THE MATMOD APPROACH TO MODELLING OF ZIRCALOY NON-ELASTIC DEFORMATION*

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SUMMARY OF PRESENTATION

The MATMOD constitutive equations represent a <u>unified</u> model for the non-elastic deformation behavior of metals and alloys. The equations are, to some extent, a bridge between materials science and structural analysis: The overall <u>form</u> of the equations follows from the dislocation-controlled physical nature of most non-elastic deformation, but the actual expressions and materials constants are determined by fitting the mechanical test data. The equations are probably most useful in treating various <u>mixed</u> situations, such as creep-fatigue interaction, mixtures of thermal and irradiation creep, or interactions of strain hardening and recovery. They have been applied in detail to Zircaloy, to type 316 austenitic stainless steel, and to 2 1/4Cr-1Mo ferritic alloy steel.

As seen in Figure 1, the central MATMOD equation is one which expresses the non-elastic strain rate ε_{th} as a function of the current stress σ and temperature T and also as a function of four structure variables. The first two of these (F_{def} and R) are <u>history-dependent</u> state variables which represent, respectively, the current states of <u>isotropic</u> and <u>directional</u> hardening. The second two structure variables ($F_{sol,1}$ and $F_{sol,2}$) are temperature and strain-rate dependent solute strength variables which represent, respectively, the effects of alloying elements which either do not or <u>do</u> interact synergistically with strain hardening. Each of the

* Research on Zircaloy sponsored by EPRI (RP-456, RP-700); research on austenitic stainless steels and 2 1/4Cr-1Mo steel sponsored by U.S. Department of Energy (EY-76-S-03-0326PA57).

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four structure variables corresponds to a specific strengthening mechanism (Figure 1).

The fact that there is only <u>one</u> non-elastic strain variable for outuf-reactor situations (instead of the traditional separation into "creep" and "plastic" strains) leads to straightforward predictions of interactions between "creep" and "plasticity" (Figure 2) and between monotonic and cyclic deformation (Figure 3). <u>Recovery</u> effects are also predicted in a straightforward manner because both R and F_{def} are governed by work hardening-recovery type equations (Figure 4).

Dynamic strain aging effects such as (1) plateaus in the yield strength versus temperature curve (Figure 5), (2) a local minimum in the strain-rate sensitivity versus temperature curve (Figure 6), and variations with temperature in the slope of the creep rate versus stress curve (Figure 7) are simulated in a natural way through the solute strengthening variables

F_{sol,1} and F_{sol,2}.

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Irradiation effects have been added (to the above descriptions of out-of-reactor deformation) by (1) adding a neutron <u>flux</u> hardening term to the <u>strain</u> hardening term in the equation controlling F_{def} , and (2) by adding a steady-state irradiation creep rate to ε_{th} . With these additions, the equations make reasonable predictions of (1) the fluence dependence of the yield strength for both cold-worked and annealed Zircaloy (Figure 8) and (2) the creep-rate versus stress behavior obtained in-reactor, out-of-reactor, and post-irradiation (Figure 9).

Figures 10 and 11 compare the model's predictions against independent data for strain-rate change tests. For annealed and for CWSR materials the average errors in predicted stress are 8% and 17%, respectively. Figure 12 shows the stress relaxation behavior of the model; it compares

favorably against independent data over a 25°C to 500°C temperature range.

A major deficiency of the model, as applied to Zircaloy, has been the fact that the yield strength plateau, "simulated in annealed material, is erased by cold work, leading to the inaccuracy shown in Figure 13. This deficiency has been rectified in recent modelling work on 316 stainless steel in which $F_{sol,2}$ was introduced; Figure 14 shows how the latest equations can actually simulate an <u>increase</u> in dynamic strain aging effects with increasing cold work.

In summary, the MATMOD approach has the advantages of: (1) physical basis (useful for extrapolations) and (2) great breadth; Figure 15 lists the large number of phenomena covered by the model. The approach has the disadvantages of (1) less accuracy than special-purpose equations fitted to specific regimes of behavior and (2) a relatively difficult procedure for calculating the materials constants for other alloys.

A list of references on the MATMOD constitutive equations'is attached.

REFERENCES ON THE MATMOD CONSTITUTIVE EQUATIONS

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MATMOD CONSTITUTIVE EQUATIONS

I. General Form:

A. Thermal strain rate:

 $\varepsilon_{th} = f(T) f[\sigma/E - R, F_{def}, F_{sol,1}, F_{sol,2}]$

- B. History-dependent state variables:
 - 1. R ("Rest stress" or back stress): Directional (kinematic) hardening associated with pileups or dislocation bowing
 - 2. F def ("Friction stress due to deformation"):

Isotropic hardening associated with subgrains, forest dislocations, irradiation

$$\dot{R} = \frac{dR}{dt} = \frac{\text{work-hardening}}{\text{term}} - \frac{\text{thermal recovery}}{\text{term}}$$

 $\dot{F}_{def} = \frac{dF_{def}}{dt} = \frac{\text{work-hardening}}{\text{term}} + \frac{\text{flux-hardening}}{\text{term}} - \frac{\text{thermal recovery}}{\text{term}}$

C. Temperature and strain-rate dependent solute strengthening variables:

F sol ("Friction stress due to solutes"):

Isotropic strengthening associated with solute atmospheres, dynamic strain aging, etc.

