

Figure 7.1-1—Chapter 7 Symbol Legend
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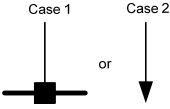
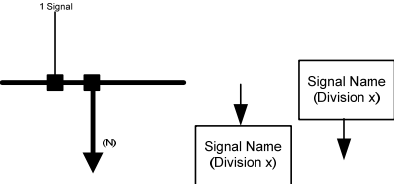



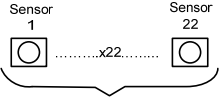
Symbols – Logic Figures	Definition
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	Sensor Measurement Signal
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Figure 7.1-1—Chapter 7 Symbol Legend
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Symbols – Logic Figures	Definition
	Multiple Signals of the Same Type
	Single Signal (2 Cases)
	Signal Transfer Between Divisions
	Signal Sent Elsewhere in Figure
	Signal Received from Elsewhere in Figure
	The logic within the block is duplicated in other divisions of the system.
	Multiple instances of the same type of object. Multiple sensors are given as an example. This convention is also applied to signal arrows and calculation boxes.

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Figure 7.1-1—Chapter 7 Symbol Legend
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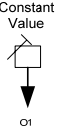
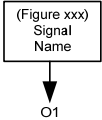
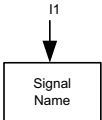
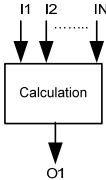
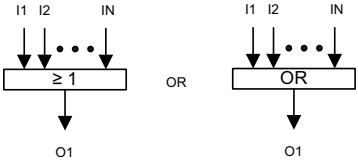
Symbols – Logic Figures	Definition
	<p>Constant Value Generator</p>
	<p>Signal Generated in Another Figure</p>
	<p>Result of Logic or Signal Sent to Another Figure</p>
	<p>“Black Box” Calculation</p>
	<p>OR Function</p>

Figure 7.1-1—Chapter 7 Symbol Legend
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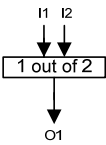
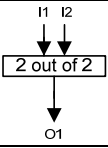
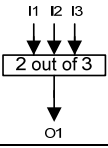
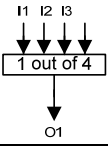
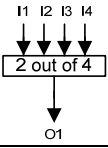
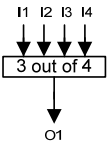
Symbols – Logic Figures	Definition															
<p> I_1 I_2 ↓ ↓ & O_1 </p> <p>or</p> <p> I_1 I_2 ↓ ↓ AND O_1 </p> <table border="1" style="display: inline-table; vertical-align: middle;"> <tr> <td>I_1</td> <td>I_2</td> <td>O_1</td> </tr> <tr> <td>F</td> <td>F</td> <td>F</td> </tr> <tr> <td>T</td> <td>F</td> <td>F</td> </tr> <tr> <td>F</td> <td>T</td> <td>F</td> </tr> <tr> <td>T</td> <td>T</td> <td>T</td> </tr> </table>	I_1	I_2	O_1	F	F	F	T	F	F	F	T	F	T	T	T	AND Function
I_1	I_2	O_1														
F	F	F														
T	F	F														
F	T	F														
T	T	T														
<p> I_1 ↓ max Max # O_1 </p>	High Threshold															
<p> I_1 ↓ min Min # O_1 </p>	Low Threshold															
<p> I_1 ↓ I_2 → min O_1 </p>	Low Variable Threshold															
<p> I_1 ↓ I_2 → max O_1 </p>	High Variable Threshold															

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Figure 7.1-1—Chapter 7 Symbol Legend
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Symbols – Logic Figures	Definition															
	On Time Delay															
	Off Time Delay															
<table border="1" data-bbox="730 703 814 816"> <thead> <tr> <th>I1</th> <th>I2</th> <th>O1</th> </tr> </thead> <tbody> <tr> <td>F</td> <td>F</td> <td>F</td> </tr> <tr> <td>T</td> <td>F</td> <td>T</td> </tr> <tr> <td>F</td> <td>T</td> <td>T</td> </tr> <tr> <td>T</td> <td>T</td> <td>F</td> </tr> </tbody> </table>	I1	I2	O1	F	F	F	T	F	T	F	T	T	T	T	F	XOR Function
I1	I2	O1														
F	F	F														
T	F	T														
F	T	T														
T	T	F														
	Logic Inversion															
	Pulse Function															

Figure 7.1-1—Chapter 7 Symbol Legend
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Symbols – Logic Figures	Definition
	1 out of 2 Function
	2 out of 2 Function
	2 out of 3 Function
	1 out of 4 Function
	2 out of 4 Function
	3 out of 4 Function

