

CERTIFICATION OF ENGINEERING CALCULATION

STATION AND UNIT NUMBER KEOWEE 1+2

TITLE OF CALCULATION Keowee Governor Mechanical Single Failure Analysis

CALCULATION NUMBER KL-UNIT 1-2-0098

ORIGINALLY CONSISTING OF:

PAGES 1 THROUGH 13

TOTAL ATTACHMENTS 3 TOTAL MICROFICHE ATTACHMENTS 0

TOTAL VOLUMES _____ TYPE I CALCULATION/ANALYSIS YES NO

TYPE I REVIEW FREQUENCY N/A

THESE ENGINEERING CALCULATIONS COVER QA CONDITION 1 ITEMS. IN ACCORDANCE WITH ESTABLISHED PROCEDURES, THE QUALITY HAS BEEN ASSURED AND I CERTIFY THAT THE ABOVE CALCULATION HAS BEEN ORIGINATED, CHECKED OR APPROVED AS NOTED BELOW:

ORIGINATED BY John B. Bohman DATE 9/29/93

CHECKED BY Wm. R. Darling DATE 9/29/93

APPROVED BY S L Nader DATE 10-14-93

ISSUED TO DOCUMENT CONTROL Kathy B. Lee DATE 10-28-93

RECEIVED BY DOCUMENT CONTROL Wm. R. Darling DATE 10/28/93

MICROFICHE ATTACHMENT LIST: Yes No SEE FORM 101.4

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I PURPOSE

The purpose of this calculation is to verify that there is no creditable active single failure in the mechanical governor system that could prevent a Keowee Hydro Unit from performing its intended safety function.

II RELATION to NUCLEAR SAFETY

Since this calculation makes conclusions about a safety related system this calculation is designated as QA Condition 1.

III DESIGN METHOD

Each active component in the governor system will be evaluated for creditable failures and the effects of the failures on the governor system.

IV APPLICABLE CODES and STANDARDS

ANSI N45.2.11 has been reviewed and all applicable design inputs are addressed in the appropriate sections of this calculation.

V OTHER DESIGN CRITERIA

None

VI FSAR CRITERIA

FSAR Section 8.3

VII ASSUMPTIONS

7.1 It is assumed that Keowee operation at frequencies of $60 \pm 5\%$ Hz is acceptable. This is justified by standard statements in electrical equipment purchase specifications that identify frequency tolerance on equipment of $60 \pm 5\%$ Hz (Ex. OSS-0320.00-00-0015 Rev. 2 Section 3.2.4.1) and Regulatory Guide 1.9

VIII REFERENCES

- 8.1 KFD 105A-1,2.1 Rev. 0
- 8.2 KM 200-85 Rev. G
- 8.3 NRC Information Report SECY-77-439
- 8.4 FSAR Section 8.3.1.2
- 8.5 KM-200-158 Doc Control Date July 11, 1990
- 8.6 KEE-111 and 211

IX CALCULATION

<u>ITEM</u>	<u>Function</u>	<u>Failure</u>	<u>Effect</u>
Governor Oil Pump KM 200-0085	Maintain Pressure Tank Pressure	Fails to run or runs with reduced discharge pressure	Each GO Pump is backed up by two other GO Pumps. On loss of auxiliary power all three GO Pumps will fail to run. The Pressure Tank maintains enough oil inventory to provide for complete unit operation for some period of time. This period of time is approximately 1 Hr. depending on the amount of load changes. This will allow operators enough time to restore auxiliary power. AP Procedures are in place to direct the operators to restore the auxiliary power in this situation.

Pump fails to stop When the oil pressure reaches the pressure setting of the unloader pilot valve, the pump is unloaded and is bypassed to the Governor Oil Sump. The unloader would still load and unload the running pump as required.

Oil Pressure Switches (63Q)

Switch 1-provides alarm on low Pressure Tank pressure

This switch is alarm only

This switch is backed up by Switch-4, Emergency Pump Run. This switch provides its own alarm plus starts one GO Pump. (See Emergency Pump Run Switch)

Switch 2-provides Normal Unit Lockout on Extremely low oil Pressure

Switch does not actuate when required.

