CHAPTER 16 – TECHNICAL SPECIFICATIONS

16.1 Introduction to Technical Specifications

16.1.1 Technical Specification Content

The content of the APR1400 Technical Specifications (TS) meets the requirements of 10 CFR 50.36. The APR1400 Technical Specifications were developed using the most appropriate guidance, NUREG-1432 Rev. 4.0 (Ref. 1).

The difference between NUREG-1432 and the APR1400 Technical Specification only exists as necessary to reflect advanced design features and operational features. The units specified in the APR1400 Technical Specifications are the International system of units (SI units) and the English units. The SI units have been used as the primary unit and the English units have been used in parentheses. The choice of units is a Combined License (COL) information item to be resolved by a COL applicant (COL 16.1(1)); however the TS and Bases do not enclose the parameter value pairs in square brackets. This is an exception to the use of brackets to denote COL information in the TS and Bases.

16.1.1.1 Completion Times and Surveillance Frequencies

The Completion Times and Surveillance Frequencies specified in NUREG-1432 have generally applied to the associated Actions and Surveillance Requirements of the APR1400 Technical Specifications. For unique systems and features of the APR1400 design, similar Completion Times and Surveillance Frequencies have been adopted as appropriate.

16.1.1.2 Plant Design Difference

There are some design differences between the APR1400 Technical Specifications and current design in NUREG-1432. Major design differences include the four train emergency core cooling system design, the adoption of pilot operated safety relief valves (POSRVs), the change of ventilation systems, and auxiliary feedwater system configuration.
16.1.1.3 LCO and Bases information

Some Limiting Conditions for Operation (LCOs) of the APR1400 Technical Specifications have been added and changed compared to NUREG-1432, the related specifications are as below:

a. Charging Flow (Specification 3.1.8),

b. Special Test Exception (STE) – Reactivity Coefficient Testing (Specification 3.1.11),

c. Unborated Water Source Isolation Valve - MODES 4 and 5 (Specification 3.1.12)

d. Boron Dilution Alarms (Specification 3.3.14),

e. Reactor Coolant Gas Vent (RCGV) Function (Specification 3.4.16),

f. Low Temperature Overpressure Protection (LTOP) System (Specification 3.4.11),

g. RCS Specific Activity (Specification 3.4.15), and

h. Unborated Water Source Isolation Valve - MODE 6 (Specification 3.9.7).

The Surveillance Frequency Control Program of the NUREG-1432 has not been applied to the APR1400 plants.

16.1.1.4 Combined License Information

The intention of the APR1400 Technical Specifications is to be used as a guide for the development of the plant-specific Technical Specifications for plants which will reference the standard APR1400 plant. Single brackets ([ ]) are used to identify the preliminary design information or plant-specific information. A listing of the COL Action Items with a concise description of each item is provided in Table 16-1.

The APR1400 Technical Specifications and Bases (generic TS and Bases) are included in Chapter 16 of the APR1400 Design Control Document (DCD) Tier 2. The generic TS and Bases reference supporting information in other chapters and sections of DCD Tier 2 by using “Final Safety Analysis Report (FSAR)” instead of “DCD Tier 2.” The referenced DCD Tier 2 information is supplemented with site specific information by the combined license
applicant to form the FSAR, which is submitted as part of the combined license application. Therefore, the information referred to by an FSAR section and the equivalent DCD Tier 2 section is the same. But “FSAR” is the appropriate identifier for a combined license. By using “FSAR” in the generic TS and Bases, a combined license applicant can avoid making this administrative change as part of the combined license application, which would require an exemption from the generic TS or Bases. The plant-specific TS issued with the combined license would already appropriately refer to FSAR chapters and sections. And were a combined license issued with plant-specific TS and Bases referring to DCD Tier 2 chapters and sections, the combined license holder would need a license amendment to change DCD Tier 2 references in the plant-specific TS to FSAR references. The combined license holder would also need to change DCD Tier 2 references in the plant-specific TS Bases to FSAR references according to the requirements of the Bases Control Program administrative controls technical specification. Using “FSAR” in the generic TS and Bases avoids having to process an exemption during the combined license application review, or a license amendment after combined license issuance, to change “DCD Tier 2” to “FSAR.”

16.1.2 Reference

### Table 16-1 (1 of 4)

**List of COL Action Items**

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<th>Item No.</th>
<th>TS Section</th>
<th>Description</th>
<th>Resolution</th>
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<tr>
<td>COL 16.1(1)</td>
<td>Generic TS and Bases</td>
<td>SI units have been used as the primary unit and the English units have been used in parentheses.</td>
<td>The choice of units is a COL information item to be resolved by the COL applicant.</td>
</tr>
<tr>
<td>COL 16-3.0(1)</td>
<td>3.0 (LCO 3.0.9)</td>
<td>Allowance for continued operation with barriers incapable of performing their required support function for an SSC required to be operable by an LCO</td>
<td>The COL applicant is to prepare and submit for NRC staff review a site specific risk evaluation supporting the adoption of LCO 3.0.9 that is based on the site specific probabilistic risk assessment as described in FSAR Chapter 19.</td>
</tr>
<tr>
<td>COL 16-3(1)</td>
<td>B 3.0 (LCO 3.0.9)</td>
<td>LCO Applicability</td>
<td>Applicability of Reviewer’s Notes is to be determined by the COL applicant. The COL applicant is to prepare and submit for NRC staff review a site specific risk evaluation supporting the adoption of LCO 3.0.9 that is based on the site specific probabilistic risk assessment as described in FSAR Chapter 19.</td>
</tr>
<tr>
<td>B 3.1.4</td>
<td>Control Element Assembly (CEA) Alignment</td>
<td>The COL applicant is to provide the number of inches a CEA is assumed to be withdrawn with its rod bank at the bank insertion limit.</td>
<td></td>
</tr>
<tr>
<td>B 3.6.7</td>
<td>Containment Penetrations - Shutdown Operations</td>
<td>The COL applicant is to provide UHS site-specific design related Bases text.</td>
<td></td>
</tr>
<tr>
<td>B 3.7.5</td>
<td>Auxiliary Feedwater System (AFWS)</td>
<td>Applicability of Reviewer’s Notes is to be determined by the COL applicant.</td>
<td></td>
</tr>
<tr>
<td>B 3.7.9</td>
<td>Ultimate Heat Sink</td>
<td>Once the COL applicant has dispositioned the Reviewer’s Note, the Note can be removed from the Bases.</td>
<td></td>
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<tr>
<td>B 3.7.11</td>
<td>Control room HVAC System (CRHS)</td>
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<td>B 3.7.12</td>
<td>Auxiliary Building Controlled Area Emergency Exhaust System (ABCAEES)</td>
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<td>B 3.8.1</td>
<td>AC Sources – Operating</td>
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<td>B 3.9.3</td>
<td>Containment Penetrations</td>
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<td>Item No.</td>
<td>TS Section</td>
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<tr>
<td>COL 16-3.6(1)</td>
<td>3.6.7</td>
<td>Containment Penetrations – Shutdown Operations</td>
<td>The COL applicant is to provide the minimum number of bolts, completion time, and surveillance frequency for shutdown operations. The value will be determined based on plant specific Shutdown Evaluation Report to satisfy the 10 CFR 50.34 dose limits.</td>
</tr>
<tr>
<td>COL 16-3.7(1)</td>
<td>3.7.5</td>
<td>Auxiliary Feedwater System (AFWS)</td>
<td>The COL applicant may either use the completion time for required action for Condition A &amp; C or provide a risk-informed justification to increase the completion time.</td>
</tr>
<tr>
<td>COL 16-3.7(2)</td>
<td>3.7.9</td>
<td>Ultimate Heat Sink (UHS)</td>
<td>The COL applicant is to provide the completion time, and surveillance frequency for ultimate heat sink. Ultimate heat sink design value varies depending on site characteristics. The COL applicant is to provide a site-specific UHS subsection based on the site-specific design, that contains appropriate LCO operability requirements, action requirements, and surveillance requirements.</td>
</tr>
<tr>
<td>COL 16-3.7(3)</td>
<td>3.7.11</td>
<td>Control Room Habitability Area option for design features to protect occupant exposures to toxic gases</td>
<td>The COL applicant is to provide the details of specific toxic chemicals of mobile and stationary sources and evaluate the MCR habitability based on the recommendation in RG 1.78. The specific toxic gas concentrations in the air intakes will vary depending on site. If the COL applicant determines that the maximum toxic gas concentrations in the MCR from all of the given site-specific toxic gas sources do not exceed the toxicity limits of RG 1.78, toxic gas detectors and the toxic gas isolation mode of the CRHS are not required by the LCO and the associated toxic-gas-related bracketed phrases may be deleted.</td>
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<td>COL 16-3.8(1)</td>
<td>3.8.1</td>
<td>SR 3.8.1.4, Day Tank Capacity</td>
<td>The COL applicant is to provide the specific value in accordance with EDG manufacture’s specific design characteristics.</td>
</tr>
<tr>
<td>COL 16-3.8(2)</td>
<td>3.8.1</td>
<td>SR 3.8.1.8, Offsite Power Transfer Test SR 3.8.1.9, EDG Single Largest Load Rejection Test SR 3.8.1.10, EDG Full-Load Rejection Test SR 3.8.1.12, EDG ESF Actuation Test SR 3.8.1.13, EDG Bypassed Trip Signal Test SR 3.8.1.18, EDG Load Sequencer Test</td>
<td>The COL applicant is to determine the unit operational MODE in which the Surveillance is allowed to be performed consistent with safe unit operation and surveillance performance policy. A MODE restriction may be removed if the COL applicant demonstrates that unit safety is maintained or enhanced when the surveillance is performed in a restricted MODE, which is denoted in brackets.</td>
</tr>
<tr>
<td>COL 16-3.8(3)</td>
<td>3.8.1</td>
<td>SR 3.8.1.9, EDG Single Largest Load Rejection Test SR 3.8.1.10, EDG Full-Load Rejection Test SR 3.8.1.14, EDG Endurance and Load Test</td>
<td>The COL applicant is to determine EDG power factor criterion for the surveillance, which must be appropriate for demonstrating EDG operability. The appropriate limiting power factor for EDG operation depends on plant specific EDG Class 1E loads, the acceptable range of the offsite power factor, and the existing current, voltage, and power factor conditions of the offsite circuit used to load the EDG for the surveillance.</td>
</tr>
<tr>
<td>COL 16-3.8(4)</td>
<td>3.8.3</td>
<td>Action E, SR 3.8.3.4 Starting Air Receiver Pressure</td>
<td>The COL applicant is to provide the specific value in accordance with EDG manufacturer’s specific design recommendation.</td>
</tr>
<tr>
<td>COL 16-3.9(1)</td>
<td>3.9.3</td>
<td>Containment Penetrations</td>
<td>The COL applicant is to provide the minimum number of bolts for equipment hatch. The value will be determined based on plant specific Shutdown Evaluation Report to satisfy the 10 CFR 50.34 dose limits.</td>
</tr>
<tr>
<td>COL 16-4.1(1)</td>
<td>4.1</td>
<td>Site Location</td>
<td>Information on site location is to be provided by the COL applicant.</td>
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<td>COL 16.5(1)</td>
<td>5.1</td>
<td>Responsibility</td>
<td>Applicability of Reviewer’s Note is to be determined by the COL applicant. Once the COL applicant has dispositioned the Review's Note, the Note can be removed from the Bases.</td>
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<td>5.5.11</td>
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<td>5.5.17</td>
<td>Battery Monitoring and Maintenance Program</td>
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<td>5.5.19</td>
<td>Setpoint Control Program</td>
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<td>5.6.4</td>
<td>Reactor Coolant System (RCS) PRESSURE AND TEMPERATURE LIMITS REPORT (PTLR)</td>
<td></td>
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<tr>
<td>COL 16-5.3(1)</td>
<td>5.3</td>
<td>Unit Staff Qualifications</td>
<td>The requirement for unit staff qualification shall be determined by COL applicant based on latest NRC RG 1.8 and ANSI standard acceptable to NRC staff.</td>
</tr>
<tr>
<td>COL 16-5.4(1)</td>
<td>5.4</td>
<td>Procedures</td>
<td>The COL applicant will determine the modification of core protection calculator (CPC) addressable constants based on plant specific data.</td>
</tr>
<tr>
<td>COL 16-5.5(1)</td>
<td>5.5.12</td>
<td>Explosive Gas and Storage Tank Radioactivity Monitoring Program</td>
<td>The methodology for gaseous radioactivity quantities and the liquid radwaste quantities is to be provided by the COL applicant.</td>
</tr>
<tr>
<td>COL 16-5.5(2)</td>
<td>5.5.19</td>
<td>Setpoint Control Program</td>
<td>The FSAR reference on setpoint control document is to be specified by the COL applicant.</td>
</tr>
<tr>
<td>COL 16-5.6(1)</td>
<td>5.6.1</td>
<td>Annual Radiological Environmental Operating Report Radiological Effluent Release Report</td>
<td>A single submittal of reporting on multiple unit stations is to be determined in COL stage.</td>
</tr>
<tr>
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<td>5.6.2</td>
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<tr>
<td>COL 16-5.6(2)</td>
<td>5.6.1</td>
<td>Annual Radiological Environmental Operating Report</td>
<td>The COL applicant will determine the format of the table. Either format of the table in the Radiological Assessment Branch Technical Position, Revision 1, November 1979, or use another format that is acceptable to NRC.</td>
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APR1400
TECHNICAL SPECIFICATIONS

Specifications
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</tbody>
</table>
Definitions

1.0 USE AND APPLICATIONS

1.1 Definitions

The defined terms of this section appear in capitalized type and are applicable throughout these Technical Specifications and Bases.

<table>
<thead>
<tr>
<th>Term</th>
<th>Definition</th>
</tr>
</thead>
<tbody>
<tr>
<td>ACTIONS</td>
<td>ACTIONS shall be that part of a Specification that prescribes Required Actions to be taken under designated Conditions within specified Completion Times.</td>
</tr>
<tr>
<td>AXIAL SHAPE INDEX (ASI)</td>
<td>ASI shall be the power generated in the lower half of the core less the power generated in the upper half of the core, divided by the sum of the power generated in the lower and upper halves of the core.</td>
</tr>
<tr>
<td>AZIMUTHAL POWER TILT (Tq)</td>
<td>AZIMUTHAL POWER TILT shall be the power asymmetry between azimuthally symmetric fuel assemblies.</td>
</tr>
<tr>
<td>CHANNEL CALIBRATION</td>
<td>A CHANNEL CALIBRATION shall be the adjustment, as necessary, of the channel output such that it responds within the necessary range and accuracy to known values of the parameter that the channel monitors. The CHANNEL CALIBRATION shall encompass the entire channel, including the required sensor, alarm, and trip functions, and shall include the CHANNEL FUNCTIONAL TEST. Calibration of instrument channels with resistance temperature detector (RTD) or thermocouple sensors may consist of an in-place cross calibration of the sensing elements and normal calibration of the remaining adjustable devices in the channel. Whenever a sensing element is replaced, the next required in-place cross calibration consists of comparing the other sensing elements with the recently installed sensing element. The CHANNEL CALIBRATION may be performed by means of any series of sequential, overlapping, or total channel steps so that the entire channel is calibrated.</td>
</tr>
</tbody>
</table>
### 1.1 Definitions

| **Channel Check** | A CHANNEL CHECK shall be the qualitative assessment, by observation, of channel behavior during operation. This determination shall include, where possible, comparison of the channel indication and status to other indications or status derived from independent instrument channels measuring the same parameter. |
| **Channel Functional Test** | A CHANNEL FUNCTIONAL TEST shall be: |
| | a. Analog and bistable logic channels – the injection of a simulated or actual signal into the channel as close to the sensor as practicable to verify OPERABILITY, including required alarms, interlocks, display and trip functions. |
| | b. Digital computer channels – the use of diagnostic programs to test digital computer hardware and the injection of simulated process data into the channel to verify OPERABILITY, including alarms and trip functions. |
| **Core Alteration** | CORE ALTERATION shall be the movement or manipulation of any fuel, sources, reactivity control components, or other components (excluding control element assemblies (CEAs) withdrawn into the upper guide structure) affecting reactivity within the reactor vessel with the vessel head removed and fuel in the vessel. Suspension of CORE ALTERATIONS shall not preclude completion of movement of a component to a safe position. |
| **Core Operating Limits Report (COLR)** | The COLR is the unit specific document that provides cycle specific parameter limits for the current reload cycle. These cycle specific parameter limits shall be determined for each reload cycle in accordance with Specification 5.6.3. Plant operation within these limits is addressed in individual Specifications. |
DOSE EQUIVALENT I-131 shall be that concentration of I-131 (Bq/g) that alone would produce the same dose when inhaled as the combined activities of iodine isotopes I-131, I-132, I-133, I-134, and I-135 actually present. The determination of DOSE EQUIVALENT I-131 shall be performed using thyroid dose conversion factors from Table 2.1 of EPA Federal Guidance Report No. 11, “Limiting Values of Radionuclide Intake and Air Concentration and Dose Conversion Factors for Inhalation, Submersion, and Ingestion,” EPA-520/1-88-020, September 1988.

DOSE EQUIVALENT XE-133 shall be that concentration of Xe-133 (Bq/g) that alone would produce the same acute dose to the whole body as the combined activities of noble gas nuclides Kr-85m, Kr-85, Kr-87, Kr-88, Xe-131m, Xe-133m, Xe-133, Xe-135m, Xe-135 and Xe-138 actually present. The determination of DOSE EQUIVALENT XE-133 shall be performed using effective dose conversion factors for air submersion listed in Table III.1 of EPA Federal Guidance Report No. 12, “External Exposure to Radionuclides in Air, Water, and Soil,” EPA 402-R-93-081, September 1993.

The ESF RESPONSE TIME shall be the time interval from when the monitored parameter exceeds its ESF actuation setpoint at the channel sensor until the ESF equipment is capable of performing its safety function (i.e., the valves travel to their required positions, pump discharge pressures reach their required values, etc.). Times shall include emergency diesel generator starting and sequence loading delays, where applicable. The response time may be measured by means of any series of sequential, overlapping, or total steps so that the entire response time is measured. In lieu of measurement, response time may be verified for selected components provided that the components and methodology for verification have been previously reviewed and approved by the NRC.
1.1 Definitions

LEAKAGE

LEAKAGE shall be:

a. Identified LEAKAGE

1. LEAKAGE, such as that from pump seals or valve packing (except reactor coolant pump (RCP) seal water injection or leakoff), that is captured and conducted to collection systems or a sump or collecting tank,

2. LEAKAGE into the containment atmosphere from sources that are both specifically located and known either not to interfere with the operation of leakage detection systems or not to be pressure boundary LEAKAGE, or

3. Reactor Coolant System (RCS) LEAKAGE through a steam generator (SG) to the Secondary System (primary to secondary LEAKAGE),

b. Unidentified LEAKAGE

All LEAKAGE (except RCP seal water injection or leakoff) that is not identified LEAKAGE, and

c. Pressure Boundary LEAKAGE

LEAKAGE (except primary to secondary LEAKAGE) through a nonisolable fault in an RCS component body, pipe wall, or vessel wall.

MODE

A MODE shall correspond to any one inclusive combination of core reactivity condition, power level, reactor coolant cold leg temperature, and reactor vessel head closure bolt tensioning specified in Table 1.1-1 with fuel in reactor vessel.
1.1 Definitions

OPERABLE - OPERABILITY
A system, subsystem, division, train, component or device shall be OPERABLE or have OPERABILITY when it is capable of performing its specified safety function(s) and when all necessary attendant instrumentation, controls, normal or emergency electrical power, cooling and seal water, lubrication, and other auxiliary equipment that are required for the system, subsystem, division, train, component, or device to perform its specified function(s) are also capable of performing their related support function(s).

PHYSICS TESTS
PHYSICS TESTS shall be those tests performed to measure the fundamental nuclear characteristics of the reactor core and related instrumentation. These tests are:

a. Described in Chapter 14, Initial Test Program, of the FSAR,

b. Authorized under the provisions of 10 CFR 50.59, or

c. Otherwise approved by the NRC.

PRESSURE AND TEMPERATURE LIMITS REPORT (PTLR)
The PTLR is the unit specific document that provides the reactor vessel pressure and temperature limits, including heatup and cooldown rates, for the current reactor vessel fluence period. These pressure and temperature limits shall be determined for each fluence period in accordance with Specification 5.6.4.

RATED THERMAL POWER (RTP)
RTP shall be a total reactor core heat transfer rate to the reactor coolant of 3,983 MWt.

REACTOR PROTECTION SYSTEM (RPS) RESPONSE TIME
The RPS RESPONSE TIME shall be that time interval from when the monitored parameter exceeds its RPS trip setpoint at the input to the channel sensor until electrical power to the CEA’s drive mechanism is interrupted. The response time may be measured by means of any series of sequential, overlapping, or total steps so the entire response time is measured. In lieu of measurement, response time may be verified for selected components provided that the components and methodology for verification have been previously reviewed and approved by the NRC.
**SHUTDOWN MARGIN (SDM)**

SDM shall be the instantaneous amount of reactivity by which the reactor is subcritical or would be subcritical from its present condition assuming:

a. All full strength CEAs (shutdown and regulating) are fully inserted except for the single CEA of highest reactivity worth, which is assumed to be fully withdrawn. However, with all CEAs verified fully inserted by two independent means, it is not necessary to account for a stuck CEA in the SDM calculation. With any CEAs not capable of being fully inserted, the reactivity worth of these CEAs must be accounted for in the determination of SDM, and

b. There is no change in part strength CEA position.

**STAGGERED TEST BASIS**

A STAGGERED TEST BASIS shall consist of the testing of one of the systems, subsystems, channels, or other designated components during the interval specified by the Surveillance Frequency, so that all systems, subsystems, channels, or other designated components are tested during \( n \) Surveillance Frequency intervals, where \( n \) is the total number of systems, subsystems, channels, or other designated components in the associated function.

**THERMAL POWER**

THERMAL POWER shall be the total reactor core heat transfer rate to the reactor coolant.
Table 1.1-1 (page 1 of 1)

<table>
<thead>
<tr>
<th>MODE</th>
<th>TITLE</th>
<th>REACTIVITY CONDITION ((k_{\text{eff}}))</th>
<th>% RATED THERMAL POWER(^{\text{(a)}})</th>
<th>REACTOR COOLANT COLD LEG TEMPERATURES</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>Power Operation</td>
<td>≥ 0.99</td>
<td>&gt; 5</td>
<td>NA</td>
</tr>
<tr>
<td>2</td>
<td>Startup</td>
<td>≥ 0.99</td>
<td>≤ 5</td>
<td>NA</td>
</tr>
<tr>
<td>3</td>
<td>Hot Standby</td>
<td>&lt; 0.99</td>
<td>NA</td>
<td>≥ 177°C (350°F)</td>
</tr>
<tr>
<td>4</td>
<td>Hot Shutdown(^{\text{(b)}})</td>
<td>&lt; 0.99</td>
<td>NA</td>
<td>177°C (350°F) &gt; T_{cold} &gt; 99°C (210°F)</td>
</tr>
<tr>
<td>5</td>
<td>Cold Shutdown(^{\text{(b)}})</td>
<td>&lt; 0.99</td>
<td>NA</td>
<td>≤ 99°C (210°F)</td>
</tr>
<tr>
<td>6</td>
<td>Refueling(^{\text{(c)}})</td>
<td>NA</td>
<td>NA</td>
<td>NA</td>
</tr>
</tbody>
</table>

\(^{\text{(a)}}\) Excluding decay heat

\(^{\text{(b)}}\) All reactor vessel head closure bolts fully tensioned

\(^{\text{(c)}}\) One or more reactor vessel head closure bolts less than fully tensioned
1.0 USE AND APPLICATIONS

1.2 Logical Connectors

PURPOSE The purpose of this section is to explain the meaning of logical connectors.

Logical connectors are used in Technical Specifications (TS) to discriminate between, and yet connect, discrete Conditions, Required Actions, Completion Times, Surveillances, and Frequencies. The only logical connectors that appear in TS are AND and OR. The physical arrangement of these connectors constitutes logical conventions with specific meanings.

BACKGROUND Several levels of logic may be used to state Required Actions. These levels are identified by the placement (or nesting) of the logical connectors and by the number assigned to each Required Action. The first level of logic is identified by the first digit of the number assigned to a Required Action and the placement of the logical connector in the first level of nesting (i.e., left justified with the number of the Required Action). The successive levels of logic are identified by additional digits of the Required Action number and by successive indentions of the logical connectors.

When logical connectors are used to state a Condition, Completion Time, Surveillance, or Frequency, only the first level of logic is used, and the logical connector is left justified with the statement of the Condition, Completion Time, Surveillance, or Frequency.

EXAMPLES The following examples illustrate the use of logical connectors.
### EXAMPLE 1.2-1

**ACTIONS**

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. LCO not met.</td>
<td>A.1 Verify …</td>
<td></td>
</tr>
<tr>
<td></td>
<td>AND</td>
<td></td>
</tr>
<tr>
<td></td>
<td>A.2 Restore …</td>
<td></td>
</tr>
</tbody>
</table>

In this example, the logical connector **AND** is used to indicate that when in Condition A, both Required Actions A.1 and A.2 must be completed.
EXAMPLE 1.2-2

ACTIONS

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. LCO not met.</td>
<td>A.1 Trip …</td>
<td></td>
</tr>
<tr>
<td></td>
<td>OR</td>
<td></td>
</tr>
<tr>
<td></td>
<td>A.2.1 Verify …</td>
<td></td>
</tr>
<tr>
<td></td>
<td>AND</td>
<td></td>
</tr>
<tr>
<td></td>
<td>A.2.2.1 Reduce …</td>
<td></td>
</tr>
<tr>
<td></td>
<td>OR</td>
<td></td>
</tr>
<tr>
<td></td>
<td>A.2.2.2 Perform …</td>
<td></td>
</tr>
<tr>
<td></td>
<td>OR</td>
<td></td>
</tr>
<tr>
<td></td>
<td>A.3 Align …</td>
<td></td>
</tr>
</tbody>
</table>

This example represents a more complicated use of logical connectors. Required Actions A.1, A.2, and A.3 are alternative choices, only one of which must be performed as indicated by the use of the logical connector OR and the left justified placement. Any one of these three Actions may be chosen. If A.2 is chosen, then both A.2.1 and A.2.2 must be performed as indicated by the logical connector AND. Required Action A.2.2 is met by performing A.2.2.1 or A.2.2.2. The indented position of the logical connector OR indicates that A.2.2.1 and A.2.2.2 are alternative choices, only one of which must be performed.
1.0 USE AND APPLICATIONS

1.3 Completion Times

PURPOSE The purpose of this section is to establish the Completion Time convention and to provide guidance for its use.

BACKGROUND Limiting Conditions for Operation (LCOs) specify minimum requirements for ensuring safe operation of the unit. The ACTIONS associated with an LCO state Conditions that typically describe the ways in which the requirements of the LCO can fail to be met. Specified with each stated Condition are Required Action(s) and Completion Time(s).

DESCRIPTION The Completion Time is the amount of time allowed for completing a Required Action. It is referenced to the time of discovery of a situation (e.g., inoperable equipment or variable not within limits) that requires entering an ACTIONS Condition, unless otherwise specified, providing the unit is in a MODE or specified condition stated in the Applicability of the LCO. Required Actions must be completed prior to the expiration of the specified Completion Time. An ACTIONS Condition remains in effect and the Required Actions apply until the Condition no longer exists or the unit is not within the LCO Applicability.

If situations are discovered that require entry into more than one Condition at a time within a single LCO (multiple Conditions), the Required Actions for each Condition must be performed within the associated Completion Time. When in multiple Conditions, separate Completion Times are tracked for each Condition starting from the time of discovery of the situation that required entry into the Condition.

Once a Condition has been entered, subsequent trains, subsystems, components, or variables expressed in the Condition, discovered to be inoperable or not within limits, will not result in separate entry into the Condition, unless specifically stated. The Required Actions of the Condition continue to apply to each additional failure, with Completion Times based on initial entry into the Condition.
1.3 Completion Times

Description (continued)

However, when a subsequent train, subsystem, component, or variable expressed in the Condition is discovered to be inoperable or not within limits, the Completion Time(s) may be extended. To apply this Completion Time extension, two criteria must first be met. The subsequent inoperability:

a. Must exist concurrent with the first inoperability and

b. Must remain inoperable or not within limits after the first inoperability is resolved.

The total Completion Time allowed for completing a Required Action to address the subsequent inoperability shall be limited to the more restrictive of either:

a. The stated Completion Time, as measured from the initial entry into the Condition, plus an additional 24 hours or

b. The stated Completion Time as measured from discovery of the subsequent inoperability.

The above Completion Time extensions do not apply to those Specifications that have exceptions that allow completely separate re-entry into the Condition (for each train, subsystem, component, or variable expressed in the Condition) and separate tracking of Completion Times based on this re-entry. These exceptions are stated in individual Specifications.

The above Completion Time extension does not apply to a Completion Time with a modified “time zero.” This modified “time zero” may be expressed as a repetitive time (i.e., “once per 8 hours,” where the Completion Time is referenced from a previous completion of the Required Action versus the time of Condition entry) or as a time modified by the phrase “from discovery...”
1.3 Completion Times

EXAMPLES

The following examples illustrate the use of Completion Times with different types of Conditions and changing Conditions.

EXAMPLE 1.3-1

ACTIONS

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>B. Required Actions and associated Completion Time not met.</td>
<td>B.1 Be in MODE 3.</td>
<td>6 hours</td>
</tr>
<tr>
<td></td>
<td>AND</td>
<td></td>
</tr>
<tr>
<td></td>
<td>B.2 Be in MODE 5.</td>
<td>36 hours</td>
</tr>
</tbody>
</table>

Condition B has two Required Actions. Each Required Action has its own separate Completion Time. Each Completion Time is referenced to the time that Condition B is entered.

The Required Actions of Condition B are to be in MODE 3 within 6 hours AND in MODE 5 within 36 hours. A total of 6 hours is allowed for reaching MODE 3 and a total of 36 hours (not 42 hours) is allowed for reaching MODE 5 from the time that Condition B was entered. If MODE 3 is reached within 3 hours, the time allowed for reaching MODE 5 is the next 33 hours because the total time allowed for reaching MODE 5 is 36 hours.

If Condition B is entered while in MODE 3, the time allowed for reaching MODE 5 is the next 36 hours.
EXAMPLE 1.3-2

**ACTIONS**

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. One pump inoperable.</td>
<td>A.1 Restore pump to OPERABLE status.</td>
<td>7 days</td>
</tr>
<tr>
<td>B. Required Actions and associated Completion Time not met.</td>
<td>B.1 Be in MODE 3.</td>
<td>6 hours</td>
</tr>
<tr>
<td></td>
<td>AND</td>
<td></td>
</tr>
<tr>
<td></td>
<td>B.2 Be in MODE 5.</td>
<td>36 hours</td>
</tr>
</tbody>
</table>

When a pump is declared inoperable, Condition A is entered. If the pump is not restored to OPERABLE status within 7 days, Condition B is also entered and the Completion Time clocks for Required Actions B.1 and B.2 start. If the inoperable pump is restored to OPERABLE status after Condition B is entered, Conditions A and B are exited, and therefore, the Required Actions of Condition B may be terminated.

When a second pump is declared inoperable while the first pump is still inoperable, Condition A is not re-entered for the second pump. LCO 3.0.3 is entered, since the ACTIONS do not include a Condition for more than one inoperable pump. The Completion Time clock for Condition A does not stop after LCO 3.0.3 is entered, but continues to be tracked from the time Condition A was initially entered.
1.3 Completion Times

EXAMPLES (continued)

While in LCO 3.0.3, if one of the inoperable pumps is restored to OPERABLE status and the Completion Time for Condition A has not expired, LCO 3.0.3 may be exited and operation continued in accordance with Condition A.

While in LCO 3.0.3, if one of the inoperable pumps is restored to OPERABLE status and the Completion Time for Condition A has expired, LCO 3.0.3 may be exited and operation continued in accordance with Condition B. The Completion Time for Condition B is tracked from the time the Condition A Completion Time expired.

On restoring one of the pumps to OPERABLE status, the Condition A Completion Time is not reset, but continues from the time the first pump was declared inoperable. This Completion Time may be extended if the pump restored to OPERABLE status was the first inoperable pump. A 24 hour extension to the stated 7 days is allowed, provided this does not result in the second pump being inoperable for > 7 days.
**EXAMPLE 1.3-3**

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. One Function X train inoperable.</td>
<td>A.1 Restore Function X train to OPERABLE status.</td>
<td>7 days</td>
</tr>
<tr>
<td>B. One Function Y train inoperable.</td>
<td>B.1 Restore Function Y train to OPERABLE status.</td>
<td>72 hours</td>
</tr>
<tr>
<td>C. One Function X train inoperable.</td>
<td>C.1 Restore Function X train to OPERABLE status.</td>
<td>72 hours</td>
</tr>
<tr>
<td>AND One Function Y train inoperable.</td>
<td>OR C.2 Restore Function Y train to OPERABLE status.</td>
<td>72 hours</td>
</tr>
</tbody>
</table>

When one Function X train and one Function Y train are inoperable, Condition A and Condition B are concurrently applicable. The Completion Times for Condition A and Condition B are tracked separately for each train starting from the time each train was declared inoperable and the Condition was entered. A separate Completion Time is established for Condition C and tracked from the time the second train was declared inoperable (i.e., the time the situation described in Condition C was discovered).
1.3 Completion Times

EXAMPLES (continued)

If Required Action C.2 is completed within the specified Completion Time, Conditions B and C are exited. If the Completion Time for Required Action A.1 has not expired, operation may continue in accordance with Condition A. The remaining Completion Time in Condition A is measured from the time the affected train was declared inoperable (i.e., initial entry into Condition A).

It is possible to alternate between Conditions A, B, and C in such a manner that operation could continue indefinitely without ever restoring systems to meet the LCO. However, doing so would be inconsistent with the basis of the Completion Times. Therefore, there shall be administrative controls to limit the maximum time allowed for any combination of Conditions that result in a single contiguous occurrence of failing to meet the LCO. These administrative controls shall ensure that the Completion Times for those Conditions are not inappropriately extended.
EXAMPLE 1.3-4

**ACTIONS**

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. One or more valves inoperable.</td>
<td>A.1 Restore valve(s) to OPERABLE status.</td>
<td>4 hours</td>
</tr>
<tr>
<td>B. Required Action and associated Completion Time not met.</td>
<td>B.1 Be in MODE 3.</td>
<td>6 hours</td>
</tr>
<tr>
<td></td>
<td>AND</td>
<td></td>
</tr>
<tr>
<td></td>
<td>B.2 Be in MODE 4.</td>
<td>12 hours</td>
</tr>
</tbody>
</table>

A single Completion Time is used for any number of valves inoperable at the same time. The Completion Time associated with Condition A is based on the initial entry into Condition A and is not tracked on a per valve basis. Declaring subsequent valves inoperable, while Condition A is still in effect, does not trigger the tracking of separate Completion Times.

Once one of the valves has been restored to OPERABLE status, the Condition A Completion Time is not reset, but continues from the time the first valve was declared inoperable. The Completion Time may be extended if the valve restored to OPERABLE status was the first inoperable valve. The Condition A Completion Time may be extended for up to 4 hours provided this does not result in any subsequent valve being inoperable for > 4 hours.

If the Completion Time of 4 hours (including the extension) expires while one or more valves are still inoperable, Condition B is entered.
EXAMPLE 1.3-5

**ACTIONS**

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. One or more valves inoperable.</td>
<td>A.1 Restore valve to OPERABLE status.</td>
<td>4 hours</td>
</tr>
<tr>
<td>B. Required Action and associated Completion Time not met.</td>
<td>B.1 Be in MODE 3. AND B.2 Be in MODE 4.</td>
<td>6 hours 12 hours</td>
</tr>
</tbody>
</table>

The Note above the ACTIONS Table is a method of modifying how the Completion Time is tracked. If this method of modifying how the Completion Time is tracked was applicable only to a specific Condition, the Note would appear in that Condition rather than at the top of the ACTIONS Table.

The Note allows Condition A to be entered separately for each inoperable valve and Completion Times tracked on a per valve basis. When a valve is declared inoperable, Condition A is entered and its Completion Time starts. If subsequent valves are declared inoperable, Condition A is entered for each valve and separate Completion Times start and are tracked for each valve.
If the Completion Time associated with a valve in Condition A expires, Condition B is entered for that valve. If the Completion Times associated with subsequent valves in Condition A expire, Condition B is entered separately for each valve and separate Completion Times start and are tracked for each valve. If a valve that caused entry into Condition B is restored to OPERABLE status, Condition B is exited for that valve.

Since the Note in this example allows multiple Condition entry and tracking of separate Completion Times, Completion Time extensions do not apply.
1.3 Completion Times

EXAMPLES (continued)

EXAMPLE 1.3-6

<table>
<thead>
<tr>
<th>ACTIONS</th>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. One channel inoperable.</td>
<td>A.1</td>
<td>Perform SR 3.x.x.x.</td>
<td>Once per 8 hours</td>
</tr>
<tr>
<td>OR</td>
<td>A.2</td>
<td>Reduce THERMAL POWER to ≤ 50% RTP.</td>
<td>8 hours</td>
</tr>
<tr>
<td>B. Required Action and associated Completion Time not met.</td>
<td>B.1</td>
<td>Be in MODE 3.</td>
<td>6 hours</td>
</tr>
</tbody>
</table>

Entry into Condition A offers a choice between Required Action A.1 or A.2. Required Action A.1 has a “once per” Completion Time, which qualifies for the 25% extension, per SR 3.0.2, to each performance after the initial performance. The initial 8 hour interval of Required Action A.1 begins when Condition A is entered and the initial performance of Required Action A.1 must be complete within the first 8 hour interval. If Required Action A.1 is followed and the Required Action is not met within the Completion Time (plus the extension allowed by SR 3.0.2), Condition B is entered. If Required Action A.2 is followed and the Completion Time of 8 hours is not met, Condition B is entered.

If after entry into Condition B, Required Action A.1 or A.2 is met, Condition B is exited and operation may then continue in Condition A.
1.3 Completion Times

EXAMPLES (continued)

**EXAMPLE 1.3-7**

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. One channel inoperable.</td>
<td><strong>A.1</strong> Verify affected subsystem isolated.</td>
<td>1 hour AND Once per 8 hours thereafter</td>
</tr>
<tr>
<td></td>
<td><strong>A.2</strong> Restore subsystem to OPERABLE status.</td>
<td>72 hours</td>
</tr>
<tr>
<td>B. Required Action and associated Completion Time not met.</td>
<td><strong>B.1</strong> Be in MODE 3.</td>
<td>6 hours AND</td>
</tr>
<tr>
<td></td>
<td><strong>B.2</strong> Be in MODE 5.</td>
<td>36 hours</td>
</tr>
</tbody>
</table>

Required Action A.1 has two Completion Times. The 1 hour Completion Time begins at the time the Condition is entered and each “Once per 8 hours thereafter” interval begins upon performance of Required Action A.1.
1.3 Completion Times

EXAMPLES (continued)

If after Condition A is entered, Required Action A.1 is not met within either the initial 1 hour or any subsequent 8 hour interval from the previous performance (plus the extension allowed by SR 3.0.2), Condition B is entered. The Completion Time clock for Condition A does not stop after Condition B is entered, but continues from the time Condition A was initially entered. If Required Action A.1 is met after Condition B is entered, Condition B is exited and operation may continue in accordance with Condition A, provided the Completion Time for Required Action A.2 has not expired.

IMMEDIATE COMPLETION TIME

When “Immediately” is used as a Completion Time, the Required Action should be pursued without delay and in a controlled manner.
1.0 USE AND APPLICATIONS

1.4 Frequency

PURPOSE The purpose of this section is to define the proper use and application of Frequency requirements.

DESCRIPTION Each Surveillance Requirement (SR) has a specified Frequency in which the Surveillance must be met in order to meet the associated LCO. An understanding of the correct application of the specified Frequency is necessary for compliance with the SR.

The “specified Frequency” is referred to throughout this section and each of the Specifications of Section 3.0, “Surveillance Requirement (SR) Applicability.” The “specified Frequency” consists of the requirements of the Frequency column of each SR, as well as certain Notes in the Surveillance column that modify performance requirements.

Sometimes special situations dictate when the requirements of a Surveillance are to be met. They are "otherwise stated" conditions allowed by SR 3.0.1. They may be stated as clarifying Notes in the Surveillance, as part of the Surveillances, or both.

Situations where a Surveillance could be required (i.e., its Frequency could expire), but where it is not possible or not desired that it be performed until sometime after the associated LCO is within its Applicability, represent potential SR 3.0.4 conflicts. To avoid these conflicts, the SR (i.e., the Surveillance or the Frequency) is stated such that it is only “required” when it can be and should be performed. With an SR satisfied, SR 3.0.4 imposes no restriction.

The use of "met" or "performed" in these instances conveys specific meanings. A Surveillance is "met" only when the acceptance criteria are satisfied. Known failure of the requirements of a Surveillance, even without a Surveillance specifically being "performed," constitutes a Surveillance not "met." "Performance" refers only to the requirement to specifically determine the ability to meet the acceptance criteria.
Some Surveillances contain Notes that modify the Frequency of performance or the conditions during which the acceptance criteria must be satisfied. For these Surveillances, the MODE-entry restrictions of SR 3.0.4 may not apply. Such a Surveillance is not required to be performed prior to entering a MODE or other specified condition in the Applicability of the associated LCO if any of the following three conditions are satisfied:

a. The Surveillance is not required to be met in the MODE or other specified condition to be entered; or

b. The Surveillance is required to be met in the MODE or other specified condition to be entered, but has been performed within the specified Frequency (i.e., it is current) and is known not to be failed; or

c. The Surveillance is required to be met, but not performed, in the MODE or other specified condition to be entered, and is known not to be failed.

Examples 1.4-3, 1.4-4, 1.4-5, and 1.4-6 discuss these special situations.
1.4 Frequency

EXAMPLES

The following examples illustrate the various ways that Frequencies are specified. In these examples, the Applicability of the LCO (LCO not shown) is MODES 1, 2, and 3.

EXAMPLE 1.4-1

SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>Perform CHANNEL CHECK</td>
<td>12 hours</td>
</tr>
</tbody>
</table>

Example 1.4-1 contains the type of SR most often encountered in the Technical Specifications (TS). The Frequency specifies an interval (12 hours) during which the associated Surveillance must be performed at least one time. Performance of the Surveillance initiates the subsequent interval. Although the Frequency is stated as 12 hours, an extension of the time interval to 1.25 times the stated Frequency is allowed by SR 3.0.2 for operational flexibility. The measurement of this interval continues at all times, even when the SR is not required to be met per SR 3.0.1 (such as when the equipment is inoperable, a variable is outside specified limits, or the unit is outside the Applicability of the LCO). If the interval specified by SR 3.0.2 is exceeded while the unit is in a MODE or other specified condition in the Applicability of the LCO, and the performance of the Surveillance is not otherwise modified (refer to Example 1.4-3), then SR 3.0.3 becomes applicable.

If the interval as specified by SR 3.0.2 is exceeded while the unit is not in a MODE or other specified condition in the Applicability of the LCO for which performance of the SR is required, then SR 3.0.4 becomes applicable. The Surveillance must be performed within the Frequency requirements of SR 3.0.2, as modified by SR 3.0.3, prior to entry into the MODE or other specified condition or the LCO is considered not met (in accordance with SR 3.0.1) and LCO 3.0.4 becomes applicable.
### EXAMPLE 1.4-2

**SURVEILLANCE REQUIREMENTS**

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>Verify flow is within limits.</td>
<td>Once within 12 hours after $\geq 25%$ RTP</td>
</tr>
<tr>
<td></td>
<td>$\text{AND}$</td>
</tr>
<tr>
<td></td>
<td>24 hours thereafter</td>
</tr>
</tbody>
</table>

Example 1.4-2 has two Frequencies. The first is a one time performance Frequency, and the second is of the type shown in Example 1.4-1. The logical connector “AND” indicates that both Frequency requirements must be met. Each time reactor power is increased from a power level $< 25\%$ RTP to $\geq 25\%$ RTP, the Surveillance must be performed within 12 hours.

The use of “once” indicates a single performance will satisfy the specified Frequency (assuming no other Frequencies are connected by “AND”). This type of Frequency does not qualify for the extension allowed by SR 3.0.2. “Thereafter” indicates future performances must be established per SR 3.0.2, but only after a specified condition is first met (i.e., the “once” performance in this example). If reactor power decreases to $< 25\%$ RTP, the measurement of both intervals stops. New intervals start upon reactor power reaching 25% RTP.
EXAMPLE 1.4-3

SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>-------------</td>
<td>-----------</td>
</tr>
<tr>
<td>NOTE</td>
<td>7 days</td>
</tr>
</tbody>
</table>

Not required to be performed until 12 hours after $\geq 25\%$ RTP.

The interval continues, whether or not the unit operation is $< 25\%$ RTP between performances.

As the Note modifies the required performance of the Surveillance, it is construed to be part of the “specified Frequency.” Should the 7 day interval be exceeded while operation is $< 25\%$ RTP, this Note allows 12 hours after power reaches $\geq 25\%$ RTP to perform the Surveillance. The Surveillance is still considered to be performed within the “specified Frequency.” Therefore, if the Surveillance were not performed within the 7 day (plus the extension allowed by SR 3.0.2) interval, but operation was $< 25\%$ RTP, it would not constitute a failure of the SR or failure to meet the LCO. Also, no violation of SR 3.0.4 occurs when changing MODES, even with the 7 day Frequency not met, provided operation does not exceed 12 hours (plus the extension allowed by SR 3.0.2) with power $\geq 25\%$ RTP.

Once the unit reaches 25% RTP, 12 hours would be allowed for completing the Surveillance. If the Surveillance were not performed within this 12 hour interval (plus the extension allowed by SR 3.0.2), there would then be a failure to perform a Surveillance within the specified Frequency, and the provisions of SR 3.0.3 would apply.
EXAMPLE 1.4-4

SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>------------------------------------</td>
<td>---------------</td>
</tr>
<tr>
<td>------------------------------------</td>
<td>---------------</td>
</tr>
<tr>
<td>NOTE</td>
<td></td>
</tr>
<tr>
<td>Only required to be met in MODE 1.</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
</tr>
<tr>
<td>Verify leakage rates are within limits.</td>
<td>24 hours</td>
</tr>
</tbody>
</table>

Example 1.4-4 specifies that the requirements of this Surveillance do not have to be met until the unit is in MODE 1. The interval measurement for the Frequency of this Surveillance continues at all times, as described in Example 1.4-1. However, the Note constitutes an "otherwise stated" exception to the Applicability of this Surveillance. Therefore, if the Surveillance were not performed within the 24 hour interval (plus the extension allowed by SR 3.0.2), but the unit was not in MODE 1, there would be no failure of the SR nor failure to meet the LCO. Therefore, no violation of SR 3.0.4 occurs when changing MODES, even with the 24 hour Frequency exceeded, provided the MODE change was not made into MODE 1. Prior to entering MODE 1 (assuming again that the 24 hour Frequency were not met), SR 3.0.4 would require satisfying the SR.
EXAMPLES (continued)

EXAMPLE 1.4-5

SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>----------------------------------</td>
<td>-----------</td>
</tr>
<tr>
<td>NOTE -----------------------------</td>
<td>-----------</td>
</tr>
<tr>
<td>Only required to be performed in MODE 1.</td>
<td>7 days</td>
</tr>
<tr>
<td>----------------------------------</td>
<td>-----------</td>
</tr>
<tr>
<td>Perform complete cycle of the valve.</td>
<td>7 days</td>
</tr>
</tbody>
</table>

The interval continues, whether or not the unit operation is in MODE 1, 2, or 3 (the assumed Applicability of the associated LCO) between performances.

As the Note modifies the required performance of the Surveillance, the Note is construed to be part of the "specified Frequency." Should the 7 day interval be exceeded while operation is not in MODE 1, this Note allows entry into and operation in MODES 2 and 3 to perform the Surveillance. The Surveillance is still considered to be performed within the "specified Frequency" if completed prior to entering MODE 1. Therefore, if the Surveillance were not performed within the 7 day (plus the extension allowed by SR 3.0.2) interval, but operation was not in MODE 1, it would not constitute a failure of the SR or failure to meet the LCO. Also, no violation of SR 3.0.4 occurs when changing MODES, even with the 7 day Frequency not met, provided operation does not result in entry into MODE 1.

Once the unit reaches MODE 1, the requirement for the Surveillance to be performed within its specified Frequency applies and would require that the Surveillance had been performed. If the Surveillance were not performed prior to entering MODE 1, there would then be a failure to perform a Surveillance within the specified Frequency, and the provisions of SR 3.0.3 would apply.
EXAMPLE 1.4-6

SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>--------------</td>
<td>-----------</td>
</tr>
<tr>
<td>NOTE-----------</td>
<td>-----------</td>
</tr>
<tr>
<td>Not required to be met in MODE 3.</td>
<td>24 hours</td>
</tr>
<tr>
<td>--------------</td>
<td>-----------</td>
</tr>
</tbody>
</table>

Example 1.4-6 specifies that the requirements of this Surveillance do not have to be met while the unit is in MODE 3 (the assumed Applicability of the associated LCO is MODES 1, 2, and 3). The interval measurement for the Frequency of this Surveillance continues at all times, as described in Example 1.4-1. However, the Note constitutes an "otherwise stated" exception to the Applicability of this Surveillance. Therefore, if the Surveillance were not performed within the 24 hour interval (plus the extension allowed by SR 3.0.2), and the unit was in MODE 3, there would be no failure of the SR nor failure to meet the LCO. Therefore, no violation of SR 3.0.4 occurs when changing MODES to enter MODE 3, even with the 24 hour Frequency exceeded, provided the MODE change does not result in entry into MODE 2. Prior to entering MODE 2 (assuming again that the 24 hour Frequency were not met), SR 3.0.4 would require satisfying the SR.
2.0 SAFETY LIMITS (SLs)

2.1 SLs

2.1.1 Reactor Core SLs

2.1.1.1 In MODES 1 and 2, the departure from nucleate boiling ratio (DNBR) shall be maintained ≥ 1.29.

2.1.1.2 In MODES 1 and 2, the peak fuel centerline temperature shall be maintained at < 2,804.4°C (5,080°F), decreasing by 32.2°C (58°F) per 10,000 MWD/MTU for burnup and adjusted for burnable poison per CENPD-275-P, Revision 1-P-A.

2.1.2 Reactor Coolant System (RCS) Pressure SL

In MODES 1, 2, 3, 4 and 5, the RCS pressure shall be maintained ≤ 193.3 kg/cm²A (2,750 psia).

2.2 SL Violations

2.2.1 If SL 2.1.1.1 or SL 2.1.1.2 is violated, restore compliance and be in MODE 3 within 1 hour.

2.2.2 If SL 2.1.2 is violated:

2.2.2.1 In MODES 1 or 2, restore compliance and be in MODE 3 within 1 hour.

2.2.2.2 In MODES 3, 4, or 5, restore compliance within 5 minutes.
3.0 LIMITING CONDITION FOR OPERATION (LCO) APPLICABILITY

LCO 3.0.1  LCOs shall be met during the MODES or other specified Conditions in the Applicability, except as provided in LCOs 3.0.2, 3.0.7, 3.0.8, and 3.0.9.

LCO 3.0.2  Upon discovery of a failure to meet an LCO, the Required Actions of the associated Conditions shall be met, except as provided in LCOs 3.0.5 and 3.0.6.

If the LCO is met or is no longer applicable prior to expiration of the specified Completion Time(s), completion of the Required Action(s) is not required, unless otherwise stated.

LCO 3.0.3  When an LCO is not met and the associated ACTIONS are not met, an associated ACTION is not provided, or if directed by the associated ACTIONS, the unit shall be placed in a MODE or other specified Condition in which the LCO is not applicable. Action shall be initiated within 1 hour to place the unit, as applicable, in:

a.  MODE 3 within 7 hours,

b.  MODE 4 within 13 hours, and

c.  MODE 5 within 37 hours.

Exceptions to this Specification are stated in the individual Specifications.

Where corrective measures are completed that permit operation in accordance with the LCO or ACTIONS, completion of the actions required by LCO 3.0.3 is not required.

LCO 3.0.3 is only applicable in MODES 1, 2, 3, and 4.
3.0 LCO Applicability

LCO 3.0.4 When an LCO is not met, entry into a MODE or other specified Condition in the Applicability shall not be made except when the associated ACTIONS to be entered permit continued operation in the MODE or other specified Condition in the Applicability for an unlimited period of time.

This Specification shall not prevent changes in MODES or other specified conditions in the Applicability that are required to comply with ACTIONS or that are part of a shutdown of the unit. Exceptions to this Specification are stated in the individual Specifications. These exceptions allow entry into MODES or other specified Conditions in the Applicability when the associated ACTIONS to be entered allow unit operation in the MODE or other specified condition in the Applicability only for a limited period of time.

LCO 3.0.4 is only applicable for entry into a MODE or other specified Condition in the Applicability in MODES 1, 2, 3, and 4.

LCO 3.0.5 Equipment removed from service or declared inoperable to comply with ACTIONS may be returned to service under administrative control solely to perform testing required to demonstrate OPERABILITY or the OPERABILITY of other equipment. This is an exception to LCO 3.0.2 for the system returned to service under administrative control to perform the testing required to demonstrate OPERABILITY.

LCO 3.0.6 When a supported system LCO is not met solely due to a support system LCO not being met, the Conditions and Required Actions associated with this supported system are not required to be entered. Only the support system LCO ACTIONS are required to be entered. This is an exception to LCO 3.0.2 for the supported system. In this event, additional evaluations and limitations may be required in accordance with Subsection 5.5.15 of Technical Specification (TS), “Safety Function Determination Program (SFDP)”. If a loss of safety function is determined to exist by this program, the appropriate Conditions and Required Actions of the LCO in which the loss of safety function exists are required to be entered.

When a support system's Required Action directs a supported system to be declared inoperable or directs entry into Conditions and Required Actions for a supported system, the applicable Conditions and Required Actions shall be entered in accordance with LCO 3.0.2.
3.0 LCO Applicability

LCO 3.0.7 Special test exception (STE) LCOs in LCOs 3.1.9, 3.1.10 and 3.1.11 allow specified TS requirements to be changed to permit performance of special tests and operations. Unless otherwise specified, all other TS requirements remain unchanged. Compliance with STE LCOs is optional. When an STE LCO is desired to be met but is not met, the ACTIONS of the STE LCO shall be met. When an STE LCO is not desired to be met, entry into a MODE or other specified condition in the Applicability shall only be made in accordance with the other applicable Specifications.

LCO 3.0.8 When one or more required snubbers are unable to perform their associated support function(s), any affected supported LCO(s) are not required to be declared not met solely for this reason if risk is assessed and managed, and:

a. The snubbers not able to perform their associated support function(s) are associated with only one train or subsystem of a multiple train or subsystem supported system or are associated with a single train or subsystem supported system and are able to perform their associated support function within 72 hours, or

b. The snubbers not able to perform their associated support function(s) are associated with more than one train or subsystem of a multiple train or subsystem supported system and are able to perform their associated support function within 12 hours.

At the end of the specified period, the required snubbers must be able to perform their associated support function(s), or the affected supported system LCO(s) shall be declared not met.
3.0 LCO Applicability

LCO 3.0.9  

[When one or more required barriers are unable to perform their related support function(s), any supported system LCO(s) are not required to be declared not met solely for this reason for up to 30 days provided that at least one train or subsystem of the supported system is OPERABLE and supported by barriers capable of providing their LCO related support function(s), and risk is assessed and managed.

This specification may be concurrently applied to more than one train or subsystem of a multiple train or subsystem supported system provided at least one train or subsystem of the supported system is OPERABLE and the barriers supporting each of these trains or subsystems provide their related support function(s) for different categories of initiating events.

If the required OPERABLE train or subsystem becomes inoperable while this specification is in use, it must be restored to OPERABLE status within 24 hours or the provisions of this specification cannot be applied to the trains or subsystems supported by the barriers that cannot perform their related support function(s).

At the end of the specified period, the required barriers must be able to perform their related support function(s) or the supported system LCO(s) shall be declared not met.]
3.0 SURVEILLANCE REQUIREMENT (SR) APPLICABILITY

SR 3.0.1 SRs shall be met during the MODES or other specified Conditions in the Applicability for individual LCOs, unless otherwise stated in the SR. Failure to meet a Surveillance, whether such failure is experienced during the performance of the Surveillance or between performances of the Surveillance shall be failure to meet the LCO. Failure to perform a Surveillance within the specified Frequency shall be failure to meet the LCO, except as provided in SR 3.0.3. Surveillances do not have to be performed on inoperable equipment or variables outside specified limits.

SR 3.0.2 The specified Frequency for each SR is met if the Surveillance is performed within 1.25 times the interval specified in the Frequency, as measured from the previous performance or as measured from the time a specified condition of the Frequency is met.

For Frequencies specified as “once”, the above interval extension does not apply.

If a Completion Time requires periodic performance on a “once per...” basis, the above Frequency extension applies to each performance after the initial performance.

Exceptions to this Specification are stated in the individual Specifications.

SR 3.0.3 If it is discovered that a Surveillance was not performed within its specified Frequency, then compliance with the requirement to declare the LCO not met may be delayed, from the time of discovery, up to 24 hours or up to the limit of the specified Frequency, whichever is less. This delay period is permitted to allow performance of the Surveillance.

If the Surveillance is not performed within the delay period, the LCO must immediately be declared not met, and the applicable Condition(s) must be entered.

When the Surveillance is performed within the delay period and the Surveillance is not met, the LCO must immediately be declared not met, and the applicable Condition(s) must be entered.
3.0 SR APPLICABILITY

SR 3.0.4 Entry into a MODE or other specified Condition in the Applicability of an LCO shall only be made when the LCO’s Surveillances have been met within their specified Frequencies except as provided by SR 3.0.3. When an LCO is not met due to Surveillances not having been met, entry into a MODE or other specified Condition in the Applicability shall only be made in accordance with LCO 3.0.4.

This provision shall not prevent entry into MODES or other specified Conditions in the Applicability that are required to comply with ACTIONS or that are part of a shutdown of the unit.

SR 3.0.4 is only applicable for entry into a MODE or other specified Condition in the Applicability in MODES 1, 2, 3, and 4.
3.1 REACTIVITY CONTROL SYSTEMS

3.1.1 SHUTDOWN MARGIN (SDM)

LCO 3.1.1
a. SDM shall be within the limits specified in the COLR.

b. $k$ effective assuming the inserted control element assembly (CEA) of the highest worth is fully withdrawn ($k_{N-1}$) shall be < 0.99.

c. With reactor trip circuit breakers (RTCBs) closed: Reactor criticality shall not be achieved with shutdown group CEAs movement.

APPLICABILITY: MODES 3, 4 and 5.

### ACTIONS

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. SDM not within limits.</td>
<td>A.1 Initiate boration to restore SDM to within limit.</td>
<td>15 minutes</td>
</tr>
<tr>
<td>B. $k_{N-1}$ not within limit.</td>
<td>B.1 Vary CEA position to restore within limit.</td>
<td>15 minutes</td>
</tr>
<tr>
<td>OR</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Reactor criticality can be achieved by shutdown group CEA movement when RTCBs are closed.</td>
<td>B.2 Initiate boration to restore within limit.</td>
<td>15 minutes</td>
</tr>
</tbody>
</table>
### SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR  3.1.1.1  Verify SDM to be within the limits specified in the COLR.</td>
<td>24 hours</td>
</tr>
<tr>
<td>SR  3.1.1.2  Verify $k_{n-1} &lt; 0.99$.</td>
<td>24 hours</td>
</tr>
<tr>
<td>SR  3.1.1.3  Verify criticality cannot be achieved with shutdown group CEA movement when RTCBs are closed.</td>
<td>24 hours</td>
</tr>
</tbody>
</table>
3.1 REACTIVITY CONTROL SYSTEMS

3.1.2 Reactivity Balance

LCO 3.1.2 The core reactivity balance shall be within $\pm 1\% \Delta k/k$ of predicted values.

APPLICABILITY: MODES 1 and 2.

**ACTIONS**

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. Core reactivity balance not within limit.</td>
<td>A.1 Re-evaluate core design and safety analysis and determine that the reactor core is acceptable for continued operation. AND A.2 Establish appropriate operating restrictions and SRs for continued operation.</td>
<td>7 days 7 days</td>
</tr>
<tr>
<td>B. Required Action and associated Completion Time not met.</td>
<td>B.1 Be in MODE 3.</td>
<td>6 hours</td>
</tr>
</tbody>
</table>
### SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>SR 3.1.2.1</strong></td>
<td></td>
</tr>
<tr>
<td>1. The predicted reactivity values may be adjusted (normalized) to correspond to the measured core reactivity prior to exceeding a fuel burnup of 60 effective full power days (EFPD) after each fuel loading.</td>
<td></td>
</tr>
<tr>
<td>2. Not required to be performed prior to entry into MODE 2.</td>
<td></td>
</tr>
<tr>
<td>Verify overall core reactivity balance is within ± 1.0% $\Delta k/k$ of predicted values.</td>
<td>Prior to entering MODE 1 after fuel loading</td>
</tr>
<tr>
<td></td>
<td>AND</td>
</tr>
<tr>
<td></td>
<td>-------NOTE-------</td>
</tr>
<tr>
<td></td>
<td>Only required after 60 EFPD.</td>
</tr>
<tr>
<td></td>
<td>-------------------------</td>
</tr>
<tr>
<td></td>
<td>31 EFPD</td>
</tr>
</tbody>
</table>
3.1 REACTIVITY CONTROL SYSTEMS

3.1.3 Moderator Temperature Coefficient (MTC)

LCO 3.1.3 The MTC shall be maintained within the lower limit specified in the COLR and the upper limit that varies linearly from 0.9E-4 $\Delta$k/k$^\circ$C (0.5E-4 $\Delta$k/k$^\circ$F) at 0% RTP to 0.0 $\Delta$k/k$^\circ$C (0.0 $\Delta$k/k$^\circ$F) at 100% RTP.

APPLICABILITY: MODES 1 and 2.

ACTIONS

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. MTC not within limits.</td>
<td>A.1 Be in MODE 3.</td>
<td>6 hours</td>
</tr>
</tbody>
</table>

SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.1.3.1 Verify MTC is within the upper limit specified in LCO 3.1.3.</td>
<td>Prior to entering MODE 1 after each fuel loading</td>
</tr>
</tbody>
</table>
### SURVEILLANCE REQUIREMENTS (continued)

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.1.3.2</td>
<td></td>
</tr>
<tr>
<td><strong>--------------------------------NOTE--------------------------------</strong></td>
<td></td>
</tr>
<tr>
<td>If the MTC is more negative than the COLR limit when extrapolated to the end of cycle, SR 3.1.3.2 may be repeated. Shutdown must occur prior to exceeding the minimum allowable boron concentration at which MTC is projected to exceed the lower limit.</td>
<td></td>
</tr>
<tr>
<td><strong>------------------------------------------------------------------------</strong></td>
<td></td>
</tr>
<tr>
<td>Verify MTC is within the lower limit specified in the COLR.</td>
<td>Each fuel cycle within 7 effective full power days (EFPD) of reaching 40 EFPD core burnup AND Each fuel cycle within 7 EFPD of reaching 2/3 of expected core burnup</td>
</tr>
</tbody>
</table>
### 3.1 REACTIVITY CONTROL SYSTEMS

#### 3.1.4 Control Element Assembly (CEA) Alignment

**LCO 3.1.4**

All full strength (regulating and shutdown) CEAs shall be **OPERABLE**, _AND_ all full and part strength CEAs shall be aligned to within 16.8 cm (6.6 in) (indicated position) of their respective groups.

**APPLICABILITY:** MODES 1 and 2.

**ACTIONS**

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. One or more CEAs misaligned from its group by &gt; 16.8 cm (6.6 in) and ≤ 48.3 cm (19 in). OR One CEA misaligned from its group by &gt; 48.3 cm (19 in).</td>
<td>A.1 Reduce THERMAL POWER in accordance with Figure 3.1.4-1. AND A.2 Restore CEA Alignment.</td>
<td>1 hour 2 hours</td>
</tr>
</tbody>
</table>
### ACTIONS (continued)

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>B. Required Action and associated Completion Time of Condition A not met.</td>
<td>B.1 Be in MODE 3.</td>
<td>6 hours</td>
</tr>
<tr>
<td>OR</td>
<td>One or more full strength CEAs inoperable.</td>
<td></td>
</tr>
<tr>
<td>OR</td>
<td>Two or more CEAs misaligned by &gt; 48.3 cm (19 in).</td>
<td></td>
</tr>
</tbody>
</table>

### SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.1.4.1 Verify indicated position of each full and part strength CEA is within 16.8 cm (6.6 in) of all other CEAs in its group.</td>
<td>12 hours</td>
</tr>
<tr>
<td>SR 3.1.4.2 Verify that, for each CEA, its OPERABLE CEA position indicator channels indicate within 13.2 cm (5.2 in) of each other.</td>
<td>12 hours</td>
</tr>
<tr>
<td>SR 3.1.4.3 Verify full strength CEA freedom of movement (trippability) by moving each individual full strength CEA that is not fully inserted in the core at least 12.7 cm (5 in).</td>
<td>92 days</td>
</tr>
<tr>
<td>SR 3.1.4.4 Perform a CHANNEL FUNCTIONAL TEST of each reed switch position transmitter channel.</td>
<td>18 months</td>
</tr>
<tr>
<td>SURVEILLANCE</td>
<td>FREQUENCY</td>
</tr>
<tr>
<td>---------------</td>
<td>-----------</td>
</tr>
<tr>
<td>Verify each full strength CEA drop time from the fully withdrawn position to the 90% insertion position is ≤ 4 seconds.</td>
<td>Prior to reactor criticality, after each removal of the reactor head</td>
</tr>
</tbody>
</table>
When core power is reduced to 55% RTP per this limit curve, further reduction is not required by this Specification.

Figure 3.1.4-1 (page 1 of 1)
Required Power Reduction after CEA Deviation
3.1 REACTIVITY CONTROL SYSTEMS

3.1.5 Shutdown Control Element Assembly (CEA) Insertion Limits

LCO 3.1.5 All shutdown CEAs shall be withdrawn to \( \geq 367.7 \text{ cm (144.75 in)} \).

APPLICABILITY: MODE 1, MODE 2 with any regulating CEA not fully inserted.

---------------------------------------------NOTE---------------------------------------------
This LCO is not applicable while performing SR 3.1.4.3.

--------------------------------------------------------------------------------------------------

ACTIONS

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. One or more shutdown CEAs not within limit.</td>
<td>A.1 Restore shutdown CEA(s) to within limit.</td>
<td>2 hours</td>
</tr>
<tr>
<td>B. Required Action and associated Completion Time not met.</td>
<td>B.1 Be in MODE 3.</td>
<td>6 hours</td>
</tr>
</tbody>
</table>
SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.1.5.1</td>
<td>12 hours</td>
</tr>
<tr>
<td>Verify each shutdown CEA is withdrawn ≥ 367.7 cm (144.75 in).</td>
<td>AND</td>
</tr>
<tr>
<td>Once within 15 minutes prior to withdrawal of any CEA in regulating groups during an approach to reactor criticality</td>
<td></td>
</tr>
</tbody>
</table>
Regulating CEA Insertion Limits

3.1 REACTIVITY CONTROL SYSTEMS

3.1.6 Regulating Control Element Assembly (CEA) Insertion Limits

LCO 3.1.6 The power dependent insertion limit (PDIL) alarm circuit shall be OPERABLE, and

   a. With the Core Operating Limit Supervisory System (COLSS) in service, the regulating CEA groups shall be limited to the withdrawal sequence, insertion limits, and associated time restraints specified in the COLR.

   b. With COLSS out of service, the regulating CEA groups shall be limited to the withdrawal sequence, insertion limits, and associated time restraints specified in the COLR.

APPLICABILITY: MODES 1 and 2.

-------------------------------------------NOTE--------------------------------------------
This LCO is not applicable while conducting SR 3.1.4.3 or during reactor power cutback operation.
--------------------------------------------------------------------------------------------------

ACTIONS

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. Regulating CEA groups inserted beyond the transient insertion limit with COLSS in service.</td>
<td>A.1 Restore regulating CEA groups to within limits.</td>
<td>2 hours</td>
</tr>
<tr>
<td></td>
<td>OR</td>
<td></td>
</tr>
<tr>
<td></td>
<td>A.2 Reduce THERMAL POWER to less than or equal to the fraction of RTP allowed by the CEA group position and insertion limits specified in the COLR.</td>
<td>2 hours</td>
</tr>
<tr>
<td>CONDITION</td>
<td>REQUIRED ACTION</td>
<td>COMPLETION TIME</td>
</tr>
<tr>
<td>---------------------------------------------------------------------------</td>
<td>----------------------------------------------------------------------------------</td>
<td>-----------------</td>
</tr>
<tr>
<td>B. Regulating CEA groups inserted between the long term steady state</td>
<td>B.1 Verify short term steady state insertion limits are not exceeded.</td>
<td>15 minutes</td>
</tr>
<tr>
<td>insertion limit and the transient insertion limit for accumulated times</td>
<td><strong>OR</strong></td>
<td></td>
</tr>
<tr>
<td>&gt; 4 hours per 24 hour interval with COLSS in service.</td>
<td>B.2 Restrict increases in THERMAL POWER to ≤ 5% RTP per hour.</td>
<td>15 minutes</td>
</tr>
<tr>
<td>C. Regulating CEA groups inserted between the long term steady state</td>
<td>C.1 Restore regulating CEA groups to within long term steady state insertion limit.</td>
<td>2 hours</td>
</tr>
<tr>
<td>insertion limit and the transient insertion limit for accumulated times</td>
<td></td>
<td></td>
</tr>
<tr>
<td>&gt; 5 effective full power days (EFPD) per 30 EFPD interval or &gt; 14 EFPD</td>
<td></td>
<td></td>
</tr>
<tr>
<td>per 365 EFPD interval with COLSS in service.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>D. Regulating CEA groups inserted beyond the short term steady state</td>
<td>D.1 Restore regulating CEA groups to within limits.</td>
<td>2 hours</td>
</tr>
<tr>
<td>insertion limit with COLSS out of service.</td>
<td><strong>OR</strong></td>
<td></td>
</tr>
<tr>
<td></td>
<td>D.2 Reduce THERMAL POWER to less than or equal to the fraction of RTP allowed by</td>
<td>2 hours</td>
</tr>
<tr>
<td></td>
<td>the CEA group position and short term steady state insertion limit specified in</td>
<td></td>
</tr>
<tr>
<td></td>
<td>the COLR.</td>
<td></td>
</tr>
</tbody>
</table>
### ACTIONS (continued)

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>E. PDIL alarm circuit inoperable.</td>
<td>E.1 Perform SR 3.1.6.1.</td>
<td>1 hour AND Once per 4 hours thereafter</td>
</tr>
<tr>
<td>F. Required Action and associated Completion Time not met.</td>
<td>F.1 Be in MODE 3.</td>
<td>6 hours</td>
</tr>
</tbody>
</table>

### SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.1.6.1</td>
<td>12 hours</td>
</tr>
<tr>
<td>Verify each regulating CEA group position is within its insertion limits.</td>
<td></td>
</tr>
<tr>
<td>Note: Not required to be performed prior to entry into MODE 2.</td>
<td></td>
</tr>
<tr>
<td>SR 3.1.6.2</td>
<td>24 hours</td>
</tr>
<tr>
<td>Verify the accumulated times during which the regulating CEA groups are inserted beyond the steady state insertion limits but within the transient insertion limits.</td>
<td></td>
</tr>
<tr>
<td>SR 3.1.6.3</td>
<td>31 days</td>
</tr>
<tr>
<td>Verify PDIL alarm circuit is OPERABLE.</td>
<td></td>
</tr>
</tbody>
</table>
# Part Strength CEA Insertion Limits

## 3.1 REACTIVITY CONTROL SYSTEMS

### 3.1.7 Part Strength Control Element Assembly (CEA) Insertion Limits

**LCO 3.1.7** The part strength CEA groups shall be limited to the insertion limits specified in the COLR.

**APPLICABILITY:** MODE 1 with THERMAL POWER $> 20\%$ RTP.

---

**NOTE**

Not applicable while exercising the OPERABILITY test of part strength CEAs.

---

### ACTIONS

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. Part strength CEA groups inserted between the long term steady state insertion limit and the transient insertion limit for accumulated times $&gt; 7$ effective full power days (EFPD) per 30 EFPD interval or $&gt; 14$ EFPD per 365 EFPD interval.</td>
<td>A.1 Restore part strength CEA groups to within the long term steady state insertion limit.</td>
<td>2 hours</td>
</tr>
<tr>
<td>B. Required Action and associated Completion Time of Condition A not met.</td>
<td>B.1 Reduce THERMAL POWER to $\leq 20%$ RTP.</td>
<td>4 hours</td>
</tr>
</tbody>
</table>
## SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.1.7.1 Verify part strength CEA group position.</td>
<td>12 hours</td>
</tr>
<tr>
<td>SR 3.1.7.2 Verify the accumulated times during which the part strength CEA groups are inserted beyond the long term steady state insertion limit.</td>
<td>24 hours after insertion of part strength CEA groups beyond the long term steady state insertion limit <strong>AND</strong> 24 hours thereafter</td>
</tr>
</tbody>
</table>
3.1 REACTIVITY CONTROL SYSTEMS

3.1.8 Charging Flow

LCO 3.1.8 Charging flow shall be maintained below 681.4 L/min (180 gpm).

APPLICABILITY: MODES 1, 2, 3, 4, and 5.

ACTIONS

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. Charging flow ≥ 681.4 L/min (180 gpm).</td>
<td>A.1 Restore charging flow to &lt; 681.4 L/min (180 gpm).</td>
<td>Immediately</td>
</tr>
<tr>
<td></td>
<td>OR</td>
<td></td>
</tr>
<tr>
<td>A.2</td>
<td>Isolate the demineralized water supply to the Chemical and Volume Control System (CVCS).</td>
<td>Immediately</td>
</tr>
</tbody>
</table>

SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.1.8.1</td>
<td>12 hours</td>
</tr>
</tbody>
</table>
3.1 REACTIVITY CONTROL SYSTEMS

3.1.9 Special Test Exception (STE) – SHUTDOWN MARGIN (SDM)

LCO 3.1.9 During performance of criticality test or measurement of control element assembly (CEA) worth and SDM, the requirements of:

- LCO 3.1.1, “SHUTDOWN MARGIN (SDM),”
- LCO 3.1.5, “Shutdown Control Element Assembly (CEA) Insertion Limits”,
- LCO 3.1.6, “Regulating Control Element Assembly (CEA) Insertion Limits,”
- LCO 3.3.1, “Reactor Protection System (RPS) Instrumentation – Operating” (Only applied to Trip Functions 2, 14, and 15 in Table 3.3.1-1), and
- LCO 3.3.2, “Reactor Protection System (RPS) Instrumentation – Shutdown” (Only applied to Trip Function 1 in Table 3.3.2-1),

may be suspended, provided shutdown reactivity equivalent to at least the highest estimated CEA worth (of those CEAs actually withdrawn) is available for trip insertion or the reactor is subcritical by at least the reactivity equivalent of the highest CEA worth.

APPLICABILITY: MODES 2 and 3 during PHYSICS TESTS.

-------------------------------------------NOTE--------------------------------------------
Operation in MODE 3 shall be limited to 6 consecutive hours.
--------------------------------------------------------------------------------------------------
### ACTIONS

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. Any full strength CEA not fully inserted and less than the required shutdown reactivity available for trip insertion.</td>
<td>A.1 Initiate boration to restore required shutdown reactivity.</td>
<td>15 minutes</td>
</tr>
<tr>
<td>OR</td>
<td></td>
<td></td>
</tr>
<tr>
<td>All full strength CEAs inserted and the reactor subcritical by less than the above required shutdown reactivity equivalent.</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

### SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.1.9.1</td>
<td>2 hours</td>
</tr>
</tbody>
</table>

- Verify position of each CEA not fully inserted is within the acceptance criteria for available negative reactivity addition.

----------NOTE----------
Not required to be performed during initial power escalation following a refueling outage if SR 3.1.4.5 has been met.

----------

- Verify each full strength CEA not fully inserted is capable of full insertion when tripped from at least the 50% withdrawn position.

Within 24 hours prior to reducing SDM to less than the limits of LCO 3.1.1.
### SURVEILLANCE REQUIREMENTS (continued)

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.1.9.3</td>
<td>2 hours</td>
</tr>
<tr>
<td>--------------</td>
<td>-----------</td>
</tr>
<tr>
<td><strong>NOTE</strong> Applicable to operation in MODE 3 only.</td>
<td></td>
</tr>
<tr>
<td>Verify that when all full strength CEAs are fully inserted, the reactor is subcritical by more than the above required shutdown reactivity equivalent.</td>
<td></td>
</tr>
<tr>
<td>SR 3.1.9.4</td>
<td>Within 12 hours prior to initiation of reactor startup or PHYSICS TESTS</td>
</tr>
<tr>
<td>Perform CHANNEL FUNCTIONAL TESTS of each logarithmic and variable overpower neutron flux monitoring channel.</td>
<td></td>
</tr>
</tbody>
</table>
3.1 REACTIVITY CONTROL SYSTEMS

3.1.10 Special Test Exception (STE) – MODES 1 and 2

LCO 3.1.10 During performance of PHYSICS TESTS, the requirements of:

LCO 3.1.3, “Moderator Temperature Coefficient (MTC),”
LCO 3.1.4, “Control Element Assembly (CEA) Alignment,”
LCO 3.1.5, “Shutdown Control Element Assembly (CEA) Insertion Limits,”
LCO 3.1.6, “Regulating Control Element Assembly (CEA) Insertion Limits,”
LCO 3.1.7, “Part Strength CEA Insertion Limits,”
LCO 3.2.2, “Planar Radial Peaking Factors (F_{xy}),”
LCO 3.2.3, “AZIMUTHAL POWER TILT (T_a),” and
LCO 3.2.5, “AXIAL SHAPE INDEX (ASI),”

may be suspended, provided THERMAL POWER is restricted to the test power plateau, which shall not exceed 85% RTP.

APPLICABILITY: MODES 1 and 2 during PHYSICS TESTS.

ACTIONS

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. Test power plateau exceeded.</td>
<td>A.1 Reduce THERMAL POWER to less than or equal to the test power plateau.</td>
<td>15 minutes</td>
</tr>
<tr>
<td>B. Required Action and associated Completion Time not met.</td>
<td>B.1 Suspend PHYSICS TESTS.</td>
<td>1 hour</td>
</tr>
</tbody>
</table>
### SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.1.10.1: Verify THERMAL POWER equal to or less than the test power plateau.</td>
<td>1 hour</td>
</tr>
</tbody>
</table>
3.1 REACTIVITY CONTROL SYSTEMS

3.1.11 Special Test Exception (STE) – Reactivity Coefficient Testing

LCO 3.1.11 During performance of PHYSICS TESTS, the requirements of:

LCO 3.1.6, “Regulating Control Element Assembly (CEA) Insertion Limits,”
LCO 3.1.7, “Part Strength CEA Insertion Limits,” and
LCO 3.4.1, “RCS Pressure, Temperature and Flow limits” (LCOs 3.4.1.b and 3.4.1.c, RCS Cold Leg Temperature only),

may be suspended, provided Linear Heat Rate (LHR) and Departure from Nucleate Boiling Ratio (DNBR) do not exceed the limits specified in:

LCO 3.2.1, “Linear Heat Rate (LHR),” and
LCO 3.2.4, “Departure from Nucleate Boiling Ratio (DNBR).”

APPLICABILITY: MODE 1 with THERMAL POWER > 20% RTP.

ACTIONS

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. LHR or DNBR not within limits.</td>
<td>A.1 Reduce THERMAL POWER to restore LHR and DNBR to within limits.</td>
<td>15 minutes</td>
</tr>
<tr>
<td>B. Required Action and associated Completion Time not met.</td>
<td>B.1 Suspend PHYSICS TESTS.</td>
<td>1 hour</td>
</tr>
<tr>
<td>SURVEILLANCE REQUIREMENTS</td>
<td></td>
<td></td>
</tr>
<tr>
<td>---------------------------</td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>SURVEILLANCE</strong></td>
<td><strong>FREQUENCY</strong></td>
<td></td>
</tr>
<tr>
<td><strong>SR 3.1.11.1</strong></td>
<td>15 minutes</td>
<td></td>
</tr>
<tr>
<td>-----------------</td>
<td>------------</td>
<td></td>
</tr>
<tr>
<td>Only required to be performed when Core Operating Limits Supervisory System (COLSS) is out of service. With COLSS in service, LHR is continuously monitored.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Verify LHR, as indicated on any OPERABLE Core Protection Calculator local power density channel, is within the limit specified in the COLR.</td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>SR 3.1.11.2</strong></td>
<td>15 minutes</td>
<td></td>
</tr>
<tr>
<td>-----------------</td>
<td>------------</td>
<td></td>
</tr>
<tr>
<td>Only required to be performed when COLSS is out of service. With COLSS in service, DNBR is continuously monitored.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Verify DNBR, as indicated on any OPERABLE Core Protection Calculator DNBR channel, is within the limits of Figure 3.2.4-2 or Figure 3.2.4-3 of the COLR, as applicable.</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
3.1 REACTIVITY CONTROL SYSTEMS

3.1.12 Unborated Water Source Isolation Valve – MODES 4 and 5

LCO 3.1.12 The CV-186 valve used to isolate unborated water sources shall be secured in the closed position.

APPLICABILITY: MODES 4 and 5 with all RCPs idle.

ACTIONS

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. Valve not secured in closed position.</td>
<td>A.1 Suspend all operations involving positive reactivity changes.</td>
<td>Immediately</td>
</tr>
<tr>
<td>AND</td>
<td>A.2 Initiate actions to secure valve in closed position.</td>
<td>Immediately</td>
</tr>
<tr>
<td>AND</td>
<td>A.3 Perform SDM verification in accordance with SR 3.1.1.1.</td>
<td>4 hours</td>
</tr>
</tbody>
</table>

SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.1.12.1</td>
<td>12 hours</td>
</tr>
</tbody>
</table>
3.2 POWER DISTRIBUTION LIMITS

3.2.1 Linear Heat Rate (LHR)

LCO 3.2.1 LHR shall not exceed the limit specified in the COLR.

APPLICABILITY: MODE 1 with THERMAL POWER > 20% RTP.

ACTIONS

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. Core Operating Limit Supervisory System (COLSS) calculated core power exceeds the COLSS calculated core power operating limit based on LHR.</td>
<td>A.1 Restore LHR to within limit.</td>
<td>1 hour</td>
</tr>
<tr>
<td>B. One OPERABLE core protection calculator (CPC) calculated LHR not within region of acceptable operation when the COLSS is out of service.</td>
<td>B.1 Determine trend in LHR. AND B.2.1 With an adverse trend, restore LHR to within limit. OR B.2.2 With no adverse trend, restore LHR to within limit.</td>
<td>Once per 15 minutes 1 hour 4 hours</td>
</tr>
<tr>
<td>C. Required Action and associated Completion Time not met.</td>
<td>C.1 Reduce THERMAL POWER to ≤ 20% RTP.</td>
<td>6 hours</td>
</tr>
</tbody>
</table>
SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
</table>
| **SR 3.2.1.1**  
Only required to be met when COLSS is out of service. With COLSS in service, LHR is continuously monitored.  
Verify LHR, as indicated on any OPERABLE local power density channel, is within its limit. | 2 hours   |
| SR 3.2.1.2  
Verify COLSS margin alarm actuates at a THERMAL POWER equal to or less than the core power operating limit based on LHR. | 31 days   |
3.2 POWER DISTRIBUTION LIMITS

3.2.2 Planar Radial Peaking Factors \( F_{xy} \)

LCO 3.2.2  The measured planar radial peaking factors \( F_{xy}^M \) shall be equal to or less than the planar radial peaking factors \( F_{xy}^C \) used in the Core Operating Limit Supervisory System (COLSS) and in the core protection calculators (CPCs).

APPLICABILITY:  MODE 1 with THERMAL POWER > 20% RTP.

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. ( F_{xy}^M &gt; F_{xy}^C ).</td>
<td>A.1.1 Adjust addressable CPC constants to increase the multiplier applied to planar radial peaking by a factor ( \geq \frac{F_{xy}^M}{F_{xy}^C} ).</td>
<td>6 hours</td>
</tr>
<tr>
<td></td>
<td>AND</td>
<td></td>
</tr>
<tr>
<td></td>
<td>A.1.2 Maintain a margin to the COLSS operating limits of ( \left(\frac{F_{xy}^M}{F_{xy}^C} - 1.0\right) \times 100% ).</td>
<td>6 hours</td>
</tr>
<tr>
<td></td>
<td>OR</td>
<td></td>
</tr>
<tr>
<td></td>
<td>A.2 Adjust affected ( F_{xy}^C ) used in the COLSS and CPCs to a value greater than or equal to the measured ( F_{xy}^M ).</td>
<td>6 hours</td>
</tr>
<tr>
<td></td>
<td>OR</td>
<td></td>
</tr>
<tr>
<td></td>
<td>A.3 Reduce THERMAL POWER to ( \leq 20% ) RTP.</td>
<td>6 hours</td>
</tr>
</tbody>
</table>
### SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.2.2.1 Verify measured $F_{xy}^M$ obtained using the Incore Detector System is equal to or less than the value of calculated $F_{xy}^C$ used in COLSS and CPCs.</td>
<td>Once after each fuel loading with THERMAL POWER &gt; 40% RTP but prior to operations above 80% RTP AND 31 effective full power days (EFPD) thereafter</td>
</tr>
</tbody>
</table>
### 3.2 POWER DISTRIBUTION LIMITS

#### 3.2.3 AZIMUTHAL POWER TILT (T_q)

**LCO 3.2.3** The measured T_q shall be less than or equal to the T_q allowance used in the core protection calculators (CPCs).

**APPLICABILITY:** MODE 1 with THERMAL POWER > 20% RTP.

**ACTIONS**

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. Measured T_q greater than allowance used in CPCs and ≤ 0.10.</td>
<td>A.1 Restore measured T_q. OR A.2 Adjust the T_q allowance in the CPCs to greater than or equal to the measured value.</td>
<td>2 hours</td>
</tr>
</tbody>
</table>

---

**B. Measured T_q > 0.10.**

------------------------NOTE------------------------

All subsequent Required Actions must be completed if power reduction commences prior to restoring T_q to ≤ 0.10.

------------------------NOTE------------------------

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>B.1 Reduce THERMAL POWER to ≤ 50% RTP. AND B.2 Reduce variable overpower trip (VOPT) setpoints to ≤ 55% RTP.</td>
<td></td>
<td>4 hours AND 8 hours</td>
</tr>
</tbody>
</table>
### ACTIONS (continued)

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>B. (continued)</td>
<td>B.3 Restore the measured $T_q$ to less than the $T_q$ allowance used in the CPCs.</td>
<td>Prior to increasing THERMAL POWER</td>
</tr>
<tr>
<td></td>
<td></td>
<td>--------\NOTE--------\</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Correct the cause of the out of limit condition prior to increasing THERMAL POWER.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Subsequent power operation &gt; 50% RTP may proceed provided that the measured $T_q$ is verified $\leq 0.10$ at least once per hour for 12 hours, or until verified at $\geq 95%$ RTP.</td>
</tr>
<tr>
<td>C. Required Actions and associated Completion Times not met.</td>
<td>C.1 Reduce THERMAL POWER to $\leq 20%$ RTP.</td>
<td>6 hours</td>
</tr>
</tbody>
</table>

### SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.2.3.1</td>
<td></td>
</tr>
<tr>
<td></td>
<td>--------\NOTE--------\</td>
</tr>
<tr>
<td></td>
<td>Only applicable when Core Operating Limits Supervisory System (COLSS) is out of service. With COLSS in service, this parameter is continuously monitored.</td>
</tr>
<tr>
<td></td>
<td>--------------------------\</td>
</tr>
<tr>
<td></td>
<td>Calculate $T_q$ and verify it is within the limit.</td>
</tr>
<tr>
<td></td>
<td>12 hours</td>
</tr>
</tbody>
</table>

---
### SURVEILLANCE REQUIREMENTS (continued)

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.2.3.2</td>
<td>Verify COLSS azimuthal tilt alarm is actuated at a $T_q$ value less than the $T_q$ value used in the CPCs.</td>
</tr>
<tr>
<td>SR 3.2.3.3</td>
<td>Independently confirm the validity of the COLSS calculated $T_q$ by use of the incore detectors.</td>
</tr>
</tbody>
</table>
3.2  POWER DISTRIBUTION LIMITS

3.2.4  Departure from Nucleate Boiling Ratio (DNBR)

LCO 3.2.4  The DNBR shall be maintained by one of the following methods:

a.  Core Operating Limit Supervisory System (COLSS) In Service:

1.  Maintaining COLSS calculated core power less than or equal to COLSS calculated core power operating limit based on DNBR when at least one control element assembly calculator (CEAC) is OPERABLE in each OPERABLE core protection calculator (CPC) channel; or

2.  Maintaining COLSS calculated core power less than or equal to COLSS calculated core power operating limit based on DNBR decreased by the allowance specified in Figure 3.2.4-1 of the COLR when the CEAC requirements of LCO 3.2.4.a.1 are not met.

b.  COLSS Out of Service:

1.  Operating within the region of acceptable operation of Figure 3.2.4-2 specified in the COLR using any OPERABLE CPC channel when at least one CEAC is OPERABLE in each OPERABLE CPC channel; or

2.  Operating within the region of acceptable operation of Figure 3.2.4-3 specified in the COLR using any OPERABLE CPC channel (with both CEACs inoperable) when the CEAC requirements of LCO 3.2.4.b.1 are not met.

APPLICABILITY:  MODE 1 with THERMAL POWER > 20% RTP.

ACTIONS

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. COLSS calculated core power not within limit.</td>
<td>A.1 Restore DNBR to within limit.</td>
<td>1 hour</td>
</tr>
</tbody>
</table>

APR1400 GTS 3.2.4-1 Rev. 3
### ACTIONS (continued)

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>B. DNBR outside the region of acceptable operation when COLSS is out of service.</strong></td>
<td><strong>B.1</strong> Determine trend in DNBR. AND <strong>B.2.1</strong> With an adverse trend, restore DNBR to within limit. <strong>OR</strong> <strong>B.2.2</strong> With no adverse trend, restore DNBR to within limit.</td>
<td><strong>Once per 15 minutes</strong> <strong>1 hour</strong> <strong>4 hours</strong></td>
</tr>
<tr>
<td><strong>C. Required Action and associated Completion Time not met.</strong></td>
<td><strong>C.1</strong> Reduce THERMAL POWER to $\leq 20%$ RTP.</td>
<td><strong>6 hours</strong></td>
</tr>
</tbody>
</table>

### SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>SR 3.2.4.1</strong></td>
<td>---------------------------------NOTE---------------------------------- Only applicable when COLSS is out of service. With COLSS in service, this parameter is continuously monitored.</td>
</tr>
<tr>
<td></td>
<td>Verify DNBR, as indicated on any OPERABLE DNBR channel, is within the limits of Figure 3.2.4-2 or 3.2.4-3 of the COLR, as applicable.</td>
</tr>
<tr>
<td><strong>SR 3.2.4.2</strong></td>
<td>Verify COLSS margin alarm actuates at a THERMAL POWER level equal to or less than the core power operating limit based on DNBR.</td>
</tr>
</tbody>
</table>
3.2 POWER DISTRIBUTION LIMITS

3.2.5 AXIAL SHAPE INDEX (ASI)

LCO 3.2.5 ASI shall be within the limits specified in the COLR.

APPLICABILITY: MODE 1 with THERMAL POWER > 20% RTP.

ACTIONS

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. Core average ASI not within limits.</td>
<td>A.1 Restore ASI to within limits.</td>
<td>2 hours</td>
</tr>
<tr>
<td>B. Required Action and associated Completion Time not met.</td>
<td>B.1 Reduce THERMAL POWER to ≤ 20% RTP.</td>
<td>4 hours</td>
</tr>
</tbody>
</table>

SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.2.5.1 Verify ASI is within limits.</td>
<td>12 hours</td>
</tr>
</tbody>
</table>
3.3 INSTRUMENTATION

3.3.1 Reactor Protection System (RPS) Instrumentation – Operating

LCO 3.3.1 Four RPS trip and associated automatic operating bypass removal channels for each Function in Table 3.3.1-1 shall be OPERABLE.

APPLICABILITY: According to Table 3.3.1-1.

ACTIONS

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. One or more Functions with one automatic RPS trip channel inoperable.</td>
<td>A.1 Place trip channel in bypass or trip.</td>
<td>1 hour</td>
</tr>
<tr>
<td>AND</td>
<td>A.2 Restore trip channel to OPERABLE status.</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Prior to entering MODE 2 following next MODE 5 entry</td>
<td></td>
</tr>
<tr>
<td>B. One or more Functions with two automatic RPS trip channels inoperable.</td>
<td>B.1 Place one trip channel in bypass and the other in trip.</td>
<td>1 hour</td>
</tr>
<tr>
<td>CONDITION</td>
<td>REQUIRED ACTION</td>
<td>COMPLETION TIME</td>
</tr>
<tr>
<td>-----------</td>
<td>-----------------</td>
<td>-----------------</td>
</tr>
<tr>
<td>C. One or more Functions with one automatic operating bypass removal channel inoperable.</td>
<td>C.1 Disable affected bypass channel.</td>
<td>1 hour</td>
</tr>
<tr>
<td></td>
<td>OR</td>
<td></td>
</tr>
<tr>
<td></td>
<td>C.2.1 Place affected automatic trip channel in bypass or trip.</td>
<td>1 hour</td>
</tr>
<tr>
<td></td>
<td>AND</td>
<td></td>
</tr>
<tr>
<td></td>
<td>C.2.2 Restore automatic operating bypass removal channel and associated automatic trip channel to OPERABLE status.</td>
<td>Prior to entering MODE 2 following next MODE 5 entry</td>
</tr>
<tr>
<td>D. One or more Functions with two automatic operating bypass removal channels inoperable.</td>
<td>D.1 Disable affected bypass channels.</td>
<td>1 hour</td>
</tr>
<tr>
<td></td>
<td>OR</td>
<td></td>
</tr>
<tr>
<td></td>
<td>D.2 Place one affected automatic trip channel in bypass and place the other in trip.</td>
<td>1 hour</td>
</tr>
<tr>
<td>E. Required Action and associated Completion Time not met.</td>
<td>E.1 Be in MODE 3.</td>
<td>6 hours</td>
</tr>
</tbody>
</table>
### SURVEILLANCE REQUIREMENTS

Refer to Table 3.3.1-1 to determine which SR shall be performed for each RPS Function.

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>SR 3.3.1.1</strong></td>
<td>Perform CHANNEL CHECK of each RPS instrument channel.</td>
</tr>
<tr>
<td><strong>SR 3.3.1.2</strong></td>
<td>Not required to be performed until 12 hours after THERMAL POWER ≥ 80% RTP. Verify total Reactor Coolant System (RCS) flow rate indicated by each core protection calculator (CPC) is ≤ the RCS total flow rate. If necessary, adjust CPC addressable constant flow coefficients such that each CPC indicated flow is ≤ the RCS flow rate.</td>
</tr>
<tr>
<td><strong>SR 3.3.1.3</strong></td>
<td>Check CPC System event log.</td>
</tr>
<tr>
<td><strong>SR 3.3.1.4</strong></td>
<td>1. Not required to be performed until 12 hours after THERMAL POWER ≥ 15% RTP. 2. The daily power calibration may be suspended during PHYSICS TESTS, provided calibration is performed upon reaching each major test power plateau and prior to proceeding to next major test power plateau. Perform the daily power calibration by calculating the core THERMAL POWER from the daily secondary heat balance measurement (a calorimetric) and adjusting the linear power, CPC ΔT power, and CPC neutron flux power channels to agree with the calculated THERMAL POWER if any channel indicated more than 0.5% RTP less than the calculated THERMAL POWER.</td>
</tr>
</tbody>
</table>
### Surveillance Requirements (continued)

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.3.1.5</td>
<td>31 days</td>
</tr>
<tr>
<td>Not required to be performed until 12 hours after THERMAL POWER ≥ 80% RTP.</td>
<td></td>
</tr>
<tr>
<td>Verify total RCS flow rate indicated by each CPC is less than or equal to RCS flow rate determined by secondary calorimetric calculations.</td>
<td></td>
</tr>
</tbody>
</table>

| SR 3.3.1.6    | 31 days   |
| Not required to be performed until 12 hours after THERMAL POWER ≥ 15% RTP. |
| Verify linear power subchannel gains of excore neutron detectors are consistent with values used to establish shape annealing matrix elements in the CPCs. |

<table>
<thead>
<tr>
<th>SR 3.3.1.7</th>
<th>31 days</th>
</tr>
</thead>
<tbody>
<tr>
<td>1. The CPC CHANNEL FUNCTIONAL TEST shall include verification that the correct values of addressable constants are installed in each OPERABLE CPC.</td>
<td></td>
</tr>
<tr>
<td>2. Not required to be performed for Logarithmic Power Level – High until 2 hours after reducing logarithmic power below 1E-3% and only if reactor trip circuit breakers (RTCBs) are open.</td>
<td></td>
</tr>
<tr>
<td>Perform CHANNEL FUNCTIONAL TEST for each RPS instrumentation channel in accordance with the Setpoint Control Program.</td>
<td></td>
</tr>
</tbody>
</table>
### SURVEILLANCE REQUIREMENTS (continued)

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.3.1.8</td>
<td>![NOTE](Excore neutron detectors are excluded from CHANNEL CALIBRATION.)</td>
</tr>
<tr>
<td>SR 3.3.1.9</td>
<td>![NOTE](Excore neutron detectors are excluded from CHANNEL CALIBRATION.)</td>
</tr>
<tr>
<td>SR 3.3.1.10</td>
<td>Perform CHANNEL FUNCTIONAL TEST on each CPC channel in accordance with the Setpoint Control Program.</td>
</tr>
<tr>
<td>SR 3.3.1.11</td>
<td>Using incore detectors, verify shape annealing matrix elements to be used by the CPCs in accordance with the Setpoint Control Program.</td>
</tr>
<tr>
<td>SR 3.3.1.12</td>
<td>Perform CHANNEL FUNCTIONAL TEST on each automatic operating bypass removal channel.</td>
</tr>
<tr>
<td>SURVEILLANCE REQUIREMENTS (continued)</td>
<td></td>
</tr>
<tr>
<td>--------------------------------------</td>
<td></td>
</tr>
<tr>
<td>SURVEILLANCE</td>
<td>FREQUENCY</td>
</tr>
<tr>
<td>------------</td>
<td>-----------</td>
</tr>
<tr>
<td>SR 3.3.1.13</td>
<td>18 months on a STAGGERED TEST BASIS</td>
</tr>
<tr>
<td>Note: Excore neutron detectors are excluded.</td>
<td></td>
</tr>
<tr>
<td>Verify RPS RESPONSE TIME is within limits.</td>
<td></td>
</tr>
</tbody>
</table>

---

RPS Instrumentation - Operating
3.3.1
<table>
<thead>
<tr>
<th>FUNCTION</th>
<th>APPLICABLE MODES OR OTHER SPECIFIED CONDITION</th>
<th>SURVEILLANCE REQUIREMENTS</th>
</tr>
</thead>
<tbody>
<tr>
<td>1. Variable Overpower</td>
<td>1, 2</td>
<td>SR 3.3.1.1</td>
</tr>
<tr>
<td></td>
<td></td>
<td>SR 3.3.1.4</td>
</tr>
<tr>
<td></td>
<td></td>
<td>SR 3.3.1.6</td>
</tr>
<tr>
<td></td>
<td></td>
<td>SR 3.3.1.7</td>
</tr>
<tr>
<td></td>
<td></td>
<td>SR 3.3.1.8</td>
</tr>
<tr>
<td></td>
<td></td>
<td>SR 3.3.1.9</td>
</tr>
<tr>
<td></td>
<td></td>
<td>SR 3.3.1.13</td>
</tr>
<tr>
<td>2. Logarithmic Power Level – High(^{(a)})</td>
<td>2</td>
<td>SR 3.3.1.1</td>
</tr>
<tr>
<td></td>
<td></td>
<td>SR 3.3.1.7</td>
</tr>
<tr>
<td></td>
<td></td>
<td>SR 3.3.1.9</td>
</tr>
<tr>
<td></td>
<td></td>
<td>SR 3.3.1.12</td>
</tr>
<tr>
<td></td>
<td></td>
<td>SR 3.3.1.13</td>
</tr>
<tr>
<td>3. Pressurizer Pressure – High</td>
<td>1, 2</td>
<td>SR 3.3.1.1</td>
</tr>
<tr>
<td></td>
<td></td>
<td>SR 3.3.1.7</td>
</tr>
<tr>
<td></td>
<td></td>
<td>SR 3.3.1.9</td>
</tr>
<tr>
<td></td>
<td></td>
<td>SR 3.3.1.13</td>
</tr>
<tr>
<td>4. Pressurizer Pressure – Low(^{(b)})</td>
<td>1, 2</td>
<td>SR 3.3.1.1</td>
</tr>
<tr>
<td></td>
<td></td>
<td>SR 3.3.1.7</td>
</tr>
<tr>
<td></td>
<td></td>
<td>SR 3.3.1.9</td>
</tr>
<tr>
<td></td>
<td></td>
<td>SR 3.3.1.12</td>
</tr>
<tr>
<td></td>
<td></td>
<td>SR 3.3.1.13</td>
</tr>
</tbody>
</table>

(a) Trip may be bypassed when logarithmic power is > 1E-3%. Operating bypass shall be automatically removed when logarithmic power is ≤ 1E-3%. Trip may be manually bypassed during PHYSICS TESTS pursuant to LCO 3.1.9, “Special Test Exception (STE) – SHUTDOWN MARGIN (SDM).”

(b) Pressurizer Pressure – Low trip setpoint may be decreased as pressurizer pressure is reduced to 7.0 kg/cm\(^2\) (100 psia). The margin between pressurizer pressure and the setpoint shall be maintained at ≤ 28.1 kg/cm\(^2\) (400 psi). The operating bypass shall be removed automatically at ≥ 35.2 kg/cm\(^2\) (500 psia). The setpoint shall be increased automatically to the normal setpoint as pressurizer pressure is increased.
Table 3.3.1-1 (Page 2 of 4)
Reactor Protection System Instrumentation – Operating

<table>
<thead>
<tr>
<th>FUNCTION</th>
<th>APPLICABLE MODES OR OTHER SPECIFIED CONDITION</th>
<th>SURVEILLANCE REQUIREMENTS</th>
</tr>
</thead>
<tbody>
<tr>
<td>5. Containment Pressure – High</td>
<td>1, 2</td>
<td>SR 3.3.1.1, SR 3.3.1.7, SR 3.3.1.9, SR 3.3.1.13</td>
</tr>
<tr>
<td>6. Steam Generator #1 Pressure – Low</td>
<td>1, 2</td>
<td>SR 3.3.1.1, SR 3.3.1.7, SR 3.3.1.9, SR 3.3.1.13</td>
</tr>
<tr>
<td>7. Steam Generator #2 Pressure – Low</td>
<td>1, 2</td>
<td>SR 3.3.1.1, SR 3.3.1.7, SR 3.3.1.9, SR 3.3.1.13</td>
</tr>
<tr>
<td>8. Steam Generator #1 Water Level – Low</td>
<td>1, 2</td>
<td>SR 3.3.1.1, SR 3.3.1.7, SR 3.3.1.9, SR 3.3.1.13</td>
</tr>
<tr>
<td>9. Steam Generator #2 Water Level – Low</td>
<td>1, 2</td>
<td>SR 3.3.1.1, SR 3.3.1.7, SR 3.3.1.9, SR 3.3.1.13</td>
</tr>
<tr>
<td>10. Steam Generator #1 Water Level – High</td>
<td>1, 2</td>
<td>SR 3.3.1.1, SR 3.3.1.7, SR 3.3.1.9, SR 3.3.1.13</td>
</tr>
<tr>
<td>11. Steam Generator #2 Water Level – High</td>
<td>1, 2</td>
<td>SR 3.3.1.1, SR 3.3.1.7, SR 3.3.1.9, SR 3.3.1.13</td>
</tr>
</tbody>
</table>
### Table 3.3.1-1 (Page 3 of 4)
Reactor Protection System Instrumentation – Operating

<table>
<thead>
<tr>
<th>FUNCTION</th>
<th>APPLICABLE MODES OR OTHER SPECIFIED CONDITION</th>
<th>SURVEILLANCE REQUIREMENTS</th>
</tr>
</thead>
</table>
| 12. Reactor Coolant Flow, Steam Generator #1 – Low | 1, 2 | SR 3.3.1.1  
SR 3.3.1.7  
SR 3.3.1.9  
SR 3.3.1.13 |
| 13. Reactor Coolant Flow, Steam Generator #2 – Low | 1, 2 | SR 3.3.1.1  
SR 3.3.1.7  
SR 3.3.1.9  
SR 3.3.1.13 |
| 14. Local Power Density – High<sup>(c)(d)</sup> | 1, 2 | SR 3.3.1.1  
SR 3.3.1.2  
SR 3.3.1.3  
SR 3.3.1.4  
SR 3.3.1.5  
SR 3.3.1.7  
SR 3.3.1.9  
SR 3.3.1.10  
SR 3.3.1.11  
SR 3.3.1.12  
SR 3.3.1.13 |

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(c) Trip may be manually bypassed when logarithmic power is < 1E-4%. Operating bypass shall be automatically removed when logarithmic power is ≥ 1E-4%. During testing pursuant to LCO 3.1.9, trip may be bypassed below 5% RTP. Operating bypass shall be automatically removed when THERMAL POWER is > 5% RTP.

(d) The OPERABILITY of the Local Power Density – High and DNBR – Low Functions includes the CPC auxiliary trips.
<table>
<thead>
<tr>
<th>FUNCTION</th>
<th>APPLICABLE MODES OR OTHER SPECIFIED CONDITION</th>
<th>SURVEILLANCE REQUIREMENTS</th>
</tr>
</thead>
<tbody>
<tr>
<td>15. Departure From Nucleate Boiling Ratio (DNBR) – Low$^{(c)(d)}$</td>
<td>1, 2</td>
<td>SR 3.3.1.1</td>
</tr>
<tr>
<td></td>
<td></td>
<td>SR 3.3.1.2</td>
</tr>
<tr>
<td></td>
<td></td>
<td>SR 3.3.1.3</td>
</tr>
<tr>
<td></td>
<td></td>
<td>SR 3.3.1.4</td>
</tr>
<tr>
<td></td>
<td></td>
<td>SR 3.3.1.5</td>
</tr>
<tr>
<td></td>
<td></td>
<td>SR 3.3.1.7</td>
</tr>
<tr>
<td></td>
<td></td>
<td>SR 3.3.1.9</td>
</tr>
<tr>
<td></td>
<td></td>
<td>SR 3.3.1.10</td>
</tr>
<tr>
<td></td>
<td></td>
<td>SR 3.3.1.11</td>
</tr>
<tr>
<td></td>
<td></td>
<td>SR 3.3.1.12</td>
</tr>
<tr>
<td></td>
<td></td>
<td>SR 3.3.1.13</td>
</tr>
</tbody>
</table>

(c) Trip may be manually bypassed when logarithmic power is $< 1E-4\%$. Operating bypass shall be automatically removed when logarithmic power is $\geq 1E-4\%$. During testing pursuant to LCO 3.1.9, trip may be bypassed below 5% RTP. Operating bypass shall be automatically removed when THERMAL POWER is $> 5\%$ RTP.

(d) The OPERABILITY of the Local Power Density – High and DNBR – Low Functions includes the CPC auxiliary trips.
3.3 INSTRUMENTATION

3.3.2 Reactor Protection System (RPS) Instrumentation – Shutdown

LCO 3.3.2 Four RPS trip and associated automatic operating bypass removal channels for each Function in Table 3.3.2-1 shall be OPERABLE.

APPLICABILITY: According to Table 3.3.2-1.

ACTIONS

Separate Condition entry is allowed for each RPS Function.

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. One or more Functions with one automatic RPS trip channel inoperable.</td>
<td>A.1 Place trip channel in bypass or trip. AND A.2 Restore trip channel to OPERABLE status.</td>
<td>1 hour Prior to entering MODE 2 following next MODE 5 entry</td>
</tr>
<tr>
<td>B. One or more Functions with two automatic RPS trip channels inoperable.</td>
<td>B.1 Place one trip channel in bypass and the other in trip.</td>
<td>1 hour</td>
</tr>
<tr>
<td>CONDITION</td>
<td>REQUIRED ACTION</td>
<td>COMPLETION TIME</td>
</tr>
<tr>
<td>---------------------------------------------------------------------------</td>
<td>---------------------------------------------------------------------------------</td>
<td>------------------------------------------------------</td>
</tr>
<tr>
<td>C. One automatic operating bypass removal channel inoperable.</td>
<td>C.1 Disable affected bypass channel.</td>
<td>1 hour</td>
</tr>
<tr>
<td>OR</td>
<td>C.2.1 Place affected automatic trip channel in bypass or trip.</td>
<td>1 hour</td>
</tr>
<tr>
<td>AND</td>
<td>C.2.2 Restore automatic operating bypass removal channel and associated automatic trip channel to OPERABLE status.</td>
<td>Prior to entering MODE 2 following next MODE 5 entry</td>
</tr>
<tr>
<td>D. Two automatic operating bypass removal channels inoperable.</td>
<td>D.1 Disable affected bypass channels.</td>
<td>1 hour</td>
</tr>
<tr>
<td>OR</td>
<td>D.2 Place one affected automatic trip channel in bypass and place the other in trip.</td>
<td>1 hour</td>
</tr>
<tr>
<td>E. Required Action and associated Completion Time not met.</td>
<td>E.1 Open all reactor trip circuit breakers (RTCBs).</td>
<td>1 hour</td>
</tr>
</tbody>
</table>
SURVEILLANCE REQUIREMENTS

Refer to Table 3.3.2-1 to determine which SR shall be performed for each RPS Function.

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>SR 3.3.2.1</strong> Perform CHANNEL CHECK of each RPS instrument channel.</td>
<td>12 hours</td>
</tr>
<tr>
<td><strong>SR 3.3.2.2</strong> Perform CHANNEL FUNCTIONAL TEST on each RPS trip channel in accordance with the Setpoint Control Program.</td>
<td>31 days</td>
</tr>
<tr>
<td><strong>SR 3.3.2.3</strong> Perform CHANNEL FUNCTIONAL TEST on each automatic operating bypass removal function.</td>
<td>Once within 31 days prior to each reactor startup</td>
</tr>
<tr>
<td><strong>SR 3.3.2.4</strong> Neutron detectors are excluded from CHANNEL CALIBRATION. Perform CHANNEL CALIBRATION on each RPS trip channel, including automatic operating bypass removal function in accordance with the Setpoint Control Program.</td>
<td>18 months</td>
</tr>
<tr>
<td><strong>SR 3.3.2.5</strong> Verify RPS RESPONSE TIME is within limits.</td>
<td>18 months on a STAGGERED TEST BASIS</td>
</tr>
</tbody>
</table>
### Table 3.3.2-1 (Page 1 of 1)
Reactor Protection System Instrumentation – Shutdown

<table>
<thead>
<tr>
<th>FUNCTION</th>
<th>APPLICABLE MODES OR OTHER SPECIFIED CONDITION</th>
<th>SURVEILLANCE REQUIREMENTS</th>
</tr>
</thead>
<tbody>
<tr>
<td>1. Logarithmic Power Level – High&lt;sup&gt;(a)&lt;/sup&gt;</td>
<td>3&lt;sup&gt;(b)&lt;/sup&gt;, 4&lt;sup&gt;(b)&lt;/sup&gt;, 5&lt;sup&gt;(b)&lt;/sup&gt;</td>
<td>SR 3.3.2.1, SR 3.3.2.2, SR 3.3.2.3, SR 3.3.2.4, SR 3.3.2.5</td>
</tr>
<tr>
<td>2. Steam Generator Pressure #1 – Low&lt;sup&gt;(c)&lt;/sup&gt;</td>
<td>3&lt;sup&gt;(b)&lt;/sup&gt;, 4&lt;sup&gt;(b)&lt;/sup&gt;</td>
<td>SR 3.3.2.1, SR 3.3.2.2, SR 3.3.2.4, SR 3.3.2.5</td>
</tr>
<tr>
<td>3. Steam Generator Pressure #2 – Low&lt;sup&gt;(c)&lt;/sup&gt;</td>
<td>3&lt;sup&gt;(b)&lt;/sup&gt;, 4&lt;sup&gt;(b)&lt;/sup&gt;</td>
<td>SR 3.3.2.1, SR 3.3.2.2, SR 3.3.2.4, SR 3.3.2.5</td>
</tr>
</tbody>
</table>

---

(a) Trip may be bypassed when logarithmic power is > 1E-3%. Operating bypass shall be automatically removed when logarithmic power is ≤ 1E-3%.

(b) With any RTCBs closed, any control element assembly (CEA) capable of being withdrawn.

(c) Steam Generator Pressure – Low trip setpoint may be manually decreased as steam generator pressure is reduced in MODES 3 and 4, provided the margin between steam generator pressure and the setpoint is maintained at ≤ 14.1 kg/cm² (200 psi). The setpoint shall be increased automatically as steam generator pressure is increased.
3.3 INSTRUMENTATION

3.3.3 Control Element Assembly Calculators (CEACs)

LCO 3.3.3 Two CEACs shall be OPERABLE in each Core Protection Calculator System (CPCS) channel.

APPLICABILITY: MODES 1 and 2.

ACTIONS

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. One CEAC inoperable in one or more CPCS channels.</td>
<td>A.1 Declare affected CPCS channel(s) inoperable.</td>
<td>1 hour</td>
</tr>
<tr>
<td>OR</td>
<td>A.2.1 Verify indicated position of each full and part strength CEA is within 16.8 cm (6.6 in) of all other CEAs in its group.</td>
<td>1 hour AND Once per 4 hours thereafter</td>
</tr>
<tr>
<td>AND</td>
<td>A.2.2 Restore CEAC to OPERABLE status.</td>
<td>7 days</td>
</tr>
</tbody>
</table>
### ACTIONS (continued)

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>B. Required Action and associated Completion Time of Condition A not met.</td>
<td>B.1 Declare affected channel(s) inoperable.</td>
<td>1 hour</td>
</tr>
<tr>
<td>OR</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Both CEACs inoperable in one or more CPCS channels.</td>
<td>B.2.1 Verify indicated position of each full and part strength CEA is within 16.8 cm (6.6 in) of all other CEAs in its group.</td>
<td>1 hour</td>
</tr>
<tr>
<td>AND</td>
<td></td>
<td></td>
</tr>
<tr>
<td>B.2.2 Verify departure from nucleate boiling ratio requirement of LCO 3.2.4 is met and Reactor Power Cutback System (RPCS) is disabled.</td>
<td></td>
<td>Once per 4 hours thereafter</td>
</tr>
<tr>
<td>AND</td>
<td></td>
<td></td>
</tr>
<tr>
<td>B.2.3 Verify all full strength and part strength CEA groups are fully withdrawn and maintained fully withdrawn, except during Surveillance testing pursuant to SR 3.1.4.3, or for power control, when CEA group #5 may be inserted to a maximum of 323.9 cm (127.5 in).</td>
<td></td>
<td>4 hours</td>
</tr>
<tr>
<td>AND</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

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### ACTIONS (continued)

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>B. (continued)</td>
<td>B.2.4 Verify addressable constant in each affected CPC is set to indicate that both CEACs are inoperable and &quot;RSPT/CEAC inoperable&quot; status is indicated. <strong>AND</strong> B.2.5 Verify Digital Rod Control System (DRCS) is placed in &quot;standby&quot; and maintained in &quot;standby,&quot; except during CEA motion permitted by Required Action B.2.2.</td>
<td>4 hours</td>
</tr>
<tr>
<td>C. Required Action and associated Completion Time of Condition B not met.</td>
<td>C.1 Be in MODE 3.</td>
<td>6 hours</td>
</tr>
</tbody>
</table>

### SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.3.3.1</td>
<td>Perform CHANNEL CHECK.</td>
</tr>
<tr>
<td>SR 3.3.3.2</td>
<td>Check CPC System event log.</td>
</tr>
<tr>
<td>SR 3.3.3.3</td>
<td>Perform CHANNEL FUNCTIONAL TEST.</td>
</tr>
<tr>
<td>SR 3.3.3.4</td>
<td>Perform CHANNEL CALIBRATION in accordance with the Setpoint Control Program</td>
</tr>
<tr>
<td>SURVEILLANCE REQUIREMENTS (continued)</td>
<td>SURVEILLANCE</td>
</tr>
<tr>
<td>--------------------------------------</td>
<td>--------------</td>
</tr>
<tr>
<td>SR 3.3.3.5</td>
<td>Perform CHANNEL FUNCTIONAL TEST in accordance with the Setpoint Control Program (including annunciation and trip function test).</td>
</tr>
</tbody>
</table>
3.3 INSTRUMENTATION

3.3.4 Reactor Protection System (RPS) Logic and Trip Initiation

LCO 3.3.4 Four RPS logic channels (Coincidence, Initiation Logic), four channels of reactor trip circuit breakers (RTCBs), and four channels of Manual Trip shall be OPERABLE.

APPLICABILITY: MODES 1 and 2, MODES 3, 4, and 5, with any RTCBs closed and any control element assemblies capable of being withdrawn.

ACTIONS

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. --------NOTE--------- RTCBs associated with one inoperable channel may be closed for up to 1 hour for the performance of an RPS CHANNEL FUNCTIONAL TEST.</td>
<td>A.1 Open affected RTCBs.</td>
<td>1 hour</td>
</tr>
<tr>
<td>One channel of Manual Trip, RTCB, or RPS logic inoperable in MODE 1 or 2.</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

A.1 Open affected RTCBs.

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
</table>

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
### ACTIONS (continued)

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
</table>
| B. --------NOTE--------
RTCBs associated with one inoperable channel may be closed for up to 1 hour for the performance of an RPS CHANNEL FUNCTIONAL TEST.---------------------------------
One channel of Manual Trip, RTCB, or RPS logic inoperable in MODE 3, 4, or 5. | B.1 Open affected RTCBs. | 48 hours |
| C. Required Action and associated Completion Time of Condition A not met. OR One or more Functions with more than one channel of Manual Trip, RTCB, or RPS logic inoperable. | C.1 Be in MODE 3. AND C.2 Open all RTCBs. | 6 hours 6 hours |
## SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.3.4.1 Perform CHANNEL FUNCTIONAL TEST on each RPS logic channel and RTCB channel.</td>
<td>31 days</td>
</tr>
<tr>
<td>SR 3.3.4.2 Perform CHANNEL FUNCTIONAL TEST, including separate verification of undervoltage and shunt trips, on each RTCB.</td>
<td>18 months</td>
</tr>
<tr>
<td>SR 3.3.4.3 Perform CHANNEL FUNCTIONAL TEST on each RPS Manual Trip channel.</td>
<td>31 days</td>
</tr>
</tbody>
</table>
### 3.3 INSTRUMENTATION

#### 3.3.5 Engineered Safety Features Actuation System (ESFAS) Instrumentation

| LCO 3.3.5 | Four ESFAS trip and associated automatic operating bypass removal channels for each Function in Table 3.3.5-1 shall be OPERABLE. |   |

**APPLICABILITY:** According to Table 3.3.5-1.

**ACTIONS**

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. One or more Functions with one automatic ESFAS trip channel inoperable.</td>
<td>A.1 Place trip channel in bypass or trip. AND A.2 Restore trip channel to OPERABLE status.</td>
<td>1 hour Prior to entering MODE 2 following next MODE 5 entry</td>
</tr>
<tr>
<td>B. One or more Functions with two automatic ESFAS trip channels inoperable.</td>
<td>B.1 Place one trip channel in bypass and the other in trip.</td>
<td>1 hour</td>
</tr>
</tbody>
</table>
### ACTIONS (continued)

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>C. One or more Functions with one automatic operating bypass removal channel inoperable.</td>
<td>C.1 Disable affected bypass channel.</td>
<td>1 hour</td>
</tr>
<tr>
<td>OR</td>
<td>C.2.1 Place affected automatic trip channel in bypass or trip.</td>
<td>1 hour</td>
</tr>
<tr>
<td>AND</td>
<td>C.2.2 Restore automatic operating bypass removal channel and associated automatic trip channel to OPERABLE status.</td>
<td>Prior to entering MODE 2 following next MODE 5 entry</td>
</tr>
<tr>
<td>D. One or more Functions with two automatic operating bypass removal channels inoperable.</td>
<td>D.1 Disable affected bypass channels.</td>
<td>1 hour</td>
</tr>
<tr>
<td>OR</td>
<td>D.2 Place one affected automatic trip channel in bypass and place the other in trip.</td>
<td>1 hour</td>
</tr>
<tr>
<td>E. Required Action and associated Completion Time not met.</td>
<td>-------------------------------NOTE------------------------------- Only applicable to Functions 5 and 6 of Table 3.3.5-1.</td>
<td></td>
</tr>
<tr>
<td>E.1 Be in MODE 3.</td>
<td>6 hours</td>
<td></td>
</tr>
<tr>
<td>AND</td>
<td>E.2 Be in MODE 4 without reliance upon SGs for heat removal.</td>
<td>12 hours</td>
</tr>
</tbody>
</table>
### ACTIONS (continued)

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>F. Required Action and associated Completion Time not met.</td>
<td>-------------------------- NOTE -------------------------- Only applicable to Functions 1, 2, 3, and 4 of Table 3.3.5-1.</td>
<td></td>
</tr>
<tr>
<td></td>
<td>F.1 Be in MODE 3.</td>
<td>6 hours</td>
</tr>
<tr>
<td></td>
<td>AND</td>
<td></td>
</tr>
<tr>
<td></td>
<td>F.2 Be in MODE 5.</td>
<td>36 hours</td>
</tr>
</tbody>
</table>

### SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.3.5.1 Perform CHANNEL CHECK of each ESFAS channel.</td>
<td>12 hours</td>
</tr>
<tr>
<td>SR 3.3.5.2 Perform CHANNEL FUNCTIONAL TEST of each ESFAS channel in accordance with the Setpoint Control Program.</td>
<td>31 days</td>
</tr>
<tr>
<td>SR 3.3.5.3 Perform CHANNEL CALIBRATION of each ESFAS channel, including automatic operating bypass removal function in accordance with the Setpoint Control Program.</td>
<td>18 months</td>
</tr>
<tr>
<td>SR 3.3.5.4 Verify ESFAS RESPONSE TIME is within limits.</td>
<td>18 months on a STAGGERED TEST BASIS</td>
</tr>
<tr>
<td>SR 3.3.5.5 Perform CHANNEL FUNCTIONAL TEST on each automatic operating bypass removal channel.</td>
<td>Once within 31 days prior to each reactor startup</td>
</tr>
</tbody>
</table>
ESFAS Instrumentation

### Table 3.3.5-1 (Page 1 of 1)
Engineered Safety Features Actuation System Instrumentation

<table>
<thead>
<tr>
<th>FUNCTION</th>
<th>APPLICABLE MODES OR OTHER SPECIFIED CONDITIONS</th>
</tr>
</thead>
<tbody>
<tr>
<td>1. Safety Injection Actuation Signal</td>
<td>1, 2, 3, 4</td>
</tr>
<tr>
<td>a. Containment Pressure – High</td>
<td>1, 2, 3, 4</td>
</tr>
<tr>
<td>b. Pressurizer Pressure – Low(^{(a)})</td>
<td>1, 2, 3, 4</td>
</tr>
<tr>
<td>2. Containment Spray Actuation Signal</td>
<td>1, 2, 3, 4</td>
</tr>
<tr>
<td>a. Containment Pressure – High High</td>
<td>1, 2, 3, 4</td>
</tr>
<tr>
<td>3. Containment Isolation Actuation Signal</td>
<td>1, 2, 3, 4</td>
</tr>
<tr>
<td>a. Containment Pressure – High</td>
<td>1, 2, 3, 4</td>
</tr>
<tr>
<td>b. Pressurizer Pressure – Low(^{(a)})</td>
<td>1, 2, 3, 4</td>
</tr>
<tr>
<td>4. Main Steam Isolation Signal</td>
<td>1, 2(^{(b)}), 3(^{(b)}), 4(^{(b)(d)})</td>
</tr>
<tr>
<td>a. Steam Generator Pressure – Low(^{(c)})</td>
<td>1, 2(^{(b)}), 3(^{(b)}), 4(^{(b)(d)})</td>
</tr>
<tr>
<td>b. Containment Pressure – High</td>
<td>1, 2(^{(b)}), 3(^{(b)}), 4(^{(b)(d)})</td>
</tr>
<tr>
<td>c. Steam Generator Level – High</td>
<td>1, 2(^{(b)}), 3(^{(b)}), 4(^{(b)(d)})</td>
</tr>
<tr>
<td>5. Auxiliary Feedwater Actuation Signal SG #1 (AFAS-1)</td>
<td>1, 2, 3, 4(^{(d)})</td>
</tr>
<tr>
<td>a. Steam Generator Level – Low</td>
<td>1, 2, 3, 4(^{(d)})</td>
</tr>
<tr>
<td>6. Auxiliary Feedwater Actuation Signal SG #2 (AFAS-2)</td>
<td>1, 2, 3, 4(^{(d)})</td>
</tr>
<tr>
<td>a. Steam Generator Level – Low</td>
<td>1, 2, 3, 4(^{(d)})</td>
</tr>
</tbody>
</table>

(a) The setpoint may be manually decreased to a minimum value of 7.0 kg/cm\(^2\)A (100 psia), as pressurizer pressure is reduced, provided the margin between pressurizer pressure and the setpoint is maintained ≤ 28.1 kg/cm\(^2\) (400 psi). Trips may be bypassed when pressurizer pressure is < 28.1 kg/cm\(^2\)A (400 psia). Bypass shall be automatically removed when pressurizer pressure is ≥ 35.2 kg/cm\(^2\)A (500 psia). The setpoint shall be automatically increased to the normal setpoint as pressurizer pressure is increased.

(b) Main Steam Isolation Signal (MSIS) Function (Steam Generator Pressure – Low, Containment Pressure – High, and Steam Generator Level – High signals) is not required to be OPERABLE when all associated valves isolated by the MSIS Function are closed and deactivated.

(c) The setpoint may be decreased as steam pressure is reduced, provided the margin between steam pressure and the setpoint is maintained ≤ 14.1 kg/cm\(^2\) (200 psi). The setpoint shall be automatically increased to the normal setpoint as steam pressure is increased.

(d) When a steam generator is relied upon for heat removal.

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3.3 INSTRUMENTATION

3.3.6 Engineered Safety Features Actuation System (ESFAS) Logic and Manual Trip

LCO 3.3.6 The ESFAS Coincidence Logic, Initiation Logic, Actuation Logic, Manual Trip and Diverse Manual ESF Actuation channels required for each Function in Table 3.3.6-1 shall be OPERABLE.

APPLICABILITY: According to Table 3.3.6-1.

ACTIONS

-------------------------------------------------------------------------------------------------------------------------------NOTE-------------------------------------------------------------------------------------------------------------------------------
Separate Condition entry is allowed for each ESFAS Function and for each Diverse Manual ESF Actuation Function.
-------------------------------------------------------------------------------------------------------------------------------

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. One or more Functions with one Coincidence Logic channel, Initiation Logic channel, or Manual Trip channel inoperable.</td>
<td>A.1 Restore channel to OPERABLE status.</td>
<td>48 hours</td>
</tr>
<tr>
<td>B. One or more Functions with two Initiation Logic channels affecting the same trip leg inoperable.</td>
<td>B.1 Open at least one contact in affected trip leg of both ESFAS Actuation Logic channels.</td>
<td>Immediately</td>
</tr>
<tr>
<td></td>
<td>AND</td>
<td></td>
</tr>
<tr>
<td></td>
<td>B.2 Restore channels to OPERABLE status.</td>
<td>48 hours</td>
</tr>
</tbody>
</table>
### ACTIONS (continued)

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>C. One or more Functions with one Actuation Logic channel inoperable.</td>
<td>C.1 _<em><strong><strong><strong><strong><strong><strong>NOTE</strong></strong></strong></strong></strong></strong></em>___</td>
<td>48 hours</td>
</tr>
<tr>
<td></td>
<td>_<em><strong><strong><strong><strong><strong><strong>NOTE</strong></strong></strong></strong></strong></strong></em>___</td>
<td></td>
</tr>
<tr>
<td></td>
<td>One channel of Actuation Logic may be bypassed for up to 1 hour for Surveillances, provided the other channel is OPERABLE.</td>
<td></td>
</tr>
<tr>
<td></td>
<td>_<em><strong><strong><strong><strong><strong><strong>NOTE</strong></strong></strong></strong></strong></strong></em>___</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Restore inoperable channel to OPERABLE status.</td>
<td></td>
</tr>
<tr>
<td>D. One or more Diverse Manual ESF Actuation Functions with one channel inoperable.</td>
<td>D.1 _<em><strong><strong><strong><strong><strong><strong>NOTE</strong></strong></strong></strong></strong></strong></em>___</td>
<td>72 hours</td>
</tr>
<tr>
<td></td>
<td>_<em><strong><strong><strong><strong><strong><strong>NOTE</strong></strong></strong></strong></strong></strong></em>___</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Restore inoperable channel to OPERABLE status.</td>
<td></td>
</tr>
<tr>
<td>E. Required Action and associated Completion Time of Condition A, B, C, or D not met.</td>
<td>E.1 Be in MODE 3.</td>
<td>6 hours</td>
</tr>
<tr>
<td></td>
<td>_<em><strong><strong><strong><strong><strong><strong>NOTE</strong></strong></strong></strong></strong></strong></em>___</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Be in MODE 3.</td>
<td></td>
</tr>
<tr>
<td></td>
<td>_<em><strong><strong><strong><strong><strong><strong>NOTE</strong></strong></strong></strong></strong></strong></em>___</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Be in MODE 4 without reliance upon SGs for heat removal.</td>
<td></td>
</tr>
<tr>
<td></td>
<td>_<em><strong><strong><strong><strong><strong><strong>NOTE</strong></strong></strong></strong></strong></strong></em>___</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Be in MODE 5.</td>
<td></td>
</tr>
<tr>
<td>OR</td>
<td>E.2 _<em><strong><strong><strong><strong><strong><strong>NOTE</strong></strong></strong></strong></strong></strong></em>___</td>
<td>36 hours</td>
</tr>
<tr>
<td></td>
<td>_<em><strong><strong><strong><strong><strong><strong>NOTE</strong></strong></strong></strong></strong></strong></em>___</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Only applicable to Functions 5, 6, 7.c, and 7.d of Table 3.3.6-1.</td>
<td></td>
</tr>
<tr>
<td></td>
<td>_<em><strong><strong><strong><strong><strong><strong>NOTE</strong></strong></strong></strong></strong></strong></em>___</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Be in MODE 4 without reliance upon SGs for heat removal.</td>
<td></td>
</tr>
<tr>
<td>AND</td>
<td>E.3 _<em><strong><strong><strong><strong><strong><strong>NOTE</strong></strong></strong></strong></strong></strong></em>___</td>
<td>36 hours</td>
</tr>
<tr>
<td></td>
<td>_<em><strong><strong><strong><strong><strong><strong>NOTE</strong></strong></strong></strong></strong></strong></em>___</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Only applicable to Functions 1, 2, 3, 4, 7.a, 7.b, 7.e, and 7.f of Table 3.3.6-1.</td>
<td></td>
</tr>
<tr>
<td></td>
<td>_<em><strong><strong><strong><strong><strong><strong>NOTE</strong></strong></strong></strong></strong></strong></em>___</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Be in MODE 5.</td>
<td></td>
</tr>
</tbody>
</table>
### SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>SR 3.3.6.1</strong></td>
<td><img src="image" alt="NOTE" /> Testing of Actuation Logic shall include the verification of proper operation of each actuation circuit. <img src="image" alt="NOTE" /> Perform CHANNEL FUNCTIONAL TEST on each ESFAS logic channel and Manual ESF Actuation channel.</td>
</tr>
<tr>
<td><strong>SR 3.3.6.2</strong></td>
<td><img src="image" alt="NOTES" /> 1. Components exempt from testing during operation shall be tested once every 18 months (MODE 6) or in MODE 5 if not tested within the previous 62 days. 2. The pair of Actuation Logic subgroup channels A and C and the pair of Actuation Logic subgroup channels B and D shall be tested on a staggered basis. <img src="image" alt="NOTE" /> Perform a verification of the OPERABILITY of subgroup for Actuation signal of each Actuation Logic channel.</td>
</tr>
<tr>
<td><strong>SR 3.3.6.3</strong></td>
<td><img src="image" alt="NOTE" /> Perform CHANNEL FUNCTIONAL TEST on each Diverse Manual ESF Actuation channel.</td>
</tr>
</tbody>
</table>
## Table 3.3.6-1 (Page 1 of 2)
Engineered Safety Features Actuation System Logic and Manual Trip Applicability

<table>
<thead>
<tr>
<th>FUNCTION</th>
<th>REQUIRED CHANNELS</th>
<th>APPLICABLE MODES</th>
</tr>
</thead>
<tbody>
<tr>
<td>1. Safety Injection Actuation Signal</td>
<td>4</td>
<td>1, 2, 3, 4</td>
</tr>
<tr>
<td>a. Coincidence Logic</td>
<td>4</td>
<td>1, 2, 3, 4</td>
</tr>
<tr>
<td>b. Initiation Logic</td>
<td>4</td>
<td>1, 2, 3, 4</td>
</tr>
<tr>
<td>c. Actuation Logic</td>
<td>4</td>
<td>1, 2, 3, 4</td>
</tr>
<tr>
<td>d. Manual Trip</td>
<td>4</td>
<td>1, 2, 3, 4</td>
</tr>
<tr>
<td>2. Containment Spray Actuation Signal</td>
<td>4</td>
<td>1, 2, 3, 4</td>
</tr>
<tr>
<td>a. Coincidence Logic</td>
<td>4</td>
<td>1, 2, 3, 4</td>
</tr>
<tr>
<td>b. Initiation Logic</td>
<td>4</td>
<td>1, 2, 3, 4</td>
</tr>
<tr>
<td>c. Actuation Logic</td>
<td>4</td>
<td>1, 2, 3, 4</td>
</tr>
<tr>
<td>d. Manual Trip</td>
<td>4</td>
<td>1, 2, 3, 4</td>
</tr>
<tr>
<td>3. Containment Isolation Actuation Signal</td>
<td>4</td>
<td>1, 2, 3, 4</td>
</tr>
<tr>
<td>a. Coincidence Logic</td>
<td>4</td>
<td>1, 2, 3, 4</td>
</tr>
<tr>
<td>b. Initiation Logic</td>
<td>4</td>
<td>1, 2, 3, 4</td>
</tr>
<tr>
<td>c. Actuation Logic</td>
<td>4</td>
<td>1, 2, 3, 4</td>
</tr>
<tr>
<td>d. Manual Trip</td>
<td>4</td>
<td>1, 2, 3, 4</td>
</tr>
<tr>
<td>4. Main Steam Isolation Signal</td>
<td>4</td>
<td>1, 2, 3, 4</td>
</tr>
<tr>
<td>a. Coincidence Logic</td>
<td>4</td>
<td>1, 2, 3, 4</td>
</tr>
<tr>
<td>b. Initiation Logic</td>
<td>4</td>
<td>1, 2, 3, 4</td>
</tr>
<tr>
<td>c. Actuation Logic</td>
<td>4</td>
<td>1, 2, 3, 4</td>
</tr>
<tr>
<td>d. Manual Trip</td>
<td>4</td>
<td>1, 2, 3, 4</td>
</tr>
<tr>
<td>5. Auxiliary Feedwater Actuation Signal SG #1 (AFAS-1)</td>
<td>4</td>
<td>1, 2, 3, 4 (a)</td>
</tr>
<tr>
<td>a. Coincidence Logic</td>
<td>4</td>
<td>1, 2, 3, 4 (a)</td>
</tr>
<tr>
<td>b. Initiation Logic</td>
<td>4</td>
<td>1, 2, 3, 4 (a)</td>
</tr>
<tr>
<td>c. Actuation Logic</td>
<td>4</td>
<td>1, 2, 3, 4 (a)</td>
</tr>
<tr>
<td>d. Manual Trip</td>
<td>4</td>
<td>1, 2, 3, 4 (a)</td>
</tr>
</tbody>
</table>

(a) When a steam generator is relied upon for heat removal.
Table 3.3.6-1 (Page 2 of 2)
Engineered Safety Features Actuation System Logic and Manual Trip Applicability

<table>
<thead>
<tr>
<th>FUNCTION</th>
<th>REQUIRED CHANNELS</th>
<th>APPLICABLE MODES</th>
</tr>
</thead>
<tbody>
<tr>
<td>6. Auxiliary Feedwater Actuation Signal SG #2 (AFAS-2)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>a. Coincidence Logic</td>
<td>4</td>
<td>1, 2, 3, 4(^{(a)})</td>
</tr>
<tr>
<td>b. Initiation Logic</td>
<td>4</td>
<td>1, 2, 3, 4(^{(a)})</td>
</tr>
<tr>
<td>c. Actuation Logic</td>
<td>4</td>
<td>1, 2, 3, 4(^{(a)})</td>
</tr>
<tr>
<td>d. Manual Trip</td>
<td>4</td>
<td>1, 2, 3, 4(^{(a)})</td>
</tr>
<tr>
<td>7. Diverse Manual ESF Actuation Signal</td>
<td></td>
<td></td>
</tr>
<tr>
<td>a. Safety Injection</td>
<td>2</td>
<td>1, 2, 3, 4</td>
</tr>
<tr>
<td>b. Containment Spray</td>
<td>2</td>
<td>1, 2, 3, 4</td>
</tr>
<tr>
<td>c. Auxiliary Feedwater (SG #1)</td>
<td>2</td>
<td>1, 2, 3, 4(^{(a)})</td>
</tr>
<tr>
<td>d. Auxiliary Feedwater (SG #2)</td>
<td>2</td>
<td>1, 2, 3, 4(^{(a)})</td>
</tr>
<tr>
<td>e. Main Steam Isolation per main steam isolation valve (MSIV)</td>
<td>1</td>
<td>1, 2, 3, 4</td>
</tr>
<tr>
<td>f. Containment Isolation</td>
<td>1</td>
<td>1, 2, 3, 4</td>
</tr>
</tbody>
</table>

\(^{(a)}\) When a steam generator is relied upon for heat removal.
3.3 INSTRUMENTATION

3.3.7 Emergency Diesel Generator (EDG) – Loss of Voltage Start (LOVS)

LCO 3.3.7 Four channels of Loss of Voltage Function and four channels of Degraded Voltage Function auto-initiation instrumentation per EDG shall be OPERABLE.

APPLICABILITY: MODES 1, 2, 3, and 4, When associated EDG is required to be OPERABLE by LCO 3.8.2, “AC Sources – Shutdown.”

ACTIONS

--------------------------------------------------------------------------------NOTE--------------------------------------------------------------------------------
Separate Condition entry is allowed for each Function.
--------------------------------------------------------------------------------

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. One or more Functions with one channel per EDG inoperable.</td>
<td>A.1 Place channel in bypass or trip.</td>
<td>1 hour</td>
</tr>
<tr>
<td>AND</td>
<td>A.2 Restore channel to OPERABLE status.</td>
<td></td>
</tr>
<tr>
<td>B. One or more Functions with two channels per EDG inoperable.</td>
<td>B.1 Enter applicable Conditions and Required Actions for associated EDG made inoperable by EDG – LOVS instrumentation.</td>
<td>1 hour</td>
</tr>
<tr>
<td>OR</td>
<td>B.2 Place one channel in bypass and the other channel in trip.</td>
<td>1 hour</td>
</tr>
</tbody>
</table>
### ACTIONS (continued)

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>C. One or more Functions with more than two channels inoperable.</td>
<td>C.1 Restore all but two channels to OPERABLE status.</td>
<td>1 hour</td>
</tr>
<tr>
<td>D. Required Action and associated Completion Time not met.</td>
<td>D.1 Enter applicable Conditions and Required Actions for the associated EDG made inoperable by EDG – LOVS instrumentation.</td>
<td>Immediately</td>
</tr>
</tbody>
</table>

### SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.3.7.1 Perform CHANNEL CHECK.</td>
<td>12 hours</td>
</tr>
<tr>
<td>SR 3.3.7.2 Perform CHANNEL FUNCTIONAL TEST in accordance with the Setpoint Control Program.</td>
<td>92 days</td>
</tr>
<tr>
<td>SR 3.3.7.3 Perform CHANNEL CALIBRATION in accordance with the Setpoint Control Program.</td>
<td>18 months</td>
</tr>
</tbody>
</table>
3.3 INSTRUMENTATION

3.3.8 Containment Purge Isolation Actuation Signal (CPIAS)

LCO 3.3.8 One CPIAS instrument division with two area radiation monitor channels, one Manual Actuation division, and one Actuation Logic division shall be OPERABLE.

APPLICABILITY: MODES 1, 2, 3, and 4, MODE 5 with RCS loops not filled when relying on LCO 3.6.7.c.2, MODE 6 when relying on LCO 3.6.7.c.2 or LCO 3.9.3.c.2.

---------------------------------------------NOTE---------------------------------------------
Only required when the associated containment purge or exhaust line penetration flow path is not isolated by at least one closed and deactivated automatic valve, closed manual valve, or blind flange.

--------------------------------------------------------------------------------------------------

ACTIONS

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. CPIAS required Manual Actuation division, required Actuation Logic division, or required instrument division with one or more required area radiation monitor channels inoperable in MODES 1, 2, 3, and 4.</td>
<td>A.1 Enter applicable Conditions and Required Actions of LCO 3.6.3, “Containment Isolation Valves,” for containment purge isolation valves made inoperable by CPIAS instrumentation.</td>
<td>Immediately</td>
</tr>
<tr>
<td>B. Required Action and associated Completion Time not met in MODE 1, 2, 3, or 4.</td>
<td>B.1 Be in MODE 3.</td>
<td>6 hours</td>
</tr>
<tr>
<td></td>
<td>AND</td>
<td></td>
</tr>
<tr>
<td></td>
<td>B.2 Be in MODE 5.</td>
<td>36 hours</td>
</tr>
</tbody>
</table>
### ACTIONS (continued)

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>C. CPIAS required Manual Actuation division, required Actuation Logic division, or required instrument division with one or more required area radiation monitor channels inoperable during CORE ALTERATIONS or movement of irradiated fuel assemblies within containment, or in MODE 5 with LCO 3.6.7.c.2 not met or in MODE 6 with LCO 3.6.7.c.2 or LCO 3.9.3.c.2 not met.</td>
<td>C.1 Place and maintain containment purge and exhaust valves in closed position.</td>
<td>Immediately</td>
</tr>
<tr>
<td></td>
<td>OR</td>
<td></td>
</tr>
<tr>
<td></td>
<td>C.2.1 Suspend CORE ALTERATIONS.</td>
<td>Immediately</td>
</tr>
<tr>
<td></td>
<td>AND</td>
<td></td>
</tr>
<tr>
<td></td>
<td>C.2.2 Suspend movement of irradiated fuel assemblies in containment.</td>
<td>Immediately</td>
</tr>
</tbody>
</table>

### SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.3.8.1</td>
<td>12 hours</td>
</tr>
<tr>
<td>SR 3.3.8.2</td>
<td>92 days</td>
</tr>
</tbody>
</table>

---

**SURVEILLANCE**

**FREQUENCY**

**SR 3.3.8.1**

Perform CHANNEL CHECK on required containment upper operating area radiation monitor channel and operating area radiation monitor channel.

**SR 3.3.8.2**

---

**NOTE**

Only required to be met in MODES 1, 2, 3, and 4.

---

Perform CHANNEL FUNCTIONAL TEST on each required upper operating area radiation monitor channel and each required operating area radiation monitor channel in accordance with the Setpoint Control Program.
<table>
<thead>
<tr>
<th>SURVEILLANCE REQUIREMENTS (continued)</th>
</tr>
</thead>
<tbody>
<tr>
<td>SURVEILLANCE</td>
</tr>
<tr>
<td>--------------------------------------</td>
</tr>
<tr>
<td>SR 3.3.8.3</td>
</tr>
<tr>
<td>Only required to be met during CORE ALTERATIONS and during movement of irradiated fuel assemblies within containment, and in MODE 5 with RCS loops not filled when relying on LCO 3.6.7.c.2, and in MODE 6 when relying on LCO 3.6.7.c.2 or LCO 3.9.3.c.2.</td>
</tr>
<tr>
<td>SR 3.3.8.4</td>
</tr>
<tr>
<td>Surveillance of Actuation Logic shall include actuation of each initiation circuit and verification of proper operation of each initiation circuit.</td>
</tr>
<tr>
<td>SR 3.3.8.5</td>
</tr>
<tr>
<td>Perform CHANNEL CALIBRATION on each required containment radiation monitor channel in accordance with the Setpoint Control Program.</td>
</tr>
<tr>
<td>SR 3.3.8.6</td>
</tr>
<tr>
<td>Verify that the response time of each required CPIAS division is within limits.</td>
</tr>
<tr>
<td>SR 3.3.8.7</td>
</tr>
<tr>
<td>Perform CHANNEL FUNCTIONAL TEST on required CPIAS Manual Actuation division.</td>
</tr>
</tbody>
</table>
3.3 INSTRUMENTATION

3.3.9 Control Room Emergency Ventilation Actuation Signal (CREVAS)

LCO 3.3.9 One CREVAS instrument division with one radiation monitor channel, one Manual Actuation division, and one Actuation Logic division shall be OPERABLE.

APPLICABILITY: MODES 1, 2, 3, and 4, During CORE ALTERATIONS, During movement of irradiated fuel assemblies.

| ACTIONS |
|------------------|--------------------|----------------|
| CONDITION | REQUIRED ACTION | COMPLETION TIME |
| A. CREVAS required Manual Actuation division, required Actuation Logic division, or required instrument division with one required radiation monitor channel inoperable in MODE 1, 2, 3, or 4. | A.1 Place one Control Room Area heating, ventilation, and air conditioning (HVAC) System train in emergency operation mode. | 1 hour |
| B. Required Action and associated Completion Time of Condition A not met. | B.1 Be in MODE 3. AND B.2 Be in MODE 5. | 6 hours 36 hours |
### ACTIONS (continued)

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>C. CREVAS required Manual Actuation division, required Actuation Logic division, or required instrument division with one required radiation monitor channel inoperable during CORE ALTERATIONS or movement of irradiated fuel assemblies.</td>
<td>C.1 Place one Control Room Area HVAC System train in emergency operation mode.</td>
<td>Immediately</td>
</tr>
<tr>
<td></td>
<td>OR</td>
<td></td>
</tr>
<tr>
<td></td>
<td>C.2.1 Suspend movement of irradiated fuel assemblies.</td>
<td>Immediately</td>
</tr>
<tr>
<td></td>
<td>AND</td>
<td></td>
</tr>
<tr>
<td></td>
<td>C.2.2 Suspend positive reactivity additions.</td>
<td>Immediately</td>
</tr>
<tr>
<td></td>
<td>AND</td>
<td></td>
</tr>
<tr>
<td></td>
<td>C.2.3 Suspend CORE ALTERATIONS.</td>
<td>Immediately</td>
</tr>
</tbody>
</table>

### SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.3.9.1</td>
<td>Perform CHANNEL CHECK on required CREVAS radiation monitor channel. 12 hours</td>
</tr>
<tr>
<td>SR 3.3.9.2</td>
<td>Perform CHANNEL FUNCTIONAL TEST on required CREVAS radiation monitor channel in accordance with the Setpoint Control Program. 92 days</td>
</tr>
</tbody>
</table>
### SURVEILLANCE REQUIREMENTS (continued)

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>SR 3.3.9.3</strong></td>
<td></td>
</tr>
<tr>
<td>SURVEILLANCE REQUIREMENTS</td>
<td></td>
</tr>
<tr>
<td>SURVEILLANCE REQUIREMENTS (continued)</td>
<td></td>
</tr>
<tr>
<td><strong>SR 3.3.9.4</strong></td>
<td></td>
</tr>
<tr>
<td>Perform CHANNEL CALIBRATION on required CREVAS radiation monitor channel in</td>
<td>18 months</td>
</tr>
<tr>
<td>accordance with the Setpoint Control Program.</td>
<td></td>
</tr>
<tr>
<td><strong>SR 3.3.9.5</strong></td>
<td></td>
</tr>
<tr>
<td>Perform CHANNEL FUNCTIONAL TEST on required CREVAS Manual Actuation division.</td>
<td>18 months</td>
</tr>
<tr>
<td><strong>SR 3.3.9.6</strong></td>
<td></td>
</tr>
<tr>
<td>Verify that the response time of required CREVAS division is within limits.</td>
<td>18 months</td>
</tr>
</tbody>
</table>
3.3 INSTRUMENTATION

3.3.10 Fuel Handling Area Emergency Ventilation Actuation Signal (FHEVAS)

LCO 3.3.10 One FHEVAS instrument division with one radiation monitor channel, one Manual Actuation division, and one Actuation Logic division shall be OPERABLE.

APPLICABILITY: During movement of irradiated fuel in the fuel handling area.

ACTIONS

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. Required Manual Actuation division, required Actuation Logic division, or required instrument division with required radiation monitor channel inoperative.</td>
<td>A.1 Place one OPERABLE Fuel Handling Area heating, ventilation, and air conditioning (HVAC) System train in emergency operation mode. OR A.2 Suspend movement of irradiated fuel assemblies in fuel handling area.</td>
<td>Immediately</td>
</tr>
</tbody>
</table>

SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.3.10.1</td>
<td>Perform CHANNEL CHECK on required FHEVAS radiation monitor channel. 12 hours</td>
</tr>
<tr>
<td>SR 3.3.10.2</td>
<td>Perform CHANNEL FUNCTIONAL TEST on required FHEVAS radiation monitor channel in accordance with the Setpoint Control Program. 92 days</td>
</tr>
<tr>
<td>SURVEILLANCE REQUIREMENTS (continued)</td>
<td></td>
</tr>
<tr>
<td>--------------------------------------</td>
<td></td>
</tr>
<tr>
<td><strong>SURVEILLANCE</strong></td>
<td><strong>FREQUENCY</strong></td>
</tr>
<tr>
<td>-------------------</td>
<td>---------------</td>
</tr>
<tr>
<td>SR 3.3.10.3</td>
<td>Testing of Actuation Logic shall include actuation of each initiation circuit and verification of proper operation of each initiation circuit. Perform CHANNEL FUNCTIONAL TEST on required FHEVAS Actuation Logic division.</td>
</tr>
<tr>
<td>SR 3.3.10.4</td>
<td>Perform CHANNEL FUNCTIONAL TEST on required FHEVAS Manual Actuation division.</td>
</tr>
<tr>
<td>SR 3.3.10.5</td>
<td>Perform CHANNEL CALIBRATION on required FHEVAS radiation monitor channel in accordance with the Setpoint Control Program.</td>
</tr>
<tr>
<td>SR 3.3.10.6</td>
<td>Verify that the response time of required FHEVAS division is within limits.</td>
</tr>
</tbody>
</table>
3.3 INSTRUMENTATION

3.3.11 Accident Monitoring Instrumentation (AMI)

LCO 3.3.11  The AMI measurement channels for each Function in Table 3.3.11-1 shall be OPERABLE.

APPLICABILITY: MODES 1, 2, and 3.

ACTIONS

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. One or more Functions with one required measurement channel inoperable.</td>
<td>A.1 Restore required measurement channel to OPERABLE status.</td>
<td>31 days</td>
</tr>
<tr>
<td>B. Required Action and associated Completion Time of Condition A not met.</td>
<td>B.1 Initiate action in accordance with Specification 5.6.5.</td>
<td>Immediately</td>
</tr>
<tr>
<td>C. One or more Functions with two required measurement channels inoperable.</td>
<td>C.1 Restore one measurement channel to OPERABLE status.</td>
<td>7 days</td>
</tr>
<tr>
<td>D. Required Action and associated Completion Time of Condition C not met.</td>
<td>D.1 Enter Condition referenced in Table 3.3.11-1 for the channel.</td>
<td>Immediately</td>
</tr>
</tbody>
</table>

NOTES

1. LCO 3.0.4 is not applicable.

2. Separate Condition entry is allowed for each Function.
### ACTIONS (continued)

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>E. As required by Required Action D.1 and referenced in Table 3.3.11-1.</td>
<td>E.1 Be in MODE 3. AND E.2 Be in MODE 4.</td>
<td>6 hours AND 12 hours</td>
</tr>
<tr>
<td>F. As required by Required Action D.1 and referenced in Table 3.3.11-1.</td>
<td>F.1 Initiate action in accordance with Specification 5.6.5.</td>
<td>Immediately</td>
</tr>
</tbody>
</table>

### SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.3.11.1</td>
<td>Perform CHANNEL CHECK for each required measurement channel that is normally energized.</td>
</tr>
<tr>
<td>SR 3.3.11.2</td>
<td>Neutron detectors are excluded from CHANNEL CALIBRATION. Perform CHANNEL CALIBRATION.</td>
</tr>
<tr>
<td>FUNCTION</td>
<td>REQUIRED MEASUREMENT CHANNELS</td>
</tr>
<tr>
<td>------------------------------------------------------------------------</td>
<td>-------------------------------</td>
</tr>
<tr>
<td>1. Logarithmic Reactor Power (neutron flux)</td>
<td>2</td>
</tr>
<tr>
<td>2. Hot Leg Temperature (Wide Range)</td>
<td>2 per loop</td>
</tr>
<tr>
<td>3. Cold Leg Temperature (Wide Range)</td>
<td>2 per loop</td>
</tr>
<tr>
<td>4. Reactor Coolant System Pressure</td>
<td>2</td>
</tr>
<tr>
<td>5. Reactor Vessel Level (RV Closure Head Level/RV Plenum Level)</td>
<td>2</td>
</tr>
<tr>
<td>6. Reactor Cavity Level</td>
<td>2</td>
</tr>
<tr>
<td>7. Containment Pressure (Wide Range)</td>
<td>2</td>
</tr>
<tr>
<td>8. Containment Pressure (Extended Wide Range)</td>
<td>2</td>
</tr>
<tr>
<td>9. Containment Isolation Valve Position</td>
<td>1 per valve (a),(b)</td>
</tr>
<tr>
<td>10. Containment Upper Operating Area Radiation</td>
<td>2</td>
</tr>
<tr>
<td>11. Pressurizer Level</td>
<td>2</td>
</tr>
<tr>
<td>12. Steam Generator Level (Wide Range)</td>
<td>2 per Steam Generator</td>
</tr>
<tr>
<td>13. Holdup Volume Tank Level</td>
<td>2</td>
</tr>
</tbody>
</table>

(a) Not required for isolation valves whose associated penetration is isolated by at least one closed and deactivated automatic valve, closed manual valve, blind flange, or check valve with flow through the valve secured.

(b) Only one position indication channel is required for penetration flow paths with only one installed main control room indication channel.
<table>
<thead>
<tr>
<th>FUNCTION</th>
<th>REQUIRED MEASUREMENT CHANNELS</th>
<th>CONDITIONS REFERENCED FROM REQUIRED ACTION D.1</th>
</tr>
</thead>
<tbody>
<tr>
<td>14. Core Exit Temperature – Quadrant 1</td>
<td>2(^{(c)})</td>
<td>E</td>
</tr>
<tr>
<td>15. Core Exit Temperature – Quadrant 2</td>
<td>2(^{(c)})</td>
<td>E</td>
</tr>
<tr>
<td>16. Core Exit Temperature – Quadrant 3</td>
<td>2(^{(c)})</td>
<td>E</td>
</tr>
<tr>
<td>17. Core Exit Temperature – Quadrant 4</td>
<td>2(^{(c)})</td>
<td>E</td>
</tr>
<tr>
<td>18. Steam Generator Pressure</td>
<td>2 per Steam Generator</td>
<td>E</td>
</tr>
<tr>
<td>19. RCS Saturation Margin</td>
<td>2(^{(d)})</td>
<td>E</td>
</tr>
<tr>
<td>20. Core Exit Temperature Saturation Margin</td>
<td>2(^{(e)})</td>
<td>E</td>
</tr>
<tr>
<td>21. Reactor Vessel Upper Head Saturation Margin</td>
<td>2(^{(f)})</td>
<td>E</td>
</tr>
<tr>
<td>22. Pressurizer Pressure (Wide Range)</td>
<td>2</td>
<td>E</td>
</tr>
</tbody>
</table>

(c) A measurement channel consists of two or more core exit thermocouples.

(d) A measurement channel consists of Reactor Coolant Cold Leg Temperature (T-Cold) Wide Range, Reactor Coolant Hot Leg Temperature (T-Hot) Wide Range, and Pressurizer Pressure (Wide Range).

(e) A measurement channel consists of one or more Core Exit Temperature and Pressurizer Pressure (Wide Range).

(f) A measurement channel consists of Reactor Vessel Upper Head Temperature and Pressurizer Pressure (Wide Range).
<table>
<thead>
<tr>
<th>FUNCTION</th>
<th>REQUIRED MEASUREMENT CHANNELS</th>
<th>CONDITIONS REFERENCED FROM REQUIRED ACTION D.1</th>
</tr>
</thead>
<tbody>
<tr>
<td>23. In-containment Refueling Water Storage Tank (IRWST) Level</td>
<td>2</td>
<td>E</td>
</tr>
<tr>
<td>24. IRWST Temperature</td>
<td>2</td>
<td>E</td>
</tr>
<tr>
<td>25. Containment Water Level</td>
<td>2</td>
<td>E</td>
</tr>
<tr>
<td>26. Containment Operating Area Radiation (For Fuel Handling Accident)</td>
<td>2</td>
<td>E</td>
</tr>
<tr>
<td>27. Spent Fuel Pool Radiation</td>
<td>2</td>
<td>E</td>
</tr>
<tr>
<td>28. Safety Injection Pump (SIP) Direct Vessel Injection (DVI) Flow Rate</td>
<td>4</td>
<td>E</td>
</tr>
<tr>
<td>29. Main Steam Atmospheric Steam Dump Valve Position</td>
<td>2</td>
<td>E</td>
</tr>
<tr>
<td>30. Auxiliary Feedwater Flow</td>
<td>2</td>
<td>E</td>
</tr>
<tr>
<td>31. Hydrogen Concentration</td>
<td>2</td>
<td>E</td>
</tr>
<tr>
<td>32. Containment Atmosphere Temperature</td>
<td>2</td>
<td>E</td>
</tr>
<tr>
<td>33. 4.16 kV Switchgear Voltage</td>
<td>2</td>
<td>E</td>
</tr>
<tr>
<td>34. DC Bus Voltage</td>
<td>2</td>
<td>E</td>
</tr>
<tr>
<td>35. Instrument Power Bus Voltage</td>
<td>2</td>
<td>E</td>
</tr>
</tbody>
</table>
3.3  INSTRUMENTATION

3.3.12  Remote Shutdown Display and Control

LCO 3.3.12  The Remote Shutdown Display and Control Functions in Table 3.3.12-1 shall be OPERABLE.

APPLICABILITY:  MODES 1, 2, and 3.

ACTIONS

---NOTES---

1.  LCO 3.0.4 is not applicable.

2.  Separate Condition entry is allowed for each Function.

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. One or more required Functions inoperable.</td>
<td>A.1  Restore required Functions to OPERABLE status.</td>
<td>31 days</td>
</tr>
</tbody>
</table>
| B. Required Action and associated Completion Time not met. | B.1  Be in MODE 3.  
  AND  
  B.2  Be in MODE 4. | 6 hours  
  12 hours |
## SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.3.12.1</td>
<td>Perform CHANNEL CHECK for each required measurement channel that is normally energized.</td>
</tr>
<tr>
<td>SR 3.3.12.2</td>
<td>Verify that the required indication, control circuit, and transfer switch is capable of performing the intended function.</td>
</tr>
<tr>
<td>SR 3.3.12.3</td>
<td>NOTE: Neutron detectors are excluded from CHANNEL CALIBRATION. Perform CHANNEL CALIBRATION for each required measurement channel.</td>
</tr>
<tr>
<td>SR 3.3.12.4</td>
<td>Perform CHANNEL FUNCTIONAL TEST of reactor trip switch gear open/closed indication.</td>
</tr>
<tr>
<td>FUNCTION (DISPLAY or CONTROL)</td>
<td>REQUIRED CHANNELS&lt;sup&gt;(a)&lt;/sup&gt;</td>
</tr>
<tr>
<td>-------------------------------</td>
<td>----------------------------------</td>
</tr>
<tr>
<td>1. Neutron Logarithmic Power</td>
<td>2</td>
</tr>
<tr>
<td>2. Hot Leg Temperature</td>
<td>1 per loop</td>
</tr>
<tr>
<td>3. Cold Leg Temperature</td>
<td>1 per loop</td>
</tr>
<tr>
<td>4. Pressurizer Pressure</td>
<td>2</td>
</tr>
<tr>
<td>5. Pressurizer Level</td>
<td>2</td>
</tr>
<tr>
<td>6. Reactor Coolant Gas Vent (RCGV) Valve Position</td>
<td>1 per valve</td>
</tr>
<tr>
<td>7. Steam Generator (SG) #1 Pressure</td>
<td>2</td>
</tr>
<tr>
<td>8. Steam Generator (SG) #2 Pressure</td>
<td>2</td>
</tr>
<tr>
<td>9. SG #1, #2 Level</td>
<td>2</td>
</tr>
<tr>
<td>10. In-containment Refueling Water Storage Tank (IRWST) Level</td>
<td>2</td>
</tr>
<tr>
<td>11. Safety Injection (SI) Pump Discharge Pressure</td>
<td>1</td>
</tr>
<tr>
<td>12. Safety Injection Tank (SIT) Pressure (Wide Range)</td>
<td>4 (1 per tank)</td>
</tr>
<tr>
<td>13. Shutdown Cooling (SC) Inlet and Outlet Temperature</td>
<td>4 per tank loop</td>
</tr>
<tr>
<td>14. SC Pump Flow Rate</td>
<td>1</td>
</tr>
<tr>
<td>15. SI Pump Flow Rate</td>
<td>1</td>
</tr>
<tr>
<td>16. Auxiliary Feedwater (AFW) Pump Discharge Pressure (SG #1)</td>
<td>2 &lt;sup&gt;(b)&lt;/sup&gt;</td>
</tr>
<tr>
<td>17. AFW Pump Discharge Pressure (SG #2)</td>
<td>2 &lt;sup&gt;(b)&lt;/sup&gt;</td>
</tr>
</tbody>
</table>

<sup>(a)</sup> A division can have one or more channels (per IEEE 603).

<sup>(b)</sup> Turbine Driven Pump Display and Control for Division I, Motor Driven Pump Display and Control for Division II.
Table 3.3.12-1 (Page 2 of 4)
Remote Shutdown Display and Control Functions

<table>
<thead>
<tr>
<th>FUNCTION (DISPLAY or CONTROL)</th>
<th>REQUIRED CHANNELS&lt;sup&gt;(a)&lt;/sup&gt;</th>
</tr>
</thead>
<tbody>
<tr>
<td>18. AFW Pump Suction Pressure and Low Pressure Alarm (SG #1, #2)</td>
<td>4&lt;sup&gt;(b)&lt;/sup&gt;</td>
</tr>
<tr>
<td>19. AFW Steam Motive Power Instrumentation (SG #1, #2)</td>
<td>2&lt;sup&gt;(b),(c)&lt;/sup&gt;</td>
</tr>
<tr>
<td>20. AFW Pump Flow Rate (SG #1, #2)</td>
<td>2&lt;sup&gt;(b),(c)&lt;/sup&gt;</td>
</tr>
<tr>
<td>21. AFW Pump Recirculation Flow Rate (SG #1, #2)</td>
<td>4&lt;sup&gt;(b)&lt;/sup&gt;</td>
</tr>
<tr>
<td>22. AFW Storage Tank Level and Low Alarm Balance of Plant (BOP)</td>
<td>1 per tank</td>
</tr>
<tr>
<td>23. Component Cooling Water (CCW) Pump and Essential Service Water (ESW) Pump Status Indication</td>
<td>1</td>
</tr>
<tr>
<td>24. Emergency Diesel Generator (EDG) Status Indication</td>
<td>1</td>
</tr>
<tr>
<td>25. Reactor Coolant Pump (RCP) Trip Pushbutton</td>
<td>1 per pump</td>
</tr>
<tr>
<td>26. Pressurizer Backup Heater Control (Group 1 &amp; 2)</td>
<td>2</td>
</tr>
<tr>
<td>27. Main Steam Atmospheric Steam Dump Valve (MSADV) Controls (SG #1, #2)</td>
<td>4&lt;sup&gt;(d)&lt;/sup&gt;</td>
</tr>
<tr>
<td>28. MSADV Block Valve Controls (SG #1, #2)</td>
<td>4&lt;sup&gt;(d)&lt;/sup&gt;</td>
</tr>
<tr>
<td>29. RCGV Valve Controls</td>
<td>1 per valve</td>
</tr>
</tbody>
</table>

(a) A division can have one or more channels (per IEEE 603).

(b) Turbine Driven Pump Display and Control for Division I, Motor Driven Pump Display and Control for Division II.

(c) Includes Turbine-Driven Pump Turbine Inlet Pressure, Turbine-Driven Pump Turbine Speed, Turbine Trip and Throttle (Stop) Valves Open/Close Position and Close Position Alarm, to Division I Steam Motive Power, No Display for Division II Motive Power.

(d) Includes ON/OFF switch and M/A station.

---

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Table 3.3.12-1 (Page 3 of 4)
Remote Shutdown Display and Control Functions

<table>
<thead>
<tr>
<th>FUNCTION (DISPLAY or CONTROL)</th>
<th>REQUIRED CHANNELS&lt;sup&gt;(a)&lt;/sup&gt;</th>
</tr>
</thead>
<tbody>
<tr>
<td>30. Shutdown Cooling System (SCS) Warmup Line Isolation Valve Controls</td>
<td>1</td>
</tr>
<tr>
<td>31. SCS Suction Line Isolation Valve Controls (3 valves per train)</td>
<td>1</td>
</tr>
<tr>
<td>32. IRWST Isolation Valve Control</td>
<td>1</td>
</tr>
<tr>
<td>33. SCS Test Return Line Isolation Valve Control (Throttle)</td>
<td>1</td>
</tr>
<tr>
<td>34. SCS Test Return Line Isolation Valve Control</td>
<td>1</td>
</tr>
<tr>
<td>35. Containment Spray (CS) Pump/SC Pump Suction Cross Connect Valve Control</td>
<td>1</td>
</tr>
<tr>
<td>36. IRWST Return Line Isolation Valve Control</td>
<td>1</td>
</tr>
<tr>
<td>37. SC Heat Exchanger Bypass Flow Control Valve Control</td>
<td>1</td>
</tr>
<tr>
<td>38. SC Heat Exchanger Discharge Isolation and Throttle Valve Control</td>
<td>1</td>
</tr>
<tr>
<td>39. SI Low Flow Control Bypass Valve Control</td>
<td>1</td>
</tr>
<tr>
<td>40. SIT Atmospheric Vent Valve Control</td>
<td>4 (1 per tank)</td>
</tr>
<tr>
<td>41. SIT Isolation Valve Control</td>
<td>4 (1 per tank)</td>
</tr>
<tr>
<td>42. SCS Direct Vessel Injection (DVI) Isolation Valve Control</td>
<td>1</td>
</tr>
<tr>
<td>43. SI Line Isolation Valve Control</td>
<td>1</td>
</tr>
<tr>
<td>44. SI Pump/SC Pump Suction Cross Connect Valve Control</td>
<td>1</td>
</tr>
<tr>
<td>45. SI Pump Control</td>
<td>1</td>
</tr>
<tr>
<td>46. SC Pump Control</td>
<td>1</td>
</tr>
</tbody>
</table>

(a) A division can have one or more channels (per IEEE 603).
<table>
<thead>
<tr>
<th>FUNCTION (DISPLAY or CONTROL)</th>
<th>REQUIRED CHANNELS ( ^{(a)} )</th>
</tr>
</thead>
<tbody>
<tr>
<td>47. Manual Reactor Trip Switch</td>
<td>2( ^{(e)} )</td>
</tr>
<tr>
<td>48. MSIS Actuation Switch</td>
<td>2</td>
</tr>
<tr>
<td>49. AFW Pump Controls (SG #1, #2)</td>
<td>4( ^{(b)} )</td>
</tr>
<tr>
<td>50. AFW Isolation Valves (SG #1, #2)</td>
<td>4( ^{(b)} )</td>
</tr>
<tr>
<td>51. AFW Flow Control Valves (SG #1, #2)</td>
<td>4( ^{(b)}, )( ^{(d)} )</td>
</tr>
<tr>
<td>52. AFW Steam Motive Power Controls (SG #1, #2)</td>
<td>2( ^{(b)}, )( ^{(f)} )</td>
</tr>
<tr>
<td>53. Charging Pump Controls</td>
<td>2</td>
</tr>
<tr>
<td>54. AFW Turbine Trip and Throttle Valve 1&amp;2 Trip and Reset</td>
<td>2</td>
</tr>
<tr>
<td>55. EDG Power Circuit Breaker (PCB) Controls</td>
<td>2</td>
</tr>
<tr>
<td>56. Reactor Containment Building Fan Cooler Controls</td>
<td>1</td>
</tr>
<tr>
<td>57. Area Cooling Fan Controls</td>
<td>1</td>
</tr>
<tr>
<td>58. Master Transfer Switch</td>
<td>6( ^{(g)} )</td>
</tr>
<tr>
<td>59. CCW Pump and ESW Pump Controls</td>
<td>1</td>
</tr>
</tbody>
</table>

(a) A division can have one or more channels (per IEEE 603).

(b) Turbine Driven Pump Display and Control for Division I, Motor Driven Pump Display and Control for Division II.

(d) Includes ON/OFF switch and M/A station.

(e) A division consists of two Manual Reactor Trip Switches.

(f) AFW Pump Turbine Steam Supply Valves, AFW Pump Turbine Steam Isolation and Isolation Bypass Valves, AFW Turbine, and AFW Turbine Speed Control for Division I, No Steam Motive Power Controls for Division II.

(g) Includes safety Channels A, B, C and D and non-safety Channels N1 and N2.
3.3 INSTRUMENTATION

3.3.13 Logarithmic Power Monitoring Channels

LCO 3.3.13 Two channels of logarithmic power level monitoring instrumentation shall be OPERABLE.

APPLICABILITY: MODES 3, 4, and 5 with the reactor trip circuit breakers (RTCBs) open or Control Element Assembly (CEA) Drive System not capable of CEA withdrawal.

**ACTIONS**

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. One or more required channel(s) inoperable.</td>
<td>A.1 --------------NOTE---------------- Limited plant cooldown or boron dilution is allowed provided the change is accounted for in the calculated SDM.</td>
<td>Immediately</td>
</tr>
<tr>
<td>AND</td>
<td></td>
<td></td>
</tr>
<tr>
<td>A.2</td>
<td>Perform SDM verification in accordance with SR 3.1.1.1.</td>
<td>4 hours AND Once per 12 hours thereafter</td>
</tr>
</tbody>
</table>
### SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.3.13.1 Perform CHANNEL CHECK.</td>
<td>12 hours</td>
</tr>
<tr>
<td>SR 3.3.13.2 Perform CHANNEL FUNCTIONAL TEST in accordance with the Setpoint Control Program.</td>
<td>31 days</td>
</tr>
<tr>
<td>SR 3.3.13.3 Note: Neutron detectors are excluded from CHANNEL CALIBRATION.</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
</tr>
<tr>
<td>Perform CHANNEL CALIBRATION in accordance with the Setpoint Control Program.</td>
<td>18 months</td>
</tr>
</tbody>
</table>
### 3.3 INSTRUMENTATION

#### 3.3.14 Boron Dilution Alarms

**LCO 3.3.14**

Two Boron Dilution Alarm System (BDAS) channels shall be OPERABLE.

**APPLICABILITY:**

MODE 3 within 1 hour after the neutron flux is within the startup range following a reactor shutdown, MODES 4 and 5.

**ACTIONS**

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
</table>
| A. One BDAS channel inoperable. | **A.1** -----------NOTE-----------
Turn on auxiliary charging pump if necessary
---------------------------------------
Turn off charging pump and determine the RCS boron concentration. | Immediately AND
At the monitoring Frequency specified in the COLR |
| AND | **A.2** Suspend all operations involving positive reactivity additions. | Immediately |
### ACTIONS (continued)

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>B. Two BDAS channels inoperable.</td>
<td>B.1 -----------------\NOTE---------\ Turn on auxiliary charging pump if necessary. -----------------------------\ Turn off charging pump and determine the RCS boron concentration by redundant methods. -----------------------------\ Immediately \AND\ At the monitoring Frequency specified in the COLR -----------------------------\ B.2 Suspend all operations involving positive reactivity additions. -----------------------------\ Immediately</td>
<td></td>
</tr>
</tbody>
</table>

### SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.3.14.1 -----------------\NOTE---------\ Not required to be performed until 1 hour after neutron flux is within the startup range. -----------------------------\ Perform CHANNEL CHECK.</td>
<td>12 hours</td>
</tr>
<tr>
<td>SR 3.3.14.2 -----------------\NOTE---------\ Neutron flux detector is excluded from CHANNEL FUNCTIONAL TEST. -----------------------------\ Perform CHANNEL FUNCTIONAL TEST.</td>
<td>31 days of cumulative operation during shutdown</td>
</tr>
<tr>
<td>SURVEILLANCE REQUIREMENTS (continued)</td>
<td></td>
</tr>
<tr>
<td>---------------------------------------</td>
<td></td>
</tr>
<tr>
<td><strong>SURVEILLANCE</strong></td>
<td><strong>FREQUENCY</strong></td>
</tr>
<tr>
<td>-------------------------------------</td>
<td>----------------------</td>
</tr>
<tr>
<td>SR 3.3.14.3</td>
<td>NOTE</td>
</tr>
<tr>
<td>Neutron flux detector is excluded from CHANNEL CALIBRATION.</td>
<td>18 months</td>
</tr>
<tr>
<td>Perform CHANNEL CALIBRATION.</td>
<td></td>
</tr>
</tbody>
</table>
3.4  REACTOR COOLANT SYSTEM (RCS)

3.4.1  RCS Pressure, Temperature, and Flow Limits

LCO 3.4.1  RCS departure from nucleate boiling (DNB) parameters for pressurizer pressure, cold leg temperature ($T_{\text{cold}}$), and RCS total flow rate shall be within the limits specified below:

a.  Pressurizer pressure $\geq 154.7$ kg/cm²A (2,201 psia) and $\leq 161.6$ kg/cm²A (2,299 psia);

b.  $T_{\text{cold}} \geq 286.7^\circ$C (548°F) and $\leq 293.3^\circ$C (560°F) for THERMAL POWER < 90% RTP,

c.  $T_{\text{cold}} \geq 289.4^\circ$C (553°F) and $\leq 293.3^\circ$C (560°F) for THERMAL POWER $\geq 90$% RTP; and

d.  RCS total flow rate $\geq 75.6E6$ kg/hr (166.6E6 lb/hr).

APPLICABILITY:  MODES 1 and 2 for pressurizer pressure,
                MODE 1 for $T_{\text{cold}},$
                MODE 2 with $k_{\text{eff}} \geq 1.0$ for $T_{\text{cold}},$
                MODE 1 for RCS total flow rate.

----------------------------------------------------------------注-----------------------------------------------------------------------
Pressurizer pressure limit in MODE 1 does not apply during:

a.  THERMAL POWER ramp $> 5$% RTP per minute or

b.  THERMAL POWER step $> 10$% RTP.

---------------------------------------------------------------------------------------------------------------------------------

+---------------------------------+---------------------------------+----------------+
| CONDITION                        | REQUIRED ACTION                 | COMPLETION TIME |
+---------------------------------+---------------------------------+----------------+
| A.  RCS total flow rate not      | A.1  Restore RCS total flow rate | 2 hours         |
| within limits.                  | to within limits.               |                 |
+---------------------------------+---------------------------------+----------------+
### ACTIONS (continued)

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>B. Required Action and associated Completion Time of Condition A not met.</td>
<td>B.1 Be in MODE 2.</td>
<td>6 hours</td>
</tr>
<tr>
<td>C. Pressurizer pressure or RCS $T_{cold}$ not within limit.</td>
<td>C.1 Restore parameter(s) to within limits.</td>
<td>2 hours</td>
</tr>
<tr>
<td>D. Required Action and associated Completion Time of Condition C not met.</td>
<td>D.1 Be in MODE 3.</td>
<td>6 hours</td>
</tr>
</tbody>
</table>

### SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.4.1.1 Verify pressurizer pressure $\geq 154.7$ kg/cm²A (2,201 psia) and $\leq 161.6$ kg/cm²A (2,299 psia).</td>
<td>12 hours</td>
</tr>
<tr>
<td>SR 3.4.1.2 Verify RCS $T_{cold}$ $\geq 286.7^\circ$C (548°F) and $\leq 293.3^\circ$C (560°F) for $&lt; 90%$ RTP or $\geq 289.4^\circ$C (553°F) and $\leq 293.3^\circ$C (560°F) for $\geq 90%$ RTP.</td>
<td>12 hours</td>
</tr>
<tr>
<td>SR 3.4.1.3 Verify RCS total flow rate $\geq 75.6E6$ kg/hr (166.6E6 lb/hr).</td>
<td>12 hours</td>
</tr>
</tbody>
</table>
### SURVEILLANCE REQUIREMENTS (continued)

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.4.1.4</td>
<td>18 months</td>
</tr>
</tbody>
</table>

-----------------NOTE-----------------
Not required to be performed until 24 hours after ≥ 95% RTP.

Verify by precision heat balance that RCS total flow rate ≥ 75.6E6 kg/hr (166.6E6 lb/hr).
3.4 REACTOR COOLANT SYSTEM (RCS)

3.4.2 RCS Minimum Temperature for Criticality

LCO 3.4.2 Each RCS cold leg temperature ($T_{\text{cold}}$) shall be $\geq 286.7°C (548°F)$.

APPLICABILITY: MODE 1, MODE 2 with $k_{\text{eff}} \geq 1.0$.

ACTIONS

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. RCS $T_{\text{cold}}$ in one or more RCS loops not within limit.</td>
<td>A.1 Be in MODE 3.</td>
<td>30 minutes</td>
</tr>
</tbody>
</table>

SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.4.2.1 Verify RCS $T_{\text{cold}}$ in each loop is $\geq 286.7°C (548°F)$.</td>
<td>Once within 15 minutes prior to achieving criticality AND 30 minutes with the reactor critical and $T_{\text{cold}} &lt; 289.4°C (553°F)$ AND 12 hours</td>
</tr>
</tbody>
</table>
3.4 Reactor Coolant System (RCS)

3.4.3 RCS Pressure and Temperature (P/T) Limits

LCO 3.4.3 RCS pressure, RCS temperature, and RCS heatup and cooldown rates shall be maintained within the limits specified in PTLR.

Applicability: At all times.

Actions

<table>
<thead>
<tr>
<th>Condition</th>
<th>Required Action</th>
<th>Completion Time</th>
</tr>
</thead>
<tbody>
<tr>
<td>A.</td>
<td>A.1 Restore parameter(s) to within limits.</td>
<td>30 minutes</td>
</tr>
<tr>
<td></td>
<td>AND A.2 Determine RCS is acceptable for continued operation.</td>
<td>72 hours</td>
</tr>
<tr>
<td></td>
<td>Required Action A.2 shall be completed whenever Condition A is entered.</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Requirements of LCO not met in MODE 1, 2, 3, or 4.</td>
<td></td>
</tr>
<tr>
<td>B.</td>
<td>B.1 Be in MODE 3.</td>
<td>6 hours</td>
</tr>
<tr>
<td></td>
<td>AND B.2 Be in MODE 5 with RCS pressure &lt; 33.7 kg/cm²A (479 psia).</td>
<td>36 hours</td>
</tr>
<tr>
<td></td>
<td>Required Action and associated Completion Time of Condition A not met.</td>
<td></td>
</tr>
<tr>
<td>C.</td>
<td>C.1 Initiate action to restore parameter(s) to within limits.</td>
<td>Immediately</td>
</tr>
<tr>
<td></td>
<td>AND C.2 Determine RCS is acceptable for continued operation.</td>
<td>Prior to entering MODE 4.</td>
</tr>
<tr>
<td></td>
<td>Required Action C.2 shall be completed whenever this Condition is entered.</td>
<td></td>
</tr>
</tbody>
</table>
### SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.4.3.1</td>
<td>30 minutes</td>
</tr>
</tbody>
</table>

-------------------------------NOTE-------------------------------
Only required to be performed during RCS heatup and cooldown operations and RCS inservice leak and hydrostatic testing.

--------------------------------------------------------------
Verify RCS pressure, RCS temperature, and RCS heatup and cooldown rates within limits specified in PTLR.
3.4 REACTOR COOLANT SYSTEM (RCS)

3.4.4 RCS Loops – MODES 1 and 2

LCO 3.4.4 Two RCS loops shall be OPERABLE and in operation with two reactor coolant pumps operating in each loop.

APPLICABILITY: MODES 1 and 2.

ACTIONS

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. Requirements of LCO not met.</td>
<td>A.1 Be in MODE 3.</td>
<td>6 hours</td>
</tr>
</tbody>
</table>

SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.4.4.1 Verify each RCS loop is in operation.</td>
<td>12 hours</td>
</tr>
</tbody>
</table>
3.4 REACTOR COOLANT SYSTEM (RCS)

3.4.5 RCS Loops – MODE 3

LCO 3.4.5 Two RCS loops shall be OPERABLE and one RCS loop shall be in operation.

---------------------------------------------NOTE---------------------------------------------
All reactor coolant pumps may be removed from operation for \( \leq 1 \) hour per 8 hour period, provided:

a. No operations are permitted that would cause introduction of coolant into the RCS with boron concentration less than required to meet the SDM of LCO 3.1.1; and

b. Core outlet temperature is maintained at least 5.6°C (10°F) below saturation temperature.

--------------------------------------------------------------------------------------------------

APPLICABILITY: MODE 3.

ACTIONS

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. One RCS loop inoperable.</td>
<td>A.1 Restore RCS loop to OPERABLE status.</td>
<td>72 hours</td>
</tr>
<tr>
<td>B. Required Action and associated Completion Time of Condition A not met.</td>
<td>B.1 Be in MODE 4.</td>
<td>12 hours</td>
</tr>
</tbody>
</table>
### ACTIONS (continued)

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>C. No RCS loop OPERABLE. OR Required RCS loop not in operation.</td>
<td>C.1 Suspend all operations that would cause reduction of the RCS boron concentration below that required to meet the SDM of LCO 3.1.1. AND C.2 Initiate action to restore one RCS loop to OPERABLE status and operation.</td>
<td>Immediately Immediately</td>
</tr>
</tbody>
</table>

### SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.4.5.1 Verify required RCS loop is in operation.</td>
<td>12 hours</td>
</tr>
<tr>
<td>SR 3.4.5.2 Verify secondary side water level in each steam generator is ≥ 25% wide range indications.</td>
<td>12 hours</td>
</tr>
<tr>
<td>SR 3.4.5.3 Not required to be performed until 24 hours after a required pump is not in operation. Verify correct breaker alignment and indicated power available to required pump.</td>
<td>7 days</td>
</tr>
</tbody>
</table>
3.4 REACTOR COOLANT SYSTEM (RCS)

3.4.6 RCS Loops – MODE 4

LCO  3.4.6 Two loops or trains consisting of any combination of RCS loops and shutdown cooling (SC) trains shall be OPERABLE and one loop or train shall be in operation.

--------------------------------------------NOTES---------------------------------------------
1. All reactor coolant pumps (RCPs) and SC pumps may be removed from operation for \( \leq 1 \) hour per 8 hour period, provided:
   a. No operations are permitted that would cause introduction of coolant into the RCS with boron concentration less than required to meet the SDM of LCO 3.1.1; and
   b. Core outlet temperature is maintained at least 5.6°C (10°F) below saturation temperature.

2. No RCP shall be started with any RCS cold leg temperatures less than or equal to the Low Temperature Overpressure Protection (LTOP) enable temperature specified in the PTLR, unless secondary side water temperature in each steam generator (SG) is < 55.6°C (100°F) above each of the RCS cold leg temperatures.

--------------------------------------------------------------------------------------------------

APPLICABILITY: MODE 4.

