GEOVision
geophysical services

B-311 ACOUSTIC TELEVIEWER FIELD LOG

SITE: SCE&G COL DATE: 6/21/06
CLIENT: MACTEC PROJECT 6234-06-3534S JOB: 6285
AUTHOR: R. STELLER PAGE 1 OF 2

CONTACT: MATT COOKE OFFICE PHONE: 803-931-5176
CELL PHONE: 803-261-5792
CONTACT: OFFICE PHONE:
PHONE:
CONTACT: PHONE:
PHONE:
CONTACT: PHONE:
PHONE:
DRILLER: PHONE:
COMPANY: PHONE:

DIRECTIONS TO SITE:

GENERAL SITE CONDITIONS/LOCATION:

BOREHOLE DESIGNATION: B-311 LOCATION:

COUNTY: RANGE: TOWNSHIP: SECTION:
BOREHOLE CONSTRUCTION: CASED ___ UNCASED ✓
DIAMETERS AND DEPTH RANGES: 4' 0 TO 175' ; ___, ___ TO ___
BOREHOLE TOTAL DEPTH AS DRILLED: 175'
CONDUCTOR CASING?: YES ✓ DEPTH TO BOTTOM OF CASING 53'; NO ___ 4" PVC GROUTED
DEPTH TO BEDROCK: 56.5 DEPTH TO WATER TABLE:
BOREHOLE FLUID: WATER ✓; FRESH WATER MUD ___; SALT WATER MUD ___;
OTHER:
DEPTH TO BOREHOLE FLUID: Ø TIME SINCE LAST CIRCULATION: NA

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SITE: SCE&G COL B-311 DATE: 6/21/06
CLIENT: MACTEC PROJECT 6234-06-3534S JOB: 6285
AUTHOR: R. STELLER PAGE 2 OF 2

LOGGING CREW: R. STELLER, C. CARTER
VEHICLE(S) USED AND MILEAGE: RENTAL
MOBILIZED FROM: COLUMBIA, SC DEPARTURE TIME: 7:30
ARRIVED ON SITE: 8:00
STANDBY TIME: CAUSE:
LOGGING STARTED: 9:50 LOGGING COMPLETED: 11:35

WINCH: COMPROBE___ SILVER ✓ OYO___ OTHER___
MICROLOGGER 5301 ✓ OTHER___
TELEVIEWER OPTICAL #5117___ ACOUSTIC ~~#5174~~ #5500 OTHER___

PROBE TILT TEST 2.4° BRUNTON TILT 3° PROBE HANGING ___
PROBE AZIMUTH TEST 204.1° BRUNTON AZIMUTH 205°

PROBE OFFSET	OPTICAL 1.88M(6.17FT)	ACOUSTIC 1.44M(4.72FT)
CASING STICK-UP	~~- 1.3'~~	- 1.3'
DEPTH REF. OFFSET	~~4~~	3.42

LOG NAME	START DEPTH	START TIME	END DEPTH	END TIME
~~B311 AuUP01~~			~~173'~~	~~10:50~~
B311 AuDOWN01	47'	9:50	173'	10:50
B311 AuUP01	72'	11:10	3.1	11:35

MAINTENANCE PERFORMED ON SITE:

EQUIPMENT PROBLEMS OR FAILURES:

SUGGESTIONS, ADDITIONS, CHANGES:

APPENDIX F

BORING GEOPHYSICAL LOGGING FIELD MEASUREMENT PROCEDURES

PROCEDURE FOR

OYO P-S SUSPENSION SEISMIC VELOCITY LOGGING

Background

This procedure describes a method for measuring shear and compressional wave velocities in soil and rock. The OYO P-S Suspension Method is applied by generating shear and compressional waves in a borehole using the OYO P-S Suspension Logger borehole tool and measuring the travel time between two receiver geophones or hydrophones located in the same tool.

Objective

The outcome of this procedure is a plot and table of P and S_H wave velocity versus depth for each borehole. Standard analysis is performed on receiver to receiver data. Data is presented in report format, with ASCII data files and digital records transmitted on diskette.

Instrumentation

1. OYO Model 170 Digital Logging Recorder or equivalent
2. OYO P-S Suspension Logger probe or equivalent, including two sets horizontal and vertical geophones, seismic source, and power supply for the source and receivers
3. Winch and winch controller, with logging cable
4. Batteries to operate P-S Logger and winch

The Suspension P-S Logger system, manufactured by OYO Corporation, or the Robertson Digital P-S Suspension Probe with the Robertson Micrologger2 are currently the only commercially available suspension logging systems. As shown in Figure 1, these systems consists of a borehole probe suspended by a cable and a recording/control electronics package on the surface.

The suspension system probe consists of a combined reversible polarity solenoid horizontal shear-wave generator (S_H) and compressional-wave generator (P), joined to two biaxial geophones by a flexible isolation cylinder. The separation of the two geophones is one meter, allowing average wave velocity in the region between the geophones to be determined by inversion of the wave travel time between the two geophones. The total length of the probe is approximately 7 meters; the center point of the geophones is approximately 5 meters above the bottom end of the probe.

The probe receives control signals from, and sends the amplified geophone signals to, the instrumentation package on the surface via an armored 4 or 7 conductor cable. The cable is wound onto the drum of a winch and is used to support the probe. Cable travel is measured by a rotary encoder to provide probe depth data.

The entire probe is suspended by the cable and may be centered in the borehole by nylon "whiskers." Therefore, source motion is not coupled directly to the borehole walls; rather, the source motion creates a horizontally propagating pressure wave in the fluid filling the borehole and surrounding the source. This pressure wave produces a horizontal displacement of the soil forming the wall of the borehole. This displacement propagates up and down the borehole wall, in turn causing a pressure wave to be generated in the fluid surrounding the geophones as the soil displacement wave passes their location.

Environmental Conditions

The OYO P-S Suspension Logging Method can be used in either cased or uncased boreholes. For best results, the uncased borehole must be between 10 and 20 cm in diameter, or 4 to 8 inches. A cased borehole may be as small as 3 inches, if properly grouted (see below) and the grout annulus does not exceed 1 inch.

Uncased boreholes are preferred because the effects of the casing and grouting are removed. It is recommended that the borehole be drilled using the rotary mud method. This method does little damage to the borehole wall, and the drilling fluid coats and seals the borehole wall reducing fluid loss and wall collapse. The borehole fluid is required for the logging, and must be well circulated prior to logging.

If the borehole must be cased, the casing must be PVC and properly installed and grouted. Any voids in the grout will cause problems with the data. Likewise, large grout bulbs used to fill cavities will also cause problems. The grout must be set before testing. This means the grouting must take place at least 48 hours before testing.

For borehole casing, applicable preparation procedures are presented in ASTM Standard D4428/D4428M-91 Section 4.1 (see ASTM website for copy).

Calibration

Calibration of the digital recorder is required. Calibration is limited to the timing accuracy of the recorder. GEOVision's Seismograph Calibration Procedure or equivalent should be used. Calibration must be performed on an annual basis.

Measurement Procedure

The entire probe is lowered into the borehole to a specific measurement depth by the winch. A measurement sequence is then initiated by the operator from the instrumentation package control panel. No further operator intervention is then needed to complete the measurement sequence described below.

The system electronics activates the SH-wave source in one direction and records the output of the two horizontally oriented geophone axes which are situated parallel to the axis of motion of the source. The source is then activated in the opposite direction, and the horizontal output signals are again recorded, producing a SH-wave record of polarity opposite to the previous record. The source is finally actuated in the first direction again, and the responses of the vertical geophone axes to the resultant P-wave are recorded during this sampling.

The data from each geophone during each source activation is recorded as a different channel on the recording system. The seismograph has at least six channels (two simultaneous recording channels), each with at least a 12 bit 1024 sample record. Newer seismographs may have longer record lengths. The recorded data is displayed on a CRT or LCD display and possibly on paper tape output as six channels with a common time scale. Data is stored on digital media for further processing. Up to 8 sampling sequences can be stacked (averaged) to improve the signal to noise ratio of the signals.

Review of the data on the display or paper tape allows the operator to set the gains, filters, delay time, pulse length (energy), sample rate, and stacking number in order to optimize the quality of the data before recording. In the case of the Model 170, printed data is verified by the operator prior to moving the probe. In the case of the Robertson Micrologger2, storage on the hard disk should be verified from time-to-time, certainly before exiting the borehole.

Typical depth spacing for measurements is 1.0 meters, or 3.3 feet. Alternative spacing is 0.5 meter, or 1.6 feet.

Required Field Records

1) Field log for each borehole showing
   a) Borehole identification
   b) Date of test
   c) Tester or data recorder

d) Description of measurement

e) Any deviations from test plan and action taken as a result

f) QA Review

2) Paper output records are no longer required, since the Micrologger2 cannot generate them. However, data must be stored in at least 2 places prior to leaving the site

3) List of record ID numbers (for data on digital media) and corresponding depth

4) Diskettes, CDRom, or USB flash drives with backup copies of data on hard disk, labeled with borehole designation, record ID numbers, date, and tester name.

An example Field Log is attached to this procedure.

Analysis

Following completion of field work, the recorded digital records are processed by computer using the OYO Corporation software program PSLOG and interactively analyzed by an experienced geophysicist to produce plots and tables of P and S_H wave velocity versus depth.

The digital time series records from each depth are transferred to a personal computer for analysis. Figure 2 shows a sample of the data from a single depth. These digital records are analyzed to locate the first minima on the vertical axis records, indicating the arrival of P-wave energy. The difference in travel time between these arrivals is used to calculate the P-wave velocity for that 1-meter interval. When observable, P-wave arrivals on the horizontal axis records are used to verify the velocities determined from the vertical axis data. In addition, the soil velocity calculated from the travel time from source to first receiver is compared to the velocity derived from the travel time between receivers.

The digital records are studied to establish the presence of clear SH-wave pulses, as indicated by the presence of opposite polarity pulses on each pair of horizontal records. Ideally, the SH-wave signals from the 'normal' and 'reverse' source pulses are very nearly inverted images of each other. Digital FFT – IFFT lowpass filtering are used to remove the higher frequency P-wave signal from the SH-wave signal.

The first maxima are picked for the 'normal' signals and the first minima are picked for the 'reverse' signals. The absolute arrival time of the 'normal' and 'reverse' signals may vary by +/- 0.2 milliseconds, due to differences in actuation time of the solenoid source caused by constant mechanical bias in the source or by borehole inclination. This variation does not affect the velocity determinations, as the differential time is measured between arrivals of waves created by the same source actuation. The final velocity value is the average of the values obtained from the 'normal' and 'reverse' source actuations.

In Figure 2, the time difference over the 1-meter interval of 1.70 millisecond is equivalent to a SH-wave velocity of 588 m/sec. Whenever possible, time differences are determined from several phase points on the S_H -wave pulse trains to verify the data obtained from the first arrival of the S_H -wave pulse. In addition, the soil velocity calculated from the travel time from source to first receiver is compared to the velocity derived from the travel time between receivers.

Figure 3 is a sample composite plot of the far normal horizontal geophone records for a range of depths. This plot shows the waveforms at each depth, clearly showing the S-wave arrivals. This display format is used during analysis to observe trends in velocity with changing depth.

Once the proper picks are entered in PSLOG, the picks are transferred to an Excel spreadsheet where Vs and Vp are calculated. The spreadsheet allows output for presentation in charts and tables.

Standard analysis is performed on receiver 1 to receiver 2 data, with separate analysis performed on source to receiver data as a quality assurance procedure.

Registered Geophysicist Antony Martin Date 4/10/06

QA Review ______________ Date 4/10/06

References:

1. "In Situ P and S Wave Velocity Measurement", Ohya, S. 1986. Proceedings of In-Situ '86, *Use of In-Situ Tests In Geotechnical Engineering*, an ASCE Specialty Conference sponsored by the Geotechnical Engineering Division of ASCE and co-sponsored by the Civil Engineering Dept of Virginia Tech.

2. Guidelines for Determining Design Basis Ground Motions, Report TR-102293, Electric Power Research Institute, Palo Alto, California, November 1993, Sections 7 and 8.

3. "Standard test Methods for Crosshole Seismic Testing", ASTM Standard D4428/D4428M-91, July 1991, Philadelphia, PA

