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Prepared for U.S. Nuclear Regulatory Commission Washington, D.C. 20555

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INTERNAL TECHNICAL REPORT

ANALYSIS OF A TRANSIENT LOAD MEASURING SYSTEM

(LTR)

Title:

Organization:

LOFT EXPERIMENTAL MEASUREMENTS BRANCH

organization.

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LOFT TECHNICAL REPORT LOFT PROGRAM

Analysis of a Transient Load Measuring Sys	tem LTR-L0-87-80-132		
R. R. Good, T. R. Meachum	G # A NO.		
LOFT Experimental Measurements	CATE RELEASED BY LOFT CDCS		
PSE LEMB LEPD Mar. Mar.	March 17, 1980		

ABSTRACT:

An analysis of the performance of a load measuring system is presented. The load system was designed to measure the weight of a pressure vessel containing high pressure and temperature water. The uncertainty and frequency response of the system are quantified for both steady state and dynamic conditions as is the repeatability of the test rig.' Computation of the mass flow exiting the system during explosive decompression of the system is also presented.

DISPOSITION OF RECOMMENDATIONS

No disposition required.

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SUMMARY

An analysis of the weight measuring system used in a series of transient steam water flow tests is herein presented. The analysis yialds two sigma static uncertainties of 0.59% RG and dynamic uncertainties of 7.8% RG. The system frequency response is flat to 0.3 hz, and not quantified at any higher frequencies. The purpose of the weight measuring system is to provide a reference mass flow for assessing the performance of a variety of experimental mass flow transducers. The experimental transducers are currently used in the Loss-of-Fluid Test (LOFT) program. Thus in addition to the uncertainty in system weight, this analysis quantifies the repeatability of the test rig, and describes in detail the computation of mass flow given the time history of system weight.

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I. INTRODUCTION

A transient steam water calibration facility was constructed to test Loss of Fluid Test (LOFT) mass flow instrumentation. The primary design criterion of the facility was the capability to calibrate LOFT instrumentation under fluid conditions identical to those in LOFT. Achievement of the design goal required that the geometry and initial fluid conditions of LOFT be duplicated and that a reliable reference mass flow instrument be installed in the calibration system. There exists no standard reference instrumentation for multiphase calibration facilities, thus all mass flow sensing methods were considered. The requirements for an acceptable reference were severe. The reference must survive a high pressure (15.5 MPa) temperature (550 K) environment, measure the global mass flow through the blowdown piping, and be unaffected by the multi-phase nature of the flow. The only instrument which met these requirements was a load cell based weighing system. This paper presents an analysis of the frequency response, static and dynamic uncertainties of the load cell system.

The quantification of the uncertainty in mass flow measurement was achieved through a combination of experimental and analytic techniques. The lack of a recognized standard for multiphase mass flow calibration forces all uncertainty estimates to be compared to single phase standards, this creates uncertainties quantifiable only be engineering judgement. The stochastic nature of fluid requires that averaging techniques be applied to the data to produce repeatable results. The selection of appropriate averaging methods also requires engineering judgement to be utilized. Thus, the assessment of the accuracy of the reference instrumentation was a combination of engineering judgement and standard single phase calibration techniques.

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Uncertainty was quantitative both for static and dynamic conditions. The static uncertainty limits the uncertainty in the total mass flow and provides a lower bound for the dynamic uncertainty if no filtering is applied. The dynamic uncertainty quantifies the frequency response of the mass flow measurement and the uncertainty in the measurement at each frequency. The mass measurement repeatability between tests is addressed both in the static and dynamic analyses.

II. WEIGH SYSTEM DESCRIPTION

The design goal of the WTT load cell weigh system was to weigh the WTT system during explosive decompression. The weigh system consisted of two primary subsystems, the load system, and the data processing system. The load system produced a filtered electrical output proportional to the system weight. The data processing system used the electrical output of the load system to produce system weight and rate of change of system weight in engineering units. Figures 1 and 2 respectively present schematic representations of the weight and data processing subsystems.

The pertinent aspects of the load system are the load cells, the sway bracing and the air bag supports for the blowdown piping. The design concept was to support the weight of the blowdown vessel and fluid on the load cells and the weight of the blowdown piping and stabilizing mass on the air bag support system. Computer analysis, Reference 3, indicated that a negligible (< 15 Kg) amount of load sharing would occur between the load cells and the air bag support. Unfortunately this computer analysis neglected long term thermal effects as initially only short duration blowdowns were anticipated. The long term thermal effects problem resulted in a redesign of the load cell system. The primary change was the addition of another load cell. The weigh system configuration change and its effect on overall system uncertainty will be documented in a later report. This report addresses only fast transients (< 300 sec) for which the computer analysis was assumed valid.

The load cells were selected with fast transient capability. The load cells were manufactured by Interface. Appendix A contains the manufacturer's specifications. Briefly each load cell has a range of 0 - 226.82 Kilonewtons and a frequency response of not less than 100 Hz. The load cells are a strain gauge shear web design. Each

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load cell has a dual bridge; one is inputted to the data acquisition system, and the other is displayed in real time. The system consisted of three load cells spaced at 120 degree intervals around the vessel as shown in Figure 3. The output of the load cells was algebraically summed which produced an output directly proportional to load.

The air bag support system was the only other major load bearing component in the weight system. The air bag support system consisted of two separate supports, one located next to the vessel, and one at the end of the blowdown leg. Air bags were supplied by Firestone and Lord Kinematic. Firestone air bags were located closest to the vessel and the Lord Kinematic supported the stabilizing mass at the end of the blowdown leg. Manufacturer's specifications and schematic diagrams, for these components are given in Appendix B. The relative stiffness of the air bag and load cell supports determines the amount of load sharing which will occur. The ratio of stiffness of load cells to air bag (See Reference 2) support is at least 1000; thus, the load cell support system would acquire at least 1000 newtons of load for every 1 newton the air bag system acquires. The load sharing described assumes no major structural changes occur in the system.

The only major non vertical load bearing component of the weigh system were the sway braces. The design goal of sway brace system was to restrain all horizontal motion of the vessel. The design concept was to restrain the vessel with large mechanical braces. Implementation of this system resulted in the sway braces absorbing some of the vertical loading of the vessel. This system was redesigned for the second series of tests.

The software system for producing mass flow data is documented in Appendix C. The essentials of the software process are (1) 50 sample/sec sampling rate, (2) optional low pass digital filter, (3) differentiating by computation of finite differences, (4) output of data. Additionally, the program documented in Appendix C computes the mass flow based on information from the vessel differential pressure cells and compares the differential pressure and load cell data. The program is written in Fortran IV and is implemented compare CYBER 173-176 system. Provision has been made for reproduction of higher frequency load cell data via 5000 Hz analog recording of the load cell bridge output.

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III. STATIC LOAD CALIBRATION

The WTT load system was statically calibrated. The static load tests consisted of a series of fill, hydrostatic, and heatup tests. The fill tests established the load cells accuracy, the degree of load sharing between the load cells and airbag supports, and the effects of asymmetric loads on the vessel. The hydrostatic pressure tests and heatup tests quantified the WTT system sensitivity to pressure and temperature. The fill tests were conducted prior to and during the actual blowdown testing period. The pressure sensitivity of the weigh system was not suspected until after testing began; thus the pressure tests were conducted during the transient testing period. Attempts at quantifying the temperature sensitivity were made prior to and during transient testing. The results of the static load testing were in general satisfactory.

The fill tests consisted of metering water into the WTT system and recording the output of the load cells. The load cells were dual bridge devices. One set of bridges was summed analog and the output displayed. The second set of bridges was inputed to the data acquisition system. A total of six cold fill tests were conducted on the WTT system. The tests spanned a two and one half month interval. Table I summarizes the data from these tests and Figure 4 is a plot of a typical series of data sets. The reference instrument for each fill test was a Foxboro Mark 1 F1-16-SB full flow turbine serial number 31064. The uncertainty of this turbine was <0.2% RG as determined by single phase flow testing by the Foxboro Company.

The procedure for conducting a cold fill test involved metering water into the WTT system and recording the output of the load cell system and the amount of water metered into the vessel. Appendix D is the test procedure used to perform the fill tests. The data used to calculate the WTT system static uncertainty was acquired by the Wyle computer system and therefore incorporates the uncertainties due to quantization, signal transmission, and computer system effects.