ACTIONS

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. One required RCS loop inoperable. AND Two SC trains inoperable.</td>
<td>A.1 Initiate action to restore a second loop or train to OPERABLE status.</td>
<td>Immediately</td>
</tr>
</tbody>
</table>
### ACTIONS (continued)

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>B. One required SC train inoperable. <strong>AND</strong> Two required RCS loops inoperable.</td>
<td>B.1 Be in MODE 5.</td>
<td>24 hours</td>
</tr>
<tr>
<td>C. Two required RCS loops or SC trains inoperable. <strong>OR</strong> Required RCS loop or SC train not in operation.</td>
<td>C.1 Suspend all operations that would cause reduction of the RCS boron concentration below that required to meet the SDM of LCO 3.1.1. <strong>AND</strong> C.2 Initiate action to restore one loop or train to OPERABLE status and operation.</td>
<td>Immediately</td>
</tr>
</tbody>
</table>

### SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.4.6.1</td>
<td>Verify one RCS loop or SC train is in operation.</td>
</tr>
<tr>
<td>SR 3.4.6.2</td>
<td>Verify secondary side water level in required SG(s) is $\geq 25%$ wide range indication.</td>
</tr>
</tbody>
</table>
## SURVEILLANCE REQUIREMENTS (continued)

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>SR 3.4.6.3</strong></td>
<td>7 days</td>
</tr>
<tr>
<td>Not required to be performed until 24 hours after a required pump is not in operation.</td>
<td></td>
</tr>
<tr>
<td>Verify correct breaker alignment and indicated power available to each required pump.</td>
<td></td>
</tr>
<tr>
<td><strong>SR 3.4.6.4</strong></td>
<td>31 days</td>
</tr>
<tr>
<td>Not required to be performed until 12 hours after entering MODE 4.</td>
<td></td>
</tr>
<tr>
<td>Verify required SC train locations susceptible to gas accumulation are sufficiently filled with water.</td>
<td></td>
</tr>
</tbody>
</table>
3.4 REACTOR COOLANT SYSTEM (RCS)

3.4.7 RCS Loops – MODE 5 (Loops Filled)

LCO 3.4.7 One shutdown cooling (SC) train shall be OPERABLE and in operation, and either:

a. One additional SC train shall be OPERABLE, or

b. The secondary side water level of each steam generator (SG) shall be \( \geq 25\% \) wide range indication.

--------------------------------------------NOTES---------------------------------------------

1. The SC pump of the train in operation may be removed from operation for \( \leq 1 \) hour per 8 hour period provided:

a. No operations are permitted that would cause introduction of coolant into the RCS with boron concentration less than that required to meet the SDM of LCO 3.1.1; and

b. Core outlet temperature is maintained at least 5.6°C (10°F) below saturation temperature.

2. One required SC train may be inoperable for up to 2 hours for surveillance testing provided that the other SC train is OPERABLE and in operation.

3. No reactor coolant pump (RCP) shall be started with one or more of the RCS cold leg temperatures less than or equal to the Low Temperature Overpressure Protection (LTOP) enable temperature specified in the PTLR, unless secondary water temperature of each SG is \(< 55.6°C (100°F)\) above each of the RCS cold leg temperatures.

4. All SC trains may be removed from operation during planned heatup to MODE 4 when at least one RCS loop is in operation.

5. A containment spray pump can be manually realigned to meet the requirement of a SC pump.

--------------------------------------------------------------------------------------------------

APPLICABILITY: MODE 5 with RCS loops filled.
## ACTIONS

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
</table>
| A. One Required SC train inoperable.  
  AND  
  One SC train OPERABLE. | A.1 Initiate action to restore a second SC train to OPERABLE status.  
  OR  
  A.2 Initiate action to restore SG secondary side water level to within limits. | Immediately |
| B. One or more required SGs with secondary side water level not within limit.  
  AND  
  One SC train OPERABLE. | B.1 Initiate action to restore a second SC train to OPERABLE status.  
  OR  
  B.2 Initiate action to restore SG secondary side water level to within limits. | Immediately |
| C. No required SC train OPERABLE.  
  OR  
  SC train not in operation. | C.1 Suspend all operations involving reduction in RCS boron concentration.  
  AND  
  C.2 Initiate action to restore one SC train to OPERABLE status and operation. | Immediately |
### SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.4.7.1</td>
<td>Verify one SC train is in operation with circulating reactor coolant at a flow rate of ( \geq 15,710 \text{ L/min (4,150 gpm)} ).</td>
</tr>
<tr>
<td>SR 3.4.7.2</td>
<td>Verify required SG secondary side water level is ( \geq 25% ) wide range indication.</td>
</tr>
<tr>
<td>SR 3.4.7.3</td>
<td><strong>NOTE</strong> Not required to be performed until 24 hours after a required pump is not in operation. Verify correct breaker alignment and indicated power available to required SC pump.</td>
</tr>
<tr>
<td>SR 3.4.7.4</td>
<td>Verify required SC train locations susceptible to gas accumulation are sufficiently filled with water.</td>
</tr>
</tbody>
</table>
3.4 REACTOR COOLANT SYSTEM (RCS)

3.4.8 RCS Loops – MODE 5 (Loops Not Filled)

LCO 3.4.8 The heat removal system shall be in the following status:

a. Two shutdown cooling (SC) trains shall be OPERABLE and one SC train shall be in operation; and

b. The containment spray pump in the same electrical division as the operating SC train shall be OPERABLE.

------------------------------------------------------------NOTES------------------------------------------------------------

1. All SC pumps may be removed from operation for \( \leq 15 \) minutes when switching from one train to another provided:

a. Core outlet temperature is maintained at least 5.6°C (10°F) below saturation temperature;

b. No operations are permitted that would cause introduction of coolant into the RCS with boron concentration less than that required to meet the SDM of LCO 3.1.1; and

c. No draining operations to further reduce RCS water volume are permitted.

2. One SC train may be inoperable for \( \leq 2 \) hours for surveillance testing provided the other SC train is OPERABLE and in operation.

3. The containment spray pump in the same electrical division as the SC train in operation may be manually aligned to meet the requirements of its associated SC pump.

4. Operation in the mid-loop condition (RCS level \( \leq 36.30 \) m (119 ft 1 in)) is allowed if the time after reactor shutdown is \( \geq 96 \) hours and core exit temperature is maintained \( \leq 57.2°C \) (135°F).

----------------------------------------------------------------------------------------------------------------------------------

APPLICABILITY: MODE 5 with RCS loops not filled.
### ACTIONS

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. One SC train inoperable.</td>
<td>A.1 Initiate action to restore SC train to OPERABLE status.</td>
<td>Immediately</td>
</tr>
<tr>
<td>B. Two SC trains inoperable. OR No SC train in operation.</td>
<td>B.1 Suspend operations that would cause introduction of coolant into the RCS with boron concentration less than that required to meet SDM of LCO 3.1.1.</td>
<td>Immediately</td>
</tr>
<tr>
<td>AND</td>
<td>B.2 Initiate action to restore one SC train to OPERABLE status and operation.</td>
<td>Immediately</td>
</tr>
<tr>
<td>AND</td>
<td>B.3 Initiate action to raise RCS level to &gt; 38.72 m (127 ft 1/4 in).</td>
<td>Immediately</td>
</tr>
<tr>
<td>C. Containment Spray pump in the same electrical division as the operating SC train inoperable.</td>
<td>C.1 If the containment spray pump in the same electrical division as the alternate SC train is OPERABLE, initiate action to place the alternate SC train in operation.</td>
<td>Immediately</td>
</tr>
<tr>
<td>AND</td>
<td>C.2 Monitor SC System performance.</td>
<td>Every 30 minutes</td>
</tr>
<tr>
<td>AND</td>
<td>C.3 Restore containment spray pump to OPERABLE status.</td>
<td>48 hours</td>
</tr>
</tbody>
</table>
### ACTIONS (continued)

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>D. Required Action and associated Completion Time of Required Action C.3 not met.</td>
<td>D.1 Raise RCS level &gt; 38.72 m (127 ft 1/4 in).</td>
<td>6 hours</td>
</tr>
<tr>
<td>E. Core exit temperature &gt; 57.2°C (135°F) during mid-loop operation. OR RCS level ≤ 36.30 m (119 ft 1 in) with &lt; 96 hours after reactor shutdown.</td>
<td>E.1 Initiate action to restore core exit temperature to ≤ 57.2°C (135°F). AND E.2 Initiate action to raise RCS level above mid-loop condition (&gt; 36.30 m (119 ft 1 in)).</td>
<td>Immediately</td>
</tr>
</tbody>
</table>

### SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.4.8.1</td>
<td>NOTE: Only required to be met when in mid-loop operation. Verify core exit temperature is ≤ 57.2°C (135°F).</td>
</tr>
<tr>
<td>SR 3.4.8.2</td>
<td>Verify one SC train is in operation with circulating reactor coolant at a flow rate of ≥ 14,385 L/min (3,800 gpm) and &lt; 15,710 L/min (4,150 gpm).</td>
</tr>
</tbody>
</table>
## SURVEILLANCE REQUIREMENTS (continued)

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>SR 3.4.8.3</strong></td>
<td>Not required to be performed until 24 hours after a required pump is not in operation.</td>
</tr>
<tr>
<td></td>
<td>Verify correct breaker alignment and indicated power available to the required SC pump.</td>
</tr>
<tr>
<td><strong>SR 3.4.8.4</strong></td>
<td>Verify correct breaker alignment and indicated power available to the required containment spray pump that is not in operation.</td>
</tr>
<tr>
<td><strong>SR 3.4.8.5</strong></td>
<td>Verify required SC train locations susceptible to gas accumulation are sufficiently filled with water.</td>
</tr>
</tbody>
</table>
3.4  REACTOR COOLANT SYSTEM (RCS)

3.4.9 Pressurizer

LCO 3.4.9  The pressurizer shall be OPERABLE with:

a. Pressurizer water level $\geq$ 25% and $\leq$ 56%, and

b. Two groups of pressurizer backup heaters OPERABLE with the capacity of each group $\geq$ 200 kW and capable of being powered from an emergency power supply.

APPLICABILITY: MODES 1, 2, and 3.

| ACTIONS |
|-----------------|-----------------|-----------------|
| CONDITION | REQUIRED ACTION | COMPLETION TIME |
| A. Pressurizer water level not within limit. | A.1 Restore pressurizer water level within limit. | 1 hour |
| B. Required Action and associated Completion Time of Condition A not met. | B.1 Be in MODE 3 with reactor trip switch gears open. AND B.2 Be in MODE 4. | 6 hours 12 hours |
| C. One required group of pressurizer backup heaters inoperable. | C.1 Restore required group of pressurizer backup heaters to OPERABLE status. | 72 hours |
| D. Required Action and associated Completion Time of Condition C not met. | D.1 Be in MODE 3. AND D.2 Be in MODE 4. | 6 hours 12 hours |
### SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>SR 3.4.9.1</strong> Verify pressurizer water level ≥ 25% and ≤ 56%.</td>
<td>12 hours</td>
</tr>
<tr>
<td><strong>SR 3.4.9.2</strong> Verify capacity of each required group of pressurizer backup heaters ≥ 200 kW.</td>
<td>92 days</td>
</tr>
</tbody>
</table>
| **SR 3.4.9.3** Verify that on an engineered safety features actuation test signal concurrent with a loss of offsite power:  
  a. Pressurizer backup heaters are automatically shed from emergency power sources.  
  b. Pressurizer backup heaters can be reconnected to their respective buses manually from the control room. | 18 months |
3.4 REACTOR COOLANT SYSTEM (RCS)

3.4.10 Pressurizer Pilot Operated Safety Relief Valves (POSRVs)

**LCO 3.4.10**

Four pressurizer POSRVs shall be OPERABLE such that:

a. Two spring-loaded pilot valves shall be OPERABLE with lift settings \( \geq 171.1 \text{ kg/cm}^2 \text{A (2,433 psia)} \) and \( \leq 176.3 \text{ kg/cm}^2 \text{A (2,507 psia)} \).

b. The opening time of pressurizer POSRV shall be \( \leq 0.5 \) seconds, including dead time.

**APPLICABILITY:** MODES 1, 2, and 3, MODE 4 with all RCS cold leg temperatures greater than the Low Temperature Overpressure Protection (LTOP) enable temperature specified in the PTLR.

---NOTE---

The opening time measurement and lift pressure setting of each POSRV are not required to be within LCO limits during MODES 3 and 4 for the purpose of setting the POSRVs under ambient (hot) conditions. This exception is allowed for 72 hours following entry into MODE 3 provided a preliminary cold setting was made prior to heatup.

---NOTE---

**ACTIONS**

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. One pressurizer POSRV inoperable.</td>
<td>A.1 Restore pressurizer POSRV to OPERABLE status.</td>
<td>15 minutes</td>
</tr>
</tbody>
</table>
### ACTIONS (continued)

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>B.</strong> Required Action and associated Completion Time of Condition A not met. OR Two or more pressurizer POSRVs inoperable.</td>
<td><strong>B.1</strong> Be in MODE 3. <strong>AND</strong> <strong>B.2.1</strong> Be in MODE 4 with all RCS cold leg temperatures less than or equal to LTOP enable temperature specified in PTLR. OR <strong>B.2.2</strong> Be in MODE 4 on shutdown cooling with requirements of LCO 3.4.11 met.</td>
<td>6 hours 12 hours 12 hours</td>
</tr>
</tbody>
</table>

### SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>SR 3.4.10.1</strong> Verify open and close positions for the following valves in the main control room (MCR):</td>
<td>12 hours</td>
</tr>
<tr>
<td>a. Main valves – close,</td>
<td></td>
</tr>
<tr>
<td>b. Motor-operated isolation valves and manual isolation valves – open,</td>
<td></td>
</tr>
<tr>
<td>c. Spring-loaded pilot valves – close, and</td>
<td></td>
</tr>
<tr>
<td><strong>SR 3.4.10.2</strong> Verify electric power disconnections of the following motor-operated valves:</td>
<td>7 days</td>
</tr>
<tr>
<td>a. Motor-operated isolation valves and</td>
<td></td>
</tr>
</tbody>
</table>
### SURVEILLANCE REQUIREMENTS (continued)

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.4.10.3</td>
<td>For each pressurizer POSRV: 18 months</td>
</tr>
<tr>
<td>a. Verify lift pressure settings of each of the two spring-loaded pilot valves are set $\geq$ 171.1 kg/cm$^2$A (2,433 psia) and $\leq$ 176.3 kg/cm$^2$A (2,507 psia). 18 months</td>
<td></td>
</tr>
<tr>
<td>b. Adjust each spring-loaded pilot valve, as necessary, so that the lift pressure setting is $\geq$ 172.4 kg/cm$^2$A (2,451.4 psia) and $\leq$ 175.0 kg/cm$^2$A (2,488.5 psia). 18 months</td>
<td></td>
</tr>
<tr>
<td>c. Verify opening time of pressurizer POSRV is $\leq$ 0.5 seconds, including dead time. 18 months</td>
<td></td>
</tr>
<tr>
<td>SR 3.4.10.4</td>
<td>Verify alarm devices for valve positions and electric power connections of the following valves: 18 months</td>
</tr>
<tr>
<td>a. Motor-operated isolation valves – power connection alarm, 18 months</td>
<td></td>
</tr>
<tr>
<td>b. Upstream valve of motor-operated pilot valves – power connection alarm, and 18 months</td>
<td></td>
</tr>
<tr>
<td>c. Manual isolation valves – not fully open alarm. 18 months</td>
<td></td>
</tr>
<tr>
<td>SR 3.4.10.5</td>
<td>Verify position indicators of the following valves are operated normally: 18 months</td>
</tr>
<tr>
<td>a. Main valves, 18 months</td>
<td></td>
</tr>
<tr>
<td>b. Spring-loaded pilot valves, 18 months</td>
<td></td>
</tr>
<tr>
<td>c. Motor-operated pilot valves, and 18 months</td>
<td></td>
</tr>
<tr>
<td>d. Motor-operated isolation valves and manual isolation valves. 18 months</td>
<td></td>
</tr>
<tr>
<td>SURVEILLANCE REQUIREMENTS (continued)</td>
<td></td>
</tr>
<tr>
<td>--------------------------------------</td>
<td></td>
</tr>
<tr>
<td>SURVEILLANCE</td>
<td>FREQUENCY</td>
</tr>
<tr>
<td>SR 3.4.10.6  Verify downstream manual valves of spring-loaded pilot valves are locked in open position.</td>
<td>18 months</td>
</tr>
</tbody>
</table>
### 3.4 REACTOR COOLANT SYSTEM (RCS)

#### 3.4.11 Low Temperature Overpressure Protection (LTOP) System

**LCO 3.4.11** LTOP System shall be OPERABLE as follows:

- Two OPERABLE Shutdown Cooling System (SCS) suction line relief valves with lift settings specified in the PTLR, or
- RCS depressurized and an RCS vent of $\geq 180.6 \text{ cm}^2$ (28 in$^2$) established.

**APPLICABILITY:** MODE 4 when any RCS cold leg temperature is less than or equal to the LTOP enable temperature specified in the PTLR, MODE 5, MODE 6 when the reactor vessel closure head is on.

### ACTIONS

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. One required SCS suction line relief valve inoperable in MODE 4.</td>
<td>A.1 Restore required SCS suction line relief valve to OPERABLE status.</td>
<td>7 days</td>
</tr>
<tr>
<td>B. One required SCS suction line relief valve inoperable in MODE 5 or 6.</td>
<td>B.1 Restore required SCS suction line relief valve to OPERABLE status.</td>
<td>24 hours</td>
</tr>
<tr>
<td>C. Required Action and associated Completion Time of Condition A or B not met.</td>
<td>C.1 Depressurize RCS and establish an RCS vent of $\geq 180.6 \text{ cm}^2$ (28 in$^2$).</td>
<td>8 hours</td>
</tr>
<tr>
<td>D. Two required SCS suction line relief valves inoperable.</td>
<td>D.1 Initiate action to depressurize RCS and establish an RCS vent of $\geq 180.6 \text{ cm}^2$ (28 in$^2$).</td>
<td>Immediately</td>
</tr>
</tbody>
</table>
### SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>SR 3.4.11.1</strong></td>
<td></td>
</tr>
<tr>
<td>Verify both SCS suction isolation valves in both SCS suction flow paths are open.</td>
<td>12 hours</td>
</tr>
<tr>
<td><strong>SR 3.4.11.2</strong></td>
<td></td>
</tr>
<tr>
<td>Verify RCS vent of $\geq 180.6 \text{ cm}^2$ (28 in$^2$) is established.</td>
<td>12 hours</td>
</tr>
<tr>
<td><strong>SR 3.4.11.3</strong></td>
<td></td>
</tr>
<tr>
<td>Verify the lift setting for each required SCS suction line relief valve is within limits.</td>
<td>18 months</td>
</tr>
</tbody>
</table>
3.4 REACTOR COOLANT SYSTEM (RCS)

3.4.12 RCS Operational LEAKAGE

LCO 3.4.12 RCS operational LEAKAGE shall be limited to the following:

a. No pressure boundary LEAKAGE;

b. 1.89 L/min (0.5 gpm) unidentified LEAKAGE;

c. 37.8 L/min (10 gpm) identified LEAKAGE; and

d. 0.39 L/min (150 gpd) primary-to-secondary LEAKAGE through any one steam generator (SG).

APPLICABILITY: MODES 1, 2, 3, and 4.

ACTIONS

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. RCS operational LEAKAGE not within limits for reasons other than pressure boundary LEAKAGE or primary-to-secondary LEAKAGE.</td>
<td>A.1 Reduce LEAKAGE to within limits.</td>
<td>4 hours</td>
</tr>
</tbody>
</table>
## ACTIONS (continued)

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>B. Required Action and associated Completion Time of Condition A not met.</td>
<td>B.1 Be in MODE 3.</td>
<td>6 hours</td>
</tr>
<tr>
<td>OR</td>
<td>AND</td>
<td></td>
</tr>
<tr>
<td>OR</td>
<td>B.2 Be in MODE 5.</td>
<td>36 hours</td>
</tr>
<tr>
<td>OR</td>
<td>Pressure boundary</td>
<td></td>
</tr>
<tr>
<td>LEAKAGE exists.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>OR</td>
<td>Primary-to-secondary</td>
<td></td>
</tr>
<tr>
<td>LEAKAGE not within limit.</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

## SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>SR 3.4.12.1</strong></td>
</tr>
<tr>
<td>---------------</td>
</tr>
<tr>
<td>NOTES</td>
</tr>
<tr>
<td>1. Not required to be performed until 12 hours after establishment of steady state operation.</td>
</tr>
<tr>
<td>2. Not applicable to primary-to-secondary LEAKAGE.</td>
</tr>
<tr>
<td>Verify RCS operational LEAKAGE is within limit by performing RCS water inventory balance.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th><strong>SR 3.4.12.2</strong></th>
</tr>
</thead>
<tbody>
<tr>
<td>NOTE</td>
</tr>
<tr>
<td>Not required to be performed until 12 hours after establishment of steady state operation.</td>
</tr>
<tr>
<td>Verify primary-to-secondary LEAKAGE is $\leq 0.39 \text{ L/min (150 gpd)}$ through any one SG.</td>
</tr>
</tbody>
</table>
3.4 REACTOR COOLANT SYSTEM (RCS)

3.4.13 RCS Pressure Isolation Valve (PIV) Leakage

LCO 3.4.13 Leakage from each RCS PIV shall be within the limit.

APPLICABILITY: MODES 1, 2, and 3, MODE 4, except valves in the shutdown cooling (SC) flow paths when in SC operation or during the transition to or from SC operation.

ACTIONS

1. Separate Condition entry is allowed for each flow path.

2. Enter applicable Conditions and Required Actions for systems made inoperable by an inoperable PIV.

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. One or more flow paths with leakage from one or more RCS PIVs not within limit.</td>
<td>----------- NOTE ----------- Each valve used to satisfy Required Actions A.1 and A.2 must have been verified to meet the Surveillance and Frequency of SR 3.4.13.1 and be on the reactor coolant pressure boundary.</td>
<td>4 hours</td>
</tr>
<tr>
<td>A.1</td>
<td>Isolate high pressure portion of affected system from low pressure portion by use of one closed manual, deactivated automatic, or check valve.</td>
<td></td>
</tr>
<tr>
<td>AND</td>
<td></td>
<td></td>
</tr>
<tr>
<td>A.2</td>
<td>Restore RCS PIV leakage to within limit.</td>
<td>72 hours</td>
</tr>
</tbody>
</table>
### ACTIONS (continued)

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>B. Required Action and associated Completion Time of Condition A not met.</td>
<td>B.1 Be in MODE 3. (\text{AND}) B.2 Be in MODE 5.</td>
<td>6 hours (\text{AND}) 36 hours</td>
</tr>
<tr>
<td>C. SC System open permissive interlock function inoperable.</td>
<td>C.1 Depressurize RCS pressure below open permissive interlock setpoint.</td>
<td>4 hours</td>
</tr>
</tbody>
</table>

### SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.4.13.1</td>
<td>18 months AND</td>
</tr>
<tr>
<td>NOTES</td>
<td>1. Not required to be performed in MODES 3 and 4.</td>
</tr>
<tr>
<td></td>
<td>2. Not required to be performed on RCS PIVs located in SC flow path when in SC mode of operation.</td>
</tr>
<tr>
<td></td>
<td>3. RCS PIVs actuated during performance of this Surveillance are not required to be tested more than once if a repetitive testing loop cannot be avoided.</td>
</tr>
</tbody>
</table>

Verify leakage from each RCS PIV is equivalent to \(\leq 1.89 \text{ L/min (0.5 gpm)}\) per nominal \(2.54 \text{ cm (1 in)}\) of valve size up to a maximum of \(18.9 \text{ L/min (5 gpm)}\) at an RCS pressure \(\geq 156.8 \text{ kg/cm}^2\) (2,230 psia) and \(\leq 159.6 \text{ kg/cm}^2\) (2,270 psia).
### SURVEILLANCE REQUIREMENTS (continued)

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>SR 3.4.13.1 (continued)</strong></td>
<td>Prior to entering MODE 2 whenever unit has been in MODE 5 for 72 hours or more, if leakage testing has not been performed in previous 9 months <strong>AND</strong> Prior to returning valve to service following maintenance, repair, or replacement work on valve <strong>AND</strong> Within 24 hours following valve actuation due to automatic or manual action or flow through the valve</td>
</tr>
<tr>
<td><strong>SR 3.4.13.2</strong></td>
<td>18 months</td>
</tr>
</tbody>
</table>

---

**NOTE**

Not required if SC suction line isolation valves are open for Low Temperature Overpressure Protection (LTOP) by LCO 3.4.11.a.

Verify SC System open permissive interlock prevents the SC System suction line isolation valve from being opened with a simulated or actual RCS pressure signal \( \geq 31.6 \text{ kg/cm}^2 \) (450 psia).
3.4 REACTOR COOLANT SYSTEM (RCS)

3.4.14 RCS Leakage Detection Instrumentation

LCO 3.4.14 The following RCS leakage detection instrumentation shall be OPERABLE:

a. One containment sump (level) monitor,

b. One containment atmosphere radioactivity (particulate) monitor, and

c. One containment atmosphere humidity monitor.

APPLICABILITY: MODES 1, 2, 3, and 4.

ACTIONS

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. Required containment sump (level) monitor inoperable.</td>
<td>A.1 ---------------NOTE------------- Not required until 12 hours after establishment of steady state operation. Perform SR 3.4.12.1.</td>
<td>Once per 24 hours</td>
</tr>
<tr>
<td>AND</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>A.2 Restore required containment sump (level) monitor to OPERABLE status.</td>
<td>30 days</td>
</tr>
</tbody>
</table>

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<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>B. Required containment atmosphere radioactivity (particulate) monitor inoperable.</td>
<td>B.1.1 Analyze grab samples of the containment atmosphere.</td>
<td>Once per 24 hours</td>
</tr>
<tr>
<td></td>
<td>OR</td>
<td></td>
</tr>
<tr>
<td></td>
<td>B.1.2 Not required until 12 hours after establishment of steady state operation.</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Perform SR 3.4.12.1.</td>
<td>Once per 24 hours</td>
</tr>
<tr>
<td></td>
<td>AND</td>
<td></td>
</tr>
<tr>
<td></td>
<td>B.2 Restore required containment atmosphere radioactivity (particulate) monitor to OPERABLE status.</td>
<td>30 days</td>
</tr>
<tr>
<td>C. Required containment atmosphere humidity monitor inoperable.</td>
<td>C.1.1 Perform SR 3.4.14.1.</td>
<td>Once per 8 hours</td>
</tr>
<tr>
<td></td>
<td>OR</td>
<td></td>
</tr>
<tr>
<td></td>
<td>C.1.2 Not required until 12 hours after establishment of steady state operation.</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Perform SR 3.4.12.1.</td>
<td>Once per 24 hours</td>
</tr>
<tr>
<td></td>
<td>AND</td>
<td></td>
</tr>
<tr>
<td></td>
<td>C.2 Restore required containment atmosphere humidity monitor to OPERABLE status.</td>
<td>30 days</td>
</tr>
<tr>
<td>CONDITION</td>
<td>REQUIRED ACTION</td>
<td>COMPLETION TIME</td>
</tr>
<tr>
<td>-----------</td>
<td>----------------</td>
<td>-----------------</td>
</tr>
<tr>
<td>D. Required containment sump (level) monitor inoperable. AND Required containment atmosphere humidity monitor inoperable.</td>
<td>D.1 Restore required containment sump (level) monitor to OPERABLE status. OR D.2 Restore required containment atmosphere humidity monitor to OPERABLE status.</td>
<td>30 days</td>
</tr>
<tr>
<td>E. Required containment atmosphere radioactivity (particulate) monitor inoperable. AND Required containment atmosphere humidity monitor inoperable.</td>
<td>E.1 Restore required containment atmosphere radioactivity (particulate) monitor to OPERABLE status. OR E.2 Restore required containment atmosphere humidity monitor to OPERABLE status.</td>
<td>30 days</td>
</tr>
<tr>
<td>F. Required containment sump (level) monitor inoperable. AND Required containment atmosphere radioactivity (particulate) monitor inoperable.</td>
<td>F.1 Restore required containment sump (level) monitor to OPERABLE status. OR F.2 Restore required containment atmosphere radioactivity (particulate) monitor to OPERABLE status.</td>
<td>7 days</td>
</tr>
</tbody>
</table>
### ACTIONS (continued)

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>G. Required Action and associated Completion Time not met.</td>
<td>G.1 Be in MODE 3.</td>
<td>6 hours</td>
</tr>
<tr>
<td>AND</td>
<td>G.2 Be in MODE 5.</td>
<td>36 hours</td>
</tr>
<tr>
<td>H. All required monitors inoperable.</td>
<td>H.1 Enter LCO 3.0.3.</td>
<td>Immediately</td>
</tr>
</tbody>
</table>

### SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.4.14.1</td>
<td>Perform CHANNEL CHECK of the required containment atmosphere radioactivity (particulate) monitor.</td>
</tr>
<tr>
<td>SR 3.4.14.2</td>
<td>Perform CHANNEL CHECK of the required containment atmosphere humidity monitor.</td>
</tr>
<tr>
<td>SR 3.4.14.3</td>
<td>Perform CHANNEL FUNCTIONAL TEST of the required containment atmosphere (particulate) radioactivity monitor.</td>
</tr>
<tr>
<td>SR 3.4.14.4</td>
<td>Perform CHANNEL FUNCTIONAL TEST of the required containment atmosphere humidity monitor.</td>
</tr>
<tr>
<td>SR 3.4.14.5</td>
<td>Perform CHANNEL CALIBRATION of the required containment sump (level) monitor.</td>
</tr>
<tr>
<td>SR 3.4.14.6</td>
<td>Perform CHANNEL CALIBRATION of the required containment atmosphere radioactivity (particulate) monitor.</td>
</tr>
<tr>
<td>SURVEILLANCE REQUIREMENTS (continued)</td>
<td></td>
</tr>
<tr>
<td>--------------------------------------</td>
<td></td>
</tr>
<tr>
<td><strong>SURVEILLANCE</strong></td>
<td><strong>FREQUENCY</strong></td>
</tr>
<tr>
<td>SR 3.4.14.7</td>
<td>Perform CHANNEL CALIBRATION of the required containment atmosphere humidity monitor.</td>
</tr>
</tbody>
</table>
3.4 REACTOR COOLANT SYSTEM (RCS)

3.4.15 RCS Specific Activity

LCO 3.4.15 The specific activity of the reactor coolant shall be limited to:

a. DOSE EQUIVALENT I-131 specific activity \( \leq 3.7 \times 10^4 \text{ Bq/g} \) (1.0 \( \mu \text{Ci/g} \)) and

b. DOSE EQUIVALENT XE-133 specific activity \( \leq 1.11 \times 10^7 \text{ Bq/g} \) (297.3 \( \mu \text{Ci/g} \)).

APPLICABILITY: MODES 1, 2, 3 and 4.

ACTIONS

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
</table>
| A. DOSE EQUIVALENT I-131 > 3.7\( \times 10^4 \text{ Bq/g} \) (1.0 \( \mu \text{Ci/g} \)). | --------------------------NOTE--------------------------  
LCO 3.0.4 is not applicable.  
--------------------------| | Once per 4 hours |
| | A.1 Verify DOSE EQUIVALENT I-131 \( \leq 2.22 \times 10^6 \text{ Bq/g} \) (60 \( \mu \text{Ci/g} \)). | | |
| | AND | | |
| | A.2 Restore DOSE EQUIVALENT I-131 to within limit. | 48 hours |
| B. DOSE EQUIVALENT XE-133 > 1.11\( \times 10^7 \text{ Bq/g} \) (297.3 \( \mu \text{Ci/g} \)). | --------------------------NOTE--------------------------  
LCO 3.0.4 is not applicable.  
--------------------------| | 48 hours |
| | B.1 Restore DOSE EQUIVALENT XE-133 to within limit. | | |
### ACTIONS (continued)

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>C. Required Action and associated Completion Time of Condition A or B not met.</td>
<td>C.1 Be in MODE 3. AND C.2 Be in MODE 5.</td>
<td>6 hours AND 36 hours</td>
</tr>
<tr>
<td>OR</td>
<td></td>
<td></td>
</tr>
<tr>
<td>DOSE EQUIVALENT I-131 &gt; 2.22E6 Bq/g (60 µCi/g).</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

### SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.4.15.1</td>
<td>7 days</td>
</tr>
</tbody>
</table>

Verify reactor coolant DOSE EQUIVALENT XE-133 specific activity ≤ 1.11E7 Bq/g (297.3 µCi/g).

| SR 3.4.15.2 | 14 days |

Verify reactor coolant DOSE EQUIVALENT I-131 specific activity ≤ 3.70E4 Bq/g (1.0 µCi/g).

AND

Between 2 and 6 hours after a THERMAL POWER change of ≥ 15% RTP within a 1 hour period.
3.4 REACTOR COOLANT SYSTEM (RCS)

3.4.16 Reactor Coolant Gas Vent (RCGV) Function

LCO 3.4.16 The following RCGV flow paths shall be OPERABLE:

a. Two flow paths from the reactor vessel closure head to the in-containment refueling water storage tank (IRWST), and

b. Two flow paths from the pressurizer steam space to the IRWST.

APPLICABILITY: MODES 1, 2, and 3, MODE 4 with Shutdown Cooling (SC) System not aligned for Low Temperature Overpressure Protection (LTOP) of the reactor coolant pressure boundary (RCPB).

ACTIONS

Separate Condition entry is allowed for each RCGV flow path location.

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. One or both locations with one RCGV flow path inoperable.</td>
<td>A.1 Restore RCGV flow path to OPERABLE status.</td>
<td>72 hours</td>
</tr>
<tr>
<td>B. One or both locations with two RCGV flow paths inoperable.</td>
<td>B.1 Restore one RCGV flow path in each location to OPERABLE status.</td>
<td>6 hours</td>
</tr>
<tr>
<td>C. One or two RCGV valves in the common flow path to the IRWST inoperable.</td>
<td>C.1 Restore RCGV valve(s) in the common flow path to the IRWST to OPERABLE status.</td>
<td>6 hours</td>
</tr>
</tbody>
</table>
### ACTIONS (continued)

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>D. Required Action and associated Completion Time of Condition A, B, or C not met.</td>
<td>D.1 Be in MODE 3. <strong>AND</strong> D.2 Be in MODE 4 with SC System aligned for LTOP of the RCPB.</td>
<td>6 hours 12 hours</td>
</tr>
</tbody>
</table>

### SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.4.16.1 Cycle each RCGV valve to the fully closed and fully open position.</td>
<td>In accordance with the Inservice Testing Program</td>
</tr>
<tr>
<td>SR 3.4.16.2 Verify flow through the vent paths during venting.</td>
<td>18 months</td>
</tr>
<tr>
<td>SR 3.4.16.3 Verify the locally operated manual isolation valve from the reactor vessel closure head and the locally operated manual isolation valve from the pressurizer are locked in the open position.</td>
<td>18 months</td>
</tr>
<tr>
<td>SR 3.4.16.4 Verify for each RCGV valve that the solenoid power supply breaker is correctly aligned and position indication power is available.</td>
<td>7 days</td>
</tr>
</tbody>
</table>
### 3.4 REACTOR COOLANT SYSTEM (RCS)

#### 3.4.17 Steam Generator (SG) Tube Integrity

**LCO 3.4.17** SG tube integrity shall be maintained.

**AND**

All SG tubes satisfying the tube plugging criteria shall be plugged in accordance with the Steam Generator Program.

**APPLICABILITY:** MODES 1, 2, 3, and 4.

**ACTIONS**

---

**NOTE**

Separate Condition entry is allowed for each SG tube.

---

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. One or more SG tubes satisfying the tube plugging criteria and not plugged in accordance with the Steam Generator Program.</td>
<td>A.1 Verify tube integrity of affected tube(s) is maintained until next refueling outage or SG tube inspection.</td>
<td>7 days</td>
</tr>
<tr>
<td>AND</td>
<td>A.2 Plug affected tube(s) in accordance with Steam Generator Program.</td>
<td>Prior to entering MODE 4 following the next refueling outage or SG tube inspection</td>
</tr>
</tbody>
</table>

---
### ACTIONS (continued)

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>B. Required Action and associated Completion Time of Condition A not met.</td>
<td>B.1 Be in MODE 3. AND B.2 Be in MODE 5.</td>
<td>6 hours 36 hours</td>
</tr>
<tr>
<td>OR SG tube integrity not maintained.</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

### SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.4.17.1  Verify SG tube integrity in accordance with Steam Generator Program.</td>
<td>In accordance with Steam Generator Program</td>
</tr>
<tr>
<td>SR 3.4.17.2  Verify each inspected SG tube that satisfies tube plugging criteria is plugged in accordance with Steam Generator Program.</td>
<td>Prior to entering MODE 4 following a SG tube inspection</td>
</tr>
</tbody>
</table>
3.5 EMERGENCY CORE COOLING SYSTEM (ECCS)

3.5.1 Safety Injection Tanks (SITs)

LCO 3.5.1 Four SITs shall be OPERABLE.

APPLICABILITY: MODES 1 and 2, MODES 3 and 4 with pressurizer pressure $\geq 50.3 \text{ kg/cm}^2 \text{A (715 psia)}$.

## ACTIONS

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. One SIT inoperable due to boron concentration not within limits.</td>
<td>A.1 Restore SIT to OPERABLE status.</td>
<td>72 hours</td>
</tr>
<tr>
<td>OR</td>
<td>One SIT inoperable due to B-10 isotopic concentration not within limits.</td>
<td></td>
</tr>
<tr>
<td>OR</td>
<td>One SIT inoperable due to the inability to verify water level or pressure.</td>
<td></td>
</tr>
<tr>
<td>B. One SIT inoperable for reasons other than Condition A.</td>
<td>B.1 Restore SIT to OPERABLE status.</td>
<td>1 hour</td>
</tr>
<tr>
<td>C. Required Actions and associated Completion Times of Condition A or B not met.</td>
<td>C.1 Be in MODE 3.</td>
<td>6 hours</td>
</tr>
<tr>
<td>AND</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>C.2 Reduce pressurizer pressure to $&lt; 50.3 \text{ kg/cm}^2 \text{A (715 psia)}$.</td>
<td>12 hours</td>
</tr>
</tbody>
</table>
### ACTIONS (continued)

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>D. Two or more SITs inoperable.</td>
<td>D.1 Enter LCO 3.0.3.</td>
<td>Immediately</td>
</tr>
</tbody>
</table>

### SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.5.1.1</td>
<td>Verify each SIT isolation valve is fully open.</td>
</tr>
<tr>
<td>SR 3.5.1.2</td>
<td>Verify borated water volume in each SIT is ≥ 29% and ≤ 69% (% narrow range).</td>
</tr>
<tr>
<td>SR 3.5.1.3</td>
<td>Verify nitrogen cover-pressure in each SIT is ≥ 40.6 kg/cm²G (578 psig) and ≤ 43.9 kg/cm²G (624 psig).</td>
</tr>
</tbody>
</table>
### SURVEILLANCE REQUIREMENTS (continued)

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.5.1.4</td>
<td>Verify boron concentration in each SIT is ≥ 2,300 ppm and ≤ 4,400 ppm.</td>
</tr>
</tbody>
</table>
|              | AND       |\[
|              | NOTE------| Only required to be performed for affected SIT. |
|              |-----------|-------------------------|
|              | Once within 6 hours after each solution volume increase of ≥ 1% of tank volume that is not the result of addition from the in-containment refueling water storage tank | |
| SR 3.5.1.5   | Verify power is removed from each SIT isolation valve operator when pressurizer pressure is ≥ 50.3 kg/cm²A (715 psia). | 31 days |
| SR 3.5.1.6   | Verify isotopic concentration of B-10 in each SIT is within the limit specified in the COLR. | 24 months |
### 3.5 EMERGENCY CORE COOLING SYSTEM (ECCS)

#### 3.5.2 Safety Injection System (SIS) – Operating

**LCO 3.5.2** Four trains of SIS shall be OPERABLE.

**APPLICABILITY:** MODES 1, 2, and 3.

**ACTIONS**

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. One train inoperable.</td>
<td>A.1 Restore train to OPERABLE status.</td>
<td>72 hours</td>
</tr>
<tr>
<td>B. Two trains inoperable and diagonally oriented with respect to the reactor vessel (Trains 1 and 3, or Trains 2 and 4).</td>
<td>B.1 Verify two trains diagonally oriented with respect to the reactor vessel are OPERABLE. AND B.2 Restore trains to OPERABLE status.</td>
<td>1 hour 72 hours</td>
</tr>
<tr>
<td>C. Required Action and associated Completion Time of Condition A or B not met.</td>
<td>C.1 Be in MODE 3. AND C.2 Be in MODE 4.</td>
<td>6 hours 12 hours</td>
</tr>
<tr>
<td>D. Two or more trains inoperable for reasons other than Condition B.</td>
<td>D.1 Enter LCO 3.0.3.</td>
<td>Immediately</td>
</tr>
</tbody>
</table>
## SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>SR 3.5.2.1</strong> Verify the following hot leg injection isolation valves are locked in the close position: SI-321, SI-331, SI-604, and SI-609.</td>
<td>12 hours</td>
</tr>
</tbody>
</table>
| **SR 3.5.2.2** \[\begin{align*} &\text{---NOTE---} \\
&\text{Not required to be met for system vent flow paths opened under administrative control.} \\
&\text{---NOTE---}\end{align*}\] Verify each SIS manual, power-operated, and automatic valve in the flow path that is not locked, sealed, or otherwise secured in position is in correct position. | 31 days |
<p>| <strong>SR 3.5.2.3</strong> Verify SIS piping locations susceptible to gas accumulation are sufficiently filled with water. | 31 days |
| <strong>SR 3.5.2.4</strong> Verify each SIS pump develops required differential pressure on minimum flow of 123.8 kg/cm²D (1,761 psid). | In accordance with Inservice Testing Program |
| <strong>SR 3.5.2.5</strong> Verify each SIS pump develops a flow of ≥ 3,407 L/min (900 gpm) at a differential pressure ≥ 86.9 kg/cm²D (1,236 psid). | In accordance with Inservice Testing Program |
| <strong>SR 3.5.2.6</strong> Verify each SIS train automatic valve in the flow path actuates to correct position on an actual or simulated actuation signal. | 18 months |
| <strong>SR 3.5.2.7</strong> Verify each SIS pump starts automatically on an actual or simulated actuation signal. | 18 months |</p>
<table>
<thead>
<tr>
<th>SURVEILLANCE REQUIREMENTS (continued)</th>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.5.2.8</td>
<td>Verify, by inspection, that the IRWST, holdup volume tank (HVT), IRWST strainers, HVT trash racks and IRWST spillway are not restricted by debris and strainers and trash racks show no evidence of structural distress or abnormal corrosion.</td>
<td>18 months</td>
</tr>
</tbody>
</table>
3.5 EMERGENCY CORE COOLING SYSTEM (ECCS)

3.5.3 Safety Injection System (SIS) – Shutdown

LCO 3.5.3 Two trains of SIS diagonally oriented with respect to the reactor vessel shall be OPERABLE.

APPLICABILITY: MODES 4 and 5, MODE 6 with RCS level < 39.7 m (130 ft 0 in).

ACTIONS

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. Required SIS trains inoperable.</td>
<td>A.1 Restore required SIS trains to OPERABLE status.</td>
<td>1 hour</td>
</tr>
<tr>
<td>B. Required Action and associated Completion Time of Condition A not met.</td>
<td>B.1 Initiate actions to restore RCS level to ≥ 39.7 m (130 ft 0 in). AND B.2 Reduce RCS cold leg temperature to &lt; 57.2°C (135°F).</td>
<td>Immediately 24 hours</td>
</tr>
</tbody>
</table>
### SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>SR 3.5.3.1</strong> The following SRs are applicable:</td>
<td>In accordance with applicable SRs</td>
</tr>
<tr>
<td>SR 3.5.2.1,</td>
<td></td>
</tr>
<tr>
<td>SR 3.5.2.2,</td>
<td></td>
</tr>
<tr>
<td>SR 3.5.2.3,</td>
<td></td>
</tr>
<tr>
<td>SR 3.5.2.4,</td>
<td></td>
</tr>
<tr>
<td>SR 3.5.2.5,</td>
<td></td>
</tr>
<tr>
<td>SR 3.5.2.6,</td>
<td></td>
</tr>
<tr>
<td>SR 3.5.2.7, and</td>
<td></td>
</tr>
<tr>
<td>SR 3.5.2.8.</td>
<td></td>
</tr>
</tbody>
</table>
3.5 EMERGENCY CORE COOLING SYSTEM (ECCS)

3.5.4 In-Containment Refueling Water Storage Tank (IRWST)

LCO 3.5.4 The IRWST shall be OPERABLE.

APPLICABILITY: MODES 1, 2, 3, 4, and 5, MODE 6 with RCS level < 39.7 m (130 ft 0 in).

### ACTIONS

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. IRWST boron concentration not within limits. OR IRWST B-10 isotopic concentration not within limits. OR IRWST water temperature not within limits.</td>
<td>A.1 Restore IRWST to OPERABLE status.</td>
<td>8 hours</td>
</tr>
<tr>
<td>B. IRWST water volume not within limits.</td>
<td>B.1 Restore IRWST to OPERABLE status.</td>
<td>1 hour</td>
</tr>
<tr>
<td>C. Required Action and associated Completion Time of Condition A or B not met in MODE 1, 2, 3, or 4.</td>
<td>C.1 Be in MODE 3. AND C.2 Be in MODE 5.</td>
<td>6 hours 36 hours</td>
</tr>
</tbody>
</table>
## ACTIONS (continued)

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>D. Required Action and associated Completion Time of Condition A or B not met in MODE 5 or MODE 6 with RCS level &lt; 39.7 m (130 ft 0 in).</td>
<td>D.1 Initiate action to restore RCS level to ≥ 39.7 m (130 ft 0 in). AND D.2 Reduce RCS cold leg temperature to &lt; 57.2°C (135°F).</td>
<td>Immediately</td>
</tr>
</tbody>
</table>

## SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.5.4.1</td>
<td>Verify IRWST water temperature is ≥ 10°C (50°F) and ≤ 49°C (120°F).</td>
</tr>
<tr>
<td>SR 3.5.4.2</td>
<td>Verify IRWST water volume is ≥ 2,373.5 m³ (627,000 gal) and ≤ 2,540.6 m³ (671,162 gal) (i.e., ≥ 74.43% and ≤ 79.67%).</td>
</tr>
<tr>
<td>SR 3.5.4.3</td>
<td>Verify IRWST boron concentration is ≥ 4,000 ppm and ≤ 4,400 ppm.</td>
</tr>
<tr>
<td>SR 3.5.4.4</td>
<td>Verify isotopic concentration of B-10 in the IRWST is within the limit specified in the COLR.</td>
</tr>
</tbody>
</table>
3.5 EMERGENCY CORE COOLING SYSTEM (ECCS)

3.5.5 Trisodium Phosphate (TSP)

LCO 3.5.5 The TSP baskets shall contain $\geq 29.5$ m$^3$ (1,042 ft$^3$) of active TSP.

APPLICABILITY: MODES 1, 2, and 3.

ACTIONS

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. TSP not within limit.</td>
<td>A.1 Restore TSP to within limits.</td>
<td>72 hours</td>
</tr>
<tr>
<td>B. Required Action and associated Completion Time not met.</td>
<td>B.1 Be in MODE 3. AND B.2 Be in MODE 4.</td>
<td>6 hours 12 hours</td>
</tr>
</tbody>
</table>

SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.5.5.1 Verify the TSP baskets contain $\geq 29.5$ m$^3$ (1,042 ft$^3$) of TSP.</td>
<td>18 months</td>
</tr>
<tr>
<td>SR 3.5.5.2 Verify that a sample from the TSP baskets provides adequate pH adjustment of IRWST water.</td>
<td>18 months</td>
</tr>
</tbody>
</table>
3.6 CONTAINMENT SYSTEMS

3.6.1 Containment

LCO 3.6.1 Containment shall be OPERABLE.

APPLICABILITY: MODES 1, 2, 3, and 4.

ACTIONS

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. Containment inoperable.</td>
<td>A.1 Restore containment to OPERABLE status.</td>
<td>1 hour</td>
</tr>
<tr>
<td>B. Required Action and associated Completion Time not met.</td>
<td>B.1 Be in MODE 3. AND B.2 Be in MODE 5.</td>
<td>6 hours AND 36 hours</td>
</tr>
</tbody>
</table>

SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.6.1.1 Perform required visual examinations and leakage rate testing, except for containment air lock testing, in accordance with Containment Leakage Rate Testing Program.</td>
<td>In accordance with Containment Leakage Rate Testing Program</td>
</tr>
<tr>
<td>SR 3.6.1.2 Verify containment structural integrity in accordance with Containment Tendon Surveillance Program.</td>
<td>In accordance with Containment Tendon Surveillance Program</td>
</tr>
</tbody>
</table>
3.6 CONTAINMENT SYSTEMS

3.6.2 Containment Air Locks

LCO 3.6.2 Two Containment Air Locks shall be OPERABLE.

APPLICABILITY: MODES 1, 2, 3, and 4.

ACTIONS

-----------------------------------------------------------NOTES----------------------------------------------------------

1. Entry and exit are permissible to perform repairs on affected personnel lock components.

2. Separate Condition entry is allowed for each air lock.

3. Enter applicable Conditions and Required Actions of LCO 3.6.1, “Containment,” when leakage results in exceeding the overall containment leakage rate acceptance criteria.

-------------------------------------------------------------------------------------------------------------------------------

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
</table>
| A. One or more containment air locks with one containment air lock door inoperable. | -----------NOTES-----------
<p>| | 1. Required Actions A.1, A.2, and A.3 are not applicable if both doors in the same air lock are inoperable and Condition C is entered. | 1 hour |
| | 2. Entry and exit are permissible for 7 days under administrative controls if both air locks are inoperable. | |
| A.1 | Verify OPERABLE door is closed in affected air lock. | |
| AND | |
| A.2 | Lock OPERABLE door closed in affected air lock. | 24 hours |
| AND | |</p>
<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
</table>
| A. (continued)            | A.3  ![NOTE](https://example.com)  
Air lock doors in high radiation areas may be verified locked closed by administrative means.  
Verify OPERABLE door is locked closed in affected air lock. | Once per 31 days      |
|                           | B. One or more containment air locks with containment air lock interlock mechanism inoperable. |                       |
|                           | ![NOTES](https://example.com)  
1. Required Actions B.1, B.2, and B.3 are not applicable if both doors in the same air lock are inoperable and Condition C is entered.  
2. Entry and exit of containment are permissible under control of a dedicated individual. |                       |
|                           | B.1 Verify an OPERABLE door is closed in affected air lock. | 1 hour                |
|                           | AND                                                                                 |                       |
|                           | B.2 Lock an OPERABLE door closed in affected air lock. | 24 hours              |
### ACTIONS (continued)

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>B. (continued)</strong></td>
<td><strong>B.3</strong></td>
<td>Once per 31 days</td>
</tr>
<tr>
<td></td>
<td><strong>NOTE</strong> Air lock doors in high radiation areas may be verified locked closed by administrative means.</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Verify OPERABLE door is locked closed in affected air lock.</td>
<td></td>
</tr>
</tbody>
</table>

| **C.** One or more containment air locks inoperative for reasons other than Condition A or B. | **C.1** | Immediately |
| | Initiate action to evaluate overall containment leakage rate per LCO 3.6.1. | |
| | **AND** | |
| | **C.2** | 1 hour |
| | Verify a door is closed in affected air lock. | |
| | **AND** | |
| | **C.3** | 24 hours |
| | Restore air lock to OPERABLE status. | |

| **D.** Required Action and associated Completion Time not met. | **D.1** | 6 hours |
| | Be in MODE 3. | |
| | **AND** | |
| | **D.2** | 36 hours |
| | Be in MODE 5. | |
### SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>SR 3.6.2.1</strong></td>
<td>NOTES</td>
</tr>
<tr>
<td>1. An inoperable air lock door does not invalidate previous successful performance of an overall air lock leakage test.</td>
<td>In accordance with Containment Leakage Rate Testing Program</td>
</tr>
<tr>
<td>2. Results shall be evaluated against acceptance criteria of SR 3.6.1.1.</td>
<td></td>
</tr>
<tr>
<td>Perform required air lock leakage rate testing in accordance with the Containment Leakage Rate Testing Program.</td>
<td></td>
</tr>
<tr>
<td><strong>SR 3.6.2.2</strong></td>
<td></td>
</tr>
<tr>
<td>Verify only one door in the air lock can be opened at a time.</td>
<td>24 months</td>
</tr>
</tbody>
</table>
3.6 CONTAINMENT SYSTEMS

3.6.3 Containment Isolation Valves

LCO 3.6.3 Each containment isolation valve shall be OPERABLE.

APPLICABILITY: MODES 1, 2, 3, and 4.

ACTIONS

1. Penetration flow paths (except for 1219.2 mm (48 in) purge valve penetration flow paths) may be unisolated intermittently under administrative controls.

2. Separate Condition entry is allowed for each penetration flow path.

3. Enter applicable Conditions and Required Actions for system(s) made inoperable by containment isolation valves.

4. Enter applicable Conditions and Required Actions of LCO 3.6.1, “Containment,” when leakage results in exceeding the overall containment leakage rate acceptance criteria.

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A.</td>
<td></td>
<td>4 hours</td>
</tr>
<tr>
<td>A.1</td>
<td>Isolate affected penetration flow path by use of at least one closed and deactivated automatic valve, closed manual valve, blind flange, or check valve with flow through the valve secured.</td>
<td></td>
</tr>
<tr>
<td>AND</td>
<td></td>
<td></td>
</tr>
<tr>
<td>A.---------NOTE-------- Only applicable to penetration flow paths with two or more containment isolation valves.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>One or more penetration flow paths with one containment isolation valve inoperable (except for purge valve leakage not within limit).</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
### ACTIONS (continued)

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>A. (continued)</strong></td>
<td><strong>A.2</strong> --------------NOTES------------</td>
<td></td>
</tr>
<tr>
<td></td>
<td>1. Isolation devices in high radiation areas may be verified by use of administrative means.</td>
<td></td>
</tr>
<tr>
<td></td>
<td>2. Isolation devices that are locked, sealed, or otherwise secured may be verified by use of administrative means.</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Verify affected penetration flow path is isolated.</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Once per 31 days for isolation device outside containment AND Prior to entering MODE 4 from MODE 5 if not performed within the previous 92 days for isolation device inside containment</td>
<td></td>
</tr>
</tbody>
</table>

| **B. ------------NOTE------------** | **B.1** Isolate affected penetration flow path by use of at least one closed and deactivated automatic valve, closed manual valve, blind flange, or check valve with flow through the valve secured. | 1 hour |
| Only applicable to those penetration flow paths with two or more containment isolation valves. | | |
| One or more penetration flow paths with two containment isolation valves inoperable (except for purge valve leakage not within limit). | | |
# ACTIONS (continued)

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>C. ---------------NOTE------------ Only applicable to those penetration flow paths with only one containment isolation valve and a closed system.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>One or more penetration flow paths with one containment isolation valve inoperable.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>C.1 Isolate affected penetration flow path by use of at least one closed and deactivated automatic valve, closed manual valve, or blind flange.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>AND</td>
<td>C.2 ---------------NOTE------------- Isolation devices in high radiation areas may be verified by use of administrative means.</td>
<td></td>
</tr>
<tr>
<td>Verify affected penetration flow path is isolated.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>4 hours</td>
<td>24 hours</td>
<td></td>
</tr>
<tr>
<td>D. One or more penetration flow paths with one or more containment purge valves not within purge valve leakage limits.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>D.1 Isolate affected penetration flow path by use of at least one closed and deactivated automatic valve with resilient seals, closed manual valve with resilient seals, or blind flange.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>CONDITION</td>
<td>REQUIRED ACTION</td>
<td>COMPLETION TIME</td>
</tr>
<tr>
<td>-----------</td>
<td>----------------</td>
<td>----------------</td>
</tr>
<tr>
<td>D. (continued)</td>
<td>D.2 -----------NOTES-----------&lt;br&gt;1. Isolation devices in high radiation areas may be verified by use of administrative means.&lt;br&gt;2. Isolation devices that are locked, sealed, or otherwise secured may be verified by use of administrative means.</td>
<td>Once per 31 days for isolation devices outside containment AND Prior to entering MODE 4 from MODE 5 if not performed within the previous 92 days for isolation devices inside containment</td>
</tr>
<tr>
<td></td>
<td>D.3 Perform SR 3.6.3.6 for resilient seal purge valves closed to comply with Required Action D.1.</td>
<td>Once per 92 days</td>
</tr>
<tr>
<td>E. Required Action and associated Completion Time not met.</td>
<td>E.1 Be in MODE 3.</td>
<td>6 hours</td>
</tr>
<tr>
<td></td>
<td>E.2 Be in MODE 5.</td>
<td>36 hours</td>
</tr>
<tr>
<td>SURVEILLANCE REQUIREMENTS</td>
<td></td>
<td></td>
</tr>
<tr>
<td>---------------------------</td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>SURVEILLANCE</strong></td>
<td><strong>FREQUENCY</strong></td>
<td></td>
</tr>
<tr>
<td>SR 3.6.3.1</td>
<td>Verify each 1219.2 mm (48 in) purge valve is sealed closed except for one purge valve in a penetration flow path while in Condition D of this LCO.</td>
<td>31 days</td>
</tr>
<tr>
<td>SR 3.6.3.2</td>
<td>Verify each 203.2 mm (8 in) purge valve is closed, except when the purge valves are open for pressure control, ALARA, or air quality considerations for personnel entry, or for Surveillances that require the valves to be open.</td>
<td>31 days</td>
</tr>
<tr>
<td>SR 3.6.3.3</td>
<td>-------------------NOTE-------------------</td>
<td>31 days</td>
</tr>
<tr>
<td></td>
<td>Valves and blind flanges in high radiation areas may be verified by use of administrative means.</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Verify each containment isolation manual valve and blind flange that is located outside containment and not locked, sealed, or otherwise secured and is required to be closed during accident conditions is closed, except for containment isolation valves that are open under administrative controls.</td>
<td></td>
</tr>
<tr>
<td>SR 3.6.3.4</td>
<td>-------------------NOTE-------------------</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Valves and blind flanges in high radiation areas may be verified by use of administrative means.</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Verify each containment isolation manual valve and blind flange that is located inside containment and not locked, sealed, or otherwise secured and is required to be closed during accident conditions is closed, except for containment isolation valves that are open under administrative controls.</td>
<td>Prior to entering MODE 4 from MODE 5 if not performed within the previous 92 days</td>
</tr>
<tr>
<td>SR 3.6.3.5</td>
<td>Verify isolation time of each automatic power-operated containment isolation valve is within limits.</td>
<td>In accordance with Inservice Testing Program</td>
</tr>
<tr>
<td>SURVEILLANCE REQUIREMENTS (continued)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>-------------------------------------</td>
<td></td>
<td></td>
</tr>
<tr>
<td>SURVEILLANCE</td>
<td>FREQUENCY</td>
<td></td>
</tr>
<tr>
<td>SR  3.6.3.6  Perform leakage rate testing for containment purge valves with resilient seals.</td>
<td>184 days</td>
<td></td>
</tr>
<tr>
<td>AND  Within 92 days after opening the valve</td>
<td></td>
<td></td>
</tr>
<tr>
<td>SR  3.6.3.7  Verify each automatic containment isolation valve that is not locked, sealed, or otherwise secured in position, actuates to isolation position on an actual or simulated actuation signal.</td>
<td>18 months</td>
<td></td>
</tr>
</tbody>
</table>
3.6 CONTAINMENT SYSTEMS

3.6.4 Containment Pressure

LCO 3.6.4 Containment pressure shall be \( \geq -0.007 \text{ kg/cm}^2 \text{G} (-0.1 \text{ psig}) \) and \( \leq +0.07 \text{ kg/cm}^2 \text{G} (+1.0 \text{ psig}) \).

APPLICABILITY: MODES 1, 2, 3, and 4.

ACTIONS

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. Containment pressure not within limits.</td>
<td>A.1 Restore containment pressure within limits.</td>
<td>1 hour</td>
</tr>
<tr>
<td>B. Required Action and associated Completion Time not met.</td>
<td>B.1 Be in MODE 3. AND B.2 Be in MODE 5.</td>
<td>6 hours 36 hours</td>
</tr>
</tbody>
</table>

SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.6.4.1 Verify containment pressure is within limits.</td>
<td>12 hours</td>
</tr>
</tbody>
</table>
3.6 CONTAINMENT SYSTEMS

3.6.5 Containment Air Temperature

LCO 3.6.5 Containment average air temperature shall be ≤ 49°C (120°F).

APPLICABILITY: MODES 1, 2, 3 and 4.

ACTIONS

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. Containment average air temperature not within limit.</td>
<td>A.1 Restore containment average air temperature within limit.</td>
<td>8 hours</td>
</tr>
<tr>
<td>B. Required Action and associated Completion Time not met.</td>
<td>B.1 Be in MODE 3.</td>
<td>6 hours</td>
</tr>
<tr>
<td></td>
<td>AND</td>
<td></td>
</tr>
<tr>
<td></td>
<td>B.2 Be in MODE 5.</td>
<td>36 hours</td>
</tr>
</tbody>
</table>

SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.6.5.1</td>
<td>Verify containment average air temperature is within limit.</td>
</tr>
</tbody>
</table>
3.6 CONTAINMENT SYSTEMS

3.6.6 Containment Spray System

LCO 3.6.6 Two Containment Spray divisions shall be OPERABLE.

APPLICABILITY: MODES 1, 2, 3, and 4.

**ACTIONS**

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. One containment spray division inoperable.</td>
<td>A.1 Restore containment spray division to OPERABLE status.</td>
<td>72 hours</td>
</tr>
<tr>
<td>B. Required Action and associated Completion Time of Condition A not met.</td>
<td>B.1 Be in MODE 3. AND B.2 Be in MODE 5.</td>
<td>6 hours 84 hours</td>
</tr>
<tr>
<td>C. Two containment spray divisions inoperable.</td>
<td>C.1 Enter LCO 3.0.3.</td>
<td>Immediately</td>
</tr>
</tbody>
</table>

**SURVEILLANCE REQUIREMENTS**

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.6.6.1</td>
<td>31 days</td>
</tr>
</tbody>
</table>

---

Not required to be met for system vent flow paths opened under administrative control.

Verify each containment spray manual, power-operated, and automatic valve in the flow path that is not locked, sealed, or otherwise secured in position is in correct position.
<table>
<thead>
<tr>
<th>SURVEILLANCE REQUIREMENTS (continued)</th>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.6.6.2 Verify each containment spray pump's developed head at the flow test point is greater than or equal to the required developed head.</td>
<td>In accordance with Inservice Testing Program</td>
<td></td>
</tr>
<tr>
<td>SR 3.6.6.3 Verify each automatic containment spray valve in the flow path that is not locked, sealed, or otherwise secured in position, actuates to the correct position on an actual or simulated actuation signal.</td>
<td>18 months</td>
<td></td>
</tr>
<tr>
<td>SR 3.6.6.4 Verify each containment spray pump starts automatically on an actual or simulated actuation signal.</td>
<td>18 months</td>
<td></td>
</tr>
<tr>
<td>SR 3.6.6.5 Verify each spray nozzle is unobstructed.</td>
<td>At first fuel loading AND 10 years</td>
<td></td>
</tr>
<tr>
<td>SR 3.6.6.6 Verify the containment spray piping is full of water to the 26.213 m (86 ft) level in the containment spray header.</td>
<td>31 days</td>
<td></td>
</tr>
<tr>
<td>SR 3.6.6.7 Verify containment spray locations susceptible to gas accumulation are sufficiently filled with water.</td>
<td>31 days</td>
<td></td>
</tr>
</tbody>
</table>
3.6 CONTAINMENT SYSTEMS

3.6.7 Containment Penetrations - Shutdown Operations

LCO 3.6.7  The containment building penetrations shall be in the following status:

- a. The equipment hatch closed and held in place by a minimum of [four bolts,]
- b. One door in each airlock closed,
- c. Each penetration providing direct access from the containment atmosphere to the outside atmosphere is either:
  1. Closed by a manual or automatic isolation valve, or blind flange, or
  2. Exhausting through OPERABLE Containment Purge System air cleaning units (ACUs), and is capable of being closed by an OPERABLE Containment Purge and Exhaust Isolation System.

APPLICABILITY: MODE 5 with any Reactor Coolant System (RCS) loop not filled, MODE 6 with the water level $< 7.0$ m (23 ft) above the top of the reactor vessel flange.

---------------------------------------------NOTE---------------------------------------------
The equipment hatch shall be closed and held in place by a minimum of [four bolts] before opening the pressurizer manway in MODE 5.

--------------------------------------------------------------------------------------------------

ACTIONS

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. One or more containment penetrations not in required status.</td>
<td>A.1 Restore containment penetration to required status.</td>
<td>4 hours</td>
</tr>
<tr>
<td>B. Required Action and associated Completion Time not met.</td>
<td>B.1 Raise RCS level to $&gt; 38.72$ m (127 ft 1/4 in).</td>
<td>6 hours</td>
</tr>
</tbody>
</table>

APR1400 GTS 3.6.7-1 Rev. 3
## SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.6.7.1 Verify each required containment building penetration is in its required status.</td>
<td>12 hours</td>
</tr>
<tr>
<td>SR 3.6.7.2 Verify each required containment purge and exhaust valve actuates to the isolation position on an actual or simulated actuation signal.</td>
<td>18 months</td>
</tr>
</tbody>
</table>
3.7 PLANT SYSTEMS

3.7.1 Main Steam Safety Valves (MSSVs)

LCO 3.7.1 The MSSVs shall be OPERABLE as specified in Tables 3.7.1-1 and 3.7.1-2.

APPLICABILITY: MODES 1, 2, and 3.

**ACTIONS**

---NOTE---

Separate Condition entry is allowed for each MSSV.

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. One or more required MSSVs inoperable.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>A.1</td>
<td>Reduce power to less than or equal to applicable % RTP listed in Table 3.7.1-1.</td>
<td>4 hours</td>
</tr>
<tr>
<td>AND</td>
<td></td>
<td></td>
</tr>
<tr>
<td>A.2</td>
<td>Reduce maximum variable overpower trip setpoint in accordance with Table 3.7.1-1.</td>
<td>36 hours</td>
</tr>
<tr>
<td>B. Required Action and associated Completion Time not met.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>B.1</td>
<td>Be in MODE 3.</td>
<td>6 hours</td>
</tr>
<tr>
<td>AND</td>
<td></td>
<td></td>
</tr>
<tr>
<td>B.2</td>
<td>Be in MODE 4.</td>
<td>24 hours</td>
</tr>
</tbody>
</table>

OR

One or more steam generators with less than five MSSVs OPERABLE.
### SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>SR 3.7.1.1</strong></td>
<td><strong>NOTE</strong></td>
</tr>
<tr>
<td>Only required to be performed in MODES 1 and 2.</td>
<td>In accordance with In-service Testing Program.</td>
</tr>
<tr>
<td>Verify each required MSSV is within ±3% of the lift setting value stated in Table 3.7.1-2, in accordance with the In-service Testing Program. If the lift setting is found to be outside the calibration tolerance of ±1% of the lift setting value stated in Table 3.7.1-2, the valve lift setting shall be reset to within the calibration tolerance.</td>
<td></td>
</tr>
<tr>
<td>MINIMUM NUMBER OF MSSVs PER STEAM GENERATOR REQUIRED OPERABLE</td>
<td>MAXIMUM POWER (% RTP)</td>
</tr>
<tr>
<td>---------------------------------------------------------------</td>
<td>------------------------</td>
</tr>
<tr>
<td>10</td>
<td>100.0</td>
</tr>
<tr>
<td>9</td>
<td>96.8</td>
</tr>
<tr>
<td>8</td>
<td>86.0</td>
</tr>
<tr>
<td>7</td>
<td>75.3</td>
</tr>
<tr>
<td>6</td>
<td>64.5</td>
</tr>
<tr>
<td>5</td>
<td>53.8</td>
</tr>
<tr>
<td>VALVE NUMBER</td>
<td>LIFT SETTING (psig ±1%)</td>
</tr>
<tr>
<td>--------------</td>
<td>-------------------------</td>
</tr>
<tr>
<td>V1301</td>
<td>V1311 1,174</td>
</tr>
<tr>
<td>V1303</td>
<td>V1313 1,205</td>
</tr>
<tr>
<td>V1305</td>
<td>V1315 1,230</td>
</tr>
<tr>
<td>V1307</td>
<td>V1317 1,230</td>
</tr>
<tr>
<td>V1309</td>
<td>V1319 1,230</td>
</tr>
<tr>
<td>V1302</td>
<td>V1312 1,174</td>
</tr>
<tr>
<td>V1304</td>
<td>V1314 1,205</td>
</tr>
<tr>
<td>V1306</td>
<td>V1316 1,230</td>
</tr>
<tr>
<td>V1308</td>
<td>V1318 1,230</td>
</tr>
<tr>
<td>V1310</td>
<td>V1320 1,230</td>
</tr>
</tbody>
</table>

---NOTE---
Each MSSV’s as-found lift setting shall be within ±3% of the lift setting value stated in Table 3.7.1-2 for the valve to be considered OPERABLE. The valve’s lift setting shall be reset to within the calibration tolerance of ±1% of the lift setting value stated in Table 3.7.1-2 if the lift setting is found to be outside the calibration tolerance.
### 3.7 PLANT SYSTEMS

#### 3.7.2 Main Steam Isolation Valves (MSIVs)

**LCO 3.7.2**

Four MSIVs shall be OPERABLE.

**APPLICABILITY:** MODE 1, MODES 2 and 3 except when all MSIVs are closed and de-activated.

**ACTIONS**

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. One MSIV inoperable in MODE 1.</td>
<td>A.1 Restore MSIV to OPERABLE status.</td>
<td>4 hours</td>
</tr>
<tr>
<td>B. Required Action and associated Completion Time of Condition A not met.</td>
<td>B.1 Be in MODE 2.</td>
<td>6 hours</td>
</tr>
<tr>
<td>C. -----------NOTE------------ Separate Condition entry is allowed for each MSIV. One or more MSIVs inoperable in MODE 2 or 3.</td>
<td>C.1 Close MSIV. AND C.2 Verify MSIV is closed.</td>
<td>4 hours Once per 7 days</td>
</tr>
<tr>
<td>D. Required Action and associated Completion Time of Condition C not met.</td>
<td>D.1 Be in MODE 3. AND D.2 Be in MODE 4.</td>
<td>6 hours 12 hours</td>
</tr>
</tbody>
</table>
## SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>SR 3.7.2.1</strong></td>
<td><strong>NOTE</strong> Only required to be performed in MODES 1 and 2. Verify isolation time of each MSIV is within limits.</td>
</tr>
<tr>
<td><strong>SR 3.7.2.2</strong></td>
<td><strong>NOTE</strong> Only required to be performed in MODES 1 and 2. Verify each MSIV actuates to isolation position on an actual or simulated actuation signal.</td>
</tr>
</tbody>
</table>
3.7 PLANT SYSTEMS

3.7.3 Main Feedwater Isolation Valves (MFIVs)

LCO 3.7.3 Two MFIVs shall be OPERABLE.

APPLICABILITY: MODES 1, 2, and 3 except when MFIV is closed.

ACTIONS

-------------------------------------------------------------------------------------------------------------------------------
<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. One or more MFIVs inoperable.</td>
<td>A.1 Close or isolate inoperable MFIV.</td>
<td>72 hours</td>
</tr>
<tr>
<td>AND</td>
<td>A.2 Verify inoperable MFIV is closed or isolated.</td>
<td>Once per 7 days</td>
</tr>
<tr>
<td>B. Two valves in the same flow path inoperable.</td>
<td>B.1 Isolate affected flow path.</td>
<td>8 hours</td>
</tr>
<tr>
<td>AND</td>
<td>B.2 Verify inoperable MFIV is closed or isolated.</td>
<td>Once per 7 days</td>
</tr>
<tr>
<td>C. Required Action and associated Completion Time not met.</td>
<td>C.1 Be in MODE 3.</td>
<td>6 hours</td>
</tr>
<tr>
<td>AND</td>
<td>C.2 Be in MODE 4.</td>
<td>12 hours</td>
</tr>
</tbody>
</table>

-------------------------------------------------------------------------------------------------------------------------------
### SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.7.3.1 Verify isolation time of each MFIV is within limits.</td>
<td>In accordance with Inservice Testing Program</td>
</tr>
<tr>
<td>SR 3.7.3.2 Verify each MFIV actuates to isolation position on an actual or simulated actuation signal.</td>
<td>18 months</td>
</tr>
</tbody>
</table>
3.7 PLANT SYSTEMS

3.7.4 Main Steam Atmospheric Dump Valves (MSADVs)

LCO 3.7.4 Two MSADV lines per steam generator shall be OPERABLE.

APPLICABILITY: MODES 1, 2, and 3, MODE 4 when a steam generator is being relied upon for heat removal.

ACTIONS

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. One MSADV line inoperable.</td>
<td>A.1 -----------NOTE----------- LCO 3.0.4 is not applicable.</td>
<td>7 days</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>Restore MSADV line to OPERABLE status.</td>
<td></td>
</tr>
<tr>
<td>B. Two MSADV lines inoperable.</td>
<td>B.1 Restore one MSADV line to OPERABLE status.</td>
<td>24 hours</td>
</tr>
<tr>
<td>C. Required Action and associated Completion Time not met.</td>
<td>C.1 Be in MODE 3. AND</td>
<td>6 hours</td>
</tr>
<tr>
<td></td>
<td>C.2 Be in MODE 4 without reliance upon steam generators for heat removal.</td>
<td>24 hours</td>
</tr>
</tbody>
</table>

SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.7.4.1 Verify one complete cycle of each MSADV.</td>
<td>18 months</td>
</tr>
</tbody>
</table>

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**SURVEILLANCE REQUIREMENTS (continued)**

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.7.4.2 Verify one complete cycle of each MSADV block valve.</td>
<td>18 months</td>
</tr>
</tbody>
</table>
3.7 PLANT SYSTEMS

3.7.5 Auxiliary Feedwater System (AFWS)

LCO 3.7.5 Two auxiliary feedwater (AFW) divisions, each with one motor driven train and one turbine driven train, shall be OPERABLE.

---NOTE---
Only the motor driven train of one AFW division is required to be OPERABLE in MODE 4.

------------------APPLICABILITY:-------------------
MODES 1, 2, and 3, MODE 4 when a steam generator is relied upon for heat removal.

---ACTIONS---

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. One AFW division with one train inoperable in MODE 1, 2, or 3.</td>
<td>A.1 Restore train to OPERABLE status.</td>
<td>[72] hours</td>
</tr>
<tr>
<td>B. Two AFW divisions with one train inoperable in MODE 1, 2, or 3.</td>
<td>B.1 Restore two trains of an AFW division to OPERABLE status.</td>
<td>72 hours</td>
</tr>
<tr>
<td>C. One AFW division with two trains inoperable in MODE 1, 2, or 3.</td>
<td>C.1 Restore one train of affected AFW division to OPERABLE status.</td>
<td>[24] hours</td>
</tr>
</tbody>
</table>
### ACTIONS (continued)

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>D.</strong> Required Action and associated Completion Time of Condition A, B, or C not met. OR Three AFW trains inoperable in MODE 1, 2, or 3.</td>
<td><strong>D.1</strong> Be in MODE 3. <strong>AND</strong> <strong>D.2</strong> Be in MODE 4 without reliance upon SGs for heat removal.</td>
<td><strong>6 hours</strong> <strong>18 hours</strong></td>
</tr>
</tbody>
</table>

---

| **E.** Four AFW trains inoperable in MODE 1, 2, or 3. | **NOTE** LCO 3.0.3 and all other LCO Required Actions requiring MODE changes are suspended until one AFW train is restored to OPERABLE status. | **E.1** Initiate action to restore one AFW train to OPERABLE status. | **Immediately** |

---

| **F.** Two AFW motor driven trains inoperable in MODE 4. | **NOTE** LCO 3.0.3 and all other LCO Required Actions requiring MODE changes are suspended until one AFW motor driven train is restored to OPERABLE status. | **F.1** Initiate action to restore one AFW motor driven train to OPERABLE status. | **Immediately** |
### SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>SR 3.7.5.1</strong></td>
<td>Verify each manual, power-operated, and automatic valve in the flow path of each AFW train and in the steam supply flow path of each AFW turbine driven pump, that is not locked, sealed, or otherwise secured in position, is in the correct position.</td>
</tr>
<tr>
<td><strong>SR 3.7.5.2</strong></td>
<td>Verify developed head of each AFW pump at flow test point is greater than or equal to required developed head.</td>
</tr>
<tr>
<td><strong>SR 3.7.5.3</strong></td>
<td>Verify each AFW automatic valve that is not locked, sealed, or otherwise secured in position, actuates to the correct position on an actual or simulated actuation signal.</td>
</tr>
<tr>
<td><strong>SR 3.7.5.4</strong></td>
<td>Verify each AFW pump starts automatically on an actual or simulated actuation signal.</td>
</tr>
</tbody>
</table>

**NOTE**

- Not required to be performed for AFW turbine driven pumps until 24 hours after reaching 69.25 kg/cm²G (985 psig) in steam generators.
- Not required to be met in MODE 4 when steam generator is relied upon for heat removal.

**NOTES**

1. Not required to be performed for AFW turbine driven pumps until 24 hours after reaching 69.25 kg/cm²G (985 psig) in steam generators.
2. Not required to be met in MODE 4 when steam generator is relied upon for heat removal.
<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR  3.7.5.5 Verify proper alignment of required</td>
<td>Prior to entering MODE 2 whenever the unit has been in MODE 5 or 6, or</td>
</tr>
<tr>
<td>flow paths of each train of each AFW division by</td>
<td>defueled for a cumulative period of &gt; 30 days.</td>
</tr>
<tr>
<td>verifying flow from the associated auxiliary</td>
<td></td>
</tr>
<tr>
<td>feedwater storage tank to the associated steam</td>
<td></td>
</tr>
<tr>
<td>generator.</td>
<td></td>
</tr>
</tbody>
</table>
3.7 PLANT SYSTEMS

3.7.6 Auxiliary Feedwater Storage Tank (AFWST)

LCO 3.7.6 Two AFWSTs shall be OPERABLE.

APPLICABILITY: MODES 1, 2, and 3, MODE 4 when a steam generator is relied upon for heat removal.

ACTIONS

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. One AFWST inoperable.</td>
<td>A.1 Verify OPERABILITY of backup water supply and the other AFWST.</td>
<td>4 hours AND Once per 12 hours thereafter</td>
</tr>
<tr>
<td></td>
<td>A.2 Restore AFWST to OPERABLE status.</td>
<td>7 days</td>
</tr>
<tr>
<td>B. Required Action and associated Completion Time not met.</td>
<td>B.1 Be in MODE 3.</td>
<td>6 hours AND</td>
</tr>
</tbody>
</table>

SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.7.6.1</td>
<td>Verify each AFWST level is ≥ 1,524,165 L (400,000 gal).</td>
</tr>
</tbody>
</table>
# Component Cooling Water System (CCWS)

## LCO 3.7.7

Two component cooling water (CCW) divisions shall be OPERABLE.

### APPLICABILITY:

MODES 1, 2, 3, and 4.

### ACTIONS

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
</table>
| A. One CCW division inoperable. | \------------------------NOTES------------------------
1. Enter applicable Conditions and Required Actions of LCO 3.8.1, “AC Sources – Operating,” for emergency diesel generator made inoperable by CCW.  
2. Enter applicable Conditions and Required Actions of LCO 3.4.6, “RCS Loops – MODE 4,” for shutdown cooling made inoperable by CCW. | 72 hours |
| A.1 Restore CCW division to OPERABLE status. | |
| B. Required Action and associated Completion Time of Condition A not met. | B.1 Be in MODE 3.  
AND  
B.2 Be in MODE 5. | 6 hours  
36 hours |
# SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.7.7.1</td>
<td>31 days</td>
</tr>
<tr>
<td></td>
<td></td>
</tr>
<tr>
<td>NOTE</td>
<td></td>
</tr>
<tr>
<td>Isolation of CCW flow to individual components does not render the CCWS inoperable.</td>
<td></td>
</tr>
<tr>
<td>Verify each CCW manual, power-operated, and automatic valve in the flow path servicing safety-related equipment that is not locked, sealed, or otherwise secured in position, is in correct position.</td>
<td></td>
</tr>
<tr>
<td>SR 3.7.7.2</td>
<td>18 months</td>
</tr>
<tr>
<td>Verify each CCW automatic valve in the flow path that is not locked, sealed, or otherwise secured in position, actuates to correct position on actual or simulated actuation signal.</td>
<td></td>
</tr>
<tr>
<td>SR 3.7.7.3</td>
<td>18 months</td>
</tr>
<tr>
<td>Verify each CCW pump starts automatically on an actual or simulated actuation signal.</td>
<td></td>
</tr>
</tbody>
</table>
3.7 PLANT SYSTEMS

3.7.8 Essential Service Water System (ESWS)

LCO 3.7.8 Two ESWS divisions shall be OPERABLE.

APPLICABILITY: MODES 1, 2, 3, and 4.

**ACTIONS**

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. One ESWS division inoperable.</td>
<td>-----------------NOTES-----------------</td>
<td></td>
</tr>
<tr>
<td></td>
<td>1. Enter applicable Conditions and Required Actions of LCO 3.8.1, “AC Sources – Operating,” for emergency diesel generator made inoperable by ESWS.</td>
<td></td>
</tr>
<tr>
<td></td>
<td>2. Enter applicable Conditions and Required Actions of LCO 3.4.6, “RCS Loops – MODE 4” for shutdown cooling made inoperable by ESWS.</td>
<td></td>
</tr>
<tr>
<td></td>
<td>A.1 Restore ESWS division to OPERABLE status.</td>
<td>72 hours</td>
</tr>
<tr>
<td></td>
<td>B.1 Be in MODE 3.</td>
<td>6 hours</td>
</tr>
<tr>
<td></td>
<td>AND</td>
<td></td>
</tr>
<tr>
<td></td>
<td>B.2 Be in MODE 5.</td>
<td>36 hours</td>
</tr>
</tbody>
</table>
## SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>SR 3.7.8.1</strong></td>
<td>31 days</td>
</tr>
<tr>
<td>..........................NOTE..........................- Isolation of ESWS flow to individual components does not render the ESWS inoperable.</td>
<td></td>
</tr>
<tr>
<td>..........................NOTE..........................- Verify each ESWS manual, power-operated, and automatic valve in the flow path servicing safety-related equipment that is not locked, sealed, or otherwise secured in position, is in correct position.</td>
<td></td>
</tr>
<tr>
<td><strong>SR 3.7.8.2</strong></td>
<td>18 months</td>
</tr>
<tr>
<td>Verify each ESWS automatic valve in the flow path that is not locked, sealed, or otherwise secured in position, actuates to correct position on an actual or simulated actuation signal.</td>
<td></td>
</tr>
<tr>
<td><strong>SR 3.7.8.3</strong></td>
<td>18 months</td>
</tr>
<tr>
<td>Verify each ESWS pump starts automatically on an actual or simulated actuation signal.</td>
<td></td>
</tr>
</tbody>
</table>
3.7 PLANT SYSTEMS

3.7.9 Ultimate Heat Sink (UHS)

LCO 3.7.9 [Two] UHS [divisions] shall be OPERABLE.

APPLICABILITY: MODES 1, 2, 3, and 4.

<table>
<thead>
<tr>
<th>ACTIONS</th>
</tr>
</thead>
<tbody>
<tr>
<td>CONDITION</td>
</tr>
<tr>
<td>A. [One UHS cooling tower inoperable.]</td>
</tr>
<tr>
<td>B. [Required Action and associated Completion Time of Condition A not met. OR]</td>
</tr>
<tr>
<td>UHS inoperable [for reasons other than Condition A.]</td>
</tr>
</tbody>
</table>
## SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.7.9.1</td>
<td>Verify water level of UHS is $\geq$ [7.90 m (25.93 ft) from the bottom of the basin].</td>
</tr>
<tr>
<td>SR 3.7.9.2</td>
<td>Verify water temperature of UHS [basin] is $\leq$ [33.2°C (91.8°F)].</td>
</tr>
<tr>
<td>SR 3.7.9.3</td>
<td>[Operate each UHS cooling tower fan for $\geq$ 15 minutes.]</td>
</tr>
<tr>
<td>SR 3.7.9.4</td>
<td>[Verify each UHS manual, power-operated, and automatic valve in the flow path servicing safety related equipment, that is not locked, sealed, or otherwise secured in position, is in correct position.]</td>
</tr>
<tr>
<td>SR 3.7.9.5</td>
<td>[Verify each UHS automatic valve and each control valve in the flow path that is not locked, sealed, or otherwise secured in position, actuates to correct position on an actual or simulated actuation signal.]</td>
</tr>
<tr>
<td>SR 3.7.9.6</td>
<td>[Verify each cooling tower fan starts automatically on an actual or simulated actuation signal.]</td>
</tr>
</tbody>
</table>
3.7 PLANT SYSTEMS

3.7.10 Essential Chilled Water System (ECWS)

LCO 3.7.10 Two ECWS divisions shall be OPERABLE.

APPLICABILITY: MODES 1, 2, 3, and 4.

**ACTIONS**

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. One ECWS division inoperable.</td>
<td>A.1 Restore ECWS division to OPERABLE status.</td>
<td>7 days</td>
</tr>
<tr>
<td>B. Required Action and associated Completion Time not met.</td>
<td>B.1 Be in MODE 3.</td>
<td>6 hours</td>
</tr>
<tr>
<td></td>
<td>AND</td>
<td></td>
</tr>
<tr>
<td></td>
<td>B.2 Be in MODE 5.</td>
<td>36 hours</td>
</tr>
</tbody>
</table>

**SURVEILLANCE REQUIREMENTS**

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.7.10.1</td>
<td>31 days</td>
</tr>
</tbody>
</table>

-------------------------------NOTE-------------------------------
Isolation of ECW flow to individual components does not render the ECWS inoperable.

Verify each ECWS manual, power-operated, and automatic valve in the flow path that is not locked, sealed, or otherwise secured in position, is in correct position.
<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
</tr>
</thead>
<tbody>
<tr>
<td>Verify proper actuation of each ECWS component on an actual or simulated actuation signal.</td>
</tr>
<tr>
<td>FREQUENCY</td>
</tr>
<tr>
<td>18 months</td>
</tr>
</tbody>
</table>
3.7 PLANT SYSTEMS

3.7.11 Control Room Heating, Ventilation, and Air Conditioning (HVAC) System (CRHS)

LCO 3.7.11 Two Control Room Emergency Makeup Air Cleaning System (CREACS) divisions and two Control Room Supply and Return System (CRSRS) divisions of the CRHS shall be OPERABLE.

---------------------------------------------NOTE--------------------------------------------
The control room envelope (CRE) boundary may be opened intermittently under administrative control.
--------------------------------------------------------------------------------------------------

APPLICABILITY: MODES 1, 2, 3, 4, [5, and 6,] During movement of irradiated fuel assemblies.

ACTIONS

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. One CREACS division inoperable for reasons other than Condition C.</td>
<td>A.1 Restore CREACS division to OPERABLE status.</td>
<td>7 days</td>
</tr>
<tr>
<td>B. One CRSRS division inoperable.</td>
<td>B.1 Restore CRSRS division to OPERABLE status.</td>
<td>7 days</td>
</tr>
</tbody>
</table>
## ACTIONS (continued)

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>C. One or two CREACS divisions inoperable due to inoperable CRE boundary in MODE 1, 2, 3, or 4.</td>
<td>C.1 Initiate action to implement mitigating actions.</td>
<td>Immediately</td>
</tr>
<tr>
<td>AND</td>
<td>C.2 Verify mitigating actions to ensure CRE occupant exposures to radiological, [toxic gas,] and smoke hazards will not exceed limits.</td>
<td>24 hours</td>
</tr>
<tr>
<td>AND</td>
<td>C.3 Restore CRE boundary to OPERABLE status.</td>
<td>90 days</td>
</tr>
<tr>
<td>D. Required Action and associated Completion Time of Condition A, B, or C not met in MODE 1, 2, 3 or 4.</td>
<td>D.1 Be in MODE 3.</td>
<td>6 hours</td>
</tr>
<tr>
<td>AND</td>
<td>D.2 Be in MODE 5.</td>
<td>36 hours</td>
</tr>
<tr>
<td>E. Required Action and associated Completion Time of Condition A or B not met [in MODE 5 or 6, or] during movement of irradiated fuel assemblies.</td>
<td>[-------------------NOTE------------------- Place CRHS in toxic gas isolation mode if automatic transfer to toxic gas isolation mode is inoperable. -------------------------------]</td>
<td></td>
</tr>
<tr>
<td></td>
<td>E.1 Place CREACS and CRSRS of an OPERABLE CRHS division in emergency mode.</td>
<td>Immediately</td>
</tr>
<tr>
<td></td>
<td>OR</td>
<td></td>
</tr>
<tr>
<td>CONDITION</td>
<td>REQUIRED ACTION</td>
<td>COMPLETION TIME</td>
</tr>
<tr>
<td>-----------</td>
<td>-----------------</td>
<td>----------------</td>
</tr>
<tr>
<td>E. (continued)</td>
<td>E.2[.1] Suspend movement of irradiated fuel assemblies. [AND E.2.2 Suspend operations with a potential for releasing radioactivity from the Gaseous Radwaste System.</td>
<td>Immediately</td>
</tr>
<tr>
<td>F. Two CREACS divisions inoperable [in MODE 5 or 6, or] during movement of irradiated fuel assemblies. OR One or two CREACS divisions inoperable due to inoperable CRE boundary [in MODE 5 or 6, or] during movement of irradiated fuel assemblies.</td>
<td>F.1 Suspend movement of irradiated fuel assemblies. [AND F.2 Suspend operations with a potential for releasing radioactivity from the Gaseous Radwaste System.</td>
<td>Immediately</td>
</tr>
<tr>
<td>G. Two CREACS divisions inoperable in MODE 1, 2, 3, or 4 for reasons other than Condition C. OR Two CRSRS divisions inoperable in MODE 1, 2, 3, or 4.</td>
<td>G.1 Enter LCO 3.0.3.</td>
<td>Immediately</td>
</tr>
<tr>
<td>SURVEILLANCE REQUIREMENTS</td>
<td>SURVEILLANCE</td>
<td>FREQUENCY</td>
</tr>
<tr>
<td>----------------------------</td>
<td>------------------------------------------------------------------------------</td>
<td>---------------------------------</td>
</tr>
<tr>
<td>SR 3.7.11.1</td>
<td>Operate each CREACS division for ≥ 15 minutes with heaters operating.</td>
<td>31 days</td>
</tr>
<tr>
<td>SR 3.7.11.2</td>
<td>Perform required CREACS filter testing in accordance with VFTP.</td>
<td>In accordance with VFTP</td>
</tr>
<tr>
<td>SR 3.7.11.3</td>
<td>Verify active components in each CRHS division actuate on an actual or simulated actuation signal.</td>
<td>18 months</td>
</tr>
<tr>
<td>SR 3.7.11.4</td>
<td>Perform required CRE unfiltered air inleakage testing in accordance with Control Room Envelope Habitability Program.</td>
<td>In accordance with Control Room Envelope Habitability Program</td>
</tr>
<tr>
<td>SR 3.7.11.5</td>
<td>Verify each CRSRS division has the capacity to remove design heat load.</td>
<td>18 months</td>
</tr>
</tbody>
</table>
3.7 PLANT SYSTEMS

3.7.12 Auxiliary Building Controlled Area Emergency Exhaust System (ABCAEES)

LCO 3.7.12 Two ABCAEEES divisions shall be OPERABLE.

---NOTE---
The mechanical penetration room and safety-related mechanical equipment room boundary may be opened intermittently under administrative control.

APPLICABILITY: MODES 1, 2, 3, and 4.

<table>
<thead>
<tr>
<th>ACTIONS</th>
</tr>
</thead>
<tbody>
<tr>
<td>CONDITION</td>
</tr>
<tr>
<td>A. One ABCAEEES division inoperable.</td>
</tr>
<tr>
<td>B. Two ABCAEEES divisions inoperable due to inoperable mechanical penetration room or safety-related mechanical equipment room boundary.</td>
</tr>
<tr>
<td>C. Required Action and associated Completion Time not met.</td>
</tr>
</tbody>
</table>
### SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.7.12.1</td>
<td>Operate each ABCAES division for ≥ 15 minutes with heaters operating.</td>
</tr>
<tr>
<td>SR 3.7.12.2</td>
<td>Perform required ABCAES filter testing in accordance with Ventilation Filter Testing Program (VFTP).</td>
</tr>
<tr>
<td>SR 3.7.12.3</td>
<td>Verify each ABCAES division actuates on an actual or simulated actuation signal.</td>
</tr>
<tr>
<td>SR 3.7.12.4</td>
<td>Verify the mechanical penetration rooms and the safety-related mechanical equipment rooms can be maintained at a pressure of ≤ -6.35 mm (-0.25 inches) water gauge with respect to the adjacent areas using one ABCAES division during post-accident mode of operation at a flow rate of ≤ 5,097 cmh (3,000 cfm) within 300 seconds after a start signal.</td>
</tr>
</tbody>
</table>
### 3.7 PLANT SYSTEMS

#### 3.7.13 Fuel Handling Area Emergency Exhaust System (FHAEES)

**LCO 3.7.13** Two FHAEES divisions shall be OPERABLE.

---

**NOTE**

The fuel handling area boundary may be opened intermittently under administrative control.

---

**APPLICABILITY:** During movement of irradiated fuel assemblies in the fuel handling area.

**ACTIONS**

---

**NOTE**

LCO 3.0.3 is not applicable.

---

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. One FHAEES division inoperable.</td>
<td>A.1 Restore FHAEES division to OPERABLE status.</td>
<td>7 days</td>
</tr>
<tr>
<td>B. Required Action and associated Completion Time of Condition A not met during movement of irradiated fuel assemblies in fuel handling area.</td>
<td>B.1 Place OPERABLE FHAEES division in operation. OR B.2 Suspend movement of irradiated fuel assemblies in fuel handling area.</td>
<td>Immediately</td>
</tr>
<tr>
<td>C. Two FHAEES divisions inoperable during movement of irradiated fuel assemblies in fuel handling area.</td>
<td>C.1 Suspend movement of irradiated fuel assemblies in fuel handling area.</td>
<td>Immediately</td>
</tr>
</tbody>
</table>
### SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>SR 3.7.13.1</strong> Operate each FHAEES division for ≥ 15 minutes with heaters operating.</td>
<td>31 days</td>
</tr>
<tr>
<td><strong>SR 3.7.13.2</strong> Perform required FHAEES filter testing in accordance with Ventilation Filter Testing Program (VFTP).</td>
<td>In accordance with VFTP</td>
</tr>
<tr>
<td><strong>SR 3.7.13.3</strong> Verify each FHAEES division actuates on an actual or simulated actuation signal.</td>
<td>18 months</td>
</tr>
<tr>
<td><strong>SR 3.7.13.4</strong> Verify one FHAEES division can maintain a slightly negative pressure with respect to atmospheric pressure during post-accident mode of operation at a flow rate of 8,495 cmh (5,000 cfm).</td>
<td>18 months on a STAGGERED TEST BASIS</td>
</tr>
</tbody>
</table>
3.7 PLANT SYSTEMS

3.7.14 Spent Fuel Pool Water Level (SFPWL)

LCO 3.7.14 The spent fuel pool water level shall be \( \geq 7 \text{ m (23 ft)} \) over the top of irradiated fuel assemblies seated in the storage racks.

APPLICABILITY: During movement of irradiated fuel assemblies in the spent fuel pool.

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
</table>
| A. Spent Fuel Pool water level not within limit. | ------------------------ NOTE ------------------------
| | LCO 3.0.3 is not applicable. | |
| | A.1 Suspend movement of irradiated fuel assemblies in spent fuel pool. | Immediately |

SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.7.14.1</td>
<td>7 days</td>
</tr>
</tbody>
</table>
3.7 PLANT SYSTEMS

3.7.15 Spent Fuel Pool Boron Concentration

LCO 3.7.15 The spent fuel pool (SFP) boron concentration shall be ≥ 2,150 ppm, and the SFP B-10 isotopic concentration shall be ≥ 19.9% (atomic percent).

APPLICABILITY: When fuel assemblies are stored in the spent fuel pool and spent fuel pool verification has not been performed since the last movement of fuel assemblies in the spent fuel pool.

ACTIONS

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. Spent fuel pool boron concentration not within limit. OR Spent fuel pool B-10 isotopic concentration not within limit.</td>
<td>A.1 Suspend movement of fuel assemblies in spent fuel pool. AND A.2.1 Initiate action to restore spent fuel pool boron concentration and B-10 isotopic concentration to within limits. OR A.2.2 Initiate action to perform a spent fuel pool verification.</td>
<td>Immediately</td>
</tr>
</tbody>
</table>

NOTE: LCO 3.0.3 is not applicable.
## SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.7.15.1 Verify spent fuel pool boron concentration is within limit.</td>
<td>7 days</td>
</tr>
<tr>
<td>SR 3.7.15.2 Verify isotopic concentration of B-10 in the SFP is ≥ 19.9% (atomic percent).</td>
<td>24 months</td>
</tr>
</tbody>
</table>
3.7 PLANT SYSTEMS

3.7.16 Spent Fuel Assembly Storage

LCO 3.7.16 The combination of initial enrichment and burnup of each spent fuel assembly stored in Region II shall be within the acceptable burnup domain of Figure 3.7.16-1 or in accordance with Specification 4.3.1.1.

APPLICABILITY: Whenever any fuel assembly is stored in Region II of the spent fuel pool.

ACTIONS

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. Requirements of the LCO not met.</td>
<td>------------------------------- NOTE ------------------------------- LCO 3.0.3 is not applicable.</td>
<td>A.1 Initiate action to move the noncomplying fuel from Region II to Region I.</td>
</tr>
</tbody>
</table>

SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.7.16.1 Verify by administrative means that initial enrichment and burnup of the fuel assembly is in accordance with Figure 3.7.16-1 or Specification 4.3.1.1.</td>
<td>Prior to storing fuel assembly in Region II.</td>
</tr>
</tbody>
</table>
Figure 3.7.16-1 (page 1 of 1)
Discharge Burnup vs. Initial Enrichment for Region II Racks
3.7 PLANT SYSTEMS

3.7.17 Secondary Specific Activity

LCO 3.7.17 The specific activity of the secondary coolant shall be \( \leq 3.7 \times 10^3 \) Bq/g (0.1 µCi/g) DOSE EQUIVALENT I-131.

APPLICABILITY: MODES 1, 2, 3, and 4.

ACTIONS

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. Specific activity not within limit.</td>
<td>A.1 Be in MODE 3. AND A.2 Be in MODE 5.</td>
<td>6 hours 36 hours</td>
</tr>
</tbody>
</table>

SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.7.17.1 Verifying specific activity of secondary coolant is within limit.</td>
<td>31 days</td>
</tr>
</tbody>
</table>
3.8 ELECTRICAL POWER SYSTEMS

3.8.1 AC Sources – Operating

LCO 3.8.1 The following AC electrical sources shall be OPERABLE:

a. Two qualified circuits between the offsite transmission network and the onsite Class 1E AC Electrical Power Distribution System,

b. Division I and division II emergency diesel generators (EDGs), each division capable of supplying one division of the onsite Class 1E AC Electrical Power Distribution System and consisting of two EDGs (EDG A and EDG C for division I, and EDG B and EDG D for division II), and

c. Four automatic load sequencers for EDG A, EDG B, EDG C, and EDG D.

APPLICABILITY: MODES 1, 2, 3, and 4.

ACTIONS

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. One offsite circuit inoperable.</td>
<td>A.1 Perform SR 3.8.1.1 for OPERABLE offsite circuit.</td>
<td>1 hour AND</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Once per 8 hours thereafter</td>
</tr>
<tr>
<td></td>
<td>AND</td>
<td></td>
</tr>
<tr>
<td>A.2 Declare required feature(s) with no offsite power available inoperable when its redundant required feature(s) is inoperable.</td>
<td></td>
<td>24 hours from discovery of no offsite power to one division concurrent with inoperability of redundant required feature(s)</td>
</tr>
</tbody>
</table>
### ACTIONS (continued)

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. (continued)</td>
<td>A.3 Restore offsite circuit to OPERABLE status.</td>
<td>72 hours</td>
</tr>
<tr>
<td>B. One or two EDGs in one division inoperable.</td>
<td>B.1 Perform SR 3.8.1.1 for the OPERABLE offsite circuit(s).</td>
<td>1 hour</td>
</tr>
<tr>
<td></td>
<td>B.2 Declare required feature(s) supported by the inoperable EDG(s) inoperable when its redundant required feature(s) is inoperable.</td>
<td>4 hours from discovery of Condition B concurrent with inoperability of redundant required feature(s)</td>
</tr>
<tr>
<td></td>
<td>B.3.1 Determine OPERABLE EDG(s) is not inoperable due to common cause failure.</td>
<td>24 hours</td>
</tr>
<tr>
<td></td>
<td>B.3.2 Perform SR 3.8.1.2 for OPERABLE EDG(s).</td>
<td>24 hours</td>
</tr>
<tr>
<td></td>
<td>B.4 Restore EDG(s) to OPERABLE status.</td>
<td>72 hours</td>
</tr>
<tr>
<td>AND</td>
<td></td>
<td></td>
</tr>
<tr>
<td>AND</td>
<td></td>
<td></td>
</tr>
<tr>
<td>OR</td>
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<td></td>
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<td></td>
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<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>CONDITION</td>
<td>REQUIRED ACTION</td>
<td>COMPLETION TIME</td>
</tr>
<tr>
<td>-----------</td>
<td>----------------</td>
<td>----------------</td>
</tr>
<tr>
<td>C. Two offsite circuits inoperable.</td>
<td><strong>C.1</strong> Declare required feature(s) inoperable when its redundant required feature(s) is inoperable.</td>
<td>12 hours from discovery of Condition C concurrent with inoperability of redundant required feature(s)</td>
</tr>
<tr>
<td>AND</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td><strong>C.2</strong> Restore one offsite circuit to OPERABLE status.</td>
<td>24 hours</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>D. One offsite circuit inoperable.</td>
<td><strong>---------------NOTE---------------</strong> Enter applicable Conditions and Required Actions of LCO 3.8.9, “Distribution Systems – Operating,” when Condition D is entered with no AC power source to one division.</td>
<td></td>
</tr>
<tr>
<td>AND</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td><strong>D.1</strong> Restore offsite circuits to OPERABLE status.</td>
<td>12 hours</td>
</tr>
<tr>
<td>OR</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td><strong>D.2</strong> Restore EDG(s) to OPERABLE status.</td>
<td>12 hours</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>E. One or two EDGs in each division inoperable.</td>
<td><strong>E.1</strong> Restore EDG(s) in one division to OPERABLE status.</td>
<td>2 hours</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>F. One automatic load sequencer inoperable.</td>
<td><strong>F.1</strong> Restore automatic load sequencer to OPERABLE status.</td>
<td>12 hours</td>
</tr>
</tbody>
</table>
### ACTIONS (continued)

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>G. Required Actions and associated Completion Times of Conditions A, B, C, D, E, or F not met.</td>
<td>G.1 Be in MODE 3. AND G.2 Be in MODE 5.</td>
<td>6 hours 36 hours</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>H. Two offsite circuits and one or more EDGs inoperable. OR One offsite circuit and one or two EDGs in each division inoperable</td>
<td>H.1 Enter LCO 3.0.3.</td>
<td>Immediately</td>
</tr>
</tbody>
</table>

---

### SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.8.1.1 Verify correct breaker alignment and indicated power availability for each offsite circuit.</td>
<td>7 days</td>
</tr>
</tbody>
</table>
### SURVEILLANCE REQUIREMENTS (continued)

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>SR 3.8.1.2</strong></td>
<td>31 days</td>
</tr>
<tr>
<td><strong>NOTES</strong></td>
<td></td>
</tr>
<tr>
<td>1. All EDG starts may be preceded by an engine prelube period and followed by a warmup period prior to loading.</td>
<td></td>
</tr>
<tr>
<td>2. A modified EDG start, involving idling and gradual acceleration to synchronous speed, may be used for this SR as recommended by the manufacturer. When modified start procedures are not used, the time, voltage, and frequency tolerances of SR 3.8.1.7 must be met.</td>
<td></td>
</tr>
<tr>
<td>Verify each EDG starts from standby conditions and achieves steady state voltage ≥ 3,744 V and ≤ 4,576 V, and frequency ≥ 58.8 Hz and ≤ 61.2 Hz.</td>
<td></td>
</tr>
<tr>
<td><strong>SR 3.8.1.3</strong></td>
<td>31 days</td>
</tr>
<tr>
<td><strong>NOTES</strong></td>
<td></td>
</tr>
<tr>
<td>1. EDG loadings may include gradual loading as recommended by the manufacturer.</td>
<td></td>
</tr>
<tr>
<td>2. Momentary transients outside the load range do not invalidate this test.</td>
<td></td>
</tr>
<tr>
<td>3. This Surveillance shall be conducted on only one EDG at a time.</td>
<td></td>
</tr>
<tr>
<td>4. This SR shall be preceded by and immediately follow without shutdown a successful performance of SR 3.8.1.2 or SR 3.8.1.7.</td>
<td></td>
</tr>
<tr>
<td>Verify each EDG is synchronized and loaded, and operates for ≥ 60 minutes at a load ≥ 90% rating and ≤ 100% rating.</td>
<td></td>
</tr>
<tr>
<td><strong>SR 3.8.1.4</strong></td>
<td>31 days</td>
</tr>
<tr>
<td>Verify each day tank contains ≥ [2,404 L (635 gal)] of fuel oil.</td>
<td></td>
</tr>
</tbody>
</table>
### SURVEILLANCE REQUIREMENTS (continued)

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.8.1.5  Check for and remove accumulated water and sediment from each day tank and engine mounted tank.</td>
<td>31 days</td>
</tr>
<tr>
<td>SR 3.8.1.6  Verify fuel oil transfer system operates to automatically transfer fuel oil from storage tank to the day tank.</td>
<td>92 days</td>
</tr>
<tr>
<td>SR 3.8.1.7  --------------------------------NOTE-------------------------------</td>
<td>184 days</td>
</tr>
<tr>
<td>All EDG starts may be preceded by an engine prelube period.</td>
<td></td>
</tr>
<tr>
<td>Verify each EDG starts from standby condition and achieves:</td>
<td></td>
</tr>
<tr>
<td>a. In ≤ 17 seconds, voltage ≥ 3,744 V and frequency ≥ 58.8 Hz, and</td>
<td></td>
</tr>
<tr>
<td>b. Steady stage voltage ≥ 3,744 V and ≤ 4,576 V, and frequency ≥ 58.8 Hz and ≤ 61.2 Hz.</td>
<td></td>
</tr>
<tr>
<td>SR 3.8.1.8  --------------------------------NOTE-------------------------------</td>
<td>18 months</td>
</tr>
<tr>
<td>[This Surveillance shall not normally be performed in MODE 1 or 2. However, this Surveillance may be performed to reestablish OPERABILITY provided an assessment determines the safety of the plant is maintained or enhanced. Credit may be taken for unplanned events which satisfy this SR.]</td>
<td></td>
</tr>
<tr>
<td>Verify automatic and manual transfer of AC power sources from the normal offsite circuit to each alternate offsite circuit.</td>
<td></td>
</tr>
</tbody>
</table>
### SURVEILLANCE REQUIREMENTS (continued)

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>SR 3.8.1.9</strong></td>
<td>18 months</td>
</tr>
</tbody>
</table>

**NOTES**

1. [This Surveillance shall not normally be performed in MODE 1 or 2. However, this Surveillance may be performed to reestablish OPERABILITY provided an assessment determines the safety of the plant is maintained or enhanced. Credit may be taken for unplanned events that satisfy this SR.]

2. [If performed with the EDG synchronized with offsite power, it shall be performed at a power factor ≤ 0.9. However, if grid conditions do not permit, the power factor limit is not required to be met. Under this condition, the power factor shall be maintained as close to the limit as practicable.]

Verify each EDG rejects a load greater than or equal to its associated single largest post-accident load and:

- a. Following load rejection, the frequency is ≤ 63 Hz,
- b. Within 3 seconds following load rejection, the voltage is ≥ 3,744 V and ≤ 4,576 V, and
- c. Within 3 seconds following load rejection, the frequency is ≥ 58.8 Hz and ≤ 61.2 Hz.
### SURVEILLANCE REQUIREMENTS (continued)

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.8.1.10</td>
<td></td>
</tr>
</tbody>
</table>

[1. This Surveillance shall not normally be performed in MODE 1 or 2. However, this Surveillance may be performed to reestablish OPERABILITY provided an assessment determines the safety of the plant is maintained or enhanced. Credit may be taken for unplanned events that satisfy this SR.]

2. If performed with EDG synchronized with offsite power, it shall be performed at a power factor $\leq 0.9$. However, if grid conditions do not permit, the power factor limit is not required to be met. Under this condition the power factor shall be maintained as close to the limit as practicable.

Verify each EDG does not trip, and voltage is maintained $\leq 4,576$ V during and following a load rejection of $\geq 90\%$ rating and $\leq 100\%$ rating.  

18 months
### SURVEILLANCE REQUIREMENTS (continued)

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>SR 3.8.1.11</strong></td>
<td><strong>18 months</strong></td>
</tr>
</tbody>
</table>

1. All EDG starts may be preceded by an engine prelube period.

2. This Surveillance shall not be performed in MODE 1, 2, 3, or 4. However, portions of the Surveillance may be performed to reestablish OPERABILITY provided an assessment determines the safety of the plant is maintained or enhanced. Credit may be taken for unplanned events that satisfy this SR.

Verify on an actual or simulated loss of offsite power signal:

a. De-energization of emergency buses,

b. Load shedding from emergency buses,

c. EDG auto-starts from standby condition, and:

1. energizes permanently-connected loads in \( \leq 19 \) seconds,

2. energizes auto-connected shutdown loads through automatic load sequencer,

3. maintains steady state voltage \( \geq 3,744 \text{ V} \) and \( \leq 4,576 \text{ V} \),

4. maintains steady state frequency \( \geq 58.8 \text{ Hz} \) and \( \leq 61.2 \text{ Hz} \), and

5. supplies permanently connected and auto-connected shutdown connected loads for \( \geq 5 \) minutes.
### SURVEILLANCE REQUIREMENTS (continued)

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.8.1.12</td>
<td>18 months</td>
</tr>
</tbody>
</table>

**NOTES**

1. All EDG starts may be preceded by an engine prelube period.

2. [This Surveillance shall not be performed in MODE 1 or 2. However, portions of the Surveillance may be performed to reestablish OPERABILITY provided an assessment determines the safety of the plant is maintained or enhanced. Credit may be taken for unplanned events that satisfy this SR.]

---

Verify on an actual or simulated Engineered Safety Features (ESF) actuation signal each EDG auto-starts from standby condition and:

- a. In ≤ 17 seconds after auto-start and during tests, achieves voltage ≥ 3,744 V and frequency ≥ 58.8 Hz,

- b. Achieves steady state voltage ≥ 3,744 V and ≤ 4,576 V and frequency ≥ 58.8 Hz and ≤ 61.2 Hz,

- c. Operates for ≥ 5 minutes,

- d. Permanently connected loads remain energized from the offsite power system, and

- e. Emergency loads are energized or auto-connected through the automatic load sequencer from the offsite power system.
SURVEILLANCE REQUIREMENTS (continued)

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>SR 3.8.1.13</strong></td>
<td>18 months</td>
</tr>
<tr>
<td>[This Surveillance shall not be performed in MODE 1 or 2. However, this Surveillance may be performed to reestablish OPERABILITY provided an assessment determines the safety of the plant is maintained or enhanced. Credit may be taken for unplanned events that satisfy this SR.]</td>
<td></td>
</tr>
<tr>
<td>Verify each EDG’s noncritical automatic trips are bypassed on an actual or simulated loss of voltage signal on the emergency bus concurrent with an actual or simulated ESF actuation signal.</td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th><strong>SR 3.8.1.14</strong></th>
<th>18 months</th>
</tr>
</thead>
<tbody>
<tr>
<td>1. Momentary transients outside the load and power factor ranges do not invalidate this test.</td>
<td></td>
</tr>
<tr>
<td>2. This Surveillance shall not be performed in MODE 1 or 2. However, this Surveillance may be performed to reestablish OPERABILITY provided an assessment determines the safety of the plant is maintained or enhanced. Credit may be taken for unplanned events that satisfy this SR.</td>
<td></td>
</tr>
<tr>
<td>3. If performed with EDG synchronized with offsite power, it shall be performed at a power factor ≤ [0.9]. However, if grid conditions do not permit, the power factor limit is not required to be met. Under this condition, the power factor shall be maintained as close to the limit as practicable.</td>
<td></td>
</tr>
<tr>
<td>Verify each EDG operates for ≥ 24 hours:</td>
<td></td>
</tr>
<tr>
<td>a. For ≥ 2 hours loaded ≥ 105% rating and ≤ 110% rating and;</td>
<td></td>
</tr>
<tr>
<td>b. For the remaining hours of the test loaded ≥ 90% rating and ≤ 100% rating.</td>
<td></td>
</tr>
<tr>
<td>SURVEILLANCE REQUIREMENTS (continued)</td>
<td>FREQUENCY</td>
</tr>
<tr>
<td>-------------------------------------</td>
<td>-----------</td>
</tr>
<tr>
<td><strong>SURVEILLANCE</strong></td>
<td><strong>FREQUENCY</strong></td>
</tr>
<tr>
<td>-----------------------------------</td>
<td>--</td>
</tr>
<tr>
<td><strong>SR 3.8.1.15</strong></td>
<td>18 months</td>
</tr>
<tr>
<td>-----------------------------------</td>
<td>--</td>
</tr>
<tr>
<td>1. This Surveillance shall be performed within 5 minutes of shutting down the EDG after the EDG has operated in ≥ 2 hours loaded ≥ 90% rating and ≤ 100% rating. Momentary transients outside of load range do not invalidate this test.</td>
<td>18 months</td>
</tr>
<tr>
<td>2. All EDG starts may be preceded by an engine prelube period.</td>
<td>18 months</td>
</tr>
<tr>
<td>Verify each EDG starts and achieves:</td>
<td>18 months</td>
</tr>
<tr>
<td>a. In ≤ 17 seconds, voltage ≥ 3,744 V and frequency ≥ 58.8 Hz.</td>
<td>18 months</td>
</tr>
<tr>
<td>b. Steady state voltage ≥ 3,744 V and ≤ 4,576 V, and frequency ≥ 58.8 Hz and ≤ 61.2 Hz.</td>
<td>18 months</td>
</tr>
<tr>
<td><strong>SR 3.8.1.16</strong></td>
<td>18 months</td>
</tr>
<tr>
<td>-----------------------------------</td>
<td>--</td>
</tr>
<tr>
<td>This Surveillance shall not normally be performed in MODE 1, 2, 3, or 4. However, this Surveillance may be performed to reestablish OPERABILITY provided an assessment determines the safety of the plant is maintained or enhanced. Credit may be taken for unplanned events that satisfy this SR.</td>
<td>18 months</td>
</tr>
<tr>
<td>Verify each EDG:</td>
<td>18 months</td>
</tr>
<tr>
<td>a. Synchronizes with offsite power source while loaded with emergency loads upon a simulated restoration of offsite power.</td>
<td>18 months</td>
</tr>
<tr>
<td>b. Transfers loads to offsite power source, and</td>
<td>18 months</td>
</tr>
<tr>
<td>c. Returns to ready to load operation.</td>
<td>18 months</td>
</tr>
<tr>
<td>SURVEILLANCE REQUIREMENTS (continued)</td>
<td></td>
</tr>
<tr>
<td>--------------------------------------</td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.8.1.17</td>
<td>18 months</td>
</tr>
</tbody>
</table>

This Surveillance shall not normally be performed in MODE 1, 2, 3, or 4. However, portions of the Surveillance may be performed to reestablish OPERABILITY provided an assessment determines the safety of the plant is maintained or enhanced. Credit may be taken for unplanned events that satisfy this SR.

Verify, with an EDG operating in test mode and connected to its bus, an actual or simulated ESF actuation signal overrides the test mode by:

a. Returning EDG to ready-to-load operation and

b. Automatically energizing emergency loads from offsite power.

| SR 3.8.1.18 | 18 months |

This Surveillance shall not normally be performed in MODE 1, 2, 3, or 4. However, this Surveillance may be performed to reestablish OPERABILITY provided an assessment determines the safety of the plant is maintained or enhanced. Credit may be taken for unplanned events that satisfy this SR.

Verify interval between each sequenced load block is within ± 10% of design interval for each emergency and shutdown load sequencer.
SURVEILLANCE REQUIREMENTS (continued)

<table>
<thead>
<tr>
<th>SR 3.8.1.19</th>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>1. All EDG starts may be preceded by an engine prelube period.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>2. This Surveillance shall not normally be performed in MODE 1, 2, 3, or 4. However, portions of the Surveillance may be performed to reestablish OPERABILITY provided an assessment determines the safety of the plant is maintained or enhanced. Credit may be taken for unplanned events that satisfy this SR.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Verify on an actual or simulated loss of offsite power signal in conjunction with an actual or simulated ESF actuation signal:</td>
<td></td>
<td>18 months</td>
</tr>
<tr>
<td>a. De-energization of emergency buses,</td>
<td></td>
<td></td>
</tr>
<tr>
<td>b. Load shedding from emergency buses,</td>
<td></td>
<td></td>
</tr>
<tr>
<td>c. EDG auto-starts from standby condition and:</td>
<td></td>
<td></td>
</tr>
<tr>
<td>1. energizes permanently connected loads in ≤ 19 seconds,</td>
<td></td>
<td></td>
</tr>
<tr>
<td>2. energizes auto-connected emergency loads through load sequencer,</td>
<td></td>
<td></td>
</tr>
<tr>
<td>3. achieves steady state voltage ≥ 3,744 V and ≤ 4,576 V,</td>
<td></td>
<td></td>
</tr>
<tr>
<td>4. achieves steady state frequency ≥ 58.8 Hz and ≤ 61.2 Hz, and</td>
<td></td>
<td></td>
</tr>
<tr>
<td>5. supplies permanently connected and auto-connected emergency loads for ≥ 5 minutes.</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
SURVEILLANCE REQUIREMENTS (continued)

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.8.1.20 NOTE All EDG starts may be preceded by an engine prelube period.</td>
<td>10 years</td>
</tr>
<tr>
<td>Verify, when started simultaneously from standby condition, each EDG achieves:</td>
<td></td>
</tr>
<tr>
<td>a. In ≤ 17 seconds, voltage ≥ 3,744 V and frequency ≥ 58.8 Hz and</td>
<td></td>
</tr>
<tr>
<td>b. Steady state voltage ≥ 3,744 V and ≤ 4,576 V, and frequency ≥ 58.8 Hz and ≤ 61.2 Hz.</td>
<td></td>
</tr>
</tbody>
</table>
3.8 ELECTRICAL POWER SYSTEMS

3.8.2 AC Sources – Shutdown

LCO 3.8.2 The following AC electrical power sources shall be OPERABLE:

a. One qualified circuit between the offsite transmission network and the onsite Class 1E AC Electrical Power Distribution System required by LCO 3.8.10, “Distribution Systems – Shutdown” and

b. One division of emergency diesel generators (EDGs) capable of supplying one division of the onsite Class 1E AC Electrical Power Distribution System required by LCO 3.8.10.

APPLICABILITY: MODES 5 and 6, During movement of irradiated fuel assemblies.

ACTIONS
---------------------------------------------------------------NOTE---------------------------------------------------------------
LCO 3.0.3 is not applicable.
-------------------------------------------------------------------------------------------------------------------------------

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. One required offsite circuit inoperable.</td>
<td>---------------NOTE----------- Enter applicable Conditions and Required Actions of LCO 3.8.10, with one required division de-energized as a result of Condition A.</td>
<td></td>
</tr>
<tr>
<td></td>
<td>A.1 Declare affected required feature(s) with no offsite power available inoperable.</td>
<td>Immediately</td>
</tr>
<tr>
<td></td>
<td>OR</td>
<td></td>
</tr>
<tr>
<td></td>
<td>A.2.1 Suspend movement of irradiated fuel assemblies.</td>
<td>Immediately</td>
</tr>
<tr>
<td></td>
<td>AND</td>
<td></td>
</tr>
</tbody>
</table>
### ACTIONS (continued)

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>A. (continued)</strong></td>
<td><strong>A.2.2</strong> Suspend operations involving positive reactivity additions that could result in a loss of required SDM or boron concentration.</td>
<td>Immediately</td>
</tr>
<tr>
<td></td>
<td><strong>AND</strong></td>
<td></td>
</tr>
<tr>
<td></td>
<td><strong>A.2.3</strong> Initiate action to restore required offsite power circuit to OPERABLE status.</td>
<td>Immediately</td>
</tr>
<tr>
<td><strong>B. One or two required EDGs in one division inoperable.</strong></td>
<td><strong>B.1</strong> Suspend movement of irradiated fuel assemblies</td>
<td>Immediately</td>
</tr>
<tr>
<td></td>
<td><strong>AND</strong></td>
<td></td>
</tr>
<tr>
<td></td>
<td><strong>B.2</strong> Suspend operations involving positive reactivity additions that could result in loss of required SDM or boron concentration</td>
<td>Immediately</td>
</tr>
<tr>
<td></td>
<td><strong>AND</strong></td>
<td></td>
</tr>
<tr>
<td></td>
<td><strong>B.3</strong> Initiate action to restore required EDG(s) to OPERABLE status</td>
<td>Immediately</td>
</tr>
<tr>
<td>SR 3.8.2.1</td>
<td>SURVEILLANCE</td>
<td>FREQUENCY</td>
</tr>
<tr>
<td>------------</td>
<td>--------------</td>
<td>-----------</td>
</tr>
<tr>
<td>The following SRs are not required to be performed: SR 3.8.1.3, SR 3.8.1.9 through SR 3.8.1.11, SR 3.8.1.13 through SR 3.8.1.16, and SR 3.8.1.18.</td>
<td>In accordance with applicable SRs</td>
<td></td>
</tr>
<tr>
<td>For AC sources required to be OPERABLE, the SRs of Specification 3.8.1, “AC Sources – Operating,” except SR 3.8.1.8, SR 3.8.1.12, SR 3.8.1.17, SR 3.8.1.19, and SR 3.8.1.20 are applicable.</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
3.8 ELECTRICAL POWER SYSTEMS

3.8.3 Diesel Fuel Oil, Lube Oil, and Starting Air

LCO 3.8.3 The stored diesel fuel oil, lube oil, and starting air subsystem shall be within limits for each required emergency diesel generator (EDG).

APPLICABILITY: When associated EDG is required to be OPERABLE.

ACTIONS

---NOTE---Separate Condition entry is allowed for each EDG.

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. One or more EDGs with fuel level less than a 7 day supply and greater than a 6 day supply in storage tank.</td>
<td>A.1 Restore fuel oil level to within limits.</td>
<td>48 hours</td>
</tr>
<tr>
<td>B. One or more EDGs with lube oil inventory less than a 7 day supply and greater than a 6 day supply.</td>
<td>B.1 Restore lube oil inventory to within limits.</td>
<td>48 hours</td>
</tr>
<tr>
<td>C. One or more EDGs with stored fuel oil total particulates not within limits.</td>
<td>C.1 Restore stored fuel oil total particulates to within limits.</td>
<td>7 days</td>
</tr>
<tr>
<td>D. One or more EDGs with new fuel oil properties not within limits.</td>
<td>D.1 Restore stored fuel oil properties to within limits.</td>
<td>30 days</td>
</tr>
</tbody>
</table>
### ACTIONS (continued)

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>E. One or more EDGs with starting air receiver pressure $&lt; [40.77 \text{ kg/cm}^2 \text{G}(580 \text{ psig})]$ and $\geq [8.78 \text{ kg/cm}^2 \text{G}(125 \text{ psig})]$.</td>
<td>E.1 Restore starting air receiver pressure to $\geq [40.77 \text{ kg/cm}^2 \text{G}(580 \text{ psig})]$.</td>
<td>48 hours</td>
</tr>
</tbody>
</table>

F. Required Action and associated Completion Time not met. OR

One or more EDGs with diesel fuel oil, lube oil, or starting air subsystem not within limits for reasons other than Condition A, B, C, D, or E.

<table>
<thead>
<tr>
<th>SURVEILLANCE REQUIREMENTS</th>
</tr>
</thead>
<tbody>
<tr>
<td>SURVEILLANCE</td>
</tr>
<tr>
<td>SR 3.8.3.1 Verify each fuel oil storage tank contains $\geq$ a 7 day supply of fuel.</td>
</tr>
<tr>
<td>SR 3.8.3.2 Verify lubricating oil inventory is $\geq$ a 7 day supply.</td>
</tr>
<tr>
<td>SR 3.8.3.3 Verify fuel oil properties of new and stored fuel oil are tested in accordance with, and maintained within the limits of, the Diesel Fuel Oil Testing Program.</td>
</tr>
</tbody>
</table>
### SURVEILLANCE REQUIREMENTS (continued)

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.8.3.4 Verify each EDG air start receiver pressure is ≥ 40.77 kg/cm²G (580 psig).</td>
<td>31 days</td>
</tr>
<tr>
<td>SR 3.8.3.5 Check for and remove accumulated water and sediment from each fuel oil storage tank.</td>
<td>31 days</td>
</tr>
</tbody>
</table>
3.8 ELECTRICAL POWER SYSTEMS

3.8.4 DC Sources – Operating

LCO 3.8.4 Division I and Division II of the DC Electrical Power System shall be OPERABLE.

APPLICABILITY: MODES 1, 2, 3, and 4.

**ACTIONS**

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. One or two battery chargers in one division inoperable.</td>
<td>A.1 Restore battery terminal voltage to greater than or equal to the minimum established float voltage. AND A.2 Verify battery float current ≤ 2 amps. AND A.3 Restore battery chargers to OPERABLE status.</td>
<td>2 hours</td>
</tr>
<tr>
<td>B. One or two batteries in one division inoperable.</td>
<td>B.1 Restore batteries to OPERABLE status.</td>
<td>2 hours</td>
</tr>
<tr>
<td>C. One DC Electrical Power System division inoperable for reasons other than Condition A or B.</td>
<td>C.1 Restore DC Electrical Power System division to OPERABLE status.</td>
<td>2 hours</td>
</tr>
</tbody>
</table>
## ACTIONS (continued)

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>D. Required Action and Associated Completion Time not met.</td>
<td>D.1 Be in MODE 3. AND D.2 Be in MODE 5.</td>
<td>6 hours 36 hours</td>
</tr>
</tbody>
</table>

## SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.8.4.1 Verifying battery terminal voltage is greater than or equal to minimum established float voltage.</td>
<td>7 days</td>
</tr>
<tr>
<td>SR 3.8.4.2 Verifying battery chargers A and B supply 700 amps and battery chargers C and D supply 1,200 amps at greater than or equal to the minimum established float voltage for ≥ 8 hours. OR Verify each battery charger can recharge the battery to the fully charged state within 24 hours while supplying the largest combined demands of the various continuous steady state loads, after a battery discharge to the bounding design basis event discharge state.</td>
<td>18 months</td>
</tr>
</tbody>
</table>
### SURVEILLANCE REQUIREMENTS (continued)

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.8.4.3</td>
<td></td>
</tr>
<tr>
<td>1. The modified performance discharge test in SR 3.8.6.6 may be performed in lieu of SR 3.8.4.3.</td>
<td></td>
</tr>
<tr>
<td>2. This Surveillance shall not normally be performed in MODE 1, 2, 3, or 4. However, portions of the Surveillance may be performed to reestablish OPERABILITY provided an assessment determines the safety of the plant is maintained or enhanced. Credit may be taken for unplanned events that satisfy this SR.</td>
<td></td>
</tr>
<tr>
<td>----------------</td>
<td>---------------</td>
</tr>
<tr>
<td>Verify battery capacity is adequate to supply, and maintain in OPERABLE status, the required emergency loads for the design duty cycle when subjected to a battery service test.</td>
<td>18 months</td>
</tr>
</tbody>
</table>
3.8 ELECTRICAL POWER SYSTEMS

3.8.5 DC Sources – Shutdown

LCO 3.8.5  DC Electrical Power System divisions shall be OPERABLE to support each DC Electrical Power Distribution System division required by LCO 3.8.10, “Distribution Systems – Shutdown.”

APPLICABILITY: MODES 5 and 6,
During movement of irradiated fuel assemblies.

ACTIONS

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. One or two battery chargers in one division inoperable. AND The redundant division batteries and chargers OPERABLE.</td>
<td>A.1 Restore battery terminal voltage to greater than or equal to the minimum established float voltage. AND A.2 Verify battery float current ≤ 2 amps. AND A.3 Restore battery chargers to OPERABLE status.</td>
<td>2 hours Once per 12 hours 72 hours</td>
</tr>
</tbody>
</table>
ACTIONS (continued)

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>B.</strong> One or more required DC Electrical Power System divisions inoperable for reasons other than Condition A. OR Required Action and associated Completion Time of Condition A not met.</td>
<td>B.1 Declare affected required feature(s) inoperable. OR B.2.1 Suspend movement of irradiated fuel assemblies. AND B.2.2 Suspend operations involving positive reactivity additions that could result in loss of required SDM or boron concentration. AND B.2.3 Initiate action to restore required DC Electrical Power System divisions to OPERABLE status.</td>
<td>Immediately Immediately Immediately Immediately</td>
</tr>
</tbody>
</table>

SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.8.5.1</td>
<td>In accordance with applicable SRs</td>
</tr>
</tbody>
</table>

---------------------------------------------NOTE---------------------------------------------
The following SRs are not required to be performed: SR 3.8.4.2 and SR 3.8.4.3. For DC sources required to be OPERABLE, the following SRs are applicable: SR 3.8.4.1, SR 3.8.4.2, SR 3.8.4.3.
3.8 ELECTRICAL POWER SYSTEMS

3.8.6 Battery Cell Parameters

LCO 3.8.6 Battery cell parameters for the Division I and Division II batteries shall be within limits.

APPLICABILITY: When associated DC Electrical Power System divisions are required to be OPERABLE.

ACTIONS

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. One or two batteries in one division with one or more battery cells with float voltage &lt; 2.07 V.</td>
<td>- A.1 Perform SR 3.8.4.1.</td>
<td>2 hours</td>
</tr>
<tr>
<td></td>
<td>- AND</td>
<td></td>
</tr>
<tr>
<td></td>
<td>- A.2 Perform SR 3.8.6.1.</td>
<td>2 hours</td>
</tr>
<tr>
<td></td>
<td>- AND</td>
<td></td>
</tr>
<tr>
<td></td>
<td>- A.3 Restore affected cell voltage ≥ 2.07 V.</td>
<td>24 hours</td>
</tr>
<tr>
<td>B. One or two batteries in one division with float current &gt; 2 amps.</td>
<td>- B.1 Perform SR 3.8.4.1.</td>
<td>2 hours</td>
</tr>
<tr>
<td></td>
<td>- AND</td>
<td></td>
</tr>
<tr>
<td></td>
<td>- B.2 Restore battery float current to ≤ 2 amps.</td>
<td>12 hours</td>
</tr>
</tbody>
</table>

---

Separate Condition entry is allowed for each battery.
<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>C. --------NOTE-------- Required Action C.2 shall be completed if electrolyte level was below the top of plates.</td>
<td>------------------------NOTE------------------------ Required Actions C.1 and C.2 are only applicable if electrolyte level was below the top of plates.</td>
<td>8 hours</td>
</tr>
<tr>
<td>One or two batteries in one division with one or more battery cells with electrolyte level less than minimum established design limits.</td>
<td>C.1 Restore electrolyte level to above the top of plates.</td>
<td>8 hours</td>
</tr>
<tr>
<td>AND</td>
<td>C.2 Verify no evidence of leakage.</td>
<td>12 hours</td>
</tr>
<tr>
<td>AND</td>
<td>C.3 Restore electrolyte level to greater than or equal to minimum established design limits.</td>
<td>31 days</td>
</tr>
<tr>
<td>D. One or two batteries in one division with pilot cell electrolyte temperature less than minimum established design limits.</td>
<td>D.1 Restore battery pilot cell temperature to greater than or equal to minimum established design limits.</td>
<td>12 hours</td>
</tr>
<tr>
<td>E. One or more batteries in redundant divisions with battery parameters not within limits.</td>
<td>E.1 Restore battery parameters for batteries in one division to within limits.</td>
<td>2 hours</td>
</tr>
</tbody>
</table>
### ACTIONS (continued)

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>F. Required Action and associated Completion Time of Condition A, B, C, D, or E not met.</td>
<td>F.1 Declare associated battery inoperable.</td>
<td>Immediately</td>
</tr>
<tr>
<td>OR One or two batteries in one division with float current &gt; 2 amps and with one or more battery cells with float voltage &lt; 2.07 V.</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

### SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.8.6.1</td>
<td>7 days</td>
</tr>
<tr>
<td>SR 3.8.6.2</td>
<td>31 days</td>
</tr>
<tr>
<td>SR 3.8.6.3</td>
<td>31 days</td>
</tr>
<tr>
<td>SR 3.8.6.4</td>
<td>31 days</td>
</tr>
</tbody>
</table>

---

**NOTE**

Not required to be met when battery terminal voltage is less than the minimum established float voltage of SR 3.8.4.1.
### SURVEILLANCE REQUIREMENTS (continued)

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.8.6.5</td>
<td>92 day</td>
</tr>
<tr>
<td>Verify each battery connected cell float voltage is ≥ 2.07 V.</td>
<td></td>
</tr>
</tbody>
</table>

**SR 3.8.6.6**

---NOTE---

This Surveillance shall not be performed in MODE 1, 2, 3, or 4. However, portions of this Surveillance may be performed to reestablish OPERABILITY provided an assessment determines the safety of the plant is maintained or enhanced. Credit may be taken for unplanned events that satisfy this SR.

---

Verify battery capacity is ≥ 80% of the manufacturer's rating when subjected to a performance discharge test or a modified performance discharge test.

<p>| | |</p>
<table>
<thead>
<tr>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>60 months</td>
</tr>
<tr>
<td>AND</td>
<td></td>
</tr>
<tr>
<td>12 months when battery shows degradation, or has reached 85% of the expected life with capacity &lt; 100% of manufacturer's rating</td>
<td></td>
</tr>
<tr>
<td>AND</td>
<td></td>
</tr>
<tr>
<td>24 months when battery has reached 85% of the expected life with capacity ≥ 100% of manufacturer's rating</td>
<td></td>
</tr>
</tbody>
</table>
Inverters – Operating

3.8 ELECTRICAL POWER SYSTEMS

3.8.7 Inverters – Operating

LCO 3.8.7 Two inverters in Division I and two inverters in Division II are required to be OPERABLE.

---------------------------------------------NOTE---------------------------------------------
One inverter may be disconnected from its associated DC bus for \( \leq 24 \text{ hours} \) to perform an equalizing charge on its associated battery, provided:

- a. The associated AC vital bus is energized from its Class 1E regulating transformer, and
- b. All other AC vital buses are energized from their associated OPERABLE inverters.

--------------------------------------------------------------------------------------------------

APPLICABILITY: MODES 1, 2, 3, and 4.

<p>| ACTIONS |
|------------------------|------------------------|------------------------|</p>
<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. One inverter inoperable.</td>
<td>A.1 Enter applicable Conditions and Required Actions of LCO 3.8.9 “Distribution Systems – Operating,” with any AC vital bus de-energized.</td>
<td>24 hours</td>
</tr>
<tr>
<td>B. Required Action and associated Completion Time not met.</td>
<td>B.1 Be in MODE 3. AND B.2 Be in MODE 5.</td>
<td>6 hours 36 hours</td>
</tr>
<tr>
<td>SURVEILLANCE REQUIREMENTS</td>
<td></td>
<td></td>
</tr>
<tr>
<td>---------------------------</td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>SURVEILLANCE</strong></td>
<td><strong>FREQUENCY</strong></td>
<td></td>
</tr>
<tr>
<td>---------------------------</td>
<td>--------------------------</td>
<td></td>
</tr>
<tr>
<td>SR 3.8.7.1 Verify correct inverter voltage, frequency, and alignment to required AC vital buses.</td>
<td>7 days</td>
<td></td>
</tr>
</tbody>
</table>
Inverters shall be OPERABLE to support the onsite Class 1E AC Vital Bus Electrical Power Distribution System division(s) required by LCO 3.8.10, “Distribution Systems – Shutdown.”

APPLICABILITY: MODES 5 and 6, During movement of irradiated fuel assemblies.

ACTIONS

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. One or more required inverters inoperable.</td>
<td>A.1 Declare affected required feature(s) inoperable.</td>
<td>Immediately</td>
</tr>
<tr>
<td>OR</td>
<td>A.2.1 Suspend movement of irradiated fuel assemblies.</td>
<td>Immediately</td>
</tr>
<tr>
<td>AND</td>
<td>A.2.2 Suspend operations involving positive reactivity additions that could result in a loss of required SDM or boron concentration.</td>
<td>Immediately</td>
</tr>
<tr>
<td>AND</td>
<td>A.2.3 Initiate action to restore inverters to OPERABLE status.</td>
<td>Immediately</td>
</tr>
</tbody>
</table>
## SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.8.8.1</td>
<td>7 days</td>
</tr>
<tr>
<td>Verify correct inverter voltage, frequency, and alignment to required AC vital buses.</td>
<td></td>
</tr>
</tbody>
</table>
### ELECTRICAL POWER SYSTEMS

### Distribution Systems – Operating

**LCO 3.8.9** Division I and Division II AC, DC, and AC vital bus, electrical power distribution subsystems shall be OPERABLE.

**APPLICABILITY:** MODES 1, 2, 3, and 4.

**ACTIONS**

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. One or more AC electrical power distribution subsystems inoperable.</td>
<td>A.1 Enter applicable Conditions and Required Actions of LCO 3.8.4, “DC Sources – Operating,” for DC divisions made inoperable by inoperable power distribution subsystems.</td>
<td>8 hours</td>
</tr>
<tr>
<td>B. One or more AC vital buses inoperable.</td>
<td>B.1 Restore AC vital bus subsystem(s) to OPERABLE status.</td>
<td>2 hours</td>
</tr>
<tr>
<td>C. One or more DC electrical power distribution subsystems inoperable.</td>
<td>C.1 Restore DC electrical power distribution subsystem(s) to OPERABLE status.</td>
<td>2 hours</td>
</tr>
<tr>
<td>D. Required Action and associated Completion Time not met.</td>
<td>D.1 Be in MODE 3. AND D.2 Be in MODE 5.</td>
<td>6 hours AND 36 hours</td>
</tr>
</tbody>
</table>
### ACTIONS (continued)

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>E. Two or more electrical power distribution subsystems inoperable that result in a loss of safety function.</td>
<td>E.1 Enter LCO 3.0.3</td>
<td>Immediately</td>
</tr>
</tbody>
</table>

### SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.8.9.1 Verify correct breaker alignments and voltage to required AC, DC, and AC vital bus electrical power distribution subsystems.</td>
<td>7 days</td>
</tr>
</tbody>
</table>
3.8 ELECTRICAL POWER SYSTEMS

3.8.10 Distribution Systems – Shutdown

LCO 3.8.10 The necessary portion of AC, DC, and AC vital bus electrical power distribution subsystems shall be OPERABLE to support equipment required to be OPERABLE.

APPLICABILITY: MODES 5 and 6, During movement of irradiated fuel assemblies.

ACTIONS

---NOTE---

LCO 3.0.3 is not applicable.

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. One or more required AC, DC, or AC vital bus electrical power distribution subsystems inoperable.</td>
<td>A.1 Declare associated supported required feature(s) inoperable. OR A.2.1 Suspend movement of irradiated fuel assemblies. AND A.2.2 Suspend operations involving positive reactivity additions that could result in loss of required SDM or boron concentration. AND</td>
<td>Immediately</td>
</tr>
</tbody>
</table>
### ACTIONS (continued)

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. (continued)</td>
<td>A.2.3 Initiate actions to restore required AC, DC, and AC vital electrical power distribution subsystem(s) to OPERABLE status.</td>
<td>Immediately</td>
</tr>
<tr>
<td></td>
<td>AND</td>
<td></td>
</tr>
<tr>
<td></td>
<td>A.2.4 Declare associated required shutdown cooling train(s) inoperable and not in operation.</td>
<td>Immediately</td>
</tr>
</tbody>
</table>

### SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.8.10.1</td>
<td>7 days</td>
</tr>
</tbody>
</table>
3.9 REFUELING OPERATIONS

3.9.1 Boron Concentration

LCO 3.9.1 Boron concentrations of the Reactor Coolant System (RCS), the refueling canal, and the refueling pool shall be maintained within the limit specified in the COLR.

APPLICABILITY: MODE 6.

-----------------------------NOTE-----------------------------
Only applicable to the refueling canal and refueling pool when connected to the RCS.

--------------------------------------------------------------------------------------------------

ACTIONS

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. Boron concentration not within limit.</td>
<td>A.1 Suspend positive reactivity additions.</td>
<td>Immediately</td>
</tr>
<tr>
<td>AND</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>A.2 Initiate actions to restore boron concentration to within limit.</td>
<td>Immediately</td>
</tr>
</tbody>
</table>

SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.9.1.1</td>
<td>Verify boron concentration is within the limit specified in the COLR.</td>
</tr>
</tbody>
</table>
3.9 REFUELING OPERATIONS

3.9.2 Nuclear Instrumentation

LCO 3.9.2 Two startup channels of the Ex-core Neutron Flux Monitoring System (ENFMS) shall be OPERABLE.

APPLICABILITY: MODE 6.

ACTIONS

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. One startup channel of the ENFMS inoperable.</td>
<td>A.1 Suspend positive reactivity additions.</td>
<td>Immediately</td>
</tr>
<tr>
<td>AND</td>
<td>A.2 Suspend operations that would cause introduction of coolant into the Reactor Coolant System (RCS) with boron concentration less than required to meet the boron concentration of LCO 3.9.1.</td>
<td>Immediately</td>
</tr>
<tr>
<td>B. Two startup channels of the ENFMS inoperable.</td>
<td>B.1 Initiate action to restore one startup channel of the ENFMS to OPERABLE status.</td>
<td>Immediately</td>
</tr>
<tr>
<td>AND</td>
<td>B.2 Perform SR 3.9.1.1.</td>
<td>Once per 12 hours</td>
</tr>
</tbody>
</table>
### SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.9.2.1 Perform CHANNEL CHECK.</td>
<td>12 hours</td>
</tr>
<tr>
<td>SR 3.9.2.2 Neutron detectors are excluded from CHANNEL CALIBRATION.</td>
<td>18 months</td>
</tr>
<tr>
<td>Perform CHANNEL CALIBRATION.</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
</tr>
</tbody>
</table>
3.9 REFUELING OPERATIONS

3.9.3 Containment Penetrations

LCO 3.9.3 The containment penetrations shall be in the following status:

a. The equipment hatch closed and held in place by [four bolts];

b. One door in each airlock closed; and

c. Each penetration providing direct access from the containment atmosphere to the outside atmosphere is either:

   1. Closed by a manual or automatic isolation valve, blind flange, or equivalent, or

   2. Capable of being closed by an OPERABLE Containment Purge System.

APPLICABILITY: During CORE ALTERATIONS,
During movement of irradiated fuel assemblies within containment.

ACTIONS

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. One or more containment penetrations not in required status.</td>
<td>A.1 Suspend CORE ALTERATIONS.</td>
<td>Immediately</td>
</tr>
<tr>
<td>AND</td>
<td>A.2 Suspend movement of irradiated fuel assemblies within containment.</td>
<td>Immediately</td>
</tr>
</tbody>
</table>

Immediatly
## SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>SR 3.9.3.1</strong> Verify each required containment penetration is in the required status.</td>
<td>Within 100 hours prior to the start of movement of irradiated fuel within containment AND Once per 7 days during CORE ALTERATIONS or movement of irradiated fuel within containment</td>
</tr>
<tr>
<td><strong>SR 3.9.3.2</strong> Verify each required containment purge and exhaust valve actuates to the isolation position on an actual or simulated actuation signal.</td>
<td>18 months</td>
</tr>
</tbody>
</table>
3.9 REFUELING OPERATIONS

3.9.4 Shutdown Cooling System (SCS) and Coolant Circulation – High Water Level

LCO 3.9.4 One shutdown cooling (SC) train shall be OPERABLE and in operation.

---------------------------------------------NOTE---------------------------------------------
The required SC train may be removed from operation for ≤ 1 hour per 8 hour period, provided no operations are permitted that would cause introduction of coolant into the Reactor Coolant System (RCS) with boron concentration less than required to meet the minimum required boron concentration of LCO 3.9.1.

--------------------------------------------------------------------------------------------------

APPLICABILITY: MODE 6 with the water level ≥ 7.0 m (23 ft) above the top of the reactor vessel flange.

ACTIONS

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. One required SC train inoperable or not in operation.</td>
<td>A.1 Initiate action to restore one SC train to OPERABLE status and operation.</td>
<td>Immediately</td>
</tr>
<tr>
<td>AND</td>
<td></td>
<td></td>
</tr>
<tr>
<td>A.2 Suspend operations that would cause introduction of coolant into the RCS with boron concentration less than that required to meet the boron concentration of LCO 3.9.1.</td>
<td></td>
<td>Immediately</td>
</tr>
<tr>
<td>AND</td>
<td></td>
<td></td>
</tr>
<tr>
<td>A.3 Suspend loading irradiated fuel assemblies in the core.</td>
<td></td>
<td>Immediately</td>
</tr>
<tr>
<td>AND</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
### ACTIONS (continued)

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. (continued)</td>
<td>A.4 Place the containment building penetrations in the required status as specified in LCO 3.6.7.</td>
<td>4 hours</td>
</tr>
</tbody>
</table>

### SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.9.4.1</td>
<td>Verify one SC train is in operation and circulating reactor coolant at a flow rate of $\geq 15,710$ L/min (4,150 gpm).</td>
</tr>
<tr>
<td>SR 3.9.4.2</td>
<td>Verify required SC train piping locations susceptible to gas accumulation are sufficiently filled with water.</td>
</tr>
</tbody>
</table>
3.9 REFUELING OPERATIONS

3.9.5 Shutdown Cooling System (SCS) and Coolant Circulation – Low Water Level

LCO 3.9.5 The heat removal system shall be in the following status:

a. Two shutdown cooling (SC) trains shall be OPERABLE and one SC train shall be in operation.

b. When Reactor Coolant System (RCS) level is < 38.72 m (127 ft 1/4 in), the containment spray pump in the same electrical division as an operating SC train shall be OPERABLE.

APPLICABILITY: MODE 6 with the water level < 7.0 m (23 ft) above the top of the reactor vessel flange.

ACTIONS

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. One SC train inoperable.</td>
<td>A.1 Initiate action to restore SC train to OPERABLE status.</td>
<td>Immediately</td>
</tr>
<tr>
<td>OR</td>
<td>A.2 Initiate action to establish ≥ 7.0 m (23 ft) of water above the top of the reactor vessel flange.</td>
<td>Immediately</td>
</tr>
</tbody>
</table>
### ACTIONS (continued)

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>B. Two SC trains inoperable. OR No SC train in operation.</td>
<td>B.1 Suspend operations that would cause introduction of coolant into the RCS with boron concentration less than required to meet the boron concentration of LCO 3.9.1.</td>
<td>Immediately</td>
</tr>
<tr>
<td>AND</td>
<td>B.2 Initiate action to restore one SC train to OPERABLE status and to operation.</td>
<td>Immediately</td>
</tr>
<tr>
<td>AND</td>
<td>B.3 Initiate action to raise RCS level to $\geq 38.72$ m ($127$ ft $1/4$ in.).</td>
<td>Immediately</td>
</tr>
<tr>
<td>AND</td>
<td>B.4 Place the containment building penetrations in the required status as specified in LCO 3.6.7.</td>
<td>4 hours</td>
</tr>
</tbody>
</table>
### ACTIONS (continued)

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>C.  Containment spray pump in the same electrical division as an operating SC train inoperable with RCS level &lt; 38.72 m (127 ft 1/4 in).</td>
<td>C.1 If the containment spray pump in the same electrical division as the alternate SC train is OPERABLE, initiate action to place the alternate SC train in operation.</td>
<td>Immediately</td>
</tr>
<tr>
<td>AND</td>
<td>C.2 Monitor SC System performance.</td>
<td>Every 30 minutes</td>
</tr>
<tr>
<td>AND</td>
<td>C.3 Restore containment spray pump to OPERABLE status.</td>
<td>48 hours</td>
</tr>
<tr>
<td>D.  Required Action and associated Completion Time of Required Action C.3 not met.</td>
<td>D.1 Raise RCS level to ≥ 38.72 m (127 ft 1/4 in).</td>
<td>6 hours</td>
</tr>
</tbody>
</table>

### SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.9.5.1</td>
<td>12 hours</td>
</tr>
<tr>
<td>Verify required SC trains are OPERABLE and one SC train is in operation with circulating reactor coolant at a flow rate of ≥ 15,709 L/min (4,150 gpm) at RCS level ≥ 38.72 m (127 ft 1/4 in) or ≥ 14,385 L/min (3,800 gpm) and &lt; 15,710 L/min (4,150 gpm) at RCS level &lt; 38.72 m (127 ft 1/4 in).</td>
<td></td>
</tr>
<tr>
<td>SR 3.9.5.2</td>
<td>7 days</td>
</tr>
<tr>
<td>Verify correct breaker alignment and indicated power available to the required SC pump that is not in operation.</td>
<td></td>
</tr>
</tbody>
</table>
### SURVEILLANCE REQUIREMENTS (continued)

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.9.5.3 Verify correct breaker alignment and indicated power available to</td>
<td>24 hours at RCS level &lt; 38.72 m (127 ft 1/4 in)</td>
</tr>
<tr>
<td>the required CS pump.</td>
<td></td>
</tr>
<tr>
<td>------------------------------------------------------------------------------</td>
<td>------------------------------------------------</td>
</tr>
<tr>
<td>SR 3.9.5.4 Verify required SC train piping locations susceptible to gas</td>
<td>31 days</td>
</tr>
<tr>
<td>accumulation are sufficiently filled with water.</td>
<td></td>
</tr>
</tbody>
</table>
3.9 REFUELING OPERATIONS

3.9.6 Refueling Water Level

LCO 3.9.6 Refueling water level shall be maintained ≥ 7 m (23 ft) above the top of reactor vessel flange.

APPLICABILITY: During CORE ALTERATIONS, except during latching and unlatching of control rod drive shafts, During movement of irradiated fuel assemblies within containment.

ACTIONS

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. Refueling water level not within limit.</td>
<td>A.1 Suspend CORE ALTERATIONS.</td>
<td>Immediately</td>
</tr>
<tr>
<td></td>
<td>AND</td>
<td></td>
</tr>
<tr>
<td></td>
<td>A.2 Suspend movement of irradiated fuel assemblies within containment.</td>
<td>Immediately</td>
</tr>
<tr>
<td></td>
<td>AND</td>
<td></td>
</tr>
<tr>
<td></td>
<td>A.3 Initiate actions to restore refueling water level to within limits.</td>
<td>Immediately</td>
</tr>
</tbody>
</table>

SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.9.6.1</td>
<td>24 hours</td>
</tr>
</tbody>
</table>
3.9 REFUELING OPERATIONS

3.9.7 Unborated Water Source Isolation Valve – MODE 6

LCO 3.9.7 The CV-186 valve used to isolate unborated water sources shall be secured in the closed position.

APPLICABILITY: MODE 6.

ACTIONS

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. Valve not secured in closed position.</td>
<td>A.1 Suspend CORE ALTERATIONS.</td>
<td>Immediately</td>
</tr>
<tr>
<td></td>
<td>AND</td>
<td></td>
</tr>
<tr>
<td></td>
<td>A.2 Initiate actions to secure valve in closed position.</td>
<td>Immediately</td>
</tr>
<tr>
<td></td>
<td>AND</td>
<td></td>
</tr>
<tr>
<td></td>
<td>A.3 Perform SR 3.9.1.1.</td>
<td>4 hours</td>
</tr>
</tbody>
</table>

SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.9.7.1 Verify the valve that isolates unborated water sources is secured in the closed position.</td>
<td>7 days</td>
</tr>
</tbody>
</table>
3.9 REFUELING OPERATIONS

3.9.8 Decay Time

LCO 3.9.8 The reactor shall be subcritical for $\geq 100$ hours.

APPLICABILITY: During movement of irradiated fuel assemblies in the reactor pressure vessel.

ACTIONS

<table>
<thead>
<tr>
<th>CONDITION</th>
<th>REQUIRED ACTION</th>
<th>COMPLETION TIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. Reactor subcritical $&lt; 100$ hours.</td>
<td>A.1 Suspend all operations involving movement of irradiated fuel assemblies in the reactor pressure vessel.</td>
<td>Immediately</td>
</tr>
</tbody>
</table>

SURVEILLANCE REQUIREMENTS

<table>
<thead>
<tr>
<th>SURVEILLANCE</th>
<th>FREQUENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR 3.9.8.1 Verify that the reactor has been subcritical for $\geq 100$ hours by verification of the date and time of subcriticality.</td>
<td>Prior to movement of irradiated fuel assemblies in the reactor vessel</td>
</tr>
</tbody>
</table>
4.0 DESIGN FEATURES

4.1 Site Location

[Text description of site location.]

4.2 Reactor Core

4.2.1 Fuel Assemblies

The reactor shall contain 241 fuel assemblies. Each assembly shall consist of a matrix of zirconium alloy clad fuel rods with an initial composition of natural or slightly enriched uranium dioxide (UO₂) as fuel material. Limited substitutions of zirconium alloy or stainless steel filler rods for fuel rods, in accordance with approved applications of fuel rod configurations, may be used. Fuel assemblies shall be limited to those fuel designs that have been analyzed with applicable NRC staff approved codes and methods and shown by tests or analyses to comply with all fuel safety design bases. A limited number of lead test assemblies that have not completed representative testing may be placed in non-limiting core regions.

4.2.2 Control Rod Assemblies

The reactor core shall contain 81 full strength and 12 part strength control element assemblies (CEAs). The control material of full strength and part strength CEAs shall be boron carbide and Inconel Alloy 625, respectively.

4.3 Fuel Storage

4.3.1 Criticality

4.3.1.1 The spent fuel storage racks are designed and shall be maintained with:

a. Fuel assemblies having a maximum U-235 enrichment of 5 weight percent;

b. \( k_{\text{eff}} < 1.0 \) if flooded with unborated water and \( k_{\text{eff}} \leq 0.95 \) if flooded with water borated to 1231 ppm enriched, which includes an allowance for uncertainties;

c. A nominal (27.5 cm (10.83 in)) center-to-center distance between fuel assemblies placed in Region I of the spent fuel storage racks;

d. A nominal (22.5 cm (8.86 in)) center-to-center distance between fuel assemblies placed in Region II of the spent fuel storage racks;
4.0 DESIGN FEATURES

4.3 Fuel Storage (continued)

e. Fuel assemblies with a discharge burnup in the "acceptable domain" of Figure 3.7.16-1 may be allowed unrestricted storage in Region I or Region II of Figure 4.3-1; and

f. New or partially spent fuel assemblies with a discharge burnup in the "unacceptable domain" of Figure 3.7.16-1 shall be stored only in Region I of Figure 4.3-1.

4.3.1.2 The new fuel storage racks are designed and shall be maintained with:

a. Fuel assemblies having a maximum U-235 enrichment of 5 weight percent;

b. \( k_{\text{eff}} \leq 0.95 \) if fully flooded with unborated water, or mist, which includes an allowance for uncertainties as described in FSAR Section 9.1, “Fuel Storage and Handling.”;

c. \( k_{\text{eff}} \leq 0.98 \) if moderated by aqueous foam, which includes an allowance for uncertainties as described in FSAR Section 9.1, “Fuel Storage and Handling.”; and

d. A nominal center-to-center distance between fuel assemblies placed in the new fuel storage racks of 35.5 cm (14 in).

4.3.2 Drainage

The spent fuel pool is designed and shall be maintained to prevent inadvertent draining of the pool below a water level of 7 m (23 ft) above the top of the spent fuel storage rack.

4.3.3 Capacity

The spent fuel pool is designed and shall be maintained with a storage capacity limited to no more than 1,792 fuel assemblies.
Figure 4.3-1 (page 1 of 1)
Discrete Two Region Spent Fuel Storage Rack Layout
5.0 ADMINISTRATIVE CONTROLS

5.1 Responsibility

1. Titles for members of the unit staff shall be specified by use of an overall statement referencing an ANSI Standard acceptable to the NRC staff from which the titles were obtained, or an alternative title may be designated for this position. Generally, the first method is preferable; however, the second method is adaptable to those unit staffs requiring special titles because of unique organizational structures.

2. The ANSI Standard shall be the same ANSI Standard referenced in Section 5.3, Unit Staff Qualifications. If alternative titles are used, all requirements of these Technical Specifications apply to the position with the alternative title as apply with the specified title. Unit staff titles shall be specified in the Final Safety Analysis Report or Quality Assurance Plan. Unit staff titles shall be maintained and revised using those procedures approved for modifying/revising the Final Safety Analysis Report or Quality Assurance Plan.

5.1.1 The plant manager shall be responsible for overall unit operation and shall delegate in writing the succession to this responsibility during his absence. The plant manager or his designee shall approve, prior to implementation, each proposed test, experiment, or modification to systems or equipment that affects nuclear safety.

5.1.2 The Shift Supervisor (SS) shall be responsible for the control room command function. During any absence of the SS from the control room while the unit is in MODE 1, 2, 3, or 4, an individual with an active Senior Reactor Operator (SRO) license shall be designated to assume the control room command function. During any absence of the SS from the control room while the unit is in MODE 5 or 6, an individual with an active SRO license or Reactor Operator license shall be designated to assume the control room command function.
5.0 ADMINISTRATIVE CONTROLS

5.2 Organization

5.2.1 Onsite and Offsite Organizations

Onsite and offsite organizations shall be established for unit operation and corporate management, respectively. The onsite and offsite organizations shall include the positions for activities affecting safety of the nuclear power plant.

a. Lines of authority, responsibility, and communication shall be defined and established throughout highest management levels, intermediate levels, and all operating organization positions. These relationships shall be documented and updated, as appropriate, in organization charts, functional descriptions of departmental responsibilities and relationships, and job descriptions for key personnel positions, or in equivalent forms of documentation. These requirements including the plant-specific titles of those personnel fulfilling the responsibilities of the positions delineated in these Technical Specifications shall be documented in the Final Safety Analysis Report (FSAR)/Quality Assurance (QA) Plan,

b. The plant manager shall be responsible for overall safe operation of the plant and shall have control over those onsite activities necessary for safe operation and maintenance of the plant,

c. A specified corporate officer shall have corporate responsibility for overall plant nuclear safety and shall take any measures needed to ensure acceptable performance of the staff in operating, maintaining, and providing technical support to the plant to ensure nuclear safety, and

d. The individuals who train the operating staff, carry out health physics, or perform quality assurance functions may report to the appropriate onsite manager; however, these individuals shall have sufficient organizational freedom to ensure their independence from operating pressures.
5.2 Organization

5.2.2 Unit Staff

The unit staff organization shall include the following:

a. A non-licensed operator shall be assigned to each reactor containing fuel and an additional non-licensed operator shall be assigned for each control room from which a reactor is operating in MODE 1, 2, 3, or 4.

[---------------------------------------REVIEWER'S NOTE----------------------------------------
Two unit sites with both units shutdown or defueled require a total of three non-licensed operators for the two units.
-----------------------------------------------------------------------------------------------------------]

b. Shift crew composition may be less than the minimum requirement of 10 CFR 50.54(m)(2)(i) and 5.2.2.a and 5.2.2.e for a period of time not to exceed 2 hours in order to accommodate unexpected absence of on-duty shift crew members provided immediate action is taken to restore the shift crew composition to within the minimum requirements.

c. A radiation protection technician shall be on site when fuel is in the reactor. The position may be vacant for not more than 2 hours, in order to provide for unexpected absence, provided immediate action is taken to fill the required position.

d. The operations manager or assistant operations manager shall hold an Senior Reactor Operator (SRO) license.

e. An individual shall provide advisory technical support to the unit operations shift crew in the areas of thermal hydraulics, reactor engineering, and plant analysis with regard to the safe operation of the unit. This individual shall meet the qualifications specified by the Commission Policy Statement on Engineering Expertise on Shift.
5.0 ADMINISTRATIVE CONTROLS

5.3 Unit Staff Qualifications

[-------------------------------------------------REVIEWER'S NOTE--------------------------------------------------]
Minimum qualifications for members of the unit staff shall be specified by use of an overall qualification statement referencing an ANSI Standard acceptable to the NRC staff or by specifying individual position qualifications. Generally, the first method is preferable; however, the second method is adaptable to those unit staffs requiring special qualification statements because of unique organizational structures.
[-------------------------------------------------REVIEWER'S NOTE--------------------------------------------------]

5.3.1 Each member of the unit staff shall meet or exceed the minimum qualifications of [Nuclear Regulatory Commission (NRC) Regulatory Guide (RG) 1.8, Revision 2, 1987, or more recent revisions, or ANSI Standard acceptable to the NRC staff]. [The staff not covered by NRC RG 1.8 shall meet or exceed the minimum qualifications of Regulations, NRC RGs, or ANSI Standards acceptable to NRC staff].

5.3.2 For the purpose of 10 CFR 55.4, a licensed Senior Reactor Operator (SRO) and a licensed Reactor Operator (RO) are those individuals who, in addition to meeting the requirements of Specification 5.3.1, perform the functions described in 10 CFR 50.54(m).
5.0 ADMINISTRATIVE CONTROLS

5.4 Procedures

5.4.1 Written procedures shall be established, implemented, and maintained covering the following activities:

a. The applicable procedures recommended in Nuclear Regulatory Commission (NRC) Regulatory Guide (RG) 1.33, Revision 2, Appendix A, February 1978,

b. The emergency operating procedures required to implement the requirements of NUREG-0737 and to NUREG-0737, Supplement 1, as stated in Generic Letter 82-33,

c. Quality assurance for effluent and environmental monitoring,

d. Fire Protection Program implementation, and

e. All programs specified in Specification 5.5.

f. [Modification of core protection calculator (CPC) addressable constants. These procedures shall include provisions to ensure that sufficient margin is maintained in CPC type I addressable constants to avoid excessive operator interaction with CPCs during reactor operation.

Modifications to the CPC software (including changes of algorithms and fuel cycle specific data) shall be performed in accordance with the most recent version of “CPC Protection Algorithm Software Change Procedure,” CEN-39(A)-P, which has been determined to be applicable to the facility. Additions or deletions to CPC addressable constants or changes to addressable constant software limit values shall not be implemented without prior NRC approval.]
5.0 ADMINISTRATIVE CONTROLS

5.5 Programs and Manuals

The following programs shall be established, implemented, and maintained.

5.5.1 Offsite Dose Calculation Manual (ODCM)

   a. The ODCM shall contain the methodology and parameters used in the calculation of offsite doses resulting from radioactive gaseous and liquid effluents, in the calculation of gaseous and liquid effluent monitoring alarm and trip setpoints, and in the conduct of the radiological environmental monitoring program and

   b. The ODCM shall also contain the radioactive effluent controls and radiological environmental monitoring activities, and descriptions of the information that should be included in the Annual Radiological Environmental Operating, and Radiological Effluent Release Reports required by Specification 5.6.1 and Specification 5.6.2.

Licensee initiated changes to the ODCM:

   a. Shall be documented and records of reviews performed shall be retained. This documentation shall contain:

      1. Sufficient information to support the change(s) together with the appropriate analyses or evaluations justifying the change(s) and

      2. A determination that the change(s) maintain the levels of radioactive effluent control required by 10 CFR 20.1302, 40 CFR 190, 10 CFR 50.36a, and 10 CFR 50, Appendix I, and not adversely impact the accuracy or reliability of effluent, dose, or setpoint calculations,

   b. Shall become effective after the approval of the plant manager, and

   c. Shall be submitted to the NRC in the form of a complete, legible copy of the entire ODCM as a part of or concurrent with the Radiological Effluent Release Report for the period of the report in which any change in the ODCM is made. Each change shall be identified by markings in the margin of the affected pages, clearly indicating the area of the page that was changed, and shall indicate the date (i.e., month and year) the change was implemented.
5.5 Programs and Manuals

5.5.2 Primary Coolant Sources Outside Containment

This program provides controls to minimize leakage from those portions of systems outside containment that could contain highly radioactive fluids during a serious transient or accident to levels as low as practicable. The systems include Containment Spray System, Safety Injection System, Chemical and Volume Control System, Gaseous Waste Management System and Containment Hydrogen Control System. The program shall include the following:

a. Preventive maintenance and periodic visual inspection requirements and

b. Integrated leak rate test requirements for each system at least once per 18 months.

The provisions of SR 3.0.2 are applicable.

5.5.3 Post-Accident Sampling

--------------------------------------------------------------------------REVIEWER'S NOTE--------------------------------------------------------------------------

This program may be eliminated based on the implementation of Topical Report CE NPSD-1157, Rev. 1, "Technical Justification for the Elimination of the Post-Accident Sampling System from the Plant Design and Licensing Basis for CEOG Utilities," and the associated NRC Safety Evaluation dated May 16, 2000, and implementation of the following commitments:

1. The COL applicant has developed contingency plans for obtaining and analyzing highly radioactive samples of reactor coolant, containment sump, and containment atmosphere. The contingency plans will be contained in emergency plan implementing procedures and implemented with the implementation of the License amendment. Establishment of contingency plans is considered a regulatory commitment.

2. The capability for classifying fuel damage events at the Alert level threshold has been established for PLANT at radioactivity levels of 1.11E10 Bq/cc (300 mCi/cc) dose equivalent iodine. This capability may utilize the normal sampling system and/or correlations of sampling or letdown line dose rates to coolant concentrations. This capability will be described in emergency plan implementing procedures and implemented with the implementation of the License amendment. The capability for classifying fuel damage events is considered a regulatory commitment.

3. The COL applicant has established the capability to monitor radioactive iodines that have been released to offsite environs. This capability is described in our emergency plan implementing procedures. The capability to monitor radioactive iodines is considered a regulatory commitment.

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5.5 Programs and Manuals

5.5.3 Post-Accident Sampling (continued)

This program provides controls that ensure the capability to obtain and analyze reactor coolant, radioactive gases, and particulates in plant gaseous effluents and containment atmosphere samples under accident conditions. This program shall include the following:

a. Training of personnel,

b. Procedures for sampling and analysis, and

c. Provisions for maintenance of sampling and analysis equipment.

5.5.4 Radioactive Effluents Controls Program

This program conforms to 10 CFR 50.36a for the control of radioactive effluents and for maintaining the doses to members of the public from radioactive effluents as low as reasonably achievable. The program shall be contained in the ODCM, shall be implemented by procedures, and shall include remedial actions to be taken whenever the program limits are exceeded. The program shall include the following elements:

a. Limitations on the functional capability of radioactive liquid and gaseous monitoring instrumentation including surveillance tests and setpoint determination in accordance with the methodology in the ODCM,

b. Limitations on the concentrations of radioactive material released in liquid effluents to unrestricted areas, conforming to ten times the concentration values in Appendix B, Table 2, Column 2 to 10 CFR 20.1001-20.2402,

c. Monitoring, sampling, and analysis of radioactive liquid and gaseous effluents in accordance with 10 CFR 20.1302 and with the methodology and parameters in the ODCM,

d. Limitations on the annual and quarterly doses or dose commitment to a member of the public from radioactive materials in liquid effluents released from each unit to unrestricted areas, conforming to 10 CFR 50, Appendix I,

e. Determination of cumulative dose contributions from radioactive effluents for the current calendar quarter and current calendar year in accordance with the methodology and parameters in the ODCM at least every 31 days. Determination of projected dose contributions from radioactive effluents in accordance with the methodology in the ODCM at least every 31 days,
5.5 Programs and Manuals

5.5.4 Radioactive Effluents Controls Program (continued)

f. Limitations on the functional capability and use of the liquid and gaseous effluent treatment systems to ensure that appropriate portions of these systems are used to reduce releases of radioactivity when the projected doses in a period of 31 days would exceed 2% of the guidelines for the annual dose or dose commitment, conforming to 10 CFR 50, Appendix I.

g. Limitations on the dose rate resulting from radioactive material released in gaseous effluents from the site to areas at or beyond the site boundary shall be in accordance with the following:

1. For noble gases: a dose rate \( \leq 5 \text{ mSv/yr (500 mrem/yr)} \) to the whole body and a dose rate \( \leq 30 \text{ mSv/yr (3000 mrem/yr)} \) to the skin and

2. For iodine-131, iodine-133, tritium, and all radionuclides in particulate form with half-lives < 8 days: a dose rate \( \leq 15 \text{ mSv/yr (1500 mrem/yr)} \) to any organ.

h. Limitations on the annual and quarterly air doses resulting from noble gases released in gaseous effluents from each unit to areas beyond the site boundary, conforming to 10 CFR 50, Appendix I,

i. Limitations on the annual and quarterly doses to a member of the public from iodine-131, iodine-133, tritium, and all radionuclides in particulate form with half-lives > 8 days in gaseous effluents released from each unit to areas beyond the site boundary, conforming to 10 CFR 50, Appendix I, and

j. Limitations on the annual dose or dose commitment to any member of the public, beyond the site boundary, due to releases of radioactivity and to radiation from uranium fuel cycle sources, conforming to 40 CFR 190.

The provisions of SR 3.0.2 and SR 3.0.3 are applicable to the Radioactive Effluents Controls Program surveillance frequency.
5.5 Programs and Manuals

5.5.5 Component Cyclic or Transient Limit

This program provides controls to track the FSAR Section 3.9 and Table 3.9-1, cyclic and transient occurrences to ensure that components are maintained within the design limits.

5.5.6 Pre-Stressed Concrete Containment Tendon Surveillance Program

This program provides controls for monitoring any tendon degradation in prestressed concrete containments, including effectiveness of its corrosion protection medium, to ensure containment structural integrity. The program shall include baseline measurements prior to initial operations. The Tendon Surveillance Program, inspection frequencies, and acceptance criteria shall be in accordance with Section XI, Subsection IWL of the ASME Boiler and Pressure Vessel Code and applicable addenda as required by 10 CFR 50.55a, except where an alternative, exemption, or relief has been authorized by the NRC.

The provisions of SR 3.0.3 are applicable to the Tendon Surveillance Program inspection frequencies.

5.5.7 Reactor Coolant Pump Flywheel Inspection Program

This program shall provide for the inspection of each reactor coolant pump flywheel per the recommendation of regulatory position c.4.b of Nuclear Regulatory Commission (NRC) Regulatory Guide (RG) 1.14, Revision 1, August 1975.
5.5.8 Inservice Testing Program

This program provides controls for inservice testing of ASME Code Class 1, 2, and 3 components. The program shall include the following:

a. Testing frequencies applicable to the ASME Code for Operations and Maintenance of Nuclear Power Plants (ASME OM Code) and applicable Addenda as follows:

<table>
<thead>
<tr>
<th>ASME OM Code and applicable Addenda terminology for inservice testing activities</th>
<th>Required Frequencies for performing inservice testing activities</th>
</tr>
</thead>
<tbody>
<tr>
<td>Weekly</td>
<td>At least once per 7 days</td>
</tr>
<tr>
<td>Monthly</td>
<td>At least once per 31 days</td>
</tr>
<tr>
<td>Quarterly or every 3 months</td>
<td>At least once per 92 days</td>
</tr>
<tr>
<td>Semiannually or every 6 months</td>
<td>At least once per 184 days</td>
</tr>
<tr>
<td>Every 9 months</td>
<td>At least once per 276 days</td>
</tr>
<tr>
<td>Yearly or annually</td>
<td>At least once per 366 days</td>
</tr>
<tr>
<td>Biennially or every 2 years</td>
<td>At least once per 731 days</td>
</tr>
</tbody>
</table>

b. The provisions of SR 3.0.2 are applicable to the above required Frequencies and to other normal and accelerated Frequencies specified as 2 years or less in the Inservice Testing Program for performing inservice testing activities,

c. The provisions of SR 3.0.3 are applicable to inservice testing activities, and

d. Nothing in the ASME OM Code shall be construed to supersede the requirements of any Technical Specification.
5.5.9 Steam Generator (SG) Program

A Steam Generator Program shall be established and implemented to ensure that SG tube integrity is maintained. In addition, the Steam Generator Program shall include the following provisions:

a. Provisions for condition monitoring assessments. Condition monitoring assessment means an evaluation of the “as found” condition of the tubing with respect to the performance criteria for structural integrity and accident induced leakage. The “as found” condition refers to the condition of the tubing during an SG inspection outage, as determined from the inservice inspection results or by other means, prior to the plugging of tubes. Condition monitoring assessments shall be conducted during each outage during which the SG tubes are inspected or plugged to confirm that the performance criteria are being met.

b. Performance criteria for SG tube integrity. SG tube integrity shall be maintained by meeting the performance criteria for tube structural integrity, accident induced leakage, and operational LEAKAGE.

1. Structural integrity performance criterion: All inservice steam generator tubes shall retain structural integrity over the full range of normal operating conditions (including startup, operation in the power range, hot standby, and cool down) and all anticipated transients included in the design specification and design basis accidents. This includes retaining a safety factor of 3.0 against burst under normal steady state full power operation primary-to-secondary pressure differential and a safety factor of 1.4 against burst applied to the design basis accident primary-to-secondary pressure differentials. Apart from the above requirements, additional loading conditions associated with the design basis accidents, or combination of accidents in accordance with the design and licensing basis, shall also be evaluated to determine if the associated loads contribute significantly to burst or collapse. In the assessment of tube integrity, those loads that do significantly affect burst or collapse shall be determined and assessed in combination with the loads due to pressure with a safety factor of 1.2 on the combined primary loads and 1.0 on axial secondary loads.
5.5.9  **Steam Generator (SG) Program** (continued)

2. Accident induced LEAKAGE performance criterion: The primary-to-secondary accident-induced LEAKAGE rate for any design basis accident, other than a SG tube rupture, shall not exceed the LEAKAGE rate assumed in the accident analysis in terms of total LEAKAGE rate for all SGs and leakage rate for an individual SG. LEAKAGE is not to exceed 1.14 L/min (0.3 gpm) per SG.

3. The operational LEAKAGE performance criterion is specified in LCO 3.4.12, “RCS Operational LEAKAGE.”

c. Provisions for SG tube plugging criteria. Tubes found by in-service inspection to contain flaws with a depth equal to or exceeding 40% of the nominal tube wall thickness shall be plugged.

d. Provisions for SG tube inspections. Periodic SG tube inspections shall be performed. The number and portions of the tubes inspected and methods of inspection shall be performed with the objective of detecting flaws of any type (e.g., volumetric flaws, axial and circumferential cracks) that may be present along the length of the tube, from the tube-to-tubesheet weld at the tube inlet to the tube-to-tubesheet weld at the tube outlet, and that may satisfy the applicable tube plugging criteria. The tube-to-tubesheet weld is not part of the tube. In addition to meeting the requirements of d.1, d.2, and d.3 below, the inspection scope, inspection methods, and inspection intervals shall be such as to ensure that SG tube integrity is maintained until the next SG inspection. An assessment of degradation shall be performed to determine the type and location of flaws to which the tubes may be susceptible and, based on this assessment, to determine which inspection methods need to be employed and at what locations.
5.5 Programs and Manuals

5.5.9 Steam Generator (SG) Program (continued)

1. Inspect 100% of the tubes in each SG during the first refueling outage following SG installation.

2. After the first refueling outage following SG installation, inspect each SG at least every 72 effective full power months or at least every third refueling outage (whichever results in more frequent inspections). In addition, the minimum number of tubes inspected at each scheduled inspection shall be the number of tubes in all SGs divided by the number of SG inspection outages scheduled in each inspection period as defined in a, b, c and d below. If a degradation assessment indicates the potential for a type of degradation to occur at a location not previously inspected with a technique capable of detecting this type of degradation at this location and that may satisfy the applicable tube plugging criteria, the minimum number of locations inspected with such a capable inspection technique during the remainder of the inspection period may be prorated. The fraction of locations to be inspected for this potential type of degradation at this location at the end of the inspection period shall be no less than the ratio of the number of times the SG is scheduled to be inspected in the inspection period after the determination that a new form of degradation could potentially be occurring at this location divided by the total number of times the SG is scheduled to be inspected in the inspection period. Each inspection period defined below may be extended up to 3 effective full power months to include a SG inspection outage in an inspection period and the subsequent inspection period begins at the conclusion of the included SG inspection outage.

   a) After the first refueling outage following SG installation, inspect 100% of the tubes during the next 144 effective full power months. This constitutes the first inspection period;

   b) During the next 120 effective full power months, inspect 100% of the tubes. This constitutes the second inspection period;

   c) During the next 96 effective full power months, inspect 100% of the tubes. This constitutes the third inspection period; and

   d) During the remaining life of the SGs, inspect 100% of the tubes every 72 effective full power months. This constitutes the fourth and subsequent inspection periods.
5.5 Programs and Manuals

5.5.9 Steam Generator (SG) Program (continued)

3. If crack indications are found in any SG tube, then the next inspection for each affected and potentially affected SG for the degradation mechanism that caused the crack indication shall not exceed 24 effective full power months or one refueling outage (whichever results in more frequent inspections). If definitive information, such as from examination of a pulled tube, diagnostic non-destructive testing, or engineering evaluation indicates that a crack-like indication is not associated with a crack(s), then the indication need not be treated as a crack.

e. Provisions for monitoring operational primary-to-secondary LEAKAGE.

5.5.10 Secondary Water Chemistry Program

This program provides controls for monitoring secondary water chemistry to inhibit SG tube degradation and low pressure turbine disc stress corrosion cracking. The program shall include:

a. Identification of a sampling schedule for the critical variables and control points for these variables,

b. Identification of the procedures used to measure the values of the critical variables,

c. Identification of process sampling points, which shall include monitoring the discharge of the condensate pumps for evidence of condenser in leakage,

d. Procedures for the recording and management of data,

e. Procedures defining corrective actions for all off control point chemistry conditions, and

f. A procedure identifying the authority responsible for the interpretation of the data and the sequence and timing of administrative events, which is required to initiate corrective action.
5.5 Programs and Manuals

5.5.11 Ventilation Filter Testing Program (VFTP)

A program shall be established to implement the following required testing of Engineered Safety Feature (ESF) Filter Ventilation Systems in accordance with NRC RG 1.52, Revision 4, ASME N511-2007, and AG-1-2009 at the system flow rate specified below ± 10%.

a. Demonstrate for each of the ESF Systems that an in-place test of the high efficiency particulate air (HEPA) filters shows a penetration and system bypass < 0.05% when tested in accordance with Nuclear Regulatory Commission (NRC) Regulatory Guide (RG) 1.52, Revision 4, and ASME N511-2007 at the system flow rate specified below ± 10%:

<table>
<thead>
<tr>
<th>ESF Ventilation System</th>
<th>Flowrate</th>
</tr>
</thead>
<tbody>
<tr>
<td>Control Room Emergency Makeup Air Cleaning System (CREACS)</td>
<td>13,592 cmh (8,000 cfm)</td>
</tr>
<tr>
<td>Fuel Handling Area Emergency Exhaust System (FHAEES)</td>
<td>8,495 cmh (5,000 cfm)</td>
</tr>
<tr>
<td>Auxiliary Building Controlled Area Emergency Exhaust System (ABCAEES)</td>
<td>5,097 cmh (3,000 cfm)</td>
</tr>
</tbody>
</table>

b. Demonstrate for each of the ESF Systems that an in-place test of the charcoal adsorber shows a penetration and system bypass < 0.05% when tested in accordance with NRC RG 1.52, Revision 4, and ASME N511-2007 at the system flow rate specified below ± 10%:

<table>
<thead>
<tr>
<th>ESF Ventilation System</th>
<th>Flowrate</th>
</tr>
</thead>
<tbody>
<tr>
<td>CREACS</td>
<td>13,592 cmh (8,000 cfm)</td>
</tr>
<tr>
<td>FHAEES</td>
<td>8,495 cmh (5,000 cfm)</td>
</tr>
<tr>
<td>ABCAEES</td>
<td>5,097 cmh (3,000 cfm)</td>
</tr>
</tbody>
</table>

c. Demonstrate for each of the ESF Systems that a laboratory test of a sample of the charcoal adsorber, when obtained as described in NRC RG 1.52, Revision 4, shows the methyl iodide penetration less than the value specified below when tested in accordance with ASTM D3803-1989 at a temperature of 30°C (86°F) and the relative humidity specified below:

<table>
<thead>
<tr>
<th>ESF Ventilation System</th>
<th>Penetration</th>
<th>RH</th>
</tr>
</thead>
<tbody>
<tr>
<td>CREACS</td>
<td>0.5%</td>
<td>70%</td>
</tr>
<tr>
<td>FHAEES</td>
<td>0.5%</td>
<td>70%</td>
</tr>
<tr>
<td>ABCAEES</td>
<td>0.5%</td>
<td>70%</td>
</tr>
</tbody>
</table>
5.5 Programs and Manuals

5.5.11 Ventilation Filter Testing Program (VFTP) (continued)

----------------------------------------REVIEWER'S NOTE----------------------------------------

The use of any standard other than ASTM D3803-1989 to test the charcoal sample may result in an overestimation of the capability of the charcoal to adsorb radiiodine. As a result, the ability of the charcoal filters to perform in a manner consistent with the licensing basis for the facility is indeterminate.

ASTM D 3803-1989 is a more stringent testing standard because it does not differentiate between used and new charcoal, it has a longer equilibration period performed at a temperature of 30°C (86°F) and a relative humidity (RH) of 95% (or 70% RH with humidity control), and it has more stringent tolerances that improve repeatability of the test.

Allowable Penetration = (100% - Methyl Iodide Efficiency * for Charcoal Credited in Licensee's Accident Analysis) / Safety Factor

When ASTM D3803-1989 is used with 30°C (86°F) and 95% RH (or 70% RH with humidity control) is used, the staff will accept the following:

Safety factor ≥ 2 for systems with or without humidity control.

Humidity control can be provided by heaters or an NRC-approved analysis that demonstrates that the air entering the charcoal will be maintained less than or equal to 70 percent RH under worst case design basis conditions.

If the system has a face velocity greater than 110 percent of 0.203 m/s (40 ft/min), the face velocity should be specified.

*This value should be the efficiency that was incorporated in the licensee's accident analysis which was reviewed and approved by the staff in a safety evaluation.

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5.5 Programs and Manuals

5.5.11 Ventilation Filter Testing Program (VFTP) (continued)

d. Demonstrate for each of the ESF Systems that the pressure drop across the combined HEPA filters, the prefilters, and the charcoal adsorbers is less than the value specified below when tested in accordance with NRC RG 1.52, Revision 4, and ASME N511-2007 at the system flowrate specified below ± 10%:

<table>
<thead>
<tr>
<th>ESF Ventilation System</th>
<th>Delta P</th>
<th>Flowrate</th>
</tr>
</thead>
<tbody>
<tr>
<td>CREACS</td>
<td>203.2 mm wg (8 in. wg)</td>
<td>13,592 cmh (8,000 cfm)</td>
</tr>
<tr>
<td>FHAEES</td>
<td>203.2 mm wg (8 in. wg)</td>
<td>8,495 cmh (5,000 cfm)</td>
</tr>
<tr>
<td>ABCAEESES</td>
<td>203.2 mm wg (8 in. wg)</td>
<td>5,097 cmh (3,000 cfm)</td>
</tr>
</tbody>
</table>

e. Demonstrate that the heaters for each of the ESF Systems dissipate the following specified value ± 10% when tested in accordance with ASME N511-2007:

<table>
<thead>
<tr>
<th>ESF Ventilation System</th>
<th>Wattage</th>
</tr>
</thead>
<tbody>
<tr>
<td>CREACS</td>
<td>26,000 W</td>
</tr>
<tr>
<td>FHAEES</td>
<td>22,000 W</td>
</tr>
<tr>
<td>ABCAEESES</td>
<td>9,000 W</td>
</tr>
</tbody>
</table>

The provisions of SR 3.0.2 and SR 3.0.3 are applicable to the VFTP test frequencies.
5.5 Programs and Manuals

5.5.12 Explosive Gas and Storage Tank Radioactivity Monitoring Program

This program provides controls for potentially explosive gas mixtures contained in the Gaseous Waste Management System, the quantity of radioactivity released from a charcoal guard bed of Gaseous Waste Management System, and the quantity of radioactivity contained in unprotected outdoor liquid storage tanks.

The gaseous radioactivity quantities shall be determined following the methodology in [Branch Technical Position (BTP) ETSB 11-5, “Postulated Radioactive Release due to Waste Gas System Leak or Failure”]. The liquid radwaste quantities shall be determined in accordance with [Standard Review Plan, Section 15.7.3, “Postulated Radioactive Release due to Tank Failures”].

The program shall include:

a. The limits for concentrations of hydrogen and oxygen in the Gaseous Waste Management System and a surveillance program to ensure the limits are maintained. Such limits shall be appropriate to the system's design criteria (i.e., whether or not the system is designed to withstand a hydrogen explosion),

b. A surveillance program to ensure that the quantity of radioactivity released from a charcoal guard bed of Gaseous Waste Management System is less than the amount that would result in a whole body exposure of $\geq 5 \text{ mSv (0.5 rem)}$ to any individual in an unrestricted area, in the event of an uncontrolled release of the tanks' contents, and

c. A surveillance program to ensure that the quantity of radioactivity contained in all outdoor liquid radwaste tanks that are not surrounded by liners, dikes, or walls, capable of holding the tanks' contents and that do not have tank overflows and surrounding area drains connected to the Liquid Waste Management System is less than the amount that would result in concentrations less than the limits of 10 CFR 20, Appendix B, Table 2, Column 2, at the nearest potable water supply and the nearest surface water supply in an unrestricted area, in the event of an uncontrolled release of the tanks' contents.

