## **ATTACHMENT (2)**

## CALCULATION NO. CA07018, REVISION NO. 00001, MAIN

## FEEDWATER PRESSURE INPUT UNCERTAINTY TO CALDON

## **CHECKPLUS LEFM**

ATTACHMENT 1, CALCULATION COVER SHEET

A. INITIATION			Page 1 Attachr	of 21 (37 including nents)
Site CCNPF				
Calculation No.: CA070	018	Revision No.:	0001	
Vendor Calculation (Check o	one): 🛛 Yes	No	·	
Responsible Group:	E&C Design Engineering Uni	t		
Responsible Engineer:	D. A. Dvorak			
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B. CALCULATION	<u></u>			5. 5
ENGINEERING DISCIPLINE:	Civil Electrical	Instr & Controls Mechanical	Nuclear	·
Title:	MAIN FEEDWATER PRESS CHECKPLUS LEFM		ERTAINTY TO C	ALDON
Unit	⊠1 ⊠2			:
Proprietary or Safeguards Ca	alculation Y	ES	🛛 NO	
Comments:				
Vendor Calc No.:	CCN-IC-07001	REVISION NO.:	1	
Vendor Name:	HURST TECHNOLOGIES, CORP.		-	·
Safety Class (Check one):		AUGMENTED QUAL	LITY 🛛 NSR	
There are assumptions that	require Verification during wall	down: Yes TRA	CKING ID:	ES200800030-010
This calculation SUPERSED	ES: CA07018, Rev. 000	00	····	· · ·
C. REVIEW AND APPROV	AI -		•	
	TT IURST TECHNOLOGIES, CORP., S	FF PAGE 2		
Responsible Engineer:				Data
	Printed Name and Si	gilature		Date
Is Design Verification Requir	ed? 🗌 Yes 🗌 I	No		<b>3</b>
If yes, Design Verification Fo	orm is	Filed with:		
Independent Reviewer:	IURST TECHNOLOGIES, CORP, S	EE PAGE 2		
	Printed Name and Si	gnature		Date
Approval:	HURST TECHNOLOGIES, CORP, S	EE PAGE 2		
	Printed Name and Si	gnature		Date

## MAIN FEEDWATER PRESSURE INPUT UNCERTAINTY TO CALDON CHECKPLUS LEFM

## For Calvert Cliffs Nuclear Power Plant Units 1 & 2

## Calculation No. CCN-IC-09002 Revision 1

## Prepared By Hurst Technologies, Corp.

## **Project: CCNAKT**

Client:

Constellation Nuclear Calvert Cliffs Nuclear Power Plant 1650 Calvert Cliffs Parkway Lusby, Maryland 20657-4702

Prepared By:	<u>Kirk R. Melso</u>	n Kich R. Melan	Date:	4/15/09
Checked By:	R.A. Hunter	Robert Ol. Hunter	Date:	4/15/09
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Approved By:	W.G. Wellbo	m hall-lith	Date:	4/15/09

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	Attachment 1 –	Excerpt from Rosemount Product Data Shee 4001, Revision HA, March 2008	et 00813-0100- [4 pages]
	Attachment 2 –	Specifications for Analog Devices Single-C Conditioning Module 5B32, printed from th http://analog.com website on 4/9/2009, inclu- clarification, dated 4/13/2009	e
	Attachment 3 –	Excerpt from Burr-Brown Product Data She ADS7825 4 Channel, 16-Bit Sampling CMC October 1997	
	Attachment 4 –	Burr-Brown Uncertainty Analysis for Mode Converter for 0-5 Volt Input	l ADS7825 A/D [4 pages]

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Rev.	Date	Pages Involved	Description	Originator
0	02/02/09	All	Initial Issue	R.A. Hunter
1	04/15/09	All	Revised to include the uncertainties of the LEFM system, to address the total uncertainty of the digital indication. Changed the approach for determination of PMEb. Consolidated Assumptions 6.1 and 6.5 into Assumption 6.1. Added Attachments 2, 3, 4.	K. R. Melson

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## 1.0 <u>PURPOSE</u>

The purpose of this calculation is to determine the total loop uncertainty of Main Feedwater pressure digital indications for the Caldon CheckPlus LEFM and Plant Computer.

Uncertainties are calculated for normal operating (non-harsh) conditions only.

## 2.0 COMPONENT LISTING

This calculation applies to the following instruments:

Main Feedwater Pressure Transmitters

1-PT-1131A, B

2-PT-1131A, B

I/E Converters

1I/E1C209A, B

2I/E2C209A, B

A/D Converters

1M/P1C209A1, B1

2M/P2C209A1, B1

LEFM Electronic Unit

1CPU1C209A1, B1

2CPU2C209A1, B1

1M/P1C209A2, B2 2M/P2C209A2, B2

1-PT-1141A, B

2-PT-1141A, B

1I/E1C209E, F

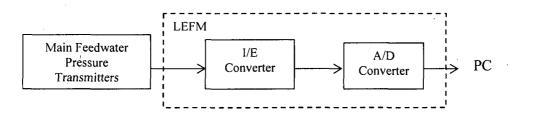
2I/E2C209E, F

1CPU1C209A2, B2 2CPU2C209A2, B2

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## 3.0 FIGURE



Note: The loop configuration is determined from Reference 7.9 and Assumption 6.9.

## 4.0 METHOD OF ANALYSIS

This calculation is performed in accordance with ES-028, Instrument Loop Uncertainty / Setpoint Methodology. This calculation utilizes the Square Root Sum of the Squares (SRSS) methodology when all variables are random, independent and normally distributed. Bias uncertainties are combined algebraically with random uncertainties.

This calculation determines device uncertainties for the Main Feedwater pressure transmitters, I/E converters, and A/D converters and then combines these uncertainties to determine the total loop uncertainty for the digital indication of the LEFM. The error in this digital indication is the same as in the plant computer, since the signal is passed to the plant computer via a digital link.

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## 5.0 **DESIGN INPUTS**

# 5.1 MAIN FEEDWATER PRESSURE SENSOR CONSIDERATIONS (Subscript: s)

TAG NUMBER:	1(2)-PT-1131A, B	[7.2]
	1(2)-PT-1141A, B	
MANUFACTURER:	Rosemount	[7.2]
MODEL NUMBER:	3051CG5	[7.2]
SPAN:	0 to 1300 psig	[7.2]
UPPER RANGE LIMIT	2000 psig	[7.1]
(URL)		

5.1.1 Per References 7.1, the Reference Accuracy for Range Code 5 transmitters with a turn down ratio (ratio of URL to Span) of less than 10:1 is ± 0.065% Span. Per Reference 7.1, URL for these transmitters is 2000 psig. Per Reference 7.2, span for these transmitters is 1300 psig, yielding a turn down ratio of 1.54:1 (result of 2000 /1300). Therefore, the sensor Reference Accuracy (RAs) is given as:

 $RA_S = \pm 0.065\%$  Span

5.1.2 Per Reference 7.2, the setting tolerance for these sensors is  $\pm 0.25\%$  Span. Therefore, the Sensor Setting Tolerance (ST<sub>S</sub>) is:

 $ST_{S} = \pm 0.250\%$  Span

5.1.3 For conservatism, and to provide flexibility in the choice of test equipment, the Sensor Measurement and Test Equipment Effect ( $MTE_S$ ) is set equal to the sensor setting tolerance ( $ST_S$ ). Therefore,

 $MTE_s = \pm 0.250\%$  Span

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5.1.4 The Drift term (DR<sub>s</sub>) is given in Reference 7.1 as  $\pm$  0.125% URL for 5 years with temperature variation limited to within  $\pm$  50°F, and up to 1000 psi line pressure. Reference 7.1 shows URL for range code 5 transmitters is 2000 psi. Per Reference 7.3, Turbine Building Maximum / Minimum design temperatures are 110°F / 60°F, respectively, ensuring that maximum temperature variation is bounded by  $\pm$ 50°F. Line pressure effects are only applicable to differential pressure transmitters. Therefore, the Sensor Drift (DR<sub>s</sub>) is given as:

$$DR_{s} = \pm \left(\frac{0.125\% X \ 2000 \text{ psi}}{1300 \text{ psi}} \ X \ 100\% \text{ Span } X \ \frac{50°F}{50°F}\right)\% \text{ Span}$$

 $DR_S = \pm 0.192\%$  Span

5.1.5 Per Reference 7.1, the Sensor Temperature Effect (TE<sub>s</sub>) is given as ± (0.0125% URL + 0.0625% Span) per 50°F for Range Code 5. Per Reference 7.1, URL for range code 5 transmitters is 2000 psi. Per Reference 7.3, Turbine Building Minimum / Maximum design temperatures are 60°F / 110°F, respectively. Using Minimum / Maximum temperatures for calibration temperature and normal operating temperature ensures that maximum temperature variation (±50°F) is considered in determination of TES. Therefore, the Sensor Temperature Effect (TE<sub>s</sub>) is given as:

$$TE_s = \pm (0.0125\% \text{ URL} + 0.0625\% \text{ Span}) X \frac{50^\circ \text{F}}{50^\circ \text{F}}$$

$$TE_{S} = \pm \left[ \frac{0.0125\% \text{ X } 2000 \text{ psi}}{1300 \text{ psi}} + 0.0625\% \text{ Span} \right] \text{ X } \frac{50^{\circ} \text{ F}}{50^{\circ} \text{ F}}$$

