

## **Section 5: Uncertainty Analysis in Risk Assessment**

- *Purpose*
  - *Students will see an overview of how Bayesian estimates are obtained in risk assessment*
- *Objectives*
  - *Through examples, students will learn about*
    - *Simulation of distributions with Monte Carlo sampling*
    - *Simulation of a “top event” probability by propagation of distributions through a logic model*
    - *Simple Monte Carlo sampling and Latin Hypercube sampling*

# Risk

- *Three elements must always be considered*
  - *What things could happen?*
  - *What are their probabilities or frequencies?*
  - *What are their consequences?*
- *Must quantify answers, and assess uncertainty in the quantification*
- *In LOSP example*
  - *Events*
    - *Initiating event could occur*
    - *Then EDG power system could successfully operate or it could fail*
  - *Consequences*
    - *Electric power production, or something bad*
  - *Frequency of bad consequence is subject of this section*

# Uncertainty Analysis in Risk Assessment

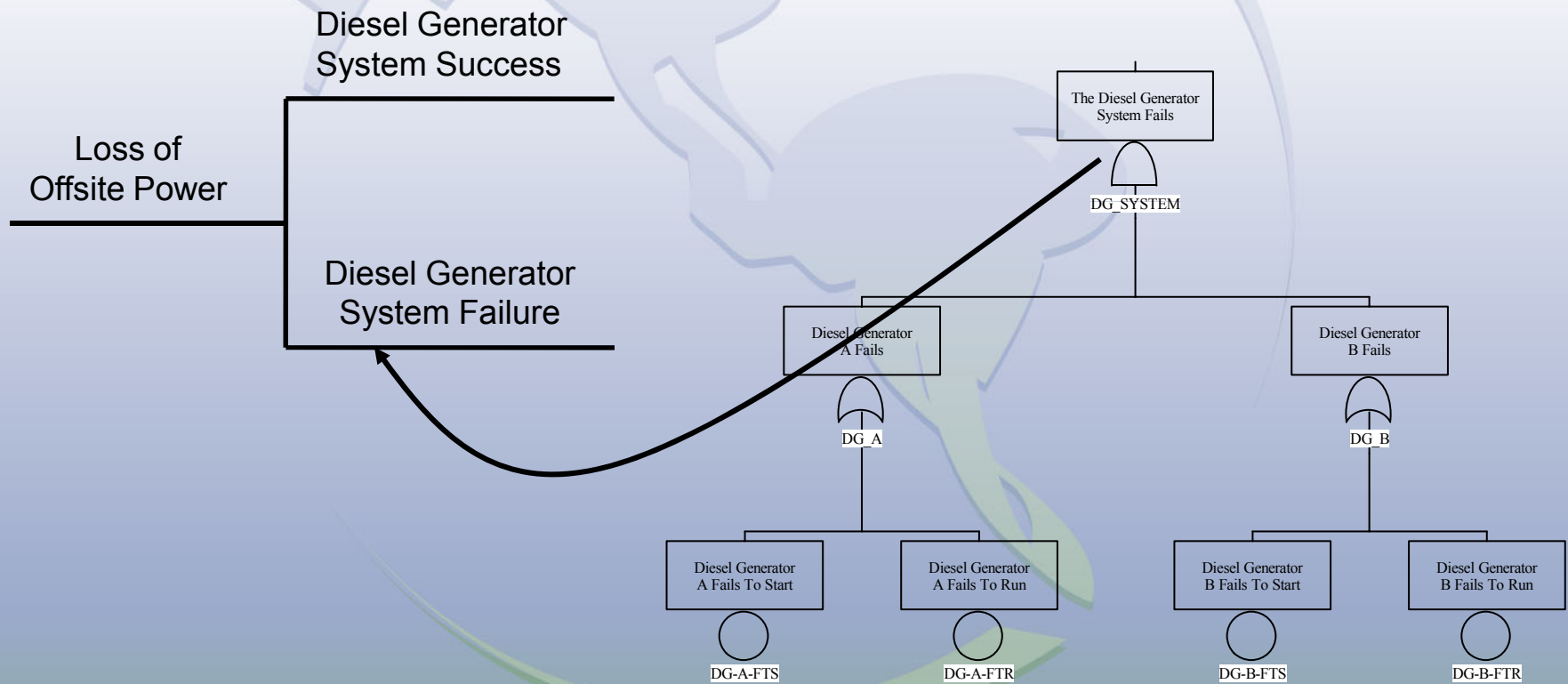
- **Overall Approach**
- *In risk assessment, we estimate*
  - *Probability of “top event” (if looking at fault trees)*
  - *Frequency of “end state” (if looking at event trees)*
- *These estimates are based upon “minimal cut sets”*
  - *Minimal cut sets contain parameters such as*
    - *Failure rates*
    - *Probabilities of failure on demand*
  - *In the LOSP example, we develop  $\lambda_{\text{SystemFail}}$  as a (fairly complicated) function of  $\lambda_{\text{LOSP}}$ ,  $p_{\text{FTS}}$ , and  $\lambda_{\text{FTR}}$*
  - *We approximate the Bayes distribution of the end-state frequency as follows*

