

## Section 2: Probability Theory

- *Purpose*
  - *Students will review fundamentals of probability*
  - *Become familiar with several probability distributions that are commonly encountered in PRA*
- *Objectives*
  - *Students will be able to calculate simple probabilities involving*
    - *“AND”, “OR”, “NOT” operations*
    - *Conditional probabilities, independent events*
    - *Bayes’ theorem*
    - *Poisson, binomial, and exponential distributions*
  - *Students will understand the terms mean, variance, percentile, and be able to relate these to particular distributions used in the course*

# ***Probability Theory***

- *Topics to be covered include*
  - *Basic (Frequentist) Framework*
  - *Rules for Manipulating Probabilities*
  - *Discrete Probability Distributions*
  - *Continuous Probability Distributions*
  - *Moments, Percentiles*
  - *Relations among Distributions*

## Basic (Frequentist) Framework

- *A repeatable experiment can result in a number of outcomes. Experiment may be “trial”, “test”, “demand”, etc.*
- *Sample space **S** is the set of all possible outcomes on any one experiment*
- ***Probability** of any outcome is long-term fraction of times when the outcome occurs*
  - *Probability is “reached” after infinite series of these outcomes*
  - *Identical experiment must be repeated over and over*
- *An **event** is a set of outcomes*
  - *Its probability is the sum of the probability of each constituent outcome*

## Example 1

- *Experiment: Try to start EDG-A*
- *The possible outcomes (i.e. the sample space,  $S$ )*
  - *Failure to start ( $FTS_A$ )*
  - *Start but failure to run ( $FTR_A$ )*
  - *Start and run to end of mission ( $Success_A$ )*
- *Some possible events*
  - *EDG-A fails somehow*
  - *EDG-A starts*
  - *Etc.*

## Example 2

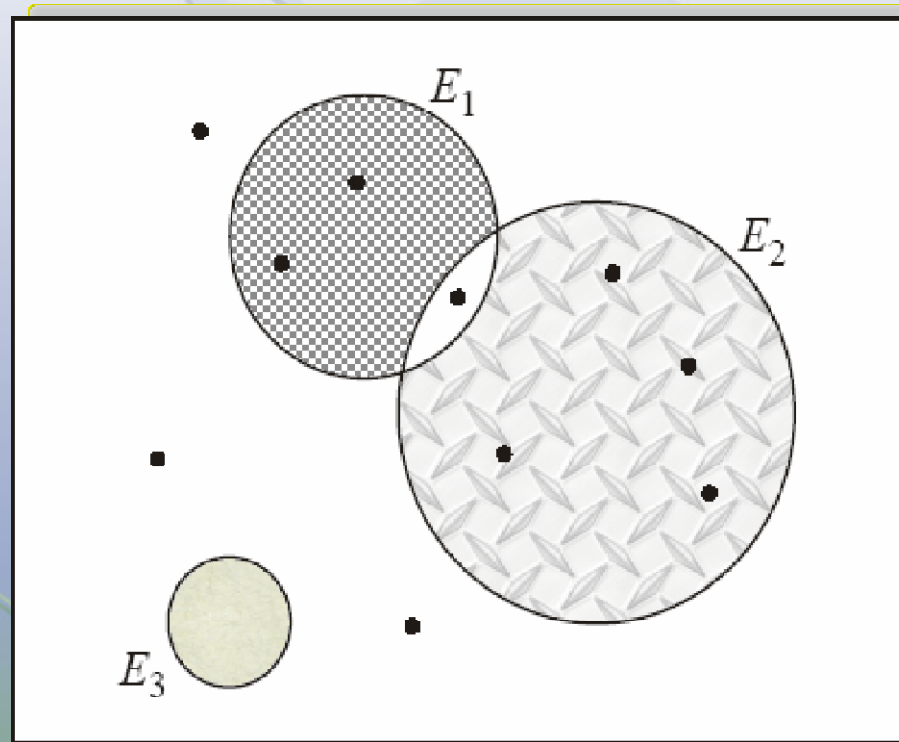
- *Experiment: Try to start two EDGs, EDG-A and EDG-B*
- *The outcomes (i.e. the sample space):*

$FTS_A \& FTS_B$	$FTS_A \& FTR_B$	$FTS_A \& Success_B$
$FTR_A \& FTS_B$	$FTR_A \& FTR_B$	$FTR_A \& Success_B$
$Success_A \& FTS_B$	$Success_A \& FTR_B$	$Success_A \& Success_B$

- *Some possible events*
  - *At least one EDG succeeds*
  - *Both EDGs fail somehow*
  - *At least one EDG fails to start*
  - *Exactly one EDG fails*
  - *Etc.*

## Example 3

- It is sometimes helpful to show **events** and **outcomes** via a Venn diagram
  - Three events, 10 outcomes



## ***Building Events from Other Events or Outcomes — OR***

- *A OR B = event containing all outcomes that are in A or in B*
  - *Also written  $A \cup B$ , the **union** of A and B*
  - *The union symbol,  $\cup$ , is easy to remember since symbol looks like the letter “U”*
- *In a PRA, minimal cut sets are “ORed” together to obtain overall results of the analysis*

## ***Building Events from Other Events or Outcomes — AND***

- *A AND B = event containing all outcomes that are both in A and in B*
  - *Also call the **intersection** of A and B, written  $A \cap B$*
  - *The intersection symbol  $\cap$  can be remembered as the opposite of the union symbol*
- *In a PRA, the events within a **single** minimal cut set are “ANDed” together to obtain the cut set value*
- *A and B are **disjoint** or **mutually exclusive** if they have no outcomes in common, i.e. A AND B is empty*



## ***Building Events from Other Events or Outcomes — NOT***

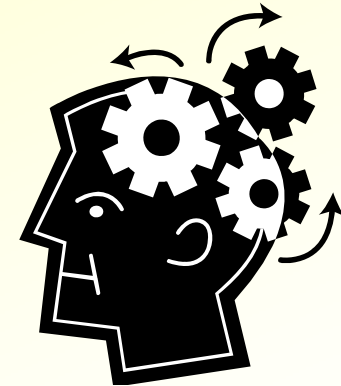
- The **complement** of  $A$ , or **NOT**  $A$ , is the event containing all the outcomes that are not in  $A$ .
- Sometimes written  $\bar{A}$  or  $/A$