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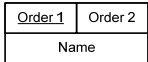
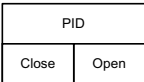
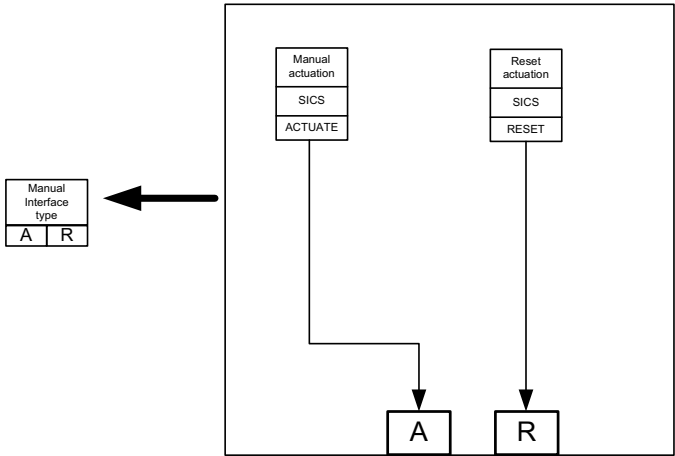
Figure 7.1-1—Chapter 7 Symbol Legend
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Symbols – Logic Figures	Definition
	<p>2nd Min Function</p>
	<p>2nd Max Function</p>
	<p>First Order Filter</p>
	<p>Second Order Filter</p>
	<p>Memory with Reset Priority</p> <p>NOTE: Leading edge of I1 going high causes O1 to go high, no matter the state of I2. Leading edge of I2 going high causes O1 to go low, no matter the state of I1.</p>

Figure 7.1-1—Chapter 7 Symbol Legend
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Symbols – Logic Figures	Definition
	<p>Memory with Set Priority</p> <p>NOTE: Leading edge of I1 going high causes O1 to go high, no matter the state of I2. Leading edge of I2 going high causes O1 to go low, only if I1 is in a low state.</p>
	<p>Analog Summation</p>
<p>If I3 = "0", O1 = I1 If I3 = "1", O1 = I2</p>	<p>Logic Switch</p>
<p>O1 is a function of I1 according to reference</p>	<p>Function Generator</p>
<p>O1 = the average of the input values</p>	<p>Average Function</p>

Figure 7.1-1—Chapter 7 Symbol Legend
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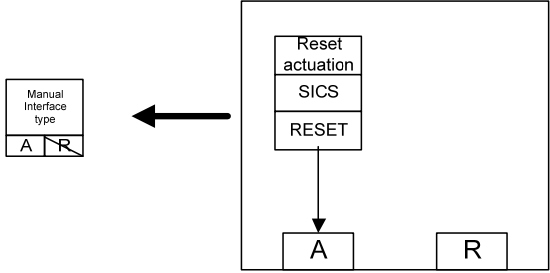
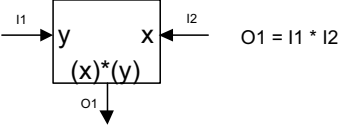
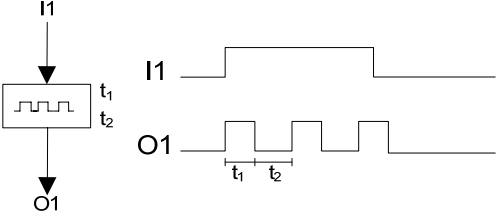
Symbols – Logic Figures	Definition
 <p>Actuator with one control order</p> <p>Name</p> <p>or</p>  <p>Actuator with two control orders (Priority order is underlined)</p>	<p>Outputs to Actuator</p>
 <p>PID Controller</p> <p>The controller structure is indicated in the symbol. It is a combination of</p> <p>“P” = proportional action enabled</p> <p>“I” = integral action enabled</p> <p>“D” = derivative action enabled</p>	<p>PID Controller</p>
<p>Manual Interface Block</p> 	<p>Manual Interface Block Actuate and Reset</p>