 $TE_S = \pm 0.082\%$  Span

5.1.6 Per Reference 7.1, Sensor Power Supply Effect ( $PSE_S$ ) is less than  $\pm$  0.005% Span per volt variation. Reference 7.4 states that, for DC power supplies, considering a 5 volt variation in power supply voltage is conservative. Therefore  $PSE_S$  is determined as follows:

$$PSE_{S} = \pm \frac{0.005\% Span}{voltDC} X 5 voltsDC$$

 $PSE_S = \pm 0.025\%$  Span

Per Reference 7.4, uncertainties less than  $\pm 0.050\%$  are considered negligible. Therefore,

$$PSE_S = N/A$$

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5.1.7 Per Reference 7.1, Sensor Vibration Effect (VE<sub>S</sub>) is negligible except at resonant frequencies. When at resonant frequencies, vibration effect is less than  $\pm$  0.1% of URL per g when tested between 15 and 2000 Hz in any axis relative to pipe-mounted process conditions. Per Assumption 6.2, vibration is bounded by 1 g at the test conditions described. Per Reference 7.1, URL for range code 5 transmitters addressed in this calculation is 2000 psi. Reference 7.2 shows calibrated span for these transmitters is 1300 psig. Therefore VE<sub>S</sub> is determined as follows:

 $VE_{S} = \pm \frac{0.1\% X 2000 \, \text{psi}}{1300 \, \text{psi}}$ 

 $VE_8 = \pm 0.154\%$  Span

5.1.8 Per Reference 7.1, Sensor RFI Effects (RFI<sub>S</sub>) is  $\pm$  0.1% Span from 20 to 1000 MHz and for field strength up to 30 V/m. Per Assumption 6.3, transmitters addressed in this calculation are not exposed to RFI conditions beyond the limits stated in the specification. Therefore:

 $RFI_S = \pm 0.100\%$  Span

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ΓAG NUMBER:	1I/E1C209A, B, E, F	
	2I/E2C209A, B, E, F	
MANUFACTURER:	Analog Devices	
MODEL NUMBER:	5B32	a .
SPAN:	4 to 20 mAdc	[7.1]
PROCESS SPAN:	(0 to 1300 psig)	[7.2]
OUTPUT SPAN:	0-5 Vdc	[7.6]

Per Reference 7.6, the initial accuracy at +25°C for the I/E Converters is  $\pm 0.05\%$ 5.2.1 Span  $\pm 0.05\%$  of I<sub>Z</sub>. The nonlinearity is defined as  $\pm 0.02\%$  Span. The accuracy of the input resistance (20  $\Omega$ ) is shown to be  $\pm 0.1\%$ . The accuracy of the input resistance is converted to percent of span at the highest input reading. This calculation conservatively computes Reference Accuracy, based on the combination of all these terms, via addition. The Converter 1 Reference Accuracy  $(RA_{P1})$  is computed as follows.

ACC<sub>RES</sub> = Accuracy of Input Resistance

$$ACC_{RES} = \pm 0.1\% \times \left(\frac{20 \text{ mAdc}}{(20 \text{ mAdc} - 4 \text{ mAdc})}\right) = \pm 0.125\% \text{ Span}$$

 $I_z = 4 \text{ mAdc}$ 

0.05% of  $I_z = 0.0005 \times 4 \text{ mAdc} \times \left(\frac{100\% \text{ Span}}{(20 \text{ mAdc} - 4 \text{ mAdc})}\right) = 0.0125\% \text{ Span}$ 

A<sub>INIT</sub> = Initial Accuracy

 $A_{\text{INIT}}$  =  $\pm 0.05\%$  Span  $\pm 0.05\%$  of I\_{Z} (Conservatively Add) A<sub>INIT</sub> = ±0.05% Span + 0.0125% Span = ±0.0625% Span

 $\mathsf{RA}_{\mathsf{P1}} = \pm (0.0625 + 0.02 + 0.125)$ 

 $RA_{P1} = \pm 0.208\%$  Span

Per Reference 7.4, the setting tolerance for these converters is set equal to the 5.2.2 Reference Accuracy, since MCDS sheets do not yet exist. Therefore, the Converter 1 Setting Tolerance  $(ST_{P1})$  is:

$$ST_{P1} = \pm 0.208\%$$
 Span

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5.2.3 For conservatism, and to provide flexibility in the choice of test equipment, the Sensor Measurement and Test Equipment Effect ( $MTE_{P1}$ ) is set equal to the Converter 1 Setting Tolerance ( $ST_{P1}$ ). Therefore,

 $MTE_{P1} = \pm 0.208\%$  Span

5.2.4 Per Assumption 6.6, Reference 7.6 does not provide a time-dependent drift specification for the I/E converter, and no historical data is available for analysis. This device is a modern electronic module used for high accuracy situations; and drift should be near zero. Therefore, the drift term for these converters is conservatively set equal to the Reference Accuracy term. The Converter 1 Drift (DR<sub>P1</sub>) is defined:

$$DR_{P1} = \pm 0.208\%$$
 Span

5.2.5 Per Reference 7.6, there are four (4) terms relating to temperature effect. This calculation conservatively computes temperature effect, based on the combination of all these terms, via addition. Note that the LEFM  $\sqrt{+}$  cabinets are air-conditioned and maintained within an approximate 10°F band, however, for conservatism, this calculation computes the I/E converter temperature effect, based on room temperatures without air conditioning. Per Reference 7.3, Turbine Building Minimum / Maximum design temperatures are 60°F / 110°F, respectively. Using Minimum / Maximum temperature ensures that maximum temperature variation (±50°F) is considered in determination of TE<sub>P1</sub>. Therefore, the Converter 1 Temperature Effect (TE<sub>P1</sub>) is computed as follows:

TE<sub>IO</sub> = Input Offset vs. Temp

$$TE_{IO} = \pm 0.0025\% \text{ of } Iz / °C \times \left(\frac{4 \text{ mAdc}}{(20 \text{ mAdc} - 4 \text{ mAdc})}\right) = \pm 0.000625\% \text{ Span} / °C$$

 $TE_{00} = Output Offset vs. Temp$ 

 $TE_{OO} = \pm 20 \ \mu V / °C \times \left(\frac{100\% \text{ Span}}{5 \text{ Vdc}}\right) \times \left(\frac{1 \text{ Vdc}}{1,000,000 \ \mu \text{ Vdc}}\right) = \pm 0.0004\% \text{ Span} / °C$ 

 $TE_{G} = Gain \text{ vs. Temp}$   $TE_{G} = \pm 0.0025\% \text{ of Reading / °C (Considered Applied as Input Specification)}$   $TE_{G} = \pm 0.0025\% \text{ Span / °C} \times \left(\frac{20 \text{ mAdc}}{(20 \text{ mAdc} - 4 \text{ mAdc})}\right) = \pm 0.003125\% \text{ Span / °C}$ 

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 $TE_{SR}$  = Stability vs. Temp for Input Resistor

$$TE_{SR} = \pm 0.001\% / °C \times \left(\frac{20 \text{ mAdc}}{(20 \text{ mAdc} - 4 \text{ mAdc})}\right) = \pm 0.00125\% \text{ Span} / °C$$
  

$$TE = \pm (TE_{IO} + TE_{OO} + TE_{G} + TE_{SR})$$
  

$$TE = \pm (0.000625 + 0.0004 + 0.003125 + 0.00125)$$
  

$$TE_{P1} = \pm 0.0054\% \text{ Span} / °C \times \left(\frac{1°C}{1.8°F}\right) \times 50°F$$

 $TE_{P1} = \pm 0.150\%$  Span  $\sim$ 

5.2.6 Per Reference 7.6, the Converter 1 Power Supply Effect (PSE<sub>P1</sub>) is defined by power supply sensitivity of  $\pm 2\mu V/Vs\%$ , with a required power supply voltage of 5 Vdc  $\pm 5\%$ . Conservatively using the worst case voltage variation specified for the module of  $\pm 5\%$  (Assumption 6.7), the PSE<sub>P1</sub> is determined as follows:

$$\mathsf{PSE}_{\mathsf{P1}} = \pm \left(\frac{2\mu\mathsf{Vdc}}{\mathsf{V}_{\mathsf{S}}\,\%}\right) \times 5\% \times \left(\frac{1\,\mathsf{Vdc}}{1,000,000\,\mu\mathsf{Vdc}}\right) \times \left(\frac{100\%\,\mathsf{Span}}{5\,\mathsf{Vdc}}\right)$$

$$PSE_{P1} = \pm 0.0002\%$$
 Span

Per Reference 7.4, uncertainties less than  $\pm 0.050\%$  Span are considered negligible. Therefore,

