Detroit

2000 Second Avenue Detroit, Michigan 48226 (313) 237-8000

June 6, 1981 EF2 - 53,475 COMMISSION

Mr. L. L. Kintner Division of Project Management Office of Nuclear Reactor Regulation U. S. Nuclear Regulatory Commission Washington, D. C. 20555

Dear Mr. Kintner:

Reference: Enrico Fermi Atomic Power Plant, Unit 2 NRC Docket No. 50-341

Subject: Regulatory Guide 1.133 - Loose Part Detection System -Verbal Question from B. K. Sun

In response to Mr. Suns request of June 5, 1981, Detroit Edison commits to revise its Appendix A compliance statement with Regulatory Guide 1.133. This revision will state Detroit Edison's degree of conformance with RG 1.133. A technical description will also be added to the appropriate section of the FSAR.

For your use, a technical description of the Fermi 2 Loose Parts Monitoring System is attached.

Sincerely,

William & Mast

William F. Colbert Technical Director Enrico Fermi 2

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Attachment



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ENRICO FERMI UNIT 2 PROJECT Instrumentation & Controls

1.0 Description of Loose Parts Monitoring System (LPM) B2107.

The LPM system used at the Enrico Fermi Atomic Power Plant Unit II is furnished by Babcock & Wilcox.

This system provides the capability to detect, alarm and record acoustic signals generated when loose parts within the reactor coolant system impact other reactor coolant system components. The system provides a contact output to the control room annunciator to notify the operator that a loose part has been detected.

- 2.0 The basic system is capable of performing the following functions:
  - Detect acoustic signals gene i from mechanically attached sensors (accelerometers).
    - 2.1.1 The eight (8) sensors are located as follows:
      - \* Vessel bottom CRD housing, two (2) sensors
      - \* Recirculating pumps inlet lines, one (1) sensor for each of the two (2) lines
      - \* Feedwater headers, one (1) sensor for each of two (2) headers
      - \* Steam headers, two (2) of the four (4) selected. One (1) sensor for each of the two (2) lines
  - 2.2 The alarm logic is capable of distinguishing and identifying signals equivalent to 0.5 ft/lbs within 3 ft of the sensor from the plant background signal (signature). The alarm threshold is adjustable for each channel (sensor string). The logic is designed to minimize false alarms.
  - 2.3 The alarm logic will give visual alarm alert. \* contact to plant annunciator \* one light per channel - local display

- 2.4 The alarm logic is capible of indicating the first channel to alarm and also to determine the four (4) most critical sensors signals/channels to be recorded on magnetic tape and loose part locator.
- 2.5 The alarm logic is capable of automatic starting of the magnetic tape recorder. Encoding of the tape will display the sensor/ channel assignment during play back of the tape.
- 2.6 The system is capable of providing real time audio output and connection for visual presentation.
- 2.7 The system is capable of manually selecting channels for audio monitoring.
- 3.0 BOP power sources and tray systems are being used.
- 4.0 The sensors are mechanically attached per B&W design recommendation.
- 5.0 The NEMA 12 cabinet which contains the electronic logic is seismically qualified by analysis to be structurally sound.
- 6.0 Field experience with this system has shown a high degree of reliability.

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