

AP1000 DOCUMENT COVER SHEET

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AP1000 DOCUMENT NO. APP-GW-GLR-134	REVISION 1	PAGE 1 of 470	ASSIGNED TO W-Sterdis	OPEN ITEMS (Y/N)
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ALTERNATE DOCUMENT NUMBER: TR-134

WORK BREAKDOWN #:

ORIGINATING ORGANIZATION: Westinghouse Electric Company

TITLE: AP1000 DCD Impacts to Support COLA Standardization

ATTACHMENTS: Attachment A and B, integral to document	DCP #/REV. INCORPORATED IN THIS DOCUMENT REVISION: None
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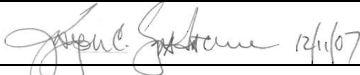

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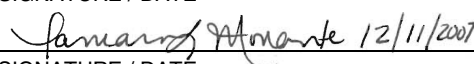

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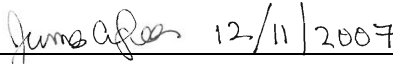

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	SIGNATURE / DATE	
	SIGNATURE / DATE	
VERIFIER(S) Don Lindgren	SIGNATURE / DATE  12/11/07	Verification Method Independent Review

**** Plant Applicability:** ☒ All AP1000 plants except: No Exceptions

☐ Only the following plants:

APPLICABILITY REVIEWER** J. A. Speer	SIGNATURE / DATE  12/11/2007
RESPONSIBLE MANAGER* A. Sterdis	SIGNATURE / DATE  11 Dec 07

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APP-GW-GLR-134
Revision 1

December 2007

AP1000 Standard Combined License Technical Report

AP1000 DCD Impacts to Support COLA Standardization

Westinghouse Electric Company LLC
Nuclear Power Plants
Post Office Box 355
Pittsburgh, PA 15230-0355

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REVISION HISTORY

Revision	Author	Change Description
0	Monte Bartley	Original Issue
1	Monte Bartley	Incorporated Tier 1 changes related to the seismic design spectra changes to address hard rock high frequency exceedances and to provide conformance with previous DCD Tier 2 changes. The Revision 1 changes are contained in separate Attachment A and Attachment B sections at the end of the document.

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LIST OF ATTACHMENTS

Attachment A – AP1000 DCD Impact Report

Sorted by DCD Chapter and Section in the order of Tier 1, Tier 2*, Tier 2

Attachment B – AP1000 DCD, Revision 16, Mark-Up pages

Sorted by DCD Chapter and Section in the order of Tier 1, Tier 2*, Tier 2

LIST OF TABLES

None

LIST OF FIGURES

None

INTRODUCTION

In support of the Combined License application pre-application activities, Westinghouse is submitting Technical Report APP-GW-GLR-134 (TR 134), “AP1000 DCD Impacts to Support COLA Standardization.” The purpose of this technical report is to identify impacts to the “AP1000 Design Control Document,” APP-GW-GL-700, Revision 16. The impacts, which occurred or were discovered subsequent to the submittal of the DCD in support of the AP1000 design certification amendment, may be in the form of: DCD discrepancies; responses to requests for additional information (RAIs) issued against prior technical reports, where those responses contain DCD changes; and correction of typographical errors and other minor corrections. This report addresses DCD Revision 16 impacts for Tier 1, Tier 2*, and Tier 2. This document is provided to track the DCD impacts and thereby maintain consistency between the AP1000 Design Certification Amendment Application and the COL applications that reference the AP1000 Design Certification Rulemaking. The impacts included in this document will be incorporated into the AP1000 DCD in a forthcoming revision.

The markups in “Attachment B” of this report are in addition to the changes indicated in “AP1000 Design Control Document,” APP-GW-GL-700, Revision 16 (i.e., the change bars in “Attachment B” assume the changes identified in Revision 16 of the DCD have been made). Accordingly, the full set of changes from DCD Revision 15 are represented by the changes identified in DCD Revision 16 plus the changes identified in “Attachment B” of this report.

This report is submitted as part of the NuStart Standard Plant COL Project (Project Number 740). The information in this report is standard and is expected to apply to all COL applications referencing the AP1000 Design Certification. The impacts to DCD Revision 16 identified in this technical report are documented via attachments to the relevant RAI responses, and markups indicating DCD discrepancies along with their resolutions.

This technical report will be revised as necessary to address any future impacts to the DCD, and Westinghouse and the AP1000 Design Centered Work Group will continue working closely with the NRC Staff to coordinate updates. The technical report is intended to serve as a tracking matrix, linking each DCD Impact to the applicable supporting documentation provided in other technical reports and RAI responses (note that, for certain minor corrections such as editorial changes where no regulatory impact is anticipated, no supporting documentation reference is necessary).

REGULATORY IMPACT

Those portions of the design-related information contained in the AP1000 Design Control Document that have been approved and certified by the NRC are identified as “Tier 1.” The technical and regulatory basis for the Tier 1 changes is provided in the referenced technical reports and RAI Responses in “Attachment A” of this report.

Those portions of the design-related information subject to the change process in Section VIII of the AP1000 design certification rule are identified as “Tier 2”. The impacts identified as “Tier 2” have been evaluated using the 10 CFR 52 Appendix D Section VIII criteria to determine whether NRC prior approval is required. While the screening results indicate that prior approval would not be required for a COL applicant, Westinghouse is including these changes in the Design Certification Rulemaking Amendment Application to support standardization of the AP1000 design. The technical and regulatory bases for these changes are provided in the referenced technical reports and RAI responses in “Attachment A” of this report.

The identification of Tier 2* information in this technical report is consistent with the information contained in Table 1-1 of the “AP1000 Design Control Document,” APP-GW-GL-700, Revision 16. The technical and regulatory basis for the Tier 2* changes is provided in the referenced technical reports and RAI Responses summarized in “Attachment A” of this report.

Additionally, those items identified as minor corrections include editorial changes and conforming or consistency changes which have no significant impact to the DCD. These changes are also described in “Attachment A” of this report.

DCD MARK-UP

“Attachment A” of this report contains a database report that identifies the impacts to Revision 16 of the DCD. The entries are sorted numerically, by Chapter and Section. Included with each item in the report is a list of related reference items and a description of the impact (as discussed above). The reference items include a sequential tracking number for each impact in the format “NRC nnn ” (for cross-reference purposes), references to applicable technical reports, and references to previously submitted relevant RAI responses. The impacts also are ordered by Tier 1, Tier 2*, Tier 2.

“Attachment B” of this report contains the mark-up pages to “AP1000 Design Control Document,” APP-GW-GL-700, Revision 16. The pages use a “track changes” format, showing deleted text with a “strike-through,” new text underlined, vertical change bars in the left margin, and the sequential tracking number (NRC nnn) to the left of the change bar. The sequential tracking number links the change information contained in the database report from “Attachment A” to the location of the change in the DCD. The mark-up pages are sorted by Chapter and Section and grouped as Tier 1, Tier 2*, Tier 2.

REFERENCES

1. Westinghouse AP1000 document APP-GW-GL-700, Revision 16, “AP1000 Design Control Document.”

ATTACHMENT A

Tier 1

Attachment A

AP1000 DCD Impact Report

APP-GW-GL-700, Revision 16, "AP1000 Design Control Document"

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
2.2.1, Table 2.2.1-3	Accepted for Revision 17	NRC176	Tier 1	NRC Prior Approval Required
<i>Description:</i> NRC175 contains corrections to Tier 1 Section 2.2.1 and Table 2.2.1-3 to be consistent with RAI-TR93-ICE2-07				
<i>Reference Information:</i> RAI-TR93-ICE2-07				
<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
2.6.1-1	Accepted for Revision 17	NRC078	Tier 1	Requires Prior NRC Approval
<i>Description:</i> NRC078 contains corrections to Figure 2.6.1-1 of DCD Revision 16 to be consistent with APP-GW-GLN-114 (TR114) and APP-GW-GLN-079 (TR79).				
<i>Reference Information:</i> APP-GW-GLN-079 (TR79), Rev 1; APP-GW-GLN-114 (TR114), Rev 0				

Attachment A

AP1000 DCD Impact Report

APP-GW-GL-700, Revision 16, "AP1000 Design Control Document"

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
3.5-5, 3.5-7	Accepted for Revision 17	NRC051	Tier 1	Requires Prior NRC Approval
<i>Description:</i> NRC051 contains corrections to Tier 1 Table 3.5-5 and Table 3.5-7 of DCD Revision 16 to change "Technical Support Center" to "CSA".				
<i>Reference Information:</i> APP-GW-GLR-107 (TR107), Rev 1RAI-TR107-NSIR-02				

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
3.5-5, 3.5-7, 7.5-1, 9.4, 9A, 11.5, 13.3, 14.2	Accepted for Revision 17	NRC123 (Tier 1 - Chapt 3)	Tier 1	Requires Prior NRC Approval
<i>Description:</i> NRC123 contains corrections to change "technical support center" to "control support area" to be consistent with TR107, APP-GW-GLR-107.				
<i>Reference Information:</i> APP-GW-GLR-107 (TR107), Rev 1RAI-TR107-NSIR-02				

Attachment A

AP1000 DCD Impact Report

APP-GW-GL-700, Revision 16, "AP1000 Design Control Document"

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
5.0-1	Accepted for Revision 17	NRC144	Tier 1	Requires Prior NRC Approval
<i>Description:</i> NRC144 contains corrections to Tier 1 Table 5.0-1 of DCD Revision 16 to be consistent with TR122, APP-GW-GLN-122.				
<i>Reference Information:</i> APP-GW-GLN-122 (TR122), Rev 0				

ATTACHMENT A

Tier 2*

Attachment A

AP1000 DCD Impact Report

APP-GW-GL-700, Revision 16, "AP1000 Design Control Document"

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
3H.5-9	Accepted for Revision 17	NRC094 (Tier 2*)	Tier 2* (Star)	NRC Prior Approval Required

Description:

NRC 094 contains corections to Figure 3H.5-9 sheet 1 and Figure 3H.5-12 of the DCD Revision 16 to be consistent with TR 57, APP-GW-GLR-045, Rev 0.

Reference Information:

APP-GW-GLR-045 (TR57), Rev 0

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
4.1.1	Accepted for Revision 17	NRC103 (Tier 2*)	Tier 2* (Star)	NRC Prior Approval Would Have Been Required

Description:

NRC103 contains corrections to Tier 2 - Chapter 4 of DCD Revision 16 to be consistent with Technical Report TR30, APP-GW-GLN-013. [Note: This portion of Chapter 4 was Tier 2* (Star) in DCD Revision 15] - Sequential "Tracking Number" NRC103 also appears in the Tier 2 Impact Report. The actual changes are in the Attachment B, Tier 2 mark-up pages.

Reference Information:

APP-GW-GLN-013 (TR30), Rev 0

Attachment A

AP1000 DCD Impact Report

APP-GW-GL-700, Revision 16, "AP1000 Design Control Document"

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
7.7.1.11	Accepted for Revision 17	NRC111 (Tier 2*)	Tier 2* (Star)	NRC Prior Approval Required
<i>Description:</i> Corrections to Section 7.7.1.11 (Tier 2*), consistent with APP-GW-GLR-080, Rev.0 is included in Revision 16 of the DCD				
<i>Reference Information:</i> APP-GW-GLR-080 (TR80), Rev 0				

ATTACHMENT A

Tier 2

Chapter 1

Attachment A

AP1000 DCD Impact Report

APP-GW-GL-700, Revision 16, "AP1000 Design Control Document"

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
1.1.7	Accepted for Revision 17	NRC130	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> NRC130 contains an editorial correction (restoration to Rev 15 wording) due to the rejection of Technical Report APP-GW-GLR-036				
<i>Reference Information:</i> APP-GW-GLR-036 (TR01), Rev 0				
<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
1.2	Accepted for Revision 17	NRC106 (Chapt 1)	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> NRC106 contains corrections to Figure 1.2-1, 5.1-2 and Figure 1.2-9. The basis for the change is TR36 APP-GW-GLR-016.				
<i>Reference Information:</i> APP-GW-GLR-016 (TR36), Rev 0				

Attachment A

AP1000 DCD Impact Report

APP-GW-GL-700, Revision 16, "AP1000 Design Control Document"

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
1.2	Accepted for Revision 17	NRC107	Tier 2	NRC Prior Approval Not Required

Description:

NRC107 contains corrections to Figure 1.2-9. The basis for the change is TR61 APP-GW-GLN-014.

Reference Information:

APP-GW-GLN-014 (TR 61), Rev 0

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
1.3-1	Accepted for Revision 17	NRC147	Tier 2	NRC Prior Approval Not Required

Description:

NRC 147 contains changes to Table 1.3-1 sheet 1 to be consistent with Section 1.2.1.1.1.

Reference Information:

Attachment A

AP1000 DCD Impact Report

APP-GW-GL-700, Revision 16, "AP1000 Design Control Document"

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
1.6-1	Accepted for Revision 17	NRC153	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> NRC 153 contains editorial changes to Table 1.6-1 sheet 12 to be consistent with APP-GW-GLR-080, Rev 0.				
<i>Reference Information:</i> APP-GW-GLR-080 (TR80), Rev 0				
<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
1.7	Accepted for Revision 17	NRC110	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> NRC110 contains an editorial correction to reference Figure 7.2-1				
<i>Reference Information:</i>				

Attachment A

AP1000 DCD Impact Report

APP-GW-GL-700, Revision 16, "AP1000 Design Control Document"

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
1.8-2, 4.4.7	Accepted for Revision 17	NRC102 (Chapt 1)	Tier 2	NRC Prior Approval Not Required

Description:

NRC102 contains corrections to Table 1.8-2 and Sub-section 4.4.7 of DCD Revision 16 to be consistent with Technical Report TR59, APP-GW-GLR-059 and TR130, APP-GW-GLR-130.

Reference Information:

APP-GW-GLR-059 (TR18), Rev 0,
APP-GW-GLR-130 (TR130), Rev 0

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
1.8-2	Accepted for Revision 17	NRC127	Tier 2	NRC Prior Approval Not Required

Description:

NRC127 contains editorial changes to Table 1.8-2.

Reference Information:

Attachment A

AP1000 DCD Impact Report

APP-GW-GL-700, Revision 16, "AP1000 Design Control Document"

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
1.8-2	Accepted for Revision 17	NRC124	Tier 2	NRC Prior Approval Not Required

Description:

NRC124 contains editorial changes to Table 1.8-1 sheet 12 to be consistent with APP-GW-GLR-012

Reference Information:

APP-GW-GLR-012 (TR72), Rev 0

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
1.8-2	Accepted for Revision 17	NRC175	Tier 2	NRC Prior Approval Not Required

Description:

NRC175 contains corrections to Table 1.8-2 of DCD Revision 16 to be consistent with APP-GW-GLR-136 (TR136), Rev 0

Reference Information:

APP-GW-GLR-136 (TR136), Rev 0

Attachment A

AP1000 DCD Impact Report

APP-GW-GL-700, Revision 16, "AP1000 Design Control Document"

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
1.8-2	Accepted for Revision 17	NRC126	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> NRC126 contains changes to Table 1.8-2 sheet 12 to be consistent with APP- GW-GLR-081 and APP-GW-GLR-090				
<i>Reference Information:</i> APP-GW-GLR-081 (TR81), Rev 0; APP-GW-GLR-090 (TR90), Rev 0				

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
1.8-2	Accepted for Revision 17	NRC125	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> NRC124 contains changes to Table 1.8-2 sheet 12 to be consistent with APP- GW-GLR-010 and APP-GW-GLR-090				
<i>Reference Information:</i> APP-GW-GLR-010 (TR52), Rev 2, APP-GW-GLR-090 (TR90), Rev 0				

Attachment A

AP1000 DCD Impact Report

APP-GW-GL-700, Revision 16, "AP1000 Design Control Document"

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
1.9.5.1.15, 3.9.6, 3.9-16, 5.2.4, 6.6	Accepted for Revision 17	NRC148 (Chapt 1)	Tier 2	NRC Prior Approval Not Required

Description:

NRC 148 contains changes to Sections 1.9.5.1.15, 3.9.3.4.3, 3.9.3.4.4, 3.9.6, 3.9.6.2, 3.9.6.2.1, 3.9.6.2.2, 3.9.6.2.3, 3.9.6.3, Table 3.9-16 and 6.6 of the DCD Revision 16 to be consistent with APP-GW-GLN-138

Reference Information:

APP-GW-GLN-138 (TR138), Rev 0

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
1.9-1	Accepted for Revision 17	NRC141	Tier 2	NRC Prior Approval Not Required

Description:

NRC141 contains corrections to Table 1.9-1 to be consistent with APP-GW-GLN-141

Reference Information:

APP-GW-GLN-141 (TR141), Rev 0

Attachment A

AP1000 DCD Impact Report

APP-GW-GL-700, Revision 16, "AP1000 Design Control Document"

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
1.9	Accepted for Revision 17	NRC172	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> NRC172 contains changes to Table 1.9-1 to be consistent with RAI-TR44-020.				
<i>Reference Information:</i> RAI-TR44-020				

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
1A	Accepted for Revision 17	NRC140	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> NRC140 contained the following changes based on technical report APP-GW-GLN-141: Reg Guide 1.27, Conformance for Criteria C.4 added Reg Guide 1.32, Change N/A to Exception and revised discussion. (Criteria is addressed in the Tech Specs Bases.) Reg Guide 1.54, Corrected Title and Date. Reg Guide 1.197, Added Reg Guide 1.98, Typographical change "4.3 to 4.e"				
<i>Reference Information:</i> APP-GW-GLN-141 (TR141), Rev 0				

Attachment A

AP1000 DCD Impact Report

APP-GW-GL-700, Revision 16, "AP1000 Design Control Document"

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
1A	Accepted for Revision 17	NRC105	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> NRC105 contains corrections to remove the reference to NQA-2 in the discussion of Reg Guide 1.28. This change is to maintain consistency with APP-GW-GLR-109.				
<i>Reference Information:</i> APP-GW-GLR-109 (TR109), Rev 0				

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
1A	Accepted for Revision 17	NRC060	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> NRC060 contains changes to Reg Guide 1.44 to maintain consistency with APP-GW-GLN-141.				
<i>Reference Information:</i> APP-GW-GLN-141 (TR141), Rev 0				

Chapter 2

Attachment A

AP1000 DCD Impact Report

APP-GW-GL-700, Revision 16, "AP1000 Design Control Document"

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
2.5	Accepted for Revision 17	NRC046	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> NRC046 contains corrections to Section 2.5 of DCD Revision 16 to be consistent with technical report TR03, APP-GW-S2R-010				
<i>Reference Information:</i> APP-GW-S2R-010 (TR03), Rev 1 RAI-TR03-019 R1				
<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
2.5.4.5.3	Accepted for Revision 17	NRC049	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> NRC049 contains corrections to Section 2.5.4.5.1 of DCD Revision 16 to be consistent with RAI-TR85-SEB1-38				
<i>Reference Information:</i> APP-GW-GLR-044 (TR85), Rev 0 RAI-TR85-SEB1-38				

Attachment A

AP1000 DCD Impact Report

APP-GW-GL-700, Revision 16, "AP1000 Design Control Document"

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
2-1	Accepted for Revision 17	NRC129	Tier 2	NRC Prior Approval Not Required

Description:

NRC129 contains an editorial clarification to Table 2-1 to change "none" to "negligible" for the Fault Displacement Potential.

Reference Information:

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
Table 2-1	Accepted for Revision 17	NRC171	Tier 2	NRC Prior Approval Not Required

Description:

NRC171 contains additions to Table 2-1 to be consistent with RAI-TR85-SEB1-37.

Reference Information:

RAI-TR85-SEB1-37

Attachment A

AP1000 DCD Impact Report

APP-GW-GL-700, Revision 16, "AP1000 Design Control Document"

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
2-1	Accepted for Revision 17	NRC143	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> NRC143 contains editorial corrections to Table 2-1 of DCD Revision 16 to be consistent with TR122, APP-GW-GLN-122.				
<i>Reference Information:</i> APP-GW-GLN-122 (TR122), Rev 0				

Chapter 3

Attachment A

AP1000 DCD Impact Report

APP-GW-GL-700, Revision 16, "AP1000 Design Control Document"

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
3.1.3	Accepted for Revision 17	NRC154	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> NRC 154 contains changes to Section 3.1.3 Criterion 20 - Protection Systems Function under AP 1000 Compliance of the DCD Revision to be consistent with APP-GW-GLR-080, Rev 0.				
<i>Reference Information:</i> APP-GW-GLR-080 (TR80), Rev 0				
<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
3.2.2.5	Accepted for Revision 17	NRC164	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> NRC164 contains a correction to Section 3.2.2.5 identifying a random selection of welds for consistency with discussion in 3.2.2.5 and RG 1.26 assessment in Appendix 1A.				
<i>Reference Information:</i>				

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<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
3.2.3	Accepted for Revision 17	NRC117	Tier 2	NRC Prior Approval Not Required

Description:

NRC 117 contains corrections to Section 3.2.3 of the DCD Revision 16 changing the code reference for the inspection of pumps and valves to ASME Code, Section XI, Subsections IWB, IWC, and IWD to be consistent with DCD Section 6.6.

Reference Information:

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
Table 3.2-3, Figure 3.8.2-4	Accepted for Revision 17	NRC044	Tier 2	NRC Prior Approval Not Required

Description:

NRC044 contains corrections to Table 3.2-3, Figure 3.8.2-4 of DCD Revision 16. The basis for the change is RAI-TR09-003.

Reference Information:

RAI-TR09-003

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<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
3.5.1.6	Accepted for Revision 17	NRC075	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> NRC 075 added the sentence "Aircraft crash probability and the effects of this hazard on the plant is determined as described in Section 2.2." to Section 3.5.1.6 for clarity.				
<i>Reference Information:</i>				
<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
3.7	Accepted for Revision 17	NRC168	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> NRC168 contains changes to Section 3.7 to be consistent with APP-GW-S2R-010 (TR3), Rev. 1				
<i>Reference Information:</i> APP-GW-S2R-010 (TR3), Rev. 1				

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<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
3.8.2.1.5	Accepted for Revision 17	NRC057	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> NRC057 contains corrections to Section 3.8.2.1.5 of the DCD Revision 16 so that it now references Table 6.2.3-1.				
<i>Reference Information:</i>				

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
3.8	Accepted for Revision 17	NRC097	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> NRC097 contains changes to the text of Section 3.8 of the DCD Revision 16 to be consistent with APP-GW-GLN-079 (TR79). It also contains figure changes in Section 3.8 of the DCD Revision 16 to be consistent with APP-GW-GLR-016 (TR 36).				
<i>Reference Information:</i> APP-GW-GLR-016 (TR36), Rev 0; APP-GW-GLN-079 (TR79), Rev 1				

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<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
3.8.2.1.6	Accepted for Revision 17	NRC058	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> NRC058 contains corrections to Section 3.8.2.1.6 of the DCD revision 16 so that it now references section 8.3.1.1.6.				
<i>Reference Information:</i>				

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
3.8.2.6, 5.2-3	Accepted for Revision 17	NRC093 (Chapt 3)	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> NRC093 contains corrections to Section 3.8.2.6 and Figure 5.2-3 of DCD Revision 16 to be consistent with Technical Report TR113, APP-GW-GLN-113.				
<i>Reference Information:</i> APP-GW-GLN-113 (TR113), Rev 0				

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<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
3.8.4.3.1.3	Accepted for Revision 17	NRC059	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> NRC059 contains corrections to Section 3.8.4.3.1.3 of the DCD Revision 16 so that it now references Table 2-1.				
<i>Reference Information:</i>				

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
3.8.5.5.4	Accepted for Revision 17	NRC134	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> NRC 134 contains changes to Section 3.8.5.5.4 and Table 3.8.5-2 of the DCD Revision 16 to be consistent with RAI-TR85-SEB1-034, Rev 0. Deleted "Hard Rock Condition" from the title of Table 3.8.5-2 consistent with RAI-TR85-SEB1-028				
<i>Reference Information:</i> RAI-TR85-SEB1-028, RAI-TR85-SEB1-034				

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<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
3.8	Accepted for Revision 17	NRC056	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> NRC056 contains changes to Table 3.8.2-1 in the DCD Revision 16 to be consistent with TR09, APP-GW-GLR-005.				
<i>Reference Information:</i> APP-GW-GLR-005 (TR09), Rev 1				

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
1.9.5.1.15, 3.9.3, 3.9.6, 3.9-16, 3D, 5.2.4, 6.6	Accepted for Revision 17	NRC148 (Chapt 3)	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> NRC 148 contains changes to Sections 1.9.5.1.15, 3.9.3.4.3, 3.9.3.4.4, 3.9.3, 3.9.6, 3.9.6.2, 3.9.6.2.1, 3.9.6.2.2, 3.9.6.2.3, 3.9.6.3, Table 3.9-16, 3D, and 6.6 of the DCD Revision 16 to be consistent with APP-GW-GLN-138, Rev 0				
<i>Reference Information:</i> APP-GW-GLN-138 (TR138), Rev 0				

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<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
Table 3.9-17	Accepted for Revision 17	NRC151	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> NRC 151 contains changes to Table 3.9-17 of the DCD Revision 16 to be consistent with APP-GW-GLR-007.				
<i>Reference Information:</i> APP-GW-GLR-007 (TR27), Rev 1				
<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
Appendix 3D	Accepted for Revision 17	NRC062	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> NRC062 updates page 3D-76 to remove reference to the technical specifications for in-service inspections. Format corrections were made to Table 3.11-1 sheet 31. Grammatical corrections were made to section 3D.6.3 and 3D.6.5.1. Correction made to Table 3.11-1 sheet 26 to be consistent with DCD Figure 5.4-7.				
<i>Reference Information:</i>				

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<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
3G	Accepted for Revision 17	NRC041	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> NRC041 contains editorial changes to Appendix 3G of the DCD Revision 16 to be consistent with RAI-TR03-013, Rev 1 and APP-GW-S2R-010, Rev 1.				
<i>Reference Information:</i> APP-GW-S2R-010 (TR03), Rev 1 RAI-TR03-013 R1				

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
3G	Accepted for Revision 17	NRC011	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> NRC011 contains changes to Appendix 3G of the DCD Revision 16 to be consistent with RAI-TR03-013, Rev A and APP-GW-S2R-010, Rev 1.				
<i>Reference Information:</i> APP-GW-S2R-010 (TR03), Rev 1 RAI-TR03-013				

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<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
3G	Accepted for Revision 17	NRC169	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> NRC169 contains changes to Appendix 3G based on APP-GW-S2R-010 (TR03), Rev 1				
<i>Reference Information:</i> APP-GW-S2R-010 (TR03), Rev 1				

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
3I	Accepted for Revision 17	NRC163	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> NRC163 replaces "Bellefonte" in APP 3I with "Hard Rock High Frequency (HRHF)" Add figure updates per APP-GW-GLR-115 (TR115). Screening Process Group No. 3 under 3I.6.4 is revised per APP-GW-GLR-115 (TR115).				
<i>Reference Information:</i> APP-GW-GLR-115 (TR115), Rev 0				

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<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
4.1.1	Accepted for Revision 17	NRC103	Tier 2	NRC Prior Approval Not Required

Description:

NRC103 contains corrections to Chapter 4 of DCD Revision 16 to be consistent with Technical Report TR30, APP-GW-GLN-013.

Reference Information:

APP-GW-GLN-013 (TR30), Rev 0

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
Table 4.2-6	Accepted for Revision 17	NRC165	Tier 2	NRC Prior Approval Not Required

Description:

NRC165 contains addition of fuel rod dia to Figure 4.2-6 to be consistent with RAI-TR18-SRSB-06

Reference Information:

RAI-TR18-SRSB-06

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<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
4.3.2.4.16	Accepted for Revision 17	NRC160	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> NRC160 contains corrections to Sub-section 4.3.2.4.16 of DCD Revision 16 to be consistent with Technical Report TR80, APP-GW-GLR-080.				
<i>Reference Information:</i> APP-GW-GLR-080 (TR80), Rev 0				
<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
4.3.2.6.1, 9.1.6	Accepted for Revision 17	NRC104 (Chapt 4)	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> NRC104 contains changes to Section 4.3.2.6.1 to be consistent with APP-GW-GLR-030 (TR67). Note: The formula was inadvertently deleted in TR67 without the use of strikeout. The DCD Attachment A markup pages correctly shows the formula deletion by strikeout.				
<i>Reference Information:</i> APP-GW-GLR-030 (TR67), Rev 0				

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<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
4.4.2.11.6	Accepted for Revision 17	NRC167	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> NRC167 contains corrections to Section 4.4.2.11.6 to change less than 22.45kW/ft to less than or equal to 22.5kW/ft. Add greater than to ... melt is 22.5kW/ft... The basis for the change is RAI-TR18-SRSB-09				
<i>Reference Information:</i> RAI-TR18-SRSB-09				

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
Table 1.8-2, 4.4.7	Accepted for Revision 17	NRC102 (Chapt 4)	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> NRC102 contains corrections to Table 1.8-2 and Sub-section 4.4.7 of DCD Revision 16 to be consistent with Technical Report (TR18) APP-GW-GLR-059 and (TR130) APP-GW-GLR-130.				
<i>Reference Information:</i> APP-GW-GLR-059 (TR18), Rev 0; APP-GW-GLR-130 (TR130), Rev 0				

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<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
Table 4.4-1	Accepted for Revision 17	NRC166	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> NRC166 contains the addition of note m to Table 4.4-1 sheet 2 to be consistent with RAI-TR18-SRSB-10				
<i>Reference Information:</i> RAI-TR18-SRSB-10				

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APP-GW-GL-700, Revision 16, "AP1000 Design Control Document"

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
1.2-1, 5.1-2	Accepted for Revision 17	NRC106 (Chapt 5)	Tier 2	NRC Prior Approval Not Required

Description:

NRC106 contains corrections to Figure 1.2-1, 5.1-2 and Figure 1.2-9. The basis for the change is TR36 APP-GW-GLR-016.

Reference Information:

APP-GW-GLR-016 (TR36), Rev 0

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
5	Accepted for Revision 17	NRC115	Tier 2	NRC Prior Approval Not Required

Description:

NRC115 contains editorial corrections to Sub-sections 5.2.1.3, 5.2.4.3 and Figure 5.3-6 of DCD Revision 16.

Reference Information:

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<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
1.9.5.1.15, 3.9.6, 3.9-16, 5.2.4, 6.6	Accepted for Revision 17	NRC148 (Chapt 5)	Tier 2	NRC Prior Approval Not Required

Description:

NRC 148 contains changes to Sections 1.9.5.1.15, 3.9.3.4.3, 3.9.3.4.4, 3.9.6, 3.9.6.2, 3.9.6.2.1, 3.9.6.2.2, 3.9.6.2.3, 3.9.6.3, 5.2.2.9, 5.2.4, 5.2.4.3, 5.2.4.5, 5.2.4.6, 5.4.9.4, 3.9.3, Table 3.9-16 and 6.6 of the DCD Revision 16 to be consistent with APP-GW-GLN-138

Reference Information:

APP-GW-GLN-138 (TR138), Rev 0

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
5.2.2.9	Accepted for Revision 17	NRC061	Tier 2	NRC Prior Approval Not Required

Description:

NRC061 contains an editorial correction to Sub-section 5.2.2.9 of DCD Revision 16.

Reference Information:

APP-GW-GLN-138 (TR138), Rev 0

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APP-GW-GL-700, Revision 16, "AP1000 Design Control Document"

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
5.2.6.2	Accepted for Revision 17	NRC089	Tier 2	NRC Prior Approval Not Required

Description:

NRC089 contains corrections to Section 5.2.6.2 of DCD Revision 16.

Reference Information:

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
5.2	Accepted for Revision 17	NRC077	Tier 2	NRC Prior Approval Not Required

Description:

NRC077 contains corrections to Table 5.2-1 of DCD Revision 16.

Reference Information:

APP-GW-GLN-009 (TR33), Rev 1

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<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
3.8.2.6, 5.2-3	Accepted for Revision 17	NRC093 (Chapt 5)	Tier 2	NRC Prior Approval Not Required

Description:

NRC093 contains corrections to Section 3.8.2.6 and Table 5.2-3 of DCD Revision 16 to be consistent with Technical Report TR113, APP-GW-GLN-113.

Reference Information:

APP-GW-GLN-113 (TR113), Rev 0

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
5.3.4.7	Accepted for Revision 17	NRC090	Tier 2	NRC Prior Approval Not Required

Description:

NRC090 contains corrections to Sub-section 5.3.4.7 of DCD Revision 16.

Reference Information:

APP-GW-GLN-138 (TR138), Rev 0

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<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
5.3.6.5	Accepted for Revision 17	NRC136	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> NRC136 contains corrections to Section 5.3.6.5 of DCD Revision 16.				
<i>Reference Information:</i> APP-GW-GLR-060 (TR24), Rev 0				

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
5.4.2.2	Accepted for Revision 17	NRC053	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> NRC053 contains corrections to Sub-section 5.4.2.2 of DCD Revision 16.				
<i>Reference Information:</i> RAI-TR35-001 R1				

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<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
5.4.9.4	Accepted for Revision 17	NRC063	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> NRC063 contains corrections to Sub-section 5.4.9.4 of DCD Revision 16.				
<i>Reference Information:</i> APP-GW-GLN-138 (TR138), Rev 0				

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APP-GW-GL-700, Revision 16, "AP1000 Design Control Document"

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
6.1.1.3	Accepted for Revision 17	NRC174	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> NRC174 contains corrections to Section 6.1.1.3 to be consistent with RAI- TR106-CIB1-01				
<i>Reference Information:</i> RAI-TR106-CIB1-01				
<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
6.2.1.2.3.2	Accepted for Revision 17	NRC088	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> NRC088 contains corrections to Sub-section 6.2.1.2.3.2 of DCD Revision 16. The basis for the change to be consistent with APP-GW-GLR-016.				
<i>Reference Information:</i> APP-GW-GLR-016 (TR36), Rev 0				

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APP-GW-GL-700, Revision 16, "AP1000 Design Control Document"

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
1.9.5.1.15, 3.9.6, 3.9-16, 5.2.4, 6.6	Accepted for Revision 17	NRC148 (Chapt 6)	Tier 2	NRC Prior Approval Not Required

Description:

NRC 148 contains changes to Sections 1.9.5.1.15, 3.9.3.4.3, 3.9.3.4.4, 3.9.6, 3.9.6.2, 3.9.6.2.1, 3.9.6.2.2, 3.9.6.2.3, 3.9.6.3, Table 3.9-16 and 6.6 of the DCD Revision 16 to be consistent with APP-GW-GLN-138

Reference Information:

APP-GW-GLN-138 (TR138), Rev 0

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
Table 6.2.3-1	Accepted for Revision 17	NRC087	Tier 2	NRC Prior Approval Not Required

Description:

NRC087 contains corrections to Table 6.2.3-1 to clarify the isolation signal to signal valve CCS-PL-208 (changed from "SS" to "S") No change required to section 6.2.3.2.2.

Reference Information:

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<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
6.2.3-1	Accepted for Revision 17	NRC150	Tier 2	NRC Prior Approval Not Required

Description:

NRC150 contains corrections to Sub-section 6.2.3 (Table 6.2.3-1) of DCD Revision 16. Corrected valve tags for CAS and CCS in Table 6.2.3-1.

Reference Information:

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
6.3.8.2	Accepted for Revision 17	NRC137	Tier 2	NRC Prior Approval Not Required

Description:

NRC137 contains corrections to Sub-section 6.3.8.2 of DCD Revision 16 to be consistent with APP-GW-GLR-079.

Reference Information:

APP-GW-GLR-079 (TR26), Rev 1

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APP-GW-GL-700, Revision 16, "AP1000 Design Control Document"

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
6.4.2.3	Accepted for Revision 17	NRC068	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> NRC068 contains corrections to Sub-section 6.4.2.3 of DCD Revision 16.				
<i>Reference Information:</i>				
<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
6.6.6	Accepted for Revision 17	NRC092	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> NRC092 contains corrections to Sub-section 6.6.6 of DCD Revision 16. Added reference to IWE-3000 and IWF-3000. Clarified wording.				
<i>Reference Information:</i>				

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APP-GW-GL-700, Revision 16, "AP1000 Design Control Document"

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
7.1, 7.2, 7.3	Accepted for Revision 17	NRC114	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> NRC 114 contains changes to Sections 7.1.1, 7.1.2, 7.1.3, 7.1.7, 7.2.1, and 7.3.1 of the DCD Revision 16 to be consistent with APP-GW-GLR-080, Rev 0.				
<i>Reference Information:</i> APP-GW-GLR-080 (TR80), Rev 0				

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
7.3, 7.5	Accepted for Revision 17	NRC112	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> NRC 112 contains changes to Sections 7.1.3 and 7.3.1.2.17, Table 7.3-1 (sheet 6 and 8), Table 7.5-1 (sheet 2 of 12) and Table 7.5-7 (sheet 4 of 4) of DCD Revision 16 to be consistent with APP-GW-GLR-080, Rev 0.				
<i>Reference Information:</i> APP-GW-GLR-080 (TR80), Rev 0				

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<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
7.2, 7.3	Accepted for Revision 17	NRC111	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> NRC 111 contains corrections to Sections 7.2.1.1.1, 7.2.1.1.3, and Table 7.3-1 (sheet 8 of 9), Table 7.3-2 (sheets 1 & 3 of 4), Table 7.3-4 (sheet 2 of 2) to be consistent with APP-GW-GLR-080, Rev.0.				
<i>Reference Information:</i> APP-GW-GLR-080 (TR80), Rev 0				

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
7.2-1	Accepted for Revision 17	NRC138	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> NRC 138 has changes to the notes of Figure 7.2-1 (sheet 20 of 20) to be consistent with RAI-TR97-ICE-03.				
<i>Reference Information:</i> RAI-TR97-ICE-03				

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<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
Table 7.3-2	Accepted for Revision 17	NRC081	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> NRC 081 contains changes to Table 7.3-2 (Sheet 3) of the DCD Revision 16 where P-12 Functions (d) and (e) were changed to be consistent with APP-GW-GLR-080, Rev 0.				
<i>Reference Information:</i> APP-GW-GLR-080 (TR80), Rev 0				

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
Table 7.5-1, Table 7.5-7	Accepted for Revision 17	NRC145	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> NRC 145 contains changes to Table 7.5-1 (sheet 2) of the DCD revision 16 to be consistent with the corrected pressure range on steam line pressure from Table 7.3-4. Changes made to Table 7.5-1 Sheet 7 for the CMT Water Level Sensor ranges and MCR Pressure Relief Valve Status on Table 7.5-1 sheet 10. These changes are consistent with APP-GW-GLN-123 (TR123) and APP-GW-GLR-080 (TR080), Rev 0. Also Table 7.5-7(sheet 4 of 4) has MCR pressure relief isolation valve status added to be consistent with APP-GW-GLR-080, Rev 0.				
<i>Reference Information:</i> APP-GW-GLN-123 (TR123), Rev 0; APP-GW-GLR-080 (TR80), Rev 0				

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<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
Table 7.5-1	Accepted for Revision 17	NRC084	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> NRC 084 adds the line item RCS sampling line isolation valve status to Table 7.5-1 (sheet 9 of 12) of the DCD Revision 16 to be consistent with APP-GW-GLR-080, Rev 0				
<i>Reference Information:</i> APP-GW-GLR-080 (TR80), Rev 0				

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
Table 7.5-1, Table 7.5-8, 9.4.1.1.2, 9A	Accepted for Revision 17	NRC052 (Chapt 7)	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> NRC 052 has changes to Table 7.5-1 (sheet 12 of 12) and Table 7.5-8 of the DCD Revision 16 that changes technical support center to control support area to be consistent with RAI-TR107-NSIR-06.				
<i>Reference Information:</i> APP-GW-GLR-107 (TR107), Rev 1 RAI-TR107-NSIR-06				

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<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
3.5-5, 3.5-7, 7.5-1, 9.4, 9A, 11.5, 13.3, 14.2	Accepted for Revision 17	NRC123 (Chapt 7)	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> NRC123 contains corrections to change "technical support center" to "control support area" to be consistent with TR107, APP-GW-GLR-107.				
<i>Reference Information:</i> APP-GW-GLR-107 (TR107), Rev 1 RAI-TR107-NSIR-02, RAI-TR107-NSIR-06				
<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
7	Accepted for Revision 17	NRC050 (Chapt 7)	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> NRC050 contains corrections to change DCD text from "technical support center" to "control support area" in the DCD. The basis for the change is TR 107, APP-GW-GLR-107.				
<i>Reference Information:</i> APP-GW-GLR-107 (TR107), Rev 1 RAI-TR107-NSIR-01, RAI-TR107-NSIR-06				

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APP-GW-GL-700, Revision 16, "AP1000 Design Control Document"

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
8.1	Accepted for Revision 17	NRC076	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> NRC076 contains editorial corrections to facilitate site specific utility connections to be described in the FSAR by using standard wording. This change makes it such that DCD changes will not be required once FSAR information is provided.				
<i>Reference Information:</i>				

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APP-GW-GL-700, Revision 16, "AP1000 Design Control Document"

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
13.6-1, 9.1.1.2	Accepted for Revision 17	NRC128 (Chapt 9)	Tier 2	NRC Prior Approval Not Required

Description:

NRC128 - Based on discussions with the NRC, the decision has been made to remove the closure of 13.6-1 to provide a plant specific physical security plan. The security plan is being provided as part of the COL applications. This editorial change is made to the DCD to enable the plant specific physical security plan to be addressed in the COLA. Section 9.1.1.2 reference changed for consistency.

Reference Information:

APP-GW-GLR-066 (TR94), Rev 1

RAI-TR94-NSIR-01

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
9.1	Accepted for Revision 17	NRC104 (Chapt 9)	Tier 2	NRC Prior Approval Not Required

Description:

NRC104 contains changes to Section 9.1.1.3, 9.1.6.2 and 9.1.7 of the DCD Revision 16 to be consistent with APP-GW-GLR-030, Rev 0.

Reference Information:

APP-GW-GLR-030 (TR67), Rev 0

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<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
Table 9.1-4	Accepted for Revision 17	NRC161	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> NRC161 contains changes to Table 9.1-4 of the DCD Revision 16 to be consistent with APP-GW-GLR-019, Rev 2.				
<i>Reference Information:</i> APP-GW-GLN-019 (TR103), Rev 2				

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
9.3.6	Accepted for Revision 17	NRC157	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> NRC157 contains changes to Section 9.3.6.3.7, 9.3.6.4.5.1, 9.3.6.6.1.2, 9.3.6.7 anf Figure 9.3.6-1(Sheets 1 & 2) of the DCD Revision 16 to be consistent with APP-GW-GLR-080,Rev 0.				
<i>Reference Information:</i> APP-GW-GLR-080 (TR80), Rev 0				

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<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
9	Accepted for Revision 17	NRC050 (Chapt 9)	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> NRC050 contains corrections to change DCD text from "technical support center" to "control support area" in the DCD. The basis for the change is TR 107, APP-GW-GLR-107.				
<i>Reference Information:</i> APP-GW-GLR-107 (TR107), Rev 1 RAI-TR107-NSIR-01				
<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
9.4.1	Accepted for Revision 17	NRC067	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> NRC 067 contains changes to Section 9.4.1.1.1, 9.4.1.1.2, 9.4.1.2.1.2, 9.4.1.2.3.1, 9.4.1.4, 9.4.1.5, 9.4.12 and 9A.3.4.16 of the DCD Revision 16 to be consistent with RAI-TR107-NSIR-01.				
<i>Reference Information:</i> RAI-TR107-NSIR-01				

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<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
3.5-5, 3.5-7, 7.5-1, 9.4, 9A, 11.5, 13.3, 14.2	Accepted for Revision 17	NRC123 (Chapt 9)	Tier 2	update later
<i>Description:</i> NRC123 contains corrections to change "technical support center" to "control support area" to be consistent with TR107, APP-GW-GLR-107.				
<i>Reference Information:</i> APP-GW-GLR-107 (TR107), Rev 1 RAI-TR107-NSIR-02				
<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
Table 7.5-1, 9.4.1.1.2, 9A	Accepted for Revision 17	NRC052 (Chapt 9)	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> NRC 052 contains changes to Section 9.4.1.2.1.2, 9.4.1.4, 9.4.12 and 9A.3.4.16 of the DCD Revision 16 to be consistent with RAI-TR107-NSIR-06.				
<i>Reference Information:</i> RAI-TR107-NSIR-06				

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<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
9.5.2.5.3	Accepted for Revision 17	NRC054	Tier 2	NRC Prior Approval Not Required

Description:

NRC054 contains changes to Section 9.5.2.5.3 and 9.5.3 of the DCD Revision 16 to be consistent with RAI-TR107-NSIR-01.

Reference Information:

RAI-TR107-NSIR-01

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
9.5.4-1	Accepted for Revision 17	NRC072	Tier 2	NRC Prior Approval Not Required

Description:

NRC 072 contains changes to Figures 9.5.4-1 (Sheets 1, 2, and 3) of the DCD Revision 16 to delete Auxiliary Boiler out of the title.

Reference Information:

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<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
10.2.1.2	Accepted for Revision 17	NRC071	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> NRC071 identifies an editorial correction (typo) in Section 10.2.1.2 of the DCD Revision 16. "The system provides extraction steam for six stages of regenerative feedwater heating." This should be seven stages of regenerative feedwater heating. The change was captured in APP-GW-GLN-018 (TR86), Rev 1				
<i>Reference Information:</i> APP-GW-GLN-018 (TR86), Rev 1				

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
10.4.7.2.2	Accepted for Revision 17	NRC070	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> NRC070 identifies an editorial correction (typo) in the Subsection 10.4.7.2.2 title of the DCD Revision 16. "High-Pressure Feedwater Heater" should be "High-Pressure Feedwater Heaters"				
<i>Reference Information:</i> APP-GW-GLN-018 (TR86), Rev 1				

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<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
10.4.7.2.3.1.3	Accepted for Revision 17	NRC066	Tier 2	NRC Prior Approval Not Required

Description:

NRC066 identifies an editorial correction (typo) in Tier 2, Section 10.4.7.2.3.1.3 of the DCD Revision 16, "Feedwater is recirculated from downstream of the No. 6 feedwater heaters to the main condenser for cleanup and deaeration of the condensate and feedwater inventory." The reference should be to the No. 7 feedwater heaters. The change was captured in APP-GW-GLN-018 (TR86), Rev 1

Reference Information:

APP-GW-GLN-018 (TR86), Rev 1

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APP-GW-GL-700, Revision 16, "AP1000 Design Control Document"

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
11.4.2.1	Accepted for Revision 17	NRC122	Tier 2	NRC Prior Approval Not Required

Description:

NRC122 contains an editorial correction to DCD Subsection 11.4.2.1, Rev. 16. In the 12th paragraph, the first sentence starting with, "A conservative estimate ...", the last word in the sentence was changed from 'cycles' to 'system' for clarity.

Reference Information:

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
11.4.2.4.2	Accepted for Revision 17	NRC116	Tier 2	NRC Prior Approval Not Required

Description:

NRC116 contains an editorial change; the inclusion of a numeric value could lead to confusion. The ability to ship wastes off-site will be appropriately regulated under existing regulations (eg: 10 CFR 61, 10 CFR 20.2002)

Reference Information:

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<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
11.5.5	Accepted for Revision 17	NRC080	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> NRC080 contains an editorial correction to Section 11.5.5 of the DCD "For further Regulatory Guide 1.97 information refer to Appendix 7A and Section 7.5." The reference should be to Appendix 1A not 7A.				
<i>Reference Information:</i> RAI-TR107-NSIR-01				
<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
11.5.6	Accepted for Revision 17	NRC050 (Chapt 11)	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> NRC050 contains corrections to change DCD text from "technical support center" to "control support area" in the DCD. The basis for the change is TR 107, APP-GW-GLR-107.				
<i>Reference Information:</i> APP-GW-GLR-107 (TR107), Rev 1 RAI-TR107-NSIR-01				

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<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
3.5-5, 3.5-7, 7.5-1, 9.4, 9A, 11.5, 13.3, 14.2	Accepted for Revision 17	NRC123 (Chapt11)	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> NRC123 contains corrections to change "technical support center" to "control support area" to be consistent with TR107, APP-GW-GLR-107.				
<i>Reference Information:</i> APP-GW-GLR-107 (TR107), Rev 1 RAI-TR107-NSIR-02				

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APP-GW-GL-700, Revision 16, "AP1000 Design Control Document"

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
12.2.1.2.4, Table 12.2-15, Table 12.2-18	Accepted for Revision 17	NRC086	Tier 2	NRC Prior Approval Not Required

Description:

The following changes are made to Chapter 12 to be consistent with changes made in Chapter 4 to the Ag-In-Cd rodlets. The basis for the change is APP-GW-GLR-059 (TR18) :

DCD Section 12.2.1.2.4 - change the second sentence of the second paragraph to read "The gray rods contain either type 304 stainless steel or Ag-In-Cd pellets in a stainless steel sleeve." i.e. add "in a stainless steel sleeve" to the sentence.

DCD Table 12.2-15 - The note at the bottom of the table should be changed to read "The absorber cross-sectional area is 0.130 square centimeters per rod and ..."; i.e. the area is reduced from 0.589 to 0.130 sq. cm.

DCD Table 12.2-18 - The title of the table should be changed to read "IRRADIATED STAINLESS STEEL SOURCE STRENGTHS (0.12 WEIGHT PERCENT COBALT)" ; i.e. delete "TYPE 304" from the title. In addition, the last item in the note at the bottom of the table should be changed to read " - Gray rod sleeve - 0.606 cm²" - ; i.e. change "pellet - 0.589" to "sleeve - 0.606":

Reference Information:

APP-GW-GLR-059 (TR18), Rev 0

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APP-GW-GL-700, Revision 16, "AP1000 Design Control Document"

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
13.6, 13.6.1	Accepted for Revision 17	NRC128 (Chapt 13)	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> NRC128 - Based on discussions with the NRC, the decision has been made to remove the closure of 13.6 and 13.6.1 to provide a plant specific physical security plan. The security plan is being provided as part of the R-COL. This editorial change is made to the DCD to enable the plant specific physical security plan to be addressed in the COLA.				
<i>Reference Information:</i> APP-GW-GLR-066 (TR94), Rev 1RAI-TR94-NSIR-01				

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APP-GW-GL-700, Revision 16, "AP1000 Design Control Document"

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
3.5-5, 3.5-7, 7.5-1, 9.4, 9A, 11.5, 13.3, 14.2	Accepted for Revision 17	NRC123 (Chapt 14)	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> NRC123 contains corrections to change "technical support center" to "control support area" to be consistent with TR107, APP-GW-GLR-107 and RAI-TR107-NSIR-01.				
<i>Reference Information:</i> APP-GW-GLR-107 (TR107), Rev 1 RAI-TR107-NSIR-01				
<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
14.2	Accepted for Revision 17	NRC050 (Chapt 14)	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> NRC050 contains corrections to change DCD text from "technical support center" to "control support area" in the DCD. The basis for the change is TR 107, APP-GW-GLR-107.				
<i>Reference Information:</i> APP-GW-GLR-107 (TR107), Rev 1 RAI-TR107-NSIR-01				

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<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
14.3-2	Accepted for Revision 17	NRC158	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> NRC158 contains corrections to Table 14.3-2 to be consistent with APP-GW-GLR-080 (TR80)				
<i>Reference Information:</i> APP-GW-GLR-080 (TR80), Rev 0				
<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
14.3-3	Accepted for Revision 17	NRC096	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> NRC096 contains editorial corrections to Tables 14.3-3 and Table 14.3-6 to be consistent with APP-GW-GLN-022 (TR97)				
<i>Reference Information:</i> APP-GW-GLN-022 (TR97), Rev 1				

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<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
14.3	Accepted for Revision 17	NRC098	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> NRC098 contains editorial corrections to Table 14.3-7 to be consistent with APP-GW-GLN-122 (TR122)				
<i>Reference Information:</i> APP-GW-GLN-122 (TR122), Rev 0				

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
14.4.3	Accepted for Revision 17	NRC029	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> NRC029 contains editorial corrections to Section 14.4.3 to be consistent with APP-GW-GLR-038 (TR71B)				
<i>Reference Information:</i> APP-GW-GLR-038 (TR71B), Rev 1 RAI-TR71B-001				

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APP-GW-GL-700, Revision 16, "AP1000 Design Control Document"

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
15.0-4A, 15.0-6	Accepted for Revision 17	NRC155	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> NRC155 contains editorial changes to delete High neutron flux from Table 15.0-4a and to change P-8 interlock to P-10 interlock in Table 15.0-6. The basis for the change is APP-GW-GLR-080.				
<i>Reference Information:</i> APP-GW-GLR-080 (TR80), Rev 0				

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
15A	Accepted for Revision 17	NRC142	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> NRC142 contains corrections to be consistent with the changes made in Table 5.0-1, Table 2-1, and Table 14.3-7. Changes to 15A.3.3 are editorial and consistent with APP-GW-GLN-122. The basis for the changes is APP-GW-GLN-122.				
<i>Reference Information:</i> APP-GW-GLN-122 (TR122), Rev 0				

Chapter 16

Attachment A

AP1000 DCD Impact Report

APP-GW-GL-700, Revision 16, "AP1000 Design Control Document"

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
16: TS Table 3.3.1-1	Accepted for Revision 17	NRC085	Tier 2	NRC Prior Approval Required

Description:

NRC085 contains an editorial correction (typo) to remove the end bracket for the Reviewer's Note in Table 3.3.1-1 on page 3.3.1-11

Reference Information:

APP-GW-GLN-075 (TR74C), Rev 1

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
16: TS 3.3.1	Accepted for Revision 17	NRC173	Tier 2	NRC Prior Approval Required

Description:

NRC173 contains pagination pointer corrections to Table 3.3.1-1 page 2 Function 6 & 7 to refer to Table 3.3.1-1 Page 5 of 5

Reference Information:

Attachment A

AP1000 DCD Impact Report

APP-GW-GL-700, Revision 16, "AP1000 Design Control Document"

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
16: TS Table 3.3.2-1	Accepted for Revision 17	NRC101	Tier 2	NRC Prior Approval Required

Description:

NRC101 contains corrections to Table 3.3.2-1 page 10, and SR 3.8.1.2. The basis for the changes is APP-GW-GLR-064 (TR74A), Rev 0 and APP-GW-GLN-075 (TR74C), Rev 1

Reference Information:

APP-GW-GLR-064 (TR74A), Rev 0;
APP-GW-GLN-075 (TR74C), Rev 1

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
16: TS 4.3.1, 4.3-1	Accepted for Revision 17	NRC100	Tier 2	NRC Prior Approval Required

Description:

NRC100 contains corrections (typos) to TS 4.3.1 and Figure 4.3-1 of DCD Revision 16. The word "an" in the following statement will be changed to the word "any" in DCD Revision 17. "New or partially spent fuel assemblies with an discharge burnup may be allowed unrestricted storage in Region 1 and defective Fuel Cells of Figure 4.3-1". Figure 4.3-1, the word "module" was misspelled.

Reference Information:

Attachment A

AP1000 DCD Impact Report

APP-GW-GL-700, Revision 16, "AP1000 Design Control Document"

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
16: TS 5.3.1	Accepted for Revision 17	NRC119	Tier 2	NRC Prior Approval Required

Description:

NRC119 contains the addition of brackets to the entire second sentence of section 5.3.1 for clarity.

Reference Information:

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
16: TS 5.5.1	Accepted for Revision 17	NRC149	Tier 2	NRC Prior Approval Required

Description:

NRC149 contains corrections to section 5.5.1 to change the reference from 10 CFR 20.106, which no longer exists, to 10 CFR 20.1302.

Reference Information:

Attachment A

AP1000 DCD Impact Report

APP-GW-GL-700, Revision 16, "AP1000 Design Control Document"

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
16: TS 5.5.9	Accepted for Revision 17	NRC162	Tier 2	NRC Prior Approval Required

Description:

NRC162 contains an editorial correction (typo) to GTS 5.5.9 Table 3.9 dot 17 should be Table 3.9 dash 17

Reference Information:

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
16: TS B.3.3.2	Accepted for Revision 17	NRC156	Tier 2	NRC Prior Approval Required

Description:

NRC156 contains corrections to B 2.2.1, B 3.3.2 Subsection 15, 15.a, 18.a, 18.f, and Action D.1 to be consistent with APP-GW-GLN-075 (TR74C), Rev 0

Reference Information:

APP-GW-GLN-075 (TR74C), Rev 0

Attachment A

AP1000 DCD Impact Report

APP-GW-GL-700, Revision 16, "AP1000 Design Control Document"

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
16: TS B 3.4.8	Accepted for Revision 17	NRC055	Tier 2	NRC Prior Approval Required
<i>Description:</i> NRC055 contains corrections to B 3.4.8 Surveillance Requirements based on (TR74C) APP-GW-GLN-075.				
<i>Reference Information:</i> APP-GW-GLN-075 (TR74C), Rev 1				

Chapter 18

Attachment A

AP1000 DCD Impact Report

APP-GW-GL-700, Revision 16, "AP1000 Design Control Document"

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
18.2.6.2	Accepted for Revision 17	NRC152	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> NRC152 contains changes to Section 18.2.6.2 in the DCD Revision 16 to be consistent with APP-GW-GLR-136. APP-GW-GLR-136 has been added as a reference in Section 18.2.7				
<i>Reference Information:</i> APP-GW-GLR-136 (TR136), Rev 0				
<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
18.2	Accepted for Revision 17	NRC065	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> NRC065 contains an editorial correction to delete the parenthetical reference to Note 1, (1), in the box containing the words "Procedure Development" on DCD Figure 18.2-3 The basis for this deletion is Revision 1 of Technical Report 70, APP-GW-GLR-040, which closes COL Applicant actions with respect to Operating Procedure development. In addition, this deletion will ensure that Figure 18.2-3 of the DCD is consistent with Table 1.8-2 which clearly states that, with respect to COL Information Item 18.9-1, there are no COL Applicant or COL Holder actions required.				
<i>Reference Information:</i> APP-GW-GLR-040 (TR70), Rev 1				

Chapter 19

Attachment A

AP1000 DCD Impact Report

APP-GW-GL-700, Revision 16, "AP1000 Design Control Document"

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
19.58	Accepted for Revision 17	NRC170	Tier 2	NRC Prior Approval Not Required

Description:

NRC170 contains corrections to 19.58.2, 19.58.3, and 19.58.4 based on APP-GW-GLR-101 (TR101), Rev 1

Reference Information:

APP-GW-GLR-101 (TR101), Rev 1

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
19.59-18	Accepted for Revision 17	NRC159	Tier 2	NRC Prior Approval Not Required

Description:

NRC159 contains corrections to Table 19.59-18 sheet 23 of DCD Revision 16 to be consistent with Technical Report TR80, APP-GW-GLR-080.

Reference Information:

APP-GW-GLR-080 (TR80), Rev 0

ATTACHMENT B

Tier 1

2.2.1 Containment System

Design Description

The containment system (CNS) is the collection of boundaries that separates the containment atmosphere from the outside environment during design basis accidents.

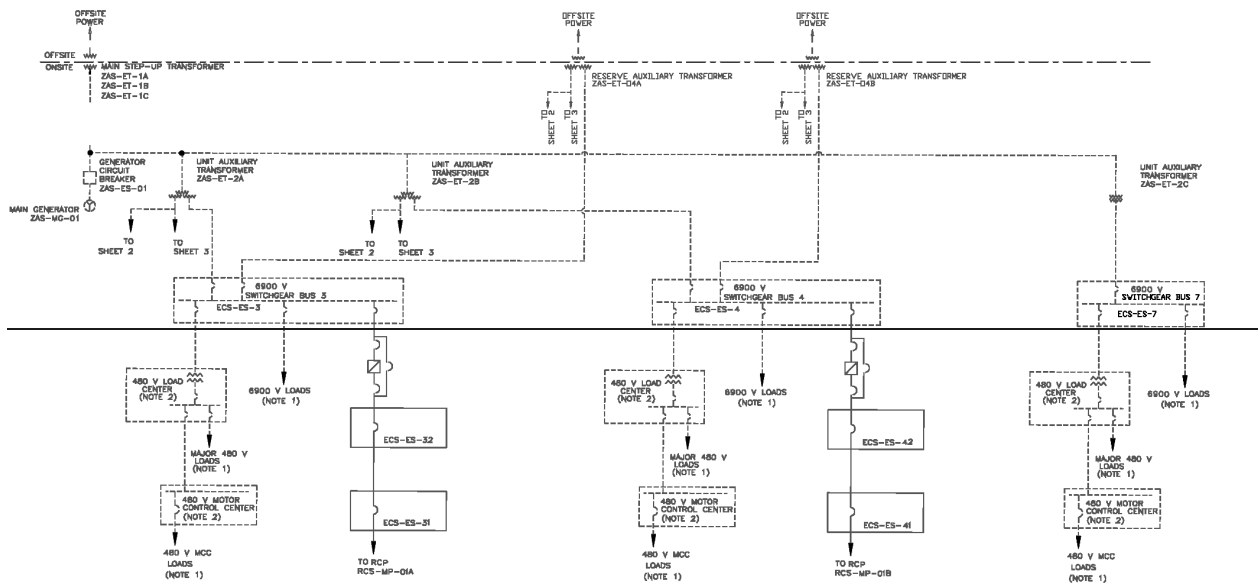
The CNS is as shown in Figure 2.2.1-1 and the component locations of the CNS are as shown in Table 2.2.1-4.