 $PSE_{P1} = N/A$ 

5.2.7 Per Reference 7.6, the Converter 1 RFI Effect (RFI<sub>P1</sub>) is defined by RFI Susceptibility, ± 0.5% Span error @ 400 MHz, 5 Watts, at 3 feet. Per Assumption 6.8, the converters addressed in this calculation are not exposed to RFI conditions beyond the limits stated in the specification. Therefore:

 $RFI_{P1} = \pm 0.500\%$  Span

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#### 5.3 A/D CONVERTER CONSIDERATIONS (Subscript: P2)

		4
TAG NUMBER:	1M/P1C209A1, A2, B1, B2	
	2M/P2C209A1, A2, B1, B2	
MANUFACTURER:	Burr Brown	n
MODEL NUMBER:	ADS7825	
SPAN:	0 to 5 Vdc	[7.6]
PROCESS SPAN:	(0 to 1300 psig)	[7.2]

5.3.1 Reference 7.7 provides the uncertainty specifications for the Burr Brown A/D converters. However, Reference 7.8 is the accuracy analysis as provided by the vendor for these devices, when using an input span of 0 to 5 Vdc. The output of this analysis is the overall accuracy for the A/D converters. Per Reference 7.8, the overall uncertainty value is derived as  $\pm$  17.5 mVdc. The Overall Accuracy of the A/D Converter (ACC<sub>P2</sub>) is computed as follows.

$$ACC_{P2} = \pm 17.5 \text{ mVdc} \times \left(\frac{100\% \text{ Span}}{5 \text{ Vdc}}\right) \times \left(\frac{1 \text{ Vdc}}{1000 \text{ mVdc}}\right)$$
$$ACC_{P2} = \pm 0.350\% \text{ Span}$$

In order to ensure that adequate temperature effects, etc., have been considered, an extra degree of conservatism is added, and  $\pm 0.400\%$  Span will be used for the Total Device Uncertainty of the A/D Converter (TDU<sub>P2</sub>). (Note that the LEFM  $\sqrt{+}$  cabinets are air-conditioned and maintained within an approximate 10°F band, so additional temperature effect uncertainties should not be present outside the uncertainty analysis of Reference 7.8.)

 $TDU_{P2} = \pm 0.400\%$  Span

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## 5.4 PROCESS MEASUREMENT EFFECT CONSIDERATIONS

Not all of the transmitters addressed in this calculation are installed (as of Revision 1 issue), making precise determination of PMEb impossible at this time. However, based on Assumption 6.1, an elevation difference of 30 feet can be used to quantify a bounding PMEb for use in this calculation. This process requires that transmitter calibration offsets be calculated and applied as stipulated on Reference 7.2. Per Assumption 6.4 this will be done prior to the initial calibration of each transmitter.

Reference 7.2 uses a conversion factor of  $0.0361 \text{ psig} / \text{inH}_2\text{O}$  to calculate offset. Multiplying the conversion factor by  $(12 \text{ in})^3 / \text{ft}^3$  yields the actual calibration density, 62.3808 lbm/ft<sup>3</sup>.

The following equation is used to calculate the PMEb due to sensing line density variations:

$$PMEb = \left(\frac{h(\rho_N - \rho_C)}{144}\right) \left(\frac{100\% \text{ Span}}{1300 \text{ psi}}\right)$$
[EQ-1]

where,

h = height of sensing line in feet (30 ft. per Assumption 6.1)

1300 psi = transmitter span

 $\rho_{\rm N}$  = assumed sensing line fill fluid density during normal operation

 $\rho_{C}$  = assumed sensing line fill fluid density to determine bounding calibration offset

NOTE: The factor 144 is used to convert from  $lbf/ft^2$  to  $lbf/in^2$ . At standard gravity, lbf may be replaced with lbm.

Per Reference 7.3, the design minimum temperature is 60°F and the design maximum temperature is 110°F in the area where the transmitters and sensing lines are located. To ensure the most conservative result, 60°F is considered calibration temperature and 110°F is the maximum temperature during normal conditions. A conservative process pressure of 1000 psia is used for density determinations.

$\rho_N @ 110^{\circ}F / 1000 \text{ psia} =$	62.04833 lbm/ft <sup>3</sup>	Reference 7.5
$\rho_C$ @ 60°F / 1000 psia =	62.56809 lbm/ft <sup>3</sup>	Reference 7.5

Note that the calibration density determined above (62.3808 lbm/ft<sup>3</sup>) is bounded by these conservative densities  $\rho_{N_s}$  and  $\rho_{C_s}$ .

Substituting values in Eq. 1 yields:

$$PMEb = \left(\frac{30(62.04833 - 62.56809)}{144}\right) \left(\frac{100\% \text{ Span}}{1300 \text{ psi}}\right)$$

PMEb = -0.008% Span

Per Reference 7.4, uncertainties less than  $\pm 0.050\%$  Span are considered negligible. Therefore:

PMEb = N/A

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## 6.0 ASSUMPTIONS

- 6.1 **UNVERIFIED ASSUMPTION** It is assumed that a Unit 1 LEFM plant modification will be implemented using the same converters, transmitters, transmitter calibrations, and configurations as presented in this calculation. In addition it is assumed that the vertical distance between transmitter centerline and process tap for the Unit 1 transmitters will not exceed 30 feet.
- 6.2 It is assumed that pipe mounted process vibrations for the transmitters addressed in this calculations are limited to 1 g between 15 and 2000 Hz in any axis.
- 6.3 It is assumed that transmitter RFI at the location of all transmitters addressed in this calculation is limited to 20 to 1000 MHz, and field strength of 30 V/m.
- 6.4 It is assumed that transmitter head correction (calibration values offset) is calculated and applied as part of the initial calibration of each transmitter addressed in this calculation, in accordance with the procedure stipulated in Reference 7.2.
- 6.5 Not used
- 6.6 Reference 7.6 does not provide a time-dependent drift specification for the I/E converter, and no historical data is available for analysis. This device is a modern electronic module used for high accuracy situations; and drift should be near zero. Therefore, the drift term for these converters is conservatively set equal to the Reference Accuracy term.
- 6.7 It is assumed that the worst case power supply variation supplied to Converter 1 is  $\pm 5\%$  of the supply voltage. This is considered conservative, since this is the worst case power variation allowed by the device specifications.
- 6.8 It is assumed that Converter 1 RFI at the location of the Caldon hardware addressed in this calculation is limited to 400 MHz, 5 Watts, 3 feet from the c device.
- 6.9 The loop configuration is assumed to consist of the transmitter, I/E converter, and A/D converter, as presented in Section 3.0. This is based on the Unit 2 schematic drawings, Reference 7.9. It is assumed that this configuration will be as built for Units 1 and 2.

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#### 7.0 <u>REFERENCES</u>

- 7.1 Rosemount 3051 Product Data Sheet 00813-0100-4001, Rev. HA, March 2008 (excerpt included in this calculation as Attachment 1)
- 7.2 BGE Master Calibration Data Sheets (MCDS's):

COMPONENT	REVISION
1-PT-1131A	0*
1-PT-1131B	0*
1-PT-1141A	0*
1-PT-1141B	0*
2-PT-1131A	0
2-PT-1131B	0
2-PT-1141A	0
2-PT-1141B	0

\*Unit 1 MCDS's not yet produced (see Assumption 6.1). Initial issue for these new instruments will be Rev. 0.

- 7.3 BG&E Updated Final Safety Analysis Report, Table 9-18, Revision 38
- 7.4 Calvert Cliffs Engineering Standard ES-028, "Instrument Loop Uncertainty and Setpoint Methodology", Revision 1
- 7.5 ASME Steam Tables, 1967
- 7.6 Specifications for Analog Devices Single-Channel Signal Conditioning Module 5B32, printed from the <u>http://analog.com</u> website on 4/9/2009, including email clarification, dated 4/13/2009 (Attachment 2)
- 7.7 Burr-Brown Product Data Sheet PDS-1304B for ADS7825 4 Channel, 16-Bit Sampling CMOS A/D Converter, October 1997 (Excerpt included as Attachment 3)
- 7.8 Burr-Brown Uncertainty Analysis for Model ADS7825 A/D Converter for 0-5 Volt Input (Attachment 4)
- 7.9 Cameron Drawing 9A-202B796, "Electronics Unit LEFM  $\sqrt{+}$  Schematic," Sheets 1 (Rev. 02), 8 (Rev. 02), 9 (Rev. 02), and 12 (Rev. 02)

## 8.0 IDENTIFICATION OF COMPUTER CODES

NONE

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## 9.0 CALCULATION

This calculation determines the Total Device Uncertainty (TDU) and Segment Uncertainty (LU) for Main Feedwater Pressure transmitters that provide input to the LEFM.

