

**PP&L**

## CALCULATION COVER SHEET

CALC. NO. M-VLV-418

FILE NO. R2-1M

SUPERSEDED BY (N/A)

SAFETY-RELATED	<input checked="" type="checkbox"/>
ASME III OR XI	<input type="checkbox"/>
OTHER QUALITY	<input type="checkbox"/>
NON QUALITY	<input type="checkbox"/>

PROJECT SSES MOV Program

ER/CTN NO. 402288

DESIGN ACTIVITY/PMR NUMBER

PAGE 1 OF 26

TITLE/DESCRIPTION MOV Data Detail, Limit Switch Settings and Torque Switch Settings  
for: HV 2 55 F003

SYSTEMS AFFECTED 52

## STATEMENT OF PROBLEM

NRC Generic Letter 89-10 required establishment of a program to provide for the testing, inspection and maintenance of safety-related motor-operated valves. This calculation provides the data details for the valve identified above which will be used to prepare the Data Detail Drawing which will support the testing, inspection and maintenance activities.

## DESIGN BASIS (EPM-QA-208 OR EPM-QA-400)

See Section 2.0 for Methodology.

This calculation serves as the Design Input for drawing M-1420

## REFERENCES/FORMULAE

See Section 3.0 for Inputs/References.

## SUMMARY/CONCLUSIONS

See Section 6.0 for Results/Conclusions.

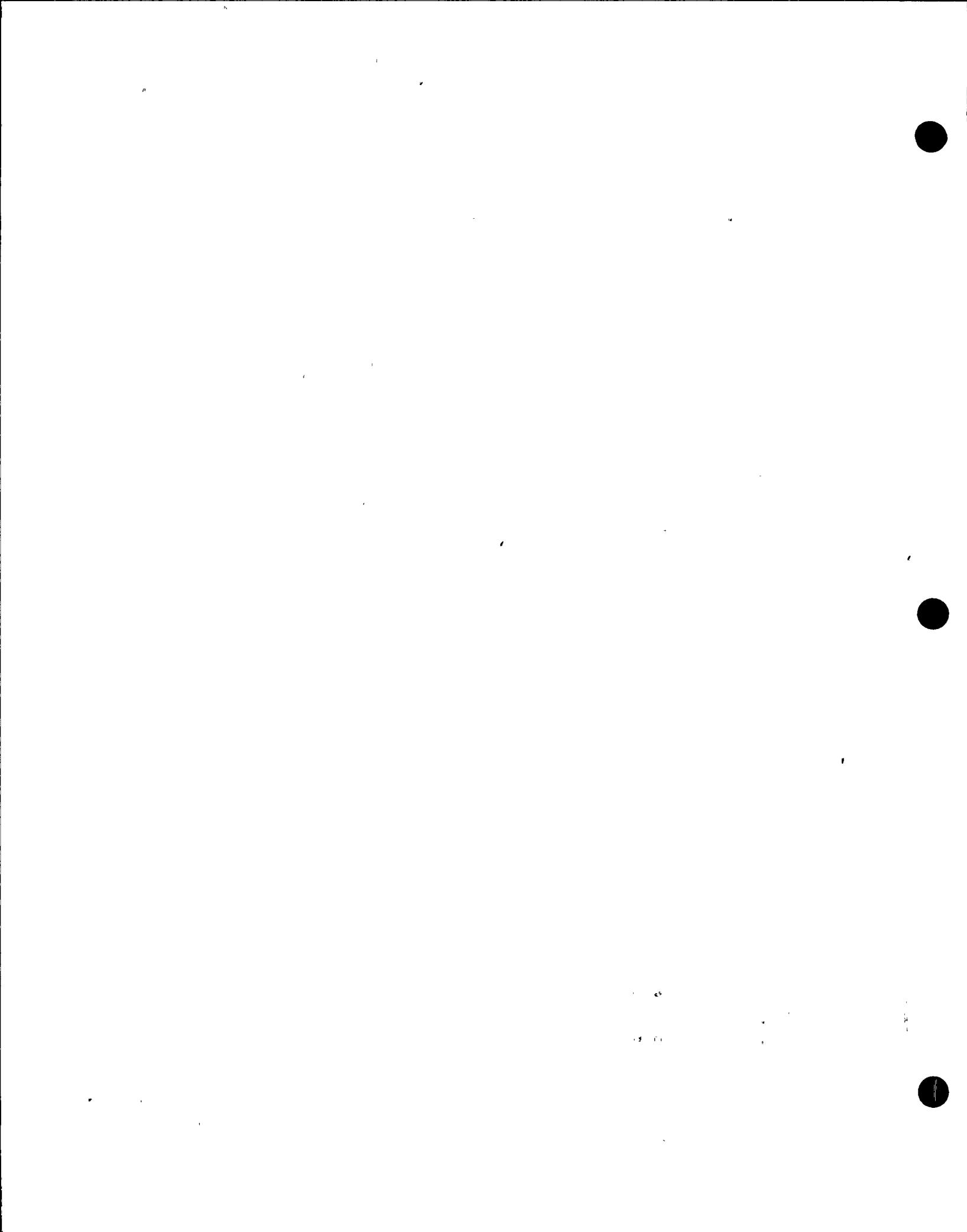
Available Motor Start  
Torque = 44 ft-lbs

Rev 2 added page 22c

## ENGINEERING TURNOVER

(ETO) BINDER AFFECTED?  YES-If Yes enter: Binder # \_\_\_\_\_ Vol. \_\_\_\_\_  
 9110100070 911004  
 PDR ADDOCK 05000337 Calc. File \_\_\_\_\_ Pgs. \_\_\_\_\_  
 Q PDR  NO

REV. NO.	DATE	PREPARED BY	REVIEWED/CHECKED BY	DATE	APPROVED BY	DATE
0	3/15/91	CDAkula	DHunt	3-21-91	RWAnderson	5/30/91
1	9-16-91	DHunt	M.Lanchison	9/21/91	RWAnderson	9/21/91
2	10-1-91	DHunt	R.W.McLulley	10-2-91	R.W.Anderson	10-13-91



Or 21/11  
2011 3-22-11

Calculation Contents

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Attachments 11 Pages

## 1.0 Purpose/Scope

The purpose of this calculation is to develop all of the information necessary to create a Motor Operated Valve Data Detail Drawing for the subject MOV. In order to meet this end the following specific activities will be performed in this calculation to complete the MOV Detail Drawing for the subject MOV:

- 1.1 Research existing design documents and records for the MOV to determine best available configuration data. This data will be used as input to the MOV Data Detail Drawing as well as to the calculations to be performed herein.
- 1.2 An actuator sizing calculation will be performed to determine the required actuator parameters (e.g. actuator size, motor size, spring pack, torque switch settings, etc.).
- 1.3 Using the results of Item 1.2, diagnostic test acceptance criteria will be established.
- 1.4 Based on the design function of the MOV, geared limit switch settings will be determined. For the purposes of this calculation, the limit switch functions to be considered will be limited to:
  - a.) Torque switch bypass (open and close direction)
  - b.) Full open limit switch
  - c.) Valve position indication
- 1.5 A review of previously approved spring pack Replacement Item Equivalency Evaluations (RIEE's or RIE's) will be performed for the particular MOV being evaluated. Changes to these RIE's will be processed as necessary based on the results of this calculation.

## 2.0 Methodology

Existing design documents, modifications and field work authorizing documents will be reviewed to identify required inputs to the MOV Data Detail Drawing. Lists of the required inputs as well as a cross reference to the data source are provided in Section 3.0 of this calculation.

**2.1 Actuator Sizing Calculations:** These will be performed using the software version of Mechanical Design Standard (MDS) Number 01 (Input a.). The following methods will be used to compliment the techniques used in the software package:

- a.) The active valve stroke length is a required program input which allows the program to calculate a design valve stroke time. The active stroke length will be calculated based on the following expression:

$$\text{ACTIVE STROKE LENGTH} = Z * \text{FSL}$$

Where:

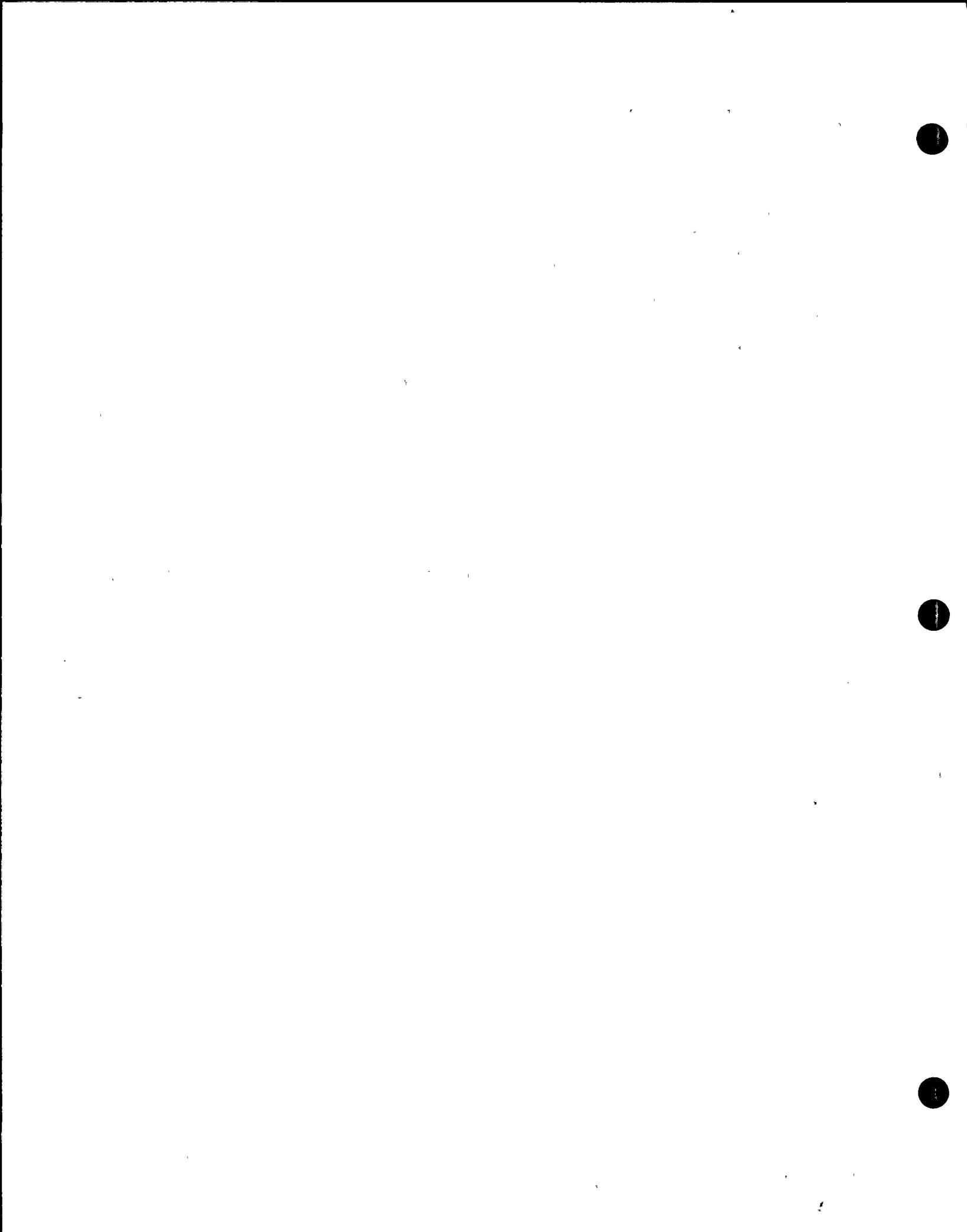
Z = The setpoint of the full open limit switch in percent open (typically 97%)

FSL = Full Valve Stroke Length from the closed position to the fully open (backseated) position. If FSL is not specifically known it can be calculated using the following expression:

$$\text{FSL} = \frac{\text{HWT} * \text{SL}}{\text{HGR}}$$

Where:

HWT = The number of handwheel turns required for the valve to travel from fully closed to fully



open.

SL = The valve stem lead.

HGR = The overall handwheel gear ratio.

- b.) Program overrides will be used to allow the calculation to reflect the current configuration of the MOV.
- c.) Once an expected motor run torque is calculated, a typical motor curve will be consulted to determine an estimated midstroke loaded motor speed (RPM). The calculation will be rerun using this value as an override, the result being a more representative design stroke time.
- d.) For gate valves the calculation will be run using a valve factor of .3.
- e.) The calculation will be run with various acceptable spring packs to allow for flexibility in future replacement. Only spring packs approved on spring pack equivalencies will be included on the MOV Data Detail Drawing.

