Steel Piping Material.

SEISMIC DESIGN OF HTS COMPONENTS

DYNAMIC ENHANCEMENT OF YIELD STRENGTH



21
X

RESPONSE MARGIN SOURCE

- DEVELOPMENT OF GROUND ACCELEROGRAM
- USE OF CONSERVATIVE SYSTEM DAMPING COEFFICIENTS

RESPONSE MARGIN

5%

17%

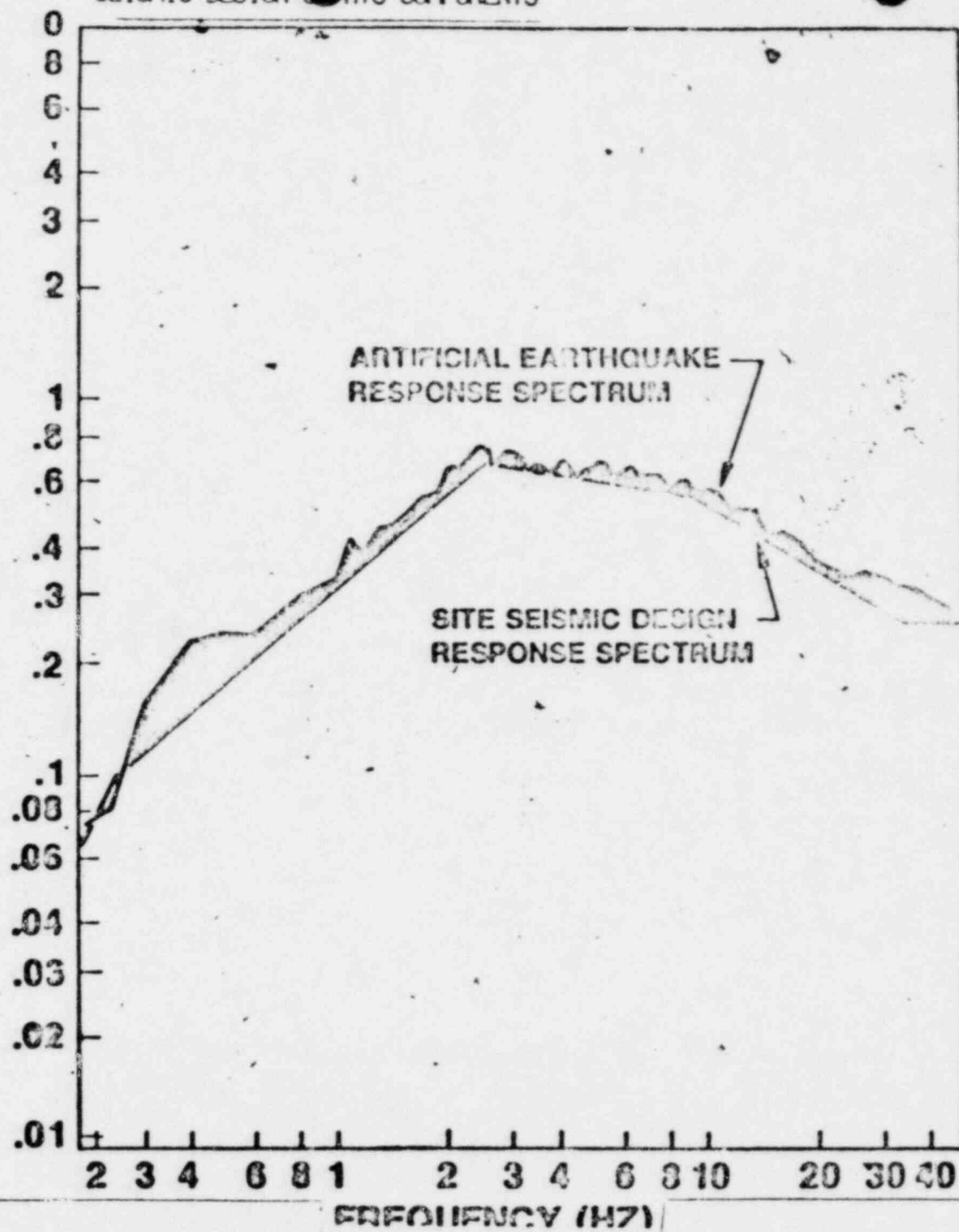
EQUIPMENT CONSERVATISM = $1.05 \times 1.17 = 1.23$

SEISMIC DESIGN LIMITS COMPONENTS

GROUND ACCELERATION

DEVELOPMENT

ACCELERATION (G)



