PAGE REPLACEMENT GUIDE FOR

AMENDMENT 56

CLINCH RIVER BREEDER REACTOR PLANT

PRELIMINARY SAFETY ANALYSIS REPORT

(DOCKET NO. 50-537)

Transmitted herein is Amendment 56 to the Clinch River Breeder Reactor Plant Preliminary Safety Analysis Report, Docket 50-537. Amendment 56 consists of new and replacement pages for the PSAR text.

Vertical lines on the right hand side of the page are used to identify question response information and lines on the left hand side are used to identify new or changed design information.

The following attached sheets list Amendment 56 pages and instructions for their incorporation into the Preliminary Safety Analysis Report.

AMENDMENT 56

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AMENDMENT 56

QUESTION/RESPONSE SUPPLEMENT

This Question/Response Supplement contains an Amendment 56 tab sheet to be inserted following the Q-i (Amendment 55, June 1980) page. Page Q-i (Amendment 56, August 1980) is to follow the Amendment 56 tab.

There are no new or updated Question/Response pages included in this Amendment.

No.	Title	Rev.	Discussed Further in PSAR Section(s)
1.38	Quality Assurance Requirements for Packaging, Shipping, Receiving, Storage & Handling of Items for Water-Cooled Nuclear Power Plants (5/77)	2	17.1, Question 411.2
1.39	Housekeeping Requirements for Water-Cooled Nuclear Power Plants (3/16/73)		17.1, Question 411.2
1.40	Qualification Tests of Continuous- Duty Motors Installed Inside the Containment of Water-Cool of Nuclear Power Plants (3/16/73)	0	7.1.2 (Tables 7.1-2 and 7.1-3) 8.3
1.41	Preoperational Testing of Redundant On-Site Electric Power Systems to Verify Proper Load Group Assignments (3/16/73)	0	8.3
1.42	Interim Licensing Policy and As Low As Practicable for Gaseous Radio- iodine Releases from Light-Water- Cooled Nuclear Power Reactors (6/73)	-	This Guide has been withdrawn by the NRC.
1.43	Control of Stainless Steel Weld Cladding of Low-Alloy Steel Components (5/73)	0	Note 3
1.44	Control of the Use of Sensitized Stainless Steel (5/73)	-	NA
1.45	Reactor Coolant Pressure Boundary Leakage Detection System (5/73)	-	NA
1.46	Protection Against Pipe Whip Inside Containment (5/73)	-	NA
1.47	Bypassed and Inoperable Status Indi- cation for Nuclear Power Plant Safety Systems (5/73)	0	7.1.2.9

	No.	Title	Rev.	Discussed Further in PSAR Section(s)
	1.48	Design Limits and Loading Combinations for Seismic Category I Fluid System Components (5/73)	0	3.9.1.5
	1.49	Power Levels of Nuclear Power Plants	1	Due to the Power Levels of CRBRP, this Guide has no impact.
	1.50	Control of Preheat Temperature for Welding of Low-Alloy Steel (5/73)	0	Note 4
25	1.51	Inservice Inspection of ASME Code Class 2 and 3 Nuclear Power Plant Components (5/73)	-	This Guide has been with- drawn by the NRC.

the secondary shutdown system is arranged using a general coincidence logic. These logics are described in Section 7.2.1. Primary and secondary systems are electrically and mechanically isolated. Sufficient redundancy is included within each system to assure that single random failures will not degrade protection by either system.

1.2.7 Auxiliary Systems

The Auxiliary Liquid Metal System provides the facilities for receipt, storage and purification of all liquid metal used in the CRBRP. It also provides the capability for controlling reactor sodium level variations, accommodates primary sodium volumetric changes, provides cooling for the core components stored in the Ex-Vessel Storage Tank (EVST), and by means of the Direct Heat Removal Service (DHRS) gives a means of long term reactor decay heat removal that is independent of the intermediate heat transport system and steam generator system loops.

The Compressed Gas System processes ambient air to provide compressed dry air for pneumatic instruments, maintenance systems, unloading devices, tooling, and miscellaneous cleaning and inspection services. This system provides for sodium removal systems and as required for plant usage.

The Recirculating Gas Cooling System provides cooling service to cells and equipment located in the Reactor Containment Building and the Reactor Service Building.

The Chilled Water Systems provide heat removal capability from certain equipment and areas in the Reactor Containment Building and the Reactor Service Building.

The Inert Gas Receiving and Processing System (IGRPS) provides inert gases as required by other systems of the CRBRP, including cover gas, cell inerting atmosphere, valve actuation gas in inerted cells, cooling gas, gas for certain seals, gas for fire-control blanketing, for component cleaning and other services, and vacuum for out-gassing and gas-collection purposes. In addition, the IGRP System provides for the control of reactor cover gas radioactivity and for the processing of gases to be released from the system to remove their contained radioactivity.

The Impurity Monitoring and Analysis System provides for the sampling, monitoring, and analysis of the sodium, NaK, and argon cover gas systems in the plant, and acceptance sampling and analysis of incoming sodium, NaK, argon, and nitrogen.

The Treated Water System includes the domestic (potable) water system, the closed cooling water system, water (makeup) treatment system and the cooling water makeup system.

The River Water Service System handles and treats river water for the plant. The system includes the river water pumps and piping, intake filtration equipment and the plant service water system.

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The Heat Rejection System provides the heat sink using the main cooling tower for waste heat loads from the turbine condensers, and from the various plant auxiliary and service systems such as sodium pump oil coolers, air conditions, air compressors, pump coolers and the turbine oil coolers. The Emergency Plant Service Water System emergency cooling tower structure provides the heat sink for the safety related components listed in Table 9.9-3. Details of the auxiliary system are given in Chapter 9.

1.2.8 Refueling System

refueling operations.

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The reactor core is designed to be refueled annually. Under equilibrium conditions, all fuel and inner blanket assemblies are replaced as a batch every two years, with a planned mid-term interchange of 6 inner blanket assemblies for 6 fresh fuel assemblies designed to add sufficient excess reactivity to the system to complete the (550 fpd) burnup. The radial blanket assemblies in the first and second rows are replaced as a batch at 4 and 5 year intervals, respectively. No fuel or blanket shuffling is planned.

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The In-Vessel Handling Subsystem (IVHS) provides for the transfer of core assemblies in the reactor vessel, between their normal positions in the reactor core and storage positions outside the core accessible by the Exvessel Transfer Machine. The major equipment comprising the IVHS are the In-Vessel Transfer Machine (IVTM), Auxiliary Handling Machine (AHM), AHM Floor Valves (FV), IVTM Port Adaptors, and associated maintenance and storage facilities and equipment. The IVTM is installed in the small rotating plug in the reactor head after reactor shutdown. The machine raises or lowers core assemblies by means of a grapple. Translation to a new position is by rotation of the reactor head rotatable plugs. The AHM is used to install and remove the control rod drivelines, port plugs, and in-vessel section of the IVTM in the reactor. The port adaptors and floor valves provide a means for closure of the reactor and storage ports during the time the port plugs are removed for

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The Ex-Vessel Handling Subsystem (EVHS) provides for the transfer of core assemblies between the reactor, the Ex-Vessel Storage Tank (EVST), and the Fuel Handling Cell (FHC) located in the Reactor Service Building (RSB). The system consists of the Ex-Vessel Transfer Machine (EVTM) mounted on a Gantry-Trolley (G-T), EVTM Floor Valves (FV), Core Component Pots (CCP), port plugs and adaptors, and associated maintenance and storage equipment and facilities.

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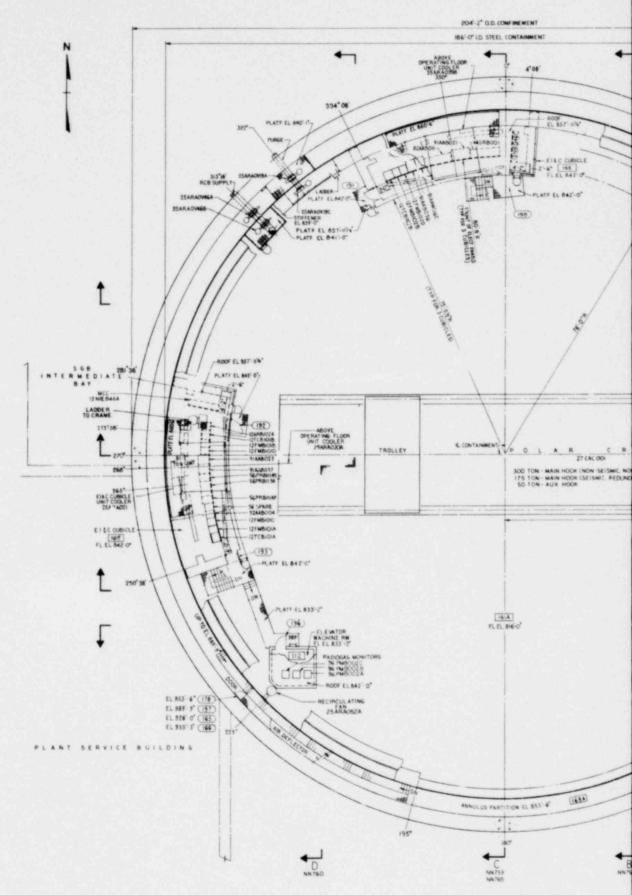
The Ex-Vessel Storage Subsystem (EVSS) consists of the Ex-Vessel Storage Tank (EVST), and the associated maintenance equipment. The EVST is a sodium-filled tank used to store and cool spent fuel prior to shipment offsite, and preheat new core assemblies. The capacity of the EVST is about 650 assemblies.

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Amend. 51

Sept. 1979



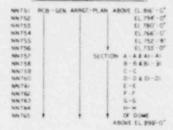
PLAN ABOVE EL 842'-0"

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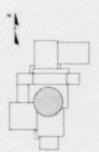
GENERAL NOTES

I. FOR PADIATION ZONING, SEE *DESIGN RADIATION DOSE RATES*

REFERENCE DRAWINGS



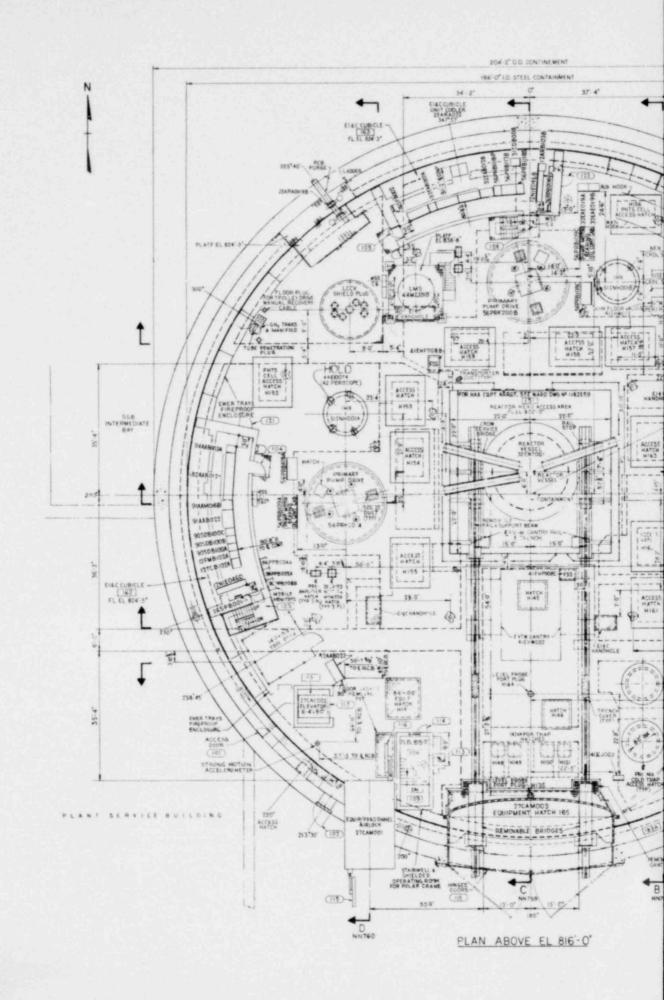
GRAPHIC SCALE



KEY PLAN

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General Arrangement
Reactor Containment Building
Plan El. 842'-0"

1.2-16



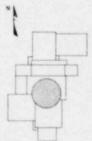


L FOR GENERAL NOTES &LEGEND, SEE DWG NA750

REFERENCE DRAWINGS



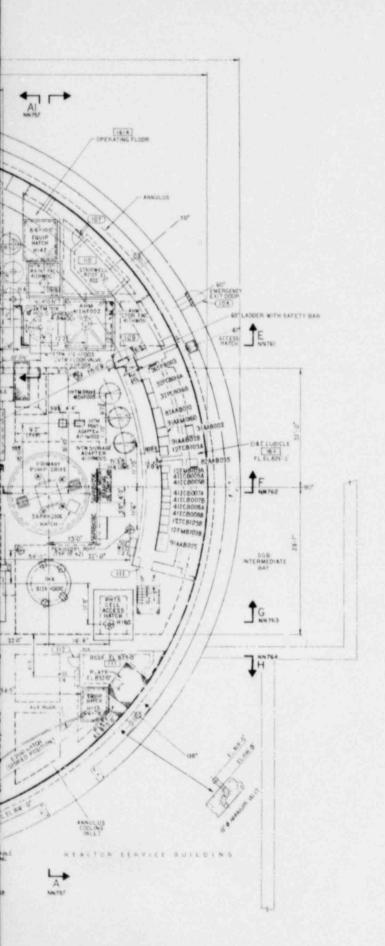


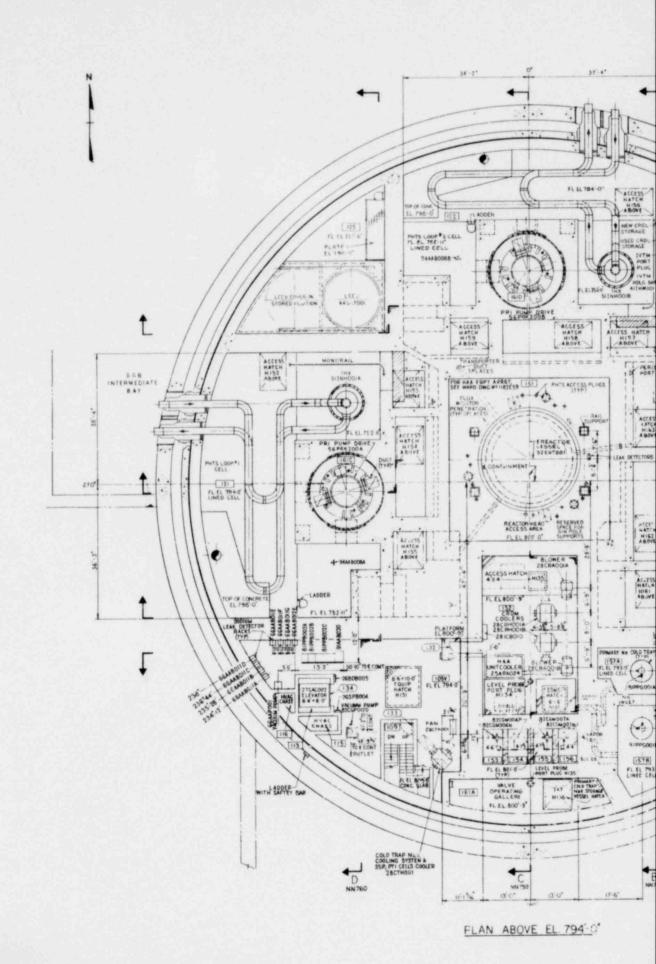


KEY PLAN

Figure 1.2-6
General Arrangement
Reactor Containment Building
Plan El. 816'-0"

1.2-17

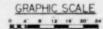


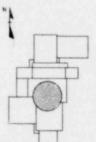


NN752-14

I. FOR GENERAL NOTES & LEGEND, SEE DWG NN 750

REFERENCE DRAWINGS

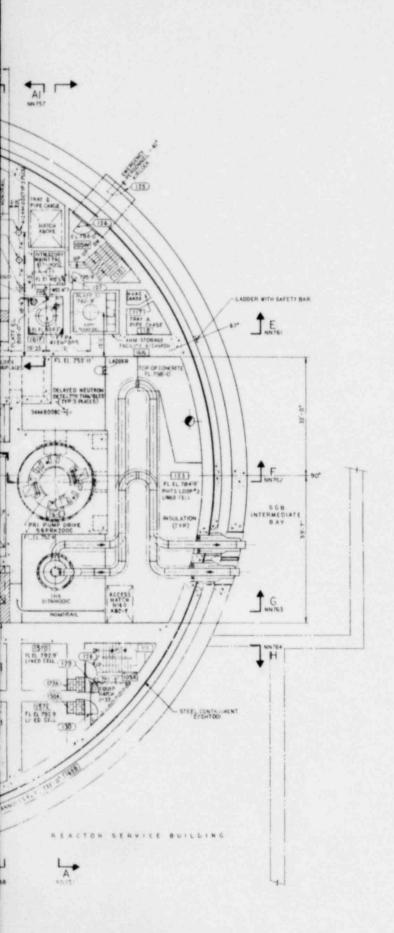


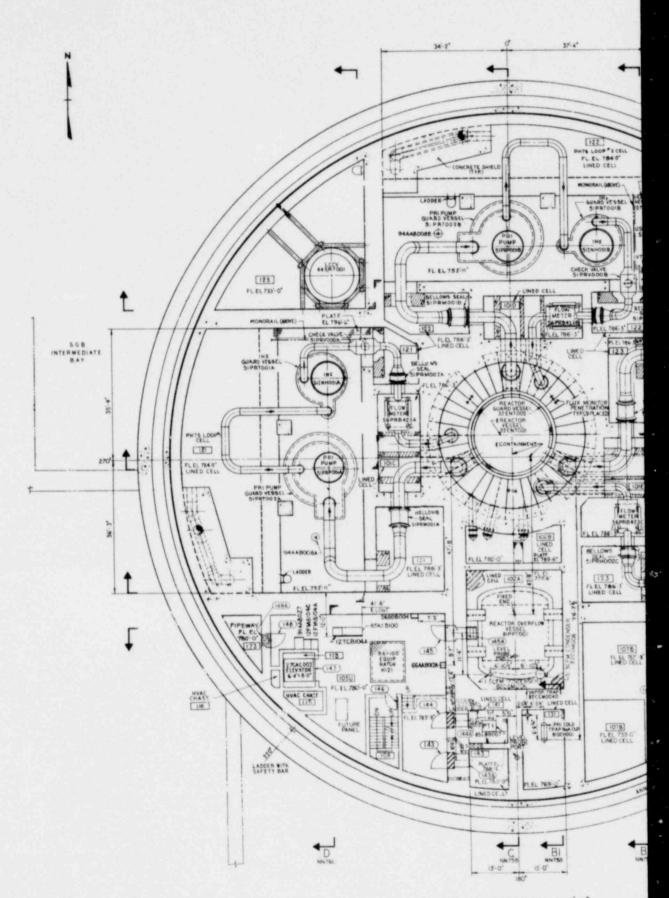


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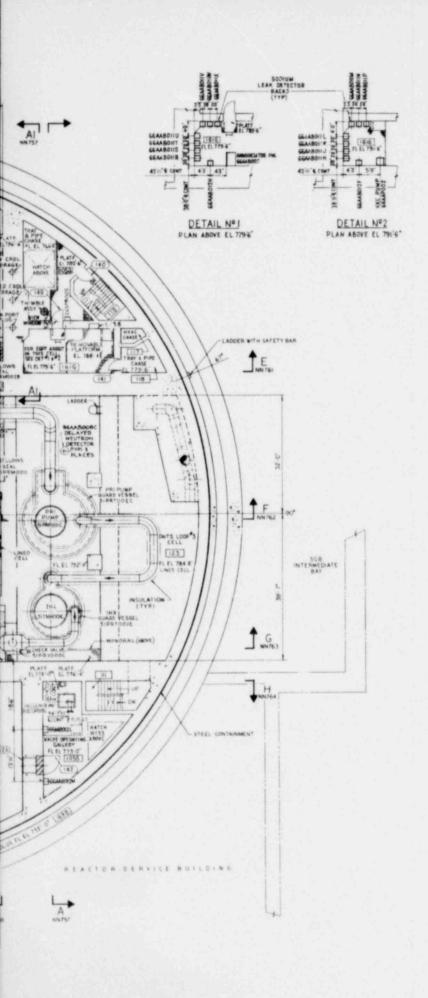
Figure 1.2-7
General Arrangement
Reactor Containment Building
Plan El. 794'-0"

1.2-18





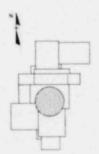
PLAN ABOVE EL. 780-0"



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REFERENCE DRAWINGS
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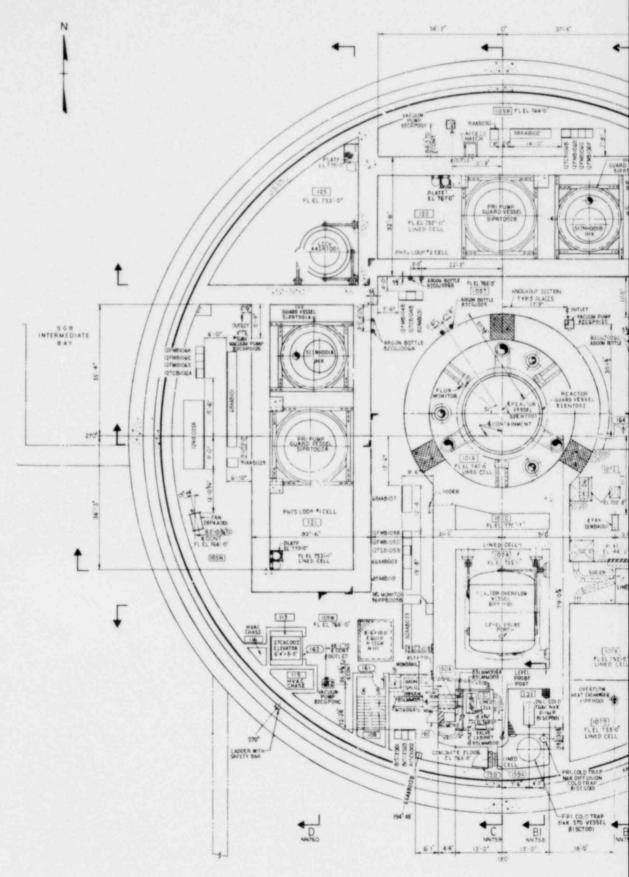




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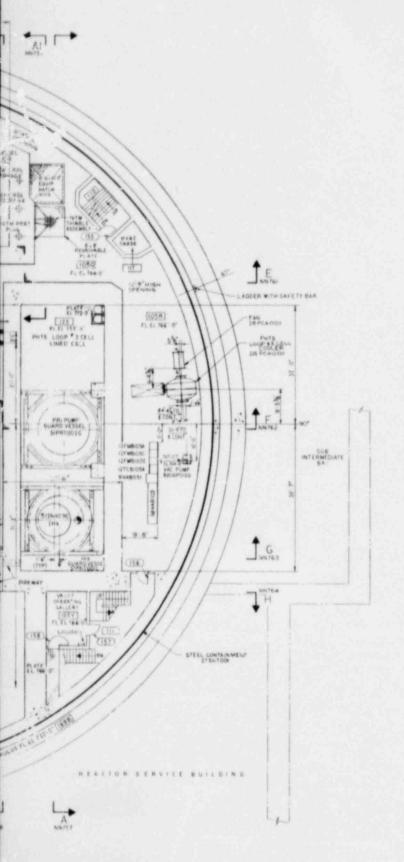
Figure 1.2-8
General Arrangement
Reactor Containment Building
Plan El. 780'-0"

1.2-19



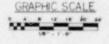
PLAN ABOVE EL. 766'-0"

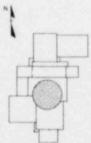
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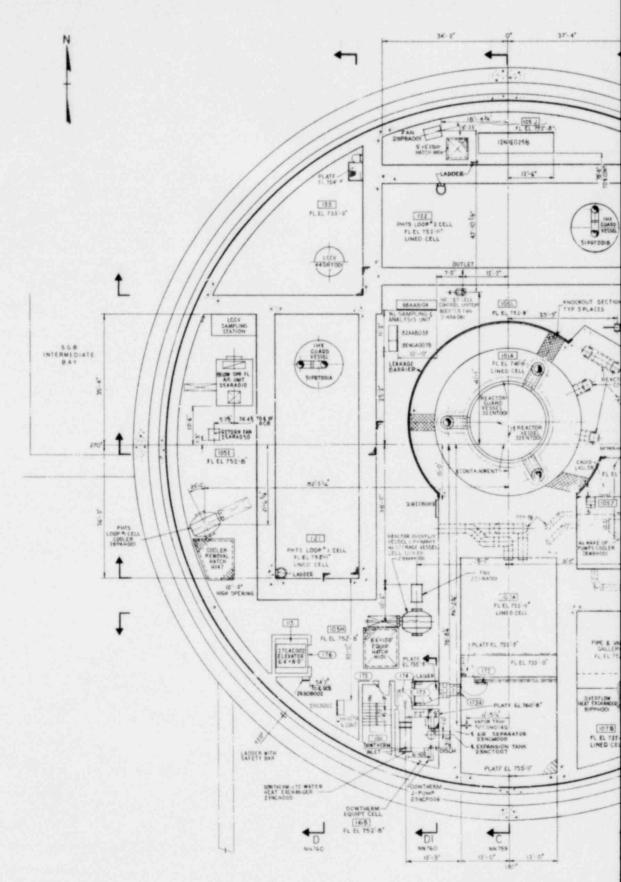




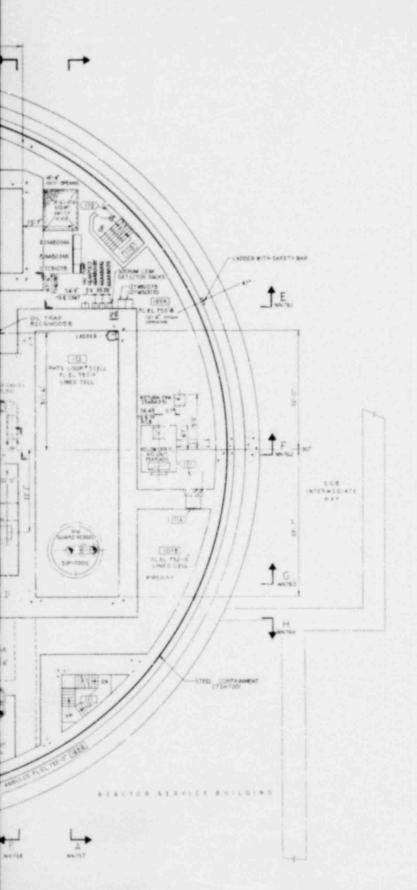
KEYPLAN

Figure 1.2-9
General Arrangement
Reactor Containment Building
Plan El. 766'-0"

1.2-20

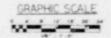


PLAN ABOVE EL. 752'-8"



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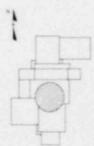


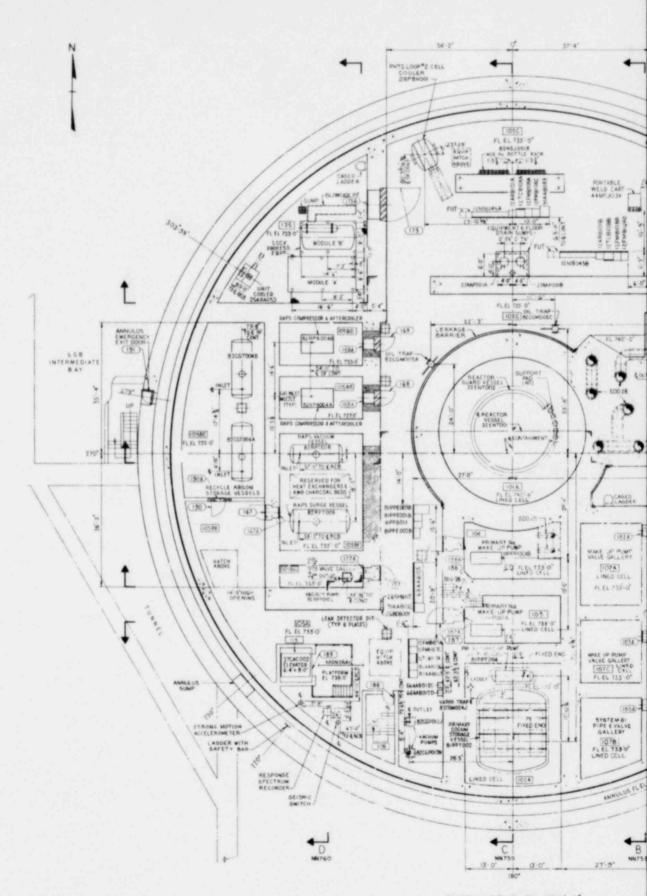
Figure 1.2-10

General Arrangement

Reactor Containment Building

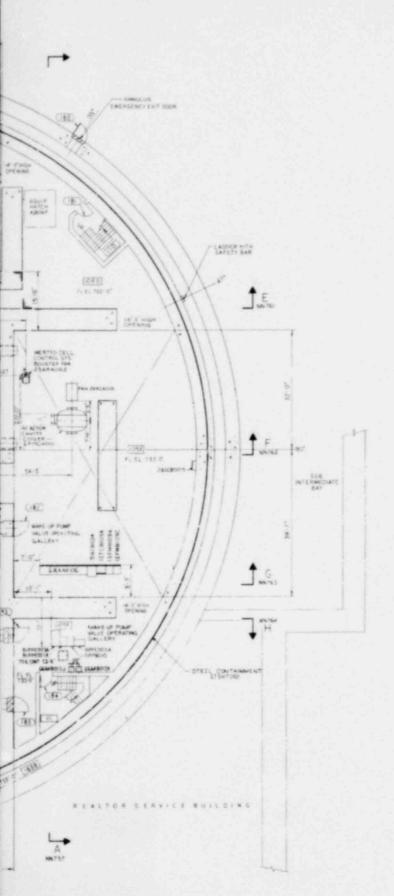
Plan El. 752'-8"

1.2-21



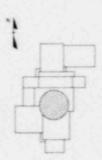
PLAN ABOVE EL. 733'-0"

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KEY PLAN

Figure 1.2-11
General Arrangement
Reactor Containment Building
Plan El. 733'-0"

1.2-22

SECTION A-A

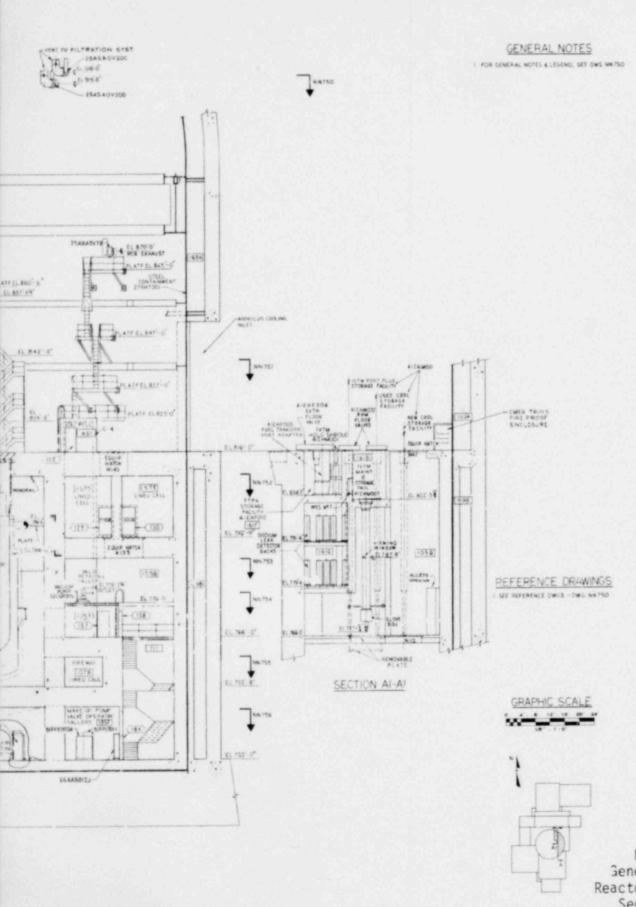


Figure 1.2-12
General Arrangement
Reactor Containment Building
Section A-A and A1-A1

1.2-23

KEY PLAN

SECTION B-B

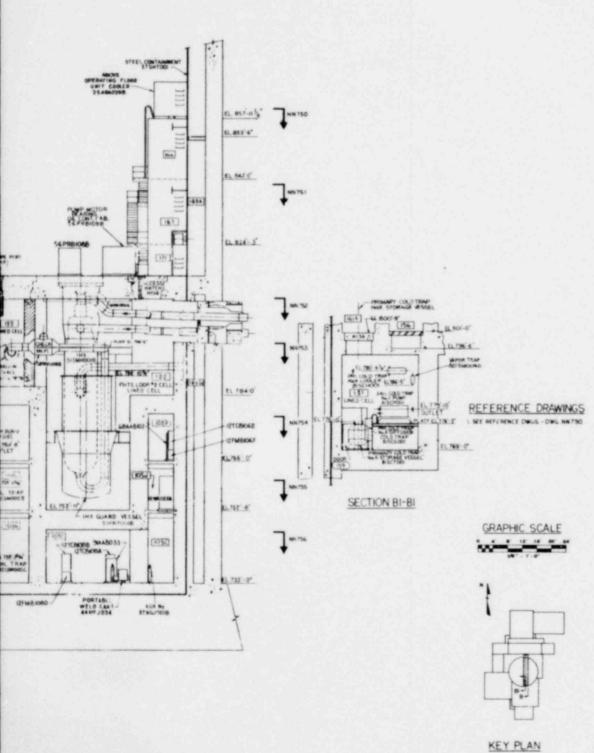
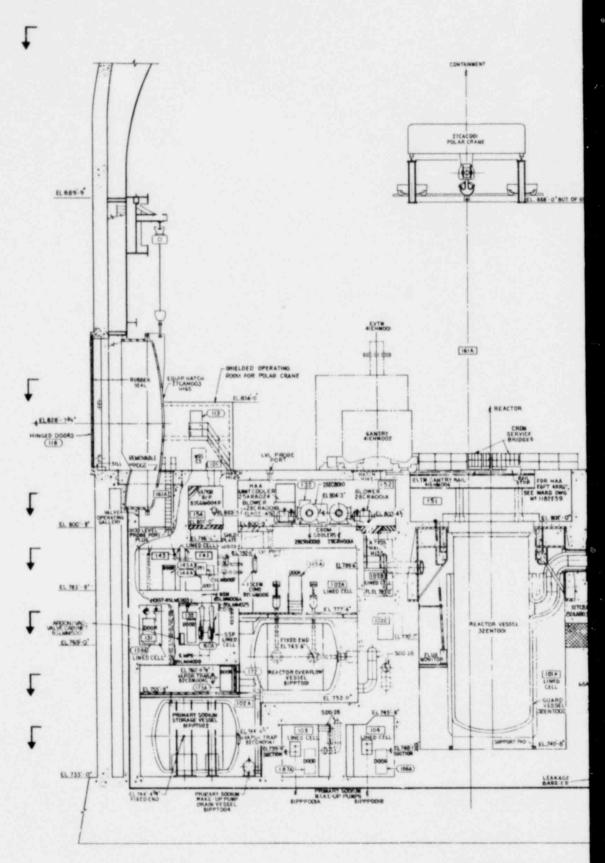


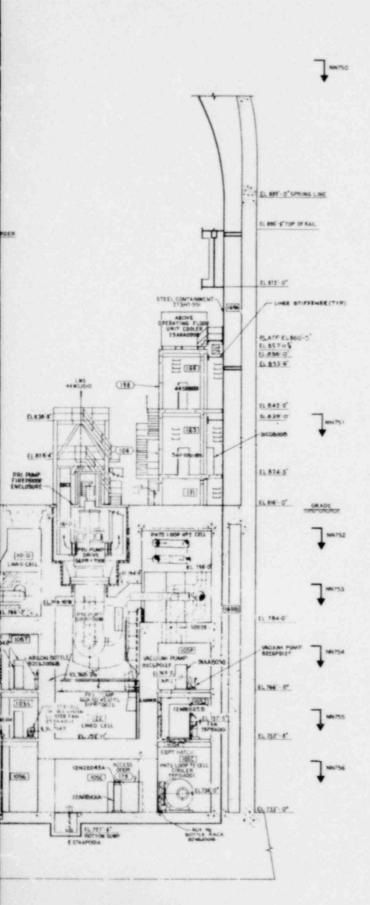
Figure 1.2-13
General Arrangement
Reactor Containment Building
Section B-B and B1-B1

1.2-24

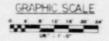


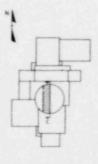
SECTION C-C

I FOR GENERAL NOTES & LEGEND, SEE DWG NN 750



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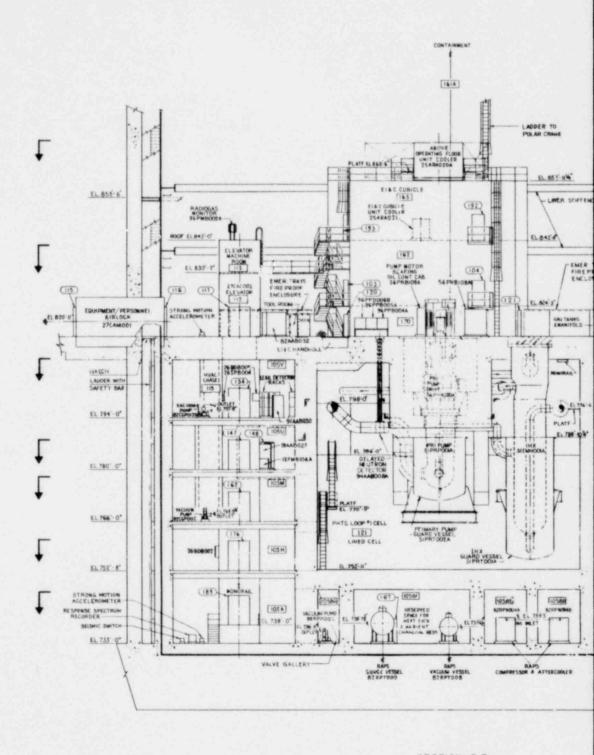




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Figure 1.2-14
General Arrangement
Reactor Containment Building
Section C-C

1.2-25



SECTION D-D

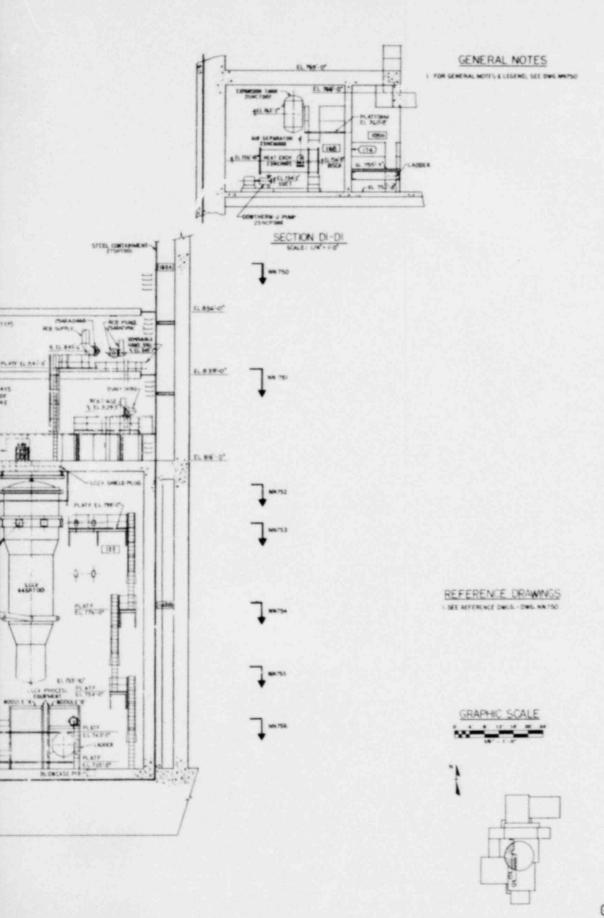
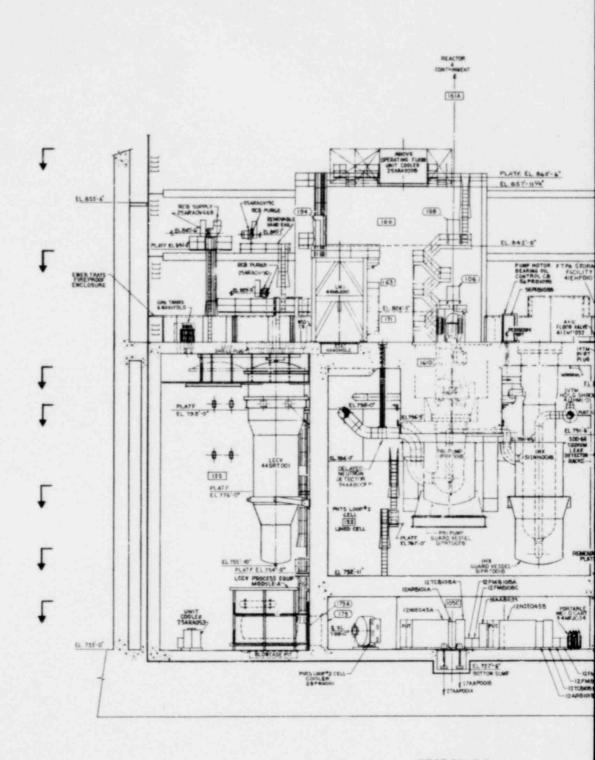


Figure 1.2-15 General Arrangement Reactor Containment Building Section D-D and D1-D1

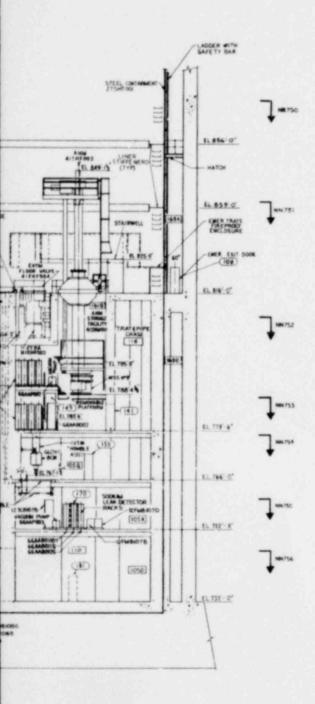
1.2-26

KEY PLAN



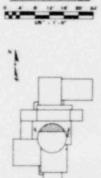
SECTION E-E

L FOR GENERAL MOTES & LEGENG, SEE DWG MN750



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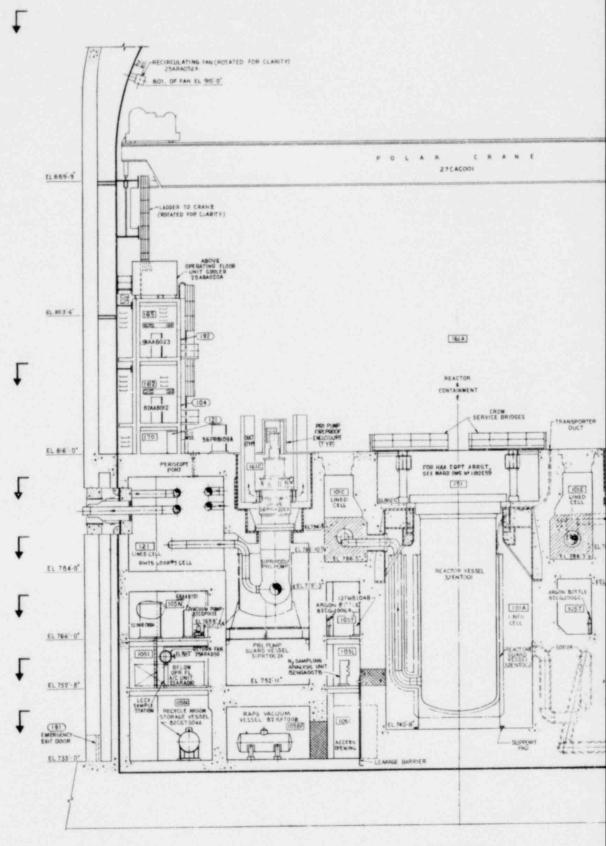
L SEE REFERENCE DWGS - DWG NN 750



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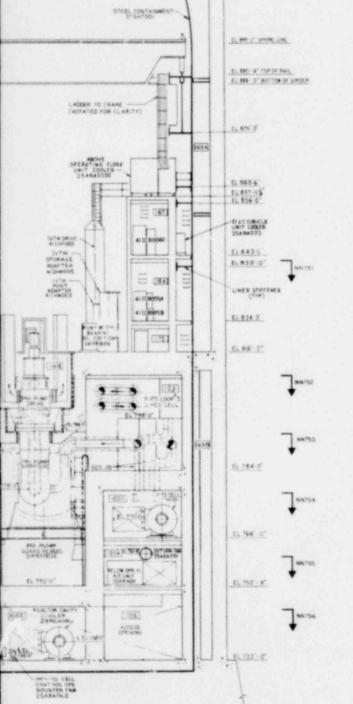
Figure 1.2-16
General Arrangement
Reactor Containment Building
Section E-E

1.2-27



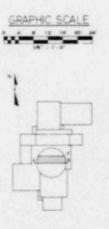
SECTION F-F

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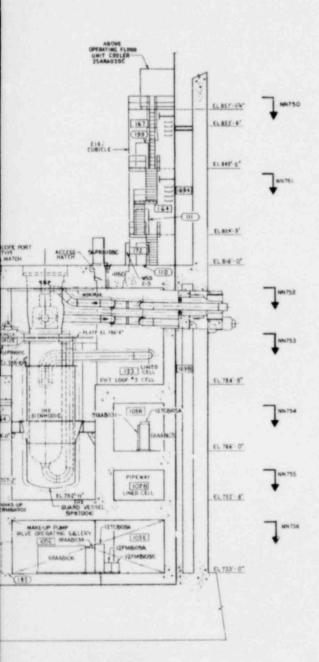


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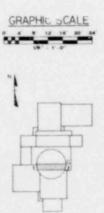
Figure 1.2-17
General Arrangement
Reactor Containment Building
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1.2-28

SECTION G-G



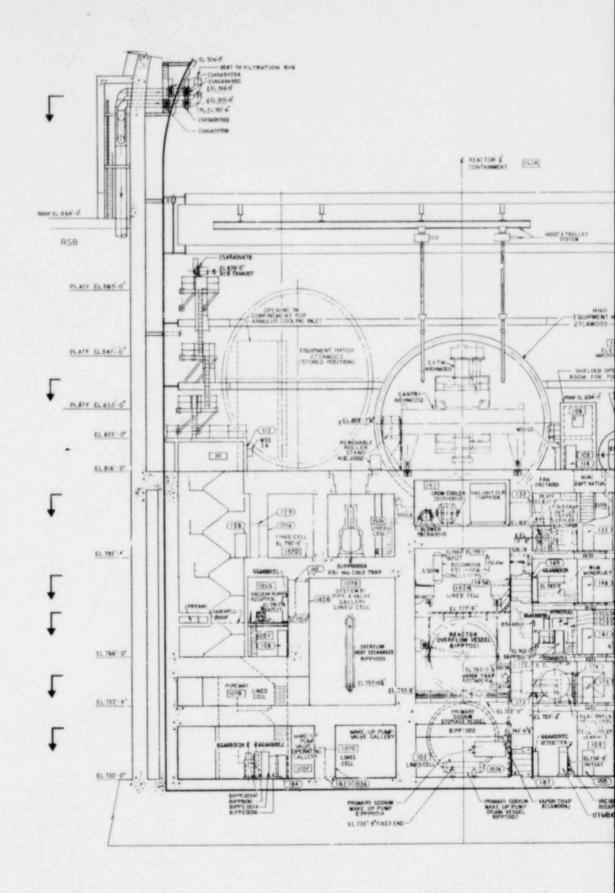
SEE REFERENCE DWGS. - DWG. NN 750



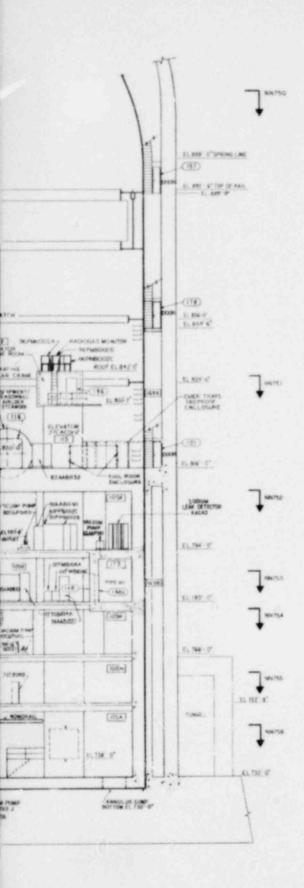
KEY PLAN

Figure 1.2-18
General Arrangement
Reactor Containment Building
Section G-G

1.2-29



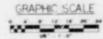
SECTION H-H

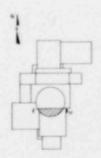


GENERAL NOTES

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REFERENCE URAWINGS

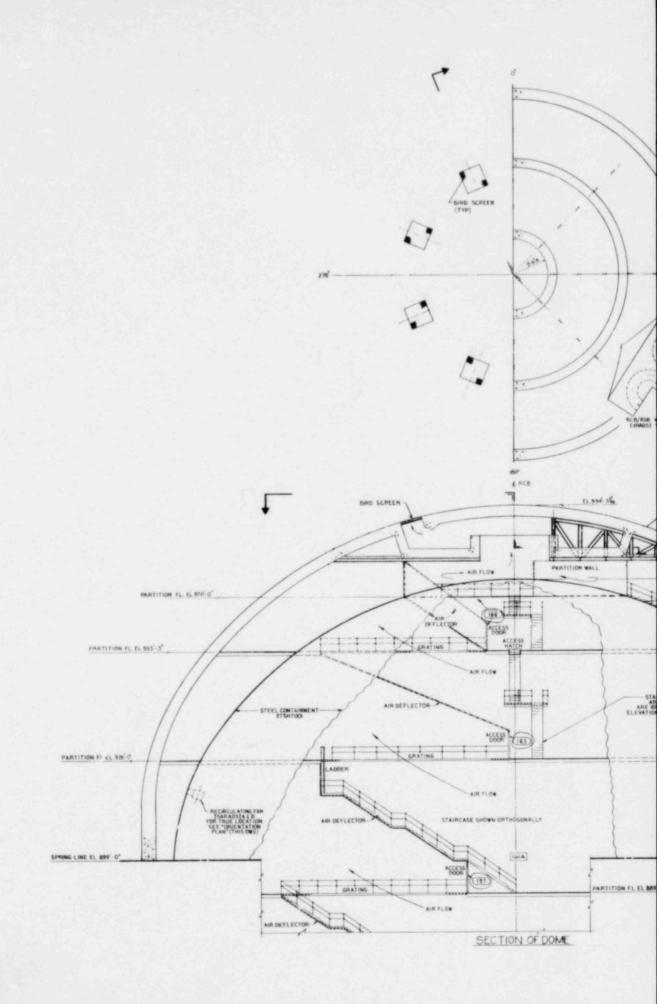


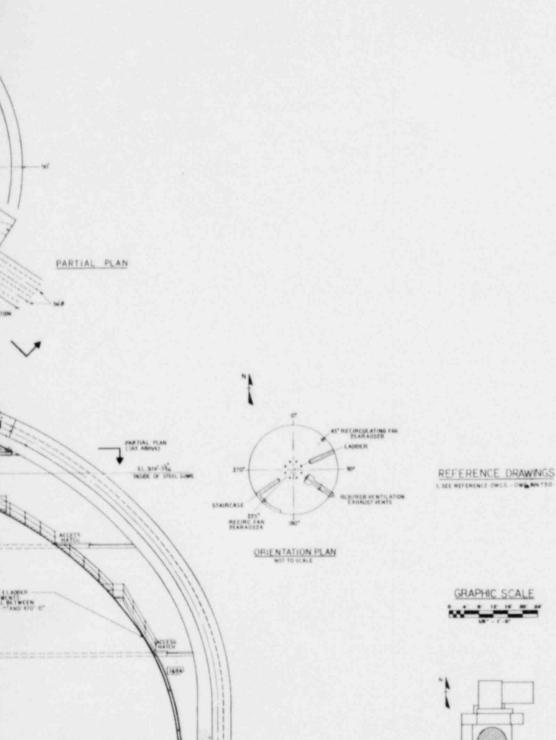


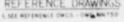
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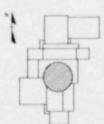
Figure 1.2-19
General Arrangement
Reactor Containment Building
Section H-H

1.2-30







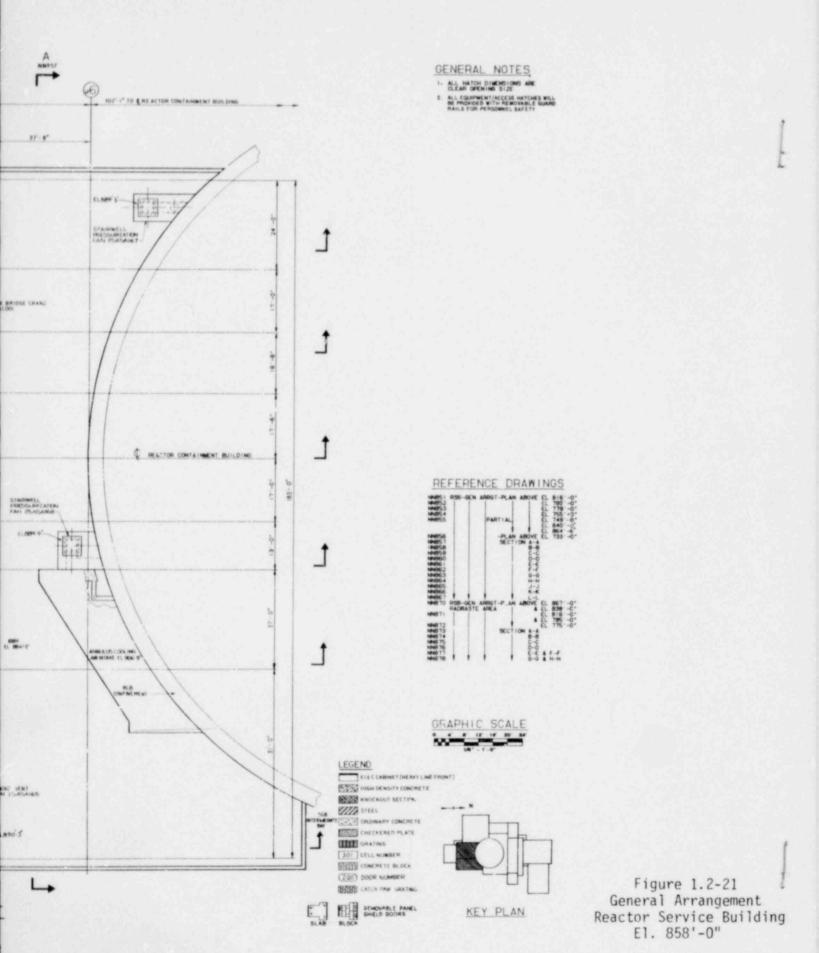


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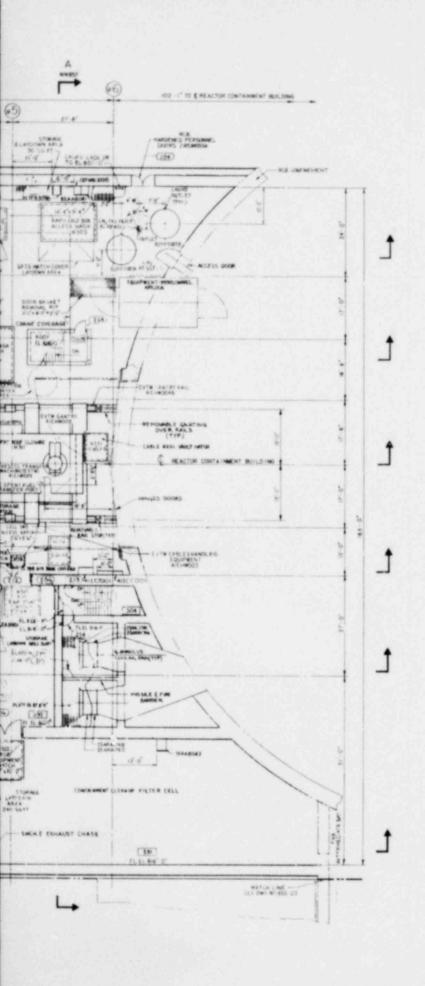
Figure 1.2-20 General Arrangement Reactor Containment Building Section C-C above plan, El. 899-0"

1.2-31

PLAN ABOVE EL. 858-0



1.2-32





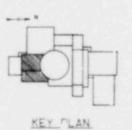
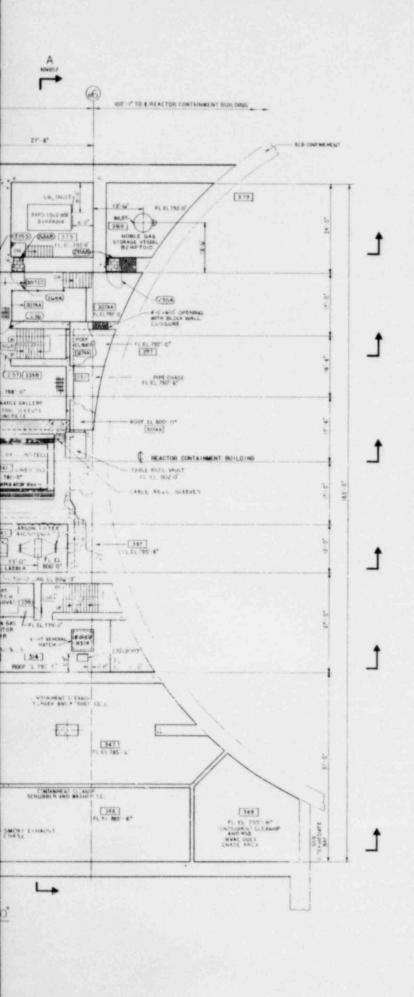
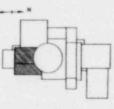


Figure 1.2-22 General Arrangement Peactor Service Building El. 816'-0"

1.2-33



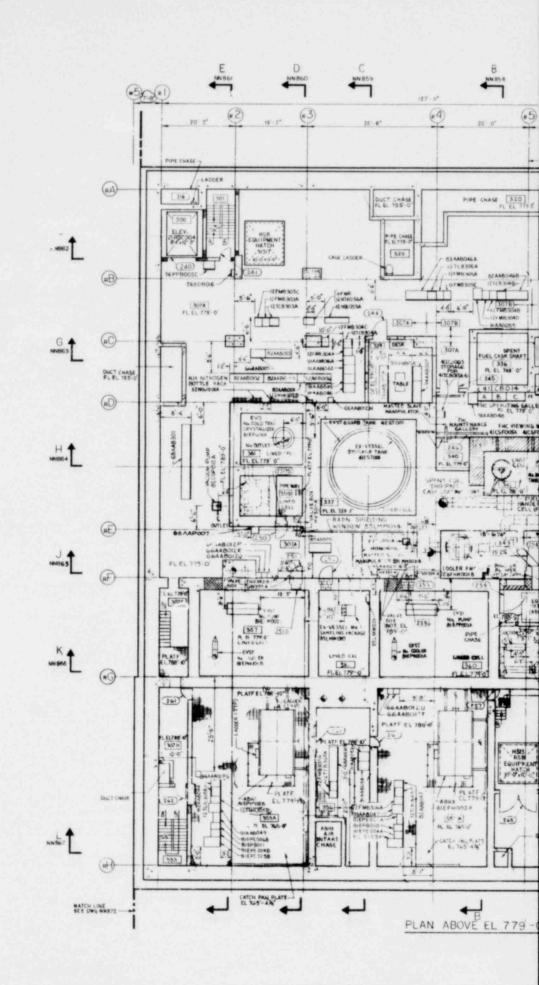


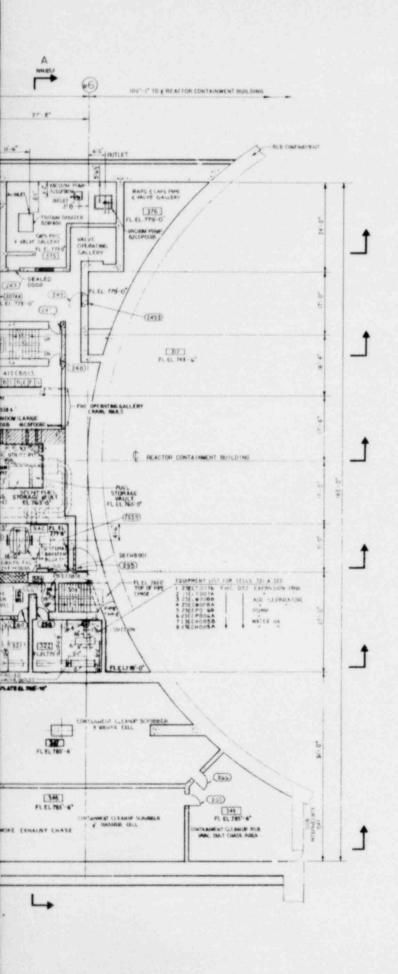


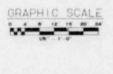
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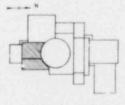
Figure 1.2-23
General Arrangement
Reactor Service Building
El. 792'-0"

1.2-34









KEY PLAN

Figure 1.2-24
General Arrangement
Reactor Service Building
El. 779'-0"

1.2-35

PLAN APOVE EL.