## 9.1 TOTAL DEVICE UNCERTAINTIES

#### Main Feedwater Pressure Transmitter Uncertainty

The normal uncertainties associated with the sensor  $(TDU_S)$  are given as:

$$\Gamma DU_{S} = \pm \sqrt{RA_{s}^{2} + ST_{s}^{2} + MTE_{s}^{2} + DR_{s}^{2} + TE_{s} + VE_{s}^{2} + RFI_{s}^{2}}$$

 $TDU_S = \pm 0.454$  % Span

#### I/E Converter Uncertainty

The normal uncertainties associated with the I/E converter  $(TDU_{P1})$  are given as:

$$TDU_{P1} = \pm \sqrt{RA_{P1}^{2} + ST_{P1}^{2} + MTE_{P1}^{2} + DR_{P1}^{2} + TE_{P1} + RFI_{P1}^{2}}$$

 $TDU_{P1} = \pm 0.667$  % Span

#### A/D Converter Uncertainty

The normal uncertainties associated with the A/D converter  $(TDU_{P2})$  are directly provided in Section 5.3.1:

 $TDU_{P2} = \pm 0.400$  % Span

#### 9.2 SEGMENT UNCERTAINTIES

The calibration procedures for this instrument loop have not been developed. Therefore, one segment is analyzed per device. Therefore loop segment uncertainty (LU) is equal to TDU. Accordingly, LU terms are presented below with results in % Span units and in engineering units (psi), based on a calibrated span of 0 to 1300 psi.

#### Segment 1: Sensor

The segment uncertainty (LU1) is given as:

 $LU1 = \pm TDU_s$ , therefore:

 $LU1 = \pm 0.454\%$  Span =  $\pm 5.902$  psi

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## Segment 2: I/E Converter

The segment uncertainty (LU2) is given as:

 $LU2 = \pm TDU_{P1}$ , therefore:

 $LU2 = \pm 0.667\%$  Span =  $\pm 8.671$  psi

### Segment 3: A/D Converter

The segment uncertainty (LU3) is given as:

 $LU3 = \pm TDU_{P2}$ , therefore:

 $LU3 = \pm 0.400\%$  Span =  $\pm 5.200$  psi

## 9.3 TOTAL LOOP UNCERTAINTY

The Total Loop Uncertainty for the Main Feedwater Pressure digital indication is computed from combining the Total Device Uncertainties from the transmitter, I/E converter and A/D converter. The TLU term is presented below with results in % Span units and in engineering units (psi), based on a calibrated span of 0 to 1300 psi.

$$TLU = \pm \sqrt{TDU_{s}^{2} + TDU_{P1}^{2} + TDU_{P2}^{2}}$$

 $TLU = \pm 0.901\%$  Span =  $\pm 11.713$  psi

#### 10.0 <u>CONCLUSIONS</u>

The total device uncertainty (TDU<sub>s</sub>) and segment uncertainty (LU1) for the Main Feedwater Pressure transmitters are as follows:

 $TDU_{S} = \pm 0.454\%$  Span =  $\pm 5.902$  psi

LU1 =  $\pm 0.454\%$  Span =  $\pm 5.902$  psi

The total device uncertainty (TDU<sub>P1</sub>) and segment uncertainty (LU2) for the Main Feedwater Pressure I/E converters are as follows:

 $TDU_{P1} = \pm 0.667\%$  Span =  $\pm 8.671$  psi

LU2 =  $\pm 0.667\%$  Span =  $\pm 8.671$  psi

The total device uncertainty  $(TDU_{P2})$  and segment uncertainty (LU3) for the Main Feedwater Pressure A/D converters are as follows:

 $TDU_{P2} = \pm 0.400\%$  Span =  $\pm 5.200$  psi

 $LU3 = \pm 0.400\%$  Span =  $\pm 5.200$  psi

The total loop uncertainty (TLU) for the Main Feedwater Pressure digital indications on the Caldon LEFM  $\sqrt{+}$  system and the Plant Computer are as follows:

 $TLU = \pm 0.901\%$  Span =  $\pm 11.713$  psi

## ATTACHMENTS

Attachment 1 –	Excerpt from Rosemount 3051 Product Data Sheet 00813-0100-4001,		
	Rev. HA, March 2008	[4 pages]	
Attachment 2 –	Specifications for Analog Devices Single-Cl	hannel Signal Conditioning	
	Module 5B32, printed from the http://analog	<u>s.com</u> website on 4/9/2009,	
	including email clarification, dated 4/13/200	)9 [5 pages]	
Attachment 3 –	Excerpt from Burr-Brown Product Data She	et PDS-1304B for	
	ADS7825 4 Channel, 16-Bit Sampling CMC	OS A/D Converter, October	
	1997	[3 pages]	
Attachment 4 –	Burr-Brown Uncertainty Analysis for Mode	ADS7825 A/D Converter	
	for 0-5 Volt Input	[4 pages]	

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## Rosemount 3051

Product Data Sheet 00813-0100-4001, Rev HA March 2008

## **Specifications**

#### PERFORMANCE SPECIFICATIONS

Total Performance is based on combined errors of reference accuracy, ambient temperature effect, and static pressure effect. This product data sheet covers both HART and fieldbus protocols unless specified.

#### Conformance To Specification (±3σ (Sigma))

Technology leadership, advanced manufacturing techniques and statistical process control ensure specification conformance to at least ±3σ.

Models	Standard	High Accuracy Option
3051CD, 3051CG	· · · · ·	
Range 0 (CD)	±0.10% of span	
	For spans less than 2:1, accuracy =	•
<b>D</b> 4	±0.05% of URL	
Range 1	±0.10% of span For spans less than 15:1, accuracy =	
	$\pm \left[0.025 + 0.005 \left(\frac{URL}{Span}\right)\right]$ % of Span	
Ranges 2-5	±0.065% of span - For spans less than 10:1, accuracy =	Ranges 2-4 High Accuracy Option, P8
		±0.04% of span
	$\pm \left[ 0.015 \pm 0.005 \left( \frac{URL}{Span} \right) \right]$ % of Span	For spans less than 5:1, accuracy =
	•	±[0.015 + 0.005( $\frac{URL}{Span}$ ]% of Span
3051T		<b>NY NA GRAN</b>
Ranges 1-4	±0.065% of span	Ranges 2-4
an an an Anna an Anna Anna Anna Anna An	For spans less than 10:1, accuracy =	High Accuracy Option, P8
	1 0.0075(URL) % of Span	For spans less than 5:1, accuracy =
	Span']	galer de cienta de la compañía de la
	en se ve het het de se	±[0.0075( <u>URL</u> ]% of Span
		en e
Range 5	±0.075% of span	
이 많은 것을 알았는	For spans less than 10:1, accuracy = .	
	t 0.0075(URL) % of Span	
	Span/J	
n në 1961 në fotorogjanë kar dhe 3051 CA	annette et de l'entrante la fantación de la companya	an a color terretari de contra da deservada
Ranges 1-4	±0,065% of span For spans less than 10:1, accuracy =	Ranges 2-4 High Accuracy Option, P8
		±0.04% of span
	$t \left[ 0.0075 \left( \frac{URL}{Span} \right) \right] \%$ of Span	For spans less than 511, accuracy m
		$a\left[0.0075\left(\frac{URL}{Span}\right)\right]\%$ of Span
3051H/3051L		
All Ranges	±0.075% of span For spans less than 10:1; accuracy =	
an an Arran an Albert An Arran an Anna Anna Anna An	i na kata kata kata kata kata kata kata k	
그 문서, 대한 이 관객을 통한 화태	±[0.025 + 0.005(URL)]% of Span	

(1) For FOURDATION fieldbus transmittens, use onlibrated range in place of spon. For zero based spans, returence ounditions, silicome oil fill, SST meteriale, Coplanan Rengo (3051G) or 72 in. - 18 NPT (30517) process counoctions, digital trim volues set to equal range points.

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Product Data Sheet 00813-0100-4001, Rev HA March 2008			F	Rosemount 3051
Total Performance				
and the second se	ire changes, up to 1000 psi (t	5,9 MPa) line pressun	e (CD only), from 1:1	ta 5:1 rangedown.
Models	Total Performance			
3051C				
3051T	±0.15% of span ±0.15% of span			
Long Term Stability				
Models	Long Term Stability	1 1 1	ļ	
3051C			· · · ·	
Ranges 2-5	±0.125% of URL for 5 years ±50 *F (28 *C) temperature		000 nsi (6 9 MPa) Br	10 119351/0
3051CO Low/Draft Range				
	±0.2% of URL for 1 year			
3051T	"	a town of and then the con-	Same of the mean-sector of	Augus o arteriaerte a ser a construintenziatar anta e a a
Ranges 1-4	±0.125% of URL for 5 years			
	±50 °F (28 °C) temperature	changes, and up to 1	000 ps: (6,9 MPa) ir	10 prossure. De successioner de la marchanarie and the
Rosemount 3051H	±0.1% of URL for 1 year		요즘 안 같은 것은 것이다.	
	±0.2% of URU for 1 year			
Dynamic Performance				
	4 - 20 mA (HART protocol) <sup>(1)</sup>	Fleidbus protocol <sup>(3)</sup>	Typical H	ART Transmitter Response Time

(HART protocol) <sup>(1)</sup> protocol <sup>(3)</sup>	Typical HART Transmitter Response Tin
Total Response Time (T <sub>d</sub> + T <sub>c</sub> ) <sup>(2)</sup> : 3051C, Ranges 2-5; 100 ms	TEREPRES
Range 11, 255 ms 307 ms Range 0, 700 ms 752 ms 3051T, 100 ms 152 ms	Transmitter Output vs. Time
3051H/L: Consult factory Consult fa Dead Time (Td) 45 ms (nominal) 97 ms	Clory
Update Rate 22 times per second 22 times p (1) Dead lines and update release pply to all models and ranges; preside output of	er second : Response Time = T <sub>d</sub> +T
<ul> <li>(1) Determined and approve the apply to be involved and intriger, binding output of (2) Norminal lotal response time at 75 °F (24 °C) reference conditions.</li> </ul>	352 S Bac Charge

Line Pressure Effect per 1000 psi (6,9 MPa) For line pressures above 2000 psi (13.7 MPa) and Ranges 4-5, see user manual (Rosemount publication number 00809-0100-4001).