1. The functional arrangement of the CNS and associated systems is as described in the Design Description of this Section 2.2.1.
2.
 - a) The components identified in Table 2.2.1-1 as ASME Code Section III are designed and constructed in accordance with ASME Code Section III requirements.
 - b) The piping identified in Table 2.2.1-2 as ASME Code Section III is designed and constructed in accordance with ASME Code Section III requirements.
3.
 - a) Pressure boundary welds in components identified in Table 2.2.1-1 as ASME Code Section III meet ASME Code Section III requirements.
 - b) Pressure boundary welds in piping identified in Table 2.2.1-2 as ASME Code Section III meet ASME Code Section III requirements.
4.
 - a) The components identified in Table 2.2.1-1 as ASME Code Section III retain their pressure boundary integrity at their design pressure.
 - b) The piping identified in Table 2.2.1-2 as ASME Code Section III retains its pressure boundary integrity at its design pressure.
5. The seismic Category I equipment identified in Table 2.2.1-1 can withstand seismic design basis loads without loss of structural integrity and safety function.
6.
 - a) The Class 1E equipment identified in Table 2.2.1-1 as being qualified for a harsh environment can withstand the environmental conditions that would exist before, during, and following a design basis accident without loss of safety function for the time required to perform the safety function.
 - b) The Class 1E components identified in Table 2.2.1-1 are powered from their respective Class 1E division.
 - c) Separation is provided between CNS Class 1E divisions, and between Class 1E divisions and non-Class 1E cable.
 - d) The non-Class 1E electrical penetrations identified in Table 2.2.1-1 as being qualified for a harsh environment can withstand the environmental conditions that would exist before, during and following a design basis accident without loss of containment pressure boundary integrity.

NRC 176

Table 2.2.1-3 (cont.) Inspections, Tests, Analyses, and Acceptance Criteria		
Design Commitment	Inspections, Tests, Analyses	Acceptance Criteria
6.a) The Class 1E equipment identified in Table 2.2.1-1 as being qualified for a harsh environment can withstand the environmental conditions that would exist before, during, and following a design basis accident without loss of safety function for the time required to perform the safety function.	<p>i) Type tests, analyses, or a combination of type tests and analyses will be performed on Class 1E equipment located in a harsh environment.</p> <p>ii) Inspection will be performed of the as-installed Class 1E equipment and the associated wiring, cables, and terminations located in a harsh environment.</p>	<p>i) A report exists and concludes that the Class 1E equipment identified in Table 2.2.1-1 as being qualified for a harsh environment can withstand the environmental conditions that would exist before, during, and following a design basis accident without loss of safety function for the time required to perform the safety function.</p> <p>ii) A report exists and concludes that the as-installed Class 1E equipment and the associated wiring, cables, and terminations identified in Table 2.2.1-1 as being qualified for a harsh environment are bounded by type tests, analyses, or a combination of type tests and analyses.</p>
6.b) The Class 1E components identified in Table 2.2.1-1 are powered from their respective Class 1E division.	Testing will be performed by providing a simulated test signal in each Class 1E division.	A simulated test signal exists at the Class 1E equipment identified in Table 2.2.1-1 when the assigned Class 1E division is provided the test signal.
6.c) Separation is provided between CNS Class 1E divisions, and between Class 1E divisions and non-Class 1E cable.	See Tier 1 Material, Table 3.3-6, item 7.d.	See Tier 1 Material, Table 3.3-6, item 7.d.
6.d) <u>The non-Class 1E electrical penetrations identified in Table 2.2.1-1 as being qualified for a harsh environmental can withstand the environmental conditions that would exist before, during and following a design basis accident without loss of containment pressure boundary integrity.</u>	<p>i) <u>Type tests, analyses, or a combination of type tests and analyses will be performed on non-Class 1E electrical penetrations located in a harsh environment.</u></p> <p>ii) <u>Inspection will be performed of the as-installed non Class 1E electrical penetrations located in a harsh environment.</u></p>	<p>i) <u>A report exists and concludes that the non-Class 1E electrical penetrations identified in Table 2.2.1-1 as being qualified for a harsh environment can withstand the environmental conditions that would exist before, during, and following a design basis accident without loss of containment pressure boundary integrity.</u></p> <p>ii. <u>A report exists and concludes that the as-installed non-Class 1E electrical penetrations identified in Table 2.2.1-1 as being qualified for a harsh environment are bounded by type tests, analyses, or a combination of type tests and analyses.</u></p>

NRC 176



NOTES:
 1. All loads are typical of one or more.
 2. Load centers and motor control centers are typical of one or more.

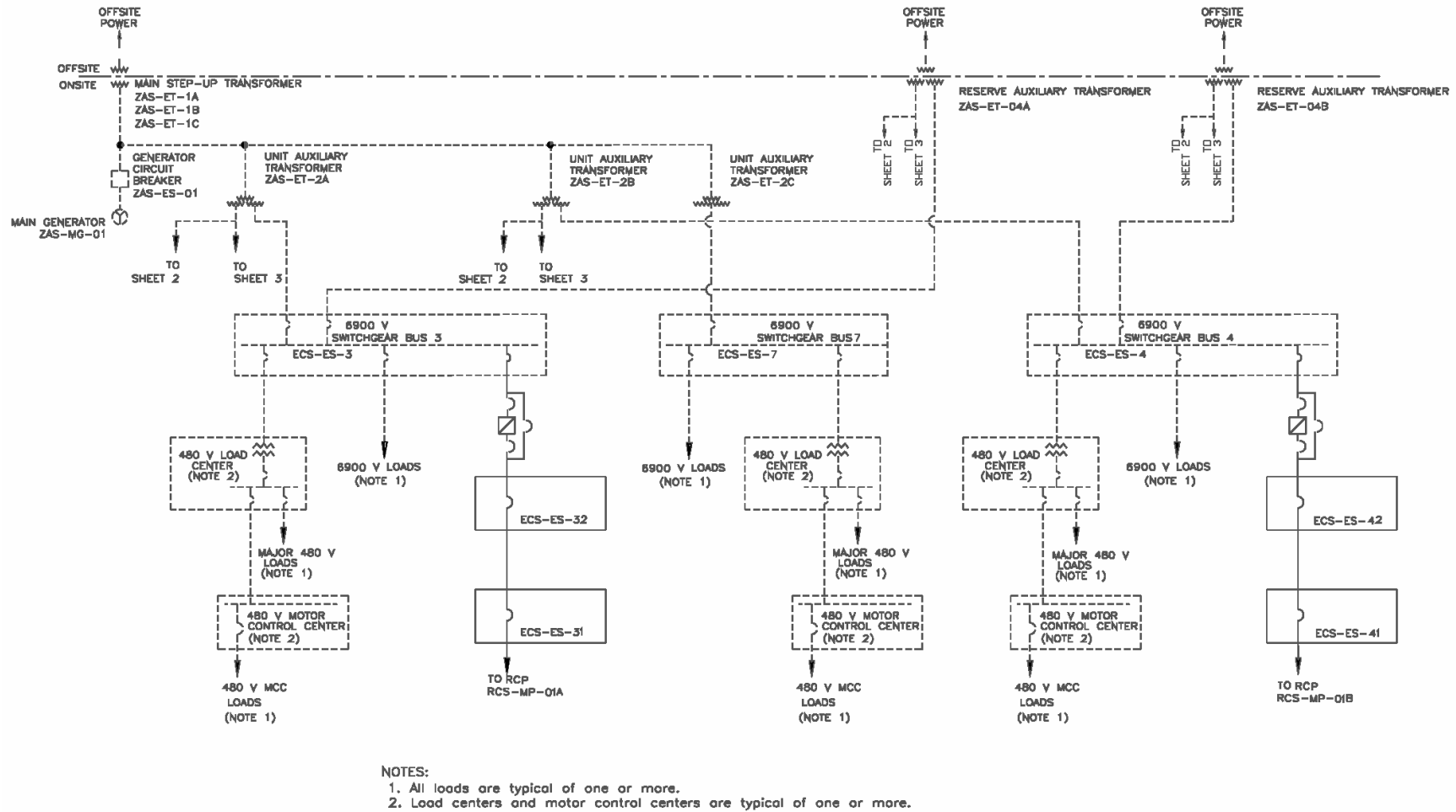


Figure 2.6.1-1 (Sheet 1 of 4)
Main ac Power System

Table 3.5-4 Airborne Radiation Monitors	
Equipment List	Equipment No.
Fuel Handling Area Exhaust Radiation Monitor	VAS-RE-001
Auxiliary Building Exhaust Radiation Monitor	VAS-RE-002
Annex Building Exhaust Radiation Monitor	VAS-RE003
Health Physics and Hot Machine Shop Exhaust Radiation Monitor	VHS-RE001
Radwaste Building Exhaust Radiation Monitor	VRS-RE023

Table 3.5-5 Area Radiation Monitors	
Primary Sampling Room Area Monitor	RMS-RE008
CSA Technical Support Center Area Monitor	RMS-RE016
Main Control Room Area Monitor	RMS-RE010

NRC 051
NRC 123

Table 3.5-7 (cont.)		
Component Name	Tag No.	Component Location
Wastewater Discharge Radiation Monitor	WWS-RE021	Yard/Turbine Building
Fuel Handling Area Exhaust Radiation Monitor	VAS-RE-001	Auxiliary Building
Auxiliary Building Exhaust Radiation Monitor	VAS-RE-002	Auxiliary Building
Annex Building Exhaust Radiation Monitor	VAS-RE003	Auxiliary Building
Health Physics and Hot Machine Shop Exhaust Radiation Monitor	VHS-RE001	Annex Building
Radwaste Building Exhaust Radiation Monitor	VRS-RE023	Radwaste Building
Primary Sampling Room Area Radiation Monitor	RMS-RE008	Auxiliary Building
CSA Technical Support Center Area Radiation Monitor	RMS-RE016	Control Support Area Technical Support Center
Main Control Room Area Radiation Monitor	RMS-RE010	Auxiliary Building

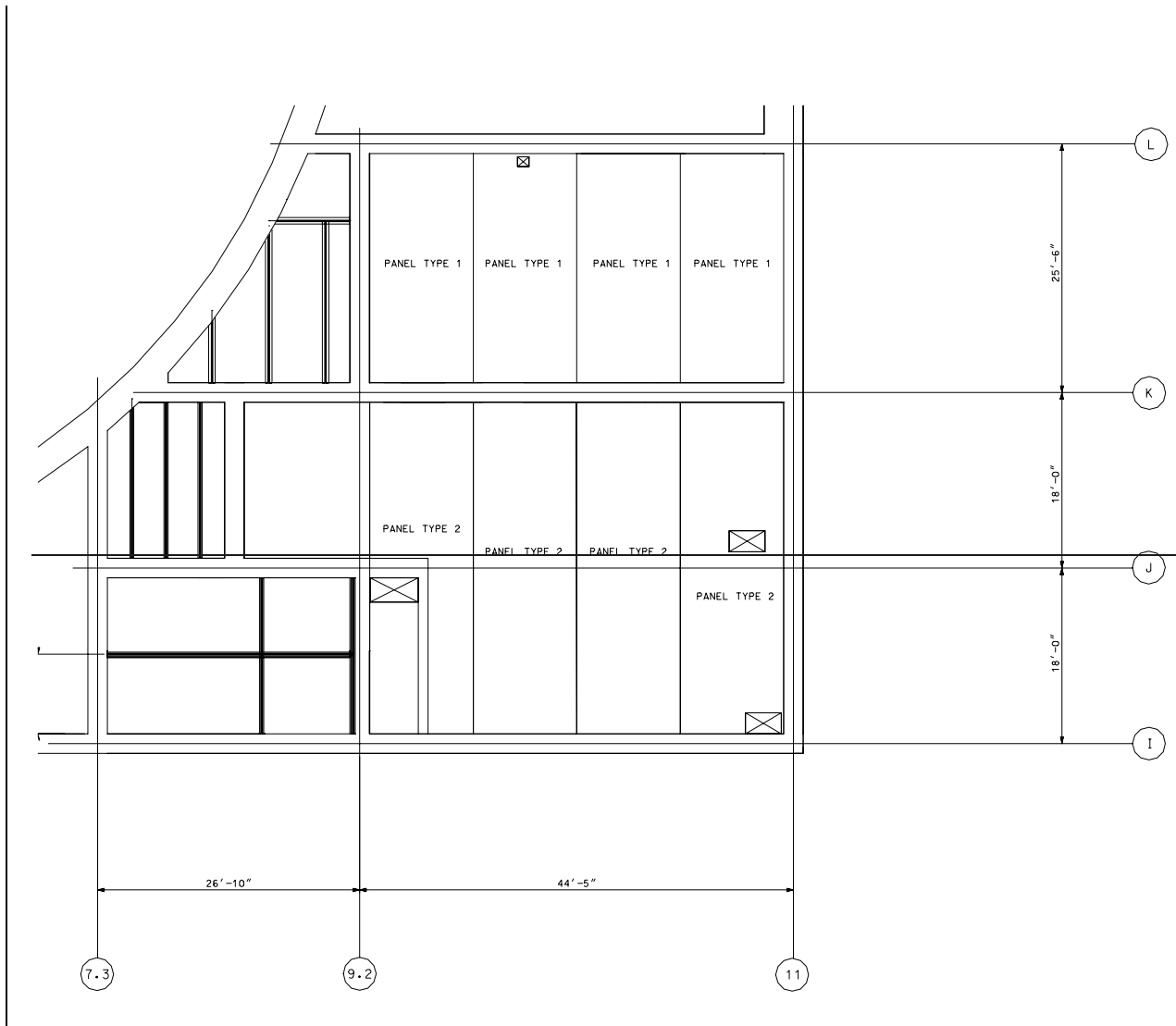
NRC 051
NRC 123

Table 5.0-1 (cont.) Site Parameters	
Atmospheric Dispersion Factors (X/Q)	
Site Boundary (0-2 hr)	$\leq 1.0 \times 10^{-3} \text{ sec/m}^3$
Site Boundary (annual average)	$\leq 2.0 \times 10^{-5} \text{ sec/m}^3$
Low Population Zone Boundary	
0 - 8 hr	$\leq \underline{5.022} \times 10^{-4} \text{ sec/m}^3$
8 - 24 hr	$\leq \underline{3.046} \times 10^{-4} \text{ sec/m}^3$
24 - 96 hr	$\leq \underline{1.510} \times 10^{-4} \text{ sec/m}^3$
96 - 720 hr	$\leq 8.0 \times 10^{-5} \text{ sec/m}^3$

NRC 144

ATTACHMENT B

Tier 2*



*NRC Staff approval is required prior to implementing a change in this information; see DCD Introduction Section 3.5.

NRC 094

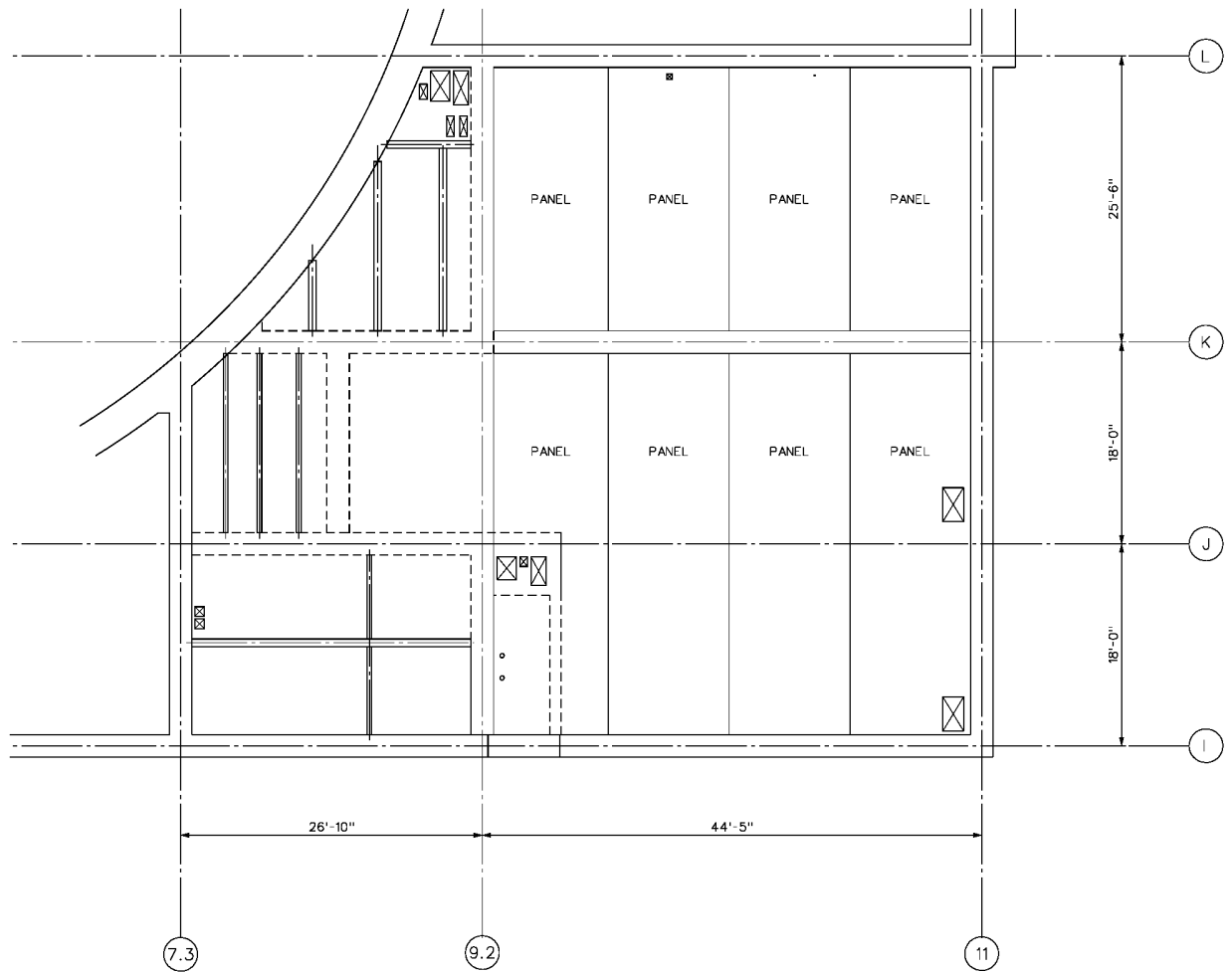
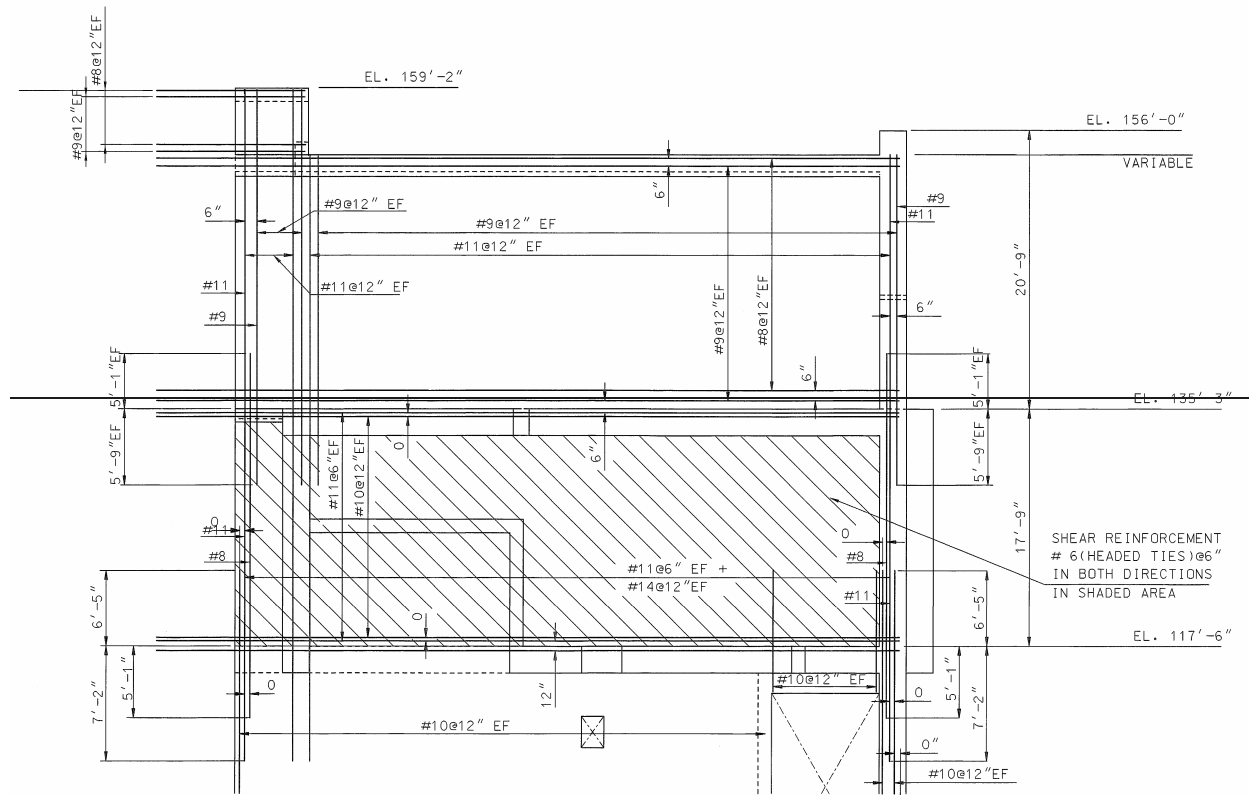


Figure 3H.5-9 (Sheet 1 of 3)

[Auxiliary Building Finned Floor]*

*NRC Staff approval is required prior to implementing a change in this information; see DCD Introduction Section 3.5.



*NRC Staff approval is required prior to implementing a change in this information; see DCD Introduction Section 3.5.

NRC 094

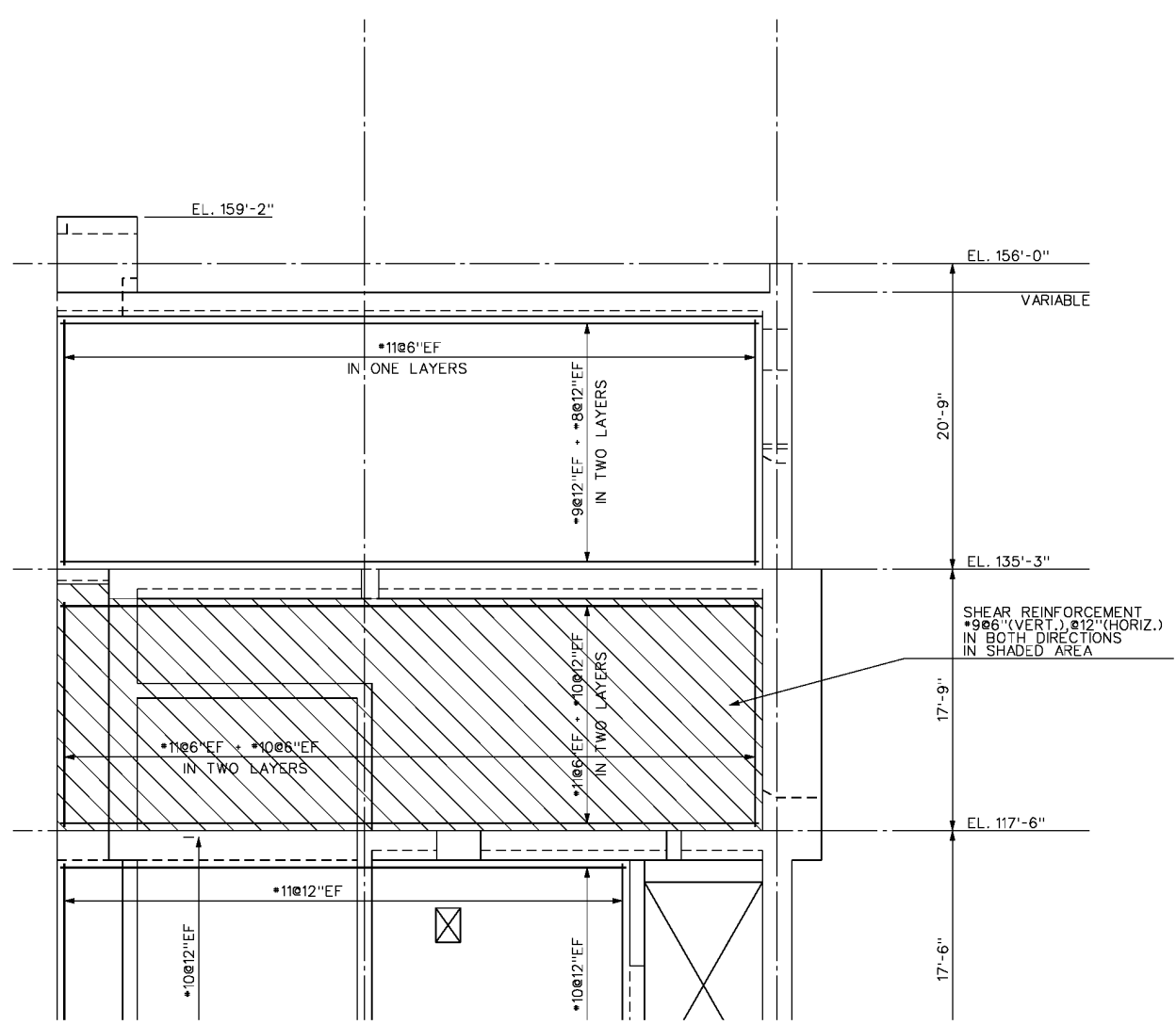


Figure 3H.5-12

[Typical Reinforcement in Wall L]*

*NRC Staff approval is required prior to implementing a change in this information; see DCD Introduction Section 3.5.

The diverse automatic actuations are:

- Trip rods via the motor generator set, trip turbine, initiate the passive residual heat removal, actuate core makeup tanks, and trip the reactor coolant pumps on low wide-range steam generator water level
- Open the passive heat removal discharge isolation valves and close the in-containment refueling water storage tank gutter isolation valves on high hot leg temperature
- Trip rods via the motor generator set, trip turbine, actuate the core makeup tanks, and trip the reactor coolant pumps on low pressurizer water level
- Isolate selected containment penetrations and start passive containment cooling water flow on high containment temperature

The selection of setpoints and time responses determine that the automatic functions do not actuate unless the protection and safety monitoring system has failed to actuate to control plant conditions. Capability is provided for testing and calibrating the channels of the diverse actuation system.

Manual Actuation Function

*[The manual actuation function of the diverse actuation system is implemented by hard-wiring the controls located in the main control room directly to the final loads in a way that completely bypasses the normal path through the control room multiplexers, the protection and safety monitoring system cabinets, and the diverse actuation system automatic logic.]**

The diverse manual functions are:

- Reactor and turbine trip
- Passive containment cooling actuation
- Core makeup tank actuation and reactor coolant pump trip
- Open stage 1 automatic depressurization system valves
- Open stage 2 automatic depressurization system valves
- Open stage 3 automatic depressurization system valves
- Open stage 4 automatic depressurization system valves
- Open the passive residual heat removal discharge isolation valves and close the in-containment refueling water storage tank gutter isolation valves
- Selected containment penetration isolation

*NRC Staff approval is required prior to implementing a change in this information; see DCD Introduction Section 3.5.

ATTACHMENT B

Tier 2

Chapter 1

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1. Introduction and General Description of the Plant AP1000 Design Control Document

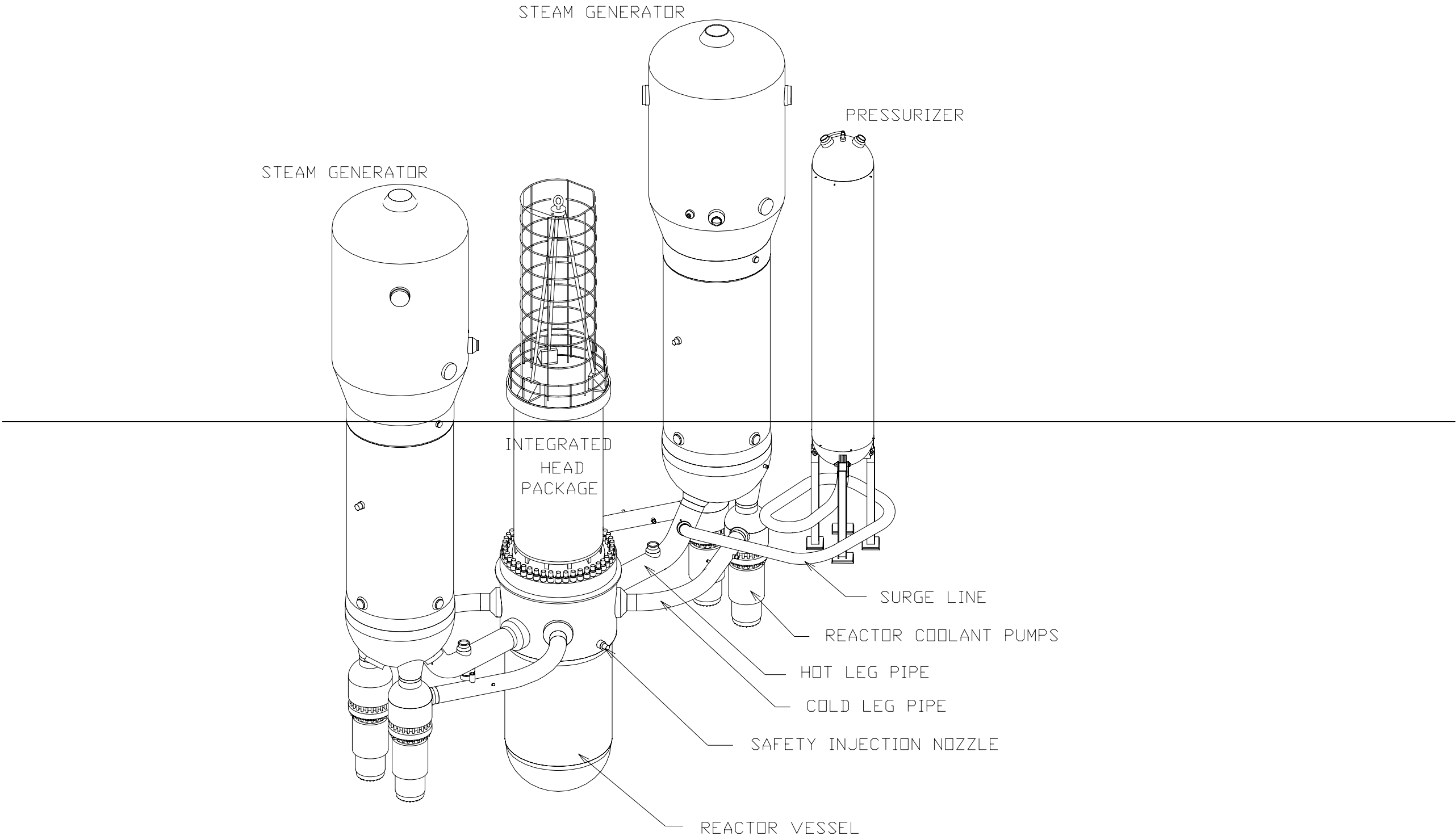
1.1.7 Combined License Information

NRC 130

Combined License applicants referencing the AP1000 certified design will provide the Generic construction and startup schedule information. ~~for the AP1000 certified design is provided in APP GW GLR 036 (Reference 1).~~

1.1.8 References

- ~~1. APP GW GLR 036, "Construction Plan and Startup Schedule," Westinghouse Electric Company LLC.~~



NRC 106

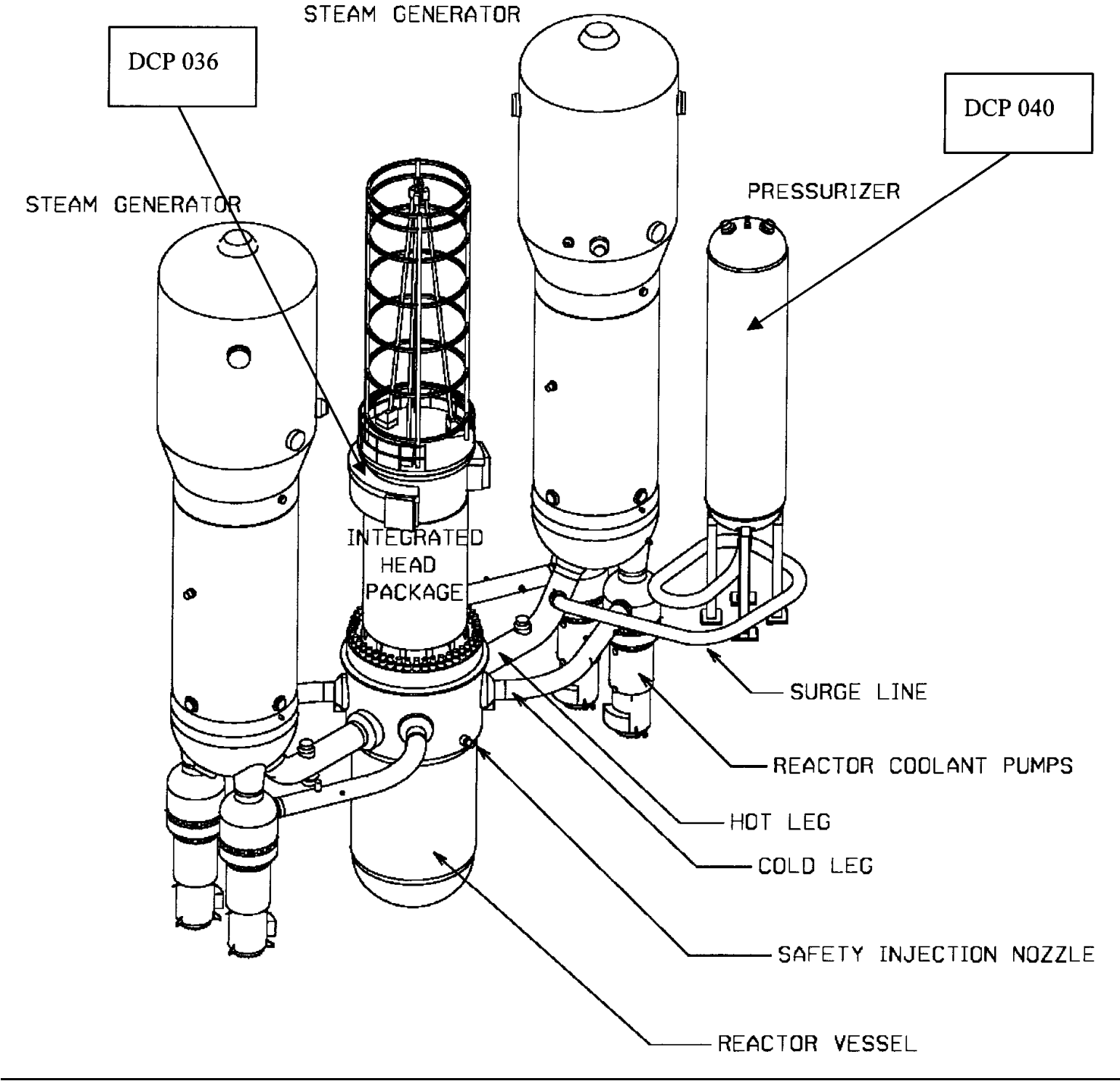


Figure 1.2-1
Reactor Coolant System

Security-Related Information, Withhold Under 10 CFR 2.390d

NRC 106
NRC 107

Figure 1.2-9

Nuclear Island General Arrangement
Plan at Elevation 117’-6” with Equipment

1. Introduction and General Description of the Plant AP1000 Design Control Document

Table 1.3-1 (Sheet 1 of 6)

AP1000 PLANT COMPARISON WITH SIMILAR FACILITIES

Systems – Components	DCD	AP1000	AP600	Reference 2 Loop
Plant design objective	1.2	60 yrs	60 yrs	40 yrs
NSSS power	4.0	3,415 MWt	1,940 MWt	3,410 MWt
Core power	4.0	3,400 MWt	1,933 MWt	3,390 MWt
Net electrical output	1.2	≥1,000 MWe	600 MWe	1,075 MWe
Reactor operating pressure	5.1	2,250 psia	2,250 psia	2,250 psia
Hot leg temp	5.1	610°F	600°F	611°F (Cycle 1) 603°F (current)
Steam Generator Design pressure	5.4	1200 psia	1200 psia	1100 psia
Main feedwater temp	10.3	440°F	435°F	445°F
Core	4.0			
Number fuel assem.		157	145	217
Active fuel length		168 in	144 in	150 in
Fuel assembly array		17 x 17	17 x 17	16 x 16
Fuel rod OD		0.374 in	0.374 in	0.382 in
Number control assem.		53	45	83
– Absorber material		Ag-In-Cd	Ag-In-Cd	B ₄ C/Ag-In-Cd
Number gray rod assem.		16	16	8 (part length)
– Absorber material		SS-304/Ag-In-Cd	SS-304/Ag-In-Cd	Inconel 625/ B ₄ C
Avg linear power		5.707 kW/ft	4.10 kW/ft	5.34 kW/ft
Heat flux hot channel factor, FQ		2.60	2.60	2.35

NRC 147

Table 1.6-1 (Sheet 12 of 20)

MATERIAL REFERENCED

DCD Section Number	Westinghouse Topical Report Number	Title
6A	WCAP-15846 (P) WCAP-15862	<u>WGOTHIC Application to AP600 and AP1000, Revision 1, March 2004</u>
	WCAP-14135 (P) WCAP-14138	Final Data Report for Passive Containment Cooling System Large Scale Test, Phase 2 and Phase 3, Revision 3, November 1998
	WCAP-15613 (P) WCAP-15706	AP1000 PIRT and Scaling Assessment Report, March 2001
7.1	WCAP-13382 (P) WCAP-13391 {WCAP-13383	AP600 Instrumentation and Control Hardware Description, May 1992 AP600 Instrumentation and Control Hardware and Software Design, Verification, and Validation Process Report, Revision 1, June 1996]*
	<u>7.1</u>	
7.1	<u>{WCAP-14605 (P)</u> <u>WCAP-14606 (NP)</u>	<u>Westinghouse Setpoint Methodology for Protection Systems – AP600, April 1996]*</u>
	{WCAP-16361-P WCAP-16361-NP	Westinghouse Setpoint Methodology for Protection Systems - AP1000, May 2006]*
	WCAP-14080 (P) WCAP-14081	AP600 Instrumentation and Control Software Architecture and Operation Description, June 1994
	<u>[WCAP-16096-NP-ACE-</u> <u>CES-195</u>	<u>Software Program Manual for Common Q Systems, Revision 01A, January 2004May 2000]*</u>
	<u>[WCAP-16097-P-A</u> <u>CENPD-396-P (P)</u> <u>WCAP-16097-NP-A</u>	<u>Common Qualified Platform, Revision 01, May 20034]*</u>
	{WCAP-15927	Design Process for AP1000 Common Q Safety Systems, August 2002]*
	WCAP-15776	Safety Criteria for the AP1000 Instrumentation and Control Systems, April 2002
7.2	<u>WCAP-16675-P</u> <u>WCAP-16675-NP</u>	<u>AP1000 Protection and Safety Monitoring System Architecture Technical Report, February 2007</u>
	WCAP-16438-P WCAP-16438-NP	FMEA of AP1000 Protection and Safety Monitoring System, Revision 1, June 2006
	WCAP-16592-P WCAP-16592-NP	Software Hazards Analysis of AP1000 Protection and Safety Monitoring System, Revision 0, June 2006

(P) Denotes Document is Proprietary

*NRC Staff approval is required prior to implementing a change in this information; see DCD Introduction Section 3.5.

NRC 153

	WCAP-15776	Safety Criteria for the AP1000 Instrumentation and Control Systems, April 2002
	<u>WCAP-16097-P-A</u> <u>WCAP-16097-NP-A</u>	<u>Common Qualified Platform, Digital Plant Protection System, Appendix 3, May 2003</u>
7.3	WCAP-15776	Safety Criteria for the AP1000 Instrumentation and Control Systems, April 2002

*NRC Staff approval is required prior to implementing a change in this information; see DCD Introduction Section 3.5.

1.7 Drawings and Other Detailed Information**1.7.1 Electrical and Instrumentation and Control Drawings**

Instrument and control functional diagrams, electrical one-line diagrams, and onsite standby diesel generator loading sequence and initiating circuit logic diagrams are listed in Table 1.7-1.

The legend for electrical power, control, lighting, and communication drawings are provided in Figure 1.7-1, sheets 1, 2, and 3. The index, notes, and symbols for instrument and control functional diagrams are provided in Figure 7.24-1.

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1.7.2 Piping and Instrumentation Diagrams

Table 1.7-2 contains a list of piping and instrumentation diagrams (P&IDs) and the corresponding DCD figure numbers. The three letter system names are provided in Table 1.7-2. Figures appear at the end of the respective text section. The P&ID legend, Figure 1.7-2, sheets 1, 2, and 3, provides an explanation of AP1000 symbols and characters used in these DCD figures.

1.7.3 Combined License Information

This section has no requirement for additional information to be provided in support of the combined license application.

Table 1.8-2 (Sheet 4 of 13)

**SUMMARY OF AP1000 STANDARD PLANT
COMBINED LICENSE INFORMATION ITEMS**

Item No.	Subject	Subsection	Addressed by Westinghouse Document	Action Required by COL Applicant	Action Required by COL Holder
3.8-2	Deleted Passive Containment Cooling System Water Storage Tank Examination	Deleted	APP-GW-GLR-021	N/A	N/A
3.8-3	Deleted As-Built Summary Report	Deleted	APP-GW-GLR-021	N/A	N/A
3.8-4	Deleted In-Service Inspection of Containment Vessel	Deleted	APP-GW-GLR-021	N/A	N/A
3.9-1	Reactor Internal Vibration Response	3.9.8.1	WCAP-16687-P	No	No
3.9-2	Design Specification and Reports	3.9.8.2	APP-GW-GLR-021	No	Yes
3.9-3	Snubber Operability Testing	3.9.8.3	N/A	Yes	–
3.9-4	Valve Inservice Testing	3.9.8.4	APP-GW-GLN-020	Yes	–
3.9-5	Surge Line Thermal Monitoring	3.9.8.5	N/A	Yes	–
3.9-6	Piping Benchmark Program	3.9.8.6	APP-GW-GLR-006	No	No
3.10-1	Experience-Based Qualification	3.10.6	APP-GW-GLN-006 APP-GW-GLR-031	No	No
3.11-1	Equipment Qualification File	3.11.5	APP-GW-GLN-110	No	Yes
4.2-1	Changes to Reference Reactor Design	4.2.5	APP-GW-GLR-059	No	No
4.3-1	Changes to Reference Reactor Design	4.3.4	APP-GW-GLR-059 APP-GW-GLR-119	No	No
4.4-1	Changes to Reference Reactor Design	4.4.7	N/A APP-GW-GLR-059 WCAP-16652-NP, Rev. 0	No Yes	No –

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Table 1.8-2 (Sheet 5 of 13)

**SUMMARY OF AP1000 STANDARD PLANT
COMBINED LICENSE INFORMATION ITEMS**

Item No.	Subject	Subsection	Addressed by Westinghouse Document	Action Required by COL Applicant	Action Required by COL Holder
4.4-2	Confirm Assumptions for Safety Analyses DNBR Limits	4.4.7	N/A APP-GW-GLR-059 WCAP-16652-NP, Rev. 0	Yes No	– Yes
5.2-1	ASME Code and Addenda	5.2.6.1	N/A	Yes	–
5.2-2	Plant Specific Inspection Program	5.2.6.2	N/A	Yes	–
5.3-1	Reactor Vessel Pressure – Temperature Limit Curves	5.3.6.1	APP-GW-GLR-021	No	Yes
5.3-2	Reactor Vessel Materials Surveillance Program	5.3.6.2	N/A	Yes	–
5.3-3	Surveillance Capsule Lead Factor and Azimuthal Location Confirmation	5.3.6.3	APP-GW-GLR-023	No	No
5.3-4	Reactor Vessel Materials Properties Verification	5.3.6.4.1	N/A APP-GW-GLR-023	No	Yes
5.3-5	Reactor Vessel Insulation	5.3.6.5	APP-GW-GLR-060	No	No
5.3-6	Analysis of Reactor Vessel Insulation and Support Structure	5.3.6.4.2	APP-GW-GLR-060	No	No
5.4-1	Steam Generator Tube Integrity	5.4.15	N/A	Yes	–
6.1-1	Procedure Review for Austenitic Stainless Steels	6.1.3.1	N/A	Yes	–
6.1-2	Coating Program	6.1.3.2	N/A	Yes	–
6.2-1	Containment Leak Rate Testing	6.2.6	N/A	Yes	–
6.3-1	Containment Cleanliness Program	6.3.8.1	N/A	Yes	–

Table 1.8-2 (Sheet 6 of 13)

**SUMMARY OF AP1000 STANDARD PLANT
COMBINED LICENSE INFORMATION ITEMS**

Item No.	Subject	Subsection	Addressed by Westinghouse Document	Action Required by COL Applicant	Action Required by COL Holder
6.3-2	Verification of Containment Resident Particulate Debris Characteristics	6.3.8.2	APP-GW-GLR-079	No	No Yes
6.4-1	Local Hazardous Gas Services and Monitoring	6.4.7	N/A	Yes	–
6.4-2	Procedures for Training for Control Room Habitability	6.4.7	N/A	Yes	–
6.4-3	Main Control Room Inleakage Test Frequency	6.4.7	APP-GW-GLR-007	No	No
6.6-1	Inspection Programs	6.6.9.1	N/A	Yes	–
6.6-2	Construction Activities	6.6.9.2	N/A	Yes	–
7.1-1	Setpoint Calculations for Protective Functions	7.1.6.1	WCAP-16361-P	No	No
7.1-2	Resolution of Generic Open Items and Plant-Specific Action Items	7.1.6.2	APP-GW-GLR-017	No	No
7.2-1	FMEA for Protection System	7.2.3	WCAP-16438-P WCAP-16592-P	No	No
8.2-1	Offsite Electrical Power	8.2.5	N/A	Yes	–
8.2-2	Technical Interfaces	8.2.5	N/A	Yes	–
8.3-1	Grounding and Lightning Protection	8.3.3	N/A	Yes	–
8.3-2	Onsite Electrical Power Plant Procedures	8.3.3	N/A	Yes	–
9.1-1	New Fuel Rack	9.1.6.1	APP-GW-GLR-026	No	No

Table 1.8-2 (Sheet 8 of 13)

**SUMMARY OF AP1000 STANDARD PLANT
COMBINED LICENSE INFORMATION ITEMS**

Item No.	Subject	Subsection	Addressed by Westinghouse Document	Action Required by COL Applicant	Action Required by COL Holder
9.5-7	Fire Resistance Test Data	9.5.1.8.8	APP-GW-GLR-019	No Yes	No –
9.5-8	Establishment of Procedures to Minimize Risk for Fire Areas Breached During Maintenance	9.5.1.8.7	N/A	Yes	–
9.5-9	Offsite Interfaces	9.5.2.5.1	N/A	Yes	–
9.5-10	Emergency Offsite Communications	9.5.2.5.2	N/A	Yes	–
9.5-11	Security Communications	9.5.2.5.3	N/A	Yes	–
9.5-12	Cathodic Protection	9.5.4.7.1	APP-GW-GLR-120	No	No
9.5-13	Fuel Degradation Protection	9.5.4.7.2	APP-GW-GLR-120	Yes	–
10.1-1	Erosion-Corrosion Monitoring	10.1.3	N/A	No Yes	Yes No
10.2-1	Turbine Maintenance and Inspection	10.2.6	APP-GW-GLN-018	No	Yes
10.4-1	Circulating Water Supply	10.4.12.1	N/A	Yes	–
10.4-2	Condensate, Feedwater and Auxiliary Steam System Chemistry Control	10.4.12.2	N/A	Yes	–
10.4-3	Potable Water	10.4.12.3	N/A	Yes	–
11.2-1	Liquid Radwaste Processing by Mobile Equipment	11.2.5.1	N/A	Yes	–
11.2-2	Cost Benefit Analysis of Population Doses	11.2.5.2	N/A	Yes	–
11.2-3	Identification of Ion Exchange and Adsorbent Media	11.2.5.3	APP-GW-GLR-008	No	No

Table 1.8-2 (Sheet 9 of 13)

**SUMMARY OF AP1000 STANDARD PLANT
COMBINED LICENSE INFORMATION ITEMS**

Item No.	Subject	Subsection	Addressed by Westinghouse Document	Action Required by COL Applicant	Action Required by COL Holder
11.2-4	Dilution and Control of Boric Acid Discharge	11.2.5.4	APP-GW-GLR-014	No	No
11.3-1	Cost Benefit Analysis of Population Doses	11.3.5.1	N/A	Yes	–
11.3-2	Identification of Adsorbent Media	11.3.5.2	APP-GW-GLR-008	No	No
11.4-1	Solid Waste Management System Process Control Program	11.4.6	N/A	Yes	–
11.5-1	Plant Offsite Dose Calculation Manual (ODCM)	11.5.7	N/A	Yes	–
11.5-2	Effluent Monitoring and Sampling	11.5.7	N/A	Yes	–
11.5-3	10 CFR 50, Appendix I	11.5.7	N/A	Yes	–
12.1-1	ALARA and Operational Policies	12.1.3	N/A	Yes	–
12.2-1	Additional Contained Radiation Sources	12.2.3	N/A	Yes	–
12.3-1	Administrative Controls for Radiological Protection	12.3.5.1	N/A	Yes	<u>–</u> Yes
12.3-2	Criteria and Methods for Radiological Protection	12.3.5.2	N/A	Yes	–
12.3-3	Groundwater Monitoring Program	12.3.5.3	N/A	Yes	–
12.3-4	Record of Operational Events of Interest for Decommissioning	12.3.5.4	N/A	Yes	–

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Table 1.8-2 (Sheet 12 of 13)

**SUMMARY OF AP1000 STANDARD PLANT
COMBINED LICENSE INFORMATION ITEMS**

Item No.	Subject	Subsection	Addressed by Westinghouse Document	Action Required by COL Applicant	Action Required by COL Holder
17.5-5	Maintaining Reliability of Risk-Significant SSCs	17.5.5	APP-GW-GLR-117	No	No
17.5-6	Maintenance Activities Relevant to Maintenance Rule	17.5.6	APP-GW-GLR-117	No	No
17.5-7	Operational Reliability Assurance Activities	17.5.7	APP-GW-GLR-117	No	No
17.5-8	Operational Reliability Assurance Program Integration with Quality Assurance Program	17.5.8	N/A	Yes	–
18.2-1	Execution of the NRC Approved Human Factors Engineering Program	18.2.6.1	<u>APP-GW-GLR-012</u> N/A	<u>No</u> Yes	<u>No</u> –
18.2-2	Design of the Emergency Operations Facility	18.2.6.2	<u>APP-GW-GLR-136</u> N/A	Yes	<u>No</u> –
18.5-1	Task Analysis	18.5.4.1	APP-GW-GLR-081 <u>APP-GW-GLR-090</u>	<u>No</u> Yes	<u>No</u> –
18.5-2	Main Control Room	18.5.4.2	APP-GW-GLR-010 <u>APP-GW-GLR-090</u>	<u>No</u> Yes	<u>No</u> –
18.6-1	Plant Staffing	18.6.1	<u>APP-GW-GLR-090</u> N/A	Yes	–
18.7-1	Execution and Documentation of the Human Reliability Analysis/Human Factors Engineering Integration	18.7.1	APP-GW-GL-011 <u>APP-GW-GLR-090</u>	No	No
18.8-1	Execution and Documentation of the Human System Interface Design Implementation Plan	18.8.5	APP-GW-GLR-082 <u>APP-GW-GLR-090</u>	No	No

Table 1.8-2 (Sheet 13 of 13)

**SUMMARY OF AP1000 STANDARD PLANT
COMBINED LICENSE INFORMATION ITEMS**

Item No.	Subject	Subsection	Addressed by Westinghouse Document	Action Required by COL Applicant	Action Required by COL Holder
18.9-1	Procedure Development	18.9.1	APP-GW-GLR-040 <u>APP-GW-GLR-090</u>	No	No
18.10-1	Training Program Development	18.10.1	<u>APP-GW-GLR-090</u> N/A	Yes	–
18.11-1	Verification and Validation of AP1000 Human Factors Engineering Program	18.11.1	APP-GW-GLR-084 <u>APP-GW-GLR-090</u>	No	No
18.14-1	Human Performance Monitoring	18.14	<u>APP-GW-GLR-090</u> N/A	Yes	–
19.59.10-1	As-Built SSC HCLPF Comparison to Seismic Margin Evaluation	19.59.10.5	APP-GW-GLR-021	No	Yes
19.59.10-2	Evaluation of As-Built Plant Versus Design in AP1000 PRA and Site-Specific PRA External Events	19.59.10.5	APP-GW-GLR-101	Yes	Yes
19.59.10-3	Internal Fire and Internal Flood Analyses	19.59.10.5	APP-GW-GLR-021	No	Yes
19.59.10-4	Develop and Implement Severe Accident Management Guidance	19.59.10.5	APP-GW-GLR-070	Yes	–
19.59.10-5	Equipment Survivability	19.59.10.5	APP-GW-GLR-021	No	Yes
	Bulletins and Generic Letters (WCAP-15800, Revision 3, July 2004)	1.9.5.5	APP-GW-GLR-129	<u>Yes</u> No	No
	Unresolved Safety Issues and Generic Safety Issues	Table 1.9-2	APP-GW-GLR-129	<u>Yes</u> No	No

AP1000 Response:

The AP1000 safety-related passive systems include the following design features:

- The AP1000 does not include any safety-related pumps.
- The motor-operated valve design is simplified by extending opening and closing times and by using simplified, conservative valve designs.
- Safety-related motor-operated valves are designed to be cycled with the plant at power.
- Features are included in the design to provide proper operational testing of the appropriate check valves, motor-operated valves, and air-operated valves, including flow and differential pressure testing during shutdown conditions.

Subsection 3.9.8.4 defines the responsibility for the in-service testing program for ASME Code Class 1, 2, and 3 valves.

Subsection 3.9.6 summarizes the requirements for the in-service testing program, including industry standards and NRC recommendations. ~~A description of the in-service inspection program is included in the technical specifications provided in Chapter 16.~~ The AP1000 system and valve designs generally allow implementation of the NRC recommendations in Generic Letters 89-04 and 89-10. Requirements for nonsafety-related pumps and valves that support the operation of systems that preclude unnecessary operation of the safety-related passive systems are outlined in subsection 3.9.6.

The AP1000 in-service testing program provides for periodic testing of the safety-related passive system components. The safety-related passive system components and systems are designed to meet the intent of the ASME Code, Section XI, for in-service inspection.

The AP1000 is designed for the following basic types of in-service testing of safety-related components:

- Periodic functional testing of active components during power operation (such as cycling of specific valves)
- Periodic flow/differential pressure operability testing of active components
- Periodic leak testing of the containment isolation valves.
- Periodic system flow or heat transfer rate testing of passive safety-related injection or cooling features during plant shutdown

The passive system design includes specific features to support in-service test performance:

- Remotely operated valves can be exercised during plant operation.