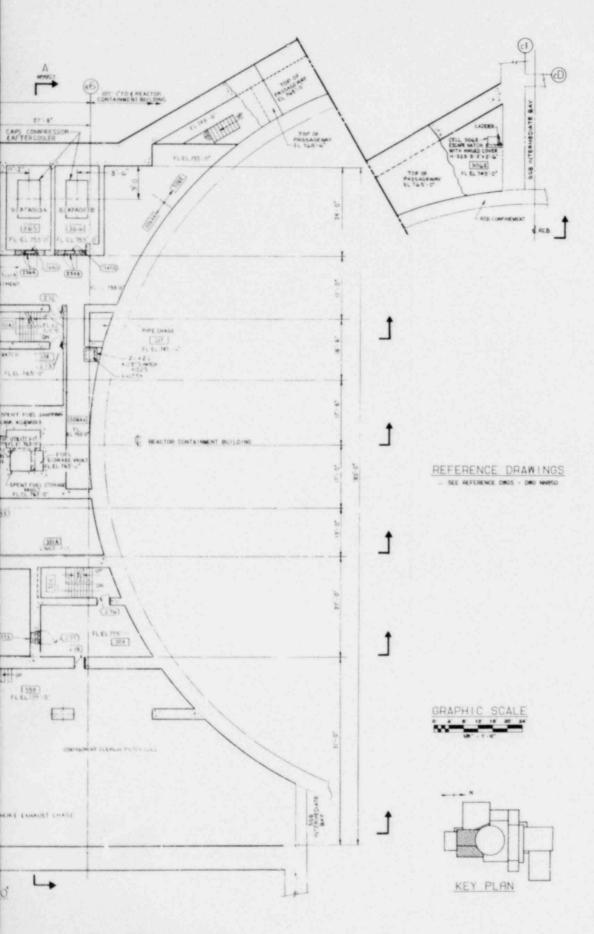
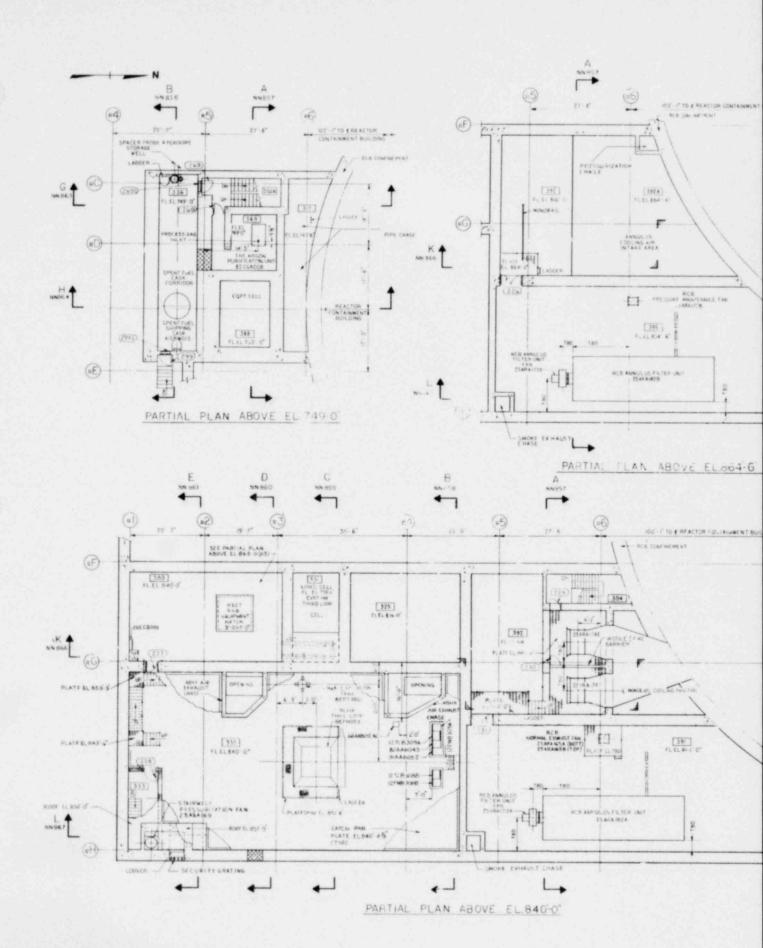
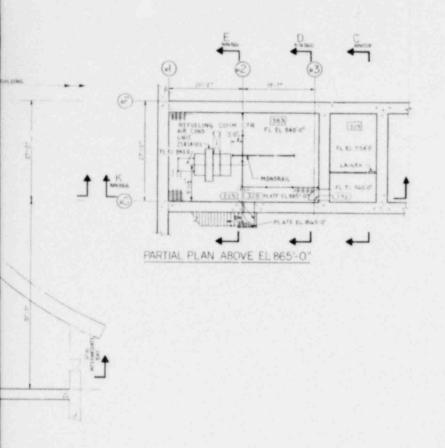


Figure 1.2-25
General Arrangement
Reactor Service Building
El. 755'-0"

1.2-36





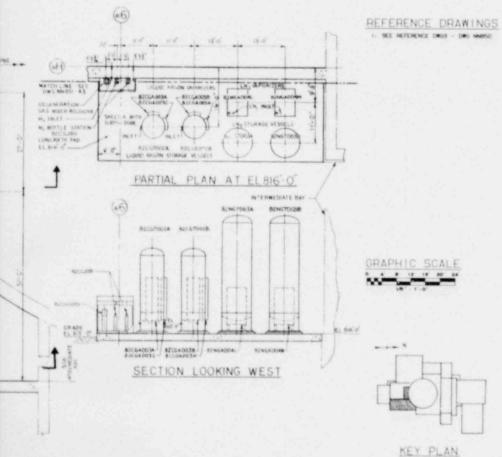
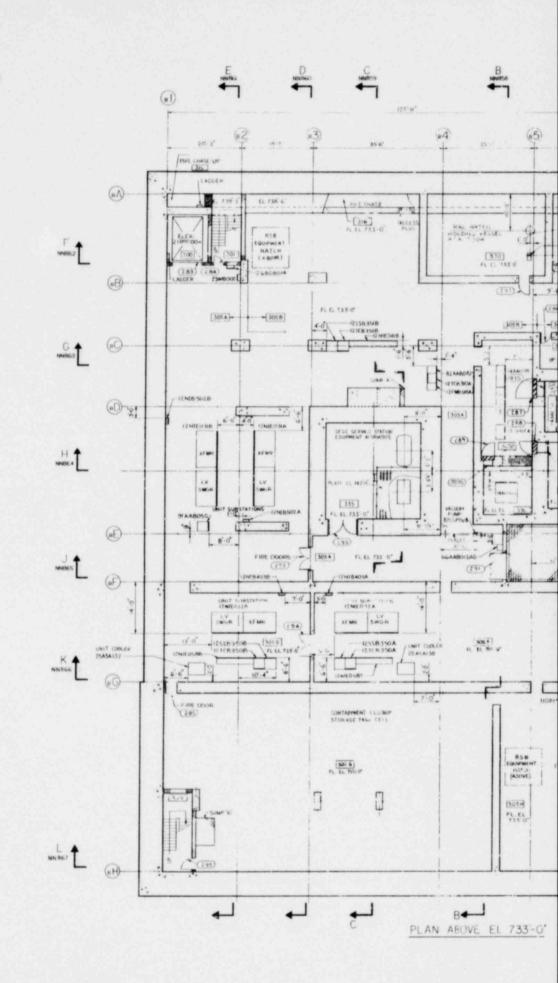


Figure 1.2-26
General Arrangement
Reactor Service Building
Above El. 749'-0", El. 840'-0"
and 864'-6"

1.2-37



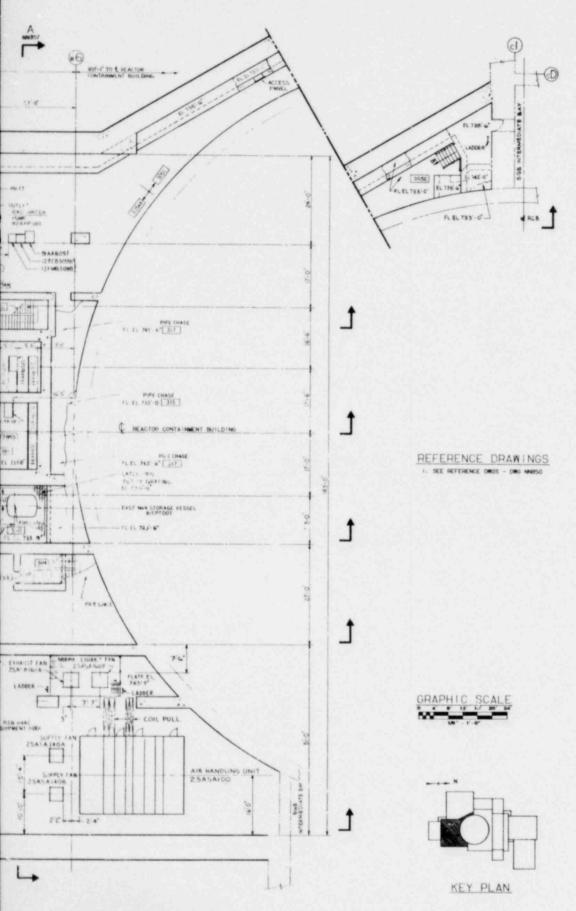
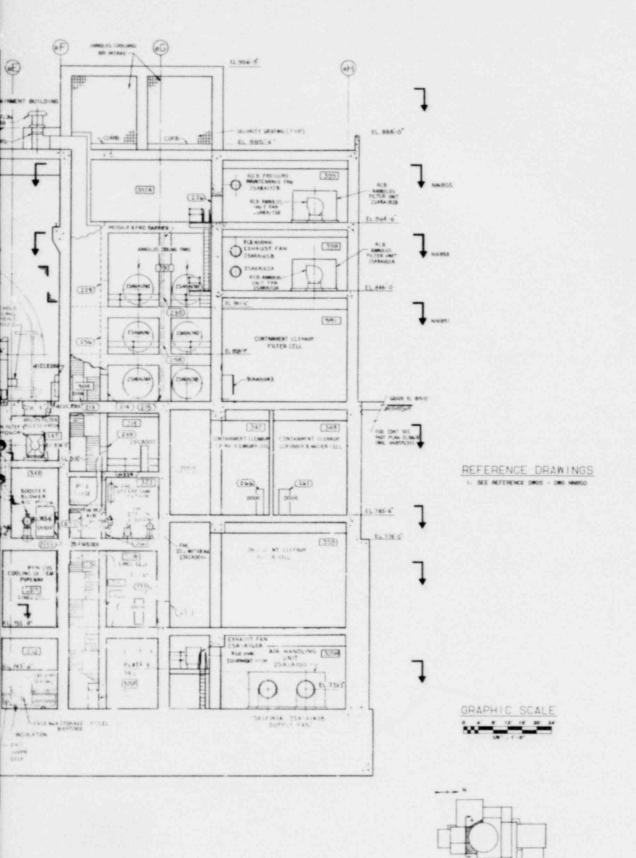
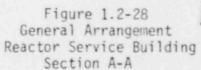


Figure 1.2-27 General Arrangement Reactor Service Building El. 733'-0"

1.2-38

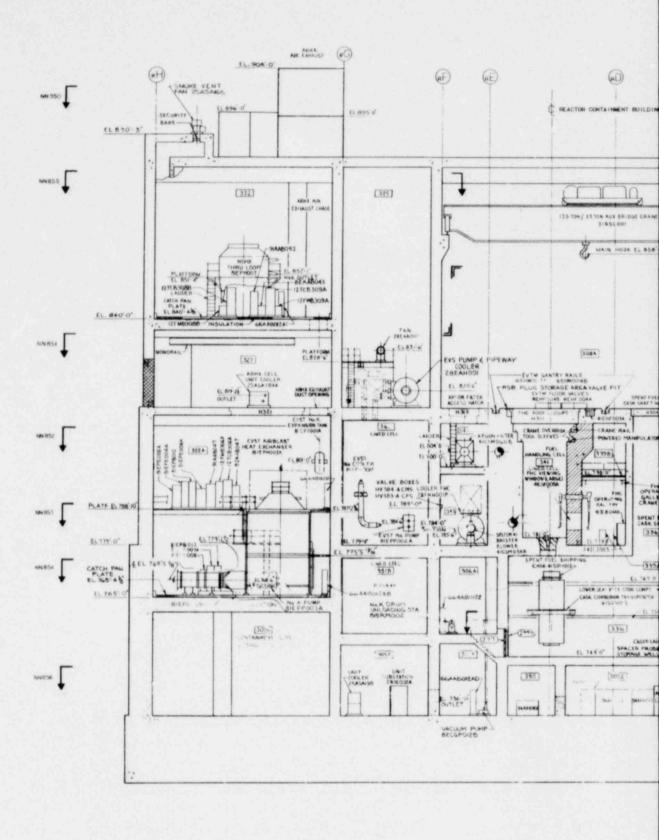
SECTION A-A



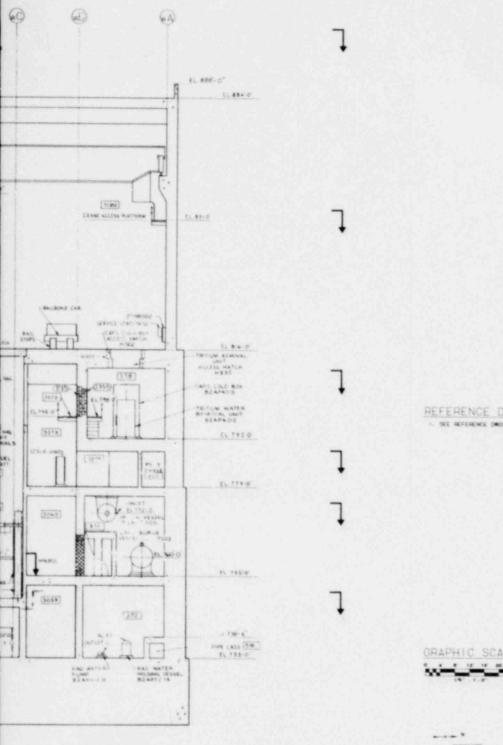


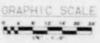
KEY PLAN

1.2-39



SECTION B-B





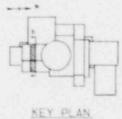
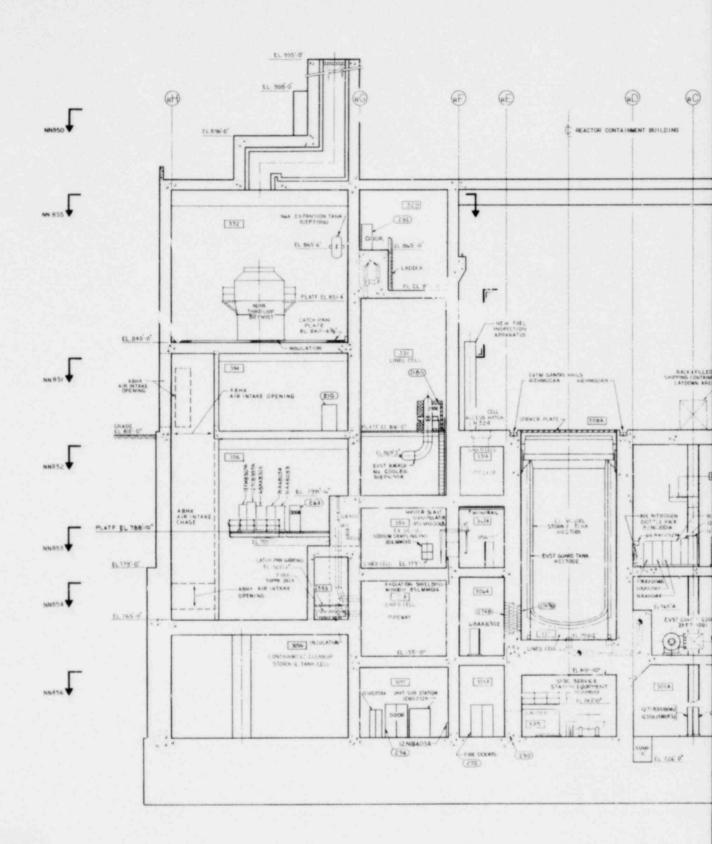


Figure 1.2-29 General Arrangement Reactor Service Building Section B-B

1.2-40



SECTION C-C

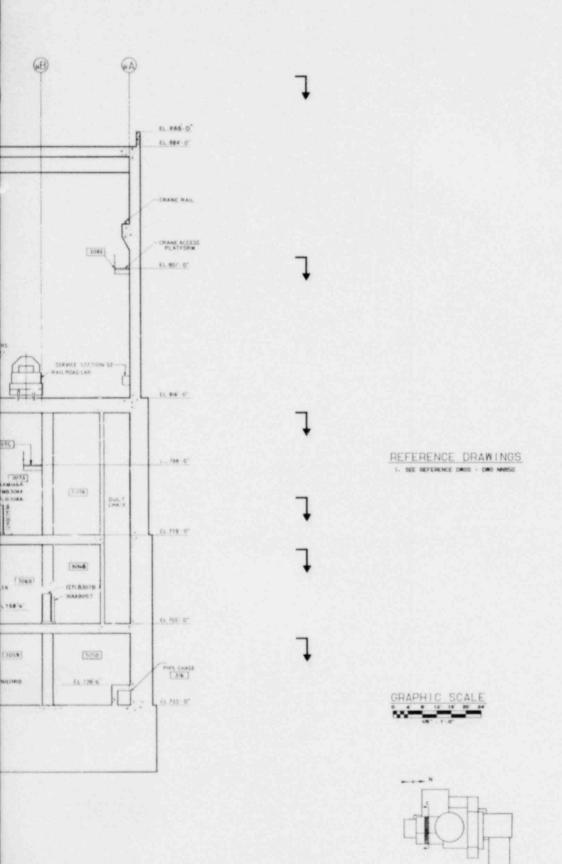
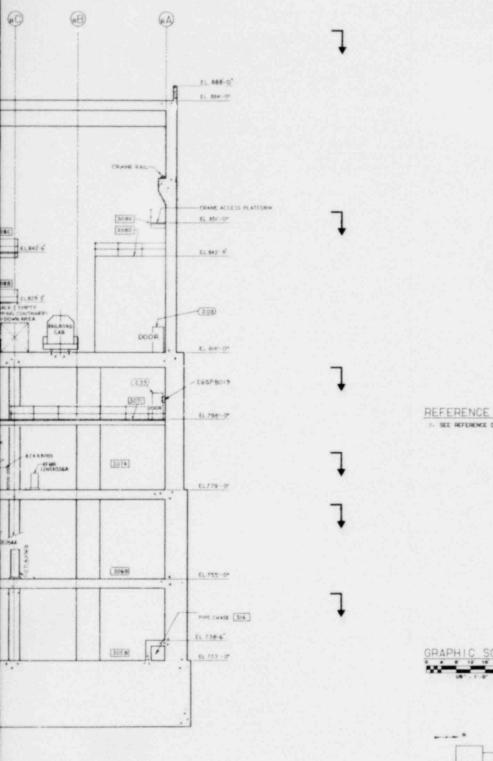


Figure 1.2-30
General Arrangement
Reactor Service Building
Section C-C

1.2-41

KEY PLAN

SECTION D-D





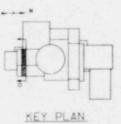
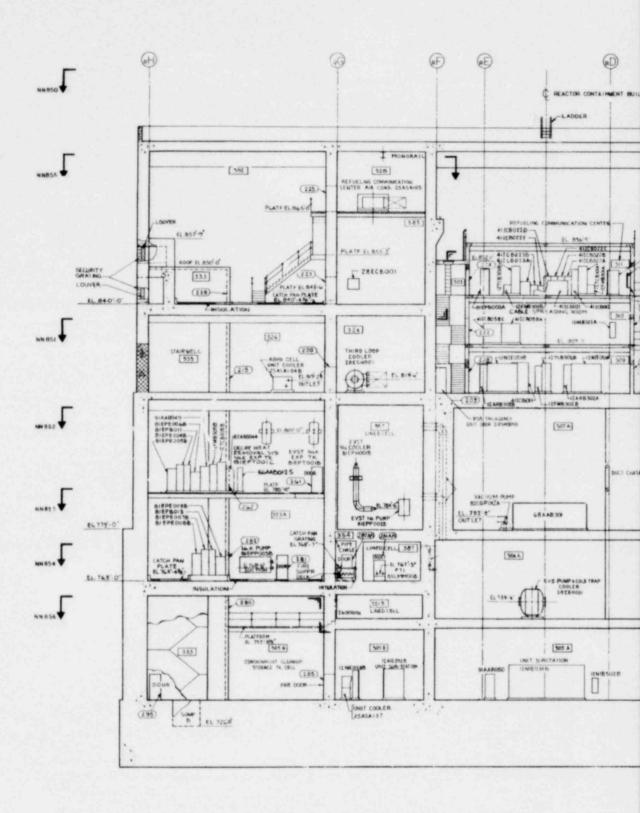


Figure 1.2-31
General Arrangement
Reactor Service Building
Section D-D

1.2-42



SECTION E-E

316

REFERENCE DRAWINGS
1. SEE REFERENCE DROS - DRG NAMESO



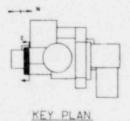


Figure 1.2-32 General Arrangement Reactor Service Building Section E-E

1.2-43

SECTION F-F

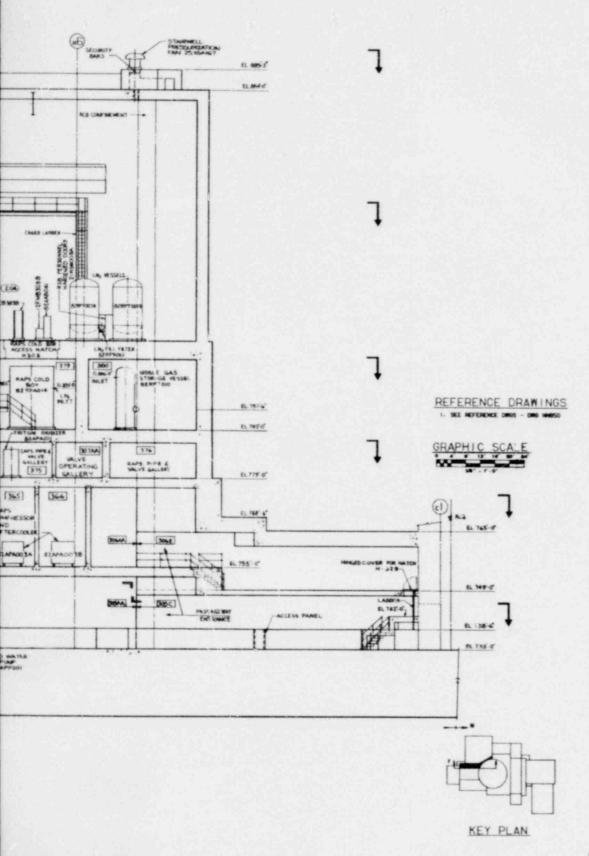
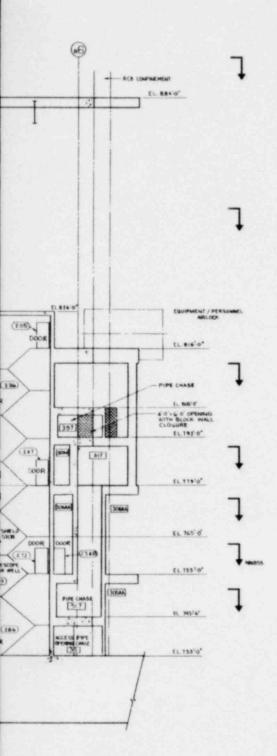
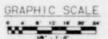


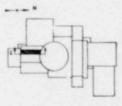
Figure 1.2-33
General Arrangement
Reactor Service Building
Section F-F

1.2-44

SECTION G-G





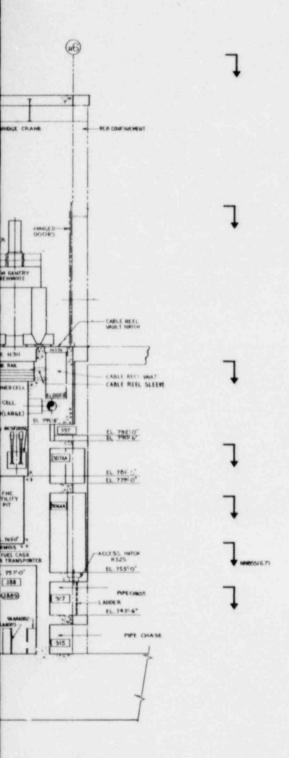


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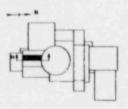
Figure 1.2-34
General Arrangement
Reactor Service Building
Section G-G

1.2-45

SECTION H-H



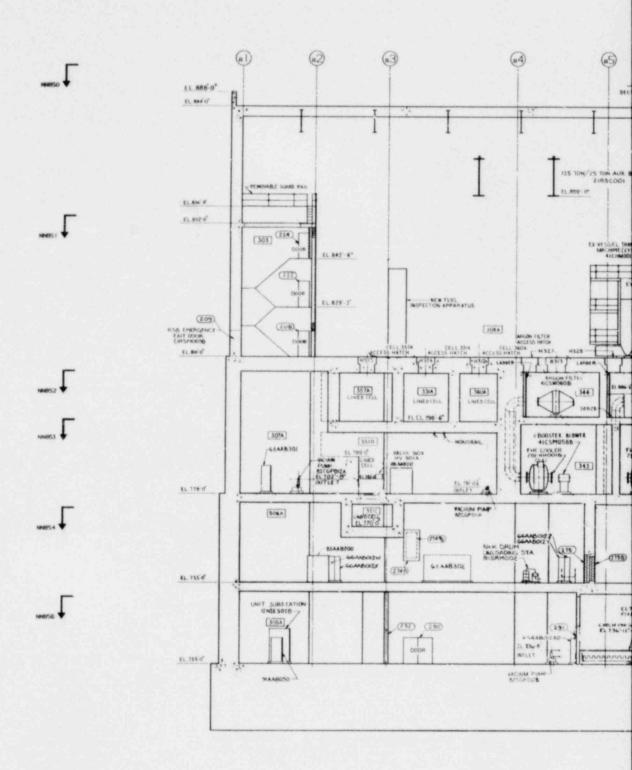




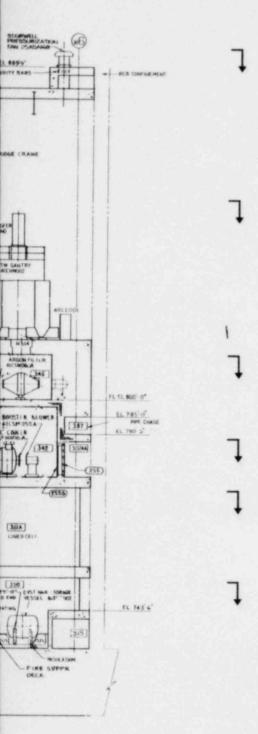
KEY PLAN

Figure 1.2-35 General Arrangement Reactor Service Building Section H-H

1.2-46

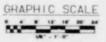


SECTION J-J



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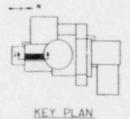
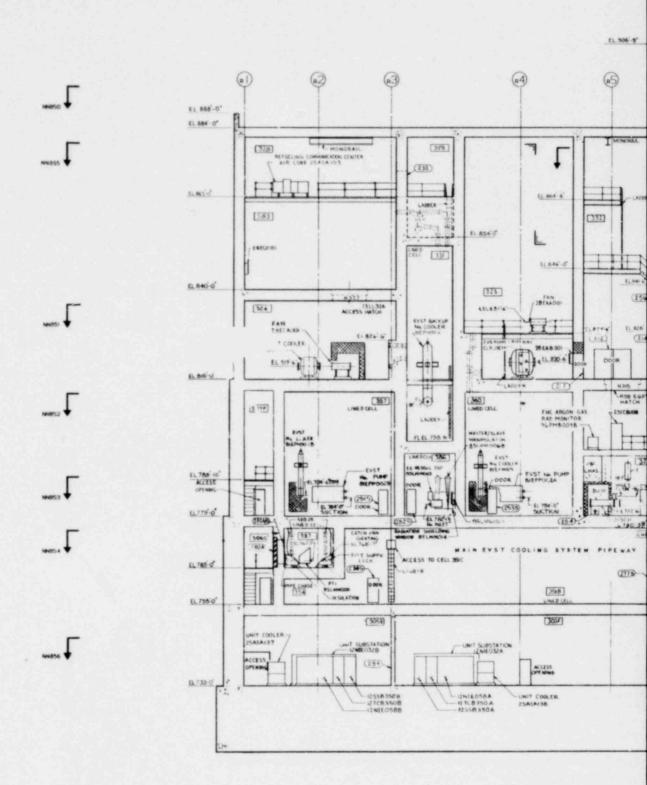
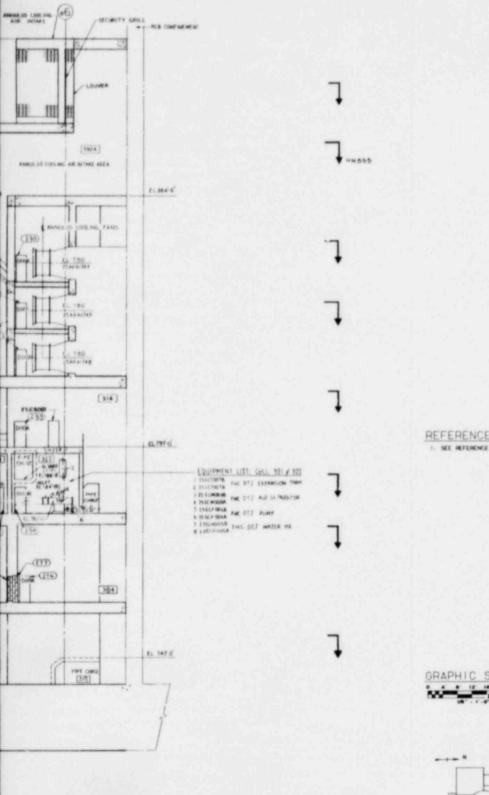


Figure 1.2-36 General Arrangement Reactor Service Building Section J-J

1.2-47



SECTION K-K



REFERENCE DRAWINGS 1. SEE REFERENCE DWGS - DWG NARSO



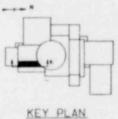
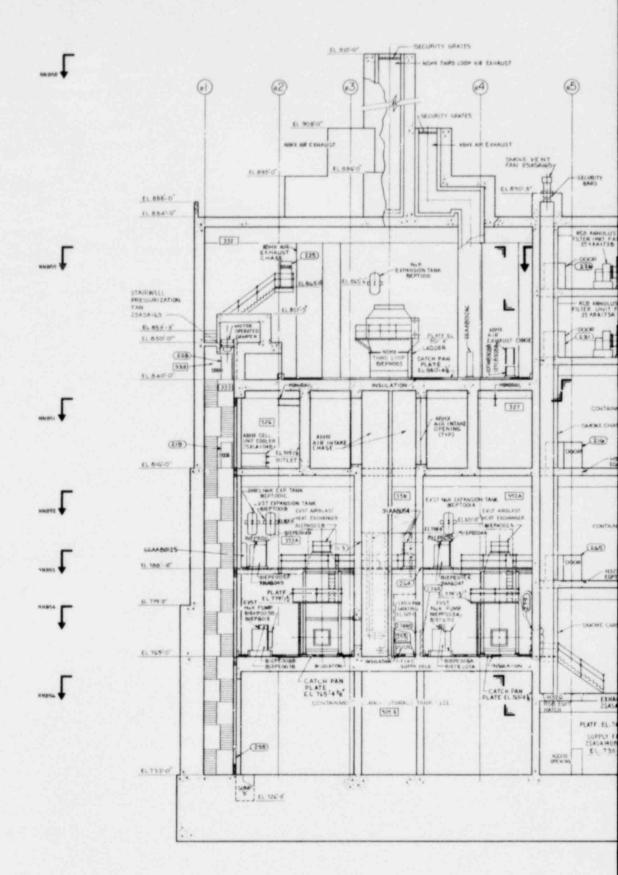


Figure 1.2-37 General Arrangement Reactor Service Building Section K-K

1.2-48



SECTION L-L

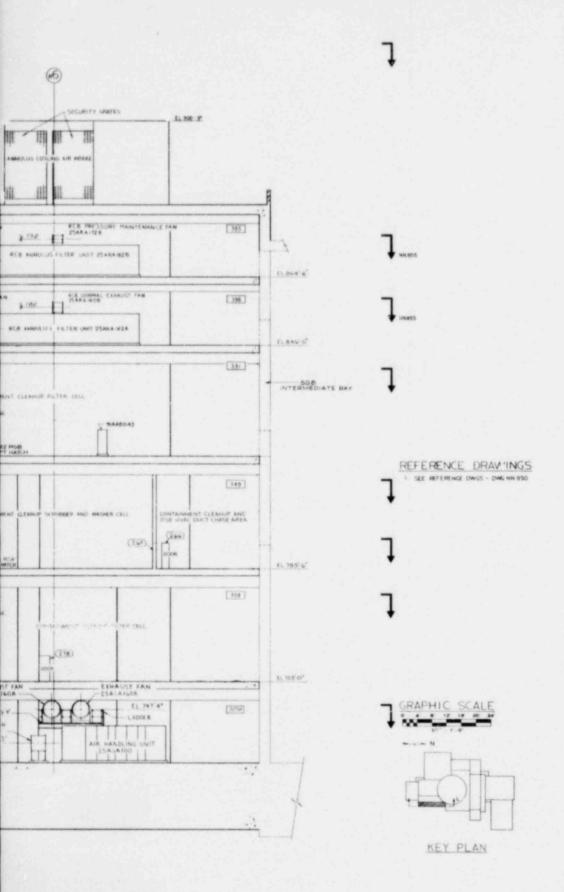
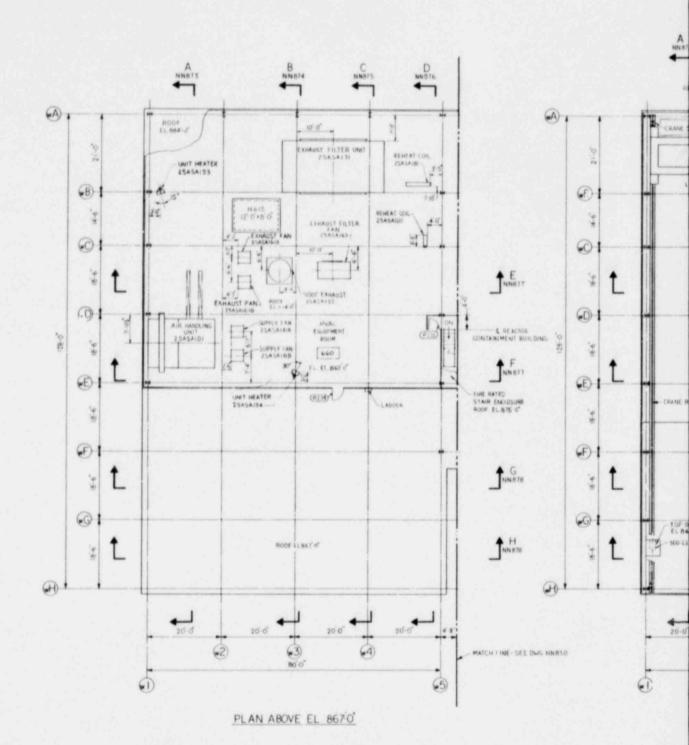


Figure 1.2-38
General Arrangement
Reactor Service Building
Section L-L



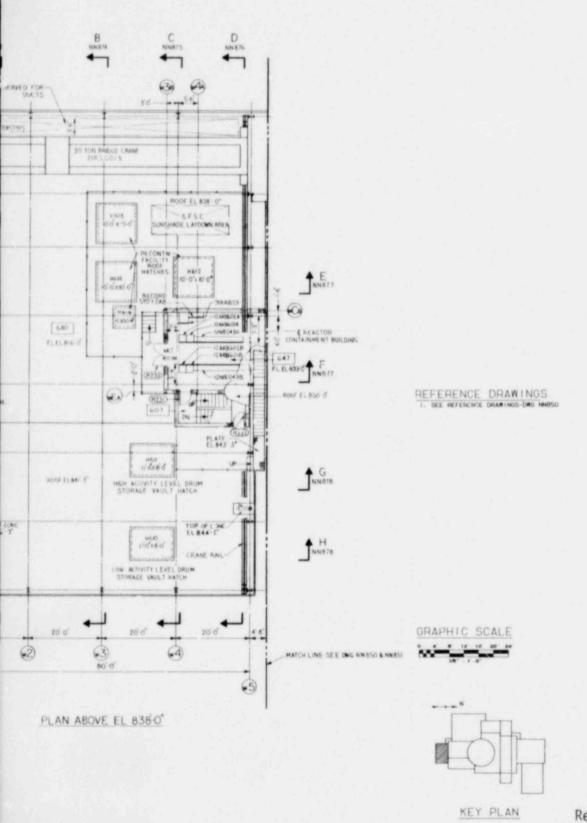
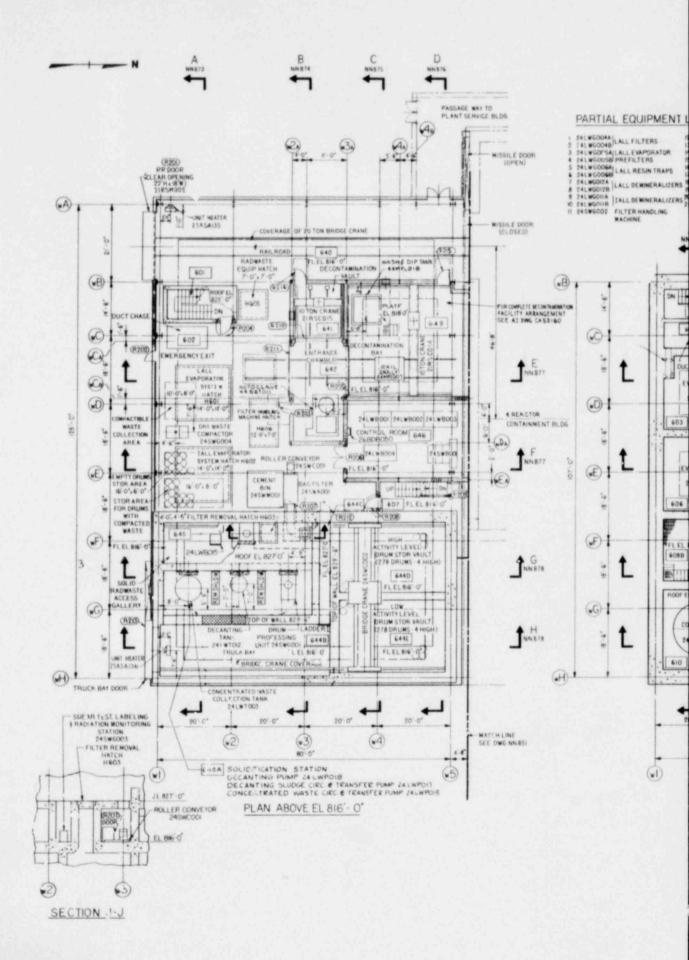
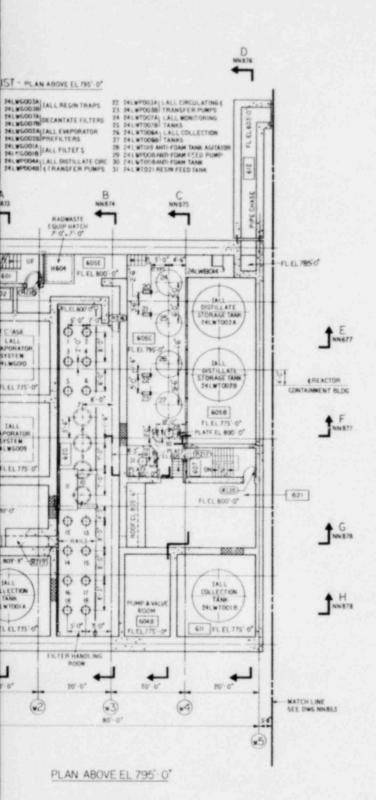


Figure 1.2-39
General Arrangement
Reactor Service Building
Radwaste Area
El. 867'-0" and 838'-0"







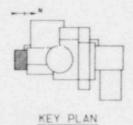
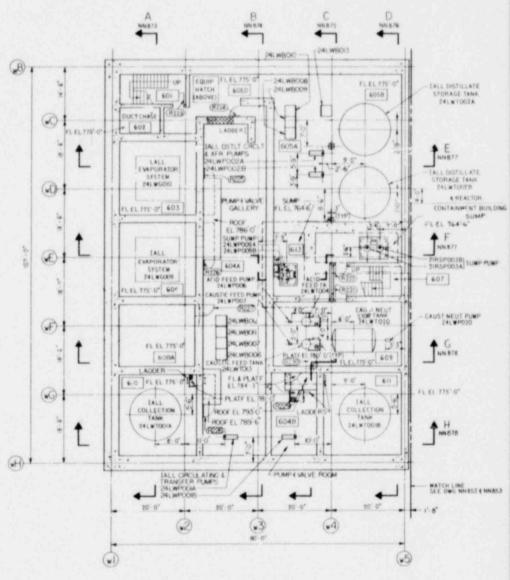
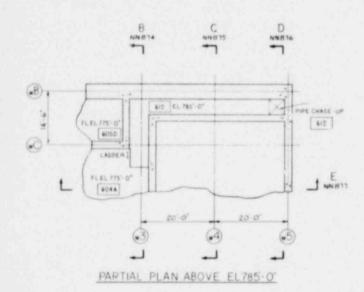


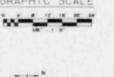
Figure 1.2-40 General Arrangement Reactor Service Building Radwaste Area

E1. 816'-0" and 795'-0"



PLAN ABOVE EL 775'-0"





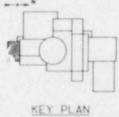
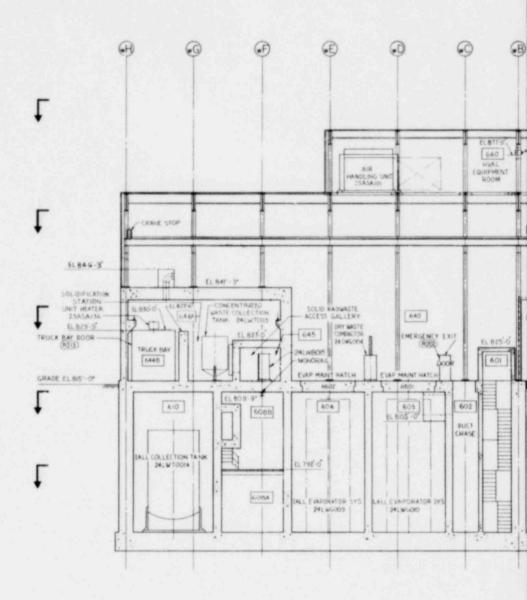
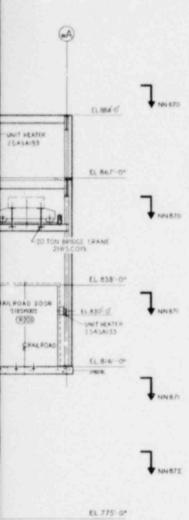


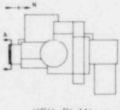
Figure 1.2-41
General Arrangement
Reactor Service Building
Radwaste Area
Plan El. 775'-0"



SECTION A-A



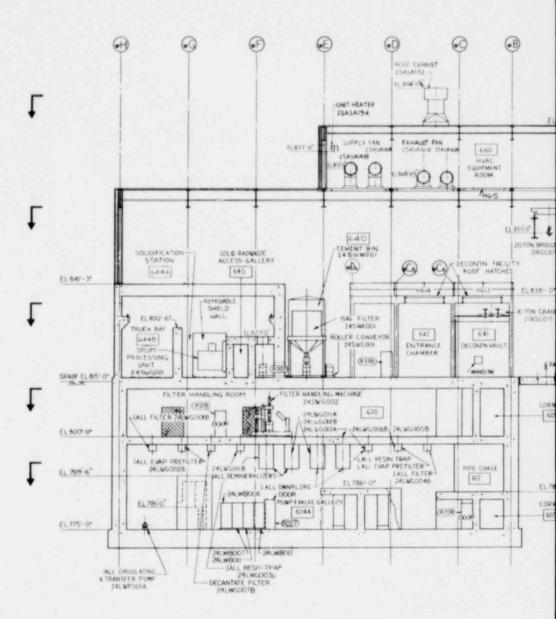




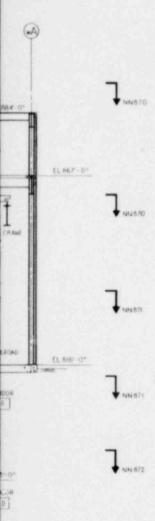
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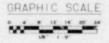
Figure 1.2-42
General Arrangement
Reactor Service Building
Radwaste Area
Section A-A

1.2-53



SECTION B-B





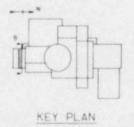
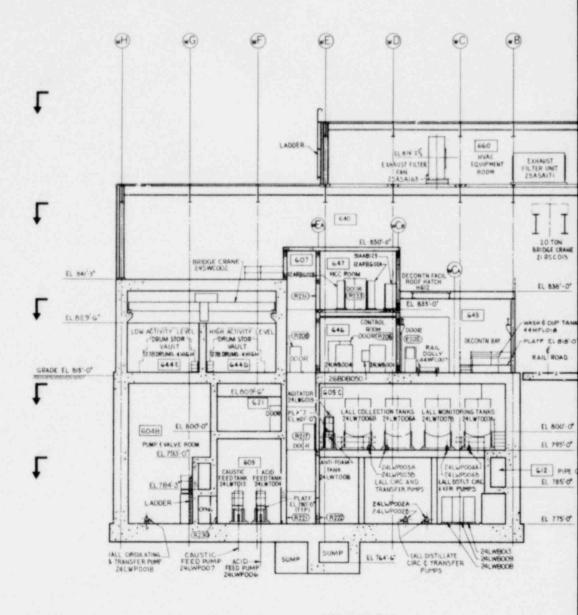
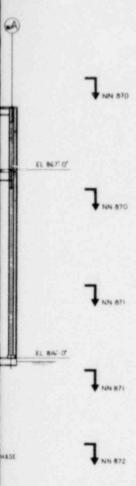


Figure 1.2-43
General Arrangement
Reactor Service Building
Radwaste Area
Section B-B



SECTION C-C



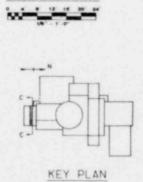
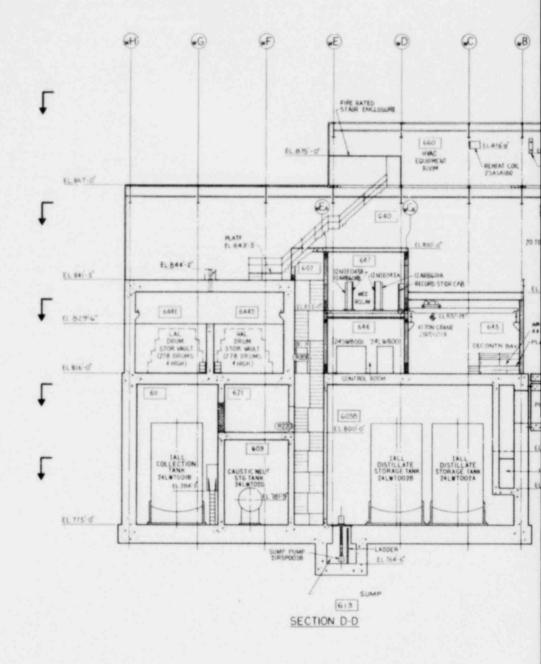
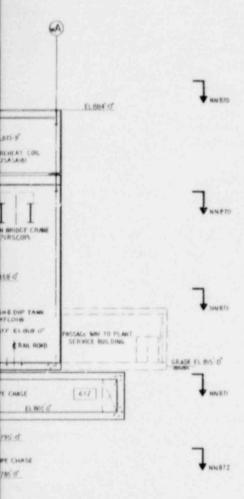


Figure 1.2-44
General Arrangement
Reactor Service Building
Radwaste Area
Section C-C

1.2-55







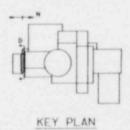
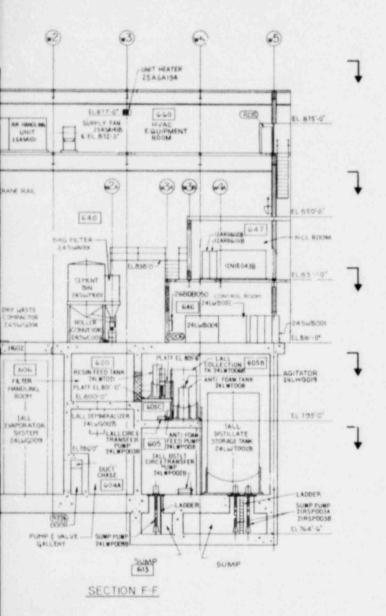
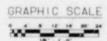


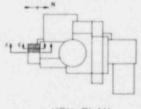
Figure 1.2-45
General Arrangement
Reactor Service Building
Radwaste Area
Section D-D

1.2-56

SECTION E-E

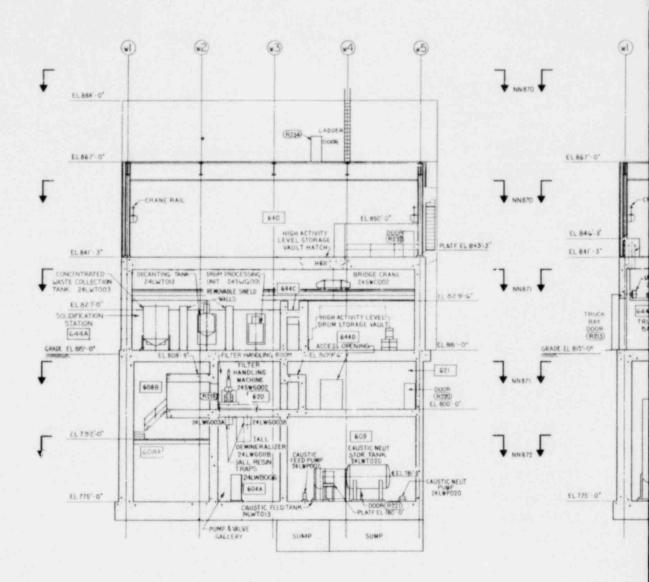




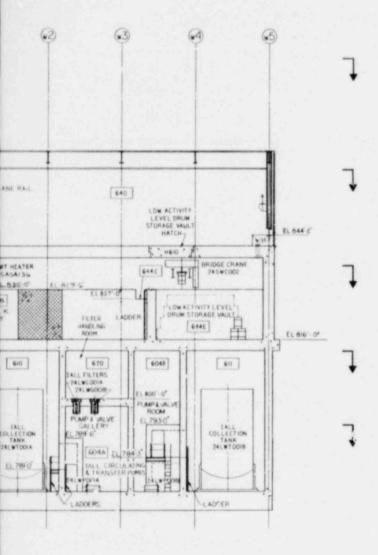


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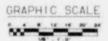
Figure 1.2-46
General Arrangement
Reactor Service Building
Radwaste Area
Section E-E and F-F

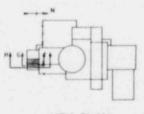


SECTION G-G



SECTION H-H





KEY PLAN

Figure 1.2-47
General Arrangement
Reactor Service Building
Radwaste Area
Section G-G and H-H

1.2.58

PLAN ABOVE EL 857-6"

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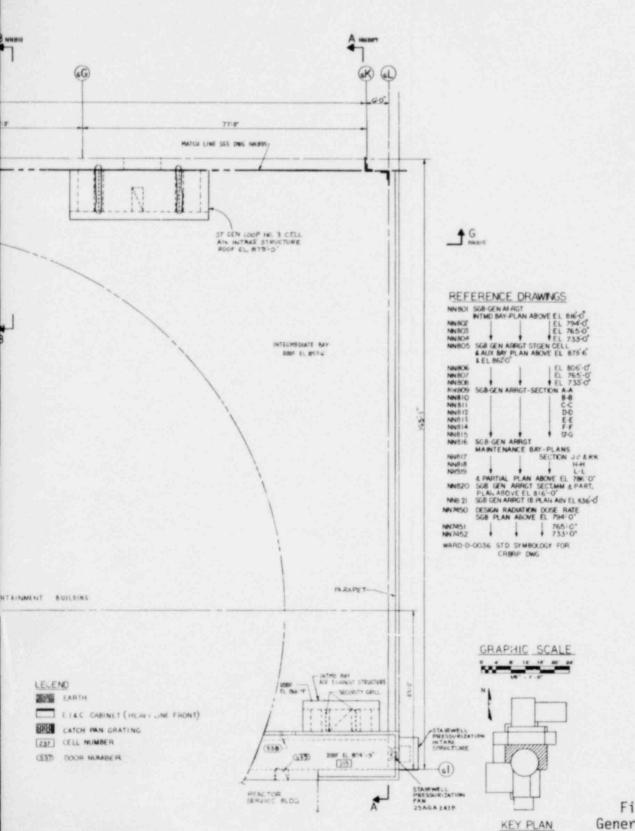
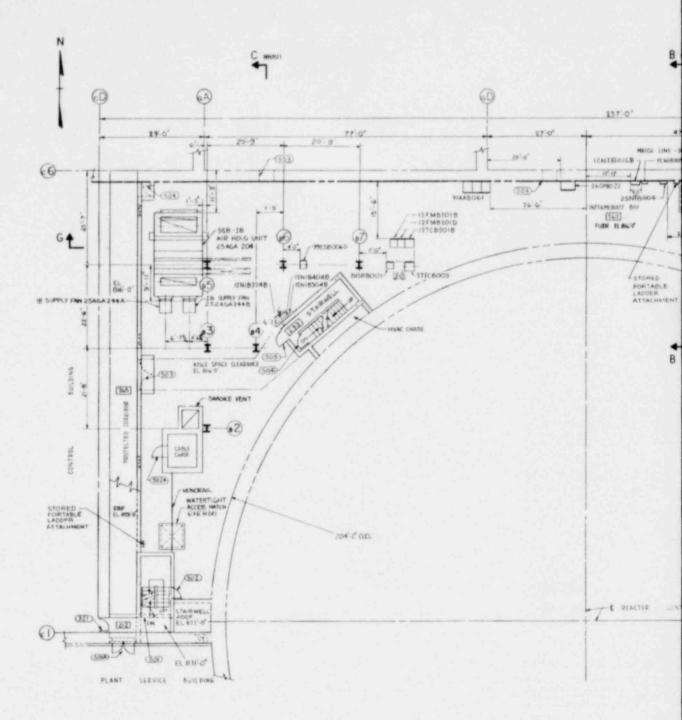


Figure 1.2-48
General Arrangement
Steam Generator Building
Plan El. 857'-6"



PLAN ABOVE EL 816'-0"

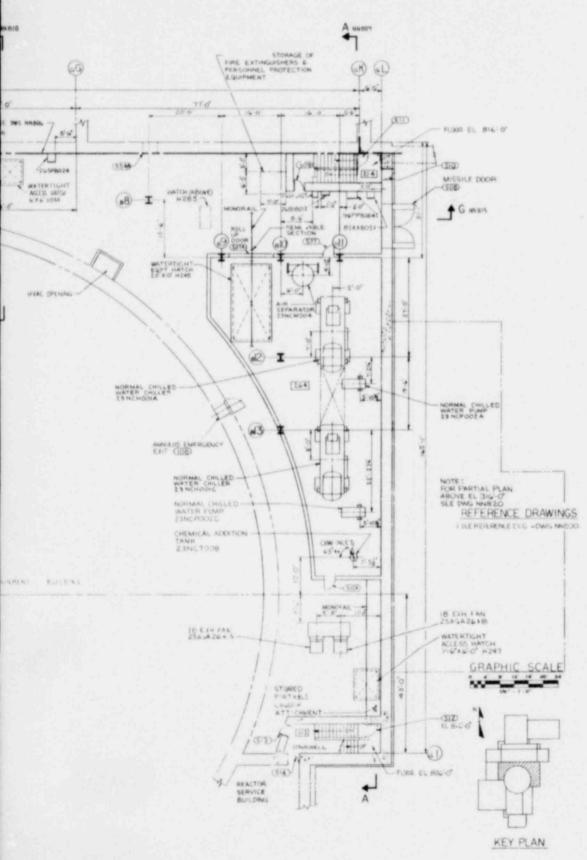
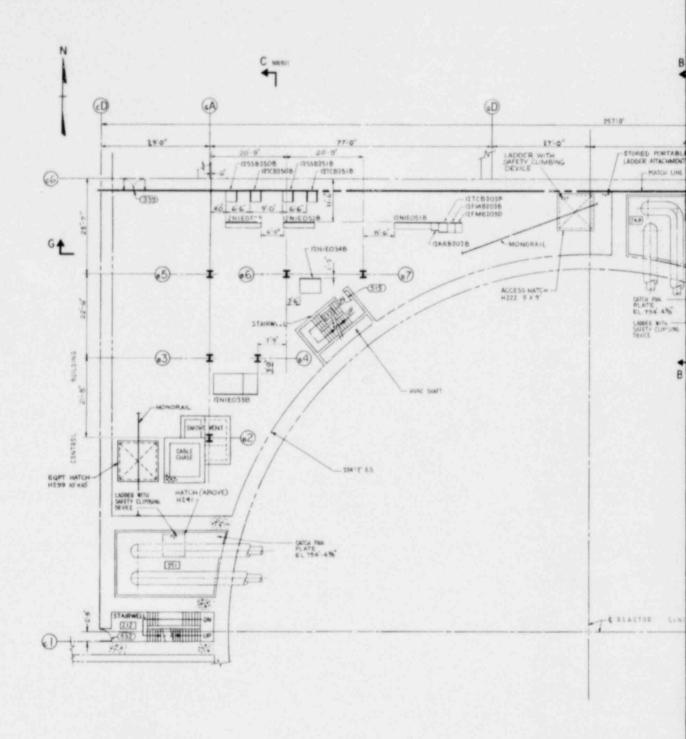


Figure 1.2-49
General Arrangement
Steam Generator Building
Plan El. 816'-0"



PLAN ABOVE EL 794-0"

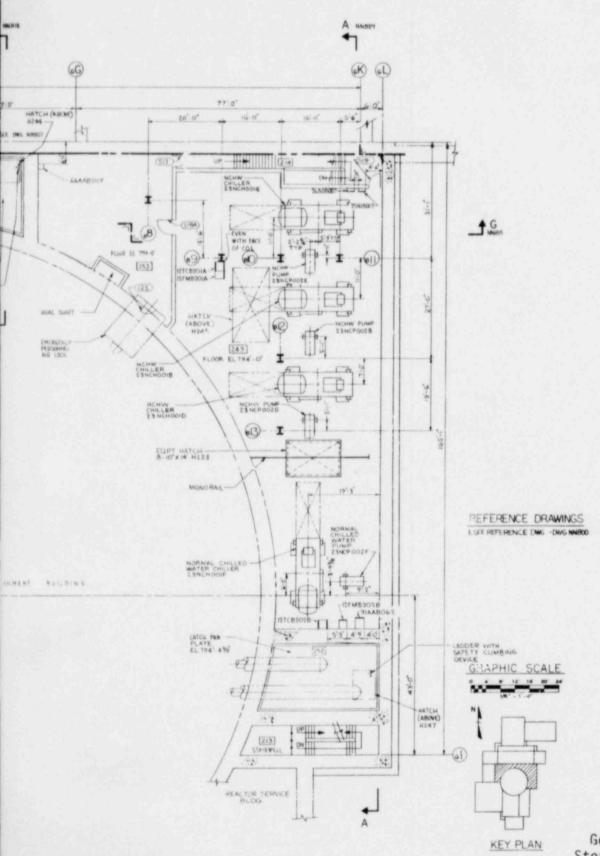


Figure 1.2-50 General Arrangement Steam Generator Building Plan El. 794'-0"

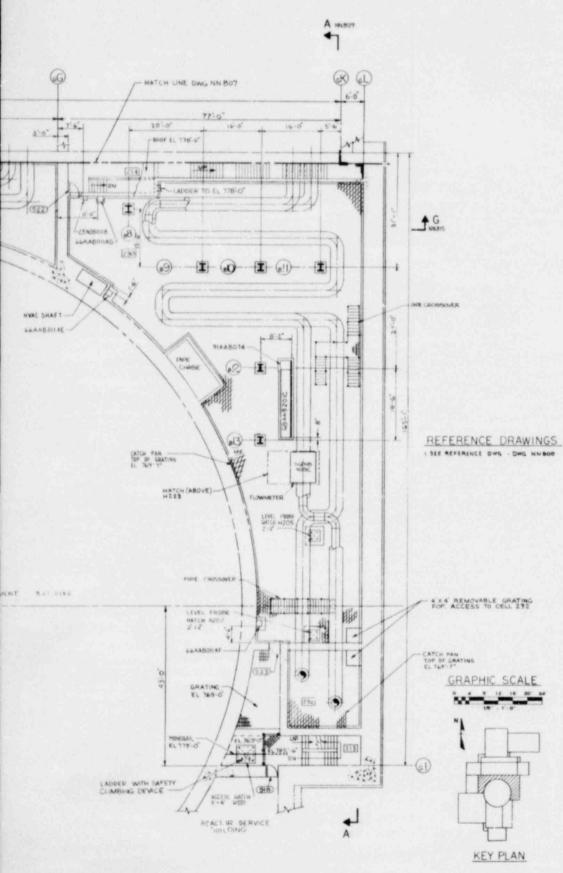


Figure 1.2-51 General Arrangement Steam Generator Building Plan El. 765'-0"

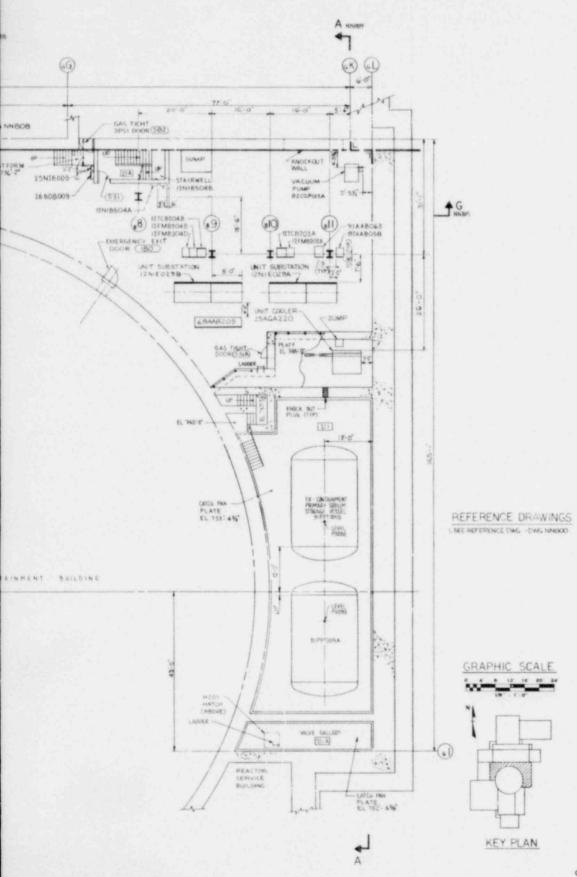
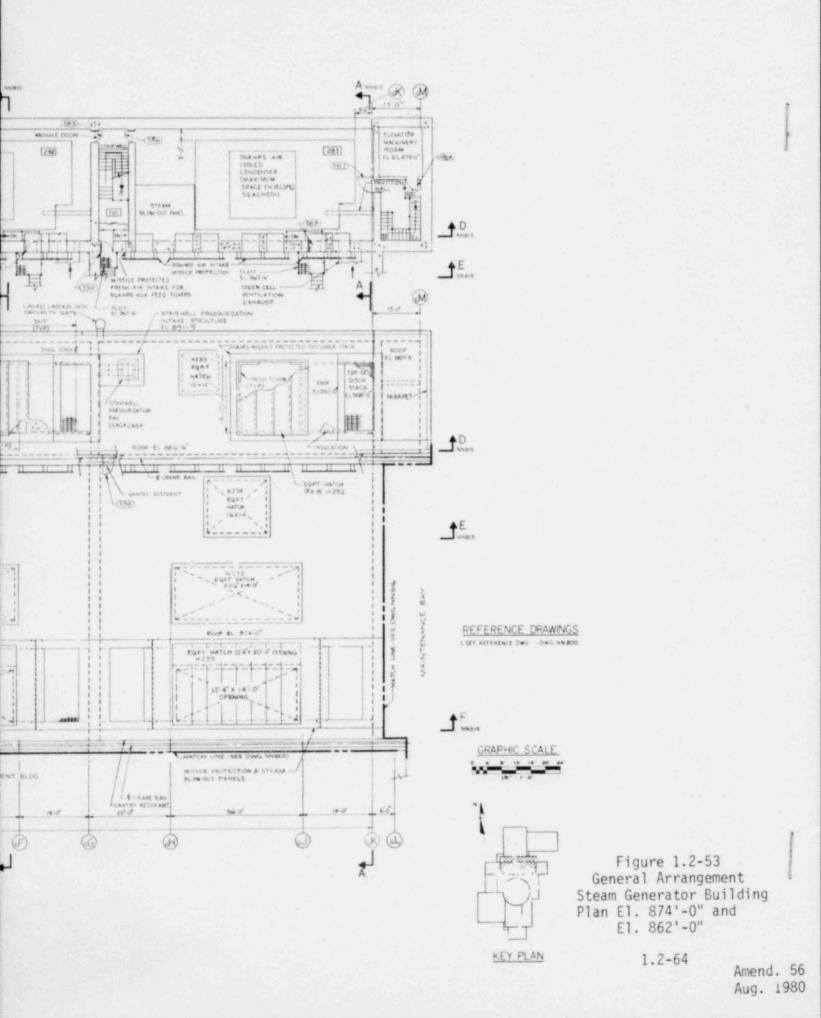


Figure 1.2-52 General Arrangement Steam Generator Building Plan El. 733'-0"



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NTMD SODREM PUMP DRIVE SEIDNK 200A 22-0

PLAN ABOVE EL 806'-0"

60

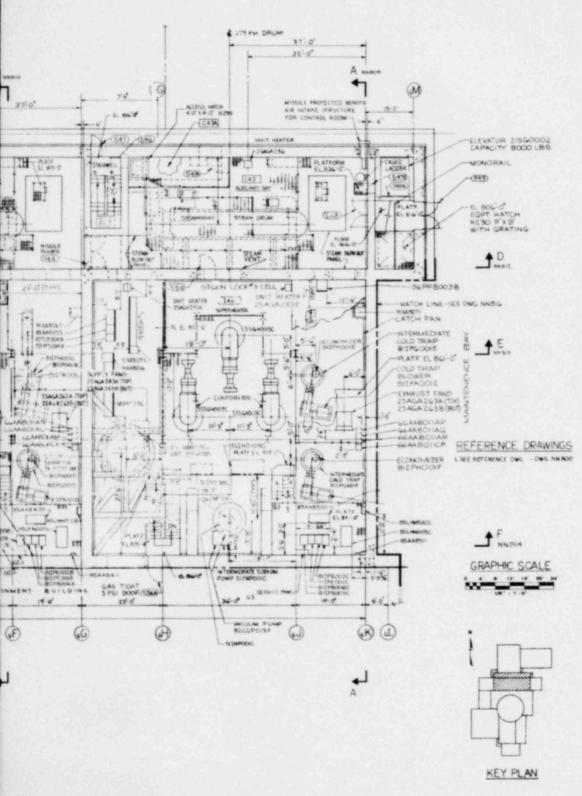
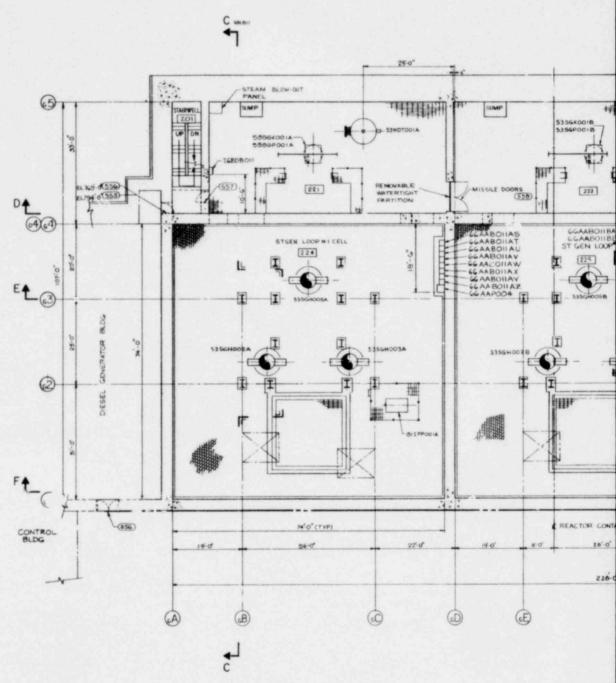


Figure 1.2-54 General Arrangement Steam Generator Building Plan El. 806'-0"



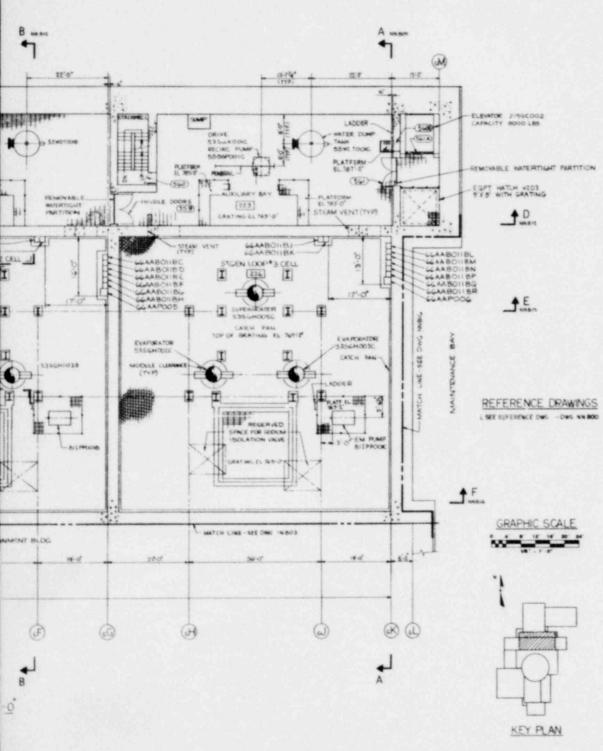
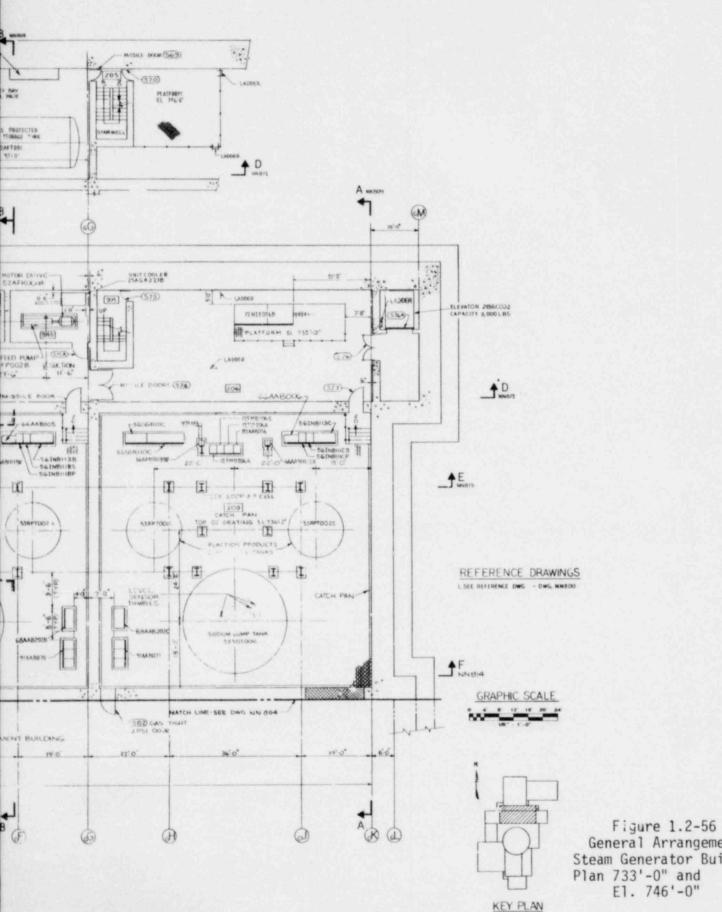
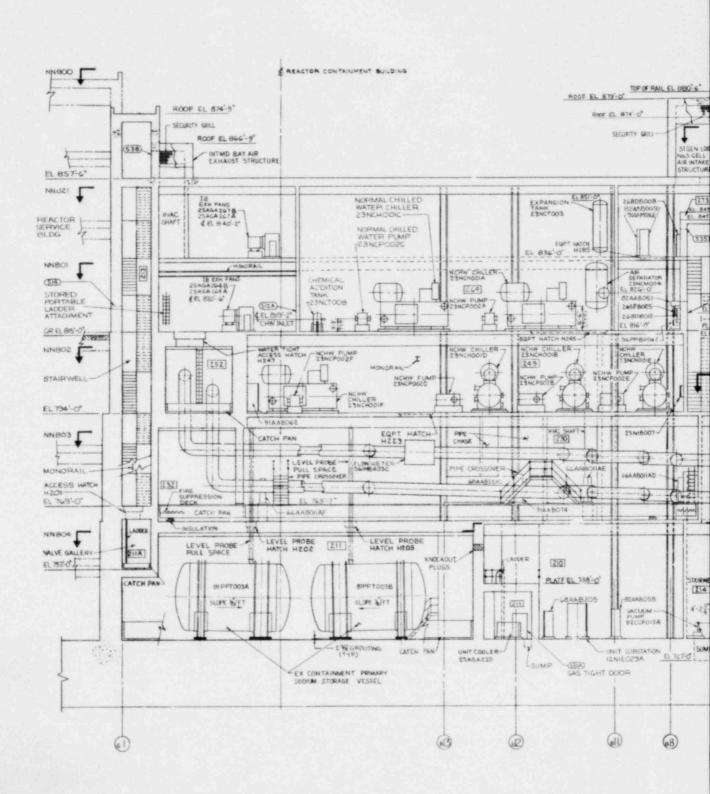


Figure 1.2-55 General Arrangement Steam Generator Building Plan 765'-0"



General Arrangement Steam Generator Building



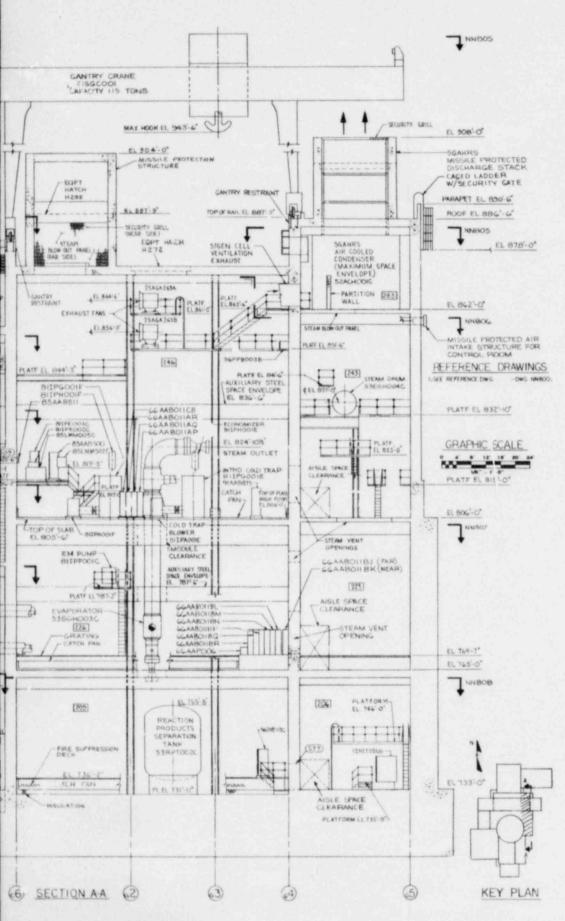
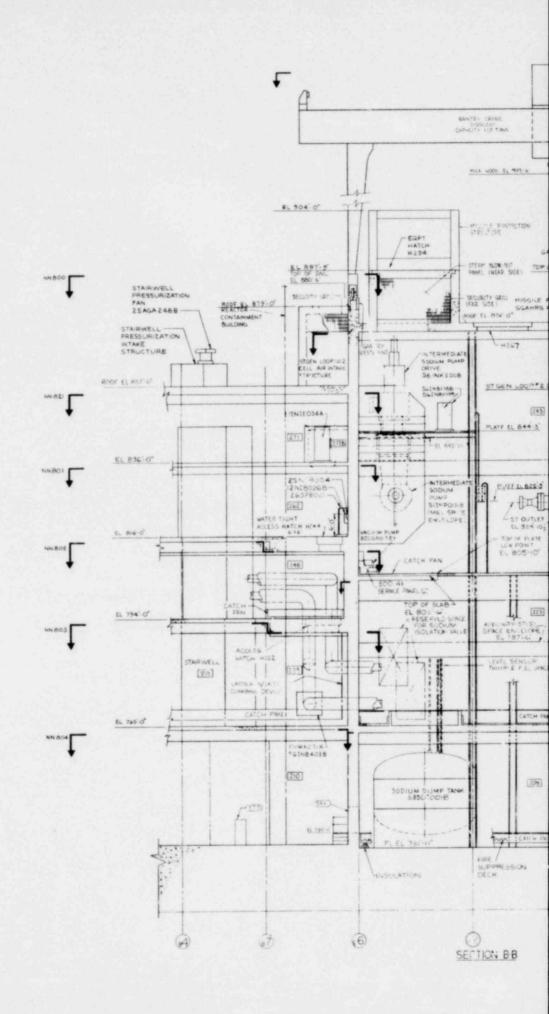