OYO SUSPENSION P-S VELOCITY LOGGING SETUP

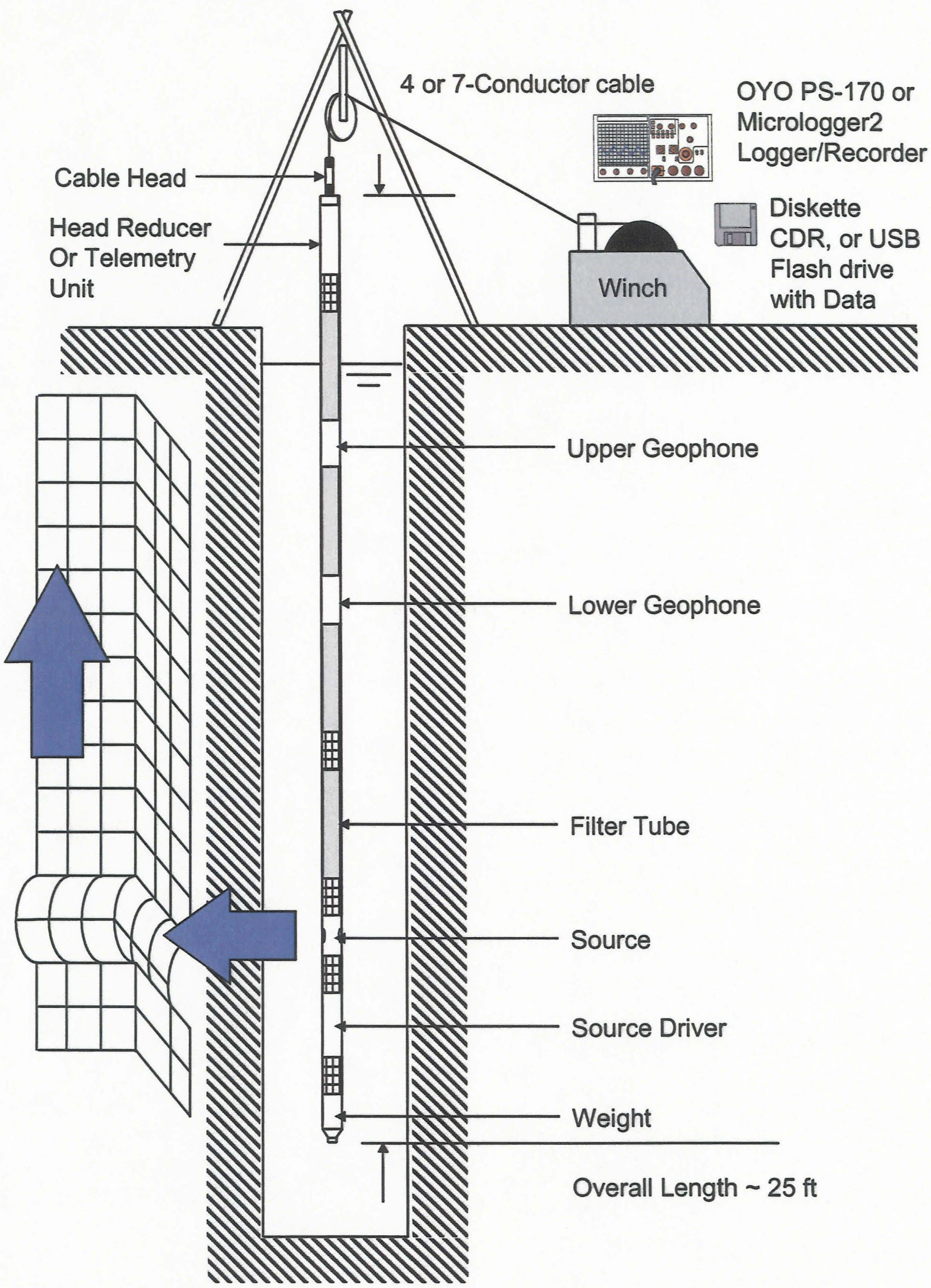

Figure 1. Suspension PS logging method setup

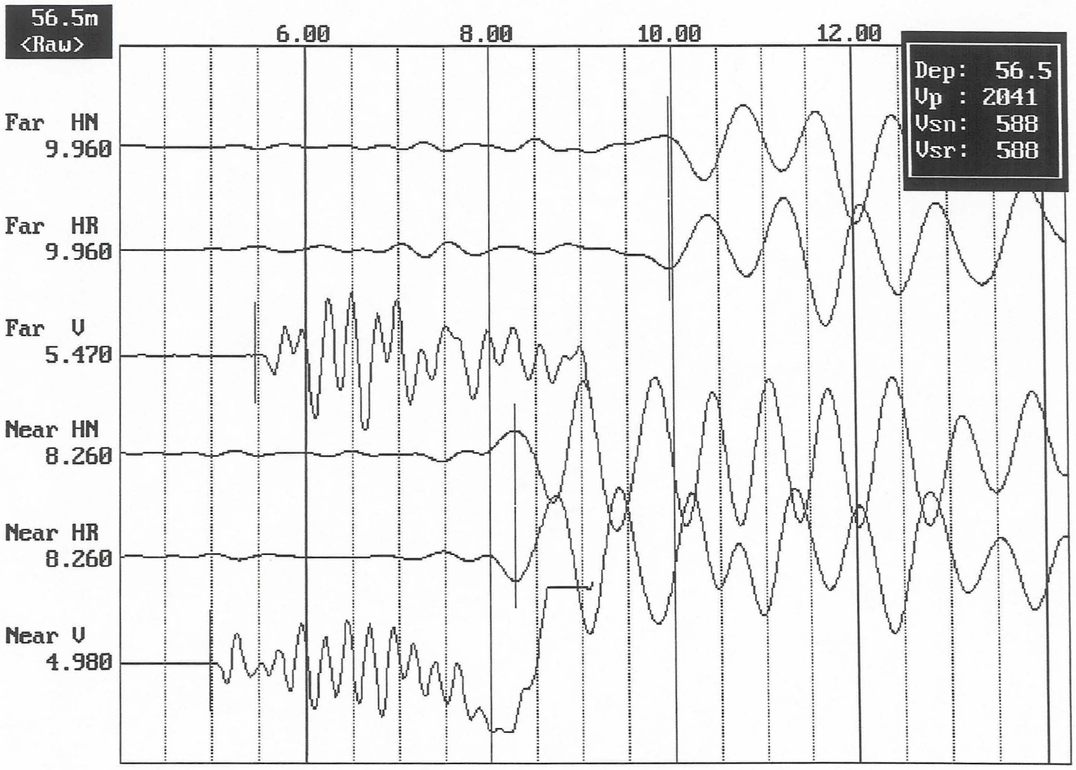

Figure 2. Sample suspension method waveform data showing horizontal normal and reversed (HR and HN), and vertical (V) waveforms received at the near (bottom 3 channels) and far (top 3 channels) geophones. The arrivals in milliseconds for each pick are shown on the left. The box in the upper right corner shows the depth in the borehole and the velocities calculated based on the picks.

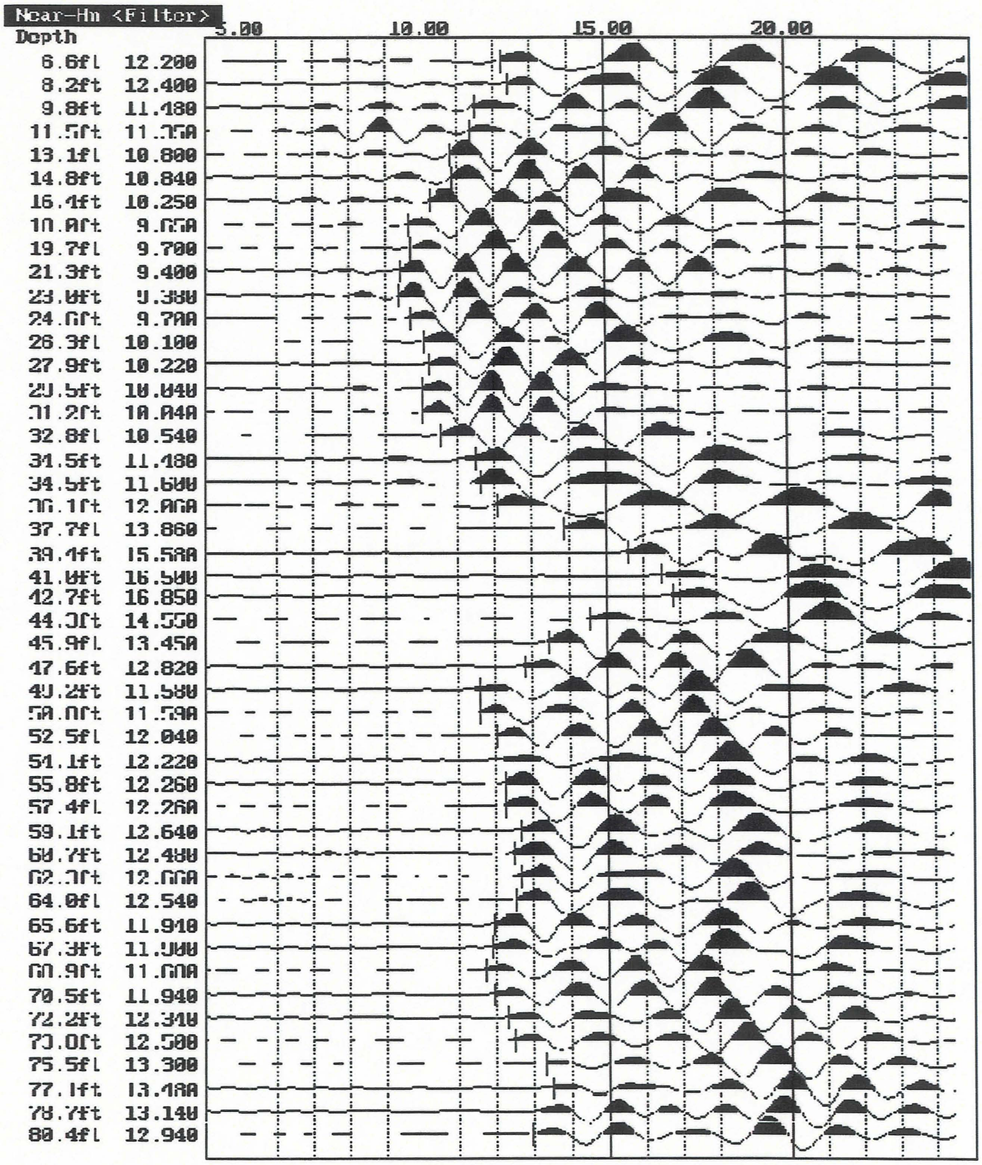

Figure 3. Sample composite waveform plot for normal shear waves received at the near geophone in a single borehole

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P-S SUSPENSION VELOCITY FIELD LOG

SITE:______________________________ DATE:________________
CLIENT:____________________________ JOB:________________
AUTHOR:____________________________ PAGE 1 OF ____

CONTACT:__________________ OFFICE PHONE:________________
PHONE:________________
CONTACT:__________________ OFFICE PHONE:________________
PHONE:________________
CONTACT:__________________ ________ PHONE:________________
PHONE:________________
CONTACT:__________________ ________ PHONE:________________
PHONE:________________
DRILLER:__________________ ________ PHONE:________________
COMPANY:__________________ ________ PHONE:________________

DIRECTIONS TO SITE:____

GENERAL SITE CONDITIONS/LOCATION:__________________________

EA#:______________________
BOREHOLE DESIGNATION:______________LOCATION:________________

COUNTY:__________RANGE:________TOWNSHIP:__________SECTION:______
BOREHOLE CONSTRUCTION: CASED____ UNCASED_____
DIAMETERS AND DEPTH RANGES: ______ 0 TO ________ ; _____, ______ TO _______
BOREHOLE TOTAL DEPTH AS DRILLED:______________
CONDUCTOR CASING?: YES____ DEPTH TO BOTTOM OF CASING______; NO____
DEPTH TO BEDROCK:_______ DEPTH TO WATER TABLE:________
BOREHOLE FLUID: WATER_____; FRESH WATER MUD_____; SALT WATER MUD _____;
OTHER:____
DEPTH TO BOREHOLE FLUID:________ TIME SINCE LAST CIRCULATION:________

GEOVision Geophysical Services 1151 Pomona Road, Suite P, Corona, CA 92882 Ph (951) 549-1234 Fx (951) 549-1236

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SITE:______________________ DATE:______________
CLIENT:______________________ JOB:______________
AUTHOR:______________________ PAGE 2 OF _____

LOGGING CREW:______________________
VEHICLE(S) USED AND MILEAGE: ______________________
MOBILIZED FROM:______________ DEPARTURE TIME:______________
ARRIVED ON SITE:______________
STANDBY TIME:______________ CAUSE:______________
LOGGING STARTED:______________ LOGGING COMPLETED:______________
STANDBY TIME:______________ CAUSE:______________
LOGGING STARTED:______________ LOGGING COMPLETED:______________
DEMOBILIZED TO:______________ ARRIVAL TIME:______________
ADDITIONAL DEMOB TIME:______________ REASON:______________

BATTERIES CHANGED BEFORE LOGGING: YES_____; NO_____; STORED WITH NEW_____

WINCH	COMPROBE ☐	GREY ☐	OYO ☐	RG ☐	OTH ☐	
INSTRUMENT	OYO 12004 ☐	15014 ☐	19029 ☐		RG 160023 ☐	160024 ☐
RECEIVER S/N	12008 ☐	20042 ☐	26066 ☐	11001 ☐	23053 ☐	

MAINTENANCE PERFORMED ON SITE:______________________

EQUIPMENT PROBLEMS OR FAILURES:______________________

SUGGESTIONS, ADDITIONS, CHANGES:______________________

COMMENTS:______________________

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GEOVISION SUSPENSION LOGGING FIELD NOTES

SITE: ______________________ DATE: ______________
CLIENT: ______________________ JOB: ______________
AUTHOR: ______________________ PAGE ______ OF ______

DEPTH METERS	DEPTH FEET	UNFILTERED FILE NO.	FILTERED FILE NO.	COMMENTS CASING, WATER, ROCK, ETC
0.5	1.64			
1.0	3.28			
1.5	4.92			
2.0	6.56			
2.5	8.20			
3.0	9.84			
3.5	11.48			
4.0	13.12			
4.5	14.76			
5.0	16.40			
5.5	18.04			
6.0	19.69			
6.5	21.33			
7.0	22.97			
7.5	24.61			
8.0	26.25			
8.5	27.89			
9.0	29.53			
9.5	31.17			
10.0	32.81			
10.5	34.45			
11.0	36.09			
11.5	37.73			
12.0	39.37			
12.5	41.01			
13.0	42.65			
13.5	44.29			
14.0	45.93			
14.5	47.57			
15.0	49.21			
15.5	50.85			
16.0	52.49			
16.5	54.13			
17.0	55.77			
17.5	57.41			
18.0	59.06			

GEOVISION SUSPENSION LOGGING FIELD NOTES

SITE: ______________________ DATE: ______________

CLIENT: ______________________ JOB: ______________

AUTHOR: ______________________ PAGE ______ OF ______

DEPTH METERS	DEPTH FEET	UNFILTERED FILE NO.	FILTERED FILE NO.	COMMENTS CASING, WATER, ROCK, ETC
18.5	60.70			
19.0	62.34			
19.5	63.98			
20.0	65.62			
20.5	67.26			
21.0	68.90			
21.5	70.54			
22.0	72.18			
22.5	73.82			
23.0	75.46			
23.5	77.10			
24.0	78.74			
24.5	80.38			
25.0	82.02			
25.5	83.66			
26.0	85.30			
26.5	86.94			
27.0	88.58			
27.5	90.22			
28.0	91.86			
28.5	93.50			
29.0	95.14			
29.5	96.78			
30.0	98.43			
30.5	100.07			
31.0	101.71			
31.5	103.35			
32.0	104.99			
32.5	106.63			
33.0	108.27			
33.5	109.91			
34.0	111.55			
34.5	113.19			
35.0	114.83			
35.5	116.47			
36.0	118.11			

GEOVISION SUSPENSION LOGGING FIELD NOTES

SITE: ______________________ DATE: ____________

CLIENT: ______________________ JOB: ____________

AUTHOR: ______________________ PAGE ______ OF ______

DEPTH METERS	DEPTH FEET	UNFILTERED FILE NO.	FILTERED FILE NO.	COMMENTS CASING, WATER, ROCK, ETC
36.5	119.75			
37.0	121.39			
37.5	123.03			
38.0	124.67			
38.5	126.31			
39.0	127.95			
39.5	129.59			
40.0	131.23			
40.5	132.87			
41.0	134.51			
41.5	136.15			
42.0	137.80			
42.5	139.44			
43.0	141.08			
43.5	142.72			
44.0	144.36			
44.5	146.00			
45.0	147.64			
45.5	149.28			
46.0	150.92			
46.5	152.56			
47.0	154.20			
47.5	155.84			
48.0	157.48			
48.5	159.12			
49.0	160.76			
49.5	162.40			
50.0	164.04			
50.5	165.68			
51.0	167.32			
51.5	168.96			
52.0	170.60			
52.5	172.24			
53.0	173.88			
53.5	175.52			
54.0	177.17			