## ***Basic (Frequentist) Framework (cont.)***

- *Within the Frequentist approach to statistics, there are two divisions of thought*
  - *Relative frequency*
    - *Repeated (unchanging) experiment yields measurable outcomes*
    - *Event probability achieved in limit of many trials*
      - *Example, toss die 100,000 times*
      - *17,003 times “1” seen... $Pr(1) \cong 0.170$*
  - *Classical (Bernoulli) approach*
    - *Equal probable outcomes*
    - *Event probability available directly by ratio of outcomes of interest versus all possible outcomes*
      - *Example,  $Pr(1 \mid \text{roll of die}) = 1 / 6 = 0.1666\dots$*

# ***Tips for Solving Probability Problems***

- *Write what you have*
  - *Can you list the outcomes?*
  - *What events are relevant?*
  - *What is “fixed” and what is “random”?*
  - *What is the problem asking for?*
  - *What formulas relate to this question?*
- *Do not try to do everything in your head.*
  - *Use pencil and paper, and proceed step by step through the problem*



# Elementary “Rules” of Probability

- *Each event has an associated probability*
- *Probability, or  $p$ , is a real value*
  - *Possible values are bounded by (and include) 0.0 and 1.0*
  - *Probability of union of non-overlapping (disjoint) events is the sum of the event probabilities*
  - *Probability of all possible outcomes (i.e., the sample space) equal to 1.0*

# Rules for Manipulating Probabilities

- The **NOT** (or complement) operation
  - Subtract probability from 1.0
  - Example,  $Pr(\text{not } A) = 1 - Pr(A)$
- Another probability problem tip
  - With messy problems using terms such as “at least” or “at most,” try to calculate complement of the probability first
    - $Pr(A) = 1 - Pr(\text{not } A)$



## ***Rules for Manipulating Probabilities (cont.)***

- The **OR** (or union) operation
  - If  $A, B$  are **disjoint**
    - $Pr(A \text{ or } B) = Pr(A) + Pr(B)$
  - If  $A, B$  are not disjoint
    - $Pr(A \text{ or } B) = Pr(A) + Pr(B) - Pr(A \text{ AND } B)$

## ***Rules for Manipulating Probabilities (cont.)***

- The **AND** (or intersection) operation
  - If  $A, B$  are **independent**
    - $Pr(A \text{ AND } B) = Pr(A) \cdot Pr(B)$
  - If  $A, B$  are not independent (i.e., dependent, or **conditional**)
    - $Pr(A \text{ AND } B) = Pr(A) \cdot Pr(B | A)$   
 $= Pr(B) \cdot Pr(A | B)$

## ***Rules for Manipulating Probabilities (cont.)***

- ***Conditional probability definition***
  - *We said that in general*
    - $Pr(A \text{ AND } B) = Pr(A) \cdot Pr(B | A)$
  - *The conditional probability is last term  $Pr(B | A)$ , so*
    - $Pr(B | A) = Pr(A \text{ AND } B) / P(A)$
    - $Pr(A | B) = Pr(A \text{ AND } B) / P(B)$
  - *These last equations define “conditional probability”.*
- *We will see that this product rule of conditional probabilities leads us to “Bayes’ Theorem”*



# ***Do Not Confuse Independent and Disjoint***

- *If A, B are mutually exclusive (i.e., disjoint), then*
  - $Pr(A \text{ AND } B) = 0$
- *If  $Pr(A \text{ AND } B) = 0$  but  $Pr(A) \cdot Pr(B) \neq 0$* 
  - *Thus, A and B are **not** independent*
  - *Instead, they simply are disjoint*
    - *On a Venn diagram, they do not overlap*

# Bayes' Theorem

- A set of events  $\{C_i\}$  is a **partition** of the sample space
  - If  $C_i$ s are mutually exclusive
    - Each pair is mutually exclusive...no overlap
  - And if union of  $C_i$ s is the entire sample space
- Bayes' Theorem: If  $\{C_i\}$  is a partition of the sample space,

$$\Pr(C_i | E) = \frac{\Pr(E | C_i) \Pr(C_i)}{\sum \Pr(E | C_j) \Pr(C_j)}$$

- Bottom term is  $\Pr(E)$  (where  $E$  is the “evidence”)  
 $\Pr(E) = \sum \Pr(E | C_j) \Pr(C_j)$   
is called “Law of Total Probability”



# Bayes' Theorem

- *If we are calculating probability of event C where evidence E is available*
  - $Pr(C | E) = Pr(C) Pr(E | C) / Pr(E)$
- *Terms in equation above have specified names*
  - $Pr(C | E)$     *Posterior probability*
  - $Pr(C)$         *Prior probability*
  - $Pr(E | C)$     *Likelihood*
  - $Pr(E)$         *Unconditional probability of evidence*

## Bayes Example

- *Tests for integrity are carried out on manufactured radiation sources*
  - *Manufacturer A results: 10% cracked, over long run*
  - *Manufacturer B results: 5% cracked, over long run*
- *Hospital gets 60% of its sources from manufacturer B*
- *Incident report is later sent to the NRC stating leak from a source at a hospital due to cracked source*
  - *What is the probability that the hospital used manufacturer B?*
  - $$P(\text{Manufacturer B}|\text{crack}) = \frac{(0.6)(0.05)}{[(0.4)(0.10) + (0.6)(0.05)]}$$
$$= 0.20$$

## Second Bayes' Theorem Example

- Look at an example...the infamous “game show” problem
- **One** of three doors contains a prize. You select door #1.
  - The host opens door #2 (which contains nothing) and asks you if you would like to **switch** to door #3
  - What does Bayes' Theorem say?
    - “ $C_1$ ” in this case is the event our door, #1, hides the prize
    - The evidence,  $E$ , is knowledge that door #2 does not have prize
- Let us first see what information we have
  - $Pr(C_1) = Pr(C_2) = Pr(C_3)$  = prior probability door holds the prize independent of any new information =  $1/3$
  - $Pr(E \mid C_1)$  = conditional probability that door #2 would have been opened by host =  $1/2$
  - $Pr(E \mid C_2) = 0$ , and  $Pr(E \mid C_3) = 1$  — The host knows where the prize is, and will never open that door!