The provisions of SR 3.0.2 and SR 3.0.3 are applicable to the Explosive Gas and Storage Tank Radioactivity Monitoring Program surveillance frequencies.
5.5 Programs and Manuals

5.5.13 Diesel Fuel Oil Testing Program

A diesel fuel oil testing program to implement required testing of both new fuel oil and stored fuel oil shall be established. The program shall include sampling and testing requirements, and acceptance criteria, all in accordance with applicable ASTM Standards. The purpose of the program is to establish the following:

a. Acceptability of new fuel oil for use prior to addition to storage tanks by determining that the fuel oil has:
   1. an API gravity or an absolute specific gravity within limits,
   2. a flash point and kinematic viscosity within limits for ASTM 2D fuel oil, and
   3. a clear and bright appearance with proper color or a water and sediment content within limits.

b. Within 31 days following addition of the new fuel oil to storage tanks, verify that the properties of the new fuel oil, other than those addressed in a., above, are within limits for ASTM 2D fuel oil, and

c. Total particulate concentration of the stored fuel oil in storage tanks and day tanks is \( \leq 10 \) mg/l when tested every 31 days.

The provisions of SR 3.0.2 and SR 3.0.3 are applicable to the Diesel Fuel Oil Testing Program test frequencies.

5.5.14 Technical Specifications (TS) Bases Control Program

This program provides a means for processing changes to the Bases of these TS.

a. Changes to the Bases of the TS shall be made under appropriate administrative controls and reviews.

b. Licensees may make changes to Bases without prior NRC approval provided the changes do not require either of the following:
   1. a change in the TS incorporated in the license or
   2. a change to the updated Final Safety Analysis Report (FSAR) or Bases that requires NRC approval pursuant to 10 CFR 50.59.
5.5 Programs and Manuals

5.5.14 Technical Specifications (TS) Bases Control Program (continued)

c. The Bases Control Program shall contain provisions to ensure that the Bases are maintained consistent with the FSAR.

d. Proposed changes that meet the criteria of 5.5.14b above shall be reviewed and approved by the NRC prior to implementation. Changes to the Bases implemented without prior NRC approval shall be provided to the NRC on a frequency consistent with 10 CFR 50.71(e).

5.5.15 Safety Function Determination Program (SFDP)

This program ensures loss of safety function is detected and appropriate action taken. Upon entering LCO 3.0.6, an evaluation shall be made to determine if loss of safety function exists. Additionally, other appropriate limitations and remedial or compensatory actions may be identified to be taken as a result of the support system inoperability and corresponding exception to entering supported system Condition and Required Actions. This program implements the requirements of LCO 3.0.6. The SFDP shall contain the following:

a. Provisions for cross train checks to ensure a loss of the capability to perform the safety function assumed in the accident analysis does not go undetected,

b. Provisions for ensuring the plant is maintained in a safe condition if a loss of function condition exists,

c. Provisions to ensure that an inoperable supported system's Completion Time is not inappropriately extended as a result of multiple support system inoperabilities, and

d. Other appropriate limitations and remedial or compensatory actions.

A loss of safety function exists when, assuming no concurrent single failure, no concurrent loss of offsite power, or no concurrent loss of onsite diesel generator(s), a safety function assumed in the accident analysis cannot be performed. For the purpose of this program, a loss of safety function may exist when a support system is inoperable, and
5.5 Programs and Manuals

5.5.15 Safety Function Determination Program (SFDP) (continued)

a. A required system redundant to the system(s) supported by the inoperable support system is also inoperable, or

b. A required system redundant to the system(s) in turn supported by the inoperable supported system is also inoperable, or

c. A required system redundant to the support system(s) for the supported systems (a) and (b) above is also inoperable.

The SFDP identifies where a loss of safety function exists. If a loss of safety function is determined to exist by this program, the appropriate Conditions and Required Actions of the LCO in which the loss of safety function exists are required to be entered. When a loss of safety function is caused by the inoperability of a single Technical Specification support system, the appropriate Conditions and Required Actions to enter are those of the support system.

5.5.16 Containment Leakage Rate Testing Program

a. A program shall establish the LEAKAGE rate testing of the containment as required by 10 CFR 50.54(o) and 10 CFR 50, Appendix J, Option B. This program shall be in accordance with the guidelines contained in NRC RG 1.163, “Performance- Based Containment Leak-Test Program,” dated September, 1995.

b. The calculated peak containment internal pressure for the design basis loss of coolant accident, \( P_a \) is 3.60 kg/cm\(^2\)G (51.21 psig). The containment design pressure is 60 psig.

c. The maximum allowable containment leakage rate, \( L_a \) at \( P_a \), shall be 0.1% of containment air weight per day.

d. LEAKAGE rate acceptance criteria are:

1. containment leakage rate acceptance criterion is \( \leq 1.0 \) \( L_a \). During the first unit startup following testing in accordance with this program, the leakage rate acceptance criteria are \( < 0.60 \) \( L_a \) for the Type B and C tests and \( \leq 0.75 \) \( L_a \) for Type A tests.

2. air lock testing acceptance criteria are:

   i. overall air lock leakage rate is \( \leq 0.05 \) \( L_a \) when tested at \( \geq P_a \).

   ii. for each door, leakage rate is \( \leq 0.01 \) \( L_a \) when pressurized to \( \geq 10 \) psig.
5.5 Programs and Manuals

5.5.16 Containment Leakage Rate Testing Program (continued)

e. The provisions of SR 3.0.3 are applicable to the Containment Leakage Rate Testing Program.

f. Nothing in these Technical Specifications shall be construed to modify the testing Frequencies required by 10 CFR 50, Appendix J.

5.5.17 Battery Monitoring and Maintenance Program

This Program provides controls for battery restoration and maintenance. The program shall be in accordance with IEEE Standard (Std) 450-2002, “IEEE Recommended Practice for Maintenance, Testing, and Replacement of Vented Lead-Acid Batteries for Stationary Applications,” as endorsed by NRC RG 1.129, Revision 2 (RG), with RG exceptions and program provisions as identified below:

a. The program allows the following RG 1.129, Revision 2 exceptions:

1. battery temperature correction may be performed before or after conducting discharge tests.

2. RG 1.129, Regulatory Position 1, Subsection 2, “References,” is not applicable to this program.

3. in lieu of RG 1.129, Regulatory Position 2, Subsection 5.2, “Inspections,” the following shall be used: “Where reference is made to the pilot cell, pilot cell selection shall be based on the lowest voltage cell in the battery.”

4. in NRC RG 1.129, Regulatory Position 3, Subsection 5.4.1, “State of Charge Indicator,” the following statements in paragraph (d) may be omitted: “When it has been recorded that the charging current has stabilized at the charging voltage for three consecutive hourly measurements, the battery is near full charge. These measurements shall be made after the initially high charging current decreases sharply and the battery voltage rises to approach the charger output voltage.”
5.5 Programs and Manuals

5.5.17 Battery Monitoring and Maintenance Program (continued)

5. in lieu of RG 1.129, Regulatory Position 7, Subsection 7.6, "Restoration," the following may be used: "Following the test, record the float voltage of each cell of the string."

b. The program shall include the following provisions:

1. actions to restore battery cells with float voltage < 2.13 V;

2. actions to determine whether the float voltage of the remaining battery cells is ≥ 2.13 V when the float voltage of a battery cell has been found to be < 2.13 V;

3. actions to equalize and test battery cells that had been discovered with electrolyte level below the top of the plates;

4. limits on average electrolyte temperature, battery connection resistance, and battery terminal voltage; and

5. a requirement to obtain specific gravity readings of all cells at each discharge test, consistent with manufacturer recommendations.
5.5 Programs and Manuals

5.5.18 Control Room Envelope (CRE) Habitability Program

A Control Room Envelope (CRE) Habitability Program shall be established and implemented to ensure that CRE habitability is maintained such that, with an OPERABLE Control Room Emergency Makeup Air Cleaning System (CREACS), CRE occupants can control the reactor safely under normal conditions and maintain it in a safe condition following a radiological event, hazardous chemical release, or a smoke challenge. The program shall ensure that adequate radiation protection is provided to permit access and occupancy of the CRE under design basis accident (DBA) conditions without personnel receiving radiation exposures in excess of 50 mSv (5 rem) total effective dose equivalent (TEDE) for the duration of the accident. The program shall include the following elements:

a. The definition of the CRE and the CRE boundary.

b. Requirements for maintaining the CRE boundary in its design condition including configuration control and preventive maintenance.

c. Requirements for (i) determining the unfiltered air inleakage past the CRE boundary into the CRE in accordance with the testing methods and at the Frequencies specified in Sections C.1 and C.2 of NRC RG 1.197, “Demonstrating Control Room Envelope Integrity at Nuclear Power Reactors,” Revision 0, May 2003, and (ii) assessing CRE habitability at the Frequencies specified in Sections C.1 and C.2 of NRC RG 1.197, Revision 0.

d. Measurement, at designated locations, of the CRE pressure relative to all external areas adjacent to the CRE boundary during the pressurization mode of operation by one division of the CREACS, operating at the flow rate required by the VFTP, at a Frequency of 18 months on a STAGGERED TEST BASIS. The results shall be trended and used as part of the 18 month assessment of the CRE boundary.

e. The quantitative limits on unfiltered air inleakage into the CRE. These limits shall be stated in a manner to allow direct comparison to the unfiltered air inleakage measured by the testing described in paragraph c. The unfiltered air inleakage limit for radiological challenges is the inleakage flow rate assumed in the licensing basis analyses of DBA consequences. Unfiltered air inleakage limits for hazardous chemicals must ensure that exposure of CRE occupants to these hazards will be within the assumptions in the licensing basis.

f. The provisions of SR 3.0.2 are applicable to the Frequencies for assessing CRE habitability, determining CRE unfiltered inleakage, and measuring CRE pressure and assessing the CRE boundary as required by paragraphs c and d, respectively.
5.5 Programs and Manuals

5.5.19 Setpoint Control Program

This program shall establish the requirements for ensuring that setpoints for automatic protective devices are initially within and remain within the assumptions of the applicable safety analyses, provides a means for processing changes to instrumentation setpoints, and identifies setpoint methodologies to ensure instrumentation will function as required. The program shall ensure that testing of automatic protective devices related to variables having significant safety functions as delineated by 10 CFR 50.36(c)(1)(ii)(A) verifies that instrumentation will function as required.

a. The program shall list the Functions in the following specifications to which it applies:

1. LCO 3.3.1, “Reactor Protection System (RPS) Instrumentation – Operating”;
2. LCO 3.3.2, “Reactor Protection System (RPS) Instrumentation – Shutdown”;
3. LCO 3.3.3, “Control Element Assembly Calculators (CEACs)”;
4. LCO 3.3.5, “Engineered Safety Features Actuation System (ESFAS) Instrumentation”;
5. LCO 3.3.7, “Emergency Diesel Generator (EDG) – Loss of Voltage Start (LOVS)”;
6. LCO 3.3.8, “Containment Purge Isolation Actuation Signal (CPIAS)”;
7. LCO 3.3.9, “Control Room Emergency Ventilation Actuation Signal (CREVAS)”;
8. LCO 3.3.10, “Fuel Handling Area Emergency Ventilation Actuation Signal (FHEVAS)”;
5.5 Programs and Manuals

5.5.19 Setpoint Control Program (continued)

b. The program shall require the nominal trip setpoint (NTSP), allowable value (AV), as-found tolerance (AFT), and as-left tolerance (ALT) (as applicable) of the Functions described in paragraph a. are calculated using the NRC approved setpoint methodology, as listed below. In addition, the program shall contain the value of the NTSP, AV, AFT, and ALT (as applicable) for each Function described in paragraph a. and shall identify the setpoint methodology used to calculate these values:

- APR1400-F-C-NR-14001-P, Rev. 3, “CPC Setpoint Analysis Methodology for APR1400,” June 2018,
- APR1400-Z-J-NR-14004-P, Rev. 2, “Uncertainty Methodology and Application for Instrumentation,” January 2018, and

[---------------------------------------REVIEWER'S NOTE----------------------------------------
List the NRC safety evaluation report by letter, date, and ADAMS accession number (if available) that approved the setpoint methodologies.
-----------------------------------------------------------------------------------------------------------]

c. The program shall establish methods to ensure that Functions described in paragraph a. will function as required by verifying the as-left and as-found settings are consistent with those established by the setpoint methodology.

[---------------------------------------REVIEWER'S NOTE----------------------------------------
A COL application must list the instrument functions to which the program requirements of paragraph d. will be applied. Paragraph d. shall apply to all Functions in the Reactor Protection System and Engineered Safety Feature Actuation System specifications unless one or more of the following exclusions apply:

1. Manual actuation circuits, automatic actuation logic circuits or to instrument functions that derive input from contacts which have no associated sensor or adjustable device, e.g., limit switches, breaker position switches, manual actuation switches, float switches, proximity detectors, etc. are excluded. In addition, those permissives and interlocks that derive input from a sensor or adjustable device that is tested as part of another TS function are excluded.

[---------------------------------------REVIEWER'S NOTE----------------------------------------]
5.5 Programs and Manuals

5.5.19 Setpoint Control Program (continued)

2. Settings associated with safety relief valves are excluded. The performance of these components is already controlled (i.e., trended with as-left and as-found limits) under the ASME Code for Operation and Maintenance of Nuclear Power Plants testing program.

3. Functions and SRs which test only digital components are normally excluded. There is no expected change in result between SR performances for these components. Where separate as-left and as-found tolerance is established for digital component SRs, the requirements would apply.

d. The program shall identify the Functions described in paragraph a. that are automatic protective devices related to variables having significant safety functions as delineated by 10 CFR 50.36(c)(1)(ii)(A). These Functions shall be demonstrated to be functioning as required by applying the following requirements during CHANNEL CALIBRATIONS and CHANNEL FUNCTIONAL TESTS that verify the NTSP.

1. The as-found value of the instrument channel trip setting shall be compared with the previous as-left value or the specified NTSP.

2. If the as-found value of the instrument channel trip setting differs from the previous as-left value or the specified NTSP by more than the pre-defined test acceptance criteria band (i.e., the specified AFT), then the instrument channel shall be evaluated before declaring the SR met and returning the instrument channel to service. This condition shall be entered in the plant corrective action program.

3. If the as-found value of the instrument channel trip setting is less conservative than the specified AV, then the SR is not met and the instrument channel shall be immediately declared inoperable.

4. The instrument channel setpoint shall be reset to a value that is within the as-left tolerance around the NTSP at the completion of the surveillance test; otherwise, the channel is inoperable (setpoints may be more conservative than the NTSP provided that the as-found and as-left tolerances apply to the actual setpoint used to confirm channel performance).

e. The program shall be specified in [insert the facility FSAR reference or the name of any document incorporated into the facility FSAR by reference].
5.5 Programs and Manuals

5.5.19 Setpoint Control Program (continued)

f. The difference between the instrument channel trip setting as-found value and the previously recorded as-left value for each Technical Specification required automatic protection instrumentation function shall be trended and evaluated to verify that the instrument channel is functioning in accordance with its design basis.

g. The program shall establish a document containing the current value of the specified NTSP, AV, AFT, and ALT for each Technical Specification required automatic protection instrumentation function and references to the calculation documentation. Changes to this document shall be governed by the regulatory requirement of 10 CFR 50.59. In addition, changes to the specified NTSP, AV, AFT, and ALT values shall be governed by the approved setpoint methodology. This document, including any revisions or supplements, shall be provided upon issuance to the NRC.
5.0 ADMINISTRATIVE CONTROLS

5.6 Reporting Requirements

The following reports shall be submitted in accordance with 10 CFR 50.4.

5.6.1 Annual Radiological Environmental Operating Report

[NOTE]

A single submittal may be made for a multiple unit station. The submittal should combine sections common to all units at the station.

The Annual Radiological Environmental Operating Report covering the operation of the unit during the previous calendar year shall be submitted by May 15 of each year. The report shall include summaries, interpretations, and analyses of trends of the results of the Radiological Environmental Monitoring Program for the reporting period. The material provided shall be consistent with the objectives outlined in the Offsite Dose Calculation Manual (ODCM), and in 10 CFR 50, Appendix I, Sections IV.B.2, IV.B.3, and IV.C.

The Annual Radiological Environmental Operating Report shall include the results of analyses of all radiological environmental samples and of all environmental radiation measurements taken during the period pursuant to the locations specified in the table and figures in the ODCM, as well as summarized and tabulated results of these analyses and measurements [in the format of the table in the Radiological Assessment Branch Technical Position, Revision 1, November 1979]. In the event that some individual results are not available for inclusion with the report, the report shall be submitted noting and explaining the reasons for the missing results. The missing data shall be submitted in a supplementary report as soon as possible.

5.6.2 Radiological Effluent Release Report

[NOTE]

A single submittal may be made for a multiple unit station. The submittal shall combine sections common to all units at the station; however, for units with separate radwaste systems, the submittal shall specify the releases of radioactive material from each unit.

The Radiological Effluent Release Report covering the operation of the unit in the previous year shall be submitted prior to May 1 of each year in accordance with 10 CFR 50.36a. The report shall include a summary of the quantities of radioactive liquid and gaseous effluents and solid waste released from the unit. The material provided shall be consistent with the objectives outlined in the ODCM and Process Control Program and in conformance with 10 CFR 50.36a and 10 CFR Part 50, Appendix I, Section IV.B.1.
5.6 Reporting Requirements

5.6.3 CORE OPERATING LIMITS REPORT (COLR)

a. Core operating limits shall be established prior to each reload cycle, or prior to any remaining portion of a reload cycle, and shall be documented in the COLR for the following:

3.1.1, SHUTDOWN MARGIN (SDM);
3.1.3, Moderator Temperature Coefficient (MTC);
3.1.4, Control Element Assembly (CEA) Alignment;
3.1.5, Shutdown Control Element Assembly (CEA) Insertion Limits;
3.1.6, Regulating Control Element Assembly (CEA) Insertion Limits;
3.1.7, Part Strength Control Element Assembly (CEA) Insertion Limits;
3.2.1, Linear Heat Rate (LHR);
3.2.4, Departure From Nucleate Boiling Ratio (DNBR);
3.2.5, AXIAL SHAPE INDEX (ASI); and
3.9.1, Boron Concentration.

b. The analytical methods used to determine the core operating limits shall be those previously reviewed and approved by the NRC, specifically those described in the following documents:


2. “The ROCS and DIT Computer Codes for Nuclear Design,” CENPD-266-P-A, (Methodology for Specifications 3.1.1, SHUTDOWN MARGIN (SDM); 3.1.3, Moderator Temperature Coefficient (MTC); 3.1.6, Regulating CEA Insertion Limits and 3.9.1, Boron Concentration (MODE 6)).

3. “Modified Statistical Combination of Uncertainties,” CEN-356(V)-P-A (Methodology for Specification 3.2.4, DNBR and 3.2.5, AXIAL SHAPE INDEX).
5.6.3 CORE OPERATING LIMITS REPORT (COLR) (continued)


6. “CESEC Digital Simulation of a Combustion Engineering Nuclear Steam Supply System,” CENPD-107, (Methodology for Specifications 3.1.1, SHUTDOWN MARGIN (SDM); 3.1.3, Moderator Temperature Coefficient; 3.1.6, Regulating CEA Insertion Limits; 3.1.7, Part Strength CEA Insertion Limits).

c. The core operating limits shall be determined such that all applicable limits (e.g., fuel thermal mechanical limits, core thermal hydraulic limits, Emergency Core Cooling System (ECCS) limits, nuclear limits such as SDM, transient analysis limits, and accident analysis limits) of the safety analysis are met.

d. The COLR, including any midcycle revisions or supplements, shall be provided upon issuance for each reload cycle to the NRC.
5.6 Reporting Requirements

5.6.4 Reactor Coolant System (RCS) PRESSURE AND TEMPERATURE LIMITS REPORT (PTLR)

a. RCS pressure and temperature limits for heatup, cooldown, low temperature operation, criticality, and hydrostatic testing as well as heatup and cooldown rates shall be established and documented in the PTLR for the following:

3.4.3, “RCS Pressure and Temperature (P/T) Limits”;

3.4.6, “RCS Loops – MODE 4”;

3.4.7, “RCS Loops – MODE 5 (Loops Filled)”;

3.4.10, “Pressurizer Pilot Operated Safety Relief Valves (POSRVs)”;

and 3.4.11, “Low Temperature Overpressure Protection (LTOP) System.”

b. The analytical methods used to determine the RCS pressure and temperature limits shall be those previously reviewed and approved by the NRC, specifically those described in the following documents:

APR1400-Z-M-NR-14008-P, “Pressure-Temperature Limits Methodology for RCS Heatup and Cooldown.”

c. The PTLR shall be provided to the NRC upon issuance for each reactor vessel fluence period and for any revision or supplement thereto.

[---------------------------------------REVIEWER'S NOTE----------------------------------------]

The methodology for the calculation of the P-T limits for NRC approval should include the following provisions:

1. The methodology shall describe how the neutron fluence is calculated (reference new Regulatory Guide when issued).

2. The Reactor Vessel Material Surveillance Program shall comply with Appendix H to 10 CFR 50. The reactor vessel material irradiation surveillance specimen removal schedule shall be provided, along with how the specimen examinations shall be used to update the PTLR curves.

3. Low Temperature Overpressure Protection (LTOP) System lift setting limits for the Pilot Operated Safety Relief Valves (POSRVs), developed using NRC approved methodologies may be included in the PTLR.
5.6.4 Reactor Coolant System (RCS) PRESSURE AND TEMPERATURE LIMITS REPORT (PTLR) (continued)

4. The adjusted reference temperature (ART) for each reactor beltline material shall be calculated, accounting for radiation embrittlement, in accordance with Regulatory Guide 1.99, Revision 2.

5. The limiting ART shall be incorporated into the calculation of the pressure and temperature limit curves in accordance with NUREG-0800 Standard Review Plan 5.3.2, Pressure-Temperature Limits.

6. The minimum temperature requirements of Appendix G to 10 CFR Part 50 shall be incorporated into the pressure and temperature limit curves.

7. COL holders who have removed two or more capsules should compare for each surveillance material the measured increase in reference temperature ($RT_{NTD}$) to the predicted increase in $RT_{NTD}$; where the predicted increase in $RT_{NTD}$ is based on the mean shift in $RT_{NTD}$ plus the two standard deviation value (2σ) specified in Regulatory Guide 1.99, Revision 2. If the measured value exceeds the predicted value (increase in $RT_{NTD} + 2σ$), the COL holder should provide a supplement to the PTLR to demonstrate how the results affect the approved methodology.
5.6 Reporting Requirements

5.6.5 Accident Monitoring Report

When a report is required by Condition B or F of LCO 3.3.11, “Accident Monitoring Instrumentation (AMI),” a report shall be submitted within the following 14 days. The report shall outline the preplanned alternate method of monitoring, the cause of the inoperability, and the plans and schedule for restoring the instrumentation channels of the Function to OPERABLE status.

5.6.6 Tendon Surveillance Report

Any abnormal degradation of the containment structure detected during the tests required by the Pre-stressed Concrete Containment Tendon Surveillance Program shall be reported to the NRC within 30 days. The report shall include a description of the tendon condition, the condition of the concrete (especially at tendon anchorages), the inspection procedures, the tolerances on cracking, and the corrective action taken.

5.6.7 Steam Generator Tube Inspection Report

A report shall be submitted within 180 days after the initial entry into MODE 4 following completion of an inspection performed in accordance with Specification 5.5.9, “Steam Generator (SG) Program.” The report shall include:

a. The scope of inspections performed on each SG,

b. Degradation mechanisms found,

c. Nondestructive examination techniques utilized for each degradation mechanism,

d. Location, orientation (if linear), and measured sizes (if available) of service induced indications,

e. Number of tubes plugged during the inspection outage for each degradation mechanism,

f. The number and percentage of tubes plugged to date, and the effective plugging percentage in each steam generator, and

g. The results of condition monitoring, including the results of tube pulls and in-situ testing.
5.0 ADMINISTRATIVE CONTROLS

5.7 High Radiation Area

As provided in paragraph 20.1601(c) of 10 CFR Part 20, the following controls shall be applied to high radiation areas in place of the controls required by paragraph 20.1601(a) and (b) of 10 CFR Part 20:

5.7.1 High Radiation Areas with Dose Rates Not Exceeding 10 mSv/hour (1.0 rem/hour) at 30 Centimeters (11.8 inches) from the Radiation Source or from any Surface Penetrated by the Radiation.

a. Each entryway to such an area shall be barricaded and conspicuously posted as a high radiation area. Such barricades may be opened as necessary to permit entry or exit of personnel or equipment.

b. Access to, and activities in, each such area shall be controlled by means of Radiation Work Permit (RWP) or equivalent that includes specification of radiation dose rates in the immediate work area(s) and other appropriate radiation protection equipment and measures.

c. Individuals qualified in radiation protection procedures and personnel continuously escorted by such individuals may be exempted from the requirement for an RWP or equivalent while performing their assigned duties provided that they are otherwise following plant radiation protection procedures for entry to, exit from, and work in such areas.

d. Each individual or group entering such an area shall possess:

1. A radiation monitoring device that continuously displays radiation dose rates in the area, or

2. A radiation monitoring device that continuously integrates the radiation dose rates in the area and alarms when the device's dose alarm setpoint is reached, with an appropriate alarm setpoint, or

3. A radiation monitoring device that continuously transmits dose rate and cumulative dose information to a remote receiver monitored by radiation protection personnel responsible for controlling personnel radiation exposure within the area, or

4. A self-reading dosimeter (e.g., pocket ionization chamber or electronic dosimeter) and,
5.7 High Radiation Area

5.7.1 **High Radiation Areas with Dose Rates Not Exceeding 10 mSv/hour (1.0 rem/hour) at 30 Centimeters (11.8 inches) from the Radiation Source or from any Surface Penetrated by the Radiation** (continued)

i. Be under the surveillance, as specified in the RWP or equivalent, while in the area, of an individual qualified in radiation protection procedures, equipped with a radiation monitoring device that continuously displays radiation dose rates in the area; who is responsible for controlling personnel exposure within the area, or

ii. Be under the surveillance, as specified in the RWP or equivalent, while in the area, by means of closed circuit television, of personnel qualified in radiation protection procedures, responsible for controlling personnel radiation exposure in the area, and with the means to communicate with individuals in the area who are covered by such surveillance.

e. Except for individuals qualified in radiation protection procedures, or personnel continuously escorted by such individuals, entry into such areas shall be made only after dose rates in the area have been determined and entry personnel are knowledgeable of them. These continuously escorted personnel will receive a pre-job briefing prior to entry into such areas. This dose rate determination, knowledge, and pre-job briefing does not require documentation prior to initial entry.

5.7.2 **High Radiation Areas with Dose Rates > 10 mSv/hour (1.0 rem/hour) at 30 Centimeters (11.8 inches) from the Radiation Source or from any Surface Penetrated by the Radiation, but < 5 Gy (500 rads/hour) at 1 Meter (3.28 feet) from the Radiation Source or from any Surface Penetrated by the Radiation**

a. Each entryway to such an area shall be conspicuously posted as a high radiation area and shall be provided with a locked or continuously guarded door or gate that prevents unauthorized entry, and, in addition:

1. All such door and gate keys shall be maintained under the administrative control of the shift supervisor, radiation protection manager, or his or her designee.

2. Doors and gates shall remain locked except during periods of personnel or equipment entry or exit.

b. Access to, and activities in, each such area shall be controlled by means of an RWP or equivalent that includes specification of radiation dose rates in the immediate work area(s) and other appropriate radiation protection equipment and measures.
5.7 High Radiation Area

5.7.2 High Radiation Areas with Dose Rates > 10 mSv/hour (1.0 rem/hour) at 30 Centimeters (11.8 inches) from the Radiation Source or from any Surface Penetrated by the Radiation, but < 5 Gy (500 rads/hour) at 1 Meter (3.28 feet) from the Radiation Source or from any Surface Penetrated by the Radiation (continued)

c. Individuals qualified in radiation protection procedures may be exempted from the requirement for an RWP or equivalent while performing radiation surveys in such areas provided that they are otherwise following plant radiation protection procedures for entry to, exit from, and work in such areas.

d. Each individual or group entering such an area shall possess:

1. A radiation monitoring device that continuously integrates the radiation rates in the area and alarms when the device's dose alarm setpoint is reached, with an appropriate alarm setpoint, or

2. A radiation monitoring device that continuously transmits dose rate and cumulative dose information to a remote receiver monitored by radiation protection personnel responsible for controlling personnel radiation exposure within the area with the means to communicate with and control every individual in the area, or

3. A self-reading dosimeter (e.g., pocket ionization chamber or electronic dosimeter) and

   i. Be under the surveillance, as specified in the RWP or equivalent, while in the area, of an individual qualified in radiation protection procedures, equipped with a radiation monitoring device that continuously displays radiation dose rates in the area; who is responsible for controlling personnel exposure within the area, or

   ii. Be under the surveillance, as specified in the RWP or equivalent, while in the area, by means of closed circuit television, of personnel qualified in radiation protection procedures, responsible for controlling personnel radiation exposure in the area, and with the means to communicate with and control every individual in the area.

4. In those cases where options (2) and (3), above, are impractical or determined to be inconsistent with the “As Low As is Reasonably Achievable” principle, a radiation monitoring device that continuously displays radiation dose rates in the area.
5.7 High Radiation Area

5.7.2 High Radiation Areas with Dose Rates > 10 mSv/hour (1.0 rem/hour) at 30 Centimeters (11.8 inches) from the Radiation Source or from any Surface Penetrated by the Radiation, but < 5 Gy (500 rads/hour) at 1 Meter (3.28 feet) from the Radiation Source or from any Surface Penetrated by the Radiation (continued)

e. Except for individuals qualified in radiation protection procedures, or personnel continuously escorted by such individuals, entry into such areas shall be made only after dose rates in the area have been determined and entry personnel are knowledgeable of them. These continuously escorted personnel will receive a pre-job briefing prior to entry into such areas. This dose rate determination, knowledge, and pre-job briefing does not require documentation prior to initial entry.

f. Such individual areas that are within a larger area where no enclosure exists for the purpose of locking and where no enclosure can reasonably be constructed around the individual area need not be controlled by a locked door or gate, nor continuously guarded, but shall be barricaded, conspicuously posted, and a clearly visible flashing light shall be activated at the area as a warning device.
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B 2.0 SAFETY LIMITS (SLs)

B 2.1.1 Reactor Core SLs

BASES

BACKGROUND

GDC 10 (Ref. 1) requires and SLs ensure that specified acceptable fuel design limits (SAFDLs) are not exceeded during steady state operation, normal operational transients, and anticipated operational occurrences (AOOs). This is accomplished by having a departure from nucleate boiling (DNB) design basis, which corresponds to a 95% probability at a 95% confidence level (95/95 DNB criterion) that DNB will not occur, and by having a requirement that fuel centerline temperature stays below the melting temperature.

The restrictions of this SL are to prevent overheating of the fuel and cladding and possible cladding perforation. Overheating of the fuel is prevented by maintaining the steady state peak linear heat rate (LHR) below the level that could cause fuel centerline melting. Overheating of the fuel cladding is prevented by restricting fuel operation to within the nucleate boiling regime, where the heat transfer coefficient is large and cladding surface temperature is slightly above the coolant saturation temperature.

Fuel centerline melting occurs when the local LHR, or power peaking, in a region of the fuel is high enough to cause the fuel centerline temperature to reach the melting point of the fuel. Expansion of the pellet upon centerline melting could cause the pellet to stress the cladding to the point of failure, allowing an uncontrolled release of activity to the reactor coolant.

Operation above the boundary of the nucleate boiling regime could result in excessive cladding temperature because of the onset of DNB and the resultant sharp reduction in the heat transfer coefficient. Inside the steam film, high cladding temperatures are reached and a cladding water (zirconium water) reaction may take place. This chemical reaction results in oxidation of the fuel cladding to a structurally weaker form. This weaker form may lose its integrity, resulting in an uncontrolled release of radioactivity to the reactor coolant.

The Reactor Protection System (RPS), in combination with the LCOs, is designed to prevent any anticipated combination of transient conditions for Reactor Coolant System (RCS) temperature, pressure, and THERMAL POWER level that would result in a violation of the reactor core SLs.
The fuel cladding must not sustain damage as a result of normal operation and AOOs. The reactor core SLs are established to preclude violation of the following fuel design criteria:

a. There must be at least a 95% probability at a 95% confidence level (95/95 DNB criterion) that the hot fuel rod in the core does not experience DNB; and

b. The hot fuel pellet in the core must not experience centerline fuel melting.

The RPS setpoints in LCO 3.3.1 “Reactor Protection System (RPS) Instrumentation – Operating,” in combination with all the LCOs, are designed to prevent any anticipated combination of transient conditions for RCS temperature, pressure, and THERMAL POWER level that would result in a DNB ratio (DNBR) of less than the DNBR limit and preclude the existence of flow instabilities.

Automatic enforcement of these reactor core SLs is provided by the following functions:

a. Pressurizer (PZR) pressure – High trip,

b. PZR pressure – Low trip,

c. Variable overpower – High trip,

d. Steam generator (SG) pressure – Low trip,

e. Local power density (LPD) – High trip,

f. DNBR – Low trip,

g. SG level – Low trip,

h. SG level – High trip,

i. Reactor coolant flow – Low trip, and

j. SG safety valves.
BASES

APPLICABLE SAFETY ANALYSES (continued)

The limitation that the average enthalpy in the hot leg be less than or equal to the enthalpy of saturated liquid also ensures that the $\Delta T$ measured by instrumentation used in the protection system design as a measure of the core power is proportional to core power.

The SL represents a design requirement for establishing the protection system trip setpoints identified previously. LCO 3.2.1, “Linear Heat Rate (LHR),” and LCO 3.2.4, “Departure from Nucleate Boiling Ratio (DNBR),” or the assumed initial conditions of the safety analyses as indicated in Reference 2 provide more restrictive limits to ensure that the SLs are not exceeded.

SAFETY LIMITS

SL 2.1.1.1 ensures that the minimum DNBR is not less than the safety analyses limit and SL 2.1.1.2 ensures that fuel centerline temperature remains below melting.

The minimum value of the DNBR during normal operation and design basis AOOs is limited to 1.29, based on a statistical combination of KCE-1 critical heat flux (CHF) correlation and engineering factor uncertainties, and is established as an SL. Additional factors (e.g., rod bow, spacer grid size and placement) will determine the limiting safety system settings (LSSS) required to ensure that the SL is maintained. SL 2.1.1.2 ensures that fuel centerline temperature remains below the fuel melt temperature of 2,804°C (5,080°F) during normal operating conditions or design AOOs with adjustments for burnup and burnable poison. An adjustment of 32.2°C (58°F) per 10,000 MWD/MTU has been established in Topical Report CEN-386-P-A (Ref. 3) and adjustments for burnable poisons are established based on Topical Report CENPD-275-P (Ref. 4).

APPLICABILITY

SL 2.1.1.1 and SL 2.1.1.2 only apply in MODES 1 and 2 because these are the only MODES in which the reactor is critical. Automatic protection functions are required to be OPERABLE during MODES 1 and 2 to ensure operation within the Reactor Core SLs. The main steam safety valves (MSSVs) or automatic protection actions serve to prevent RCS heatup to the Reactor Core SL conditions or initiate a reactor trip function, which forces the unit into MODE 3. Setpoints for the reactor trip functions are specified in LCO 3.3.1.

In MODES 3, 4, 5 and 6, SLs 2.1.1.1 and 2.1.1.2 are not applicable since the reactor is not generating significant THERMAL POWER.
### BASES

**SAFETY LIMIT VIOLATIONS**

The following violation responses are applicable to the Reactor Core SLs. If SL 2.1.1.1 or SL 2.1.1.2 is violated, the requirement is to go to MODE 3 where these SLs are not applicable.

The allowed Completion Time of 1 hour recognizes the importance of bringing the unit to a MODE of operation where the SL is not applicable and reduces the probability of fuel damage.

### REFERENCES

1. 10 CFR Part 50, Appendix A, GDC 10.

2. FSAR, Section 15.0.


B 2.0 SAFETY LIMITS (SLs)

B 2.1.2 Reactor Coolant System (RCS) Pressure SL

Bases

Background

The SL on RCS pressure protects the integrity of the RCS against overpressurization. In the event of fuel cladding failure, fission products are released into the reactor coolant. The RCS then serves as the primary barrier in preventing the release of fission products into the atmosphere. By establishing an upper limit on RCS pressure, continued RCS integrity is ensured. According to GDC 14, "Reactor Coolant Pressure Boundary," and GDC 15, "Reactor Coolant System Design" (Ref. 1), the reactor coolant pressure boundary (RCPB) design conditions are not to be exceeded during normal operation and anticipated operational occurrences (AOOs). Also, according to GDC 28 (Ref. 1), "Reactivity Limits," reactivity accidents, including rod ejection, do not result in damage to the RCPB greater than limited local yielding.

The design pressure of the RCS is 175.8 kg/cm² (2,500 psia). During normal operation and AOOs, the RCS pressure is kept from exceeding the design pressure by more than 10%, in accordance with ASME Code, Section III (Ref. 2). To ensure system integrity, all RCS components are hydrostatically tested at 125% of design pressure, according to the ASME Code requirements prior to initial operation, when there is no fuel in the core. Following inception of unit operation, RCS components shall be pressure tested in accordance with the requirements of ASME Section XI (Ref. 3), and ASME Operations and Maintenance (OM) Code (Ref. 4). Overpressurization of the RCS could result in a breach of the RCPB. If this occurs in conjunction with a fuel cladding failure, fission products could enter the containment atmosphere, raising concerns relative to limits on radioactive releases specified in 10 CFR 50.34 (Ref. 5).

Applicable Safety Analyses

The pressurizer pilot operating safety relief valves (POSRVs), the main steam safety valves (MSSVs), and the Pressurizer Pressure-High trip have settings established to ensure that the RCS pressure SL will not be exceeded.

The pressurizer POSRVs are sized to prevent system pressure from exceeding the design pressure by more than 10%, in accordance with ASME Code, Section III (Ref. 2).
The transient that establishes the required relief capacity, and hence the valve size requirements and lift settings, is a complete loss of external load with a delayed reactor trip. During the transient, no control actions are assumed except that the safety valves on the secondary plant are assumed to open when the steam pressure reaches the secondary plant safety valve settings.

The Reactor Protection System (RPS) trip setpoints, together with the settings of the MSSVs (LCO 3.7.1, “Main Steam Safety Valves (MSSVs)”) and the POSRVs, provide pressure protection for normal operation and AOOs. The Pressurizer Pressure-High trip setpoint is specifically set to provide protection against overpressurization (Ref. 6). Safety analyses for both the Pressurizer Pressure-High trip and POSRVs are performed using conservative assumptions relative to pressure control devices. More specifically, no credit is taken for operation of the following:

a. Steam Bypass Control System;

b. Pressurizer Level Control System;

c. Pressurizer Pressure Control System;

d. Feedwater Control System.

The maximum transient pressure allowable in the RCS pressure vessel under the ASME Section III, is 110% of design pressure. The maximum transient pressure allowable in the RCS piping, valves, and fittings under ASME Code, Section III, is 110% of design pressure. Therefore, the SL on maximum allowable RCS pressure is 193.3 kg/cm²A (2,750 psia).

SL 2.1.2 applies in MODES 1, 2, 3, 4, and 5 because this SL could be approached or exceeded in these MODES due to overpressurization events. The SL is not applicable in MODE 6 because the reactor vessel head closure bolts are not fully tightened, making it unlikely that the RCS can be pressurized.
The following violation responses are applicable to RCS Pressure SL.

2.2.2.1

If the RCS pressure SL is violated when the reactor is in MODE 1 or 2, the requirement is to restore compliance and be in MODE 3 within 1 hour.

With RCS pressure greater than the value specified in SL 2.1.2 in MODE 1 or 2, the pressure must be reduced to below this value. A pressure greater than the value specified in SL 2.1.2 exceeds 110% of the RCS design pressure and can challenge system integrity.

The allowed Completion Time of 1 hour provides the operator time to complete the necessary actions to reduce RCS pressure by terminating the cause of the pressure increase, removing mass or energy from the RCS, or a combination of these actions, and to establish MODE 3 conditions.

2.2.2.2

If the RCS pressure SL is exceeded in MODE 3, 4, or 5, RCS pressure must be restored to within the SL value within 5 minutes.

Exceeding the RCS Pressure SL in MODE 3, 4, or 5 is potentially more severe than exceeding this SL in MODE 1 or 2 since the reactor vessel temperature can be lower and the vessel material, consequently, less ductile. As such, pressure must be reduced to less than the SL within 5 minutes. This action does not require reducing MODES, since this would require reducing temperature, which would compound the problem by adding thermal gradient stresses to the existing pressure stress.

REFERENCES

1. 10 CFR Part 50, Appendix A, GDC 14, 15, and 28.
2. ASME Section III, Article NB-7000.
3. ASME Section XI, Article IWX-5000.
4. ASME OM Code.
5. 10 CFR 50.34.
6. FSAR, Chapter 15.
LCO Applicability

B 3.0

B 3.0 LIMITING CONDITION FOR OPERATION (LCO) APPLICABILITY

BASES

LCOs

LCO 3.0.1 through LCO 3.0.9 establish the general requirements applicable to all Specifications and apply at all times, unless otherwise stated.

LCO 3.0.1

LCO 3.0.1 establishes the Applicability statement within each individual Specification as the requirement for when the LCO is required to be met (i.e., when the unit is in the MODES or other specified conditions of the Applicability statement of each Specification).

LCO 3.0.2

LCO 3.0.2 establishes that upon discovery of a failure to meet an LCO, the associated ACTIONS shall be met. The Completion Time of each Required Action for an ACTIONS Condition is applicable from the point in time that an ACTIONS Condition is entered. The Required Actions establish those remedial measures that must be taken within specified Completion Times when the requirements of an LCO are not met. This Specification establishes that:

a. Completion of the Required Actions within the specified Completion Times constitutes compliance with a Specification and

b. Completion of the Required Actions is not required when an LCO is met within the specified Completion Time, unless otherwise specified.

There are two basic types of Required Actions. The first type of Required Action specifies a time limit in which the LCO must be met. This time limit is the Completion Time to restore an inoperable system or component to OPERABLE status or to restore variables to within specified limits. If this type of Required Action is not completed within the specified Completion Time, a shutdown may be required to place the unit in a MODE or condition in which the Specification is not applicable. (Whether stated as a Required Action or not, correction of the entered Condition is an action that may always be considered upon entering ACTIONS).

The second type of Required Action specifies the remedial measures that permit continued operation of the unit that is not further restricted by the Completion Time. In this case, compliance with the Required Actions provides an acceptable level of safety for continued operation. Completing the Required Actions is not required when an LCO is met or is no longer applicable, unless otherwise stated in the individual Specifications.
The nature of some Required Actions of some Conditions necessitates that, once the Condition is entered, the Required Actions must be completed even though the associated Conditions no longer exist. The individual LCO ACTIONS specify the Required Actions where this is the case. An example of this is in LCO 3.4.3, “RCS Pressure and Temperature (P/T) Limits.”

The Completion Times of the Required Actions are also applicable when a system or component is removed from service intentionally. The reasons for intentionally relying on the ACTIONS include, but are not limited to, performance of Surveillances, preventive maintenance, corrective maintenance, or investigation of operational problems. Entering ACTIONS for these reasons must be done in a manner that does not compromise safety. Intentional entry into ACTIONS should not be made for operational convenience. Additionally, if intentional entry into ACTIONS would result in redundant equipment being inoperable, alternatives should be used instead. Doing so limits the time both subsystems/trains of a safety function are inoperable and limits the time other conditions exist which result in LCO 3.0.3 being entered. Individual Specifications may specify a time limit for performing a Surveillance when equipment is removed from service or bypassed for testing. In this case, the Completion Times of the Required Actions are applicable when this time limit expires, if the equipment remains removed from service or bypassed.

When a change in MODE or other specified condition is required to comply with Required Actions, the unit may enter a MODE or other specified condition in which another Specification becomes applicable. In this case, the Completion Times of the associated Required Actions would apply from the point in time that the new Specification becomes applicable and the ACTIONS Conditions are entered.
LCO Applicability
B 3.0

LCO 3.0.3 establishes the ACTIONS that must be implemented when an LCO is not met and:

a. An associated Required Action and Completion Time is not met and no other Condition applies; or

b. The condition of the unit is not specifically addressed by the associated ACTIONS. This means that no combination of Conditions stated in the ACTIONS can be made that exactly corresponds to the actual condition of the unit. Sometimes, possible combinations of Conditions are such that entering LCO 3.0.3 is warranted; in such cases, the ACTIONS specifically state a Condition corresponding to such combinations and also that LCO 3.0.3 be entered immediately.

This Specification delineates the time limits for placing the unit in a safe MODE or other specified condition when operation cannot be maintained within the limits for safe operation as defined by the LCO and its ACTIONS. It is not intended to be used as an operational convenience that permits routine voluntary removal of redundant systems or components from service in lieu of other alternatives that would not result in redundant systems or components being inoperable.

Upon entering LCO 3.0.3, 1 hour is allowed to prepare for an orderly shutdown before initiating a change in unit operation. This includes time to permit the operator to coordinate the reduction in electrical generation with the load dispatcher to ensure the stability and availability of the electrical grid. The time limits specified to reach lower MODES of operation permit the shutdown to proceed in a controlled and orderly manner that is well within the specified maximum cooldown rate and within the capabilities of the unit, assuming that only the minimum required equipment is OPERABLE. This reduces thermal stresses on components of the Reactor Coolant System and the potential for a plant upset that could challenge safety systems under conditions to which this Specification applies. The use and interpretation of specified times to complete the ACTIONS of LCO 3.0.3 are consistent with the discussion of Section 1.3, Completion Times. A unit shutdown required in accordance with LCO 3.0.3 may be terminated and LCO 3.0.3 exited if any of the following occurs:

a. The LCO is now met,

b. A Condition exists for which the Required Actions have now been performed, or
c. ACTIONS exist that do not have expired Completion Times. These Completion Times are applicable from the point in time that the Condition is initially entered and not from the time LCO 3.0.3 is exited.

The time limits of LCO 3.0.3 allow 37 hours for the unit to be in MODE 5 when a shutdown is required during MODE 1 operation. If the unit is in a lower MODE of operation when a shutdown is required, the time limit for reaching the next lower MODE applies. If a lower MODE is reached in less time than allowed, however, the total allowable time to reach MODE 5, or other applicable MODE, is not reduced. For example, if MODE 3 is reached in 2 hours, then the time allowed for reaching MODE 5 is the next 35 hours, because the total time for reaching MODE 5 is not reduced from the allowable limit of 37 hours. Therefore, if remedial measures are completed that would permit a return to MODE 1, a penalty is not incurred by having to reach a lower MODE of operation in less than the total time allowed.

In MODES 1, 2, 3, and 4, LCO 3.0.3 provides ACTIONS for Conditions not covered in other Specifications. The requirements of LCO 3.0.3 do not apply in MODES 5 and 6 because the unit is already in the most restrictive Condition required by LCO 3.0.3. The requirements of LCO 3.0.3 do not apply in other specified conditions of the Applicability (unless in MODE 1, 2, 3, or 4) because the ACTIONS of individual Specifications sufficiently define the remedial measures to be taken.

Exceptions to LCO 3.0.3 are provided in instances where requiring a unit shutdown, in accordance with LCO 3.0.3, would not provide appropriate remedial measures for the associated condition of the unit. An example of this is in LCO 3.7.14, “Spent Fuel Pool Water Level.” LCO 3.7.14 has an Applicability of “During movement of irradiated fuel assemblies in the spent fuel pool.” Therefore, this LCO can be applicable in any or all MODES. If the LCO and the Required Actions of LCO 3.7.14 are not met while in MODE 1, 2, or 3, there is no safety benefit to be gained by placing the unit in a shutdown condition.

The Required Action of LCO 3.7.14 of “Suspend movement of irradiated fuel assemblies in spent fuel pool” is the appropriate Required Action to complete in lieu of the actions of LCO 3.0.3. These exceptions are addressed in the individual Specifications.
LCO 3.0.4 establishes limitations on changes in MODES or other specified conditions in the Applicability when an LCO is not met. It precludes placing the unit in a MODE or other specified condition stated in that Applicability (e.g., Applicability desired to be entered) when the following exist:

a. Unit conditions are such that the requirements of the LCO would not be met in the Applicability desired to be entered; and

b. Continued noncompliance with these LCO requirements, if the Applicability were entered, would result in the unit being required to exit the Applicability desired to be entered to comply with the Required Actions.

Compliance with Required Actions that permit continued operation of the unit for an unlimited period of time in a MODE or other specified condition provides an acceptable level of safety for continued operation. This is without regard to the status of the unit before or after the MODE change. Therefore, in such cases, entry into a MODE or other specified condition in the Applicability may be made in accordance with the provisions of the Required Actions. The provisions of this Specification should not be interpreted as endorsing the failure to exercise the good practice of restoring systems or components to OPERABLE status before entering an associated MODE or other specified condition in the Applicability.

The provisions of LCO 3.0.4 shall not prevent changes in MODES or other specified conditions in the Applicability that are required to comply with ACTIONS. In addition, the provisions of LCO 3.0.4 shall not prevent changes in MODES or other specified conditions in the Applicability that result from any shutdown.

Exceptions to LCO 3.0.4 are stated in the individual Specifications. Exceptions may apply to all the ACTIONS or to a specific Required Action of a Specification.

LCO 3.0.4 is only applicable when entering MODE 4 from MODE 5, MODE 3 from MODE 4, MODE 2 from MODE 3, or MODE 1 from MODE 2. Furthermore, LCO 3.0.4 is applicable when entering any other specified condition in the Applicability only while operating in MODE 1, 2, 3, or 4. The requirements of LCO 3.0.4 do not apply in MODES 5 and 6, or in other specified conditions of the Applicability (unless in MODE 1, 2, 3, or 4) because the ACTIONS of individual Specifications sufficiently define the remedial measures to be taken. In some cases these ACTIONS provide a Note that states “While this LCO is not met, entry into a MODE or other specified condition in the Applicability is not permitted, unless required to comply with ACTIONS.” This Note is a requirement
explicitly precluding entry into a MODE or other specified condition of the Applicability.

Surveillances do not have to be performed on the associated inoperable equipment (or on variables outside the specified limits), as permitted by SR 3.0.1. Therefore, changing MODES or other specified conditions while in an ACTIONS Condition, in compliance with LCO 3.0.4 or where an exception to LCO 3.0.4 is stated, is not a violation of SR 3.0.1 or SR 3.0.4 for those Surveillances that do not have to be performed due to the associated inoperable equipment. However, SRs must be met to ensure OPERABILITY prior to declaring the associated equipment OPERABLE (or variable within limits) and restoring compliance with the affected LCO.

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LCO 3.0.5 establishes the allowance for restoring equipment to service under administrative controls when it has been removed from service or declared inoperable to comply with ACTIONS. The sole purpose of this Specification is to provide an exception to LCO 3.0.2 (e.g., to not comply with the applicable Required Action(s)) to allow the performance of required testing to demonstrate either:

a. The OPERABILITY of the equipment being returned to service or

b. The OPERABILITY of other equipment.

The administrative controls ensure the time the equipment is returned to service in conflict with the requirements of the ACTIONS is limited to the time absolutely necessary to perform the required testing to demonstrate OPERABILITY. This Specification does not provide time to perform any other preventive or corrective maintenance.

An example of demonstrating the OPERABILITY of the equipment being returned to service is reopening a containment isolation valve that has been closed to comply with Required Actions and must be reopened to perform the required testing.

An example of demonstrating the OPERABILITY of other equipment is taking an inoperable channel or trip system out of the tripped condition to prevent the trip function from occurring during the performance of required testing on another channel in the other trip system. A similar example of demonstrating the OPERABILITY of other equipment is taking an inoperable channel or trip system out of the tripped condition to permit the logic to function and indicate the appropriate response during the
LCO 3.0.5 (continued)

performance of required testing on another channel in the same trip system.

LCO 3.0.6

LCO 3.0.6 establishes an exception to LCO 3.0.2 for supported systems that have a support system LCO specified in the Technical Specifications (TS). This exception is provided because LCO 3.0.2 would require that the Conditions and Required Actions of the associated inoperable supported system LCO be entered solely due to the inoperability of the support system. This exception is justified because the ACTIONS that are required to ensure the unit is maintained in a safe condition are specified in the support system LCO's Required Actions. These Required Actions may include entering the supported system's Conditions and Required Actions or may specify other Required Actions.

When a support system is inoperable and there is an LCO specified for it in the TS, the supported systems are required to be declared inoperable if determined to be inoperable as a result of the support system inoperability. However, it is not necessary to enter into the supported systems' Conditions and Required Actions unless directed to do so by the support system's Required Actions. The potential confusion and inconsistency of requirements related to the entry into multiple support and supported systems' LCOs' Conditions and Required Actions are eliminated by providing all the ACTIONS that are necessary to ensure the unit is maintained in a safe condition in the support system's Required Actions.

However, there are instances where a support system's Required Action may either direct a supported system to be declared inoperable or direct entry into Conditions and Required Actions for the supported system. This may occur immediately or after some specified delay to perform some other Required Action. Regardless of whether it is immediate or after some delay, when a support system's Required Action directs a supported system to be declared inoperable or directs entry into Conditions and Required Actions for a supported system, the applicable Conditions and Required Actions shall be entered in accordance with LCO 3.0.2.

Specification 5.5.15, "Safety Function Determination Program (SFDP)," ensures a loss of safety function is detected and appropriate actions are taken. Upon entry into LCO 3.0.6, an evaluation shall be made to determine if a loss of safety function exists. Additionally, other limitations, remedial actions, or compensatory actions may be identified as a result of the support system inoperability and corresponding exception to entering
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LCO 3.0.6 (continued)

supported system Conditions and Required Actions. The SFDP implements the requirements of LCO 3.0.6.

The following examples use Figure B 3.0-1 to illustrate loss of safety function conditions that may result when a TS support system is inoperable. In this figure, the fifteen systems that comprise Train A are independent and redundant to the fifteen systems that comprise Train B. To correctly use the figure to illustrate the SFDP provisions for a cross track check, the figure establishes a relationship between support and supported systems as follows: the figure shows System 1 as a support system for System 2 and System 3; System 2 as a support system for System 4 and System 5; System 4 as a support system for System 8 and System 9. Specifically, a loss of safety function may exist when a support system is inoperable, and:

a. A system redundant to system(s) supported by the inoperable support system is also inoperable (EXAMPLE B 3.0.6-1),

b. A system redundant to system(s) in turn supported by the inoperable supported system is also inoperable (EXAMPLE B 3.0.6-2), or

c. A system redundant to support system(s) for the supported systems (a) and (b) above is also inoperable (EXAMPLE B 3.0.6-3).

If this evaluation determines that a loss of safety function exists, the appropriate Conditions and Required Actions of the LCO in which the loss of safety function exists are required to be entered.

For the following examples, see Figure B 3.0-1.

EXAMPLE B 3.0.6-1

If System 2 of Train A is inoperable, and System 5 of Train B is inoperable, a loss of safety function exists in Systems 5, 10 and 11.

EXAMPLE B 3.0.6-2

If System 2 of Train A is inoperable, and System 11 of Train B is inoperable, a loss of safety function exists in System 11.

EXAMPLE B 3.0.6-3

If System 2 of Train A is inoperable, and System 1 of Train B is inoperable, a loss of safety function exists in Systems 2, 4, 5, 8, 9, 10, and 11.
This loss of safety function does not require the assumption of additional single failures or loss of offsite power. Since operations are being restricted in accordance with the ACTIONS of the support system, any resulting temporary loss of redundancy or single failure protection is taken into account. Similarly, the ACTIONS for inoperable offsite circuit(s) and inoperable diesel generator(s) provide the necessary restriction for cross train inoperabilities. This explicit cross train verification for inoperable AC electrical power sources also acknowledges that supported system(s) are not declared inoperable solely as a result of inoperability of a normal or emergency electrical power source (refer to the definition of OPERABILITY).

When a loss of safety function is determined to exist, and the SFDL requires entry into the appropriate Conditions and Required Actions of the LCO in which the loss of safety functions exists, consideration must be given to the specific type of function affected. Where a loss of function is solely due to a single Technical Specification support system (e.g., loss of automatic start due to inoperable instrumentation, or loss of pump suction source due to low tank level) the appropriate LCO is the LCO for the support system. The ACTIONS for a support system LCO adequately address the inoperabilities of that system without reliance on entering its supported system LCO. When the loss of function is the result of multiple support systems, the appropriate LCO is the LCO for the supported system.
Special tests and operations are required at various times over the unit's life to demonstrate performance characteristics, to perform maintenance activities, and to perform special evaluations. Because TS normally preclude these tests and operations, a special test exception (STE) allows specified requirements to be changed or suspended under controlled conditions. An STE is included in applicable sections of the Specifications. Unless otherwise specified, all other TS requirements remain unchanged and in effect as applicable. This will ensure that all appropriate requirements of the MODE or other specified condition not directly associated with or required to be changed or suspended to perform the special test or operation will remain in effect.

The Applicability of an STE LCO represents a condition not necessarily in compliance with the normal requirements of the TS. Compliance with STE LCOs is optional.

A special test may be performed under either the provisions of the appropriate STE LCO or the other applicable TS requirements. If it is desired to perform the special test under the provisions of the STE LCO, the requirements of the STE LCO shall be followed. This includes the SRs specified in the STE LCO.

Some of the STE LCOs require that one or more of the LCOs for normal operation be met. The Applicability, ACTIONS, and SRs of the specified normal LCOs, however, are not required to be met in order to meet the STE LCO when it is in effect. This means that, upon failure to meet a specified normal LCO, the associated ACTIONS of the STE LCO apply, in lieu of the ACTIONS of the normal LCO. Exceptions to the above do exist.

There are instances when the Applicability of the specified normal LCO must be met, where its ACTIONS must be taken, where certain of its Surveillances must be performed, or where all of these requirements must be met concurrently with the requirements of the STE LCO.

Unless the SRs of the specified normal LCOs are suspended or changed by the special test, those SRs that are necessary to meet the specified normal LCOs must be met prior to performing the special test. During the conduct of the special test, those Surveillances need not be performed unless specified by the ACTIONS or SRs of the STE LCO.

ACTIONS for STE LCOs provide appropriate remedial measures upon failure to meet the STE LCO. Upon failure to meet these ACTIONS, suspend the performance of the special test and enter the ACTIONS for all LCOs that are then not met.
Entry into LCO 3.0.3 may possibly be required, but this determination should not be made by considering only the failure to meet the ACTIONS of the STE LCO.

LCO 3.0.8 establishes conditions under which systems are considered to remain capable of performing their intended safety function when associated snubbers are not capable of providing their associated support function(s). This LCO states that the supported system is not considered to be inoperable solely due to one or more snubbers not capable of performing their associated support function(s). This is appropriate because a limited length of time is allowed for maintenance, testing, or repair of one or more snubbers not capable of performing their associated support function(s) and appropriate compensatory measures are specified in the snubber requirements, which are located outside of the TS under licensee control. The snubber requirements do not meet the criteria in 10 CFR 50.36(c)(2)(ii), and, as such, are appropriate for control by the licensee.

If the allowed time expires and the snubber(s) are unable to perform their associated support function(s), the affected supported system’s LCO(s) must be declared not met and the Conditions and Required Actions entered in accordance with LCO 3.0.2.

LCO 3.0.8.a applies when one or more snubbers are not capable of providing their associated support function(s) to a single train or subsystem of a multiple train or subsystem supported system or to a single train or subsystem supported system. LCO 3.0.8.a allows 72 hours to restore the snubber(s) before declaring the supported system inoperable.

The 72 hour Completion Time is reasonable based on the low probability of a seismic event concurrent with an event that would require operation of the supported system occurring while the snubber(s) are not capable of performing their associated support function and due to the availability of the redundant train of the supported system.

LCO 3.0.8.b applies when one or more snubbers are not capable of providing their associated support function(s) to more than one train or subsystem of a multiple train or subsystem supported system. LCO 3.0.8.b allows 12 hours to restore the snubber(s) before declaring the supported system inoperable.
The 12 hour Completion Time is reasonable based on the low probability of a seismic event concurrent with an event that would require operation of the supported system occurring while the snubber(s) are not capable of performing their associated support function.

LCO 3.0.8 requires that risk be assessed and managed. Industry and NRC guidance on the implementation of 10 CFR 50.65(a)(4) (the Maintenance Rule) does not address seismic risk. However, use of LCO 3.0.8 should be considered with respect to other plant maintenance activities, and integrated into the existing Maintenance Rule process to the extent possible so that maintenance on any unaffected train or subsystem is properly controlled, and emergent issues are properly addressed. The risk assessment need not be quantified, but may be a qualitative awareness of the vulnerability of systems and components when one or more snubbers are not able to perform their associated support function.

LCO 3.0.9 establishes conditions under which systems described in the TS are considered to remain OPERABLE when required barriers are not capable of providing their related support function(s).

Barriers are doors, walls, floor plugs, curbs, hatches, installed structures or components, or other devices, not explicitly described in TS, that support the performance of the safety function of systems described in the TS. This LCO states that the supported system is not considered to be inoperable solely due to required barriers not capable of performing their related support function(s) under the described conditions.

LCO 3.0.9 allows 30 days before declaring the supported system(s) inoperable and the LCO(s) associated with the supported system(s) not
LCO  3.0.9 (continued)

met. A maximum time is placed on each use of this allowance to ensure that as required barriers are found or are otherwise made unavailable, they are restored.

However, the allowable duration may be less than the specified maximum time based on the risk assessment.

If the allowed time expires and the barriers are unable to perform their related support function(s), the supported system’s LCO(s) must be declared not met and the Conditions and Required Actions entered in accordance with LCO 3.0.2.

This provision does not apply to barriers which support ventilation systems or to fire barriers. The TS for ventilation systems provide specific Conditions for inoperable barriers. Fire barriers are addressed by other regulatory requirements and associated plant programs. This provision does not apply to barriers which are not required to support system OPERABILITY (see NRC Regulatory Issue Summary 2001-09, "Control of Hazard Barriers," dated April 2, 2001).

The provisions of LCO 3.0.9 are justified because of the low risk associated with required barriers not being capable of performing their related support function. This provision is based on consideration of the following initiating event categories:

- Loss of coolant accidents;
- High energy line breaks;
- Main feedwater line breaks;
- Internal flooding;
- External flooding;
- Turbine missile ejection; and
- Tornado or high wind.

The risk impact of the barriers which cannot perform their related support function(s) must be addressed pursuant to the risk assessment and management provision of the Maintenance Rule, 10 CFR 50.65 (a)(4), and the associated implementation guidance, NRC Regulatory Guide
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LCO 3.0.9 (continued)

(RG) 1.182, "Assessing and Managing Risk Before Maintenance Activities at Nuclear Power Plants."

NRC RG 1.182 endorses the guidance in Section 11 of NUMARC 93-01, "Industry Guideline for Monitoring the Effectiveness of Maintenance at Nuclear Power Plants."

This guidance provides for the consideration of dynamic plant configuration issues, emergent conditions, and other aspects pertinent to plant operation with the barriers unable to perform their related support function(s). These considerations may result in risk management and other compensatory actions being required during the period that barriers are unable to perform their related support function(s).

LCO 3.0.9 may be applied to one or more trains or subsystems of a system supported by barriers that cannot provide their related support function(s), provided that risk is assessed and managed (including consideration of the effects on Large Early Release and from external events). If applied concurrently to more than one train or subsystem of a multiple train or subsystem supported system, the barriers supporting each of these trains or subsystems must provide their related support function(s) for different categories of initiating events. For example, LCO 3.0.9 may be applied for up to 30 days for more than one train of a multiple train supported system if the affected barrier for one train protects against internal flooding and the affected barrier for the other train protects against tornado missiles. In this example, the affected barrier may be the same physical barrier but serve different protection functions for each train.

If during the time that LCO 3.0.9 is being used, the required OPERABLE train or subsystem becomes inoperable, it must be restored to OPERABLE status within 24 hours. Otherwise, the train(s) or subsystem(s) supported by barriers that cannot perform their related support function(s) must be declared inoperable and the associated LCOs declared not met. This 24 hour period provides time to respond to emergent conditions that would otherwise likely lead to entry into LCO 3.0.3 and a rapid plant shutdown, which is not justified given the low probability of an initiating event which would require the barrier(s) not capable of performing their related support function(s). During this 24 hour period, the plant risk associated with the existing conditions is assessed and managed in accordance with 10 CFR 50.65(a)(4).]
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B 3.0 SURVEILLANCE REQUIREMENT (SR) APPLICABILITY

BASES

SRs

SR 3.0.1 through SR 3.0.4 establish the general requirements applicable to all Specifications and apply at all times, unless otherwise stated.

SR 3.0.1

SR 3.0.1 establishes the requirement that SRs must be met during the MODES or other specified conditions in the Applicability for which the requirements of the LCO apply, unless otherwise specified in the individual SRs. This Specification is to ensure that Surveillances are performed to verify the OPERABILITY of systems and components, and that variables are within specified limits. Failure to meet a Surveillance within the specified Frequency, in accordance with SR 3.0.2, constitutes a failure to meet an LCO. Surveillances may be performed by means of any series of sequential, overlapping, or total steps provided the entire Surveillance is performed within the specified Frequency. Additionally, the definitions related to instrument testing (e.g., CHANNEL CALIBRATION) specify that these tests are performed by means of any series of sequential, overlapping, or total steps.

Systems and components are assumed to be OPERABLE when the associated SRs have been met. Nothing in this Specification, however, is to be construed as implying that systems or components are OPERABLE when:

a. The systems or components are known to be inoperable, although still meeting the SRs; or

b. The requirements of the Surveillance(s) are known to be not met between required Surveillance performances.

Surveillances do not have to be performed when the unit is in a MODE or other specified condition for which the requirements of the associated LCO are not applicable, unless otherwise specified. The SRs associated with a special test exception (STE) are only applicable when the STE is used as an allowable exception to the requirements of a Specification.

Surveillances, including Surveillances invoked by Required Actions, do not have to be performed on inoperable equipment because the ACTIONS define the remedial measures that apply. Surveillances have to be met and performed in accordance with SR 3.0.2, prior to returning equipment to OPERABLE status.
Upon completion of maintenance, appropriate post maintenance testing is required to declare equipment OPERABLE. This includes ensuring applicable Surveillances are not failed and their most recent performance is in accordance with SR 3.0.2. Post maintenance testing may not be possible in the current MODE or other specified conditions in the Applicability due to the necessary unit parameters not having been established. In these situations, the equipment may be considered OPERABLE provided testing has been satisfactorily completed to the extent possible and the equipment is not otherwise believed to be incapable of performing its function. This will allow operation to proceed to a MODE or other specified condition where other necessary post maintenance tests can be completed.

Some examples of this process are:

a. Auxiliary feedwater (AFW) pump turbine maintenance during refueling that requires testing at steam pressures > 56.2 kg/cm²G (800 psig). However, if other appropriate testing is satisfactorily completed, the AFW System can be considered OPERABLE. This allows startup and other necessary testing to proceed until the plant reaches the steam pressure required to perform the testing.

b. Safety Injection System (SIS) maintenance during shutdown that requires system functional tests at a specified pressure. Provided other appropriate testing is satisfactorily completed, startup can proceed with SIS considered OPERABLE. This allows operation to reach the specified pressure to complete the necessary post maintenance testing.

SR 3.0.2 establishes the requirements for meeting the specified Frequency for Surveillances and any Required Action with a Completion Time that requires the periodic performance of the Required Action on a “once per...” interval.

SR 3.0.2 permits a 25% extension of the interval specified in the Frequency. This extension facilitates Surveillance scheduling and considers plant operating conditions that may not be suitable for conducting the Surveillance (e.g., transient conditions or other ongoing Surveillance or maintenance activities).
SR 3.0.2 (continued)

The 25% extension does not significantly degrade the reliability that results from performing the Surveillance at its specified Frequency. This is based on the recognition that the most probable result of any particular Surveillance being performed is the verification of conformance with the SRs. The exceptions to SR 3.0.2 are those Surveillances for which the 25% extension of the interval specified in the Frequency does not apply. These exceptions are stated in the individual Specifications. An example of where SR 3.0.2 does not apply is a Surveillance with a Frequency of “in accordance with 10 CFR Part 50, Appendix J, as modified by approved exemptions.” The requirements of regulations take precedence over the TS. The TS cannot in and of themselves extend a test interval specified in the regulations. Therefore, there is a Note in the Frequency stating, “SR 3.0.2 is not applicable.”

As stated in SR 3.0.2, the 25% extension also does not apply to the initial portion of a periodic Completion Time that requires performance on a “once per...” basis. The 25% extension applies to each performance after the initial performance. The initial performance of the Required Action, whether it is a particular Surveillance or some other remedial action, is considered a single action with a single Completion Time. One reason for not allowing the 25% extension to this Completion Time is that such an action usually verifies that no loss of function has occurred by checking the status of redundant or diverse components or accomplishes the function of the inoperable equipment in an alternative manner.

The provisions of SR 3.0.2 are not intended to be used repeatedly merely as an operational convenience to extend Surveillance intervals (other than those consistent with refueling intervals) or periodic Completion Time intervals beyond those specified.

SR 3.0.3

SR 3.0.3 establishes the flexibility to defer declaring affected equipment inoperable or an affected variable outside the specified limits when a Surveillance has not been completed within the specified Frequency. A delay period of up to 24 hours or up to the limit of the specified Frequency, whichever is less, applies from the point in time that it is discovered that the Surveillance has not been performed in accordance with SR 3.0.2, and not at the time that the specified Frequency was not met.

This delay period provides an adequate time to complete Surveillances that have been missed. This delay period permits the completion of a Surveillance before complying with Required Actions or other remedial measures that may preclude completion of the Surveillance.
The basis for this delay period includes consideration of unit conditions, adequate planning, availability of personnel, the time required to perform the Surveillance, the safety significance of the delay in completing the required Surveillance, and the recognition that the most probable result of any particular Surveillance being performed is the verification of conformance with the requirements.

When a Surveillance with a Frequency based not on time intervals, but upon specified unit conditions or operational situations, is discovered not to have been performed when specified, SR 3.0.3 allows the full delay period of 24 hours to perform the Surveillance.

SR 3.0.3 also provides a time limit for completion of Surveillances that become applicable as a consequence of MODE changes imposed by Required Actions.

Failure to comply with specified Frequencies for SRs is expected to be an infrequent occurrence. Use of the delay period established by SR 3.0.3 is a flexibility which is not intended to be used as an operational convenience to extend Surveillance intervals.

If a Surveillance is not completed within the allowed delay period, then the equipment is considered inoperable or the variable is considered outside the specified limits and the Completion Times of the Required Actions for the applicable LCO Conditions begin immediately upon expiration of the delay period. If a Surveillance is failed within the delay period, then the equipment is inoperable, or the variable is outside the specified limits and the Completion Times of the Required Actions for the applicable LCO Conditions begin immediately upon the failure of the Surveillance.

Completion of the Surveillance within the delay period allowed by this Specification, or within the Completion Time of the ACTIONS, restores compliance with SR 3.0.1.

SR 3.0.4 establishes the requirement that all applicable SRs must be met before entry into a MODE or other specified condition in the Applicability.

This Specification ensures that system and component OPERABILITY requirements and variable limits are met before entry into MODES or other specified conditions in the Applicability for which these systems and components ensure safe operation of the unit. The provisions of this Specification should not be interpreted as endorsing the failure to exercise the good practice of restoring systems or components to

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OPERABLE status before entering an associated MODE or other specified condition in the Applicability.

However, in certain circumstances, failing to meet an SR will not result in SR 3.0.4 restricting a MODE change or other specified condition change. When a system, subsystem, train, component, device, or variable is inoperable or outside its specified limits, the associated SR(s) are not required to be performed, per SR 3.0.1, which states that surveillances do not have to be performed on inoperable equipment. When equipment is inoperable, SR 3.0.4 does not apply to the associated SR(s) since the requirement for the SR(s) to be performed is removed. Therefore, failing to perform the Surveillance(s) within the specified Frequency does not result in an SR 3.0.4 restriction to changing MODES or other specified conditions of the Applicability. However, since the LCO is not met in this instance, LCO 3.0.4 will govern any restrictions that may (or may not) apply to MODE or other specified condition changes. SR 3.0.4 does not restrict changing MODES or other specified conditions of the Applicability when a surveillance has not been performed within the specified Frequency, provided the requirement to declare the LCO not met has been delayed in accordance with SR 3.0.3.

The provisions of SR 3.0.4 shall not prevent changes in MODES or other specified conditions in the Applicability that are required to comply with ACTIONS. In addition, the provisions of LCO 3.0.4 shall not prevent changes in MODES or other specified conditions in the Applicability that result from any unit shutdown. The precise requirements for performance of SRs are specified such that exceptions to SR 3.0.4 are not necessary. The specific time frames and conditions necessary for meeting the SRs are specified in the Frequency, in the Surveillance, or both.

This allows performance of Surveillances when the prerequisite condition(s) specified in a Surveillance procedure require entry into the MODE or other specified condition in the Applicability of the associated LCO prior to the performance or completion of a Surveillance. A Surveillance that could not be performed until after entering the LCO Applicability, would have its Frequency specified such that it is not “due” until the specific conditions needed are met. Alternately, the Surveillance may be stated in the form of a Note as not required (to be met or performed) until a particular event, condition, or time has been reached. Further discussion of the specific formats of SRs’ annotation is found in Section 1.4, Frequency.
SR 3.0.4 is only applicable when entering MODE 4 from MODE 5, MODE 3 from MODE 4, MODE 2 from MODE 3, or MODE 1 from MODE 2. Furthermore, SR 3.0.4 is applicable when entering any other specified condition in the Applicability only while operating in MODE 1, 2, 3, or 4. The requirements of SR 3.0.4 do not apply in MODES 5 and 6, or in other specified conditions of the Applicability (unless in MODE 1, 2, 3, or 4) because the ACTIONS of individual Specifications sufficiently define the remedial measures to be taken.
B 3.1 REACTIVITY CONTROL SYSTEMS

B 3.1.1 SHUTDOWN MARGIN (SDM)

BASES

BACKGROUND

The Reactivity Control Systems must be redundant and capable of holding the reactor core subcritical when shutdown under cold conditions, in accordance with General Design Criteria (GDC) 26 (Ref. 1). Maintenance of the SDM ensures that postulated reactivity events will not damage the fuel. SDM requirements provide sufficient reactivity margin to ensure that acceptable fuel design limits will not be exceeded for normal shutdown and anticipated operational occurrences (AOOs). As such, the SDM defines the degree of subcriticality which would be obtained immediately following the insertion of all full strength control element assemblies (CEAs), assuming the single CEA of highest reactivity worth is fully withdrawn.

The system design requires that two independent Reactivity Control Systems be provided, and that one of these systems be capable of maintaining the core subcritical under cold conditions. These requirements are provided by the use of movable CEAs and soluble boric acid in the Reactor Coolant System (RCS). The CEA System provides the SDM during power operation and is capable of making the core subcritical rapidly enough to prevent exceeding acceptable fuel damage limits, assuming that the CEA of highest reactivity worth remains fully withdrawn.

The Soluble Boron System can compensate for fuel depletion during operation and all xenon burnout reactivity changes and maintain the reactor subcritical under cold conditions.

During power operation, SDM control is ensured by operating with the shutdown CEAs fully withdrawn and the regulating CEAs within the limits of LCO 3.1.6, “Regulating Control Element Assembly (CEA) Insertion Limits.” When the unit is in the shutdown and refueling MODES, the SDM requirements are met by means of adjustments to the RCS boron concentration.

APPLICABLE SAFETY ANALYSES

The minimum required SDM is assumed as an initial condition in safety analysis. The safety analysis (Ref. 2) establishes an SDM that ensures specified acceptable fuel design limits are not exceeded for normal operation and AOOs, with the assumption of the highest worth CEA stuck out following a reactor trip.
The acceptance criteria for the SDM are that specified acceptable fuel design limits are maintained. This is done by ensuring that:

a. The reactor can be made subcritical from all operating conditions, transients, and Design Basis Events;

b. The reactivity transients associated with postulated accident conditions are controllable within acceptable limits (departure from nucleate boiling ratio (DNBR), fuel centerline temperature limit for AOOs, and ≤ 963 kJ/kg (230 cal/g) energy deposition for the CEA ejection accident); and

c. The reactor will be maintained sufficiently subcritical to preclude inadvertent criticality in the shutdown condition.

The most limiting accident for the SDM requirements are based on a main steam line break (MSLB) as described in the accident analysis (Ref. 2). The increased steam flow resulting from a pipe break in the Main Steam System causes an increased energy removal from the affected steam generator (SG), and consequently the RCS. This results in a reduction of the reactor coolant temperature. The resultant coolant shrinkage causes a reduction in pressure. In the presence of a negative moderator temperature coefficient, this cooldown causes an increase in core reactivity. As RCS temperature decreases, the severity of an MSLB decreases until the MODE 5 value is reached. The most limiting MSLB, with respect to potential fuel damage before a reactor trip occurs, is a guillotine break of a main steam line inside containment initiated at the end of core life. The positive reactivity addition from the moderator temperature decrease will terminate when the affected SG boils dry, thus terminating RCS heat removal and cooldown. Following the MSLB, a post trip return to power will not occur and THERMAL POWER will not violate the safety limit (SL) requirement of SL 2.1.1.

In addition to the limiting MSLB transient, the SDM requirement for MODES 3, 4 and 5 must also protect against:

a. Inadvertent boron dilution;

b. An uncontrolled CEA withdrawal from a subcritical condition;

c. Startup of an inactive reactor coolant pump (RCP); and

d. CEA ejection.

Each of these is discussed below:
In the boron dilution analysis, the required SDM defines the reactivity difference between an initial subcritical boron concentration and the corresponding critical boron concentration. These values, in conjunction with the configuration of the RCS and the assumed dilution flow rate, directly affect the results of the analysis. This event is most limiting at the beginning of core life when critical boron concentrations are highest.

The withdrawal of CEAs from subcritical conditions adds reactivity to the reactor core, causing both the core power level and heat flux to increase with corresponding increases in reactor coolant temperatures and pressure. The withdrawal of CEAs also produces a time dependent redistribution of core power.

Depending on the system initial conditions and reactivity insertion rate, the uncontrolled CEA withdrawal transient is terminated by either a low DNBTR trip, a high local power density trip, or a Logarithmic Power Level trip. In all cases, power level, RCS pressure, linear heat rate, and the DNBTR do not exceed allowable limits.

The startup of an inactive RCP will not result in a “cold water” criticality, even if the maximum difference in temperature exists between the SG and the core. The maximum positive reactivity addition that can occur due to an inadvertent RCP start is less than the minimum required SDM. An idle RCP cannot, therefore, produce a return to power from the hot standby condition.

The CEA ejection is the accident occurring during conditions allowed by the power dependent insertion limit (PDIL). This event will lead to a rapid positive reactivity addition resulting in a rapid power excursion. A reactor trip on high power is generated to terminate the accident. The CEA ejection can result in limited fuel damage with the subsequent release of radioactive material, so it may be necessary to evaluate the radiological consequence in accordance with the 10 CFR 50.34. SDM is an important parameter in this analysis.

In the analysis of the CEA ejection event, SDM alone cannot prevent reactor criticality following a CEA ejection. The $k_{N-1}$ requirement ensures the reactor remains subcritical and, therefore, satisfies the radially averaged enthalpy acceptance criterion considering power redistribution effects, where $k_{N-1}$ is the k effective ($k_{eff}$) calculated by considering the actual CEA configuration and assuming that the fully or partially inserted full strength CEA of highest worth is fully withdrawn.
The function of $k_{N-1}$ is to maintain sufficient subcriticality to preclude inadvertent criticality following ejection of a single CEA. $k_{N-1}$ is a measure of the core's reactivity, considering a single malfunction resulting in the highest worth inserted CEA being ejected.

$k_{N-1}$ requirements vary with the amount of positive reactivity that would be introduced assuming the CEA with the highest inserted worth ejects from the core. The $k_{N-1}$ requirement ensures that a CEA ejection event while shutdown will not result in criticality.

The requirement prohibiting criticality due to shutdown group CEA movement is associated with the assumptions used in the analysis of uncontrolled CEA withdrawal from subcritical conditions. Due to the high differential reactivity worth of the shutdown CEA groups, the analysis assumes that the initial shutdown reactivity is such that the reactor will remain subcritical in the event of unexpected or uncontrolled shutdown group withdrawal.

SDM satisfies Criterion 2 of 10 CFR 50.36(c)(2)(ii).

LCO

The MSLB (Ref. 2) and the boron dilution event (Ref. 3) are the most limiting analyses that establish the SDM value of the LCO. For MSLB, if the LCO is violated, there is a potential to exceed the DNBR limit and to exceed 10 CFR 50.34 limits (Ref. 4). For the boron dilution event, if the LCO is violated, then the minimum required time assumed for operator action to terminate dilution may no longer be applicable.

SDM, $k_{N-1}$, and criticality due to shutdown CEA withdrawal are core physics design conditions that can be ensured through CEA positioning (regulating and shutdown CEAs) and through the soluble boron concentration.

APPLICABILITY

In MODES 3, 4 and 5, the SDM requirements are applicable to provide sufficient negative reactivity to meet the assumptions of the safety analyses discussed above.

In MODES 1 and 2, SDM is ensured by complying with LCO 3.1.5, “Shutdown Control Element Assembly (CEA) Insertion Limits,” and LCO 3.1.6 “Regulating Control Element Assembly (CEA) Insertion Limits.”

In MODE 6, the shutdown reactivity requirements are given in LCO 3.9.1, “Boron Concentration.”
BASES

ACTIONS

A.1

If the SDM requirements are not met, boration must be initiated promptly. A Completion Time of 15 minutes is adequate for an operator to correctly align and start the required systems and components. It is assumed that boration will be continued until the SDM requirements are met.

In the determination of the required combination of boration flow rate and boron concentration, there is no unique requirement that must be satisfied. Since it is imperative to raise the boron concentration of the RCS as soon as possible, the boron concentration should be a highly concentrated solution, such as the boric acid in the in-containment refueling water storage tank (IRWST). The operator should borate with the best source available for the plant conditions.

In determining the boration flow rate, the time core life must be considered. For instance, the most difficult time in core life to increase the RCS boron concentration is at the beginning of cycle, when the boron concentration may approach or exceed 2000 ppm. Assuming that a value of 1% $\Delta k/k$ must be recovered and a boration flow rate of 564 L/min (149 gpm), it is possible to increase the boron concentration of the RCS by 100 ppm in approximately 35 minutes. If a boron worth of 10 pcm/ppm is assumed, this combination of parameters will increase the SDM by 1% $\Delta k/k$. These boration parameters of 564 L/min (149 gpm) and 100 ppm represent typical values and are provided for the purpose of offering a specific example.

B.1 and B.2

If the $k_{n-1}$ requirements are not met or reactor criticality is achievable by Shutdown Group CEA movement, boration must be initiated promptly and CEA position varied to restore $k_{n-1}$ within limit or to ensure criticality due to Shutdown Group CEA movement is not achievable. A Completion Time of 15 minutes is adequate for an operator to correctly align and start the required systems and components and vary CEA position. It is assumed that boration will be continued and CEA position varied to return $k_{n-1}$ to within limit or prevent reactor criticality due to Shutdown Group CEA movement. CEA movement is only required if the specific limit exceeded can be improved by taking this action.
SDM is verified by performing a reactivity balance calculation, considering the listed reactivity effects:

a. RCS boron concentration;
b. CEA positions;
c. RCS cold leg temperature;
d. Fuel burnup based on gross thermal energy generation;
e. Xenon concentration;
f. Samarium concentration; and
g. Isothermal temperature coefficient (ITC).

Using the ITC accounts for Doppler reactivity in this calculation because the reactor is subcritical and the fuel temperature will be changing at the same rate as that of the RCS.

The Frequency of 24 hours is based on the generally slow change in required boron concentration, and it also allows sufficient time for the operator to collect the required data, which includes performing a boron concentration analysis, and complete the calculation.

REFERENCES

2. FSAR, Subsection 15.1.5.
3. FSAR, Subsection 15.4.6.
4. 10 CFR 50.34.
B 3.1 REACTIVITY CONTROL SYSTEMS

B 3.1.2 Reactivity Balance

BASES

BACKGROUND

According to General Design Criteria (GDC) 26, 28, and 29 (Ref. 1), reactivity shall be controllable, such that subcriticality is maintained under cold conditions and acceptable fuel design limits are not exceeded during normal operation and anticipated operational occurrences. Therefore, reactivity balance is used as a measure of the predicted versus measured core reactivity during power operation. The periodic confirmation of core reactivity is necessary to ensure that design basis accidents (DBA) and transient safety analyses remain valid. A large reactivity difference could be the result of unanticipated changes in fuel, control element assembly (CEA) worth, or operation at conditions not consistent with those assumed in the predictions of core reactivity, and could potentially result in a loss of SDM or violation of acceptable fuel design limits. Comparing predicted versus measured core reactivity validates the nuclear methods used in the safety analysis and supports the SDM demonstrations (LCO 3.1.1, "SHUTDOWN MARGIN (SDM)") in ensuring the reactor can be brought safely to cold, subcritical conditions.

When the reactor core is critical or in normal power operation, a reactivity balance exists and the net reactivity is zero. A comparison of predicted and measured reactivity is convenient under such a balance since parameters are being maintained relatively stable under steady state power conditions. The positive reactivity inherent in the core design is balanced by the negative reactivity of the control components, thermal feedback, neutron leakage, and materials in the core that absorb neutrons, such as burnable absorbers producing zero net reactivity. Excess reactivity can be inferred from the critical boron curve, which provides an indication of the soluble boron concentration in the Reactor Coolant System (RCS) versus cycle burnup. Periodic measurement of the RCS boron concentration for comparison with the predicted value with other variables fixed (such as CEA height, temperature, pressure, and power) provides a convenient method of ensuring that core reactivity is within design expectations and that the calculational models used to generate the safety analysis are adequate.
In order to achieve the required fuel cycle energy output, the uranium enrichment in the new fuel loading and in the fuel remaining from the previous cycle, provides excess positive reactivity beyond that required to sustain steady-state operation throughout the cycle. When the reactor is critical at RTP and moderator temperature, the excess positive reactivity is compensated by burnable absorbers (if any), CEAs, whatever neutron poisons (mainly xenon and samarium) are present in the fuel, and the RCS boron concentration.

When the core is producing THERMAL POWER, the fuel is being depleted and excess reactivity is decreasing. As the fuel depletes, the RCS boron concentration is reduced to decrease negative reactivity and maintain constant THERMAL POWER. The critical boron curve is based on steady state operation at RTP. Therefore, deviations from the predicted boron letdown curve may indicate deficiencies in the design analysis, deficiencies in the calculational models, or abnormal core conditions, and must be evaluated.

Accurate prediction of core reactivity is either an explicit or implicit assumption in the accident analysis evaluations. Every accident evaluation (Ref. 2) is, therefore, dependent upon accurate evaluation of core reactivity. In particular, SDM, and reactivity transients such as CEA withdrawal accidents or CEA ejection accidents, are very sensitive to accurate prediction of core reactivity. These accident analysis evaluations rely on computer codes that have been qualified against available test data, operating plant data, and analytical benchmarks. Monitoring reactivity balance additionally ensures that the nuclear methods provide an accurate representation of the core reactivity.

Design calculations and safety analyses are performed for each fuel cycle for the purpose of predetermining reactivity behavior and the RCS boron concentration requirements for reactivity control during fuel depletion. The comparison between measured and predicted initial core reactivity provides a normalization for calculational models used to predict core reactivity. If the measured and predicted RCS boron concentrations for identical core conditions at beginning of cycle (BOC) do not agree, then the assumptions used in the reload cycle design analysis or the calculational models used to predict soluble boron requirements may not be accurate.
APPLICABLE SAFETY ANALYSES (continued)

If reasonable agreement between measured and predicted core reactivity exists at BOC, then the prediction may be normalized to the measured boron concentration. Thereafter, any significant deviations in the measured boron concentration from the predicted critical boron curve that develop during fuel depletion may be an indication that the calculational model is not adequate for core burnups beyond BOC, or that an unexpected change in core conditions has occurred.

The normalization of predicted RCS boron concentration to the measured value is typically performed after reaching RTP following startup from a refueling outage, with the CEAs in their normal positions for power operation. The normalization is performed at BOC conditions, so that core reactivity relative to predicted values can be continually monitored and evaluated as core conditions change during the cycle.

The reactivity balance satisfies Criterion 2 of 10 CFR 50.36(c)(2)(ii).

LCO

The reactivity balance limit is established to ensure plant operation is maintained within the assumptions of the safety analyses. Large differences between actual and predicted core reactivity may indicate that the assumptions of the DBA and transient analyses are no longer valid or that the uncertainties in the nuclear design methodology are larger than expected. A limit on the reactivity balance of ± 1% $\Delta k/k$ has been established, based on engineering judgment. A 1% deviation in reactivity from the predicted value is larger than expected for normal operation and should therefore be evaluated.

When measured core reactivity is within ± 1% $\Delta k/k$ of the predicted value at steady state thermal conditions, the core is considered to be operating within acceptable design limits. Since deviations from the limit are normally detected by comparing predicted and measured steady state RCS critical boron concentrations, the difference between measured and predicted values would be approximately 100 ppm (depending on the boron worth) before the limit is reached. These values are well within the uncertainty limits for analysis of boron concentration samples, so that spurious violations of the limit due to uncertainty in measuring the RCS boron concentration are unlikely.
BASES

APPLICABILITY  The limits on core reactivity must be maintained during MODES 1 and 2 because a reactivity balance must exist when the reactor is critical or producing THERMAL POWER. As the fuel depletes, core conditions are changing, and confirmation of the reactivity balance ensures the core is operating as designed. This Specification does not apply in MODES 3, 4, and 5 because the reactor is shut down and the reactivity balance is not changing.

In MODE 6, fuel loading results in a continually changing core reactivity. Boron concentration requirements (LCO 3.9.1, “Boron Concentration”) ensure that fuel movements are performed within the bounds of the safety analysis. An SDM demonstration is required during the first startup following operations that could have altered core reactivity (e.g., fuel movement, CEA replacement, shuffling).

ACTIONS  A.1 and A.2

Should an anomaly develop between measured and predicted core reactivity, an evaluation of the core design and safety analysis must be performed. Core conditions are evaluated to determine their consistency with input to design calculations. Measured core and process parameters are evaluated to determine that they are within the bounds of the safety analysis, and safety analysis calculational models are reviewed to verify that they are adequate for representation of the core conditions. The required Completion Time of 7 days is based on the low probability of a DBA occurring during this period and allows sufficient time to assess the physical condition of the reactor and complete the evaluation of the core design and safety analysis.

Following evaluations of the core design and safety analysis, the cause of the reactivity anomaly may be resolved. If the cause of the reactivity anomaly is a mismatch in core conditions at the time of RCS boron concentration sampling, then a recalculation of the RCS boron concentration requirements may be performed to demonstrate that core reactivity is behaving as expected. If an unexpected physical change in the condition of the core has occurred, it must be evaluated and corrected, if possible. If the cause of the reactivity anomaly is in the calculation technique, then the calculational models must be revised to provide more accurate predictions.

If any of these results are demonstrated and it is concluded that the reactor core is acceptable for continued operation, then the boron letdown curve may be renormalized and power operation may continue. If operational restrictions or additional SRs are necessary to ensure the reactor core is acceptable for continued operation, then they must be defined.
The required Completion Time of 7 days is adequate for preparing whatever operating restrictions or Surveillances that can be required to allow continued reactor operation.

**B.1**

If the core reactivity cannot be restored to within the ± 1% $\Delta k/k$ of predicted values, the plant must be brought to a MODE in which the LCO does not apply. To achieve this status, the plant must be brought to at least MODE 3 within 6 hours. If the SDM for MODE 3 is not met, then boration required by SR 3.1.1.1 would occur. The allowed Completion Time is reasonable, based on operating experience, for reaching MODE 3 from full power conditions in an orderly manner and without challenging plant systems.

**SURVEILLANCE REQUIREMENTS**

**SR 3.1.2.1**

Core reactivity is verified by periodic comparisons of measured and predicted RCS boron concentrations. The comparison is made considering that other core conditions are fixed or stable including CEA position, moderator temperature, fuel temperature, fuel depletion, xenon concentration, and samarium concentration. The Surveillance is performed prior to entering MODE 1 as an initial check on core conditions and design calculations at BOC. The SR is modified by two Notes. The first Note indicates that the normalization of predicted core reactivity to the measured value must take place within the first 60 effective full power days (EFPD) after each fuel loading. This allows sufficient time for core conditions to reach steady state, but prevents operation for a large fraction of the fuel cycle without establishing a benchmark for the design calculations.

The required subsequent Frequency of 31 EFPD, following the initial 60 EFPD after entering MODE 1, is acceptable based on the slow rate of core changes due to fuel depletion and the presence of other indicators for prompt indication of an anomaly.

A Note, "Only required after 60 EFPD," is added to the Frequency column to allow this. Another Note indicates that the performance of SR 3.1.2.1 is not required prior to entering MODE 2. This Note is required to allow a MODE 2 entry to verify core reactivity because Applicability is for MODES 1 and 2.
REFERENCES

1. 10 CFR Part 50, Appendix A, GDC 26, 28, and 29.
2. FSAR, Chapter 15.
B 3.1 REACTIVITY CONTROL SYSTEMS

B 3.1.3 Moderator Temperature Coefficient (MTC)

BASES

BACKGROUND

According to General Design Criteria (GDC) 11 (Ref. 1), the reactor core and its interaction with the Reactor Coolant System (RCS) must be designed for inherently stable power operation, even in the possible event of an accident. In particular, the net reactivity feedback in the system must compensate for any unintended reactivity increases.

The MTC relates a change in core reactivity to a change in reactor coolant temperature. A positive MTC means that reactivity increases with increasing moderator temperature; conversely, a negative MTC means that reactivity decreases with increasing moderator temperature. The reactor is designed to operate with a negative MTC throughout the possible range of fuel cycle operation. Therefore, a coolant temperature increase will cause a reactivity decrease, so that the coolant temperature tends to return toward its initial value. Reactivity increases that cause a coolant temperature increase will thus be self-limiting and stable power operation will result.

MTC values are predicted at selected burnups during the safety evaluation analysis and are confirmed to be acceptable by measurements. Both initial and reload cores are designed so that the beginning of cycle (BOC) MTC is less positive than that allowed by the LCO. The actual value of the MTC is dependent on core characteristics such as fuel loading and reactor coolant soluble boron concentration. The core design may require additional distributed absorbers (burnable poison assemblies) to yield an MTC at the BOC within the range analyzed in the plant accident analysis. The end of cycle (EOC) MTC is also limited by the requirements of the accident analysis. Fuel cycles that are designed to achieve high burnups or that have changes to other characteristics are evaluated to ensure that the MTC does not exceed the EOC limit.

APPLICABLE SAFETY ANALYSES

The acceptance criteria for the specified MTC are:

a. The MTC values must remain within the bounds of those used in the accident analysis (Ref. 2); and

b. The MTC must be such that inherently stable power operations result during normal operation and during accidents, such as overheating and overcooling events.
Reference 2 contains analyses of accidents that result in both overheating and overcooling of the reactor core. MTC is one of the controlling parameters for core reactivity in these accidents. Both the most positive value and most negative value of the MTC are important to safety and both values must be bounded. Values used in the analyses consider worst case conditions, such as very large soluble boron concentrations, to ensure the accident results are bounding (Ref. 2).

Accidents that cause core overheating, either by decreased heat removal or increased power production, must be evaluated for results when the MTC is positive. Reactivity accidents that cause increased power production include the control element assembly (CEA) withdrawal transient from either zero or full THERMAL POWER. The limiting overheating event relative to plant response is based on the maximum difference between core power and steam generator heat removal during a transient. The most limiting event with respect to a positive MTC is a CEA withdrawal accident from zero power, also referred to as a startup accident (Ref. 2).

Accidents that cause core overcooling must be evaluated for results when the MTC is most negative. The event that produces the most rapid cooldown of the RCS, and is therefore the most limiting event with respect to the negative MTC, is a main steam line break (MSLB). Following the reactor trip for the postulated EOC MSLB, the large moderator temperature reduction combined with the large negative MTC may produce reactivity increases that are as much as the shutdown reactivity. When this occurs, a substantial fraction of core power is produced with all CEAs inserted, except the most reactive one, which is assumed withdrawn. Even if the reactivity increase produces slightly subcritical conditions, a large fraction of core power may be produced through the effects of subcritical neutron multiplication.

MTC values are bounded in reload safety evaluations assuming steady state conditions at BOC and EOC. A middle of cycle (MOC) measurement is conducted at conditions when the RCS boron concentration reaches approximately 300 ppm. The measured value may be extrapolated to project the EOC value, in order to confirm reload design predictions.

The MTC satisfies Criterion 2 of 10 CFR 50.36(c)(2)(ii).
LCO 3.1.3 requires the MTC to be within the positive and negative limits specified in the COLR to ensure the core operates within the assumptions of the accident analysis. During the reload core safety evaluation, the MTC is analyzed to determine that its values remain within the bounds of the original accident analysis during operation. The positive MTC limit ensures that core overheating accidents will not violate the accident analysis assumptions. The negative MTC limit for EOC specified in the COLR ensures that core overcooling accidents will not violate the accident analysis assumptions.

The MTC limit specified in the LCO is the maximum positive MTC value approved in the plant's licensing basis and ensures that the reactor operates with a negative MTC over the largest possible range of fuel cycle operation. The cycle-specific MTC limit specified in the COLR must be equal to or less positive than the MTC limit specified in the LCO.

MTC is a core physics parameter determined by the fuel and fuel cycle design and cannot be easily controlled once the core design is fixed. Limited control of MTC can be achieved by adjusting CEA position and boron concentration. During operation the LCO can be ensured through measurement and adjustments to CEA position and boron concentration. The surveillance checks at BOC and MOC on an MTC provide confirmation that the MTC is behaving as anticipated, so that the acceptance criteria are met.

In MODE 1, the limits on the MTC must be maintained to ensure that any accident initiated from THERMAL POWER operation will not violate the design assumptions of the accident analysis.

In MODE 2, the limits must also be maintained to ensure startup and subcritical accidents, such as the uncontrolled CEA assembly or group withdrawal, will not violate the assumptions of the accident analysis. In MODES 3, 4, 5, and 6, this LCO is not applicable since no design basis accidents (DBAs) using the MTC as an analysis assumption are initiated from these MODES. However, the variation of the MTC with temperature in MODES 3, 4, and 5, for DBAs initiated in MODES 1 and 2, is accounted for in the subject accident analysis. The variation of the MTC with temperature assumed in the safety analysis is accepted as valid once the BOC and MOC measurements are used for normalization.
MTC is a function of the fuel and fuel cycle designs and cannot be controlled directly once the designs have been implemented in the core. If MTC exceeds its limits, the reactor must be placed in MODE 3. This eliminates the potential for violation of the accident analysis bounds. The associated Completion Time of 6 hours is reasonable, considering the probability of an accident occurring during the time period that would require an MTC value within the LCO limits, and the time for reaching MODE 3 from full power conditions in an orderly manner and without challenging plant systems.

The SRs for measurement of the MTC at the beginning and middle of each fuel cycle provide for confirmation of the limiting MTC values. The MTC changes smoothly from most positive (least negative) to most negative value during fuel cycle operation as the RCS boron concentration is reduced to compensate for fuel depletion.

The requirement for measurement prior to operation > 5% RTP satisfies the confirmatory check on the most positive (least negative) MTC value.

The requirement for measurement, within 7 effective full power days (EFPD) after reaching 40 EFPD and 2/3 of core burnup, satisfies the confirmatory check of the most negative MTC value. The measurement is performed at any THERMAL POWER so that the projected EOC MTC can be evaluated before the reactor actually reaches the EOC condition. MTC values can be extrapolated and compensated to permit direct comparison to the specified MTC limits.

SR 3.1.3.2 is modified by a Note that indicates, if extrapolated MTC is more negative than the EOC limit specified in the COLR, the Surveillance may be repeated, and that shutdown must occur prior to exceeding the minimum allowable boron concentration at which MTC is projected to exceed the lower limit. An engineering evaluation is performed if the extrapolated value of MTC exceeds the Specification limits.

REFERENCES
1. 10 CFR Part 50, Appendix A, GDC 11.
2. FSAR, Section 15.0.
B 3.1 REACTIVITY CONTROL SYSTEMS

B 3.1.4 Control Element Assembly (CEA) Alignment

BASES

BACKGROUND  The OPERABILITY (i.e., trippability) of the shutdown and regulating CEAs is an initial assumption in all safety analyses, which assume CEA insertion upon reactor trip. Maximum CEA misalignment is an initial assumption in the safety analyses which directly affects core power distributions and assumptions of available SDM.

The applicable criteria for these reactivity and power distribution design requirements are 10 CFR Part 50, Appendix A, Generic Design Criteria (GDC) 10 and 26 (Ref. 1), and 10 CFR 50.46 (Ref. 2).

Mechanical or electrical failures can cause a CEA to become inoperable or to become misaligned from its group. CEA inoperability or misalignment can cause increased power peaking, due to the asymmetric reactivity distribution and a reduction in the total available CEA worth for reactor shutdown. Therefore, CEA alignment and OPERABILITY are related to core operation in design power peaking limits and the core design requirement of a minimum SDM.

Limits on CEA alignment and OPERABILITY have been established, and all CEA positions are monitored and controlled during power operation to ensure that the power distribution and reactivity limits defined by the design power peaking and SDM limits are preserved.

CEAs are moved by their control element drive mechanisms (CEDMs). Each CEDM moves its CEA one step (approximately 1.91 cm (3/4 in)) at a time, but at varying rates (steps per minute) depending on the signal output from the Digital Rod Control System (DRCS).

The CEAs are arranged into groups that are radially symmetric. Therefore, movement of the CEAs does not introduce radial asymmetries in the core power distribution. The shutdown and regulating CEAs provide the required reactivity worth for immediate reactor shutdown upon a reactor trip. The regulating CEAs also provide reactivity (power level) control during normal operation and transients. Their movement can be automatically controlled by the Reactor Regulating System (RRS).

Part strength CEAs are not credited in the safety analyses for shutting down the reactor, as are the regulating and shutdown groups. The part strength CEAs are used for ASI control.
The axial positions of shutdown and regulating CEAs are indicated by two separate and independent systems. These are the pulse counting CEA position indication and the Reed Switch CEA Position Indication System.

The pulse counting CEA position indication counts the commands sent to the CEA gripper coils from the DRCS that moves the CEAs. There is one step counter for each group of CEAs. Individual CEAs in a group all receive the same signal to move and should, therefore, all be at the same position indicated by the group step counter for that group. The pulse counting CEA position indication is considered highly precise (± one step or 1.91 cm (±3/4 in)). If a CEA does not move one step for each command signal, the step counter will still count the command and incorrectly reflect the position of the CEA.

The Reed Switch CEA Position Indication System provides a highly accurate indication of actual CEA position, but at a lower precision than the step counters. This system is based on inductive analog signals from a series of reed switches spaced along a tube with a center to center distance of 3.81 cm (1.5 in), which is two steps. To increase the reliability of the system, there are redundant reed switches at each position.

CEA misalignment accidents are analyzed in the safety analysis (Ref. 3). The accident analysis defines CEA misoperation as any event, with the exception of sequential group withdrawals, that could result from a single malfunction in the Reactivity Control Systems. For example, CEA misalignment can be caused by a malfunction of the CEDM, DRCS, or by operator error. A stuck CEA can be caused by mechanical jamming of the CEA fingers or the gripper. Inadvertent withdrawal of a single CEA can be caused by opening of the electrical circuit of the CEDM holding coil for a full strength or part strength CEA. A dropped CEA subgroup could be caused by an electrical failure in the CEA coil power programmers.

The acceptance criteria for addressing CEA inoperability or misalignment are that:

a. There shall be no violations of either:
   1. specified acceptable fuel design limits (SAFDL) or
   2. Reactor Coolant System (RCS) pressure boundary integrity, and
b. The core must remain subcritical after accident transients.
Three types of misalignment are distinguished. During movement of a group, one CEA may stop moving while the other CEAs in the group continue. This condition can cause excessive power peaking. The second type of misalignment occurs if one CEA fails to insert upon a reactor trip and remains stuck fully withdrawn. This condition requires an evaluation to determine that sufficient reactivity worth is held in the remaining CEAs to meet the SDM requirement with the maximum worth CEA stuck fully withdrawn. If a CEA is stuck in the fully withdrawn position, its worth is added to the SDM requirement, since the safety analysis does not take two stuck CEAs into account. The third type of misalignment occurs when one CEA drops partially or fully into the reactor core. This event causes an initial power reduction followed by a return towards the original power due to positive reactivity feedback from the negative moderator temperature coefficient. Increased peaking during the power increase can result in excessive local linear heat rates (LHRs).

Two types of analyses are performed in regard to static CEA misalignment (Ref. 3). With CEA banks at their insertion limits, one type of analysis considers the case when any one CEA is inserted fully into the core. The second type of analysis considers the case of a single CEA withdrawn [ ] inches from a bank inserted to its insertion limit. Satisfying limits on departure from nucleate boiling ratio (DNBR) in both of these cases bounds the situation when a CEA is misaligned from its group by 16.8 cm (6.6 in).

Another type of misalignment occurs if one CEA fails to insert upon a reactor trip and remains stuck fully withdrawn. This condition is assumed in the evaluation to determine that the required SDM is met with the maximum worth CEA also fully withdrawn (Ref. 3).

The effect of any misoperated CEA on the core power distribution will be assessed by the CEA calculators, and an appropriately augmented power distribution penalty factor will be supplied as input to the core protection calculators (CPCs). As the reactor core responds to the reactivity changes caused by the misoperated CEA and the ensuing reactor coolant and Doppler feedback effects, the CPCs will initiate a low DNBR or high local power density trip signal if SAFDLs are approached.
Since the CEA drop incidents result in the most rapid approach to SAFDLs caused by a CEA misoperation, the accident analysis analyzed a single full strength CEA drop, a single part strength CEA drop, and a single part strength CEA subgroup drop. The most rapid approach to the DNBR SAFDL can be caused by either a single full strength drop or a part strength CEA subgroup drop depending upon initial conditions. The most rapid approach to the fuel centerline melt SAFDL is caused by a single part strength CEA drop.

In the case of the full strength CEA drop, a prompt decrease in core average power and a distortion in radial power are initially produced, which when conservatively coupled result in local power and heat flux increases, and a decrease in DNBR. For plant operation within the DNBR and local power density (LPD) LCOs, DNBR and LPD trips can normally be avoided on a dropped CEA.

For a part strength CEA subgroup drop, a distortion in power distribution, and a decrease in core power are produced. As the dropped part strength CEA subgroup is detected, an appropriate power distribution penalty factor is supplied to the CPCs, and a reactor trip signal on low DNBR is generated. For the part strength CEA drop, both core average power and three dimensional peak to average power density increase promptly. As the dropped part strength CEA is detected, core power and an appropriately augmented power distribution penalty factor are supplied to the CPCs.

CEA alignment limits and OPERABILITY requirements satisfy Criteria 2 and 3 of 10 CFR 50.36(c)(2)(ii).

The limits on shutdown and regulating CEA alignments ensure that the assumptions in the safety analysis will remain valid. The requirements on CEA OPERABILITY ensure that upon reactor trip, the CEAs will be available and will be inserted to provide enough negative reactivity to shut down the reactor. The CEA OPERABILITY requirements (i.e., trippability) are separate from the alignment requirements that ensure the CEA banks maintain the correct power distribution and CEA alignment. The CEA OPERABILITY requirement is satisfied provided the CEA will fully insert in the required CEA drop time assumed in the safety analysis. CEA control malfunctions that result in the inability to move a CEA (e.g., CEA lift coil failures), but that do not impact trippability, do not result in CEA inoperability.
The requirement on OPERABILITY to maintain the CEA alignment to within 16.8 cm (6.6 in) between the highest and lowest CEAs in a subgroup is conservative. The minimum misalignment assumed in safety analysis is 48.3 cm (19 in), and in some cases, a total misalignment from fully withdrawn to fully inserted is assumed.

Failure to meet the requirements of this LCO can produce unacceptable power peaking factors and LHRs, or unacceptable SDMs, all of which can constitute initial conditions inconsistent with the safety analysis.

The requirements on CEA OPERABILITY and alignment are applicable in MODES 1 and 2 because these are the only MODES in which neutron (or fission) power is generated and the OPERABILITY (i.e., trippability) and alignment of CEAs have the potential to affect the safety of the plant. In MODES 3, 4, 5, and 6, the alignment limits do not apply because the CEAs are bottomed, and the reactor is shut down and not producing fission power. In the shutdown MODES, the OPERABILITY of the shutdown and regulating CEAs has the potential to affect the required SDM, but this effect can be compensated for by an increase in the boron concentration of the RCS. See LCO 3.1.1, “SHUTDOWN MARGIN (SDM)” for SDM in MODES 3, 4, and 5, and LCO 3.9.1 “Boron Concentration,” for boron concentration requirements during refueling.

A.1 and A.2

If one or more CEAs (regulating, shutdown or part strength) are misaligned by > 16.8 cm (6.6 in) and ≤ 48.3 cm (19 in), or one CEA misaligned by > 48.3 cm (19 in), continued operation in MODES 1 and 2 may continue provided, within 1 hour, the power is reduced in accordance with Figure 3.1.4-1, and within 2 hours CEA alignment is restored.

Regulating and part strength CEA alignment can be restored by either aligning the misaligned CEA(s) to within 16.8 cm (6.6 in) of its group or aligning the misaligned CEA's group to within 16.8 cm (6.6 in) of the misaligned CEA. Shutdown CEA alignment can be restored by aligning the misaligned CEA(s) to within 16.8 cm (6.6 in) of its group.

Xenon redistribution in the core starts to occur as soon as a CEA becomes misaligned. Reducing THERMAL POWER in accordance with Figure 3.1.4-1 (in the accompanying LCO) ensures acceptable power distributions are maintained (Ref. 3). For small misalignments (< 48.3 cm (19 in)) of the CEAs, there is:
BASES

ACTIONS (continued)

a. A small effect on the time dependent long term power distributions relative to those used in generating LCOs and limiting safety system settings (LSSS) setpoints,

b. A negligible effect on the available SDM, and

c. A small effect on the ejected CEA worth used in the accident analysis.

With a large CEA misalignment (≥ 48.3 cm (19 in)), however, this misalignment would cause distortion of the core power distribution. This distortion can, in turn, have a significant effect on the time dependent, long term power distributions relative to those used in generating LCOs and limiting safety system settings (LSSS) setpoints. The effect on the available SDM and the ejected CEA worth used in the accident analysis remain small.

Therefore, this condition is limited to the single CEA misalignment, while still allowing 2 hours for recovery.

In both cases, a 2 hour time period is sufficient to:

a. Identify the cause of a misaligned CEA,

b. Take appropriate corrective action to realign the CEAs, and

c. Minimize the effects of xenon redistribution.

The CEA must be returned to OPERABLE status within 2 hours or transition to MODE 3.

B.1

If a Required Action or associated Completion Time of Condition A is not met, one or more full strength CEAs are inoperable, or two or more CEAs are misaligned by > 48.3 cm (19 in), the unit is required to be brought to MODE 3. By being brought to MODE 3, the unit is brought outside its MODE of applicability. When a Required Action cannot be completed within the required Completion Time, a controlled shutdown should be commenced. The allowed Completion Time of 6 hours is reasonable, based on operating experience, for reaching MODE 3 from full power conditions in an orderly manner and without challenging plant systems.
Continued operation is not allowed in the case of more than one CEA(s) misaligned from any other CEA in its group by > 48.3 cm (19 in), or with one or more full strength CEAs inoperable. This is because these cases are indicative of a loss of SDM and power distribution, and a loss of safety function, respectively.

**SURVEILLANCE REQUIREMENTS**

**SR 3.1.4.1**

Verification that individual CEA positions are within 16.8 cm (6.6 in) (indicated reed switch positions) of all other CEAs in the group at a 12 hour Frequency allows the operator to detect a CEA that is beginning to deviate from its expected position. The 12 hour Frequency takes into account other CEA position information that is continuously available to the operator in the main control room (MCR), so that during actual CEA motion, deviations can immediately be detected.

**SR 3.1.4.2**

OPERABILITY of at least two CEA position indicator channels is required to determine CEA positions, and thereby ensure compliance with the CEA alignment and insertion limits. The CEA full in and full out limits provide an additional independent means for determining the CEA positions when the CEAs are at either their fully inserted or fully withdrawn positions.

The 12 hour Frequency takes into account other CEA position information that is continuously available to the operator in the MCR, so that during actual CEA motion, deviations can immediately be detected.

**SR 3.1.4.3**

Verifying each full strength CEA is trippable would require that each CEA be tripped. In MODES 1 and 2 tripping each full strength CEA would result in radial or axial power tilts, or oscillations. Therefore individual full strength CEAs are exercised to provide increased confidence that all full strength CEAs continue to be trippable, even if they are not regularly tripped. A movement of 12.7 cm (5 in) is adequate to demonstrate motion without exceeding the alignment limit when only one full strength CEA is being moved. The 92 day Frequency takes into consideration other information available to the operator in the MCR and other Surveillances being performed more frequently, which add to the determination of OPERABILITY of the CEAs (Ref. 3). Between required performances of SR 3.1.4.3, if a CEA(s) is discovered to be immovable but remains trippable, the CEA is considered to be OPERABLE. At any time, if a CEA(s) is immovable, a
determination of the trippability (OPERABILITY) of that CEA(s) must be made and appropriate action taken.

SR 3.1.4.4

Performance of a CHANNEL FUNCTIONAL TEST of each reed switch position transmitter (RSPT) channel ensures the channel is OPERABLE and capable of indicating CEA position over the entire length of the CEA’s travel. Since this test must be performed when the reactor is shut down, an 18 month Frequency to be coincident with refueling outage was selected. Operating experience has shown that these components usually pass this Surveillance when performed at a Frequency of once every 18 months. Therefore, the Frequency was concluded to be acceptable from a reliability standpoint.

SR 3.1.4.5

Verification of full strength CEA drop times determines that the maximum CEA drop time permitted is consistent with the assumed drop time used in the safety analysis (Ref. 3). Measuring drop times prior to reactor criticality, after reactor vessel head removal, ensures the reactor internals and CEDM will not interfere with CEA motion or drop time and that no degradation in these systems has occurred that would adversely affect CEA motion or drop time. Individual CEAs whose drop times are greater than safety analysis assumptions are not OPERABLE. This SR is performed prior to criticality due to the plant conditions needed to perform the SR and the potential for an unplanned plant transient if the Surveillance were performed with the reactor at power.

The 4 second CEA drop time is the maximum time allowed for a fully withdrawn individual full strength CEA to reach its 90% insertion position (Refs. 4 and 5) when electrical power is interrupted to the CEA drive mechanism with RCS $T_{cold} \geq 286.7^\circ C (548^\circ F)$ and all reactor coolant pumps operating. The CEA drop time of full strength CEAs shall also be demonstrated through measurement prior to reactor criticality for specifically affected individual CEAs following any maintenance on or modification to the CEA Drive System which could affect the drop time of those specific CEAs.

REFERENCES

2. 10 CFR 50.46.
REFERENCES (continued)

3. FSAR, Section 15.4.

4. FSAR, Section 4.2.

5. FSAR, Section 15.0.
B 3.1 REACTIVITY CONTROL SYSTEMS

B 3.1.5 Shutdown Control Element Assembly (CEA) Insertion Limits

BASES

BACKGROUND

The insertion limits of the shutdown CEAs are initial assumptions in all safety analyses that assume CEA insertion upon reactor trip. The insertion limits directly affect core power distributions and assumptions of available SDM, ejected CEA worth, and initial reactivity insertion rate.

The applicable criteria for these reactivity and power distribution design requirements are 10 CFR Part 50, Appendix A, GDC 10 and 26 (Ref. 1), and 10 CFR 50.46 (Ref. 2). Limits on shutdown CEA insertion have been established, and all CEA positions are monitored and controlled during power operation to ensure that the reactivity limits, ejected CEA worth, and SDM limits are preserved.

The shutdown CEAs are arranged into groups that are radially symmetric. Therefore, movement of the shutdown CEAs does not introduce radial asymmetries in the core power distribution. The shutdown and regulating CEAs provide the required reactivity worth for immediate reactor shutdown upon a reactor trip.

The design calculations are performed with the assumption that the shutdown CEAs are withdrawn prior to the regulating CEAs. The shutdown CEAs can be fully withdrawn without the core going critical. This provides available negative reactivity for SDM in the event of boration errors. The shutdown CEAs are controlled manually or automatically by the main control room (MCR) operator. During normal unit operation, the shutdown CEAs are fully withdrawn. The shutdown CEAs must be completely withdrawn from the core prior to withdrawing regulating CEAs during an approach to criticality. The shutdown CEAs are then left in this position until the reactor is shut down. They affect core power, burnup distribution, and add negative reactivity to shut down the reactor upon receipt of a reactor trip signal.

APPLICABLE SAFETY ANALYSES

Accident analysis assumes that the shutdown CEAs are fully withdrawn any time the reactor is critical. This ensures that:

a. The minimum SDM is maintained; and

b. The potential effects of a CEA ejection accident are limited to acceptable limits.
CEAs are considered fully withdrawn at 367.7 cm (144.75 in) since this position places them outside the active region of the core.

On a reactor trip, all CEAs (shutdown and regulating CEAs), except the most reactive CEA, are assumed to insert into the core. The shutdown and regulating CEAs shall be at their insertion limits and available to insert the maximum amount of negative reactivity on a reactor trip signal. The regulating CEAs may be partially inserted in the core as allowed by LCO 3.1.6, “Regulating Control Element Assembly (CEA) Insertion Limits.” The shutdown CEA insertion limit is established to ensure that a sufficient amount of negative reactivity is available to shut down the reactor and maintain the required SDM (see LCO 3.1.1, “SHUTDOWN MARGIN (SDM)” following a reactor trip from full power. The combination of regulating CEAs and shutdown CEAs (less the most reactive CEA, which is assumed to be fully withdrawn) is sufficient to take the reactor from full power conditions at rated temperature to zero power and maintain the required SDM at rated no load temperature (Ref. 3). The shutdown CEA insertion limit also limits the reactivity worth of an ejected shutdown CEA.

The acceptance criteria for addressing shutdown CEA as well as regulating CEA insertion limits and inoperability or misalignment are that:

a. There be no violation of:
   1. specified acceptable fuel design limits (SAFDL); or
   2. Reactor Coolant System (RCS) pressure boundary integrity; and
b. The core remains subcritical after accident transients.

The shutdown CEA insertion limits satisfy Criterion 2 of 10 CFR 50.36(c)(2)(ii).

The shutdown CEAs must be within their insertion limits any time the reactor is critical or approaching criticality. This ensures that a sufficient amount of negative reactivity is available to shut down the reactor and maintain the required SDM following a reactor trip.
Bases

Applicability

The shutdown CEAs must be within their insertion limits with the reactor in MODES 1 and 2. The Applicability in MODE 2 begins any time any regulating CEA is not fully inserted. This ensures that a sufficient amount of negative reactivity is available to shut down the reactor and maintain the required SDM following a reactor trip.

In MODE 3, 4, 5, and 6, the shutdown CEAs are fully inserted in the core and contribute to the SDM. Refer to LCO 3.1.1 “SHUTDOWN MARGIN (SDM)” for SDM requirements in MODES 3, 4, and 5. LCO 3.9.1, “Boron Concentration,” ensures adequate SDM in MODE 6.

LCO 3.1.5 has been modified by a Note indicating the LCO requirement is suspended during SR 3.1.4.3, which verifies the freedom of the CEAs to move, and requires the shutdown CEAs to move below the LCO limits, which would normally violate the LCO.

Actions

A.1

Prior to entering this Condition, the shutdown CEAs were fully withdrawn. If a shutdown CEA is then inserted into the core, its potential negative reactivity is added to the core as it is inserted. If the CEA(s) is not restored to within limits within 1 hour, then an additional 1 hour is allowed for restoring the CEA(s) to within limits. The 2 hour total Completion Time allows the operator adequate time to adjust the CEA(s) in an orderly manner and is consistent with the required Completion Times in LCO 3.1.4, “Control Element Assembly (CEA) Alignment.”

B.1

When Required Action A.1 cannot be completed within the required Completion Time, a controlled shutdown should be commenced. The allowed Completion Time of 6 hours is reasonable, based on operating experience, for reaching MODE 3 from full power conditions in an orderly manner and without challenging plant systems.

Surveillance Requirements

SR 3.1.5.1

Verification that the shutdown CEAs are within their insertion limits prior to an approach to criticality ensures that when the reactor is critical, or being taken critical, the shutdown CEAs will be available to shut down the reactor, and the required SDM will be maintained following a reactor trip. This SR and Frequency ensure that the shutdown CEAs are withdrawn before the regulating CEAs are withdrawn during a unit startup.
Since the shutdown CEAs are positioned manually by the MCR operator, verification of shutdown CEA position at a Frequency of 12 hours is adequate to ensure that the shutdown CEAs are within their insertion limits. Also, the Frequency takes into account other information available to the operator in the MCR for the purpose of monitoring the status of the shutdown CEAs.

A second Frequency is provided to ensure that required SDM is maintained by verifying each shutdown CEA is withdrawn ≥ 367.7 cm (144.75 in) within 15 minutes prior to withdrawal of any CEA in regulating groups during an approach to reactor criticality.

REFERENCES

2. 10 CFR 50.46.
3. FSAR, Section 15.0.
B 3.1 REACTIVITY CONTROL SYSTEMS

B 3.1.6 Regulating Control Element Assembly (CEA) Insertion Limits

BASES

BACKGROUND

The insertion limits of the regulating CEAs are initial assumptions in all safety analyses that assume CEA insertion upon reactor trip. The insertion limits directly affect core power distributions, assumptions of available SDM, and initial reactivity insertion rate. The applicable criteria for these reactivity and power distribution design requirements are GDC 10 and 26 (Ref. 1) and 10 CFR 50.46 (Ref. 2).

Limits on regulating CEA insertion have been established, and all CEA positions are monitored and controlled during power operation to ensure that the power distribution and reactivity limits defined by the design power peaking, ejected CEA worth, reactivity insertion rate, and SDM limits are preserved.

The regulating CEA groups operate with a predetermined amount of position overlap, in order to approximate a linear relation between CEA worth and position (integral CEA worth). The regulating CEA groups are withdrawn and operate in a predetermined sequence. The group sequence and overlap limits are specified in the COLR.

The regulating CEAs are used for precise reactivity control of the reactor. The positions of the regulating CEAs are manually controlled. They are capable of adding reactivity very quickly (compared to borating or diluting).

The power density at any point in the core must be limited to maintain specified acceptable fuel design limits, including limits that preserve the criteria specified in 10 CFR 50.46 (Ref. 2). Together, LCO 3.1.6, LCO 3.2.4, “Departure from Nucleate Boiling Ratio (DNBR),” and LCO 3.2.5, “AXIAL SHAPE INDEX (ASI),” provide limits on control component operation and monitored process variables to ensure the core operates within LCO 3.2.1, “Linear Heat Rate (LHR),” LCO 3.2.2, “Planar Radial Peaking Factor (F_{xy}),” and LCO 3.2.4, “Departure from Nucleate Boiling Ratio (DNBR),” limits in the COLR.
Regulating CEA Insertion Limits
B 3.1.6

BASSES

BACKGROUND (continued)

Operation within the LHR limits given in the COLR prevents power peaks that would exceed the loss of coolant accident (LOCA) limits derived by the Emergency Core Cooling Systems analysis. Operation within the $F_{xy}$ and departure from nucleate boiling (DNB) limits given in the COLR prevents DNB during a loss of forced reactor coolant flow accident. In addition to the LHR, $F_{xy}$, and DNBR limits, certain reactivity limits are preserved by regulating CEA insertion limits. The regulating CEA insertion limits also restrict the ejected CEA worth to the values assumed in the safety analyses and preserve the minimum required SDM in MODES 1 and 2.

The establishment of limiting safety system settings (LSSS) and LCOs require that the expected long and short term behavior of the radial peaking factors be determined. The long term behavior relates to the variation of the steady state radial peaking factors with core burnup and is affected by the amount of CEA insertion assumed, the portion of a burnup cycle over which such insertion is assumed, and the expected power level variation throughout the cycle. The short term behavior relates to transient perturbations to the steady state radial peaks, due to radial xenon redistribution. The magnitudes of such perturbations depend upon the expected use of the CEAs during anticipated power reductions and load maneuvering. Analyses are performed, based on the expected MODE of operation of the Nuclear Steam Supply System (NSSS) (base loaded, maneuvering, etc.). From these analyses, CEA insertions are determined and a consistent set of radial peaking factors defined. The long term steady state and short term insertion limits are determined, based upon the assumed MODE of operation used in the analyses, and provide a means of preserving the assumptions on CEA insertions used. The long and short term insertion limits of LCO 3.1.6 are specified for the plant, which has been designed for primarily base loaded operation, but has the ability to accommodate a limited amount of load maneuvering.

The regulating CEA insertion and alignment limits, ASI, and $T_{a}$, are process variables that characterize and control the three dimensional power distribution of the reactor core. Additionally, the regulating bank insertion limits control the reactivity that could be added in the event of a CEA ejection accident, and the shutdown and regulating bank insertion limits ensure the required SDM is maintained.

Operation within the subject LCO limits will prevent fuel cladding failures that would breach the primary fission product barrier and release fission products to the reactor coolant in the event of a LOCA, loss of flow, ejected CEA, or other accident requiring termination by a Reactor Protection System trip function.
The fuel cladding must not sustain damage as a result of normal operation (Condition I) and anticipated operational occurrences (Condition II). The acceptance criteria for the regulating CEA insertion, part strength CEA insertion, ASI, and T₉ LCOs preclude core power distributions from occurring that would violate the following fuel design criteria:

a. During a large break LOCA, the peak cladding temperature must not exceed a limit of 1,204°C (2,200°F) per 10 CFR 50.46 (Ref. 2).

b. During a loss of forced reactor coolant flow accident, there must be at least a 95% probability at a 95% confidence level (the 95/95 DNB criterion) that the hot fuel rod in the core does not experience a DNB condition.

c. During an ejected CEA accident, the fission energy input to the fuel must not exceed 963 kJ/kg (230 cal/g) (Ref. 3).

d. The CEAs must be capable of shutting down the reactor with a minimum required SDM, with the highest worth CEA stuck fully withdrawn, per GDC 26 (Ref. 1).

Regulating CEA position, ASI, and T₉ are process variables that characterize and control the three dimensional power distribution of the reactor core.

Fuel cladding damage does not occur when the core is operated outside these LCOs during normal operation. However, fuel cladding damage could result should an accident occur with simultaneous violation of one or more of these LCOs. Changes in the power distribution can cause increased power peaking and corresponding increased local LHRs.

The SDM requirement is ensured by limiting the regulating and shutdown CEA insertion limits, so that the allowable inserted worth of the CEAs is such that sufficient reactivity is available in the CEAs to shut down the reactor to hot zero power with a reactivity margin that assumes the maximum worth CEA remains fully withdrawn upon trip (Ref. 3).

The most limiting SDM requirements for MODES 1 and 2 conditions at beginning of cycle (BOC) are determined by the requirements of several transients (e.g., loss of flow, seized rotor). However, the most limiting SDM requirements for MODES 1 and 2 at end of cycle (EOC) come from the main steam line break (MSLB). The requirements of the MSLB at EOC for both the full power and no load conditions are significantly larger than those of any other event at that time in cycle and, also, considerably larger than the most limiting requirements at BOC.
Regulating CEA Insertion Limits

Although the most limiting SDM requirements at EOC are much larger than those at BOC, the available SDMs obtained via the scrambling of the CEA banks are also substantially larger due to the much lower boron concentration at EOC. To verify that adequate SDMs are available throughout the cycle to satisfy the changing requirements, calculations are performed at both BOC and EOC. It has been determined that calculations at these two times in cycle are sufficient since the differences between available SDMs and the limiting SDM requirements are the smallest at these times in cycle. The measurement of CEA bank worth performed as part of the Startup Testing Program demonstrates that the core has the expected shutdown capability. Consequently, adherence to LCOs 3.1.5 and 3.1.6 provides assurance that the available SDMs at any time in cycle will exceed the limiting SDM requirements at that time in cycle.

Operation at the insertion or ASI limits can approach the maximum allowable linear heat generation rate or peaking factor, with the allowed T₉₅ present. Operation at the insertion limit can also indicate the maximum ejected CEA worth could be equal to the limiting value in fuel cycles that have sufficiently high ejected CEA worths.

The regulating and shutdown CEA insertion limits ensure that safety analyses assumptions for reactivity insertion rate, SDM, ejected CEA worth, and power distribution peaking factors are preserved (Ref. 3).

The regulating CEA insertion limits satisfy Criterion 2 of 10 CFR 50.36(c)(2)(ii).

The limits on regulating CEA sequence, overlap, and physical insertion, as defined in the COLR, must be maintained because they serve the function of preserving power distribution, ensuring that the SDM is maintained, ensuring that ejected CEA worth is maintained, and ensuring adequate negative reactivity insertion on trip. The overlap between regulating banks provides more uniform rates of reactivity insertion and withdrawal, and is imposed to maintain acceptable power peaking during regulating CEA motion.

The power dependent insertion limit (PDIL) alarm circuit is required to be OPERABLE for notification that the CEA banks are outside the required insertion limits. When the PDIL alarm circuit is inoperable, the verification of CEA positions is increased to ensure improper CEA alignment is identified before unacceptable flux distribution occurs.
BASES

APPLICABILITY

The regulating CEA sequence, overlap, and physical insertion limits shall be maintained with the reactor in MODES 1 and 2. These limits must be maintained, since they preserve the assumed power distribution, ejected CEA worth, SDM, and reactivity rate insertion assumptions. Applicability in MODES 3, 4, and 5 is not required, since neither the power distribution nor ejected CEA worth assumptions would be exceeded in these MODES. SDM is preserved in MODES 3, 4, and 5 by adjustments to the soluble boron concentration.

This LCO is modified by a Note indicating the LCO requirement is suspended during SR 3.1.4.3. This SR verifies the freedom of the CEAs to move and requires the regulating CEAs to move below the LCO limits, which would normally violate the LCO. The Note also allows the LCO to be not applicable during reactor power cutback operation, which inserts a selected CEA group (usually group 5) during loss of load events.

ACTIONS

A.1 and A.2

Operation beyond the transient insertion limit can result in a loss of SDM and excessive peaking factors. The transient insertion limit should not be violated during normal operation; this violation, however, can occur during transients when the operator is manually controlling the CEAs in response to changing plant conditions. When the regulating groups are inserted beyond the transient insertion limits, actions must be taken to either withdraw the regulating groups beyond the limits or to reduce THERMAL POWER to less than or equal to that allowed for the actual CEA insertion limit. Two hours provides a reasonable time to accomplish this, allowing the operator to deal with current plant conditions while limiting peaking factors to acceptable levels.

B.1 and B.2

If the CEAs are inserted between the long term steady state insertion limits, the transient insertion limits for intervals > 4 hours per 24 hour period, and the short term steady state insertion limits are exceeded, peaking factors can develop that are of immediate concern (Ref. 3).

Additionally, since the CEAs can be in this condition without misalignment, penalty factors are not inserted in the core protection calculators (CPCs) to compensate for the developing peaking factors. Verifying the short term steady state insertion limits are not exceeded ensures that the peaking factors that do develop are within those allowed for continued operation. Fifteen minutes provides adequate time for the operator to verify if the short term steady state insertion limits are exceeded.
Experience has shown that rapid power increases in areas of the core, in which the flux has been depressed, can result in fuel damage as the LHR in those areas rapidly increases. Restricting the rate of THERMAL POWER increases to ≤ 5% RTP per hour, following CEA insertion beyond the long term steady state insertion limits, ensures the power transients experienced by the fuel will not result in fuel failure (Ref. 3).

C.1

With the regulating CEAs inserted between the long term steady state insertion limit and the transient insertion limit, and with the core approaching the 5 effective full power days (EFPD) per 30 EFPD or 14 EFPD per 365 EFPD limits, the core approaches the acceptable limits placed on operation with flux patterns outside those assumed in the long term burnup assumptions. In this case, the CEAs must be returned to within the long term steady state insertion limits, or the core must be placed in a condition in which the abnormal fuel burnup cannot continue. A Completion Time of 2 hours is a reasonable time to return the CEAs to within the long term steady state insertion limits.

The required Completion Time of 2 hours from initial discovery of a regulating CEA group outside the limits until its restoration to within the long term steady state limits, shown on the figures in the COLR, allows sufficient time for borated water to enter the Reactor Coolant System from the Chemical Addition and Makeup Systems, and to cause the regulating CEAs to withdraw to the acceptable region. It is reasonable to continue operation for 2 hours after it is discovered that the 5 EFPD or 14 EFPD limit has been exceeded. This Completion Time is based on limiting the potential xenon redistribution, the low probability of an accident, and the steps required to complete the action.

D.1 and D.2

With the Core Operating Limit Supervisory System (COLSS) out of service, operation beyond the short term steady state insertion limits can result in peaking factors that could approach the DNB or local power density trip setpoints. Eliminating this condition within 2 hours limits the magnitude of the peaking factors to acceptable levels (Ref. 3). Restoring the CEAs to within the limit or reducing THERMAL POWER to that fraction of RTP that is allowed by CEA group position, using the limits specified in the COLR, ensures acceptable peaking factors are maintained.
BASES

ACTIONS (continued)

E.1
With the PDIL circuit inoperable, performing SR 3.1.6.1 within 1 hour and every 4 hours thereafter ensures improper CEA alignments are identified before unacceptable flux distributions occur.

F.1
When a Required Action cannot be completed within the required Completion Time, a controlled shutdown should be commenced. The allowed Completion Time of 6 hours is reasonable, based on operating experience, for reaching MODE 3 from full power conditions in an orderly manner and without challenging plant systems.

SURVEILLANCE REQUIREMENTS

SR 3.1.6.1
With the PDIL alarm circuit OPERABLE, verification of each regulating CEA group position every 12 hours is sufficient to detect CEA positions that may approach the acceptable limits, and provide the operator with time to undertake the Required Action(s) should the sequence or insertion limits be found to be exceeded. The 12 hour Frequency also takes into account the indication provided by the PDIL alarm circuit and other information about CEA group positions available to the operator in the main control room (MCR).

SR 3.1.6.1 is modified by a Note indicating that this Surveillance is not required prior to entry into MODE 2. This is necessary, since the unit must be in the applicable MODES in order to perform Surveillances that demonstrate the LCO limits are met.

SR 3.1.6.2
Verification of the accumulated time of CEA group insertion between the long term steady state insertion limits and the transient insertion limits ensures the cumulative time limits are not exceeded. The 24 hour Frequency ensures the operator identifies a time limit that is being approached before it is reached.
SURVEILLANCE REQUIREMENTS (continued)

SR 3.1.6.3

Demonstrating the PDIL alarm circuit OPERABLE verifies that the PDIL alarm circuit is functional. The 31 day Frequency takes into account other Surveillances being performed at shorter Frequencies that identify improper CEA alignments.

REFERENCES

2. 10 CFR 50.46.
3. FSAR, Section 15.4.
B 3.1 REACTIVITY CONTROL SYSTEMS

B 3.1.7 Part Strength Control Element Assembly (CEA) Insertion Limits

BASES

BACKGROUND  The insertion limits of the part strength CEAs are initial assumptions in all safety analyses. The insertion limits directly affect core power distributions. The applicable criteria for these power distribution design requirements are General Design Criteria (GDC) 10 (Ref. 1) and 10 CFR 50.46 (Ref. 2). Limits on part strength CEA insertion have been established, and all CEA positions are monitored and controlled during power operation to ensure that the power distribution defined by the design power peaking limits is preserved.

The part strength CEAs are used for axial power shape control of the reactor. The positions of the part strength CEAs are manually controlled. They are capable of changing reactivity very quickly.

The power density at any point in the core must be limited to maintain specified acceptable fuel design limits (SAFDL), including limits that preserve the criteria specified in 10 CFR 50.46 (Ref. 2). Together, LCO 3.1.6, “Regulating Control Element Assembly (CEA) Insertion Limits,” LCO 3.1.7, LCO 3.2.4, “Departure from Nucleate Boiling Ratio (DNBR),” and LCO 3.2.5, “AXIAL SHAPE INDEX (ASI),” provide limits on control component operation and on monitored process variables to ensure the core operates within the linear heat rate (LHR) (LCO 3.2.1, “Linear Heat Rate (LHR)”), planar peaking factor (F_{xy}) (LCO 3.2.2, “Planar Radial Peaking Factors (F_{xy})”), and LCO 3.2.4 limits in the COLR.

Operation within the limits given in the COLR prevents power peaks that would exceed the loss of coolant accident (LOCA) limits derived by the Emergency Core Cooling System analysis. Operation within the F_{xy} and departure from nucleate boiling (DNB) limits given in the COLR prevents DNB during a loss of forced reactor coolant flow accident.

The establishment of limiting safety system settings and LCOs requires that the expected long and short term behavior of the radial peaking factors be determined.

The long term behavior relates to the variation of the steady state radial peaking factors with core burnup. It is affected by the amount of CEA insertion assumed, the portion of a burnup cycle over which such insertion is assumed, and the expected power level variation throughout the cycle. The short term behavior relates to transient perturbations to the steady state radial peaks due to radial xenon redistribution. The magnitudes of such perturbations depend upon the expected use of the
B BASES

BACKGROUND (continued)

CEAs during anticipated power reductions and load maneuvering. Analyses are performed, based on the expected MODE of operation of the Nuclear Steam Supply System (e.g., base loaded, maneuvering). From these analyses, CEA insertions are determined and a consistent set of radial peaking factors are defined. The long term (steady state) and short term insertion limits are determined, based upon the assumed MODE of operation used in the analyses. They provide a means of preserving the assumptions on CEA insertions used. The long and short term insertion limits of LCO 3.1.7 are specified for the plant, which has been designed primarily for base loaded operation, but has the ability to accommodate a limited amount of load maneuvering.

APPLICABLE SAFETY ANALYSES

The fuel cladding must not sustain damage as a result of normal operation (Condition I) and anticipated operational occurrences (Condition II). The regulating CEA insertion, part strength CEA insertion, ASI, and Tq LCOs preclude core power distributions from occurring that would violate the following fuel design criteria:

a. During a large break LOCA, the peak cladding temperature must not exceed 1,204°C (2,200°F) per 10 CFR 50.46 (Ref. 2).

b. During a loss of forced reactor coolant flow accident, there must be at least a 95% probability at a 95% confidence level (the 95/95 DNB criterion) that the hot fuel rod in the core does not experience a DNB condition.

c. During an ejected CEA accident, the fission energy input to the fuel must not exceed 963 kJ/kg (230 cal/g) (Ref. 3).

d. The CEAs must be capable of shutting down the reactor with a minimum required SDM, with the highest worth CEA stuck fully withdrawn, per GDC 26 (Ref. 1).

Regulating CEA position, part strength CEA position, ASI, and Tq are process variables that characterize and control the three dimensional power distribution of the reactor core.

Fuel cladding damage does not occur when the core is operated outside these LCOs during normal operation. However, fuel cladding damage could result, should an accident occur with simultaneous violation of one or more of these LCOs. Changes in the power distribution can cause increased power peaking and corresponding increased local LHRs. The
Bases

Applicable Safety Analyses (continued)

Part strength CEA insertion limits are required due to the potential peaking factor violations that could occur if part strength CEAs exceed insertion limits.

The part strength CEA insertion limits satisfy Criterion 2 of 10 CFR 50.36(c)(2)(ii).

LCO

The limits on part strength CEA insertion, as defined in the COLR, must be maintained because they serve the function of preserving power distribution.

Applicability

The part strength insertion limits shall be maintained with the reactor in MODE 1 > 20% RTP. These limits must be maintained since they preserve the assumed power distribution. Applicability in lower MODES is not required since the power distribution assumptions would not be exceeded in these MODES.

This LCO has been modified by a Note suspending the LCO requirement while exercising part strength CEAs. Exercising part strength CEAs could require moving them outside their insertion limits.

Actions

A.1

If the part strength CEA groups are inserted between the long term (steady state) insertion limit and the transient limit for 7 or more effective full power days (EFPD) out of any 30 EFPD period, or for 14 EFPD or more out of any 365 EFPD period, flux patterns begin to develop that are outside the range assumed for long term fuel burnup. If allowed to continue beyond this limit, the peaking factors assumed as initial conditions in the accident analysis could be invalidated (Ref. 3).

Restoring the CEAs to within limits specified in the COLR ensures that acceptable peaking factors are maintained.

Since these effects are cumulative, ACTIONS are provided to limit the total time the part strength CEAs can be out of limits in any 30 EFPD or 365 EFPD period. Since the cumulative out of limit times are in days, an additional Completion Time of 2 hours is reasonable for restoring the part strength CEAs to within the allowed limits.
When a Required Action cannot be completed within the required Completion Time, a controlled THERMAL POWER reduction should commence. A Completion Time of 4 hours is reasonable, based on operating experience, for reducing power to ≤ 20% RTP from full power conditions in an orderly manner and without challenging plant systems.

Verification of each part strength CEA group position every 12 hours is sufficient to detect CEA positions that could approach the limits, and provide the operator with time to undertake the Required Action(s), should insertion limits be found to be exceeded. The 12 hour Frequency also takes into account the indication provided by the power dependent insertion limit alarm circuit and other information about CEA group positions available to the operator in the main control room (MCR).

Verification of the accumulated time of part strength CEA group insertion beyond the long term steady state insertion limits ensures the cumulative time limits are not exceeded. The 24 hour Frequency ensures the operator identifies a time limit that is being approached before it is reached.

2. 10 CFR 50.46.
3. FSAR, Section 15.4.
B 3.1 REACTIVITY CONTROL SYSTEMS

B 3.1.8 Charging Flow

BASES

BACKGROUND

The Chemical and Volume Control System (CVCS) is described in FSAR Section 9.3 (Ref. 1). The CVCS is used to control the boron concentration in the Reactor Coolant System (RCS) to obtain optimum control element assembly (CEA) positioning, to compensate for reactivity changes associated with major changes in reactor coolant temperature, core burnup, and xenon variations, and to provide SHUTDOWN MARGIN for maintenance and refueling operations. The system includes two centrifugal charging pumps and a positive displacement auxiliary charging pump. During operations one charging pump is normally in service, the other charging pump and the auxiliary charging pump are in standby.

Charging flow is assumed in the safety analysis for the inadvertent deboration event (Ref. 2). In MODES 1, 2, 3, 4, and 5, when at least one Reactor Coolant Pump (RCP) is in operation, a charging flow rate of 681.4 L/min (180 gpm) is assumed. During MODES 4 and 5 with all RCPs idle and in MODE 6, isolation valve (CV-186), for the reactor makeup water source containing unborated water that is connected to the CVCS, must be closed to prevent unplanned boron dilution of the reactor coolant in accordance with LCO 3.1.12 and LCO 3.9.7. With no RCS loop in operation a boron dilution event is precluded in MODE 3 by LCO 3.4.5. With one or more RCS loops inoperable a boron dilution event is precluded in MODES 1 and 2 by LCO 3.4.4, which would require placing the unit in MODE 3. With less than four RCPs running, a boron dilution event is precluded in MODES 1 and 2 by an automatic reactor trip in accordance with LCO 3.3.1, which would place the unit in MODE 3.

APPLICABLE SAFETY ANALYSES

The maximum charging flow rate of 681.4 L/min (180 gpm) during MODES 1, 2, 3, 4, and 5 is an assumed initial condition of the safety analysis for the inadvertent deboration event as described in the FSAR Section 15.4 (Ref. 2). Therefore, limiting charging flow during these operational conditions satisfies Criterion 2 of 10 CFR 50.36(c)(2)(ii).

LCO

The LCO states that charging flow shall be maintained below 681.4 L/min (180 gpm) during MODES 1, 2, 3, 4, and 5 to restrict the maximum charging flow.
Bases

Applicability

This LCO is applicable in MODES 1, 2, 3, 4, and 5 to maintain the maximum charging flow below 681.4 L/min (180 gpm). The maximum charging flow of 681.4 L/min (180 gpm) shall be met during MODES 1, 2, 3, 4, and 5 since charging flow is assumed to be 681.4 L/min (180 gpm) in the safety analysis of the inadvertent deboration event during MODES 1, 2, 3, 4, and 5.

Actions

A.1

The charging flow must be immediately restored below the limit if this LCO is not met. This ensures that the charging flow to the RCS is less than the limit assumed in the safety analyses. This action includes closing CV-576 (and CV-577 if required additionally) or manually modulating charging control valve CV-212P or CV-212Q. The immediate Completion Time reflects the importance of preventing positive reactivity changes resulting from reducing RCS temperature and injecting unborated water into the RCS in MODES 1, 2, 3, 4 and 5.

A.2

If Required Action A.1 cannot be completed immediately, isolation valve (CV-186) for the reactor makeup water source containing unborated water that is connected to the CVCS must be closed immediately to prevent unplanned boron dilution of the reactor coolant.

Surveillance Requirements

SR 3.1.8.1

This surveillance ensures that the charging flow to the RCS is less than the limit assumed in the safety analyses. This is performed by using the charging flow meter F-212B. The 12 hour Frequency for this Surveillance is sufficient to verify that the charging flow is maintained below 681.4 L/min (180 gpm).

References

1. FSAR, Section 9.3.
2. FSAR, Section 15.4.
B 3.1 REACTIVITY CONTROL SYSTEMS

B 3.1.9 Special Test Exception (STE) – SHUTDOWN MARGIN (SDM)

BASES

BACKGROUND

The primary purpose of the SDM STE is to permit relaxation of existing LCOs to allow the performance of certain PHYSICS TESTS. These tests are conducted to determine the control element assembly (CEA) worth and SDM.

10 CFR Part 50, Appendix B, Section XI (Ref. 1) requires that a test program be established to ensure that structures, systems, and components (SSCs) will perform satisfactorily in service. All functions necessary to ensure that specified design conditions are not exceeded during normal operation and anticipated operational occurrences (AOOs) must be tested. Testing is required as an integral part of the design, fabrication, construction, and operation of the power plant. Requirements for notification of the NRC, for the purpose of conducting tests and experiments, are specified in 10 CFR 50.59, "Changes, Tests, and Experiments" (Ref. 2).

The key objectives of a test program are to (Ref. 3):

a. Ensure the facility has been adequately designed;

b. Validate analytical models used in design and analysis;

c. Verify assumptions used for predicting plant response;

d. Ensure installation of equipment in the facility has been accomplished in accordance with the design; and

e. Verify operating and emergency procedures are adequate.

To accomplish these objectives, testing is required prior to initial criticality, after each refueling shutdown, and during startup, low power operation, power ascension, and at power operation. The PHYSICS TESTS requirements for the initial core and reload fuel cycles ensure that the operating characteristics of the core are consistent with the design predictions and that the core can be operated as designed (Ref. 4).

PHYSICS TESTS procedures are written and approved in accordance with established formats. The procedures include all information necessary to permit a detailed execution of testing required to ensure that the design intent is met.
PHYSICS TESTS are performed in accordance with these procedures and test results are approved prior to continued power escalation and long term power operation. Examples of PHYSICS TESTS include determination of critical boron concentration, CEA group worths, reactivity coefficients, flux symmetry, and core power distribution.

It is acceptable to suspend certain LCOs for PHYSICS TESTS as long as fuel damage criteria are not exceeded. Even if an accident occurs during PHYSICS TESTS with one or more LCOs suspended, fuel damage criteria are preserved because adequate limits on power distribution and shutdown capability are maintained during PHYSICS TESTS.

Reference 5 defines the requirements for initial testing of the facility, including PHYSICS TESTS. Requirements for reload fuel cycle PHYSICS TESTS are defined in ANSI/ANS-19.6.1-2005 (Ref. 4). PHYSICS TESTS for reload fuel cycles are given in Table 1 of ANSI/ANS-19.6.1-2005. Although these PHYSICS TESTS are generally accomplished within the limits of all LCOs, conditions could occur when one or more LCOs must be suspended to make completion of PHYSICS TESTS possible or practical. This is acceptable as long as the fuel design criteria are not violated. As long as the linear heat rate (LHR) and the departure from nucleate boiling ratio (DNBR) remain within their limits, fuel design criteria are preserved.

In this test, the following LCOs are suspended:

a. LCO 3.1.1, “SHUTDOWN MARGIN (SDM)”;

b. LCO 3.1.5, “Shutdown Control Element Assembly (CEA) Insertion Limits”;

c. LCO 3.1.6, “Regulating Control Element Assembly (CEA) Insertion Limits”;

d. LCO 3.3.1, “Reactor Protection System (RPS) Instrumentation – Operating” (Only applied to Trip Functions 2, 14 and 15 in Table 3.3.1-1); and

e. LCO 3.3.2, “Reactor Protection System (RPS) Instrumentation – Shutdown” (Only Applied to Trip Function 1 in Table 3.3.2-1).

Therefore, this LCO places limits on the minimum amount of CEA worth required to be available for reactivity control when CEA worth measurements are performed.
Bases

Applicable Safety Analyses (continued)

The individual LCOs cited above govern SDM, CEA group height, insertion, and alignment. Additionally, the LCOs governing Reactor Coolant System (RCS) flow, cold leg temperature ($T_{\text{cold}}$), and pressurizer pressure contribute to maintaining DNBR limits. The initial condition criteria for accidents sensitive to core power distribution are preserved by the LHR and DNBR limits. The criteria for the loss of coolant accident (LOCA) are specified in 10 CFR 50.46 (Ref. 6). The criteria for the loss of forced reactor coolant flow accidents are specified in Reference 7. Operation within the LHR limit preserves the LOCA criteria. Operation within the DNBR limits preserves the loss of flow criteria.

SRs are conducted as necessary to ensure that LHR and DNBR remain within limits during Physics Tests. Performance of these SRs allows Physics Tests to be conducted without decreasing the margin of safety.

Requiring that shutdown reactivity equivalent to at least the highest estimated CEA worth (of those CEAs actually withdrawn) be available for trip insertion from the Operable CEAs, provides a high degree of assurance that shutdown capability is maintained for the most challenging postulated accident, a stuck CEA. Since LCO 3.1.1 is suspended, however, there is not the same degree of assurance during this test that the reactor would always be shut down if the highest worth CEA was stuck out and calculational uncertainties or the estimated highest CEA worth was not as expected (the single failure criterion is not met). This situation is judged acceptable, however, because specified acceptable fuel damage limits are still met.

The risk of experiencing a stuck CEA and subsequent criticality is reduced during this Physics Test exception by the requirements to determine CEA positions every 2 hours, the trip of each CEA to be withdrawn within 24 hours prior to suspending the SDM requirements, and ensuring that shutdown reactivity is available equivalent to the reactivity worth of the estimated highest worth withdrawn CEA (Ref. 5).

Physics Tests include measurement of core parameters or exercise of control components that affect process variables. Among the process variables involved are total planar radial peaking factor, total integrated radial peaking factor, $T_a$, and ASI, which represent initial condition input (power peaking) to the accident analysis. Also involved are the shutdown and regulating CEAs, which affect power peaking and are required for shutdown of the reactor. The limits for these variables are specified for each fuel cycle in the COLR.
BASES

APPLICABLE SAFETY ANALYSES (continued)

As described in LCO 3.0.7, compliance with STE LCOs is optional, and therefore no criteria of 10 CFR 50.36(c)(2)(ii) apply. STE LCOs provide flexibility to perform certain operations by appropriately modifying requirements of other LCOs. Discussions of the criteria satisfied for the other LCOs are provided in their respective Bases.

LCO

This LCO provides that a minimum amount of CEA worth is immediately available for reactivity control when CEA worth measurement tests are performed. This STE is required to permit the periodic verification of the actual versus predicted reactivity worth of the regulating CEA and shutdown CEA. The SDM requirements of LCO 3.1.1, the Shutdown CEA Insertion Limits of LCO 3.1.5, the Regulating CEA Insertion Limits of LCO 3.1.6, Trip Functions 2, 14 and 15 in Table 3.3.1-1 of LCO 3.3.1, and Trip Function 1 in Table 3.3.2-1 of LCO 3.3.2 may be suspended.

APPLICABILITY

This LCO is applicable in MODES 2 and 3. Although CEA worth testing is conducted in MODE 2, sufficient negative reactivity is inserted during the performance of these tests to result in temporary entry into MODE 3. Because the intent is to immediately return to MODE 2 to continue CEA worth measurements, the STE allows limited operation to 6 consecutive hours in MODE 3 as indicated by the Note, without having to borate to meet the SDM requirements of LCO 3.1.1.

ACTIONS

A.1

With any CEA not fully inserted and less than the minimum required reactivity equivalent available for insertion, or with all CEAs inserted and the reactor subcritical by less than the reactivity equivalent of the highest worth withdrawn CEA, restoration of the minimum SDM requirements must be accomplished by increasing the RCS boron concentration.

The required Completion Time of 15 minutes for initiating boration allows the operator sufficient time to align the valves and start the boric acid pumps and is consistent with the Completion Time of LCO 3.1.1.
SR 3.1.9.1

Verification of the position of each partially or fully withdrawn full strength or part strength CEA is necessary to ensure that the minimum negative reactivity requirements for insertion on a trip are preserved. The 2 hour Frequency is sufficient for the operator to verify that each CEA position is within the acceptance criteria.

SR 3.1.9.2

Prior demonstration that each CEA to be withdrawn from the core during PHYSICS TESTS is capable of full insertion, when tripped from at least a 50% withdrawn position, ensures that the CEA will insert on a trip signal. The 24 hour Frequency ensures that the CEAs are OPERABLE prior to reducing SDM to less than the limits of LCO 3.1.1.

This SR is modified by a Note which allows the SR to not be performed during initial power escalation following a refueling outage if SR 3.1.4.5 has been met during that refueling outage. This allows the CEA drop time test, which also proves the CEAs are trippable, to be credited for this SR.

SR 3.1.9.3

This SR is only applicable in MODE 3 as indicated in the Note.

Verification of the reactor subcritical by more than the reactivity equivalent of the highest worth withdrawn CEA in MODE 3 is necessary to ensure that the minimum negative reactivity requirements are preserved. The minimum negative reactivity requirements are certified through the reactivity balance calculation of the following reactivity related effects:

a. Boron concentration of RCS;

b. Positions of CEAs;

c. Average temperature of RCS;

d. Fuel burnup based on total amount of thermal energy production;

e. Xenon concentration; and

f. Samarium concentration.

Considering the slow change rate of boron concentration, the 2 hour Frequency is sufficient for the operator to collect the necessary data.
SURVEILLANCE REQUIREMENTS  (continued)

SR  3.1.9.4

Within 12 hours prior to initiation of reactor startup or PHYSICS TESTS, CHANNEL FUNCTIONAL TESTS on each logarithmic and variable overpower neutron flux monitoring channel shall be performed to verify OPERABILITY of the entire channels and to adjust the setpoints with appropriate values. This ensures the Reactor Protection System is properly arranged in order to provide necessary core protection required during reactor startup or PHYSICS TESTS. During reactor startup or PHYSICS TESTS, the 12 hour Frequency is sufficient time to ensure that the components supporting the Plant Protection and Monitoring Systems are OPERABLE prior to testing.

REFERENCES

1. 10 CFR Part 50, Appendix B, Section XI.

2. 10 CFR 50.59.


5. FSAR, Chapter 14.

6. 10 CFR 50.46.

7. FSAR, Subsection 15.3.1.
B 3.1  REACTIVITY CONTROL SYSTEMS

B 3.1.10  Special Test Exception (STE) – MODES 1 and 2

BASES

BACKGROUND  The primary purpose of these MODES 1 and 2 STE is to permit relaxation of existing LCOs to allow the performance of certain PHYSICS TESTS. These tests are conducted to determine specific reactor core characteristics.

10 CFR Part 50, Appendix B, Section XI (Ref. 1) requires that a test program be established to ensure that structures, systems, and components will perform satisfactorily in service. All functions necessary to ensure that specified design conditions are not exceeded during normal operation and anticipated operational occurrences must be tested. Testing is required as an integral part of the design, fabrication, construction, and operation of the power plant. Requirements for notification of the NRC, for the purpose of conducting tests and experiments, are specified in 10 CFR 50.59, "Changes, Tests, and Experiments" (Ref. 2).

The key objectives of a test program are to (Ref. 3):

a. Ensure the facility has been adequately designed;

b. Validate analytical models used in design and analysis;

c. Verify assumptions used for predicting plant response;

d. Ensure installation of equipment in the facility has been accomplished in accordance with design; and

e. Verify operating and emergency procedures are adequate.

To accomplish these objectives, testing is required prior to initial criticality, after each refueling shutdown, and during startup, low power operation, power ascension, and at power operation. The PHYSICS TESTS requirements for the initial core and reload fuel cycles ensure that the operating characteristics of the core are consistent with the design predictions and that the core can be operated as designed (Ref. 4).

PHYSICS TESTS procedures are written and approved in accordance with established formats. The procedures include all information necessary to permit a detailed execution of testing required to ensure that design intent is met.
PHYSICS TESTS are performed in accordance with these procedures and test results are approved prior to continued power escalation and long term power operation. Examples of PHYSICS TESTS include determination of critical boron concentration, CEA group worths, reactivity coefficients, flux symmetry, and core power distribution.

It is acceptable to suspend certain LCOs for PHYSICS TESTS as long as fuel damage criteria are not exceeded. Even if an accident occurs during PHYSICS TESTS with one or more LCOs suspended, fuel damage criteria are preserved because the limits on power distribution and shutdown capability are maintained during PHYSICS TESTS.

Reference 5 defines requirements for initial testing of the facility, including PHYSICS TESTS. Requirements for reload fuel cycle PHYSICS TESTS are defined in ANSI/ANS-19.6.1-2005 (Ref. 4). Although these PHYSICS TESTS are generally accomplished within the limits of all LCOs, conditions could occur when one or more LCOs must be suspended to make completion of PHYSICS TESTS possible or practical. This is acceptable as long as the fuel design criteria are not violated. As long as the linear heat rate (LHR) and the departure from nucleate boiling ratio (DNBR) remain within their limits, fuel design criteria are preserved.

In this test, the following LCOs are suspended:

a. LCO 3.1.3, “Moderator Temperature Coefficient (MTC)”;
b. LCO 3.1.4, “Control Element Assembly (CEA) Alignment”;
c. LCO 3.1.5, “Shutdown Control Element Assembly (CEA) Insertion Limits”;
d. LCO 3.1.6, “Regulating Control Element Assembly (CEA) Insertion Limits”;
e. LCO 3.1.7, “Part Strength Control Element Assembly (CEA) Insertion Limits”;
f. LCO 3.2.2, “Planar Radial Peaking Factors (Fxy)”;
g. LCO 3.2.3, “AZIMUTHAL POWER TILT (Tq)”;
h. LCO 3.2.5, “AXIAL SHAPE INDEX (ASI)”
The safety analysis (Ref. 6) places limits on allowable THERMAL POWER during PHYSICS TESTS and requires that the LHR and the DNBR be maintained within limits. The power plateau of < 85% RTP and the associated trip setpoints are required to ensure that LHR and DNBR are maintained within acceptable limits.

The individual LCOs governing CEA height, insertion and alignment, ASI, total planar radial peaking factor, total integrated radial peaking factor, and $T_q$, preserve the LHR limits. Additionally, the LCOs governing Reactor Coolant System (RCS) flow, cold leg temperature ($T_{\text{cold}}$), and pressurizer pressure contribute to maintaining DNBR limits. The initial condition criteria for accidents sensitive to core power distribution are preserved by the LHR and DNBR limits. The criteria for the loss of coolant accident (LOCA) are specified in 10 CFR 50.46 (Ref. 7). The criteria for the loss of forced reactor coolant flow accident are specified in Reference 8. Operation within the LHR limits preserves the LOCA criteria; operation within the DNBR limits preserves the loss of flow criteria. During PHYSICS TESTS, one or more of the LCOs that normally preserve the LHR and DNBR limits may be suspended. The results of the accident analysis are not adversely impacted, however, if LHR and DNBR are verified to be within their limits while the LCOs are suspended. Therefore, SRs are placed as necessary to ensure that LHR and DNBR remain within limits during PHYSICS TESTS. Performance of these Surveillances allows PHYSICS TESTS to be conducted without decreasing the margin of safety.

PHYSICS TESTS include measurement of core parameters or exercise of control components that affect process variables. Among the process variables involved are total planar radial peaking factor, total integrated radial peaking factor, $T_q$, and ASI, which represent initial condition input (power peaking) to the accident analysis. Also involved are the shutdown and regulating CEAs, which affect power peaking and are required for shutdown of the reactor. The limits for these variables are specified for each fuel cycle in the COLR.

As described in LCO 3.0.7, compliance with STE LCOs is optional, and therefore no criteria of 10 CFR 50.36(c)(2)(ii) apply. STE LCOs provide flexibility to perform certain operations by appropriately modifying requirements of other LCOs.

Discussions of the criteria satisfied for the other LCOs are provided in their respective Bases.
This LCO permits individual CEAs to be positioned outside of their normal group heights and insertion limits during the performance of PHYSICS TESTS, such as those required to:

a. Measure CEA worth;

b. Determine the reactor stability index and damping factor under xenon oscillation conditions;

c. Determine power distributions for non-normal CEA configurations;

d. Measure rod shadowing factors; and

e. Measure temperature and power coefficients.

The requirements of LCOs 3.1.3, 3.1.4, 3.1.5, 3.1.6, 3.1.7, 3.2.2, 3.2.3, and 3.2.5 can be suspended during the performance of PHYSICS TESTS provided THERMAL POWER is restricted to test power plateau, which shall not exceed 85% RTP.

This LCO is applicable in MODES 1 and 2 because the reactor must be critical at various THERMAL POWER levels to perform the PHYSICS TESTS described in the LCO section. Limiting the test power plateau to ≤ 85% RTP ensures that LHRs are maintained within acceptable limits.

If THERMAL POWER exceeds the test power plateau in MODE 1, THERMAL POWER must be reduced to restore the additional thermal margin provided by the reduction. The 15 minute Completion Time ensures that prompt action shall be taken to reduce THERMAL POWER to within acceptable limits.

If Required Action A.1 cannot be completed within the required Completion Time, PHYSICS TESTS must be suspended within 1 hour. Allowing 1 hour for suspending PHYSICS TESTS allows the operator sufficient time to change any abnormal CEA configuration back to within the limits of LCO 3.1.4, 3.1.5, and 3.1.6. Suspension of PHYSICS TESTS exceptions requires restoration of each of the applicable LCOs to within specification.
Verifying that THERMAL POWER is equal to or less than that allowed by the test power plateau, as specified in the PHYSICS TEST procedure and required by the safety analysis, ensures that adequate LHR and DNBR margins are maintained while LCOs are suspended. The 1 hour Frequency is sufficient, based upon the slow rate of power change and increased operational controls in place during PHYSICS TESTS. Monitoring LHR ensures that the limits are not exceeded.

REFERENCES

1. 10 CFR Part 50, Appendix B, Section XI.
2. 10 CFR 50.59.
5. FSAR, Chapter 14.
6. FSAR, Chapter 15.
7. 10 CFR 50.46.
8. FSAR, Subsection 15.3.1.
B 3.1 REACTIVITY CONTROL SYSTEMS

B 3.1.11 Special Test Exception (STE) – Reactivity Coefficient Testing

BASES

BACKGROUND

The primary purpose of STE during Reactivity Coefficient Testing is to permit relaxation of existing LCOs to allow the performance of certain PHYSICS TESTS. These tests are conducted to determine isothermal temperature coefficient, moderator temperature coefficient, and power coefficient.

10 CFR Part 50, Appendix B, Section XI (Ref. 1) requires that a test program be established to ensure that structures, systems, and components (SSCs) will perform satisfactorily in service. All functions necessary to ensure that specified design conditions are not exceeded during normal operation and anticipated operational occurrences must be tested. Testing is required as an integral part of the design, fabrication, construction, and operation of the power plant. Requirements for notification of the NRC, for the purpose of conducting tests and experiments, are specified in 10 CFR 50.59, "Changes, Tests, and Experiments" (Ref. 2).

The key objectives of a test program are to (Ref. 3):

a. Ensure the facility has been adequately designed;

b. Validate analytical models used in design and analysis;

c. Verify assumptions used for predicting plant response;

d. Ensure installation of equipment in the facility has been accomplished in accordance with design; and

e. Verify operating and emergency procedures are adequate.

To accomplish these objectives, testing is required prior to initial criticality, after each refueling shutdown, and during startup, low power operation, power ascension, and at power operation. The PHYSICS TESTS requirements for the initial core and reload fuel cycles ensure that the operating characteristics of the core are consistent with the design predictions and that the core can be operated as designed (Ref. 5).

PHYSICS TESTS procedures are written and approved in accordance with established formats. The procedures include all information necessary to permit a detailed execution of testing required to ensure that design intent is met.
PHYSICS TESTS are performed in accordance with these procedures and test results are approved prior to continued power escalation and long term power operation. Examples of PHYSICS TESTS include determination of critical boron concentration, CEA group worths, reactivity coefficients, flux symmetry, and core power distribution.

It is acceptable to suspend certain LCOs for PHYSICS TESTS as long as fuel damage criteria are not exceeded. Even if an accident occurs during PHYSICS TESTS with one or more LCOs suspended, fuel damage criteria are preserved because the limits on power distribution and shutdown capability are maintained during PHYSICS TESTS.

Reference 5 defines requirements for initial testing of the facility, including PHYSICS TESTS. Requirements for reload fuel cycle PHYSICS TESTS are defined in ANSI/ANS-19.6.1-2005 (Ref. 4). Although these PHYSICS TESTS are generally accomplished within the limits of all LCOs, conditions could occur when one or more LCOs must be suspended to make completion of PHYSICS TESTS possible or practical. This is acceptable as long as the fuel design criteria are not violated. As long as the linear heat rate (LHR) and the departure from nucleate boiling ratio (DNBR) remain within their limits, fuel design criteria are preserved.

In this test, the following LCOs are suspended:

a.  LCO 3.1.6, “Regulating Control Element Assembly (CEA) Insertion Limits”;

b.  LCO 3.1.7, “Part Strength Control Element Assembly (CEA) Insertion Limits”; and

c.  LCO 3.4.1, “RCS Pressure, Temperature, and Flow Limits” (LCOs 3.4.1.b and 3.4.1.c. RCS Cold Leg Temperature only).

The safety analysis (Ref. 5) requires that the LHR and the DNBR be maintained within limits. The associated trip setpoints are required to ensure these limits are maintained.
The individual LCOs governing CEA group height, insertion and alignment, ASI, total planar radial peaking factor, total integrated radial peaking factor, and $T_q$, preserve the LHR limits. Additionally, the LCOs governing Reactor Coolant System (RCS) flow, cold leg temperature ($T_{cold}$), and pressurizer pressure contribute to maintaining DNBR limits. The initial condition criteria for accidents sensitive to core power distribution are preserved by the LHR and DNBR limits. The criteria for the loss of coolant accident (LOCA) are specified in 10 CFR 50.46 (Ref. 6). The criteria for the loss of forced reactor coolant flow accident are specified in Reference 7. Operation within the LHR limit preserves the LOCA criteria. Operation within the DNBR limits preserves the loss of flow criteria.

During PHYSICS TESTS, one or more of the LCOs that normally preserve the LHR and DNBR limits may be suspended. The results of the accident analysis are not adversely impacted, however, if LHR and DNBR are verified to be within their limits while the LCOs are suspended. Therefore, SRs are placed as necessary to ensure that LHR and DNBR remain within limits during PHYSICS TESTS. Performance of these Surveillances allows PHYSICS TESTS to be conducted without decreasing the margin of safety.

PHYSICS TESTS include measurement of core parameters or exercise of control components that affect process variables. Among the process variables involved are total planar radial peaking factor, total integrated radial peaking factor, $T_q$, and ASI, which represent initial condition input (power peaking) to the accident analysis. Also involved are the shutdown and regulating CEAs, which affect power peaking and are required for shutdown of the reactor. The limits for these variables are specified for each fuel cycle in the COLR.

As described in LCO 3.0.7, compliance with STE LCOs is optional, and therefore no criteria of 10 CFR 50.36(c)(2)(ii) apply. STE LCOs provide flexibility to perform certain operations by appropriately modifying requirements of other LCOs. Discussions of the criteria satisfied for the other LCOs are provided in their respective Bases.

This LCO permits Part Strength CEAs and Regulating CEAs to be positioned outside of their normal group heights and insertion limits, and RCS cold leg temperature to be outside its limits during the performance of PHYSICS TESTS. These PHYSICS TESTS are required to determine the isothermal temperature coefficient (ITC), moderator temperature coefficient (MTC), and power coefficient.
BASES

LCO (continued)

The requirements of LCOs 3.1.6, 3.1.7 and 3.4.1 (for RCS cold leg temperature only) may be suspended during the performance of PHYSICS TESTS provided Core Operating Limit Supervisory System (COLSS) is in service.

APPLICABILITY

This LCO is applicable in MODE 1 with THERMAL POWER > 20% RTP because the reactor must be critical at THERMAL POWER levels > 20% RTP to perform the PHYSICS TESTS described in the LCO section.

ACTIONS

A.1

With the LHR or DNBR outside the limits specified in their LCOs, adequate safety margin is not assured and power must be reduced to restore LHR and DNBR to within limits. The required Completion Time of 15 minutes ensures prompt action is taken to restore LHR or DNBR to within limits.

B.1

When the Required Action cannot be met or completed within the required Completion Time, PHYSICS TESTS must be suspended within 1 hour. Allowing 1 hour for suspending PHYSICS TESTS allows the operator sufficient time to change any abnormal conditions back to within the limits of LCOs 3.1.6, 3.1.7, and 3.4.1 (for RCS cold leg temperature only). Suspension of PHYSICS TESTS exceptions requires restoration of each of the applicable LCOs to within specification.

SURVEILLANCE REQUIREMENTS

SR 3.1.11.1

With THERMAL POWER ≥ 20% RTP, LHR can be continuously monitored using the COLSS since the COLSS is available with THERMAL POWER above 20% RTP. If COLSS is not available, the operator must monitor the LHR using any OPERABLE core protection calculator (CPC) channel to verify that the LHR is within the specified limit in the COLR. A 15 minute Frequency is adequate to allow the operator to identify trends that would result in an approach to the LHR limit.
SURVEILLANCE REQUIREMENTS (continued)

SR 3.1.11.2

With THERMAL POWER $\geq$ 20% RTP, DNBR can be continuously monitored using the COLSS since the COLSS is available with THERMAL POWER above 20% RTP. If COLSS is not available, the operator must monitor the DNBR using any OPERABLE CPC channel to verify that the DNBR is within the limits of Figure 3.2.4-2 or Figure 3.2.4-3 of the COLR, as applicable. A 15 minute Frequency is adequate to allow the operator to identify trends in conditions that would result in an approach to the DNBR limit.

REFERENCES

1. 10 CFR Part 50, Appendix B, Section XI.
2. 10 CFR 50.59.
5. FSAR, Chapter 15.
6. 10 CFR 50.46.
7. FSAR, Subsection 15.3.1.
B 3.1 REACTIVITY CONTROL SYSTEMS

B 3.1.12 Unborated Water Source Isolation Valve – MODES 4 and 5

BASES

BACKGROUND During MODES 4 and 5 with all RCPs idle, isolation valve (CV-186) for reactor makeup water source containing unborated water that is connected to the Reactor Coolant System (RCS) must be closed to prevent unplanned boron dilution of the reactor coolant. The isolation valve must be secured in the closed position. This valve is a manual valve and does not have an indication of position in the control room (Ref. 1).

The Chemical and Volume Control System is capable of supplying borated and unborated water to the RCS through various flow paths. Since a positive reactivity addition made by reducing the boron concentration is inappropriate during MODES 4 and 5 with all RCPs idle, isolation of all unborated water sources prevents an unplanned boron dilution.

APPLICABLE SAFETY ANALYSES The possibility of an inadvertent boron dilution event (Ref. 2) occurring during MODES 4 and 5 with all RCPs idle operations is precluded by adherence to this LCO, which requires that potential dilution sources be isolated. Closing the required valve during these operations prevents the flow of unborated water to the filled portion of the RCS. The valve is used to isolate unborated water sources. This valve has the potential to indirectly allow dilution of the RCS boron concentration. By isolating unborated water sources, a safety analysis for an uncontrolled boron dilution event is not required for MODES 4 and 5 with all RCPs idle.

Isolation of unborated water sources to preclude a reduction in RCS boron concentration satisfies Criterion 2 of 10 CFR 50.36(c)(2)(ii).

LCO This LCO requires that flow paths to the RCS from unborated water sources be isolated to prevent unplanned boron dilution during MODES 4 and 5 with all RCPs idle and thus avoid a reduction in SDM.

APPLICABILITY This LCO is applicable in MODES 4 and 5 with all RCPs idle to prevent an inadvertent boron dilution event by ensuring isolation of all sources of unborated water to the RCS.
Unborated Water Source Isolation Valve – MODES 4 and 5

B3.1.12

BASES

ACTIONS

A.1

With the valve used to isolate unborated water sources not secured in the closed position, all operations involving positive reactivity changes must be suspended immediately. This includes stopping all charging pumps and halting any ongoing RCS temperature reduction operations. The immediate Completion Time reflects the importance of preventing positive reactivity changes resulting from reducing RCS temperature and injecting unborated water into the RCS when all RCPs are idle in MODES 4 and 5.

A.2

Preventing inadvertent dilution of the reactor coolant boron concentration is dependent on maintaining the unborated water isolation valve secured closed. Securing the valve in the closed position ensures that the valve cannot be inadvertently opened. The Completion Time of “immediately” requires an operator to initiate actions to close an open valve and secure the isolation valve in the closed position immediately. Once actions are initiated, they must be continued until the valve is secured in the closed position.

A.3

Due to the potential of having diluted the boron concentration of the reactor coolant, SR 3.1.1.1 (verification of SHUTDOWN MARGIN) must be performed. The Completion Time of 4 hours is based on the generally slow change in required boron concentration, and it also allows sufficient time for the operator to collect the required data, which includes performing a boron concentration analysis, and complete the calculation.

SURVEILLANCE REQUIREMENTS

SR 3.1.12.1

This valve is to be secured closed to isolate possible dilution paths. A reduction in the boron concentration during MODES 4 and 5 with all RCPs idle operations is precluded by isolating the valve that isolates unborated water sources. This Surveillance demonstrates that the valve is closed. The 12 hour Frequency is based on engineering judgment and is considered reasonable in view of other administrative controls that will ensure that the valve opening is an unlikely possibility.

REFERENCES

1. FSAR, Subsection 9.3.4.

2. FSAR, Subsection 15.4.6.
B 3.2 POWER DISTRIBUTION LIMITS

B 3.2.1 Linear Heat Rate (LHR)

BASES

BACKGROUND

The purpose of this LCO is to limit the core power distribution to the initial values assumed in the accident analyses. Operation within the limits imposed by this LCO limits or prevents potential fuel cladding failures that could breach the primary fission product barrier and release fission products to the reactor coolant in the event of a loss of coolant accident (LOCA), loss of flow accident, ejected control element assembly (CEA) accident, or other postulated accidents requiring termination by a Reactor Protection System (RPS) trip function. This LCO limits the damage to the fuel cladding during an accident by ensuring that the plant is operating within acceptable bounding conditions at the onset of a transient.

Methods of controlling the power distribution include:

a. Using full or part strength CEAs to alter the axial power distribution;

b. Decreasing CEA insertion by boration, thereby improving the radial power distribution; and

c. Correcting off optimum conditions (e.g., a CEA drop, misoperation of the unit) that cause margin degradations.

The core power distribution is controlled so that, in conjunction with other core operating parameters (e.g., CEA insertion and alignment limits), the power distribution does not result in violation of this LCO. The limiting safety system settings (LSSS) and this LCO are based on the accident analyses (Refs. 1 and 2), so that specified acceptable fuel design limits (SAFDL) are not exceeded as a result of anticipated operational occurrences (AOOs), and the limits of acceptable consequences are not exceeded for other postulated accidents.

Limiting power distribution skewing over time also minimizes xenon distribution skewing, which is a significant factor in controlling the axial power distribution.

Power distribution is a product of multiple parameters, various combinations of which may produce acceptable power distributions. Operation within the design limits of power distribution is accomplished by generating operating limits on the linear heat rate (LHR) and departure from nucleate boiling (DNB).
Proximity to the DNB condition is expressed by the DNB ratio (DNBR), defined as the ratio of the cladding surface heat flux required to cause DNB to the actual cladding surface heat flux. The minimum DNBR value during both normal operation and AOOs is calculated by the KCE-1 Correlation (Ref. 3) and corrected for such factors as rod bow and grid spacers. It is accepted as an appropriate margin to DNB for all operating conditions.

There are two systems that monitor core power distribution online: the Core Operating Limit Supervisory System (COLSS) and the core protection calculators (CPCs). The COLSS and CPCs that monitor the core power distribution are capable of verifying that the LHR and the DNBR do not exceed their limits. The COLSS performs this function by continuously monitoring the core power distribution and calculating core power operating limits corresponding to the allowable peak LHR and DNBR. The CPCs perform this function by continuously calculating an actual value of DNBR and local power density (LPD) for comparison with the respective trip setpoints.

A DNBR penalty factor is included in both the COLSS and CPC DNBR calculations to accommodate the effects of rod bow. The amount of rod bow in each assembly is dependent upon the average burnup experienced by that assembly. Fuel assemblies that incur higher than average burnup experience a greater magnitude of rod bow. Conversely, fuel assemblies that receive lower than average burnup experience less rod bow. In design calculations for a reload core, each batch of fuel is assigned a penalty applied to the maximum integrated planar radial power peak of the batch. This penalty is correlated with the amount of rod bow determined from the maximum average assembly burnup of the batch. A single net penalty for the COLSS and CPCs is then determined from the penalties associated with each batch that comprises a core reload, accounting for the offsetting margins due to the lower radial power peaks in the higher burnup batches.

The COLSS indicates continuously to the operator how far the core is from the operating limits and provides an audible alarm if an operating limit is exceeded. Such a condition signifies a reduction in the capability of the plant to withstand an anticipated transient, but does not necessarily imply an immediate violation of fuel design limits. If the margin to fuel design limits continues to decrease, the RPS ensures that the SAFDLs are not exceeded during AOOs by initiating reactor trips.
The COLSS continually generates an assessment of the calculated margin for specified LHR and DNBR limits. The data required for these assessments include measured incore neutron flux, CEA positions, and Reactor Coolant System (RCS) inlet temperature, pressure, and flow.

In addition to the monitoring performed by the COLSS, the RPS (via the CPCs) continually infers the core power distribution and thermal margins by processing reactor coolant data, signals from excore neutron flux detectors, and input from redundant reed switch assemblies that indicate CEA positions. In this case, the CPCs assume a minimum core power of 20% RTP because the Power Range Excore Neutron Flux Detecting System is inaccurate below this power level. If power distribution or other parameters are perturbed as a result of an AOO, the high LPD or low DNBR trips in the RPS initiate a reactor trip prior to exceeding the fuel design limits.

The LHR and DNBR algorithms are valid within the limits on ASI, $F_{xy}$, and $T_q$. These limits are obtained directly from initial core or reload analysis.

The fuel cladding must not sustain damage as a result of normal operation or AOOs (Ref. 4).

The power distribution and CEA insertion and alignment LCOs prevent core power distributions from reaching levels that violate the following fuel design criteria:

a. During a LOCA, peak cladding temperature must not exceed 1,204°C (2,200°F) specified in the 10 CFR 50.46 (Ref. 5);

b. During a loss of flow accident, there must be at least 95% probability at the 95% confidence level (the 95/95 DNB criterion) that the hot fuel rod in the core does not experience a DNB condition (Ref. 4);

c. During an ejected CEA accident, the fission energy input to the fuel must not exceed 963 kJ/kg (230 cal/g) (Ref. 6); and

d. The control rods must be capable of shutting down the reactor with a minimum required SDM with the highest worth control rod stuck fully withdrawn (Ref. 7).
The power density at any point in the core must be limited to maintain the fuel design criteria (Refs. 4 and 5). This is accomplished by maintaining the power distribution and reactor coolant conditions so that the peak LHR and DNB parameters are within operating limits supported by the accident analyses (Ref. 1) with due regard for the correlations between measured quantities, the power distribution, and uncertainties in determining the power distribution.

Fuel cladding failure during a LOCA is limited by restricting the maximum linear heat generation rate so that the peak cladding temperature does not exceed 1,204°C (2,200°F) (Ref. 5). Peak cladding temperatures exceeding 1,204°C (2,200°F) cause severe cladding failure by oxidation due to a Zirconium alloy water reaction.

The LCOs governing the LHR, ASI, and RCS ensure that these criteria are met as long as the core is operated within the \( F_{xy} \) and ASI limits specified in LCOs 3.2.2 and 3.2.5, and the COLR, and within the \( T_q \) limits specified in LCO 3.2.3. The latter are process variables that characterize the three dimensional power distribution of the reactor core. Operation within the limits for these variables ensures that their actual values are within the ranges used in the accident analyses.

Fuel cladding damage does not occur from conditions outside the limits of these LCOs during normal operation. However, fuel cladding damage could result if an accident occurs from initial conditions outside the limits of these LCOs.

This potential for fuel cladding damage exists because changes in the power distribution can cause increased power peaking and can correspondingly increase local LHR.

The LHR satisfies Criterion 2 of 10 CFR 50.36(c)(2)(ii).

The power distribution LCO limits are based on correlations between power peaking and certain measured variables used as inputs to the LHR and DNB operating limits. The power distribution LCO limits are provided in the COLR. The limitation on LHR ensures that in the event of a LOCA, the peak temperature of the fuel cladding does not exceed 1,204°C (2,200°F).
Power distribution is a concern any time the reactor is critical. The power distribution LCOs, however, are only applicable in MODE 1 above 20% RTP. The reasons these LCOs are not applicable below 20% RTP are:

a. The incore neutron detectors that provide input to the COLSS, which then calculates the operating limits, are inaccurate due to the poor signal to noise ratios at relatively low core power levels.

b. As a result of this inaccuracy, the CPCs assume minimum core power of 20% RTP when generating LPD and DNBR trip signals. When core power is below 20% RTP, the core is operating well below its thermal limits and the resultant CPC calculated LPD and DNBR trips are highly conservative.

Operation at or below the COLSS calculated power limit based on the LHR ensures that the LHR limit is not exceeded.

If the COLSS calculated core power limit based on the LHR exceeds the operating limit, restoring the LHR to within limit in 1 hour ensures that prompt action is taken to reduce LHR to below the specified limit. One hour is a reasonable time to return LHR to within limits when the limit is exceeded without a trip due to events such as a dropped CEA or an axial xenon oscillation.

If the COLSS is not available, the OPERABLE LPD channels are monitored to ensure that the LHR limit is not exceeded. Operation within this limit ensures that in the event of a LOCA, the fuel cladding temperature does not exceed 1,204°C (2,200°F). Four hours is allowed for restoring the LHR limit to within the region of acceptable operation. This duration is reasonable because the COLSS allows the plant to operate with less LHR margin (closer to the LHR limit than when monitoring the CPCs).
When operating with the COLSS out of service and LHR not within the region of acceptable operation, there is a possibility of a slow undetectable transient that degrades the LHR slowly over the 4 hour period and is then followed by an AOO or an accident. To remedy this, the CPC calculated values of LHR are monitored every 15 minutes when the COLSS is out of service and the LHR is not within the region of acceptable operation. The 15 minute Frequency is adequate to allow the operator to identify an adverse trend in conditions that could result in an approach to the LHR limit.

Also, a maximum allowable change in the CPC calculated LHR ensures that further degradation requires the operators to take immediate action to restore LHR to within limit or reduce reactor power to comply with the Technical Specifications (TS).

With an adverse trend, one hour is allowed for restoring LHR to within limit if the COLSS is not restored to OPERABLE status.

Implementation of this requirement ensures that reductions in core thermal margin are quickly detected, and if necessary, results in a decrease in reactor power and subsequent compliance with the existing COLSS out of service TS limits.

With no adverse trend, 4 hours is allowed to restore the LHR to within limit if the COLSS is not restored to OPERABLE status. This duration is reasonable because the Frequency of the CPC determination of LHR is increased and if operation is maintained steady, the likelihood of exceeding the LHR limit during this period is not increased. The likelihood of induced reactor transients from an early power reduction is also decreased.

C.1

If the LHR cannot be returned to within its limit or the LHR cannot be determined because of the COLSS and CPC inoperability, core power must be reduced. Reduction of core power to < 20% RTP ensures that the core is operating within its thermal limits and places the core in a conservative condition based on the trip setpoints generated by the CPCs, which assume a minimum core power of 20% RTP. The allowed Completion Time of 6 hours is reasonable, based on operating experience, to reach 20% RTP in an orderly manner and without challenging plant systems.
BASES

SURVEILLANCE REQUIREMENTS

SR 3.2.1.1

With the COLSS out of service, the operator must monitor the LHR with any OPERABLE local power density channel.