## ***Uncertainty Analysis (cont.)***

- *Randomly sample a value of each basic parameter*
  - *This sample comes from its posterior distribution*
- *Samples are used to calculate a desired*
  - *Top-event probability*
  - *End-state frequency*
- *This process is repeated*
  - *Use new sampled values of the basic parameters on each iteration*
  - *Obtain many calculated values of desired result*
  - *Resulting values are a random sample from the Bayesian distribution of the top-event prob. or end-state frequency*
    - *Together, they approximate the result distribution*

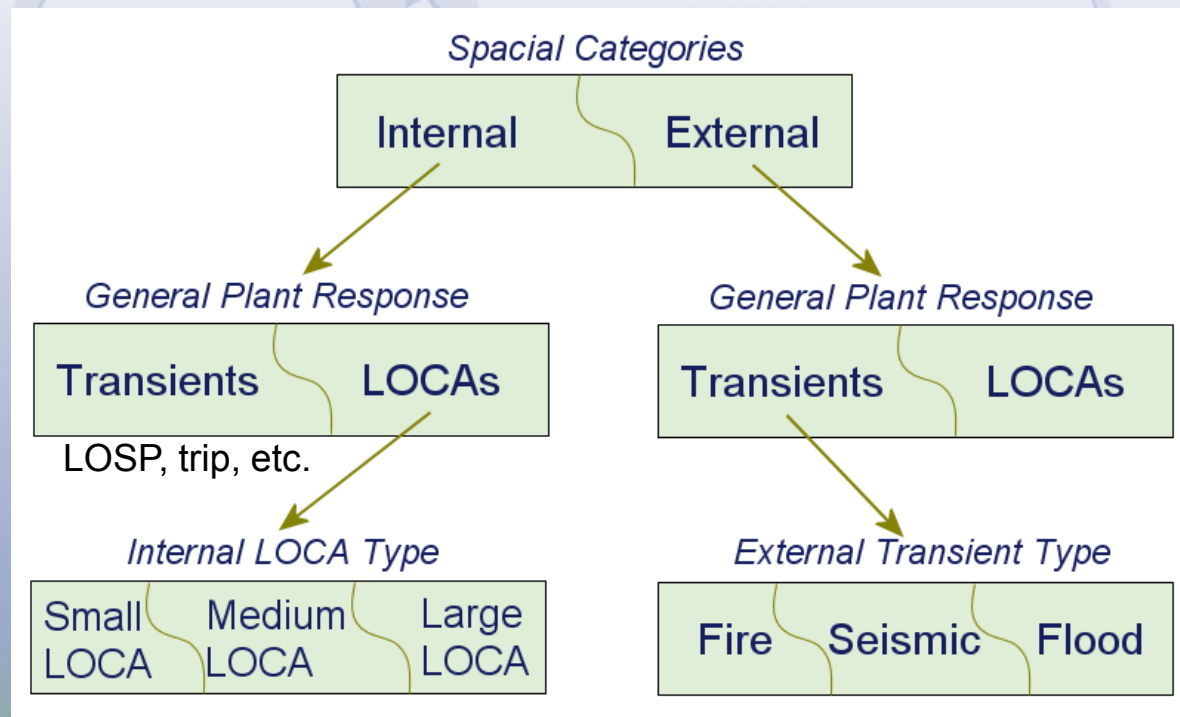
# LOSP Example

- Once again



# LOSP Example (cont.)

- Note that LOSP is just one initiating event...this analysis process is carried out for all results from all initiating events



## ***PRA Minimal Cut Sets***

- *In every minimal cut set there are “basic events”*
- *Every basic event stored in PRA database has some uncertainty about the value used for the event*
  - *The **propagation** of this uncertainty through cut sets must be performed in order to understand the overall uncertainty*

## Minimal Cut Sets in LOSP Example

- $\lambda_{SystemFail} = \lambda_{LOSP} \times Pr[EDG \text{ system fails}]$
- $Pr[EDG \text{ system fails}]$ 
  - =  $Pr[(FTS_A \text{ and } FTS_B) \text{ or } (FTS_A \text{ and } FTR_B)$   