GEOVISION SUSPENSION LOGGING FIELD NOTES

SITE: ____ DATE: ____
CLIENT: ____ JOB: ____
AUTHOR: ____ PAGE ____ OF ____

DEPTH METERS	DEPTH FEET	UNFILTERED FILE NO.	FILTERED FILE NO.	COMMENTS CASING, WATER, ROCK, ETC
54.5	178.81			
55.0	180.45			
55.5	182.09			
56.0	183.73			
56.5	185.37			
57.0	187.01			
57.5	188.65			
58.0	190.29			
58.5	191.93			
59.0	193.57			
59.5	195.21			
60.0	196.85			
60.5	198.49			
61.0	200.13			
61.5	201.77			
62.0	203.41			
62.5	205.05			
63.0	206.69			
63.5	208.33			
64.0	209.97			
64.5	211.61			
65.0	213.25			
65.5	214.90			
66.0	216.54			
66.5	218.18			
67.0	219.82			
67.5	221.46			
68.0	223.10			
68.5	224.74			
69.0	226.38			
69.5	228.02			
70.0	229.66			
70.5	231.30			
71.0	232.94			
71.5	234.58			
72.0	236.22			

GEOVISION SUSPENSION LOGGING FIELD NOTES

SITE: ______________________ DATE: __________

CLIENT: ______________________ JOB: __________

AUTHOR: ______________________ PAGE ______ OF ______

DEPTH METERS	DEPTH FEET	UNFILTERED FILE NO.	FILTERED FILE NO.	COMMENTS CASING, WATER, ROCK, ETC
72.5	237.86			
73.0	239.50			
73.5	241.14			
74.0	242.78			
74.5	244.42			
75.0	246.06			
75.5	247.70			
76.0	249.34			
76.5	250.98			
77.0	252.62			
77.5	254.27			
78.0	255.91			
78.5	257.55			
79.0	259.19			
79.5	260.83			
80.0	262.47			
80.5	264.11			
81.0	265.75			
81.5	267.39			
82.0	269.03			
82.5	270.67			
83.0	272.31			
83.5	273.95			
84.0	275.59			
84.5	277.23			
85.0	278.87			
85.5	280.51			
86.0	282.15			
86.5	283.79			
87.0	285.43			
87.5	287.07			
88.0	288.71			
88.5	290.35			
89.0	291.99			
89.5	293.64			
90.0	295.28			

GEOVISION SUSPENSION LOGGING FIELD NOTES

SITE: ______ DATE: ______
CLIENT: ______ JOB: ______
AUTHOR: ______ PAGE ______ OF ______

DEPTH METERS	DEPTH FEET	UNFILTERED FILE NO.	FILTERED FILE NO.	COMMENTS CASING, WATER, ROCK, ETC
90.5	296.92			
91.0	298.56			
91.5	300.20			
92.0	301.84			
92.5	303.48			
93.0	305.12			
93.5	306.76			
94.0	308.40			
94.5	310.04			
95.0	311.68			
95.5	313.32			
96.0	314.96			
96.5	316.60			
97.0	318.24			
97.5	319.88			
98.0	321.52			
98.5	323.16			
99.0	324.80			
99.5	326.44			
100.0	328.08			
100.5	329.72			
101.0	331.36			
101.5	333.01			
102.0	334.65			
102.5	336.29			
103.0	337.93			
103.5	339.57			
104.0	341.21			
104.5	342.85			
105.0	344.49			
105.5	346.13			
106.0	347.77			
106.5	349.41			
107.0	351.05			
107.5	352.69			
108.0	354.33			

GEOVISION SUSPENSION LOGGING FIELD NOTES

SITE: ______ DATE: ______
CLIENT: ______ JOB: ______
AUTHOR: ______ PAGE ______ OF ______

DEPTH METERS	DEPTH FEET	UNFILTERED FILE NO.	FILTERED FILE NO.	COMMENTS CASING, WATER, ROCK, ETC
108.5	355.97			
109.0	357.61			
109.5	359.25			
110.0	360.89			
110.5	362.53			
111.0	364.17			
111.5	365.81			
112.0	367.45			
112.5	369.09			
113.0	370.73			
113.5	372.38			
114.0	374.02			
114.5	375.66			
115.0	377.30			
115.5	378.94			
116.0	380.58			
116.5	382.22			
117.0	383.86			
117.5	385.50			
118.0	387.14			
118.5	388.78			
119.0	390.42			
119.5	392.06			
120.0	393.70			
120.5	395.34			
121.0	396.98			
121.5	398.62			
122.0	400.26			
122.5	401.90			
123.0	403.54			
123.5	405.18			
124.0	406.82			
124.5	408.46			
125.0	410.10			
125.5	411.75			
126.0	413.39			

PROCEDURE FOR USING THE ROBERTSON GEOLOGGING HI-RESOLUTION ACOUSTIC TELEVIEWER (HiRAT)

Reviewed 2/13/06

Background

The acoustic televiewer is a device for producing a qualitative image of the wall of a borehole. Because it uses ultrasound rather than visible light it is able to work in dirty or opaque borehole fluids, although heavy drilling mud will cause excessive dispersion of the acoustic beam. The picture below shows the sonde's lower nylon section, and one of the bowspring attachments which are used to centralize the sonde in the borehole.

Pulses of ultrasound (0.5 - 1.5MHz) are generated by a piezo-electric resonator. The pulses are transmitted through the oil in which the resonator is immersed, through the wall of the acoustic housing, then propagate through the borehole fluid and are reflected from the wall of the borehole. The reflected energy is picked up by the same transducer, from which is recorded both the ***amplitude*** of the returned pulse and the ***travel-time*** which have elapsed. Blanking must be applied to prevent the transducer from registering reflections from the inside surface of the acoustic housing. The material of the housing is chosen so that its acoustic properties are similar to the oil which fills it. The housing is not designed to withstand borehole fluid pressures, but has a piston device to allow equalization between inside and outside pressure.

The ***amplitude*** of the returned pulse is a function of the acoustic reflectivity of the borehole wall. If the beam strikes a hard borehole wall normally to the surface the energy will be returned to the transducer and a strong return will be recorded. If the formation is softer, then less energy will be reflected. Also, if the surface of the borehole is rough, or effectively missing because of the presence of a fracture or other structure, then energy will be dispersed and a poor return will be recorded.

The ***travel-time*** is a simple function of the diameter of the borehole and the velocity of sound in the borehole fluid (typically 1.5Km/sec). An A/D converter monitors the output from the transducer once the blanking period has expired and a comparator is used to detect the peak amplitude during the sampling window.

The coaxially-mounted transducer has a planar radiating surface, but the vibration characteristics are such that the acoustic pulse is emitted as a 'pencil' beam. The emitted beam is deflected by a planar mirror so that it leaves the acoustic housing at right angles to the sonde axis. The mirror is rotated to scan the borehole wall. The ultrasound pulses are synchronized with rotation of the mirror so that up to 360 pulses are emitted in every revolution. Because of the time which must elapse for the two-way transit of the borehole fluid, there is an upper limit upon the number of radial samples that may be acquired from a borehole of a particular radius. In larger boreholes, therefore, it may be necessary to reduce the number of radial samples. The sonde is able to operate at 90, 180 or 360 samples per revolution.

An image of the borehole wall is produced by moving the sonde along the borehole axis while it is scanning radially. By the same logic as shown above, it can be seen that any horizontal point will be imaged by more than one sweep of the acoustic beam so long as the axial movement of the sonde during one complete sweep is no greater than the beam diameter. An upper limit is therefore imposed upon the logging speed which will be a function of the rotational speed of the transducer, the radial sampling interval and borehole diameter.

Objective

The objective of this procedure is to provide a pseudo "core" of the borehole, and map the orientation and angles of cracks and voids in rock boreholes.

Instrumentation

This procedure is written specifically for the Robertson Geologging High-Resolution Acoustic Televiewer (HiRAT). The required equipment includes:

1. The Robertson High-Resolution Acoustic Televiewer (HiRAT) sonde with centralizers
2. A 4-conductor wire-line winch with cable at least 30m (100ft) longer than the depth of the borehole (RG Smart Winch or equivalent. GEOVision has adapted all our 4-conductor winches)
3. A sheave with depth encoder with minimum 500 pulse/revolution
4. A Robertson Geologging Micrologger II
5. A laptop with Winlogger installed and the following minimum system requirements:
   - Windows 98SE or above
   - 64M System memory
   - 800x600x24 SVGA Display with DirectX 8.0
   - 500Mhz CPU
   - USB 2.0 connection
6. Battery power supply with cables

Environmental Conditions

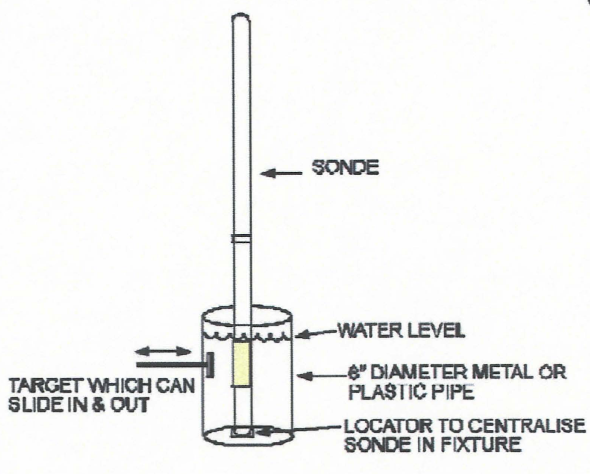
This tool is designed for fluid-filled boreholes between 67 and 150mm (3-6in) in rock. Since fine cracks are usually not visible in the walls of soil borings, the televiewers add very little information from a soil boring than a simple video. Now if the boring has soil AND rock, televiewer visuals in the soil may still be useful.

Calibration

The acoustic televiewer uses the variability in reflectance and the travel time to make an image of the borehole wall, mostly resulting from relative differences of materials and the physical characteristics of the wall. Since these are relative measurements, no field calibration of the sonde is required. However, it is important that the same location in the borehole be checked at the start and finish of the logging to make sure that the response or functionality haven't changed during the measurement.

A test fixture may be used to check function of the acoustic televiewer prior to use. This test fixture should comprise a plastic pipe, with a known internal diameter between 3 and 6 inches. This should be filled with water and the sonde stood upright in the fixture. A target made of metal or metal foil is glued on the inside of the container, or optionally on a seal and shaft so that it can be moved in and out on a line radial to the center-line of the pipe. A representation of this is shown in the figure below.

The purpose of this test fixture is to check the ability of the sonde to differentiate between materials of different acoustic reflectances, and different travel times, and to check the calibration of the caliper function of the sensor using the measured diameter of the pipe. However, if calibrated caliper measurements are required, it is recommended that a mechanical 3-arm caliper tool be used for this purpose because it can be calibrated in the field prior to use. The HiRAT will give very accurate results but this procedure does not cover calibration.



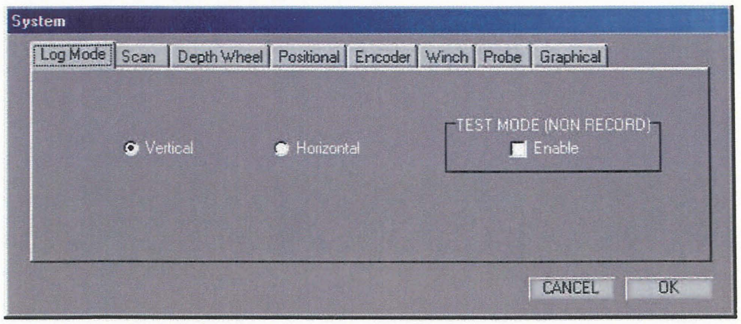
TELEVIEWER TEST JIG

Hi-RAT Field Procedure

Because the logging software is a standalone module, there are a number of settings which must be initialized independently of the WinLogger software. These include the depth measurement subsystem and sonde operating modes. Click on 'System' on the menu bar to show the following dialog boxes:

1.0 Log Mode

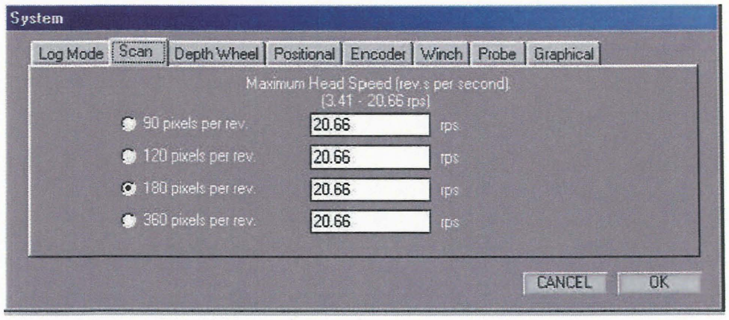
The sonde can operate in three distinct modes:



- Vertical mode is used for boreholes which are drilled from the surface and are deviated at less than 70 degrees from the vertical. Most exploration boreholes will fall into this class. In this mode the image is orientated according to compass directions (magnetic co-ordinates).
- Horizontal mode is used for boreholes which are sub-horizontal so their inclination will probably exceed 70 degrees from the vertical. Boreholes in this class would normally be drilled as part of ground investigations for tunneling and mining, drilling ahead of a drive to determine the nature and extent of fracturing. In this mode the image is orientated according to gravitational coordinates (up/down) since there is no unique point of the image circle which can be orientated to North with any precision.
- Test mode is used to exercise all sonde functions without creating a log. The image will scroll on the screen in the normal fashion, and orientation readouts will be refreshed continuously.

2.0 Scan Parameters

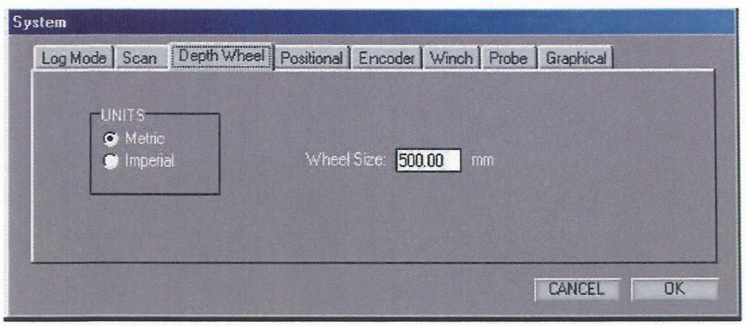
The scan parameters control the radial sampling of the borehole. The values will be retained between logging sessions, so the sonde will be initialized correctly at power-on. There are three parameters in the dialog:



- The radial sampling rate can be set to one of 90, 120, 180, 360 samples per revolution. There is a relationship between the logging speed and the radial sampling rate, since the time taken to send the dataset to the surface depends upon its length. The size of the log file is also determined by the radial sampling rate. The probe will always try to use the maximum head speed entered. If limited by a low Baud rate or a large 'window' setting then the probe will reduce its head speed automatically to compensate - see sonde operation section.

3.0 Depth Wheel Configuration

The depth measurement system is dependent upon the combination of depth measurement wheel with its calibrated groove, and the shaft encoder which translates rotation into pulses which are counted by the logging system controller. Two parameters are therefore required: depth wheel circumference and encoder pulse rate. The encoder parameters are covered in a subsequent topic.