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The effect of asymetric system loading was quantified during the fill tests and by subjecting the load ring to point loads of approximately 1250 newtons. Asymetric loads of approximately 4406 newtons were placed on the system during the fill tests due to the mass distributed in the blowdown piping. No measurable change in the sum of the load cell outputs was detected while asymetric loads were placed on the system; therefore, the effect of asymetric loads on system uncertainty is deemed neglible, <0.05% RG.

The WTT system static load uncertainty design requirement was 1% RG. Range was 40800 newtons. Range was determined by the mass of water required to fill the WTT system at 15.5 MPa and 550 K. The required uncertainty of the weigh system was achieved after modification of the air regulating system and the turbine meter fill system. The static system weigh uncertainty was 0.59% RG (241 newtons).

The long term drift uncertainty of the weigh system was astablished by repeating the calibrated fill tests approximately two months later. Figure 5 is a comparison of two calibration tests taken two months apart. There is no statistically significant (95% confidence) difference in the calibration coefficient (the offset varies but this is removed on a test by test basis). Thus, long term drift uncertainty is deemed negligible (<0.05% RG).

Uncertainty in system load due to pressure effects was quantified in a series of cold and hot hydrostatic tests. The results of these tests are tabulated in Table II. Figures 6 and 7 represent the range of results obtained. A total of four cold pressure tests and two hot pressure tests were conducted. In general, the system load appeared sensitive to pressure; however, no repeatable functional relationship could be derived. Investigation of system load at decompression initiation revealed a step change in load occurring simultaneously with system subcooled depressurization to saturation and no detectable

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load sensitivity to pressure during the remaining depressurization. Figure 8 is a typical load cell blowdown trace illustrating the initial step change. Analysis of data gathered during transient testing indicated that the sway brace system was assuming significant vertical load during system pressurization and was releasing that load when the depressurization shock wave propagated through the system. A hot hydrostatic test and system depressurization was conducted with the sway brace system removed to verify the analysis. Figure 9 presents the hot hydro with sway brace removed data. The data indicate a slight increase in load with pressure. The increase in system load is commensurate with the mass required to raise the system pressure by 7.5 MPa. Thus, the removal of sway braces removed any system pressure sensitivity. The weigh system uncertainty due to pressure changes was deemed negligible (<0.05%) if a mechanical shock sufficient to remove any friction vertical load bearing in the sway brace system occurs prior to measurement. If a mechanical shock does not occur, the uncertainty is approximately 27% RG.

The weigh system uncertainty due to temperature fluctuations was not fully quantified. Tests were conducted to reveal system sensitivity to small (20 K) temperature fluctuations. Those tests demonstrated no significant weigh system temperature sensitivity. WTT system design precluded varying system temperature significantly while maintaining system mass constant. Thus, no quantitative large scale system temperature sensitivity was calculated. System temperature sensitivity was judged neglible for transients less than 300 seconds.

The static weigh system uncertainty consists only of the uncertainty in the force measurement of the load cells as all other uncertanties are less than 0.05% RG assuming that the effects of the sway bracing have been nullified. The uncertainty in system weight under static conditions is therefore \pm 255 newtons (\pm 25.5 kg or 0.59% RG).

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IV. DYNAMIC LOAD UNCERTAINTY

The quantification of the Wyle Transient Test system's dynamic uncertainty requires both experimental and analytic methods. The experimental methods allow the direct measurement of the system's response to physical excitation. The analytic approach yields estimates of the system uncertainty given the system's static response and the filtering applied to the output. Thus estimates of the system's frequency response have been obtained experimentally and quantification of the system uncertainty has been obtained analytically.

The experimental analyses involve the load cells and their structural support system. The support system acts as a complex damped spring mass system, the spring constants, etc. of which are unknown. The experiments performed to quantify the system frequency response included low frequency excitation of the system and broad band system excitation via explosive decompression of the system. The lowest frequency observed during either explosive decompression or low frequency excitation was 3 Hz. Figures 10 through 13 are power spectral densities (PSD's) of the individual load cells and their electronic summation. There is a clear peak evident in the PSD's of load cells 002 and 242 and a slightly more ill defined peak in load cell 122 and the net load. All of these peaks occur within 0.2 hz of 3 hz. Figures 14 and 15 present PSD's of the output of a velocity and momentum flux instrument respectively. These instruments are located in the center of the blowdown piping 2 meters from the blowdown vessel. Neither the velocity nor momentum flux PSD exhibits any clearly defined peaks. Thus since these two measurements incorporate both density and velocity measurements it is evident that the 3 Hz phenomena measured by the load cell system is an artifact of the load alls and their support system, not a real oscillation in mass flow. The experimental data then provides the basis for engineering

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jud ent in establishing the upper bound of frequency response for mass flow computed using the load cells. This upper bound is set at 0.3 Hz, one decade below the lowest measured load cell system resonant frequency.

The computational software system provided the means for extracting the desired frequency range and calculating the mass flow given system mass. Analysis of the software system provided an estimate of the uncertainty in mass flow after the signal had been processed. Signal processing consisted of analog and digital filtering. The analog filtering consisted of a 4 pole 10 Hz filter. The digital filter was a convolution of a 112 term low pass filter and a 25 term derivative filter. The digital filters were implemented as a weighted sum of finite differences. Figure 16 is the transfer function of the digital filter. All signals used to calculate the static uncertainties were passed through the analog filter, hence any uncertainty associated with the analog filter is integral to the static uncertainty estimate. Uncertainties associated with the digital filter are calculated via Equation (1) (see Reference 4).

$$\sigma_f^2 = \sigma_u^2 \sum_{K=-K}^{K} c_K^2$$
 (1)

where

$$\sigma_f^2$$
 = uncertainty in filtered output
 σ_u^2 = uncertainty in unfiltered output
 C_v = coefficients of digital filter.

Equation (1) yields an estimated uncertainty in mass flow of 2.16×10^{-3} newtons/sec (0.22 grams/sec) given the static uncertainty of (25.5 kilograms). A basic assumption of Equation (1) is that the

system being filtered is a linear time invariant system. This assumption is probably invalid when considering signal magnitudes of the order of 1 newton or less. Thus a reasonable engineering estimate of the uncertainty in system mass flow is 0.5 kg/sec (2σ) , assuming that the digital filter described in Appendix C is applied to the data.

The dynamic uncertainty within any single test has now been analytically quantified. The dynamic repeatability however remains unknown. The dynamic repeatability is a function of many independent variables. These variables include initial system pressure, water temperature, metal temperature, and temperature distribution. Few of these parameters are well defined, thus an experimental approach must be employed to obtain meaningful estimates of the system's dynamic repeatability.

The WTT experimental series included several replications of identical pretest configurations. Table III presents the results of comparing the first and second test series. Figure 17 is an overlay of the mass flow for three identical blowdown tests. Estimates of the instantaneous repeatability between tests were obtained by computing the deviation from the first test of the test series. All tests started at time zero as defined by the time a 5.0 MPa drop occurred across an orifice in the blowdown piping. Equation (2) was used to compute system instantaneous repeatability as well as integrated mass repeatability.

$$\sqrt{\sigma_{I}} = \sqrt{\frac{\sum_{j=2}^{n} (x_{1} - x_{j})^{2}}{n-1}}$$

(2)

where

 X_1 = reference channel

 $X_i = all other channels$

 $\sqrt{\sigma_{T}}$ = instantaneous standard deviation

Figure 18 is a plot of instantaneous repeatability of mass flow for the first test series. System instantaneous repeatability varies widely during the blowdowns with the largest levels occurring during the subcooled portion of the blowdowns and at approximately 20 to 25 seconds. The time period of 20 to 25 seconds corresponds to the time when the downcomer uncovers. The mean instantaneous repeatability in mass flow for time segment is given in Table III.C.

V. CONCLUSION

The transient steam water calibration facility's reference mass flow system has proven to be an accurate, repeatable and durable system. The isolation of the transducers from the internal environment of the system has allowed the mass flow system to perform reliably for more than twenty experiments. The nature of the transducers, being they measure system weight directly, has contributed to their accuracy and has eased the computational requirements to preduce mass flow rate. The uncertainty in static system weight is + 25.5 Kg, the uncertainty in mass flow (assuming filtering is applied to the signal) is 0.5 Kg/sec. The weight systems frequency response is flat to 0.3 Hz and has not been quantified for greater frequencies. Additionally the transient facility's repeatability has been quantified. The repeatability of the weigh system is an integral part of the transient system's repeatability but has not been quantified separately. The transient systems worst case repeatability is + 20.1 Kg/sec, 7.8% of range.