Madels	Line Pressure Effect
3051CD	Zero Error <sup>(1)</sup>
Range 0	±0.125% of URL/100 psi (6.89 ba/)
Range 1	±0.25% of URL/1000 psi (68.9 bar)
Ranges 2-3	±0.05% of URL/1000 psi (68.9 bar) for line pressures from 0 to 2000 psi (0 to 13.7 MPa)
	Span Error
Range 0	±0.15% of reading/100 psi (6,89 bar)
Range 1	±0.4% of reading/1000 psi (68,9 bar)
Ranges 2-3	±0.1% of reading/1000 psi (68,9 bar)
3051HD	Zero Error <sup>(1)</sup>
All Ranges	±0.1% of URL/1000 psi (68.9 bar) for line pressures from 0 to 2000 psi (0 to 13.7 MPa)
	Span Error
All Ranges	±0.1% of reading/1000 psi (58.9 bar)

(1) Cen be calibrated out at line pressure.

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2,

#### **Product Data Sheet** 00813-0100-4001, Rev HA Rosemount 3051 March 2008 Ambient Temperature Effect per 50°F (28°C) Amblent Temperature Effect dodels 3051CD/CG Range 0 ±(0.25% URL + 0.05% span) Range 1 ±(0.1% URL + 0.25% span) Ranges 2-5 ±(0.0125% URL + 0.0625% span) from 1:1 to 5:1 ±(0.025% URL + 0.125% span) from 5:1 to 100:1 30517 Range 1 ±(0.025% URL + 0.125% span) from 1:1 to 10:1 ±(0.05% URL + 0.125% span) from 10:1 to 100:1 Range 2-4 ±(0.025% URL + 0.125% span) from 1:1 to 30:1 ±(0.035% URL + 0 125% span) from 30:1 to 100 1 Range 5 ±(0.1% URL + 0.15% span) 3051CA All Ranges ±(0.025% URL + 0.125% span) from 1:1 to 30:1 ±(0.035% URL + 0.125% span) from 30:1 to 100:1 3051H All Ranges ±(0.025% URL + 0.125% span + 0.35 inH2O) from 1:1 to 30:1. #(0.035% URL + 0.125% span + 0.35 inH2O) from 1:1 to 30:1 3051L See Rosemount Inc. Instrument Toolkit® software **Mounting Position Effects** Models Mounting Position Effects 3051C Zero shifts up to ±1.25 inH2O (3.11 mbar), which can be calibrated out. No span effect 3051H Zero shifts up to ±5 inH2O (12,43 mbar), which can be calibrated out. No span effect. With liquid level diaphragm in vert cal plane, zero shift of up to 1 inH2O (2.49 mbar). With diaphragm in horizontal plane, zero shift of up to 5 inH2O (12.43 mbar) plus extension length on extended units. All zero shifts can be calibrated out. No span effect. 3051L 3051T/CA **Vibration Effect** Transient Protection (Option Code T1) All Models: All Models Meets IEEE C62.41, Category B Measurement effect due to vibrations is negligible except at 6 kV crest (0,5 µs - 100 kHz) 3 kV crest (8 × 20 microseconds) resonance frequencies. When at resonance frequencies, vibration effect is less than ±0.1% of URL per g when tested between 15 6 kV crest (1.2 × 50 microseconds) and 2000 Hz in any axis relative to pipe-mounted process Meets IEEE C37.90.1, Surge Withstand Capability conditions. SWC 2.5 KV crest, 1,25 MHz wave form **Power Supply Effect** General Specifications: Response Time: < 1 nenosecond All Models Peak Surge Current: 5000 amps to housing Peak Transient Voltage: 100 V dc Loop Impedance: < 25 ohms Less than ±0.005% of calibrated span per volt. Applicable Standards: IEC61000-4-4, IEC61000-4-5 **RFI Effects** All Models NOTE: Calibrations at 68 °F (20 °C) per ASME Z210.1 (ANSI) ±0.1% of span from 20 to 1000 MHz and for field strength up to 30 V/m

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Product Data Sheet 00813-0100-4001, Rev HA March 2008

## Rosemount 3051

#### FUNCTIONAL SPECIFICATIONS

#### Range and Sensor Limits

TABLE 1. 3051CD, 3051CG, 3051L, and 3051H Range and Sensor Limits

	Minimu	m Span			Range and Se	nsor Limits		
Range				,	Lower (	LRL)		
Ra	3051CD <sup>(1)</sup> , CG, L, H	Upper (URL)	3051C Differential	3051C/ Gage	3051L Differential	3051L Gage	3051H Differential	3051H Gage
0	0,1 inH <sub>2</sub> O (0,25 mbar)	3.0 inH <sub>2</sub> O (7,47 mbar)	-3.0 inH <sub>2</sub> O (-7,47 mbar)	NA	NA	NA	NA	NA
1	0.5 inH <sub>2</sub> O (1.2 mbar)	25 inH <sub>2</sub> O (62,3 mbar)	-25 nH <sub>2</sub> O (-62 1 mbar)	-25 inH <sub>2</sub> O (-62,1 mbar)	NA	NA	NA	NA
2	2.5 inH <sub>2</sub> O (6.2 mbar)	250 inH <sub>2</sub> O (0.62 bar)	-250 inH <sub>2</sub> O (-0.62 bar)	-250 inH <sub>2</sub> O (-0.62 bar)	-250 inH2O (-0,62 bar)	-250 inH <sub>2</sub> O (-0.62 bar)	-250 nH2O (-0,62 bar)	-250 inH <sub>2</sub> O (-0,62 bar)
3	10 inH <sub>2</sub> O (24,9 mbar)	1000 InH <sub>2</sub> O (2,49 bar)	-1000 inH20	0.5 psia (34,5 mbar abs)	-1000 nH2O	(-0.02 dar) (0.5 psia (34,5 mbar abs)	-1000 inH2O	0.5 psla (34,5 mbar abs)
4	3 psi	300 psi	300 psi	0.5 psia	-300 ps	0.5 psia	-300 ps	0.5 psa
5	(0,20 bar)	(20,6 bar) 2000 psi	- 2000 ps	(34,5 mbar abs) 0.5 psia	(20,6 bər) NA	(34,5 mbar abs)	(20,6 bar) 2000 psi	(34,5 mbar abs) 0.5 psia
122	(1,38 bar)	(137,9 bar)	(-137,9 bar)	(34,5 mbar abs)			(-137.9 bar)	(34,5 mbar abs)

(1) Ranga 0 city available with 3051CD. Rango 1 unity available with 3051CD or 3051CG

#### TABLE 2. Range and Sensor Limits

		3051CA		
0		Range and Se	ensor Limits	e Gue Minimum
Range	Minimum Span	Upper (URL)	Lower (LRL)	Minimum Span
1	0.3 psia	30 psia	0 psia	1 0.3 psi
	(20,6 mbar)	(2,07 bar)	(0 bar)	(20,6 mbar)
2	1.5 psia	150 psia	0 psia	2 1.5 psi
1999 - 1999 1999 - 1999	(0,103 bar)	(10,3 bar)	(0 bar)	(0,103 bar)
3	8 ps a	800 psia	0 psia	3 8 psi
	(0,55 bar)	(55.2 bar)	(0 bar)	(0,55 bar)
	40 ps a (2,76 bar)	4000 ps a (275.8 bar)	0 psia (0 bar)	4 40 ps (2,76 bar)

		3051	T	
ЭĞ,		Range and Se		
-Rar	Minimum Span	Upper (URL)	Lower (LRL)	Lower <sup>(1)</sup> (LRL) (Gage)
1	0.3 psi	30 psi	0 psia	-14.7 psig
	(20,6 mbar)	(2.07 bar)	(0 bar)	(1,01 bar)
	1:5 psi	150 psi	0 psia	-14.7 psig
	(0,103 bar)	(10,3 bar)	(0 bar)	(-1,01 bar)
3	8 psi	800 psi	0 psia	-14.7 psig
	(0,55 bar)	(55,2 bar)	(0 bar)	(1,01 bar)
	40 psi (2,76 bar)	4000 psi (275,8 bar)	0 psia (0 bar)	-14.7 psig (-1,01 bar)
5	2000 psi (137,9 bar)	10000 psi (689,4 bar)	0 psia (0 bar)	-14.7 psig (-1.01 bar)

(1) Assumes atmospheric pressure of 14.7 psig.