A 2 hour Frequency is sufficient to allow the operator to identify trends that would result in an approach to the LHR limits.

This SR is modified by a Note that states that the SR is applicable only when the COLSS is out of service. Continuous monitoring of the LHR is provided by the COLSS, which calculates core power and core power operating limits based on the LHR and continuously displays these limits to the operator. A COLSS margin alarm is annunciated in the event that the THERMAL POWER exceeds the core power operating limit based on LHR.

SR 3.2.1.2

Verification that the COLSS margin alarm actuates at a THERMAL POWER level equal to or less than the core power operating limit based on the LHR (W/cm) ensures the operator is alerted when conditions approach the LHR operating limit.

The 31 day Frequency for performance of this SR is consistent with the historical testing Frequency of Reactor Monitoring Systems.

REFERENCES

1. FSAR, Chapter 15.
2. FSAR, Chapter 6.
5. 10 CFR 50.46.
B 3.2 POWER DISTRIBUTION LIMITS

B 3.2.2 Planar Radial Peaking Factors (F_{xy})

BASES

BACKGROUND

The purpose of this LCO is to limit the core power distribution to the initial values assumed in the accident analyses. Operation within the limits imposed by this LCO limits or prevents potential fuel cladding failures that could breach the primary fission product barrier and release fission products to the reactor coolant in the event of a loss of coolant accident (LOCA), loss of flow accident, ejected control element assembly (CEA) accident, or other postulated accidents requiring termination by a Reactor Protection System (RPS) trip function. This LCO limits the damage to the fuel cladding during an accident by ensuring that the plant is operating within acceptable bounding conditions at the onset of a transient.

Methods of controlling the power distribution include:

a. Using full or part strength CEAs to alter the axial power distribution;

b. Decreasing CEA insertion by boration, thereby improving the radial power distribution; and

c. Correcting off optimum conditions (e.g., a CEA drop or misoperation of the unit) that cause margin degradations.

The core power distribution is controlled so that, in conjunction with other core operating parameters (e.g., CEA insertion and alignment limits), the power distribution does not result in violation of this LCO. The limiting safety system settings (LSSS) and this LCO are based on the accident analyses (Refs. 1 and 2), so that specified acceptable fuel design limits (SAFDLs) are not exceeded as a result of anticipated operational occurrences (AOOs), and the limits of acceptable consequences are not exceeded for other postulated accidents.

Limiting power distribution skewing over time also minimizes xenon distribution skewing, which is a significant factor in controlling the axial power distribution.

Power distribution is a product of multiple parameters, various combinations of which may produce acceptable power distributions. Operation within the design limits of power distribution is accomplished by generating operating limits on the linear heat rate (LHR) and departure from nucleate boiling (DNB).
Proximity to the DNB condition is expressed by the departure from nucleate boiling ratio (DNBR), defined as the ratio of the cladding surface heat flux required to cause DNB to the actual cladding surface heat flux. The minimum DNBR value during both normal operation and AOOs is calculated by the KCE-1 Correlation (Ref. 3) and corrected for such factors as rod bow and grid spacers. It is accepted as an appropriate margin to DNB for all operating conditions.

There are two systems that monitor core power distribution online: the Core Operating Limit Supervisory System (COLSS) and the core protection calculators (CPCs). The COLSS and CPCs that monitor the core power distribution are capable of verifying that the LHR and the DNBR do not exceed their limits. The COLSS performs this function by continuously monitoring the core power distribution and calculating core power operating limits corresponding to the allowable peak LHR and DNBR. The CPCs perform this function by continuously calculating an actual value of DNBR and local power density (LPD) for comparison with the respective trip setpoints.

DNBR penalty factors are included in both the COLSS and CPC DNBR calculations to accommodate the effects of rod bow. The amount of rod bow in each assembly is dependent upon the average burnup experienced by that assembly. Fuel assemblies that incur higher than average burnup experience a greater magnitude of rod bow. Conversely, fuel assemblies that receive lower than average burnup experience less rod bow. In design calculations for a reload core, each batch of fuel is assigned a penalty applied to the maximum integrated planar radial power peak of the batch. This penalty is correlated with the amount of rod bow determined from the maximum average assembly burnup of the batch. A single net penalty for the COLSS and CPCs is then determined from the penalties associated with each batch that comprises a core reload, accounting for the offsetting margins due to the lower radial power peaks in the higher burnup batches.

The COLSS indicates continuously to the operator how near the core is to the operating limits and provides an audible alarm if an operating limit is exceeded. Such a condition signifies a reduction in the capability of the plant to withstand an anticipated transient, but does not necessarily imply an immediate violation of fuel design limits. If the margin to fuel design limits continues to decrease, the RPS ensures that the SAFDLs are not exceeded during AOOs by initiating reactor trips.
BACKGROUND (continued)

The COLSS continually generates an assessment of the calculated margin for specified LHR and DNBR limits. The data required for these assessments include measured incore neutron flux, CEA positions, and Reactor Coolant System (RCS) inlet temperature, pressure, and flow.

In addition to the monitoring performed by the COLSS, the RPS (via the CPCs) continually infers the core power distribution and thermal margins by processing reactor coolant data, signals from excore neutron flux detectors, and input from redundant reed switch assemblies that indicate CEA positions. In this case, the CPCs assume a minimum core power of 20% RTP because the Power Range Excore Neutron Flux Detecting System is inaccurate below this power level. If power distribution or other parameters are perturbed as a result of an AOO, the high LPD or low DNBR trips in the RPS initiate a reactor trip prior to exceeding the fuel design limits.

The LHR and DNBR algorithms are valid within the limits on ASI, planar radial peaking factors ($F_{xy}$), and $T_q$. These limits are obtained directly from initial core or reload analysis.

APPLICABLE SAFETY ANALYSES

The fuel cladding must not sustain damage as a result of normal operation or AOOs (Ref. 4).

The power distribution and CEA insertion and alignment LCOs prevent core power distributions from reaching levels that violate the following fuel design criteria:

a. During a LOCA, peak cladding temperature must not exceed 1,204°C (2,200°F) specified in the 10 CFR 50.46 (Ref. 5).

b. During a loss of flow accident, there must be at least 95% probability at the 95% confidence level (the 95/95 DNB criterion) that the hot fuel rod in the core does not experience a DNB condition (Ref. 4).

c. During an ejected CEA accident, the fission energy input to the fuel must not exceed 963 kJ/kg (230 cal/g) (Ref. 6).

d. The control rods must be capable of shutting down the reactor with a minimum required SDM with the highest worth control rod stuck fully withdrawn (Ref. 7).
The power density at any point in the core must be limited to maintain the fuel design criteria (Refs. 4 and 5). This is accomplished by maintaining the power distribution and reactor coolant conditions so that the peak LHR and DNB parameters are within operating limits supported by the accident analyses (Ref. 1) with due regard for the correlations between measured quantities, the power distribution, and uncertainties in determining the power distribution.

Fuel cladding failure during a LOCA is limited by restricting the maximum linear heat generation rate so that the peak cladding temperature does not exceed 1,204°C (2,200°F) (Ref. 5). Peak cladding temperatures exceeding 1,204°C (2,200°F) cause severe cladding failure by oxidation due to a Zirconium alloy water reaction.

The LCOs governing the LHR, ASI, and RCS ensure that these criteria are met as long as the core is operated within the F\textsubscript{xy} and ASI limits specified in LCOs 3.2.2 and 3.2.5, and the COLR, and within the T\textsubscript{q} limits specified in LCO 3.2.3. The latter are process variables that characterize the three dimensional power distribution of the reactor core. Operation within the limits for these variables ensures that their actual values are within the ranges used in the accident analyses.

Fuel cladding damage does not occur from conditions outside the limits of these LCOs during normal operation. However, fuel cladding damage could result if an accident occurs from initial conditions outside the limits of these LCOs. This potential for fuel cladding damage exists because changes in the power distribution can cause increased power peaking and can correspondingly increase local LHR.

F\textsubscript{xy} satisfies Criterion 2 of 10 CFR 50.36(c)(2)(ii).

The power distribution LCO limits are based on correlations between power peaking and certain measured variables used as inputs to the LHR and DNBR operating limits. The power distribution LCO limits are provided in Section 3.2 and the COLR.

Limiting of the calculated planar radial peaking factors (F\textsubscript{c}\textsubscript{xy}) used in the COLSS and CPCs to values equal to or greater than the measured planar radial peaking factors (F\textsubscript{M}\textsubscript{xy}) ensures that the limits calculated by the COLSS and CPCs remain valid.
APPLICABILITY

Power distribution is a concern any time the reactor is critical. The power distribution LCOs, however, are only applicable in MODE 1 above 20% RTP. The reasons these LCOs are not applicable below 20% RTP are:

- The incore neutron detectors that provide input to the COLSS, which then calculates the operating limits, are inaccurate due to the poor signal to noise ratios at relatively low core power levels.
- As a result of this inaccuracy, the CPCs assume minimum core power of 20% RTP when generating LPD and DNBR trip signals. When core power is below 20% RTP, the core is operating well below its thermal limits and the resultant CPC calculated LPD and DNBR trips are highly conservative.

ACTIONS

A.1.1 and A.1.2

When the $F_{xy}^M$ values exceed the $F_{xy}^C$ values used in the COLSS and CPCs, nonconservative operating limits and trip setpoints may be calculated. In this case, action must be taken to ensure that the COLSS operating limits and CPC trip setpoints remain valid with respect to the accident analysis. The operator can do this by performing the Required Actions A.1.1 and A.1.2. The 6 hour Completion Time provides the time required to calculate the required multipliers and make the necessary adjustments to the CPC addressable constants. During this period, the DNBR and LHR setpoints may be slightly nonconservative, but DNBR and LHR are still within limits. Therefore, 6 hours is an acceptable Completion Time to perform these actions considering the low probability of an accident occurring during this time period.

A.2

As an alternative to Required Actions A.1.1 and A.1.2, the operator may adjust the affected values of $F_{xy}^C$ used in the COLSS and CPCs to values greater than or equal to $F_{xy}^M$. The 6 hour Completion Time provides the time required to calculate the required multipliers and make the necessary adjustments to the CPC addressable constants. During this period, the DNBR and LHR setpoints may be slightly nonconservative, but DNBR and LHR are still within limits. Therefore, 6 hours is an acceptable Completion Time to perform these actions considering the low probability of an accident occurring during this time period.
BASES

ACTIONS (continued)

A.3

If Required Actions A.1.1 and A.1.2 or A.2 cannot be accomplished within 6 hours, the core power must be reduced. Reduction to 20% RTP or less ensures that the core is operating within the specified thermal limits and places the core in a conservative condition based on the trip setpoints generated by the COLSS and CPC operating limits.

These limits are established assuming a minimum core power of 20% RTP. Six hours is a reasonable time to reach 20% RTP in an orderly manner and without challenging plant systems.

SURVEILLANCE REQUIREMENTS

SR 3.2.2.1

This periodic Surveillance is for determining, using the Incore Detector System, that $F_{xy}^M$ values are less than or equal to $F_{xy}^C$ values used in the COLSS and CPCs. It ensures that the $F_{xy}^C$ values used remain valid throughout the fuel cycle. A Frequency of 31 effective full power days (EFPD) is acceptable because the power distribution changes only slightly with the amount of fuel burnup. Determining the $F_{xy}^M$ values after each fuel loading when THERMAL POWER is > 40% RTP, but prior to its exceeding 80% RTP, ensures that the core is properly loaded.

REFERENCES

1. FSAR, Chapter 15.

2. FSAR, Chapter 6.


5. 10 CFR 50.46.


B 3.2 POWER DISTRIBUTION LIMITS

B 3.2.3 AZIMUTHAL POWER TILT ($T_q$)

BACKGROUND

The purpose of this LCO is to limit the core power distribution to the initial values assumed in the accident analyses. Operation within the limits imposed by this LCO limits or prevents potential fuel cladding failures that could breach the primary fission product barrier and release fission products to the reactor coolant in the event of a loss of coolant accident (LOCA), loss of flow accident, ejected control element assembly (CEA) accident, or other postulated accidents requiring termination by a Reactor Protection System (RPS) trip function. This LCO limits the damage to the fuel cladding during an accident by ensuring that the plant is operating within acceptable bounding conditions at the onset of a transient.

Methods of controlling the power distribution include:

a. Using full or part strength CEAs to alter the axial power distribution;

b. Decreasing CEA insertion by boration, thereby improving the radial power distribution; and

c. Correcting off optimum conditions (e.g., a CEA drop, misoperation of the unit) that cause margin degradations.

The core power distribution is controlled so that, in conjunction with other core operating parameters (e.g., CEA insertion and alignment limits), the power distribution does not result in violation of this LCO. The limiting safety system settings (LSSS) and this LCO are based on the accident analyses (Refs. 1 and 2), so that specified acceptable fuel design limits (SAFDLs) are not exceeded as a result of anticipated operational occurrences (AOOs), and the limits of acceptable consequences are not exceeded for other postulated accidents.

Limiting power distribution skewing over time also minimizes xenon distribution skewing, which is a significant factor in controlling the axial power distribution.

Power distribution is a product of multiple parameters, various combinations of which may produce acceptable power distributions. Operation within the design limits of power distribution is accomplished by generating operating limits on the linear heat rate (LHR) and departure from nucleate boiling (DNB).
Proximity to the DNB condition is expressed by the departure from nucleate boiling ratio (DNBR), defined as the ratio of the cladding surface heat flux required to cause DNB to the actual cladding surface heat flux. The minimum DNBR value during both normal operation and AOOs is calculated by the KCE-1 Correlation (Ref. 3) and corrected for such factors as rod bow and grid spacers. It is accepted as an appropriate margin to DNB for all operating conditions.

There are two systems that monitor core power distribution online: the Core Operating Limit Supervisory System (COLSS) and the core protection calculators (CPCs). The COLSS and CPCs that monitor the core power distribution are capable of verifying that the LHR and the DNBR do not exceed their limits. The COLSS performs this function by continuously monitoring the core power distribution and calculating core power operating limits corresponding to the allowable peak LHR and DNBR. The CPCs perform this function by continuously calculating an actual value of DNBR and local power density (LPD) for comparison with the respective trip setpoints.

DNBR penalty factors are included in both the COLSS and CPC DNBR calculations to accommodate the effects of rod bow. The amount of rod bow in each assembly is dependent upon the average burnup experienced by that assembly. Fuel assemblies that incur higher than average burnup experience a greater magnitude of rod bow. Conversely, fuel assemblies that receive lower than average burnup experience less rod bow. In design calculations for a reload core, each batch of fuel is assigned a penalty applied to the maximum integrated planar radial power peak of the batch. This penalty is correlated with the amount of rod bow determined from the maximum average assembly burnup of the batch. A single net penalty for the COLSS and CPCs is then determined from the penalties associated with each batch that comprises a core reload, accounting for the offsetting margins due to the lower radial power peaks in the higher burnup batches.

The COLSS indicates continuously to the operator how far the core is from the operating limits and provides an audible alarm if an operating limit is exceeded. Such a condition signifies a reduction in the capability of the plant to withstand an anticipated transient, but does not necessarily imply an immediate violation of fuel design limits. If the margin to fuel design limits continues to decrease, the RPS ensures that the SAFDLs are not exceeded during AOOs by initiating reactor trips.
The COLSS continually generates an assessment of the calculated margin for specified LHR and DNBR limits. The data required for these assessments include measured incore neutron flux, CEA positions, and Reactor Coolant System (RCS) inlet temperature, pressure, and flow.

In addition to the monitoring performed by the COLSS, the RPS (via the CPCs) continually infers the core power distribution and thermal margins by processing reactor coolant data, signals from excore neutron flux detectors, and input from redundant reed switch assemblies that indicate CEA positions. In this case, the CPCs assume a minimum core power of 20% RTP because the Power Range Excore Neutron Flux Detecting System is inaccurate below this power level. If power distribution or other parameters are perturbed as a result of an AOO, the high LPD or low DNBR trips in the RPS initiate a reactor trip prior to exceeding the fuel design limits.

The LHR and DNBR algorithms are valid within the limits on ASI, planar radial peaking factors ($F_{xy}$), and $T_q$. These limits are obtained directly from initial core or reload analysis.

**APPLICABLE SAFETY ANALYSES**

The fuel cladding must not sustain damage as a result of normal operation or AOOs (Ref. 4).

The power distribution and CEA insertion and alignment LCOs prevent core power distributions from reaching levels that violate the following fuel design criteria:

a. During a LOCA, peak cladding temperature must not exceed 1,204°C (2,200°F) specified in the 10 CFR 50.46 (Ref. 5).

b. During a loss of flow accident, there must be at least 95% probability at the 95% confidence level (the 95/95 DNB criterion) that the hot fuel rod in the core does not experience a DNB condition (Ref. 4).

c. During an ejected CEA accident, the fission energy input to the fuel must not exceed 963 kJ/kg (230 cal/g) (Ref. 6).

d. The control rods must be capable of shutting down the reactor with a minimum required SDM with the highest worth control rod stuck fully withdrawn (Ref. 7).
APPLICABLE SAFETY ANALYSES (continued)

The power density at any point in the core must be limited to maintain the fuel design criteria (Refs. 4 and 5). This is accomplished by maintaining the power distribution and reactor coolant conditions so that the peak LHR and DNB parameters are within operating limits supported by the accident analyses (Ref. 1) with due regard for the correlations between measured quantities, the power distribution, and uncertainties in determining the power distribution.

Fuel cladding failure during a LOCA is limited by restricting the maximum linear heat generation rate so that the peak cladding temperature does not exceed 1,204°C (2,200°F) (Ref. 5). Peak cladding temperatures exceeding 1,204°C (2,200°F) cause severe cladding failure by oxidation due to a Zirconium alloy water reaction.

The LCOs governing the LHR, ASI, and RCS ensure that these criteria are met as long as the core is operated within the $F_{xy}$ and ASI limits specified in LCOs 3.2.2 and 3.2.5, and the COLR, and within the $T_q$ limits specified in LCO 3.2.3. The latter are process variables that characterize the three dimensional power distribution of the reactor core. Operation within the limits for these variables ensures that their actual values are within the ranges used in the accident analyses.

Fuel cladding damage does not occur from conditions outside the limits of these LCOs during normal operation. However, fuel cladding damage could result if an accident occurs from initial conditions outside the limits of these LCOs. This potential for fuel cladding damage exists because changes in the power distribution can cause increased power peaking and can correspondingly increase local LHR.

$T_q$ satisfies Criterion 2 of 10 CFR 50.36(c)(2)(ii).

LCO

The power distribution LCO limits are based on correlations between power peaking and certain measured variables used as inputs to the LHR and DNBR operating limits. The power distribution LCO limits are provided in Section 3.2 and the COLR.

The limitations on the $T_q$ are provided to ensure that design operating margins are maintained. $T_q > 0.10$ is not expected. If it occurs, the actions to be taken ensure that operation is restricted to only those conditions required to identify the cause of the tilt. It is necessary to explicitly account for power asymmetries because the radial peaking factors used in the core power distribution calculations are based on an untilted power distribution.
Power distribution is a concern any time the reactor is critical. The power distribution LCOs, however, are only applicable in MODE 1 above 20% RTP. The reasons these LCOs are not applicable below 20% RTP are:

a. The incore neutron detectors that provide input to the COLSS, which then calculates the operating limits, are inaccurate due to the poor signal to noise ratios at relatively low core power levels.

b. As a result of this inaccuracy, the CPCs assume minimum core power of 20% RTP when generating LPD and DNBR trip signals. When core power is below 20% RTP, the core is operating well below its thermal limits and the resultant CPC calculated LPD and DNBR trips are highly conservative.

If the measured \( T_q \) is greater than the \( T_q \) allowance used in the CPCs but \( \leq 0.1 \), non-conservative trip setpoints may be calculated. Required Action A.1 restores \( T_q \) to within its specified limits by repositioning the CEAs, and the reactor may return to normal operation. A Completion Time of 2 hours is sufficient time to allow the operator to reposition the CEAs because significant radial xenon redistribution does not occur within this time.

If the \( T_q \) cannot be restored within 2 hours, the \( T_q \) allowance in the CPCs must be adjusted, per Required Action A.2, to be equal to or greater than the measured value of \( T_q \) to ensure that the design safety margins are maintained.

Required Actions B.1, B.2, and B.3 are modified by a Note that requires all subsequent actions be performed if power reduction commences prior to restoring \( T_q \leq 0.1 \). This requirement ensures that corrective action is taken before unrestricted power operation resumes.

If the measured \( T_q \) is > 0.1, THERMAL POWER is reduced to \( \leq 50\% \) RTP within 4 hours. The 4 hours allows enough time to take action to restore \( T_q \) prior to reducing power and limits the probability of operation with a power distribution out of limits. Such actions include performing SR 3.2.3.2, which provides a value of \( T_q \) that can be used in subsequent actions.
Also in the case of a tilt generated by a CEA misalignment, the 4 hours allows recovery of the CEA misalignment because a measured $T_q > 0.1$ is not expected. If it occurs, continued operation of the reactor could be necessary to discover the cause of the tilt. Operation then is restricted to only those conditions required to identify the cause of the tilt. It is necessary to explicitly account for power asymmetries because the radial power peaking factors used in the core power distribution calculation are based on an untilted power distribution.

If the measured $T_q$ is not restored to within its specified limits, the reactor continues to operate with an axial power distribution mismatch. Continued operation in this configuration can induce an axial xenon oscillation, which results in increased linear heat generation rates when the xenon redistributes. If the measured $T_q$ cannot be restored to within its limit within 4 hours, reactor power must be reduced. Reducing THERMAL POWER to $<50\%$ RTP within 4 hours provides an acceptable level of protection from increased power peaking due to potential xenon redistribution while maintaining a power level sufficiently high enough to allow the tilt to be analyzed.

The variable overpower trip (VOPT) setpoints are reduced to $\leq 55\%$ RTP to ensure that the assumptions of the accident analysis regarding power peaking are maintained. After power has been reduced to $\leq 50\%$ RTP, the rate and magnitude of changes in the core flux are greatly reduced. Therefore, 8 hours is an acceptable time period to allow for reduction of the variable overpower trip setpoints, Required Action B.2. The 8 hour Completion Time allowed to reduce the variable overpower trip setpoints is required to perform the actions necessary to reset the trip setpoints.

THERMAL POWER is restricted to 50% RTP until the measured $T_q$ is restored to within its specified limit by correcting the out of limit condition. This action prevents the operator from increasing THERMAL POWER above the conservative limit when a significant $T_q$ has existed but allows the unit to continue operation for diagnostic purposes.

The Completion Time of Required Action B.3 is modified by a Note governing subsequent power increases. After a THERMAL POWER increase following restoration of $T_q$, operation may proceed provided the measured $T_q$ is determined to remain within its specified limit at the increased THERMAL POWER level.
The provision to allow discontinuation of the Surveillance after verifying that \( T_q \leq 0.1 \) at least once per hour for 12 hours or until \( T_q \) is verified to be within its specified limit at a THERMAL POWER \( \geq 95\% \) RTP provides an acceptable exit from this action after the measured \( T_q \) has been returned to an acceptable value.

C.1

If the measured \( T_q \) cannot be restored or determined within its specified limit, core power must be reduced. Reduction of core power to \(< 20\% \) RTP ensures that the core is operating within its thermal limits and places the core in a conservative condition based on the trip setpoints generated by the CPCs, which assume a minimum core power of 20\% RTP. Six hours is a reasonable time to reach 20\% RTP in an orderly manner and without challenging plant systems.

SURVEILLANCE REQUIREMENTS

SR 3.2.3.1

Continuous monitoring of the measured \( T_q \) by the in-core nuclear detectors is provided by the COLSS. A COLSS alarm is annunciated in the event that the measured \( T_q \) exceeds the value used in the CPCs.

With the COLSS out of service, the operator must calculate \( T_q \) and verify that it is within its specified limits. The 12 hour Frequency is sufficient to identify slowly developing \( T_q \)'s before they exceed the limits of this LCO. Also, the 12 hour Frequency prevents significant xenon redistribution.

SR 3.2.3.2

Verification that the COLSS \( T_q \) alarm actuates at a value less than the value used in the CPCs ensures that the operator is alerted if \( T_q \) approaches its operating limit.

The 31 day Frequency for performance of this SR is consistent with the historical testing Frequency of Reactor Protection and Monitoring Systems.

SR 3.2.3.3

Independent confirmation of the validity of the COLSS calculated \( T_q \) ensures that the COLSS accurately identifies \( T_q \)'s. The 31 day Frequency for performance of this SR is consistent with the historical testing Frequency of Reactor Monitoring Systems.
BASES

REFERENCES

1. FSAR, Chapter 15.

2. FSAR, Chapter 6.


5. 10 CFR 50.46.


B 3.2 POWER DISTRIBUTION LIMITS

B 3.2.4 Departure from Nucleate Boiling Ratio (DNBR)

BASES

BACKGROUND The purpose of this LCO is to limit the core power distribution to the initial values assumed in the accident analyses. Operation within the limits imposed by this LCO limits or prevents potential fuel cladding failures that could breach the primary fission product barrier and release fission products to the reactor coolant in the event of a loss of coolant accident (LOCA), loss of flow accident, ejected control element assembly (CEA) accident, or other postulated accidents requiring termination by a Reactor Protection System (RPS) trip function. This LCO limits the damage to the fuel cladding during an accident by ensuring that the plant is operating within acceptable bounding conditions at the onset of a transient.

Methods of controlling the power distribution include:

a. Using full or part strength CEAs to alter the axial power distribution;

b. Decreasing CEA insertion by boration, thereby improving the radial power distribution; and

c. Correcting off optimum conditions (e.g., a CEA drop, misoperation of the unit) that cause margin degradations.

The core power distribution is controlled so that, in conjunction with other core operating parameters (e.g., CEA insertion and alignment limits), the power distribution does not result in violation of this LCO. The limiting safety system settings (LSSS) and this LCO are based on the accident analyses (Refs. 1 and 2), so that specified acceptable fuel design limits (SAFDLs) are not exceeded as a result of anticipated operational occurrences (AOOs), and the limits of acceptable consequences are not exceeded for other postulated accidents.

Limiting power distribution skewing over time also minimizes xenon distribution skewing, which is a significant factor in controlling the axial power distribution. Power distribution is a product of multiple parameters, various combinations of which may produce acceptable power distributions. Operation within the design limits of power distribution is accomplished by generating operating limits on the linear heat rate (LHR) and departure from nucleate boiling (DNB).
Proximity to the DNB condition is expressed by the departure from nucleate boiling ratio (DNBR), defined as the ratio of the cladding surface heat flux required to cause DNB to the actual cladding surface heat flux. The minimum DNBR value during both normal operation and AOOs is calculated by the KCE-1 Correlation (Ref. 3) and corrected for such factors as rod bow and grid spacers. It is accepted as an appropriate margin to DNB for all operating conditions.

There are two systems that monitor core power distribution online: the Core Operating Limit Supervisory System (COLSS) and the core protection calculators (CPCs). The COLSS and CPCs that monitor the core power distribution are capable of verifying that the LHR and the DNBR do not exceed their limits. The COLSS performs this function by continuously monitoring the core power distribution and calculating core power operating limits corresponding to the allowable peak LHR and DNBR. The CPCs perform this function by continuously calculating an actual value of DNBR and local power density (LPD) for comparison with the respective trip setpoints.

DNBR penalty factors are included in both the COLSS and CPC DNBR calculations to accommodate the effects of rod bow. The amount of rod bow in each assembly is dependent upon the average burnup experienced by that assembly. Fuel assemblies that incur higher than average burnup experience a greater magnitude of rod bow. Conversely, fuel assemblies that receive lower than average burnup experience less rod bow. In design calculations for a reload core, each batch of fuel is assigned a penalty applied to the maximum integrated planar radial power peak of the batch. This penalty is correlated with the amount of rod bow determined from the maximum average assembly burnup of the batch. A single net penalty for the COLSS and CPCs is then determined from the penalties associated with each batch that comprises a core reload, accounting for the offsetting margins due to the lower radial power peaks in the higher burnup batches.

The COLSS indicates continuously to the operator how far the core is from the operating limits and provides an audible alarm if an operating limit is exceeded.

Such a condition signifies a reduction in the capability of the plant to withstand an anticipated transient, but does not necessarily imply an immediate violation of fuel design limits. If the margin to fuel design limits continues to decrease, the RPS ensures that the SAFDLs are not exceeded during AOOs by initiating reactor trips.
BACKGROUND (continued)

The COLSS continually generates an assessment of the calculated margin for specified LHR and DNBR limits. The data required for these assessments include measured incore neutron flux, CEA positions, and Reactor Coolant System (RCS) inlet temperature, pressure, and flow.

In addition to the monitoring performed by the COLSS, the RPS (via the CPCs) continually infers the core power distribution and thermal margins by processing reactor coolant data, signals from excore neutron flux detectors, and input from redundant reed switch assemblies that indicate CEA positions. In this case, the CPCs assume a minimum core power of 20% RTP because the Power Range Excore Neutron Flux Detecting System is inaccurate below this power level. If power distribution or other parameters are perturbed as a result of an AOO, the high LPD or low DNBR trips in the RPS initiate a reactor trip prior to exceeding the fuel design limits.

The LHR and DNBR algorithms are valid within the limits on ASI, planar radial peaking factors ($F_{xy}$), and $T_q$. These limits are obtained directly from initial core or reload analysis.

APPLICABLE SAFETY ANALYSES

The fuel cladding must not sustain damage as a result of normal operation or AOOs (Ref. 4).

The power distribution and CEA insertion and alignment LCOs prevent core power distributions from reaching levels that violate the following fuel design criteria:

a. During a LOCA, peak cladding temperature must not exceed 1,204°C (2,200°F) specified in the 10 CFR 50.46 (Ref. 5).

b. During a loss of flow accident, there must be at least 95% probability at the 95% confidence level (the 95/95 DNB criterion) that the hot fuel rod in the core does not experience a DNB condition (Ref. 4).

c. During an ejected CEA accident, the fission energy input to the fuel must not exceed 963 kJ/kg (230 cal/g) (Ref. 6).

d. The control rods must be capable of shutting down the reactor with a minimum required SDM with the highest worth control rod stuck fully withdrawn (Ref. 7).
APPLICABLE SAFETY ANALYSES (continued)

The power density at any point in the core must be limited to maintain the fuel design criteria (Refs. 4 and 5). This is accomplished by maintaining the power distribution and reactor coolant conditions so that the peak LHR and DNB parameters are within operating limits supported by the accident analyses (Ref. 1) with due regard for the correlations between measured quantities, the power distribution, and uncertainties in determining the power distribution.

Fuel cladding failure during a LOCA is limited by restricting the maximum linear heat generation rate so that the peak cladding temperature does not exceed 1,204°C (2,200°F) (Ref. 5). Peak cladding temperatures exceeding 1,204°C (2,200°F) cause severe cladding failure by oxidation due to a Zirconium alloy water reaction.

The LCOs governing the LHR, ASI, and RCS ensure that these criteria are met as long as the core is operated within the $F_{xy}$ and ASI limits specified in LCOs 3.2.2 and 3.2.5, and the COLR, and within the $T_q$ limits specified in LCO 3.2.3. The latter are process variables that characterize the three dimensional power distribution of the reactor core. Operation within the limits for these variables ensures that their actual values are within the ranges used in the accident analyses.

Fuel cladding damage does not occur from conditions outside the limits of these LCOs during normal operation. However, fuel cladding damage could result if an accident occurs from initial conditions outside the limits of these LCOs.

This potential for fuel cladding damage exists because changes in the power distribution can cause increased power peaking and can correspondingly increase local LHR.

DNBR satisfies Criterion 2 of 10 CFR 50.36(c)(2)(ii).

LCO

The power distribution LCO limits are based on correlations between power peaking and certain measured variables used as inputs to the LHR and DNBR operating limits. The power distribution LCO limits are provided in Section 3.2 and the COLR.

With the COLSS in service and at least one of the control element assembly calculators (CEACs) OPERABLE in each OPERABLE CPC channel, the DNBR will be maintained by ensuring that the core power calculated by the COLSS is equal to or less than the permissible core power operating limit based on DNBR calculated by the COLSS. In the
event that the COLSS is in service but neither of the two CEACs is OPERABLE in each OPERABLE CPC channel, the DNBR is maintained by ensuring that the core power calculated by the COLSS is equal to or less than a reduced value of the permissible core power operating limit calculated by the COLSS. In this condition, the calculated operating limit must be reduced by the allowance specified in the COLR as shown in Figure 3.2.4-1.

In instances for which the COLSS is out of service and at least one of the CEACs is OPERABLE in each OPERABLE CPC channel, the DNBR is maintained by operating within the acceptable region specified in the COLR as shown in Figure 3.2.4-2, in the COLR, and using any OPERABLE CPC channel. Alternatively, when the COLSS is out of service and neither of the two CEACs is OPERABLE, the DNBR is maintained by operating within the acceptable region specified in the COLR for this condition as shown in Figure 3.2.4-3, in the COLR, and using any OPERABLE CPC channel with two inoperable CEACs.

With the COLSS out of service, the limitation on DNBR as a function of the ASI represents a conservative envelope of operating conditions consistent with the analysis assumptions that have been analytically demonstrated adequate to maintain an acceptable minimum DNBR for all AOOs. Of these, the postulated loss of flow transient is the most limiting. Operation of the core with a DNBR at or above this limit ensures that an acceptable minimum DNBR is maintained in the event of a loss of flow transient.

**APPLICABILITY**

Power distribution is a concern any time the reactor is critical. The power distribution LCOs, however, are only applicable in MODE 1 above 20% RTP. The reasons these LCOs are not applicable below 20% RTP are:

a. The incore neutron detectors that provide input to the COLSS, which then calculates the operating limits, are inaccurate due to the poor signal to noise ratios at relatively low core power levels.

b. As a result of this inaccuracy, the CPCs assume minimum core power of 20% RTP when generating LPD and DNBR trip signals. When core power is below 20% RTP, the core is operating well below its thermal limits and the resultant CPC calculated LPD and DNBR trips are highly conservative.
A.1

Operating at or above the minimum required value of the DNBR ensures that an acceptable minimum DNBR is maintained in the event of a postulated loss of flow transient. If the core power as calculated by the COLSS exceeds the core power limit calculated by the COLSS based on the DNBR, fuel design limits might not be maintained following a loss of flow, and prompt action must be taken to restore the DNBR above its minimum allowable value. With the COLSS in service, the allowed Completion Time of 1 hour is a reasonable time for the operator to initiate corrective actions to restore the DNBR above its specified limit, because of the low probability of a severe transient occurring in this relatively short time.

B.1 and B.2.1 and B.2.2

If the COLSS is not available the OPERABLE DNBR channels are monitored to ensure that the DNBR is not exceeded. Maintaining the DNBR within this specified range ensures that no postulated accident results in consequences more severe than those described in Chapter 15 of the FSAR. A 4 hour Frequency is allowed to restore the DNBR limit to within the region of acceptable operation. This Frequency is reasonable because the COLSS allows the plant to operate with less DNBR margin (closer to the DNBR limit) than when monitoring with the CPCs.

When operating with the COLSS out of service and DNBR outside the region of acceptable operation, there is a possibility of a slow undetectable transient that degrades the DNBR slowly over the 4 hour period and is then followed by an AOO or an accident.

To remedy this, the CPC calculated values of DNBR are monitored every 15 minutes when the COLSS is out of service and DNBR outside the region of acceptable operation. The 15 minute Frequency is adequate to allow the operator to identify an adverse trend in conditions that could result in an approach to the DNBR limit. Also, a maximum allowable change in the CPC calculated DNBR ensures that further degradation requires the operators to take immediate action to restore DNBR to within limit or reduce reactor power to comply with the Technical Specifications (TS). With an adverse trend, one hour is allowed for restoring DNBR to within limit if the COLSS is not restored to OPERABLE status. Implementation of this requirement ensures that potential reductions in core thermal margin are quickly detected and, if necessary, cause a decrease in reactor power and subsequent compliance with the existing COLSS out of service TS limits. If DNBR cannot be monitored every 15 minutes, assume that there is an adverse trend.
Bases

Actions (continued)

With no adverse trend, 4 hours is allowed for restoring the DNBR to within limits if the COLSS is not restored to OPERABLE status. This duration is reasonable because the Frequency of the CPC determination of DNBR has been increased, and, if operation is maintained steady, the likelihood of exceeding the DNBR limit is not increased. The likelihood of induced reactor transients from an early power reduction is also decreased.

C.1

If the DNBR cannot be restored or determined within the allowed times of Conditions A and B, core power must be reduced. Reduction of core power to $< 20\%$ RTP ensures that the core is operating within its thermal limits and places the core in a conservative condition based on trip setpoints generated by the CPCs, which assume a minimum core power of $20\%$ RTP. The allowed Completion Time of 6 hours is reasonable, based on operating experience, to reach $20\%$ RTP from full power conditions in an orderly manner and without challenging plant systems.

Surveillance Requirements

SR 3.2.4.1

With the COLSS out of service, the operator must monitor the DNBR as indicated on any of the OPERABLE DNBR CHANNELS of the CPCs to verify that the DNBR is within the specified limits in Figure 3.2.4-2 or 3.2.4-3 of the COLR, as applicable. A 2 hour Frequency is adequate to allow the operator to identify trends in conditions that would result in an approach to the DNBR limit.

This SR is modified by a Note that states that the SR is only applicable when the COLSS is out of service. Continuous monitoring of the DNBR is provided by the COLSS, which calculates core power and core power operating limits based on the DNBR and continuously displays these limits to the operator. A COLSS margin alarm is annunciated in the event that the THERMAL POWER exceeds the core power operating limit based on the DNBR.

SR 3.2.4.2

Verification that the COLSS margin alarm actuates at a power level equal to or less than the core power operating limit, as calculated by the COLSS, based on the DNBR, ensures that the operator is alerted when operating conditions approach the DNBR operating limit. The 31 day Frequency for performance of this SR is consistent with the historical testing Frequency of Reactor Monitoring Systems.
REFERENCES

1. FSAR, Chapter 15.

2. FSAR, Chapter 6.


5. 10 CFR 50.46.


B 3.2 POWER DISTRIBUTION LIMITS

B 3.2.5 AXIAL SHAPE INDEX (ASI)

BASES

BACKGROUND

The purpose of this LCO is to limit the core power distribution to the initial values assumed in the accident analyses. Operation within the limits imposed by this LCO limits or prevents potential fuel cladding failures that could breach the primary fission product barrier and release fission products to the reactor coolant in the event of a loss of coolant accident (LOCA), loss of flow accident, ejected control element assembly (CEA) accident, or other postulated accidents requiring termination by a Reactor Protection System (RPS) trip function. This LCO limits the damage to the fuel cladding during an accident by ensuring that the plant is operating within acceptable bounding conditions at the onset of a transient.

Methods of controlling the power distribution include:

a. Using full or part strength CEAs to alter the axial power distribution;

b. Decreasing CEA insertion by boration, thereby improving the radial power distribution; and

c. Correcting off optimum conditions (e.g., a CEA drop, misoperation of the unit) that cause margin degradations.

The core power distribution is controlled so that, in conjunction with other core operating parameters (e.g., CEA insertion and alignment limits), the power distribution does not result in violation of this LCO. The limiting safety system settings (LSSS) and this LCO are based on the accident analyses (Refs. 1 and 2), so that specified acceptable fuel design limits (SAFDLs) are not exceeded as a result of anticipated operational occurrences (AOOs), and the limits of acceptable consequences are not exceeded for other postulated accidents.

Minimizing power distribution skewing over time also minimizes xenon distribution skewing, which is a significant factor in controlling the axial power distribution.

Power distribution is a product of multiple parameters, various combinations of which may produce acceptable power distributions. Operation within the design limits of power distribution is accomplished by generating operating limits on the linear heat rate (LHR) and departure from nucleate boiling (DNB).
Proximity to the DNB condition is expressed by the departure from nucleate boiling ratio (DNBR), defined as the ratio of the cladding surface heat flux required to cause DNB to the actual cladding surface heat flux. The minimum DNBR value during both normal operation and AOOs is calculated by the KCE-1 Correlation (Ref. 3) and corrected for such factors as rod bow and grid spacers. It is accepted as an appropriate margin to DNB for all operating conditions.

There are two systems that monitor core power distribution online: the Core Operating Limit Supervisory System (COLSS) and the core protection calculators (CPCs). The COLSS and CPCs that monitor the core power distribution are capable of verifying that the LHR and the DNBR do not exceed their limits. The COLSS performs this function by continuously monitoring the core power distribution and calculating core power operating limits corresponding to the allowable peak LHR and DNBR. The CPCs perform this function by continuously calculating an actual value of DNBR and local power density (LPD) for comparison with the respective trip setpoints.

DNBR penalty factors are included in both the COLSS and CPC DNBR calculations to accommodate the effects of rod bow. The amount of rod bow in each assembly is dependent upon the average burnup experienced by that assembly. Fuel assemblies that incur higher than average burnup experience a greater magnitude of rod bow. Conversely, fuel assemblies that receive lower than average burnup experience less rod bow. In design calculations for a reload core, each batch of fuel is assigned a penalty applied to the maximum integrated planar radial power peak of the batch. This penalty is correlated with the amount of rod bow determined from the maximum average assembly burnup of the batch. A single net penalty for the COLSS and CPCs is then determined from the penalties associated with each batch that comprises a core reload, accounting for the offsetting margins due to the lower radial power peaks in the higher burnup batches.

The COLSS indicates continuously to the operator how far the core is from the operating limits and provides an audible alarm if an operating limit is exceeded. Such a condition signifies a reduction in the capability of the plant to withstand an anticipated transient, but does not necessarily imply an immediate violation of fuel design limits. If the margin to fuel design limits continues to decrease, the RPS ensures that the SAFDLs are not exceeded during AOOs by initiating reactor trips.
The COLSS continually generates an assessment of the calculated margin for specified LHR and DNBR limits. The data required for these assessments include measured incore neutron flux, CEA positions, and Reactor Coolant System (RCS) inlet temperature, pressure, and flow.

In addition to the monitoring performed by the COLSS, the RPS (via the CPCs) continually infers the core power distribution and thermal margins by processing reactor coolant data, signals from excore neutron flux detectors, and input from redundant reed switch assemblies that indicate CEA positions. In this case, the CPCs assume a minimum core power of 20% RTP because the Power Range Excore Neutron Flux Detecting System is inaccurate below this power level. If power distribution or other parameters are perturbed as a result of an AOO, the high LPD or low DNBR trips in the RPS initiate a reactor trip prior to exceeding the fuel design limits.

The LHR and DNBR algorithms are valid within the limits on ASI, planar radial peaking factors ($F_{xy}$), and $T_q$. These limits are obtained directly from initial core or reload analysis.

**APPLICABLE SAFETY ANALYSES**

The fuel cladding must not sustain damage as a result of normal operation or AOOs (Ref. 4).

The power distribution and CEA insertion and alignment LCOs prevent core power distributions from reaching levels that violate the following fuel design criteria:

a. During a LOCA, peak cladding temperature must not exceed 1,204°C (2,200°F) specified in the 10 CFR 50.46 (Ref. 5).

b. During a loss of flow accident, there must be at least 95% probability at the 95% confidence level (the 95/95 DNB criterion) that the hot fuel rod in the core does not experience a DNB condition (Ref. 4).

c. During an ejected CEA accident, the fission energy input to the fuel must not exceed 963 kJ/kg (230 cal/g) (Ref. 6).

d. The control rods must be capable of shutting down the reactor with a minimum required SDM with the highest worth control rod stuck fully withdrawn (Ref. 7).
The power density at any point in the core must be limited to maintain the fuel design criteria (Refs. 4 and 5). This is accomplished by maintaining the power distribution and reactor coolant conditions so that the peak LHR and DNB parameters are within operating limits supported by the accident analyses (Ref. 1) with due regard for the correlations between measured quantities, the power distribution, and uncertainties in determining the power distribution.

Fuel cladding failure during a LOCA is limited by restricting the maximum linear heat generation rate so that the peak cladding temperature does not exceed 1,204°C (2,200°F) (Ref. 5). Peak cladding temperatures exceeding 1,204°C (2,200°F) cause severe cladding failure by oxidation due to a Zirconium alloy water reaction.

The LCOs governing the LHR, ASI, and RCS ensure that these criteria are met as long as the core is operated within the $F_{xy}$ and ASI limits specified in LCOs 3.2.2 and 3.2.5, and the COLR, and within the $T_q$ limits specified in LCO 3.2.3. The latter are process variables that characterize the three dimensional power distribution of the reactor core. Operation within the limits for these variables ensures that their actual values are within the ranges used in the accident analyses.

Fuel cladding damage does not occur from conditions outside the limits of these LCOs during normal operation. However, fuel cladding damage could result if an accident occurs from initial conditions outside the limits of these LCOs. This potential for fuel cladding damage exists because changes in the power distribution can cause increased power peaking and can correspondingly increase local LHR.

The ASI satisfies Criterion 2 of 10 CFR 50.36(c)(2)(ii).

The power distribution LCO limits are based on correlations between power peaking and certain measured variables used as inputs to the LHR and DNBR operating limits. The power distribution LCO limits are provided in Section 3.2 and the COLR.

The limitation on ASI ensures that the actual ASI value is maintained within the range of values used in the accident analysis. The ASI limits ensure that with $T_q$ at its maximum upper limit, the DNBR does not drop below the DNBR safety limit for AOOs.
BASES

APPLICABILITY

Power distribution is a concern any time the reactor is critical. The power distribution LCOs, however, are only applicable in MODE 1 above 20% RTP. The reasons these LCOs are not applicable below 20% RTP are:

a. The incore neutron detectors that provide input to the COLSS, which then calculates the operating limits, are inaccurate due to the poor signal to noise ratios at relatively low core power levels.

b. As a result of this inaccuracy, the CPCs assume minimum core power of 20% RTP when generating LPD and DNBR trip signals. When core power is below 20% RTP, the core is operating well below its thermal limits and the resultant CPC calculated LPD and DNBR trips are highly conservative.

ACTIONS

A.1

The ASI limits specified in the COLR ensure that the LOCA and loss of flow accident criteria assumed in the accident analyses remain valid. If the ASI exceeds its limit, a Completion Time of 2 hours is allowed to restore the ASI to within its specified limit. This duration gives the operator sufficient time to reposition the regulating or part strength CEAs to reduce the axial power imbalance. The magnitude of any potential xenon oscillation is significantly reduced if the condition is not allowed to persist for 2 hours.

B.1

If the ASI is not restored to within its specified limits within the required Completion Time, the reactor continues to operate with an axial power distribution mismatch. Continued operation in this configuration induces an axial xenon oscillation, and results in increased linear heat generation rates when the xenon redistributes. Reducing THERMAL POWER to ≤ 20% RTP reduces the maximum LHR to a value that does not exceed the fuel design limits if a design basis event occurs. The allowed Completion Time of 4 hours is reasonable, based on operating experience, to reduce power in an orderly manner and without challenging plant systems.
The ASI can be monitored by both the Incore (COLSS) and Excore (CPC) Neutron Detector Systems. The COLSS provides the operator with an alarm if an ASI limit is approached.

Verification of the ASI every 12 hours ensures that the operator is aware of changes in the ASI as they develop. A 12 hour Frequency for this Surveillance is acceptable because the mechanisms that affect the ASI, such as xenon redistribution or CEA drive mechanism malfunctions, cause slow changes in the ASI, which can be discovered before the limits are exceeded.

REFERENCES
1. FSAR, Chapter 15.
2. FSAR, Chapter 6.
5. 10 CFR 50.46.
B 3.3 INSTRUMENTATION

B 3.3.1 Reactor Protection System (RPS) Instrumentation – Operating

BASES

BACKGROUND The Reactor Protection System (RPS) initiates a reactor trip to protect against violating the core specified acceptable fuel design limits (SAFDLs) and breaching the reactor coolant pressure boundary (RCPB) during anticipated operational occurrences (AOOs). By tripping the reactor, the RPS also assists the Engineered Safety Features (ESF) Systems in mitigating accidents.

The Protection and Monitoring Systems have been designed to ensure safe operation of the reactor. This is achieved by specifying limiting safety system settings (LSSS) in terms of parameters directly monitored by the RPS, as well as LCOs on other reactor system parameters and equipment performance.

Technical Specifications are required by 10 CFR 50.36 (Ref. 1) to include LSSS for variables that have significant safety functions. LSSS are defined by the regulation as “Where a LSSS is specified for a variable on which a safety limit has been placed, the setting must be chosen so that automatic protective actions will correct the abnormal situation before a Safety Limit (SL) is exceeded.” The Analytical Limit is the limit of the process variable at which a safety action is initiated, as established by the safety analysis, to ensure that a SL is not exceeded. Any automatic protective action that occurs on reaching the Analytical Limit therefore ensures that the SL is not exceeded. However, in practice, the actual settings for automatic protection channels must be chosen to be more conservative than the Analytical Limit to account for channel uncertainties related to the setting at which automatic protective action would actually occur. The LSSS values are identified and maintained in a document required by Specification 5.5.19, Setpoint Control Program (SCP), which specifies that the changes to LSSS values (and related limits) shall be controlled by 10 CFR 50.59 and the Nuclear Regulatory Commission (NRC) approved setpoint methodology referenced in Specification 5.5.19 (the SCP). In conjunction with the LCOs, the LSSS establish the thresholds for protection system actuation to prevent exceeding acceptable limits during design basis events (DBEs).
The Nominal Trip Setpoint (NTSP) specified in the SCP is a predetermined setting for a protective channel chosen to ensure automatic actuation prior to the process variable reaching the Analytical Limit and thus ensuring that the SL would not be exceeded. As such, the NTSP accounts for uncertainties in setting the channel (e.g., calibration), uncertainties in how the channel might actually perform (e.g., repeatability), changes in the point of action of the channel over time (e.g., drift during surveillance intervals), and any other factors which may influence its actual performance (e.g., harsh accident environments). In this manner, the NTSP ensures that SLs are not exceeded. As such, the NTSP meets the definition of a LSSS (Ref. 1).

The NTSPs listed in the SCP are based on the NRC approved setpoint methodology referenced in the SCP, which incorporates all of the known uncertainties applicable for each channel. The magnitudes of these uncertainties are factored into the determination of each NTSP. All field sensors and signal processing equipment for these channels are assumed to operate within the allowances of these uncertainty magnitudes. Transmitter and signal processing equipment calibration tolerances and drift allowances must be specified in plant calibration procedures, and must be consistent with the values used in the setpoint methodology.

Technical Specifications contain values related to the OPERABILITY of equipment required for safe operation of the facility. OPERABLE is defined in Technical Specifications as “…being capable of performing its safety function(s).” Relying solely on the NTSP to define OPERABILITY in Technical Specifications would be an overly restrictive requirement if it were applied as an OPERABILITY limit for the “as-found” value of a protection channel setting during a Surveillance. This would result in Technical Specification compliance problems, as well as reports and corrective actions required by the rule which are not necessary to ensure safety. For example, an automatic protection channel device with a setting that has been found to be different from the NTSP due to some drift of the setting may still be OPERABLE because drift is to be expected. This expected drift would have been specifically accounted for in the setpoint methodology for calculating the NTSP and thus the automatic protective action would still have ensured that the SL would not be exceeded provided the “as-found” setting of the protection channel is within the as-found tolerance band. Therefore, the channel would still be OPERABLE because it would have performed its safety function and the only corrective action required would be to reset the channel within the established as-left tolerance around the NTSP to account for further drift during the next surveillance interval.
BACKGROUND (continued)

Note that, although the channel is OPERABLE under these circumstances, the trip setpoint must be left adjusted to a value within the as-left tolerance, in accordance with uncertainty assumptions stated in the referenced setpoint methodology (as-left criteria), and confirmed to be operating within the statistical allowances of the uncertainty terms assigned (as-found criteria).

However, there is also some point beyond which the channel may not be able to perform its function due to, for example, greater than expected drift. This value needs to be specified in the Technical Specifications in order to define OPERABILITY of the channels and is designated as the Allowable Value.

If the actual setting (as-found setpoint) of the channel is found to be conservative with respect to the Allowable Value but is beyond the as-found tolerance band, the channel is OPERABLE, but degraded. The degraded condition will be further evaluated during performance of the Surveillance. This evaluation will consist of resetting the channel setpoint to the NTSP (within the allowed tolerance), and evaluating the channel response. If the channel is functioning as required and is expected to pass the next surveillance, then the channel is OPERABLE and can be restored to service at the completion of the surveillance. After the surveillance is completed, the channel as-found condition will be entered into the Corrective Action Program for further evaluation.

During AOOs, which are those events expected to occur one or more times during the plant life, the acceptable limits are:

- a. The departure from nucleate boiling ratio (DNBR) shall be maintained above the SL value to prevent departure from nucleate boiling (DNB).

- b. Fuel centerline melting shall not occur.

- c. The Reactor Coolant System (RCS) pressure SL of 193.3 kg/cm²A (2,750 psia) shall not be exceeded.

Maintaining the parameters within the above values ensures that offsite dose will be within the 10 CFR Part 50, Appendix A, GDC 21 (Ref. 2) and 10 CFR 50.34 (Ref. 3) criteria during AOOs.
Accidents are events that are analyzed even though they are not expected to occur during the plant life. The acceptable limit during accidents is that the offsite dose shall be maintained within an acceptable fraction of 10 CFR 50.34 (Ref. 3) limits. Different accident categories allow a different fraction of these limits based on probability of occurrence. Meeting the acceptable dose limit for an accident category is considered having acceptable consequences for that event.

The Reactor Trip System (RTS) is a safety system which initiates reactor trips. The RTS consists of four channels of sensors, auxiliary process cabinet-safety (APC-S) cabinets, Excore Neutron Flux Monitoring System (ENFMS) cabinets, Core Protection Calculator System (CPCS) cabinets, the RPS portion of Plant Protection System (PPS) cabinets, and Reactor Trip Switchgear System (RTSS) cabinets.

The RPS function is performed through the below portions in the RTS:

a. Measurement channels – consist of the sensor and transmitter providing a process value to bistable logics.

b. Bistable logics – provide trip signal to RPS logic comparing the process value with predetermined setpoint. There are two bistable racks (including separate input and output modules, data links, one bistable processor, etc.) per channel.

c. RPS logic – provides trip signal to reactor trip circuit breakers (RTCBs) after performing 2/4 logic based on bistable trip status of four channels. There are two local coincidence logic racks (including separate input and output modules, data links, four local coincidence logic processors, etc.) per channel.

d. RTSS – opens RTCBs based on trip signal from RPS logic. Each RTCB has undervoltage trip equipment and shunt trip equipment. The PPS interfaces with the undervoltage trip device of the RTCBs. The DPS interfaces with the shunt trip device of the RTCBs.

This LCO addresses measurement channels and bistable trip logics and automatic operating bypass removal features for those trips with operating bypasses. The RPS logic and RTCBs are addressed in LCO 3.3.4, “Reactor Protection System (RPS) Logic and Trip Initiation.” The control element assembly calculators (CEACs) are addressed in LCO 3.3.3, “Control Element Assembly Calculators (CEACs).”
Measurement Channels

Measurement channels, consisting of the sensor, transmitter, and related instruments, provide a measurable signal based upon the physical characteristics of the parameter being measured. The excore nuclear instrumentation and the CPCS, though complex, are considered components in the measurement channels of the Variable Overpower – High, Logarithmic Power Level – High, DNBR – Low, and Local Power Density (LPD) – High trips.

Four identical measurement channels, designated channels A through D, with electrical and physical separation, are provided for each parameter used in the generation of trip signals, with the exception of the control element assembly (CEA) position indication used in the CPCS. Each measurement channel provides input to one or more RPS bistables within the same RPS channel. In addition, some measurement channels can be used as inputs to Engineered Safety Features Actuation System (ESFAS) bistables, and most provide indication in the main control room (MCR).

Measurement channels used as input of RPS meet the independence requirements from control signals.

When a channel monitoring a parameter exceeds a predetermined setpoint, indicating an unsafe condition, the bistable monitoring the parameter in that channel will trip. Tripping bistables monitoring the same parameter in two or more channels will de-energize local coincidence logic, which in turn de-energizes the initiation logic. This causes all eight RTCBs to open, interrupting power to the CEAs, allowing them to fall into the core.

Three of the four measurement channels and bistable logics channels are necessary to meet the redundancy and testability of 10 CFR Part 50, Appendix A, GDC 21 (Ref. 2). The fourth channel provides additional flexibility by allowing one channel to be removed from service (trip channel bypass) for maintenance or testing, while still maintaining a minimum 2-out-of-3 logic. Thus, even with a channel inoperable, no single additional failure in the RPS can either cause an inadvertent trip or prevent a required trip from occurring.

Adequate channel to channel independence includes physical and electrical independence of each channel from the others. This allows operation in 2-out-of-3 logic with one removed from service until following the next MODE 5 entry. Since no single failure will either cause or prevent a protection system actuation, this arrangement meets the requirements of IEEE Standard 603 (Ref. 4).
The CPCs perform the calculations required to derive the DNBR and LPD parameters and their associated RPS trips. Four separate CPCs perform the calculations independently, one for each of the four RPS channels. The CPCs provide pre-trip signals and trip signals for each of DNBR - Low and LPD – High, and transmit the result of calculation including DNBR margin, LPD margin, and calibrated neutron flux power level to Information Processing System (IPS) and Qualified Indication and Alarm System Non – Safety (QIAS-N). The CPC channel outputs for the DNBR – Low and LPD – High trips operate contacts in the coincidence logics in a manner identical to the other RPS trip.

Each CPC receives the following inputs:

a. Hot leg and cold leg temperatures;

b. Pressurizer pressure;

c. Reactor coolant pump speed;

d. Excore neutron flux levels;

e. Target CEA position; and

f. CEAC penalty factors.

Each CPC is programmed with “addressable constants.” These are various alignment values, correction factors, etc., that are required for the CPC computations. They can be accessed for display or for the purpose of changing them as necessary.

The CPCs use this constant and variable information to perform a number of calculations. These include the calculation of CEA group and subgroup deviations (and the assignment of conservative penalty factors), correction and calculation of average axial power distribution (APD) (based on excore flux levels and CEA positions), calculation of coolant flow (based on pump speed), and calculation of calibrated average power level (based on excore flux levels and ΔT power).

The DNBR calculation considers primary pressure, inlet temperature, coolant flow, average power, APD, radial peaking factors, and CEA deviation penalty factors from the CEACs to calculate the state of the limiting (hot) coolant channel in the core. A DNBR – Low trip occurs when the calculated value reaches the minimum DNBR trip setpoint.
The LPD calculation considers APD, average power, radial peaking factors (based upon target CEA position), and CEAC penalty factors to calculate the current value of compensated peak power density. An LPD – High trip occurs when the calculated value reaches the trip setpoint. The four CPC channels provide input to the four DNBR – Low and four LPD – High RPS trip channels. They effectively act as the sensor and bistable trip units (using many inputs) for these trips.

The CEACs perform the calculations required to determine the position of CEAs within their subgroups for the CPCs. Two independent CEACs, designated CEAC1 and CEAC2, within each CPC channel compare the position of each CEA to its subgroup position. If a deviation is detected by either CEAC, an annunciator sounds and appropriate “penalty factors” are transmitted to the CPC in the affected channel. These penalty factors conservatively adjust the effective operating margins to the DNBR – Low and LPD – High reactor trip setpoints.

Each CEA has two separate reed switch position transmitter (RSPT) assemblies mounted outside the RCPB, designated RSPT1 and RSPT2. CEA position from the RSPTs is processed by two CEA position processors (CPPs) located in each CPC channel. The CPPs transmit CEA position to the appropriate CEAC in each of the four CPC channels over optically isolated serial data links, such that CEAC1 in all channels receives the position of all CEAs based upon RSPT1, and CEAC2 receives the position of all CEAs based upon RSPT2. Thus the positions of all CEAs are independently monitored by both CEACs in each CPC channel.

The CPCs display the position of each CEA on the display of IPS to be monitored by the operator. Each CPC channel is connected to the display by means of an optically isolated data link. The operator can select the channel for display. Selecting channel A or B will display CEA position based upon RSPT1 on each CEA, whereas selecting channel C or D will display CEA position based upon RSPT2 on each CEA.

CEACs are addressed in LCO 3.3.3.
BACKGROUND (continued)

Bistable Logics

The bistable logic of Plant Protection System (PPS) cabinet receives analog inputs from measurement channels. The analog input signals are directed to analog input modules in the bistable processor rack, where the analog-digital (A/D) conversion is performed. The bistable logic algorithm determines the pre-trip and trip status. Each output status is determined comparing the digitized process value from the A/D converter with the setpoint (pre-trip and trip) from the setpoint algorithm. The status of bistable logic is provided to trip indication and remote alarm.

There are four bistable channels for each RPS parameter. The bistable channels are designated A, B, C and D per measurement channels. When a trip occurs, each bistable channel provides the trip output signal to associated local coincidence logic (LCL) channels. The trip outputs are provided to LCL channels in other channel via fiber optic link for isolation.

When two or more of the bistable trip signals monitoring same parameter are in a tripped condition, the coincidence logic (2-out-of-4 logic) generates a reactor trip signal.

Some measurement channels provide contact outputs to the PPS. These are DNBR – Low and LPD – High trips generated from CPCS.

The trip setpoints used in the bistables are based on the analytical limits derived from the accident analysis of FSAR (Ref. 5). The selection of these trip setpoints is such that adequate protection is provided when all sensor and processing time delays are taken into account. To allow for calibration tolerances, instrumentation uncertainties, instrument drift, and severe environment errors for those RPS channels that must function in harsh environments as defined by 10 CFR 50.49 (Ref. 6), Allowable Values specified in SCP, in the accompanying LCO, are conservatively adjusted with respect to the analytical limits. The nominal trip setpoint entered into the bistable is normally still more conservative than that specified by the Allowable Value to account for changes in random measurement errors detectable by a CHANNEL FUNCTIONAL TEST. One example of such a change in measurement error is drift during the interval between surveillances. A channel is inoperable if its actual setpoint is not within its Allowable Value.

Setpoints in accordance with the Allowable Value will ensure that SLs are not violated during AOOs and the consequences of design basis accidents (DBAs) will be acceptable, providing the plant is operated from within the LCOs at the onset of the AOO or DBA and the equipment functions as designed.
Note that in LCO 3.3.1, the Allowable Values of SCP are the LSSS.

Functional testing of the entire RPS, from bistable input through the opening of individual sets of RTCBs, can be performed either at power or shut down and is normally performed on a 31 day basis. Ex-core nuclear instrumentation, the CPCS, and the CEACs can be similarly tested. FSAR, Section 7.2 provides more detail on RPS testing. Processing transmitter calibration is normally performed on a refueling basis.

RPS Logic

The RPS Logic, addressed in LCO 3.3.4, consists of both local coincidence and initiation logic and employs a scheme that provides a reactor trip when bistables in any two of the four channels sense the same input parameter trip. This is called a 2-out-of-4 trip logic.

Each LCL receives four trip signals, one from its associated bistable logic in the channel and one from each of the equivalent bistable logic located in the other three channels. The LCL also receives the trip channel bypass status signals associated with each of the above mentioned bistables. The function of the LCL is to generate a coincidence signal whenever two or more like bistables are in a tripped condition. The LCL takes into consideration the trip bypass input state when determining the coincidence logic state. Designating the protection channels as A, B, C, and D, with no trip bypass present, the LCL will produce a coincidence signal for any of the following trip inputs: AB, AC, AD, BC, BD, CD, ABC, ABD, ACD, BCD, and ABCD. These represent all possible two or more trip combinations of the four protection channels. Should a trip bypass be present, the logic will provide a coincidence signal when two or more of the three un-bypassed bistables are in a tripped condition.

On a system basis, a coincidence signal is generated in all four protection channels whenever a coincidence of two or more like bistables of the four channels are in a tripped state.

In addition to a coincidence signal, each LCL also provides bypass status outputs. The bypass status is provided to verify that a bypass has actually been entered into the logic either locally or remotely via the maintenance and test panel or the operator's module.
The inputs to the initiation logic are the LCL outputs from the appropriate LCLs. The LCL outputs are arranged in the initiation circuit to provide 2-out-of-4 coincidence. This configuration will avoid spurious channel initiation in the event of a single LCL processor or digital output module failure. The RPS initiation logic consists of an “OR” circuit for each undervoltage and shunt trip relay and de-energizes interposing relays. Each interposing relay opens one RTCB in turn.

Each trip path is responsible for opening two of eight RTCBs. The PPS interfaces with the undervoltage trip device of RTSS breakers. The DPS interfaces with the shunt trip device of the RTSS breakers. The actuation of either the undervoltage or the shunt trip device interrupts power from the motor generator (MG) sets to the control element drive mechanisms (CEDMs).

It is possible to change the 2-out-of-4 RPS logic to a 2-out-of-3 logic for a given input parameter in one channel at a time by trip channel bypassing. Thus, the bistable logic will function normally, producing normal trip indication and annunciation, but a reactor trip will not occur unless two additional channels indicate a trip condition. Trip channel bypassing can be simultaneously performed on any number of parameters in any number of channels, providing each parameter is bypassed in only one channel at a time. Trip channel bypassing is normally employed during maintenance or testing.

2-out-of-3 logic also prevents inadvertent trips caused by any single channel failure in a trip condition. In addition to the trip channel bypasses, there are also operating bypasses on select RPS trips. These bypasses are enabled manually in all four RPS channels when plant conditions do not warrant the specific trip protection. All operating bypasses are automatically removed when enabling bypass conditions are no longer satisfied.

Operating bypasses are implemented in the bistable logic, so that normal trip indication is also disabled. Trips with operating bypasses include Pressurizer Pressure – Low, Logarithmic Power Level – High, and CPC (DNBR – Low and LPD – High).

An enabled operating bypass inhibits the trip and pre-trip outputs from trip and pre-trip algorithms in the associated bistable processor. A loss of vital electrical power to a PPS division removes an enabled operating bypass, since this deenergizes the bistable processor.
The reactor trip switchgear, addressed in LCO 3.3.4, consists of eight RTCBs. Power input to the reactor trip switchgear comes from two full capacity MG sets operated in parallel, such that the loss of either MG set does not de-energize the CEDMs.

There are two separate CEDM power supply buses, each bus powering half of the CEDMs. The RTSS consists of one set of four RTCBs (RTSS 1) and another set of four RTCBs (RTSS 2). Each RTSS channel consists of two RTCBs. The eight RTCBs are connected in a 2-out-of-4 logic configuration.

Each of the two trip legs consists of two RTCBs in each RTSS in series. The two RTCBs within a trip leg are actuated by separate initiation circuits.

Each set of RTCBs is operated by either a manual reactor trip switch or an interposing relay actuated by RPS. There are four manual trip switches, arranged in two sets of two. Depressing both switches in either set will result in a reactor trip.

When a manual trip is initiated using manual switches in the MCR, the RPS trip paths and relays are bypassed and the RTCB undervoltage and shunt trip devices are actuated independent of the RPS.

Manual trip circuitry includes the switches and interconnecting wiring to both RTCBs necessary to actuate both the undervoltage and shunt trip devices, but excludes the interposing relay contacts and their interconnecting wiring to the RTCBs, which are considered part of the initiation circuit.

Functional testing of the entire RPS, from bistable logic input through the opening of individual sets of RTCBs, can be performed either at power or shut down and is normally performed on a 31 day basis. FSAR, Section 7.2 (Ref. 7), explains RPS testing in more detail.
The RPS is designed to ensure that the following operational criteria are met:

a. The associated actuation will occur when the monitored parameter reaches its setpoint and specific coincidence logic is satisfied.

b. Separation and redundancy are maintained to permit a channel to be out of service for testing or maintenance while still maintaining redundancy within the RPS instrumentation network.

Each of the analyzed accidents and transients can be detected by one or more RPS functions. The accident analysis takes credit for most of the RPS trip functions. Those functions for which no credit is taken, termed equipment protective functions, are not needed from a safety perspective.

Each RPS setpoint is chosen to be consistent with the Function of the respective trip. The basis for each trip setpoint falls into one of three general categories:

Category 1: To ensure SLs are not exceeded during AOOs,

Category 2: To assist the ESFAS during accidents, or

Category 3: To prevent material damage to major plant components (equipment protective).

The RPS maintains the SLs during AOOs and mitigates the consequences of DBAs in all MODES in which the RTCBs are closed.

The specific safety analysis applicable to each protective function is identified below:

1. **Variable Overpower – High**

   The Variable Overpower – High trip provides protection against core damage during the following events:
   
   - Uncontrolled CEA Withdrawal from Low Power (AOO);
   - Uncontrolled CEA Withdrawal at Power (AOO); and
   - CEA Ejection (Accident).
APPLICABLE SAFETY ANALYSES (continued)

2. **Logarithmic Power Level – High**

   The Logarithmic Power Level–High trip protects the integrity of the fuel cladding and helps protect the RCPB in the event of an unplanned criticality from a shutdown condition.

   In MODES 2, 3, 4, and 5, with the RTCBs closed and the CEA Drive System capable of CEA withdrawal, protection is required for CEA withdrawal events originating when logarithmic power is $< 1E-3\%$. For events originating above this power level, other trips provide adequate protection.

   MODES 3, 4, and 5, with the RTCBs closed, are addressed in LCO 3.3.2, “Reactor Protection System (RPS) Instrumentation – Shutdown.”

   In MODES 3, 4, or 5, with the RTCBs open or the CEAs not capable of withdrawal, the Logarithmic Power Level – High trip does not have to be OPERABLE. The indication and alarm Functions are addressed in LCO 3.3.13, “Logarithmic Power Monitoring Channels.”

3. **Pressurizer Pressure – High**

   The Pressurizer Pressure – High trip provides protection for the high RCS pressure SL. In conjunction with the pressurizer safety valves and the main steam pilot operated safety relief valve (POSRV), it provides protection against overpressurization of the RCPB during the following events:

   - Loss of electrical load without a reactor trip being generated by the turbine trip (AOO);
   - Loss of condenser vacuum (AOO);
   - CEA withdrawal from low power conditions (AOO);
   - Chemical and Volume Control System malfunction (AOO); and
   - Main Feedwater System pipe break (accident).
BASES

APPLICABLE SAFETY ANALYSES (continued)

4. **Pressurizer Pressure – Low**

   The Pressurizer Pressure – Low trip is provided to trip the reactor to assist the ESF System in the event of loss of coolant accidents (LOCAs). During a LOCA, the SLs could be exceeded. However, the consequences of the accident will be acceptable. A safety injection actuation signal (SIAS) and a containment isolation actuation signal (CIAS) are initiated simultaneously.

5. **Containment Pressure – High**

   The Containment Pressure – High trip prevents exceeding the containment design pressure during a design basis LOCA, main steam line break (MSLB), and main feedwater line break (MFLB). A SIAS, CIAS, and main steam isolation signal (MSIS) are initiated simultaneously.

6, 7. **Steam Generator Pressure – Low**

   The Steam Generator #1 Pressure – Low and Steam Generator #2 Pressure – Low trips provide protection against an excessive rate of heat extraction from the steam generators and resulting rapid, uncontrolled cooldown of the RCS. This trip is needed to shut down the reactor and assist the ESF System in the event of an MSLB or MFLB. A MSIS is initiated simultaneously.

8, 9. **Steam Generator Level – Low**

   The Steam Generator #1 Level – Low and Steam Generator #2 Level – Low trips ensure that a reactor trip signal is generated for the following events to help prevent exceeding the design pressure of the RCS due to the loss of the heat sink:

   - Inadvertent opening of a steam generator atmospheric dump valve (AOO);
   - Loss of normal feedwater event (AOO); and
   - Main Feedwater System pipe break (accident).
APPLICABLE SAFETY ANALYSES (continued)

10, 11. **Steam Generator Level – High**

The Steam Generator #1 Level – High and Steam Generator #2 Level – High trips are provided to protect the turbine from excessive moisture carryover in case of a steam generator overfill event.

12, 13. **Reactor Coolant Flow – Low**

The Reactor Coolant Flow, Steam Generator #1 – Low and Reactor Coolant Flow, Steam Generator #2 – Low trips provide protection against a MSLB with concurrent loss of offsite power and a reactor coolant pump (RCP) sheared shaft event.

The low reactor coolant flow trip signal initiates a reactor trip when the measured steam generator differential pressure across the primary side of either steam generator decreases at a rate great enough to require loss of flow protection or reaches a low preset value. The trip setpoint ensures that the reactor is tripped so as not to exceed the power density or DNBR limit.

14. **Local Power Density – High**

The CPCs perform the calculations required to derive the DNBR and LPD parameters, and their associated RPS trips. The DNBR – Low and LPD – High trips provide plant protection during the following AOOs:

The LPD – High trip provides protection against fuel centerline melting due to the occurrence of excessive local power density peaks during the following AOOs:

- Decrease in feedwater temperature;
- Increase in feedwater flow;
- Increased main steam flow (not due to the steam line rupture) without turbine trip;
- Uncontrolled CEA withdrawal from low power;
- Uncontrolled CEA withdrawal at power; and
- CEA misoperation; single part-strength CEA drop.
For the events listed above (except CEA misoperation; single part-strength CEA drop), DNBR – Low will trip the reactor first since DNB would occur before fuel centerline melting.

15. Departure from Nucleate Boiling Ratio (DNBR) – Low

The CPCs perform the calculations required to derive the DNBR and LPD parameters, and their associated RPS trips. The DNBR – Low and LPD – High trips provide plant protection during the following AOOs.

The DNBR – Low trip provides protection against core damage due to the occurrence of locally saturated conditions in the limiting (hot) channel during the following events and is the primary reactor trip (trips the reactor first) for these events:

- Decrease in feedwater temperature (AOO);
- Increase in feedwater flow (AOO);
- Increased main steam flow (not due to steam line rupture) without turbine trip (AOO);
- Increased main steam flow (not due to steam line rupture) with a concurrent single failure of an active component (AOO);
- MSLB with concurrent loss of offsite AC power (accident);
- Loss of normal AC power (AOO);
- Partial loss of forced reactor coolant flow (AOO);
- Total loss of forced reactor coolant flow (AOO);
- Single RCP shaft seizure (accident);
- Uncontrolled CEA withdrawal from low power (AOO);
- Uncontrolled CEA withdrawal at power (AOO);
- CEA misoperation; full strength CEA drop (AOO);
- CEA misoperation; part strength CEA drop (AOO);
APPLICABLE SAFETY ANALYSES (continued)

- Primary sample or instrument line break (AOO); and
- Steam generator tube rupture (accident).

CPC Auxiliary Trips

The CPC auxiliary trip parameters are calculated using the same process sensor inputs used to calculate the DNBR and LPD trips. There are no separate dedicated inputs for the auxiliary trip parameters. The CPC output signals of the DNBR - Low and LPD - High reactor trip Functions are sent to the PPS through the DNBR trip contact and LPD trip contact, respectively. When any of the calculated auxiliary trip parameters exceeds the trip setting value specified in the SCP, the DNBR trip contact and LPD trip contact are both activated at the same time. This results in the CPC channel sending DNBR - Low and LPD - High reactor trip signals to the PPS.

The CPC auxiliary trip signal parameters and setpoints are the following:

- RCS Cold Leg Temperature, High and Low setpoints,
- Hot Pin ASI, Positive and Negative setpoints,
- Pressurizer Pressure, High and Low setpoints,
- Integrated One Pin Radial Peaking Factor, High and Low setpoints,
- RCP Shaft Speed, Low setpoint,
- CPC Variable Overpower, Ceiling, Increasing Rate, Decreasing Rate, and Step setpoints,
- Hot Leg Temperature Saturation Margin, temperature difference setpoint below saturation temperature,
- Asymmetric Steam Generator Transient, Loop 1 and Loop 2 cold leg temperature difference setpoint, and
- Pressurizer Pressure, Low setpoint, Coincident with DNBR, Low setpoint.
Interlocks/Bypasses

The bypasses and their Allowable Values are addressed in SCP. They are not otherwise addressed as specific table entries.

The automatic operating bypass removal features must function as a backup to manual actions for all safety-related trips to ensure the trip Functions are not operationally bypassed when the safety analysis assumes the Functions are not bypassed. The basis for each of the operating bypasses is discussed under individual trips in the LCO section:

a. Logarithmic power level – High;
b. DNBR – low and LPD – High; and
c. Pressurizer pressure – Low.

The RPS satisfies Criterion 3 of 10 CFR 50.36(c)(2)(ii).

LCO

The LCO requires all instrumentation performing an RPS Function to be OPERABLE. Failure of any required portion of the instrument channel renders the affected channel(s) inoperable and reduces the reliability of the affected Functions.

Actions allow trip channel (maintenance) bypass of individual channels. With one channel of each Function in trip channel bypass, the coincidence logic for each Function changes into a 2-out-of-3 logic configuration.

Bypassing the same parameter in more than one channel is restricted by administrative procedural controls. With one parameter in trip channel bypass, the coincidence logic for each supported trip Function changes from a 2-out-of-4 into a 2-out-of-3 logic configuration. The all-bypass function for bypassing all parameters in one channel is interlocked in the LCL algorithm to prevent simultaneous bypass of two or more channels. The all-bypass interlock is implemented based on an analog circuit with hardwired cable between the LCLs of all channels. The purpose of the all-bypass function is to support testing and maintenance of bistable processor (BP) racks whereas the trip channel bypass is used to support repair and testing of failed sensors.
The NTSP, allowable value (AV), as-found tolerance (AFT), and as-left tolerance (ALT) are specified for each RPS trip Function in the SCP. The NTSPs are selected to ensure that the as-found trip settings measured by CHANNEL FUNCTIONAL TESTS remain conservative with respect to the AFT band around the previous as-left setting between successive CHANNEL CALIBRATIONS and do not exceed the AVs, provided the channel is performing normally as expected. Operation with a trip setting less conservative than the NTSP, but within the AFT band and AV, is acceptable provided that channel operation and testing are consistent with the assumptions of the plant specific setpoint calculations. A channel is considered degraded but OPERABLE if its actual trip setting is non-conservative with respect to its AFT band but within (more conservative than) its AV. The SCP requires entering such degraded channels in the plant's corrective action program. A channel is inoperable if its actual trip setting is not within its AV. In accordance with the NRC-approved setpoint methodology specified in the SCP, each specified AV is determined by accounting for instrument uncertainties, appropriate to the RPS trip Function, conservatively applied to the analytical limit, which is the trip setpoint assumed in the safety analysis. After each CHANNEL FUNCTIONAL TEST and CHANNEL CALIBRATION the trip setpoint is required by the SCP to be left within the ALT band around the NTSP.

The Bases for the individual function requirements are as follows:

1. **Variable Overpower – High**

   This LCO requires four channels of Variable Overpower – High to be OPERABLE in MODES 1 and 2.

   The variable over power trip signal initiates a reactor trip when the indicated neutron flux power increases at a rate greater than a predetermined value or reaches a high preset value.

   The flux signal to be used is the average of three linear subchannel flux signals originating from ENFMS.

2. **Logarithmic Power Level – High**

   This LCO requires all four channels of the Logarithmic Power Level – High to be OPERABLE in MODE 2, and in MODE 3, 4, or 5 when the RTCBs are closed and the CEA Drive System is capable of CEA withdrawal.
The MODES 3, 4, and 5 Condition is addressed in LCO 3.3.2.

The Allowable Value is high enough to provide an operating envelope that prevents unnecessary Logarithmic Power Level – High reactor trips during normal plant operations. The Allowable Value is low enough for the system to maintain a margin to unacceptable fuel cladding damage should a CEA withdrawal event occur.

The Logarithmic Power Level – High trip may be bypassed manually when logarithmic power is > 1E-3% RTP to allow the reactor to be brought to power during a reactor startup. This bypass is automatically removed when logarithmic power is ≤ 1E-3%. The operating bypass setpoint for Logarithmic Power Level – High Reactor Trip needs to be temporarily changed to 1E-4% during low power physics test in order to reduce the possibility of spurious trip. Above 1E-3%, the Variable Overpower – High and Pressurizer Pressure – High trips provide protection for reactivity transients.

The trip may be manually bypassed during PHYSICS TEST pursuant to LCO 3.1.9, “Test Exceptions – SDM.” During this testing, the Variable Overpower – High trip and administrative controls provide the required protection.

3. Pressurizer Pressure – High

This LCO requires four channels of Pressurizer Pressure – High to be OPERABLE in MODES 1 and 2.

The Allowable Value is set below the nominal lift setting of the POSRVs, and its operation avoids the undesirable operation of these valves during normal plant operation. In the event of an AOO or Accident causing overpressure, this setpoint ensures the reactor trip will take place, thereby assuring the integrity of the RCPB and preventing consequent pressure rise. The POSRVs can lift to prevent overpressurization of the RCS.

4. Pressurizer Pressure – Low

This LCO requires four channels of Pressurizer Pressure – Low to be OPERABLE in MODES 1 and 2.
The Allowable Value is set low enough to prevent a reactor trip during normal plant operation and pressurizer pressure transients. However, the setpoint is high enough that with a LOCA, the reactor trip will occur soon enough to allow the ESF Systems to perform as expected in the analyses and mitigate the consequences of the accident.

The trip setpoint may be manually decreased to a minimum value (floor value) of 7.0 kg/cm²A (100 psia) as pressurizer pressure is reduced during controlled plant shutdowns, provided the margin between the pressurizer pressure and the setpoint is maintained < 28.1 kg/cm² (400 psi). This allows for controlled depressurization of the RCS while still maintaining an active trip setpoint until the time is reached when the trip is no longer needed to protect the plant. Since the same Pressurizer Pressure – Low bistable logic is also shared with the SIAS, an inadvertent SIAS actuation is also prevented. The setpoint increases automatically as pressurizer pressure increases, until the trip setpoint is reached.

The Pressurizer Pressure – Low trip and the SIAS Function may be simultaneously bypassed when RCS pressure is below 28.1 kg/cm²A (400 psia), when neither the reactor trip nor an inadvertent SIAS actuation are desirable, and these Functions are no longer needed to protect the plant. The bypass is automatically removed as RCS pressure increases above 35.2 kg/cm²A (500 psia). The difference between the operating bypass enable and removal features allows for bypass permissive bistable hysteresis, and allows setting the operating bypass setpoint close enough to the limit so as to avoid inadvertent actuation at the 7.0 kg/cm²A (100 psia) trip setpoint minimum value (floor value).

5. Containment Pressure – High

The LCO requires four channels of Containment Pressure – High to be OPERABLE in MODES 1 and 2.

The Allowable Value is set high enough to allow for small pressure increases in containment expected during normal operation (i.e., plant heatup), and is not indicative of an abnormal condition. It is set low enough to initiate a reactor trip when an abnormal condition is indicated.
BASES

LCO (continued)

6, 7. **Steam Generator Pressure – Low**

This LCO requires four channels of Steam Generator #1 Pressure – Low and Steam Generator #2 Pressure – Low to be OPERABLE in MODES 1 and 2.

This Allowable Value is sufficiently below the full load operating value for steam pressure so as not to interfere with normal plant operation, but still high enough to provide the required protection in the event of excessive steam demand. Since excessive steam demand causes the RCS to cool down, resulting in positive reactivity addition to the core, a reactor trip is required to offset that effect.

The trip setpoint may be manually decreased as steam generator pressure is reduced during controlled plant cooldown, provided the margin between steam generator pressure and the setpoint is maintained less 14.1 kg/cm² (200 psi).

This allows for controlled depressurization of the secondary system while still maintaining an active reactor trip setpoint and MSIS setpoint, until the time is reached when the setpoints are no longer needed to protect the plant.

8, 9. **Steam Generator Level – Low**

This LCO requires four channels of Steam Generator #1 Level – Low and Steam Generator #2 Level – Low for each steam generator to be OPERABLE in MODES 1 and 2.

The Allowable Value is sufficiently below the normal operating level for the steam generators so as not to cause a reactor trip during normal plant operations. The same bistable providing the reactor trip also initiates emergency feedwater to the affected steam generator via auxiliary feedwater actuation signal (AFAS). The reactor trip will remove the heat source (except decay heat), thereby conserving the reactor heat sink.
10, 11. **Steam Generator Level – High**

This LCO requires four channels of Steam Generator #1 Level – High and Steam Generator #2 Level – High to be OPERABLE in MODES 1 and 2.

The Allowable Value is high enough to allow for normal plant operation and transients without causing a reactor trip. It is set low enough to ensure a reactor trip occurs before the level reaches the steam dryers. Having steam generator water level at the trip value is indicative of the plant not being operated in a controlled manner.

12, 13. **Reactor Coolant Flow – Low**

This LCO requires four channels of Reactor Coolant Flow – Low to be OPERABLE in MODES 1 and 2. The Allowable Value is set low enough to allow for the slight variations in reactor coolant flow during normal plant operations, while providing the required protection. Tripping the reactor ensures that the resultant power to flow ratio provides adequate core cooling to maintain DNBR under the expected pressure conditions for this event.

14. **Local Power Density – High**

This LCO requires four channels of LPD – High to be OPERABLE.

The LCO on the CPCs ensures that the SLs are maintained during all AOOs and the consequences of accidents are acceptable.

A CPC is not considered inoperable if CEAC inputs to the CPC are inoperable. The Required Action required in the event of CEAC channel failures ensures that the CPCs are capable of performing their safety function.

The CPC channel has many redundant feature designed to improve channel reliability. A minimum subset of features must be functional in order for the CPC to be capable of performing its safety-related trip function. Therefore, the channel can remain OPERABLE in the presence of a subset of channel failures, while maintaining the ability to provide the LPD – High trip function.
On-line CPC channel diagnostics make use of redundant features to maintain channel OPERABILITY to the extent possible, and provide alarm and annunciation of detectable failures.

Those detectable CPC channel failure resulting in a loss of protective function and channel inoperability will result in a CPC fail indication and associated low DNBR and high LPD channel trips. Input failures resulting in a sensor out of range affecting one or more CPC process inputs will result in a CPC sensor failure indication.

Detectable failures, whether they result in a channel inoperability or not, are logged in a system event list.

a. Each CPC channel redundantly processes analog process and nuclear instrumentation inputs. Only one of the two redundant analog processing modules is required to maintain OPERABILITY.

b. CEA position is redundantly processed by two CPPs in each CPC channel, and transmitted to the appropriate CEACs in all four CPC channels over one way fiber-optically isolated data links. Only one source of CEC position is required to be OPERABLE to maintain channel OPERABILITY.

c. Each CPC channel has two redundant operator interface panels shared with other systems, a maintenance and test panel (MTP) in the Instrumentation and Control (I&C) equipment room, an operator module (OM) in the MCR. At least one must be functional to assist personnel in performing certain surveillances. Upon failure of the OM, MTP, or both, the CPC channel will remain OPERABLE.

d. Each CPCS channel contains six processor modules. Failures of these modules are treated as follows:

1. CPC processor module failure – this failure results in a CPC channel inoperability as addressed by this LCO.

2. Auxiliary CPC processor module failure – this failure does not result in a CPC channel inoperability since this module does not perform any safety-related functions.
3. CEAC1 processor module failure – this failure is addressed in LCO 3.3.3.

4. CEAC2 processor module failure – this failure is addressed in LCO 3.3.3.

5. CPP1 processor module failure – this failure is addressed in LCO 3.3.3.

6. CPP2 processor module failure – this failure is addressed in LCO 3.3.3.

The CPC channels may be manually bypassed below 1E-4% as sensed by the logarithmic nuclear instrumentation. This bypass is enabled manually in all four CPC channels when plant conditions do not warrant the trip protection. The bypass effectively removes the DNBR – Low and LPD – High trips from the RPS logic circuitry. The operating bypass is automatically removed when enabling bypass conditions are no longer satisfied.

This operating bypass is required to perform a plant startup, since both CPC generated trips will be in effect whenever shutdown CEAs are inserted. It also allows system tests at low power with pressurizer pressure – low or RCPs off.

During PHYSICS TESTS pursuant to LCO 3.1.9, the trip may be manually bypassed to make these tests possible without tripping the reactor as long as THERMAL POWER is \( \leq 5\% \) RTP.

The OPERABILITY of an LPD – High reactor trip Function channel requires that the channel’s CPC auxiliary trip Functions also be OPERABLE.

15. Departure from Nucleate Boiling Ratio (DNBR) – Low

This LCO requires four channels of DNBR – Low to be OPERABLE. The LCO on the CPCs ensures that the SLs are maintained during all AOOs and the consequences of accidents are acceptable.
The CPC channel has many redundant features designed to improve channel reliability. A minimum subset of features must be functional in order for the CPC to be capable of performing its safety-related trip function. Therefore, the channel can remain OPERABLE in the presence of a subset of channel failures, while maintaining the ability to provide the DNBR – Low trip function. On-line CPC channel diagnostics make use of redundant features to maintain channel OPERABILITY to the extent possible, and provide alarm and annunciation of detectable failures.

Those detectable CPC channel failures resulting in a loss of protective function and channel inoperability will result in a CPC fail indication and associated low DNBR and high LPD channel trips. Input failures resulting in a sensor out of range affecting one or more CPC process inputs will result in a CPC sensor Failures indication.

Detectable failures, whether they result in a channel inoperability or not, are logged in a system event list.

a. Each CPC channel redundantly processes analog process and nuclear instrumentation inputs. Only one of the two redundant analog processing modules is required to maintain OPERABILITY.

b. CEA position is redundantly processed by two CPPs in each CPC channel, and transmitted to the appropriate CEACs in all four CPC channels over one way fiber-optically isolated data links. At least one CEAC is required to be OPERABLE to maintain channel OPERABILITY in each channel.

c. Each CPC channel has two redundant operator interface panels shared with other systems, such as a MTP in the instrumentation control equipment room, and an OM in the MCR. At least one must be functional to assist personnel in performing certain surveillances. Upon failure of the OM, MTP, or both, the CPC channel will remain OPERABLE.
d. Each CPCS channel contains six processor modules. Failures of these modules are treated as follows:

1. CPC processor module failure – this failure results in a CPC channel inoperability, as addressed by this LCO.
2. Aux CPC processor module failure – this failure does not result in a CPC channel inoperability since this module does not perform any safety-related functions.
3. CPP1 processor module failure – this failure is addressed in LCO 3.3.3.
4. CPP2 processor module failure – this failure is addressed in LCO 3.3.3.

A CPC is not considered inoperable if CEAC inputs to the CPC are inoperable. The Required Actions required in the event of CEAC channel failures ensure the CPCs are capable of performing their safety function.

The CPC channels may be manually bypassed below 1E-4%, as sensed by the logarithmic nuclear instrumentation. This bypass is enabled manually in all four CPC channels when plant conditions do not warrant the trip protection. The bypass effectively removes the DNBR – Low and LPD – High trips from the RPS logic circuitry. The operating bypass is automatically removed when enabling bypass conditions are no longer satisfied.

This operating bypass is required to perform a plant startup, since both CPC generated trips will be in effect whenever shutdown CEAs are inserted. It also allows system tests at lower power with Pressurizer Pressure – Low or RCPs off.

During PHYSICS TESTS pursuant to LCO 3.1.9, the trip may be manually bypassed to make these tests possible without tripping the reactor as long as THERMAL POWER is ≤ 5% RTP.

The OPERABILITY of an LPD – High reactor trip Function channel requires that the channel’s CPC auxiliary trip Functions also be OPERABLE.
Interlocks/Bypasses

The LCO on operating bypass permissive removal channels requires that the automatic operating bypass removal feature of all four operating bypass channels be OPERABLE for each RPS function with an operating bypass in the MODES addressed in the specific LCO for each Function. All four operating bypass removal channels must be OPERABLE to ensure that none of the four RPS channels are inadvertently bypassed.

This LCO applies to the operating bypass removal feature only. If the bypass enable Function is failed so as to prevent entering a bypass condition, operation may continue. In the case of the Logarithmic Power Level – High trip (Function 2), the absence of a bypass will limit maximum power to below the trip setpoint.

The interlock function Allowable Values are based upon analysis of functional requirements for the bypassed Functions. These are discussed above as part of the LCO discussion for the affected Functions.

APPLICABILITY

Most RPS trips are required to be OPERABLE in MODES 1 and 2 because the reactor is critical in these MODES. The reactor trips are designed to take the reactor subcritical, which maintains the SLs during AOOs and assists the ESFAS in providing acceptable consequences during accidents. Most trips are not required to be OPERABLE in MODES 3, 4, and 5. In MODES 3, 4, and 5, the emphasis is placed on return to power events. The reactor is protected in these MODES by ensuring adequate SDM. Exceptions to this are:

The Logarithmic Power Level – High trip, RPS Logic RTCBs, and manual trip are required in MODES 3, 4, and 5, with the RTCBs closed, to provide protection for boron dilution and CEA withdrawal events.

The Logarithmic Power Level – High trip in these lower MODES is addressed in LCO 3.3.2. The Logarithmic Power Level – High trip is bypassed prior to MODE 1 entry and is not required in MODE 1. The RPS Logic in MODES 1, 2, 3, 4 and 5 is addressed in LCO 3.3.4.
BASES

The most common causes of channel inoperability are outright failure or drift of the sensor, transmitter, or analog signal processing equipment sufficient to exceed the tolerance allowed by the plant specific setpoint analysis. Typically, the drift is found to be small and results in a delay of actuation rather than a total loss of function. This determination is generally made during the performance of a CHANNEL FUNCTIONAL TEST when the process instrument is set up for adjustment to bring it to within specification. If the trip setpoint is less conservative than the Allowable Value, the channel is declared inoperable immediately and the appropriate Conditions must be entered immediately.

In the event a channel’s trip setpoint is found non-conservative with respect to the Allowable Value or the transmitter, instrument loop, signal processing electronics, or RPS bistable trip unit is found inoperable, then all affected functions provided by that channel must be declared inoperable and the unit must enter the Condition for the particular protection Function affected.

When the number of inoperable channels in a trip Function exceeds that specified in any related Condition associated with the same trip Function, then the plant is outside the safety analysis. Therefore, LCO 3.0.3 is immediately entered, if applicable in the current MODE of operation.

A Note has been added to the ACTIONS. The Note has been added to clarify the application of the Completion Time rules. The Conditions of this Specification may be entered independently for each Function. The Completion Times of each inoperable Function will be tracked separately for each Function, starting from the time the Condition was entered for that function.

When a process measurement channel affecting redundant function equipment is inoperable, the below trip functions are placed in bypass state or trip state.
### ACTIONS (continued)

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<th>Process Measurement Functions</th>
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<td>Low DNBR</td>
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#### A.1 and A.2

Condition A applies when one or more RPS automatic trip Functions have one trip channel inoperable. RPS coincidence logic is 2-out-of-4.

If one trip channel is inoperable, startup or power operation is allowed to continue, providing the inoperable channel is placed in bypass or trip in 1 hour. The 1 hour allotted to bypass or trip the trip channel is sufficient to allow the operator to take all appropriate actions for the failed trip channel and still ensures that the risk involved in operating with the failed trip channel is acceptable. The failed trip channel must be restored to OPERABLE status prior to next entry into MODE 2 following entry into MODE 5. With a trip channel in bypass, the coincidence logic is now in a 2-out-of-3 configuration.
The Completion Time prior to next entry into MODE 2 following entry into MODE 5 is based on adequate channel to channel independence, which allows a 2-out-of-3 channel operation since no single failure will cause or prevent a reactor trip.

B.1

Condition B applies when one or more RPS automatic trip Functions have two trip channels inoperable.

Required Action B.1 provides for placing one inoperable trip channel in bypass and the other trip channel in trip within the Completion Time of 1 hour. This Completion Time is sufficient to allow the operator to take all appropriate actions for the failed trip channels while ensuring the risk involved in operating with the failed channels is acceptable. With one trip channel of protective instrumentation bypassed, the RPS is in a 2-out-of-3 logic; but with another trip channel failed, the RPS could be operating in a two-out-of-two logic. This is outside the assumptions made in the analyses and should be corrected. To correct the problem, the second trip channel is placed in trip. This places the RPS in a one-out-of-two logic. If any of the other OPERABLE trip channels receives a trip signal, the reactor will trip.

One of the two inoperable channels will need to be restored to OPERABLE status prior to the next required CHANNEL FUNCTIONAL TEST, because channel surveillance testing on an OPERABLE channel requires that the OPERABLE channel be placed in bypass. However, it is not possible to bypass more than one RPS channel, and placing a second channel in trip will result in a reactor trip. Therefore, if one RPS channel is in trip and a second channel is in bypass, a third inoperable channel would place the unit in LCO 3.0.3.

C.1, C.2.1, and C.2.2

Condition C applies to one automatic operating bypass removal Function inoperable. If the inoperable bypass removal Function for any bypass channel cannot be restored to OPERABLE status within 1 hour, the associated trip channel may be considered OPERABLE only if the bypass is not in effect. Otherwise the affected trip channel must be declared inoperable, as in Condition A, and the affected automatic trip channel placed in bypass or trip. The operating bypass removal Function and the automatic trip channel must be repaired prior to next entry into MODE 2 following entry into MODE 5. The Bases for the Required Actions and required Completion Times are consistent with Condition A.
D.1 and D.2

Condition D applies to two inoperable automatic operating bypass removal Functions. If the operating bypass removal Functions for two operating bypasses cannot be restored to OPERABLE status within 1 hour, the associated trip channel may be considered OPERABLE only if the operating bypass is not in effect. Otherwise the affected trip channels must be declared inoperable, as in Condition B, and the operating bypasses either removed or one automatic trip channel placed in bypass and the other in trip within 1 hour. The restoration of one affected bypassed automatic trip channel must be completed prior to the next CHANNEL FUNCTIONAL TEST, or the plant must shut down per LCO 3.0.3 as explained in Condition B.

E.1

Condition E is entered when the Required Action and associated Completion Time of Condition A, B, C or D are not met.

If the Required Actions associated with these Conditions cannot be completed within the required Completion Times, the reactor must be brought to a MODE where the Required Actions do not apply. The allowed Completion Time of 6 hours is reasonable, based on operating experience, for reaching the required MODE from full power conditions in an orderly manner without challenging plant systems.

SURVEILLANCE REQUIREMENTS

The SRs for any particular RPS Function are found in the SR column of Table 3.3.1-1, for that Function. Most Functions are subject to CHANNEL CHECK, CHANNEL FUNCTIONAL TEST, CHANNEL CALIBRATION, and response time testing.

The OPERABILITY of the interface and test processor (ITP) is not required by LCO 3.3.1 because the RPS does not need the ITP to perform the safety function of the RPS. However, the ITP must be maintained capable of supporting performance of the CHANNEL FUNCTIONAL TEST of SRs 3.3.1.7, 3.3.1.10, and 3.3.1.12.

SR 3.3.1.1

Performance of the CHANNEL CHECK once every 12 hours ensures that gross failure of instrumentation has not occurred. A CHANNEL CHECK is a comparison of the parameter indicated on one channel to a similar parameter on other channels. It is based on the assumption that
instrument channels monitoring the same parameter should read approximately the same value. Significant deviations between the two instrument channels could be an indication of excessive instrument drift in one of the channels. CHANNEL CHECK will detect gross channel failure; thus, it is a key to verifying that the instrumentation continues to operate properly between each CHANNEL CALIBRATION.

Agreement criteria are determined by the plant staff based on a combination of the channel instrument uncertainties, including indication and readability. If a channel is outside the match criteria, it could be an indication that the transmitter or the signal processing equipment has drifted outside its limits.

The Frequency, about once every shift, is based on operating experience that demonstrates the rarity of channel failure. Since the probability of two random failures in redundant channels in any 12 hour period is extremely low, the CHANNEL CHECK minimizes the chance of loss of protection function due to failure of redundant channels. The CHANNEL CHECK supplements less formal, but more frequent checks of channel OPERABILITY during normal operational use of the displays associated with the LCO required channels.

In the case of RPS trips with multiple inputs, such as the DNBR and LPD inputs to the CPCs, a CHANNEL CHECK must be performed on all inputs.

**SR 3.3.1.2**

The RCS flow rate indicated by each CPC is verified to be less than or equal to the actual RCS total flow rate measured by RCS pump differential pressure or the THERMAL POWER calculation every 12 hours when THERMAL POWER is ≥ 80% RTP. The check Frequency is modified by a Note indicating “Not required to be performed until 12 hours after THERMAL POWER ≥ 80% RTP.” The 12 hours after reaching 80% RTP is for plant stabilization, data taking, and flow verification.

This check (and if necessary, the adjustment of flow measurement error by the CPC addressable constant flow coefficients adjustment and measurement method to be included in CPC BERR1 item) ensures that the DNBR setpoint is conservatively adjusted with respect to actual flow indications, as determined by the Core Operating Limits Supervisory System (COLSS).
SURVEILLANCE REQUIREMENTS (continued)

SR 3.3.1.3

The CPC System Event Log is checked every 12 hours to monitor the CPCS channel performance. The System Event Log provides an historical record of the last thirty detected CPC channel error conditions including error conditions affecting the CEAC performance. A detected error condition may not render a channel inoperable, unless it is accompanied by a CPC Fail indication.

The Frequency of 12 hours is based upon the nature of the surveillance in detecting many non-critical error conditions and considers that detectable failures resulting in channel inoperability will result in a CPC Fail condition.

SR 3.3.1.4

The daily power calibration is the calculation of the core THERMAL POWER by performing a secondary heat balance measurement (a calorimetric) and adjusting the linear power, CPC ΔT power, and CPC neutron flux power channels to agree with the calculated THERMAL POWER if any channel indicates more than 0.5% RTP below the calculated THERMAL POWER. A daily power calibration is performed when THERMAL POWER is ≥ 15% RTP. The linear power level signal and the CPC addressable constant multipliers are adjusted in each channel to make the linear power level signal and CPC-calculated signals for CPC ΔT power and CPC neutron flux power agree with the calculated THERMAL POWER (calorimetric) if the signal from any channel of linear power, CPC ΔT power, and the CPC neutron flux power is more than 0.5% RTP less than the calculated THERMAL POWER. The value of 0.5% RTP is adequate because this value is assumed in the safety analysis. These checks (and if necessary, the adjustment of the linear power level signal and CPC addressable constant coefficients) are adequate to ensure that the accuracy of these CPC-calculated signals is maintained within the analyzed error margins. Core THERMAL POWER must be > 15% RTP to obtain accurate secondary heat balance measurement (calorimetric) data. At lower power levels, the accuracy of calorimetric data is inadequate.

The Frequency of 24 hours is based on plant operating experience and takes into account indications and alarms located in the MCR to detect deviations in channel outputs. The Frequency is modified by Note 1 indicating this Surveillance need only be performed within 12 hours after reaching 15% RTP. The 12 hours after reaching 15% RTP is required for plant stabilization, data taking, and flow verification. The secondary
SURVEILLANCE REQUIREMENTS (continued)

calorimetric calculated THERMAL POWER is inaccurate at lower power levels. A second note in the SR indicates the SR may be suspended during PHYSICS TESTS.

The conditional suspension of the daily power calibration under strict administrative control is necessary to allow special testing to occur.

SR 3.3.1.5

The RCS flow rate indicated by each CPC is verified to be less than or equal to the RCS total flow rate every 31 days. The Note indicates the Surveillance is performed within 12 hours after THERMAL POWER is ≥ 80% RTP. This check (and if necessary, the adjustment of the CPC addressable flow constant coefficients) ensures that the DNBR setpoint is conservatively adjusted with respect to actual flow indications as determined by a daily power calibration.

Operating experience has shown the specified Frequency is adequate, as instrument drift is minimal, and changes in actual flow rate are minimal over core life.

SR 3.3.1.6

The three vertically mounted excore nuclear instrumentation detectors in each channel are used to determine APD for use in the DNBR and LPD calculations. Because the detectors are mounted outside the reactor vessel, a portion of the signal from each detector is from core sections not adjacent to the detector. This is termed shape annealing and is compensated for after every refueling by performing SR 3.3.1.11, which adjusts the gains of the three detector amplifiers for shape annealing. SR 3.3.1.6 ensures that the pre-assigned gains are still proper. Power must be ≥ 15% RTP because the CPCs do not use the excore generated signals for axial flux shape information at low power levels.

The Note allowing 12 hours after reaching 15% RTP is required for plant stabilization and testing.

The 31 day Frequency is adequate because the demonstrated long term drift of the instrument channels is minimal.
SURVEILLANCE REQUIREMENTS (continued)

SR 3.3.1.7

A CHANNEL FUNCTIONAL TEST on each channel is performed every 31 days to ensure the entire channel will perform its intended function when needed. The SR is modified by a Note. The Note allows the CHANNEL FUNCTIONAL TEST for the Logarithmic Power Level – High channels to be performed 2 hours after logarithmic power drops below 1E-3% and is required to be performed only if the RTCBs are closed.

The RPS CHANNEL FUNCTIONAL TEST consists of overlapping tests as described in FSAR, Section 7.2 (Ref. 7). These tests verify that the RPS is capable of performing its intended function from bistable input through the RTCBs. They include:

Bistable Logic Tests

Bistable logic tests are performed to confirm that bistable logics are properly operating.

Local Coincidence Logic Tests

Local coincidence logic tests are described in Bases for LCO 3.3.4. Local coincidence logic tests are performed to confirm the OPERABILITY of 2-out-of-4 logic and trip channel bypass logic.

Trip Path Tests

Trip path (initiation logic) tests are described in Bases for LCO 3.3.4. Initiation logic tests composed of selective 2-out-of-4 are performed after local coincidence logic tests are completed. These tests are performed for only one channel and one initiation logic at a time.

The RTCB test is a manually initiated test. The test is manually initiated because the test philosophy requires operator involvement in the testing and reclosing of these important reactor trip devices. The operator can obtain status information from the breaker open/close indication and current monitors and thus determine the success or failure of the test. The RTCBs must then be closed prior to testing the other three initiation circuits or a reactor trip could result.

The CPC and CEAC channels and excore nuclear instrumentation channels are tested separately.
SURVEILLANCE REQUIREMENTS (continued)

The excore channels use pre-assigned test signals to verify proper channel alignment. The excore logarithmic channel test signal is inserted into the preamplifier input, so as to test the first active element downstream of the detector.

The linear range excore test signal is inserted at the drawer input, since there is no preamplifier.

The CPC CHANNEL FUNCTIONAL TEST is performed every 31 days to check system operation status using an MTP. The CPC CHANNEL FUNCTIONAL TEST including trip function is performed every 18 months according to SR 3.3.1.10. A note is added to specify that the CPC CHANNEL FUNCTIONAL TEST includes verifying that each OPERABLE CPC has the correct values of addressable constants installed.

SR 3.3.1.8

A Note indicates that excore neutron detectors are excluded from CHANNEL CALIBRATION. A CHANNEL CALIBRATION of the linear power of excore neutron flux channel every 31 days ensures that the channels are reading accurately and within tolerance. The Surveillance verifies that the channel responds to a measured parameter within the necessary range and accuracy. CHANNEL CALIBRATION leaves the channel adjusted to account for instrument drift between successive calibrations to ensure that the channel remains operational between successive Surveillances. CHANNEL CALIBRATION must be performed consistent with the SCP.

The detectors are excluded from CHANNEL CALIBRATION because they are passive devices, with minimal drift, and because of the difficulty of simulating a meaningful signal. Slow changes in detector sensitivity are compensated by performing the daily power calibration (SR 3.3.1.4) and the monthly linear power subchannel gain check (SR 3.3.1.6). In addition, the associated MCR indications are monitored by the operators.

SR 3.3.1.9

SR 3.3.1.9 is the performance of a CHANNEL CALIBRATION every 18 months.

CHANNEL CALIBRATION is a complete check of the instrument channel including the sensor. The surveillance verifies that the channel responds to a measured parameter within the necessary range and accuracy.
SURVEILLANCE REQUIREMENTS (continued)

CHANNEL CALIBRATION leaves the channel adjusted to account for instrument drift between successive calibrations to ensure that the channel remains operational between successive Surveillances. CHANNEL CALIBRATION must be performed consistent with the SCP.

The Frequency is based upon the assumption of an 18 month calibration interval for the determination of the magnitude of equipment drift in the setpoint analysis as well as operating experience and consistency with the 18 month fuel cycle.

The Surveillance is modified by a Note to indicate that the excore neutron detectors are excluded from CHANNEL CALIBRATION because they are passive devices, with minimal drift, and because of the difficulty of simulating a meaningful signal. Slow changes in detector sensitivity are compensated for by performing the daily power calibration (SR 3.3.1.4) and the monthly linear power subchannel gain check (SR 3.3.1.6). In addition, the associated MCR indications are monitored by the operators.

SR 3.3.1.10

Every 18 months, a CHANNEL FUNCTIONAL TEST is performed on the CPCs. The CHANNEL FUNCTIONAL TEST shall include the injection of a signal as close to the sensors as practicable to verify OPERABILITY including alarm and trip Functions. This surveillance also includes the CPC auxiliary trip Functions.

The basis for the 18 month Frequency is that the CPCs perform a continuous self-monitoring function that eliminates the need for more frequent CHANNEL FUNCTIONAL TESTS. This CHANNEL FUNCTIONAL TEST essentially validates the self-monitoring function and checks for a small set of failure modes that are undetectable by the self-monitoring function.

SR 3.3.1.11

The three excore neutron detectors used by each CPC channel for axial flux distribution information are far enough from the core to be exposed to flux from all heights in the core, although it is desired that they only read their particular level. The CPCs adjust for this flux overlap by using the predetermined shape annealing matrix elements in the CPC software.

After refueling, it is necessary to re-establish the shape annealing matrix elements for the excore neutron detectors based on more accurate incore detector readings. This is necessary because refueling could possibly produce a significant change in the shape annealing matrix coefficients.
Incore detectors are inaccurate at low power levels. THERMAL POWER should be significant but < 80% to perform an accurate axial shape calculation used to derive the shape annealing matrix elements.

By restricting power to ≤ 80% until shape annealing matrix elements are verified, excessive local power peaks within the fuel are avoided. Operating experience has shown this Frequency to be acceptable.

SR 3.3.1.12

SR 3.3.1.12 is a CHANNEL FUNCTIONAL TEST similar to SR 3.3.1.7 except it is applicable only to automatic operating bypass removal functions and is performed once within 31 days prior to each startup. Proper operation of operating bypass permissive Functions is critical during plant startup so that the associated operating bypasses can be manually put in place to allow startup operation. In addition, other operating bypasses must be automatically removed by associated automatic operating bypass removal Functions at the appropriate points during power ascent to enable certain reactor trip Functions.

Consequently, the appropriate time to verify bypass removal function OPERABILITY is just prior to startup.

Once the operating bypasses are removed, the bypasses must not fail in such a way that the associated trip function gets inadvertently bypassed. This feature is verified by the trip function CHANNEL FUNCTIONAL TEST, SR 3.3.1.7. Therefore, further testing of the bypass removal function after startup is unnecessary.

SR 3.3.1.13

This SR ensures that the RPS RESPONSE TIMES are verified to be less than or equal to the maximum values assumed in the safety analysis. Individual component response times are not modeled in the analyses. The analyses model the overall or total elapsed time, from the point at which the parameter exceeds the trip setpoint value at the sensor to the point at which the RTCBs open. Response times are conducted on an 18 month STAGGERED TEST BASIS. This results in the interval between successive surveillances of a given channel of n × 18 months, where n is the number of channels in the function. The Frequency of 18 months is based upon operating experience, which has shown that random failures of instrumentation components causing serious response time degradation, but not channel failure at power, are infrequent.
BASES

SURVEILLANCE REQUIREMENTS (continued)

occurrences. Also, response times cannot be determined at power, since equipment operation is required. Testing may be performed in one measurement or in overlapping segments, with verification that all components are tested.

A Note is added to indicate that the excore neutron detectors may be excluded from RPS RESPONSE TIME testing because they are passive devices, with minimal drift, and because of the difficulty of simulating a meaningful signal. Slow changes in detector sensitivity are compensated for by performing the daily power calibration (SR 3.3.1.4).

REFERENCES

1. 10 CFR 50.36.

2. 10 CFR Part 50, Appendix A, GDC 21.

3. 10 CFR 50.34.


5. FSAR, Chapters 6 and 15.

6. 10 CFR 50.49.

7. FSAR, Chapter 7.
B 3.3 INSTRUMENTATION

B 3.3.2 Reactor Protection System (RPS) Instrumentation – Shutdown

BASES

BACKGROUND

The RPS initiates a reactor trip to protect against violating the core fuel design limits and reactor coolant pressure boundary (RCPB) integrity during anticipated operational occurrences (AOOs). By tripping the reactor, the RPS also assists the Engineered Safety Features Systems in mitigating accidents.

The Protection and Monitoring Systems have been designed to ensure safe operation of the reactor. This is achieved by specifying limiting safety system settings (LSSS) in terms of parameters directly monitored by the RPS, as well as LCOs on other reactor system parameters and equipment performance.

The LSSS, defined in this Specification as the Allowable Value, in conjunction with the LCOs, establish the threshold for protection system action to prevent exceeding acceptable limits during design basis accidents (DBAs).

During AOOs, which are those events expected to occur one or more times during the plant life, the acceptable limits are:

a. The departure from nucleate boiling ratio shall be maintained above the safety limit (SL) value to prevent departure from nucleate boiling.

b. Fuel centerline melting shall not occur.

c. The Reactor Coolant System (RCS) pressure SL of 193.3 kg/cm²A (2750 psia) shall not be exceeded.

Maintaining the parameters within the above values ensures that the offsite dose will be within the 10 CFR Part 50, Appendix A (Ref. 1) and 10 CFR 50.34 (Ref. 2) criteria during AOOs.

Accidents are events that are analyzed even though they are not expected to occur during the plant life. The acceptable limit during accidents is that the offsite dose shall be maintained within an acceptable fraction of 10 CFR 50.34 (Ref. 2) limits.
The Reactor Trip System (RTS) is a safety system which initiates reactor trips. The RTS consists of four channels of sensors, auxiliary process cabinet-safety (APC-S) cabinets, Excore Neutron Flux Monitoring System (ENFMS) cabinets, Core Protection Calculator System (CPCS) cabinets, the Reactor Protection System (RPS) portion of Plant Protection System (PPS) cabinets, and Reactor Trip Switchgear System (RTSS) cabinets as shown in Figure 7.2-1.

Different accident categories allow a different fraction of these limits based on probability of occurrence. Meeting the acceptable dose limit for an accident category is considered having acceptable consequences for that event.

The RPS function is performed through the below portions in the RTS:

a. Measurement channels;
b. Bistable logics;
c. RPS logic; and
d. Reactor trip circuit breakers (RTCBs).

This LCO applies only to the Logarithmic Power Level – High trip in MODES 3, 4, and 5 with the RTCBs closed. In MODES 1 and 2, this trip Function is addressed in LCO 3.3.1, “Reactor Protection System (RPS) Instrumentation – Operating.” LCO 3.3.13, “Logarithmic Power Monitoring Channels,” applies when the RTCBs are open. In the case of LCO 3.3.13, the logarithmic channels are required for monitoring neutron flux, although the trip Function is not required.

**Measurement Channels and Bistable Logic**

The measurement channels providing input to the Logarithmic Power Level – High trip consist of the four logarithmic nuclear instrumentation channels detecting neutron flux leakage from the reactor vessel. Other aspects of the Logarithmic Power Level – High trip are similar to the other measurement channels and bistables. These are addressed in the Background section of LCO 3.3.1.
BASES

BACKGROUND (continued)

Functional testing of the entire RPS, from bistable input through the opening of individual sets of RTCBs, can be performed either at power or shut down and is normally performed on a 31 day basis. Nuclear instrumentation can be similarly tested. FSAR, Section 7.2 (Ref. 3), provides more detail on RPS testing.

APPLICABLE SAFETY ANALYSES

The RPS functions to maintain the SLs during AOOs and mitigates the consequence of DBAs in all MODES in which the RTCBs are closed. Each of the analyzed transients and accidents can be detected by one or more RPS Functions. The Logarithmic Power Level - High trip protects the integrity of the fuel cladding and helps protect the RCPB in the event of an unplanned criticality from a shutdown condition.

In MODES 2, 3, 4, and 5, with the RTCBs closed and the Control Element Assembly (CEA) Drive System capable of CEA withdrawal, protection is required for CEA withdrawal events originating when logarithmic power is < 1E-3%. For events originating above this power level, other trips provide adequate protection.

MODES 3, 4, and 5, with the RTCBs closed, are addressed in this LCO. MODE 2 is addressed in LCO 3.3.1.

In MODES 3, 4, or 5, with the RTCBs open or the CEAs not capable of withdrawal, the Logarithmic Power Level – High trip does not have to be OPERABLE. However, the indication and alarm portion of two logarithmic channels must be OPERABLE to ensure proper indication of neutron population and to indicate a boron dilution event. The indication and alarm functions are addressed in LCO 3.3.13.

The bypasses and their Allowable Values are addressed in Setpoint Control Program (SCP). The automatic operating bypass removal features must function as a backup to manual actions for all safety-related trips to ensure the trip functions are not operationally bypassed when the safety analysis assumes the functions are not bypassed. The operating bypass for Logarithmic Power Level – High is described in Table 3.3.2-1.

The RPS satisfies Criterion 3 of 10 CFR 50.36(c)(2)(ii).

LCO

The LCO requires the Logarithmic Power Level – High RPS Function to be OPERABLE. Failure of any required portion of the instrument channel renders the affected channel inoperable and reduces the reliability of the affected Function.
Bypassing the same parameter in more than one channel is restricted by the administrative procedure. The coincidence logic becomes 2-out-of-3 coincidence logic. The all-bypass function for bypassing all parameters in the channel is interlocked in local coincidence logic (LCL) algorithm to prevent simultaneous bypass of more than one channel. The all-bypass interlock is implemented based on analog circuit through hardwired cable between LCLs in all channels. The purpose of the all-bypass function is to support testing and maintenance of bistable processor (BP) whereas the trip channel bypass is used against sensor failure. With one channel in each Function trip channel bypassed, this effectively places the plant in a two-out-of-three logic configuration in those Functions. Plants are restricted to 48 hours in a trip channel bypass condition before either restoring the function to four channel operation (2-out-of-4 logic) or placing the channel in trip (1-out-of-3 logic).

This LCO requires all four channels of the Logarithmic Power Level – High to be OPERABLE in MODE 2, and in MODE 3, 4, or 5 when the RTCBs are closed and the CEA Drive System is capable of CEA withdrawal.

The Allowable Value specified in the SCP is high enough to provide an operating envelope that prevents unnecessary Logarithmic Power Level – High reactor trips during normal plant operations. The Allowable Value is low enough for the system to maintain a safety margin for unacceptable fuel cladding damage should a CEA withdrawal event occur.

The Logarithmic Power Level – High trip may be bypassed when logarithmic power is above 1E-3% to allow the reactor to be brought to power during a reactor startup. This bypass is automatically removed when logarithmic power decreases below 1E-3%. Above 1E-3%, the Linear Power Level – High and Pressurizer Pressure – High trips provide protection for reactivity transients.

The trip may be manually bypassed during physics testing pursuant to LCO 3.1.9, “Special Test Exception (STE) – SHUTDOWN MARGIN (SDM).” During this testing, the Linear Power Level – High trip and administrative controls provide the required protection.
APPLICABILITY

Most RPS trips are required to be OPERABLE in MODES 1 and 2 because the reactor is critical in these MODES. The trips are designed to take the reactor subcritical, which maintains the SLs during AOOs and assists the Engineered Safety Features Actuation System (ESFAS) in providing acceptable consequences during accidents.

Most trips are not required to be OPERABLE in MODES 3, 4, and 5. In MODES 3, 4, and 5, the emphasis is placed on return to power events. The reactor is protected in these MODES by ensuring adequate SDM. Exceptions to this are:

a. The Logarithmic Power Level – High trip, RPS Logic RTCBs, and Manual Trip are required in MODES 3, 4, and 5, with the RTCBs closed, to provide protection for boron dilution and CEA withdrawal events. The Logarithmic Power Level – High trip in these lower MODES is addressed in this LCO. The RPS Logic in MODES 1, 2, 3, 4, and 5 is addressed in LCO 3.3.4, “Reactor Protection System (RPS) Logic and Trip Initiation.”

b. The Steam Generator #1 Pressure – Low trip, Steam Generator #2 Pressure – Low trip, RPS Logic, RTCBs and manual trip are required in MODES 3 and 4, with the RTCBs closed, to provide protection for MSLB. The Steam Generator Pressure – Low trip in shutdown MODE is described in this LCO.

c. The Applicability is modified by a Note that allows the trip to be bypassed when logarithmic power is > 1E-3%, and the bypass is automatically removed when logarithmic power is ≤ 1E-3%.

The most common causes of channel inoperability are outright failure or drift of the bistable or process module sufficient to exceed the tolerance allowed by the plant specific setpoint analysis. Typically, the drift is found to be small and results in a delay of actuation rather than a total loss of function. This determination is generally made during the performance of a CHANNEL FUNCTIONAL TEST when the process instrument is set up for adjustment to bring it to within specification. If the trip setpoint is less conservative than the Allowable Value stated in the SCP, the channel is declared inoperable immediately, and the appropriate Condition(s) must be entered immediately.

In the event a channel's trip setpoint is found nonconservative with respect to the Allowable Value, or the excore logarithmic power channel or RPS bistable trip unit is found inoperable, then all affected Functions provided by that channel must be declared inoperable and the unit must enter the Condition for the particular protection Function affected.
When a process measurement channel affecting redundant function equipment is inoperable, the below trip functions are placed in bypass state or trip state:

<table>
<thead>
<tr>
<th>Process Measurement Functions</th>
<th>Bypass/Trip of Trip Functions</th>
</tr>
</thead>
<tbody>
<tr>
<td>Channel</td>
<td></td>
</tr>
<tr>
<td>Steam Generator Pressure</td>
<td>Steam Generator Low Pressure (RPS)</td>
</tr>
<tr>
<td></td>
<td>Steam Generator #1 Low Pressure (ESF)</td>
</tr>
<tr>
<td></td>
<td>Steam Generator #2 Low Pressure (ESF)</td>
</tr>
</tbody>
</table>

When the number of inoperable channels in a trip Function exceeds that specified in any related Condition associated with the same trip Function, then the plant is outside the safety analysis. Therefore, LCO 3.0.3 is immediately entered, if applicable in the current MODE of operation.

A.1 and A.2

Condition A applies to the failure of a single trip channel or associated instrument channel inoperable in any RPS automatic trip function.

RPS coincidence logic is 2-out-of-4. If one RPS channel is inoperable, the operation in MODES 3, 4, 5 is allowed to continue, providing the inoperable channel is placed in bypass or trip in 1 hour (Required Action A.1)

The 1 hour allotted to bypass or trip the channel is sufficient to allow the operator to take all appropriate actions for the failed channel and still ensures that the risk involved in operating with the failed channel is acceptable.

The failed channel must be restored to OPERABLE status prior to next entry into MODE 2 following entry into MODE 5. With a channel in bypass, the coincidence logic is now in a 2-out-of-3 configuration.

The Completion Time of prior to next entry into MODE 2 following entry into MODE 5 is based on adequate channel to channel independence, which allows operation with two or more channels since no single failure will prevent a reactor trip.
B.1

Condition B applies to the failure of two Logarithmic Power Level – High trip channels or associated instrument channels. Required Action B.1 provides for placing one inoperative channel in bypass and the other channel in trip within the Completion Time of 1 hour. This Completion Time is sufficient to allow the operator to take all appropriate actions for the failed channels and still ensures the risk involved in operating with the failed channels is acceptable. With one channel of protection instrumentation bypassed, the RPS is in a 2-out-of-3 logic; but with another channel failed, the RPS could be operating in a 2-out-of-2 logic. This is outside the assumptions made in the analyses and should be corrected. To correct the problem, the second channel is placed in trip. This places the RPS in a one-out-of-two logic. If any of the other OPERABLE channels receives a trip signal, the reactor will trip.

One of the two inoperative channels will need to be restored to OPERABLE status prior to the next required CHANNEL FUNCTIONAL TEST because channel surveillance testing on an OPERABLE channel requires that the OPERABLE channel be placed in bypass. However, it is not possible to bypass more than one RPS channel and placing a second channel in trip will result in a reactor trip. Therefore, if one RPS channel is in trip and a second channel is in bypass, a third inoperative channel would place the unit in LCO 3.0.3.

C.1, C.2.1, and C.2.2

Condition C applies to one automatic operating bypass removal channel inoperative. If the bypass removal channel for the high logarithmic power level operating bypass cannot be restored to OPERABLE status within 1 hour, the associated RPS channel may be considered OPERABLE only if the bypass is not in effect. Otherwise, the affected RPS channel must be declared inoperative, as in Condition A, and the bypass either removed or the affected automatic channel placed in trip or bypass. Both the bypass removal channel and the associated automatic trip channel must be repaired prior to entering MODE 2 following the next MODE 5 entry. The Bases for the Required Actions and required Completion Times are consistent with Condition A.
D.1 and D.2

Condition D applies to two inoperable automatic operating bypass removal channels. If the bypass removal channels for two operating bypasses cannot be restored to OPERABLE status within 1 hour, the associated RPS channel may be considered OPERABLE only if the bypass is not in effect. Otherwise, the affected RPS channels must be declared inoperable, as in Condition B, and the bypass either removed or one automatic trip channel placed in bypass and the other in trip within 1 hour. The restoration of one affected bypassed automatic trip channel must be completed prior to the next CHANNEL FUNCTIONAL TEST or the plant must shut down per LCO 3.0.3, as explained in Condition B. Completion Times are consistent with Condition B.

E.1

Condition E is entered when the Required Actions and associated Completion Times of Condition A, B, C, or D are not met.

If Required Actions associated with these Conditions cannot be completed within the required Completion Time, all RTCBs must be opened, placing the plant in a condition where the logarithmic power trip channels are not required to be OPERABLE. A Completion Time of 1 hour is a reasonable time to perform the Required Action, which maintains the risk at an acceptable level while having one or two channels inoperable.

SR 3.3.2.1

SR 3.3.2.1 is the performance of a CHANNEL CHECK of each logarithmic power channel. This SR is identical to SR 3.3.1.1. Only the Applicability differs.

Performance of the CHANNEL CHECK once every 12 hours ensures that gross failure of instrumentation has not occurred.
A CHANNEL CHECK is normally a comparison of the parameter indicated on one channel to a similar parameter on another channel. It is based on the assumption that instrument channels monitoring the same parameter should read approximately the same value. Significant deviations between the two instrument channels could be an indication of excessive instrument drift in one of the channels or of something even more serious. CHANNEL CHECK will detect gross channel failure; thus, it is key to verifying that the instrumentation continues to operate properly between each CHANNEL CALIBRATION.

Agreement criteria are determined by the plant staff based on a combination of the channel instrument uncertainties, including indication and readability. If a channel is outside the criteria, it could be an indication that the sensor or the signal processing equipment has drifted outside its limits.

The Frequency, about once every shift, is based on operating experience that demonstrates the rarity of channel failure. Since the probability of two random failures in redundant channels in any 12 hour period is extremely low, the CHANNEL CHECK minimizes the chance of loss of protection function due to failure of redundant channels. The CHANNEL CHECK supplements less formal, but more frequent, checks of channel OPERABILITY during normal operational use of the displays associated with the LCO required channels.

SR 3.3.2.2

A CHANNEL FUNCTIONAL TEST on each channel is performed every 31 days to ensure the entire channel will perform its intended function when needed. This SR is identical to SR 3.3.1.7. Only the Applicability differs. The RPS CHANNEL FUNCTIONAL TEST consists of three overlapping tests as described in FSAR, Section 7.2 (Ref. 3). These tests verify that the RPS is capable of performing its intended function, from bistable input through the RTCBs. They include:
SURVEILLANCE REQUIREMENTS (continued)

Bistable Logic Tests

A test signal is superimposed on the input in one channel at a time to verify that the bistable trips within the specified tolerance around the setpoint. This is done with the affected RPS channel trip channel bypassed.

The SCP has controls which require verification that the instrument channel functions as required by verifying the as-left and as-found settings are consistent with those established by the setpoint methodology.

Local Coincidence Logic Tests

Local coincidence logic tests are addressed in LCO 3.3.4. Local coincidence logic tests are performed to confirm the OPERABILITY of two-out-of-four logic and trip channel bypass logic.

Trip Path Test

Trip path (initiation logic) tests are described in LCO 3.3.4. Initiation logic tests composed of 2-out-of-4 are performed after local coincidence logic tests are completed. These tests are performed only for one channel and one initiation logic.

The RTCB test is a manually initiated test. The test is manually initiated because the test philosophy requires operator involvement in the testing and reclosing of these important reactor trip devices. The operator can obtain status information from the breaker open/close indication and current monitors and thus determine the success or failure of the test. The RTCBs must then be closed prior to testing the other three initiation circuits, or a reactor trip could result.

The excore channels use pre-assigned test signals to verify proper channel alignment. The excore logarithmic channel test signal is inserted into the preamplifier input, so as to test the first active element downstream of the detector.
SR 3.3.2.3

SR 3.3.2.3 is a CHANNEL FUNCTIONAL TEST similar to SR 3.3.2.2, except SR 3.3.2.3 is applicable only to bypass functions and is performed once within 31 days prior to each startup. This SR is identical to SR 3.3.1.12. Only the Applicability differs.

Proper operation of bypass permissives is critical during plant startup because the bypasses must be in place to allow startup operation and must be removed at the appropriate points during power ascent to enable certain reactor trips. Consequently, the appropriate time to verify automatic operating bypass removal function OPERABILITY is just prior to startup. Once the operating bypasses are removed, the bypasses must not fail in such a way that the associated trip Function gets inadvertently bypassed. This feature is verified by the trip Function CHANNEL FUNCTIONAL TEST, SR 3.3.2.2. Therefore, further testing of the bypass function after startup is unnecessary.

SR 3.3.2.4

This SR is identical to SR 3.3.1.9. Only the Applicability differs.

CHANNEL CALIBRATION is a complete check of the instrument channel excluding the sensor. The Surveillance verifies that the channel responds to a measured parameter within the necessary range and accuracy. CHANNEL CALIBRATION leaves the channel adjusted to account for instrument drift between successive calibrations to ensure that the channel remains operational between successive tests. The SCP has controls which require verification that the instrument channel functions as required by verifying the as-left and as-found settings are consistent with those established by the setpoint methodology.

Allowable Values and nominal trip setpoints are specified for this RPS trip Function in the SCP setpoint calculations. The nominal setpoint is selected to ensure the setpoint measured by CHANNEL FUNCTIONAL TESTS does not exceed the Allowable Value if the bistable is performing as required. Operation with a trip setpoint less conservative than the nominal trip setpoint, but within its Allowable Value, is acceptable provided that operation and testing are consistent with the assumptions of the plant specific setpoint calculations.
SURVEILLANCE REQUIREMENTS (continued)

Each Allowable Value specified in the SCP is more conservative than the analytical limit assumed in the safety analysis in order to account for instrument uncertainties appropriate to the trip Function. A channel is inoperable if its actual trip setpoint is not within its required Allowable Value.

The Frequency is based upon the assumption of an 18 month calibration interval for the determination of the magnitude of equipment drift in the setpoint analysis and includes operating experience and consistency with the typical 18 month fuel cycle.

The Surveillance is modified by a Note to indicate that the excore neutron detectors are excluded from CHANNEL CALIBRATION because they are passive devices with minimal drift and because of the difficulty of simulating a meaningful signal. Slow changes in detector sensitivity are compensated for by performing the daily power calibration (SR 3.3.1.4).

SR 3.3.2.5

This SR ensures that the RPS RESPONSE TIMES are verified to be less than or equal to the maximum values assumed in the safety analysis. Individual component response times are not modeled in the analyses. The analyses model the overall or total elapsed time, from the point at which the parameter exceeds the trip setpoint value at the sensor to the point at which the RTCBs open. Response times are conducted on an 18 month STAGGERED TEST BASIS. This results in the interval between successive tests of a given channel of \( n \times 18 \) months, where \( n \) is the number of channels in the Function. The 18 month Frequency is based upon operating experience, which has shown that random failures of instrumentation components causing serious response time degradation, but not channel failure, are infrequent occurrences. Also, response times cannot be determined at power, since equipment operation is required. Testing may be performed in one measurement or in overlapping segments, with verification that all components are tested.

REFERENCES

1. 10 CFR Part 50, Appendix A.

2. 10 CFR 50.34.

3. FSAR, Section 7.2.
B 3.3 INSTRUMENTATION

B 3.3.3 Control Element Assembly Calculators (CEACs)

BASES

BACKGROUND

The Reactor Protection System (RPS) initiates a reactor trip to protect against violating the specified acceptable fuel design limits (SAFDLs) and breaching the reactor coolant pressure boundary (RCPB) during anticipated operational occurrences (AOOs). By tripping the reactor, the RPS also assists the Engineered Safety Features Actuation Systems (ESFAS) in mitigating accidents.

The Protection and Monitoring Systems have been designed to ensure safe operation of the reactor. This is achieved by specifying limiting safety system settings (LSSS) in terms of parameters directly monitored by the RPS, as well as LCOs on other reactor system parameters and equipment performance.

The LSSS (defined in this Specification as the Allowable Values), in conjunction with the LCOs, establishes the thresholds for protection system action to prevent exceeding acceptable limits during Design Basis Accidents (DBAs).

During AOOs, which are those events expected to occur one or more times during the plant life, the acceptable limits are:

a. The departure from nucleate boiling ratio (DNBR) shall be maintained above the safety limit value to prevent departure from nucleate boiling.

b. Fuel centerline melting shall not occur.

c. The Reactor Coolant System (RCS) pressure safety limit of 193.3 kg/cm²A (2750 psia) shall not be exceeded.

Maintaining the parameters within the above values ensures that the offsite dose will be within the 10 CFR Part 50 (Ref. 1) and 10 CFR 50.34 (Ref. 2) criteria during AOOs.

Accidents are events that are analyzed even though they are not expected to occur during the plant life. The acceptable limit during accidents is that the offsite dose shall be maintained within an acceptable fraction of 10 CFR 50.34 (Ref. 2) limits. Different accident categories allow a different fraction of these limits based on probability of occurrence. Meeting the acceptable dose limit for an accident category is considered having acceptable consequences for that event.
The RPS function is performed through the portions below in the Reactor Trip System (RTS):

a. Measurement channels;
b. Bistable logics;
c. RPS logic; and
d. Reactor trip circuit breakers (RTCB).

This LCO addresses the CEACs. LCO 3.3.1 provides a description of this equipment in the RPS.

The CEACs are considered components in the measurement channels of the DNBR-Low and low power density (LPD)-High trips. The CEACs are addressed by this LCO.

Each core protection calculator (CPC) receives control element assembly (CEA) deviation penalty factors from both CEACs in that channel and uses the larger of the penalty factors from the two CEACs in the calculation of DNBR and LPD. CPCs are further described in the Background section of LCO 3.3.1.

The CEACs perform the calculations required to determine the position of CEAs within their subgroups for the CPCs. Two independent CEACs in each Core Protection Calculator System (CPCS) channel compare the position of each CEA to its subgroup position. If a deviation is detected by either CEAC, an alarm occurs and appropriate “penalty factors” are transmitted to the associated CPC processor in that channel. These penalty factors conservatively adjust the effective operating margins to the DNBR – Low and LPD – High trips.

Each CEA has two separate reed switch position transmitter (RSPT) assemblies mounted outside the RCPB, designated RSPT1 and RSPT2. CEA position from the RSPTs is processed by CEA position processors (CPPs) located in each CPCS channel. The CPPs transmit CEA position to the appropriate CEAC in all four CPCS channels over optically isolated datalinks, such that CEAC1 in all channels receives the position of all CEAs based upon RSPT1, and CEAC2 receives the position of all CEAs based upon RSPT2. Thus, the position of all CEAs is independently monitored by both CEACs in each CPCS channel.
The CPCS displays the position of each CEA to the operator on the display of Information Processing System (IPS). Each CPCS channel is connected to the display by means of an optically isolated data link. The operator can select the channel for display. Selecting channel A or B displays CEA position based upon RSPT1 on each CEA, whereas selecting channel C or D displays CEA position based upon RSPT2 on each CEA.

Functional testing of the entire RPS function, from bistable input through the opening of individual sets of reactor trip switch gears, can be performed either at power or shutdown and is normally performed on a 31 day basis. Nuclear instrumentation, the CPCs, and the CEACs can be similarly tested. Process transmitter calibration is normally performed on a refueling basis.

Each of the analyzed transients and accidents can be detected by one or more RPS Functions.

The effect of any misoperated CEA within a subgroup on the core power distribution is assessed by the CEACs, and an appropriately augmented power distribution penalty factor will be supplied as input to the CPCs. As the reactor core responds to the reactivity changes caused by the misoperated CEA and the ensuing reactor coolant and doppler feedback effects, the CPCs will initiate a DNBR – Low, or LPD – High trip signal, if SAFDLs are approached. Each CPC also directly monitors one “target CEA” from each subgroup, and uses this information to account for excessive radial peaking factors for events involving CEA groups out of sequence and subgroup deviations within a group, without the need for CEACs.

Therefore, although the CEACs do not provide a direct reactor trip Function, their input to the CPCs is taken credit for in the CEA misoperation analysis.

The CEACs satisfy Criterion 3 of 10 CFR 50.36(c)(2)(ii).
This LCO on the CEACs ensures that the CPCs are either informed of individual CEA position within each subgroup, using one or both CEACs in each channel, or that appropriate conservatism is included in the CPC calculations to account for anticipated LCO CEA deviations.

CEAC1 in all four CPC channels monitors CEA position based upon RSPT1 on all CEAs. CEAC2 in all four channels monitors CEA position based upon RSPT2 on all CEAs. Each CPC uses the higher of the two deviation penalty factors transmitted by the channel CEACs. Thus only one OPERABLE CEAC is required in each channel to provide CEA deviation protection. Because a single RSPT is used to provide RSPT input to one CEAC in all four channels, this LCO requires both CEACs to be OPERABLE in each channel so that no sensor failure resulting in CEAC failure in multiple channels can prevent a required trip from occurring.

For reliability, each CPC channel contains two CPPs, which redundantly monitor the channel RSPT inputs, perform analog to digital conversion, and transmit the CEA position to the appropriate CEAC in all four CPCS channel over separate one-way fiber optically isolated data links. The receiving CEAC will automatically switch to the backup CPP and associated data link upon failure of the preferred CPP or associated data link. CPPs in CPCS channel A or B together process all RSPT1 CEA position inputs, and transmit them to CEAC1 in all four CPC channels. Similarly, CPPs in channels C or D together process all RSPT2 position inputs, and transmit them to CEAC2 in all four CPC channels.

Operation of at least one CPP and associated data links in each CPCS channel is therefore required for both CEACs in all CPCS channels to receive CEA position information. Failure of both redundant CPPs in a channel or failure of redundant RSPT power supplies in that channel will cause the associated receiving CEACs in all channels to lose CEA position input on multiple CEAs. Failure of individual RSPTs will result in a subset of CEAs being identified as failed in the associated CEAC in multiple channels.

This LCO therefore addresses both individual channel and multiple channel CEAC inoperabilities.
CEACs
B 3.3.3

BASES

APPLICABILITY
Most RPS trips are required to be OPERABLE in MODES 1 and 2 because the reactor is critical in these MODES. The trips are designed to take the reactor subcritical, which maintains the safety limits (SLs) during AOOs, and assists the ESFAS in providing acceptable consequences during accidents. Most trips are not required to be OPERABLE in MODES 3, 4, and 5. In MODES 3, 4, and 5, the emphasis is placed on return to power events. The reactor is protected in these MODES by ensuring adequate SDM.

Because CEACs provide the inputs to the DNBR – Low and LPD – High trips, they are required to be OPERABLE in MODES 1 and 2 for the same reasons.

ACTIONS
One Note has been added to the ACTIONS. The note has been added to clarify the application of the Completion Time rules. The Conditions of this Specification may be entered independently for each CPC channel. The Completion Times of each inoperable channel will be tracked separately, starting from the time the Condition was entered for that channel.

A.1, A.2.1, and A.2.2
Condition A applies to the failure of one CEAC in one or more CPCS channels. A CEAC failure affecting a single channel could result from failure within a CEAC processor module, whereas a CEAC failure in multiple channels could be caused by failure of redundant CPPs within a CPCS channel. Thus, Condition A addresses both possibilities.

A.1
Required Action A.1 provides for declaration of affected CPCS channel inoperability within 1 hour, followed by immediate entry into the applicable Conditions and Required Actions associated with LCO 3.3.1 for the DNBR – Low and LPD – High reactor trip functions. This Required Action treats failure of a single CEAC in one or more CPCS channels in a manner consistent with other failures in one or more RPS trip function channels. Required Action A.1 may be the preferred action if only one CPCS channel is affected. If the failure affects two or more CPCS channels, Required Actions A.2.1 and A.2.2 would be preferable.

LCO 3.3.1 Conditions that were entered because of LCO 3.3.3 Required Action A.1 may only be exited by restoring the inoperable CEAC(s) to
ACTIONs (continued)

OPERABLE status, and not by "undeclaring" the inoperability of the CPCS channel(s) with the inoperable CEAC(s).

A.2.1 and A.2.2

Required Actions A.2.1 and A.2.2 accommodate a loss of CEA position monitoring capability by one CEAC in up to all four CPCS channels. There are two CEACs per CPCS channel, each providing CEA deviation input to the associated channel CPC. CEAC is able to recognize the inoperability status of CPP and CPC is able to recognize the inoperability status of CEAC. With one failed CEAC in one or more channels, the CPC in the affected channels will receive CEA deviation penalty factors from the remaining OPERABLE CEAC. The specific Required Actions are as follows.

With one CEAC inoperable in one or more channels, the second CEAC still provides penalty factor output, CEA deviation alarm and position indication for display, etc., to the affected CPC through comparison of individual CEA in subgroup. Verification every 4 hours that each CEA is within 16.8 cm (6.6 in) of the other CEAs in its group provides a check on the position of all CEAs and provides verification of the proper operation of the OPERABLE CEAC. An OPERABLE CEAC will not generate penalty factors until deviations > 25.1 cm (9.9 in) within a subgroup are encountered.

The Completion Time of 1 hour and once per 4 hours thereafter is adequate based on operating experience, considering the low probability of an undetected CEA deviation coincident with an undetected failure in the remaining CEAC within this limited time frame.

As long as Required Action A.2.1 is accomplished as specified, the inoperable CEAC can be restored to OPERABLE status within 7 days. The Completion Time of 7 days is adequate for most repairs, while minimizing risk, considering that dropped CEAs are detectable by the redundant CEAC, and other LCOs specify Required Actions necessary to maintain DNBR and LPD margin.

B.1, B.2.1, B.2.2, B.2.3, B.2.4, and B.2.5

Condition B applies if a Required Action and associated Completion Time of Condition A are not met, or if both CEACs are inoperable in one or more CPCS channels. The Required Actions associated with this Condition involve two choices.
Bases

Actions (continued)

a. Required Action B.1 requires that the affected CPCS channels be considered inoperable within 1 hour, thus requiring entry into the applicable Conditions and Required Actions associated with LCO 3.3.1.

b. Required Action B.2.1 through B.2.5 disable the Digital Rod Control System (DRCS), while providing increased assurance that CEA deviations are not occurring and informing all OPERABLE CPCS channels, via a software flag, that both CEACs are failed. This will ensure that the large penalty factor associated with two CEAC failures will be applied to the CPC calculations. The penalty factor for two failed CEACs is sufficiently lower than 100% RTP if CPC generated reactor trips are to be avoided. The Completion Time of 4 hours is adequate to accomplish these actions while minimizing risks.

The Required Actions are as follows.

B.1

Required Action B.1 provides for declaration of affected CPCS channel inoperability within 1 hour, followed by immediate entry into the applicable Conditions and Required Actions associated with LCO 3.3.1 for the DNBR – Low and LPD – High reactor trip functions. This Required Action treats failure of both CEACs in one or more CPCS channels in a manner consistent with other failures in one or more RPS trip function channels. Required Action B.1 also applies if a Required Action and associated Completion Time of Condition A are not met, and similarly permits declaration of CPCS channel inoperability within 1 hour followed by immediate entry into the applicable Conditions and Required Actions of LCO 3.3.1. Required Action B.1 may be the preferred action if only one CPCS channel is affected. If the CEAC failure(s) affect two or more CPCS channels, Required Action B.2.1 through B.2.5 would be preferable.

LCO 3.3.1 Conditions that were entered because of LCO 3.3.3 Required Action B.1 may only be exited by restoring the inoperable CEAC(s) to OPERABLE status, and not by "undeclaring" the inoperability of the CPCS channel(s) with the inoperable CEAC(s).

B.2.1

A comprehensive set of comparison checks on individual CEAs within groups must be made within 4 hours. Verification that each CEA is within 16.8 cm (6.6 in) of other CEAs in its group provides a check that no CEA has deviated from its proper position within the group.
Meeting the margin requirements of DNBR in LCO 3.2.4 ensures that power level is within a conservative region of operation based on actual core conditions. In addition to the above actions, Reactor Power Cutback System (RPCS) must be disabled. This ensures that CEA positions will not be affected by RPCS operation.

The upper electrical limit (UEL) CEA reed switches provide an acceptable indication of CEA position. The CEA must be maintained fully withdrawn, except as required for specified testing or flux control via group #5. This ensures that undesired perturbations in local fuel burnup are prevented.

The “RSPT/CEAC Inoperable” addressable constant in each of the CPCs is set to indicate that both CEACs are inoperable. This provides a conservative penalty factor to ensure that a conservative effective margin is maintained by the CPCs in the computation of DNBR and LPD trips.

The DRCS is placed and maintained in “standby,” except during CEA motion permitted by Required Action B.2.2, to prevent inadvertent motion and possible misalignment of the CEAs.

Condition C is entered when the Required Action and Completion Time in relation to Condition B are not met.

If the Required Actions associated with this Condition cannot be completed within the required Completion Times, the reactor must be brought to a MODE where the Required Actions are not applied. The Completion Time of 6 hours is reasonable, based on operating experience, for reaching the required MODE from full power conditions in an orderly manner without challenging plant systems.
Performance of the CHANNEL CHECK once every 12 hours ensures that gross failure of instrumentation has not occurred. A CHANNEL CHECK is normally a comparison of the parameter indicated on one channel to a similar parameter on another channel. It is based on the assumption that instrument channels monitoring the same parameter should indicate approximately the same value.

Significant deviations between the two instrument channels could be an indication of excessive instrument drift in one of the channels or of something even more serious. CHANNEL CHECK will detect gross channel failure; thus, it is a key to verifying that the instrumentation continues to operate properly between each CHANNEL CALIBRATION.

Agreement criteria are determined by the plant staff, based on a combination of the channel instrument uncertainties, including indication and readability. If a channel is outside the criteria, it could be an indication that the sensor or the signal processing equipment has drifted outside its limits. If a channel is within the criteria, it means that the channel is OPERABLE.

The Frequency, about once every shift, is based on operating experience that demonstrates the rarity of channel failure. Since the probability of two random failures in redundant channels in any 12 hour period is extremely low, the CHANNEL CHECK minimizes the chance of loss of protection function due to failure of redundant channels. Channel OPERABILITY is verified by using channel related indication value requested in LCO through CHANNEL CHECK during normal operation period.

The CPC System Event Log is checked every 12 hours to monitor the CPCS channel performance. The system event log provides an historical record of the last thirty detected CPC channel error conditions including error conditions affecting the CEAC performance. A detected error condition may not render a channel inoperable, unless it is accompanied by a CPC Fail indication.

The Frequency of 12 hours is based upon the nature of the surveillance in detecting many non-critical error conditions, and considers that detectable failures resulting in channel inoperability will result in a CPC Fail condition.
SURVEILLANCE REQUIREMENTS (continued)

**SR 3.3.3.3**

A CHANNEL FUNCTIONAL TEST on each CEAC channel is performed every 31 days to ensure the entire channel will perform its intended function when needed. The CHANNEL FUNCTIONAL TEST is performed by using a maintenance and test panel (MTP).

**SR 3.3.3.4**

CHANNEL CALIBRATION is performed every 18 months according to SR 3.3.3.4. CHANNEL CALIBRATION is a complete check of the instrument channel including the sensor. The Surveillance verifies that the channel responds to a measured parameter within the necessary range and accuracy. CHANNEL CALIBRATION leaves the channel adjusted to account for instrument drift between successive calibrations to ensure that the channel remains operational between successive Surveillances. CHANNEL CALIBRATION must be performed consistent with the CPCS specific setpoint analysis.

The amount of equipment drift assumed in setpoint calculations is based on using an 18 month calibration cycle, which is based on operational experience and an 18 month fuel cycle.

**SR 3.3.3.5**

Every 18 months, a CHANNEL FUNCTIONAL TEST is performed on the CEACs. The CHANNEL FUNCTIONAL TEST shall include the injection of a signal as close to the sensors as practical to verify OPERABILITY, including alarm and trip Functions.

The basis for the 18 month Frequency is that the CEACs perform a continuous self-monitoring function that eliminates the need for frequent CHANNEL FUNCTIONAL TESTS. This CHANNEL FUNCTIONAL TEST essentially validates the self-monitoring function and checks for a small set of failure modes that are undetectable by the self-monitoring function. Operating experience has shown that undetected CPC or CEAC failures do not occur in any given 18 month interval.

**REFERENCES**

1. 10 CFR Part 50.
2. 10 CFR 50.34.
B 3.3 INSTRUMENTATION

B 3.3.4 Reactor Protection System (RPS) Logic and Trip Initiation

BASES

BACKGROUND

The RPS initiates a reactor trip to protect against violating the core specified acceptable fuel design limits and breaching the reactor coolant pressure boundary (RCPB) during anticipated operational occurrences (AOOs). By tripping the reactor, the RPS also assists the Engineered Safety Features (ESF) Systems in mitigating accidents.

The Protection and Monitoring Systems have been designed to ensure safe operation of the reactor. This is achieved by specifying limiting safety system settings (LSSS) in terms of parameters directly monitored by the RPS, as well as LCOs on other reactor system parameters and equipment performance.

The LSSS, defined in this Specification as the Allowable Value, in conjunction with the LCOs, establishes the threshold for protection system action to prevent exceeding acceptable limits during design basis events (DBEs).

During AOOs, which are those events expected to occur one or more times during the plant life, the acceptable limits are:

a. The departure from nucleate boiling ratio (DNBR) shall be maintained above the safety limit (SL) value to prevent departure from nucleate boiling (DNB).

b. Fuel centerline melting shall not occur.

c. The Reactor Coolant System (RCS) pressure SL of 193.3 kg/cm²A (2,750 psia) shall not be exceeded.

Maintaining the parameters within the above values ensures that the offsite dose will be within the 10 CFR Part 50, Appendix A (Ref. 1) and 10 CFR 50.34 (Ref. 2) criteria during AOOs.

Accidents are events that are analyzed even though they are not expected to occur during the plant life. The acceptable limit during accidents is that the offsite dose shall be maintained within an acceptable fraction of 10 CFR 50.34 (Ref. 2) limits.
Different accident categories allow a different fraction of these limits based on probability of occurrence. Meeting the acceptable dose limit for an accident category is considered having acceptable consequences for that event.

The Reactor Trip System (RTS) is a safety system which initiates reactor trips. The RTS consists of four channels of sensors, auxiliary process cabinet-safety (APC-S) cabinets, Excore Neutron Flux Monitoring System (ENFMS) cabinets, Core Protection Calculator System (CPCS) cabinets, the RPS portion of Plant Protection System (PPS) cabinets, and Reactor Trip Switchgear System (RTSS) cabinets.

The RPS function is performed through the below portions in the RTS:

a. Measurement channels;

b. Bistable logics;

c. RPS logic; and

d. Reactor trip circuit breakers (RTCBs).

This LCO addresses the RPS logic and RTCBs, including manual trip capability. Measurement channels and bistable logics are described in LCO 3.3.1, “Reactor Protection System (RPS) Instrumentation – Operating.” LCO 3.3.1 provides a description of the role of this equipment in the RPS. This is summarized below:

RPS Logic

The RPS logic consists of both local coincidence and initiation logic includes watchdog timer monitoring the heartbeat signal of local coincidence logic (LCL) processor located in initiation circuit. The RPS logic employs a scheme that provides a reactor trip when bistables in any two of the four channels sense the same input parameter trip. This is called a 2-out-of-4 trip logic.

Each LCL receives four trip signals, one from its associated bistable logic in the channel and one from each of the equivalent bistable logic located in the other three channels. The LCL also receives the trip channel bypass status associated with each of the above mentioned bistables. The function of the LCL is to generate a coincidence signal whenever two or more like bistables are in a tripped condition.
The LCL takes into consideration the trip bypass input state when determining the coincidence logic state. Designating the protection channels as A, B, C, D, with no trip bypass present, the LCL will produce a coincidence signal for any of the following trip inputs: AB, AC, AD, BC, BD, CD, ABC, ABD, ACD, BCD, ABCD. These represent all possible two- or more out-of-four trip combinations of the four protection channels. Should a trip bypass be present, the logic will provide a coincidence signal when two or more of the three un-bypassed bistables are in a tripped condition.

On a system basis, a coincidence signal is generated in all four protection channels whenever a coincidence of two or more like bistables of the four channels are in a tripped state.

In addition to a coincidence signal, each LCL also provides bypass status outputs. The bypass status is provided to verify that a bypass has actually been entered into the logic either locally or remotely via the maintenance and test panel or the operator’s module.

The inputs to the initiation logic are the LCL outputs from the appropriate LCLs. The LCL outputs are arranged in the initiation circuit to provide selective 2-out-of-4 coincidence. This configuration will avoid spurious channel initiation in the event of a single LCL processor or digital output module failure.

The RPS initiation logic consists of an “OR” circuit for each undervoltage and de-energizes interposing relays. Each interposing relay opens one RTCB in turn.

It is possible to change the 2-out-of-4 RPS logic to a 2-out-of-3 logic for a given input parameter in one channel at a time by trip channel bypassing.

Thus, the bistable logic will function normally, producing normal trip indication and announcement, but a reactor trip will not occur unless two additional channels indicate a trip condition. Trip channel bypassing can be simultaneously performed on any number of parameters in any number of channels, providing each parameter is bypassed in only one channel at a time. Bypassing the same parameter in more than one channel is restricted by the administrative procedure. The coincidence logic becomes 2-out-of-3 coincidence logic. The all-bypass function for bypassing all parameters in the channel is interlocked in LCL algorithm to prevent simultaneous bypass of more than one channel. The all-bypass interlock is implemented based on analog circuit through hardwired cable between LCLs in all channels. The
purpose of the all-bypass function is to support testing and maintenance of bistable processor (BP) whereas the trip channel bypass is used for sensor failure.

**RTCBB**

The RTSS consists of two sets of four RTCBs, RTSS-1 and RTSS-2, connected in series (i.e., eight RTCBs in total), which are operated in four sets (i.e., channels A, B, C, and D) of two RTCBs each. RTSS-1 contains four RTCBs designated A1, B1, C1, and D1 arranged in two parallel trip legs (A1 and B1; C1 and D1) (A trip leg contains two RTSS circuit breakers in series.) RTSS-2 contains four RTCBs designated A2, B2, C2, and D2 also arranged in two parallel trip legs (A2 and C2; B2 and D2). Opening one RTCB in each trip leg of RTSS-1 or RTSS-2 interrupts power to all control element drive mechanisms (CEDMs).

Power input to the CEDMs by way of RTSS-1 and RTSS-2 and the Digital Rod Control System (DRCS) comes from two full capacity motor generator (MG) sets operated in parallel, such that the loss of either MG set does not de-energize the CEDMS. Power is supplied from the MG sets to the CEDMS via two trip legs (redundant paths) in RTSS-1 and two trip legs in RTSS-2, with RTSS-1 and RTSS-2 connected in series. This arrangement of the eight RTCBs ensures that a fault, or the opening of an RTSS-1 RTCB in one trip leg (i.e., for testing purposes) coincident with a fault, or the opening of an RTSS-2 RTCB in one trip leg will not interrupt power to the CEDMs. With two channels in trip for the same RPS Function, at least one RTCB will be opened in both trip legs of either RTSS-1 or RTSS-2. Two separate methods for opening each RTSS circuit breaker are provided, the undervoltage trip device and the shunt trip device. The two RTCBs within a trip leg are actuated by separate RPS initiation logic circuits. When electrical power to the two CEDM power supply buses is lost, all CEAs will fall into the core by gravity. The PPS interfaces with the undervoltage trip device of the RTCBs. The Diverse Protection System (DPS) interfaces with the shunt trip device of the RTCBs. The actuation of either the undervoltage or the shunt trip device interrupts power from the MG sets to the CEDMS.

Each set of RTCBs is operated by either a manual reactor trip switch or an interposing relay actuated by RPS. There are four manual trip switches, arranged in two sets of two. Depressing both switches in either set will result in a reactor trip. When a manual trip is initiated using manual switches in the main control room (MCR), the RPS trip paths and relays are bypassed, and the RTCB undervoltage and shunt trip devices are actuated independent of the RPS.
Manual trip circuitry includes the switches and interconnecting wiring to both RTCBs necessary to actuate both the undervoltage and shunt trip devices but excludes the interposing relay contacts and their interconnecting wiring to the RTCBs, which are considered part of the initiation circuit.

Functional testing of the entire RPS, from bistable logic input through the opening of individual sets of RTCBs, can be performed either at power or shut down and is normally performed on a 31 day basis. FSAR, Section 7.2 (Ref. 3), explains RPS testing in more detail.

**Reactor Protection System (RPS) Logic**

The RPS logic provides for automatic trip initiation to maintain the SLs during AOOs and assist the ESF Systems in ensuring acceptable consequences during accidents. All transients and accidents that call for a reactor trip assume the RPS logic is functioning as designed.

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**APPLICABLE SAFETY ANALYSES**

**Reactor Trip Circuit Breakers (RTCBs)**

All of the transient and accident analyses that call for a reactor trip assume that the RTCBs operate and interrupt power to the CEDMs.

**Manual Trip**

There are no accident analyses that take credit for the manual trip; however, the manual trip is part of the RPS circuitry. It is used by the operator to shut down the reactor whenever any parameter is rapidly trending toward its trip setpoint. A manual trip accomplishes the same results as any one of the automatic trip functions.

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**LCO**

**Reactor Protection System (RPS) Logic**

The LCO on the RPS logic channels ensures that each of the following requirements are met:

a. A reactor trip will be initiated when necessary.

b. The required protection system coincidence logic is maintained (minimum 2-out-of-3, normal 2-out-of-4).

c. Sufficient redundancy is maintained to permit a channel to be out of service for testing or maintenance.
Failures of individual bistable logics are addressed in LCO 3.3.1.

This Technical Specification (TS) addresses failures of the RPS logic not addressed in the above, such as the failure of LCL power supplies or the failure of the trip channel bypass in the bypass condition.

Loss of a single vital bus will de-energize one of the power supplies in each LCL Channel. This will result in two RTCB opening. However, the remaining six closed RTCBs will prevent a reactor trip. For the purposes of this LCO, de-energizing up to the affected channel power supplies due to a single failure is to be treated as a single channel failure, providing the affected coincidence logic operates as designed and opens the affected RTCBs.

Each LCL receives four trip signals, one from its associated bistable logic in the channel and one from each of the equivalent bistable logic located in the other three channels. On a system basis, a coincidence signal is generated in all four protection channels whenever a coincidence of two or more like bistables of the four channels are in a tripped state. The inputs to the initiation logic are the LCL outputs from the appropriate LCLs. The LCL outputs are arranged in the initiation circuit to provide selective 2-out-of-4 coincidence. The reactor protection system initiation logic consists of an “OR” circuit for each undervoltage relay and de-energizes interposing relays. Each interposing relay opens one RTCB in turn.

If a coincidence logic power supply or vital instrument bus in a channel fails, two interposing relays in the affected channel are de-energized. This will result in opening the affected RTCB.

If two RTCBs in a channel have been opened in response to a single RTCB channel, initiation logic channel, or manual trip channel failure, the affected RTCB may be closed for up to 1 hour for Surveillance on the initiation logic channel, RTCB, and manual trip channels. In this case, the redundant RTCB will provide protection if a trip should be required.

1. **Coincidence Logic**

This LCO requires four coincidence logic channels to be OPERABLE in MODES 1 and 2, and in MODES 3, 4, and 5 when the RTCBs are closed and any CEA is capable of being withdrawn.
2. **Initiation Logic**

This LCO requires four initiation logic channels to be OPERABLE in MODES 1 and 2, and in MODES 3, 4, and 5 when the RTCBs are closed and any CEA is capable of being withdrawn.

3. **RTCB**

The LCO requires four RTCB channels to be OPERABLE in MODES 1 and 2, and in MODES 3, 4, and 5 when the RTCBs are closed and any CEA is capable of being withdrawn.

Each channel of RTCBs starts at the interposing relay contact and the manual trip contact for each breaker. Manual trip contacts and upstream circuitry are considered to be manual trip circuitry.

A Note associated with the ACTIONS states that if one RTCB has been opened in response to a single RTCB channel, initiation logic channel, or manual trip channel failure, the affected RTCB may be closed for up to 1 hour for Surveillance on the OPERABLE initiation logic, RTCB, and manual trip channels.

4. **Manual Trip**

The LCO requires all four manual trip channels to be OPERABLE in MODES 1 and 2, and MODES 3, 4, and 5 when the RTCBs are closed and any control element assembly (CEA) is capable of being withdrawn.

Two independent sets of two adjacent switches are provided at separate locations. Each switch is considered a channel and operates two of the eight RTCBs. Depressing both push switches in either set will cause an interruption of power to the CEDMs, allowing the CEAs to fall into the core. This design ensures that no single failure in any push switch circuit can either cause or prevent a reactor trip.

Manual trip switches are also provided at the RTCB (locally) in case the MCR push buttons become inoperable or the MCR becomes uninhabitable. These are not part of the RPS and cannot be credited in fulfilling the LCO OPERABILITY requirements. Furthermore, LCO 3.3.4 ACTIONS need not be entered due to failure of a local manual trip.
APPLICABILITY
The RPS logic channels (coincidence logic, initiation logic), RTCBs, and manual trip channels are required to be OPERABLE in MODES 1 and 2 and MODES 3, 4, and 5 when the CEAs are capable of being withdrawn and RTCBs are closed. RPS instrument in MODES 1 and 2 is described in LCO 3.3.1. When the CEAs are capable of being withdrawn and RTCBs are closed, RPS instrument in MODES 3, 4, and 5 are described in LCO 3.3.2. Control element assembly calculator (CEAC) in MODES 1 and 2 is described in LCO 3.3.3.

The RPS logic, RTCBs, and manual trip are required to be OPERABLE in any MODE when any CEA is capable of being withdrawn from the core (i.e., RTCBs closed and power available to the CEDMs). This ensures the reactor can be tripped when necessary, but allows for maintenance and testing when the reactor trip is not needed.

In MODES 3, 4, and 5 with all the RTCBs open, the CEAs are not capable of withdrawal and these Functions do not have to be OPERABLE.

However, two logarithmic power level channels must be OPERABLE to ensure proper indication of neutron population and indicate a boron dilution event. This is addressed in LCO 3.3.14, “Boron Dilution Alarm.”

ACTIONS
When the number of inoperable channels in a trip Function exceeds that specified in any related Condition associated with the same trip Function, then the plant is outside the safety analysis. Therefore, LCO 3.0.3 is immediately entered if applicable in the current MODE of operation.

A.1
Condition A applies to one coincidence logic channel, one initiation logic channel, RTCB channel, or manual trip channel in MODES 1 and 2, since they have the same ACTIONS. MODES 3, 4, and 5, with the RTCBs closed, are addressed in Condition B. These Required Actions require opening the affected RTCBs.

This removes the need for the affected channel by performing its associated safety function. With an RTCB open, the affected Functions are in 2-out-of-3 logic, which meets redundancy requirements, but testing on the OPERABLE channels cannot be performed without causing a reactor trip unless the RTCBs in the inoperable channels are closed to permit testing.

Therefore, a Note has been added, specifying that the RTCBs associated with one inoperable channel may be closed for up to 1 hour for the performance of an RPS CHANNEL FUNCTIONAL TEST.
BASES

ACTIONS (continued)

Required Action A.1 provides for opening the RTCBs associated with the inoperable channel within a Completion Time of 1 hour. This Required Action is conservative, since depressing the manual trip switch associated with either set of breakers in the other channels will cause a reactor trip. With this configuration, a single channel failure will not prevent a reactor trip. The allotted Completion Time is adequate for opening the affected RTCBs while maintaining the risk of having them closed at an acceptable level.

B.1

Condition B applies to the failure of one initiation logic channel, RTCB channel, or manual trip channel in MODE 3, 4, or 5 with the RTCBs closed. The channel must be restored to OPERABLE status within 48 hours. If the inoperable channel cannot be restored to OPERABLE status within 48 hours, the affected RTCBs must be opened so the affected functions are one-out-of-two logic which meets redundancy requirements.

The Completion Time of 48 hours is adequate to repair most failures.

Testing on the OPERABLE channels cannot be performed without causing a reactor trip, unless the RTCBs in the inoperable channels are closed to permit testing. Therefore, a Note has been added specifying that the RTCBs associated with one inoperable channel may be closed for up to 1 hour for the performance of an RPS CHANNEL FUNCTIONAL TEST.

C.1 and C.2

Condition C is entered if Required Actions associated with Condition A are not met within the required Completion Time or if for one or more functions, more than one logic (coincidence logic, initiation logic), manual trip channel, or RTCB channel is inoperable.

If the RTCBs associated with the inoperable channel cannot be opened, the reactor must be shut down within 6 hours and all the RTCBs opened. A Completion Time of 6 hours is reasonable, based on operating experience, for reaching the required plant conditions from full power conditions in an orderly manner and without challenging plant systems and for opening RTCBs. All RTCBs should then be opened, placing the plant in a MODE where the LCO does not apply and ensuring no CEA withdrawal occurs.
SURVEILLANCE REQUIREMENTS

The OPERABILITY of the interface and test processor (ITP) is not required by LCO 3.3.4 because the RPS does not need the ITP to perform the safety function of RPS. However, the ITP must be maintained capable of supporting performance of the CHANNEL FUNCTIONAL TEST of SRs 3.3.4.1 and 3.3.4.2.

SR 3.3.4.1

A CHANNEL FUNCTIONAL TEST on each channel is performed every 31 days to ensure the entire channel will perform its intended function when needed.

The RPS CHANNEL FUNCTIONAL TEST consists of overlapping tests as described in FSAR, Section 7.2 (Ref. 3). These tests verify that the RPS is capable of performing its intended function, from bistable input through the RTCBs.

Bistable logic test is described in SR 3.3.1.7. This SR describes two kinds of test related to RPS logic which includes coincidence logic and trip path (initiation logic).

LCL Testing

LCL testing is performed to verify the OPERABILITY of 2-out-of-4 logic and trip channel bypass logic. The LCL test is initiated manually from the maintenance and test panel (MTP). The trip path of 2-out-of-4 coincidence logic is tested for all input combinations.

Trip Path Testing

The RTCB test is a manually initiated test. The test is manually initiated because the test philosophy requires operator involvement in the testing and reclosing of these important reactor trip devices. The operator can obtain status information from the breaker open/close indication and current monitors and thus determine the success or failure of the test. The RTCBs must then be closed prior to testing the other three initiation circuits, or a reactor trip could result.

SR 3.3.4.2

Each RTCB is actuated by an undervoltage coil and a shunt trip coil. De-energizing the undervoltage coil or energizing the shunt trip coil will cause the circuit breaker to open. The PPS interfaces with the undervoltage trip device of RTCBs. The DPS interfaces with the shunt trip device of the RTCBs. The actuation of either the undervoltage or the shunt trip device interrupts power from the MG sets to the CEDMs.
When an RTCB is opened, either during an automatic reactor trip or by using the manual push switches in the MCR, the undervoltage coil is de-energized and the shunt trip coil is energized. This makes it possible to determine if one of the coils or associated circuitry is defective.

Therefore, once every 18 months, a CHANNEL FUNCTIONAL TEST is performed, that individually tests all four sets of undervoltage coils and all four sets of shunt trip coils. During undervoltage coil testing, the shunt trip coils must remain de-energized, preventing their operation. Conversely, during shunt trip coil testing, the undervoltage coils must remain energized, preventing their operation.

This Surveillance ensures that every undervoltage coil and every shunt trip coil is capable of performing its intended function, and that no single active failure of any RTCB component will prevent a reactor trip. The 18 month Frequency is based on the need to perform this Surveillance under the conditions that apply during a plant outage and the potential for an unplanned transient if the Surveillance were performed with the reactor at power. Operating experience has shown these components usually pass the Surveillance when performed at the Frequency of once every 18 months.

SR 3.3.4.3

A CHANNEL FUNCTIONAL TEST on the Manual Trip channels is performed periodically once every 31 days to ensure the entire channel will perform its intended function if required. Manual trip testing is performed to verify that the RTCBs can be manually operated as designed. The 31 day Surveillance period has been determined based on operating experience to be an adequate period of time to provide assurance that the RPS manual trip channel can satisfactorily perform its intended function.

REFERENCES

1. 10 CFR Part 50, Appendix A.
2. 10 CFR 50.34.
3. FSAR, Section 7.2.
B 3.3 INSTRUMENTATION

B 3.3.5 Engineered Safety Features Actuation System (ESFAS) Instrumentation

BASES

BACKGROUND

The ESFAS initiates necessary safety systems, based upon the values of selected unit parameters, to protect against violating core design limits and Reactor Coolant System (RCS) pressure boundary during anticipated operational occurrences (AOOs) and ensures acceptable consequences during accidents.

The ESFAS contains devices and circuitry that generate the following signals when monitored variables reach levels that are indicative of conditions requiring protection action:

1. Safety injection actuation signal (SIAS),
2. Containment spray actuation signal (CSAS),
3. Containment isolation actuation signal (CIAS),
4. Main steam isolation signal (MSIS), and
5, 6. Auxiliary feedwater actuation signal (AFAS).

The equipment actuated by each of the above signals is identified in the FSAR, Section 7.3 (Ref. 1).

The Engineered Safety Features (ESF) Actuation System consists of four channels of sensors, auxiliary process cabinets – safety (APC-S), the ESFAS signal generation portion of the Plant Protection System (PPS) cabinets and the ESF Component Control System (ESF-CCS).

The devices and circuitry that generate the above ESFAS signals are grouped into the following interconnected parts. These parts are:

- Measurement channels,
- Bistable logic processor channels, and
- ESFAS logic channels:
  - Coincidence Logic,
  - Initiation Logic (trip paths), and
  - Actuation Logic.
This LCO addresses measurement channels and bistable logic processor channels. ESFAS logic channels are addressed in LCO 3.3.6, “Engineered Safety Features Actuation System (ESFAS) Logic and Manual Trip.”

The role of each of these interconnected parts of the ESFAS, including the ESFAS logic, which is also described in LCO 3.3.6, is discussed below.

**Measurement Channels**

Measurement channels, consisting of the sensor, transmitter and signal conditioning devices provide a measurable electronic signal based upon the physical characteristics of the parameter being measured.

Four identical measurement channels with electrical and physical separation are provided for each parameter used in the generation of trip signals. These channels are designated A through D. Measurement channels provide input to ESFAS bistable processors within the same ESFAS channel. In addition, some measurement channels are used as inputs to Reactor Protection System (RPS) bistable processors and provide indication in the main control room (MCR).

When a channel monitoring a parameter indicates an unsafe condition, the bistable monitoring the parameter in that channel will trip. Tripping two or more channels of Nuclear Steam Supply System (NSSS) ESFAS bistables monitoring the same parameter will generate initiation signal in local coincidence logic. This causes both channels of actuation logic to respond. Each channel of actuation logic controls one train of the associated ESF equipment.

Three of the four measurement channels and bistable processors are necessary to meet the redundancy and testability of 10 CFR Part 50, Appendix A, GDC 21 (Ref. 2).

The fourth channel provides additional flexibility, by allowing one channel to be removed from service for maintenance or testing, while still maintaining a minimum 2-out-of-3 logic.

Since no single failure will prevent a protection system actuation, this arrangement meets the requirements of IEEE 603 (Ref. 3).
Bistable Logic Processors

The bistable trip unit, mounted in the Plant Protection System (PPS) cabinet, receives an analog input from the measurement channels. The analog signal then converted into digital in the analog input module of bistable processor. The bistable trip algorithm decides the pretrip and trip status. Each output status is derived through comparing the digitalized process values by analog-digital (A/D) converter to the setpoints (pretrip and trip). The output status of bistable trip logic is provided to the local coincidence logic. In addition, the status is provided for trip indication and remote alarm.

There are four bistable logic channels for each ESFAS function corresponding to each measurement channel (A, B, C, and D). When two ESFAS functions share the same input and trip setpoints (e.g., containment pressure being inputted to CIAS and SIAS), bistable logic output in one channel can be used for two safety Functions. Similarly, RPS and ESFAS can share bistable logic (e.g., Pressurizer Pressure – Low inputs to RPS and SIAS). When a trip occurs, each bistable logic channel provides a trip output signal to the corresponding coincidence logic. The trip status in one channel is sent to the local coincidence logic in the other channels through fiber-optic links for isolation.

The local coincidence logic (2-out-of-4 logic) generates the ESFAS initiation signal when two or more bistable logics are in tripped condition. The trip setpoints and Allowable Values used in the bistables based on the analytical limits stated in Chapter 15 (Ref. 4). The selection of these trip setpoints is such that adequate protection is provided when all sensor and processing time delays are taken into account.

To allow for calibration tolerances, instrumentation uncertainties, instrument drift, and severe environment effects, for those ESFAS channels that must function in harsh environments as defined by 10 CFR 50.49 (Ref. 5), Allowable Values specified in Setpoint Control Program (SCP), in the accompanying LCO, are conservatively adjusted with respect to the analytical limits. The actual nominal trip setpoint entered into the bistable is normally still more conservative than that specified by the Allowable Value to account for changes in random measurement errors detectable by a CHANNEL FUNCTIONAL TEST. A channel is inoperative if its actual trip setpoint is not within its required Allowable Value.
Setpoints in accordance with the Allowable Value will ensure that Safety Limits (SLs) are not violated during AOOs and the consequences of design basis accidents (DBAs) will be acceptable, providing the plant is operated from within the LCOs at the onset of the AOO or DBA and the equipment functions as designed.

Functional testing of the ESFAS, from the bistable input through the output to the ESFAS actuation logic, can be performed either at power or shut down, and is normally performed on a monthly basis (31 days). FSAR, Section 7.2 (Ref. 6) provides more detail on ESFAS testing. Process transmitter calibration is normally performed on a refueling basis.

ESFAS Logic

The ESFAS logic, consisting of coincidence, initiation and actuation logic, employs a scheme that provides an ESFAS actuation signal from all four PPS divisions to the component control logic of all trains of the associated ESF Systems when any two of the four bistable logic processor channels sense that the same input parameter has satisfied the ESFAS Function’s trip setpoint on the input parameter. This logic scheme is called a 2-out-of-4 trip logic.

Each local coincidence logic (LCL) receives four trip signals, one for its associated bistable logic in the channel and one from each of the equivalent bistable logic located in the other three channels. The LCL receives the trip channel bypass status associated with each of the above mentioned bistables. The function of the LCL is to generate a coincidence signal whenever two or more like bistables are in a tripped condition. The LCL takes into consideration the trip bypass input state when determining the coincidence logic state. Designating the protection channels as A, B, C, D, with no trip bypass present, the LCL will produce a coincidence signal for any of the following trip inputs: AB, AC, AD, BC, BD, CD, ABC, ABD, ACD, BCD, ABCD. These represent all possible two- or more out-of-four trip combinations of the four protection channels. Should a trip bypass be present, the logic will provide a coincidence signal when two or more of the three un-bypassed bistables are in a tripped condition.

On a system basis, a coincidence signal is generated in all four protection channels whenever a coincidence of two or more like bistables of the four channels are in a tripped state. The local coincidence trip output in coincidence logic is used as an input to the initiation logic. This signal is sent to actuation logic in each channel of ESF-CCS.
The actuation logic in each channel of ESF-CCS takes part in actuating the equipment of the corresponding ESF train. Each ESFAS Function has individual actuation logic in each channel of the ESF-CCS.

The initiation logic performs the logical “OR” of LCL outputs for each ESFAS Function, to generate the ESF actuation signal to the ESF-CCS actuation logic.

Each ESFAS Function has an associated group of outputs. Each group of outputs is divided into subgroups. Outputs within a subgroup are tested concurrently and are selectively arranged so that concurrent actuation does not adversely affect plant operations. The initiation and actuation logics to the subgroups are addressed in LCO 3.3.6.

By trip channel bypassing one input parameter for a channel, the 2-out-of-4 ESFAS coincidence logic shall be converted to 2-out-of-3. Though the bypass produces trip indication and alarm in the bistable processor, the LCL does not accept the corresponding input signal as an input for actuation. Different parameters may be simultaneously bypassed, either in one channel or in different channels. Bypassing the same parameter in more than one channel is restricted by administrative procedure. The coincidence logic becomes 2-out-of-3 coincidence logic. The all-bypass function for bypassing all parameters in an ESFAS channel is interlocked in the LCL algorithm to prevent simultaneous bypass of more than one channel. The all-bypass function interlock is implemented with an analog circuit and hardwired cable between the LCLs in all channels. The purpose of the all-bypass function is to support testing and maintenance of the bistable processor (BP) whereas the trip channel bypass is used in case of sensor failure.

In addition to the trip channel bypasses, there are also operating bypasses for ESFAS actuation trip. These bypasses are enabled manually, in all four channels, when plant conditions do not warrant the specific trip protection. All operating bypasses are automatically removed when enabling bypass conditions are no longer satisfied.

An enabled operating bypass function blocks the output of trip and alarm signals from the bistable processor to the LCL, Information Processing System (IPS), and Qualified Indication and Alarm System - Non-Safety (QIAS-N). The Pressurizer Pressure – Low input to the SIAS shares an operating bypass with the Pressurizer Pressure – Low reactor trip.

The operating bypass inhibits the trip and pre-trip outputs from the trip and pre-trip algorithms in the bistable processor. The loss of (vital ac) electrical power to two PPS divisions generates ESF initiation signals.
which are provided to the ESF-CCS GC in each division. At that time, an enabled operating bypass in a deenergized PPS division returns to the normal state (disabled). An enabled operating bypass in an unaffected PPS division (power remains) will stay in the bypassed state. In both cases, the plant will be in a safe condition since deenergization of two PPS divisions causes the ESF equipment to be actuated if the selective 2/4 coincidence logic in the ESF-CCS GC is met.

When necessary, the operator can manually actuate the ESFAS in the MCR and local panel.

Each of the analyzed accidents can be detected by one or more ESFAS Functions. One of the ESFAS Functions is the primary actuation signal for that accident. An ESFAS Function can be the primary actuation signal for more than one type of accident. An ESFAS Function can also be the secondary, or backup, actuation signal for one or more other accidents.

ESFAS protection Functions are as follows:

1. Safety Injection Actuation Signal (SIAS)

   SIAS ensures acceptable consequences during large break loss of coolant accidents (LOCAs), small break LOCAs, control element assembly (CEA) ejection accidents, steam generator tube rupture, and main steam line breaks (MSLBs). To provide the required protection, either a high containment pressure or a low pressurizer pressure signal will initiate SIAS. The SIAS initiates the Safety Injection System (SIS) and actuates emergency diesel generator (EDG).

2. Containment Spray Actuation Signal (CSAS)

   CSAS actuates containment spray, preventing containment overpressurization during large break LOCAs, small break LOCAs, and MSLBs or main feedwater line breaks (MFLBs) inside containment. CSAS is initiated by high containment pressure.

3. Containment Isolation Actuation Signal (CIAS)

   CIAS ensures acceptable mitigating actions during large and small break LOCAs, and MSLBs inside containment or MFLBs either inside or outside containment. CIAS is initiated by low pressurizer pressure or high containment pressure.
APPLICABLE SAFETY ANALYSES (continued)

4. Main Steam Isolation Signal (MSIS)

MSIS ensures acceptable consequences during an MSLB, small LOCA, or MFLB (between the steam generator and the main feedwater check valve), either inside or outside containment. MSIS isolates both steam generators if either steam generator indicates a low pressure condition, if a high containment pressure condition exists or if either steam generator indicates a high level condition.

This prevents an excessive rate of heat extraction and subsequent cooldown of the RCS during these events.

5, 6. Auxiliary Feedwater Actuation Signal (AFAS)

AFAS consists of two steam generator specific signals (AFAS-1 and AFAS-2). AFAS-1 initiates auxiliary feed to SG #1 and AFAS-2 initiates auxiliary feed to SG #2.

AFAS maintains a steam generator heat sink during steam generator tube rupture, small LOCA, MSLB, or MFLB either inside or outside containment.

The ESFAS satisfies Criterion 3 of 10 CFR 50.36(c)(2)(ii).

LCO

The LCO requires all channel equipment necessary for ESFAS actuation, to be OPERABLE.

The bases for the LCOs on ESFAS Functions are:

1. Safety Injection Actuation Signal
   a. Containment Pressure – High

   This LCO requires four channels of Containment Pressure – High to be OPERABLE in MODES 1, 2, 3, and 4.

   The Containment Pressure – High signal is shared among the SIAS (Function 1), CIAS (Function 3), and MSIS (Function 4).
The Allowable Value for this trip is set high enough to allow for small pressure increases in containment expected during normal operation (i.e., plant heatup) and not indicative of an abnormal condition. The setting is low enough to initiate the ESF Functions when an abnormal condition is indicated. This allows the ESF Systems to perform as expected in the accident analyses to mitigate the consequences of the analyzed accidents.

b. **Pressurizer Pressure – Low**

This LCO requires four channels of Pressurizer Pressure – Low to be OPERABLE in MODES 1, 2, 3, and 4.

The Allowable Value for this trip is set low enough to prevent actuating the ESF Functions (SIAS and CIAS) during normal plant operation and pressurizer pressure transients. The setting is high enough that with the specified accidents the ESF Systems will actuate to perform as expected, mitigating the consequences of the accident.

The Pressurizer Pressure – Low trip setpoint, which provides SIAS, CIAS, and RPS trip, may be manually decreased to a floor value of 7.0 kg/cm² (100 psia) during MODES 3 and 4 by maintaining the margin between pressurizer pressure and the trip setpoint \( \leq 28.1 \text{ kg/cm}^2 \) (400 psi).

The margin between actual pressurizer pressure and the trip setpoint must be maintained less than or equal to the specified value 28.1 kg/cm² (400 psi) to ensure a reactor trip, CIAS, and SIAS will occur if required during RCS cooldown and depressurization.

From this reduced setting, the trip setpoint will increase automatically as pressurizer pressure increases, tracking actual RCS pressure until the trip setpoint is reached.

When the trip setpoint has been lowered below the operating bypass permissive setpoint of 28.1 kg/cm² (400 psia), the Pressurizer Pressure – Low reactor trip, CIAS, and SIAS actuation may be manually bypassed in preparation for shutdown cooling. When pressurizer pressure rises above bypass removal setpoint of 35.2 kg/cm² (500 psia), the bypass is removed.
Bypass Removal

This LCO requires the automatic operating bypass removal function for all four Pressurizer Pressure – Low trip channels to be OPERABLE in MODES 1, 2, 3, and 4.

Each of the four channels enables and disables the operating bypass capability for a single channel. Therefore, this LCO applies to the operating bypass removal feature only. If the operating bypass enable function is failed so as to prevent entering a bypass condition, operation may continue. Since the trip setpoint has a floor value of 7.0 kg/cm²A (100 psia), a channel trip will result if pressure is decreased equal to or below this setpoint without bypassing.

The operating bypass removal Allowable Value was chosen because MSLB originating from below this setpoint add less positive reactivity than that which can be compensated for by required SDM.

2. Containment Spray Actuation Signal

Containment spray is initiated either manually or automatically. For an automatic actuation, it is necessary to have a Containment Pressure – High High signal. The SIAS requirement should always be satisfied on a legitimate CSAS, since the Containment Pressure – High signal used in the SIAS will initiate before the Containment Pressure – High. This ensures that a CSAS will not initiate unless required.

a. Containment Pressure – High High

This LCO requires four channels of Containment Pressure – High High to be OPERABLE in MODES 1, 2, 3, and 4.

The Allowable Value for this trip is set high enough to allow for first response ESF Systems (Containment Cooling Systems) to attempt to mitigate the consequences of an accident before resorting to spraying borated water onto containment equipment. The setting is low enough to initiate CSAS in time to prevent containment pressure from exceeding design.
LCO (continued)

3. **Containment Isolation Actuation Signal**

The SIAS and CIAS are actuated on Pressurizer Pressure – Low or Containment Pressure – High, the SIAS and CIAS share the same input channels, bistables, and local coincidence logic. The remainder of the initiation channels, the manual channels, and the actuation logic are separate and are addressed in LCO 3.3.6.

a. **Containment Pressure – High**

This LCO requires four channels of Containment Pressure – High to be OPERABLE in MODES 1, 2, 3, and 4.

The Containment Pressure – High signal is shared among the SIAS (Function 1), CIAS (Function 3), and MSIS (Function 4).

The Allowable Value for this trip is set high enough to allow for small pressure increases in containment expected during normal operation (i.e., plant heatup), and not indicative of an abnormal condition. The setting is low enough to initiate the ESF functions when an abnormal condition is indicated. This allows the ESF Systems to perform as expected in the accident analyses to mitigate the consequences of the analyzed accidents.

b. **Pressurizer Pressure – Low**

This LCO requires four channels of Pressurizer Pressure – Low to be OPERABLE in MODES 1, 2, 3, and 4.