 $\text{or } (FTS_B \text{ and } FTR_A) \text{ or } (FTR_A \text{ and } FTR_B)]$
  - $\approx Pr(FTS_A \text{ and } FTS_B) + Pr(FTS_A \text{ and } FTR_B)$   
 $+ Pr(FTS_B \text{ and } FTR_A) + Pr(FTR_A \text{ and } FTR_B)$
  - (rare event approximation)
  - =  $Pr(FTS_A) \times Pr(FTS_B) + Pr(FTS_A) \times Pr(FTR_B)$   
 $+ Pr(FTS_B) \times Pr(FTR_A) + Pr(FTR_A) \times Pr(FTR_B)$
  - assume EDGs A and B fail independently



## Minimal Cut Sets in LOSP Example (cont.)

- Generic forms for basic event probabilities
  - $Pr(FTS) = p_{FTS}$
  - $Pr(FTR) = 1 - e^{-\lambda_{FTR}t_{mission}} \approx \lambda_{FTR}t_{mission}$
- $Pr(FTS_A) \times Pr(FTS_B) = ?$ 
  - $p_{FTS}^2$  ? (one estimated parameter)
  - $p_{FTS-A} \times p_{FTS-B}$  ? (two estimated parameters)

## How Many Distinct Parameters in Example?

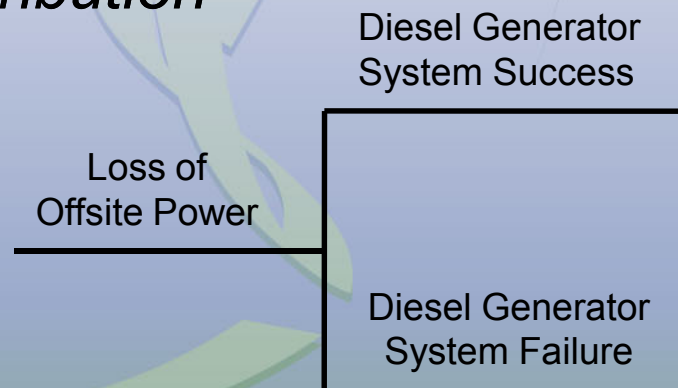
- *If we distinguish between  $p_{FTS-A}$  and  $p_{FTS-B}$* 
  - *Assume that the two  $p$ 's differ to important degree*
  - *Use only data from EDG  $i$  to estimate  $p_{FTS-i}$* 
    - *Have relatively more uncertainty in each estimate*
    - *Same prior for each  $p_{FTS-i}$  ?*
- *If we model only a single  $p_{FTS}$* 
  - *Assume that the two  $p$ 's are nearly equal*
  - *Use data from both EDGs, and generic prior, to estimate the one  $p$* 
    - *Have relatively less uncertainty in the one estimate*
    - *Use generic prior*

