

16.0 TECHNICAL SPECIFICATIONS

INTRODUCTION

The U.S. EPR Technical Specifications are provided as required by 10 CFR 50.36, "Technical specifications," and 10 CFR 50.36a, "Technical specifications on effluents from nuclear power reactors". The U.S. EPR Generic Technical Specifications (GTS) were developed utilizing Revision 3.1 of the Standard Technical Specifications (STS), NUREGs -1430, -1431, -1432, and -1434, as deemed appropriate to the U.S. EPR design. The U.S. EPR Generic Technical Specifications are supported by a separate document (Chapter 16B, Bases) that provide the bases for each of the Technical Specifications other than Section 1.0, Use and Application, Section 4.0, Design Features, and Section 5.0, Administrative Controls. As with currently operating plants, the Bases are not considered to be a part of the Technical Specifications.

The criteria of 10 CFR 50.36(c)(2)(ii) have been used to identify the structures, systems, components, and design features for which Limiting Conditions for Operation (LCO) have been included in the U.S. EPR Technical Specifications. The four criteria are:

- 1) Installed instrumentation that is used to detect, and indicate in the control room, a significant abnormal degradation of the reactor coolant pressure boundary.
- 2) A process variable, design feature, or operating restriction that is an initial condition of a Design Basis Accident or Transient Analysis that either assumes the failure of or presents a challenge to the integrity of a fission product barrier.
- 3) A structure, system or component that is part of the primary success path and which functions or actuates to mitigate a Design Basis Accident or Transient that either assumes the failure of or presents a challenge to the integrity of a fission product barrier.
- 4) Structures, systems and components which operating experience or probabilistic assessment has shown to be important to public health and safety.

The Completion Times and Surveillance Frequencies specified in STS NUREGs were generally applied to the U.S. EPR Generic Technical Specifications. For systems and features unique to the U.S. EPR, similar Completion Times and Surveillance Frequencies were adopted.

The U.S. EPR Generic Technical Specifications are intended to be a model for the development of plant specific Technical Specifications for plants that reference the U.S. EPR standard plant.

Reviewer's Notes and brackets are used to identify information or parameters that are plant specific or are based on preliminary design information. A COL applicant that references the U.S. EPR design certification will provide the necessary information in response to the Reviewer's Notes and replace preliminary information provided in brackets of the Technical Specifications and Technical Specification Bases with plant specific values.

U.S. EPR GENERIC TECHNICAL SPECIFICATIONS
TABLE OF CONTENTS

SECTION	TITLE	REVISION
1.0	USE AND APPLICATION	
1.1	Definitions	1
1.2	Logical Connectors	1
1.3	Completion Times	1
1.4	Frequency	1
2.0	SAFETY LIMITS (SLs)	
2.1	SLs	1
2.2	SL Violations	1
3.0	LIMITING CONDITION FOR OPERATION (LCO) APPLICABILITY	1
3.0	SURVEILLANCE REQUIREMENT (SR) APPLICABILITY	1
3.1	REACTIVITY CONTROL SYSTEMS	
3.1.1	SHUTDOWN MARGIN (SDM)	1
3.1.2	Core Reactivity	1
3.1.3	Moderator Temperature Coefficient (MTC)	1
3.1.4	Rod Control Cluster Assembly (RCCA) Group Alignment Limits	1
3.1.5	Shutdown Bank Insertion Limits	1
3.1.6	Control Bank Insertion Limits	1
3.1.7	Rod Control Cluster Assembly (RCCA) Position Indication	1
3.1.8	Boron Dilution Protection (BDP)	1
3.1.9	PHYSICS TESTS Exceptions - MODE 2	1
3.2	POWER DISTRIBUTION LIMITS	
3.2.1	Linear Power Density (LPD)	1
3.2.2	Nuclear Enthalpy Rise Hot Channel Factor ($F_{\Delta H}^N$)	1
3.2.3	Departure From Nucleate Boiling Ratio (DNBR)	1
3.2.4	AXIAL OFFSET (AO)	1
3.2.5	AZIMUTHAL POWER IMBALANCE (API)	1

U.S. EPR GENERIC TECHNICAL SPECIFICATIONS
TABLE OF CONTENTS

SECTION	TITLE	REVISION
3.3	INSTRUMENTATION	
3.3.1	Protection System (PS)	1
3.3.2	Post Accident Monitoring (PAM) Instrumentation	1
3.3.3	Remote Shutdown System (RSS)	1
3.4	REACTOR COOLANT SYSTEM (RCS)	
3.4.1	RCS Pressure, Temperature, and Flow Departure from Nucleate Boiling (DNB) Limits	1
3.4.2	RCS Minimum Temperature for Criticality	1
3.4.3	RCS Pressure and Temperature (P/T) Limits	1
3.4.4	RCS Loops - MODES 1 and 2	1
3.4.5	RCS Loops - MODE 3	1
3.4.6	RCS Loops - MODE 4	1
3.4.7	RCS Loops - MODE 5, Loops Filled	1
3.4.8	RCS Loops - MODE 5, Loops Not Filled	1
3.4.9	Pressurizer	1
3.4.10	Pressurizer Safety Relief Valves	1
3.4.11	Low Temperature Overpressure Protection (LTOP)	1
3.4.12	RCS Operational LEAKAGE	1
3.4.13	RCS Pressure Isolation Valve (PIV) Leakage	1
3.4.14	RCS Leakage Detection Instrumentation	1
3.4.15	RCS Specific Activity	1
3.4.16	Steam Generator (SG) Tube Integrity	1
3.4.17	RCS Loops - Test Exceptions	1
3.5	EMERGENCY CORE COOLING SYSTEMS (ECCS)	
3.5.1	Accumulators	1
3.5.2	ECCS - Operating	1
3.5.3	ECCS - Shutdown, MODE 4	1
3.5.4	In-Containment Refueling Water Storage Tank (IRWST) - Operating	1
3.5.5	Extra Borating System (EBS)	1