It is the recommendation of the authors that load cell based systems be considered for all future transient two phase systems and that weigh systems be recommended as a standard reference for the industry.

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TABLE I

Test No.	Date	Calib Coeff Kg/Volt**	ration icient Newtons/Volt	Correlation Coefficient	Stand Devia of Y	lard ation (on X lewtons	# of Points
1	6/26/79	1731.6	17282	0.9997	23.7	237	21
2	6/28/79	1690.5	16871	1.0000	10.0	100	22
3	6/28/79	1689.5	16861	1.0000	12.7	127	19
4	7/2/79	1434.5*	14316	1.0000	66.2	661	9
5	7/25/79	1699.5	16961	0.9999	8.8	88	27
6	8/29/79	1702.7	16993	1.0000	8.7	87	24

CALIBRATED FILL TESTS OF THE WYLE TRANSIENT TEST FACILITY

* Flow meter partially bypassed thus this point is not used in any analyses.

** Volts = sum of output of loadcells 1, 2, & 3 from data acquisition system
output.

TABLE II

Test #	Pressure Range MPa	Maximum Force Range Newtons	Data	Temperature K
1	15	1355	8-6-79	350
2	14	9108	8-22-79	350
3	15	1014	8-28-79	350
4	5	3401	8-30-79	500
5	7.5	1181	9-5-79	500
6	17	1866	7-25-79	350

WYLE TRANSIENT TEST SYSTEM PRESSURE SENSITIVITY

.

TABLE III

COMPARISON OF INSTANTANEOUS REPEATABILITY

A. RMS ERROR (Kg/sec)

TIME INTERVALS (SECONDS)

Test Series	0-10	10-20	20-25	25-40	40-60
IA1	20.1	9.4	17.2	10.3	2.1
IA2	22.8	7.4	16.6	5.0	1.9

B. MASS FLOW (Kg/sec)

TIME INTERVALS (SECONDS)

Test Number	0-10	10-20	20-25	25-40	40-60
IA101	175.7	128.9	59.6	18.2	3.6
IA102	188.0	126.3	83.7	28.5	2.6
IA103	175.6	130.1	83.7	30.8	4.0
IA1 Series (Avg)	179.8	128.4	75.7	25.8	3.4
IA201	178.2	129.5	85.9	29.5	3.5
IA202	169.4	130.3	74.2	24.9	2.6
IA2 Series (Avg)	173.8	129.9	80.1	27.2	3.1

C. % OF RD UNCERTAINTY IN MASS FLOW

TIME INTERVALS (SECONDS)

Test Number	0-10	10-20	20-25	25-40	40-60
IA101 IA102 IA103 IA1 Series (Avg) IA201 IA202 IA2 Series (Avg) Mean	11 11 11 13 13 13 12	7 7 7 6 6 6 7	29 21 21 23 19 22 21 23	57 36 33 40 17 20 18 32	58 81 53 62 54 73 61

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WYLE LOAD CELL CAL SUM OF LOAD CELLS VERSUS REF MASS



FIGURE 4

10-8-79

WYLE LONG TERM DRIFT TEST SUM OF LOAD CELLS VERSUS REF MASS



FIGURE 5

11-28-79

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WYLE LOAD CELL PRESSURE SENSITIVITY HYDRO



FIGURE 6

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0-07-00-10

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8-28-79





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8-22-79

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TYPICAL LOAD CELL BLOWDOWN VOLTAGE TRACE

FIGURE 8





9-5-79

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DIGITAL FILTER TRANSFER FUNCTION





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4
OVERLAY OF WYLE IA1 SERIES (3 TESTS)



WYLE IA1 SERIES (3 TESTS)



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FIGURE 18

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FIGURE 19

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APPENDIX A

LOAD CELL SPECIFICATIONS

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8200

2550

3600

4350 .

6000

5350

600

1000

1550

1850

2350

2150

3350

2150

3350

1750

2050

1311-1K

1311-2K

1311-5K...

1311-10K

1321-25K

1321-50K

1410-50

1410-100

1420-250

1420-500

1921-30K

SM-10

SM-25

SM-50

SM-100

SM-250

SM-500

SM-1000

SSM-500

SSM-1000

SSB-100

SSB-250

NATURAL



MODEL	FREQUENCIES	(H_z)		MODEL	FREQUENCIES	(H_z)
1010-500	6950	Hz		1211-1K	6350	Hz
1010-1K	9850	11 *		1211-2K	9000	
1010-2 5K	6600	11		1211-5K	6050	11
1010-54	9350	H		1211-10K	8600	11
1020 12 54	6450	н		1221-25K	8200	
1020-12.50	7000	0		1221-50K	11650	н
1020-25K	5000			1231-100K	7550	и.
1032-50K 1040-100K	4950	н		1241-200K	6700	н
1110 18	6050	н		1310-1K	6950	н
1110-16	0950	18		1310-2K	9850	11
1110~CK	9030			1310-5K	6600	п.,
1110-56	0000	18	and Service	1310-10K	9350	11
1110-10K	9350	11		1320-25K	6450	14
1120-25K	0450	15		1220 504	7000	11
1120-50K	7000			1330-100K	7550	н
1111-1K	6350					

CALCULATED NATURAL FREQUENCIES (AXIAL) FOR INTERFACE LOAD CELLS

NATURAL

3	A	n	A	0	з
ş	1	u	u	C	×
1		0	P	1	
- 1	9	- 2	C	~4	

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1111-10K 1121-25K	8600 5850	и И	
1121-50K	6550		
1210-1K	6950	8	
1210-2K	6600	н	
1210-10K	9350	<u>u</u>	
1220-25K	6450 7000	u	
1232-100K	5800	n	
1240-200K	4950	- "	
MB-5	950	H	
MB-10	1300	8	
MB-25	2250		
MB-50 MB-75	3900	H	
MB-100	4000	u	
MB-150	4750	11	
MB-250	4400		

11

n

11

9000

6050

8600

1111-2K

1111-5K

MAXIMUM ERROR BAND, COMPUTED ON A BEST STRAIGHT-LINE THROUGH ZERO BASIS, INCLUDING NON-LINEARITY HYSTERESIS AND REPEATABILITY. +.018 SYSTEMS CALIBRATION with DS-300-T2 undicator \$N 62751 R-cal= 34920 lb A2 Resonant Frequency = 11650 Hz INTERFACE INC. 7401 EAST BUTHERUS DRIVE . SCOTISDALE, ARIZONA 85260 TLX 668 394 TELEPHONE 602 - 948-5555 USA



TWO YEAR WARRANTY

Interface, Inc. hereby warrants all products of its inanufacture as follows: Commencing with the date of shipment of each load cell to the original purchaser, and for a period expiring two years from said date, Interface, Inc. unconditionally warrants that each unit shall remain free from defects in parts, materials, and workmanship.

The warranties herein shall not obligate Interface, Inc. in any manner whatsoever with respect to, and shall not be applicable to, any defects which after inspection by Interface, Inc. are not to Interface, Inc.'s reasonable satisfaction demonstrably the result of defective parts, materials or workmanship. Interface, Inc. is not liable for consequential damages. All transportation charges for returned merchandise are to b repaid and borne by customer.

CERTIFICATION

Interface, inc. cellufies that this load cell was thoroughly tested and inspected and found to meet its published specifications when shipped from the factory. Interface, Inc. further certifies that its calibration measurements are traceable to NBS.

INSTALLATION

The load cell should be mounted on a surface which is flat and parallel within 0.0002 T.I.R. for Universal, and within 0.0005 T.I.R. for compression units. It should be mounted to the surface with grade 8 bolts evenly tightened to the following torques:

Bolt Size	8-32	2	10-32		1/4-28	
Installation Torque (ft, lbs.)	2		4	5 10	(Alum.) (Load Cell) (Steel) (Load Cell)	
Bolt Size	5/16-24	3/8-24	7/16-20		5/8-18	
Installation To-que (ftlbs.)	25	55	130		303	

9743 Model 1221-J2 Customer Sales Order

Purchase Order __

	CA	LIBRA	ATION	
Bridge" _	A		Date	12-15-78
Range	50,000	Ibs.	Serial	No. 12291
Input Res	istance			ohm
Output R	esistance			3:0.7_ohm
Recomme	ended Excitation			10_VDC or VA
Maximum	Excitation			20 VDC or VA
Non-Line	arity (terminal)			REFER TO % F
Hysteresis	5			"NOTES" % F
Compensa	ated Temp. Range			+15 °F 10 +115 °1
Thermal 2	Zero Shift			. 0008 % FS/ 1
Zero Bala	nce			.09 %F
Tension C	Jutput			MV/
Compress	ion Output			4.002 MV/

WIRING

Function	Pin	Pigtail
+ Excitation		Ren - with / Ren
+ Output		WH- WH/422.
- Output		BRID
- Excitation		BUK-WH/BUK
Shield		
Polarity shown result	in positive output	ut for:

(compression)

(toneron)

TR-L0-87-80-

SHUNT CALIBRATION



IXAN	NUM PREO	R BAND	COMP	UTED ON	A
NC11	DING NOU	LINE TH	KOUGH	LEKU BA	515,
NCLU	TABULTY	HINEAKI	14-1112	CHESIS-A	NU
(EPEA	TABILITT. 4	-,026			

with DS-300-TZ indicators

R-cal = 34930

-A4-

INTERFACE, INC.