Figure 1.2-57
General Arrangement
Steam Generator Building
Section A-A



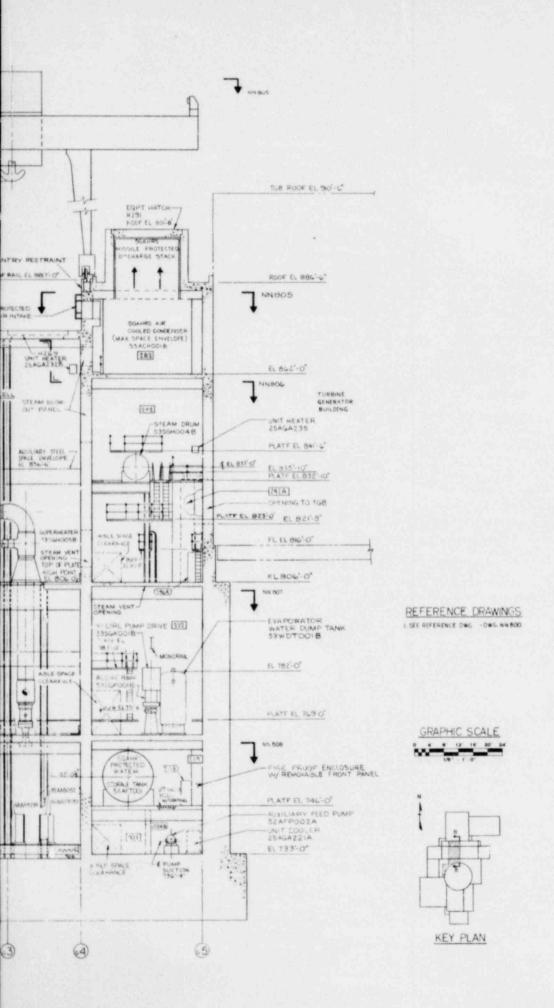
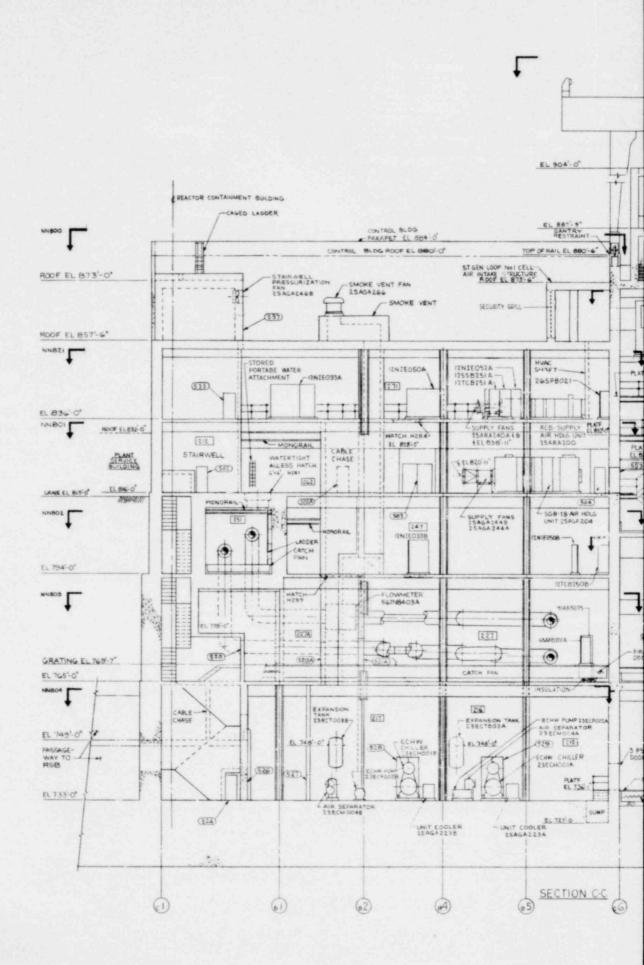
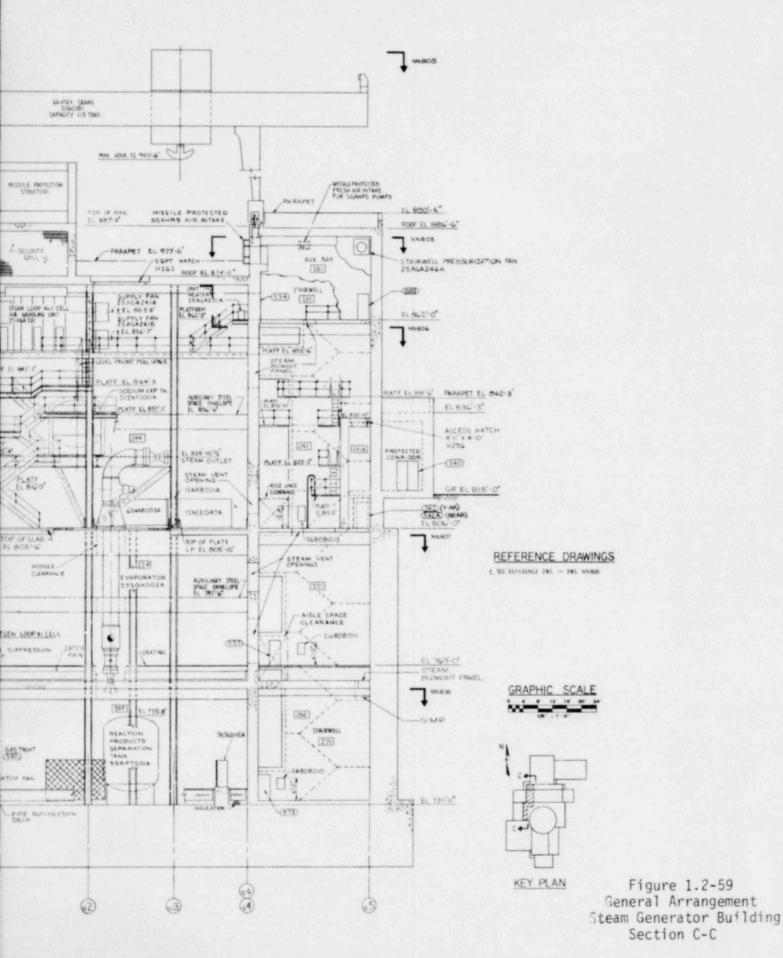
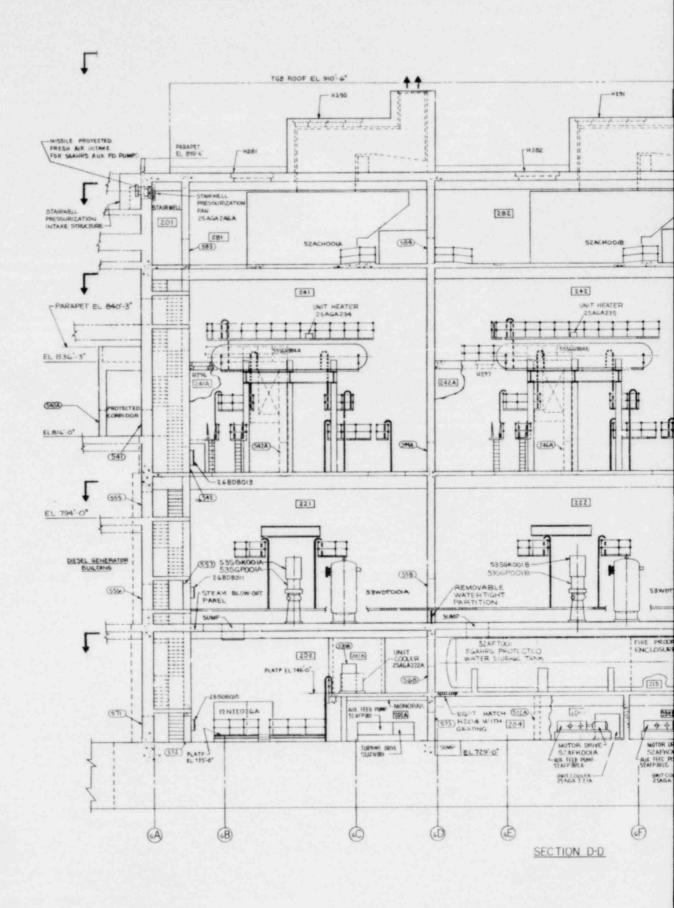


Figure 1.2-58
General Arrangement
Steam Generator Building
Section B-B







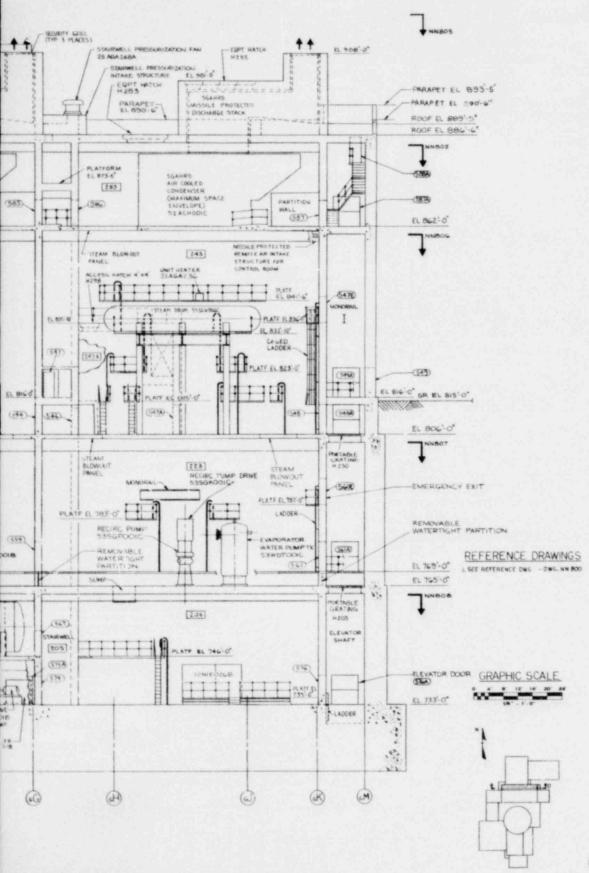
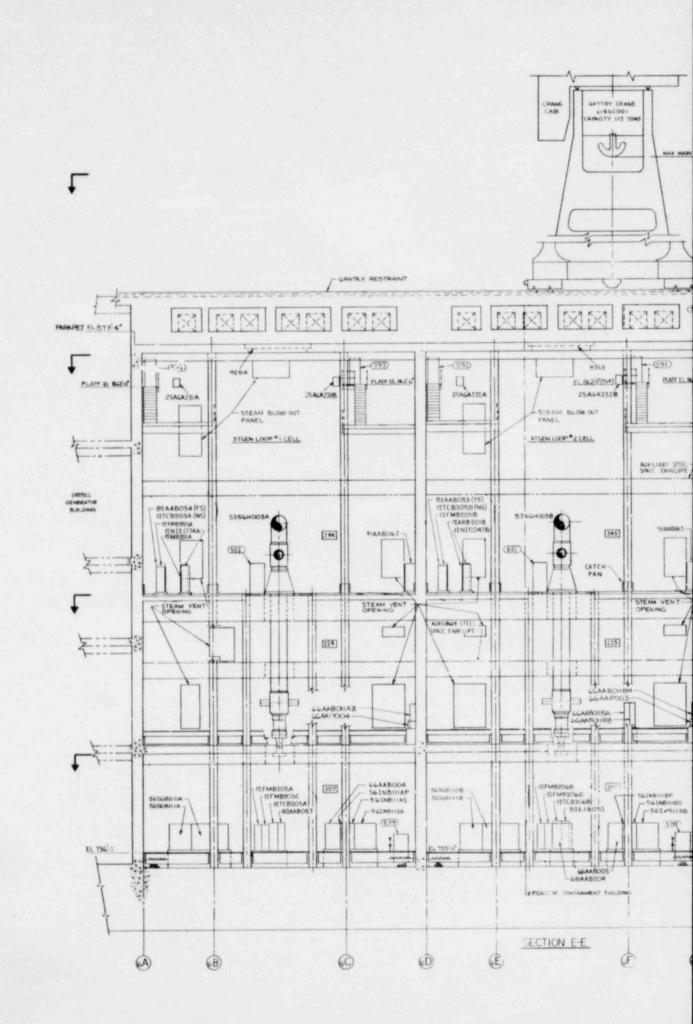


Figure 1.2-60 General Arrangement Steam Generator Building Section D-D

KEY PLAN



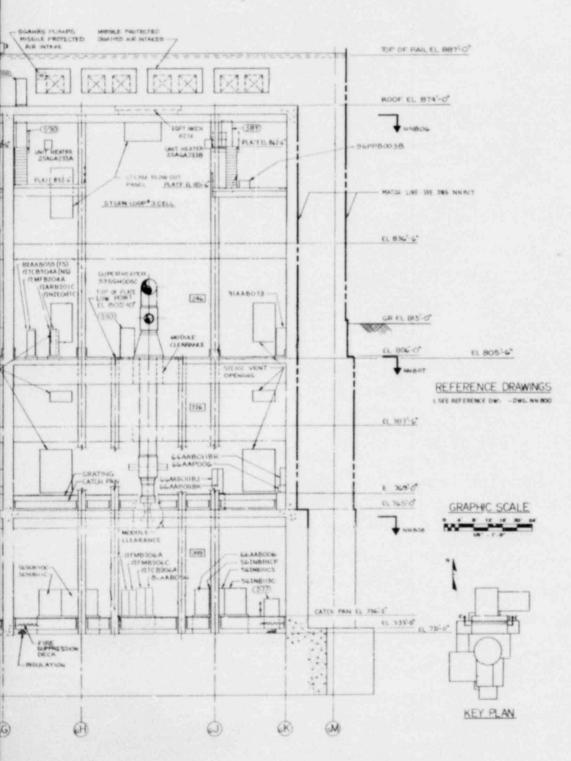
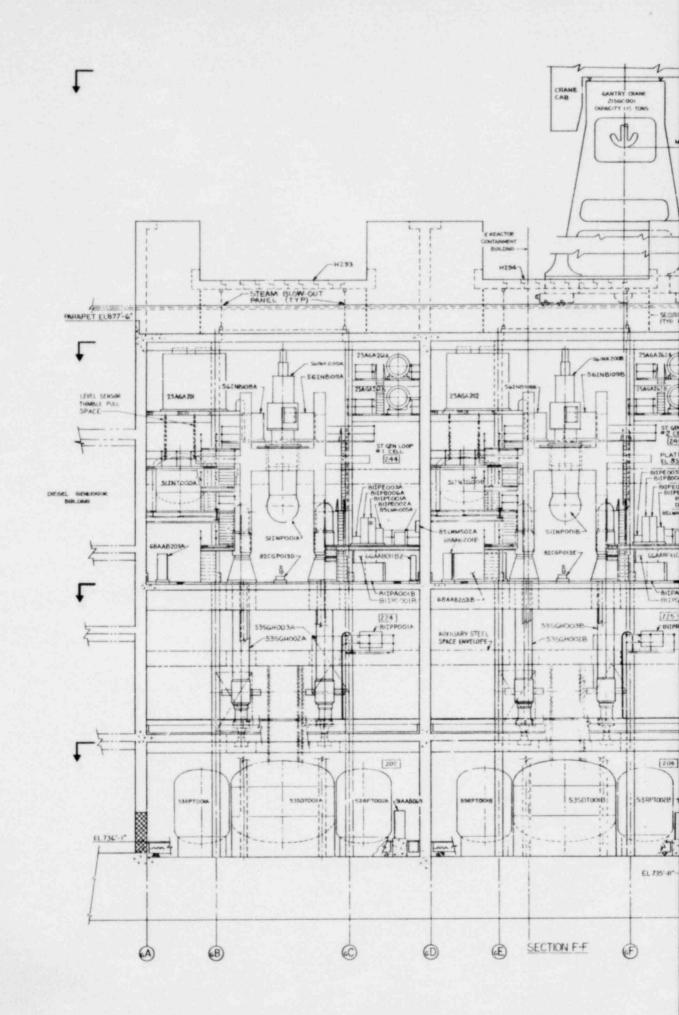
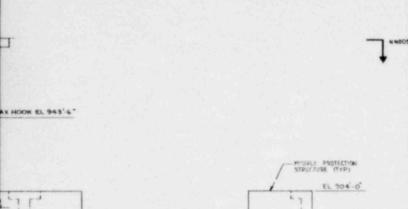


Figure 1.2-61 General Arrangement Steam Generator Building Section E-E





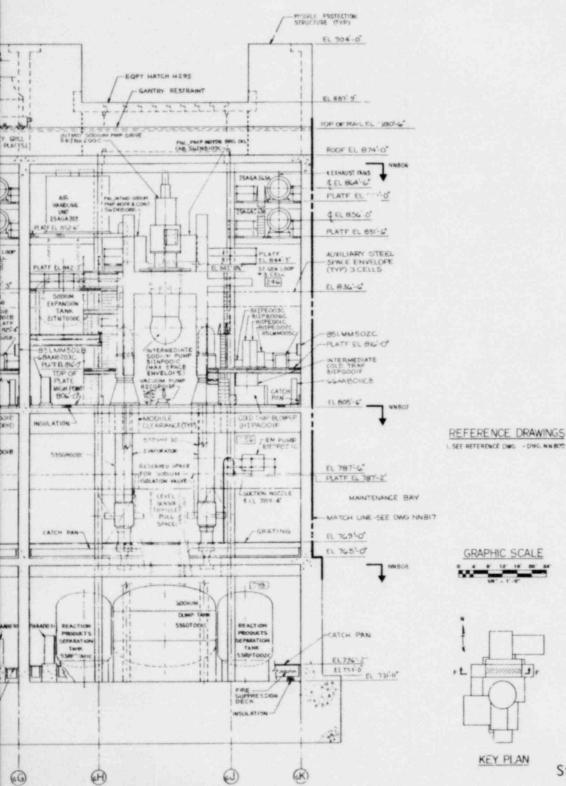
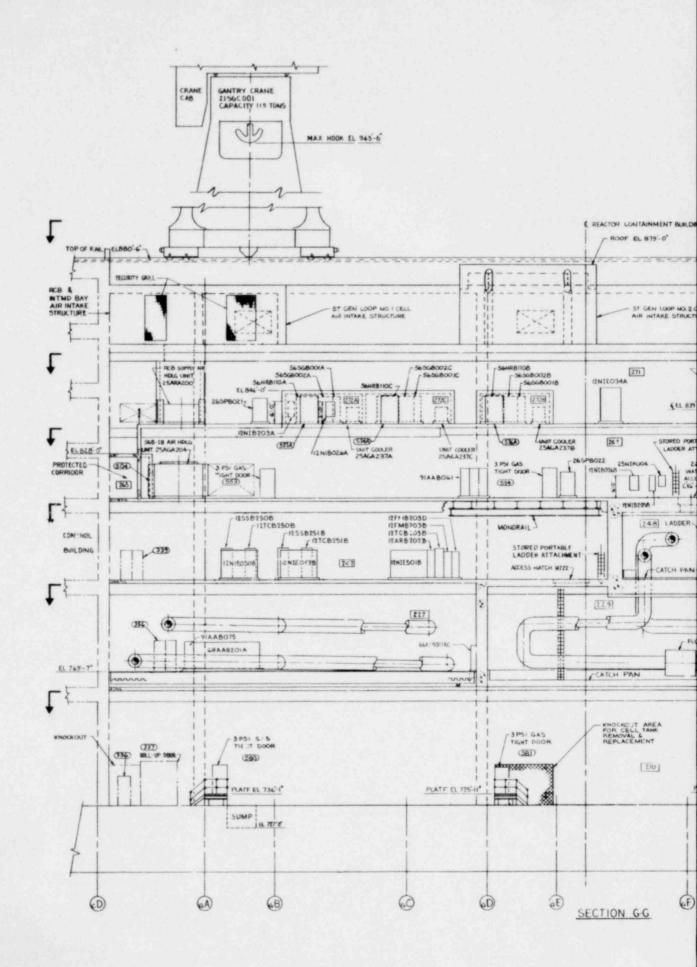


Figure 1.2-62 General Arrangement Steam Generator Building Section F-F



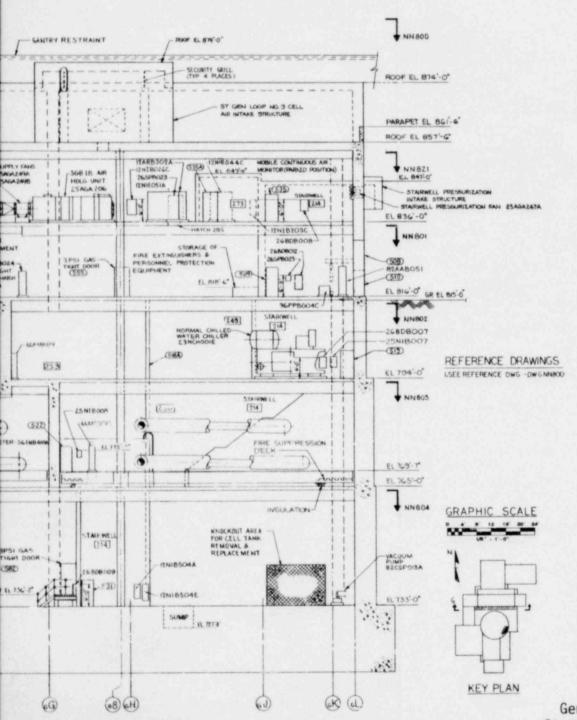


Figure 1.2-63
General Arrangement
Steam Generator Building
Section G-G

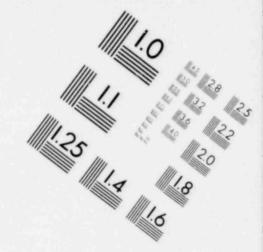


IMAGE EVALUATION TEST TARGET (MT-3)

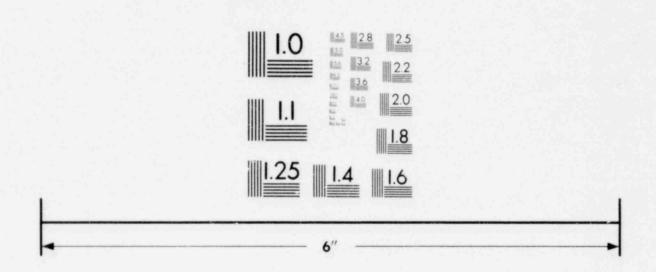
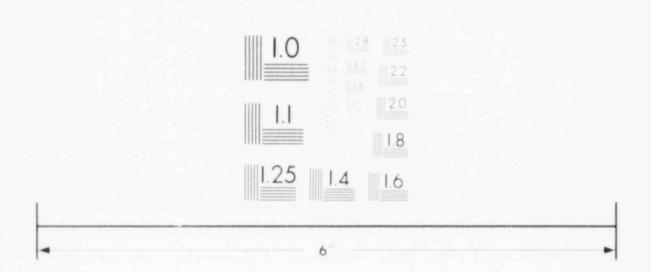




IMAGE EVALUATION TEST TARGET (MT-3)





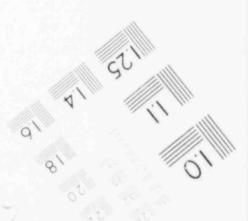
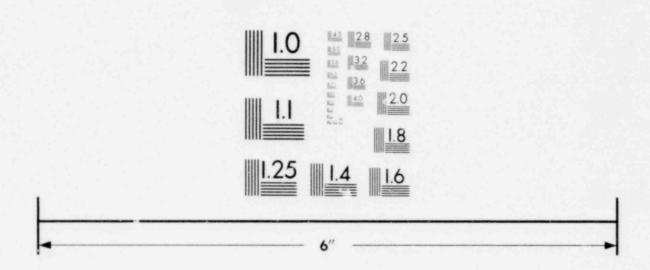
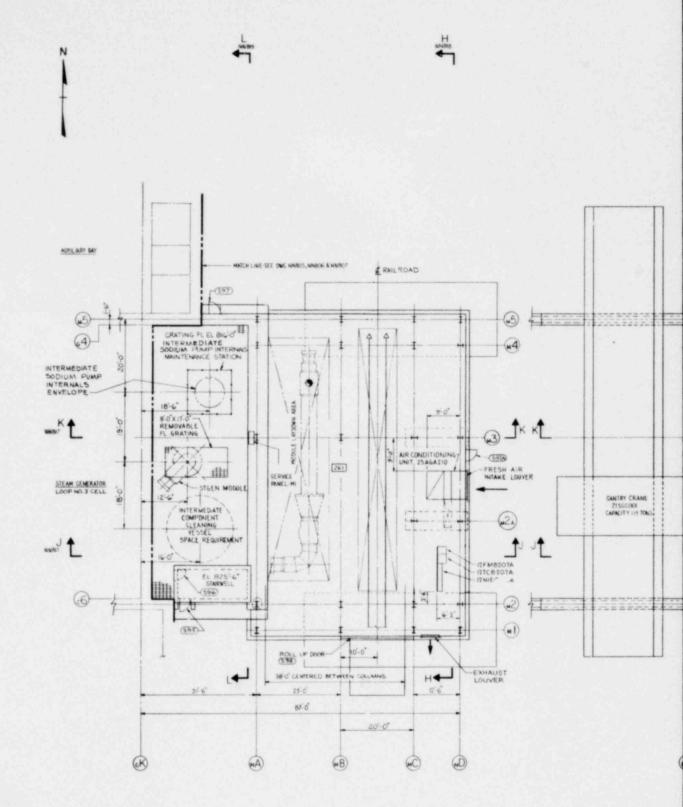


IMAGE EVALUATION TEST TARGET (MT-3)



To all to a second seco



PLAN ABOVE EL 816-0°





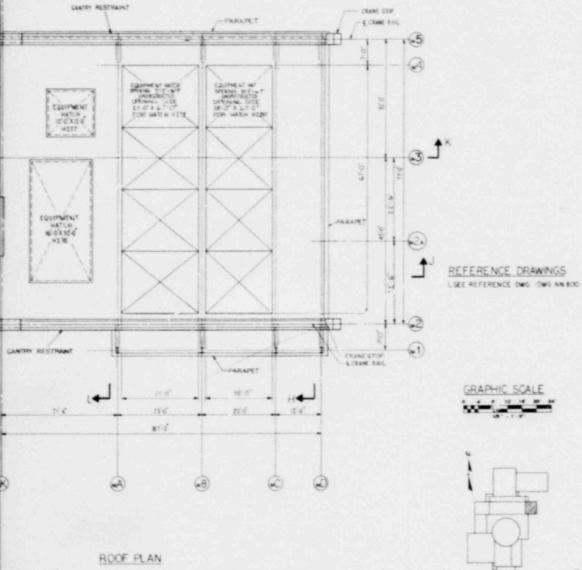
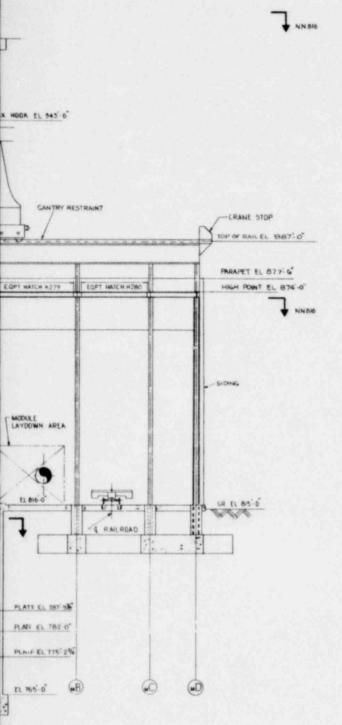


Figure 1.2-64
General Arrangement
Steam Generator Building
Plan El. 816'-0" and Roof Plan

1.2-75

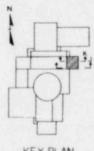
KEY PLAN



SECTION K-K

REFERENCE DRAWINGS

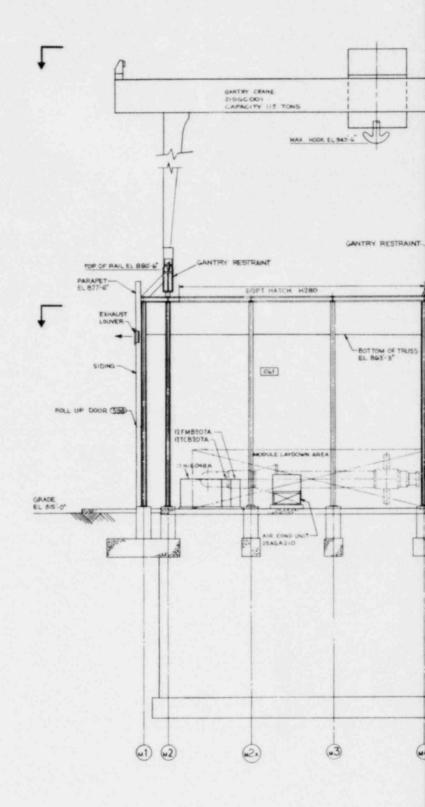


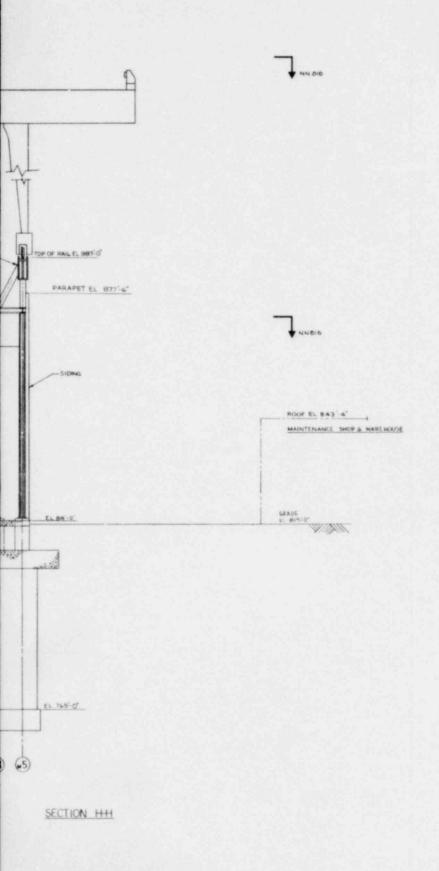


KEY PLAN

Figure 1.2-65 General Arrangement Steam Generator Building Section J-J and K-K

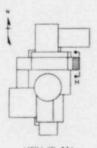
1.2-76





REFERENCE DRAWINGS





KEY PLAN

Figure 1.2-66 General Arrangement Steam Generator Building Section H-H

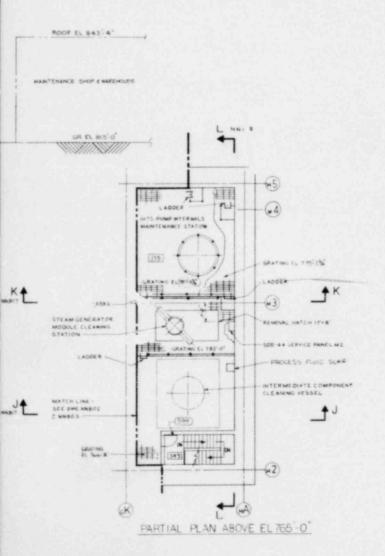


5'- 6"

99'-6"

TURBINE GENERATOR BUILDING





REFERENCE DRAWINGS

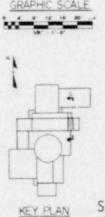
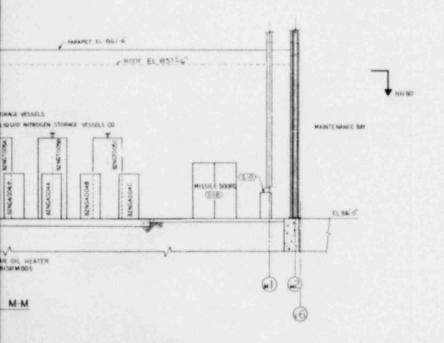


Figure 1.2-67
General Arrangement
Steam Generator Building
Section L-L Part Plan
El. 765'-0"

OIL HEATER

MOOI .



REFERENCE DRAWINGS

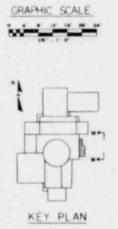


Figure 1.2-68
General Arrangement
Steam Generator Building
Plan El. 816'-0" and 840'-0"

1.2-79

PLAN ABOVE EL 836'-0"

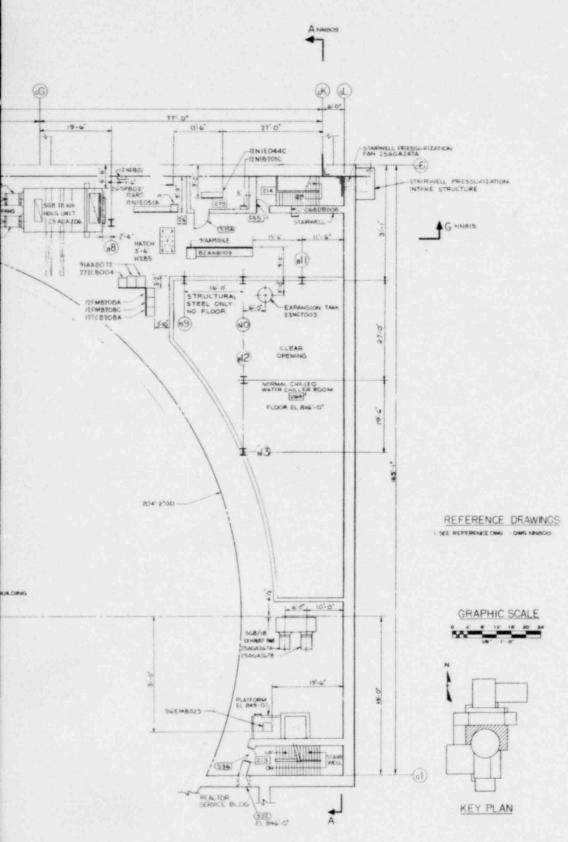
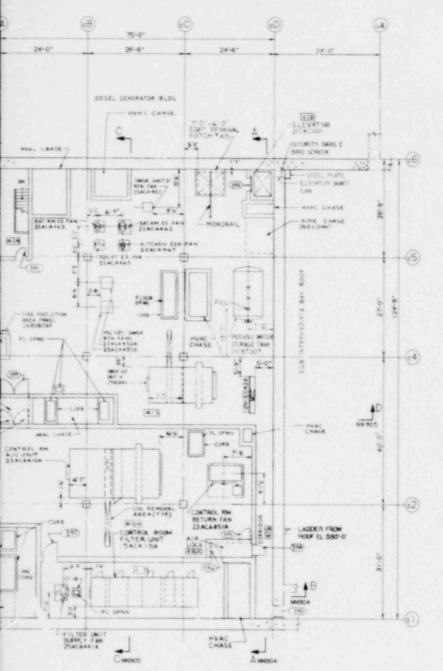


Figure 1.2-69
General Arrangement
Steam Generator Building
Intermediate Bay
El. 836'-0"

ROOF PLAN ABOVE EL 880'-0"

GENERAL NOTES

- L STWERS S AND ASSESSIVATIONS WARD DOC -D GOSA E ALL PRETITION WALLS ON EL 765'6'A EL 735'0" ARE FREWALLS.



PLAN ABOVE EL 863-3"

REFERENCE DRAWINGS

HEFERENCE DHAMING
MODI-CE SONESIA SHARINGEMENT PLAN
MODI-CE SONESIA SHARINGEMENT PLAN
MODI-CE SONESIA SHARINGEMENT PLAN
MODI-CE SONESIA SHARINGEMENT PLAN
MODI-CE SONESIA SHARINGEMENT

LEGEND

- EIRS CASINGT SWIGHT NIT LINE FRONT
- 40 CELL MINIBER
- RNOCKOUT SECTION
- CONCRUTE

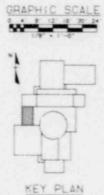
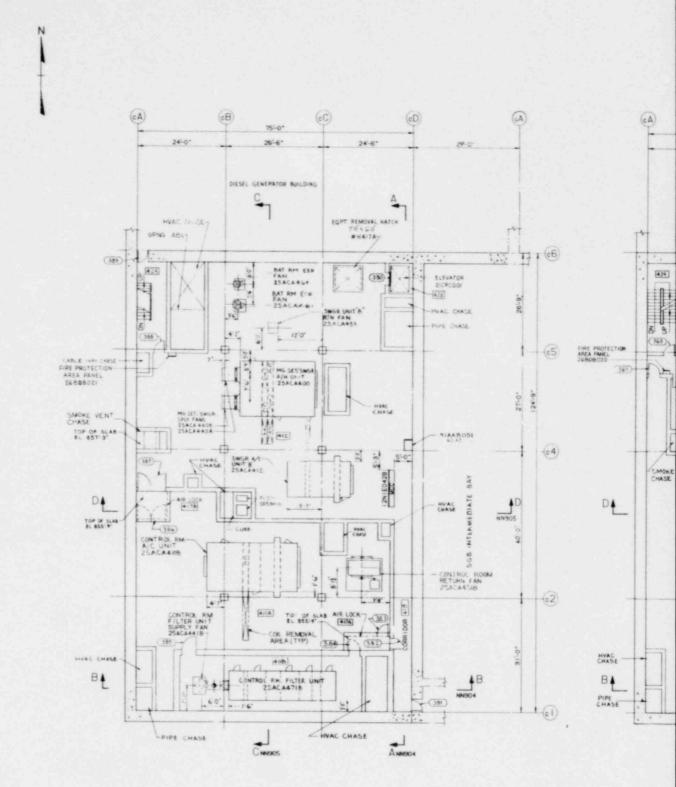
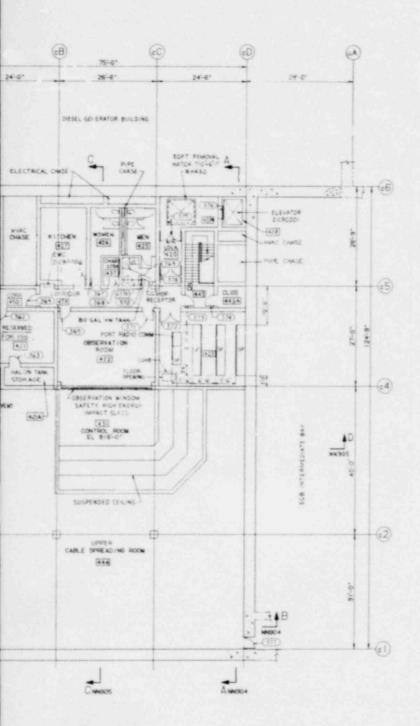


Figure 1.2-70 General Arrangement Control Building E1. 880'-0" and 863'-3"

1.2-81



PLAN ABOVE EL 847-3"



PLAN ABOVE EL 831'-0"

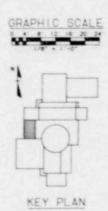
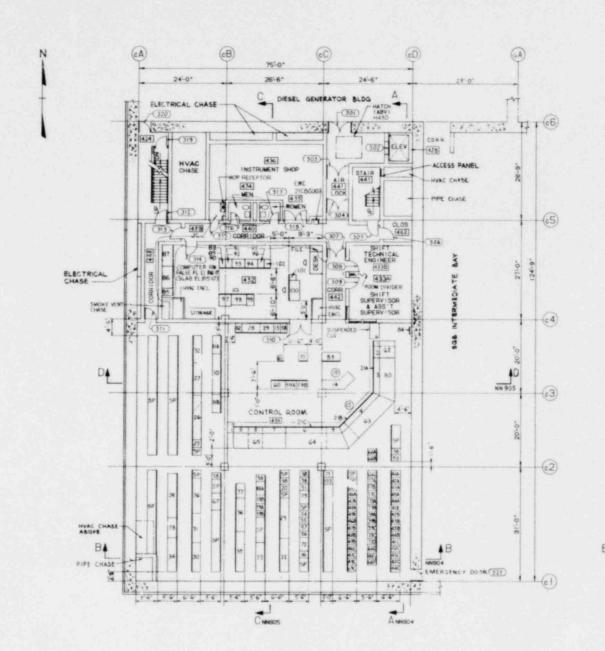


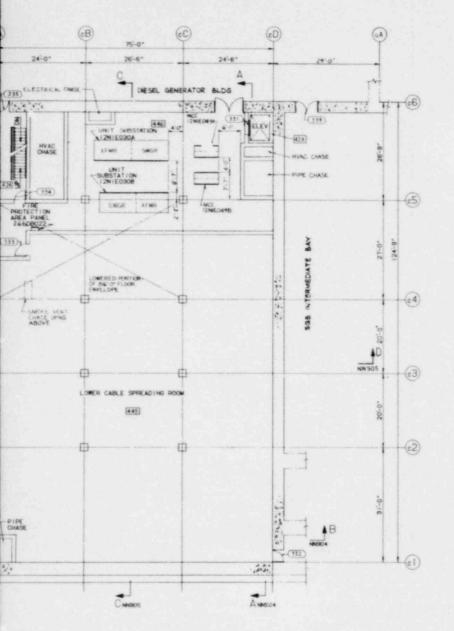
Figure 1.2-71 General Arrangement Control Building El. 847'-3" and 831'-0"

1.2-82



PLAN ABOVE EL 816'-0"

TEM		EQUIPMENT NO	ITEM		EQUIPMENT NO	TEM	DESCRIPTION	EQUIPMEN'
1	REACTOR SUPPORT SYSTEMS	90098016	22	HVAC SYS RECIPC AIR & "TUS CAR	5NAB((0)	434	PRIMARY PPS COMPARATOR PML	9995800
2	REACTOR SUPPORT SYSTEMS	90038016	2:	HVAC CONTROL RACK	59AAB002	438	PRIMARY POS COMPARATOR PNL	9995800
3	ENGINEERED SAFETY SYSTEMS	90038016	24	GEN PROTECTION	12N1B002	43C	PRIMARY PPS COMPARATOR PNL	99PSB00
4	REACTOR PRI HEAT TRANSPORT SYSTEMS	90CSBC16	25	TURB GEN SUPERVISORY PANEL	69NAB025	444	PRIMARY PPS LOGIC RACK	99PS8003
5	INTHO NA HEAT TRANSPORT SYSTEMS	9003B016	26	TURA EHC FOUIPMENT BAYS	63AAB028	44B	PRIMARY PPS LOGIC RACK	99958003
6	STEAM OEN & ASSOCIATED SYSTEMS	90058016	27	BOY NUXILIANIES	69AA8024	440	PRIMARY PPS LOGIC RACK	99958003
7	TURBINE SYSTEMS	90CSB016	28	NON DODIUM FIRE PROTECTION PANEL	26808047	45A	PRIMARY PPS ISOLATION RACK	99PS8000
8	GENERATOR SYSTEMS	90CSB016	29	SODILIM FIRE PROT Z-IND PANEL	265PB015	458	PRIMARY PPS ISOLATION RACK	99PSB003
9	SYNC & MAIN UNIT CONTROL	90038016	30	HEAT REMOVAL & CONDIN LGC RACK	56PRB020	45C	PRIMARY PPS ISOLATION RACK	99958003
10	SMYD & STA ELEC DISTR	12N1B02C	31	STEAM GEN LGC RACK	56568100	46A	SECONDARY PPS BUFFER	99258002
1.14	EMER DIESEL DEN PANEL	12N1B010	52	CHILLED WATER CONTROL CABINET	1 231CB001	468	SECONDARY PPS BUFFER	99958002
LIBI	EMER DIESEL GEN PANEL	12N16019	35	AUX LIQ METAL CONTROL CABINET	SIAABOIS	46C	SECUNDARY PPS BUFFER	99P5B002
12.	REACTOR OPERATOR	I received	34	REMOTE ANNUNCIATION CABINETS	90058019	474	SECONDARY PRS TERMINATION CAB	99958002
1.3	SODIUM LEAK DETECTOR PANEL	66AAB008	35	STEAM PLANT CONDITIONING RACK	G9AABUZG	478	SECONDARY PPS TERMINATION CAB	99958002
14	DESK	-	36	STEAM PLANT LOGIC RACK	URAABU27	470	SECONDARY PPS TERMINATION CAB	99958002
15	CHAIR	The second second	37			484	SECONDARY PPS COMPARATOR CAP	99958002
à	SEISMIC INSTRUMENT PANEL	271CB001	38	TERMINATION RACKS	900'58'015	48B	SECONDARY PPS COMPARATOR CAB	99958002
7A	FLUX MON! TORING	95AAB001A	350	PPS CONTAINMENT ISOL INSTRIRACH	99ESB005A	48C	SECONDARY PPS COMPARATOR CAB -	99PS9002
7B	FLUX MONITORING	95AABUCIE	596	PPS CONTAINMENT ISOL INSTRIBACK	99ESB0058	494	SECONDARY PPS SOLENDID DRIVE	99958004
126.	FLUX MONITORING	95AAB001G	396	PPS CONTAINMENT ISOL NOTE RACK	99£380050	43B	SECONDARY PPS SOLENDID DRIVE	99P5B004
8A	CR RAD MON PRINTER	36AABCOZA				49C	SECONCARY PPS SOLENDID DRIVE	99PS8004
åB.	CR RAD MON CONSOLE	96AABCO1A				50	PPS MONITOR RACK	99AAB007
9A	CLASS 1E PANEL A	36AAB003A	AIA:	PRIMARY PPS BUFFER	99P5B0010	51	PRIMARY ROD CONTROL & INSTR	90058010
38	CLASS IE PANEL A	%AABOOJB	418	PRIMARY PPS BUFFER	99P5B0010			
20	WEATHER STATION SPINCE		416	PRIMARY PPS BUFFER	9985B001G		DEUK TIAP RACTO	1
Z1A:	PAX TELEPHONE		42A	PRIMARY PPS TERMINATION CAB	99PSB001B	54	REACTOR CONTROL PANEL	90CSB013
	PAIC		428	PRIMARY PPS TERMINATION CAB	99P\$8001E	55	SUPERVISORY CONTROL PANEL	90AAB005
1215	COMMUNICATIONS JACK & SWITCH		420	PRIMARY PPS TERMINATION CAB	99PSB001H	56	FLOR CONTROL PANEL	90058011



REFERENCE DRAWINGS

PLAN ABOVE EL 794'-0"

OLITEM	DESCRIPTION	EQUIPMENT NO	STEM	DESCRIPTION.	EQUIPMENT NO
57	LOAD DISPATCH PANEL	90CSB00SB	76	HEAT REMOVAL & CUNDTH LOC RACK	56HRB020
1.58	FAILED FUEL HEADOUT PANEL	94AABC12	2.7	POH & OS REM DATA ACQ TERM	91AAB056
SSA	COMPUTER TYP MRITER	91AAMO15A	78	PLEMOTE ANNUNCIATOR CABRIETS	67NIBO03A
599	COMPLITER TYPERRITER	BIAAMOISB	79	MANUAL TEL SWBO & PAIC HAND SET	
60	COMPUTER LINE PRINTER/PLOTTER	91AAMC13	80	CRT DISPLAY & KZYBOARD	91AAMODIF
61	CRT DISPLAY & KEYBOARD	91AAMOO1A	81		
62	CRY DISPLAY & KEYBOARD	SIAAMODIB	87	BLOG FIRE PROTECTION FINEL	26808023
63	CRT DISPLAY & KEYBOARD	STAAMOOTO	83	PLANT SECURITY	ZICBCOOZ
64	CRT DISPLAY & KEYBOARD	STARMOOTO	84	PATCH PANEL	
65	CRT DISPLAY & KEYBOARD	STANNOOTE	8.5	CABBAET CARD STORIUE	91AAJ003
56a	POH & DS REW DATA ACQ TERM	BIAABOSTA	86	CABINET PAPER STORAGE	SINASONS
669	POH & DS REW DATA ACG TERM	SIAABOSES	87	CABINET MAGNETIC TAPE STORAGE	91AA2001
860	POH & DS REW DATA ACQ TERM	SIA ABOSEC	8.6	MAGNETIC TAPE UNIT NO 3	91AAMO-DC
Teep	POH A DS REW DATA ACQ TERM	91AAB055A	89	SERIAL LINE INTERFACE	91AA8005
1968	POH A DS HEW DATA ACQ TERM	SIAABOSS B	90	FLERBLE DISC	91AAMO14
BEX	POH A DS REN DATA ACQ TERM	91AABOSSC	91	FIXED HEAD DISC	91AAMOO8B
	RECIRCULATING GAS CONTROL CAN	28168001	9.2	MAGNETIC TAPE NO. 2	31AAMOIOB
68	AND THE REAL PROPERTY OF THE PERSON NAMED IN COLUMN TWO IS NOT THE PERSON NAMED IN COLUMN TWO IS NAMED IN THE PERSON NAMED IN THE PERS		93	CENTRAL PROCESSOR UNIT NO 1	**************************************
69			9.4	CENTRAL PROCESSOR (NIT NO 2	#IAABOOZB
70	SECURITY SURVERLANCE STATION	21 c8c003	95	FIXED HEAD DON	91AAMOOSA
71	CONTAINMENT INSTRUMENTATION	27109002	76	MAGNETIC TAPE UNIT NO. 1	PIANNOTTA-
1 99	PCS SWITCHING LODGE	20058014	9.7	CARD PUNCH WITH KEY BOARD	91AAMO12
134	PHO AUX EQUIPMENT ISOLATION & LOGIC	99P5B005A	98	INE PRINTER	91AAMOO9
736	PPS AUX EQUIPMENT ISOLATION & LOGIC	99P5B005B	99	CARD READER	HIAAMOOS
792	PPS AUX COUPMENT PSOLATION & DOK	99P5B005C	106	FADGRAMER CONSOLE	91AABOOI
	PPS ALX EQUIPMENT ISOLATION & LOGIC	99P5B0090	101	COLDR CRY DISPLAY UNIT	PIAPRODIF
	PORTABLE RADIO COMMUNICATION	TBD	102	MAGNETIC TAPE UNIT NO 4	91 AAMOIDD
	SEC BOD CONTROL CARDING T	180	103	CONTAINMENT INSTRUMENTATION DIVI ON I	271080005

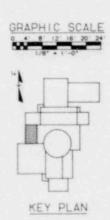
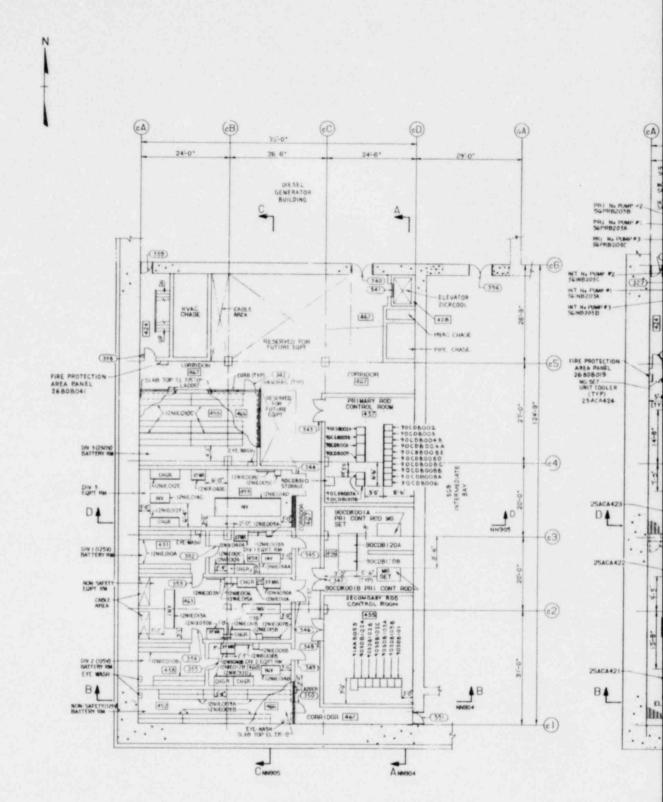
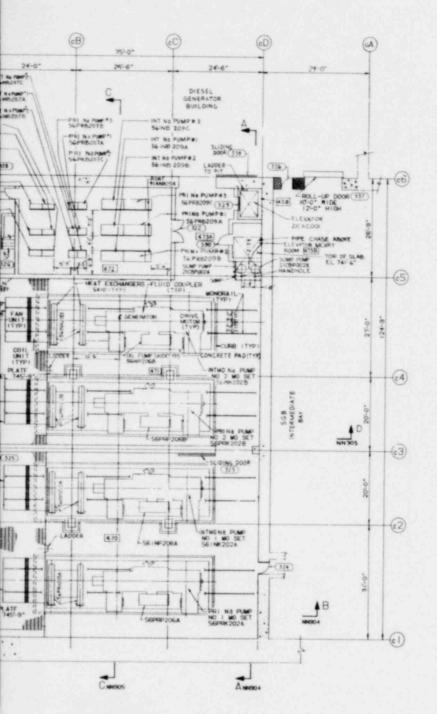


Figure 1.2-72
General Arrangement
Control Building
El. 816'-0" and 794'-0"



PLAN ABOVE EL 765'-0"



PLAN ABOVE EL 733'-0"

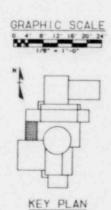
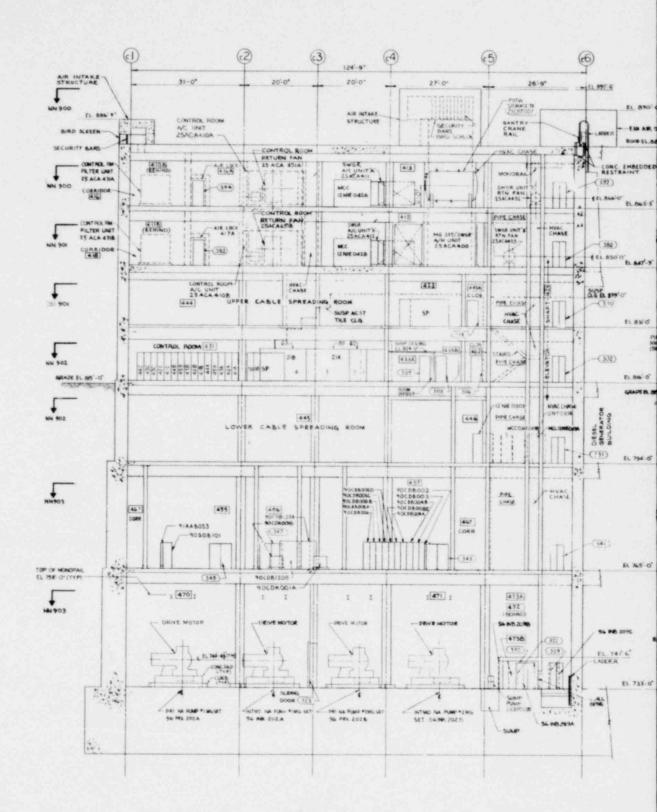
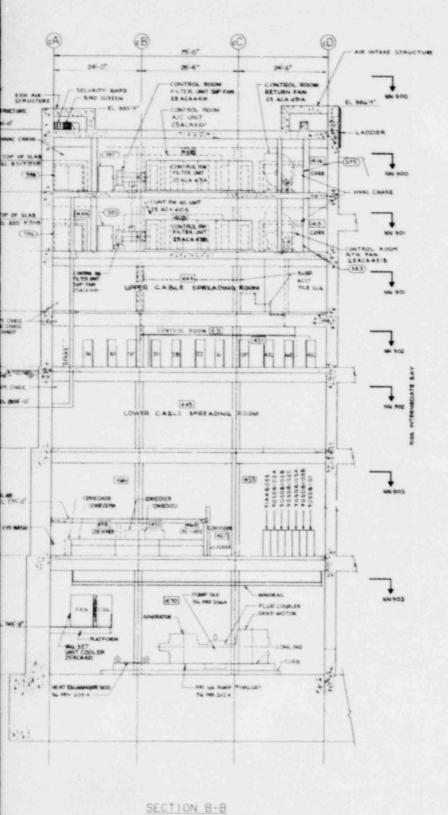


Figure 1.2-73
General Arrangement
Control Building
El. 765'-0" and 733'-0"



SECTION A-A



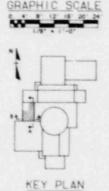
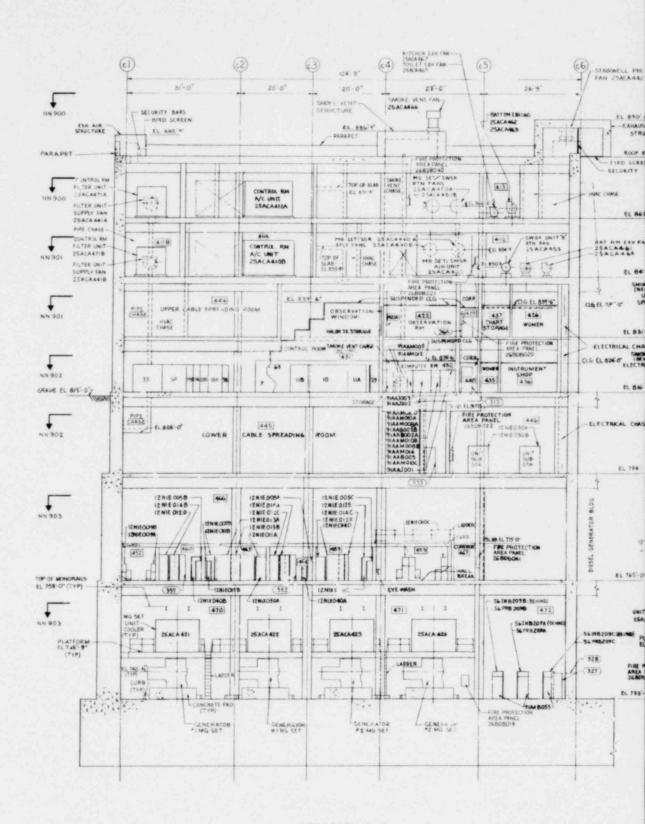


Figure 1.2-74 General Arrangement Control Building Section A-A and B-B



SECTION C-C

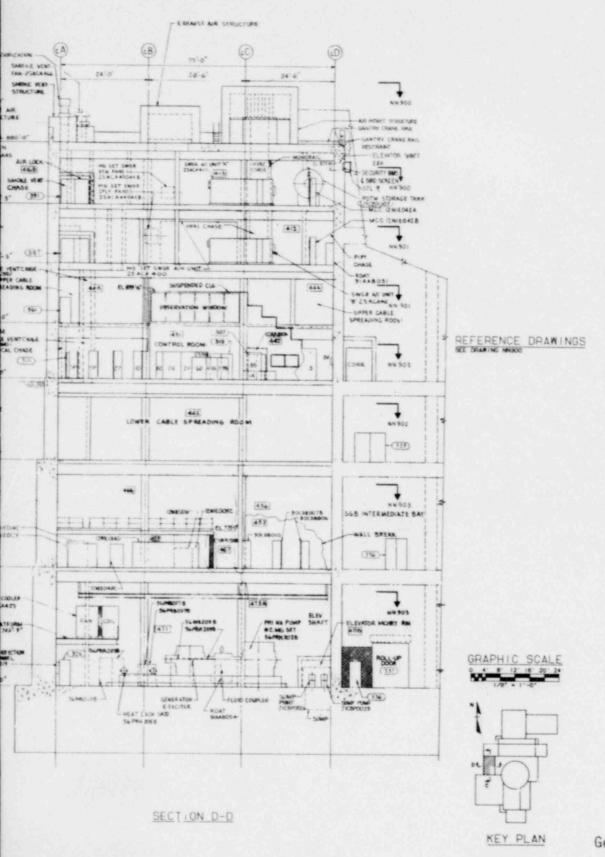


Figure 1.2-75 General Arrangement Control Building Section C-C and D-D

ROOF PLAN ABOVE EL 847'-3"

GENERAL NOTES

- I. SYMBOLS & ABBREVIATIONS PER WARD DOC D-0036
- 3 EQUIPMENT REMOVAL HATCH WILL BE SERVICED BY THE EXTENSION OF THE SGB GANTRY CRANE

REFERENCE DRAWINGS

NN953 DGB GENERAL ARRANGEMENT - PLAN ABOVE EL 816 - 0' & EL 794 - 0"

NN954 DGB GENERAL ARRANGEMENT - FLAN ABOVE SL 765'-0' & EL 733'-0'

NN955 DGB GENERAL ARRANGEMENT SECTION A-A & B-B

NN956 DGB GENERAL ARRANGEMENT SECTION C - C & D - D

LEGEND

EI&C CABINET, SWGR (HEAVY LINE FRONT)

GRATING

[410] CELL NUMBER

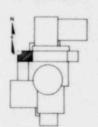
KNOCKOUT SECTION

TONCRETE BLOCK

CHECKERED PLATE

(400) DOOR MUMBER





KEY PLAN

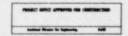
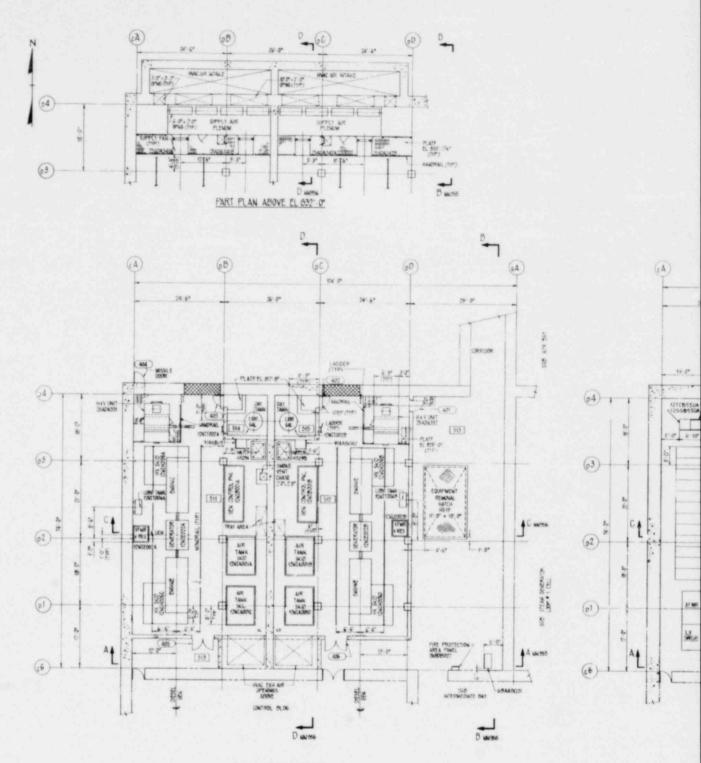


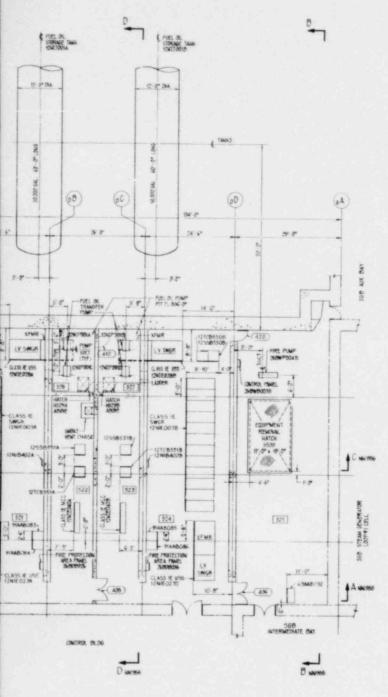
Figure 1.2-76 General Arrangement Diesel Generator Building El. 847'-3"

1.2-87



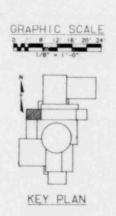


PLAN ABOVE EL 816'-0"



PLAN ABOVE EL 794'-0"

REFERENCE DRAWINGS
SEE DRAWING NNSS2



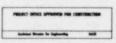
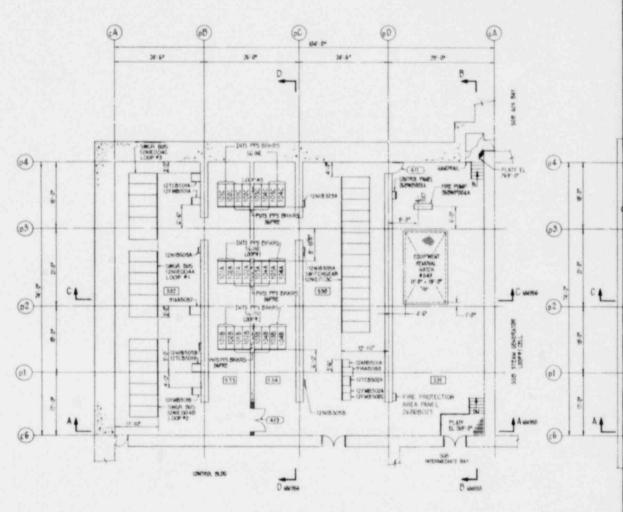
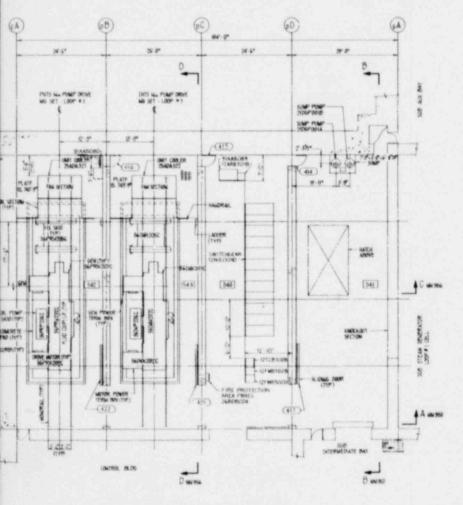


Figure 1.2-77 General Arrangement Diesel Generator Building El. 816'-0" and 794'-0"



PLAN ABOVE EL 765'-0"



PLAN ABOVE EL 733' 0"

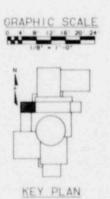
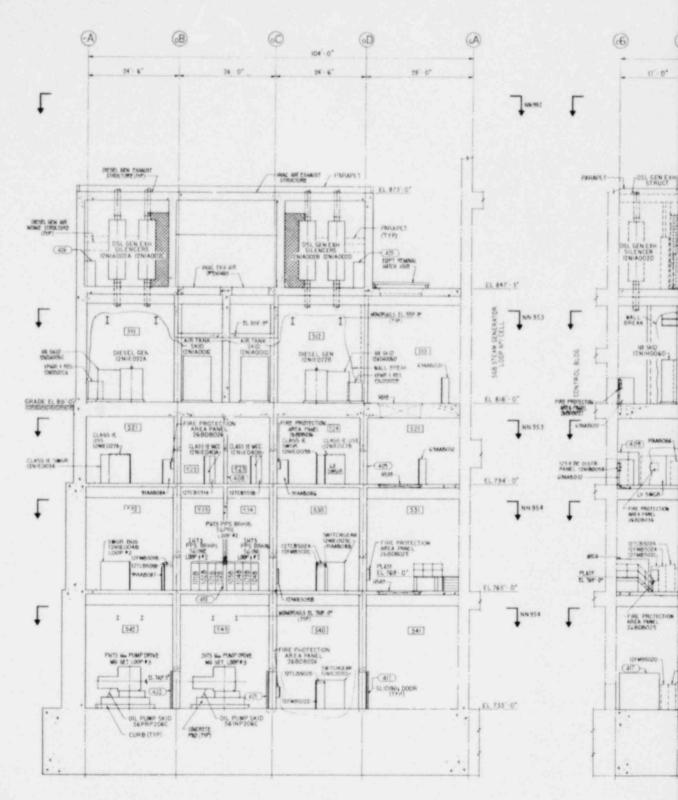


Figure 1.2-78
General Arrangement
Diesel Generator Building
El. 765'-0" and 733'-0"

1.2-89



SECTION A-A

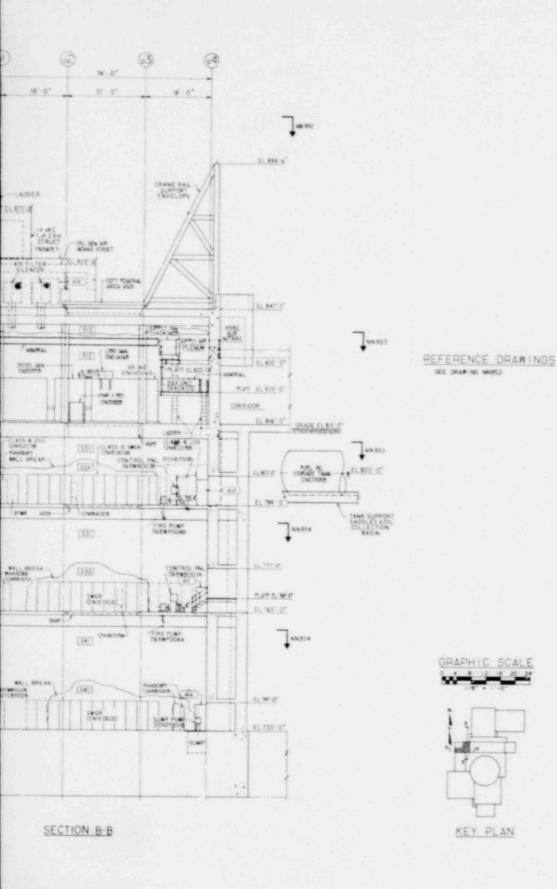
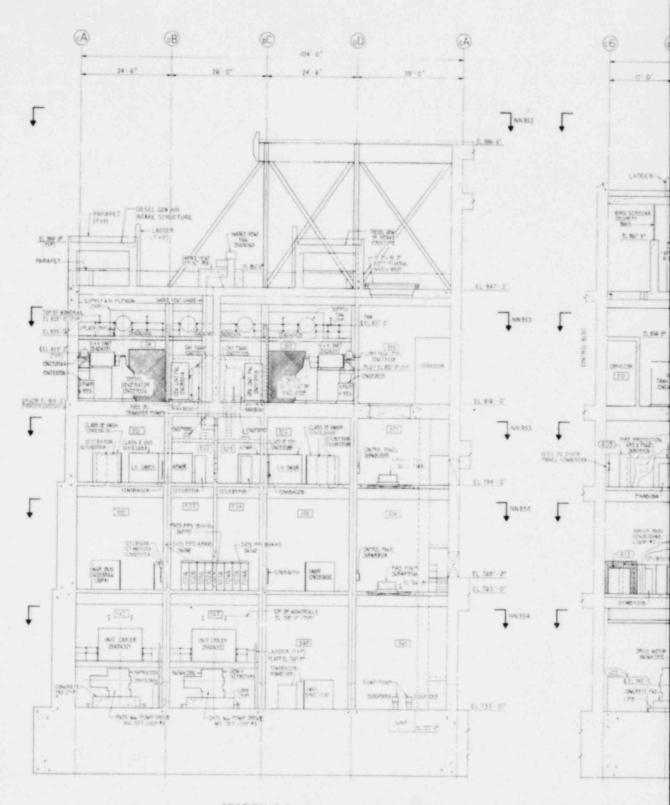
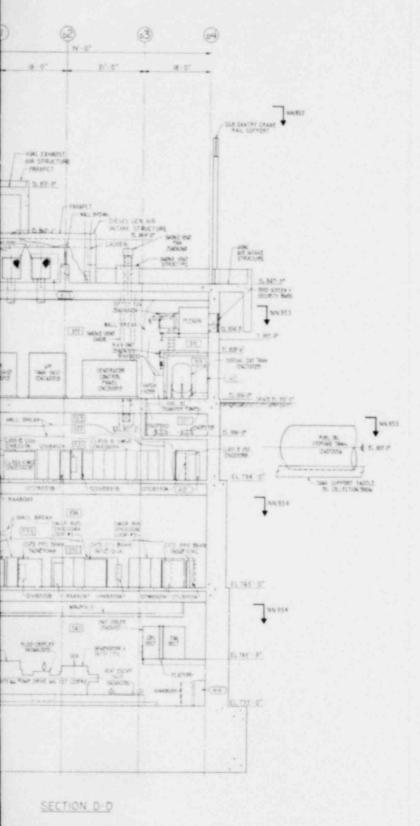