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Table 1.9-1 (Sheet 1 of 15)

REGULATORY GUIDE/DCD SECTION CROSS-REFERENCES

Division 1 Regulatory Guide		DCD Chapter, Section or Subsection
1.1	Net Positive Suction Head for Emergency Core Cooling and Containment Heat Removal System Pumps (Rev. 0, November 2, 1970)	This regulatory guide is not applicable to AP1000.
1.2	Withdrawn	
1.3	Assumptions Used for Evaluating the Potential Radiological Consequences of a Loss-of-coolant Accident for Boiling Water Reactors (Rev. 2, June 1974)	This regulatory guide is not applicable to AP1000.
1.4	Assumptions Used for Evaluating the Potential Radiological Consequences of a Loss-of-Coolant Accident for Pressurized Water Reactors (Rev. 2, June 1974)	The guidance of Reg. Guide 1.183, "Alternative Radiological Source Terms For Evaluating Design Basis Accidents At Nuclear Power Reactors" will be followed instead of Reg. Guide 1.4.
1.5	Assumptions Used for Evaluating the Potential Radiological Consequences of a Steam Line Break Accident for Boiling Water Reactors (Rev. 0, March 10, 1971)	This regulatory guide is not applicable to AP1000.
1.6	Independence Between Redundant Standby (Onsite) Power Sources and Between Their Distribution Systems (Rev. 0, March 10, 1971)	8.1 8.3.1 8.3.2 <u>16.1 Bases</u>
1.7	Control of Combustible Gas Concentration in Containment Following a Loss-of-Coolant Accident (Rev. 2, November 1978)	6.1.1 6.2.4 15.6.3 Appendix 15A
1.8	Qualification and Training of Personnel for Nuclear Power Plants (Rev. 3, 1 May 2000)	This regulatory guide is not applicable to AP1000 design certification.
1.9	Selection, Design, and Qualification of Diesel Generator Units Used as Onsite Electric Power Systems at Nuclear Power Plants (Proposed Rev. 3, November 1988)	This regulatory guide is not applicable to AP1000.
1.10	Withdrawn	
1.11	Instrument Lines Penetrating Primary Reactor Containment (Rev. 0, March 10, 1971)	3.6.2 6.2.3
1.12	Instrumentation for Earthquakes (Rev. 2, March 1997)	3.7.4

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Table 1.9-1 (Sheet 2 of 15)

REGULATORY GUIDE/DCD SECTION CROSS-REFERENCES

Division 1 Regulatory Guide		DCD Chapter, Section or Subsection
1.13	Spent Fuel Storage Facility Design Basis (Proposed Rev. 2, December 1981)	9.1.2 9.1.3 9.1.4 <u>16.1 Bases</u>
1.14	Reactor Coolant Pump Flywheel Integrity (Rev. 1, August 1975)	5.4.1
1.15	Withdrawn	
1.16	Reporting of Operating Information - Appendix A Technical Specifications (Rev. 4, August 1975).	This regulatory guide is not applicable to AP1000 design certification.
1.17	Withdrawn	
1.18	Withdrawn	
1.19	Withdrawn	
1.20	Comprehensive Vibration Assessment Program for Reactor Internals During Preoperational and Initial Startup Testing (Rev.2, May 1976)	3.9.2 14
1.21	Measuring, Evaluating, and Reporting Radioactivity in Solid Wastes and Releases of Radioactive Materials in Liquid and Gaseous Effluents From Light-Water-Cooled Nuclear Power Plants (Rev. 1, June 1974)	11.5
1.22	Periodic Testing of Protection System Actuation Functions (Rev. 0, February 17, 1972)	7.1 7.2 7.4
1.23	Onsite Meteorological Program (Second Proposed Rev. 1, April 1986)	2.3
1.24	Assumptions Used for Evaluating the Potential Radiological Consequences of a Pressurized Water Reactor Radioactive Gas Storage Tank Failure (Rev. 0, March 23, 1972)	This regulatory guide is not applicable to AP1000.
1.25	Assumptions Used for Evaluating the Potential Radiological Consequences of a Fuel Handling Accident in the Fuel Handling and Storage Facility for Boiling and Pressurized Water Reactors (Rev. 0, March 23, 1972)	The guidance of Reg. Guide 1.183, "Alternative Radiological Source Terms For Evaluating Design Basis Accidents At Nuclear Power Reactors" will be followed instead of Reg. Guide 1.25.
1.26	Quality Group Classifications and Standards for Water-, Steam-, and Radioactive-Waste-Containing Components of Nuclear Power Plants (Rev. 3, February 1976)	3.2.2
1.27	Ultimate Heat Sink for Nuclear Power Plants (Rev. 2, January 1976)	6.2.2

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Table 1.9-1 (Sheet 3 of 15)

REGULATORY GUIDE/DCD SECTION CROSS-REFERENCES

Division 1 Regulatory Guide		DCD Chapter, Section or Subsection
1.28	Quality Assurance Program Requirements (Design and Construction) (Rev. 3, August 1985)	2.5 17
1.29	Seismic Design Classification (Rev. 3, September 1978)	3.2.1
1.30	Quality Assurance Requirements for the Installation, Inspection, and Testing of Instrumentation and Electric Equipment (Rev. 0, August 11, 1972)	This regulatory guide is not applicable to AP1000 design certification.
1.31	Control of Ferrite Content in Stainless Steel Weld Metal (Rev. 3, April 1978)	4.5.1 4.5.2 5.2.3 5.3.2 6.1.1
1.32	Criteria for Safety-Related Electric Power Systems for Nuclear Power Plants (Rev. 2, February 1977)	8.1 8.2 8.3.1 8.3.2 <u>16.1 Bases</u>
1.33	Quality Assurance Program Requirements (Operation) (Second Proposed Rev. 3, November 1980)	3.11.2.1 3D.4.1.2 3D.6.4
1.34	Control of Electroslag Weld Properties (Rev. 0, December 28, 1972)	4.5.2 5.2.3 5.3.2
1.35	Inservice Inspection of UngROUTED Tendons in Pre-stressed Concrete Containments (Rev. 3, July 1990)	This regulatory guide is not applicable to AP1000.
1.35.1	Determining Prestressing Forces for Inspection of Prestressed Concrete Containments (Rev. 0, July 1990)	This regulatory guide is not applicable to AP1000.
1.36	Nonmetallic Thermal Insulation for Austenitic Stainless Steel (Rev. 0, February 23, 1973)	5.2.3 6.1.1
1.37	Quality Assurance Requirements for cleaning of Fluid Systems and Associated Components of Water-Cooled Nuclear Power Plants (Rev. 0, March 1973)	17
1.38	Quality Assurance Requirements for Packaging, Shipping, Receiving, Storage, and Handling of Items for Water-Cooled Nuclear Power Plants (Rev. 2, May 1977)	17
1.39	Housekeeping Requirements for Water-Cooled Nuclear Power Plants (Rev. 2, September 1977)	17

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Table 1.9-1 (Sheet 4 of 15)

REGULATORY GUIDE/DCD SECTION CROSS-REFERENCES

Division 1 Regulatory Guide		DCD Chapter, Section or Subsection
1.40	Qualification Tests of Continuous-Duty Motors Installed Inside the Containment of Water-Cooled Nuclear Power Plants (Rev. 0, March 16, 1973)	This regulatory guide is not applicable to AP1000.
1.41	Preoperational Testing of Redundant Onsite Electric Power Systems to Verify Proper Load Group Assignments (Rev. 0, March 16, 1973)	14
1.42	Withdrawn	
1.43	Control of Stainless Steel Weld Cladding of Low-Alloy Steel Components (Rev. 0, May 1973)	5.2.3 5.3.2
1.44	Control of the Use of Sensitized Stainless Steel (Rev. 0, May 1973)	4.5.1 4.5.2 5.2.3 5.3.2 6.1.1 10.3
1.45	Reactor Coolant Pressure Boundary Leakage Detection Systems (Rev. 0, May 1973)	5.2.5 <u>16.1 Bases</u>
1.46	Withdrawn	
1.47	Bypassed and Inoperable Status Indication for Nuclear Power Plant Safety Systems (Rev. 0, May 1973)	6.3 7.2 7.3 7.4 7.5 8.3.2
1.48	Withdrawn	
1.49	Power Levels of Nuclear Power Plants (Rev. 1, December 1973)	16
1.50	Control of Preheat Temperature for Welding of Low-Alloy Steel (Rev. 0, May 1973)	5.2.3 5.3.2 6.1.1
1.51	Withdrawn	
1.52	Design, Testing, and Maintenance Criteria for Post Accident Engineered-Safety-Feature Atmosphere Cleanup System Air Filtration and Adsorption Units of Light-Water-Cooled Nuclear Power Plants (Rev. 2, March 1978)	6.5.4 <u>This regulatory guide is not applicable to AP1000.</u>

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Table 1.9-1 (Sheet 6 of 15)

REGULATORY GUIDE/DCD SECTION CROSS-REFERENCES

Division 1 Regulatory Guide		DCD Chapter, Section or Subsection
1.68	Initial Test Programs for Water-Cooled Nuclear Power Plants (Rev. 2, August 1978)	14 <u>16.1 Bases</u>
1.68.1	Preoperational and Initial Startup Testing of Feedwater and Condensate Systems for Boiling Water Reactor Power Plants (Rev. 1, January 1977)	This regulatory guide is not applicable to AP1000.
1.68.2	Initial Test Program to Demonstrate Remote Shutdown Capability for Water-Cooled Nuclear Power Plants (Rev. 1, July 1978)	14
1.68.3	Preoperational Testing of Instrument and Air Control Systems (Task RS 709-4) (Rev. 0, April 1982)	9.3.1 14
1.69	Concrete Radiation Shields for Nuclear Power Plants (Rev. 0, December 1973)	3.8.4 12.3
1.70	Standard Format and Content of Safety Analysis Reports for Nuclear Power Plants (Rev. 3, November 1978)	1.1
1.71	Welder Qualification for Areas of Limited Accessibility (Rev. 0, December 1973)	5.2.3.4.6
1.72	Spray Pond Piping Made From Fiberglass-Reinforced Thermosetting Resin (Rev. 2, November 1978)	This regulatory guide is not applicable to AP1000.
1.73	Qualification Tests of Electric Valve Operators Installed Inside the Containment of Nuclear Power Plants (Rev.0, January 1974)	3.11
1.74	Withdrawn	
1.75	Physical Independence of Electric Systems (Rev. 2, September 1978)	7.1 7.2 7.3 7.4 7.5 8.1 8.3.1 8.3.2 9.5.1
1.76	Design Basis Tornado for Nuclear Power Plants (Rev. 0, April 1974)	2.3 3.3

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Table 1.9-1 (Sheet 7 of 15)

REGULATORY GUIDE/DCD SECTION CROSS-REFERENCES

Division 1 Regulatory Guide		DCD Chapter, Section or Subsection
1.77	Assumptions Used for Evaluating a Control Rod Ejection Accident for Pressurized Water Reactors (Rev. 0, May 1974)	The guidance of Reg. Guide 1.183, "Alternative Radiological Source Terms For Evaluating Design Basis Accidents At Nuclear Power Reactors" will be followed instead of Reg. Guide 1.77. <u>16.1 Bases</u>
1.78	Evaluating the Habitability of a Nuclear Power Plant Control Room During a Postulated Hazardous Chemical Release (Rev. 1, December 2001)	2.2 6.4 9.4.1 9.5.1 <u>16.1 Bases</u>
1.79	Preoperational Testing of Emergency Core Cooling Systems for Pressurized Water Reactors (Rev. 1, September 1975)	14
1.80	Withdrawn	
1.81	Shared Emergency and Shutdown Electric Systems for Multi-Unit Nuclear Power Plant (Rev. 1, January 1975)	This regulatory guide is not applicable to AP1000.
1.82	Water Sources for Long Term Recirculation Cooling Following a Loss-of-Coolant Accident (Task 203-4) (Rev. 2, May, 1996)	6.3
1.83	Inservice Inspection of Pressurized Water Reactor Steam Generator Tubes (Rev. 1, July 1975)	5.4.2
1.84	Design and Fabrication Code Case Acceptability ASME Section III Division 1 (Rev. 32, June 2003)	4.5.1 4.5.2 5.2.1 5.2.3 10.3
1.85	Withdrawn	
1.86	Termination of Operating Licenses for Nuclear Reactors (Rev. 0, June 1974)	This regulatory guide is not applicable to AP1000 design certification.
1.87	Guidance for Construction of Class 1 Components in Elevated-Temperature Reactors (Rev. 1, June 1975)	This regulatory guide is not applicable to AP1000.
1.88	Withdrawn	

Table 1.9-1 (Sheet 8 of 15)

REGULATORY GUIDE/DCD SECTION CROSS-REFERENCES

Division 1 Regulatory Guide		DCD Chapter, Section or Subsection
1.89	Environmental Qualification of Certain Electric Equipment Important to Safety for Nuclear Power Plants (Task EE 042-2) (Rev. 1, June 1984)	3.11
1.90	Inservice Inspection of Prestressed Concrete Containment Structures With Grouted Tendons (Rev. 1, August 1977)	This regulatory guide is not applicable to AP1000.
1.91	Evaluations of Explosions Postulated to Occur on Transportation Routes Near Nuclear Power Plant Sites (Rev. 1, February 1978)	19.58
1.92	Combining Modal Responses and Spatial Components in Seismic Response Analysis (Rev. 1, February 1976)	3.7
1.93	Availability of Electric Power Sources (Rev. 0, December 1974)	8.1 8.3 <u>16.1 Bases</u>
1.94	Quality Assurance Requirements for Installation, Inspection, and Testing of Structural Concrete and Structural Steel During the Construction Phase of Nuclear Power Plants (Rev. 1, April 1976)	This regulatory guide is not applicable to AP1000 design certification.
1.95	Withdrawn	
1.96	Design of Main Steam Isolation Valve Leakage Control Systems for Boiling Water Reactor Nuclear Power Plants (Rev. 1, June 1976)	This regulatory guide is not applicable to AP1000.
1.97	Instrumentation for Light-Water-Cooled Nuclear Power Plants to Assess Plant and Environs Conditions During and Following an Accident (Rev. 3, May 1983)	7.5 18.8 <u>16.1 Bases</u>
1.98	Assumptions Used for Evaluating the Potential Radiological Consequences of a Radioactive Offgas System Failure in a Boiling Water Reactor (Rev. 0, March 1976)	This regulatory guide is not applicable to AP1000.
1.99	Radiation Embrittlement of Reactor Vessel Materials (Task ME 305-4) (Rev. 2, May 1988)	5.3.2 5.3.3 <u>16.1 Bases</u>
1.100	Seismic Qualification of Electric and Mechanical Equipment for Nuclear Power Plants (Task EE 108-5) (Rev. 2, June 1988)	3.10
1.101	Emergency Planning and Preparedness for Nuclear Power Reactors (Rev. 3, August 1992)	This regulatory guide is not applicable to AP1000 design certification.
1.102	Flood Protection for Nuclear Power Plants (Rev. 1, September 1976)	3.4

Table 1.9-1 (Sheet 9 of 15)

REGULATORY GUIDE/DCD SECTION CROSS-REFERENCES

Division 1 Regulatory Guide		DCD Chapter, Section or Subsection
1.103	Withdrawn	
1.104	Withdrawn	
1.105	Instrument Setpoints for Safety-Related Systems (Task 1C 010-5) (Rev. 3, December 1999)	7.1 16
1.106	Thermal Overload Protection for Electric Motors on Motor-Operated Valves (Rev. 1, March 1977)	8.1
1.107	Qualifications for Cement Grouting Tendons for Prestressing Tendons in Containment Structures (Rev. 1, February 1977)	This regulatory guide is not applicable to AP1000.
1.108	Withdrawn	
1.109	Calculation of Annual Doses to Man From Routine Releases of Reactor Effluents for the Purpose of Evaluating Compliance With 10 CFR Part 50 Appendix I (Rev. 1, October 1977)	11.3.3
1.110	Cost-Benefit Analysis for Radwaste Systems for Light-Water-Cooled Nuclear Power Reactors (Rev. 0, March 1976)	11.2 11.3
1.111	Methods for Estimating Atmospheric Transport and Dispersion of Gaseous Effluents in Routine Releases From Light-Water-Cooled Reactors (Rev. 1, July 1977)	2.3
1.112	Calculation of Releases of Radioactive Materials in Gaseous and Liquid Effluents From Light-Water-Cooled Power Reactors (Rev. 0-R, May 1977)	11.2.3 11.3.3
1.113	Estimating Aquatic Dispersion of Effluents From Accidental and Routine Reactor Releases for the Purpose of Implementing Appendix I (Rev. 1, April 1977)	This regulatory guide is not applicable to AP1000 design certification.
1.114	Guidance to Operators at the Controls and to Senior Operators in the Control Room of a Nuclear Power Unit (Rev. 2, May 1989)	This regulatory guide is not applicable to AP1000 design certification.
1.115	Protection Against Low-Trajectory Turbine Missiles (Rev 1, July 1977)	3.5 3.8.4
1.116	Quality Assurance Requirements for Installation, Inspection, and Testing of Mechanical Equipment and Systems (Rev. 0-R, May 1977)	This regulatory guide is not applicable to AP1000 design certification.
1.117	Tornado Design Classification (Rev. 1, April 1978)	3.5 9.1.2

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Table 1.9-1 (Sheet 10 of 15)

REGULATORY GUIDE/DCD SECTION CROSS-REFERENCES

Division 1 Regulatory Guide		DCD Chapter, Section or Subsection
1.118	Periodic Testing of Electric Power and Protection Systems (Rev. 3, April 1995)	7.1 8.1 8.3
1.119	Withdrawn	
1.120	Fire Protection Guidelines for Nuclear Power Plants (Rev. 1, November 1977)	9.5.1
NRC 141 1.121	Bases for Plugging Degraded PWR Steam Generator Tubes (Rev. 0, August 1976)	5.4.2 <u>16.1 Bases</u>
1.122	Development of Floor Design Response Spectra for Seismic Design of Floor-Supported Equipment or Components (Rev. 1, February 1978)	3.7
1.123	Withdrawn	
NRC 172 1.124	Service Limits and Loading Combinations for Class 1 Linear-Type Component Supports (Rev. 1, January 1978)	3.9.3, 9.1.2.1, <u>9.1.1.1</u>
1.125	Physical Models for Design and Operation of Hydraulic Structures and Systems for Nuclear Power Plants (Rev. 1, October 1978)	2.4
1.126	An Acceptable Model and Related Statistical Methods for the Analysis of Fuel Densification (Rev. 1, March 1978)	4.2
1.127	Inspection of Water-Control Structures Associated With Nuclear Power Plants (Rev. 1, March 1978)	This regulatory guide is not applicable to AP1000.
1.128	Installation Design and Installation of Large Lead Storage Batteries for Nuclear Power Plants (Rev. 1, October 1978)	8.3.2
NRC 141 1.129	Maintenance, Testing, and Replacement of Large Lead Storage Batteries for Nuclear Power Plants (Rev. 1, February 1978)	<u>16.1 Bases</u> This regulatory guide is not applicable to AP1000 design certification.
1.130	Service Limits and Loading Combinations for Class 1 Plate-and-Shell-Type Component Supports (Rev. 1, October 1978)	3.9.3
1.131	Qualification Tests of Electric Cables, Field Splices and Connections for Light-Water-Cooled Nuclear Power Plants (Rev. 0, August 1977)	3.11
1.132	Site Investigations for Foundations of Nuclear Power Plants (Rev. 1, March 1979)	This regulatory guide is not applicable to AP1000 design certification.
1.133	Loose-Part Detection Program for the Primary System of Light-Water-Cooled Reactors (Rev. 1, May 1981)	4.4.6.4

Table 1.9-1 (Sheet 11 of 15)

REGULATORY GUIDE/DCD SECTION CROSS-REFERENCES

Division 1 Regulatory Guide		DCD Chapter, Section or Subsection
1.134	Medical Evaluation of Nuclear Power Plant Personnel Requiring Operator Licenses (Rev. 3, March 1998)	This regulatory guide is not applicable to AP1000 design certification.
1.135	Normal Water Level and Discharge at Nuclear Power Plants (Rev. 0, September 1977)	2.4
1.136	Material for Concrete Containments (Rev. 2, June 1981)	This regulatory guide is not applicable to AP1000.
1.137	Fuel-Oil Systems for Standby Diesel Generators (Rev. 1, October 1979)	9.5.4
1.138	Laboratory Investigation of Soils for Engineering Analysis and Design of Nuclear Power Plants (Rev. 0, April 1978)	This regulatory guide is not applicable to AP1000 design certification.
1.139	Guidance for Residual Heat Removal (Rev. 0, May 1978)	6.3 7.4
1.140	Design, Inspection, and Testing Criteria for Air Filtration and Adsorption Units of Normal Atmosphere Cleanup Systems in Light-Water-Cooled Nuclear Power Plants (Rev. 2, June 2001)	9.4.1 9.4.4 9.4.5 9.4.7 9.4.9 <u>16.1 Bases</u>
1.141	Containment Isolation Provisions for Fluid Systems (Rev. 0, April 1978)	6.2.4
1.142	Safety-Related Concrete Structures for Nuclear Power Plants (Other Than Reactor Vessels and Containments) (Rev. 1, October 1981)	3.8.3 3.8.4 3.8.5
1.143	Design Guidance for Radioactive Waste Management Systems, Structures, and Components Installed in Light-Water-Cooled Nuclear Power Plants (Rev. 1, October 1979)	3.8.4 10.4.8 11.2 11.3 11.4 11.5
1.144	Withdrawn	
1.145	Atmospheric Dispersion Models for Potential Accident Consequence Assessments at Nuclear Power Plants (Rev. 1, November 1982)	This regulatory guide is not applicable to AP1000 design certification.
1.146	Withdrawn	

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REGULATORY GUIDE/DCD SECTION CROSS-REFERENCES

Division 1 Regulatory Guide		DCD Chapter, Section or Subsection
1.159	Assuring the Availability of Funds for Decommissioning Nuclear Reactors (Rev. 0, August 1990)	This regulatory guide is not applicable to AP1000 design certification.
1.160	Monitoring the Effectiveness of Maintenance at Nuclear Power Plants (Rev. 2, March 1997)	This regulatory guide is not applicable to AP1000 design certification.
1.161	Evaluation of Reactor Pressure Vessels with Charpy Upper-Shelf Energy Less Than 50 Ft-Lb (Rev. 0, June 1995)	This regulatory guide is not applicable to AP1000 design certification.
1.162	Format and Content of Report for Thermal Annealing of Reactor Pressure Vessels (Rev. 0, February 1996)	This regulatory guide is not applicable to AP1000 design certification.
1.163	Performance Based Containment Leak-Test Program (Rev. 0, September 1995)	6.2 <u>16.1 Bases</u>
1.165	Identification and Characterization of Seismic Sources and Determination Safe Shutdown Earthquake Ground Motion (Rev. 0, March 1997)	
1.166	Pre-Earthquake Planning and Immediate Nuclear Power Plant Operator Postearthquake Actions (Rev. 0, March 1997)	This regulatory guide is not applicable to AP1000 design certification.
1.167	Restart of a Nuclear Power Plant Shut Down by a Seismic Event (Rev. 0, March 1997)	This regulatory guide is not applicable to AP1000 design certification.
1.168	Verification, Validation, Reviews, and Audits for Digital Computer Software Used in Safety Systems of Nuclear Power Plants (Rev. 04, September 1997 February 2004)	7
1.169	Configuration Management Plans for Digital Computer Software Used in Safety Systems of Nuclear Power Plants (Rev. 0, September 1997)	7
1.170	Software Test Documentation for Digital Computer Software Used in Safety Systems of Nuclear Power Plants (Rev. 0, September 1997)	7
1.171	Software Unit Testing for Digital Computer Software Used in Safety Systems of Nuclear Power Plants (Rev. 0, September 1997)	7

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REGULATORY GUIDE/DCD SECTION CROSS-REFERENCES

Division 1 Regulatory Guide		DCD Chapter, Section or Subsection
1.172	Software Requirements Specifications for Digital Computer Software Used in Safety Systems of Nuclear Power Plants (Rev. 0, September 1997)	7
1.173	Developing Software Life Cycle Processes for Digital Computer Software Used in Safety Systems of Nuclear Power Plants (Rev. 0, September 1997)	7
1.174	An Approach for using Probabilistic Risk Assessment in Risk-Informed Decisions On Plant-Specific Changes to the Licensing Basis (Rev. 0, July 1998)	This regulatory guide is not applicable to AP1000 design certification.
1.175	An Approach for Plant-Specific, Risk-Informed Decisionmaking: Inservice Testing (Rev. 0, July 1998)	This regulatory guide is not applicable to AP1000 design certification.
1.176	An Approach for Plant-Specific, Risk-Informed Decisionmaking: Graded Quality Assurance (Rev. 0, August 1998)	This regulatory guide is not applicable to AP1000 design certification.
NRC 141 1.177	An Approach for Plant-Specific, Risk-Informed Decisionmaking: Technical Specifications (Rev. 0, August 1998)	16.1 Bases This regulatory guide is not applicable to AP1000 design certification.
1.178	An Approach for Plant-Specific, Risk-Informed Decisionmaking: Inservice Inspection of Piping (Rev. 0, September 1998)	This regulatory guide is not applicable to AP1000 design certification.
1.179	Standard Format and Content of License Termination Plans for Nuclear Power Reactors (Rev. 0, January 1999)	This regulatory guide is not applicable to AP1000 design certification.
NRC 141 1.180	Guidelines for Evaluating Electromagnetic and Radio-Frequency Interference in Safety-Related Instrumentation and Control Systems (Rev. 04, January 2000 October 2003)	Appendix 3D
1.181	Content of the Updated Final Safety Analysis Report in Accordance with 10 CFR 50.71(e) (Rev. 0, September 1999)	This regulatory guide is not applicable to AP1000 design certification.
NRC 141 1.182	Assessing and Managing Risk Before Maintenance Activities at Nuclear Power Plants (Rev. 0, May 2000)	16.1 Bases This regulatory guide is not applicable to AP1000 design certification.

Table 1.9-1 (Sheet 15 of 15)

REGULATORY GUIDE/DCD SECTION CROSS-REFERENCES

Division 1 Regulatory Guide		DCD Chapter, Section or Subsection
1.183	Alternative Radiological Source Terms For Evaluating Design Basis Accidents At Nuclear Power Reactors (Rev. 0, July 2000)	2.3 4.2 6.5.1 15.4 15.6.3 15.7 <u>16.1 Bases</u>
1.184	Decommissioning of Nuclear Power Reactors (Rev. 0, August 2000)	This regulatory guide is not applicable to AP1000 design certification.
1.185	Standard Format and Content for Post-shutdown Decommissioning Activities Report (Rev. 0, August 2000)	This regulatory guide is not applicable to AP1000 design certification.
1.186	Guidance and Examples of Identifying 10 CFR 50.2 Design Bases (Rev. 0, December 2000)	This regulatory guide is not applicable to AP1000 design certification.
1.187	Guidance for Implementation of 10 CFR 50.59, Changes, Tests, and Experiments (Rev. 0, November 2000)	This regulatory guide is not applicable to AP1000 design certification.
1.189	Fire Protection for Operating Nuclear Power Plants (Rev. 0, April 2001)	This regulatory guide is not applicable to AP1000 design certification.
1.190	Calculational and Dosimetry Methods for Determining Pressure Vessel Neutron Fluence (Rev. 0, March 2001)	5.3.2.6.2.2
1.197	<u>Demonstrating Control Room Envelope Integrity at Nuclear Power Reactors (Rev. 0, May 2003)</u>	<u>9.4.1</u>

1. Introduction and General Description of Plant

AP1000 Design Control Document

Criteria Section	Referenced Criteria	AP1000 Position	Clarification/Summary Description of Exceptions
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NRC 140	C.4	Conforms	Technical Specifications exist for the passive containment cooling system and air inlet and air baffle.
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Reg. Guide 1.28, Rev. 3, 8/85 – Quality Assurance Program Requirements (Design and Construction)

General	ANSI/ASME N45.2-1977 ANSI/ASME NQA-1-1983 through NQA-1a-1983 Addenda	Conforms	The Westinghouse quality assurance program is described in Chapter 17. Refer to "Westinghouse Electric Company Quality Management System" (QMS) referenced therein for Westinghouse positions on regulatory guides within the scope of the quality assurance program. In some cases current industry consensus standards have replaced the standards specifically referenced by certain regulatory guides. In particular, the N45.2 series standards have been replaced by ASME NQA-1. Therefore, the "Quality Management System" may reference ASME NQA-1 and NQA-2 rather than the N45.2 series standards when describing the Westinghouse position. QMS complies with ASME NQA-1-1994.
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NRC 105

2.	Criteria 17 10 CFR 50 Appendix B	Conforms
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Reg. Guide 1.29, Rev. 3, 9/78 – Seismic Design Classification

C.1.a	Conforms	
C.1.b	Conforms	
C.1.c	Conforms	
C.1.d	Exception	<p>The AP1000 normal residual heat removal system is nonsafety-related. The safety-related function of decay heat removal is provided by the safety-related passive residual heat removal heat exchanger of the passive core cooling system that is seismic Category I. The spent fuel pool cooling system does not have active components that are required for the safety-related decay heat removal function. This function is provided passively through a large heat sink of water in the pool. The spent fuel pool is sized to keep the fuel covered for at least 72 hours without active cooling or makeup following a loss of ac power sources.</p> <p>The 72-hour sizing calculation accounts for the maximum loss of water due to the rupture of non-seismic piping, seismic Category I components within the spent fuel pool cooling system include the</p>

1. Introduction and General Description of Plant

AP1000 Design Control Document

Criteria Section	Referenced Criteria	AP1000 Position	Clarification/Summary Description of Exceptions
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Reg. Guide 1.30, Rev. 0, 8/72 – Quality Assurance Requirements for the Installation, Inspection, and Testing of Instrumentation and Electric Equipment

General	ANSI/ASME N45.2.4-1972	N/A	Not applicable to AP1000 design certification. Section 17.5 defines the responsibility for the Quality Assurance program.
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Reg. Guide 1.31, Rev. 3, 4/78 – Control of Ferrite Content in Stainless Steel Weld Metal

General		Conforms	
C.1-5		Conforms	

Reg. Guide 1.32, Rev. 2, 2/77 – Criteria for Safety-Related Electric Power Systems for Nuclear Power Plants

1.	IEEE Std. 308-1974	Exception	Regulatory Guide 1.32 endorses IEEE Std. 308-1974 (Reference 5), which has been superseded by IEEE Std. 308-1991(Reference 6). The AP1000 uses the latest version of the industry standards (as of 4/2001). This version is not endorsed by a regulatory guide but its use should not result in deviation from the design philosophy otherwise stated in Regulatory Guide 1.32. The guidelines are applicable to the Class 1E dc and UPS system only. There are no safety-related ac power systems in the AP1000.
1.a	Regulatory Guide 1.93	N/A	The AP1000 has no safety-related ac power system. Therefore, the guidelines specified in this criterion section recommending the availability of offsite power "within a few seconds" is not applicable.
1.b	IEEE Std. 308-1974, Section 5.3.4	Exception	See comment on Criterion Section 1.
1.c	IEEE Std. 450-1975	<u>Exception</u> N/A	<u>Battery performance discharge test is per IEEE Std 450-1995 as described in Bases for Technical Specification, Surveillance Requirement 3.8.7.6.</u> Not applicable to AP1000 design certification. Section 13.5 defines the responsibility for development of procedures.
1.d	Regulatory Guide 1.6 Regulatory Guide 1.75	Exception	The guidelines are applicable to the Class 1E dc and UPS system only. There are no safety-related ac power systems in the AP1000.
1.e	Regulatory Guide 1.75	Exception	The guidelines are applicable to the Class 1E dc and UPS system only. There are no safety-related ac power systems in the AP1000.

NRC 140

Criteria Section	Referenced Criteria	AP1000 Position	Clarification/Summary Description of Exceptions
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Reg. Guide 1.44, Rev. 0, 5/73 – Control of the Use of Sensitized Stainless Steel

C.1-62		Conforms	
C.3		Exception	<u>Product forms with simple shapes are not corrosion tested provided they are water quenched following solution anneal. Cast metal and weld metal containing more than five percent delta ferrite also are not corrosion tested as they are not susceptible to sensitization.</u>
C.4		Exception	<u>Welding operations necessarily result in the weld heat affected zone (HAZ) being between the temperature of 800°F to 1500°F.</u>
C.5		Conforms	
C.6		Exception	<u>Extensive testing has been completed and documentation is available such that an intergranular corrosion test is not required for AP1000 welding procedures.</u>

NRC 060

Reg. Guide 1.45, Rev. 0, 5/73 – Reactor Coolant Pressure Boundary Leakage Detection Systems

C.1		Conforms	
C.2		Conforms	
C.3		Exception	The AP1000 reactor coolant pressure boundary leakage detection methods are selected and designed in accordance with the guidelines of this regulatory guide. No credit is taken for airborne particulate radiation measurement in quantifying the leak rate.
C.4		Conforms	
C.5		Conforms	
C.6		Exception	Airborne particulate radioactivity monitoring is not used to determine reactor coolant pressure boundary leakage.
C.7		Conforms	
C.8		Conforms	
C.9		Conforms	

Criteria Section	Referenced Criteria	AP1000 Position	Clarification/Summary Description of Exceptions
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NRC 140

Reg. Guide 1.54, Rev. 1, 7/3/00 – ~~Service Level I, II and III~~ ~~Quality Assurance Requirements for Protective Coatings Applied to Water-Cooled Nuclear Power Plants~~

General	ASTM D 3843-00, ASTM D 3911-95, ASTM D 5144-00	Exception	Some coatings inside containment are nonsafety-related and satisfy appropriate ASTM Standards. See subsection 6.1.2 for additional information. Application is controlled by procedures using qualified personnel to provide a high quality product. The paint materials for coatings inside the containment are subject to 10 CFR Part 50 Appendix B Quality Assurance requirements. The quality assurance features of the AP1000 coatings systems are outlined in DCD subsection 6.1.2.1.6. Subsection 6.1.3 defines the responsibility for the coating program.
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Reg. Guide 1.55 – Withdrawn

Reg. Guide 1.56, Rev. 1, 7/78 – Maintenance of Water Purity in Boiling Water Reactors

General		N/A	Applies to boiling water reactors only.
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Reg. Guide 1.57, Rev. 0, 6/73 – Design Limits and Loading Combinations for Metal Primary Reactor Containment System Components

General	ASME Code, Section III	Exception	The regulatory guide was issued in 1973. It refers to the ASME Code through the Summer 1973 Addenda. The acceptance criteria have been defined in greater detail in SRP 3.8.2. The AP1000 complies with the SRP acceptance criteria with the exception that the operating basis earthquake is excluded.
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Reg. Guide 1.58 – Withdrawn

Reg. Guide 1.59, Rev. 2, 8/77 – Design Basis Floods for Nuclear Power Plants

C.1-4	Regulatory Guide 1.29	N/A	The maximum water level due to the probable maximum flood is established as a site interface in Chapter 2 and is used in the design of the AP1000. Subsection 2.4.1.2 defines the responsibility for addressing site-specific information on historical flooding and potential flooding factors.
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Reg. Guide 1.60, Rev. 1, 12/73 – Design Response Spectra for Seismic Design of Nuclear Power Plants

C.1		Conforms	
C.2		Conforms	

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Criteria Section	Referenced Criteria	AP1000 Position	Clarification/Summary Description of Exceptions
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Reg. Guide 1.186, Rev. 0, 12/00 – Guidance and Examples of Identifying 10 CFR 50.2 Design Bases

General		N/A	Not applicable to AP1000 design certification. Subsection 1.9.1.5 defines the responsibility for Regulatory Guides not applicable to Design Certification.
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Reg. Guide 1.187, Rev. 0, 11/00 – Guidance for Implementation of 10 CFR 50.59, Changes, Tests, and Experiments

General		N/A	Not applicable to AP1000 design certification. Subsection 1.9.1.5 defines the responsibility for Regulatory Guides not applicable to Design Certification.
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Reg. Guide 1.189, Rev. 0, 4/01 – Fire Protection for Operating Nuclear Power Plants

General		N/A	Subsection 9.5.1 describes the AP1000 Fire Protection System. Subsection 9.5.1.8 defines the responsibility for completing a fire protection program.
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Reg. Guide 1.190, Rev. 0, 4/01 – Calculational and Dosimetry Methods for Determining Pressure Vessel Neutron Fluence

General		N/A	Subsection 5.3.2.6 describes the calculational and dosimetry methods for determining pressure vessel neutron fluence for the AP1000 subsection 5.3.6.4 defines the responsibility for reactor vessel materials properties verification.
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Reg. Guide 1.197, Rev. 0, 5/03 – Demonstrating Control Room Envelope Integrity at Nuclear Power Reactors

General		Conforms	The design of the AP1000 control room and associated HVAC systems facilitates testing to demonstrate control room envelope integrity
C.1.1-2.6		N/A	Not applicable to AP1000 design certification. Section 13.5 defines the responsibility for procedures. Section 14.4 describes the responsibilities required to perform the AP1000 plant initial test program

NRC 140

Criteria Section	Referenced Criteria	AP1000 Position	Clarification/Summary Description of Exceptions
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4.b-d		N/A	Not applicable to AP1000 design certification. Subsection 12.1.3 defines the responsibility for operational considerations of ALARA,
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NRC 140 | 4.e3

Conforms

Reg. Guide 8.10, Rev. 1-R, 5/77 – Operating Philosophy For Maintaining Occupational Radiation Exposures as Low as is Reasonably Achievable

General		N/A	Not applicable to AP1000 design certification. Subsection 12.1.3 defines the responsibility for operational considerations of ALARA,
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Reg. Guide 8.12 – Withdrawn

Reg. Guide 8.13, Rev. 3, 6/99 – Instruction Concerning Prenatal Radiation Exposure

General	10 CFR 19.12	N/A	Not applicable to AP1000 design certification. Subsection 12.1.3 defines the responsibility for operational considerations of ALARA, Section 13.5 defines the responsibility for administrative procedures.
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Reg. Guide 8.14 – Withdrawn

Reg. Guide 8.15, Rev. 1, 10/99 – Acceptable Programs for Respiratory Protection

General	10 CFR 20.103	N/A	Not applicable to AP1000 design certification. Subsection 12.1.3 defines the responsibility for operational considerations of ALARA, See Section 12.3 for information on radiation protection design features. See Section 12.5 for information on health physics facilities. Section 13.5 defines the responsibility for administrative procedures.
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Reg. Guide 8.19, Rev. 1, 6/79 – Occupational Radiation Dose Assessment in Light-Water Reactor Power Plants Design Stage Man-Rem Estimates

General		Conforms	
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Reg. Guide 8.38, Rev. 0, 6/93 – Control of Access to High and Very High Radiation Areas of Nuclear Plants

General		Conforms	
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Chapter 2

4. In lieu of (1) and (2) above, for a site where the nuclear island is founded on competent rock with shear wave velocity greater than 8000 feet per second and there are thin layers of soft material overlying the rock, the site-specific peak ground acceleration and spectra may be developed at the top of the competent rock and shown at the foundation level to be less than or equal to those given in Figures 3I.1-1 and 3I.1-2.
5. Foundation material layers are approximately horizontal (dip less than 20 degrees), and the median estimate of the low strain shear wave velocity of the soil below the foundation of the nuclear island is greater than or equal to 1000 feet per second.
6. For sites where the nuclear island is founded on soil, the median estimate of the strain-compatible soil shear modulus and hysteretic damping is compared to the values used in the AP1000 generic analyses shown in Table 3.7.1-4 and Figure 3.7.1-17. Properties of soil layers within a depth of 120 feet below finished grade are compared to those in the generic soil site analyses (soft soil, soft-to-medium soil, and upper bound soft-to-medium soil).
7. In lieu of (1) to (6) above, a site-specific evaluation can be performed as described in subsection 2.5.2.3.

Where features of the site are not within the parameters specified for the AP1000, site-specific soil structure interaction analyses may be performed using the 2D SASSI models described in Appendix 3G for variations in site conditions that can be represented in these models. Results should be compared to the results of the 2D SASSI analyses described in Appendix 3G. Such analyses may be used to demonstrate that local features, such as soil degradation properties or backfill, are bounded by the design cases. If the results are not clearly enveloped, then a 3D SASSI analysis may be required.

NRC 046

2.5.2.2 Site-Specific Seismic Structures

The AP1000 includes all seismic Category I structures, systems and components in the scope of the design certification.

2.5.2.3 Sites with Geoscience Parameters Outside the Certified Design

If the site-specific spectra at foundation level exceed the response spectra in Figures 3.7.1-1 and 3.7.1-2 at any frequency, or if soil conditions are outside the range evaluated for AP1000 design certification, a site-specific evaluation can be performed. This evaluation will consist of a site-specific dynamic analysis and generation of in-structure response spectra to be compared with the floor response spectra of the certified design at 5-percent damping. The site design response spectra at the foundation level in the free-field given in Figures 3.7.1-1 and 3.7.1-2 were used to develop the floor response spectra. They were applied at foundation level for the hard rock site and at finished grade level for the soil sites. The site is acceptable for construction of the AP1000 if the floor response spectra from the site-specific evaluation do not exceed the AP1000 spectra for each of the locations identified below:

Containment internal structures at elevation of reactor vessel support	Figure 3G.4-5
Containment operating floor	Figure 3G.4-6
Auxiliary building NE ^{north-east} corner at elevation 117'6"135'	Figure 3G.4-7
Shield building at fuel building roof	Figure 3G.4-8
Shield building roof	Figure 3G.4-9
Steel containment vessel at polar crane support	Figure 3G.4-10

Site-specific soil structure interaction analyses are performed using the 3D SASSI models described in Appendix 3G. The site-specific soil structure interaction analyses use the site-specific soil conditions (including variation in soil properties in accordance with Standard Review Plan 3.7.2). The three components of the site-specific ground motion time history must satisfy the regulatory requirements for statistical independence and enveloping of the site design spectra at 5% damping. Floor response spectra determined from the site-specific analyses should be compared against the design basis of the AP1000 described above. These evaluations and comparisons will be provided and reviewed as part of the Combined License application.

If the site-specific spectra at foundation level at a rock site exceed the response spectra in Figures 3I.1-1 and 3I.1-2 at any frequency, a site-specific evaluation can be performed similar to that described in Appendix 3I.

2.5.3 Surface Faulting Combined License Information

Combined License applicants referencing the AP1000 certified design will address the following surface and subsurface geological, seismological, and geophysical information related to the potential for surface or near-surface faulting affecting the site:

- Geological, seismological, and geophysical investigations
- Geological evidence, or absence of evidence, for surface deformation
- Correlation of earthquakes with capable tectonic sources
- Ages of most recent deformation
- Relationship of tectonic structures in the site area to regional tectonic structures
- Characterization of capable tectonic sources
- Designation of zones of quaternary deformation in the site region
- Potential for surface tectonic deformation at the site

2.5.4 Stability and Uniformity of Subsurface Materials and Foundations

Combined License applicants referencing the AP1000 certified design will address the following site-specific information related to the stability and uniformity of subsurface materials and foundations.

- Excavation

stratigraphic boundaries, lithologic changes, and unconformities, but most important, they should represent boundaries between layers having different shear wave velocities. Shear wave velocity is the primary property used for defining uniformity of a site.

The distribution of bearing reactions under the basemat is a function of the subgrade modulus, which in turn is a function of the shear wave velocity. The Combined License applicant shall demonstrate that the variation of subgrade modulus or shear wave velocity across the footprint is within the range considered for design of the nuclear island basemat. The farther that the non-uniform layer is located below the foundation, the less influence it has on the bearing pressures at the basemat. Lateral variability of the shear wave velocity at depths greater than 120 feet below grade (80 feet below the foundation) do not significantly affect the subgrade modulus.

If a site can be classified as uniform, it qualifies for the AP1000 based on analyses and evaluations performed to support design certification without additional site-specific analyses. For a site to be considered uniform, the variation of shear wave velocity in the material below the foundation to a depth of 120 feet below finished grade within the nuclear island footprint shall meet the criteria outlined below:

- The depth to a given layer indicated on each boring log may not fall precisely on the postulated “best-estimate” plane. The deviation of the observed layers from the “best-estimate” planes should not exceed 5 percent of the observed depths from the ground surface to the plane. If the deviation is greater than 5 percent, additional planes may be appropriate or additional borings may be required. This thereby diminishes the spacing.
- For a layer with a low strain shear wave velocity greater than or equal to 2500 feet per second, the layer should have approximately uniform thickness and should have a dip no greater than 20 degrees, and the shear wave velocity at any location within any layer should not vary from the average velocity within the layer by more than 20 percent.
- For a layer with a low strain shear wave velocity less than 2500 feet per second, the layer should have approximately uniform thickness and should have a dip no greater than 20 degrees, and the shear wave velocity at any location within any layer should not vary from the average velocity within the layer by more than 10 percent.

2.5.4.5.3.1 Site-Specific Subsurface Uniformity Design Basis

Many sites that do not meet the above criteria for a uniform site are acceptable for the AP1000. The key attribute for acceptability of the site for an AP1000 is the bearing pressure on the underside of the basemat. A site having local soft or hard spots within a layer or layers does not meet the criteria for a uniform site. Non-uniform soil conditions may also require evaluation of the AP1000 seismic response as described in subsection 2.5.2.32.

As described in subsection 3.8.5, the nuclear island foundation is designed specifically for bearing pressures of 120 percent of those of the uniform soil properties case. Evaluation criteria are defined to evaluate sites that do not satisfy the site parameters directly. The design basis provided below is included to provide a clear specification of the design commitment and evaluation criteria required to demonstrate that a site-specific application satisfies AP1000 requirements. Application of the

Table 2-1 (Sheet 1 of 3)

SITE PARAMETERS**Air Temperature**

Maximum Safety ^(a)	115°F dry bulb/80°F coincident wet bulb 85.5°F wet bulb (noncoincident)
Minimum Safety ^(a)	-40°F
Maximum Normal ^(b)	100°F dry bulb/80.1°F coincident wet bulb 80.1°F wet bulb (noncoincident) ^(d)
Minimum Normal ^(b)	-10°F

Wind Speed

Operating Basis	145 mph (3 second gust); importance factor 1.15 (safety), 1.0 (nonsafety); exposure C; topographic factor 1.0
Tornado	300 mph

Seismic

SSE	0.30g peak ground acceleration ^(c)
Fault Displacement Potential	None <u>Negligible</u>

Soil

Average Allowable Static Bearing Capacity	Greater than or equal to 8,600 lb/ft ² over the footprint of the nuclear island at its excavation depth
Maximum Allowable Dynamic Bearing Capacity for Normal Plus SSE	Greater than or equal to 35,000 lb/ft ² at the edge of the nuclear island at its excavation depth
Shear Wave Velocity	Greater than or equal to 1,000 ft/sec based on low-strain best-estimate soil properties over the footprint of the nuclear island at its excavation depth
Lateral Variability	Soils supporting the nuclear island should not have extreme variations in subgrade stiffness Case 1: For a layer with a low strain shear wave velocity greater than or equal to 2500 feet per second, the layer should have approximately uniform thickness, should have a dip not greater than 20 degrees, and should have less than 20 percent variation in the shear wave velocity from the average velocity in any layer. Case 2: For a layer with a low strain shear wave velocity less than 2500 feet per second, the layer should have approximately uniform thickness, should have a dip not greater than 20 degrees, and should have less than 10 percent variation in the shear wave velocity from the average velocity in any layer (see subsection 2.5.4.5).

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Table 2-1 (Sheet 2 of 3)	
SITE PARAMETERS	
Liquefaction Potential	None
<u>Minimum Soil Angle of Internal Friction</u>	<u>Greater than or equal to 35 degrees below footprint of nuclear island at its excavation depth</u>
Missiles	
Tornado	4000 - lb automobile at 105 mph horizontal, 74 mph vertical 275 - lb, 8 in. shell at 105 mph horizontal, 74 mph vertical 1 inch diameter steel ball at 105 mph horizontal and vertical
Flood Level	Less than plant elevation 100'
Ground Water Level	Less than plant elevation 98'
Plant Grade Elevation	Less than plant elevation 100' except for portion at a higher elevation adjacent to the annex building
Precipitation	
Rain	19.4 in./hr (6.3 in./5 min)
Snow/Ice	75 pounds per square foot on ground with exposure factor of 1.0 and importance factors of 1.2 (safety) and 1.0 (non-safety)
Atmospheric Dispersion Values - $\chi/Q^{(e)}$	
Site boundary (0-2 hr)	$\leq 1.0 \times 10^{-3} \text{ sec/m}^3$
Site boundary (annual average)	$\leq 2.0 \times 10^{-5} \text{ sec/m}^3$
Low population zone boundary	
0 - 8 hr	$\leq \underline{5.022} \times 10^{-4} \text{ sec/m}^3$
8 - 24 hr	$\leq \underline{3.046} \times 10^{-4} \text{ sec/m}^3$
24 - 96 hr	$\leq \underline{1.540} \times 10^{-4} \text{ sec/m}^3$
96 - 720 hr	$\leq 8.0 \times 10^{-5} \text{ sec/m}^3$
Population Distribution	
Exclusion area (site)	0.5 mi

Notes:

- Maximum and minimum safety values are based on historical data and exclude peaks of less than 2 hours duration.
- Maximum and minimum normal values are the 1 percent exceedance magnitudes.
- With ground response spectra as given in Figures 3.7.1-1 and 3.7.1-2. Seismic input is defined at finished grade except for sites where the nuclear island is founded on hard rock.
- The noncoincident wet bulb temperature is applicable to the cooling tower only.
- For AP1000, the terms "site boundary" and "exclusion area boundary" are used interchangeably. Thus, the χ/Q specified for the site boundary applies whenever a discussion refers to the exclusion area boundary.

Chapter 3

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AP1000 Compliance

The protection system is a microprocessor-based system that trips the reactor and actuates engineered safety features when predetermined limits are exceeded or when manually initiated.

The reactor trip portion of the protection system includes four independent, redundant, physically separated, electrically-isolated divisions. The coincidence circuits guard against the loss of protection or the generation of false protection signals due to equipment failures through the use of a two-out-of-four logic and built-in operational bypasses.

Independent, redundant, physically separated, electrically-isolated engineered safety features trains are provided. Signal conditioning for the plant sensors is provided. ~~Control and status signals are transmitted between the protection system and the main control room and the remote shutdown workstation and between the distributed logic circuits by internally redundant fiber optic data links.~~

See Chapter 7 for additional information concerning the design of the protection system.

Criterion 21 – Protection System Reliability and Testability

The protection system shall be designed for high functional reliability and in-service testability commensurate with the safety functions to be performed. Redundancy and independence designed into the protection system shall be sufficient to assure that (1) no single failure results in the loss of the protection function and (2) removal from service of any component or channel does not result in the loss of the required minimum redundancy unless the acceptable reliability of operation of the protection system can be otherwise demonstrated. The protection system shall be designed to permit periodic testing of its functioning when the reactor is in operation, including a capability to test channels independently to determine failures and losses of redundancy that may have occurred.

AP1000 Compliance

The protection system is designed for functional reliability and in-service testability. The design employs redundant logic trains and measurement and equipment diversity.

The protection system equipment includes integral testing circuits. System equipment, from input to output, in the protection cabinets and the engineered safety features cabinets, is tested. Simulated inputs replace the field signals. Outputs are monitored for validity. Manual and automatic testing is used to test the final stages of the reactor trip circuits and the reactor trip switchgear. Testing of cabinets and communications links verifies the functional operation of the equipment and the hardware. See Chapter 7 for further information concerning the test capabilities of the protection system.

Criterion 22 – Protection System Independence

The protection system shall be designed to assure that the effects of natural phenomena, and of normal operating, maintenance, testing, and postulated accident conditions on redundant channels do not result in the loss of the protection function or shall be demonstrated to be acceptable on

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10 CFR 21 applies to Class B structures, systems, and components. Class B structures, systems, and components are seismic Category I and use codes and standards consistent with the guidelines for NRC Quality Group B. 10 CFR 50, Appendix B, and ASME Code, Section III, Class 2 or Class MC apply. ASME Code, Section III, Subsection NE applies to the containment vessel and guard pipes.

3.2.2.5 Equipment Class C

Class C is a safety-related class equivalent to ANS Safety Class 3. It applies to other safety-related functions required to mitigate design basis accidents and other design basis events. Minor leakage will not prevent Class C structures, systems, and components from meeting the safety-related function, either from the regard of radiation dose or system functioning.

This class also applies to equipment that, upon rupturing, would cause dose limits for unrestricted areas, as specified in 10 CFR 20, to be exceeded or would cause a loss of core cooling.

10 CFR 21 applies to Class C structures, systems, and components. Class C structures, systems, and components use codes and standards consistent with the guidelines for NRC Quality Group C. Class C structures, systems, and components are seismic Category I except those noted below which are not required to provide a safety-related function following a seismic event. 10 CFR 50, Appendix B and ASME Code, Section III, Class 3 apply. In addition to these requirements, for systems that provide emergency core cooling functions, full radiography in accordance with the requirements of ASME Code, Section III, ND-5222 of a random sample of welds will be conducted on the piping butt welds during construction. For Class C air and gas storage tanks fabricated without welding, ASME Code, Section VIII, Appendix 22 may be used in lieu of Section III, Class 3. 10 CFR 50, Appendix B requirements and 10 CFR 21 apply to the manufacture of safety-related air and gas storage tanks. For core support structures ASME Code, Section III, Subsection NG applies. For electrical systems, appropriate IEEE standards, including IEEE standard 323-74 (Reference 3) and IEEE standard 344-87 (Reference 4), apply.

Class C applies to structures, systems, and components not included in Class A or Class B that are designed and relied upon to accomplish one or more of the following safety-related functions:

- Provide safety injection or maintain sufficient reactor coolant inventory to allow for core cooling
- Provide core cooling
- Provide containment cooling
- Provide for removal of radiation from the containment atmosphere as necessary to meet the offsite dose limits
- Limit the buildup of radioactive material in the atmosphere of rooms and areas outside containment as necessary to meet the offsite dose limits

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to. Sensing lines connected to the reactor coolant system pressure boundary are Class B if a suitable flow restrictor is provided.

The parts of the sensor, outside the pressure boundary, are designated Class C (1E) if they provide a safety-related function per subsection 3.2.2.1. They are Class D if the instrument supports Class D functions per subsection 3.2.2.6. Otherwise the parts are Class E.

3.2.2.9 Electrical Classifications

Safety-related electrical equipment is equipment Class C, as outlined in subsection 3.2.2.5, and is constructed to IEEE standards for Class 1E. The nonsafety-related electrical equipment and instrumentation is constructed to standards including non-Class 1E IEEE standards and National Electrical Manufacturers Association (NEMA) standards. Safety-related electrical equipment and instrumentation is identified in Section 3.11.

3.2.3 Inspection Requirements

Safety-related structures, systems, and components built to the requirements of the ASME Code, Section III, are required by 10 CFR 50.55a to have in-service inspections. The requirements of the in-service inspection program for ASME Code, Section III structures, systems, and components are found in Section XI of the ASME Code.

The following ASME standards apply to safety-related structures, systems, and components:

- | | |
|---------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| NRC 117 | <ul style="list-style-type: none">• Pumps (Class A, B, C) – ASME <u>Code, Section XI, Subsections IWB, IWC, and IWD/ANSI OM Part 6</u> |
| NRC 117 | <ul style="list-style-type: none">• Valves (Class A, B, C) – ASME <u>Code, Section XI, Subsections IWB, IWC, and IWD/ANSI OM Part 10</u>• Equipment supports (Class A, B, C) – ASME Code, Section XI, Subsection IWF• Metal containments and vessels – ASME Code, Section XI, Subsection IWE• Other Class A components such as pipes and tanks – ASME Code, Section XI, Subsection IWB• Other Class B components such as pipes and tanks – ASME Code, Section XI, Subsection IWC• Other Class C components such as pipes and tanks – ASME Code, Section XI, Subsection IWD. |

The inspection requirements, if applicable, for Class D structures, systems, and components are established by the designer for each structure, system, and component. These inspection requirements are developed so that the reliability of the structures, systems, and components is not degraded. The inspection requirements are included in the administratively controlled inspection or maintenance plans.