U.S. EPR GENERIC TECHNICAL SPECIFICATIONS
TABLE OF CONTENTS

SECTION	TITLE	REVISION
3.5.6	In-Containment Refueling Water Storage Tank (IRWST) - Shutdown, MODE 5	1
3.5.7	In-Containment Refueling Water Storage Tank (IRWST) - Shutdown, MODE 6	1
3.5.8	ECCS - Shutdown, MODES 5 and 6	1
3.6	CONTAINMENT SYSTEMS	
3.6.1	Containment	1
3.6.2	Containment Air Locks	1
3.6.3	Containment Isolation Valves	1
3.6.4	Containment Pressure	1
3.6.5	Containment Air Temperature	1
3.6.6	Shield Building	1
3.6.7	Annulus Ventilation System (AVS)	1
3.6.8	pH Adjustment	1
3.7	PLANT SYSTEMS	
3.7.1	Main Steam Safety Valves (MSSVs)	1
3.7.2	Main Steam Isolation Valves (MSIVs)	1
3.7.3	Main Feedwater (MFW) Valves	1
3.7.4	Main Steam Relief Trains (MSRTs)	1
3.7.5	Emergency Feedwater (EFW) System	1
3.7.6	Emergency Feedwater (EFW) Storage Pools	1
3.7.7	Component Cooling Water (CCW) System	1
3.7.8	Essential Service Water (ESW) System	1
3.7.9	Safety Chilled Water (SCW) System	1
3.7.10	Control Room Emergency Filtration (CREF)	1
3.7.11	Control Room Air Conditioning System (CRACS)	1
3.7.12	Safeguard Building Controlled Area Ventilation System (SBVS)	1
3.7.13	Safeguard Building Ventilation System Electrical Division (SBVSED)	1
3.7.14	Spent Fuel Storage Pool Water Level	1
3.7.15	Spent Fuel Storage Pool Boron Concentration and Enrichment	1

U.S. EPR GENERIC TECHNICAL SPECIFICATIONS
TABLE OF CONTENTS

SECTION	TITLE	REVISION
3.7.16	Spent Fuel Storage	1
3.7.17	Secondary Specific Activity	1
3.7.18	Main Steam Line Leakage	1
3.7.19	Ultimate Heat Sink (UHS)	1
3.8	ELECTRICAL POWER SYSTEMS	
3.8.1	AC Sources - Operating	1
3.8.2	AC Sources - Shutdown	1
3.8.3	Diesel Fuel Oil, Lube Oil, and Starting Air	1
3.8.4	DC Sources - Operating	1
3.8.5	DC Sources - Shutdown	1
3.8.6	Battery Parameters	1
3.8.7	Inverters - Operating	1
3.8.8	Inverters - Shutdown	1
3.8.9	Distribution Systems - Operating	1
3.8.10	Distribution Systems - Shutdown	1
3.9	REFUELING OPERATIONS	
3.9.1	Boron Concentration	1
3.9.2	Nuclear Instrumentation	1
3.9.3	Decay Time	1
3.9.4	Residual Heat Removal (RHR) Loops - High Water Level	1
3.9.5	Residual Heat Removal (RHR) Loops - Low Water Level	1
3.9.6	Refueling Cavity Water Level	1
4.0	DESIGN FEATURES	
4.1	Site Location	1
4.2	Reactor Core	1
4.3	Fuel Storage	1
5.0	ADMINISTRATIVE CONTROLS	
5.1	Responsibility	1
5.2	Organization	1

U.S. EPR GENERIC TECHNICAL SPECIFICATIONS
TABLE OF CONTENTS

<u>SECTION</u>	<u>TITLE</u>	<u>REVISION</u>
5.3	Unit Staff Qualifications	1
5.4	Procedures	1
5.5	Programs and Manuals	1
5.6	Reporting Requirements	1
5.7	High Radiation Area	1

U.S. EPR GENERIC TECHNICAL SPECIFICATIONS
TABLE OF CONTENTS

SECTION	TITLE	REVISION
B 2.0	SAFETY LIMITS (SLs)	
B 2.1.1	Reactor Core SL	1
B 2.1.2	Reactor Coolant System (RCS) Pressure SL	1
B 3.0	LIMITING CONDITION FOR OPERATION (LCO) APPLICABILITY	1
B 3.0	SURVEILLANCE REQUIREMENT (SR) APPLICABILITY	1
B 3.1	REACTIVITY CONTROL SYSTEMS	
B 3.1.1	SHUTDOWN MARGIN (SDM)	1
B 3.1.2	Core Reactivity	1
B 3.1.3	Moderator Temperature Coefficient (MTC)	1
B 3.1.4	Rod Control Cluster Assembly (RCCA) Group Alignment Limits	1
B 3.1.5	Shutdown Bank Insertion Limits	1
B 3.1.6	Control Bank Insertion Limits	1
B 3.1.7	Rod Control Cluster Assembly (RCCA) Position Indication	1
B 3.1.8	Boron Dilution Protection (BDP)	1
B 3.1.9	PHYSICS TESTS Exceptions - MODE 2	1
B 3.2	POWER DISTRIBUTION LIMITS	
B 3.2.1	Linear Power Density (LPD)	1
B 3.2.2	Nuclear Enthalpy Rise Hot Channel Factor ($F_{\Delta H}^N$)	1
B 3.2.3	Departure From Nucleate Boiling Ratio (DNBR)	1
B 3.2.4	AXIAL OFFSET (AO)	1
B 3.2.5	AZIMUTHAL POWER IMBALANCE (API)	1
B 3.3	INSTRUMENTATION	
B 3.3.1	Protection System (PS)	1
B 3.3.2	Post Accident Monitoring (PAM) Instrumentation	1
B 3.3.3	Remote Shutdown System (RSS)	1

U.S. EPR GENERIC TECHNICAL SPECIFICATIONS
TABLE OF CONTENTS

SECTION	TITLE	REVISION
B 3.4	REACTOR COOLANT SYSTEM (RCS)	
B 3.4.1	RCS Pressure, Temperature, and Flow Departure from Nucleate Boiling (DNB) Limits	1
B 3.4.2	RCS Minimum Temperature for Criticality	1
B 3.4.3	RCS Pressure and Temperature (P/T) Limits	1
B 3.4.4	RCS Loops - MODES 1 and 2	1
B 3.4.5	RCS Loops - MODE 3	1
B 3.4.6	RCS Loops - MODE 4	1
B 3.4.7	RCS Loops - MODE 5, Loops Filled	1
B 3.4.8	RCS Loops - MODE 5, Loops Not Filled	1
B 3.4.9	Pressurizer	1
B 3.4.10	Pressurizer Safety Relief Valves (PSRVs)	1
B 3.4.11	Low Temperature Overpressure Protection (LTOP)	1
B 3.4.12	RCS Operational LEAKAGE	1
B 3.4.13	RCS Pressure Isolation Valve (PIV) Leakage	1
B 3.4.14	RCS Leakage Detection Instrumentation	1
B 3.4.15	RCS Specific Activity	1
B 3.4.16	Steam Generator (SG) Tube Integrity	1
B 3.4.17	RCS Loops - Test Exceptions	1
B 3.5	EMERGENCY CORE COOLING SYSTEMS (ECCS)	
B 3.5.1	Accumulators	1
B 3.5.2	ECCS - Operating	1
B 3.5.3	ECCS - Shutdown, MODE 4	1
B 3.5.4	In-Containment Refueling Water Storage Tank (IRWST) - Operating	1
B 3.5.5	Extra Borating System (EBS)	1
B 3.5.6	In-Containment Refueling Water Storage Tank (IRWST) - Shutdown, MODE 5	1
B 3.5.7	In-Containment Refueling Water Storage Tank (IRWST) - Shutdown, MODE 6	1
B 3.5.8	ECCS - Shutdown, MODES 5 and 6	1