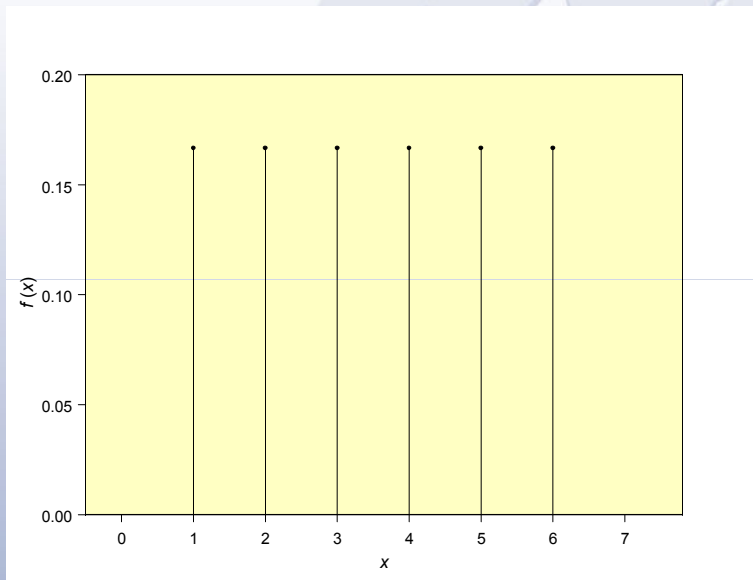
## Second Bayes' Theorem Example (cont.)

- $Pr(C_1 | E)$  = probability that our door has the prize, given door #2 was opened
$$= Pr(C_1) Pr(E | C_1) / Pr(E) \quad \textbf{Bayes!}$$
- We know  $Pr(C_1)$  and  $Pr(E | C_1)$ , but what is  $Pr(E)$ ?
  - Use Law of Total Probability
- $Pr(E) = Pr(\text{\#1 has prize}) Pr(\text{\#2 opened} | \text{\#1 has prize}) + Pr(\text{\#2 has prize}) Pr(\text{\#2 opened} | \text{\#2 has prize}) + Pr(\text{\#3 has prize}) Pr(\text{\#2 opened} | \text{\#3 has prize})$ 
$$= (1/3)(1/2) + (1/3)(0) + (1/3)(1) = 1/2$$
- We now have all the parts, doing the math indicates
  - $Pr(C_1 | E) = (1/3)(1/2)/(1/2) = 1/3$
  - $Pr(C_3 | E) = (1/3)(1)/(1/2) = 2/3$

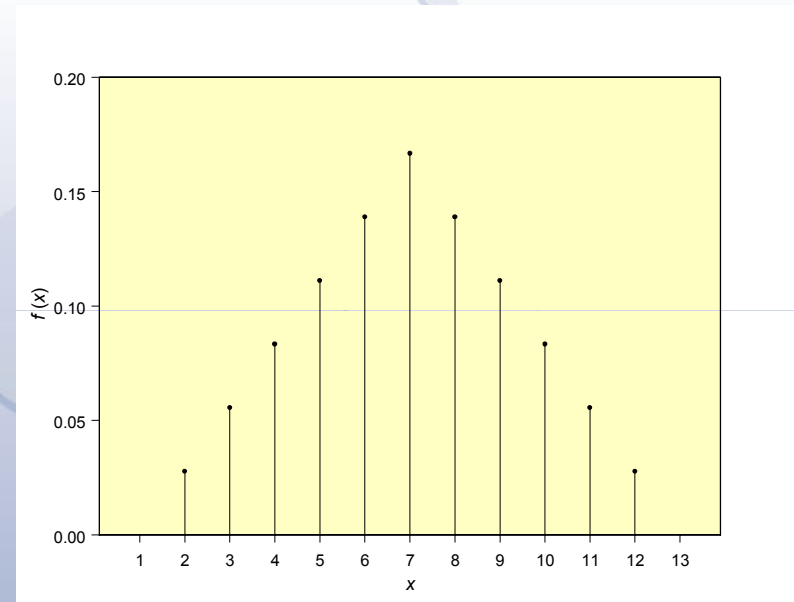
# Discrete Probability Distributions

- Outcomes can be summarized by a **random** variable  $X$ , which takes possible values  $x$
- Probabilities are based on  $X$ 's probability distribution function (pdf)
  - $f(x) = \Pr(X = x)$
- Facts about a pdf
  - $f(x_i) \geq 0$
  - $\text{SUM}[f(x_i)]_{\text{all } i} = \sum f(x_i) = 1$

# Examples: Number of Spots on Dice



*Spots on One Die*



*Total Spots on Two Dice*



# Random?

- *Wolfram's thought of randomness in "New Kind of Science"*
  - *Try standard simple programs to detect regularities/patterns*
  - *If none detected, likely no other tests will show nonrandom behavior*
  - *He does not consider something to be truly random if generated from simple rules*
- *In other words*
  - *"... one considers a sequence 'random' if no patterns can be recognized in it, no predictions can be made about it, and no simple description of it can be found."*

# Random?

- Consulting a dictionary...  
*“lacking any definite plan or order or purpose; governed by or depending on chance”*
- Jaynes’ thought is that there is no such thing as “random,” including no such thing as random variables
  - We only have variables whose values may not be known with certainty

# ***Two Most Popular Discrete Distributions***

- *Poisson*
- *Binomial*

# Poisson Distribution

- *Most commonly used model for initiating events.*
- *Assumptions on the physical process*
  1. *Probability of event in short time period  $\Delta t$  is approximately  $\lambda \times \Delta t$ , for some constant  $\lambda$*
  2. *Simultaneous events do not occur*
  3. *Occurrences of events in disjoint time periods are independent*
- *Assumption on the data*
  4. *We observe a random number of events  $X$  in a fixed time period  $t$*



## Poisson Distribution (cont.)

- Then  $X$  has a **Poisson**( $\lambda t$ ) distribution:

$$\Pr(X = x) = e^{-\lambda t} (\lambda t)^x / x! , \text{ for } x = 0, 1, 2, \dots$$