This switch is bypassed in Emergency operation, therefore it would require more than two failures to lock the unit out on an emergency start. Pressure switch is also backed up by the Emergency pump run circuit 63Q-4

GO Pump Discharge Check Valves OG-11,14&17

Isolates the GO Pump from the Pressure Tank

Check Valve failures are Passive Failures Ref 8.3

Keowee Mechanical Systems are not required to be passive failure proof Ref 8.4

<p>GO Pump Unloader, Unloader Pilot, Unloader Switch</p>	<p>Allows GO Pump to start in an unloaded condition, Starts and stops pump and determines at what pressure the GO Pump starts and stops.</p>	<p>Fails to start pump Fails to stop pump Fails to unload pump Fails to load pump</p>	<p>See GO Pump See GO Pump Each pump is protected by a safety valve OG-13,16,19 Ref. 8.1 Same as pump fails to start.</p>
<p>Safety Valves OG-13,16,19</p>	<p>Overpressure protection of GO Pump discharge</p>	<p>Safety valves are Passive Failures Ref. 8.3</p>	<p>For these valves to be required to operate, failure of the Oil Pump Unloader must occur. Keowee Mechanical Systems are not required to be passive failure proof Ref 8.4</p>
<p>Emergency Pump Run Pressure Switch (63Q-4)</p>	<p>Monitors pressure of Governor Oil Pressure Header And initiates The Emergency Pump Run On low Oil Pressure</p>	<p>Fails to start Pump</p>	<p>A failure of the two other GO Pumps or a passive failure of valve OG-7 is required for this Press Switch to be needed. Therefore this is not a creditable failure.</p>

Emergency
Pump Run
Solenoid
(20QGPA)

Used to initiate Emergency Pump Run start by Emergency Pump Run Pressure Switch.

Fails to operate.

A failure of the two other GO Pumps or a passive failure of valve OG-7 is required for this solenoid to be needed. Therefore this is not a creditable failure.

Auxiliary
Valve

Is used for manual control of turbine speed during maintenance.

This valve is bypassed in emergency operation by the manual transfer valve.

This valve has no effect on emergency operation and is used only during maintenance. During this time of use the Unit would be under a Tech Spec LCO and the other Keowee Unit would be available.

Distribution
valve

Directs Pressurized oil to the appropriate side of the Gate Servo Motors to open or close the gates.

This valve is inherently rugged and simple in operation. There are no creditable failures of this item.
(Att. 1)

Distribution Valve Servo Motor

This Hydraulic Servo Motor positions the Distribution Valve so that the turbine gates can be moved.

This Servo Motor is inherently rugged and simple in operation. There are no creditable failures of this item. (Att. 1)

Gate Servo Motor

These Servo Motors are attached to the turbine gate mechanism and they provide the opening and closing forces to these gates.

This Servo Motor is inherently rugged and simple in operation. There are no creditable failures of this item. (Att. 1)

Pilot Valve

This valve receives position input from the Governor Head and directs pressurized oil to the appropriate side of the Distribution Valve Servo Motor to move the Distribution Valve in the proper direction to allow for proper gate movement.

This Pilot Valve is inherently rugged and simple in operation. There are no creditable failures of this item. (Att. 1)

Oil Motor
Vibrator

Provide constant agitation to the pilot valve and distribution valve to prevent sticking

This is a hydraulic motor and is always in operation the only failure mode is to stop.

If the Vibrator motor fails, only long term operation of the unit may be affected. The purpose of the is motor is to prevent the buildup of varnish on the internal moving parts of the Pilot and Distribution Valves. This failure would have no short term effect on the emergency operation of the Governor.

Governor Linkages, Cables and Gearing

Transfers input motion and feed back to the hydraulic valves.

These linkages are inherently rugged and simple in operation. There are no creditable failures of these items.
(Att. 1)

Compensating Dashpot

Provides stability to the control of the unit.

The dash pot is inherently rugged and simple in operation. There are no creditable failures of this item.
(Att. 1)

Complete
Shutdown
Solenoid

Manually bypasses the governor controls and shuts the unit down by forcing the turbine gates closed

The Complete Shutdown Solenoid is energized during unit operation. A failure would de-energize the solenoid.

A de-energized solenoid would result in the unit shutting down completely. If this occurred while the unit is carrying emergency loads, the power control circuits would transfer to the other operating Keowee unit.