U.S. EPR GENERIC TECHNICAL SPECIFICATIONS
TABLE OF CONTENTS

SECTION	TITLE	REVISION
B 3.6	CONTAINMENT SYSTEMS	
B 3.6.1	Containment	1
B 3.6.2	Containment Air Locks	1
B 3.6.3	Contaminant Isolation Valves	1
B 3.6.4	Containment Pressure	1
B 3.6.5	Containment Air Temperature	1
B 3.6.6	Shield Building	1
B 3.6.7	Annulus Ventilation System (AVS)	1
B 3.6.8	pH Adjustment	1
B 3.7	PLANT SYSTEMS	
B 3.7.1	Main Steam Safety Valves (MSSVs)	1
B 3.7.2	Main Steam Isolation Valves (MSIVs)	1
B 3.7.3	Main Feedwater (MFW) Valves	1
B 3.7.4	Main Steam Relief Trains (MSRTs)	1
B 3.7.5	Emergency Feedwater (EFW) System	1
B 3.7.6	Emergency Feedwater (EFW) Storage Pools	1
B 3.7.7	Component Cooling Water (CCW) System	1
B 3.7.8	Essential Service Water (ESW) System	1
B 3.7.9	Safety Chilled Water (SCW) System	1
B 3.7.10	Control Room Emergency Filtration (CREF)	1
B 3.7.11	Control Room Air Conditioning System (CRACS)	1
B 3.7.12	Safeguard Building Controlled Area Ventilation System (SBVS)	1
B 3.7.13	Safeguard Building Ventilation System Electrical Division (SBVSED)	1
B 3.7.14	Spent Fuel Storage Pool Water Level	1
B 3.7.15	Spent Fuel Storage Pool Boron Concentration and Enrichment	1
B 3.7.16	Spent Fuel Storage	1
B 3.7.17	Secondary Specific Activity	1
B 3.7.18	Main Steam Line Leakage	1
B 3.7.19	Ultimate Heat Sink (UHS)	1

U.S. EPR GENERIC TECHNICAL SPECIFICATIONS
TABLE OF CONTENTS

SECTION	TITLE	REVISION
B 3.8	ELECTRICAL POWER SYSTEMS	
B 3.8.1	AC Sources - Operating	1
B 3.8.2	AC Sources - Shutdown	1
B 3.8.3	Diesel Fuel Oil, Lube Oil, and Starting Air	1
B 3.8.4	DC Sources - Operating	1
B 3.8.5	DC Sources - Shutdown	1
B 3.8.6	Battery Parameters	1
B 3.8.7	Inverters - Operating	1
B 3.8.8	Inverters - Shutdown	1
B 3.8.9	Distribution Systems - Operating	1
B 3.8.10	Distribution Systems - Shutdown	1
B 3.9	REFUELING OPERATIONS	
B 3.9.1	Boron Concentration	1
B 3.9.2	Nuclear Instrumentation	1
B 3.9.3	Decay Time	1
B 3.9.4	Residual Heat Removal (RHR) Loops - High Water Level	1
B 3.9.5	Residual Heat Removal (RHR) Loops - Low Water Level	1
B 3.9.6	Refueling Cavity Water Level	1

1.0 USE AND APPLICATION

1.1 DEFINITIONS

-----NOTE-----

The defined terms of this section appear in capitalized type and are applicable throughout these Technical Specifications and Bases.

<u>Term</u>	<u>Definition</u>
ACTIONS	ACTIONS shall be that part of a Specification that prescribes Required Actions to be taken under designated Conditions within specified Completion Times.
ACTUATING DEVICE OPERATIONAL TEST (ADOT)	An ADOT shall consist of operating the actuating device and verifying the OPERABILITY of all devices in the division required for actuating device OPERABILITY. The ADOT may be performed by means of any series of sequential, overlapping, or total division steps.
AXIAL OFFSET (AO)	<p>AO (%) shall be the power generated in the upper half of the core less the power generated in the lower half of the core, divided by the sum of the power generated in the lower and upper halves of the core.</p> $AO = ((Upper - Lower) / (Lower + Upper)) * 100$
AZIMUTHAL POWER IMBALANCE (API)	<p>AZIMUTHAL POWER IMBALANCE shall be the maximum of the difference between the maximum power generated in any core quadrant (QN_{max}) and the minimum power generated in any core quadrant (QN_{min}), as measured by the power range excore detectors.</p> $API = QN_{max} - QN_{min}$
CALIBRATION	A CALIBRATION shall be the adjustment, as necessary, of the sensor output such that it responds within the necessary range and accuracy to known values of the parameter that the division monitors. The CALIBRATION shall encompass all devices in the division required for sensor OPERABILITY. CALIBRATION of instrument divisions with resistance temperature detector (RTD) or thermocouple sensors may consist of an in-place qualitative assessment of sensor behavior and normal CALIBRATION of the remaining adjustable devices in the division. The CALIBRATION may be performed by means of any series of sequential, overlapping, or total steps.

1.1 Definitions

CHANNEL CHECK

A CHANNEL CHECK shall be the qualitative assessment, by observation, of channel behavior during operation. This determination shall include, where possible, comparison of the channel indication and status to other indications or status derived from independent instrumentation channels measuring the same parameter.

CORE OPERATING LIMITS
REPORT (COLR)

The COLR is the unit specific document that provides cycle specific parameter limits for the current reload cycle. These cycle specific parameter limits shall be determined for each reload cycle in accordance with Specification 5.6.3. Plant operation within these limits is addressed in individual Specifications.