Figure 1.2-79
General Arrangement
Diesel Generator Building
Section A-A and B-B



SECTION C-C



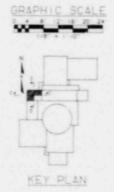
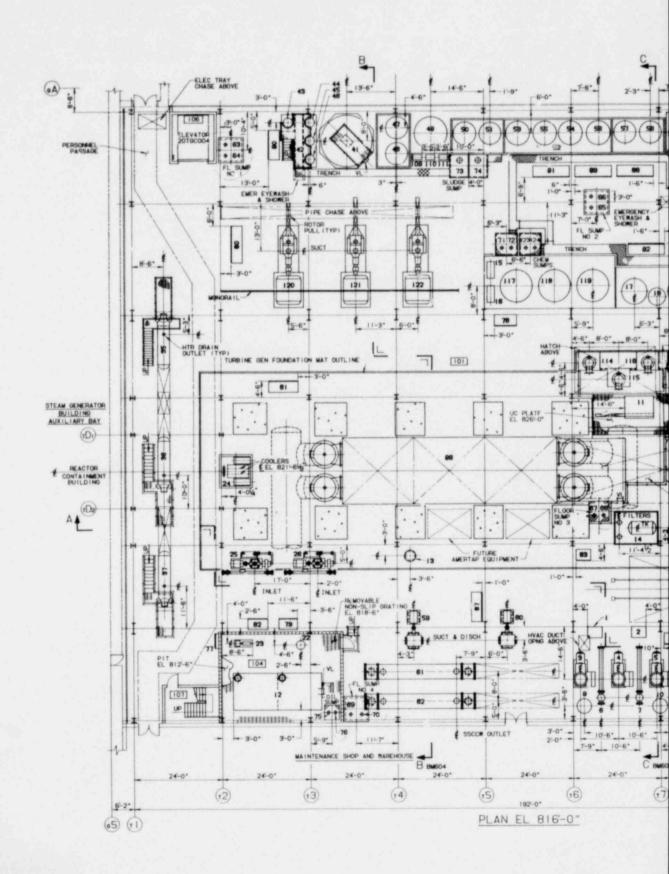
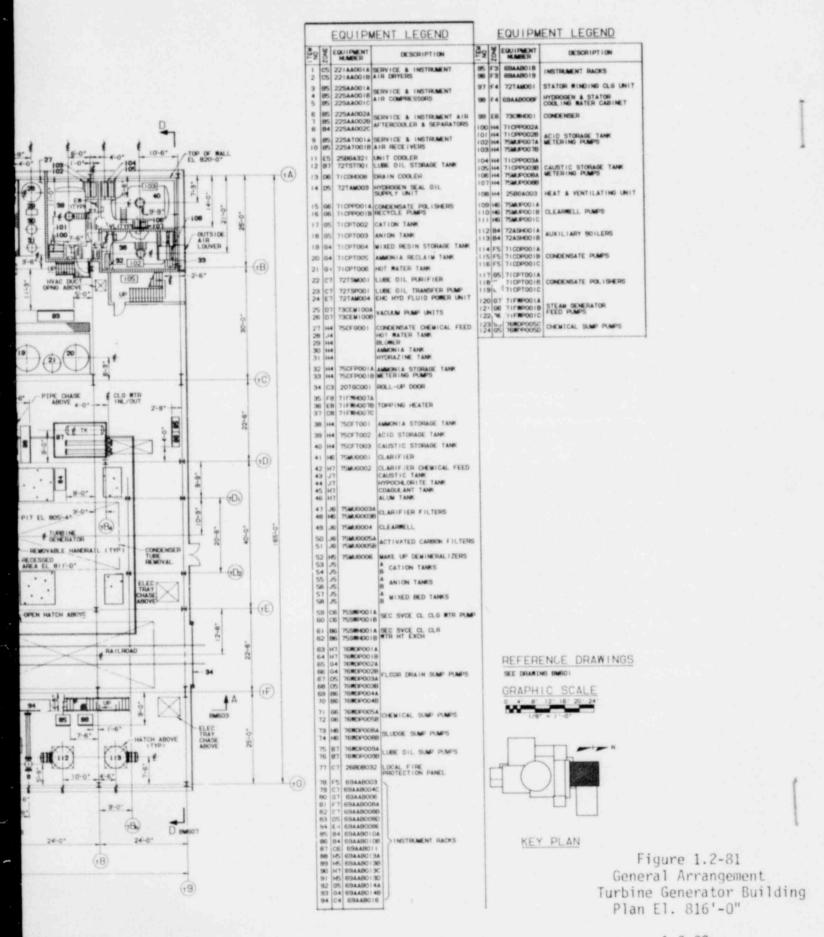
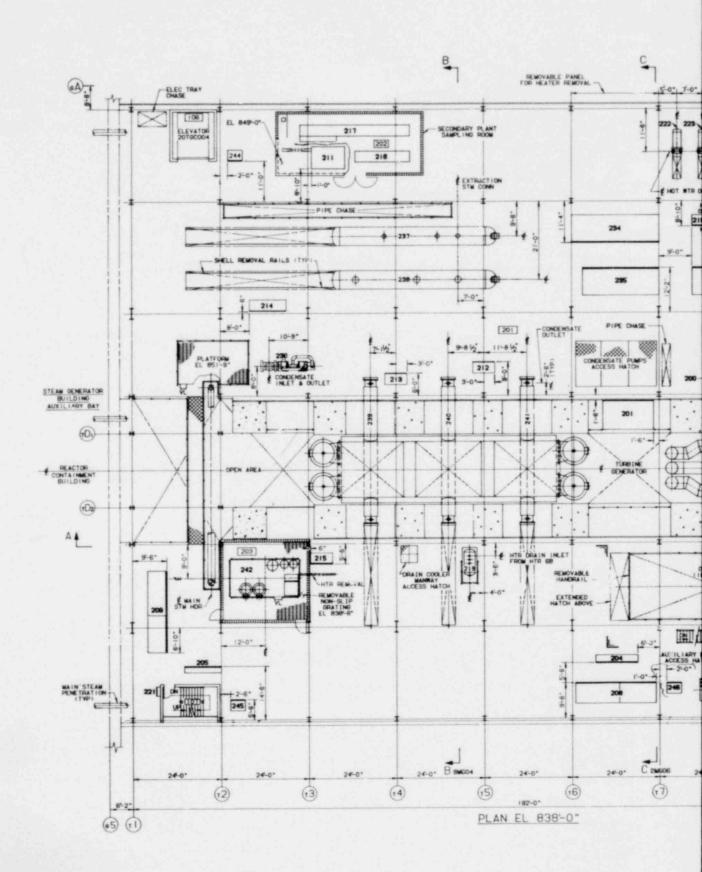
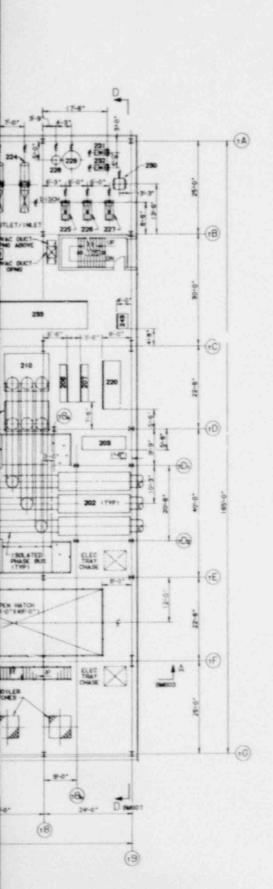


Figure 1.2-80 General Arrangement Diesel Generator Building Section C-C and D-D

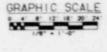


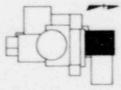






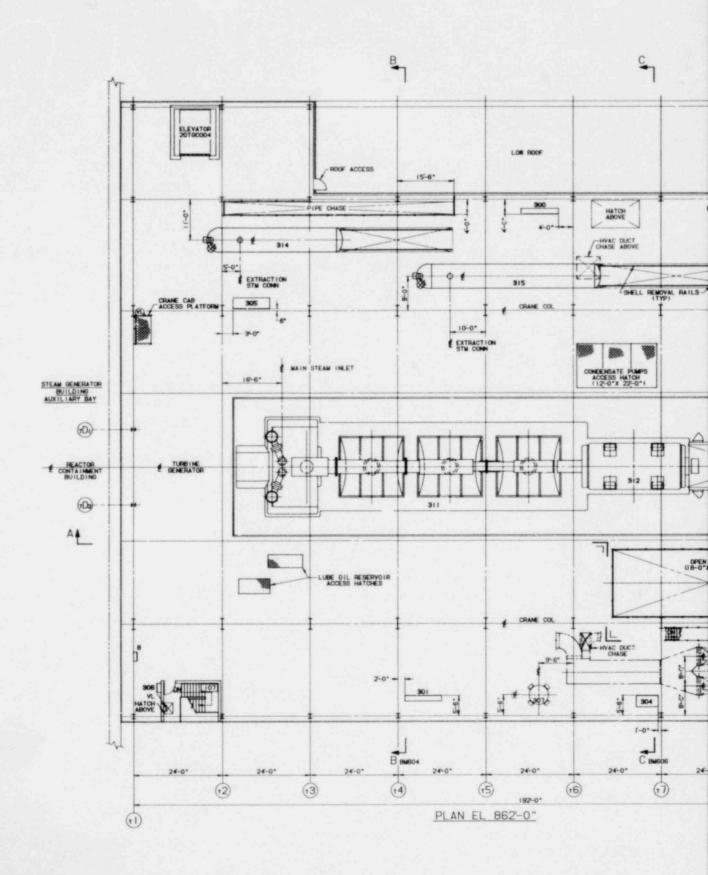




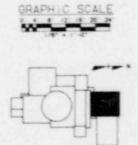


KEY PLAN

Figure 1.2-82
General Arrangement
Turbine Generator Building
Plan El. 838'-0"



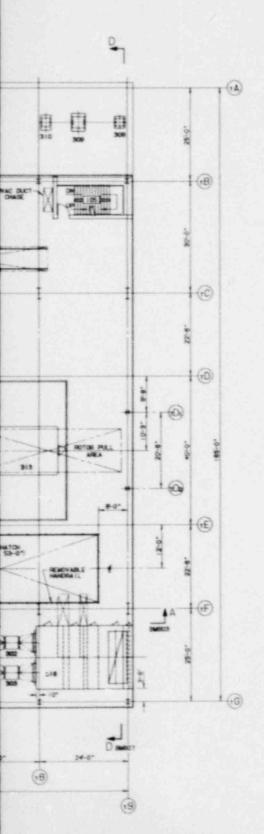




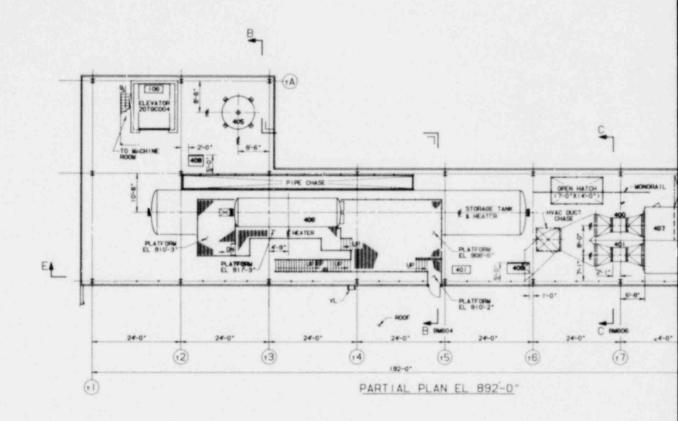
KEY PLAN

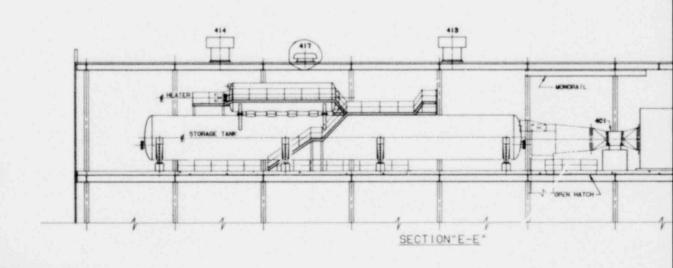
Figure 1.2-83
General Arrangement
Turbine Generator Building
Plan El. 862'-0"

1.2-94

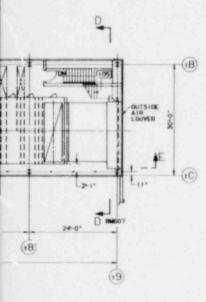


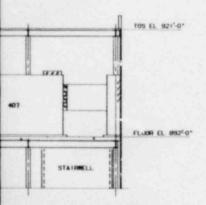






		EQUIPMENT LEGEND					
200	ZONE	EQUIPMENT MANEER	ØESCRIPTION				
400 401	94 94	25864141A 258641418	AIR HANDLING UNIT				
413	C8	2586A161A 2586A1818	EXHAUST FANS				
406	H7 66	710VT062 71F#4003	RELIEF HOOD FLASH TANK DEAERATOR HEATER AIR HANDLING UNIT				
408	H7	69AAB029	INSTRUMENT RACKS				





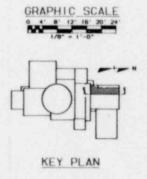
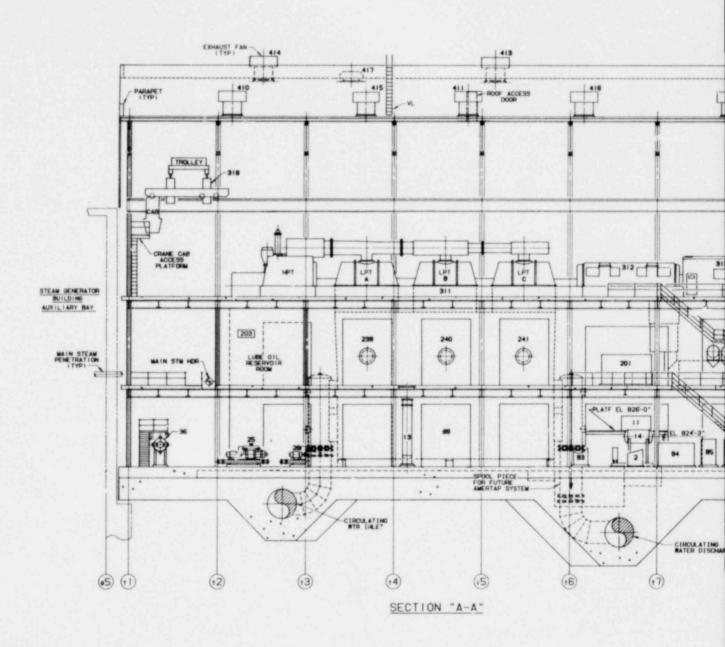
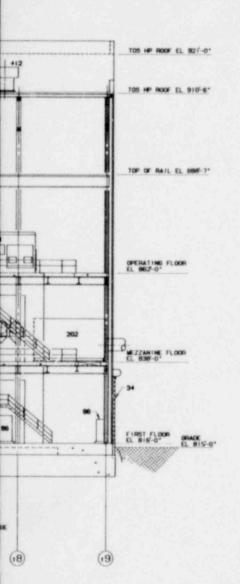
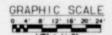


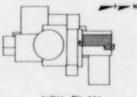
Figure 1.2-84
General Arrangement
Turbine Generator Building
Partial Plan and Section E-E





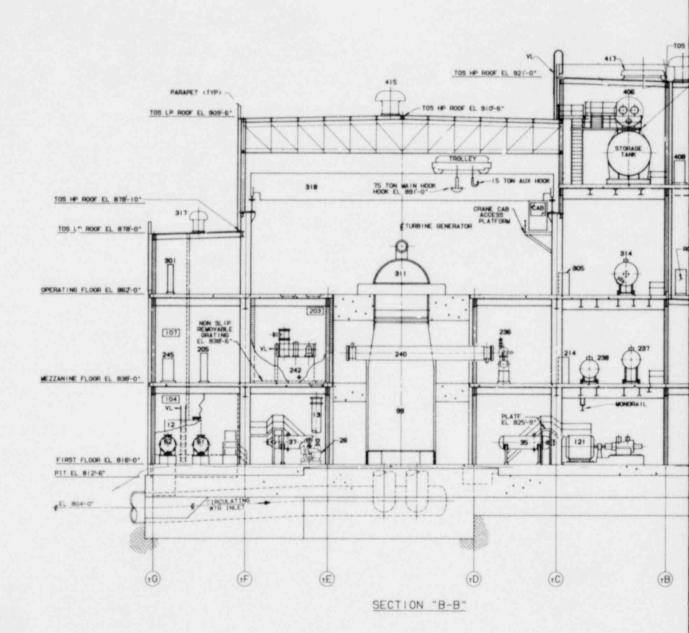
20	COME	EGJIPMENT N. MEER	DESCRIPTION
2	05	221AA0018	AIR DRYER
		2580A321 71CDH008	UNIT COOLER GRAIN COOLER
14	05	721AM003	HYDROGEN SEAL OIL SUPPLY UNIT
		79CEN 100A 73CEN 100B	
		2070C001 71FMH0079	ROLL-UP DOOR TOPPING HEATER
85 86 54 96	04 04 04 04	69AAB0060 69AAB0018 69AAB016 69AAB017	
90	UMO.	730#4001	COMENSES
201	ES	11AAE009	TURBINE GENERATOR GNE
202	E4	11AAE012	GENERATOR LOAD BREAK SWITCH
240	8.3	71CDH0068 71CDH0068 71CDH006C	LP FEEDMATER HEATERS
313	F4		TURBINE GENERATOR ALTERNATOR CRAME BRIDGE
412 413 414 415	格 格 格 H7	2586A261A 2586A261B 2586A261C 2586A161A 2586A161B 2586A161C 2586A161D	EXHAUST FAMS
	100	20004111	DEC LET WAYS





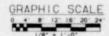
KEY PLAN

Figure 1.2-85
General Arrangement
Turbine Generator Building
Section A-A





REFERENCE DRAWINGS



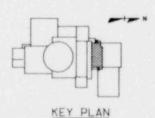
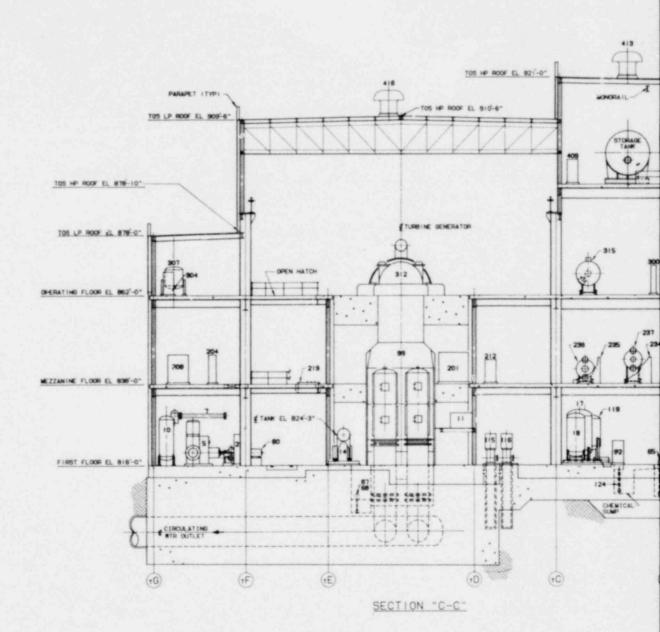


Figure 1.2-86
General Arrangement
Turbine Generator Building
Section B-B

1.2-97



ug g	3402	EQUIPMENT MANEER	DESCRIPTION
2	07	221AA0018	SERVICE & INSTRUMENT
5	5 07 225AA001C		SERVICE & INSTRUMENT
7	7 07 225AAG028		SERVICE & INSTRUMENT A
10	07	225AT0018	SERVICE & INSTRUMENT
11	EB	2586A321	UNIT COOLER
14	6.6	721AM003	HYDROGEN SEAL DIL
17	ES	71CP1002	CATION TANK
1.8	05	71CPT003	ANTON TANK
		75MJG003A 75MJG003B	CLARIFIER FILTERS
49			CLEARMELL
51	04	75MJ6005B 75MJ6006	MAKEUP DEMINERALIZER
60	07	755#P001B	SEC SYCE CL. CLO NTR PLA
65 66	D4	76#0P002A 76#0P002B	FLOOR DRAIN SLAP PLAPS
			CHEWICAL SUMP PUMP
88 D4 69AABO+3A 92 D5 69AABO+4A			INSTRUMENT RACKS
99			CONDENSER
	115 05 71C0P0018 116 05 71C0P001C 119 05 71CP1001C		CONDENSATE PLANPS
			CONDENSATE POLISHER
124	04	76#DP0050	CHEMICAL SUMP PUMP
201	66	11AAE009	TURBINE GEMERATOR GND XFMR & RESISTOR
		128PE006A 128PE022A	MOTOR CONTROL CENTER UNIT SUBSTATION
		69AAB004A	INSTRUMENT RACK
219		TIDYTOOL	ORAIN TANK
		128PE0018	SMITCHGEAR
237	ES	7100H004 7100H005	LP FEEDMATER HEATERS
- 30		7.00000	
300	F4	128FE 005A 258FB001B	MOTOR CONTROL CENTER INSTRUMENT RACK
307	F7	755#1001	SEC SVCE CL CLG MATER
312			GENERATOR
315			HP FEEDMATER HEATER
413	16	2586A161A 2586A161D	EXHAUST FANS
7.10			INSTRUMENT RACK

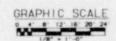
TOS LP ROOF EL 920'-4"2"

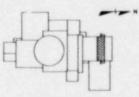
DEAERATOR FLOOR EL 892'-0"

(yA)

705 LP ROOF EL 860-7%

REFERENCE DRAWINGS

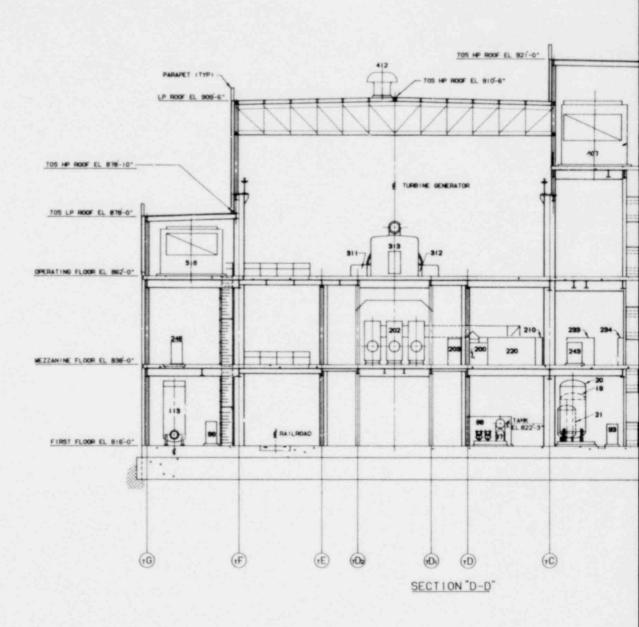


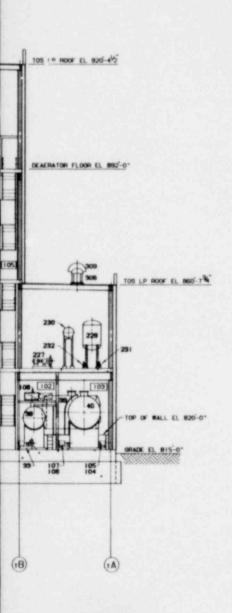


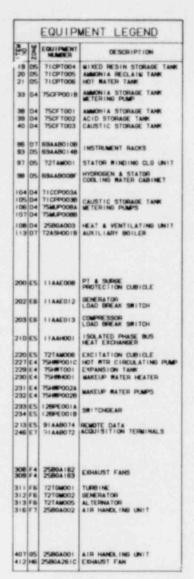
KEY PLAN

т.

Figure 1.2-87
General Arrangement
Turbine Generator Building
Section C-C









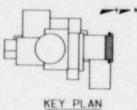
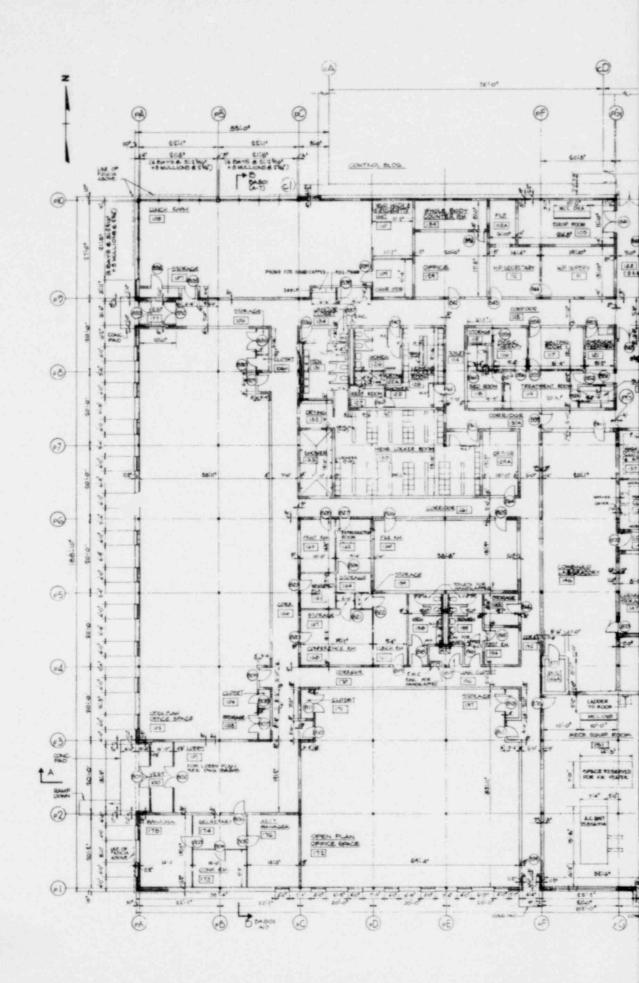
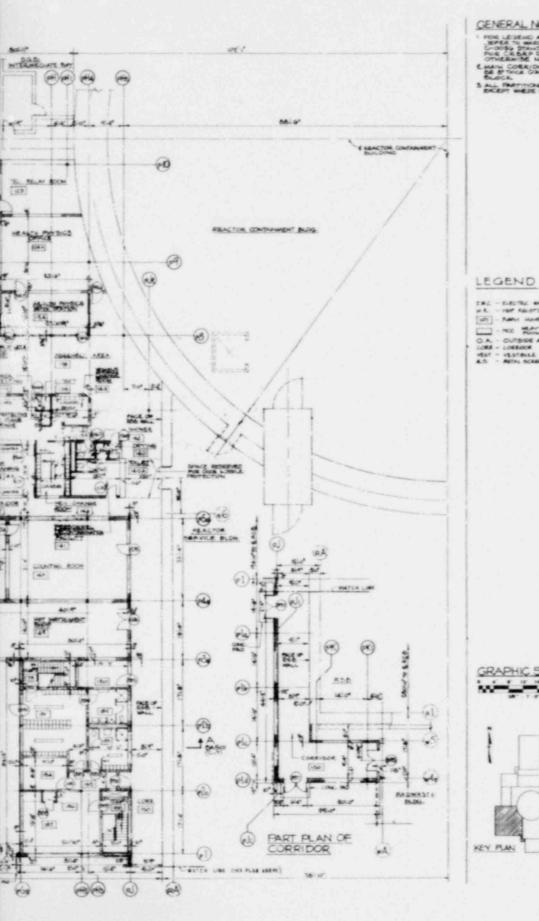


Figure 1.2-88
General Arrangement
Turbine Generator Building
Section D-D

1.2 - 99





GENERAL NOTES

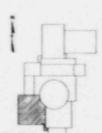
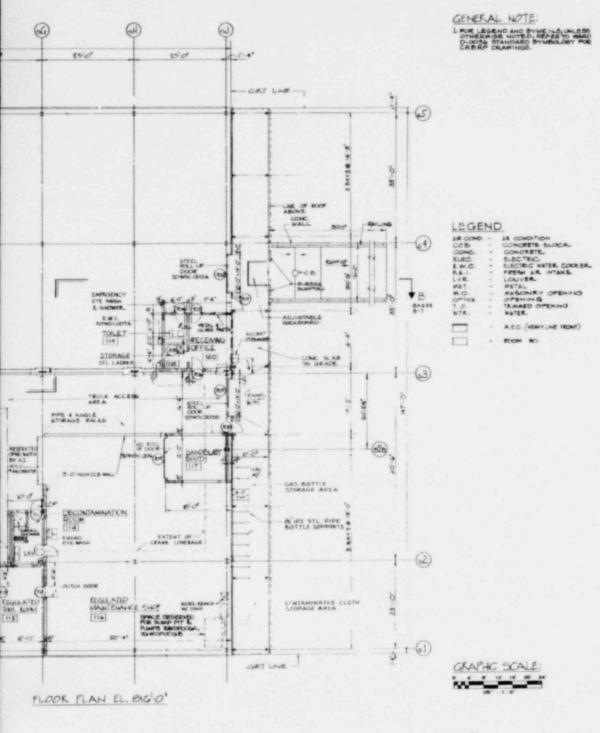


Figure 1.2-89 General Arrangement Plant Service Building Floor Plan El. 816'-0"

1.2-100



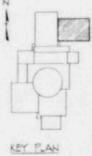
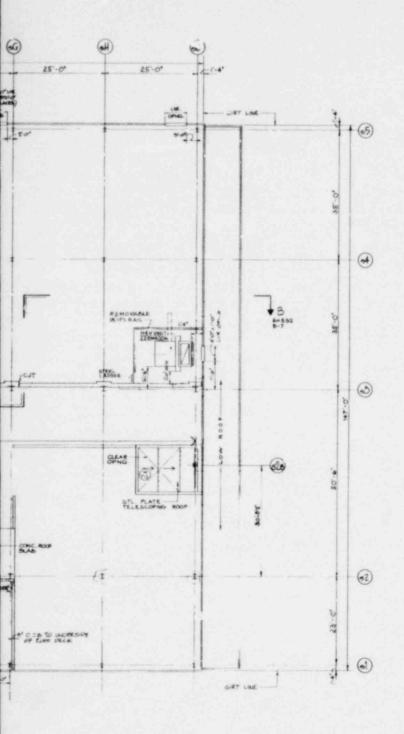


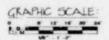
Figure 1.2-90 General Arrangement Maintenance Shop and Warehouse First Floor Plan El. 816'-0"

1.2-101

BA531-3



REFERENCE DRAWINGS



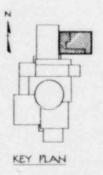
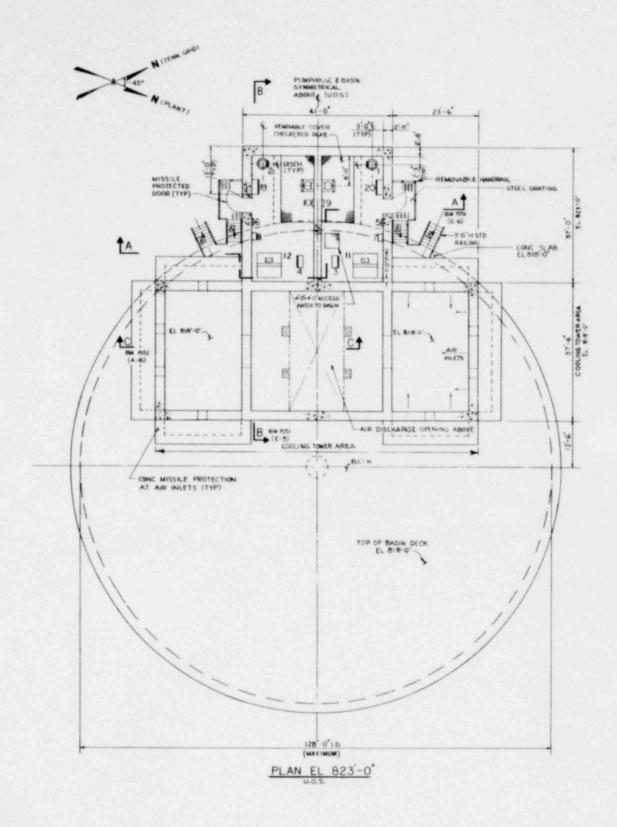


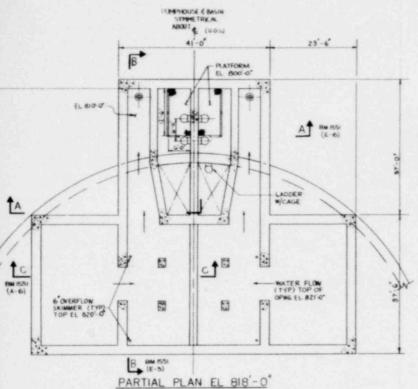
Figure 1.2-91
General Arrangement
Maintenance Shop and Warehouse
Mezzanine Plan El. 829'-0"

1.2-102





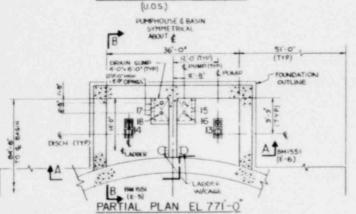
- I FOR LEGEND AND SYMBOLS, UNLESS OTHERWISE NOTED, REFER TO WARD DOCUMENT DOC D-0036 STANDARD SYMBOLOGY FOR CREEP DRAWINGS.
- 2 TEAVY LINE DENOTES



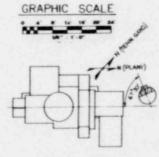
EMERGENCY COOLING TOWERS AND THEIR STRUCT SUPPC (TS., INCLUDING, AIR INTAKE MISSILE PROTECTION AIR ON HOLD & 20-000044 PENDING RECEIPT OF YENDOR. INFORMATION

REFERENCE DRAWINGS

BM 1551 GENERAL ARRANGEMENT EMER. COOLING TOWER PUMPHOUSE AND BASIN SECTIONS



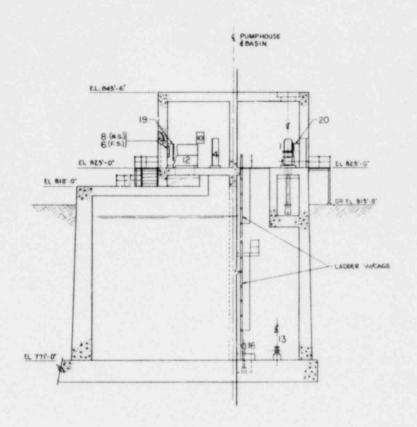
		EQUIP	MENT LEGEND				
NO.	ZONE	EQUIPMENT NUMBER	DESCRIPTION				
2	16	75EPP0018. 75EPP001A	EMER PLANT SYCE WIR PUMPS				
3	H6 H7	12 NIE OGOB 12 NIE OGOA	MOTOR CONTROL CENTERS				
5	H6 H7	12 NIB0398 12 NIB039A	LIGHTING PANELS				
7	146	12 MIX(1998) 12 MIX(199A)	TRANSFORMERS				
		12 NIBO40B	DISTRIBUTION PANELS				
11	H6 H7	25BEAROS 25BEAROSA	AIR HANDLING UNITS				
13	D3	75EPP003B 75EPP003A	EMER PLANT SICE WITH MAUP PHPS				
16	03	20ECPOORA 20ECPOORA 20ECPOORA 20ECPOORB	DRAIN SLAWP PUMPS				
19 20		69AAB033 69AAB034	INSTRUMENT RACKS				



KEY PLAN

Figure 1.2-92 General Arrangement Emergency Cooling Tower Pumphouse and Basin Plan

1.2-103



EL 853'-6"

EL 843-6 SECURITY BARG W/BIRDSCREEN

EL 823'-0

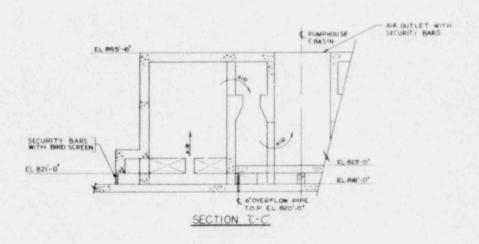
EL 818-0 GRADE EL 813-0 EL 810-0

(8) 3-0'4 4'-0" GRAVITY DAMPER

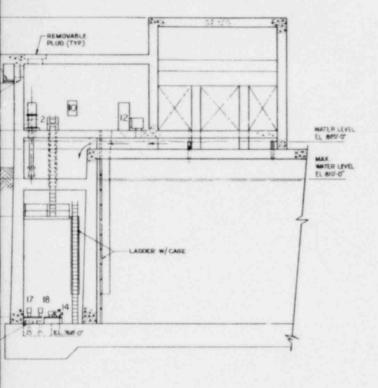
PLATFORM EL. 800'-0"

(2) I'x 2" OPENINGS IN SUMP PUMP PIER, (TYP)

SECTION 'A-A'



BM1551-1



SECTION 'B-B'

-	-						
NON	SONE	EQUIPMENT NUMBER	DESCRIPTION				
		75EPP001B 15EPF001A	EMERGENCY PLANT SERVICE WATER PUMPS				
4	н7	IZ NIE OLOA	MOTOR CONTROL CENTER				
6	нт	12 NIB039A	LIGHTING PANEL				
8	147	12 NEX 0.38A	TRANSFORMER				
10	116	12 NIBONGA	DISTRIBUTION PANEL				
12	H3 H6	25 BEADOA	AIR HANDLING UNIT				
		75EPP00818 75EPP008.A	EMERGENCY PLANT SERV.				
	F4	20ECP001A 20ECP001B	SUMP PUMPS				
	0.00	69AAB033 69AAB084	INSTRUMENT RACKS				

REFERENCE DRAWINGS

BM 1550 GENERAL ARRANGEMENT EMER. COOLING TOWER PLANPHOLDE AND RASIN PLAN

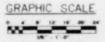


Figure 1.2-93
General Arrangement
Emergency Cooling Tower
Pumphouse and Basin Plan Sections

1.2-104

		CRBRP - 975 Mwt	FFTF - 400 Mwt	CRBRP PSAR Section
41	Fire Protection	Catch pans, oxygen suppression equipment, nitrogen flooding equipment, isolation devices.	Catch pans, oxygen suppression equipment, nitrogen flooding equipment, isolation devices, water prohibited from containment.	9.13
1.3- 11	Emergency Water Service	Provides water to systems essential for plant in safe shutdown condition, in event normal water distribution system is unavailable. Seismic design Category I cooling tower has 30-day supply of evaporative water.	No similar system.	9.9
56	Impurity Monitoring and Analysis	Provides for the sampling monitoring and analysis of sodium, NaK and argon cover gas systems in the plant and acceptance sampling and analysis of incoming sodium, NaK, argon, and nitrogen.	Same as CRBRP except that the argon cover gas sampling is an on-line subsystem.	9.8

TABLE 1.3-3 DETAILED COMPARISON BETWEEN CRBRP, FFTF, and MONJU

1	. Reactor Core	CRBRP - 975 Mwt	FFTF 400 Mwt	MONJU*- 714 Mwt	PSAR Section
	Number Assemblies				
51	Core Zone 1 Core Zone 2 Inner Blanket Radial Blanket Removable Radial Shield Primary Control Secondary Control Radial Reflector Core Barrel Inner Diameter (in.)	156 NA 82 132 306 9 6 NA 150	28 45 NA NA NA 3 6 108 140	108 88 NA 174 316 12 7	4.3
51	Active Core Ht. (in.) Active Core Equiv. Dia. (in.) Reactor Engineering Parameters	36 79.50	36 47 .23	35.4 70.08	
	Thermal Power Rating (mw) Gross Electrical Rating (mw) Gross Plant Efficiency (%) Maximum Power (% of Rated Power)	975 380 39 115	400 NA NA 115	714 300 42 116	4.3
Amend.	Maximum Clad Temp.; Hot Channel, 100% Rated Power, T & H Design Condition, Beginning of Assembly Life, (20, except where noted)	1350	1180 (600°F Rea Inlet Tem 1380 (800°F Rea Inlet Tem	ip.)	al)
51	*Notation "-" reflects data not availa "NA" = not applicable	ble.			

"NA" = not applicable

in these two figures coincides with the area of deepest weathering and lies about one-third of the way upslope from the topographic low towards the crest of the ridge to the northwest.

Water levels were measured at 33 of the observation wells shown in Figure 2.4-67 on a regular basis from December 19, 1973 through April 1, 1974. The water levels in some of the wells changed as much as 20 feet during the period of observation. The rainfall recorded at Melton Hill Dam (Reference 45), about six miles from the site, is shown in Figure 2.4-71. Watts Bar headwater levels during the same period are listed in Figure 2.4-72.

Water levels measured subsequent to the site investigation indicate fluctuations which comprise an annual cycle, with the maximum water levels occurring during the months of January and February, decreasing to low values recorded during the months of October and November. Water level fluctuations due to rainfall conditions are shown for fifteen selected wells in Figure 2.4-70a through 2.4-705.

The rapid response of the water levels to precipitation is indicative of rapid recharge, which occurs largely in areas of exposed rock and small sinkholes along the northwest and southeast ridges which bound the Plant Island. The large fluctuations in the groundwater table on the topographic highs and the quick response to precipitation are likely due to the proximity of these areas to recharge areas.

Eleven piezometers were installed in nests of twos and threes near borings 6, 7, 12, and 40 to supplement the information obtained from the observation wells described above. A typical piezometer installation is shown in Figure 2.4-73 and the locations of the piezometers are shown in Figure 2.4-74.

The water levels at the piezometers were also recorded at regular monthly intervals after the completion of the site investigation work until the suspension of the groundwater monitoring program. They were measured on a regular basis during the investigation from the beginning of February 1974 to April 1, 1974 and groundwater fluctuations in selected piezometers are plotted in Figures 2.4-75a through 2.4-75f. The piezometric head decreased with depth in the piezometers located on topographic highs, indicating downward flow and thus confirming that these areas are recharge areas. The piezometric head increase with depth in those piezometers located in the groundwater trough around boring 27. The upward piezometric gradient indicates that this is an area of upward flow and, thus, is a discharge area.

Amend. 56 Aug. 1980

2.4.13.2.3 Movement of Groundwater

In general, movement of groundwater occurs in a direction normal to the groundwater contours. At the site, movement is generally from topographically high areas to topographic lows; however, this pattern is modulated by the extent of weathering of the bedrock aquifers. Ultimately, the Clinch River acts as a sink to which all groundwater at the site migrates. Reference 33 lists instances in carbonate rock terraines in which weathering in topographically high areas is so deep that interchanges between adjacent valleys separated by these topographic highs may occur. Such situations are conducive to important reversals of groundwater flow. No evidence of such deep weathering action has been encountered at the site. Sound rock was encountered in the core of the ridges at elevations higher than the adjacent valley floors. Thus, at the site, the major ridges may be regarded as approximate locations of groundwater divides. Reversals in direction of flow which may occur because of the rather large fluctuations of the groundwater table will be local in extent and will not represent a diversion of groundwater from one major groundwater basin to another.

The Clinch River itself may act as a source of recharge during those periods when the river is subject to a rapid increase in stage. During such periods, water will flow from the river into the aquifer. This reverse flow will occur until a new condition of dynamic equilibrium within the groundwater system is established.

2.4.13.2.4 Effects of Plant Construction and Operation on Groundwater System

The groundwater environment at the site will be substantially changed by the construction of the Nuclear Island. The foundation of the Nuclear Island Structures is to be placed generally at elevation 715.

Excavation for the Nuclear Island foundation will be concurrent with dewatering. Due to the proximity of the

Amend. 55 June 1980

- Tornadoes tornado protection is provided by ensuring the integrity of the RCB and SGB.
- 3) Missiles missile protection is provided by ensuring the integrity of the RCB and SGB and the individual cells within the RCB and SGB.
- 4) Earthquakes protection from earthquake induced damage is promided by ensuring the structural adequacy of the RCB and SGB, the individual cells within the RCB and SGB, the components and the components supports of the IHTS.
- 5) Fires fire protection is provided by both the conventional fire protection system and the sodium fire protection system.

Criterion 33 INSPECTION AND SURVEILLANCE OF INTERMEDIATE COOLANT BOUNDARY

Components which are part of the intermediate coolant boundary shall be designed to permit (1) periodic inspection of areas and features important to safety, to assess their structural and leaktight integrity, and (2) appropriate material surveillance program for the intermediate coolant boundary. Means shall be provided for detecting intermediate coolant leakage.

Response:

33

A Liquid Metal-to-Gas Leak Detector System is provided to detect and identify the location of Liquid Metal-to-Gas leaks for the purpose of continuous surveillance of the intermediate system boundaries.

The major portion of the intermediate boundary is in readily accessible areas, facilitating in-service inspection by visual methods. An inservice inspection program for the IHTS will be implemented and conducted in accordance with the intent of the ASMF Boiler and Pressure Vessel Code, Section XI, Rules for Inservice Inspection of Nuclear Reactor Coolant System. The inservice inspection program will in ude all IHTS components such as pressure vessels, piping, pumps and valve.

To facilitate the inspection program, it is a design goal that all IHTS sodium welds be accessible for inspection after insulation and heater removal. Where necessary, hand held optical aids or remote devices such as periscopes will be used for inspection.

The need to monitor austenitic stainless steel oughness changes (due to carburization, plastic creep straining and the tremal environment) will be assessed as part of an ongoing program. These studie will be performed in parallel with design. If fracture toughness curveillance is determined, by ongoing programs, to be required, then the surveillance program will be designed in accord with the philosophy of Appendix H to CFR Part 50.

Criterion 34 REACTOR COOLANT AND COVER GAS PURITY CON ROL

Systems shall be provided to monitor and mai tain reactor and intermediate coolant and cover gas purity within spec fied design limits. These limits shall be based on consideration of (1) chemical attack, (2) fouling and plugging of passages and (3) radioisotone concentrations and (4) detection of sodium-water reactions.

Response:

Plugging temperature indicators are used to monitor the saturation temperature of the total impurities in the primary sodium, the EVST coolant, and the Intermediate Heat Transfer System (IHIS) sodium. Additionally, sodium samples are taken from these systems for laboratory analysis of sodium impurities. Gas impurity analysis is performed periodically on reactor, EVST, FHC and IHTS cover gas samples by the gas chromatograph in the Plant Service Building laboratory. These monitoring systems are described in Section 9.8.

TABLE 3.2-2 (Continued)

PRELIMINARY LIST OF SEISMIC CATEGORY I MECHANICAL SYSTEM

COMPONENTS AND ASSIGNED SAFETY CLASSES (3)

Components	Safety Class(1)	Quality Group(11)	Location ⁽²⁾	
Impurity Monitoring and Analysis System				
Primary Plugging Temperature Indi- cation Package	3	C	RCB	
Primary Sodium Sampling Package Ex-Vessel Plugging Temperature	3	Č	RCB	
Indication Package	3	С	RSB	
Ex-Vessel Sodium Sampling Package (2)	3	C	RSB	
IHTS Sodium Characterization Package (3)	3	C	SGB	

Preliminary Listing of Non-Seismic Category 1 Equipment in Containment

Compressed Air System (non-safety related)
Pump Seal Oil Control System
Primary Sodium Impurity Monitoring System - 1/4 T Hoist
Master-slave Manipulator

Primary Sodium Removal and Decontamination System Leak Detection (Liquid Metal-to-Gas) System Primary Cold Trap NaK Cooling System Refueling System - AHM

> IVTM Adapters Floor Valves Control Equipment

Electric Heating System - Control Panels Electrical System - Non-class IE Motor Control Centers Fire Protection System - Portable Equipment Area Panels

Radiation Monitoring System - Area Monitors HVAC System - Below floor air conditioning units Below floor return fan

HAA Heaters HAA Ducts

Communication System
Inservice Inspection Equipment
Maintenance Equipment and Supplies
Closure Head Plug Drive System
HAA Cable Handling Units and Personnel Platforms
Dip Seal Control Panel
DHDS - Remote Terminals
Delayed Neutron Detectors

TABLE 3.2-7

INVOKED RDT STANDARDS TO ASME CODE SECTION III COMPONENTS

	Standard Number, Revision	Standard 	Application
	E15-2NB, (NC, ND)T	Class 1, (2,3) Nuclear Components	All ASME Section III Components which perform liquid metal service with
	F9-4T	Requirements for Con- struction of Nuclear System Components at Elevated Temperatures	a Design Temperature above 800°F or other severe conditions
	F2-2	Quality Assurance Program Requirements	See PSAR Chapter 17
	F3-6T F6-5T	Nondestructive Examination	All ASME Section III Components which perform
54	F6-5T	Welding & Brazing Qualifica- tions	liquid metal service

upper shroud tube is attached to the intermediate rotating p ug and pilots over the lower shroud tube. The CRDM nozzle extension and seismic support structure are rigidly attached to the intermediate rotating plug.

The PCRS is included in the reactor system model in somewhat simplified form. The gap locations where the translating assembly is intended to be guided within surrounding components (i.e., CRDM bushings and absorber wear pads) are replaced by pin connections. Thus, for purposes of determining reactor system motions, we have a coupled model which includes both system and linearized subsystem. The stiffness and mass of the PCRS (and SCRS) are therefore included in the reactor system model. Note, however, that this linearized model cannot provide the detailed gap force data that is required from this analysis.

The detailed nonlinear PCRS model is decoupled from the reactor system model to make it practical economically to analyze both system and subsystem. The reactor system model is used for many time history and response spectrum cases for operating, refueling and preparation for refueling cases. However, the PCRS model need only be run for the few worst seconds of the horizontal seismic events and for the operating configuration of the reactor system model only.

The loads on and motions of the PCR system (supported system) occur as a result of the relative motions of the core, the upper internals structure and the intermediate rotating plug (not by any forces applied directly to the PCRS system). The nonlinear model of Figure 3.7-18A. uses displacement time history input at the six locations indicated by the arrows. These displacement inputs are obtained from the reactor system model. A careful interpolation (on time) is made between reactor system results to obtain a fine time increment needed for the PCRS model.

The direct results obtained from the impact analysis are histories of gap forces and displacements. Displacement results can be used directly to obtain component loads and/or stresses. The gap force histories, however, are the results of most interest. Special total impact force results are prepared from the individual gap results for use in subsequent scram analyses. A typical plot of the total force is shown in Figure 3.7-18B.See Section 4.2.3 for the detailed discussion of the seismic scram analysis.

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3.7.4 Seismic Instrumentation Program

3.7.4.1 Comparison With NRC Regulatory Guide 1.12

Seismic instrumentation will be provided to determine promptly the seismic response of the plant features important to safety to permit comparison of such response with that used as the design basis. Such a comparison is needed to decide whether the plant can continue to be operated safely.

The instrumentation to be provided is described in Section 3.7.4.2 below and meets the requirements of Regulatory Guide 1.12 for a Safe Shutdown Earthquake maximum foundation acceleration of 0.3g or greater.

3.7.4.2 Location and Description of Instrumentation

Preliminary information on seismic instrumentation for the CRBRP is summarized in the following. More detailed information on instrument locations, basis of the selection of the locations, the extent of planned utilization, etc. will be provided in the FSAR.

The seismic instrumentation as planned will consist of the following:

1. Triaxial Time - History Accelerograph

It will consist of four (4) strong motion triaxial sensors, one (1) triaxial seismic trigger, one (1) central recorder and control unit and one (1) tape playback unit.

The strong motion triaxial sensors will be installed at the following locations:

- a) "Free field" at a distance away from plant large enough to record the undisturbed free field motion.
- On the foundation mat of the Reactor Containment Building.

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TABLE 3A.1-3 (Continued)

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-	CELL (1)	TITLE	FLOOR ELEVATION	RADIATION OPERATION	ZONE (2) SHUTDOWN	DESIGN PRESS. (PSIG)	DESIGN (4) TEMP. (OF)	OPERATING TEMP. (F)	NORMAL (3) ATMOS.	EQUIPMENT CONTAINED
	104	Primary Na Makeup & Future Pump Cell	733*-0"	٧	IV	10	180	120	N	Primary Na LM Make- up Pump
	107A	Primary Na Makeup Pump Valve Gallery	733*-0"	V	٧	10	180	120	n	Primary Na IM Make- up Piping & Valves
	1078	Aux. LM Pipeway and Valve Gallery	733'-0"	٧	٧	10	180	120	N	Direct Heat Removal Service DHRS Cooler Sodium Piping & Valves
3A.	121	PHTS Loop #1 Cell **	75248"	V	V	10	180	120	N	Primary Na Pump & Guard Vessel, Inter- mediate Heat Exchanger & Guard Vessel, Cold Leg Check Valve, PHTS and IHTS Hot Leg & Cold Leg Sodium Piping
1-9a	122	PHTS Loop #2 Cell **	752'-8"	V	V	10	180	120	N	" Leg Souram
۵	123	PHIS Loop #3 Cell **	752'-8"	٧	V	10	180	120	N	
	131	Nak Cooling Equip. Cell	769*-0"	ш	III	10	180	120	N	Nak Storage lank, Nak EM Pump, Nak Cooler
56	132	Nak Sampling Cell	769* -0*	V	٧	10	180	120	н	Multipurpose Sample (MPS), MPS Valve Cabinet, Master Slave Manipulator, Sodium Piping, Radiation Shielding Window, Sodium Iransfer tunnel

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NO.	(1) TITLE	FLOOR ELEVATION	RADIATION OPERATION	ZONE (2) SHUTDOWN	DESICH PRESS. (PSIG)	DESIGN (4) TEMP. (OF)	OPERATING TEMP. (OF)	NORMAL ATMOS.	(3) EQUIPMENT CONTAINED
141	PTI Cell	783'-9"	٧	٧	10	180	120	N	Plugging Temp. Indi- cator (PTI) PTI Valve Cabinet
143	PTI Cell	792'-0"	V	V	10	180	120	N	
157A	Pri. Na (Id Trap Cell (A)	793'-0"	٧	V	10	180	120	N	Pri. Na Cold Traps
1578	Pri. Na (ald Trap Cell (B)	792'-9"	٧	٧	10	180	120	N	Pri. Na Cold Traps
1570	Cold Trap Valve Gallery	7921-9"	٧	IA	10	180	120	N	Cold Traps Piping & Valves
157E	Cold Trap Valve Gallery	792'-9"	V	IA	10	180	120	N	Cold Traps Piping & Valves

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NOTES: 1) Alph betical designations following cell nos. indicate sub-cells sharing a common atmosphere.

2) For definition of Radiation Zones see Table 12.1-1

3) N = Nitrogen

4) Liner Design Temperature

^{**} These cells shall have a design capability of surviving a one time high temperature sodium spill of $1050^{\circ}\mathrm{F}$.

3A.4.2.9 Auxiliary Liquid Metal

The Auxiliary Liquid Metal System provides the facilities for purification and cooling of the sodium in the ex-vessel storage tank (EVST). The EVST sodium storage is provided by the Primary Sodium Storage and Processing System of the Auxiliary Liquid Metal System. This is discussed in greater detail in Section 9.1, 9.3.

The maximum activity in the EVST sodium (i.e., after 30 years of plant operation and with no EVST cold trapping) is given in Table 12.1-23.

3A.4.2.10 Inert Gas Receiving and Processing

Sections 9.5 and 11.3 present details of this system. The radioactive inventory, by isotope, present in the various cells within the RSB are given in Table 12.1-12 through 12.1-18.

3A.4.2.11 Impurity Monitoring and Analysis

The Impurity Monitoring and Analysis System provides for the sampling monitoring, and analysis of sodium and cover gas impurities in the CRBRP systems. The system provides the following areas of impurity monitoring and sampling;

1) EVS cover gas sampling

- 2) Primary cover gas sampling
- 3) EVS sodium sampling

Section 9.8 presents more details of this system.

3A.4.2.12 Fuel Failure Monitoring

Section 7.5.4 presents details of this system. The isotopic gas activity in the sampling trap cell (gas tag analysis) and the cover gas monitor cell are presented in Table 12.1-20.

3A.4.3 Design Evaluation

The RSB is designed to house the various systems listed in Table 3A.4-1. Each of the systems containing radioactive fluids or components will be separately housed in their respective cells, that have thick concrete walls. These walls, in addition to providing radiation protection to operating personnel, will act as a confinement barrier. Accidents considered by the individual systems housed in the RSB are presented in Chapter 15.

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3A.4.4 Tests and Inspection

A CRBRP Quality Assurance Program is established to assure that critical structures are built in accordance with specifications. This program is described in Chapter 17.

Principal Materials Used in the RSB - Concrete, reinforcing steel, steel liner plates, and structural steel - are manufactured in accordance with nationally recognized standards. User installation tests and inspections are detailed in construction specifications.

Conventional methods will be used to inspect the cell liners. These methods may include:

- 1) Visual inspection of welds
- 2) Dye penetrant
- 3) Vacuum box

Tests and inspection will be performed during construction of the RSB structure, to verify conformance with construction specifications and applicable parts of building codes.

The tests and inspection of systems within the RSB are discussed in detail in those sections of this report pertaining to the individual systems housed by the RSB (see Table 3A.4-1).

3A.4.5 Instrumentation Requirements

The RSB will be sufficiently instrumented to provide for the safety of both operating personnel and the general public. This instrumentation will include such items as neutron counters for EVST and the FHC area, radiation detectors in all accessible areas, exhaust monitors for the H&V System, etc. The specific instrumentation requirements for the various systems in the RSB will be the joint responsibility of the functional system and its corresponding instrumentation system. These pairs of systems, together with a brief discussion of their instrumentation requirements, are given in other sections of this PSAR (see Table 3A.4-1). The responsibility of providing general radiation monitoring (i.e., not within the jurisdiction of any functional system) will be the Radiation Monitoring System. Section 12.2.4 of this PSAR presents the requirement for radiation monitoring in the RSB.

has an incubation period in which the swelling rate is low. During this time the fuel swelling generally closes the fabricated fuel-clad gap and generates a fuel-clad interaction stress. After the incubation period the increased clad swelling relieves the interaction stress. Under certain conditions, this increased cladding swelling results in re-opening the fuel clad gap. This has been observed experimentally with solution treated cladding in EBR-II.

The code used in the ongoing calculations of cladding loads is LIFE, Reference 175, (see Appendix A). LIFE was developed by Argonne National Laboratory as a fuel performance code with the capability of following the reactor power history. The magnitude and duration of the fuel-cladding mechanical contact are calculated with the LIFE code. LIFE has been adopted as the national fuel pin modeling code and is undergoing further development at ANL, W-ARD, HEDL, AI and GE. Limitations on the current version of the LIFE code (LIFE-III) and the methodology by which it is app ied to fuel and blanket rod analysis is discussed in Section 4.2.1.1.3.5.

Two types of rods were investigated for FCMI effects: those with the highest end-of-life damage due to fission gas loads, and those which experienced the highest percent increase in steady state power level between cycles. The first type of rods are the least capable of withstanding any additional loading of any variety. In the second type of rod, the power increase at middle-of-life could lead to FCMI due to fuel-cladding differential thermal expansion, particularly if previous conditions resulted in a closed fuel-cladding gap at the time of the power increase. For all rods, the axial locations which showed the most significant calculated FCMI loads were analyzed in detail for cladding damage. A corewide map of end-of-life cladding steady state CDF for the hot spot of the hot rod in each assembly is given and discussed in Section 4.2.1.3.1.2. The hot rod of radial blanket assembly 201, which experiences a 12% power jump between cycles 2 and 3, was chosen for investigation of power jump effects. In addition to experiencing a relatively high power jump, this rod also has one of the higher cladding CDF values at end-of-life.

Steady state FCMI loads were calculated for the hot rods of fuel assemblies 10 and 14, inner blanket assembly 67, and radial blanket assembly 201 (see Figure 4.2-10B). These rods were found to sustain the highest cladding damage due to fission gas pressure alone (see Section 4.2.1.3.1.2.1 below). Between cycles, a 10 hour drop to zero power followed by a 10 hour rise to full power was assumed. The FCMI pressure values calculated by LIFE III for the fuel rods were adjusted to account for the greater cladding wastage which is assumed in the CRBR for design evaluations. 51 For example, in the LIFE III calculations, the initial cladding thickness

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The recults of these calculations are shown in Figures 4.2-17A, 4.2-17B, 4.2-17C and 4.2-17D. These figures are plots of total internal cladding pressure (plenum gas pressure + FCMI pressure) at the three cladding axial locations under consideration. The straight line pressure histories are due to plenum gas pressure only while the non-linear portions of these pressure history plots indicate the occurrence of FCMI loading.

The effects of the mid-life power increase on FCMI in the hot rods of radial blanket assembly 201 was investigated with the LIFE-III code by varying the power ramp rate at the beginning of the third cycle. For this study, three third cycle startup programs were considered:

- Normal startup (3 loop operation)
- Fast startup (3% min.)
- Programmed startup

The three startup procedures used in the analysis are shown in Figure 4.2-16. The fast startup was based on the maximum possible ramp rate achievable in the reactor, i.e., 3% per minute. The programmed start-up was based on an earlier fuel pin power-to-melt uncertainty analysis for CRBR (Section 4.4).

Figure 4.2-24 shows the maximum calculated FCMI loads during the third cycle startup for the three startup schemes described above. This figure demonstrates that the FCMI loading calculated by LIFE III due to mid-life power increases in radial blanket rods can be significantly altered by varying the rates at which these rods are brought up to power at the beginning of the cycle when the power increase occurs. The effects of these cladding loadings on rod lifetime, and the overall conclusions derived from these calculations are discussed in Section 4.2.1.3.1.2.

Based upon experience with FFTF and EBR-II fuel assembly design, the following mechanisms were expected to be of secondary importance with respect to cladding damage in CRBRP but important to overall fuel and blanket rod performance.

From the data of Figure 4.2-27, the hot rods of outer blanket assembly 201, and inner blanket assembly 67 were calculated to have the highest end-of-life CDF values at the hot spot for each blanket type. These rods were analyzed for transient effects at the hot spot using the methods and assumptions previously described for the fuel rods. The results of these analyses are shown in Figure 4.2-28A and 4.2-28B. These results show that these blanket rods achieve the goal life with the transient limit curves at end-of-life lying above the peak transient cladding hot spot temperature. The cladding hot spot transient temperature margins at end-of-life for the other blanket rods are greater than the hot spot margins for the hot rods of assemblies 201 and 67.

As noted in Section 4.2.1.1, the LIFE III code has not been calibrated for blanket rods. However, the magnitude of the calculated blanket rod FCMI loads as a function of rod power, temperature, etc., correlate well with the calculated fuel rod FCMI dependence on these parameters. This indicates the LIFE III models are mathematically capable of predicting blanket rod FCMI results. To compensate for the uncertainty in blanket rod FCMI magnitude due to lack of specific calibrations, the blanket rod wastage was assumed to equal the conservative design cladding wastage. This resulted in conservative calculated FCMI stresses.

The effects of these calculated steady state FCMI loads and the transient duty cycle on cladding lifetime at axial locations $\rm X/L=0.46$ and 0.62 were determined for the hot rods of outer blanket assembly 201 and inner blanket assembly 67. The cladding temperature assumptions and transient limit curve techniques utilized for these blanket rods are identical to those utilized for the fuel rods. The total cladding internal pressures are shown in Figures 4.2-17C and 4.2-17D for the axial locations considered. These calculations predict that at end-of-life, the steady state and transient CDF margins at these axial locations on both blanket rods exceed the CDF margins at the hot spot location.

Mid-Life Power Increase Effects

As noted in Section 4.2.1.1, the LIFE III code has not been calibrated to calculate the magnitude of FCMI loads for this type of environment change. However, the code models are capable of predicting the qualitative physical relation between FCMI and power change rate over the periods of time typical of reactor startup. Thus, for this study, blanket rod cladding performance with these startup programs at the beginning of the third cycle were calculated and compared. These startup programs were described in detail in Section 4.2.1.3.1.1.

The cladding CDF due to the most severe startup loading (100% power at 3% per minute) was calculated with the FURFAN code. Results of these analyses are shown in Table 4.2-10. Steady state CDF values are shown for 878 EFPD (4 cycles of operation) with and without accounting for the power jump. Comparison of the results shows that even in the worst case the mid-life power jump, per se, has no significant deleterious effect on the steady state performance capability (CDF) of the blanket rod.

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4.2.1.3.1.2.2 Cladding Ductility Limited Strain

The FRST computer code (see Appendix A) was used to calculate fuel rod cladding ductility limited strain versus time. This code provides a means of calculating effects of time-varying cladding temperature, plenum pressure, cladding wastage, and fuel-cladding contact pressure on the cladding ductility limited strain as defined in Section 4.2.1.1.2.2. This is done by utilizing the cladding thermal and pressure loads which equal or envelope those of Section 4.4 in the solution annealed 316 SS thermal creep equation, referenced in Section 4.2.1.1. Cladding wastage and steady state fuel-cladding contact pressure effects are considered in the cladding load calculations. Irradiation creep and swelling strains are also calculated by FRST using the 20% cold worked 316 SS models. The FRST calculational procedure has been verified against both hand calculations and MINIGRO code results.

For conservatism, the FRST computer code used the material modeling assumptions presented in Section 4.2.1.1; all pertinent initial environmental conditions considered for the fuel rod cladding strain calculations are also described or referenced in this section.

A sub-routine to the FRST code which calculates the cladding plastic strain increment and thermal creep strain rate during the transient, was used to determine the effects of transients on cladding strain accumulation. For the cladding material, the solution annealed 316 SS thermal creep strain relation, specified in Section 4.2.1.1, and the stress-strain relationship given in Figure 15.1.2-22, were assumed. Fission gas plenum pressure and FCMI at the time of transient occurrence is input to this sub-routine from the steady state analysis results. During a given transient, the sub-routine adjusts this pressure to reflect increased fission gas pressure, transient fuel-cladding differential expansion, and the time varying cladding temperature. During the transient, the code calculates the cladding stress, and utilizes this stress and the cladding temperature in the solution annealed 316 SS thermal creep equation to calculate the cladding strain rate due to the transient. Whenever the cladding stress exceeds the material proportional elastic limit given by the stress-strain-temperature relation of Figure 15.1.2-22, the code uses the mathematical equation of this relation to calculate cladding plastic strain, and this value is added to the plastic strain to obtain the total cladding transient ductility limited strain. This technique, which is the same as used for FFTF, is described and verified in References 57 and 173.

A minimum beginning-of-life cladding thickness of 0.0135 inches was assumed, which allows for design tolerances and defect allowances. The cladding material wastage rates and mechanical properties are discussed in Section 4.2.1.2. The pertinent initial conditions used for these calculations were previously described in this section.

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is not fed back directly to the reactor control system, the operator utilizes the position data to evaluate the plant and to interpret reproducibility of reactivity control. The relative position indication accuracy of ±0.1 inch leads to reactivity reproducibility of approximately 1¢ for the highest worth rod in the primary system. In addition, the position indication is utilized for logic interlocks and alarm as described in Section 7.7.1.3.

4.2.3.1.5 Structural Requirements

Control Rod Drive Mechanisms

The primary and secondary control rod drive mechanisms are designed to the following classes of components:

- 1. ASME Boiler and Pressure Vessel Code, Section III, 1974 edition, Class 1. For the primary control rod system, the mechanism motor tube, motor tube hold-down ring, nozzle extensions and position indicator housing form a part of the pressure retaining boundary. For the secondary control rod system, the extension nozzle, the hold-down ring, the upper portion of the mechanism housing, and the connector plate form a portion of the pressure retaining boundary.
- Seismic Category I. The control rod systems are required to remain functional and shutdown the reactor in the event of an SSE. (See Section 3.2.1 for detailed discussion).
- Safety Class I. The control rod systems are categorized as Class I because of their control and shutdown functions. (See Section 3.2.2 for detailed discussion).

The primary control rod drive mechanisms shall be designed to the load conditions of Table 4.2-37. For these loading conditions, pressure boundary components shall meet the structural requirements of Section III of the ASME Pressure Vessel Code together with applicable code cases and amendments to the code by RDT Standards. The portion of the Secondary Control Rod System that is coded in accordance with the ASME B&PV code and hence forms a part of the pressure retaining boundary shall be designed to the load conditions of Table 4.2-37. The structural requirements of Section III of the ASME Pressure Vessel Code together with applicable code cases and amendments to the code by RDT Standards shall be met.

The governing stresses in the mechanism are the time independent effects of primary mechanical loads, secondary thermal loads and fatigue. Use of the methods of these codes together with consideration

of material effects such as carbon and nitrogen depletion, thermal aging, and environmental correction factors to account for material interaction with sodium leads to conservative structural designs of the mechanisms.

The primary and secondary control rod drive mechanisms shall have a design life of 30 years. This lifetime is consistent with the design lifetime of the reactor. Sufficient shielding shall be provided where appropriate to assure adequate strength to meet the structural criteria over the required lifetime. Interim maintenance will be required in order to achieve this lifetime.

The PCRDM and SCRDM shall remain structurally intact and attached to the reactor vessel, and shall not permit sodium leakage under Structural Margin Beyond the Design Base conditions. (See Reference 10a, Section 1.6). This requirement provides added margin of safety for an event for which no causative mechanism is known.

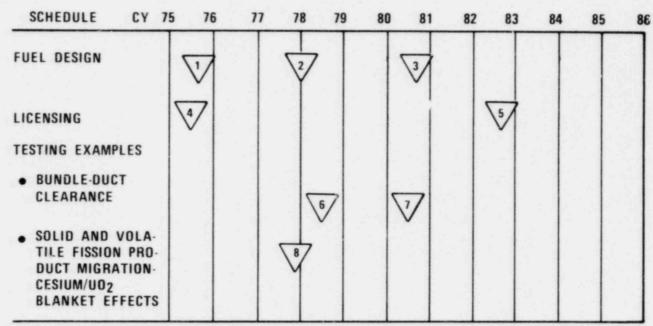
The PCRDM and SCRDM shall be designed such that no mechanical failure can result in any parts becoming missiles.

Control Rod Driveline

The primary control rod driveline (PCRD) and the secondary control rod driveline (SCRD) shall meet the intent of the structural requirements of Section III, ASME Pressure Vessel Code, together with applicable Code Cases (1592), and amendments by applicable RDT Standards. The stress and stability criteria for evaluation of the design shall be as specified in the above codes for all significant loading conditions including those identified in Table 4.2-37. Material physical property changes due to irradiation, thermal, and sodium environments shall be considered in evaluating the design.

The ASME Code specifies conservative allowable stresses for various loads and combinations of loads. The compressive load limit shall be no greater than 1/3 the buckling stability load of the driveline, and the design stress intensity limit shall be the lower of 1/3 ultimate or 2/3 yield stress. Satisfaction of the criteria assures that conservative margins exist for all conceivable loads including rod ejection for which no causative mechanism is known.

The design lifetimes of the primary and secondary drivelines shall be as shown in Table 4.2-38. The design lifetime requirements are conservative with regard to material considerations, taking into account the irradiation environments of these components (Table 4.2-39).



FALLBACK EXAMPLES

- BUNDLE-DUCT INTERACTION CHANGE THE INITIAL POROSITY BY SMALL CHANGES IN WIRE WRAP DIAMETER AND/OR SELECTIVE ASSEMBLY
- CESIUM/UO2 BKT. EFFECTS FOR THE FIRST SEVERAL AXIAL BLANKET PELLETS AT EACH END, INCREASE THE DIAMETRAL GAP.