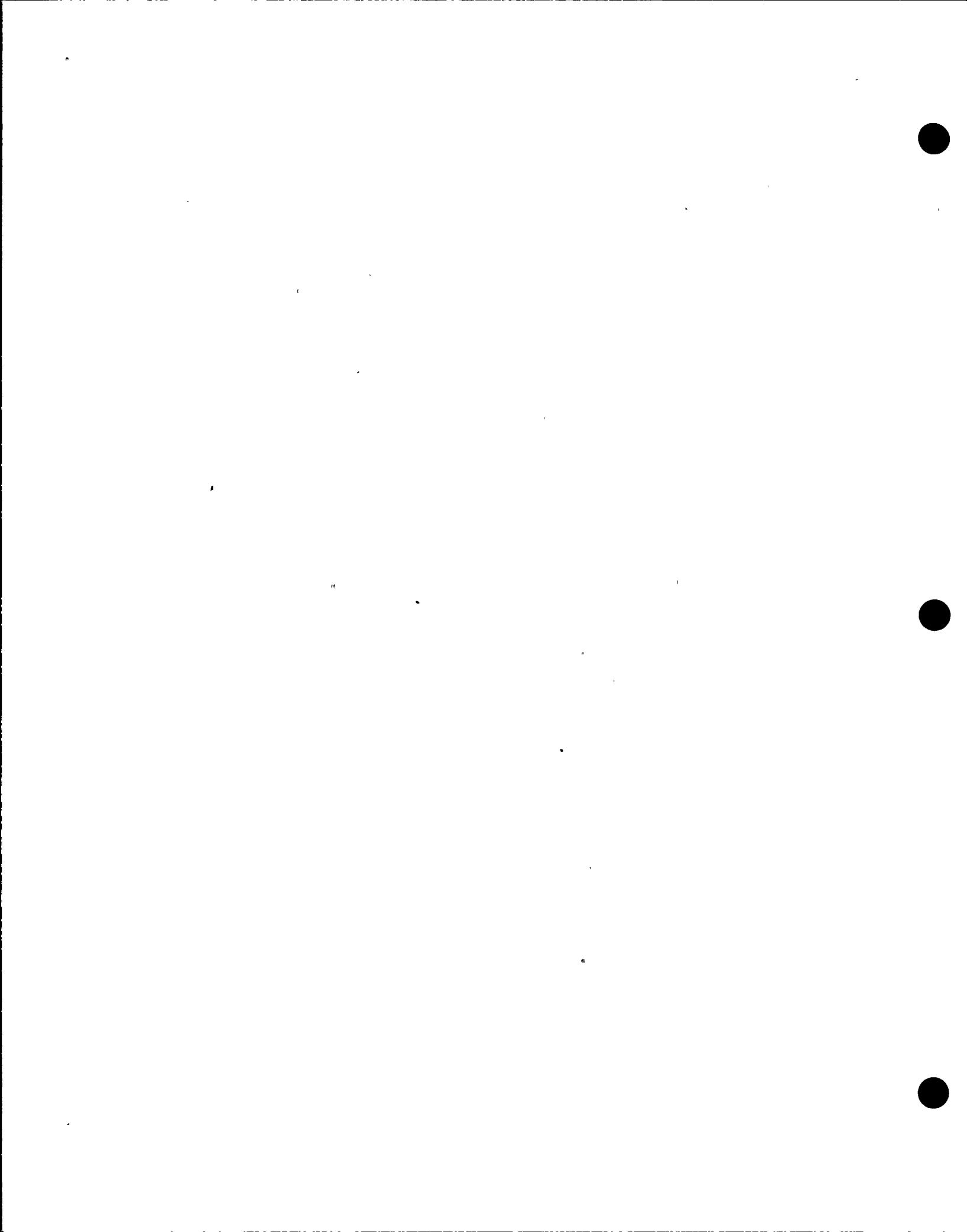
2.2 VOTES Diagnostic Thrust Acceptance Criteria: Once the actuator sizing has been completed diagnostic test thrust acceptance criteria will be established using the following methodology:

- a.) The Minimum Allowable Thrust will be established as 115% of the design calculated required thrust. This allows for at least 10% error in the diagnostic test results and 5% variation in torque switch repeatability.
- b.) The Maximum Allowable Running Thrust will be established as the Stuffing Box Friction load used in the actuator sizing calculations.
- c.) The Maximum Allowable Thrust will be established as the thrust corresponding to the minimum of the following:

AW 9-16-91 QMP 9/21/91

- 1.) Actuator thrust rating,
  - 2.) 120% of the equivalent thrust at maximum allowable actuator output torque,
  - 3.) Maximum allowed valve thrust (if available).
  - d.) The acceptance criteria at each torque switch setting will be specified as the expected thrust +/- 20% .
  - e.) In all cases items a.) and c.) shall take precedence over item d.).
- 2.3 Limit Switch Settings: This section of the calculation will determine the appropriate geared limit switch settings for valve control and position indication. The limit switch settings will be established per the requirements of MDS-03 (Input b.). The switch settings will be specified in percentages of physical stem travel from either full open or full closed.

2.4 Other Items



4/2/89/11  
DWH 3-21-91

### 3.0 Inputs/References

3.1 The principle design inputs for this calculation are:

- a.) MDS-01 "Design Standard for the Sizing of Limitorque Actuators Including Thrust Calculation, Actuator Sizing, Spring Pack Selection and Torque Switch Setting Determination." Revision 1.
- b.) MDS-03 "Design Standard for Determining and Setting Valve Motor Actuator Limit Switches." Revision 0.

3.2 Information required for entry on the MOV Data Detail Drawing and as input to this calculation is provided on pages 9 through 11 of this calculation. Reference Numbers are provided for each of the entries. A listing of all references is provided on Page 12 (Note: Copies of references not readily available are provided as attachment to this calculation).

## General Valve Design

	Data Value	Reference No.
Valve Manufacturer	Anchor Darling	1
Vendor Drawing Number	93-13802	1
Valve Serial Number		
Valve Quality Class	Q	1
Valve ASME Section III Edition and Class	1971 w/winter '72 Addlclm1	1
Valve Location (Inside/Outside Containment)	OUTSIDE	8
Valve Type	GATE	1
Valve Pressure Class	600	1
Valve Size (Inches)	10"	1
Valve Seat Area (Inches Squared)	66.33	2
<b>Stem Information:</b>		
Stem Diameter (Inches):		
At Stuffing Box Location	1.875	13
At Threaded Portion	1.875	13
Thread Pitch/Lead	0.333   0.667	13
Stem Material	A276-410	1
Original Design Stroke Time (Seconds)	50	3

CA 8/81

08-3-22-91

DHS 9-16-91  
QMP 9/19/91

Reference No.

## General Valve Design (Cont.)

Data Value

## Process Parameters:

Flow Medium

STEAM

3

Design/Maximum Pressure (PSIG)

1250 / 1350

7

Design/Maximum Temperature ( F )

585 / 585

7

Design/Maximum Flow (GPM or LB/HR) <sup>CA</sup>

LATER

Throttled Flow (GPM or LB/HR)

N/A

## Max. Operating Differential Press. (PSID):

Opening Direction

O

12

Closing Direction

1146

12

④

## Additional Physical Parameters:

Valve Max. Thrust Capability (LBS)

NOT AVAILABLE

End Connections/Rating

BW Sch 80

1,3

Body Material

A 216 WCB

1

Disc Trim Material

STELLITE

1,3

Body Seat Trim Material

STELLITE

1,3

Guide Rib Facing (Gate Valves Only)

A 216 WCB

1

Drain/Bypass Required (Y/N)

N | N

3

# Actuator Design

CALC # M-VLV- 415 Rev 1  
Page 10 of 26  
CA 3/16/91

Reference No. DXA 3-21-91  
DJAH 9-16-91  
JMP 4-21-91

## General:

	Data Value	
Actuator Quality Class	Q	8
Safety Function (Open/Close)	C	<del>Page 6 Ex. 4.4.4</del> 4
Actuator Manufacturer	LIMITORQUE	1
Main Unit ( e.g. SMB):		
Actuator Order Number	381264-H	11
Actuator Serial Number	205546	11
Actuator Size	SMB-1-40	1
Gearing Information:		
Motor Pinion Number of Teeth	33	11
Worm Gear Number of Teeth	39	11
Worm to Worm Gear Ratio	66:1	11
Overall Actuator Ratio	78 *	11
Lost Motion Drive Sleeve (Y/N)		
Auxiliary Worm/Bevel Gear Unit:		
Unit Order Number	N/A	
Unit Serial Number	N/A	
Unit Type/Size	N/A	
Unit Gear Ratio	N/A	
Overall Handwheel Ratio	49 : 1	10
Handwheel Orientation (Top or Side Mount)	SIDE	1
Handwheel Efficiency	25.0	10

$$* \frac{39}{33} \times 66 = 78$$

CALC # M - VLV - A16 Rev 1  
Page 11 of 26  
G318191

# Electrical/Motor Design Information

	Data Value	Reference No.
Motor Class (1E/Non1E)	IE	14
Power Supply Type (AC/DC)	DC	11
Power Source	20264031	12
Voltage Supply/Phase/Frequency	250 / NA / NA	11
Motor Manufacturer	RELIANCE	11
Motor Serial Number		
Design Motor Speed (RPM)	1900	11
Motor Start/Run Torque (ft-lbs)	40   8	11
Motor Horsepower	2.9	5
Service Factor	1.0	5
Motor Type/Frame Size	/ L186A	5
Motor Frame Design/Enclosure Type		
Winding Type (DC Motors)		
Motor Duty Rating	5	5
Insulation Class	B	5
Temp. Rise/Ambient Temp. ( C )	40	5
Full Load/ <del>Locked</del> Rotor Current (Amps) or KVA Code (LRIC) at Supply Voltage (See Note 3)	11.1   85.4	5
DC Motor Field Current (Amps)		
Limit Switch Comp/Motor Spaceheaters (Y/N)		

Calc No:  
M-VLV- 418 Rev 1  
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Cr 41811 D DH 9.16.9  
DH 3-21-91 9MP 9/9/91

REFERENCES:

1. VALVE VENDOR DRAWING NO: 93-13802 Rev F  
(FF 110100 6101)
2. VALVE VENDOR DESIGN REPORT NO: 8856-P-10A-10 REV: 1 (Attached)  
(FF 110101 0201)
3. VALVE SPEC<sup>V</sup> NO: 8856-P-10 PAGE 9 OF 15. REV: 4 (Attached)  
DATA SHEET
4. DESIGN BASIS DEVELOPMENT PRIORITY 2 MOVs:SEA-238, REV: 0 (9/19/91)
5. MOTOR OPERATOR'S INFORMATION SHEET FOR ORDER NO: 381264-H (Attached)
6. DESIGN STROKE TIME CALC NO: M-VLV- 029, REV. 0
7. SEIS PIPE INDEX Rev 6
8. P&ID NO: M-2155 REV NO: 23
9. IN SERVICE TESTING OF PUMPS AND VALVES M-1437.REV. NO: (NOT USED)
10. LIMITORQUE STANDARD HANDWHEEL RATIO CHART ( SEL-11). (Attached)
11. WORK AUTHORIZATION NOS: V80063 and V 60388 (Attached)
12. ~~VALVE DESIGN BASIS DOCUMENT NO: SEA-M-127, REV: 0~~ (Attached) | A
13. Anchor Darling letter dated 2-20-1990 (Attached)
14. Schematic Diagram E-152 sheet 31 Rev 11
15. Anchor Darling Teletype dated 3/28/91 (copy attached) | A
16. E-AAA-619 Rev 3 (Applicable Sheet Attached)

4 0449-16-91  
QTR 9/19/91

#### 4.0 Assumptions

1. For the purposes of this calculation, attempts have been made to verify design information against actual as-installed information as documented in Plant Work Authorizations. Where actual as-installed information is unavailable the original design information will be used. Upon completion of field as-built verification, any discrepancies will be reconciled and this calculation shall be revised as appropriate.
2. Stuffing box friction values will be consistent with the empirical values listed in MDS-01 unless otherwise noted herein.
3. Unless noted otherwise, the stem factor used herein will be based on a coefficient of friction of 0.15 (Reference /5 ). This is consistent with the original design seismic analysis. The SSES MOV preventative maintenance and trending program will ensure the valve stems/stem nuts are maintained in a manner which supports this assumption.
4. The minimum voltage available will be assumed to be 80% unless noted otherwise. If the electrical voltage drop calculations show this to be unconservative a lower value will be used. If the use of 80% initially produces unacceptable results the electrical voltage drop calcs will be consulted in an attempt to remove some of the conservatism.
5. Gate valve sizing calculations will be run using a valve factor of .3.
6. During the initial preparation of this calculation, the valve maximum thrust capability may not yet be available. In these cases, the maximum thrust/torque shall be based on the following:

##### Maximum Torque

The maximum allowed torque shall be the lesser of the maximum torque calculated by the MDS01 software or the torque corresponding to the original design maximum torque switch setting.

##### Maximum Thrust

The maximum allowed thrust shall be the lesser of the actuator thrust rating or 120% of the equivalent thrust at the maximum allowable actuator output torque.