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Figure 7.1-1—Chapter 7 Symbol Legend
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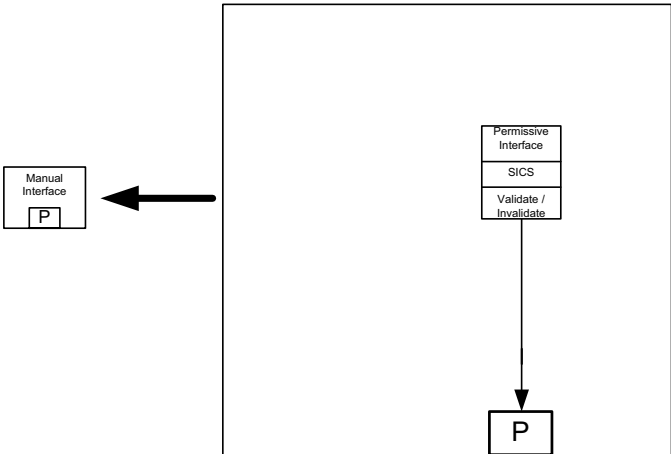
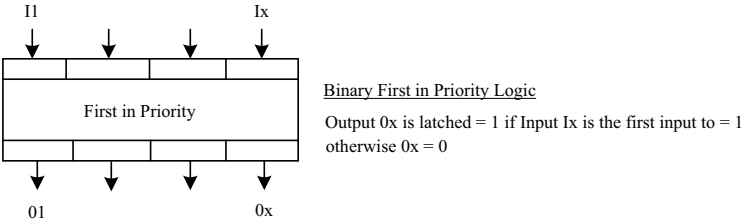
Symbols – Logic Figures	Definition
<p style="text-align: center;">Manual Interface Block (Reset only)</p>	<p>Manual Interface Block Reset Only</p>
<p style="text-align: center;">O1 = the absolute value of the input value</p>	<p>Absolute Value Function</p>

Figure 7.1-1—Chapter 7 Symbol Legend
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Symbols – Logic Figures	Definition
<p style="text-align: center;">Manual Interface Block (Actuate only)</p> 	<p>Manual Interface Block Actuate Only</p>
	<p>Multiplication Function</p>
	<p>Continuous Pulse Function</p>

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Figure 7.1-1—Chapter 7 Symbol Legend
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Symbols – Logic Figures	Definition
<p style="text-align: center;">Permissive Interface Block</p> 	<p>Permissive Interface Block</p>
 <p style="text-align: center;">Binary First in Priority Logic Output O_x is latched = 1 if Input I_x is the first input to = 1 otherwise O_x = 0</p>	<p>Binary First in Priority</p>
<p style="text-align: center;"><< or >> Line Continuation Symbol</p>	<p>Line Continuation</p>

**Figure 7.1-1—Chapter 7 Symbol Legend
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Acronym	Description
ALU	Actuation & Logic Unit
Amps	Ampere
APU	Acquisition & Processing Unit
Aux	Auxiliary
Blwndn	Blowdown
BYP	Bypass
CI	Containment Isolation
CI-V	Containment Isolation Valve
Cleg	Cold Leg
Cls	Close
CPL	Core Power Level
CRDM	Control Rod Drive Mechanism
C-V	Control Valve
CVCS	Chemical and Volume Control System (KBA)
DEGV	Degraded Voltage
Div	Division
DNB	Departure from Nucleate Boiling
DNBR	Departure from Nucleate Boiling Ratio
dP	Differential Pressure
DT	Doubling Time
D-V	Drain Valve
EDG	Emergency Diesel Generator
EFW	Emergency Feedwater
EFWS	Emergency Feedwater System

**Figure 7.1-1—Chapter 7 Symbol Legend
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Acronym	Description
Ex	Exercise
FCV	Flow Control Valve
FLD	Full Load
FST	Fast
HL	Hot Leg
HLEG	Hot Leg
HLPD	High Linear Power Density
IMB	Imbalance
IRD	Intermediate Range Detector
I-V	Isolation Valve
LCV	Level Control Valve
LLD	Low Load
LOOP	Loss of Offsite Power
LOV	Loss of voltage
LPD	Linear Power Density
Max	Maximum
MaxRD	Maximum Rod Drop
MCR	Main Control Room
MFW	Main Feedwater
Min	Minimum
MS	Main Steam
MSIV	Main Steam Isolation Valve
MSRCV	Main Steam Relief Control Valve
MSRIV	Main Steam Relief Isolation Valve
MSRT	Main Steam Relief Train