## How Many Distinct Parameters in Example? (cont.)

- If assign independent Bayes distributions to  $p_{FTS-A}$  and  $p_{FTS-B}$ 
  - $E(p_{FTS-A} \times p_{FTS-B}) = E(p_{FTS-A}) \times E(p_{FTS-B})$
- If assign Bayes distribution to  $p_{FTS}$ 
  - $E(p_{FTS}^2) > E(p_{FTS}) \times E(p_{FTS})$
- So if the two parameters are really the same
  - Modeling them with independent distributions yields too small a mean.
- In SAPHIRE, to force  $p_{FTS-A}$  and  $p_{FTS-B}$  to equal each other, i.e. to equal  $p_{FTS}$ 
  - Assign them to a single **correlation class**.

# End-State Frequency in LOSP Example

- Assume single  $p_{FTS}$ , single  $\lambda_{FTR}$
- $\lambda_{SystemFail} \approx \lambda_{LOSP} \times [p_{FTS}^2 + 2p_{FTS}\lambda_{FTR}t_{mission} + (\lambda_{FTR}t_{mission})^2]$
- Approximate the Bayes distribution of  $\lambda_{SystemFail}$  by a (large) random sample from the distribution



# Uncertainty Analysis for NMSS Application

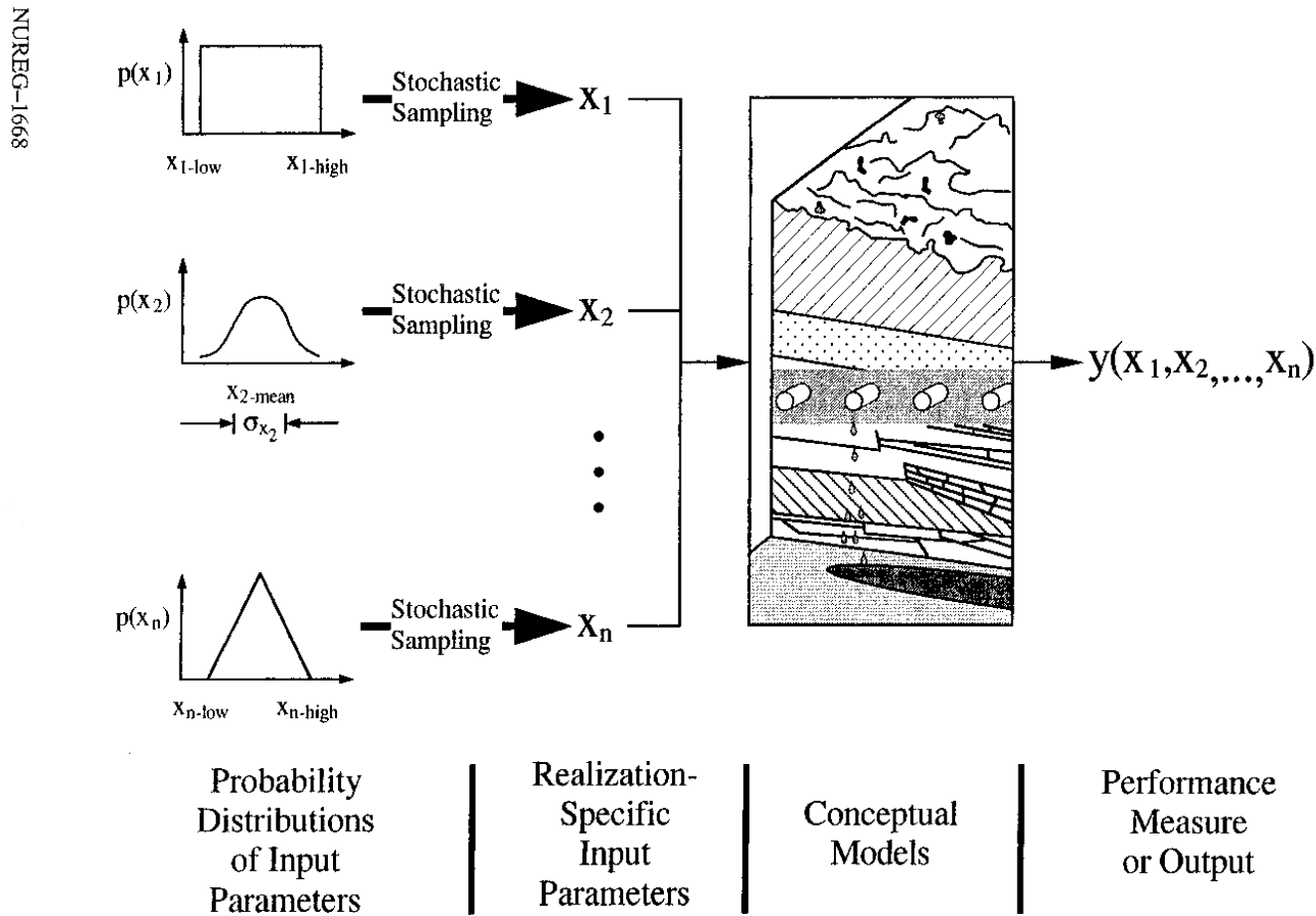


Figure 4-1. A diagram illustrating the use of the Monte Carlo method in performance assessment.

# Propagation of Uncertainty

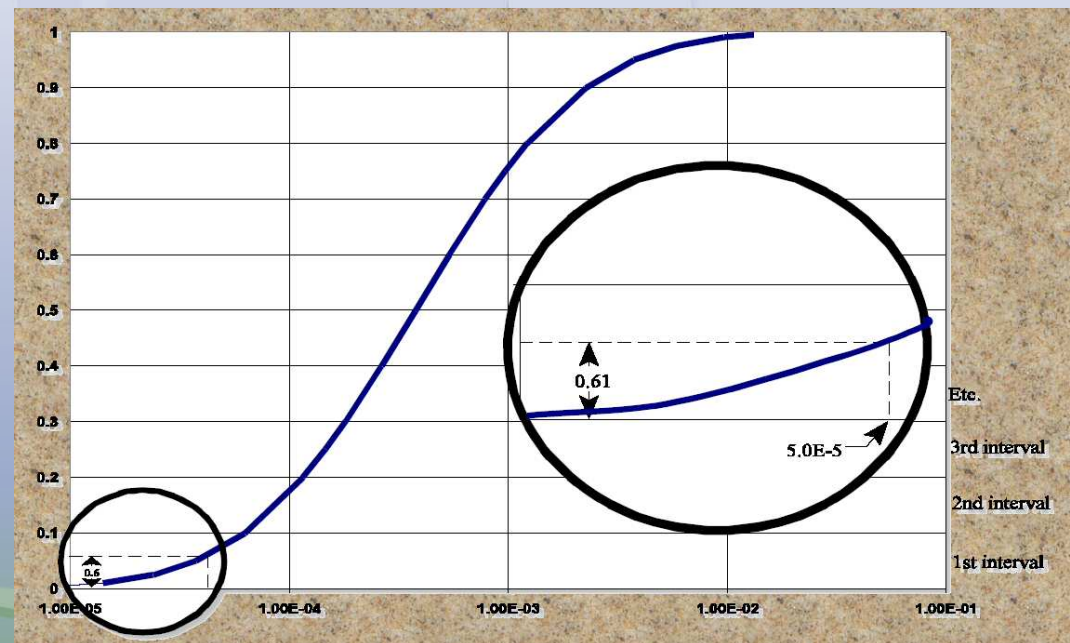
- *Prior to performing the uncertainty analysis, the PRA requires answers to three queries:*
  1. *The type of sampling*
    - *Simple random sampling (SRS)*
    - *Latin hypercube sampling (LHS)*
  2. *The number of iterations (i.e., samples)*
    - *For example, if we specify 2,000 samples and there are 10 unique basic events, we generate 20,000 random numbers*
  3. *The random number generator seed value*