7401 EAST BUTHERUS DRIVE . SCOTTSDALE, ARIZONA 85260

TLX 668-394

TELEPHONE 602 - 948-5555

555

USA

CALIBRATION

Interface

Load Cell

LTR-L0-87-80-132

CERTIFICATE

L79894

WARRANTY

INSTALLATION

TWO YEAR WARRANTY

Interface, Inc. hereby warrants all products of its manufact re as follows: Commencing with the date of shipment of e...h load cell to the original purchaser, and for a period expiring two years from said date, Interface, Inc. unconditionally warrants that each unit shall remain free from defects in parts, materials, and workmanship.

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INSTALLATION

The load cell should be mounted on a surface which is flat and parallel within 0.0002 T.I.R. for Universal, and within 0.0005 T.I.R. for compression units. It should be mounted to the surface with grade 8 bolts evenly tightened to the following torques:

Bolt Size	8-32	1	0.32	1/4-28
Installation Torque (ftlbs.)	2		4	5 (Aium.) (Load Cell) 10 (Steel) (Load Cell)
Bolt Size	5/16-24	3/8-24	7/16-20	5/8-18
Installation Torque (ft. lbs.)	25	55	150	300

The load cell mating thread should be class 3.

Customer Wyle Laboratories Sates Orger 9743 Model 1221-32

Purchase Order ____

CALIBHA	ATION
Bridge*A	Date _/2-19-75
Range 50,000 lbs.	Senal No. 12292
Input Resistance	367.4 ohm
Output Resistance	3 50-7 ohm
Recommended Excitation	10 VDC or VAC
Maximum Excitation	20 VDC or VAC
Non-Linearity (terminal)	REFER IO % FS
Hysteresis	"NOTES" % FS
Compensated Temp. Range	+15 "F to +115"
Thermal Zero Shift	% FS/ S
Zero Balance	%F5
Tension Output	MV/
Compression Output	4.000 MVA

	WIRING	
Function	Pin	Pigtail
+ Excitation		Len wir ken
+ Output		WN-WALTA.
- Output		Gen
- Excitation		B.K- WH/BLK
Shield		
Polarity shown res	ults in positive output l	for:

(compression)

(Ineren)

R

L0-87

SHUNT CALIBRATION



ALC PROVE An al Grows LTR-L0-87-80-132 ane reachance SALARS AND A LAND AND A Load Cell ----An and the second NFORM ATION INSTALLATION CALIBRATION CERTFICATE ATMASSAMTV 199395 - and a star star and star 1. é ----CARTINE LA CONTRA BURNET PLAN STATES FIRE AND ADD SYSTEMS CALIBRATION 7401 EAST BUTHERUS DRIVE . SCOTTSDALE, ARIZONA 85260 NSN WAND, COMPUTED ON A TALLEING HONCINEARITY HYSTERESIS AND with DS-300-12 indicated MET STRAIGHT UNE THROUGH ZERO BASH, TELEPHONE 002 - 948-5505 INTERFACE, INC. Le. R-cal = 34830 REPSTACHEN, 1 125 5/2 62751 11 X 668-354

-A6-

TWO YEAR WARRANTY

Interface, Inc. hereby warrants all products of its manufacture as follows: Commencing with the date of shipment of each load cell to the original purchaser, and for a period expiring two years from said date, Interface, Inc. unconditionally warrants that each unit shall remain free from defects in parts, materials, and workmanship.

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CERTIFICATION

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INSTALLATION

The load cell should be mounted on a surface which is flat and parallel within 0.0002 T.I.R. for Universal, and within 0.0005 T.I.R. for compression units. It should be mounted to the surface with grade 8 bolts evenly tightened to the following torques:

Bolt Size	8-3	2 1	10-32		1/4-28	
Installation Torque (ftlbs.)	2		4	5 10	(Alum.) (Load Cell) (Steel.) (Load Cell)	
Bolt Size	5/16-24	3/8-24	7/16-20	T	5/8-18	
Installation Torque (ftlbs.)	25	55	100	T	300	

The load cell mating thread should be class 3.

Customer <u>Gyre</u> LASONATCATES Sales Order <u>G2773</u> Model 1227-32

Purchase Order _____

CA	LIBHA	ATION		
Bridge*		Date	12.20	78
Range 50000	Ibs.	Serial	No. 122	23
Input Resistance			368.6	ohm
Output Resistance			350:5'	ohn
Recommended Excitation			10 VI	DC or VAC
Maximum Excitation			20 VI	DC or VAC
Non-Linearity (terminal)			REFER TO) % FS
Hysteresis			"NOTES"	% FS
Compensated Temp. Range			*15 °F 10	10 °F
Thermal Zero Shift			. mor	% FS/"F
Zero Balance			,05	% FS
Tension Output			-	MV/V
Compression Output			7.000	MV/V

WIRING

Function	Pin	Pigtail
+ Excitation		Kez - UNTIKED
+ Output		WAY WHELYNZ
- Output		GRU
- Excitation		itt - UNITIELE
Shield		

Polarity shown results in positive output for:

(compression)

(tension)

L0-87-8()-

w

SHUNT CA. IBRATION

	ohms - Exc. to - Out	lbs
201:0012	ohms - cxu. 10 - 6ct. 34528 5	:bs
Calibrated by	Therein of Marie	
*For multiple bridge	load cells	

APPENDIX B

. . . .

AIR BAG SPECIFICATIONS

LIK-8/-80-132 Industrial Product Sales

Lord Kinematics Lord Corporation 2730 West 12th Street Erie, Pa 16505 Telephone 800 458-0456 814 456-9511 Telex 914-478

Air Springs Actuators

ration, Shock, Noise Control Pro



REACTION MASS SUPPORT

Pneuride Air-Bellows are effective air springs and air actuators which have numerous industrial applications. Their rugged construction of reinforced neoprene flexing element, sealed with metal end plates, assures reliable long service life even under the most severe conditions. Available in six diameters and one, two, or three convolutions, they meet a wide range of operating conditions. Each size can be used for a variety of loads and disturbing frequencies by varying the air pressure.

Ideal Vibration Isolators

LORD

Vibration isolation efficiency ranging to above 99 percent is attainable depending upon the disturbing frequency. They provide protection for adjacent surroundings from machinery shock and vibration, and they protect sensitive machinery from external disturbances. Typical applications for Air Bellows as vibration isolators include machinery mounts, platform vibration isolation systems, and especially systems requiring suspension system with variable frequency. The low natural frequency (95 to 200 cycles per minute) of Air Bellows systems makes thern an exceptionally versatile isolator. Special systems can be designed with lower natural frequencies if required.

Effective Actuators

There is no smoother actuator than an Air Bellow. Easily installed and no wearing parts to lubricate or require maintenance. Air Bellows will withstand cocking when inherent in the application thereby eliminating the need for cleves or other misalignment accommodation. The same parts are used for isolators are recommended for actuators. This wide variety make Air Bellows suitable for many industrial applications such as: automatic lift/lower rams, constant load cells, stitching machines and many others.