The Allowable Value for this trip is set low enough to prevent actuating the ESF Functions (SIAS and CIAS) during normal plant operation and pressurizer pressure transients. The setting is high enough that with the specified accident the ESF systems will actuate to perform as expected, mitigating the consequences of the accidents.

The Pressurizer Pressure – Low trip setpoint, which provides an SIAS, CIAS, and RPS trip, may be manually decreased to a value of 7.0 kg/cm²A (100 psia) during MODES 3 and 4 by maintaining the margin between pressurizer pressure and the trip setpoint ≤ 28.1 kg/cm² (400 psi). The safety margin between actual pressurizer pressure and the trip setpoint must be maintained less than or equal to the specified value 28.1 kg/cm² (400 psi) to ensure a reactor trip, CIAS, and SIAS will occur if required during RCS cooldown and depressurization.
From this reduced setting, the trip setpoint will increase automatically as pressurizer pressure increases, tracking actual RCS pressure until the trip setpoint is reached.

When the trip setpoint has been lowered below the operating bypass removal setpoint of 28.1 kg/cm²A (400 psia), the pressurizer pressure – Low reactor trip, CIAS, and SIAS actuation may be manually bypassed in preparation for shutdown cooling. When pressurizer pressure rises above bypass removal setpoint of 35.2 kg/cm²A (500 psia), the bypass is removed.

**Bypass Removal**

This LCO requires the bypass removal Function for all four Pressurizer Pressure – Low trip channels to be OPERABLE in MODES 1, 2, 3, and 4. Each of the four channels enables and disables the operating bypass capability for a single channel. Therefore all four operating bypass removal channels must be OPERABLE to ensure that none of the four channels are inadvertently bypassed.

This LCO applies to the operating bypass removal feature only. If the operating bypass enable Function is failed so as to prevent entering a bypass condition, operation may continue. Since the trip setpoint has a floor value of 7.0 kg/cm²A (100 psia), a channel trip will result if pressure is decreased equal to or below this setpoint without bypassing.

The operating bypass removal Allowable Value was chosen because MSLB originating from below this setpoint add less positive reactivity than that which can be compensated by required SDM.

**4. Main Steam Isolation Signal**

The LCO is applicable to the MSIS in MODES 1, 2, 3, and 4 except when all associated valves are closed and deactivated.

a. **Steam Generator Pressure – Low**

This LCO requires four channels of Steam Generator Pressure – Low to be OPERABLE in MODES 1, 2, 3, and 4.
The Allowable Value for this trip is set below the full load operating value for steam pressure so as not to interfere with normal plant operation. However, the setting is high enough to provide an MSIS (Function 4) during an excessive steam demand event. An excessive steam demand event causes the RCS to cool down resulting in a positive reactivity addition to the core.

An RPS trip on Steam Generator Pressure – Low is initiated simultaneously, using the same bistable. The Steam Generator Pressure – Low trip setpoint may be manually decreased as steam generator pressure is reduced. This prevents an RPS trip or MSIS actuation during controlled plant cooldown.

The margin between actual steam generator pressure and the trip setpoint must be maintained less than or equal to the specified value of 14.1 kg/cm$^2$ (200 psi) to ensure a reactor trip and MSIS will occur when required.

b. Containment Pressure – High

This LCO requires four channels of Containment Pressure – High to be OPERABLE in MODES 1, 2, 3, and 4. The Containment Pressure – High signal is shared among the SIAS (Function 1), CIAS (Function 3), and MSIS (Function 4).

The Allowable Value for this trip is set high enough to allow for small pressure increases in containment expected during normal operation (i.e., plant heatup), and not indicative of an abnormal condition. The setting is low enough to initiate the ESF Functions when an abnormal condition is indicated. When decreasing pressurizer pressure, the pressure may be manually decreased to a value of 7.0 kg/cm$^2$A (100 psia) during MODES 3 and 4 by maintaining the margin between pressurizer pressure and the trip setpoint $\leq$ 28.1 kg/cm$^2$ (400 psi).

c. Steam Generator Level – High

This LCO requires four channels of Steam Generator Level – High to be OPERABLE in MODES 1, 2, 3, and 4.

The Allowable Value for this trip is set high enough not to effect normal operation. The setting is low enough to protect secondary side equipment during abnormal increase of steam generator level.
5, 6. **Auxiliary Feedwater Actuation Signal SG #1 and SG #2 (AFAS-1 and AFAS-2)**

AFAS-1 is initiated to SG #1 by a low steam generator level. AFAS-2 is similarly configured to feed AFW into SG #2.

The following LCO description applies to both AFAS signals.

a. **Steam Generator Level – Low**

This LCO requires four channels of Steam Generator Level – Low to be OPERABLE for each AFAS in MODES 1, 2, 3, and 4.

The Steam Generator Level – Low AFAS input is derived from the Steam Generator Level – Low PPS bistable output. AFAS is initiated well before steam generator inventory is challenged.

**APPLICABILITY**

In MODES 1, 2, 3, and 4, there is sufficient energy in the primary and secondary systems to warrant the automatic ESF System responses below.

a. Close main steam isolation valves to preclude a positive reactivity addition.

b. Actuate auxiliary feedwater to preclude the loss of the steam generators as a heat sink (in the event the Normal Feedwater System is not available).

c. Actuate ESF Systems to prevent or limit the release of fission product radioactivity to the environment by isolating containment and limiting the containment pressure from exceeding the containment design pressure during a design basis LOCA or MSLB.

d. Actuate ESF Systems to ensure sufficient borated inventory to permit adequate core cooling and reactivity control during a design basis LOCA or MSLB.

In MODES 5 and 6, automatic actuation of these Functions is not required because adequate time is available to evaluate plant conditions and respond by manually operating the ESF components if required, as addressed by LCO 3.3.6.
APPLICABILITY  (continued)

Several trips have operating bypasses, discussed in the preceding LCO section. The interlocks that allow these bypasses shall be OPERABLE whenever the RPS function they support is OPERABLE.

ACTIONS

The most common causes of channel inoperability are outright failure or drift of the bistable or process module sufficient to exceed the tolerance allowed by the plant specific setpoint analysis. Typically, the drift is found to be small and results in a delay of actuation rather than a total loss of function. Determination of setpoint drift is generally made during the performance of a CHANNEL FUNCTIONAL TEST when the process instrument is set up for adjustment to bring it to within specification.

In the event a channel trip setpoint is found non-conservative with respect to the Allowable Value, or the transmitter, instrument loop, signal processing electronics, or ESFAS bistable is found inoperable, then all affected Functions provided by that channel must be declared inoperable and the LCO Condition entered for the particular protection Function affected.

When one channel of process measurement circuit affecting multiple functioning equipment is in test or inoperable, all the following associated functioning equipment is set to bypassed or tripped.

<table>
<thead>
<tr>
<th>Process Measurement Circuit</th>
<th>Bypass/Trip of Functioning Equipment</th>
</tr>
</thead>
<tbody>
<tr>
<td>1  SG Pressure – Low</td>
<td>SG Pressure – Low (RPS)</td>
</tr>
<tr>
<td></td>
<td>SG #1 Pressure Low (ESF)</td>
</tr>
<tr>
<td></td>
<td>SG #2 Pressure Low (ESF)</td>
</tr>
<tr>
<td>2  SG Level – Low (WR)</td>
<td>SG Pressure – Low (RPS)</td>
</tr>
<tr>
<td></td>
<td>SG #1 Level Low (ESF)</td>
</tr>
<tr>
<td></td>
<td>SG #1 Level Low (ESF)</td>
</tr>
</tbody>
</table>

When the number of inoperable channels in a trip Function exceeds those specified in any related Condition associated with the same trip Function, then the plant is outside the safety analysis. Therefore, LCO 3.0.3 should be entered immediately, if applicable in the current MODE of operation.
A Note has been added to the ACTIONS to clarify the application of the Completion Time rules. The Conditions of this Specification may be entered independently for each Function. The Completion Time for the inoperable channel of a Function will be tracked separately for each Function starting from the time the Condition was entered for that Function.

A.1 and A.2

Condition A applies to the failure of a single channel of one or more input parameters in any of the following ESFAS Functions:

1. **SIAS**
   - Containment Pressure – High or
   - Pressurizer Pressure – Low.

2. **CSAS**
   - Containment Pressure – High High.

3. **CIAS**
   - Containment Pressure – High or
   - Pressurizer Pressure – Low.

4. **MSIS**
   - Steam Generator Pressure – Low,
   - Containment Pressure – High, or
   - Steam Generator Level – High.

5. **AFAS-1**
   - Steam Generator #1 Level – Low.

6. **AFAS-2**
   - Steam Generator #2 Level – Low.

ESFAS coincidence logic is normally 2-out-of-4.

If one automatic ESFAS trip channel is inoperable, startup or power operation is allowed to continue providing the inoperable channel is placed in bypass or trip within 1 hour (Required Action A.1).
The Completion Time of 1 hour allotted to restore, bypass, or trip the channel is sufficient to allow the operator to take all appropriate actions for the failed channel and still ensures that the risk involved in operating with the failed channel is acceptable.

The failed channel is restored to OPERABLE status prior to entry into MODE 2 following next entry into MODE 5. With a channel bypassed, the coincidence logic is in a 2-out-of-3 configuration. In this configuration, common cause failure of dependent channels cannot prevent trip.

The Completion Time of prior to entry into MODE 2 following next entry into MODE 5 is based on adequate channel to channel independence, which allows a 2-out-of-3 channel operation, since no single failure will prevent an ESFAS initiation.

B.1

The Required Action is modified by a Note stating that LCO 3.0.4 is not applicable. The Note was added to allow the changing of MODES even though two channels are inoperable, with one channel bypassed and one tripped. In this configuration, the protection system is in a 1-out-of-2 logic, which is adequate to ensure that no random failure will prevent protection system operation.

Condition B applies to the failure of two channels of one or more input parameters in any of the following ESFAS automatic trip Functions:

1. **SIAS**
   
   Containment Pressure – High or Pressurizer Pressure – Low.

2. **CSAS**
   
   Containment Pressure – High High.

3. **CIAS**
   
   Containment Pressure – High or Pressurizer Pressure – Low.
Bases

Actions (continued)

4. **Msis**

Steam Generator Pressure – Low, Containment Pressure – High, or Steam Generator Level – High.

5. **Afas-1**

Steam Generator #1 Level – Low.

6. **Afas-2**

Steam Generator #2 Level – Low.

With two inoperable automatic ESFAS trip channels, power operation may continue, provided one inoperable channel is placed in bypass and the other channel is placed in trip within 1 hour. With one channel of protection instrumentation bypassed, the ESFAS Function is in 2-out-of-3 logic in the bypassed input parameter, but with another channel failed, the ESFAS could be operating with a two-out-of-two logic. This is outside the assumptions made in the analyses and should be corrected. To correct the problem, the second channel is placed in trip. This places the ESFAS Function in a one-out-of-two logic. If any of the other operable channels receives a trip signal, ESFAS actuation will occur.

One of the two inoperable automatic ESFAS trip channels will need to be restored to operable status prior to the next required channel functional test because channel surveillance testing on an operable channel requires that the operable channel be placed in bypass. However, it is not possible to bypass more than one ESFAS channel, and placing a second channel in trip will result in an ESFAS actuation. Therefore, if one ESFAS channel is in trip and a second channel is in bypass, a third inoperable channel would place the unit in LCO 3.0.3.

C.1, C.2.1 and C.2.2.

Condition C applies to an inoperable automatic operating bypass removal function of any operating bypass channel. The only automatic operating bypass removal function on an ESFAS Function is on the Pressurizer Pressure – Low signal, which is used to actuate SIAS and CIAS. This automatic operating bypass removal function is shared with the RPS Reactor Trip on Pressurizer Pressure – Low automatic operating bypass removal function.
BASIS

ACTIONS (continued)

If the automatic operating bypass removal function of any operating bypass channel cannot be restored to OPERABLE status, the associated ESFAS Pressurizer Pressure – Low Function trip channel may be considered OPERABLE only if the operating bypass is not in effect (disabled). Otherwise the affected ESFAS Pressurizer Pressure – Low Function trip channel must be declared inoperable, and Condition A must be entered. Action C requires within 1 hour either removing (disabling) the operating bypass, or placing the affected automatic trip channel in bypass or trip; it also requires repairing the automatic operating bypass removal channel before entering MODE 2 following the next MODE 5 entry. The Bases for the Required Actions and associated Completion Times of Condition C are consistent with Condition A.

D.1 and D.2

The Required Action is modified by a Note stating that LCO 3.0.4 is not applicable. The Note was added to allow the changing of MODES even though two channels are inoperable, with one channel bypassed and one tripped. In this configuration, the protection system is in a 1-out-of-2 logic, which is adequate to ensure that no random failure will prevent protection system operation.

Condition D applies to two inoperable automatic operating bypass removal functions within a Completion Time of 1 hour. If the bypass removal Functions for two operating bypasses cannot be restored to OPERABLE, the associated ESFAS channel may be considered OPERABLE, only if the bypass is not in effect. Otherwise the affected ESFAS channels must be declared inoperable, as in Condition B, and either the bypasses removed, or the operating bypass removal functions repaired. The restoration of one affected bypassed automatic trip channel must be completed prior to the next CHANNEL FUNCTIONAL TEST or the plant must shut down per LCO 3.0.3, as explained in Condition B.

E.1 and E.2

If the Required Actions and associated Completion Times for AFAS Functions cannot be met, the plant must be brought to a MODE in which the LCO does not apply. To achieve this status, the plant must be brought to at least MODE 3 within 6 hours and to MODE 4 without reliance upon SGs for heat removal within 12 hours. The allowed Completion Times are reasonable, based on operating experience, to reach the required plant conditions from full power conditions in an orderly manner and without challenging plant systems.
Bases

Actions (continued)

F.1 and F.2

If a Required Action and associated Completion Time for a SIAS, CIAS, CSAS or MSIS function cannot be met, the plant must be brought to a MODE in which the LCO does not apply. To achieve this status, the plant must be brought to at least MODE 3 within 6 hours and to MODE 5 within 36 hours.

The allowed Completion Times are reasonable, based on operating experience, to reach the required plant conditions from full power conditions in an orderly manner and without challenging plant systems.

Surveillance Requirements

Since the interface and test processor (ITP) is not needed to perform any ESFAS safety function, the OPERABILITY of the ITP is not required by LCO 3.3.5. However, the ITP must be maintained capable of supporting performance of the CHANNEL FUNCTIONAL TEST of SRs 3.3.5.2, 3.3.5.3, and 3.3.5.5.

SR 3.3.5.1

Performance of the CHANNEL CHECK once every 12 hours ensures that a gross failure of instrumentation has not occurred. A CHANNEL CHECK is a comparison of the parameter indicated on one channel to a similar parameter on other channels. It is based on the assumption that instrument channels monitoring the same parameter should read approximately the same value. Significant deviations between instrument channels could be an indication of excessive instrument drift in one of the channels. CHANNEL CHECK will detect gross channel failure; thus, it is a key to verifying the instrumentation continues to operate properly between each CHANNEL CALIBRATION.

Agreement criteria are determined by the plant staff based on a combination of the channel instrument uncertainties, including indication and readability. If a channel is outside the match criteria, it could be an indication that the sensor or the signal processing equipment has drifted outside its limit. If the channels are within the match criteria, it is an indication that the channels are OPERABLE.

The CHECK FREQUENCY, twice a day, is based on operating experience that demonstrates channel failure is rare. Since the probability of two random failures in redundant channels in any 12 hour period is low, the CHANNEL CHECK minimizes the chance of loss of protection function due to failure of redundant channels.
SURVEILLANCE REQUIREMENTS (continued)

The CHANNEL CHECK supplements checks of channel OPERABILITY during normal operational use of displays associated with the LCO required channels.

**SR 3.3.5.2**

A CHANNEL FUNCTIONAL TEST on each channel is performed to ensure the entire channel will perform its intended function when needed. The OPERABILITY of each ESFAS instrumentation channel is verified on a 31 day interval with applicable extensions. This Frequency is based on operating experience which shows that ESFAS instrument channels usually pass the CHANNEL FUNCTIONAL TEST when performed on a 31 day Frequency.

This test is part of an overlapping test sequence similar to that employed in the RPS. This sequence consists of SR 3.3.5.2, SR 3.3.6.1, and SR 3.3.6.2 and tests the entire ESFAS from sensor input to the bistable logic processor through the automatic ESF actuation logic (actuational) output of each subgroup. These overlapping tests are described in FSAR Section 7.3 (Ref. 1).

SR 3.3.5.2 and SR 3.3.6.1 are performed together and in conjunction with ESFAS testing. SR 3.3.6.2 verifies that each subgroup can actuate ESF equipment when actuational output of each subgroup is generated.

These tests verify that the ESFAS is capable of performing its intended function, from sensor input to the bistable logic processor through the actuational output of each subgroup to the actuated ESF components. SR 3.3.6.1 and SR 3.3.6.2 are described in LCO 3.3.6. SR 3.3.5.2 includes bistable logic processor testing.

To assure that the actual trip setting in the bistable logic processor is conservative with respect to the Allowable Value, a test signal is superimposed on the input in one channel at a time to verify that the bistable processor trips within the specified as-found setting tolerance around the previous as-left setting. This is performed with the corresponding RPS trip channel placed in trip channel bypass. Setpoint adjustment must be performed as specified in the Setpoint Control Program.

**SR 3.3.5.3**

CHANNEL CALIBRATION is a complete check of the instrument channel including the detector and the automatic operating bypass removal functions.
The Surveillance verifies that the channel responds to a measured parameter within the necessary range and accuracy. CHANNEL CALIBRATION leaves the channel adjusted to account for instrument drift between successive calibrations to ensure that the channel remains operational between successive Surveillances. CHANNEL CALIBRATION must be performed consistent with the plant specific setpoint analysis.

The 18 month Frequency is based upon the possibility for the necessity of surveillance activity and upon the unexpected transients in case when the check is performed at plant operation.

**SR 3.3.5.4**

This Surveillance ensures that the actuation response times are within the maximum values assumed in the safety analyses.

Response time testing acceptance criteria are included in FSAR Section 7.3 (Ref. 1).

ESF RESPONSE TIME tests are conducted on a STAGGERED TEST BASIS of once every 18 months. The 18 month Frequency is based upon plant operating experience, which shows that random failures of instrumentation components causing serious response time degradation are infrequent occurrences.

**SR 3.3.5.5**

SR 3.3.5.5 is a CHANNEL FUNCTIONAL TEST similar to SR 3.3.5.2, is performed within 31 days prior to startup and is only applicable to operating bypass Functions. Since the Pressurizer Pressure – Low bypass is identical for both the RPS and ESFAS, this is the same Surveillance performed for the RPS in SR 3.3.1.12.

The CHANNEL FUNCTIONAL TEST for proper operation of the bypass permissives is critical during plant heatups because the operating bypasses may be in place prior to entering MODE 3, but must be removed at the appropriate points during plant startup to enable the ESFAS Function. Consequently, just prior to startup is the appropriate time to verify bypass Function OPERABILITY. Once the operating bypasses are removed, the bypasses must not fail in such a way that the associated ESFAS Function is inappropriately bypassed. This feature is verified by SR 3.3.5.2.
REFERENCES

1. FSAR, Section 7.3.

2. 10 CFR Part 50, Appendix A.


4. FSAR, Chapter 15.

5. 10 CFR 50.49.

6. FSAR, Section 7.2.
B 3.3 INSTRUMENTATION

B 3.3.6 Engineered Safety Features Actuation System (ESFAS) Logic and Manual Trip

BASES

BACKGROUND

The ESFAS initiates necessary safety systems, based upon the values of selected unit parameters, to protect against violating core design limits and the Reactor Coolant System (RCS) pressure boundary during anticipated operational occurrences (AOOs) and ensures acceptable consequences during accidents.

The ESFAS contains devices and circuitry that generate the following signals when monitored variables reach levels that are indicative of conditions requiring protective action:

1. Safety injection actuation signal (SIAS),
2. Containment isolation actuation signal (CIAS),
3. Containment spray actuation signal (CSAS),
4. Main steam isolation signal (MSIS),
5. Auxiliary feedwater actuation signal steam generator (SG) #1 (AFAS-1), and
6. Auxiliary feedwater actuation signal SG #2 (AFAS-2).

Equipment actuated by each of the above signals is identified in the FSAR (Ref. 1).

The Engineered Safety Features (ESF) Actuation System consists of four channels of sensors, auxiliary process cabinets – safety (APC-S), the ESFAS signal generation portion of the Plant Protection System (PPS) cabinets and the ESF Component Control System (ESF-CCS).
The devices and circuitry that generate the above ESFAS signals are grouped into the following interconnected parts. These parts are:

- Measurement channels,
- Bistable logic processor channels,
- ESFAS logic channels:
  - Coincidence Logic,
  - Initiation Logic (trip paths), and
  - Actuation Logic.

This LCO addresses the ESFAS logic channels. Bistable logic processor channels and measurement channels are addressed in LCO 3.3.5, “Engineered Safety Features Actuation System (ESFAS) Instrumentation.”

The roles of the measurement channels and bistable logic processor channels are described in LCO 3.3.5. The role of the ESFAS logic is described below.

**ESFAS Logic**

The ESFAS logic, consisting of coincidence, initiation and actuation logic, employs a scheme that provides an ESFAS actuation signal from all four PPS divisions to the component control logic of all trains of the associated ESF Systems when any two of the four bistable logic processor channels sense that the same input parameter has satisfied the ESFAS Function’s trip setpoint on the input parameter. This logic scheme is called a 2-out-of-4 trip logic. The actuation logic includes the priority logic.

**Coincidence Logic**

There is one local coincidence logic (LCL) associated with each trip bistable logic of each channel of a given ESFAS instrument Function. Each LCL receives four trip signals, one from the trip bistable logic in the associated channel and one from each trip bistable logic located in the other three channels of the affected ESFAS instrument Function. The LCL also receives the trip channel bypass status signal associated with each of the bistable signals. The function of the LCL is to generate a coincidence logic trip signal whenever two or more like bistables are in a tripped condition. Each LCL automatically changes the state of each of the four coincidence logic channels based on the state of the trip channel.
bypass Function in each channel. For example, a 2-out-of-4 trip logic goes to 2-out-of-3 if one trip bistable logic channel is bypassed.

Designating the protection channels as A, B, C, D, with no trip channel bypass signal present, the LCL will produce a coincidence logic trip signal for any of the following trip inputs: AB, AC, BC, BD, CD, ABC, ABD, ACD, BCD, ABCD. These represent all possible 2- or more out-of-4 trip combinations of the four protection channels. Should a trip channel bypass be present, the logic will provide a coincidence logic trip signal when two or more of the three un-bypassed trip bistable logic channels are in a tripped condition.

In accordance with the IEEE Std. 603-1991, the channel loses its identity where single protective action signals are combined. Technical Specifications and Bases use the word “channel” or “division” for the portion of the circuit from the local coincidence logic to the actuation logic. The words “channel” and “division” are interchangeable regarding the portion from the local coincidence logic to the actuation logic.

Initiation Logic

The initiation logic is designed to be fail-safe. Failure of one initiation logic channel will result in a partial trip (1 of 4) in the 1-out-of-2 taken twice ESFAS selective actuation logic. The partial trip will be alarmed the same as a full ESFAS trip and will be indicated by the Qualified Indication and Alarm System – Safety (QIAS-P) and the Information Processing System (IPS); the partial trip cannot be bypassed.

Actuation Logic

The four initiation logic signals from the PPS are used to generate a selective 2-out-of-4 logic actuation signal in each division of the ESF-CCS. In the actuation logic, each signal also sets a latch when the selective two-out-of-four logic actuates to assure that the ESF actuation signal is not automatically reset once it has been generated.

A trip leg is defined as the “logical or” combination of channel states and represents half of a selective 2-out-of-4 logic function. When both trip legs of a selective 2-out-of-4 logic function assume a true state, the output of the selective 2-out-of-4 logic function assumes a true state (e.g., in a selective 2-out-of-4 logic \((A \ “or” \ C) \ “and” \ (B \ “or” \ D) = N\); the term \((A \ “or” \ C)\) is a trip leg, the term \((B \ “or” \ D)\) is a trip leg, and \(N\) is the output).
Receipt of two ESFAS initiation logic channel signals will generate the actuation logic division signals. This is done independently in each ESF-CCS cabinet, generating division A and division B signals, and where required for ESF Systems with four trains, division C and division D actuation signals.

The actuation logic includes the priority logic in the ESF-CCS loop controller (LC) and the priority logic in the component interface module (CIM). The LC provides the prioritization logic between system-level ESFAS signals and component-level control signals. The system-level ESFAS signals have priority over the component-level control signals.

The manual ESFAS switches generate system-level ESFAS manual actuation signals that have priority over the component-level control signals, using the priority logic in the LC.

The CIM prioritizes the control signals from the (A) ESF-CCS LC, (B) diverse protection system (DPS), and (C) diverse manual actuation (DMA) switches. Of signals A and B, the one that causes the associated component to go to its safety state is the higher priority signal (state based priority). Regardless of signals A and B, signal C has the highest priority. Since the DMA functions initiate system-level actuation of all ESF trains, the DMA switch generated signals have system-level priority.

Manual Trip

ESFAS Manual Trip capability is provided to permit the operator to manually actuate an ESF System when necessary.

Two sets of two push buttons (in the main control room (MCR)) for each ESF function are provided, and each set actuates all trains provided for that ESF Function, either two or four. Each manual trip push button signal is sent to the actuation logic in the ESF-CCS cabinets via the control panel multiplexer (CPM). By arranging the push buttons in two sets of two, such that both push buttons in a set must be depressed, it is possible to ensure that manual trip will not be prevented in the event of a signal random failure in the signal path associated with one set of push buttons.
Diverse Manual ESF Actuation

Independent of the above design features, APR1400 implements a means for manual actuation of engineered safety feature Functions using a single channel which uses hardwired communication that bypasses all data links, network communications, and all computers with large software applications. Switches located in the main control room provide for system level actuation of safety injection, containment spray, auxiliary feedwater for each steam generator, main steam isolation per mainstream isolation valve (MSIV), and containment isolation.

The hardwired manual input signal from the control room switches will override input data received from the network communication interface to actuate the plant components. This feature of APR1400 design provides an additional level of protection against a postulated common mode failure of protection system software.

Provisions are made to permit periodic testing of the complete ESFAS. These tests cover the trip actions from sensor input through the protection system and actuation devices. The system test does not interfere with the protection function of the system. Overlap between individual tests exists so that the entire ESFAS can be tested. FSAR, Section 7.3 (Ref. 1) describes ESFAS testing in detail.

APPLICABLE SAFETY ANALYSES

Each of the analyzed accidents can be detected by one or more ESFAS Functions. One of the ESFAS Functions is the primary actuation signal for that accident. An ESFAS Function can be the primary actuation signal for more than one type of accident. An ESFAS Function can also be a secondary, or backup, actuation signal for one or more other accidents.

ESFAS Functions are as follows:

1. Safety Injection Actuation Signal

SIAS ensures acceptable consequences during large break loss of coolant accidents (LOCAs), small break LOCAs, control element assembly ejection accidents, and main steam line breaks (MSLBs) inside containment. To provide the required protection, either a high containment pressure or a low pressurizer pressure signal will initiate SIAS. The SIAS initiates the Safety Injection System and actuates the emergency diesel generator (EDG).
APPLICABLE SAFETY ANALYSES (continued)

2. **Containment Spray Actuation Signal**

   CSAS actuates containment spray, preventing containment overpressurization during large break LOCAs, small break LOCAs, and MSLBs or main feedwater line breaks (MFLBs) inside containment. CSAS is initiated by high-high containment pressure and a SIAS. This configuration reduces the likelihood of inadvertent containment spray. The CSAS actuates the EDG.

3. **Containment Isolation Actuation Signal**

   CIAS ensures acceptable mitigating actions during large and small break LOCAs and during MSLBs or MFLBs either inside or outside containment. CIAS is initiated by low pressurizer pressure or high containment pressure.

4. **Main Steam Isolation Signal**

   MSIS ensures acceptable consequences during a MSLB or MFLB (between the steam generator and the main feedwater check valve) either inside or outside containment. Main stream isolation signal (MSIS) isolates both steam generators if either generator indicates a low pressure condition or if a high containment pressure condition exists. This prevents an excessive rate of heat extraction and subsequent cooldown of the RCS during these events.

5, 6. **Auxiliary Feedwater Actuation Signal**

   AFAS consists of two steam generator specific signals (AFAS-1 and AFAS-2). AFAS-1 initiates auxiliary feed to SG #1 and AFAS-2 initiates auxiliary feed to SG #2.

   AFAS maintains a steam generator heat sink during a small break LOCA, a steam generator tube rupture, a MSLB, or MFLB either inside or outside of containment, or any event where normal AC power or the Main Feedwater (MFW) System is unavailable. The AFAS actuates the EDG.

   The ESFAS satisfies Criterion 3 of 10 CFR 50.36(c)(2)(ii).
APPLICABLE SAFETY ANALYSES (continued)

Diverse Manual ESF Actuation Interface to ESF Components

The diverse manual ESF actuation interface to ESF components is a single channel which uses hardwired communication that bypasses all data links, network communications, and all computers with large software applications. Switches located in the control room provide system level actuation of safety injection, containment spray, auxiliary feedwater for each steam generator, main steam isolation per main steam isolation valve (MSIV), and containment isolation.

The hardwired manual input signal from the control room switches will override input data received from the network communication interface to actuate the plant components. The two position control room switches for safety injection, containment spray, auxiliary feedwater, main steam isolation, and containment isolation also have the ability to deactivate the associated plant components. These features of the design provide an additional level of protection against a postulated common mode failure of protection system software.

The diverse manual ESF actuation channel satisfies Criterion 4 of 10 CFR 50.36(c)(2)(ii).

LCO

The LCO requires all channel components necessary to provide an ESFAS actuation to be OPERABLE.

The requirements for each Function are listed below. The reasons for the applicable MODES for each Function are addressed under APPLICABILITY.

1. Safety injection actuation signal

   Automatic SIAS occurs in Pressurizer Pressure – Low or Containment Pressure – High and is explained in Bases 3.3.5.

   a. Coincidence Logic

      This LCO requires four channels of SIAS coincidence logic to be OPERABLE in MODES 1, 2, 3, and 4.

   b. Initiation Logic

      This LCO requires four channels of SIAS initiation logic to be OPERABLE in MODES 1, 2, 3, and 4.
c. **Actuation Logic**

This LCO requires four channels of SIAS actuation logic to be OPERABLE in MODES 1, 2, 3, and 4.

d. **Manual Trip**

This LCO requires four channels of SIAS manual trip to be OPERABLE in MODES 1, 2, 3, and 4.

2. **Containment spray actuation signal**

CSAS is initiated either manually or automatically. For an automatic actuation it is necessary to have a Containment Pressure – High High signal. The SIAS requirement should always be satisfied on a legitimate CSAS, since the Containment Pressure – High signal used in the SIAS will initiate before the Containment Pressure – High High input signal to CSAS. This ensures that a CSAS will not initiate unless required.

a. **Coincidence Logic**

This LCO requires four channels of CSAS coincidence logic to be OPERABLE in MODES 1, 2, 3, and 4.

b. **Initiation Logic**

This LCO requires four channels of CSAS initiation logic to be OPERABLE in MODES 1, 2, 3, and 4.

c. **Actuation Logic**

This LCO requires four channels of CSAS actuation logic to be OPERABLE in MODES 1, 2, 3, and 4.

d. **Manual Trip**

This LCO requires four channels of CSAS manual trip to be OPERABLE in MODES 1, 2, 3, and 4.
3. **Containment isolation actuation signal**

For plants where the SIAS and CIAS are actuated on Pressurizer Pressure – Low or Containment Pressure – High, the SIAS and CIAS share the same input channels, bistables, and coincidence logic. The remainder of the initiation channels, the manual channels, and the actuation logic are separate. Since their applicability is also the same, they have identical actions.

   a. **Coincidence Logic**

   This LCO requires four channels of CIAS coincidence logic to be OPERABLE in MODES 1, 2, 3, and 4.

   b. **Initiation Logic**

   This LCO requires four channels of CIAS initiation logic to be OPERABLE in MODES 1, 2, 3, and 4.

   c. **Actuation Logic**

   This LCO requires two channels of CIAS actuation logic to be OPERABLE in MODES 1, 2, 3, and 4.

   d. **Manual Trip**

   This LCO requires four channels of CIAS manual trip to be OPERABLE in MODES 1, 2, 3, and 4.

4. **Main steam isolation signal (MSIS)**

MSIS occurs on a Steam Generator Pressure – Low or Containment Pressure – High.

   a. **Coincidence Logic**

   This LCO requires six channels of coincidence logic to be OPERABLE in MODES 1, 2, 3, and 4.

   b. **Initiation Logic**

   This LCO requires four channels of initiation logic to be OPERABLE in MODES 1, 2, 3, and 4.
c. **Actuation Logic**

   This LCO requires four channels of actuation logic to be OPERABLE in MODES 1, 2, 3, and 4.

   **d. Manual Trip**

   This LCO requires four channels of manual trip to be OPERABLE in MODES 1, 2, 3, and 4.

5. **Auxiliary feedwater actuation signal SG #1 (AFAS-1)**

   AFAS-1 occurs on a Steam Generator Level – Low in Steam Generator #1. AFAS-1 is required in MODES 1, 2 and 3, and in MODE 4 only while relying on SGs for heat removal.

   **a. Coincidence Logic**

   This LCO requires four channels of coincidence logic to be OPERABLE in MODES 1, 2, 3, and 4.

   **b. Initiation Logic**

   This LCO requires four channels of initiation logic to be OPERABLE in MODES 1, 2, 3, and 4.

   **c. Actuation Logic**

   This LCO requires four channels of actuation logic to be OPERABLE in MODES 1, 2, 3, and 4.

   **d. Manual Trip**

   This LCO requires four channels of manual trip to be OPERABLE in MODES 1, 2, 3, and 4.

6. **Auxiliary feedwater actuation signal SG #2 (AFAS-2)**

   AFAS-2 occurs on a Steam Generator Level – Low in Steam Generator #2. AFAS-2 is required in MODES 1, 2 and 3, and in MODE 4 only while relying on SGs for heat removal.
BASES

LCO (continued)

a. **Coincidence Logic**

This LCO requires four channels of coincidence logic to be OPERABLE in MODES 1, 2, 3, and 4.

b. **Initiation Logic**

This LCO requires four channels of initiation logic to be OPERABLE in MODES 1, 2, 3, and 4.

c. **Actuation Logic**

This LCO requires four channels of actuation logic to be OPERABLE in MODES 1, 2, 3, and 4.

d. **Manual Trip**

This LCO requires four channels of manual trip to be OPERABLE in MODES 1, 2, 3, and 4.

7. **Diverse Manual ESF Actuation Signal**

The diverse manual ESF actuation interface to ESF components is initiated manually from switches in the MCR. The switches for safety injection, containment spray, auxiliary feedwater, main steam isolation, and containment isolation have two positions as follows: normal and actuate. When in actuate, input received from the network communication interface to actuate the components will be overridden.

This LCO requires two channels of safety injection, containment spray, auxiliary feedwater, and one channel for each main steam isolation valve and one channel for containment isolation to be OPERABLE in MODES 1, 2, 3, and 4. AFAS is required in MODES 1, 2 and 3, and in MODE 4 only while relying on SGs for heat removal for functions 7c and 7d.

**APPLICABILITY**

In MODES 1, 2, 3, and 4, there is sufficient energy in the primary and secondary systems to warrant automatic ESF System responses to:

a. Close the main steam isolation valves to preclude a positive reactivity addition.
APPLICABILITY (continued)

b. Actuate auxiliary feedwater to preclude the loss of the steam generators as a heat sink (in the event the Normal Feedwater System is not available).

c. Actuate ESF Systems to prevent or limit the release of fission product radioactivity to the environment by isolating containment and limiting the containment pressure from exceeding the containment design pressure during a design basis LOCA or MSLB.

d. Actuate ESF Systems to ensure sufficient borated inventory to permit adequate core cooling and reactivity control during a design basis LOCA or MSLB.

In MODES 5 and 6, automatic actuation of these Functions is not required because adequate time is available to evaluate plant conditions and respond by manually operating the ESF components if required.

In MODES 5 and 6, the systems initiated by ESFAS are either reconfigured or disabled for shutdown cooling operation. Accidents in these MODES are slow to develop and would be mitigated by manual operation of individual components.

ACTIONS

When the number of inoperable channels in a trip Function exceeds those specified in any related Condition associated with the same trip Function, then the plant is outside the safety analysis. Therefore, LCO 3.0.3 should be entered immediately, if applicable in the current MODE of operation.

A Note has been added to the ACTIONS to clarify the application of the Completion Time rules. The Conditions of this Specification may be entered independently for each Function. The Completion Time for the inoperable channel of a Function will be tracked separately for each Function, starting from the time the Condition was entered for that Function.

A.1

Condition A applies to one manual trip, coincidence logic, or initiation logic channel inoperable.

The channel must be restored to OPERABLE status within 48 hours. Operating experience has demonstrated that the probability of a random failure in a second channel is low during any given 48 hour period.
BASES

ACTIONS (continued)

Failure of a single initiation logic channel affects one trip leg of a selective 2-out-of-4 actuation logic channel. In this case, for the purposes of this Specification, the actuation logic is not inoperable. This prevents the need to enter LCO 3.0.3 in the event of an initiation logic channel failure. This Action is different from Required Action related to the RPS Manual channel inoperable because open contact of reactor trip switchgear is implemented and confirmed easily in RPS. If the channel cannot be restored to OPERABLE status with 48 hours, Condition E is entered.

B.1 and B.2

Condition B applies to the failure of both initiation logic channels affecting the same trip leg.

In this case, the actuation logic channels are not inoperable, since they are in one-out-of-two logic and capable of performing as required. This obviates the need to enter LCO 3.0.3 in the event of a coincidence logic or vital bus power failure.

The failure of vital electrical power to two PPS divisions which excludes the same trip leg of the selective 2-out-of-4 actuation logic causes the inputs from both PPS divisions to go to a failed (i.e., safe) state. The ESF-CCS recognizes the failed input signals as actuated states in the actuation logic. Therefore, a loss of vital electrical power to two PPS divisions generates ESF actuation signals to the component control logic in the LC when the selective 2-out-of-4 coincidence logic in the ESF-CCS GC is met.

If a LCL power supply or vital instrument bus is lost, the initiation logic channels in the same trip leg will generate the initiation signal. This will open the actuation logic contacts, satisfying the Required Action to generate at least the actuation logic signal in the affected trip leg from actuation logic.

The channel must be restored to OPERABLE status within 48 hours. This provides the operator with time to take appropriate actions and still ensures that any risk involved in operating with a failed channel is acceptable. Operating experience has demonstrated that the probability of a random failure of a second initiation logic is low during any given 48 hour period.

If the channel cannot be restored to OPERABLE status with 48 hours, Condition E is entered.
BASES

ACTIONs (continued)

Of greater concern is the failure of the initiation circuit in a non-trip condition (e.g., two initiation logic failures). With one failed, there is still the redundant input in the trip leg of each 2-out-of-4 actuation logic. With both failed in a nontrip condition, the ESFAS Function is lost in the affected train. To prevent this, immediate opening of at least one actuation logic signal in the affected trip leg is required. If the required actuation logic signal has not occurred, as indicated by annunciation or trip leg current lamps, manual trip of the affected trip leg may be attempted. Caution must be exercised since depressing the wrong ESFAS push buttons can result in an ESFAS actuation.

C.1

Condition C applies to actuation logic. With one actuation logic channel inoperable, automatic actuation of one train of ESF may be inhibited. The remaining train provides adequate protection in the event of Design Basis Accidents, but the single failure criterion could be violated. For this reason, operation in this condition is restricted.

The channel must be restored to OPERABLE status within 48 hours. Operating experience has demonstrated that the probability of a random failure in the actuation logic of the second train is low during a given 48 hour period. If the channel cannot be restored to OPERABLE status with 48 hours, Condition E is entered.

Failure of a single initiation logic channel, coincidence logic power supply, or vital instrument bus could open one or both contacts in the same trip leg in both actuation logic channels.

For the purposes of this Specification, the actuation logic is not inoperable. This obviates the need to enter LCO 3.0.3 in the event of a vital bus, coincidence, or initiation channel failure.

Required Action C.1 is modified by a Note to indicate that one channel of actuation logic may be bypassed for up to 1 hour for Surveillance, provided the other channel is OPERABLE.

This allows performance of a PPS CHANNEL FUNCTIONAL TEST on an OPERABLE ESFAS train without generating an ESFAS actuation in the inoperable train.

D.1

Required Action D.1 applies to the diverse manual ESF Actuation equipment.
The associated Completion Time is reasonable based on operating experience for repair and restoration of this type of diverse manual ESF equipment. In addition, it is assumed that the probability of multiple failures occurring in the automatic ESFAS actuation logic and other manual controls within 72 hours is small. If the inoperative Diverse Manual ESF Actuation channel is not restored to OPERABLE status within 72 hours, Condition E is entered.

**E.1, E.2, and E.3**

If any Required Action and associated Completion Time of Condition A, B, C, or D cannot be met, or one or more Functions with two or more Actuation Logic channels are inoperable, the plant must be brought to a MODE in which the LCO does not apply. To achieve this status, the plant must be brought to at least MODE 3 within 6 hours, and for Functions 5, 6, 7.c, and 7.d, to MODE 4 without reliance upon SGs for heat removal within 36 hours, and for Functions 1, 2, 3, 4, 7.a, 7.b, 7.e, and 7.f to MODE 5 within 36 hours. The allowed Completion Times are reasonable, based on operating experience, to reach the required plant conditions from full power conditions in an orderly manner and without challenging plant systems.

**SURVEILLANCE REQUIREMENTS**

Since the interface and test processor (ITP) is not needed to perform any ESFAS safety function, the OPERABILITY of the ITP is not required by LCO 3.3.6. However, the ITP must be maintained capable of supporting performance of the CHANNEL FUNCTIONAL TEST of SR 3.3.6.1.

**SR 3.3.6.1**

A CHANNEL FUNCTIONAL TEST is performed to ensure the entire channel will perform its intended function when needed. The OPERABILITY of each ESFAS Logic channel and ESFAS Manual Trip channel is verified on a 31 day interval with applicable extensions. This Frequency is based on operating experience which shows that automatic ESF actuation logic channels and ESF manual trip channels usually pass the CHANNEL FUNCTIONAL TEST when performed on a 31 day Frequency.

The CHANNEL FUNCTIONAL TEST is part of an overlapping test sequence similar to that employed in the RPS. This sequence, consisting of SR 3.3.5.2, SR 3.3.6.1, and SR 3.3.6.2 tests the entire ESFAS from sensor input to the bistable logic processor through the automatic ESF actuation logic (actuational) output of each subgroup. These overlapping
tests are described in Reference 1. SR 3.3.5.2 and SR 3.3.6.1 are normally performed together and in conjunction with ESFAS testing. When the actuation output signal for a subgroup is generated, SR 3.3.6.2 verifies that ESF components associated with the subgroup are capable of being actuated by the ESF-CCS.

These tests verify that the ESFAS is capable of performing its intended function, from sensor input to the bistable logic processor through to the actuated components. SR 3.3.5.2 is addressed in LCO 3.3.5. SR 3.3.6.1 includes LCL testing, initiation logic (trip path) testing, and actuation logic testing. This CHANNEL FUNCTIONAL TEST also verifies that an EDG start is separately actuated by SIAS, CSAS, and AFAS signals.

Local Coincidence Logic Testing

LCL testing verifies the OPERABILITY of the 2-out-of-4 coincidence logic and trip channel bypass logic.

Initiation Logic (Trip Path) Testing

Testing of initiation logic, which consists of logical “OR”, is performed after the completion of LCL testing. This testing exercises only one initiation logic channel at a time, which affects only one trip path.

Actuation Logic Testing

Actuation logic testing verifies the OPERABILITY of the selective 2-out-of-4 actuation logic after the completion of initiation logic (trip path) testing. This test is performed only for one channel and one actuation logic at a time by periodic automatic test.

Manual ESF Actuation Testing

Manual ESF actuation testing is tested every 31 days to verify that manual pushbutton can actuate the actuation logic as designed.

The 31 day Frequency is supported by operating experience, which shows that the Surveillance of the manual ESF actuation equipment is usually successful when performed at this Frequency.

Individual subgroups must also be tested, one at a time, to verify the individual ESFAS components will actuate when required.
Each ESFAS Function has an associated group of outputs. Each group of outputs is divided into subgroups. Outputs within a subgroup are tested concurrently and are selectively arranged so that concurrent actuation does not adversely affect plant operations.

The ESFAS initiation signals from the PPS are sent to separate ESF-CCS cabinets. Each cabinet contains the actuation logic for only one division. Therefore, a failure in one cabinet cannot affect the circuitry and actuated equipment of the other divisions.

Single failures of the actuation logic will cause, at worst, only a failure of a component, group of components, or one entire redundant train. The actuation of the remaining redundant division is sufficient for the protective action.

This Surveillance also verifies that an EDG start is separately actuated by SIAS, CSAS, and AFAS signals.

The 31 day Frequency on a STAGGERED TEST BASIS is supported by operating experience, which shows that the Surveillance of each ESF logic subgroup pair is usually successful when performed at this Frequency, and is adequate to ensure detection of problems with individual logic signals within this time frame.

Some components cannot be tested at power operation since their actuation may lead to plant trip or equipment damage. Actuation logic subgroups not tested at power operation must be tested in accordance with Note 1 to this SR.

In accordance with Note 2 to this SR, the pair of Actuation Logic subgroup channels A and C are tested during the first interval of the staggered 31 day Frequency, and the pair of Actuation Logic subgroup channels B and D are tested during the second interval of the staggered 31 day Frequency. Therefore, each pair of Actuation logic subgroup channels is tested during an interval of 62 days, plus applicable extensions.

SR 3.3.6.3

A CHANNEL FUNCTIONAL TEST of each diverse ESF manual actuation channel is performed to demonstrate OPERABILITY of the diverse manual ESF actuation circuit by manual actuation of each Function. This testing is performed every 18 months, which is adequate to ensure that the trip pushbutton can actuate the actuation logic as designed.
REFERENCES
1. FSAR, Section 7.3.
B 3.3 INSTRUMENTATION

B 3.3.7 Emergency Diesel Generator (EDG) – Loss of Voltage Start (LOVS)

BASES

BACKGROUND
The EDGs provide a source of emergency power when offsite power is either unavailable or insufficiently stable to allow safe plant operation. Undervoltage protection will generate a LOVS in the event a Loss of Voltage or Degraded Voltage condition occurs. There are two LOVS Functions for each Class 1E 4.16 kV bus (ESF bus).

Four undervoltage relays with inverse time characteristics are provided on each ESF bus for the purpose of detecting a sustained undervoltage condition or a loss of bus voltage. The relays are combined in a 2-out-of-4 logic to generate a LOVS if the voltage is below 75% for a short time or below 90% for a long time. The LOVS initiated actions are described in “Onsite Power Systems” (Ref. 1).

Trip Setpoints and Allowable Values

The trip setpoints and Allowable Values are based on the analytical limits presented in “Accident Analysis,” Reference 2. The selection of these trip setpoints is such that adequate protection is provided when all sensor and processing time delays are taken into account. To allow for calibration tolerances, instrumentation uncertainties, and instrument drift, Allowable Values specified in Setpoint Control Program (SCP) are conservatively adjusted with respect to the analytical limits. A detailed description of the methodology used to calculate the trip setpoints, including their explicit uncertainties, is provided in the SCP. The actual nominal trip setpoint is normally still more conservative than that required by the plant specific setpoint calculations. If the measured trip setpoint does not exceed the documented Surveillance acceptance criteria, the undervoltage relay is considered OPERABLE.

Setpoints in accordance with the Allowable Values will ensure that the consequences of accidents will be acceptable, providing the plant is operated from within the LCOs at the onset of the accident and the equipment functions as designed.
The undervoltage protection scheme has been designed to protect the plant from spurious trips caused by the offsite power source. This is made possible by the inverse voltage time characteristics of the relays used. A complete loss of offsite power will result in approximately a 1 second delay in LOVS actuation. The EDG starts and is available to accept loads within a 17 second time interval on the Engineered Safety Features Actuation System (ESFAS) or LOVS. Emergency power is established within the maximum time delay assumed for each event analyzed in the accident analysis (Ref. 2).

Since there are four protective channels in a 2-out-of-4 trip logic for each train of the 4.16 kV power supply, no single failure will cause or prevent protective system actuation. This arrangement meets IEEE Std 603 criteria (Ref. 3).

The EDG – LOVS is required for Engineered Safety Features (ESF) Systems to function in any accident with a loss of offsite power. Its design basis is that of the ESFAS.

Accident analyses credit the loading of the EDG based on a loss of offsite power during a loss of coolant accident. The actual EDG start has historically been associated with the ESFAS actuation. The safety injection actuation signal (SIAS), containment spray actuation signal (CSAS), or auxiliary feedwater actuation signal (AFAS) automatically starts the EDG, but the EDG breaker is not connected to the ESF buses, if preferred offsite AC power is available. The diesel loading has been included in the delay time associated with each safety system component requiring EDG supplied power following a loss of offsite power. The analysis assumes a non-mechanistic EDG loading, which does not explicitly account for each individual component of the loss of power detection and subsequent actions. This delay time includes contributions from the EDG start, EDG loading, and safety injection system component actuation. The response of the EDG to a loss of power must be demonstrated to fall within this analysis response time when including the contributions of all portions of the delay.

The required channels of LOVS, in conjunction with the ESF Systems powered from the EDGs, provide plant protection in the event of any of the analyzed accidents discussed in Reference 2, in which a loss of offsite power is assumed. LOVS channels are required to meet the redundancy and testability requirements of 10 CFR Part 50, Appendix A, GDC 21 (Ref. 4).
APPLICABLE SAFETY ANALYSES (continued)

The delay times assumed in the safety analysis for the ESF equipment include the 17 second EDG start delay and the appropriate sequencing delay, if applicable. The response times for ESFAS actuated equipment in LCO 3.3.5, “Engineered Safety Features Actuation System (ESFAS) Instrumentation,” include the appropriate EDG loading and sequencing delay.

The EDG – LOVS channels satisfy Criterion 3 of 10 CFR 50.36(c)(2)(ii).

LCO

The LCO for the LOVS requires that four channels per bus of each LOVS instrumentation Function be OPERABLE in MODES 1, 2, 3, and 4 and when the associated EDG is required to be OPERABLE by LCO 3.8.2, “AC Sources – Shutdown.” The LOVS supports safety systems associated with the ESFAS. In MODES 5 and 6, the four channels must be OPERABLE whenever the associated EDG is required to be OPERABLE to ensure that the automatic start of the EDG is available when needed.

Actions allow maintenance (trip channel) bypass of individual channels. Plants are restricted to 48 hours in a trip channel bypass condition before either restoring the Function to four channel operation (2-out-of-4 logic) or placing the channel in trip (one-out-of-three logic). At units where adequate channel to channel independence has been demonstrated, specific exceptions have been approved by the NRC staff to permit one of the 2-out-of-4 channels to be bypassed for an extended period of time.

Loss of LOVS Function could result in the delay of safety system initiation when required. This could lead to unacceptable consequences during accidents. During the loss of offsite power, which is an anticipated operational occurrence, the EDG powers the motor driven auxiliary feedwater pumps. Failure of these pumps to start would leave only the one turbine driven pump as well as an increased potential for a loss of decay heat removal through the secondary system.

Allowable Values and nominal trip setpoints are specified for each Function in the LCO in the SCP. The nominal setpoints are selected to ensure that the setpoint measured by CHANNEL FUNCTIONAL TESTS does not exceed the Allowable Value if the bistable is performing as required. Operation with a trip setpoint less conservative than the nominal trip setpoint, but within the Allowable Value, is acceptable, provided that operation and testing is consistent with the assumptions of the SCP.
A channel is inoperable if its actual trip setpoint is not within its required Allowable Value.

**APPLICABILITY**

The EDG – LOVS actuation Function is required in MODES 1, 2, 3, and 4 because ESF Functions are designed to provide protection in these MODES. Actuation in MODE 5 or 6 is required whenever the required EDG must be OPERABLE, so that it can perform its function on a loss of power or degraded power to the vital bus.

**ACTIONS**

A LOVS channel is inoperable when it does not satisfy the OPERABILITY criteria for the channel's function. The most common cause of channel inoperability is outright failure or drift of the bistable or process module sufficient to exceed the tolerance allowed by the plant specific setpoint analysis. Typically, the drift is found to be small and results in a delay of actuation rather than a total loss of function. Determination of setpoint drift is generally made during the performance of a CHANNEL FUNCTIONAL TEST when the instrument is set up for adjustment to bring it within specification. If the actual trip setpoint is not within the Allowable Value, the channel is inoperable, and the appropriate Conditions must be entered.

In the event a channel's trip setpoint is found non-conservative with respect to the Allowable Value, or the channel is found inoperable, then all affected Functions provided by that channel must be declared inoperable and the LCO Condition entered. The required channels are specified on a per EDG basis.

When the number of inoperable channels in a trip Function exceeds those specified in any related Condition associated with the same trip Function, then the plant is outside the safety analysis. Therefore, LCO 3.0.3 should be entered immediately if applicable in the current MODE of operation.

A Note has been added to clarify the application of Completion Time rules. The Conditions of this Specification may be entered independently for each EDG – LOVS Function. The Completion Times of the inoperable channels of a Function will be tracked separately for each Function, starting from the time the Condition was entered for that Function.

**A.1 and A.2**

Condition A applies if one channel is inoperable for one or more Functions per EDG bus.
If the channel cannot be restored to OPERABLE status, the affected channel should either be bypassed or tripped within 1 hour (Required Action A.1).

Placing this channel in either Condition ensures that logic is in a known configuration. In trip, the LOVS logic is one-out-of-three. In bypass, the LOVS logic is 2-out-of-3 and interlocks prevent bypass of a second channel for the affected Function. The 1 hour Completion Time is sufficient to perform these Required Actions.

Once Required Action A.1 has been complied with, Required Action A.2 allows prior to entering MODE 2 following the next MODE 5 entry to repair the inoperable channel. If the channel cannot be restored to OPERABLE status, the plant cannot enter MODE 2 following the next MODE 5 entry. The time allowed to repair or trip the channel is reasonable to repair the affected channel while ensuring that the risk involved in operating with the inoperable channel is acceptable. The prior to entering MODE 2 following the next MODE 5 entry Completion Time is based on adequate channel independence, which allows a 2-out-of-3 channel operation since no single failure will cause or prevent a reactor trip.

B.1 and B.2

Condition B applies if two channels are inoperable for one or more Functions.

If the channel cannot be placed in bypass or trip within 1 hour, the Conditions and Required Action for the associated EDG made inoperable by EDG – LOVS instrumentation are required to be entered. Alternatively, one affected channel is required to be bypassed and the other is tripped, in accordance with Required Action B.2. This places the Function in one-out-of-two logic. The 1 hour Completion Time is sufficient to perform the Required Actions.

One of the two inoperable channels will need to be restored to OPERABLE status prior to the next required CHANNEL FUNCTIONAL TEST because channel surveillance testing on an OPERABLE channel requires that the OPERABLE channel be placed in bypass. However, it is not possible to bypass more than one EDG – LOVS channel, and placing a second channel in trip will result in a loss of voltage diesel start signal. Therefore, if one EDG – LOVS channel is in trip and a second channel is in bypass, a third inoperable channel would place the unit in LCO 3.0.3.
After one channel is restored to OPERABLE status, the provisions of Condition A still apply to the remaining inoperable channel.

C.1

Condition C applies when more than two undervoltage or degraded voltage channels on a single bus are inoperable.

Required Action C.1 requires all but two channels to be restored to OPERABLE status within 1 hour. With more than two channels inoperable, the logic is not capable of providing the EDG – LOVS signal for valid Loss of Voltage or Degraded Voltage conditions. The 1 hour Completion Time is reasonable to evaluate and take action to correct the degraded condition in an orderly manner and takes into account the low probability of an event requiring LOVS occurring during this interval.

D.1

Condition D applies if the Required Actions and associated Completion Times are not met.

Required Action D.1 ensures that Required Actions for the affected EDG inoperabilities are initiated. Depending upon plant MODE, the ACTIONS specified in LCO 3.8.1, “AC Sources – Operating,” or LCO 3.8.2 are required immediately.

The following SRs apply to each EDG – LOVS Function.

SR 3.3.7.1

Performance of the CHANNEL CHECK ensures that a gross failure of instrumentation has not occurred. A CHANNEL CHECK is normally a comparison of the indicated output of the potential transformers that feed the LOVS undervoltage relays. It is based on the assumption that instrument channels monitoring the same parameter should read approximately the same value. Significant deviations between the two channels could be an indication of excessive drift in one of the channels or of something even more serious. CHANNEL CHECK will detect gross channel failure; thus, it is key to verifying that the instrumentation continues to operate properly between each CHANNEL CALIBRATION.
SURVEILLANCE REQUIREMENTS (continued)

Agreement criteria are determined by the plant staff based on a combination of channel instrument uncertainties, including indication and readability. If the channels are within the criteria, it is an indication that the channels are OPERABLE.

The Frequency, about once every shift, is based upon operating experience that demonstrates channel failure is rare. Since the probability of two random failures in redundant channels in any 12 hour period is extremely low, the CHANNEL CHECK minimizes the chance of loss of protective function due to failure of redundant channels. The CHANNEL CHECK supplements less formal, but more frequent, checks of channel OPERABILITY during normal operational use of the displays associated with the LCO required channels.

SR 3.3.7.2

A CHANNEL FUNCTIONAL TEST is performed to ensure that the entire CHANNEL will perform its intended function when needed. A successful test of the required contacts of a channel relay may be performed by the verification of the change of state of a single contact of the relay. This clarifies what is an acceptable CHANNEL FUNCTIONAL TEST of a relay. This is acceptable because all of the other required contacts of the relay are verified by other Technical Specifications (TS) and non-TS tests at least once per refueling interval with applicable extensions.

The Frequency of 92 days is based on plant operating experience with regard to channel OPERABILITY and drift, which demonstrates that failure of more than one channel of a given Function in any 92 day Frequency is a rare event. The SCP has controls which require verification that the instrument channel functions as required by verifying the as-left and as-found settings are consistent with those established by the setpoint methodology.

SR 3.3.7.3

SR 3.3.7.3 is the performance of a CHANNEL CALIBRATION. The CHANNEL CALIBRATION verifies the accuracy of each component within the instrument channel. This includes calibration of the undervoltage relays and demonstrates that the equipment falls within the specified operating characteristics defined by the manufacturer. The Surveillance verifies that the channel responds to a measured parameter within the necessary range and accuracy. CHANNEL CALIBRATION leaves the channel adjusted to account for instrument drift between successive surveillances to ensure the instrument channel remains
operational. The SCP has controls which require verification that the instrument channel functions as required by verifying the as-left and as-found settings are consistent with those established by the setpoint methodology.

The setpoints, as well as the response to a Loss of Voltage and Degraded Voltage test, shall include a single point verification that the trip occurs within the required delay time as shown in Reference 1. The Frequency is based upon the assumption of an 18 month calibration interval for the determination of the magnitude of equipment drift in the setpoint analysis.

REFERENCES

1. FSAR, Chapter 8.
2. FSAR, Chapter 15.
B 3.3 INSTRUMENTATION

B 3.3.8 Containment Purge Isolation Actuation Signal (CPIAS)

BASES

BACKGROUND

This LCO encompasses the CPIAS, which is an Engineered Safety Feature (ESF) instrumentation and control system that performs a containment isolation actuation function required for plant protection against the uncontrolled release of radioactivity but is not otherwise included in LCO 3.3.6, “Engineered Safety Features Actuation System (ESFAS) Logic and Manual Trip,” or LCO 3.3.7, “Emergency Diesel Generator (EDG) – Loss of Voltage Start (LOVS).”

The CPIAS provides protection from the release of radioactivity and radioactive contamination in the containment in the event a fuel assembly should be severely damaged during handling. It also closes the purge valves during plant operation in response to a Reactor Coolant System (RCS) leak.

The CPIAS will detect any abnormal amounts of radioactive material in the containment and will initiate purge valve closure to limit the release of radioactivity to the environment. Both the low and high volume purge supply and exhaust valves are closed on a CPIAS when a high radiation level in containment is detected.

The CPIAS includes two independent, redundant logic divisions, including actuation logic. Each division employs two sensors, each one detecting gamma (area).

If the signal from any one of these four sensors exceeds the bistable logic trip setpoint, both CPIAS Division A and Division B will be actuated (1-out-of-4 logic).

The upper operating area radiation sensors monitor loss of coolant accident (LOCA). A breach of the reactor coolant pressure boundary is detected by this sensor. The measurement range reflects the purpose and intended function and is from 10 to 1E8 mSv/hr (1.0 to 1E7 rem/hr).

The operating area radiation sensors monitor the refueling operation to detect a fuel handling accident condition. These sensors generate a containment purge isolation actuation signal (CPIAS) should a fuel handling accident occur. The measurement range reflects the purpose and intended function and is from 1E-3 to 1E2 mSv/hr (1E-4 to 10 rem/hr).
The operating area radiation monitors are provided to input signals for a one-out-of-two coincident logic. Even though not required, the two upper operating area monitors can be used in a redundant capacity to the operating area radiation monitors. Therefore, the signals from the upper operating area radiation monitors are inputted into the CPIAS coincidence logic to take advantage of this capability and the 1-out-of-2 coincident logic is taken twice to ensure required safety function.

Each CPIAS division actuates a separate series valve in the containment low and high volume purge supply and return lines. Either CPIAS division controls sufficient equipment to perform the isolation function. These valves are also isolated on a safety injection actuation signal (SIAS) and containment isolation actuation signal (CIAS).

**Nominal Trip Setpoints and Allowable Values**

The nominal trip setpoints (NTSPs) used in the bistable logic are based on the accident analyses’ analytical limits (Ref. 1). The selection of NTSPs is such that adequate protection is provided when all sensor and processing time delays are taken into account.

To allow for calibration tolerances, instrumentation uncertainties, and instrument drift, actuation setpoint Allowable Values specified in the Setpoint Control Program (SCP) are conservatively calculated with respect to the analytical limits. The actual NTSP entered into the bistable logic is more conservative than the Allowable Value to account for changes in random measurement errors detectable by a CHANNEL FUNCTIONAL TEST.

One example of such a change in measurement error is drift of the transmitter during the surveillance interval. If the as-found actuation setting measured by the CHANNEL FUNCTIONAL TEST remains conservative with respect to the As-Found Tolerance (AFT) band around the previous as-left setting between successive CHANNEL CALIBRATIONS and does not exceed the Allowable Value, the instrument channel is considered OPERABLE, provided the channel is performing normally as expected.

Setpoints in accordance with the Allowable Value will ensure that safety limits are not violated during anticipated operational occurrences (AOOs) and the consequences of design basis accidents will be acceptable, providing the plant is operated from within the LCOs at the onset of the AOO or accident and the equipment functions as designed.
The CPIAS is a backup to the CIAS Systems in MODES 1, 2, 3, and 4 and will close the containment low and high volume purge supply and exhaust line isolation valves in the event of high radiation levels resulting from a primary leak in the containment.

The CPIAS is also required to close the containment purge line isolation valves in the event of the fuel handling accident in containment, as described in Reference 1. This accident is a limiting case representing a class of accidents that may involve radioactivity release in containment without CIAS actuation. The CPIAS ensures the consequences of a dropped irradiated fuel assembly in containment are not as severe as a dropped irradiated fuel assembly in the fuel handling area. This ensures that the offsite consequences of fuel handling accidents in containment are within 10 CFR 50.34 limits (Ref. 2).

The CPIAS satisfies Criterion 3 of 10 CFR 50.36(c)(2)(ii).

LCO LCO 3.3.8 requires one CPIAS division to be OPERABLE. The required division consists of one instrument division with two area radiation monitor channels, one Actuation Logic division; and one Manual Actuation division.

The specific Allowable Values for the actuation (trip) setpoints of the CPIAS are listed in the Setpoint Control Program required documentation.

Operation with a trip setpoint less conservative than the NTSP, but within its Allowable Value, is acceptable provided that the difference between the actual trip setting and the Allowable Value is equal to or greater than the drift allowance assumed for each actuation in the calculated NTSP, which is derived from the analytical limit in the transient and accident analyses.

Each specified Allowable Value is more conservative than the analytical limit assumed in the transient and accident analyses in order to account for instrument uncertainties appropriate to the actuation function.

These uncertainties are defined in the NRC approved setpoint methodology specified by the Setpoint Control Program, Specification 5.5.19.

The Bases for the LCO on CPIAS are discussed below for each Function:

a. Manual Actuation

The LCO on the CPIAS Manual Actuation Function division backs up the CPIAS Automatic Actuation Function division and ensures
operators have the capability to rapidly initiate the CPIAS Function if any parameter is trending toward its NTSP. Only one Manual Actuation division of CPIAS is required in MODES 1, 2, 3, and 4, since the CPIAS is redundant to the CIAS and SIAS for isolating the purge supply and exhaust line containment penetrations. Only one Manual Actuation division of CPIAS is required in MODE 6 during CORE ALTERATIONS or movement of irradiated fuel assemblies, when reactor vessel water level is required by LCO 3.9.6, "Refueling Water Level," to be at least 7.0 m (23 ft) above the top of the reactor vessel flange (high water level). One Manual Actuation division of CPIAS is also required in MODE 6 (high water level) when an OPERABLE Containment Purge System is being relied upon to close the containment purge isolation valves in accordance with LCO 3.9.3.c.2, by using the required CPIAS Manual Actuation division. Acceptable mitigation of a fuel handling accident is assured in the event of a Manual Actuation division failure, since there are additional means of closing the containment purge isolation valves.

In MODE 5 with RCS loops not filled, and in MODE 6 with reactor vessel water level less than 7.0 m (23 ft) above the top of the reactor vessel flange (low water level) the unit is in a reduced water inventory condition and LCO 3.6.7, "Containment Penetrations - Shutdown Operations," is applicable. With the containment purge system unisolated, LCO 3.6.7.c.2 requires that each penetration providing direct access from the containment atmosphere to the outside atmosphere is exhausting through OPERABLE Containment Purge System air cleaning units (ACUs), and is capable of being closed by an OPERABLE Containment Purge and Exhaust Isolation System. In the event shutdown cooling is lost in MODE 6, Required Action A.4 of LCO 3.9.4, "Shutdown Cooling System (SCS) and Coolant Circulation - High Water Level," and Required Action B.4 of LCO 3.9.5, "SCS and Coolant Circulation - Low Water Level," require within 4 hours placing the containment building penetrations in the required status as specified in LCO 3.6.7. When LCO 3.6.7.c.2 is relied upon to mitigate a loss of decay heat removal capability, which could lead to reactor core fuel damage, LCO 3.3.8 requires only one Manual Actuation division of CPIAS. Acceptable mitigation of a core damage accident is assured in the event of a Manual Actuation division failure, since there are additional means of closing the containment purge isolation valves.
b. Containment Area Radiation Monitors and Bistable Logic

The LCO on the CPIAS instrument Function division requires that each of the two area radiation monitor channels be OPERABLE for sending a bistable logic trip signal to the Actuation Logic division. The two area radiation monitor channels are not totally redundant to each other, since the indication overlap only ranges from 10 mSv/hour to 100 mSv/hour (1 rem/hr to 10 rem/hr); however both NTSPs are within this range.

The CPIAS NTSP is selected to allow detection of small deviations from the normal background radiation level. The absolute value of the NTSP in MODES 5 and 6 differs from the NTSP in MODES 1, 2, 3, and 4 so that a fuel handling accident can be detected in the lower levels of radiation expected in MODES 5 and 6. The containment upper operating area radiation monitor channel supports the CPIAS during MODES 1, 2, 3, and 4, and has a higher NTSP. The containment operating area radiation monitor channel supports the CPIAS during MODES 5 and 6, and has a lower NTSP. In any MODE, just one area radiation monitor channel is relied upon for initiating an automatic containment purge line isolation.

In the event shutdown cooling is lost in MODE 5 with RCS loops not filled, or in MODE 6 with low RCS water level, and if LCO 3.6.7.c.2 is relied upon to mitigate a loss of decay heat removal capability, which could lead to reactor core fuel damage, LCO 3.3.8 requires only one CPIAS instrument division with two area radiation monitor channels for sending a bistable logic trip signal to the one required CPIAS Actuation Logic division. Acceptable mitigation of a core damage accident is assured in the event of a CPIAS instrument division failure, since there are additional means of closing the containment purge isolation valves.

c. Actuation Logic

One Actuation Logic division is required, since the containment purge isolation valves can be shut independently of the CPIAS signal either manually from the main control room (MCR) or using either the SIAS or CIAS push button.
APPLICABILITY

In MODES 1, 2, 3, and 4, the low volume purge line isolation valves may be open. In these MODES, it is necessary to ensure the valves will shut in the event of a primary coolant leak in containment whenever any of the containment purge valves are open.

With the purge line isolation valves open during CORE ALTERATIONS or movement of irradiated fuel assemblies within containment, there is the possibility of a fuel handling accident requiring CPIAS on high radiation in containment.

With the purge line isolation valves open during RCS low water level conditions in MODES 5 and 6, there is a possibility of a loss of shutdown cooling, which could lead to a reactor core fuel damage event requiring CPIAS on high radiation in containment.

The APPLICABILITY is modified by a Note, which states that the CPIAS Specification is only required when the associated containment purge or exhaust line penetration flow path is not isolated by at least one closed and deactivated automatic valve, closed manual valve, or blind flange.

ACTIONS

A CPIAS division is inoperable when it does not satisfy the OPERABILITY criteria for the division’s function. The most common cause of process instrument channel inoperability is outright failure or drift of the sensor, transmitter, or analog signal processing equipment sufficient to exceed the tolerance allowed by the Nuclear Regulatory Commission (NRC) approved setpoint methodology specified in the Setpoint Control Program, Specification 5.5.19. Typically, the drift is not large and would result in a delay of actuation rather than a total loss of function. This determination is generally made during the performance of a CHANNEL FUNCTIONAL TEST when the process instrument is set up for adjustment to bring it within specification. If the as-found actuation setting is not consistent with the Allowable Value, the division must be declared inoperable immediately, and the appropriate Conditions must be entered.

In the event a division’s actuation setting is found nonconservative with respect to the Allowable Value, or the sensor, instrument loop, signal processing electronics, or bistable logic processor is found inoperable, then all affected Functions provided by that division are required to be declared inoperable and the LCO Condition entered for the particular protective function affected.

When the number of inoperable channels or divisions of an ESF actuation Function exceeds that specified in any related Condition associated with the same ESF actuation Function, then the unit is outside the safety analyses. Therefore, LCO 3.0.3 is immediately entered if applicable in the current MODE of operation.
Condition A applies to the failure of the CPIAS required Manual Actuation division, required Actuation Logic division, and one or more of the required CPIAS instrument division area radiation monitor channels in MODES 1, 2, 3, and 4. The Required Action is to immediately enter the applicable Conditions and Required Actions of LCO 3.6.3, “Containment Isolation Valves,” for containment purge isolation valves made inoperable by CPIAS instrumentation. The Completion Time accounts for the condition that the capability to isolate containment on valid containment high radiation or manual signals is degraded during power operation, startup, standby, or hot shutdown MODES.

Condition B applies when the Required Action and associated Completion Time of Condition A are not met in MODE 1, 2, 3, or 4. If Required Action A cannot be met within the required Completion Time, the plant must be brought to a MODE in which the LCO does not apply. To achieve this status, the plant must be brought to at least MODE 3 within 6 hours and MODE 5 within 36 hours.

Condition C applies to the same conditions as are described in Condition A, but during CORE ALTERATIONS or during the movement of irradiated fuel assemblies within containment. Required Action C.1 is to place the containment purge and exhaust isolation valves in the closed position. The Required Action immediately performs the isolation function of the CPIAS. Required Actions C.2.1 and C.2.2 may be performed in lieu of Required Action C.1. Required Action C.2.1 requires the suspension of CORE ALTERATIONS and Required Action C.2.2 requires suspension of movement of irradiated fuel in containment immediately. The Completion Time accounts for the fact that the automatic capability to isolate containment on valid containment high radiation signals is degraded during conditions in which a fuel handling accident is possible and CPIAS provides the only automatic mitigation of radiation release.
SURVEILLANCE REQUIREMENTS

SR 3.3.8.1
Performance of the CHANNEL CHECK once every 12 hours ensures that a gross failure of instrumentation has not occurred on the required upper operating area radiation monitor channels and operating area radiation monitor channels used in the CPIAS. A CHANNEL CHECK is normally a comparison of the parameter indicated on one channel to a similar parameter on other channels. Both containment upper operating area radiation monitor channels and both containment operating area radiation monitor channels need to be OPERABLE so comparison can be made. It is based on the assumption that instrument channels monitoring the same parameter should read approximately the same value. Significant deviations between the two instrument channels could be an indication of excessive instrument drift in one of the channels or of something even more serious. CHANNEL CHECK will detect gross channel failure. Thus, it is key to verifying the instrumentation continues to operate properly between each CHANNEL CALIBRATION.

Agreement criteria are determined by the plant staff based on a combination of the channel instrument uncertainties, including indication and readability. If a channel is outside the criteria, it could be an indication that the transmitter or the signal processing equipment has drifted outside its limit.

The Surveillance Frequency, about once every shift, is based on operating experience that demonstrates the rarity of channel failure. Since the probability of two random failures in redundant channels in any 12 hour period is low, the CHANNEL CHECK minimizes the chance of loss of protective function due to failure of redundant channels. The CHANNEL CHECK supplements less formal, but more frequent, checks of channel OPERABILITY during normal operational use of the displays associated with the LCO required channels.

SR 3.3.8.2
A CHANNEL FUNCTIONAL TEST is performed on each required upper operating area radiation monitor channel and each required operating area radiation monitor channel to ensure the entire channel will perform its intended function. The SCP has controls which require verification that the instrument channel functions as required by verifying the as-left and as-found settings are consistent with those established by the setpoint methodology. The Frequency of 92 days is based on plant operating experience with regard to channel OPERABILITY and drift, which demonstrates that failure of more than one channel of a given Function in any 92 day Frequency is a rare event.
A Note to the SR indicates this Surveillance is required to be met in MODES 1, 2, 3, and 4 only.

SR 3.3.8.3

A CHANNEL FUNCTIONAL TEST is performed on each required upper operating area radiation monitor channel and each required operating area radiation monitor channel to ensure the entire channel will perform its intended function. The SCP has controls which require verification that the instrument channel functions as required by verifying the as-left and as-found settings are consistent with those established by the setpoint methodology. The Frequency of 92 days is based on plant operating experience with regard to channel OPERABILITY and drift, which demonstrates that failure of more than one channel of a given Function in any 92 day interval is a rare event.

A Note to the SR indicates that this test is only required to be met during CORE ALTERATIONS and during movement of irradiated fuel assemblies within containment and in MODE 5 with RCS loops not filled when relying on LCO 3.6.7.c.2, and in MODE 6 when relying on LCO 3.6.7.c.2 or LCO 3.9.3.c.2.

SR 3.3.8.4

Proper operation of the individual initiation circuit is verified by actuating these circuits during the CHANNEL FUNCTIONAL TEST of the required Actuation Logic division every 18 months. This will actuate the Function, operating all associated equipment. Proper operation of the equipment actuated by each division is thus verified. The Frequency of 18 months is based on plant operating experience with regard to channel OPERABILITY and drift, which demonstrates that failure of an Actuation Logic division of a given Function during any 18 month interval is a rare event. A Note to the SR indicates that this Surveillance includes verification of operation for each initiation circuit.

SR 3.3.8.5

CHANNEL CALIBRATION is a complete check of the instrument channel including the sensor. The Surveillance verifies that the channel responds to a measured parameter within the necessary range and accuracy. CHANNEL CALIBRATION leaves the channel adjusted to account for instrument drift between successive calibrations to ensure that the channel remains OPERABLE between successive surveillances.
SURVEILLANCE REQUIREMENTS (continued)

The SCP has controls which require verification that the instrument channel functions as required by verifying the as-left and as-found settings are consistent with those established by the NRC approved setpoint methodology.

The 18 month Frequency is based on the need to perform this Surveillance under the conditions that apply during a plant outage.

SR 3.3.8.6

This Surveillance ensures that the CPIAS division actuation response times are less than or equal to the maximum times assumed in the accident analyses (Ref. 1). The 18 month Frequency is based upon plant operating experience, which shows that random failures of instrumentation components causing serious response time degradation, but not channel failure, are infrequent occurrences. Testing of the final actuating devices, which make up the bulk of the response time, is included in the Surveillance.

SR 3.3.8.7

Every 18 months, a CHANNEL FUNCTIONAL TEST is performed on the required CPIAS Manual Actuation division.

This test verifies that the actuation push buttons are capable of providing manual actuation of the containment purge line isolation Function.

The 18 month Frequency is based on the need to perform this Surveillance under the conditions that apply during a plant outage. Operating experience has shown these components usually pass the Surveillance when performed at a Frequency of once every 18 months.

REFERENCES
1. FSAR, Chapter 15.
2. 10 CFR 50.34.
B 3.3 INSTRUMENTATION

B 3.3.9 Control Room Emergency Ventilation Actuation Signal (CREVAS)

BASES

BACKGROUND

This LCO encompasses the CREVAS, which is an Engineered Safety Feature (ESF) instrumentation and control system that performs an emergency ventilation actuation function required for plant protection but is not otherwise included in LCO 3.3.6, “Engineered Safety Features Actuation System (ESFAS) Logic and Manual Trip,” or LCO 3.3.7, “Emergency Diesel Generator (EDG) – Loss of Voltage Start (LOVS).” This is a balance of plant (BOP) ESFAS Function that, because of differences in purpose, design, and operating requirements, is not included in LCO 3.3.6 and LCO 3.3.7.

The CREVAS terminates the normal supply of outside air to the main control room (MCR) and initiates actuation of the control room emergency air cleaning unit to minimize operator radiation exposure. The CREVAS includes two independent, redundant divisions, including actuation logic. Each CREVAS division employs two separate sensors and detects gaseous activity. Since there are separate sensors in each division, the divisions are redundant. If the signal from any one of these four sensors exceeds the bistable logic trip setpoint, both CREVAS Division A and Division B will be actuated (one-out-of-four logic). Each CREVAS division actuates separate equipment. Actuating either CREVAS division will perform the intended function. Control room isolation also occurs on a safety injection actuation signal (SIAS).

Nominal Trip Setpoints and Allowable Values

The nominal trip setpoints (NTSPs) used in the bistable logic are based on the accident analyses’ analytical limits (Ref. 1). The selection of NTSPs is such that adequate protection is provided when all sensor and processing time delays are taken into account. To allow for calibration tolerances, instrumentation uncertainties, and instrument drift, Allowable Values specified in the Setpoint Control Program (SCP) are conservatively calculated with respect to the analytical limits. The actual NTSP entered into the bistable logic is more conservative than the Allowable Value to account for changes in random measurement errors detectable by a CHANNEL FUNCTIONAL TEST.
One example of such a change in measurement error is drift of the transmitter during the surveillance interval. If the as-found actuation setting measured by the CHANNEL FUNCTIONAL TEST remains conservative with respect to the as-found tolerance (AFT) band around the previous as-left setting between successive CHANNEL CALIBRATIONS and does not exceed the Allowable Value, the instrument channel is considered OPERABLE, provided the channel is performing normally as expected.

Setpoints in accordance with the Allowable Value will ensure that the MCR occupant dose limit is not violated during anticipated operational occurrences (AOOs) and the consequences of design basis accidents will be acceptable, providing the plant is operated from within the LCOs at the onset of the AOO or accident and the equipment functions as designed.

The CREVAS, in conjunction with the Control Room Area Heating, Ventilation, and Air Conditioning (HVAC) System maintains the MCR atmosphere within conditions suitable for prolonged occupancy throughout the duration of any one of the accidents discussed in Reference 1. The radiation exposure of MCR personnel, through the duration of any one of the postulated accidents discussed in "Transient and Accident Analysis," FSAR, Chapter 15 (Ref. 1), does not exceed the limits set by 10 CFR Part 50, Appendix A, GDC 19 (Ref. 2).

The CREVAS satisfies Criterion 3 of 10 CFR 50.36(c)(2)(ii).

LCO 3.3.9 requires one CREVAS division to be OPERABLE. The required division consists of one instrument division with one radiation monitor channel, one Manual Actuation division; and one Actuation Logic division. The specific Allowable Values for the actuation (trip) setpoints of the CREVAS are listed in the SCP required documentation.

Operation with an actuation setpoint less conservative than the NTSP, but within its allowable value, is acceptable provided that the difference between the actual trip setting and the allowable value is equal to or greater than the drift allowance assumed for each actuation in the calculated NTSP, which is derived from the analytical limit in the transient and accident analyses.
Each specified Allowable Value is more conservative than the analytical limit assumed in the transient and accident analysis in order to account for instrument uncertainties appropriate to the actuation function. A channel is inoperable if its actual actuation setpoint is not within its!required Allowable Value.

These uncertainties are defined in the Nuclear Regulatory Commission (NRC) approved setpoint methodology specified by the Setpoint Control Program, Specification 5.5.19.

The Bases for the LCO on the CREVAS are discussed below for each Function:

a. Manual Actuation

The LCO on the CREVAS Manual Actuation Function division backs up the CREVAS Automatic Actuation Function division and ensures operators have the capability to rapidly initiate the CREVAS Function if any parameter is trending toward its NTSP. One Manual Actuation division of CREVAS must be OPERABLE. This considers that the manual actuation capability is a backup and that other means are available to actuate the redundant division if required, including manual SIAS.

b. Gaseous Radiation

Both channels of gaseous radiation detection in the required division are required to be OPERABLE to ensure the MCR isolates on high gaseous concentration.

c. Actuation Logic

One Actuation Logic division must be OPERABLE, since there are alternate means available to actuate the redundant division, including SIAS.

APPLICABILITY

The CREVAS Functions must be OPERABLE in MODES 1, 2, 3, and 4, during CORE ALTERATIONS, and during movement of irradiated fuel assemblies to ensure a habitable environment for the MCR operators.
A CREVAS division is inoperable when it does not satisfy the OPERABILITY criteria for the division’s function. The most common cause of process instrument channel inoperability is outright failure or drift of the sensor, transmitter, or analog signal processing equipment sufficient to exceed the tolerance allowed by the NRC approved setpoint methodology specified in the SCP, Specification 5.5.19. Typically, the drift is not large and would result in a delay of actuation rather than a total loss of function. This determination is generally made during the performance of a CHANNEL FUNCTIONAL TEST when the process instrument is set up for adjustment to bring it within specification.

If the as-found actuation setting is not within the Allowable Value, the division is inoperable and the appropriate Conditions must be entered:

A.1, B.1, B.2, C.1, C.2.1, C.2.2, and C.2.3

Conditions A, B, and C are applicable to manual and automatic actuation of the Control Room Area HVAC System by CREVAS. Condition A applies to the failure of the CREVAS required Manual Actuation division, required Actuation Logic division, or required instrument division with one required radiation monitor channel inoperable in MODE 1, 2, 3, or 4. Entry into this Condition requires action to either restore the failed division(s) or manually perform the CREVAS safety function (Required Action A.1).

The Completion Time of 1 hour is sufficient to complete the Required Actions and accounts for the fact that CREVAS supplements MCR isolation by other Functions (e.g., SIAS) in MODES 1, 2, 3, and 4. If the channel cannot be restored to OPERABLE status, the plant must be brought to a MODE in which the LCO does not apply. To achieve this status, the plant must be brought to at least MODE 3 within 6 hours (Required Action B.1) and to MODE 5 within 36 hours (Required Action B.2). The Completion Times of 6 hours and 36 hours for reaching MODES 3 and 5 from MODE 1 are reasonable, based on operating experience and normal cooldown rates, for reaching the required MODE from full power conditions in an orderly manner and without challenging plant safety systems.

Condition C applies to the failure of CREVAS required Manual Actuation division, required Actuation Logic division, or required instrument division with one required radiation monitor channel inoperable during CORE ALTERATIONS or movement of irradiated fuel assemblies. The Required Actions are immediately taken to place one OPERABLE Control Room Area HVAC System train in the emergency radiation protection mode, or to suspend CORE ALTERATIONS, positive reactivity additions, and movement of irradiated fuel assemblies.
BASES

ACTIONS (continued)

The Completion Time recognizes the fact that the radiation signals are the only Functions available to initiate MCR isolation in the event of a fuel handling accident.

SURVEILLANCE REQUIREMENTS

SR 3.3.9.1

Performance of the CHANNEL CHECK once every 12 hours ensures that a gross failure of instrumentation has not occurred. A CHANNEL CHECK is normally a comparison of the parameter indicated on one channel to a similar parameter on other channels. It is based on the assumption that instrument channels monitoring the same parameter should read approximately the same value.

Significant deviations between the two instrument channels could be an indication of excessive instrument drift in one of the channels or of something even more serious.

CHANNEL CHECK will detect gross channel failure; thus, it is key to verifying the instrumentation continues to operate properly between each CHANNEL CALIBRATION.

Agreement criteria are determined by the plant staff based on a combination of the channel instrument uncertainties, including indication and readability. If a channel is outside the criteria, it could be an indication that the transmitter or the signal processing equipment has drifted outside its limit.

The Frequency, about once every shift, is based on operating experience that demonstrates the rarity of channel failure. Since the probability of two random failures in redundant channels in any 12 hour period is low, the CHANNEL CHECK minimizes the chance of loss of protective function due to failure of redundant channels. The CHANNEL CHECK supplements less formal, but more frequent, checks of channel OPERABILITY during normal operational use of the displays associated with the LCO required channels.

SR 3.3.9.2

A CHANNEL FUNCTIONAL TEST is performed on the required MCR radiation monitoring channel to ensure the entire channel will perform its intended function.
SURVEILLANCE REQUIREMENTS (continued)

The SCP has controls which require verification that the instrument channel functions as required by verifying the as-left and as-found settings are consistent with those established by the setpoint methodology.

The Frequency of 92 days is based on plant operating experience with regard to channel OPERABILITY and drift, which demonstrates that failure of more than one channel of a given Function in any 92 day interval is a rare event.

SR 3.3.9.3

Proper operation of the individual initiation circuit is verified by de-energizing these circuits during the CHANNEL FUNCTIONAL TEST of the required CREVAS Actuation Logic division every 18 months. This will actuate the Function, operating all associated equipment. Proper operation of the equipment actuated by each division is thus verified.

The Frequency of 18 months is based on plant operating experience with regard to channel OPERABILITY, which demonstrates that failure of an Actuation Logic division of a given Function in any 18 month interval is a rare event.

A Note to the SR indicates this Surveillance includes verification of operation for each initiation circuit.

SR 3.3.9.4

CHANNEL CALIBRATION is a complete check of the instrument channel including the sensor. The Surveillance verifies that the channel responds to a measured parameter within the necessary range and accuracy. The SCP has controls which require verification that the instrument channel functions as required by verifying the as-left and as-found settings are consistent with those established by the setpoint methodology. CHANNEL CALIBRATION leaves the channel adjusted to account for instrument drift between successive calibrations to ensure that the channel remains OPERABLE between successive surveillances.

The Frequency is based upon the assumption of an 18 month calibration interval for the determination of the magnitude of equipment drift in the setpoint analyses.
SR 3.3.9.5

Every 18 months, a CHANNEL FUNCTIONAL TEST is performed on the required CREVAS Manual Actuation division.

This test verifies that the actuation push buttons are capable of providing manual actuation of the control room emergency ventilation function.

The 18 month Frequency is based on the need to perform this Surveillance under the conditions that apply during a plant outage. Operating experience has shown these components usually pass the Surveillance when performed at a Frequency of once every 18 months.

SR 3.3.9.6

This Surveillance ensures that the CREVAS division actuation response times are less than the maximum times assumed in the accident analyses (Ref. 1). The 18 month Frequency is based upon plant operating experience, which shows that random failures of instrumentation components causing serious response time degradation, but not channel failure, are infrequent occurrences. Testing of the final actuating devices, which make up the bulk of the response time, is included in the Surveillance testing.

REFERENCES

1. FSAR, Chapter 15.

2. 10 CFR Part 50, Appendix A, GDC 19.
B 3.3 INSTRUMENTATION

B 3.3.10 Fuel Handling Area Emergency Ventilation Actuation Signal (FHEVAS)

BASES

BACKGROUND

This LCO encompasses the FHEVAS, which is an Engineered Safety Feature (ESF) instrumentation and control system that performs an emergency ventilation actuation function required for plant protection but is not otherwise included in LCO 3.3.6, "Engineered Safety Features Actuation System (ESFAS) Logic and Manual Trip," or LCO 3.3.7, "Emergency Diesel Generator (EDG) – Loss of Voltage Start (LOVS)." This is a balance of plant (BOP) ESFAS Function that, because of differences in purpose, design, and operating requirements, is not included in LCO 3.3.6 and LCO 3.3.7. Details of this LCO are for illustration only.

The FHEVAS provides protection from the release of radioactivity and radioactive contamination in the spent fuel pool area in the event that a spent fuel element ruptures during handling.

The FHEVAS will detect radioactivity from fission products in the fuel and will initiate appropriate actions so the release to the environment is limited. More detail is provided in Reference 1.

The FHEVAS includes two independent, redundant divisions, including actuation logic. Each FHEVAS division employs one separate sensor. Since there is a separate sensor in each division, the divisions are redundant. If the signal from any one of these four sensors exceeds the bistable logic trip setpoint, both FHEVAS Division A and Division B will be actuated (1-out-of-2 logic). Each FHEVAS division actuates separate equipment.

Nominal Trip Setpoints and Allowable Values

The nominal trip setpoints (NTSPs) used in the bistable logic are based on the accident analyses' analytical limits (Ref. 2). The selection of NTSPs is such that adequate protection is provided when all sensor and processing time delays are taken into account. To allow for calibration tolerances, instrumentation uncertainties, and instrument drift, Allowable Values specified in the setpoint control program (SCP) are conservatively calculated with respect to the analytical limits. The actual NTSP entered into the bistable logic is more conservative than the Allowable Value to account for changes in random measurement errors detectable by a CHANNEL FUNCTIONAL TEST.
Bases

Background (continued)

One example of such a change in measurement error is drift of the transmitter during the surveillance interval. If the as-found actuation setting measured by the CHANNEL FUNCTIONAL TEST remains conservative with respect to the as-found tolerance (AFT) band around the previous as-left setting between successive CHANNEL CALIBRATIONS and does not exceed the Allowable Value, the instrument channel is considered OPERABLE, provided the channel is performing normally as expected.

Setpoints in accordance with the Allowable Value will ensure that Safety Limits are not violated during anticipated operational occurrences (AOOs) and the consequences of design basis accidents will be acceptable, providing the plant is operated from within the LCOs at the onset of the AOO or accident and the equipment functions as designed.

Applicable Safety Analyses

The FHEVAS is required to isolate the Normal Fuel Handling Area Heating, Ventilation, and Air Conditioning (HVAC) System and automatically initiate the recirculation and filtration systems in the event of the fuel handling accident in the fuel handling area, as described in Reference 2. The FHEVAS helps ensure acceptable consequences for the dropping of a spent fuel bundle breaching up to 60 fuel pins.

The FHEVAS satisfies Criterion 3 of 10 CFR 50.36(c)(2)(ii).

LCO

LCO 3.3.10 requires one FHEVAS division to be OPERABLE. The required division consists of one instrument division with one radiation monitor channel, one Manual Actuation division; and one Actuation Logic division. The specific Allowable Values for the actuation (trip) setpoints of the FHEVAS are listed in the SCP required documentation.

Only the Allowable Values are specified for each actuation Function in the SRs. Operation with an actuation setpoint less conservative than the NTSP, but within its allowable value, is acceptable, provided that the difference between the actual trip setting and the Allowable Value is equal to or greater than the drift allowance assumed for each actuation in the calculated NTSP, which is derived from the analytical limit in the transient and accident analyses.

Each specified Allowable Value is more conservative than the analytical limit assumed in the transient and accident analyses in order to account for instrument uncertainties appropriate to the actuation Function.
Bases

LCO (continued)

These uncertainties are defined in the Nuclear Regulatory Commission (NRC) approved setpoint methodology specified by the SCP, Specification 5.5.19.

The Bases for the LCO on the FHEVAS are discussed below for each Function:

a. Manual Actuation

The LCO on the FHEVAS Manual Actuation Function division ensures that the FHEVAS Function can easily be initiated if any parameter is trending rapidly toward its setpoint. Components can be actuated independently of the FHEVAS. Both available divisions are required to ensure a single failure will not disable automatic initiation capability.

b. Area Radiation

The LCO on the two area radiation channels requires that each channel be OPERABLE for the required actuation logic.

c. Actuation Logic

Two divisions of actuation logic are required to be OPERABLE to ensure no single random failure can prevent automatic actuation.

Applicability

The FHEVAS Functions are required to be OPERABLE during movement of irradiated fuel in the fuel handling area. The FHEVAS isolates the fuel handling area in the event of a fuel handling accident.

The FHEVAS must be OPERABLE in during movement of irradiated fuel in the fuel handling area, since the FHEVAS isolates the fuel handling area in the event of a fuel handling accident.

Actions

An FHEVAS division is inoperable when it does not satisfy the OPERABILITY criteria for the division’s function. The most common cause of process instrument channel inoperability is outright failure or drift of the sensor, transmitter, or analog signal processing equipment sufficient to exceed the tolerance allowed by the NRC approved setpoint methodology specified in the Setpoint Control Program, Specification 5.5.19. Typically, the drift is not large and would result in a delay of actuation rather than a total loss of function. This determination is generally made during the performance of a CHANNEL FUNCTIONAL
TEST when the process instrument is set up for adjustment to bring it within specification. If the as-found actuation setting is not consistent with the Allowable Value in LCO 3.3.10, the division must be declared inoperable immediately and the appropriate Conditions must be entered.

In the event a division’s actuation setting is found non-conservative with respect to the Allowable Value, or the sensor, instrument loop, signal processing electronics, or bistable logic processor is found inoperable, then all affected Functions provided by that division are required to be declared inoperable and the LCO Condition entered for the particular protective function affected.

When the number of inoperable channels or divisions of an ESF actuation Function exceeds that specified in any related Condition associated ESF with the same actuation Function, the unit is outside the safety analyses. Therefore, LCO 3.0.3 is immediately entered if applicable in the current MODE of operation.

A.1 and A.2

Condition A applies only to those configurations when the fuel handling area HVAC is shared with the ESF equipment room.

Condition A applies to any FHEVAS Required Manual Actuation division, required Actuation Logic division, or required instrument division with required radiation monitor channel inoperable during movement of irradiated fuel in the fuel handling area.

The Required Actions place one OPERABLE Fuel Handling Area HVAC System train in emergency operation mode or suspend movement of irradiated fuel assemblies in the fuel handling area. These Required Actions are required to be completed immediately.

The Completion Time accounts for the higher likelihood of releases in the fuel handling area during fuel handling.

SURVEILLANCE REQUIREMENTS

Performance of the CHANNEL CHECK once every 12 hours ensures that a gross failure of instrumentation has not occurred. A CHANNEL CHECK is normally a comparison of the parameter indicated on one channel to a similar parameter on other channels. It is based on the assumption that instrument channels monitoring the same parameter should read approximately the same value.
SURVEILLANCE REQUIREMENTS (continued)

Significant deviations between the two instrument channels could be an indication of excessive instrument drift in one of the channels or of something even more serious. CHANNEL CHECK will detect gross channel failure; thus, it is key to verifying the instrumentation continues to operate properly between each CHANNEL CALIBRATION.

If only one radioactivity particulate monitor channel is required, surveillance of one radioactivity particulate monitor channel is performed by using a radioactive check source. The radioactive check source is generally built into the detector assembly and can be remotely activated by the operator. The radioactive check source is primarily used to check whether a particular radiation monitoring channel loop is live or functioning. When a check source is exposed to the detector on demand, if upscale measurement is indicated, the channel is assessed with channel live status by pass/fail criteria. The criteria are qualitative assessment, by observation, of channel behavior during operation.

Agreement criteria are determined by the plant staff based on a combination of the channel instrument uncertainties, including indication and readability. If a channel is outside the criteria, it could be an indication that the transmitter or the signal processing equipment has drifted outside its limit.

The Frequency, about once every shift, is based on operating experience that demonstrates the rarity of channel failure. Since the probability of two random failures in redundant channels in any 12 hour period is low, the CHANNEL CHECK minimizes the chance of loss of protective function due to failure of redundant channels. The CHANNEL CHECK checks channel OPERABILITY during normal operational use of the displays associated with the LCO required channels.

SR 3.3.10.2

A CHANNEL FUNCTIONAL TEST is performed on the required fuel handling area radiation monitor channel to ensure the entire channel will perform its intended function. The SCP has controls which require verification that the instrument channel functions as required by verifying the as-left and as-found settings are consistent with those established by the setpoint methodology.

The Frequency of 92 days is based on plant operating experience with regard to channel OPERABILITY and drift, which demonstrates that failure of more than one channel of a given Function in any 92 day Frequency is a rare event.
SR 3.3.10.3

Proper operation of the individual initiation circuit is verified by actuating these circuits during the CHANNEL FUNCTIONAL TEST of the required FHEVAS Actuation Logic division every 18 months. This will actuate the Function, operating all associated equipment. Proper operation of the equipment actuated by each division is thus verified. The Frequency of 18 months is based on plant operating experience with regard to channel OPERABILITY and drift, which demonstrates that failure of an Actuation Logic division of a given Function during any 18 month Frequency is a rare event.

A Note to the SR indicates that this Surveillance includes verification of operation for each initiation circuit.

SR 3.3.10.4

Every 18 months, a CHANNEL FUNCTIONAL TEST is performed on the required FHEVAS Manual Actuation division.

This Surveillance verifies that the actuation push buttons are capable of providing manual actuation of the fuel handling area emergency ventilation Function.

The 18 month Frequency is based on the need to perform this Surveillance under the conditions that apply during a plant outage. Operating experience has shown these components usually pass the Surveillance when performed at a Frequency of once every 18 months.

SR 3.3.10.5

CHANNEL CALIBRATION is a complete check of the instrument channel including the sensor. The Surveillance verifies that the channel responds to a measured parameter within the necessary range and accuracy.

CHANNEL CALIBRATION leaves the channel adjusted to account for instrument drift between successive calibrations to ensure that the channel remains OPERABLE between successive tests. The SCP has controls which require verification that the instrument channel functions as required by verifying the as-left and as-found settings are consistent with those established by the NRC approved setpoint methodology.
The Frequency is based upon the assumption of an 18 month calibration interval for the determination of the magnitude of equipment drift in the setpoint analyses.

This Surveillance ensures that the FHEVAS division actuation response times are less than the maximum times assumed in the accident analyses (Ref. 2). The 18 month Frequency is based upon plant operating experience, which shows that random failures of instrumentation components causing serious response time degradation, but not channel failure, are infrequent occurrences. Testing of the final actuating devices, which make up the bulk of the response time, is included in the Surveillance.

REFERENCES
1. FSAR, Chapter 9.
2. FSAR, Chapter 15.
B 3.3  INSTRUMENTATION

B 3.3.11  Accident Monitoring Instrumentation (AMI)

BASES

BACKGROUND  The primary purpose of the AMI is to display plant variables that provide information required by the main control room (MCR) operators during accident situations.

The OPERABILITY of AMI ensures that there is sufficient information available on selected plant parameters to monitor and assess plant status and behavior following an accident.

The availability of AMI is important so that responses to corrective actions can be observed, and the need for further actions can be determined. These essential instruments are identified in FSAR, Chapter 7 (Ref. 1) addressing the recommendations of Nuclear Regulatory Commission (NRC) Regulatory Guide 1.97 (Ref. 2), as required by Supplement 1 to NUREG-0737, “TMI Action Items” (Ref. 3).

The AMI instruments included in Table 3.3.11-1, Accident Monitoring Instrumentation, are required for the following reasons:

• Perform the diagnosis specified in the emergency operating procedures. These variables are restricted to preplanned actions for the primary success path of design basis accidents (DBAs) (e.g., loss of coolant accident (LOCA)).

• Provide information to indicate whether plant safety functions are being accomplished for reactivity control, core cooling, maintaining Reactor Coolant System (RCS) integrity, and maintaining containment integrity (including radioactive effluent control).

• Provide information to indicate the potential for being breached or actual breach of the barriers to fission product releases (i.e., fuel cladding, primary coolant pressure boundary, and containment).

• Provide information to indicate the performance of those safety systems and auxiliary supporting features necessary for the mitigation of design basis events and to indicate the performance of other systems necessary to achieve and maintain a safe shutdown condition and to verify safety system status.

• Provide information to indicate the magnitude of the release of radioactive materials and to assess such releases. The AMI is displayed through the Qualified Indication and Alarm System (QIAS).
The AMI ensures the OPERABILITY of NRC Regulatory Guide 1.97 variables, so that the MCR operating staff can:

- Perform the diagnosis specified in the emergency operating procedures. These variables are restricted to preplanned actions for the primary success path of DBAs.

- Take the specified, preplanned, manually controlled actions, for which no automatic control is provided, that are required for safety systems to accomplish their safety functions.

- Determine whether systems important to safety are performing their intended functions.

- Determine the potential for causing a gross breach of the barriers to radioactivity release.

- Determine if a gross breach of a barrier has occurred.

- Initiate action necessary to protect the public as well as to obtain an estimate of the magnitude of any impending threat.

AMI that performs certain functions related to verification of key safety functions and monitoring key barriers for breach must be retained in the Specification because they are intended to assist operators in minimizing the consequences of accidents. Therefore, these variables are important in reducing public risk.

The seismically Qualified Indication and Alarm System - P (QIAS-P) is dedicated to continuously monitor and display the Type A, B, and C variables. The Qualified Indication and Alarm System - Non-Safety (QIAS-N) and Information Processing System (IPS) also monitor all Type A, B, C, D, and E variables.

Two measurement channels provide the necessary information in the MCR for adequate accident monitoring. The channels provide wide-range information which meets the electrical and physical separation requirements for each parameter displayed. This design is consistent with the requirements of IEEE Std. 603-1991 (Ref. 4). The channels are provided with equipment qualified to operate in the environments specified for design basis events. These channels comply with the recommendations of NRC Regulatory Guide 1.97.
LCO

LCO 3.3.11 requires two OPERABLE measurement channels for all but one Function to ensure no single failure prevents the operators from being presented with the information necessary to determine the status of the plant and to bring the plant to, and maintain it in, a safe condition following that accident.

Furthermore, provision of two channels allows a CHANNEL CHECK during the post-accident phase to confirm the validity of displayed information.

More than two channels could be required at some plants if the NRC Regulatory Guide 1.97 analysis determined that failure of one accident monitoring channel results in information ambiguity (that is, the redundant displays disagree) that could lead operators to defeat or to fail to accomplish a required safety function.

The exception to the two channel requirement is the Containment Isolation Valve Position. In this case, the important information is the status of the containment penetrations. The LCO requires one position indicator for each active containment isolation valve. This is sufficient to redundantly verify the isolation status of each isolable penetration either via indicated status of the active valve and prior knowledge of passive valve or via system boundary status. If a normally active containment isolation valve is known to be closed and deactivated, position indication is not needed to determine status. Therefore, the position indication for valves in this state is not required to be OPERABLE.

Listed below are discussions of the specified instrument functions listed in Table 3.3.11-1. The following instruments are displayed on QIAS-P, QIAS-N, and IPS.

1. **Logarithmic Reactor Power**

   Logarithmic Reactor Power indication is provided to verify reactor shutdown.

   Inputs are provided by two safety channels with a minimum sensor and indicated range of 2E-8 to 200% power.

2, 3. **Hot Leg Temperature (wide range) and Cold Leg Temperature (wide range)**

   Hot leg and cold leg temperatures are variables provided for verification of core cooling and long term surveillance. They are also inputs to the Reactor Coolant System saturation margin monitor.
Reactor coolant outlet and inlet temperature inputs to the AMI are provided by two fast response resistance elements and associated transmitters in each loop. The channels provide indication over a minimum sensor and indicated range of 0 to 400°C (32 to 752°F).

4. Reactor Coolant System Pressure

RCS pressure is a variable, provided for verification of core cooling and RCS integrity long term surveillance. RCS loop pressure is measured by pressure transmitters with a minimum sensor and indicated range of 0 to 281.2 kg/cm²G (0 to 4,000 psig). The pressure transmitters are located inside the containment. Redundant monitoring capability is provided by two trains of instrumentation.

5. Reactor Vessel Level

Reactor vessel level is provided for verification and long term surveillance of core cooling.

The reactor vessel level monitors provide a direct measurement of the collapsed liquid level above the fuel alignment plate surface. The collapsed liquid represents the amount of liquid mass that is in the reactor vessel above the core. Measurement of the collapsed coolant level is selected because it is a direct indication of the coolant inventory. The collapsed level is obtained over the same temperature and pressure range as the saturation measurements, thereby encompassing all operating and accident conditions where it must function. Also, it functions during the recovery interval. Therefore, it is designed to survive the high steam temperature that can occur during the preceding core recovery interval.

The level range extends from the top of the vessel down to the top of the fuel alignment plate surface. The response time is short enough to track the level during a small break LOCA. The resolution is sufficient to show the initial level drop, the key locations near the hot leg elevation, and the lowest levels just above the fuel alignment plate surface. This provides the operator with adequate indication to track the progression of the accident and to detect the consequences of its mitigating actions or the functionality of automatic equipment.
Two channels with minimum sensor range of 0 ~ 673.5 cm (0 ~ 265.16 in) above the fuel alignment plate surface is provided. The minimum indicated range for these two channels is 0 to 100%.

6. Reactor Cavity Level

Reactor cavity level is provided for verification and long term surveillance of the RCS integrity and vessel integrity.

Reactor cavity level is measured by four instruments with a minimum sensor and indicated range of 0 to 100%.

7, 8. Containment Pressure (wide range, extended wide range)

Containment pressure (wide range, extended wide range) is provided for verification of RCS and containment OPERABILITY.

Two extended wide range pressure sensors with a minimum sensor and indicated range of –500 to 14,500 cmH₂O (–7.1 to 206.2 psig) and two wide range sensors with a minimum sensor and indicated range of –400 to 5,600 cmH₂O (–5.7 to 79.5 psig) are provided for display of related information.

9. Containment Isolation Valve Position

Containment isolation valve position is provided for verification of containment isolation OPERABILITY.

Containment isolation valve position indication is summarized by two status indicators. The containment isolation valves are split between the two status indicators in cases where there are two containment isolation valves for one penetration. For any particular containment penetration, one isolation valve or boundary is on one status indicator, and the other isolation valve or boundary is on the other status indicator. These status indicators will identify if any single containment isolation valve is not in its required position (closed) for isolation valves aggregated under that status indicator. Any containment isolation valve whose associated penetration is isolated by at least one closed and deactivated automatic valve, closed manual valve, blind flange, or check valve with flow through the valve secured will not cause the associated containment isolation valve status indicator to indicate that not all of the containment isolation valves are closed, if all other containment isolation valves...
10. **Containment Upper operating Area Radiation**

The Containment Upper operating Area Radiation monitor is provided to monitor for the potential of significant radiation releases and to provide release assessment for use by operators in determining the need to invoke site emergency plans. Two sensors with a minimum sensor and indicated range of 1E1 to 1E8 mSv/hr (1 to 1E7 rem/hr) provide input to the monitor.

11. **Pressurizer Level**

The Pressurizer Level is used to determine whether to terminate safety injection (SI), if still in progress, or to reinitiate SI if it has been stopped. Knowledge of pressurizer level is also used to verify the plant conditions necessary to establish natural circulation in the RCS and to verify that the plant is maintained in a safe shutdown condition.

Two pressurizer level sensors are provided. They have a minimum indicated and sensor range of 0 to 100%.

12. **Steam Generator Level (wide range)**

The Steam Generator Level (wide range) monitor is provided to monitor operation of decay heat removal via the steam generators. The measured differential pressure is displayed as 0 to 100% at the reference leg temperature of 20°C (68°F). Temperature compensation of this indication is performed automatically. Redundant monitoring capability is provided by two trains of instrumentation.

13. **Holdup Volume Tank (HVT) Level**

The HVT performs water collection and storage functions during accident conditions. Level indication is provided in the MCR to allow the operator to monitor HVT level after an accident. HVT level is measured by five instruments with a minimum sensor and indicated range of 0 to 100%.
14, 15, 16, 17. **Core Exit Temperature**

Core exit temperature is provided for verification and long term surveillance of core cooling.

An evaluation is made of the minimum number of valid core exit thermocouples necessary for inadequate core cooling detection. The evaluation determines the reduced complement of core exit thermocouples necessary to detect initial core recovery and trend the ensuing core heatup. The evaluations account for core nonuniformities including incore effects of the radial decay power distribution and excore effects of condensate runback in the hot legs and nonuniform inlet temperatures. Based on these evaluations, adequate or inadequate core cooling detection is ensured with two valid core exit thermocouples per quadrant.

The design of the Incore Instrumentation System includes a Type K (chromel alumel) thermocouple within each of the incore instrument detector assemblies. The junction of each thermocouple is located a few centimeters (inches) above the fuel assembly, inside a structure that supports and shields the incore instrument detector assembly string from flow forces in the outlet plenum region. These core exit thermocouples monitor the temperature of the reactor coolant as it exits the fuel assemblies.

The core exit thermocouples have a usable sensor and indicated temperature range from 0 to 1,260.0°C (32 to 2,300°F), although accuracy is reduced at temperatures above 982.2°C (1,800°F).

18. **Steam Generator Pressure**

The steam generator pressure monitor is provided to monitor operation of the steam generators and verification of Reactor Coolant System (RCS) heat removal. There are two sensed channels of the steam generator pressure per steam generator. The minimum sensor range of these channels is 1.1 to 105.5 kg/cm²A (15 to 1500 psia). The minimum indicated range of these channels is 0 to 105 kg/cm²A (0 to 1494 psia).
LCO (continued)

19. **RCS Saturation Margin**

RCS Saturation Margin is provided for verification and analysis of plant conditions.

There are two sensed channels of RCS Saturation Margin. RCS Saturation Margin is calculated from:

a. Wide Range Pressurizer Pressure (minimum sensor range of 0 to 210.9 kg/cm² (0 to 3,000 psi)), and

b. Reactor Coolant Hot Leg and Cold Leg Temperatures (minimum sensor range of 0 to 400°C (32 to 752°F)).

RCS Temperature Saturation Margin indicated range is from 358.3°C (677°F) subcooled (below saturation temperature) to 399°C (750°F) superheated (above saturation temperature).

RCS Pressure Saturation Margin indicated range is from 210.9 kg/cm² (3,000 psi) subcooled (above saturation pressure) to 225.5 kg/cm² (3,208 psi) superheated (below saturation pressure).

20. **CET Saturation Margin**

CET Saturation Margin is provided for verification and analysis of plant conditions.

There are two sensed channels of CET Saturation Margin. CET Saturation Margin is calculated from:

a. Wide Range Pressurizer Pressure (minimum sensor range of 0 to 210.9 kg/cm² (0 to 3,000 psi)), and

b. Core Exit Temperatures (minimum sensor range of 0 to 1,260.0°C (32 to 2,300°F)).

CET Temperature Saturation Margin indicated range is from 368.3°C (695°F) subcooled (below saturation temperature) to 1,260.0°C (2,300°F) superheated (above saturation temperature).
21. RV Upper Head Saturation Margin

RV Upper Head Saturation Margin is provided for verification and analysis of plant conditions.

There are two sensed channels of RV Upper Head Saturation Margin. RV Upper Head Saturation Margin is calculated from:

a. Wide Range Pressurizer Pressure (minimum sensor range of 0 to 210.9 kg/cm² (0 to 3,000 psi)), and

b. RV Upper Head Temperature (minimum sensor range of 0 to 1,260.0°C (32 to 2,300°F)).

RV Upper Head Temperature Saturation Margin indicated range is from 368.3°C (695°F) subcooled (below saturation temperature) to 1,260.0°C (2,300°F) superheated (above saturation temperature).

RV Upper Head Pressure Saturation Margin indicated range is from 210.9 kg/cm² (3,000 psi) subcooled (above saturation pressure) to 225.5 kg/cm² (3,208 psi) superheated (below saturation pressure).

22. Pressurizer Pressure (wide range)

Pressurizer Pressure (wide range) is measured by pressure transmitters with a minimum sensor and indicated range of 0 to 210.9 kg/cm²A (0 to 3,000 psia).

23. In-containment Refueling Water Storage Tank (IRWST) Level

The IRWST Level monitor is provided to sure water supply for emergency core cooling and containment spray. The IRWST consists of one torus-type tank inside containment. There are four 0 to 100% sensors and indicated range level channels.
24. **IRWST Temperature**

IRWST temperature is provided for verification of long term decay heat removal operation. There are four 10 to 176.7°C (50 to 350°F) sensors with an indicated range temperature channels.

25. **Containment Water Level**

The containment water level monitor is provided for verification and long term surveillance of emergency core cooling and the containment water level is measured by two instruments with a minimum sensor and indicated range of 0 to 100%.

26. **Containment Operating Area Radiation**

A containment operating area radiation monitor is provided to monitor the potential of significant radiation releases from an event occurring in the containment (e.g., fuel handling accident) and to provide a release assessment for use by operators in determining the need to invoke the site emergency plans. In addition, this area monitoring initiates containment purge isolation actuation signal (CPIAS) to prevent radioactive release through Containment Purge System.

Two containment operating radiation monitors are available and two sensors with a minimum sensor indicated range of 1E−3 mSv/hr to 1E2 mSv/hr (1E−4 rem/hr to 1E1 rem/hr) provide input.

27. **Spent Fuel Pool Radiation**

The spent fuel pool radiation monitor is provided to monitor the potential of significant radiation releases from the event occurring in the fuel handling area (e.g., fuel handling accident) and to provide release assessment for use by operators in determining the need to invoke site emergency plans. In addition, this area monitor initiates fuel handling area emergency ventilation actuation signal (FHEVAS) to stop the Fuel Handling Area Normal Ventilation System and to activate the Fuel Handling Area Emergency ventilation System. Two spent fuel pool radiation monitors are available and two sensors with a minimum sensor indicated range of 1E−3 mSv/hr to 1E2 mSv/hr (1E−4 rem/hr to 1E1 rem/hr) provide input.
28. **SIP DVI Flow Rate**

The SIP DVI Flow Rate monitor is provided to verify that safety systems are performing their safety functions for control of RCS inventory during an accident and the SIP DVI Flow Rate is measured with a minimum sensor and indicated range of 0 to 5,678 L/min (0 to 1,500 gpm).

29. **MSADV Position**

MSADV position is provided to monitor the actuation of MSADV for each main steam line. MSADV is to allow cooldown of the reactor coolant system (RC) through a controlled discharge of steam to the atmosphere when the MSIVs are closed or when the main condenser is not available as a heat sink.

30. **Auxiliary Feedwater Flow**

The Auxiliary Feedwater Flow is provided to verify the flow of Auxiliary Feedwater supplied to corresponding steam generator. The Auxiliary Feedwater System delivers the minimum required flow of 2,461 L/min (650 gpm) to the affected steam generator within 60 seconds following an AFAS. The maximum rate of auxiliary feedwater flow delivered to the steam generator at 87.2 kg/cm²A (1,240 psia) or less is equal to or less than 3,600 L/min (950 gpm). The flowrate indicated range is from 0 to 3,600 L/min (0 to 950 gpm).

31. **Hydrogen Concentration**

Hydrogen concentration is a variable to support containment combustible gas control during the accident. Two channel hydrogen concentration sensors are provided with a minimum sensor indication range of 0 to 15% by volume.

32. **Containment Atmosphere Temperature**

Containment atmosphere temperature is a variable to support containment temperature control during the accident. Containment atmosphere temperatures are provided with a minimum sensor indication range of 4.4 to 204.4°C (40 to 400°F).
33. **4.16 kV Switchgear Voltage**

The Class 1E 4.16 kV switchgear bus voltage is provided to verify adequate electric power which is available for ESF loads. For each bus, one voltage input is provided with a range of 0 to 5,250 Vac.

34. **DC Bus Voltage**

The 125 Vdc bus voltage of the Class 1E DC power system is provided to verify adequate electric power which is available for monitoring and control of the safety functions. For each bus, one voltage input is provided with a range of 0 to 150 Vdc.

35. **Instrument Power Bus Voltage**

The 120 Vac bus voltage of the Class 1E instrumentation and control power system is provided to verify adequate electric power which is available for monitoring and control of the safety functions. For each bus, one voltage input is provided with a range of 0 to 150 Vac.

Two channels are required to be OPERABLE for all but one Function. Two OPERABLE channels ensure that no single failure within the AMI or its auxiliary supporting features or power sources, concurrent with failures that are a condition of or result from a specific accident, prevents the operators from being presented the information necessary for them to determine the safety status of the plant and to bring the plant to and maintain it in a safe condition following that accident.

Table 3.3.11-1 delineates that the exception to the two channel requirement is the containment isolation valve position.

Two OPERABLE channels of core exit thermocouples are required for each channel in each quadrant to provide indication of radial distribution of the coolant temperature rise across representative regions of the core. Power distribution symmetry is considered in determining the specific number and locations provided for diagnosis of local core problems. Therefore, two randomly selected thermocouples may not be sufficient to meet the two thermocouples per channel requirement in any quadrant. The two thermocouples in each channel must meet the additional requirement that one be located near the center of the core and the other near the core perimeter, such that the pair of core exit thermocouples indicates the radial temperature gradient across their core quadrant. Two sets of two thermocouples in each quadrant ensure a single failure will not disable the ability to determine the radial temperature gradient.
For loop and steam generator related variables, the required information is individual loop temperature and individual steam generator level. In these cases two channels are required to be OPERABLE for each loop or steam generator to redundantly provide the necessary information.

In the case of containment isolation valve position, the important information is the status of the containment penetrations. The LCO requires one position indicator for each active containment isolation valve. This is sufficient to redundantly verify the isolation status of each isolable penetration either via indicated status of the active valve and prior knowledge of the passive valve or via system boundary status. If a normally active containment isolation valve is known to be closed and deactivated, position indication is not needed to determine status. Therefore, the position indication for valves in this state is not required to be OPERABLE.

The AMI LCO is applicable in MODES 1, 2, and 3. These variables are related to the diagnosis and preplanned actions required to mitigate DBAs. The applicable DBAs are assumed to occur in MODES 1, 2, and 3. In MODES 4, 5, and 6, plant conditions are such that the likelihood of an event occurring that would require AMI is low; therefore, the AMI is not required to be OPERABLE in these MODES.

Note 1 has been added in the ACTIONS to exclude the MODE change restriction of LCO 3.0.4. This exception allows entry into the applicable MODE while relying on the ACTIONS, even though the ACTIONS may eventually require plant shutdown. This exception is acceptable due to the passive function of the instruments, the operator's ability to monitor an accident using alternate instruments and methods, and the low probability of an event requiring these instruments.

Note 2 has been added in the ACTIONS to clarify the application of Completion Time rules. The Condition of this Specification may be entered independently for each Function listed in Table 3.3.11-1. The Completion Time(s) of the inoperable channel(s) of a Function will be tracked separately for each Function starting from the time the Condition was entered for that Function.
Bases

Actions (continued)

A.1

When one or more Functions have one required measurement channel that is inoperable, the required inoperable channel must be restored to OPERABLE status within 31 days. The 31 day Completion Time is based on operating experience and takes into account the remaining OPERABLE measurement channel (or in the case of a Function that has only one required measurement channel, other non NRC Regulatory Guide 1.97 instrument measurement channels to monitor the Function), the passive nature of the instrument (no critical automatic action is assumed to occur from these instruments), and the low probability of an event requiring AMI during this interval.

B.1

This Required Action specifies initiation of actions in accordance with Specification 5.6.5, which requires a written report to be submitted to the NRC. This report discusses the results of the root cause evaluation of the inoperability and identifies proposed restorative Required Actions. This Required Action is appropriate in lieu of a shutdown requirement, given the likelihood of plant conditions that would require information provided by this instrumentation. Also, alternative Required Actions are identified before a loss of functional capability condition occurs.

C.1

When one or more Functions have two required measurement channels inoperable (i.e., two measurement channels inoperable in the same Function), one measurement channel in the Function should be restored to OPERABLE status within 7 days. The Completion Time of 7 days is based on the relatively low probability of an event requiring AMI operation and the availability of alternate means to obtain the required information. Continuous operation with two required channels inoperable in a Function is not acceptable because the alternate indications may not fully meet all performance qualification requirements applied to the AMI.

Therefore, requiring restoration of one inoperable channel of the Function limits the risk that the AMI Function will be in a degraded condition should an accident occur.
BASES

ACTIONS (continued)

D.1

This Required Action directs entry into the appropriate Condition referenced in Table 3.3.11-1. The applicable Condition referenced in the table is Function dependent. Each time Required Action C.1 is not met and the associated Completion Time has expired, Condition D is entered for that channel and provides for transfer to the appropriate subsequent Condition.

E.1 and E.2

If the Required Action and associated Completion Time of Condition D is not met and Table 3.3.11-1 directs entry into Condition E, the plant must be brought to a MODE in which the LCO does not apply. To achieve this status, the plant must be brought to at least MODE 3 within 6 hours and to MODE 4 within 12 hours. The allowed Completion Times are reasonable, based on operating experience, to reach the required plant conditions from full power conditions in an orderly manner and without challenging plant systems.

F.1

Alternate means of monitoring Reactor Vessel Level and Containment Upper Operating Area Radiation have been developed and tested. These alternate means may be temporarily installed if the normal accident monitoring channel cannot be restored to OPERABLE status within the allotted time. If these alternate means are used, the Required Action is not to shut down the plant, but rather to follow the directions of Specification 5.6.5. The report provided to the NRC should discuss the alternate means used, describe the degree to which the alternate means are equivalent to the installed accident monitoring channels, justify the areas in which they are not equivalent, and provide a schedule for restoring the normal accident monitoring channels.

A Note in the beginning of the SR table specifies that the following SRs apply to each AMI Function found in Table 3.3.11-1.

SR 3.3.11.1

Performance of the CHANNEL CHECK for each required instrument channel that is normally energized once every 31 days ensures that a gross failure of instrumentation has not occurred. A CHANNEL CHECK is a comparison of the parameter indicated on one channel to a similar parameter on other channels.
It is based on the assumption that instrument channels monitoring the same parameter should read approximately the same value. Significant deviations between the two instrument channels could be an indication of excessive instrument drift in one of the channels. A CHANNEL CHECK will detect gross channel failure. Thus, it is key to verifying the instrumentation continues to operate properly between each CHANNEL CALIBRATION.

Agreement criteria are determined by the plant staff based on a combination of the channel instrument uncertainties, including indication and readability. If a channel is outside the match criteria, it could be an indication that the sensor or the signal processing equipment has drifted outside its limit.

If the channels are within the match criteria, it is an indication that the channels are OPERABLE. If the channels are normally off scale during times when surveillance is required, the measurement CHANNEL CHECK will only verify that they are off scale in the same direction. Off scale low current loop channels are verified to be reading at the bottom of the range and not failed downscale.

The Frequency of 31 days is based upon plant operating experience with regard to channel OPERABILITY and drift, which demonstrates that failure of more than one channel of a given Function in any 31 day interval is a rare event. The measurement CHANNEL CHECK supplements less formal, but more frequent, checks of channel OPERABILITY during normal operational use of the displays associated with this LCO's required channels.

SR 3.3.11.2

A CHANNEL CALIBRATION is performed every 18 months. CHANNEL CALIBRATION is a complete check of the instrument channel including the sensor. The Surveillance verifies the channel responds to the measured parameter with the necessary range and accuracy.

For the Containment Upper Operating Area Radiation instrumentation, a CHANNEL CALIBRATION may consist of an electronic calibration of the channel, not including the detector, for range decades above 100 mSv/hr (10 rem/hr) and one point calibration check of the detector below 100 mSv/hr (10 rem/hr) with a gamma source.
The Frequency is based upon operating experience and consistency with the typical industry refueling cycle and is justified by the assumption of an 18 month calibration interval for the determination of the magnitude of equipment drift.

REFERENCES
1. FSAR, Chapter 7.
3. NUREG-0737, Supplement 1, January 1983.
B 3.3 INSTRUMENTATION

B 3.3.12 Remote Shutdown Display and Control

BASES

BACKGROUND

The remote shutdown display and control provides the main control room (MCR) operator with sufficient instrumentation and controls to place and maintain the unit in a safe shutdown condition from a location other than the MCR. This capability is necessary to protect against the possibility that the MCR becomes inaccessible. A safe shutdown condition is defined as MODE 3. With the unit in MODE 3, the Auxiliary Feedwater System (AFWS) and the steam generator safety valves or the steam generator atmospheric dump valves can be used to remove core decay heat and meet all safety requirements. The long term supply of water for the AFWS and the ability to borate the Reactor Coolant System (RCS) from outside the MCR allow extended operation in MODE 3.

In the event that the MCR becomes inaccessible, the operators can establish control at the remote shutdown console and place and maintain the unit in MODE 3. Not all controls and necessary transfer switches are located at the remote shutdown console. Some controls and transfer switches will be operated locally at the switchgear, motor control panels, or other local stations. The unit automatically reaches MODE 3 following a unit shutdown and can be maintained safely in MODE 3 for an extended period of time.

The OPERABILITY of the remote shutdown console Functions ensures that there is sufficient information available on selected plant parameters to bring the plant to, and maintain it in, MODE 3 should the MCR become inaccessible.

APPLICABLE SAFETY ANALYSES

The remote shutdown display and control is required to provide equipment at appropriate locations outside the MCR with a capability to promptly shut down the plant and maintain it in a safe condition in MODE 3.

The criteria governing the design and the specific system requirements of the remote shutdown display and control are located in 10 CFR Part 50, Appendix A, GDC 19 (Ref. 1) and Appendix R (Ref. 2).

The remote shutdown display and control satisfies Criterion 4 of 10 CFR 50.36(c)(2)(ii).
The remote shutdown display and control LCO provides the requirements for the OPERABILITY of the instrumentation and controls necessary to place and maintain the plant in MODE 3 from a location other than the MCR. The instrumentation and controls required are listed in Table 3.3.12-1.

The controls, instrumentation, and transfer switches are those required for:

a. Reactivity control (initial and long term);

b. RCS pressure control;

c. Decay heat removal;

d. RCS inventory control; and

e. Safety support systems for the above functions, as well as station service water, component cooling water, and onsite power.

A Function of a remote shutdown display and control is OPERABLE if all instrument and control channels needed to support the remote shutdown Functions are OPERABLE. In some cases, Table 3.3.12-1 could indicate that the required information or control capability is available from several alternate sources. In these cases, the Remote Shutdown Console is OPERABLE as long as one channel of any of the alternate information or control sources for each Function is OPERABLE.

The remote shutdown display and control covered by this LCO do not need to be energized to be considered OPERABLE. This LCO is intended to ensure that the instrument and control circuits will be OPERABLE if plant conditions require that the Remote Shutdown Console be placed in operation.

The remote shutdown display and control LCO is applicable in MODES 1, 2, and 3. This is required so that the unit can be placed and maintained in MODE 3 for an extended period of time from a location other than the MCR.

This LCO is not applicable in MODE 4, 5, or 6. In these MODES, the unit is already subcritical and in the condition of reduced RCS energy. Under these conditions, considerable time is available to restore necessary instrument control functions if MCR instruments or control become unavailable.
Bases

Actions
A Remote Shutdown Console division is inoperable when each function is not accomplished by at least one designated Remote Shutdown Console channel that satisfies the OPERABILITY criteria for the channel’s function. These criteria are outlined in the LCO section of the Bases.

A Note has been added in the ACTIONS to clarify the application of Completion Time rules. The Conditions of this Specification may be entered independently for each Function listed in Table 3.3.12-1. The Completion Time(s) of the inoperable channel(s)/division(s) of a Function will be tracked separately for each Function starting from the time the Condition was entered for that Function.

A.1
Condition A addresses the situation where one or more channels of the Remote Shutdown Console are inoperable. This includes the control and transfer switches for any required Function.

The Required Action is to restore the division to OPERABLE status within 31 days. The Completion Time is based on operating experience, and the low probability of an event that would require evacuation of the MCR.

B.1 and B.2
If the Required Action and associated Completion Time of Condition A are not met, the plant must be brought to a MODE in which the LCO does not apply. To achieve this status, the plant must be brought to at least MODE 3 within 6 hours and to MODE 4 within 12 hours. The allowed Completion Times are reasonable, based on operating experience, to reach the required MODE from full power conditions in an orderly manner and without challenging plant systems.

Surveillance Requirements
SR 3.3.12.1
Performance of the CHANNEL CHECK once every 31 days ensures that a gross failure of instrumentation has not occurred. A CHANNEL CHECK is normally a comparison of the parameter indicated on one channel to a similar parameter on other channels. It is based on the assumption that instrument channels monitoring the same parameter should read approximately the same value. Significant deviations between the instrument channels could be an indication of excessive instrument drift in one of the channels or of something even more serious. A CHANNEL CHECK will detect gross channel failure; thus, it is key to verifying that the instrumentation continues to operate properly between each CHANNEL CALIBRATION. Agreement criteria are determined by the plant staff, based on a combination of the channel instrument
uncertainties, including indication and readability. If a channel is outside the criteria, it could be an indication that the sensor or the signal processing equipment has drifted outside its limit. As specified in the Surveillance, a CHANNEL CHECK is only required for those channels that are normally energized.

The Frequency is based on plant operating experience that demonstrates channel failure is rare.

**SR 3.3.12.2**

SR 3.3.12.2 verifies that each required Remote Shutdown Console transfer switch and control circuit performs its intended function. This verification is performed from the remote shutdown console and locally, as appropriate. Operation of the equipment from the remote shutdown Console is not necessary. The Surveillance can be satisfied by performance of a continuity check. This will ensure that if the MCR becomes inaccessible, the plant can be brought to and maintained in MODE 3 from the reactor shutdown panel and the local control stations. The 18 month Frequency is based on the need to perform this Surveillance under the conditions that apply during a plant outage and the potential for an unplanned transient if the Surveillance were performed with the reactor at power. Operating experience demonstrates that Remote Shutdown Console control channels seldom fail to pass the Surveillance when performed at a Frequency of once every 18 months.

**SR 3.3.12.3**

CHANNEL CALIBRATION is a complete check of the instrument channel including the sensor. The Surveillance verifies that the channel responds to the measured parameter within the necessary range and accuracy. Whenever a sensing element is replaced, the next required CHANNEL CALIBRATION of the resistance temperature detectors (RTD) sensors is accomplished by an in-place cross calibration that compares the other sensing elements with the recently installed sensing element.

The 18 month Frequency is based on the need to perform this Surveillance under the conditions that apply during a plant outage and the potential for an unplanned transient if the Surveillance were performed with the reactor at power.
SR 3.3.12.4

SR 3.3.12.4 is the performance of a CHANNEL FUNCTIONAL TEST every 18 months. This Surveillance should verify the OPERABILITY of the reactor trip circuit breaker (RTCB) open/closed indication on the remote shutdown panels by actuating the RTCBs. A successful test of the required contact(s) of a channel relay may be performed by the verification of the change of state of a single contact of the relay. This clarifies what is an acceptable CHANNEL FUNCTIONAL TEST of a relay. This is acceptable because all of the other required contacts of the relay are verified by other Technical Specifications and non-Technical Specifications tests at least once per refueling interval with applicable extensions.

The Frequency of 18 months was chosen because the RTCBs cannot be exercised while the unit is at power. Operating experience has shown that these components usually pass the Surveillance when performed at a Frequency of once every 18 months. Therefore, the Frequency was concluded to be acceptable from a reliability standpoint.

REFERENCES

1. 10 CFR Part 50, Appendix A, GDC 19.
2. 10 CFR Part 50, Appendix R.
B 3.3 INSTRUMENTATION

B 3.3.13 Logarithmic Power Monitoring Channels

BASES

BACKGROUND
The logarithmic power monitoring channels provide neutron flux power indication from $< 1E^{-7}\%$ RTP to $> 100\%$ RTP. They also provide reactor protection when the reactor trip circuit breakers (RTCBs) are shut, in the form of a Logarithmic Power Level – High trip.

This LCO addresses MODES 3, 4, and 5 with the RTCBs open. When the RTCBs are shut, the logarithmic power monitoring channels are addressed by LCO 3.3.2, “Reactor Protection System (RPS) Instrumentation – Shutdown.”

When the RTCBs are open, two of the four logarithmic power monitoring channels must be available to monitor neutron flux power. In this application, the RPS channels need not be OPERABLE since the reactor trip Function is not required. By monitoring neutron flux (logarithmic) power when the RTCBs are open, loss of SDM caused by boron dilution can be detected as an increase in flux. Alarms are also provided when power increases above the fixed bistable setpoints. Two channels must be OPERABLE to provide single failure protection and to facilitate detection of channel failure by providing CHANNEL CHECK capability.

APPLICABLE SAFETY ANALYSES
The logarithmic power monitoring channels are necessary to monitor core reactivity changes. They are one of the primary means for detecting and triggering operator actions to respond to reactivity transients initiated from conditions in which the RPS is not required to be OPERABLE. The logarithmic power monitoring channels also trigger operator actions to anticipate RPS actuation in the event of reactivity transients starting from shutdown or low power conditions. The logarithmic power monitoring channel’s LCO requirements support compliance with Reference 1. Reference 2 describes the specific logarithmic power monitoring channel features that are critical to comply with the GDC.

The OPERABILITY of logarithmic power monitoring channels is necessary to meet the assumption of the safety analyses and to provide for the mitigation of accident and transient conditions.

The logarithmic power monitoring channels satisfy Criterion 3 of 10 CFR 50.36(c)(2)(ii).
The LCO on the logarithmic power monitoring channels ensures that adequate information is available to verify core reactivity conditions while shut down.

A minimum of two logarithmic power monitoring channels are required to be OPERABLE.

In MODES 3, 4, and 5, with RTCBs open or the Control Element Assembly (CEA) Drive System not capable of CEA withdrawal, logarithmic power monitoring channels must be OPERABLE to monitor core power for reactivity changes. In MODES 1 and 2, and in MODES 3, 4, and 5, with the RTCBs shut and the CEAs capable of withdrawal, the logarithmic power monitoring channels are addressed as part of the RPS in LCO 3.3.1, “Reactor Protection System Instrumentation – Operating,” and LCO 3.3.2, “Reactor Protection System Instrumentation – Shutdown.”

The requirements for startup channels of the ENFMS in MODE 6 are addressed in LCO 3.9.2, "Nuclear Instrumentation." Startup channels of the ENFMS provide neutron flux coverage extending an additional one to two decades below the logarithmic channels for use during refueling, when neutron flux could be extremely low.

A channel is inoperable when it does not satisfy the OPERABILITY criteria for the channel's function. These criteria are outlined in the LCO section of the Bases.

A.1 and A.2

With one required channel inoperable, it may not be possible to perform a CHANNEL CHECK to verify that the other required channel is OPERABLE. Therefore, with one or more required channels inoperable, the logarithmic power monitoring Function cannot be reliably performed. Consequently, the Required Actions are the same for one required channel inoperable or more than one required channel inoperable. The absence of reliable neutron flux indication makes it difficult to ensure SDM is maintained. Required Action A.1 is modified by a Note to indicate that normal plant control operations that individually add limited positive reactivity (e.g., temperature or boron fluctuations associated with Reactor Coolant System (RCS) inventory management or temperature control) are not precluded by this Action, provided they are accounted for in the calculated SDM.
BASES (continued)

SDM must be verified periodically to ensure that it is being maintained. Both required channels must be restored as soon as possible. The initial Completion Time of 4 hours and once every 12 hours thereafter to perform SDM verification takes into consideration that Required Action A.1 eliminates many of the means by which SDM can be reduced. These Completion Times are based on operating experience in performing the Required Actions and the fact that plant conditions will change slowly.

SURVEILLANCE REQUIREMENTS

SR 3.3.13.1

SR 3.3.13.1 is the performance of a CHANNEL CHECK on each required channel every 12 hours. A CHANNEL CHECK is a comparison of the parameter indicated on one channel to a similar parameter on other channels. It is based upon the assumption that instrument channels monitoring the same parameter should read approximately the same value. Significant deviations between instrument channels could be an indication of excessive instrument drift in one of the channels or of something even more serious. CHANNEL CHECK will detect gross channel failure, thus it is the key to verifying that the instrumentation continues to operate properly between each CHANNEL CALIBRATION.

Agreement criteria are determined by the plant staff and should be based on a combination of the channel instrument uncertainties including indication, and readability. If a channel is outside of the criteria, it could be an indication that the preamplifier or the signal processing equipment has drifted outside of its limits. If the channels are within the criteria, it is an indication that the channels are OPERABLE.

The Frequency, about once every shift, is based on operating experience that demonstrates the rarity of channel failure. Since the probability of two random failures in redundant channels in any 12 hour period is extremely low, CHANNEL CHECK minimizes the chance of loss of protection function due to failure of redundant channels. CHANNEL CHECK supplements check of channel OPERABILITY during normal operational use of displays associated with the LCO required channels.

SR 3.3.13.2

A CHANNEL FUNCTIONAL TEST is performed every 31 days to ensure that the entire channel is capable of properly indicating neutron flux. Internal test circuitry is used to feed pre-adjusted test signals into the
preamplifier to verify channel alignment. It is not necessary to test the detector, because generating a meaningful test signal is difficult; the detectors are of simple construction, and any failures in the detectors will be apparent as change in channel output. The 31 day Frequency is the same as that employed for the same channels in the other applicable MODES.

The Setpoint Control Program (SCP) has controls which require verification that the instrument channel functions as required by verifying the as-left and as-found settings are consistent with those established by the setpoint methodology.

SR 3.3.13.3

SR 3.3.13.3 is the performance of a CHANNEL CALIBRATION. A CHANNEL CALIBRATION is performed every 18 months. The Surveillance is a complete check and readjustment of the logarithmic power channel from the preamplifier input through to a remote display. The Surveillance verifies that the channel responds to a measured parameter within the necessary range and accuracy. CHANNEL CALIBRATION leaves the channel adjusted to account for instrument drift between successive calibrations to ensure that the channel remains operational between successive surveillance. The SCP has controls which require verification that the instrument channel functions as required by verifying the as-left and as-found settings are consistent with those established by the setpoint methodology.

This SR is modified by a Note to indicate that it is not necessary to test the detector, because generating a meaningful test signal is difficult. The detectors are of simple construction and any failures in the detectors will be apparent as change in channel output. This test Frequency is the same as that employed for the same channels in the other applicable MODES.

REFERENCES

2. FSAR, Sections 7.1, 7.2, 7.5, 7.8, and 15.4.
B 3.3 INSTRUMENTATION

B 3.3.14 Boron Dilution Alarms

BASES

BACKGROUND

The Boron Dilution Alarm System (BDAS) alerts the operator of a boron dilution event in MODES 3, 4 and 5. The boron dilution alarm is received at least 30 minutes prior to criticality in MODES 3, 4, and 5 to allow the operator to terminate the boron dilution.

In MODES 1 and 2, protection for a boron dilution event is presented in LCO 3.3.1, “Reactor Protection System (RPS) Instrumentation – Operating.” In MODES 3 and 4 with the control element assemblies (CEAs) withdrawn, LCO 3.3.2, “Reactor Protection System (RPS) Instrumentation – Shutdown,” provides protection. In MODE 6, protection for a boron dilution event is presented in LCO 3.9.2, “Nuclear Instrumentation.”

The BDAS uses two startup channels of the Ex-core Neutron Flux Monitoring System (ENFMS) that monitor the neutron flux. If the neutron flux signals increase to the calculated alarm setpoint a main control room (MCR) annunciation is received. The setpoint is automatically lowered to a fixed amount above the current flux level signal. The alarm setpoint will only follow decreasing or constant flux levels, not increasing levels. Two channels of BDAS must be OPERABLE to provide single failure protection and to facilitate detection of channel failure by providing CHANNEL CHECK capability.

APPLICABLE SAFETY ANALYSES

The BDAS channels are necessary to monitor core reactivity changes. They are the primary means for detecting and triggering operator ACTIONS to respond to boron dilution events initiated from conditions in which the RPS is not required to be OPERABLE.

The OPERABILITY of BDAS channels is necessary to meet the assumptions of the safety analyses to mitigate the consequences of an inadvertent boron dilution event as described in the APR1400 FSAR, Chapter 15 (Ref. 1).

The BDAS channels satisfy Criterion 3 of 10 CFR 50.36(c)(2)(ii).
The LCO on the BDAS channels ensures that adequate information is available to mitigate the consequences of a boron dilution event.

At least two BDAS channels are required to be OPERABLE. Because the BDAS uses the startup channels of the ENFMS as its detection system, the OPERABILITY of the startup channels of the ENFMS is also part of the OPERABILITY of the BDAS.

The BDAS must be OPERABLE in MODES 3, 4, and 5 because the safety analysis assumes this alarm will be available in these MODES to alert the operator to take action to terminate the boron dilution. In MODES 1 and 2 and in MODES 3, 4 and 5, with the reactor trip circuit breakers (RTCBs) shut and the CEAs capable of withdrawal, the logarithmic power monitoring channels are addressed as part of the RPS in LCO 3.3.1, “Reactor Protection System (RPS) Instrumentation – Operating,” and LCO 3.3.2, “Reactor Protection System (RPS) Instrumentation – Shutdown.”

The requirements for startup channels of the ENFMS in MODE 6 are addressed in LCO 3.9.2, “Nuclear Instrumentation.” The startup channels of the ENFMS provide neutron flux coverage extending an additional one to two decades below the logarithmic channels for use during shutdown and refueling when neutron flux could be extremely low.

The Applicability specifies that BDAS is required in MODE 3 within 1 hour after the neutron flux is within the startup range following a reactor shutdown. This allows the neutron flux level to decay to a level within the range of the startup channels of the ENFMS and for the operator to initialize the BDAS.

A channel is inoperable when it does not satisfy the OPERABILITY criteria for the channel's function. These criteria are outlined in the LCO section of the Bases.

Turn off charging pump immediately to prohibit a possible excessive positive reactivity addition if LCO 3.3.14 is not met. But, an auxiliary charging pump, which supplies a restricted charging flow, may be turned on if necessary.
With one required channel inoperable, Required Action A.1 requires the Reactor Coolant System (RCS) boron concentration to be determined immediately and at the applicable monitoring Frequency specified in the COLR. The RCS boron concentration may be determined by the boronometer reading or by RCS sampling. The RCS sample should be from the hot leg if one or more reactor coolant pumps (RCPs) are running or from the discharge of the operating pump providing shutdown cooling flow with no RCPs running. The monitoring Frequency specified in the COLR ensures that a decrease in the boron concentration during a boron dilution event will be detected. The boron concentration measurement and the OPERABLE BDAS channel provide alternate methods of detection of boron dilution with sufficient time for termination of the event before the reactor achieves criticality.

According to Required Action A.2, the SDM is ensured, under the operator administrative control, by suspending all operations involving positive reactivity addition like the boron concentration or reactor coolant temperature change.

With two required channels inoperable Required Action B.1 requires the RCS boron concentration to be determined by redundant methods immediately and at the monitoring Frequency specified in the COLR. The redundant methods may use the boronometer and RCS sampling or independent collection and analysis of two RCS samples. The RCS sample should be from the hot leg if one or more RCPs are running or from the discharge of the operating pump providing shutdown cooling flow with no RCPs running. The simultaneous use of the boronometer and RCS sampling or independent collection and analysis of two RCS samples to monitor the RCS boron concentration provides alternate indications of inadvertent boron dilution. This will allow detection with sufficient time for termination of boron dilution before the reactor achieves criticality.

According to Required Action B.2, the SDM is ensured, under the operator administrative control, by suspending all operations involving positive reactivity addition like the boron concentration or reactor coolant temperature change.
SR 3.3.14.1 is the performance of a CHANNEL CHECK on each required channel every 12 hours. A CHANNEL CHECK is normally a comparison of the parameter indicated on one channel to the same parameter on other channels. It is based upon the assumption that instrument channels monitoring the same parameter should read approximately the same value. Significant deviations between instrument channels could be an indication of excessive instrument drift in one of the channels or of something even more serious.

CHANNEL CHECK will detect gross channel failure. Thus, it is a key to verifying that the instrumentation continues to operate properly between each CHANNEL CALIBRATION.

Agreement criteria are determined by the plant staff and should be based on a combination of the channel instrument uncertainties. If a channel is outside of the criteria, it could be an indication that the transmitter or the signal processing equipment has drifted outside of its limits. If the channels are within the criteria, it is an indication that the channels are OPERABLE.

The Frequency, about once every shift, is based on operating experience that demonstrates the rarity of channel failure. Since the probability of two random failures in redundant channels in any 12 hour period is extremely low, CHANNEL CHECK minimizes the chance of a loss of a protective alarm function due to a failure of redundant channels. CHANNEL CHECK supplements less formal, but more frequent, checks of channel OPERABILITY during normal operational use of displays associated with the LCO required channels.

This SR is modified by a Note that states the CHANNEL CHECK is not required to be performed until 1 hour after neutron flux is within the startup range.

SR 3.3.14.2

A CHANNEL FUNCTIONAL TEST is performed every 31 days of cumulative operation during shutdown to ensure that the BDAS is capable of properly alerting the operator to a boron dilution event.

Internal startup channel of the ENFMS test circuitry is used to feed pre-adjusted test signals into the startup channel of the ENFMS to verify the proper neutron flux indication is received at the BDAS.
Bases

Surveillance Requirements (continued)

This SR is modified by a Note to indicate that it is not necessary to test the detector, because generating a meaningful test signal is difficult; the detectors are of simple construction, and any failures in the detectors will be apparent as a change in channel output.

A CHANNEL FUNCTIONAL TEST of the BDAS consists of online tests including verification of the alarm in the MCR.

SR 3.3.14.3

SR 3.3.14.3 is the performance of a CHANNEL CALIBRATION. A CHANNEL CALIBRATION is performed every 18 months. The Surveillance is a complete check and adjustment of the startup channel of the ENFMS from the neutron flux detector input through to the BDAS alarm in the MCR. The Surveillance verifies that the channel responds to a measured parameter within the necessary range and accuracy. CHANNEL CALIBRATION leaves the channel adjusted to account for instrument drift between successive calibrations to ensure that the channel remains OPERABLE. This SR is an extension of the SR 3.9.2.2 for the startup channel of the ENFMS nuclear instrumentation CHANNEL CALIBRATION listed here because of its Applicability in MODES 3, 4 and 5.

This SR is modified by a Note to indicate that it is not necessary to test the detector, because generating a meaningful test signal is difficult; the detectors are of simple construction, and any failures in the detectors will be apparent as a change in channel output.

References

1. FSAR, Chapter 15.
B 3.4 REACTOR COOLANT SYSTEM (RCS)

B 3.4.1 RCS Pressure, Temperature, and Flow Limits

BASES

BACKGROUND

These Bases address requirements for maintaining Reactor Coolant System (RCS) pressure, temperature, and flow rate within limits assumed in the safety analyses. The safety analyses (Ref. 1) for normal operating conditions and anticipated operational occurrences (AOOs) assume initial conditions within the normal steady state envelope. The limits placed on departure from nucleate boiling (DNB) related parameters ensure that these parameters will not be less conservative than were assumed in the safety analyses and thereby provide assurance that the minimum departure from nucleate boiling ratio (DNBR) will meet the required criteria for each of the transients analyzed.

The LCO limits for the minimum and maximum pressurizer (PZR) pressures are consistent with operation within the nominal operating envelope and are bounded by those used as the initial pressures in the safety analyses.

The LCO limits for minimum and maximum RCS cold leg temperatures are consistent with operation at the indicated power level and are bounded by those used as the initial temperatures in the safety analyses.

The LCO limit for minimum RCS flow rate is bounded by the thermal design flow rate which is the minimum flow rate in the thermal analysis. The RCS flow rate is not expected to vary during plant operation with all pumps running.

APPLICABLE SAFETY ANALYSES

The requirements of LCO 3.4.1 represent the initial conditions for DNB limited transients analyzed in the safety analyses (Ref. 1).

The safety analyses have shown that transients initiated from the limits of this LCO will meet the DNBR criterion of $\geq 1.29$. This is the acceptance limit for the RCS DNB parameters. Changes to the facility that could impact these parameters must be assessed for their impact on the DNBR criterion. The transients analyzed include loss of coolant flow events and dropped or stuck control element assembly (CEA) events.
BASES

APPLICABLE SAFETY ANALYSES (continued)

A key assumption for the analysis of these events is that the core power distribution is within the limits of LCO 3.1.6, "Regulating Control Element Assembly (CEA) Insertion Limits," LCO 3.1.7, "Part Strength Control Element Assembly (CEA) Insertion Limits," LCO 3.2.3, “AZIMUTHAL POWER TILT (T₀),” and LCO 3.2.5, “AXIAL SHAPE INDEX (ASI).” The safety analyses are performed over the following range of initial values:

RCS pressure 151.9 to 162.4 kg/cm²G (2,160 to 2,310 psig), core inlet temperature \( \geq 285°C (545°F) \) and \( \leq 295°C (563°F) \) for \(< 90\% \) of RTP, or \( \geq 287.8°C (550°F) \) and \( \leq 295°C (563°F) \) for \( \geq 90\% \) of RTP, and reactor vessel inlet coolant flow rate 95 to 116%.

The RCS DNB limits satisfy Criterion 2 of 10 CFR 50.36(c)(2)(ii).

LCO

This LCO specifies limits on the monitored process variables: pressurizer pressure, RCS cold leg temperature, and RCS total flow rate to ensure that the core operates within the limits assumed for the plant safety analyses. Operating within these limits will result in meeting the DNBR criterion in the event of a DNB limited transient.

The LCO values for pressurizer pressure and RCS cold leg temperature account for instrument error. The LCO value for RCS flow rate does not account for instrument error. Plant specific limits of instrument error for RCS flow rate are established by the plant staff to meet the requirements of this LCO.

APPLICABILITY

In MODE 1 for RCS flow rate, MODES 1 and 2 for RCS pressurizer pressure, MODE 1 for RCS cold leg temperature, and MODE 2 with \( k_{\text{eff}} \geq 1.0 \) for RCS cold leg temperature, the limits must be maintained during steady state operation in order to ensure that DNBR criteria will be met in the event of an unplanned loss of forced coolant flow or other DNB limited transient. In all other MODES, the power level is low enough so that DNBR is not a concern.

A Note has been added to indicate the limit on pressurizer pressure may be exceeded during short term operational transients such as a THERMAL POWER ramp increase of > 5% RTP per minute or a THERMAL POWER step increase of > 10% RTP. These conditions represent short term perturbations where actions to control pressure variations might be counterproductive. Also, since they represent transients initiated from power levels < 100% RTP, an increased DNBR margin exists to offset the temporary pressure variations.
Another set of limits on DNB related parameters is provided in Safety Limit (SL) 2.1.1, "Reactor Core Safety Limits." Those limits are less restrictive than the limits of this LCO, but violation of SLs merits a stricter, more severe Required Action. Should a violation of this LCO occur, the operator should check whether or not an SL could have been exceeded.

RCS total flow rate is not a controllable parameter and is not expected to vary during steady state operation. If the flow rate is not within the LCO limit, action must be taken to restore DNB margin.

The 2 hour Completion Time for restoration of RCS flow rate provides sufficient time to determine the cause of the off normal condition and to restore the readings within limits. The Completion Time is based on plant operating experience.

If Required Action A.1 is not met within the associated Completion Time, the plant must be brought to a MODE in which the LCO does not apply. To achieve this status, the plant must be brought to MODE 2 within 6 hours. In MODE 2, the reduced power condition eliminates the potential for violation of the accident analysis bounds.

The 6 hours is a reasonable time that permits the plant power to be reduced at an orderly rate in conjunction with even control of steam generator heat removal.

Pressurizer pressure and RCS cold leg temperature are controllable and measurable parameters. If these parameters are not within the LCO limits, action must be taken to restore the parameters.

The 2 hour Completion Time is based on plant operating experience that shows that the parameters can be restored in this time period.

If Required Action C.1 is not met within the associated Completion Time, the plant must be brought to MODE 3. In MODE 3, the potential for violation of the DNB limits is greatly reduced.
The 6 hour Completion Time is a reasonable time that permits the plant power to be reduced at an orderly rate in conjunction with even control of steam generator heat removal.

**SURVEILLANCE REQUIREMENTS**

**SR 3.4.1.1**

This SR ensures that pressurizer pressure is within limit. The 12 hour Frequency has been shown by operating practice to be sufficient to regularly assess degradation and verify operation within safety analysis assumptions.

**SR 3.4.1.2**

This SR ensures that RCS cold leg temperature is within limit. The 12 hour Frequency has been shown by operating practice to be sufficient to regularly assess for potential degradation and to verify operation is within safety analysis assumptions.

Since the measurement uncertainty for RCS cold leg temperature of the Data Processing System is lower than that of the RCS cold leg temperature indicator, whether or not a violation of the LCO has occurred shall be verified using the RCS cold leg temperature of the Data Processing System, if the RCS cold leg temperature indication appears to be outside of the LCO limits.

**SR 3.4.1.3**

This SR for RCS total flow rate is performed using the installed flow instrumentation. The 12 hour Frequency has been shown by operating experience to be sufficient to assess potential degradation and to verify operation is within thermal analysis assumptions.

The measurement uncertainty shall be incorporated into the measured RCS flow rate for performing this Surveillance.

**SR 3.4.1.4**

The RCS total flow rate is measured by performance of a precision calorimetric heat balance once every 18 months. This allows the installed RCS flow instrumentation to be calibrated and verifies that the actual RCS flow rate is within the bounds of the analyses.
BASES

SURVEILLANCE REQUIREMENTS (continued)

The Frequency of 18 months reflects the importance of verifying flow after a refueling outage where the core has been altered, which may have caused an alteration of flow resistance.

The measurement uncertainty shall be incorporated into measured RCS total flow rate for performing this Surveillance.

The SR is modified by a Note which states the SR is only required to be performed 24 hours after \( \geq 95\% \) RTP. The Note is necessary to allow measurement of the flow rate at normal operating conditions at power in MODE 1. The Surveillance cannot be performed in MODE 2 or below and will not yield accurate results if performed below 95\% RTP.

REFERENCES

1. FSAR, Chapter 15.
B 3.4  REACTOR COOLANT SYSTEM (RCS)

B 3.4.2  RCS Minimum Temperature for Criticality

BASES

BACKGROUND  Establishing the value for the minimum temperature for reactor criticality is based upon considerations for:

a. Operation within the existing instrumentation ranges and accuracies;

b. Operation within the bounds of the existing accident analyses; and

c. Operation with the reactor vessel above its minimum nil ductility reference temperature when the reactor is critical.

The moderator temperature coefficient used in core operating and accident analysis is typically defined for the normal operating temperature range 285 to 295°C (545 to 563°F). Safety and operating analyses for temperatures which are out of this temperature range have not been performed.

APPLICABLE SAFETY ANALYSES  There are no accident analyses which dictate the minimum temperature for criticality, but all low power safety analyses (Ref. 1) assume initial temperatures near the 286.7°C (548°F) limit. This minimum cold leg temperature limit is the sum of the safety analysis initial condition of 285°C (545°F) and an uncertainty of 1.7°C (3°F).

The RCS minimum temperature for criticality satisfies Criterion 2 of 10 CFR 50.36(c)(2)(ii).

LCO  The purpose of the LCO is to prevent criticality below the minimum normal operating temperature and to prevent operation in an unanalyzed regime.

The LCO is only applicable when any RCS loop's $T_{\text{cold}}$ is below 289.4°C (553°F) which provides a reasonable distance to the lower limit of 286.7°C (548°F). This allows adequate time to trend the approach of $T_{\text{cold}}$ towards the lower limit and take corrective actions prior to going below it.
BASES

APPLICABILITY The reactor has been designed and analyzed to be critical in MODES 1 and 2 only and in accordance with this specification. Criticality is not permitted in any other MODE. Therefore, this LCO is applicable in MODES 1 and 2 when $k_{\text{eff}} \geq 1.0$. Monitoring for RCS temperature is required at or below a $T_{\text{cold}}$ of 289.4°C (553°F). The no-load temperature of 291.3°C (556.3°F) is maintained by the Steam Bypass System.

ACTIONS A.1

If $T_{\text{cold}}$ is below 286.7°C (548°F), the plant must be brought to a MODE in which the LCO does not apply. To achieve this status, the plant must be brought to MODE 3 within 30 minutes. Rapid reactor shutdown can be readily and practically achieved within a 30 minute period. The allowed time reflects the ability to perform this action and maintain the plant within the analyzed range.

SURVEILLANCE REQUIREMENTS SR 3.4.2.1

The first Frequency requires verifying that $T_{\text{cold}}$ is $\geq$ 286.7°C (548°F) within 15 minutes prior to achieving criticality. The 15 minute time period allows the operator to adjust RCS cold leg temperatures or delay criticality to avoid violating the LCO. The second Frequency requires performing this Surveillance every 30 minutes whenever the reactor is critical and $T_{\text{cold}}$ is $< 289.4$°C (553°F). The once per 30 minute Frequency is often enough to prevent inadvertent violation of the LCO. The third Frequency requires performing this Surveillance every 12 hours and takes into account indications and alarms that are continuously available to the operator in the control room and is consistent with other routine Surveillances that are typically performed once per shift. In addition, operators are trained to be sensitive to RCS temperature during approach to criticality and will ensure that the minimum temperature for criticality is met as criticality is approached.

Since the measurement uncertainty for RCS cold leg temperature of the Data Processing System is lower than the measurement uncertainty of the indicator, whether or not there is a violation of the LCO shall be verified by using the RCS cold leg temperature indication of the Data Processing System, if the RCS cold leg temperature is approaching the LCO limit.

REFERENCES 1. FSAR, Chapter 15.
B 3.4 REACTOR COOLANT SYSTEM (RCS)

B 3.4.3 RCS Pressure and Temperature (P/T) Limits

BASES

BACKGROUND

All components of the RCS are designed to withstand effects of cyclic loads due to system pressure and temperature changes. These loads are introduced by startup (heatup) and shutdown (cooldown) operations, power transients, and reactor trips. This LCO limits the pressure and temperature changes during RCS heatup and cooldown, within the design assumptions and the stress limits for cyclic operation.

The PTLR contains P/T limit curves for heatup, cooldown, and inservice leak and hydrostatic (ISLH) testing, and data for the maximum rate of change of reactor coolant temperature (Ref. 1).

Each P/T limit curve defines an acceptable region for normal operation. The usual use of the curves is operational guidance during heatup or cooldown maneuvering, when pressure and temperature indications are monitored and compared to the curves to determine that operation is within the allowable region.

The LCO establishes operating limits that provide a margin to brittle failure of the reactor vessel and piping of the reactor coolant pressure boundary (RCPB). The reactor vessel is the component most subject to brittle failure, and the LCO limits apply mainly to the reactor vessel. The limits do not apply to the pressurizer, which has different design characteristics and operating functions.

10 CFR Part 50, Appendix G (Ref. 2), requires the establishment of P/T limits for material fracture toughness requirements of the RCPB materials. Reference 2 requires an adequate margin to brittle failure during normal operation, anticipated operational occurrences, and system hydrostatic tests. It mandates the use of the American Society of Mechanical Engineers (ASME) Code, Section XI, Appendix G (Ref. 3).

The actual shift in the reference temperature for nil-ductility transition (RTNDT) of the reactor vessel material will be established periodically by removing and evaluating the irradiated reactor vessel material specimens, in accordance with ASTM E 185 (Ref. 4) and Appendix H of 10 CFR Part 50 (Ref. 5). The operating P/T limit curves will be adjusted, as necessary, based on the evaluation findings and the recommendations of Reference 3.
The P/T limit curves are composite curves established by superimposing limits derived from stress analyses of those portions of the reactor vessel and head that are the most restrictive. At any specific pressure, temperature, and temperature rate of change, one location within the reactor vessel will dictate the most restrictive limit. Across the span of the P/T limit curves, different locations are more restrictive, and, thus, the curves are composites of the most restrictive regions.

The heatup curve represents a different set of restrictions than the cooldown curve because the directions of the thermal gradients through the reactor vessel wall are reversed. The thermal gradient reversal alters the location of the tensile stress from the outer to inner walls.

The criticality limit includes the Reference 2 requirement that the limit be no less than 22°C (40°F) above the heatup curve or the cooldown curve and not less than the minimum permissible temperature for the ISLH testing. However, the criticality limit is not operationally limiting; a more restrictive limit exists in LCO 3.4.2, “RCS Minimum Temperature for Criticality.”

The consequence of violating the LCO limits is that the RCS has been operated under conditions that can result in brittle failure of the RCPB, possibly leading to a non-isolable leak or loss-of-coolant accident. In the event these limits are exceeded, an evaluation must be performed to determine the effect on the structural integrity of the RCPB components. The ASME Code, Section XI, Appendix E (Ref. 6), provides a recommended methodology for evaluating an operating event that causes an excursion outside the limits.

The P/T limits are not derived from design basis event (DBE). They are prescribed during normal operation to avoid encountering pressure, temperature, and temperature rate of change conditions that may cause undetected flaws to propagate and cause non-ductile failure of the RCPB, an unanalyzed condition. Since the P/T limits are not derived from any DBE, there are no acceptance limits related to the P/T curves. Rather, the P/T curves are acceptance limits themselves since they preclude operation in an unanalyzed condition.

The RCS P/T limits satisfy Criterion 2 of 10 CFR 50.36(c)(2)(ii).
Bases

LCO

The two elements of this LCO are:

a. The limit curves for heatup, cooldown, and ISLH testing and

b. Limits on the rate-of-change of temperature.

The LCO limits apply to all components of the RCS, except the pressurizer. These limits define allowable operating regions and permit a large number of operating cycles while providing a wide margin to non-ductile failure.

The limits for rate-of-change of temperature control the thermal gradient through the walls and are used as input for calculating the heatup, cooldown, and ISLH testing P/T limit curves. Thus, the LCO for the rate-of-change of temperature restricts stresses caused by thermal gradients and also ensures the validity of the P/T limit curves.

Violation of the LCO limits places the reactor vessel outside of the bounds of the stress analysis and can increase stresses in other RCPB components. The consequences depend on several factors, as follows:

a. The severity of the departure from the operating P/T regime or the severity of the rate-of-change of temperature;

b. The length of time that the limits were violated (longer violations allow the temperature gradient in the thick walls of the vessel to become more pronounced); and

c. The existences, sizes, and orientations of flaws in the vessel material.

Applicability

The RCS P/T limits provide a definition of acceptable operation for prevention of non-ductile failure that is in accordance with 10 CFR Part 50, Appendix G (Ref. 2). Although the P/T limits were developed to provide guidance for operation during heatup or cooldown (MODES 3, 4, and 5) or ISLH testing, their Applicability is at all times in keeping with the concern for non-ductile failure. “At all times” is defined to be any condition with fuel in the reactor vessel. The limits do not apply to the pressurizer.

During MODES 1 and 2, other Technical Specifications (TS) provide limits for operation that can be more restrictive than or can supplement these P/T limits. LCO 3.4.1, “RCS Pressure, Temperature, and Flow Limits,” LCO 3.4.2, “RCS Minimum Temperature for Criticality,” and Safety Limit (SL) 2.1, “Safety Limits” also provide operational restrictions for pressure and temperature and maximum pressure.
BASES

APPLICABILITY (continued)

Furthermore, MODES 1 and 2 are above the temperature range of concern for non-ductile failure, and stress analyses have been performed for normal maneuvering profiles, such as power ascension or descent.

The actions of this LCO consider the premise that a violation of the limits occurred during normal plant maneuvering. A violation of P/T limits caused by abnormal transients, which could be accompanied by equipment failures, may also require additional ACTIONS based on emergency operating procedures.

Since the RCS cannot be pressurized with the reactor vessel closure head detensioned, the limits of pressure, temperature, and rate of heatup and cooldown do not apply.

ACTIONS

A.1 and A.2

Operation outside the P/T limits must be corrected so that the RCPB is returned to a condition that has been verified by stress analysis.

The Completion Time of 30 minutes reflects the urgency of restoring the parameters to within the analyzed range. Most violations will not be severe and the activity can be accomplished in this time in a controlled manner.

Besides restoring operation to within limits, an evaluation is required to determine if RCS operation can continue. The evaluation must verify the RCPB integrity remains acceptable and must be completed before continuing operation. Several methods may be used, including comparison with pre-analyzed transients in the stress analysis, new analyses, or inspection of the components.

ASME Code, Section XI, Appendix E (Ref. 6) may be used to support the evaluation. However, its use is restricted to evaluation of the vessel beltline.

The 72 hour Completion Time is a reasonable time to accomplish the evaluation. The evaluation for a mild violation is possible within this time, but more severe violations may require special, event specific stress analyses or inspections. A favorable evaluation must be completed before continuing to operate.
Bases

Actions (continued)

Condition A is modified by a Note requiring Required Action A.2 to be completed whenever the Condition is entered. The Note emphasizes the need to perform the evaluation of the effects of the excursion outside the allowable limits. Restoration alone per Required Action A.1 is insufficient because higher than analyzed stresses could have occurred and could have affected the RCPB integrity.

B.1 and B.2

If a Required Action and associated Completion Time of Condition A are not met, the plant must be placed in a lower MODE because:

a. The RCS remained in an unacceptable P/T region for an extended period of increased stress; or

b. A sufficiently severe event caused entry into an unacceptable region.

Either possibility indicates a need for more careful examination of the event, which is best accomplished with the RCS at reduced pressure and temperature state. With reduced pressure and temperature conditions, the possibility of propagation of undetected flaws is decreased.

Pressure and temperature are reduced by placing the plant in MODE 3 within 6 hours and in MODE 5 with RCS pressure \(< 33.7 \text{ kg/cm}^2 \) \((479 \text{ psia})\) within 36 hours.

The Completion Times are reasonable, based on operating experience, to reach the required plant conditions from full power conditions in an orderly manner and without challenging plant systems.

C.1 and C.2

The actions of this LCO, anytime other than in MODE 1, 2, 3, or 4, consider the premise that a violation of the limits occurred during normal plant maneuvering. Severe violations caused by abnormal transients, at times accompanied by equipment failures, may also require additional ACTIONS from emergency operating procedures. Operation outside the P/T limits must be corrected so that the RCPB is returned to a condition that has been verified by stress analyses.

The Completion Time of "immediately" reflects the urgency of restoring the parameters to within the analyzed range. Most violations will not be severe, and the activity can be accomplished in a short period of time in a controlled manner.
Besides restoring operation to within limits, an evaluation is required to determine if RCS operation can continue. The evaluation must verify that the RCPB integrity remains acceptable and must be completed before continuing operation. Several methods may be used, including comparison with pre-analyzed transients in the stress analyses, new analyses, or inspection of the components.

ASME Code, Section XI, Appendix E (Ref. 6), may be used to support the evaluation. However, its use is restricted to evaluation of the reactor vessel beltline.

The Completion Time of prior to entering MODE 4 forces the evaluation prior to entering a MODE where temperature and pressure can be significantly increased. The evaluation for a mild violation is possible within several days, but more severe violations may require special, event specific stress analyses or inspections.

Condition C is modified by a Note requiring Required Action C.2 to be completed whenever the Condition is entered. The Note emphasizes the need to perform the evaluation of the effects of the excursion outside the allowable limits. Restoration alone per Required Action C.1 is insufficient because higher than analyzed stresses could have occurred and could have affected the RCPB integrity.

Verification that operation is within the PTLR limits is required every 30 minutes when RCS temperature and pressure conditions are undergoing planned changes. This Frequency is considered reasonable in view of the main control room (MCR) indication available to monitor RCS status. Also, since temperature rate-of-change limits are specified in hourly increments, 30 minute periods permit assessment and correction for minor deviations within a reasonable time.

Surveillance for heatup, cooldown, or ISLH testing may be discontinued when definitions given in the plant procedures for ending the activity is satisfied.

The SR is modified by a Note which states that this SR be performed only during RCS system heatup, cooldown, and ISLH testing. There are no SRs during critical operation because LCO 3.4.2 contains a more restrictive requirement.
# BASES

## REFERENCES


2. 10 CFR Part 50, Appendix G.

3. ASME Section XI, Appendix G.


5. 10 CFR Part 50, Appendix H.

6. ASME Section XI, Appendix E.
B 3.4 REACTOR COOLANT SYSTEM (RCS)

B 3.4.4 RCS Loops – MODES 1 and 2

BASES

BACKGROUND

The primary function of the RCS is removal of the heat generated in the fuel due to the fission process and transfer of this heat, via the steam generators (SGs), to the secondary plant.

The secondary functions of the RCS include:

a. Moderating the neutron energy level to the thermal state, to increase the probability of fission;

b. Improving the neutron economy by acting as a reflector;

c. Carrying the soluble neutron poison, boric acid;

d. Providing a second barrier against fission product release to the environment; and

e. Removing the heat generated in the fuel due to fission product decay following a unit shutdown.

The RCS configuration for heat transport uses two RCS loops. Each RCS loop contains a SG and two reactor coolant pumps (RCPs). An RCP is located in each of the two SG cold legs. The pump flow rate has been sized to provide core heat removal with appropriate margin to departure from nucleate boiling (DNB) during power operation and for anticipated transients originating from power operation (Ref. 1). This Specification requires two RCS loops with both RCPs in operation in each loop. The intent of the Specification is to require core heat removal with forced flow during power operation. Specifying two RCS loops provides the minimum necessary paths (two SGs) for heat removal.

APPLICABLE SAFETY ANALYSES

Safety analyses contain various assumptions for the design bases event (DBE) initial conditions including RCS pressure, RCS temperature, reactor power level, core parameters, and safety system setpoints. The important aspect for this LCO is the reactor coolant forced flow rate, which is represented by the number of RCS loops in service.
Both transient and steady state analyses have been performed to establish the effect of flow on DNB. The transient or accident analysis for the plant has been performed assuming four RCPs are in operation. The majority of the plant safety analyses are based on initial conditions at high core power or zero power. The accident analyses that are of most importance to RCP operation are the four pump coastdown, single pump locked rotor, and single pump broken shaft or coastdown, and rod withdrawal events (Ref. 1).

For four pump operation, the transient state DNB analysis, which generates the pressure and temperature and Safety Limit (i.e., the departure from nucleate boiling ratio (DNBR) limit), had been performed for a maximum THERMAL POWER level. The accident analysis setpoint of the nuclear overpower (high flux) trip is based on an analysis assumption that bounds possible instrumentation errors. The DNBR limit is established statistically combining the system design values with the critical heat flux correlation limit.

RCS Loops – MODES 1 and 2 satisfy Criteria 2 and 3 of 10 CFR 50.36(c)(2)(ii).

The purpose of this LCO is to require adequate forced flow for core heat removal. Flow is represented by having both RCS loops with both RCPs in each loop in operation for removal of heat by the two steam generators. To meet safety analysis acceptance criteria for DNB, four pumps are required in MODES 1 and 2.

Each OPERABLE loop consists of two RCPs providing forced flow for heat transport to a steam generator which is OPERABLE in accordance with the Steam Generator Program. Steam generator, and hence RCS loop, OPERABILITY with regard to SG water level is ensured by the Reactor Protection System (RPS) in MODES 1 and 2. A reactor trip places the plant in MODE 3 if any SG level is ≤ 45.0% wide range as sensed by the RPS. The minimum water level to declare the SG OPERABLE is 25% WR.

In MODES 1 and 2, the reactor is critical and thus has the potential to produce maximum THERMAL POWER. Thus, to ensure that the assumptions of the accident analyses remain valid, all RCS loops are required to be OPERABLE and in operation in these MODES to prevent DNB and core damage.
The decay heat production rate is much lower than the full power heat rate. As such, the forced circulation flow and heat sink requirements are reduced for lower, noncritical MODES as indicated by the LCOs for MODES 3, 4, 5, and 6.

Operation in other MODES is covered by:

- LCO 3.4.5, “RCS Loops – MODE 3”;
- LCO 3.4.6, “RCS Loops – MODE 4”;
- LCO 3.4.7, “RCS Loops – MODE 5 (Loops Filled)”;
- LCO 3.4.8, “RCS Loops – MODE 5 (Loops Not Filled)”;
- LCO 3.9.4, “Shutdown Cooling System (SCS) and Coolant Circulation – High Water Level”; and
- LCO 3.9.5, “Shutdown Cooling System (SCS) and Coolant Circulation – Low Water Level.”

If the requirements of the LCO are not met, the Required Action is to reduce power and bring the plant to MODE 3. This lowers power level and thus reduces the core heat removal needs and minimizes the possibility of violating DNB limits. It should be noted that the reactor will trip and place the plant in MODE 3 as soon as the RPS senses less than four RCPs operating.

The Completion Time of 6 hours is reasonable, based on operating experience, to reach MODE 3 from full power conditions in an orderly manner and without challenging safety systems.
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<td>This SR requires verification every 12 hours of the required number of RCS loops in operation. Verification includes flow rate, temperature or pump status monitoring, which help to ensure that forced flow is providing heat removal while maintaining the margin to DNB. The Frequency of 12 hours has been shown by operating practice to be sufficient to regularly assess degradation and verify operation within safety analysis assumptions. In addition, main control room indication and alarm will normally indicate loop status.</td>
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REFERENCES

1. FSAR, Chapter 15.
B 3.4 REACTOR COOLANT SYSTEM (RCS)

B 3.4.5 RCS Loops – MODE 3

BASES

BACKGROUND
The primary function of the reactor coolant in MODE 3 is removal of decay heat and transfer of this heat, via the steam generators (SGs), to the secondary plant fluid. The secondary function of the reactor coolant is to act as a carrier for soluble neutron poison, boric acid.

In MODE 3, reactor coolant pumps (RCPs) are used to provide forced circulation heat removal during heatup and cooldown. The MODE 3 decay heat removal requirements are low enough that a single RCS loop with one RCP running is sufficient to remove core decay heat. However, two RCS loops are required to be OPERABLE to satisfy single failure criteria. Only one RCP need be OPERABLE to declare the associated RCS loop OPERABLE.

Reactor coolant natural circulation is not normally used, but is sufficient for core cooling. However, natural circulation does not provide turbulent flow conditions. Therefore, boron reduction in natural circulation is prohibited because mixing to obtain a homogeneous concentration in all portions of the RCS cannot be ensured.

APPLICABLE SAFETY ANALYSES
Analyses have shown that the rod withdrawal event from MODE 3 with one RCS loop in operation is bounded by the rod withdrawal initiated from MODE 2.

Failure to provide heat removal can result in challenges to a fission product barrier. The RCS loops are part of the primary success path which functions or actuates to prevent or mitigate a design basis event (DBE) or transient that either assumes the failure of, or presents a challenge to, the integrity of a fission product barrier.

RCS loops – MODE 3 satisfy Criterion 3 of 10 CFR 50.36(c)(2)(ii).

LCO
The purpose of this LCO is to require two RCS loops to be available for heat removal, thus providing redundancy. The LCO requires the two RCS loops to be OPERABLE with the intent of requiring both SGs to be capable (≥ 25% wide range water level) of transferring heat from the reactor coolant at a controlled rate. Forced reactor coolant flow is the required way to transport heat, although natural circulation flow provides adequate removal. A minimum of one running RCP meets the LCO requirement for one loop in operation.
The Note permits a limited period of operation without RCPs. All RCPs may be removed from operation for \( \leq 1 \) hour per 8 hour period. This means that natural circulation has been established. The Note prohibits boron dilution with coolant at boron concentrations less than required to assure the SDM of LCO 3.1.1 is maintained when forced flow is stopped because an even concentration distribution cannot be ensured. Core outlet temperature is to be maintained at least 5.6°C (10°F) below the saturation temperature so that no vapor bubble could form and possibly cause a natural circulation flow obstruction.

In MODES 3, 4, and 5, it is sometimes necessary to stop all RCPs or shutdown cooling (SC) pump forced circulation (e.g., to change operation from one SC train to the other, to perform surveillance or startup testing, to perform the transition to and from SC System cooling, or to avoid operation below the RCP minimum net positive suction head (NPSH) limit). The time period is acceptable because natural circulation is adequate for heat removal, or the reactor coolant temperature can be maintained subcooled and boron stratification affecting reactivity control is not expected.

An OPERABLE RCS loop consists of at least one OPERABLE RCP and an SG that is OPERABLE in accordance with the Steam Generator Program. An RCP is OPERABLE if it is capable of being powered and is able to provide forced flow if required.

In MODE 3, the heat load is lower than at power; therefore, one RCS loop in operation is adequate for transport and heat removal. A second RCS loop is required to be OPERABLE but not in operation for redundant heat removal capability.

Operation in other MODES is covered by:

- LCO 3.4.4, “RCS Loops – MODES 1 and 2”;
- LCO 3.4.6, “RCS Loops – MODE 4”;
- LCO 3.4.7, “RCS Loops – MODE 5 (Loops Filled)”;
- LCO 3.4.8, “RCS Loops – MODE 5 (Loops Not Filled)”;
- LCO 3.9.4, “Shutdown Cooling System (SCS) and Coolant Circulation – High Water Level”; and
APPLICABILITY (continued)

LCO 3.9.5, “Shutdown Cooling System (SCS) and Coolant Circulation – Low Water Level.”

ACTIONS

A.1

If one RCS loop is inoperable, redundancy for forced flow heat removal is lost. The Required Action is restoration of the required RCS loop to OPERABLE status within a Completion Time of 72 hours. This time allowance is a justified period to be without the redundant, non-operating loop because a single loop in operation has a heat transfer capability much greater than that needed to remove the decay heat produced in the reactor core.

B.1

If restoration for Required Action A.1 is not possible within 72 hours, the unit must be placed in MODE 4 within 12 hours. In MODE 4 the plant may be placed on the Shutdown Cooling System. The Completion Time of 12 hours is compatible with required operation to achieve cooldown and depressurization from the existing plant condition in an orderly manner and without challenging plant systems.

C.1 and C.2

If no RCS loop is OPERABLE or in operation, except as provided by the Note in the LCO section, all operations involving reduction of the RCS boron concentration below that required to meet the minimum SDM of LCO 3.1.1 must be immediately suspended. This is necessary because boron dilution requires forced circulation for proper homogenization. Suspending the introduction of coolant into the RCS with boron concentration less than required to meet the minimum SDM of LCO 3.1.1 is required to assure continued safe operation. With coolant added without forced circulation, unmixed coolant could be introduced to the core, however coolant added with boron concentration meeting the minimum SDM maintains acceptable margin to ensure subcritical operation.

Action to restore one RCS loop to OPERABLE status and operation shall be immediately initiated and continued until one RCS loop is restored to OPERABLE status and operation. The immediate Completion Times reflect the importance of maintaining operation for decay heat removal.
BASES

SURVEILLANCE REQUIREMENTS

SR 3.4.5.1

This SR requires verification every 12 hours that the required number of RCS loops are in operation. Verification includes flow rate, temperature, and pump status monitoring, which help ensure that forced flow is providing heat removal. The 12 hour Frequency has been shown by operating practice to be sufficient to regularly assess degradation and verify operation within safety analysis assumptions. In addition, main control room (MCR) indication and alarm will normally indicate loop status.

SR 3.4.5.2

This SR requires verification every 12 hours that the secondary side water level in each SG is ≥ 25% wide range. An adequate SG water level is required in order to have a heat sink for removal of the core decay heat from the reactor coolant. The 12 hour Frequency has been shown by operating practice to be sufficient to regularly assess degradation and verify operation within the safety analysis assumptions.

SR 3.4.5.3

Verification that the required number of RCPs are OPERABLE ensures that the single failure criterion is met and that an additional RCS loop can be placed in operation, if needed, to maintain decay heat removal and reactor coolant circulation. Verification is performed by verifying proper breaker alignment and power availability to the required RCPs. The 7 day Frequency is considered reasonable in view of other administrative controls available and has been shown to be acceptable by operating experience.

This SR is modified by a Note that states the SR is not required to be performed until 24 hours after a required pump is not in operation.

REFERENCES

None.
B 3.4  REACTOR COOLANT SYSTEM (RCS)

B 3.4.6  RCS Loops – MODE 4

BASES

BACKGROUND
In MODE 4, the primary function of the reactor coolant is the removal of decay heat and transfer of this heat to the steam generators (SGs) or shutdown cooling (SC) heat exchangers. The secondary function of the reactor coolant is to act as a carrier for soluble neutron poison, boric acid.

In MODE 4, either reactor coolant pumps (RCPs) or SC trains can be used for coolant circulation. The intent of this LCO is to provide forced flow from at least one RCP or one SC train for decay heat removal and transport. The flow provided by one RCP or SC train is adequate for heat removal. The other intent of this LCO is to require that two paths be available to provide redundancy for heat removal.

APPLICABLE SAFETY ANALYSES
In MODE 4, RCS circulation is considered in the determination of the time available for mitigation of the accidental boron dilution. The RCS loops and SC trains provide this circulation.

RCS Loops – MODE 4 satisfies Criterion 4 of 10 CFR 50.36(c)(2)(ii).

LCO
The purpose of this LCO is to require that at least two RCS loops or SC trains shall be OPERABLE in MODE 4 and one of these loops or trains be in operation. The LCO allows the two loops that are required to be OPERABLE to consist of any combination of RCS loops and SC trains. Any one loop or train in operation provides enough flow to remove the decay heat from the core with forced circulation. An additional loop or train is required to be OPERABLE to provide redundancy for heat removal.

Note 1 permits all RCPs and SC pumps to be removed from operation for \( \leq 1 \text{ hour per 8 hour period} \). This means that natural circulation has been established using the steam generators. The Note prohibits boron dilution with coolant at boron concentrations below that required to assure the SDM of LCO 3.1.1 is maintained when forced flow is stopped because an even concentration distribution cannot be ensured.
Core outlet temperature is to be maintained at least 5.6°C (10°F) below saturation temperature so that no vapor bubble can form and possibly cause a natural circulation flow obstruction. The response of the RCS without the RCPs or SC pumps depends on the core decay heat load and the length of time that the pumps are stopped. As decay heat diminishes, the effects on RCS temperature and pressure diminish. Without cooling by forced flow, higher heat loads will cause the reactor coolant temperature and pressure to increase at a rate proportional to the decay heat load. Because pressure can increase, the applicable system pressure limits (pressure and temperature (P/T) limits or low temperature overpressure protection (LTOP) limits) must be observed and forced SC flow or heat removal via the SGs must be re-established prior to reaching the pressure limit. The circumstances for stopping both RCPs or SC pumps are to be limited to situations where:

a. Pressure and temperature increases can be maintained well within the allowable pressure (P/T limits and LTOP) and 5.6°C (10°F) saturation margin limits or

b. An alternate heat removal path through the SGs is in operation.

Note 2 requires that before an RCP is started with any RCS cold leg temperature less than or equal to the LTOP enable temperature specified in the PTLR, secondary side water temperature in each SG is < 55.6°C (100°F) above each of the RCS cold leg temperatures.

Satisfying the above condition will preclude a large pressure surge in the RCS when the RCP is started.

An OPERABLE RCS loop consists of at least one OPERABLE RCP and an SG that is OPERABLE in accordance with the Steam Generator Program and has the minimum water level specified in SR 3.4.6.2.

Similarly, for the SC System (SCS), an OPERABLE SC train is composed of the OPERABLE SC pump capable of providing forced flow to the SC heat exchanger.

RCPs and SC pumps are OPERABLE if they are capable of being powered and are able to provide flow if required. Management of gas voids is important to SCS OPERABILITY.
APPLICABILITY

In MODE 4, this LCO applies because it is possible to remove core decay heat with either the RCS loops and SGs or the SC System. In MODE 4, RCS circulation forced by RCPs is considered in the determination of the time available for mitigation of the accidental boron dilution event. In MODE 4 with all RCPs idle, the possibility of an inadvertent boron dilution event (Ref. 1) is precluded by adherence to LCO 3.1.12, which requires that potential dilution sources be isolated.

Operation in other MODES is covered by:

LCO 3.4.4, “RCS Loops – MODES 1 and 2”;

LCO 3.4.5, “RCS Loops – MODE 3”;

LCO 3.4.7, “RCS Loops – MODE 5 (Loops Filled)”;

LCO 3.4.8, “RCS Loops – MODE 5 (Loops Not Filled)”;

LCO 3.9.4, “Shutdown Cooling System (SCS) and Coolant Circulation – High Water Level”; and

LCO 3.9.5, “Shutdown Cooling System (SCS) and Coolant Circulation – Low Water Level.”

ACTIONS

A.1

If only one required RCS loop is OPERABLE and in operation and no SC trains are OPERABLE, redundancy for heat removal is lost. The Required Action must be initiated immediately to restore a second RCS loop or SC train to OPERABLE status.

The immediate Completion Time reflects the importance of maintaining the availability of two paths for heat removal.

B.1

If only one required SC train is OPERABLE and in operation and no RCS loops are OPERABLE, redundancy for heat removal is lost. The plant must be placed in MODE 5 within the next 24 hours. Placing the plant in MODE 5 is a conservative action with regard to decay heat removal. With only one SC train OPERABLE, redundancy for decay heat removal is lost and, in the event of a loss of the remaining SC train, it would be safer to initiate that loss from MODE 5 (≤ 98.9°C (210°F)) rather than MODE 4 (98.9°C to 176.7°C (210°F to 350°F)). The Completion Time of 24 hours...
BASES

ACTIONS (continued)

is reasonable based on operating experience to reach MODE 5 from MODE 4, with only one SC train operating, in an orderly manner and without challenging plant systems.