CKJ/dgj  
JUL 3-21-91

## 5.0 Calculations

### 5.1 Actuator Sizing Calculation

The results of the actuator sizing calculations are provided as follows:

<u>Run #</u>	<u>Conditions</u>	<u>Calc. Pages</u>
1.	SP. pack long 600-0007-1 Valve factor 0.3	21-21A
2.	SPRING PAC. 0068 VALVE FACTOR .3	22-22A
3.		
4.		

### 5.2 VOTES Diagnostic Thrust Acceptance Criteria

The calculation of the thrust acceptance criteria was performed per the method outlined in 2.2.

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### 5.3 Limit Switch Settings

Page 15

## Geared Limit Switch Settings

	Data Value	Reference No.
Electrical Schematic & Connection Diagram No.	E-152 SF3 / E380-14	14
Full Stroke Length & Number of Handwheel Turns	9.95	750 Page 6 Ref 11
Limit Switch Number	Function	Setpoint (See Note 4)
ZS-1		
ZS-2		
ZS-3	CLOSE L/S	3.15
ZS-4	OPEN L/S	0-100
ZS-5		
ZS-6		
ZS-7	OPEN	3% open
ZS-8	CLOSING	97% close
ZS-9		
ZS-10		
ZS-11		
ZS-12		
ZS-13		
ZS-14		
ZS-15		
ZS-16		

## Spring Pack/Torque Switch Settings

Data Value

Minimum Required Torque (ft-lbs)

577

Page 22

Maximum Allowable Torque (ft-lbs)

550

Original Design

Replacement 1

Replacement 2

Spring Pack Number

60-600-00001

60-600-0068-1

5

Limitorque B/M  
Number

0701-212

Lowest Allowed Torque  
Switch Setting

3.0\*

2.25

Corresponding Expected  
Actuator Output Torque  
(ft-lbs)

641

638

Highest Allowed Torque  
Switch Setting

3.75\*\*

2.75

Corresponding Expected  
Actuator Output Torque  
(ft-lbs)

845

838

RIE Number

91-0154

\* USED PER Computer Selection

\*\* 3.75 is used as the maximum setting per computer selection. The original limiting setting of 3.5 / 780 ft-lbs given on Ref.5 is no longer applicable because Limitorque based it on the reduced voltage pullout with the OAR = 103.7. Using the current OAR of 78 and the pullout calculated on page 22B, a limit of 850 ft-lbs is acceptable.

## VOTES Thrust Acceptance Criteria

	Data Value	Reference No.
Minimum Thrust Required (lbs)	32740	1.15
Maximum Total Thrust Allowable (lbs)	45000	$\leq 850/0.22 \times 1.2$
Maximum Allowable Running Thrust (lbs)	2500	Page 21A

Torque Switch Setting	Acceptable Thrust Range at Torque Switch Trip (lbs)		
	Original Design Spring Pack Installed	Replacement 1 Spring Pack Installed	Replacement 2 Spring Pack Installed
1.0			
1.25			
1.5			
1.75			
2.0			
2.25	512	32740 - 37650	
2.50	750	32740 - 44330	
2.75	888	33030 - 45000	
3.0	641	32740 - 37890	
3.25	709	32740 - 41910	
3.50	775	32740 - 45000	
3.75	845	33300 - 45000	
4.0			

CALCULATION SHEET  
ACTUATOR SIZING

PP&L CALC NO.  
PAGE 19 OF 26  
MDS-01-03 Rev. 1 [5 OF 7]  
Valve tag number  
HV255F003

## CALCULATION:

(A S INSTALLED)

SELECTED ACTUATOR &  
OVERALL ACTUATOR RATIO

SMB-1

78.00  
(SEE SECTION 2.4)

Select UNIT EFFICIENCIES based on actuator &amp; overall actuator ratio [APPENDIX D]

Unit PULLOUT Efficiency	35	SEE NOTE 1 BELOW
Unit RUN Efficiency	45	
Unit STALL Efficiency	45	

Revise UNIT RPM, STEM SPEED, and STROKE TIME based  
the selected OVERALL ACTUATOR RATIO:

Revised UNIT RPM	$\frac{2140}{78} =$ 27.44 RPM	[eqn.10]
= <u>Motor Design Speed (rpm)* (SEE NOTE 2)</u> Overall Actuator Ratio		

Revised STEM SPEED (in/min)	$27.44 \times 0.67$ = 18.38 IN/MIN	[eqn. 11]
= Revised Unit RPM x Stem Lead		

DESIGN STROKE TIME (min)	$\frac{9.95}{18.38} \text{ (see section 2.4)}$ = 0.5412 MIN = 32.47 Seconds. MIN CA (see Para C.3.2) Page 23	[eqn. 12]
= <u>Design Stroke Length (in)</u> <u>Revised Stem Speed (in/min)</u>		

\* If motor curves are available, motor speed should be determined based on actual Motor Run Torques (Eqn. 15). If this option is chosen, the results of equations 10, 11, & 12 cannot be determined until the results of equations 13 & 15 are known.

NOTE: 1. Units efficiencies are based on actual installed worm gear sets. 78 OAR is not used for unit efficiency selection ref 6 (Page 4-87).

- 2. BASED ON MOTOR RUN TORQUE OF 2.81 AND THE MOTOR CURVE DRW6 # 4100 82-1643 dated 1/18/68 FOR ULV HV-EAI-F003 (ref 6 Page 11), THE MOTOR RPM = 2140

CALCULATION SHEET  
ACTUATOR SIZING

PP&L CALC NO. M-VW-418 Rev 1  
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MDS-01-03 Rev.1 [6 OF 7]  
Valve tag number  
HV255FO03

CA-3(19A) 10 MAR 16 91  
DWH 3-12-91 PWD 1/1/91

Select APPLICATION FACTORS [APPENDIX E]

Selected APPLICATION FACTORS

0.9 Standard

Resultant Application Factor

0.9

Calculated MOTOR START Torque

Stem Torque

Overall Actuator Ratio x Unit Pullout Efficiency  
x Application Factor

$$\frac{577}{567.3} = \frac{23.5}{23.1} \text{ Nm}$$

FT-LBS

[ eqn. 13 ]

Calculated MOTOR RUN Torque

Trun x FS

Overall Actuator Ratio x Unit Run Efficiency

$$\frac{5664.3}{4846.24 \times 0.0203} = \frac{3.3}{2.85} \text{ Nm}$$

FT-LBS

[ eqn. 15 ]

Reduced Voltage Requirements (if applicable):

Revised MOTOR START Torque (AC)

$$= \frac{\text{Calculated Motor Start Torque}}{(\% \text{ Voltage Available})^2}$$

N/A

FT-LBS

[ eqn. 16 ]

Revised MOTOR START Torque (DC)

$$= \frac{\text{Calculated Motor Start Torque}}{\% \text{ Voltage Available}}$$

$$\frac{23.5}{0.8} = \frac{29.4}{28.87} \text{ Nm}$$

FT-LBS

[ eqn. 17 ]

CALCULATION SHEET  
SPRING PAC SELECTION  
MOTOR SIZE SELECTION

PP&L CALC NO. M-VLV-418, Rev 1  
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MDS-01-03 Rev.1 [7 OF 7]  
Valve tag number  
HV255FOO3

MOTOR SIZE SELECTION:

Select MOTOR SIZE based on criteria stated in MDS-01 section 5.2.8.2

INSTALLED

Selected MOTOR SIZE

40 FT-LB

per ref 11 (V80063) <sup>WT#</sup>

MOTOR SIZE CHECK:

Selected Motor Size		Criteria
40	>	<del>23.1 23.5</del> <sup>ON</sup> Calc. MOTOR START torque
40	>	<del>28.87 29.4</del> <sup>ON</sup> Revised MOTOR START torque
40	>	<del>5x2.83 = 14.15</del> <sup>ON</sup> 5 x Calc. MOTOR RUN torque

MOTOR STALL:

Stall Torque (ft-lbs)		
= Selected Motor Size (ft-lbs) x Overall actuator ratio x Stall Efficiency x 1.1		$40 \times 78 \times 0.45 \times 1.1$ [eqn. 19]

Stall Thrust ( $T_{stall}$ ) lbs		
= Stall Torque/FS		$\frac{1544.4}{0.0203} = 76079$ [eqn. 18] LBS

MOTOR STALL CHECK:

Stall Thrust ( $T_{stall}$ )		CRITERIA
76079	LBS	$112500$ LBS MAX Valve Thrust Rating or 2.5 x Actuator Thrust Rating

PP&amp;L REVISION 1.90226 DATED 08-14-90 - TODAY IS 09-16-1991 12:13:42

## VALVE Info (Input) (TABLE # 1 ) - FILE: 155F003

Page 1 of 2

Calculated by:

Checked by:

Valve MANUFACTURER: ANCHOR DARLING  
 Valve TYPE (GATE or GLOBE): GATE  
 Valve SIZE: 10  
 Valve TAG Number: HV255F003  
 Valve VENDOR DRAWING number: 93-13802  
 Valve PP&L Drawing number:  
 Valve LOCATION:  
 Valve SYSTEM:  
 Valve LINE (ie. PIPE LINE I.D.):  
 Valve MAXIMUM Design THRUST: 0

## VALVE Data (Input) (TABLE # 2 ) - FILE: 155F003

ANCHOR DARLING GATE Tag: HV255F003

Valve STEM DIAMETER (Inches):	1.875
Valve STEM PITCH:	.333
Valve STEM LEAD (Inches):	.667
Valve SEAT AREA (Sq-Inches):	66.33
Valve STEM AREA (Default = 0 Sq-Inches):	2.761172
Req'd STEM SPEED (0 or 3-6=Globe or 12-14=Gate):	0
Valve STROKE LENGTH (Inches):	0
Req'd STROKE TIME (Seconds):	0 ( 0 Min.)
Valve INLET PRESSURE (PSIG):	1146
Valve PRESSURE DROP (PSIG):	1146
Valve Factor (.2 or .3=Gate 1.1=Globe):	.3
Valve STUFFING BOX FRICTION (Default = 0 Lbs):	2500
Valve STEM/NUT Coeff. FRICTION (0 .15 or .2):	.15
Manual ACTUATOR RATIO Selected:	92.4 : 1
Manual ACTUATOR Selected:	18
Manual SPRING PAC CURVE Selected:	27

## MOTOR Data (Input) (TABLE # 3 ) - FILE: 155F003

ANCHOR DARLING GATE Tag: HV255F003

Motor TYPE (AC or DC):	DC
Motor RPM (900 1800 or 3600):	1800
Motor REDUCED VOLTAGE Percent (Default=0.8):	.8
HIGH TEMPERATURE application (Y or N):	N
COMPOUND motor GEAR application (Y or N):	N
AIR MOTORS (Y or N):	N
MODULTRONIC MOTORS (Y or N):	N
HILO Applications (Y or N):	N
Non-Rising Stem - OPERATOR thrust (Y or N):	N
Non-Rising Stem - VALVE thrust (Y or N):	N
Manual MOTOR Selected:	16

DRAFT 9-16-91 QMP 9/1/91

PP&amp;L REVISION 1.90226 DATED 08-14-90 - TODAY IS 09-16-1991 12:13:42

## Calculation RESULTS (TABLE # 4) - FILE: 155F003

Page 2 of 2

Calculated by:

Checked by:

ANCHOR DARLING GATE Tag: HV255F003

Valve STEM FACTOR: 0.0203  
 STUFFING BOX FRICTION: 2500 Lbs  
 THRUST: 28468.56 Lbs  
 STEM TORQUE: 576.943 Ft-Lbs  
 STEM SPEED: 13.71537 Inches/Min.  
 UNIT RPM: 20.56277 RPM  
 Design STROKE TIME: 0 Seconds  
 OVERALL ACTUATOR RATIO: 92.4 ~~Actuator Ratio~~

\* SMB-1 ACTUATOR selected having a 92.4 - 171.6 Ratio RANGE (IACT= 18 )

\* SMB-1 92.4 - 171.6 UNIT Efficiencies: PULLOUT= 35 RUN= 45 STALL= 45

\* \* USER Selected ACTUATOR

\* \* USER Selected ACTUATOR Ratio

used 1800 Rpm 'DC' Motor OPERATING at 1900 Rpm  
~~APPLICATION FACTOR: .9~~

~~Calc. MOTOR START TORQUE: 19.82213 Ft-Lbs  
 MIDSTROKE RUN THRUST: 5664.303 Lbs  
 Calc. MOTOR RUN TORQUE: 2.760765 Ft-Lbs (5 X RUN= 13.80382 )~~

40 Ft-Lbs SMB-1 MOTOR with 106 Maximum Ratio Selected (IMTR= 16 )

\* \* USER Selected MOTOR

~~Revised MOTOR START TORQUE: 24.77767 Ft-Lbs  
 STALL TORQUE: 1829.52 Ft-Lbs  
 STALL THRUST: 90275.46 Lbs (2.5 X Rated= 112500 )~~

\* \* USER Selected Motor SIZE

\* SPRING PAC Curve: SMB-1 OBSOL Selected (ISPG= 27 )

