

### 2.8.6 Main Feedwater System

#### **Design Description**

#### 1.0 System Description

The main feedwater system (MFWS) is a non-safety-related system with portions that are safety related. It transports and controls feedwater from the deaerator/feedwater storage tank to the steam generators (SG). It includes the startup/shutdown feedwater supply. The MFWS is safety related from the connections to the SGs to the fixed seismic restraint in each main feedwater line and to the fixed seismic restraint in each startup/shutdown feedwater line.

The MFWS provides the following safety-related function:

• Shut off main feedwater supply and startup/shutdown feedwater supply.

The MFWS provides the following non-safety-related functions:

- The MFWS supplies feedwater to the SGs for power operation.
- A startup/shutdown system supplies feedwater to the SGs for low-power operation.

## 2.0 Arrangement

- 2.1 The functional arrangement of the MFWS is as described in the Design Description of Section 2.8.6, Tables 2.8.6-1—MFWS Equipment Mechanical Design and 2.8.6-2—MFWS Equipment I&C and Electrical Design, and as shown on Figure 2.8.6-1—MFWS Functional Arrangement.
- 2.2 Deleted.
- 2.3 Physical separation exists between divisions of the safety-related portions of MFWS as listed in Table 2.8.6-1.

#### 3.0 Mechanical Design Features

- 3.1 Valves listed in Table 2.8.6-1 will be functionally designed and qualified such that each valve is capable of performing its intended function for a full range of system differential pressure and flow, ambient temperatures, and available voltage (as applicable) under design basis accident conditions.
- 3.2 Check valves listed in Table 2.8.6-1 will function to change position as listed in Table 2.8.6-1 under normal operating conditions.
- 3.3 Deleted.
- 3.4 Equipment identified as Seismic Category I in Table 2.8.6-1 can withstand seismic design basis loads without a loss of the function listed in Table 2.8.6-1.





3.5	ASME Code Class 1, 2 and 3 piping systems are designed in accordance with ASME Code Section III requirements.
3.6	As-built ASME Code Class 1, 2 and 3 components are reconciled with the design requirements.
3.7	Pressure-boundary welds in ASME Code Class 1, 2 and 3 components meet ASME Code Section III non-destructive examination requirements.
3.8	ASME Code Class 1, 2 and 3 components retain their pressure-boundary integrity at their design pressure.
3.9	ASME Code Class 1, 2 and 3 components are fabricated, installed, and inspected in accordance with ASME Code Section III requirements.
3.10	Deleted.
3.11	Deleted.
3.12	Deleted.
3.13	Deleted.
3.14	Deleted.
4.0	Instrumentation and Control (I&C) Design Features, Displays, and Controls
4.1	Displays listed in Table 2.8.6-2 are indicated on the PICS operator workstations in the MCR and the RSS.
4.2	Controls on the PICS operator workstations in the MCR perform the function listed in Table 2.8.6-2.
4.2	
	Table 2.8.6-2.  Equipment listed as being controlled by a priority and actuator control system (PACS) module in Table 2.8.6-2 responds to the state requested and provides drive monitoring signals back to the PACS module. The PACS module will protect the equipment by
4.3	Table 2.8.6-2.  Equipment listed as being controlled by a priority and actuator control system (PACS) module in Table 2.8.6-2 responds to the state requested and provides drive monitoring signals back to the PACS module. The PACS module will protect the equipment by terminating the output command upon the equipment reaching the requested state.
<b>4.3 5.0</b>	Table 2.8.6-2.  Equipment listed as being controlled by a priority and actuator control system (PACS) module in Table 2.8.6-2 responds to the state requested and provides drive monitoring signals back to the PACS module. The PACS module will protect the equipment by terminating the output command upon the equipment reaching the requested state.  Electrical Power Design Features  Equipment designated as Class 1E in Table 2.8.6-2 are powered from the Class 1E
<b>5.0</b> 5.1	Table 2.8.6-2.  Equipment listed as being controlled by a priority and actuator control system (PACS) module in Table 2.8.6-2 responds to the state requested and provides drive monitoring signals back to the PACS module. The PACS module will protect the equipment by terminating the output command upon the equipment reaching the requested state.  Electrical Power Design Features  Equipment designated as Class 1E in Table 2.8.6-2 are powered from the Class 1E division as listed in Table 2.8.6-2 in a normal or alternate feed condition.  The main feedwater full load isolation valves (MFWFLIV) fail closed on loss of



#### 6.0 Environmental Qualifications

6.1 Equipment designated as harsh environment in Table 2.8.6-2 will perform the function listed in Table 2.8.6-1 under normal environmental conditions, containment test conditions, anticipated operational occurrences, and accident and post-accident environmental conditions.