Table 3.2-3 (Sheet 1 of 65)

**AP1000 CLASSIFICATION OF MECHANICAL AND
FLUID SYSTEMS, COMPONENTS, AND EQUIPMENT**

Tag Number	Description	AP1000 Class	Seismic Category	Principal Construction Code	Comments
Auxiliary Steam Supply System (ASS) Location: Turbine Building					
System components are Class E					
Steam Generator Blowdown System (BDS) Location: Turbine Building					
System components are Class E					
Compressed and Instrument Air System (CAS) Location: Various					
CAS-PL-V014	Instrument Air Supply Outside Containment Isolation	B	I	ASME III-2	
CAS-PL-V015	Instrument Air Supply Inside Containment Isolation	B	I	ASME III-2	
CAS-PL-V027	Containment Penetration Test Connection Isolation	B	I	ASME III-2	
CAS-PL-V204	Service Air Supply Outside Containment Isolation	B	I	ASME III-2	
CAS-PL-V205	Service Air Supply Inside Containment Isolation	B	I	ASME III-2	
CAS-PL-V219	Containment Penetration Test Connection Isolation	B	I	ASME III-2	
CAS-PY-C02	Containment Instrument Air Inlet Penetration	B	I	ASME III, 2MC	
CAS-PY-C03	Containment Service Air Inlet Penetration	B	I	ASME III, 2MC	
Balance of system components are Class E					
Component Cooling Water System (CCS) Location: Auxiliary Building and Turbine Building					
n/a	Heat Exchangers, CCS and SWS Side	D	NS	ASME VIII	
n/a	Pumps	D	NS	Hydraulic Institute Stds.	
n/a	Tanks	D	NS	ASME VIII	
n/a	Valves Providing CCS AP1000 Equipment Class D Function	D	NS	ANSI 16.34	
CCS-PL-V200	CCS Containment Isolation Valve - Inlet Line ORC	B	I	ASME III-2	
CCS-PL-V201	CCS Containment Isolation Valve - Inlet Line IRC	B	I	ASME III-2	

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Table 3.2-3 (Sheet 2 of 65)

**AP1000 CLASSIFICATION OF MECHANICAL AND
FLUID SYSTEMS, COMPONENTS, AND EQUIPMENT**

Tag Number	Description	AP1000 Class	Seismic Category	Principal Construction Code	Comments
Component Cooling Water System (Continued)					
CCS-PL-V207	CCS Containment Isolation Valve - Outlet Line IRC	B	I	ASME III-2	
CCS-PL-V208	CCS Containment Isolation Valve - Outlet Line ORC	B	I	ASME III-2	
CCS-PL-V209	Containment Isolation Valve Test Connection - Outlet Line	B	I	ASME III-2	
CCS-PL-V257	Containment Isolation Valve Test Connection - Inlet Line	B	I	ASME III-2	
CCS-PY-C01	Containment Supply Header Penetration	B	I	ASME III, 2MC	
CCS-PY-C02	Containment Return Header Penetration	B	I	ASME III, 2MC	
Balance of system components are Class E					
Condensate System (CDS)				Location: Turbine Building	
System components are Class E					
Condenser Tube Cleaning System (CES)				Location: Turbine Building	
System components are Class E					
Turbine Island Chemical Feed System (CFS)				Location: Turbine Building	
System components are Class E					
Condenser Air Removal System (CMS)				Location: Turbine Building	
n/a	Condenser Vacuum Breakers	E	NS	ANSI 16.34	
Balance of system components are Class D					
Containment System (CNS)				Location: Containment	
CNS-MV-01	Containment Vessel	B	I	ASME III, MC	
CNS-MY-Y01	Equipment Hatch	B	I	ASME III, MC	
CNS-MY-Y02	Maintenance Hatch	B	I	ASME III, MC	
CNS-MY-Y03	Personnel Hatch - 135'-3"	B	I	ASME III, MC	
CNS-MY-Y04	Personnel Hatch - 107'-2"	B	I	ASME III, MC	
n/a	Spare Containment Penetrations	B	I	ASME III, MC	
Condensate Polishing System (CPS)				Location: Turbine Building	
System components are Class E					

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Table 3.2-3 (Sheet 4 of 65)

**AP1000 CLASSIFICATION OF MECHANICAL AND
FLUID SYSTEMS, COMPONENTS, AND EQUIPMENT**

Tag Number	Description	AP1000 Class	Seismic Category	Principal Construction Code	Comments
Chemical and Volume Control System (Continued)					
CVS-PL-V092	Hydrogen Add Containment Isolation	B	I	ASME III-2	
CVS-PL-V094	Hydrogen Add IRC Isolation	B	I	ASME III-2	
CVS-PL-V096	Hydrogen Add Containment Isolation Test Connection	B	I	ASME III-2	
CVS-PL-V100	Makeup Line Containment Isolation Relief	B	I	ASME III-2	
CVS-PL-V136A	Demineralized Water System Isolation	C	I	ASME III-3	
CVS-PL-V136B	Demineralized Water System Isolation	C	I	ASME III-3	
CVS-PY-C01	Demineralizer Resin Flush Line Containment Penetration	B	I	ASME III, MC	
CVS-PY-C02	Letdown Line Containment Penetration	B	I	ASME III, MC ₂	
CVS-PY-C03	Makeup Line Containment Penetration	B	I	ASME III, MC	
CVS-PY-C04	Hydrogen Add Line Containment Penetration	B	I	ASME III, 2MC	
Balance of system components are Class D or E					
Circulating Water System (CWS)			Location: Turbine Building and pump intake structure		
System components are Class E					
Standby Diesel and Auxiliary Boiler Fuel Oil System (DOS)			Location: Diesel Generator Building and yard		
n/a	Fuel Oil Transfer Package	D	NS	Manufacturer Std.	
n/a	Fuel Oil Storage Tanks	D	NS	API 650	
n/a	Fuel Oil Day Tanks	D	NS	ASME VIII	
n/a	Valves Providing DOS AP1000 Equipment Class D Function	D	NS	ANSI 16.34	
n/a	Ancillary Diesel Generator Fuel Tank	D	II	UL 142	
Balance of system components are Class E					

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Table 3.2-3 (Sheet 5 of 65)

**AP1000 CLASSIFICATION OF MECHANICAL AND
FLUID SYSTEMS, COMPONENTS, AND EQUIPMENT**

Tag Number	Description	AP1000 Class	Seismic Category	Principal Construction Code	Comments
Storm Drain System (DRS)					Location: Various
System components are Class E					
Demineralized Water Treatment System (DTS)					Location: Turbine Building
System components are Class E					
Demineralized Water Transfer and Storage System (DWS)					Location: Various
n/a	Condensate Storage Tanks	D	NS	API 650	
n/a	Valves Providing DWS AP1000 Equipment Class D Function	D	NS	ANSI 16.34	
DWS-PL-V244	Demineralized Water Supply Containment Isolation - Outside	B	I	ASME III-2	
DWS-PL-V245	Demineralized Water Supply Containment Isolation - Inside	B	I	ASME III-2	
DWS-PL-V248	Containment Penetration Test Connection Isolation	B	I	ASME III-2	
DWS-PY-C01	Containment Demineralized Water Supply Penetration	B	I	ASME III, 2MC	
Balance of system components are Class E					
Fuel Handling and Refueling System (FHS)					Location: Containment and Auxiliary Building
FHS-FH-02	Fuel Handling Machine	D	II/NS	AISC	
FHS-FH-52	Spent Fuel Assembly Handling Tool	D	II	AISC	
FHS-FS-01	New Fuel Storage Rack	D	I	Manufacturer Std.	
FHS-FS-02	Spent Fuel Storage Rack	D	I	Manufacturer Std.	
FHS-FT-01	Fuel Transfer Tube	B	I	ASME III Class MC	
FHS-MT-01	Spent Fuel Pool	C	I	ACI 349	ACI 349 Evaluation of Structural Boundary Only
FHS-MT-02	Fuel Transfer Canal	C	I	ACI 349	ACI 349 Evaluation of Structural Boundary Only

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Table 3.2-3 (Sheet 6 of 65)

**AP1000 CLASSIFICATION OF MECHANICAL AND
FLUID SYSTEMS, COMPONENTS, AND EQUIPMENT**

Tag Number	Description	AP1000 Class	Seismic Category	Principal Construction Code	Comments
Fuel Handling and Refueling System (Continued)					
FHS-MT-05	Spent Fuel Cask Loading Pit	C	I	ACI 349	ACI 349 Evaluation of Structural Boundary Only
FHS-MT-06	Spent Fuel Cask Washdown Pit	C	I	ACI 349	ACI 349 Evaluation of Structural Boundary Only
FHS-MY-Y01	Spent Fuel Transfer Gate	C	I	Manufacturer Std.	
FHS-MY-Y02	Spent Fuel Cask Loading Pit Gate	C	I	Manufacturer Std.	
FHS-PL-V001	Fuel transfer tube Isolation Valve	C	I	ASME-III-3	
FHS-PY-B01	Fuel Transfer Tube Blind Flange	B	I	ASME III-2	
Balance of system components are Class E					
Fire Protection System (FPS)					Location: Various
FPS-PL-V050	Fire Water Containment Supply Isolation	B	I	ASME III-2	
FPS-PL-V051	Fire Water Containment Test Connection Isolation	B	I	ASME III-2	
FPS-PL-V052	Fire Water Containment Supply Isolation - Inside	B	I	ASME III-2	
FPS-PY-C01	Fire Protection Containment Penetration	B	I	ASME III, 2MC	
Balance of system components are Class E					
Main and Startup Feedwater System (FWS)					Location: Turbine Building
n/a	Startup Feedwater Pumps	D	NS	Hydraulic Institute Standards	
n/a	Valves Providing SFW AP1000 Equipment Class D Function	D	NS	ANSI 16.34	
Balance of system components are Class E					

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Table 3.2-3 (Sheet 13 of 65)					
AP1000 CLASSIFICATION OF MECHANICAL AND FLUID SYSTEMS, COMPONENTS, AND EQUIPMENT					
Tag Number	Description	AP1000 Class	Seismic Category	Principal Con- struction Code	Comments
Primary Sampling System (Continued)					
PSS-PL-V010B	Liquid Sample Line Containment Isolation IRC	B	I	ASME III-2	
PSS-PL-V011	Liquid Sample Line Containment Isolation ORC	B	I	ASME III-2	
PSS-PL-V012A	Liquid Sample Check Valve	C	I	ASME III-3	
PSS-PL-V012B	Liquid Sample Check Valve	C	I	ASME III-3	
PSS-PL-V023	Sample Return Line Containment Isolation ORC	B	I	ASME III-2	
PSS-PL-V024	Sample Return Containment Isolation Check IRC	B	I	ASME III-2	
PSS-PL-V046	Air Sample Line Containment Isolation ORC	B	I	ASME III-2	
PSS-PL-V076A	Containment Testing Boundary Isolation Valve	C	I	ASME III-3	
PSS-PL-V076B	Containment Testing Boundary Isolation Valve	C	I	ASME III-3	
PSS-PL-V082	Containment Isolation Test Connection Isolation Valve	C	I	ASME III-3	
PSS-PL-V083	Containment Isolation Test Connection Isolation Valve	C	I	ASME III-3	
PSS-PL-V085	Containment Isolation Test Connection Isolation Valve	B	I	ASME III-2	
PSS-PL-V086	Containment Isolation Test Connection Isolation Valve	C	I	ASME III-3	
PSS-PY-C01	Common Primary Sample Line Penetration	B	I	ASME III, MC	
PSS-PY-C02	Containment Atmosphere Sample Line Penetration	B	I	ASME III, MC	
PSS-PY-C03	Containment Atmosphere Sample Line Penetration	B	I	ASME III, 2MC	
Balance of system components are Class E					
Potable Water System (PWS)					Location: Various
System components are Class E					

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Table 3.2-3 (Sheet 21 of 65)					
AP1000 CLASSIFICATION OF MECHANICAL AND FLUID SYSTEMS, COMPONENTS, AND EQUIPMENT					
Tag Number	Description	AP1000 Class	Seismic Category	Principal Con- struction Code	Comments
Passive Core Cooling System (Continued)					
PXS-PL-V232B	Accumulator B Fill/Drain Isolation	C	I	ASME III-3	
PXS-PY-C01	Nitrogen Makeup Containment Penetration	B	I	ASME III, 2MC	
Balance of system components are Class E					
Reactor Coolant System (RCS)				Location: Containment	
RCS-MB-01	Steam Generator 1	A	I	ASME III-1	
RCS-MB-02	Steam Generator 2	A	I	ASME III-1	
RCS-MP-01A	SG 1 Reactor Coolant Pump	A	I	ASME III-1	
RCS-MP-01B	SG 1 Reactor Coolant Pump	A	I	ASME III-1	
RCS-MP-02A	SG 2 Reactor Coolant Pump	A	I	ASME III-1	
RCS-MP-02B	SG 2 Reactor Coolant Pump	A	I	ASME III-1	
RCS-MV-01	Reactor Vessel	A	I	ASME III-1	
RCS-MV-02	Pressurizer	A	I	ASME III-1	
RCS-MY-Y11	SG 1 Shell	B	I	ASME III-1	
RCS-MY-Y12	SG 1 Channel Head Divider Plate	B	I	ASME III-1	
RCS-MY-Y13	SG 1 Tube Bundle Support Assembly	C	I	ASME III, NG	
RCS-MY-Y14	SG 1 Steam Flow Limiting Venturi	B	I	ASME III, NG	
RCS-MY-Y15	SG 1 Feedwater Distribution Ring Supports	B	I	ASME III, NG	
RCS-MY-Y21	SG 2 Shell	B	I	ASME III-1	
RCS-MY-Y22	SG 2 Channel Head Divider Plate	B	I	ASME III-1	
RCS-MY-Y23	SG 2 Tube Bundle Support Assembly	C	I	ASME III, NG	
RCS-MY-Y24	SG 2 Steam Flow Limiting Venturi	B	I	ASME III, NG	
RCS-MY-Y25	SG 2 Feedwater Distribution Ring Supports	B	I	ASME III, NG	

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**AP1000 CLASSIFICATION OF MECHANICAL AND
FLUID SYSTEMS, COMPONENTS, AND EQUIPMENT**

Tag Number	Description	AP1000 Class	Seismic Category	Principal Construction Code	Comments
Main Control Room Emergency Habitability System (Continued)					
VES-PL-V038	Makeup Air Stop Valve	C	I	ASME III-3	
VES-PL-V040A	Air Tank Safety Relief Valve A	C	I	ASME III-3	
VES-PL-V040B	Air Tank Safety Relief Valve B	C	I	ASME III-3	
VES-PL-V041A	Air Tank Safety Relief Valve A	C	I	ASME III-3	
VES-PL-V041B	Air Tank Safety Relief Valve B	C	I	ASME III-3	
VES-PL-V043A	Differential Pressure Instrument Line Isolation Valve A	C	I	ASME III-3	
VES-PL-V043B	Differential Pressure Instrument Line Isolation Valve B	C	I	ASME III-3	
VES-PL-V044	Main Air Flowpath Isolation Valve	C	I	ASME III-3	
Containment Air Filtration System (VFS)			Location: Auxiliary Building and Annex Building		
VFS-PY-C01	Containment Supply Duct Penetration	B	I	ASME III, 2MC	
VFS-PY-C02	Containment Exhaust Duct Penetration	B	I	ASME III, 2MC	
VFS-MY-Y01	Containment Air Supply Debris Screen	C	I	ASME Sec. III Class 3	
VFS-MY-Y02	Containment Air Exhaust Debris Screen	C	I	ASME Sec. III Class 3	
VFS-PL-V001	Containment Isolation Test Connection	B	I	ASME III-2	
VFS-PL-V002	Containment Isolation Test Connection	C	I	ASME III-3	
VFS-PL-V003	Containment Purge Supply Containment Isolation Valve	B	I	ASME III-2	
VFS-PL-V004	Containment Purge Supply Containment Isolation Valve	B	I	ASME III-2	
VFS-PL-V006	Containment Isolation Test Connection	C	I	ASME III-3	

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Table 3.2-3 (Sheet 62 of 65)					
AP1000 CLASSIFICATION OF MECHANICAL AND FLUID SYSTEMS, COMPONENTS, AND EQUIPMENT					
Tag Number	Description	AP1000 Class	Seismic Category	Principal Con- struction Code	Comments
Central Chilled Water System (Continued)					
NRC 044 VWS-PY-C01	Containment Chilled Water Supply Penetration	B	I	ASME III, 2MC	
NRC 044 VWS-PY-C02	Containment Chilled Water Return Penetration	B	I	ASME III, 2MC	
VWS-PL-V058	Fan Coolers Supply Containment Isolation	B	I	ASME III-2	
VWS-PL-V062	Fan Coolers Supply Containment Isolation	B	I	ASME III-2	
VWS-PL-V082	Fan Coolers Return Containment Isolation	B	I	ASME III-2	
VWS-PL-V086	Fan Coolers Return Containment Isolation	B	I	ASME III-2	
VWS-PL-V424	Containment Penetration Test Connection	B	I	ASME III-2	
VWS-PL-V425	Containment Penetration Test Connection	B	I	ASME III-2	
Balance of system components are Class E					
Annex/Auxiliary Nonradioactive Ventilation System (VXS) Location: Auxiliary Building and Annex Building					
n/a	Air Handling Unit Fans Providing AP1000 Equipment Class D Function	Note 2	NS	AMCA	
n/a	Dampers Providing VXS AP1000 Equipment Class D Function	Note 2	NS	ANSI/AMCA-500	
n/a	Exhaust Fan Providing Ancillary Diesel Room Ventilation	Note 2	NS	AMCA	
n/a	Fire Dampers	Note 3	NS	UL-555 or UL-555S	
n/a	Air Handling Units	L	NS	Manufacturer Std.	
n/a	Filters	L	NS	UL 900	
n/a	Fans, Ductwork	L	NS	SMACNA	
Balance of system components are Class E or Class L					

Table 3.2-3 (Sheet 64 of 65)					
AP1000 CLASSIFICATION OF MECHANICAL AND FLUID SYSTEMS, COMPONENTS, AND EQUIPMENT					
Tag Number	Description	AP1000 Class	Seismic Category	Principal Con- struction Code	Comments
Liquid Radwaste System (Continued)					
n/a	Ion Exchangers	D	NS	ASME VIII	
n/a	Filters	D	NS	ASME VIII	
n/a	Valves Providing WLS AP1000 Equipment Class D Function (local drain valves in Radwaste Building)	D	NS	ANSI 16.34	
WLS-PL-V055	Sump Discharge Containment Isolation IRC	B	I	ASME III-2	
WLS-PL-V057	Sump Discharge Containment Isolation ORC	B	I	ASME III-2	
WLS-PL-V067	RCDT Gas Outlet Containment Isolation IRC	B	I	ASME III-2	
WLS-PL-V068	RCDT Gas Outlet Containment Isolation ORC	B	I	ASME III-2	
WLS-PL-V071A	CVS Compartment to Sump	C	I	ASME III-3	
WLS-PL-V071B	PXS A Compartment to Sump	C	I	ASME III-3	
WLS-PL-V071C	PXS B Compartment to Sump	C	I	ASME III-3	
WLS-PL-V072A	CVS Compartment to Sump	C	I	ASME III-3	
WLS-PL-V072B	PXS A Compartment to Sump	C	I	ASME III-3	
WLS-PL-V072C	PXS B Compartment to Sump	C	I	ASME III-3	
WLS-PY-C02	Reactor Coolant Drain Tank WLS Connection Penetration	B	I	ASME III, 2MC	
WLS-PY-C03	Containment Sump Pumps Combined Discharge Penetration	B	I	ASME III, 2MC	
Balance of system components are Class E					
Radioactive Waste Drain System (WRS)				Location: Auxiliary Building	
n/a	Pumps	D	NS	Manufacturer Std.	
n/a	Valves Providing WRS AP1000 Equipment Class D Function	D	NS	ANSI 16.34	

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3.5.1.6 Aircraft Hazards

As described previously in Section 2.2, the site interface is established to address aircraft hazards as discussed in subsection 3.5.4. The AP1000 missile interface criteria are based on the tornado missiles described in subsection 3.5.1.4. Additional analyses are required to evaluate other site specific missiles. Aircraft crash probability and the effects of this hazard on the plant is determined as described in Section 2.2.

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3.5.2 Protection from Externally Generated Missiles

Systems required for safe shutdown are protected from the effects of missiles. These systems are identified in Section 7.4. Protection from external missiles, including those generated by natural phenomena, is provided by the external walls and roof of the Seismic Category I nuclear island structures. The external walls and roofs are reinforced concrete. The structural design requirements for the shield building and auxiliary building are outlined in subsection 3.8.4. Openings through these walls are evaluated on a case-by-case basis to provide confidence that a missile passing through the opening would not prevent safe shutdown and would not result in an offsite release exceeding the limits defined in 10 CFR 100. The evaluation of site-specific hazards for external events that may produce missiles more energetic than tornado missiles is discussed in subsection 2.2.1.

Evaluation of turbine missiles is provided in subsection 3.5.1.3. Evaluation of tornado missiles is provided in subsection 3.5.1.4. Conformance with regulatory guide recommendations is provided in Appendix 1A.

3.5.3 Barrier Design Procedures

Missile barriers and protective structures are designed to withstand and absorb missile impact loads to prevent damage to safety-related components.

Formulae used for missile penetration calculations into steel or concrete barriers are the Modified National Defense Research Committee (NDRC) formula for concrete and either the Ballistic Research Laboratory (BRL) or Stanford formulae for steel.

Concrete (Modified NDRC Formula)

$$x = \left[4 \text{KNWd} \left(\frac{V}{1000d} \right)^{1.8} \right]^{0.5} \quad \text{for } \frac{x}{d} \leq 2.0$$

$$x = \text{KNW} \left(\frac{V}{1000d} \right)^{1.8} + d \quad \text{for } \frac{x}{d} > 2.0$$

where

x = penetration depth, inches
W = missile weight, lbs

NRC 168 | For the design of seismic Category I structures, a set of ~~six~~five design soil profiles (that include hard rock) of various shear wave velocities is established from parametric studies as described in Appendix 3G. These ~~six~~five profiles are sufficient to envelope sites where the shear wave velocity of the supporting medium at the foundation level exceeds 1000 feet per second (see subsection 2.5.2). The design soil profiles include a hard rock site, a soft rock site, a firm rock site, an upper bound soft-to-medium soil site, a soft-to-medium soil site, and a soft soil site. The shear wave velocity profiles and related governing parameters of the ~~six~~five sites considered are as follows:

- For the hard rock site, an upper bound case for rock sites using a shear wave velocity of 8000 feet per second.
- For the firm rock site, a shear wave velocity of 3500 feet per second to a depth of 120 feet and base rock at the depth of 120 feet.
- NRC 168 | • For the soft rock site, a shear wave velocity of 2400 feet per second at the ground surface, increasing linearly to 3200 feet per second at a depth of 240 feet, and base rock at the depth of 120 feet.
- For the upper bound soft-to-medium soil site, a shear wave velocity of 1414 feet per second at ground surface, increasing parabolically to 3394 feet per second at 240 feet, base rock at the depth of 120 feet, and ground water at grade level. The initial soil shear modulus profile is twice that of the soft-to-medium soil site.
- For the soft-to-medium soil site, a shear wave velocity of 1000 feet per second at ground surface, increasing parabolically to 2400 feet per second at 240 feet, base rock at the depth of 120 feet, and ground water is assumed at grade level.
- For the soft soil site, a shear wave velocity of 1000 feet per second at ground surface, increasing linearly to 1200 feet per second at 240 feet, base rock at the depth of 120 feet, and ground water is assumed at grade level

NRC 168 | The strain-dependent shear modulus curves for the foundation materials, together with the corresponding damping curves are taken from References 37 and 38 and are shown in Figures 3.7.1-15 and 3.7.1-16 for rock material and soil material respectively. The different curves for soil in Figure 3.7.1-16 apply to the range of depth within a soil column below grade. The strain-dependent soil material damping is limited to 15 percent of critical damping. The strain-dependent properties used in the SSI analyses for the safe shutdown earthquake are shown in Table 3.7.1-4 and Figure 3.7.1-17 for the firm rock, soft rock, upper bound soft-to-medium soil, soft-to-medium soil, and soft soil properties.

3.7.2 Seismic System Analysis

Seismic Category I structures, systems, and components are classified according to Regulatory Guide 1.29. Seismic Category I building structures of AP1000 consist of the containment building (the steel containment vessel and the containment internal structures), the shield building, and the auxiliary building. These structures are founded on a common basemat and are collectively known as the nuclear island or nuclear island structures. [*Key dimensions, such as thickness of the*

*NRC Staff approval is required prior to implementing a change in this information; see DCD Introduction Section 3.5.

Seismic systems are defined, according to SRP 3.7.2, Section II.3.a, as the seismic Category I structures that are considered in conjunction with their foundation and supporting media to form a soil-structure interaction model. The following subsections describe the seismic analyses performed for the nuclear island. Other seismic Category I structures, systems, equipment, and components not designated as seismic systems (that is, heating, ventilation, and air-conditioning systems; electrical cable trays; piping systems) are designated as seismic subsystems. The analysis of seismic subsystems is presented in subsection 3.7.3.

Seismic Category I building structures are on the nuclear island. Other building structures are classified nonseismic or seismic Category II. Nonseismic structures are analyzed and designed for seismic loads according to the Uniform Building Code (Reference 2) requirements for Zone 2A. Seismic Category II building structures are designed for the safe shutdown earthquake using the same methods and design allowables as are used for seismic Category I structures. The acceptance criteria are based on ACI 349 for concrete structures and on AISC N690 for steel structures including the supplemental requirements described in subsections 3.8.4.4.1 and 3.8.4.5. The seismic Category II building structures are constructed to the same requirements as the nonseismic building structures, ACI 318 for concrete structures and AISC-S355 for steel structures.

Separate seismic analyses are performed for the nuclear island for each of the ~~six~~five design soil profiles defined in subsection 3.7.1.4. The analyses generate one set of in-structure responses for each of the design soil profiles. The ~~six~~five sets of in-structure responses are enveloped to obtain the seismic design envelope (design member forces, nodal accelerations, nodal displacements, and floor response spectra), which are used in the design and analysis of seismic Category I structures, components, and seismic subsystems.

Appendix 3G summarizes the types of models and analysis methods that are used in the seismic analyses of the nuclear island, as well as the type of results that are obtained and where they are used in the design. The seismic analyses of the nuclear island are summarized in a seismic analysis summary report. This report describes the development of the finite element models, the soil structure interaction and fixed base analyses, and the results thereof. ~~A separate report provides the floor response spectra for the nuclear island.~~ Seismic response spectra are given in Appendix 3G for the six key locations:

- Containment internal structures at reactor vessel support elevation 100.00'.
- Containment internal structures at operating deck elevation 134.25'.
- Auxiliary shield building north east corner at control room floor elevation 116.50'.
- Auxiliary shield building corner of fuel building roof at shield building elevation 179.19'.
- Auxiliary shield building roof area elevation 327.41'.
- Steel containment vessel near polar crane elevation 224.000'.

3.7.2.1 Seismic Analysis Methods

Seismic analyses of the nuclear island are performed in conformance with the criteria within SRP 3.7.2.

Seismic analyses – using response spectra analysis the equivalent static acceleration method, the mode superposition time-history method, and the complex frequency response analysis method – are performed for the safe shutdown earthquake to determine the seismic force distribution for use

in the design of the nuclear island structures, and to develop in-structure seismic responses (accelerations, displacements, and floor response spectra) for use in the analysis and design of seismic subsystems.

3.7.2.1.1 Equivalent Static Acceleration Analysis

Equivalent static analyses, using computer program ANSYS (Reference 36), are performed to obtain the seismic forces and moments required only for the structural design of the auxiliary building, the shield building, the steel containment vessel and the nuclear island basemat (see subsection 3.8.2.4.1.1), ~~and the containment internal structures on the nuclear island~~. Equivalent static loads are applied to the finite element models using the maximum acceleration results from the time history analyses for the ~~six~~^{four} design soil profiles. Accidental torsional moments are applied as described in subsection 3.7.2-11.

~~Coupled Shield and Auxiliary Buildings on Fixed Base~~

~~The analyses are performed using the three dimensional, finite element model of the coupled shield and auxiliary buildings including the shield building roof. The effect of the containment internal structures are considered by inclusion of the shell models. The equivalent static accelerations are developed and discussed in Appendix 3G.~~

~~Equivalent static analyses are performed using the fixed base, three dimensional, finite element models fixed at elevation 63' 6". The support provided by the embedment below grade is not considered in these analyses.~~

~~Containment Internal Structures~~

~~Equivalent static analyses of the containment internal structures on a fixed base are performed using the three dimensional, finite element model of the containment internal structures developed and discussed in Appendix 3G.~~

3.7.2.1.2 Time-History Analysis and Complex Frequency Response Analysis

Mode superposition time-history analyses using computer program ANSYS and complex frequency response analysis using computer program SASSI are performed to obtain the in-structure seismic response needed in the analysis and design of seismic subsystems. Three-dimensional finite element shell models of the nuclear island structures are used in conjunction with the design soil profiles presented in subsection 3.7.1.4 to obtain the in-structure responses. Stick models are coupled to the shell models of the concrete structures for the containment vessel, polar crane, reactor coolant loop, pressurizer, and core makeup tanks. Two models are used. The fine (NI10) model, as described in subsection 3G.2.2.1, is used to define the seismic response for the hard rock site. The coarse (NI20) model, as described in subsection 3G.2.2.2, is used for the soil structure interaction (SSI) analyses and is set up in both ANSYS and SASSI. The models and analyses are described in Appendix 3G.

For the hard rock site, the soil-structure interaction effect is negligible. Therefore, for the hard rock site, the nuclear island is analyzed as a fixed-base structure, using computer program ANSYS without the foundation media. The three components of earthquake (two horizontal and one vertical time histories) are applied simultaneously in the analysis. Since the NI10 finite element

model of the auxiliary and shield building uses shell elements to represent the 6-foot-thick basemat, the nodes of the basemat element are at the center of the basemat (elevation 63'-6"). The finite element model of the containment internal structures uses solid elements, which extend down to elevation 60'-6". When the finite element models are combined and used in the time history analyses, the auxiliary building finite element model is fixed at the shell element basemat nodes (elevation 63'-6") and the base of the containment internal structures is fixed at the bottom of the solid element base nodes (elevation 60'-6"). This difference in elevation of the base fixity is not significant since the concrete between elevations 60'-6" and 63'-6", below the auxiliary building, is nearly rigid. There is no lateral support due to soil or hard rock below grade. This case results in higher response than a case analyzed with full lateral support below grade.

3.7.2.1.3 Response Spectrum Analysis

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~~Response spectral analysis is used. Equivalent static acceleration and mode superposition time-history methods are primarily used~~ for the evaluation of the nuclear island structures. Response spectrum analyses ~~is may be~~ used to perform an analysis of a particular structure or portion of structure using the procedures described in subsections 3.7.2.6, 3.7.2.7, and 3.7.3.

3.7.2.2 Natural Frequencies and Response Loads

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Modal analyses are performed for the shell and lumped-mass stick models of the seismic Category I structures on the nuclear island, as described in Appendix 3G. Seismic response spectra at the six key locations (subsection 3.7.2) are given in ~~Typical results are shown in~~ Appendix 3G.

3.7.2.3 Procedure Used for Modeling

Based on the general plant arrangement, three-dimensional, finite element models are developed for the nuclear island structures: a finite element model of the coupled shield and auxiliary buildings, a finite element model of the containment internal structures, a finite element model of the shield building roof, and an axisymmetric shell model of the steel containment vessel. These three-dimensional, finite element models provide the basis for the development of the dynamic model of the nuclear island structures.

The finite element models of the coupled shield and auxiliary buildings, and the containment internal structures are based on the gross concrete section with the modulus based on the specified compressive strength of concrete reduced by a factor of 0.8 to consider the effect of cracking as recommended in Table 6-5 of FEMA 356 (Reference 5).

Seismic subsystems coupled to the overall dynamic model of the nuclear island include the coupling of the reactor coolant loop model to the model of the containment internal structures, and the coupling of the polar crane model to the model of the steel containment vessel. The criteria used for decoupling seismic subsystems from the nuclear island model are according to Section II.3.b of SRP 3.7.2, Revision 2. The total mass of other major subsystems and equipment is less than one percent of the respective supporting nuclear island structures; therefore, the mass of other major subsystems and equipment is included as concentrated lumped-mass only.

The floor response spectra for the design of subsystems and components are generated by broadening the enveloped nodal response spectra determined for the hard rock site and soil sites.

The spectral peaks are broadened by ± 15 percent to account for the variation in the structural frequencies, due to the uncertainties in parameters such as material and mass properties of the structure and soil, damping values, seismic analysis technique, and the seismic modeling technique. Figure 3.7.2-14 shows the broadening procedure used to generate the design floor response spectra. Spectral peaks at frequencies associated with fundamental soil structure interaction frequencies are reviewed. If there is a “valley” between peaks ~~due to associated with~~ different soil profiles and not the building modal response, then this valley is filled by extending the broadening of the lower peak horizontally until it meets the broadened upper peak.

Floor response spectra for the auxiliary building are obtained from the three-dimensional model as described in Appendix 3G. These spectra are developed for the specific location in the auxiliary building. Where spectra at a number of nodes have similar characteristics, a single set of spectra may be developed by enveloping the broadened spectra at each of the nodes.

The safe shutdown earthquake floor response spectra for 5 percent damping, at representative locations of the coupled auxiliary and shield buildings, the steel containment vessel, and the containment internal structures are presented in Appendix 3G.

3.7.2.6 Three Components of Earthquake Motion

Seismic system analyses are performed considering the simultaneous occurrences of the two horizontal and the vertical components of earthquake.

In mode superposition time-history analyses using computer program ANSYS, the three components of earthquake are applied either simultaneously or separately. In the ANSYS analyses with the three earthquake components applied simultaneously, the effect of the three components of earthquake motion is included within the analytical procedure so that further combination is not necessary.

In analyses with the earthquake components applied separately and in the response spectrum and equivalent static analyses, the effect of the three components of earthquake motion are combined using one of the following methods:

- For seismic analyses with the statistically independent earthquake components applied separately, the time-history responses from the three earthquake components are combined algebraically at each time step to obtain the combined response time-history. This method is used in the SASSI analyses.
- The peak responses due to the three earthquake components from the response spectrum and equivalent static analyses are combined using the square root of the sum of squares (SRSS) method.
- The peak responses due to the three earthquake components are combined directly, using the assumption that when the peak response from one component occurs, the responses from the other two components are 40 percent of the peak (100 percent-40 percent-40 percent).

- The structure is classified as seismic Category II and is analyzed and designed to prevent its collapse under the safe shutdown earthquake.

The structures adjacent to the nuclear island are the annex building, the radwaste building, and the turbine building.

3.7.2.8.1 Annex Building

The portion of the annex building adjacent to the nuclear island is classified as seismic Category II. The structural configuration is shown in Figure 3.7.2-19. The annex building is analyzed for the safe shutdown earthquake for the ~~six~~^{five} soil profiles described in subsection 3.7.1.4. For the hard rock site, a range of soil properties is assumed for the layer above rock at the level of the nuclear island foundation. Seismic input is defined by response spectra applied at the base of a dynamic model of the annex building. The horizontal spectra are obtained from the 2D SASSI analyses and account for soil-structure and structure-soil-structure interaction. Input in the east-west direction uses the response spectra obtained from the two dimensional analyses for the annex building mat. Input in the north-south direction uses the response spectra obtained from the two dimensional analyses for the turbine building mat. Vertical input is obtained from 2D SASSI finite element soil-structure interaction analyses. The seismic response spectra input at the base of the annex building are the envelopes of the range of soil sites and also envelope the AP1000 design free field ground spectra shown in Figures 3.7.1-1 and 3.7-1-2. The envelope of the maximum building response acceleration values is applied as equivalent static loads to a more detailed static model.

The minimum space required between the annex building and the nuclear island to avoid contact is obtained by absolute summation of the deflections of each structure obtained from either a time history or a response spectrum analysis for each structure. The maximum displacement of the roof of the annex building is 1.6 inches in the east-west direction. The minimum clearance between the structural elements of the annex building above grade and the nuclear island is 4 inches.

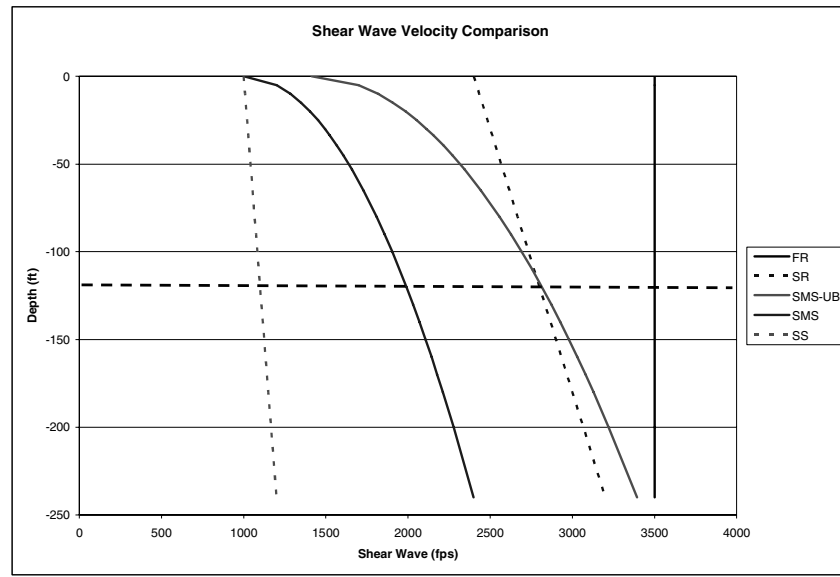
3.7.2.8.2 Radwaste Building

The radwaste building is classified as nonseismic and is designed to the seismic requirements of the Uniform Building Code, Zone 2A with an Importance Factor of 1.25. As shown in the radwaste building general arrangement in Figure 1.2-22, it is a small steel framed building. If it were to impact the nuclear island or collapse in the safe shutdown earthquake, it would not impair the integrity of the reinforced concrete nuclear island. The minimum clearance between the structural elements of the radwaste building above grade and the nuclear island is 4 inches.

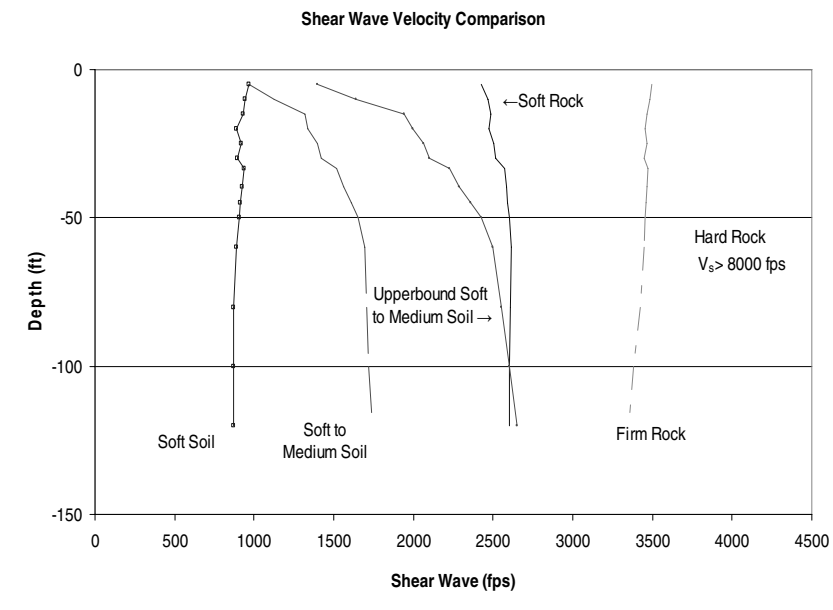
Three methods are used to demonstrate that a potential radwaste building impact on the nuclear island during a seismic event will not impair its structural integrity:

- The maximum kinetic energy of the impact during a seismic event considers the maximum radwaste building and nuclear island velocities. The total kinetic energy is considered to be absorbed by the nuclear island and converted to strain energy. The deflection of the nuclear island is less than 0.2". The shear forces in the nuclear island walls are less than the ultimate shear strength based on a minus one standard deviation of test data.

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Initial Properties



Strain-Iterated Shear Wave Velocity Profiles

Note: Fixed base analyses were performed for hard rock sites. These analyses are applicable for shear wave velocity greater than 8000 feet per second.

Figure 3.7.1-17

Generic Soil Profiles

of the doors within the lock. The airlocks extend radially out from the containment vessel through the shield building. They are supported by the containment vessel.

Each airlock has two double-gasketed, pressure-seated doors in series. The doors are mechanically interlocked to prevent simultaneous opening of both doors and to allow one door to be completely closed before the second door can be opened. The interlock can be bypassed by using special tools and procedures.

3.8.2.1.5 Mechanical Penetrations

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The mechanical penetrations consist of the fuel transfer penetration and mechanical piping penetrations and are listed in Table 6.2.3-14.

Figure 3.8.2-4, sheet 1, shows typical details for the main steam penetration. This includes bellows to minimize piping loads applied to the containment vessel and a guardpipe to protect the bellows and to prevent overpressurization of the containment annulus in a postulated pipe rupture event. Similar details are used for the feedwater penetration.

Figure 3.8.2-4, sheet 2, shows typical details for the startup feedwater penetration. This includes a guardpipe to prevent overpressurization of the containment annulus in a postulated pipe rupture event. Similar details are used for the steam generator blowdown penetration.

Figure 3.8.2-4, sheet 3, shows typical details for the normal residual heat removal penetration. Similar details are used for other penetrations below elevation 107'-2" where there is concrete inside the containment vessel. The flued head is integral with the process piping and is welded to the containment sleeve. The welds are accessible for in-service inspection. The containment sleeve is separated from the concrete by compressible material.

Figure 3.8.2-4, sheet 4 shows typical details for the other mechanical penetrations. These consist of a sleeve welded to containment with either a flued head welded to the sleeve (detail A), or with the process piping welded directly to the sleeve (detail B). Flued heads are used for stainless piping greater than 2 inches in nominal diameter and for piping with high operating temperatures.

Design requirements for the mechanical penetrations are as follows:

- Design and construction of the process piping follow ASME, Section III, Subsection NC. Design and construction of the remaining portions follow ASME Code, Section III, Subsection NE. The boundary of jurisdiction is according to ASME Code, Section III, Subsection NE.
- Penetrations are designed to maintain containment integrity under design basis accident conditions, including pressure, temperature, and radiation.
- Guard pipes are designed for pipe ruptures as described in subsection 3.6.2.1.1.4.
- Bellows are stainless steel or nickel alloy and are designed to accommodate axial and lateral displacements between the piping and the containment vessel. These displacements include

thermal growth of the main steam and feedwater piping during plant operation, relative seismic movements, and containment accident and testing conditions. Cover plates are provided to protect the bellows from foreign objects during construction and operation. These cover plates are removable to permit in-service inspection.

The fuel transfer penetration, shown in Figure 3.8.2-4, sheet 5, is provided to transfer fuel between the containment and the fuel handling area of the auxiliary building. The fuel transfer tube is welded to the penetration sleeve. The containment boundary is a double-gasketed blind flange at the refueling canal end. The expansion bellows are not a part of the containment boundary. Rather, they are water seals during refueling operations and accommodate differential movement between the containment vessel, containment internal structures, and the auxiliary building.

3.8.2.1.6 Electrical Penetrations

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Figure 3.8.2-4, sheet 6, shows a typical 12-inch-diameter electrical penetration. The penetration assemblies consist of conductors ~~three~~ three modules (or medium voltage cables ~~six~~ six modules in a similar 18-inch-diameter penetration) passing through a bulkhead attached to the containment nozzle. Electrical design of these penetrations is described in subsection 8.3.1.1.65.

Electrical penetrations are designed to maintain containment integrity under design basis accident conditions, including pressure, temperature, and radiation. Double barriers permit testing of each assembly to verify that containment integrity is maintained. Design and testing is according to IEEE Standard 317-83 and IEEE Standard 323-74.

3.8.2.2 Applicable Codes, Standards, and Specifications

*[The containment vessel is designed and constructed according to the 2001 edition of the ASME Code, Section III, Subsection NE, Metal Containment, including the 2002 Addenda. Stability of the containment vessel and appurtenances is evaluated using ASME Code, Case N-284-1, Metal Containment Shell Buckling Design Methods, Class MC, Section III, Division 1, as published in the 2001 Code Cases, 2001 Edition, July 1, 2001.]**

Structural steel nonpressure parts, such as ladders, walkways, and handrails are designed to the requirements for steel structures defined in subsection 3.8.4.

Section 1.9 discusses compliance with the Regulatory Guides and the Standard Review Plans.

3.8.2.3 Loads and Load Combinations

Table 3.8.2-1 summarizes the design loads, load combinations and ASME Service Levels. They meet the requirements of the ASME Code, Section III, Subsection NE. The containment vessel is designed for the following loads specified during construction, test, normal plant operation and shutdown, and during accident conditions:

- D Dead loads or their related internal moments and forces, including any permanent piping and equipment loads

*NRC Staff approval is required prior to implementing a change in this information; see DCD Introduction Section 3.5.

3.8.2.4.2.4 Personnel Airlocks

The capacity of the personnel airlocks was determined by comparing the airlock design to that tested and reported in NUREG/CR-5118 (Reference 3). Critical parameters are the same, so the results of the test apply directly. In the tests the inner door and end bulkhead of the airlock withstood a maximum pressure of 300 psig at 400°F. The capacity of the airlock is therefore at least 300 psig at ambient temperature. The maximum pressure corresponding to Service Level C is conservatively estimated by reducing this capacity in the ratio of the minimum specified material yield to ultimate.

3.8.2.4.2.5 Mechanical and Electrical Penetrations

Subsections 3.8.2.1.3 through 3.8.2.1.6 describe the containment penetrations. Penetration reinforcement is designed following the area replacement method of the ASME Code. The insert plates and sleeves permit development of the hoop tensile yield stresses predicted as the limiting capacity in subsection 3.8.2.4.1. Capacities of the equipment hatch covers are discussed in subsection 3.8.2.4.2.3 and of the personnel airlocks in subsection 3.8.2.4.2.4.

Mechanical penetrations welded directly to the containment vessel are generally piping systems with design pressures greater than that of the containment vessel. Thicknesses of the flued head or end plate are established based on piping support loads or stiffness requirements. The capacities of these penetrations are greater than the capacity of the containment vessel cylinder.

Mechanical penetrations for the large-diameter high-energy lines, such as the main steam and feedwater piping, include expansion bellows. The piping and flued head have large pressure capability. The response of expansion bellows to severe pressure and deformations is described in NUREG/CR-5561 (Reference 4). The bellows can withstand large pressure loading but may tear once the containment vessel deflection becomes large. Testing reported in NUREG/CR-6154 (Reference 26) has shown that the bellows remain leaktight even when subjected to large deflections sufficient to fully compress the bellows. Such large deflections do not occur as long as the containment vessel remains elastic. As described in subsection 3.8.2.4.2.6, the radial deflection of the shell increases substantially once the containment cylinder yields. The resulting deflections are assumed to cause loss of containment function. The containment penetration bellows are designed for a pressure of 90 psig at design temperature within Service Level C limits, concurrent with the relative displacements imposed on the bellows when the containment vessel is pressurized to these magnitudes.

Electrical penetrations have a pressure boundary consisting of the sleeve and an end plate containing a series of modules. The electrical pressure boundary is designed and built to the requirements of the ASME Code, Section III, Class MC, Subsection NE. The pressure capacity of these elements is large and is greater than the capacity of the containment vessel cylinder at temperatures up to the containment design temperature. Electrical penetration assemblies are also designed to satisfy ASME Service Level C stress limits under a pressure of 90 psig at design temperature. Tests at pressures and temperatures representative of severe accident conditions are described in NUREG/CR-5334 (Reference 5), where typical nuclear industry the Westinghouse penetrations were irradiated, aged, then tested. One design was tested to 1375 psia at 7400°F. Other electrical penetration assemblies were tested to 75 psia at 400°F and 155 psia at 361°F. ~~Higher pressures and temperatures.~~ These tests showed that the electrical penetration

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The deterministic severe accident pressure that can be accommodated according to the ASME Service Level C stress intensity limits and using a factor of safety of 1.67 for buckling of the top head is determined by the capacity of the 16-foot-diameter equipment hatch cover and the ellipsoidal head. The maximum capacity of the hatch cover, calculated according to ASME paragraph NE-3222, Service Level C, is 84 psig at an ambient temperature of 100°F and 81 psig at 300°F. When calculated in accordance with ASME Code, Case N-284, Service Level C, the maximum capacity is 126 psig at an ambient temperature of 100°F and 121 psig at 300°F. The maximum capacity of the ellipsoidal head is 104 psig at 100°F and 91 psig at 300°F.

The maximum pressure that can be accommodated according to the ASME Service Level C stress intensity limits, excluding evaluation of instability, is determined by yield of the cylinder and is 135 psig at an ambient temperature of 100°F and 117 psig at 300°F. This limit is used in the evaluations required by 10 CFR 50.34(f).

3.8.2.5 Structural Criteria

The containment vessel is designed, fabricated, installed, and tested according to the ASME Code, Section III, Subsection NE, and will receive a code stamp.

Stress intensity limits are according to ASME Code, Section III, Paragraph NE-3221 and Table NE-3221-1. [*Critical buckling stresses are checked according to the provisions of ASME Code, Section III, Paragraph NE-3222, or ASME Code Case N-284.*]*

3.8.2.6 Materials, Quality Control, and Special Construction Techniques

Materials for the containment vessel, including the equipment hatches, personnel locks, penetrations, attachments, and appurtenances meet the requirements of NE-2000 of the ASME Code. The basic containment material is SA738, Grade B, plate. The procurement specification for the SA738, grade B, plate includes supplemental requirements S1, Vacuum Treatment and S20, Maximum Carbon Equivalent for Weldability. This material has been selected to satisfy the lowest service metal temperature requirement of -18.5°F. This temperature is established by analysis for the portion of the vessel exposed to the environment when the minimum ambient air temperature is -40°F. Impact test requirements are as specified in NE-2000.

The containment vessel is coated with an inorganic zinc coating, except for those portions fully embedded in concrete. The inside of the vessel below the operating floor and up to 8 feet above the operating floor also has a phenolic top coat. Below elevation 100' the vessel is fully embedded in concrete with the exception of the few penetrations at low elevations (see Figure 3.8.2-4, sheet 3 of 6, for typical details). Embedding the steel vessel in concrete protects the steel from corrosion.

The AP1000 configuration is shown in the general arrangement figures in Section 1.2 and in Figure 3.8.2-1. The exterior of the vessel is embedded at elevation 100' and concrete is placed against the inside of the vessel up to the maintenance floor at elevation 107'-2". Above this elevation the inside and outside of the containment vessel are accessible for inspection of the coating. The vessel is coated with an inorganic zinc primer to a level just below the concrete.

*NRC Staff approval is required prior to implementing a change in this information; see DCD Introduction Section 3.5.

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N = Loads generated by the probable maximum precipitation (provided previously in Table 2-0-1).

3.8.4.3.1.4 Abnormal Loads

Abnormal loads are those loads generated by a postulated high-energy pipe break accident for pipes not qualified for leak-before-break. Abnormal loads include the following:

P_a = Pressure load within or across a compartment generated by the postulated break. The main steam isolation valve (MSIV) and steam generator blowdown valve compartments are designed for a pressurization load of 6 psi. The subcompartment design pressure bounds the pressurization effects due to postulated breaks in high energy pipe. Determination of subcompartment pressure loads is discussed in subsection 6.2.1.2.

T_a = Thermal loads under thermal conditions generated by the postulated break and including T_o . Determination of subcompartment temperatures is discussed in subsection 6.2.1.2.

R_a = Piping and equipment reactions under thermal conditions generated by the postulated break and including R_o . Determination of pipe reactions generated by postulated breaks is discussed in subsection 3.6.

Y_r = Load on the structure generated by the reaction on the broken high-energy pipe during the postulated break. Determination of the loads is discussed in Section 3.6.

Y_j = Jet impingement load on the structure generated by the postulated break. Determination of the loads is discussed in Section 3.6.

Y_m = Missile impact load on the structure generated by or during the postulated break, as from pipe whipping. Determination of the loads is discussed in Section 3.6.

3.8.4.3.1.5 Dynamic Effects of Abnormal Loads

The dynamic effects from the impulsive and impactive loads caused by P_a , R_a , Y_r , Y_j , Y_m , and tornado missiles are considered by one of the following methods:

- Applying an appropriate dynamic load factor to the peak value of the transient load
- Using impulse, momentum, and energy balance techniques
- Performing a time-history dynamic analysis

Elastoplastic behavior may be assumed with appropriate ductility ratios, provided excessive deflections will not result in loss of function of any safety-related system.

Dynamic increase factors appropriate for the strain rates involved may be applied to static material strengths of steel and concrete for purposes of determining section strength.

F_D = maximum dynamic lateral force, including dynamic active earth pressures
 F_H = maximum lateral force due to all loads except seismic loads

The sliding resistance is based on the friction force developed between the basemat and the foundation. The governing friction value in the interface zone is a thin soil layer below the mudmat with an angle of internal friction of 35° giving a coefficient of friction of 0.70. The effect of buoyancy due to the water table is included in calculating the sliding resistance.

3.8.5.5.4 Overturning

The factor of safety against overturning of the nuclear island during a tornado or a design wind is shown in Table 3.8.5-2 and is calculated as follows:

$$F.S. = \frac{M_R}{M_O}$$

where:

$F.S.$ = factor of safety against overturning from tornado or design wind
 M_R = resisting moment
 M_O = overturning moment of tornado or design wind

The factor of safety against overturning of the nuclear island during a safe shutdown earthquake is shown in Table 3.8.5-2 and is evaluated using the static moment balance approach assuming overturning about the edge of the nuclear island at the bottom of the basemat. The factor of safety is defined as follows:

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$$F.S. = \frac{(M_R + M_P)}{(M_O + M_{AO})} \quad F.S. = \frac{M_R}{M_O}$$

where:

$F.S.$ = factor of safety against overturning from a safe shutdown earthquake
 M_R = nuclear island's resisting moment against overturning
 M_O = maximum safe shutdown earthquake induced overturning moment acting on the nuclear island, applied as a static moment
 M_P = Resistance moment associated with passive pressure
 M_{AO} = Moment due to lateral forces caused by active and overburden pressures

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The resisting moment is equal to the nuclear island dead weight, minus buoyant force from ground water table, multiplied by the distance from the edge of the nuclear island to its center of gravity. The overturning moment is the maximum moment about the same edge considering all of the soil cases including hard rock.

Table 3.8.2-1

LOAD COMBINATIONS AND SERVICE LIMITS FOR CONTAINMENT VESSEL

Load Description		Load Combination and Service Limit											
		Con	Test	Des.	Des.	A	A	A	C	D	C	D	D
Dead	D	x	x	x	x	x	x	x	x	x	x	x	x
Live	L	x	x	x	x	x	x	x	x	x	x	x	x
Wind	W	x				x							
Safe shutdown earthquake	E _S								x	x		x	x
Tornado	W _t										x		
Test pressure	P _t		x										
Test temperature	T _t		x										
Operating pressure	P _O										x		
Design pressure	P _d			x			x		x			x	
External pressure (2.9 psid)	P _e				x			x		x			
External pressure (0.9 psid) ⁽³⁾	P _e					x							x
Normal reaction	R _O				x	x		x		x	x		
Normal thermal	T _O				(4)	(5)		(4)		(4)	(4)		(5)
Accident thermal reactions	R _a			x			x		x			x	
Accident thermal	T _a			x			x		x			x	
Accident pipe reactions	Y _r											x	
Jet impingement	Y _j											x	
Pipe impact	Y _m											x	

Notes:

- Service limit levels are per ASME-NE.
- Where any load reduces the effects of other loads, that load is to be taken as zero, unless it can be demonstrated that the load is always present or occurs simultaneously with the other loads.
- Reduced pressure of 0.9 psid at one hour in loss of all AC transient in cold weather.
- Temperature of vessel is 70°F.
- Temperature distribution for loss of all AC in cold weather.

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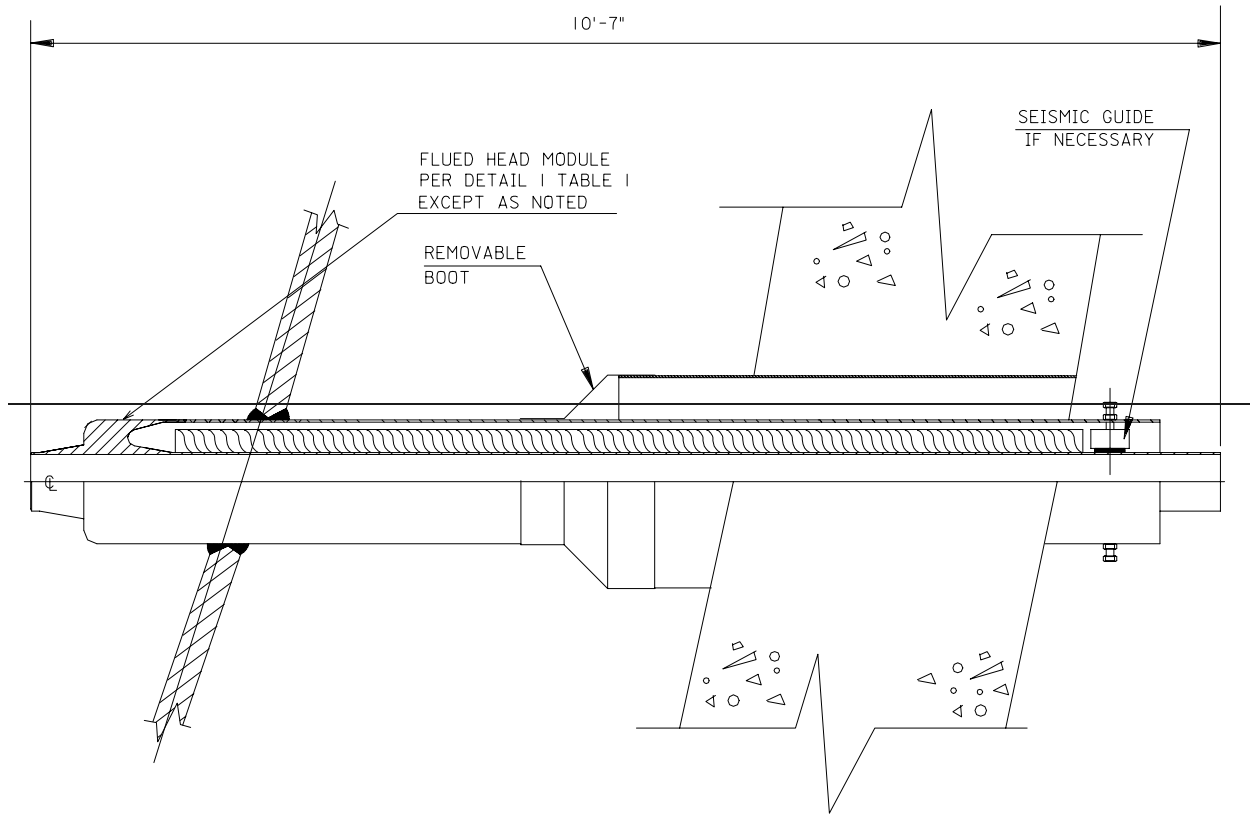
Table 3.8.5-2	
FACTORS OF SAFETY FOR FLOTATION, OVERTURNING AND SLIDING OF NUCLEAR ISLAND STRUCTURES	
HARD ROCK CONDITION	
Environmental Effect	Factor of Safety ⁽¹⁾
Flotation	
High Ground Water Table	3.7
Design Basis Flood	3.5
Sliding	
Design Wind, North-South	23.2
Design Wind, East-West	17.4
Design Basis Tornado, North-South	12.8
Design Basis Tornado, East-West	10.6
Safe Shutdown Earthquake, North-South	1.28 ⁽²⁾
Safe Shutdown Earthquake, East-West	1.34 ⁽²⁾
Overturning	
Design Wind, North-South	51.5
Design Wind, East-West	27.9
Design Basis Tornado, North-South	17.7
Design Basis Tornado, East-West	9.6
Safe Shutdown Earthquake, North-South	1.39
Safe Shutdown Earthquake, East-West	1.07 ⁽³⁾

Note:

- Factor of safety is calculated for the soil and rock sites described in subsection 3.7.1.4. Minimum value for all sites is shown in this table.
- Factor of safety is shown for soils below and adjacent to nuclear island having angle of internal friction of 35 degrees.
- ~~The factor of safety of 1.07 does not consider active and passive soil pressures on the external walls below grade. When these soil pressures are considered for overturning (as they are in the sliding evaluation), the minimum factor of safety against overturning increases to 1.12. This factor of safety meets the requirement of 1.1 based on the conservative moment balance formula treating the seismic moment as static loads. ASCE/SEI 43-05, Reference 46, recognizes that there is considerable margin beyond that given by the moment balance formula and permits a nonlinear rocking analysis. The nonlinear (liftoff allowed) time history analysis described in Appendix 3G-6 showed that the nuclear island basemat uplift effect is insignificant. Further, these analyses were performed for free field seismic ZPA input as high as 0.5g without significant uplift. Therefore the factor of safety against overturning is greater than 1.67 (0.5g/0.3g).~~

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NRC 044

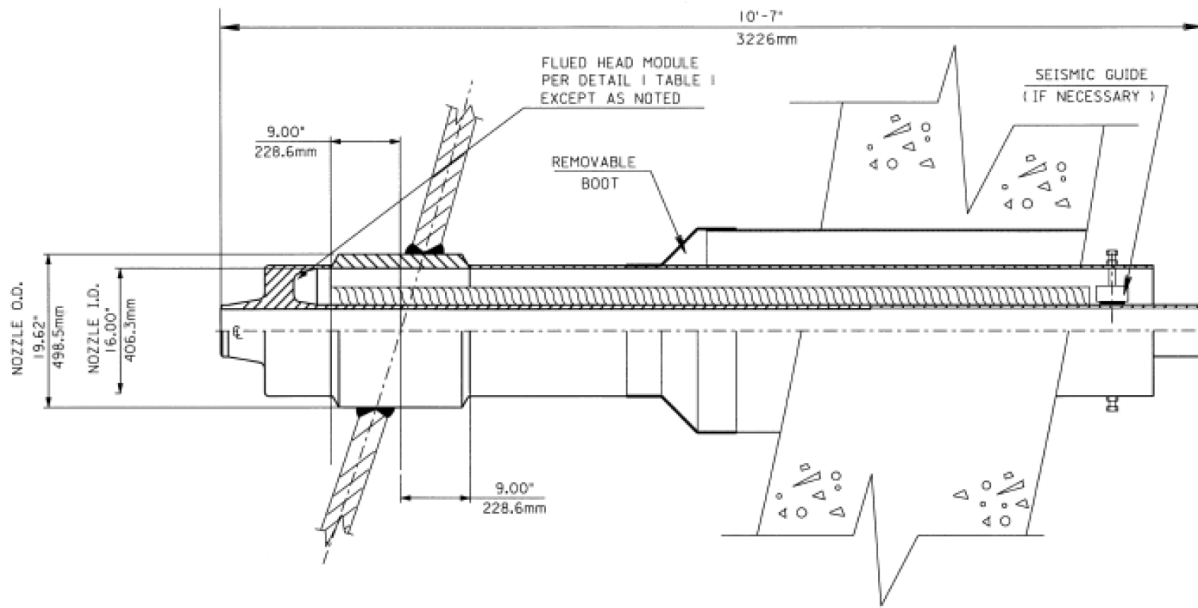
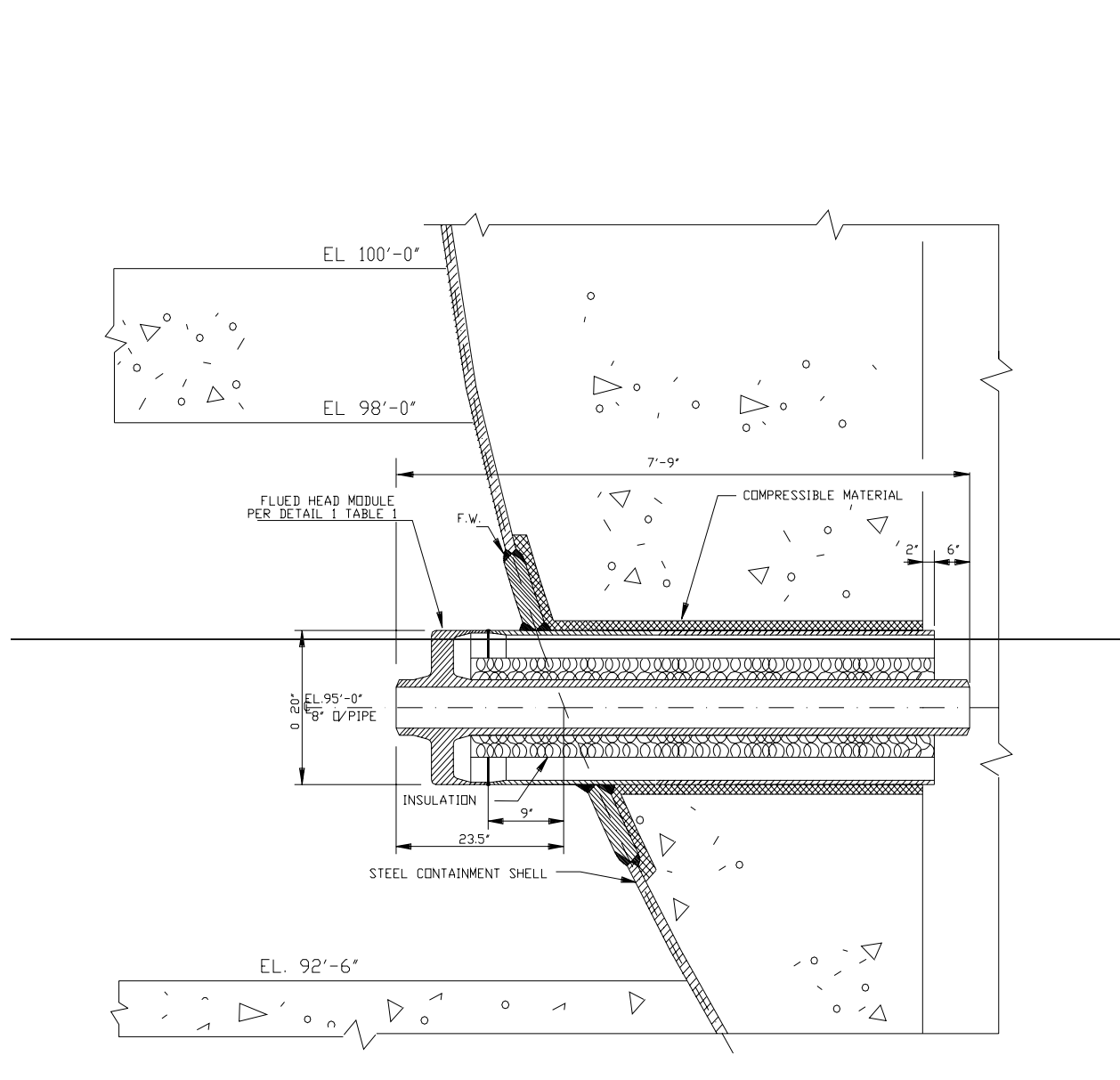


Figure 3.8.2-4 (Sheet 2 of 6)