LEGEND:

PRELIMINARY DESIGN REVIEW

PSAR SUBMITTAL

PRELIMINARY DESIGN REVIEW

PSAR SUBMITTAL

PSAR SUB

Figure 4.2-35A Design Fallback Positions

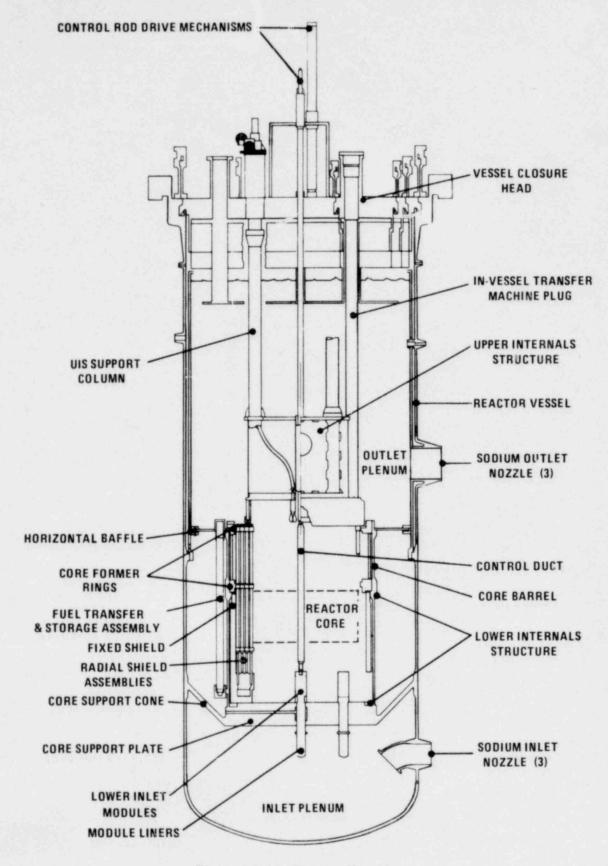


Figure 4.2-36. Reactor Elevation

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where

$$A_{1} = \frac{1}{\beta} \sum_{i=1}^{M} \left[c_{i}'(t_{1}) - c_{i}'(t_{0}) \right]$$

$$A_{2} = \frac{1}{\beta} \sum_{i=1}^{M} \left[c_{i}'(t_{2}) - c_{i}'(t_{1}) \right]$$

$$B_{1} = \int_{t_{0}}^{t_{1}} CR(t) dt$$

$$B_2 = \int_{t_1}^{t_2} CR(t)dt$$

$$\Delta t_1 = t_1 - t_0$$

$$\Delta t_2 = t_2 - t_1$$

$$c_i(t) = \frac{W c_i(t)}{v}$$

 t_0 = a time slightly greater than t_s ; $t_0 - t_s \stackrel{\sim}{=} 0.5$ seconds.

 t_1 = a time greater than t which occurs while the count rate transient is still decaying; t_1 - t_s \cong 25 seconds.

 t_2 = a time near the end of the transient when the reactor is approaching its final steady-state condition; t_2 - t_e = 240 seconds.

The initial reactivity state p_0 is calculated by solving Equations (8) and (9) at steady-state, or

$$\rho_0 = -\frac{WS}{v CR(0)}$$
 (12)

Substituting Equation (11) into Equation (12) we have

$$\rho \circ = -\left(\frac{B_1 A_2 - B_2 A_1}{B_1 \Delta t_2 - B_2 \Delta t_1}\right) \left(\frac{\beta}{CR(0)}\right)$$
 (13)

Equations (10) and (13) are evaluated for the final, and initial subcritical reactivity states, respectively. The values for $C_1^{-1}(t)$ are based on a recursive solution of Equation (9); see Reference 3 for details.

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A study has been performed to assess the uncertainty in control rod worth as inferred from IKRD experiments due to the statistical uncertainty inherent in the observed count rate of the detector (Reference 4). The IKRD experiments were performed by ORNL personnel at the Southwest Experimental Fast Oxide Reactor. Two analytical methods were applied to the results from these experiments. First, a propagation of error analysis technique was applied to three-point IKRD subcritical measurements. The second verification method was an error analysis based on repeated roddrops which were simulated from observed count rate vs. time data. In both cases, the assumption was made that the uncertainty in the reactivity estimate was due solely to the detection process itself. The reactivity uncertainties for various experimental rod-drop data sets were computed by both of these methods and the results were in good agreement. Both techniques yielded errors of approximately 0.6% in the initial and final reactivity states when control rods worth 1 to 2 dollars were inserted from a near critical state.

Additional analyses have been performed to determine the uncertainty in control rod worth as inferred from the IKRD technique which results from the uncertainty in the kinetics parameters β_i and λ_i (Reference 3). These analyses were based on rod-drop experiments performed on the Fast Flux Test Facility-Engineering Mockup Critical loaded into ZPR-9 at ANL. For this configuration, the uncertainty in the final reactivity measurement is 1.8% due to uncertainties in β , and 0.6% due to uncertainties in λ . Similarly, the determination of the initial reactivity state is uncertain by as much as 3.0% due to uncertainties in β_i and as much as 2.0% due to uncertainties in λ_i . Adding together the β_i and λ_i related uncertainties and statistically combining the result with the 0.6% detector count rate uncertainty yields the following: the minimum uncertainty associated with the determination of the final reactivity state is 2.5%, and the minimum uncertainty associated with the determination of the initial reactivity state is 5.1% (minimum = theoretical, no systematic error included).

The precision of the IKRD technique depends to a large extent on systematic uncertainties, i.e., the ability to reproduce the same initial reactor conditions when a rod-drop experiment is to be repeated. Reference 4 discusses a particular rod-drop experiment that was repeated four times in SEFOR under nearly identical reactor conditions. The standard deviation (one o error) for the control rod worth, which is based on the difference between ρ_f and ρ_o , is approximately 0.7%.

During refueling, the SRFM must provide a warning to the operator and thereby assure that the reactor does not approach criticality any closer than that level from which criticality could be attained by a single refueling error with adequate margin for the associated uncertainties. The uncertainties associated with the subcritical reactivity monitoring technique fall into three categories: (1) the uncertainty in the calcu-51 | lated reactivity worth of the single worst refueling error, (2) the

buildup, 2) the mid-term row 6 refueling, and 3) control rod bank with-drawal effects. Equivalent Doppler constants at the beginning-of-cycle one and at the end-of-cycle four in a sodium-voided environment are shown in Table 4.3-17. The effect of the removal of sodium is to harden the neutron energy spectrum and substantially reduce the magnitude of the Doppler constants.

Table 4.3-18 presents a typical nodal-average Doppler distribution in the fuel, inner, and radial blankets at the beginning-of-cycle one. Each region contains a total of seven axial nodes; five equal-volume nodes in the 36-inch high "fuel" region and one node each in the upper and lower blankets (extensions). The row 1 and row 2 radial blanket Doppler constants have been combined additively into a single region. This combination results in a slightly conservative (less negative) feedback reactivity due to temperature differences in the two rows of radial blankets.

Figures 4.3-27a and b show the distribution of Doppler constant by assembly in the 36-inch active fuel and inner blankets at the beginning of cycle one and the end of cycle four, respectively. The values in Figures 4.3-27a and b are condensed from three-dimensional (VENTURE) first-order perturbation theory calculations which were used to develop nodal feedback coefficient input to SAS analyses (see Chapter 15).

The temperature dependence of the Doppler constant is discussed in Reference 5. The Doppler contribution of the fissile material is a small positive effect, and generally follows a $T^{-3/2}$ dependence. However, the U-238 contribution is strongly negative and overrides the small positive contribution from the fissile nuclides. Calculations of the temperature dependence for a series of U-238 resonances result in a Doppler temperature relationship of T^{-1} . Self-shielding effects will tend to decrease the absolute value of the temperature exponent, but for a fast reactor having a fertile/fissile content similar to CRBRP, the overall Doppler constant has approximately a T^{-1} variation.

The temperature dependence of the Doppler reactivity constant for CRBRP has been examined parametrically for a homogeneous core configuration using FX-2. The code system used for generation of cross sections is verified in Reference 6 and applied to the CRBRP model as explained in Reference 7. FX-2 utilizes a three-term temperature-dependence formula cross section curve fit (in terms of $T^{-\frac{1}{2}}$, $T^{-\frac{1}{4}}$, and $T^{-\frac{1}{2}}$) to four points generated over the temperature range of interest from a theoretical basis taking into account core design heterogeneity and self-shielding. Using FX-2, the Doppler reactivity effect in changing the core temperature uniformly from 1000° K to other temperatures is tabulated in Table 4.3-19. A comparisor is then made with a $T^{-\frac{1}{4}}$ extrapolation of the reactivity effect be ween 300° K and 1000° K. This comparison shows that the more detailed emperature dependence in FX-2 agrees well with the simple $T^{-\frac{1}{4}}$ dependence. The maximum final average temperatures do not exceed 4800° K.

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At higher temperatures than those present in Table 4.3-19, other uncertainties make the comparison less meaningful. In SAS and VENUS calculations, the variations in Doppler associated with different postulated scenarios are large compared to the uncertainties associated with the temperature dependence of the Doppler constant. For example, in Section 4.4 of Reference 7 a \$100/sec ramp rate was input to VENUS ir a fully voided core. This condition corresponded to a Doppler constant of -0.00297. The resulting core average temperature at disassembly was 4802°K. A second case assumed some sodium remained in the core based on a somewhat different scenario. In this case, the effective Doppler constant was -0.00379, and the resulting core average temperature at disassembly was 4533°K. Consequently, large variations in Doppler have already been considered by considering different scenarios and the uncertainty in the Doppler temperature dependence is well within these other variations.

Doppler Uncertainty:

The uncertainty in the CRBRP Doppler Constant has been developed from the analysis of the SEFOR Core I and II experiments. The Southwest Experimental Fast Oxide Reactor (SEFOR) was constructed specifically to determine the LMFBR Core Doppler feedback through a series of power coefficient (¢/MWth) and sub- and super-prompt transient energy coefficient (¢/MWth.sec) measurements. SEFOR Core II had a material composition, resultant neutron energy spectrum and fuel temperature that was reasonably characteristic of that in CRBRP. The SEFOR experiments are described in, for example, Reference 8. The SEFOR Core II Doppler constant derived from these measurements (T dk/dT = -0.0060) is in good agreement with the value of -0.0062 calculated by GE in Reference 9. GE estimated the SEFOR Doppler constant uncertainty as + 9% (10 equivalent) in Reference 9. The principal contributions to this value, other than the direct measurement uncertainties themselves, are estimated uncertainties in the fuel temperature-power relationships (fuel to coolant thermal conductance and fuel specific heat) required to extract the Doppler constant, -T dk/dT, from the measured power and energy coefficients (¢/MWth and of the SEFOR power and energy coefficients to LMFBR power readtors are attributable to effects which are significantly different between the two reactors (uncertainties in fuel thermal properties, delayed neutron data, and the like are highly correlated between SEFOR and power reactors so that these uncertainties largely cancel in the normalization). The net extrapolated uncertainty in LMFBR power or energy coefficient was determined to be + 11% (10) in Reference 9. This extrapolation accounted for differences in the SEFOR and LMFBR core composition and spectrum, fuel thermal property differences, and spatial temperature and importance weighting uncertainties. The neglect of spatial temperature and importance weighting (that is, the use of region Doppler constants with average fuel temperatures) tends to (conservatively) underestimate

magnitude of the changes in sodium density reactivity with burnup are similar to those in the sodium void worth in Table 4.3-20. The uncertainty in the sodium density reactivity coefficient is taken to be the same as the sodium void worth uncertainty.

4.3.2.3.4 Expansion and Bowing Reactivity Coefficients

Physical changes in the overall reactor configuration will result in corresponding reactivity perturbations. The reactivity coefficients discussed in this section are: (1) uniform axial fuel expansion (fuel surface temperature dependent), (2) uniform radial core expansion (inlet coolant temperature dependent), and (3) relative radial motion of fuel assemblies (bowing) resulting from a combination of temperature gradients and long-term swelling, the latter being highly dependent on irradiation history.

a. Uniform Axial Expansion Coefficient

The axial expansion coefficient defines the relationship between reactivity and changes in the length of the active core (fuel pellet stack height). It should be noted that the axial expansion is assumed to be dependent on the temperature at the radial surface (shoulder) of the dished fuel pellets. Implicit in this definition of the uniform axial expansion coefficient is the assumption of free movement of the fuel pellets within the clad tubes. This assumption tends to yield the largest (magnitude) coefficient insofar as degradation of the fuel pellets under irradiation will significantly reduce the magnitude of this coefficient. This effect was noted in the RAPSODIE reactor (Ref. 13).

The reactivity feedback due to core axial expansion or contraction consists of worth components from fuel and blanket expansion, stainless steel expansion, and another component for relative core/ control rod motion. The fuel and steel expansion worths are determined from a perturbation technique whereby the axial expansion worth is taken to be the difference between the uniform material worth over the 36-inch active core and the material worth at the core/axial blanket boundaries. These material worth distributions are determined from a firs+-order perturbation theory calculation in RZ geometry. Table 4.3-22 shows the distribution of the pellet and steel components of the uniform axial expansion coefficient (t/mil of uniform expansion) in the fuel and blankets by radial "row" throughout the core at the beginning-of-cycle one and at the end-of-cycle four. Axial expansion of the fuel lowers the core density and removes reactivity from the system. The higher beginning of life fuel enrichment, and hence the relatively high fuel worth, results in a larger fuel expansion worth in the fresh core at the beginning-of-cycle

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one than in the burned core at the end-of-cycle four. Expansion of the blankets removes absorber from the core and thereby slightly increases reactivity, except in the case of the radial blankets where the predominant effect is to lower the reflective (scattering) worth of the blanket material. Expansion of either the fuel or inner blanket steel again removes absorber from the core and increases reactivity. In addition to the direct core expansion reactivity, there is an added effect of net movement of the core with respect to the partly inserted control rods.

The axial expansion coefficients in Table 4.3-22 can be converted to \$\epsilon F using linearized material thermal expansion coefficients for fresh fuel pellet material (0..81 mils/0F) and for unirradiated stainless steel (0.425 mils/OF). However, these material expansion coefficients are expected to be a function of accumulated burnup and fluence. In the case of fuel pellet material, the mechanism of thermal expansion may vary substantially from the fresh unirradiated behavior due to pellet cracking. Consequently, the fuel expansion reactivity feedback can vary from a minimum of zero to the value calculated assuming free movement of the fuel column and thermal expansion driven by the pellet surface temperature. For this reason, fuel expansion negative reactivity feedback is generally not included in transient evaluations. At the other extreme, complete pellet-clad sticking could result in the fuel column growing axially according to the cladding temperature change. In this case, due to the higher thermal expansion coefficient for the steel cladding, the thermal growth of the fuel column in the startup transition from refueling temperature conditions to hot full power would increase approximately 20% (10¢ additional power defect) compared to the case of freemoving pellets. However, such global pellet-clad contact is unlikely to occur throughout the entire startup temperature transition, especially in fresh fuel where the axial expansion reactivity coefficients in Table 4.3-22 are highest. Therefore, pellet-clad sticking is not considered in the determination of the cold-to-hot temperature defect.

b. Uniform Radial Expansion Coefficient

The uniform radial expansion coefficient defines the relationship between reactivity and changes in the effective (equivalent circular) radius of the core (fuel/radial blanket boundary). The uniform radial expansion coefficient is dependent upon the change in dimensions of the lower core support structure which in turn depends on the inlet coolant temperature. This definition is convenient from a calculational standpoint since the detailed mechanical motion of the fuel and inner blanket assemblies need not be known (this detailed mechanical motion is subsequently

included in the bowing reactivity component). During the heat-up period between refueling and hot-standby temperature, the core is essentially isothermal and the uniform radial expansion coefficient is applicable.

Calculations of the uniform radial xpansion coefficient for the CRBRP were performed in hexagonal geometry using the diffusion theory code 2DB with 9 energy groups. The pitch of all fuel, inner and radial blankets, primary and secondary control rods and removable radial shield assemblies is increased uniformly while at the same time the masses of structural and fuel materials are held constant. The mass of sodium necessarily increases in the expanded core. This calculational technique for the uniform radial expansion coefficient duplicates the results from three-dimensional calculations except for slight increases in axial leakage which accompany such expansions. The resulting values, expressed in terms of cents per mil of cutward radial motion of the core/radial blanket boundary, are shown in Table 4.3-23 for various times-in-life. The beginningof-cycle (hot standby startup conditions) are best characterized by the configuration with 6 Row 7 corner primary control rods inserted, whereas the end-of-cycle conditions are most nearly simulated by the all-control-rods-out configuration. The uniform radial expansion coefficients in Table 4.3-23 can be translated to units of t/0F change in coolant inlet temperature by multiplying by 0.415 mils/oF which is derived from the linearized stainless steel (lower core support plate) thermal expansion coefficient. At the beginning-of-cycle-one, the reactivity change from uniform core radial expansion between refugling temperature (400°F) and hot-full-power conditions (730°F inlet temperature) is -58.5¢.

c. Fuel Assembly Bowing Reactivity

In addition to structural reactivity changes associated with the uniform expansion of the fuel and blanket assemblies, additional reactivity contributions occur as a result of core assembly bowing during reactor startup and shutdown. Fuel and blanket assembly bowing is a complex function of both the local temperature and neutron flux irradiation. The temperature dependence is a function of the absolute temperature within and the temperature gradients across the assembly ducts and pins. The irradiation induced swelling and creep are complex functions of the flux magnitude and spectrum, temperature and assembly residence time.

Radial bowing reactivity coefficients are calculated for each row of fuel and blanket assemblies at various axial nodes. First-order perturbation theory calculations in RZ geometry are used to determine the material worth gradients for fuel, steel, and coolant throughout the core. The radial bowing reactivity worth coefficients, expressed in units of $\rlap/$ c/inch of node displacement, are determined from differences in fuel, structural and coolant edge worths simulating row-by-row radial displacements.

The radial-row model for CRBRP is shown in Figure 4.3-30. Radial bowing reactivity coefficients were generated for Rows 2 through 12; the central (Row 1) blanket assembly and the six outermost radial blanket assemblies having a negligible reactivity contribution. Tables 4.3-24 and 4.3-25 give the radial bowing reactivity coefficients (\$\nable\$/inch of inward radial motion) for two core configurations. The beginning-of-cycle one results (Table 4.3-24) model hot-standby (initial startup) conditions and are characterized by a clean core and blankets and six Row 7 corner primary control rods partially inserted. The end-of-cycle two results (Table 4.3-25) were calculated with burned fuel assemblies, bred plutonium in the blankets, and with all 15 control rods fully withdrawn.

The predicted mechanical bowing displacements, discussed in Section 4.2.2.4.1.8.3, are superimposed on the reactivity worth coefficients in Tables 4.3-24 and 4.3-25 to determine the total reactivity feedback associated with various bowed configurations experienced by the core during the approach to power.

d. Uncertainty in Expansion Reactivity Worth Coefficients

Core expansion reactivity effects are difficult to simulate experimentally. However, an indirect verification of the core expansion reactivity worth calculational technique, using small-sample reactivity worth profiles in the homogeneous ZPPR-5 configuration, is discussed in Reference 14. Worth profiles from an RZ reactivity worth map, synthesized from small-sample reactivity worth traverses for major reactor materials in the fuel and blankets, are integrated to represent the reactivity worth changes due to uniform core axial and radial expansion, and thereby to deduce the "experimental" expansion coefficients. First-order perturbation theory calculations of these same expansion coefficients were compared with the experimental values in order to assess the calculational uncertainty. The experimental simulation of uniform expansion using measured small-sample worth distributions was validated by using this same small-sample worth data to predict the measured axial expansion reactivity worth of a shimmed oscillator fuel drawer in the inner and outer core zones.

Having accomplished the validation of the method for a measurable material rearrangement, the small sample traverses were used to determine an experimentally based (inferred) core expansion reactivity coefficient. First-order perturbation theory calculations of the reactor material worth distributions generally overestimated the magnitude of the worths themselves, consistent with the historically observed central worth discrepancy, but accurately predicted the shapes of the reactivity traverses upon which the expansion worth coefficients are based. The calculations of the measured expansion worth components resulted in calculationto-prediction (C/P) ratios of 1.01 and 1.11 for axial and radial expansion, respectively. These differences are not only an indication of calculational uncertainty, but also an indication of the degree of accuracy in the measurement and integration techniques. In the expansion reactivity prediction from the small-sample traverses, two axial reactivity shapes were combined with the midplane radial worth measurements to create an RZ reactivity map from which the expansion coefficients were inferred by integration of the worth distributions over the fuel and blankets. The potential for systematic errors introduced by the approximations inherent in this technique was evaluated. The stainless steel contribution was found to be very sensitive to the location of the axial shape measurements and this was a substantial contributor to the estimated error in the radial expansion worth. In the case of the axial expansion worth coefficient, both positive and negative components were overestimated resulting in compensating errors so that the calculation and measurement agreed very well (C/P = 1.01).

Based on the ZPPR-5 measurements and analysis, the uncertainty in the calculated expansion coefficient was estimated to be $\pm 15\%$ (1σ) in Reference 14 for a clean, homogenous core configuration. This uncertainty has been increased to $\pm 20\%$ (1σ) for application to CRBRP expansion calculations to account for extrapolation effects.

4.3.2.3.5 Power and Startup Coefficients and Temperature Defect

a. Power Coefficient

The power coefficient relates the change in reactor power level to a change in reactivity in the power operating range (40 to 100 percent of full power). The power coefficient consists mainly of Doppler reactivity feedback. The average power coefficient incorporates slower acting feedback mechanisms such as uniform radial expansion (Section 4.3.2.3.4-b) and coolant density changes (Section 4.3.2.3.3), as well as the fast-acting fuel and blanket Doppler (Section 4.3.2.3.1) and axial fuel expansion (Section 4.3.2.3.4.a). Between 40 percent

The prompt power coefficient only incorporates the fast-acting feedback components: Doppler and axial fuel expansion. The Doppler reactivity freeback comes from both the fuel assemblies, where the fuel pellet temperature responds essentially instantaneously to changes in power and from the blanket assemblies where the feedback response is delayed due to the thermal inertia in the larger blanket rods. Fuel axial expansion, driven by the fuel pellet surface temperature, is considered as a fast-acting feedback response. The prompt power coefficient, averaged over the range of 40 to 100 percent of full power, is -0.15 \$\exists /MWt at the beginning-of-cycle one (-0.06 \$\exists /MWt when only fuel Doppler is considered) and -0.17 \$\exists /MWt at the end-of-cycle four (-0.05 \$\exists /MWt fuel Doppler only).

The hot-full-power prompt power coefficient provides the stabilizing, inherently negative, feedback mechanism in response to power level increases in the power operating range.

b. Startup Coefficient

The startup (shutdown) coefficient relates the change in power level to a change in reactivity in the startup and shutdown range from 0 to 40 percent of full reactor power. The startup coefficient includes the reactivity effect of fuel and blanket assembly bowing (Section 4.3.2.3.4-c) in addition to feedback from Doppler, uniform expansion, and coolant density changes as discussed in Item (a).

The startup profile (Appendix B) indicates that most of the core temperature gradients will be established during the interval when the reactor power is being incrementally increased from near zero to 40 percent at a constant coolant flow rate of 40 percent of full flow. Fuel and blanket assembly bowing occurs in response to the power-to-flow transitions as the core thermal gradients are established (Section 4.2.2.4.1.8.3). Above 40 percent power, the reactor power level and the coolant flow rate are increased simultaneously (power-to-flow ratio is maintained at a value of 1.0) so that no further assembly bowing occurs.

The reactor power ascent is initiated after the reactor coolant temperature has been raised isothermally from 400°F (refueling temperature) to 600°F (hot standby) using 100% primary flow (i.e. using pump work) and minimum or no reactor power. During

this initial heat-up, Doppler, uniform core expansion and sodium density changes provide a negative reactivity feedback of about -90¢ which is compensated by control rod withdrawal. Beyond hotstandby conditions, as the reactor power is increased from near zero to 40 percent (at 40% primary coolant flow), the reactor coolant inlet temperature increases from 600°F to 635°F and the 265°F core AT is established. Table 4.3-26 summarizes the total feedback from Doppler, uniform radial and axial expansion, and sodium density changes between zero power (hot-standby conditions) and 40 percent power (40 percent flow). The largest negative feedback contribution in Table 4.3-26 is that from Doppler, ranging from -70.0¢ at the beginning-of-cycle one to -95.5¢ at the end-ofcycle four. The uncertainty in Doppler coefficient is + 10% (1σ). When the Doppler coefficient uncertainty is combined in quadrature with the temperature change uncertainties, the total uncertainty in Doppler feedback in the O to 40 percent power range is +12% (1σ). Uniform radial expansion only contributes about -6¢ (+20% lg)_based on the coolant inlet temperature change from 600°F to 635°F. Uniform axial expansion of -17.2¢ at the beginning-ofcycle one and -8.1¢ at the end-of-cycle four includes both a negative component from fuel pellet expansion and smaller positive contributions from blanket and steel expansion. The uncertainty in axial expansion reactivity is +20% from ZPPR -5 (+23% when combined in quadrature with thermal uncertainties at the lo level). Sodium coolant density changes contribute -1.4¢ (+30%) at the beginning of cycle one and +4.8¢ at the end of cycle four. The total negative feedback (excluding bowing) over the startup range from 0 to 40 percent power is therefore -94.8¢ (-76.0¢ minimum feedback with 2σ uncertainties) at the beginning of cycle one and -105.3¢ (-81.7¢ minimum) at the end of cycle four.

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The net bowing reactivity feedback is determined by superimposing the physical motion of the fuel and blanket assemblies (as described in Section 4.2.2.4.1.8.3) on the differential reactivity worth distributions (Section 4.3.2.3.4.c) throughout the core. The bowing reactivity response to the establishment of the core thermal gradients with increasing power-to-flow ratio (P/F) in the startup power range is characterized by an initial negative reactivity component as the assemblies bow outward and contact the TCLP (Top Core Load Pad). Further increases in P/F cause the fueled portion of the assemblies to be displaced inward toward the core centerline during which time reactivity is added to the system. The inward displacement continues until the assemblies again contact at the ACLP (Above Core Load Pad) in the upper axial blanket. From this point on, the assemblies assume an "S"-shape bowed configuration in which the fueled region of the core is again displaced radially outward and the reactivity contribution is again negative. When worst case data

uncertainties (maximum positive bowing reactivity coupled with minimum compensating negative Doppler feedback) are combined with conservative core compaction assumptions, the overall net startup reactivity feedback is predicted to be positive over a limited power range. The significance of this limited positive startup coefficient to reactor control and transient response is evaluated in Section 4.3.2.8 (Reactor Stability), 7.7.1.2 (Reactor Control System), and 15.1.4.5 (Reactor Assembly Bowing Reactivity Considerations). In the power operating range, from 40-100 percent of full power, no additional bowing takes place and the reactivity feedback is dominated by the strongly negative Doppler.

c. Temperature Defect

The net reactivity loss between zero-power, isothermal hot-standby or refueling temperature conditions and steady-state, hot-full-power thermal conditions is called the power or temperature defect. The temperature defect reflects the negative feedback reactivity contributions from Doppler, uniform radial and axial core expansion, sodium density changes and net negative bowing. Table 4.3-27 shows the temperature defect components in CRBRP at the beginning of the first cycle. Table 4.3-28 summarizes the net temperature defect at the beginning and end of the first four cycles of operation. The temperature defect, in part, determines the primary and secondary control rod worth (shutdown) requirements discussed in Section 4.3.2.4. The uncertainties in the temperature defect components in Table 4.3-27 reflect the statistical combination of both reactivity coefficient and temperature difference uncertainties.

4.3.2.4 Control Requirements

The reactivity control systems in CRBR are designed in accordance with the General Safety Design Criteria given in Section 3.1 and the appropriate design bases discussed in Section 4.3.1. These criteria assure that acceptable fuel design limits are not exceeded as a result of any anticipated operational occurrence or for any single malfunction of the reactivity control system.

Two independent reactivity control systems are utilized in the CRBRP. The primary system serves both a safety and an operational function. This system must have sufficient worth at any time in the reactor operating cycle, assuming the failure of any single active component (i.e. a stuck rod), to shutdown the reactor from any planned operating condition and to maintain subcriticality over the full range of coolant temperatures expected during shutdown. Allowance must be made for the maximum reactivity fault associated with any anticipated

occurrence. In addition, the primary control system is designed to meet the fuel burnup requirements for each cycle as well as to compensate for criticality and refueling uncertainties. The other reactivity control system, which is identified as the secondary system, must have sufficient worth at any time in the reactor cycle, assuming the failure of any single active component (i.e., a stuck rod), to shut down the reactor from any planned operating condition to the hot shutdown temperature of the coolant (hot standby conditions). Allowance must also be made for the maximum reactivity fault associated with any anticipated occurrence.

The primary and secondary control systems operate independently such that the capability of either system to fulfill its safety function is not dependent on the operation (or failure) of the other system. Design diversity and separation are provided to protect against common mode failures, as discussed in Section 4.2.3.

The aforementioned design criteria are interpreted to define the reactivity control requirements in terms of the minimum acceptable control capability under faulted conditions which will assure that the reactor power level can be brought down to zero at either the hot refueling temperature (in the case of the primary system) or the hot standby temperature (in the case of the secondary safety system). The faulted conditions are postulated to be the simultaneous failure of one system to scram, a stuck rod in the remaining system and a reactivity insertion resulting from the uncontrolled withdrawal of the highest worth control rod in the reactor.

The contributions to the control rod worth requirements are listed in Tables 4.3-29 and 30 for the primary and secondary systems, respectively, and are discussed in the paragraphs that follow.

a. Power Defect

The power defect (hot-full-power temperature defect) component of the control requirements compensates for the net positive reactivity insertion due to Doppler effect, radial and axial core contraction, bowing, and sodium density changes during reactor shutdown from hot-full-power to zero power isothermal temperature conditions as discussed in Section 4.3.2.3.5-c. The primary control system is designed to take the reactor temperature down from hot-full-power (including 3σ temperature uncertainties and 15% overpower) to 375°F (the hot refueling temperature, 400°F, less 25°F uncertainty). The secondary control system is designed to take the reactor temperature down from hot-full-power (including 3σ temperature uncertainties and 15% overpower) to 550°F (the hot-stand by temperature, 600°F, less 50°F uncertainty). The

largest contribution to the power defect comes from Doppler feedback. The uncertainties in the hot-to-cold reactivity swing, at the 2σ level, are determined from the root-mean-square combination of hot-full-power and shutdown temperature uncertainties with \pm 20% Doppler coefficient, \pm 40% for each of the radial and axial expansion feedbacks, and \pm 60% for the sodium density feedback. Also included is a worst-case uncertainty for assembly bowing which would lead to an additional positive reactivity component (core compaction) during shutdown.

b. Maximum Reactivity Fault

The maximum reactivity insertion in any anticipated operational occurrence is postulated to occur upon the withdrawal of the highest worth inserted control rod from its furthest inserted to the full out position. Although mechanical and electrical systems are provided to preclude this event, the resulting positive reactivity insertion envelopes other postulated operational faults and is, therefore, imposed on the shutdown requirements of both the primary and secondary control systems.

The maximum depth of insertion of the row 7 corner primary control bank is determined by the inserted worth required to compensate for the planned excess reactivity (excess fuel loading) for burnup requirements plus a combination of criticality and feedback uncertainties resulting in the highest anticipated excess reactivity in the system at any particular time-in-life For example, at the beginning of cycle 5 (see Table 4.3-29), the excess fuel loading of 2.86% Ak plus the root-mean-square combination of minimum hot-to-cold feedback (U.29% Ak), maximum criticality prediction uncertainty (0.43% Ak), and maximum fissile content tolerance (0.28% Ak) results in a maximum anticipated excess reactivity of 3.45% Ak (2.86 + .59). This excess is compensated by an expected row 7 corner primary control rod bank insertion of about 16.7 inches (21.9 inches with minimum worths). The maximum reactivity fault is postulated to occur upon the withdrawal of one of these row 7 corner control rods from the furthest bank insertion (plus 1.5 inch out-of-bank tolerance). It will be shown in Section 4.3.2.6 that the worth of a single control rod withdrawn from an inserted row 7 corner bank is substantially larger than the "average" worth of the rods in the bank. This rod interaction effect for the banked conditions discussed above at the beginning of cycle 5, increases the worth of the rod runout approximately 66% over the average row 7 corner single rod worth in the bank. Consequently, at the beginning of cycle 5, the maximum reactivity fault is taken

to be 0.98% Δk (3.45% Δk maximum excess reactivity divided equally among 6 row 7 corner inserted rods, increased by the out-of-bank tolerance, and then multiplied by a 1.66 rod interaction factor). The maximum reactivity fault values for other times-in-life are determined in a similar manner.

c. Reactivity Excess

The fuel enrichment requirements in CRBRP are based upon guaranteeing hot-full-power criticality at the end of each burnup cycle. Consequently, at times-in-life other than the end-of-cycle, some reactivity excess is present in the reactor. The primary control system (only) is designed to compensate this excess. Fuel burnup over the cycle is the largest reactivity margin which is included in the excess. Other reactivity effects, which include power defect uncertainties, fuel loading and core geometry tolerances, refueling worth, and criticality calculation uncertainties, are combined statistically and added to the nominal, resulting in a one-sided probability distribution which gives approximately 84% confidence (at the + 1σ level) that the fuel loadings will supply at least enough reactivity to meet the stated design fuel burnup lifetime requirements.

The criteria by which the reactivity excess is determined at any time-in-life is discussed in Section 4.3.2.1.1, "Fuel Enrichments and Loadings". The primary control rods must have sufficient worth at any time-in-life to suppress this excess reactivity.

d. Criticality Uncertainty

Control margin is included in the primary system (only) to compensate for the high-side of the 0.43% Δk (2 σ) biased cold criticality prediction uncertainty. This value is derived from the analysis of ZPPR-7 critical experiments as the RMS sum of the 2 σ ZPPR eigenvalue uncertainty and the uncertainty in the application of this bias to CRBRP.

e. Fissile Tolerance

Control margin is also included in the primary system (only) to compensate for the high-side of the 0.5% batch fissile content tolerance in the fuel. The batch fissile content tolerance results in a \pm 0.28% Δk excess reactivity uncertainty.

f. Miscellaneous Uncertainties

Fuel pellet stack height and impurities uncertainties were included in the fuel enrichment (start-of-cycle excess reactivity) requirements discussed in Section 4.3.2.1.1 to assure that the fuel loadings provided sufficient excess reactivity to compensate for potential reactivity deficits from variations in fuel column height and axial alignment and from the presence of neutron-absorbing impurities in the system. However, it is not necessary to cover the other side of these same uncertainties in the control requirements. That is, the potential for too much excess reactivity from these particular sources is already included in the nominal calculations which consider the highest core reactivity state resulting from the most compact core (axially aligned pellet stacks) and no impurities.

Burnup reactivity swing uncertainties could affect the core reactivity state at times-in-life other than with a fresh core loading. The burnup reactivity swing uncertainty is, however, considered to be one-sided. That is, we do not consider the potential for the core to be in a higher-than-expected reactivity state at the end-of-life due to a gross overprediction of the burnup reactivity deficit.* Therefore, the burnup reactivity swing uncertainties are not included in the control requirements.

^{*} The burnup reactivity swing uncertainty, which is included in the fuel enrichment (excess reactivity) requirement, accounts for 1) the expected underprediction of the lumped fission product worth, 2) the expected overprediction of core conversion ratio, 3) the expected irradiation-induced fuel swelling, and 4) the expected Np²³⁹ reactivity deficit at the end-of-life. All of these expected deviations from the nominal calculated burnup reactivity swing act more as biases rather than uncertainties, and they tend to make the nominal calculated burnup reactivity deficit smaller than expected (hence, the end-of-life reactivity state is already higher than expected which is conservative from the standpoint of control rod requirements but must be included in the fuel enrichment requirements).

4.3.2.6 Control Rod Worths

The locations of the primary and secondary control rod banks are shown in Figure 4.3-1. The principal components and dimensions of the control assemblies are summarized in Table 4.3-1.

The available control worths in the primary and secondary ystems were calculated for a variety of control configurations as a function of time-in-life. The analytical technique used in these calculations is summarized in Figure 4.3-31. Microscopic cross sections for the primary and secondary control rods were generated from ENDF/B-III data (Ref. 15) with the XSRES/1DX code (Appendix A) in a central control channel surrounded by fuel. The cross sections were resonance self-shielded and collapsed to 9 energy groups in the appropriate spectral zones. Nine-group macroscopic control assembly cross sections were homogenized over the full hexagonal subassembly. This was done by volume and transport flux-disadvantage weighting the microscopic cross sections in the rod bundle, the surrounding duct and sodium volumes using their respective atom densities. The resulting macroscopic control rod cross sections were used in coarsemesh, two-dimensional (120 degree, hexagonal) direct eigenvalue difference calculations (2DB) to determine the reactivity worth of the inserted control banks. The axial neutron leakage used in these problems was modeled from a group-independent, zone-dependent buckling obtained from an RZ model of the reactor at this particular time-in-life.

The burnup-dependent spatial distributions of fuel and fission products were modeled explicitly in the control rod worth calculations. Additionally, the secondary control rod worths were determined for an initially critical core configuration with the row 7 corner primary control rod bank partially inserted.

The calculated primary and secondary control rod worths are shown in Tables 4.3-29 and 30, respectively.

The nominal calculated control rod worths may contain uncertainties attributable to methods and modeling approximations, cross section uncertainties, the use of few-group, coarse mesh, two-dimensional diffusion theory, and others. Consequently, the control rod worth analysis methods and data are biased using calculations and measurements of control rod worths in the ZPPR-7 and 8 critical experiments. ZPPR-7 and 8 are pre-EMC (Engineering Mockup Critical) mockups of the heterogeneous CRBRP core configuration. Control rod bank worth (R4, R7C, and R7F) measurements were performed in both beginning-of-life (clean blankets) and end-of-life (plutonium loaded in the inner blankets) configurations. In addition, extensive measurements were made of single and asymmetric-bank worths in order to assess the accuracy of first-in and first-out control rod interaction factors. The analysis of these experiments using CRBRP design methods and cross-section data is summarized in Section 4.3.3.9.

For beginning-of-life conditions, the row 4 and 7 flat roa bank worths are systematically underpredicted by 10%, whereas the row 7 corner rod bank worth is only slightly underpredicted (1%) using standard few-group, coarse mesh diffusion theory. This difference is attributed to the observed tilt from the center of the core out toward the row 7 corner control channel in the calculation-to-experiment (C/E) ratios of both fission rates and small-sample reactivity worths. That is to say, the overall better agreement between calculated and measured R7C rod bank worths at beginning-of-life is most likely a result of at least partial cancellation of errors. At the end-of-life, with plutonium in the inner blankets, the rod bank worths are all consistently underpredicted by 10-12%. These biases differ markedly from the near-unity C/E ratios for rod bank worth predictions in the homogeneous-core (ZPPR-4) experiments. However, in contrast with the ZPPR-4 measurements where coarse mesh and diffusiontransport effects approximately canceled, the ZPPR-7 control rod worth calculations have been shown to be very sensitive to mesh structure. In fact, adjusting the aforementioned ZPPR-7 control rod worth biases for the difference between the ZPPR mesh structure (1 mesh per ZPPRdrawer or 4 meshes per "assembly") and the CRBRP mesh structure (6 meshes per assembly) lowers the bias factors about 4%, to 0.97 for the R7C rods at beginning-of-life and 1.05 to 1.06 for the remaining rod banks at the beginning or end-of-life. The worth-weighted primary control system (R4 + R7C) bias is, therefore, near unity; and the secondary control system bias is greater than unity indicating that the calculated control rod worths are conservatively underpredicted. The unbiased Root-Mean-Square (RMS) variation in the calculation-toexperiment ratios is about +4%. Considering that the systematic differences in these calculated control rod worths are not yet completely understood, it has been decided not to bias the calculated CRBRP control rod worths until final resolution of these values in the Engineering Mockup Critical (EMC) experiments. Rather, the minimum worths are determined from the unbiased calculated primary and secondary control rod worths, less uncertainty (2 x 4%) from above. It is well to note that the control rod worth biases have no direct impact on the minimum shutdown worth (which is set equal to the shutdown requirement). Rather, the control rod worth biases only enter into the determination of the minimum B10 loading (enrichment) required to satisfy the safe shutdown requirements. At the present stage of the CRBRP design, the primary and secondary control rod worths continue to be specified with fully enriched (92% B10) B.C. and the calculated worths exceed the shutdown requirements by a substantial (~10%) margin as indicated in Tables 4.3-29 and 30 (i.e., the "minimum" B10 loading is not being specified at this time).

The control rod worths, reported in Tables 4.3-29 and 30, represent expected configurations with symmetric bank insertion patterns. Significant rod interaction effects exist between the rods within a given bank and between banks due to flux redistribuion in the reactor in response to the insertion of the highly enriched poison. Table 4.3-31 summarizes various control rod interaction effects* for single

^{*}Interaction defined as relative rod worth normalized to the "average" rod worth in a bank where, for example, the average rod worth in a 6-rod inserted bank is one-sixth of the total inserted bank worth.

rods inserted in a clean core, asymmetric banks inserted, etc., determined from a series of parametric two-dimensional rod worth calculations with a 360° full-core model. Of special significance is the higher worth of a single row 7 corner rod removed from an inserted bank (first-out effect) which directly impacts the maximum worth available in a rod runout event. Figure 4.3-32 shows the variation in first-out row 7 corner rod interaction factor with depth of bank insertion. The worth of single rods inserted in a clean (or symmetrically poisoned) core are significantly lower than the average in the bank (first-in effect). The minimum worth of 5-out-of-6 secondary control rods is strongly influenced by whether the stuck secondary control rod is adjacent to the faulted primary rod which has been withdrawn (in which case the stuck secondary rod occurs in a local flux peak and is worth nearly twice as much as the average secondary rod) or opposite to the faulted primary rod.

Control rod interactions and flux tilting effects were investigated in ZPPR-7G (Section 4.3.3.9) where it was shown that control rod interaction factors (ratios of single first-in or first-out rod worths or asymmetric rod cluster worths to average rod worths in a symmetric bank) can be calculated with an accuracy somewhat better than the rod bank worths themselves. For a large number of measurements in ZPPR-7G, the ratio of calculated to measured rod interaction factors was $0.99 \pm .01$ which is well within the $\pm 4\%$ control rod worth uncertainty.

The control requirements specify that each of the primary and secondary control systems must perform their stated safety functions assuming the failure of a single active component. This is interpreted to be the failure of the highest worth single control rod in the system to respond to the trip signal (i.e., a stuck rod).

In the primary system, the stuck rod is the highest of either a fully withdrawn row 4 rod or a partly inserted row 7 corner rod. If a row 4 rod is stuck, then by definition all the row 7 corner (plus the 2 remaining row 4) rods scram, including the rod which is running out, thereby removing the reactivity fault. If a row 7 corner rod fails (other than the faulted rod which is running out), then the rod running out scrams, again removing the reactivity fault. If, however, the rod running out is also the primary rod which fails to respond to the scram then one has the largest realizable net positive reactivity insertion which must be compensated by the negative reactivity insertion from the remaining primary rods. In no case can this net reactivity (run-out plus stuck rod) exceed the worth of one row 7 corner rod with the maximum (full-in to full-out) first-out rod interaction effect. Therefore, the highest stuck primary rod worth is determined by:

[worth of average row 7 corner rod * full first-out rod interaction factor] - rod run-out (requirement), where the worth of the average row 7 corner rod is one-sixth of the total row 7 corner bank worth and the full first-out rod interaction factor, from Table 4.3-31, is 2.11 at beginning-of-cycle or 1.66 at end-of-cycle. It should be noted that this is an entirely self-consistent definition of reactivity fault and the stuck rod worth. That is, for any smaller reactivity fault within the allowed criticality uncertainty band width, the stuck rod worth would be proportionately larger, thereby maintaining the relationship between the worth and requirement in Table 4.3-29 such that the capability will always exist for the primary control system to satisfy the stated design safety function.

For the secondary control system in Table 4.3-30, the minimum shutdown capability occurs when the (highest worth) stuck secondary rod is adjacent to the faulted primary control rod which is running out at the beginning-of-life (interaction effect from Table 4.3-31 is 2.01). This is the value used at the start of each cycle in Table 4.3-30. Since the limiting secondary control rod capability (minimum shutdown margin) occurs at the beginning-of-life, and since the control rod interaction factor decreases with burnup as the primary control rod bank is withdrawn, this interaction factor is conservatively applied at all times-in-life in Table 4.3-30.

The minimum primary and secondary control rod worth capability is determined by reducing the nominal calculated rod worth by the 2σ (8%) uncertainty and subtracting the highest worth stuck rod from each system as described above. As shown in Tables 4.3-29 and 30, the minimum control rod worths exceed the maximum requirements at all times in life, which satisfies the safety design criteria.

It should be noted that these requirements are satisfied even under the extremely pessimistic, postulated accident assumptions that: the highest worth burnup and load-follow rod is uncontrollably withdrawn, one of the two independent, shutdown control systems fails to operate, and the highest worth control rod in the operating system remains stuck in the fully withdrawn position.

The integral rod worth characteristic curve, fraction of worth withdrawn vs. fraction of rod bank distance withdrawn, over the operating range of fully inserted to fully withdrawn is presented in Figure 4.3-33. The integral rod worth is well approximated by a sin² function of rod bank height, with a slight downward skew (phase shift) resulting from the relatively low worth of the uppermost regions of the core caused by the parked control rods in the upper axial blanket.

The primary control rods serve both as a burnup operational control system and as the primary shutdown system. The fraction of the total primary system reactivity worth which is available for shutdown

rod at a time. The nominal design rod withdrawal rate is 9 inches per minute, although a rod could be driven out of the core at maximum rate of 73 inches per minute in the event of a controller failure. Control rod outmotion in the unlatched condition is not considered credible, as is discussed in Section 4.2.3, and in any event would be limited by the out-motion pawl. An uncontrolled withdrawal of the highest worth control rod (the nominal calculated rod worth with the high side uncertainty, the maximum B-10 content and the highest rod interaction factor) at ramp runout rates of 9 and 73 inches per minute ("anticipated" and "unlikely" class accidents, respectively) would result in peak reactivity insertion rate: of 4.1 and 32.9 \$\psi/\sec\$, respectively at the highest point on the differential worth curve near the core midplane. The values corresponding to minimum shutdown margin conditions are 2.4 and 19.1 \$\psi/\sec\$, respectively.

4.3.2.7 Criticality of Fuel Assemblies

Two aspects of the criticality of fuel assemblies are discussed in this section. First, the uncertainty in the prediction of the absolute eigenvalue for CRBRP is considered. This result has a direct impact on the calculation of the feed enrichments and the control shutdown margins for the first and equilibrium cycles. Second, the criticality of small bundles of fuel assemblies is discussed in detail. These results impact the safety related aspects associated with the determination of the minimum number of fuel assemblies required for criticality.

4.3.2.7.1 Reactor Eigenvalue Prediction

The uncertainty in the CRBRP eigenvalue prediction is obtained from analysis of zero power fast critical assemblies which mock-ur the composition and geometry of the CRBRP core. One major difference between the experimental configuration and the CRBRP core is the use of fuel plates in a square lattice in place of the cylindrical fuel pins in a hexagonal array. Another difference is the extrapolation of the room temperature reactivity, obtained in the critical assembly, to that expected in the hot-full-power reactor.

The accuracy of design eigenvalue (lculations is evaluated by a comparison of calculated and measured criticality in ZPPR. Table 4.3-33 lists selected measured and calculated room temperature eigenvalues (keff) for several ZPPR experiments modeling both homogeneous (ZPPR-4) and heterogeneous (ZPPR-7) core configurations. Using the CRBRP design method (coarse-mesh, XY diffusion theory in this case) and data (ENDF/B-III cross sections in 9 energy groups)

results in a systematic underprediction of the reactor eigenvalue with an average C/E ratio of 0.996 + 0.003 in the homogeneous systems and 0.990 + 0.002 in the heterogeneous systems. The inverse of the average C/E ratio is applied as a bias in the calculation of CRBRP criticality (using the same calculational methods and data base) and the lo variation is included as an uncertainty in the start-of-cycle excess reactivity requirement. In order to use such an eigenvalue bias, one must consider the sensitivity of the eigenvalue to particular ZPPR parameters (plate heterogeneity correction as discussed in Reference 16, streaming and the like) which are not present in the power reactor and which may therefore introduce errors in the extrapolation of the ZPPR-bias to the power reactor. Consequently, an additional uncertainty of 0.2% Ak is included to account for potential systematic uncertainties in the keff bias arising from extrapolation of the heterogeneous plate-geometry ZPPR keff bias to the nearly homogeneous pin-geometry power reactor.

In order to establish the criticality of the hot-full-power CRBRP, a cold-to-hot temperature defect correction is applied to the cold-critical eigenvalue. The temperature defect accounts for the net reactivity loss from Doppler feedback, radial and axial core thermal expansion, sodium density changes, etc., in the escalation to hot-full-power conditions. The calculation of the temperature defect is discussed in Section 4.3.2.3.5. The uncertainty in the components of the temperature defect are combined statistically with the cold criticality uncertainty to establish the overall uncertainty in the hot-full-power reactor eigenvalue.

4.3.2.7.2 Minimum Critical Configuration

The highest expected fuel enrichment under equilibrium cycle conditions in CRBRP with low-240 grade plutonium fuel is 33.1 weight percent. Consideration of worst-case criticality uncertainties, highest fissile content tolerance, and simultaneous refueling of the entire core (including fuel, inner, and radial blankets) results in a 35.0 weight percent fuel enrichment envelope. A cluster of fresh fuel assemblies with the maximum fuel loading would contain a minimum number of assemblies required to achieve a critical configuration. Critical eigenvalue calculations were performed for various numbers of these maximum enrichment fuel assemblies in a regular hexagonal array spaced with a reactor pitch corresponding to refueling temperature. The assembly cluster was assumed to be immersed in a sodium pool with no control or blanket assemblies. One-dimensional S4, Po, 21-group fundamental mode eigenvalue calculations were performed in ANISN to determine keff as a function of the number of fresh fuel assemblies in concentric annular rings. Axial leakage was modeled by buckling factors determined from two-dimensional, RZ geometry, diffusion theory calculations.

The equations describing the temperature dependence in the reactor are a simplified version of the ones in the computer code DEMO (Appendix A). All coefficients are assumed constant at nominal full-power conditions. The average channel in the core is modeled with seven axial nodes, one each for upper and lower axial blankets and five evenly spaced nodes in the fuel region. Radially, three nodes are used; one in the fuel, one in the clad, and one for the sodium coolant temperature at the node exit. Inner and radial blankets are modeled with seven evenly spaced axial nodes. Radially, three nodes are used; one in the fuel, one in the clad and one for the sodium coolant temperature at the node exit. The equations described thus treat only internal reactivity feedback mechanisms. Specifically, the effect of control system response, operator intervention and plant system operation resulting in variation in inlet coolant temperature and flow, are not included.

The above set of linear first-order differential neutronic and thermal equations is mathematically expressed as:

$$\frac{\dot{x}}{\dot{x}} = \underline{A} \, \underline{x} + \underline{b} \, \delta k_{e} \tag{8}$$

where A is a 70 x 70 matrix. The feedback network of this system is shown in Figure 4.3-41. The various reactivity coefficients used in the analysis are discussed in Section 4.3.2.3.

The criterion for absolute stability is based on Liapunov's "first method" (Ref. 17) which reduces the problem of determining the stability of the system to that of finding the eigenvalues of the matrix A of equation (8)*. If the real part of all roots is negative, the system is stable. Conversely, if the real part of any root is positive, the system is unstable. The GASA program (Appendix A) is used to determine the eigenvalues of matrix A of equation (8).

The GASA program is also used to generate transfer functions for various combinations of reactivity feedback coefficients. The transfer functions at beginning and end of equilibrium cycle are shown in Figures 4.3-42 through 44. Normalization is at 100 Hz to zero 56 decibels (DB) since at that frequency all feedback effects have negligible effect and the -20DB/decade roll-off due to the finite prompt neutron lifetime has not become apparent. The stability analysis was performed for an early version of the CRBRP heterogeneous core configuration in which the predominant negative Doppler feedback was slightly smaller than in the current design. The results of the stability

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^{*} The eigenvalues of matrix A are identical to the roots of the characteristic equation of the system.

analysis presented herein are therefore somewhat conservative and the qualitative characteristics and the inherent reactor stability are valid. The interpretation of the transfer functions for the various reactivity feedback coefficient combinations is presented below.

a. Zero Power-Zero Feedback Transfer Function

The transfer function of the system at zero power with no feedback is shown in Figure 4.3-42, Curve A. The characteristic equation has one root equal to zero, which shows up in the -20DB/decade slope of the curve at low frequencies; i.e., the system acts as a pure integrator at low frequencies. Therefore, the system is unstable at zero frequency. This is expected since zero frequency corresponds to a constant reactivity insertion. In a system with no feedback, the power will increase indefinitely, thus invalidating the zero power transfer function. The utility of curve A is that it provides a basis to compare the stabilizing effect of feedback effects. A transfer function of lower magnitude than that of the zero power transfer function will be more stable and one of larger magnitude will be less stable at the particular frequencies where these differences occur.

b. Sodium Density Feedback

The transfer function of Figure 4.3-42, Curve B, results if credit is taken for the sodium density feedback only. The system is stable since all roots of the characteristic equation have negative real parts. This transfer function, which includes only the smallest negative feedback mechanism, already results in a noticeable improvement in stability as compared to the zero-power, zero-feedback transfer function.

c. Axial Expansion Feedback

Considering only the negative feedback due to axial expansion of the fuel (active core region only) results in the transfer function shown in Figure 4.3-42, Curve C. This feedback effect is noticeably stronger than the sodium expansion feedback.

d. Doppler Feedback

Curves D and E (Figure 4.3-42) depict transfer functions obtained when only the Doppler feedback is considered, with Curve D, representing the case where credit was taken for only half the nominal Doppler feedback, and Curve E, the case where the nominal Doppler feedback was used. It is apparent that the Doppler constant represents the strongest feedback mechanism, even taken at half its nominal value.

FORE-2M reactor kinetics and feedback model. As a further conservatism a dynamic bowing reactivity function (Figure 4.3-45) was defined in order to envelope the dynamic uncertainties associated with thermal time constant differences between the fuel and blanket assemblies. The dynamic function applies during that portion of the transient when the fuel assembly duct temperatures are changing rapidly (on the order of 50°F/second). The static function applies during the portion of the transient when the fuel assembly duct temperatures are changing slowly (less than 5°F/second). The duct temperature used in the model was determined from the assembly coolant temperature as shown schematically in Figure 4.3-41.

Additional conservative features which were employed in the model were:

1. Minimizing the negative Doppler reactivity effect.

Evaluating the results at the hottest fuel, cladding and coolant locations in the reactor.

3. Neglecting the ~ 2 second delay of the duct temperature relative to the coolant.

Figures 4.3-46 through 49 illustrate key reactor responses during an inherent response transient (no control or PPS action) initiated at a reactor startup operating point (8% power; 40% flow) at which the reactivity insertion due to bowing would be maximum. The transient was initiated by a $+2\cancel{k}$ step reactivity perturbation.

The responses illustrate that all parameters rise initially due to the dominance of positive bowing reactivity at low power/flow ratios. However, when the bowing reactivity coefficient becomes negative at higher power flow/ratios, all parameter responses change slowly and approach a new stable equilibrium state. The final values of the parameters are shown in Table 4.3-34 together with acceptability limits.

It is concluded that if the limits for acceptability (Table 4.3-34) are selected so as to remain below reactor parameter severity levels associated with a major incident (Table 15.1.2-1), and parameter responses remain below acceptability limits, the reactor is stable in the practical sense and inherent reactor protection shall have been demonstrated.

Additional reactor stability (inherent response) transients have been evaluated which were initiated at other operating states (i.e., reactor flow, reactor power, etc.). All of these indicate the response characteristics typically exhibited in Figures 4.3-46 through 4.3-49 and were bounded by the acceptability levels of Table 4.3-34.

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As a result of these studies, it is concluded that the reactor is stable given the bowing reactivity characteristics exhibited in Figure 4.2-92a since all transient responses are bounded for a bounded input perturbation. Furthermore, the reactor is stable in the practical sense since the maximum values of key reactor variables are below levels which are considered acceptable for the reactor when responding to its inherent feedbacks. Therefore, reactor inherent protection is demonstrated and Criterion 9 is satisfied.

4.3.2.9 Vessel Irradiation

The spatial and energy dependent neutron flux distributions are utilized in obtaining the irradiated characteristics of the reactor structural materials and components. One application of this flux data is in determining the total and fast fluence received by both replaceable and non-replaceable reactor components. The neutron fluence must be limited so that the end-of-life ductility for structural materials exceeds the specified minimum requirements.

Assembly-by-assembly radial neutron flux distributions (assembly-average in the central 36-inch active core height) are given in Figures 4.3-50 and 51 for core conditions reflecting the beginning of cycle one with the six row 7 corner primary control rods partly inserted and with fresh fuel and clean blankets, and for the end of cycle four conditions with all control rods fully withdrawn and with plutonium burned out of the fuel and built up in the blankets. Values are shown in Figures 4.3-50 and 51 for both the total neutron flux and for the fraction of the flux with an energy greater than 0.11 MeV. The latter reflects the relative spectral behavior throughout the core. The shift in the critical flux shape toward the center of the core with increasing burnup, and the spectral hardening in the blankets, is evident by comparing the fluxes in Figure 4.3-50 at the beginning-of-life with the end-of-life fluxes in Figure 4.3-51. Figures 4.3-52 and 53 show typical axial distributions of the total flux and the fast flux fraction in the core. These axial distributions are normalized to 1.0 over the central 36-inch active core height such that the product of the axial shape factors in Figures 4.3-52 and 53 with the fluxes in Figures 4.3-50 and 51 results in the three-dimensional flux distribution throughout the central core and blankets. The total flux in Figure 4.3-52 exhibits the typical bell-shaped axial distribution. Figure 4.3-53 indicates that the neutron energy spectrum (as measured by the fraction of the flux with an energy greater than 0.11 MeV) is relatively flat throughout the central core and degrades rapidly through the axial blankets. These radial and axial flux and spectrum distributions were obtained from two-dimensional, 21group diffusion calculations in hexagonal-planar and RZ geometry, respectively.

The peak total and fast (E > 0.11 MeV) fluxes in CRBRP (5.5 x 10^{15} n/cm² sec and 3.4 x 10^{15} n/cm² sec, respectively) occur in the rows 7 and 8 fuel cluster around the row 7 corner primary control rods.

The peak total (fast) fluences in the fuel and inner blanket assemblies have been determined for cycles one and two (first core) and for the subsequent equilibrium cycles. The first-core peak total (fast) fluences for the fuel and inner blanket assemblies are 1.47×10^{23} (9.20 x 10^{22}) neutrons/cm² and 1.46×10^{23} (8.66 x 10^{22}) neutrons/cm2, respectively. For the equilibrium core, the peak total (fast) fluences of the fuel and inner blanket assemblies are 2.38×10^{23} (1.45×10^{23}) neutrons/cm² and 2.29 x 10^{23} (1.35×10^{23}) neutrons/cm², respectively. The most conservative estimate of the neutron flux at the reactor vessel boundary is obtained at the beginning of equilibrium cycle. Later in life, the flux has shifted toward the center of the core and away from the core periphery in response to the inner blanket plutonium buildup, and therefore, the corresponding vessel fluxes would be somewhat lower. Table 4.3-35 summarizes the flux and spectrum data for the core, core and shield boundaries, core barrel, and the reactor vessel wall at the beginning of equilibrium cycle.

4.3.3 Analytical Methods

Each preceeding section described briefly the neutron data and computer codes used in the analysis. In most cases, calculational flow diagrams were presented for the particular analysis. This section describes the overall analytical techniques used in analysis of CRBRP and the supporting critical experiments performed in the ZPPR assemblies.

4.3.3.1 Analytical Approach

The CRBRP analytical methodology is summarized in Figure 4.3-54. Specific details about the development of particular nuclear characteristics were discussed in the preceding subsections. The core mockup experiments in ZPPR are analyzed with the same CRBRP design methods and cross-section data as described in Figure 4.3-55.

The multigroup cross-section libraries for CRBRP (or for ZPPR) are developed using the Bondarenko formalism (Reference 20). A generalized cross-section file, consisting of infinitely dilute fine-group cross sections, inelastic scatter transfer matrices, and temperature dependent self-shielding factors as a function of σ_0 (the total cross-section per atom), is obtained from the ENDF/B-III data file by way of the MINX* or ETOX* code. Using atom densities

* Appendix A contains computer code abstracts.

and cell models from the reactor or critical assembly, resonance selfshielding factors are calculated in the SPHINX* (XSRES) resonance module for each isotope as a function of temperature and non-resonant total cross-section (on) using an iterative scheme whereby the selfshielding factors are used to calculate σ_0 for the mixture and on and temperature are then used to interpolate new self-shielding factors. A Dancoff correction is applied to the cross-sections using Sauer's approximation for a cylindrical fuel pin 'n a hexagonal lattice (reactor design calculations) or Bell's approximation for plate lattices (critical assembly calculations). The resulting cross-sections are corrected for elastic removal and collapsed (condensed) to the desired few-group structure (9 or 21 neutron energy groups are generally used in CRBRP nuclear design calculations) in the SPHINX* (1DX) diffusion module. Both the elastic removal correction and group condensation are performed over the local reactor spectrum obtained from a one-dimensional (cylindrical or slab) diffusion calculation. Due to the size of the fuel plates in the ZPPR criticals, these cross-sections are further corrected for the in-cell fine structure in the flux by applying spatial flux-weighted cell homogenization factors obtained from one dimensional SPHINX* (ANISN) transport calculations with Po scattering and S16 quadrature.

The resulting 9 and 21-group master cross-section libraries are employed in the W-2DB* code in both hexagonal-planar and cylindrical (RZ) geometry to determine critical reactor eigenvalue (keff), radial and axial power and flux distributions, and control rod worth parameters and to perform burnup (depletion) calculations. Reactor depletion and power distribution calculations are performed in twodimensional hexagonal geometry with each of the fuel, inner and radial blanket assemblies modeled as a separate burnup zone in order to accurately model the spatial dependence of the fuel depletion, and blanket plutonium accumulation. Axial leakage in the hexagonal calculations is modeled as a DB2-type absorption cross section with a region-dependent, group-independent buckling determined from an equivalent RZ geometry calculation at the beginning and end of each cycle. Using these depletion models, control rod worth parameters are determined using 2DB eigenvalue difference calculations for a variety of reactor configurations as a function of time in life. Reactivity feedback coefficients, such as Doppler constants and sodium void worth, are calculated using first-order perturbation theory (PLRT-V)* and forward and adjoint flux distributions from RZ 2DB calculations.

^{*} Appendix A contains computer code abstracts.

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There are particular areas in the nuclear design process where the two-dimensional synthesis methods are known to be lacking due to spatial inseparability. One of these areas is the prediction of the local power distribution in the vicinity of partly inserted control rods as described in Section 4.3.2.2. Another area is the determination of the sodium void worth distribution throughout the core for input to design-limiting (margin, safety analyses (Section 4.3.2.3.2). In these particular areas, three-dimensional methods with the VENTURE* code (Reference 21) have been employed for the analysis of benchmark design problems.

4.3.3.2 Neutron Cross Section Data

The cross section data used in the CRBRP nuclear design calculations is obtained from the ENDF/B-III data file. A description of the Evaluated Nuclear Data File/B Version III is given in Ref. 15. The ENDF/B-III pointwise data and resonance parameters were processed by the ETCX code (Appendix A) at HEDL and supplied as punched-card output in the Bondarenko format for final processing as described in the preceding section. The 30 neutron energy group structure consists of basically 0.5 lethargy width groups with some subdivisions to handle the principal resonance structure of the diluents Na, Fe and 0. Details of this group structure and that of the condensed 9- and 21-group sets are shown in Table 4.3-36.

The inclusior of axial and radial blankets is a primary design feature of LMFBR's. Therefore, the prediction of in-core gamma heating has become an important post-FFTF LMFBR design problem. LMFBR gamma heating is calculated for CRBRP by the neutron-gamma coupled diffusion method in which the coupling between neutron and gamma groups, which occurs due to gamma production by way of neutron interactions, is mathematically represented in the cross sections in the scattering matrix. The scattering matrix contains gamma energy yield data from fission, capture and inelastic scattering sources. The gamma energy yield cross-section matrix is developed and coupled with a neutron cross-section data set, producing an N plus G group master cross section library in a module of SPHINX*. The SPHINX neutrongamma coupling libraries currently contain data from three basic sources: (1) Westinghouse's local coupling library designed for use in the APPROPOS* code, (2) ENDF/B-IV coupling data processed through AMPX by ORNL, and (3) particle energy release data (MeV/fission) from M. F. James (Reference 22).

^{*} Appendix A contains computer code abstracts.

4.3.3.3 Critical Experiments in Support of CRBRP

The LMFBR design methods and cross section data are verified by direct comparison of calculated parameters with integral measurements in critical mockup experiments. In the following sections, we will discuss the historical application of these integral experiments as benchmarks against which the accuracy of the design methods and data are evaluated and design bias factors and uncertainties are developed for application to the CRBRP (Reference 23).

4.3.3.4 ZPPR Assembly 2 and ZPR-6 Assembly 7

ZPPR Assembly 2 was the first de ionstration plant benchmark critical assembly. It was designed in accordance with the general LMFBR design features envisioned by the major LMFBR contractors, including Atomics International, General Electric and Westinghouse Electric Corporation. The experimental program was developed by the Argonne National Laboratory for pin versus plate measurements in order to assess the influence of the critical assembly plate environment, which generates local heterogeneities that are significantly different than those found in the nearly homogeneous pin environment in power reactors. Special emphasis was placed on reactivity, reaction rate ratios, Doppler effects and sodium voiding. The ZPPR-2 program on pin versus plate experiments and analyses was essential to the verification of the general applicability of the plate critical experiments to the design analyses of pin geometry power reactors. Prior to the ZPPR-2 pin measurements, the only experimental data for testing heterogeneity estimates involved plate bunching experiments wherein reactivity effects of varying plate drawer arrangements were made. The pin replacement experiments provided a more direct test of heterogeneity effects even though the experimental pin cells are somewhat more heterogeneous than an LMFBR fuel assembly. Similar measurements were performed in ZPR-6-7 which is a large single-zone assembly with a cell structure and composition nearly identical to the inner core zone in ZPPR-2.

The pin versus plate measurements in ZPPR-2 and ZPR-6-7 were performed by replacing small regions of the normal plate core with pin calandria containing 16 fuel rods (0.410 and 0.348 inch cladding and mixed oxide fuel pellet diameters, respectively) within each approximately 2x2 inch drawer. Figure 4.3-56 shows a cross section view of the ZPPR-2 assembly which outlines the central pin region (69 matrix drawers) and the radial pin sector. Initial pin versus plate measurements were performed in the central 69 drawers and the pin calandria were then rearranged into the radial pin sector for later measurements. Figure 4.3-56 also shows cross sections of the ZPPR-2 inner core zone plate arrangement and of the pin calandria.

In ZPR-6-7, the pin sector was comprised of 25 drawers. Axially, the ZPPR-2 pin region included the full 36 inch core height and extended 6-inches into the axial blankets, while the ZPR-6-7 pin region included only the central 24 inches of the 60 inch core height.

The evaluation and analysis of the pin versus plate ZPPR-2 measurements have been reported elsewhere (Ref. 16, 24, & 25). This data is summarized in Table 4.3-37. With the exception of the pin versus plate interchange reactivity effects, calculations at both ANL and ARD accurately reproduced the measured values for pin/plate ratios including sodium void, Doppler effect, reaction rate ratios and central Pu²³⁹ worth measurements (Ref. 16). These results gave considerable confidence that biases and uncertainties derived for these quantities from the plate-critical integral experiments could be applied to the power reactor. However, there was a substantial discrepancy in the capability to calculate the pin versus plate interchange reactivity effect in ZPPR-2 compared to ZPR-6-7 (C/E ratio of 1.64 in ZPPR-2 compared to 1.07 in ZPR-6-7). The axially longer region of pin versus plate replacement in ZPPR-2 (48 inches) compared with ZPR-6-7 (24 inches) was pointed out (Ref. 24) as a possible cause for the significant effects in ZPPR-2 due to rod/plate streaming differences. A difference of about 5-6% in diffusion coefficients between pin and plate environments was shown to be sufficient to explain the inconsistency between ZPPR-2 and ZPR-6-7 pin versus plate reactivity effects (Ref. 16 & 24). The direction-dependent streaming in the conventional pin versus plate reactivity analysis in ZPPR-2 has been confirmed by Zoltar, etc. (Ref. 26). Application of Benoist's streaming corrections (Ref. 27) to the analyses of ZPPR-2 and ZPR-6-7 put the two comparisons in reasonable consistency. The ratio of calculation to experiment for the pin versus plate fuel replacement reactivity is about 1.2 for ZPPR-2 and 1.07 for ZPR-6-7.

4.3.3.5 ZPPR Assembly 3

ZPPR-3 was a two enrichment zone assembly with each zone containing approximately 50% of the core volume. Axial and radial blankets surround the core. The drawer fuel loading pattern remained the same as ZPPR-2. The major difference between ZPPR-2 and ZPPR-3 was the simulation of a control system in ZPPR-3.

A series of critical experiments were performed in ZPPR Assembly 3 to investigate the effects of the control system on core nuclear characteristics as a part of the Demonstration Plant Benchmark Critical Program. The experimental configuration of ZPPR-3 (shown in Figure 4.3-57) was separated into 3 phases corresponding to the end-of-cycle (Phase 1B), middle-of-cycle (Phase 2), and beginning-of-cycle (Phase 3) reactor control conditions. The principal reactor parameters experimentally studied in ZPPR-3 were power distri-

bution, control worth and sodium void reactivity effects. ZPPR-3 was used primarily to provide a preliminary estimate of the Demonstration Plant power and control rod worth uncertainties.

4.3.3.6 ZPPR-3 Modified Phase 3 Sodium Void Benchmark

The Modified Phase 3 configuration of ZPPR-3 was designed to more closely mockup the homogeneous core design of the CRBRP with seven inserted control rods. An extensive series of sodium void measurements were performed in ZPPR-3. The primary purpose of these experiments was to measure the reactivity effect of large sodium void zones with a number of control rods inserted. One of the measurement configurations, the 632 drawer reference void in the Modified Phase 3 configuration as shown in Figure 4.3-58, has been chosen to be the basis for the sodium void benchmark.