## 7.0 Equipment and System Performance

7.1 Class 1E valves listed in Table 2.8.6-2 will function to change position as listed in Table 2.8.6-1 under normal operating conditions.

## Inspections, Tests, Analyses, and Acceptance Criteria

Table 2.8.6-3 lists the MFWS ITAAC.



Table 2.8.6-1—MFWS Equipment Mechanical Design Sheet 1 of 2

Description	Tag Number <sup>(1)</sup>	Location	ASME Code Section III	Function	Seismic Category
Main Feedwater Full Load Isolation Valves (MFWFLIV)	30LAB60AA001 30LAB70AA001 30LAB80AA001 30LAB90AA001	1UJE26001 2UJE26001 3UJE26001 4UJE26001	Yes	Close	I
Main Feedwater Full Load Control Valves (MFWFLCV)	30LAB60AA101 30LAB70AA101 30LAB80AA101 30LAB90AA101	1UJE26001 2UJE26001 3UJE26001 4UJE26001	Yes	Close	I
Main Feedwater Isolation Valves (MFWIV)	30LAB60AA002 30LAB70AA002 30LAB80AA002 30LAB90AA002	1UJE26001 2UJE26001 3UJE26001 4UJE26001	Yes	Close	I
Main Feedwater Check Valves (MFWCKV)	30LAB60AA003 30LAB70AA003 30LAB80AA003 30LAB90AA003	Reactor Building Reactor Building Reactor Building Reactor Building	Yes	Close	I
Main Feedwater Low Load Isolation Valves (MFWLLIV)	30LAB64AA001 30LAB74AA001 30LAB84AA001 30LAB94AA001	1UJE26001 2UJE26001 3UJE26001 4UJE26001	Yes	Close	I
Main Feedwater Low Load Control Valves (MFWLLCV)	30LAB64AA101 30LAB74AA101 30LAB84AA101 30LAB94AA101	1UJE26001 2UJE26001 3UJE26001 4UJE26001	Yes	Close	I



Table 2.8.6-1—MFWS Equipment Mechanical Design Sheet 2 of 2

Description	Tag Number <sup>(1)</sup>	Location	ASME Code Section III	Function	Seismic Category	
Main Feedwater Very Low Load Control Valves (MFWVLLCV)	30LAB64AA102 30LAB74AA102 30LAB84AA102 30LAB94AA102	1UJE26001 2UJE26001 3UJE26001 4UJE26001	Yes	Close	I	
Deaerator/Feedwater Storage Tank	30LAA10BB001	Turbine Building	N/A	N/A	N/A	
High-Pressure Feedwater Heaters	N/A	Turbine Building	N/A	N/A	N/A	
Main Feedwater Pump	30LAC11AP001	Turbine Building	N/A	N/A	N/A	
Main Feedwater Pump	30LAC12AP001	Turbine Building	N/A	N/A	N/A	
Main Feedwater Pump	30LAC13AP001	Turbine Building	N/A	N/A	N/A	
Main Feedwater Pump	30LAC14AP001	Turbine Building	N/A	N/A	N/A	
Startup/Shutdown Feedwater Pump	30LAJ10AP001	Turbine Building	N/A	N/A	N/A	

<sup>1.</sup> Equipment tag numbers are provided for information only and are not part of the certified design.