C.1 and C.2

If no RCS loops or SC train are OPERABLE or in operation, except during conditions permitted by Note 1 in the LCO section, all operations involving reduction of RCS boron concentration must be suspended and action to restore one RCS loop or SC train to OPERABLE status and operation must be initiated. Boron dilution requires forced circulation for proper mixing, and the margin to criticality must not be reduced in this type of operation. The immediate Completion Time reflects the importance of maintaining operation for decay heat removal. The action to restore must be continued until one loop or train is restored to operation.

SURVEILLANCE

REQUIREMENTS

SR 3.4.6.1

This SR requires verification every 12 hours that one required loop or train is in operation. This ensures forced flow is providing heat removal. Verification includes flow rate, temperature, and pump status monitoring. The 12 hour Frequency has been shown by operating practice to be sufficient to regularly assess RCS loop status.

In addition, main control room (MCR) indication and alarms will normally indicate status.

SR 3.4.6.2

This SR requires verification every 12 hours of secondary side water level in the required steam generator(s) ≥ 25% wide range. An adequate SG water level is required in order to have a heat sink for removal of the core decay heat from the reactor coolant. The 12 hour Frequency has been shown by operating practice to be sufficient to regularly assess degradation and verify operation within safety analyses assumptions.

SR 3.4.6.3

Verification that the required pump is OPERABLE ensures that an additional RCS loop or SC train can be placed in operation, if needed to maintain decay heat removal and reactor coolant circulation.
Verification is performed by verifying proper breaker alignment and power available to the required pumps. The 7 day Frequency is considered reasonable in view of other administrative controls available and has been shown to be acceptable by operating experience.

This SR is modified by a Note that states the SR is not required to be performed until 24 hours after a required pump is not in operation.

SR 3.4.6.4

SCS piping and components have the potential to develop voids and pockets of entrained gases. Preventing and managing gas intrusion and accumulation is necessary for proper operation of the required SCS train(s) and may also prevent water hammer, pump cavitation, and pumping of non-condensible gas into the reactor vessel.

Selection of SCS locations susceptible to gas accumulation is based on a review of system design information, including piping and instrumentation drawings, isometric drawings, plan and elevation drawings, and calculations. The design review is supplemented by system walk downs to validate the system high points and to confirm the location and orientation of important components that can become sources of gas or could otherwise cause gas to be trapped or difficult to remove during system maintenance or restoration. Susceptible locations depend on plant and system configuration, such as stand-by versus operating conditions.

The SCS is OPERABLE when it is sufficiently filled with water. Acceptance criteria are established for the volume of accumulated gas at susceptible locations. If accumulated gas is discovered that exceeds the acceptance criteria for the susceptible location (or the volume of accumulated gas at one or more susceptible locations exceeds an acceptance criterion for gas volume at the suction or discharge of a pump), the Surveillance is not met. If it is determined by subsequent evaluation that the SCS is not rendered inoperable by the accumulated gas (i.e., the system is sufficiently filled with water), the Surveillance may be declared met. Accumulated gas should be eliminated or brought within the acceptance criteria limits.

SCS locations susceptible to gas accumulation are monitored and, if gas is found, the gas volume is compared to the acceptance criteria for the location. Susceptible locations in the same system flow path that are subject to the same gas intrusion mechanisms may be verified by monitoring a representative sub-set of susceptible locations. Monitoring
may not be practical for locations that are inaccessible due to radiological or environmental conditions, the plant configuration, or personnel safety. For these locations, alternative methods (e.g., operating parameters, remote monitoring) may be used to monitor the susceptible location. Monitoring is not required for susceptible locations where the maximum potential accumulated gas void volume has been evaluated and determined to not challenge system OPERABILITY. The accuracy of the method used for monitoring the susceptible locations and trending of the results should be sufficient to provide reasonable assurance of system OPERABILITY during the Surveillance interval.

This SR is modified by a Note that states the SR is not required to be performed until 12 hours after entering MODE 4. In a rapid shutdown, there may be insufficient time to verify all susceptible locations prior to entering MODE 4.

The 31 day Frequency takes into consideration the gradual nature of gas accumulation in the SCS piping and the procedural controls governing system operation.

REFERENCES

1. FSAR, Subsection 15.4.6.
B 3.4 REACTOR COOLANT SYSTEM (RCS)

B 3.4.7 RCS Loops – MODE 5 (Loops Filled)

BASES

BACKGROUND

In MODE 5 with the RCS loops filled, the primary function of the reactor coolant is the removal of decay heat and the transfer of this heat either to the steam generators (SGs) secondary side coolant or the component cooling water via shutdown cooling (SC) heat exchangers. While the principal means for decay heat removal is via the SC System, the SGs are specified as a backup means for redundancy. Even though the SGs cannot produce steam in this MODE, they are capable of being a heat sink due to their large contained volume of secondary side water. As long as the SG secondary side water is at a lower temperature than the reactor coolant, heat transfer will occur. The rate of heat transfer is directly proportional to the temperature difference. The secondary function of the reactor coolant is to act as a carrier for soluble neutron poison, boric acid.

In MODE 5 with RCS loops filled, the SC trains are the principal means for decay heat removal. The number of trains in operation can vary to suit the operational needs. The intent of this LCO is to provide forced flow from at least one SC train for decay heat removal and transport. The flow provided by one SC train is adequate for decay heat removal. The other intent of this LCO is to require that a second path be available to provide redundancy for decay heat removal.

The LCO provides for redundant paths of decay heat removal capability. The first path can be an SC train that must be OPERABLE and in operation. The second path can be another OPERABLE SC train, or through the SGs, having an adequate water level.

APPLICABLE SAFETY ANALYSES

In MODE 5, RCS circulation forced by RCPs is considered in the determination of the time available for mitigation of the accidental boron dilution event. In MODE 5 with all RCPs idle, the possibility of an inadvertent boron dilution event (Ref. 1) is precluded by adherence to LCO 3.1.12, which requires that potential dilution sources be isolated. The flow provided by one SC train is adequate for decay heat removal.

RCS loops – MODE 5 (loops filled) satisfies Criterion 4 of 10 CFR 50.36(c)(2)(ii).
The purpose of this LCO is to require at least one of the SC trains to be OPERABLE and in operation with an additional SC train OPERABLE or secondary side water level of each SG shall be ≥ 25% wide range. One SC train provides sufficient forced circulation to perform the safety functions of the reactor coolant under these conditions. The second SC train is normally maintained OPERABLE as a backup to the operating SC train to provide redundant paths for decay heat removal. However, if the standby SC train is not OPERABLE, a sufficient alternate method to provide redundant paths for decay heat removal is two SGs with their secondary side water levels ≥ 25% wide range. Should the operating SC train fail, the SGs could be used to remove the decay heat.

Note 1 permits all SC pumps to be de-energized ≤ 1 hour per 8 hour period. The circumstances for stopping both SC trains are to be limited to situations where pressure and temperature increases can be maintained well within the allowable pressure (pressure and temperature (P/T) limits or low temperature overpressure protection (LTOP) limits) and 5.6°C (10°F) saturation margin limits, or an alternate heat removal path through the SG(s) is in operation.

Core outlet temperature is to be maintained at least 5.6°C (10°F) below saturation temperature, so that no vapor bubble would form and possibly cause a natural circulation flow obstruction.

In this MODE, the SG(s) can be used as the backup for SC heat removal. To ensure their availability, the RCS loop flow path is to be maintained with subcooled liquid.

In MODE 5, it is sometimes necessary to stop all RCPs or SC forced circulation. This is permitted to change operation from one SC train to the other, perform surveillance or startup testing, perform the transition to and from the SC System, or to avoid operation below the RCP minimum net positive suction head limit. The time period is acceptable because natural circulation is acceptable for decay heat removal, the reactor coolant temperature can be maintained subcooled, and boron stratification affecting reactivity control is not expected.

Note 2 allows one SC train to be inoperable for a period of up to 2 hours provided that the other SC train is OPERABLE and in operation. This permits periodic surveillance tests to be performed on the inoperable train during the only time when such testing is safe and possible.

Note 3 requires that before an RCP may be started with any RCS cold leg temperature less than or equal to the LTOP enable temperature specified in the PTLR, secondary side water temperature in each SG is < 55.6°C (100°F) above each of the RCS cold leg temperatures.
Satisfying the above condition will preclude a low temperature overpressure event due to a thermal transient when the RCP is started.

Note 4 provides for an orderly transition from MODE 5 to MODE 4 during a planned heatup by permitting removal of SC trains from operation when at least one RCP is in operation. This Note provides for the transition to MODE 4 where an RCP is permitted to be in operation and replaces the RCS circulation function provided by the SC trains.

An OPERABLE SC train is composed of an OPERABLE SC pump and an OPERABLE SC heat exchanger. Management of gas voids is important to SCS OPERABILITY.

SC pumps are OPERABLE if they are capable of being powered and are able to provide flow if required. An OPERABLE SG can perform as a heat sink when it has an adequate secondary water level and is OPERABLE in accordance with the In-service Inspection Program.

Note 5 permits the alignment of a containment spray pump if a SC pump is not available or becomes inoperable. These pumps are designed to be interchangeable for operational flexibility.

In MODE 5 with RCS loops filled, this LCO requires forced circulation to remove decay heat from the core. One SC train provides sufficient circulation for this purpose.

The MODE 5 with RCS loops filled condition is when the SGs can be used for core decay heat removal. This loops filled condition can be maintained while draining the RCS, provided the reactor coolant level is maintained above 134 ft, since below this level containment atmospheric pressure can no longer completely support the column of water remaining in the SG tubes above the reactor coolant level. At reactor coolant level below 134 ft, water vapor voids begin forming in the horizontal portions of SG tubes, beginning with the highest tubes. The number of affected tubes increases as RCS level decreases until all tubes contain water vapor voids. SG tubes containing voids of water vapor, at the saturation temperature vapor pressure of the coolant in the tubes, block coolant flow and secondary heat transfer. When reactor coolant level has decreased to 119 ft 1 in (just above the high point of the hot leg), air can begin entering the hot leg through the surge line connection and displace the coolant remaining in the SG tubes. This results in the SG tubes being filled with non-condensible gases. The condition in MODE 5 with RCS water level within the top half of the hot legs is called mid-loop operation.
BASES

APPLICABILITY (continued)

Restoring the unit to the MODE 5 with RCS loops filled condition requires raising RCS level above 134 ft during a draining operation, provided no air was introduced into the SG tubes. Restoring the unit to the MODE 5 with RCS loops filled condition following mid-loop operation requires closing the pressurizer manway, filling the pressurizer, and dynamically venting non-condensible gases from the SG tubes and reactor vessel closure head using the Reactor Coolant Gas Vent (RCGV) System and the reactor coolant pumps (RCPs).

Forced circulation by the RCPs in the MODE 5 with loops not filled condition is possible when the static head of the water from pressurizer water level establishes an RCS pressure high enough to run an RCP.

Operation in other MODES is covered by:

LCO 3.4.4, “RCS Loops – MODES 1 and 2”;
LCO 3.4.5, “RCS Loops – MODE 3”;
LCO 3.4.6, “RCS Loops – MODE 4”;
LCO 3.4.8, “RCS Loops – MODE 5 (Loops Not Filled)”;
LCO 3.9.4, “Shutdown Cooling System (SCS) and Coolant Circulation – High Water Level”; and
LCO 3.9.5, “Shutdown Cooling System (SCS) and Coolant Circulation – Low Water Level.”

ACTIONS A.1, A.2, B.1 and B.2

If the required SC train is inoperable and any SGs have secondary side water levels < 25% wide range, redundancy for heat removal is lost. Action must be initiated immediately to restore a second SC train to OPERABLE status or to restore the water level in the required SGs. Either Required Action A.1 or Required Action A.1 and A.2 will restore redundant decay heat removal paths. The immediate Completion Times reflect the importance of maintaining the availability of two paths for decay heat removal.
BASES

ACTIONS (continued)

**C.1 and C.2**

If both SC trains are inoperable or no SC train is in operation, except as permitted in Note 1, all operations involving the reduction of RCS boron concentration must be suspended. Action to restore one SC train to OPERABLE status and operation must be initiated immediately. Boron dilution requires forced circulation for proper mixing and margin to criticality must not be reduced in this type of operation. The immediate Completion Times reflect the importance of maintaining operation for decay heat removal.

SURVEILLANCE REQUIREMENTS

**SR 3.4.7.1**

This SR requires verification every 12 hours that one SC train is in operation and circulating reactor coolant. The flow rate is determined by the flow rate necessary to provide sufficient decay heat removal capability and to prevent thermal and boron stratification. Verification includes flow rate, temperature, or pump status monitoring, which help ensure that forced flow is providing decay heat removal. The 12 hour Frequency has been shown by operating practice to be sufficient to regularly assess degradation and verify operation is within safety analyses assumptions. In addition, main control room (MCR) indication and alarms will normally indicate loop status.

The SC flow is established to ensure that core outlet temperature is maintained sufficiently below saturation to allow time for swap over to the standby SC train should the operating train be lost.

**SR 3.4.7.2**

Verifying the SGs are OPERABLE by ensuring their secondary side water levels are ≥ 25% wide range ensures that redundant heat removal paths are available if the second SC train is inoperable.

The Surveillance is required to be performed when the LCO requirement is being met by use of the SGs. If both SC trains are OPERABLE, this SR is not needed. The 12 hour Frequency has been shown by operating practice to be sufficient to regularly assess degradation and verify operation within safety analyses assumptions.
SURVEILLANCE REQUIREMENTS (continued)

SR 3.4.7.3

Verification that the second SC train is OPERABLE ensures that redundant paths for decay heat removal are available. The requirement also ensures that the additional train can be placed in operation, if needed, to maintain decay heat removal and reactor coolant circulation. Verification is performed by verifying proper breaker alignment and power available to the required pump. The Surveillance is required to be performed when the LCO requirement is being met by one of two SC trains (e.g., SGs have \(<25\%\) wide range water level). The 7 day Frequency is considered reasonable in view of other administrative controls available and has been shown to be acceptable by operating experience.

This SR is modified by a Note that states the SR is not required to be performed until 24 hours after a required pump is not in operation.

SR 3.4.7.4

Shutdown Cooling System (SCS) piping and components have the potential to develop voids and pockets of entrained gases. Preventing and managing gas intrusion and accumulation is necessary for proper operation of the required SCS train(s) and may also prevent water hammer, pump cavitation, and pumping of non-condensible gas into the reactor vessel.

Selection of SCS locations susceptible to gas accumulation is based on a review of system design information, including piping and instrumentation drawings, isometric drawings, plan and elevation drawings, and calculations. The design review is supplemented by system walk downs to validate the system high points and to confirm the location and orientation of important components that can become sources of gas or could otherwise cause gas to be trapped or difficult to remove during system maintenance or restoration. Susceptible locations depend on plant and system configuration, such as stand-by versus operating conditions.

The SCS is OPERABLE when it is sufficiently filled with water. Acceptance criteria are established for the volume of accumulated gas at susceptible locations. If accumulated gas is discovered that exceeds the acceptance criteria for the susceptible location (or the volume of accumulated gas at one or more susceptible locations exceeds an acceptance criterion for gas volume at the suction or discharge of a pump), the Surveillance is not met. If it is determined by subsequent evaluation that the SCS is not rendered inoperable by the accumulated
gas (i.e., the system is sufficiently filled with water), the Surveillance may be declared met. Accumulated gas should be eliminated or brought within the acceptance criteria limits.

SCS locations susceptible to gas accumulation are monitored and, if gas is found, the gas volume is compared to the acceptance criteria for the location. Susceptible locations in the same system flow path which are subject to the same gas intrusion mechanisms may be verified by monitoring a representative sub-set of susceptible locations. Monitoring may not be practical for locations that are inaccessible due to radiological or environmental conditions, the plant configuration, or personnel safety. For these locations alternative methods (e.g., operating parameters, remote monitoring) may be used to monitor the susceptible location. Monitoring is not required for susceptible locations where the maximum potential accumulated gas void volume has been evaluated and determined to not challenge system OPERABILITY. The accuracy of the method used for monitoring the susceptible locations and trending of the results should be sufficient to assure system OPERABILITY during the Surveillance interval.

This SR is modified by a Note that states the SR is not required to be performed until 12 hours after entering MODE 4. In a rapid shutdown, there may be insufficient time to verify all susceptible locations prior to entering MODE 4.

The 31 day Frequency takes into consideration the gradual nature of gas accumulation in the SCS piping and the procedural controls governing system operation.

SCS locations susceptible to gas accumulation are monitored and, if gas is found, the gas volume is compared to the acceptance criteria for the location. Susceptible locations in the same system flow path which are subject to the same gas intrusion mechanisms may be verified by monitoring a representative sub-set of susceptible locations. Monitoring may not be practical for locations that are inaccessible due to radiological or environmental conditions, the plant configuration, or personnel safety. For these locations alternative methods (e.g., operating parameters, remote monitoring) may be used to monitor the susceptible location. Monitoring is not required for susceptible locations where the maximum potential accumulated gas void volume has been evaluated and determined to not challenge system OPERABILITY. The accuracy of the method used for monitoring the susceptible locations and trending of the results should be sufficient to assure system OPERABILITY during the Surveillance interval.
This SR is modified by a Note that states the SR is not required to be performed until 12 hours after entering MODE 4. In a rapid shutdown, there may be insufficient time to verify all susceptible locations prior to entering MODE 4.

The 31 day Frequency takes into consideration the gradual nature of gas accumulation in the SCS piping and the procedural controls governing system operation.

REFERENCES
1. FSAR, Subsection 15.4.6.
B 3.4 REACTOR COOLANT SYSTEM (RCS)  

B 3.4.8 RCS Loops – MODE 5 (Loops Not Filled)  

BASES  

BACKGROUND  
In MODE 5 with the RCS loops not filled, the primary function of the reactor coolant is the removal of decay heat and transfer of this heat to the shutdown cooling (SC) heat exchangers. The steam generators are not available as a heat sink when the loops are not filled. The secondary function of the reactor coolant is to act as a carrier for soluble neutron poison, boric acid.  

In MODE 5 with loops not filled, only the SC System (SCS) can be used for coolant circulation. The number of trains in operation can vary to suit the operational needs. The intent of this LCO is to provide forced flow from at least one SC train for decay heat removal and transport. The other intent of this LCO is to require that two paths be available to provide redundancy for heat removal.  

This LCO permits limited periods without forced circulation. When the SC trains are not in operation, no alternate heat removal path exists. The response of the RCS without the SCS depends on the decay heat load and the length of time that the SC pumps are stopped. As decay heat diminishes, the effects on RCS temperature diminish. Without cooling by SCS, higher heat loads will cause the reactor coolant temperature to increase at a rate proportional to the decay heat load. Because pressure can increase, applicable system pressure limits (pressure and temperature limits or low temperature overpressurization limits) must be observed and forced SCS flow must be reestablished prior to reaching the pressure limit. Entry into a condition with no SC train in operation stops heat removal and should only be considered for limited circumstances such as when switching from one SC train to the other. With the SC pumps stopped, pressure and temperature could increase and pumps must be restored prior to exceeding pressure and saturation margin limits.  

The SC System removes decay heat from the RCS and transfers the heat to the Component Cooling Water (CCW) System. During “Loops Not Filled” operations the interruption or loss of SCS flow, decay heat removal (DHR) capability, can lead to bulk boiling quite rapidly. In some cases, this can occur in 15 to 20 minutes. During “Loops Not Filled” operations, the SCS is the primary means of decay heat removal.
### BASES

| APPLICABLE SAFETY ANALYSES | In MODE 5, RCS circulation forced by RCPs is considered in determining the time available for mitigation of the accidental boron dilution event. In MODE 5 with all RCPs idle, the possibility of an inadvertent boron dilution event (Ref. 1) is precluded by adherence to LCO 3.1.12, which requires that potential dilution sources be isolated. The flow provided by one SC train is adequate for decay heat removal. RCS loops – MODE 5 (loops not filled) satisfies Criterion 4 of 10 CFR 50.36(c)(2)(ii). |

### LCO

The purpose of this LCO is to require a minimum of two SC trains be OPERABLE and one of these trains be in operation. An OPERABLE train is one that has the capability of transferring heat from the reactor coolant at a controlled rate.

Heat removal cannot occur via the SC System unless forced flow is used. A minimum of one running SC pump meets the LCO requirement for one train in operation. An additional SC train is required to be OPERABLE to meet the single failure criterion.

During Loops Not Filled operations, the containment spray pump in the OPERABLE SC train shall be OPERABLE.

Note 1 permits the SC pumps to be removed from operation for ≤15 minutes when switching from one train to another. The circumstances for stopping both SC pumps are to be limited to situations when the outage time is short and the core outlet temperature is maintained at least 5.6°C (10°F) below saturation temperature. The Note prohibits boron dilution with coolant at boron concentrations less than required to assure the SDM of LCO 3.1.1 is maintained or draining operations when SC forced flow is stopped.

Note 2 allows one SC train to be inoperable for a period of 2 hours provided that the other train is OPERABLE and in operation. This permits periodic surveillance tests to be performed on the inoperable train during the only time when these tests are safe and possible.

An OPERABLE SC train is composed of an OPERABLE SC pump capable of providing forced flow to an OPERABLE SC heat exchanger, along with the appropriate flow and temperature instrumentation for control, protection, and indication. SC pumps are OPERABLE if they are capable of being powered and are able to provide flow if required. Management of gas voids is important to SCS OPERABILITY.
Note 3 permits the containment spray (CS) pump associated with the SC train not in operation to be manually aligned to meet the LCO OPERABILITY requirement of its associated SC pump. The CS pump is designed to be interchangeable with its associated SC pump for operational flexibility. In MODE 5, the CS pumps are not required to meet the requirements of LCO 3.6.6, therefore they are available to support the SC function. If the CS pump is aligned to meet the requirements of its associated SC pump, then the SRs of this LCO must be applied to the CS pump instead of the SC pump, as necessary.

The mid-loop condition is the plant condition with the fuel in the reactor vessel and the reactor coolant level below the top of the hot legs at their junction with the reactor vessel. Note 4 prohibits entering mid-loop conditions (RCS level \( \leq \) 36.30 m (119 ft 1 in)) until 96 hours after reactor shutdown provided core exit temperature is maintained less than or equal to 57.2°C (135°F). These limitations ensure the operating conditions assumed in the Safety Analysis of the Loss of Residual Heat Removal event will be maintained in order to operate the plant safely during mid-loop operation.

In MODE 5 with loops not filled, this LCO requires core heat removal and coolant circulation by the SCS.

In the MODE 5 with RCS loops not filled condition, the steam generators (SGs) cannot be used for core decay heat removal because the SG tubes contain water vapor voids or non-condensible gases that restrict the flow of reactor coolant through the SG tubes to less than the flow needed for adequate secondary heat transfer. The loops not filled condition is entered during draining of the RCS when the reactor coolant level is below 134 ft, which is about 28 ft below the highest SG tubes. Below this level, containment atmospheric pressure can no longer completely support the column of water remaining in the SG tubes above the reactor coolant level. At reactor coolant levels below 134 ft, water vapor voids begin forming in the horizontal portions of SG tubes, beginning with the highest tubes. The number of affected tubes increases as RCS level decreases until all tubes contain water vapor voids. SG tubes containing voids of water vapor, at the saturation temperature vapor pressure of the coolant in the tubes, block coolant flow and secondary heat transfer. When reactor coolant level has decreased to 119 ft 1 in (just above the high point of the hot leg), air can begin entering the hot leg through the surge line connection and displace the coolant remaining in the SG tubes. This results in the SG tubes being filled with non-condensible gases. The condition in MODE 5 with RCS water level within the top half of the hot legs is called mid-loop operation.
Restoring the unit to the MODE 5 with RCS loops filled condition requires raising RCS level above 134 ft during a draining operation, provided no air was introduced into the SG tubes. Restoring the unit to the MODE 5 with RCS loops filled condition following mid-loop operation requires closing the pressurizer manway, filling the pressurizer, and dynamically venting non-condensible gases from the SG tubes and reactor vessel closure head using the Reactor Coolant Gas Vent (RCGV) System and the reactor coolant pumps (RCPs). A forced circulation by the RCPs in the MODE 5 with loops not filled condition is possible when the static head of the water from pressurizer water level establishes an RCS pressure high enough to run an RCP.

The typical initial conditions of loss of residual heat removal (LORHR) are the reduced inventory or the mid-loop operation. The pressurizer manway opening configuration is selected as a representative case because the pressurizer manway will be always open during the reduced inventory operation. Several calculations are performed for the LORHR events with various RCS openings in addition to the pressurizer manway opening.

The time of 4 days after shutdown and the hot leg temperature of 57.2°C (135°F) are used for the analyses. The initial steady state calculation is performed considering one train of the Shutdown Cooling System (SCS) operation based on the normal SC operation. The coolant injection of SC to the RCS is performed through the DVI nozzle and the SC suction is considered from the hot leg. The SCS flow rate is assumed as approximate average value of 1 train SCS flow.

Operation in other MODES is covered by:

LCO 3.4.4, “RCS Loops – MODES 1 and 2”;
LCO 3.4.5, “RCS Loops – MODE 3”;
LCO 3.4.6, “RCS Loops – MODE 4”;
LCO 3.4.7, “RCS Loops – MODE 5 (Loops Filled)”;
LCO 3.9.4, “Shutdown Cooling System (SCS) and Coolant Circulation – High Water Level”; and
LCO 3.9.5, “Shutdown Cooling System (SCS) and Coolant Circulation – Low Water Level.”
ACTIONS

A.1

If one required SC train is inoperable, redundancy for heat removal is lost. Action must be initiated immediately to restore a second train to OPERABLE status. The immediate Completion Time reflects the importance of maintaining the availability of two paths for heat removal.

B.1, B.2 and B.3

If no required SC train is OPERABLE or the required train is not in operation, except as provided in Note 1, all operations involving introduction of coolant into the RCS with boron concentration less than required to meet the minimum SDM of LCO 3.1.1 must be suspended. The action must be initiated to raise RCS level to greater than 38.72 m (127 ft 1/4 in) and to immediately start restoration of one SC train to OPERABLE status. The required margin to criticality must not be reduced in this type of operation. Suspending the introduction of coolant into the RCS of coolant with boron concentration less than required to meet the minimum SDM of LCO 3.1.1 is required to assure continued safe operation. With coolant added without forced circulation, unmixed coolant could be introduced to the core, however coolant added with boron concentration meeting the minimum SDM maintains acceptable margin to subcritical operations. The immediate Completion Time reflects the importance of maintaining operation for decay heat removal.

C.1, C.2, and C.3

If the containment spray pump in the operating SC train is inoperable, action must be initiated immediately to place the alternate SC train in operation if the containment spray pump in the alternate train is OPERABLE. Also, SC System performance must be monitored every 30 minutes and the inoperable containment spray pump must be restored to OPERABLE status within 48 hours.

D.1

If the containment spray pump cannot be restored within 48 hours, RCS level must be raised to > 38.72 m (127 ft 1/4 in) within 6 hours. This will place the plant in a conservative position with respect to providing decay heat removal.
If the core exit temperature > 57.2°C (135°F) during mid-loop operation or RCS level in mid-loop condition (≤ 36.30 m (119 ft 1 in)) with < 96 hours after reactor shutdown, action must be initiated immediately to decrease the RCS temperature and raise the RCS level higher than the hot leg top. These actions assure the plant conditions assumed in the safety analysis.

**SURVEILLANCE REQUIREMENTS**

**SR 3.4.8.1**

This SR requires verification of the core exit temperature is within the limit. This verification ensures the plant conditions assumed in the safety analysis during mid-loop operation. The Frequency of 15 minutes reflects the importance of maintaining the core exit temperature below the assumed value in the safety analysis during the mid-loop operation. This SR is modified by a Note that states the SR is only required to be met when in mid-loop operation.

**SR 3.4.8.2**

This SR requires verification of the required SC train is in operation and circulating reactor coolant every 12 hours. The flow rate is determined to provide sufficient decay heat removal capability and to prevent thermal and boron stratification and also to address air ingestion in the hot leg when the RCS water inventory is maintained at the lowest permitted level.

Verification includes flow rate, temperature, or pump status monitoring, which help ensure that forced flow is providing decay heat removal.

The 12 hour Frequency has been shown by operating practice to be sufficient to regularly assess degradation and verify operation within safety analyses assumptions.

**SR 3.4.8.3**

Verification that the required number of trains are OPERABLE ensures that redundant paths for heat removal are available and additional trains can be placed in operation, if needed, to maintain decay heat removal and reactor coolant circulation. Verification is performed by verifying proper breaker alignment and indicated power available to the required pump that is not in operation.
This verification is not needed for the operating pump since it is verified to be in operation in accordance with SR 3.4.8.2. If the containment spray pump is aligned to meet the requirements of the SC pump that is not in operation, then this SR must be applied to the containment spray pump instead of the SC pump.

The 7 day Frequency is considered reasonable in view of other administrative controls available and has been shown to be acceptable by operating experience.

This SR is modified by a Note that states the SR is not required to be performed until 24 hours after a required pump is not in operation.

SR 3.4.8.4

Verification of the correct breaker alignment and indicated power available to the required containment spray pump ensures that the redundant containment spray pump will be able to remove heat from the RCS in the event of a power failure to the operating SC train. The Frequency of 24 hours is based on operating experience.

SR 3.4.8.5

SCS piping and components have the potential to develop voids and pockets of entrained gases. Preventing and managing gas intrusion and accumulation is necessary for proper operation of the SC trains and may also prevent water hammer, pump cavitation, and pumping of non-condensible gas into the reactor vessel.

Selection of SCS locations susceptible to gas accumulation is based on a review of system design information, including piping and instrumentation drawings, isometric drawings, plan and elevation drawings, and calculations. The design review is supplemented by system walk downs to validate the system high points and to confirm the location and orientation of important components that can become sources of gas or could otherwise cause gas to be trapped or difficult to remove during system maintenance or restoration. Susceptible locations depend on plant and system configuration, such as stand-by versus operating conditions.
The SCS is OPERABLE when it is sufficiently filled with water. Acceptance criteria are established for the volume of accumulated gas at susceptible locations. If accumulated gas is discovered that exceeds the acceptance criteria for the susceptible location (or the volume of accumulated gas at one or more susceptible locations exceeds an acceptance criterion for gas volume at the suction or discharge of a pump), the Surveillance is not met. If it is determined by subsequent evaluation that the SCS is not rendered inoperable by the accumulated gas (i.e., the system is sufficiently filled with water), the Surveillance may be declared met. Accumulated gas should be eliminated or brought within the acceptance criteria limits.

SCS locations susceptible to gas accumulation are monitored and, if gas is found, the gas volume is compared to the acceptance criteria for the location. Susceptible locations in the same system flow path which are subject to the same gas intrusion mechanisms may be verified by monitoring a representative sub-set of susceptible locations. Monitoring may not be practical for locations that are inaccessible due to radiological or environmental conditions, the plant configuration, or personnel safety. For these locations alternative methods (e.g., operating parameters, remote monitoring) may be used to monitor the susceptible location. Monitoring is not required for susceptible locations where the maximum potential accumulated gas void volume has been evaluated and determined to not challenge system OPERABILITY. The accuracy of the method used for monitoring the susceptible locations and trending of the results should be sufficient to assure system OPERABILITY during the Surveillance interval.

The 31 day Frequency takes into consideration the gradual nature of gas accumulation in the SCS piping and the procedural controls governing system operation.

REFERENCES
   1. FSAR, Subsection 15.4.6.
B 3.4  REACTOR COOLANT SYSTEM (RCS)

B 3.4.9  Pressurizer

BASES

BACKGROUND  The pressurizer provides a point in the RCS where liquid and vapor are maintained in equilibrium under saturated conditions for pressure control purposes to prevent bulk boiling in the remainder of the RCS. Key functions include maintaining required primary system pressure during steady state operation and limiting the pressure changes caused by reactor coolant thermal expansion and contraction during normal load transients.

The pressure control components addressed by this LCO include the pressurizer water level, the proportional heaters and their backup heater controls, and emergency power supplies. Pilot operated safety relief valves (POSRVs) are addressed by LCO 3.4.10, "Pressurizer Pilot Operated Safety Relief Valves."

The maximum steady state water level limit in the pressurizer has been established to ensure that a liquid-to-vapor interface exists to permit RCS pressure control, using sprays and heaters during normal operation and proper pressure response for anticipated design basis transients (Ref. 1). The maximum and minimum steady state water level limit serves two purposes:

a. Pressure control during normal operation maintains subcooled reactor coolant in the loops and thus, in the preferred state for heat transport; and

b. By restricting the level to a maximum, expected transient reactor coolant volume increases (pressurizer insurge) will not cause excessive level changes which could result in degraded ability for pressure control.

The maximum steady state water level limit in the pressurizer permits pressure control equipment to function as designed. The limit preserves the steam space during normal operation, thus, both sprays and heaters can operate to maintain the design operating pressure. The level limit also prevents filling the pressurizer (water solid) for anticipated design basis transients, thus ensuring that pressure relief devices (POSRVs) can control pressure by steam relief rather than water relief (Ref. 1). If the level limits were exceeded prior to a transient that creates a large pressurizer insurge volume leading to water relief, the maximum RCS pressure may exceed the safety limit of 193.3 kg/cm²A (2,750 psia).
The minimum steady state water level in the pressurizer assures pressurizer heaters, which are required to achieve and maintain pressure control, remain covered with water to prevent failure, which could occur if the heaters were energized uncovered.

The requirement to have two groups of pressurizer heaters ensures that RCS pressure can be maintained. The pressurizer heaters maintain RCS pressure to keep the reactor coolant subcooled. Inability to control RCS pressure during natural circulation flow could result in a loss of single phase flow and a decreased capability to remove core decay heat.

In MODES 1, 2, and 3, the LCO requirement for a steam bubble is reflected implicitly in the accident analyses. No safety analyses are performed in lower MODES. All analyses performed from a critical reactor condition assume the existence of a steam bubble and saturated conditions in the pressurizer. In making this assumption, the analyses neglect the small fraction of non-condensible gases normally present.

Safety analyses presented in FSAR do not take credit for pressurizer heater operation, however, an implicit initial condition assumption of the safety analyses is that the RCS is operating at normal pressure.

Although the heaters are not specifically credited in accident analysis, the need to maintain saturation margin in the long term during loss of offsite power, as indicated in NUREG-0737 (Ref. 2), is the reason for inclusion. The requirement for emergency power supplies is based on NUREG-0737 (Ref. 2). The intent is to allow maintaining the reactor coolant in a subcooled condition with natural circulation at hot, high pressure conditions for an undefined, but extended, time period after a loss of offsite power. While loss of offsite power is a coincident occurrence with turbine trip assumed in many accident analyses, maintaining hot, high pressure conditions over an extended time period is not evaluated as part of the accident analyses.

The pressurizer satisfies Criteria 2 and 3 of 10 CFR 50.36(c)(2)(ii).
BASES

LCO

The LCO requirement for the pressurizer to be OPERABLE with water level $\geq 25\%$ and $\leq 56\%$ ensures that a steam bubble exists. Limiting the maximum operating water level preserves the steam space for pressure control. The minimum operating water level is established to ensure that pressurizer heaters remain covered with water to prevent failure, which could occur if the heaters were energized uncovered in the steam bubble region. The intent of the LCO is to ensure that a steam bubble exists in the pressurizer to minimize the consequences of potential overpressure transients.

The LCO requires two groups of OPERABLE pressurizer heaters, each with a capacity $\geq 200$ kW (and capable of being powered from an emergency power supply). The minimum heater capacity required is sufficient to maintain the RCS near normal operating pressure when accounting for heat losses through the pressurizer insulation. By maintaining the pressure near the operating conditions, a wide subcooling margin to saturation can be obtained in the loops. The exact design value of 300 kW is derived from the use of 6 heaters rated at 50 kW each. The amount needed to maintain pressure is dependent on the ambient heat losses.

APPLICABILITY

The need for pressurizer pressure control is most pertinent when core heat can cause the greatest effect on RCS temperature resulting in the greatest effect on pressurizer level and RCS pressure control. Thus, Applicability has been designated for MODES 1, 2, and 3. The purpose is to prevent solid water RCS operation during heatup and cooldown to avoid rapid pressure rises caused by normal operational perturbation, such as reactor coolant pump startup.

The LCO does not apply to MODE 5 (Loops Filled) because LCO 3.4.11, “Low Temperature Overpressure Protection (LTOP) System,” applies. The LCO does not apply to MODES 5 and 6 with partial loop operation.

In MODES 1, 2, and 3, there is the need to maintain the availability of pressurizer heaters capable of being powered from an emergency power supply. In the event of a loss of offsite power, the initial conditions of these MODES give the greatest demand for maintaining the RCS in a hot pressurized condition with loop saturation margin for an extended period. For MODE 4, 5, or 6, it is not necessary to control pressure (by heaters) to ensure loop saturation margin for heat transfer when the Shutdown Cooling System is in-service and, therefore, the LCO is not applicable.
With pressurizer water level outside the limits, action must be taken within 1 hour to restore the plant to operation within the bounds of the safety analyses. If pressurizer water level cannot be restored to within the limits in 1 hour, this is done by placing the plant in MODE 3 with the reactor trip switch gears open within 6 hours, and placing the plant in MODE 4 within 12 hours. This takes the plant out of the applicable MODES and restores the plant to operation within the bounds of the safety analyses.

The Completion Time of 6 hours is a reasonable time based on operating experience to reach MODE 3 from full power in an orderly manner and without challenging plant systems. Further pressure and temperature reduction to MODE 4 brings the plant into a MODE where the LCO is not applicable. The 12 hour time to reach the non-applicable MODE is reasonable based on operating experience for that evolution.

C.1

If one required group of pressurizer heaters is inoperable, restoration is required within 72 hours. The Completion Time of 72 hours is reasonable considering that a demand caused by loss of offsite power would be unlikely in this period. RCS pressure control may be maintained during this time using normal station powered heaters.

D.1 and D.2

If one required group of pressurizer heaters is inoperable and cannot be restored within the allowed Completion Time of Required Action C.1, the plant must be brought to a MODE in which the LCO does not apply. To achieve this status, the plant must be brought to MODE 3 within 6 hours and to MODE 4 within 12 hours. The Completion Time of 6 hours is reasonable, based on operating experience, to reach MODE 3 from full power in an orderly manner and without challenging safety systems. Similarly, the Completion Time of 12 hours is reasonable, based on operating experience, to reach MODE 4 from full power in an orderly manner and without challenging plant systems.

This SR ensures that during steady state operation, pressurizer water level is maintained below the nominal upper limit to provide a minimum space for a steam bubble and above the nominal lower limit to prevent failure, which could occur if the heaters were energized uncovered. The Surveillance is performed by observing indicated level.
The 12 hour interval has been shown by operating practice to be sufficient to regularly assess degradation and verify operation within safety analysis assumptions. Alarms are also available for early detection of abnormal level indications.

**SR 3.4.9.2**

The SR is satisfied when the power supplies are demonstrated to be capable of producing the minimum power and the associated pressurizer heaters are verified to be at their design rating. This may be done by testing the power supply output and by performing an electrical check on heater element continuity and resistance. The 92 day Frequency is considered adequate to detect heater degradation and has been shown by operating experience to be acceptable.

**SR 3.4.9.3**

This SR demonstrates that the heaters can be manually transferred to and energized by emergency power supplies. The Frequency of 18 months is based on a typical fuel cycle and industry accepted practice. This is consistent with similar verifications of emergency power.

**REFERENCES**

1. FSAR, Chapter 15.
2. NUREG-0737, II.E.3.1, November 1980.
B 3.4 REACTOR COOLANT SYSTEM (RCS)

B 3.4.10 Pressurizer Pilot Operated Safety Relief Valves (POSRVs)

Bases

Background

Pressurizer POSRVs are designed to provide an overpressure protection function and a rapid depressurization function for the RCS. Two spring-loaded pilot valves per each main valve are installed to provide RCS overpressure protection. Motor operated isolation valves and manual isolation valves are installed to isolate spring-loaded pilot valves, and are maintained in the open position during normal operation. Two motor operated pilot valves per each main valve are installed in series to provide the rapid depressurization function. These motor operated pilot valves are maintained in the closed position during normal operation. Operating in conjunction with the Reactor Protection System, four POSRVs are used to ensure that the safety limit (SL) of 193.3 kg/cm²A (2,750 psia) is not exceeded for analyzed transients during operation in MODES 1 and 2. Four POSRVs are also required in MODE 3 and a portion of MODE 4. In the remainder of MODE 4 and in MODE 5, overpressure protection is provided by operating procedures and LCO 3.4.11, “Low Temperature Overpressure Protection (LTOP) System.”

The self-actuated pressurizer POSRVs are designed in accordance with the requirements set forth in the ASME Boiler and Pressure Vessel Code, Section III (Ref. 1). The pressurizer POSRVs discharge steam from the pressurizer to the in-containment refueling water storage tank (IRWST) located in the containment.

The lift pressure setpoint of the four pressurizer POSRVs is 173.7 kg/cm²A (2,470 psia). The lift pressure setpoint of the four POSRVs is established to prevent the RCS pressure from exceeding the RCS pressure SL and maintain the assumed conditions of the safety analyses. The POSRV lift setting (as-found setpoint) includes a tolerance of 1.5% for the lifting pressure during operation. After testing, the lift setting (as-left setpoint) is adjusted to within the setpoint tolerance of 0.75%. The lift setting accounts for the ambient conditions associated with unit operation in MODES 1, 2, and 3. This requires that the valves be set while in a hot condition.

The overpressure protection function of the POSRVs is achieved by opening the main valve in response to the opening of the spring-loaded pilot valves, resulting in a pressure relief function. The inherent time delay (dead time) between the operations of the pilot valves and the main valve is caused by the design characteristics of the POSRVs. The required opening time of the POSRVs is limited to within 0.5 seconds.
Therefore, a POSRV is OPERABLE if the lift setting of its two spring-
loaded pilot valves per each main valve and the opening time of the
POSRVs satisfy the above requirements. Since safety analyses do not
take credit for motor operated isolation valve operation to mitigate the
inadvertent opening of spring-loaded pilot valves, this isolation valve
operation is not considered to be a safety function.

The pressurizer POSRVs are part of the primary success path and to
mitigate the effects of postulated accidents. OPERABILITY of the
POSRVs ensures that the RCS pressure will be limited to 110% of design
pressure. The consequences of exceeding the ASME pressure limit
(Ref. 1) could include damage to RCS components, increased leakage, or
a requirement to perform additional stress analyses prior to resumption of
reactor operation.

All accident analyses described in the FSAR that require safety valve
actuation assume operation of all four POSRVs to limit increasing RCS
pressure. The overpressure protection analysis is based on operation of
all POSRVs and assumes that the valves open at the high end of the
range of the allowable lift setting (nominal lift setting pressure plus a total
uncertainty of 2%) with an opening time of 0.55 seconds. The total
uncertainty in the lift setting pressure includes 0.5% for the uncertainty of
instrumentation used to verify the lift setting of the valves plus some
operating margin. The 0.55 second opening time includes 0.05 second
operating margin.

These valves must accommodate pressurizer insurges, which could occur
during various heatup events such as startup, rod withdrawal, ejected rod,
loss of main feedwater, loss of load, or main feedwater line break
accident. The loss of load event with delayed reactor trip which is
described in FSAR Chapter 5 establishes the minimum pressurizer
POSRV relieving capacity.

The pressurizer POSRVs are components that are part of the primary
success path and function or actuate to mitigate a design basis event or
transient that either assumes the failure of, or presents a challenge to, the
integrity of a fission product barrier. As such, the pressurizer POSRVs
satisfy Criterion 3 of 10 CFR 50.36(c)(2)(ii).
The four pressurizer POSRVs are set to open at 173.7 kg/cm²A (2,470 psia). The lift pressure of four POSRVs is established to prevent the RCS pressure from exceeding the RCS pressure SL and the assumed conditions of the safety analyses. The POSRV lift setting (as-found setpoint) includes a tolerance of 1.5% for the lifting pressure during operation. After testing, the lift setting (as-left setpoint) is adjusted to within the setpoint tolerance of 0.75%.

The fully opening time is assumed to be 0.55 seconds, including a measurement uncertainty of 0.05 seconds, in the safety analyses. Therefore, the required opening time of the POSRVs is limited to within 0.5 seconds and is verified once during each refueling cycle.

If the lift settings of the two spring-loaded pilot valves and the actuation times of the POSRVs are within the LCOs, then the POSRVs are OPERABLE.

The limit protected by this Specification is the reactor coolant pressure boundary SL of 110% of design pressure.

The consequences of exceeding the ASME pressure limit could include damage to one or more RCS components, increased LEAKAGE, or additional stress analysis being required prior to resumption of reactor operation.

In MODES 1, 2, and 3, and portions of MODE 4 above LTOP temperatures, OPERABILITY of four POSRVs is required because the combined capacity is required to keep RCS pressure below 110% of its design value during certain accidents. MODE 3 and portions of MODE 4 are conservatively included although the listed accidents may not require all pressurizer POSRVs for protection.

The LCO is not applicable in MODE 4 when all RCS cold leg temperatures are less than or equal to the LTOP enable temperature specified in the PTLR, MODES 5 and 6 with reactor vessel closure head on, because LTOP is provided by LCO 3.4.11, “Low Temperature Overpressure Protection (LTOP) System.” Overpressure protection is not required in MODE 6 with the reactor vessel closure head detensioned.
APPLICABILITY (continued)

The Note allows entry into MODES 3 and 4 with the lift settings outside the LCO limits. This permits testing and examination of the pressurizer POSRVs at high pressure and temperature near their normal operating range, but only after opening time measurement and lift setting of POSRVs have had a preliminary cold setting. The cold setting gives assurance that the valves are OPERABLE near their design condition. The 72 hour exception is derived from operating experience that hot testing can be performed within this time frame.

ACTIONS

A.1

With one pressurizer POSRV inoperable, the restoration must take place within 15 minutes. The Completion Time of 15 minutes reflects the importance of maintaining the RCS Overpressure Protection System. An inoperable POSRV coincident with an RCS overpressure event could challenge the integrity of the reactor coolant pressure boundary (RCPB).

B.1, B.2.1, and B.2.2

If the Required Action cannot be met within the associated Completion Time, or if two or more POSRVs are inoperable, the plant must be placed in a MODE in which the requirement does not apply. To achieve this status, the plant must be brought to at least MODE 3 within 6 hours and to MODE 4 with all RCS cold leg temperature less than or equal to the LTOP enable temperature specified in the PTLR within 12 hours, or a condition where shutdown cooling suction line LTOP relief valves are applied within 12 hours. The 6 hours allowed is a reasonable time based on operating experience to reach MODE 3 from full power without challenging plant systems. Similarly, the 12 hours allowed is a reasonable time based on operating experience to reach MODE 4 without challenging plant systems.

With RCS cold leg temperature less than or equal to the LTOP enable temperature specified in the PTLR, overpressure protection is provided by LTOP.

The change from MODE 1, 2, or 3 to MODE 4 reduces the RCS energy (core power and pressure), lowers the potential for large pressurizer insurges, and thereby removes the need for overpressure protection by four POSRVs.
### BASES

<table>
<thead>
<tr>
<th>SURVEILLANCE REQUIREMENTS</th>
<th>SR 3.4.10.1</th>
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<tbody>
<tr>
<td></td>
<td>Periodic verification of the correct valve position indication in the main control room (MCR) for all pressurizer POSRVs, spring-loaded pilot valves, motor operated isolation valves, manual isolation valves, and motor operated pilot valves ensures that the valves are properly aligned and that the position indicators are functioning properly. A Frequency of 12 hours is accepted by industry practice, and has been shown to be acceptable by operating experience.</td>
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<th>SR 3.4.10.2</th>
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<td></td>
<td>Verification of removal of power to motor operated isolation valves and upstream valves of motor operated pilot valves ensures that the motor operated isolation valves are not inadvertently actuated by an operator. The 7 day Frequency is accepted by industry practice and has been shown to be acceptable by operating experience.</td>
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<th>SR 3.4.10.3</th>
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<td></td>
<td>SRs are specified for verifying the lift pressure settings and opening time of pressurizer POSRVs. The allowable range of the as-found lift pressure setting of each pressurizer POSRV spring-loaded pilot valve is 1.5% of the valve setpoint above the valve setpoint to 1.5% of the valve setpoint below the valve setpoint. The surveillance requires adjusting the as-left lift pressure setting within the allowable range of 0.75% of the valve setpoint above the valve setpoint and 0.75% of the valve setpoint below the valve setpoint. The specified pressurizer POSRV opening time including dead time of 0.5 seconds or less is consistent with the safety analyses. The dead time is from when the pressure reaches the spring-loaded pilot valves' opening setpoint until the main valve begins to move (open). The pressurizer POSRV lift pressure setpoint verification and adjustment, and opening time verification are normally performed in MODE 3 during plant heatup following each refueling, which is once every 18 months. The ASME Operations and Maintenance (OM) Code (Ref. 2) recommends performing the lift pressure setting verification and adjustment every 5 years as the necessary Frequency to satisfy the requirements for lift pressure settings of safety relief valves. However, the surveillance to verify the pressurizer POSRV lift pressure setting and opening time are performed every refueling cycle according to the special requirements of the pressurizer POSRVs. If the two spring-loaded pilot valves of a pressurizer POSRV both satisfy the requirements of lift setting and opening time, then the pressurizer POSRV is OPERABLE.</td>
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SR 3.4.10.4

Verification of the OPERABILITY of alarm devices for the valve positions and electric power connections for motor operated isolation valves, manual isolation valves, and motor operated pilot valves ensures that inadvertent actuation of each valve can be monitored. This Surveillance must be performed at an 18 month Frequency.

SR 3.4.10.5

Verification of the OPERABILITY of position indicators for each valve containing main valve ensures that inadvertent actuation of each valve can be monitored. This Surveillance must be performed at an 18 month Frequency.

SR 3.4.10.6

When the downstream manual isolation valves of spring-loaded pilot valves are locked in open position, overpressure protection function can be performed properly. Securing these valves in position by removing power or key locking the control in the correct position ensures that the valves cannot be inadvertently misaligned or repositioned. The 18 month Frequency is based on the POSRVs being easily accessible only during the shutdown conditions of a refueling outage.

REFERENCES

1. ASME Section III.
2. ASME OM Code.
3. FSAR, Chapter 5.
B 3.4 REACTOR COOLANT SYSTEM (RCS)

B 3.4.11 Low Temperature Overpressure Protection (LTOP) System

BACKGROUND

The LTOP System controls RCS pressure at low temperatures so the integrity of the reactor coolant pressure boundary (RCPB) is not compromised by violating the pressure and temperature (P/T) limits of 10 CFR 50, Appendix G (Ref. 1). The reactor vessel is the limiting component for demonstrating that protection is provided. LCO 3.4.3, “RCS Pressure and Temperature (P/T) Limits,” provides the allowable combinations for operational pressure and temperature during cooldown, shutdown, and heatup to keep from violating the Reference 1 requirements during the LTOP MODES.

The reactor vessel material is less tough at low temperatures than at normal operating temperatures. As reactor vessel neutron exposure accumulates, the vessel material toughness decreases and becomes less resistant to pressure stress at low temperatures (Ref. 2). RCS pressure, therefore, is maintained low at low temperatures and is increased only as temperature is increased.

The potential for vessel overpressurization is most acute when the RCS is water solid, occurring only while shutdown; a pressure fluctuation can occur more quickly than an operator can react to relieve the condition. Exceeding the RCS P/T limits by a significant amount could cause brittle cracking of the reactor vessel. LCO 3.4.3 requires administrative control of RCS pressure and temperature during heatup and cooldown to prevent exceeding the P/T limits.

This LCO provides RCS overpressure protection by having adequate pressure relief capacity. The pressure relief capacity requires either two OPERABLE Shutdown Cooling System (SCS) suction line relief valves or the RCS depressurized and an RCS vent of sufficient size. One SCS suction line relief valve or the RCS vent is sufficient to provide the overpressure protection necessary to terminate an increasing pressure event.

The LTOP System for pressure relief consists of two OPERABLE SCS suction line relief valves with their opening setpoints or an RCS vent of sufficient size. Two relief valves are required for redundancy. One SCS suction line relief valve has adequate relieving capability to prevent overpressurization for the limiting low temperature and overpressurization transients.
SCS suction line relief valve Requirements

As designed for the LTOP System, the SCS suction line relief valves automatically open if the RCS pressure approaches their opening setpoints. When the SCS suction line relief valves are opened in an increasing pressure transient, the release of coolant causes the pressure increase to slow and maintains RCS pressure below the P/T limits.

RCS Vent Requirements

Once the RCS is depressurized, a vent exposed to the containment atmosphere will maintain the RCS at containment ambient pressure in an RCS overpressure transient, if the relieving requirements of the transient do not exceed the capabilities of the vent. Thus, the vent path must be capable of relieving the flow resulting from an RCS overpressure transient and maintaining pressure below the P/T limits. The required vent capacity may be provided by opening one or more vent paths.

For an RCS vent to meet the specified flow capacity, a pressurizer manway, with flow area greater than the flow area of one SCS suction line relief valve discharge path, must be opened. An open pressurizer manway vent of this size ensures that the capabilities of the vent exceed the pressure relieving requirements of the limiting RCS pressure transient. The level of reactor coolant in the RCS must be below the elevation of the pressurizer manway, which is opened for LTOP, to avoid draining reactor coolant from the RCS through the open manway.

Safety analyses (Ref. 3) demonstrate that the reactor vessel is adequately protected against exceeding the P/T limits during shutdown. Transients that are capable of overpressurizing the RCS have been identified and evaluated. Postulated transients include inadvertent safety injection actuation; energizing the pressurizer heaters; the charging control valve open; temporary loss of decay heat removal; and, reactor coolant thermal expansion caused by one reactor coolant pump (RCP) start causing heat transfer from hot steam generators.

The LTOP System is designed to protect the RCS from overpressurization resulting from any of the following conditions:

a. The starting of an idle RCP with the steam generator secondary water temperature of 138.9°C (250°F) higher than the RCS cold leg temperature; and
b. The inadvertent starting of four (4) safety injection pumps and one charging pump.

**SCS suction line relief valve Performance**

The two SCS suction line relief valves open when the RCS pressure increases to the relief valve opening setpoints for LTOP. When SCS suction line relief valves open during an increasing pressure transient, the release of coolant slows the rate of pressure increase and limits the peak RCS pressure to below the P/T limits.

**RCS Vent Performance**

With the RCS depressurized, a vent with at least the flow area of one SCS suction line relief valve is capable of mitigating the limiting increasing pressure transient. An RCS vent of this size will limit peak RCS pressure to below the P/T limits.

The RCS vent is passive and is not subject to active failure.

The LTOP System satisfies Criterion 2 of 10 CFR 50.36(c)(2)(ii).
Each of these methods of overpressure protection is capable of mitigating the limiting LTOP transient.

This LCO is applicable in MODE 4 with the temperature of any RCS cold leg less than or equal to the LTOP enable temperature specified in the PTLR, in MODE 5, and in MODE 6 with the reactor vessel head on. The LCO is not applicable for operating conditions above the specified temperatures because the pilot operated safety relief valves (POSRVs) are able to provide overpressure protection. With the vessel head off, there is no need for overpressure protection.

A.1 and B.1

With one SCS suction line relief valve inoperable, overpressure relieving capability is reduced. The other SCS suction line relief valve remains OPERABLE and one of these paths provides adequate overpressure protection. However, redundancy has been lost. The 7 day Completion Time in MODE 4 and 24 hour Completion Time in MODES 5 and 6 (per GL 90-06) (Ref. 4) reflect the need to restore redundancy and also take into consideration the other overpressure protection paths available in this condition.

C.1

If the Required Actions cannot be met within the associated Completion Times, the plant must be placed in a condition where an overpressure event cannot occur. This is done by depressurizing the RCS through the open alternate vent. The 8 hour Completion Time is reasonable based on the amount of time required to place the plant in this condition and the probability of an accident requiring the LTOP System during this relatively short period of time.

D.1

If both SCS suction line relief valves are inoperable, action must be initiated immediately to depressurize the RCS and establish an adequate open RCS vent flow path. The immediate Completion Time reflects the importance of establishing an adequate open vent flow path because an inadvertent or uncontrolled actuation of safety injection pumps or charging flow control valves could overpressurize the RCPB and SCS.
The SCS suction relief valves shall be demonstrated OPERABLE by verifying both SCS suction isolation valves in both SCS suction flow paths are open. This Surveillance is only performed if the two SCS suction relief valves are being used to satisfy this LCO.

The SCS suction isolation valves are verified to be open every 12 hours. The Frequency is considered adequate in view of other administrative controls such as valve status indications available to the operator in the control room that verify SCS suction isolation valves remain open. This Surveillance is modified by a Note that states it is only required to be met if the SCS suction line relief valves are being used to satisfy the pressure relief requirements of LCO 3.4.11.a.

The RCS vent with a flow area $\geq 180.6 \text{ cm}^2 (28 \text{ in}^2)$ must be verified open to protect the RCPB from overpressurization by providing adequate pressure relief capacity. The Frequency of 12 hours has been shown by operating experience to be sufficient to ensure the vent is maintained open. In view of other administrative controls such as valve status indications available to the operator in the control room, this Frequency ensures that inadvertent closure of the vent is unlikely.

This Surveillance is modified by a Note that states it is only required to be met if an RCS vent is being used to satisfy the pressure relief requirements of LCO 3.4.11.b.

The lift setting of each required SCS suction line relief valve must be verified to be within limits every 18 months. The lift setting for LTOP ensures that the SCS suction line relief valves will actuate at an appropriate RCS pressure by verifying the accuracy of the valve lift pressure is within the specified setting tolerance. The 18 month Frequency considers operating experience with equipment reliability and matches the typical refueling cycle.

This Surveillance is modified by a Note that states it is only required to be met if the SCS suction line relief valves are being used to satisfy the pressure relief requirements of LCO 3.4.11.a.
BANCES

REFERENCES

1. 10 CFR Part 50, Appendix G.


3. FSAR, Chapter 5.

B 3.4  REACTOR COOLANT SYSTEM (RCS)

B 3.4.12  RCS Operational LEAKAGE

BASES

BACKGROUND

Components that contain or transport the coolant to or from the reactor core make up the RCS. Component joints are made by welding, bolting, rolling, or pressure loading, and valves isolate connecting systems from the RCS.

During plant life, the joint and valve interfaces can produce varying amounts of reactor coolant LEAKAGE, through either normal operational wear or mechanical deterioration. The purpose of the RCS operational LEAKAGE LCO is to limit system operation in the presence of LEAKAGE from these sources to amounts that do not compromise safety. This LCO specifies the types and amounts of LEAKAGE.

GDC 30 (Ref. 1) requires means for detecting and, to the extent practical, identifying the source of reactor coolant LEAKAGE. Nuclear Regulatory Commission (NRC) Regulatory Guide (RG) 1.45 (Ref. 2) describes acceptable methods for selecting leakage detection systems.

The safety significance of RCS LEAKAGE varies widely depending on its source, rate, and duration. Therefore, detecting and monitoring reactor coolant LEAKAGE into the containment area is necessary. Quickly separating the identified LEAKAGE from the unidentified LEAKAGE is necessary to provide quantitative information to the operators, allowing them to take corrective action should a leak occur detrimental to the safety of the facility and the public.

A limited amount of LEAKAGE inside containment is expected from auxiliary systems that cannot be made 100% leak tight. Leakage from these systems should be detected, located, and isolated from the containment atmosphere, if possible, to not interfere with RCS leakage detection.

This LCO deals with protection of the reactor coolant pressure boundary (RCPB) from degradation and the core from inadequate cooling, in addition to preventing the accident analysis radiation release assumptions from being exceeded. The consequences of violating this LCO include the possibility of a loss of coolant accident (LOCA).

APPLICABLE SAFETY ANALYSES

Except for the primary to secondary LEAKAGE, the safety analyses do not address operational LEAKAGE. However, other operational LEAKAGE is related to the safety analyses for LOCA; the amount of LEAKAGE can affect the probability of such an event. The safety
BASES

APPLICABLE SAFETY ANALYSES (continued)

analysis for an event resulting in steam discharge to the atmosphere assumes a 2.27 L/min (0.6 gpm) primary to secondary LEAKAGE as the initial condition.

Primary to secondary LEAKAGE is a factor in the dose releases outside containment resulting from a main steam line break (MSLB). To a lesser extent, other accidents or transients involve secondary steam release to the atmosphere, such as a steam generator (SG) tube rupture (SGTR). The LEAKAGE contaminates the secondary fluid.

The FSAR (Ref. 3) analysis for SGTR assumes the contaminated secondary fluid is only briefly released via safety valves and the majority is steamed to condenser. The 2.27 L/min (0.6 gpm) primary to secondary LEAKAGE is relatively inconsequential.

The MSLB is more limiting for site radiation releases. The safety analysis for the MSLB assumes 1.13 L/min (0.3 gpm) through each steam generator for the first 30 minutes, and then the entire 2.27 L/min (0.6 gpm) primary to secondary LEAKAGE is through the affected generator as an initial condition. The dose consequences resulting from the MSLB are well within the limits defined in 10 CFR 50.34 (Ref. 4).

RCS operational LEAKAGE satisfies Criterion 2 of 10 CFR 50.36(c)(2)(ii).

LCO

RCS operational LEAKAGE shall be limited to:

a. **Pressure boundary LEAKAGE**

No pressure boundary LEAKAGE is allowed, being indicative of material deterioration. LEAKAGE of this type is unacceptable as the leak itself could cause further deterioration, resulting in higher LEAKAGE. Violation of this LCO could result in continued degradation of the RCPB. LEAKAGE past seals and gaskets is not pressure boundary LEAKAGE.

b. **Unidentified LEAKAGE**

1.89 L/min (0.5 gpm) of unidentified LEAKAGE is allowed as a reasonable minimum detectable amount that the containment air monitoring and containment sump level monitoring equipment can detect within a reasonable time period.

Violation of this LCO could result in continued degradation of the RCPB, if the LEAKAGE is from the pressure boundary.
c. Identified LEAKAGE

Up to 37.8 L/min (10 gpm) of identified LEAKAGE is considered allowable because LEAKAGE is from known sources which do not interfere with detection of unidentified LEAKAGE and is well within the capability of the RCS Makeup System. Identified LEAKAGE includes LEAKAGE to the containment from sources that are specifically known and located, but does not include pressure boundary LEAKAGE or controlled reactor coolant pump (RCP) seal leakoff (which is a normal function and is not considered LEAKAGE). Violation of this LCO could result in continued degradation of a component or system.

LCO 3.4.13, “RCS Pressure Isolation Valve (PIV) Leakage,” measures leakage through each individual PIV and can impact this LCO. Of the two PIVs in series in each PIV line, leakage measured through one PIV may not result in any RCS LEAKAGE if the other is leak tight. If both valves leak and result in a loss of mass from the RCS, the loss must be included in allowable Identified LEAKAGE.

d. Primary-to-Secondary LEAKAGE through Any One Steam Generator

The 0.39 L/min (150 gpd) limit on primary-to-secondary LEAKAGE through any one steam generator is based on allocating the total 0.79 L/min (0.2 gpm) allowed primary-to-secondary LEAKAGE equally between the two steam generators and operational LEAKAGE performance criterion in NEI 97-06, Steam Generator Program Guidelines (Ref. 5).

The Steam Generator Program operational LEAKAGE performance criterion in NEI 97-06 states, “The RCS operational primary to secondary leakage through any one SG shall be limited to 0.39 L/min (150 gpd).” The limit is based on operating experience with SG tube degradation mechanisms that result in tube leakage. The operational leakage rate criterion in conjunction with the implementation of the Steam Generator Program is an effective measure for minimizing the frequency of steam generator tube ruptures.
BASIS

ACTIONS

A.1

Unidentified LEAKAGE, identified LEAKAGE, or primary-to-secondary LEAKAGE in excess of the LCO limits must be reduced to within limits within 4 hours. This Completion Time allows time to verify LEAKAGE rates and either identify unidentified LEAKAGE or reduce LEAKAGE to within limits, before the reactor must be shut down. This action is necessary to prevent further deterioration of the RCPB.

B.1 and B.2

If any pressure boundary LEAKAGE exists or if unidentified, identified, or primary-to-secondary LEAKAGE cannot be reduced to within limits within 4 hours, the reactor must be brought to lower pressure conditions to reduce the severity of the LEAKAGE and its potential consequences. The reactor must be brought to MODE 3 within 6 hours and to MODE 5 within 36 hours. This action reduces the LEAKAGE and also reduces the factors which tend to degrade the pressure boundary.

The allowed Completion Times are reasonable based on operating experience, to reach the required conditions from full power conditions in an orderly manner and without challenging plant systems. In MODE 5, the pressure stresses acting on the RCPB are much lower and further deterioration is much less likely.

SURVEILLANCE REQUIREMENTS

SR 3.4.12.1

Verifying that RCS LEAKAGE is within the LCO limits ensures that the integrity of the RCPB is maintained. Pressure boundary LEAKAGE would at first appear as unidentified LEAKAGE and can only be positively identified by inspection. Unidentified LEAKAGE and identified LEAKAGE are determined by performance of an RCS water inventory balance.

The RCS water inventory balance must be performed with the reactor at steady state operating conditions and near operating pressure. The Surveillance is modified by two Notes. Note 1 states that this SR is not required to be performed until 12 hours after establishing steady state operation. The 12 hour allowance provides sufficient time to collect and process all necessary data after stable plant conditions are established.

Steady state operation is required to perform a proper water inventory balance since calculations during maneuvering are not useful. For RCS operational LEAKAGE determination by water inventory balance, steady state is defined as stable RCS pressure, temperature, power level, pressurizer and makeup tank level, makeup and letdown, and reactor coolant pump seal injection and return flows.
SURVEILLANCE REQUIREMENTS (continued)

An early warning of pressure boundary LEAKAGE or unidentified LEAKAGE is provided by the automatic systems that monitor the containment atmosphere radioactivity or containment sump level. These leakage detection systems are specified in LCO 3.4.14, “RCS Leakage Detection Instrumentation.”

Note 2 states that this SR is not applicable to primary to secondary LEAKAGE because LEAKAGE of 0.39 L/min (150 gpd) cannot be measured accurately by an RCS water inventory balance.

The 72 hour Frequency is a reasonable interval to trend LEAKAGE and recognizes the importance of early leak detection in the prevention of accidents.

SR 3.4.12.2

This SR verifies that primary to secondary LEAKAGE is \( \leq 0.39 \) L/min (150 gpd) through any one SG. Satisfying the primary to secondary LEAKAGE limit ensures that the operational LEAKAGE performance criterion in the Steam Generator Program is met. If this SR is not met, compliance with LCO 3.4.17, “Steam Generator Tube Integrity,” should be evaluated.

The 0.39 L/min (150 gpd) limit is measured at room temperature as described in Reference 6. The operational LEAKAGE rate limit applies to LEAKAGE through any one SG. If it is not practical to assign the leakage to an individual SG, all the primary to secondary LEAKAGE should be conservatively assumed to be from one SG.

The SR is modified by a Note which states that the Surveillance is not required to be performed until 12 hours after establishment of steady state operation. For RCS primary to secondary LEAKAGE determination, steady state is defined as stable RCS pressure, temperature, power level, pressurizer and makeup tank levels, makeup and letdown, and RCP seal injection and return flows.

The 72 hour Frequency is a reasonable interval to trend primary to secondary LEAKAGE and recognizes the importance of early leakage detection in the prevention of accidents. The primary-to-secondary LEAKAGE is determined using continuous process radiation monitors or radiochemical grab sampling in accordance with the EPRI guidelines (Ref. 6).
REFERENCES

1. 10 CFR Part 50, Appendix A, GDC 30.
3. FSAR, Subsection 15.6.3.
4. 10 CFR 50.34.
5. NEI 97-06, “Steam Generator Program Guidelines.”
B 3.4 REACTOR COOLANT SYSTEM (RCS)

B 3.4.13 RCS Pressure Isolation Valve (PIV) Leakage

BASES

BACKGROUND

10 CFR 50.2, 10 CFR 50.55a(c), and GDC 55 of 10 CFR Part 50, Appendix A (Refs. 1, 2, and 3), define RCS PIVs as any two normally closed valves in series within the RCS pressure boundary that separate the high pressure RCS from an attached low pressure system. During their lives, these valves can produce varying amounts of reactor coolant LEAKAGE through either normal operational wear or mechanical deterioration. The RCS PIV LCO allows RCS high pressure operation when leakage through these valves exists in amounts that do not compromise safety.

The PIV leakage limit applies to each individual valve. Leakage through both PIVs in series in a line must be included as part of the identified LEAKAGE, governed by LCO 3.4.12, “RCS Operational LEAKAGE.” This is true during operation only when the loss of RCS mass through two valves in series is determined by an RCS water inventory balance (SR 3.4.12.1). A known component of the identified LEAKAGE before operation begins is the least of the two individual leakage rates determined for leaking series PIVs during the required surveillance testing; leakage measured through one PIV in a line is not RCS operational LEAKAGE if the other is leak tight.

Although this specification provides a limit on the allowable PIV leakage rate, its main purpose is to prevent overpressure failure of the low pressure portions of connecting systems. The leakage limit is an indication that the PIVs between the RCS and connecting systems are degraded or becoming degraded. PIV leakage could lead to overpressure of the low pressure piping or components. Failure consequences could be a loss of coolant accident (LOCA) outside of containment, an unanalyzed condition that could degrade the ability for low pressure injection.

The basis for this LCO is the NRC “Reactor Safety Study,” WASH-1400 (Ref. 4), which identified potential intersystem LOCAs as a significant contributor to the risk of core melt. A subsequent study (Ref. 5) evaluated various PIV configurations to determine the probability of intersystem LOCAs.

PIVs are provided to isolate the RCS from the following typically connected systems:

a. Shutdown Cooling System (SCS) and
b. Safety Injection System (SIS).

Violation of this LCO could result in continued degradation of a PIV, which could lead to overpressurization of a low pressure system and the loss of the integrity of a fission product barrier.

Reference 4 identified potential intersystem LOCAs as a significant contributor to the risk of core melt. The dominant accident sequence in the intersystem LOCA category is the failure of the low pressure portion of the Shutdown Cooling System outside of containment. The accident is the result of a postulated failure of the PIVs, which are part of the reactor coolant pressure boundary (RCPB), and the subsequent pressurization of the Shutdown Cooling System downstream of the PIVs from the RCS. Because the low pressure portion of the Shutdown Cooling System is typically designed for 63.2 kg/cm²G (900 psig), overpressurization failure of the shutdown cooling low pressure line would result in a LOCA outside containment and subsequent risk of core melt.

Reference 5 evaluated various PIV configurations, leakage testing of the valves, and operational changes to determine the effect on the probability of intersystem LOCAs. This study concluded that periodic leakage testing of the PIVs can substantially reduce the probability of an intersystem LOCA.

RCS PIV leakage satisfies Criterion 2 of 10 CFR 50.36(c)(2)(ii).

RCS PIV leakage is identified LEAKAGE into closed systems connected to the RCS. PIV leakage is usually on the order of drops per minute. Leakage that increases significantly suggests that something is operationally wrong and corrective action must be taken.

The LCO PIV leakage limit is 1.89 L/min (0.5 gpm) per nominal 2.54 cm (1 in) of valve size, with a maximum limit of 18.9 L/min (5 gpm). The previous criterion of 3.78 L/min (1 gpm) for all valve sizes imposed an unjustified penalty on the larger valves without providing information on potential valve degradation and resulted in higher personnel radiation exposures. A study concluded a leakage rate limit based on valve size was superior to a single allowable value.
Bases

LCO (continued)

Reference 6 permits leakage testing at a lower pressure differential than between the specified maximum RCS pressure and the normal pressure of the connected system during RCS operation (the maximum pressure differential) in those types of valves in which the higher service pressure will tend to diminish the overall leakage channel opening. In such cases, the observed rate may be adjusted to the maximum pressure differential by assuming leakage is directly proportional to the pressure differential to the one-half power.

Applicability

In MODES 1, 2, 3, and 4, this LCO applies because the potential for PIV leakage is greatest when the RCS is pressurized. In MODE 4, valves in the shutdown cooling flow path are not required to meet the requirements of this LCO when in, or during the transition to or from, the shutdown cooling MODE of operation.

In MODES 5 and 6, leakage limits are not provided because the RCS pressure is far lower resulting in a reduced potential for leakage and a lower potential for LOCA outside the containment.

Actions

The ACTIONS are modified by two Notes. Note 1 is added to provide clarification that each flow path allows separate entry into a Condition. This is allowed based on the functional independence of the flow path. Note 2 requires an evaluation of affected systems if a PIV is inoperable. The leakage could affect system OPERABILITY or isolation of a leaking flow path with an alternate valve could degrade the ability of the interconnected system to perform its safety function.

A.1 and A.2

The flow path must be isolated by two valves. Required Actions A.1 and A.2 are modified by a Note stating that the valves used for isolation must meet the same leakage requirements as the PIVs and must be in the RCPB.

Required Action A.1 requires that the isolation with one valve must be performed within 4 hours. Four hours provides time to reduce leakage in excess of the allowable limit and to isolate if leakage cannot be reduced. The 4 hours allows the Actions and restricts the operation with leaking isolation valves.
BASES

ACTIONS (continued)

The 72 hour Completion Time after exceeding the limit allows for the restoration of the leaking PIV to OPERABLE status. This time frame considers the time required to complete this Action and the low probability of a second valve failing during this period.

B.1 and B.2

If leakage cannot be reduced, the system isolated or other Required Actions accomplished, the plant must be brought to a MODE in which the LCO does not apply. To achieve this status, the plant must be brought to MODE 3 within 6 hours and MODE 5 within 36 hours. This Action could reduce the leakage and also reduces the potential for a LOCA outside the containment. The allowed Completion Times are reasonable, based on operating experience, to reach the required plant conditions from full power conditions in an orderly manner and without challenging plant systems.

C.1

The inoperability of the SCS open permissive interlock renders the shutdown cooling (SC) suction isolation valves incapable of isolating in response to a high pressure condition and preventing inadvertent opening of the valves at RCS pressure in excess of SCS design pressure. If the SCS open permissive interlock is inoperable, RCS pressure shall be depressurized below open permissive setpoint within 4 hours.

SURVEILLANCE REQUIREMENTS

SR 3.4.13.1

Performance of leakage testing on each RCS PIV or isolation valve used to satisfy Required Action A.1 or A.2 is required to verify that leakage is below the specified limit and to identify each leaking valve. The leakage limit of 1.89 L/min (0.5 gpm) per 2.54 cm (1 in) of nominal valve diameter up to 18.9 L/min (5 gpm) maximum applies to each valve. Leakage testing requires a stable pressure condition.

For the two PIVs in series, the leakage requirement applies to each valve individually and not to the combined leakage across both valves. If the PIVs are not individually leakage tested, one valve could fail completely and not be detected if the other valve in series meets the leakage requirement. In this situation, the protection provided by redundant valves would be lost.

Testing is to be performed every 9 months, but may be extended up to a maximum of 18 months, if the plant does not go into MODE 5 for at least
BASES

SURVEILLANCE REQUIREMENTS (continued)

72 hours. The 18 month Frequency is consistent with 10 CFR 50.55a (f) (Ref. 7), as contained in the in-service testing program, is within Frequency allowed by the ASME Operations and Maintenance Code (Ref. 6), and is based on the need to perform the Surveillance under conditions that apply during a plant outage and the potential for an unplanned transient if the Surveillance were performed with the reactor at power.

In addition, testing must be performed once after the valve has been opened by flow or exercised to ensure tight reseating. PIVs disturbed in the performance of this Surveillance should also be tested unless documentation shows that an infinite testing loop cannot practically be avoided. Testing must be performed within 24 hours after the valve has been reseated. Within 24 hours is a reasonable and practical time limit for performing this test after opening or reseating a valve. Prior to returning the valve to service following maintenance, repair, or replacement work on the valve, the leak testing should be performed and the valve integrity should be verified.

The leakage limit is to be met at the RCS pressure associated with MODES 1 and 2. This permits leakage testing at high differential pressures with stable conditions not possible in the MODES with lower pressures.

Entry into MODES 3 and 4 is allowed to establish the necessary differential pressures and stable conditions to allow for performance of this Surveillance. Note 1 that allows this provision is complementary to the Frequency of prior to entry into MODE 2 whenever the unit has been in MODE 5 for 72 hours or more, if leakage testing has not been performed in the previous 9 months. In addition, this Surveillance is not required to be performed on the Shutdown Cooling System by Note 2 when the Shutdown Cooling System is aligned to the RCS in the shutdown cooling MODE of operation. PIVs contained in the shutdown cooling flow path must be leakage rate tested after Shutdown Cooling System is secured and stable unit conditions and the necessary differential pressures are established.

Note 3 states that RCS PIVs actuated during the performance of this Surveillance are not required to be tested more than once if a repetitive testing loop cannot be avoided.
SURVEILLANCE REQUIREMENTS (continued)

SR 3.4.13.2

The interlock setpoint that prevents the valves from being opened is set so the actual RCS pressure must be $< 31.6$ kg/cm$^2$A (450 psia) to open the valves. This setpoint ensures that the Shutdown Cooling System design pressure will not be exceeded and the SCS relief valves will not lift.

The 18 month Frequency is based on the need to perform these Surveillances under conditions that apply during a plant outage. The 18 month Frequency is also acceptable based on consideration of the design reliability and confirming operation experience of the equipment.

The SR is modified by a Note allowing this SR to not be met when the SCS suction isolation valves all opened for low temperature overpressure protection (LTOP) in accordance with LCO 3.4.11.a.

REFERENCES

1. 10 CFR 50.2.
2. 10 CFR 50.55a(c).
3. 10 CFR Part 50, Appendix A, Section V, GDC 55.
4. WASH-1400 (NUREG-75/014), Appendix V, October 1975.
5. NUREG-0677, May 1980.
7. 10 CFR 50.55a(f).
B 3.4 REACTOR COOLANT SYSTEM (RCS)

B 3.4.14 RCS Leakage Detection Instrumentation

BASES

BACKGROUND

GDC 30 of Appendix A to 10 CFR Part 50 (Ref. 1) requires means for detecting and, to the extent practical, identifying the location of the source of RCS leakage. Nuclear Regulatory Commission (NRC) Regulatory Guide (RG) 1.45 (Ref. 2) describes acceptable methods for selecting leakage detection systems.

Leakage detection systems must have the capability to detect significant reactor coolant pressure boundary (RCPB) degradation as soon after occurrence as practical to minimize the potential for propagation to a gross failure. Thus, an early indication or warning signal is necessary to permit proper evaluation of all unidentified leakage. In addition, to meet the OPERABLE requirements, the monitors are typically set to provide the most sensitive response without causing an excessive number of spurious alarms.

The containment sump (level) monitor used to detect unidentified leakage and the containment atmosphere humidity monitor are instrumented to alarm for increases above the normal rates.

The reactor coolant contains radioactivity that, when released to the containment, can be detected by radiation monitoring instrumentation. Radioactivity detection systems are included for monitoring the particulate activity, because of its sensitivities and rapid responses to RCS leakage.

Other indications may be used to detect an increase in unidentified leakage. An increase in humidity of the containment atmosphere would indicate release of water vapor to the containment. Dew point temperature measurements can thus be used to monitor humidity levels of the containment atmosphere as an indicator of potential RCS leakage.

Since the humidity level is influenced by several factors, a quantitative evaluation of an indicated leakage rate by this means could be questionable and should be compared to observed increases in liquid flow into or from the containment sump.

Humidity level monitoring is considered most useful as an indirect alarm or indication to alert the operator to a potential problem.
BASES

BACKGROUND (continued)

Air temperature and pressure monitoring methods may also be used to infer unidentified leakage to the containment. Containment temperature and pressure fluctuate slightly during plant operation, but a rise above the normally indicated range of values could indicate RCS leakage into the containment. The relevance of temperature and pressure measurements is affected by containment free volume and, for temperature, detector location. Alarm signals from these instruments can be valuable in recognizing rapid and sizable leakage to the containment. Temperature and pressure monitors are not required by this LCO.

The above mentioned leakage detection methods or systems differ in sensitivity and response time. Some of these systems could serve as early alarm systems signaling the operators that closer examination of other detection systems is necessary to determine the extent of any corrective action that could be required.

APPLICABLE SAFETY ANALYSES

The need to evaluate the severity of an alarm or an indication is important to the operators, and the ability to compare and verify the indications from other systems is necessary.

The safety significance of RCS leakage varies widely depending on its source, rate, and duration. Therefore, detecting and monitoring of RCS leakage into the containment area is necessary. Quickly separating the identified leakage from the unidentified leakage provides quantitative information to the operators, allowing them to take corrective action should leakage occur detrimental to the safety of the facility and the public.

RCS leakage detection instrumentation satisfies Criterion 1 of 10 CFR 50.36(c)(2)(ii).

LCO

This LCO requires instruments of diverse monitoring principles to be OPERABLE to provide confidence that small amounts of unidentified leakage are detected in time to allow actions to place the plant in a safe condition when RCS leakage indicates possible RCPB degradation.

The LCO requires three instruments to be OPERABLE.

The containment sump is used to collect unidentified leakage. The containment sump consists of the normal sump and in-core instrumentation (ICI) cavity sump. The LCO requirements apply to the total amount of unidentified leakage collected in the both sumps. The
monitor on the measuring tube inside the containment sump detects the leakage level or the operating frequency of discharge in the measuring tube inside containment sump. The measuring tube is instrumented to detect when there is leakage of an increase above the normal value by 1.89 L/min (0.5 gpm). The identification of an increase in unidentified leakage will be delayed by the time required for the unidentified leakage to travel to the containment sump and it could take longer than 1 hour to detect a 1.89 L/min (0.5 gpm) increase in unidentified leakage, depending on the origin and magnitude of the leakage. This sensitivity is acceptable for containment sump (level) monitor OPERABILITY.

The reactor coolant contains radioactivity that, when released to the containment, can be detected by the containment atmosphere radioactivity (particulate) monitor. Radioactivity detection systems are included for monitoring particulate activities because of its sensitivities and rapid responses to RCS leakage, but have recognized limitations. The reactor coolant radioactivity level will be low during initial reactor startup and for a few weeks thereafter, until activated corrosion products have been formed and fission products appear from fuel element cladding contamination or cladding defects.

If there are few fuel element cladding defects and low levels of activation products, it may not be possible for the containment atmosphere radioactivity (particulate) monitor to detect a 1.89 L/min (0.5 gpm) increase within 1 hour during normal operation. However, the containment atmosphere radioactivity (particulate) monitor is OPERABLE when it is capable of detecting a 1.89 L/min (0.5 gpm) increase in unidentified leakage within 1 hour given an RCS activity equivalent to that assumed in the design calculations for the monitors (Ref. 3).

Humidity monitor can detect the increased vapor content of the containment air and a sudden and significant increase of humidity level is indicative of reactor coolant leakage. Several factors such as containment temperature, containment air volume, leak location, etc., influence the humidity level. This makes the humidity measurement difficult to use in a quantitative evaluation of an indicated leakage rate, and thus its usefulness may be questionable. Therefore humidity monitoring that detects a sudden and significant increase of humidity level can be best suited to alert the operator about a potential reactor coolant leakage.

The LCO is satisfied when monitors of diverse measurement means are available. Thus, the combination of containment sump (level) monitors, in combination with a particulate radioactivity monitor and humidity monitors provides an acceptable minimum.
BASES

APPLICABILITY

Because of elevated RCS temperature and pressure in MODES 1, 2, 3, and 4, RCS leakage detection instrumentation is required to be OPERABLE.

In MODES 5 or 6, the temperature is $\leq 98.9^\circ$C (210°F) and pressure is maintained low or at atmospheric pressure. Since the temperatures and pressures are far lower than those for MODES 1, 2, 3, and 4, the likelihood of leakage and crack propagation is much smaller. Therefore, the requirements of this LCO are not applicable in MODES 5 and 6.

ACTIONS

A.1 and A.2

With the required containment sump (level) monitor inoperable, no other form of sampling can provide the equivalent information.

However, the containment atmosphere radioactivity (particulate) monitor will provide indications of changes in leakage. Together with the containment atmosphere radioactivity (particulate) monitor, the periodic surveillance for the RCS water inventory balance, SR 3.4.12.1, must be performed at an increased Frequency of 24 hours to provide information that is adequate to detect leakage. A Note is added allowing that SR 3.4.12.1 is not required to be performed until 12 hours after establishing steady state operation (stable temperature, power level, pressurizer and makeup tank levels, makeup and letdown, and RCP seal injection and return flows). The 12 hour allowance provides sufficient time to collect and process all necessary data after stable plant conditions are established.

Restoration of the required containment sump (level) monitor to OPERABLE status within a Completion Time of 30 days is required to regain the function after the monitor’s failure. This time is acceptable considering the frequency and adequacy of the RCS water inventory balance required by Required Action A.1.

B.1.1, B.1.2, and B.2

With the containment atmosphere radioactivity (particulate) monitoring instrumentation channel inoperable, alternative action is required. Either grab samples of the containment atmosphere must be taken and analyzed or water inventory balances, in accordance with SR 3.4.12.1, must be performed to provide alternate periodic information.

With a sample obtained and analyzed or water inventory balance performed every 24 hours, the reactor may be operated for up to 30 days to allow restoration of the required containment atmosphere radioactivity (particulate) monitors.
The 24 hour interval provides periodic information that is adequate to detect leakage. A Note is added allowing that SR 3.4.12.1 is not required to be performed until 12 hours after establishing steady state operation (stable temperature, power level, pressurizer and makeup tank levels, makeup and letdown, and RCP seal injection and return flows). The 12 hour allowance provides sufficient time to collect and process all necessary data after stable plant conditions are established. The 30 day Completion Time recognizes at least one other form of leakage detection is available.

C.1.1, C.1.2 and C.2

With the containment atmosphere humidity monitor inoperable, alternative action is again required. Either SR 3.4.14.1 must be performed or water inventory balance, in accordance with SR 3.4.12.1, must be performed to provide alternate periodic information. Provided a CHANNEL CHECK is performed every 8 hours, or a water inventory balances is performed every 24 hours, reactor operation may continue while awaiting restoration of the containment atmosphere humidity monitor to OPERABLE status. The 24 hour interval provides periodic information that is adequate to detect RCS leakage.

A Note is added allowing that SR 3.4.12.1 is not required to be performed until 12 hours after establishing steady state operation (stable temperature, power level, pressurizer and makeup tank levels, makeup and letdown, and RCP seal injection and return flows.) The 12 hour allowance provides sufficient time to collect and process all necessary data after stable plant conditions are established. The 30 day Completion Time recognizes at least one other form of leakage detection is available.

D.1 and D.2

With the required containment sump (level) monitor and the containment atmosphere humidity monitor inoperable, the only means of detecting LEAKAGE is the required containment atmosphere radioactivity (particulate) monitor. This condition is applicable when the only OPERABLE monitor is the containment atmosphere radioactivity (particulate) monitor. This configuration does not provide the required diverse means of leakage detection. The Required Action provides 30 days to restore another RCS leakage monitor to OPERABLE status to regain the intended leakage detection diversity. The 30 day Completion Time ensures that the plant will not be operated in a degraded configuration for a lengthy time period.
E.1 and E.2

With the required containment atmosphere radioactivity (particulate) monitor and the containment atmosphere humidity monitor inoperable, the only means of detecting leakage is the containment sump (level) monitor. This condition is applicable when the only OPERABLE monitor is the containment sump (level) monitor.

This condition does not provide the required diverse means of leakage detection. The Required Action is to restore either of the inoperable required monitors to OPERABLE status within 30 days to regain the intended leakage detection diversity. The 30 day Completion Time ensures that the plant will not be operated in a reduced configuration for a lengthy time period.

F.1 and F.2

With the required containment sump (level) monitor and the containment atmosphere radioactivity (particulate) monitor inoperable, the only means of detecting leakage is the containment atmosphere humidity monitor. This condition is applicable when the only OPERABLE monitor is the containment atmosphere humidity monitor. This condition does not provide the required diverse means of leakage detection. The Required Action is to restore either of the inoperable required monitors to OPERABLE status within 7 days to regain the intended leakage detection diversity. The 7 day Completion Time ensures that the plant will not be operated in a degraded configuration for a lengthy time period.

G.1 and G.2

If a Required Action of Condition A, B, C, D or E cannot be met, the plant must be brought to a MODE in which the requirement does not apply. To achieve this status, the plant must be brought to at least MODE 3 within 6 hours and to MODE 5 within 36 hours. The allowed Completion Times are reasonable, based on operating experience, to reach the required plant conditions from full power conditions in an orderly manner and without challenging plant systems.

H.1

If all required monitors inoperable, no automatic means of monitoring leakage are available, and immediate plant shutdown in accordance with LCO 3.0.3 is required.
SURVEILLANCE REQUIREMENTS

SR 3.4.14.1

SR 3.4.14.1 requires the performance of a CHANNEL CHECK of the required containment atmosphere radioactivity (particulate) monitors. The check gives reasonable confidence that the channel is operating properly. The Frequency of 12 hours is based on instrument reliability and is reasonable for detecting off normal conditions.

If only one radioactivity particulate monitor channel is required, surveillance of one radioactivity particulate monitor channel is performed by using a radioactive check source. The radioactive check source is generally built into the detector assembly and can be remotely activated by the operator. The radioactive check source is primarily used to check whether a particular radiation monitoring channel loop is live or functioning. When a check source is exposed to the detector on demand, if upscale measurement is indicated, the channel is assessed with channel live status by pass/fail criteria. The criteria are qualitative assessment, by observation, of channel behavior during operation.

SR 3.4.14.2

SR 3.4.14.2 requires the performance of a CHANNEL CHECK of the required containment atmosphere humidity monitors. The check gives reasonable confidence that the channel is operating properly. The Frequency of 12 hours is based on instrument reliability and is reasonable for detecting off normal conditions.

SR 3.4.14.3

SR 3.4.14.3 requires the performance of a CHANNEL FUNCTIONAL TEST on the required containment atmosphere radioactivity (particulate) monitor. The test ensures that the monitor can perform its function in the desired manner. A successful test of the required contact(s) of a channel relay may be performed by the verification of the change of state of a single contact of the relay. This clarifies what is an acceptable CHANNEL FUNCTIONAL TEST of a relay. This is acceptable because all of the other required contacts of the relay are verified by other Technical Specifications (TS) and non-TS tests at least once per refueling interval with applicable extensions. The test verifies the alarm setpoint and relative accuracy of the instrument string. The Frequency of 31 days considers instrument reliability, and operating experience has shown that it is adequate for detecting degradation.
SR 3.4.14.4

SR 3.4.14.4 requires the performance of a CHANNEL FUNCTIONAL TEST on the required containment atmosphere humidity monitor. The test ensures that the monitor can perform its function in the desired manner. A successful test of the required contact(s) of a channel relay may be performed by the verification of the change of state of a single contact of the relay. This clarifies what is an acceptable CHANNEL FUNCTIONAL TEST of a relay. This is acceptable because all of the other required contacts of the relay are verified by other Technical Specifications (TS) and non-TS tests at least once per refueling interval with applicable extensions. The test verifies the alarm setpoint and relative accuracy of the instrument string. The Frequency of 31 days considers instrument reliability, and operating experience has shown that it is adequate for detecting degradation.


These SRs require the performance of a CHANNEL CALIBRATION for each of the RCS leakage detection instrumentation channels. The calibration verifies the accuracy of the instrument string, including the instruments located inside containment. The 18 month Frequency is a typical refueling cycle and considers channel reliability. Again, operating experience has proven that this Frequency is acceptable.

REFERENCES

1. 10 CFR Part 50, Appendix A, Section IV, GDC 30.
3. FSAR, Chapter 5.
B 3.4 REACTOR COOLANT SYSTEM (RCS)

B 3.4.15 RCS Specific Activity

BASES

BACKGROUND
The maximum dose that an individual at the exclusion area boundary can receive for 2 hours following an accident, or at low population zone outer boundary for the radiological release duration, is specified in 10 CFR 50.34 (Ref. 1). Doses to main control room (MCR) operators must be limited per GDC 19. The limits on specific activity ensure that the offsite and MCR doses are appropriately limited during analyzed transients and accidents.

The RCS specific activity LCO limits the allowable concentration level of radionuclides in the reactor coolant. The LCO limits are established to minimize the dose consequences in the event of a main steam line break (MSLB) or a steam generator tube rupture (SGTR).

The LCO contains specific activity limits for both DOSE EQUIVALENT I-131 and DOSE EQUIVALENT XE-133. The allowable levels are intended to ensure that offsite and MCR doses meet the appropriate acceptance criteria in the Standard Review Plan (Ref. 2).

APPLICABLE SAFETY ANALYSES
The LCO limits on the specific activity of the reactor coolant ensure that the resulting offsite and MCR doses meet the appropriate SRP acceptance criteria following a MSLB or an SGTR. The safety analyses (Refs. 3 and 4) assume the specific activity of the reactor coolant is at the LCO limits, and an existing reactor coolant steam generator (SG) tube leakage rate of 2.27 L/min (0.6 gpm) exists. The safety analyses assume the specific activity of the secondary coolant is at its limit of 3.70E3 Bq/g (0.1 µCi/g) DOSE EQUIVALENT I-131 from LCO 3.7.17, "Secondary Specific Activity."

The analyses for the MSLB and SGTR accidents establish the acceptance limits for RCS specific activity. Reference to these analyses is used to assess changes to the unit that could affect RCS specific activity, as they relate to the acceptance limits.

The safety analyses consider two cases of reactor coolant iodine specific activity. One case assumes specific activity at 3.70E4 Bq/g (1.0 µCi/g) DOSE EQUIVALENT I-131 with a concurrent large iodine spike that increases the rate of release of iodine from the fuel rods containing cladding defects to the primary coolant immediately after a MSLB (by a factor of 500), or SGTR (by a factor of 335), respectively. The second
case assumes the initial reactor coolant iodine activity at 2.22E6 Bq/g (60 µCi/g) DOSE EQUIVALENT I-131 because of an iodine spike caused by a reactor or an RCS transient prior to the accident. In both cases, the noble gas specific activity is assumed to be 1.11E7 Bq/g (300 µCi/g) DOSE EQUIVALENT XE-133.

The SGTR analysis assumes a rise in pressure in the ruptured SG causes radioactively contaminated steam to discharge to the atmosphere through the atmospheric dump valves or the main steam safety valves. The atmospheric discharge stops when the turbine bypass to the condenser removes the excess energy to rapidly reduce the RCS pressure and close the valves. The unaffected SG removes core decay heat by venting steam until the cooldown ends and the Shutdown Cooling System (SCS) is placed in service.

The MSLB radiological analysis assumes that offsite power is lost at the same time as the pipe break occurs outside containment. The affected SG blows down completely and steam is vented directly to the atmosphere. The unaffected SG removes core decay heat by venting steam to the atmosphere until the cooldown ends and the SC System is placed in service.

Operation with iodine specific activity levels greater than the LCO limit is permissible, if the activity levels do not exceed 2.22E6 Bq/g (60 µCi/g) for more than 48 hours.

The limits on RCS specific activity are also used for establishing standardization in radiation shielding and plant personnel radiation protection practices.

RCS specific activity satisfies Criterion 2 of 10 CFR 50.36(c)(2)(ii).

LCO

The iodine specific activity in the reactor coolant is limited to 3.70E4 Bq/g (1.0 µCi/g) DOSE EQUIVALENT I-131, and the noble gas specific activity in the reactor coolant is limited to 1.11E7 Bq/g (300 µCi/g) DOSE EQUIVALENT XE-133. The limits on specific activity ensure that offsite and MCR doses will meet the appropriate SRP acceptance criteria (Ref. 2).

The MSLB and SGTR analyses (Refs. 3 and 4) show that the calculated doses are within acceptable limits. Violation of the LCO could result in reactor coolant radioactivity levels that could, in the event of a MSLB or SGTR, lead to doses that exceed the SRP acceptance criteria (Ref. 2).
Bases

Appliability

In_modes_1, 2, 3 and 4, operation within the LCO limits for dose equivalent I-131 and dose equivalent Xe-133 is necessary to limit the potential consequences of a MSLB or SGTR to within the SRP acceptance criteria (Ref. 2).

In Modes 5 and 6, the steam generators are not being used for decay heat removal, the RCS and steam generators are depressurized, and primary to secondary leakage is minimal. Therefore, the monitoring of RCS specific activity is not required.

Actions

A.1 and A.2

With the dose equivalent I-131 greater than the LCO limit, samples at intervals of 4 hours must be taken to demonstrate that the specific activity is $\leq 2.22 \times 10^6$ Bq/g (60 µCi/g). The completion time of 4 hours is required to obtain and analyze a sample. Sampling is continued every 4 hours to provide a trend.

The dose equivalent I-131 must be restored to within limit within 48 hours.

The completion time of 48 hours is acceptable since it is expected that, if there were an iodine spike, the normal coolant iodine concentration would be restored within this time period. Also, there is a low probability of an event which is limiting due to exceeding this limit, and the ability to restore transient specific activity excursions while the plant remains at, or proceeds to, power operation.

A Note excludes the mode change restriction of LCO 3.0.4. This exception allows entry into the applicable mode(s), relying on required actions A.1 and A.2 while the dose equivalent I-131 LCO limit is not met. This exception is acceptable due to the significant conservatism incorporated into the specific activity limit, the low probability of an event which is limiting due to exceeding this limit, and the ability to restore transient specific activity excursions while the plant remains at, or proceeds to, power operation.

B.1

With the dose equivalent Xe-133 greater than the LCO limit, dose equivalent Xe-133 must be restored to within limit within 48 hours. The allowed completion time of 48 hours is acceptable since it is expected that, if there were a noble gas spike, the normal coolant noble gas concentration would be restored within this time period. Also, there is a low probability of a MSLB or SGTR occurring during this time period.
Bases

Actions (continued)

A Note excludes the MODE change restriction of LCO 3.0.4. This exception allows entry into the applicable MODE(S), relying on Required Actions B.1 while the DOSE EQUIVALENT XE-133 LCO limit is not met. This exception is acceptable due to the significant conservatism incorporated into the specific activity limit, the low probability of an event which is limiting due to exceeding this limit, and the ability to restore transient specific activity excursions while the plant remains at, or proceeds to, power operation.

C.1 and C.2

If the Required Action and the associated Completion Time of Condition A or B is not met, or if the DOSE EQUIVALENT I-131 is > 2.22E6 Bq/g (60 µCi/g), the reactor must be brought to MODE 3 within 6 hours and MODE 5 within 36 hours. The allowed Completion Time is reasonable, based on operating experience, to reach the required plant conditions from full power conditions in an orderly manner and without challenging plant systems.

Surveillance Requirements

SR 3.4.15.1

SR 3.4.15.1 requires performing a gamma isotopic analysis as a measure of the noble gas specific activity of the reactor coolant at least once every 7 days. This measurement is the sum of the degassed gamma activities and the gaseous gamma activities in the sample taken. This Surveillance provides an indication of any increase in the noble gas specific activity.

Trending the results of this Surveillance allows proper remedial action to be taken before reaching the LCO limit under normal operating conditions. The 7 day Frequency considers the low probability of a gross fuel failure during the time.

Due to the inherent difficulty in detecting Kr-85 in a reactor coolant sample due to masking from radioisotopes with similar decay energies, such as F-18 and I-134, it is acceptable to include the minimum detectable activity for Kr-85 in the SR 3.4.15.1 calculation. If a specific noble gas nuclide listed in the definition of DOSE EQUIVALENT XE-133 is not detected, it should be assumed to be present at the minimum detectable activity.

A Note modifies the SR to allow entry into and operation in MODE 4, MODE 3, and MODE 2 prior to performing the SR. This allows the Surveillance to be performed in those MODES, prior to entering MODE 1.
SURVEILLANCE REQUIREMENTS (continued)

SR 3.4.15.2

This Surveillance is performed to ensure iodine specific activity remains within the LCO limit during normal operation and following fast power changes when iodine spiking is more apt to occur. The 14 day Frequency is adequate to trend changes in the iodine activity level, considering noble gas activity is monitored every 7 days. The Frequency, between 2 and 6 hours after a power change ≥ 15% RTP within a 1 hour period, is established because the iodine levels peak during this time following iodine spike initiation; samples at other times would provide inaccurate results.

The Notes modifies this SR to allow entry into and operation in MODE 4, MODE 3, and MODE 2 prior to performing the SR. This allows the Surveillance to be performed in those MODES, prior to entering MODE 1.

REFERENCES

1. 10 CFR 50.34.
2. NUREG-0800, Section 15.0.3, March 2007.
3. FSAR, Subsection 15.1.5.
4. FSAR, Subsection 15.6.3.
B 3.4 REACTOR COOLANT SYSTEM (RCS)

B 3.4.16 Reactor Coolant Gas Vent (RCGV) Function

BASES

BACKGROUND

The reactor coolant gas vent (RCGV) function is to provide a safety grade means of venting non-condensible gases and steam from the pressurizer and the reactor vessel closure head. The RCGV function is designed to be used during all design bases events for RCS pressure control purposes when Main Spray and Auxiliary Spray Systems are unavailable. The OPERABILITY of at least one RCGV path from the pressurizer and at least one RCGV path from the reactor vessel closure head to the IRWST ensures that this function can be performed.

The RCGV function is a manually operated safety grade system. It removes non-condensible gases or steam from the pressurizer and the reactor vessel closure head through vent lines to the in-containment refueling water storage tank (IRWST). Each vent line has two pairs of parallel isolation valves which are closed during normal operation. During shutdown or transient conditions, if the operator judges that non-condensible gases are collected in the pressurizer or in the reactor vessel closure head, the operator vents the gases by manually opening the RCGV valves from the main control room (MCR) according to operating procedures. The RCGV function will have the capability to be manually actuated, monitored, and controlled from the MCR as required by GDC 19.

The two isolation valves in each parallel vent flow path are normally powered from the 125 Vdc buses and emergency power is provided to the valves by batteries. The RCGV System is designed to maintain a vent flow path after a single failure of any single valve or its power source. This design feature satisfies the requirements of GDC 17 and GDC 34.

APPLICABLE SAFETY ANALYSES

The RCGV function provides a safety grade method of RCS depressurization that is credited during natural circulation. The operator uses the Safety Injection System, the pressurizer backup heaters, and the RCGV function to control RCS inventory and saturation margin. The pressurizer vent line is 5.0 cm (2.0 in) nominal diameter to meet the requirement to vent one-half the RCS volume in one hour.

The reactor vessel vent line is a 1.9 cm (3/4 in) line which expands to 2.54 cm (1 in) through the valving. This provides adequate venting to remove steam and non-condensible gases from the reactor vessel closure head.

The RCGV function satisfies Criterion 3 of 10 CFR 50.36(c)(2)(ii).
LCO

The purpose of the LCO is to ensure the core cooldown and RCS depressurization can be established using natural circulation venting non-condensible gases from the reactor vessel upper closure head and the pressurizer steam space at post-accident conditions. The RCGV function is OPERABLE when a vent path can be established from the pressurizer steam space and from the reactor vessel closure head to the IRWST. The valves are designed to be closed when the solenoid valves are de-energized to minimize the possibility of the common failure, and powered from the divisions A and B with different power sources, respectively.

This LCO is to ensure the capability of core cooldown and RCS depressurization, therefore, establishes the OPERABLE vent paths from the reactor vessel closure head and the pressurizer steam space to the IRWST, and ensure the independent power for valves in vent paths.

APPLICABILITY

In MODES 1, 2, 3, and in MODE 4 with the Shutdown Cooling (SC) System not aligned for Low Temperature Overpressure Protection (LTOP) of the reactor coolant pressure boundary (RCPB), the two vent paths of the reactor vessel closure head and the pressurizer are required to be OPERABLE. The RCGV function is primarily used for natural circulation considering loss of offsite power and single failure events. It assumes the Pressurizer Auxiliary Spray System is inoperable when these events occur. Vent paths of the reactor vessel closure head and the pressurizer steam space are used as the means of RCS depressurization. In MODES 1, 2, 3, and in MODE 4 with the SC System not aligned for LTOP of the RCPB, the steam generators are primarily used for RCS heat removal up to a point of the time before starting Shutdown Cooling System.

In MODES 1, 2, 3, and in MODE 4 with the SC System not aligned for LTOP of the RCPB, vent valves of the reactor vessel closure head and the pressurizer are used for RCS depressurization up to a point of the time before entering shutdown cooling when the Pressurizer Auxiliary Spray System is inoperable.

The OPERABLE RCS vent paths are not required for operating the SC System because the overpressure protection of the RCS is performed by the LTOP System.

In MODES 5 and 6, there is no need for OPERABLE RCS vent paths since the RCS temperature and pressure are low.
ACTIONS

The ACTIONS are modified by a Note to clarify that separate condition entry is allowed for each of the two RCS reactor coolant gas vent flow path locations, the reactor vessel closure head and the pressurizer steam space.

A.1

With inoperable components, such that one required vent path is inoperable, the required vent path must be returned to OPERABLE status within 72 hours. The Completion Time of 72 hours is reasonable considering the OPERABLE status of the other vent path.

B.1

With components inoperable, such that two required vent paths from either location are inoperable, at least one of the vent paths must be returned to OPERABLE status within 6 hours.

The Completion Time of 6 hours is reasonable to allow time to correct the situation, considering the importance of restoring at least one vent path. If at least one vent path is not restored to OPERABLE status within 6 hours, then Condition D is entered.

C.1

With inoperable components, such that one or two common flow paths to the IRWST are inoperable, the common flow path(s) must be returned to OPERABLE status within 6 hours. The Completion Time of 6 hours is reasonable to allow time to correct the situation, considering the importance of restoring common flow path(s). If the common flow path(s) are not restored to OPERABLE status within 6 hours, then Condition D is entered.

D.1 and D.2

If a Required Action and associated Completion Time of Condition A, B, or C cannot be met, the plant must be brought to a MODE in which the LCO does not apply. To achieve this status, the plant must be in MODE 3 within 6 hours, and in MODE 4 with the SC System aligned for LTOP of the RCPB within 12 hours. The Completion Times are reasonable, based on operating experience, to reach the required plant conditions from full power conditions in an orderly manner and without challenging plant systems.
At least one complete cycling for all remote control valves in each vent flow path from the MCR verifies the RCGV System valves will function when necessary. There are two in-series solenoid-operated valves in each of the two parallel flow paths from the reactor vessel closure head, and two in-series solenoid-operated valves in each of the two parallel flow paths from the pressurizer upper head that connect to a common header, which contains two solenoid-operated valves in parallel lines, which connect to a common flow path to the IRWST. The Surveillance must be performed in MODE 5. The test Frequency is based on the Inservice Testing Program, since these valves are designated as safety-related.

This SR requires verification of flow through each vent path and must be performed in MODE 5 during venting of non-condensible gases from the RCS after operations that involved entering the RCS loops not filled condition. The 18 month Frequency is based on a typical refueling cycle and operating experience, which has shown this interval provides adequate assurance that the vent flow paths are not obstructed.

There are three locally operated manual valves in the RCGV system that are normally locked open. One valve is in the vent path from the reactor vessel closure head; one valve is in the vent path from the pressurizer; and one valve is in the common vent flow path to the IRWST. It is necessary to verify that these valves are locked open to ensure that a vent path can be established from the reactor vessel closure head and from the pressurizer steam space to the IRWST. The Surveillance must be performed in MODE 5 or 6. The 18 month Frequency is based on avoiding containment entry to access these valves during unit operation and the ease of accessing these valves during a refueling outage in MODE 5 or 6. The administrative control of locking the valves in the open position and the difficulty in accessing the valves during unit operation make an inadvertent closure of these valves unlikely.

Verification of the correct breaker alignment and valve position indication ensures that the solenoid-operated valves are able to actuate and the valve positions are able to be monitored when necessary. There are two in-series solenoid-operated valves in each of the two parallel flow paths from the reactor vessel closure head and in each of the two parallel flow paths from the pressurizer steam space, and two in-parallel solenoid-
operated valves in the common flow path to the IRWST. The 7 day Frequency has been shown to be acceptable by operating experience.

REFERENCES

1. FSAR, Subsection 5.4.12.
Steam generator (SG) tubes are small diameter, thin walled tubes that carry primary coolant through the primary to secondary heat exchangers. The SG tubes have a number of important safety functions. Steam generator tubes are an integral part of the reactor coolant pressure boundary (RCPB) and, as such, are relied on to maintain the primary system’s pressure and inventory. The SG tubes isolate the radioactive fission products in the primary coolant from the secondary system. In addition, as part of the RCPB, the SG tubes are unique in that they act as the heat transfer surface between the primary and secondary systems to remove heat from the primary system. This Specification addresses only the RCPB integrity function of the SG. The SG heat removal function is addressed by LCO 3.4.4, “RCS Loops – MODES 1 and 2,” LCO 3.4.5, “RCS Loops – MODE 3,” LCO 3.4.6, “RCS Loops – MODE 4,” and LCO 3.4.7, “RCS Loops – MODE 5 (Loops Filled).”

SG tube integrity means that the tubes are capable of performing their intended RCPB safety function consistent with the licensing basis, including applicable regulatory requirements.

Steam generator tubing is subject to a variety of degradation mechanisms. Steam generator tubes can experience tube degradation related to corrosion phenomena, such as wastage, pitting, intergranular attack, and stress corrosion cracking, along with other mechanically induced phenomena such as denting and wear. These degradation mechanisms can impair tube integrity if they are not managed effectively. The SG performance criteria are used to manage SG tube degradation.

Specification 5.5.9, “Steam Generator (SG) Program,” requires that a program be established and implemented to ensure that SG tube integrity is maintained. Pursuant to Specification 5.5.9, tube integrity is maintained when the SG performance criteria are met. There are three SG performance criteria: structural integrity, accident induced leakage, and operational LEAKAGE. The SG performance criteria are described in Specification 5.5.9. Meeting the SG performance criteria provides reasonable assurance of maintaining tube integrity at normal and accident conditions.

The processes used to meet the SG performance criteria are defined by the Steam Generator Program Guidelines (Ref. 1).
Steam generator tube integrity satisfies Criterion 2 of 10 CFR 50.36(c)(2)(ii).

The LCO requires that SG tube integrity be maintained. The LCO also requires that all SG tubes that satisfy the plugging criteria be plugged in accordance with the Steam Generator Program.

During an SG inspection, any inspected tube that satisfies the Steam Generator Program plugging criteria is removed from service by plugging. If a tube was determined to satisfy the plugging criteria but was not plugged, the tube may still have tube integrity.

In the context of this Specification, a SG tube is defined as the entire length of the tube, including the tube wall, between the tube-to-tubesheet weld at the tube inlet and the tube-to-tubesheet weld at the tube outlet. The tube-to-tubesheet weld is not considered part of the tube.

A SG tube has tube integrity when it satisfies the SG performance criteria. The SG performance criteria are defined in Specification 5.5.9, “Steam Generator Program,” and describe acceptable SG tube performance.
The Steam Generator Program also provides the evaluation process for determining conformance with the SG performance criteria.

There are three SG performance criteria: structural integrity, accident induced leakage, and operational LEAKAGE. Failure to meet any one of these criteria is considered failure to meet the LCO.

The structural integrity performance criterion provides a margin of safety against tube burst or collapse under normal and accident conditions, and ensures structural integrity of the SG tubes under all anticipated transients included in the design specification. Tube burst is defined as, “The gross structural failure of the tube wall. The condition typically corresponds to an unstable opening displacement (e.g., opening area increased in response to constant pressure) accompanied by ductile (plastic) tearing of the tube material at the ends of the degradation.” Tube collapse is defined as, “For the load displacement curve for a given structure, collapse occurs at the top of the load versus displacement curve where the slope of the curve becomes zero.” The structural integrity performance criterion provides guidance on assessing loads that have a significant effect on burst or collapse. In that context, the term “significant” is defined as “An accident loading condition other than differential pressure is considered significant when the addition of such loads in the assessment of the structural integrity performance criterion could cause a lower structural limit or limiting burst/collapse condition to be established.” For tube integrity evaluations, except for circumferential degradation, axial thermal loads are classified as secondary loads. For circumferential degradation, the classification of axial thermal loads as primary or secondary loads will be evaluated on a case-by-case basis. The division between primary and secondary classifications will be based on detailed analysis and/or testing.

Structural integrity requires that the primary membrane stress intensity in a tube not exceed the yield strength for all ASME Code, Section III, Service Level A (normal operating conditions) and Service Level B (upset or abnormal conditions) transients included in the design specification. This includes safety factors and applicable design basis loads based on ASME Code, Section III, Subsection NB (Ref. 4) and Nuclear Regulatory Commission (NRC) Regulatory Guide (RG) 1.121 (Ref. 5).
The accident induced leakage performance criterion ensures that the primary to secondary leakage caused by a design basis accident, other than an SGTR, is within the accident analysis assumptions. The accident analysis assumes that accident induced leakage does not exceed 1.14 L/min (0.3 gpm) per SG, except for specific types of degradation at specific locations where the NRC has approved greater accident induced leakage. The accident induced leakage rate includes any primary to secondary leakage existing prior to the accident in addition to primary to secondary leakage induced during the accident.

The operational LEAKAGE performance criterion provides an observable indication of SG tube conditions during plant operation. The limit on operational leakage is contained in LCO 3.4.12, “RCS Operational LEAKAGE,” and limits primary to secondary leakage through any one SG to 0.39 L/min (150 gpd). This limit is based on the assumption that a single crack leaking this amount would not propagate to an SGTR under the stress conditions of a LOCA or a main steam line break. If this amount of leakage is due to more than one crack, the cracks are very small, and the above assumption is conservative.

Steam generator tube integrity is challenged when the pressure differential across the tubes is large. Large differential pressures across SG tubes can only be experienced in MODE 1, 2, 3, or 4.

RCS conditions are far less challenging in MODES 5 and 6 than during MODES 1, 2, 3, and 4. In MODES 5 and 6, primary to secondary differential pressure is low, resulting in lower stresses and reduced potential for leakage.

The ACTIONS are modified by a Note clarifying that the Conditions may be entered independently for each SG tube. This is acceptable because the Required Actions provide appropriate compensatory actions for each affected SG tube. Complying with the Required Actions may allow for continued operation, and subsequent affected SG tubes are governed by subsequent Condition entry and application of associated Required Actions.
Bases (continued)

A.1 and A.2

Condition A applies if it is discovered that one or more SG tubes examined in an inservice inspection satisfy the tube plugging criteria but were not plugged in accordance with the Steam Generator Program as required by SR 3.4.17.2. An evaluation of SG tube integrity of the affected tube(s) must be made. Steam generator tube integrity is based on meeting the SG performance criteria described in the Steam Generator Program. The SG plugging criteria define limits on SG tube degradation that allow for flaw growth between inspections while still providing assurance that the SG performance criteria will continue to be met. In order to determine if a SG tube that should have been plugged has tube integrity, an evaluation must be completed that demonstrates that the SG performance criteria will continue to be met until the next refueling outage or SG tube inspection. The tube integrity determination is based on the estimated condition of the tube at the time the situation is discovered and the estimated growth of the degradation prior to the next SG tube inspection. If it is determined that tube integrity is not being maintained, Condition B applies.

A Completion Time of 7 days is sufficient to complete the evaluation while minimizing the risk of plant operation with a SG tube that may not have tube integrity.

If the evaluation determines that the affected tube(s) have tube integrity, Required Action A.2 allows plant operation to continue until the next refueling outage or SG inspection provided the inspection interval continues to be supported by an operational assessment that reflects the affected tubes. However, the affected tube(s) must be plugged prior to entering MODE 4 following the next refueling outage or SG inspection. This Completion Time is acceptable since operation until the next inspection is supported by the operational assessment.

B.1 and B.2

If the Required Actions and associated Completion Times of Condition A are not met or if SG tube integrity is not being maintained, the reactor must be brought to MODE 3 within 6 hours and MODE 5 within 36 hours.

The allowed Completion Times are reasonable, based on operating experience, to reach the desired plant conditions from full power conditions in an orderly manner and without challenging plant systems.
During shutdown periods the SGs are inspected as required by this SR and the Steam Generator Program. NEI 97-06, Steam Generator Program Guidelines (Ref. 1), and its referenced EPRI Guidelines, establish the content of the Steam Generator Program. Use of the Steam Generator Program ensures that the inspection is appropriate and consistent with accepted industry practices.

During SG inspections a condition monitoring assessment of the SG tubes is performed. The condition monitoring assessment determines the “as found” condition of the SG tubes. The purpose of the condition monitoring assessment is to ensure that the SG performance criteria have been met for the previous operating period.

The Steam Generator Program determines the scope of the inspection and the methods used to determine whether the tubes contain flaws satisfying the tube plugging criteria. Inspection scope (i.e., which tubes or areas of tubing within the SG are to be inspected) is a function of existing and potential degradation locations. The Steam Generator Program also specifies the inspection methods to be used to find potential degradation. Inspection methods are a function of degradation morphology, nondestructive examination (NDE) technique capabilities, and inspection locations.

The Steam Generator Program defines the Frequency of SR 3.4.17.1. The Frequency is determined by the operational assessment and other limits in the SG examination guidelines (Ref. 6). The Steam Generator Program uses information on existing degradations and growth rates to determine an inspection Frequency that provides reasonable assurance that the tubing will meet the SG performance criteria at the next scheduled inspection. In addition, Specification 5.5.9 contains prescriptive requirements concerning inspection intervals to provide added assurance that the SG performance criteria will be met between scheduled inspections.

If crack indications are found in any SG tube, the maximum inspection interval for all affected and potentially affected SGs is restricted by Specification 5.5.9 until subsequent inspections support extending the inspection interval.
BASES

SURVEILLANCE REQUIREMENTS (continued)

SR 3.4.17.2

During an SG inspection, any inspected tube that satisfies the Steam Generator Program plugging criteria is removed from service by plugging. The tube plugging criteria delineated in Specification 5.5.9 are intended to ensure that tubes accepted for continued service satisfy the SG performance criteria with allowance for error in the flaw size measurement and for future flaw growth. In addition, the tube plugging criteria, in conjunction with other elements of the Steam Generator Program, ensure that the SG performance criteria will continue to be met until the next inspection of the subject tube(s). Reference 1 provides guidance for performing operational assessments to verify that the tubes remaining in service will continue to meet the SG performance criteria.

The Frequency of prior to entering MODE 4 following a SG inspection ensures that the Surveillance has been completed and all tubes meeting the plugging criteria are plugged prior to subjecting the SG tubes to significant primary to secondary pressure differential.

REFERENCES

1. NEI 97-06, “Steam Generator Program Guidelines.”
2. 10 CFR Part 50, Appendix A, GDC 19.
3. 10 CFR Part 50.34.
4. ASME Section III, Subsection NB.
B 3.5  EMERGENCY CORE COOLING SYSTEM (ECCS)

B 3.5.1  Safety Injection Tanks (SITs)

BASES

BACKGROUND  The functions of the four safety injection tanks (SITs) are to supply water to the reactor vessel during the blowdown phase of a loss of coolant accident (LOCA), to provide inventory to help accomplish the refill phase that follows thereafter, and to provide Reactor Coolant System (RCS) makeup for a small break LOCA.

The blowdown phase of a large break LOCA is the initial period of the transient during which the RCS departs from equilibrium conditions, and heat from fission product decay, hot internals, and the vessel continues to be transferred to the reactor coolant. The blowdown phase of the transient ends when the RCS pressure falls to a value approaching that of the containment atmosphere.

The refill phase of a LOCA follows immediately where reactor coolant inventory has vacated the core through steam flashing and ejection out through the break. The core is essentially in adiabatic heatup. The balance of the SIT’s inventory is then available to help fill voids in the lower plenum and reactor vessel downcomer to establish a recovery level at the bottom of the core and ongoing reflood of the core with the addition of safety injection (SI) water.

The SITs are pressure vessels partially filled with borated water and pressurized with nitrogen gas. The SITs are passive components, since no operator or control action is required for them to perform their function. Internal tank pressure and gravity are sufficient to discharge the contents to the RCS, if RCS pressure decreases below the SIT pressure.

Each SIT discharges its water volume directly to the reactor vessel downcomer via a direct vessel injection (DVI) nozzle, also used by the Safety Injection System (SIS). Each SIT is isolated from the RCS by a motor operated isolation valve and two check valves in series. The motor operated isolation valves are normally open with power removed from the valve motor to prevent inadvertent closure prior to, or during an accident.

At the initial stage of plant heatup, the SIT isolation valves are closed with power available to the valve motors. When RCS pressure increases above 42.2 kg/cm² (600 psia), the SIT isolation valves are automatically opened through an interlock with the pressurizer pressure channels. When RCS pressure increases above 50.3 kg/cm² (715 psia), the operators remove power to the SIT isolation valves.


Bases

Background (continued)

Power is restored to the SIT motor operated isolation valves when RCS pressure decreases below 50.3 kg/cm²A (715 psia) during plant cooldown. Before RCS pressure is reduced to 45.0 kg/cm²A (640 psia), operators will lower SIT pressure to 28.1 kg/cm²G (400 psig). An interlock prevents the SIT isolation valves from being closed if RCS pressure is > 33.4 kg/cm²A (475 psia). Once RCS pressure is below 33.4 kg/cm²A (475 psia), the SIT isolation valves will be closed and power to the valve actuator is maintained available.

Additionally, the isolation valves are interlocked with the pressurizer pressure instrumentation channels to ensure the valves will automatically open as RCS pressure is increased above SIT pressure and to prevent inadvertent closure prior to an accident. The valves also receive a safety injection actuation signal (SIAS) from the Plant Protection System (PPS) or Diverse Protection System (DPS) to open. These features ensure the valves meet the requirements of IEEE Std. 603-1991 (Ref. 1) for “operating bypasses” and that the SITs will be available for injection without reliance on operator action.

The SIT gas and water volumes, gas pressure, and outlet pipe size are selected to allow the four SITs to partially recover the core before significant clad melting or zirconium-water reaction can occur following a LOCA. Four SITs are adequate for this function for a cold leg guillotine break which is the limiting break case in the LOCA analysis.

Applicable Safety Analyses

The SITs are taken credit for in both the large and small break LOCA analyses at full power (Ref. 2). These are the design basis accidents (DBAs) that establish the acceptance limits for the SITs. Reference to the analyses for these DBAs is used to assess changes to the SITs as they relate to the acceptance limits.

In performing the LOCA calculations, conservative assumptions are made concerning the availability of safety injection flow. These assumptions include signal generation time, equipment starting times, and delivery time due to system piping. In the early stages of a LOCA with a loss of offsite power, the SITs provide the sole source of makeup water to the RCS. (The assumption of a loss of offsite power is required by regulations.) This is because the safety injection pumps cannot deliver flow until the emergency diesel generators (EDGs) start, come to rated speed, and go through their timed loading sequence. During a LOCA, the entire contents of four SITs are assumed to be injected directly to vessel downcomer via the direct vessel injection nozzle during the blowdown, lower plenum refill, and early core reflood phases.
The limiting large break LOCA is a double ended guillotine cold leg break at the discharge of the reactor coolant pump. During this event the SITs discharge to the RCS as soon as RCS pressure decreases below SIT pressure.

As a conservative estimate in the calculation of the reflood portion of the accident, no credit is taken for safety injection pump (SIP) flow within the SIP's actuation delay time. This results in a minimum effective delay of over 40 seconds during which the SITs must provide the core cooling function. The actual delay time does not exceed 40 seconds. No operator action is assumed during a large break LOCA.

The worst case small break LOCA assumes also some time delay before pumped flow reaches the core. For the larger range of small breaks, the rate of blowdown is such that the increase in fuel clad temperature is terminated mainly by the SITs, with pumped flow then providing continued cooling. As break size continues to decrease, the SITs and an SIP both play a part in terminating the rise in clad temperature. As break size decreases the role of the SITs decreases until they are not required and the SIPs become solely responsible for terminating the temperature increase.

This LCO helps to ensure that the following acceptance criteria, established by 10 CFR 50.46 (Ref. 3) for ECCSs, will be met following a LOCA:

a. Maximum fuel element cladding temperature of \( \leq 1,204.4°C \) (2,200°F);

b. Maximum cladding oxidation of \( \leq 0.17 \) times the total cladding thickness before oxidation;

c. Maximum hydrogen generation from a zirconium-water reaction of \( \leq 0.01 \) times the hypothetical amount that would be generated if all of the metal in the cladding cylinders surrounding the fuel, excluding the cladding surrounding the plenum volume, were to react; and

d. The core is maintained in a coolable geometry.

Since the SITs discharge during the blowdown, lower plenum refill, and early core reflood phases of a LBLOCA, they do not contribute to the long term requirements of 10 CFR 50.46.

Since the SITs are passive components, single active failures are not applicable to their operation. The SIT isolation valves, however, are not
single failure proof; therefore, whenever the valves are open, power is removed from their operators and the switch is key locked open.

These precautions ensure that the SITs are available during an accident (Ref. 4). With power supplied to the valves a single active failure could result in a valve closure, which would render one SIT unavailable for injection. If a second SIT is lost through a DVI break only two SITs would reach the core. Since the only active failure which could affect the SITs would be the closure of a motor operated outlet valve, the requirement to remove power from these eliminates this failure mode.

The minimum volume requirement for the SITs ensures that four SITs can provide adequate inventory to reflood the core and downcomer following a large break LOCA (LBLOCA) considering ECC water bypass. The downcomer then remains flooded until the Safety Injection Pumps start to deliver flow.

The maximum volume limit is based upon maintaining an adequate gas volume to ensure proper injection and the ability of the SITs to fully discharge, as well as limiting the maximum amount of boron inventory in the SITs.

A minimum of 25% narrow range level corresponding to 50.7 m$^3$ (1,790 ft$^3$) of borated water, and a maximum of 75% narrow range level corresponding to 54.6 m$^3$ (1,927 ft$^3$) of borated water, are used in the safety analyses as the volume in the SITs. To allow for instrument accuracy, 29% narrow range (corresponding to 51.1 m$^3$ (1,805 ft$^3$)) and 69% narrow range (corresponding to 54.0 m$^3$ (1,906 ft$^3$)), are specified. The analyses are based upon the cubic feet requirements; the percentage figures are provided for operator use because the level indication provided in the main control room (MCR) is in percentages, not in cubic feet.

The minimum nitrogen gas pressure requirement ensures that the contained gas volume will generate discharge flow rates during injection which are consistent with those assumed in the safety analyses.

The maximum nitrogen cover gas pressure limit ensures that excessive amounts of gas will not be injected into the RCS after the SITs have emptied.

A minimum pressure of 40.1 kg/cm$^2$G (570 psig) and a maximum pressure of 44.4 kg/cm$^2$G (632 psig) are used in the analyses. To allow for instrument accuracy, a 40.6 kg/cm$^2$G (578 psig) minimum and 43.9 kg/cm$^2$G (624 psig) maximum are specified.
The maximum allowable boron concentration of 4,400 ppm in the SITs is based upon boron precipitation limits in the core following a LOCA. Establishing a maximum limit for boron is necessary since the time at which boron precipitation would occur in the core following a LOCA is a function of break location, break size, the amount of boron injected into the core and the point of ECCS injection. Post LOCA emergency procedures directing the operator to establish simultaneous hot leg and DVI nozzle injection are based upon the worst case minimum boron precipitation time. Maintaining the maximum SIT boron concentration within the upper limit ensures the SITs do not invalidate this calculation. An excessive boron concentration in any of the borated water sources used for injection during a LOCA could result in boron precipitation earlier than predicted.

The minimum boron requirements of 2,300 ppm are based on beginning of life reactivity values and are selected to ensure the reactor will remain subcritical during the reflood stage of a large break LOCA. During a large break LOCA all control element assemblies (CEAs) are assumed not to insert into the core and the initial reactor shutdown is accomplished by void formation during blowdown. Sufficient boron concentration must be maintained in the SITs to prevent a return to criticality during reflood. Although this requirement is similar to the basis for the minimum boron concentration of the in-containment refueling water storage tank (IRWST) the minimum SIT concentration is lower than the IRWST. Dilution by the RCS was already taken into account for in the calculation of the minimum boron requirements for the SITs. Operators need not account for dilution by the RCS.

The SITs satisfy Criterion 3 of 10 CFR 50.36(c)(2)(ii).

The LCO establishes the minimum conditions required to ensure the SITs are available to accomplish their core cooling safety function following a LOCA. Four SITs are required to be OPERABLE to ensure adequate core cooling during a LBLOCA.

If the contents of fewer than four SITs are injected during the blowdown, lower plenum refill, and early core reflood phases of a LBLOCA considering ECC water bypass, the ECCS acceptance criteria of 10 CFR 50.46 (Ref. 3) could be violated.

For a SIT to be considered OPERABLE, the motor operated isolation valve must be fully open with power removed and the limits established in the SR for contained volume, boron concentration and nitrogen cover gas pressure must be met.
APPLICABILITY

In MODES 1 and 2, and MODES 3 and 4 with RCS pressure \( \geq 50.3 \text{ kg/cm}^2 \text{A} \) (715 psia), the SIT OPERABILITY requirements are based on an assumption of full power operation. Although cooling requirements decrease as power decreases, the SITs are still required to provide core cooling as long as elevated RCS pressures and temperatures exist.

This LCO is only applicable at pressures \( \geq 50.3 \text{ kg/cm}^2 \text{A} \) (715 psia). Below 50.3 kg/cm²A (715 psia), the rate of RCS blowdown is such that the SIPs can provide adequate injection to ensure that peak clad temperature remains below the 10 CFR 50.46 (Ref. 3) limit of 1,204.4°C (2,200°F).

In MODES 3 and 4 with pressure < 50.3 kg/cm²A (715 psia) and in MODES 5 and 6, the SIT motor operated isolation valves are closed to isolate the SITs from RCS. This allows RCS cooldown and depressurization without discharging the SITs into the RCS or requiring depressurization of the SITs.

ACTIONS

A.1

If the boron concentration of one SIT is not within limits, it must be returned to within the limits within 72 hours. In this condition, ability to maintain subcriticality or minimum boron precipitation time could be reduced, but the reduced concentration effects on core subcriticality during reflood are minor. Boiling of the ECCS water in the core during reflood concentrates the boron in the saturated liquid that remains in the core. In addition, the volume of the SIT is still available for injection, since the boron requirements are based on the average boron concentration of the total volume of four SITs, the consequences are less severe than they would be if an SIT were not available for injection. Thus, 72 hours is allowed to return the boron concentration to within limits.

If the Boron-10 isotopic concentration is not within limits, it must be returned to within the limits within 72 hours. The reactor coolant in the RCS is mixed with the refueling water in the IRWST during the refueling outages. The Boron-10 isotopic concentration of the refueling water in the IRWST can be decreased over time whenever the mixture process is repeated. The Boron-10 isotopic concentration in the SITs also can decrease over a long time, because the IRWST water may be utilized in order to add water inventory to the SITs. The 72 hour Completion Time to restore Boron-10 isotopic concentration in the affected SITs is reasonable considering that discovery of a low Boron-10 isotopic concentration most likely would occur when the unit is outside the LCO's Applicability and would have to be corrected before entering the...
Bases

Actions (continued)

Applicability as required by LCO 3.0.4, and the low probability that a low SIT Boron-10 isotopic concentration condition will occur between performances of SR 3.5.1.6; the 72 hours Completion Time also provides sufficient time to correct the condition and avoid an unnecessary unit shutdown.

If the level and pressure cannot be verified, pressure and level indication for the affected SIT would not be available to the operators. However, in this condition the SIT would still be available to fulfill its function because it is unlikely that the level or pressure would deteriorate to outside specified limits within 72 hours. Therefore, based on this, and that the level and pressure instrumentation associated with the SITs do not initiate a safety action, it is reasonable to allow 72 hours to restore the SIT to OPERABLE status. This is consistent with the recommendations of NUREG-1366 (Ref. 5).

B.1

If one SIT is inoperable, for a reason other than boron concentration or the inability to verify level or pressure, the SIT must be returned to OPERABLE status within 1 hour. In this Condition, the required contents of four SITs cannot be assumed to reach the core during a LBLOCA. Due to the severity of the consequences should a LOCA occur in these conditions, the 1 hour Completion Time to open the valve, remove power to the valve, or restore the proper water volume or nitrogen cover gas pressure ensures that prompt action will be taken to return the inoperable SIT to OPERABLE status. The Completion Time minimizes the exposure of the plant to a LOCA in these conditions.

C.1 and C.2

If the SIT cannot be returned to OPERABLE status within the associated Completion Time, the plant must be placed in a MODE in which the LCO does not apply. To achieve this status, the plant must be brought to at least MODE 3 within 6 hours and pressurizer pressure reduced to < 50.3 kg/cm²A (715 psia) within 12 hours. The allowed Completion Times are reasonable, based on operating experience, to reach the required plant conditions from full power conditions in an orderly manner and without challenging plant systems.

D.1

If more than one SIT is inoperable, the unit is in a condition outside the accident analyses. Therefore, LCO 3.0.3 must be entered immediately.
SR 3.5.1.1

Verification every 12 hours that each SIT isolation valve is fully open, as indicated in the MCR, ensures the SITs are available for injection and ensures timely discovery if a valve should be partially closed. If an isolation valve is not fully open the rate of injection to the RCS would be reduced. Although a motor operated valve position should not change with power removed, a closed valve could result in not meeting accident analysis assumptions. A 12 hour Frequency is considered reasonable in view of other administrative controls that ensure the unlikelihood of a mispositioned isolation valve.

SR 3.5.1.2 and SR 3.5.1.3

SIT borated water volume and nitrogen cover gas pressure should be verified to within specified limits every 12 hours in order to ensure adequate injection during a LOCA. Due to the static design of the SITs, a 12 hour Frequency allows the operator sufficient time to identify changes before the limits are reached. Operating experience has shown this Frequency to be appropriate for early detection and correction of off normal trends.

SR 3.5.1.4

A period of 31 days is reasonable for verification to determine that each SIT’s boron concentration is within the required limits, because the static design of the SITs limits the ways in which the concentration can be changed. The 31 day Frequency is adequate to identify changes which could occur from mechanisms such as stratification or inleakage. Sampling the affected SIT within 6 hours after a 1% volume increase will identify whether inleakage from the RCS has caused a reduction in boron concentration to below the required limit. It is not necessary to verify boron concentration if the added water is from the IRWST, because the water contained in the IRWST is within the SIT boron concentration requirements. This is consistent with the recommendations of NUREG-1366 (Ref. 5).

SR 3.5.1.5

Verification every 31 days that power is removed from each SIT isolation valve operator when the pressurizer pressure is $\geq 50.3 \text{ kg/cm}^2\text{A} \ (715 \text{ psia})$ ensures that an active failure could not result in the undetected closure of an SIT motor operated isolation valve. If this were to occur, only three SITs would be available for injection during a LOCA. Since installation and removal of power to the SIT isolation valve operators is
SURVEILLANCE REQUIREMENTS (continued)

conducted under administrative control, the 31 day Frequency was chosen to provide additional assurance that power is removed.

This SR allows power to be supplied to the motor operated isolation valves when pressurizer pressure is < 50.3 kg/cm²A (715 psia), thus allowing operational flexibility by avoiding unnecessary delays to manipulate the breakers during unit startups or shutdowns. Even with power supplied to the valves, inadvertent closure is prevented by the RCS pressure interlock associated with the valves. Should closure of a valve occur in spite of the interlock, the SI signal provided to the valves would open a closed valve in the event of a LOCA.

SR 3.5.1.6

Periodic verification that the isotopic concentration of Boron-10 in each SIT is within the limit specified in the COLR ensures that the Boron-10 isotopic concentration assumed in the safety analysis is available. Since Boron-10 in the SITs is not directly exposed to a significant neutron flux and the IRWST water used as inventory for the SITs is only mixed with the reactor coolant during refueling outages, the Frequency of 24 months is considered conservative. The Surveillance Frequency is based on operating experience, equipment reliability, and plant risk.

REFERENCES

2. FSAR, Subsection 6.3.
3. 10 CFR 50.46.
4. FSAR, Chapter 15.
5. NUREG-1366, February 1990.
B 3.5 EMERGENCY CORE COOLING SYSTEM (ECCS)

B 3.5.2 Safety Injection System (SIS) – Operating

BASES

BACKGROUND

The function of the SIS is to provide core cooling and negative reactivity to ensure that the reactor core is protected after any of the following accidents:

a. Loss of coolant accident (LOCA);

b. Control element assembly (CEA) ejection accident;

c. Loss of secondary coolant accident, including uncontrolled steam release or loss of feedwater; and

d. Steam generator tube rupture (SGTR).

The addition of negative reactivity is designed primarily for the main steam line break (MSLB) where primary cooldown could add enough positive reactivity to achieve criticality and return to significant power.

There is only one phase of SIS operation. In the injection phase, all injection is added to the Reactor Coolant System (RCS) via the direct vessel injection (DVI) nozzles. After the blowdown stage of the LOCA stabilizes, injection flow is split equally between the hot legs and DVI nozzles.

Four mechanically redundant safety injection (SI) trains are provided. Each train consists of an SI pump and the associated piping and valves. SI flow credited in LOCA analyses is dependent on the pipe break location. Full flow from two pumps diagonally positioned in the reactor vessel and four SITs is credited for a break in a reactor coolant pump (RCP) discharge leg. Full flow from one SI pump and three SITs is credited for a break in a DVI line; the flow from the one pump and from one SIT is assumed to spill out the break. In MODES 1, 2, and 3, all SI trains are required to be OPERABLE. This ensures that 100% of the core cooling requirements can be provided even in the event of a RCP discharge leg break or a DVI line break with a failure of emergency diesel generator (EDG) to start.

An independent suction header supplies water from the in-containment refueling water storage tank (IRWST) to each of the safety injection pumps. Each SI pump discharges directly to the reactor vessel downcomer via the direct vessel injection nozzle. The SI pump directs sufficient flow to the core to meet the analysis assumptions following a LOCA in one of the RCS cold legs.
During a large break LOCA RCS pressure will decrease to < 14.1 kg/cm²A (200 psia) in < 20 seconds. The SISs are actuated upon receipt of a safety injection actuation signal (SIAS) from Plant Protection System (PPS) or Diverse Protection System (DPS). The actuation of safeguard loads is accomplished in a programmed time sequence. If offsite power is available, the safeguard loads start immediately in the programmed sequence.

If offsite power is not available, the engineered safety features (ESF) buses shed normally operating loads and are connected to the EDGs. Safeguard loads are then actuated in the programmed time sequence. The time delay associated with diesel starting, sequenced loading, and pump starting determines the time required before pumped flow is available to the core following a LOCA.

The active SIS components, along with the passive safety injection tanks (SITs) and the IRWST, covered in LCO 3.5.1, “Safety Injection Tanks (SITs),” and LCO 3.5.4, “In-containment Refueling Water Storage Tank (IRWST),” provide the cooling water to meet GDC 35 (Ref. 1).

LCO 3.5.2 helps to ensure that the following acceptance criteria established by 10 CFR 50.46 (Ref. 2) for SIS will be met following a LOCA:

a. Maximum fuel element cladding temperature of \( \leq 1,204.4°C \) (2,200°F);

b. Maximum cladding oxidation of \( \leq 0.17 \) times the total cladding thickness before oxidation;

c. Maximum hydrogen generation from a zirconium-water reaction of \( \leq 0.01 \) times the hypothetical amount that would be generated if all of the metal in the cladding cylinders surrounding the fuel, excluding the cladding surrounding the plenum volume, were to react;

d. The core is maintained in a coolable geometry; and

e. Adequate long term core cooling capability is maintained.

The LCO also limits the potential for a post-trip return to power following a MSLB and a CEA ejection and ensures that containment temperature limits are met.
SI pump flow is set during pre-operational testing to ensure that the pump runout flow is not excessive when the RCS is at atmospheric conditions. The SI System is assumed to be OPERABLE in the large break and small break LOCA analyses at full power, FSAR, Chapter 6 (Ref. 3). The delivered SI pump flow credited in safety analyses for a LOCA is dependent on the pressure conditions that exist as a result of the size of the LOCA. SI delivery curves define the SI performance credited in the large and small break LOCA analyses over the operating range of the SI pumps from pump shutoff head to pump runout flow. The MSLB also establishes the flow-head requirement and in addition establishes the minimum required response time for actuation of the pumps. The SGTR, CEA ejection, and inadvertent opening of an atmospheric dump valve analyses also credit the SI pumps, but do not limit the design.

The large break LOCA with a loss of offsite power and a single failure (disabling one SIS train) establishes the OPERABILITY requirements for the SIS. During the blowdown stage of a LOCA, the RCS depressurizes as primary coolant is ejected through the break into the containment. The nuclear reaction is terminated either by moderator voiding during large breaks or CEA insertion during small breaks. Long-term shutdown is preserved by the borated water delivered by the SIS to the core. Following depressurization, emergency cooling water is injected through the direct vessel injection nozzles into the downcomer, fills the lower plenum, and refloods the core.

On smaller breaks, RCS pressure will stabilize at a value dependent upon break size, heat load, and injection flow. The smaller the break, the higher this equilibrium pressure and the lower the injection flow rate. In all LOCA analyses, injection flow is not credited until RCS pressure drops below the shutoff head of the SI pumps.

The LCO ensures an SIS train will deliver sufficient water to match decay heat boil-off rates soon enough to minimize core uncovery for a large LOCA.

It also ensures that the SI pump will deliver sufficient water during a small break LOCA, and provide sufficient boron, in conjunction with the CEAs (assuming that the most reactive CEA does not insert), to maintain the core subcritical following an MSLB.

SIS – Operating satisfies Criterion 3 of 10 CFR 50.36(c)(2)(ii).
In MODES 1, 2, and 3, four independent (and redundant) SIS trains are required to ensure sufficient SIS flow is available to mitigate the consequences of a LOCA assuming a single failure coincident with a LOOP. Additionally, the SIS trains may be called upon to mitigate the consequences of other transients and accidents.

In MODES 1, 2, and 3, an SIS train consists of an SI pump, the piping, instruments, and controls to ensure an OPERABLE flow path capable of taking suction from the IRWST on an SIAS from PPS or DPS.

During an event requiring SIS actuation, a flow path is provided to ensure an abundant supply of water from the IRWST to the RCS via the SI pumps and their respective supply lines to each of the four direct vessel injection nozzles. In the long term, flow paths may be switched to supply part of its flow to the RCS hot legs via the Shutdown Cooling System (SCS) suction nozzles on two of the trains. Managing gas or voids in the piping is important to SIS OPERABILITY.

The flow path for each train must maintain its designed independence to ensure that no single failure can prevent delivery of the minimum required flow rate.

In MODES 1, 2, and 3 the SIS OPERABILITY requirements for the limiting design basis accident (DBA), large break LOCA, are based on full power operation. Although reduced power would not require the same level of performance, the accident analysis also does provide for reduced cooling requirements in the lower MODES. SRs for SI pump testing are based on the limiting safety analyses. SRs for SI pump performance are specified to ensure that head/flow characteristics, as measured at design conditions, are within the tolerances allowed in developing the SI delivery curves over the operating range from shutoff head to runout flow.

The SIS functional requirements for MODES 4, 5, and 6 are described in LCO 3.5.3.

If one train is inoperable, the inoperable components must be returned to OPERABLE status within 72 hours. The 72 hour Completion Time is based on an NRC study (Ref. 4) using a reliability evaluation and is a reasonable amount of time to effect many repairs.
Bases

Actions (continued)

An SIS train is inoperable if it is not capable of delivering the design flow to the RCS. The individual components are inoperable if they are not capable of performing their design function, or if supporting systems are not available (except as allowed by their respective LCOs).

The LCO requires the operability of a number of independent subsystems. Due to the redundancy of trains and the diversity of subsystems, the inoperability of one component in a train does not render the SIS incapable of performing its function.

An event accompanied by a loss of offsite power and the failure of an emergency diesel generator can disable one SIS train until power is restored.

B.1 and B.2

If two trains are inoperable, it should be verified within 1 hour whether the inoperable trains are diagonally oriented with respect to the reactor vessel (Trains 1 and 3, or Trains 2 and 4) or not.

If the inoperable trains are diagonally oriented, both trains must be returned to OPERABLE status within 72 hours, even if one train is restored before then.

Full flow from two diagonal SIS trains is credited because the safety analysis acceptance criteria cannot be satisfied should a cold leg break occur with the only two OPERABLE DVI nozzles being adjacent to the faulted cold leg due to core bypass flow that could occur. Hence, continued operation for 72 hours is justified.

C.1 and C.2

If the inoperable train cannot be restored to OPERABLE status or the two OPERABLE diagonal trains cannot be verified within the associated Completion Time, the plant must be brought to a MODE in which the LCO does not apply. To achieve this status, the plant must be brought to at least MODE 3 within 6 hours followed by placing the plant in MODE 4 within 12 hours. The allowed Completion Times are reasonable, based on operating experience, to reach the required unit conditions from full power in an orderly manner and without challenging unit systems.
Bases

Actions (continued)

D.1

If two or more trains are inoperative for reasons other than Condition B, the unit is in a condition outside the accident analysis. Therefore, LCO 3.0.3 must be entered immediately.

Surveillance Requirements

SR 3.5.2.1

Verification of proper valve position ensures the flow path from the SIS pumps to the RCS is maintained. Misalignment of these valves could render the associated SIS train inoperative. Securing these valves in position by locking after positioning them in the correct position ensures that the valves cannot be inadvertently misaligned or change position as the result of an improper operation (e.g., unauthorized, inadvertent). A 12 hour Frequency is considered reasonable in view of other administrative controls ensuring that a mispositioned valve is an unlikely possibility.

SR 3.5.2.2

Verifying the correct alignment for manual, power operated, and automatic valves in the SIS flow paths provides assurance that the proper flow paths will exist for SIS operation. This SR does not apply to valves which are locked, sealed or otherwise secured in position since these were verified to be in the correct position prior to locking, sealing or securing. A valve which receives an actuation signal is allowed to be in a non-accident position provided the valve automatically repositions within the proper stroke time. This Surveillance does not require any testing or valve manipulation. Rather, it involves verification that those valves capable of being mispositioned are in the correct position. The 31 day Frequency is appropriate because the valves are operated under procedural control, an improper valve position would only affect a single train, and the probability of an event requiring SIS actuation during this time period is low. This Frequency has been shown to be acceptable through operating experience.

The Surveillance is modified by a Note that allows system vent flow paths to be opened under administrative control. The procedure should be administratively controlled to station a dedicated field operator at the system vent flow path who is in continuous communication with the operators in the control room. The field operators will have a method to rapidly close the system vent flow path and restore the system to a condition equivalent to the design condition.
SR  3.5.2.3

With the exception of systems in operation, the SIS pumps are normally in a standby, non-operating condition. As such, flow path piping has the potential to develop voids and pockets of entrained gases. Maintaining the piping from the SIS pumps to the RCS full of water ensures that the system will perform properly, injecting its full capacity into the RCS upon demand. Water source comes from the IRWST and safety injection filling tanks (SIFTs). This will also prevent water hammer, pump cavitation, and pumping of non-condensible gas (e.g., air, nitrogen, hydrogen) into the reactor vessel during shutdown cooling or following an SIAS from PPS or DPS.

Selection of SIS piping locations susceptible to gas accumulation is based on a review of system design information, including piping and instrumentation drawings, isometric drawings, plan and elevation drawings, and calculations. The design review is supplemented by system walk downs to validate the system high points and to confirm the locations and orientation of important components that can become sources of gas or could otherwise cause gas to be trapped or difficult to remove during system maintenance or restoration. Susceptible piping locations depend on plant and system configuration, such as stand-by versus operating conditions.

The SIS is OPERABLE when it is sufficiently filled with water. Acceptance criterion is established for the volume of accumulated gas at susceptible locations. If accumulated gas is discovered that exceeds an acceptance criterion for the susceptible locations (or the volume of accumulated gas at one or more susceptible piping locations exceeds an acceptance criterion for gas volume at the suction or discharge of a pump), the Surveillance is not met. If it is determined by subsequent evaluation that the SIS is not rendered inoperable by the accumulated gas (i.e., the system is sufficiently filled with water), the Surveillance may be declared to be met. Accumulated gas should be eliminated or brought within the acceptance criterion limit.

SIS piping locations susceptible to gas accumulation are monitored and, if gas is found, the gas volume is compared to the acceptance criterion for the piping locations. Susceptible piping locations in the same system flow path that are subject to the same gas accumulation mechanisms may be verified by monitoring a representative subset of susceptible piping locations. Monitoring may not be practical for piping locations inaccessible due to radiological or environmental conditions, the plant configuration or personal safety. For these locations, alternative
methods (e.g., operating parameters, remote monitoring) may be used to monitor the susceptible piping locations. Monitoring is not required for susceptible piping locations where the maximum potential accumulated gas void volume has been evaluated and determined not to challenge system OPERABILITY. The accuracy of the method used for monitoring the susceptible piping locations and trending of the results should be sufficient to provide reasonable assurance of system OPERABILITY during the Surveillance interval.

The 31 day Frequency is based on the low probability of an event requiring SIS actuation during this time, the gradual nature of gas accumulation in the SIS piping, and the adequacy of procedural controls governing system operation.

SR 3.5.2.4

Periodic Surveillance testing of SIS pumps to detect gross degradation caused by impeller structural damage or other hydraulic component problems is required by Section XI of the ASME OM Code. This type of testing may be accomplished by measuring the pump developed head at only one point of the pump characteristic curve. This verifies both that the measured performance is within an acceptable tolerance of the original pump baseline performance and that the performance at the test flow is greater than or equal to the performance assumed in the unit safety analysis. SRs are specified in the Inservice Testing Program, which encompasses the ASME OM Code. Section XI of the ASME OM Code provides the activities and Frequencies necessary to satisfy the requirements.

SR 3.5.2.5

Discharge head at design flow is a normal test of SI pump performance required by the ASME Operations and Maintenance (OM) Code. The Frequency for such tests is a Code requirement. Such in-service inspections detect component degradation and incipient failures.

SR 3.5.2.6 and SR 3.5.2.7

These SRs demonstrate each automatic SIS valve actuates to its required position on an actual or simulated SIAS from PPS or DPS and that each SIS Pump starts on receipt of an actual or simulated SIAS from PPS or DPS. The 18 month Frequency is based on the need to perform these Surveillances under the conditions that apply during a plant outage and the potential for unplanned transients if the Surveillances were
SURVEILLANCE REQUIREMENTS (continued)

performed with the reactor at power. The 18 month Frequency is also acceptable based on consideration of the design reliability (and confirming operating experience) of the equipment. The actuation logic is tested as part of the Engineered Safety Feature Actuation System (ESFAS) testing and equipment performance is monitored as part of the Inservice Testing Program.

SR 3.5.2.8

Periodic visual inspections, that the IRWST, holdup volume tank (HVT), IRWST strainers, HVT trash racks and IRWST spillway are not restricted by debris and strainers and trash racks show no evidence of structural distress or abnormal corrosion helps to ensure SIS will function as required during a design bases events. The 18 month Frequency is based on the need to perform this surveillance under the conditions that apply during an outage, on the need to have access to the location, and on the potential for unplanned transients if the surveillance were performed with the reactor at power. This Frequency is sufficient to detect abnormal degradation and is confirmed by operating experience.

REFERENCES

1. 10 CFR Part 50, Appendix A, GDC 35.
2. 10 CFR 50.46.
3. FSAR, Chapter 6.
B 3.5 EMERGENCY CORE COOLING SYSTEM (ECCS)

B 3.5.3 Safety Injection System (SIS) – Shutdown

BASES

BACKGROUND
The Background section for Bases B 3.5.2, “Safety Injection System (SIS) – Operating,” is applicable to these Bases with the following modifications:

In MODES 4, 5, and 6 with Reactor Coolant System (RCS) level < 39.7 m (130 ft), the decay heat generation and RCS blowdown rates are such that a single safety injection (SI) pump is capable of providing the core cooling function in the event of a loss of coolant accident (LOCA). Also, a zero power main steam line break will have negligible consequences with respect to a reactivity transient.

APPLICABLE SAFETY ANALYSES
The Applicable Safety Analyses section of Bases 3.5.2 is applicable to these Bases.

Due to the stable conditions associated with operation in MODES 4, 5, and 6 with RCS level < 39.7 m (130 ft), and the reduced probability of a design basis accident (DBA), the SIS operational requirements are reduced. Included in these reductions is that certain automatic SI actuation signals are not available. In these MODES, sufficient time exists for manual actuation of the required SIS to mitigate the consequences of a DBA.

Only two trains of SIS diagonally oriented with respect to the reactor vessel are required for MODES 4, 5 and 6 with RCS level < 39.7 m (130 ft). Protection against single failure is not relied on for these MODES of operation.

SIS – Shutdown satisfies Criterion 3 of 10 CFR 50.36(c)(2)(ii).

LCO
During an event requiring SIS actuation, a flow path is required to supply water from the in-containment refueling water storage tank (IRWST) to the RCS via each SI pump to one of the four direct vessel injection (DVI) nozzles. In the long term, this flow path may be switched to take its supply from the IRWST and to deliver its flow to the RCS hot leg and DVI nozzle. Managing gas or voids in the piping is important to SIS OPERABILITY.

In the safety analysis, DVI line break is the most limiting case in these MODES. Two OPERABLE SI trains diagonally oriented with respect to
reactor vessel ensure at least one pump is capable of adequate flow to the core in the event of a LOCA.

**APPLICABILITY**
In MODES 1, 2 and 3, the OPERABILITY requirements for SIS are covered by LCO 3.5.2.

In MODES 4, 5, and 6 with RCS level < 39.7 m (130 ft), a loss of coolant resulting from a DVI line break requires two SI trains to be OPERABLE to ensure that if a LOCA disables one train an alternate SIS train is available. The requirement of having two OPERABLE SI trains is acceptable without single failure consideration on the basis of the stable reactivity condition and the limited core cooling requirements.

**ACTIONS**

**A.1**
With only one SI pump or two SI pump OPERABLE and not diagonally oriented with respect to the reactor vessel, the unit is not prepared to respond to a LOCA. The 1 hour Completion Time to restore at least two SIS trains to OPERABLE status ensures prompt action is taken to restore the required cooling capacity.

**B.1 and B.2**
The plant must be placed in a condition in which the LCO does not apply if SIS cannot be returned to OPERABLE status within the associated Completion Time. In MODE 6, an RCS level > 39.7 m (130 ft) (the top of the reactor vessel flange) will provide sufficient water inventory in the event of a LOCA. In MODE 4 or MODE 5, the reduction of RCS cold leg temperature to < 57.2°C (135°F) will enhance the margin for the peak cladding temperature for LOCA conditions. The reduction of cold leg temperature does not yield the unit conditions where the LCO is not applicable. However, considering that the possibility of a LOCA during MODE 4 or MODE 5 is extremely low, this action is considered acceptable. It is possible to reduce RCS cold leg temperature from any shutdown conditions to < 57.2°C (135°F) within 24 hours; therefore, the associated Completion Time is reasonable.

**SURVEILLANCE REQUIREMENTS**

SR  3.5.3.1 through SR  3.5.3.8
The applicable Surveillance descriptions from the Bases for LCO 3.5.2 apply.
The applicable references from the Bases for LCO 3.5.2 apply.
B 3.5  EMERGENCY CORE COOLING SYSTEM (ECCS)

B 3.5.4  In-Containment Refueling Water Storage Tank (IRWST)

BASES

BACKGROUND

The IRWST supports the Safety Injection System (SIS) and the Containment Spray System (CSS) as a source of borated water for engineered safety feature (ESF) pump operation.

The IRWST supplies four trains of SIS with borated water. Each SIS train has a separate suction line. The IRWST also supplies two containment spray pumps. Use of a single IRWST to supply four trains of SIS and two divisions of containment spray is acceptable since the IRWST is a passive component, and passive failures are not assumed to occur coincidently with a design basis event.

The shutdown cooling (SC) pump is interchangeable with the containment spray pump of the same division (i.e., the shutdown cooling pump can be used as a backup to the containment spray pump of the same division and vice versa). The shutdown cooling pump can take suction from the IRWST when it is used as a backup for the containment spray pump.

The safety injection (SI), SC, and containment spray (CS) pumps are provided with recirculation lines that ensure each pump can maintain minimum flow requirements when operating at shutoff head conditions. The SI pump recirculation lines discharge back to the IRWST. The SC and CS pumps have individual recirculation loops with heat exchangers which discharge back to the pump suction.

This LCO ensures that the IRWST contains sufficient borated water to support the SIS during a loss of coolant accident (LOCA), ensures the reactor remains subcritical following a LOCA, ensures sufficient scrub of radioactive iodines and particulates in the containment atmosphere and dilution of radionuclide in water for limiting offsite dose, and ensures that the assumptions used in the safety analysis for containment net free volume are maintained. Insufficient water inventory in the IRWST could result in insufficient cooling capacity of the SIS and CSS, higher risk on core degradation and containment integrity, and higher offsite doses following a LOCA.

Improper boron concentrations could result in a reduction of SHUTDOWN MARGIN or excessive boric acid precipitation in the core following a LOCA, as well as excessive caustic stress corrosion of mechanical components and systems inside containment.
Storage capacity of the IRWST is based on operational and safety analysis requirements. The minimum LCO volume is based upon SIS and CSS requirements. The maximum LCO volume is determined such that the water surface is lower than the bottom of the reactor vessel, even if the IRWST water is flooded in the reactor cavity due to an inadvertent operation of the Cavity Flooding System during normal operation. The IRWST temperature requirements are based on an inadvertent containment spray actuation.


During design bases accident conditions the IRWST provides a source of borated water to the SI pumps and CS pumps or SC pumps. As such, it supports containment cooling and depressurization, core cooling and maintaining cooling water inventory, RCS depressurization using feed and bleed methods, and keeping reactor SHUTDOWN MARGIN. The design basis transients and applicable safety analyses concerning each of these systems are discussed in the applicable safety analyses sections of Bases for LCOs 3.5.2, 3.5.3, and 3.6.6. These analyses are used to assess changes to the IRWST in order to evaluate their effects in relation to the acceptance limits.

The minimum volume in the IRWST of 2,373.5 m$^3$ (627,000 gal) is required for continuous SIS and CSS operation and used for safety analyses. The maximum volume of IRWST of 2,540.6 m$^3$ (671,162 gal) is determined such that the water surface is lower than the bottom of the reactor vessel, even if the IRWST water is flooded into the reactor cavity due to an inadvertent operation of the Cavity Flooding System during normal operation. A free space of 752.8 m$^3$ (26,584 ft$^3$) in the IRWST is assumed for a safety analysis of hydrogen concentration in IRWST. This free volume is guaranteed if the IRWST water volume is less than the maximum volume in the IRWST of 2,540.6 m$^3$ (671,162 gal).
The LOCA dose analyses assumes a volume of at least (2,370 m$^3$ (627,000 gal)) for dilution of radionuclide in water. The 4,000 ppm limit for minimum boron concentration was established to ensure that, following a LOCA with a minimum IRWST level, the reactor will remain subcritical in the cold condition following mixing of the IRWST and RCS water volumes. The safety analysis assumes that the boron has the minimum Boron-10 isotopic concentration limit specified in the COLR. Small break LOCAs assume that all control rods are inserted, except for the control element assembly (CEA) of highest worth, which is withdrawn from the core. Large break LOCAs assume that all CEAs remain withdrawn from the core. The most limiting case occurs at beginning of life.

The maximum boron limit of 4,400 ppm in the IRWST is based on boron precipitation in the core following a LOCA. With the reactor vessel at saturated conditions, the core dissipates heat by pool nucleate boiling. Because of this boiling phenomenon in the core, the boric acid concentration will increase in this region. If allowed to proceed in this manner, boron precipitation will occur in the core. Post LOCA emergency procedure directs the operator to establish simultaneous hot leg/DVI nozzle injection to prevent this condition by a forced flow through the core regardless of break location.

This procedure is based upon the minimum time in which precipitation could occur, assuming the maximum LCO limit of the IRWST boron concentration. Boron concentrations in the IRWST in excess of the limit could result in precipitation earlier than assumed in the analysis.

The safety analyses assumes the minimum allowed IRWST water temperature is 10°C (50°F) and the maximum temperature of the IRWST is 49°C (120°F).

The IRWST satisfies Criterion 3 of 10 CFR 50.36(c)(2)(ii).

LCO

The IRWST ensures that an adequate supply of borated water is available to cool and depressurize the containment in the event of a design basis accident (DBA) and to cool and cover the core in the event of a LOCA. The IRWST ensures the reactor remains subcritical following a DBA.

To be considered OPERABLE, the IRWST must meet the limits established in the SR for water volume, boron concentration and temperature.
The flow path for each train must maintain its designed independence to ensure that no single failure can prevent delivery of the minimum required flow rate.

APPLICABILITY

In MODES 1, 2, 3 and 4, the IRWST OPERABILITY requirements are dictated by the SIS and CSS OPERABILITY requirements. Since both the SIS and CSS must be OPERABLE in MODES 1, 2, 3 and 4, the IRWST must be OPERABLE to support these systems.

In MODES 5 and MODE 6 with RCS level < 39.7 m (130 ft), the IRWST OPERABILITY requirements are dictated by the SIS. The requirements of SIS are specified in LCO 3.5.3. Two trains of SIS, one in each division, are required in these MODES, therefore the IRWST must be OPERABLE to support the SIS.

MODE 6 considers a loss of decay heat removal (DHR) resulting from a break in the bottom of the hot leg or a lower head instrument line (2.8 cm² (0.003 ft²)). If the reactor coolant water level is above the reactor vessel flange (> 39.7 m (130 ft)), the low power shutdown risk is negligible because sufficient water inventory in refueling pool is available.

ACTIONS

A.1

With IRWST boron concentration, Boron-10 isotopic concentration or water temperature not within limits, they must be returned to within limits within 8 hours. In this condition neither the SIS nor the CSS can perform its design functions, therefore, prompt action must be taken to restore the tank to OPERABLE condition.

The allowed Completion Time of 8 hours to restore the IRWST boron concentration, Boron-10 isotopic concentration or temperature to within limits was developed considering the time required to change boron concentration or temperature, Boron-10 isotopic concentration and that the contents of the tank are still available for injection.

B.1

With IRWST water volume not within limits, it must be returned to within limits within 1 hour. In this condition neither the SIS nor the CSS can perform its design function; therefore, prompt action must be taken to restore the tank to OPERABLE status or to place the plant in a MODE in which these systems are not required. The Completion Time of 1 hour to
BASES

ACTIONS (continued)

restore the IRWST to OPERABLE is based on this condition simultaneously affecting multiple trains.

C.1, and C.2

If the IRWST cannot be returned to OPERABLE status within the associated Completion Time, the plant must be brought to a condition in which the LCO does not apply. To achieve this status, the plant must be brought to at least MODE 3 within 6 hours and to MODE 5 within 36 hours.

The allowed Completion Times are reasonable, based on operating experience, to reach the required plant condition from full power and shutdown conditions in an orderly manner and without challenging plant systems.

D.1 and D.2

The plant must be placed in a condition in which the LCO does not apply if SIS cannot be returned to OPERABLE status within the associated Completion Time. A Reactor Coolant System (RCS) level of > 39.7 m (130 ft) (the top of the reactor vessel flange) will provide a minimum water inventory in the event of a LOCA. In case that the reactor water level is below the reactor vessel flange with head off in MODE 6, one safety injection pump is required immediately after loss of coolant accident at the low power shutdown condition according to the shutdown LOCA safety analysis. If the reactor coolant water level is above the reactor vessel flange with head off in MODE 6, the low power shutdown risk is negligible because sufficient water inventory in refueling pool is available.

Therefore, the reactor flange water level above the reactor vessel flange with head off in MODE 6 does not require one safety injection pump after loss of coolant accident at low power shutdown risk. In addition, if RCS water level is below the flange of the reactor vessel, there is a potential of evaporation of the coolant. The reduction of RCS cold leg temperature to < 57.2°C (135°F) will provide a reduction in clad temperature. If RCS cold leg temperature reaches above 57.2°C (135°F), there is a potential to evaporate. The 24 hour Completion Time limits the time the plant is subject to conditions where the LCO is applicable.
IRWST water temperature shall be verified every 24 hours to be within the limits assumed in the accident analysis. This Frequency has been shown to be sufficient to identify temperature changes that approach either acceptable limit.

SR 3.5.4.2

The IRWST water volume must be maintained equal to or more than the required minimum value and equal to or less than the maximum value. IRWST water volume shall be verified every 7 days. Since the IRWST water volume is normally stable and provided with a low level alarm, a 7 day Frequency is appropriate and has been shown to be acceptable through operating experience.

SR 3.5.4.3

The boron concentration of the IRWST shall be verified every 7 days to be within the required range. This Frequency ensures that the reactor will remain subcritical following a LOCA. Further, it ensures that the resulting IRWST pH is maintained in an acceptable range such that boron precipitation in the core will not occur earlier than predicted and the effect of chloride and caustic stress corrosion on mechanical systems and components will be minimized. Since the IRWST volume is normally stable, a 7 day sampling Frequency is appropriate and has been shown through operating experience to be acceptable.

SR 3.5.4.4

Periodic verification that the isotopic concentration of Boron-10 in the IRWST is within the limit specified in the COLR ensures that the Boron-10 isotopic concentration assumed in the safety analysis is available. Since Boron-10 in the IRWST is not directly exposed to a significant neutron flux and the IRWST water is only mixed with the reactor coolant during refueling outages, the Frequency of 24 months is considered conservative. The Surveillance Frequency is based on operating experience, equipment reliability, and plant risk.

REFERENCES

1. 10 CFR Part 50, Appendix A, GDC 35.
B 3.5 EMERGENCY CORE COOLING SYSTEM (ECCS)

B 3.5.5 Trisodium Phosphate (TSP)

BASES

BACKGROUND

The in-containment refueling water storage tank (IRWST) is the suction source for the safety injection (SI) pumps and containment spray (CS) pumps during short-term injection and long-term cooling MODES of post-accident operation. Reactor coolant blown out through a break and water sprayed by the CS pumps during a loss of coolant accident (LOCA) is collected in the holdup volume tank (HVT). The accumulated water in the HVT overflows back into the IRWST, thereby the IRWST is replenished. Trisodium phosphate dodecahydrate (TSP) is placed in the baskets mounted on the wall of the HVT so that it can be dissolved without any operator action. The dissolved TSP prevents the iodine, which is dissolved in the collected reactor cooling water and sprayed water, from evolving to the air. TSP also helps inhibit stress corrosion cracking (SCC) of austenitic stainless steel components in containment during the long-term cooling phase following an accident.

Fuel that is damaged during a LOCA will release iodine in several chemical forms to the reactor coolant and to the containment atmosphere. A portion of the iodine in the containment atmosphere is washed to the HVT by containment sprays.

The emergency core cooling water is borated for reactivity control. This borated water causes the HVT solution to be acidic. In a low pH (acidic) solution, dissolved iodine will be converted to a volatile form. The volatile iodine will evolve out of solution into the containment atmosphere, significantly increasing the level of airborne iodine. The increased level of airborne iodine increases the radiological releases and consequences due to containment leakage following an accident.

After a LOCA, the components of the Core Cooling and Containment Spray Systems will be exposed to high temperature borated water. Prolonged exposure to the core cooling water combined with stresses imposed on the components can cause SCC. The SCC is a function of stress, oxygen and chloride concentrations, pH, temperature, and alloy composition of the components. High temperatures and low pH, which would be present after a LOCA, tend to promote SCC. This can lead to the failure of necessary safety systems or components.
Maintaining the pH of the solution circulated by SI and CS pumps above 7.0 prevents a significant fraction of the dissolved iodine from converting to a volatile form. The higher pH thus decreases the level of airborne iodine in containment and reduces the radiological consequences from containment atmosphere leakage following a LOCA. Maintaining the solution pH above 7.0 also reduces occurrences of SCC of austenitic stainless steel components in containment. Reducing SCC reduces the probability of failure of components.

TSP is employed as a passive form of pH control for post LOCA containment spray and core cooling water. TSP baskets are mounted on the wall of the HVT for TSP to be dissolved with the released reactor coolant water and containment sprayed water after a LOCA.

Recirculation of the water for core cooling and containment spray then provides mixing to achieve a uniform solution pH. The dodecahydrate form of TSP is used because of the humidity inside containment during normal operation. Since the TSP is hydrated, it is less likely to absorb large amounts of water from the humid atmosphere and will undergo less physical and chemical change than the anhydrous form of TSP.

APPLICABLE SAFETY ANALYSES

The LOCA radiological consequences analysis takes credit for iodine retention in the sump solution based on the recirculated water pH being ≥ 7.0. The radionuclide releases from the containment atmosphere and the consequences of a LOCA would be increased if the pH of the recirculated water were not adjusted to 7.0 or above.

TSP satisfies Criterion 3 of 10 CFR 50.36(c)(2)(ii).

LCO

The TSP is required to adjust the pH of the recirculated water to > 7.0 after a LOCA. A pH > 7.0 is necessary to prevent significant amounts of iodine released from fuel failures and dissolved in the recirculated water from converting to a volatile form and evolving into the containment atmosphere. Higher levels of airborne iodine in containment could increase the release of radionuclides and the consequences of the accident. A pH > 7.0 is also necessary to prevent SCC of austenitic stainless steel components in containment. SCC increases the probability of failure of components.
The required amount of TSP is based upon the extreme cases of water volume and pH possible in the HVT after a large break LOCA. The minimum required volume is the volume of TSP that will achieve a solution pH of $\geq 7.0$ when taking into consideration the maximum possible water volume and the minimum possible pH. The amount of TSP needed in the containment is based on the mass of TSP required to achieve the desired pH. However, a required volume is specified, rather than mass, since it is not feasible to weigh the entire amount of TSP in containment. The minimum required volume is based on the manufactured density of TSP. Since TSP can have a tendency to agglomerate due to humidity inside containment, the density may increase and the volume decrease during normal plant operation.

Due to possible agglomeration and increase in density, estimating the minimum volume of TSP in containment is conservative with respect to achieving a minimum required pH.

In MODES 1, 2, and 3, the Reactor Coolant System (RCS) is at elevated temperature and pressure, providing an energy potential for a LOCA. The potential for a LOCA results in a need for the ability to control the pH of the recirculated coolant.

In MODES 4, 5, and 6, the potential for a LOCA is reduced or nonexistent and TSP is not required.

If it is discovered that the TSP in the HVT is not within limit, action must be taken to restore the TSP to within limit. During plant operation, the HVT is not accessible and corrective ACTIONS may not be possible.

The Completion Time of 72 hours is allowed for restoring the TSP within limits, where possible, because 72 hours is the same time allowed for restoration of other ECCS variables.

If the TSP cannot be restored within limits within the Completion Time of Required Action A.1, the plant must be brought to a MODE in which the LCO does not apply. The specified Completion Times for reaching MODES 3 and 4 are chosen to allow reaching the specified conditions from full power in an orderly manner without challenging plant systems.
The stainless steel baskets, which are mounted on the walls of the HVT, have a solid top and bottom with mesh sides to permit submergence of the TSP. The elevation of the baskets is above the normal operating water level in the HVT and below the IRWST spillway. Access is provided to the baskets for inspection and sampling.

Periodic identification of the volume of TSP in the containment must be performed due to the possibility of leaking valves and components inside containment that could cause the dissolution of TSP during normal operation. It is required to determine visually with a Frequency of 18 months that a minimum of 29.5 m³ (1,042 ft³) is contained in the TSP baskets. This requirement ensures that there is a sufficient volume of TSP to maintain the pH of the post LOCA solution above 7.0.

The Surveillance Frequency is determined to be 18 months since access to the TSP baskets is only feasible during outages and normal fuel cycles are scheduled for 18 months. Operating experience has shown this Surveillance Frequency acceptable due to the margin in the volume of TSP placed in the containment.

Testing must be performed to ensure the solubility and pH control ability of the TSP is maintained after exposure to the containment environment. A representative sample of 30.3 g (6.7E-2 lb) of TSP from one of the baskets in containment is submerged in borated water of 3.8 ± 0.19 liters (1.0 ± 0.05 gallons) at the temperature of 25 ± 5°C (77 ± 9°F). Without agitation, the solution pH should be raised to 7.0 or above within 4 hours. The representative sample weight is based on the minimum required TSP weight of 26,471 kg (58,358 lb), which corresponds to a minimum volume of 29.5 m³ (1,042 ft³) at manufactured density, normalized to buffer a 3.8 liters (1.0 gallon) sample. The boron concentration of the test water is representative of the maximum possible boron concentration corresponding to the maximum possible post LOCA recirculation water volume. Agitation of the test solution is prohibited, since an adequate standard for the agitation intensity cannot be specified. The test time of 4 hours is necessary to allow time for the dissolved TSP to naturally diffuse through the sample solution. Since the TSP and boated water would mix in the HVT following a LOCA better than the test without agitation, it takes considerably less time to achieve the required pH actually.
This would ensure compliance with the Standard Review Plan (SRP) requirement of a pH $\geq 7.0$ by the onset of recirculation after a LOCA.

The Surveillance Frequency is determined to be 18 months, since access to the TSP baskets is only feasible during outages, and normal fuel cycles are scheduled for 18 months. Operating experience has shown this Surveillance Frequency acceptable due to the margin in the volume of TSP placed in the containment.

REFERENCES
None.
BACKGROUND

The containment consists of the concrete reactor building (RB), its steel liner, and the penetrations through this structure. The structure is designed to contain radioactive material that could be released from the reactor core following a design basis loss of coolant accident (LOCA). Additionally, this structure provides shielding from the fission products that could be present in the containment atmosphere following accident conditions.

The containment is a reinforced concrete structure with a cylindrical wall, a flat foundation mat, and a shallow dome roof. For containments with ungrouted tendons, the cylinder wall is prestressed with a post tensioning system in the vertical and horizontal directions, and the dome roof is prestressed using a three way post tensioning system. The inside surface of the containment is lined with a carbon steel liner to ensure a high degree of leak tightness during operating and accident conditions.

The concrete RB is required for structural integrity of the containment under design basis accident (DBA) conditions.

The steel liner and its penetrations establish the leakage limiting boundary of the containment. Maintaining the containment OPERABLE limits the leakage of fission product radioactivity from the containment to the environment. SR 3.6.1.1 leakage rate requirements comply with 10 CFR Part 50, Appendix J, Option B (Ref. 1).

The isolation devices for the penetrations in the containment boundary are a part of the containment leak tight barrier. To maintain this leak tight barrier:

a. All penetrations required to be closed during accident conditions are either:

   1. Capable of being closed by an OPERABLE automatic Containment Isolation System; or

   2. Closed by manual valves, blind flanges, or de-activated automatic valves secured in their closed positions, except as provided in LCO 3.6.3, “Containment Isolation Valves.”;

b. Each airlock is OPERABLE except as provided in LCO 3.6.2, “Containment Airlocks.”;
c. All equipment hatches are closed; and

d. The pressurized sealing mechanism associated with a penetration, except as provided in LCO 3.6.1, is OPERABLE.

The safety design basis for the containment is that the containment must withstand the pressures and temperatures of the limiting DBA without exceeding the design leakage rate.

The DBAs which result in a release of radioactive material within containment are a LOCA, a main steam line break (MSLB), a main feedwater line break (MFLB), and a control element assembly (CEA) ejection accident (Ref. 2).

In the analysis of each of these accidents, it is assumed that the containment is OPERABLE at event initiation such that the majority of the release of fission products to the environment is controlled by the rate of containment leakage. In addition, for the above accidents, it is assumed that the containment low volume purge is operating at event initiation. Isolation of the purge will be automatic or manual depending upon the pressure transient associated with the analyzed accident.

The containment was designed with an allowable leakage rate of 0.1% of the containment air weight per day (Ref. 3). This leakage rate, used in the evaluation of offsite doses resulting from accidents, is defined in 10 CFR Part 50, Appendix J, Option B, as $L_a$: the maximum allowable containment leakage rate at the calculated maximum peak containment pressure (Pa) following a DBA. The calculated maximum peak containment pressure 3.60 kg/cm$^2$G (51.21 psig) was obtained from a double ended discharge leg slot break (DEDLSB) with maximum Emergency Core Cooling System (ECCS) flow. The containment internal design pressure is 4.218 kg/cm$^2$G (60 psig). The allowable leakage rate represented by $L_a$ forms the basis for the acceptance criteria imposed on all containment leak rate testing.

Satisfactory leak test results are a requirement for the establishment of containment OPERABILITY.

The acceptance criteria applied to accidental releases of radioactive material to the environment are given in terms of total effective dose (TED) received by a member of the general public who remains at the exclusion area boundary for any two hour period following onset of the postulated fission product release. The limit established in Reference 4 is 0.25 Sv (25 rem) total effective dose.
The containment satisfies Criterion 3 of 10 CFR 50.36(c)(2)(ii).

Containment OPERABILITY is maintained by limiting leakage to $\leq 1.0 \text{ L}_a$, except prior to the first startup after performing a required Containment Leakage Rate Testing Program leakage test. At this time, the applicable leakage limits must be met. Compliance with this LCO will ensure a containment configuration, including equipment hatches, that is structurally sound and that will limit leakage to those leakage rates assumed in the safety analysis.

Individual leakage rates specified for the containment airlocks (LCO 3.6.2), and purge valves with resilient seals (LCO 3.6.3) are not specifically part of the acceptance criteria of 10 CFR Part 50, Appendix J. Therefore, leakage rates exceeding these individual limits only result in the containment being inoperable when the leakage results in exceeding the overall acceptance criteria of $1.0 \text{ L}_a$.

In MODES 1, 2, 3, and 4, a DBA could cause a release of radioactive material into containment. In MODES 5 and 6, the probability and consequences of these events are reduced due to the pressure and temperature limitations of these MODES. Therefore, containment is not required to be OPERABLE in MODE 5 to prevent leakage of radioactive material from containment. The requirements for containment during MODES 5 and 6 are addressed in LCOs 3.9.3, “Containment Penetrations” and 3.6.7, “Containment Penetrations - Shutdown Operations.”

In the event containment is inoperable, containment must be restored to OPERABLE status within 1 hour. The 1 hour Completion Time provides a period of time to correct the problem commensurate with the importance of maintaining containment OPERABLE during MODES 1, 2, 3, and 4. This time period also ensures that the probability of an accident (requiring containment OPERABILITY) occurring during periods where containment is inoperable is minimal.
Bases

Actions (continued)

B.1 and B.2

If containment cannot be restored to OPERABLE status in the associated Completion Time, the plant must be placed in a MODE in which the LCO does not apply. To achieve this status, the plant must be brought to at least MODE 3 within 6 hours and to MODE 5 within 36 hours. The allowed Completion Times are reasonable, based on operating experience, to reach the required plant conditions from full power conditions in an orderly manner and without challenging plant systems.

Surveillance Requirements

SR 3.6.1.1

Maintaining containment OPERABLE requires compliance with the visual examinations and leakage rate test requirements of Containment Leakage Rate Testing Program.

The containment concrete visual examinations may be performed during either power operation (e.g., concurrently with other containment inspection-related activities such as tendon testing) or during a maintenance or refueling outage. The visual examinations of the steel liner plate inside containment are performed during maintenance or refueling outages since this is the only time the liner plate is fully accessible.

Failure to meet airlock and purge valve with resilient seal specific leakage limits specified in LCOs 3.6.2 and 3.6.3 does not invalidate the acceptability of these overall leakage determinations unless their contribution to overall Type A, B, and C leakage causes limits to be exceeded. As left leakage prior to the startup after performing a required Containment Leakage Rate Testing Program is required to be \( \leq 0.6 \ L_a \) for combined Type B and C leakage and \( \leq 0.75 \ L_a \) for option B for overall Type A leakage.

At all other times between required leakage rate tests, the acceptance criteria is based on an overall Type A leakage limit of \( \leq 1.0 \ L_a \). At \( \leq 1.0 \ L_a \), the offsite dose consequences are bounded by the assumptions of the safety analysis.

SR Frequencies are as required by the Containment Leakage Rate Testing Program. These periodic testing requirements verify that the containment leakage rate does not exceed the leakage rate assumed in the safety analysis.
Bases

Surveillance Requirements (continued)

SR 3.6.1.2

For ungrouted, post tensioned tendons, this SR ensures that the structural integrity of the containment will be maintained in accordance with the provisions of the Containment Tendon Surveillance Program. Testing and Frequency are consistent with the ASME Code, Section XI, Subsection IWL (Ref. 5) and applicable addenda as required by 10 CFR 50.55a.

References

1. 10 CFR Part 50, Appendix J, Option B.
2. FSAR, Chapter 15.
3. FSAR, Section 6.2.
4. 10 CFR 50.34.
5. ASME Section XI, Subsection IWL.
B 3.6 CONTAINMENT SYSTEMS

B 3.6.2 Containment Airlocks

BASES

BACKGROUND

Two containment airlocks form part of the containment pressure boundary and provide a means for personnel access during all MODES of operation.

Each airlock is nominally a right circular cylinder 3.05 m (10 ft) in diameter with a door at each end. The doors are interlocked to prevent simultaneous opening. During periods when containment is not required to be OPERABLE, the door interlock mechanism may be disabled, allowing both doors to remain open for extended periods when frequent containment entry is necessary. Each airlock door has been designed and tested to certify its ability to withstand a pressure in excess of the maximum expected pressure following a design basis accident (DBA) in containment. As such, closure of a single door supports containment OPERABILITY. Each of the doors contains double gasketed seals and local leakage rate testing capability to ensure pressure integrity. To ensure a leak tight seal, the airlock design uses pressure seated doors (i.e., an increase in containment internal pressure results in increased sealing force on each door).

Each personnel air lock is provided with limit switches on both doors that provide main control room (MCR) indication of door position. Additionally, MCR indication is provided to alert the operator whenever an airlock door interlock mechanism is defeated.

The containment airlocks form part of the containment pressure boundary. As such, airlock integrity and leak tightness is essential for maintaining the containment leakage rate within limit in the event of a DBA. Not maintaining airlock integrity or leak tightness could result in a leakage rate in excess of that assumed in the unit safety analysis.

APPLICABLE SAFETY ANALYSES

For atmospheric containment the DBAs that result in a release of radioactive material within containment are a loss of coolant accident (LOCA), a main steam line break (MSLB), a main feedwater line break (MFLB), and a control element assembly (CEA) ejection accident (Ref. 1). In the analysis of each of these accidents, it is assumed that containment is OPERABLE at event initiation, such that release of fission products to the environment is controlled by the rate of containment leakage.
APPLICABLE SAFETY ANALYSES (continued)

The containment was designed with an allowable leakage rate of 0.1% of containment air weight per day (Ref. 2). This leakage rate is defined in 10 CFR Part 50, Appendix J, Option A, as \(L_a\): the maximum allowable containment leakage rate at the calculated maximum peak containment pressure \(P_{a}\) of 3.60 kg/cm\(^2\)G (51.21 psig), which results from the limiting DBA (a double ended discharge leg slot break (DEDLSB) with maximum Emergency Core Cooling System (ECCS) flow) (Ref. 2). This allowable leakage rate forms the basis for the acceptance criteria imposed on the SR associated with the airlock.

The containment airlocks satisfy Criterion 3 of 10 CFR 50.36(c)(2)(ii).

LCO

Each containment airlock forms part of the containment pressure boundary. As part of containment, the airlock safety function is related to control of the containment leakage rate resulting from a DBA. Thus, each airlock's structural integrity and leak tightness are essential to the successful mitigation of such an event.

Two airlocks are required to be OPERABLE. For the airlock to be considered OPERABLE, the airlock interlock mechanism must be OPERABLE, the airlock must be in compliance with the Type B airlock leakage test, and both airlock doors must be OPERABLE. The interlock allows only one airlock door of an airlock to be opened at one time. This provision ensures that a gross breach of containment does not exist when containment is required to be OPERABLE. Closure of a single door in each airlock is sufficient to provide a leak tight barrier following postulated events. Nevertheless, both doors are kept closed when the airlock is not being used for normal entry into and exit from containment.

APPLICABILITY

In MODES 1, 2, 3, and 4, a DBA could cause a release of radioactive material to containment. In MODES 5 and 6, the probability and consequences of these events are reduced due to the pressure and temperature limitations of these MODES. Therefore, the containment airlocks are not required in MODE 5 to prevent leakage of radioactive material from containment. The requirements for the containment airlocks during MODE 6 are addressed in LCO 3.9.3, “Containment Penetrations.” In MODE 5 with any RCS loop not filled, and in MODE 6 with the refueling pool water level < 7.0 m (23 ft) above the top of the reactor vessel flange, the requirements of the containment air locks are addressed in LCO 3.6.7, “Containment Penetrations – Shutdown Operations.”
**BASES**

**ACTIONS**
The ACTIONS are modified by a Note that allows entry and exit to perform repairs on the affected airlock component. If the outer door is inoperable, then it can be easily accessed for most repairs. It is preferred that the airlock be accessed from inside containment by entering through the other OPERABLE airlock. However, if this is not practicable, or if repairs on either door must be performed from the barrel side of the door then it is permissible to enter the airlock through the OPERABLE door, which means there is a short time during which the containment boundary is not intact (during access through the outer door). The ability to open the OPERABLE door, even if it means the containment boundary is temporarily not intact, is acceptable because of the low probability of an event that could pressurize the containment during the short time in which the OPERABLE door is expected to be open. After each entry and exit, the OPERABLE door must be immediately closed. If As Low As Reasonably Achievable (ALARA) conditions permit, entry and exit should be via an OPERABLE airlock.