This series of experiments provided considerable insight into the ability of the design methodology and cross section data to predict the maximum positive sodium void reactivity worth in a CRBRP-size LMFBR. Sodium voiding was accomplished in ZPPR-3 by replacing a number of steel-clad sodium plates with empty steel cans such that only a change in sodium content occurred. The axial height of the voided zone was ± 12 inches about the core midplane which is approximately the void height which is predicted to result in the maximum positive reactivity effect. The sodium void reactivity worth was determined for void zones extending from the core centerline out to a total of 632 matrix drawers (approximately 80% of the core cross sectional area).

Figure 4.3-59 shows the two-dimensional RZ calculational model which was used for the analysis of the ZPPR-3 Modified sodium void worth experiments. First-order perturbation calculations were performed using 21-group ENDF/B-III cross section data. The results of this analysis are shown in Figure 4.3-60 for 228, 466, 510, and 632-drawer voided zones. Experimentally, the maximum positive void worth occurs at approximately 510 drawers voided where the ratio of the calculated void reactivity worth to the measured value is about 1.33. All of the calculated void worths lie within + 50 percent of the measured values up to and including the point of maximum positive void worth, and in fact, the RZ calculation conservatively overpredicts the positive void reactivity worth. The experimental voiding patterns did not lend themselves particularly well to the cylindrical modeling in two dimensional RZ geometry. This was particularly evident in Figure 4.3-60 where the calculation-to-experiment ratios were somewhat divergent in the vicinity of the smeared row seven control ring. Consequently, a series of three-dimensional (VENTURE) perturbation calculations were performed for the sodium voiding experiments in both ZPPR-3 Phase 3 and Phase 3 Modified configurations. The results of these calculations are shown

in Figures 4.3-61 and 62, respectively. The three-dimensional calculations produced void reactivity worth results which were within ± 10 percent of the measured values for the Phase 3 experiments and ± 4 percent of the measured values for the Phase 3 Modified experiments. This overall good agreement suggests that the design method and data can indeed accurately predict the worth of large-scale sodium voiding so long as the void zone is confined to the strongly moderation-driven positive void worth regions of the core.

4.3.3.7 ZPPR-4 (Pre-Engineering Mockup Critical for Homogeneous CRBRP)

The primary objectives of the ZPPR-4 program were to verify the homogeneous CRBRP core nuclear characteristics including power margins for the first and equilibrium cycles, control rod worth characteristics and the effect of control insertion patterns on the core power distribution, and radial and axial blanket effects. The reference ZPPR-4 configuration is shown in Figure 4.3-63. The drawer fuel loadings and core layout of ZPPR-4 closely simulated the CRBRP first-core configuration.

The detailed results of the analysis of the ZPPR-4 experiments are presented in References 28 and 29. Table 4.3-38 summarizes the measured and calculated eigenvalues for the four phases of ZPPR-4. The calculations systematically underpredict the critical eigenvalue resulting in a $k_{\mbox{eff}}$ bias of 1.0036 and an uncertainty of ± 0.0031 (1 σ).

Foil activation measurements of Pu²³⁹ (n,f), U²³⁵ (n,f), U²³⁸ (n,f), and U^{238} (n,γ) (for the prediction of blanket plutonium buildup and core conversion ratio) reaction rates and TLD measurements of gamma heating rate support the determination of the power distribution uncertainty throughout the core and blankets. Foil and thermoluminescent dosimeter (TLD) irradiations are performed at a large number of locations throughout a symmetric core sector at both the core midplane and for axial distributions in selected fuel and blanket drawers. Special emphasis is placed on enrichment-zone, blanket and reflector interfaces, as well as regions surrounding inserted control rods. The pointwise foil data are corrected for cell fine-structure through a combination of cell calculations and drawer-averaging measurements, making the measured reaction rate data compatible with homogenizeddrawer calculations. In order to avoid a first-order uncertainty in the normalization to ZPPR power level, the calculated reaction rates are normalized such that the total calculated Pu239 fission rate in the fuel is equal to the total measured value. This is nearly equivalent to a power level normalization since Pu239 fission accounts

for 80-90% of the total reactor power. The remaining reaction rates are then compared based on this same power (flux level) normalization. Complete details of the analysis of the ZPPR-4 reaction rate measurements are given in References 28 and 29. Table 4.3-39 summarizes this analysis in terms of a mean or average calculation-to-experiment (C/E) ratio and a lo variation about this mean, with each calculated distribution being power (flux) normalized to the measured Pu²³⁹ fission rate as described above. The normalization factors indicate that U²³⁵ fission is overpredicted by about 2% relative to Pu²³⁹ fission, and U^{238} fission is unpredicted by nearly 7%, suggesting an underprediction of the high-energy fluxes in the few-group diffusion calculation. U²³⁸ capture is overpredicted by nearly 6% relative to Pu²³⁹ fission, indicating an overprediction of the end-of-life blanket plutonium content. Several general trends are noted in the data. Most importantly, it appears that the standard power reactor design calculational method does a good job of predicting the power distributions throughout a great majority of the core. The RMS variation in the C/E ratio for the important Pu239 fission rate is less than +2%. There does tend to be some degree of misprediction of the C/E ratios across the inner core/outer core boundary and the core/blanket interface. The largest differences show up in the radial blanket where the C/E ratios consistently fall off approximately 10 to 15% in the vicinity of the blanket/reflector interface which is generally a low power region. The normalized axial reaction rate distributions indicate a 2-3% overprediction of the midplane values with respect to the core-average, resulting in an overprediction of the axial peak-to-average ratio. Correspondingly, these same C/E ratios are low by about 5% in the vicinity of the core/axial blanket interface.

The ability to accurately and reliably predict the minimum available control rod worth in a variety of reactor configurations is clearly important in the design of reactors. Consequently, a substantial amount of effort has been expended in the recent ZPPR program, commencing with ZPPR-3 and 4, toward confirmation of control rod worth calculational methods and the establishment of calculational bias factors and uncertainties. The analysis of the ZPPR-4 control rod worth measurements is contained in References 28 and 29. Table 4.3-40 summarizes the results of ZPPR-4 control rod bank worth calculations using the standard power reactor coarse mesh, two-dimensional diffusion theory methods with 9-group ENDF/B-III data. Overall, the control rod bank worths were well predicted, confirming the adequacy of the design calculational method, with calculation-to-experiment ratios ranging from 0.95 to 1.04. There is a very slight tendency to underpredict the worth of the central and inner ring (row 4) rods. The average control rod worth bias (inverse of the calculation-to-experiment ratio), based on 27 control rod worth measurements in all four phases of ZPPR-4 is 1.01 + 0.02 (1σ). In addition to the determination of the control

rod worth bias and uncertainty, a number of special experiments were performed to investigate particular design problems. Among these special experiments were the determination of the worth as a function of B-10 enrichment (B_4C loading), the measurement of several data points on the integral worth curve for partly inserted rod banks (ZPPR-6), and the confirmation of the worth reduction associated with a tightly clustered control absorber bundle (ZPPR-4).

4.3.3.8 ZPPR-5 (HCDA Engineering Mockup Critical for Homogeneous CRBR)

Upon completion of the ZPPR-4 program, an Engineering Mockup Critical program for CRBRP was initiated. The program was to consist of measurements and analysis of two distinct configurations. The first, ZPPR-5, was designed to provide HCDA related measurements, and the second, ZPPR-6, was to provide measurements of basic design related parameters such as power distributions and control rod worths. Due to the implementation of the ZPPR-7 program for the heterogeneous core (Section 4.3.3.9), only the ZPPR-5 results are considered herein.

ZPPR-5 investigated such HCDA related parameters as sodium voiding, steel slumping, fuel slumping and Doppler feedback. The sodium voiding experiments encompassed portions of the core and the upper axial blanket in a sequence representative of a hypothetical power reactor voiding pattern. Two-dimensional RZ analysis indicated a non-statistical uncertainty of +20% in regions of large positive voiding worths (central core regions). The error is much larger in the axial blankets due to the inability of the method to accurately predict neutron streaming in the plates. Three-dimensional (XYZ) perturbation theory analysis has been performed in the voiding sequence in ZPPR-5 but has indicated no significant improvement in the uncertainty. It should be noted that the voiding was not confined axially to + 12 inches as was the case in the ZPPR-3 experiments but extended into the axial blankets in order to model a representative sodium voiding sequence. Voiding was performed in the axial blankets prior to the fuel height region. Consequently, the uncertainty in these predictions are larger than ZPPR-3 due to the enhanced neutron streaming. The neutron streaming effect due to plate heterogeneity in the criticals will not be so predominant in power reactors because of their more homogeneous material distribution.

4.3.3.9 ZPPR-7 (Pre-Engineering Mockup Critical for CRBRP Heterogeneous Core)

The purpose of the ZPPR-7 program was to provide pre-EMC design support for the heterogeneous CRBRP core arrangement. Information obtained from this program was used to validate and provide

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preliminary design bias factors and uncertainties for the CRBRP heterogeneous core physics characteristics, and to affect the selection of the CRBRP core layout and fuel management scheme. The experimental program was divided into a number of phases, highlighted by a clean benchmark configuration with annular blanket rings and no control rod or control channel heterogeneities; simulations of both a clean, beginning-of-life, core with fresh blankets and a burned, end-of-life, core with depleted fuel and plutonium buildup in the internal blankets; and various simulations of control pattern effects on core characteristics. The initial ZPPR-7 configurations modeled an early version of the CRBRP heterogeneous core layout. These measurements were followed by a brief series of experiments which validated the earlier results in a mockup of the final CRBRP heterogeneous core configuration in Figure 4.3-1. The analysis and description of the ZPPR-7 neasurements is contained in References 30 and 31. Figure 4.3-64 shows the core layouts for the principal ZPPR-7 configurations.

ZPPR-7A was a benchmark configuration with clean (no plutonium) annular blanket rings inside a single enrichment core with no control rods or control rod channels which was intended to isolate the characteristics of the heterogeneous core geometry. The principal experiments investigated criticality, key isotopic neutron reaction rate distributions and sodium void worth.

The Phase B core was rearranged to provide a better simulation of a CRBRP fresh core with 12 control rod channels (6 in row 4 and 6 in row 7 corner) and inner blanket islands in the outer fuel zones. The objectives of this configuration included an examination of criticality, control rod bank worths and fuel/blanket interchange worths, and isotopic fission and capture rate distributions in the fuel and blankets.

Many of the Phase B measurements were repeated in the Phase C configuration which simulated end-of-life core conditions with depleted fuel and plutonium loaded in the inner blankets. This series of experiments provided information on the flux and power shift associated with blanket plutonium buildup and its effect on criticality, reaction rate distributions, and control rod worth.

The Phase D configuration more closely simulated the CRBRP control pattern with a total of 15 control rods (6 row seven corner rods, 6 row seven flat rods, and 3 row 4 rods) in the end-of-life ckup. The Phase E configuration examined the effects of the inserted row seven corner control rod bank on the core power distribution.

After the completion of the ZPPR matrix expansion to 14 feet by 14 feet to accommodate larger core configurations, the ZPPR-7B configuration was reassembled as a normalization to the earlier measurements (designated Phase F).

Extensive control rod worth measurements were performed in Phase G. The Phase G core configuration was the same as that of Phase D with 15 control rods except that no plutonium was loaded in the blankets in order to simulate beginning-of-life clean core conditions. Control rod interactions and flux tilting effects were investigated through a series of symmetric and asymmetric rod-cluster and individual rod insertion measurements.

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In Phase H, the row seven corner control rod bank was half inserted and extensive foil irradiations were performed in order to simulate the three-dimensional power perturbations encountered in a clean, beginning-of-life core with partial control rod insertion.

Following a series of non-CRBRP thorium-zone measurements in ZPPR-8, the Phase 8F configuration was assembled to simulate the final CRBRP heterogeneous core configuration at the beginning-of-life with fuel islands surrounding both the row seven corner and the row seven flat control rod banks (Figure 4.3-1). The experimental program was structured to verify the power shape and control rod worth biases and uncertainties which were determined in the earlier ZPPR-7 experiments. In addition, the power tilt associated with an out-of-bank control rod was measured as was the control rod/fuel assembly interchange worth in the shutdown configuration.

The ZPPR-7 Critical experiments provide a valuable integral data base against which the accuracy of the CRBRP design methods and cross section data can be evaluated for application to the heterogeneous core configuration. Because of differences in geometry, composition, size, and temperature between the zero power critical experiments and the CRBRP, the measured integral parameters obtained from the critical are not applied directly to the reactor design. Rather, the accuracy of the design calculational methods and cross section data are evaluated by comparing calculated and measured critical parameters. The resulting biases and/or uncertainties from this comparison are then applied to the calculation of these same parameters in the reactor design using the same calculational methods and data. In the paragraphs that follow, the development of the preliminary design bias factors and uncertainties from the ZPPR-7 and 8 data base will be summarized for application to the heterogeneous core configuration in the principal design areas of reactor eigenvalue prediction, power distribution accuracy, control rod worth uncertainty and sodium void worth. Complete details of the ZPPR-7 and 8 analysis are included in References 30 and 31.

ZPPR-7 and 8 Eigenvalue Prediction:

Table 4.3-41 summarizes the measured and calculated critical eigenvalues (keff) for ZPPR-7 and 8. In order to avoid mixing the control rod worth biases in with the development of the reactor eigenvalue bias, only the clean (unrodded) phases of ZPPR-7 and 8 are included in Table 4.3-41. The calculations systematically underpredict the critical eigenvalue, resulting in a keff bias of 1.0101 and an uncertainty of \pm 0.19% $_{\Delta k}$ (10). Within the stated standard deviation in the calculation-to-experiment ratios in Table 4.3-41, there is no statistical difference between the eigenvalue bias in the beginning-of-life and end-of-life phases of ZPPR-7 and 8. The ZPPR-7 and 8 eigenvalue bias is included directly in the determination of the CRBRP critical loading and the lo variation is included as an uncertainty in the excess reactivity requirements for both the critical fuel loading and control rod worth requirements determinations.

Power Distribution:

The integral data from the ZPPR experiments supporting the power distribution analysis consists of foil activation measurements of Pu^{239} (n,f), U^{235} (n,f), U^{238} (n,f), and U^{238} (n, γ) (for the prediction of blanket plutonium buildup and core conversion ratio), and TLD measurements of gamma heating 'ate. Foil and TLD irradiations are performed simultaneously in a large number of locations throughout a symmetric core sector at the core midplane and axial distributions in selected fuel and blanket drawers. Special emphasis is placed on blanket and reflector interfaces as well as regions surrounding inserted control rods. The pointwise foil data are corrected for cell fine structure through a combination of cell calculations and drawer-averaging measurements, making the measured reaction rate data compatible with homogenized-drawer calculations. In order to avoid a first-order unertainty in the normalization to ZPPR power level, the calculated reaction rates are normalized such that the average calculated Pu²³⁹ fission rate in the fuel is set equal to the average measured value. This is nearly equivalent to a power normalization since Pu²³⁹ fission accounts for between 80 and 90% of the total reactor power generation. The remaining reaction rates are then compared based on this same power (flux level) normalization.

Table 4.3-42 summarizes the analysis of the ZPPR-7 reaction rates in terms of an average calculation-to-experiment (C/E) ratio and a lo variation, with each calculated distribution being power (flux level) normalized to the measured Pu^{239} fission rate in the fuel as described above. The normalization factors indicate that U^{235} fission is overpredicted by about 4% relative to Pu^{239} fission in the heterogeneous critical assemblies. U^{238} fission is underpredicted by nearly 20% in the fuel and about 6% in the inner blankets, indica-

ting both a general underprediction of the high energy fluxes and substantial errors in predicting the spectral gradients between the fuel and blanket assemblies with the coarse-mesh, few-group diffusion calculations. U^{238} capture is overpredicted by nearly 10% relative to Pu^{239} fission, indicating a general overprediction of the end-of-life blanket plutonium buildup, and hence, the end-of-life blanket power generation. The important Pu^{239} fission rate is, however, well predicted with the standard reactor design methods, with an RMS deviation of less than \pm 2% in the C/E ratios throughout the core and blankets.

Figures 4.3-65 and 66 show the normalized distributions of the midplane Pu239 fission rate calculation-to-experiment ratios representing the general radial distribution trends at the beginning-(Phase B) and end-of-life (Phase C). In the beginning-of-life core (Phase B in Figure 4.3-65) with no plutonium in the blankets, the C/E ratios tend to be low in the central core regions and tilted toward 3-5% higher values around the outer ring fuel clusters especially around the row-seven corner control channels. The impact of refinements in the power distribution calculation methods, and the sensitivity of this tilted characteristic to cross section data variations is discussed in Reference 32. The CRBRP power predictions in comparable regions are biased downward 1-3% as described in Section 4.3.2.2.9 to compensate for this inherent overprediction. This tilt is not observed in the end-of-life (Phase C in Figure 4.3-66) simulation with a more homogeneous distribution of plutonium throughout the core.* The largest differences in both phases occur in the radial blanket where the C/E ratios consistently fall off 10-15% or more in the vicinity of the blanket/reflector interface (which is generally a low power region). This fall-off, which is similar to that observed in the homogeneous ZPPR-4 experiments, is included in the blanket uncertainty assessment in Section 4.3.2.2.9. The normalized axial reaction rate distributions indicate a 2% overprediction of the midplane reaction rates with respect to the channel-average and a corresponding 5% underprediction of the reaction rates at the core extremities in the vicinity of the core/axial blanket interface.

The power-normalized reaction rate biases and uncertainties (at the 3d level) are applied in the reactor design, with appropriate weighting for the time and space dependent fraction of power attributable to each reaction type, in order to determine the limits of the power distribution in Section 4.3.2.2.10 for design margin and safety analyses.

^{*} The Phase C configuration has plutonium loaded in the inner blankets and removed from selected fuel locations to simulate an end-of-life burned core.

Control Rod Worth:

A substantial amount of effort was expended in the ZPPR-7 and 8 program toward confirmation of the control rod worth calculational methods and the development of calculation bias factors and uncertainties supporting the minimum shutdown margin. Table 4.3-43 lists the results of control rod worth calculations in the heterogeneous ZPPR-7 mockup for both the beginning-of-life with a clean core and blankets and for an end-of-life simulation with plutonium loaded in the inner blankets. In contrast to the generally well predicted ZPPR-4 results in Section 4.3.3.7, the heterogeneous ZPPR-7 control rod worth calculation-to-experiment ratios exhibit a strong spatial bias in the beginning-of-life core (Phase B), varying between 0.91 in the inner ring (row 4) rod worths and 0.99 in the outer ring (row 7 corner) rod worths. end-of-life worths (Phase C) are consistently underpredicted by nearly 10%. It would seem that the close prediction of the beginningof-life row 7 corner rod worths is an anomaly associated with the calculated reaction rate tilt (overprediction) in this same region. Transport and mesh effects no longer compensate in the highly-loaded ZPPR-7 control rods as noted by the much closer overall agreement obtained with a finer mesh diffusion calculation in Table 4.3-43. The coarse-mesh (1 mesh per ZPPR drawer corresponding to 4 meshes per control assembly) control rod bias is therefore not directly micable to the power reactor control rod worths, calculated with ciangular meshes per control assembly, without adjustment for mesh sensitivity. Although the consistent underprediction of control rod worths in ZPPR-7 may not be fully understood at this time, the experiments do seem to indicate that the unbiased power reactor calculated rod worths are probably conservatively low (that is, final resolution of a set of heterogeneous ZPPR-7 control rod worth biases will tend to raise the calculated power reactor rod worths).

Due to the importance of the control rod withdrawal event (reactivity fault) in the design of the heterogeneous CRBRP where flux thifting and control rod interactions have been found to be substantial, a series of experiments (ZPPR-7G) were performed in which a large number of asymmetric control rod insertion patterns were studied. These patterns included single and small clusters of rods inserted asymmetrically in the core, five-out-of-six rods inserted in a bank (simulating the stuck rod condition), and five-out-of-six secondary control rods inserted in a core containing five-out-of-six inserted primary rods (simulating the limiting condition where the stuck secondary control rod is adjacent to a faulted-withdrawn-primary control rod). The patterns produced substantial flux shifts in the reactor, resulting in control rod interaction factors* exceeding a factor of two. Pre-

^{*} Control rod interaction factor is defined as the ratio of the rod worth in a particular asymmetric pattern to the average worth in a symmetric bank.

liminary analysis of these experiments in Reference 30 indicates that the grossly asymmetric patterns (or control rod interactions) are predicted with approximately the same accuracy as the symmetric bank worths in Table 4.3-43 using the standard power reactor design method and a full-core two-dimensional calculation model, thereby confirming the adequacy of the maximum reactivity fault values used in the development of the heterogeneous power reactor control requirements.

Sodium Void Worth:

A series of sodium void worth measurements were performed in the clean benchmark ZPPR-7A configuration. The voiding was more confined to the central core regions than the HCDA simulation in ZPPR-5 (Section 4.3.3.8). The voided region extended stepwise from the central blanket out through the second fuel ring (see Figure 4.3-64) at a radius of about 50 cm, and the axial void included parts of the axial blanket (+ 60 cm from the core midplane) in the central blanket and first fuel ring, and only the central core regions (+30.5 cm) in the first blanket ring and the second fuel ring in Figure 4.3-64. Two-dimensional (RZ) first order perturbation theory calculations indicated that the positive (moderation) component of the void worth is reduced compared to the homogeneous ZPPR core values, confirming the lower positive sodium void worth characteristic of the heterogenous core, and the calculation-to-experiment ratios for the positive void worth regions were somewhat lower than the comparable ZPPR-3 and 5 values.

4.3.3.10 Computer Code Abstracts

Nine computer codes were used to support the nuclear analysis described in the previous sections. They are: ANISN-W, W-2DB, PERT-V, ETOX, XSRES-WIDX, PUMA, SPHINX, VENTURE, and POWPIN. A brief abstract of each of these codes is found in Appendix A.

4.3.4 Changes

The design features of the Clinch River Breeder Reactor can be compared with at least four different sodium cooled, fast reactors built or currently under construction in the United States. These include: (1) the Experimental Breeder Reactor (EBR)-II, (2) the Enrico Fermi Atomic Power Plant, (3) the Southwest Experimental Fast Oxide Reactor (SEFOR), and (4) the Fast Flux Test Facility (FFTF). These four reactors were all designed to test and verify specific features and components of fast breeder reactors.

The EBR-II was originally designed as a demonstration of the feasibility of operating an LMFBR power plant with integral closed fuel cycle provided by an on-site fuel reprocessing and refabrication plant. Although not specifically designed for the purpose, it was designated as the nation's principal fast flux irradiation facility. Samples are irradiated in high temperature sodium and high fast neutron flux environment. The reactor core employs metallic uranium fuel surrounded by radial and axial blankets and produces 62.5 MWt and 20 MWe.

The Fermi reactor was designed and built to serve as the first full-scale mockup of a large, sodium cooled, fast breeder reactor. More specifically, its objectives included the testing of such components as the steam generator, sodium pump and fuel handling equipment and to demonstrate the economic feasibility of the LMFBR to produce power on an electric utility grid. The Fermi reactor also employed metallic uranium fuel, radial and axial blanket assemblies. The rated power of the first core loading was 200 MWt.

SEFOR was a ceramic fueled, sodium cooled fast flux reactor intended to provide data in support of a test program to demonstrate that fast power reactors could be designed with desirable operating and safety characteristics. In particular, it was designed for the systematic determination of the Doppler coefficient of reactivity at temperatures up to the vicinity of fuel melting. SEFOR employed a mixed uranium-plutonium oxide fueled core with a nickel reflector and was rated at 20 MWt.

The FFTF, currently under construction, was designed to provide a fast neutron, sodium cooled environment typical of a large LMFBR. This reactor will act as a full size test bed for both current and advanced fast reactor fuel, absorber and structural materials. These samples will be irradiated in both open and closed test loop locations within the reactor core. The FFTF employs (U-Pu)02 fuel in two enrichment zones surrounded by a nickel reflector and has a nominal power rating of 400 MWt.

The CRBRP has particular design objectives which set it apart from previous fast reactors built in the United States. Principal among these is the requirement that CRBRP must breed fissile plutonium with a breeding ratio in excess of 1.2 to demonstrate the potential for large scale commercial LMFBR operation. A second distinctive feature is the nominal power capability of 975 MWt which is more than twice as large as any of the four reactors described above. In addition, CRBRP is the first sodium-cooled LMFBR in the United States to incorporate the heterogeneous core configuration.

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These requirements imply that the fuel and blanket regions of the CRBR must be designed to maximize both the breeding of fissile material and the thermal power output. But at the same time the reactor must be maintained and operated in a safe and reliable manner throughout its thirty year design life. In the following discussion a detailed comparison will be made between the CRBRP and the FFTF designs with particular emphasis on safety related features and components.

Pertinent nuclear design features of the two reactors are compared in Table 4.3-44. It should be noted that the dimensions included in Table 4.3-44 are based on cold (room temperature) conditions.

For the initial core loading, the CRBR? fuel pin and fuel assembly designs take the maximum advantage of the FFTF fuel experience. Essentially, the same design has been employed with a slightly larger assembly pitch. Because of the increased power capability, the CRBRP fuel volume was increased by approximately 2.3 times compared to FFTF. Since the demonstration of breeding was not an FFTF design objective, axial and radial blankets were not employed.

The fuel enrichments, compositions and loadings are also compared in Table 4.3-44. In the early operating cycles the CRBRP fuel assemblies employ the same type of low-240 plutonium fuel as the FFTF. In later cycles the CRBRP may employ light water reactor discharge grade plutonium which has a fractionally lower relative amount of Pu-239 and larger concentrations of the higher plutonium isotopes. More than twice as much fissile plutonium is employed in the first core loading of the CRBRP as in FFTF.

The designs of the control rod systems for these two reactors are summarized in Table 4.3-44. Both the primary and secondary control systems in CRBRP and FFTF employ boron carbide as the neutron absorber. All CRBRP control assemblies are fully enriched in B-10 to meet the control requirements (see subsection 4.3.2.6 for details).

The operating conditions, including burnup limits, refueling, power distributions and peak flux for these two reactors are also listed in Table 4.3-44. The overall radial power peaking factors for the CRBRP are smaller than those quoted for FFTF. This is due to the larger core radius, different control rod patterns and the heterogeneous fuel and blanket arrangement.

The reactivity coefficients for the CRBRP are discussed in detail in subsection 4.3.2.3. Table 4.3-45 compares the different reactivity coefficients of CRBRP and FFTF.

provides a reliable, prompt negative reactivity feedback to mitigate the effects of reactivity transients which can lead to rapid power increases. Consequently, the magnitude of the Doppler coefficient has special significance in the safety analysis of fast reactors. The par coefficients in Table 4.3-45 are listed by reactor zore for four different times in the life of the plant.

In all four cases the CRBRP Doppler coefficient summed over all core zones is at least 60% larger (more negative) than the FFTF value. The fuel and inner blanket Doppler constant is nearly 40% larger than the FFTF value. The fast-acting fuel Doppler contribution alone is about half the comparable FFTF value.

The remaining reactivity coefficients compared for these two reactors are all associated with mechanical motion due to temperatur changes in the fuel, coolant and structure. The average sodium density coefficients for the CRBRP and FFTF during the first cycle are given in Table 4.3-45. These results are based on changing the density of the coolant in all fueled zones, including the inner and radial blankets in the CRBR. The sodium density coefficient is significantly smaller (less negative) in the CRBRP because of the positive contribution from the fuel zone.

The uniform radial expansion coefficients for the two reactors during the first cycle are also shown in Table 4.3-45. These values are based on the expansion of the lower core support structure, which changes the average assembly pitch with changes in the coolant inlet temperature. The uniform radial expansion coefficient for CRBRP is smaller than the FFTF value because of the heterogeneous fuel and blanket arrangement in the CRBRP core. Radial bowing effects, including those imposed by the core restraint mechanism, are discussed in Section 4.3.2.3.4.

Finally, the uniform axial expansion coefficients for the two reactors at beginning-of-life are listed in Table 4.3-45. These results are based on the expansion of the fuel pellet stack with changes in the average surface temperature of the dished fuel pellets. It is assumed that the pellets move freely within the cladding tubes and that the axial motion is governed solely by the linear expansion coefficient of the mixed uranium-plutonium oxide. This assumption tends to yield the largest (magnitude) coefficients; fuel pellet sticking to the clad or degradation of the fuel pellets under irradiation will significantly reduce the magnitude of this coefficient.

Additional safety related features and components of the CRBRP are compared with selected foreign built LMFBRs in Section 1.3.

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TABLE 4.3-1 (C	continued)
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1		(001101111000)	
	INNER/RADIAL BLANKET RODS (Cont)	UNITS	DESCRIPTION
	Clad Material		20 Percent CW-Type 316 SS
	Clad Thickness	MM	0.381
	Pitch/Diameter Ratio		1.072
	INNER/RAPIAL BLANKET PELLETS		
	Material		Depleted Uranium Oxide
	Pellet Density (Percent of Theoretical)	%	95.6
1	Pellet Diameter	MM	11.938
	Pellet Stack Height	М	1.626
	CONTROL ROD ASSEMBLIES		
	Geometry		Hexagonal
	Number in Plant		15
	Primary Rods (Startup, Burnup and Load Follow)		9
	Secondary Rods (Safety)		6
	Neutron Absorber		Enriched Boron Carbide
	Fraction of Theoretical Density	%	92.0
	B-10 Enrichment in Boron Carbide:		
	1) Primary Rods (all cycles)	atom percent	92.0
	2) Secondary Rods	atom percent	92.0

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CONTROL ROD ASSEMBLIES (Cont)	UNITS	DESCRIPTION
Rods Per Assembly		
Primary System		37
Secondary System		31
Clad Material		20 Percent CW-Type 316 SS
Clad Outside Diameter		
Primary System	MM	15.291
Secondary System	MM	14.036
Clad Thickness		
Primary System	MM	1.270
Secondary System	MM	0.699
Pellet Diameter		
Primary System	MM	11.659
Secondary System	MM	11.951
Pellet Stack Height	М	0.9144

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TABLE 4.3-7

FUEL AND INNER BLANKET POWER FRACTION SUMMARY*

Time-In-Life	<u>Fuel</u>	INNER Blanket (36")
BOC1	.8603	.0720
EØC1	.8174	.0989
BOC2	.8208	.0967
EØC2	.7618	.1330
восз	.8308	.0683
EØC3	.7526	.1190
BOC4	.7623	.1129
EØC4	.6973	.1536
B0C5	.8351	.0690
EØC5	.7541	.1214
BOC6	.7895	.1195
EØC6	.7172	.1639

^{51 | *} fraction of full operating power in central 36 inch high region.

TABLE 4.3-8

AXIAL BLANKET, AXIAL EXTENSION POWER NORMALIZATION FACTORS

TIME IN LIFE	POWER IN CORE + LAB + UAB : POWER IN CORE + LAB POWER IN CORE : POWER IN CORE								
	Fuel Assemblies	Inner B1	ankets	Radial I	Blankets				
		Rows 2,4	Rows 6,8	RB1	RB2				
30C1	1.0137:1.0079	1.13:1.07	1.11:1.07	1.11:1.06	1.17:1.09				
E0C1	1.0176:1.0102	1.12:1.07	1.11:1.07	1.11:1.06	1.15:1.08				
30C2	1.0177:1.0105	1.12:1.07	1.11:1.07	1.11:1.06	1.15:1.08				
E0C2	1.0247:1.0140	1.12:1.07	1.11:1.07	1.11:1.06	1.14:1.07				
30C3	1.0140:1.0081	1.13:1.07	1.11:1.07	1.11:1.06	1.13:1.07				
E0C3	1.0224:1.0132	1.12:1.07	1.11:1.07	1.11:1.06	1.13:1.07				
30C4	1.0229:1.0143	1.12:1.07	1.11:1.07	1.11:1.06	1.13:1.07				
OC4	1.0329:1.0192	1.12:1.07	1.11:1.07	1.11:1.06	1.13:1.07				
	(a)	(b)	(c)	(a)				

- (a) Cycles 5-6 and subsequent repeat cycles 3-4 for the fuel.
- (b) Cycles 5-6 and subsequent repeat cycles 3-4 for the inner blankets.
- (c) Cycles 5-8 and subsequent repeat cycles 1-4.
- (d) Assume cycle 5 = 1.12:1.07. Cycles 6-10 and subsequent repeat cycles 1-5.

TABLE 4.3-11

RADIAL BLANKET POWER AND BURNUP HISTORY HIGHEST POWER ASSEMBLY (#1)

	Average Rod		Peak	Rod	Peak Power	Peak Eurnup
	Power(kw)+	Burnup(a/o)+	Power(kw)+	Burnup(a/o)+	(kw/ft)	(a/o)
Initial:			14:14:			
SOC1 EOC1 (128 fpd) SOC2 EOC2 (200 fpd) SOC3 EOC3 (275 fpd) SOC4 EOC4 (275 fpd)	10.78 13.19 13.37 16.67 17.96 21.46 20.03 22.67	0.0 0.075 0.075 0.235 0.235 0.536 0.536	16.55 19.59 19.86 24.00 25.68 29.68 27.62 30.65	0.0 0.114 0.114 0.347 0.347 0.770 0.770	6.37 7.83 7.94 9.92 10.58 12.53 11.66	0.0 0.241 0.241 0.749 0.749 1.695 1.695 2.737
'Equilibrium":						
SOC5 EOC5 (275 fpd) SOC6 EOC6 (275 fpd) SOC7 EOC7 (275 fpd) SOC8 EOC8 (275 fpd)	10.89 15.65 14.45 17.84 20.97 23.91 22.31 24.59	0.0 0.187 0.187 0.430 0.430 0.783 0.783	16.44 22.27 20.89 25.10 29.60 32.80 30.50 33.03	0.0 0.272 0.272 0.618 0.618 1.108 1.108	6.33 9.13 8.57 10.56 12.43 13.99 13.01 14.23	0.0 0.580 0.580 1.352 1.352 2.465 2.465 3.634

⁺ total power and burnup in full 64" blanket rod.

TABLE 4.3-12 $\label{eq:axial_peak-to-average_power_factors} \text{AXIAL PEAK-TO-AVERAGE POWER FACTORS, } \textbf{F}_{Z}^{N}$

(Normalized to 1.0 Over 36-inch Active Core Height)

Time-in-Life	Peak FZ								
	Clean Fuel(*)	Fuel With CR Influence(b)	Row 2, 4 Inner Blanket	Row 6, 8 Inner Blanket	Radial Blanket Row 1	Radial Blanket Row 2			
8001	1,282	1.381	1.280	1.325	1.290	1.273			
EOC1	1.255	1.309	1.340	1.377	1.331	1.331			
80CZ	1,262	1.347	1.342	1.395	1.334	1.332			
ECC2	1.210	1.210	1.371	1.370	1.344	1.353			
EDC3	1.271	1.381	1.276	1.306	1.373	1.373			
£0C3	1.230	1.269	1.365	1.377	1.376	1.387			
8004	1.242	1.356	1.369	1.426	1.383	1.391			
EOC4	1.186 (c)	1.193 (c)	1.375 (c)	1.360 (c)	1,359	1.378			

(a) applicable to all core fuel assemblies excluding those directly adjacent to R7C control rods.

(b) applicable to those fuel assemblies directly adjacent to R7C control rods. Note, first year of life (i.e. cycles 1, 3,...) values should be applied to freshly refueled R6C fuel assemblies.

(c) cycles 5-6, and subsequent, assumed to repeat cycles 3-4 for the fuel and inner blankets.

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TABLE 4.3-13

CRBRP POWER DISTRIBUTION UNCERTAINTY (%)
FUEL ASSEMBLIES

		CLEAN FU	EL ZONES	41111	FUEL ZONES AWACENT TO INSERTED RIC CR			
	Peak Power Density	Power Density At Top Of Core	Rod Power	Assembly Power	Peak Power Density (near/far) ^a	Power Density at Top of Core (near/far)	Rod Power (near/far)a	Assembly Power
STATISTICAL								
Experimental (30) Criticality Fissile Content (tolerance)	+7 +1 +3	+7 +1 +3	+7 +1 +3	+7 +1 +3	±7 ±4/±1 ±3	±7 ±0/±3 ±3	±7 ±4/±i ±3	+7 +2 +3
SUBTOTAL (RMS)	+7.7	+7.7	+7.7	<u>+7.7</u>	+8.6/+7.7	+7.6/+8.2	+8.4/+7.7	+7.9
NON-STATISTICAL (DIRECT)C								
Modeling Control Rod Banking Power Level/Dead Band ZPPR-7 Tilt (BDL)	+2 +2 +3 f	+10 +2 +3 7	+2 +2 +3 7	+1 +2 +3 7	+3/-59 +4/+29 +3 f	+15 ^e +1 +3 7	+4/+1 ⁹ +4/+2 ⁹ +3	+2 ⁹ +3 ⁹ +3 f

anear refers to side of F/A directly adjacent to inserted R7C CR; far refers to far side of F/A adjacent to R7C CR.

bstatistical uncertainties combine by quadrature.

cnon-statistical uncertainties combine directly .

dnot applied simultaneously with 15% overpower.

eEØL value with substantial portion of R7C control rods withdrawn. BØL apply +25+5 on far side of F/A adjacent to R7C CR.

fdirect bias power down 3% in F/A #s 9, 10, 13-17, 23, 25, 37, 38, 41-45, 51 and 53; bias power down 1% in F/A #s 8, 11, 19, 36, 39, 47, 65, 68, 101 and 104 (BØC1, BØC3, BØC5,... only); bias power down 1% in F/A #62 at BØC2 and F/A #'s 62 and 98 at BØC4, BØC6,....

g for EBC, use corresponding clean fuel zone uncertainty.

TABLE 4.3-14

CRBRP INNER BLANKET POWER DISTRIBUTION UNCERTAINTY (%)

	1 2	Beginning-Of-Life				End-Of-L	ife .	
	Peak- Power Density	Power Density At Top Of Core (36")	Rod Power	Assy. Power	Peak- Power Density	Power Density At Top Of Core (36")	Rod Power	Assy. Power
OMSTATISTICAL (Direct) (a								
Experimental	<u>-10</u>	+7 <u>+</u> 10	+2+10	+2 <u>+</u> 10	-5 <u>+</u> 5	+2 <u>+</u> 5	-2 <u>+</u> 5	-2 +5
Heavy Metal Content	±1	<u>+</u> 1	<u>+</u> 1	±1	<u>+</u> 1	±1	<u>+1</u>	<u>+</u> 1
U-235 Content	±1	<u>+</u> 1	<u>+</u> 1	±1				-
Modeling	±7	<u>+</u> 11	<u>+6</u>	<u>+</u> 1	+4	<u>+</u> 12	+2	<u>+1</u>
Criticality	+2	<u>+2</u>	+2	+2	<u>+</u> 1	<u>+</u> 1	±1	±1
Control Rod Banking	+2	+2	+2	+2	+2	+2	+2	+2
Reactor Power(b)	±3	<u>+3</u>	±3	+3	<u>+</u> 3	<u>+</u> 3	+3	+3
Non-Pellet Heating(c)	-5	-5	-5		-2.5	-2.5	-2.5	
TOTAL	-5+26	+2+30	-3+25	+2 +20	-7.5 <u>+</u> 16	-0.5+24	-4.5+14	-2 <u>+1</u>

⁽a) Nonstatistical uncertainties combine directly.

4.3-113

⁽⁵⁾ Not applied simultaneous with 15% overpower.

⁽c) Gamma heating in clad, Na and duct. Apply only to calculation of pellet (stack) power density.

4.3-114

TABLE 4.3-15

CRBRP RADIAL BLANKET POWER DISTRIBUTION UNCERTAINTY (%)

	1 - 4	Beginning-Of-Life				End-Of-L	.1fe	
	Peak- Power Density	Power Density At Top Of Core (36")	Rod Power	Assy. Power	Peak- Power Density	Power Density At Yop Of Core (36")	Rod Power	Assy. Power
NONSTATISTICAL (Direct)(a)								
Row 1:								
Experimental Heavy Netal Content U-235 Content Modeling Control Rod Banking Reactor Power(b) Non-Pellet Heating(c)	+2+9 +1 +1 +1 +1 +2 +3 -5	+9+9 +1 +1 -3+5 +2 +3 -5	+4+9 -2+5 -2+5 -3 -5	# 1000000000000000000000000000000000000	-4+7 -1	+3+7 +1 -3+8 +2 +3 -3	-2+7 -2+3 -2+3 -2+3 -3	-2+7 +2 +2 +2 +2 193
TOTAL	-3+23	<u> ना</u> रा	-3+21	+4+18	-7 <u>+20</u>	-3 <u>+</u> 21	-7+16	-2H5
Experimental Heavy Metal Content U-235 Content Modeling Control Rod Banking Reactor Power(b) Non-Pellet Heating(c)	+10+14 +11 +11 +17 +22 +33 -5	+18+14 +1 +1 -6+5 +2 +3 -5	+13+14 +1 +1 -2+5 +2 +3 -5	+13+14 +1 +1 +1 +2 +2 +2 +3	+5 +8 +7 +7 +2 +3 -3	+13+8 +1 -6+8 +2 +3 -3	+7 +8 -1 -2+3 -2 +3 -3	+7 +8 +1 +2 +2 +2 +2 +3
TOTAL	+5+28	+7+26	+6+26	+13+23	+2 +21	+4 +22	+2+17	-+7+1

a) Nonstatistical uncertainties combine directly.

b) Not applied simultaneous with 15% overpower.

c) Garma heating in clad, Na and duct. Apply only to calculation of pellet (stack) power density.

TABLE 4.3-16

CRBRP DOPPLER CONSTANTS

(-T dk/dT * 10⁴)

	Fue1	Inner(a) Blankets	Radial(a) Blankets	Lower Axial Blanket	Upper Axia Blanket
вост	20,8	44.0	11.8	1.90	0.68
EOC1	-25.8	47.6	12.4	2.10	0.74
BOC2	25.3	45.9	11.7	2.26	0.69
EOC2	25.8	49.3	12.0	2.38	0.88
B0C3	24.3	40.6	15.3	1.99	0.68
EOC3	24.6	47.7	14.9	2.32	0.83
BOC4	23.6	44.6	13.1	2.68	1.00
EOC4	24.2	45.9	12.8	2.56	1.16

(a) Includes axial extensions

TABLE 4.3-17

CRBRP VOIDED DOPPLER CONSTANTS

 $(-T dk/dT * 10^4)$

	Fuel	Inner(a) Blankets	Radial (a) Blankets	Lower Axial Blanket	Upper Axial Blanket
вост	16.6	35.4	9.9	1.6	0.6
EOC4	15.8	35.1	10.8	2.1	0.9

(a) Includes axial extensions

TABLE 4.3-18

NODAL DOPPLER CONSTANTS

BOC1

(T DK/DT)

UPPER	LIDDED AVIAL	HODED
EXTENSION	UPPER AXIAL BLANKET	UPPER EXTENSION
.5110E-04	6780E-04	2359E-04
INNER BLANKET	Fue1	RADIAL BLANKET
4284E-03	2471E-03	1373E-03
7519E-03	4391E-03	2168E-03
1272E-02	7865E-03	3340E-03
1139E-02	7098E-03	2899E-03
6084E-03	3942E-03	1471E-03
LCCCR	LOWER	LOWER
EXT SION	AXIAL BLANKET	EXTENSION
1459E-03	1904E-03	3213E-04

56 |

TABLE 4.3-19

TEMPERATURE DEPENDENCE OF DOPPLER CONSTANT

		Uniform temperature of fueled core, K	300	2000	3000	4000	5000
4.3	561	Reactivity change, Δk from 1000 K core, as computed by FX-2 threeterm temperature dependence formula	+.004727	002744	004331	005443	006296
4.3-118	56	Reactivity change, Δk^* using T-1 extrapolation of data between 300° K and 1000° K	+.004727	002721	004313	005443	006319

^{*}Note that Δk is the integrated inverse temperature-dependent Doppler reactivity coefficient such that $\Delta k = -.0.003926$ ln (TFinal/TInitial)

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TABLE 4.3-20

CRBRP REGIONWISE SODIUM VOID REACTIVITY

(\$)(a)

						Post	Maximum tive Void	Worth
	Fue1	Inner(b) Fuel Blankets	Radial(b) Blankets	Lower Axial Blanket	Upper Axial Blanket	Fuel	Inner Blankets	Total
B0C1	+0.02	+1.38	-0.79	-0.27	-0.15	1.51	1.40	2.91
EOC1	+0.28	+1.43	-0.72	-0.25	-0.16	1.60	1.46	3.06
80C2	+0.51	+1.45	-0.67	-0.27	-0.15	1.76	1.48	3.24
EOC2	+0.82	+1.51	-0.58	-0.23	-0.17	1.89	1.55	3.44
BOC3	+0.28	+1.36	-0.81	-0.28	-0.15	1.60	1.36	2.96
EOC3	+0.79	+1.47	-0.63	-0.25	-0.16	1.77	1.49	3.26
BOC4	+1.20	+1.48	-0.56	-0.27	-0.15	2.10	1.50	3.60
EOC4	+1.56	+1.61	-0.46	-0.22	-0.20	2.31	1.64	3.95

⁽a) Beff = 0.0034

(b) Includes axial extensions

TABLE 4.3-23

CRBRP UNIFORM RADIAL EXPANSION COEFFICIENTS

	Cents	per Mil of Outw	ard Radial Mo	tion
	B0C-1	E0C-2	B0C-3	EOC-4
All Control Rods Out	-0.461	-0.441(1)	-0.459	-0.448(1)
6 Row 7 Corner Rods In	-0.427(2)		-0.426(2)	
All 15 Control Rods In	-0.422(3)			-0.390(3)

- (1) Recommended values for end-of-cycle conditions.
- (2) Recommended values for beginning-of-cycle conditions.
- (3) Refueling conditions.

TABLE 4.3-24

RADIAL MOTION REACTIVITY COEFFICIENTS (BEGINNING OF CYCLE ONE -- HOT STANDBY)

AXIAL LOC	ATION			,	CEN	TS PER	INCH OF	INWARD	RADIA	L MOTIO	M				
Inches abo		Row 2	Row 3	Row 4	Row 5	Row6A	Row 6B	Row 7	Row 8A	Row 88	Row BC	Row 9	Row 10	Row 11	Row 1
assembly)	rue i	Blkt. Fue	Fue1	Blkt.	. Fuel	Blkt.	Refuel*	efuel*Fuel F	Fuel Fuel	1 Fuel B	Blkt.	Fuel	Fuel	Radial Blkt.	Redia Blkt
	107.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	+0.01	0.0
Upper Axial	103.C	0.0	0.0	0.0	0.0	0.0	0.0	-0.01	0.0	+0.01	0.0	+0.01	+0.1	+0.11	6.0
Blanket	97.0	+0.01	-0.01	0.0	-0.01	-0.01	0.0	-0.07	0.0	+0.05	0.0	+0.08	+0.7	+1.10	+0.29
-	93.0	+0.08	-0.18	-0.03	-0.39	-0.12	-0.07	-1.44	-0.08	+1.08	+0.19	+1.45	+10.5	+5.30	+1.13
	87.0	+0.43	-0.59	-0.16	-1.34	-0.67	-0.47	-4.99	-0.29	+3.71	+1.51	+4.88	+36.0	+11.44	+2.5
	81.0	+0.91	-1.02	-0.35	-2.35	-1.48	-1.07	-9.27	-0.53	+6.79	+3.53	+8.68	+64.5	+15.27	+2.8
Core Zone	75.0	+0.97	-1.03	-0.38	-2.43	-1.67	-1.21	-10.29	-0.58	+7.40	+4.03	+9.14	+67.6	+15.06	+3.4
	69.0	+1.02	-1.13	-0.40	-2.72	-1.67	-1.36	-11.88	-0.67	+8.52	+4.45	+10.34	+76.0	+19.14	+3.7
	63.0	+0.55	-0.73	-0.22	-1.79	-1.06	-0.75	-7.95	-0.45	+5.69	+2.34	+6.80	+49.1	+16.56	+3.7
Lower Axial Blanket	57.0	+0.14	-0.23	-0.06	-0.56	-0.31	-0.21	-2.50	-0.14	+1,85	+0.46	+2.24	+16.0	+8.76	+1.90
	50.0	+0.01	0.0	-0.01	0.0	-0.04	-0.02	0.0	0.0	+0.03	+0.03	+0.05	+0.5	+0.76	+0.19
+	43.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	+0.02	0.0
Row Total	-	+4.12	4.92	-1.61	-11.50	-7 23	-5.16	-48 40	-2 74	155 13	+16.54	143 67	+321 0	103 53	+10.1

^{*}Six refueling locations contain blanket assemblies in cycle one.

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TABLE 4.3-25

RADIAL MOTION REACTIVITY COEFFICIENTS (END OF CYCLE TWO -- ALL RODS OUT)

AXIAL LOCA	MOITA				CEN	TS PER	INCH O	INWAR	D RADIA	L MOTIO	H				
Inches abo		Row 2	Row 3	Row 4	Row 5	Row6A	Row 6B	Row 7	Row 8A	Row 88	Row 8C	Row 9	Row 10	Row 11	Row
bottom of fuel assembly)		Blkt.	. Fuel	8,1kt.	Fuel	Blkt.	. Refuel*	Fuel	Fuel Fuel	1 Fue1	Blkt.	Fuel	Fuel	Radial Blkt.	Radi. Blkt
-+-	107.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	+0.01	-0.01
Upper Axial Blanket	103.0	0.0	0.0	0.0	0.0	0.0	0.0	-0.01	+0.01	+0.01	0.0	+0.03	+0.1	+0.12	+0.01
	97.0	0.0	-0.01	0.0	-0.02	0.01	+0.03	-0.07	+0.06	+0.08	-0.04	+0.19	+0.8	+1.22	+0.34
	93.0	+0.03	-0.17	-0.05	-0.30	-0.11	+0.35	-0.92	+0.77	+1.20	+0.24	+2.78	+10.4	+5.93	+1.35
	87.0	+0.17	-0.55	-0.40	-0.95	-0.79	+0.82	-2.73	+2.31	+3.69	+3.33	+8.58	+32.9	+12.85	+3.02
	81.0	+0.33	-0.85	-0.79	-1.46	-1.52	+1.12	-4.06	+3.42	+5.51	+6.69	+13.08	+51.0	+17.31	+3.33
Core	75.0	+0.32	-0.80	-0.74	-1.37	-1.40	+1.05	-3.69	+3.12	+5.02	+5.98	+12.12	+47.5	+16.88	+4.06
	69.0	+0.34	-0.87	-0.81	-1.50	-1.52	+1.16	-4.06	+3.42	+5.50	+6.37	+13.22	+51.5	+18.05	+4.45
	63.0	+0.19	-0.58	-0.45	-1.01	-0.84	+0.86	-2.74	+2.31	+3.71	+3.24	+8.79	+33.7	+13,58	+4.50
Lower Azial Blanket	57.0	+0.05	-0.19	-0.12	-0.32	-0.23	+0.29	-0.89	+0.77	+1.25	+0.41	+2.97	+11.3	+6.92	+2.25
	50.0	+0.01	0.0	-0.02	0.0	-0.03	-0.01	-0.01	+0.02	+0.04	+0.02	+0.10	+0.4	+0.65	+0.2
	43.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	+0.01	-0.0
Sow Total		+1.44	-4.02	-3.38	-6.93	-6.45	+5.57	-19.18	+16.21	+26.01	+26.24	+61.86	+239.6	+93.53	+23.5

*Six refueling locations contain three fuel and three blanket assemblies in cycle two.

TABLE 4.3-26

CRBRP INHERENT FEEDBACK REACTIVITY (\$)

STARTUP FROM HOT-STANDBY CONDITIONS* TO 40% POWER/40% FLOW*

	Feedba	ick (\$)
	BOC1	EOC4
Doppler		
Fuel	-0.385	-0.295
Axial Blankets	-0.008	-0.013
Inner Blankets	-0.259	-0.547
Radial Blankets	-0.048	-0.100
Total	-0.700 ± 0.084	-0.955 ± 0.115
Uniform Radial Expansion	-0.062 <u>+</u> 0.012	-0.065 ± 0.013
Uniform Axial Expansion		
Fuel	-0.219	-0.126
Structure (FA)	+0.023	+0.021
Blankets	+0.020	+0.015
Structure (BA)	+0.004	+0.009
Total	-0.172 ± 0.040	-0.081 ± 0.019
Sodium Density	-0.014 ± 0.004	+0.048 ± 0.014
Total + 1g**	-0.948 ± 0.094	-1.053 ± 0.118

^{* 600°}F isothermal

^{+ 635°}F inlet temperature

^{**}Uncertainty in net feedback includes both nuclear uncertainty in reactivity coefficient and thermal uncertainty.

TABLE 4.3-29 CRBRP PRIMARY CONTROL SYSTEM REQUIREMENTS AND MINIMUM CONTROL WORTHS ($\frac{\wedge \Delta k}{k}$)

PCA Control Requirements		EOC1	BOCZ	E0C5	BOC3	E0C3
Hot-to-Cold*	0.99 ± .29	1.06 ± .30	1.04 + .27	1.10 ± .32	0.98 ± .29	1.07 ± .32
Reactivity Fault	0.54	0.36	0.84	0.20	0.83	0.25
Excess Loaded	1.77	1.17	2.70	0.46	2.56	0.70
Criticality Uncertainty	± .43	± .43	± .43	± .43	<u>+</u> .43	± .43
Fissile Tolerance	± .28	<u>+</u> .28	± .28	± .28	± ,28	± .28
Total	3.30 ± .59	2.59 ± .59	4.58 ± .58	1.76 ± .60	4.37. + .59	2.02 ± .60
Maximum Requirement	3.89	3.18	5.16	2.36	4.98	2.62
Minimum PCA Control Worth (Calculated -20)**						
6-R7C	5.58	5.37	5.82	5.39	5.55	0.75
3-R4C	1.37	1.60	1.62	1.96	1.23	1.86
Stuck Rod	-1.43	-1.44	-1.11	-1.45	-1.12	-1.36
	_					-
Total	5.52	5.53	6.33	5.90	5.66	5.45

^{*} Hot-full-power to refueling temperatures.

$$$ = \frac{\Delta k}{k \cdot \beta \text{ eff}}, \quad \beta = 0.0034$$

^{**} σ = 4%, unbiased.

CRBRP PRIMARY CONTROL SYSTEM REQUIREMENTS AND MINIMUM CONTROL WORTHS (% $\frac{\Delta k}{k}$)

PCA Control Requirements	B0C4	EOC4	80/.5	EOC5	B0C6	EOC6
Hot-to-Cold*	1.00 ± .31	1.06 ± .32	0.98 + .29	1.07 ± .32	1.00 ± .31	1.06 ± .32
Reactivity Fault	1.04	0.21	0.98	0.35	1.02	0.21
Excess Loaded	3.29	0.53	2.86	1.14	3.23	0.51
Criticality Uncertainty	<u>+</u> .43	± .43	<u>+</u> .43	± .43	± .43	± .43
Fissile Tolcrance	<u>+</u> .28	<u>+</u> .28	+ .28	<u>+</u> .28	<u>+</u> .28	<u>+</u> .28
	-			-		
Total	5 60	1.80 ± .60	4.82 ± .59	2.56 ± .60	5.25 ± .60	1.78 + .60
Maximum Requirements	5.93	2.40	5.41	3.16	5.85	2.38
Minimum PCA Control Worth (Calculated -20)**						
6-R7C	5.94	5.36	5.56	5.12	5.91	5.26
3-R4C	1.87	2.24	1.29	1.75	2.07	2.48
Stuck Rod	-0.82	-1.27	-v.98	-1.25	-0.83	-1.25
	-		-			
Total	6.99	6.33	5.87	5.62	7.15	6.49

* Hot-full-power to refueling temperatures.
**
$$\sigma$$
 = 4%, unbiased.
\$ = $\frac{\Delta k}{k \cdot \beta_{eff}}$, β = 0.0034

TABLE 4.3-30

CRBRP SECONDARY CONTROL SYSTEM REQUIREMENTS AND MINIMUM CONTROL WORTHS (% $\frac{\Delta k}{k}$)

SCA Control Requirement	BOC1	ECC1	BOC2	E0C2	BOC3	EOC3
Hot-to-Cold* Reactivity Fault	0.67 <u>+</u> .27 0.54	0.73 ± .29 0.36	0.71 <u>+</u> .27 0.84	0.78 ± .30 0.20	0.66 ± .27 0.83	0.75 ± .30 0.25
Total	1.21 ± .27	1.09 ± .29	1.55 ± .27	0.98 ± .30	1.49 ± .27	1.00 ± .30
Maximum Requirement	1.48	1.38	1.82	1.28	1.76	1.30
Minimum SCA Control Worth (Calculated -20)**						
6-R7F	4.01	4.17	4.17	4.30	3.82	4.09
Stuck Rod	-1.34	-1.40	-1.40	-1.44	-1.28	-1.37
			-			
Total	2.67	2.77	2.77	2.86	2.54	2.72

^{*} Hot-full-power to standby temperature. ** σ = 4%, unbiased.

$$\$ = \frac{\Delta k}{k \cdot \beta \text{eff}}, \quad \beta = 0.0034$$

TABLE 4.3-30 (Continued)

CRBRP SECONDARY CONTROL SYSTEM REQUIREMENTS AND MINIMUM CONTROL WORTHS (% $\frac{\triangle k}{k}$)

SCA Control Requirements	SOC4	EOC4	S0C5	EOC5	5006	EOC6
Hot-to-Cold*	0.70 ± .29	0.76 ± .30	0.66 ± .27	0.75 ± .30	0.70 ± .29	0.76 ± .30
Reactivity Fault	1.04	0.21	0.98	0.35	1.02	0.21
Total	1.74 ± .29	0.97 ± .30	1.64 ± .27	1.10 ± .30	1.72 ± .29	0.97 ± .30
Maximum Requirement	2.03	1.27	1.91	1.40	2.61	1.27
Hinimum SCA Control Worth (Calculated -20)**						
6-R7F	4.17	4.30	3.92	4.14	4.33	4.40
Stuck Rod	-1.40	-1.44	-1.31	-1.39	-1.45	-1.47
	-	_		-	-	-
Total	2.77	2.86	2.61	2.75	2.88	2.93

^{*} Hot-full-power to standby temperature. ** σ = 4%, unbiased

$$$ = \frac{\Delta k}{k \cdot \beta_{eff}}, \beta = 0.0034$$

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TABLE 4.3-43

ZPPR-7 CONTROL ROD WORTH CALCULATION-TO-EXPERIMENT RATIOS*

	Beginning-of-Life Phase B	End-of-Life Phase C		
Row 4	0.916 (0.963)	0.906 (0.973)		
Row 7 - Flat	0.898 (0.987)	0.887 (0.952)		
Row 7 - Corner	0.992 (1.074)	0.905 (0.986)		

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^{*} Calculated with standard two-dimensional (hexagonal planar geometry) coarse-mesh direct eigenvalue difference diffusion theory methods using 9-group ENDF/B-III data. Values in () from four-mesh per ZPPR drawer diffusion calculations.

TABLE 4.3-44

COMPARISON OF NUCLEAR PARAMETERS FOR CRBRP AND FFTF

	CRBRE	FFTF
LAYOUT		
Number of Fuel Assemblies	156	73
Inner Enrichment Zone		28
Outer Enrichment Zone		45
Number of Test Loop Locations		9
Number of In-Core Control Rods	15	9
Number of Inner Blanket Assemblies	82	
Number of Radial Blanket Assemblies	150	
Number of Radial Reflector Assemblies		108(1)
Number of Removable Radial Shields	306	4.5
DIMENSIONS		
Assembly Pitch (meters)	0.1209	0.1198
Core (2) Equivalent Diameter (meters)	2.019	1.200
Core (2) Cross-Sectional Area (meters)	3.203	1.131
Active Fuel Height (meters)	0.9144	0.9144
Height-to-Diameter Ratio	0.453	0.762
Axial Blkt. Height, Upper/Lower (meters)	0.3556/0.3556	
Inner and Radial Blanket Height (meters)	1.6256	
INITIAL CORE ENRICHMENTS ALD FUEL MASSES		
Enrichments (Pu/U+Pu)		
Inner Enrichment Zone	0.328	0.224
Outer Enrichment Zone		0.274
Enrichment Ratio (Outer/Inner)	N/A	1.22
Isotopic Composition of Feed Plutonium		
Pu-238	0.0006	
Pu-239	0.8604	0.864
Pu-240	0.1170	0.117
Pu-241	0.0200	0.017
Pu-242	0.0020	0.002

^[1] Includes positions for as many as fifteen peripheral shim rods.

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^{(2) &}quot;Core" includes fuel, inner blankets and in-core control rods.

TABLE 4.3-44 (Continued)

Peak Neutron Flux (4) (neutrons/cm ² sec) Fuel and Inner Blanket Zone	CRBRP	FFTF
Total Flux Fast Flux (energy > 0.1 MeV)	5.5×10^{15} 3.4×10^{15}	8 × 10 ¹⁵ 5 × 10 ¹⁵
Radial Blanket Zone Total Flux Fast Flux (energy > 0.1 MeV)	3.9×10^{15} 2.4×10^{15}	-

⁽⁴⁾ Maximum value attained at any time in life and at any point in the zone.

TABLE 4.3-45

COMPARISON OF REACTIVITY COEFFICIENTS FOR CRBRP AND FFTF

Doppler Constant (- $T \frac{dk}{dT}$)		CRBRP	FFTF
Initial Core, BOC1	Fuel Inner Blanket Radial Blanket Axial Blankets	0.0026 0.0044 0.0012 0.0003	0.0050
Initial Core, EOC2	Fuel Inner Blanket Radial Blanket Axial Blankets	0.0026 0.0049 0.0012 0.0003	0.0055
Equilibrium Core, BOL	Fuel Inner Blanket Radial Blanket Axial Blankets	0.0024 0.0041 0.0015 0.0003	0.0050
Equilibrium Core, EOL	Fuel Inner Blanket Radial Blanket Axial Blankets	0.0024 0.0046 0.0013 0.0004	0.0055
Core-Average Sodium Density	Coefficients (cents/OF)	
First Cycle		-0.006	-0.049
Uniform Radial Expansion Coe	fficient (cents/OF)		
First Cycle		-0.177	-0.21
Uniform Axial Expansion Coef	ficient (cents/OF)		
First Cycle		-0.038	-0.038

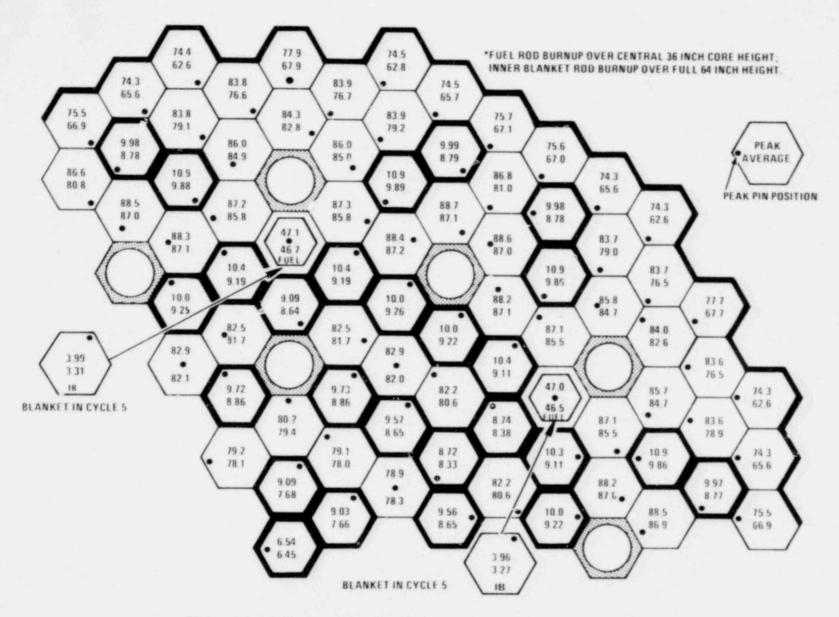
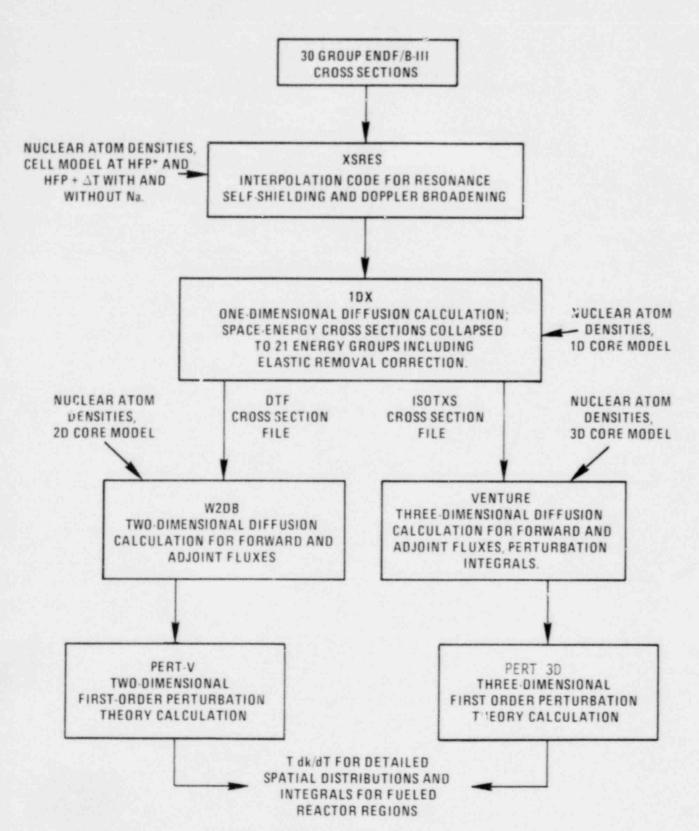


Figure 4.3-25. Peak and Average Rod Burnup* (MWD/KG) Cycles 5-6



*HFP = HOT FULL POWER TEMPERATURE CONG. JONS

Figure 4.3-26. Flow Chart for Doppler Calculations

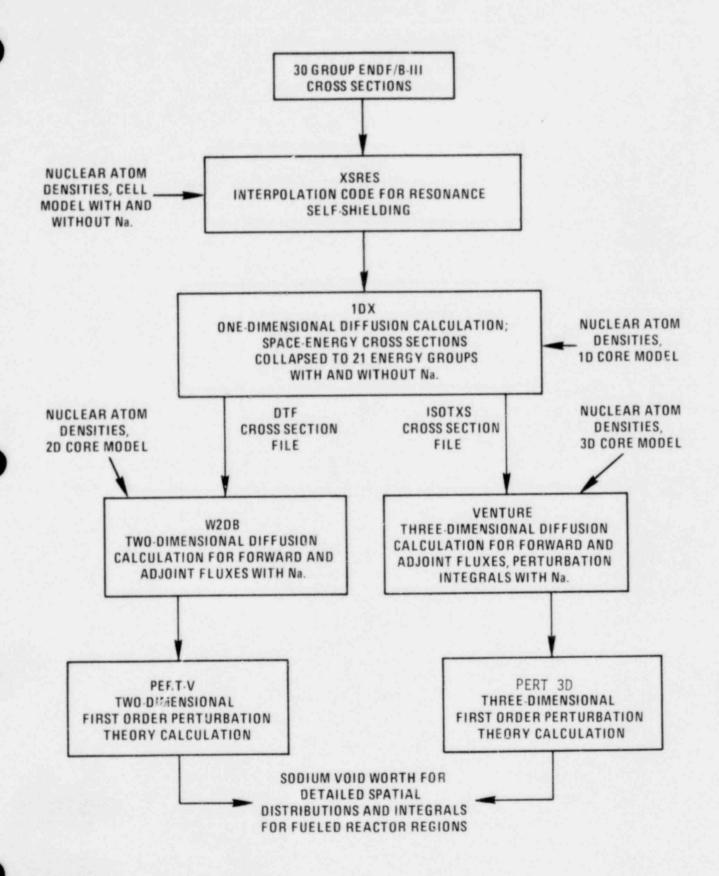


Figure 4.3-28. Flow Chart for Sodium Voiding Reactivity Worth Calculations

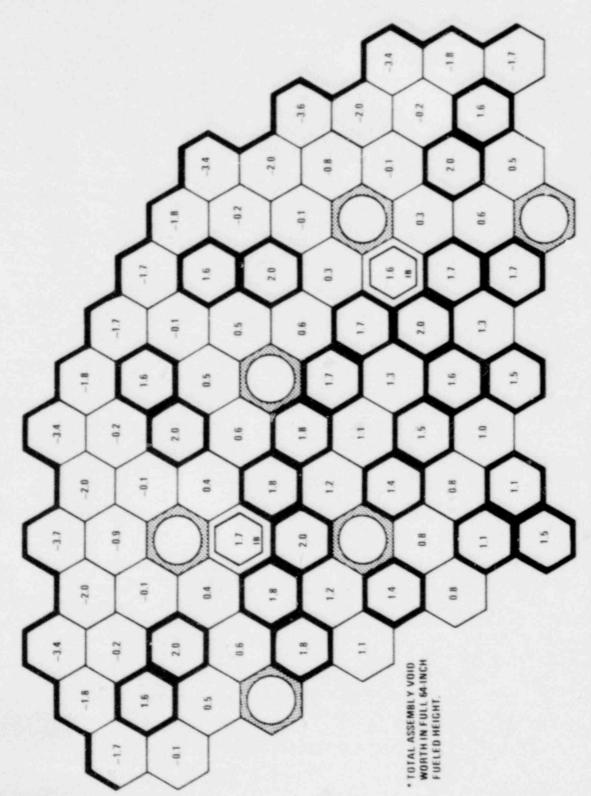


Figure 4.3-29a. CRBRP Sodium Void Worth By Assembly Beginning of Cycle One* (¢)

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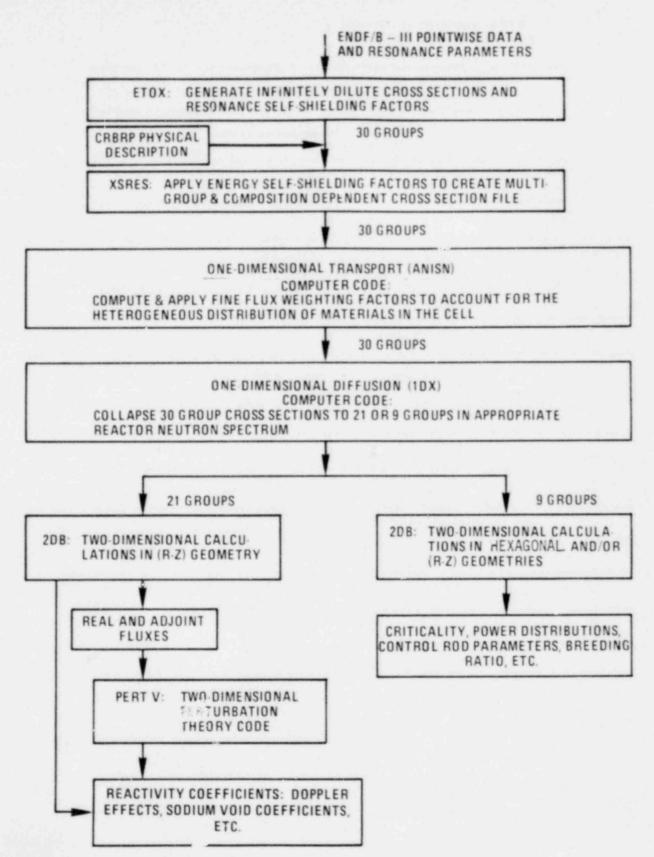


Figure 4.3-54. Calculational Scheme for Analysis of CRBRP

1544-53

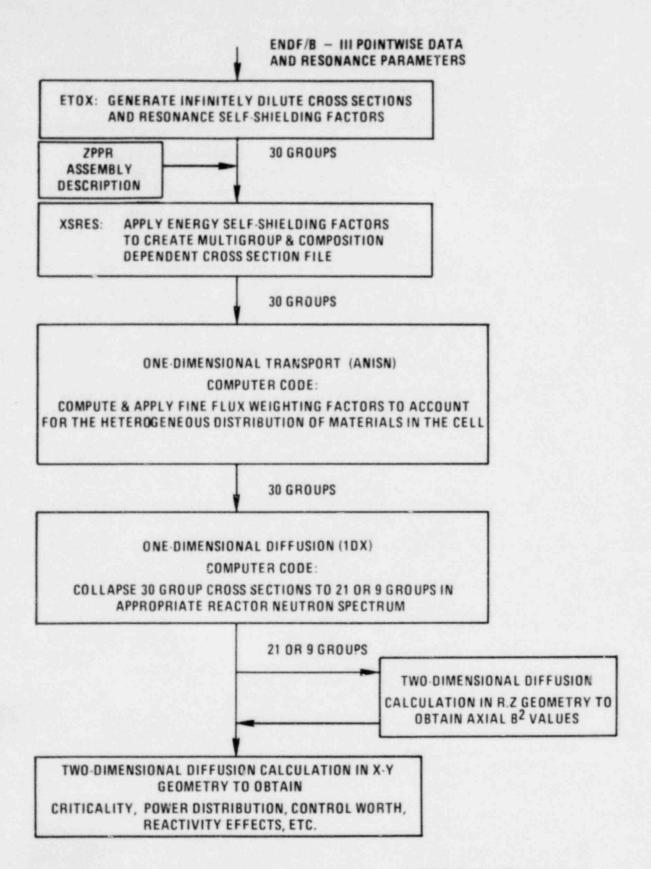


Figure 4.3-55. Calculational Scheme for Evaluation of ZPPR Critical Experiments
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Amend. 51 Sept. 1979 Since the absorber pellet centerline temperature $(T_{abs}, \boldsymbol{\xi})(*)$, is dependent on the absorber pellet surface temperature $(T_{abs}, \boldsymbol{s})$ as a boundary condition, the iterative process on T_{abs} , avg actually involves T_{abs} ,s. Based on the heat transfer across the absorber pellet-to-cladding gap, considering the bond (helium) thermal conductivity and the (hot) gap size, the surface temperature can be expressed (under nominal rod operating conditions), as the following:

$$T_{abs,s} = T_{cl, i} + \frac{Q_{abs}}{2\pi K_{gap} \lambda Z} \ln \left(\frac{R_i}{R_p}\right)$$
 (4.4.2.8-11)

where T_{cl-i} is the cladding inside temperature;

 Q_{abs} is the absorber heat generation within a length ΔZ ;

R; is the hot cladding inside radius based on Equation (4.4.2.8-7);

 R_p as indicated by Equations (4.4.2.8-9) and (4.4.2.8-10), is a function of $T_{abs,s}$;

Kgap is the gap (helium) thermal conductivity (see following Equation 4.4.2.8-14).