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5B32 Isolated Current Input | IOS Subsystems | Other | Analog Devices

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ANALOG DEVICES

#### 5B32 isolated Current input

(5) Strain Constant (S. Senier Medickaladina) ( Austrin's Station Machine 1 & Same Samuration and Manifest Control Form Statement Station ( OR Samu Strainguilet ( St. Same Const. Science Constant, Control Science, Science, 2013) (Science, 2014).

Specifications

Functional Description

The 5832 is a single-channel signal conditioning module that amplifies, protects, fitters and isolates its analog input. The module measures a process-current input signal of 4-20 mA or 0-20 mA by reading the voltage across an external precision 20 0 resistor (supplied) and generaling an output of 0 to +5 V. Extra current conversion resistors are available as accessories (See Model <u>ACL325</u>), in the Accessories section).

Note that the 5B32 module circuitry can withstand 240 V rms at the input screw-terminals, thereby strietiong computer-side circuitry from field-side overvotage conditions. In addition, all 5B32 Series modules are mix-andmatch and hot sweppable, so can be inserted or removed from any socket in the same backplane without powering down the system.

#### inside the 5032 Series Module

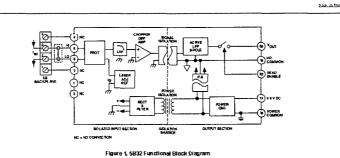
A chopper-stabilized input amplifier provides low critt and stable gain. At the amplifier input, a stable, laser-thmmed zero-scale input offset is subtracted from the input signal to set the zero-scale value for the 4-zo O AA rango. For user conversions, the zero can be optionably factory-set to meet custom needs. This allows suppression of a zero-scale med value and with wate mest interesting to the data gain of needs expended-scale measurements.

Internal multi-pole lowpass (fitsing with a four-Hz cutoff (-308) enhances normal-mode (noise on signa) and common-mode (noise on signa) return) rejection at 50/60 Hz, enabling accurate measurement of small signals in high electrical noise.

Signal isolation by transformer coupling uses a propriet any modulation technique for linear, stable and refacte performance. The differential input circuit on the field side is fully floating, eliminating the need for input grounding. A demodulator on the computer side of the signal transformer recovers the original signal, which is then fittered and buffered to provide a low-noise, low-impedance output signal. The output common must be kept within ±3 Vot of power common.

#### Convenience Features

A series output switch eliminates the need for external multiplexing in many applications. The switch is turned on by an active-low enable input. If the switch is to be on at all times, the enable-input should be prounded to power common as it is on the 5801 and 5808 <u>backgrass</u>.



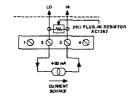
http://www.analog.com/en/other/ios-subsystems/products/cu\_5b32\_isolated\_current\_imput/... 4/9/2009

#### 5B32 Isolated Current Input | IOS Subsystems | Other | Analog Devices

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#### Figure 2. 5032 Input Field Connections

Input Ranges Output

4 mA to 20 mA

0 to +5 ∨ (-5 ∨ to +5 ∨ custom)

\_\_\_\_\_

5832 Models Available				_
	Madel	Input Range	Output Range	
(uteri Niew	5B32-01	4 mA to 20 mA	0 V to +5 V	
Didel Now	5832-02	0 mA to 20 mA	0 V to +5 V	1
	5B32 Custom	•		

\* Custom Input/Output ranges a

Refer to configuration and the

Description	Model 5832	
	lapat Ranges	
Standard Ranges	0 mA to 20 mA or 4 mA to 20 mA	
Custom R anges	0 mA to 20 mA (rater to ordering section)	
Output Rangias (R <sub>L</sub> > 50 kΩ) <sup>4</sup>	-5 V te+5 V or 0 V te+5 V	
	Accuracy <sup>2</sup>	
Initial @ +25°C	±0.05% Span ±0.05% iz <sup>1</sup>	
Nonlinearity	±002% Span	
Input Offset vs., Temperature	20.0025 of 12"C	
Oulput Offretvy. Temperature	±20 µ//*C	
Gain vs. Temperature	100025% of Reading*C	
	Input Resistor <sup>6</sup>	
Value	20.0 습	
Accuracy	±0.1%	
Stability vs. Temperature	10 001 %/°C	
	Noise	
Input 0.1 Hz is 10 Hz Bandwidth	10 nA ms	
Gutput, 100 kHz Bandwidth /	200 µV imp	
Bandwidth,-3 dB	4 Hz	
Dutput Rise Time, 10% to 90% Span	200 ms	
	Common-Mode Voltage (CMV) <sup>3</sup>	
Iapul-to-Output, Continuous	1500 V ime maximum	
Output-lo-Pawer, Continuous	±3.Vm.aximuth	

#### http://www.analog.com/en/other/ios-subsystems/products/cu\_5b32\_isolated\_current\_imput/... 4/9/2009

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## Attachment 2

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#### 5B32 Isolated Current Input | IOS Subsystems | Other | Analog Devices

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Trackera	ANSWERE C37 50 1-2989
	Common Mode Rejection (CMR)
1 KD Strate Homboor, SOMD 112	360.09
Normal Monte Protoban 50%0 Ke	60 ab
	input Protection
Construction	248 V ma masseries
traktaena	ANSALLE COLSO 1-1908
Ouser Reinzerze <sup>4</sup>	39.Q
Validade Overpul Proprision	Continuous Swint to System
Outual Servicion Free	600@C <sub>800</sub> > 0 to 7,000 pt
	Dulput Ensbie Cantrol
Mar Logix 107	-1 v
Minkopk Y	*2.5 ¥
N > FRANC, J.	、
Rogan Clutters "D"	C B KIJA
Power Suppy Votage	4 ¥ 2 % b
Power Supply Current	- 90 m.s.
Found Scoppy Actuationsy, 10th	#2 puvysis
Mitcharacial Dentempons	2 2751 v 2 3157 x 8 5985
•	(07.0 mmx 50.1 mm a 15.1 mm)
	Erivitormental
Temperatum Range	
Poors Perform Silve	-25°C to +85°C
(per Min)	-40°0 0 - 10°0
5100 a.30	-\$1°C (2) +35°C
Reistre turnicity	6 to 6 to 4 work approximation of
#Fi Successenter	of the Span enorgh and Mar, 5 Wat, 3 R

 $^{\rm 6}$  Ia is the nominal input current that results in a GV subject

 $^3$  includes the companed effects of repeatability, insteaders and normeanly and assumes  $R_{\rm c}$  a 30 i

 $^3$  The august common must be kept within all  $\vee$  of pawer common

4 Useds metwee then 30 kD will degrade remistie anty and gain temper alone been/cent.

<sup>4</sup> The context backspe conversion minimal (CC)(SD) is supplied as a project companies for mounting enders of the number of backspectration and an analysis of the second provide p

Spephadana subjets to phange without hoppy

995362.500 .

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## Attachment 2

Page 1 of 2

From: Date: To: Subject:	"Kellogg, Jim" <jim,kellogg@analo Monday, April 13, 2009 11:58 AM "Kirk Melson" <kirk.melson@excels RE: Specification Clarification for 58</kirk.melson@excels </jim,kellogg@analo 	ervices.com>					
Kirk,	RE. Specification Clanification for SE	502					
SB are con	ect about the Input Offset Spec. It sh	ould be 0.0025%	0075				
	2-01 module I get the following error						
<ul> <li>Inp</li> </ul>	ut Offset 0.0025% of 4mA 🔿 0.1uA/°	C or 0.00063%/°C					
	tput Offset 20uV/°C → 0.064uA/°C					•	
• Ga	'n TC 0.0025%/°C → 0.5uA/°C or	0.003125%/*C					
otal accura	icy error vs. temp of 0.664uA/°C or	0.0041%/°C					
orry for th	e confusion on the datasheets, I hope	this helps.					
egards,		•					
n					·		
Fro	m: Kirk Melson (mailto:kirk.melson@e	excelservices.com]					
Ser	t: 2009-04-13 10:47	•					
	Kellogg, Jim <b>ject:</b> Fw: Specification Clarification for	or 5832					
Jim							
	ry, I got the email address wrong. Try	this again, Could you d	call me when you ge	t a chance? y			
Sor	ry, I got the email address wrong. Try	this again. Could you o	call me when you ge	t a chance? y			
Sor Kirk Exc	ry, I got the email address wrong. Try lyn R. Melson el Services Corporation	this again. Could you o	call me when you ge	et a chance? y			
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Sor Kirk Exc (86- (86- <b>Fro</b>	ry, I got the email address wrong. Try lyn R. Melson el Services Corporation 4)962-5701 Cell 4)228-7100 Alternate and Fax <b>m: <u>Kirk Melson</u></b>	this again. Could you o	call me when you ge	t a chance? ∖			
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Sor Kirk Exc (86 (86 Fro Ser To: Cc:	ry, I got the email address wrong. Try el Services Corporation 4)962-5701 Cell 4)228-7100 Alternate and Fax <b>m: <u>Kirk Melson</u> It: Thursday, April 09, 2009 5:50 PM jim.kellog@analog.com</b>		call me when you ge	at a chance? \			
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#### Attachment 2

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We are working with a Caldon Ultrasonic flowmeter system, and we need tight accuracy. The room temperature could change as much as 50 degrees F in that room. We have a 4 to 20 mAdc signal coming in. If this specification is correct, I think I compute an error just due to this effect as:

Input Offset due to Temp = (0.0025 x 4 mA) x (100% Span / 16 mAdc) x (1 degree C / 1 degree F) x 50 degrees F = 1.74% Span.