Partial
Shutdown
Solenoid

Is used to limit turbine gate movement during normal startups

The Partial Shutdown Solenoid is energized during unit operation. A failure would de-energize the solenoid.

A de-energized solenoid would result in the unit being limited to the Partial Shutdown gate limit. This limit is set at approximately 25% open. The governor will operate normally below this amount. This limit is sufficient to allow normal unit operations for the emergency loads.

Synchronizing
motor

Used to raise and lower speed from remote locations and for synchronizing the unit to the grid.

Motor is normally off, could fail on to raise unit speed

This motor is designed to override the governor controls a small amount to allow for synchronizing the unit's speed with that of the Power grid. The amount is defined by the amount of droop set on the machine. The droop setting defines the band around 60Hz that the unit would operate. Keowee is set at maximum droop (5%). This would allow frequency to change $\pm 2.5\%$ If this

motor failed on, and began to raise the unit speed, then the governor would begin to compensate. Frequency would remain elevated 2.5% while the motor is running. This would be acceptable for the emergency loads. (Assumption 7.1)

Motor could fail on to lower unit speed Same as above except the unit would run at 2.5% lower frequency. (Assumption 7.1)

Gate Limit Motor

Used to change the Gate Limit (Maximum amount of gate opening allowed) from remote locations.

Assume failure causes the Gate Limit Motor to lower the gate limit. The Unit is at rest in standby.

If the Keowee Unit is at rest, then the gate limit is automatically set at 50% open. Taking the failure of the Gate Limit Motor at the event initiation, the gate limit would decrease rapidly while the unit is starting up. As the gate limit continues to decrease, it would begin to limit the units speed and ultimately shut the unit down. Then the other Keowee Unit would be available for the Emergency Loads. This would occur in less than the required 23 sec. because of the quick speed (16 sec. 50% to 0%) of the Gate Limit Motor (Att. 3)

Keowee unit is running When the unit is running, the gate

and the limit is
Gate Limit automatically changed
Motor fails to 100%. If the
to lower motor tries to lower
the limit. the limit, then the
raise and lower
portion of the Gate
Limit Motor would
begin competing with
each other. The
raise winding is
trying to raise the
limit back to 100%
and the failed lower
circuit is trying to
lower the limit.
Under this condition,
the motor would stop
and the protective
circuits would see a
fault condition and
open the circuit.
The gate limit would
remain at the setting
just prior to this
occurrence and would
be in the vicinity of
100%. This limit is
in excess of the
unit's emergency
operation
requirements and will
not hinder its
operation.

Failure The gate limit would
causes the rise to 100% which is
Gate Limit how it is supposed to
Motor to respond.
raise the
gate limit

Pressure Tank Prevents air in
Float Valve the Pressure Tank
OG-7. from entering the
OG system

This valve is normally
open. Fails
closed

This failure is a
passive failure and
is not considered for
Keowee Mech Systems.
(See Pressure Switch
63Q-4 Emergency Pump
Run)

Valve fails
to close
when
required

This valve closes
only when the oil
level in the Pressure
Tank drops to the
point where air may
enter the hydraulic
system. For this to
occur, another
failure must have
occurred. For
example, the failure
of all three GO
Pumps. If all Oil
Pumps fail (see Gov.
Oil Pump) and the
unit is operated for
an extended period of
time, then the oil
level may drop to a
point where the float
valve may close. If
this occurs then the
governor becomes
inoperable (the unit
could no longer
control speed but
would maintain the
same turbine gate
position). If the
float valve fails to
close then air would
enter the governor
and it again would
become inoperable.
Therefore this valve
serves no safety
function. The only
function of this
valve is to make
regaining control of
the unit easier.

Governor
Head,
Permanent
Magnet
Generator
(PMG)

Provides the
corrective force
for turbine speed
correction

Governor
Head fails
to run

If the Governor head
fails to run, this
would be an
indication of no
turbine speed and the
governor would react
by opening the
turbine gates. The
gates would open
until the unit
tripped on overspeed.

Following the
installation of NSM
ON-52966, Gov. Head
Failures will be
detected differently:

Gov. Head
Fails when
the unit is
initially
at rest.