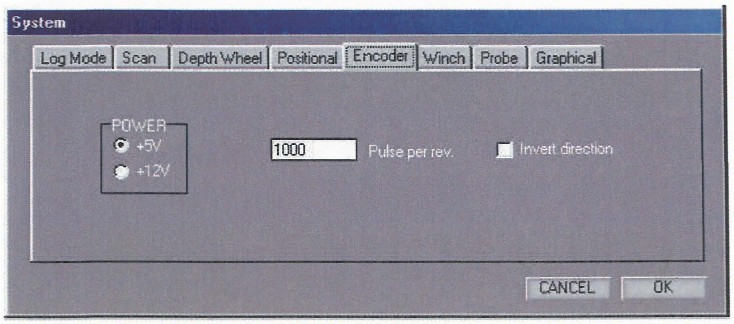


- Select Metric or Imperial depth measurement units from the left-hand pane.

- Type the circumference of the depth measurement wheel into the 'wheel size' box. The standard sizes of GEOVision wheels are 1000mm. If you are measuring in Imperial units (or changing back to metric units), the standard wheel size can be converted automatically by clicking the left mouse button and choosing the appropriate conversion. The size is always specified in units of 1/1000 of the depth unit i.e. millimetres (mm) or millifeet (mft).

4.0 Encoder Configuration

The depth measurement system is dependent upon the combination of depth measurement wheel with its calibrated groove, and the shaft encoder which translates rotation into pulses which are counted by the logging system controller. The depth wheel circumference is covered in a previous topic. In order to accommodate a variety of encoders, their operational characteristics can be configured in the software.



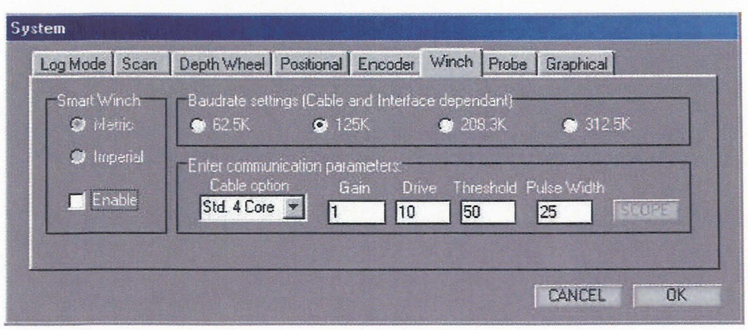
- Select supply voltage from the radio buttons in the left-hand pane. The options are 5 Volt and 12 Volt. GEOVision encoders are always specified for 5 Volt operation.

- Type the number of pulses emitted per revolution into the central box. The standard values for all GEOVision winches are 500 pulses/rev.

- The logical direction of movement can be reversed if required to accommodate the directional characteristics (phase lead or lag) of the different encoder types.

5.0 Winch and Cable Configuration

Support for remote control of the RG Smart Winch is provided, and can be enabled by checking the ***Enable*** control in the left-hand Smart Winch pane. If the Smart Winch control is enabled, it is also necessary to select the measure units in force - select ***Metric*** or ***Imperial*** from the radio buttons on offer.



The Baud settings can be chosen to match the *quality* of the communication channel. The channel will be effected by cable type and length. Typically a Baudrate of 312.5K is used. The remaining controls in the dialog relate to the communications parameters. The operation is entirely compatible with the WinLogger software operation and the values would be expected to be the same as those in force for logging six-channel type sondes with that software. (Certain probe types may be fitted with a digital interface that does not require set-up and in this case the parameter edit boxes will not appear.)

- ***Cable Option*** is used to select the logging cable type which is available on the winch. The options are *Not Connected*, *Std. 4 Core*, *Differential* and *Monocable*. The only cable types used in GEOVision systems is Std. 4 Core. Select the appropriate type from the drop-down menu box. Note this value can only be changed when the probe power is turned off.

- ***Gain*** is related to cable length and uphole signal attenuation. Gain values range from 0-3 and control the amplification applied to the incoming signal. Use the *Scope* dialog to visualize the incoming signals. Gain should be set so that the signal reaches between 70% and 100% of the height of the display, generally obtained with a setting of 0 for GEOVision winches. If the peak height exceeds this level, clipping will result in artifacts which will be detected erroneously. Click *Apply* to set the parameters before proceeding to the *Scope* dialog.

- ***Threshold*** is the level at which the incoming signals are detected. Gain and Threshold are related, and can be visualized using the *Scope* dialog. Set the gain so that the signal reaches between 70% and 100% of the height of the display. Then adjust the threshold so that it is between 50% and 70% of the height of the pulses displayed and clear of any region of 'overshoot' of the positive and negative pulses. This will ensure that peaks are detected and noise is ignored. Generally a setting of 25 is used for GEOVision winches. When the scope dialog is displayed, the position of the mouse is reported as a threshold value to make it simpler to infer the correct setting. The scope option is greyed out when the probe power is turned off.

- ***Drive*** sets the strength of the downhole signal. It is not possible to visualize the downhole signal, but the effect of insufficient drive is to disable downhole communication, which will result in the commands being ignored by the sonde. Values range from 0 -127, and for GEOVision winches will be around 10. Increase the drive for longer cables.

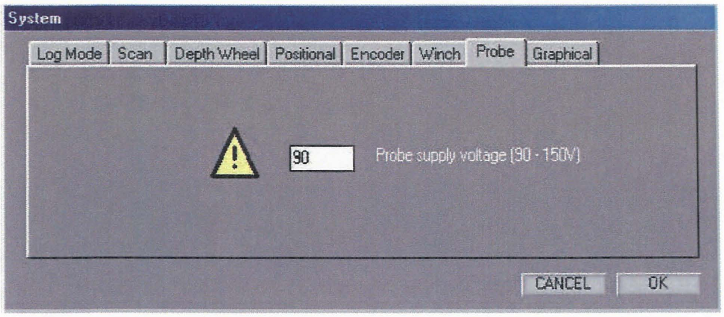
- ***Pulse Width*** This is the width of the transmitted communication pulses in 100nS steps. The default is 25 equivalent to 2.5uS. The range is from 8 to 64. The pulse width can be reduced to prevent signal overshoot on short cables. The default value is used in most cases. Note any changes only come into effect during a log. (Note setting too large a pulse width when using the highest Baud rates will automatically be prevented within the probe and the pulse width reduced.)

IMPORTANT Please note the effects of changing 'Baud' will not appear until the first new log is made. The setting for 'threshold' may be effected by an increase in the 'Baud' rate please recheck 'threshold' if 'Baud' is altered using the 'Scope' function after making a short test log.

The parameters which are entered will be applied automatically if you close the dialog with ***OK***. The above parameters once set correctly will be remembered by the system and should never need to be altered.

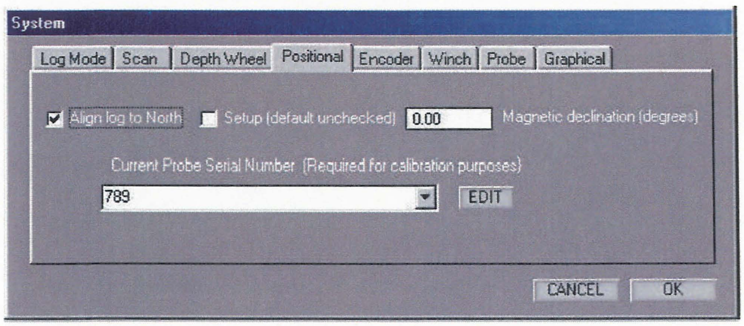
6.0 Probe Configuration

The probe is normally energized at 90 Volts from the surface. However, it may be necessary to compensate for voltage drop on longer cables due to the higher power draw of this sonde. The voltage at the surface may be increased in order to deliver 90 Volts at the sonde. Simply type the value into the text box provided. The voltage should be set at 90V for all GEOVision winches. Values outside the indicated range will be rejected.



7.0 Positional Configuration

The probe includes a 3-axis orientation package, and is capable of producing a borehole image aligned to geographic North. This is achieved by determining and applying two image rotation parameters:



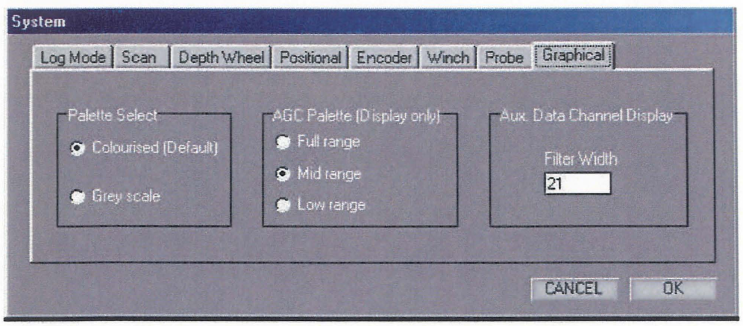
- ***Magnetic Declination*** is used to correct for the difference between Magnetic North and True North. The value varies from place to place, so the local value must be inserted here if you wish to perform this correction during data collection. This correction may also be made during processing. If the value is zero, the log will be referred to Magnetic North.
- ***Align to North*** is a check-box used to select image rotation to start at Magnetic North. If in addition a value is set for Magnetic Declination (see above) the image will be rotated to start at True North. If the box is not checked, the image will not be oriented to geographic co-ordinates, but will use the local co-ordinate frame of the sonde (X, Y, Z axis of the orientation module). This mode may be used to inspect the inside of magnetic casing, where an orientated image would be subjected to random effects caused by the metalwork.
- Set-up mode is selected by checking the ***Setup*** box, and is used to determine the required image rotation offset to correct for the angle between the axis of the orientation package and the index mark of the rotating transducer section. In set-up mode the normal sonde azimuth display is modified, and will instead show the 'relative bearing' which is measured between the high side of the borehole and the orientation sensor index. Check ***Setup***, then OK to close the dialog. The icon adjacent to the sonde azimuth readout at the top of the screen is modified with the legend CAL when the system is in set-up mode. The sonde must now be placed in a stand or jig so that it

is inclined at about 20 degrees to the vertical, and adjacent to a target fixed to the jig so that it is directly above the transducer in the vertical plane. Lower the sonde with its attachment into a large bucket of water so that the transducer and target are fully immersed. Start the radial amplitude display, when it will be possible to see the strong signal returning from the target. Rotate the sonde so that the image of the target moves to the top of the display. When the two are coincident, the 'relative bearing' reads out the image rotation offset. This value is fixed for the sonde unless it is disassembled and rebuilt, at which point the procedure MUST be repeated. Please see the additional topic on the Radial Amplitude Display for further details.

- The ***Serial Number*** list box is used to select the sonde which is in use. When the appropriate sonde is selected, the image rotation offset determined by the above procedure is selected. To edit the image offset click the '***Edit***' and enter the new offset. Several serial numbers and associated offsets can be stored and selected as required.

8.0 Graphical

The palette can be changed between a colored and grey scale setting. The changes affect the log screen palette display and are also applied when replaying a log. Selecting Full range in the 'AGC Palette' will cause the software to spread the palette over the full 16bit signal. 'Mid range' will spread the palette over the first quarter of the 16bit range and 'Low range' will spread the palette over the first eighth of the 16 bit range. In most cases the 'Low range' selection is used. Note these settings do not affect the stored log data in any way. The 'Filter Width' is applied to the Natural Gamma trace data and is a simply running average filter. The range of the filter width is from 1 to 50 (x 10 millidepth units ie. mm or mft).

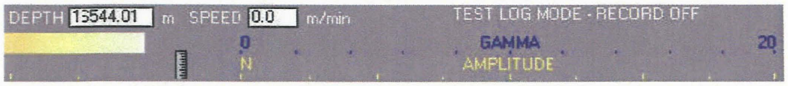


9.0 Sonde Operation

When the operations specified above have been reviewed and the correct settings have been selected, the system is ready for use. The main screen area is divided into 3 horizontal elements. At the top is the depth and orientation readout, together with the scale headings for the scrolling display of unwrapped borehole image.

On the left side of the depth track is the travel time display, with text boxes for sonde inclination, azimuth and head temperature.

On the right side is the display of amplitude and indication of current operating mode. Located in the center above the depth track are the text boxes for depth and cable speed (computed at the surface). The ranges for the 'Natural Gamma' channel overlay (optional) are shown above the Amplitude.



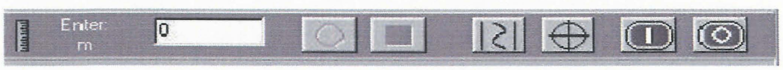
The central area is utilized for the scrolling display of unwrapped borehole data. The display is orientated with the left edge corresponding to North point of the aligned image data (if orientation is selected) according to the outputs of the sonde's orientation package.

The lower area has controls for the winch (applicable to RG Smart Winch only), depth initialization and sonde control.

The winch control area is only displayed when RG SmartWinch operation is enabled - see section 5 - and has four controls. Set Target Speed by typing the required speed into the window and pressing Enter.

Cable movement is initiated by clicking on either the UP or DOWN arrow control.

Cable movement is halted by clicking on the square STOP control.



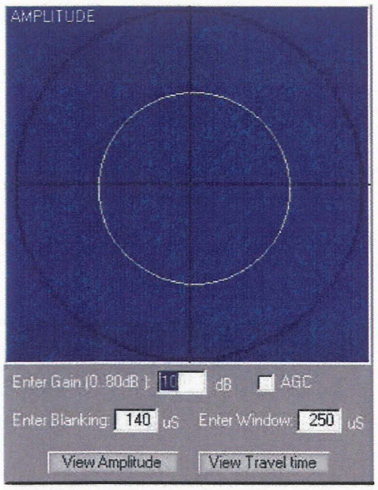
Depth is initialized by typing the required value into the entry box and pressing Enter. The entry box is not available at times when the system is in logging mode and the depth should not be changed by user entry.

Sonde power is applied by clicking on the green-colored 1 button. Power is turned off by clicking on the red-colored 0 button. There is no indicator for the state of the power supply on the desktop, so the external indicators should be observed for this purpose.

To make a log ensure that the Test Mode is disabled - see section 1, Log Mode setting. Click File|New Log and select a filename. Old logs may be overwritten if necessary -TAKE CARE. The header editor will be started automatically. A previous set of header data may be loaded by clicking LOAD and choosing a template.

To start logging, click on the red Record (circle) control. The log data will start to scroll down the screen after a brief pause for synchronization. The messages "DSP2: Detecting data stream" and "Updating probe settings" will be observed at the bottom of the screen during this process. Note that the screen scrolling direction is not affected by the actual direction of movement of the sonde. To cease logging, click on the black STOP control (square). The data should be immediately backed up to a USB drive, CD, or other data storage prior to beginning another log.

If the data display from a probe which is properly connected appears to occupy only half of the track area, with the remainder filled with random colors such as green which are not part of the regular palette, then it is most likely that the downhole data communication is not functioning properly. This symptom is due to the fact that the probe settings cannot be communicated properly, and it is operating in its default power-up mode. If this is the case, the Drive setting of the System|Winch dialog should be increased or decreased accordingly. See section 5 for full details.