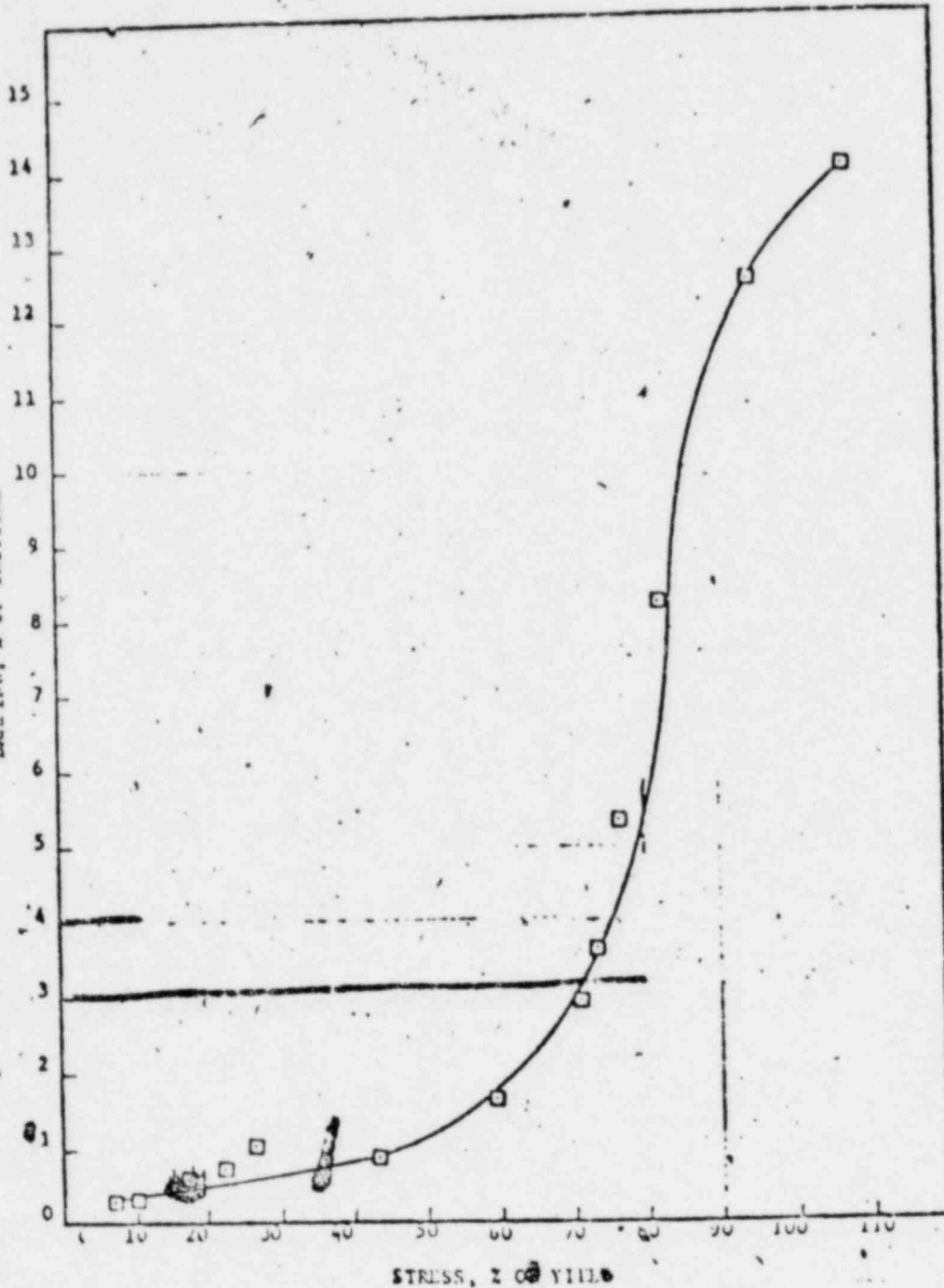
23

X

RESULTS OF FIXED-END 1/2" O.D.
PIPE DAMPING TESTS

DAMPING
DAMPING, % OF CRITICAL

W 4

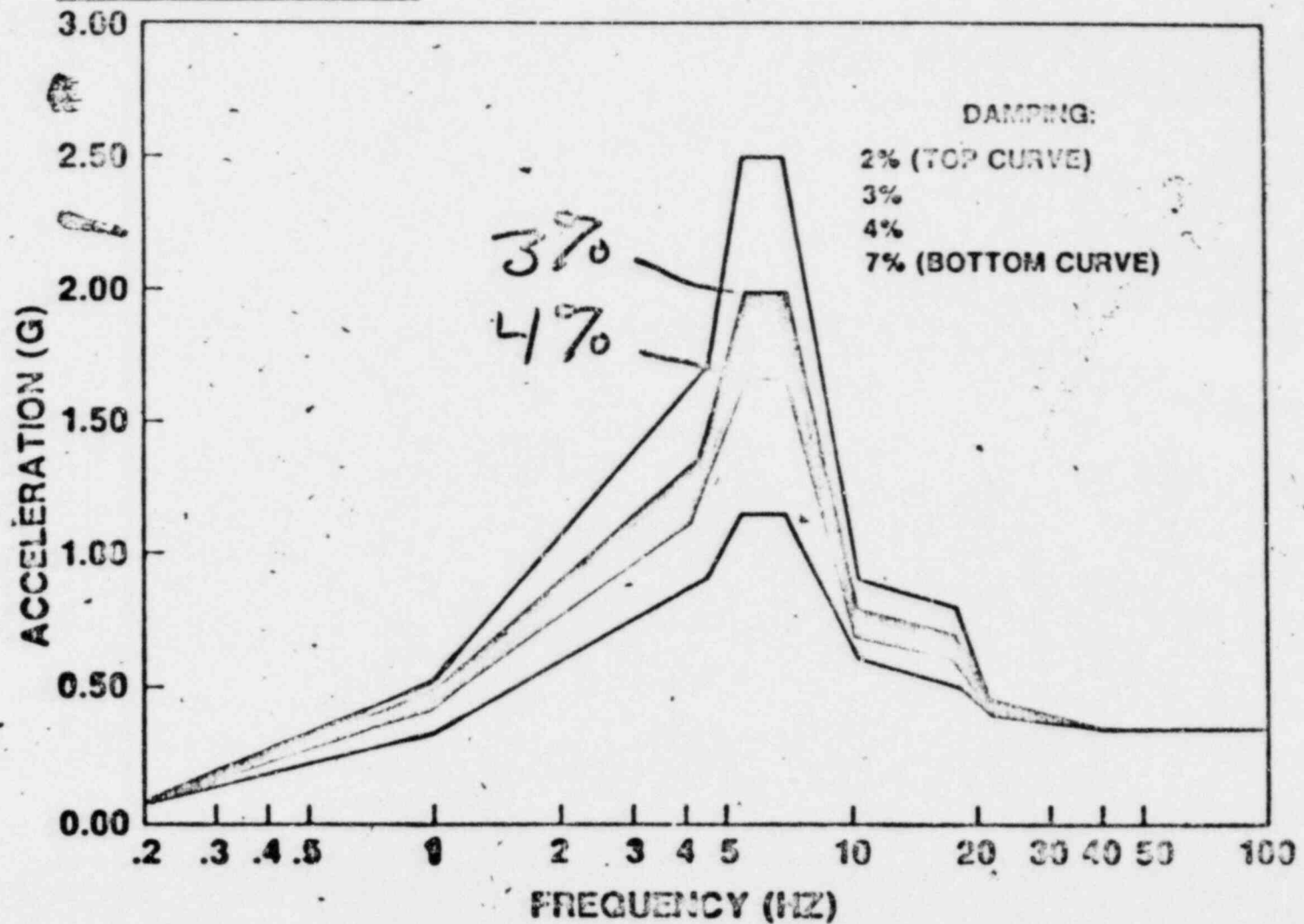


STRESS, % OF YIELD

STRESS

SEISMIC DESIGN OF HTS COMPONENTS

SYSTEM DAMPING ASSUMPTION



SEISMIC DESIGN OF HTS COMPONENTS

2

RESERVE STRUCTURAL STRENGTH

- | | |
|--|-------------|
| • CODE AVERAGE TO MINIMUM YIELD STRENGTH | 1.25 |
| • STRAIN RATE EFFECT ON YIELD STRENGTH | 1.18 |
| • CODE SAFETY FACTORS | 1.50 |
| • COMBINED EFFECT OF ITEMS 1, 2, AND 3 | <u>1.40</u> |

SEISMIC RESPONSE CONSERVATISM

- | | |
|---|-------------|
| • MARGIN BETWEEN THE CRBRP ARTIFICIAL RESPONSE SPECTRUM AND
CRITERIA RESPONSE SPECTRUM | 1.05 |
| • SYSTEM DAMPING INCREASES FOR SEISMIC RESPONSES IN EXCESS OF SSE LEVELS | 1.17 |
| • COMBINED EFFECT OF ITEMS 1 AND 2 | <u>1.23</u> |

COMBINED EFFECT

1.72

CONCLUSIONS

INHERENT SEISMIC MARGIN IS AVAILABLE AND COULD BE USED WITHOUT
COMPROMISING PLANT SAFETY.