The response of the
unit would be such
that Gov. would open
the gates in an
attempt to increase
the Gov. Head speed.
This failure would be
detected by new
circuitry using a
speed sensing
magnetic pickup
(14MPU/1). If this
MPU does not sense
rotation of the Gov.
Head then that unit
is not allowed to
load to ONS.

Gov. Head
Fails when
the unit is
initially
at Power
Generation.

Again the Gov would
open the gates full
open trying to
increase the Gov.
Head speed. The unit
speed would increase
due to this as well
as the normal Load
Rejection overspeed
caused by Emergency
start signal. New
over frequency relays
(81/X1, 81/Y1 and

REV
1
AFB
5/23/95

81/Z1) would prevent the failed unit from loading to ONS.

Rev 1
JRB
5/23/95

Governor Head runs at wrong speed

Since the Governor Head Motor is tied solely to the PMG which is directly coupled to the generator shaft, There are no failures that could make the Governor Head Motor run at any speed other than the correct proportional synchronous speed of the generator. Therefore this is not a creditable failure.

Compensating Dashpot Bypass Solenoid

Allows for the bypassing of the effects of the Compensating Dashpot

Solenoid is normally off, could fail on.

There are two contacts in series that are opened during emergency operation that will prevent a single failure from energizing this solenoid. Therefore this is not a creditable failure. Ref 8.6

X CONCLUSION

The above calculation found no failures that would result in the Keowee Unit operating at an unacceptable speed or frequency. Several failures were found that would result in the shutdown of the unit. With these failures the other Keowee Unit would be available for the emergency load.

XI ATTACHMENTS

- 1 Memo to File, by S.L. Nader, Dated Jan.15, File K-201.
- 2 Telephone Conversation Report between John Beckman (Duke) and Jerry Runion (Woodward Gov. Co). Dated 9/22/93.
- 3 Keowee Unit 2 Governor Actuator inspection report following initial installation.

Memo To File

Jan. 15, 1993

Re: Oconee Nuclear Station
Keowee Hydro Station
Governor Operation
File: K-201

The purpose of this memo is to document the substance and conclusions of conversations on Jan. 13 and 14, 1993 addressing the potential single failures that could affect the governor at Keowee. Individuals involved in these conversations were Bob Dobson, Julian Davis and Dhiaa Jamil, Oconee Electrical Engineering; Steve Nader and John Beckman, Oconee Mechanical Engineering; Don Couch, Keowee Station Manager; Rick Gerbers, Hydro Maintenance; Bob Howell, DESI; Bob Hall, McGuire Mechanical Engineering; and an engineering representative from Woodward Governor Co.

The conclusion reached by all members of the discussion was that there are no credible design basis mechanical failures that could affect the governor without also tripping the unit. The following scenarios were discussed. One or both Keowee units are generating to the grid when Oconee has a LOCA/LOOP requiring emergency loads to be supplied from Keowee. Keowee has a load rejection, isolating it from the grid. The question at this point is are there any credible single failures of the governor that might keep the unit running at a speed other than design (128.6 rpm). Keeping in mind that if the governor closes the wicket gates, the unit will trip; and if the governor opens the wicket gates the overspeed switch will trip the unit, discussions focused on potential failures that might keep the wicket gates in some "stuck" mid-position. (It should be noted that the Woodward representative could recall no instances in his 16 years experience when this had occurred).

Complete sudden loss of hydraulic oil pressure was postulated. This would result in no movement of the wicket gates. This is beyond design basis. No passive failures must be assumed except in ECCS systems in long term operation. Other failures in the hydraulic oil system such as loss of governor oil pumps or failure of the valve in the oil pressure tank will result in a slow loss of pressure over the long term. However the oil tank is designed for three opening strokes of the wicket gates. With the expected small variances in electrical load after an accident, the stored oil pressure will be sufficient for the period of time necessary to recover oil pressurization capability.

A failure in the wiring from the Permanent Magnet Generator (PMG) to the ball head will result in the ball head sensing no or low speed, thereby opening the wicket gates. An overspeed trip will trip the unit.