 $F_{sol} = f(T, \varepsilon)$

 $\varepsilon_{\rm irr} = B_2 \exp(-$

- 1. F sol,1 : independent of strain hardening (substitutional solutes?)
- 2. F_{sol,2} : <u>synergistic</u> with strain hardening (interstitial solutes?)
- II. Specific Equations (1-dimensional form):

$$\dot{\epsilon}_{th} = B\theta' \left\{ sinh \left[\left(\frac{|\sigma/E - R|}{\sqrt{F_{sol,1} + F_{def}(1+F_{sol,2})}} \right)^{1.5} \right] \right\}^n sgn(\sigma/E - R)$$
(1)

$$h = H_1 \hat{\epsilon}_{th} - H_1 B \theta^{\dagger} [\sinh(A_1|R|)]^n \operatorname{sgn}(R)$$
(2)

$$\dot{F}_{def} = H_2[C_2 + |R| - (A_2/A_1)F_{def}^{1.5}]\dot{\epsilon}_{th} + H_3\phi - H_2C_2B\theta'[\sinh(A_2F_{def}^{1.5})]^n \quad (3)$$

$$\frac{|\varepsilon_{th}|/\exp(-\frac{q_{sol}}{kT}) = \frac{|\varepsilon_{th}|/\exp(-\frac{q_{sol}}{kT})}{(6)}$$

$$\dot{\epsilon} = \dot{\epsilon}_{th} + \dot{\epsilon}_{irr}$$

 θ' is similar to $\exp(-\frac{Q}{kT})$

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Figure 2. Experimental data and independent simulations of the effect of prior room-temperature straining on the subsequent creep response. Prestraining reduces the amount of primary creep; the work hardening is not removed by static annealing at 200°C, but dynamic recovery occurs upon sub quent creep testing at 200°C.



Figure 3. Simulations of the effect of prior cyclic straining on the subsequent creep response. Prior cycling reduces the amount of primary creep.



Figure 4.



Figure 5. 1605 302



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Figure 6. Strain-rate sensitivity as a function of temperature at various strain levels. The simulations utilize the final material constants and are independent of the data









Figure 7.



Figure 8. Elevated-temperature yield strength annealed and coldworked material as a function of fast fluence. The simulations used the final material constants and (for fluences unequal to zero) are independent of the data [86,93].

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Figure 9a. Simulation of in-reactor, out-of-reactor, and postirradiation strain rate vs. stress, for comparison with data in Figure 9b.



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Figure 9b. Zircaloy data on in-reactor, out-of-reactor, and post-irradiation strain vs. stress, for comparison with simulation in Figure 9a.



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Figure 12. Stress relaxation behavior of annealed Zircaloy. The simulations (final material constants) are totally independent of the data

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Figure 13. Yield strength as a function of temperature, for annealed material and cold-worked material. The simulations use the final material constants. Data from this research program (Appendix A).



Figure 14. Yield strength (data and independent MATMOD predictions) for type 316 stainless steel cold-worked by various amounts.

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Phenomena Simulated by the MATMOD Constitutive Equations

- 1. "Plasticity", including:
 - (a) essentially elastic behavior followed by gradual yielding
 - (b) strain-rate sensitivity
 - (c) temperature sensitivity
- 2. "Creep", including:
 - (a) primary creep
 - (b) steady-state creep
 - (c) sinh variation of steady-state creep rate with stress
- 3. Cyclic stress-strain behavior, including:
 - (a) Bauschinger effect
 - (b) cyclic hardening and cyclic softening
 - (c) shakedown to a saturated condition of constant stress and strain amplitudes
- 4. Recovery:
 - (a) static recovery
 - (b) dynamic recovery
- 5. Dynamic strain-aging effects, including:
 - (a) plateau in yield strength vs. temperature
 - (b) negative strain-rate sensitivity
 - (c) effect on creep rate
- 6. Complex histories:
 - (a) stress changes
 - (b) strain-rate changes
 - (c) temperature changes
- 7. Irradiation effects:
 - (a) irradiation hardening
 - (b) irradiation-enhanced creep
 - (c) channelling (strain softening)
 - (d) swelling

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8. Interactions of all of the above

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Figure 15.