This is a huge error for this module. If the specification actually should have a "%" listed, the error goes to around 0.0174% Span, which is much more reasonable in my opinion.

Anyway, if you get just a minute, I would really appreciate your looking at this specification and clarifying it for me. I am in a bit of a time crunch on this one, so your quick attention would be greatly appreciated.

Thanks for your time and consideration.

Kirklyn R. Melson Excel Services Corporation (864)962-5701 Cell (864)228-7100 Alternate and Fax

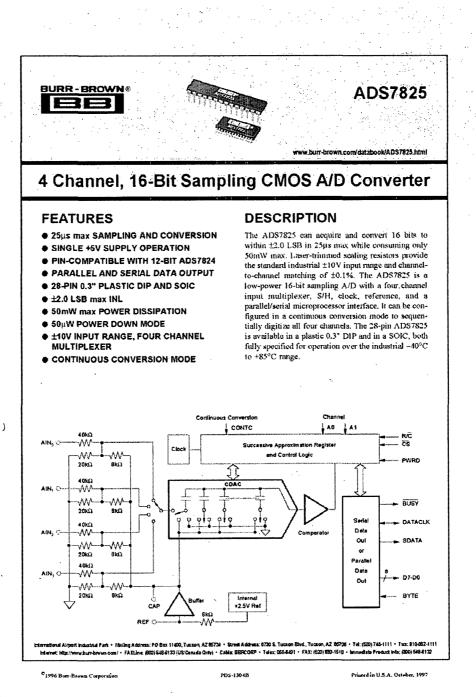
#### 4/13/2009

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Attachment 3



SBAS045

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## SPECIFICATIONS

#### ELECTRICAL

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At T<sub>A</sub> = -40°C to +85°C, f<sub>S</sub> = 40kHz, V<sub>S1</sub> = V<sub>S2</sub> = V<sub>S</sub> = +5V ±5%, using external reference, CONTC = 0V, unless otherwise specified.

			AD \$7825P	υ	A	D\$7825PB,	UB	
PARAMETER	CONDITIONS	MIN TYP MAX		MIN TYP MAX		MAX	UNITS	
RESOLUTION				16			<b>*</b> (1)	Bits
ANALOG INPUT								
Vollage Range			±10V	1		*		v
Impedance	Channel On or Off		45.7			*		κΩ
Capacitance			35	1		*		pF '
THROUGHPUT SPEED			1					
Conversion Time			20			*	1	μs ·
Acquisition Time			5			*		μs
Multiplexer Settling Time	Includes Acquisition		5			*	[	μs
Complete Cycle (Acquire and Convert)	CONTC = +5V			25 40			*	μs
Complete Cycle (Acquire and Convert) Throughput Rate	CONIC = +5V	40		40	*	1	*	μs kHz
DC ACCURACY		40				+	· · · · · · · · · · · · · · · · · · ·	N72
Integral Linearity Error				±3			±2	LSB <sup>(2)</sup>
No Missing Codes		15	1	10	16		-	
Transition Noise(3)			0.8			*		LSB
Full Scale Error <sup>(4)</sup>	Internal Reference		1	±0.5		1	±0.25	~
Full Scale Error Drift	Internal Reference		±7			±5		ppm/°C
Full Scale Error <sup>(4)</sup>				±0.5		1	±0.25	%
Full Scale Error Drift			±2	1		*		ppm/°C
Bipolar Zero Error				±10			*	m۷
Bipolar Zero Error Drift			±2	±0.1		*	±0.1	ppm/°C %a
Channel-to-Channel Mismatch Power Supply Sensitivity	+4.75 < V <sub>S</sub> < +6.25			10.1 18			±0.1	LSB
	14.76 - Vg - 10.25			10		<u> </u>	ļ	
AC ACCURACY		90					1	dB
Spurious-Free Dynamic Range <sup>(5)</sup> Total Harmonic Distortion	f <sub>IN</sub> = 1kHz f <sub>IN</sub> = 1kHz	an		-90	*		*	dB dB
Signal-to-(Noise+Distortion)	$t_{\rm IN} = 1  {\rm kHz}$	83		-30	86			dB
Signa-to-Noise	f <sub>IN</sub> ≕ 1kHz	83		1	86			dB
Channel Separation <sup>(5)</sup>	f <sub>IN</sub> = 1kHz	100	120		*	*	1	dB
-3dB Bandwidth	-IN		2			*		MHz
Useable Bandwidth <sup>(7)</sup>			90			*		kHz
SAMPLING DYNAMICS				1		1		
Aperture Delay			40			*		ns
Transient Response <sup>(8)</sup>	FS Step		5			*		μs
Overvoltage Recovery <sup>(9)</sup>			1			*		μs
REFERENCE								
Internal Reference Voltage		2.48	2.5	2.52	*	*	*	v
Internal Reference Source Current			1			*		μΑ
(Must use external buffer)		2.3	2.5	2.7	*	<u> </u>	*	v
External Reference Voltage Range for Specified Linearity		2.3	2.0	2.1	~	<b>*</b>	, T	1 ¥
External Reference Current Drain	V <sub>REF</sub> = +2.5V			100			*	μA
DIGITAL INPUTS						+		
Logic Levels								
VIL		-0.3		+0.8	*		*	v
V <sub>IH</sub>		+2.4		V <sub>S</sub> +0.3V	*	1	*	v
h <sub>it</sub>				±10		1	*	μΑ
l <sub>ін</sub>				±10		L	*	μΑ
DIGITAL OUTPUTS			1	1				
Data Formal			in two byle			*	1	
Data Coding		Binary	Two's Con			*	*	v
V <sub>OL</sub>	I <sub>SINK</sub> ≖ 1.6mA	+4		+0.4	*	1		l V I
V <sub>DH</sub> Leakage Current	I <sub>SOURCE</sub> = 500µA High-Z State, V <sub>OUT</sub> = 0V to V <sub>S</sub>	J	J	±5	l T	1	*	μΑ
Oulput Capacitance	High-Z State			15			*	pF
	····	L		L		1	L	<u> </u>

The information provided herein is believed to be reliable; however, BURR-BROWN assumes no responsibility for inaccuracies or omissions. BURR-BROWN assumes no responsibility for the use of this information, and all use of such information shaft be entirely at the user's own fisk. Prices and specifications are subject to change without notice. No specific fits on the circuit secricide herein are implied or granted to any third party. BURR-BROWN does not authorize or werrant any BURR-BROWN product for use in the support devices and/or systems.

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## SPECIFICATIONS (CONT)

#### ELECTRICAL

At  $T_A = -40^{\circ}$ C to +85°C,  $f_S = 40$ kHz,  $V_{S1} = V_{S2} = V_S = +5V \pm 5\%$ , using external reference, CONTC = 0V, unless otherwise specified.

	CONDITIONS	ADS7825P, U			ADS7825PB, UB			
PARAMETER		MIN	TYP	MAX	MIN	ТҮР	MAX	UNITS
DIGITAL TIMING				ř – – – – – – – – – – – – – – – – – – –				
Bus Access Time	PAR/SER = +5V			83			*	ns
Bus Relinguish Time	PAR/SER = +6V			83		1	*	ns
Data Clock	PAR/SER = OV			1			1	
Internal Clock (Output only when transmitting data)	EXTANT LOW	0.5		1.5	*		*	MHz
External Clock	EX TANT HIGH	0.1		10	*		*	MHz
POWER SUPPLIES								
$V_{S1} = V_{S2} = V_{S}$		+4.75	+5	+5.25	*	*	*	l v
Power Dissipation	f <sub>s</sub> = 40kHz			50		l l	*	mW
·	PWRD HIGH		50			*	1	μW
TEMPERATURE RANGE				r				
Specified Performance		-40		+85	*		*	°C
Storage		-65		+150	*		*	°C
Thermal Resistance (6IA)				1		1	1	1
Plastic DIP		1 1	75			*		°C∧w
SOIC		1	75			*		•cw

NOTES: (1) An asterik (4) specifies same value as grade to the left. (2) LSB means Least Significant Bit. For the 16-bit, ±10V input ADS7825, one LSB is 305µV. (3) Typical rms noise at worst case transitions and temperatures. (4) Full scale error is the worst case of -Full Scale or +Full Scale untrimmed deviation from ideal first and last code transitions, divided by the transition voltage (nd divided by the full-scale error) and includes the effect of offset error. (5) All specifications in dB are referred to a full-scale ±10V input. (6) A full scale sinewave input on one channel will be attenuated by this amount on the other channels. (7) Useable Bandwidth defined as Full-Scale input frequency at which Signati-C(Noise-Distortion) degrades to 6080, or 10 bits of accuracy. (8) The ADS7825 will accurately acquire any input step if given a full acquisition period after the step. (9) Recovers to specified performance after 2 x FS input overvollage, and normal equisitions can begin.