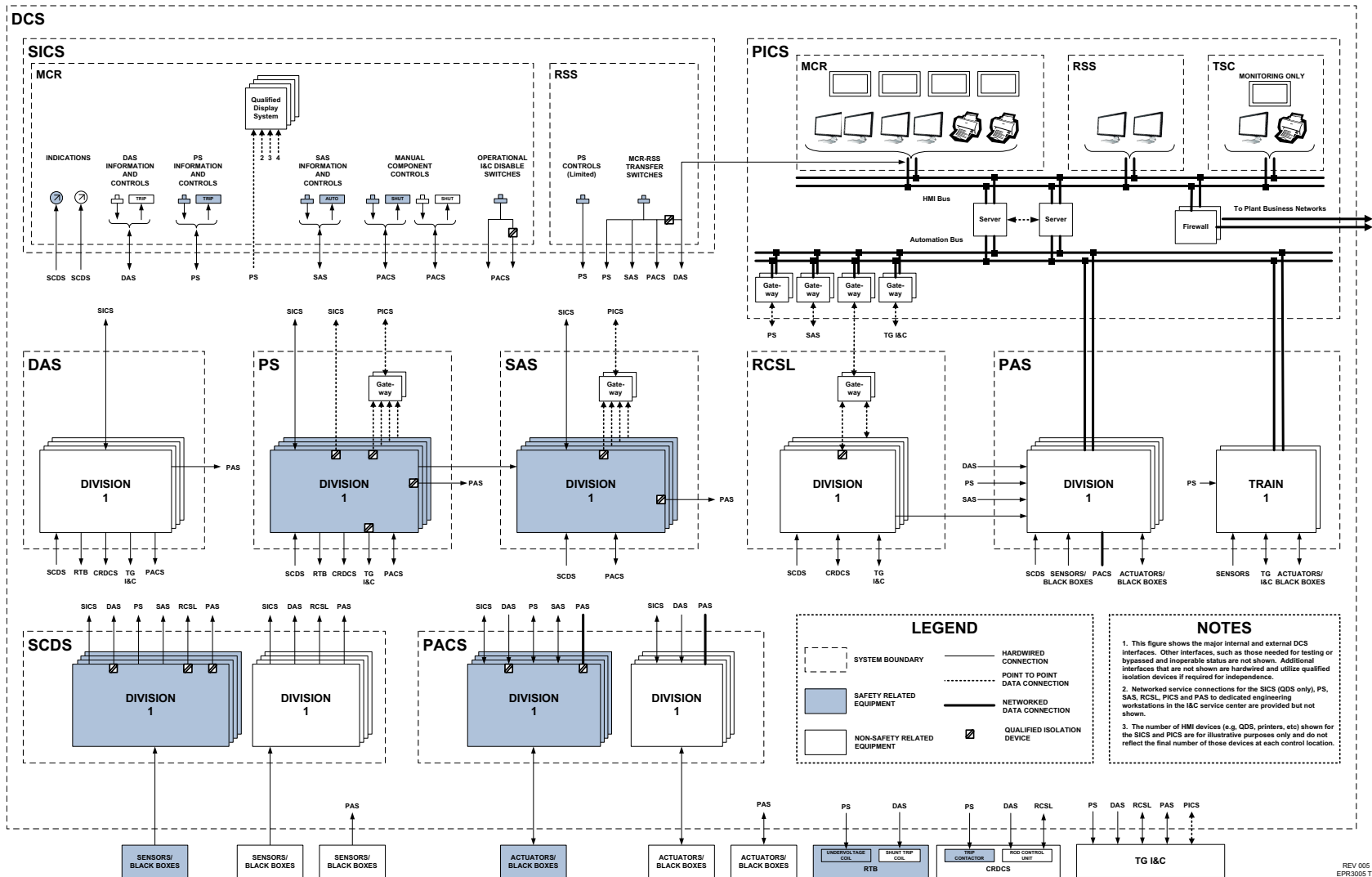
**Figure 7.1-1—Chapter 7 Symbol Legend
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Acronym	Description
NF	Neutron Flux
Norm	Normal
NR	Narrow Range
PICS	Process Information and Control System
PIL V	Pilot Valve
PRD	Power Range Detector
Press	Pressure
Psat	Saturation Pressure
PSRV	Pressurizer Safety Relief Valve
PZR	Pressurizer
QROC	Flux Rate of Change
QUAL	Quality
RAU	Remote Acquisition Unit
RCCA	Rod Cluster Control Assembly
RCPS	Reactor Coolant Pump Speed
RCP	Reactor Coolant Pump
RD	Rod Drop
RT	Reactor Trip
SAS	Safety Automation System
SAT	Saturation
SI	Safety Injection
SICS	Safety Information and Control System
SIS	Safety Injection System
SG	Steam Generator
SGPD	Steam Generator Pressure Drop