A failure of the Partial Shutdown Solenoid Valve will result in a gate position of 23% - 25% open. This gate position yields sufficient MW to satisfy ONS emergency power loads. The governor would continue to operate as designed, adjusting wicket gate

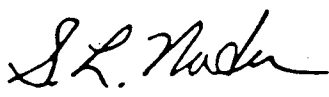
position to match load.

Servomotor failure was also considered. The servomotor is essentially a large hydraulically operated piston valve. Based on experience it is not expected that a stuck piston is credible. The high hydraulic oil pressure will result in very large piston forces. Credible foreign objects would not be able to interfere with piston operation. In addition, standard single failure licensing rules do not assume partial stroking of valves. They either work as designed or fail to their as-designed failure position. Therefore any credible failure will be expected to trip the unit.

The failure of linkages within the governor and wicket gate shear pins was also evaluated. These components are considered to be passive, inherently rugged items whose failure need not be postulated. Normal operation of the unit would reveal actual problems with these components should they occur.

In general it has been the Oconee position to not consider "smart failure" within control systems. The system is assumed to control as designed or to fail to its as-designed state.

Based on the above, it was concluded that the Keowee governor will continue to operate or result in a tripped unit for all credible design basis single failures.



S.L.Nader
Engineering Supervisor
Oconee Mechanical Engineering

cc: R.L.Dobson, D.M.Jamil, J.B.Beckman, B.J.Dolan

DUKE POWER COMPANY
TELEPHONE CONVERSATION REPORT

PROJECT Keowee FILE NO. K-201
SUBJECT Keowee Governor Dash POT
PERSON CALLED Jerry Runion Woodward Gov. Co.
DATE 8/22/93 TIME 13:00
PERSON CALLING John Beckman
SPECIFICATION NUMBER KC-UNIT 1-2-0098

SUBJECT DISCUSSED Unit operation with
Compensating Dash POT Bypass Solenoid
energized

RECOMMENDATION OR RESOLUTION When The Bypass
Solenoid is energized, The Governor operates
without The Compensating Dash POT Bypassed.
This means That the unit will become
Slightly unstable w.r.t. speed. Jerry
said that speed swings would be less
than $\pm 3\%$

SIGNED:

John B. Beckman

Duke Power Company --- Keowee Development ---

Unit # 2

MECHANICAL FEATURES		ELECTRICAL FEATURES	
Drawings Checked for Latest Change		Diagrams Checked for Latest Change	
Serial Number <u>551216</u>		Cabinet Light and Switch <u>OK</u>	
Normal Speed <u>125.6</u> PMG <u>355</u> Ballhead		Tachometer & Rotation Signal Coupler <u>OK</u>	
0= <u>386</u> RPM at 5% Gate		Gate Limit & Gate Position Trans. <u>OK</u>	
Speed <u>386</u> RPM at 50% Gate		Speed Adjustment Trans. <u>110 VAC</u> <u>OK</u>	
Droop <u>386</u> RPM at 95% Gate		Speed Droop Trans. <u>None</u>	
5% - XXXXX <u>396</u> RPM at 5% Gate		Shutdown Solenoid <u>Inenergize</u> S. D. <u>OK</u> (De-energize)	
<u>386.8</u> RPM at 50% Gate		Speed No Load Sol. <u>X(Energize)X</u> S. D. <u>OK</u> (De-energize)	
<u>377.2</u> RPM at 95% Gate		Reset Solenoids <u>None</u>	
RPM + 10% Dial		Dashpot Sol. Operated Bypass <u>OK</u>	
<u>406</u> RPM + 5% Dial		Sol. Operated Brake Valve <u>OK</u>	
Speed <u>366</u> RPM - 5% Dial		Speed Adjustment Limit Switch <u>1 Pole</u> <u>OK</u>	
Adjustment <u>345.2</u> RPM - 10% Dial		Gate Position Limit Switch <u>6 Pole</u> <u>OK</u>	
<u>372.5</u> RPM - 15% Dial		Gate Limit (R. H.) Limit Switch <u>5 Pole</u> <u>OK</u>	
Max. Gate/Max. Droop/Max. Speed <u>396</u> RPM		Gen. Brake Control Switch <u>OK</u>	
Min. Gate/ 0 Droop/Min. Speed _____ RPM		Dashpot Solenoid Switch <u>None</u>	
w Through Inner Hole		Pump Control Switch <u>(3)</u> <u>OK</u>	
Outer Hole		Brake Timer <u>OK</u>	
Transfer Valve & Gauge <u>OK</u>		Magnetic Starter <u>None</u>	
Auxiliary Valve <u>OK</u>		Indicating Lights <u>(4)</u> <u>OK</u>	
Gate Limit & Gate Position Ind. <u>OK</u>		Gate Limit Potentiometer Trans. <u>(2)</u> <u>OK</u>	
Oil Pressure Gauge <u>OK</u>		Gate Pos. Potentiometer Trans. <u>(2)</u> <u>OK</u>	
Air Brake Gauge <u>OK</u>		Shutdown Sol. Aux. Contact <u>5 Pole</u> <u>OK</u>	
Manual Shutdown & Reset <u>None</u>		Shutdown & Reset Control Sw. <u>OK</u>	
Compensating Cable Travel <u>22.875</u> in. <u>OK</u>		Spd. No Load Sol. Aux. Contact <u>5 Pole</u> <u>OK</u>	
Kaplan Valve & Restoring <u>None</u>		Coincident Switch <u>OK</u>	
Oil Motor (Vibrator) <u>OK</u>		S.N.L. Selector Switch (Power Supply) <u>OK</u>	
Cotter Pins etc. <u>OK</u>		Dual Gate Lock Sol. Valve Energ. To Act	
Check for Oil Leaks etc. <u>OK</u>		Main-Aux. Transfer Valve Switch <u>OK</u>	
Ballhead Motor Disconnect Sw. <u>OK</u>		Ohmmer Check of Ballhead Motor	
SNL Setting Relays (2) <u>OK</u>		1--- Tachometer	
Sump Tank Oil Level Sw. (Pumping Unit) <u>OK</u>		1--- Dual Indicator	
Voltage Comp. Assy. For SNL Net Hd. <u>OK</u>		Switchboard <u>OK</u> 1--- Spd. Adj. Indic	
Power Supply Assy. For Volt Comp. <u>OK</u>		Instruments _____	
SNL Settings Vs. Net Hd. Cam Assem. <u>OK</u>		Press. Tank Oil Level Trans.	
Rotation Signal Transmitter <u>OK</u>		Actuator Inspected by <u>[Signature]</u> Date <u>10-18-64</u>	
Rotation Signal Transmitter Relay <u>OK</u>		Wiring Inspected by <u>[Signature]</u> Date <u>10-22-64</u>	
Not Test - Witnessed By <u>[Signature]</u>		PMG & Auxiliaries <u>[Signature]</u> Date <u>10-18-64</u>	
Gate Lock <u>10-22-64</u>			
Press. Tank Float Valve			
Tank Inspected by _____ Date _____			

Safety Valve Bushing # 8-1000-E Hand _____
 Hapian Valve Bushing# NONE Hand _____

Limit Motor 125 Volts ~~AC~~ /D.C.
31.5 Sec. From 0 Gate to 100% Gate
31.5 Sec. From 100% Gate to 0 Gate

Syn. Motor 125 Volts ~~AC~~ /D.C.
86 Sec. From 0 Adj. to - 15% Adj.
84 Sec. From -15% Adj. to 0 Adj.

PUMP "A" (Standing at Front of Unit Pump "A" Furthest to Right)

Motor Mfg. Allis Chalmers Serial # 1-5103-25342-2HP 50
 Capacity 198 G.P.M. Safety Opens at 383 P.S.I.
 On Lead Position Loads at 318 P.S.I. Unloads at 350 P.S.I.
 On Lag Position Loads at 298 P.S.I. Unloads at 331 P.S.I.

PUMP "B" (Standing at Front of Unit Pump "B" Furthest Left)

Motor Mfg. Allis Chalmers Serial # 1-5103-25342-2-5HP 50
 Capacity 198 G.P.M. Safety Opens at 386 P.S.I.
 On Lead Position Loads at 316 P.S.I. Unloads at 350 P.S.I.
 On Lag Position Loads at 298 P.S.I. Unloads at 332 P.S.I.