#### PACKAGE/ORDERING INFORMATION

PRODUCT	PACKAGE	PACKAGE DRAWING NUMBER <sup>(1)</sup>	TEMPERATURE RANGE	MAXIMUM INTEGRAL LINEARITY ERROR (LSB)	MINIMUM SIGNAL- TO-(NOISE + DISTORTION) RATIO (dB)
ADS7825P	Plastic Dip	246	-40°C to +85°C	±3	. 83
ADS7825PB	Plastic Dip	246	-40°C to +85°C	±2	86 -
ADS7825U	SOIC	217	-40°C to +85°C	±3	83
ADS7825UB	SOIC	217	-40°C to +65°C	±2	86

3

DIN CONFICURATION

NOTE: (1) For detailed drawing and dimension table, please see end of data sheet, or Appendix C of Burr-Brown IC Data Book.

#### ABSOLUTE MAXIMUM RATINGS

Analog Inputs: AINg, AIN1, AIN2, AIN3	±15V	
REF (AGN	D2 -0.3V) lo (V <sub>S</sub> + 0.3V)	
CAPIn	definite Short to AGND2,	
	Momentary Short to Vs	
V <sub>S1</sub> and V <sub>S2</sub> to AGND2		
V <sub>S1</sub> 10 V <sub>S2</sub>	±0.3V	
Difference between AGND1, AGND2 and DGND	±0.3V	
Digital Inputs and Outputs	0.3V to (Vs + 0.3V)	
Maximum Junction Temperature	150°C	
Internal Power Dissipation		
Lead Temperature (soldering, 10s)		
Maximum Input Current to Any Pin	100mA	

#### ELECTROSTATIC DISCHARGE SENSITIVITY

This integrated circuit can be damaged by ESD. Burr-Brown recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

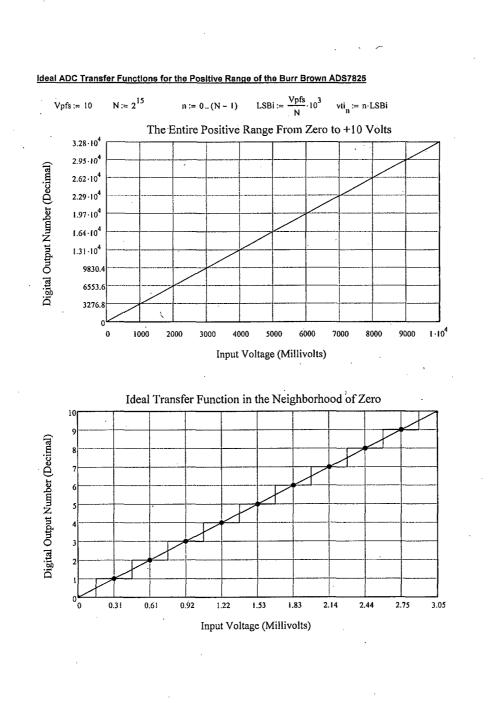
ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

			TOP VIEW
28         V <sub>S1</sub> 27         V <sub>S2</sub> 26         PWRD           25         CONTC           24         BUSY           22         CS           21         BYTE           20         PAR/SER           19         A0           18         A1           17         D0           16         D1           15         D2	AD\$7825	AGND1 1 AIN <sub>0</sub> 2 AIN <sub>1</sub> 3 AIN <sub>2</sub> 4 AIN <sub>3</sub> 5 CAP 6 REF 7 AGND2 8 D 07 9 D 05 111 D 04 12 D 03 13 D 050D 14	TOP MEW TRI-STATE TRI-STATE TRI-STATE EXT/INT SYNC

## ADS7825

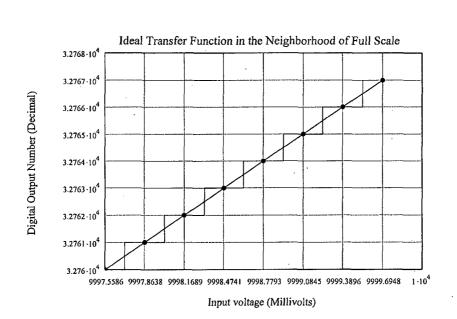
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#### Transfer Functions Considering Only Offset Error and Full-Scale Error

Using the values from the ADS7825 data sheet: Vos = +/-10 mV (+/-33LSBi where LSBi =  $20^{\circ}2^{(-16)}$ ) and FSE = +/-10^{\circ}0.25/100 = +/-25mV (+/-82LSBi). Note 4 states that the full-scale error includes the offset error which leads me to believe that the full-scale error with offset zeroed out is (82 - 33)<sup>\*</sup>LSBi = +/-49LSBi (since offset errors shift the ideal transfer function to the right or left). This means that there are two slopes for the worst case transfer functions which are slightly different from the slope of the ideal transfer function. This translates into slightly different values of LSB for the two cases: LSB1 for the slope corresponding to the -49 LSBi error; and, LSB2 for the slope corresponding to the +49 LSBi error given by:

> LSB1 :=  $\frac{10^4 - 49 \cdot \text{LSBi}}{32768}$  LSB1 = 0.30472 LSB2 :=  $\frac{10^4 + 49 \cdot \text{LSBi}}{32768}$  LSB2 = 0.30563

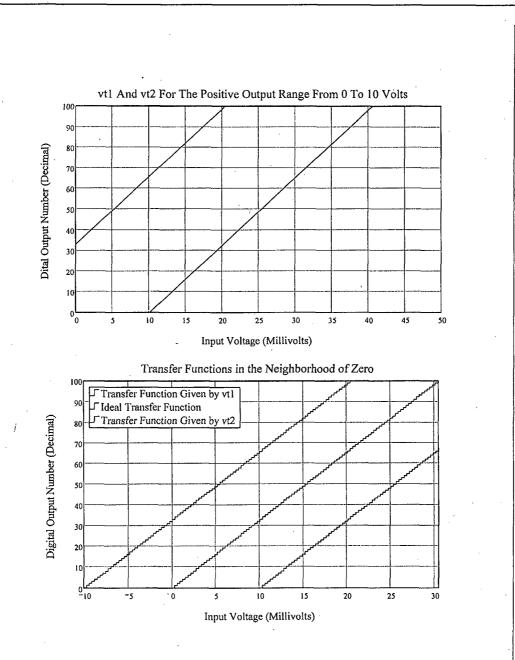
Then the offsets can be added in to give the worst case transfer functions where the offset and gain errors add together so as to make the total error the greatest. These two straight lines are the envelope of the bundle of all possible straight lines which meet the offset and FSE of the part.

 $vt_n := -33 \cdot LSBi + LSB1 \cdot n$  $vt_n := 33 \cdot LSBi + LSB2 \cdot n$ 

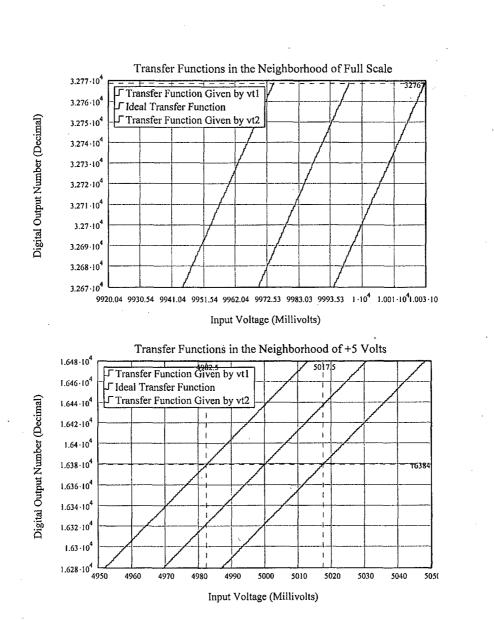
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Attachment 4



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The worst case error at n = 16384 (where vti = 5000 mV) is +/- 17.5 mV (+/- 16.44LSBi). In general, the worst case error at any voltage V in mV is +/- (vt2-V) with vt2 evaluated at n =  $(V/1000)^{+32768}$ .

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