\* \* USER Selected SPRING PAC Curve

SPRING PAC No: 60-600-0007-1

BILL of Materials No: NONE

\* Calc. SPRING PAC SETTING: 2.764496

\* Set SPRING PAC to: 3 Normal TORQUE: 641 Ft-Lbs  
 Max. SPRING PAC SETTING: 3.75 Max. TORQUE: 845 Ft-Lbs

MOTOR SIZE Checks: 40 Ft-Lbs vs 19.82213 Ft-Lbs Calc. Start TORQUE  
 40 Ft-Lbs vs 24.77767 Ft-Lbs Revised Start TORQUE  
 40 Ft-Lbs vs 13.80382 Ft-Lbs 5 X RUN TORQUE

MOTOR STALL Check: 90275.46 Lbs vs 112500 Lbs 2.5 X Actuator THRUST

TORQUE SWITCH Checks: 845 Ft-lbs vs 850 Ft-Lbs Actuator RATING  
 41695 Lbs vs 45000 Lbs Max. Actuator THRUST  
 845 Ft-Lbs vs 1829 Ft-Lbs Stall TORQUE  
 3.75 SETTING vs 5 Max. SPRING PAC Setting

\* CAUTION - Check MDS-01 if this application operates at 340 DEG.F

PP&amp;L REVISION 1.90226 DATED 08-14-90 - TODAY IS 09-16-1991 12:12:36

844 9-16-91 GMP 9/21/91

## VALVE Info (Input) (TABLE # 1 ) - FILE: 155F003

Page 1 of 2

Calculated by:

Checked by:

Valve MANUFACTURER: ANCHOR DARLING  
 Valve TYPE (GATE or GLOBE): GATE  
 Valve SIZE: 10  
 Valve TAG Number: HV255F003  
 Valve VENDOR DRAWING number: 93-13802  
 Valve PP&L Drawing number:  
 Valve LOCATION:  
 Valve SYSTEM:  
 Valve LINE (ie. PIPE LINE I.D.):  
 Valve MAXIMUM Design THRUST: 0

## VALVE Data (Input) (TABLE # 2 ) - FILE: 155F003

ANCHOR DARLING GATE Tag: HV255F003

Valve STEM DIAMETER (Inches):	1.875
Valve STEM PITCH:	.333
Valve STEM LEAD (Inches):	.667
Valve SEAT AREA (Sq-Inches):	66.33
Valve STEM AREA (Default = 0 Sq-Inches):	2.761172
Req'd STEM SPEED (0 or 3-6=Globe or 12-14=Gate):	0
Valve STROKE LENGTH (Inches):	0
Req'd STROKE TIME (Seconds):	0 ( 0 Min.)
Valve INLET PRESSURE (PSIG):	1146
Valve PRESSURE DROP (PSIG):	1146
Valve Factor (.2 or .3=Gate 1.1=Globe):	.3
Valve STUFFING BOX FRICTION (Default = 0 Lbs):	2500
Valve STEM/NUT Coeff. FRICTION (0 .15 or .2):	.15
Manual ACTUATOR RATIO Selected:	92.4 : 1
Manual ACTUATOR Selected:	18

## MOTOR Data (Input) (TABLE # 3 ) - FILE: 155F003

ANCHOR DARLING GATE Tag: HV255F003

Motor TYPE (AC or DC):	DC
Motor RPM (900 1800 or 3600):	1800
Motor REDUCED VOLTAGE Percent (Default=0.8):	.8
HIGH TEMPERATURE application (Y or N):	N
COMPOUND motor GEAR application (Y or N):	N
AIR MOTORS (Y or N):	N
MODULTRONIC MOTORS (Y or N):	N
HILO Applications (Y or N):	N
Non-Rising Stem - OPERATOR thrust (Y or N):	N
Non-Rising Stem - VALVE thrust (Y or N):	N
Manual MOTOR Selected:	16

PP&amp;L REVISION 1.90226 DATED 08-14-90 - TODAY IS 09-16-1991 12:12:37

## Calculation RESULTS (TABLE # 4 ) - FILE: 155F003

Page 2 of 2

Calculated by:

Checked by:

ANCHOR DARLING GATE Tag: HV255F003

Valve STEM FACTOR: 0.0203  
 STUFFING BOX FRICTION: 2500 Lbs  
 THRUST: 28468.56 Lbs  
 STEM TORQUE: 576.943 Ft-Lbs  
 STEM SPEED: 13.71537 Inches/Min.  
 UNIT RPM: 20.56277 RPM  
 Design STROKE TIME: 0 Seconds  
 OVERALL ACTUATOR RATIO: 92.4 Actuator's 72.0

\* SMB-1 ACTUATOR selected having a 92.4 - 171.6 Ratio RANGE (IACT= 18 )  
 \* SMB-1 92.4 - 171.6 UNIT Efficiencies: PULLOUT= 35 RUN= 45 STALL= 45  
 \* \* USER Selected ACTUATOR  
 \* \* USER Selected ACTUATOR Ratio

~~used 1800 Rpm 'DC' Motor OPERATING at 1900 Rpm~~  
~~APPLICATION FACTOR: 9~~

~~Calc. MOTOR START TORQUE: 19.82213 Ft-Lbs~~  
~~MIDSTROKE RUN THRUST: 5664.303 Lbs~~  
~~Calc. MOTOR RUN TORQUE: 2.760765 Ft-Lbs (5 X RUN= 13.80382 )~~

\* 40 Ft-Lbs SMB-1 MOTOR with 106 Maximum Ratio Selected (IMTR= 16 )  
 \* \* USER Selected MOTOR

~~Revised MOTOR START TORQUE: 24.77767 Ft-Lbs~~  
~~STALL TORQUE: 1829.52 Ft-Lbs~~  
~~STALL THRUST: 90275.46 Lbs (2.5 X Rated= 112500 )~~  
 \* \* USER Selected Motor SIZE

\* SPRING PAC Curve: SMB-1 HEAVY Selected (ISPG= 12 )  
 SPRING PAC No: 60-600-0068-1  
 BILL of Materials No: 0701-212

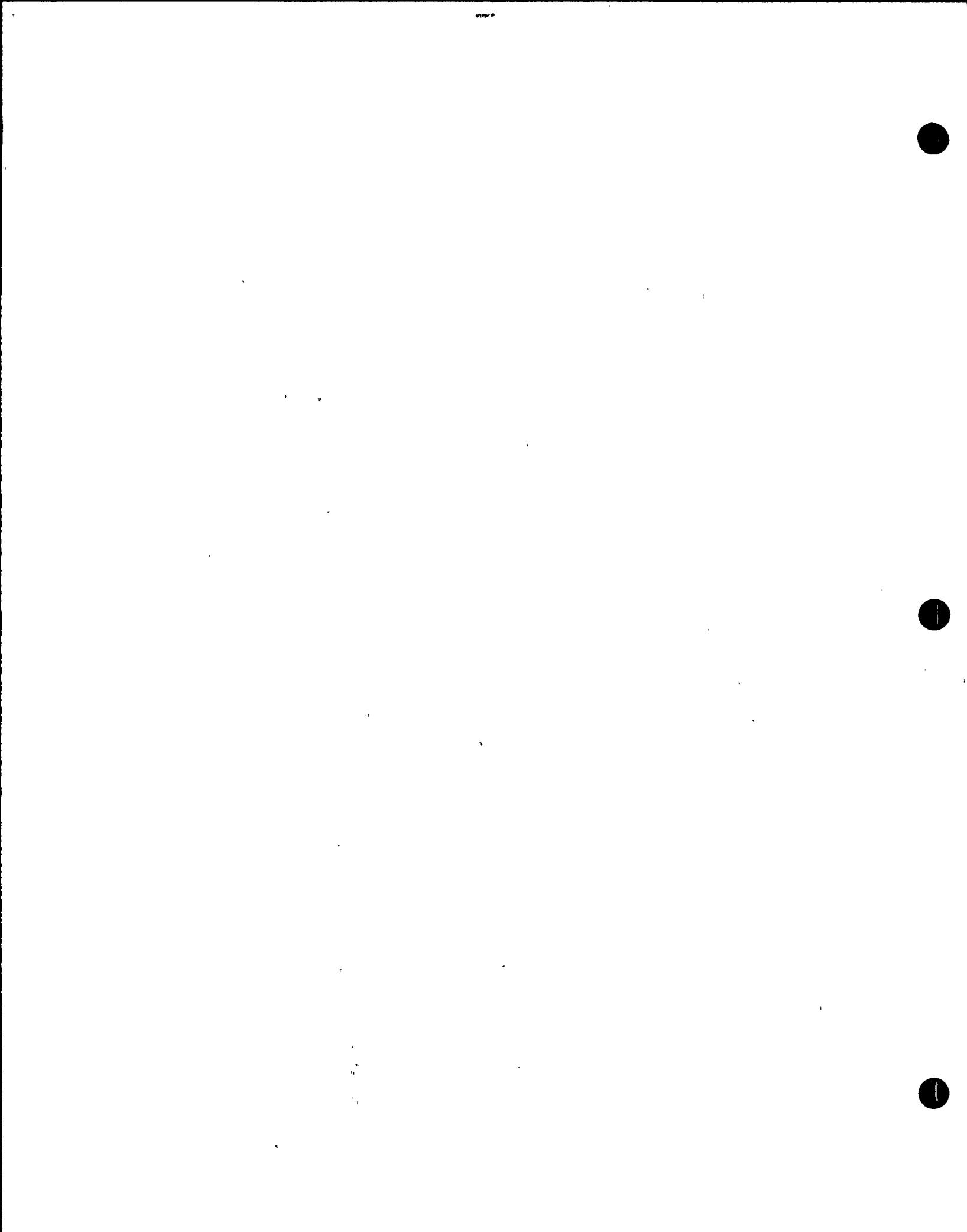
\* Calc. SPRING PAC SETTING: 2.076543  
 \* Set SPRING PAC to: 2.25 Normal TORQUE: 638 Ft-Lbs  
 Max. SPRING PAC SETTING: 2.75 Max. TORQUE: 838 Ft-Lbs

MOTOR SIZE Checks: 40 Ft-Lbs vs 19.82213 Ft-Lbs Calc. Start TORQUE  
 40 Ft-Lbs vs 24.77767 Ft-Lbs Revised Start TORQUE  
 40 Ft-Lbs vs 13.80382 Ft-Lbs 5 X RUN TORQUE

MOTOR STALL Check: 90275.46 Lbs vs 112500 Lbs 2.5 X Actuator THRUST

TORQUE SWITCH Checks: 838 Ft-lbs vs 850 Ft-Lbs Actuator RATING  
 41350 Lbs vs 45000 Lbs Max. Actuator THRUST  
 838 Ft-Lbs vs 1829 Ft-Lbs Stall TORQUE  
 2.75 SETTING vs 2.75 Max. SPRING PAC Setting

\* CAUTION - Check MDS-01 if this application operates at 340 DEG.F



Dept. \_\_\_\_\_  
Date 9-16 1991  
Designed by JM/GMP  
Approved by \_\_\_\_\_

PENNSYLVANIA POWER & LIGHT COMPANY  
CALCULATION SHEET  
PROJECT MOV Data Detail,  
Limit Switch Settings, and  
Torque Switch Settings for HV-255F003

ER No. \_\_\_\_\_  
M-VLV-418 Rev  
Sht. No. 228 of 26

**PULLOUT TORQUE CALCULATION: (100% Voltage)**

Pullout Torque (ft-lbs) = Motor Start Torque x Overall Actuator Ratio x  
Pullout Efficiency x Application Factor

Pullout Torque (ft-lbs) =  $40^k \times .78 \times .35 \times .9$

Pullout Torque (ft-lbs) = 982.8

Equivalent Thrust (lbs) =  $\frac{982.8}{.0203} = 48414$

**TORQUE SWITCH SETTING CHECK (cont'd):**

Torque (ft-lbs) at Max  
Torque Switch Setting vs. Voltage Pullout  
Torque (ft-lbs)

845 vs. 982

\* Per E-AAA-619 Rev 3 available torque = 44 ft-lbs

Dept. \_\_\_\_\_  
Date 10-1 1991  
Designed by JRW/RWA  
Approved by \_\_\_\_\_

PENNSYLVANIA POWER & LIGHT COMPANY  
CALCULATION SHEET  
PROJECT \_\_\_\_\_  
HV 255E003

ER No. \_\_\_\_\_  
M-VLV-418 Rev 2  
Sht. No. 22C of 26  
QNM 10.2.91

Check for Limiting Value Factor in closing direction:

$$LVF = \frac{RVT_{stall} - F - (A_{sr} \times P)}{A_{sr} \times \Delta P}$$

[MDS-01 Rev 2]  
Eqn. 23

Where:  $F = 2500$

OAR = 78

$A_{sr} = 2.76$

Unit Stall Eff. = .45

$A_{se} = 66.33$

FS = .0203

$P = 1146$

Reduced Voltage =

Actual motor start torque = 44 at reduced voltage (Ref. 16)

Reduced Voltage Stall Torque = Reduced Voltage Motor Start Torque  $\times$  OAR  $\times$  Unit Stall Eff.  
 $\times$  Appl. Factor

$$= 44 \times 78 \times .45 \times .9$$

$$= 1390$$

$$\text{Reduced Voltage Stall Thrust} = \frac{RV \text{ Stall Torque}}{FS} = \frac{1390}{.0203} = 68472$$

Thus:

$$LVF = \frac{68472 - 2500 - (2.76 \times 1146)}{66.33 \times 1146}$$

$$= .83$$

CA-3116(1)  
DHH 3-21-91

## 6.0 Results/Conclusions

- 6.1 All available MOV Data Detail Drawing input has been researched and documented herein. Where it was determined that information was unavailable from existing records, the field has been left blank. This information will be determined during the as-built walkdown.
- 6.2 The results of the actuator sizing calculations, VOTES diagnostic acceptance criteria calculations and limit switch setting determination are provided within the body of the calculation.
- 6.3 The following anomalies have been identified through the performance of this calculation:
  - 1.) With sp. pack 66-600-0007-1 use 3.0 T/S Setting instead of 2.5 as recommended by Limitorque. Thrust Value at TS setting of 2.5 is less than the minimum required. Therefore TS setting of 3.0 per Computer is applicable/allowable value.
  - 2: Stroke time of 32.47 seconds differs with the stroke time 31.86±32 second. ~~the difference is calculated in m-vlv-029~~. This difference is not a significant issue with respect to the operation of the VLV. The difference is due to the fact that M-VLV-029 based the valve stroke length on the average of four valve's full stroke handwheel turns. Herein, the stroke length is based on full stroke handwheel turns for HV-255FOO3 only.