DOSE EQUIVALENT I-131

DOSE EQUIVALENT I-131 shall be that concentration of I-131 (microcuries per gram) that alone would produce the same dose when inhaled as the combined activities of iodine isotopes I-131, I-132, I-133, I-134, and I-135 actually present. The determination of DOSE EQUIVALENT I-131 shall be performed using thyroid dose conversion factors from EPA Federal Guidance Report No. 11, 1988, "Limiting Values of Radionuclide Intake and Air Concentration and Dose Conversion Factors for Inhalation, Submersion, and Ingestion."

1.1 Definitions

DOSE EQUIVALENT XE-133

DOSE EQUIVALENT XE-133 shall be that concentration of Xe-133 (microcuries per gram) that alone would produce the same acute dose to the whole body as the combined activities of noble gas nuclides Kr-85m, Kr-85, Kr-87, Kr-88, Xe-131m, Xe-133m, Xe-133, Xe-135m Xe-135, and Xe-138 actually present. If a specific noble gas nuclide is not detected, it should be assumed to be present at the minimum detectable activity. The determination of DOSE EQUIVALENT XE-133 shall be performed using effective dose conversion factors for air submersion listed in Table III.1 of EPA Federal Guidance Report No. 12, 1993, "External Exposure to Radionuclides in Air, Water, and Soil" or the average gamma disintegration energies as provided in ICRP Publication 38, "Radionuclide Transformations".

EXTENDED SELF TESTS

Testing of the Protection System signal processors that cannot be performed during power operation are performed during the start-up of a computer. These tests can also be initiated by pushing a reset button on the computer. These tests include a basic hardware test using the internal diagnostics monitor, a self-test of the operating system, and basic hardware tests.

1.1 Definitions

LEAKAGE

LEAKAGE shall be:

a. Identified LEAKAGE

1. LEAKAGE, such as that from pump seals or valve packing (except reactor coolant pump (RCP) seal water injection or leakoff), that is captured and conducted to collection systems or a sump or collecting tank;
2. LEAKAGE into the containment atmosphere from sources that are both specifically located and known either not to interfere with the operation of leakage detection systems or not to be pressure boundary LEAKAGE; or
3. Reactor Coolant System (RCS) LEAKAGE through a steam generator to the Secondary System (primary to secondary LEAKAGE);

b. Unidentified LEAKAGE

All LEAKAGE (except RCP seal water injection or leakoff) that is not identified LEAKAGE; and

c. Pressure Boundary LEAKAGE

LEAKAGE (except primary to secondary LEAKAGE) through a nonisolable fault in an RCS component body, pipe wall, or vessel wall.

MODE

A MODE shall correspond to any one inclusive combination of core reactivity condition, power level, average reactor coolant temperature, and reactor vessel head closure bolt tensioning specified in Table 1.1-1 with fuel in the reactor vessel.

OPERABLE – OPERABILITY

A system, subsystem, train, component, or device shall be OPERABLE or have OPERABILITY when it is capable of performing its specified safety function(s) and when all necessary attendant instrumentation, controls, normal or emergency electrical power, cooling and seal water, lubrication, and other auxiliary equipment that are required for the system, subsystem, train, component, or device to perform its specified safety function(s) are also capable of performing their related support function(s).

1.1 Definitions

PHYSICS TESTS

PHYSICS TESTS shall be those tests performed to measure the fundamental nuclear characteristics of the reactor core and related instrumentation. These tests are:

- a. Described in FSAR Chapter 14, "Verification Programs";
- b. Authorized under the provisions of 10 CFR 50.59; or
- c. Otherwise approved by the Nuclear Regulatory Commission.

PRESSURE AND TEMPERATURE LIMITS REPORT (PTLR)

The PTLR is the unit specific document that provides the reactor vessel pressure and temperature limits, including heatup and cooldown rates and the low temperature overpressure protection setpoints, for the current reactor vessel fluence period. These pressure and temperature limits shall be determined for each fluence period in accordance with Specification 5.6.4, "Reactor Coolant System (RCS) PRESSURE AND TEMPERATURE LIMITS REPORT (PTLR)."

PROTECTION SYSTEM (PS) RESPONSE TIME

The PS RESPONSE TIME shall be that time interval from when the monitored parameter exceeds its PS actuation setpoint at the diversion sensor until the PS equipment is capable of performing its safety function (i.e., loss of stationary gripper coil voltage, the valves travel to their required positions, pump discharge pressures reach their required values, etc.). Times shall include diesel generator starting and sequence loading delays, where applicable. The response time may be measured by means of any series of sequential, overlapping, or total steps so that the entire response time is measured. In lieu of measurement, response time may be verified for selected components provided that the components and methodology for verification have been previously reviewed and approved by the NRC.

RATED THERMAL POWER (RTP)

RTP shall be a total reactor core heat transfer rate to the reactor coolant of 4590 MWt.

1.1 Definitions

SENSOR OPERATIONAL TEST (SOT)

A SOT shall be the injection of a simulated or actual signal into the division as close to the sensor as practicable to verify OPERABILITY of all devices in the division required for sensor OPERABILITY. The SOT shall include the verification of the accuracy and time constants of the analog input modules. The SOT may be performed by means of any series of sequential, overlapping, or total steps.

SHUTDOWN MARGIN (SDM)

SDM shall be the instantaneous amount of reactivity by which the reactor is subcritical or would be subcritical from its present condition assuming:

- a. All rod cluster control assemblies (RCCAs) are fully inserted except for the single RCCA of highest reactivity worth, which is assumed to be fully withdrawn. However, with all RCCAs verified fully inserted by two independent means, it is not necessary to account for a stuck RCCA in the SDM calculation. With any RCCA not capable of being fully inserted, the reactivity worth of the RCCA must be accounted for in the determination of SDM; and
- b. In MODES 1 and 2, the fuel and moderator temperatures are changed to the nominal zero power design level.

STAGGERED TEST BASIS

A STAGGERED TEST BASIS shall consist of the testing of one of the systems, subsystems, divisions, or other designated components during the interval specified by the Surveillance Frequency, so that all systems, subsystems, divisions, or other designated components are tested during n Surveillance Frequency intervals, where n is the total number of systems, subsystems, divisions, or other designated components in the associated function.

THERMAL POWER

THERMAL POWER shall be the total reactor core heat transfer rate to the reactor coolant.