QUESTION

Q WHAT ARE SOME OF THE SPECIAL ATTRIBUTES CONSIDERED IN DESIGN OF

CRRP COMPONENTS?

- LOADINGS
- FLEXIBILITY
- CONSEQUENCES

COMPARISON OF SHRSSE RESTRAINT LOADSLOADING

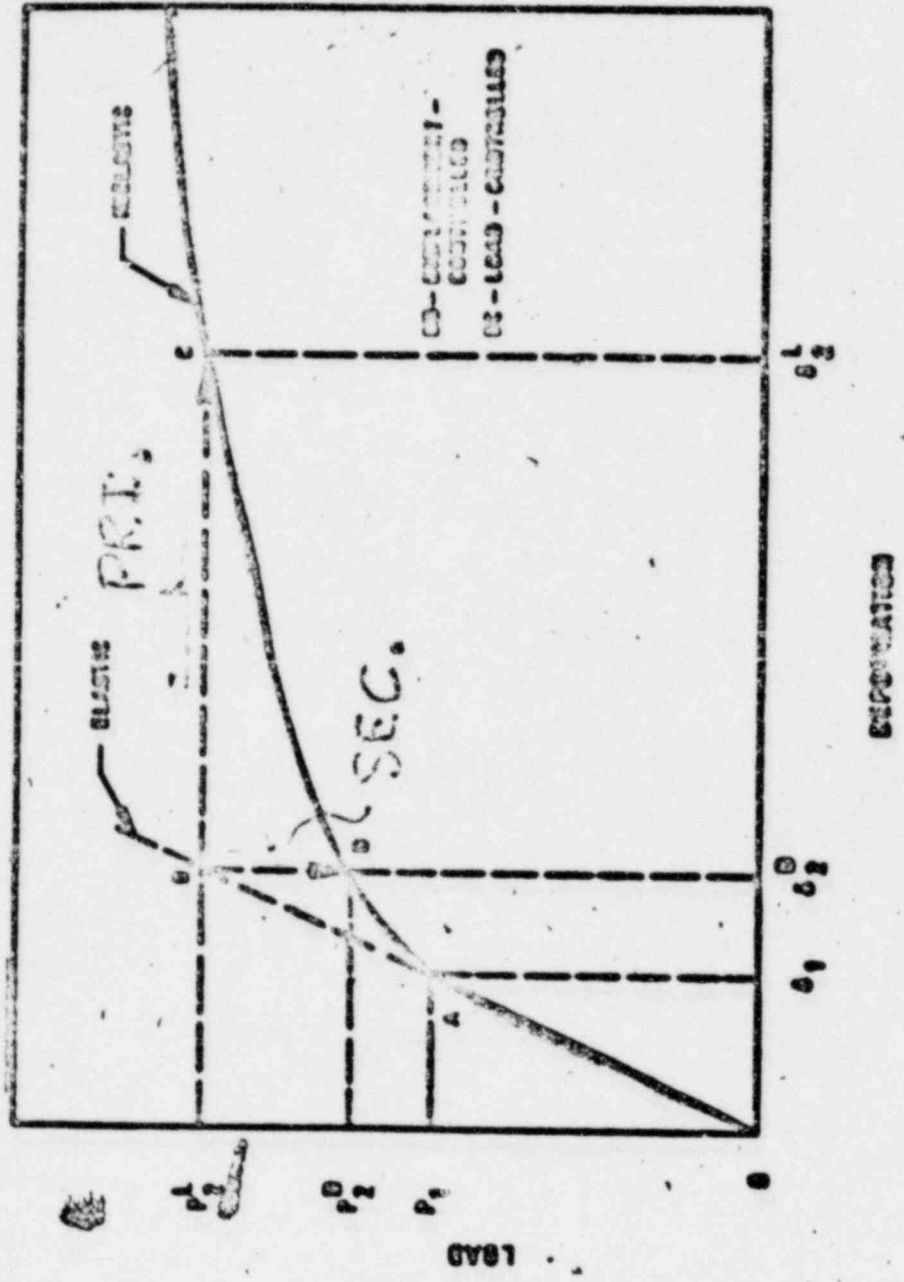
• IHTS HOT LEG PIPING DESIGNED FOR SEISMIC EVENTS.

<u>SNUBBER NUMBER</u>	<u>SSE LOAD KIPS</u>	<u>SHR LOAD, KIPS</u>
S-201	<u>21</u>	<u>60</u>
S-202	20	<u>5</u>
S-204	17	18
S-206	<u>30</u>	<u>45</u>
S-207	12	22
S-211	5	12
S-208	4	19
S-210	15	22

SEISMIC DESIGN OF HTS COMPONENTS

FLEXIBILITY

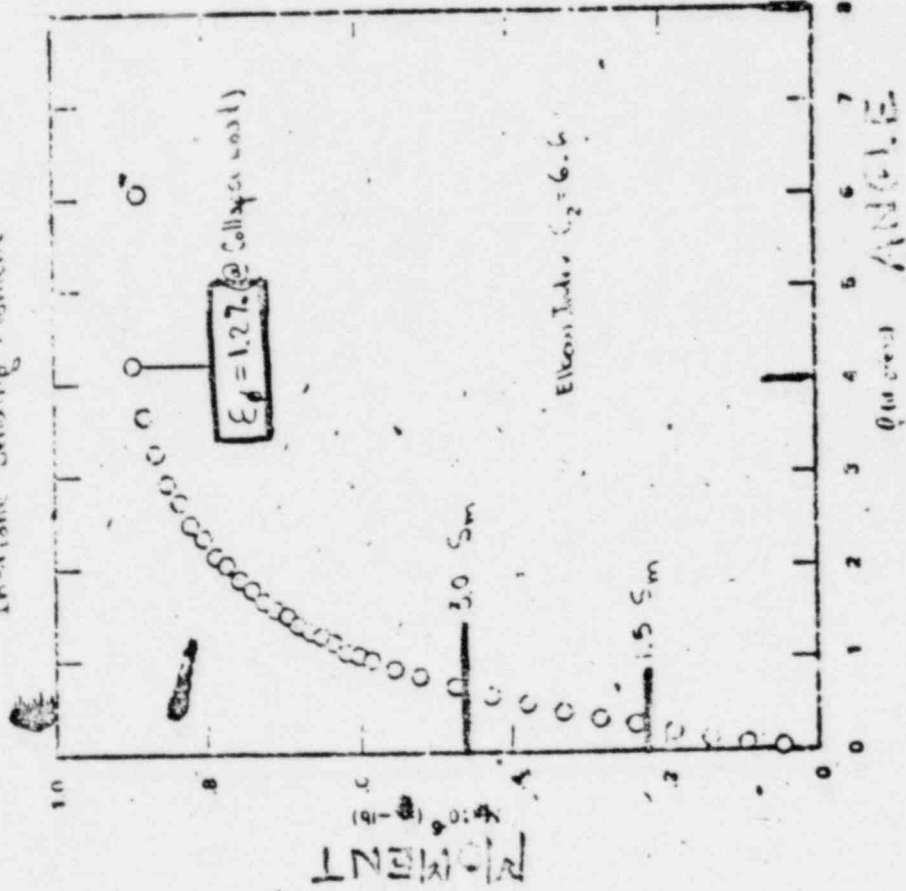
COMPRESSIVE



Division is - load... 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 19 20 21 22 23 24 25 26 27 28 29 30 31 32 33 34 35 36 37 38 39 40 41 42 43 44 45 46 47 48 49 50 51 52 53 54 55 56 57 58 59 60 61 62 63 64 65 66 67 68 69 70 71 72 73 74 75 76 77 78 79 80 81 82 83 84 85 86 87 88 89 90 91 92 93 94 95 96 97 98 99 100