The gap thermal conductivity is again dependent on the absorber pellet surface temperature Tabs,s, since it is a function of the average gap temperature which can be defined as,

$$T_{gap, avg} = \frac{T_{abs,s} + T_{c1,i}}{2}$$
 (4.4.2.8-13)

*The absorber centerline temperature, Tabs, c, is calculated based on the general differential equation representing the heat transfer through the absorber pellet.

$$K_{abs} \frac{d^2T}{dr^2} + \frac{K_{abs}}{r} \frac{dT}{dr} + q_{abs}''' = 0$$
 (4.4.2.8-12)

where K_{abs} is the absorber (B₄C) thermal conductivity reported in Section 4.4.2.8.8; and

 $q_{abs}^{""}$ is the volumetric heat generation rate in the pellet.

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The iterative procedure on the hot pellet radius (R_p) is initiated by the first guestimate of T_{abs} , s from Equation (4.4.2.8-11), assuming $R_p = (R_p)$ cold and T_{gap} , $avg = T_{cl}$. This first guestimate value is used next to estimate values of R_p by Equations (4.4.2.8-9) and (4.4.2.8-10), and T_{gap} , avg by Equation (4.4.2.8-13). As mentioned previously, this process is repeated until the value R_p calculated in two successive iterations converges within a prefixed limit; with the established values of R_p and R_i (see Equation 4.4.2.8-7), the hot gap is obtained by Equation (4.4.2.8-6).

Experimental values of the control rods gap conductance have been determined (Reference 20) to be consistent with the method used.

The helium thermal conductivity is given by (Ref. 21).

$$K = 0.097 + 7 \times 10^{-5}T$$
 (4.4.2.8-14)

where K is in Btu/hr-ft-oF and T in oF.

The above equation is valid for T > 700 °F.

4.4.2.8.7 Fuel Thermal Conductivity

The following equation (Ref. 18) is used in evaluating the fuel thermal conductivity in the fuel assemblies:

$$K = FP \left[\frac{1}{A+BT} + CT^3 \right]$$
 (4.4.2.8-15)

where K =thermal conductivity, $W/m^{O}K;$

T = temperature, °K;

$$FP = \frac{1.079 (1-P)}{(1.0+0.5P+4.62P^2)}$$

P = fractional porosity (1-fraction of theoretical density);

$$A = -6.0656 \times 10^{-4}$$

$$B = 3.04212 \times 10^{-4}$$

$$C = 0.75137 \times 10^{-10}$$

A review of the effects of plutonium weight percent on conductivity revealed that for the range 0.12 ≤Pu ≤0.3, such effect was within the range of experimental uncertainties, and therefore, the thermal conductivity could be considered independent of plutonium content. No experimental conductivity data exist for a plutonium content corresponding

was in good agreement with ARD correlation. The root mean square deviation of the HEDL cubic fit was 0.2643. The arc-tangent curve had a much larger spread (0.418), while the hyperbolic relationship:

$$Q'_{m} = 19.5$$
 $G \le 5 \text{ mils}$ $Q'_{m} = 13.60 + \frac{12.96}{G-3.11}$ $G>5 \text{ mils}$ $G>5 \text{ mils}$

had a root mean square deviation of 0.2953, i.e., comparable to the cubic fit. Finally the HEDL data were officially published (Reference 37), where the hyperbolic correlation (Equation 4.4.2.8-20) was selected as the most accurate fit while the numerical constants were slightly readjusted.

Figure 4.4-29 shows Equation 4.4.2.8-20 and the experimental data. The ±0.92 kw/ft band eariier determined for the cubic polynominal fit is superimposed. As evident from the figure, the uncertainty band is definitely overestimated when the optimum hyperbolic fit is adopted.

Subsequent to the P-19 test, additional power-to-melt data on very low burnup irradiated pins (P-20 test, Reference 38) indicated an improvement of about 20% in the value of the power-to-melt for pre-irradiated pins to 0.3% burnup, which can be achieved by initial operation at reduced power. Based on this experimental evidence, several programmed startups (combinations of reduced power and holding time) can be utilized to satisfy the nomelting criterion in the high power CRBRP fuel rods. A detailed power-tomelt analysis and preliminary suggestions for a startup procedure are reported in Section 5 of Reference 3. An optimum programmed startup will be selected following final analyses.

4.4.2.8.15 Fuel Restructuring Parameters

The LIFE-III code features a continuous pore migration model which supercades the previous finite restructuring zones approach, and therefore no longer requires the definition of threshhold restructuring temperatures or restructured zone densities.

4.4.2.8.16 Fission Gas Release and Fission Gas Yield

The model employed to predict fission gas release from the fuel pellets is basically an updating and refinement of the HEDL model (Reference 39).

The correlation for fission gas release from non-restructured fuel 51 | as determined in Reference 39 is:

$$F_N = 1 - \frac{1 - \exp(-A_1B)}{A_1A_2B\exp(A_3Q)}$$

(4.4.2.8-24)

where

 F_{N} = fractional gas release from non-restructured fuel

B = local burnup (a/o)

Q = local linear heat generation rate (kw/ft)

 $A_1A_2A_3$ = empirical constants.

The experimental data considered covered the following range of parameters (see Table 4.4-12):

Peak Burnup

Peak Linear Power Fuel Density

Beginning of Life Peak Cladding ID Temperature 837 - 1070°F Diametral Gap Thickness

0.87 - 5.8 a/o3.9 - 16 kw/ft

0.895 - 0.956 theoretical pellet density

0.0022 - 0.008 inch (cold dimensions)

By fitting the correlation to experimental data, the values of the empirical constants were determined as follows:

 $A_1 = 0.5748$ $A_2 = 0.3745$ $A_3 = 0.0911$

Subsequently, the model predictions of total gas release were compared with two sets of experimental data not used in the calibration and equation fitting, thus providing an independent check.

The first set (Reference 40) of data referred to high burnup (up to 12.7 a/o) fuel, the second set (Reference 41) to high cladding temperature (1160-1170°F) rods.

Tables 4.4-13 and 4.4-14 list the additional data for high burnup and high cladding temperature conditions, respectively, which were used 51 Ito verify the validity of the previously determined constants.

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TABLE 4.4-5 FUEL ASSEMBLY COMPONENT PRESSURE DROP DATA LINEAR REGRESSION AMALYSIS

COMPONENT	LINEAR REGRESSION FUNCTION	NO. OF DATA POINTS	OF	STANDARD DEVIATION ABOUT MEAN OF ln(Re)	MEAN OF In(D)	STANDARD DEVIATION ABOUT MEA OF In(D)	N OF
Inlet Hozzle	ln(K) = 0.917705289 ln(Re)	222	13.64	0.3560			0.0841
Inlet Hozzle- Orifice-Shield							
1 Plate 2 Plates 3 Plates 4 Plates 5 Plates	ln(K)=2.352092111n(Re)-1.4521n(D) ln(K)=1.708050221n(Re)-3.2931n(D) ln(K)=2.240082261n(Re)-3.8911n(D) ln(K)=2.293071411n(Re)-4.0321n(D) ln(K)=2.225030721n(Re)-3.6511n(D)	41 73 60 33	13.95 13.73 13.61 13.52 13.45	0.3763 0.3684 0.3560 0.2982 0.2589	1845 3528 4064 4454 4484	0.1256 0.1057 0.1165 0.1040 0.0997	0.0170 0.0472 0.0207 0.0136 0.0165
Shield	ln(K)=0.3988038791n(Re)	17	13.82	0.3768			0.0966
Rod Eundle: Inlet Roa Friction Outlet	K = 0.370 see Table 4.4-6 K = 0.178		entire ra				0.2(*) 0.0524 0.0312,-0.0262 0.2(*)
Outlet Nozzle	ln(K) = .0049504902 ln(Re)	16	13.67	0.7483			0.0450

^(*) A 20% uncertainty was selected as a bounding value (not standard error), since no test data are available. This uncertainty is much greater than the values determined for other components, but the effect on flow rate calculations is negligible since the untested components account for only 1 to 2 psi of the 100 psi total assembly pressure drop.

^{**}D is the hydraulic diameter of the plate flow area.

COMPONENT	CORRELATION	REFERENCE AREA (IN2)	REFERENCE HYDRAULIC DIAMETER (IN)	REFERENCES
Inlet Nozzle	K = 2.504 Re ^{-0.0529}	3.976	2.250	7
Inlet Nozzle-Orifice-Shield:				
1 Plate	K = 10.50 Re ^{-0.0921} D ^{-1.452}	3.976	2.250	7
2 Plates	$K = 5.519 \text{ Re}^{-0.0502} \text{ D}^{-3.293}$			
3 Plates	K = 9.396 Re-0.0823 D-3.891			
4 Plates	$K = 9.909 \text{ Re}^{-0.0714} \text{ p}^{-4.032}$			
5 Plates	K = 9.253 Re ^{-0.0307} D ^{-3.651}			
Shield	$K = 1.490 \text{ Re}^{-0.0388}$	3.976	2.250	7
Rod Bundle:				
Inlet	K = 0.370	6.724	0.1281	11
Rod Friction	f = 84/Re for Re < 1000	6.724	0.1281	4 - 6
	$f = [1.080 \cdot 0.0927 \cdot (1000/Re)^2 + .1694 \cdot (1000/Re)^4] f_c$ where $f_c^{(*)} = 4Log_{10}(2.51/(Re/f_c))$			
Outlet	K = 0.178	6.724	0.1281	11
Outlet Nozzle	K = 1.005 Re-0.0490	5.899	2.116	7

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TABLE 4.4-7
BLANKET ASSEMBLIES COMPONENT HYDRAULIC CORRELATIONS

COMPONENT	CORRELATION		REFERENCE HYDRAULIC DIAMETER (IN)(*)	REFERENCES
Inlet Nozzle	K = 2.504 Re ^{-0.0529}	3.976 (1.767)	2.250 (1.500)	7
Inlet Nozzle Orifice Shield	K = C Re-0.05	3.976 (1.767)	2.250 (1.500)	7,8
Shield	K = 2.0	2.405	1.750	11
Rod Bundle:				
Inlet	K = 0.427	3.956	0.1338	11
Rod Friction	$f = 110/Re \text{ for } Re \le 400$ $f = (110/Re)\sqrt{1-\psi} + (.55/Re^{.25})\sqrt{\psi}$	3.956	0.1338	9
	where $\psi = (Re-400)/4600$ for $400 < R$ f = .55/Re ^{.25} for Re > 5000	te < 5000		
Outlet	K = 0.290	3.956	0.1338	11
Outlet Nozzle	K = 1.005 Re ^{-0.0490}	3.976	2,250	7

^(*) Number outside parentheses refers to inner blanket assemblies; inside parenthesis refers to radial blanket.

TABLE 4.4-8
BASES FOR REACTOR INTERNALS PRESSURE DROPS

MPONENT	NOMINAL PRESSURE LOSS (psi)	LOSS COEFFICIENT	FLOW (1b/hr)10 ⁶	FLOW AREA (ft ²)	BASIS - LIMITATIONS
Reactor Vessel Inlet Plenum	4.25	K=1.19	41.446	8.655	Loss coefficient obtained from the inlet plenum feature model test. +9% uncertainty used in design. $(\Delta P = K W^2/2g\rho\Lambda_f^2)$
Lower Inlet Module	8.66	$(K+\frac{f!}{0})=2.13$	1.096	0.214	Calculated; to be confirmed by radial blanket orificing test. $\pm 20\%$ uncertainty used in design ($\Delta P = (K + \frac{fL}{D}) W^2/2g_P A_f^2$)
Reactor Ve	ssel Outlet Plenum:				
a) UIS	1.78	$(K+\frac{fL}{0})=2.01$	33.986(*)	14.51	Loss coefficient obtained from the integral reactor feature model test. $\pm 3\%$ uncertainty used in design. $(\Delta P = (r + \frac{fL}{D}) \overline{W}^2 / 2g_P A_f^2)$
b) Exit Nozzle	0.43	K=0.29	41.446	13,77	Loss coefficient obtained from the integral reactor feature model test. +7% uncertainty used in design. $(\Delta P = K \overline{W}^2/2g_P A_f^2)$
	Reactor Vessel Inlet Plenum Lower Inlet Module Reactor Ve a) UIS	PRESSURE LOSS (psi) Reactor 4.25 Vessel Inlet Plenum Lower 8.66 Inlet Module Reactor Vessel Outlet Plenum: a) UIS 1.78 b) Exit 0.43	##PONENT PRESSURE LOSS COEFFICIENT Reactor 4.25	PRESSURE LOSS (psi) COEFFICIENT (1b/hr)10 ⁶ Reactor 4.25 K=1.19 41.446 Vessel Inlet Plenum Lowe: 8.66 (K+fl/D)=2.13 1.096 Inlet Module Reactor Vessel Outlet Plenum: a) UIS 1.78 (K+fl/D)=2.01 33.986(*)	PRESSURE LOSS (psi) COEFFICIENT (1b/hr)10 ⁶ FLOW AREA (ft ²) Reactor 4.25 K=1.19 41.446 8.655 Vessel Inlet Plenum Lowe: 8.66 (K+ $\frac{fL}{D}$)=2.13 1.096 0.214 Reactor Vessel Outlet Plenum: a) UIS 1.78 (K+ $\frac{fL}{D}$)=2.01 33.986(*) 14.51

^(*) Based on a total reactor flow of 41.446 x 10^6 lb/hr with 82% flowing up the UIS chimneys. $A_f = flow$ area

$$\rho = density (\frac{g}{cc})$$

f = friction factor

TABLE 4.4-27 CRBRP SECONDARY CONTROL ASSEMBLIES PIN TEMPERATURES HOT CHANNEL/SPOT FACTORS

							He	at Generati	on
(4)		Coolant	F11m	Cladding	Gap	Absorber	Absorber	Cladding	Coolant
DIRECT (+)									
Inlet Flow Mail Subassembly Fl	Idistribution low Maldistribution I Uncertainties Flow Split umferential Variation	1.03 1.05 1.10 1.06 }	1.12 1.58 2.53 ^(*)				1.03	1.03	1.03
Conductivity Subchannel flo Film Heat Tran Cuefficient	isfer	1.02	1.40 1.37 (*)	1.38(*)		1.10	1.03		1.0
Fellet-Claddin Cladding Thick	ng Eccentricity		1.37	1.30					
Conductivity		1.01		1.10	1.13			1.04	
Coolant Proper	and Conductivity	1.01							
JATOT	20 30	1.54 1.58	2.25 3.85(*) 2.48 4.36(*)	1.07 1.26 1.10 1.39(*)	1.13	1.10	1.05	1.06	1.03

⁽⁺⁾ Uncertainties due to physics analysis calculational methods (15% on coolant enthalpy rise and on absorber, cladding and coolant heat generation) are applied directly on nuclear radial peaking factors.

(o) in addition, the assembly inlet temperature will be increased by 16°F, to account for primary loop temperature con-

trol uncertainties.

^(*) For maximum local cladding midwall temperature calculations only.

TABLE 4.4-28

CRBR EXPECTED OPERATING CONDITIONS DURING PLANT LIFETIME

Parameter	Clean & Unplugged Heat Exchangers (New Plant)				Estimated (2 Year Fouling)			Fo		lugged He hangers r Foulir		
	Nominal	Hean	σ	T _{97.7}	Nominal	Mean	σ	T _{97.7}	Nominal	Mean	σ	T _{97.7}
Primary Hot Leg Temperature (°F)	943	946	13	968	950	954	13	976	960	964	13	937
Frimary Cold Leg Temperature (°F)	698	697	13	722	705	704	11	725	714	714	12	735
Primary AT (°F)	245	249	12	273	245	250	12	274	246	250	12	275
Power (MI/t)	975	975		1004	975	975		1004	975	975		1004

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NOTE: Design and control uncertainties are included.

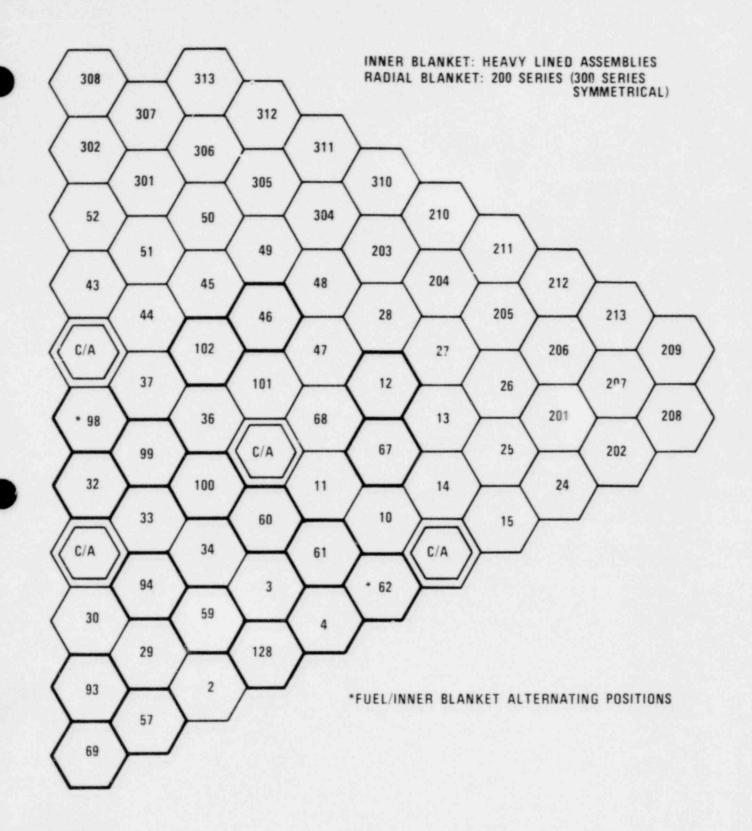


Figure 4.4-9 CRBRP Core 60^o Symmetry Sector and Assemblies Numbering Scheme

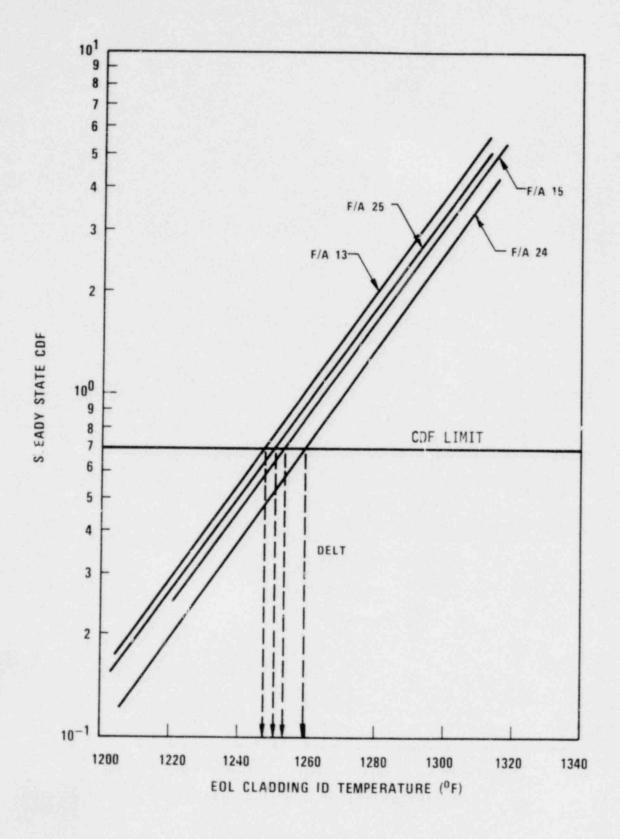


Figure 4.4-10 Typical DELT Determination for First Core Fuel Assemblies 1668-67

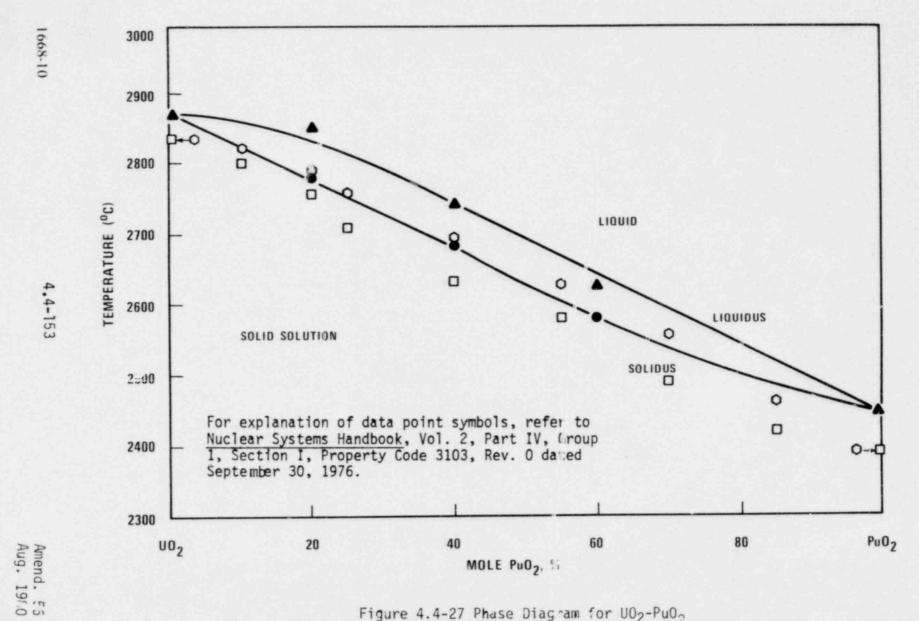


Figure 4.4-27 Phase Diagram for UO2-PuO2

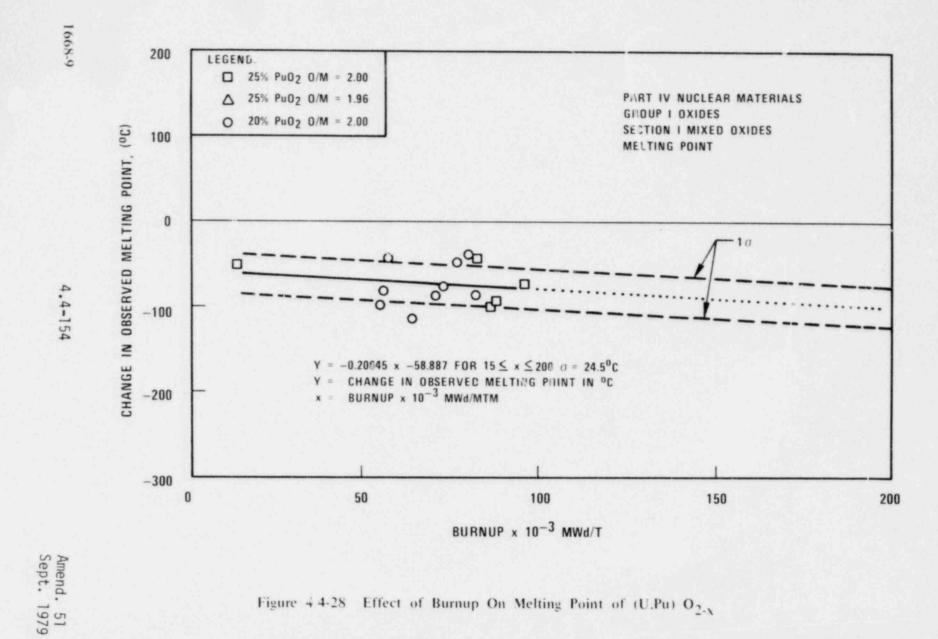


Figure 4 4-28 Effect of Burnup On Melting Point of (U,Pu) O2-x

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TABLE 5.1-1
HEAT TRANSPORT SYSTEM THERMAL HYDRAULIC DESIGN CONDITIONS

<u>Parameter</u>	Thermal Hydraulic Design Value
Thermal Power (MWt)	975
Primary System	
Hot leg temperature (°F)	995
Cold leg temperature (°F)	730
45 Flow (per loop) 10 ⁶ lb/hr	13.8
Pump Flow (gpm @ 995°F)	33,700
45 36 Pump Head (Ft Na @ Design Flow and Temp)	450 33
Intermediate System	
45 40 Hot leg temperature (°F)	936
Cold leg temperature (°F)	651
45 40 Flow (per loop) 10 ⁶ lb/hr	12.8
Pump Flow gpm @ 651°F	29,500
45 Pump Head (Ft Na @ Design Flow and Temp)	330 33

TABLE 5.1-2
PHTS VOLUMES AND VOLUME CHANGES*

45	Component	Sodium Containment Volume (ft) ³ at Room Temperature	Sodium Containment Volume at Thermal/ Hydraulic Design Conditions	
	Primary System			
45	Primary System o R.V. to Pump	725, 717, 728	746, 738, 749	
	o Pump to IHX	235	242	
	o IHX to R.V.	426, 435, 448	434, 444, 457	
	43 IHX (Shell Side)	1348	1381	
	Pump - Tank, Suction, and Discharge Nozzle at Normal Operating Level	367	378	33
	Check Valve	88	90	
	Total Volume (Per Loop)	3189, 3190, 3214	3271, 3273, 3297	
	43 Three Loop Total	9593	9841	
	Reactor Vessel	13629	13961	
45 44	43 Total Primary Volume	23222	23802	

Note: Net sodium overflow volume from a system fill temperature of 400°F to the thermal/hydraulic operating condition is 1439 FT when corrected to an assumed 900°F in the overflow tank.

^{*} Where three volumes are given, they refer to loops #1, #2 and #3 respectively.

5.2 REACTOR VESSEL, CLOSURE HEAD, AND GUARD VESSEL

5.2.1 Design Basis

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5.2.1.1 General - Reactor Enclosure System

The major components of the reactor enclosure system are the reactor vessel, the closure head, and the guard vessel. The primary safety related function of these components is to provide containment, as appropriate, of coolant, cover gas, fuel, and associated thermal and nuclear activities under all normal, upset, emergency and faulted conditions. These components shall be designed, fabricated and erected to quality standards that reflect the importance of this safety function. Where generally recognized codes or standards for design, materials, fabrication, and inspection are adequate, they shall be used. Where a component is not covered by nationally recognized codes or standards, specific and appropriate design requirements and acceptance criteria will be defined and provided in component specifications.

The reactor enclosure system provides radiation shielding as well as access for insertion and removal of surveillance material, for in-service inspection and for controlling, monitoring and servicing the core and its associated components and structures. The design transients for each of the components are described in Appendix B of this PSAR. In all cases the expected or hypothesized condition, shall not be more severe than the selected design criteria and transients.

With regard to Regulatory Guide 1.87 (June 1974, Rev. 0),
"Construction Criteria for Class 1 Components in Elevated Temperature
Reactors" (Supplement to ASME Section III Code Cases 1592, 1593, 1594,
1595, and 1596), portions relevant to component design and manufacture
"ave been applied through the equipment specifications in the following
manner:

Regulatory Position C.I.a:

All five Code Cases should be invoked, where applicable, for components in high-temperature gas-cooled reactors, gas-cooled fast breeder reactors, and liquid metal fast breeder reactors.

Implementation

The subject Code Cases are imposed by the equipment specifications except the Code Case revision distributed at time of contract placement, or later, will be used. For example, Code Case 1592-2 was received at the time of reactor vessel contract placement (April 18, 1975). Hence, either Code Case 1592-2 or subsequent revisions will be applicable to the reactor vessel, in lieu of Code Case 1592 as specified in Regulatory Guide 1.87.

Regulatory Position C.I.b:

These Code Cases may be used in conjunction with Subsection NB of Section III of the ASME Boiler and Pressure Vessel Code. Additional justification, relative to elevated comperature applicability, should

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Amend. 41 Oct. 1977 be provided in the Stress Report when other portions of Section III such as Appendixes E and F and Subsections NF and NG are used with these code Cases.

Implementation

Application of the subject Code Cases to Section III Appendix E and Subsections NF and NG is not relevant to elevated temperature portions of the reactor vessel, closure head, or guard vessel (guard vessel support design to NB in lieu of NF). Supplementary rules for application of Code Case 1592 to Appendix F are imposed via RDT Standard F9-4T required by the equipment specifications.

Regulatory Position C.I.c:

Component designs should accommodate any required inservice inspection and surveillance programs to monitor and alert for material or component degradation such as creep rupture, creep deformation, creep-fatigue interaction, profusion of microcracks, and buckling. Representative environmental factors of concern which should be considered are the effects of the cooling fluid such as sodium, helium, air, and/or impurities; irradiation effects such as aging and ductility loss; and aging resulting from prolonged exposure to elevated temperature.

Implementation

The Reactor Enclosure System and components (reactor vessel, guard vessel and closure head) are being designed to accommodate inservice inspection. A surveillance program is being planned. Each equipment specification contains detailed requirements necessary for implementation of the system programs for inservice inspection and surveillance. Environmental effects on material properties are specifically considered in design through definition of effects in the equipment specifications.

Regulatory Position C.I.d:

When a Code Case refers to an Article in Subsection NB or that Article in turn references another Article in Subsection NB, it should be ascertained that all referenced Articles in Subsection NB are consistent with all applicable elevated-temperature Code Cases and the corresponding supplements in Part C of this guide.

Implementation

The CRBRP requires full compliance with the precise provisions of the Code in regard to the requirement of this Regulatory Position. Consistency and/or applicability is determined in strict accordance with the detailed requirements defined in the Code, including the applicable Code Cases.

5.2-1a

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Upper Internals Structure Jacking Mechanism

The UIS jacking mechanism utilizes metal buffered seals in the 400°F areas. These seals are part of the mechanical assemblies. The seals will be removed with components at the appropriate maintenance period. Elastomer seals are located in the cooler regions, 125°F maximum, and will be replaced using hands-on maintenance.

Liquid Level Monitor Ports

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Four of these components, operating at 400°F, are located on the reactor vessel head. The double metal "O" rings which seal these components will remain attached to the liquid level plug during installation and removal. An inerted cask will be used to install and remove the liquid level monitor while at 400°F, requiring no hands-on operation. Because the liquid level plug remains stationary to the head assembly, the metal "O" rings beneath the plug are expected to require no maintenance.

5.2.1.4 Guard Vessel

The guard vessel provides for the retention of the primary sodium coolant in the event of a leak in the portion of the primary coolant boundary which it surrounds. The guard vessel geometry assures reactor vessel outlet nozzle submergence after such a leak which will maintain continuity in operating primary coolant loops to provide core cooling. The guard vessel also provides a uniform annulus for in-service inspection of the reactor vessel, with clearances that preclude contact with the reactor vessel and piping under accident conditions. Insulation for the reactor vessel and a heating system for the reactor vessel to be used prior to sodium fill and during prolonged shutdown are also mounted upon the guard vessel.

The maximum and minimum widths of the radial gap between the guard vessel and the reactor vessel have been conservatively calculated, taking into account all relevent factors such as tolerances on the diameters of the two vessels, permissible t-of-roundness of the two vessels, possible deviations from straightness due to manufacture and subsequent operation, thermal expansion, initial deviations in the alignment of the two vessels, etc. The transporter for the television camera will be designed to accommodate itself to this maximum possible range of gaps as it moves in the space between the two vessels.

5.2.1.5 Reactor Vessel Preheat

The Reactor Vessel Preheat System will control the dry heat-up and cool down of the Guard Vessel, Reactor Vessel and Internals between ambient (70°F) and $400^{\circ}F$ and if required will provide make-up heat for that lost to the Reactor Cavity during prolonged shutdowns.

The heat will be provided by tubular electrical heaters mounted between the Guard Vessel and insulation. These heaters will be arranged circumferentially around the Guard Vessel and will be grouped and controlled in zones of uniform heat output. Temperature sensing devices will monitor the Guard Vessel temperature in each of these zones and provide the necessary feedback for power level adjustments in the heaters.

The heaters will be mounted to the same framework which supports the Guard Vessel insulation. Ceramic offsets will be used to offset the framework and heaters from the Guard Vessel surface. The heaters and framework will therefore be electrically isolated from the Guard Vessel. Convective barriers, reflective sheaths and the Guard Vessel insulation will be used to optimize heat input to the Guard Vessel and minimize losses to the Reactor Cavity.

Preliminary preheat, startup, and shutdown analyses have been performed on the Reactor Vessel and Guard Vessel to determine the temperature differences which will result in opening and/or closure of the annular gap between the two vessels. By necessity the preheat analysis is very preliminary since no firm preheat procedure has yet been developed. Figures 5.2-4 through 5.2-6 show the temperature differences between the Reactor Vessel and Guard Vessel in the inlet and outlet plenum regions for the three transients in question. As shown the largest positive temperature difference between the Reactor Vessel and the Guard Vessel occurs in the outlet plenum region during startup (335°F) while the largest negative temperature difference occurs in the

(335°F) while the largest negative temperature difference occurs in the outlet plenum region during shutdown (-214°F). The nominal radial gap between the reactor vessel and guard vessel is 8 inches at assembly and at the end of preheat. This gap decreases to approximately 7.6 inches minimum during start-up and increases to approximately 8.3 inches maximum during shutdown. During preheat the gap also increases but to a lesser value than during shutdown due to the smaller maximum temperature difference.

Variations in the axial gap between the bottom of the reactor vessel and the inner surface of the guard vessel are noted between the states shown in the table. Thus the largest axial gap is 11.0 inches at the dry cold condition and the smallest gap is 6.2 inches at the end of the heating phase of preheat.

5.2.2 Design Parameters

Overall schematic views of the reactor vessel, closure head assembly, inlet and outlet piping, and guard vessel are shown in Figures 5.2-1, 1A and 1B. The top view is given in Figure 5.2-2.

17 load transmitted to the support ledge is reduced due to the large mass presented by the spring-coupled closure head/reactor vessel system compared to the mass of the postulated sodium slug.

5.2.2.2 Closure Head

The closure head consists of three rotating plugs which will be constructed of SA 508 Class 2 steel. Each plug contains a major penetration eccentric to its outside diameter. These rotating plugs are interconnected by means of a series of plug risers. Sealing between the plugs is accomplished by sodium dip seals and double inflatable seals of elastomer material. At its top, the large rotating plug has an outer diameter of 257.38 in., and an inner diameter of 176.50 in. The large rotating plug provides access to the vessel interior for the ex-vessel transfer machine and the core coolant liquid level monitors. The intermediate rotating plug (175.50 in. 0.D. and 58.94 in. I.D.) provides access to the vessel interior for the control rod drivelines, upper intervals support columns, and the liquid level monitors. The small rotating plug (67.94 in. 0.D.) provides access to the vessel interior for the In-Vessel Transfer Machine. The thickness of each rotating plug is 22.0 in. Rotation of the plugs will be accomplished by a gearing and bearing system attached to the plug risers. The nozzles for each penetration will be constructed of an austenitic stainless steel.

Each rotating plug is provided with a system of mechanical locks and electrical interlocks which prevent plug rotation during reactor operation and refueling when plug rotation is not desired.

The mechanical locks include the following:

- a. Each plug includes a separate positive lock to assure that the plug cannot be moved, and will not drift from its normal operating position during reactor operation. This lock will be installed to prevent relative rotation between each bull gear and its outer riser whenever the control rod drivelines are connected. The locks shall be manually installed at the end of each refueling cycle, and will be removed only during the refueling period when plug rotation is necessary.
- b. The plug drives are designed to be self locking to react to any seismic torque occurring during refueling, which could rotate the plugs and thus damage a fuel or blanket assembly during removal from the core.

The electrical interlocks include the following:

a. During reactor operation, the plug drive and control system keyswitch is in the OFF position, the control system is deenergized, and there is no power to the plug drive motors.

- b. Electrical interlocks are provided to prevent the plugs from being inadvertently rotated by their drive system unless the upper internals are raised and locked, and the IVTM and EVTM are in a safe condition.
- c. An electrical interlock is also provided to prevent vertical operation of the IVTM or operation of the EVTM over the HAA during operation of the plug drive system.

Each rotating plug has attendant thermal and radiological shielding extended to a depth of 74.65 in. beneath the top of each plug forging. The shielding is composed of a series of plates fabricated from carbon steel, and stainless steel. The cover gas between each set of plates attenuates thermal conduction and thereby acts to decrease the heat flux imparted to the rotating plug. A heating and cooling system is provided to maintain the closure head at 400°F (nominal) as well as providing heating and cooling for other small head mounted subassemblies.

A gas entrainment suppressor plate assembly is positioned beneath 45 17 the head thermal and radiological shielding at a depth of 122.65 in. beneath the top of each rotating plug. It protects the head shielding from being contacted by the core coolant and minimizes the amount of cover gas entrained in the core coolant. The assembly is designed to accommodate all normal, 17 upset, emergency, and faulted conditions.

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42 In plan view, the subassembly consists of 33 plates at the same elevation with horizontal gaps between them. (Fig. 5.2-3) These plates have penetrations in line with the head penetrations to allow the passage of the head mounted components into the outlet plenum. Each plate is supported by means of a central support column affixed to the lower shield plate and hanger rods, as needed, near the outer periphery of each plate. These central columns, when possible, consist of tubes which surround closure head penetrations. The number and location of the hanger rods will be determined such that harmful effects from seismic and flow induced vibrations are prevented. The support columns will be inserted through oversized penetrations in the lower shield plate, accurately positioned and then attached to the top surface of the lower plate by means of bolting. The support columns will be attached to the suppressor plate by means of welding. This attachment weld is located above the region of the suppressor plate where high thermal gradients occur by using a plate with an extruded weld neck. The use of a single support provides adequate support while lessening the thermal stresses by permitting the plates to flex 42 freely under the expected thermal gradient.

ABLE 5.2-3

MATERIALS FROM WHICH THE REACTOR VESSEL, CLOSURE HEAD AND GUARD VESSEL ARE FABRICATED

	F	Reactor Nessel	Product Form	Material					Comment	
17 l	,	Support Ring Vessel Flange Transition Shell Shell Cources Core Support Ring	Ring Forging Ring Forging Plate Plate Forging	SA SB SA	508 508 168 240, 182,	Clas	ss 2 be 30		Inconel 600 Austenitic stainless steel Austenitic stainless steel	
	, !	Core Support Cone Inlet Plenum Thermal Liner Thermal Liner Support Ring	Plate Plate Plate Forging	SA SA SA	240, 240, 240, 182,	Typ Typ	pe 30 pe 31 pe F3	4 6 04	Austenitic stainless steel Austenitic stainless, formed into segments and welded	
5.2-14	(Nozzles Closure Head	Forging	SA	182,	Тур	pe F3	04		
4		Rotating Plugs	Forging	SA	508,	Cla	ass 2			
	15	Guard Vessel								
11	1	Vessel top flange	Bar, Plate, Forging		479, SA 18		240,	Туре	304	
17		Vessel Vessel to support skirt ring Support Skirt Support Flange Nozzles Guard Pipe Flanges Guard Pipe Guard Pipe Elbows	Plate Bar, Forging Plate Plate Plate Plate, Forging Bar, Plate Welded Pipe, Plate Welded Fitting, Plate	SA SA SA SA SA SA	240 479, 240 240, 479, 409, 403,	SA SA SA	182 240 240	Туре	304 304 304 304 304	
		Cleanout Nozzle Cleanout Nozzle Cap	Forging, Plate			SA	240		F 304	

Amend. 41 Oct. 1977 56 TABLE 5.2-4 HAS BEEN DELETED

b. After the second cycle or repair in welds that are heat treated after each repair cycle.

Purchaser approval is required for repair of crater cracks restricted to the crater of any weld pass if the third repair cycle results are not acceptable.

5.3.1.5 Leak Detection Requirement

The PHTS Leak Detection Subsystem, part of the Sodium/Gas Leak Detection System described in Section 7.5.5.1, will provide indication and location information to the operator in the event of a sodium leak from the primary sodium coolant boundary, in a timely manner in order that action may be taken before a critical size crack in the primary boundary develops. (A critical size crack is a crack that would buige open due to operating stresses. See Section 5.3.3.6.)

The detection system sensitivity requirements are discussed in Section 7.5.5.1.

5.3.1.6 Instrumentation Requirements

The primary system is provided with an instrumentation system which monitors the process variables within the PHTS and which provides signals for safety action and operational information. The measured variables and instrumentation provided are discussed in Section 7.5.2.

5.3.2 Design Description

5.3.2.1 Design Methods and Procedures

5.3.2.1.1 Identification of Active and Passive Components which Inhibit Leaks

In the primary heat transport system, the only active component which is considered a part of the PHTS is the primary pump (see Table 5.3-10 for a list of pumps and valves). In the event of pipe leaks, the primary pumps are reduced to pony motor flow following reactor shutdown.

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In the unlikely event of a primary pipe or component boundary failure, the PHTS has been resigned to limit the loss of reactor coolant and assure that for any boundary failure, continued reactor cooling is provided. The PHTS design features which limit loss of coolant and assure reactor cooling are the combined use of elevated piping, use of a guard vessel around major equipment and a five foot pony motor shutoff head. The PHTS guard vessels have been designed such that the tops of the guard vessels are at an elevation which is approximately 9 feet above the tops of the reactor vessel discharge nozzles. This level is based on the combination of the pony motor shut-off head of 5 feet and the minimum safe reactor vessel level which is two feet above the top of the reactor discharge nozzle, plus an additional two feet to accommodate sodium shrinkage and hydraulic uncertainties.

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Amend. 56 Aug. 1980 The volume of the guard vessel and the volume of sodium above the minimum safe level of the reactor vessel have been sized to assure that the guard vessel's volume will be less than or equal to the volume loss from the reactor vessel for any leak condition plus contraction. The volume of sodium above the minimum safe level in the reactor is 3870 ft³ and the PHTS guard vessels are sized at 2700 ft³.

Continued reactor cooling is provided in the unlikely event of a pipe failure by the PHTS elevated piping arrangement. All PHTS piping is routed at an elevation above the tops of the PHTS guard vessels thereby limiting the loss of coolant in the unlikely event of a pipe failure.

The combination of guard vessel elevation, guard vessel volume, reactor vessel sodium inventory above the minimum safe level, pony motor shutdown head and elevated piping assures a limited loss of reactor coolant and continued reactor cooling capability.

Within the PHTS, there are two general types of failures of the pressure containing boundary. They are (1) failures which occur in a guard vessel and (2) failures in elevated piping outside of the PHTS guard vessels. Consideration of these cases has led to the conclusion that a rupture in a guard vessel represents the worst possible leak condition.

Leak in a Guard Vessel

To verify the consequences of a leak within a guard vessel, an analysis was conducted which made a number of assumptions to ensure conservatism. These assumptions are:

- a. The leak occurs in the highest pressure point of the system, i.e., at the pump discharge.
- b. The leak occurs when the plant is operating at the maximum temperature which will result in maximum sodium shrinkage following initiation of a leak. (Maximum temperature conditions are normal full power operation.)
- c. The reactor vessel cover gas make-up is 100 SCFM. (The current design calls for a scram make-up rate of 25 SCFM.)
- d. There is no reactor vessel sodium make-up.
- e. Any sodium inleakage to a guard vessel will not flow back to the reactor vessel following sodium shrinkage.
- There is no thermal shrinkage of components or piping; only sodium shrinkage.

The analysis based on the preceding indicated that for a very large leak, the reactor vessel cover gas make-up capacity limited the leak rate after a initial spill which would fill roughly 1/2 of a guard vessel. After

- c. Pipe supports are located at points of concentration loads.
- d. Pipe supports are located as close as practical to component nozzles to minimize the component deadweight nozzle loads.

The pipe supports for the Primary Piping System consist of assemblies made up of commercially available constant load pipe hangers, commercially available pipe vibration/seismic snubbers, and specially designed pipe clamps.

The load carrying capacity requirements of the constant load hangers will be determined by deadweight analysis and the travel requirements of the hanger will be determined from free thermal expansion analysis. The minimum travel to be accommodated by the constant load hangers will be the maximum free thermal expansion of the pipe at the hanger location plus 20 percent of that travel. The minimum travel must not be less than 1.0 inches. The constant load hangers will be provided with travel stops to limit the vertical travel of the pipe run when the pipe is empty.

The seismic snubbers are of the mechanical friction type (non hydraulic). The snubber allows the free movement of the pipe during normal expansion and contraction of the piping system, but will "lockup" before the pipe has moved farther than the design displacement along the axis of the snubter.

The pipe clamps which are located on the horizontal runs of piping will be of the "non-integral" type. Typically, the horizontal pipe clamps will consist of a segmented outer steel clamp ring, and a segmented steel sheathed load bearing insulation inner ring. The outer segments are held together by a system of bolts and belleville spring washers. The clamping loads exerted by the belleville spring washers are designed to prevent slippage of the clamp under a 3g acceleration, but will not cause any undue stress on the pipe wall or cause damage to the sheathed load bearing insulations. Reference Figure 5.3-36.

In order that the primary pipe in the vicinity of the reactor vessel maintain its integrity and to accommodate the deflections of the reactor vessel under third level margin design loads, the piping seismic restraints will be designed to fail at loads well beyond those of plant operating conditions but below those that could be generated by the reactor vessel movements. At support locations, where the seismic support must fail to accommodate the third level margin deflections of the reactor vessel, shear pin assemblies as shown in Figures 5.3-37A and 5.3-37B will be provided. An excessive load on the restraint will cause the shear pin to fail, releasing the load, and reducing stresses in the piping, thus preventing excessive yielding or precipitation of cracking in the piping. The pipe hanger assemblies will be designed to accommodate the increased pipe travel.

The pipe clamps which are located on the vertial runs of piping engage the horizontal surfaces of the transition pieces which are integral parts of the vertical piping to satisfactorily transmit the pipe loads to the pipe hangers without slip age. The vertical pipe clamp consists of three major components; the outer support ring, the steel-sheathed load-bearing insulation inner bands, and the pipe transistion section which includes an axial support ledge. The transition piece is designed to be welded to the vertical run of the pipe line. It has the same inner diameter of the pipe, and the wall thickness is the same as the pipe line at the point of attachment to the pipe line, but gradually slopes to a larger wall thickness, thus forming a support ledge which contacts the load bearing insulation and transmits the pipe load to the clamp ring. The outer support ring is made up of two Type 304 stainless steel semicircular rings which are bolted together to form a very stiff circular ring. The inside surface of the ring is machined to a "channel" shape to receive and capture the canned load-bearing insulation. Attachment lugs for snubbers and hangers are welded to the outer surface of the 5615 ring (see Figure 5.3-38).

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The constant load hangers being used for pipe support in the reactor cavity area are of "all metal" ...struction, and are designed to meet the requirements of the ASME Code subsection ", components supports. Although there is no directly applicable experience with constant load pipe hangers in areas such as the CRBRP reactor cavity, it is expected that no material property degradation will take place due to the radiation and temperature environment because of the type of materials being used.

The radiation fluence in the vicinity of the hangers nearest the reactor core has been estimated to be a 5×10^{18} nvt when integrated over all energy neutrons essentially no neutrons have energy >1 MeV). For this type of neutron energy spectrum, a fluence of 1019 nvt corresponds to the onset of shift in nil-ductility temperature (Ref. 29). It is concluded that no significant material degradation will accrue from this phenomenon.

Access to the pipe hangers in the reactor cavity for maintenance and inspection is provided by removable access plugs located in the HAA ledge. There are no inaccessible pipe hangers.

speeds coincided with the synchronous speed of the drive motors and maximum (15 psig) cover gas pressure are less than the design pressure of the system (200 psig downstream of the pump, 30 psig upstream of the pump).

Code Case 1596, "Protection Against Overpressure of Elevated Temperature Components," Section III, Class 1, is complied with by the following method.

Specifications for components and piping in the reactor coolant boundary include off-normal dynamic and sustained overpressure loads resulting from:

- Check valve slams resulting from a primary pump seizure
- Dynamic loads associated with a sodium/water reaction (IHX)

The plant protection system trips the pumps on primary to intermediate flow mismatches. Therefore, any decrease in primary flow due to some flow blockage in one primary loop causing the pressure to increase as the pump approaches its shutoff head would be limited. The plant protection system also trips the reactor and pumps on a flux to flow mismatch, thereby providing protection against overpressure due to core blockage during power operation.

5.3.2.5 Leak Detection System

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5.3.2.5.1 Leak Detection Methods

Leaks from the liquid metal circuits of the reactor coolant system can be detected by measurement of changes in liquid metal inventory, detection of radioactivity and a separate leak detection system.

The leak detection system will detect leaks, if they should occur, in piping, and inside of major component guard vessels as well as below large tanks such as the reactor overflow tank. Details of the methods for detection of liquid metal to gas leaks are discussed in Section 7.5.5.1.

5.3.2.5.2 Indication in Control Room

Detection of a leak will activate an annunciator in the control room. As discussed in Section 7.5.5.1, leak location will be identifiable from either the Plant Data Handling and Display System or by reference to the leak monitoring panels.

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Since these loops do not contain isolation valves, isolation of the leaking loop is not possible; however, following shutdown, the affected loop may be partially or completely drained to limit the leak without jeopardizing the function of the other two loops.

5.3.2.5.3 PHTS Coolant Volume Monitoring

The total sodium inventory in the Primary Heat Transport System is monitored by the Data Handling and Display System, using sodium level detectors in the Reactor Vessel (see Section 7.5.3), in the Primary Sodium Pump Tank (see Section 7.5.2), and in the Auxiliary Liquid Metal Overflow Tank (see Section 9.3.5).

5.3.2.5.4 Critical Leaks

Reference 2 of Section 1.6 provides the results of the investigation of potential cracks in the PHTS and the capability to detect leakage from such cracks.

5.3.2.5.5 Sensitivity and Operability Tests

The sodium-to-gas leak detection system, as described in Sec-56 tion 7.5.5.1, is continuously self-monitoring for channel malfunction. Periodic maintenance procedures will provide for additional checking of operating characteristics. During installation and check-out, the correct electrical functioning of each contact and cable detector will be tested.

5.3.2.5.6 Confinement of Leaked Coolant

All cells and pipe chases within the Reactor Containment Building that house coolant (sodium) equipment and/or piping are operated with an inert atmosphere (nitrogen gas) containing a low oxygen concentration. Information concerning the design of these cells and pipeways is contained in Paragraph 3.A.l.l. The operation of these cells in an inerted atmosphere ensures that a minimum coolant fire will result from any spill or leak.

Inerting gas for individual cells or groups of cells is treated separately to prevent the spread of aerosol vapors beyond the confines of the area where the leakage or spill occurred. Separate cells are provided for redundant and/or safeguard equipment or systems to preclude the loss of that equipment or system in the event of a coolant leak or spill.

Provisions have been made for reducing any splash effect around coolant handling equipment or instrumentation by approximately locating such equipment within the cell to minimize such consequences.

The following design bases have been used to minimize the effects of leaks (including splash effects) from other components:

- a) All piping and major components are suspended from the ceiling or side walls above the floor.
- b) All piping and major components have an outer layer of metal sheathing over the insulation.
- c) All instrumentation in general penetrates the top of the pipe and is protected by metal guard boxes.

classified as faulted for the affected steam generator module. Differential pressure between the primary and intermediate sides during this event is conservatively evaluated by assuming that the primary side pressure is that resulting from pony motor speed (approximately 6 psig). For the rest of the loop, the occurrence is classified as an emergency event.

For the unaffected loops, the event is similar to the reactor trip from full power. Decay heat removal is maintained throughout the two remaining loops. The transient responses of temperature, flow and pressure on both the primary and intermediate side of the IHX in the affected loop are presented in Figures 5.3-18A through 5.3-18G. Particular attention is directed to Figures 5.3-18F and G which show intermediate side short term and long term pressure effects.

In evaluating the structural adequacy of the IHX, with respect to the check valve slam, the dynamic nature of the primary sodium pressure history is being accounted for by using dynamic load factors. The factor will be applied to the maximum primary pressure, which in turn, is used to determine the pressure-induced primary stresses. These primary stresses are limited by the emergency condition allowables of Code Case 1592, Paragraph 3224, as modified by RDT F9-4T. The fatigue damage associated with the cyclic nature of the pressure history will be accounted for per Paragraph T-1400 of Code Case 1592. The description of the pressure pulses for the sodium-water reaction and check valve closure is included in the equipment specification. The curves define the amplitudes, duration and number of cycles.

Rapid check valve closure can only occur as a result of primary pump mechanical failure. The event involves a postulated instantaneous stoppage of the impeller of one primary pump, while the system is operating at 100% power. The failure may be a seizure or breakage of the shaft or impeller. Primary system sodium flow in the affected loop decreases rapidly to zero as the pumps in the unaffected loops seat the check valve (thereby causing a rapid check valve closure or slam). A reactor trip will be initiated by the primary intermediate flow ratio subsystem. Sodium flow in the intermediate circuit of the affected loop decays as in a reactor trip from full power, modified by changes in natural circulation head. The event is characterized by a down transient in the hot leg of the intermediate circuit of the affected loop. The transient responses of temperature, flow and pressure on both the primary and intermediate side of the IHX in the affected loop are presented in Figures 5.3-18H through 5.3-18M. Particular attention is directed to Figure 5.3-18J which shows primary pressure effects.

Both the sodium water reaction and check valve closure events are classified as emergency events for the IHX. As such, the IHX designer is required to determine which of the six emergency events is most severe to the IHX. The selected event is then applied with a periodicity of two consecutive occurrences during the first three years of operation, and thereafter five times over the remaining 27 years (or once every six year period). If vendor analysis indicate either as the most severe event, the occurrence of the two consecutive events will be moved to the most stringent time in the life for the event to occur. The IHX design has not progressed to the point where either the sodium water reaction or check valve closure can be defined as the most severe emergency event. Rather, preliminary analysis indicates that damage from either of these events will be insignificant.

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Inelastic analyses of the pumps may be required to demonstrate conformance with ASME and RDT Standards. Paragraph 4 of RDT F9-5T, Sept. 1974 gives a description of acceptable methods for time-independent elastic-plastic analysis and time-dependent creep analysis. Some of the computer programs listed above have inelastic capabilities, and will be used where applicable.

For the purposes of loads and analysis the pump R-Spec divides the pump into four areas. These are: Subcomponent 1 which consists of the pump tank, Subcomponent 2 which is the upper inner structure including the pressure bulkhead, Subcomponent 3 which is the rotating machinery and Subcomponent 4 which is the static hydraulics.

Subcomponent 1 is designed to the ASME Boiler and Pressure Vessel Code Section III, Subsection NB Class 1 and Code Case 1592 where applicable. The cone and cylinder are designed mainly by dynamic stiffness requirements. These include seismic loads and the necessity of keeping the natural frequency of the structure above the operating speed of the impeller. SAP IV and the "CRISP" computer codes are used for this analysis. The analysis has been qualified by comparing the results of one analysis against the other. The sphere sealing ring and cone-sphere support ring are designed by sealing ring leakage which requires elastic response during normal and upset conditions. A failure will reduce pump efficiency below plant criteria. These areas are being analyzed by 3D global analysis using NASTRAN. The nozzles are designed by pressure, pipe nozzle loads, and thermal transients. The failure modes associated will be creep and creep fatigue. 2D elastic analysis will be required. The design is being made with sufficient space for thermal baffles and liners to keep it elastic as much as is possible. But it may be necessary to qualify it using simple inelastic analysis. A hydraulic leakage test will be run to determine the relation of sealing gap to leakage rate.

Subcomponent 2 will conform to the same Code requirements as Subcomponent 1. The upper closure plate and radiation shield are designed by the design pressure and temperature requirements. Elastic failure is the predominant mode. The heat shield will have steady state thermal gradients which will be determined by a 2D axisymmetric model and stresses will be calculated with a 2D stress model. The motor stand will be designed by the stiffness requirements of the motor and seismic loads. The principle failure would be excess vibration leading to fatigue failures.

Subcomponent 3 can be removed and inspected after an emergency or faulted event and repaired before the plant is placed in service again. Therefore, this section will be designed and analyzed to the ASME Boiler and Pressure-Vessel Code, Section III, Subsection NB for Class 1 Components and Code Case 1592 where applicable. However for emergency events if Code Case 1592 is used the design rules for load controlled stresses (Section 3227) will apply. Strain deformation and fatigue analysis need only be performed up to the emergency event and the limits will apply only to the pumps ability to operate at pony motor speed after the event. This area will be designed by critical frequency requirements, inertial loads, torque and thermal transients. Failures associated will be fatigue, shear failure and creep fatique. It will be analyzed with a 2D axisymmetric model. The loads caused by bearing misalignment will be accounted for. A general 1/2 scale model hydraulic performance test will be run using water as the pumped fluid. This test will give a measure of pump performance and of internal leakage flows.

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5.3.3.10.3.2 Mass Transfer of Radioactive Species

The radioactive aspects of mass transfer in the reactor coolant from the reactor to the Heat Transport System are discussed in detail in Section 11.1. These aspects, in themselves, do not affect the structural integrity of the HTS.

5.3.3.10.4 Compatibility with External Insulation and Environmental Atmosphere

Within the heat transport system the reactor vessel, pumps, and intermediate heat exchangers are enclosed by guard vessels. Between these components and the guard vessels a semi-inert gaseous atmosphere of 0.5-2% oxygen/nitrogen is maintained. The piping and the upper portions of the components containing sodium external to the guard vessels are also insulated to minimize heat loss to the PHTS cells. The thermal insulation consists of alumina silicate blanket material manufactured under controlled conditions to minimize the pickup of halogens and/or moisture. The insulation is protected from halogen pickup during shipping, storage and installation. The insulation has an inner liner and is installed on standoffs to provide a gap for heaters and leak detection equipment and, therefore, does not directly contact piping or components. No field compounded thermal insulation materials are used. This will minimize any potential contamination of the piping by corrosive elements in the insulation. Most piping is also exposed to the 0.5-2% oxygen/nitrogen atmosphere.

Sodium leaks into the guard vessels, should they occur, are unlikely to be self sealing in view of the low oxygen content. Small leakages will be contained within the guard vessel. With respect to the piping (except that which is situated within the guard vessels) any sodium leakage will react with Gaygen, nitrogen, and thermal insulation. No comprehensive data appear to be available to evaluate the reaction in detail but available information from experimental sodium loops indicates that the leaking sodium will form a sodium oxide (and very likely sodium nitride) "growth" beneath the insulation at the point of leakage. For temperatures below about 1000°F no self sealing of the leak is usually observed. Studies were conducted to evaluate the nature of sodium leakage through precracked austenitic stainless steel piping into a 1.2 v/o oxygen/98.7 v/o nitrogen atmosphere. Materials of Construction are listed in Tables 5.3-4 thru 5.3-9.

5.3.3.10.5 Chemistry of Reactor Coolant

The heat transport system sodium chemistry is selected to minimize corrosion. A periodic analysis of the coolant chemical composition is performed to verify that the coolant quality meets the specifications.

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Sodium purification capability is provided through the use of cold traps.

Capabilities are provided both for "in-line" primary and interrediate sodium purity determinations (sodium plugging temperature indicators) and for direct sampling and laboratory analysis to monitor impurities. The systems are described in Section 9.3.2.

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TABLE 5.3-13

COLD LEG CHECK VALVE CHARACTERISTICS

Requirement	Units	Design Value
Design Flow Rate (at 730°F)	lbs/hr	13.82 x 10 ⁶
Flow Range at Normal Operating Conditions	% of Design Flow	40 - 100
Max. Shutoff, Δ P Imposed Across Seat		
Steady State	psi	160
Pressure Loss at Design Flow	psi	<10
Pressure Loss at Pony-Motor Flow Conditions of 2500 gpm at 600°F	psi	<0.20
Pressure Loss at Natural Circulation Flow Conditions of 670 gpm at 730°F	psi	<0.03
Temp. at Which Design Flow Pressure Loss is Calculated	°F	730
Allowable Leakage in Reverse Direction at Shutoff at 730°F	gpm	21
Pressure Difference for Allowable Leakage, Reverse Direction	psi	50

Closure Characteristics

The maximum steady state reverse flow allowed by the check valve shall be less than 1100 gpm. The valve shall not require a pressure differential across the disk greater than 1.0 psi to shut. Closing time shall be 5 seconds maximum (after flow reversal) with a resultant pressure surge of less than 50 psi under the specified reverse flow conditions.

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TABLES 5.3-14 thru 5.3-22 HAVE BEEN DELETED

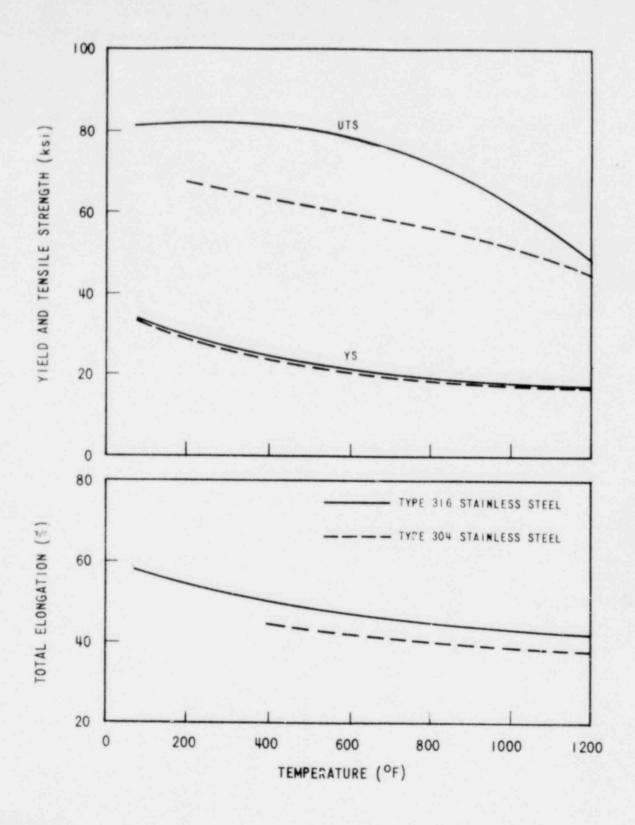


Figure 5.3-1. Comparison Between the Strengths and Ductilities of Solution Treated
Types 304 and 316 Stainless Steel Containing 0.08 Weight Percent (C + N)

* Taken from Reference 54.

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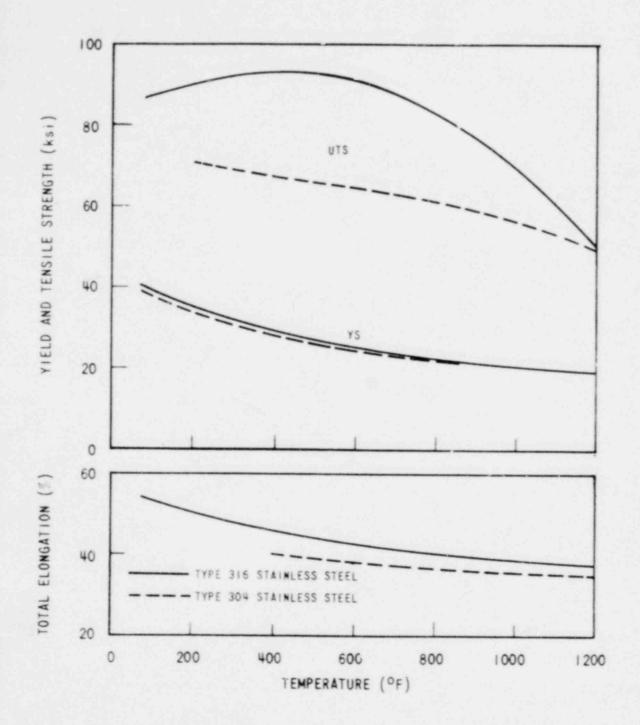


Figure 5.3-2. Comparison Between the Strengths and Ductilities of Solution Treated Types 304 and 316 Stainless Steel Containing 0.12 Weight Percent (C + N)

* Taken from Reference 54. 6669-18

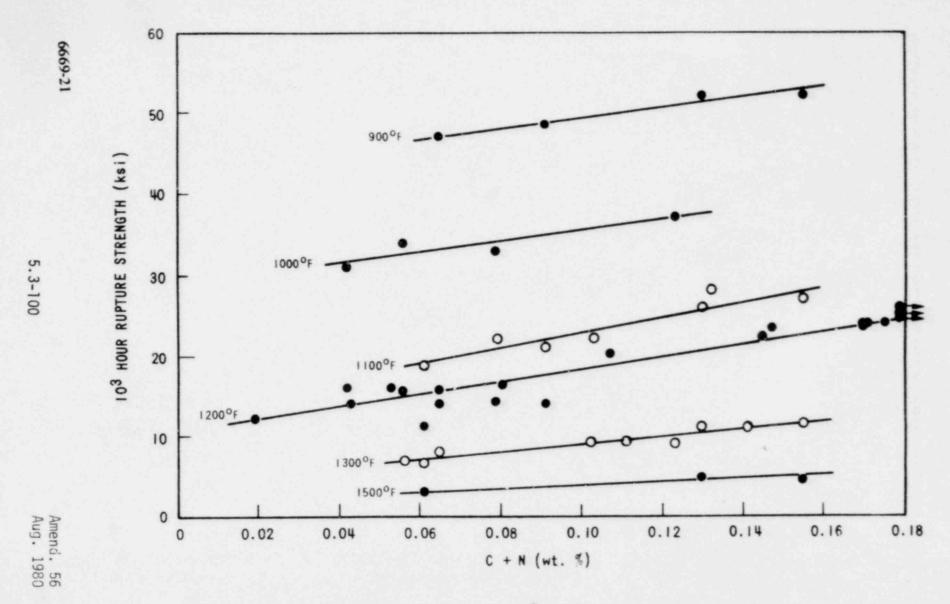


Figure 5.3-3. Effect of Interstitial Content on the 10^3 Hour Rupture Strength of Type 304 Stainless Steel Bar * Taken from Reference 55.

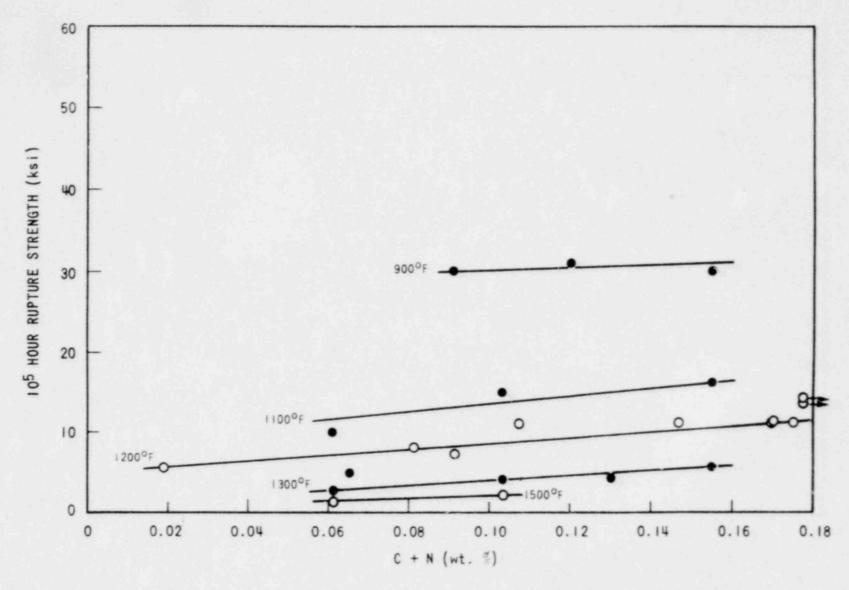


Figure 5.3-4. Effect of Interstitial Content on the 10⁵ Hour Rupture Strength of Type 304 Stainless Steel Bar

* Taken from Reference 55.