A second Note has been added to provide clarification that, for this LCO, separate Condition entry is allowed for each airlock. This is acceptable, since the Required Actions for each Condition provide appropriate compensatory action for each inoperable airlock. Complying with the Required Actions may allow for continued operation, and a subsequent inoperable airlock is governed by subsequent condition entry and application of associated Required Actions. A third Note has been included that requires entry into the applicable Conditions and Required Actions of LCO 3.6.1, “Containment,” when leakage results in exceeding the overall containment leakage limit.

**A.1, A.2, and A.3**

With one airlock door inoperable in one or more containment airlocks, the OPERABLE door must be verified closed (Required Action A.1) in each affected containment airlock. This ensures that a leak tight containment barrier is maintained by the use of an OPERABLE airlock door. This action must be completed within 1 hour. This specified time period is consistent with the ACTIONS of LCO 3.6.1 which requires containment be restored to OPERABLE status within 1 hour.

In addition, the affected airlock penetration must be isolated by locking closed an OPERABLE airlock door within the 24 hour Completion Time. The 24 hour Completion Time is considered reasonable for locking the OPERABLE airlock door considering the OPERABLE door of the affected airlock is being maintained closed.
Required Action A.3 verifies that an airlock with an inoperable door has been isolated by the use of a locked and closed OPERABLE airlock door. This ensures that an acceptable containment leakage boundary is maintained. The Completion Time of once per 31 days is based on engineering judgment and is considered adequate in view of the low likelihood of a locked door being mispositioned and other administrative controls. Required Action A.3 is modified by a Note that applies to airlock doors located in high radiation areas and allows these doors to be verified locked closed by use of administrative means. Allowing verification by administrative means is considered acceptable, since access to these areas is typically restricted. Therefore, the probability of misalignment of the door, once it has been verified to be in the proper position, is small.

The Required Actions have modified by two Notes. Note 1 ensures that only the Required Actions and associated Completion Times of Condition C are required if both doors in the same airlock are inoperable. With both doors in the same airlock inoperable, an OPERABLE door is not available to be closed. Required Actions C.1 and C.2 are the appropriate remedial actions. The exception of Note 1 does not affect tracking the Completion Time from the initial entry into Condition A; only the requirement to comply with the Required Actions. Note 2 allows use of the airlock for entry and exit for 7 days under administrative controls if both airlocks have an inoperable door.

This 7 day restriction begins when the second airlock is discovered inoperable. Containment entry may be required to perform Technical Specifications (TS) Surveillances and Required Actions, as well as other activities on equipment inside containment that are required by TS or activities on equipment that support TS-required equipment. This Note is not intended to preclude performing other activities (i.e., non-TS-required activities) if the containment was entered, using the inoperable airlock, to perform an allowed activity listed above.

This allowance is acceptable due to the low probability of an event that could pressurize the containment during the short time that the OPERABLE door is expected to be open.

B.1, B.2, and B.3

With an airlock door interlock mechanism inoperable in one or more airlocks, the Required Actions and associated Completion Times are consistent with those specified in Condition A.
The Required Actions have been modified by two Notes. Note 1 ensures that only the Required Actions and associated Completion Times of Condition C are required if both doors in the same airlock are inoperable. With both doors in the same airlock inoperable, an OPERABLE door is not available to be closed. Required Actions C.1 and C.2 are the appropriate remedial actions. Note 2 allows entry into and exit from containment under the control of a dedicated individual stationed at the airlock to ensure that only one door is opened at a time (i.e., the individual performs the function of the interlock).

Required Action B.3 is modified by a Note that applies to airlock doors located in high radiation areas and allows these doors to be verified locked closed by use of administrative means. Allowing verification by administrative means is considered acceptable, since access to these areas is typically restricted. Therefore, the probability of misalignment of the door, once it has been verified to be in the proper position, is small.

C.1, C.2, and C.3

With one or more airlocks inoperable for reasons other than those described in Condition A or B, Required Action C.1 requires action to be initiated immediately to evaluate previous combined leakage rates per LCO 3.6.1, “Containment,” using current airlock test results. An evaluation is acceptable since it is overly conservative to immediately declare the containment inoperable if both doors in an airlock have failed a seal test or if the overall airlock leakage is not within limits. In many instances (e.g., only one seal per door has failed), containment remains OPERABLE, yet only 1 hour (per LCO 3.6.1) would be provided to restore the airlock door to OPERABLE status prior to requiring a plant shutdown. In addition, even with both doors failing the seal test, the overall containment leakage rate can still be within limits.

Required Action C.2 requires that one door in the affected containment airlock must be verified to be closed. This action must be completed within the 1 hour Completion Time. This specified time period is consistent with the ACTIONS of LCO 3.6.1, which requires that containment be restored to OPERABLE status within 1 hour.

Additionally, the affected airlocks must be restored to OPERABLE status within the 24 hour Completion Time. The specified time period is considered reasonable for restoring an inoperable airlock to OPERABLE status, assuming that at least one door is maintained closed in each affected airlock.
D.1 and D.2

If the inoperable airlock cannot be restored to OPERABLE status within the required Completion Time, the plant must be placed in a MODE in which the LCO does not apply. To achieve this status, the plant must be brought to at least MODE 3 within 6 hours and to MODE 5 within 36 hours. The allowed Completion Times are reasonable, based on operating experience, to reach the required plant conditions from full power conditions in an orderly manner and without challenging plant systems.

SR 3.6.2.1

Maintaining containment airlocks OPERABLE requires compliance with the leakage rate test requirements of Containment Leakage Rate Testing Program (Ref. 3). This SR reflects the leakage rate testing requirements with regard to airlock leakage (Type B leakage tests). The acceptance criteria were established during initial airlock and containment OPERABILITY testing. The periodic testing requirements verify that the airlock leakage does not exceed the allowed fraction of the overall containment leakage rate. The Frequency is required by Containment Leakage Rate Testing Program. Thus, SR 3.0.2 (which allows Frequency extensions) does not apply.

The SR has been modified by two Notes. Note 1 states that an inoperable airlock door does not invalidate the previous successful performance of the overall airlock leakage test. This is considered reasonable since either airlock door is capable of providing a fission product barrier in the event of a DBA. Note 2 requires the results to be evaluated against the acceptance criteria of SR 3.6.1.1. This ensures that airlock leakage is properly accounted for in determining the overall containment leakage rate.

SR 3.6.2.2

The airlock door interlock is designed to prevent simultaneous opening of both doors in a single airlock. Since both the inner and outer doors of an airlock are designed to withstand the maximum expected post-accident containment pressure, closure of either door will support containment OPERABILITY. Thus, the door interlock feature supports containment OPERABILITY while the airlock is being used for personnel transit into and out of containment. Periodic testing of this interlock demonstrates that the interlock will function as designed and that simultaneous opening
of the inner and outer doors will not inadvertently occur. Due to the purely mechanical nature of this interlock, and given that the interlock mechanism is not normally challenged when the containment airlock door is used for entry and exit (procedures require strict adherence to single door opening), this test is only required to be performed upon entering containment but is not required more frequently than every 24 months.

The 24 month Frequency is based on the need to perform this Surveillance under the conditions that apply during a plant outage, and the potential for loss of containment OPERABILITY if the Surveillance were performed with the reactor at power. The 24 month Frequency for the interlock is justified based on generic operating experience. The 24 month Frequency is based on engineering judgment and is considered adequate given that the interlock is not challenged during the use of the airlock.

REFERENCES

1. FSAR, Chapter 15.
2. FSAR, Section 6.2.
3. 10 CFR Part 50, Appendix J, Option B.
B 3.6 CONTAINMENT SYSTEMS

B 3.6.3 Containment Isolation Valves

BASES

BACKGROUND

The containment isolation valves form part of the containment pressure boundary and provide a means for fluid penetrations not serving accident consequence limiting systems to be provided with two isolation barriers that are closed on an automatic isolation signal. These isolation devices are either passive or active (automatic). Manual valves, deactivated automatic valves secured in their closed position (including check valves with flow through the valve secured), blind flanges, and closed systems are considered passive devices. Check valves or other automatic valves designed to close without operator action following an accident are considered active devices. Two barriers in series are provided for each penetration so that no single credible failure or malfunction of an active component can result in a loss of isolation or leakage that exceeds limits assumed in the accident analysis. One of these barriers may be a closed system.

Containment isolation occurs upon receipt of a high containment pressure signal or a low Reactor Coolant System (RCS) pressure signal. The containment isolation signal closes automatic containment isolation valves in fluid penetrations not required for operation of Engineered Safety Feature Systems in order to prevent leakage of radioactive material. Upon actuation of safety injection, automatic containment isolation valves also isolate systems not required for containment or RCS heat removal. Other penetrations are isolated by the use of valves in the closed position or blind flanges. As a result, the containment isolation valves (and blind flanges) help ensure that the containment atmosphere will be isolated in the event of a release of radioactive material to containment atmosphere from the RCS following a design basis accident (DBA).

The OPERABILITY requirements for containment isolation valves help ensure that containment is isolated within the time limits assumed in the safety analysis. Therefore, the OPERABILITY requirements provide assurance that containment function assumed in the accident analysis will be maintained.

Containment purge valves were designed for intermittent operation, providing a means of removing airborne radioactivity caused by minor RCS LEAKAGE prior to personnel entry into containment. There are two sets of purge valves: high volume purge valves and low volume purge valves. The Containment High Volume Purge System and Low Volume Purge System purge the containment atmosphere to the unit vent. The high volume purge and low volume purge supply and exhaust lines are
Background (continued)

Each supplied with inside and outside containment isolation valves. The high volume purge valves are designed for purging the containment atmosphere to the unit stack while introducing filtered make up from the outside to provide adequate ventilation for personnel comfort when the unit is shutdown during refueling operations and maintenance. The Low Volume Purge System is a pressure relief system that is used to relieve containment pressure during startup or shutdown. These containment isolation valves (with the exception of check valves used as containment isolation valves) are operated manually from the main control room (MCR). The valves will close automatically upon receipt of a Containment purge isolation signal. Air operated valves fail closed upon a loss of instrument air. Because of their large size, the high volume purge containment isolation valves are not qualified for automatic closure from their open position under DBA conditions. Therefore, the high volume purge containment isolation valves (supply and exhaust) are normally maintained closed in MODES 1, 2, 3, and 4 to ensure the containment boundary is maintained.

Open high volume purge valves or failure of the low volume purge valves to close, following an accident that releases contamination to the containment atmosphere, would cause a significant increase in the containment leakage rate.

Applicable Safety Analyses

The containment isolation valve LCO was derived from the requirements related to minimizing the loss of reactor coolant inventory and establishing the containment boundary resulting from major accidents. As part of the containment boundary, containment isolation valve and containment purge valve OPERABILITY support leak tightness of the containment. Therefore, the safety analysis of any event requiring isolation of containment is applicable to this LCO.

The DBAs that result in a release of radioactive material within containment are a loss of coolant accident (LOCA), a main steam line break (MSLB), a main feedwater line break (MFLB), or a control element assembly (CEA) ejection accident. In the analysis for each of these accidents, it is assumed that containment isolation valves are either closed or function to close within the required isolation time following event initiation.

This ensures that potential leakage paths to the environment through containment isolation valves (including containment purge valves) are minimized. The safety analysis assumes that the high volume purge valves are closed at event initiation.
The DBA analysis assumes that, within 60 seconds after the accident, isolation of the containment is complete and leakage terminated except for the design leak rate ($L_d$). The containment isolation total response time of 60 seconds includes signal delay, diesel generator startup (for loss of offsite power), and containment isolation valve stroke times.

The single failure criteria required to be imposed in the conduct of unit safety analyses was considered in the design of the containment purge valves. Two valves in series on each purge line provide assurance that both the supply and exhaust lines could be isolated even if a single failure occurred. The inboard and outboard isolation valves on each line are provided with diverse power sources motor operated and pneumatically operated spring closed, respectively. This arrangement was designed to preclude common mode failures from disabling both valves on a purge line.

The high volume purge valves could be unable to close in the environment following a LOCA. Therefore, each of the high volume purge valves is required to remain sealed closed during MODES 1, 2, 3, and 4. In this case, the single failure criteria remain applicable to the containment purge valves due to failure in the control circuit associated with each valve. Again, the purge system valve design precludes a single failure from compromising the containment boundary as long as the system is operated in accordance with the subject LCO. The low volume purge valves are capable of closing under accident conditions. Therefore, they are allowed to be open for limited periods during power operation.

The containment isolation valves satisfy Criterion 3 of 10 CFR 50.36(c)(2)(ii).

**LCO**

Containment isolation valves form a part of the containment boundary. The containment isolation valve safety function is related to minimizing the loss of reactor coolant inventory and establishing the containment boundary during a DBA.

The automatic power operated isolation valves are required to have isolation times within limits and to actuate on an automatic isolation signal. The purge valves must be maintained sealed closed. The valves covered by this LCO are listed with their associated stroke times in Chapter 6 (Ref. 1).
The normally closed isolation valves are considered OPERABLE when manual valves are closed, automatic valves are de-activated and secured in their closed position, blind flanges are in place, and closed systems are intact. These passive isolation valves or devices are those listed in Chapter 6 (Ref. 1).

Purge valves with resilient seals must meet additional leakage rate requirements. The other containment isolation valve leakage rates are addressed by LCO 3.6.1, “Containment,” as Type C testing.

This LCO provides assurance that the containment isolation valves and purge valves will perform their designed safety function to minimize the loss of reactor coolant inventory and establish the containment boundary during accidents.

In MODES 1, 2, 3 and 4, a DBA could cause a release of radioactive material to containment. In MODES 5 and 6, the probability and consequences of these events are reduced due to the pressure and temperature limitations of these MODES. Therefore, the containment isolation valves are not required to be OPERABLE in MODE 5. The requirements for containment isolation valves during MODE 6 are addressed in LCO 3.9.3, “Containment Penetrations.”

The ACTIONS are modified by a Note allowing penetration flow paths, except for 1219.2 mm (48 in) purge valve penetration flow paths, to be unisolated intermittently under administrative controls. These administrative controls consist of stationing a dedicated operator at the valve controls in continuous communication with the MCR. In this way, the penetration can be rapidly isolated when a need for containment isolation is indicated. Due to the size of the containment purge line penetration and the fact that those penetrations exhaust directly from the containment atmosphere to the environment, these valves may not be opened under administrative controls.

A second Note has been added to provide clarification that, for this LCO, separate Condition entry is allowed for each penetration flow path. This is acceptable, since the Required Actions for each Condition provide appropriate compensatory actions for each inoperable containment isolation valve. Complying with the Required Actions may allow for continued operation, and subsequent inoperable containment isolation valves are governed by subsequent condition entry and application of associated Required Actions.
The ACTIONS are further modified by a third Note, which ensures that appropriate remedial actions are taken, if necessary, if the affected systems are rendered inoperable by an inoperable containment isolation valve.

A fourth Note has been added that requires entry into the applicable Conditions and Required Actions of LCO 3.6.1 when leakage results in exceeding the overall containment leakage limit.

A.1 and A.2

In the event one containment isolation valve in one or more penetration flow paths is inoperable except for purge valve leakage not within limit, the affected penetration flow path must be isolated. The method of isolation must include the use of at least one isolation barrier that cannot be adversely affected by a single active failure. Isolation barriers that meet this criterion are a closed and de-activated automatic containment isolation valve, a closed manual valve, a blind flange, and a check valve with flow through the valve secured. For penetrations isolated in accordance with Required Action A.1, the valve used to isolate the penetration should be the closest available one to containment. Required Action A.1 must be completed within the 4 hour Completion Time. The 4 hour Completion Time is reasonable, considering the time required to isolate the penetration and the relative importance of supporting containment OPERABILITY during MODES 1, 2, 3, and 4.

For affected penetrations which cannot be restored to OPERABLE status within the 4 hour Completion Time and that have been isolated in accordance with Required Action A.1, the affected penetration flow paths must be verified to be isolated on a periodic basis. This is necessary to ensure that containment penetrations required to be isolated following an accident and no longer capable of being automatically isolated will be in the isolation position should an event occur. This Required Action does not require any testing or valve manipulation. Rather, it involves verification that those isolation devices outside containment and capable of being mispositioned are in the correct position.

The Completion Time of "once per 31 days for isolation devices outside containment" is appropriate considering the fact that the devices are operated under administrative controls and the probability of their misalignment is low. For the isolation devices inside containment, the time period specified as “prior to entering MODE 4 from MODE 5 if not performed within the previous 92 days” is based on engineering judgment and is considered reasonable in view of the inaccessibility of the isolation...
Containment Isolation Valves

B 3.6.3

BASES

ACTIONS (continued)

devices and other administrative controls that will ensure that isolation device misalignment is an unlikely possibility.

Condition A has been modified by a Note indicating that this Condition is only applicable to those penetration flow paths with two or more containment isolation valves. For penetration flow paths with only one containment isolation valve and a closed system, Condition C provides appropriate actions.

Required Action A.2 is modified by two Notes. Note 1 applies to isolation devices located in high radiation areas and allows these devices to be verified closed by use of administrative means. Allowing verification by administrative means is considered acceptable, since access to these areas is typically restricted. Note 2 applies to isolation devices that are locked, sealed, or otherwise secured in position and allows these devices to be verified closed by use of administrative means. Allowing verification by administrative means is considered acceptable, since the function of locking, sealing, or securing components is to ensure that these devices are not inadvertently repositioned. Therefore, the probability of misalignment of these devices, once they have been verified to be in the proper position, is small.

B.1

With two containment isolation valves in one or more penetration flow paths inoperable except for purge valve leakage not within limit, the affected penetration flow path must be isolated within 1 hour. The method of isolation must include the use of at least one isolation barrier that cannot be adversely affected by a single active failure. Isolation barriers that meet this criterion are a closed and de-activated automatic valve, a closed manual valve, and a blind flange. The 1 hour Completion Time is consistent with the ACTIONS of LCO 3.6.1. In the event the affected penetration is isolated in accordance with Required Action B.1, the affected penetration must be verified to be isolated on a periodic basis per Required Action A.2, which remains in effect. This periodic verification is necessary to assure leak tightness of containment and that penetrations requiring isolation following an accident are isolated.

The Completion Time of once per 31 days for verifying each affected penetration flow path is isolated is appropriate considering the fact that the valves are operated under administrative controls and the probability of their misalignment is low.
Condition B is modified by a Note indicating this Condition is only applicable to penetration flow paths with two or more containment isolation valves. Condition A of this LCO addresses the condition of one containment isolation valve inoperable in this type of penetration flow path.

**C.1 and C.2**

With one or more penetration flow paths with one containment isolation valve inoperable, the inoperable valve must be restored to OPERABLE status or the affected penetration flow path must be isolated. The method of isolation must include the use of at least one isolation barrier that cannot be adversely affected by a single active failure. Isolation barriers that meet this criterion are a closed and de-activated automatic valve, a closed manual valve, and a blind flange. A check valve may not be used to isolate the affected penetration. Required Action C.1 must be completed within the 4 hour Completion Time. The specified time period is reasonable, considering the relative stability of the closed system (hence, reliability) to act as a penetration isolation boundary and the relative importance of supporting containment OPERABILITY during MODES 1, 2, 3, and 4. In the event the affected penetration is isolated in accordance with Required Action C.1, the affected penetration flow path must be verified to be isolated on a periodic basis. This is necessary to assure leak tightness of containment and that containment penetrations requiring isolation following an accident are isolated. The Completion Time of once per 31 days for verifying that each affected penetration flow path is isolated is appropriate considering the valves are operated under administrative controls and the probability of their misalignment is low.

Condition C is modified by a Note indicating that this Condition is only applicable to those penetration flow paths with only one containment isolation valve and a closed system. This Note is necessary since this Condition is written to specifically address those penetration flow paths in a closed system.

Required Action C.2 is modified by a Note that applies to valves and blind flanges located in high radiation areas and allows these devices to be verified closed by use of administrative means. Allowing verification by administrative means is considered acceptable, since access to these areas is typically restricted. Therefore, the probability of misalignment of these valves, once they have been verified to be in the proper position, is small.
D.1, D.2, and D.3

In the event one or more containment purge valves in one or more penetration flow paths are not within the purge valve leakage limits, purge valve leakage must be restored to within limits, or the affected penetration must be isolated. The method of isolation must be by the use of at least one isolation barrier that cannot be adversely affected by a single active failure. Isolation barriers that meet this criterion are a closed and deactivated automatic valve with resilient seals, a closed manual valve with resilient seals, or a blind flange. A purge valve with resilient seals used to satisfy Required Action D.1 must have been demonstrated to meet the leakage requirements of SR 3.6.3.6. The specified Completion Time is reasonable, considering that one containment purge valve remains closed so that a gross breach of containment does not exist.

In accordance with Required Action D.2, this penetration flow path must be verified to be isolated on a periodic basis. The periodic verification is necessary to ensure that containment penetrations required to be isolated following an accident, which are no longer capable of being automatically isolated, will be in the isolation position should an event occur. This Required Action does not require any testing or valve manipulation. Rather, it involves verification that those isolation devices outside containment capable of being mispositioned are in the correct position. For the isolation devices inside containment, the time period specified as “prior to entering MODE 4 from MODE 5 if not performed within the previous 92 days” is based on engineering judgment and is considered reasonable in view of the inaccessibility of the isolation devices and other administrative controls that will ensure that isolation device misalignment is an unlikely possibility.

Required Action D.2 is modified by two Notes. Note 1 applies to isolation devices located in high radiation areas and allows these devices to be verified closed by use of administrative means. Allowing verification by administrative means is considered acceptable, since access to these areas is typically restricted. Note 2 applies to isolation devices that are locked, sealed, or otherwise secured in position and allows these devices to be verified closed by use of administrative means. Allowing verification by administrative means is considered acceptable, since the function of locking, sealing, or securing components is to ensure that these devices are not inadvertently repositioned.
For the containment purge valve with resilient seal that is isolated in accordance with Required Action D.1, SR 3.6.3.6 must be performed at least once every 92 days. This assures that degradation of the resilient seal is detected and confirms that the leakage rate of the containment purge valve does not increase during the time the penetration is isolated. The normal Frequency for SR 3.6.3.6 (184 days) is based on Generic Issue B-20 (Ref. 2). Since more reliance is placed on a single valve while in this Condition, it is prudent to perform the SR more often. Therefore, a Frequency of once per 92 days was chosen and has been shown to be acceptable based on operating experience.

E.1 and E.2

If the Required Actions and associated Completion Times are not met, the plant must be brought to a MODE in which the LCO does not apply. To achieve this status, the plant must be brought to at least MODE 3 within 6 hours and to MODE 5 within 36 hours. The allowed Completion Times are reasonable, based on operating experience, to reach the required plant conditions from full power conditions in an orderly manner and without challenging plant systems.

SURVEILLANCE REQUIREMENTS

Each 1219.2 mm (48 in) containment purge valve is required to be verified sealed closed at 31 day intervals. This Surveillance is designed to ensure that a gross breach of containment is not caused by an inadvertent or spurious opening of a containment purge valve. Detailed analysis of the purge valves failed to conclusively demonstrate their ability to close during a LOCA in time to limit offsite doses. Therefore, these valves are required to be in the sealed closed position during MODES 1, 2, 3, and 4.

A containment purge valve that is sealed closed must have motive power to the valve operator removed. This can be accomplished by de-energizing the source of electric power or removing the air supply to the valve operator. In this application, the term “sealed” has no connotation of leak tightness. The Frequency is a result of Generic Issue B-24, related to containment purge valve use during plant operations (Ref. 3). This SR is not required to be met while in Condition D of this LCO. This is reasonable since the penetration flow path would be isolated.
SURVEILLANCE REQUIREMENTS (continued)

**SR 3.6.3.2**

This SR ensures the 203.2 mm (8 in) purge valves are closed as required or, if open, open for an allowable reason. If the inoperable valve is not otherwise known to have excessive leakage when closed, it is not considered to have leakage outside of limits. The SR is not required to be met when the purge valves are open for pressure control, As Low As Reasonably Achievable (ALARA), and air quality considerations for personnel entry, and for Surveillance that require the valves to be open. The 203.2 mm (8 in) purge valves are capable of closing in the environment following a LOCA. Therefore, these valves are allowed to be open for limited periods of time. The 31 day Frequency is consistent with other containment isolation valve requirements discussed under SR 3.6.3.3.

**SR 3.6.3.3**

This SR requires verification that each containment isolation manual valve and blind flange located outside containment and not locked, sealed, or otherwise secured and required to be closed during accident conditions is closed. The SR helps to ensure that post-accident leakage of radioactive fluids or gases outside the containment boundary is within design limits. This SR does not require any testing or valve manipulation. Rather, it involves verification that those containment isolation valves outside containment and capable of being mispositioned are in the correct position. Since verification of valve position for containment isolation valves outside containment is relatively easy, the 31 day Frequency is based on engineering judgment and was chosen to provide added assurance of the correct positions. Containment isolation valves that are open under administrative controls are not required to meet the SR during the time the valves are open. This SR does not apply to valves that are locked, sealed, or otherwise secured in the closed position, since these were verified to be in the correct position upon locking, sealing, or securing.

The Note applies to valves and blind flanges located in high radiation areas and allows these devices to be verified closed by use of administrative means. Allowing verification by administrative means is considered acceptable, since access to these areas is typically restricted during MODES 1, 2, 3, and 4 for ALARA reasons. Therefore, the probability of misalignment of these containment isolation valves, once they have been verified to be in the proper position, is small.
SR 3.6.3.4

This SR requires verification that each containment isolation manual valve and blind flange located inside containment and required to be closed during accident conditions is closed. The SR helps to ensure that post-accident leakage of radioactive fluids or gases outside the containment boundary is within design limits. For Containment isolation valves inside containment, the Frequency of “prior to entering MODE 4 from MODE 5 if not performed within the previous 92 days” is appropriate, since these containment isolation valves and flanges are operated under administrative controls and the probability of their misalignment is low. Containment isolation valves that are open under administrative controls are not required to meet the SR during the time that they are open. This SR does not apply to valves that are locked, sealed, or otherwise secured in the closed position, since these were verified to be in the correct position upon locking, sealing, or securing.

The Note allows valves and blind flanges located in high radiation areas to be verified closed by use of administrative means. Allowing verification by administrative means is considered acceptable, since the primary containment is inerted and access to these areas is typically restricted during MODES 1, 2, and 3 for ALARA reasons. Therefore, the probability of misalignment of these containment isolation valves, once they have been verified to be in their proper position, is small.

SR 3.6.3.5

Verifying that the isolation time of each automatic power operated containment isolation valve is within limits is required to demonstrate OPERABILITY. The isolation time test ensures the valve will isolate in a time period less than or equal to that assumed in the safety analysis. The Frequency of this SR is in accordance with the Inservice Testing Program.

SR 3.6.3.6

For containment purge valves with resilient seals, additional leakage rate testing beyond the test requirements of 10 CFR Part 50, Appendix J, Option B (Ref. 4), is required to ensure OPERABILITY. Operating experience has demonstrated that this type of seal has the potential to degrade in a shorter time period than do other seal types. Based on this observation and the importance of maintaining this penetration leak tight
(due to the direct path between containment and the environment), a Frequency of 184 days was established as part of Generic Issue B-20 (Ref. 2).

Additionally, this SR must be performed within 92 days after opening the valve. The 92 day Frequency was chosen recognizing that cycling the valve could introduce additional seal degradation (beyond that occurring to a valve that has not been opened). Thus, decreasing the interval (from 184 days) is a prudent measure after a valve has been opened.

SR 3.6.3.7

Automatic containment isolation valves close on a Containment Isolation Signal to prevent leakage of radioactive material from containment following a DBA. This SR ensures each automatic containment isolation valve will actuate to its isolation position on a Containment Isolation Actuation Signal. This Surveillance is not required for valves that are locked, sealed, or otherwise secured in the required position under administrative controls. The 18 month Frequency was developed considering it is prudent that this SR be performed only during a unit outage, since isolation of penetrations would eliminate cooling water flow and disrupt normal operation of many critical components. Operating experience has shown that these components usually pass this SR when performed on the 18 month Frequency. Therefore, the Frequency was concluded to be acceptable from a reliability standpoint.

REFERENCES

1. FSAR, Chapter 6.
4. 10 CFR Part 50, Appendix J, Option B.
B 3.6  CONTAINMENT SYSTEMS

B 3.6.4  Containment Pressure

Bases

Background

The containment structure serves to contain radioactive material that could be released from the reactor core following a design basis accident (DBA), such that offsite radiation exposures are maintained within the requirement of 10 CFR 50.34 (Ref. 1). The containment pressure is limited during normal operation to preserve the initial conditions assumed in the accident analyses for a loss of coolant accident (LOCA) or main steam line break (MSLB). These limits also prevent the containment pressure from exceeding the containment design negative pressure differential with respect to the outside atmosphere in the event of inadvertent actuation of the Containment Spray System.

Containment pressure is a process variable which is monitored and controlled during MODES 1 through 4. The containment pressure limits are derived from the input conditions used in the containment functional analyses and the containment structure external pressure analysis. Should operation occur outside these limits coincident with a DBA, post-accident containment pressures could exceed calculated values.

Applicable Safety Analyses

The limits for containment pressure ensure that operation is maintained within the design and accident analysis bases for containment. The accident analyses and evaluations include both LOCAs and MSLBs to determine the maximum peak containment pressure ($P_a$). A double-ended discharge leg slot break with maximum safety injection (SI) flow results in the highest calculated internal containment pressure of 3.60 kg/cm²G (51.21 psig). This is below the internal design pressure of 4.218 kg/cm²G (60 psig). In addition, this LOCA peak pressure bounds all the MSLB containment peak pressure results.

The initial pressure value used to calculate the containment peak pressure following a LOCA is 0.1 kg/cm²G (1.42 psig). The containment is also designed for a maximum external pressure loading of 0.281 kg/cm²G (4.0 psig) to withstand the abrupt pressure drop from accidental actuation of the Containment Spray System.

The minimum containment external pressure which would occur as a result of an inadvertent actuation of the Containment Spray System is 0.25 kg/cm²G (3.54 psig), starting with an initial pressure of -0.037 kg/cm²G (-0.52 psig).

Containment pressure satisfies Criterion 2 of 10 CFR 50.36(c)(2)(ii).
**Containment Pressure**

**B 3.6.4**

**BASES**

LCO

Maintaining containment pressure less than or equal to the LCO upper pressure limit ensures that, in the event of a DBA, the resultant peak containment accident pressure will remain below the containment design pressure. Maintaining containment pressure greater than or equal to the LCO lower pressure limit ensures the containment will not exceed the design negative differential pressure following the inadvertent actuation of the Containment Spray System.

**APPLICABILITY**

In MODES 1, 2, 3, and 4, a DBA could cause a release of radioactive material to containment. Since maintaining containment pressure within limits is essential to ensure initial conditions assumed in the accident analysis are maintained, the LCO is applicable in MODES 1, 2, 3, and 4. In MODES 5 and 6, the probability and consequences of a DBA are reduced due to the pressure and temperature limitations of these MODES.

**ACTIONS**

A.1

When containment pressure is not within the limits of the LCO, containment pressure must be restored within these limits within 1 hour. The Required Action is necessary to return operation to within the bounds of the containment analysis. The 1 hour Completion Time is consistent with the ACTIONS of LCO 3.6.1, “Containment,” which requires the containment be restored to OPERABLE status within 1 hour.

B.1 and B.2

If containment pressure cannot be restored within limits within the required Completion Time, the plant must be placed in a MODE in which the LCO does not apply. To achieve this status, the plant must be brought to at least MODE 3 within 6 hours and to MODE 5 within 36 hours. The allowed Completion Times are reasonable, based on operating experience, to reach the required plant conditions from full power conditions in an orderly manner and without challenging plant systems.
Verifying containment pressure is within limits ensures that operation remains within the limits assumed in the containment analysis. The 12 hour Frequency of this SR was developed after taking into consideration operating experience related to containment pressure variations and pressure instrument drift during the applicable MODES, and the low probability of a DBA occurring between surveillances. Furthermore, the 12 hour Frequency is considered adequate in view of other indications in the main control room (MCR), including alarms, to alert the operator of an abnormal containment pressure condition.

REFERENCES

1. 10 CFR 50.34.
Containment Air Temperature

B 3.6 CONTAI NEMENT SYS TEMS

B 3.6.5 Containment Air Temperature

BASES

BACKGROUND  The containment structure serves to contain radioactive material that could be released from the reactor core following a design basis accident (DBA). The containment average air temperature is limited during normal operation to preserve the initial conditions assumed in the accident analyses for a loss of coolant accident (LOCA) or main steam line break (MSLB).

The containment average air temperature limit is derived from the input conditions used in the containment functional analyses and the containment structure external pressure analyses. This LCO ensures that initial conditions assumed in the analysis of containment response to a DBA are not violated during unit operations. The total amount of energy to be removed from containment by the Containment Spray System during post-accident conditions is dependent on the energy released to the containment due to the event, as well as the initial containment temperature and pressure. The higher the initial temperature, the more energy that must be removed, resulting in a higher peak containment pressure and temperature. Exceeding containment design pressure could result in leakage greater than assumed in the accident analysis (Ref. 1). Operation with containment temperature in excess of the LCO limit violates an initial condition assumed in the accident analysis.

APPLICABLE SAFETY ANALYSES  Containment average air temperature is an initial condition used in the DBA analysis that establishes the containment environmental qualification operating envelope for both pressure and temperature. The limit for containment average air temperature ensures that operation is maintained within the assumptions used in the DBA analysis for containment. The accident analyses and evaluations include both LOCAs and MSLBs to determine the maximum peak containment pressures and temperatures. The worst case MSLB generates higher temperature than the worst case LOCA. Thus, the MSLB bounds the LOCA with respect to containment peak temperature.

The initial pre-accident temperature inside containment was assumed to be 49°C (120°F) (Ref. 2) and the calculated peak temperature reaches 171.55°C (340.78°F) at the event of MSLB (102% power, main steam isolation valve (MSIV) single failure). However, this superheated condition does not influence the design of the containment, since it lasts only for a short period of time. In addition, the superheated vapor rapidly condenses after coming in contact with the subcooled surfaces of
Containment Air Temperature
B 3.6.5

BASSES

APPLICABLE SAFETY ANALYSES (continued)

containment internal structures. The design temperature of structures within the containment including liner plate is determined to 143.3°C (290°F) based on saturated conditions at the steam partial pressure in containment.

The consequence of exceeding this design temperature could be the potential for degradation of the containment structure under accident loads.

Containment average air temperature satisfies Criterion 2 of 10 CFR 50.36 (c)(2)(ii).

LCO

During a DBA, with an initial containment average temperature less than or equal to the LCO temperature limit, the resultant accident temperature profile assures that the containment structural temperature is maintained below its design temperature and that required safety-related equipment will continue to perform its function.

APPLICABILITY

In MODES 1, 2, 3, and 4, a DBA could cause a release of radioactive material to containment. In MODES 5 and 6, the probability and consequences of these events are reduced due to the pressure and temperature limitations of these MODES. Therefore, maintaining containment average air temperature within the limit is not required in MODE 5 or 6.

ACTIONS

A.1

With containment average air temperature not within the limit of the LCO, it must be restored within 8 hours. The Required Action is necessary to return operation to within the bounds of the containment analysis. The 8 hour Completion Time is acceptable considering the sensitivity of the analysis to variations in this parameter and provides sufficient time to correct minor problems.

B.1 and B.2

If the containment average air temperature cannot be restored to within its limits within the required Completion Time, the plant must be brought to a MODE in which overall plant risk is minimized. To achieve this status, the plant must be brought to at least MODE 3 within 6 hours and to MODE 5 within 36 hours.
The allowable Completion Times are reasonable, based on operating experience, to reach the required plant conditions from full power conditions in an orderly manner and without challenging the plant systems.

**SR 3.6.5.1**

Verifying the containment average air temperature is within the LCO limit ensures that containment operation remains within the limits assumed for the containment analyses. In order to determine the average temperature, an arithmetic average is calculated using measurements taken at locations within the containment selected to provide a representative sample of the overall containment atmosphere. The 24 hour Frequency of this SR is considered acceptable based on the observed slow rates of temperature increase within containment as a result of environmental heat sources (due to the large volume of containment).

**REFERENCES**

1. FSAR, Chapter 15.
2. FSAR, Section 6.2.
B 3.6  CONTAINMENT SYSTEMS

B 3.6.6  Containment Spray System

BASES

BACKGROUND  The Containment Spray System (CSS) cools containment atmosphere to limit post-accident pressure and temperature to less than the design values. Reduction of containment pressure and the iodine removal capability of the spray reduce the release of fission product radioactivity from containment to the environment, in the event of a design basis accident (DBA), within regulatory limits. The CSS is designed to the requirements of 10 CFR Part 50, Appendix A, and GDC 39 through 43 (Ref. 1).

The CSS is an Engineered Safety Feature (ESF) System. It is designed to ensure that the heat removal capability required during the post-accident period can be attained. The CSS provides redundant methods to limit and maintain post-accident conditions to less than the containment design values.

In the event of a loss of coolant accident (LOCA) or a main steam line break (MSLB), the CSS sprays IRWST water into the containment atmosphere to reduce the post-accident energy and to remove fission product iodine. There are two redundant containment spray divisions.

Each division consists of one containment spray pump, one containment spray pump miniflow heat exchanger, one containment spray heat exchanger, one containment spray header and associated piping, valves, instrumentation and controls. The pumps and remotely operated valves can be operated from the main control room (MCR).

A 2-out-of-4 pressurizer pressure low signal or a containment pressure high signal from the Engineered Safety Features Actuation System (ESFAS) generates a safety injection actuation signal (SIAS) which starts containment spray pumps.

A 2-out-of-4 containment pressure high-high signal from the ESFAS generates a containment spray actuation signal (CSAS) which initiates containment spray operation. Upon receipt of a CSAS, the containment spray header isolation valve opens and the containment spray pump starts in each of the two redundant divisions.

The pumps take suction from the in-containment refueling water storage tank (IRWST) and discharge through the containment spray heat exchangers and the spray header isolation valves and to their respective spray nozzle headers, then into the containment atmosphere.
BACKGROUND (continued)

The CSS is capable of removing sufficient decay heat from the containment atmosphere following a design basis accident (DBA) to maintain containment pressure and temperature within design limits.

The CSS protects the integrity of the containment by limiting the temperature and pressure following a DBA. Protection of adequate containment leak tightness prevents leakage of radioactive material from containment. Loss of adequate containment leak tightness could cause site boundary doses, due to a design bases LOCA, to exceed values given in Reference 2.

APPLICABLE SAFETY ANALYSES

The CSS limits the temperature and pressure following a DBA. The limiting DBAs considered relative to containment temperature and pressure are LOCA and MSLB. The LOCA and MSLB are analyzed using computer codes designed to predict the resultant containment pressure and temperature transients. No DBAs are assumed to occur simultaneously or consecutively. The postulated DBAs are analyzed with regard to containment ESF Systems, assuming the loss of one ESF bus, which is the worst case single active failure, resulting in one division of the CSS being rendered inoperable.

The accident analysis considers the worst case single active failure in the power supply which results in minimum containment cooling.

The analysis and evaluation show that under this scenario, the highest peak containment pressure is 3.60 kg/cm²G (51.21 psig) during a LOCA, and actual temperature of the containment structure, remained below the maximum design temperature of 143.3°C (290°F). (See Bases B 3.6.4, “Containment Pressure,” and B 3.6.5, “Containment Air Temperature,” for a detailed discussion.)

The effect of an inadvertent containment spray actuation has been analyzed (Ref. 3). An inadvertent containment spray actuation reduces the containment pressure to -0.25 kg/cm²G (-3.54 psig) due to the sudden cooling effect in the interior of the air tight containment. Additional discussion is provided in Bases 3.6.4, “Containment Pressure.”

The CSS actuation time in the containment analysis is based upon a response time associated with a containment high-high pressure signal to achieve full flow through the containment spray nozzles. The CSS total response time includes diesel generator startup (for loss of offsite power), load shedding and sequencing, containment spray pump startup, and spray line filling (Ref. 4). The containment spray piping is full of water at least to the 26.213 m (86 ft) by difference in the static head between...
Containment Spray System

APPLICABLE SAFETY ANALYSES (continued)

IRWST water level and containment spray piping. It minimizes the time required to fill the header.

The shutdown cooling pump in the same electrical division can be aligned to serve as the containment spray pump in MODES 1, 2, and 3 when the containment spray pump is not available.

The Containment Spray System satisfies Criterion 3 of 10 CFR 50.36(c)(2)(ii).

LCO

During a DBA, one containment spray division at least, is required to maintain the containment peak pressure and temperature below the design limits (Ref. 4). One containment spray division is also required to remove iodine from the containment atmosphere and maintain concentrations below those assumed in the safety analysis. To ensure that these requirements are met, two containment spray divisions must be OPERABLE. Therefore, in the event of an accident, the minimum requirements are met, even when the worst case single active failure occurs.

Each division of the CSS includes a containment spray pump, a containment spray heat exchanger, a containment spray pump mini-flow heat exchanger, containment spray headers, nozzles, valves, piping, instruments, and controls to ensure an OPERABLE flow path through which the IRWST borated water is supplied for containment spray upon an ESF actuation signal. Management of gas voids is important to Containment Spray System OPERABILITY.

One or two shutdown cooling pumps can be aligned to meet the requirements of the associated containment spray pump in MODES 1, 2, and 3 when the shutdown cooling pumps are not required to be OPERABLE. In MODE 4 this is not allowed, since the shutdown cooling pumps should be in service for supporting the shutdown cooling function.

APPLICABILITY

In MODES 1, 2, 3, and 4, a DBA could cause a release of radioactive material to containment and an increase in containment pressure and temperature, requiring the operation of the containment spray divisions.

In MODES 5 and 6, the probability and consequences of these events are reduced due to the pressure and temperature limitations of these MODES. Thus, the containment spray is not required to be OPERABLE in MODES 5 and 6.
BASES

APPLICABILITY  (continued)

When the unit is in MODE 6 with RCS water level \( \leq 38.72 \text{ m} \) (127 ft 1/4 in), LCO 3.9.5.b requires the containment spray (CS) pump, which is in the same electrical division as the SC train in operation, to be OPERABLE.

ACTIONS

A.1

With one containment spray division inoperable, the inoperable containment spray division must be restored to OPERABLE status within 72 hours. In this Condition, the remaining OPERABLE spray division is capable to perform the iodine removal and containment cooling functions. The Completion Time was determined to be 72 hours taking into account the redundant heat removal capability, reasonable time for repairs, and the low probability of a DBA occurring during this period.

B.1 and B.2

If the inoperable containment spray division cannot be restored to OPERABLE status within the required Completion Time, the plant must be placed in a MODE in which the LCO does not apply. To achieve this status, the plant must be brought to at least MODE 3 within 6 hours and to MODE 5 within 84 hours. The allowed Completion Time of 6 hours is reasonable, based on operating experience, to reach MODE 3 from full power conditions in an orderly manner and without challenging plant systems.

The allowed Completion Time of 84 hours to reach MODE 5 allows additional time for the restoration of the containment spray division and is reasonable when considering that the driving force for a release of radioactive material from the Reactor Coolant System is reduced in MODE 3.

C.1

With two containment spray divisions inoperable, the unit is in a condition outside the accident analysis. Therefore, LCO 3.0.3 must be entered immediately.

SURVEILLANCE REQUIREMENTS

If the shutdown cooling pump is aligned to meet the requirements of the associated containment spray pump, then the Surveillance Requirements of this LCO must be met for the shutdown cooling pump before declaring the shutdown cooling pump OPERABLE to satisfy LCO 3.6.6.
SURVEILLANCE REQUIREMENTS (continued)

SR 3.6.6.1

Verifying the correct alignment for manual, power operated, and automatic valves in the containment spray flow path provides assurance that the proper flow paths will be available for CSS operation. This SR does not apply to valves which are locked, sealed, or otherwise secured in position since they were verified to be in the correct position prior to locking, sealing, or securing. This SR also does not apply to valves which cannot be inadvertently misaligned, such as check valves. A valve which receives an actuation signal is allowed to be in a non-accident position provided the valve will automatically reposition within the proper stroke time. This SR does not require any valve testing or manipulation. Rather, it involves verifying that those valves outside containment are in the correct position.

The 31 day Frequency is based on engineering judgment, is consistent with the procedural controls governing valve operation, and ensures correct valve positions.

The Surveillance is modified by a Note which exempts system vent flow paths opened under administrative control. The administrative control should be proceduralized and include stationing a dedicated individual at the system vent flow path who is in continuous communication with the operators in the control room. This individual will have a method to rapidly close the system vent flow path if directed.

SR 3.6.6.2

Verifying that each containment spray pump develops 13.99 kg/cm²D (199.1 psid) of differential pressure at a flow rate of ≥ 20,535.24 L/min (5,425 gpm) ensures that each containment spray pump performance has not degraded during the cycle. Flow and differential pressure are normal tests of centrifugal pump performance required by ASME Operations and Maintenance (OM) Code (Ref. 5).

Since the containment spray pumps cannot be tested with flow through the spray nozzles, they are tested on recirculation flow. The recirculation alignment is full flow to the IRWST. This test confirms pump performance. Such in-service inspections confirm component OPERABILITY, trend performance, and detect incipient failures by indicating abnormal performance. The Frequency of this SR is in accordance with the in-service testing program.
SURVEILLANCE REQUIREMENTS (continued)

SR 3.6.6.3 and SR 3.6.6.4

These SRs demonstrate each automatic containment spray valve actuates to its correct position and that each containment spray pump starts upon receipt of an actual or simulated containment spray actuation signal. The 18 month Frequency is based on the need to perform these Surveillances under the conditions that apply during a plant outage and the potential for an unplanned transient if the Surveillances were performed with the reactor at power. Operating experience has shown that these components usually pass the Surveillances when performed at the 18 month Frequency. Therefore, the Frequency was concluded to be acceptable from a reliability standpoint.

SR 3.6.6.5

With the containment spray inlet valves closed and the containment spray header drained, low pressure air or smoke can be blown through test connections. Performance of this SR demonstrates that each spray nozzle is unobstructed and provides assurance that spray coverage of the containment during an accident is not degraded. Due to the passive nature of the design of the nozzle, a test at the first fuel loading and at 10 year intervals is considered adequate to detect obstruction of the spray nozzles.

SR 3.6.6.6

Verifying that the containment spray header piping is full of water to the 26.213 m (86 ft) level minimizes the time required to fill the header. This ensures that spray flow will be admitted to the containment atmosphere within the time frame assumed in the containment analysis. The 31 day Frequency is based on the static nature of the fill header and the low probability of a significant degradation of water level in the piping occurring between surveillances.

SR 3.6.6.7

Containment Spray System piping and components have the potential to develop voids and pockets of entrained gases. Preventing and managing gas intrusion and accumulation is necessary for proper operation of the required containment spray trains and may also prevent water hammer and pump cavitation.
Selection of Containment Spray System locations susceptible to gas accumulation is based on a review of system design information, including piping and instrumentation drawings, isometric drawings, plan and elevation drawings, and calculations. The design review is supplemented by system walk downs to validate the system high points and to confirm the location and orientation of important components that can become sources of gas or could otherwise cause gas to be trapped or difficult to remove during system maintenance or restoration.

Susceptible locations depend on plant and system configuration, such as stand-by versus operating conditions.

The Containment Spray System is OPERABLE when it is sufficiently filled with water. Acceptance criteria are established for the volume of accumulated gas at susceptible locations. If accumulated gas is discovered that exceeds the acceptance criteria for the susceptible location (or the volume of accumulated gas at one or more susceptible locations exceeds an acceptance criterion for gas volume at the suction or discharge of a pump), the Surveillance is not met. If it is determined by subsequent evaluation that the Containment Spray System is not rendered inoperable by the accumulated gas (i.e., the system is sufficiently filled with water), the Surveillance may be declared met. Accumulated gas should be eliminated or brought within the acceptance criteria limits.

Containment Spray System locations susceptible to gas accumulation are monitored and, if gas is found, the gas volume is compared to the acceptance criteria for the location. Susceptible locations in the same system flow path which are subject to the same gas intrusion mechanisms may be verified by monitoring a representative sub-set of susceptible locations. Monitoring may not be practical for locations that are inaccessible due to radiological or environmental conditions, the plant configuration, or personnel safety. For these locations alternative methods (e.g., operating parameters, remote monitoring) may be used to monitor the susceptible location. Monitoring is not required for susceptible locations where the maximum potential accumulated gas void volume has been evaluated and determined to not challenge system OPERABILITY.

The accuracy of the method used for monitoring the susceptible locations and trending of the results should be sufficient to assure system OPERABILITY during the Surveillance interval.
BASES

SURVEILLANCE REQUIREMENTS (continued)

The 31 day Frequency takes into consideration the gradual nature of gas accumulation in the Containment Spray System piping and the procedural controls governing system operation.

REFERENCES

1. 10 CFR Part 50, Appendix A, GDC 38, 39, 40, 41, 42, and 43.

2. 10 CFR 50.34.


4. FSAR, Subsection 6.2.2.

5. ASME OM Code.
B 3.6 CONTAINMENT SYSTEMS

B 3.6.7 Containment Penetrations - Shutdown Operations

BASES

BACKGROUND
Containment closure capability is required during shutdown operations, such as in MODE 5 with the Reactor Coolant System (RCS) loops not filled or in MODE 6 with the water level < 7.0 m (23 ft) above the top of reactor vessel flange. RCS heatup and direct venting could result in steaming into the containment if heat removal function is no longer available in MODES 5 and 6 during shutdown operations. In response to such an event, the equipment hatch, air locks and penetrations must be closed prior to steaming into containment. The LCO requires "containment closure" in MODES 5 and 6 during shutdown operations. Containment closure means that all potential leak paths are closed or capable of being closed.

[--------------------REVIEWER'S NOTE------------------------]
The number of bolts, material, size, and analysis supporting the hatch capability to support the dead weight (at a minimum) will be determined by the COL applicant.

[-------------------------------------------------------------------]

The containment equipment hatch, which is part of the containment pressure boundary, provides a means for moving large equipment and components into and out of the containment. The equipment hatch can be closed within an hour with or without alternating current (AC) power. The hatch moves vertically and is pulled down to the operation floor for closure.

However, the equipment hatch keeps closed during shutdown operations because administratively the hatch is closed prior to entering MODES 5 and 6 when the containment is OPERABLE. In MODES 5 and 6 during shutdown operations, the equipment hatch must be held in place by at least four bolts. Good engineering practice dictates that the bolts required by this LCO be approximately equally spaced.

The containment airlocks, which are also part of the containment pressure boundary, provide a means for personnel access during shutdown operations in accordance with LCO 3.6.2, "Containment Airlocks." Each airlock has a door at both ends. The doors are normally interlocked to prevent simultaneous opening when containment OPERABILITY is required. During shutdown operations when containment closure is not required, the door interlock mechanism may be disabled, allowing both doors of an airlock to remain open for extended periods when frequent containment entry is necessary.
In MODES 5 and 6 during shutdown operations, only containment closure is required; therefore the door interlock mechanism may remain disabled, but one airlock door must remain capable of being closed.

In MODE 6 during shutdown operations, large air exchanges may be required to conduct refueling operations. The high volume purge system is used for this purpose and all valves are closed by the ESFAS such as containment purge isolation actuation signal (CPIAS) and containment isolation actuation signal (CIAS) in accordance with LCO 3.3.5, “Engineered Safety Feature Actuation System (ESFAS) Instrumentation.”

The containment penetrations that provide direct access from containment atmosphere to outside atmosphere must be isolated on at least one side. Isolation may be achieved by an OPERABLE automatic isolation valve, or by a manual isolation valve, or blind flange.

Release of fission products to the environment from containment is limited by 10 CFR 50.34. If the LCO requirements are adhered to, then no release exceeding the 10 CFR 50.34 limits can occur (Ref. 1).

Containment penetration status during shutdown operations satisfies Criterion 4 of 10 CFR 50.36(c)(2)(ii).

This LCO minimizes the release of radioactivity from containment. The LCO requires the equipment hatch be closed and held in place by a minimum of [four bolts], one door in each airlock be closed, and each penetration providing direct access to the outside environment to be closed with the exception of the containment purge penetrations.

The LCO is applicable in MODE 5 with any RCS loop not filled and in MODE 6 with the refueling pool water level < 7.0 m (23 ft) above the top of the reactor vessel flange.

The equipment hatch is administratively required to be closed before opening the pressurizer manway in MODE 5, and is kept closed during MODE 5 in the RCS loops not filled condition and during MODE 6 with water level below the level required by LCO 3.9.6 “Refueling Water Level.” This ensures that all containment penetrations will be in the status required by LCO 3.6.7 before the onset of reactor coolant boiling and steaming into containment in the event of a loss of shutdown cooling during reduced RCS inventory conditions.
Containment Penetrations - Shutdown Operations

B 3.6.7

BASES

ACTIONS

A.1

If one or more containment penetrations are not in the required status, restoration must be accomplished within 4 hours. This will ensure that the plant will be within the assumptions of the safety analysis.

B.1

If Action A.1 has not been completed within the 4 hours, then an RCS level of > 38.72 m (127 ft 1/4 in) must be established within 6 hours of Action A.1 not being met. Maintaining this level with one or more penetrations not in the required status is acceptable because this inventory provides adequate time for operators to respond to a loss of shutdown cooling event by isolating affected penetrations, restoring shutdown cooling, and preventing steaming into the containment.

SURVEILLANCE REQUIREMENTS

SR 3.6.7.1

This SR verifies that each required containment building penetration is in its required status every 12 hours. This ensures that fission products will not escape containment in a quantity greater than assumed in the safety analysis.

SR 3.6.7.2

This SR verifies each containment purge and exhaust valve actuates to its isolated position on an actual or simulated actuation signal. The 18 month Frequency maintains consistency with similar engineered safety features actuation signal (ESFAS) testing requirements and has been shown to be acceptable through operating experience.

REFERENCES

B 3.7  PLANT SYSTEMS

B 3.7.1  Main Steam Safety Valves (MSSVs)

BASES

BACKGROUND  The primary purpose of the MSSVs is to provide overpressure protection for the secondary system. The MSSVs also provide protection against overpressurizing the reactor coolant pressure boundary (RCPB) by providing a heat sink for the removal of energy from the Reactor Coolant System (RCS) if the preferred heat sink, provided by the Condenser and Circulating Water System, is not available.

Five MSSVs are located on each main steam header (ten MSSVs per one steam generator), outside containment, upstream of the main steam isolation valves, as described in the FSAR Section 5.2 and 5.4 (Ref. 1). The MSSV rated capacity passes the full steam flow at 102% RTP (100 + 2% for instrument error) with the valves full open. This meets the requirements of the ASME Code, Section III (Ref. 2). The MSSV design includes staggered setpoints, according to Table 3.7.1-1, in the accompanying LCO, so that only the number of valves needed will actuate. Staggered setpoints reduce the potential for valve chattering because of insufficient steam pressure to fully open all valves following a turbine reactor trip.

APPLICABLE SAFETY ANALYSES  The design basis for the MSSVs comes from Reference 2. The MSSV's purpose is to limit secondary system pressure to ≤ 110% of design pressure when passing 100% of design steam flow.

This design basis is sufficient to cope with any anticipated operational occurrence (AOO) or accident considered in the Design Basis Accident (DBA) and transient analysis.

The events that challenge the MSSV relieving capacity, and thus RCS pressure, are those characterized as decreased heat removal events, and are presented in the FSAR, Section 15.2 (Ref. 3). Of these, the full power loss of condenser vacuum (LOCV) event is the limiting AOO. An LOCV isolates the turbine and condenser, and terminates normal feedwater flow to the steam generators. Before delivery of auxiliary feedwater to the steam generators, RCS peak pressure is < 110% of the design pressure of 175.8 kg/cm²A (2500 psia), but high enough to actuate the pressurizer safety valves.

The maximum relieving rate during the LOCV event is less than the rated capacity of two MSSVs.
The limiting accident for peak RCS pressure is the full power main feedwater line break (MFLB), inside containment, with the failure of the backflow check valve in the feedwater line from the affected steam generator. Water from the affected steam generator is assumed to be lost through the break with minimal additional heat transfer from the RCS. With heat removal limited to the unaffected steam generator, the reduced heat transfer causes an increase in RCS temperature, and the resulting RCS fluid expansion causes an increase in pressure. The RCS peak pressure is \(< 110\% \) of the design pressure of 175.8 kg/cm\(^2\) (2500 psia) with the pressurizer safety valves providing relief capacity. The maximum relieving rate of the MSSVs during the MFLB is less than the rated capacity of two MSSVs.

Using conservative analysis assumptions, a small range of MFLB sizes less than a full double ended guillotine break produce an RCS pressure exceeding 110\% (193.3 kg/cm\(^2\) (2750 psia)) of design pressure. This is considered acceptable as RCS pressure is still well below 120\% of design pressure where deformation could occur. The probability of this event is in the range of 4E-6/year.

In the safety analysis, the lift setpoint of MSSV is considered to have a total uncertainty of \(\pm 4\%\) that includes \(\pm 3\%\) setpoint uncertainty with long term drift and \(\pm 1\%\) instrument error uncertainty for additional conservatism.

The MSSVs satisfy Criterion 3 of 10 CFR 50.36(c)(2)(ii).

This LCO requires all MSSVs to be OPERABLE in compliance with Reference 2, even though this is not a requirement of the DBA analysis. This is because operation with less than the full number of MSSVs requires limitations on allowable THERMAL POWER (to meet Reference 2 requirements), and adjustment to the reactor protection system trip setpoints. These limitations are according to those shown in Table 3.7.1-1, Required Action A.1, and Required Action A.2 in the accompanying LCO. An MSSV is considered inoperable if it fails to open upon demand.

The OPERABILITY of the MSSVs is defined as the ability to fully open within the setpoint tolerances, relieve steam generator overpressure, and reseat when pressure has been reduced. The OPERABILITY of the MSSVs is determined by periodic surveillance testing in accordance with the inservice testing program.
BASES

LCO (continued)

The lift settings, according to Table 3.7.1-2 in the accompanying LCO, correspond to ambient conditions of the valve at nominal operating temperature and pressure.

This LCO provides assurance that the MSSVs will perform their designed safety function to mitigate the consequences of accidents that could result in a challenge to the RCPB.

APPLICABILITY

In MODE 1, a minimum of five MSSVs per steam generator are required to be OPERABLE, according to Table 3.7.1-1 in the accompanying LCO, which is limiting and bounds all lower MODES. In MODES 2 and 3, both the ASME Code and the accident analysis require MSSVs per Table 3.7.1-1 to provide overpressure protection.

In MODES 4 and 5, there are no credible transients requiring the MSSVs.

The steam generators are not normally used for heat removal in MODES 5 and 6, and thus cannot be overpressurized; there is no requirement for the MSSVs to be OPERABLE in these MODES.

ACTIONS

The ACTIONS table is modified by a Note indicating that separate Condition entry is allowed for each MSSV.

A.1 and A.2

An alternative to restoring the inoperable MSSV(s) to OPERABLE status is to reduce power so that the available MSSV relieving capacity meets Code requirements for the power level. Operation may continue provided the allowable THERMAL POWER is equal to the product of: 1) the ratio of the number of MSSVs available per steam generator to the total number of MSSVs per steam generator, and 2) the ratio of the available relieving capacity to total steam flow, multiplied by 100%.

Allowable THERMAL POWER = \( \left( \frac{10 - N}{10} \right) \times 107.55 \)

With one or more MSSVs inoperable, the ceiling on the variable overpower trip is reduced to an amount over the allowable THERMAL POWER equal to the band given for this trip, according to Table 3.7.1-1 in the accompanying LCO.
SP = Allowable THERMAL POWER + 9.4

where:

SP = Reduced reactor trip setpoint in % RTP. This is a ratio of the available relieving capacity over the total steam flow at rated power.

10 = Total number of MSSVs per steam generator.

N = Number of inoperable MSSVs on the steam generator with the greatest number of inoperable valves.

107.55 = Ratio of MSSV relieving capacity at 110% steam generator design pressure to calculated steam flow rate at 100% RTP + 2% instrument uncertainty expressed as a percentage (see text above).

9.4 = Band between the maximum THERMAL POWER and the variable overpower trip setpoint ceiling (Table 3.7.1-1).

The operator should limit the maximum steady state power level to some value slightly below this setpoint to avoid an inadvertent overpower trip.

The 4 hour Completion Time for Required Action A.1 is a reasonable time period to reduce power level and is based on the low probability of an event occurring during this period that would require activation of the MSSVs. An additional 32 hours is allowed in Required Action A.2 to reduce the setpoints. The Completion Time of 36 hours for Required Action A.2 is based on a reasonable time to correct the MSSV inoperability, the time required to perform the power reduction, operating experience in resetting all channels of a protective function, and on the low probability of the occurrence of a transient that could result in steam generator overpressure during this period.

B.1 and B.2

If the MSSVs cannot be restored to OPERABLE status in the associated Completion Time, or if one or more steam generators have less than four MSSVs OPERABLE, the unit must be placed in a MODE in which the LCO does not apply. To achieve this status, the unit must be placed in at least MODE 3 within 6 hours, and in MODE 4 within 24 hours. The allowed Completion Times are reasonable, based on operating experience, to reach the required unit conditions from full power conditions in an orderly manner and without challenging unit systems.
This SR verifies the OPERABILITY of the MSSVs by the verification of each MSSV lift setpoints in accordance with the Inservice Testing Program. The ASME Code (Ref. 4) requires that safety and relief valve tests be performed in accordance with ANSI/ASME OM-1-1987 (Ref. 5). According to Reference 5, the following tests are required for MSSVs:

a. Visual examination,

b. Seat tightness determination,

c. Setpoint pressure determination (lift setting),

d. Compliance with owner's seat tightness criteria, and

e. Verification of the balancing device integrity on balanced valves.

The ANSI/ASME Standard requires that all valves be tested every 5 years, and a minimum of 20% of the valves be tested every 24 months. The ASME Code specifies the activities and frequencies necessary to satisfy the requirements. Table 3.7.1-2 allows a ±3% setpoint tolerance for OPERABILITY. Therefore, further testing for the valves is unnecessary in the case where the lift setting is within the OPERABILITY limit. If the lift setting does not meet the OPERABILITY limit, two additional valves per valve showing an unsatisfactory result, up to the total number of remaining valves, are required to be tested according to the ANSI/ASME OM-1987 requirements. In case that the lift setting is not within ±1% even though it is within the OPERABILITY limit, the valves must be reset within ±1%.

This SR is modified by a Note that allows entry into and operation in MODE 3 prior to performing the SR. This is to allow testing of the MSSVs at hot conditions. The MSSVs may be either bench tested or tested in situ at hot conditions using an assist device to simulate lift pressure. If the MSSVs are not tested at hot conditions, the lift setting pressure shall be corrected to ambient conditions of the valve at operating temperature and pressure.
## BASES

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<th>REFERENCES</th>
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<td>3. FSAR, Section 15.2.</td>
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</table>
The MSIVs isolate steam flow from the secondary side of the steam generators (SGs) following a high energy line break (HELB). MSIV closure terminates flow from the unaffected (intact) steam generator (SG).

One MSIV is located in each main steam line outside, but close to, containment. The MSIVs are downstream from the main steam safety valves (MSSVs), atmospheric dump valves, and auxiliary feedwater pump turbine steam supplies to prevent their being isolated from the SGs by MSIV closure. Closing the MSIVs isolates each SG from the other, and isolates the turbine, Turbine Bypass System, and other auxiliary steam supplies from the SGs.

The MSIVs close on a main steam isolation signal generated by high SG level, low SG pressure, and high containment pressure. The MSIVs fail closed on loss of control or actuation power. The main steam isolation signal (MSIS) also actuates the main feedwater isolation valves (MFIVs) to close. The MSIVs may also be actuated manually.

A description of the MSIVs is found in the FSAR, Section 10.3 (Ref. 1).

The design basis of the MSIVs is established by the containment analysis for the main steam line break (MSLB) inside containment, as discussed in the FSAR, Section 6.2 (Ref. 2). It is also influenced by the accident analysis of the MSLB presented in the FSAR, Section 15.1.5 (Ref. 3). The design precludes the blowdown of more than one SG, assuming a single active component failure (e.g., the failure of one MSIV to close on demand).

The case for the containment analysis is the hot zero power MSLB inside containment with a loss of offsite power following turbine trip, and failure of the MSIV on the affected SG to close. At zero power, the SG inventory and temperature are at their maximum, maximizing the analyzed mass and energy release to the containment.

Due to reverse flow, failure of the MSIV to close contributes to the total release of the additional mass and energy in the steam headers, which are downstream of the other MSIV. With the most reactive rod cluster control assembly assumed stuck in the fully withdrawn position, there is an increased possibility that the core will become critical and return to power.
The core is ultimately shut down by the borated water injection delivered by the Emergency Core Cooling System. Other failures considered are the failure of an MFIV to close and failure of an emergency diesel generator to start.

The accident analysis compares several different MSLBs against different acceptance criteria. The MSLB outside containment upstream of the MSIV is limiting for offsite dose, although a break in this short section of main steam header has a very low probability. The MSLB inside containment at hot zero power is the limiting case for a post trip return to power. The analysis includes scenarios with offsite power available and with a loss of offsite power following turbine trip.

With offsite power available, the reactor coolant pumps continue to circulate coolant through the steam generators, maximizing the Reactor Coolant System (RCS) cooldown. With a loss of offsite power, the response of mitigating systems, such as the high pressure safety injection (SI) pumps, is delayed. Significant single failures considered include: failure of a MSIV to close, failure of an emergency diesel generator, and failure of an SI pump.

The MSIVs serve only a safety function and remain open during power operation. These valves operate under the following situations:

a. HELB inside containment.

In order to maximize the mass and energy release into the containment, the analysis assumes that the MSIV in the affected SG remains open. For this accident scenario, steam is discharged into containment from both SGs until closure of the MSIV in the intact SG occurs. After MSIV closure, steam is discharged into containment only from the affected SG, and from the residual steam in the main steam header downstream of the closed MSIV in the intact loop.

b. A break outside of containment and upstream from the MSIVs.

This scenario is not a containment pressurization concern. The uncontrolled blowdown of more than one SG must be prevented to limit the potential for uncontrolled RCS cooldown and positive reactivity addition. Closure of the MSIVs isolates the break and limits the blowdown to a single SG.
APPLICABLE SAFETY ANALYSES (continued)

c. A break downstream of the MSIVs.

This type of break will be isolated by the closure of the MSIVs. Events such as increased steam flow through the turbine or the steam bypass valves will also terminate on closure of the MSIVs.

d. Steam generator tube rupture.

For this scenario, closure of the MSIVs isolates the affected SG from the intact SG. In addition to minimizing radiological releases, this enables the operator to maintain the pressure of the SG with the ruptured tube below the MSSV setpoints, a necessary step toward isolating the flow through the rupture.

The MSIVs are also used during other events such as a main feedwater line break. These events are less limiting so far as MSIV OPERABILITY is concerned.

The MSIVs satisfy Criterion 3 of 10 CFR 50.36(c)(2)(ii).

LCO

This LCO requires that the MSIV in each of the four steam lines be OPERABLE. The MSIVs are considered OPERABLE when the isolation times are within limits, and they close on an isolation actuation signal.

This LCO provides assurance that the MSIVs will perform their design safety function to mitigate the consequences of accidents that could result in offsite exposures comparable to the 10 CFR 50.34 (Ref. 4) limits or the Nuclear Regulatory Commission (NRC) staff approved licensing basis.

APPLICABILITY

The MSIVs must be OPERABLE in MODE 1 and in MODES 2 and 3 except when all MSIVs are closed and deactivated. In these MODES there is significant mass and energy in the RCS and SGs. When the MSIVs are closed, they are already performing their safety function.

In MODE 4, the SG energy is low. Therefore, the MSIVs are not required to be OPERABLE.

In MODES 5 and 6, the SGs do not contain much energy because their temperature is below the boiling point of water; therefore, the MSIVs are not required for isolation of potential high energy secondary system pipe breaks in these MODES.
A.1

With one MSIV inoperable in MODE 1, time is allowed to restore the component to OPERABLE status. Some repairs can be made to the MSIV with the unit hot. The 4 hour Completion Time is reasonable, considering the probability of an accident occurring during the time period that would require closure of the MSIVs.

The 4 hour Completion Time is greater than that normally allowed for containment isolation valves because the MSIVs are valves that isolate a closed system penetrating containment. These valves differ from other containment isolation valves in that the closed system provides an additional means for containment isolation.

B.1

If the MSIV cannot be restored to OPERABLE status within 4 hours, the unit must be placed in a MODE in which the LCO does not apply. To achieve this status, the unit must be placed in MODE 2 within 6 hours and Condition C would be entered. The Completion Time is reasonable, based on operating experience, to reach MODE 2, and close the MSIVs in an orderly manner and without challenging unit systems.

C.1 and C.2

Condition C is modified by a Note indicating that separate Condition entry is allowed for each MSIV.

Since the MSIVs are required to be OPERABLE in MODES 2 and 3, the inoperable MSIVs may either be restored to OPERABLE status or closed. When closed, the MSIVs are already in the position required by the assumptions in the safety analysis.

The 4 hour Completion Time is consistent with that allowed in Condition A.

Inoperable MSIVs that cannot be restored to OPERABLE status within the specified Completion Time, but are closed, must be verified on a periodic basis to be closed. This is necessary to ensure that the assumptions in the safety analysis remain valid. The 7 day Completion Time is reasonable, based on engineering judgment, MSIV status indications available in the main control room (MCR), and other administrative controls, to ensure these valves are in the closed position.
D.1 and D.2

If the MSIVs cannot be restored to OPERABLE status or closed within the associated Completion Time, the unit must be placed in a MODE in which the LCO does not apply. To achieve this status, the unit must be placed in at least MODE 3 within 6 hours, and in MODE 4 within 12 hours. The allowed Completion Times are reasonable, based on operating experience, to reach the required unit conditions from MODE 2 conditions in an orderly manner and without challenging unit systems.

SR 3.7.2.1

This SR verifies that the closure time of each MSIV is within the limit given in Reference 5 and is within that assumed in the accident and containment analyses. This SR also verifies the valve closure time is in accordance with the Inservice Testing Program. This SR is normally performed upon returning the unit to operation following a refueling outage. The MSIVs should not be tested at power since even a part stroke exercise increases the risk of a valve closure with the unit generating power. As the MSIVs are not tested at power, they are exempt from the ASME Code (Ref. 6) requirements during operation in MODES 1 and 2.

The Frequency for this SR is in accordance with the Inservice Testing Program.

This test is conducted in MODE 3, with the unit at operating temperature and pressure. This SR is modified by a Note that allows entry into and operation in MODE 3 prior to performing the SR. This allows a delay of testing until MODE 3, in order to establish conditions consistent with those under which the acceptance criterion was generated.

SR 3.7.2.2

This SR verifies that each MSIV can close on an actual or simulated actuation signal. This Surveillance is normally performed upon returning the plant to operation following a refueling outage. The Frequency of MSIV testing is every 18 months. The 18 month Frequency for testing is based on the refueling cycle. Operating experience has shown that these components usually pass the Surveillance when performed at the 18 month Frequency. Therefore, this Frequency is acceptable from a reliability standpoint.
This test is conducted in MODE 3, with the unit at operating temperature and pressure. This SR is modified by a Note that allows entry into and operation in MODE 3 prior to performing the SR. This allows a delay of testing until MODE 3, in order to establish conditions consistent with those under which the acceptance criterion was generated.

REFERENCES
1. FSAR, Section 10.3.
2. FSAR, Section 6.2.
3. FSAR, Subsection 15.1.5.
4. 10 CFR 50.34.
B 3.7 PLANT SYSTEMS

B 3.7.3 Main Feedwater Isolation Valves (MFIVs)

BACKGROUND

The MFIVs isolate main feedwater (MFW) flow to the secondary side of the steam generators following a high energy line break (HELB). Closure of the MFIVs terminates flow to both steam generators, terminating the event for main feedwater line breaks (MFLBs) occurring upstream of the MFIVs. The consequences of events occurring in the main steam lines or in the MFW lines downstream of the MFIVs will be mitigated by their closure. Closure of the MFIVs effectively terminates the addition of feedwater to an affected steam generator (SG), limiting the mass and energy release of main steam line breaks (MSLBs) or MFLBs inside containment, and reducing the cooldown effects of MSLBs.

The MFIVs isolate the non-safety-related portions from the safety-related portion of the system. In the event of a secondary side pipe rupture inside containment, closure of the MFIVs limits the quantity of high energy fluid that enters containment through the pipe break, and provides a pressure boundary for the controlled addition of auxiliary feedwater (AFW) to the intact SG.

Two redundant and fail-closed type MFIVs in series are installed in both the economizer MFW line and the downcomer MFW line of each SG. The MFIVs are located outside the reactor containment building as close to the containment wall as possible. The MFIVs in the downcomer MFW line are located upstream of the AFW injection point inside containment so that AFW can be supplied to the associated SG following MFIV closure. The MFW piping volume from the outer MFIV to the SG must be accounted for in calculating mass and energy releases, and the downcomer MFW line must be refilled prior to AFW reaching the SG following either an MSLB or MFLB.

The MFIVs close on receipt of a main steam isolation signal (MSIS) generated by any one of low SG pressure, high SG level, and high containment pressure. The MSIS also actuates the main steam isolation valves (MSIVs) to close. The MFIVs can also be actuated manually. Downstream of the MFIVs, two check valves in series are located in the downcomer MFW line and the economizer MFW line of each SG to preclude blowdown of both SGs following a pipe rupture upstream of the check valves. In the downcomer MFW line, one of these check valves is outside the containment and one of these check valves is inside the containment upstream of the AFW injection line connection. In the economizer MFW line, one of these check valves is also outside the containment. After the split in the economizer MFW line inside the
containment, one of these check valves is located in each of the two parallel lines. The economizer MFW line check valves inside the containment are located as close to the SG as possible to minimize the possibility of a pipe break between the check valve and the SG resulting in backflow from the SG to the containment. These check valves ensure that the consequences of events do not exceed the capacity of the containment heat removal systems, such as the Containment Spray System with the shutdown cooling pump as a backup.

A description of the MFIVs is found in the FSAR, Subsection 10.4.7 (Ref. 1).

The design basis of the MFIVs is established by the analysis for the MSLB. It is also influenced by the accident analysis for the MFLB. Closure of the MFIVs may also be relied on to terminate a steam break for core response analysis and an excess feedwater flow event upon receipt of a MSIS on high SG level.

Failure of an MFI to close following an MSLB, MFLB, or excess feedwater flow event can result in additional mass and energy to the SGs contributing to cooldown. This failure also results in additional mass and energy releases following an MSLB or MFLB.

The MFIVs satisfy Criterion 3 of 10 CFR 50.36(c)(2)(ii).

This LCO ensures that the MFIVs will isolate MFW flow to the steam generators. Following an MFLB or MSLB, these valves will also isolate the non-safety-related portions from the safety-related portions of the system. This LCO requires that two MFIVs in each feedwater line be OPERABLE. The MFIVs are considered OPERABLE when the isolation times are within limits, and are closed on an isolation actuation signal.

Failure to meet the LCO requirements can result in additional mass and energy being released to containment following an MSLB or MFLB inside containment. If an MSIS on high steam generator level is relied on to terminate an excess feedwater flow event, failure to meet the LCO could result in the introduction of water into the main steam lines.

The MFIVs must be OPERABLE whenever there is significant mass and energy in the Reactor Coolant System and steam generators. This ensures that, in the event of an HELB, a single failure cannot result in the blowdown of more than one steam generator.
In MODES 1, 2 and 3, the MFIV are required to be OPERABLE, except when they are closed and deactivated or isolated by a closed manual valve, in order to limit the amount of available fluid that could be added to containment in the case of a secondary system pipe break inside containment. When the valves are closed, they are already performing their safety function.

In MODES 4, 5, and 6, steam generator energy is low. Therefore, the MFIVs are normally closed since MFW is not required.

The ACTIONS Table is modified by a Note indicating that separate Condition entry is allowed for each valve.

A.1 and A.2

With one MFIV inoperable, action must be taken to close or isolate the inoperable valves within 72 hours. When these valves are closed or isolated, they are performing their required safety function (i.e., to isolate the line).

The 72 hour Completion Time takes into account the redundancy afforded by the remaining OPERABLE valves, and the low probability of an event occurring during this time period that would require isolation of the MFW flow paths.

B.1 and B.2

If more than one MFIV in the same flow path cannot be restored to OPERABLE status, then there may be no redundant system to operate automatically and perform the required safety function. Although the containment can be isolated with the failure of two valves in parallel in the same flow path, the double failure can be an indication of a common mode failure in the valves of this flow path, and as such is treated the same as a loss of the isolation capability of this flow path. Under these conditions, valves in each flow path must be restored to OPERABLE status, closed, or the flow path isolated within 8 hours. This action returns the system to the condition where at least one valve in each flow path is performing the required safety function. The 8 hour Completion Time is reasonable to close the MFIV or otherwise isolate the affected flow path.

Inoperable MFIVs that cannot be restored to OPERABLE status within the Completion Time, but are closed or isolated, must be verified on a periodic basis that they are closed or isolated. This is necessary to
Bases

Actions (continued)

Ensure that the assumptions in the safety analysis remain valid. The 7 day Completion Time is reasonable, based on engineering judgment, in view of valve status indications available in the main control room (MCR), and other administrative controls to ensure that these valves are closed or isolated.

C.1 and C.2

If the MFIVs cannot be restored to OPERABLE status, closed, or isolated in the associated Completion Time, the unit must be placed in a MODE in which the LCO does not apply. To achieve this status, the unit must be placed in at least MODE 3 within 6 hours and in MODE 4 within 12 hours. The allowed Completion Times are reasonable, based on operating experience, to reach the required unit conditions from full power conditions in an orderly manner and without challenging unit systems.

Surveillance Requirements

SR 3.7.3.1

This SR verifies that the closure time of each MFIV is within the limit given in Reference 2 and is within that assumed in the accident and containment analyses. This SR also verifies that the valve closure time is in accordance with the Inservice Testing Program. This SR is normally performed upon returning the unit to operation following a refueling outage. The MFIVs should not be tested at power since even a part stroke exercise increases the risk of a valve closure with the unit generating power. As these valves are not tested at power, they are exempt from the ASME Code (Ref. 3) requirements during operation in MODES 1 and 2.

The Frequency is in accordance with the Inservice Testing Program.

SR 3.7.3.2

This SR verifies that each MFIV can close on an actual or simulated actuation signal. This Surveillance is normally performed upon returning the plant to operation following a refueling outage.

The Frequency for this SR is every 18 months. The 18 month Frequency for testing is based on the refueling cycle. Operating experience has shown that these components usually pass the Surveillance when performed at the 18 month Frequency. Therefore, this Frequency is acceptable from a reliability standpoint.
REFERENCES

1. FSAR, Subsection 10.4.7.


3. ASME OM Code.
B 3.7 PLANT SYSTEMS

B 3.7.4 Main Steam Atmospheric Dump Valves (MSADVs)

BASES

BACKGROUND

The MSADVs provide a safety grade method for cooling the unit to Shutdown Cooling System (SCS) entry conditions, should the preferred heat sink via the Steam Bypass System to the condenser not be available, as discussed in the FSAR, Section 10.3 (Ref. 1). This is done in conjunction with the Auxiliary Feedwater System providing cooling water from the auxiliary feedwater storage tank (AFWST). The MSADVs could also be required to meet the design cooldown rate during a normal cooldown when steam pressure drops too low for maintenance of a vacuum in the condenser to permit use of the Steam Bypass System.

Four MSADV lines are provided. Each MSADV line consists of one MSADV and an associated block valve. Two MSADV lines per steam generator are required to meet single failure assumptions following an event rendering one steam generator unavailable for Reactor Coolant System (RCS) heat removal.

The MSADVs are provided with upstream block valves to permit their being tested at power, and to provide an alternate means of isolation. The MSADVs are electro-hydraulically operated and include internal solenoid operated pilot valves and electronic valve positioners to permit control of the cooldown rate.

A description of the MSADVs is found in Reference 1. The MSADVs are OPERABLE with only a DC and AC power source available. In addition, hand wheels or manual control provisions are provided to enable manual operation of the electro-hydraulic operator mounted on the valve upon total loss of power.

APPLICABLE SAFETY ANALYSES

The design basis of the MSADVs is established by the capability to cool the unit to SCS entry conditions. A cooldown rate of 41.7°C (75°F) per hour is obtainable by one or both steam generators. This design is adequate to cool the unit to SCS entry conditions with only one MSADV and one steam generator, using the cooling water supply available in the AFWST.

In the accident analysis presented in the FSAR, the MSADVs are assumed to be used by the operator to cool down the unit to SCS System entry conditions for accidents accompanied by a loss of offsite power. Prior to the operator action, the main steam safety valves (MSSVs) are used to maintain steam generator pressure and temperature at the MSSV setpoint. This is typically 30 minutes following the initiation of an event.
This could be less for a steam generator tube rupture (SGTR) event. The limiting events are those that render one steam generator unavailable for RCS heat removal, with a coincident loss of offsite power; this results from a turbine trip and the single failure of one MSADV on the unaffected steam generator. Typical initiating events falling into this category are a main steam line break upstream of the main steam isolation valves, a main feedwater line break, and an SGTR (although the MSADVs on the affected steam generator could still be available following an SGTR).

The design must accommodate the single failure of one MSADV to open on demand; thus, each steam generator must have at least two MSADVs. The MSADVs are equipped with block valves in the event an MSADV spuriously opens, or fails to close during use.

The MSADVs satisfy Criterion 3 of 10 CFR 50.36(c)(2)(ii).

Two MSADV lines are required to be OPERABLE on each steam generator to ensure that at least one MSADV is OPERABLE to conduct a unit cooldown following an event in which one steam generator becomes unavailable, accompanied by a single active failure of one MSADV line on the unaffected steam generator. The block valves must be OPERABLE to isolate a failed open MSADV. A closed block valve does not render it or its MSADV line inoperable if operator action time to open the block valve is supported in the accident analysis.

Failure to meet the LCO can result in the inability to cool the unit to SCS entry conditions following an event in which the condenser is unavailable for use with the Steam Bypass System.

An MSADV is considered OPERABLE when it is capable of providing a controlled relief of the main steam flow, and is capable of fully opening and closing on demand.

In MODES 1, 2, and 3, and in MODE 4, when steam generator is being relied upon for heat removal, the MSADVs are required to be OPERABLE.

In MODES 5 and 6, an SGTR is not a credible event.
With one MSADV line inoperable, action must be taken to restore the OPERABLE status within 7 days. The 7 day Completion Time takes into account the redundant capability afforded by the remaining OPERABLE MSADV lines, and a non-safety grade backup in the Steam Bypass System and MSSVs.

A Note has been added in the ACTION to exclude the MODE change restriction of LCO 3.0.4. This exception allows entry into the applicable MODE while relying on the ACTIONS with one MSADV line inoperable. This exception is acceptable due to the redundant design of MSADV lines and the ability to restore the MSADV within 7 days while the plant remains at, or proceeds to, power operation.

With two MSADV lines inoperable, action must be taken to restore one of the MSADV lines to OPERABLE status. As the block valve can be closed to isolate an MSADV, some repairs could be possible with the unit at power. The 24 hour Completion Time is reasonable to repair inoperable MSADV lines, based on the availability of the Steam Bypass System and MSSVs, and the low probability of an event occurring during this period that requires the MSADV lines.

If the MSADV lines cannot be restored to OPERABLE status within the associated Completion Time, the unit must be placed in a MODE in which the LCO does not apply. To achieve this status, the unit must be placed in at least MODE 3 within 6 hours, and in MODE 4, without reliance upon the steam generator for heat removal, within 24 hours. The allowed Completion Times are reasonable, based on operating experience, to reach the required unit conditions from full power conditions in an orderly manner and without challenging unit systems.

To perform a controlled cooldown of the RCS, the MSADVs must be able to be opened and throttled through their full range. This SR ensures the MSADVs are tested through a full control cycle at least once per fuel cycle. Performance of inservice testing or use of an MSADV during a unit cooldown can satisfy this requirement. Operating experience has shown
that these components usually pass the SR when performed at the 18 month Frequency. Therefore, the Frequency is acceptable from a reliability standpoint.

SR 3.7.4.2

The function of the MSADV block valve is to isolate a failed open MSADV. Cycling the block valve closed and open demonstrates its capability to perform this function. Performance of inservice testing or use of the block valve during unit cooldown can satisfy this requirement. Operating experience has shown that these components usually pass the SR when performed at the 18 month Frequency. Therefore, the Frequency is acceptable from a reliability standpoint.

REFERENCES

1. FSAR, Section 10.3.
B 3.7 PLANT SYSTEMS

B 3.7.5 Auxiliary Feedwater System (AFWS)

BASES

BACKGROUND The AFWS automatically supplies feedwater to the steam generators (SGs) to remove decay heat from the Reactor Coolant System upon the loss of normal feedwater supply. The two auxiliary feedwater (AFW) pumps in each mechanical division take suction from a respective common auxiliary feedwater storage tank (AFWST) (LCO 3.7.6), each pump with a respective discharge header, and discharge to the respective steam generator secondary side through a common AFW discharge header, which connects to the steam generator downcomer main feedwater (MFW) piping inside containment. The steam generator functions as a heat sink for core decay heat. The heat load is dissipated by releasing steam to the atmosphere from the steam generators via the main steam safety valves (MSSVs) (LCO 3.7.1) or main steam atmospheric dump valves (MSADVs) (LCO 3.7.4).

The AFWS is configured into two separate mechanical divisions, each with one motor driven train and one turbine driven train. Each AFW pump, whether turbine or motor driven, provides 100% of the required AFW flow capacity to its respective SG as assumed in the accident analysis. The two AFW pumps in each mechanical division take suction from a respective common AFWST (LCO 3.7.6).

Each motor driven AFW pump is powered from an independent Class 1E power supply, and each turbine driven AFW pump receives steam from an independent main steam line, upstream of the main steam isolation valve (MSIV). The AFWS is designed to have sufficient capacity to remove decay heat and cool the unit to the Shutdown Cooling System (SCS) entry condition (MODE 4).

Each auxiliary feedwater actuation signal (AFAS) is generated to supply feedwater to its respective SG. As described in LCO 3.3.1, “Reactor Protection System (RPS) Instrumentation - Operating”, and LCO 3.3.5, “Engineered Safety Features Actuation System (ESFAS) Instrumentation”, if two-out-of-four SG wide range level instruments sense low level in their respective SG, an AFAS signal is generated to actuate the associated division of AFW (the motor driven train and turbine driven train are started simultaneously). An AFAS signal for either SG also generates a start signal to all four emergency diesel generators (EDGs).

During operation of the AFWS for RCS heat removal, SG level is automatically maintained within normal limits by the DC-powered solenoid-operated flow control (modulating) valve in the AFW pump discharge line of each AFW train in operation.
The AFWS satisfies Criterion 3 of 10 CFR 50.36(c)(2)(ii).
The AFWS is considered to be OPERABLE when the components and flow paths required to provide AFW flow to the steam generators are OPERABLE. This requires that the two motor driven AFW pumps be OPERABLE in two diverse paths, each supplying AFW flow to a separate steam generator. Two turbine driven AFW pumps shall be OPERABLE with steam supplies from the main steam lines upstream of the MSIVs, and each capable of supplying AFW flow to the dedicated steam generators which provides driving steam. The piping, valves, instrumentation, and controls in the required flow paths shall also be OPERABLE.

Assuming a postulated pipe failure concurrent with a single active component failure, four 100 percent capacity pumps are required to be OPERABLE for the AFW System. If one steam generator is not OPERABLE for reactor cooling on an initiating event, the turbine driven pump and the motor driven pump in that mechanical division are also not OPERABLE due to the respective inoperable steam generator. Concurrent with the initiating event, a single active component failure is considered for the turbine driven pump or the motor driven pump in the other mechanical division. One AFW pump and the associated SG would remain OPERABLE to provide reactor cooling because of the AFW System design that provides redundant capacity, and motive power that is both independent and diverse. The two motor driven pumps are powered from independent emergency buses and each of the two turbine driven pumps is powered from steam supplied by the respective SG, which provides diversity. The capability to withstand a single failure is accomplished by powering two 100 percent capacity motor driven pumps from independent emergency buses and by two 100 percent capacity turbine driven pumps each powered by an independent steam supply, which is a diverse means of motive power.

The LCO is modified by a Note indicating that only the motor driven train of one AFW division is required to be OPERABLE in MODE 4 when a steam generator is relied upon for heat removal. This is because of reduced heat removal requirements (such as when conducting a unit startup with a low core decay heat input), and the short period of time in MODE 4 during which AFW is required; also the steam supply available in MODE 4 may be insufficient to power a turbine driven AFW pump.
APPLICABILITY

In MODES 1, 2, and 3, the AFWS is required to be OPERABLE and to function in the event of a loss of adequate main feedwater flow to one or both SGs. In addition, the AFWS is required to supply enough makeup water to maintain SG levels within normal limits as SG secondary side inventory volume contracts as the unit cools to MODE 4 conditions.

In MODE 4, the AFWS may be used for heat removal via a steam generator.

In MODES 5 and 6, the steam generators are not normally used for decay heat removal, and the AFWS is not required.

ACTIONS

A.1

If one AFW train is inoperable, functional diversity is lost and action must be taken to restore the train to OPERABLE status within the [72] hour Completion Time of Condition A. The specified Completion Time is based on the following:

a. Redundancy and independence of the two AFW divisions,

b. Redundancy and diversity of the two AFW trains in each AFW division,

c. Availability of one OPERABLE AFW train in the affected AFW division, assuming an event renders both trains of the other AFW division inoperable,

d. Low probability of such an event occurring within the Completion Time period, and

e. Each SG can be supplied the required feedwater flow by at least one AFW train of the associated AFW division during this period.

[----------------------------------REVIEWER’S NOTE-----------------------------------

-------------------------------------------------------------------------------------------------]
B.1

If an AFW train of each AFW division is inoperable in MODE 1, 2, or 3, functional redundancy is lost and action must be taken to restore two trains of an AFW division to OPERABLE status within 72 hours. The 72 hour Completion Time is reasonable based on the reasons stated in items a, b, and e for Required Action A.1; and on the availability of one OPERABLE AFW train in one affected AFW division, assuming an event renders the remaining train of the other affected AFW division inoperable.

In addition, during the 72 hour period, one OPERABLE AFW train in each division remains available to supply feedwater to its respective SG.

C.1

With both AFW trains inoperable in one AFW division, the AFW function would be lost for events that render both trains of the unaffected AFW division inoperable. Action must be taken to restore one train of the affected AFW division to OPERABLE status within [24] hours. The [24 hour] Completion Time is based on the redundancy and diversity of the two OPERABLE AFW trains in the remaining AFW division, the time needed for repairs, and the low probability of such an event occurring during this period.

In addition, during the Completion Time period, for most events, two OPERABLE AFW trains would remain available to supply feedwater to the associated SG.

[----------------------------------REVIEWER’S NOTE-----------------------------------]


[-------------------------------------------------------------]

D.1 and D.2

When Required Action A.1, B.1, or C.1 cannot be completed within the required Completion Time, or when three AFW trains are inoperable in MODE 1, 2, or 3, the unit must be placed in a MODE in which the LCO does not apply. To achieve this status, the unit must be placed in at least
MODE 3 within 6 hours, and MODE 4 without reliance upon SGs for heat removal within 18 hours.

The allowed Completion Times are reasonable, based on operating experience, to reach the required unit conditions from full power conditions in an orderly manner and without challenging unit systems.

E.1

Required Action E.1 is modified by a Note indicating that all required MODE changes or power reductions are suspended until one AFW train is restored to OPERABLE status.

With four AFW trains (two AFW divisions) inoperable in MODE 1, 2, or 3, the unit is in a seriously degraded condition with no safety-related means for conducting a cooldown, and only limited means for conducting a cooldown with non-safety grade equipment. In such a condition, the unit should not be perturbed by any action, including a power change, that may result in a reactor trip. The seriousness of this condition requires that action be started immediately to restore one AFW train to OPERABLE status.

LCO 3.0.3 is not applicable because it could force the unit into a less safe condition.

F.1

Required Action F.1 is modified by a Note indicating that all required MODE changes or power reductions are suspended until one AFW motor driven train is restored to OPERABLE status.

With two AFW motor driven trains inoperable in MODE 4, action must be started immediately to restore the one required AFW motor driven train to OPERABLE status.

LCO 3.0.3 is not applicable because it could force the unit into a less safe condition.

SURVEILLANCE REQUIREMENTS

SR 3.7.5.1

Verifying the correct alignment for manual, power operated, and automatic valves in the AFW water and steam flow paths provides assurance that the proper flow paths exist for AFW operation. This SR does not apply to valves which are locked, sealed, or otherwise secured.
in position, since these valves are verified to be in the correct position prior to locking, sealing, or securing. This SR also does not apply to valves that cannot be inadvertently misaligned, such as check valves. This Surveillance does not require any testing or valve manipulations. Rather, it involves verification that those valves capable of potentially being mispositioned are in the correct position.

The 31 day Frequency is based on engineering judgment, is consistent with the procedural controls governing valve operation and ensures correct valve positions.

SR 3.7.5.2

Verifying that each AFW pump's developed head at the flow test point is greater than or equal to the required developed head ensures that AFW pump performance has not degraded during the cycle. Flow and differential head are normal tests of pump performance required by the ASME Operations and Maintenance (OM) Code (Ref. 2). Because it is undesirable to introduce cold AFW into the steam generators while they are operating, this testing is performed on recirculation flow. This test confirms one point on the pump design curve and is indicative of overall performance. Such in-service tests confirm component OPERABILITY, trend performance, and detect incipient failures by indicating abnormal performance. Performance of in-service testing, discussed in the ASME OM Code (Ref. 2), at 3 month intervals satisfies this requirement.

This SR is modified by a Note indicating that the SR should be deferred until suitable test conditions are established. This deferral is required because there is an insufficient steam pressure to perform the test.

SR 3.7.5.3

This SR ensures that feedwater can be delivered by each AFW train to its respective SG, in the event of any accident or transient that generates an AFAS signal, by demonstrating that each automatic valve in the flow path actuates to its correct position on an actual or simulated actuation signal. This Surveillance is not required for valves that are locked, sealed, or otherwise secured in the required position under administrative controls.

The 18 month Frequency is based on the need to perform this Surveillance under the conditions that apply during a unit outage and the potential for an unplanned transient if the Surveillance were performed with the reactor at power. The 18 month Frequency is acceptable based on the design reliability and operating experience of the equipment.
This SR is modified by a Note that states the SR is not required to be met in MODE 4. In MODE 4, the required AFW train is already aligned and operating.

SR 3.7.5.4

This SR ensures that the AFW pumps will start in the event of any accident or transient that generates an AFAS signal by demonstrating that each AFW pump starts automatically on an actual or simulated actuation signal. The 18 month Frequency is based on the need to perform this Surveillance under the conditions that apply during a unit outage and the potential for an unplanned transient if the Surveillance were performed with the reactor at power. The 18 month Frequency is acceptable based on the design reliability and operating experience of the equipment.

This SR is modified by two Notes. Note 1 indicates that the SR be deferred until suitable test conditions are established. This deferral is required because there is insufficient steam pressure to perform the test. Note 2 states that the SR is not required to be met in MODE 4. In MODE 4, the required pump is already operating.

SR 3.7.5.5

This SR ensures that the AFWS is properly aligned by verifying the flow path to each steam generator prior to entering MODE 2 operation, after 30 days in any combination of MODE 5, 6, or defueled. OPERABILITY of AFW flow paths must be verified before sufficient core heat is generated that would require the operation of the AFWS during a subsequent shutdown.

The Frequency is reasonable, based on engineering judgment, and other administrative controls to ensure that flow paths remain OPERABLE. To further ensure AFWS alignment, the OPERABILITY of the flow paths is verified following extended outages to determine that no misalignment of valves has occurred. This SR ensures that the flow path from the AFWST to the steam generators is properly aligned by requiring a verification of minimum flow capacity of 2,461 L/min (650 gpm) at 87.2 kg/cm²A (1,240 psia).

REFERENCES

1. FSAR, Subsection 10.4.9.
2. ASME OM Code.
B 3.7 PLANT SYSTEMS

B 3.7.6 Auxiliary Feedwater Storage Tank (AFWST)

BASES

BACKGROUND

The AFWST provides a safety grade source of water to the steam generators for removing decay and sensible heat from the Reactor Coolant System (RCS). The AFWST provides a passive flow of water, by gravity, to the auxiliary feedwater (AFW) pumps (LCO 3.7.5). The steam produced is released to the atmosphere by the main steam safety valves (MSSVs) or the main steam atmospheric dump valves (MSADVs). The AFW pumps operate with a continuous recirculation to the AFWST.

When the main steam isolation valves are open, the preferred means of heat removal is to discharge steam to the condenser by the non-safety grade path of the turbine bypass valves. This has the advantage of conserving condensate while minimizing releases to the environment.

Because the AFWST is a principal component in removing residual heat from the RCS, it is designed to withstand earthquakes and other natural phenomena. The AFWST is designed to seismic Category I requirements to ensure availability of the feedwater supply. Feedwater is also available from one of two 100% capacity AFWSTs as backup water sources.

A description of the AFWST is provided in FSAR Subsection 10.4.9 (Ref. 1).

APPLICABLE SAFETY ANALYSES

The AFWST provides cooling water to remove decay heat and cooldown the unit following all events in the accident analysis, Chapter 6 and 15. For anticipated operational occurrences and accidents which do not affect the OPERABILITY of the steam generators, the analysis assumption is generally 30 minutes at MODE 3 steaming through the MSSVs followed by a cooldown to shutdown cooling (SC) entry conditions at the design cooldown rate.

The limiting event for the AFW volume is the main feedwater line break with a coincident loss of offsite power. Single failures that also affect this event include the following:

a. The failure of the emergency diesel generator powering the motor driven AFW pump to the unaffected steam generator (requiring additional steam to drive the remaining AFW pump turbine); and

b. The failure of the turbine driven AFW pump (requiring a longer time for cooldown using only one motor driven AFW pump).
APPLICABLE SAFETY ANALYSES  (continued)

These are not usually the limiting failures in terms of consequences for these events.

A nonlimiting event considered in AFWST inventory determinations is a break either in the main feedwater or AFW line near where the two join. This break has the potential for dumping condensate until terminated by operator action, as the Auxiliary Feedwater Actuation System would not detect a difference in pressure between the steam generators for this break location. This loss of condensate inventory is partially compensated by the retaining of steam generator inventory.

The AFWST satisfies Criteria 2 and 3 of 10 CFR 50.36(c)(2)(ii).

LCO

To satisfy accident analysis assumptions, the AFWST must contain sufficient cooling water to remove decay heat for 30 minutes following a reactor trip from 102% RTP and then cooldown the RCS to SC entry conditions, assuming a loss of offsite power and the most adverse single failure. In doing this it must retain sufficient water to ensure adequate net positive suction head (NPSH) for the AFW pumps during the cooldown, as well as to account for any losses from the steam driven AFW pump turbine or before isolating AFW to a broken line.

The AFWST level required is a usable volume of ≥ 1,524,165 L (400,000 gal), which is based on holding the unit in MODE 3 for 8 hours followed by a cooldown to SC entry conditions at 41.7°C (75°F) per hour. This bases is established by the BTP RSB 5-4 (Ref. 2) and exceeds the volume required by the accident analysis.

OPERABILITY of the AFWST is determined by maintaining the tank level at or above the minimum required level.

APPLICABILITY

In MODES 1, 2, and 3, and in MODE 4, when a steam generator is relied upon for heat removal, the AFWST is required to be OPERABLE.

In MODES 5 and 6, the AFWST is not required because the AFW System is not required.

ACTIONS

A.1 and A.2

If one AFWST is not OPERABLE, the OPERABILITY of the backup water supply and the other AFWST must be verified by administrative means within 4 hours and once every 12 hours thereafter.
The backup water supply is the affected division’s condensate storage tank (CST), and its OPERABILITY verification requires checking the CST water volume, and the CST supply line, including the manual isolation valve, to the affected division’s AFW pump suction lines. OPERABILITY of the other AFWST must include verification of the OPERABILITY of the affected division's AFWST supply line to the affected division's AFW pump suction lines, the necessary volume of water in the other division's AFWST, and the connection line between the two AFWSTs. The AFWST must be returned to OPERABLE status within 7 days. The 4 hour Completion Time is reasonable, based on operating experience, to verify the OPERABILITY of the backup water supply and the other AFWST. Additionally, verifying the OPERABILITY of the backup water supply and the other AFWST every 12 hours is adequate to ensure the AFW supply continues to be available. The 7 day Completion Time is reasonable, based on an OPERABLE AFWST being available and the low probability of an event requiring the use of the water from the AFWST occurring during this period.

B.1 and B.2

If the AFWST cannot be restored to OPERABLE status within the associated Completion Time, the unit must be placed in a MODE in which the LCO does not apply. To achieve this status, the unit must be placed in at least MODE 3 within 6 hours, and in MODE 4, without reliance on steam generators for heat removal, within 24 hours. The allowed Completion Times are reasonable, based on operating experience, to reach the required unit conditions from full power conditions in an orderly manner and without challenging unit systems.

This SR verifies that the AFWST of each AFW division contains the required volume of cooling water. (This level is ≥ 1,524,165 L (400,000 gal).) The 12 hour Frequency is based on operating experience and the need for operator awareness of unit evolutions that could affect the AFWST inventory between checks. The 12 hour Frequency is considered adequate in view of other indications in the main control room (MCR), including alarms, to alert the operator to abnormal AFWST level deviations.
REFERENCES

1. FSAR, Subsection 10.4.9.

BACKGROUND

The Component Cooling Water System (CCWS) is a closed loop cooling water system which cools components and heat exchangers connected to the CCWS. The CCWS is capable of removing sufficient heat using various combinations of pumps and heat exchangers to:

a. Ensure a safe reactor shutdown coincident with loss of offsite power.
b. Perform a normal shutdown cooling of the reactor within 24 hours.
c. Perform a safe shutdown cooling of the reactor within 24 hours.
d. Perform post-loss of coolant accident (LOCA) cooling.
e. Perform normal power operation cooling.

The CCWS consists of two separate, independent, redundant, closed loop, safety-related divisions. Either division of the CCWS is capable of supporting 100% of the cooling functions required for a safe reactor shutdown.

Each division of the CCWS includes three CCW heat exchangers, a surge tank, two CCW pumps, a chemical addition tank, a component cooling water radiation monitor, piping, valves, controls, and instrumentation. There are two cross connections between divisions. The CCWS provides cooling water to essential and non-essential components.

The non-essential headers are isolated automatically on a safety injection actuation signal (SIAS). If these headers fail to isolate, the idle CCW pump in the respective loop will automatically start on a low pump discharge common header pressure signal. This assures that there is no flow degradation to the safety-related components. The cross connection headers are also isolated automatically on an SIAS. The non-essential headers, cross connection lines, and the reactor coolant pump (RCP) headers lines isolate on a low-low surge tank level.

Makeup water to the CCWS is normally supplied by the Makeup Demineralized System. The backup makeup water source is from the Auxiliary Feedwater (AFW) System.
The CCWS serves as an intermediate cooling water system between the radioactive systems and the Essential Service Water System (ESWS). A radiation monitor is provided at the outlet of the component cooling water pumps to detect any radioactive leakage into the CCWS.

Additional information on the design and operation of the system, along with a list of components served, can be found in Chapter 9 (Ref. 1).

<table>
<thead>
<tr>
<th>APPLICABLE SAFETY ANALYSES</th>
</tr>
</thead>
<tbody>
<tr>
<td>The CCWS, in conjunction with the ESWS and the ultimate heat sink (UHS), is capable of removing sufficient heat from the essential heat exchangers to ensure a safe reactor shutdown and cooling following a postulated accident coincident with a loss of offsite power.</td>
</tr>
</tbody>
</table>

The CCWS, in conjunction with the ESWS, is capable of maintaining the outlet temperature of the CCW heat exchanger within the limits of 18.33°C (65°F) and 43.33°C (110°F) during a design basis accident with loss of offsite power. This can be attained with one component cooling water (CCW) pump and one ESW pump in a single division.

For a safe shutdown, the CCWS, in conjunction with the Shutdown Cooling System (SCS) and ESWS, are designed to cool the reactor coolant from 176.7°C (350°F) to 93.3°C (200°F) through the shutdown cooling heat exchangers and the component cooling water heat exchangers. The reactor can be cooled to 93.3°C (200°F) within 24 hours after reactor shutdown by first cooling the reactor coolant to 176.7°C (350°F) through a steam generator and then cooling to 93.3°C (200°F) using one SCS pump, one essential service water (ESW) pump and one CCW pump in a single division of the SCS, CCWS, and ESWS. The CCW flow to non-safety heat loads has to be isolated.

A single failure of any component in the CCWS will not impair the ability of the CCWS to meet its safety functional requirements.

For the normal shutdown, the CCWS, in conjunction with the SCS and ESWS, is designed to cool the reactor coolant from 176.7°C (350°F) to 60.0°C (140°F) through the shutdown cooling heat exchangers and the CCW heat exchangers. The reactor can be cooled to 60.0°C (140°F) within 24 hours after reactor shutdown by first cooling the reactor coolant to 176.7°C (350°F) through the steam generators and then cooling to 60.0°C (140°F) by using both divisions of SCS, CCWS, and ESWS.

The CCWS satisfies Criterion 3 of 10 CFR 50.36(c)(2)(ii).
The CCWS divisions are independent of each other to the degree that each has separate controls, power supplies, and the operation of one does not depend on the other. In the event of a design basis accident (DBA), one CCWS division is required to provide the minimum heat removal capability assumed in the safety analysis for the systems to which it supplies cooling water. To ensure this requirement is met, two divisions of CCWS must be OPERABLE. At least one division will operate assuming the LCO’s worst single active failure occurs coincident with the loss of offsite power.

A division is considered OPERABLE when:

a. Pump and associated surge tank are OPERABLE.

b. Associated piping, valves, two heat exchangers, and instrumentation and controls required to perform safety-related functions are OPERABLE.

The isolation of CCW to non-safety-related components or systems can render those components or systems inoperable, but does not affect the OPERABILITY of the CCWS.

In MODES 1, 2, 3, and 4 the CCWS is a normally operating system, which must be available to perform its post-accident safety functions, primarily Reactor Coolant System (RCS) heat removal, by cooling the shutdown cooling heat exchanger.

In MODES 5 and 6, the OPERABILITY requirements of the CCWS are determined by the systems it supports.

Required Action A.1 is modified by two Notes. The first requires entry into the applicable Conditions and Required Actions of LCO 3.8.1, “AC Sources – Operating,” for an emergency diesel generator made inoperable by CCW. The second requires entry into the applicable Conditions and Required Actions of LCO 3.4.6, “RCS Loops – MODE 4,” for an SCS division made inoperable by CCW. These are exceptions to LCO 3.0.6 and ensure the proper ACTIONS are taken for these components.

In MODE 1, 2, 3, or 4 with one CCW division inoperable, action must be taken to restore OPERABLE status within 72 hours. In this Condition, the remaining OPERABLE CCW division is capable to perform the heat removal function. The 72 hour Completion Time is based on the
BASES

ACTIONS (continued)

redundant capabilities afforded by the OPERABLE division and the low probability of a DBA occurring during this period.

B.1 and B.2

If the CCW division cannot be restored to OPERABLE status within the associated Completion Time, the unit must be placed in a MODE in which the LCO does not apply. To achieve this status, the unit must be placed in at least MODE 3 within 6 hours and in MODE 5 within 36 hours.

The allowed Completion Times are reasonable, based on operating experience, to reach the required unit conditions from full power conditions in an orderly manner and without challenging unit systems.

SURVEILLANCE REQUIREMENTS

SR 3.7.7.1

Verifying the correct alignment for manual, power operated, and automatic valves in the CCW flow path provides assurance that the proper flow paths are available for CCW operation. This SR does not apply to valves which are locked, sealed, or otherwise secured in position, since they were verified to be in the correct position prior to locking, sealing, or securing. This SR also does not apply to valves which cannot be inadvertently misaligned, such as check valves. This Surveillance does not require any testing or valve manipulation. Rather, it involves verification that those valves capable of potentially being mispositioned are in their correct positions.

This SR is modified by a Note indicating that the isolation of the CCW components or systems can render those components inoperable but does not affect the OPERABILITY of the CCWS.

The 31 day Frequency, based on engineering judgment, is consistent with the procedural controls governing valve operation and ensures correct valve positions.

SR 3.7.7.2

This SR verifies proper automatic operation of the CCW valves on an actual or simulated actuation signal. The CCWS is a normally operating system that cannot be fully actuated as part of routine testing during normal operation. The 18 month Frequency is based on the need to perform this Surveillance under the conditions that apply during a unit outage and the potential for an unplanned transient if the Surveillance
SURVEILLANCE REQUIREMENTS (continued)

were performed with the reactor at power. Operating experience has shown that these components usually pass the Surveillance when performed at the 18 month Frequency. Therefore, the Frequency is acceptable from a reliability standpoint.

SR 3.7.7.3

This SR verifies proper automatic operation of the CCW pumps on an actual or simulated actuation signal. The CCWS is a normally operating system that cannot be fully actuated as part of routine testing during normal operation. The 18 month Frequency is based on the need to perform this Surveillance under the conditions that apply during a unit outage and the potential for an unplanned transient if the surveillance were performed with the reactor at power. Operating experience has shown these components usually pass the Surveillance when performed at the 18 month Frequency. Therefore, the Frequency is acceptable from a reliability standpoint.

REFERENCES

1. FSAR, Subsection 9.2.2.
B 3.7 PLANT SYSTEMS

B 3.7.8 Essential Service Water System (ESWS)

BASES

BACKGROUND
The Essential Service Water System (ESWS) provides a heat sink for the removal of process and operating heat from safety-related components during a transient or design basis accident (DBA). During normal operation or a normal shutdown, the ESWS also provides this function for various safety-related and non-safety-related components through the Component Cooling Water System (CCWS).

The ESWS consists of two separate, redundant, open loop, safety-related divisions. Each division cools one of two divisions of the CCWS, which in turn cools 100% of the safety-related loads. The ESWS operates at a lower pressure than the CCWS to prevent contamination of the CCWS with raw water.

Each division of the ESWS consists of two pumps, three debris filters and associated piping, valves, controls and instrumentation. The essential service water (ESW) pumps circulate cooling water to the CCW heat exchanger and back to the ultimate heat sink. Provisions are made to ensure a continuous flow of cooling water under normal and accident conditions.

Additional information on the design and operation of the system, along with a list of the components served, can be found in FSAR Subsection 9.2.1 (Ref. 1).

APPLICABLE SAFETY ANALYSES
The ESWS, in conjunction with the CCWS and ultimate heat sink (UHS), is capable of removing sufficient heat to ensure a safe reactor shutdown coincident with a loss of offsite power.

The ESWS is capable of maintaining the CCWS supply temperature of 43.33°C (110°F) or less following the DBA under the most adverse historical meteorological conditions consistent with the intent of Nuclear Regulatory Commission (NRC) Regulatory Guide 1.27. This can be attained with one ESW pump in a single division.

For a safe shutdown, the ESWS, in conjunction with the Shutdown Cooling System (SCS) and Component Cooling Water System (CCWS), are designed to cool the reactor coolant from 176.7°C (350°F) to 93.3°C (200°F) through the shutdown cooling (SC) heat exchangers and the component cooling water (CCW) heat exchangers. The reactor can be cooled to 93.3°C (200°F) within 24 hours after reactor shutdown by first cooling the reactor coolant to 176.7°C (350°F) through a steam generator.
and then cooling to 93.3°C (200°F) using one SC pump, one ESW pump, and one CCW pump in a single division of the SCS, CCWS, and ESWS. The CCW flow to non-safety heat loads has to be isolated.

A single failure of any component in the ESWS will not impair the ability of the ESWS to meet its functional requirements.

For the normal shutdown, the ESWS, in conjunction with the CCWS and SCS, is designed to cool the reactor coolant from 176.7°C (350°F) to 60°C (140°F) through the SC heat exchangers and the CCW heat exchangers. The reactor coolant can be cooled to 60°C (140°F) within 24 hours after reactor shutdown by first cooling the reactor coolant to 176.7°C (350°F) through the steam generators and then cooling the reactor coolant to 60°C (140°F) by using both divisions of the SCS, CCWS, and ESWS.

The ESWS, in conjunction with the CCWS, is designed to provide a maximum CCW temperature of 35.0°C (95°F) or less during normal operating MODES.

The ESWS satisfies Criterion 3 of 10 CFR 50.36(c)(2)(ii).

LCO

Two ESWS divisions provide the required redundancy to ensure the system functions to remove post-accident heat loads, assuming the worst single active failure occurs coincident with the loss of offsite power.

An ESWS division is considered OPERABLE when:

a. An associated pump is OPERABLE.

b. The associated piping, valves, and instrumentation and controls required to perform the safety-related functions are OPERABLE.

APPLICABILITY

In MODES 1, 2, 3, and 4 the ESWS is a normally operating system, which is required to support the OPERABILITY of the equipment serviced by the ESWS and required to be OPERABLE in these MODES.

In MODES 5 and 6, the OPERABILITY requirements of the ESWS are determined by the systems it supports.
Required Action A.1 is modified by two Notes. The first Note indicates that the applicable Conditions of LCO 3.8.1, “AC Sources – Operating,” should be entered if the inoperable ESWS division results in an inoperable emergency diesel generator. The second Note indicates that the applicable Conditions and Required Actions of LCO 3.4.6, “RCS Loops – MODE 4,” should be entered if an inoperable ESWS division results in an inoperable SCS division. These are exceptions to LCO 3.0.6 and ensure the proper ACTIONS are taken for these components.

In MODES 1, 2, 3, and 4 with one ESWS division inoperable, action must be taken to restore OPERABLE status within 72 hours. In this Condition, the remaining OPERABLE ESWS division is adequate to perform the heat removal function. However, the overall reliability is reduced because a single failure in the ESWS divisions could result in loss of ESWS function.

The 72 hour Completion Time is based on the redundant capabilities afforded by the OPERABLE division and the low probability of a DBA occurring during this time period.

The unit must be placed in a MODE in which the LCO does not apply if the ESWS division cannot be restored to OPERABLE status in the associated Completion Time. This is done by placing the plant in at least MODE 3 within 6 hours and MODE 5 within 36 hours. The allowed Completion Times are reasonable based on operating experience to reach the required MODES from full power operation without challenging unit systems.

Verifying the correct alignment for manual, power operated, and automatic valves in the ESWS flow path ensures that the proper flow paths exist for ESWS operation. This SR does not apply to valves that are locked, sealed, or otherwise secured in position, since they are verified to be in the correct position prior to locking, sealing, or securing. This SR also does not apply to valves that cannot be inadvertently misaligned, such as check valves. This Surveillance does not require any testing or valve manipulation; rather, it involves verification that those valves capable of potentially being mispositioned are in the correct position. This SR is modified by a Note indicating that the isolation of
Bases

Surveillance Requirements (continued)

The ESWS components or systems can render those components inoperable but does not affect the operability of the ESWS.

The 31 day frequency is based on engineering judgment, is consistent with the procedural controls governing valve operation and ensures correct valve positions.

SR 3.7.8.2

This SR verifies proper automatic operation of the ESWS valves on an actual or simulated actuation signal. The ESWS is a normally operating system that cannot be fully actuated as part of the normal testing. This surveillance is not required for valves that are locked, sealed, or otherwise secured in the required position under administrative controls.

The 18 month frequency is based on the need to perform this surveillance under the conditions that apply during a unit outage and the potential for an unplanned transient if the surveillance were performed with the reactor at power. Operating experience has shown that these components usually pass the surveillance when performed at the 18 month frequency. Therefore, the frequency is acceptable from a reliability standpoint.

SR 3.7.8.3

The SR verifies proper automatic operation of the ESWS pumps on an actual or simulated actuation signal. The ESWS is a normally operating system that cannot be fully actuated as part of the normal testing during normal operation. The 18 month frequency is based on the need to perform this surveillance under the conditions that apply during a unit outage and the potential for an unplanned transient if the surveillance were performed with the reactor at power. Operating experience has shown that these components usually pass the surveillance when performed at the 18 month frequency. Therefore, the frequency is acceptable from a reliability standpoint.

References
1. FSAR, Subsection 9.2.1.
The UHS provides a heat sink for process and operating heat from safety-related components during a design basis accident (DBA) or transient, as well as during normal operation. This is done by using the Essential Service Water System (ESWS) and the Component Cooling Water System (CCWS).

The safety function of the UHS is to dissipate the maximum heat load of all MODES of operation including that of a loss of coolant accident (LOCA) and loss of offsite power (LOOP) under the worst combination of adverse environmental conditions.

The four mechanical draft cooling towers and two basins are safety-related, seismic Category I structures sized to provide heat dissipation for safe shutdown or post-accident. The cooling tower is protected from tornadoes, external missiles, and seismic phenomena.

The basic performance requirements are that a 30 day supply of water be available, and that the design basis temperatures of safety-related equipment not be exceeded.

Additional information on the design and operation of the system along with a list of components served can be found in Reference 1.
The operating limits are based on 3.5 hours after shutdown. [A conservative heat transfer analysis for the worst case accident was performed to ensure that the cooling tower capacity and the basin water inventory adequately remove the heat load for the worst case accident.] The UHS is designed in accordance with Nuclear Regulatory Commission (NRC) Regulatory Guide (RG) 1.27 (Ref. 2), which requires a 30 day supply of cooling water in the UHS.

The UHS satisfies Criterion 3 of 10 CFR 50.36(c)(2)(ii).

[A] UHS [division] is considered OPERABLE when:

a. [Cooling tower fans in a cooling tower are OPERABLE.]

b. [The associated piping, valves, and instrumentation and controls required to perform the safety-related function are OPERABLE.]

c. Water temperature of the UHS is $\leq 33.2^\circ C$ (91.8°F) and water level of the UHS is $\geq 7.90$ m (25.93 ft) from the bottom of basin with capability to makeup from OPERABLE makeup source during normal operation.] Definition of OPERABLE makeup source is to be provided by the Combined License (COL) applicant.

In MODES 1, 2, 3, and 4, the UHS is a normally operating system that is required to support the OPERABILITY of the equipment serviced by the UHS and required to be OPERABLE in these MODES.

In MODES 5 and 6, the OPERABILITY requirements of the UHS are determined by the systems it supports.
A.1

[If one UHS division is inoperable, action must be taken to restore the inoperable cooling tower(s) and associated fan(s) to OPERABLE status within 72 hours. In this Condition, the remaining OPERABLE UHS division is adequate to perform the heat removal function. However, the overall reliability is reduced because a single failure in the UHS division could result in loss of UHS function.]

The 72 hour Completion Time is based on the redundant capabilities afforded by the OPERABLE division and the low probability of a DBA occurring during this time period.]

B.1

If [the Required Actions and Completion Times of Condition A are not met, or] the UHS is inoperable [for reasons other than Condition A], the unit must be placed in a MODE in which the LCO does not apply. To achieve this status, the unit must be placed in at least MODE 3 within 6 hours and MODE 5 within 36 hours.

The allowed Completion Times are reasonable, based on operating experience, to reach the required unit conditions from full power conditions in an orderly manner and without challenging unit systems.

SR 3.7.9.1

[This SR verifies adequate 30 days cooling can be maintained.] The level specified also ensures sufficient NPSH is available for operating the ESW pumps [during 30 days] following DBA or safe shutdown with LOOP. The 24 hour Frequency is based on operating experience related to the trending of the parameter variations during the applicable MODES. This SR verifies that the UHS water level is ≥ [7.90 m (25.93 ft) from the bottom of the basin.]

SR 3.7.9.2

This SR verifies that the ESWS is available to cool the CCWS to at least its maximum design temperature within the maximum accident or normal design heat loads for 30 days following a DBA. The 24 hour Frequency is based on operating experience related to the trending of the parameter variations during the applicable MODES. This SR verifies that the UHS water temperature is ≤ [33.2°C (91.8°F).]
BASES

SURVEILLANCE REQUIREMENTS (continued)

SR 3.7.9.3

[Operating each cooling tower fan for ≥ 15 minutes verifies that all fans are OPERABLE and that all associated controls are functioning properly. It also ensures that fan or motor failure or excessive vibration can be detected for corrective action. The 31 day Frequency is based on operating experience, the known reliability of the fan units, the redundancy available, and the low probability of significant degradation of the UHS cooling tower fans occurring between surveillances.]

SR 3.7.9.4

[This SR verifies the correct alignment for manual, power operated, and automatic valves in the UHS flow path ensures that the proper flow paths exist for UHS operation. This SR does not apply to valves that are locked, sealed, or otherwise secured in position since they are verified to be in the correct position prior to locking, sealing, or securing. This SR also does not apply to valves that cannot be inadvertently misaligned, such as check valves. This Surveillance does not require any testing or valve manipulation. Rather, it involves verification that those valves capable of potentially being mispositioned are in the correct position.]

[The 31 day Frequency is based on engineering judgment, is consistent with the procedural controls governing valve operation and ensures correct valve positions.]

SR 3.7.9.5

[This SR verifies proper automatic operation of the UHS valves on an actual or simulated actuation signal. The UHS is a normally operating system that cannot be fully actuated as part of the normal testing. This Surveillance is not required for valves that are locked, sealed, or otherwise secured in the required position under administrative controls.]

[The 18 month Frequency is based on the need to perform this Surveillance under the conditions that apply during a unit outage and the potential for an unplanned transient if the Surveillance were performed with the reactor at power. Operating experience has shown that these components usually pass the Surveillance when performed at the 18 month Frequency. Therefore, the Frequency is acceptable from a reliability standpoint.]
SURVEILLANCE REQUIREMENTS (continued)

SR 3.7.9.6

[The SR verifies proper automatic operation of the cooling tower fans on an actual or simulated actuation signal. The UHS is a normally operating system that cannot be fully actuated as part of the normal testing during normal operation. The 18 month Frequency is based on the need to perform this Surveillance under the conditions that apply during a unit outage and the potential for an unplanned transient if the Surveillance were performed with the reactor at power. Operating experience has shown that these components usually pass the Surveillance when performed at the 18 month Frequency. Therefore, the Frequency is acceptable from a reliability standpoint.]

REFERENCES

1. FSAR, Subsection 9.2.5.

The ECWS provides a heat sink for the removal of process and operating heat from selected safety-related air handling systems during a design basis accident (DBA) or transient.

The ECWS is a closed loop system consisting of two independent divisions. Each 100% capacity division includes two 100% capacity chillers and chilled water pumps, a compression tank, a chilled water makeup pump, an air separator, a chemical addition tank, piping, valves, controls, and instrumentation. An independent, 100% capacity chilled water refrigeration unit cools each division. The ECWS supplies chilled water to the heating, ventilation, and air conditioning (HVAC) units in engineered safety features (ESF) equipment areas (e.g., main control room, electrical equipment room, and safety injection pump area).

Additional information about the design and operation of the system, along with a list of components served, can be found in FSAR Subsection 9.2.7 (Ref. 1).

The design basis of the ECWS is to remove the post-accident heat load from ESF spaces following a DBA coincident with a loss of offsite power. Each division provides chilled water to the HVAC units at the design temperature of 5.6°C (42°F).

The maximum heat load in the ESF pump room area occurs during the recirculation phase following a loss of coolant accident. During recirculation, hot fluid from the in-containment refueling water storage tank (IRWST) is supplied to the safety injection (SI) and containment spray pumps. This heat load to the area atmosphere must be removed by the ECWS to ensure these systems remain OPERABLE.

The ECWS satisfies Criterion 3 of 10 CFR 50.36(c)(2)(ii).

Two ECWS divisions are required to be OPERABLE to provide the required redundancy to ensure that the system functions to remove post-accident heat loads, assuming the worst single failure.

An ECWS division is considered OPERABLE when:

a. One chiller, chilled water pump, chilled water makeup pump and compression tank are OPERABLE.
b. The associated piping, valves, refrigeration unit, and instrumentation and controls required to perform the safety-related function are OPERABLE.

APPLICABILITY

In MODES 1, 2, 3, and 4 the ECWS is required to be OPERABLE when a LOCA or other accident would require ESF operation.

In MODES 5 and 6, potential heat loads are smaller and the probability of accidents requiring the ECWS is low.

ACTIONS

A.1

If one ECWS division is inoperable, action must be taken to restore OPERABLE status within 7 days. In this condition, one OPERABLE ECWS division is adequate to perform the cooling function. The 7 day Completion Time is reasonable based on the low probability of an event occurring during this time, the 100% capacity OPERABLE ECWS division, and the redundant availability of the Normal HVAC System.

B.1 and B.2

If the ECWS division cannot be restored to OPERABLE status within the associated Completion Time, the unit must be placed in a MODE in which the LCO does not apply. To achieve this status, the unit must be placed in at least MODE 3 within 6 hours, and in MODE 5 within 36 hours.

The allowed Completion Times are reasonable, based on operating experience, to reach the required unit conditions from full power conditions in an orderly manner and without challenging unit systems.

SURVEILLANCE REQUIREMENTS

SR 3.7.10.1

Verifying the correct alignment for manual, power operated, and automatic valves in the ECWS flow path provides assurance that the proper flow paths exist for ECWS operation. This SR does not apply to valves that are locked, sealed, or otherwise secured in position since they are verified to be in the correct position prior to locking, sealing, or securing. This SR also does not apply to valves that cannot be inadvertently misaligned, such as check valves. This Surveillance does not require any testing or valve manipulation; rather, it involves
verification that those valves capable of potentially being mispositioned are in the correct position.

The 31 day Frequency is based on engineering judgment, is consistent with the procedural controls governing valve operation and ensures correct valve positions.

SR 3.7.10.2

This SR verifies proper automatic operation of the ECWS components that the ECW pumps will start on an actual or simulated actuation signal.

The 18 month Frequency is based on the need to perform this Surveillance under the conditions that apply during unit outage and the potential for an unplanned transient if the Surveillance were performed with the reactor at power. The 18 month Frequency is based on operating experience and design reliability of the equipment.

REFERENCES

1. FSAR, Subsection 9.2.7.
B 3.7 PLANT SYSTEMS

B 3.7.11 Control Room HVAC System (CRHS)

BASES

BACKGROUND

The CRHS consists of Control Room Emergency Makeup Air Cleaning System (CREACS) and Control Room Supply and Return System (CRSRS).

The CREACS provides a protected environment from which occupants can control the unit following an uncontrolled released of radioactivity, [toxic gas,] or smoke. The CRSRS provides air temperature control for the control room.

The CREACS consists of two independent, redundant emergency outside air makeup ducts, isolation dampers, and two air cleaning units (ACUs) that recirculate and filter the air in the control room envelope (CRE). Each ACU consists of a moisture separator, two electric heating coils, a prefilter, a high efficiency particulate air (HEPA) filter, an activated carbon adsorber section for removal of gaseous activity (principally iodine), a postfilter, and two fans for filtering the outside makeup air and part of recirculated CRE air. Ductwork, dampers, and instrumentation also form part of the system. The prefilters and moisture separator remove any large particles in the air, and any entrained water droplets present to prevent excessive loading of the HEPA filters and carbon adsorbers. Continuous operation of each ACU for at least 15 minutes per month with the heaters on reduces moisture buildup on the HEPA filters and adsorbers. Both the moisture separator and heater are important to the effectiveness of the carbon adsorbers. Postfilter follows the adsorber section to collect carbon fines and provides backup in case of failure of the main HEPA filter bank.

The CRSRS consists of dual outside air intakes, normal outside makeup duct, isolation dampers, and four air handling units (AHUs) that provides cooling and heating of recirculated CRE air. Each AHU consists of a heating coil, a cooling coil, a fan, and instrumentation and controls to provide for control room temperature control. Two AHUs are provided per division and the cooling coils of the two AHUs in a division receive chilled water from the same division of the essential chilled water system.

The CRE is the area within the confines of the CRE boundary that contains the spaces that control room occupants inhabit to control the unit during normal and accident conditions. This area encompasses the control room and other non-critical areas to which frequent personnel access or continuous occupancy is not necessary in the event of an accident. The CRE is protected during normal operation, natural events,
and accident conditions. The CRE boundary is the combination of walls, floor, roof, ducting, doors, penetrations and equipment that physically form the CRE.

The OPERABILITY of the CRE boundary must be maintained to ensure that the inleakage of unfiltered air into the CRE will not exceed the inleakage assumed in the licensing basis analysis of design basis accident (DBA) consequences to CRE occupants.

The CRE and its boundary are defined in the Control Room Envelope Habitability Program.

The CRHS operation to maintain the control room temperature is discussed in FSAR, Subsection 9.4.1 (Ref. 1). Upon receipt of the actuating signal(s), normal makeup air supply to the AHU is isolated, and the stream of ventilation air is recirculated through the filter trains of the CREACS.

[----------------------------------REVIEWER’S NOTE-----------------------------------
The need for toxic gas isolation mode will be determined by the COL applicant.

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Actuation of the CRHS places the system into the emergency mode for protection from radiation [or the toxic gas isolation mode for protection from toxic gas, depending on the initiation signal]. Upon receipt of an actuation signal for the emergency mode of operation, the unfiltered normal makeup air path is isolated, exhaust isolation dampers are closed, and the CREACS of the operating division is automatically started. The emergency mode initiates pressurization and filtered ventilation of the air supply to the CRE.

Outside air is filtered, and then added to the air being recirculated from the CRE. Pressurization of the CRE minimizes infiltration of unfiltered air through the CRE boundary from all the surrounding areas adjacent to the CRE boundary.

[Upon detection of a toxic gas, the toxic gas detector will initiate complete closure of outside intake isolation dampers to the CRE.] The air entering the CRE is continuously monitored by radiation [and toxic gas] detectors. One detector output above the setpoint causes actuation of the emergency mode [or the toxic gas isolation mode] as required. [The actions of the toxic gas isolation mode take precedence, and will override the action of the emergency mode.]
The CRHS operating at a flow rate of 6,286 cm/h (3,700 cfm) pressurizes the control room to about 3.175 mm (0.125 in) water gauge relative to external areas adjacent to the CRE boundary. The CRHS operation in maintaining the CRE habitable is discussed in FSAR, Section 6.4 (Ref. 2).

Normally open isolation dampers are arranged in series pairs so that the failure of one damper to shut will not result in a breach of isolation. The CRHS is designed in accordance with seismic Category I requirements.

The CRHS is designed to maintain a habitability environment in the CRE for 30 days of continuous occupancy after a DBA without exceeding a 50 mSv (5 rem) whole body dose or its equivalent to any part of the body.

The CRHS components are arranged in redundant safety-related ventilation divisions. The CRHS provides airborne radiological protection for the CRE occupants, as demonstrated by the CRE occupant dose analyses for the most limiting DBA fission product release presented in FSAR, Chapter 15 (Ref. 3).

The location of components and ducting within the CRE ensures an adequate supply of filtered air to all areas requiring access.

The CRHS provides protection from smoke [and toxic gas] to the CRE occupants. [The analysis of toxic gas releases demonstrates that the toxicity limits are not exceeded in the CRE following a toxic gas release (Ref. 2).] The evaluation of a smoke challenge demonstrates that it will not result in the inability of the CRE occupants to control the reactor either from the control room or from the remote shutdown room (Ref. 4).

The worst case single active failure of a component of the CRHS, assuming a loss of offsite power, does not impair the ability of the system to perform its design function.

The CRHS satisfies Criterion 3 of 10 CFR 50.36 (c)(2)(ii).

Two independent and redundant divisions of the CRHS are required to be OPERABLE to ensure that one division is available during an event requiring the CRHS, if a single failure disables the other division. An OPERABLE CRHS division requires the emergency makeup air cleaning unit (ACU) in the associated CREACS division and one of the two air handling units (AHUs) in the associated CRSRS division to be OPERABLE. The outside air intake isolation dampers, the ACU inlet isolation damper, the ACU return air isolation damper, the emergency makeup ACU fan, and the ACU discharge airflow control damper, which
are associated with the required AHU flow path, are also required to be OPERABLE for OPERABILITY of the CRHS division.

Total CRHS failure, such as from a loss of both CRSRS divisions, both CREACS divisions, or one CRSRS division and the CREACS in the opposite division, or from an inoperable CRE boundary, could result in exceeding a dose of 50 mSv (5 rem) to the control room operators in the event of an accident with a large radioactive release.

Total CRSRS failure, such as from the loss of all AHUs, could result in exceeding operating temperature limits of equipment in the CRE, not just in the event of an accident when the CRSRS may be needed to operate in the recirculation or emergency mode, but also during normal operation.

Each CRHS division is considered OPERABLE in the emergency mode when the individual components necessary to limit CRE occupant exposure are OPERABLE. A CRHS division is considered OPERABLE in the emergency mode when the associated:

a. One of two fans in the ACU is OPERABLE.

b. One of two electric heating coils in the ACU is OPERABLE.

c. HEPA filter and carbon adsorber are not excessively restricting flow and are capable of performing their filtration functions.

d. One of two AHUs with associated AHU fan, AHU heating coil, AHU cooling coil, and AHU discharge flow control damper is OPERABLE.

e. One of two outside air intake isolation dampers in each of two outside air intake paths is OPERABLE.

f. One of two AHU inlet isolation dampers in each of the two normal makeup paths to the AHU inlet is OPERABLE.

g. One of two ACU inlet isolation dampers is OPERABLE.

h. One of two ACU return air isolation dampers is OPERABLE.

i. One of two ACU discharge flow control dampers is OPERABLE.

j. One of two kitchen and toilet exhaust isolation dampers is OPERABLE.

k. One of two smoke removal isolation dampers is OPERABLE.
A CRHS division is considered OPERABLE in the isolation mode when
the above components, with the exception of the individual components
associated with the ACU, are OPERABLE.

The normal and isolation modes of CRHS operation do not include using
the ACU function, but regardless of whether the CRHS is operating in the
normal, emergency, or isolation mode, two CREACS divisions (each with
its ACU and associated required fan and dampers) must still be
OPERABLE when the unit is in the Applicability of LCO 3.7.11.

In order for the CREACS divisions to be considered OPERABLE, the
CRE boundary must be maintained such that the CRE occupant dose
from a large radioactive release does not exceed the calculated dose in
the licensing basis consequence analyses for DBAs, and that CRE
classified occupants are protected from [toxic gas and] smoke.

The LCO is modified by a Note allowing the CRE boundary to be opened
 intermittently under administrative controls. This Note only applies to
openings in the CRE boundary that can be rapidly restored to the design
condition, such as doors, hatches, floor plugs, and access panels. For
entry and exit through doors, the administrative control of the opening is
performed by the person(s) entering or exiting the area. For other
openings, these controls should be proceduralized and consist of
stationing a dedicated individual at the opening who is in continuous
communication with the operators in the CRE. This individual will have a
method to rapidly close the opening and to restore the CRE boundary to
a condition equivalent to the design condition when a need for CRE
isolation indicated.

In MODES 1, 2, 3, 4, [5, and 6] and during movement of irradiated fuel
assemblies, the CRHS must be OPERABLE to ensure that the CRE will
remain habitable during and following a DBA and ensure that the control
room temperature will not exceed equipment operational requirements
following isolation of the control room.

[In MODES 5 and 6, the CRHS is also required to cope with a failure of
the Gaseous Radwaste System.]

During movement of irradiated fuel assemblies, the CRHS must be
OPERABLE to cope with the radioactivity release from a fuel handling
accident.
With one CREACS division inoperable for reasons other than an inoperable CRE boundary, action must be taken to restore the division to OPERABLE status within 7 days. In this condition, the remaining OPERABLE CREACS division is adequate to perform the CRE occupant protection function. However, the overall reliability is reduced because a single failure in the OPERABLE CREACS division could result in loss of the CREACS function. The 7 day Completion Time is based on the low probability of a DBA occurring during this time period, and the ability of the remaining division to provide the required capabilities.

An OPERABLE CRSRS division requires just one AHU. With one CRSRS division inoperable, action must be taken to restore the division to OPERABLE status within 7 days. In this condition, the remaining OPERABLE CRSRS division is adequate to maintain the control room temperature and relative humidity within limits. However, the overall reliability is reduced because a single failure in the OPERABLE CRSRS division could result in loss of the CRSRS function. The 7 day Completion Time is based on the low probability of a DBA occurring during this time period and the ability of the remaining AHU of the OPERABLE CRSRS division to provide the required capabilities.

If the unfiltered inleakage of potentially contaminated air past the CRE boundary and into the CRE can result in CRE occupant radiological dose greater than the calculated dose of the licensing basis analyses of DBA consequences (allowed to be up to 50 mSv (5 rem) whole body or its equivalent to any part of the body), or inadequate protection of CRE occupants from [toxic gas or] smoke, the CRE boundary is inoperable. Actions must be taken to restore an OPERABLE CRE boundary within 90 days.

During the period that the CRE boundary is considered inoperable, action must be initiated to implement mitigating actions to lessen the effect on CRE occupants from the potential hazards of a radiological [or toxic gas] event or challenge from smoke. Actions must be taken within 24 hours to verify that in the event of a DBA, the mitigating actions will ensure that CRE occupant radiological exposures will not exceed the calculated dose of the licensing basis analyses of DBA consequences, and that CRE occupants are protected from [toxic gas and] smoke. These mitigating actions (i.e., actions that are taken to offset the consequences of the inoperable CRE boundary) should be preplanned for implementation upon entry into the condition, regardless of whether entry is intentional or
unintentional. The 24 hour Completion Time is reasonable based on the low probability of a DBA occurring during this time period and the use of mitigating actions. The 90 day Completion Time is reasonable based on the determination that the mitigating actions will ensure protection of CRE occupants within analyzed limits while limiting the probability that CRE occupants will have to implement protective measures that could adversely affect their ability to control the reactor and maintain it in a safe shutdown condition in the event of a DBA. In addition, the 90 day Completion Time is a reasonable time to diagnose, plan, and possibly repair and test most problems with the CRE boundary.

D.1 and D.2

In MODE 1, 2, 3, or 4, if the inoperable CREACS or CRSRS division or the CRE boundary cannot be restored to OPERABLE status within the required Completion Time, the unit must be placed in a MODE that minimizes the accident risk. To achieve this status, the unit must be placed in at least MODE 3 within 6 hours, and MODE 5 within 36 hours.

The allowed Completion Times are reasonable, based on operating experience, to reach the required unit conditions from full power conditions in an orderly manner and without challenging unit systems.

E.1 and E.2

Required Action E.1 is performed manually.

[In MODE 5 or 6, or during] [During] movement of irradiated fuel assemblies, if Required Action A.1 or B.1 cannot be completed within the required Completion Time, the CREACS and CRSRS of the OPERABLE CRHS division must be immediately placed in the emergency mode of operation. This action ensures that the remaining division is OPERABLE, that no failures preventing automatic actuation will occur, and that any active failure will be readily detected.

An alternative to Required Action E.1 is Required Action[s] E.2[.1 and E.2.2] to immediately suspend activities that could result in a release of radioactivity that may require isolation of the CRE. This places the unit in a condition that minimizes the accident risk.

This does not preclude the movement of fuel assemblies to a safe position.
The need for toxic gas isolation mode will be determined by the COL applicant.

Required Action E.1 is modified by a Note that requires placing the CRHS in the toxic gas isolation mode if the automatic toxic gas isolation mode is inoperable.

F.1 [and F.2]

In MODE 5 or 6, or during movement of irradiated fuel assemblies with two CREACS divisions inoperable or two CRSRS divisions inoperable, or with one or two CREACS divisions inoperable due to an inoperable CRE boundary, Required Action[s] F.1 [and F.2] must be taken immediately to suspend activities that could result in a release of radioactivity that may require isolation of the CRE. This places the unit in a condition that minimizes the accident risk. This does not preclude the movement of fuel to a safe position.

G.1

If both CREACS divisions are inoperable in MODE 1, 2, 3, or 4 for reasons other than an inoperable CRE boundary (i.e., Condition C) or both CRSRS divisions are inoperable in MODE 1, 2, 3, or 4, the CRHS may not be capable of performing the intended functions and the unit is in a condition outside the accident analyses. Therefore, LCO 3.0.3 must be entered immediately.

SR 3.7.11.1

Standby systems should be checked periodically to ensure that they function properly. Since the environment and normal operating conditions on this system are not severe, testing each ACU once every month provides an adequate check on this system.

Monthly heater operations dry out any moisture accumulated in the charcoal from humidity in the ambient air. Systems with heaters must be operated for $\geq 15$ minutes with the heaters energized. The 31 day Frequency is based on the known reliability of the equipment and the two train redundancy available.
SR 3.7.11.2

This SR verifies that the required CRHS testing is performed in accordance with the ventilation filter testing program (VFTP). The testing is performed in accordance with Nuclear Regulatory Commission (NRC) Regulatory Guide (RG) 1.52 (Ref. 5). The VFTP includes testing HEPA filter performance, carbon adsorber efficiency, minimum system flow rate, and the physical properties of the activated carbon (general use and following specific operations). Specific test frequencies and additional information are discussed in detail in the VFTP.

SR 3.7.11.3

This SR verifies active components in each CRHS division start and operate on an actual or simulated actuation signal. The automatic functions of the individual components necessary for OPERABILITY of the emergency mode of CRHS operation such as ACUs, AHUs, and dampers, which are described in FSAR, Subsection 9.4.1 (Ref. 1), are verified by this SR. This SR also verifies the standby CRHS train (which includes the standby AHU and the standby ACU fan) in the same division automatically starts and realigns to emergency mode [or toxic gas isolation mode] when the running CRHS train in a division fails to operate in emergency mode [or toxic gas isolation mode], and the standby CRHS train (which includes the standby AHU and the standby ACU fan) in the other division automatically starts and realigns to emergency mode [or toxic gas isolation mode] when a CRHS division fails to operate in emergency mode [or toxic gas isolation mode]. The 18 month Frequency is based on the need to perform this Surveillance under the conditions that apply during unit outage and the potential for an unplanned transient if the Surveillance were performed with the reactor at power. The 18 month Frequency is based on operating experience and design reliability of the equipment.

SR 3.7.11.4

This SR verifies the OPERABILITY of the CRE boundary by testing for unfiltered air inleakage past the CRE boundary and into the CRE. The details of the testing are specified in the Control Room Envelope Habitability Program.

The CRE is considered habitable when the radiological dose to CRE occupants calculated in the licensing basis analyses of DBA consequences is no more than 50 mSv (5 rem) whole body or its equivalent to any part of the body and the CRE occupants are protected from [toxic gas and] smoke. This SR verifies that the unfiltered air
inleakage into the CRE is no greater than the flow rate assumed in the licensing basis analyses of DBA consequences. When unfiltered air inleakage is greater than the assumed flow rate, Condition C must be entered. Required Action C.3 allows time to restore the CRE boundary to OPERABLE status provided mitigating actions can ensure that the CRE remains within the licensing basis habitability limits for the occupants following an accident. Compensatory measures are discussed in NRC RG 1.196, Section C.2.7.3 (Ref. 6), which endorses, with exceptions, NEI 99-03, Section 8.4 and Appendix F (Ref. 7). These compensatory measures may also be used as mitigating actions as required by Required Action C.2. Temporary analytical methods may also be used as compensatory measures to restore OPERABILITY (Ref. 8). Options for restoring the CRE boundary to OPERABLE status include changing the licensing basis DBA consequence analysis, repairing the CRE boundary, or a combination of these actions. Depending upon the nature of the problem and the corrective action, a full scope inleakage test may not be necessary to establish that the CRE boundary has been restored to OPERABLE status.

SR 3.7.11.5

This SR verifies that the heat removal capability of the system is sufficient to meet design requirements. This SR consists of a combination of testing and calculations. An 18 month Frequency is appropriate since significant degradation of the CRHS is slow and is not expected over this time period.

REFERENCES

1. FSAR, Subsection 9.4.1.
2. FSAR, Section 6.4.
3. FSAR, Chapter 15.
4. FSAR, Section 9.5.
REFERENCES (continued)


B 3.7 PLANT SYSTEMS

B 3.7.12 Auxiliary Building Controlled Area Emergency Exhaust System (ABCAEES)

BASES

BACKGROUND

The ABCAEES filters air from the mechanical penetration rooms and the safety-related mechanical equipment rooms during the recirculation phase of a loss-of-coolant accident (LOCA).

The ABCAEES consists of two independent and redundant divisions. Each division includes two emergency exhaust air cleaning units (ACUs), each consisting of a moisture separator, an electric heating coil, a prefilter, a high efficiency particulate air (HEPA) filter, an activated carbon adsorber section for removal of gaseous activity (principally iodines), a postfilter, and a fan. Ductwork, dampers, and instrumentation also form part of the system. The moisture separator removes any entrained water droplets in the air stream to reduce the relative humidity of the air and the prefilter removes any large particles in the air to prevent excessive loading of the HEPA filters and carbon adsorbers. A postfilter follows the adsorber section to collect carbon fines and provide backup in case the HEPA filter bank fails. The system initiates filtered ventilation of the mechanical penetration rooms and the safety-related mechanical equipment rooms following upon receipt of an engineered safety features actuation signal – safety injection actuation signal (ESFAS-SIAS). In addition, the actuation signal closes isolation dampers downstream of the normal supply air handling units (AHUs) and upstream of the normal exhaust ACUs to prevent inleakage into the auxiliary building controlled area from outside of the auxiliary building. The normal exhaust ACUs and the normal supply AHUs stop sequentially upon the isolation damper close signal.

The ABCAEES is discussed in Subsections 6.5.1, 9.4.5, and 15.6.5 (Refs. 1, 2, and 3, respectively), as it can be used for normal, as well as post-accident, atmospheric cleanup functions.

APPLICABLE SAFETY ANALYSES

The design basis of the ABCAEES is established by the large break LOCA. The system evaluation assumes a passive failure of the Emergency Core Cooling System (ECCS) outside containment, such as safety injection pump seal failure during recirculation mode.

In such a case, the system limits the radioactive release to within 10 CFR 50.34 limits (Ref. 4), or the NRC staff-approved licensing basis (e.g., a specified fraction of 10 CFR 50.34 limits). The analysis of the effects and consequences of a large break LOCA is presented in Reference 3.
The ABCAEES also actuates following a small break LOCA, requiring the unit to go into the recirculation mode of long term cooling and to clean up release of smaller leaks, such as from valve stem packing. The two types of system failures that are considered in the accident analysis are complete loss of function and excessive LEAKAGE. Either type of failure can result in a lower efficiency of removal for any gaseous and particulate activity released to the mechanical penetration rooms and the safety-related mechanical equipment rooms following a LOCA.

The ABCAEES satisfies Criterion 3 of 10 CFR 50.36(c)(2)(ii).

Two independent and redundant divisions of the ABCAEES are required to ensure that at least one is available, assuming a single failure coincident with a loss of offsite power. Total system failure could result in the atmospheric releases from the mechanical penetration rooms and the safety-related mechanical equipment rooms exceeding the required limits in the event of a design basis accident (DBA).

The ABCAEES is considered OPERABLE when the individual components necessary to maintain the safety-related mechanical equipment rooms filtration are OPERABLE in both divisions. A division is considered OPERABLE when its associated:

a. Fan is OPERABLE.

b. HEPA filter and carbon adsorber are not excessively restricting flow and are capable of performing its filtration functions.

c. Electric heating coil, moisture separator, ductwork, and dampers are OPERABLE.

The LCO is modified by a Note allowing the mechanical penetration room and safety-related mechanical equipment room boundary to be opened intermittently under administrative controls. For entry and exit through doors, the administrative control of the opening is performed by the person(s) entering or exiting the area. For other openings, these controls consist of stationing a dedicated individual at the opening who is in continuous communication with the main control room (MCR). This individual will have a method to rapidly close the opening when a need for the mechanical penetration rooms or the safety-related mechanical equipment rooms isolation is indicated.
APPLICABILITY

In MODES 1, 2, 3, and 4, the ABCAEES is required to be OPERABLE consistent with the OPERABILITY requirements of the ECCS.

In MODES 5 and 6, the ABCAEES is not required to be OPERABLE, since the ECCS is not required to be OPERABLE.

ACTIONS

A.1

With one ABCAEES division inoperable, the inoperable ABCAEES division must be restored to OPERABLE status within 7 days. In this condition, the remaining OPERABLE division is adequate to perform the ABCAEES function.

The 7 day Completion Time is appropriate because the risk contribution of the system is less than that for the ECCS (72 hour Completion Time) and this system is not a direct support system for the ECCS. The 7 day Completion Time is reasonable, based on the low probability of a DBA occurring during this time period and the consideration that the remaining division can provide the required capability.

B.1

[-------------------REVIEWER’S NOTE-------------------]
Adoption of Condition B is dependent on a commitment from the COL applicant to have guidance available describing compensatory measures to be taken in the event of an intentional and unintentional entry into Condition B.

[-------------------REVIEWER’S NOTE-------------------]
The need for toxic gas isolation mode will be determined by the COL applicant.

If the mechanical penetration room or safety-related mechanical equipment room boundary is inoperable, the ABCAEES divisions cannot perform their intended functions. Actions must be taken to restore an OPERABLE mechanical penetration room and safety-related mechanical equipment room boundary within 24 hours. During the period that the mechanical penetration room or safety-related mechanical equipment room boundary is inoperable, appropriate compensatory measures [consistent with the intent, as applicable, of GDC 19, 60, 64 and 10 CFR 50.34] should be utilized to protect plant personnel from potential hazards such as radioactive contamination, [toxic gases], smoke, temperature, and physical security. Preplanned measures should be available to address these concerns for intentional and unintentional
entry into the condition. The 24 hour Completion Time is reasonable based on the low probability of a DBA occurring during this time period, and the use of compensatory measures. The 24 hour Completion Time is a typically reasonable time to diagnose, plan and possibly repair, and test most problems with the mechanical penetration room or safety-related mechanical equipment room boundary.

C.1 and C.2

If the inoperable ABCAEES division cannot be restored to OPERABLE status within the associated Completion Time, the unit must be in a MODE in which overall plant risk is minimized. To achieve this status, the unit must be placed in at least MODE 3 within 6 hours, and in MODE 5 within 36 hours.

The allowed Completion Times are reasonable, based on operating experience, to reach the required unit conditions from full power conditions in an orderly manner and without challenging unit systems.

SURVEILLANCE REQUIREMENTS

SR  3.7.12.1

Standby systems should be checked periodically to ensure they start and function properly. As the environment and normal operating conditions on this system are not severe, testing each division once every month provides an adequate check on this system. Heater operations dry out any moisture that may have accumulated in the charcoal from humidity in the ambient air. Systems with heaters must be operated for $\geq 15$ minutes with the heaters energized. The 31 day Frequency is based on the known reliability of equipment and the two division redundancy available.

SR  3.7.12.2

This SR verifies that the required ABCAEES testing is performed in accordance with the Ventilation Filter Testing Program (VFTP). The ABCAEES filter tests are in accordance with Nuclear Regulatory Commission (NRC) Regulatory Guide (RG) 1.52 (Ref. 5). The VFTP includes testing HEPA filter performance, carbon adsorber efficiency, the minimum system flow rate, and the physical properties of the activated carbon (general use and following specific operations). Specific test frequencies and additional information are discussed in detail in the VFTP.
SURVEILLANCE REQUIREMENTS (continued)

SR 3.7.12.3

This SR verifies that each ABCAES division starts and operates on an actual or simulated actuation signal. The 18 month Frequency is based on the need to perform this Surveillance under the conditions that apply during unit outage and the potential for an unplanned transient if the Surveillance were performed with the reactor at power. The 18 month Frequency is based on operating experience and design reliability of the equipment.

SR 3.7.12.4

The ABCAES draws down and maintains the mechanical penetration rooms and the safety-related mechanical equipment rooms under a negative pressure with respect to adjacent areas. This SR verifies that the mechanical penetration rooms and the safety-related mechanical equipment rooms can be drawn down to at a pressure of ≤ -6.35 mm (-0.25 inches) water gauge with respect to the adjacent areas. This SR verifies the integrity of the mechanical penetration rooms and the safety-related mechanical equipment rooms enclosure. The ability of the mechanical penetration rooms and the safety-related mechanical equipment rooms to draw down and maintain a negative pressure with respect to adjacent areas is periodically tested to verify proper function of the ABCAES. During the post-accident mode of operation, each ABCAES division is designed to draw down the mechanical penetration rooms and the safety-related mechanical equipment rooms to at a pressure of ≤ -6.35 mm (-0.25 inches) water gauge with respect to the adjacent areas within 300 seconds after a start signal and maintain a pressure of ≤ -6.35 mm (-0.25 inches) water gauge with respect to the adjacent areas at a flow rate of 5,097 cmh (3,000 cfm) to prevent unfiltered LEAKAGE.

The ABCAES is designed to maintain this negative pressure at a flow rate of ≤ 5,097 cmh (3,000 cfm) from the auxiliary building controlled area. The 18 month Frequency is based on the need to perform this Surveillance under the conditions that apply during unit outage and the potential for an unplanned transient if the Surveillance were performed with the reactor at power. The 18 month Frequency is based on operating experience and design reliability of the equipment.

This test is conducted with the tests for filter penetration. An 18 month Frequency on a STAGGERED TEST BASIS is consistent with other filtration SRs.
REFERENCES

1. FSAR, Subsection 6.5.1.
2. FSAR, Subsection 9.4.5.
3. FSAR, Subsection 15.6.5.
4. 10 CFR 50.34.
The FHAEES filters airborne radioactive particulates from the area of the fuel pool following a fuel handling accident or loss of coolant accident.

The FHAEES consists of two independent, redundant divisions. Each division consists of a moisture separator, an electric heating coil, a prefilter, a high efficiency particulate air (HEPA) filter, an activated carbon adsorber section for removal of gaseous activity (principally iodines), a postfilter and a fan. Ductwork, dampers, and instrumentation also form part of the system. The moisture separator removes any entrained water droplets in the air stream to reduce the relative humidity of the air and the prefilter removes any large particles in the air to prevent excessive loading of the HEPA filters and carbon adsorbers. Postfilters follow the adsorber section to collect carbon fines and provide backup in case of failure of the main HEPA filter bank. The system initiates filtered ventilation of the fuel handling area following receipt of an engineered safety features actuation signal-fuel handling area emergency ventilation actuation signal (ESFAS-FHEVAS) or a high radiation signal.

Upon receipt of the ESFAS-FHEVAS or a high radiation signal normal air supply, and normal discharge from the fuel handling area are isolated, and the stream of ventilation air discharges through the FHAEES division.

The FHAEES is discussed in FSAR Subsections 6.5.1, 9.4.2, and 15.7.4 (Ref. 1, 2 and 3, respectively). It can be used for normal, as well as post-accident, atmospheric cleanup functions.

The FHAEES satisfies Criterion 3 of 10 CFR 50.36(c)(2)(ii).
Two independent and redundant divisions of the FHAEES are required to be OPERABLE to ensure that at least one is available, assuming a single failure of the other division coincident with loss of offsite power. Total system failure could result in the atmospheric release from the fuel handling area exceeding the 10 CFR 50.34 (Ref. 5) limits in the event of a fuel handling accident.

The FHAEES is considered OPERABLE when the individual components necessary to control operator exposure are OPERABLE in both divisions. A division is considered OPERABLE when its associated:

a. Fan is OPERABLE.

b. HEPA filter and carbon adsorber are not excessively restricting flow and is capable of performing the filtration functions.

c. Heater, moisture separator, ductwork, and dampers are OPERABLE.

The LCO is modified by a Note allowing the fuel handling area boundary (e.g., spent fuel pool (SFP) cooling heat exchanger rooms, the SFP, the loading & unloading area) to be opened intermittently under administrative controls. For entry and exit through doors, the administrative control of opening is performed by the person(s) entering and exiting the area. For other openings, these controls consist of stationing a dedicated individual at the opening who is in continuous communication with the main control room (MCR). This individual will have a method to rapidly close the opening when a need for fuel handling area isolation is indicated.

During movement of irradiated fuel in the fuel handling area, the FHAEES is required to be OPERABLE to mitigate the consequences of a fuel handling accident.

LCO 3.0.3 is not applicable while in MODE 5 or 6. However, since irradiated fuel assembly movement can occur in MODE 1, 2, 3, or 4, the ACTIONS have been modified by a Note stating that LCO 3.0.3 is not applicable. If moving irradiated fuel assemblies while in MODE 5 or 6, LCO 3.0.3 would not specify any action. If moving irradiated fuel assemblies while in MODE 1, 2, 3, or 4, the fuel movement is independent of reactor operations. Entering LCO 3.0.3 while in MODE 1, 2, 3, or 4 would require the unit to be shutdown unnecessarily.
A.1

If one FHAEES division is inoperable, action must be taken to restore OPERABLE status within 7 days. During this time period, the remaining OPERABLE division is adequate to perform the FHAEES function. The 7 day Completion Time is reasonable, based on the risk from an event occurring requiring the inoperable FHAEES division and ability of the remaining FHAEES division to provide the required protection.

B.1 and B.2

When Required Action A.1 cannot be completed within the required Completion Time during movement of irradiated fuel assemblies in the fuel handling area, the OPERABLE FHAEES division must be started immediately or fuel movement suspended. This action ensures that the remaining division is OPERABLE and that no undetected failures preventing system operation will occur and that any active failures will be readily detected.

If the system is not placed in operation, this action requires suspension of fuel movement which precludes a fuel handling accident. This does not preclude the movement of fuel assemblies to a safe position.

C.1

When two divisions of the FHAEES are inoperable during movement of irradiated fuel assemblies in the fuel building area, action should be taken to place the unit in a condition in which the LCO does not apply. This LCO involves immediately suspending movement of irradiated fuel assemblies in the fuel handling area. This does not preclude the movement of fuel to a safe position.

SURVEILLANCE REQUIREMENTS

SR 3.7.13.1

The standby FHAEES division should be checked periodically to ensure it functions properly. As the environment and normal operating conditions on this system are not severe, testing each division once every month provides an adequate check on this system. Heater operation dries out any moisture accumulated in the carbon from humidity in the ambient air. System with heater must be operated for ≥ 15 minutes with the heater energized. The 31 day Frequency is based on the known reliability of the equipment and the two division redundancy available.
SURVEILLANCE REQUIREMENTS (continued)

SR  3.7.13.2

This SR verifies that the required FHAEES testing is performed in accordance with the ventilation filter testing program (VFTP). The FHAEES filter tests are in accordance with the NRC RG 1.52 (Ref. 6). The VFTP includes testing HEPA filter performance, carbon adsorber efficiency, minimum system flow rate, and the physical properties of the activated carbon (general use and following specific operations).

Specific test frequencies and additional information are discussed in detail in the VFTP.

SR  3.7.13.3

This SR verifies that each ventilation filter testing division starts and operates on an actual or simulated actuation signal. The 18 month Frequency is based on the need to perform this Surveillance under the conditions that apply during unit outage and the potential for an unplanned transient if the Surveillance were performed with the reactor at power. The 18 month Frequency is based on operating experience and design reliability of the equipment.

SR  3.7.13.4

This SR verifies the integrity of the fuel handling area. The ability of the fuel handling area to maintain negative pressure with respect to potentially uncontaminated adjacent areas is periodically tested to verify proper function of the FHAEES. During the post-accident mode of operation, the FHAEES is designed to maintain a slightly negative pressure in the fuel handling area, with respect to adjacent areas, to prevent unfiltered leakage. The FHAEES is designed to maintain this negative pressure at a flow rate of 8,495 cmh (5,000 cfm) from the fuel handling area. The 18 month Frequency is based on the need to perform this Surveillance under the conditions that apply during unit outage and the potential for an unplanned transient if the Surveillance were performed with the reactor at power. The 18 month Frequency is based on operating experience and design reliability of the equipment.

This test is conducted with the tests for filter penetration. An 18 month Frequency on a STAGGERED TEST BASIS is consistent with other filtration SRs.
REFERENCES

1. FSAR, Subsection 6.5.1.

2. FSAR, Subsection 9.4.2.

3. FSAR, Subsection 15.7.4.


5. 10 CFR 50.34.

B 3.7 PLANT SYSTEMS

B 3.7.14 Spent Fuel Pool Water Level (SFPWL)

BASES

BACKGROUND

The minimum water level in the spent fuel pool meets the assumptions of iodine decontamination factors following a fuel handling accident. The specified water level shields and minimizes the general area dose when the storage racks are at their maximum capacity. The water also provides shielding during the movement of spent fuel.

A general description of the spent fuel pool design is found in FSAR Subsection 9.1.2 (Ref. 1). A general description of the Spent Fuel Pool Cooling and Cleanup System design is found in FSAR Subsection 9.1.3 (Ref. 2). The assumptions of the fuel handling accident are found in FSAR Subsection 15.7.4 (Ref. 3).

APPLICABLE SAFETY ANALYSES

The minimum water level in the spent fuel pool meets the assumptions of the fuel handling accident described in Nuclear Regulatory Commission (NRC) Regulatory Guide (RG) 1.183 (Ref. 4). The resultant two hour dose to a person at the exclusion area boundary (EAB) is well within the 10 CFR 50.34 (Ref. 5) limits.

According to Reference 4, there is 7 m (23 ft) of water between the top of the damaged fuel bundle and the fuel pool surface for a fuel handling accident. With 7 m (23 ft) water level, the assumptions of Reference 4 can be used directly. In practice, this LCO preserves this assumption for the bulk of the fuel in the storage racks. In the case of a single bundle, dropped and lying horizontally on top of the spent fuel racks, however, there could be < 7 m (23 ft) above the top of the fuel bundle and the surface by the width of the bundle. To offset this small non-conservatism, the analysis assumes that all fuel rods fail.

The spent fuel pool water level satisfies Criteria 2 and 3 of 10 CFR 50.36(c)(2)(ii).

LCO

The specified water level preserves the assumptions of the fuel handling accident analysis (Ref. 3). As such, it is the minimum required for irradiated fuel storage within the spent fuel pool.

APPLICABILITY

This LCO applies during movement of irradiated fuel assemblies in the spent fuel pool since the potential for a release of fission products exists.
BASES

ACTIONS

A.1

Required Action A.1 is modified by a Note indicating that LCO 3.0.3 does not apply.

When the initial conditions for an accident cannot be met, steps should be taken to preclude the accident from occurring. When the spent fuel pool water level is lower than the required level, the movement of irradiated fuel assemblies in the spent fuel pool is immediately suspended. This effectively precludes a spent fuel handling accident from occurring. This does not preclude moving a fuel assembly to a safe position.

If moving irradiated fuel assemblies while in MODE 5 or 6, LCO 3.0.3 would not specify any action. If moving irradiated fuel assemblies while in MODES 1, 2, 3, and 4, the fuel movement is independent of reactor operations. Therefore, in either case, inability to suspend movement of irradiated fuel assemblies is not sufficient reason to require a reactor shutdown.

SURVEILLANCE REQUIREMENTS

SR 3.7.14.1

This SR verifies sufficient spent fuel pool water is available in the event of a fuel handling accident. The water level in the spent fuel pool must be checked periodically. The 7 day Frequency is appropriate because the volume in the pool is normally stable. Water level changes are controlled by plant procedures and are acceptable, based on operating experience.

During refueling operations, the level in the spent fuel pool is in equilibrium with the refueling canal, and the level in the refueling canal is checked daily in accordance with LCO 3.9.6, “Refueling Water Level.”

REFERENCES

1. FSAR, Subsection 9.1.2.
2. FSAR, Subsection 9.1.3.
3. FSAR, Subsection 15.7.4.
5. 10 CFR 50.34.
B 3.7 PLANT SYSTEMS

B 3.7.15 Spent Fuel Pool Boron Concentration

BASES

BACKGROUND
As described in LCO 3.7.16, "Spent Fuel Assembly Storage," fuel assemblies are stored in the spent fuel racks in accordance with criteria based on initial enrichment and discharge burnup. Although the water in the spent fuel pool is normally borated to ≥ 2,150 ppm and the SFP Boron-10 isotopic concentration is ≥ 19.9% (atomic percent), the criteria which limits the storage of a fuel assembly to specific rack locations is conservatively developed without taking credit for boron. Safe operation with unborated water and no movement of assemblies may be achieved by controlling the location of each assembly in accordance with LCO 3.7.16, "Spent Fuel Assembly Storage." Prior to movement of an assembly, it is necessary to perform SR 3.7.16.1.

APPLICABLE SAFETY ANALYSES
A fuel assembly could be inadvertently loaded into a spent fuel rack location not allowed by LCO 3.7.16 (e.g., an unirradiated fuel assembly or an insufficiently depleted fuel assembly). This accident is analyzed assuming the case of misloading the fuel pool racks with an unirradiated assembly of maximum enrichment. Another type of postulated accident is associated with a fuel assembly which is dropped onto the fully loaded fuel pool storage rack. Either incident could have a positive reactivity effect, decreasing the margin to criticality. However, the negative reactivity effect of the soluble boron compensates for the increased reactivity caused by either one of the two postulated accident scenarios.

The SFP effective multiplication factor ($k_{eff}$) storage limit of 0.95 is maintained during these events by a minimum boron concentration of ≥ 1,231 ppm. Compliance with the LCO minimum boron concentration limit of 2,150 ppm ensures that the credited concentration is always available.

The concentration of dissolved boron in the fuel pool satisfies Criterion 2 of 10 CFR 50.36(c)(2)(ii).

LCO
The specified concentration of dissolved boron in the fuel pool preserves the assumptions used in the analyses of the potential accident scenarios described above. This concentration of dissolved boron is the minimum required concentration for fuel assembly storage and movement within the fuel pool.
Bases

Applicability

This LCO applies whenever fuel assemblies are stored in the spent fuel pool until a complete spent fuel pool verification has been performed following the last movement of fuel assemblies in the spent fuel pool. This LCO does not apply following the verification since the verification would confirm that there are no misloaded fuel assemblies. With no further fuel assembly movements in progress, there is no potential for a misloaded fuel assembly or a dropped fuel assembly.

Actions

The Required Actions are modified by a Note indicating that LCO 3.0.3 does not apply.

A.1, A.2.1, and A.2.2

When the concentration of boron or Boron-10 isotopic concentration in the spent fuel pool is less than required, immediate action must be taken to preclude an accident from happening or to mitigate the consequences of an accident in progress. This is most efficiently achieved by immediately suspending the movement of fuel assemblies. This does not preclude the movement of fuel assemblies to a safe position. In addition, action must be immediately initiated to restore boron concentration and Boron-10 isotopic concentration to within limit. Alternately, an immediate verification, by administrative means, of the spent fuel pool fuel locations, to ensure proper locations of the fuel since the last movement of fuel assemblies in the spent fuel pool, can be performed. However, prior to resuming movement of fuel assemblies, the concentration of boron and Boron-10 isotopic concentration must be restored.

If moving irradiated fuel assemblies while in MODE 5 or 6, LCO 3.0.3 would not specify any action. If moving irradiated fuel assemblies while in MODE 1, 2, 3, or 4, the fuel movement is independent of reactor operation. Therefore, inability to suspend movement of fuel assemblies is not sufficient reason to require a reactor shutdown.

Surveillance Requirements

SR 3.7.15.1

This SR verifies that the concentration of boron in the spent fuel pool is within the required limit. As long as this SR is met, the analyzed incidents are fully addressed. The 7 day Frequency is appropriate because no major replenishment of pool water is expected to take place over a short period of time.
SURVEILLANCE REQUIREMENTS (continued)

SR 3.7.15.2

Periodic verification that the isotopic concentration of Boron-10 in the SFP is $\geq 19.9\%$ (atomic percent) ensures that the Boron-10 isotopic concentration assumed in the safety analysis is available. The 24 month Frequency is appropriate because the boron in the SFP is not exposed to a significant neutron flux.

REFERENCES

None.
B 3.7 PLANT SYSTEMS

B 3.7.16 Spent Fuel Assembly Storage

BASES

BACKGROUND

The spent fuel storage facility is designed to store either new (non-irradiated) nuclear fuel assemblies, or burned (irradiated) fuel assemblies in a vertical configuration underwater. The spent fuel pool is sized to store 1,792 irradiated fuel assemblies, which includes storage for five failed fuel assemblies.

The spent fuel storage cells are installed in parallel rows. The center to center nominal distances between fuel assemblies for Region I and Region II are specified in Specification 4.3.1.1. This space and the neutron absorbing material attached to the storage cell are sufficient to maintain a $k_{\text{eff}} < 1.0$ for spent fuel of original enrichment of up to 5 weight percent.

The spent fuel storage racks are required to maintain a $k_{\text{eff}}$ of $< 1.0$ under normal conditions at a 95/95 level assuming the pool is flooded with unborated water. Compliance with this regulatory requirement has been ensured by developing storage requirements as a function of burnup and initial enrichment (Figure 3.7.16-1). Once the burnup requirements have been determined, the amount of soluble boron necessary to maintain a $k_{\text{eff}}$ of $\leq 0.95$ under normal and postulated accident conditions is calculated. The details of the analyses are provided in Reference 1. It is shown that a soluble boron concentration of 1,231 ppm enriched boron is required to maintain a $k_{\text{eff}}$ of $\leq 0.95$ for allowable storage configurations, which is well within the 2,150 ppm enriched boron requirement of LCO 3.7.15.

APPLICABLE SAFETY ANALYSES

The spent fuel storage facility is designed for non-criticality by maintaining sufficient space and using the neutron absorbing material. The spent fuel assembly storage satisfies Criterion 2 of 10 CFR 50.36(c)(2)(ii).

LCO

The restrictions on the placement of fuel assemblies within the spent fuel pool, according to Figure 3.7.16-1 in the accompanying LCO, ensures that the $k_{\text{eff}}$ of the spent fuel pool will always remain $< 1.0$ assuming the pool to be flooded with unborated water.

The restrictions are consistent with the criticality safety analysis performed for the spent fuel pool according to Figure 3.7.16-1 in the accompanying LCO. Fuel assemblies not meeting the criteria of Figure 3.7.16-1 shall be stored in accordance with Specification 4.3.1.1.
### BASES

<table>
<thead>
<tr>
<th>APPLICABILITY</th>
<th>This LCO applies whenever any fuel assembly is stored in Region II of the spent fuel pool.</th>
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</thead>
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<table>
<thead>
<tr>
<th>ACTIONS</th>
<th>A.1</th>
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</thead>
</table>

Required Action A.1 is modified by a Note indicating that LCO 3.0.3 is not applicable.

When the configuration of fuel assemblies stored in Region II of the spent fuel pool is not in accordance with Figure 3.7.16-1, immediate action must be taken to make the necessary fuel assembly movement to bring the configuration into compliance with Figure 3.7.16-1.

If irradiated fuel assemblies are moved while in MODE 5 or 6, LCO 3.0.3 would not specify any action. If irradiated fuel assemblies are moved while in MODE 1, 2, 3, or 4, the fuel movement is independent of reactor operation. Therefore, in either case, inability to move fuel assemblies is not sufficient reason to require a reactor shutdown.

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<tr>
<th>SURVEILLANCE REQUIREMENTS</th>
<th>SR 3.7.16.1</th>
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This SR verifies by administrative means that the initial enrichment and burnup of the fuel assembly is in accordance with Figure 3.7.16-1 in the accompanying LCO. For fuel assemblies in the unacceptable range of Figure 3.7.16-1, performance of this SR will ensure compliance with Specification 4.3.1.1.

|------------|-----------------------------------------------------------------------------------------------------------------|
Activity in the secondary coolant results from a steam generator tube leakage of the reactor coolant. Under steady-state conditions, the iodines with relatively short half-lives are main radionuclides in the secondary coolant, and thus is an indicative of current conditions. During a transient, I-131 spike is observed as well as an increased release of some noble gases. Other fission product isotopes, as well as activated corrosion products in lesser amounts, can also be found in the secondary coolant.

A limit on secondary coolant specific activity during power operation minimizes releases to the environment during normal operation, anticipated operational occurrences, and accidents.

The steam line failure is assumed to result in the release of the noble gas and iodine activity contained in the steam generator inventory, the feedwater, and reactor coolant LEAKAGE. Most of the iodine isotopes have short half-lives, (i.e., < 20 hours). I-131 with a half-life of 8.04 days concentrates faster than it decays, but does not reach equilibrium because of blowdown and other losses.

If the plant is operating within the LCO limit, the 2 hour exclusion area boundary (EAB) exposure due to an accident is less than a small fraction of the limits in 10 CFR 50.34 (Ref. 1).

The accident analysis of the main steam line break (MSLB) described in FSAR, Chapter 15 (Ref. 2) assumes the initial secondary coolant specific activity to have a radioactive isotope concentration of 3.7E3 Bq/g (0.1 µCi/g) DOSE EQUIVALENT I-131. This assumption is used in the analysis for determining the radiological consequence of a postulated accident. The accident analysis shows that the radiological consequence of a MSLB does not exceed a small fraction of the EAB exposure limits of 10 CFR 50.34.

With the loss of offsite power, the remaining unaffected steam generator is available for core decay heat dissipation by venting steam to the atmosphere through the main steam safety valves (MSSVs) and main steam atmospheric dump valves (MSADVs). The Auxiliary Feedwater System supplies the necessary makeup to the steam generator. Venting continues until the reactor coolant temperature and pressure has decreased sufficiently for the Shutdown Cooling System to be engaged for the cooldown.
In the evaluation of the radiological consequences of a MSLB, the activity released from the steam generator connected to the failed steam line is assumed to be released directly to the environment. The unaffected steam generator is assumed to discharge steam and any entrained activity through the MSSVs and MSADVs during the event.

The secondary specific activity satisfies Criterion 2 of 10 CFR 50.36(c)(2)(ii).

As indicated in the applicable safety analyses, the specific activity limit in the secondary coolant system of ≤ 3.7E3 Bq/g (0.1 µCi/g) DOSE EQUIVALENT I-131 is required to limit the radiological consequences of a design basis accident (DBA) to a small fraction of 10 CFR 50.34 limits.

Monitoring the specific activity of the secondary coolant ensures that when secondary specific activity limits are exceeded, appropriate actions are taken in a timely manner to place the unit in an operational MODE that would minimize the radiological consequences of a DBA.

In MODES 1, 2, 3 and 4, the limits on secondary specific activity are applied considering the potential secondary steam releases to atmosphere.

In MODES 5 and 6, the steam generators are not being used for heat removal. Both the RCS and steam generators are depressurized, and primary to secondary leakage is minimal. Therefore, monitoring of secondary activity is not required.

DOSE EQUIVALENT I-131 exceeding the LCO limit is an indication of a problem in the RCS, as well as the possibility of the post-accident doses exceeding the regulatory limit. The plant must be placed in a MODE in which the requirement does not apply if secondary specific activity cannot be restored within limit in the associated Completion Time. This is done by placing the plant in MODE 3 within 6 hours, and MODE 5 within 36 hours. Based on operating experience, the allowed Completion Times are reasonable to reach the required MODES from the full power operation in an orderly manner without challenging plant systems.
This SR ensures that the secondary activity is within the limit assumed in the accident analyses. A gamma isotopic analysis of the secondary coolant, which determines DOSE EQUIVALENT I-131, confirms the validity of the accident analysis assumptions as to the source terms in post-accident releases. It also serves to identify and analyze any unusual isotopic concentrations which may indicate changes in reactor coolant activity or LEAKAGE. The 31 day Frequency is sufficient to monitor the level of DOSE EQUIVALENT I-131 and its increasing trends, and to take appropriate actions to maintain the level below the LCO limit.

REFERENCES

1. 10 CFR 50.34.
2. FSAR, Chapter 15.
B 3.8  ELECTRICAL POWER SYSTEMS

B 3.8.1  AC Sources – Operating

BASES

BACKGROUND  The Class-1E Electrical Power Distribution System alternating current (AC) power sources consist of the offsite power sources (preferred power sources, normal and alternate), and the onsite standby power sources—two divisions of emergency diesel generators (EDGs), each division consisting of two EDGs (Train A and Train C EDGs for division I, and Train B and Train D EDGs for division II). The unavailability of either one or two EDGs on one division disables one load group to perform its partial or all of the safety functions. Because of the divisional approach of the four EDGs in the APR1400 design, the condition with three or more AC sources inoperable is divided into two different cases: two offsite circuits and one or more EDGs inoperable, and two offsite circuits and one or more EDGs inoperable. As required by 10 CFR Part 50, Appendix A, GDC 17 (Ref. 1), the design of the AC Electrical Power System provides independence and redundancy to ensure an available source of power to the Engineered Safety Feature (ESF) Systems.

The Onsite Class 1E AC Distribution System is divided into redundant load groups (divisions) so that loss of any one group does not prevent the minimum safety functions from being performed. Each train has connections to two preferred offsite power sources and a single EDG.

Offsite power is supplied to the unit switchyard(s) from the transmission network by at least two transmission lines. From the switchyard(s), two electrically and physically separated circuits provide AC power, through [auxiliary transformers], to the 4.16 kV Class 1E buses (ESF buses). A detailed description of the offsite power network and the circuits to the ESF buses is found in FSAR, Chapter 8 (Ref. 2).

An offsite circuit consists of all breakers, transformers, switches, interrupting devices, cabling, and controls required to transmit power from the offsite transmission network to the onsite ESF buses.

Certain required unit loads are returned to service in a predetermined sequence in order to prevent overloading the transformer supplying offsite power to the Onsite Class 1E Distribution System. Within 1 minute after the initiating signal is received, all automatic and permanently connected loads needed to recover the unit or maintain it in a safe condition are returned to service via the load sequencer.
The onsite standby power source for each ESF bus is a dedicated EDG. EDGs 1A, 1B, 1C, and 1D are dedicated to ESF buses SW01A, SW01B, SW01C, and SW01D, respectively. An EDG starts automatically on a safety injection (SI) signal (i.e., low pressurizer pressure or high containment pressure signals) or on an ESF bus degraded voltage or undervoltage signal. After the EDG has started, it will automatically tie to its respective bus after offsite power is tripped as a consequence of ESF bus undervoltage or degraded voltage, independent of or coincident with an SI signal. The EDGs will also start and operate in the standby mode without tying to the ESF bus on an SI signal alone. Following the trip of offsite power, a sequencer trips nonpermanent loads from the ESF bus. When the EDG is tied to the ESF bus, loads are then sequentially connected to its respective ESF bus by the automatic load sequencer. The sequencing logic controls the permissive and starting signals to motor breakers to prevent overloading the EDG by automatic load application.

In the event of a loss of preferred power, the ESF electrical loads are automatically connected to the EDGs in sufficient time to provide for safe reactor shutdown and to mitigate the consequences of a design basis accident (DBA), such as a loss of coolant accident (LOCA).

Certain required unit loads are returned to service in a predetermined sequence in order to prevent overloading the EDG in the process. Within 1 minute after the initiating signal is received, all loads needed to recover the unit or maintain it in a safe condition are returned to service.

Ratings for Trains A, B, C, and D EDGs satisfy the requirements of Nuclear Regulatory Commission (NRC) Regulatory Guide (RG) 1.9 (Ref. 3). The continuous service rating of EDGs A and B are 9,100 kW and EDGs C and D are 7,500 kW with 10% overload permissible for up to 2 hours in any 24 hour period. The ESF loads that are powered from the ESF buses are listed in Reference 2.

The initial conditions of DBA and transient analyses in FSAR, Chapters 6 (Ref. 4) and 15 (Ref. 5), assume ESF Systems are OPERABLE. The AC electrical power sources are designed to provide sufficient capacity, capability, redundancy, and reliability to ensure the availability of necessary power to ESF Systems so that the fuel, Reactor Coolant System (RCS), and containment design limits are not exceeded.
APPLICABLE SAFETY ANALYSES (continued)

These design limits are discussed in more detail in the Bases for LCOs 3.2, “Power Distribution Limits,” 3.4, “Reactor Coolant System (RCS),” and 3.6, “Containment Systems.”

The OPERABILITY of the AC electrical power sources is consistent with the initial assumptions of the accident analyses and is based upon meeting the design basis of the unit. This results in maintaining at least one division of the onsite or offsite AC sources OPERABLE during accident conditions in the event of:

a. An assumed loss of all offsite power or all onsite AC power and

b. A worst case single failure.

The AC sources satisfy Criterion 3 of 10 CFR 50.36(c)(2)(ii).

LCO

Two qualified circuits between the offsite transmission network and the Onsite Class 1E AC Electrical Power Distribution System and separate and independent EDGs for each division ensure availability of the required power to shut down the reactor and maintain it in a safe shutdown condition after an anticipated operational occurrence (AOO) or a postulated DBA.

Qualified offsite circuits are those that are described in FSAR, Chapter 8, and are part of the licensing basis for the unit.

One required automatic load sequencer per train must be OPERABLE.

Each offsite circuit must be capable of maintaining rated frequency and voltage, and accepting required loads during an accident while connected to the ESF buses.

Offsite circuit #1, being fed from the switchyard Bus A, consists of the main transformer and the unit auxiliary transformers (TR01M and TR01N), and powers the ESF buses (SW01A, SW01B, SW01C, and SW01D) through their normal feeder breakers. Offsite circuit #2, being fed from the switchyard Bus B, consists of the standby auxiliary transformers (TR02M and TR02N), and powers the ESF buses (SW01A, SW01B, SW01C, and SW01D) through their alternate feeder breakers in case Offsite circuit #1 is not available.
Each EDG must be capable of starting, accelerating to speed and voltage, and connecting to its respective ESF bus on detection of bus undervoltage. This will be accomplished within 17 seconds. Each EDG must also be capable of accepting required loads within the assumed loading sequence intervals, and continue to operate until offsite power can be restored to the ESF buses. These capabilities are required to be met from a variety of initial conditions such as EDG in standby with the engine hot and EDG in standby with the engine at ambient conditions. Additional EDG capabilities must be demonstrated to meet required Surveillance (e.g., capability of EDG to revert to standby status on a safety injection signal while operating in parallel test mode).

Proper sequencing of loads, including tripping of nonessential loads, is a required function for EDG OPERABILITY.

The AC sources in one train must be separate and independent (to the extent possible) of the AC sources in the other trains. For the EDGs, separation and independence are complete.

For the offsite AC sources, separation and independence are to the extent practical. The offsite circuit #1 is connected to two ESF buses in each division, with automatic bus transfer (fast transfer and residual voltage transfer) capability to the OPERABLE offsite circuit #2, and this does not violate separation criteria. The offsite circuit #2 that is not connected to the ESF buses during normal operation is required to have OPERABLE automatic bus transfer interlock mechanisms to respective ESF buses in both divisions to support OPERABILITY of that circuit.

The AC sources and sequencers are required to be OPERABLE in MODES 1, 2, 3, and 4 to ensure that:

a. Acceptable fuel design limits and reactor coolant pressure boundary limits are not exceeded as a result of AOOs or abnormal transients.

b. Adequate core cooling is provided and containment OPERABILITY and other vital functions are maintained in the event of a postulated DBA.

The AC power requirements for MODES 5 and 6 are covered in LCO 3.8.2, “AC Sources – Shutdown.”
To ensure a highly reliable power source remains with the one offsite circuit inoperable, it is necessary to verify the OPERABILITY of the remaining required offsite circuit on a more frequent basis. Since the Required Action only specifies “perform,” a failure of SR 3.8.1.1 acceptance criteria does not result in a Required Action not met. However, if a second required circuit fails SR 3.8.1.1, the second offsite circuit is inoperable and Condition C, for two offsite circuits inoperable, is entered.

Required Action A.2, which only applies if the division cannot be powered from an offsite source, is intended to provide assurance that an event coincident with a single failure of the associated EDG will not result in a complete loss of safety function of critical redundant required features. These features are powered from the redundant AC electrical power division.

The Completion Time for Required Action A.2 is intended to allow the operator time to evaluate and repair any discovered inoperabilities. This Completion Time also allows for an exception to the normal “time zero” for beginning the allowed outage time “clock.” In this Required Action, the Completion Time only begins on discovery that both:

a. The division has no offsite power supplying its loads.

b. A required feature on the other division is inoperable.

If at any time during the existence of Condition A (one offsite circuit inoperable) a redundant required feature subsequently becomes inoperable, this Completion Time begins to be tracked.

Discovering no offsite power to one division of the Onsite Class 1E Electrical Power Distribution System coincident with one or more inoperable required support or supported features, or both, that are associated with the other division that has offsite power, results in starting the Completion Times for the Required Action. A 24 hour Completion Time is acceptable because it minimizes risk while allowing time for restoration before subjecting the unit to transients associated with shutdown.
The remaining OPERABLE offsite circuit and EDGs are adequate to supply electrical power to Division I and Division II of the Onsite Class 1E Distribution System. The 24 hour Completion Time takes into account the component OPERABILITY of the redundant counterpart to the inoperable required feature. Additionally, the 24 hour Completion Time takes into account the capacity and capability of the remaining AC sources, a reasonable time for repairs, and the low probability of a DBA occurring during this period.

A.3

According to NRC RG 1.93 (Ref. 6), operation may continue in Condition A for a period that should not exceed 72 hours. With one offsite circuit inoperable, the reliability of the offsite system is degraded, and the potential for a loss of offsite power is increased, with attendant potential for a challenge to the unit safety systems. In this Condition, however, the remaining OPERABLE offsite circuit and EDGs are adequate to supply electrical power to the Onsite Class 1E Distribution System.

The 72 hour Completion Time takes into account the capacity and capability of the remaining AC sources, a reasonable time for repairs, and the low probability of a DBA occurring during this period.