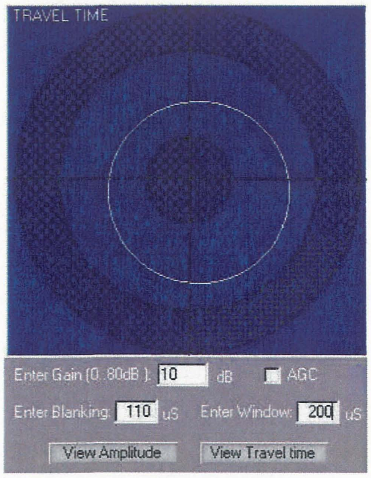
To adjust the sonde gain it is necessary to use the Radial Amplitude plot, which is enabled by clicking on the circle with cross-hairs symbol. When the dialog is active a new window will open on top of the unwrapped data display. In this display, the data is presented as a 'polar' plot. Press the 'View Amplitude' button to display the amplitude plot. This plot shows amplitude increasing towards the outside of the circle and the compass direction following the sweep of the transducer. The line indicating the data is drawn in the regular palette, so that high amplitudes are drawn in white and low amplitudes in black/brown. The picture here shows the image of the inside of a cylinder.

If the data is concentrated in a small circle at the center, the gain is too low and should be increased. If the data is obviously clipped at the outside of the circle, then the gain should be reduced. Type the new gain value into the entry box and press Enter. The ideal would be to set a gain value which allows the peak values to be displayed without clipping, with the majority of the data around the half-way level. It may also be necessary to adjust the blanking to ensure that internal reflections from the acoustic housing are not detected at the new gain value. This will be apparent in the unwrapped data display as pronounced patterning unrelated to the true target. The AGC option causes the probe to set gain automatically thus preventing signal saturation in most cases. (The gain is varied in 6dB steps

Blanking Period and window length can be set independently. Blanking is set to avoid reflections from the housing of the acoustic transducer or random reflections from a rugose borehole, and window length is set to accommodate the range of borehole radius that might be expected. An error will be indicated if the sum of the blanking period and window length would be greater than 409 microseconds, which is the maximum range of the timer. The default value for the blanking period is 145 microseconds, which is the minimum required for the two-way transit from the transceiver to the outer surface of the acoustic housing. It is not advisable to reduce this value beyond the default setting, although it may be increased for larger boreholes at the rate of 1.5mm of one-way travel per microsecond.

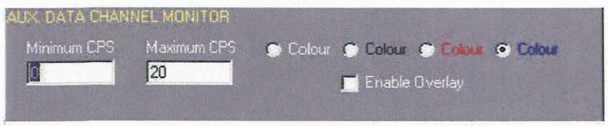
Window Length (sample time) defines the period during which the arrival gate remains open to detect the returned acoustic pulse. The acoustic pulse will travel in water at a speed of approximately 1.5mm per microsecond. The default window length is 150 microseconds, which is equivalent to 225 mm of (two-way) travel in the borehole fluid, or approximately 110mm of borehole diameter. If this is added to the default blanking period, which is equivalent to the outside diameter of the acoustic housing, it can be seen that the default set-up will be correct for boreholes up to 150mm. An error will be indicated if the sum of the blanking period and window length would be greater than 409 microseconds, which is the maximum range of the timer. Choose your window setting to best match the borehole diameter.

Pressing the 'View Travel time' button changes the display to that shown below:



The unhatched ring between the two cross hatched zones represents the sample window. The width of this ring will vary with window length value. The profile of a cylinder is represented here appearing as a circle in the sample window.

Pressing this button displays the following dialog box:



This box allows you to enable the Natural Gamma option by checking the 'Enable Overlay' check box. The Overlay appears as a trace upon the Amplitude plot. The trace range and color can also be set by this dialog. The level of filtering can also be altered (see section 8) (note that any displayed trace data is automatically aligned with the acoustic scan data but only when logging up. The Natural Gamma sensor occupies a higher position in the probe so sufficient data has to be prebuffered so that the acoustic data can depth aligned with gamma. The prebuffering results in a delay at the start of a log before correct gamma data appears this is normal.)

Data Analysis and Interpretation

RG-DIP, the manufacturer's image interpretation package, offers manual and automatic feature recognition options. Feature orientations (dip/strike and azimuth) are automatically calculated. Display options include stereographic projections of zone axes, orientation frequency plots and 'synthetic cores' for comparison with real core data. The last option is invaluable for orientating core samples, particularly in the case of incomplete recovery.

Reporting

The final report will include the objective and scope of the survey, location of the boreholes, discussion of instrumentation and procedures in the field and lab. For each borehole there will be a plot showing the dip/strike and azimuth of features. The next page shows an example.

Assumptions and limitations of the results will be discussed. Supporting references will be listed as necessary

Required Field Records

Field log for each borehole showing

a) Location and description of the borehole

b) Date of test

c) Field personnel

d) Instrumentation

e) Any deviations from test plan and action taken as a result

This procedure has been reviewed and approved by the undersigned:

Professional Geophysicist Antony Martin Date Feb 13. 2006

QA Review ________ Date Feb 13. 2006

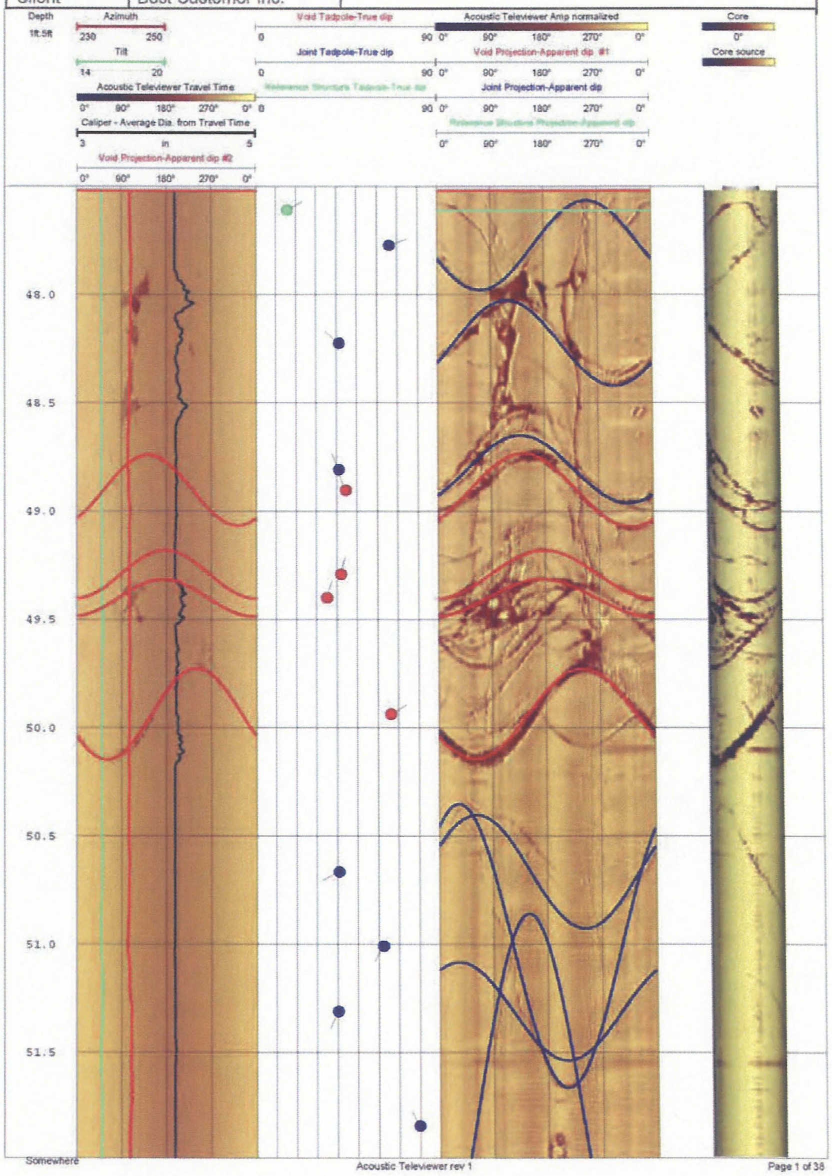
B-XXX	Company	Geovision Geophysical Services
	Location	Somewhere Dam

BH	B-XXX Acoustic Televiewer		
Date	7/8/05	BH Fluid	Air/Water
Casing	4" Steel to 15 ft		
File Name	BXXXdown1		
Depth Drilled	300 feet		
Depth Logged	299.3 feet		
Logged by	Rob Steller		
Client	Best Customer Inc.		

Notes:

1) All orientations referenced to True North

2) Tadpole tails indicate dip direction with True North as up.



Designation: D 5753 – 05

Standard Guide for Planning and Conducting Borehole Geophysical Logging[1]

This standard is issued under the fixed designation D 5753; the number immediately following the designation indicates the year of original adoption or, in the case of revision, the year of last revision. A number in parentheses indicates the year of last reapproval. A superscript epsilon (ε) indicates an editorial change since the last revision or reapproval.

1. Scope

1.1 This guide covers the documentation and general procedures necessary to plan and conduct a geophysical log program as commonly applied to geologic, engineering, ground-water, and environmental (hereafter referred to as geotechnical) investigations. It is not intended to describe the specific or standard procedures for running each type of geophysical log and is limited to measurements in a single borehole. It is anticipated that standard guides will be developed for specific methods subsequent to this guide.

1.2 Surface or shallow-depth nuclear gages for measuring water content or soil density (that is, those typically thought of as construction quality assurance devices), measurements while drilling (MWD), cone penetrometer tests, and logging for petroleum or minerals are excluded.

1.3 Borehole geophysical techniques yield direct and indirect measurements with depth of the (*1*) physical and chemical properties of the rock matrix and fluid around the borehole, (*2*) fluid contained in the borehole, and (*3*) construction of the borehole.

1.4 To obtain detailed information on operating methods, publications (for example, **2**, **5**, **7**, **18**, **24**, **29**, **34**, **35**, and **36**)[2] should be consulted. A limited amount of tutorial information is provided, but other publications listed herein, including a glossary of terms and general texts on the subject, should be consulted for more complete background information.

1.5 This guide provides an overview of the following: (*1*) the uses of single borehole geophysical methods, (*2*) general logging procedures, (*3*) documentation, (*4*) calibration, and (*5*) factors that can affect the quality of borehole geophysical logs and their subsequent interpretation. Log interpretation is very important, but specific methods are too diverse to be described in this guide.

1.6 Logging procedures must be adapted to meet the needs of a wide range of applications and stated in general terms so that flexibility or innovation are not suppressed.

1.7 *This standard does not purport to address all of the safety and liability concerns, if any, (for example, lost or lodged probes and radioactive sources[3]) associated with its use. It is the responsibility of the user of this standard to establish appropriate safety and health practices and determine the applicability of regulatory limitations prior to use.*

1.8 *This guide offers an organized collection of information or a series of options and does not recommend a specific course of action. This document cannot replace education or experience and should be used in conjunction with professional judgment. Not all aspects of this guide may be applicable in all circumstances. This ASTM standard is not intended to represent or replace the standard of care by which the adequacy of a given professional service must be judged, nor should this document be applied without consideration of a project's many unique aspects. The word "Standard" in the title of this document means only that the document has been approved through the ASTM consensus process.*

2. Referenced Documents

2.1 *ASTM Standards:* [4]

D 653 Terminology Relating to Soil, Rock, and Contained Fluids

D 5088 Practice for the Decontamination of Field Equipment Used at Non-Radioactive Waste Sites

D 5608 Practice for the Decontamination of Field Equipment Used at Low Level Radioactive Waste Sites

3. Terminology

3.1 Definitions—Definitions shall be in accordance with Terminology D 653.

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[1] This guide is under the jurisdiction of ASTM Committee D18 on Soil and Rock and is the direct responsibility of Subcommittee D18.01 on Surface and Subsurface Characteristics.

Current edition approved June 1, 2005. Published June 2005. Originally approved in 1995. Last previous edition approved in 1995 as D 5753–95.

[2] The boldface numbers in parentheses refer to the list of references at the end of this standard.

[3] The use of radioactive materials required for some log measurements is regulated by federal, state, and local agencies. Specific requirements and restrictions must be addressed prior to their use.

[4] For referenced ASTM standards, visit the ASTM website, www.astm.org, or contact ASTM Customer Service at service@astm.org. For *Annual Book of ASTM Standards* volume information, refer to the standard's Document Summary page on the ASTM website.

3.2 *Definitions of Terms Specific to This Standard:* Descriptions of Terms Specific to This Standard—Terms shall be in accordance with Ref (**1**).

4. Summary of Guide

4.1 This guide applies to borehole geophysical techniques that are commonly used in geotechnical investigations. This guide briefly describes the significance and use, apparatus, calibration and standardization, procedures and reports for planning and conducting borehole geophysical logging. These techniques are described briefly in Table 1 and their applications in Table 2.[5]

4.2 Many other logging techniques and applications are described in the textbooks in the reference list. There are a number of logging techniques with potential geotechnical applications that are either still in the developmental stage or have limited commercial availability. Some of these techniques and a reference on each are as follows: buried electrode direct current resistivity (**37**), deeply penetrating electromagnetic techniques (**38**), gravimeter (**39**), magnetic susceptibility (**40**), magnetometer, nuclear activation (**41**), dielectric constant (**42**), radar (**50**), deeply penetrating seismic (**39**), electrical polarizability (**45**), sequential fluid conductivity (**46**), and diameter (**48**). Many of the guidelines described in this guide also apply to the use of these newer techniques that are still in the research phase. Accepted practices should be followed at the present time for these techniques.

5. Significance and Use

5.1 An appropriately developed, documented, and executed guide is essential for the proper collection and application of borehole geophysical logs.

5.1.1 The benefits of its use include improving the following:

5.1.1.1 Selection of logging methods and equipment,

5.1.1.2 Log quality and reliability, and

5.1.1.3 Usefulness of the log data for subsequent display and interpretation.

5.1.2 This guide applies to commonly used logging methods (see Table 1 and Table 2) for geotechnical investigations.

5.1.3 It is essential that personnel (see 7.3.3) consult up-to-date textbooks and reports on each of the logging techniques, applications, and interpretation methods. A partial list of selected publications is given at the end of this guide.

5.1.4 This guide is not meant to describe the specific or standard procedures for running each type of geophysical log and is limited to measurements in a single borehole.

6. Apparatus

6.1 *Geophysical Logging System*, including probes, cable, draw works, depth measurement system, interfaces and surface controls, and digital and analog recording equipment.

6.1.1 Logging probes, also called sondes or tools, enclose the sensors, sources, electronics for transmitting and receiving signals, and power supplies.

6.1.2 Logging cable routinely carries signals to and from the logging probe and supports the weight of the probe.

6.1.3 The draw works move the logging cable and probe up and down the borehole and provide the connection with the interfaces and surface controls.

6.1.4 The depth measurement system provides probe depth information for the interfaces and surface controls and recording systems.

6.1.5 The surface interfaces and controls provide some or all of the following: electrical connection, signal conditioning, power, and data transmission between the recording system and probe.