SPECIAL LIMITS

Moment vs Rotation for
16-Inch Elbow with
In-Plane Bending Moment



Can not reach failure strain

THE CORNERS ARE NOT NEARLY

CONSEQUENCES

Dwg 6376A3R

37

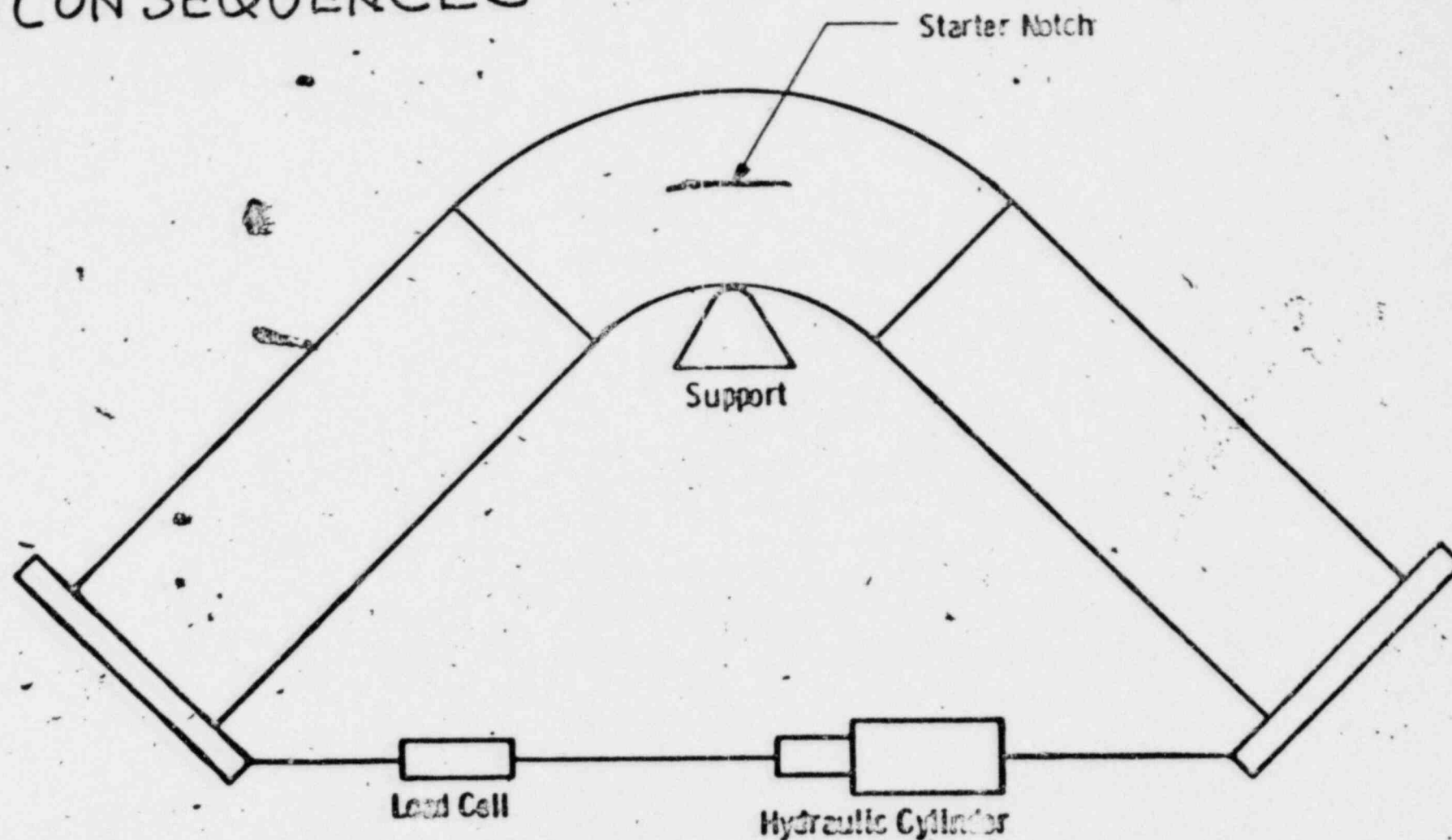


Fig. 24 - Schematic diagram of loading assembly for in-plane bending fatigue test of full-scale elbow

FULL SCALE ELBOW AT END OF
PRESSURIZATION TEST

CONSEQUENCES

EVALUATION OF PIPING INTEGRITY

● BASIC

- BASED UPON DESIGN SPECIFICATION

● SPECIAL

- BASED UPON POSTULATED DEFECT

● EXTENDED

- BASED UPON FORCING CRACK GROWTH

CONCLUSION

- ① - ABRUPT GROSS LEAKAGE IS NOT CREDIBLE

40

SEISMIC DESIGN OF HTS COMPONENTS

CONCLUSION

- CRYOP EXHIBITS SPECIAL ATTRIBUTES THAT REDUCE THE RISK ASSOCIATED

WITH HIGH SEISMIC LOADS.