B.1

To ensure a highly reliable offsite power source remains with an inoperable EDG, it is necessary to verify the availability of the offsite circuits on a more frequent basis. Since the Required Action only specifies “perform,” a failure of SR 3.8.1.1 acceptance criteria does not result in a Required Action being not met. However, if a circuit fails to pass SR 3.8.1.1, it is inoperable. Upon offsite circuit inoperability, additional Conditions and Required Actions must then be entered.

B.2

Required Action B.2 is intended to provide assurance that a loss of offsite power, during the period that an EDG is inoperable, does not result in a complete loss of safety function of critical systems. These features are designed with redundant safety-related divisions. Redundant required feature failures consist of inoperable features with a division, redundant to the division that has an inoperable EDG.
The Completion Time for Required Action B.2 is intended to allow the operator time to evaluate and repair any discovered inoperabilities. This Completion Time also allows for an exception to the normal “time zero” for beginning the allowed outage time “clock.” In this Required Action, the Completion Time only begins on discovery that both:

- An inoperable EDG exists.
- A required feature on the other division is inoperable.

If at any time during the existence of this Condition (one EDG inoperable) a required feature subsequently becomes inoperable, this Completion Time begins to be tracked.

Discovering one required EDG inoperable coincident with one or more inoperable required support or supported features, or both, that are associated with the OPERABLE EDG, results in starting the Completion Time for the Required Action. A 4 hour Completion Time from the discovery of these events existing concurrently is acceptable because it minimizes risk, while allowing time for restoration before subjecting the unit to transients associated with shutdown.

In this Condition, the remaining OPERABLE EDG and offsite circuits are adequate to supply electrical power to the Onsite Class 1E Distribution System. Thus, on a component basis, single failure protection for the required feature’s function may have been lost; however, function has not been lost. The 4 hour Completion Time takes into account the OPERABILITY of the redundant counterpart to the inoperable required feature. Additionally, the 4 hour Completion Time takes into account the capacity and capability of the remaining AC sources, a reasonable time for repairs, and the low probability of a DBA occurring during this period.

B.3.1 and B.3.2

Required Action B.3.1 provides an allowance to avoid unnecessary testing of OPERABLE EDGs. If it can be determined that the cause of the inoperable EDG does not exist on the OPERABLE EDG, SR 3.8.1.2 does not have to be performed. If the cause of inoperability exists on other EDG(s), the other EDG(s) would be declared inoperable upon discovery and Condition E of LCO 3.8.1 would be entered. Once the failure is repaired, the common cause failure no longer exists and Required Action B.3.1 is satisfied. If the cause of the initial inoperable EDG cannot be confirmed not to exist on the remaining EDG(s), performance of SR 3.8.1.2 suffices to provide assurance of continued OPERABILITY of that EDG.
In the event the inoperable EDG is restored to OPERABLE status prior to completing either B.3.1 or B.3.2, the plant corrective action program will continue to evaluate the common cause possibility. This continued evaluation, however, is no longer under the 24 hour constraint imposed while in Condition B.

According to GL 84-15 (Ref. 7), a time of 24 hours is reasonable to confirm that the OPERABLE EDG(s) is not affected by the same problem as the inoperable EDG.

B.4

According to NRC RG 1.93 (Ref. 6), operation may continue in Condition B for a period that should not exceed 72 hours.

In Condition B, the remaining OPERABLE EDG and offsite circuits are adequate to supply electrical power to the Onsite Class 1E Distribution System. The 72 hour Completion Time takes into account the capacity and capability of the remaining AC sources, a reasonable time for repairs, and the low probability of a DBA occurring during this period.

C.1 and C.2

Required Action C.1, which applies when two offsite circuits are inoperable, is intended to provide assurance that an event with a coincident single failure will not result in a complete loss of redundant required safety functions. The Completion Time for this failure of redundant required features is reduced to 12 hours from that allowed for one division without offsite power (Required Action A.2). The rationale for the reduction to 12 hours is that NRC RG 1.93 (Ref. 6) allows a Completion Time of 24 hours for two required offsite circuits inoperable, based upon the assumption that two complete safety divisions are OPERABLE. When a concurrent redundant required feature failure exists, this assumption is not the case, and a shorter Completion Time of 12 hours is appropriate. These features are powered from redundant AC safety divisions.

The Completion Time for Required Action C.1 is intended to allow the operator time to evaluate and repair any discovered inoperabilities. This Completion Time also allows for an exception to the normal “time zero” for beginning the allowed outage time “clock.” In this Required Action, the Completion Time only begins on discovery that both:
AC Sources – Operating

B 3.8.1

BASES

ACTIONS (continued)

a. All required offsite circuits are inoperable; and

b. A required feature is inoperable.

If at any time during the existence of Condition C (two offsite circuits inoperable) and a required feature becomes inoperable, this Completion Time begins to be tracked.

According to NRC RG 1.93 (Ref. 6), operation may continue in Condition C for a period that should not exceed 24 hours. This level of degradation means that the Offsite Electrical Power System does not have the capability to effect a safe shutdown and to mitigate the effects of an accident. However, the onsite AC sources have not been degraded. This level of degradation generally corresponds to a total loss of the immediately accessible offsite power sources.

Because of the normally high availability of the offsite sources, this level of degradation can appear to be more severe than other combinations of two AC sources inoperable that involve one or more EDGs inoperable.

However, two factors tend to decrease the severity of this level of degradation:

a. The configuration of the redundant AC Electrical Power System that remains available is not susceptible to a single bus or switching failure.

b. The time required to detect and restore an unavailable offsite power source is generally much less than that required to detect and restore an unavailable onsite AC source.

With both of the required offsite circuits inoperable, sufficient onsite AC sources are available to maintain the unit in a safe shutdown condition in the event of a DBA or transient. In fact, a simultaneous loss of offsite AC sources, a LOCA, and a worst case single failure were postulated as a part of the design basis in the safety analysis. Thus, the 24 hour Completion Time provides a period of time to effect restoration of one of the offsite circuits commensurate with the importance of maintaining an AC Electrical Power System capable of meeting its design criteria.

According to Reference 6, with the available offsite AC Sources, two less than required by the LCO, operation may continue for 24 hours. If two offsite sources are restored within 24 hours, unrestricted operation may continue. If only one offsite source is restored within 24 hours, power operation continues in accordance with Condition A.
D.1 and D.2

Pursuant to LCO 3.0.6, the distribution system ACTIONS would not be entered even if all AC sources to it were inoperable resulting in de-energization. Therefore, the Required Actions of Condition D are modified by a Note to indicate that when Condition D is entered with no AC source to any division, the Conditions and Required Actions for LCO 3.8.9, “Distribution Systems – Operating,” must be immediately entered. This allows Condition D to provide requirements for the loss of one offsite circuit and one EDG without regard to whether a division is de-energized. LCO 3.8.9 provides the appropriate restrictions for a de-energized division.

According to the NRC RG 1.93 (Ref. 6), operation may continue in Condition D for a period that should not exceed 12 hours.

In Condition D, individual redundancy is lost in both the Offsite Electrical Power System and the Onsite AC Electrical Power System. Since power system redundancy is provided by two diverse sources of power, however, the reliability of the power systems in this Condition can appear higher than that in Condition C (loss of both required offsite circuits). This difference in reliability is offset by the susceptibility of this power system configuration to a single bus or switching failure. The 12 hour Completion Time takes into account the capacity and capability of the remaining AC sources, a reasonable time for repairs, and the low probability of a DBA occurring during the period.

E.1

With division I and division II EDGs inoperable, there are no remaining standby AC sources. Thus, with an assumed loss of offsite electrical power, insufficient standby AC sources are available to power the minimum required ESF functions. Since the Offsite Electrical Power System is the only source of AC power for this level of degradation, the risk associated with continued operation for a very short time could be less than that associated with an immediate controlled shutdown (the immediate shutdown could cause grid instability, which could result in total loss of AC power). Since any inadvertent generator trip could also result in a total loss of offsite AC power, however, the time allowed for continued operation is severely restricted. The intent here is to avoid the risk associated with an immediate controlled shutdown and to minimize the risk associated with this level of degradation.

According to NRC RG 1.93 (Ref. 6), with both divisions inoperable, operation may continue for a period that should not exceed 2 hours.
The sequencer(s) is an essential support system to the EDG associated with a given ESF bus. Furthermore, the sequencer is on the primary success path for most major AC electrically powered safety systems powered from the associated ESF bus. Therefore, loss of an ESF bus sequencer affects every major ESF System in the train. The 12 hour Completion Time provides a period of time to correct the problem commensurate with the importance of maintaining sequencer OPERABILITY. This time period also ensures that the probability of an accident (requiring sequencer OPERABILITY) occurring during periods when the sequencer is inoperable is minimal.

If the inoperable AC electrical power sources cannot be restored to OPERABLE status within the required Completion Time, the unit must be brought to a MODE in which the LCO does not apply. To achieve this status, the unit must be brought to at least MODE 3 within 6 hours, and MODE 5 within 36 hours.

The allowed Completion Times are reasonable, based on operating experience, to reach the required unit conditions from full power conditions in an orderly manner and without challenging unit systems.

Condition H corresponds to a level of degradation in which all redundancy in the AC electrical power supplies has been lost. At this severely degraded level, any further losses in the AC Electrical Power System will cause a loss of function. Therefore, no additional time is justified for continued operation. The unit is required by LCO 3.0.3 to commence a controlled shutdown.

The AC sources are designed to permit inspection and testing of all important areas and features, especially those that have a standby function, in accordance with 10 CFR Part 50, Appendix A, GDC 18 (Ref. 8). Periodic component tests are supplemented by extensive functional tests during refueling outages (under simulated accident conditions). The SRs for demonstrating the OPERABILITY of the EDGs are in accordance with the recommendations of NRC RG 1.9 (Ref. 3) and NRC RG 1.137 (Ref. 9), as addressed in FSAR, Chapter 8.
Where the SRs discussed herein specify voltage and frequency tolerances, the following is applicable. The minimum steady state output voltage of 3,744 V is 90% of the nominal 4,160 V output voltage. This value, specified in ANSI C84.1-1989 (Ref. 10), allows for voltage drop to the terminals of 4,000 V motors whose minimum operating voltage is specified as 90% or 3,600 V. It also allows for voltage drops to motors and other equipment down through the 120 V level where minimum operating voltage is also usually specified as 80% of name plate rating. The specified maximum steady state output voltage of 4,576 V is equal to the maximum operating voltage specified for 4,000 V motors. It ensures that for a lightly loaded distribution system, the voltage at the terminals of 4,000 V motors is no more than the maximum rated operating voltages. The specified minimum and maximum frequencies of the EDG are 58.8 Hz and 61.2 Hz, respectively. These values are equal to ± 2% of the 60 Hz nominal frequency and are derived from the recommendations given in NRC RG 1.9 (Ref. 3).

**SR 3.8.1.1**

This SR assures proper circuit continuity for the offsite AC electrical power supply to the onsite distribution network and availability of offsite AC electrical power. The breaker alignment verifies that each breaker is in its correct position to ensure that distribution buses and loads are connected to their preferred power source and that appropriate independence of offsite circuits is maintained. The 7 day Frequency is adequate since breaker position is not likely to change without the operator being aware of it and because its status is displayed in the main control room (MCR).

**SR 3.8.1.2 and SR 3.8.1.7**

These SRs help to ensure the availability of the standby electrical power supply to mitigate DBAs and transients and to maintain the unit in safe shutdown condition.

To minimize the wear on moving parts that do not get lubricated when the engine is not running, these SRs are modified by a Note (Note 1 for SR 3.8.1.2 and Note 2 for SR 3.8.1.7) to indicate that all EDG starts for these Surveillances may be preceded by an engine prelube period and followed by a warmup period prior to loading by an engine prelube period.
For the purpose of SR 3.8.1.2 and SR 3.8.1.7 testing, the EDGs are started from standby conditions. Standby conditions for an EDG mean the diesel engine coolant and oil are being continuously circulated and temperature is being maintained consistent with manufacturer recommendations.

In order to reduce stress and wear on diesel engines, the EDG manufacturers recommend a modified start in which the starting speed of EDGs is limited, warmup is limited to this lower speed, and the EDGs are gradually accelerated to synchronous speed prior to loading. This is the intent of Note 2, which is only applicable when such modified start procedures are recommended by the manufacturer.

SR 3.8.1.7 requires that the EDG starts from standby conditions and achieves required voltage and frequency within 17 seconds. The 17 second start requirement supports the assumptions of the design basis LOCA analysis in FSAR, Chapter 15 (Ref. 5).

The 17 second start requirement is not applicable to SR 3.8.1.2 (see Note 2) when a modified start procedure as described above is used. If a modified start is not used, the 17 second start requirement of SR 3.8.1.7 applies.

Since SR 3.8.1.7 requires a 17 second start, it is more restrictive than SR 3.8.1.2 and may be performed in lieu of SR 3.8.1.2.

In addition to the SR requirements, the time for the EDG to reach steady state operation, unless the modified EDG start method is employed, is periodically monitored and the trend evaluated to identify degradation of governor and voltage regulator performance.

The 31 day Frequency for SR 3.8.1.2 is consistent with NRC RG 1.9 (Ref. 3). The 184 day Frequency for SR 3.8.1.7 is a reduction in cold testing consistent with GL 84-15 (Ref. 7). These Frequencies provide adequate assurance of EDG OPERABILITY, while minimizing degradation resulting from testing.

**SR 3.8.1.3**

This Surveillance verifies that the EDGs are capable of synchronizing with the Offsite Electrical System and accepting loads greater than or equal to the equivalent of the maximum expected accident loads. A minimum run time of 60 minutes is required to stabilize engine temperatures, while minimizing the time that the EDG is connected to the offsite source.
Although no power factor requirements are established by this SR, the EDG is normally operated at a power factor between 0.8 lagging and 1.0. The 0.8 value is the design rating of the machine, while 1.0 is an operational limitation to ensure circulating currents are minimized. The 31 day Frequency for this Surveillance is consistent with NRC RG 1.9 (Ref. 3).

This SR is modified by four Notes. Note 1 indicates that diesel engine runs for this Surveillance may include gradual loading, as recommended by the manufacturer, so that mechanical stress and wear on the diesel engine are minimized. Note 2 states that momentary transients because of changing bus loads do not invalidate this test. Similarly, momentary power factor transients above the limit will not invalidate the test. Note 3 indicates that this Surveillance should be conducted on only one EDG at a time in order to avoid common cause failures that may result from offsite circuit or grid perturbations. Note 4 stipulates a prerequisite requirement for performance of this SR. A successful EDG start must precede this test to credit satisfactory performance.

**SR 3.8.1.4**

This SR provides verification that the level of fuel oil in the day tank is at or above the level at which fuel oil is automatically added. The level is expressed as an equivalent volume in liters (gallons) and is selected to ensure adequate fuel oil for a minimum of 1 hour of EDG operation at full load plus 10%.

The 31 day Frequency is adequate to assure that a sufficient supply of fuel oil is available, since low level alarms are provided and unit operators would be aware of any large uses of fuel oil during this period.

**SR 3.8.1.5**

Microbiological fouling is a major cause of fuel oil degradation. There are numerous bacteria that can grow in fuel oil and cause fouling, but all must have a water environment in order to survive. Removal of water from the fuel oil day tank eliminates the necessary environment for bacterial survival. This is the most effective means of controlling microbiological fouling. In addition, it eliminates the potential for water entrainment in the fuel oil during EDG operation. Water can come from any of several sources, including condensation, ground water, rain water, contaminated fuel oil, and from breakdown of the fuel oil by bacteria. Frequent checking for and removal of accumulated water minimizes fouling and provides data regarding the watertight integrity of the Fuel Oil System.
SURVEILLANCE REQUIREMENTS (continued)

The 31 day Frequency is established by NRC RG 1.137 (Ref. 9). This SR is for preventive maintenance.

The presence of water does not necessarily represent failure of this SR provided the accumulated water is removed during the performance of this Surveillance.

SR 3.8.1.6

This Surveillance demonstrates that each required fuel oil transfer pump operates and transfers fuel oil from its associated storage tank to its associated day tank. This is required to support continuous operation of standby power sources. This Surveillance provides assurance that the fuel oil transfer pump is OPERABLE, the Fuel Oil Piping System is intact, the fuel delivery piping is not obstructed, and the controls and control systems for Automatic Fuel Transfer Systems are OPERABLE.

The 92-day Frequency corresponds to the testing requirements for pumps as contained in the ASME Code (Ref. 11); however, the design of Fuel Transfer Systems is such that pumps will operate automatically in order to maintain an adequate volume of fuel oil in the day tanks during or following EDG testing. In such a case, the pumps and fuel oil level can be checked by an operator. Since proper operation of Fuel Transfer Systems is an inherent part of EDG OPERABILITY, the Frequency of this SR reflects the standard design.

SR 3.8.1.7

See SR 3.8.1.2.

SR 3.8.1.8

Transfer of each ESF bus power supply from the normal offsite circuit to the alternate offsite circuit demonstrates the OPERABILITY of the alternate circuit distribution network to power the shutdown loads. The 18 month Frequency of the Surveillance is based on engineering judgment, taking into consideration the unit conditions required to perform the Surveillance, and is intended to be consistent with expected fuel cycle lengths. Operating experience has shown that these components usually pass the SR when performed at the 18 month Frequency. Therefore, the Frequency was concluded to be acceptable from a reliability standpoint.
This SR is modified by a Note. The reason for the Note is that during operation with the reactor critical, performance of this SR could cause perturbations to the Electrical Distribution Systems that could challenge continued steady state operation and, as a result, unit safety systems. This restriction from normally performing the Surveillance in MODE 1 or 2 is further amplified to allow the Surveillance to be performed for the purpose of reestablishing OPERABILITY (e.g., post work testing following corrective maintenance, corrective modification, deficient or incomplete surveillance testing, and other unanticipated OPERABILITY concerns) provided an assessment determines plant safety is maintained or enhanced.

This assessment shall, as a minimum, consider the potential outcomes and transients associated with a failed Surveillance, a successful Surveillance, and a perturbation of the offsite or onsite system when they are tied together or operated independently for the Surveillance; as well as the operator procedures available to cope with these outcomes. These shall be measured against the avoided risk of a plant shutdown and startup to determine that plant safety is maintained or enhanced when the Surveillance is performed in MODE 1 or 2. Risk insights or deterministic methods may be used for this assessment. Credit may be taken for unplanned events that satisfy this SR.

SR 3.8.1.9

Each EDG is provided with an engine overspeed trip to prevent damage to the engine. Recovery from the transient caused by the loss of a large load could cause diesel engine overspeed which, if excessive, may result in a trip of the engine. This Surveillance demonstrates the EDG load response characteristics and capability to reject the largest single load without exceeding predetermined voltage and frequency and while maintaining a specified margin to the overspeed trip. For this unit, the single load for each EDG and its horsepower rating is the component cooling water pump with a horsepower (HP) rating of 1250 HP. This Surveillance may be accomplished by:

a. Tripping the EDG output breaker with the EDG carrying greater than or equal to its associated single largest post-accident load while paralleled to offsite power or while solely supplying the bus and

b. Tripping its associated single largest post-accident load with the EDG solely supplying the bus.
As required by IEEE Std. 308 (Ref. 12), the load rejection test is acceptable if the increase in diesel speed does not exceed 75% of the difference between synchronous speed and the overspeed trip setpoint, or 15% above synchronous speed, whichever is lower.

The time, voltage, and frequency tolerances specified in this SR are derived from NRC RG 1.9 (Ref. 3) recommendations for response during load sequence intervals. The 3 seconds specified is = 60% of a typical 5 second load sequence interval associated with sequencing of the largest load. The voltage and frequency specified are consistent with the design range of the equipment powered by the EDG. SR 3.8.1.9a corresponds to the maximum frequency excursion, while SR 3.8.1.9b and SR 3.8.1.9c are steady state voltage and frequency values to which the system must recover following load rejection. The 18 month Frequency is consistent with the recommendation of NRC RG 1.9 (Ref. 3).

This SR is modified by two Notes. The reason for Note 1 is that during operation with the reactor critical, performance of this SR could cause perturbations to the electrical distribution systems that could challenge continued steady state operation and, as a result, unit safety systems. This restriction from normally performing the Surveillance in MODE 1 or 2 is further amplified to allow the Surveillance to be performed for the purpose of reestablishing OPERABILITY (e.g., post work testing following corrective maintenance, corrective modification, deficient or incomplete surveillance testing, and other unanticipated OPERABILITY concerns) provided an assessment determines plant safety is maintained or enhanced. This assessment shall, as a minimum, consider the potential outcomes and transients associated with a failed Surveillance, a successful Surveillance, and a perturbation of the offsite or onsite system when they are tied together or operated independently for the Surveillance; as well as the operator procedures available to cope with these outcomes. These shall be measured against the avoided risk of a plant shutdown and startup to determine that plant safety is maintained or enhanced when the Surveillance is performed in MODE 1 or 2. Risk insights or deterministic methods may be used for this assessment. Credit may be taken for unplanned events that satisfy this SR. Note 2 ensures that the EDG is tested under load conditions that are as close to design basis conditions as possible. When synchronized with offsite power, testing should be performed at a power factor of ≤ 0.9. This power factor is representative of the actual inductive loading an EDG would see under design basis accident conditions. Under certain conditions, however, Note 2 allows the Surveillance to be conducted at a power factor other than ≤ 0.9.
These conditions occur when grid voltage is high, and the additional field excitation needed to get the power factor to $\leq 0.9$ results in voltages on the emergency busses that are too high. Under these conditions, the power factor should be maintained as close as practicable to 0.9 while still maintaining acceptable voltage limits on the emergency busses. In other circumstances, the grid voltage could be such that the EDG excitation levels needed to obtain a power factor of 0.9 may not cause unacceptable voltages on the emergency busses, but the excitation levels are in excess of those recommended for the EDG. In such cases, the power factor shall be maintained as close as practicable to 0.9 without exceeding the EDG excitation limits.

The above MODE restrictions may be deleted if it can be demonstrated to the staff, on a plant specific basis, that performing the SR with the reactor in any of the restricted MODES can satisfy the following criteria, as applicable:

a. Performance of the SR will not render any safety system or component inoperable.

b. Performance of the SR will not cause perturbations to any of the electrical distribution systems that could result in a challenge to steady state operation or to plant safety systems.

c. Performance of the SR or failure of the SR will not cause or result in an AOO with attendant challenge to plant safety systems.

SR 3.8.1.10

This Surveillance demonstrates the EDG capability to reject a full load without overspeed tripping or exceeding the predetermined voltage limits. The EDG full load rejection could occur because of a system fault or inadvertent breaker tripping. This Surveillance ensures proper engine generator load response under the simulated test conditions. This test simulates the loss of the total connected loads that the EDG experiences following a full load rejection and verifies that the EDG will not trip upon loss of the load. These acceptance criteria provide for EDG damage protection. While the EDG is not expected to experience this transient during an event and continue to be available, this response assures that the EDG is not degraded for future application, including reconnection to the bus if the trip initiator can be corrected or isolated.
The 18 month Frequency is consistent with the recommendation of NRC RG 1.9 (Ref. 3) and is intended to be consistent with expected fuel cycle lengths.

This SR is modified by two Notes. The reason for Note 1 is that during operation with the reactor critical, performance of this SR could cause perturbation to the electrical distribution systems that could challenge continued steady state operation and, as a result, unit safety systems. This restriction from normally performing the Surveillance in MODE 1 or 2 is further amplified to allow the Surveillance to be performed for the purpose of reestablishing OPERABILITY (e.g., post work testing following corrective maintenance, corrective modification, deficient or incomplete surveillance testing, and other unanticipated OPERABILITY concerns) provided an assessment determines plant safety is maintained or enhanced. This assessment shall, as a minimum, consider the potential outcomes and transients associated with a failed Surveillance, a successful Surveillance, and a perturbation of the offsite or onsite system when they are tied together or operated independently for the Surveillance; as well as the operator procedures available to cope with these outcomes. These shall be measured against the avoided risk of a plant shutdown and startup to determine that plant safety is maintained or enhanced when the Surveillance is performed in MODE 1 or 2. Risk insights or deterministic methods may be used for this assessment. Credit may be taken for unplanned events that satisfy this SR. Note 2 ensures that the EDG is tested under load conditions that are as close to design basis conditions as possible. When synchronized with offsite power, testing should be performed at a power factor of \( \leq 0.9 \).

This power factor is representative of the actual inductive loading an EDG would see under design basis accident conditions. Under certain conditions, however, Note 2 allows the Surveillance to be conducted at a power factor other than \( \leq 0.9 \). These conditions occur when grid voltage is high, and the additional field excitation needed to get the power factor to \( \leq 0.9 \) results in voltages on the emergency busses that are too high. Under these conditions, the power factor should be maintained as close as practicable to 0.9 while still maintaining acceptable voltage limits on the emergency busses. In other circumstances, the grid voltage could be such that the EDG excitation levels needed to obtain a power factor of 0.9 may not cause unacceptable voltages on the emergency busses, but the excitation levels are in excess of those recommended for the EDG. In such cases, the power factor shall be maintained as close as practicable to 0.9 without exceeding the EDG excitation limits.
The above MODE restrictions may be deleted if it can be demonstrated to the staff, on a plant specific basis, that performing the SR with the reactor in any of the restricted MODES can satisfy the following criteria, as applicable:

a. Performance of the SR will not render any safety system or component inoperable.

b. Performance of the SR will not cause perturbations to any of the electrical distribution systems that could result in a challenge to steady state operation or to plant safety systems.

c. Performance of the SR or failure of the SR will not cause or result in an AOO with attendant challenge to plant safety systems.

SR 3.8.1.11

As required by NRC RG 1.9 (Ref. 3), this Surveillance demonstrates the as-designed operation of the standby power sources during loss of the offsite power source. This test verifies all actions encountered from the loss of offsite power, including shedding of the nonessential loads and energization of the emergency buses and respective loads from the EDG. It further demonstrates the capability of the EDG to automatically achieve the required voltage and frequency within the specified time.

The EDG auto-start time of 17 seconds is derived from requirements of the accident analysis to respond to a design basis large break LOCA. The Surveillance should be continued for a minimum of 5 minutes in order to demonstrate all starting transients have decayed and stability has been achieved.

The requirement to verify the connection and power supply of permanent and auto-connected loads is intended to satisfactorily show the relationship of these loads to the EDG loading logic. In certain circumstances, many of these loads cannot actually be connected or loaded without undue hardship or potential for undesired operation. For instance, Emergency Core Cooling Systems (ECCS) injection valves are not desired to be stroked open, high pressure injection systems are not capable of being operated at full flow, or Shutdown Cooling (SC) Systems performing a decay heat removal function are not desired to be realigned to the ECCS mode of operation. In lieu of actual demonstration of connection and loading of loads, testing that adequately shows the capability of the EDG System to perform these functions is acceptable.
This testing may include any series of sequential, overlapping, or total steps so that the entire connection and loading sequence is verified.

The 18 month Frequency is consistent with the recommendations of NRC RG 1.9 (Ref. 3), takes into consideration unit conditions required to perform the Surveillance, and is intended to be consistent with expected fuel cycle lengths.

This SR is modified by two Notes. The reason for Note 1 is to minimize wear and tear on the EDGs during testing. For the purpose of this testing, the EDGs must be started from standby conditions (i.e., engine coolant and oil continuously circulated and temperature maintained consistent with manufacturer recommendations).

The reason for Note 2 is that performing the Surveillance would remove a required offsite circuit from service, perturb the electrical distribution system, and challenge safety systems. This restriction from normally performing the Surveillance in MODE 1 or 2 is further amplified to allow portions of the Surveillance to be performed for the purpose of reestablishing OPERABILITY (e.g., post work testing following corrective maintenance, corrective modification, deficient or incomplete surveillance testing, and other unanticipated OPERABILITY concerns) provided an assessment determines plant safety is maintained or enhanced. This assessment shall, as a minimum, consider the potential outcomes and transients associated with a failed partial Surveillance, a successful partial Surveillance, and a perturbation of the offsite or onsite system when they are tied together or operated independently for the partial Surveillance; as well as the operator procedures available to cope with these outcomes. These shall be measured against the avoided risk of a plant shutdown and startup to determine that plant safety is maintained or enhanced when portions of the Surveillance are performed in MODE 1 or 2. Risk insights or deterministic methods may be used for the assessment. Credit can be taken for unplanned events that satisfy this SR.

SR 3.8.1.12

This Surveillance demonstrates that the EDG automatically starts and achieves the required voltage and frequency within the specified time (17 seconds) from the design basis actuation signal (LOCA signal) and operates for ≥ 5 minutes. The 5 minute period provides sufficient time to demonstrate stability. SR 3.8.1.12d and SR 3.8.1.12e ensure that permanently connected loads and emergency loads are energized from offsite electrical power system on an ESF signal without loss of offsite power.
The requirement to verify the connection of permanent and auto-connected loads is intended to satisfactorily show the relationship of these loads to the EDG loading logic. In certain circumstances, many of these loads cannot actually be connected or loaded without undue hardship or potential for undesired operation. For instance, the ECCS injection valves are not desired to be stroked open, high pressure injection systems are not capable of being operated at full flow, or SC System performing a decay heat removal function are not desired to be realigned to the ECCS mode of operation. In lieu of actual demonstration of connection and loading of loads, testing that adequately shows the capability of the EDG System to perform these functions is acceptable.

This testing may include any series of sequential, overlapping, or total steps so that the entire connection and loading sequence is verified.

The 18 month Frequency takes into consideration unit conditions required to perform the Surveillance and is intended to be consistent with the expected fuel cycle lengths. Operating experience has shown that these components usually pass the SR when performed at the 18 month Frequency. Therefore, the Frequency was concluded to be acceptable from a reliability standpoint.

This SR is modified by [two Notes. The reason for Note 1] is to minimize wear and tear on the EDGs during testing. For the purpose of this testing, the EDGs must be started from standby conditions, that is, with the engine coolant and oil continuously circulated and temperature maintained consistent with manufacturer recommendations. [The reason for Note 2 is that during operation with the reactor critical, performance of this Surveillance could cause perturbations to the electrical distribution systems that could challenge continued steady state operation and, as a result, unit safety systems. This restriction from normally performing the Surveillance in MODE 1 or 2 is further amplified to allow portions of the Surveillance to be performed for the purpose of reestablishing OPERABILITY (e.g., post work testing following corrective maintenance, corrective modification, deficient or incomplete surveillance testing, and other unanticipated OPERABILITY concerns) provided an assessment determines plant safety is maintained or enhanced. This assessment shall, as a minimum, consider the potential outcomes and transients associated with a failed partial Surveillance, a successful partial Surveillance, and a perturbation of the offsite or onsite system when they are tied together or operated independently for the partial Surveillance; as well as the operator procedures available to cope with these outcomes. These shall be measured against the avoided risk of a plant shutdown and startup to determine that plant safety is maintained or enhanced]
when portions of the Surveillance are performed in MODE 1 or 2. Risk insights or deterministic methods may be used for the assessment. Credit may be taken for unplanned events that satisfy this SR.]

SR 3.8.1.13

This Surveillance demonstrates that EDG noncritical protective functions (e.g., high jacket water temperature) are bypassed on a loss of voltage concurrent with an ESF actuation test signal. Noncritical automatic trips are all automatic trips except:

a. Engine overspeed and
b. Generator differential current.

The noncritical trips are bypassed during DBAs and provide an alarm on an abnormal engine condition. This alarm provides the operator with sufficient time to react appropriately. The EDG availability to mitigate the DBA is more critical than protecting the engine against minor problems that are not immediately detrimental to emergency operation of the EDG.

The 18 month Frequency is based on engineering judgment, taking into consideration unit conditions required to perform the Surveillance, and is intended to be consistent with expected fuel cycle lengths. Operating experience has shown that these components usually pass the SR when performed at the 18 month Frequency. Therefore, the Frequency was concluded to be acceptable from a reliability standpoint.

This SR is modified by a Note. The reason for the Note is that performing the Surveillance would remove a required EDG from service. This restriction from normally performing the Surveillance in MODE 1 or 2 is further amplified to allow the Surveillance to be performed for the purpose of reestablishing OPERABILITY (e.g., post work testing following corrective maintenance, corrective modification, deficient or incomplete surveillance testing, and other unanticipated OPERABILITY concerns) provided an assessment determines plant safety is maintained or enhanced. This assessment shall, as a minimum, consider the potential outcomes and transients associated with a failed Surveillance, a successful Surveillance, and a perturbation of the offsite or onsite system when they are tied together or operated independently for the Surveillance; as well as the operator procedures available to cope with these outcomes. These shall be measured against the avoided risk of a plant shutdown and startup to determine that plant safety is maintained or enhanced when the Surveillance is performed in MODE 1 or 2. Risk
insights or deterministic methods may be used for this assessment. Credit may be taken for unplanned events that satisfy this SR.

[----------------------------------REVIEWER’S NOTE-----------------------------------]

The above MODE restrictions may be deleted if it can be demonstrated to the staff, on a plant specific basis, that performing the SR with the reactor in any of the restricted MODES can satisfy the following criteria, as applicable:

a. Performance of the SR will not render any safety system or component inoperable.

b. Performance of the SR will not cause perturbations to any of the electrical distribution systems that could result in a challenge to steady state operation or to plant safety systems.

c. Performance of the SR or failure of the SR will not cause or result in an AOO with attendant challenge to plant safety systems.

SR 3.8.1.14

NRC RG 1.9 (Ref. 3) requires demonstration that the EDGs can start and run continuously at full load capability for an interval of not < 24 hours, ≥ 2 hours of which is at a load equivalent to 110% of the continuous duty rating and the remainder of the time at a load equivalent to the continuous duty rating of the EDG. The EDG starts for this Surveillance can be performed either from standby or hot conditions. The provisions for prelubricating and warmup, discussed in SR 3.8.1.2, and for gradual loading, discussed in SR 3.8.1.3, are applicable to this SR.

The load band is provided to avoid routine overloading of the EDG. Routine overloading could result in more frequent teardown inspections in accordance with vendor recommendations in order to maintain EDG OPERABILITY.

The 18 month Frequency is consistent with the recommendations of NRC RG 1.9 (Ref. 3) takes into consideration unit conditions required to perform the Surveillance, and is intended to be consistent with expected fuel cycle lengths.
This Surveillance is modified by three Notes. Note 1 states that momentary transients due to changing bus loads do not invalidate this test. Similarly, momentary power factor transients above the power factor limit will not invalidate the test. The reason for Note 2 is that during operation with the reactor critical, performance of this Surveillance could cause perturbations to the electrical distribution systems that could challenge continued steady state operation and, as a result, unit safety systems. This restriction from normally performing the Surveillance in MODE 1 or 2 is further amplified to allow the Surveillance to be performed for the purpose of reestablishing OPERABILITY (e.g., post work testing following corrective maintenance, corrective modification, deficient or incomplete surveillance testing, and other unanticipated OPERABILITY concerns) provided an assessment determines plant safety is maintained or enhanced. This assessment shall, as a minimum, consider the potential outcomes and transients associated with a failed Surveillance, a successful Surveillance, and a perturbation of the offsite or onsite system when they are tied together or operated independently for the Surveillance; as well as the operator procedures available to cope with these outcomes. These shall be measured against the avoided risk of a plant shutdown and startup to determine that plant safety is maintained or enhanced when the Surveillance is performed in MODE 1 or 2. Risk insights or deterministic methods may be used for this assessment. Credit may be taken for unplanned events that satisfy this SR. Note 3 ensures that the EDG is tested under load conditions that are as close to design basis conditions as possible. When synchronized with offsite power, testing should be performed at a power factor of \( \leq 0.9 \). This power factor is representative of the actual inductive loading an EDG would see under design basis accident conditions. Under certain conditions, however, Note 3 allows the Surveillance to be conducted at a power factor other than \( \leq 0.9 \). These conditions occur when grid voltage is high, and the additional field excitation needed to get the power factor to \( \leq 0.9 \) results in voltages on the emergency busses that are too high. Under these conditions, the power factor should be maintained as close as practicable to 0.9 while still maintaining acceptable voltage limits on the emergency busses.

In other circumstances, the grid voltage could be such that the EDG excitation levels needed to obtain a power factor of 0.9 may not cause unacceptable voltages on the emergency busses, but the excitation levels are in excess of those recommended for the EDG. In such cases, the power factor shall be maintained as close practicable to 0.9 without exceeding the EDG excitation limits.
SURVEILLANCE REQUIREMENTS (continued)

SR 3.8.1.15

This Surveillance demonstrates that the diesel engine can restart from a hot condition, such as subsequent to a shutdown from normal Surveillances, and achieve the required voltage and frequency within 17 seconds. The 17 second time is derived from the requirements of the accident analysis to respond to a design basis large break LOCA. The 18 month Frequency is consistent with the recommendations of NRC RG 1.9 (Ref. 3).

This SR is modified by two Notes. Note 1 ensures that the test is performed with the diesel sufficiently hot. The load band is provided to avoid routine overloading of the EDG. Routine overloads could result in more frequent teardown inspection in accordance with vendor recommendations in order to maintain OPERABILITY. This requirement that the diesel has operated for at least 2 hours at full load condition prior to performance of this Surveillance is based on manufacturer recommendations for achieving hot conditions. Momentary transients due to changing bus loads do not invalidate the test. Note 2 allows all EDG starts to be preceded by an engine prelube period to minimize wear and tear on the diesel during testing.

SR 3.8.1.16

As required by NRC RG 1.9 (Ref. 3), this Surveillance assures that the manual synchronization and automatic load transfer from the EDG to the offsite source can be made and that the EDG can be returned to ready to load status when offsite power is restored. It also ensures that the auto-start logic is reset to allow the EDG to reload if a subsequent loss of offsite power occurs. The EDG is considered to be in ready to load status when the EDG is at rated speed and voltage, the output breaker is open and can receive an autoclose signal on bus undervoltage, and the load sequence timers are reset.

The 18 month Frequency is consistent with the recommendations of NRC RG 1.9 (Ref. 3) and takes into consideration unit conditions required to perform the Surveillance.
SURVEILLANCE REQUIREMENTS (continued)

This SR is modified by a Note. The reason for the Note is that performing the Surveillance would remove a required offsite circuit from service, perturb the electrical distribution system, and challenge safety systems. This restriction from normally performing the Surveillance in MODE 1 or 2 is further amplified to allow the Surveillance to be performed for the purpose of reestablishing OPERABILITY (e.g., post work testing following corrective maintenance, corrective modification, deficient or incomplete surveillance testing, and other unanticipated OPERABILITY concerns) provided an assessment determines plant safety is maintained or enhanced. This assessment shall, as a minimum, consider the potential outcomes and transients associated with a failed Surveillance, a successful Surveillance, and a perturbation of the offsite or onsite system when they are tied together or operated independently for the Surveillance; as well as the operator procedures available to cope with these outcomes. These shall be measured against the avoided risk of a plant shutdown and startup to determine that plant safety is maintained or enhanced when the Surveillance is performed in MODE 1 or 2. Risk insights or deterministic methods may be used for this assessment. Credit may be taken for unplanned events that satisfy this SR.

SR 3.8.1.17

Demonstration of the test mode override ensures that the EDG availability under accident conditions will not be compromised as the result of testing and the EDG will automatically reset to ready to load operation if a LOCA actuation signal is received during operation in the test mode. Ready to load operation is defined as the EDG running at rated speed and voltage with the EDG output breaker open. These provisions for automatic switchover are required by IEEE Std. 308 (Ref. 12), paragraph 6.2.6(2).

The requirement to automatically energize the emergency loads with offsite power is essentially identical to that of SR 3.8.1.12. The intent in the requirement associated with SR 3.8.1.17b is to show that the emergency loading was not affected by the EDG operation in test mode. In lieu of actual demonstration of connection and loading of loads, testing that adequately shows the capability of the emergency loads to perform these functions is acceptable. This testing may include any series of sequential, overlapping, or total steps so that the entire connection and loading sequence is verified.
The 18 month Frequency is consistent with the recommendations of NRC RG 1.9 (Ref. 3), takes into consideration unit conditions required to perform the Surveillance, and is intended to be consistent with expected fuel cycle lengths.

This SR is modified by a Note. The reason for the Note is that performing the Surveillance would remove a required offsite circuit from service, perturb the electrical distribution system, and challenge safety systems. This restriction from normally performing the Surveillance in MODE 1 or 2 is further amplified to allow portions of the Surveillance to be performed for the purpose of reestablishing OPERABILITY (e.g., post work testing following corrective maintenance, corrective modification, deficient or incomplete surveillance testing, and other unanticipated OPERABILITY concerns) provided an assessment determines plant safety is maintained or enhanced. This assessment shall, as a minimum, consider the potential outcomes and transients associated with a failed partial Surveillance, a successful partial Surveillance, and a perturbation of the offsite or onsite system when they are tied together or operated independently for the partial Surveillance; as well as the operator procedures available to cope with these outcomes. These shall be measured against the avoided risk of a plant shutdown and startup to determine that plant safety is maintained or enhanced when portions of the Surveillance are performed in MODE 1 or 2. Risk insights or deterministic methods may be used for the assessment. Credit may be taken for unplanned events that satisfy this SR.

**SR 3.8.1.18**

Under accident and loss of offsite power conditions, loads are sequentially connected to the bus by the automatic load sequencer. The sequencing logic controls the permissive and starting signals to motor breakers to prevent overloading of the EDGs due to high motor starting currents. The 10% load sequence time interval tolerance ensures that sufficient time exists for the EDG to restore frequency and voltage prior to applying the next load and that safety analysis assumptions regarding ESF equipment time delays are not violated. Reference 2 provides a summary of the automatic loading of ESF buses.

The 18 month Frequency is consistent with the recommendations of NRC RG 1.9 (Ref. 3), takes into consideration unit conditions required to perform the Surveillance, and is intended to be consistent with expected fuel cycle lengths.
This SR is modified by a Note. The reason for the Note is that performing the Surveillance would remove a required offsite circuit from service, perturb the electrical distribution system, and challenge safety systems. This restriction from normally performing the Surveillance in MODE 1 or 2 is further amplified to allow the Surveillance to be performed for the purpose of reestablishing OPERABILITY (e.g., post work testing following corrective maintenance, corrective modification, deficient or incomplete surveillance testing, and other unanticipated OPERABILITY concerns) provided an assessment determines plant safety is maintained or enhanced. This assessment shall, as a minimum, consider the potential outcomes and transients associated with a failed Surveillance, a successful Surveillance, and a perturbation of the offsite or onsite system when they are tied together or operated independently for the Surveillance; as well as the operator procedures available to cope with these outcomes. These shall be measured against the avoided risk of a plant shutdown and startup to determine that plant safety is maintained or enhanced when the Surveillance is performed in MODE 1 or 2. Risk insights or deterministic methods may be used for this assessment. Credit may be taken for unplanned events that satisfy this SR.

[----------------------------------REVIEWER’S NOTE-----------------------------------]

The above MODE restrictions may be deleted if it can be demonstrated to the staff, on a plant specific basis, that performing the SR with the reactor in any of the restricted MODES can satisfy the following criteria, as applicable:

a. Performance of the SR will not render any safety system or component inoperable.

b. Performance of the SR will not cause perturbations to any of the electrical distribution systems that could result in a challenge to steady state operation or to plant safety systems.

c. Performance of the SR or failure of the SR will not cause or result in an AOO with attendant challenge to plant safety systems.

SR 3.8.1.19

In the event of a DBA coincident with a loss of offsite power, the EDGs are required to supply the necessary power to ESF Systems so that the fuel, Reactor Coolant System (RCS), and containment design limits are not exceeded.
This Surveillance demonstrates the EDG operation, as discussed in the Bases for SR 3.8.1.11, during a loss of offsite power actuation test signal in conjunction with an ESF actuation signal. In lieu of actual demonstration of connection and loading of loads, testing that adequately shows the capability of the EDG System to perform these functions is acceptable. This testing may include any series of sequential, overlapping, or total steps so that the entire connection and loading sequence is verified.

The 18 month Frequency takes into consideration unit conditions required to perform the Surveillance and is intended to be consistent with an expected fuel cycle length of 18 months.

This SR is modified by two Notes. The reason for Note 1 is to minimize wear and tear on the EDGs during testing. For the purpose of this testing, the EDGs must be started from standby conditions, that is, with the engine coolant and oil continuously circulated and temperature maintained consistent with manufacturer recommendations for EDGs. The reason for Note 2 is that performing the Surveillance would remove a required offsite circuit from service, perturb the electrical distribution system, and challenge safety systems. This restriction from normally performing the Surveillance in MODE 1 or 2 is further amplified to allow portions of the Surveillance to be performed for the purpose of reestablishing OPERABILITY (e.g., post work testing following corrective maintenance, corrective modification, deficient or incomplete surveillance testing, and other unanticipated OPERABILITY concerns) provided an assessment determines plant safety is maintained or enhanced.

This assessment shall, as a minimum, consider the potential outcomes and transients associated with a failed partial Surveillance, a successful partial Surveillance, and a perturbation of the offsite or onsite system when they are tied together or operated independently for the partial Surveillance; as well as the operator procedures available to cope with these outcomes. These shall be measured against the avoided risk of a plant shutdown and startup to determine that plant safety is maintained or enhanced when portions of the Surveillance are performed in MODE 1 or 2. Risk insights or deterministic methods may be used for the assessment. Credit may be taken for unplanned events that satisfy this SR.

SR 3.8.1.20

This Surveillance demonstrates that the EDG starting independence has not been compromised. Also, this Surveillance demonstrates that each
engine can achieve proper speed within the specified time when the EDGs are started simultaneously.

The 10 year Frequency is consistent with the recommendations of NRC RG 1.9 (Ref. 3).

This SR is modified by a Note. The reason for the Note is to minimize wear on the EDG during testing. For the purpose of this testing, the EDGs must be started from standby conditions (i.e., engine coolant and oil continuously circulated and temperature maintained consistent with manufacturer recommendations).

REFERENCES

1. 10 CFR Part 50, Appendix A, GDC 17.
2. FSAR, Chapter 8.
4. FSAR, Chapter 6.
5. FSAR, Chapter 15.
11. ASME OM Code.
### B 3.8  ELECTRICAL POWER SYSTEMS

#### B 3.8.2  AC Sources – Shutdown

**BASES**

**BACKGROUND**

A description of the alternating current (AC) sources is provided in the Bases for LCO 3.8.1, “AC Sources – Operating.”

**APPLICABLE SAFETY ANALYSES**

The OPERABILITY of the minimum AC sources during MODES 5 and 6 and during movement of irradiated fuel assemblies ensures that:

a. The unit can be maintained in the shutdown or refueling condition for extended periods,

b. Sufficient instrumentation and control capability is available for monitoring and maintaining the unit status, and

c. Adequate AC electrical power is provided to mitigate events postulated during shutdown, such as a fuel handling accident involving handling irradiated fuel.

In general, when the unit is shut down, the Technical Specifications (TS) requirements ensure that the unit has the capability to mitigate the consequences of postulated accidents. However, assuming a single failure and concurrent loss of all offsite or all onsite power is not required. The rationale for this is based on the fact that many design basis accidents (DBAs) that are analyzed in MODES 1, 2, 3, and 4 have no specific analyses in MODES 5 and 6. Worst case bounding events are deemed not credible in MODES 5 and 6 because the energy contained within the reactor pressure boundary, reactor coolant temperature and pressure, and the corresponding stresses result in the probabilities of occurrence being significantly reduced or eliminated, and in minimal consequences. These deviations from DBA analysis assumptions and design requirements during shutdown conditions are allowed by the LCO for required systems.

During MODES 1, 2, 3, and 4, various deviations from the analysis assumptions and design requirements are allowed within the Required Actions. This allowance is in recognition that certain testing and maintenance activities must be conducted provided an acceptable level of risk is not exceeded.
APPLICABLE SAFETY ANALYSES (continued)

During MODES 5 and 6, performance of a significant number of required testing and maintenance activities is also required. In MODES 5 and 6, the activities are generally planned and administratively controlled. Relaxations from MODE 1, 2, 3, and 4 LCO requirements are acceptable during shutdown MODES based on:

a. The fact that time in an outage is limited. This is a risk prudent goal as well as a utility economic consideration.

b. Requiring appropriate compensatory measures for certain conditions. These may include administrative controls, reliance on systems that do not necessarily meet typical design requirements applied to systems credited in operating MODE analyses, or both.

c. Prudent utility consideration of the risk associated with multiple activities that could affect multiple systems.

d. Maintaining, to the extent practical, the ability to perform required functions (even if not meeting MODE 1, 2, 3, and 4 OPERABILITY requirements) with systems assumed to function during an event.

In the event of an accident during shutdown, this LCO ensures the capability to support systems necessary to avoid immediate difficulty, assuming either a loss of all offsite power or a loss of all onsite emergency diesel generator (EDG) power.

The AC sources satisfy Criterion 3 of 10 CFR 50.36(c)(2)(ii).

LCO

One offsite circuit capable of supplying the onsite Class 1E power distribution subsystems of LCO 3.8.10, “Distribution Systems – Shutdown,” ensures that all required loads are powered from offsite power. Two OPERABLE EDGs, associated with a distribution system division required to be OPERABLE by LCO 3.8.10, ensures a diverse power source is available to provide electrical power support, assuming a loss of the offsite circuit. Together, OPERABILITY of the required offsite circuit and EDGs ensures the availability of sufficient AC sources to operate the unit in a safe manner and to mitigate the consequences of postulated events during shutdown (e.g., fuel handling accidents involving handling irradiated fuel).
The qualified offsite circuit must be capable of maintaining rated frequency and voltage, and accepting required loads during an accident, while connected to the 4.16 kV Class 1E buses (ESF buses). Qualified offsite circuits are those that are described in FSAR Section 8.2 (Ref. 1) and are part of the licensing basis for the unit.

- Offsite circuit #1 supplies power from the switchyard to the ESF buses via the main transformer and the unit auxiliary transformers TR01M for division I and TR02M for division II.

- Offsite circuit #2 supplies power from the switchyard to the ESF buses via the standby auxiliary transformers TR01N for division I and TR02N for division II.

The EDG must be capable of starting, accelerating to rated speed and voltage, connecting to its respective ESF bus on detection of bus undervoltage, and accepting required loads. This sequence must be accomplished within 17 seconds. The EDG must be capable of accepting required loads within the assumed loading sequence intervals, and must continue to operate until offsite power can be restored to the ESF buses. These capabilities are required to be met from a variety of initial conditions such as EDG in standby with the engine hot and EDG in standby at ambient conditions.

Proper sequencing of loads, including tripping of nonessential loads, is a required function for EDG OPERABILITY.

In addition, proper sequencer operation is an integral part of offsite circuit OPERABILITY if its inoperability impacts on the ability to start and maintain energized loads required OPERABLE by LCO 3.8.10.

It is acceptable for divisions to be cross tied during shutdown conditions, allowing a single offsite power circuit to supply all required divisions.

APPLICABILITY

The AC sources required to be OPERABLE in MODES 5 and 6 and during movement of irradiated fuel assemblies provide assurance that:

a. Systems to provide adequate coolant inventory makeup are available for the irradiated fuel assemblies.

b. Systems needed to mitigate a fuel handling accident are available.

c. Systems necessary to mitigate the effects of events that can lead to core damage during shutdown are available.
BASES

APPLICABILITY (continued)

d. Instrumentation and control capability is available for monitoring and maintaining the unit in a cold shutdown condition or refueling condition.

AC power requirements for MODES 1, 2, 3, and 4 are addressed in LCO 3.8.1.

ACTIONS

LCO 3.0.3 is not applicable while in MODE 5 or 6. However, since irradiated fuel assembly movement can occur in MODE 1, 2, 3, or 4, the ACTIONS have been modified by a Note stating that LCO 3.0.3 is not applicable. If moving irradiated fuel assemblies while in MODE 5 or 6, LCO 3.0.3 would not specify any action. If moving irradiated fuel assemblies while in MODE 1, 2, 3, or 4, the fuel movement is independent of reactor operations. Entering LCO 3.0.3, while in MODE 1, 2, 3, or 4 would require the unit to be shutdown unnecessarily.

A.1

An offsite circuit would be considered inoperable if it were not available to one required ESF division. Although two divisions may be required by LCO 3.8.10, the remaining division with offsite power available could be capable of supporting sufficient required features to allow continuation of irradiated fuel movement. By the allowance of the option to declare required features inoperable, with no offsite power available, appropriate restrictions will be implemented in accordance with the affected required features LCO’s ACTIONS.

A.2.1, A.2.2, A.2.3, B.1, B.2, and B.3

With the offsite circuit not available to all required divisions, the option would still exist to declare all required features inoperable. Since this option could involve undesired administrative efforts, the allowance for sufficiently conservative ACTIONS is made. With the required EDG inoperable, the minimum required diversity of AC power sources is not available. It is, therefore, required to suspend movement of irradiated fuel assemblies, and operations involving positive reactivity additions that could result in loss of required SDM (MODE 5) or boron concentration (MODE 6). Suspending positive reactivity additions that could result in failure to meet the minimum SDM or boron concentration limit is required to assure continued safe operation.
Introduction of coolant inventory must be from sources that have a boron concentration greater than that which would be required in the Reactor Coolant System (RCS) for minimum SDM or refueling boron concentration. This could result in an overall reduction in RCS boron concentration, but provides acceptable margin to maintaining subcritical operation. Introduction of temperature changes including temperature increases when operating with a positive moderator temperature coefficient (MTC) must also be evaluated to ensure they do not result in a loss of required SDM.

Suspension of these activities does not preclude completion of actions to establish a safe conservative condition. These actions minimize the probability or the occurrence of postulated events. It is further required to immediately initiate action to restore the required AC sources and to continue this action until restoration is accomplished in order to provide the necessary AC power to the unit safety systems.

The Completion Time of immediately is consistent with the required times for actions requiring prompt attention. The restoration of the required AC electrical power sources should be completed as quickly as possible in order to minimize the time during which the unit safety systems could be without sufficient power.

Pursuant to LCO 3.0.6, the distribution system's ACTIONS are not entered even if all AC sources to it are inoperable, resulting in de-energization. Therefore, the Required Actions of Condition A are modified by a Note to indicate that when Condition A is entered with no AC power to any ESF bus, the ACTIONS for LCO 3.8.10 must be immediately entered. This Note allows Condition A to provide requirements for the loss of the offsite circuit, whether or not a division is de-energized. LCO 3.8.10 provides the appropriate restrictions for the situation involving a de-energized division.

SR 3.8.2.1 requires the SRs from LCO 3.8.1 that are necessary for ensuring the OPERABILITY of the AC sources in other than MODES 1, 2, 3, and 4. SR 3.8.1.8 is not required to be met since only one offsite circuit is required to be OPERABLE. SR 3.8.1.12 and SR 3.8.1.19 are not required to be met because the ESF actuation signal is not required to be OPERABLE. SR 3.8.1.17 is not required to be met because the required OPERABLE EDG(s) is not required to undergo periods of being synchronized to the offsite circuit. SR 3.8.1.20 is excepted because
starting independence is not required with EDG(s) that are not required to be OPERABLE.

This SR is modified by a Note. The reason for the Note is to preclude requiring the OPERABLE EDG(s) from being paralleled with the offsite power network or otherwise rendered inoperable during performance of SRs, and to preclude deenergizing a required ESF bus or disconnecting a required offsite circuit during performance of SRs. With limited AC Sources available, a single event could compromise both the required circuit and the EDG. It is the intent that these SRs must still be capable of being met, but actual performance is not required during periods when the EDG and offsite circuit is required to be OPERABLE. Refer to the corresponding Bases for LCO 3.8.1 for a discussion of each SR.

REFERENCES

1. FSAR, Section 8.2.
B 3.8  ELECTRICAL POWER SYSTEMS

B 3.8.3  Diesel Fuel Oil, Lube Oil, and Starting Air

BASES

BACKGROUND  Each emergency diesel generator (EDG) is provided with a storage tank having a fuel oil capacity sufficient to operate that diesel for a period of 7 days, while the EDG is supplying maximum post loss-of-coolant accident load demand as discussed in Subsection 9.5.4 (Ref. 1) and Nuclear Regulatory Commission (NRC) Regulatory Guide (RG) 1.137 (Ref. 2). The maximum load demand is calculated using the assumption that at least two EDGs are available. This onsite fuel oil capacity is sufficient to operate the EDGs for longer than the time to replenish the onsite supply from outside sources.

Fuel oil is transferred from storage tank to day tank by either of two transfer pumps associated with each storage tank. Redundancy of pumps and piping precludes the failure of one pump, or the rupture of any pipe, valve, or tank to result in the loss of more than one EDG. All outside tanks, pumps, and piping are located underground.

For proper operation of the standby EDGs, it is necessary to ensure the proper quality of the fuel oil. NRC RG 1.137 (Ref. 2) addresses the recommended fuel oil practices as supplemented by ANSI/ANS-59.51-1997 (Ref. 3). The fuel oil properties governed by these SRs are the water and sediment content, the kinematic viscosity, specific gravity (or API gravity), and impurity level.

The EDG Lubrication System is designed to provide sufficient lubrication to permit proper operation of its associated EDG under all loading conditions. The system is required to circulate the lube oil to the diesel engine working surfaces and to remove excess heat generated by friction during operation. Each engine oil sump contains an inventory capable of supporting a minimum of 7 days of operation. The onsite storage in addition to the engine oil sump is sufficient to ensure 7 days of continuous operation. This supply is sufficient supply to allow the operator to replenish lube oil from outside sources.

Each EDG has an air start system with adequate capacity for five successive start attempts on the EDG without recharging the air start receiver(s).
The initial conditions of design basis accident (DBA) and transient analyses in FSAR, Chapter 6 (Ref. 4), and in the Chapter 15 (Ref. 5), assume Engineered Safety Feature (ESF) Systems are OPERABLE. The EDGs are designed to provide sufficient capacity, capability, redundancy, and reliability to ensure the availability of necessary power to ESF Systems so that fuel, Reactor Coolant System, and containment design limits are not exceeded. These limits are discussed in more detail in the Bases for LCOs 3.2, “Power Distribution Limits,” 3.4, “Reactor Coolant System (RCS),” and 3.6, “Containment Systems.”

Since diesel fuel oil, lube oil, and the air start subsystems support the operation of the standby AC power sources, they satisfy Criterion 3 of 10 CFR 50.36(c)(2)(ii).

Stored diesel fuel oil is required to have sufficient supply for 7 days of full load operation. It is also required to meet specific standards for quality. Additionally, sufficient lubricating oil supply must be available to ensure the capability to operate at full load for 7 days. This requirement, in conjunction with an ability to obtain replacement supplies within 7 days, supports the availability of EDGs required to shut down the reactor and to maintain it in a safe condition for an anticipated operational occurrence (AOO) or a postulated DBA with loss of offsite power. EDG day tank fuel requirements, as well as transfer capability from the storage tank to the day tank, are addressed in LCO 3.8.1, “AC Sources – Operating,” and LCO 3.8.2, “AC Sources – Shutdown.”

The Starting Air System is required to have a minimum capacity for five successive EDG start attempts without recharging the air start receivers.

The AC sources (LCO 3.8.1 and LCO 3.8.2) are required to ensure the availability of the required power to shut down the reactor and maintain it in a safe shutdown condition after an AOO or a postulated DBA. Since stored diesel fuel oil, lube oil, and starting air subsystems support LCO 3.8.1 and LCO 3.8.2, stored diesel fuel oil, lube oil and starting air are required to be within limits when the associated EDG is required to be OPERABLE.
The ACTIONS Table is modified by a Note indicating that separate Condition entry is allowed for each EDG. This is acceptable, since the Required Actions for each Condition provide appropriate compensatory actions for each inoperable EDG subsystem. Complying with the Required Actions for one inoperable EDG subsystem may allow for continued operation, and subsequent inoperable EDG subsystem(s) are governed by separate Condition entry and application of associated Required Actions.

A.1

In this Condition, the 7 day fuel oil supply for an EDG is not available. However, the Condition is restricted to fuel oil level reductions that maintain at least a 6 day supply. The fuel oil level equivalent to a 6 day supply is [313,358 L (82,780 gal)]. These circumstances could be caused by events such as full load operation required after an inadvertent start while at minimum required level; or feed and bleed operations, which can be necessitated by increasing particulate levels or any number of other oil quality degradations. This restriction allows sufficient time for obtaining the requisite replacement volume and performing the analyses required prior to addition of fuel oil to the tank. A period of 48 hours is considered sufficient to complete restoration of the required level prior to declaring the EDG inoperable. This period is acceptable based on the remaining capacity (> 6 days), the fact that procedures will be initiated to obtain replenishment, and the low probability of an event during this brief period.

B.1

In this Condition, the 7 day lube oil inventory (i.e., sufficient lubricating oil to support 7 days of continuous EDG operation at full load conditions) is not available. However, the Condition is restricted to lube oil volume reductions that maintain at least a 6 day supply. The lube oil inventory equivalent to a 6 day supply is [1,609 L (425 gal)]. This restriction allows sufficient time to obtain the requisite replacement volume. A period of 48 hours is considered sufficient to complete restoration of the required volume prior to declaring the EDG inoperable. This period is acceptable based on the remaining capacity (> 6 days), the low rate of usage, the fact that procedures will be initiated to obtain replenishment, and the low probability of an event during this brief period.
C.1

This Condition is entered as a result of a failure to meet the acceptance criterion of SR 3.8.3.5. Normally, trending of particulate levels allows sufficient time to correct high particulate levels prior to reaching the limit of acceptability. Poor sample procedures (bottom sampling), contaminated sampling equipment, and errors in laboratory analysis can produce failures that do not follow a trend. Since the presence of particulates does not mean failure of the fuel oil to burn properly in the diesel engine, and particulate concentration is unlikely to change significantly between Surveillance Frequency intervals, and proper engine performance has been recently demonstrated (within 31 days), it is prudent to allow a brief period prior to declaring the associated EDG inoperable. The 7 day Completion Time allows for further evaluation, resampling, and reanalysis of the EDG fuel oil.

D.1

With the new fuel oil properties defined in the Bases for SR 3.8.3.4 not within the required limits, a period of 30 days is allowed for restoring the stored fuel oil properties. This period provides sufficient time to test the stored fuel oil to determine that the new fuel oil, when mixed with previously stored fuel oil, remains acceptable, or restore the stored fuel oil properties. This restoration could involve feed and bleed procedures, filtering, or combinations of these procedures. Even if an EDG start and load was required during this time interval and the fuel oil properties were outside limits, there is a high likelihood that the EDG would still be capable of performing its intended function.

E.1

With starting air receiver pressure < [40.78 kg/cm²G (580 psig)], sufficient capacity for five successive EDG start attempts does not exist. However, as long as the receiver pressure is > [8.79 kg/cm²G (125 psig)], there is adequate capacity for at least one start attempt, and the EDG can be considered OPERABLE while the air receiver pressure is restored to the required limit. A period of 48 hours is considered sufficient to complete restoration to the required pressure prior to declaring the EDG inoperable. This period is acceptable based on the remaining air start capacity, the fact that most EDG starts are accomplished on the first attempt, and the low probability of an event during this brief period.
BASES

ACTIONS (continued)

F.1

With a Required Action and associated Completion Time not met, or one or more EDGs with diesel fuel oil, lube oil, or starting air subsystem not within limits for reasons other than addressed by Conditions A through E, the associated EDG could be incapable of performing its intended function and must be immediately declared inoperable.

SURVEILLANCE REQUIREMENTS

SR 3.8.3.1

This SR provides verification that there is an adequate inventory of fuel oil in the storage tanks to support each EDG's operation for 7 days at full load. The fuel oil level equivalent to a 7 day supply is [365,584 L (96,577 gal)] when calculated in accordance with References 2 and 3. The required fuel storage volume is determined using the most limiting energy content of the stored fuel. Using the known correlation of diesel fuel oil absolute specific gravity or API gravity to energy content, the required diesel generator output, and the corresponding fuel consumption rate, the onsite fuel storage volume required for 7 days of operation can be determined. SR 3.8.3.3 requires new fuel to be tested to verify that the absolute specific gravity or API gravity is within the range assumed in the diesel fuel oil consumption calculations. The 7 day period is sufficient time to place the unit in a safe shutdown condition and to bring in replenishment fuel from an offsite location.

The 31 day Frequency is adequate to ensure that a sufficient supply of fuel oil is available, since low level alarms are provided and unit operators would be aware of any large uses of fuel oil during this period.

SR 3.8.3.2

This Surveillance ensures that sufficient lube oil inventory is available to support at least 7 days of full load operation for each EDG. The lube oil inventory equivalent to a 7 day supply is [1,893 L (500 gal)] and is based on the EDG manufacturer consumption values for the run time of the EDG. Implicit in this SR is the requirement to verify the capability to transfer the lube oil from its storage location to the EDG, when the EDG lube oil sump does not hold adequate inventory for 7 days of full load operation without the level reaching the manufacturer recommended minimum level.

A 31 day Frequency is adequate to ensure that a sufficient lube oil supply is onsite, since EDG starts and run time are closely monitored by the unit staff.
The tests listed below are a means of determining whether new fuel oil is of the appropriate grade and has not been contaminated with substances that would have an immediate, detrimental impact on diesel engine combustion. If results from these tests are within acceptable limits, the fuel oil may be added to the storage tanks without concern for contaminating the entire volume of fuel oil in the storage tanks. These tests are to be conducted prior to adding the new fuel to the storage tank(s), but in no case is the time between receipt of new fuel and conducting the tests to exceed 31 days. The tests, limits, and applicable ASTM Standards are as follows:

a. Sample the new fuel oil in accordance with ASTM D4057-06 (Reapproved in 2011) (Ref. 6),

b. Verify in accordance with the tests specified in ASTM D975-13 (Ref. 6) that the sample has an absolute specific gravity at 15.6/15.6°C (60/60°F) of ≥ 0.83 and ≤ 0.89, or an API gravity at 15.6°C (60°F) of ≥ 27° and ≤ 39° when tested in accordance with ASTM D1298-12b (2012) (Ref. 6), a kinematic viscosity at 40°C (104°F) of ≥ 1.9 centistokes and ≤ 4.1 centistokes, and a flash point ≥ 51.7°C (125°F), and

c. Verify that the new fuel oil has a clear and bright appearance with proper color when tested in accordance with ASTM D4176-04 (2009) or a water and sediment content within limits when tested in accordance with ASTM D2709-96 (2011) e1 (Ref. 6).

Failure to meet any of the above limits is cause for rejecting the new fuel oil, but does not represent a failure to meet the LCO concern since the fuel oil is not added to the storage tanks. Within 31 days following the initial new fuel oil sample, the fuel oil is analyzed to establish that the other properties specified in Table 1 of ASTM D975-13 (Ref. 7) are met for new fuel oil when tested in accordance with ASTM D975-13 (Ref. 6), except that the analysis for sulfur may be performed in accordance with ASTM D1552-08, ASTM D2622-10, or ASTM D4294-10 (Ref. 6).

The 31 day period is acceptable because the fuel oil properties of interest, even if they were not within stated limits, would not have an immediate effect on EDG operation. This Surveillance ensures the availability of high quality fuel oil for the EDGs.
Fuel oil degradation during long term storage shows up as an increase in particulate, due mostly to oxidation. The presence of particulate does not mean the fuel oil will not burn properly in a diesel engine. The particulate can cause fouling of filters and fuel oil injection equipment, however, which can cause engine failure.

Particulate concentrations should be determined in accordance with ASTM D6217-11 (Ref. 6). This method involves the determination of the particulate concentration in the fuel oil and has a limit of 10 mg/l ($6.24\times10^{-4}$ lbm/ft$^3$). It is acceptable to obtain a field sample for subsequent laboratory testing in lieu of field testing. The Frequency of this test takes into consideration fuel oil degradation trends that indicate that particulate concentration is unlikely to change significantly between Frequency intervals.

SR 3.8.3.4

This Surveillance ensures that, without the aid of the refill compressor, sufficient air start capacity for each EDG is available. The system design requirements provide for a minimum of five engine start cycles without recharging. A start cycle is defined by the EDG vendor, but usually is measured in terms of time (seconds or cranking) or engine cranking speed. The pressure specified in this SR is intended to reflect the lowest value at which the five starts can be accomplished.

The 31 day Frequency takes into account the capacity, capability, redundancy, and diversity of the AC sources and other indications available in the main control room (MCR), including alarms, to alert the operator to below normal air start pressure.

SR 3.8.3.5

Microbiological fouling is a major cause of fuel oil degradation. There are numerous bacteria that can grow in fuel oil and cause fouling, but all must have a water environment in order to survive. Removal of water from the fuel storage tanks eliminates the necessary environment for bacterial survival. This is the most effective means of controlling microbiological fouling. In addition, it eliminates the potential for water entrainment in the fuel oil during EDG operation. Water can come from any of several sources, including condensation, ground water, rain water, and contaminated fuel oil, and from breakdown of the fuel oil by bacteria. Frequent checking for and removal of accumulated water minimizes fouling and provides data regarding the watertight integrity of the Fuel Oil.
System. The 31 day Surveillance Frequency is established by NRC RG 1.137 (Ref. 2). This SR is for preventative maintenance.

The presence of water does not necessarily represent failure of this SR provided the accumulated water is removed during performance of the Surveillance.

REFERENCES

1. FSAR, Subsection 9.5.4.


4. FSAR, Chapter 6.

5. FSAR, Chapter 15.

6. ASTM Standards: D4057-06 (Reapproved in 2011); D975-13; D1298-12b (2012); D4176-04 (2009); D2709-96 (Reapproved in 2011) e1; D1552-08; D2622-10; D4294-10; D6217-11.

7. ASTM Standards, D975-13, Table 1.
B 3.8 ELECTRICAL POWER SYSTEMS

B 3.8.4 DC Sources – Operating

BASES

BACKGROUND

The station Direct Current (DC) Electrical Power System provides the Alternating Current (AC) Emergency Power System with control power. It also provides both motive and control power to selected safety-related equipment and preferred AC vital bus power (via inverters). As required by 10 CFR Part 50, Appendix A, GDC 17 (Ref. 1), the DC Electrical Power System is designed to have sufficient independence, redundancy, and testability to perform its safety functions, assuming a single failure. The DC Electrical Power System also conforms to the recommendations of Nuclear Regulatory Commission (NRC) Regulatory Guide (RG) 1.6 (Ref. 2) and IEEE Std. 308 (Ref. 3).

The 125 Vdc Electrical Power System consists of two independent and redundant safety-related Class 1E DC electrical power divisions I and II. Each division consists of two independent trains A and C for division I, and trains B and D for division II. In addition, each train consists of one 125 Vdc battery, the associated battery charger for each battery, and all the associated control equipment and interconnecting cabling.

Additionally there is one spare battery charger per train, which provides backup service in the event that the preferred battery charger is out of service. If the spare battery charger is substituted for the preferred battery charger, then the requirements of independence and redundancy between divisions are maintained.

During normal operation, the 125 Vdc load is powered from the battery chargers with the batteries floating on the system. In case of loss of normal power to the battery charger, the DC load is automatically powered from the station batteries.

The trains A, B, C, and D DC electrical power subsystems provide the control power for its associated Class 1E AC power loads, 4.16 kV switchgear, and 480 Vac load centers. The DC electrical power subsystems also provide DC electrical power to the inverters, which in turn power the AC vital buses.

Each 125 Vdc battery is separately housed in a ventilated room apart from its charger and distribution center. Each subsystem is located in an area separated physically and electrically from the other subsystems to ensure that a single failure in one subsystem does not cause a failure in the other subsystems. There is no sharing between independent Class 1E subsystems, such as batteries, battery chargers, or distribution panels.

Each battery has adequate storage capacity to meet the duty cycle discussed in FSAR, Chapter 8 (Ref. 4). The battery is designed with additional capacity above that required by the design duty cycle to allow for temperature variations and other factors.

The batteries for trains A, B, C, and D DC electrical power subsystems are sized to produce required capacity at 80% of nameplate rating, corresponding to warranted capacity at end of life cycles and the 100% design demand. The minimum design voltage limit is 105 Vdc.

The battery cells are of flooded lead acid construction with a nominal specific gravity of 1.215. This specific gravity corresponds to an open circuit battery voltage of approximately 120 Vdc for a 58 cell battery (i.e., cell voltage of 2.065 volts per cell (Vpc)). The open circuit voltage is the voltage maintained when there is no charging or discharging. Once fully charged with its open circuit voltage ≥ 2.065 Vpc, the battery cell will maintain its capacity for 30 days without further charging per manufacturer's instructions. Optimal long term performance however, is obtained by maintaining a float voltage 2.20 to 2.25 Vpc. This provides adequate over-potential, which limits the formation of lead sulfate and self-discharge. The nominal float voltage of 2.22 Vpc corresponds to a total float voltage output of 128.8 V for a 58 cell battery as discussed in FSAR, Chapter 8 (Ref. 4).

Each battery charger of trains A, B, C, and D DC electrical power subsystems has ample power output capacity for the steady state operation of connected loads required during normal operation, while at the same time maintaining its battery bank fully charged. Each battery charger also has sufficient excess capacity to restore the battery from the design minimum charge to its fully charged state within 24 hours while supplying normal steady state loads discussed in FSAR, Chapter 8 (Ref. 4).
The battery charger is normally in the float-charge mode. Float-charge is the condition in which the charger is supplying the connected loads and the battery cells are receiving adequate current to optimally charge the battery. This assures the internal losses of a battery are overcome and the battery is maintained in a fully charged state.

When desired, the charger can be placed in the equalize mode. The equalize mode is at a higher voltage than the float mode and charging current is correspondingly higher. The battery charger is operated in the equalize mode after a battery discharge or for routine maintenance. Following a battery discharge, the battery recharge characteristic accepts current at the current limit of the battery charger (if the discharge was significant, e.g., following a battery service test) until the battery terminal voltage approaches the charger voltage setpoint. Charging current then reduces exponentially during the remainder of the recharge cycle. Lead-calcium batteries have recharge efficiencies of > 95%, so once at least 105% of the ampere-hours discharged have been returned, the battery capacity would be restored to the same condition as it was prior to the discharge. This can be monitored by direct observation of the exponentially decaying charging current or by evaluating the amp-hours discharged from the battery and amp-hours returned to the battery.

The initial conditions of design basis accident (DBA) and transient analyses in FSAR, Chapter 6 (Ref. 5) and Chapter 15 (Ref. 6), assume that Engineered Safety Feature (ESF) Systems are OPERABLE. The DC Electrical Power System provides normal and emergency DC electrical power for the EDGs, emergency auxiliaries, and control and switching during all MODES of operation.

The OPERABILITY of the DC sources is consistent with the initial assumptions of the accident analyses and is based upon meeting the design basis of the unit. This includes maintaining the DC sources OPERABLE during accident conditions in the event of:

a. An assumed loss of all offsite AC power or all onsite AC power.

b. A worst-case single failure.

The DC sources satisfy Criterion 3 of 10 CFR 50.36(c)(2)(ii).
The DC electrical power subsystems (of trains A, B, C, and D), each subsystem consisting of one battery, two battery chargers (one operating and one standby) and the corresponding control equipment and interconnecting cabling supplying power to the associated bus within the subsystem, are required to be OPERABLE to ensure the availability of the required power to shut down the reactor and maintain it in a safe condition after an anticipated operational occurrence (AOO) or a postulated DBA. Loss of any DC electrical power subsystem does not prevent the minimum safety function from being performed (Ref. 4).

An OPERABLE DC electrical power subsystem requires the battery and associated charger to be operating and connected to the associated DC bus.

The DC electrical power sources are required to be OPERABLE in MODES 1, 2, 3, and 4 to ensure safe unit operation and to ensure that:

a. Acceptable fuel design limits and reactor coolant pressure boundary limits are not exceeded as a result of AOOs or abnormal transients.

b. Adequate core cooling is provided, and containment integrity and other vital functions are maintained in the event of a postulated DBA.

The DC electrical power requirements for MODES 5 and 6 are addressed in the Bases for LCO 3.8.5, “DC Sources – Shutdown.”

Condition A represents one division with one or two battery chargers inoperable (e.g., the voltage limit of SR 3.8.4.1 is not maintained). The ACTIONS provide a tiered response that focuses on returning the battery to the fully charged state and restoring a fully qualified charger to OPERABLE status in a reasonable time period. Required Action A.1 requires that the battery terminal voltage be restored to greater than or equal to the minimum established float voltage within 2 hours. This time provides for returning the inoperable charger to OPERABLE status or providing an alternate means of restoring battery terminal voltage to greater than or equal to the minimum established float voltage. Restoring the battery terminal voltage to greater than or equal to the minimum established float voltage provides good assurance that, within 12 hours, the battery will be restored to its fully charged condition (Required Action A.2) from any discharge that may have occurred due to the charger inoperability.
A discharged battery having terminal voltage of at least the minimum established float voltage indicates that the battery is on the exponential charging current portion (the second part) of its recharge cycle. The time to return a battery to its fully charged state under this condition is simply a function of the amount of the previous discharge and the recharge characteristic of the battery. Thus there is good assurance of fully recharging the battery within 12 hours, avoiding a premature shutdown with its own attendant risk.

If established battery terminal float voltage cannot be restored to greater than or equal to the minimum established float voltage within 2 hours, and the charger is not operating in the current-limiting mode, a faulty charger is indicated. A faulty charger that is incapable of maintaining established battery terminal float voltage does not provide assurance that it can revert to and operate properly in the current limit mode that is necessary during the recovery period following a battery discharge event that the DC System is designed for.

If the charger is operating in the current limit mode after 2 hours that is an indication that the battery is partially discharged and its capacity margins will be reduced. The time to return the battery to its fully charged condition in this case is a function of the battery charger capacity, the amount of loads on the associated DC System, the amount of the previous discharge, and the recharge characteristic of the battery. The charge time can be extensive, and there is not adequate assurance that it can be recharged within 12 hours (Required Action A.2).

Required Action A.2 requires that the battery float current be verified as ≤ 2 amps. This indicates that, if the battery had been discharged as the result of the inoperable battery charger, it is now fully capable of supplying the maximum expected load requirement. The 2 amp value is based on returning the battery to 95% charge and assumes a 5% design margin for the battery. If at the expiration of the initial 12 hour period the battery float current is not ≤ 2 amps this indicates there could be additional battery problems and the battery must be declared inoperable.

Required Action A.3 limits the restoration time for the inoperable battery charger to 72 hours. This action is applicable if an alternate means of restoring battery terminal voltage to greater than or equal to the minimum established float voltage has been used (e.g., balance of plant non-Class 1E battery charger). The 72 hour Completion Time reflects a reasonable time to effect restoration of the qualified battery charger to OPERABLE status.
B.1

Condition B represents one division with one or two batteries inoperable. With one or two batteries inoperable, each associated DC bus is being supplied by its OPERABLE battery charger. Any event that then results in a loss of the AC bus supporting the battery charger will also result in a loss of DC power to the associated DC bus and its supported loads. Recovery of the AC bus, especially if it is due to a loss of offsite power, will be hampered by the fact that many of the components necessary for the recovery (e.g., diesel generator control and field flash, AC load shed and diesel generator output circuit breakers, etc.) likely rely upon the battery. In addition the energization transients of any DC loads that are beyond the capability of the battery charger and normally require the assistance of the battery will not be able to be brought online. The 2 hour limit allows sufficient time to effect restoration of an inoperable battery given that the majority of the conditions that lead to battery inoperability (e.g., loss of battery charger, battery cell voltage < 2.07 V) are identified in Specifications 3.8.4, 3.8.5, and 3.8.6, together with additional specific Completion Times.

C.1

Condition C represents one division with a loss of ability to completely respond to an event, and a potential loss of ability to remain energized during normal operation. It is therefore, imperative that the operator's attention focus on stabilizing the unit, minimizing the potential for complete loss of DC power to the affected division. The 2 hour limit is consistent with the allowed time for an inoperable DC distribution system division.

If one of the required DC electrical power system divisions is inoperable for reasons other than Condition A or B (e.g., inoperable battery charger and associated inoperable battery in one or both trains), the remaining DC electrical power system division has the capacity to support a safe shutdown and to mitigate an accident condition.

Since a subsequent worst case single failure could, however, result in the loss of the minimum necessary DC electrical system divisions to mitigate a worst case accident, continued power operation should not exceed 2 hours. The 2 hour Completion Time is based on NRC RG 1.93 (Ref. 7) and reflects a reasonable time to assess unit status as a function of the inoperable DC electrical power system division and, if the DC electrical power system division is not restored to OPERABLE status, to prepare to effect an orderly and safe unit shutdown.
Bases

Actions (continued)

D.1 and D.2

If the inoperable DC electrical power subsystem cannot be restored to OPERABLE status within the required Completion Time, the unit must be brought to a MODE in which the LCO does not apply. To achieve this status, the unit must be brought to at least MODE 3 within 6 hours, and MODE 5 within 36 hours.

The allowed Completion Times are reasonable, based on operating experience, to reach the required unit conditions from full power conditions in an orderly manner and without challenging plant systems.

The Completion Time to bring the unit to MODE 5 is consistent with the time required in NRC RG 1.93 (Ref. 7).

Surveillance Requirements

SR 3.8.4.1

Verifying battery terminal voltage while on float charge for the batteries helps to ensure the effectiveness of the battery chargers, which support the ability of the batteries to perform their intended function. Float charge is the condition in which the charger is supplying the continuous charge required to overcome the internal losses of a battery and maintain the battery in a fully charged state while supplying the continuous steady state loads of the associated DC subsystem. On float charge, battery cells will receive adequate current to optimally charge the battery. The voltage requirements are based on the nominal design voltage of the battery and are consistent with the minimum float voltage established by the battery manufacturer (2.20 Vpc times the number of connected cells or 127.6 V for a 58 cell battery at the battery terminals). This voltage maintains the battery plates in a condition that supports maintaining the grid life. The 7 day Frequency is consistent with manufacturer recommendations.

SR 3.8.4.2

This SR verifies the design capacity of the battery chargers. According to NRC RG 1.32 (Ref. 8), the battery charger supply is recommended to be based on the largest combined demands of the various steady state loads and the charging capacity to restore the battery from the design minimum charge state to the fully charged state, irrespective of the status of the unit during these demand occurrences. The minimum required amperes and duration ensures that these requirements can be satisfied.
This SR provides two options. One option requires that battery chargers A and B be capable of supplying 700 amps and battery chargers C and D be capable of supplying 1,200 amps at the minimum established float voltage for 8 hours. The ampere requirements are based on the output rating of the chargers. The voltage requirements are based on the charger voltage level after a response to a loss of AC power. The time period is sufficient for the charger temperature to have stabilized and to have been maintained for at least 2 hours.

The other option requires that each battery charger be capable of recharging the battery after a service test coincident with supplying the largest coincident demands of the various continuous steady state loads (irrespective of the status of the plant during which these demands occur). This level of loading may not normally be available following the battery service test and will need to be supplemented with additional loads.

The duration for this test may be longer than the charger sizing criteria since the battery recharge is affected by float voltage, temperature, and the exponential decay in charging current. The battery is recharged when the measured charging current is $\leq 2$ amps.

The 18 month Surveillance Frequency is acceptable, given the unit conditions required to perform the test and the other administrative controls existing to ensure adequate charger performance during these 18 month intervals. In addition, this Frequency is intended to be consistent with expected fuel cycle lengths.

SR 3.8.4.3

A battery service test is a special test of the battery capability, as found, to satisfy the design requirements (battery duty cycle) of the DC Electrical Power System. The discharge rate and test length should correspond to the design duty cycle requirements as specified in Reference 4.

The 18 month Surveillance Frequency is consistent with the recommendations of NRC RG 1.32 (Ref. 8) and NRC RG 1.129 (Ref. 9), which state that the battery service test should be performed during refueling operations, or at some other outage, with intervals between tests not to exceed 18 months.

This SR is modified by two Notes. Note 1 allows the performance of a modified performance discharge test in lieu of a service test.
The reason for Note 2 is that performing the Surveillance would perturb the Electrical Distribution System and challenge safety systems. This restriction from normally performing the Surveillance in MODE 1 or 2 is further amplified to allow portions of the Surveillance to be performed for the purpose of reestablishing OPERABILITY (e.g., post work testing following corrective maintenance, corrective modification, deficient or incomplete surveillance testing, and other unanticipated OPERABILITY concerns) provided an assessment determines plant safety is maintained or enhanced. This assessment shall, as a minimum, consider the potential outcomes and transients associated with a failed partial Surveillance, a successful partial Surveillance, and a perturbation of the offsite or onsite system when they are tied together or operated independently for the partial Surveillance; as well as the operator procedures available to cope with these outcomes. These shall be measured against the avoided risk of a plant shutdown and startup to determine that plant safety is maintained or enhanced when portions of the Surveillance are performed in MODE 1 or 2. Risk insights or deterministic methods may be used for the assessment. Credit may be taken for unplanned events that satisfy this SR.

REFERENCES
1. 10 CFR Part 50, Appendix A, GDC 17.
4. FSAR, Chapter 8.
5. FSAR, Chapter 6.
6. FSAR, Chapter 15.
B 3.8 ELECTRICAL POWER SYSTEMS

B 3.8.5 DC Sources – Shutdown

BASES

BACKGROUND
A description of the direct current (DC) sources is provided in the Bases for LCO 3.8.4, “DC Sources – Operating.”

APPLICABLE SAFETY ANALYSES
The initial conditions of design basis accident (DBA) and transient analyses in FSAR, Chapter 6 (Ref. 1) and Chapter 15 (Ref. 2), assume that Engineered Safety Feature (ESF) Systems are OPERABLE. The DC Electrical Power System provides normal and emergency DC electrical power for the emergency diesel generators (EDGs), emergency auxiliaries, and control and switching during all MODES of operation.

The OPERABILITY of the DC subsystems is consistent with the initial assumptions of the accident analyses and the requirements for the supported systems' OPERABILITY.

The OPERABILITY of the minimum DC electrical power sources during MODES 5 and 6 and during movement of irradiated fuel assemblies ensures that:

a. The unit can be maintained in the shutdown or refueling condition for extended periods.

b. Sufficient instrumentation and control capability is available for monitoring and maintaining the unit status.

c. Adequate DC electrical power is provided to mitigate events postulated during shutdown, such as a fuel handling accident.

In general, when the unit is shut down, the Technical Specifications (TS) requirements ensure that the unit has the capability to mitigate the consequences of postulated accidents. However, assuming a single failure and concurrent loss of all offsite or all onsite power is not required.

The rationale for this is based on the fact that many design basis accidents (DBAs) that are analyzed in MODES 1, 2, 3, and 4 have no specific analyses in MODES 5 and 6 because the energy contained within the reactor pressure boundary, reactor coolant temperature and pressure, and the corresponding stresses result in the probabilities of occurrence being significantly reduced or eliminated, and in minimal consequences.
APPLICABLE SAFETY ANALYSES (continued)

These deviations from DBA analysis assumptions and design requirements during shutdown conditions are allowed by the LCO for required systems.

The shutdown TS requirements are designed to ensure that the unit has the capability to mitigate the consequences of certain postulated accidents. Worst case DBAs which are analyzed for operating MODES are generally viewed not to be a significant concern during shutdown MODES due to the lower energies involved. The TS therefore require a lesser complement of electrical equipment to be available during shutdown than is required during operating MODES. More recent work completed on the potential risks associated with shutdown, however, has found significant risk associated with certain shutdown evolutions. As a result, in addition to the requirements established in the TS, the industry has adopted NUMARC 91-06, “Guidelines for Industry Actions to Assess Shutdown Management,” as an Industry initiative to manage shutdown tasks and associated electrical support to maintain risk at an acceptable low level. This could require the availability of additional equipment beyond that required by the shutdown TS.

The DC sources satisfy Criterion 3 of 10 CFR 50.36(c)(2)(ii).

**LCO**

The DC electrical power subsystems (of trains A, B, C, and D), each required subsystem consisting of one battery, two battery chargers (one operating and one standby), and the corresponding control equipment and interconnecting cabling within the subsystem, are required to be OPERABLE to support one subsystem of distribution systems required OPERABLE by LCO 3.8.10, “Distribution Systems – Shutdown.” This ensures the availability of sufficient DC electrical power sources to operate the unit in a safe manner and to mitigate the consequences of postulated events during shutdown (e.g., fuel handling accidents).

**APPLICABILITY**

The DC electrical power sources required to be OPERABLE in MODES 5 and 6, and during movement of irradiated fuel assemblies provide assurance that:

a. Required features needed to mitigate a fuel handling accident are available.

b. Required features necessary to mitigate the effects of events that can lead to core damage during shutdown are available.
BASES

APPLICABILITY (continued)

c. Instrumentation and control capability is available for monitoring and maintaining the unit in a cold shutdown condition or refueling condition.

The DC electrical power requirements for MODES 1, 2, 3, and 4 are covered in LCO 3.8.4.

ACTIONS

LCO 3.0.3 is not applicable while in MODE 5 or 6. However, since irradiated fuel assembly movement can occur in MODE 1, 2, 3, or 4, the ACTIONS have been modified by a Note stating that LCO 3.0.3 is not applicable. If moving irradiated fuel assemblies while in MODE 5 or 6, LCO 3.0.3 would not specify any action. If moving irradiated fuel assemblies while in MODE 1, 2, 3, or 4, the fuel movement is independent of reactor operations. Entering LCO 3.0.3, while in MODE 1, 2, 3, or 4 would require the unit to be shutdown unnecessarily.

A.1, A.2 and A.3

Condition A represents one subsystem with one or two battery chargers inoperable (e.g., the voltage limit of SR 3.8.4.1 is not maintained). The ACTIONS provide a tiered response that focuses on returning the battery to the fully charged state and restoring a fully qualified charger to OPERABLE status in a reasonable time period. Required Action A.1 requires that the battery terminal voltage be restored to greater than or equal to the minimum established float voltage within 2 hours. This time provides for returning the inoperable charger to OPERABLE status or providing an alternate means of restoring battery terminal voltage to greater than or equal to the minimum established float voltage. Restoring the battery terminal voltage to greater than or equal to the minimum established float voltage provides good assurance that, within 12 hours, the battery will be restored to its fully charged condition (Required Action A.2) from any discharge that may have occurred due to the charger inoperability.

A discharged battery having terminal voltage of at least the minimum established float voltage indicates that the battery is on the exponential charging current portion (the second part) of its recharge cycle. The time to return a battery to its fully charged state under this condition is simply a function of the amount of the previous discharge and the recharge characteristic of the battery. Thus there is good assurance of fully recharging the battery within 12 hours, avoiding a premature shutdown with its own attendant risk.
Bases

Actions (continued)

If established battery terminal float voltage cannot be restored to greater than or equal to the minimum established float voltage within 2 hours, and the charger is not operating in the current-limiting modes, a faulty charger is indicated. A faulty charger that is incapable of maintaining established battery terminal float voltage does not provide assurance that it can revert to and operate properly in the current limit modes that is necessary during the recovery period following a battery discharge event that the DC System is designed for.

If the charger is operating in the current limit mode after 2 hours that is an indication that the battery is partially discharged and its capacity margins will be reduced. The time to return the battery to its fully charged condition in this case is a function of the battery charger capacity, the amount of loads on the associated DC System, the amount of the previous discharge, and the recharge characteristic of the battery. The charge time can be extensive, and there is not adequate assurance that it can be recharged within 12 hours (Required Action A.2).

Required Action A.2 requires that the battery float current be verified as \( \leq 2 \) amps. This indicates that, if the battery had been discharged as the result of the inoperative battery charger, it has now been fully recharged. If at the expiration of the initial 12 hour period the battery float current is not \( \leq 2 \) amps this indicates there could be additional battery problems and the battery must be declared inoperative.

Required Action A.3 limits the restoration time for the inoperative battery charger to 72 hours. This action is applicable if an alternate means of restoring battery terminal voltage to greater than or equal to the minimum established float voltage has been used (e.g., balance of plant non-Class 1E battery charger). The 72 hour Completion Time reflects a reasonable time to effect restoration of the qualified battery charger to OPERABLE status.

B.1, B.2.1, B.2.2, and B.2.3

If two subsystems are required by LCO 3.8.10, the remaining subsystem with DC power available could be capable of supporting sufficient systems to allow continuation of irradiated fuel movement. By allowing the option to declare required features inoperative with the associated DC power source(s) inoperative, appropriate restrictions will be implemented in accordance with the affected required features LCO ACTIONS. In many instances, this option can involve undesired administrative efforts.
Therefore, the allowance for sufficiently conservative actions is made (i.e., to suspend movement of irradiated fuel assemblies, and operations involving positive reactivity additions) that could result in loss of required SDM (MODE 5) or boron concentration (MODE 6).

Suspending positive reactivity additions that could result in failure to meet the minimum SDM or boron concentration limit is required to assure continued safety operation. Introduction of coolant inventory must be from sources that have a boron concentration greater than that what would be required in the Reactor Coolant System (RCS) for minimum SDM or refueling boron concentration. This could result in an overall reduction in RCS boron concentration, but provides acceptable margin to maintaining subcritical operation. Introduction of temperature changes including temperature increases when operating with a positive moderator temperature coefficient (MTC) must also be evaluated to ensure they do not result in a loss of required SDM.

Suspension of these activities shall not preclude completion of actions to establish a safe conservative condition. These actions minimize probability of the occurrence of postulated events. It is further required to immediately initiate action to restore the required DC electrical power subsystems and to continue this action until restoration is accomplished in order to provide the necessary DC electrical power to the unit safety systems.

The Completion Time of immediately is consistent with the required times for actions requiring prompt attention. The restoration of the required DC electrical power subsystems should be completed as quickly as possible in order to minimize the time during which the unit safety systems are without sufficient power.

SR 3.8.5.1 states that Surveillances required by SR 3.8.4.1 through SR 3.8.4.3 are applicable in these MODES. See the corresponding Bases for LCO 3.8.4 for a discussion of each SR.

This SR is modified by a Note. The reason for the Note is to preclude requiring the OPERABLE DC sources from being discharged below their capability to provide the required power supply or otherwise rendered inoperable during the performance of SRs. It is the intent that these SRs must still be capable of being met, but actual performance is not required.
REFERENCES

1. FSAR, Chapter 6.

2. FSAR, Chapter 15.
B 3.8 ELECTRICAL POWER SYSTEMS

B 3.8.6 Battery Cell Parameters

BASES

BACKGROUND

This LCO delineates the limits on battery float current as well as electrolyte temperature, level, and float voltage for the direct current (DC) power subsystem batteries. A discussion of these batteries and their OPERABILITY requirements is provided in the Bases for LCO 3.8.4, “DC Sources – Operating,” and LCO 3.8.5, “DC Sources – Shutdown.” In addition to the limitations of this Specification, the licensee controlled program also implements a program specified in Specification 5.5.17 for monitoring various battery parameters.

The battery cells are of flooded lead acid construction with a nominal specific gravity of 1.215. This specific gravity corresponds to an open circuit battery voltage of approximately 120 V for 58 cell battery (i.e., cell voltage of 2.065 volts per cell (Vpc)). The open circuit voltage is the voltage maintained when there is no charging or discharging. Once fully charged with its open circuit voltage \( \geq 2.065 \text{ Vpc} \), the battery cell will maintain its capacity for 30 days without further charging per manufacturer's instructions. Optimal long term performance however, is obtained by maintaining a float voltage 2.20 to 2.25 Vpc. This provides adequate over-potential which limits the formation of lead sulfate and self-discharge. The nominal float voltage of 2.22 Vpc corresponds to a total float voltage output of 128.8 V for a 58 cell battery as discussed in FSAR, Chapter 8 (Ref. 1).

APPLICABLE

SAFETY

ANALYSES

The initial conditions of design basis accident (DBA) and transient analyses in FSAR, Chapter 6 (Ref. 2) and Chapter 15 (Ref. 3), assume Engineered Safety Feature Systems are OPERABLE. The DC Electrical Power System provides normal and emergency DC electrical power for the EDGs, emergency auxiliaries, and control and switching during all MODES of operation.

The OPERABILITY of the DC subsystems is consistent with the initial assumptions of the accident analyses and is based upon meeting the design basis of the unit.

This includes maintaining at least one subsystem of DC sources OPERABLE during accident conditions, in the event of:

a. An assumed loss of all offsite AC power or all onsite AC power and
b. A worst-case single failure.
Battery cell parameters satisfy Criterion 3 of 10 CFR 50.36(c)(2)(ii).

Battery cell parameters must remain within acceptable limits to ensure availability of the required DC power to shut down the reactor and maintain it in a safe condition after an anticipated operational occurrence or a postulated DBA. Battery cell parameter limits are conservatively established, allowing continued DC Electrical System function even with limits not met. Additional preventative maintenance, testing, and monitoring performed in accordance with the licensee controlled program is conducted as specified in Specification 5.5.17.

The battery cell parameters are required solely for the support of the associated DC electrical power subsystems. Therefore, battery cell parameter limits are only required when the DC power source is required to be OPERABLE. Refer to the Applicability discussion in Bases for LCO 3.8.4 and LCO 3.8.5.

With one or more cells in one or more batteries in one subsystem < 2.07 V, the battery cell is degraded. Within 2 hours verification of the required battery charger OPERABILITY is made by monitoring the battery terminal voltage (SR 3.8.4.1) and of the overall battery state of charge by monitoring the battery float charge current (SR 3.8.6.1). This assures that there is still sufficient battery capacity to perform the intended function. Therefore, the affected battery is not required to be considered inoperable solely as a result of one or more cells in one or more batteries < 2.07 V and continued operation is permitted for a limited period up to 24 hours.

Since the Required Actions only specify “perform,” a failure of SR 3.8.4.1 or SR 3.8.6.1 acceptance criteria does not result in this Required Action not met. However, if one of the SRs is failed the appropriate Condition(s), depending on the cause of the failures, is entered. If SR 3.8.6.1 is failed then there is no assurance that there is still sufficient battery capacity to perform the intended function and the battery must be declared inoperable immediately.
One or more batteries in one division with float current > 2 amps indicate that a partial discharge of the battery capacity has occurred. This could be due to a temporary loss of a battery charger or possibly due to one or more battery cells in a low voltage condition reflecting some loss of capacity. Within 2 hours verification of the required battery charger OPERABILITY is made by monitoring the battery terminal voltage. If the terminal voltage is found to be less than the minimum established float voltage there are two possibilities, the battery charger is inoperable or is operating in the current limit mode. Condition A addresses charger inoperability. If the charger is operating in the current limit mode after 2 hours that is an indication that the battery has been substantially discharged and likely cannot perform its required design functions. The time to return the battery to its fully charged condition in this case is a function of the battery charger capacity, the amount of loads on the associated DC System, the amount of the previous discharge, and the recharge characteristic of the battery. The charge time can be extensive, and there is not adequate assurance that it can be recharged within 12 hours (Required Action B.2). The battery must therefore be declared inoperable.

If the float voltage is found to be satisfactory but there are one or more battery cells with float voltage < 2.07 V, the associated "OR" statement in Condition F is applicable and the battery must be declared inoperable immediately. If float voltage is satisfactory and there are no cells < 2.07 V there is good assurance that, within 12 hours, the battery will be restored to its fully charged condition (Required Action B.2) from any discharge that may have occurred due to a temporary loss of the battery charger.

A discharged battery with float voltage (the charger setpoint) across its terminals indicates that the battery is on the exponential charging current portion (the second part) of its recharge cycle. The time to return a battery to its fully charged state under this condition is simply a function of the amount of the previous discharge and the recharge characteristic of the battery. Thus there is good assurance of fully recharging the battery within 12 hours, avoiding a premature shutdown with its own attendant risk.

If the condition is due to one or more cells in a low voltage condition but still > 2.07 V and float voltage is found to be satisfactory, this is not indication of a substantially discharged battery and 12 hours is a reasonable time prior to declaring the battery inoperable.
Since Required Action B.1 only specifies “perform,” a failure of SR 3.8.4.1 acceptance criteria does not result in the Required Action not met. However, if SR 3.8.4.1 is failed, the appropriate Condition(s), depending on the cause of the failure, is entered.

C.1, C.2 and C.3

With one or more batteries in one division with one or more cells with electrolyte level above the top of the plates, but below the minimum established design limits, the battery still retains sufficient capacity to perform the intended function. Therefore, the affected battery is not required to be considered inoperable solely as a result of electrolyte level not met. Within 31 days, the minimum established design limits for electrolyte level must be re-established.

With electrolyte level below the top of the plates there is a potential for dryout and plate degradation. Required Actions C.1 and C.2 address this potential (as well as provisions in Specification 5.5.17, Battery Monitoring and Maintenance Program). They are modified by a Note that indicates they are only applicable if electrolyte level is below the top of the plates. Within 8 hours, level is required to be restored to above the top of the plates. The Required Action C.2 requirement to verify that there is no leakage by visual inspection and the Specification 5.5.17.b item to initiate action to equalize and test in accordance with manufacturer's recommendation are taken from IEEE Std. 450 (Ref. 4).

They are performed following the restoration of the electrolyte level to above the top of the plates. Based on the results of the manufacturer's recommended testing, the batteries may have to be declared inoperable and the affected cells replaced.

D.1

With one or more batteries in one division with pilot cell temperature less than the minimum established design limits, 12 hours is allowed to restore the temperature to within limits. A low electrolyte temperature limits the current and power available. Since the battery is sized with margin, while battery capacity is degraded, sufficient capacity exists to perform the intended function and the affected battery is not required to be considered inoperable solely as a result of the pilot cell temperature not met.
B BASES

ACTIONS (continued)

E.1

With one or more batteries in redundant divisions with battery parameters not within limits there is not sufficient assurance that battery capacity has not been affected to the degree that the batteries can still perform their required function, given that redundant batteries are involved. With redundant batteries involved this potential could result in a total loss of function on multiple systems that rely upon the batteries. The longer Completion Times specified for battery cell parameters on non-redundant batteries not within limits are therefore not appropriate, and the parameters must be restored to within limits on both trains of one division within 2 hours.

F.1

With one or more batteries with any battery cell parameter outside the allowances of the Required Actions for Condition A, B, C, D, or E, sufficient capacity to supply the maximum expected load requirement is not assured and the corresponding battery must be declared inoperable. Additionally, discovering one or more batteries in one division with float current > 2 amps, and with one or more battery cells with float voltage < 2.07 V indicates that the battery capacity might not be sufficient to perform the intended functions. The battery must therefore be declared inoperable immediately.

S SURVEILLANCE REQUIREMENTS

SR 3.8.6.1

Verifying battery float current while on float charge is used to determine the state of charge of the battery. Float charge is the condition in which the charger is supplying the continuous charge required to overcome the internal losses of a battery and maintain the battery in a charged state. The float current requirements are based on the float current indicative of a charged battery. Use of float current to determine the state of charge of the battery is consistent with IEEE Std. 450 (Ref. 4). The 7 day Frequency is consistent with IEEE Std. 450 (Ref. 4).

This SR is modified by a Note that states the float current requirement is not required to be met when battery terminal voltage is less than the minimum established float voltage of SR 3.8.4.1. When this float voltage is not maintained the Required Actions of LCO 3.8.4 ACTION A are being taken, which provide the necessary and appropriate verifications of the battery condition. Furthermore, the float current limit of 2 amps is established based on the nominal float voltage value and is not directly applicable when this voltage is not maintained.
SURVEILLANCE REQUIREMENTS (continued)

SR 3.8.6.2 and SR 3.8.6.5

Optimal long term battery performance is obtained by maintaining a float voltage greater than or equal to the minimum established design limits provided by the battery manufacturer, which corresponds to 130.5 V at the battery terminals, or 2.25 Vpc. This provides adequate over-potential, which limits the formation of lead sulfate and self-discharge, which could eventually render the battery inoperable. Float voltages in this range or less, but > 2.07 Vpc, are addressed in Specification 5.5.17. SRs 3.8.6.2 and 3.8.6.5 require verification that the cell float voltages are equal to or greater than the short term absolute minimum voltage of 2.07 V. The Frequency for cell voltage verification every 31 days for pilot cell and 92 days for each connected cell is consistent with IEEE Std. 450 (Ref. 4).

SR 3.8.6.3

The limit specified for electrolyte level ensures that the plates suffer no physical damage and maintains adequate electron transfer capability. The 31 day Frequency is consistent with IEEE Std. 450 (Ref. 4).

SR 3.8.6.4

This Surveillance verifies that the pilot cell temperature is greater than or equal to the minimum established design limit (i.e., 7.2°C (45°F)). Pilot cell electrolyte temperature is maintained above this temperature to assure the battery can provide the required current and voltage to meet the design requirements. Temperatures lower than assumed in battery sizing calculations act to inhibit or reduce battery capacity. The 31 day Frequency is consistent with IEEE Std. 450 (Ref. 4).

SR 3.8.6.6

A battery performance discharge test is a test of constant current capacity of a battery, normally done in the as-found condition, after having been in service, to detect any change in the capacity determined by the acceptance test. The test is intended to determine overall battery degradation due to age and usage.

Either the battery performance discharge test or the modified performance discharge test is acceptable for satisfying SR 3.8.6.6; however, only the modified performance discharge test may be used to satisfy the battery service test requirements of SR 3.8.4.3.
SURVEILLANCE REQUIREMENTS (continued)

A modified discharge test is a test of the battery capacity and its ability to provide a high rate, short duration load (usually the highest rate of the duty cycle). This will often confirm the battery’s ability to meet the critical period of the load duty cycle, in addition to determining its percentage of rated capacity. Initial conditions for the modified performance discharge test should be identical to those specified for a service test.

It may consist of just two rates; for instance the one minute rate for the battery or the largest current load of the duty cycle, followed by the test rate employed for the performance test, both of which envelope the duty cycle of the service test. Since the ampere-hours removed by a one minute discharge represents a very small portion of the battery capacity, the test rate can be changed to that for the performance test without compromising the results of the performance discharge test. The battery terminal voltage for the modified performance discharge test must remain above the minimum battery terminal voltage specified in the battery service test for the duration of time equal to that of the service test.

The acceptance criteria for this Surveillance are consistent with IEEE Std. 450 (Ref. 4) and IEEE Std. 485 (Ref. 5). These references recommend that the battery be replaced if its capacity is below 80% of the manufacturer's rating. A capacity of 80% shows that the battery rate of deterioration is increasing, even if there is ample capacity to meet the load requirements. Furthermore, the battery is sized to meet the assumed duty cycle loads when the battery design capacity reaches this 80% limit.

The Surveillance Frequency for this test is normally 60 months.

If the battery shows degradation, or if the battery has reached 85% of its expected life and capacity is < 100% of the manufacturer's rating, the Surveillance Frequency is reduced to 12 months. However, if the battery shows no degradation but has reached 85% of its expected life, the Surveillance Frequency is only reduced to 24 months for batteries that retain capacity ≥ 100% of the manufacturer's ratings. Degradation is indicated, according to IEEE Std. 450 (Ref. 4), when the battery capacity drops by more than 10% relative to its capacity on the previous performance test or when it is ≥ 10% below the manufacturer's rating. These Frequencies are consistent with the recommendations in IEEE Std. 450 (Ref. 4).
This SR is modified by a Note. The reason for the Note is that performing the Surveillance would perturb the electrical distribution system and challenge safety systems. This restriction from normally performing the Surveillance in MODE 1, 2, 3, or 4 is further amplified to allow portions of the Surveillance to be performed for the purpose of reestablishing OPERABILITY (e.g., post work testing following corrective maintenance, corrective modification, deficient or incomplete surveillance testing, and other unanticipated OPERABILITY concerns) provided an assessment determines plant safety is maintained or enhanced. This assessment shall, as a minimum, consider the potential outcomes and transients associated with a failed partial Surveillance, a successful partial Surveillance, and a perturbation of the offsite or onsite system when they are tied together or operated independently for the partial Surveillance; as well as the operator procedures available to cope with these outcomes. These shall be measured against the avoided risk of a plant shutdown and startup to determine that plant safety is maintained or enhanced when portions of the Surveillance are performed in MODE 1 or 2. Risk insights or deterministic methods may be used for the assessment. Credit may be taken for unplanned events that satisfy this SR.

REFERENCES

1. FSAR, Chapter 8.
2. FSAR, Chapter 6.
3. FSAR, Chapter 15.
B 3.8 ELECTRICAL POWER SYSTEMS

B 3.8.7 Inverters – Operating

BASES

BACKGROUND

The inverters are the preferred source of power for the AC vital buses because of the stability and reliability they achieve. The function of the inverter is to provide AC electrical power to the vital buses. The inverters can be powered from a rectifier or from the station battery. The station battery provides an uninterruptible power source for the instrumentation and controls for the Reactor Protection System (RPS) and the Engineered Safety Feature Actuation System (ESFAS). Specific details on inverters and their operating characteristics are found in FSAR, Chapter 8 (Ref. 1).

APPLICABLE SAFETY ANALYSES

The initial conditions of design basis accident (DBA) and transient analyses in FSAR, Chapter 6 (Ref. 2) and Chapter 15 (Ref. 3) assume Engineered Safety Feature Systems are OPERABLE. The inverters are designed to provide the required capacity, capability, redundancy, and reliability to ensure the availability of necessary power to the RPS and ESFAS instrumentation and controls so that the fuel, Reactor Coolant System, and containment design limits are not exceeded. These limits are discussed in more detail in the Bases for LCOs of Sections 3.2, “Power Distribution Limits,” 3.4, “Reactor Coolant System (RCS),” and 3.6, “Containment Systems.”

The OPERABILITY of the inverters is consistent with the initial assumptions of the accident analyses and is based on meeting the design basis of the unit. This includes maintaining required alternating current (AC) vital buses OPERABLE during accident conditions in the event of:

a. An assumed loss of all offsite AC electrical power or all onsite AC electrical power and

b. A worst case single failure.

Inverters are a part of the distribution system and, as such, satisfy Criterion 3 of 10 CFR 50.36(c)(2)(ii).

LCO

The inverters ensure the availability of AC electrical power for the systems instrumentation required to shut down the reactor and maintain it in a safe condition after an anticipated operational occurrence (AOO) or a postulated DBA.
Maintaining the required inverters OPERABLE ensures that the redundancy incorporated into the design of the RPS and ESFAS instrumentation and controls is maintained. The four battery powered inverters (two per division) ensure an uninterruptible supply of AC electrical power to the AC vital buses even if the 4.16 kV Class 1E buses (ESF buses) are de-energized.

OPERABLE inverters require the associated vital bus to be powered by the inverter with output voltage and frequency within tolerances, and power input to the inverter from a 125 Vdc station battery.

This LCO is modified by a Note that allows one inverter to be disconnected from a battery for ≤ 24 hour, if the vital bus is powered from a Class 1E regulating transformer during the period and all other inverters are OPERABLE. This allows an equalizing charge to be placed on one battery. Were the inverter not disconnected, the resulting voltage condition might damage the inverter. These provisions minimize the loss of equipment that would occur in the event of a loss of offsite power. The 24 hour time period for the allowance minimizes the time during which a loss of offsite power could result in the loss of equipment energized from the affected AC vital bus while taking into consideration the time required to perform an equalizing charge on the battery bank.

The intent of this Note is to limit the number of inverters that may be disconnected. Only the inverter associated with the single battery undergoing an equalizing charge may be disconnected. All other inverters must be aligned to their associated batteries.

The inverters are required to be OPERABLE in MODES 1, 2, 3, and 4 to ensure that:

a. Acceptable fuel design limits and reactor coolant pressure boundary limits are not exceeded as a result of AOOs or abnormal transients.

b. Adequate core cooling is provided and containment OPERABILITY and other vital functions are maintained in the event of a postulated DBA.

Inverter requirements for MODES 5 and 6 are covered in the Bases for LCO 3.8.8, “Inverters – Shutdown.”
With a required inverter inoperable, its associated AC vital bus becomes inoperable until it is re-energized from its Class 1E regulating transformer.

Required Action A.1 is modified by a Note, which states to enter the applicable conditions and Required Actions of LCO 3.8.9, “Distribution Systems – Operating,” when Condition A is entered with one AC vital bus de-energized. This ensures the bus is re-energized within 2 hours.

Required Action A.1 allows 24 hours to fix the inoperable inverter and return it to service. The 24 hour limit is based upon Nuclear Regulatory Commission (NRC) Regulatory Guide (RG) 1.93 (Ref. 4), taking into consideration the time required to repair an inverter and the additional risk to which the unit is exposed because of the inverter inoperability. This has to be balanced against the risk of an immediate shutdown, along with the potential challenges to safety systems such a shutdown may entail. When the AC vital bus is powered from its regulating transformer, it is relying upon interruptible AC electrical power sources (offsite and onsite). The uninterruptible inverter source to the AC vital buses is the preferred source for powering instrumentation trip setpoint devices.

If the inoperable devices or components cannot be restored to OPERABLE status within the required Completion Time, the unit must be brought to a MODE in which the LCO does not apply. To achieve this status, the unit must be brought to at least MODE 3 within 6 hours, and MODE 5 within 36 hours.

The allowed Completion Times are reasonable, based on operating experience, to reach the required unit conditions from full power conditions in an orderly manner and without challenging unit systems.

This Surveillance verifies that the inverters are functioning properly with all required circuit breakers closed and AC vital buses energized from the inverter. The verification of proper voltage and frequency output ensures that the required power is readily available for the instrumentation of the RPS and ESFAS connected to the AC vital buses. The 7 day Frequency takes into account the redundant capability of the inverters and other indications available in the main control room (MCR) that alert the operator to inverter malfunctions.
BASES

REFERENCES

1. FSAR, Chapter 8.

2. FSAR, Chapter 6.

3. FSAR, Chapter 15.

B 3.8 ELECTRICAL POWER SYSTEMS

B 3.8.8 Inverters – Shutdown

BASES

BACKGROUND

A description of the inverters is provided in the Bases for LCO 3.8.7, “Inverters – Operating.”

APPLICABLE SAFETY ANALYSES

The initial conditions of design basis accident (DBA) and transient analyses in FSAR, Chapter 6 (Ref. 1) and Chapter 15 (Ref. 2), assume Engineered Safety Feature Systems are OPERABLE. The direct current (DC) to alternating current (AC) inverters are designed to provide the required capacity, capability, redundancy, and reliability to ensure the availability of necessary power to the Reactor Protection System and Engineered Safety Features Actuation System instrumentation and controls so that the fuel, Reactor Coolant System, and containment design limits are not exceeded.

The OPERABILITY of the inverters is consistent with the initial assumptions of the accident analyses and the requirements for the supported systems' OPERABILITY.

The OPERABILITY of the minimum inverters to each AC vital bus during MODES 5 and 6 ensures that:

a. The unit can be maintained in the shutdown or refueling condition for extended periods.

b. Sufficient instrumentation and control capability is available for monitoring and maintaining the unit status.

c. Adequate power is available to mitigate events postulated during shutdown, such as a fuel handling accident.

In general, when the unit is shut down, the Technical Specification (TS) requirements ensure that the unit has the capability to mitigate the consequences of postulated accidents. However, assuming a single failure and concurrent loss of all offsite or all onsite power is not required. The rationale for this is based on the fact that many DBAs that are analyzed in MODES 1, 2, 3, and 4 have no specific analyses in MODES 5 and 6 because the energy contained within the reactor pressure boundary, reactor coolant temperature and pressure, and the corresponding stresses result in the probabilities of occurrence being significantly reduced or eliminated, and in minimal consequences.
These deviations from DBA analysis assumptions and design requirements during shutdown conditions are allowed by the LCO for required systems.

The shutdown TS requirements are designed to ensure that the unit has the capability to mitigate the consequences of certain postulated accidents. Worst case DBAs which are analyzed for operating MODES are generally viewed not to be a significant concern during shutdown MODES due to the lower energies involved. The TS therefore require a lesser complement of electrical equipment to be available during shutdown than is required during operating MODES. More recent work completed on the potential risks associated with shutdown, however, has found significant risk associated with certain shutdown evolutions. As a result, in addition to the requirements established in the TS, the industry has adopted NUMARC 91-06, “Guidelines for Industry Actions to Assess Shutdown Management,” as an Industry initiative to manage shutdown tasks and associated electrical support to maintain risk at an acceptable low level. This could require the availability of additional equipment beyond that required by the shutdown TS.

The inverters were previously identified as part of the distribution system and, as such, satisfy Criterion 3 of 10 CFR 50.36(c)(2)(ii).

The inverters ensure the availability of electrical power for the instrumentation for systems required to shut down the reactor and maintain it in a safe condition after an anticipated operational occurrence or a postulated DBA. The battery powered inverters provide uninterruptible supply of AC electrical power to the AC vital buses even if the 4.16 kV Class 1E buses (ESF buses) are de-energized. OPERABILITY of the inverters requires that the vital bus be powered by the inverter. This ensures the availability of sufficient inverter power sources to operate the unit in a safe manner and to mitigate the consequences of postulated events during shutdown (e.g., fuel handling accidents).

The inverters are required to be OPERABLE in MODES 5 and 6, and during movement of irradiated fuel assemblies provide assurance that:

a. Systems to provide adequate coolant inventory makeup are available for the irradiated fuel in the core.

b. Systems needed to mitigate a fuel handling accident are available.
Inverters – Shutdown

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BASSES

APPLICABILITY (continued)

c. Systems necessary to mitigate the effects of events that can lead to core damage during shutdown are available.

d. Instrumentation and control capability is available for monitoring and maintaining the unit in a cold shutdown condition or refueling condition.

Inverter requirements for MODES 1, 2, 3, and 4 are covered in LCO 3.8.7.

ACTIONS

LCO 3.0.3 is not applicable while in MODE 5 or 6. However, since irradiated fuel assembly movement can occur in MODE 1, 2, 3, or 4, the ACTIONS have been modified by a Note stating that LCO 3.0.3 is not applicable. If moving irradiated fuel assemblies while in MODE 5 or 6, LCO 3.0.3 would not specify any action. If moving irradiated fuel assemblies while in MODE 1, 2, 3, or 4, the fuel movement is independent of reactor operations. Entering LCO 3.0.3, while in MODE 1, 2, 3, or 4 would require the unit to be shutdown unnecessarily.

A.1, A.2.1, A.2.2, and A.2.3

If two divisions are required by LCO 3.8.10, “Distribution Systems – Shutdown,” the remaining OPERABLE inverters may be capable of supporting sufficient required features to allow continuation of irradiated fuel movement, operations with a potential for draining the reactor vessel, and operations with a potential for positive reactivity additions. By the allowance of the option to declare required features inoperable with the associated inverter(s) inoperable, appropriate restrictions will be implemented in accordance with the affected required features LCO ACTIONS. In many instances, this option can involve undesired administrative efforts. Therefore, the allowance for sufficiently conservative actions is made (i.e., to suspend, movement of irradiated fuel assemblies, and operations involving positive reactivity additions) that could result in loss of required SDM (MODE 5) or boron concentration (MODE 6). Suspending positive reactivity additions that could result in failure to meet the minimum SDM or boron concentration limit is required to assure continued safe operation. Introduction of coolant inventory must be from sources that have a boron concentration greater than that what would be required in the Reactor Coolant System (RCS) for minimum SDM or refueling boron concentration. This could result in an overall reduction in RCS boron concentration, but provides acceptable margin to maintaining subcritical operation. Introduction of temperature changes including temperature increases when operating with a positive

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BASES

ACTIONS (continued)

moderator temperature coefficient (MTC) must also be evaluated to ensure they do not result in a loss of required SDM.

Suspension of these activities shall not preclude completion of actions to establish a safe conservative condition. These actions minimize the probability of the occurrence of postulated events. It is further required to immediately initiate action to restore the required inverters and to continue this action until restoration is accomplished in order to provide the necessary inverter power to the unit safety systems.

The Completion Time of immediately is consistent with the required times for actions requiring prompt attention. The restoration of the required inverters should be completed as quickly as possible in order to minimize the time the unit safety systems are without power or are powered from a regulating transformer.

SURVEILLANCE REQUIREMENTS

SR 3.8.8.1

This Surveillance verifies that the inverters are functioning properly with all required circuit breakers closed and AC vital buses energized from the inverter. The verification of proper voltage and frequency output ensures that the required power is readily available for the instrumentation connected to the AC vital buses. The 7 day Frequency takes into account the redundant capability of the inverters and other indications available in the main control room that alert the operator to inverter malfunctions.

REFERENCES

1. FSAR, Chapter 6.
2. FSAR, Chapter 15.
B 3.8 ELECTRICAL POWER SYSTEMS

B 3.8.9 Distribution Systems – Operating

BASES

BACKGROUND

The Onsite Class 1E alternating current (AC), direct current (DC), and AC Vital Bus Electrical Power Distribution Systems are divided into two redundant load groups (division I and division II) with four independent AC, DC, and AC vital bus electrical power distribution subsystems: train A and train C for division I; and train B and train D for division II.

The AC electrical power subsystem for each train consists of a Class 1E 4.16 kV bus (ESF bus), having at least one separate and independent offsite source of power as well as a dedicated onsite emergency diesel generator (EDG) source. Each ESF bus is normally connected to a preferred offsite source. After a loss of the preferred offsite power source to an ESF bus, a transfer to the alternate offsite source is accomplished by using a time delayed bus undervoltage relay. If all offsite sources are unavailable, the onsite EDG supplies power to the ESF bus. Control power for the 4.16 kV breakers is supplied from the Class 1E batteries. Additional description of this system can be found in the Bases for LCO 3.8.1, “AC Sources – Operating,” and the Bases for LCO 3.8.4, “DC Sources – Operating.”

The secondary safety-related AC electrical power distribution subsystem for each train includes one 480 Vac load center and four 480 Vac motor control centers, as shown in Table B 3.8.9-1.

One AC vital bus is provided for each train of the safety-related AC vital bus electrical power distribution subsystem. Each 120 Vac vital bus is normally powered from its respective inverter. The alternate power supply for each AC vital bus is its Class 1E regulating transformer, which is powered from the same train as the associated inverter, and its use is governed by LCO 3.8.7, “Inverters – Operating.” Each regulating transformer is powered from its Class 1E AC bus.

Each train of the 125 Vdc safety-related DC electrical power distribution subsystem consists of one DC safety bus, as shown in Table B 3.8.9-1.
The initial conditions of design basis accident (DBA) and transient analyses in FSAR, Chapters 6 (Ref. 1) and Chapter 15 (Ref. 2), assume ESF Systems are OPERABLE. The AC, DC, and AC Vital Bus Electrical Power Distribution Systems are designed to provide sufficient capacity, capability, redundancy, and reliability to ensure the availability of necessary power to ESF Systems so that the fuel, Reactor Coolant System, and containment design limits are not exceeded. These limits are discussed in more detail in the Bases for LCOs 3.2, “Power Distribution Limits,” 3.4, “Reactor Coolant System (RCS),” and 3.6, “Containment Systems.”

The OPERABILITY of the AC, DC, and AC Vital Bus Electrical Power Distribution Systems is consistent with the initial assumptions of the accident analyses and is based upon meeting the design basis of the unit. This includes maintaining power distribution systems OPERABLE during accident conditions in the event of:

a. An assumed loss of all offsite power or all onsite AC electrical power.

b. A worst case single failure.

The distribution systems satisfy Criterion 3 of 10 CFR 50.36(c)(2)(ii).

The required power distribution subsystem listed in Table B 3.8.9-1 ensure the availability of AC, DC, and AC vital bus electrical power for the systems required to shut down the reactor and maintain it in a safe condition after an anticipated operational occurrence (AOO) or a postulated design basis accident (DBA). The AC, DC, and AC vital bus electrical power distribution subsystems are required to be OPERABLE.

Maintaining the division I and division II AC, DC, and AC Vital Bus Electrical Power Distribution Subsystems OPERABLE ensures that the redundancy incorporated into the design of ESF is not defeated. Therefore, a single failure within any system or within the electrical distribution subsystems will not prevent safe shutdown of the reactor.

OPERABLE AC electrical power distribution subsystems require the associated buses, load centers, motor control centers, and distribution panels to be energized to their proper voltages.

OPERABLE DC electrical power distribution subsystems require the associated buses and distribution panels to be energized to their proper voltage from either the associated battery or charger. OPERABLE vital bus electrical power distribution subsystems require the associated buses to be energized to their proper voltage from the associated inverter via inverted DC voltage or Class 1E regulating transformer.
In addition, tie breakers between redundant safety-related AC, DC, and AC vital bus power distribution subsystems, if they exist, must be open. This prevents any electrical malfunction in any power distribution subsystem from propagating to the redundant subsystem, which could cause the failure of a redundant subsystem and a loss of essential safety functions. If any tie breakers are closed, the affected redundant electrical power distribution subsystems are considered inoperable. This applies to the onsite, safety-related redundant electrical power distribution subsystems. It does not, however, preclude redundant ESF buses from being powered from the same offsite circuit.

The electrical power distribution subsystems are required to be OPERABLE in MODES 1, 2, 3, and 4 to ensure that:

a. Acceptable fuel design limits and reactor coolant pressure boundary limits are not exceeded as a result of AOOs or abnormal transients.

b. Adequate core cooling is provided and containment OPERABILITY and other vital functions are maintained in the event of a postulated DBA.

Electrical power distribution subsystem requirements for MODES 5 and 6 are covered in the Bases for LCO 3.8.10, “Distribution Systems – Shutdown.”

With one or more division I and division II required AC buses, load centers, motor control centers, or distribution panels (except AC vital buses), in one division inoperable and a loss of function has not occurred, the remaining AC electrical power distribution subsystems are capable of supporting the minimum safety functions necessary to shut down the reactor and maintain it in a safe shutdown condition, assuming no single failure.

The overall reliability is reduced, however, because a single failure in the remaining power distribution subsystems could result in the minimum required ESF functions not being supported. Therefore, the required AC buses, load centers, motor control centers, and distribution panels must be restored to OPERABLE status within 8 hours.
BASES

ACTIONS (continued)

Condition A worst scenario is one division without AC power (i.e., no offsite power to the division and the associated EDGs inoperable). In this condition, the unit is more vulnerable to a complete loss of AC power. It is, therefore, imperative that the unit operator’s attention be focused on minimizing the potential for loss of power to the remaining division by stabilizing the unit, and on restoring power to the affected division. The 8 hour time limit before requiring a unit shutdown in this condition is acceptable because of:

a. The potential for decreased safety if the unit operator’s attention is diverted from the evaluations and actions necessary to restore power to the affected division, to the actions associated with taking the unit to shut down within this time limit.

b. The potential for an event in conjunction with a single failure of a redundant component in the division with AC power.

Required Action A.1 is modified by a Note that requires the applicable Conditions and Required Actions of LCO 3.8.4, “DC Sources – Operating,” to be entered for DC divisions made inoperable by inoperable power distribution subsystems. This is an exception to LCO 3.0.6 and ensures the proper actions are taken for these components. Inoperability of a distribution system can result in loss of charging power to batteries and eventual loss of DC power. This Note ensures that the appropriate attention is given to restoring charging power to batteries, if necessary, after loss of distribution systems.

B.1

With one or more AC vital buses inoperable, and a loss of function has not yet occurred, the remaining OPERABLE AC vital buses are capable of supporting the minimum safety functions necessary to shut down the unit and maintain it in the safe shutdown condition.

Overall reliability is reduced, however, since an additional single failure could result in the minimum required ESF functions not being supported. Therefore, the required AC vital bus must be restored to OPERABLE status within 2 hours by powering the bus from the associated inverter via inverted DC or Class 1E regulating transformer.
Condition B represents one or more AC vital buses without power; potentially both the DC source and the associated AC source are nonfunctioning. In this situation, the unit is significantly more vulnerable to a complete loss of all noninterruptible power. It is, therefore, imperative that the operator’s attention focus on stabilizing the unit, minimizing the potential for loss of power to the remaining vital buses, and restoring power to the affected vital bus.

This 2 hour limit is more conservative than Completion Times allowed for the vast majority of components that are without adequate vital AC power. Taking exception to LCO 3.0.2 for components without adequate vital AC power, which would have the Required Action Completion Times shorter than 2 hours if declared inoperable, is acceptable because of:

a. The potential for decreased safety by requiring a change in unit conditions (i.e., requiring a shutdown) and not allowing stable operations to continue.

b. The potential for decreased safety by requiring entry into numerous applicable Conditions and Required Actions for components without adequate vital AC power and not providing sufficient time for the operators to perform the necessary evaluations and actions for restoring power to the affected division.

c. The potential for an event in conjunction with a single failure of a redundant component.

The 2 hour Completion Time takes into account the importance to safety of restoring the AC vital bus to OPERABLE status, the redundant capability afforded by the other OPERABLE vital buses, and the low probability of a DBA occurring during this period.

C.1

With one or more DC buses or distribution panels inoperable, and a loss of function has not yet occurred, the remaining DC electrical power distribution subsystems are capable of supporting the minimum safety functions necessary to shut down the reactor and maintain it in a safe shutdown condition, assuming no single failure. The overall reliability is reduced, however, because a single failure in the remaining DC electrical power distribution subsystem could result in the minimum required ESF functions not being supported. Therefore, the required DC buses and distribution panels must be restored to OPERABLE status within 2 hours by powering the bus from the associated battery or charger.
Condition C represents one or more DC buses or distribution panels without adequate DC power; potentially both with the battery significantly degraded and the associated charger nonfunctioning. In this situation, the unit is significantly more vulnerable to a complete loss of all DC power. It is, therefore, imperative that the operator's attention focus on stabilizing the unit, minimizing the potential for loss of power to the remaining division and restoring power to the affected division.

This 2 hour limit is more conservative than Completion Times allowed for the vast majority of components which would be without power. Taking exception to LCO 3.0.2 for components without adequate DC power, which would have Required Action Completion Times shorter than 2 hours, is acceptable because of:

a. The potential for decreased safety by requiring a change in unit conditions (i.e., requiring a shutdown) while allowing stable operations to continue.

b. The potential for decreased safety by requiring entry into numerous applicable Conditions and Required Actions for components without DC power and not providing sufficient time for the operators to perform the necessary evaluations and actions for restoring power to the affected division.

c. The potential for an event in conjunction with a single failure of a redundant component.

The 2 hour Completion Time for DC buses is consistent with Nuclear Regulatory Commission (NRC) Regulatory Guide (RG) 1.93 (Ref. 3).

D.1 and D.2

If the inoperable distribution subsystem cannot be restored to OPERABLE status within the required Completion Time, the unit must be brought to a MODE in which the LCO does not apply. To achieve this status, the unit must be brought to at least MODE 3 within 6 hours, and MODE 5 within 36 hours. The allowed Completion Times are reasonable, based on operating experience, to reach the required unit conditions from full power conditions in an orderly manner and without challenging unit systems.
CONDITIONS

**E.1**

Condition E corresponds to a level of degradation in the electrical distribution system that causes a required safety function to be lost. When more than one inoperable electrical power distribution subsystem results in the loss of a required function, the plant is in a condition outside the accident analysis. Therefore, no additional time is justified for continued operation. LCO 3.0.3 must be entered immediately to commence a controlled shutdown.

**SURVEILLANCE REQUIREMENTS**

**SR 3.8.9.1**

This Surveillance verifies that the AC, DC, and AC vital bus electrical power distribution systems are functioning properly, with the correct circuit breaker alignment. The correct breaker alignment ensures the appropriate separation and independence of the electrical trains is maintained, and the appropriate voltage is available to each required bus. The verification of proper voltage availability on the buses ensures that the required voltage is readily available for motive as well as control functions for critical system loads connected to these buses. The 7 day Frequency takes into account the redundant capability of the AC, DC, and AC vital bus electrical power distribution subsystems, and other indications available in the control room that alert the operator to subsystem malfunctions.

**REFERENCES**

1. FSAR, Chapter 6.
2. FSAR, Chapter 15.
<table>
<thead>
<tr>
<th>TYPE</th>
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<td>AC vital buses</td>
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<td>Bus 1A</td>
<td>Bus 1B</td>
</tr>
</tbody>
</table>

(1) Each train of the AC and DC Electrical Power Distribution Systems is a subsystem.
B 3.8 ELECTRICAL POWER SYSTEMS

B 3.8.10 Distribution Systems – Shutdown

BASES

BACKGROUND

A description of the alternating current (AC), direct current (DC), and AC Vital Bus Electrical Power Distribution Systems is provided in the Bases for LCO 3.8.9, “Distribution Systems – Operating.”

APPLICABLE SAFETY ANALYSES

The initial conditions of design basis accident and transient analyses in FSAR, Chapter 6 (Ref. 1) and Chapter 15 (Ref. 2) assume engineered safety feature (ESF) Systems are OPERABLE. The AC, DC, and AC Vital Bus Electrical Power Distribution Systems are designed to provide sufficient capacity, capability, redundancy, and reliability to ensure the availability of necessary power to ESF Systems so that the fuel, Reactor Coolant System, and containment design limits are not exceeded.

The OPERABILITY of the AC, DC, and AC Vital Bus Electrical Power Distribution System is consistent with the initial assumptions of the accident analyses and the requirements for the supported systems' OPERABILITY.

The OPERABILITY of the minimum AC, DC, and AC vital bus electrical power distribution subsystems during MODES 5 and 6, and during movement of irradiated fuel assemblies, ensures that:

a. The unit can be maintained in the shutdown or refueling condition for extended periods.

b. Sufficient instrumentation and control capability is available for monitoring and maintaining the unit status.

c. Adequate power is provided to mitigate events postulated during shutdown, such as a fuel handling accident.

The AC and DC Electrical Power Distribution Systems satisfy Criterion 3 of 10 CFR 50.36(c)(2)(ii).
Various combinations of subsystems, equipment, and components are required OPERABLE by other LCOs, depending on the specific unit condition. Implicit in those requirements is the required OPERABILITY of necessary support required features. This LCO explicitly requires energization of the portions of the electrical distribution system necessary to support OPERABILITY of required systems, equipment and components – all specifically addressed in each LCO and implicitly required via the definition of OPERABILITY.

Maintaining these portions of the distribution system energized ensures the availability of sufficient power to operate the unit in a safe manner to mitigate the consequences of postulated events during shutdown (e.g., fuel handling accidents).

The AC and DC electrical power distribution subsystems required to be OPERABLE in MODES 5 and 6, and during movement of irradiated fuel assemblies, provide assurance that:

a. Systems to provide adequate coolant inventory makeup are available for the irradiated fuel in the core.

b. Systems needed to mitigate a fuel handling accident are available.

c. Systems necessary to mitigate the effects of events that can lead to core damage during shutdown are available.

d. Instrumentation and control capability is available for monitoring and maintaining the unit in a cold shutdown or refueling condition.

AC, DC, and AC vital bus electrical power distribution subsystem requirements for MODES 1, 2, 3, and 4 are covered in LCO 3.8.9.

LCO 3.0.3 is not applicable while in MODE 5 or 6. However, since irradiated fuel assembly movement can occur in MODE 1, 2, 3, or 4, the ACTIONS have been modified by a Note stating that LCO 3.0.3 is not applicable. If moving irradiated fuel assemblies while in MODE 5 or 6, LCO 3.0.3 would not specify any action. If moving irradiated fuel assemblies while in MODE 1, 2, 3, or 4, the fuel movement is independent of reactor operations. Entering LCO 3.0.3, while in MODE 1, 2, 3, or 4 would require the unit to be shutdown unnecessarily.
BASES

ACTIONS (continued)

A.1, A.2.1, A.2.2, A.2.3, and A.2.4

Although redundant required features can require redundant divisions of electrical power distribution subsystems to be OPERABLE, one OPERABLE distribution subsystem division could be capable of supporting sufficient required features to allow continuation of irradiated fuel movement. By allowing the option to declare required features associated with an inoperable distribution subsystem inoperable, appropriate restrictions are implemented in accordance with the affected distribution subsystems LCO's Required Actions. In many instances, this option can involve undesired administrative efforts. Therefore, the allowance for sufficiently conservative actions is made (i.e., to suspend movement of irradiated fuel assemblies, and operations involving positive reactivity additions that could result in loss of required SDM (MODE 5) or boron concentration (MODE 6). Suspending positive reactivity additions that could result in failure to meet the minimum SDM or boron concentration limit is required to assure continued safe operation. Introduction of coolant inventory must be from sources that have a boron concentration greater than that what would be required in the Reactor Coolant System (RCS) for minimum SDM or refueling boron concentration. This could result in an overall reduction in RCS boron concentration, but provides acceptable margin to maintaining subcritical operation. Introduction of temperature changes including temperature increases when operating with a positive moderator temperature coefficient (MTC) must also be evaluated to ensure they do not result in a loss of required SDM.

Suspension of these activities shall not preclude completion of actions to establish a safe conservative condition. These actions minimize the probability of the occurrence of postulated events. It is further required to immediately initiate action to restore the required AC and DC electrical power distribution subsystems and to continue this action until restoration is accomplished in order to provide the necessary power to the unit safety systems.

Notwithstanding performance of the above conservative Required Actions, a required shutdown cooling (SC) subsystem could be inoperable. In this case, Required Actions A.2.1 through A.2.4 do not adequately address the concerns relating to coolant circulation and heat removal. Pursuant to LCO 3.0.6, the SC ACTIONS would not be entered. Therefore, Required Action A.2.5 is provided to direct declaring SC inoperable, which results in taking the appropriate SC ACTIONS.
The Completion Time of immediately is consistent with the required times for actions requiring prompt attention. The restoration of the required distribution subsystems should be completed as quickly as possible in order to minimize the time the unit safety systems are be without power.

This Surveillance verifies that the AC, DC, and AC Vital Bus Electrical Power Distribution System is functioning properly, with all the buses energized. The verification of proper voltage availability on the buses ensures that the required power is readily available for motive as well as control functions for critical system loads connected to these buses. The 7 day Frequency takes into account the redundant capability of the electrical power distribution subsystems, and other indications available in the main control room that alert the operator to subsystem malfunctions.

1. FSAR, Chapter 6.
2. FSAR, Chapter 15.
B 3.9 REFUELING OPERATIONS

B 3.9.1 Boron Concentration

BASES

BACKGROUND

The limit on the boron concentration of the Reactor Coolant System (RCS), refueling pool and refueling canal during refueling ensures that the reactor remains subcritical during MODE 6. Refueling boron concentration is the soluble boron concentration in the reactor coolant in each of these volumes having direct access to the reactor core during refueling or fuel handling.

The soluble boron concentration offsets the fuel reactivity and is measured by chemical analysis of the reactor coolant. The refueling boron concentration specified in the COLR ensures the $k_{\text{eff}}$ of the core will remain $\leq 0.95$ during fuel handling with control element assemblies (CEAs) and fuel assemblies assumed to be in the most adverse (least negative reactivity) configuration allowed by plant procedures.

10 CFR Part 50, Appendix A, GDC 26 requires two independent reactivity control systems of different design principles be provided (Ref. 1). One of these systems must be capable of holding the reactor core subcritical under cold conditions. The Chemical and Volume Control System (CVCS) is the system capable of maintaining the reactor subcritical in cold conditions by maintaining the boron concentration.

The reactor is brought to shutdown conditions before beginning operations to open the reactor vessel for refueling. After the RCS is cooled and depressurized, and the reactor vessel head is unbolted, the head is slowly raised. The refueling pool and canal are then flooded by pumping borated water from the in-containment refueling water storage tank (IRWST) using the Shutdown Cooling System (SCS) pump(s).

If additions of boron are required after the vessel has been opened, the CVCS makes the additions through the RCS and open vessel. The pumping action of the SCS and natural circulation due to thermal driving heads in the vessel and pool mix the added concentrated boric acid with the water in the RCS and the refueling canal.

The SCS is kept in service during the refueling period to assist in maintaining the boron concentration in the RCS, the refueling canal, and the refueling pool above the COLR limit and to remove core decay heat and provide forced circulation in the RCS. (Refer to LCO 3.9.4, “Shutdown Cooling System (SCS) and Coolant Circulation – High Water Level” and LCO 3.9.5, “Shutdown Cooling System (SCS) and Coolant Circulation – Low Water Level”).
During refueling operations the reactivity condition of the core is consistent with the initial conditions assumed for the boron dilution event in the accident analysis and is conservative for MODE 6. The magnitude of the boron concentration specified in the COLR is based on the nuclear design of each fuel cycle. It is further based on the core reactivity at the beginning of each fuel cycle (the end of refueling) and includes an uncertainty allowance.

The required boron concentration and the unit refueling procedures that demonstrate the correct fuel loading plan (including full core mapping) ensure the $k_{eff}$ of the core will remain $\leq 0.95$ during the refueling operation.

During refueling, the water volume in the spent fuel pool, the transfer canal, the refueling pool, the refueling canal and the reactor vessel form a single mass. As a result, the soluble boron concentration is the same in each of these volumes.

The inadvertent boron dilution event is discussed in FSAR, Section 15.4.6 (Ref. 2).

The RCS boron concentration satisfies Criterion 2 of 10 CFR 50.36(c)(2)(ii).

LCO 3.9.1 requires that a minimum boron concentration be maintained while in MODE 6. The boron concentration limit specified in the COLR during fuel handling operations ensures a $k_{eff}$ of $\leq 0.95$ is maintained. Violation of the LCO could lead to possible inadvertent criticality during MODE 6.

This LCO is applicable in MODE 6 to ensure that the fuel in the reactor vessel will remain subcritical. The required boron concentration ensures a $k_{eff}$ of $\leq 0.95$. Above MODE 6, LCO 3.1.1, “SHUTDOWN MARGIN (SDM),” ensures that an adequate amount of negative reactivity is available to shut down the reactor and to maintain the reactor subcritical.

The Applicability is modified by a Note. The Note states that the limits on boron concentration are only applicable to the refueling canal and the refueling pool when those volumes are connected to the RCS. When the refueling canal and the refueling pool are isolated from the RCS, no potential path for boron dilution exists.
Borons Concentration

ACTIONS

A.1

Continuation of positive reactivity additions (including actions to reduce boron concentration) is contingent upon maintaining the plant in compliance with the LCO. If the boron concentration of any of the filled portions of the RCS, the refueling canal, or the refueling pool is less than its limit, all operations involving positive reactivity additions must be suspended immediately. Operations that individually add limited positive reactivity (e.g., temperature fluctuations from inventory addition or temperature control fluctuations), but when combined with all other operations affecting core reactivity (e.g., intentional boration) result in overall net negative reactivity addition, are not precluded by this action.

Suspension of positive reactivity additions shall not preclude completion of actions to establish a safe condition.

A.2

In addition to immediately suspending positive reactivity additions, boration to restore the concentration must be initiated immediately. In the determination of the required combination of boration flow rate and boron concentration, there is not a unique design basis event which must be satisfied. The only requirement is to restore the boron concentration to its required value as soon as possible. In order to raise the boron concentration of the RCS as soon as possible, the operator should begin boration with the best source available for unit conditions.

Once boration is initiated, it must be continued until the boron concentration is restored. The Completion Time depends on the amount of boron which must be injected to reach the required concentration.

SURVEILLANCE REQUIREMENTS

SR 3.9.1.1

This SR ensures the reactor coolant boron concentration in the RCS, refueling canal and refueling pool is within the COLR limits. The boron concentration in the coolant is determined periodically by chemical analysis. Prior to reconnecting portions of the refueling canal or the refueling pool to the RCS, this SR must be met per SR 3.0.4. If any dilution activity has occurred while the pool or canal were disconnected from the RCS, this SR ensures the correct boron concentration prior to communication with the RCS. A minimum Frequency of once every 72 hours is a reasonable interval to verify boron concentration. The Surveillance Frequency is based on extensive operating experience and ensures that the boron concentration is checked at adequate intervals.
REFERENCES


2. FSAR, Subsection 15.4.6.
B 3.9 REFUELING OPERATIONS

B 3.9.2 Nuclear Instrumentation

BASES

BACKGROUND

The installed startup channels of the Ex-core Neutron Flux Monitoring System (ENFMS) and the Boron Dilution Alarm System (BDAS) are used during refueling operations to monitor the core reactivity condition. The startup channels are a part of ENFMS and include related indicators and recorders. The neutron flux detectors of these startup channels are located external to the reactor vessel and detect neutrons leaking from the core.

The startup channels of the ENFMS monitor the neutron flux in counts per second (cps) and cover neutron flux up to 1E5 cps with a 5% instrument accuracy. Each startup channel of the ENFMS provides visual indication in the main control room (MCR) and startup range neutron flux information to the BDAS for an audible alarm to alert operators to a possible dilution accident. The ENFMS is designed in accordance with the criteria presented in Reference 1.

APPLICABLE SAFETY ANALYSES

Two OPERABLE startup channels of the ENFMS are required to provide a signal to alert the operator to unexpected changes in core reactivity such as a boron dilution event or an improperly loaded fuel assembly. The safety analysis of the uncontrolled boron dilution event is described in Reference 2. This analysis shows that the normally available SDM would be reduced, but that there is sufficient time available for the operator to detect and to terminate the event should it occur.

The startup channels of the ENFMS satisfy Criterion 3 of 10 CFR 50.36(c)(2)(ii).

LCO

This LCO requires two OPERABLE startup channels of the ENFMS to ensure that redundant monitoring capability is available to detect changes in core reactivity.

The BDAS is not required to be OPERABLE in MODE 6 because such an event is precluded by LCO 3.9.7, "Unborated Water Source Isolation Valve – MODE 6" which requires the flow paths for unborated makeup water sources to be isolated in MODE 6.
APPLICABILITY

In MODE 6 two startup channels of the ENFMS must be OPERABLE to determine changes in core reactivity. No other direct means are available to check core reactivity levels.

In MODES 3, 4, and 5, the installed startup channels of the ENFMS are required to be OPERABLE by LCO 3.3.14, “Boron Dilution Alarms.”

ACTIONS

A.1 and A.2

With only one startup channel of the ENFMS OPERABLE, redundancy has been lost. Since these instruments are the only direct means of monitoring core reactivity conditions, positive reactivity additions and introduction of coolant into the Reactor Coolant System (RCS) with boron concentration less than required to meet the minimum boron concentration of LCO 3.9.1 must be suspended immediately. Suspending positive reactivity additions that could result in failure to meet the minimum boron concentration limit is required to assure continued safe operation. Introduction of coolant inventory must be from sources that have a boron concentration greater than that what would be required in the RCS for minimum refueling boron concentration. This could result in an overall reduction in RCS boron concentration, but provides acceptable margin to maintaining subcritical operation. Performance of Required Action A.1 shall not preclude completion of movement of a component to a safe position.

B.1

With no startup channel of the ENFMS OPERABLE, ACTION to restore a monitor to OPERABLE status shall be initiated immediately. Once initiated, ACTIONS shall be continued until a startup channel of the ENFMS is restored to OPERABLE status.

B.2

With no startup channel of the ENFMS OPERABLE, there is no direct means of detecting changes in core reactivity. However, since positive reactivity additions are not to be made, the core reactivity condition is stabilized until the startup channels of the ENFMS are OPERABLE. This stabilized condition is determined by performing SR 3.9.1.1 to verify that the required boron concentration exists.

The Completion Time of once per 12 hours is sufficient to obtain and analyze a reactor coolant sample for boron concentration and ensures that unplanned changes in boron concentration would be identified. The 12 hour Frequency is reasonable, considering the low probability of a change in core reactivity during this period.
SR 3.9.2.1 is the performance of a CHANNEL CHECK, which is the comparison between channels of the indicated parameter values for each of the functions. It is based on the assumption that the two indication channels should be consistent with core conditions. Changes in fuel loading and core geometry can result in significant differences between startup channels of the ENFMS but each channel should be consistent with its local conditions. The 12 hour Frequency is consistent with the CHANNEL CHECK Frequency specified similarly for LCO 3.3.1, "Reactor Protection System (RPS) Instrumentation – Operating."

SR 3.9.2.2 is the performance of a CHANNEL CALIBRATION every 18 months. The CHANNEL CALIBRATION for the startup channels of the ENFMS consists of obtaining the voltage plateau curves or preamp discriminator curves, evaluating those curves, and comparing the curves to the manufacturer’s data. The 18 month Frequency is based on the need to perform this Surveillance under the conditions that apply during a plant outage.

REFERENCES

1. 10 CFR Part 50, Appendix A, GDC 13, 26, 28, and 29.

2. FSAR, Subsection 15.4.6.
B 3.9   REFUELING OPERATIONS

B 3.9.3  Containment Penetrations

BASES

BACKGROUND  

During CORE ALTERATIONS or movement of irradiated fuel assemblies within containment, a release of fission product radioactivity within the containment will be restricted from leakage to the environment when the LCO requirements are met. In MODES 1, 2, 3, and 4 this is accomplished by maintaining containment OPERABLE as described in LCO 3.6.1 “Containment.” In MODE 6, the potential for containment pressurization as a result of an accident is not present, therefore, less stringent requirements are needed to isolate the containment from the outside atmosphere. The LCO requirements are referred to as “containment closure” rather than “containment OPERABILITY.” Containment closure means that all potential escape paths are closed or capable of being closed. Since there is no potential for containment pressurization, the ANSI/ANS 56.8-1994 leakage criteria and tests are not required.

The containment structure serves to contain fission product radioactivity which could be released from the reactor core following a Design Basis Accident (DBA), such that offsite radiation exposures are maintained well within the requirements of 10 CFR Part 50.34. Additionally, this structure provides radiation shielding from the fission products which could be present in the containment atmosphere following accident conditions.

[----------------------------------REVIEWER’S NOTE-----------------------------------]

The number of bolts, material, size, and analysis supporting the hatch capability to support the dead weight (at a minimum) will be determined by the COL applicant.

-------------------------------------------------------------------------------------------------

The containment equipment hatch, which is part of the containment pressure boundary, provides a means for moving large equipment and components into and out of containment. During CORE ALTERATIONS or movement of irradiated fuel assemblies within containment, the equipment hatch must be held in place by at least [four bolts]. Good engineering practice dictates that the bolts required by this LCO be approximately equally spaced.

The containment airlocks, which are also part of the containment pressure boundary, provide a means for personnel access during MODES 1, 2, 3, and 4 operation in accordance with LCO 3.6.2, “Containment Airlocks.” Each airlock has a door at both ends. The doors are normally interlocked to prevent simultaneous opening when containment OPERABILITITY is required.
During periods of unit shutdown when containment closure is not required, the door interlock mechanism may be disabled, allowing both doors of an airlock to remain open for extended periods when frequent containment entry is necessary. During CORE ALTERATIONS or movement of irradiated fuel assemblies within containment, containment closure is required; therefore the door interlock mechanism may remain disabled, but one airlock door must remain capable of being closed.

The requirements on containment penetration closure ensure that a release of fission product radioactivity within containment will be restricted to within regulatory limits.

The Containment Purge System includes two subsystems. The high volume purge subsystem includes two 1219.2 mm (48 in) purge penetrations and two 1219.2 mm (48 in) exhaust penetrations. The low volume purge subsystem includes two 203.2 mm (8 in) purge penetration and two 203.2 mm (8 in) exhaust penetration. During MODES 1, 2, 3, and 4, the two valves in each of the high volume purge and exhaust penetrations are secured in the closed position. The two valves in each of the two low volume purge penetrations can be opened intermittently, but are closed automatically by the Engineered Safety Features Actuation System (ESFAS). Neither of the subsystems is subject to a Specification in MODE 5.

In MODE 6, large air exchanges are necessary to conduct refueling operations. The High Volume Purge System is used for this purpose and all valves are closed by the ESFAS such as containment purge isolation actuation signal (CPIAS) and containment isolation actuation signal (CIAS) in accordance with LCO 3.3.5, “Engineered Safety Feature Actuation System (ESFAS) Instrumentation.”

The Low Volume Purge System is not used in MODE 6. All four 203.2 mm (8 in) valves are secured in the closed position.

The other containment penetrations that provide direct access from containment atmosphere to outside atmosphere must be isolated on at least one side. Isolation may be achieved by an OPERABLE automatic isolation valve, or by a manual isolation valve, blind flange, or equivalent. Equivalent isolation methods must be approved and may include use of a material that can provide a temporary, atmospheric pressure ventilation barrier for the other containment penetrations during fuel movements (Ref. 1).
Containment Penetrations

B 3.9.3

APPLICABLE
SAFETY
ANALYSES

During CORE ALTERATIONS or movement of irradiated fuel assemblies within containment, the most severe radiological consequences result from a fuel handling accident. The fuel handling accident is a postulated event that involves damage to irradiated fuel (Ref. 2). Fuel handling accidents, analyzed in Section 15.7.4, include dropping a single fuel assembly and handling tool or a heavy object onto other irradiated fuel assemblies. The requirements of this LCO and LCO 3.9.6, “Refueling Water Level,” and the minimum decay time of 100 hours prior to CORE ALTERATIONS ensure that the release of fission product radioactivity subsequent to a fuel handling accident, results in doses that are well within the guideline values specified in 10 CFR Part 50.34. The acceptance limits for offsite radiation exposure are contained in Standard Review Plan (Ref. 3), which defines “well within” 10 CFR 50.34 to be 25% or less of the 10 CFR 50.34 values.

Containment penetrations satisfy Criterion 3 of 10 CFR 50.36(c)(2)(ii).

LCO

This LCO limits the consequences of a fuel handling accident in containment by limiting the potential escape paths for fission product radioactivity released within containment. The LCO requires any penetration providing direct access from the containment atmosphere to the outside atmosphere to be closed except for the OPERABLE containment purge and exhaust penetrations. For the OPERABLE containment purge penetrations, this LCO ensures that these penetrations are isolable by the Containment Purge System. The OPERABILITY requirements for this LCO ensure that the automatic purge and exhaust valve closure times specified in FSAR, Chapter 15 can be achieved and therefore meet the assumptions used in the safety analysis to ensure releases through the valves are terminated, such that the radiological doses are within the acceptance limit.

APPLICABILITY

The containment penetration requirements are applicable during CORE ALTERATIONS or movement of irradiated fuel assemblies within containment because this is when there is a potential for a fuel handling accident. In MODES 1, 2, 3 and 4, Containment Penetration requirements are addressed by LCO 3.6.1, “Containment.” In MODES 5 and 6 when CORE ALTERATIONS or movement of irradiated fuel assemblies within containment are not being conducted, the potential for a fuel handling accident does not exist. Therefore, under these conditions no requirements are placed on containment penetration status.
CONTAINMENT PENETRATIONS

B 3.9.3

BASES

ACTIONS

A.1 and A.2

With the containment equipment hatch, airlocks, or any containment penetration that provides direct access from the containment atmosphere to the outside atmosphere not in the required status, including the Containment Purge and Exhaust Isolation System not capable of automatic actuation when the purge and exhaust valves are open, the unit must be placed in a condition where the isolation function is not needed. This is accomplished by immediately suspending CORE ALTERATIONS and movement of irradiated fuel assemblies within containment. Performance of these actions shall not preclude completion of actions to establish a safe condition.

SURVEILLANCE REQUIREMENTS

SR 3.9.3.1

This SR demonstrates that each of the containment penetrations required to be in its closed position is in that position. The Surveillance on the open purge and exhaust valves will demonstrate that the valves are not blocked from closing. Also, the Surveillance will demonstrate that each valve operator has motive power, which will ensure each valve is capable of being closed by an OPERABLE automatic containment purge and exhaust isolation signal.

The Surveillance is performed every 7 days during CORE ALTERATIONS or movement of irradiated fuel assemblies within the containment. The Surveillance interval is selected to be commensurate with the normal duration of time to complete fuel handling operations. A Surveillance before the start of refueling operations will provide two or three surveillance verifications during the applicable period for this LCO.

SR 3.9.3.2

This SR demonstrates each containment purge and exhaust valve actuates to its isolation position on an actual or simulated actuation signal. The 18 month Frequency maintains consistency with similar ESFAS testing requirements and has been shown to be acceptable through operating experience.

As such, this Surveillance ensures that a postulated fuel handling accident which involves a release of fission product radioactivity within the containment will not result in a release of significant fission product radioactivity to the environment in excess of those recommended by Standard Review Plan Section 15.0.3 (Ref. 3).
REFERENCES

2. FSAR, Chapter 15.
3. NUREG-0800, Section 15.0.3, March 2007.
B 3.9 REFUELING OPERATIONS

B 3.9.4 Shutdown Cooling System (SCS) and Coolant Circulation – High Water Level

BASES

BACKGROUND

The main purposes of the Shutdown Cooling System (SCS) are to remove decay heat and sensible heat from the Reactor Coolant System (RCS) when RCS pressure and temperature are below approximately 31.6 kg/cm²A (450 psia) and 177°C (350°F), respectively (Ref. 1), to provide sufficient coolant circulation to minimize the effects of a boron dilution event, and to prevent boron stratification. Heat is transferred from the RCS by circulating reactor coolant through the SCS where the heat is transferred to the Component Cooling Water (CCW) System via the shutdown cooling (SC) heat exchangers.

The coolant is then returned to the RCS via the direct vessel injection (DVI) nozzle(s). Operation of the SCS for normal cooldown or decay heat removal is manually accomplished from the main control room (MCR). The heat removal rate is adjusted by controlling the flow of reactor coolant through the SC heat exchanger(s) and bypassing the heat exchanger(s). Mixing of the coolant is maintained by this continuous circulation of reactor coolant through the SCS.

APPLICABLE SAFETY ANALYSES

If the reactor coolant temperature is not maintained below 93.3°C (200°F), boiling of the reactor coolant could result. This could lead to inadequate cooling of the reactor fuel due to a resulting loss of coolant in the reactor vessel. Additionally, boiling of the reactor coolant could lead to a reduction in boron concentration in the coolant due to the boron plating out on components near the areas of the boiling activity, and because of the possible addition of water to the reactor vessel with a lower boron concentration than is required to keep the reactor subcritical. The loss of reactor coolant and the reduction of boron concentration in the reactor coolant would eventually challenge the integrity of the fuel cladding, which is a fission product barrier. One train of the SCS is required to be operational in MODE 6, with the water level ≥ 7.0 m (23 ft) above the top of the reactor vessel flange, to prevent this challenge. The LCO does permit de-energizing of the SC pump for short durations under the condition that the boron concentration is not diluted. This conditional de-energizing of the SC pump does not result in a challenge to the fission product barrier.

Shutdown Cooling System and Coolant Circulation – High Water Level satisfies Criterion 2 of 10 CFR 50.36(c)(2)(ii).
Only one SC train is required for decay heat removal in MODE 6 with water level \(\geq 7.0 \text{ m} (23 \text{ ft})\) above the top of the reactor vessel flange. Only one SC train is required because the volume of water above the reactor vessel flange provides backup decay heat removal capability. At least one SCS train must be OPERABLE and in operation to:

1. Provide for decay heat removal,
2. Provide mixing of borated coolant to minimize the possibility of a criticality, and
3. Provide indication of average reactor coolant temperature.

An OPERABLE train consists of an SC pump, a heat exchanger, valves, piping, instruments, and controls to ensure an OPERABLE flow path and to determine the low end temperature. The flow path starts in one of the RCS hot legs and is returned to the DVI nozzle(s). Managing gas or voids in the piping is important to SCS OPERABILITY.

Both SC pumps may be aligned to the in-containment refueling water storage tank (IRWST) to support filling or draining the refueling pool or for performance of required testing.

The requirements of this LCO are derived primarily from experience with decay heat removal in shutdown MODES of operation. The principal purpose of this specification is to assure the capability to remove decay heat and to control RCS temperature and chemistry.

The LCO is modified by a Note which allows the operating SC train to be removed from service for up to 1 hour per 8 hour period, provided no operations are permitted that would dilute the RCS boron concentration by introduction of coolant into the RCS with boron concentration less than that required to meet the minimum boron concentration of LCO 3.9.1. Boron concentration reduction with coolant at boron concentrations less than required to assure the RCS boron concentration is maintained is prohibited because uniform concentration distribution cannot be ensured without forced circulation. This permits operations such as core mapping or alterations in the vicinity of the reactor vessel hot leg nozzles and RCS to SCS isolation valve testing. During this 1 hour period, decay heat is removed by natural convection to the large mass of water in the refueling pool.
One SC train must be OPERABLE and in operation in MODE 6 with the water level \( \geq 7.0 \) m (23 ft) above the top of the reactor vessel flange to provide decay heat removal. The 7.0 m (23 ft) value was selected because it corresponds to the requirement for fuel movement established by LCO 3.9.6, “Refueling Water Level.” Requirements for the SCS in other MODES are covered by LCOs in Section 3.4, “Reactor Coolant System.”

SC train requirements in MODE 6 when water level is \(< 7.0 \) m (23 ft) are located in LCO 3.9.5, “SCS and Coolant Circulation – Low Water Level.”

SC train requirements are met by having one SC train OPERABLE and in operation except as permitted in the Note to the LCO.

A.1

If one required SC train is inoperable or not in operation, action shall be immediately initiated and continued until the SC train is restored to OPERABLE status and to operation. An immediate Completion Time is necessary for an operator to initiate corrective actions.

A.2

If one required SC train is inoperable or not in operation, there will be no forced circulation to provide mixing to establish uniform boron concentrations. Suspending positive reactivity additions that could result in failure to meet the minimum boron concentration limit is required to assure continued safe operation. Introduction of coolant inventory must be from sources that have a boron concentration greater than what would be required in the RCS for minimum refueling boron concentration. This may result in an overall reduction in RCS boron concentration, but provides acceptable margin to maintaining subcritical operation.

A.3

If one required SC train is inoperable or not in operation, actions shall be taken immediately to suspend loading irradiated fuel assemblies in the core. With no forced circulation cooling, decay heat removal from the core occurs by natural convection to the heat sink provided by the water above the core. A minimum refueling water level of 7.0 m (23 ft) above the reactor vessel flange provides an adequate available heat sink. Suspending any operation which would increase decay heat load, such as loading a fuel assembly, is a prudent action under this condition.
ACTIONS (continued)

A.4

If one required SC train is inoperable and not in operation, actions must be taken to make the containment building penetrations in the required status as specified in LCO 3.6.7.

With SC train requirements not met, the potential exists for the coolant to boil and release radioactive gas to the containment atmosphere. Performing the actions described above ensures that all containment penetrations are either closed or can be closed so that the dose limits are not exceeded.

The 4 hour Completion Time allows fixing of most SC problems and is reasonable, based on the low probability of the coolant boiling in that time.

SURVEILLANCE REQUIREMENTS

SR 3.9.4.1

This Surveillance verifies that the SC train is in operation and circulating reactor coolant. The flow rate is determined by the flow rate necessary to provide sufficient decay heat removal capability and to prevent thermal and boron stratification in the core. The 12 hour Frequency is sufficient considering the flow, temperature, pump control, and alarm indications available to the operator to monitor the SCS in the MCR. This Frequency ensures that SC train operation and flow is checked at adequate intervals.

SR 3.9.4.2

With the exception of systems in operation, the SC pumps are normally in a standby, non-operating condition. As such, flow path piping has the potential to develop voids and pockets of entrained gases. Maintaining the piping from the SC pumps to the RCS full of water ensures that the system will perform properly, injecting its full capacity into the RCS upon demand. Water source comes from the IRWST and safety injection filling tanks (SIFTs). This will also prevent water hammer, pump cavitation, and pumping of non-condensible gas (e.g., air, nitrogen, hydrogen) into the reactor vessel during shutdown cooling.
SURVEILLANCE REQUIREMENTS (continued)

Selection of SCS piping locations susceptible to gas accumulation is based on a review of system design information, including piping and instrumentation drawings, isometric drawings, plan and elevation drawings, and calculations. The design review is supplemented by system walk downs to validate the system high points and to confirm the locations and orientation of important components that can become sources of gas or could otherwise cause gas to be trapped or difficult to remove during system maintenance or restoration. Susceptible piping locations depend on plant and system configuration, such as stand-by versus operating conditions.

The SCS is OPERABLE when it is sufficiently filled with water. Acceptance criterion is established for the volume of accumulated gas at susceptible locations. If accumulated gas is discovered that exceeds an acceptance criterion for the susceptible locations (or the volume of accumulated gas at one or more susceptible piping locations exceeds an acceptance criterion for gas volume at the suction or discharge of a pump), the Surveillance is not met. If it is determined by subsequent evaluation that the SCS is not rendered inoperable by the accumulated gas (i.e., the system is sufficiently filled with water), the Surveillance may be declared to be met. Accumulated gas should be eliminated or brought within the acceptance criterion limit.

SCS piping locations susceptible to gas accumulation are monitored and, if gas is found, the gas volume is compared to the acceptance criterion for the piping locations. Susceptible piping locations in the same system flow path which are subject to the same gas accumulation mechanisms may be verified by monitoring a representative sub-set of susceptible piping locations. Monitoring may not be practical for piping locations inaccessible due to radiological or environmental conditions, the plant configuration or personal safety. For these locations alternative methods (e.g., operating parameters, remote monitoring) may be used to monitor the susceptible piping locations. Monitoring is not required for susceptible piping locations where the maximum potential accumulated gas void volume has been evaluated and determined not to challenge system OPERABILITY. The accuracy of the method used for monitoring the susceptible piping locations and trending of the results should be sufficient to assure system OPERABILITY during the Surveillance interval.

The 31 day Frequency is based on the low probability of an event requiring SCS operation during this time, the gradual nature of gas accumulation in the SCS piping, and the adequacy of procedural controls governing system operation.
REFERENCES

1. FSAR, Subsection 5.4.7.
B 3.9  REFUELING OPERATIONS

B 3.9.5  Shutdown Cooling System (SCS) and Coolant Circulation – Low Water Level

BASSES

BACKGROUND  The main purposes of the Shutdown Cooling System (SCS) are to remove decay heat and sensible heat from the Reactor Coolant System (RCS) when RCS pressure and temperature are below approximately 31.6 kg/cm²A (450 psia) and 177°C (350°F), respectively (Ref. 1), to provide sufficient coolant circulation to minimize the effects of a boron dilution event, and to prevent boron stratification. Heat is transferred from the RCS by circulating reactor coolant through the SCS where the heat is transferred to the Component Cooling Water System (CCWS) via the shutdown cooling (SC) heat exchangers.

The coolant is then returned to the RCS via the direct vessel injection (DVI) nozzle(s). Operation of the SCS for normal cooldown or decay heat removal is manually accomplished from the main control room (MCR). The heat removal rate is adjusted by controlling the flow of reactor coolant through the SC heat exchanger(s) and bypassing the heat exchanger(s). Mixing of the coolant is maintained by this continuous circulation of reactor coolant through the SCS.

APPLICABLE SAFETY ANALYSES  If the reactor coolant temperature is not maintained below 93.3°C (200°F), boiling of the reactor coolant could result. This could lead to inadequate cooling of the reactor fuel due to the resulting loss of coolant in the reactor vessel. Additionally, boiling of the reactor coolant could lead to a reduction in boron concentration in the coolant due to the boron plating out on components near the areas of the boiling activity, and because of the possible addition of water to the reactor vessel with a lower boron concentration than is required to keep the reactor subcritical. The loss of reactor coolant and the reduction of boron concentration in the reactor coolant would eventually challenge the integrity of the fuel cladding, which is a fission product barrier. Two trains of the SCS are required to be OPERABLE, and one train is required to be in operation in MODE 6, with the water level < 7.0 m (23 ft) above the top of the reactor vessel flange, to prevent this challenge.

SCS and Coolant Circulation – Low Water Level satisfies Criterion 2 of 10 CFR 50.36(c)(2)(ii).
Only one SC train is needed for decay heat removal in MODE 6 with water level < 7.0 m (23 ft) above the top of the reactor vessel flange. To increase reliability, both SC trains must be OPERABLE. Additionally, one train of SCS must be in operation in order to:

a. Provide for decay heat removal,

b. Provide mixing of borated coolant to minimize the possibility of a criticality, and

c. Provide indication of average reactor coolant temperature.

An OPERABLE SC train consists of an SC pump, a heat exchanger, valves, piping, instruments, and controls to ensure an OPERABLE flow path and to determine the low end temperature. The flow path starts in one of the RCS hot legs and is returned to the DVI nozzle(s). Managing gas or voids in the piping is important to SCS OPERABILITY.

In addition, when RCS level < 38.72 m (127 ft 1/4 in), a containment spray (CS) pump in the same train as the operating SC pump is required to be OPERABLE. The containment spray pump is interchangeable with the SC pump and provides a backup to the operating SC pump. This requirement ensures forced circulation is available for decay heat removal if the operating SC pump becomes inoperable for any reason.

The requirements of this LCO are derived primarily from experience with decay heat removal in shutdown MODES of operation. The principal purpose of this specification is to assure the capability to remove decay heat and to control RCS temperature, and chemistry with low water level.

Both SC pumps may be aligned to the in-containment refueling water storage tank (IRWST) to support filling or draining of the refueling pool or for performance of required testing.

Two SC trains are required to be OPERABLE and one SC train must be in operation in MODE 6 with the water < 7.0 m (23 ft) above the top of the reactor vessel flange to provide decay heat removal. Requirements for the SCS in other MODES are covered by LCOs in Section 3.4, “Reactor Coolant System.” MODE 6 requirements with water level ≥ 7.0 m (23 ft) above the reactor vessel flange are covered in LCO 3.9.4, “SCS and Coolant Circulation – High Water Level.”
With one SC train inoperable and the other SC train operating, actions shall be taken and continued until the SC train is restored to OPERABLE status or to establish water level of > 7.0 m (23 ft) above the reactor vessel flange. At that point, the Applicability will change to that of LCO 3.9.4, “SCS and Coolant Circulation – High Water Level,” and only one SC train is required to be OPERABLE and in operation. With the unit in MODE 6, immediate corrective actions must be taken.

**B.1**

If no SC train is in operation or no SC trains are OPERABLE, there will be no forced circulation to provide mixing to establish uniform boron concentrations. Suspending positive reactivity additions that could result in failure to meet the minimum boron concentration limit is required to assure continued safe operation. Introduction of coolant inventory must be from sources that have boron concentration greater than required in the RCS for minimum refueling boron concentration. This may result in an overall reduction in RCS boron concentration, but provides acceptable margin to maintaining subcritical operation.

**B.2**

With no SC train in operation or with both SC trains inoperable, actions shall be initiated immediately and continued without interruption to restore one SC train to OPERABLE status and operation. As the unit is in Conditions A and B concurrently, the restoration of two OPERABLE SC trains and one operating SC train should be accomplished as quickly as possible. With at least one SC train OPERABLE, water level can be raised ≥ 7.0 m (23 ft) above the reactor vessel flange and the applicability will change to that of LCO 3.9.4, “SCS and Coolant Circulation – High Water Level,” and only one SC train is required.

**B.3**

If no SC train is in operation or no SC trains are OPERABLE and the RCS level < 38.72 m (127 ft 1/4 in) the action requires to immediately initiate action to raise RCS level to ≥ 38.72 m (127 ft 1/4 in). The immediate Completion Time reflects the importance of maintaining operation for decay heat removal and prevents a boron dilution event.

**B.4**

If no SC train is in operation, actions must be taken to the containment building penetrations in the required status as specified in LCO 3.6.7.
With SC train requirements not met, the potential exists for the coolant to boil and release radioactive gas to the containment atmosphere. Performing the actions described above ensures that all containment penetrations are either closed or can be closed so that the dose limits are not exceeded.

The Completion Time of 4 hours allows fixing of most SCS problems and is reasonable, based on the low probability of the coolant boiling in that time.

C.1, C.2 and C.3

If the CS pump in the same electrical train as an operating SC train is inoperable with RCS level < 38.72 m (127 ft 1/4 in), action must be initiated to place the alternate SC train in operation (if the containment spray pump in the alternate SC train is OPERABLE) immediately. Also, SC System performance must be monitored every 30 minutes and the inoperable CS pump must be restored to OPERABLE condition within 48 hours.

D.1

If the CS pump cannot be restored within 48 hours, RCS level must be raised to \( \geq 38.72 \text{ m (127 ft 1/4 in)} \) within 6 hours. This will place the plant in a conservative position with respect to providing decay heat removal.

SURVEILLANCE REQUIREMENTS

SR 3.9.5.1

This Surveillance verifies that the SC train is in operation and circulating reactor coolant. The flow rate is determined by the flow rate necessary to provide sufficient decay heat removal and to prevent thermal and boron stratification in the core. At RCS level < 38.72 m (127 ft 1/4 in) the flow rate is determined to provide sufficient decay heat removal capability and to prevent thermal and boron stratification and also to address air ingestion in the hot leg when the RCS water inventory is maintained at the lowest permitted level. In addition, this surveillance demonstrates that the other SC train is OPERABLE.
In addition, during operation of the SC train with the water level in the vicinity of the reactor vessel nozzles, the SC train flow rate determination must also consider the SC pump suction requirements. The 12 hour Frequency is sufficient considering the flow, temperature, pump control, and alarm indications available to the operator to monitor the SCS in the MCR. This Frequency ensures that flow is checked and temperature monitored at adequate intervals.

Verification that the required trains are OPERABLE and in operation ensures that trains can be placed in operation as needed, to maintain decay heat and retain forced circulation. The 12 hour Frequency is considered reasonable, since other administrative controls are available and have proven to be acceptable by operating experience.

SR 3.9.5.2

Verification that the required pump is OPERABLE ensures that an additional SC pump can be placed in operation, if needed, to maintain decay heat removal and reactor coolant circulation.

Verification is performed by ensuring correct breaker alignment and indicated power available to the required pumps. The 7 day Frequency is considered reasonable in view of other administrative controls available and has been shown to be acceptable by operating experience.

SR 3.9.5.3

Verification of the correct breaker alignment and indicated power available to the OPERABLE CS pump ensures that the CS pump will be able to remove heat from the RCS in the event of a power failure to the operating SC train. To be considered OPERABLE, the required CS pump must be in standby for manual start and its flow path must be aligned to perform the shutdown cooling function. The required CS pump must meet the requirements of the associated operating SC pump in the event the operating SC pump stops. Therefore, the SRs of this Specification must be applied to the required CS pump, as necessary. The 24 hour Frequency is based on operating experience.
SCS and Coolant Circulation - Low Water Level

Bases

Surveillance Requirements (continued)

SR 3.9.5.4

With the exception of systems in operation, the SC pumps are normally in a standby, non-operating condition. As such, flow path piping has the potential to develop voids and pockets of entrained gases. Maintaining the piping from the SC pumps to the RCS full of water ensures that the system will perform properly, injecting its full capacity into the RCS upon demand. Water source comes from the IRWST and safety injection filling tanks (SIFTs). This will also prevent water hammer, pump cavitation, and pumping of non-condensible gas (e.g., air, nitrogen, hydrogen) into the reactor vessel during shutdown cooling.

Selection of SCS piping locations susceptible to gas accumulation is based on a review of system design information, including piping and instrumentation drawings, isometric drawings, plan and elevation drawings, and calculations. The design review is supplemented by system walk downs to validate the system high points and to confirm the locations and orientation of important components that can become sources of gas or could otherwise cause gas to be trapped or difficult to remove during system maintenance or restoration. Susceptible piping locations depend on plant and system configuration, such as stand-by versus operating conditions.

The SCS is OPERABLE when it is sufficiently filled with water. Acceptance criterion is established for the volume of accumulated gas at susceptible locations. If accumulated gas is discovered that exceeds an acceptance criterion for the susceptible locations (or the volume of accumulated gas at one or more susceptible piping locations exceeds an acceptance criterion for gas volume at the suction or discharge of a pump), the Surveillance is not met. If it is determined by subsequent evaluation that the SCS is not rendered inoperable by the accumulated gas (i.e., the system is sufficiently filled with water), the Surveillance may be declared to be met. Accumulated gas should be eliminated or brought within the acceptance criterion limit.

SCS piping locations susceptible to gas accumulation are monitored and, if gas is found, the gas volume is compared to the acceptance criterion for the piping locations. Susceptible piping locations in the same system flow path that are subject to the same gas accumulation mechanisms may be verified by monitoring a representative sub-set of susceptible piping locations. Monitoring may not be practical for piping locations inaccessible due to radiological or environmental conditions, the plant.
configuration, or personal safety. For these locations alternative methods (e.g., operating parameters, remote monitoring) may be used to monitor the susceptible piping locations. Monitoring is not required for susceptible piping locations where the maximum potential accumulated gas void volume has been evaluated and determined not to challenge system OPERABILITY. The accuracy of the method used for monitoring the susceptible piping locations and trending of the results should be sufficient to assure system OPERABILITY during the Surveillance interval.

The 31 day Frequency is based on the low probability of an event requiring SCS operation during this time, the gradual nature of gas accumulation in the SCS piping, and the adequacy of procedural controls governing system operation.

REFERENCES 1. FSAR, Subsection 5.4.7.
B 3.9 REFUELING OPERATIONS

B 3.9.6 Refueling Water Level

BASES

BACKGROUND
The movement of irradiated fuel assemblies or performance of CORE ALTERATIONS, except during latching and unlatching of control rod drive shafts, within containment requires a minimum water level of 7 m (23 ft) above the top of the reactor vessel flange. During refueling this maintains sufficient water level in the containment, the refueling canal, the fuel transfer canal, the refueling pool, and the spent fuel pool. Sufficient water is necessary to retain iodine fission product activity in the water in the event of a fuel handling accident (Refs. 1 and 2). Sufficient iodine activity would be retained to limit offsite doses from the accident to under 25% of 10 CFR 50.34 limits, as provided by the guidance of Reference 3.

APPLICABLE SAFETY ANALYSES
During CORE ALTERATIONS and during movement of irradiated fuel assemblies, the water level in the refueling pool and refueling canal is an initial condition design parameter in the analysis of the fuel handling accident in containment postulated by Nuclear Regulatory Commission (NRC) Regulatory Guide (RG) 1.183 (Ref. 1). A minimum water level of 7 m (23 ft) allows a decontamination factor of 200 to be used in the accident analysis for iodine. This relates to the assumption that 99.5% of the total iodine released from the pellet to cladding gap of all the dropped fuel assembly rods is retained by the refueling pool water.

The fuel handling accident analysis inside containment is described in Reference 2. With a minimum water level of 7 m (23 ft) and a minimum decay time of 100 hours prior to fuel handling, the analysis and test programs demonstrate that the iodine release due to a postulated fuel handling accident is adequately captured by the water and offsite doses are maintained within allowable limits (Ref. 4).

Refueling water level satisfies Criterion 2 of 10 CFR 50.36(c)(2)(ii).

LCO
A minimum refueling water level of 7 m (23 ft) above the reactor vessel flange is required to ensure that the radiological consequences of a postulated fuel handling accident inside containment are within acceptable limits (Ref. 3).
Bases

Applicability
Specification 3.9.6 is applicable during CORE ALTERATIONS, except during latching and unlatching of control rod drive shafts, and when moving irradiated fuel assemblies within containment. The LCO minimizes the possibility of a fuel handling accident in containment that is beyond the assumptions of the safety analysis. If irradiated fuel is not present in containment, there can be no significant radioactivity release as a result of a postulated fuel handling accident. Requirements for fuel handling accidents in the spent fuel pool are covered by LCO 3.7.14, “Spent Fuel Pool Water Level.”

Actions
A.1 and A.2
With a water level of ˂ 7 m (23 ft) above the top of the reactor vessel flange, all CORE ALTERATIONS and operations involving movement of irradiated fuel assemblies shall be suspended immediately to ensure a fuel handling accident cannot occur. The suspension of CORE ALTERATIONS and irradiated fuel movement shall not preclude completion of movement to a safe position.

A.3
In addition to immediately suspending CORE ALTERATIONS and movement of irradiated fuel assemblies, actions to restore refueling water level must be initiated immediately.

Surveillance Requirements
SR 3.9.6.1
Verification of a minimum refueling water level of 7 m (23 ft) above the top of the reactor vessel flange ensures that the design basis for the postulated fuel handling accident analysis during refueling operations is met. Water at the required level above the top of the reactor vessel flange mitigates the consequences of a postulated fuel handling accident inside containment which results in damaged fuel rods (Ref. 2).

The Frequency of 24 hours is based on engineering judgment and is considered adequate in view of the large volume of water and the normal procedural controls of valve positions, which make significant unplanned level changes unlikely.
BASES

REFERENCES


2. FSAR, Subsection 15.7.4.

3. NUREG-0800, Section 15.0.3, March 2007.

4. 10 CFR 50.34.
B 3.9 REFUELING OPERATIONS

B 3.9.7 Unborated Water Source Isolation Valve – MODE 6

BASES

BACKGROUND During MODE 6 operations, isolation valve (CV-186) for reactor makeup water source containing unborated water that is connected to the Reactor Coolant System (RCS) must be closed to prevent unplanned boron dilution of the reactor coolant. The isolation valve must be secured in the closed position. This valve is a manual valve and does not have an indication of position in the control room (Ref. 1).

The Chemical and Volume Control System is capable of supplying borated and unborated water to the RCS through various flow paths. Since a positive reactivity addition made by reducing the boron concentration is inappropriate during MODE 6, isolation of all unborated water sources prevents an unplanned boron dilution.

APPLICABLE SAFETY ANALYSES The possibility of an inadvertent boron dilution event (Ref. 2) occurring during MODE 6 refueling operations is precluded by adherence to this LCO, which requires that potential dilution sources be isolated. Closing the required valve during refueling operations prevents the flow of unborated water to the filled portion of the RCS. The valve is used to isolate unborated water sources. This valve has the potential to indirectly allow dilution of the RCS boron concentration in MODE 6. By isolating unborated water sources, a safety analysis for an uncontrolled boron dilution event is not required in MODE 6.

Isolation of unborated water sources to preclude a reduction in RCS boron concentration satisfies Criterion 2 of 10 CFR 50.36(c)(2)(ii).

LCO This LCO requires that flow paths to the RCS from the unborated water sources be isolated to prevent unplanned boron dilution during MODE 6 and thus avoid a reduction in SDM.

APPLICABILITY This LCO is applicable in MODE 6 to prevent an inadvertent boron dilution event by ensuring isolation of all sources of unborated water to the RCS.
Continuation of CORE ALTERATIONS is contingent upon maintaining the unit in compliance with this LCO. With the valve used to isolate unborated water sources not secured in the closed position, all operations involving CORE ALTERATIONS must be suspended immediately. The Completion Time of “immediately” for performance of Required Action A.1 shall not preclude completion of movement of a component to a safe position.

Preventing inadvertent dilution of the reactor coolant boron concentration is dependent on maintaining the unborated water isolation valve secured closed. Securing the valve in the closed position ensures that the valve cannot be inadvertently opened. The Completion Time of “immediately” requires an operator to initiate actions to close an open valve and secure the isolation valve in the closed position immediately. Once actions are initiated, they must be continued until the valve is secured in the closed position.

Due to the potential of having diluted the boron concentration of the reactor coolant, SR 3.9.1.1 (verification of boron concentration) must be performed. The Completion Time of 4 hours is sufficient to obtain and analyze a reactor coolant sample for boron concentration.

This valve is to be secured closed to isolate possible dilution paths. The likelihood of a significant reduction in the boron concentration during MODE 6 operations is remote due to the large mass of borated water in the refueling pool and the fact that all unborated water sources are isolated, precluding a dilution. This Surveillance demonstrates that the valve is closed. The 7 day Frequency is based on engineering judgment and is considered reasonable in view of other administrative controls that will ensure that the valve opening is an unlikely possibility.

1. FSAR, Subsection 9.3.4.
2. FSAR, Subsection 15.4.6.
B 3.9  REFUELING OPERATIONS

B 3.9.8  Decay Time

BASES

BACKGROUND  The movement of irradiated fuel assemblies within containment or in the fuel handling area inside the auxiliary building requires allowing at least 100 hours for radioactive decay time before fuel assembly handling can be initiated. During fuel handling, the decay time ensures that sufficient radioactive decay has occurred in the event of a fuel handling accident (Refs. 1 and 2). Sufficient radioactive decay of short-lived fission products would have occurred to limit offsite doses from the accident to within the values reported in FSAR Chapter 15 (Ref. 2).

APPLICABLE SAFETY ANALYSES  During movement of irradiated fuel assemblies, the radioactive decay time is an initial condition design parameter in the analysis of a fuel handling accident inside containment or in the fuel handling area inside the auxiliary building, as postulated by Regulatory Guide 1.183 (Ref. 1).

The fuel handling accident analysis inside containment or in the fuel handling area inside the auxiliary building is described in Reference 2. This analysis assumes a radioactive decay time not > 100 hours.

Radioactive decay time satisfies Criterion 2 of 10 CFR 50.36(c)(2)(ii).

LCO  A minimum radioactive decay time of 100 hours is required to ensure that the radiological consequences of a postulated fuel handling accident inside containment or in the fuel handling area inside the auxiliary building are within the values calculated in Reference 2.

APPLICABILITY  Radioactive decay time is applicable when moving irradiated fuel assemblies in containment or in the fuel handling area inside auxiliary building. The LCO minimizes the possibility of radioactive release due to a fuel handling accident that is beyond the assumptions of the safety analysis. If irradiated fuel assemblies are not being moved, there can be no significant radioactivity release as a result of a postulated fuel handling accident. Requirements for fuel handling accidents in the spent fuel pool are also covered by LCO 3.7.14, “Spent Fuel Pool Water Level” and LCO 3.9.6, “Refueling Water Level.”
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<th>ACTIONS</th>
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<td>With a decay time of &lt; 100 hours, all operations involving movement of irradiated fuel assemblies within containment or in the fuel handling area inside the auxiliary building shall be suspended immediately to ensure that a fuel handling accident cannot occur. The suspension of fuel movement shall not preclude completion of movement to a safe position.</td>
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<th>SURVEILLANCE REQUIREMENTS</th>
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<td>Verification that the reactor has been subcritical for at least 100 hours prior to movement of irradiated fuel assemblies in the reactor pressure vessel to the refueling pool in containment or to the fuel handling area inside the auxiliary building ensures that the design basis for the analysis of the postulated fuel handling accident during refueling operations is met. Specifying radioactive decay time limits the consequences of damaged fuel rods that are postulated to result from a fuel handling accident (Ref. 2).</td>
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<td>2. FSAR, Subsection 15.7.4.</td>
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