6.1.6 The recording system includes the digital recorder and an analog display or hard copy device.

7. Calibration and Standardization of Geophysical Logs

7.1 *General*:

7.1.1 National Institute of Standards and Technology (NIST) calibration and operating procedures do not exist for the borehole geophysical logging industry. However, calibration or standardization physical models are available (see Appendix X1).

7.1.2 Geophysical logs can be used in a qualitative (for example, comparative) or quantitative manner, depending on the project objectives. (For example, a gamma-gamma log can be used to indicate that one rock is more or less dense than another, or it can be expressed in density units.)

7.1.3 The calibration and standardization scope and frequency shall be sufficient for project objectives.

7.1.3.1 Calibration or standardization should be performed each time a logging probe is modified or repaired or at periodic intervals.

7.2 *Calibration*:

7.2.1 Calibration is the process of establishing values for log response. It can be accomplished with a representative physical model or laboratory analysis of representative samples. Calibration data values related to the physical properties (for example, porosity) may be recorded in units (for example, pulses/s or µm/ft) that can be converted to apparent porosity units.

7.2.1.1 At least three, and preferably more, values are needed to establish a calibration curve, and the interface or contact between different values in the model should be recorded. Because of the variability in subsurface conditions, many more values are needed if sample analyses are used for calibration.

7.2.1.2 The statistical scatter in regression of core analysis against geophysical log values may be caused by the difference between the sample size and geophysical volume of investigation and may not represent measurement error.

7.2.2 *Physical Models*—A representative model simulates the chemical and physical composition of the rock and fluids to be measured.

7.2.2.1 Physical models include calibration pits, coils, resistors, rings, temperature baths, etc.

7.2.2.2 The calibration of nuclear probes should be performed in a physical model that is nearly infinite with respect to probe response.

[5] The references indicated in these tables should be consulted for detailed information on each of these techniques and applications.

TABLE 1 Common Geophysical Logs

Type of Log (References)	Varieties and Related Techniques	Properties Measured	Required Hole Conditions	Other Limitations	Typical Measuring Units and Calibration or Standardization	Brief Probe Description
Spontaneous potential (**7, 8, 12**)	differential	electric potential caused by salinity differences in borehole and interstitial fluids, streaming potentials	uncased hole filled with conductive fluid	salinity difference needed between borehole fluid and interstitial fluids; needs correction for other than NaCl fluids	mV; calibrated power supply	records natural voltages between electrode in well and another at surface
Single-point resistance (**7**)	conventional, differential	resistance of rock, saturating fluid, and borehole fluid	uncased hole filled with conductive fluid	not quantitative; hole diameter effects are significant	Ω; V-Ω meter	constant current applied across lead electrode in well and another at surface of well
Multi-electrode resistivity (**7, 8, 13**)	various normal focused, guard, lateral arrays	resistivity and saturating fluids	uncased hole filled with conductive fluid	reverses or provides incorrect values and thickness in thin beds	Ω-m; resistors across electrodes	current and potential electrodes in probe and remote current and potential electrodes
Induction (**10, 11**)	various coil spacings	conductivity or resistivity of rock and saturating fluids	uncased hole or nonconductive casing; air or fluid filled	not suitable for high resistivities	mS or Ω-m; standard dry air zero check or conductive ring	transmitting coil(s) induce eddy currents in formation; receiving coil(s) measures induced voltage from secondary magnetic field
Gamma (**5, 7, 22**)	gamma spectral (**44**)	gamma radiation from natural or artificial radioisotopes	any hole conditions	may be problem with very large hole, or several strings of casing and cement	pulses per second or API units; gamma source	scintillation crystal and photomultiplier tube measure gamma radiation
Gamma-gamma (**23, 24**)	compensated (dual detector)	electron density	optimum results in uncased hole; can be calibrated for casing	severe hole-diameter effects; difficulty measuring formation density through casing or drill stem	gs/cm^3; Al, Mg, or Lucite blocks	scintillation crystal(s) shielded from radioactive source measure Compton scattered gamma
Neutron (**7, 14, 25**)	epithermal, thermal, compensated sidewall, activation, pulsed	hydrogen content	optimum results in uncased hole; can be calibrated for casing	hole diameter and chemical effects	pulses/s or API units; calibration pit or plastic sleeve	crystal(s) or gas-filled tube(s) shielded from radioactive neutron source
Acoustic velocity (**5, 26, 27**)	compensated, waveform, cement bond	compressional wave velocity or transit time, or compressional wave amplitude	fluid filled, uncased, except cement bond	does not detect secondary porosity; cement bond and wave form require expert analysis	velocity units, for example, ft/s or m/s or µs/ft; steel pipe	1 or more transmitters and 2 or more receivers
Acoustic televiewer (**28, 7**)	acoustic caliper	acoustic reflectivity of borehole wall	fluid filled, 3 to 16-in. diameter; problems in deviated holes	heavy mud or mud cake attenuate signal; very slow logging speed	orientated image-magnetometer must be checked	rotating transducer sends and receives high-frequency pulses
Borehole video	axial or side view (radial)	visual image on tape	air or clean water; clean borehole wall	may need special cable	NA[A]	video camera and light source
Caliper (**29, 7**)	oriented, 4-arm high-resolution, *x-y* or max-min bow spring	borehole or casing diameter	any conditions	deviated holes limit some types; significant resolution difference between tools	distance units, for example, in.; jig with holes or rings	1 to 4 retractable arms contact borehole wall
Temperature (**30, 31, 32**)	differential	temperature of fluid near sensor	fluid filled	large variation in accuracy and resolution of tools	°C or °F; ice bath or constant temperature bath	thermistor or solid-state sensor
Fluid conductivity (**7**)	fluid resistivity	most measure resistivity of fluid in hole	fluid filled	accuracy varies, requires temperature correction	µS/cm or Ω-m; conductivity cell	ring electrodes in a tube
Flow (**12, 33, 7**)	impellers, heat pulse	vertical velocity of fluid column	fluid filled	impellers require higher velocities. Needs to be centralized.	velocity units, for example, ft/min; lab flow column or log in casing	rotating impellers; thermistors detect heated water; other sensors measure tagged fluid.
Deviation (**4, 7, 47**)	magnetic, gyroscopic, or mechanical	horizontal and vertical displacement of borehole	any conditions (see limitations)	magnetic methods orientation not valid in steel casing	degrees and depth units; orientation and inclination must be checked	various techniques to measure inclination and bearing of borehole

[A] NA = not applicable.

TABLE 2 Log Selection Chart for Geotechnical Applications Using Common Geophysical Logs[A]

Information Desired	Acoustic: Acoustic Televiewer	Acoustic: Acoustic Velocity, Δt, CBL, VDL, FWS	Electric and Induction: Induced Polarization	Electric and Induction: Multi-electrode Resistivity, Normal, Lateral, Micro Guard Resistivity	Electric and Induction: Single-Point Resistance	Electric and Induction: Spontaneous Potential	Electric and Induction: Induction (Conductivity)	Fluid Logs: Flow Meter	Fluid Logs: Fluid Resistivity	Fluid Logs: Fluid Sampler	Fluid Logs: Temperature, Differential Temperature	Radioactive or Nuclear: Gamma-Gamma Density	Radioactive or Nuclear: Gamma	Radioactive or Nuclear: Neutron	Radioactive or Nuclear: Spectral Gamma	Other Methods: Borehole Video	Other Methods: Caliper	Other Methods: Casing Collar Locator	Other Methods: Deviation
Lithology and Correlation																			
Bed/aquifer thickness; correlation, structure	•	•		•	•	•	★					Δ	√	Δ	√	◇	√		
Lithology—depositional environment	?	•		•	•	•	★					Δ	√	Δ	√	◇	√		
Shale or clay content			•	•		•	★					Δ	√	Δ	√				
Bulk density												Δ							
Formation resistivity				•			★												
Injection/production profiles				?			?	□	□		□	Δ		Δ					
Permeability estimates		•						□	□		□		√						
Porosity (amount and type)	•	•		•			★					Δ		Δ					
Mineral identification			•									Δ			√				
Potassium-uranium thorium content (KUT)															√				
Rock Structure																			
Strike and dip of bedding	•															◇			√
Fracture detection (number of fractures), RQD	•	•		•	•											◇	√		
Fracture orientation and character	•															◇			√
Thin bed resolution	•			?	•											◇	√		
Fluid Parameters																			
Borehole fluid characteristics								?	□	□	□								
Fluid flow						•		□	□		□					◇			
Formation water quality				•		•	★			□									
Moisture content—water saturation				?			?					Δ		Δ					
Temperature		?									□								
Water level and water table	•	•		•	•	•	?		□		□	Δ		Δ		◇			
Borehole Parameters																			
Casing evaluation integrity, leaks, damage, screen location	■	■					?	■			■					◆	√	†	
Deviation of borehole																			√
Diameter of borehole	•																√		
Examination behind casing		•					★					Δ		Δ					
Location of debris in wells	•															◆	√	√	
Well completion evaluation, for example, cement bond, seal location, grout location	?	■					★					Δ	√	Δ					

[A] Required hole conditions: ■ = cased fluid-filled hole, ◆ = clear fluid or dry cased hole, □ = screened or open fluid-filled hole, ◇ = clear fluid or dry open hole, † = steel casing only, Δ = active nuclear log to be run in stable holes, ★ = open or nonconductive cased holes, dry or fluid filled, √ = no restrictions, • = open fluid-filled hole only, and ? = possible applications.

7.2.2.3 Some probes have internal devices such as resistors, but this does not substitute for checking the probe response in an environment that simulates borehole conditions, and the use of such devices is considered standardization.

7.2.2.4 *Calibration Facilities*—Commonly used calibration pits or models for use by anyone at the present time are listed in Appendix X1 (14-18). The user should inquire concerning the present validity of any facility.

7.2.3 *Sample Analyses*:

7.2.3.1 Representative samples from boreholes in the project area that have been collected carefully and analyzed quantitatively also may be used to calibrate log response.

7.2.3.2 To reduce depth errors, the sample recovery of rock cores in calibration holes needs to approach 100 % for the intervals used for calibration. Log response should be used to select sample depths to span the range of desired log calibration values and to be within thick units to minimize the effects of potential depth errors. Samples need to be analyzed immediately or steps taken to preserve them for later analysis.

7.2.3.3 Samples to be used for log calibration should be analyzed only from depth intervals at which the log response is relatively uniform for a depth interval considerably greater than the vertical dimension of the volume of investigation of the logging probe. Samples near lithologic contacts or fluid interfaces should not be used because of possible boundary effects or depth errors.

7.3 *Standardization*:

7.3.1 Standardization is the process of checking the log response to reveal evidence of repeatability and consistency.

7.3.2 Standardization is needed to establish comparability between logs made with different equipment or at different times and to ensure the accuracy of measurements.

7.3.2.1 Standardization checks should include at least two different measurement values approximating the range of interest (For example, aluminum and magnesium or plastic blocks are used commonly to check the response of gamma-gamma density logging systems in the field.)

7.3.3 Standardization uses some type of a standard that may be used in the field or laboratory and repeat logs.

7.3.3.1 Log response needs to be checked using field standards often enough to satisfy the project objectives. Standardization of the log response provides the basis for correcting for changes (for example, changes in output with time due to system drift or changes of equipment).

7.3.3.2 Selected log intervals should be repeated (that is, re-logged). Repeat logs provide information on the stability of logging equipment.

7.3.3.3 A representative borehole may be used to check log response periodically. This borehole environment and the rocks and fluids penetrated may change with time.

8. Procedure

8.1 *Planning the Logging Program*:

8.1.1 A work plan should be developed prior to implementing the logging program.

8.1.2 The key steps in developing a logging work plan should include the following:

8.1.2.1 *Log Selection*—See Table 1 and Table 2.

8.1.2.2 *Personnel Selection*—See 8.3.2.

8.1.2.3 *Quality Control and Documentation*—See 8.4.

8.1.2.4 *Calibration and Standardization Procedures*—See Section 7.

8.1.2.5 *Equipment Liability*—See 1.7.

8.1.2.6 *Equipment Decontamination*—In environmental investigations, equipment decontamination may be required before, after, and between individual wells. Equipment decontamination may involve a number of standardized procedures, depending on the nature of the project (see Practices D 5088 and D 5608). A decontamination program should be agreed upon by all parties before logging commences, and procedures specified by the work plan should be followed.[6]

8.1.2.7 *Log Interpretation*—See 8.5.

8.2 *Field Assessment of Borehole Conditions*:

8.2.1 Borehole conditions can have a profound influence on the quality of log data and subsequent interpretation. Important parameters to consider include the following:

8.2.1.1 Drilling method, casing, drill hole history, and well completion materials.

8.2.1.2 *Borehole Fluid Properties*—Resistivity, temperature, density, viscosity, and chemistry at the time of logging.

8.2.1.3 Borehole diameter, rugosity, and stability.

8.2.1.4 Deviation of borehole.

8.2.1.5 Wellhead pressure.

8.2.2 *Logging Operations*:

8.2.2.1 Determine the sequence and direction of logging. The sequence in which a suite of logs is run is important from both a data quality and operational viewpoint. Because logging operations mix the borehole fluid, logs of fluid properties (for example, temperature, fluid resistivity, and fluid sampling should be run prior to other logs). Consideration should also be given to when borehole video surveys are performed because some logging tools may degrade borehole clarity. Tools that have arms or bowsprings that contact the borehole wall should be run late in the logging sequence because of the greater possibility of material from the borehole wall falling into the borehole. Because of the consequences of losing a tool with a radioactive source, these tools should be run last, and after a caliper log. Unstable boreholes should not be logged with radioactive source probes. All logs except fluid properties and video should be run with the probe moving up the borehole to reduce depth errors.

8.2.2.2 Select the depth reference. The selected depth reference needs to be stable and accessible.

8.2.2.3 Select horizontal and vertical scales.

8.2.2.4 Select the digitizing interval. See 8.3.1.2.

8.3 *Other Considerations*:

8.3.1 *Data Formats*—There are two methods of recording log data, digital and analog. Digital recording of logs should be used because of the numerous benefits of data manipulation. Digital recording is not yet practical for some logs such as video or acoustic televiewer.

8.3.1.1 An analog display should be available to be viewed in the field to verify the correct tool operation. Depth scales and units of measurement for the horizontal scale must be indicated clearly on each log.

8.3.1.2 The digital data are recorded at an operator-selected depth interval that should be as small as possible, at most, half the thickness of the smallest rock unit that can be resolved. The time interval for digital samples can also be selected by the operator. ASCII is the recommended format except for such logs as spectral gamma, full waveform sonic, borehole video, and acoustic televiewer. The digital file header should include all of the necessary information to reconstruct the logging

[6] Equipment decontamination procedures may have specific safety and equipment limitations that must be addressed prior to their use.

procedures accurately and should duplicate the information included in the written header of the log.

8.3.1.3 Unprocessed data should be available. Nonproprietary processing algorithms shall be furnished if processed data is provided.

8.3.2 *Personnel*:

8.3.2.1 Personnel not having specialized training or experience should be cautious about using borehole geophysics and should solicit assistance from qualified practitioners or attend courses on borehole geophysics.