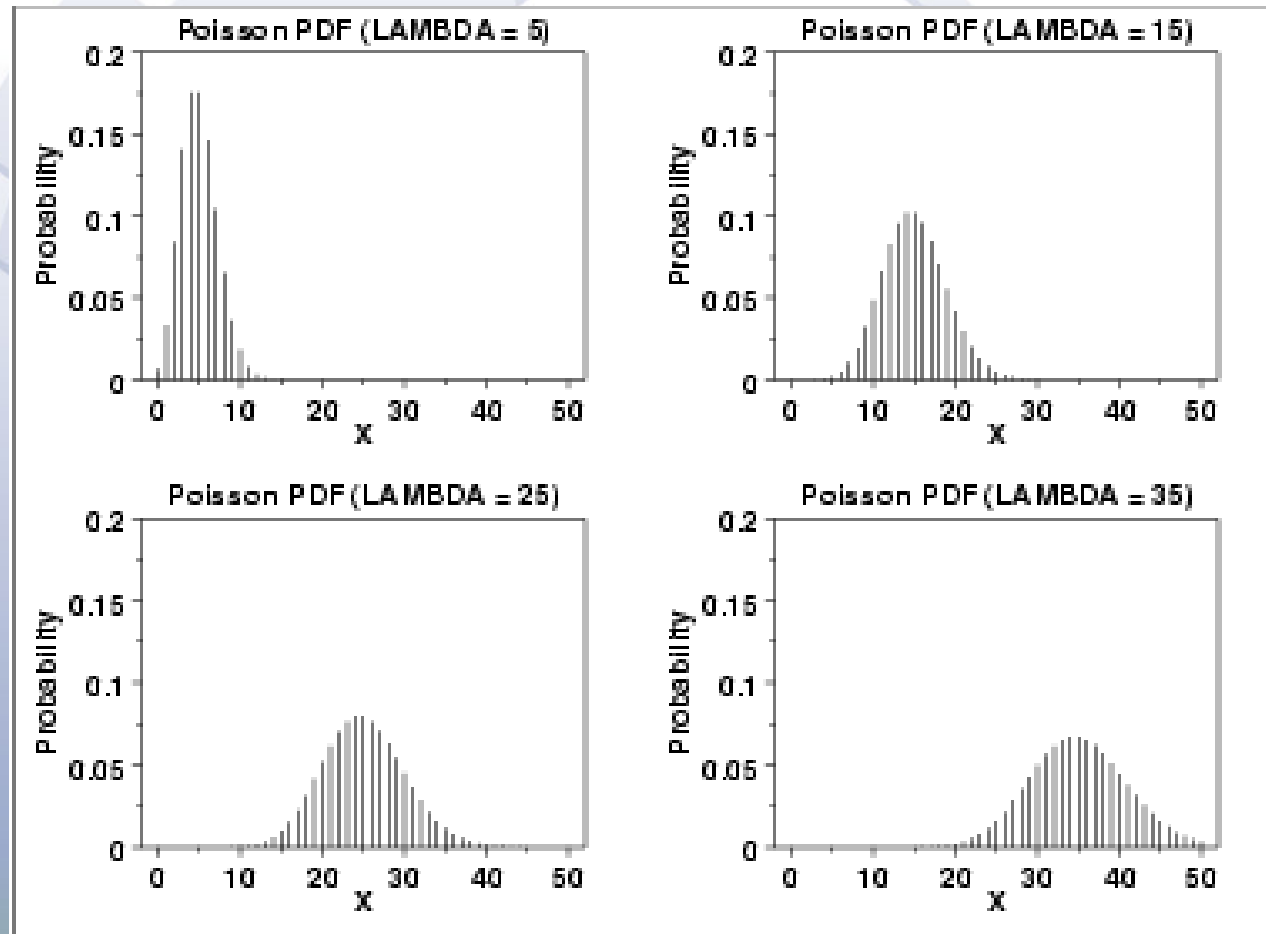
( $x$  = number failures)

(for pictures, HOPE page A-14)

- The distribution depends on one quantity,  $\lambda t$ 
  - Therefore, product  $\lambda t$  is sometimes written as  $\mu$ , and the distribution is called *Poisson*( $\mu$ )
- Moments
  - Mean =  $\lambda t$
  - Variance =  $\lambda t$

## Poisson Distribution (cont.)

- *L' image*



<http://www.itl.nist.gov/div898/handbook/eda/section3/eda366.htm>

# ***Binomial Distribution***

- *One commonly used model for failure to start.*
- *Assumptions on the physical process*
  1. *On each demand, outcome is a failure with probability  $p$  (success with probability  $1 - p$ )*
    - *This  $p$  is the same for all demands*
  2. *Occurrences of failures on different demands are independent*
- *Assumption on the data*
  3. *We observe a random number of failures  $X$  in a fixed number of demands  $n$*

## ***Binomial Distribution (cont.)***

- Then  $X$  has a **binomial**( $n, p$ ) distribution:

$$\Pr(X = x) = \binom{n}{x} p^x (1-p)^{n-x}, \text{ for } x = 0, 1, \dots, n$$

*( $x$  = number failures)*

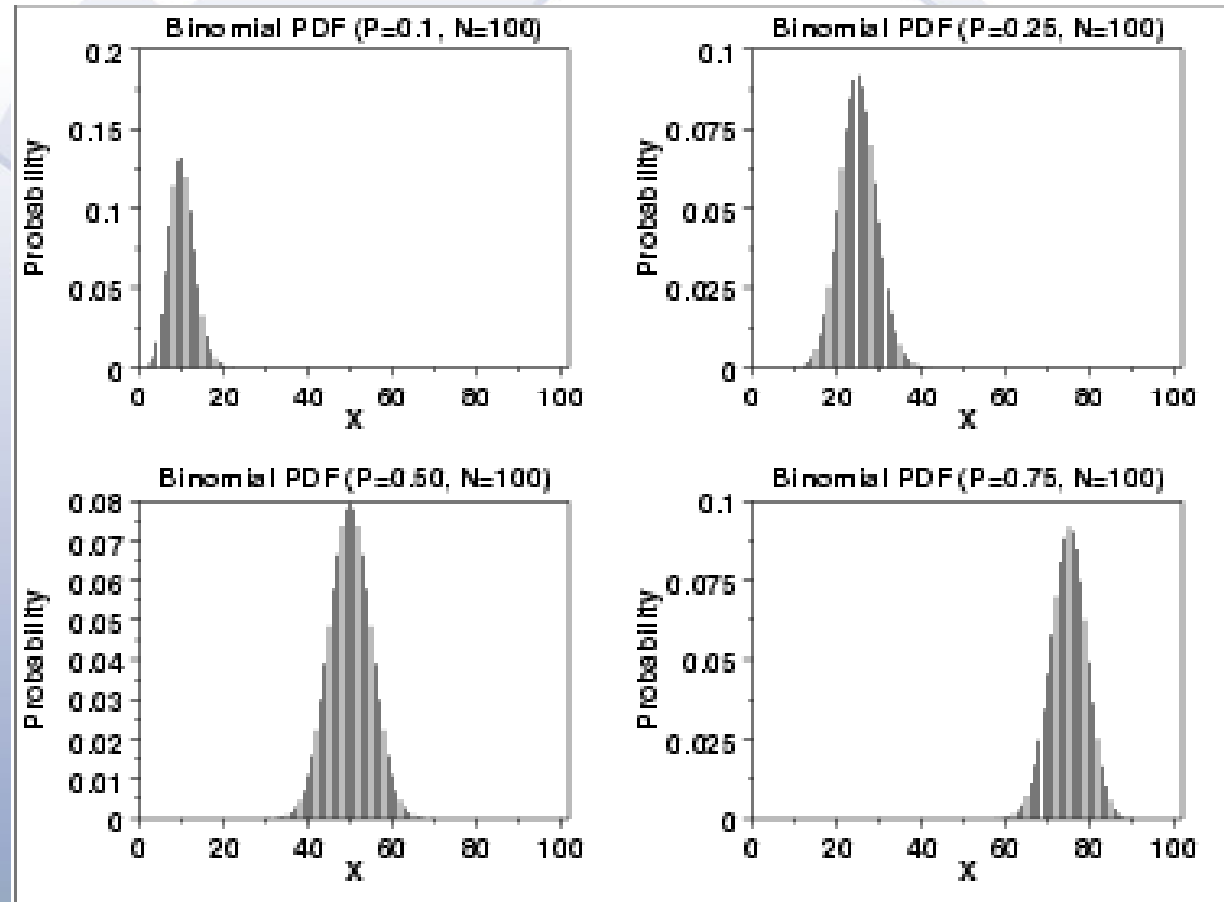
*(for pictures, HOPE page A-13)*

- **Moments**
  - Mean =  $n p$
  - Variance =  $n p (1 - p)$



## ***Binomial Distribution (cont.)***

- *L' image*



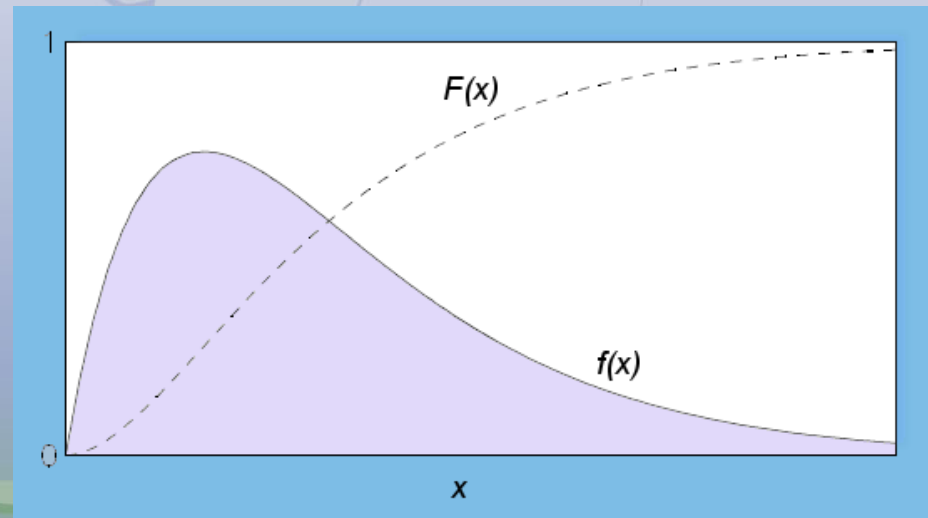
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# Continuous Probability Distributions

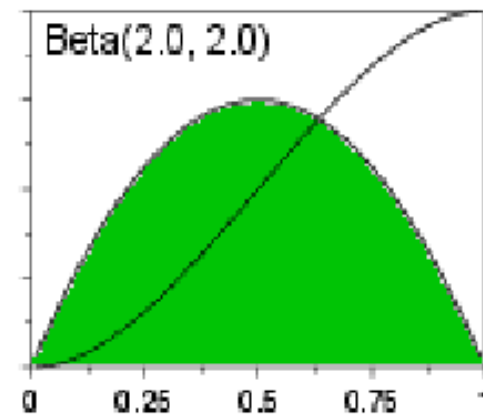
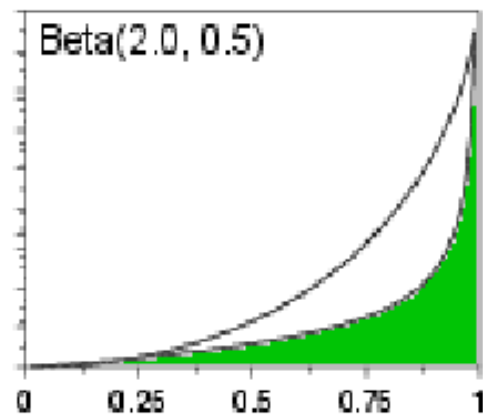
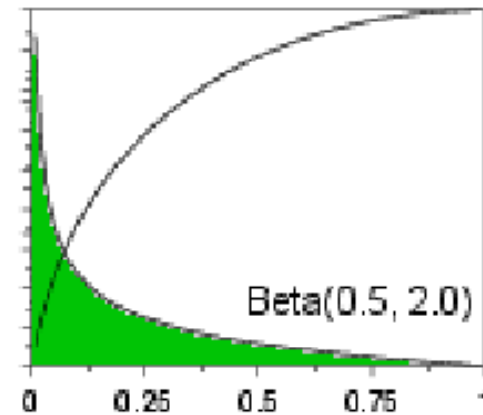
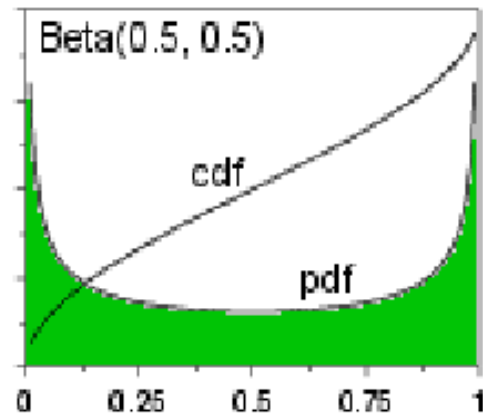
- Random variable  $X$  takes values in a continuous range, such as from 0 to  $\infty$
- In principle,  $Pr(a \leq X \leq b) = \int_a^b f(x)dx$  ,
  - where  $f(x)$  is the probability density function.
- In practice,  $Pr(a \leq X \leq b) = F(b) - F(a)$ 
  - where  $F$  is the cumulative distribution function (cdf)

## Continuous Probability Distributions (cont)

- *Relations*
  - $F(x) \equiv \Pr( X \leq x ) = \int_{-\infty}^x f(x') dx'$
  - $f(x) = dF(x)/dx$
- *Note,  $\Pr(X = x) = 0$  for any number  $x$* 
  - *But probability that  $X$  is in an interval is typically nonzero*