41

SEISMIC DESIGN OF HTS COMPONENTS

QUESTION

• WHAT SPECIAL ACTIONS HAVE BEEN TAKEN IN VIEW OF LIMITED PRIOR LMFBR

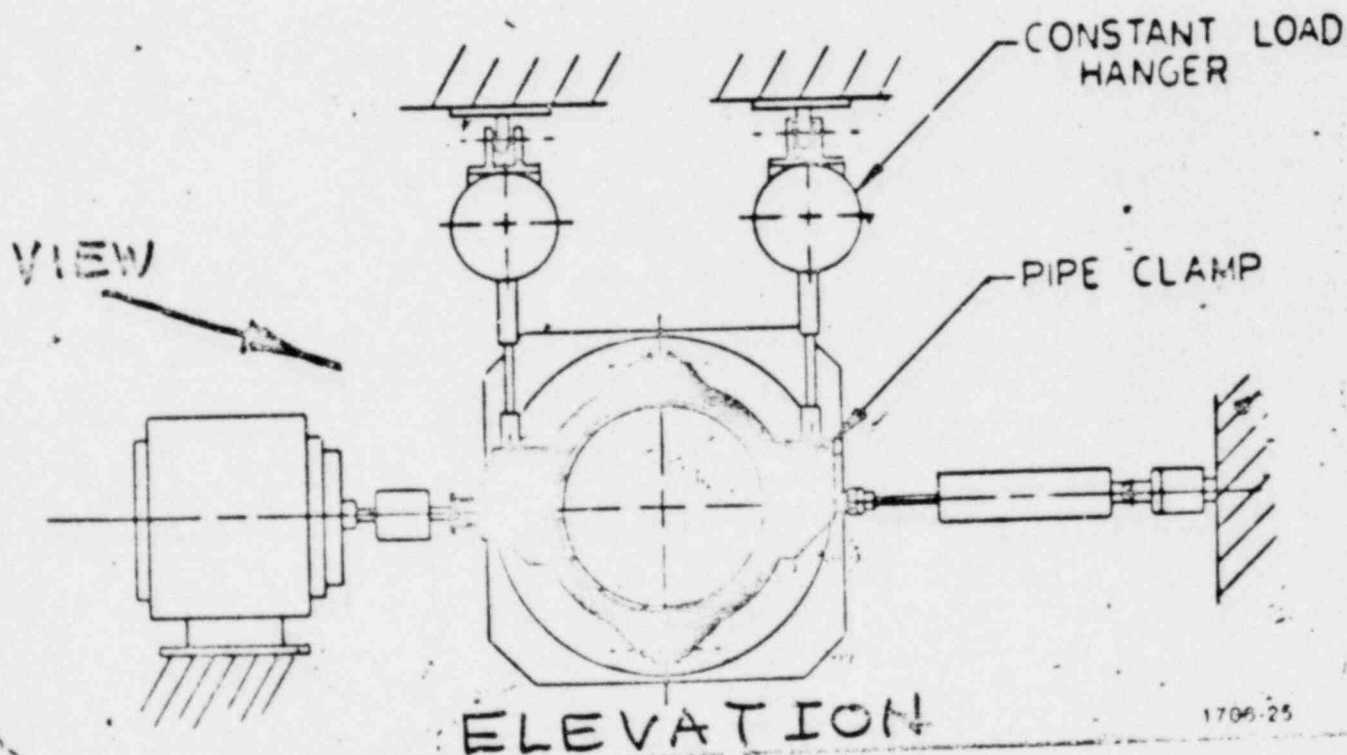
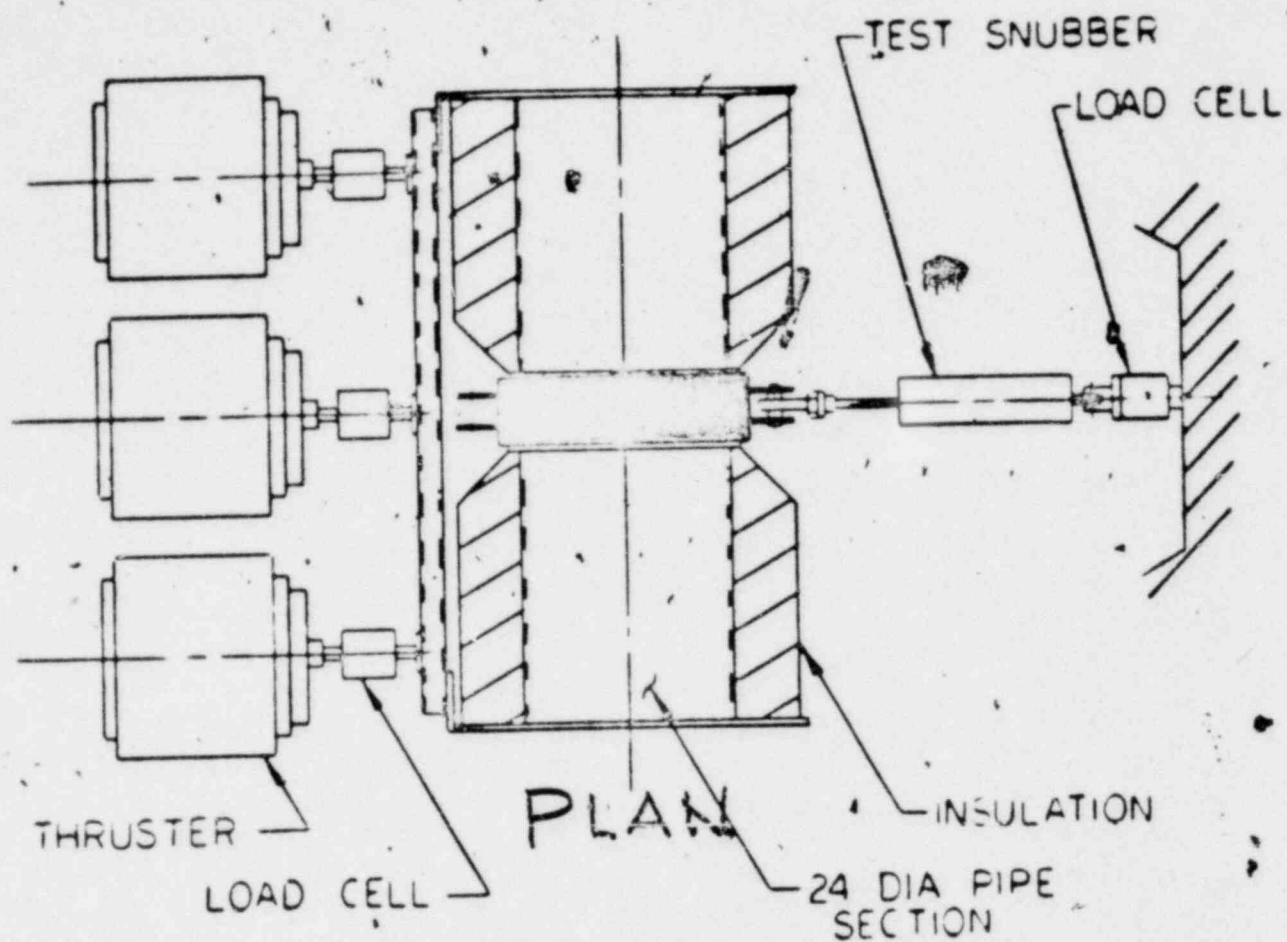
EXPERIENCE?