OCT 18 1991  
0447-21-91

**DESIGN INPUTS CHECKLIST**

Title & No. M-VLV-

**A. DESIGN INPUTS**

	APPLICABLE	
	<u>YES</u>	<u>NO</u>
1. APPLICABLE CODES		
Codes: ASME, ASTM, AISI. Standards: ANSI, IEEE, AWS, ANS Regulatory Requirements.	(X)	( )
2. PERFORMANCE REQUIREMENTS		
A. Input Requirements - For services such as air, water, electricity, lube oil, etc.	(X)	( )
B. Output Requirements - Physical output such as: capacity, pressure, temperature, voltage, velocities of fluids, pressure drops separation and isolation both system and unit, and redundancy requirements of structures systems and components.	(X)	( )
C. Operational requirements under various conditions, such as plant startup, normal plant operation, plant shutdown, plant emergency operation, special or infrequent operation and system abnormal or emergency operation. This includes the overall effect on the plant (i.e., the potential loss of generation).	(X)	( )
D. Failure effects requirements of structures, systems and components, including a definition of those events and accidents which they must be designed to withstand.	( )	(X)
3. COMPATIBILITY		
A. Compatibility and suitability of material selection, such as chemical and physical characteristics, radiation and heat resistance protective coatings and corrosion resistance.	( )	(X)
B. Operational interface requirements including definition of the functional interface involving structures, systems and components.	( )	(X)
4. INSTALLATION (ITEMS MAY APPLY TO ANY DISCIPLINE)		
A. Transporting and Storing - Includes environmental conditions anticipated during storage, construction and operation and handling storage and shipping requirements.	( )	(X)
B. Civil - Plant layout and arrangement requirements, escape from enclosures, anchor bolts, penetrations, equipment foundations.	( )	(X)
C. Piping - Thermal expansion or heat restriction requirements, vibration or dynamic loading considerations, stress, shock, reaction forces and pipe supports.	( )	(X)
D. Electrical - Voltage, source, grounding conduit/raceway requirements.	(X)	( )
E. Instrumentation - Instrumentation and control requirements including indicating instruments, control and alarms required for operation, testing and maintenance and calibration.	(X)	( )
F. Chemistry - Water chemistry considerations, including sampling provisions.	( )	(X)
5. MAINTAINABILITY		
A. Accessibility - Maintenance, ISI and ALARA accessibility requirements.	( )	(X)
6. TEST REQUIREMENTS - Including pre-OPS, ISI and LLRT tests.	( )	(X)
7. SAFETY - Personnel and public safety including special blocking, radiation exposures, ALARA environmental concerns, effluents and noise.	( )	(X)
8. SECURITY - Physical security plant considerations.	( )	(X)
9. DESIGN CONSIDERATIONS - Form EPM-QA-208B2 and B3.	(X)	( )
10. OTHER -	( )	(X)

CR 9/16/91  
DNA 3-21-91

## DESIGN INPUTS CHECKLIST

Title &amp; No.

<u>SUBJECT</u>	<u>B. DESIGN CONSIDERATIONS</u>				<u>ISSUED GUIDANCE</u>
	<u>APPLICABLE</u>	<u>NO</u>	<u>REFERENCE PROCEDURE</u>	<u>NPE LEAD</u>	
1. Dynamic Qualification	( )	(X)	EPM-QA-222	CIV Vernatt	
2. Environmental Qualification	(X)	( )	EPM-QA-222	CIV Derkacs	GDG-03
2.1 Relay Qualified Life	( )	(X)		ELC Nudge	SEA-EE-170 SEA-EE-171
3. Electrical Separation	( )	(X)		ELC Akus	E-1012
4. II over I, Safety Impact	( )	(X)	EPM-QA-211	CIV Rose	
5. Fire Protection	( )	(X)	NDI-QA-15.3.1 EPM-QA-440	EP Kohn	Fire Protection Manual
6. Appendix R - 6.1 Safe Shutdown Analysis 6.2 Combustible Loading Anal.	( )	(X)		ELC Backenstoe CIV Delgado	EDS-01 CDS-03 & Dwg. C-1929
7. Flooding Protection	( )	(X)		MCH	
8. Jet Impingement	( )	(X)		MCH	
9. Missile Protection	( )	(X)		CIV Reinsmith	
10. Radiation Exposure, ALARA	( )	(X)	NDI-6.4.2	CIV Matchick	Memo AM-151 DG-G-100
11. Physical Separation	( )	(X)		CIV Rose	Dwg. C-1804
12. HVAC Requirements	( )	(X)		MCH Agnew	
13. Electrical Load/Voltage Study	(X)	( )		ELC Sleva/Nudge	EDG-02 EDS-02
14. Human Factors Engineering	( )	(X)	NDI-15.3.12	EP Patnaude	Human Factors Specifications & Guidelines Manual
15. Inservice Inspection Requirements	( )	(X)	NDI-QA-15.3.7	EP Lindberg	ISI Manuals
16. Materials Compatibility	( )	(X)		EP Willertz	
17. ASME Code Compliance (See Note 1)	( )	(X)		MCH Sattar	
18. Design Assessment	( )	(X)		SE Detamore	PLI-59437 dated 3/31/89
19. Fuel/Core Effects	( )	(X)	NDI-QA-7.2.2	NFE Kulick	

CA/3-18-91 OHH-4-91

## DESIGN INPUTS CHECKLIST

Title &amp; No.

## B. DESIGN CONSIDERATIONS

SUBJECT	APPLICABLE <u>YES</u>	APPLICABLE <u>NO</u>	REFERENCE PROCEDURE	NPE LEAD	ISSUED GUIDANCE
20. Heavy Loads	<input type="checkbox"/>	<input checked="" type="checkbox"/>	M-1435	MCH Kostelnick	
21. Radwaste Minimization	<input type="checkbox"/>	<input checked="" type="checkbox"/>		MCH	NDPL85-003
22. Approved Materials	<input type="checkbox"/>	<input checked="" type="checkbox"/>	NDI-QA-15.3.9	EP Morgan	Susq. Approved Matl's PLI-37573 of 1/10/85 PLI-45673 of 5/22/86
23. Secondary Containment, Control Structure, Ventilation Zone Boundary Penetrations	<input type="checkbox"/>	<input checked="" type="checkbox"/>		MCH Agnew	
24. Electrical Load Tracking	<input type="checkbox"/>	<input checked="" type="checkbox"/>		ELC Sleva/Nudge	EDS-02
25. Computer Program Change including Display Formats	<input type="checkbox"/>	<input checked="" type="checkbox"/>	EPM-QA-401	CPU	
26. Environmental Protection	<input type="checkbox"/>	<input checked="" type="checkbox"/>	NDI-QA-6.3.2	(Nuc. Svcs.- J. S. Fields)	
27. Station Blackout	<input type="checkbox"/>	<input checked="" type="checkbox"/>		ELC Sleva	GDS-08

NOTE 1: For modifications to ASME III systems/components (both paperwork only and physical changes) request in the installation instructions that Plant Staff prepare the required documentation package per NDI-QA-5.3.4 and AD-QA-522.

dc/a1861(11)

**PP&L****DESIGN INPUTS (con't)**2. TITLE M-VLV-4181. PAGE 27 OF 27

FILE NO. R35

4. ITEM	5. DISCUSSION	3. NO
1.	Applicable Codes: Calculation shall address requirements of NRC Generic Letter 89-10	
2. A,B,C	<p>Performance Requirements:</p> <p>Electricity input requirements are given by Limitorque Data Sheets, SEA-ME-237 and the MBS-01 Torque and Thrust calculation.</p> <p>Output requirements for the actuator are given by the MBS-01 calculation.</p> <p>Operational requirements when the actuator is required to function, including ΔP, are given in SEA-ME-237.</p>	
4 D	Installation - Electrical:  Electrical voltage, current and source requirements are given in the calculation data tables. (Table: Electrical/Motor Design Information).	
4 E	Instrumentation:  Geared Limit Switch settings and Spring Pac/Torque switch settings are given in tables in the calculation.	

1

2

3

(2)  
CALC # N-8SLV-418  
Attn. # RF#2

### ANCHOR/DARLING VALVE

#### MOTOR OPERATOR DATA SHEET

Customer: Bechtel SF P.O. No. 8856-P-10-A

Prepared by: "R Itm Approved by: OVK 3-5-75 Sht 3 of 1

Form Line Number	S.Q. No.	E 5853
	Vlv. Size, Press. & Type	10" 600 Gate
	No. Req'd & (Item No.)	21, 22, 62, 63

1	Seat Mean Dia. In. & Area In. <sup>2</sup>	= $A = .7854 \times d^2 = .7854(9.19)^2$	66.33
2	System Design Press. PSI	= Line Pressure = p	1230
3	Design Diff. Press. PSI	= $\Delta P$	1000
4	Disc Thrust LBS	= $T_d = A \times P$ (Line 1 x Line 3)	66330
5	Stem Thrust Tent. LBS	= $T_t = T_d \times f$ (Line 4 x Coeff Friction)*	19899
6	Stem End Thrust	= $T_e = .7854 \times D_s^2 \times P_1$ (stem area x Line 2)	3396
7	Stuff Box Load LBS	= $T_s$	2500
8	Total Stem Thrust LBS	= $F = T_t + T_e + T_s$ (Sum of Lines 5,6 & 7)	25,795