# Continuous Probability Distributions (cont)



# Exponential Distribution

- *A commonly used distribution for a duration*
- *Very simple (sometimes too simple)*
- *Setting: Watch something until an event of interest occurs*
  - *Failure to run*
  - *Restoration of power*
  - *Suppression of fire, etc.*
- *Let  $T$  be time when event occurs*



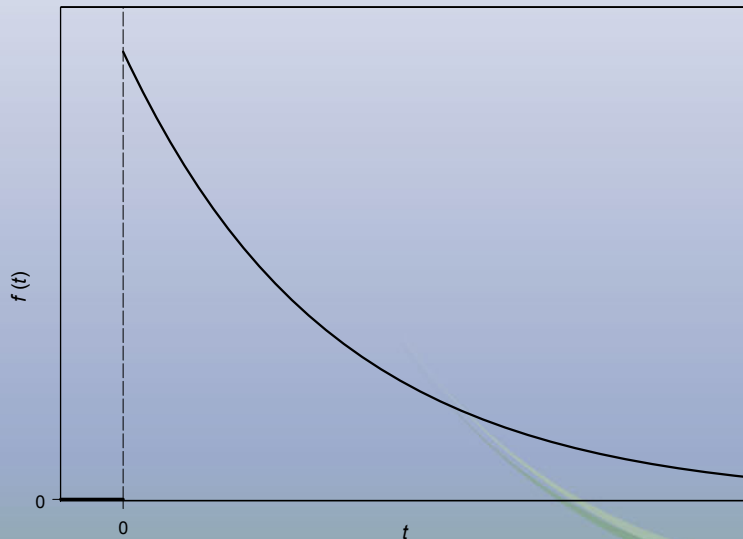
## ***Exponential Distribution (cont.)***

- *Assumption on the physical process*
  1. *For  $t \geq 0$  and small  $\Delta t$* 
$$\Pr(T \leq t + \Delta t \mid T > t) \approx \lambda \times \Delta t \quad (\text{for a constant } \lambda)$$
- *Interpretation*
  - *If the system is running at time  $t$ , probability that system will fail in next small time interval  $\Delta t$  is  $\lambda \times \Delta t$ , regardless of what  $t$  is.*
  - *That is, the system does not improve or age as a function of time*
- *Assumption on the data*
  2. *We observe the event time,  $T$*

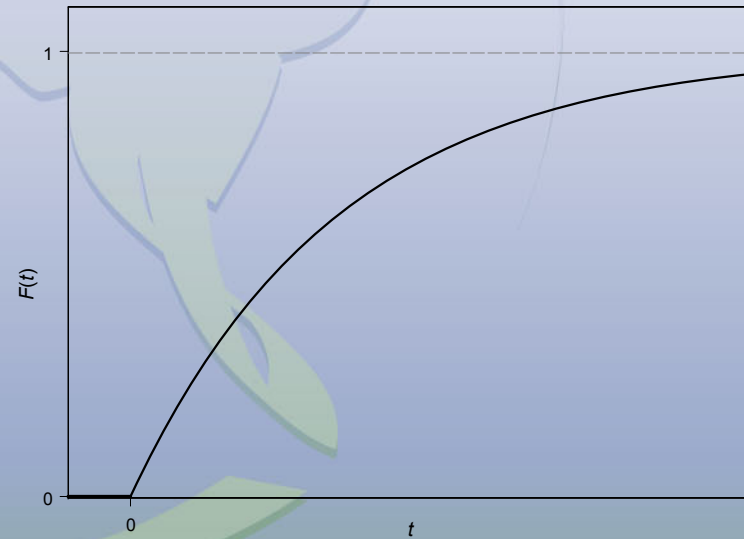
## Exponential Distribution (cont.)

- Under the above assumption
  - $T$  has an **exponential**( $\lambda$ ) distribution

$$f(t) = \lambda e^{-\lambda t} \quad \text{for } t \geq 0$$



$$F(t) = 1 - e^{-\lambda t} \quad \text{for } t \geq 0$$



## ***Exponential Distribution (cont.)***

- ***Units***
  - “ $\lambda t$ ” is unitless
  - $\lambda$  has units of  $1/t$  (in PRA, usually per hour)
    - Some initiating events are per year
- ***Alternative parameterization in terms of  $\mu = 1/\lambda$ .***
  - Just rewrite formulas in obvious way
  - Units of  $\mu$  are units of  $t$ 
    - Also known as “mean time to failure”

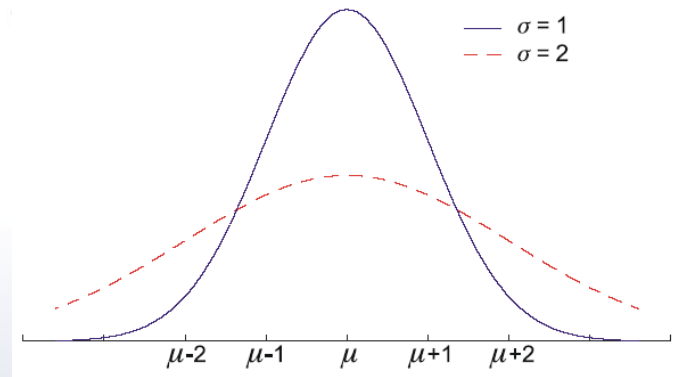


# Normal Distribution

- *Arises in many settings*
  - *Primary application in this course is as a means to the lognormal distribution*
  - *Density equation in HOPE, page A-15*
- *If  $X$  has a **normal**( $\mu$ ,  $\sigma^2$ ) distribution, then*

$$\Pr(X \leq x) = \Pr\left(\frac{X - \mu}{\sigma} \leq \frac{x - \mu}{\sigma}\right) = \Phi\left(\frac{x - \mu}{\sigma}\right)$$

$\Phi$  is tabulated in many books, for example HOPE Table C-1



# Moments and Percentiles

- The **mean**, or **expected value**, or **expectation**, of  $X$  is weighted average of the values of  $X$