**Figure 7.1-1—Chapter 7 Symbol Legend
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Acronym	Description
SOV	Solenoid Operated Valve
SP	Set Point
SPND	Self Powered Neutron Detector
SSS	Startup Shutdown System
T1, T2, T3, T4	Train 1, Train 2, Train 3, Train 4
TDEGV	Time Delay – Degraded Voltage
TEMP	Temperature
TLOV	Time Delay – Loss of Voltage
U.V.Coil	Under Voltage Coil
VLLD	Very Low Load
VCT	Volume Control Tank
WR	Wide Range

Figure 7.1-2—Distributed Control System Functional Architecture



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Figure 7.1-3—Safety Information and Control System Architecture (QDS Portion)

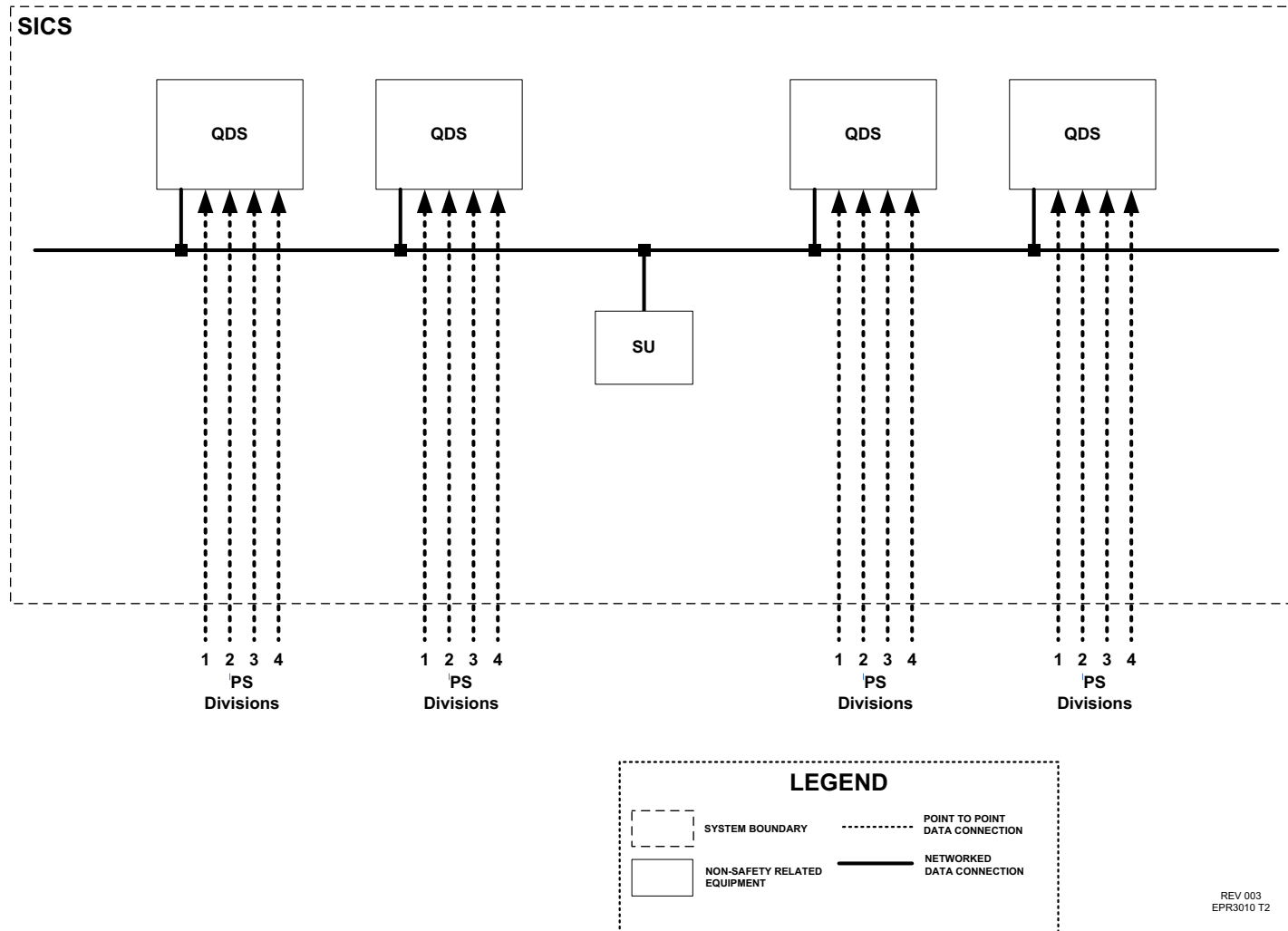


Figure 7.1-4—Deleted

Figure 7.1-5—Deleted