*

TABLE 1

CHARACTERISTICS

ISOLATOR DATA				AC	TUATOR D	ATA (3)	
Lord Kinematics P/N	Size Dia. (in.) x No. Conv.	Rated Static Load Cap. (lbs.)	(1) Effoct. Area (in. ²)	(2) Nat. Freq. (cpm)	Max. Recom. Stroke (in.)	Force at Max. Stroke (Ibs.)	Force at 1" Stroke (Ibs.)
ASA-0002-1-1	6 × 2	1500	18.81	151	35	1200	2230
ASA-0BC1-1-1	8 x 1	24.85	26.6	178	3.5	1000	3300
ASA 0802-1-1	8 x 2	$2M/\pi$	29.7	134	60	1750	4210
1.1.1.5200.623	8 + 3	0.4°,	29.4	105	9.5	1300	4350
Á5A 10C2 T 1	10 x 2	4,200	52.5	117	60	3250	6400
A\$4-10C3-2-1	10 × 3	3740	46.8	96	10.0	3000	6400
ASA-1201-1-1	12 x 1	6500	81.3	148	2.75	5500	9300
ASA 12/02-1-1	f2 x 2	6190	79.9	116	6.5	5550	10000
ASA-12C3-1-1	12 × 3	6200	77.5	95	10.0	5500	10000
ASA 14C1-1-1	14-172 8-1	91:60	114-1	153	40	8200	14000
ASA-14C2-1-1	14-1.2 × 2	9540	1192	110	75	8100	14000
AGA LIGER F.	16 + 2	11500	143.8	105	75	10800	14800

At static besight and 80 per air pressure.
 At static besight and static load.

(a) Breaction 100 projan pressure-

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LTR-L0-87-80-132

Specification and Instaliation

Air Bellows are available in six diameters and one, two and three convolution designs. Air supply up to 120 psr is acceptable. Design data is based on 80 psr to the Air Spring or Actuator. Clearance must be allowed for maximum diameter of loaded or retracted Air Bellows. Attachment studs are 3/8-24 UNF by 1 inch long. The air inlet is 1/4 N.P. Air Bellows can be operated with water based fluid (with antifreeze or rust inhibitor additive) or a brake fluid. Petroleum-based fluids should not be employed.

STABILITY CONSIDERATIONS

The inherent softness of the Air Bellow isolator makes it necessary to consider the lateral stability of the system. When the center of gravity is very high above the mounting plane, instability might be a problem. For best results, the C.G. should be no higher above the mounting plane than the narrowest mount spacing. It is also important to consider lateral forces present. Air Bellows exhibit a charactenstic change in effective area with stroke, decreasing as the static height increases. This effect can be determined from the static load-pressure curves.

TABLE 2

$\cap 1$	AA:	E I	UE:	Q1	\cap	84	C
21	1.41	C 1	۰	31	1.8	1.4	3

Lord Kinematics P/N	A (1) Static Height (S.H.) (in.)	Max. Height (in.)	Min. Height (in.)	B Max. Dia. Dia. (in.)	C End Plate Dia. (in.)	D Stud Spacing B.C. Dia. (in.)
AGA-06C2-1-1	4 75	6 75	2 75	7	6 00	5.000
ASA-08C1-1-1	3 75	5 75	1 75	9	7 25	6 125
ASA-08C2-1-1	5.75	8 75	2 75	9	7 25	6 125
ASA-08C3-1-1	02: 8	13.50	3 50	9	7 25	6 125
ASA-10C2-1-1	6.25	9.50	3.00	11	8 25	7.125
ASA-10C3-2-1	9 25	14 25	3.50	11	8.25	7 125
ASA 1201-1-16	5 00	6.75	4 00	13	10.25	9.125
ASA-12C2-1-1	6 25	9.25	2 75	13	10.25	9 125
ASA 12C3-1-1	8 75	13.75	3 50	13	10 25	9 125
ASA 14C1-1-1	4 25	6 50	2 50	15	12.25	11 125
ASA-14C2-1-1	7.00	11 00	2 75	15	12 25	11 125
ASA 16C2-2-1	7.00	11()()	3 00	17	12.25	11 125

(1) At rated static load



-84-

34-



-85-

APPENDIX C

WYLE MASS PROGRAM OUTLINE

. . .

PRØGRAM ØUTLINE

- I. Start
- II. Read in Constants
 - A. Slope for load cell calibration equation
 - B. Density (KG/m^3) from reference leg of differential pressure (DP)
- III. Read in variables
 - A. Time
 - B. Load cell #1 (volts)
 - C. Load cell #2 (volts)
 - D. Load cell #3 (volts)
 - E. Differential pressure (DP) cell #1 (in / $H_0 \emptyset$)
 - F. Temperature from vessel (K)
 - i. DP cell #2 (in / H_0)
 - H. Average density
 - I. Load cell #4 (volts) if available -
- IV. For first one hundred (100) samples
 - A. Initialize variables to zero
 - B. Sum values for load cell
 - C. Sum values for DP cell #1
 - D. Sum values for DP cell #2
- V. Calculate density from temperature in vessel (IIIF) assuming saturated temperature.
- VI. Calculate offsets using density from vessel temperature (V), density from reference leg of DP (IIB), and sum of the first 100 samples of either load cells (IVB) or DP cells (IVC).

LØAD ØFFSET = 4133.55 - Average load cell for first 100 samples

DP1 ØFFSET = 7.72668 - (density from reference leg / density from vessel temperature * 7.72668) - (Average of DP cell #1 for first 100 samples * 102 / density from vessel temperature).

- DP2 ØFFSET = 4.7244 (density from reference leg / density from vessel temperature * 4.7244) - (Average of DP cell #2 for first 100 samples * 102. / density from vessel temperature).
- VII. Convert both DP cells from KPa to meters / H_2 Ø for each sample.
 - DP1 = density from reference leg / density from vessel temperature * 7.72668) - (original DP reading * 102. / density from vessel temperature) + DP1 ØFFSET
 - DP2 = density from reference leg / density from vessel temperature * 4.7244) - (original DP2 reading * 102. / density from vessel temperature) + DP2 ØFFSET
- VIII. Calculate system weight from load cells
 - A. Sum all load cell readings for each sample.
 - B. Multiply the above sum by the slope for the load cell calibration equation (IIA).
 - C. Add above value to load offset.
- IX. Initialize variables for vessel volumes and vessel heigths. (This is necessary because the internal shape of the vessel changes. See Figure 19 for drawing of vessel).
- X. Initialize variables
 - A. For radius of vessel
 - B. For radius of hemisphere
- XI. Convert DP cells from meters to centimeters
- XII. Calculate volumes for each distinct shape of vessel (Figure 19).
 - A. If the reading for DP cell #1 is less than zero, the volume is set to zero.
 - B. If the reading for DP cell #1 is greater than zero, but less than 91.52, then the volume equals:

Pi * $(reading - 51.83)^2$ * [hemisphere radius - ((reading - 51.83)/3)]

C. If the reading for DP cell #1 is between 91.52 and 128.33, then the volume equals:

Pi * vessel radius² * (reading - 91.52) + 204865.1125

where 204865.1125 is the vessel volume constant

D. If the reading for DP cell #1 is between 128.33 and 637.61, then the volume equals:

(reading - 128.33) * 5476.3 + 204865.1125 + 319208.22

where 204865.1125 and 319208.22 are the vessel volume constants

E. If the reading for DP cell #1 is between 637.61 and 693.49, then the volume equals:

Pi * (reading - 637.61) * radius of vessel² + 204865.1125 + 319208.22 + 2815007.0

where 204865.1125, 319208.22, and 2815007.0 are the vessel volume constants

- F. If the reading for DP cell #1 is between 693.49 and 733.1, then the volume equals:
 - $(Pi * (693.49 reading)^2 * [hemisphere radius (693.49 reading/3)] + (2 * 204865.1125) + 319208.22 + 2815007.0 + 483755.215.$

where 204865.1125, 319208.22, 2815007.0, and 483755.215 are the vessel volume constants

G. If the reading for DP cell #1 is between 733.1 and the top of the vessel, then the volume equals the sum total of the volume constants.

(2 * 204865.1125) + 319208.22 + 2815007.0 + 483755.215

XIII. Compute system weight using volume obtained from DP cells (cubic centimeters), average density (Kg) and density from vessel temperature (Kg).