- $E(X) = \sum_x x \Pr(X = x) = \sum_x xf(x)$  if  $X$  discrete

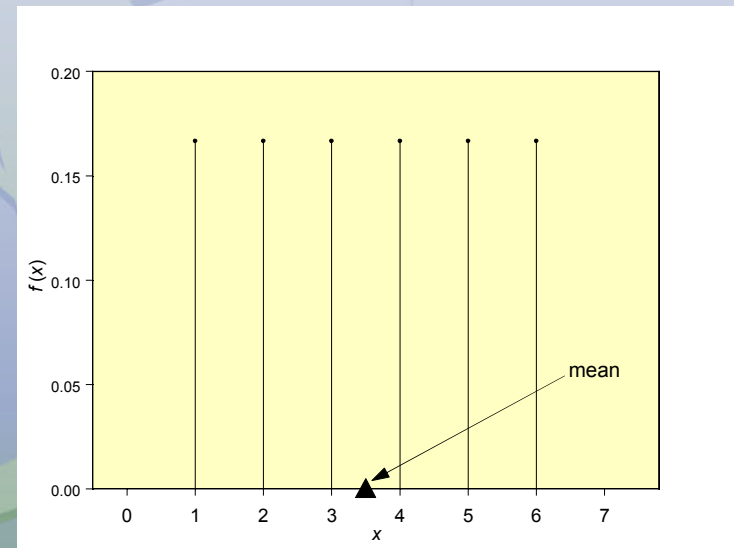
- $E(X) = \int_{-\infty}^{\infty} xf(x)dx$  if  $X$  continuous

## ***Moments and Percentiles (cont.)***

- The **variance** is the analogous weighted average of  $[X - E(X)]^2$ :
  - $\text{var}(X) = \sum_x [x - E(X)]^2 f(x)$  if  $X$  discrete
  - $\text{var}(X) = \int_{-\infty}^{\infty} [x - E(X)]^2 f(x) dx$  if  $X$  continuous
- The **standard deviation** is the square root of the variance

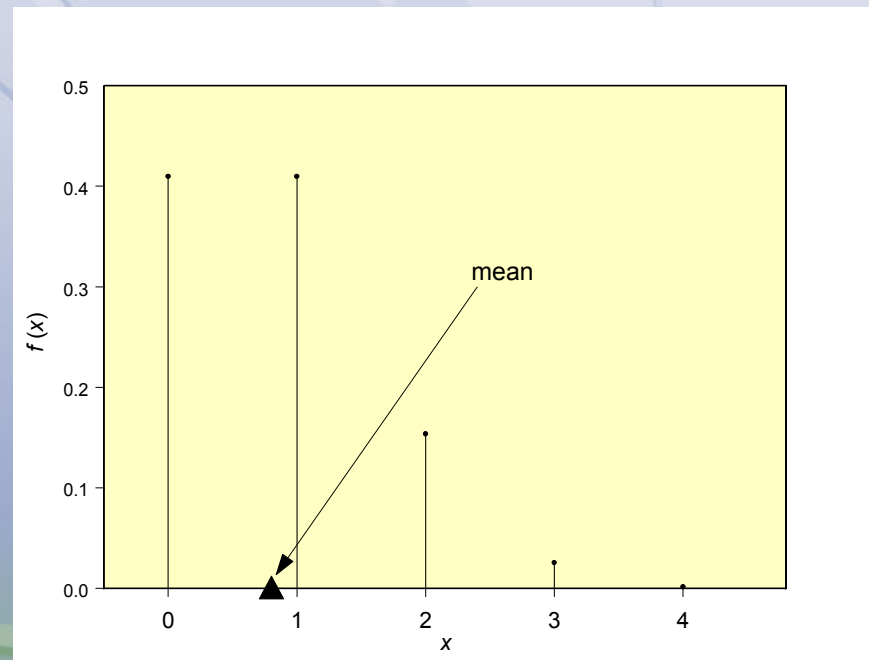
# Mean Example

- We have the discrete distribution for a single die
  - What is the expected value?
  - $Pr(X = x) = 1/6$
  - $E[X] = 1(1/6) + 2(1/6) + 3(1/6) + 4(1/6) + 5(1/6) + 6(1/6)$   
 $= 1/6 + 2/6 + 3/6 + 4/6 + 5/6 + 1 = 3.5$
  - Since discrete, we can not really get an outcome of 3.5.  
It has to be 1, 2, 3, 4, 5, or 6



## Second Mean Example — *Binomial( $n=4$ , $p=0.2$ )*

- Possible values are 0, 1, 2, 3, 4.
- The distribution is skewed, not symmetrical
- Smaller values have higher probability, so mean is weighted toward small side
- Direct calculation shows  
 $\text{mean} = 0.8$

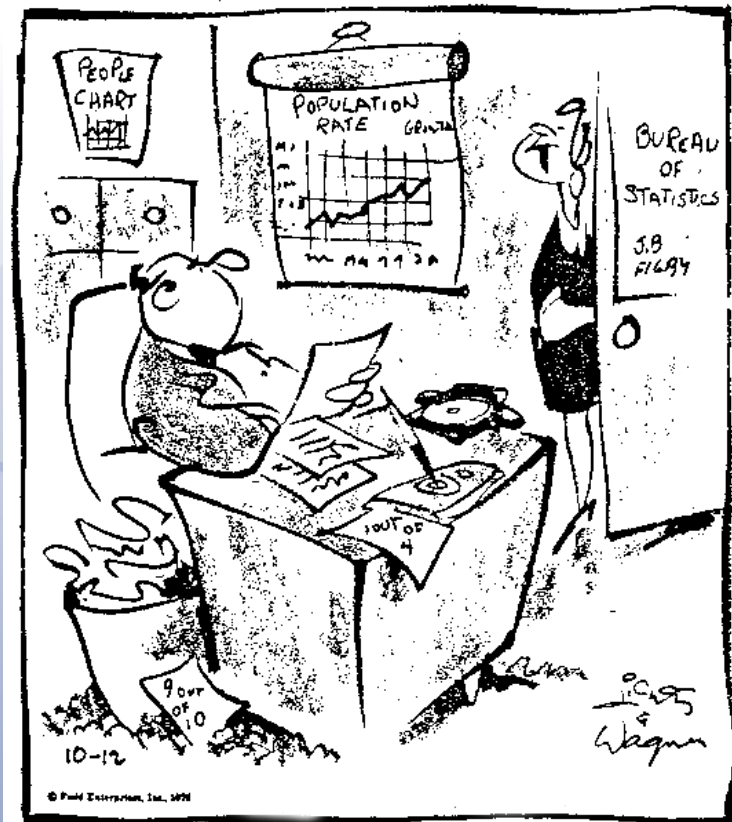


## Moments and Percentiles (cont.)

- The distinction between the mean and the full distribution is the basis of most statistician jokes.