$$D_s = 1\frac{3}{4} D_{dia}$$

\*Coefficient of Friction: Double Disc .2

Flex Wedge .3 ✓

Globe Valve 1.1

FOR  
M-VLV-029

10"-EBA-FT-MD-F203 6"-EBA-FT-MD-F001-F6" EBA-FT-MG-F224

REV.	DESCRIPTION	VALVE NO.		REACTOR	REACTOR		
		SERVICE	TYPE	MAIN STEAM	REGCIRCULATION	REGCIRCULATION	GATE
1	REVERSED DIFF. PRESS & GATE VALVE DESIGNATION	LINE OR EQUIPMENT REF.	MOTOR TYPE	DGA-102	DBA-101	DBA-101	D.C.
2	AUXILIARY	SIZE		10"	6"	6"	6"
3	VALVE APPROV.	COMMODITY		STEAM	DEMINERALIZED WATER	DEMINERALIZED WATER	
4	DATE	DESIGN/MAX. PRESS. (PSIG)	(OF)	1230 / 1350	1250 / 1375	1250 / 1375	
5	BUTT	DESIGN/MAX. TEMP. (OF)		565 / 565	565 / 565	565 / 565	
6	CRAK	FLOW Normal/Max.		184.5 X 10 <sup>3</sup> lb./sec	352 GPM / 358 GPM	352 GPM / 358 GPM	
7	END	VALVE RATING		600# ASME	600# ASME	600# ASME	
8	END	TYPE ENDS/RATING		P.W. / S.C. 80	P.W. / S.C. 80	P.W. / S.C. 80	
9	END	BODY MATERIAL		See APPENDIX 3	See APPENDIX 3	See APPENDIX 3	
10	END	TRIM MATERIAL		See A/DV Dwg	STELLITE	STELLITE	
11	END	SEAT FACINGS		STELLITE	STELLITE	STELLITE	
12	END	PACKING		CRANE 187-3	CRANE 187-1	CRANE 187-1	
13	END	TYPE BONNET		PRESSURE SEAL	PRESSURE SEAL	PRESSURE SEAL	
14	END	TYPE OF SEATS		See APPENDIX 3	See APPENDIX 3	See APPENDIX 3	
15	END	TYPE OF DISC		FLEXIBLE (NET SPLIT)	FLEXIBLE (NET SPLIT)	FLEXIBLE (NET SPLIT)	
16	END	BYPASS SIZE & TYPE		-	-	-	
17	END	HANDWHEEL PULL-BREAKAWAY LBS		.20	70	70	
18	END	ACT. OP. DIFF. PRESS. (MAX.)		A 1172 PSID	1000 PSID	1000 PSID	
19	END	PORT DIAMETER (SEAT)		8.88	5.38	5.38	
20	END	PRESS. DROP (PSI)		0.047 / 0.040	0.016 / 0.017	0.016 / 0.017	
21	END	VELOCITY (FPS) (SEAT)		43 / 38	6.9 / 7.0	6.9 / 7.0	
22	END	VALVE WEIGHT LBS incl. OPER.		1530	570	565	
23	END	MOTOR OPER (TYPE/SIZE/SPD)		SMB-1-40/1900	SMB 00-10/3600	SMB 00-15/1900	
24	END	OPER. SPEED RPM/MIN/HP		1.1 / 2.7	1 / 1.3	1 / 1.1	
25	END	TIME TO OPEN		A 50 SEC	~28 SEC	~28 SEC	
26	END	TIME TO CLOSE		A 50 SEC	~28 SEC	~28 SEC	
27	END	FULL LOAD CURRENT (440V, 38.60C)		11.1	2.3	4	
28	END	STALLED MOTOR CURRENT		85.4	11.9	25	
29	END	MOTOR OPERATOR WEIGHT		430	210	215	
30	END	COST - EACH VALVE					
31	END	BYPASS					
32	END	FURN & INSTALL LIMIT BWS.					
33	END	TESTS - MAGNAPLUX					
34	END	TESTS - X-RAY					
35	END	NO. REQUIRED UNIT 1 / PN 112		1 / 1	1 / 1	1 / 1	
36	END	TOTAL COST					
37	END	MANUFACTURER		Anchor / Darling			
38	END	MODEL OR FIG. NO.					
39	END	VENDOR		Anchor / Darling			
40	END	P/D (ITEM NO. 8856-P-10)		9.3 + 4.4	4.5 + 4.6	4.7 + 4.8	
41	END	FOREIGN PRINT NO.		93-13802	93-13748	93-13668	
42	END	WELD END Dwg. REFERENCE 8856-M-199, SWS. 3C6+400		SWS. 2C1+400	SWS. 2C1+400	SWS. 2C1+400	
43	END	P.D.I. DIAGRAM REF. 8856-M-		155	144	144	
44	END	LOCATION Dwg. REF.					
45	END	Seismic Class 1 (Yes/No)		YES	YES	YES	
46	END	Active Valve (Yes/No)		YES	YES	YES	



VALVE DATA SHEET Δ 9-2-82 R/H  
MOTOR OPERATED

SUSQUEHANNA STEAM ELECTRIC STATION  
UNITS 1 AND 2  
PENNSYLVANIA POWER & LIGHT COMPANY

JOB NO. 8856

ATTACHMENT NO. 2  
8856-P-10

REV.

4.

Sheet 9 of 15

Attachment

CALC # N-VLV-A18  
Ref # 5

Attachment A  
Page 4 of 11

MOTOR OPERATOR INFORMATION SHEET

LIMITORQUE ORDER NO.: 381264 ITEM: H

OPERATOR SERIAL NOS.: 205545 + 546

OPERATOR TYPE: SMB OPERATOR SIZE: 1

DESIGN UNIT RPM (AS DEFINED IN LIMITORQUE SEL-3): Ⓐ 33.5

SPRING PACK NUMBER: 60-600-0007-1

NORMAL TORQUE SWITCH SETTING: 2 1/2

CORRESPONDING INPUT TORQUE (LB-FT): 42 FT. LBS.  
(SEE NOTE 1)

CORRESPONDING OPERATOR OUTPUT TORQUE (LB-FT): 516 FT. LBS.

CORRESPONDING OPERATOR OUTPUT THRUST (LBS): 25,240 LBS.

MAXIMUM TORQUE SWITCH SETTING: 3 1/2

CORRESPONDING INPUT TORQUE (LB-FT): 64 FT. LBS.  
(SEE NOTE 1)

CORRESPONDING OPERATOR OUTPUT TORQUE (LB-FT): 780 FT. LBS.

CORRESPONDING OPERATOR OUTPUT THRUST (LBS): 38,128 LBS.

GEAR RATIO INFORMATION

MOTOR PINION NUMBER OF TEETH: Ⓐ 33 WORM SHAFT GEAR NO. OF TEETH: Ⓐ 39

WORM TO WORM GEAR RATIO: Ⓐ 66 : 1

OVERALL ACTUATOR RATIO: Ⓐ 77.9 : 1

NOTE 1: INPUT TORQUE IS TORQUE FROM WORMSHAFT ON SMB-00 & 000 AND FROM  
HANDWHEEL ON SMB-0 AND LARGER.

LIMITORQUE SIGNATURE: Bradley Stone

Ⓐ 9/14/88 REVISED  
XWA 9/28/88

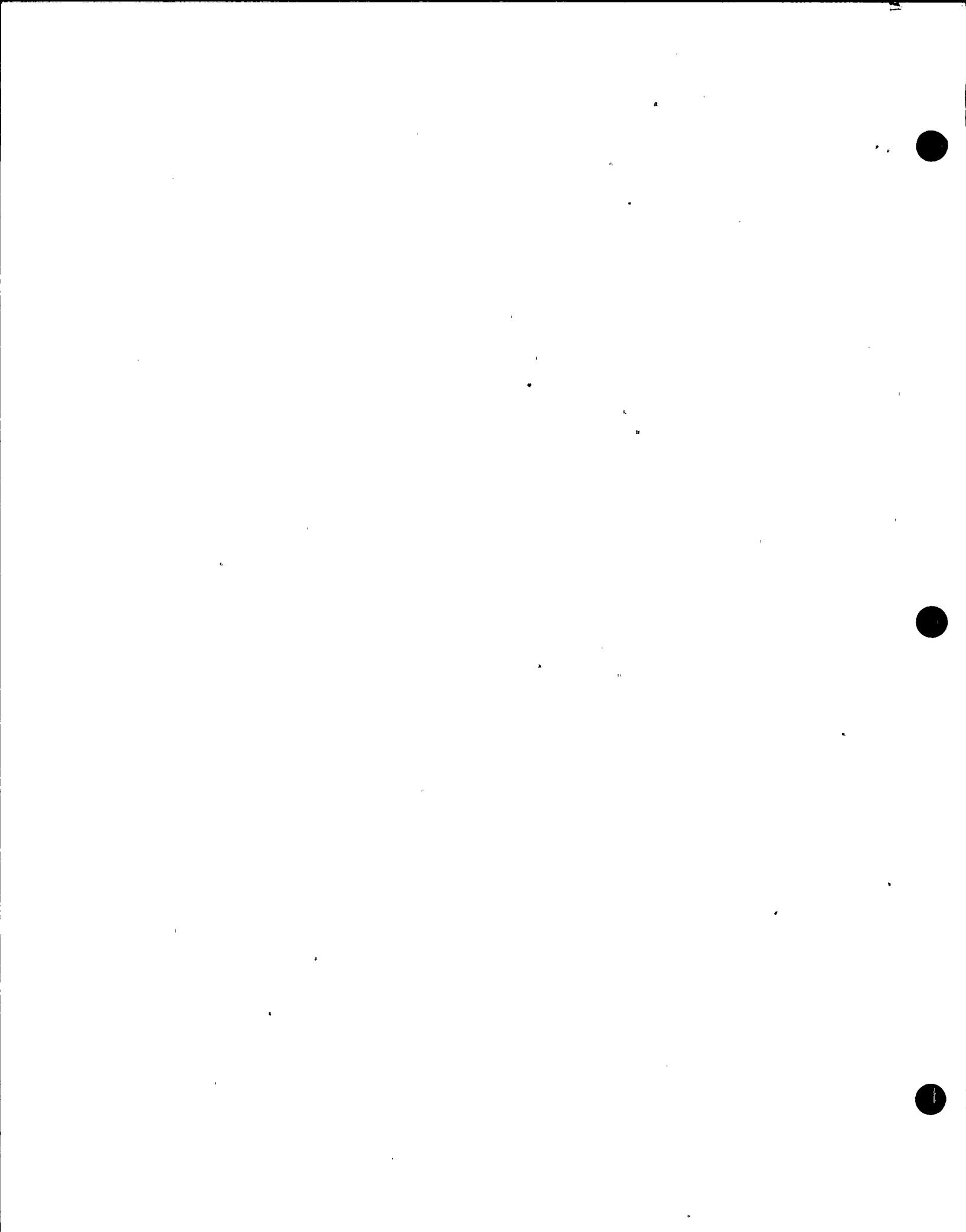
## LIMITORQUE MOTOR NAMEPLATE

## DATA SHEET

ORDER NUMBER: 381264 HSERIAL NUMBER: 205545 + 516

## MOTOR NAME PLATE DATA

IDENTIFICATION NUMBER: ① 1KA576887START TORQUE (LB-FT): ④ 40 HORSEPOWER: ④ 2.9RUN TORQUE (LB-FT): ④ 8 S.F.: 1.0TYPE: — FRAME: ④ L186A PHASE: D.C.MOTOR SPEED (RPM): 1900 HZ: C.P.D.VOLTS: ④ 250 DC CODE: — AMPS: ④ 11.1 / 85.4 F.L.A. L.A.A.AMB. C: 40° INSULATION CLASS: B DUTY: 5 MIN.LIMITORQUE SIGNATURE: Bradley Stone④ 9/14/88 REvised



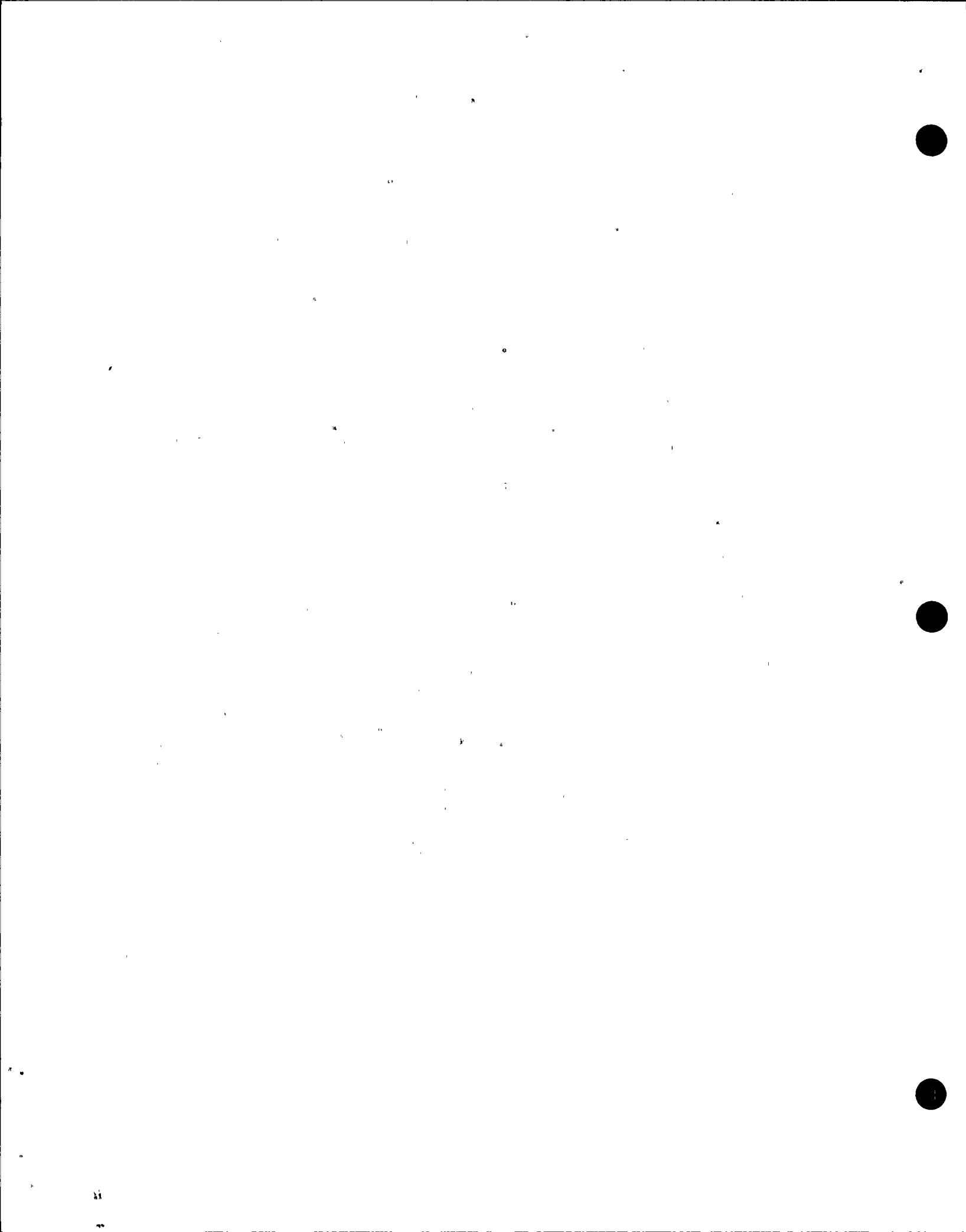
$$\text{Stroke Length} = \frac{\text{Arm Lead}}{\text{Handwheel turns}} \times \frac{1}{\text{HWR}}$$