8.3.2.2 Personnel operating logging equipment should have an understanding of the theory, field procedures, and methods of log interpretation.

8.3.2.3 A geoscientist, with experience in borehole geophysics, who understands the project objectives and local geohydrology may need to be available to examine logging results during logging operations when consistent with objectives of the program. This geoscientist is responsible for determining whether the instructions selected in the pre-logging conference are being followed and whether changes should be made.

8.3.2.4 Log interpretation should be performed by a geoscientist with experience in borehole geophysics and knowledge of the site geology and hydrology.

8.4 *Field Documentation*—A documentation plan for both the analog plot and digital data file should be established and become part of the work plan. Documentation of the following procedures is needed: calibration of logging probes, field operation of geophysical logging equipment, applicable decontamination, and format for presenting geophysical well log data. Repair, standardization, and calibration information should also be documented. Probes should be numbered to simplify the identification of associated documentation. Document all field problems including equipment malfunctions. This should include the steps taken to solve the problem and how the logs might have been affected. Repeat runs and field standardization should be more frequent when equipment problems occur. The use of one borehole on the project to check the probe response may aid in the identification of equipment or other problems. Probes should be recalibrated in a physical model after major repairs have been made.

8.4.1 *Log Headings (Headers)*—The log heading should contain all of the information that is necessary to analyze the log trace. Because auxiliary documents are frequently unavailable to other users of the log, all of the critical information concerning the log should be included on the final log heading. The header information should also be included in the same computer file as the log data. The following items listed are necessary and should be included on the log headings and computer files when appropriate. If information is not available or applicable, it should be noted on the heading. The following information should be included:

8.4.1.1 *Background Well Information*:

Owner of well and address, location of well (UTM coordinates, ¼ section, etc.); date; logging contractor and address; logging operator; drilling contractor and address; client and address; observer and address; elevation of top casing and distance above ground; and drilling history, methods etc.

8.4.1.2 *Borehole Conditions*:

Casing description; description of log depth datum; elevation of log depth datum; type of drilling fluid; resistivity and temperature of borehole fluid; depth of origin of borehole fluid samples; fluid level; time since last mud circulation; bottom hole temperature; and problems and unusual conditions.

8.4.1.3 *Equipment Data and Logging Parameters*:

Description of probe reference point; model and manufacturer of logging tools; logging company tool number; date and type of last calibration; date, type, and response of field standardization; top and bottom of logged interval; logging speed and direction; vertical depth error after logging; time constant or the time interval of digital samples; identification of disk containing digitized logs; and equipment problems.

8.4.1.4 *Specific Information for Nuclear Logging Probes*:

Source description, initial source strength, and date determined; source to detector or receiver spacing; detector description; and data filtering or enhancement parameters.

8.4.1.5 *Specific Information for Acoustic and Electric Logging Probes*:

source or transmitter description and signal output; source or transmitter to detector or receiver spacing; detector or receiver description; and data filtering or enhancement parameters.

8.4.2 *Quality Control During Logging Operations*:

request changes in logging speed and time constant; repeat logs or log intervals based on field log analysis; check depth readout against log; note errors or changes on the log; and verify documentation listed above.

8.5 *Log Interpretation*—The full potential of a logging program cannot be realized until the logging measurements are interpreted. Log interpretation should start at the time of data acquisition and should continue as an iterative process throughout the project.

8.5.1 Logs should be analyzed and described as a suite and combined with information on lithology and fluid quality because of the synergistic nature of log data. The nonunique response of logs dictates the use of data from other sources to check the log interpretation, and this background data must be included in the report. A computer will be used in most cases to aid analysis of the logs, and information on the software and algorithms used should be included in the report.

8.5.2 Important interpretation steps include the following:

8.5.2.1 Establishing database (for example, format conversion, depth corrections, editing, and filtering).

8.5.2.2 Applying borehole corrections (for example, correct electric logs for borehole diameter and fluid resistivity).

8.5.2.3 Performing initial data inversion-conversion log units to values appropriate for investigation (for example, density units to porosity).

8.5.2.4 Performing large-scale data inversion (for example, cross sections, regional correlation, and model parameters).

9. Report

9.1 Depending on the project objective, report only data or data and interpretations.

9.1.1 Both types of reports should include the following:

9.1.1.1 Objectives and scope.

9.1.1.2 Field Documentation (for example, site conditions, borehole conditions, data collection procedures, calibration and standardization of logging probes, field operation of geophysical logging equipment, and format for recording geophysical log data, including any filtering or processing of the data, problems, and unusual conditions; see 8.4).

9.1.1.3 Both the digital log data and log plots.

9.1.1.4 Abstract, executive summary, or conclusions.

9.1.2 Interpretation reports should include the following:

9.1.2.1 Log composites (for example, summary plots showing logs, lithology, well construction, and water quality zones). These composites are commonly annotated to indicate the features of interest and correlated with lithologic descriptions.

9.1.2.2 Brief description of the geologic and hydrologic setting.

9.1.2.3 Specific information on log analysis, that is, depth corrections and recalibration of logs, physical models or sample analyses that were used for calibration, methods of log interpretation, software used, and copies of cross-plots or other plots of data resulting from log analysis.

9.1.2.4 Well-to-well correlation sections and comparison to surface geophysical and other testing data, when available.

10. Keywords

10.1 acoustic logging; acoustic televiewer; borehole geophysics; borehole video; caliper logging; chemical properties and physical properties; deviation; electric logging; environmental; fluid conductivity/resistivity logging; fluid logging; gamma logging; gamma-gamma logging; geology; geophysics; geotechnical; ground water; hydrology; induction logging; log calibration and standardization; log headings; neutron logging; nuclear logging; resistivity logging; singlepoint resistance logging; spontaneous potential logging; temperature logging; well logging

APPENDIX

(Nonmandatory Information)

X1. CALIBRATION FACILITIES AVAILABLE FOR PUBLIC USE (1989)

X1.1 *Name and Location*—American Petroleum Institute Calibration Facility, University of Houston, Houston, TX: four pits (**14**, **19**, **20**).

X1.2 *Who to Contact:* University of Houston, Cullen College of Engineering, (713) 749-3423.

X1.3 *Probes That Can Be Calibrated*—Pit 1: neutron and gamma-gamma; Pit 2: gamma (simulated shale); Pits 3 and 4: spectral gamma.

X1.3.1 *Name and Location*—U.S. Department of Energy, Grand Junction, CO: 20 models or pits (**18**).

X1.3.2 *Who to Contact*—U.S. Department of Energy, Grand Junction Operations Office, or the prime contractor at the U.S. Department of Energy office, (303) 248-7768 or 6702.

X1.4 *Probes That Can Be Calibrated*—Gamma, gamma spectral, neutron, gamma-gamma, and magnetic susceptibility. Also, wet and dry borehole size factors and a 300-ft borehole with radium foil at known depths for check of depth measurements.

X1.4.1 *Name and Location*—U.S. Bureau of Mines density pits Pit 1: six holes and magnetic susceptibility (Pits 2). Denver Federal Center, Lakewood, CO: Pit six holes; Pit 2: three holes (**17**).

X1.4.2 *Who to Contact*—U.S. Geological Survey, Water Resources Division, Borehole Geophysics Project, Building 25, Denver Federal Center, (303) 236-5913.

X1.5 *Probes That Can Be Calibrated*—Pit 1: gamma-gamma, acoustic, resistivity; and Pit 2: magnetic susceptibility.

X1.5.1 *Name and Location*—U.S. Department of Energy, Fractured igneous rock calibration models, Denver Federal Center, Lakewood, CO: Three models or pits (**16**).

X1.5.2 *Who to Contact*—U.S. Geological Survey, Water Resources Division, Borehole Geophysics Project, Building 25, Denver Federal Center, (303) 236-5913.

X1.6 *Probes That Can Be Calibrated*—Fracture detection probes, neutron, gamma-gamma, short-spaced resistivity, and acoustic velocity.

X1.7 *Other Facilities*—The Geological Survey of Canada is developing a system of deep test holes and calibration facilities that are presently available at several locations in Canada. Gamma, gamma spectral, and coal property models are completed, and other physical property models are under construction (**15**). Calibration facilities at universities, private logging companies, and government agencies may also be available at other locations for use by outside logging groups.

REFERENCES

The following is a partial list of references intended to provide basic information on the various logging methods. There are many more pertinent references, but they are too numerous for listing in this guide **(34, 36, 51)**.

(1) *Glossary of Terms and Expressions Used in Well Logging*, 2nd Ed., Society of Professional Well Log Analysts, Houston, TX, 1984, p. 74.

(2) Bateman, R. M., *Log Quality Control*, IHRDC, Boston, MA, 1985, p. 398.

(3) Doveton, J. H., *Log Analysis of Subsurface Geology—Concepts and Computer Methods*, John Wiley and Sons, Inc., New York, NY, 1986, p. 273.

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Designation: D 6167 – 97 (Reapproved 2004)

Standard Guide for Conducting Borehole Geophysical Logging: Mechanical Caliper[1]

This standard is issued under the fixed designation D 6167; the number immediately following the designation indicates the year of original adoption or, in the case of revision, the year of last revision. A number in parentheses indicates the year of last reapproval. A superscript epsilon (ε) indicates an editorial change since the last revision or reapproval.

1. Scope

1.1 This guide covers the general procedures necessary to conduct caliper logging of boreholes, wells, access tubes, caissons, or shafts (hereafter referred as boreholes) as commonly applied to geologic, engineering, ground-water, and environmental (hereafter referred as geotechnical) investigations. Caliper logging for mineral or petroleum exploration and development are excluded.

1.2 This guide defines a caliper log as a record of borehole diameter with depth.

1.2.1 Caliper logs are essential in the interpretation of geophysical logs since they can be significantly affected by borehole diameter.

1.2.2 Caliper logs are commonly used to measure borehole diameter, shape, roughness, and stability; calculate borehole volume; provide information on borehole construction; and delineate lithologic contacts, fractures, and solution cavities and other openings.

1.3 This guide is restricted to mechanically based devices with spring-loaded arms, which are the most common calipers used in caliper logging with geotechnical applications.

1.4 This guide provides an overview of caliper logging, including general procedures, specific documentation, calibration and standardization, and log quality and interpretation.

1.5 To obtain additional information on caliper logs see Section 9 of this guide.

1.6 This guide is to be used in conjunction with Guide D 5753.

1.7 This guide should not be used as a sole criterion for caliper logging and does not replace professional judgement. Caliper logging procedures should be adapted to meet the needs of a range of applications and stated in general terms so that flexibility or innovation is not suppressed.

1.8 The geotechnical industry uses English or SI units. The caliper log is typically recorded in units of inches, millimetres, or centimetres.

1.9 *This guide does not purport to address all of the safety and liability problems (for example, lost or lodged probes and equipment decontamination) associated with its use.*

1.10 *This standard does not purport to address all of the safety concerns, if any, associated with its use. It is the responsibility of the user of this standard to establish appropriate safety and health practices and determine the applicability of regulatory limitations prior to use.*

2. Referenced Documents

2.1 *ASTM Standards:* [2]

D 653 Terminology Relating to Soil, Rock and Contained Fluids

D 5088 Practice for Decontamination of Field Equipment Used at Nonradioactive Waste Sites

D 5608 Practice for Decontamination of Field Equipment Used at Low Level Radioactive Waste Sites

D 5753 Guide for Planning and Conducting Borehole Geophysical Logging

3. Terminology

3.1 *Definitions:* Definitions shall be in accordance with Terminology D 653, Section 12, Ref **(1)**,[3] or as defined below:

3.1.1 *accuracy, n*—how close a measured log values approaches true value. It is determined in a controlled environment. A controlled environment represents a homogeneous sample volume with known properties.

3.1.2 *depth of investigation, n*—the radial distance from the measurement point to a point where the predominant measured response may be considered centered, that is not to be confused with borehole depth (for example, distance) measured from the surface.

3.1.3 *measurement resolution, n*—the minimum change in measured value that can be detected.

[1] This guide is under the jurisdiction of ASTM Committee D18 on Soil and Rock and is the direct responsibility of Subcommittee D18.01 on Surface and Subsurface Characterization.

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[2] For referenced ASTM standards, visit the ASTM website, www.astm.org, or contact ASTM Customer Service at service@astm.org. For *Annual Book of ASTM Standards* volume information, refer to the standard's Document Summary page on the ASTM website.

[3] The boldface numbers given in parentheses refer to a list of references at the end of the text.

3.1.4 *repeatability, n*—the difference in magnitude of two measurements with the same equipment and in the same environment.

3.1.5 *vertical resolution, n*—the minimum thickness that can be separated into distinct units.

3.1.6 *volume of investigation, n*—the volume that contributes 90 % of the measured response. It is determined by a combination of theoretical and empirical modeling. The volume of investigation is non-spherical and has gradational boundaries.

4. Summary of Guide

4.1 This guide applies to borehole caliper logging and is to be used in conjunction with Guide D 5753.

4.2 This guide briefly describes the significance and use, apparatus, calibration and standardization, procedures, and reports for conducting borehole caliper logging.

5. Significance and Use

5.1 An appropriately developed, documented, and executed guide is essential for the proper collection and application of caliper logs. This guide is to be used in conjunction with Guide D 5753.

5.2 The benefits of its use include the following: improving selection of caliper logging methods and equipment, caliper log quality and reliability, and usefulness of the caliper log data for subsequent display and interpretation.

5.3 This guide applies to commonly used caliper logging methods for geotechnical applications.

5.4 It is essential that personnel (see the Personnel section of Guide D 5753) consult up-to-date textbooks and reports on the caliper technique, application, and interpretation methods.

6. Interferences

6.1 Most extraneous effects on caliper logs are caused by instrument problems and borehole conditions.

6.2 Instrument problems include the following: electrical leakage of cable and grounding problems, temperature drift, wear of mechanical components including the hinge pins and in the linear potentiometer (mechanical hysteresis), damaged or bent arms, and lack of lubrication of the mechanical components.

6.3 Borehole conditions include heavy drilling mud, borehole deviation, and drilling-related borehole irregularities.

7. Apparatus

7.1 A geophysical logging system has been described in the general guide (see the Apparatus section of Guide D 5753).

7.2 Caliper logs may be obtained with probes having a single arm, three arms (averaging or summation), multiple independent arms (x-y caliper), multiple-feeler arms, bow springs, or gap wheels. Single-arm and three-arm averaging probes are most commonly used for geotechnical investigations.

7.2.1 A single-arm caliper commonly provides a record of borehole diameter while being used to decentralize another type of log, such as a side-collimated gamma-gamma probe (see Fig. 1). The caliper arm generally follows the high side of a deviated hole. The single-arm decentralizing caliper may not have the resolution needed for some applications.