Table 1.1-1 (page 1 of 1)
MODES

MODE	TITLE	REACTIVITY CONDITION (k_{eff})	% RATED THERMAL POWER ^(a)	AVERAGE REACTOR COOLANT TEMPERATURE (°F)
1	Power Operation	≥ 0.99	> 5	NA
2	Startup	≥ 0.99	≤ 5	NA
3	Hot Standby	< 0.99	NA	≥ 350
4	Hot Shutdown ^(b)	< 0.99	NA	$350 > T_{avg} > 200$
5	Cold Shutdown ^(b)	< 0.99	NA	≤ 200
6	Refueling ^(c)	NA	NA	NA

(a) Excluding decay heat.

(b) All reactor vessel head closure bolts fully tensioned.

(c) One or more reactor vessel head closure bolts less than fully tensioned.

| 1.0 USE AND APPLICATION

| 1.2 LOGICAL CONNECTORS

PURPOSE The purpose of this section is to explain the meaning of logical connectors.

Logical connectors are used in Technical Specifications (TS) to discriminate between, and yet connect, discrete Conditions, Required Actions, Completion Times, Surveillances, and Frequencies. The only logical connectors that appear in TS are AND and OR. The physical arrangement of these connectors constitutes logical conventions with specific meanings.

BACKGROUND Several levels of logic may be used to state Required Actions. These levels are identified by the placement (or nesting) of the logical connectors and by the number assigned to each Required Action. The first level of logic is identified by the first digit of the number assigned to a Required Action and the placement of the logical connector in the first level of nesting (i.e., left justified with the number of the Required Action). The successive levels of logic are identified by additional digits of the Required Action number and by successive indentations of the logical connectors.

When logical connectors are used to state a Condition, Completion Time, Surveillance, or Frequency, only the first level of logic is used, and the logical connector is left justified with the statement of the Condition, Completion Time, Surveillance, or Frequency.

EXAMPLES The following examples illustrate the use of logical connectors.

EXAMPLE 1.2-1

ACTIONS

CONDITION	REQUIRED ACTION	COMPLETION TIME
A. LCO not met.	A.1 Verify . . . <u>AND</u> A.2 Restore . . .	

In this example the logical connector AND is used to indicate that when in Condition A, both Required Actions A.1 and A.2 must be completed.

1.2 Logical Connectors

EXAMPLES (continued)

EXAMPLE 1.2-2

ACTIONS

CONDITION	REQUIRED ACTION	COMPLETION TIME
A. LCO not met.	A.1 Trip . . . <u>OR</u> A.2.1 Verify . . . <u>AND</u> A.2.2.1 Reduce . . . <u>OR</u> A.2.2.2 Perform . . . <u>OR</u> A.3 Align . . .	

This example represents a more complicated use of logical connectors. Required Actions A.1, A.2, and A.3 are alternative choices, only one of which must be performed as indicated by the use of the logical connector OR and the left justified placement. Any one of these three Actions may be chosen. If A.2 is chosen, then both A.2.1 and A.2.2 must be performed as indicated by the logical connector AND. Required Action A.2.2 is met by performing A.2.2.1 or A.2.2.2. The indented position of the logical connector OR indicates that A.2.2.1 and A.2.2.2 are alternative choices, only one of which must be performed.

| 1.0 USE AND APPLICATION

| 1.3 COMPLETION TIMES

PURPOSE	The purpose of this section is to establish the Completion Time convention and to provide guidance for its use.
BACKGROUND	Limiting Conditions for Operation (LCOs) specify minimum requirements for ensuring safe operation of the unit. The ACTIONS associated with an LCO state Conditions that typically describe the ways in which the requirements of the LCO can fail to be met. Specified with each stated Condition are Required Action(s) and Completion Time(s).
DESCRIPTION	<p>The Completion Time is the amount of time allowed for completing a Required Action. It is referenced to the time of discovery of a situation (e.g., inoperable equipment or variable not within limits) that requires entering an ACTIONS Condition unless otherwise specified, providing the unit is in a MODE or specified condition stated in the Applicability of the LCO. Required Actions must be completed prior to the expiration of the specified Completion Time. An ACTIONS Condition remains in effect and the Required Actions apply until the Condition no longer exists or the unit is not within the LCO Applicability.</p> <p>If situations are discovered that require entry into more than one Condition at a time within a single LCO (multiple Conditions), the Required Actions for each Condition must be performed within the associated Completion Time. When in multiple Conditions, separate Completion Times are tracked for each Condition starting from the time of discovery of the situation that required entry into the Condition.</p> <p>Once a Condition has been entered, subsequent trains, subsystems, components, or variables expressed in the Condition, discovered to be inoperable or not within limits, will <u>not</u> result in separate entry into the Condition, unless specifically stated. The Required Actions of the Condition continue to apply to each additional failure, with Completion Times based on initial entry into the Condition.</p> <p>However, when a <u>subsequent</u> train, subsystem, component, or variable expressed in the Condition is discovered to be inoperable or not within limits, the Completion Time(s) may be extended. To apply this Completion Time extension, two criteria must first be met. The subsequent inoperability:</p> <ol style="list-style-type: none">a. Must exist concurrent with the <u>first</u> inoperability; and

1.3 Completion Times

DESCRIPTION (continued)

- b. Must remain inoperable or not within limits after the first inoperability is resolved.

The total Completion Time allowed for completing a Required Action to address the subsequent inoperability shall be limited to the more restrictive of either:

- a. The stated Completion Time, as measured from the initial entry into the Condition, plus an additional 24 hours; or
- b. The stated Completion Time as measured from discovery of the subsequent inoperability.

The above Completion Time extensions do not apply to those Specifications that have exceptions that allow completely separate re-entry into the Condition (for each train, subsystem, component, or variable expressed in the Condition) and separate tracking of Completion Times based on this re-entry. These exceptions are stated in individual Specifications.

The above Completion Time extension does not apply to a Completion Time with a modified "time zero." This modified "time zero" may be expressed as a repetitive time (i.e., "once per 8 hours," where the Completion Time is referenced from a previous completion of the Required Action versus the time of Condition entry) or as a time modified by the phrase "from discovery . . ."

EXAMPLES

The following examples illustrate the use of Completion Times with different types of Conditions and changing Conditions.

EXAMPLE 1.3-1

ACTIONS

CONDITION	REQUIRED ACTION	COMPLETION TIME
B. Required Action and associated Completion Time not met.	B.1 Be in MODE 3.	6 hours
	<u>AND</u> B.2 Be in MODE 5.	36 hours

1.3 Completion Times

EXAMPLES (continued)

Condition B has two Required Actions. Each Required Action has its own separate Completion Time. Each Completion Time is referenced to the time that Condition B is entered.