Containment Penetrations Startup Feedwater



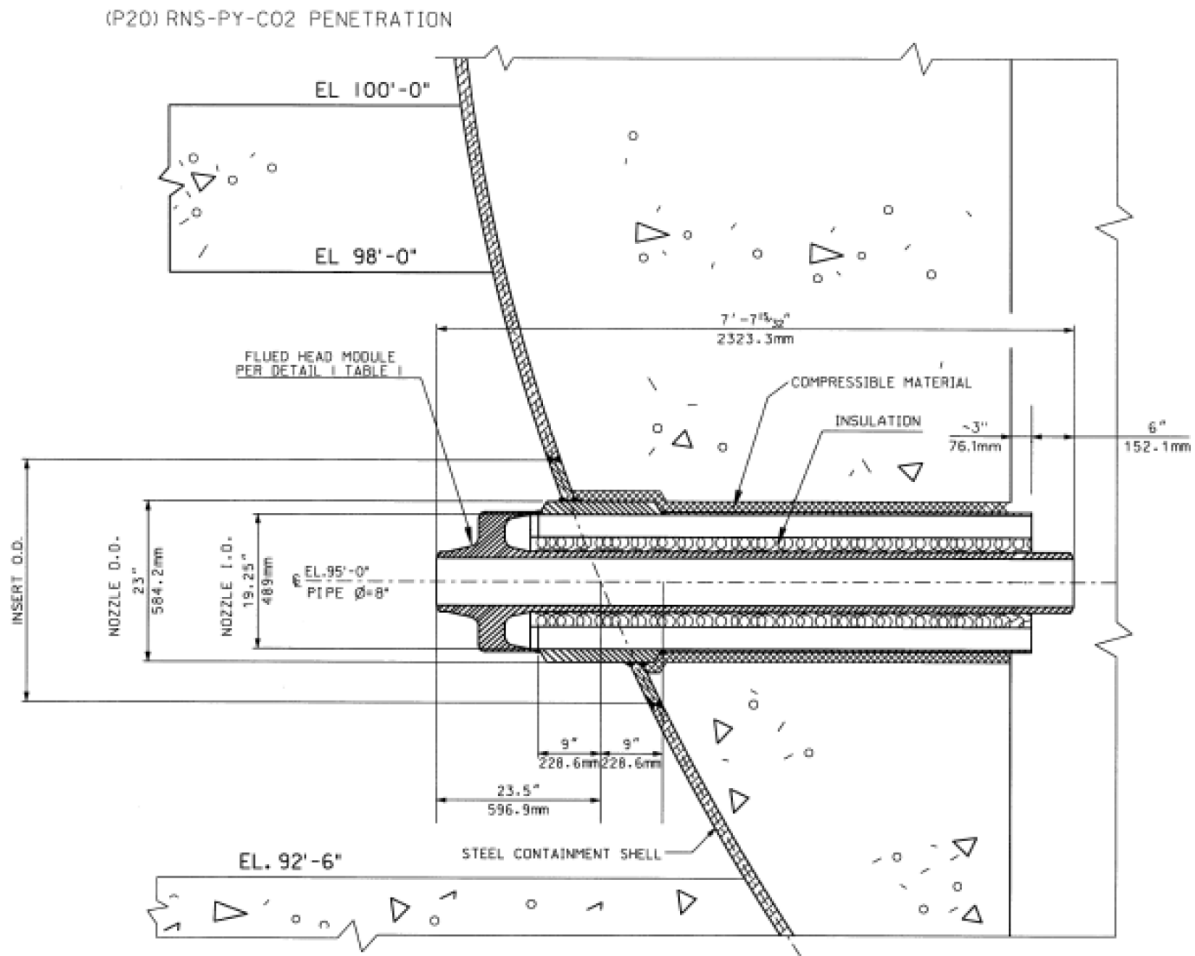
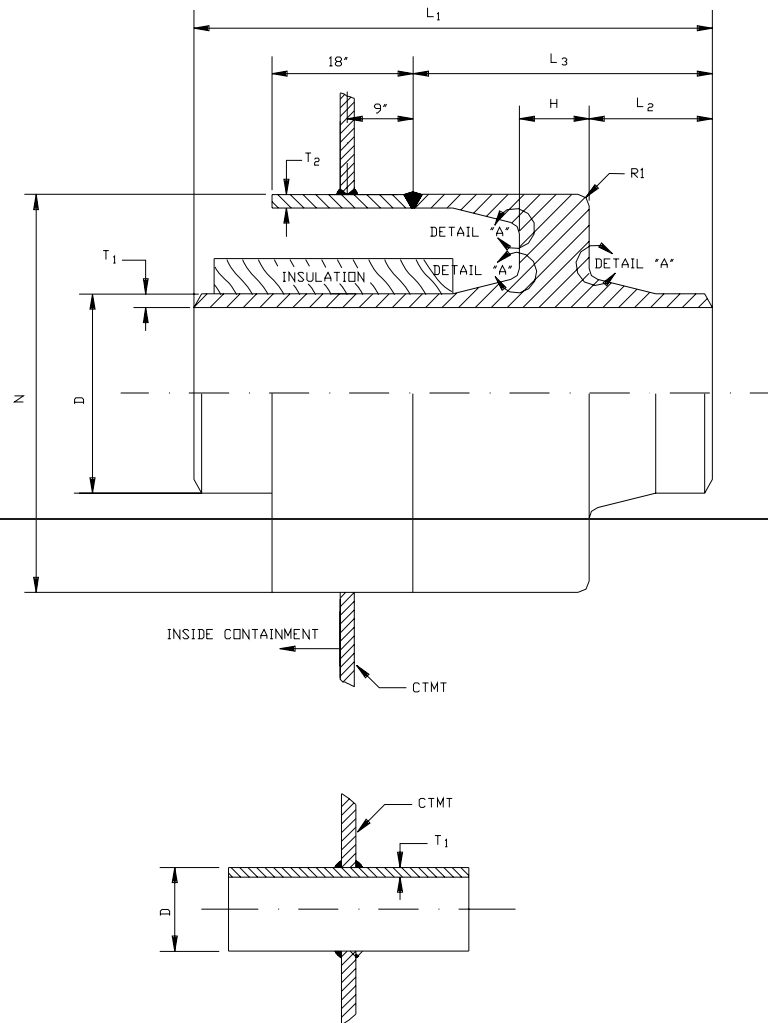


Figure 3.8.2-4 (Sheet 3 of 6)

Containment Penetrations Normal RHR Piping



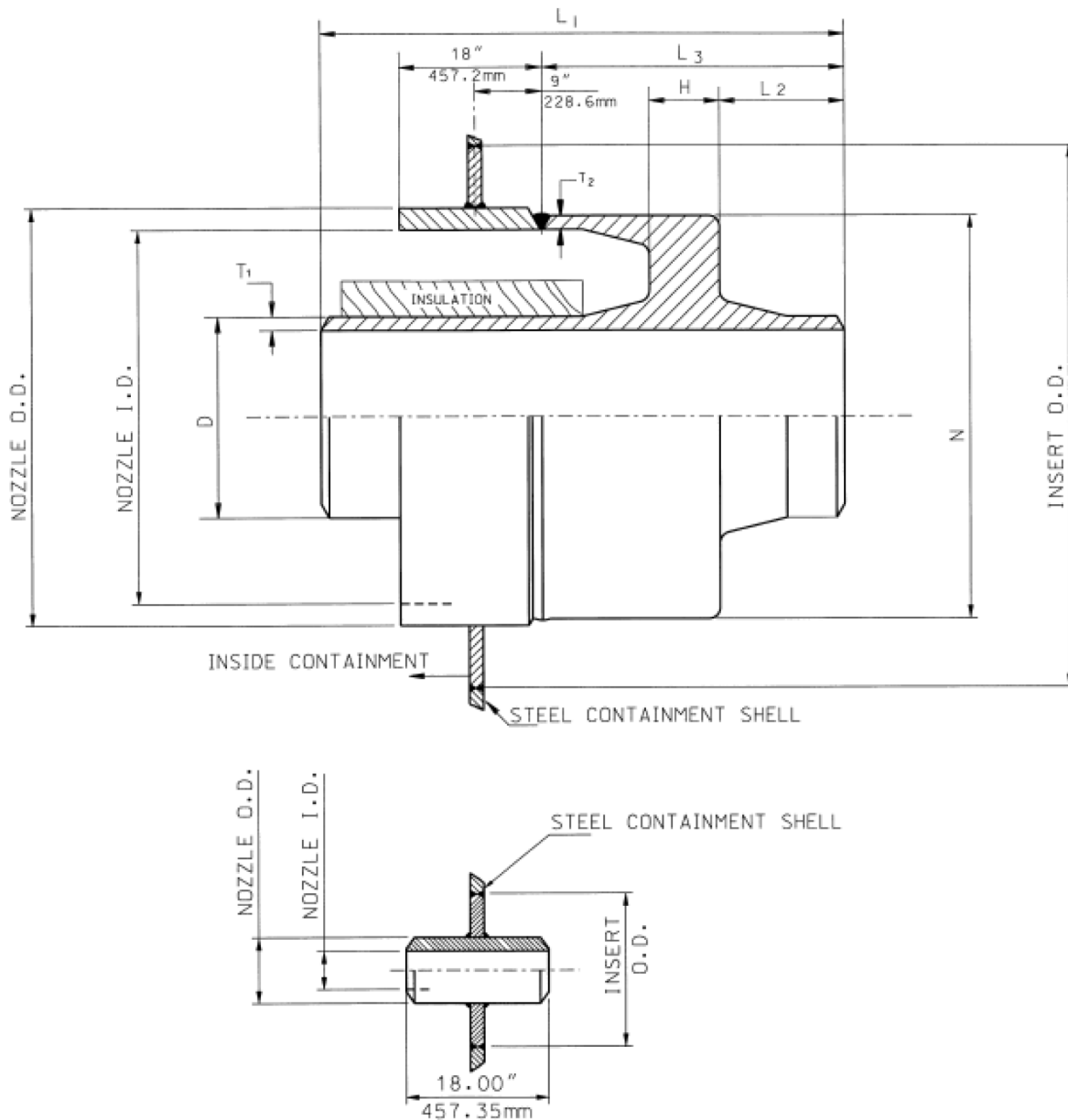
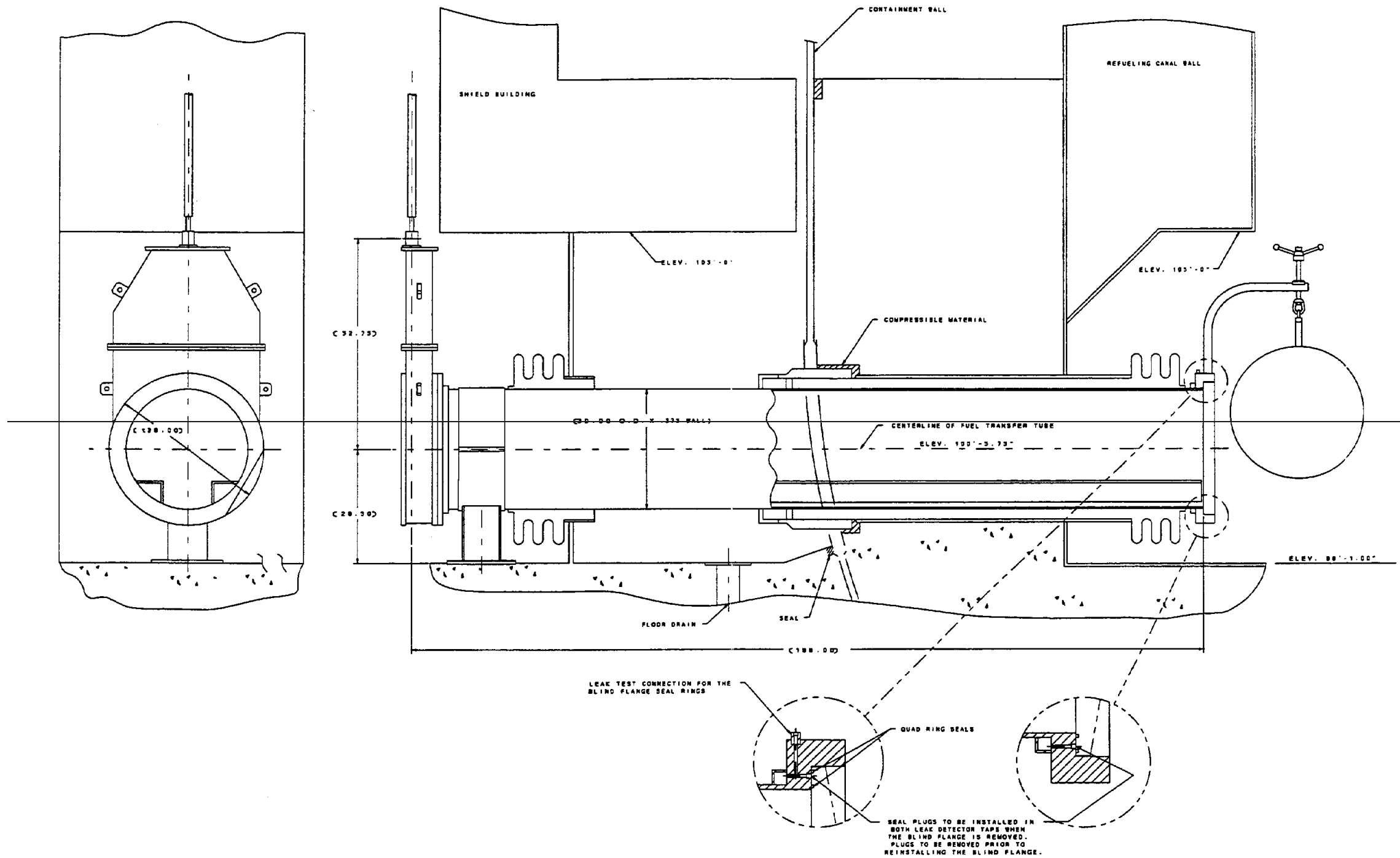


Figure 3.8.2-4 (Sheet 4 of 6)

Containment Penetrations



NRC 044

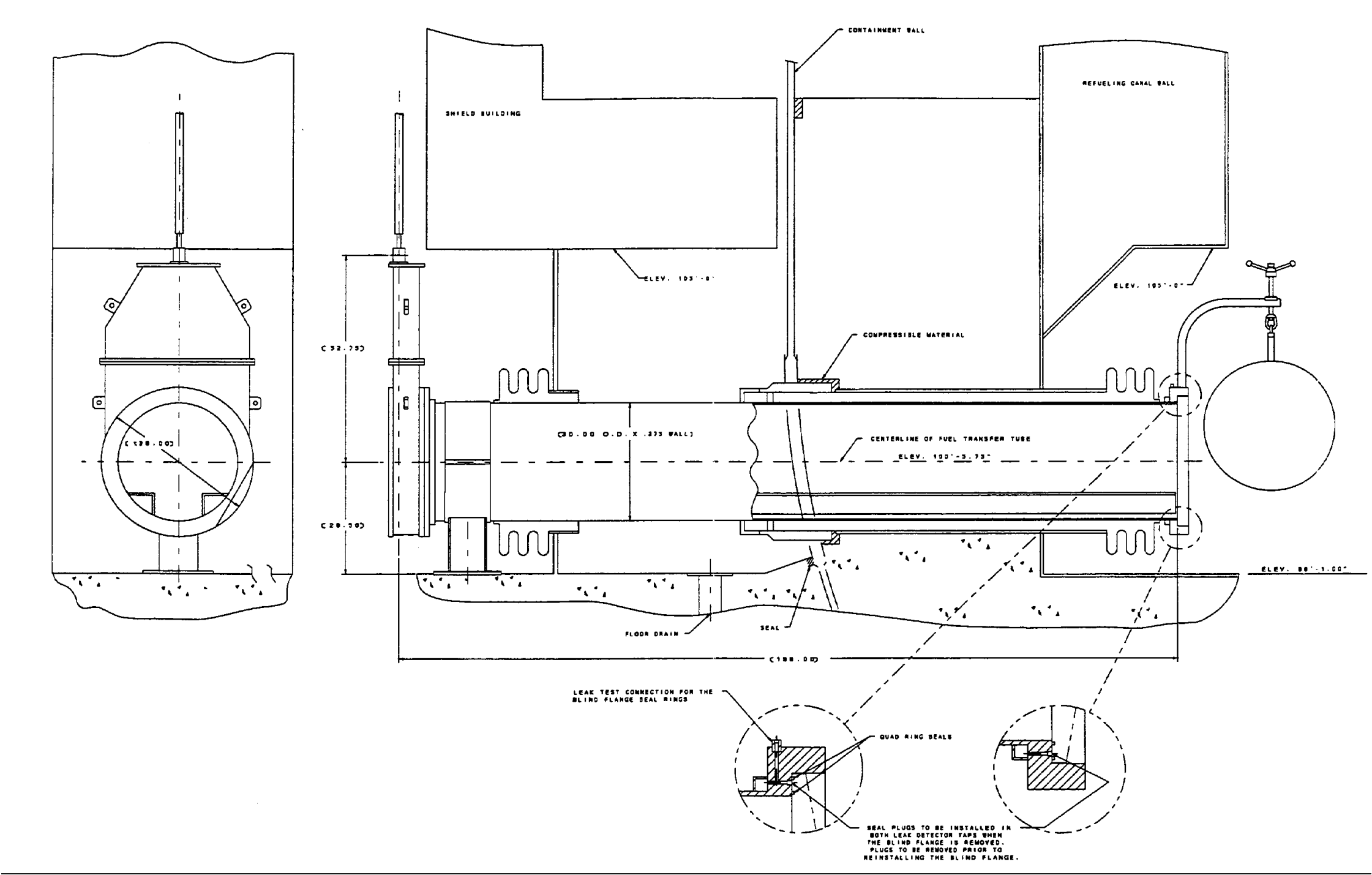
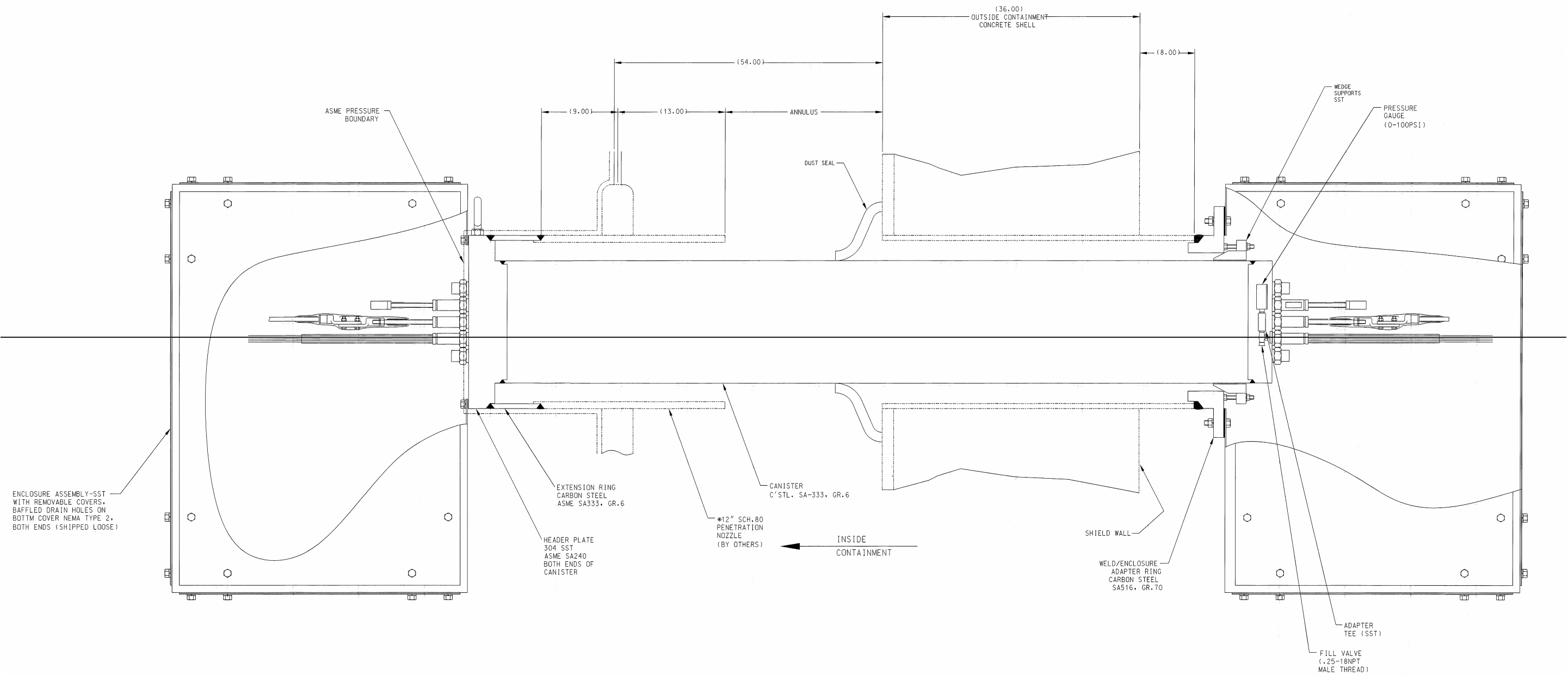


Figure 3.8.2-4 (Sheet 5 of 6)

Containment Penetrations
Fuel Transfer Penetration



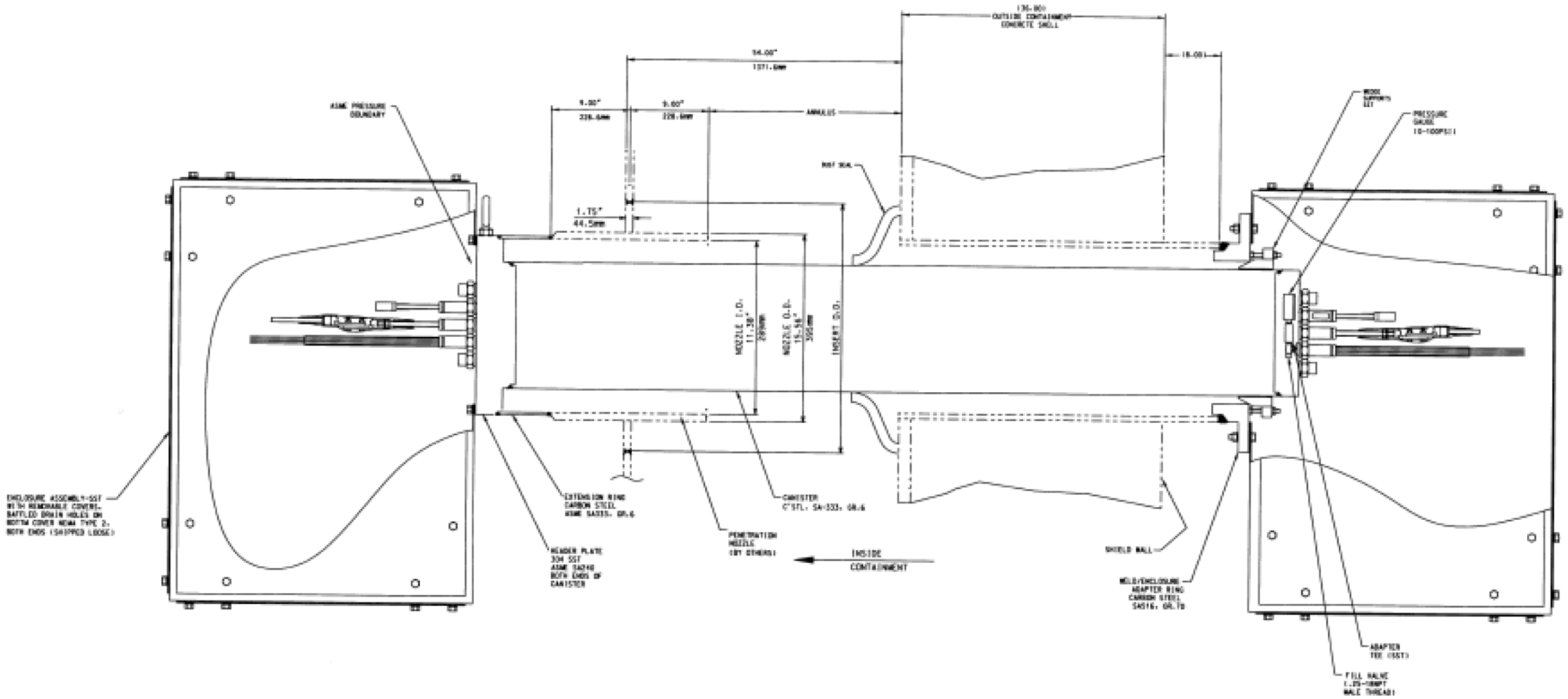
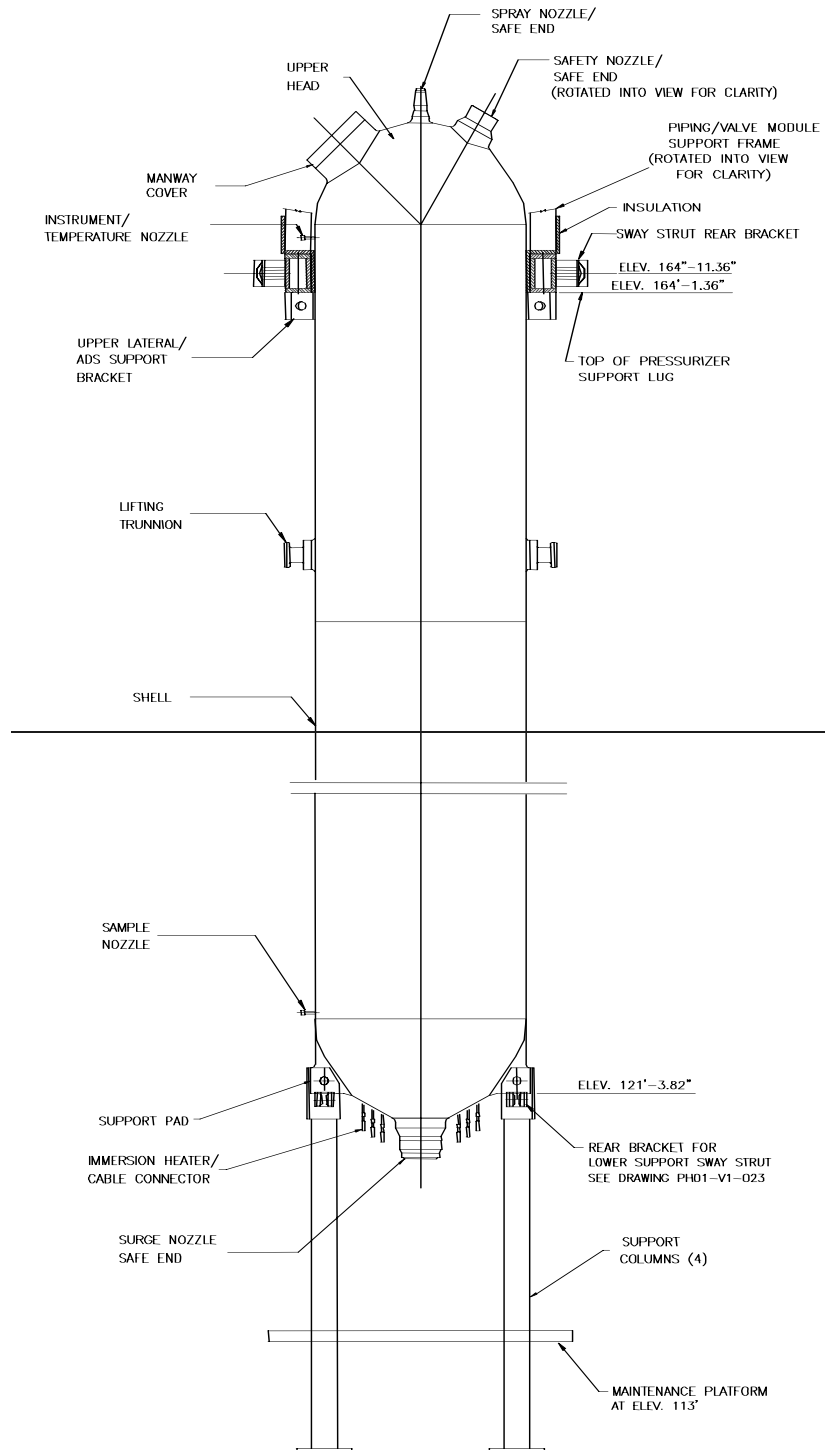
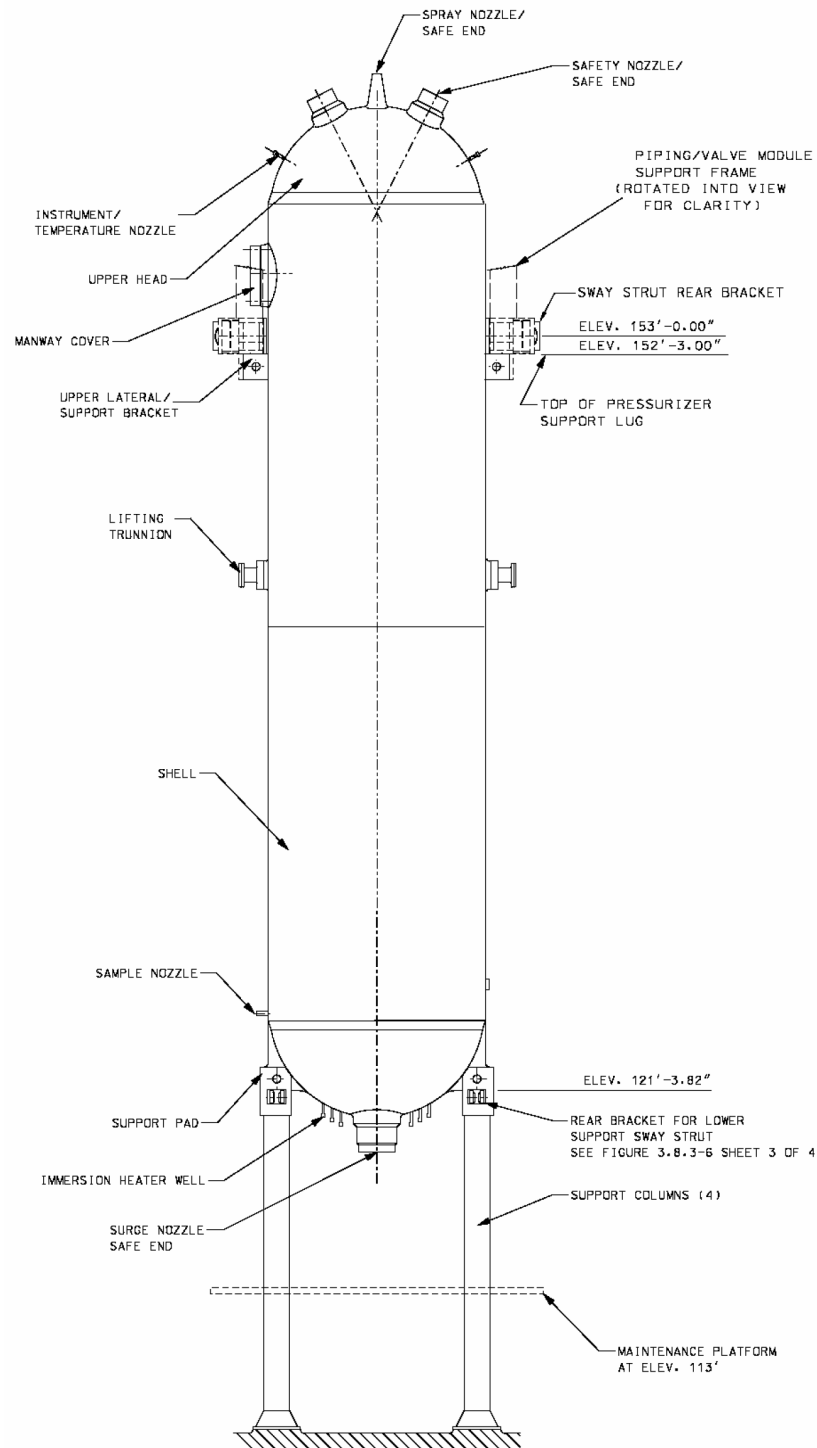


Figure 3.8.2-4 (Sheet 6 of 6)

Containment Penetrations
Typical Electrical Penetration

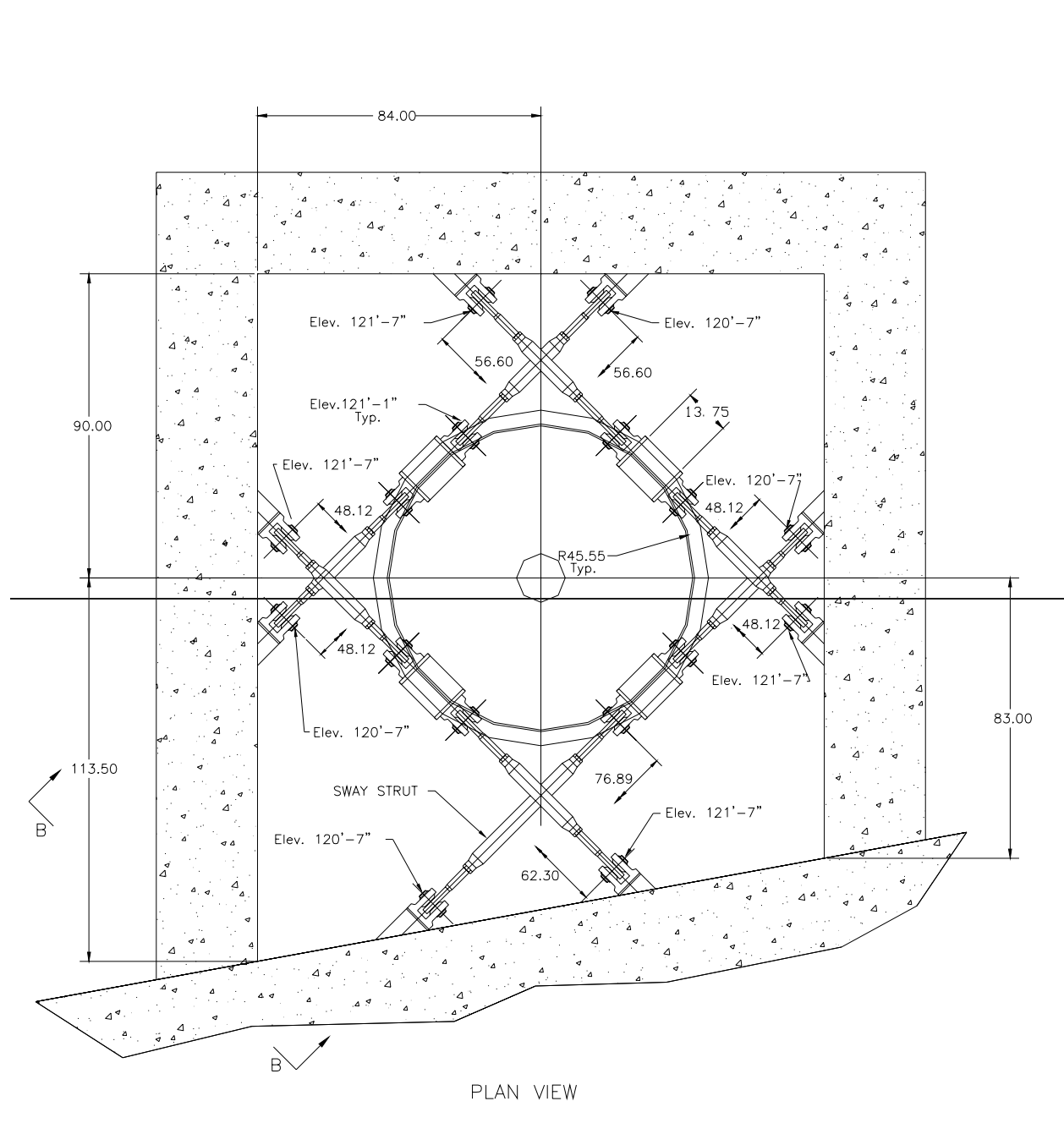




NRC 097

Figure 3.8.3-6 (Sheet 1 of 4)

Pressurizer Support Columns



NRC 097

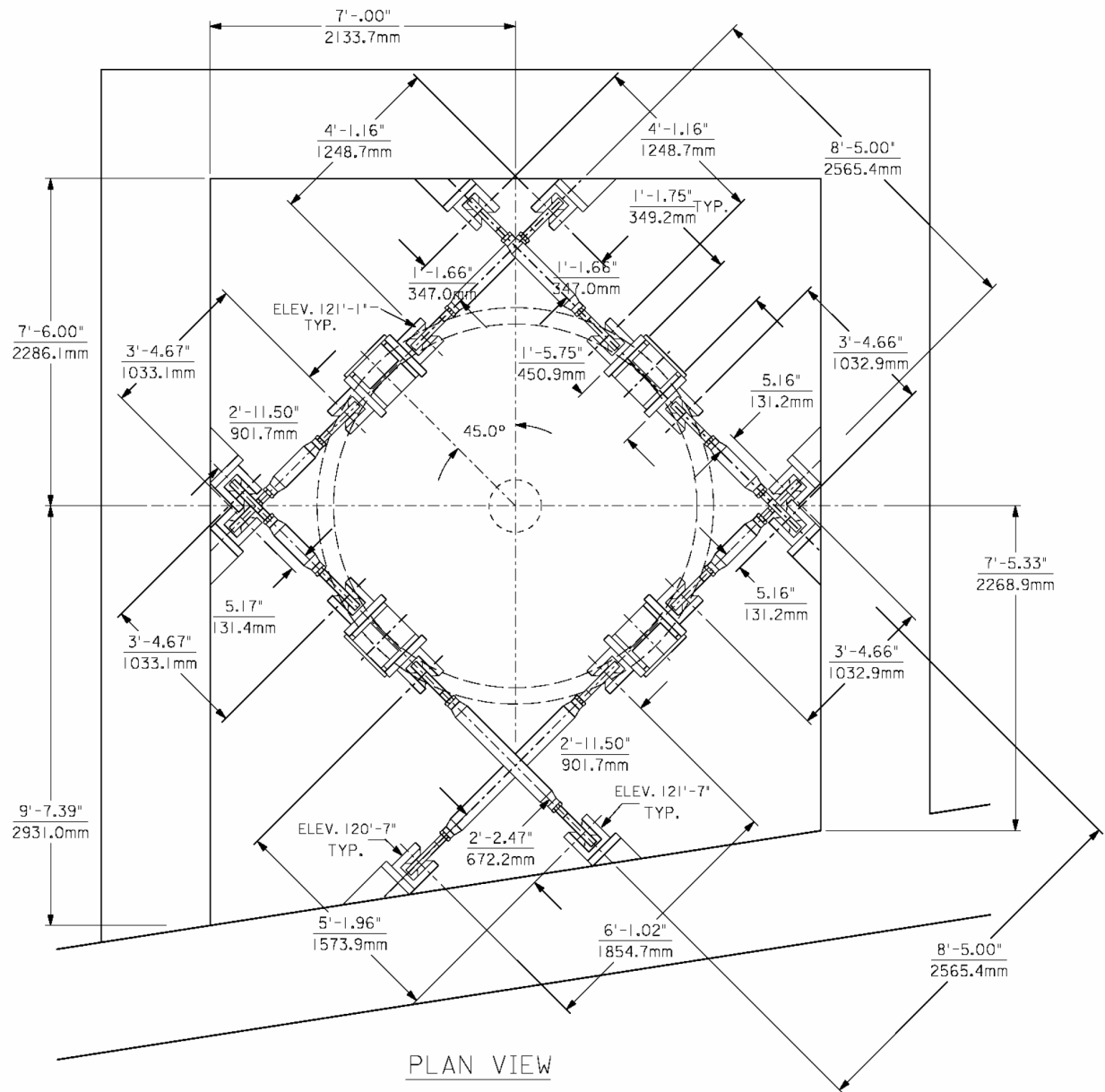
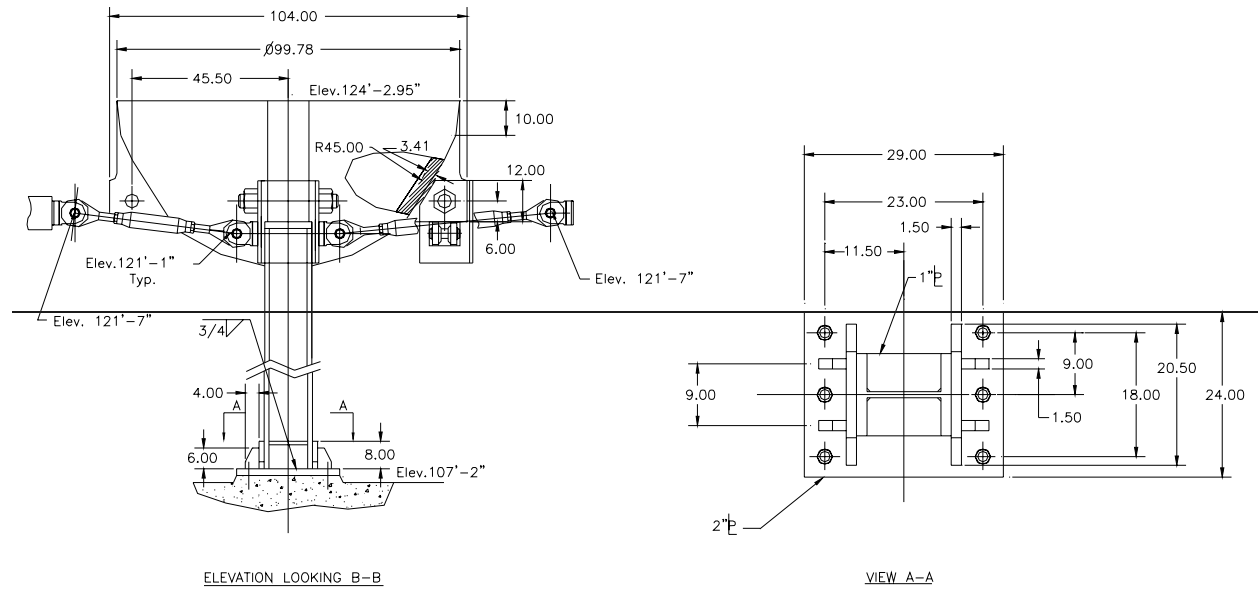


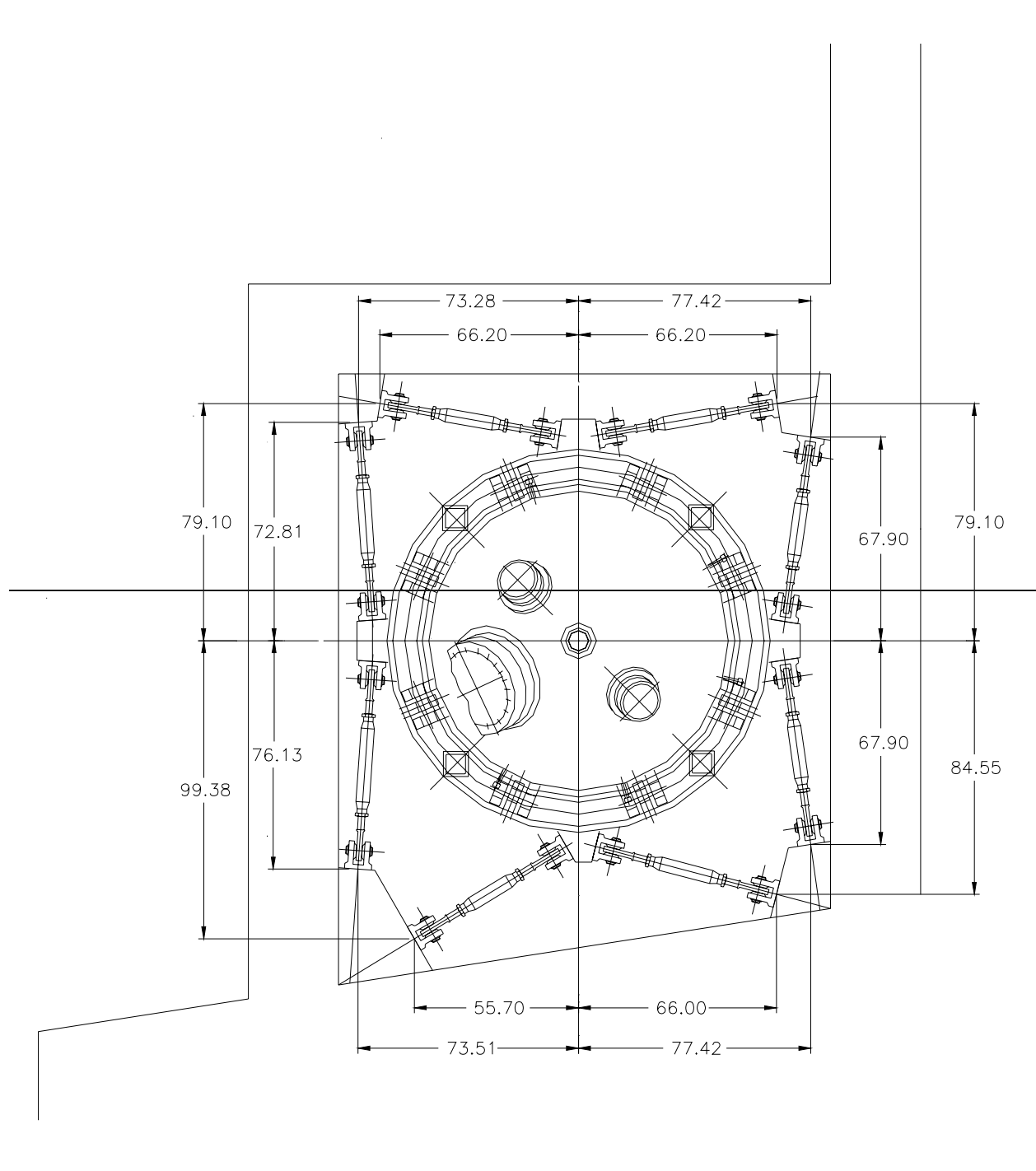
Figure 3.8.3-6 (Sheet 2 of 4)

Pressurizer Lower Lateral Supports





Pressurizer Lower Supports



NRC 097

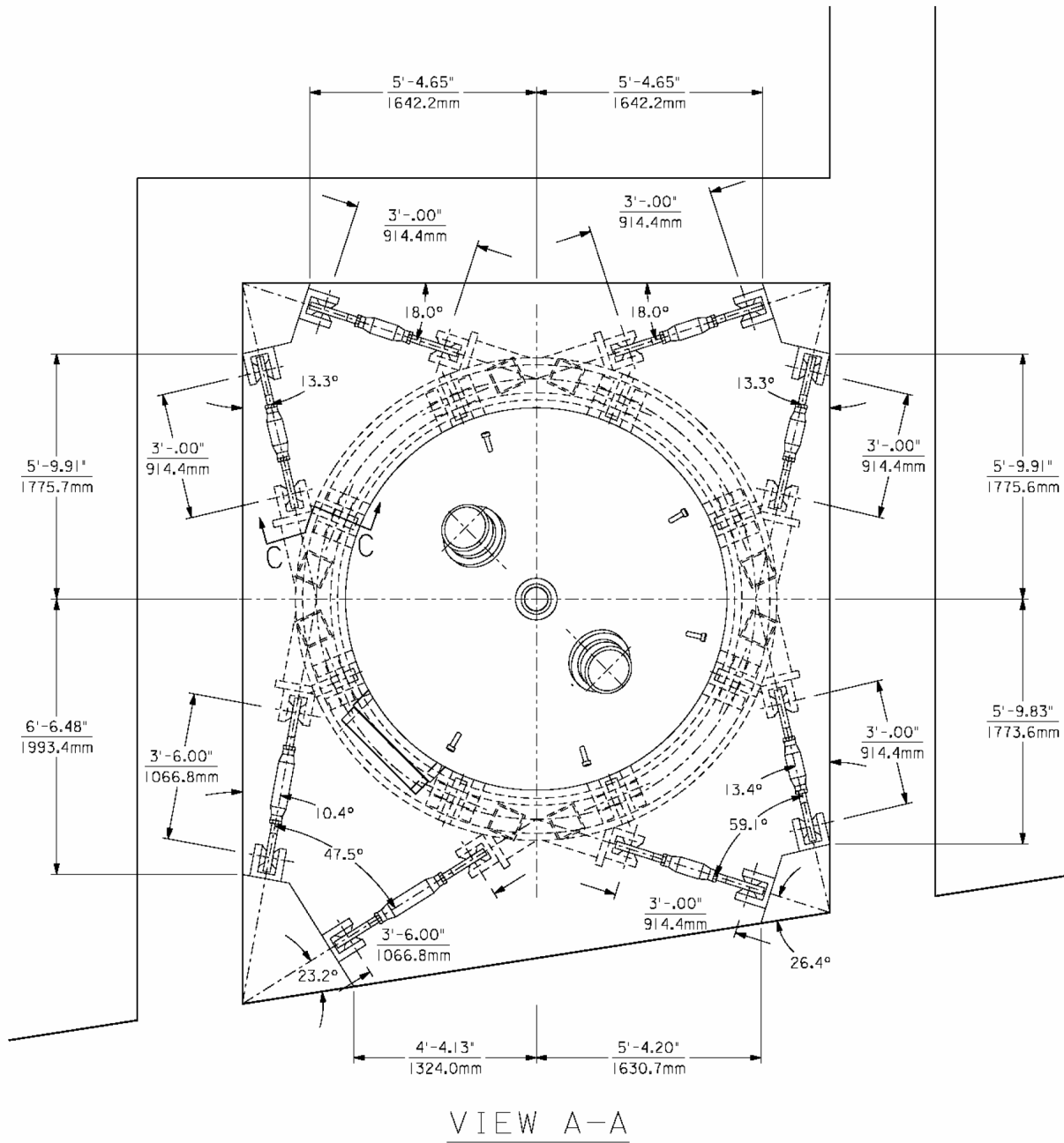


Figure 3.8.3-6 (Sheet 4 of 4)

Pressurizer Upper Supports

The production operability tests for large hydraulic snubbers (that is, those with capacities of 50 kips or greater) include 1) a full Level D load test to verify sufficient load capacity, 2) testing at full load to verify proper bleed with the control valve closed, 3) testing to verify the control valve closes within the specified velocity range, and 4) testing to demonstrate that breakaway and drag loads are within the design limits.

NRC 148

The operability of essential snubbers is verified as ~~described~~^{discussed} in subsection 3.9.3.4.4 and in the inservice testing program required by subsection 3.9.8.3 by verifying the proper installation of the snubbers, and performing visual inspections and measurements of the cold and hot positions of the snubbers as required during plant heatup to verify the snubbers are performing as intended. The ASME OM Code used to develop the inservice testing plan for the AP1000 Design Certification is the 1995 Edition and 1996 Addenda. Inservice testing is performed in accordance with Section XI of the ASME Code and applicable addenda, as required by 10 CFR 50.55a.

3.9.3.4.4 Inspection, Testing, Repair and/or Replacement of Snubbers

A program for inservice examination and testing of dynamic supports (snubbers) in the AP1000 is prepared in accordance with the requirements of ASME OM code, Subsection ISTD.

NRC 148

The inservice examination and testing includes a thermal motion monitoring program that is established for verification of snubber movement, adequate clearance and gaps, including motion measurements and acceptance criteria to assure compliance with ASME Section III, Subsection NF.

The inservice examination and testing plan for applicable snubbers is prepared in accordance with the requirements of the ASME OM Code, Subsection ISTD. Snubber maintenance, repairs, replacements and modifications are performed in accordance with the requirements of the ASME OM Code, Subsection ISTD. Details of the inservice examination and testing program, including test schedules and frequencies, are reported in the inservice inspection and testing plan included in the inservice testing program required by Subsection 3.9.8.3

3.9.3.5 Instrumentation Line Supports

*[The design loads, load combinations, and acceptance criteria for safety-related instrumentation supports are similar to those of pipe supports. Design loads include deadweight, thermal, and seismic (as appropriate). The acceptance criteria is ASME Subsection NF.]**

3.9.4 Control Rod Drive System (CRDS)

3.9.4.1 Descriptive Information of CRDS

3.9.4.1.1 Control Rod Drive Mechanism (CRDM)

The AP1000 control rod drive mechanism is based on a proven Westinghouse design that has been used in many operating nuclear power plants. Figure 3.9-4 shows the control rod drive mechanism. Figure 4.2-8 shows the configuration of the driveline, including the control rod drive mechanism. Subsection 4.2.2 describes the design of the rod cluster control assemblies and gray

*NRC Staff approval is required prior to implementing a change in this information; see DCD Introduction Section 3.5.

limited to approximately 18 percent, after which a positive stop is provided. The maximum deformation of the secondary core support allows for the maintenance of flow paths through the lower portion of the vessel and lower core support to provide cooling of the fuel under forced and natural circulation conditions.

3.9.6 Inservice Testing of Pumps and Valves

NRC 148 |

Inservice testing of ASME Code, Section III, Class 1, 2, and 3 pumps and valves is performed in accordance with ~~Section XI~~ of the ASME Operations and Maintenance (OM) Code and applicable addenda, as required by 10 CFR 50.55a(f), except where specific relief has been granted by the NRC in accordance with 10 CFR 50.55a(f). The Code includes requirements for leak tests and functional tests for active components.

The requirements for system pressure tests are defined in the ASME Code, Section XI, IWA-5000. These tests verify the pressure boundary integrity and are part of the inservice inspection program, not part of the inservice test program.

Testing requirements for components constructed to the ASME Code are in several parts of the ASME OM Code (Reference 2). The ASME OM Code used to develop the inservice testing plan for the AP1000 Design Certification is the 1995 Edition and 1996 Addenda. The edition and addenda to be used for the inservice testing program are administratively controlled as described in subsection 3.9.8. A limited number of valves not constructed to the ASME Code are also included in the inservice testing plan using the requirements of the ASME OM Code. These valves are relied on in some safety analyses.

The specific ASME Code requirements for functional testing of pumps are found in the ASME OM Code, Subsection ISTB. The specific ASME Code requirements for functional testing of valves are found in the ASME OM Code, Subsection ISTC. The functional tests are required for pumps and valves that have an active safety-related function.

The AP1000 inservice test plan does not include testing of pumps and valves in nonsafety-related systems unless they perform safety-related missions, such as containment isolation. Subsection 16.3.1 describes the evaluation of the importance of nonsafety-related systems, structures and components. Fluid systems with important missions are shown to be available by operation of the system.

NRC 148 |

The AP1000 inservice test plan includes periodic systems level tests and inspections that demonstrate the capability of safety-related features to perform their safety-related functions such as passing flow or transferring heat. For this system level testing, ~~t~~The test and inspection frequency is once every 10 years. Staggering of the tests of redundant components is not required. These tests may be performed in conjunction with inservice tests conducted to exercise check valves or to perform power-operated valve operability tests. Alternate means of performing these tests and inspections that provide equivalent demonstration may be developed in the inservice test program as described in subsection 3.9.8. Table 3.9-17 identifies the system level ~~inservice~~ tests. The system level testing is not governed by the ASME OM Code.

NRC 148 |

NRC 148 |

A preservice test program, which identifies the required functional testing, is to be submitted to the NRC prior to performing the tests and following the start of construction as discussed in subsection 3.9.8. The inservice test program, which identifies requirements for functional testing, is to be submitted to the NRC prior to the anticipated date of commercial operation as described in subsection 3.9.8. Table 3.9-16 identifies the components subject to the preservice and the inservice test program. This table also identifies the method, ~~extent~~, and frequency of preservice and inservice testing.

3.9.6.1 Inservice Testing of Pumps

Safety-related pumps are subject to operational readiness testing. The only safety-related mission performed by an AP1000 pump is the coast down of the reactor coolant pumps. As a result, the AP1000 inservice test plan does not include any pumps.

The AP1000 inservice test plan does not include testing of pumps in nonsafety-related systems unless they perform safety-related missions. Systems containing pumps with important missions have the capability during operation to measure the flow rate, the pump head, and pump vibration to confirm availability of the pumps. These measurements may be made with temporary instruments or test devices. The AP1000 inservice test plan does not include testing of nonsafety-related pumps because they do not perform safety-related missions.

3.9.6.2 Inservice Testing of Valves

Safety-related valves and other selected valves are subject to operational readiness testing. Inservice testing of valves assesses operational readiness including actuating and position indicating systems. The valves that are subject to inservice testing include those valves that perform a specific function in shutting down the reactor to a safe shutdown condition, in maintaining a safe shutdown condition, or in mitigating the consequences of an accident. The AP1000 safe shutdown condition includes conditions other than the cold shutdown mode. Safe shutdown conditions are discussed in subsection 7.4.1. In addition, pressure relief devices used for protecting systems or portions of systems that perform a function in shutting down the reactor to a safe shutdown condition, in maintaining a safe shutdown condition, or in mitigating the consequences of an accident, are subject to inservice testing.

The AP1000 inservice test plan does not include testing of nonsafety-related valves except where they perform safety-related missions. Valves that are identified as having important nonsafety-related missions have provisions to allow testing but are not included in the inservice test plan unless inservice testing is identified as part of the regulatory oversight required for investment protection (see Section 16.3). This testing may use temporary instruments or test devices.

The valve test program is controlled administratively by the Combined License holder and is based on the plan outlined in this subsection. Valves (including relief valves) subject to inservice testing in accordance with the ASME Code are indicated in Table 3.9-16. This table includes the type of testing to be performed and the frequency at which the testing should be performed. The test program conforms to the requirements of ASME OM, Subsection ISTC, to the extent practical. The guidance in NRC Generic Letters, AEOD reports, and industry and utility guidelines (including NRC Generic Letter 89-04) is also considered in developing the test

NRC 148

program. Inservice testing incorporates the use of nonintrusive techniques to periodically assess degradation and performance of selected valves. The testing of power operated valves utilizes guidance from Generic Letter 96-05 and the Joint Owners Group (JOG) MOV Periodic Verification (PV) study, MPR 2524-A (November 2006). During the inservice testing period the following are performed to demonstrate the acceptability of the functional performance of power operated valves other than motor-operated valves; (1) periodically assess the diagnostic methods used in the verification for valve function; and (2) evaluation of lessons learned through other related programs such as MOV Generic Letter (GL) 89-10 and (96-05 Programs.

Safety-related check valves with ~~an active-safety function to open~~ or with a safety function to close or remain closed to prevent reverse flow are exercised to both the open and closed positions regardless of safety function position in accordance with the ASME OM Code in response to flow. Safety-related power-operated valves with an active function are subject to an exercise test and an operability test. The operability test may be either a static or a dynamic (flow and differential pressure) test. Refer to subsection 3.9.6.2.1 for additional information.

NRC 148

Relief from the requirements for testing is discussed in Section 3.9.6.3. ~~If required, and~~ the alternative to the tests are justified and documented in DCD Table 3.9-16.

3.9.6.2.1 Valve Functions Tested

The AP1000 inservice testing program plan identifies the safety-related missions for safety-related valves for the AP1000 systems. The following safety-related valve missions have been identified in Table 3.9-16.

- Maintain closed
- Maintain open
- Transfer closed (active function)
- Transfer open (active function)
- Throttle flow (active function)

NRC 148

Based on the safety-related missions identified for each valve, the inservice tests to confirm the capability of the valve to perform these missions are identified. Active valves include valves that transfer open, transfer closed, and/or have throttling missions. Active valves, as defined in the ASME Code, include valves that change obturator (the part of the valve that blocks the flow stream) position to accomplish the safety-related function(s). Valve missions to maintain closed and maintain open are designated as passive and do not include valve exercise inservice testing. Although the throttling function is included in the AP1000 inservice testing program, testing of throttling (pressure regulation) is not required in the ASME OM Code.

NRC 148

If upon removal of the actuation power (electrical power, air or fluid for actuation) an active valve fails to the position associated with performing its safety-related function, it is identified as “active-to-fail” in Table 3.9-16. The ‘fail-safe’ test is not specifically identified; this function is tested as part of the exercise test.

NRC 148	<p>Valve <u>and actuator characteristics and functions</u> are used in determining the type of inservice testing for the valve. These valve functions include:</p> <ul style="list-style-type: none"> • Active or active-to-fail for fulfillment of the safety-related mission(s) • Reactor coolant system pressure boundary isolation function • Containment isolation function • Seat leakage (in the closed position), is limited to a specific maximum amount when important for fulfillment of the safety-related mission(s) • Actuators that fail to a specific position (open/closed) upon loss of actuating power for fulfillment of the safety-related mission(s) • Safety-related remote position indication <p>The ASME inservice testing categories are assigned based on the safety-related valve functions and the valve characteristics. The following criteria are used in assigning the ASME inservice testing categories to the AP1000 valves.</p>
NRC 148	<p>Category A – safety-related valves with safety-related seat leakage requirements (<u>valves for which seat leakage is limited to a specific maximum amount in the closed position for fulfillment of their required function(s)</u>)</p>
NRC 148	<p>Category B – safety-related valves requiring inservice testing, but without safety-related seat leakage requirements (<u>valves for which seat leakage in the closed position is inconsequential for fulfillment of the required function(s)</u>)</p>
NRC 148	<p>Category C – safety-related, self-actuated valves (such as check valves and pressure relief valves) (<u>valves that are self-actuating in response to some system characteristic, such as pressure (relief valves) or flow direction (check valves) for fulfillment of the required function(s)</u>)</p>
NRC 148	<p>Category D – safety-related, explosively actuated valves and nonreclosing pressure relief devices (<u>valves that are actuated by an energy source capable of only on operation, such as rupture disks or explosively actuated valves</u>)</p>

3.9.6.2.2 Valve Testing

Four basic groups of inservice tests have been identified for the AP1000. These testing groups are described below.

Remote Valve Position Indication Inservice Tests

Valves that are included in the inservice testing program that have position indication will be observed locally during valve exercising to verify proper operation of the position indication. The

NRC 148 | frequency for this position indication test is once every two years, unless otherwise justified.
NRC 148 | Where local observation is not practicable, other methods will be used for verification of valve
position indicator operation. The alternate method and justification are provided in Table 3.9-16.
Position indication testing requirements for passive valves is identified in Table 3.9-16.

Valve Leakage Inservice Tests

Valves with safety-related seat leakage limits will be tested to verify their seat leakage. These valves include:

- Containment Isolation - valves that provide isolation of piping/lines that penetrate the containment.