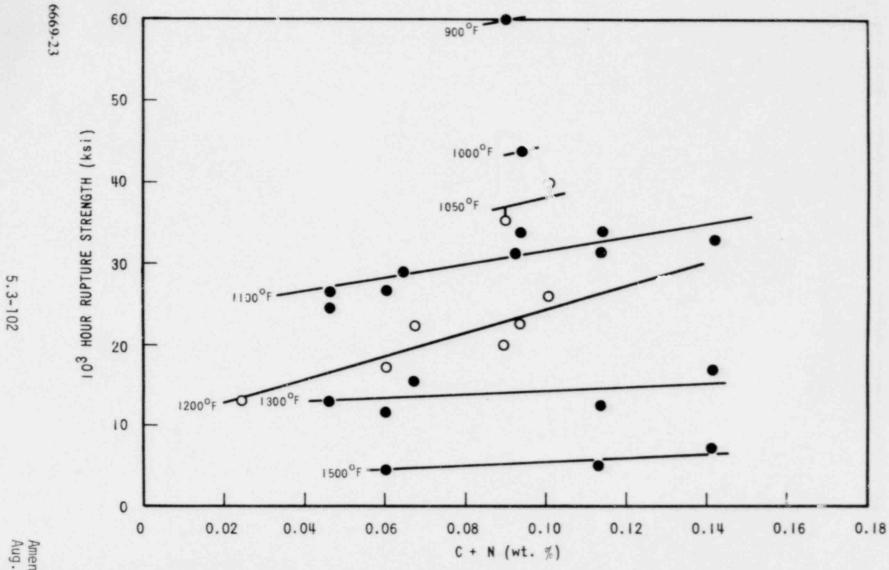


Figure 5.3-5. Effect of Interstitial Content on the 10³ Hour Rupture Strength of Type 316 Stainless Steel Bar * Taken from Reference 55.

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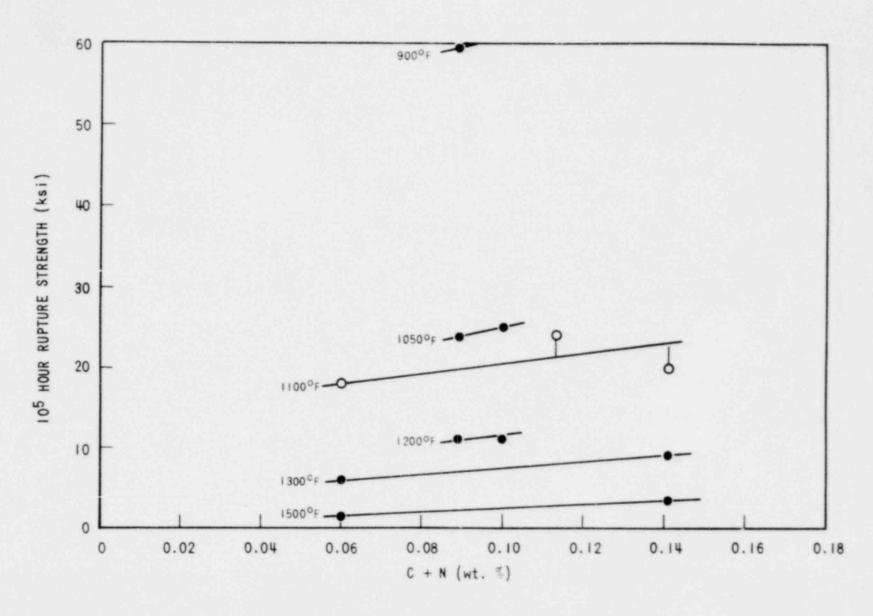


Figure 5.3-6. Effect of Interstitial Content on the 10⁵ Hour Rupture Strength of Type 316 Stainless Steel Bar

* Taken from Reference 55.

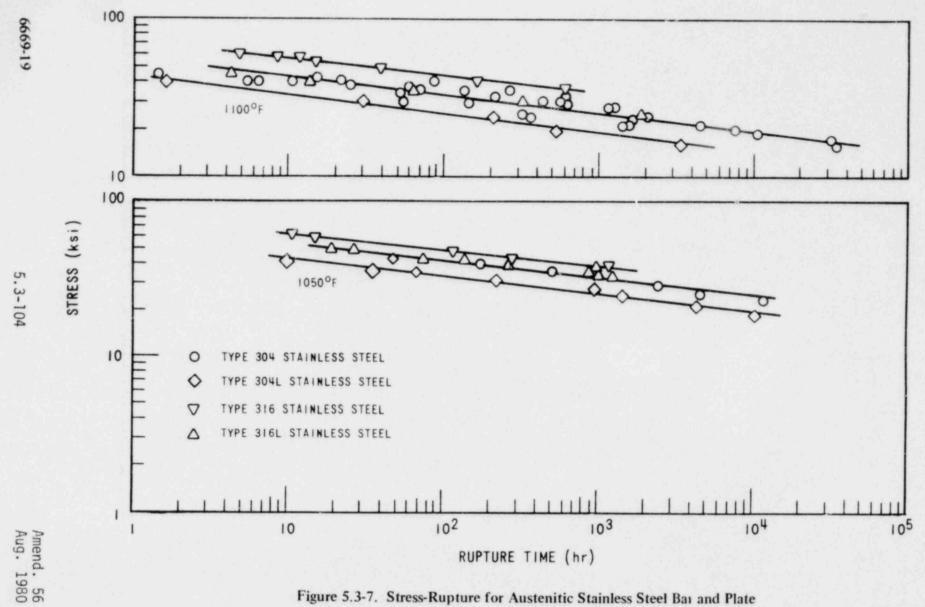


Figure 5.3-7. Stress-Rupture for Austenitic Stainless Steel Bar and Plate * Taken from Reference 56.

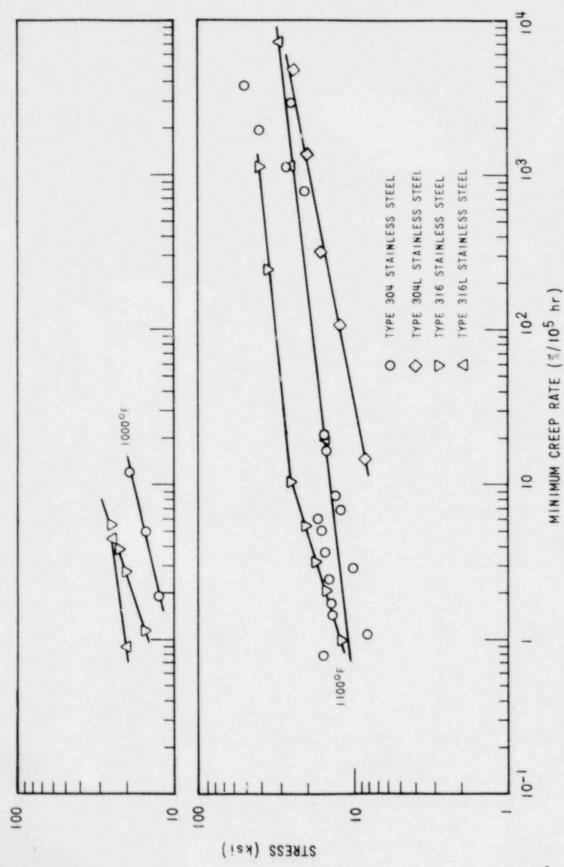
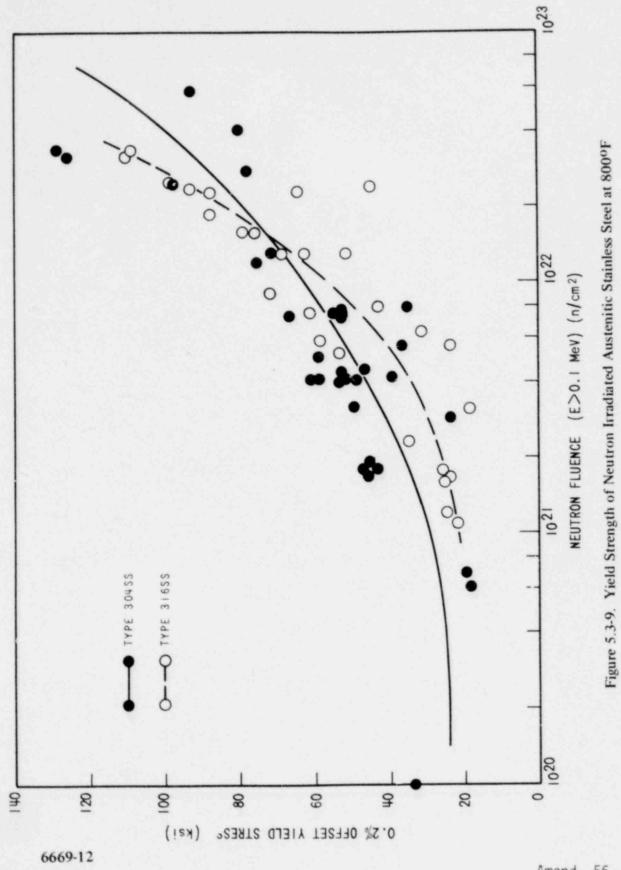


Figure 5.3-8. Minimum Creep Rates for Austenitic Stainless Steel Bar and Plate

* Taken from Reference 56.

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* Taken from Reference 57.

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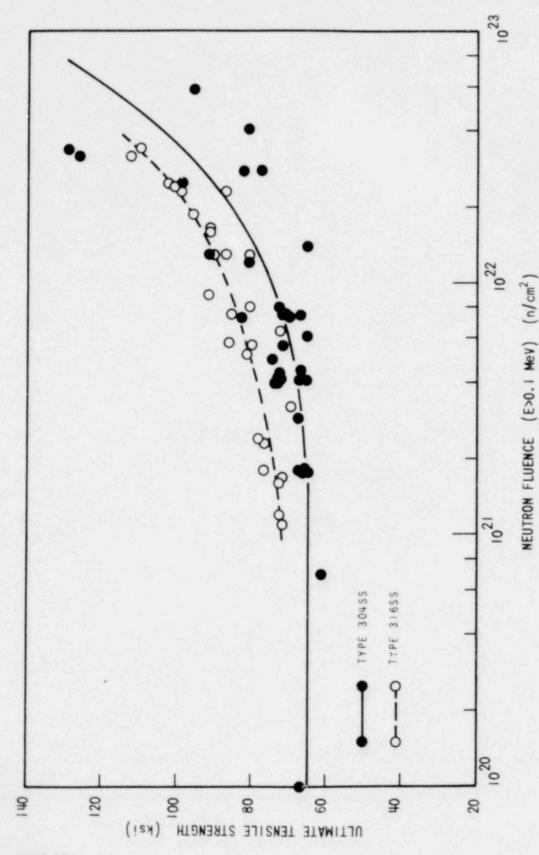


Figure 5.3-10. Ultimate Tensile Strength of Neutron Irradiated Austenitic Stainless Steel at 8000F Taken from Reference 57

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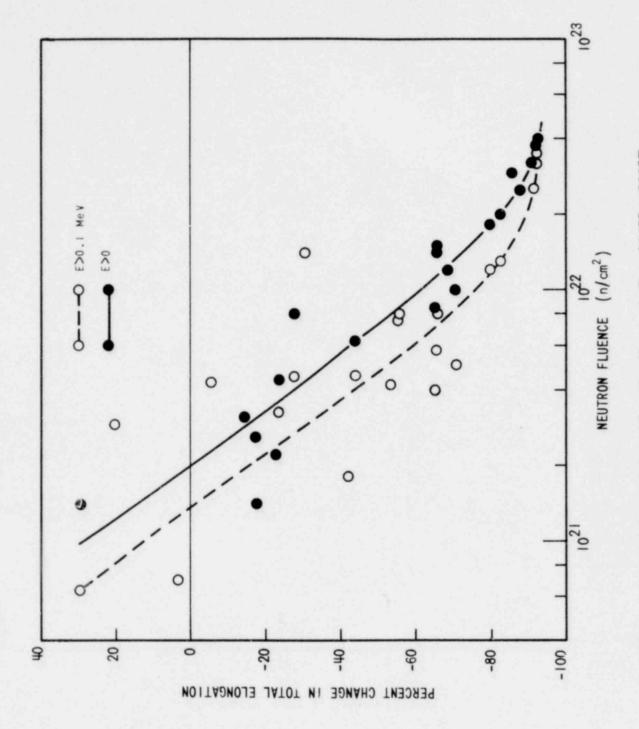
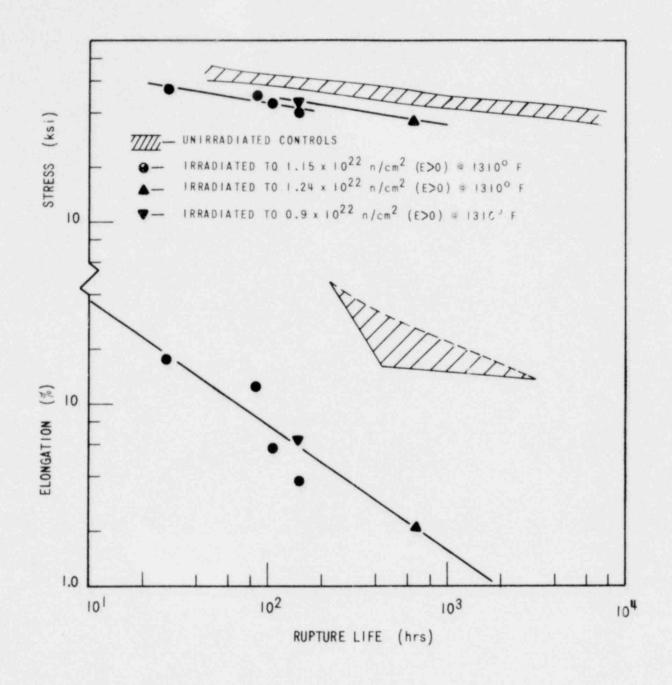


Figure 5.3-11. Irradiation-Induced Ductility Changes in Type 304SS at 800°F * Taken from Reference 57.

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* Figure 5.3-12. Creep-Rupture of Irradiated Type 316SS at 1000°F Taken from Reference 57.

FIGURES 5.3-25 thru 5.3-35 HAVE BEEN DELETED

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5.3-123 (next page is 5.3-134) Amend. 56 Aug. 1980

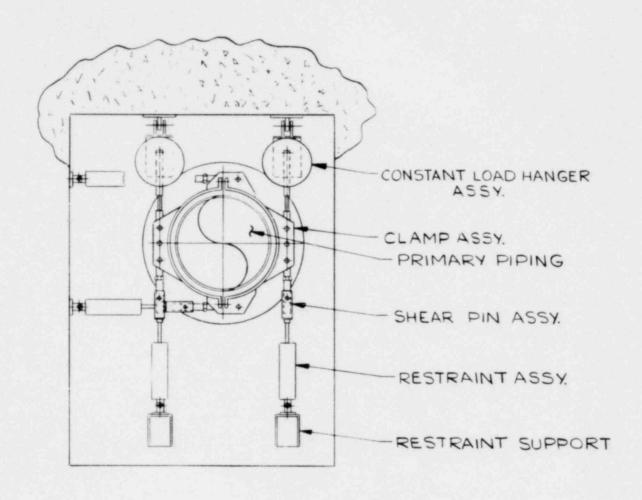
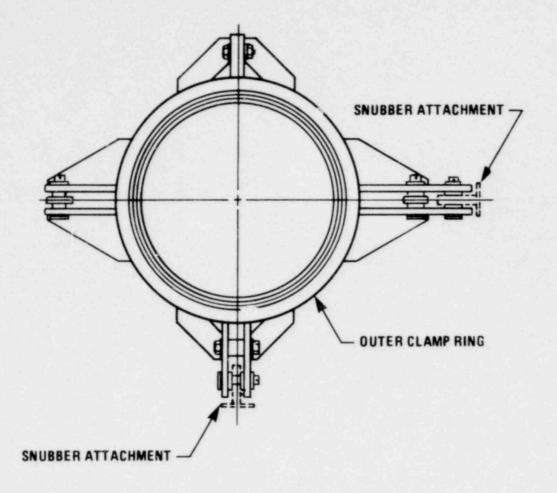


FIGURE 5.3-37B PIPE HANGER/SNUBBER ARRANGEMENT



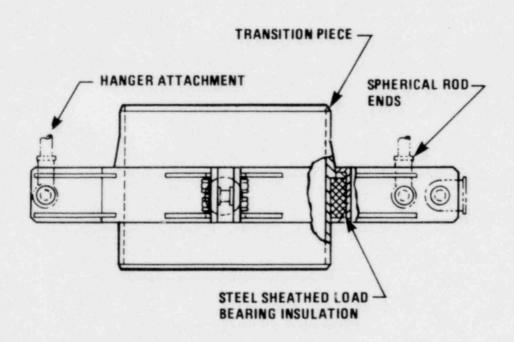


Figure 5.3-38. Vertical Pipe Clamp Assembly

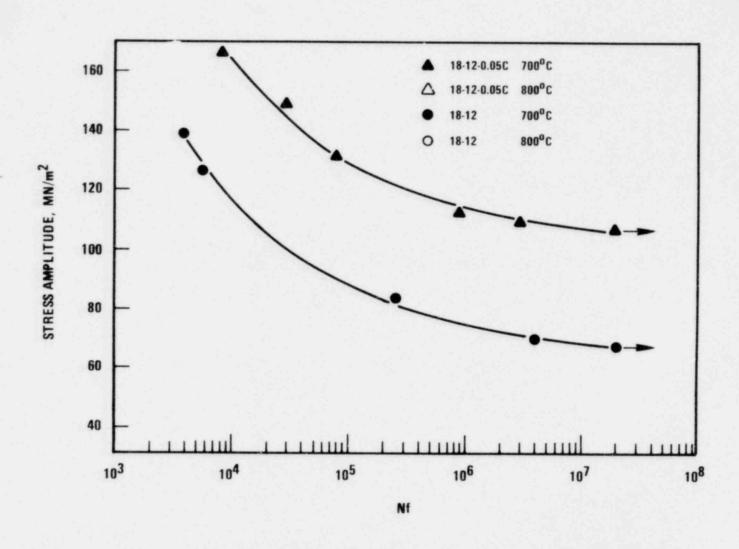


FIGURE 5.3-39 S/N Curves Of 18/12 And 18/12/0.05 C Alloys At 1292°F

FIGURE 5.3-40 HAS BEEN DELETED

FIGURE 5.3-41 HAS BEEN DELETED

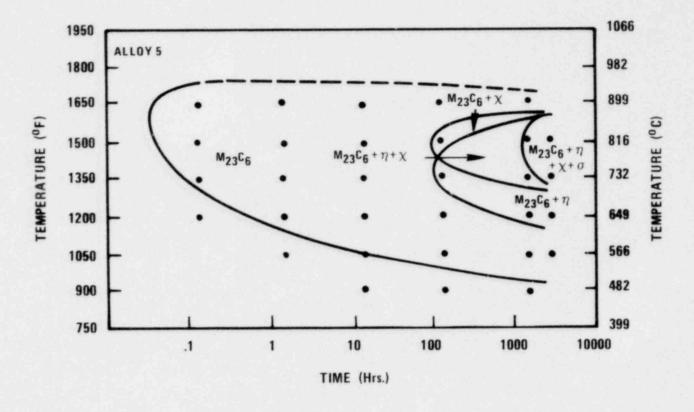


FIGURE 5.3-42 Precipitation Reactions In Type 316 Stainless Steel Solution Treated At 2300°F For 1.5 Hours And Water Quenched.

The IHTS piping will be supported from the building structure with constant load support hangers and will be restrained with seismic snubbers. Attachments to the piping for supports will be of the clamp type on the outside of load bearing insulation. If any attachment requires direct support to the pipe full penetration welds will be used.

Piping penetrations through the Reactor Containment will be a flued head, rigid type seal. Piping penetrations through the Steam Generator Building will not provide leak tight seals.

The piping within the IHTS consists of large sodium containing piping which must be installed per detailed drawings and rigid quality assurance requirements. There is no piping which can be field run.

5.4.2.3.4 Intermediate Heat Exchanger

The CRBRP Intermediate Heat Exchanger (IHX) serves to transfer reactor thermal energy from the radioactive primary sodium to the non-radioactive intermediate sodium. The IHX is a counterflow shell and tube type unit with a vertical orientation in the plant. The design arrangement provides for downflow of the cooled (primary) fluid and upflow of the heated (intermediate) fluid to enhance natural circulation for reactor decay heat removal. A detailed description of the IHX design is given in Section 5.3.2.3.2.

5.4.2.4 Overpressurization Protection

The IHTS has no isolation valves within the normal circulation path so that isolation of individual system pipe sections or components is not possible. If for some reason the system becomes blocked, the intermediate pump will not overpressurize the system as the IHTS structural design is sufficient to withstand the pump shutoff head. In the event of an argon supply valve failure, the system would not be overpressurized as the combination of argon supply pressure of 115 psi and pump shutoff head would not exceed the IHTS design pressure. This is true even if the pump shutoff head associated with the PHTS pump were reached instead of the IHTS pump shutoff head.

The system may be subjected to overpressure in the event of a water or steam leak in the Steam Generation System. For large or intermediate sodiumwater reactions, the resulting pressure increase due to the formation of reaction products in the faulted evaporator or superheater module is relieved through rupture disks. (See Section 5.5.2.4).

5.4.2.5 Leak Detection System

5.4.2.5.1 Leak Detection Methods

The methods used to detect Liquid Metal to gas leaks from pipes and components of the IHTS are aerosol detectors, cable detectors, contact detectors and visual inspection with back up from smoke detectors. See Section 7.5.5.1.

A sodium level monitoring system is provided to monitor any leakage between reactor and intermediate coolant occurring in the IHX. The method is described in Section 7.5.5.2 in detail.

5.4.2.5.2 Indication in Control Room

Audible alarms will be sounded in the control room as described in Sections 7.5.5.1 and 7.5.5.2.

5.4.2.5.3 IHTS Coolant Volume Monitoring

The IHTS coolant volume is monitored by the level indicators in the IHTS pump tank and in the expansion tank. Details are discussed in Section 7.5.5.2. These monitors coupled with the sodium temperature measurements allow monitoring of the total sodium in the IHTS loops. Small leakages of sodium from the IHTS can be replaced by use of the sodium fill system.

5.4.2.5.4 Critical Leaks

Critical leaks are discussed in Section 5.3.2.5.4. Detection capability is discussed in Section 7.5.5.

5.4.2.5.5 Sensitivity and Operability Tests

Periodic maintenance will provide for checking the operational readiness of leak detectors. During installation and checkout, the correct electrical functioning of each leak detector and level detector will be tested.

5.4.2.5.6 Confinement of Leaked Coolant

If there is any leakage from the IHTS in the RCB it will be confined as described in 5.3.2.5.6. Any leakage from the IHTS in the SGB will be contained in the catch pans and will be detected by the leak detection system. Fires as a result of sodium spills are evaluated in Section 15.6. Leaks in the IHX are still contained in the passive coolant boundary, and no leakage into the RCB will result.

5.4.2.5.7 Intermediate/Primary Coolant Leakage

Primary to Intermediate coolant leakage is very unlikely due to the higher operating pressure of the intermediate system. The IHTS pressure shall be maintained at a minimum of 10 psi higher than the PHTS pressure at all points in the IHX during all normal modes of operation. Intermediate to primary coolant leakage detection is described in Section 7.5.5.2.

5.4.2.6 Coolant Purification (IHTS)

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The IHTS coolant purification is accomplished by six cold traps, two in each of the three loops. One trap is in operation while the other is on standby, except for a cleanup period after maintenance action. These cold

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7.5.5.1.1 DESIGN BASES AND DESIGN CRITERIA FOR THE LIQUID METAL-TO-GAS LEAK DETECTION SYSTEM

The design bases of the Liquid Metal-to-Gas Leak Detection System arise from criteria needed to support the integrity of the PHTS boundary and from maintenance and plant availability considerations in the IHTS, SGS, and Auxiliary Systems.

The design bases are as follows:

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- The Liquid Metal-to-Gas Leak Detection System must provide diverse means for detecting and locating liquid metal to gas leaks throughout the plant at normal operating conditions.
- 2) The Liquid Metal-to-Gas Leak Detection System must operate at lower temperature conditions (<700° F), though its sensitivity may be reduced.
- 3, The Liquid Metal-to-Gas Leak Detection System must perform its function during and after an OBE (operating basis earthquake) even in the event of loss of offsite power.

The Design Criteria of the Liquid Metal-to-Gas Leak Detection 56 System for the Primary Heat Transport and Reactor Systems are outlined below:

- 1) The Leak Detection System must be able to detect "weeping" leaks which may have potential for long term growth.
- 2) The reference "weeping" leak is defined as a rate of approximately 100 gm/hr, or over, in pipes and components at temperatures greater than 700°F.
- 3) The Leak Detection System must be capable of identifying within which cells the leak has occurred. Also, detection must be provided within each of the reactor vessel, IHX, and Pump Guard Vessels.
- 4) Each cell (and contained guard vessels) shall be monitored for leaks by at least two diverse methods capable of providing the defined sensitivity. A confirmation method shall also be available in the event that conflicting information is provided by these systems.

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- 5) Each of the two diverse methods shall have an individual response time of less than 250 hours for the reference 100 gm/hr leak size. Leaks of 30 gpm or larger shall be detected in less than 5 min. Leaks smaller than 30 gpm and larger than 100 gm/hr shall be detected prior to either a total spill volume of 150 gallons or 250 hours, whichever is less.
- 6) Indicators and alarms for leakage detection shall be provided in the main control
 - shall be provided in the main control room.

 7) The leak detectors shall be equipped
- 7) The leak detectors shall be equipped with provisions to readily permit testing for operability and calibration during plant operation.

Design Criteria Requirements for the Intermediate Heat Transport System, Steam Generator System, and Auxiliary Liquid Metal System are detection of a 30 gpm leak in five minutes.

45 Detection time requirements for a 100 gm/hr leak are up to 250 hours.

7.5.5.1.1.1 Design Description

General

A liquid metal-to-gas leak detection system is provided to protect against economic losses and to support inservice inspection for CRBRP. Detection equipment is provided to monitor the primary and intermediate sodium coolant boundaries to identify comparatively small leaks when they occur.

A development program has provided the experimental data necessary for the selection of the best method to satisfy these requirements. The data available from this program covers sensitivity, range, response time and overall performance of various detection.

The leak detection system selected for the following installations are:

- Contact detectors in the space between the bellows and the stem packing of the bellows sealed sodium valves.
- Cable detectors in guard vessels and under major liquid metal components.
- Sodium Ionization Detectors (SIDs) which are aerosol detectors, for cell atmosphere monitoring.
- 4. Plugging filter aerosol detectors (PFADs) for Main Heat Transfer System piping and associated auxiliary piping; guard vessel and major components (e.g. Steam Generators, etc.).

The performance of these aerosol detectors for specific CRBRP applications have been demonstrated by verification tests (Reference 2).

The response of these detection methods has been determined for a wide range of environmental conditions, sodium temperatures and leak rates including:

Sodium Temperature	350 - 1000°F
Atmosphere Moisture Content	300 - 30000 VPPM
Nitrogen Atmosphere	1 - 21% 02
Sodium Leak Rate	0.4 - 243,000 gm/hr
Detection Sample Line Length	10 - 200 feet
Detection Sample Line Size	1/4 & 1/2 inch O.D.
Detection Sample Gas Flow Rate	0.3 - 7.0 liters/min.

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Of the types of leak detection devices proposed for the Leak Detection System, only sodium vapor/aerosol leak detection devices show a difference in their response when operated in an air atmosphere as opposed to an inert atmosphere. The electrical sensing types such as cable and contact detectors show no difference in response due to operating atmospheres. However, the potential for higher moisture content in air 561 31 can result in greater inhibition to sodium flow when the leak is very small.

The sodium vapor/aerosol detection devices sense the concentration of sodium vapor/aerosol from a leak and give a response. In air atmospheres, sodium burns more readily than in inert atmospheres and vapor/aerosol detection devices would be expected to respond faster in air atmospheres. However, because the reaction products tend to cover the leak, actual formation of aerosols tends to be inhibited by air atmospheres. The time for a detector to respond to a leak into an inert atmosphere tends to be shorter than for leaks into air.

There are other considerations which affect detection devices response. These are: cell moisture content, sodium leak rate and temperature detection device location, and cell size. Test data indicates that sodium leaks of 2 gm to 100 gm per hour in an air atmosphere or inert atmospheres can be detected by aerosol detection for sodium temperatures as low as 350°F.

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Results from tests that have been performed have verified that the leak detection system will reliably and rapidly detect sodium-to-gas leaks (Reference (2)). It is observed from the results that small leaks (~100 gm/hr) of high temperature Na into an inert atmosphere (1% 02) can be detected in approximately I hour by most of the detection systems' under consideration. At lower temperatures (400°F) it will take up to 24 hours to detect the leak. For a 100 gm/hr leak rate of 640°F Na into an air atmosphere the time to detection of leaks is in the range of four to six hours. In the case of 100 gm/hr leaks from sodium pipes at 400°F into an air atmosphere (as might occur in the case of the intermediate system) leak detection levels are attained within about six hours by a majority of the systems used. It will be noted that this is about one-fourth of the detection time applicable to an equivalent sodium leak into an inert atmosphere. From 56! these test data it has been shown that larger leaks (order of kg/min) will be readily detected by two or more detection systems in minutes.

The increase in cell atmosphere temperature and pressure in the eyent leaks of larger thar 20 kg/min as detected by temperature and pressure sensors can provide an additional source of leak detection. These detection devices do not require development nor does the prediction of the cell atmosphere temperature/pressure rise since extensive data is available from the sodium burning experiments which were performed in support of FFTF.

The ability to detect small leaks (∿100 gm/hr) by several methods in hours plus the ability to detect large leaks (>kg/min) in minutes will provide a highly reliable leak detection system that provides the operator information and enable safe shutdown (see Section 15.6) to repair defects without causing extensive time for cleanup operations.

Table 7.5-3 gives the candidate primary and possible back-up methods of leak detection for the principal sodium systems and components in the plant. These exact combinations were selected as a result of the development program described above. The methods shown in the table are related to the three sizes of leaks defined in Section 7.5.5.1.2. The principal methods of leak detection are described below.

Contact Detectors (Spark-Plug)

Contact detectors consist of a stainless-steel-sheathed, mineral oxide-insulated, two-wire probe with the sensing end open and the wire ends exposed. Contact detectors are installed, for example, on bellows sealed valves with the sensing end between the bellows and the mechanical backup seal. A leak is detected by the reduction in circuit electrical resistance caused by sodium contacting the wire ends.

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Cable Detectors

Cable detectors consist of stainless-steel-sheathed, mineraloxide-insulated, cable with holes penetrating the sheath to permit leaked liquid metal to come in contact with the conductors. Cable detectors will be placed, for example, in the bottom of guard vessels and below large tanks. The experimental results are presented in Reference 2.

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Aerosol Monitoring

45 Aerosol monitoring will be performed by measuring the pressure drop across a membrane filter with a constant flow of gas sampled from the annular space between major piping and its insulation, from the space within quard vessels, and from cells containing liquid metal systems. Another aerosol monitoring method uses a sodium ionization detector. Liquid Metal aerosols or vapor are ionized by a hot filament and the ion current is measured. Increases in the 45 ion current indicate a leak.

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Based upon the experimental results, these methods would allow detection of leaks of 100 gm/hr or less with a response time of several, minutes for 1000°F sodium (Reference 2).

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The major function of this instrumentation will be to provide indication of the presence of small leaks which do not present a significant contamination hazard, but which might result in undesirable long-term corrosion. The instrumentation will also provide backup signals for other leak detection methods.

45 Other Detection Methods

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Pressure and temperature measurements available in the inerted cells (Section 9.5.1.5) will provide immediate indication of the presence of large leaks over the 20 kg/min size. In the case of systems containing radioactive sodium, the detection of airborne radioactivity arising from Na-24 or Na-22 in the aerosols will be performed by particulate radiation monitoring equipment (Section 11.4.2) which provides a sensitive detection method for aerosol concentrations as low as 10-15 gm/cc.

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Other Backup Detection Method

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Liquid Sodium Level Sensors in the reactor, the EVST, the IHTS expansion tank, and sodium storage tanks will provide indications of large leaks. Smoke detectors (Fire Protection System) will detect combustion products originating from sodium leaks in air (See Section 9.13.2).

Indication in Control Room

An audible group alarm is sounded in the control room upon indication of a leak or certain failures of contact, cable, or aerosol channels. The channel number producing the alarm and the location of the region covered by this channel are displayed on an annunciator on a local panel. This information will identify the leak as occurring in a specific major component or series of pipe sections, or specific bellow-sealed valve, or the cell containing the leaking system. The leak detection system uses the Plant Data Handling System for channel failure monitoring, data and trend logging; the sampling time interval will nominally be approximately 30 seconds.

No automatic isolation functions or reactor scram are initiated by the Liquid Metal-to-Gas Leak Detection System. Isolation or shutdown of a system showing a leak will be performed manually, following verification of the leak and review of the operating conditions.

7.5.5.1.2 Design Analysis

The Liquid Metal-to-Gas Leak Detection System will meet the appropriate requirements of CRBRP Design Criterion 30, "Inspection and Surveillance of Reactor Coolant Roundary" and Criterion 33, "Inspection and Surveillance of Intermediate Coolant Boundary." Criterion 30 requires that means be provided for detecting and identifying the location of the source of reactor coolant leakage from the reactor coolant boundary to the extent necessary to assure that timely discovery and correction of leaks which could lead to accidents whose consequences could exceed the limits prescribed for protection of the health and safety of the public. Criterion 33 requires that means be provided for detecting intermediate coolant leakage from the intermediate coolant boundary. In order to demonstrate how the intent of the criteria will be satisfied, the instrumentation requirements met by this system for three different ranges of leaks 56 are discussed. These ranges have been selected to analyze situations which cover the complete range of the leak detection instruments. Section 15.6 discusses the consequences of leaks for the health and safety of the public.

Large Leaks

This category covers failures up to those resulting in a leak of 30 gpm or 100 kg/min. A significant physical characteristic of leaks of this size is that they would result in pressure and temperature changes in the primary cells if the leak occurs in PHTS pipe sections. This feature sets the lower boundary of the leak at about 20 kg/min; this being an estimate of the amount of sodium which would result in measurable changes in cell pressure and temperature. If the leak occurs in a guard vessel, continuity

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The pressure and temperature measurements available in the inerted 561 cells will, in conjunction with the aerosol detectors, continuity detectors and radiation monitors, provide the response required for proper operator action in case of leaks of this magnitude.

Intermediate Leaks

Intermediate leaks were defined as those leaks which would not result in significant changes in cell pressures and temperatures but where the extent of the resulting contamination and plant maintenance makes plant shutdown desirable. The range of leak rates covered extends from the lower limit of the large leaks previously considered down to a leak of 100 gm/hr. The detection times for the wide range of leaks in this group would vary from a few minutes to several hours depending on the rate of leakage. Based upon experimental results, it is concluded that several systems would detect a leak of this magnitude in several hours at least and possibly in minutes.

Instrumentation capable of detecting leaks of this magnitude include radiation monitors, continuity detectors, and the different types of aerosol detectors currently under long term performance evaluation.

Small Leaks

Small leaks at or below 100 gm/hr were defined as those events resulting in releases of sodium which do not pose a contamination or maintenance problem but might result in undesirable long-term corrosion (see Section 5.3.3). The methods for detecting leaks of this range are aerosol detectors and radiation monitors in the case of the primary system.

In the course of test programs, aerosol concentrations produced by leaks of dcwn to 5 gm/hr were found to be within the detection capability of both a Sodium Ionization Detector and a Plugging Filter Aerosol Detector. The initial tests results show that leaks of this size can be detected in the range of one hour to 24 hours by annuli monitors depending upon the sodium temperature and gas environment. It is deduced from the test results that very small

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Amend. 56 Aug. 1980 leaks (<1 gm/hr) will be detected by annuli monitors in several days. Tests during 1975 and 1976 showed that under environmental conditions typical of LMFBR operation, small leaks from typical piping configurations can be detected by both Sodium Ionization and Plugging Filter Aerosol Detectors. Continuity (cable or contact) detectors did not reliably detect small pipe leaks under these conditions. Testing in 1978 verified the performance of aerosol detectors using prototypic CRBRP cell atmosphere recirculation as well as pipe/insulation design.

It is deduced from the test results that the sodium vapor/aerosol systems will, in conjunction with existing radiation monitoring technology, provide adequate indication of the smallest sizes of leaks of interest.

Sodium Leaks into an Air Atmoschere

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Test results (Reference 2) indicate that the methods applicable to sodium leaks in inerted cells will also operate when applied in an air atmosphere. The additional use of smoke detectors and the accessibility of piping located in an air atmosphere to visual inspection assist in the selection of an effective sodium-to-air leak detection system.

7.5.5.2 Intermediate to Primary Heat Transport System Leak Detection

7.5.5.2.1 Design Description

The IHTS pressure is maintained at least 10 psi higher than the Primary Heat Transport System at the IHX to prevent radioactive primary sodium from entering the IHTS in the event of a tube leak. Maintaining a positive pressure differential across the IHX is a limiting condition for operation of the plant (Chapter 16 - Technical Specifications). This provides assurance that a zero or negative differential will not exist during any extended interval. A loss of this pressure of a reversal of it is not expected to occur except during accident conditions. Such an occurance would necessitate an orderly plant shutdown to correct the problem. Since a reverse differential cannot occur for a significant interval, the potential leakage of primary sodium into the intermediate system, through an IHX tube leak, is small.

Leakage of primary sodium into the IHTS, should it occur, will be detected by radiation monitors provided on the IHTS piping within the SGB. The radiation monitor system will provide an indication of the radiation level and will provide alarms for conditions of excessive radiation indicative of ingress of primary sodium. Since the only activity expected in the IHTS is a low level of tritium, the radiation monitors will be very sensitive to the presence of significant amounts of radioactive primary sodium in the intermediate system. For accidents which involve a loss of IHTS boundary integrity the radiological effects have been evaluated. The results of these evaluations are presented in Sections 15.3.2.3, 15.3.3.3 and 16.6.1.5.

Maintaining a positive pressure differential across the IHX assures that the leakage across the IHX tube barrier will result in an inflow of sodium into the primary system causing a loss of sodium inventory in the IHTS. The sodium inventory in the IHTS is monitored by tracking the sodium levels and correcting for loop temperature effects. Alarms are provided in the control room to alert the operator upon detection of a large loss of IHTS sodium inventory.

7.5.5.2.2 Design Analysis

Intermediate to Primary Heat Transport System leak detection is provided to comply with CRBRP General Design Criterion 36 "Inspection and Surveillance of Intermediate Coolant Boundary". In order to demonstrate now the intent of this criterion will be satisfied, an analysis of the minimum detectable leaks in the IHX is provided below.

The minimum detectable level change of sodium in the IHTS pump and expansion tank is approximately 3 inches which corresponds to about 150 gallons. In the event of a full-circumferential break of an IHX tube, the leak rate of intermediate sodium to the primary side of the IHX would be approximately 150 gpm. At this leak rate, the detection time would be about one minute assuming steady state temperature conditions.

Based upon a 3-inch level change, leakage of as low as 6.25 gph would fall within the detection threshold. Over long time periods, the sensitivity of the detection system will be reduced by an insignificant amount due to other potential leakages from the system. If leakage occurs due to piping or component leaks, the external leak detection system will detect the leakage. A second potential source is leakage through the four sets of dump valves which has a maximum expected rate of one to two gallons per day. Since this leakage rate is essentially two orders of magnitude smaller than the leakage threshold, it will not have a consequential effect on the detection sensitivity.

7.5.5.3 Steam Generator Leak Detection System

A steam Generator Leak Detection System is provided to detect small (as low as 10^{-5} lb/sec) water-to-sodium and steam-to-sodium leaks in the steam generator modules, to identify the module in which the leak has occured, and to alert the control room operator enabling him to take manual corrective action to prevent the leak rate from increasing. Leak detection instrumentation is provided for:

- 1. Sodium exiting from the superheater.
- 2. Sodium filled vent lines from combined evaporator vents and the superheater vent.
- Bulk sodium in the IHTS cold leg.

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System	Equipment Monitored	Size of Leak (see Section 7.5.5.1.2)	Primary Method of Detection	Back-up Method of Detection
Reactor Enclosure	Reactor vessel and inlet, outlet, overflow nozzles	small.	radiation monitoring	cable detector sodium level
		intermediate and large	aerosol monitoring radiation monitoring cable detector	in vessel cell temp. & pressure
PHTS	Major pipe sections	small	annuli aerosol moni- toring, cell radia- tion monitoring, cell aerosol monitoring	sodium leve nn vessels
		intermediate and large	monitoring, cell aerosol monitoring, annuli aerosol monitoring	céll temp. A pressure
	Pump housing, IHX shell, check valves	small	aerosol monitors and cell radiation monitoring	cable detec t ors
		intermediate and large	aerosol monitoring radiation monitoring caule detector	sodium lev vessels cell temp & pressure

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System	Equipment Monitored	Size of Leak (see Section 7.5.5.1.2)	Primary Method of Detection	Back-up Method of Detection
	Major sine continue numn	small	aerosol monitoring	visual inspection vault smoke detector
IHTS and Steam Gen.	Major pipe sections, pump housing, expansions tank, steam generators distribution lines, steam generators	intermediate and large	cable detector aerosol monitoring	
Aux. Liq. Metal, Impurity Monitoring and Analysis, and Reactor Refueling	EVST, overflow and storage tanks	sma11	cell radiation monitoring (RCB only) & aerosol monitoring	sodium levels in vessels
		intermediate and large	cell radiation monitoring, aerosol monitoring, and cable detector	cell temp. & pressure
	Cold traps, heat exchangers, impurity monitoring, and other small equipment	all	cell radiation monitoring, aerosol monitoring, and cable detector	cell temp. & pressure (large leaks

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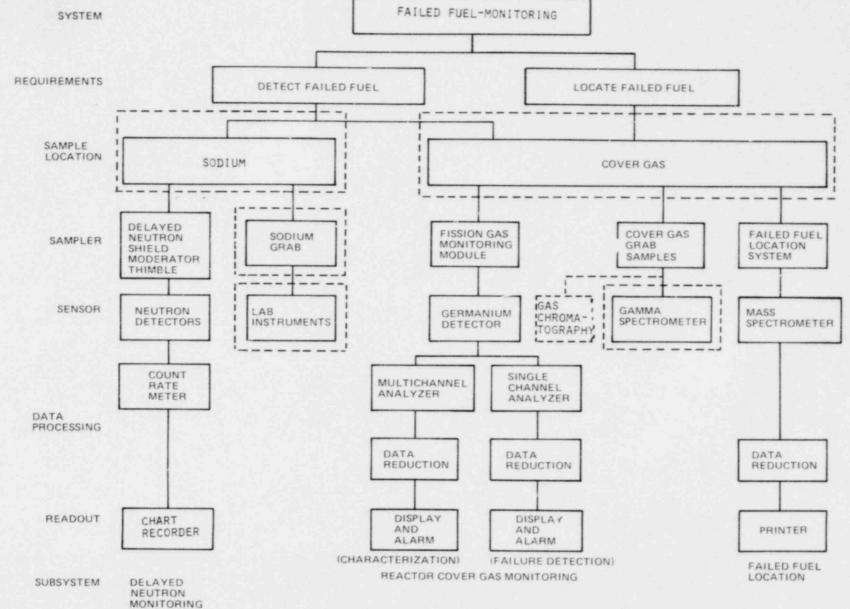


Figure 7.5-3. Fuel Failure Monitoring System

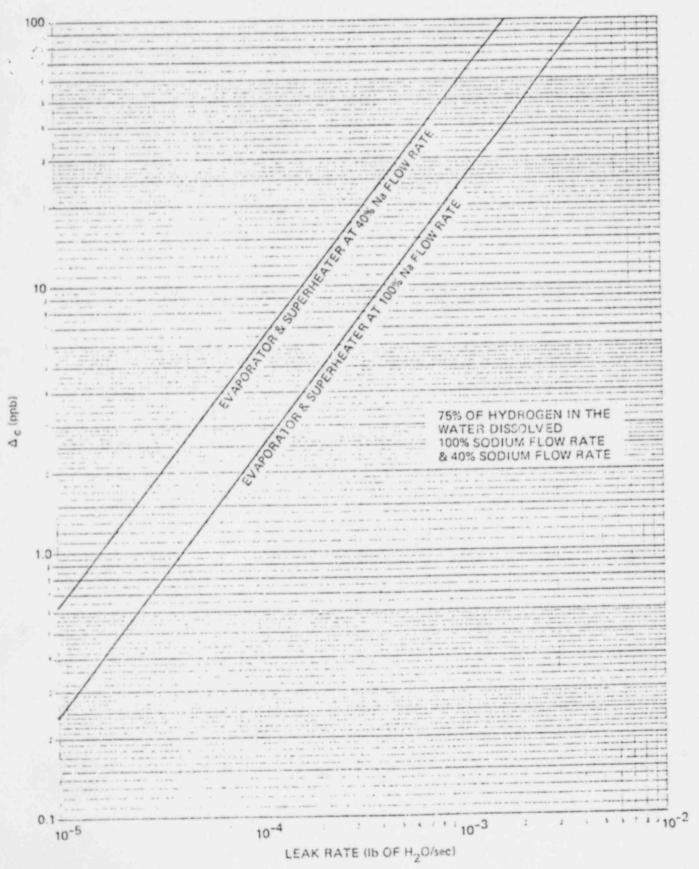


Figure 7.5-4 Main Sodium Stream First Pass Hydrogen Concentration Versus Leak Rate
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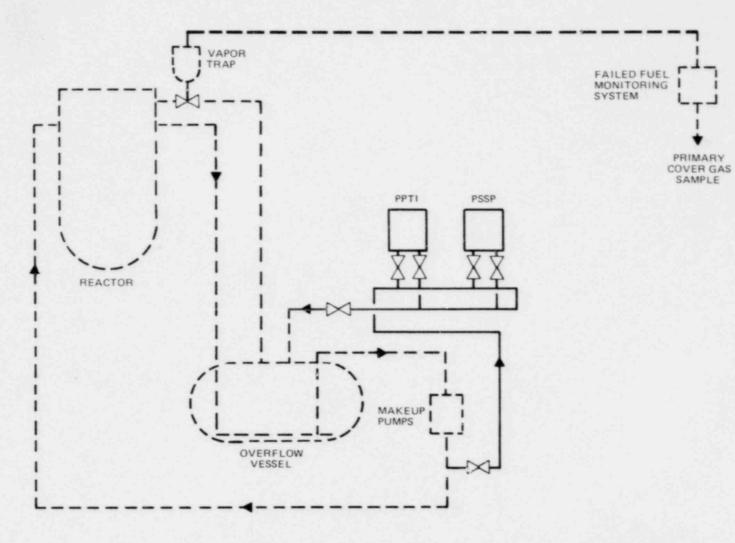


Figure 9.8-1. PHTS Sodium Characterization and Primary Cover Gas Sampling and Monitoring Subsystems

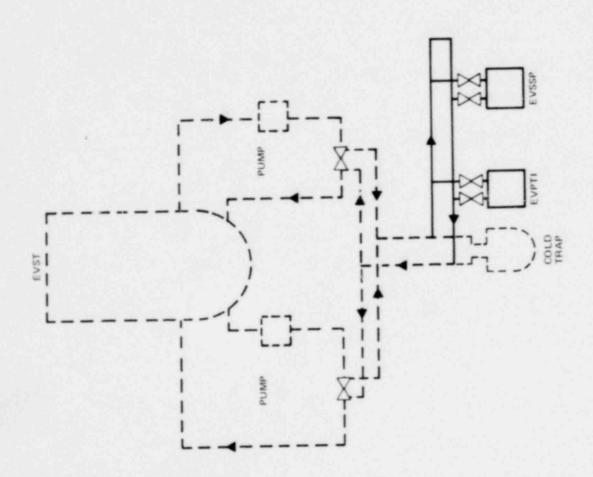
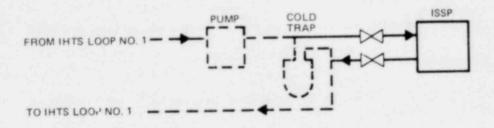
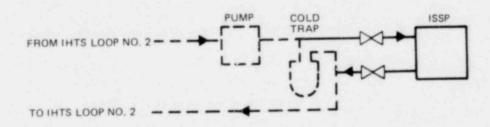


Figure 9.8-2 EVST Sodium Characterization Subsystem





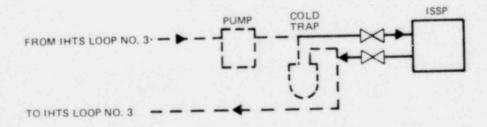
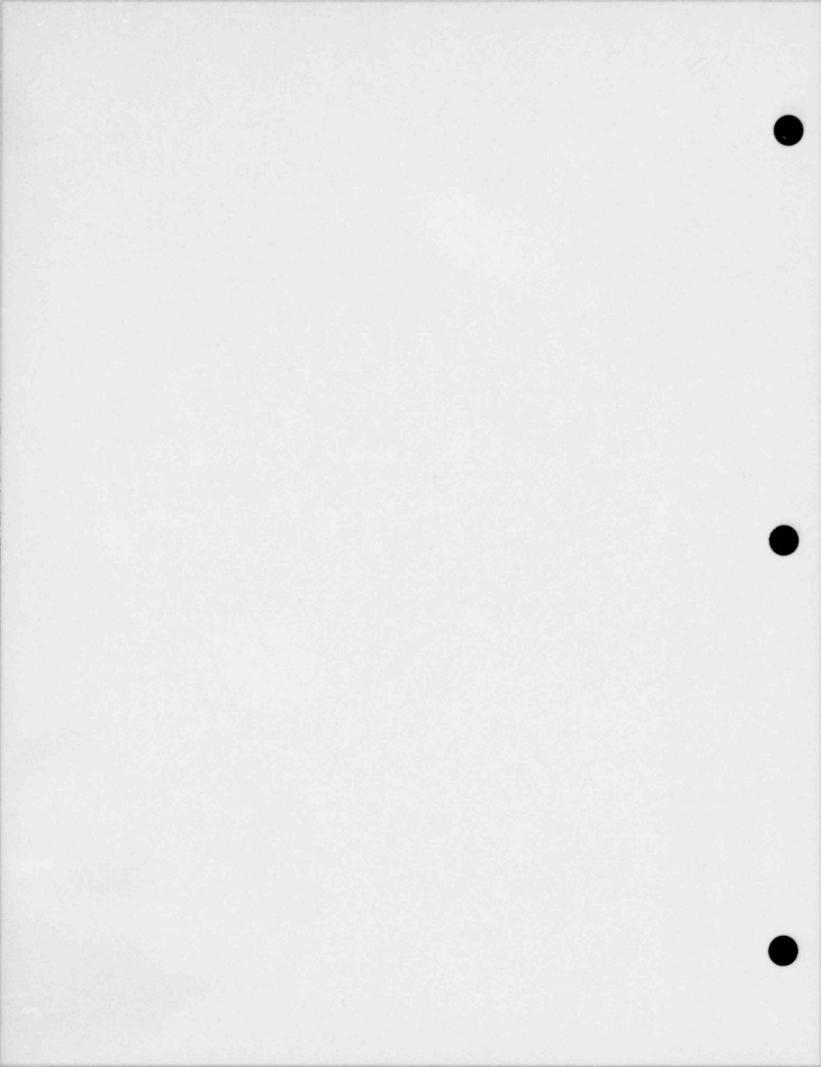


Figure 9.8-3 IHTS Sodium Characterization Subsystem

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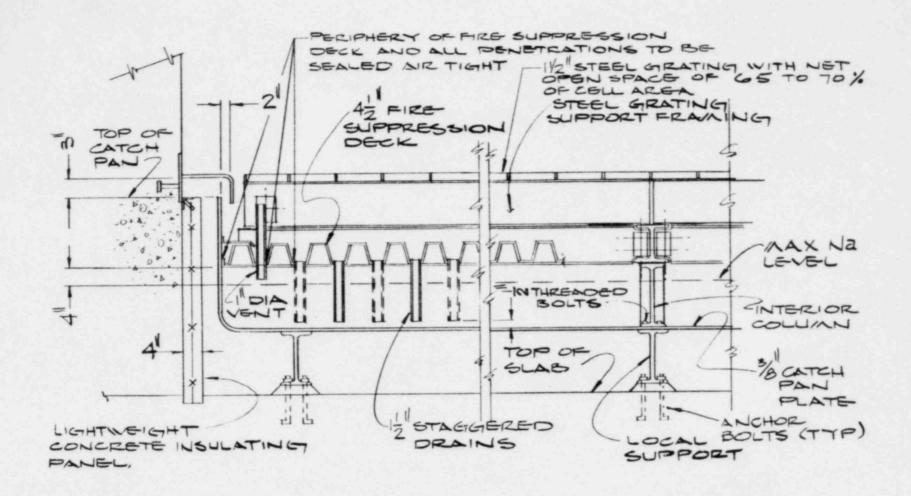
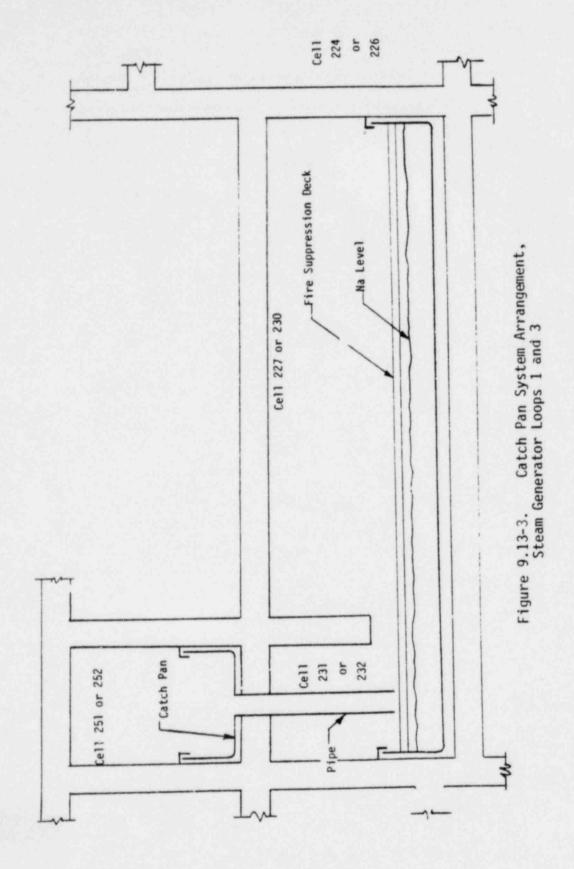


FIGURE 9.13-2
TYPICAL CATCH PAN
FIRE SUPPRESSION DECK ARRANGEMENT



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15.3.3.4 Primary Heat Transport System Pipe Leak

15.3.3.4.1 Identification of Causes and Accident Description

Small sodium leaks have occurred several times in sodium testing facilities and in operating reactors. As a result, PHTS leaks are considered in the design and evaluation of the plant to assure that the design has adequate capabilities from the standpoint of core thermal transients. This particular section will address the PHTS pipe leak as an undercooling event while Section 15.6.1.4 provides a detailed discussion of the PHTS pipe leak and its consequences with regard to cell pressure and temperature transients and radiological effects.

Based on considerations of the leak detection system capabilities discussed in Section 7.5.1.5, and the fact that the leak detection systems

56 provide wide ranging coverage, it is considered that

leaks of approximately 3 gal/min will be easily detected. Therefore, to provide a wide margin between detectability and the leak rate selected for analysis purposes, a leak rate of 10 times the above value (i.e., 30 gal/min) for ten minutes was established as the leak that would result in assured detection and plant shutdown. With assurance that the leak rate of 30 gal/min is well above the detectable range of CRBRP instrumentation, a study was conducted to determine if this leak rate resulted in a significant core transient.

15.3.3.4.2 Analysis of Effects and Consequences

A 30 gal/min leak would not result in any measurable core transient. An automatic reactor trip would not be required. A normal reactor shutdown would be accomplished following indications from the leak detection system.

The magnitude of the 30 gal/min leak rate is orders of magnitude below the leak rate that could cause a significant core transient. Analysis indicates that for 3-loop operation, a transient maximum loss rate of approximately 75,000 gal/min would be required for the core sodium temperature to approach the saturation value, and this would require a rupture of about 1.7 square feet at the reactor inlet nozzle. At other postulated primary heat transport system locations, even larger rupture areas would have to be postulated for a peak loss rate of 75,000 gal/min.

Following an indication of a leak, the reactor would be shutdown and the coastdown of the pumps would reduce the system pressure. After pump coastdown (<1 minute), the leak rate would be reduced to a fraction of the 30 gal/min leak rate used for the event because of the pressure reduction and the system would then continue to drain until static equilibrium of the fluid in the system is reached, assuming no operator action to reduce the amount of sodium released. The quantity of sodium which could potentially leak from the system during this period is dependent on the location of the leak and the action that the operator takes. Once the plant is shutdown, the leakage rate becomes so small that the operator would have several days to select a

method for further reducing the sodium leakage. Even if no further action were taken, the system design (guard vessels and elevated piping) would assure that long term core cooling would be provided.

15.3.3.4.3 Conclusions

The improbable occurrence of a leak, on the order of 30 gal/min in the PHTS piping would lead to an inconsequential transient in the reactor. Activation of several leak detection systems would result in corrective action including manual plant shutdown within minutes. The consequences would be limited to an economic penalty for plant downtime, sodium cleanup, and piping repair. Moreover, a leak over three orders of magnitude (70,000 GPM) would not cause hot channel coolant temperatures to approach saturation.

15.6.1.5 Intermediate Heat Transport System Pipe Leak

15.6.1.5.1 Identification of Causes and Accident Description

As in the discussion presented in Section 15.3.3.5, sodium leaks associated with Intermediate Heat Transport System (HTS) are being considered on a different basis from the Primary Heat Transport System (PHTS).

It is expected that results from development programs to be initiated along with inservice inspection considerations, pipe fabrication quality assurance measures, fracture mechanics analysis and tests, and leak detectability will lead to the conclusion that a large leak equivalent to the complete severance of an IHTS pipe is not credible. In particular, data from tests of leak detection capability indicate that the selected methods of leak detection (filter plugging, ionization and cable detectors), insure early detection of small IHTS leaks. However, since the data currently available on corrosion and mixing tee behavior are insufficient at this time for PSAR purposes, it was determined that a prudent approach to analyzing the potential programs associated with an IHTS leak was to examine the limiting case, namely a large leak equivalent to the complete severance of the pipe. As the necessary information becomes available from the various development programs and analyses, it will be possible to analyze this event based on specific leakage rather than on the limiting case approach.

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Based on this discussion an evaluation of leaks equivalent to complete severance of the pipe in the 24-inch IHTS piping is evaluated as the limiting case transient for the IHTS (leaks in branch lines or thermowells are considered to fall within the score of this limiting analysis). The break is assumed to occur at 781 ft. elevation in a horizontal run of piping between the pump and IHX in Loop No. 3 (each side of building) while the intermediate heat transport system is operating at full flow and heat load, and entire contents of the loop are assumed spilled into the sodium catch pans at the 765 ft. elevation.

The leak is assumed to result in a spray of sodium impinging on a flat surface causing splashing and breakup of the high velocity (22 fps) sodium stream, which increases the spill area. This increases the burning rate of sodium and produces consequences characteristic of a spray fire. As a result of the failure causing a sudden pressure reduction at the break, sodium flows from the expansion tank and pump tank to supply sodium to the pump inlet for several seconds. Then pump trip would be expected to result in reactor shutdown and flow coastdown with decreasing sodium velocities. Termination of the spray phase will occur within 30 seconds. The remainder of the loop contents are assumed to spill into the sodium catch pan during the next 30 to 60 minutes as the sodium drains under gravity head.

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The spill volume utilized for this analysis is conservatively evaluated since portions of the superheater and evaporator are below the level of the 24-inch piping and these components would not be expected to be completely drained. The volume also assumes complete siphoning of the IHX tube bundle. This is a very conservative assumption because complete siphoning of the IHX tube bundle is not likely to happen because of the relative elevations of the IHX inlet and outlet nozzles with respect to the horizontal run of 24-inch piping. The area of the resultant sodium pool and therefore, the rate at which sodium is burned during the pool fire is maximized by selecting Loop No. 3.

Loop 3 is the largest of the three loops and this results in a spill quantity of 400,000 lbs. of sodium at a volume-average loop temperature of 800°F. The intermediate system would normally not contain radioactive primary sodium. However, it is postulated for this accident that the plant has been operating with a leak in the intermediate heat exchanger immediately prior to Under normal operating conditions, the intermediate heat the pipe leak. transport system sodium pressure is higher than the primary sodium pressure and any leak would flow from the intermediate to the primary system. A sudden leak in the intermediate system would cause the pressure to drop in the intermediate system and might reverse the direction of leakage. Primary sodium could possibly leak into the intermediate system until the primary pumps are shut off and the primary pressure decreased to the intermediate sodium pressure. Intermediate sodium which is mixed with this primary sodium could then drain out through the intermediate system pipe break and burn in the steam generator building. This is a very conservative assumption because the inert gas pressure on the intermediate system is maintained until after the reactor has been tripped, or until the gas is relieved through the leak.

The pertinent dimensions and ambient conditions of the Intermediate Bay are itemized in Table 15.6.1.5-1. The cell is ventilated at an air flow rate of 1000 cfm. The ventilation system is manually controlled and it is assumed for the evaluation of sodium burning rates and temperatures that the ventilation system is not shut off until five minutes after the spill. The ventilation rate is low enough so that the consequences of the fire are not strongly affected by the time of shutoff within approximately the first 30 minutes. Smoke detectors will alert the operators to the fire. An oxygen suppressing grating is installed above the sodium level in the catch pan which covers the floor area at the 765 ft. elevation. The internal recirculating air coolers are assumed inoperative. Nitrogen flooding is provided for in the event of a fire, and the nitrogen flow would be adjusted to maintain a slight positive pressure of a few inches of water to prevent inleakage during cooldown.

15.6.1.5.2 Analysis of Effects and Consequences

The spray is produced by impingement of sodium discharge from the break in the outlet pipe at the 781 ft. elevation. This leak location was selected since it is farthest from the pump suction and therefore maximizes

- h. When an audit response has not been received in the allotted time.
- When Nonconformance Review Board actions determine that a corrective action is required to obtain a specific corrective/ preventive action.
- a proposed action from the recipient of the request. The required CAR response contains the proposed corrective action to preclude repetition, the persons responsible for implementation of the actions, and the schedule by which they will be completed. This is reviewed for acceptability by Quality Assurance and Engineering as may be applicable. Areas involved in corrective actions are verified by Quality Assurance at the end of the scheduled period for implementation of the corrective action. When a CAR is issued, the fact is recorded on a CAR summary. The summary identifies the originator of the request and the date. It provides a description of the deficiency, identifies the organization responsible for answering, the date a reply is required and the type of deficiency. When an answer is received, the date of the required verification of the correction is added to the summary. Frequent review of this summary defines that status of all corrective action requests issued and provides a means for effective follow-up until the request is closed.

16.3 DISTRIBUTION OF CORRECTIVE ACTION REQUESTS

Internal CARs are distributed to the responsible organization representative, the Cognizant Project Engineering Manager, and any others as may be required by the individual corrective action being requested. CARs for suppliers or contractors are transmitted via a transmittal letter to the concerned contractor or supplier through contractual channels.

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17.1 QUALITY ASSURANCE RECORDS SYSTEM

The AE has established a Quality Records Management Plan providing the general requirements for records identification and collection for transfer to the Owner. The Quality Records Center (QRC) processes those records resulting from activities that are necessary to define the overall program quality and provide objective evidence of quality achievement. The system includes provisions that ensure:

- Records are processed to provide documentary evidence of the quality of items and activities affecting quality.
- QA records include operating logs; results of reviews, inspections, tests, audits, and material analyses; monitoring of work performance; qualification of personnel, procedures, and equipment; and other documentation such as drawings, specifications, procurement documents, calibration procedures and reports, and deviations and corrective action reports.
- 3. Records are readily identifiable and retrievable.
- 4. Requirements and responsibilities for record transmittals, retention, and maintenance subsequent to completion of work are consistent with applicable codes, standards, and procurement documents.
- 5. Inspection and test records contain the following:
 - a. A description of the type of observation
 - Evidence of completing and verifying a manufacturing, inspection, or test operation
 - c. The date and results of the inspection or test
 - d. Information related to deviations
 - e. Inspector or data recorder identification
 - f. A statement as to the acceptability of the results
- 6. Record storage facilities provided by the owner are located and secured to prevent destruction of the records by fire, flooding, theft, and deterioration by environmental conditions such as temperature or humidity.

The Quality Records Management Plan is executed using approved procedures which address the following major elements:

- o Declaring
- o Filing
- o Storage
- o Retrieval

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52		1)	Maintaining and administering the Quality Program Audit System by preparing and maintaining audit schedules.
	551	2)	Arranging for checklists; conducting or arranging for audit teams to conduct audits.
		3)	Insuring preparation of audit reports.
		4)	Follow-up to verify corrective action implementation.
		5)	Maintenance of audit case history files.
1		6)	Development, issuance, control, and revision of Quality Assurance Manuals and procedures.
		7)	Review of operating procedures, and revisions thereto, prepared by other quality-affecting organizations, to assure compatibility with overall ESG Quality Assurance Program requirements.
	551	8)	Performing supplier quality surveys of procurement sources for materials and fabrication services and maintenance of the approved list of such supplies.
	551	9)	Administering a Material Review System for nonconforming items.
52	551	10)	Administering a Corrective Action System to assure prompt and effective correction of conditions causing nonconformance to technical requirements/procedures.

- Quality Assurance Engineering LMFBR Programs Manager The
 Quality Assurance Engineering LMFBR Programs Manager is responsible +o
 the Quality Assurance Director and provides quality assurance engineers
 to support the CRBRP Quality Assurance Project Manager. The Quality
 Assurance Engineering LMFBR Programs Manager is responsible for performance
 of the following activities:
 - Quality Assurance Program administration for specific portions of the CRBRP activities, to monitor and assure effective implementation of quality requirements, from design through procurement and fabrication.
 - 2) Quality engineering support for change control boards, design reviews, and design document review and approval.
 - 3) Nonconforming item review board coordination.
- 4) Develop and implement statistical test programs and analyses as required.
- 5) Provide source inspection, planning, and surveillance of suppliers of materials and fabrication services.
- 52 6) Review and evaluate bid invitations and returns for quality impact.
 - 7) Participate on capability evaluation teams for prospective suppliers of major items.
 - 8) Procurement document review and supplier quality surveys for materials and fabrication services and maintenance of the approved list of such suppliers.
 - 9) Receiving inspection planning.
 - 10) ESG fabrication inspection planning.
 - A quality data and records collection and storage system for procured and ESG-fabricated items.
 - 12) Data packages for ESG-fabricated items.

Quality Assurance Engineering Utility and Energy Programs Manager - The Quality Assurance Engineering Utility and Energy Programs Manager is responsible to the Quality Assurance Director.

This function does not provide any services to the CRBRP Project Manager.

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Appendix B Criterion	ESG Implementing Document or Procedure		
	Number	Title	
I. Organization	SOP M-10	Program Management	
	SOP Q-10	ESG Quality Assurance Program	
	QAOP N1.21	Quality Assurance Plans	
II. Quality	SOP A-01	ESG Policies and Procedures	
Assurance	SOP M-10	Program Management	
	SOP Q-10	ESG Quality Assurance Program	
	SOP Q-16	Quality Assurance (QA) - Program Support Functions	
	SOP Q-12	Quality Assurance Program Audits	
	SOP Q-18	ESG Quality Records	
	PMD No. 16	Quality Assurance Management Reviews	
	PMD No. 11	CRBRP Document Hold Status System	
	PMD No. 20	CRBRP Training and Indoctrination	
	PMD No. 27	CRBRP Document Status System	
	EMP 3-1	Engineering Documentation Process	
	CMP 2.126	Case File Documentation	
	QAOP N1.00	Preface to Quality Assurance Manual	
	QAOP N1.01	Quality Assurance Department Functions	
	QAOP N1.03	Vision Requirements for Quality Assurance Personnel	
	QAOP N1.21	Quality Assurance Plans	
	QAOP N1.23	Quality Status Reports	
	QAOP N6.02	Qualification and Certification of Nondestructive	
	CS3M2.4	Examination Personnel	
	QAOP N7.02	Qualification and Certification of Visual and Dimensiona Inspection Personnel	
	QAOP N8.00	Statistical Quality Control Program	
	QAOP N13.02	Quality Assurance Data Packages	
	CS3M2.3	Training	

Figure 17J-4. Quality Assurance Procedure Index vs Requirements of 10 CFR 50, Appendix B (Sheet 1 of 13)

	Appendix B	ESG Implementing Document or Procedure		
	Criterion	Number	Title	
	II. Quality Assurance	CS3M17	Quality Assurance Records	
	Program (cont'd)	PMD-13	CRBRP Licensing Administrator	
	III. Design Control	SOP M-10	Program Management	
		SOP N-14	Configuration Summary Reports	
		PMD No. 1	CRBRP Correspondence Control	
		PMD No. 11	CRBRP Document Hold Status System	
		PMD No. 15	Schedule Development and Control	
		PMD No. 19	CRBRP SDD Preparation and Revision	
		PMD No. 21	CRBRP Development Activities	
17J-39		PMD No. 25	CRBRP Parts Standardization	
(4)		Prid No. 26	Use of Controlled Information Data Transmittal (CINDT)	
9		PMD No. 27	CRBRP Document Status System	
		PMD No. 30	CRBRP Specifications	
		PMD No. 32	CRBRP Design Reviews and Release	
		PMD No. 34	Application of Additions to ASME Code Requirements	
		PMD No. 36	Engineering Drawings	
		PMD No. 40 PMD No. 41	Materials and Processes for CRBRP	
		PMD No. 54	Baselining of Documents	
		EMP 1-0	SHRS Reliability Program Preface to Engineering Management Procedures Manual	
		EMP 2-8	Engineering Studies	
		EMP 2-9	Design and Acceptance Criteria	
		EMP 3-3	Limited Release System	
		EMP 3-5	Standard Release System	
		EMP 3-42	Engineering Management System for Specifications	
Amend. 56 Aug. 1980		Figure 17J-4. Quality Assurance Procedure Index vs Requirements of 10 CFR 50, Appendix B (Sheet 2 of 13)		

AMENDMENT 56

LIST OF RESPONSES TO NRC QUESTIONS

There are no new NRC Questions in Amendment 56.