The Required Actions of Condition B are to be in MODE 3 within 6 hours AND in MODE 5 within 36 hours. A total of 6 hours is allowed for reaching MODE 3 and a total of 36 hours (not 42 hours) is allowed for reaching MODE 5 from the time that Condition B was entered. If MODE 3 is reached within 3 hours, the time allowed for reaching MODE 5 is the next 33 hours because the total time allowed for reaching MODE 5 is 36 hours.

If Condition B is entered while in MODE 3, the time allowed for reaching MODE 5 is the next 36 hours.

EXAMPLE 1.3-2

ACTIONS

CONDITION	REQUIRED ACTION	COMPLETION TIME
A. One pump inoperable.	A.1 Restore pump to OPERABLE status.	7 days
B. Required Action and associated Completion Time not met.	B.1 Be in MODE 3.	6 hours
	<u>AND</u> B.2 Be in MODE 5.	36 hours

When a pump is declared inoperable, Condition A is entered. If the pump is not restored to OPERABLE status within 7 days, Condition B is also entered and the Completion Time clocks for Required Actions B.1 and B.2 start. If the inoperable pump is restored to OPERABLE status after Condition B is entered, Conditions A and B are exited, and therefore, the Required Actions of Condition B may be terminated.

| 1.3 Completion Times

EXAMPLES (continued)

When a second pump is declared inoperable while the first pump is still inoperable, Condition A is not re-entered for the second pump. LCO 3.0.3 is entered, since the ACTIONS do not include a Condition for more than one inoperable pump. The Completion Time clock for Condition A does not stop after LCO 3.0.3 is entered, but continues to be tracked from the time Condition A was initially entered.

While in LCO 3.0.3, if one of the inoperable pumps is restored to OPERABLE status and the Completion Time for Condition A has not expired, LCO 3.0.3 may be exited and operation continued in accordance with Condition A.

While in LCO 3.0.3, if one of the inoperable pumps is restored to OPERABLE status and the Completion Time for Condition A has expired, LCO 3.0.3 may be exited and operation continued in accordance with Condition B. The Completion Time for Condition B is tracked from the time the Condition A Completion Time expired.

On restoring one of the pumps to OPERABLE status, the Condition A Completion Time is not reset, but continues from the time the first pump was declared inoperable. This Completion Time may be extended if the pump restored to OPERABLE status was the first inoperable pump. A 24 hour extension to the stated 7 days is allowed, provided this does not result in the second pump being inoperable for > 7 days.

1.3 Completion Times

EXAMPLES (continued)

EXAMPLE 1.3-3

ACTIONS

CONDITION	REQUIRED ACTION	COMPLETION TIME
A. One Function X train inoperable.	A.1 Restore Function X train to OPERABLE status.	7 days
B. One Function Y train inoperable.	B.1 Restore Function Y train to OPERABLE status.	72 hours
C. One Function X train inoperable. <u>AND</u> One Function Y train inoperable.	C.1 Restore Function X train to OPERABLE status. <u>OR</u> C.2 Restore Function Y train to OPERABLE status.	72 hours 72 hours

When one Function X train and one Function Y train are inoperable, Condition A and Condition B are concurrently applicable. The Completion Times for Condition A and Condition B are tracked separately for each train starting from the time each train was declared inoperable and the Condition was entered. A separate Completion Time is established for Condition C and tracked from the time the second train was declared inoperable (i.e., the time the situation described in Condition C was discovered).

1.3 Completion Times

EXAMPLES (continued)

If Required Action C.2 is completed within the specified Completion Time, Conditions B and C are exited. If the Completion Time for Required Action A.1 has not expired, operation may continue in accordance with Condition A.

It is possible to alternate between Conditions A, B, and C in such a manner that operation could continue indefinitely without ever restoring systems to meet the LCO. However, doing so would be inconsistent with the basis of the Completion Times. Therefore, there shall be administrative controls to limit the maximum time allowed for any combination of Conditions that result in a single contiguous occurrence of failing to meet the LCO. These administrative controls shall ensure that the Completion Times for those Conditions are not inappropriately extended.

EXAMPLE 1.3-4

ACTIONS

CONDITION	REQUIRED ACTION	COMPLETION TIME
A. One or more valves inoperable.	A.1 Restore valve(s) to OPERABLE status.	4 hours
B. Required Action and associated Completion Time not met.	B.1 Be in MODE 3.	6 hours
	<u>AND</u> B.2 Be in MODE 4.	12 hours

A single Completion Time is used for any number of valves inoperable at the same time. The Completion Time associated with Condition A is based on the initial entry into Condition A and is not tracked on a per valve basis. Declaring subsequent valves inoperable, while Condition A is still in effect, does not trigger the tracking of separate Completion Times.

1.3 Completion Times

EXAMPLES (continued)

Once one of the valves has been restored to OPERABLE status, the Condition A Completion Time is not reset, but continues from the time the first valve was declared inoperable. The Completion Time may be extended if the valve restored to OPERABLE status was the first inoperable valve. The Condition A Completion Time may be extended for up to 4 hours provided this does not result in any subsequent valve being inoperable for > 4 hours.

If the Completion Time of 4 hours (including the extension) expires while one or more valves are still inoperable, Condition B is entered.

EXAMPLE 1.3-5

ACTIONS

-----NOTE-----

Separate Condition entry is allowed for each inoperable valve.

CONDITION	REQUIRED ACTION	COMPLETION TIME
A. One or more valves inoperable.	A.1 Restore valve to OPERABLE status.	4 hours
B. Required Action and associated Completion Time not met.	B.1 Be in MODE 3.	6 hours
	<u>AND</u> B.2 Be in MODE 4.	12 hours

The Note above the ACTIONS Table is a method of modifying how the Completion Time is tracked. If this method of modifying how the Completion Time is tracked was applicable only to a specific Condition, the Note would appear in that Condition rather than at the top of the ACTIONS Table.

1.3 Completion Times

EXAMPLES (continued)

The Note allows Condition A to be entered separately for each inoperable valve, and Completion Times tracked on a per valve basis. When a valve is declared inoperable, Condition A is entered and its Completion Time starts. If subsequent valves are declared inoperable, Condition A is entered for each valve and separate Completion Times start and are tracked for each valve.

If the Completion Time associated with a valve in Condition A expires, Condition B is entered for that valve. If the Completion Times associated with subsequent valves in Condition A expire, Condition B is entered separately for each valve and separate Completion Times start and are tracked for each valve. If a valve that caused entry into Condition B is restored to OPERABLE status, Condition B is exited for that valve.