* if DP cell reading (cm) > 750, then Sysmass = Sysmass + 73.21

- XIV. Compute mass flow from load cells and from DP cells
 - A. Read in number of terms (NTERMS) and values of coefficients for positive direction to be used in the digital filter.
 - B. Set the middle coefficient equal to zero and the negative coefficients equal to the negative of the corresponding coefficient in the positive direction.
 - example: for 3 terms with values of .1, .2, and .3, the coefficients would be -.3, -.2, -.1, 0.0, .1, .2, .3

- C. For the first 100 samples, fill the mass flow array with the mass of those samples. (This is done because the software used cannot go backward in time and the filter used needs both past and future times.)
- D. Calculate the mass flow of the system, using either the load cells or DP cells, by summing, from 1 to (NTERMS + 1), the mass times the corresponding coefficient.
 - 1) Present time sample corresponds to the zero coefficient.
 - Past (NTERMS) time samples correspond to the coefficients of negative direction and future (NTERMS) samples to coefficients of the positive direction.
 - (NOTE: The oldest time sample must correspond to the coefficient of the most negative direction).
- E. Multiply the value obtained in the previous summation by the number of samples per second to get the mass flow from the load cells when using the load cell mass and the mass flow from the DP cells when using DP cell mass. **

XV. Compute the root mean square (RMS) difference

A. Øf load cell mass and DP cell mass for all samples

B. Øf mass flow from the load cells and the mass flow from the DP cells for all samples.

XVI. Øutput values

- A. Time
- B. System weight from load cells in kilograms
- C. Mass flow from load cells in kilograms / second
- D. System weight from DP cells in kilograms
- E. Mass flow from DP cells in kilograms / second
- F. RMS difference of load cell weight versus DP cell weight
- G. RMS difference of mass flow from load cells versus mass flow from DP cells.

XVII. Stop

** The value for the mass flows at this point have been shifted forward in time, due to the software used. Upon completion, the mass flows need to be shifted back in time by NTERMS/samp:es per seconds.

-C4-

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TEMLC, P3, TAGC, STMEB,

ACCCUCKT, 60, 10, 542151C02, TAU.

ATTACF, LLCFLLOPTPL, 10-LF1, ST-MFA.

FILE, OLCPFL, RT-S.

LFDATE, O, M, K.

REWINL, CUPFILE.

FIN, 1, R-3, S-SYSTEXT, S-PFMTEXT, PL-250000.

FIN, K-3.

ATTACF, LAB1, CCPLIP, 10-LF1, ST-MFA.

KLOUE, T, ABS, *PF.

SEGLCAC, 1-CCMPILE.

LCSET, LAB-LIB1.

LCSET, LIB-LIB1.

LCSET, LIB-LIB1.

LCSET, LIB-LIB1.

LCSET, LIB-LIB1.

LCSET, LAB., WCOPERA, ID-GRR, RP-999, MR-1.

*ID CUFL

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          CATA CPTIONS
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                                                                                                                             THIS FUNCTION COMPUTES THE WYLE TRANSIENT SYSTEM NEIGHT AND MASS FLOW FROM THE LOAD CELL VOLTAGE CUTPLT AND THE 3CC INCH DELTA P.
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           5
           57
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             NCHET=7
NCONST=4 $ NXNAME=9
IF(FFMKNT.EG.1) CALL INFOUT(C,NCONST,XNAME,NXNAME,SUBNAME,OPTIJNS)
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SLCPE FOR LOAG CELL CAL EQUATION

DENSITY (KG/M 3) REFERENCE LEG OF OP

FLAG FOR LOAD CELL COMPUTATION 1- DC

FLAG FOR CP CELL COMPUTATION 1- DC

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·----8 UNITS VARIABLES TIME SECONDS LOAL CELL 2 VCLIS OUTPUT LOAD CELL 2 VCLIS OUTPUT SCC INCH OP CELL INCHES WATER OUTPUT TEMPERATURE TF-V-1 CNUSED CP-V-1 AVERAGE DENSITY OR DE-1-8 OR DE-2-8 OUTPUT XL 1 12 ----.... 3 4 č----5 E7 C---6 č----5 UNITS TIME SECONDS SYSTEM WEIGHT KILOGRAMS FROM LOAD CELLS SYSTEM WEIGHT DIFFERENTIAL FROM LOAD CELLS SYSTEM WEIGHT KILOGRAMS FROM DP CELL SYSTEM WEIGHT KILOGRAMS DIFFERENTIAL FROM DP SYSTEM WEIGHT KILOGRAMS FROM DP CELL BIFFERENTIAL FROM DP SYSTEM WEIGHT KILOGRAMS DIFFERENTIAL FROM DP SYSTEM WEIGHT KILOGRAMS FROM DP CELL BIFFERENTIAL FROM DP SYSTEM WEIGHT KILOGRAMS DIFFERENTIAL FROM DP SAMPLE() C---C --č----8=== C ---Ç ----THIS PRUGRAM CALCULATES THE MASS AND TIME DERIVATIVE OF THE BYLE SYSTEM GIVEN THE OUTPUT OF THE INCIVICUAL LOAD CELLS AND THE OUTPUT FROM THE DIFFERENTIAL PRESSURE CELL DP-V-2 (300 INCH). THE KMS DIFFERENCE BETWEEM THE LCAD CELL COMPUTATION AND DP CELL COMPUTATION IS ALST COMPUTED AND OUTPUT. C--- REMARKS: C----LS ALSE COMPUTED AND DUTPUT. (---INITALIZE VARIABLES FOR SUMMATION £=== 1) SUH3 = 0.0 1) SUH4 = 0.0 1) SUH5 = 0.0 IF (FRMKNT .EQ. IF (FRMKNT .EC. (----FOR FIRST 100 SAMPLES OF DATA, INITALIZE VARIABLES TO 0.0 č---IF (FRMKNT-1CC) 20,30,30 CONTINUE LLEMASS - C. SAMPLE(1) - C. SAMPLE(2) - C. SAMPLE(3) - C. SAMPLE(3) - C. 20 SAMPLE(6) = C. Ç---SLP VALUES FOR DP CELL #2 (---C ----SLP3 = SLP3 + X(5) (---SUP VALUES FER OP CELL #1 č----SUMS . SUMS + X(8) (----SUP VALUES FOR LOAD CELL ž=== SLM4 = SUM4 + (C(2) + (X(2) + X(3) + X(4))){----CALCULATE DENSITY FROM TEMPERATURE IN VESSEL x(6) = (x(6) + (9./5.)) -459.67 LEN - - COO56004 + (X(6) * 1,15893E-4) + X(6) * X(6) * (-2.572C9E-7)) + (X(6) * X(6) * X(6) * 2.18697E-10) + CEN . (1./CEN) + 16.018 C ----GE 16 400 C ---