OIL PRESSURE FAILURE SWITCHES

1 -- C.L.P. / ~~O.L.P.~~ At 275 P.S.I. --- Resets At 288 P.S.I. *oil*
 # 2 -- C.L.P. / ~~O.L.P.~~ At 250 P.S.I. --- Resets At 257 P.S.I. "
 # 3 -- C.L.P. / ~~O.L.P.~~ At 250 P.S.I. --- Resets At 256 P.S.I. "
~~# 4 -- C.L.P. / O.L.P. At _____ P.S.I. Reset At _____ P.S.I.~~
~~# 5 -- C.L.P. / O.L.P. At _____ P.S.I. Reset At _____ P.S.I.~~
~~# 6 -- C.L.P. / O.L.P. At _____ P.S.I. Reset At _____ P.S.I.~~
~~# 7 -- C.L.P. / O.L.P. At _____ P.S.I. Reset At _____ P.S.I.~~
 C.L.P. O.L.P. At 50 P.S.I. Reset At 57 P.S.I. Air
~~C.L.P. / O.L.P. At _____ P.S.I. Reset At _____ P.S.I. Air~~

*Removed
 at Custom
 Request*

Factor Mfg. ALLS. CRANERS

Serial # 1-5103-25342-2-3 HP 50

City 198 G.P.M.

Safety Opens at 388 P.S.I. CENTER
PUMP

On Lead Position
Loads at 316 P.S.I.

Unloads at 350 P.S.I.

On Lag Position
Loads at 294 P.S.I.

Unloads at 326 P.S.I.

UNIT 1
October 24, 1969

ATT 3 Py 4 of 5

HEADWATER ELEVATION	HEADWATER ELEVATION POTENTIOMETER SETTING	NET HEAD	TAILWATER ELEVATION	TAILWATER ELEVATION POTENTIOMETER SETTING	SNL GATE POSITION
775	000	100 Ft.	675	513	30.250%
		90 Ft.	685	769	32.750%
		81 Ft.	694	1000	34.250%
785	400	100 Ft.	685	769	29.750%
		91 Ft.	694	1000	32.500%
	760	100 Ft.	694	1000	30.500%
800	1000	136 Ft.	664	230	20.750%
796	840	128 Ft.	668	333	22.500%
792	680	120 Ft.	672	436	24.750%
788	520	112 Ft.	676	538	27.000%
	360	104 Ft.	680	641	29.000%
780	200	96 Ft.	684	744	31.000%
784	360	104 Ft.	680	641	29.750%
788	520	112 Ft.	676	538	27.500%
792	680	120 Ft.	672	436	25.250%
796	840	128 Ft.	668	333	23.000%
800	1000	136 Ft.	664	230	20.500%

*37 Crittenden Elect. Engr.
Haines, Staftman
Schleicher Eng. Inc.*

TESTED BY

Stan Haines
Ben Schleicher

DATE 10/21/69
NAME H. Juhlin

P. M. G. ACCEPTANCE DATA

UNIT NAME Keowee Development 01117 2 ACTUATOR NO. 851616
SHOP ORDER NO. HC-582

P. M. G. SPECIFICATION

NO. OF RINGS 3 NO. OF POLES _____ STATOR ORDER NO. 200147
FRAME _____ WIRING SPEC. NOS. 9972-162

NAME PLATE DATA

SPEED 128.6 R. P. M. FREQUENCY 6.4 CYCLES 3 PHASE
FULL LOAD VOLTS 64 NO LOAD VOLTS 94
FULL LOAD CURRENT 2.2 AMPS. SERIAL NO. 851616

BALLHEAD MOTOR SPECIFICATION

FRAME _____ FREQUENCY _____ VOLTAGE _____
STACK THICKNESS _____ INCHES NO. OF POLES _____
WIRING SPEC. NOS. _____

MAGNETIZATION DATA BY H. Juhlin

MAG. VOLTS 117.0 MAG. CURRENT 60 AMPS

OPERATION DATA BY H. Juhlin

INITIAL NO LOAD VOLTAGE 115 FINAL NO LOAD VOLTAGE 94
INITIAL FULL LOAD VOLTAGE 87 FINAL FULL LOAD VOLTAGE 76
FULL LOAD CURRENT 2.2 AMPS.

WORKS: TESTER Walter K. Pappas
INSPECTOR J. Brantley
SUPERVISOR W. M. K. Miller