- DEVELOPMENT

- VERIFICATION

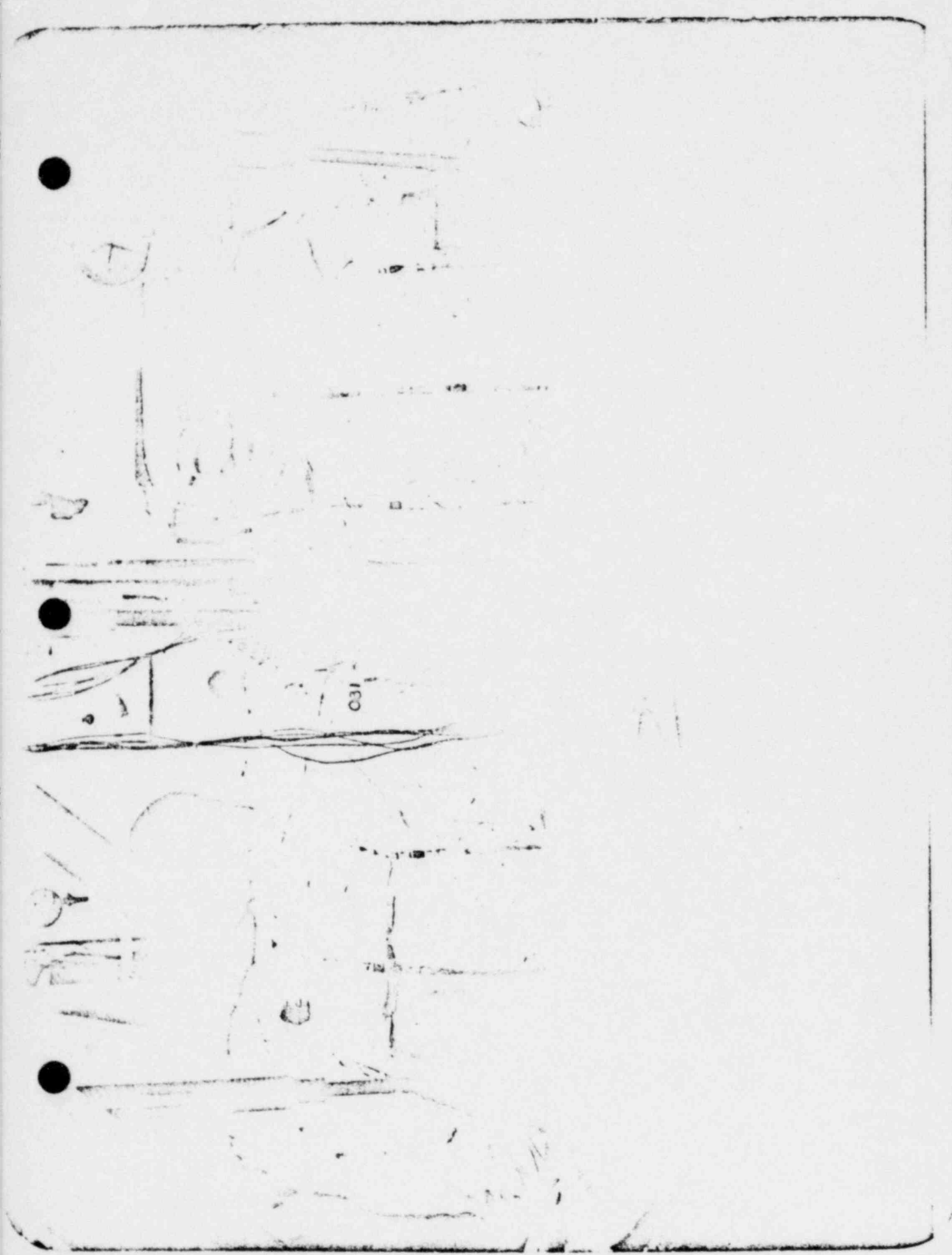
- COORDINATION

CLAMP TEST SETUP



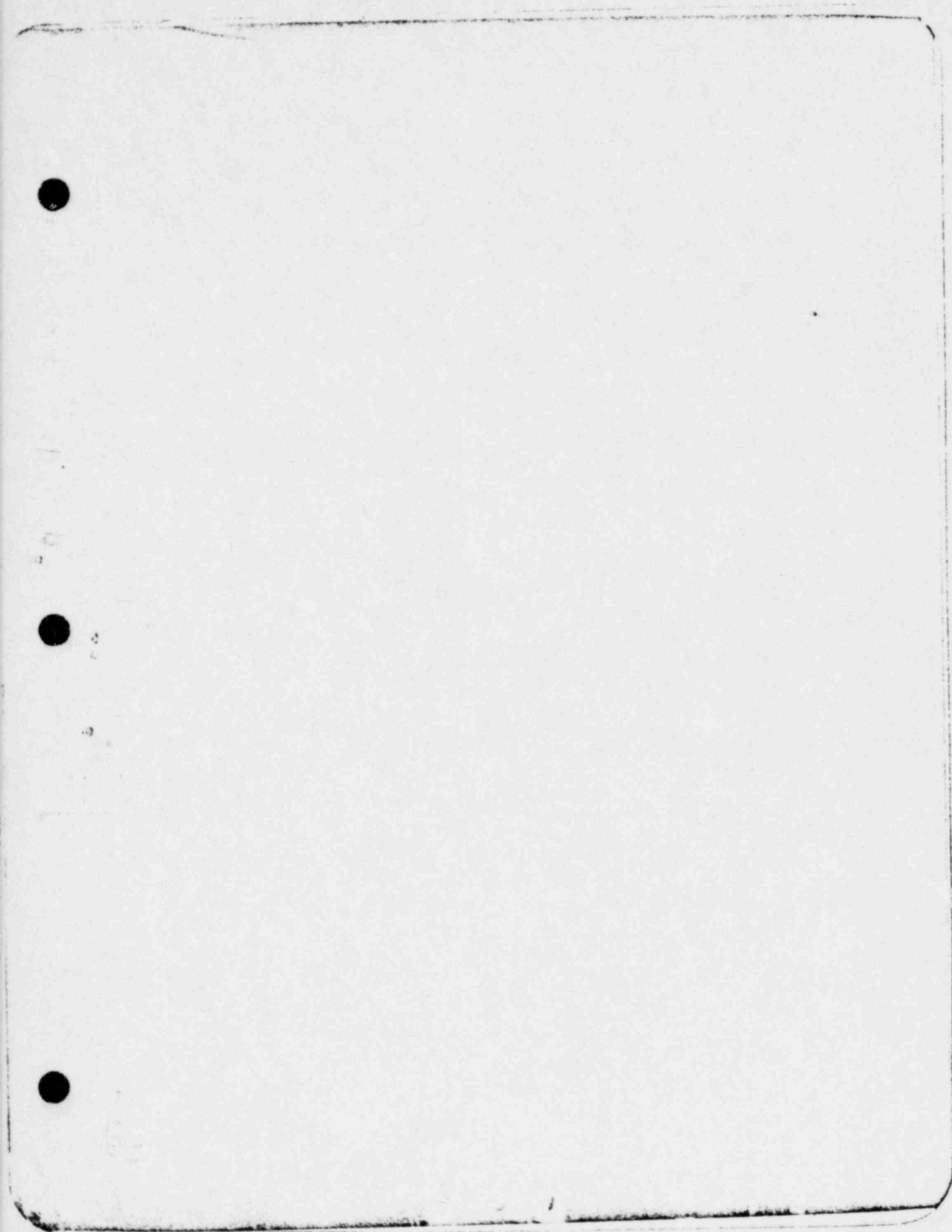
4.