3

```
CONTINUE

x(E) * (x(E) * (9./5.)) -::9.67

CEN = -.COC56004 + (x(E) * 1.15893E-4) +

(x(E) * x(E) * (-2.57209E-7)) +

(x(E) * x(E) * x(E) * 2.18697E-10)

DEN = (1./CEN) * 16.018
                                                                                   LTR-L0-87-80-132
    30
         +
         4
C ----
             CALCULATE OFFSETS USING DENSITY FROM VESSEL TEMP.
CENSITY FROM REFERENCE LEG OF DP, AND FROM THE SUM
OF THE FIRST 100 SAMPLES OF EITHER LOAD OR DP CELLS.
8----
(---
(---
          IF (FRMKNT .NE 100) GCTO 35
C ----
2----
             UFFSET FCR : #2
          CFFSET . 7.72668-((C(3)/DEN#7.72668) - (SUM3/99.4102./DEN))
( ----
8===
  ---
             OFFSET FOR CP #1
          CFFV1 = 4.7244 -((C(3)/DEN*4.7244) - (SUM5/99.*102./DEN))
C ----
8===
             OFFSET FOR LOAD CELL
          MCFF = -(SUM4/99.) + 4133.55
     35 CLNTINUE
£----
           ACJUST OF INPUT FROM KPA 10 M/H20 FOR EACH SAMPLE
č ----
          x(5) = (C(3)/CEN+7.72668) - (X(5) + 1C2./DEN) + OFFSET
C ----
C ----
                6+
          X(8) - (C(3)/DEN+4.7244) - (X(8) +102./DEN) + CFFV1
£----
             CHECK FOR FLAG TO COMPUTE LOAD CELL WEIGHT
           IF (C(4)) 50,56,40
2===
             CLAPUTE SYSTEP WEIGHT FRUM LUAD CELLS
C ---
    40 CONTINUE
SUM = X(2) + X(3) + X(4)
WELCHI = (C(2)+SUM) + MOFF
ç----
ç----
             CHECK FCP CF CELL WEIGHT
    50 CENTINUE
17 (C(5)) 60,60,70
ç----
             CLAPUTE SYSTEP WEIGHT FORM OF CELLS
(----
(----
             WESSEL VOLUME CONSTANTS (IN CENTIMENTERS) AND
HEIGHT CONSTANTS (IN CUBIC CENTIMETERS)
C ----
2----
             INITALIZE VESSEL HEIGHT AT WHICH SYSTEM INTERNAL SPAPE
(---
    7C CCNTINUE

H1 = 91 -52

H2 = 128 - 33

H5 = 637 - 61

H6 = 693 - 49

H7 = 733 - 10
(---
          INITALIZE VESSEL VOLUME CONSTANTS FOR EACH DISTINCT SHAPE
V1 = 204665.1125
V2 = 319268.22
V3 = 2815007.0
V6 = 483755.215
INITALIZE CONSTANTS FOR VESSEL AND PIPE RADIUSES
RVES = 52.53162
RHEMI = 54.61
L ---
....
(---
2:::
          DEFINE PI
         PI = 3.14159
```

```
LTR-L0-87-80-132
```

```
C---
              ASSUME OF CELL IN METERS OF WATER AND CONVERT TO
č----
         FFLV1 = x(8) + 100.
Č ----
(---
         HFLLIC . X(5) . 100.
C ---
č----
              CALCULATE VELLE FER EACH FEIGHT, DEPENDING ON THE
DISTINCT SHAPE OF THE VESSEL AT THAT HEIGHT
         LF (FFLUID .GT. 0.) GO TO 90
SYSVLL .C.
GU 16 200
(---
    90 IF (HFLUID .GT. H1) GOID 100
SYSVEL - FI*(FFLUID-51.83)**2.*(RHEMI-(HFLUID-51.83)/3.)
GEIG 180
( ---
         SYSVEL = PI RVES+2. + (HFLUID - H1) + VI
  100
C ----
   110 IF (HELUID .( . H5) GCTO 140

SYSVCL = 5/76.3 • (HELUID- H2)

SYSVCL = SYSVCL + V1 + V2

GCTC 180
            (HELLID .GT. HE) GCTO 150
SYSVOL - (HELLID - H5) - PI + RVES+2 + VI + V2 + V3
GLTC 180
   140 IF
C ----
   150 IF (FFLUIC .GT. F7) GCI0 160

SYSVCL = -(FI + (H7-HFLUID)++2 + (RHEFI-(H7-HFLUIC)/3))

SISVCL = SYSVCL + 2.+V1 + V2 + V3 + V6

GLIC 180
C---
   16C CONTINUE

SYSUEL • V1 + V2 + V3 + V6 + V1

160 CONTINUE

16 (FFLV1 .LE. F2 ) GOID 200

IF (FFLV1 .GE. 472.44) GOID 181

YSUEL • SYSUE + (FFLV1 -H2)• 2470.2

UTC 200
(---
   181 SYSVEL - SYSVEL + 937662.7
(---
             CLAPUTE SYSTEP MASS GIVEN SYSTEM VOLUME IN CC AND
LENSITY IN KG/MS++2
(---
 ----
(---
   2CC SYSMASS - SYSVEL/1CCOCCO. + DEN + C.449028 + X(9)
IF (HELUID .GE. 750.) SYSMASS - SYSMASS + 73.21
ç----
                CHECK TO SEE IF BOTH OP AND LOAD CELL USEC,
( ---
    60 IF ( C(4)*C(5) .LE. 0.) GOTO 3CO
C ---
8:::
              LLPPUTE DIFFERENTIAL OF BOTH
         CALL DIFFE (WEIGHT, SYSMASS, D1, D2, FRMKNT)
(---
2===
               LLMPUTATION LF RMS DIFFERENCE LLAD CELL VS DP CELL MASS
          CMASS = (WEIGHT-SYSMASS)**2. + DDMASS
SAMPLE(5) = SCRT (DHASS/FLUAT(FRMKNT))
UDFASS = TMASS
L ---
                CCMPUTATION OF RMS DIFFERENCE OF DIFFERENCES
C ---
C---
         SAMPLE(6) - SCAT (DOMASS/FLUAT(FRMKAT))
```

CUTPLT OF COMPLTED PARAMETERS LOAD CELL AND CP CALCULATED (---8=== SAPPLE(1) - FEIGHT SAPPLE(2) - C1 SAPPLE(3) - SYSPASS SAPPLE(4) - D2 GCTC 400 300 IF (C(4) - EC. C.) GCTC 500 LUTPUT OF COMPUTED PARAMETERS LOAD CELL ONLY CALCULATED (---2----ZERL . C.C. (WEIGHT, ZEKE, D1, D2, FRMKNT) C---C. SAPFLE(1) SAPFLE(2) SAPFLE(3) SAPFLE(4) SAFFLE(5) SAFFLE(6) GOIL 40C £----CUTPUT OF COMPUTED PARAMETERS OF CELL ONLY CALCULATED C. C. C. C. SUD CALL DIFF2(ZERC, SYSMASS, D1, D2, FRMKNT) (.... SAPPLE (3) SAPPLE (3) SAPPLE (3) SAPPLE (5) SAPPLE (5) SAPPLE (5) CEED 400 £ CUTINE DIFF2 (V1,V2,D1,C2,NFRAME) SICH ALOAD (500), ADP (500), CDEFF1(250), CDEFF2(250) V1 - VARIABLE USED TO COMPUTE LOAD CELL CERIVATIVE V2 - VARIABLE USED TO COMPUTE DP DERIVATIVE L1 - LERIVATIVE CF DP L2 - DERIVATIVE CF DP NEE - PRESENT FRAME COUNT HE - NUMBER OF SETS OF TERMS IN FILTER (HEAC IN FROM CARDS) ASSUMES THAT FRAME COUNT IS EQUALS 100 FOR FIRST LERIVATIVE TO BE COMPUTED. SUBRELTINE LIMENSICH V2 LI (----(----(---2----NERANE C---- READ IN DATA INPUT AND INITALIZE VARIABLES. U.Fr2 CI CHERAPE LT. 1001 CHERAPE GI. 1001 HEAL (5,*) NTERPS KEAL (5,*) SAMPLES 11 RETURN 60 TO 15 C---- INITALIZE VARIABLES NUM - FOSITION OF FIRST COEFF. IN POSITIVE DIRECTION NIWC - FOSITION OF LAST COEFF. IN POSITIVE CIRECTION NIWC - FOSITION OF MICOLE COEFF. W VALUE - 0.0 2----NTHO . NTERMS . 2 + 1 NUM . NTERMS . \$ 2 1 + C----(COEFF2(I);I = NUM;NIWO) REAL (5,*) C---- SET PLODLE COEFFICIENT VALUE (----CLEFFI (NVAL) : 0.0 C----

```
LTR-10-87-80-132
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```
SET NEGATIVE DIRECTION CDEFFICIENTS

UC 5 I = 1.NTERMS

IF (1 .EQ.1) J = JT[]

CUEFFICI) = CCEFFICJ)

CCEFFICI) = CCEFFICJ)

CCEFFICI) = CCEFFICJ)

CCEFFICI) = CCEFFICJ)

CUEFFICI) = CCEFFICJ)

CUEFFICI) = V1

ALDACLAND ACP W/ 100 FRAME VALUE FOR INITALIZATION

DU 1C I = 1.NTWC

ALDACLI = V1

ALDACLI = V1

ALDACLI = V1

ALDACLI = V1

IC CONTINUE

UI = CI = IANTWC

UI = CI = SAMPLES

ALCAC(IB) = V2

IE = IB + 1

ACP (AB) = V2

IE = IB + 1

ACP (AB) = V2

IE = IB + 1

ACP (AB) = V2

IE = IB + 1

ACP (AB) = V2

IE = IB + 1

ACP (AB) = V2

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ACP (AB) = V2

IE = IB + 1

ACP (AB) = V2

IE = IB + 1

ACP (AB) = V2

ACP
```

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APPENDIX D

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LOAD CELL FILL CALIBRATION PROCEDURE

LTR-LO-87-80-132

TEST PROCEDURE NO. 3958

WALE LABORATORIES SCIENTIFIC SERVICES & SYSTEMS GROUP WESTERN OPERATIONS, EL SEGUNDO FACILITY

DATE: 30 May 1979

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TRANSIENT FLOW CALIBRATION SYSTEM

WEIGHING ACCURACY TEST

PROVE	D 8Y:		AP	PROVED BY	Houselaw WYLE LABORATORIES
PROVE	D BY: FOR:		AP	PROVED BY	A Wheeloch
PROVE	D BY:		PI	REPARED BT	WYLE LABORATORIES
V. NO.		PAGES AFFECTED	REVISION	S APP'L.	DESCRIPTION OF CHANGES
	6/20/79	4, 5, 6	Mas	FH	Additional information
3	7/2/79	8	1812	7A	Error reference 9000 lbs

COPYEIGHT BY WYLE LABORATORIES. THE RIGHT TO REPRODUCE, COPY, EXHIBIT, OR OTHERWISE UTILIZE ANY OF THE MATERIAL CONTAINED HEREIN WITHOUT THE EXPRESS PRIOR PERMISSION OF WYLE LABORATORIES IS PROHIBITED. THE ACCEPTANCE OF A PURCHASE ORDER IN CONNECTION WITH THE MATERIAL CONTAINED HEREIN SHALL BE EQUIVALENT TO EXPRESS PRIOR PERMISSION.