Since the Note in this example allows multiple Condition entry and tracking of separate Completion Times, Completion Time extensions do not apply.

EXAMPLE 1.3-6

ACTIONS

CONDITION	REQUIRED ACTION	COMPLETION TIME
A. One channel inoperable.	A.1 Perform SR 3.x.x.x.	Once per 8 hours
	<u>OR</u> A.2 Reduce THERMAL POWER to ≤ 50% RTP.	8 hours
B. Required Action and associated Completion Time not met.	B.1 Be in MODE 3.	6 hours

1.3 Completion Times

EXAMPLES (continued)

Entry into Condition A offers a choice between Required Action A.1 or A.2. Required Action A.1 has a "once per" Completion Time, which qualifies for the 25% extension, per SR 3.0.2, to each performance after the initial performance. The initial 8 hour interval of Required Action A.1 begins when Condition A is entered and the initial performance of Required Action A.1 must be complete within the first 8 hour interval. If Required Action A.1 is followed, and the Required Action is not met within the Completion Time (plus the extension allowed by SR 3.0.2), Condition B is entered. If Required Action A.2 is followed and the Completion Time of 8 hours is not met, Condition B is entered.

If after entry into Condition B, Required Action A.1 or A.2 is met, Condition B is exited and operation may then continue in Condition A.

EXAMPLE 1.3-7

ACTIONS

CONDITION	REQUIRED ACTION	COMPLETION TIME
A. One subsystem inoperable.	A.1 Verify affected subsystem isolated.	1 hour <u>AND</u> Once per 8 hours thereafter
	<u>AND</u> A.2 Restore subsystem to OPERABLE status.	72 hours
B. Required Action and associated Completion Time not met.	B.1 Be in MODE 3.	6 hours
	<u>AND</u> B.2 Be in MODE 5.	36 hours

| 1.3 Completion Times

EXAMPLES (continued)

Required Action A.1 has two Completion Times. The 1 hour Completion Time begins at the time the Condition is entered and each "Once per 8 hours thereafter" interval begins upon performance of Required Action A.1.

If after Condition A is entered, Required Action A.1 is not met within either the initial 1 hour or any subsequent 8 hour interval from the previous performance (plus the extension allowed by SR 3.0.2), Condition B is entered. The Completion Time clock for Condition A does not stop after Condition B is entered, but continues from the time Condition A was initially entered. If Required Action A.1 is met after Condition B is entered, Condition B is exited and operation may continue in accordance with Condition A, provided the Completion Time for Required Action A.2 has not expired.

IMMEDIATE
COMPLETION
| TIME

When "Immediately" is used as a Completion Time, the Required Action should be pursued without delay and in a controlled manner.

| 1.0 USE AND APPLICATION

| 1.4 FREQUENCY

PURPOSE The purpose of this section is to define the proper use and application of Frequency requirements.

DESCRIPTION Each Surveillance Requirement (SR) has a specified Frequency in which the Surveillance must be met in order to meet the associated LCO. An understanding of the correct application of the specified Frequency is necessary for compliance with the SR.

The "specified Frequency" is referred to throughout this section and each of the Specifications of Section 3.0, Surveillance Requirement (SR) Applicability. The "specified Frequency" consists of the requirements of the Frequency column of each SR as well as certain Notes in the Surveillance column that modify performance requirements.

Sometimes special situations dictate when the requirements of a Surveillance are to be met. They are "otherwise stated" conditions allowed by SR 3.0.1. They may be stated as clarifying Notes in the Surveillance, as part of the Surveillance, or both.

Situations where a Surveillance could be required (i.e., its Frequency could expire), but where it is not possible or not desired that it be performed until sometime after the associated LCO is within its Applicability, represent potential SR 3.0.4 conflicts. To avoid these conflicts, the SR (i.e., the Surveillance or the Frequency) is stated such that it is only "required" when it can be and should be performed. With an SR satisfied, SR 3.0.4 imposes no restriction.

The use of "met" or "performed" in these instances conveys specific meanings. A Surveillance is "met" only when the acceptance criteria are satisfied. Known failure of the requirements of a Surveillance, even without a Surveillance specifically being "performed," constitutes a Surveillance not "met." "Performance" refers only to the requirement to specifically determine the ability to meet the acceptance criteria.

Some Surveillances contain Notes that modify the Frequency of performance or the conditions during which the acceptance criteria must be satisfied. For these Surveillances, the MODE-entry restrictions of SR 3.0.4 may not apply. Such a Surveillance is not required to be performed prior to entering a MODE or other specified condition in the Applicability of the associated LCO if any of the following three conditions are satisfied:

1.4 Frequency

DESCRIPTION (continued)

- a. The Surveillance is not required to be met in the MODE or other specified condition to be entered;
- b. The Surveillance is required to be met in the MODE or other specified condition to be entered, but has been performed within the specified Frequency (i.e., it is current) and is known not to be failed; or
- c. The Surveillance is required to be met, but not performed, in the MODE or other specified condition to be entered, and is known not to be failed.

Examples 1.4-3, 1.4-4, 1.4-5, and 1.4-6 discuss these special situations.

EXAMPLES

The following examples illustrate the various ways that Frequencies are specified. In these examples, the Applicability of the LCO (LCO not shown) is MODES 1, 2, and 3.

EXAMPLE 1.4-1

SURVEILLANCE REQUIREMENTS

SURVEILLANCE	FREQUENCY
Perform CHANNEL CHECK	12 hours

Example 1.4-1 contains the type of SR most often encountered in the Technical Specifications (TS). The Frequency specifies an interval (12 hours) during which the associated Surveillance must be performed at least one time. Performance of the Surveillance initiates the subsequent interval. Although the Frequency is stated as 12 hours, an extension of the time interval to 1.25 times the stated Frequency is allowed by SR 3.0.2 for operational flexibility. The measurement of this interval continues at all times, even when the SR is not required to be met per SR 3.0.1 (such as when the equipment is inoperable, a variable is outside specified limits, or the unit is outside the Applicability of the LCO). If the interval specified by SR 3.0.2 is exceeded while the unit is in a MODE or other specified condition in the Applicability of the LCO, and the performance of the Surveillance is not otherwise modified (refer to Example 1.4-3), then SR 3.0.3 becomes applicable.