NRC 148 | Containment isolation valves are tested in accordance with 10 CFR 50, Appendix J. Depending on
the function and configuration, some valves are tested during the integrated leak rate testing
(Type A) or individually as a part of the Type C testing or both. The leak rate test frequency for
containment isolation valves is defined in subsection 6.2.5. The provisions in 10 CFR 50.55a (b) 2
that require leakage limits and corrective actions for individual containment isolation valves by
reference to ASME/ANSI OM, ISTC, which addresses the corrective actions to be taken following
the measured inability of a valve to meet its leakage criteria. ~~Part 10~~ apply to the AP1000
containment isolation valves. ~~Changes to these provisions are discussed in subsection 3.9.8.~~

NRC 148 | The ASME Code specifies a test frequency for other than containment isolation valves of at least
once every 2 years. The ASME Code does not require additional leak testing for valves that
demonstrate operability during the course of plant operation. In such cases, the acceptability of the
valve performance is recorded during plant operation to satisfy inservice testing requirements.
Therefore, a specific inservice test need not be performed on valves that meet this criteria. The
AP1000 maximum leakage requirement for pressure isolation valves that provide isolation
between high and low pressure systems is included in the surveillance requirements for Technical
Specification 3.4.156. The pressure isolation valves that require leakage testing are tabulated in
Table 3.9-18.

The AP1000 has no temperature isolation valves whose leakage may cause unacceptable thermal loading to piping or supports.

Manual/Power-Operated Valve Tests

NRC 148 | **Manual/Power-Operated Valve Exercise Tests** - Safety-related active valves and other selected
active valves, both manual- and power-operated (motor-operated, air-operated,
hydraulically operated, solenoid-operated) will be exercised periodically. The ASME code
specifies a quarterly valve exercise frequency for power-operated valves. Active manual valves are
exercised once every two years in accordance with 10 CFR 50.55a(b)(3)(iv). The AP1000 test
frequencies are identified in Table 3.9-16.

NRC 148 | In some cases, the valves are tested on a less frequent basis because it is not practicable to exercise
the valve during plant operation. If ~~an exception is taken to performing~~ quarterly full-stroke
exercise testing of a valve is not practicable, then full-stroke testing will be performed during cold

shutdowns on a frequency not more often than quarterly. If this is not practicable, then the full-stroke testing will be performed each refueling cycle.

The inservice testing requirement for measuring stroke time for valves in the AP1000 will be completed in conjunction with a valve exercise inservice test. The stroke time test is not identified as a separate inservice test.

Valves that operate during the course of normal plant operation at a frequency that satisfies the exercising requirement need not be additionally exercised, provided that the observations required of inservice testing are made and recorded at intervals no greater than that specified in this section.

Safety-related valves that fail to the safety-related actuation position to perform the safety-related missions, are subject to a valve exercise inservice test. The test verifies that the valve repositions to the safety-related position on loss of actuator power. The valve exercise test satisfies this test as long as the test removes actuator power for the valve. The fail-safe test is not identified as a separate test in Table 3.9-16.

Power-Operated Valve Operability Tests - The inservice operability testing of power-operated valves rely on non-intrusive diagnostic techniques to permit periodic assessment of valve operability at design basis conditions. Operability testing as required by 10 CFR 50.55a(b)(3)(ii) is performed on motor-operated valves (MOV)s that are included in the ASME OM Code inservice testing program to demonstrate that the MOVs are capable of performing their design basis safety function(s). Table 3.9-16 identifies valves that may require valve operability testing. The specified frequency for operability testing is a maximum of once every 10 years. The initial test frequency is the longer of every 3 refueling cycles or 5 years until sufficient data exists to determine a longer test frequency is appropriate in accordance with Generic Letter 96-05.

Static testing with diagnostic measurements will be performed on these valves. The specific frequency for operability testing will be based on the risk ranking and the functional margin of the individual valve with a maximum test frequency of once every 10 years. The factors below are used to determine the risk ranking and functional margin. See subsection 3.9.8.4 for a discussion on developing the inservice test program, which will also include analysis of trends of valve test parameters resulting from the valve operability.

- Risk Ranking

The risk ranking shall consist of calculating the at-power risk importance, developing component ranking worksheets, and conducting an expert panel review.

- Functional Margin

The functional margin will be determined considering the valve design features, material of construction, operating parameters, actuator capability, and uncertainties. The uncertainties shall consider degradations, and variations of diagnostic measurements and control logic.

Valves for which functional margins have not been determined – due to the use of different valve design features, materials of construction, operating parameters, actuator capability, and other

uncertainties – may require dynamic testing (differential pressure testing) to determine the appropriate margins.

Check Valve Tests

NRC 148

Check Valve Exercise Flow Tests - Safety-related check valves identified with specific safety-related missions to transfer open or transfer closed or maintain close are tested periodically. ~~Exercising a check valve confirms the valve capability to move to the position(s) to fulfill the safety-related mission(s). Category C check valves are exercised to both the open and closed positions regardless of safety function position in accordance with ASME OM Code ISTC. The exercise test shows that the check valve opens in response to flow and closes when the flow is stopped. Sufficient flow is provided to fully open the check valve unless the maximum accident flows are not sufficient to fully open the check valve. Either permanently or temporarily installed nonintrusive check valve indication is used for this test. During the exercise test, valve obturator position is verified by direct measurements using nonintrusive devices or by other positive means (i.e., changes in system pressure, temperature, flow rate, level, seat leakage or nonintrusive tests results). Valves that can not be checked using a flow test may use other means to exercise the valve to the open and closed position.~~

NRC 148

Valves that normally operate at a frequency that satisfies the exercising requirement need not be additionally exercised, provided that the observations required of inservice testing are made and recorded at intervals no greater than that specified in this section.

NRC 148

The ASME Code specifies a quarterly valve exercise frequency. The AP1000 test frequencies are identified in Table 3.9-16. In some cases, check valves are tested on a less frequent basis because it is not practical to exercise the valve during plant operation. ~~If an exception is taken to performing quarterly exercise testing is not practicable,~~ then exercise testing is performed during cold shutdown on a frequency not more often than quarterly. If this is not practical, the exercise testing is performed during each refueling

NRC 148

outage. If exercise testing during a refueling outage is not practical, then an ~~alternative~~ another means is provided. ~~Alternative~~ Other means include nonintrusive diagnostic techniques or valve disassembly and inspection.

Check Valve Low Differential Pressure Tests - Safety-related check valves that perform a safety-related mission to transfer open under low differential pressure conditions have periodic inservice testing to verify the capability of the valve to initiate flow.

The intent of this inservice test is to determine the pressure required to initiate flow. This differential pressure will verify that the valve will initiate flow at low differential pressure. This low pressure differential inservice test is performed in addition to exercise inservice tests.

The specified frequency for this inservice test is once each refueling cycle.

Other Valve Inservice Tests

Explosively Actuated Valves - Explosively actuated valves are subject to periodic test firing of the explosive actuator charges. The inservice tests for these valves is specified in the ASME code.

At least 20 percent of the charges installed in the plant in explosively actuated valves are fired and replaced at least once every 2 years. If a charge fails to fire, all charges with the same batch number are removed, discarded, and replaced with charges from a different batch. The firing of the explosive charge may be performed inside of the valve or outside of the valve in a test fixture. The maintenance and review of the service life for charges in explosively actuated valves follow the requirements in the ASME OM Code.

Pressure/Vacuum Relief Devices - Pressure relief devices that provide safety-related functions or that protect equipment in systems that perform AP1000 safety-related missions are specified by ASME to have periodic inservice testing. The inservice tests for these valves are identified in ASME IST, Appendix I.

The periodic inservice testing include visual inspection, seat tightness determination, set pressure determination, and operational determination of balancing devices, alarms, and position indication as appropriate. The frequencies for this inservice test is every 5 years for ASME Class 1 and main steam line safety valve or every 10 years for ASME Classes 2 and 3 devices. Nonreclosing pressure relief devices are inspected when installed and replaced every 5 years unless historical data indicate a requirement for more frequent replacement.

3.9.6.2.3 Valve Disassembly and Inspection

~~Section 3.9.8 discusses developing a~~ The program for periodic check valve disassembly and inspection ~~includes Evaluation of the factors below will to~~ determine which of the valves identified in the inservice testing program in Table 3.9-16 ~~will require~~ disassembly and inspection and the frequency of the inspection. If the test methods in ISTC-5221(a) and ISTC-5521(b) are impractical for certain check valves, or if sufficient flow cannot be achieved or verified, a sample disassembly examination program shall be used to verify valve obturator movement. The sample disassembly examination program shall group check valves of similar design, application, and service condition and require a periodic examination of one valve from each group.

Disassembly and inspection of other types of valves will be performed based on information from inservice testing, or other program requirements, as noted below:

- AP1000 PRA importance measures.
- Design reliability assurance program contained in DCD Section 16.2.
- Historical performance of power-operated valves (identify valve types which experience unacceptable degradation in service.)
- Basic design of valves including the use of components subject to aging and requiring periodic replacement.
- Analysis of trends of valve test parameters during valve inservice tests.
- Results of nonintrusive techniques. Disassembly and inspection may not be needed if nonintrusive techniques are sufficient to detect unacceptable valve degradation.

3.9.6.3 Relief Requests

NRC 148 | Considerable experience has been used in designing and locating systems and valves to permit preservice and inservice testing required by ~~Section XI~~ of the ASME OM Code. Deferral of testing to cold shutdown or refueling outages in conformance with the rules of the ASME OM Code when testing during power operation is not practical is not considered a relief request. Relief from the testing requirements of the ASME OM Code will be requested when full compliance with requirements of the ASME OM Code ~~of the Code~~ is not practical. In such cases, specific information will be provided which identifies the applicable code requirements, justification for the relief request, and the testing method to be used as an alternative.

NRC 148 |

3.9.7 Integrated Head Package

The integrated head package (IHP) combines several components in one assembly to simplify refueling the reactor. Figure 3.9-7 illustrates the integrated head package. The integrated head package includes a lifting rig, seismic restraints for control rod drive mechanisms, support for reactor head vent piping, power cables, cables and guide tubes for in-core instrumentation, cable supports and shroud assembly.

The integrated head package provides the ability to rapidly disconnect cables, including the CRDM power cables, digital rod position indication cables, and in-core instrument cables from the components. The integrated head package also provides the ability to rapidly disconnect the reactor head vent system.

The integrated head package provides the ability to move these components as an assembly to permit their lifting and removal with the reactor vessel head. In addition, the integrated head package provides support for the vessel head stud tensioner/detensioner during refueling.

The lifting rig function is discussed in subsection 9.1.5. The control rod drive mechanisms are discussed in subsection 3.9.4. The control rod drive mechanism support and cooling function is discussed in Section 4.6. The reactor vessel head vent function is discussed in subsection 5.4.12. The function and requirements of the in-core instrumentation are discussed in Chapter 7.

3.9.7.1 Design Bases

Components, including the shroud and control rod drive mechanism seismic support plate, required to provide seismic restraint for the control rod drive mechanisms and the valves and piping of the reactor head vent are AP1000 equipment Class C, seismic Category I. The shroud and seismic support plate are designed in accordance with the ASME Code, Section III, Subsection NF requirements.

The loads and loading combinations due to seismic loads for these components are developed using the appropriate seismic spectra.

The structural design of the integrated head package is based on a design temperature consistent with the heat loads from the vessel head, the control rod drive mechanisms, and electrical power cables. The design also considers changes in temperature resulting from plant design transients and loss of power to the cooling fans.

Table 3.9-16 (Sheet 1 of 21)								
VALVE INSERVICE TEST REQUIREMENTS								
NRC 148	Valve Tag Number	Description ⁽¹⁾	Valve/Actuator Type	Safety-Related Missions	Safety Functions ⁽²⁾	ASME Class/IST Category	Inservice Testing Type and Frequency	IST Notes
NRC 148	CAS-PL-V014	Instrument Air Supply Outside Containment Isolation	Remote <u>AO Butterfly</u>	Maintain Close Transfer Close	Active-to-Failed Containment Isolation Safety Seat Leakage Remote Position	<u>Class 2</u> <u>Category A</u>	Remote Position Indication, Exercise/2 Years Containment Isolation Leak Test Exercise Full Stroke/Refueling Shutdown Operability Test	18, 27, 31
NRC 148	CAS-PL-V015	Instrument Air Supply Inside Containment Isolation	Check	Maintain Close Transfer Close	Active Containment Isolation Safety Seat Leakage	<u>Class 2</u> <u>Category AC</u>	Containment Isolation Leak Test Check Exercise/Refueling Shutdown	18, 27
NRC 148	CAS-PL-V204	Service Air Supply Outside Containment Isolation	Manual	Maintain Close	Containment Isolation Safety Seat Leakage	<u>Class 2</u> <u>Category A</u>	Containment Isolation Leak Test	27
	CAS-PL-V205	Service Air Supply Inside Containment Isolation	Check	Maintain Close	Containment Isolation Safety Seat Leakage	<u>Class 2</u> <u>Category AC</u>	Containment Isolation Leak Test	27
	CCS-PL-V200	CCS Containment Isolation Valve - Inlet Line ORC	Remote <u>MO Butterfly</u>	Maintain Close Transfer Close	Active Containment Isolation Safety Seat Leakage Remote Position	<u>Class 2</u> <u>Category A</u>	Remote Position Indication, Exercise/2 Years Containment Isolation Leak Test Exercise Full Stroke/Cold Shutdown Operability Test	14, 27, 31
NRC 148	CCS-PL-V201	CCS Containment Isolation Valve - Inlet Line IRC	Check	Maintain Close Transfer Close	Active Containment Isolation Safety Seat Leakage	<u>Class 2</u> <u>Category AC</u>	Containment Isolation Leak Test Check Exercise/Cold Shutdown	14, 27
NRC 148	CCS-PL-V207	CCS Containment Isolation Valve - Outlet Line IRC	Remote <u>MO Butterfly</u>	Maintain Close Transfer Close	Active Containment Isolation Safety Seat Leakage Remote Position	<u>Class 2</u> <u>Category A</u>	Remote Position Indication, Exercise/2 Years Containment Isolation Leak Test Exercise Full Stroke/Cold Shutdown Operability Test	14, 27, 31
NRC 148	CCS-PL-V208	CCS Containment Isolation Valve - Outlet Line ORC	Remote <u>MO Butterfly</u>	Maintain Close Transfer Close	Active Containment Isolation Safety Seat Leakage Remote Position	<u>Class 2</u> <u>Category A</u>	Remote Position Indication, Exercise/2 Years Containment Isolation Leak Test Exercise Full Stroke/Cold Shutdown Operability Test	14, 27, 31
NRC 148	CVS-PL-V001	RCS Purification Stop	Remote <u>MO GATE</u>	Maintain Close Transfer Close	Active Safety Seat Leakage Remote Position	<u>Class 1</u> <u>Category A</u>	Remote Position Indication, Exercise/2 Years RCS Isolation Leak Test/Refueling Exercise Full Stroke/Cold Shutdown Operability Test	6, 31, 32
NRC 148	CVS-PL-V002	RCS Purification Stop	Remote <u>MO GATE</u>	Maintain Close Transfer Close	Active Safety Seat Leakage Remote Position	<u>Class 1</u> <u>Category A</u>	Remote Position Indication, Exercise/2 Years RCS Isolation Leak Test/Refueling Exercise Full Stroke/Cold Shutdown Operability Test	6, 31, 32
NRC 148	CVS-PL-V003	RCS Purification Stop	Remote <u>MO GLOBE</u>	Maintain Close Transfer Close	Active Remote Position	<u>Class 3</u> <u>Category B</u>	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Cold Shutdown Operability Test	6, 31

Table 3.9-16 (Sheet 2 of 21)								
VALVE INSERVICE TEST REQUIREMENTS								
NRC 148	Valve Tag Number	Description ⁽¹⁾	Valve/Actuator Type	Safety-Related Missions	Safety Functions ⁽²⁾	ASME Class/IST Category	Inservice Testing Type and Frequency	IST Notes
NRC 148	CVS-PL-V040	Resin Flush IRC Isolation	Manual	Maintain Close	Containment Isolation Safety Seat Leakage	<u>Class 2</u> <u>Category A</u>	Containment Isolation Leak Test	27
	CVS-PL-V041	Resin Flush ORC Isolation	Manual	Maintain Close	Containment Isolation Safety Seat Leakage	<u>Class 2</u> <u>Category A</u>	Containment Isolation Leak Test	27
NRC 148	CVS-PL-V042	Flush Line Containment Isolation Relief	Relief	Maintain Close Transfer Open Transfer Close	Active Containment Isolation Safety Seat Leakage	<u>Class 2</u> <u>Category AC</u>	Containment Isolation Leak Test Class 2/3 Relief Valve Tests/10 Years and 20% in 4 Years	27
	CVS-PL-V045	Letdown Containment Isolation IRC	Remote <u>AO</u> <u>GLOBE</u>	Maintain Close Transfer Close	Active-to-Failed RCS Pressure Boundary Containment Isolation Safety Seat Leakage Remote Position	<u>Class 2</u> <u>Category A</u>	Remote Position Indication, Exercise/2 Years Containment Isolation Leak Test Exercise Full Stroke/Quarterly Operability Test	27, 31
NRC 148	CVS-PL-V047	Letdown Containment Isolation ORC	Remote <u>AO</u> <u>GLOBE</u>	Maintain Close Transfer Close	Active-to-Failed RCS Pressure Boundary Containment Isolation Safety Seat Leakage Remote Position	<u>Class 2</u> <u>Category A</u>	Remote Position Indication, Exercise/2 Years Containment Isolation Leak Test Exercise Full Stroke/Quarterly Operability Test	27, 31
NRC 148	CVS-PL-V080	RCS Purification Return Line Check Valve	Check	Maintain Close Transfer Close	Active Safety Seat Leakage	<u>Class 3</u> <u>Category AC</u>	Check Exercise/Cold Shutdown RCS Isolation Leak Test/Refueling	6, 32
	CVS-PL-V081	RCS Purification Return Line Stop Valve	<u>AO Stop</u> Check	Maintain Close Transfer Close	Active Safety Seat Leakage	<u>Class 1</u> <u>Category AC</u>	Check Exercise/Cold Shutdown RCS Isolation Leak Test/Refueling	6, 8, 32
	CVS-PL-V082	RCS Purification Return Line Check Valve	Check	Maintain Close Transfer Close	Active Safety Seat Leakage	<u>Class 1</u> <u>Category AC</u>	Check Exercise/Cold Shutdown RCS Isolation Leak Test/Refueling	6, 32
NRC 148	CVS-PL-V084	Auxiliary Pressurizer Spray Line Isolation	Remote <u>AO</u> <u>GLOBE</u>	Maintain Close Transfer Close	Active-to-Failed Safety Seat Leakage Remote Position	<u>Class 1</u> <u>Category A</u>	Remote Position Indication, Exercise/2 Years RCS Isolation Leak Test/Refueling Exercise Full Stroke/Cold Shutdown Operability Test	22, 31, 32
	CVS-PL-V085	Auxiliary Pressurizer Spray Line	Check	Maintain Close Transfer Close	Active Safety Seat Leakage	<u>Class 1</u> <u>Category AC</u>	Check Exercise/Cold Shutdown RCS Isolation Leak Test/Refueling	22, 32
	CVS-PL-V090	Makeup Line Containment Isolation	Remote <u>MO</u> <u>GATE</u>	Maintain Close Transfer Close	Active RCS Pressure Boundary Containment Isolation Safety Seat Leakage Remote Position	<u>Class 2</u> <u>Category A</u>	Remote Position Indication, Exercise/2 Years Containment Isolation Leak Test Exercise Full Stroke/Quarterly Operability Test	27, 31

Table 3.9-16 (Sheet 3 of 21)								
VALVE INSERVICE TEST REQUIREMENTS								
NRC 148	Valve Tag Number	Description ⁽¹⁾	Valve/Actuator Type	Safety-Related Missions	Safety Functions ⁽²⁾	ASME Class/IST Category	Inservice Testing Type and Frequency	IST Notes
NRC 148	CVS-PL-V091	Makeup Line Containment Isolation	Remote <u>MO GATE</u>	Maintain Close Transfer Close	Active RCS Pressure Boundary Containment Isolation Safety Seat Leakage Remote Position	<u>Class 2</u> <u>Category A</u>	Remote Position Indication, Exercise/2 Years Containment Isolation Leak Test Exercise Full Stroke/Quarterly Operability Test	27, 31
NRC 148	CVS-PL-V092	Hydrogen Addition Containment Isolation	Remote <u>AO GLOBE</u>	Maintain Close Transfer Close	Active-to-Failed RCS Pressure Boundary Containment Isolation Safety Seat Leakage Remote Position	<u>Class 2</u> <u>Category A</u>	Remote Position Indication, Exercise/2 Years Containment Isolation Leak Test Exercise Full Stroke/Quarterly Operation Operability Test	27, 31
NRC 148	CVS-PL-V094	Hydrogen Addition IRC Isolation	Check	Maintain Close Transfer Close	Active RCS Pressure Boundary Containment Isolation Safety Seat Leakage Remote Position	<u>Class 2</u> <u>Category AC</u>	Remote Position Indication, Exercise/2 Years Containment Isolation Leak Test Check Exercise/Quarterly Operation	27
NRC 148	CVS-PL-V100	Makeup Line Containment Isolation Relief	Check	Maintain Close Transfer Close Transfer Open	Active Containment Isolation Safety Seat Leakage	<u>Class 2</u> <u>Category AC</u>	Containment Isolation Leak Test/2 Years Check Exercise/Refueling Shutdown	23, 27
NRC 148	CVS-PL-V136A	Demineralized Water System Isolation	Remote <u>AO Butterfly</u>	Maintain Close Transfer Close	Active-to-Failed Remote Position	<u>Class 3</u> <u>Category B</u>	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Quarterly Operability Test	31
NRC 148	CVS-PL-V136B	Demineralized Water System Isolation	Remote <u>AO Butterfly</u>	Maintain Close Transfer Close	Active-to-Failed Remote Position	<u>Class 3</u> <u>Category B</u>	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Quarterly Operability Test	31
NRC 148	DWS-PL-V244	Demineralized Water Supply Containment Isolation - Outside	Manual	Maintain Close	Containment Isolation Safety Seat Leakage	<u>Class 2</u> <u>Category A</u>	Containment Isolation Leak Test	27
	DWS-PL-V245	Demineralized Water Supply Containment Isolation - Inside	Check	Maintain Close	Containment Isolation Safety Seat Leakage	<u>Class 2</u> <u>Category AC</u>	Containment Isolation Leak Test	27
	FPS-PL-V050	Fire Water Containment Supply Isolation	Manual	Maintain Close	Containment Isolation Safety Seat Leakage	<u>Class 2</u> <u>Category A</u>	Containment Isolation Leak Test	27
	FPS-PL-V052	Fire Water Containment Supply Isolation - Inside	Check	Maintain Close	Containment Isolation Safety Seat Leakage	<u>Class 2</u> <u>Category AC</u>	Containment Isolation Leak Test	27
	FHS-PL-V001	Fuel Transfer Tube Isolation Valve	Manual	Transfer Close Maintain Open	Active	<u>Class 3</u> <u>Category B</u>	Exercise Full Stroke/ 2 Years <u>Refueling Shutdown</u>	33, <u>37</u>

Table 3.9-16 (Sheet 4 of 21)								
VALVE INSERVICE TEST REQUIREMENTS								
NRC 148	Valve Tag Number	Description ⁽¹⁾	Valve/Actuator Type	Safety-Related Missions	Safety Functions ⁽²⁾	ASME Class/IST Category	Inservice Testing Type and Frequency	IST Notes
NRC 148	MSS-PL-V001	Turbine Bypass Control Valve	Remote <u>AO</u> <u>GLOBE</u>	Maintain Close Transfer Close	Active-to-Failed Remote Position	<u>Non Code</u> <u>Category B</u>	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Cold Shutdown Operability Test	29, 31, 34
NRC 148	MSS-PL-V002	Turbine Bypass Control Valve	Remote <u>AO</u> <u>GLOBE</u>	Maintain Close Transfer Close	Active-to-Failed Remote Position	<u>Non Code</u> <u>Category B</u>	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Cold Shutdown Operability Test	29, 31, 34
NRC 148	MSS-PL-V003	Turbine Bypass Control Valve	Remote <u>AO</u> <u>GLOBE</u>	Maintain Close Transfer Close	Active-to-Failed Remote Position	<u>Non Code</u> <u>Category B</u>	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Cold Shutdown Operability Test	29, 31, 34
NRC 148	MSS-PL-V004	Turbine Bypass Control Valve	Remote <u>AO</u> <u>GLOBE</u>	Maintain Close Transfer Close	Active-to-Failed Remote Position	<u>Non Code</u> <u>Category B</u>	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Cold Shutdown Operability Test	29, 31, 34
NRC 148	MSS-PL-V005	Turbine Bypass Control Valve	Remote <u>AO</u> <u>GLOBE</u>	Maintain Close Transfer Close	Active-to-Failed Remote Position	<u>Non Code</u> <u>Category B</u>	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Cold Shutdown Operability Test	29, 31, 34
NRC 148	MSS-PL-V006	Turbine Bypass Control Valve	Remote <u>AO</u> <u>GLOBE</u>	Maintain Close Transfer Close	Active-to-Failed Remote Position	<u>Non Code</u> <u>Category B</u>	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Cold Shutdown Operability Test	29, 31, 34
NRC 148	MSS-PL-V016A	Moisture Separator Reheater Steam Supply Control Valve	Remote <u>AO</u> <u>GLOBE</u>	Maintain Close Transfer Close	Active-to-Failed Remote Position	<u>Non Code</u> <u>Category B</u>	Remote Position Indication, Exercise/2 Years Exercise Part Stroke/Operation Exercise Full Stroke/Cold Shutdown Operability Test	25, 31, 34
NRC 148	MSS-PL-V017A	Moisture Separator Reheater Steam Supply Bypass Control Valve	Remote	Maintain Close Transfer Close	Active-to-Failed Remote Position	B	Remote Position Indication, Exercise/2 Years Exercise Part Stroke/Operation Exercise Full Stroke/Cold Shutdown Operability Test	25, 31, 34
	MSS-PL-V016B	Moisture Separator Reheater Steam Supply Control Valve	Remote <u>AO</u> <u>GLOBE</u>	Maintain Close Transfer Close	Active-to-Failed Remote Position	<u>Non Code</u> <u>Category B</u>	Remote Position Indication, Exercise/2 Years Exercise Part Stroke/Operation Exercise Full Stroke/Cold Shutdown Operability Test	25, 31, 34
	MSS-PL-V017B	Moisture Separator Reheater Steam Supply Bypass Control Valve	Remote	Maintain Close Transfer Close	Active-to-Failed Remote Position	B	Remote Position Indication, Exercise/2 Years Exercise Part Stroke/Operation Exercise Full Stroke/Cold Shutdown Operability Test	25, 31, 34

NRC 148	MTS-PL-V001A	Turbine Stop Valve	Remote <u>Electro</u> <u>Hydraulic Angle</u> <u>Globe</u>	Maintain Close Transfer Close	Active-to-Failed Remote Position	<u>Non Code</u> <u>Category B</u>	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Cold Shutdown Operability Test	31, 34, 35, 36
	MTS-PL-V001B	Turbine Stop Valve	Remote <u>Electro</u> <u>Hydraulic Angle</u> <u>Globe</u>	Maintain Close Transfer Close	Active-to-Failed Remote Position	<u>Non Code</u> <u>Category B</u>	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Cold Shutdown Operability Test	31, 34, 35, 36
	MTS-PL-V002A	Turbine Control Valve	Remote <u>Electro</u> <u>Hydraulic Angle</u> <u>Globe</u>	Maintain Close Transfer Close	Active-to-Failed Remote Position	<u>Non Code</u> <u>Category B</u>	Remote Position Indication, Exercise/2 Years Exercise Part Stroke/Operation Exercise Full Stroke/Cold Shutdown Operability Test	25, 31, 34, 36

Table 3.9-16 (Sheet 5 of 21)								
VALVE INSERVICE TEST REQUIREMENTS								
NRC 148	Valve Tag Number	Description ⁽¹⁾	Valve/Actuator Type	Safety-Related Missions	Safety Functions ⁽²⁾	ASME Class/IST Category	Inservice Testing Type and Frequency	IST Notes
NRC 148	MTS-PL-V002B	Turbine Control Valve	Remote <u>Electro Hydraulic Angle Globe</u>	Maintain Close Transfer Close	Active-to-Failed Remote Position	<u>Non Code Category B</u>	Remote Position Indication, Exercise/2 Years Exercise Part Stroke/Operation Exercise Full Stroke/Cold Shutdown Operability Test	25, 31, 34, 36
NRC 148	MTS-PL-V003A	Turbine Stop Valve	Remote <u>Electro Hydraulic Angle Globe</u>	Maintain Close Transfer Close	Active-to-Failed Remote Position	<u>Non Code Category B</u>	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Cold Shutdown Operability Test	31, 34, 35, 36
	MTS-PL-V003B	Turbine Stop Valve	Remote <u>Electro Hydraulic Angle Globe</u>	Maintain Close Transfer Close	Active-to-Failed Remote Position	<u>Non Code Category B</u>	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Cold Shutdown Operability Test	31, 34, 35, 36
	MTS-PL-V004A	Turbine Control Valve	Remote <u>Electro Hydraulic Angle Globe</u>	Maintain Close Transfer Close	Active-to-Failed Remote Position	<u>Non Code Category B</u>	Remote Position Indication, Exercise/2 Years Exercise Part Stroke/Operation Exercise Full Stroke/Cold Shutdown Operability Test	25, 31, 34, 36
NRC 148	MTS-PL-V004B	Turbine Control Valve	Remote <u>Electro Hydraulic Angle Globe</u>	Maintain Close Transfer Close	Active-to-Failed Remote Position	<u>Non Code Category B</u>	Remote Position Indication, Exercise/2 Years Exercise Part Stroke/Operation Exercise Full Stroke/Cold Shutdown Operability Test	25, 31, 34, 36
NRC 148	PCS-PL-V001A	PCCWST Isolation	Remote <u>AO Butterfly</u>	Maintain Open Transfer Open	Active-to-Failed Remote Position	<u>Class 3 Category B</u>	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Quarterly Operability Test	31
NRC 148	PCS-PL-V001B	PCCWST Isolation	Remote <u>AO Butterfly</u>	Maintain Open Transfer Open	Active-to-Failed Remote Position	<u>Class 3 Category B</u>	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Quarterly Operability Test	<u>31</u>
NRC 148	PCS-PL-V001C	PCCWST Isolation	Remote <u>MO GATE</u>	Maintain Open Transfer Open	Active Remote Position	<u>Class 3 Category B</u>	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Quarterly Operability Test	<u>31</u>
NRC 148	PCS-PL-V002A	PCCWST Series Isolation	Remote <u>MO GATE</u>	Maintain Open Transfer Open	Active Remote Position	<u>Class 3 Category Class 3 Category-B</u>	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Quarterly Operability Test	<u>31</u>
NRC 148	PCS-PL-V002B	PCCWST Series Isolation	Remote <u>MO GATE</u>	Maintain Open Transfer Open	Active Remote Position	<u>Class 3 Category Class 3 Category-B</u>	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Quarterly Operability Test	<u>31</u>

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PCS-PL-V002C	PCCWST Series Isolation	Remote <u>MO</u> <u>GATE</u>	Maintain Open Transfer Open	Active Remote Position	<u>Class 3</u> <u>Category B</u>	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Quarterly Operability Test	<u>31</u>
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NRC 148

NRC 148

NRC 148

NRC 148

Table 3.9-16 (Sheet 6 of 21)							
VALVE INSERVICE TEST REQUIREMENTS							
Valve Tag Number	Description ⁽¹⁾	Valve/Actuator Type	Safety-Related Missions	Safety Functions ⁽²⁾	ASME Class/IST Category	Inservice Testing Type and Frequency	IST Notes
PCS-PL-V005	PCCWST Supply to Fire Protection Service Isolation	Manual	Maintain Close Transfer Close	Active	<u>Class 3</u> <u>Category B</u>	Exercise Full Stroke/ <u>2 Years</u>	<u>37</u>
PCS-PL-V009	Spent Fuel Pool Emergency Makeup Isolation	Manual	Maintain Close Transfer Open Maintain Open	Active	<u>Class 3</u> <u>Category B</u>	Exercise Full Stroke/ <u>2 Years</u> Quarterly	<u>37</u>
PCS-PL-V014	Post 72 Hour Water Source Isolation	Manual/ Check	Transfer Open	Active	B	Exercise Full Stroke/Quarterly Check Exercise/Refueling	<u>37</u>
PCS-PL-V015	Water Bucket Makeup Line Drain Valve	Manual	Maintain Close Transfer Close	Active	<u>Class 3</u> <u>Category B</u>	Exercise Full Stroke/ <u>2 Years</u> Quarterly	<u>37</u>
PCS-PL-V020	Water Bucket Makeup Line Isolation Valve	Manual	Maintain Open Transfer Open	Active	<u>Class 3</u> <u>Category B</u>	Exercise Full Stroke/ <u>2 Years</u> Quarterly	<u>37</u>
PCS-PL-V023	PCS Recirculation Return Isolation	Manual	Maintain Close Transfer Close	Active	<u>Class 3</u> <u>Category B</u>	Exercise Full Stroke/ <u>2 Years</u> Quarterly	13, <u>37</u>
PCS-PL-V039	PCCWST Long-Term Makeup Check Valve	Check	Maintain Open Transfer Open	Active	<u>Class 3</u> <u>Category C-B</u>	Check Exercise/Refueling	21
PCS-PL-V042	PCCWST Long-Term Makeup Isolation Drain Valve	Manual	Maintain Close Transfer Close	Active	<u>Class 3</u> <u>Category B</u>	Exercise Full Stroke/ <u>2 Years</u> Quarterly	<u>37</u>
PCS-PL-V044	PCCWST Long-Term Makeup Isolation Valve	Manual	Maintain Open Transfer Open	Active	<u>Class 3</u> <u>Category B</u>	Exercise Full Stroke/ <u>2 Years</u> Quarterly	<u>37</u>
PCS-PL-V045	Emergency Makeup to the Spent Fuel Pool Isolation Valve	Manual	Maintain Open Transfer Open	Active	<u>Class 3</u> <u>Category B</u>	Exercise Full Stroke/ <u>2 Years</u> Quarterly	<u>37</u>
PCS-PL-V046	PCCWST Recirculation Return Isolation Valve	Manual	Maintain Close Transfer Close	Active	<u>Class 3</u> <u>Category B</u>	Exercise Full Stroke/ <u>2 Years</u> Quarterly	<u>37</u>
PCS-PL-V049	Emergency Makeup to the Spent Fuel Pool Drain Isolation Valve	Manual	Maintain Close Transfer Close	Active	<u>Class 3</u> <u>Category B</u>	Exercise Full Stroke/ <u>2 Years</u> Quarterly	<u>37</u>
PCS-PL-V050	Spent Fuel Pool Long-Term Makeup Isolation Valve	Manual	Maintain Open Transfer Open	Active	<u>Class 3</u> <u>Category B</u>	Exercise Full Stroke/ <u>2 Years</u> Quarterly	<u>37</u>
PCS-PL-V051	Spent Fuel Pool Emergency Makeup Lower Isolation Valve	Manual	Maintain Close Transfer Close	Active	<u>Class 3</u> <u>Category Class 3</u> Category B	Exercise Full Stroke/ <u>2 Years</u> Quarterly	37
PSS-PL-V008	Containment Air Sample Containment Isolation IRC	Remote <u>SO</u> <u>GLOBE</u>	Maintain Close Transfer Close	Active-to-Failed Containment Isolation Safety Seat Leakage Remote Position	<u>Class 2</u> <u>Category Class 2</u> Category A	Remote Position Indication, Exercise/ <u>2 Years</u> Containment Isolation Leak Test Exercise Full Stroke/ <u>Quarterly</u> Operability Test	27, 31
PSS-PL-V010A	Liquid Sample Line Containment Isolation IRC	Remote <u>SO</u> <u>GLOBE</u>	Maintain Close Transfer Close	Active-to-Failed Containment Isolation Safety Seat Leakage Remote Position	<u>Class 2</u> <u>Category A</u>	Remote Position Indication, Exercise/ <u>2 Years</u> Containment Isolation Leak Test Exercise Full Stroke/ <u>Quarterly</u> Operability Test	27, 31

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PSS-PL-V010B	Liquid Sample Line Containment Isolation IRC	Remote <u>SO</u> <u>GLOBE</u>	Maintain Close Transfer Close	Active-to-Failed Containment Isolation Safety Seat Leakage Remote Position	<u>Class 2</u> <u>Category A</u>	Remote Position Indication, Exercise/2 Years Containment Isolation Leak Test Exercise Full Stroke/Quarterly Operability Test	27, 31
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Table 3.9-16 (Sheet 7 of 21)								
VALVE INSERVICE TEST REQUIREMENTS								
NRC 148	Valve Tag Number	Description ⁽¹⁾	Valve/Actuator Type	Safety-Related Missions	Safety Functions ⁽²⁾	ASME Class/IST Category	Inservice Testing Type and Frequency	IST Notes
NRC 148	PSS-PL-V011	Liquid Sample Line Containment Isolation ORC	Remote <u>AO</u> <u>GLOBE</u>	Maintain Close Transfer Close	Active-to-Failed Containment Isolation Safety Seat Leakage Remote Position	<u>Class 2</u> <u>Category A</u>	Remote Position Indication, Exercise/2 Years Containment Isolation Leak Test Exercise Full Stroke/Quarterly Operability Test	27, 31
NRC 148	PSS-PL-V023	Sample Return Line Containment Isolation ORC	Remote <u>AO</u> <u>Globe</u>	Maintain Close Transfer Close	Active-to-Failed Containment Isolation Safety Seat Leakage Remote Position	<u>Class 2</u> <u>Category A</u>	Remote Position Indication, Exercise/2 Years Containment Isolation Leak Test Exercise Full Stroke/Quarterly Operability Test	27, 31
NRC 148	PSS-PL-V024	Sample Return Containment Isolation Check IRC	Check	Maintain Close Transfer Close	Active Containment Isolation Safety Seat Leakage	<u>Class 2</u> <u>Category AC</u>	Containment Isolation Leak Test Check Exercise/Refueling Shutdown	19, 27
NRC 148	PSS-PL-V046	Air Sample Line Containment Isolation ORC	Remote <u>AO</u> <u>GLOBE</u>	Maintain Close Transfer Close	Active-to-Failed Containment Isolation Safety Seat Leakage Remote Position	<u>Class 2</u> <u>Category A</u>	Remote Position Indication, Exercise/2 Years Containment Isolation Leak Test Exercise Full Stroke/Quarterly Operability Test	27, 31
NRC 148	PXS-PL-V002A	Core Makeup Tank A Cold Leg Inlet Isolation	Remote <u>MO</u> <u>GATE</u>	Maintain Open	Remote Position	<u>Class 1</u> <u>Category B</u>	Remote Position Indication, Exercise/2 Years	
	PXS-PL-V002B	Core Makeup Tank B Cold Leg Inlet Isolation	Remote <u>MO</u> <u>GATE</u>	Maintain Open	Remote Position	<u>Class 1</u> <u>Category B</u>	Remote Position Indication, Exercise/2 Years	
	PXS-PL-V014A	Core Makeup Tank A Discharge Isolation	Remote <u>AO</u> <u>GLOBE</u>	Maintain Open Transfer Open	Active-to-Failed Remote Position	<u>Class 1</u> <u>Category B</u>	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Quarterly Operability Test	31
NRC 148	PXS-PL-V014B	Core Makeup Tank B Discharge Isolation	Remote <u>AO</u> <u>GLOBE</u>	Maintain Open Transfer Open	Active-to-Failed Remote Position	<u>Class 1</u> <u>Category B</u>	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Quarterly Operability Test	31
NRC 148	PXS-PL-V015A	Core Makeup Tank A Discharge Isolation	Remote <u>AO</u> <u>GLOBE</u> AO GLOBE	Maintain Open Transfer Open	Active-to-Failed Remote Position	<u>Class 1</u> <u>Category B</u> Class 1 Category B	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Quarterly Operability Test	31
NRC 148	PXS-PL-V015B	Core Makeup Tank B Discharge Isolation	Remote <u>AO</u> <u>GLOBE</u>	Maintain Open Transfer Open	Active-to-Failed Remote Position	<u>Class 1</u> <u>Category B</u>	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Quarterly Operability Test	31
NRC 148	PXS-PL-V016A	Core Makeup Tank A Discharge Check	Check	Maintain Open Transfer Open Transfer Close	Active Remote Position	<u>Class 1</u> <u>Category BC</u>	Remote Position Indication, Exercise/2 Years Check Exercise/Refueling Shutdown	10
NRC 148	PXS-PL-V016B	Core Makeup Tank B Discharge Check	Check	Maintain Open Transfer Open Transfer Close	Active Remote Position	<u>Class 1</u> <u>Category BC</u>	Remote Position Indication, Exercise/2 Years Check Exercise/Refueling Shutdown	10

Table 3.9-16 (Sheet 8 of 21)								
VALVE INSERVICE TEST REQUIREMENTS								
NRC 148	Valve Tag Number	Description ⁽¹⁾	Valve/Actuator Type	Safety-Related Missions	Safety Functions ⁽²⁾	ASME Class/IST Category	Inservice Testing Type and Frequency	IST Notes
NRC 148	PXS-PL-V017A	Core Makeup Tank A Discharge Check	Check	Maintain Open Transfer Open Transfer Close	Active Remote Position	Class 1 Category BC	Remote Position Indication, Exercise/2 Years Check Exercise/Refueling Shutdown	10
NRC 148	PXS-PL-V017B	Core Makeup Tank B Discharge Check	Check	Maintain Open Transfer Open Transfer Close	Active Remote Position	Class 1 Category BC	Remote Position Indication, Exercise/2 Years Check Exercise/Refueling Shutdown	10
NRC 148	PXS-PL-V022A	Accumulator A Pressure Relief	Relief	Maintain Close Transfer Open Transfer Close	Active	Class 3 Category BC	Class 2/3 Relief Valve Tests/10 Years and 20% in 4 Years	
NRC 148	PXS-PL-V022B	Accumulator B Pressure Relief	Relief	Maintain Close Transfer Open Transfer Close	Active	Class 3 Category BC	Class 2/3 Relief Valve Tests/10 Years and 20% in 4 Years	
NRC 148	PXS-PL-V027A	Accumulator A Discharge Isolation	Remote <u>MO GATE</u>	Maintain Open	Remote Position	Class 1 Category B	Remote Position Indication, Exercise/2 Years	
	PXS-PL-V027B	Accumulator B Discharge Isolation	Remote <u>MO GATE</u>	Maintain Open	Remote Position	Class 1 Category B	Remote Position Indication, Exercise/2 Years	
	PXS-PL-V028A	Accumulator A Discharge Check	Check	Maintain Close Transfer Open	Active RCS Pressure Boundary Remote Position Safety Seat Leakage	Class 1 Category AC	Remote Position Indication, Exercise/2 Years Check Exercise/Refueling Shutdown Pressure Isolation Leak Test/ <u>2 years</u> Refueling Shutdown	9
NRC 148	PXS-PL-V028B	Accumulator B Discharge Check	Check	Maintain Close Transfer Open	Active RCS Pressure Boundary Remote Position Safety Seat Leakage	Class 1 Category AC	Remote Position Indication, Exercise/2 Years Check Exercise/Refueling Shutdown Pressure Isolation Leak Test/ <u>2 Years</u> Refueling Shutdown	9
NRC 148	PXS-PL-V029A	Accumulator A Discharge Check	Check	Maintain Close Transfer Open	Active RCS Pressure Boundary Remote Position Safety Seat Leakage	Class 1 Category Class 1 AC	Remote Position Indication, Exercise/2 Years Check Exercise/Refueling Shutdown Pressure Isolation Leak Test/Refueling Shutdown	9
NRC 148	PXS-PL-V029B	Accumulator B Discharge Check	Check	Maintain Close Transfer Open	Active RCS Pressure Boundary Remote Position Safety Seat Leakage	Class 1 Category AC	Remote Position Indication, Exercise/2 Years Check Exercise/Refueling Shutdown Pressure Isolation Leak Test/Refueling Shutdown	9
NRC 148	PXS-PL-V042	Nitrogen Supply Containment Isolation ORC	Remote <u>AO GLOBE</u>	Maintain Close Transfer Close	Active-to-Failed Containment Isolation Safety Seat Leakage Remote Position	Class 2 Category A	Remote Position Indication, Exercise/2 Years Containment Isolation Leak Test Exercise Full Stroke/Quarterly Operability Test	27, 31

Table 3.9-16 (Sheet 9 of 21)								
VALVE INSERVICE TEST REQUIREMENTS								
NRC 148	Valve Tag Number	Description ⁽¹⁾	Valve/Actuator Type	Safety-Related Missions	Safety Functions ⁽²⁾	ASME Class/IST Category	Inservice Testing Type and Frequency	IST Notes
NRC 148	PXS-PL-V043	Nitrogen Supply Containment Isolation IRC	Check	Maintain Close Transfer Close	Active Containment Isolation Safety Seat Leakage Remote Position	Class 2 Category AC	Remote Position Indication, Exercise/2 Years Containment Isolation Leak Test Check Exercise/Quarterly	27
NRC 148	PXS-PL-V101	PRHR HX Inlet Isolation	Remote MO GATE	Maintain Open	Remote Position	Class 1 Category B	Remote Position Indication, Exercise/2 Years	
	PXS-PL-V108A	PRHR HX Control	Remote AO GLOBE	Maintain Open Transfer Open	Active-to-Failed Remote Position	Class 1 Category B	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Quarterly Operability Test	31
NRC 148	PXS-PL-V108B	PRHR HX Control	Remote AO GLOBE	Maintain Open Transfer Open	Active-to-Failed Remote Position	Class 1 Category B	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Quarterly Operability Test	31
NRC 148	PXS-PL-V117A	Containment Recirculation A Isolation	Remote MO GATE	Maintain Open Maintain Close Transfer Open	Active Remote Position	Class 3 Category B	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Quarterly Operability Test	31
NRC 148	PXS-PL-V117B	Containment Recirculation B Isolation	Remote MO GATE	Maintain Open Maintain Close Transfer Open	Active Remote Position	Class 3 Category B	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Quarterly Operability Test	31
NRC 148	PXS-PL-V118A	Containment Recirculation A Isolation	Squib	Maintain Open Maintain Close Transfer Open	Active Remote Position	Class 3 Category D	Remote Position Indication, Alternate/2 Years Charge Test Fire/20% in 2 Years	5
NRC 148	PXS-PL-V118B	Containment Recirculation B Isolation	Squib	Maintain Open Maintain Close Transfer Open	Active Remote Position	Class 3 Category D	Remote Position Indication, Alternate/2 Years Charge Test Fire/20% in 2 Years	5
NRC 148	PXS-PL-V119A	Containment Recirculation A Check	Check	Maintain Open Maintain Close Transfer Open	Active Remote Position	Class 3 Category BC	Remote Position Indication, Exercise/2 Years Check-Initial Open Differential Pressure/2 Years Check Exercise/Refueling Shutdown	11
NRC 148	PXS-PL-V119B	Containment Recirculation B Check	Check	Maintain Open Maintain Close Transfer Open	Active Remote Position	Class 3 Category Class 3-Category BC	Remote Position Indication, Exercise/2 Years Check-Initial Open Differential Pressure/2 Years Check Exercise/Refueling Shutdown	11
NRC 148	PXS-PL-V120A	Containment Recirculation A Isolation	Squib	Maintain Open Maintain Close Transfer Open	Active Remote Position	Class 3 Category D	Remote Position Indication, Alternate/2 Years Charge Test Fire/20% in 2 Years	5
NRC 148	PXS-PL-V120B	Containment Recirculation B Isolation	Squib	Maintain Open Maintain Close Transfer Open	Active Remote Position	Class 3 Category D	Remote Position Indication, Alternate/2 Years Charge Test Fire/20% in 2 Years	5
NRC 148	PXS-PL-V121A	IRWST Line A Isolation	Remote MO GATE	Maintain Open	Remote Position	Class 3 Category B	Remote Position Indication, Exercise/2 Years	

Table 3.9-16 (Sheet 10 of 21)								
VALVE INSERVICE TEST REQUIREMENTS								
NRC 148	Valve Tag Number	Description ⁽¹⁾	Valve/Actuator Type	Safety-Related Missions	Safety Functions ⁽²⁾	ASME Class/IST Category	Inservice Testing Type and Frequency	IST Notes
NRC 148	PXS-PL-V121B	IRWST Line B Isolation	Remote <u>MO GATE</u>	Maintain Open	Remote Position	<u>Class 3 Category B</u>	Remote Position Indication, Exercise/2 Years	
NRC 148	PXS-PL-V122A	IRWST Injection A Check	Check	Maintain Open Maintain Close Transfer Open	Active RCS Pressure Boundary Remote Position	<u>Class 1 Category BC</u>	Remote Position Indication, Exercise/2 Years Check-Initial Open Differential Pressure/2 Years Check Exercise/Refueling Shutdown	12
NRC 148	PXS-PL-V122B	IRWST Injection B Check	Check	Maintain Open Maintain Close Transfer Open	Active RCS Pressure Boundary Remote Position	<u>Class 1 Category BC</u>	Remote Position Indication, Exercise/2 Years Check-Initial Open Differential Pressure/2 Years Check Exercise/Refueling Shutdown	12
NRC 148	PXS-PL-V123A	IRWST Injection A Isolation	Squib	Maintain Open Maintain Close Transfer Open	Active RCS Pressure Boundary Remote Position	<u>Class 1 Category D</u>	Remote Position Indication, Alternate/2 Years Charge Test Fire/20% in 2 Years	5
NRC 148	PXS-PL-V123B	IRWST Injection B Isolation	Squib	Maintain Open Maintain Close Transfer Open	Active RCS Pressure Boundary Remote Position	<u>Class 1 Category D</u>	Remote Position Indication, Alternate/2 Years Charge Test Fire/20% in 2 Years	5
NRC 148	PXS-PL-V124A	IRWST Injection A Check	Check	Maintain Open Maintain Close Transfer Open	Active RCS Pressure Boundary Remote Position	<u>Class 1 Category BC</u>	Remote Position Indication, Exercise/2 Years Check-Initial Open Differential Pressure/2 Years Check Exercise/Refueling Shutdown	12
NRC 148	PXS-PL-V124B	IRWST Injection B Check	Check	Maintain Open Maintain Close Transfer Open	Active RCS Pressure Boundary Remote Position	<u>Class 1 Category BC</u>	Remote Position Indication, Exercise/2 Years Check-Initial Open Differential Pressure/2 Years Check Exercise/Refueling Shutdown	12
NRC 148	PXS-PL-V125A	IRWST Injection A Isolation	Squib	Maintain Open Maintain Close Transfer Open	Active RCS Pressure Boundary Remote Position	<u>Class 1 Category D</u>	Remote Position Indication, Alternate/2 Years Charge Test Fire/20% in 2 Years	5
NRC 148	PXS-PL-V125B	IRWST Injection B Isolation	Squib	Maintain Open Maintain Close Transfer Open	Active RCS Pressure Boundary Remote Position	<u>Class 1 Category D</u>	Remote Position Indication, Alternate/2 Years Charge Test Fire/20% in 2 Years	5
NRC 148	PXS-PL-V130A	IRWST Gutter Isolation	Remote <u>AO GLOBE</u>	Maintain Close Transfer Close	Active-to-Failed Remote Position	<u>Class 3 Category B</u>	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Quarterly Operability Test	31
NRC 148	PXS-PL-V130B	IRWST Gutter Isolation	Remote <u>AO GLOBE</u>	Maintain Close Transfer Close	Active-to-Failed Remote Position	<u>Class 3 Category B</u>	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Quarterly Operability Test	31
NRC 148	PXS-PL-V208A	RNS Suction Leak Test	Manual	Maintain Close	Containment Isolation Safety Seat Leakage	<u>Class 2 Category A</u>	Containment Isolation Leak Test/2 Years	
NRC 148	RCS-PL-V001A	First Stage Automatic Depressurization System	Remote <u>MO GLOBE</u>	Maintain Open Maintain Close Transfer Open	Active RCS Pressure Boundary Remote Position	<u>Class 1 Category B</u>	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Cold Shutdown Operability Test	3, 31

Table 3.9-16 (Sheet 11 of 21)								
VALVE INSERVICE TEST REQUIREMENTS								
NRC 148	Valve Tag Number	Description ⁽¹⁾	Valve/Actuator Type	Safety-Related Missions	Safety Functions ⁽²⁾	ASME Class/ IST Category	Inservice Testing Type and Frequency	IST Notes
NRC 148	RCS-PL-V001B	First Stage Automatic Depressurization System	Remote <u>MO</u> <u>GLOBE</u>	Maintain Open Maintain Close Transfer Open	Active RCS Pressure Boundary Remote Position	<u>Class 1</u> <u>Category B</u>	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Cold Shutdown Operability Test	3, 31
NRC 148	RCS-PL-V002A	Second Stage Automatic Depressurization System	Remote <u>MO</u> <u>GLOBE</u>	Maintain Open Maintain Close Transfer Open	Active RCS Pressure Boundary Remote Position	<u>Class 1</u> <u>Category B</u>	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Cold Shutdown Operability Test	3, 31
NRC 148	RCS-PL-V002B	Second Stage Automatic Depressurization System	Remote <u>MO</u> <u>GLOBE</u>	Maintain Open Maintain Close Transfer Open	Active RCS Pressure Boundary Remote Position	<u>Class 1</u> <u>Category B</u>	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Cold Shutdown Operability Test	3, 31
NRC 148	RCS-PL-V003A	Third Stage Automatic Depressurization System	Remote <u>MO</u> <u>GLOBE</u>	Maintain Open Maintain Close Transfer Open	Active RCS Pressure Boundary Remote Position	<u>Class 1</u> <u>Category B</u>	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Cold Shutdown Operability Test	3, 31
NRC 148	RCS-PL-V003B	Third Stage Automatic Depressurization System	Remote <u>MO</u> <u>GLOBE</u>	Maintain Open Maintain Close Transfer Open	Active RCS Pressure Boundary Remote Position	<u>Class 1</u> <u>Category B</u>	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Cold Shutdown Operability Test	3, 31
NRC 148	RCS-PL-V004A	Fourth Stage Automatic Depressurization System	Squib	Maintain Open Maintain Close Transfer Open	Active RCS Pressure Boundary Remote Position	<u>Class 1</u> <u>Category D</u>	Remote Position Indication, Alternate/2 Years Charge Test Fire/20% in 2 Years	5
NRC 148	RCS-PL-V004B	Fourth Stage Automatic Depressurization System	Squib	Maintain Open Maintain Close Transfer Open	Active RCS Pressure Boundary Remote Position	<u>Class 1</u> <u>Category D</u>	Remote Position Indication, Alternate/2 Years Charge Test Fire/20% in 2 Years	5
NRC 148	RCS-PL-V004C	Fourth Stage Automatic Depressurization System	Squib	Maintain Open Maintain Close Transfer Open	Active RCS Pressure Boundary Remote Position	<u>Class 1</u> <u>Category D</u>	Remote Position Indication, Alternate/2 Years Charge Test Fire/20% in 2 Years	5
NRC 148	RCS-PL-V004D	Fourth Stage Automatic Depressurization System	Squib	Maintain Open Maintain Close Transfer Open	Active RCS Pressure Boundary Remote Position	<u>Class 1</u> <u>Category D</u>	Remote Position Indication, Alternate/2 Years Charge Test Fire/20% in 2 Years	5
NRC 148	RCS-PL-V005A	Pressurizer Safety Valve	Relief	Maintain Close Transfer Open Transfer Close	Active RCS Pressure Boundary Remote Position	<u>Class 1</u> <u>Category BC</u>	Remote Position Indication, Alternate/2 Years Class 1 Relief Valve Tests/5 Years and 20% in 2 Years	7
NRC 148	RCS-PL-V005B	Pressurizer Safety Valve	Relief	Maintain Close Transfer Open Transfer Close	Active RCS Pressure Boundary Remote Position	<u>Class 1</u> <u>Category BC</u>	Remote Position Indication, Alternate/2 Years Class 1 Relief Valve Tests/5 Years and 20% in 2 Years	7
NRC 148	RCS-PL-V010A	Automatic Depressurization System Discharge Header A Vacuum Relief	Relief	Transfer Open	Active	<u>Class 3</u> <u>Category BC</u>	Class 2/3 Relief Valve Tests/10 Years and 20% in 4 Years	
	RCS-PL-V010B	Automatic Depressurization System Discharge Header B Vacuum Relief	Relief	Transfer Open	Active	<u>Class 3</u> <u>Category BC</u>	Class 2/3 Relief Valve Tests/10 Years and 20% in 4 Years	

Table 3.9-16 (Sheet 12 of 21)								
VALVE INSERVICE TEST REQUIREMENTS								
NRC 148	Valve Tag Number	Description ⁽¹⁾	Valve/Actuator Type	Safety-Related Missions	Safety Functions ⁽²⁾	ASME Class/IST Category	Inservice Testing Type and Frequency	IST Notes
NRC 148	RCS-PL-V011A	First Stage Automatic Depressurization System Isolation	Remote <u>MO</u> <u>GATE</u>	Maintain Open Maintain Close Transfer Open	Active RCS Pressure Boundary Remote Position	<u>Class 1</u> <u>Category B</u>	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Cold Shutdown Operability Test	3, 31
NRC 148	RCS-PL-V011B	First Stage Automatic Depressurization System Isolation	Remote <u>MO</u> <u>GATE</u>	Maintain Open Maintain Close Transfer Open	Active RCS Pressure Boundary Remote Position	<u>Class 1</u> <u>Category B</u>	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Cold Shutdown Operability Test	3, 31
NRC 148	RCS-PL-V012A	Second Stage Automatic Depressurization System Isolation	Remote <u>MO</u> <u>GATE</u>	Maintain Open Maintain Close Transfer Open	Active RCS Pressure Boundary Remote Position	<u>Class 1</u> <u>Category B</u>	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Cold Shutdown Operability Test	3, 31
NRC 148	RCS-PL-V012B	Second Stage Automatic Depressurization System Isolation	Remote <u>MO</u> <u>GATE</u>	Maintain Open Maintain Close Transfer Open	Active RCS Pressure Boundary Remote Position	<u>Class 1</u> <u>Category B</u>	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Cold Shutdown Operability Test	3, 31
NRC 148	RCS-PL-V013A	Third Stage Automatic Depressurization System Isolation	Remote <u>MO</u> <u>GATE</u>	Maintain Open Maintain Close Transfer Open	Active RCS Pressure Boundary Remote Position	<u>Class 1</u> <u>Category B</u>	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Cold Shutdown Operability Test	3, 31
NRC 148	RCS-PL-V013B	Third Stage Automatic Depressurization System Isolation	Remote <u>MO</u> <u>GATE</u>	Maintain Open Maintain Close Transfer Open	Active RCS Pressure Boundary Remote Position	<u>Class 1</u> <u>Category B</u>	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Cold Shutdown Operability Test	3, 31
NRC 148	RCS-PL-V014A	Fourth Stage Automatic Depressurization System Isolation	Remote <u>MO</u> <u>GATE</u>	Maintain Open	Remote Position	<u>Class 1</u> <u>Category B</u>	Remote Position Indication, Exercise/2 Years	
	RCS-PL-V014B	Fourth Stage Automatic Depressurization System Isolation	Remote <u>MO</u> <u>GATE</u>	Maintain Open	Remote Position	<u>Class 1</u> <u>Category B</u>	Remote Position Indication, Exercise/2 Years	
	RCS-PL-V014C	Fourth Stage Automatic Depressurization System Isolation	Remote <u>MO</u> <u>GATE</u>	Maintain Open	Remote Position	<u>Class 1</u> <u>Category B</u>	Remote Position Indication, Exercise/2 Years	
	RCS-PL-V014D	Fourth Stage Automatic Depressurization System Isolation	Remote <u>MO</u> <u>GATE</u>	Maintain Open	Remote Position	<u>Class 1</u> <u>Category B</u>	Remote Position Indication, Exercise/2 Years	
NRC 148	RCS-PL-V150A	Reactor Vessel Head Vent	Remote <u>SO</u> <u>GLOBE</u>	Maintain Open Maintain Close Transfer Open	Active-to-Failed RCS Pressure Boundary Remote Position	<u>Class 1</u> <u>Category B</u>	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Cold Shutdown Operability Test	4, 31
	RCS-PL-V150B	Reactor Vessel Head Vent	Remote <u>SO</u> <u>GLOBE</u>	Maintain Open Maintain Close Transfer Open	Active-to-Failed RCS Pressure Boundary Remote Position	<u>Class 1</u> <u>Category B</u>	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Cold Shutdown Operability Test	4, 31
NRC 148	RCS-PL-V150C	Reactor Vessel Head Vent	Remote <u>SO</u> <u>GLOBE</u>	Maintain Open Maintain Close Transfer Open	Active-to-Failed RCS Pressure Boundary Remote Position	<u>Class 1</u> <u>Category B</u>	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Cold Shutdown Operability Test	4, 31
NRC 148	RCS-PL-V150D	Reactor Vessel Head Vent	Remote <u>SO</u> <u>GLOBE</u>	Maintain Open Maintain Close Transfer Open	Active-to-Failed RCS Pressure Boundary Remote Position	<u>Class 1</u> <u>Category B</u>	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Cold Shutdown Operability Test	4, 31