X



7

1



VERIFICATION

PIPING NATURAL FREQUENCIES

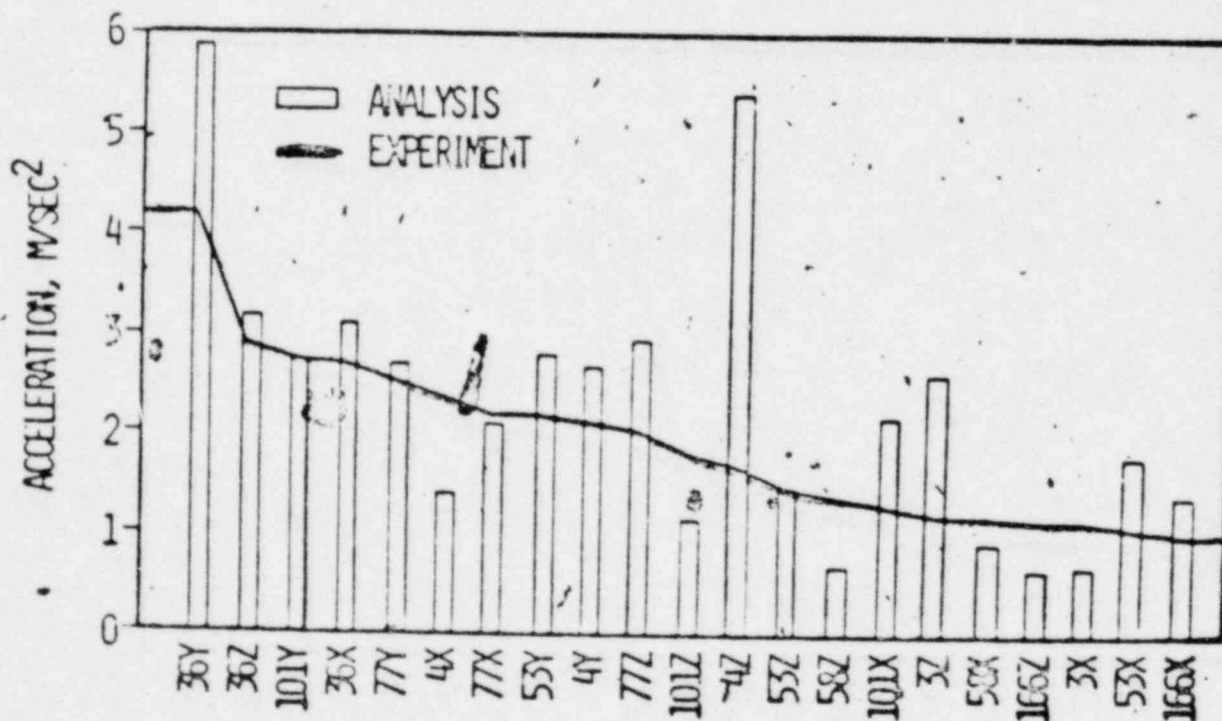
EXPERIMENTAL FREQUENCY, HZ

ANALYTICAL FREQUENCY, HZ

2.40
2.75 - 2.95
3.72 - 3.95

1.82
2.84
3.62

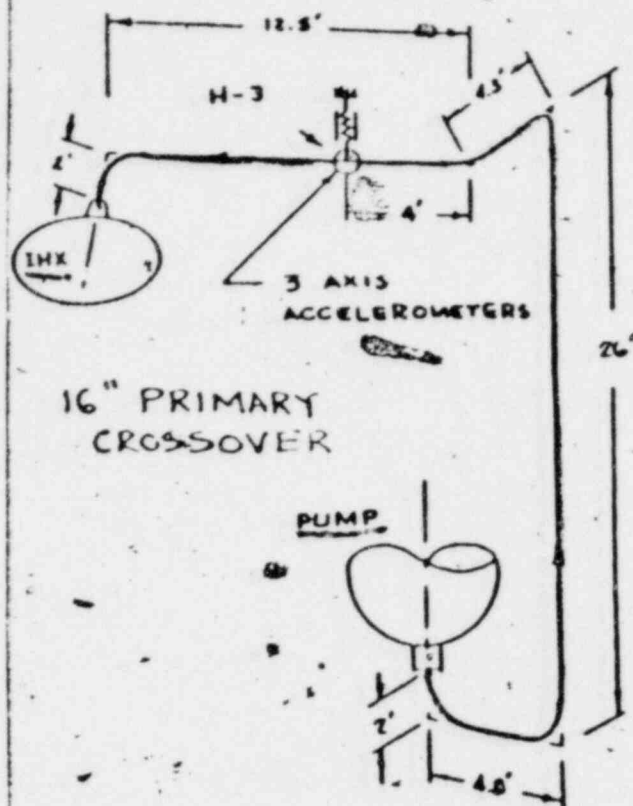
PIPING ACCELERATION RESPONSE



FFTF XOVER PIPING - SURVEY OF PUMP INDUCED VIBRATIONS

46

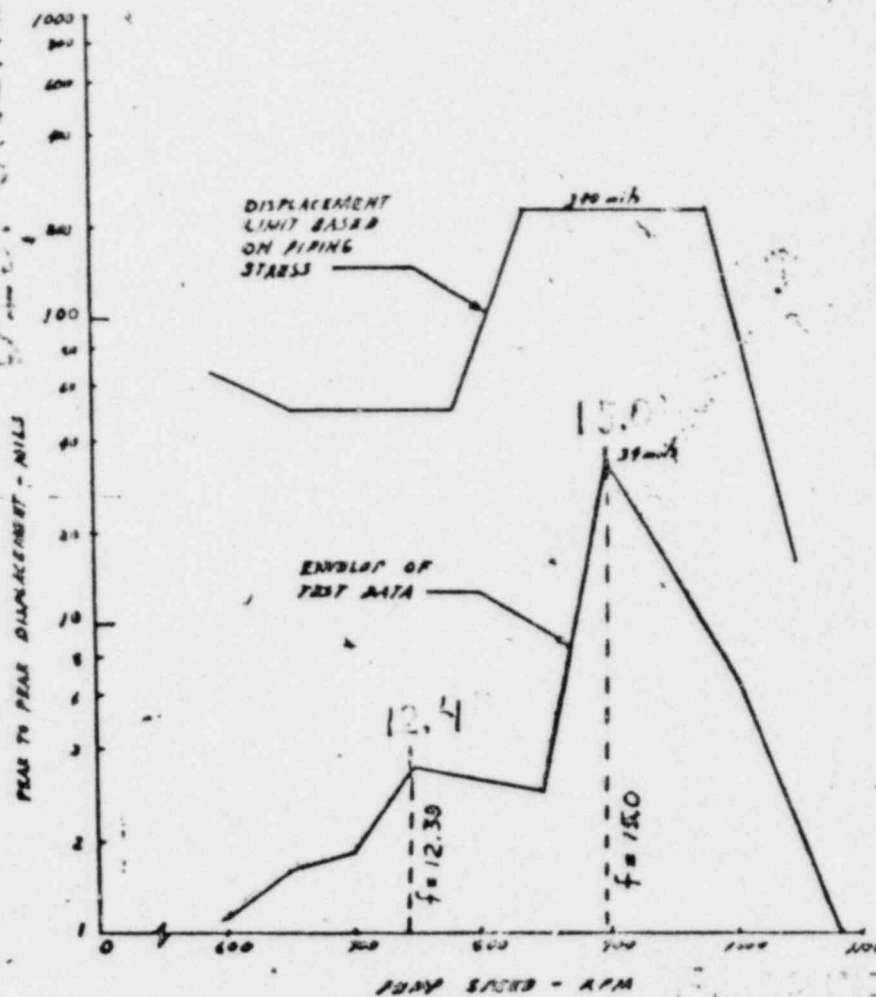
VERIFICATION



NATURAL FREQUENCIES

- $f_1 = 7.522 \text{ Hz (451 rpm)}$
- $f_2 = 8.590 (515)$
- ⑧ $f_3 = 12.129 (728)$
- ⑨ $f_4 = 15.108 (906)$
- $f_5 = 18.922 (1135)$

PEAK TO PEAK DISPLACEMENT - MILS



VIBRATION DISPLS. VS. PUMP SPEED

4

SEISMIC DESIGN OF HTS COMPONENTS

4

COORDINATION

IN-SITU VERIFICATION OF
JOYO PIPING DYNAMICS

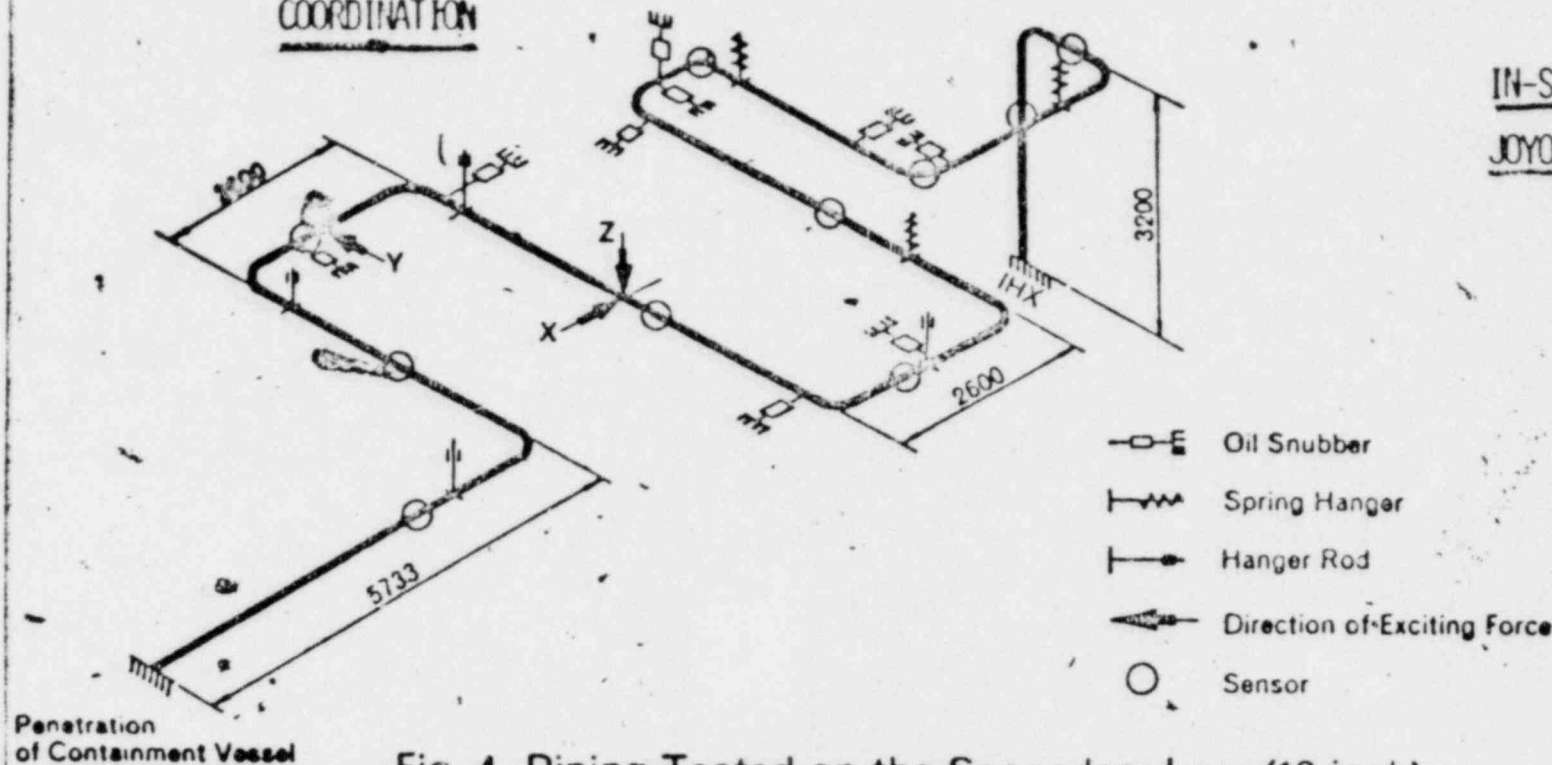