Grin and Bear It

By Lichty



"There are 2 and 3-10ths people to see you, Chief."

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## Moments and Percentiles (cont.)

Frank and Ernest



## ***Moments and Percentiles (cont.)***

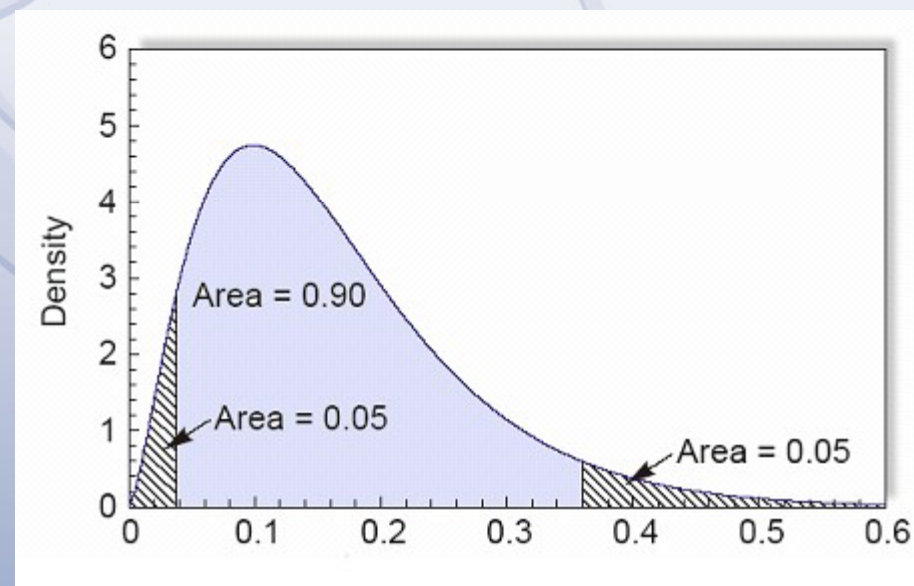
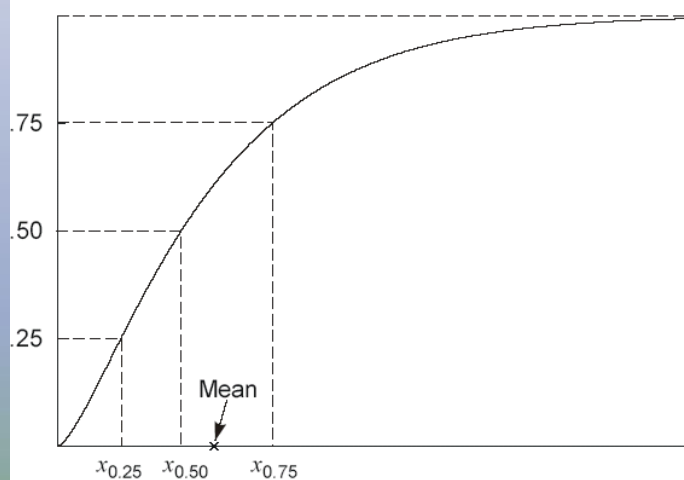
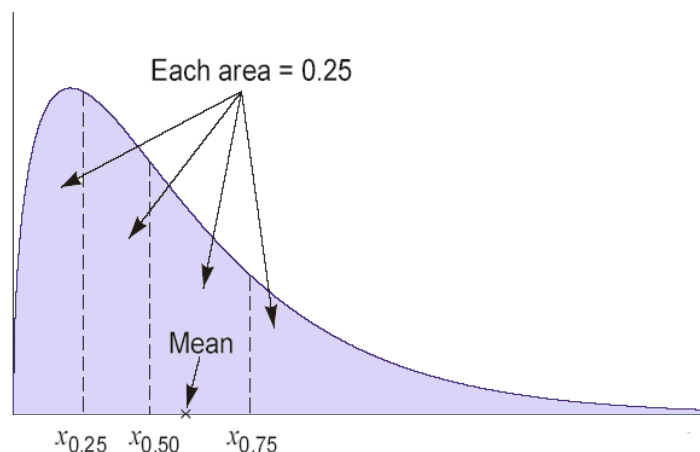
- $X \sim \text{Poisson}(\lambda t)$ 
  - $E(X) = \lambda t$
  - $\text{Var}(X) = \lambda t$
- $X \sim \text{binomial}(n, p)$ 
  - $E(X) = np$
  - $\text{Var}(X) = np(1 - p)$
- $T \sim \text{exponential}(\lambda)$ 
  - $E(T) = 1/\lambda$
  - $\text{Var}(T) = 1/\lambda^2$
- $X \sim \text{normal}(\mu, \sigma^2)$ 
  - $E(X) = \mu$
  - $\text{Var}(X) = \sigma^2$



## *Moments and Percentiles (cont.)*

- *The 95th **percentile**, denoted  $x_{0.95}$ , is the value such that  $F(x_{0.95}) = 0.95$* 
  - *Primarily used for continuous distributions*
- *Similar definition for any number from 0 to 100 percent*
- *Special cases common in PRA include*
  - ***Median** = 50th percentile*
  - *1st and 3rd **quartiles** = 25th and 75th percentiles*
  - ***Upper bound** = 95<sup>th</sup>*
    - *Should properly be called 95% upper bound*
  - ***Lower bound** = 5<sup>th</sup>*
    - *Should properly be called the 5% lower bound*

## Moments and Percentiles (cont.)



## ***Moments and Percentiles (cont.)***

- *Alternative language*
  - *The **q quantile** is the 100q percentile*
- *If a distribution is **positively skewed** (longer tail on the right), then mean is greater than median*
  - *$E[x] > 50\text{th}$*
  - *Also, the mode (highest point on the pdf) is less than the 50th percentile for positively skewed distributions*
    - *$\text{Mode} < \text{Median} < \text{Mean}$*

# Relations among Distributions

- In a **Poisson** process with event frequency  $\lambda$ 
  - Time to first event and between events is **exponential**( $\lambda$ )
    - See HOPE, page A-17
- If  $n$  is large,  $p$  is small, and  $np$  is moderate, then
  - **Binomial**( $n, p$ ) distribution is approximately **Poisson**( $\mu$ )
    - In this case,  $\mu = np$
    - See HOPE, page A-14
- Normal approximations (p. A-16, plus pictures)
  - **Binomial**( $n, p$ ) is approximately **normal** as  $n$  becomes large and  $p$  is fixed
  - **Poisson**( $\mu$ ) is approximately **normal** as  $\mu$  becomes large