1.4 Frequency

EXAMPLES (continued)

If the interval as specified by SR 3.0.2 is exceeded while the unit is not in a MODE or other specified condition in the Applicability of the LCO for which performance of the SR is required, then SR 3.0.4 becomes applicable. The Surveillance must be performed within the Frequency requirements of SR 3.0.2, as modified by SR 3.0.3, prior to entry into the MODE or other specified condition or the LCO is considered not met (in accordance with SR 3.0.1) and LCO 3.0.4 becomes applicable.

EXAMPLE 1.4-2

SURVEILLANCE REQUIREMENTS

SURVEILLANCE	FREQUENCY
Verify flow is within limits.	Once within 12 hours after $\geq 25\%$ RTP <u>AND</u> 24 hours thereafter

Example 1.4-2 has two Frequencies. The first is a one time performance Frequency, and the second is of the type shown in Example 1.4-1. The logical connector "AND" indicates that both Frequency requirements must be met. Each time reactor power is increased from a power level $< 25\%$ RTP to $\geq 25\%$ RTP, the Surveillance must be performed within 12 hours.

The use of "once" indicates a single performance will satisfy the specified Frequency (assuming no other Frequencies are connected by "AND"). This type of Frequency does not qualify for the 25% extension allowed by SR 3.0.2. "Thereafter" indicates future performances must be established per SR 3.0.2, but only after a specified condition is first met (i.e., the "once" performance in this example). If reactor power decreases to $< 25\%$ RTP, the measurement of both intervals stops. New intervals start upon reactor power reaching 25% RTP.

1.4 Frequency

EXAMPLES (continued)

EXAMPLE 1.4-3

SURVEILLANCE REQUIREMENTS

SURVEILLANCE	FREQUENCY
<p>-----NOTE----- Not required to be performed until 12 hours after ≥ 25% RTP. -----</p>	
<p>Perform channel adjustment.</p>	<p>7 days</p>

The interval continues, whether or not the unit operation is < 25% RTP between performances.

As the Note modifies the required performance of the Surveillance, it is construed to be part of the "specified Frequency." Should the 7 day interval be exceeded while operation is < 25% RTP, this Note allows 12 hours after power reaches ≥ 25% RTP to perform the Surveillance. The Surveillance is still considered to be performed within the "specified Frequency." Therefore, if the Surveillance was not performed within the 7 day (plus the extension allowed by SR 3.0.2) interval, but operation was < 25% RTP, it would not constitute a failure of the SR or failure to meet the LCO. Also, no violation of SR 3.0.4 occurs when changing MODES, even with the 7 day Frequency not met, provided operation does not exceed 12 hours with power ≥ 25% RTP.

Once the unit reaches 25% RTP, 12 hours would be allowed for completing the Surveillance. If the Surveillance was not performed within this 12 hour interval, there would then be a failure to perform a Surveillance within the specified Frequency, and the provisions of SR 3.0.3 would apply.

1.4 Frequency

EXAMPLES (continued)

EXAMPLE 1.4-4

SURVEILLANCE REQUIREMENTS

SURVEILLANCE	FREQUENCY
<p>-----NOTE----- Only required to be met in MODE 1. -----</p>	
<p>Verify leakage rates are within limits.</p>	<p>24 hours</p>

Example 1.4-4 specifies that the requirements of this Surveillance do not have to be met until the unit is in MODE 1. The interval measurement for the Frequency of this Surveillance continues at all times, as described in Example 1.4-1. However, the Note constitutes an "otherwise stated" exception to the Applicability of this Surveillance. Therefore, if the Surveillance was not performed within the 24 hour interval (plus the extension allowed by SR 3.0.2), but the unit was not in MODE 1, there would be no failure of the SR nor failure to meet the LCO. Therefore, no violation of SR 3.0.4 occurs when changing MODES, even with the 24 hour Frequency exceeded, provided the MODE change was not made into MODE 1. Prior to entering MODE 1 (assuming again that the 24 hour Frequency was not met), SR 3.0.4 would require satisfying the SR.

EXAMPLE 1.4-5

SURVEILLANCE REQUIREMENTS

SURVEILLANCE	FREQUENCY
<p>-----NOTE----- Only required to be performed in MODE 1. -----</p>	
<p>Perform complete cycle of the valve.</p>	<p>7 days</p>

1.4 Frequency

EXAMPLES (continued)

The interval continues, whether or not the unit operation is in MODES 1, 2, or 3 (the assumed Applicability of the associated LCO) between performances.

As the Note modifies the required performance of the Surveillance, the Note is construed to be part of the "specified Frequency." Should the 7 day interval be exceeded while operation is not in MODE 1, this Note allows entry into and operation in MODES 2 and 3 to perform the Surveillance. The Surveillance is still considered to be performed within the "specified Frequency" if completed prior to entering MODE 1. Therefore, if the Surveillance was not performed within the 7 day (plus the extension allowed by SR 3.0.2) interval, but operation was not in MODE 1, it would not constitute a failure of the SR or failure to meet the LCO. Also, no violation of SR 3.0.4 occurs when changing MODES, even with the 7 day Frequency not met, provided operation does not result in entry into MODE 1.

Once the unit reaches MODE 1, the requirement for the Surveillance to be performed within its specified Frequency applies and would require that the Surveillance had been performed. If the Surveillance was not performed prior to entering MODE 1, there would then be a failure to perform a Surveillance within the specified Frequency, and the provisions of SR 3.0.3 would apply.

EXAMPLE 1.4-6

SURVEILLANCE REQUIREMENTS

SURVEILLANCE	FREQUENCY
<p>-----NOTE----- Not required to be met in MODE 3. -----</p>	
<p>Verify parameter is within limits.</p>	<p>24 hours</p>

| 1.4 Frequency

EXAMPLES (continued)

Example 1.4-6 specifies that the requirements of this Surveillance do not have to be met while the unit is in MODE 3 (the assumed Applicability of the associated LCO is MODES 1, 2, and 3). The interval measurement for the Frequency of this Surveillance continues at all times, as described in Example 1.4-1. However, the Note constitutes an "otherwise stated" exception to the Applicability of this Surveillance. Therefore, if the Surveillance was not performed within the 24 hour interval (plus the extension allowed by SR 3.0.2), and the unit was in MODE 3, there would be no failure of the SR nor failure to meet the LCO. Therefore, no violation of SR 3.0.4 occurs when changing MODES to enter MODE 3, even with the 24 hour Frequency exceeded, provided the MODE change does not result in entry into MODE 2. Prior to entering MODE 2 (assuming again that the 24 hour Frequency was not met), SR 3.0.4 would require satisfying the SR.