STANDARD HANDWHEEL RATIOS FOR SMB & HMB UNITS

UNIT SIZE	HANDWHEEL RATIO	UNIT RATIO	EPP. #	UNIT SIZE	HANDWHEEL RATIO	UNIT RATIO	EPP. #
SMB-000	1:1	All	100	HMB-00	19:1 45:1	9.7-22.0 23.0-109.0	60 30
SMB-00	1:1 4.38:1	All All	100 95	HMB-0	15.7:1 37:1 58:1 95:1	11.2-26.1 26.4-96.2 102.6-150.8 158.3-247	60 30 25 25
SMB-0 SB-0	8.93:1 21.1:1 33:1 54.1:1	11.2-26.1 26.4-96.2 102.6-150.8 158.3-247	60 30 25 25	HMB-1	14.5:1 34:1 66:1 90:1	11.6-25.6 27.2-88.4 92.4-171.6 191.7-234	60 30 25 25
SMB-1 SB-1	10.75:1 25.3:1 49.0:1 66.7:1	11.6-25.6 27.2-88.4 92.4-171.6 191.7-234	60 30 25 25	HMB-2	13.3:1 33:1 60:1 85:1	10.6-27.2 26.2-82.5 84.8-150.0 153-212.5	60 30 25 25
SMB-2 SB-2	9:1 22.3:1 40.5:1 57.4:1	10.6-25.5 26.2-82.5 84.8-150 153-212.5	60 30 25 25	HMB-3	10.3:1 16:1 41:1 57:1 80:1	11.1-24.1 25.7-37.3 35.9-95.5 98.6-132.8 138.4-186-4	60 60 30 25 25
SMB-3 SB-3	7.15:1 11.07:1 28.37:1 39.4:1 55.36:1	11.1-24.1 25.7-37.3 43.9-95.5 98.6-132.8 138.4-186.4	60 60 30 25 25	HMB-4 HMB-4T	12.7:1 50:1 58:1	10.1-32.3 40.0-124.9 131.8-147.9	60 30 25
SMB-4 SMB-4T SB-4	8.7:1 13.06:1 33.69:1 39.87:1 59.13:1	13.4-32.3 33.6-48.4 51.8-124.9 131.8-147.9 152.1-219.3	60 60 30 25 25				
SMB-5 SMB-5T	86:1) 163.5:1) 142.0:1) 269.8:1)	61.4-93.4 101.4-230.2	25 25				

\*This ratio supplied when torque required exceeds 65 ft/lbs.

△ For SMB-5 and SMB-5T unit, this ratio provided as standard. Alternate ratio shown provided only on request.



CALC # M-VLV-418  
Page of cr Rds 11

VALVE ID V80063  
VALVE NO 10 VALVE F003  
SYSTEM 52

This is incorrect. The order #  
Should be 381264 H per serial  
number 205546.

### 5.12 Actuator Trouble Shooting

JAB 4/7/90

#### SECTION I (NAMEPLATE/REFERENCE)

Q (Y/N) YES  
P&ID M-255  
Schematic EIS2 SH.31  
Loc. Area \_\_\_\_\_  
LLRT (Y/N) YES

Number of handwheel  
turns to (1) stroke

750

Max Thrust

\_\_\_\_\_

Pitch

\_\_\_\_\_

Lead

\_\_\_\_\_

Actuator Order No. 381264-1  
Actuator Serial No. 205546  
Actuator Size SMB-1

Motor Start torque 40 FT-lbs  
Motor Run torque 8 FT-lbs  
Motor Mfg Reliance  
Motor Hp SP 56  
Motor Voltage 250  
Motor Run Current 11.10  
Motor Start Current 4.9  
Motor RPM 1900

#### SECTION II (TORQUE SWITCH DATA)

	LIMIT TORQUE	AS FOUND	AS LEFT	CONFIRM
"OPEN" SETTING	<u>2 1/2</u>	<u>2 1/2</u> 3	<u>2 1/2</u>	<u>2 1/2</u>
"CLOSE" SETTING	<u>3 3/4</u>	<u>3 3/4</u> 3	<u>3 3/4</u>	<u>3 3/4</u>
Normal Setting	<u>2 1/2</u>			
Maximum Setting	<u>3 3/4</u>			
As Found Setting				
Corresponding ft-lbs				
Normal Setting				
Corresponding ft-lbs				
Max Setting				
Corresponding ft-lbs				
Torque Switch				
Calibration Chart	<u>1/16 Washers .157 Thickness</u> <u>1/16 380 650 920 1050</u>	<u>1/16 380 650 920 1050</u>	<u>60-600-0007-1</u>	

#### SECTION III (SPRING PAC)

	LIMIT TORQUE	AS FOUND	AS LEFT	CONFIRM
Part No.	<u>60-600-0007-1</u>			
No. of Washers	<u>11</u>	<u>11</u>	<u>11</u>	<u>11</u>
Thickness of Washers	<u>.157</u>	<u>.157</u>	<u>.157</u>	<u>.157</u>
Spring PAC Gap	<u>.657</u>	<u>.657</u>	<u>.657</u>	<u>.657</u>
Spring PAC Preload		<u>15 TURN PER MOVE</u>		

WA NO 1180063  
 VALVE ID HV2552F003

SECTION IV (RATIOS/EFFICIENCIES)	LIMIT TORQUE	AS FOUND	AS LEFT	CONFIRM
Actuator Overall Ratio	<u>103.7</u>	<u>77.88</u>	<u>77.88</u>	<u>OVS</u>
Pinion Gear to Wormshaft		<u>118:1</u>	<u>118:1</u>	<u>OVS</u>
Gear Ratio				
Worm to Worm Gear Ratio	<u>66:1</u>	<u>66:1</u>	<u>66:1</u>	<u>OVS</u>
Worm to Worm Gear Efficiency				
Handwheel to Stem Ratio	<u>49:1</u>	<u>49:1</u>	<u>49:1</u>	<u>OVS</u>
Handwheel to Stem Efficiency				
# Motor Pinion Gear Teeth	<u>28</u>	<u>28</u>	<u>28</u>	<u>OVS</u>
# Wormshaft Gear Teeth	<u>39</u>	<u>39</u>	<u>39</u>	<u>OVS</u>
	<u>3/2/88</u>			

5.12.12 Actuator operates satisfactorily.

OVS

Comments:

5.12.13 This completed data sheet has been forwarded to Maintenance Engineer.

OVS

R. J. Johnson, 3/2/88  
 Confirm Date

J. Montgomery, 4/9/88  
 Review Date

Cals # M-VLV-418  
Page of left

WAB V60388  
SYS 252  
DATE 9-24-86

Design Inputs for M-VLV-029  
Showing order#, motor type,

MOVATS TEST DATA SHEET

SECTION I

Record Operator Information  
Type: SMB  
Size: 1  
Serial No.: 205546  
Order No: 381264H  
Stem Orientation: Horiz  
Spring Pack No.: 1675-11

Record Valve Information

I.D. #: HV-501-~~2~~003  
Type: Gate  
Size: 10"  
Valve Body Orientation: Horiz  
# of Handwheel turns: N/A  
# of turns to open limit: N/A  
Orifice size: N/A  
Stem diameter: About 2"

Record Motor Information

Volts: Rated / Actual 250 VDC  
Rated Amps: 11.10  
Speed: 1900 RPM  
Horsepower: SPCF  
AC or DC: AC / DC  
Orientation: Top/Side/Bot

Control Circuit Volts: 250  
AC or DC Control Circuit: AC/DC  
Open Control: LIM/TOR  
Close Control: LIM/TOR  
Breaker #: 2P264-031

Record System Information  
System: HPC1 252  
Flow: 0  
Temp: Amb  
Press: Atmos

Record Torque Switch Information  
Open Torque Switch Setting: 3.0  
Close Torque Switch Setting: 3.0  
Limiter Plate Size: 3/4"  
TS Balancing Capability: Yes

Record Test Equipment Numbers and Calibration Due Dates

Mainframe: 7/30/87  
Load Cell: 7/31/87  
TMD: 7/31/87  
Amp Probe: 7/31/87  
Cable Length: 30 FEET  
Initial Position of Valve: 0/0  
Final Position of Valve: 0/0  
Safety Related: Yes/No

SECTION II:

As Found DSP at TST O 1.445 TSS <sup>bigule</sup> Final DSP at TST O .965  
As Found DSP at TST C .620 TSS <sup>bigule</sup> Final DSP at TST C 1.050

SPRING PACK CALIBRATION

SECTION III:

Spring Pack Constant: 12046 o/V Preload: < RL

Cal # M-VLV-418  
Ref 13

# Anchor/Darling

Valve Company

701 FIRST STREET  
P.O. BOX 3428  
WILLIAMSPORT, PA 17701-0428  
(717) 327-4800  
TELEX: 759953

February 20, 1990

PENNSYLVANIA POWER & LIGHT COMPANY  
Two North Ninth Street  
Allentown, PA 18101

Attn: Mr. Ken Anderson, Engineering

SUBJECT: VALVE DATA

Dear Ken,

The valve data you requested at our recent meeting is enclosed.

Please advise if you need further information.

Yours sincerely,

ANCHOR/DARLING VALVE COMPANY

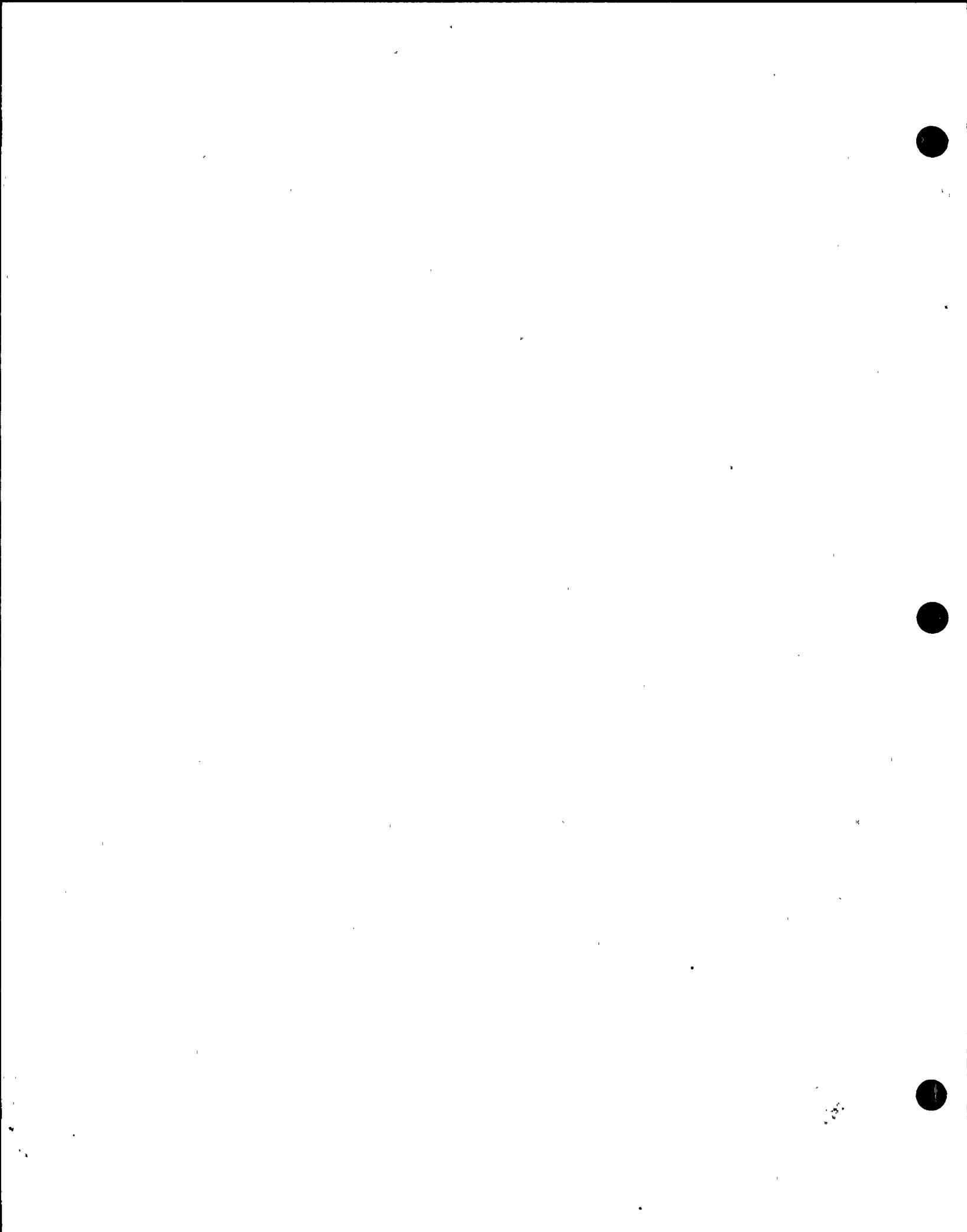
R. W. Dommers

Director - Marketing & Sales

/cll

cc: J. J. Chappell  
R. J. Stout

encl.