Table 2.8.6-2—MFWS Equipment I&C and Electrical Design Sheet 1 of 2

Description	Tag Number <sup>(1)</sup>	Location	IEEE Class 1E <sup>(2)</sup>	EQ – Harsh Env.	PACS	MCR/RSS Displays	MCR/RSS Controls
Main Feedwater Full Load Isolation Valves	30LAB60AA001	SB 1	$3^{ m N}, 1^{ m N} \ 4^{ m A}, 2^{ m A}$	Yes	Yes	Position / Position	Close / Close
(MFWFLIV)	30LAB70AA001	SB 1	$4^{ m N}, 2^{ m N} \ 3^{ m A}, 1^{ m A}$				
	30LAB80AA001	SB 4	$1^{ m N}, 3^{ m N} \ 2^{ m A}, 4^{ m A}$				
	30LAB90AA001	SB 4	2 <sup>N</sup> , 4 <sup>N</sup> 1 <sup>A</sup> , 3 <sup>A</sup>				
Main Feedwater Full	30LAB60AA101	SB 1	1 <sup>N</sup> , 2 <sup>A</sup>	Yes	Yes	Position / Position	Close / Close
Load Control Valves (MFWFLCV)	30LAB70AA101	SB 1	2 <sup>N</sup> , 1 <sup>A</sup>				
(	30LAB80AA101	SB 4	3 <sup>N</sup> , 4 <sup>A</sup>				
	30LAB90AA101	SB 4	4 <sup>N</sup> , 3 <sup>A</sup>				
Main Feedwater	30LAB60AA002	SB 1	1 <sup>N</sup> , 2 <sup>A</sup>	Yes	Yes	Position / Position	Close / Close
Isolation Valves (MFWIV)	30LAB70AA002	SB 1	2 <sup>N</sup> , 1 <sup>A</sup>				
	30LAB80AA002	SB 4	3 <sup>N</sup> , 4 <sup>A</sup>				
	30LAB90AA002	SB 4	$4^{N}, 3^{A}$				



Table 2.8.6-2—MFWS Equipment I&C and Electrical Design Sheet 2 of 2

Description	Tag Number <sup>(1)</sup>	Location	IEEE Class 1E <sup>(2)</sup>	EQ – Harsh Env.	PACS	MCR/RSS Displays	MCR/RSS Controls
Main Feedwater Low	30LAB64AA001	SB 1	3 <sup>N</sup> , 4 <sup>A</sup>	Yes	Yes	Position / Position	Close / Close
Load Isolation Valves (MFWLLIV)	30LAB74AA001	SB 1	4 <sup>N</sup> , 3 <sup>A</sup>				
	30LAB84AA001	SB 4	1 <sup>N</sup> , 2 <sup>A</sup>				
	30LAB94AA001	SB 4	2 <sup>N</sup> , 1 <sup>A</sup>				
Main Feedwater Low	30LAB64AA101	SB 1	1 <sup>N</sup> , 2 <sup>A</sup>	Yes	Yes	Position / Position	Close / Close
Load Control Valves (MFWLLCV)	30LAB74AA101	SB 1	2 <sup>N</sup> , 1 <sup>A</sup>				
	30LAB84AA101	SB 4	3 <sup>N</sup> , 4 <sup>A</sup>				
	30LAB94AA101	SB 4	4 <sup>N</sup> , 3 <sup>A</sup>				
Main Feedwater Very	30LAB64AA102	SB 1	1 <sup>N</sup> , 2 <sup>A</sup>	Yes	Yes	Position / Position	Close / Close
Low Load Control Valves (MFWVLLCV)	30LAB74AA102	SB 1	2 <sup>N</sup> , 1 <sup>A</sup>				
	30LAB84AA102	SB 4	3 <sup>N</sup> , 4 <sup>A</sup>				
	30LAB94AA102	SB 4	$4^{\mathrm{N}}, 3^{\mathrm{A}}$				

- 1. Equipment tag numbers are provided for information only and are not part of the certified design.
- 2. N denotes the division equipment is normally powered from; A denotes the division equipment is powered from when alternate feed is implemented.



Table 2.8.6-3—Main Feedwater System ITAAC Sheet 1 of 6

	Commitment Wording	Inspections, Tests, Analyses	Acceptance Criteria
2.1	The functional arrangement of the MFWS is as described in the Design Description of Section 2.8.6, Tables 2.8.6-1 and 2.8.6-2, and as shown on Figure 2.8.6-1.	An inspection of the as-built MFWS functional arrangement will be performed.	The MFWS conforms to the functional arrangement as described in the Design Description of Section 2.8.6, Tables 2.8.6-1 and 2.8.6-2, and as shown on Figure 2.8.6-1.
2.2	Deleted.	Deleted.	Deleted.
2.3	Physical separation exists between divisions of the safety-related portions of MFWS as listed in Table 2.8.6-1.	An inspection will be performed to verify that the as-built safety-related portions of the MFWS are located in separate valve rooms in Safeguard Buildings 1 and 4.	The divisions of the safety-related portions of the MFWS are located in separate valve rooms in Safeguard Buildings 1 and 4 as listed in Table 2.8.6-1.
3.1	Valves listed in Table 2.8.6-1 will be functionally designed and qualified such that each valve is capable of performing its intended function for a full range of system differential pressure and flow, ambient temperatures, and available voltage (as applicable) under design basis accident conditions.	Tests or type tests of valves will be performed to demonstrate that the valves function under design basis accident conditions.	A report concludes that the valves listed in Table 2.8.6-1 are capable of performing their intended function for a full range of system differential pressure and flow, ambient temperatures, and available voltage (as applicable) under design basis accident conditions.
3.2	Check valves listed in Table 2.8.6-1 will function to change position as listed in Table 2.8.6-1 under normal operating conditions.	Tests will be performed to verify the ability of check valves to change position under normal operating conditions.	The check valves change position as listed in Table 2.8.6-1 under normal operating conditions.
3.3	Deleted.	Deleted.	Deleted.