Fig. 4 Piping Tested on the Secondary Loop(12 inch)

MODE	TEST	FREQUENCY (HZ)		TEST DAMPING
		ANALYSIS		
		RIGID	SPRING	
1	5.3	5.9	5.6	17.5 - 18.2
2	7.2	7.5	7.2	14.8 - 22.4
3	8.3	11.1	7.8	---
4	8.8	12.3	10.1	3.7 - 5.3

SEISMIC DESIGN OF HTS COMPONENTS

CONCLUSIONS

- CRRP SEISMIC DESIGN METHODS AND CRITERIA INCLUDE THE CONVENTIONAL CONSERVATISM.
- CRRP COMPONENTS HAVE INHERENT MARGIN THAT COULD BE USED WITHOUT COMPROMISING THE SAFETY OF THE PLANT.
- CRRP EXHIBITS SPECIAL ATTRIBUTES THAT REDUCE THE RISK ASSOCIATED WITH HIGH SEISMIC EVENTS.
- CRRP DESIGN PROGRAMS INCLUDE A WIDE RANGE OF ACTIVITIES TO VERIFY THE DESIGNS AND AVOID OVERSIGHTS.

OVERALL - SEISMIC SAFETY LEVELS FOR CRRP AND LAR COMPONENTS ARE COMPARABLE.