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	LTR-L0-87	-80-	132
EST	PROCEDURE	NO	3958

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SCIENTIFIC SERVICES & SYSTEMS GROUP WESTERN OPERATIONS, NORCO FACILITY

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1.0 PURPOSE

The purpose of this document is to present the procedures to be followed in performing the Weighing Accuracy Test.

2.0 IEFERENCES

- 2.1 Wyle taboratories Test Procedure No. 3936, dated 24 January 1979.
- 2.2 ASME Research Committee on Fluid Meters, Sixth Edition, dated 1971.
- 2.3 Dick Munns Company Flowmeter Calibration Certificate, Wyle Laboratories Turbine Meter #31064, dated 24 April 1979.

3.0 REQUIREMENTS

- 3.1 Perform the Weighing Accuracy Test required by Reference 2.1.
- 3.2 To demonstrate the calibration accuracy of the weighing system, ambient water will be metered into the test vessel. The total weight of the water metered into the test vessel will be compared with the differential weight indicated by the load cell system.

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4.0 TEST CONDITIONS AND TEST EQUIPMENT

4.1 Ambient Conditions

Unless otherwise specified herein, all tests required by the specification shall be performed at an atmospheric pressure of 28.5 \pm 2/-4.5 inches of mercury absolute, a temperature of 73 \pm 18 F, and a relative humidity of 50 \pm 30 per cent.

4.2 Instrumentation and Equipment

- 4.2.1 Measuring and test equipment utilized in the performance of this contract have been calibrated by the Wyle Laboratories Standards Laboratory, or a commercial facility utilizing reference standards (or interim standards) whose calibration has been certified as being traceable to the National Bureau of Standards. All reference standards utilized in the above calibration system are supported by certificates, reports or data sheets attesting to the date, accuracy and conditions under which the results furnished were obtained. All subordinate standards and measuring and test equipment are supported by like data when such information is essential to achieve the accuracy control required by the subject contract.
- 4.2.2 Wyle Laboratories attests that the commercial sources providing calibration services on the above referenced equipment, other than the National Bureau of Standards, are in fact capable of performing the required services to the satisfaction of the Wyle Laboratories Quality Control Department. Certificates and reports of all calibrations performed are retained in the Wyle Laboratories Quality Control files and are available for inspection upon request by authorized customer representatives.
- 4.2.3 Actual test equipment used in the performance of this test program will be listed on the appropriate test data sheets. (See sample, page 12).

4.3 Test Equipment

Item	Manufacturer	Model	Description
Flowmeter	Foxboro	FL-16-SB	10-40 GPM
Frequency Meter	Fluke	1941A	1-100K Hz
Digital Totalizer	Fluke	1941A	1-100K Hz
Load Cell Indicator	Interface	7500	6-150K Lbs.
Digital Thermometer	Fluke	2100A	-320 to 750°F
Load Cell	Interface	1221-J2	S/N 12291 12292 12293

IEST PROCEDURE NO. 3000

SCIENTIFIC SERVICES & SYSTEMS GROUP WESTERN OPERATIONS, NORCO FACILITY

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5.0 PROCEDURE

5.1 The test system will be plumbed and instrumented as shown in Figure 1. The installation of the reference flowmeter will duplicate the system plumbing used during the calibration, Reference 2.3, as shown in Figure 2.

5.2 Initial System Preparation

- a) Activate the water supply transfer pumps and flood the system.
- b) Continue to flood and drain the system until the water and air temperatures (T_w and T_A) have stabilized and the general performance of the frequency meter and totalizer has been verified.

5.3 Data Point Acquisition

- Record the load cell indicator initial weight reading on the data sheet, Figure 3.
- b) Zero the digital totalizer.
- c) Open the solenoid valve to begin the filling process.
- d) During the filling process, maintain a constant filling rate and enter the flowmeter frequency, water temperature, air temperature and barometric pressure on the data sheet.
- e) Continue to fill the test tank until at least 3000 pounds of water has been added to the system.
- f) Terminate the filling process by closing the solenoid valve.
- g) Record the load cell indicator final weight and the totalized flowmeter count on the data sheet.
- h) Using the equation from Figure 4, c mpute $\Delta W_{\rm F}$, then * ΔW .
- Repeat steps (a) through (h) three times. The measured water into the system during the last increment must be sufficient to fill the horizontal test spool.
- j) Drain the test tank and repeat steps (a) through (i) two more times, generating a total of 9 data points.

6.0 SUPPLEMENTAL INFORMATION

A plot of the Foxboro flowmeter calibration is shown in Figure 5 and the reference water density in Figure 6.

		LTR-L0-87-80-132
[and]		PAGE NO6
	FIGURE 1	
WYLE LABORATORIES Norto,	California	



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FIGURE 2



LTR-L0-87-80-132

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and is being their		
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DATA SHEET

CUSTOMER Test Titles

Part No.

Specimen

lob No.	
S/N	
Date	

LOAD	CELL REP	DING				7 2 2 2 2 2 2 2 2	1	CONTRACTOR OF A DESCRIPTION OF A DESCRIP	
INIT. FINAL AWL WT. WT.	FREQ. (f)	TOTAL COUNT (Ef)	TEMP. (T _W)	AIR TEMP. (T_{Λ})	BAR. PRESS. (P _B)	ΔW_F	80W		
			1						
		1							
						· · · · ·			+
									+
	1			120					
					+				
					+			+	-
								1	-
					-		-	1	
		-							-
									-
				1,			-		
	-				1				
			-						
+		-		-					
+									
	-								
								_	
1									
		Aw - A	W_						
	∆w = 100	.9000	E						
	Q. C.	ΑW = 100 Q. C. Form A	ΔW = 100 ΔW _L - Δ 9000 Q. C. Form Approva	$\Delta W = 100 \frac{\Delta W_{L} - \Delta W_{F}}{9000}$	$AW = 100 \frac{\Delta W_{L} - \Delta W_{F}}{900}$	$\Delta M = 100 \frac{\Delta M_{L} - \Delta M_{F}}{9000}$	 ΔW = 100 ΔW_L - ΔW_E 9000 Q. C. Form Approval Δατ. 		

(B)

LTR-L0-87-80-122 TEST PROCEDURE NO. ______

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FIGURE 4

$\Delta W_{\rm F}$ =	(Σf) (Y _W - 7.481 (K)	(γ_A)	
K = A	+ B (f) + C	(f) ²	CYCLE/GAL
Υ _W = [) + E (T _W) +	$F(T_W)^2$	LB/FT ³
Y _A =	144 P _B 53.35 (T _A +	460)	LB/FT ³
f	CYCLE/SEC		
τ _w	°F		
TA	°F		
PB	PSIA		
А	5.40069	E 2	
в	-4.03109	E-2	
С	6.00409	E-5	
D	6.23205	E 1	
Ε	6.76993	E-3	
F	-9.98624	E-5	

WALE LADD BAILINGS

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LTR-L0-87-80-132 TEST PROCEDURE NC. 3958

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FIGURE 5



WALE LACORATORIES

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LTR-L0-87-80-132 TEST PROCEDURE NO. 3950

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PAGE NO

FIGURE 6

SPECIFIC WEIGHT OF WATER

REF: Fluid Meters, ASME, Sixth Edition, 1971



SPEC. WT. (LB/FT³

-011-

8 NO	LIBRATION ACCY.							/-80	-132		SHEET OF
97 0 H M	CA										
	WYLE NO.			· . •							
	RANGE										
0. EER	MODEL NO.										
SPECIMI CUT ON PART NI S/N S/N	MANUFACTURER										
WYLE LABORATORIES	EQUIPMENT										W614C OC. Approval Purt

-D12-