Table 2.8.6-3—Main Feedwater System ITAAC Sheet 2 of 6

	Commitment Wording	Inspections, Tests, Analyses	Acceptance Criteria
3.4	Equipment identified as Seismic Category I in Table 2.8.6-1 can withstand seismic design basis loads without a loss of the function listed in Table 2.8.6-1.	<ul> <li>a. Type tests, analyses, or a combination of type tests and analyses will be performed on the equipment identified as Seismic Category I in Table 2.8.6-1 using analytical assumptions, or under conditions, which bound the Seismic Category I design requirements.</li> <li>b. An inspection will be performed of the as-built equipment identified as Seismic Category I in Table 2.8.6-1 to verify that the equipment, including anchorage, are installed per the approved design requirements.</li> </ul>	<ul> <li>a. Test/analysis reports conclude that the equipment identified as Seismic Category I in Table 2.8.6-1 can withstand seismic design basis loads without a loss of the function listed in Table 2.8.6-1 including the time required to perform the listed function.</li> <li>b. Inspection reports conclude that the equipment identified as Seismic Category I in Table 2.8.6-1, including anchorage, are installed per the approved design requirements.</li> </ul>
3.5	ASME Code Class 1, 2 and 3 piping systems are designed in accordance with ASME Code Section III requirements.	An inspection of piping design and analysis documentation required by the ASME Code Section III will be performed. {{DAC}}	ASME Code Section III Design Report(s) exist that meet the requirements of NCA-3550 and conclude that the design of the ASME Code Class 1, 2 and 3 piping system complies with the requirements of the ASME Code Section III. {{DAC}}
3.6	As-built ASME Code Class 1, 2 and 3 components are reconciled with the design requirements.	A reconciliation analysis of ASME Code Class 1, 2 and 3 components will be performed.	ASME Code Design Report(s) exist that meet the requirements of NCA-3550, conclude that the design reconciliation has been completed for as-built ASME Code Class 1, 2 and 3 components, and document the results of the reconciliation analysis.



# Table 2.8.6-3—Main Feedwater System ITAAC Sheet 3 of 6

	Commitment Wording	Inspections, Tests, Analyses	Acceptance Criteria
3.7	Pressure-boundary welds in ASME Code Class 1, 2 and 3 components meet ASME Code Section III non-destructive examination requirements.	An inspection of the as-built pressure-boundary welds in ASME Code Class 1, 2 and 3 components will be performed.	ASME Code reports(s) exist that conclude that ASME Code Section III requirements are met for non-destructive examination of pressure-boundary welds in ASME Code Class 1, 2 and 3 components.
3.8	ASME Code Class 1, 2 and 3 components retain their pressure-boundary integrity at their design pressure.	A hydrostatic test will be conducted on ASME Code Class 1, 2 and 3 components that are required to be hydrostatically tested by the ASME Code Section III.	ASME Code Data Report(s) exist and conclude that the results of the hydrostatic test of ASME Code Class 1, 2 and 3 components comply with the requirements of ASME Code Section III.
3.9	ASME Code Class 1, 2 and 3 components are fabricated, installed, and inspected in accordance with ASME Code Section III requirements.	An inspection of the as-built construction activities and documentation for ASME Code Class 1, 2 and 3 components will be conducted.	ASME Code Data Report(s) exist that conclude that ASME Code Class 1, 2 and 3 components are fabricated, installed, and inspected in accordance with ASME Code Section III requirements.
3.10	Deleted.	Deleted.	Deleted.
3.11	Deleted.	Deleted.	Deleted.
3.12	Deleted.	Deleted.	Deleted.
3.13	Deleted.	Deleted.	Deleted.
3.14	Deleted.	Deleted.	Deleted.