## STEM DATA FOR P.P.&amp;L. (SUSQUEHANNA)

CERT. Dwg. No.	A/DN S.O. ITEM NO.	VALVE SIZE / TYPE	STEM DIA AT S. BCX	STEM DIA AT THDS	PITCH & LEAD
21700	15G4-2	2-1500-FW	.750	.750	1/3 - 1/3
21699	15G4-1	2-1500-FW	.750	.750	1/3 - 1/3
13661	5853-1	4-900-FW	1.250	1.250	1/3 - 2/3
13662	5853-2	4-900-FW	1.250	1.250	1/3 - 2/3
13689	5854-14	20-150-FW	1.875	1.875	1/3 - 1/3
13692	5854-21	6-150-FW	1.125	1.125	1/3 - 1/3
13699	5854-9	3-300-FW	.875	.875	1/3 - 1/3
13709	5853-8	14-900-FW	2.375	2.375	1/3 - 1/1
13711	5853-11	10-900-FW	2.000	2.000	1/3 - 1/1
13712	5853-15	6-900-FW	1.625	1.625	1/3 - 2/3
13713	5853-85	4-900-GB	1.500	1.500	1/4 - 1/4
13715	5854-18	10-150-FW	1.500	1.500	1/3 - 1/3
13739	5855-2	20-900-FW	3.125	3.125	1/3 - 1/1
13740	5855-3	20-900-FW	3.125	3.125	1/3 - 2/3
13747	5855-10	6-900-GB	2.125	2.125	1/3 - 2/3
13795	5853-28	10-900-GB	3.125	3.125	1/4 - 1/4
13797	5853-5	3-900-FW	1.125	1.125	1/3 - 2/3
13798	5853-6	3-900-FW	1.125	1.125	1/3 - 2/3
13801	5853-21	10-600-FW	1.875	1.875	1/3 - 2/3
13802	5853-22	10-600-FW	1.875	1.875	1/3 - 2/3
13808	5854-27	18-300-GB	3.250	3.250	1/4 - 1/4
13812	5854-30	6-300-GB	1.500	1.500	1/4 - 1/4
13814	5853-93	4-600-FW	1.250	1.250	1/3 - 2/3
13831	5854-28	12-300-GB	2.500	2.500	1/4 - 1/2
13858	5854-16	16-150-FW	1.750	1.750	1/3 - 1/3
13956	57956-3	6-900-FW	1.625	1.625	1/3 - 1/3
13981	5854-89	3-150-FW	.750	.750	1/3 - 2/3
14071	5853-109	4-900-FW	1.250	1.250	1/3 - 1/3
15251	5853-67	4-900-GB	1.500	1.500	1/4 - 1/4
13687	5854-12	24-150-FW	2.000	2.000	1/3 - 1/3
13710	5853-10	12-900-FW	2.250	2.250	1/3 - 1/1
13741	5855-4	12-900-FW	2.250	2.250	1/3 - 1/1
15175	5052-1	4-150-FW	1.000	1.000	1/4 - 1/2
13738	5855-1	24-900-FW	3.750	3.750	1/3 - 1/1
13691	5854-19	6-150-FW	1.125	1.125	1/3 - 1/3
13688		20-150-FW	1.875	1.875	1/3 - 1/3
13748			1.5	1.5	1/3 - 1/3
13668			1.5	1.5	1/3 - 1/3

Ref. 15

**PENNSYLVANIA POWER & LIGHT  
Susquehanna Steam Electric Station  
MOV - Design Basis Review**

VALVE TAG NUMBER: HV-255F003

UNIT 2

PRIORITY: 2

VALVE DWG NO. FF110100-6101

MFG. ANCHOR/DARLING

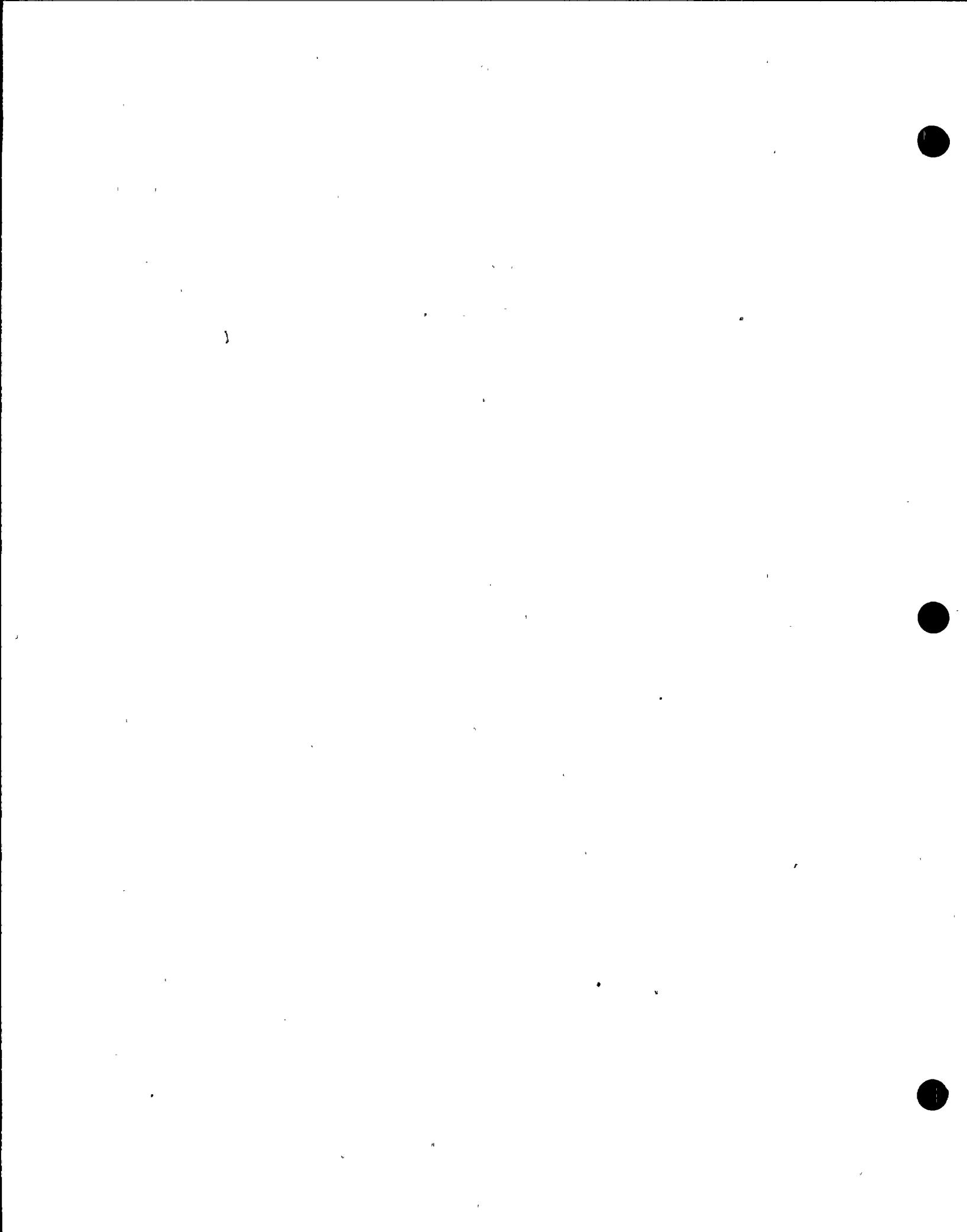
DESIGN DATA		REF NO	MATERIAL/DIMENSIONAL DATA		REF NO
Valve Type	GT	3	Stroke Length (in)	10.625	22
Valve Size	10.00	3	Stroke Time (sec)	50	4
Pressure Class	600	3	Orifice Diameter (in)	9.187	22
Valve Code	SR	6	Stem Diameter (in)	1.875	2
Area/Room	33/II202	5,16	Stem Pitch (in)	0.33	2
Elevation	708.5'	5	Stem Lead (in)	0.66	2
Line No.	DBA-202	1	Stem Material	A276-410T	3
Normal Valve Pos	0	1	Stem Mod of Elasticity	29.200	21
Actuator Size	SMB-1-40	3	Stem Mod of Rigidity	11.300	21
Valve Orientation	H	5	Valve Thrust Capability		
Stem Orientation	R	5	Dsk Guide Fac Mat	SA216-WCB	3
Power Supply	2D264031	6	Dsk Seat Surf Mat	STELLITE	3
Rework Window	OC-1, 2 & 3 - 14 DAYS (3.5.1)				

## DEFINITION OF SAFETY RELATED FUNCTION

HV-255F003, A NORMALLY OPEN VALVE, IS THE HPCI STEAM SUPPLY LINE INBOARD CONTAINMENT ISOLATION VALVE. THIS VALVE'S SAFETY FUNCTION IS TO CLOSE TO ISOLATE HPCI ON A STEAM LINE BREAK, TO PREVENT TURBINE EXHAUST OVERPRESSURE, AND ON LOW STEAM LINE PRESSURE AND PROVIDES CONTAINMENT ISOLATION. RECOVERY FROM MISPOSITIONING IS NOT REQUIRED SINCE THE VALVE IS NOT CLASSIFIED AS POSITION CHANGEABLE.

## VALVE OPERATIONAL DATA

	Lrge Brk LOCA	Smal Brk LOCA	Station Blackout	HELB	LOOP	Fire	Inadvert Oper
Max Diff Press	1030	1030	NA	1146	NA	NA	NA
Dir Diff Press	D	D	NA	D	NA	NA	NA
Flow Rate	216K	216K	NA	648K	NA	NA	NA
Line Press(psig)	1040	1040	NA	1146	NA	NA	NA
Fluid	S	S	NA	S	NA	NA	NA
Process Temp(F)	551	551	NA	563	NA	NA	NA
Duty Cycle	1	1	NA	1	NA	NA	NA
Time Line (sec)	5	5	NA	3	NA	NA	NA
Envr Profile(F)	139	139	NA	130	NA	NA	NA
Initiate Signal	P4	P4	NA	DP1	NA	NA	NA
Valve Cycle	C	C	NA	C	NA	NA	NA
Normal Cond		O,C					



M-VLV-418

Ref. 16

Pennsylvania Power & Light Company  
MOV Voltage Drop

Calc. No. E-AAA-619  
Revision 3  
Page 14 of 100

ATTACHMENT B

VALVE TAG NUMBER: HV-255F003

GE ID NO: HV-E41-2F003

INPUT DATA

Motor Control Center .....	2D264031
Motor Rated Voltage (Vdc) .....	240
Motor Locked Rotor Amps (amps) .....	85.40
Motor Accident Temperature (°C) .....	59.4
Conductor Scheme .....	FP2Q4012A
Conductor Type .....	D21
Conductor Size .....	2
Conductor Resistance/1000 ft at 50 °C (ohms) .....	0.185
Number of Conductors per Leg/Phase .....	1
Circuit Length (one-way distance from starter to mtr) (ft).....	233
Starting Resistor (ohms) .....	0.52
Overload Heater Catalog Number .....	L135B
Overload Heater Resistance/Heater (ohms) .....	0.011
Motor Control Center Minimum Voltage (Vdc) .....	210.0

CALCULATED DATA INPUT

Motor Resistance at 59.4 °C (ohms) .....	3.135
Motor Reactance ( PU ) .....	0.000
Cable Resistance at 59.4 °C/50 °C (ohms) .....	0.175
Overload Heater Resistance (ohms) .....	0.022
Total Circuit Resistance (ohms) .....	3.852
Total Circuit Reactance ( PU ) .....	0.000

AVAILABLE VOLTS/AMPS

Motor Inrush Current Draw (amps) .....	54.5
Motor Terminal Voltage (Vdc) .....	170.9
TORQUE (FT-LBS)	44.0

SOURCE DOCUMENTS

Electrical Schematic:	E-152 SHT 31 REV 11
Set Point Drawing:	E-618 SHT 5 REV 0
Set Point Calculation:	E-AFS-004 04/18/83
Valve Design Basis:	SEA-ME-238 REV 0
Cable Codes and Descriptions:	E-1001 REV 2
Conductor Resistance:	Attachment F
Overload Heater Resistance:	Attachments C,D or E
'CARTS'	

REMARK: Motor is assumed to be same as Unit 1 (WA V10195)  
LRA & torque obtained from motor performance curve (Attachment H).