## ***Two Kinds of Sampling***

- ***Simple Random Sampling (SRS)***
- *In simple random sampling, each parameter is sampled at random*
  - *The sampled values are entered into the logic model(s)*
  - *The frequency/probability of the top event is calculated*
  - *This process is repeated many times (up to the number of samples specified)*

## Two Kinds of Sampling (cont.)

- **Latin Hypercube Sampling (LHS)**
- In Latin hypercube sampling, each parameter is sampled in a stratified way, to guarantee that **each** portion of the range of the distribution is represented
- An example with 10 stratifications is shown
  - Within each portion, we randomly sample





## LHS (cont.)

- For example, let us denote one parameter by  $p$ 
  - Bayesian distribution of  $p$  is known, the posterior distribution of  $p$  based on prior information and relevant data
  - If 10 samples were to be constructed
    1.  $p$  would be sampled randomly from interval  $(p_{0.0}, p_{0.10})$ , giving a value that we denote as  $p_1$
    2. Again, sample randomly from interval  $(p_{0.10}, p_{0.20})$ , giving a value that we denote at  $p_2$
    3. Repeat process until we have  $p_{10}$  [from interval  $(p_{0.90}, p_{1.0})$ ]
  - This is **stratified sampling**, in which the sampled points are forced to cover entire range of the distribution

## LHS (cont.)

- *After all parameters in the model have been sampled in this stratified way, they are randomly matched to each other*
  - *In example with  $\lambda_{LOSP}$ ,  $p_{FTS}$ , and  $\lambda_{FTR}$ , one of the sampled values of each parameter would be chosen*
  - *However, they would be chosen so that the largest value of one parameter is **not** necessarily matched with largest or smallest values of other parameters*
  - *Instead, the choice of each pairing is random*
  - *For the chosen values, the top-event is calculated*
  - *Then another set of sampled parameter values is chosen, using values that have not been chosen yet*
- *In this way, a number (10 in this example) of values are calculated for the end-state frequency*

## **Differences Between Sampling Types**

- *While there are computational differences between the two techniques (SRS and LHS):*
  - *One should not be too concerned about which technique is selected for a particular analysis*
  - *Instead, one should be concerned about **convergence** of the numeric calculation*
  - *Convergence may be checked by noting change (or lack thereof) of uncertainty results as the number of samples is varied*
- *The samples from either method **converge** to the Bayes distribution of the end-state frequency or top-event probability*

## The Seed Value

- *A seed value tells software where, in sequence of possible random numbers, to **start selecting** random numbers*
  - *The random number generator gives a sequence of “random” integers (which are typically converted to real numbers)*
  - *A seed of “51” may tell us to start at the  $i$ 'th random integer*
  - *A seed of “1,236” may tell us to start at the  $j$ 'th random integer*
  - *etc.*
- *Again, checking for **convergence** should make seed selection irrelevant*
  - *But, to reproduce analysis results, one must use the same seed and same number of samples*

# Accuracy of Sampling

- Accuracy of a simple random sample is roughly **proportional** to square root of sample size
  - For example, if  $\lambda_{\text{SystemFail}}$  is sampled from its distribution  $n$  times
    - Mean of the distribution is estimated by **average** of  $n$  sampled values (the sample mean), and this average has standard deviation proportional to  $1/\sqrt{n}$
    - Estimate of this quantity is the standard error
      - A confidence interval equals the sample mean  $\pm$  a multiple of the standard error
- LHS is more **complicated** than simple random sampling
  - But requires **fewer samples** for comparable accuracy
  - Therefore, it is justified if each calculation of top-event is expensive or time-consuming

# Uncertainty Analysis Results

- *Every result from the PRA is uncertain*
  - *Individual basic events (FTS, FTR, etc.)*
  - *Initiating event frequency*
  - *System failure probability*
  - *Overall results such as core damage frequency*