Table 3.9-16 (Sheet 13 of 21)								
VALVE INSERVICE TEST REQUIREMENTS								
NRC 148	Valve Tag Number	Description ⁽¹⁾	Valve/Actuator Type	Safety-Related Missions	Safety Functions ⁽²⁾	ASME Class/IST Category	Inservice Testing Type and Frequency	IST Notes
	RCS-K03	Safety Valve Discharge Chamber Rupture Disk	Relief	Transfer Open	Active	<u>Class 3</u> <u>Category BC</u>	Inspect and Replace/5 Years	
NRC 148	RCS-K04	Safety Valve Discharge Chamber Rupture Disk	Relief	Transfer Open	Active	<u>Class 3</u> <u>Category BC</u>	Inspect and Replace/5 Years	
	RNS-PL-V001A	RNS Hot Leg Suction Isolation - Inner	Remote <u>MO</u> <u>GATE</u>	Maintain Close Transfer Close	Active RCS Pressure Boundary Safety Seat Leakage Remote Position	<u>Class 1</u> <u>Category A</u>	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Cold Shutdown Pressure Isolation Leak Test/ <u>2 Years</u> Refueling Shutdown Operability Test	15, 31
NRC 148	RNS-PL-V001B	RNS Hot Leg Suction Isolation - Inner	Remote <u>MO</u> <u>GATE</u>	Maintain Close Transfer Close	Active RCS Pressure Boundary Safety Seat Leakage Remote Position	<u>Class 1</u> <u>Category A</u>	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Cold Shutdown Pressure Isolation Leak Test/ <u>2 Years</u> Refueling Shutdown Operability Test	15, 31
NRC 148	RNS-PL-V002A	RNS Hot Leg Suction and Containment Isolation - Outer	Remote <u>MO</u> <u>GATE</u>	Maintain Close Transfer Close	Active RCS Pressure Boundary Containment Isolation Safety Seat Leakage Remote Position	<u>Class 1</u> <u>Category A</u>	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Cold Shutdown Pressure Isolation Leak Test/ <u>2 Years</u> Refueling Shutdown Operability Test	15, 16, 31
NRC 148	RNS-PL-V002B	RNS Hot Leg Suction and Containment Isolation - Outer	Remote <u>MO</u> <u>GATE</u>	Maintain Close Transfer Close	Active RCS Pressure Boundary Containment Isolation Safety Seat Leakage Remote Position	<u>Class 1</u> <u>Category A</u>	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Cold Shutdown Pressure Isolation Leak Test/ <u>2 Years</u> Refueling Shutdown Operability Test	15, 16, 31
NRC 148	RNS-PL-V003A	RCS Pressure Boundary Valve Thermal Relief	Check	Maintain Close Transfer Open Transfer Close	Active RCS Pressure Boundary	<u>Class 2</u> <u>Category BC</u>	Check Exercise/Refueling Shutdown	23
NRC 148	RNS-PL-V003B	RCS Pressure Boundary Valve Thermal Relief	Check	Maintain Close Transfer Open Transfer Close	Active RCS Pressure Boundary	<u>Class 2</u> <u>Category BC</u>	Check Exercise/Refueling Shutdown	23
NRC 148	RNS-PL-V011	RNS Discharge Containment Isolation Valve - ORC	Remote <u>MO</u> <u>GATE</u>	Maintain Close Transfer Close	Active Containment Isolation Safety Seat Leakage Remote Position	<u>Class 2</u> <u>Category A</u>	Remote Position Indication, Exercise/2 Years Containment Isolation Leak Test Exercise Full Stroke/Quarterly Operability Test	27, 31
NRC 148	RNS-PL-V013	RNS Discharge Containment Isolation - IRC	Check	Maintain Close Transfer Open Transfer Close	Active Containment Isolation Safety Seat Leakage	<u>Class 2</u> <u>Category AC</u>	Containment Isolation Leak Test Check Exercise/Quarterly	27
NRC 148	RNS-PL-V015A	RNS Discharge RCS Pressure Boundary	Check	Maintain Close Transfer Close	Active RCS Pressure Boundary Safety Seat Leakage	<u>Class 1</u> <u>Category AC</u>	Check Exercise/Refueling Shutdown Pressure Isolation Leak Test/ <u>2 Years</u> Refueling Shutdown	24

Table 3.9-16 (Sheet 14 of 21)								
VALVE INSERVICE TEST REQUIREMENTS								
NRC 148	Valve Tag Number	Description ⁽¹⁾	Valve/Actuator Type	Safety-Related Missions	Safety Functions ⁽²⁾	ASME Class/IST Category	Inservice Testing Type and Frequency	IST Notes
NRC 148	RNS-PL-V015B	RNS Discharge RCS Pressure Boundary	Check	Maintain Close Transfer Close	Active RCS Pressure Boundary Safety Seat Leakage	<u>Class 1</u> <u>Category AC</u>	Check Exercise/Refueling Shutdown Pressure Isolation Leak Test/ <u>2 Years</u> Refueling Shutdown	24
NRC 148	RNS-PL-V017A	RNS Discharge RCS Pressure Boundary	Check	Maintain Close Transfer Open Transfer Close	Active RCS Pressure Boundary Safety Seat Leakage	<u>Class 1</u> <u>Category AC</u>	Check Exercise/Refueling Shutdown Pressure Isolation Leak Test/ <u>2 Years</u> Refueling Shutdown	24
NRC 148	RNS-PL-V017B	RNS Discharge RCS Pressure Boundary	Check	Maintain Close Transfer Open Transfer Close	Active RCS Pressure Boundary Safety Seat Leakage	<u>Class 1</u> <u>Category AC</u>	Check Exercise/Refueling Shutdown Pressure Isolation Leak Test/ <u>2 Years</u> Refueling Shutdown	24
NRC 148	RNS-PL-V021	RNS Hot Leg Suction Pressure Relief	Relief	Maintain Close Transfer Open Transfer Close	Active Containment Isolation Safety Seat Leakage	<u>Class 2</u> <u>Category AC</u>	Containment Isolation Leak Test/2 Years Class 2/3 Relief Valve Tests/10 Years and 20% in 4 Years	17, 27
NRC 148	RNS-PL-V022	RNS Suction Header Containment Isolation - ORC	Remote <u>MO</u> <u>GATE</u>	Maintain Close Transfer Close	Active Containment Isolation Safety Seat Leakage Remote Position	<u>Class 2</u> <u>Category A</u>	Remote Position Indication, Exercise/2 Years Containment Isolation Leak Test Exercise Full Stroke/Quarterly Operability Test	27, 31
NRC 148	RNS-PL-V023	RNS Suction from IRWST - Containment Isolation	Remote <u>MO</u> <u>GATE</u>	Maintain Close Transfer Close	Active Containment Isolation Safety Seat Leakage Remote Position	<u>Class 2</u> <u>Category A</u>	Remote Position Indication, Exercise/2 Years Containment Isolation Leak Test Exercise Full Stroke/Quarterly Operability Test	17, 27, 31
NRC 148	RNS-PL-V045	RNS Pump Discharge Relief	Relief	Maintain Close Transfer Open Transfer Close	Active	<u>Class 3</u> <u>Category BC</u>	Class 2/3 Relief Valve Tests/10 Years and 20% in 4 Years	
NRC 148	RNS-PL-V046	RNS Heat Exchanger A Channel Head Drain Isolation	Manual	Maintain Open Transfer Open	Active	<u>Class 3</u> <u>Category B</u>	Exercise Full Stroke/ <u>2 Year</u> quarterly	<u>37</u>
	RNS-PL-V061	RNS Return from CVS - Containment Isolation	Remote <u>AO</u> <u>GLOBE</u>	Maintain Close Transfer Close	Active-to-Failed Containment Isolation Safety Seat Leakage Remote Position	<u>Class 2</u> <u>Category A</u>	Remote Position Indication, Exercise/2 Years Containment Isolation Leak Test Exercise Full Stroke/Quarterly Operability Test	27, 31
NRC 148	SFS-PL-V034	SFS Suction Line Containment Isolation	Remote <u>MO</u> <u>Butterfly</u>	Maintain Close Transfer Close	Active Containment Isolation Safety Seat Leakage Remote Position	<u>Class 2</u> <u>Category A</u>	Remote Position Indication, Exercise/2 Years Containment Isolation Leak Test Exercise Full Stroke/Quarterly Operability Test	27, 31
NRC 148	SFS-PL-V035	SFS Suction Line Containment Isolation	Remote <u>MO</u> <u>Butterfly</u>	Maintain Close Transfer Close	Active Containment Isolation Safety Seat Leakage Remote Position	<u>Class 2</u> <u>Category A</u>	Remote Position Indication, Exercise/2 Years Containment Isolation Leak Test Exercise Full Stroke/Quarterly Operability Test	27, 31

Table 3.9-16 (Sheet 15 of 21)								
VALVE INSERVICE TEST REQUIREMENTS								
NRC 148	Valve Tag Number	Description ⁽¹⁾	Valve/Actuator Type	Safety-Related Missions	Safety Functions ⁽²⁾	ASME Class/IST Category	Inservice Testing Type and Frequency	IST Notes
NRC 148	SFS-PL-V037	SFS Discharge Line Containment Isolation	Check	Maintain Close Transfer Close Transfer Open	Active Containment Isolation Safety Seat Leakage	Class 2 Category AC	Containment Isolation Leak Test Check Exercise/Quarterly	27
NRC 148	SFS-PL-V038	SFS Discharge Line Containment Isolation	Remote MO Butterfly	Maintain Close Transfer Close	Active Containment Isolation Safety Seat Leakage Remote Position	Class 2 Category A	Remote Position Indication, Exercise/2 Years Containment Isolation Leak Test Exercise Full Stroke/Quarterly Operability Test	27, 31
NRC 148	<u>SFS-PL-V066</u>	<u>Spent Fuel Pool to Cask Washdown Pit Isolation</u>	<u>Manual</u>	<u>Transfer Open</u> <u>Transfer Close</u> <u>Maintain Close</u>	<u>Active</u>	<u>Class 3</u> <u>Category B</u>	<u>Exercise Full Stroke/2 Years</u>	<u>37</u>
	<u>SFS-PL-V068</u>	<u>Cask Washdown Pit Drain Isolation</u>	<u>Manual</u>	<u>Transfer Open</u> <u>Transfer Close</u> <u>Maintain Close</u>	<u>Active</u>	<u>Class 3</u> <u>Category B</u>	<u>Exercise Full Stroke/2 Years</u>	<u>37</u>
NRC 148	SFS-PL-V071	Refueling Cavity to Steam Generator Compartment	Check	Transfer Open Transfer Close Maintain Close	Active	Class 3 Category BC	Check Exercise/Refueling Shutdown	26
	SFS-PL-V072	Refueling Cavity to Steam Generator Compartment	Check	Transfer Open Transfer Close Maintain Close	Active	Class 3 Category BC	Check Exercise/Refueling Shutdown	26
NRC 148	SGS-PL-V027A	Power-Operated Relief Valve Block Valve Steam Generator 01	Remote MO GATE	Maintain Close Transfer Close	Active Containment Isolation Remote Position	Class 2 Category B	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Quarterly Operability Test	31
NRC 148	SGS-PL-V027B	Power-Operated Relief Valve Block Valve Steam Generator 02	Remote MO GATE	Maintain Close Transfer Close	Active Containment Isolation Remote Position	Class 2 Category B	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Quarterly Operability Test	31
NRC 148	SGS-PL-V030A	Main Steam Safety Valve Steam Generator 01	Relief	Maintain Close Transfer Open Transfer Close	Active Containment Isolation Remote Position	Class 2 Category BC	Remote Position Indication, Alternate/2 Years Class 2/3 Relief Valve Tests/5 Years and 20% in 2 Years	7
NRC 148	SGS-PL-V030B	Main Steam Safety Valve Steam Generator 02	Relief	Maintain Close Transfer Open Transfer Close	Active Containment Isolation Remote Position	Class 2 Category BC	Remote Position Indication, Alternate/2 Years Class 2/3 Relief Valve Tests/5 Years and 20% in 2 Years	7
NRC 148	SGS-PL-V031A	Main Steam Safety Valve Steam Generator 01	Relief	Maintain Close Transfer Open Transfer Close	Active Containment Isolation Remote Position	Class 2 Category BC	Remote Position Indication, Alternate/2 Years Class 2/3 Relief Valve Tests/5 Years and 20% in 2 Years	7
NRC 148	SGS-PL-V031B	Main Steam Safety Valve Steam Generator 02	Relief	Maintain Close Transfer Open Transfer Close	Active Containment Isolation Remote Position	Class 2 Category BC	Remote Position Indication, Alternate/2 Years Class 2/3 Relief Valve Tests/5 Years and 20% in 2 Years	7

Table 3.9-16 (Sheet 16 of 21)								
VALVE INSERVICE TEST REQUIREMENTS								
NRC 148	Valve Tag Number	Description ⁽¹⁾	Valve/Actuator Type	Safety-Related Missions	Safety Functions ⁽²⁾	ASME Class/IST Category	Inservice Testing Type and Frequency	IST Notes
NRC 148	SGS-PL-V032A	Main Steam Safety Valve Steam Generator 01	Relief	Maintain Close Transfer Open Transfer Close	Active Containment Isolation Remote Position	<u>Class 2</u> <u>Category BC</u>	Remote Position Indication, Alternate/2 Years Class 2/3 Relief Valve Tests/5 Years and 20% in 2 Years	7
NRC 148	SGS-PL-V032B	Main Steam Safety Valve Steam Generator 02	Relief	Maintain Close Transfer Open Transfer Close	Active Containment Isolation Remote Position	<u>Class 2</u> <u>Category BC</u>	Remote Position Indication, Alternate/2 Years Class 2/3 Relief Valve Tests/5 Years and 20% in 2 Years	7
NRC 148	SGS-PL-V033A	Main Steam Safety Valve Steam Generator 01	Relief	Maintain Close Transfer Open Transfer Close	Active Containment Isolation Remote Position	<u>Class 2</u> <u>Category BC</u>	Remote Position Indication, Alternate/2 Years Class 2/3 Relief Valve Tests/5 Years and 20% in 2 Years	7
NRC 148	SGS-PL-V033B	Main Steam Safety Valve Steam Generator 02	Relief	Maintain Close Transfer Open Transfer Close	Active Containment Isolation Remote Position	<u>Class 2</u> <u>Category BC</u>	Remote Position Indication, Alternate/2 Years Class 2/3 Relief Valve Tests/5 Years and 20% in 2 Years	7
NRC 148	SGS-PL-V034A	Main Steam Safety Valve Steam Generator 01	Relief	Maintain Close Transfer Open Transfer Close	Active Containment Isolation Remote Position	<u>Class 2</u> <u>Category BC</u>	Remote Position Indication, Alternate/2 Years Class 2/3 Relief Valve Tests/5 Years and 20% in 2 Years	7
NRC 148	SGS-PL-V034B	Main Steam Safety Valve Steam Generator 02	Relief	Maintain Close Transfer Open Transfer Close	Active Containment Isolation Remote Position	<u>Class 2</u> <u>Category BC</u>	Remote Position Indication, Alternate/2 Years Class 2/3 Relief Valve Tests/5 Years and 20% in 2 Years	7
NRC 148	SGS-PL-V035A	Main Steam Safety Valve Steam Generator 01	Relief	Maintain Close Transfer Open Transfer Close	Active Containment Isolation Remote Position	<u>Class 2</u> <u>Category BC</u>	Remote Position Indication, Alternate/2 Years Class 2/3 Relief Valve Tests/5 Years and 20% in 2 Years	7
NRC 148	SGS-PL-V035B	Main Steam Safety Valve Steam Generator 02	Relief	Maintain Close Transfer Open Transfer Close	Active Containment Isolation Remote Position	<u>Class 2</u> <u>Category BC</u>	Remote Position Indication, Alternate/2 Years Class 2/3 Relief Valve Tests/5 Years and 20% in 2 Years	7
NRC 148	SGS-PL-V036A	Steam Line Condensate Drain Isolation	Remote <u>AO</u> <u>GLOBE</u>	Maintain Close Transfer Close	Active-to-Failed Containment Isolation Remote Position	<u>Class 2</u> <u>Category B</u>	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Quarterly Operability Test	31
NRC 148	SGS-PL-V036B	Steam Line Condensate Drain Isolation	Remote <u>AO</u> <u>GLOBE</u>	Maintain Close Transfer Close	Active-to-Failed Containment Isolation Remote Position	<u>Class 2</u> <u>Category B</u>	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Quarterly Operability Test	31
NRC 148	SGS-PL-V040A	Main Steam Line Isolation	Remote <u>Pneumatic</u> <u>Hydraulic</u> <u>GATE</u>	Maintain Close Transfer Close	Active-to-Failed Containment Isolation Remote Position	<u>Class 2</u> <u>Category B</u>	Remote Position Indication, Exercise/2 Years Exercise Part Stroke/Quarterly Exercise Full Stroke/Cold Shutdown Operability Test	20, 31
	SGS-PL-V040B	Main Steam Line Isolation	Remote <u>Pneumatic</u> <u>Hydraulic</u> <u>GATE</u>	Maintain Close Transfer Close	Active-to-Failed Containment Isolation Remote Position	<u>Class 2</u> <u>Category B</u>	Remote Position Indication, Exercise/2 Years Exercise Part Stroke/Quarterly Exercise Full Stroke/Cold Shutdown Operability Test	20, 31

Table 3.9-16 (Sheet 17 of 21)								
VALVE INSERVICE TEST REQUIREMENTS								
NRC 148	Valve Tag Number	Description ⁽¹⁾	Valve/Actuator Type	Safety-Related Missions	Safety Functions ⁽²⁾	ASME Class/IST Category	Inservice Testing Type and Frequency	IST Notes
	SGS-PL-V057A	Main Feedwater Isolation	Remote Pneumatic Hydraulic GATE	Maintain Close Transfer Close	Active-to-Failed Containment Isolation Remote Position	Class 2 Category B	Remote Position Indication, Exercise/2 Years Exercise Part Stroke/Quarterly Exercise Full Stroke/Cold Shutdown Operability Test	20, 31
NRC 148	SGS-PL-V057B	Main Feedwater Isolation	Remote Pneumatic Hydraulic GATE	Maintain Close Transfer Close	Active-to-Failed Containment Isolation Remote Position	Class 2 Category B	Remote Position Indication, Exercise/2 Years Exercise Part Stroke/Quarterly Exercise Full Stroke/Cold Shutdown Operability Test	20, 31
	SGS-PL-V067A	Startup Feedwater Isolation	Remote MO GATE	Maintain Close Transfer Close	Active Containment Isolation Remote Position	Class 2 Category B	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Quarterly Operability Test	31
NRC 148	SGS-PL-V067B	Startup Feedwater Isolation	Remote MO GATE	Maintain Close Transfer Close	Active Containment Isolation Remote Position	Class 2 Category B	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Quarterly Operability Test	31
NRC 148	SGS-PL-V074A	Steam Generator Blowdown Isolation	Remote AO GLOBE	Maintain Close Transfer Close	Active-to-Failed Containment Isolation Remote Position	Class 2 Category B	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Quarterly Operability Test	31
NRC 148	SGS-PL-V074B	Steam Generator Blowdown Isolation	Remote AO GLOBE	Maintain Close Transfer Close	Active-to-Failed Containment Isolation Remote Position	Class 2 Category B	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Quarterly Operability Test	31
NRC 148	SGS-PL-V075A	Steam Generator Series Blowdown Isolation	Remote AO GLOBE	Maintain Close Transfer Close	Active-to-Failed Remote Position	Class 3 Category B	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Quarterly Operability Test	31
NRC 148	SGS-PL-V075B	Steam Generator Series Blowdown Isolation	Remote AO GLOBE	Maintain Close Transfer Close	Active-to-Failed Remote Position	Class 3 Category B	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Quarterly Operability Test	31
NRC 148	SGS-PL-V086A	Steam Line Condensate Drain Control	Remote AO GLOBE	Maintain Close Transfer Close	Active-to-Failed Remote Position	Class 3 Category B	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Quarterly Operation Operability Test	31
NRC 148	SGS-PL-V086B	Steam Line Condensate Drain Control	Remote AO GLOBE	Maintain Close Transfer Close	Active-to-Failed Remote Position	Class 3 Category B	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Quarterly Operability Test	31
NRC 148	SGS-PL-V233A	Power-Operated Relief Valve	Remote AO GLOBE	Maintain Close Transfer Close	Active-to-Failed Remote Position	Class 3 Category B	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Quarterly Operability Test	31
NRC 148	SGS-PL-V233B	Power-Operated Relief Valve	Remote AO GLOBE	Maintain Close Transfer Close	Active-to-Failed Remote Position	Class 3 Category B	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Quarterly Operability Test	31

Table 3.9-16 (Sheet 18 of 21)								
VALVE INSERVICE TEST REQUIREMENTS								
NRC 148	Valve Tag Number	Description ⁽¹⁾	Valve/Actuator Type	Safety-Related Missions	Safety Functions ⁽²⁾	ASME Class/IST Category	Inservice Testing Type and Frequency	IST Notes
NRC 148	SGS-PL-V240A	Main Steam Isolation Valve Bypass Isolation	Remote <u>AO</u> <u>GLOBE</u>	Maintain Close Transfer Close	Active-to-Failed Containment Isolation Remote Position	<u>Class 2</u> <u>Category B</u>	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Quarterly Operability Test	31
NRC 148	SGS-PL-V240B	Main Steam Isolation Valve Bypass Isolation	Remote <u>AO</u> <u>GLOBE</u>	Maintain Close Transfer Close	Active-to-Failed Containment Isolation Remote Position	<u>Class 2</u> <u>Category B</u>	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Quarterly Operability Test	31
NRC 148	SGS-PL-V250A	Main Feedwater Control	Remote <u>AO</u> <u>GLOBE</u>	Maintain Close Transfer Close	Active-to-Failed Remote Position	<u>Class 3</u> <u>Category B</u>	Remote Position Indication, Exercise/2 Years Exercise Part Stroke/Quarterly Operation Exercise Full Stroke/Cold Shutdown Operability Test	25, 31
NRC 148	SGS-PL-V250B	Main Feedwater Control	Remote <u>AO</u> <u>GLOBE</u>	Maintain Close Transfer Close	Active-to-Failed Remote Position	<u>Class 3</u> <u>Category B</u>	Remote Position Indication, Exercise/2 Years Exercise Part Stroke/Quarterly Operation Exercise Full Stroke/Cold Shutdown Operability Test	25, 31
NRC 148	SGS-PL-V255A	Startup Feedwater Control	Remote <u>AO</u> <u>GLOBE</u>	Maintain Close Transfer Close	Active-to-Failed Remote Position	<u>Class 3</u> <u>Category B</u>	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Quarterly Operability Test	31
NRC 148	SGS-PL-V255B	Startup Feedwater Control	Remote <u>AO</u> <u>GLOBE</u>	Maintain Close Transfer Close	Active-to-Failed Remote Position	<u>Class 3</u> <u>Category B</u>	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Quarterly Operability Test	31
NRC 148	VBS-PL-V186	MCR Supply Air Isolation Valve	Remote <u>Electric</u> <u>Hydraulic</u> <u>Butterfly</u>	Maintain Close Transfer Close	Active-to-Failed Remote Position	<u>Class 3</u> <u>Category B</u>	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Quarterly Operability Test	31
	VBS-PL-V187	MCR Supply Air Isolation Valve	Remote <u>Electric</u> <u>Hydraulic</u> <u>Butterfly</u>	Maintain Close Transfer Close	Active-to-Failed Remote Position	<u>Class 3</u> <u>Category B</u>	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Quarterly Operability Test	31
	VBS-PL-V188	MCR Return Air Isolation Valve	Remote <u>Electric</u> <u>Hydraulic</u> <u>Butterfly</u>	Maintain Close Transfer Close	Active-to-Failed Remote Position	<u>Class 3</u> <u>Category B</u>	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Quarterly Operability Test	31
	VBS-PL-V189	MCR Return Air Isolation Valve	Remote <u>Electric</u> <u>Hydraulic</u> <u>Butterfly</u>	Maintain Close Transfer Close	Active-to-Failed Remote Position	<u>Class 3</u> <u>Category B</u>	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Quarterly Operability Test	31
	VBS-PL-V190	MCR Exhaust Air Isolation Valve	Remote <u>Electric</u> <u>Hydraulic</u> <u>Butterfly</u>	Maintain Close Transfer Close	Active-to-Failed Remote Position	<u>Class 3</u> <u>Category B</u>	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Quarterly Operability Test	31

Table 3.9-16 (Sheet 19 of 21)								
VALVE INSERVICE TEST REQUIREMENTS								
NRC 148	Valve Tag Number	Description ⁽¹⁾	Valve/Actuator Type	Safety-Related Missions	Safety Functions ⁽²⁾	ASME Class/IST Category	Inservice Testing Type and Frequency	IST Notes
NRC 148	VBS-PL-V191	MCR Exhaust Air Isolation Valve	Remote Electric <u>Hydraulic</u> <u>Butterfly</u>	Maintain Close Transfer Close	Active-to-Failed Remote Position	<u>Class 3</u> <u>Category B</u>	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Quarterly Operability Test	31
	VES-PL-V001	Air Delivery Isolation Valve	Manual	Maintain Close Transfer Open Maintain Open	Active	<u>Class 3</u> <u>Category B</u>	Exercise Full Stroke/ 2 Years <u>Quarterly</u>	<u>37</u>
	VES-PL-V002A	Pressure Regulating Valve A	Press. Reg.	Throttle Flow	Active	<u>Class 3</u> <u>Category B</u>	Exercise Full Stroke/Quarterly Operability Test	31, <u>38</u>
NRC 148	VES-PL-V002B	Pressure Regulating Valve B	Press. Reg.	Throttle Flow	Active	<u>Class 3</u> <u>Category B</u>	Exercise Full Stroke/Quarterly Operability Test	31, <u>38</u>
	VES-PL-V005A	Air Delivery Isolation Valve A	Remote SO <u>GLOBE</u>	Maintain Open Transfer Open	Active-to-Failed	<u>Class 3</u> <u>Category B</u>	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Quarterly Operability Test	31
NRC 148	VES-PL-V005B	Air Delivery Isolation Valve B	Remote SO <u>GLOBE</u>	Maintain Open Transfer Open	Active-to-Failed	<u>Class 3</u> <u>Category B</u>	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Quarterly Operability Test	31
NRC 148	VES-PL-V022A	Pressure Relief Isolation Valve A	Remote AO <u>Butterfly</u>	Maintain Open Transfer Open	Active-to-Failed	<u>Class 3</u> <u>Category B</u>	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Quarterly Operability Test	31
NRC 148	VES-PL-V022B	Pressure Relief Isolation Valve B	Remote AO <u>Butterfly</u>	Maintain Open Transfer Open	Active-to-Failed	<u>Class 3</u> <u>Category B</u>	Remote Position Indication, Exercise/2 Years Exercise Full Stroke/Quarterly Operability Test	31
	VES-PL-V040A	Air Tank Safety Relief Valve A	Relief	Maintain Close Transfer Open	Active	<u>Class 3</u> <u>Category BC</u>	Class 2/3 Relief Valve Tests/10 Years and 20% in 4 Years	
	VES-PL-V040B	Air Tank Safety Relief Valve B	Relief	Maintain Close Transfer Open	Active	<u>Class 3</u> <u>Category BC</u>	Class 2/3 Relief Valve Tests/10 Years and 20% in 4 Years	
NRC 148	VES-PL-V041A	Air Tank Safety Relief Valve A	Relief	Maintain Close Transfer Open	Active	<u>Class 3</u> <u>Category BC</u>	Class 2/3 Relief Valve Tests/10 Years and 20% in 4 Years	
	VES-PL-V041B	Air Tank Safety Relief Valve B	Relief	Maintain Close Transfer Open	Active	<u>Class 3</u> <u>Category BC</u>	Class 2/3 Relief Valve Tests/10 Years and 20% in 4 Years	
	VES-PL-V044	Main Air Flowpath Isolation Valve	Manual	Maintain Close Transfer Open	Active	<u>Class 3</u> <u>Category B</u>	Exercise Full Stroke/ 2 Years <u>Quarterly</u>	<u>37</u>

Table 3.9-16 (Sheet 20 of 21)								
VALVE INSERVICE TEST REQUIREMENTS								
NRC 148	Valve Tag Number	Description ⁽¹⁾	Valve/Actuator Type	Safety-Related Missions	Safety Functions ⁽²⁾	ASME Class/IST Category	Inservice Testing Type and Frequency	IST Notes
NRC 148	VFS-PL-V003	Containment Purge Inlet Containment Isolation Valve	Remote <u>AO</u> <u>Butterfly</u>	Maintain Close Transfer Close	Active-to-Failed Containment Isolation Safety Seat Leakage Remote Position	<u>Class 2</u> <u>Category A</u>	Remote Position Indication, Exercise/2 Years Containment Isolation Leak Test Exercise Full Stroke/Quarterly Operability Test	27, 31
NRC 148	VFS-PL-V004	Containment Purge Inlet Containment Isolation Valve	Remote <u>AO</u> <u>Butterfly</u>	Maintain Close Transfer Close	Active-to-Failed Containment Isolation Safety Seat Leakage Remote Position	<u>Class 2</u> <u>Category A</u>	Remote Position Indication, Exercise/2 Years Containment Isolation Leak Test Exercise Full Stroke/Quarterly Operability Test	27, 31
NRC 148	VFS-PL-V009	Containment Purge Discharge Containment Isolation Valve	Remote <u>AO</u> <u>Butterfly</u>	Maintain Close Transfer Close	Active-to-Failed Containment Isolation Safety Seat Leakage Remote Position	<u>Class 2</u> <u>Category A</u>	Remote Position Indication, Exercise/2 Years Containment Isolation Leak Test Exercise Full Stroke/Quarterly Operability Test	27, 31
NRC 148	VFS-PL-V010	Containment Purge Discharge Containment Isolation Valve	Remote <u>AO</u> <u>Butterfly</u>	Maintain Close Transfer Close	Active-to-Failed Containment Isolation Safety Seat Leakage Remote Position	<u>Class 2</u> <u>Category A</u>	Remote Position Indication, Exercise/2 Years Containment Isolation Leak Test Exercise Full Stroke/Quarterly Operability Test	27, 31
NRC 148	VWS-PL-V058	Fan Coolers Supply Containment Isolation	Remote <u>AO</u> <u>Butterfly</u>	Maintain Close Transfer Close	Active-to-Failed Containment Isolation Safety Seat Leakage Remote Position	<u>Class 2</u> <u>Category A</u>	Remote Position Indication, Exercise/2 Years Containment Isolation Leak Test Exercise Full Stroke/Quarterly Operability Test	27, 28, 31
NRC 148	VWS-PL-V062	Fan Coolers Supply Containment Isolation	Check	Maintain Close Transfer Close	Active Containment Isolation Safety Seat Leakage	<u>Class 2</u> <u>Category AC</u>	Containment Isolation Leak Test Check Exercise/Quarterly	27, 28
NRC 148	VWS-PL-V082	Fan Coolers Return Containment Isolation	Remote <u>AO</u> <u>Butterfly</u>	Maintain Close Transfer Close	Active-to-Failed Containment Isolation Safety Seat Leakage Remote Position	<u>Class 2</u> <u>Category A</u>	Remote Position Indication, Exercise/2 Years Containment Isolation Leak Test Exercise Full Stroke/Quarterly Operability Test	27, 28, 31
NRC 148	VWS-PL-V086	Fan Coolers Return Containment Isolation	Remote <u>AO</u> <u>Butterfly</u>	Maintain Close Transfer Close	Active-to-Failed Containment Isolation Safety Seat Leakage Remote Position	<u>Class 2</u> <u>Category A</u>	Remote Position Indication, Exercise/2 Years Containment Isolation Leak Test Exercise Full Stroke/Quarterly Operability Test	27, 28, 31
NRC 148	WLS-PL-V055	Sump Discharge Containment Isolation IRC	Remote <u>AO Plug</u>	Maintain Close Transfer Close	Active-to-Failed Containment Isolation Safety Seat Leakage Remote Position	<u>Class 2</u> <u>Category A</u>	Remote Position Indication, Exercise/2 Years Containment Isolation Leak Test Exercise Full Stroke/Quarterly Operation Operability Test	27, 31

Table 3.9-16 (Sheet 21 of 21)								
VALVE INSERVICE TEST REQUIREMENTS								
NRC 148	Valve Tag Number	Description ⁽¹⁾	Valve/Actuator Type	Safety-Related Missions	Safety Functions ⁽²⁾	ASME Class/IST Category	Inservice Testing Type and Frequency	IST Notes
NRC 148	WLS-PL-V057	Sump Discharge Containment Isolation ORC	Remote <u>AO</u> <u>PLUG</u>	Maintain Close Transfer Close	Active-to-Failed Containment Isolation Safety Seat Leakage Remote Position	<u>Class 2</u> <u>Category A</u>	Remote Position Indication, Exercise/2 Years Containment Isolation Leak Test Exercise Full Stroke/Quarterly Operation Operability Test	27, 31
NRC 148	WLS-PL-V067	Reactor Coolant Drain Tank Gas Outlet Containment Isolation IRC	Remote <u>AO</u> <u>GLOBE</u>	Maintain Close Transfer Close	Active-to-Failed Containment Isolation Safety Seat Leakage Remote Position	<u>Class 2</u> <u>Category A</u>	Remote Position Indication, Exercise/2 Years Containment Isolation Leak Test Exercise Full Stroke/Quarterly Operation Operability Test	27, 31
NRC 148	WLS-PL-V068	Reactor Coolant Drain Tank Gas Outlet Containment Isolation ORC	Remote <u>AO</u> <u>GLOBE</u>	Maintain Close Transfer Close	Active-to-Failed Containment Isolation Safety Seat Leakage Remote Position	<u>Class 2</u> <u>Category A</u>	Remote Position Indication, Exercise/2 Years Containment Isolation Leak Test Exercise Full Stroke/Quarterly Operation Operability Test	27, 31
NRC 148	WLS-PL-V071A	CVS Compartment to Sump	Check	Maintain Close Transfer Close	Active	<u>Class 3</u> <u>Category BC</u>	Check Exercise/Refueling Shutdown	26
	WLS-PL-V071B	PXS A Compartment to Sump	Check	Maintain Close Transfer Close	Active	<u>Class 3</u> <u>Category BC</u>	Check Exercise/Refueling Shutdown	26
	WLS-PL-V071C	PXS B Compartment to Sump	Check	Maintain Close Transfer Close	Active	<u>Class 3</u> <u>Category BC</u>	Check Exercise/Refueling Shutdown	26
	WLS-PL-V072A	CVS Compartment to Sump	Check	Maintain Close Transfer Close	Active	<u>Class 3</u> <u>Category BC</u>	Check Exercise/Refueling Shutdown	26
	WLS-PL-V072B	PXS A Compartment to Sump	Check	Maintain Close Transfer Close	Active	<u>Class 3</u> <u>Category BC</u>	Check Exercise/Refueling Shutdown	26
	WLS-PL-V072C	PXS B Compartment to Sump	Check	Maintain Close Transfer Close	Active	<u>Class 3</u> <u>Category BC</u>	Check Exercise/Refueling Shutdown	26

Notes:

1. Acronyms:

ADS automatic depressurization system
CAS compressed and instrument air system
CCS component cooling water system
CVS chemical and volume control system
DWS demineralized water transfer and storage system
FPS fire protection system
IRC inside reactor containment
IRWST in-containment refueling water storage tank
MSS main steam system
MTS main turbine system
ORC outside reactor containment
PCCWST passive containment cooling water storage tank

PCS passive containment cooling system
PSS primary sampling system
PXS passive core cooling system
RCS reactor coolant system
RNS normal residual heat removal system
SFS spent fuel pool cooling system
SGS steam generator system
VBS nuclear island nonradioactive ventilation system
VES main control room emergency habitability system
VFS containment air filtration system
VWS central chilled water system
WLS liquid radwaste system

AO Air Operated
MO Motor Operated
SO Solenoid Operated

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2. Valves listed as having an active or an active-to-failed safety-related function provide the safety-related valve transfer capabilities identified in the safety-related mission column. Valves having an active-to-failed function will transfer to the position identified in the safety-related mission column on loss of motive power. Valves with an active-to-failed function shall be tested by observing the operation of the actuator upon loss of valve actuating power. This ‘fail-safe’ requirement is not otherwise shown and is performed during exercise testing.

3. This note applies to the ADS stage 1/2/3 valves (RCS-V001A/B, V002A/B, V003A/B, V011A/B, V012A/B, V013A/B). These valves are normally closed to maintain the RCS pressure boundary. These valves have a safety-related function to open following LOCAs to allow safety injection from lower pressure water supplies (accumulators and IRWST). These valves also have beyond design basis functions to depressurize the RCS. These valves have the same design pressure as the RCS and are AP1000 equipment class A. Downstream of the second valve is a lower design pressure and is equipment class C. The discharge of these valves is open to the containment through the IRWST.

Both ADS valves in each line are normally closed during normal reactor operation in accordance with 10 CFR 50.2 and ANS/ANSI 51.1. If one of these valves is opened, for example for testing, the RCS pressure boundary is not maintained in accordance with the criteria contained in these two documents. In addition, the ADS valve configuration is similar to the normal residual heat removal system suction valve configuration. Even though the RNS suction valve configuration includes a third valve in the high pressure portion of the line, and the first two RNS valves have safety related functions to transfer closed, they are not stroke tested during normal reactor operation to avoid a plant configuration where the mispositioning of one valve would cause a LOCA. Note 15 describes the justification for testing the RNS valves during cold shutdown.

These ADS valves are tested during cold shutdowns when the RCS pressure is reduced to atmospheric pressure so that mispositioning of a single valve during this IST will not cause a LOCA. Testing these valves every cold shutdown is consistent with the AP1000 PRA which assumes more than 2 cold or refueling shutdowns per year.

4. This note applies to the reactor vessel head vent solenoid valves (RCS-V150A/B/C/D). Exercise testing of these valves at power represents a risk of loss of reactor coolant and depressurization of the RCS if the proper test sequence is not followed. Such testing may also result in the valves developing through seal leaks. Exercise testing of these valves will be performed at cold shutdown.

5. This note applies to squib valves in the RCS and the PXS. The squib valve charge is removed and test fired outside of valve. Squib valves are not exercised for inservice testing. Their position indication sensors will be tested by local inspection.

6. This note applies to the CVS isolation valves (CVS-V001, V002, V003, V080, V081, V082). Closing these valves at power will result in an undesirable temperature transient on the RCS due to the interruption of purification flow. Therefore, quarterly exercise testing will not be performed. Exercise testing will be performed at cold shutdown.

7. This note applies to the pressurizer safety valves (RCS-V005A/B) and to the main steam safety valves (SGS-V030A/B, V031A/B, V032A/B, V033A/B, V034A/B and V035A/B). Since these valves are not exercised for inservice testing, their position indication sensors are tested by local inspection without valve exercise.

8. This note applies to CVS valve (CVS-V081). The safety functions are satisfied by the check valve function of the valve.

9. This note applies to the PXS accumulator check valves (PXS-V028A/B, V029A/B). To exercise these valves, flow must be provided through these valves to the RCS. These valves are not exercised during power operations because the accumulators cannot provide flow to the RCS since they are at a lower pressure. In addition, providing flow to the RCS during power operation would cause undesirable thermal transients on the RCS. During cold shutdowns, a full flow stroke test is impractical because of the potential of adding significant water to the RCS, and lifting the RNS relief valve. There is also a risk of injecting nitrogen into the RCS. A partial stroke test is practical during longer cold shutdowns (≥48 hours in Mode 5). In this test, flow is provided from test connections, through the check valves and into the RCS. Sufficient flow is not available to provide a detectable obturator movement. Full stroke exercise testing of these valves is conducted during refueling shutdowns.

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10. This note applies to the PXS CMT check valves (PXS-V016A/B, V017A/B). These check valves are biased open valves and are fully open during normal operation. These valves will be verified to be open quarterly. In order to exercise these check valves, significant reverse flow must be provided from the DVI line to the CMT. These valves are not tested during power operations because the test would cause undesirable thermal transients on the portion of the line at ambient temperatures and change the CMT boron concentration. These valves are not exercised during cold shutdowns because of changes that would result in the CMT boron concentration. Because this parameter is controlled by Technical Specifications, this testing is impractical. These valves are exercised during refueling when the RCS boron concentration is nearly equal to the CMT concentration and the plant is in a mode where the CMTs are not required to be available by the Technical Specifications.

11. This note applies to the PXS containment recirculation check valves (PXS-V119A/B). Squib valves in line with the check valves prevent the use of IRWST water to test the valves. To exercise these check valves an operator must enter the containment, remove a cover from the recirculation screens, and insert a test device into the recirculation pipe to push open the check valve. The test device is made to interface with the valve without causing valve damage. The test device incorporates loads measuring sensors to measure the initial opening and full open force. These valves are not exercised during power operations because of the need to enter highly radioactive areas and because during this test the recirculation screen is bypassed. These valves are not exercised during cold shutdown operations for the same reasons. These valves are exercised during refueling conditions when the recirculation lines are not required to be available by Technical Specifications LCOs 3.5.7 and 3.5.8 and the radiation levels are reduced.

12. This note applies to the PXS IRWST injection check valves (PXS-V122A/B, V124A/B). To exercise these check valves a test cart must be moved into containment and temporary connections made to these check valves. In addition, the IRWST injection line isolation valves must have power restored and be closed. These valves are not exercised during power operations because closing the IRWST injection valve is not permitted by the Technical Specifications and the need to perform significant work inside containment. Testing is not performed during cold shutdown for the same reasons. These valves are exercised during refueling conditions when the IRWST injection lines are not required to be available by Technical Specifications and the radiation levels are reduced.

13. Deleted.

14. Component cooling water system containment isolation motor-operated valves CCS-V200, V207, V208 and check valve CCS-V201 are not exercised during power operation. Exercising these valves would stop cooling water flow to the reactor coolant pumps and letdown heat exchanger. Loss of cooling water may result in damage to equipment or reactor trip. These valves are exercised during cold shutdowns when these components do not require cooling water.

15. Normal residual heat removal system reactor coolant isolation motor-operated valves (RNS-V001A/B, V002A/B) are not exercised during power operation. These valves isolate the high pressure RCS from the low pressure RNS and passive core cooling system (PXS). Opening during normal operation may result in damage to equipment or reactor trip. These valves are exercised during cold shutdowns when the RNS is aligned to remove the core decay heat.

16. Normal residual heat removal system containment isolation motor-operated valves (RNS-V002A/B) are not containment isolation leak tested. The basis for the exception is:

- The valve is submerged during post-accident operations which prevents the release of the containment atmosphere radiogas or aerosol.
- The RNS is a closed, seismically-designed safety class 3 system outside containment
- The valves are closed when the plant is in modes above hot shutdown

17. Normal residual heat removal system containment penetration relief valve (RNS-V021) and containment isolation motor-operated valve (RNS-V023) are subjected to containment leak testing by pressurizing the lines in the reverse direction to the flow which accompanies a containment leak in this path.

NRC 148	NRC 148	18. This note applies to the CAS instrument air containment isolation valves (CAS-V014, V015). It is not practical to exercise these valves during power operation or cold shutdowns. Exercising the valves during these conditions may result in some air-operated valves inadvertently opening or closing, resulting in plant or system transients. These valves are exercised during refueling conditions when system and plant transients would not occur.	28. This note applies to the chilled water system containment isolation valves (VWS-V058, V062, V082 and V086). Closing any of these valves stops the water flow to the containment fan coolers. This water flow may be necessary to maintain the containment air temperature within Technical Specification limits. As a result, quarterly exercise testing will be deferred when plant operating conditions and site climatic conditions would cause the containment air temperature to exceed this limit during testing.
		19. Primary sampling system containment isolation check valve (PSS-V024) is located inside containment and considerable effort is required to install test equipment and cap the discharge line. Exercise testing is not performed during cold shutdown operations for the same reasons. These valves are exercised during refueling conditions when the radiation levels are reduced.	29. Exercise testing of the turbine bypass control valves (MSS-V001, V002, V003, V004, V005 and V006) will result in an undesirable temperature transient on the turbine, condenser and other portions of the turbine bypass due to the actuation of bypass flow. Therefore, quarterly exercise testing will not be performed. Exercise testing will be performed during cold shutdowns.
NRC 148	NRC 148	20. This note applies to the main steam isolation valves and main feedwater isolation valves (SGS-V040A/B, V057A/B). The valves are not full stroke tested quarterly at power since full valve stroking will result in a plant transient during normal power operation. Therefore, these valves will be partially stroked on a quarterly basis and will be full stroke tested on a cold shutdown frequency basis. The full stroke testing will be a full “slow” closure operation. The large size and fast stroking nature of the valve makes it advantageous to limit the number of fast closure operations which the valve experiences. The timed slow closure <u>supports the continued verification of the valves operability status of the valves in the intervals between fast closure tests and ensures</u> that the valve is not mechanically bound.	30. Deleted.
		21. Post-72 hour check valves that require temporary connections for inservice-testing are exercised every refueling outage. These valves require transport and installation of temporary test equipment and pressure/fluid supplies. Since the valves are normally used very infrequently, constructed of stainless steel, maintained in controlled environments, and of a simple design, there is little benefit in testing them more frequently. For example, valve PCS-V039 is a simple valve that is opened to provide the addition of water to the PCS post-72 hour from a temporary water supply. To exercise the valve, a temporary pump and water supply is connected using temporary pipe and fittings, and the flow rate is observed using a temporary flow measuring device to confirm valve operation.	31. These valves may be subject to operability testing. See subsection 3.9.6.2.2 for the factors to be considered in the evaluation of operability testing and subsection 3.9.8.4 for the Combined License information item. The specified frequency for operability testing is a maximum of once every 10 years. The test frequency is the longer of every 3 refueling cycles or 5 years until sufficient data exists to determine a longer test frequency is appropriate in accordance with Generic Letter 96-05. Some of the valves will be tested the first time after a shorter period to provide for trending information.
NRC 148	NRC 148	22. Exercise testing of the auxiliary spray isolation valve (CVS-V084, V085) will result in an undesirable temperature transient on the pressurizer due to the actuation of auxiliary spray flow. Therefore, quarterly exercise testing will not be performed. Exercise testing will be performed during cold shutdowns.	32. These valves are subject to leak testing to support the nonsafety-related classification of the CVS purification subsystem inside containment. These valves are not included in the PIV integrity Technical Specification 3.4.16. The leakage through valves CVS-V001, CVS-V002, and CVS-V080 will be tested separately with a leakage limit of 1.5 gpm for each valve. The leakage through valves CVS-V081, V082, V084, and V085 will be tested at the same time as a group with a leakage limit of 1 gpm for the group. The leak tests will be performed at reduced RCS pressures. The observed leakage at lower pressures can be assumed to be the leakage at the maximum pressure as long as the valve leakage is verified to diminish with increasing pressure differential. Verification that the valves have the characteristic of decreasing leakage with pressure may be provided with two tests at different test pressures. The test requirements including the minimum test pressure and the difference between the test pressures will be defined by the Combined License applicant in the inservice test program as discussed in subsection 3.9.8.
		23. Thermal relief check valves in the normal residual heat removal suction line (RNS-V003A/B) and the Chemical and Volume Control System makeup line (CVS-V100) are located inside containment. To exercise test these valves, entry to the containment is required and temporary connections made to gas supplies. Because of the radiation exposure and effort required, this test is not conducted during power operation or during cold shutdowns. Exercise testing is performed during refueling shutdowns.	33. This note applies to valve FHS-V001. This valve closes one end of the fuel transfer tube. The fuel transfer tube is normally closed by a flange except during refuelings. This valve has an active safety function to close when the fuel transfer tube flange is removed and normal shutdown cooling is lost. Closing this valve, along with other actions, provides containment closure which allows long term core cooling to be provided by the PXS. As a result this valve is only required to be operable during refueling operations. The exercise testing of this valves will be performed during refueling shutdowns prior to removing the fuel transfer tube flange.
NRC 148	NRC 148	24. Normal residual heat removal system reactor coolant isolation check valves (RNS-V015A/B, V017A/B) are not exercise tested quarterly. During normal power operation these valves isolate the high pressure RCS from the low pressure RNS. Opening during normal operation would require a pressure greater than the RCS normal pressure, which is not available. It would also subject the RCS connection to undesirable transients. These valves will be exercised during cold shutdowns.	34. This note applies to the moisture separator reheater steam control valve (MSS-V016A/B), turbine control valves (MTS-V002A/B, V004A/B), main turbine stop valves (MTS-V001A/B, V003A/B), the turbine bypass control valves (MSS-V001, V002, V003, V004, V005, V006). These valves are not <u>ASME Code Class 1, 2 or 3 and the ASME 1ST Category is indicated based on the valve functions listed</u> safety-related . These valves are relied on in the safety analyses for those cases in which the rupture of the main steam or feedwater piping inside containment is the postulated initiating event. These valves are credited in single failure analysis to mitigate the event.
		25. This note applies to the main feedwater control valves (SGS-V250A/B), moisture separator reheater steam control valve (MSS-V016A/B), turbine control valves (MTS-V002A/B, V004A/B). The valves are not quarterly stroke tested since full stroke testing would result in a plant transient during power operation. Normal feedwater and turbine control operation provides a partial stroke confirmation of valve operability. The valves will be full stroke tested during cold shutdowns.	35. This note applies to the turbine stop valves (MTS-V001A/B, V003A/B). The valves are not quarterly stroke tested since full stroke testing would result in a plant transient during power operation. The valves will be full stroke tested during cold shutdowns. <u>See Note 34 above.</u>
NRC 148	NRC 148	26. This note applies to containment compartment drain line check valves (SFS-V071, SFS-V072, WLS-V071A/B/C, WLS-V072A/B/C). These check valves are located inside containment and require temporary connections for exercise testing. Because of the radiation exposure and effort required, these valves are not exercised during power operation or during cold shutdowns. The valves will be exercised during refuelings.	36. In each of the four turbine inlet lines, there is a turbine stop valve and turbine control valve. Only one of the valves in each of the four lines is required by Technical Specification 3.7.2 to be operable.
		27. Containment isolation valves leakage test frequency will be conducted in accordance with the “Primary Containment Leakage Rate Test Program” in accordance with 10 CFR 50 Appendix J. Refer to SSAR subsection 6.2.5.	37. <u>Active Category A and B manual valves are exercised once every two years in accordance with 10 CFR 50.55a(b)(3)(vi).</u> 38. <u>The exercise stroke test for the VES pressure regulating valves is the stroke distance sufficient to provide the pressure regulating function.</u>

Table 3.9-17			
SYSTEM LEVEL OPERABILITY TEST REQUIREMENTS			
System/Feature	Test Purpose	Test Method	Tech Spec ^a
PCS			
PCCWST drain lines	Flow capability and water coverage	Note 1	SR 3.6.6.6
PXS			
Accumulator injection lines	Flow capability	Note 2	SR 3.5.1.6
CMT injection lines	Flow capability	Note 3	SR 3.5.2.7
PRHR HX	Heat transfer capability	Note 4	SR 3.5.4.6
IRWST injection lines	Flow capability	Note 5	SR 3.5.6.9
Containment recirculation lines	Flow capability	Note 6	SR 3.5.6.9
VES			
MCR isolation/makeup	MCR pressurization capability	Note 7	SR 3.7.6.10

Alpha Note:

- a. Refer to the Technical Specification surveillance identified in this column for the test frequency.

Notes:

- The flow capability of each PCS water drain line is demonstrated by conducting a test where water is drained from the PCS water storage tank onto the containment shell by opening two of the three parallel isolation valves. During this flow test the water coverage is also demonstrated. The test is terminated when the flow measurement is obtained and the water coverage is observed. The minimum allowable flow rate is 469.1 gpm with the passive containment cooling water storage tank level 27.3 feet above the lowest standpipe. The test may be run with a higher water level and the test results adjusted for the increased level. Water coverage is demonstrated by visual inspection that there is unobstructed flow from the lower weirs. In addition, at least four air baffle panels will be removed at the containment vessel spring line, approximately 90 degrees apart, to permit visual inspection of the water coverage and the vessel coating. The water coverage observed at these locations will be compared against the coverage measured at the same locations during pre-operational testing (see item 7.(b)(i) of ITAAC Table 2.2.2-6).
- The flow capability of each accumulator is demonstrated by conducting a test during cold shutdown conditions. The initial conditions of the test include reduced accumulator pressure. Flow from the accumulator to the RCS is initiated by opening the accumulator isolation valve. Sufficient flow is provided to fully open the check valves. The test is terminated when the flow measurement is obtained. The allowable calculated flow resistance between each accumulator and the reactor vessel is $\geq 1.47 \times 10^{-5}$ ft/gpm² and $\leq 1.83 \times 10^{-5}$ ft/gpm².
- The flow capability of each CMT is demonstrated by conducting a test during cold shutdown conditions. The initial conditions of the test include the RCS loops drained to a level below the top of the RCS hot leg. Flow from the CMT to the RCS is initiated by opening one CMT isolation valve. The test is terminated when the flow measurement is obtained. The allowable calculated flow resistance between each CMT and the reactor vessel is $\geq 1.83 \times 10^{-5}$ ft/gpm² and $\leq 2.25 \times 10^{-5}$ ft/gpm².

Table 3.11-1 (Sheet 26 of 50)

ENVIRONMENTALLY QUALIFIED ELECTRICAL AND MECHANICAL EQUIPMENT

Description	AP1000 Tag No.	Envir. Zone (Note 2)	Function (Note 1)	Operating Time Required (Note 5)	Qualification Program (Note 6)
IRWST Suction Line Isolation	RNS-PL-V023	1	ESF	5 min	M *
Limit Switch	RNS-PL-V023-L	1	PAMS	1 yr	E *
Motor Operator	RNS-PL-V023-M	1	ESF	5 min	E *
RNS HX A Channel Head Drain	RNS-PL-V046A	6	ESF	1 yr	M **
RNS – CVS Containment Isolation	RNS-PL-V061	1	ESF	5 min	M *
Limit Switch	RNS-PL-V061-L	1	PAMS	1 yr	E *
Air Motor Operator	RNS-PL-V061-SM	1	ESF	5 min	E *
Containment Isolation	SFS-PL-V034	1	ESF	5 min	M *
Limit Switch	SFS-PL-V034-L	1	PAMS	1 yr	E *
Motor Operator	SFS-PL-V034-M	1	ESF	5 min	E *
Containment Isolation	SFS-PL-V035	6	ESF	5 min	M S **
Limit Switch	SFS-PL-V035-L	6	PAMS	2 wks	E **
Motor Operator	SFS-PL-V035-M	6	ESF	5 min	E **
SFS Discharge Containment Isolation	SFS-PL-V037	1	ESF	5 min	M *
Containment Isolation	SFS-PL-V038	6	ESF	5 min	M S **
Limit Switch	SFS-PL-V038-L	6	PAMS	2 wks	E **
Motor Operator	SFS-PL-V038-M	6	ESF	5 min	E **
Spent Fuel Pool to Cask Washdown Pit Isolation	SFS-PL-V066	6	ESF	2 wks	M **
Cask Washdown Pit Drain Isolation	SFS-PL-V068	6	ESF	2 wks	M **
Refueling Cavity to SG Compartment	SFS-PL-V071	1	ESF	2 wks	M *
Refueling Cavity to SG Compartment	SFS-PL-V072	1	ESF	2 wks	M *
PORV Block Valve	SGS-PL-V027A	5	ESF	5 min	M *
Limit Switch	SGS-PL-V027A-L	5	PAMS	2 wks	E *
Motor Operator	SGS-PL-V027A-M	5	ESF	5 min	E *
PORV Block Valve	SGS-PL-V027B	5	ESF	5 min	M *
Limit Switch	SGS-PL-V027B-L	5	PAMS	2 wks	E *
Motor Operator	SGS-PL-V027B-M	5	ESF	5 min	E *
Steam Safety Valve SG01	SGS-PL-V030A	5	ESF	5 min	M *
Limit Switch	SGS-PL-V030A-L	5	PAMS	2 wks	E * +
Steam Safety Valve SG02	SGS-PL-V030B	5	ESF	5 min	M *
Limit Switch	SGS-PL-V030B-L	5	PAMS	2 wks	E * +
Steam Safety Valve SG01	SGS-PL-V031A	5	ESF	5 min	M *
Limit Switch	SGS-PL-V031A-L	5	PAMS	2 wks	E * +
Steam Safety Valve SG02	SGS-PL-V031B	5	ESF	5 min	M *
Limit Switch	SGS-PL-V031B-L	5	PAMS	2 wks	E * +

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ENVIRONMENTALLY QUALIFIED ELECTRICAL AND MECHANICAL EQUIPMENT					
Description	AP1000 Tag No.	Envir. Zone (Note 2)	Function (Note 1)	Operating Time Required (Note 5)	Qualification Program (Note 6)
Containment Purge Discharge Isolation	VFS-PL-V009	1	ESF	5 min	M *
Limit Switch	VFS-PL-V009-L	1	PAMS	1 yr	E *
Solenoid Valve	VFS-PL-V009-S1	1	ESF	5 min	E *
Containment Purge Discharge Isolation	VFS-PL-V010	6	ESF	5 min	M S **
Limit Switch	VFS-PL-V010-L	6	PAMS	2 wks	E **
Solenoid Valve	VFS-PL-V010-S1	6	ESF	5 min	E **
Fan Cooler Supply Isolation	VWS-PL-V058	2	ESF	5 min	M S
Limit Switch	VWS-PL-V058-L	2	PAMS	2 wks	E
Solenoid Valve	VWS-PL-V058-S	2	ESF	5 min	E
Fan Cooler Supply Isolation	VWS-PL-V062	1	ESF	5 min	M *
Fan Cooler Return Isolation	VWS-PL-V082	1	ESF	5 min	M *
Limit Switch	VWS-PL-V082-L	1	PAMS	1 yr	E *
Solenoid Valve	VWS-PL-V082-S	1	ESF	5 min	E *
Fan Cooler Return Isolation	VWS-PL-V086	2	ESF	5 min	M S
Limit Switch	VWS-PL-V086-L	2	PAMS	2 wks	E
Solenoid Valve	VWS-PL-V086-S	2	ESF	5 min	E
Sump Containment Isolation IRC	WLS-PL-V055	1	ESF	5 min	M *
Limit Switch	WLS-PL-V055-L	1	PAMS	1 yr	E *
Solenoid Valve	WLS-PL-V055-S1	1	ESF	5 min	E *
Sump Containment Isolation ORC	WLS-PL-V057	7	ESF	5 min	M S **
Limit Switch	WLS-PL-V057-L	7	PAMS	2 wks	E **
Solenoid Valve	WLS-PL-V057-S1	7	ESF	5 min	E **
RCDT Gas Containment Isolation	WLS-PL-V067	1	ESF	5 min	M *
Limit Switch	WLS-PL-V067-L	1	PAMS	1 yr	E *
Solenoid Valve	WLS-PL-V067-S	1	ESF	5 min	E *
RCDT Gas Containment Isolation	WLS-PL-V068	7	ESF	5 min	M S **
Limit Switch	WLS-PL-V068-L	7	PAMS	2 wks	E **
Solenoid Valve	WLS-PL-V068-S	7	ESF	5 min	E **
CVS To Sump	WLS-PL-V071 A	1	ESF	2 wks	M *
PXS A To Sump	WLS-PL-V071 B	1	ESF	2 wks	M *
PXS B To Sump	WLS-PL-V071 C	1	ESF	2 wks	M *
CVS To Sump	WLS-PL-V072 A	1	ESF	2 wks	M *
PXS A To Sump	WLS-PL-V072 B	1	ESF	2 wks	M *
PXS B To Sump	WLS-PL-V072 C	1	ESF	2 wks	M *

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3D.6.2.3.9 Qualification Documentation

The qualification of the mechanical equipment to the postulated environments is documented in an auditable form. See subsection 3D.7.