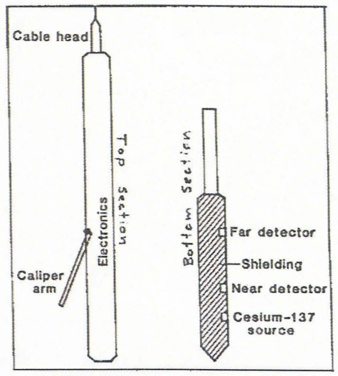

FIG. 1 Probe for Making Side-Collimated Gamma-Gamma Logs with Single-Arm Caliper (2)

7.2.2 The three-arm averaging or summation caliper has arms of equal length oriented 120° apart (see Fig. 2). All arms move together, which provides an average diameter measurement. This caliper provides higher resolution than the single-arm caliper measurement (see Fig. 3).

7.2.3 Multiple independent arm calipers generally have three or four independent arms of equal length; these arms are sometimes oriented. Horizontal resolution, that provides accurate borehole-diameter measurement regardless of borehole shape, is related to the number of independent arms. In general, calipers with four or more independent arms will have higher resolution than three-arm averaging (see Fig. 3). The four independent-arm caliper log may show borehole elongation (elliptical borehole shape) and better indicates the actual irregularity of the borehole.

7.3 Caliper probes using arms are typically spring loaded. The arms are retracted and opened with an electric motor and

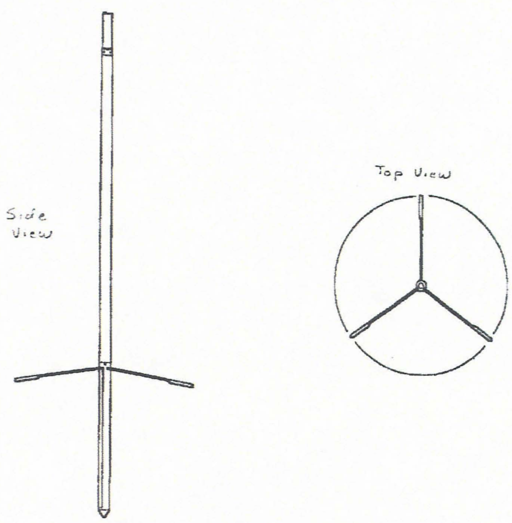

FIG. 2 Three-Arm Averaging Caliper

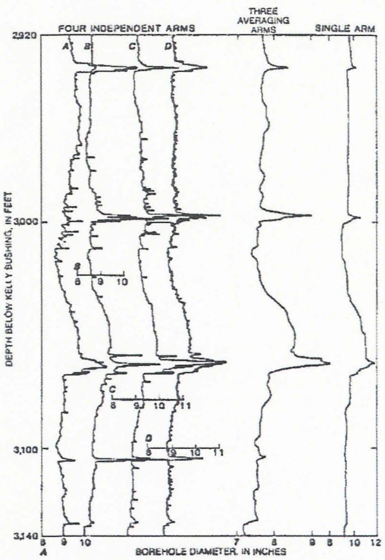

FIG. 3 Caliper Logs From Probes Having Four Independent Arms, Three Averaging Arms, and a Single Arm, Madison Limestone Test Well 1, Wyoming (2)

retention spring. The arms and gears are lubricated. Caliper probes closed by hand are held closed with an electric solenoid or weighted retention ring that is released with a sudden drop. Typically, the caliper arms are mechanically connected to a linear or rotary potentiometer such that changes in the angle of the arms causes changes in resistance. These changes in resistance are proportional to average borehole diameter. In some probes, the voltage changes are converted to a varying pulse rate or digitized downhole to eliminate or minimize cable transmission noise. Different arm length can be used to optimize sensitivity for the borehole-diameter range expected.

7.4 The concepts of volume of investigation and depth of investigation are not applicable to caliper logs since it is a surface-contact measurement.

7.5 Vertical resolution of caliper measurements is a function of the size of the contact surface (arm tip or pad), the response of the mechanical and electronic components, and digitizing interval used. The theoretical limit of vertical resolution is equal to the width of the caliper pad or tip. Selection of arm lengths and angle, and tip diameter will affect sensitivity. Shorter arms generally will provide more detail of the rugosity (borehole roughness as defined by Ref. **(2)**) of the borehole wall than longer arms. However, size of caliper probe and borehole diameter may also determine arm lengths used.

7.6 Measurement resolution of typical caliper probes is 0.05 in. (0.13 cm) of borehole diameter.

7.7 A variety of caliper logging equipment is available for geotechnical investigations. It is not practical to list all of the sources of potentially acceptable equipment.

8. Calibration and Standardization of Caliper Logs

8.1 *General:*

8.1.1 National Institute of Standards and Technology (NIST) calibration and standardization procedures do not exist for caliper logging.

8.1.2 Caliper logs can be used in a qualitative (for example, comparative) or quantitative (for example, borehole diameter corrections) manner depending upon the project objectives.

8.1.3 Caliper calibration methods and frequency shall be sufficient to meet project objectives.

8.1.3.1 Calibration and standardization should be performed each time a caliper probe is suspected to be damaged, modified, repaired, and at periodic intervals.

8.2 Calibration is the process of establishing values for caliper response and is accomplished with a physical model of a known diameter. Calibration data values related to the physical properties (for example, borehole diameter, roughness) may be recorded in units (for example, counts per second), that can be converted to units of length (for example, inches, millimetres, or centimetres.)

8.2.1 At least two, and preferably more, values, which approximate the anticipated operating range, are needed to establish a calibration curve (for example, 4- and 10-in. (10.2- and 25.4-cm) rings) if the borehole diameter to be logged is 5 in. (12.7 cm)).

8.2.2 Physical models of measured diameter that may be used to calibrate the caliper response may include rings or bars made of rigid materials that are not easily deformed and resist wear.

8.2.2.1 Calibration of caliper probes is done most accurately in rings of different diameters.

8.2.2.2 A calibration bar is a plate that is drilled and marked at regular intervals and machined to fit over the body of the probe (see Fig. 4). One arm is placed in the appropriate hole for the range to be logged.

8.2.2.3 Calibration can be checked by using casing of measured diameter logged in the borehole.

8.3 Standardization is the process of checking logging response to show evidence of repeatability and consistency.

8.3.1 Calibration serves as a check of standardization.

8.3.2 A representative borehole may be used to periodically check caliper response providing the borehole environment does not change with time. Caliper response may not repeat exactly because the probe may rotate, causing the arms to follow slightly different paths within the borehole.

9. Procedure

9.1 See the Procedure section of Guide D 5753 for planning a logging program, data formats, personnel qualifications, field documentation, and header documentation.

9.2 Caliper specific information (for example, arm length) should be documented.

9.3 Identify caliper logging objectives.

9.4 Select appropriate equipment to meet objectives.

9.4.1 Caliper equipment decontamination is addressed according to project specifications (see Practice D 5088 for non-radioactive waste sites and Practice D 5608 for low level radioactive waste sites). Some materials commonly used for caliper-arm lubrication may be environmentally sensitive.

9.5 Select the order in the logging sequence in which the caliper probe is to be run (see 8.2.2.1 of Guide D 5753).

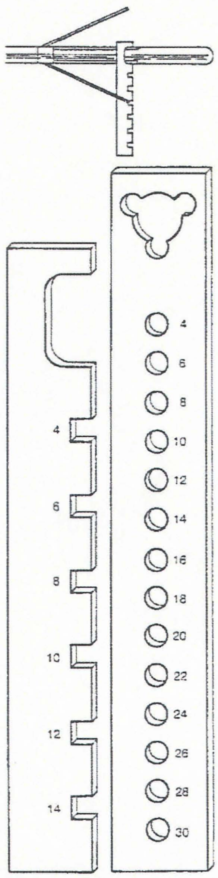

FIG. 4 Calibration Bars for Caliper Probes (3)

9.5.1 Caliper probes are run before any probe utilizing nuclear sources and more expensive centralized probes.

9.5.2 Caliper probes are run after any television camera and fluid property probes are run.

9.6 Caliper operation and calibration are checked at the start of each borehole or at an interval consistent with project objectives. (see the Procedure section of Guide D 5753). After calibration, the caliper arms are closed before lowering.

9.7 Select and document the depth reference.

9.7.1 The selected depth reference needs to be stable and accessible (for example, top of borehole casing).

9.8 Determine and document probe zero reference point (for example, top of probe or cablehead) and depth offset to caliper measurement point.

9.8.1 The measurement point of a caliper is the end of caliper arms and it changes as the arms open and close with the sine of arm angle multiplied by length of arm. Typically, the measurement point varies less than a few tenths of a foot (a few centimetres).

9.8.2 The measurement point will change if the arm length is changed.

9.9 Select horizontal and vertical scales for log display.

9.10 Select digitizing interval (or sample rate if applicable) to meet project objectives (see 8.3.1.2 of Guide D 5753).

9.10.1 Maximum vertical resolution requires the selection of a digitizing interval at least as small as the arm tip contact height.

9.10.2 Typically, this interval is no larger than 0.1 ft (0.03 m) for high-resolution applications.

9.11 The caliper probe is lowered to the bottom of the borehole.

9.11.1 Any time the caliper probe is lowered in the borehole, the arms should be closed to avoid damaging equipment or borehole.

9.11.2 Selection of probe speed while lowering is based on knowledge of borehole depth, stability, and other conditions.

9.12 Open caliper arm(s).

9.13 Select logging speed.

9.13.1 A logging speed of approximately 15 ft (5 m) per min is recommended for high-resolution applications. Faster logging speeds may induce noise due to the caliper probe bumping the borehole wall. Slower logging speeds will not enhance measurement resolution for most systems.

9.14 Collect caliper data while the probe is moving up the borehole.

9.15 When the probe reaches the top of the borehole:

9.15.1 If surface casing is present, compare and document caliper measurement.

9.15.2 Check depth reference and document after survey depth error (ASDE).

9.15.3 Determine if ASDE meets project objectives.

9.15.4 Typical tolerance for ASDE is ±0.4 ft per 100-ft (0.4 m per 100-m) interval logged.

9.16 Selected borehole intervals should be repeated (that is, relogged) under similar logging parameters as the initial log. Repeat logs provide information on the stability of the caliper equipment. The interval repeated should have enough variability, if possible, to check repeatability and resolution.

9.16.1 Repeat logs should be compared with the original log to ensure correct operation of the probe prior to ending a logging event.

9.16.2 Repeat sections may not repeat exactly due to a different orientation of the logging probe on the repeat run or changes in the borehole between logging runs (see Section 6).

9.16.3 Close caliper arms prior to lowering the probe down the borehole for a repeat section.

9.17 Evaluate the field log quality and compare log with drilling and completion information.

9.17.1 A reduction in borehole diameter over large depth sections may be indicative of borehole deviation on three-arm averaging caliper logs.

9.17.1.1 The magnitude of borehole deviation that causes this effect depends upon the length of the caliper arms being used and the strength of the tensioning spring within the caliper. Typically, a borehole deviation of greater than 15° is likely to produce this effect.

9.17.1.2 Converting the three-arm averaging caliper by removing two of the caliper arms may allow a good log to be obtained in these types of boreholes.

9.17.2 Mud can prevent caliper arms from opening fully, and thick mud cake may prevent accurate measurement of drilled diameter. Lack of caliper arm movement, especially in the bottom of a mud drilled borehole, may be indicative of arm sticking due to heavy mud.

9.17.2.1 If mud interferences are suspected, the borehole may be reconditioned, the caliper probe cleaned and lubricated, and the caliper log repeated.

9.18 Post-acquisition calibration checks may be required (surface casing or calibration standard) to meet the objectives of the logging program. Typical tolerances between pre- and post-calibration are ±0.2 in. (0.5 cm).

10. Interpretation of Results

10.1 See the Log Interpretation section of Guide D 5753 for procedures on log interpretation.

10.2 A valid caliper log is essential in the interpretation of the logs that are affected by changes in borehole diameter, including those logs that are labeled 'borehole compensated.' It is not always possible to compensate logs for substantial differences in borehole diameter.

10.2.1 Caliper logs can be analyzed individually (that is, borehole volume).

10.2.2 Caliper logs can be analyzed as part of a suite to take advantage of the synergistic nature of log data.

10.3 The caliper log should be depth correlated with the other geophysical logs as the first step to interpretation. This is especially important for logs that use the caliper data for borehole correction and depth adjustment.

10.4 Other pertinent information, including borehole construction (casing size), drilling history (hole size, drill method, penetration rate, core loss, fluid loss, etc.), and geologic information, should be integrated with the caliper-log data.

10.5 Interpretations based on changes in borehole diameter may be related to changes in drilling, mud cake, mud rings, borehole construction, lithology and structure, fractures and solution openings, and stress-induced breakouts.

10.6 The measured borehole diameter may be significantly different than the drilled diameter because of plastic formations extruded into the borehole and friable formations enlarging the borehole. A series of caliper logs may also show increases or decreases in borehole diameter with time.

10.6.1 Caliper logs are useful for determining what other logs can be made and what range of borehole diameters will be accepted by centralizers or decentralizers.

10.7 Fractures and solution openings may be obvious on a caliper log; however, their character may not be uniquely defined.

10.7.1 The single-arm caliper log may completely miss a feature or indicate only a small anomaly.

10.7.2 The three-arm averaging caliper log of a fracture dipping at an angle such that the three arms enter the opening at different depths will indicate three separate anomalies rather than one.

10.8 Borehole-diameter information is essential for calculation of volumetric rate from flowmeter logs.

10.9 Caliper logs provide useful information for borehole completion and testing.

10.9.1 Caliper logs are used to locate the optimum placement of inflatable packers for borehole testing. Inflatable packers can only form an effective seal within a specified range of borehole diameters, and can be damaged if they are set in rough or irregular parts of the borehole.

10.9.2 Caliper logs are used to estimate the volume of borehole completion material (cement, gravel, etc.) needed to fill the annular space between borehole and casing(s) or well screen.

10.10 Caliper logs may be applied to correlate lithology between boreholes based upon enlargements related to lithology.

11. Report

11.1 Consult the Report section, Guide D 5753 for requirements of the report.

11.2 Reports presenting caliper logs shall describe the components of the caliper logging system, the principles of the methods used, and their limits, methods and results of calibration and standardization, and performance verification (for example, diameter of surface casing, correlation with other logs, repeat sections, ASDE, etc.).

11.3 Information on the software and algorithms used should be included in the report.

11.4 Any deviations from this guide should be justified with documentation.

11.5 Presentation of caliper logs should be designed to meet project objectives. At a minimum, depth (y-axis) and units of measurement (x-axis) scales should be clearly marked (see Fig. 3). There may be a difference between presentations of data collected in the field versus in final report. Any scale "wraps" should be clearly marked.

11.5.1 Caliper logs are typically displayed with linear scales in inches, millimetres, or centimetres.

12. Keywords

12.1 borehole correction; borehole diameter; borehole geophysics; borehole volume; caliper log; ground water; single-arm caliper; three-arm caliper; well construction; well logging

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(3) Hodges, R. E., Calibration and Standardization of Geophysical Well-Logging Equipment for Hydrologic Applications, *U.S. Geological Survey Water Resources Investigations Report 88-4058*, 1988.