Table 2.8.6-3—Main Feedwater System ITAAC Sheet 4 of 6

		Inspections, Tests,	
	Commitment Wording	Analyses	Acceptance Criteria
4.1	Displays listed in Table 2.8.6-2 are indicated on the PICS operator workstations in the MCR and the RSS.	a. Tests will be performed to verify that the displays listed in Table 2.8.6-2 are indicated on the PICS operator workstations in the MCR by using test input signals to PICS.	a. Displays listed in Table 2.8.6-2 are indicated on the PICS operator workstations in the MCR.
		b. Tests will be performed to verify that the displays listed in Table 2.8.6-2 are indicated on the PICS operator workstations in the RSS by using test input signals inputs to PICS.	b. Displays listed in Table 2.8.6-2 are indicated on the PICS operator workstations in the RSS.
4.2	Controls on the PICS operator workstations in the MCR perform the function listed in Table 2.8.6-2.	Tests will be performed using controls on the PICS operator workstations in the MCR.	Controls on the PICS operator workstations in the MCR perform the function listed in Table 2.8.6-2.
4.3	Equipment listed as being controlled by a PACS module in Table 2.8.6-2 responds to the state requested and provides drive monitoring signals back to the PACS module. The PACS module will protect the equipment by terminating the output command upon the equipment reaching the requested state.	A test will be performed using test input signals to verify equipment controlled by a PACS module responds to the state requested and provides drive monitoring signals back to the PACS module.	Equipment listed as being controlled by a PACS module in Table 2.8.6-2 responds to the state requested and provides drive monitoring signals back to the PACS module. The PACS module will protect the equipment by terminating the output command upon the equipment reaching the requested state.



# Table 2.8.6-3—Main Feedwater System ITAAC Sheet 5 of 6

	Commitment Wording	Inspections, Tests, Analyses	Acceptance Criteria
5.1	Equipment designated as Class 1E in Table 2.8.6-2 are powered from the Class 1E division as listed in Table 2.8.6-2 in a normal or alternate feed condition.	a. Testing will be performed by providing a test input signal in each normally aligned division.	a. The test input signal provided in the normally aligned division is present at the respective Class 1E equipment identified in Table 2.8.6-2.
		b. Testing will be performed by providing a test input signal in each division with the alternate feed aligned to the divisional pair.	b. The test input signal provided in each division with the alternate feed aligned to the divisional pair is present at the respective Class 1E equipment identified in Table 2.8.6-2.
5.2	The MFWFLIVs fail closed on loss of hydraulic pressure in each redundant dump line.	Tests will be performed to verify that the MFWFLIVs fail closed on loss of hydraulic pressure in each redundant dump line.	Following loss of hydraulic pressure in each redundant dump line, the MFWFLIVs fail closed.
5.3	Deleted.	Deleted.	Deleted.



Table 2.8.6-3—Main Feedwater System ITAAC Sheet 6 of 6

	Commitment Wording		Inspections, Tests, Analyses		Acceptance Criteria
6.1	Equipment designated as harsh environment in Table 2.8.6-2 will perform the function listed in Table 2.8.6-1 under normal environmental conditions, containment test conditions, anticipated operational occurrences, and accident and post-accident environmental conditions.	a.	Type tests or type tests and analysis will be performed to demonstrate the ability of the equipment designated as harsh environment in Table 2.8.6-2 to perform the function listed in Table 2.8.6-1 under normal environmental conditions, containment test conditions, anticipated operational occurrences, and accident and post-accident environmental conditions.	a.	EQDPs conclude that the equipment designated as harsh environment in Table 2.8.6-2 can perform the function listed in Table 2.8.6-1 under normal environmental conditions, containment test conditions, anticipated operational occurrences, and accident and post-accident environmental conditions, including the time required to perform the listed function.
		b.	An inspection will be performed of the as-built equipment designated as harsh environment in Table 2.8.6-2 to verify that the equipment, including anchorage, are installed per the approved design requirements.	b.	Inspection reports conclude that the equipment designated as harsh environment in Table 2.8.6-2, including anchorage, are installed per the approved design requirements.
7.1	Class 1E valves listed in Table 2.8.6-2 will function to change position as listed in Table 2.8.6-1 under normal operating conditions.	ver valv	ts will be performed to ify the ability of Class 1E wes to change position ler normal operating aditions.	2.8 list	uss 1E valves listed in Table .6-2 change position as ed in Table 2.8.6-1 under rmal operating conditions.