3D.6.3 Operating Experience

Qualification by experience is typically not employed in the AP1000 equipment qualification program as a prime method of qualification. Operating experience provides supportive evidence to the prime method of qualification. For those instances where seismic experience data are to be used, the Combined License applicant will provide documentation of the methodology. Where such information is provided, it is demonstrated that the experience is applicable to the safety-related functional requirements of the equipment. This demonstration of applicability includes an evaluation of operating environments, mountings, performance requirements, and performance history. Requirements for the documentation of qualification via experience are discussed in subsection 3D.7.6.

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3D.6.4 On-Going Qualification

The AP1000 equipment qualification program may employ on-going qualification through special maintenance and surveillance activities. However, this method of qualification is not suitable as a sole means for qualifying equipment for design basis event conditions. On-going qualification, as a method, is used exclusively for safety-related equipment located in a mild environment area. Such use requires supplementary test, analysis, or experience data to address equipment operability and performance during and after a seismic design basis event.

Documentation requirements for qualification that includes on-going qualification as a method are developed to conform with NRC guidance provided in Regulatory Guide 1.33, Revision 2.

3D.6.5 Combinations of Methods

Qualification by a combination of the preceding methods is used whenever qualification by type test is not the sole basis of qualification under the AP1000 equipment qualification program. If analysis is used, justification includes identifying a test or experience bases, and addressing concerns related to departure from the required type test sequence.

3D.6.5.1 Use of Existing Qualification Reports

Pre-existing qualification programs and documents are used only if the seismic test program satisfies the guidelines of IEEE 344-1987 and the environmental qualification program satisfies the guidelines of IEEE 323-1974.

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Qualification test and analysis reports conforming to those IEEE Standards, but not specifically performed to the AP1000 equipment qualification program parameters, may be acceptable as qualification bases. In such cases, supplementary qualification efforts described in subsections 3D.6.2, 3D.6.3, and 3D.6.4 of this appendix may be required to validate acceptability under the AP1000 equipment qualification program. Justifications are documented as analyses, and appear in equipment qualification data package, Section 4.0. (See Attachment A.)

4.Y.2 Component Identification

{Per Subsection 6.2.3.1}

4.Y.3 Safety Related Functions

{Per Subsection 6.2.3.2}

4.Y.4 Component Acceptance Criteria

{Per Subsection 6.2.3.3}

4.Y.5 Service Conditions

{Per Subsection 6.2.3.4}

4.Y.6 Potential Failure Modes

{Per Subsection 6.2.3.5}

4.Y.7 Identify the Environmental Effects on Material Properties

Each non-metallic, including lubricants, is evaluated to determine the effect of the environmental conditions on the material properties. For each non-metallic, a radiation threshold level and maximum service temperature is identified.

The radiation threshold level and the maximum service temperature are identified using materials handbooks, textbooks, government and industry reports, and laboratory data. If the evaluation indicates that the lowest levels may be exceeded for certain equipment, higher levels are identified at which varying degrees of material degradation may occur.

Mechanical equipment is highly resistive to degradation due to elevated humidity levels: therefore, relative humidity is not included as a parameter to be evaluated for environmental qualification. Pressure can be discounted for most equipment types, as there are no foreseen failures due to elevated pressure levels for most mechanical equipment. However, pressure must be addressed in the evaluation.

The susceptibility of the non-metallic material to the chemicals due to the design basis accident and exposure to the process fluid is evaluated. The material information in the chemical handbooks is an acceptable source of qualification documentation.

4.Y.7.1 Perform Thermal Aging Analysis

Aging analysis is performed for organic materials. Mineral-based subcomponents are not considered to be sensitive to thermal aging during the design life of a plant and, therefore, are not analyzed.

Aging in mechanical components is associated with corrosion, erosion, particle deposits and embrittlement. In new construction, corrosion and erosion are considered by providing additional material thickness as a corrosion or erosion allowance above the required design. The other aging phenomena are considered during inservice inspections of operating components in accordance with as contained in plant technical specifications and ASME Code, Section XI. Aging qualification of metallic parts of equipment except for corrosion and erosion is in compliance with ASME Code, Section XI, therefore aging effects on metallic components are not addressed herein.

The non-metallic material analysis for determining the expected qualified thermal life is performed using Arrhenius methodology. The thermal input during the operating time, as explained below, is deducted from the tested thermal aging of the material at service temperature to obtain the qualified life.

The component is evaluated for the specified post-accident operating time. The thermal input from the postulated accident profile (i.e., LOCA/MSLB) for the duration of the specified operating time is compared to the material thermal aging data. The Arrhenius model is used to perform this comparison. The component is evaluated for the maximum post-accident operating time unless a system analysis is performed to justify shorter operating times.

APPENDIX 3G NUCLEAR ISLAND SEISMIC ANALYSES

3G.1 Introduction

This appendix summarizes the seismic analyses of the nuclear island building structures performed to support the AP1000 design certification extension from just hard rock sites, to sites ranging from soft soils to hard rock. The seismic Category I building structures consist of the containment building (the steel containment vessel [SCV] and the containment internal structures [CIS]), the shield building, and the auxiliary building. These structures are founded on a common basemat and are collectively known as the nuclear island or nuclear island structures. Key dimensions of the seismic Category I building structures, such as thickness of the basemat, floor slabs, roofs and walls, are shown in Figures 3.7.1-14 and 3.7.2-12.

Analyses were performed in accordance with the criteria and methods described in Section 3.7. Section 3G.2 describes the development of the finite element models. Section 3G.3 describes the soil structure interaction analyses of a range of site parameters and the selection of the parameters used in the design analyses. Section 3G.4 describes the fixed base and soil structure interaction dynamic analyses and provides typical results from these dynamic analyses. In Reference 3 are provided a summary of dynamic and seismic analysis results (i.e., modal model properties, accelerations, displacements response spectra) and the nuclear island liftoff analyses.

The seismic analyses of the nuclear island are summarized in a seismic analysis summary report. Deviations from the design due to as-procured or as-built conditions are acceptable based on an evaluation consistent with the methods and procedures of Sections 3.7 and 3.8 provided the following acceptance criteria are met:

- The structural design meets the acceptance criteria specified in Section 3.8.
- The seismic floor response spectra (FRS) meet the acceptance criteria specified in subsection 3.7.5.4.

Depending on the extent of the deviations, the evaluation may range from documentation of an engineering judgment to performance of a revised analysis and design. The results of the evaluation will be documented in an as-built summary report by the Combined License applicant.

Table 3G.1-1 and Figure 3G.1-1 summarize the types of models and analysis methods that are used in the seismic analyses of the nuclear island, as well as the type of results that are obtained and where they are used in the design. Table 3G.1-2 summarizes the dynamic analyses performed and the methods used for combination of modal responses and directional input.

3G.2 Nuclear Island Finite Element Models

The AP1000 nuclear island consists of three distinct seismic Category I structures founded on a common basemat. The three building structures that make up the nuclear island are the coupled auxiliary and shield building (ASB), the SCV, and the CIS. The shield building and the auxiliary building are monolithically constructed with reinforced concrete and, therefore, considered one structure. The nuclear island is embedded approximately 40 feet with the bottom of basemat at

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includes a surrounding layer of excavated soil and the existing soil media as shown in Figures 3G.4-3 and 3G.4-4. Acceleration time histories and floor response spectra are obtained. Adjacent structures have a negligible effect on the nuclear island structures and, thus, are not considered in the 3D SASSI analyses.

In these analyses, the three components of ground motions (N-S, E-W, and vertical direction) are input separately. Each design acceleration time history (N-S, E-W, and vertical) is applied separately, and the time history responses are calculated at the required nodes. The resulting co-linear time history responses at a node due to the three earthquake components are then combined algebraically.

3G.4.3 Seismic Analysis ~~Dynamic Results~~

3G.4.3.1 Response Spectrum Analysis

The response spectrum methodology used in the AP1000 design employs the Complete Quadratic Combination (CQC, Section 1.1 of Reference 5) grouping method for closely spaced modes with the Der Kiureghian Correlation Coefficient (Section 1.1.3 of Reference 5) used for correlation between modes. The Lindley-Yow (Section 1.3.2, Reference 5) spectra analysis methodology is employed for modes with both periodic and rigid response components. The modal analysis performed to develop composite modal participation is used to develop input for the response spectrum analysis. Modes ranging from 0 to 33 Hz or higher are considered. For modes above the cutoff frequency, the Lindley-Yow is used. The Static ZPA Method (Section 1.4.2, Reference 5) is employed for the residual rigid response component for each mode as outlined in NRC Reg. Guide 1.92 (Reference 5). The complete solution is developed via Combination Method B (Section 1.5.2, Reference 5). The combined effects, considering three spatial components of an earthquake (N-S, E-W, and Vertical), are combined by square root sum of the squares method (Section 2.1, Reference 5).

3G.4.3.2 Absolute Accelerations

The seismic analyses results, which include the new shield building configuration described in Section 3.8, are given in Reference 3.

3G.4.3.3 Seismic Response Spectrum

The AP1000 plant floor response spectrum for the six key locations are provided in Figure 3G.4-5X to 3G.4-10Z. the bay locations are defined in Table 3G.4-1.

3G.5 References

1. NUREG-800, Review of Safety Analysis Reports for Nuclear Power Plants, Section 3.7.2, Seismic System Analysis, Revision 2.
2. GW-GL-700, AP600 Design Control Document, Appendices 2A and 2B, Revision 4.

3. APP-GW-S2R-010, "Extension of Nuclear Island Seismic Analyses to Soil Sites," Revision 1, Westinghouse Electric Company LLC.
4. APP-GW-GLN-112, "Structural Verification for Enhanced Shield Building," Westinghouse Electric Company LLC.
5. U.S. NRC Regulatory 1.92, Rev. 2, "Combining Modal Responses and Spatial Components in Seismic Analysis."

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Table 3G.1-1 (Sheet 1 of 3)

SUMMARY OF MODELS AND ANALYSIS METHODS

Model	Analysis Method	Program	Type of Dynamic Response/Purpose
3D (ASB) solid-shell model	-	ANSYS	Creates the finite element mesh for the ASB finite element model.
3D (CIS) solid-shell model	-	ANSYS	Creates the finite element mesh for the CIS finite element model.
3D finite element model including shield building roof (ASB10)	-	ANSYS	ASB portion of NI10.
3D finite element model including dish below containment vessel	<u>Response spectrum analysis</u> Equivalent static analysis using accelerations from time history analyses	ANSYS	CIS portion of NI10. To obtain SSE member forces for the containment internal structures.
3D finite element shell model of nuclear island [NI10] (coupled <u>auxiliary and shield building</u> ASB-shell model, containment internal structures, <u>steel containment vessel</u> SCV, polar crane, <u>RCL</u> reactor coolant loop, pressurizer, and <u>CMT</u> core makeup tanks)	Mode superposition time history analysis	ANSYS	Performed for hard rock profile for ASB with CIS as superelement and for CIS with ASB as superelement. To develop time histories for generating plant design floor response spectra for nuclear island structures. To obtain maximum absolute nodal accelerations (ZPA) to be used in equivalent static analyses. To obtain maximum displacements relative to basemat. To obtain maximum member forces and moments in selected elements for comparison to equivalent static results.

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NRC 011 NRC 041	3D finite element coarse shell model of <u>auxiliary and shield building ASB</u> and containment internal structures [NI20] (including <u>steel containment vessel SCV</u> , polar crane, <u>RCL reactor coolant loop</u> , and pressurizer)	Mode superposition time history analysis	ANSYS	Performed for hard rock profile for comparisons against more detailed NI10 model.
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Table 3G.1-1 (Sheet 2 of 3)				
SUMMARY OF MODELS AND ANALYSIS METHODS				
	Model	Analysis Method	Program	Type of Dynamic Response/Purpose
NRC 011 NRC 041	Finite element lumped-mass stick model of nuclear island.	Time history analysis	SASSI	Performed 2D <u>parametric soil structure interaction</u> studies to help establish the bounding generic soil conditions <u>and to develop loads for overturning and stability evaluation.</u>
	Finite element lumped mass stick model of nuclear island.	Time history analysis	ANSYS	Performed 2D linear and non-linear seismic analyses to evaluate effect of lift off on Floor Response Spectra and bearing.
NRC 011 NRC 041	3D finite element coarse shell model of <u>auxiliary and shield building ASB</u> and containment internal structures [NI20] (including <u>steel containment vessel SCV</u> , polar crane, <u>RCL reactor coolant loop</u> , and pressurizer)	Time history analysis	SASSI	<p>Performed for the three soil profiles of firm rock, upper bound soft-to-medium soil, and soft-to-medium soil.</p> <p>To develop time histories for generating plant design floor response spectra for nuclear island structures.</p> <p>To obtain maximum absolute nodal accelerations (ZPA) to be used in equivalent static analyses.</p> <p>To obtain maximum displacements relative to basemat.</p> <p>To obtain maximum member forces and moments in selected elements for comparison to equivalent static results.</p>

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NRC 011 NRC 041	3D shell of revolution model of <u>steel containment vessel</u> SCV	Model analysis; equivalent static analysis using accelerations from time history analyses	ANSYS	To obtain dynamic properties. To obtain SSE stresses for the containment vessel.
NRC 011 NRC 041	3D lumped-mass stick model of the SCV	-	ANSYS	Used in the NI10 and NI20 models.
NRC 011 NRC 041	3D lumped-mass stick model of the <u>RCL reactor coolant loop</u>	-	ANSYS	Used in the NI10 and NI20 models.
NRC 011 NRC 041	3D lumped-mass stick model of the pressurizer	-	ANSYS	Used in the NI10 and NI20 models.

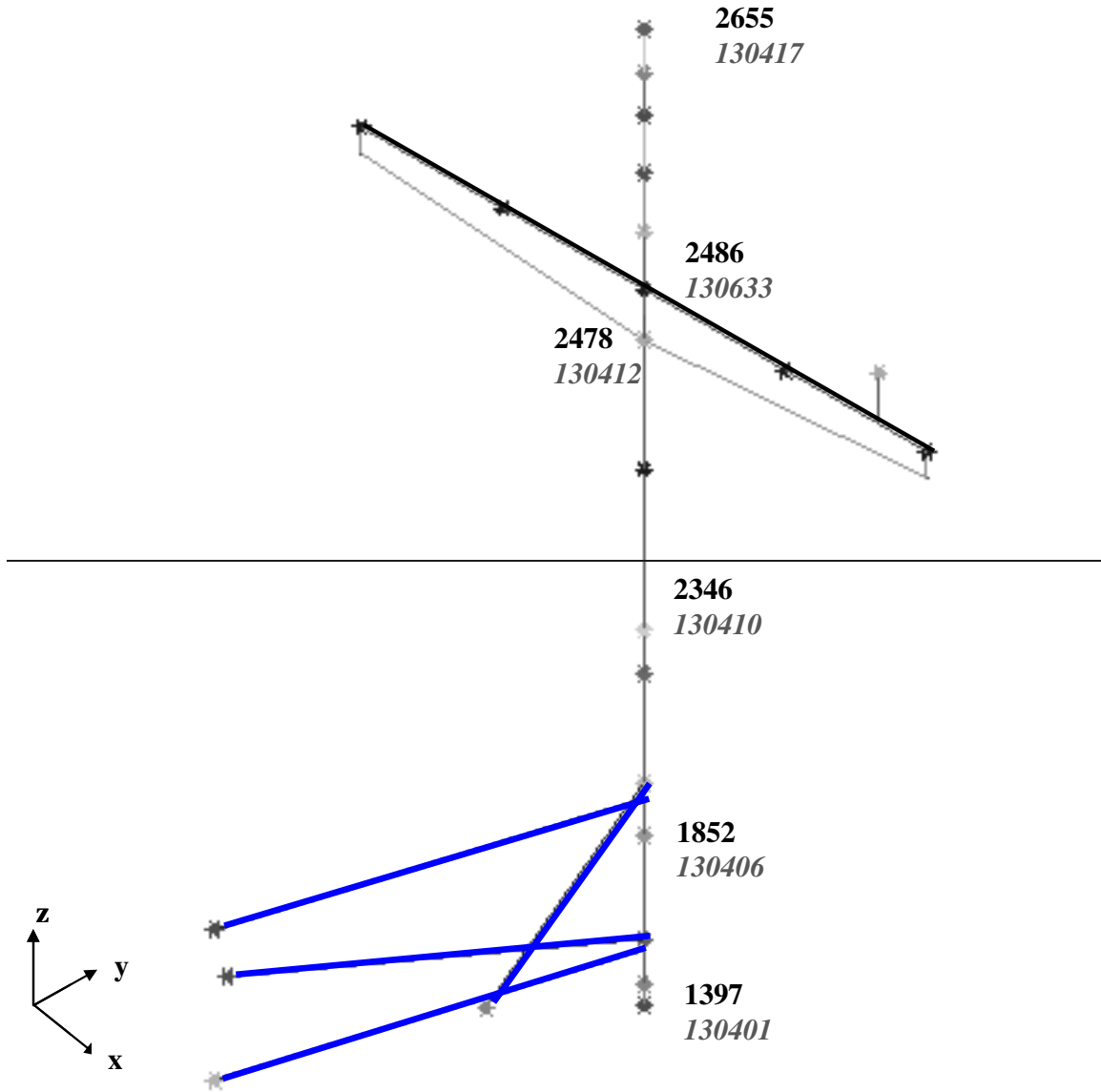
Table 3G.1-1 (Sheet 3 of 3)

SUMMARY OF MODELS AND ANALYSIS METHODS

Model	Analysis Method	Program	Type of Dynamic Response/Purpose
Static Analyses			
3D lumped-mass stick model of the CMT core makeup tank	-	ANSYS	Used in the NI10 model.
3D lumped mass detailed model of the polar crane	Modal analysis	ANSYS	To obtain dynamic properties. Used with 3D finite element shell model of the containment vessel.
3D lumped mass simplified (single beam) model of the polar crane.		ANSYS	Used in the NI10 and NI20 models.
3D finite element shell model of containment vessel ⁽¹⁾	Mode superposition time history analysis; static analysis; response spectrum analysis.	ANSYS	Used with detailed polar crane model to obtain acceleration response of equipment hatch and airlocks. To obtain shell stresses in vicinity of the large penetrations of the containment vessel.
<u>Static and Response Spectrum Analyses</u>			
3D finite element refined shell model of ASB (ASB05)	Equivalent static analysis using accelerations from time history analyses	ANSYS	To obtain SSE member forces for the ASB.
3D finite element model of the shield building roof	Equivalent static analysis using accelerations from time history analyses	GT-STRUDL	To obtain SSE member forces for the shield building roof.
3D finite element refined shell model of nuclear island (NI05)	Equivalent static non-linear analysis using accelerations from time history analyses; response spectrum analysis	ANSYS	To obtain SSE member forces for the nuclear island basemat.

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Table 3G.4-1		
<u>KEY NODES AT LOCATION</u>		
<u>Location</u>	<u>General Area</u>	<u>Elevation (feet)</u>
<u>CIS at Reactor Vessel Support Elevation</u>	<u>SCV Center</u>	<u>100.00</u>
<u>CIS at Operating Deck</u>	<u>SG West Compartment, NE</u>	<u>134.25</u>
<u>ASB NE Corner at Control Room Floor</u>	<u>NE Corner</u>	<u>116.50</u>
<u>ASB Corner of Fuel Building Roof at Shield Building</u>	<u>NW Corner of Fuel Bldg</u>	<u>179.19</u>
<u>ASB Shield Building Roof Area</u>	<u>South Side of Shield Bldg</u>	<u>327.41</u>
<u>SCV Near Polar Crane</u>	<u>SCV Stick Model</u>	<u>224.00</u>



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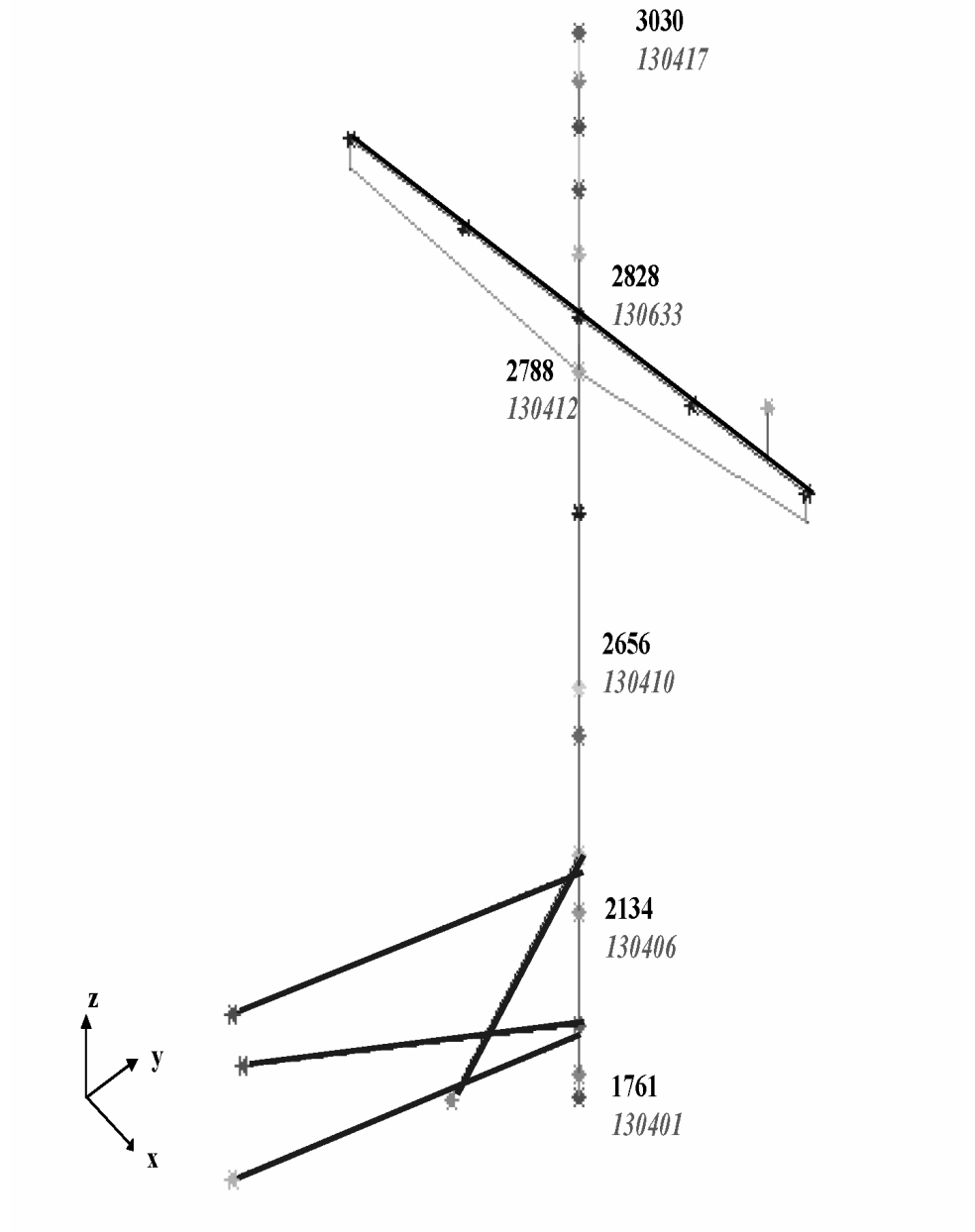
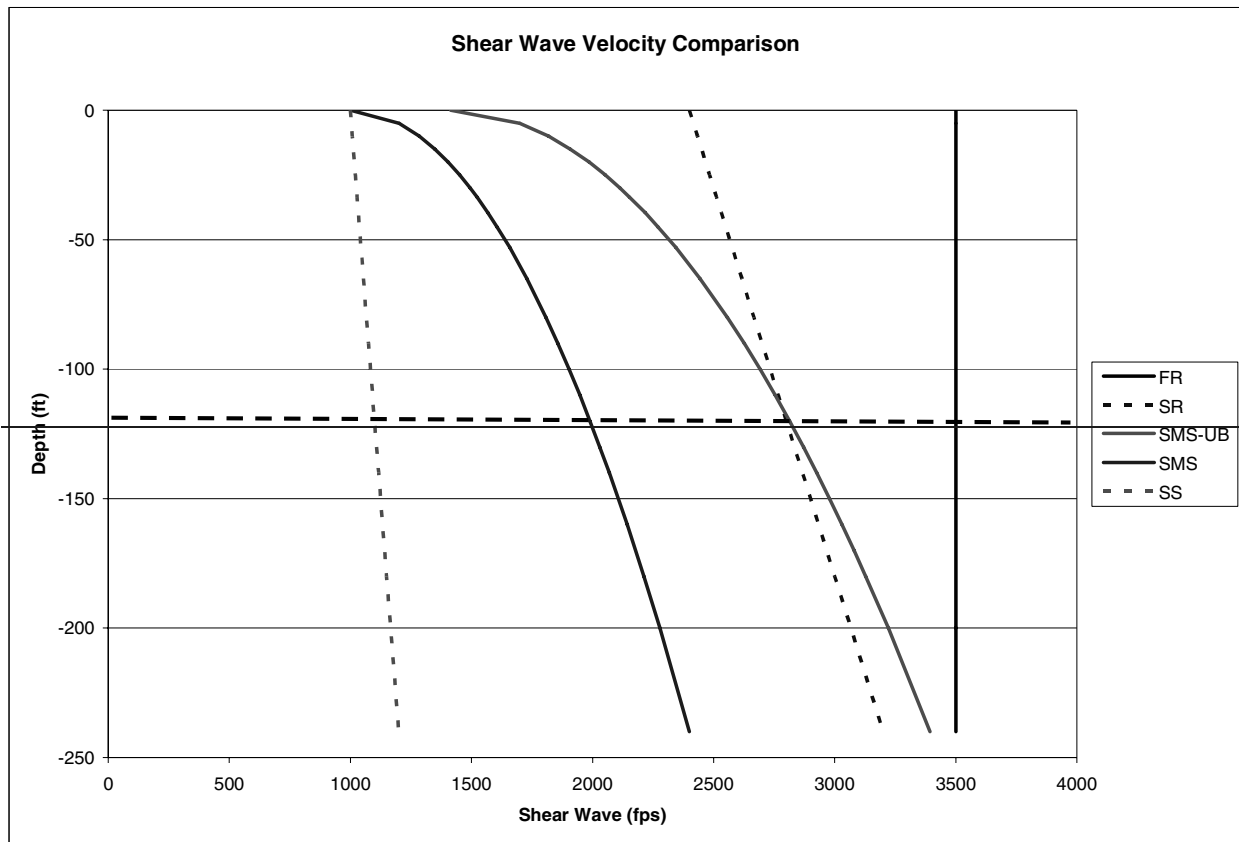
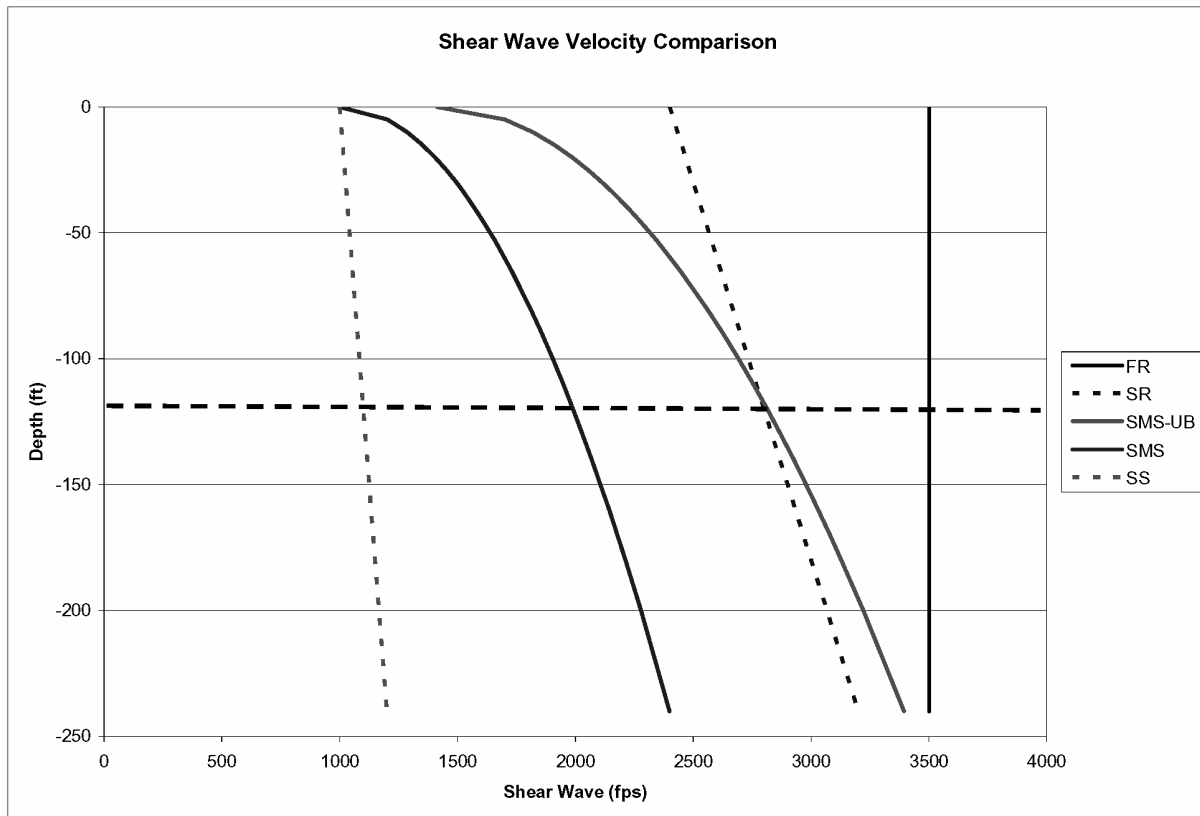


Figure 3G.2-4

Steel Containment Vessel and Polar Crane Models



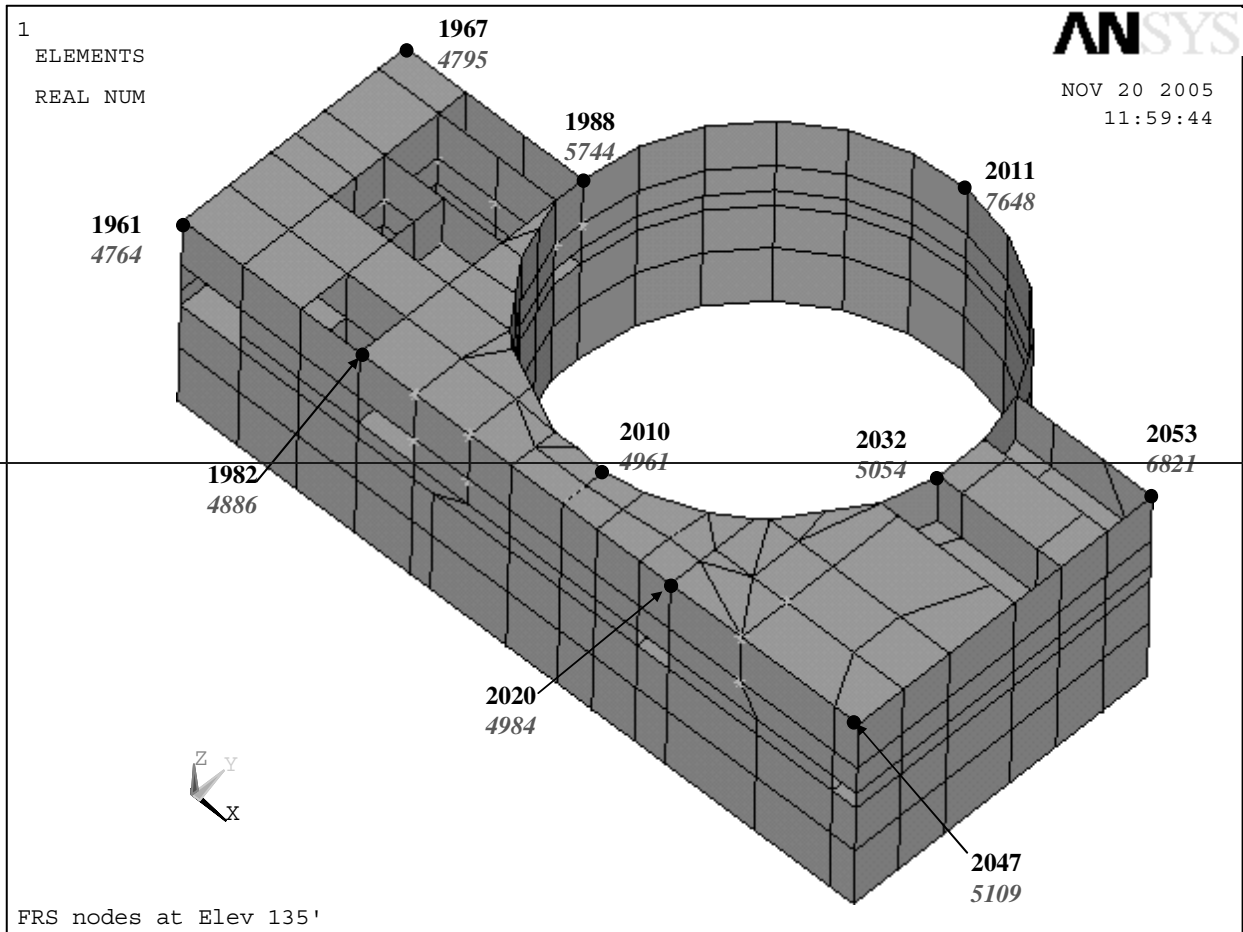
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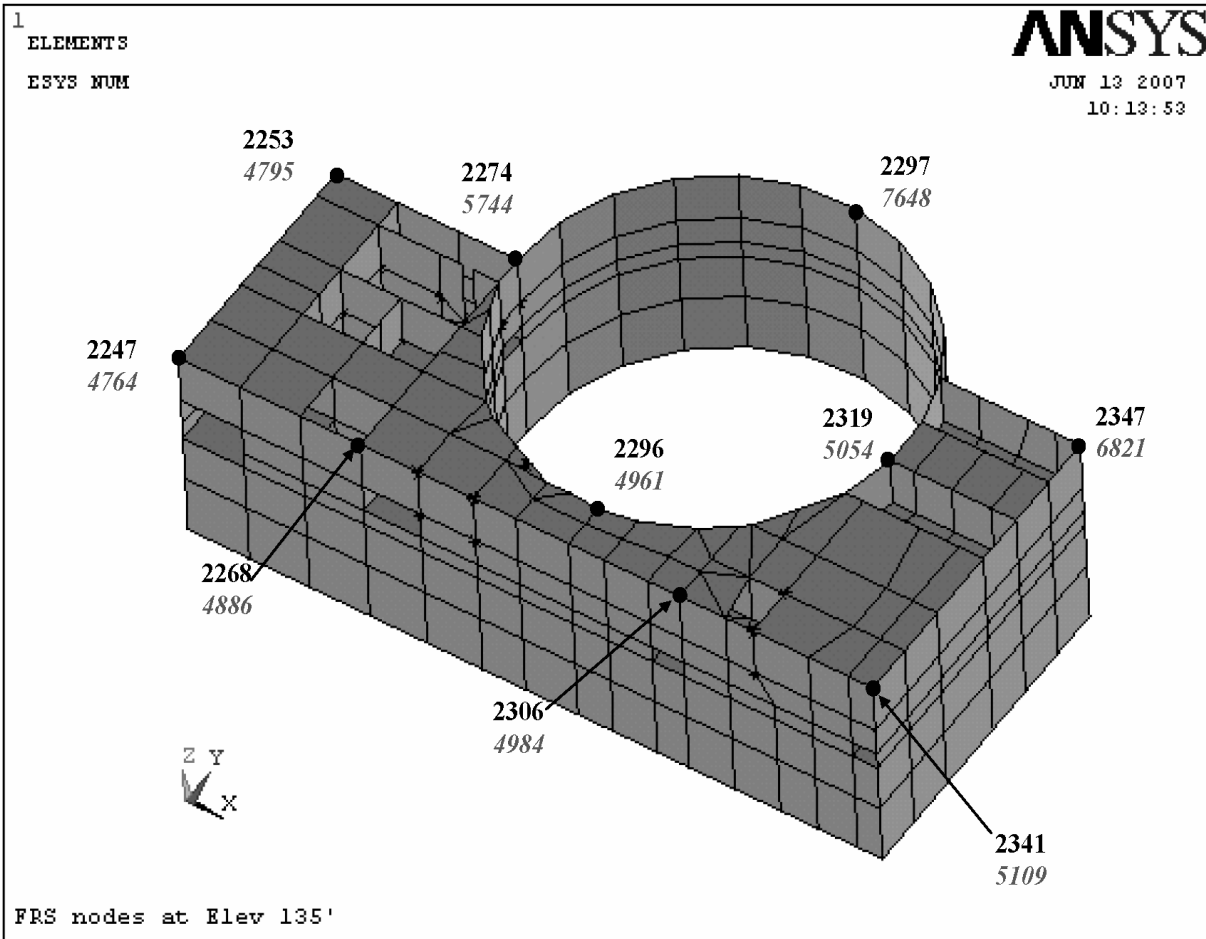


Note: Fixed base analyses were performed for hard rock sites. These analyses are applicable for shear wave velocity greater than 8000 feet per second.

Figure 3G.3-1

Generic Soil Profiles

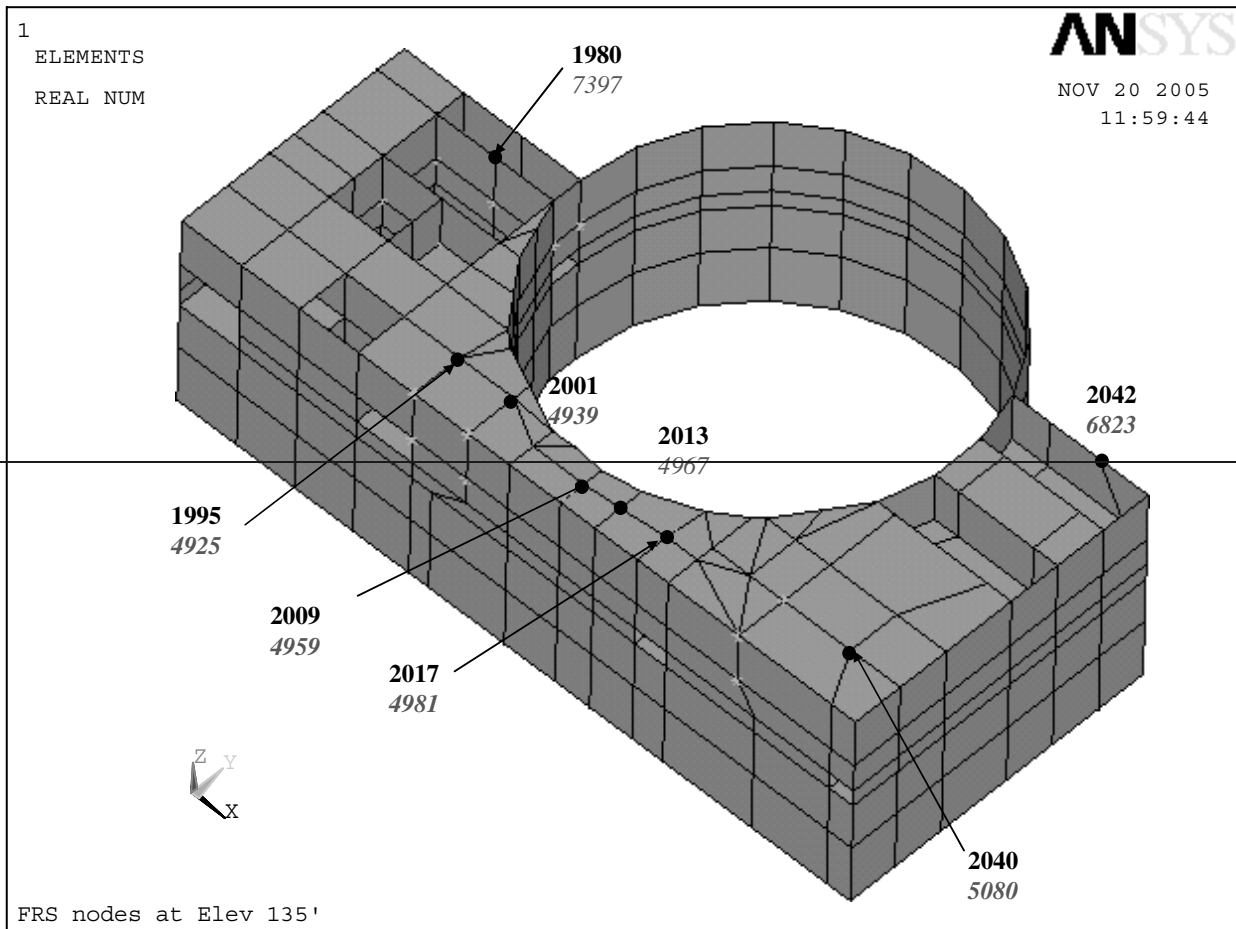




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Figure 3G.4-1

Auxiliary Shield Building “Rigid” Nodes at EL. 135’



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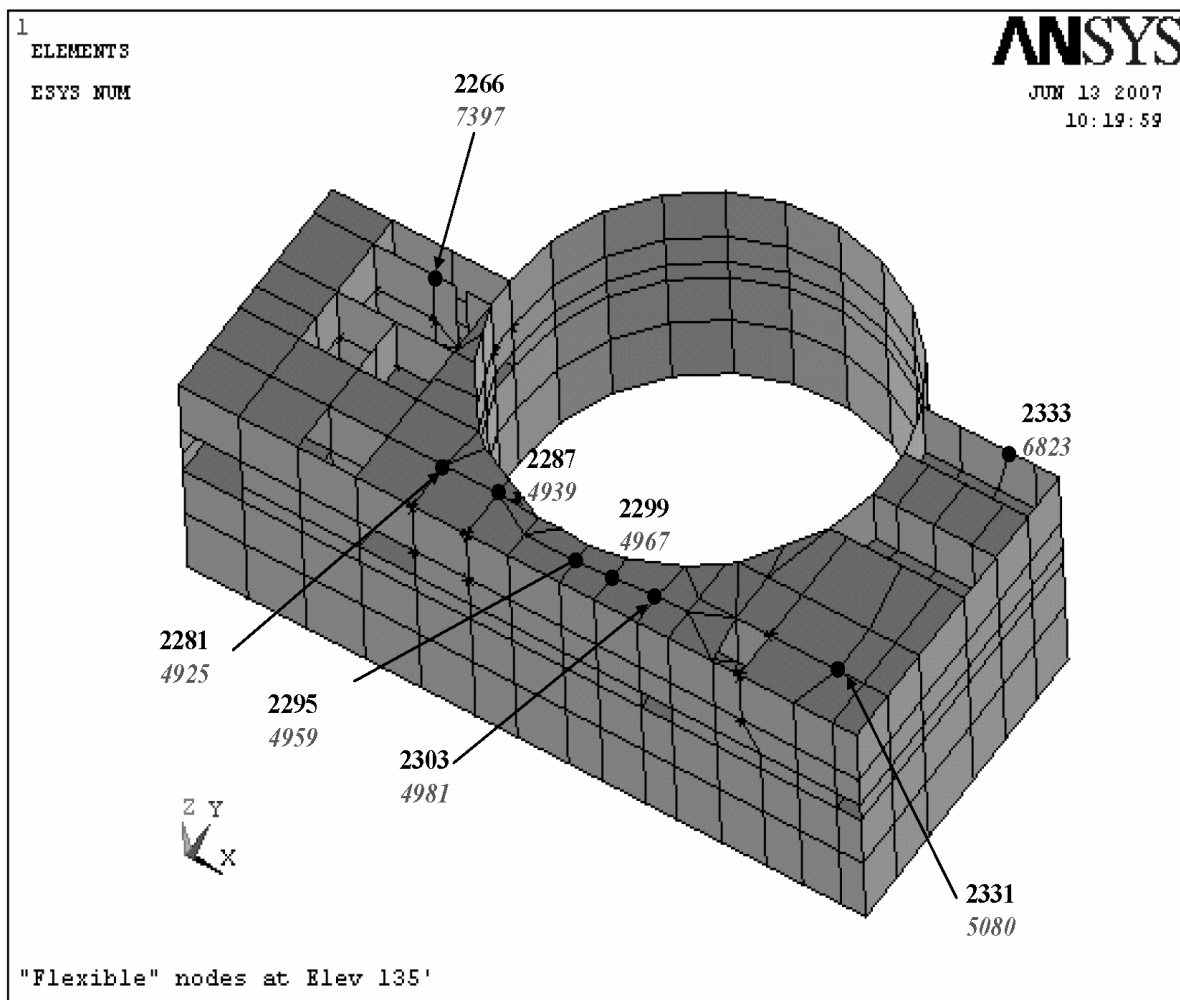


Figure 3G.4-2

Auxiliary Shield Building "Flexible" Nodes at El. 135'

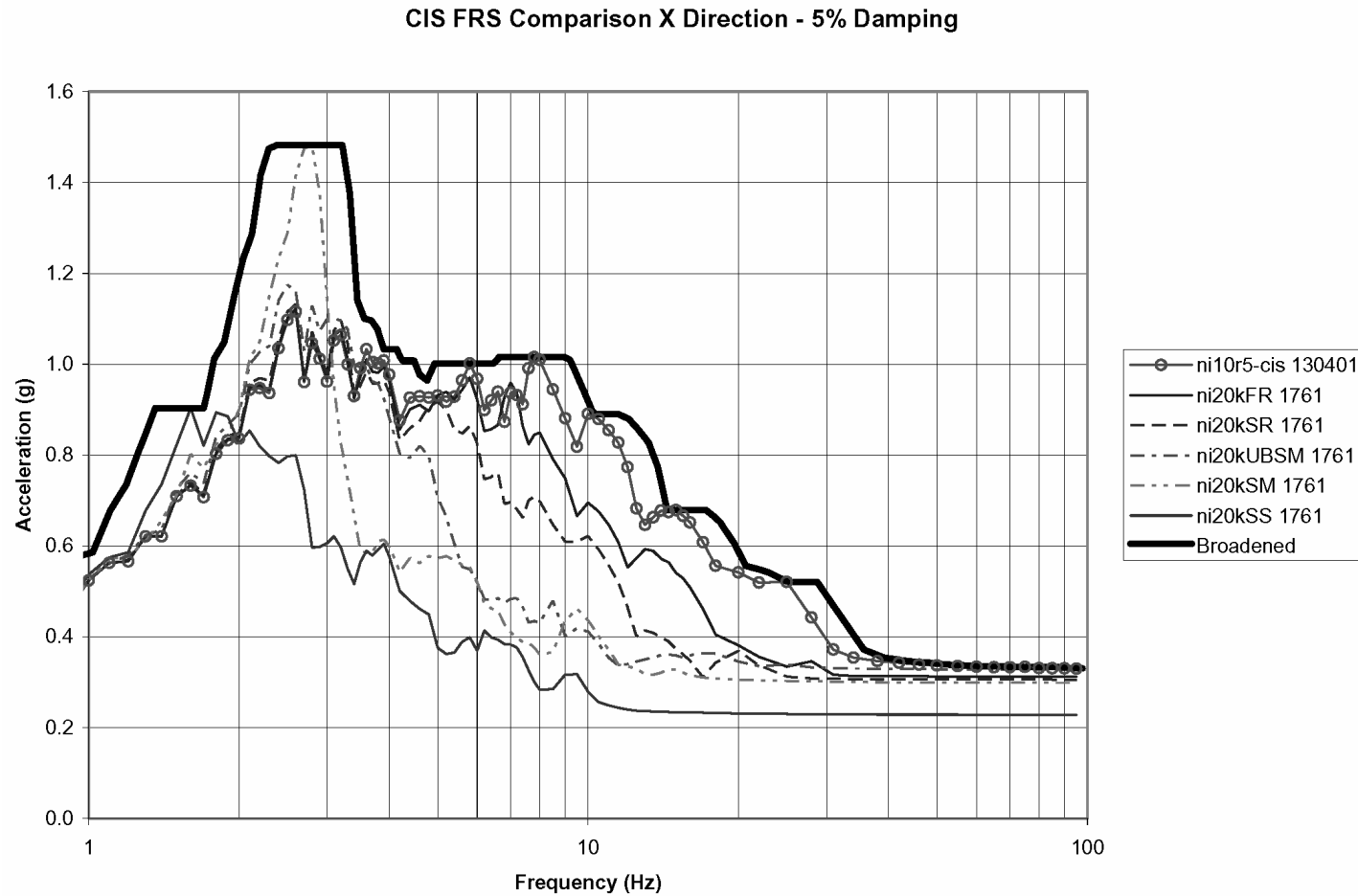


Figure 3G.4-5X

X Direction FRS for Node 130401 (NI10) or 1761 (NI20)
CIS at Reactor Vessel Support Elevation of 100'

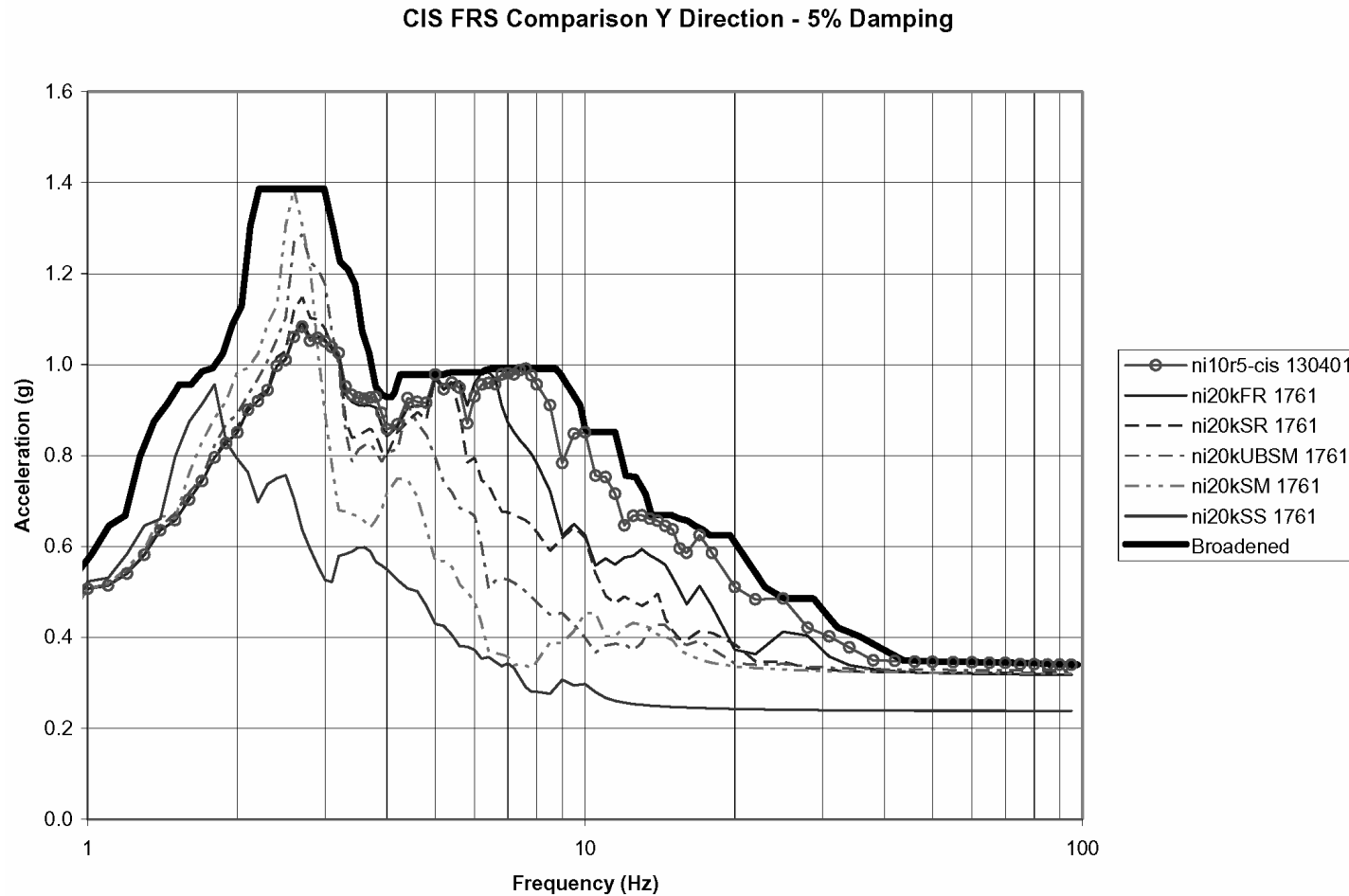


Figure 3G.4-5Y

Y Direction FRS for Node 130401 (NI10) or 1761 (NI20)
CIS at Reactor Vessel Support Elevation of 100'

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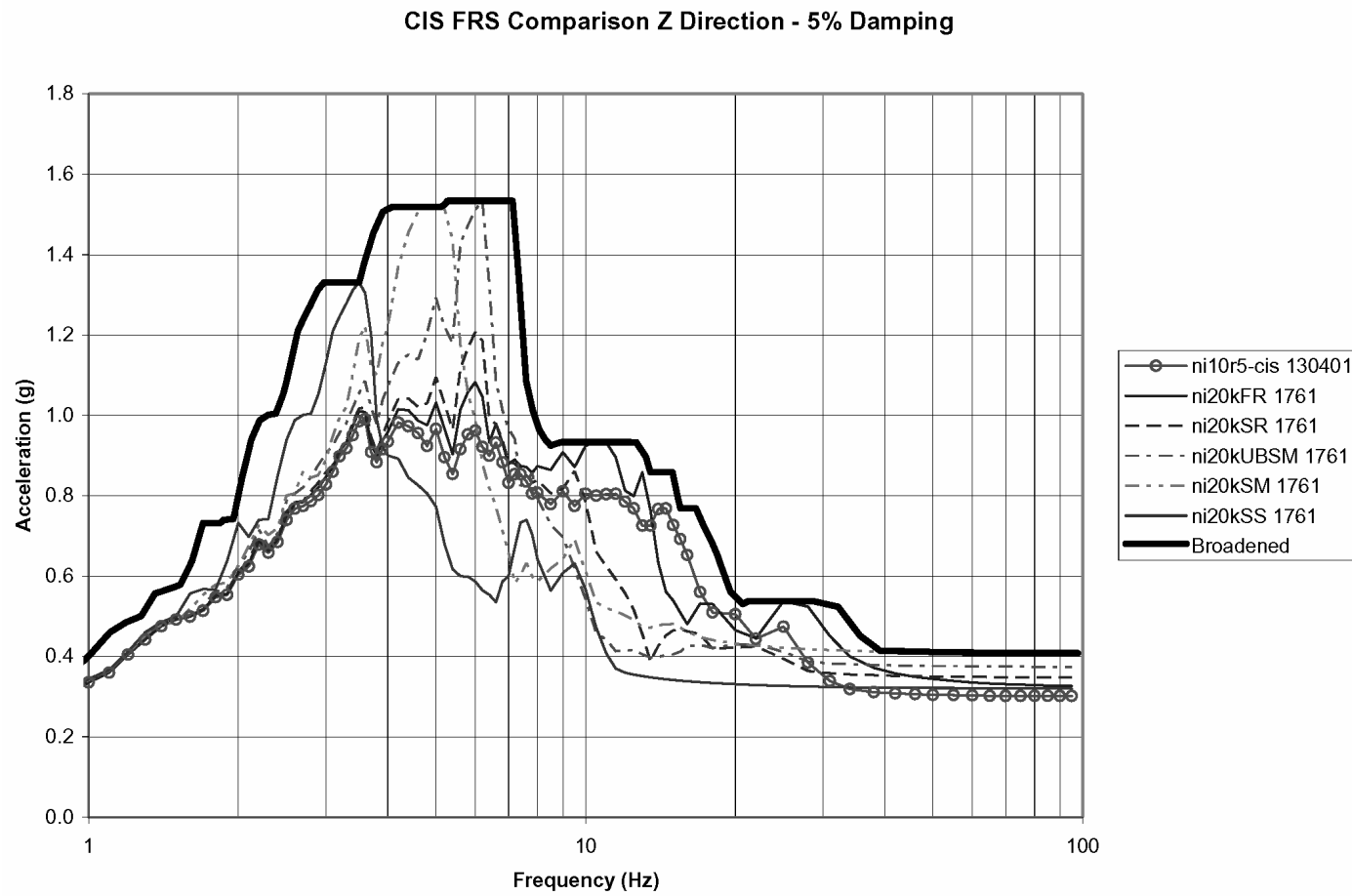


Figure 3G.4-5Z

Z Direction FRS for Node 130401 (NI10) or 1761 (NI20)
CIS at Reactor Vessel Support Elevation of 100'

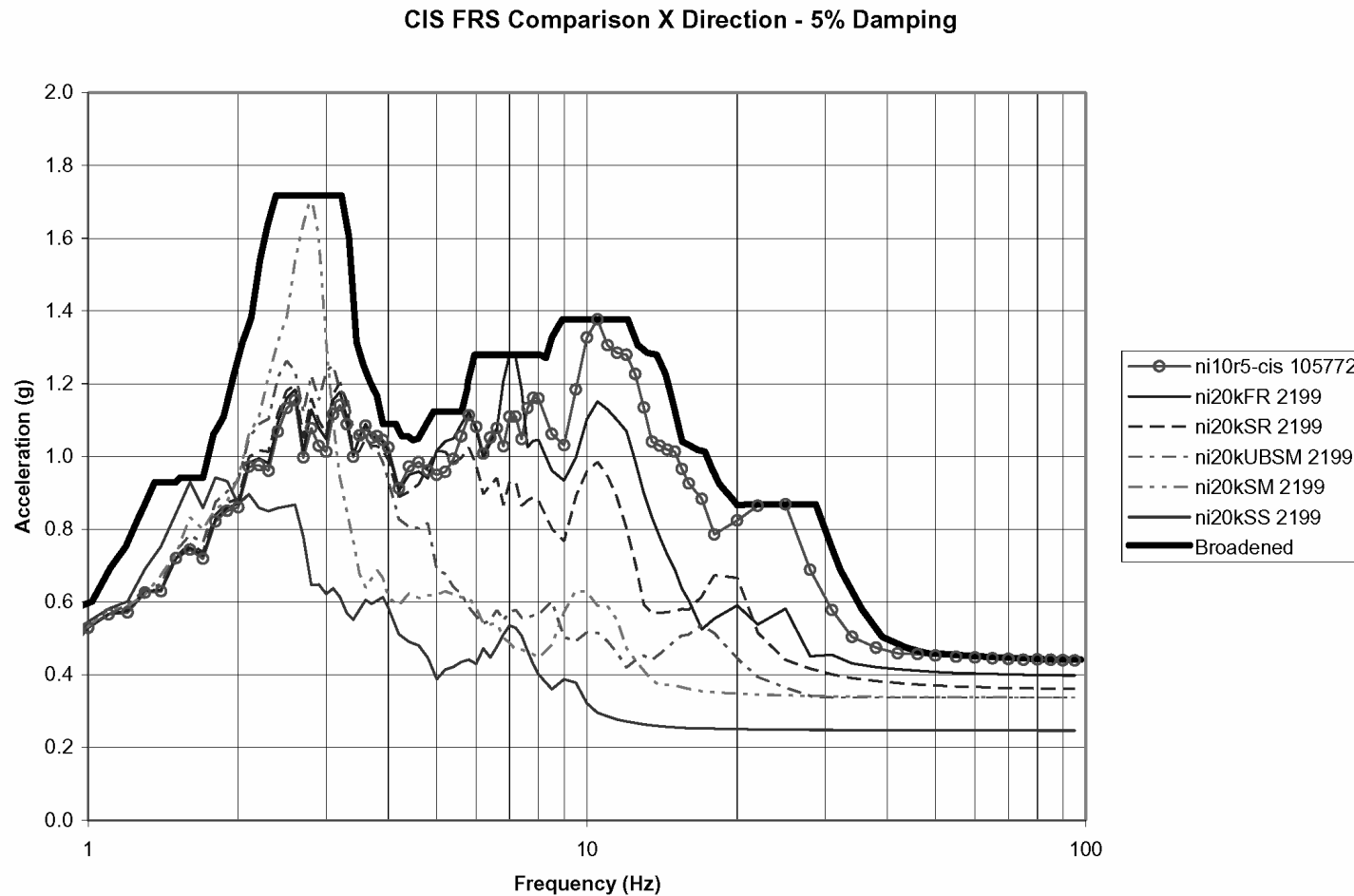


Figure 3G.4-6X

X Direction FRS for Node 105772 (NI10) or 2199 (NI20)
CIS at Operating Deck Elevation 134.25'

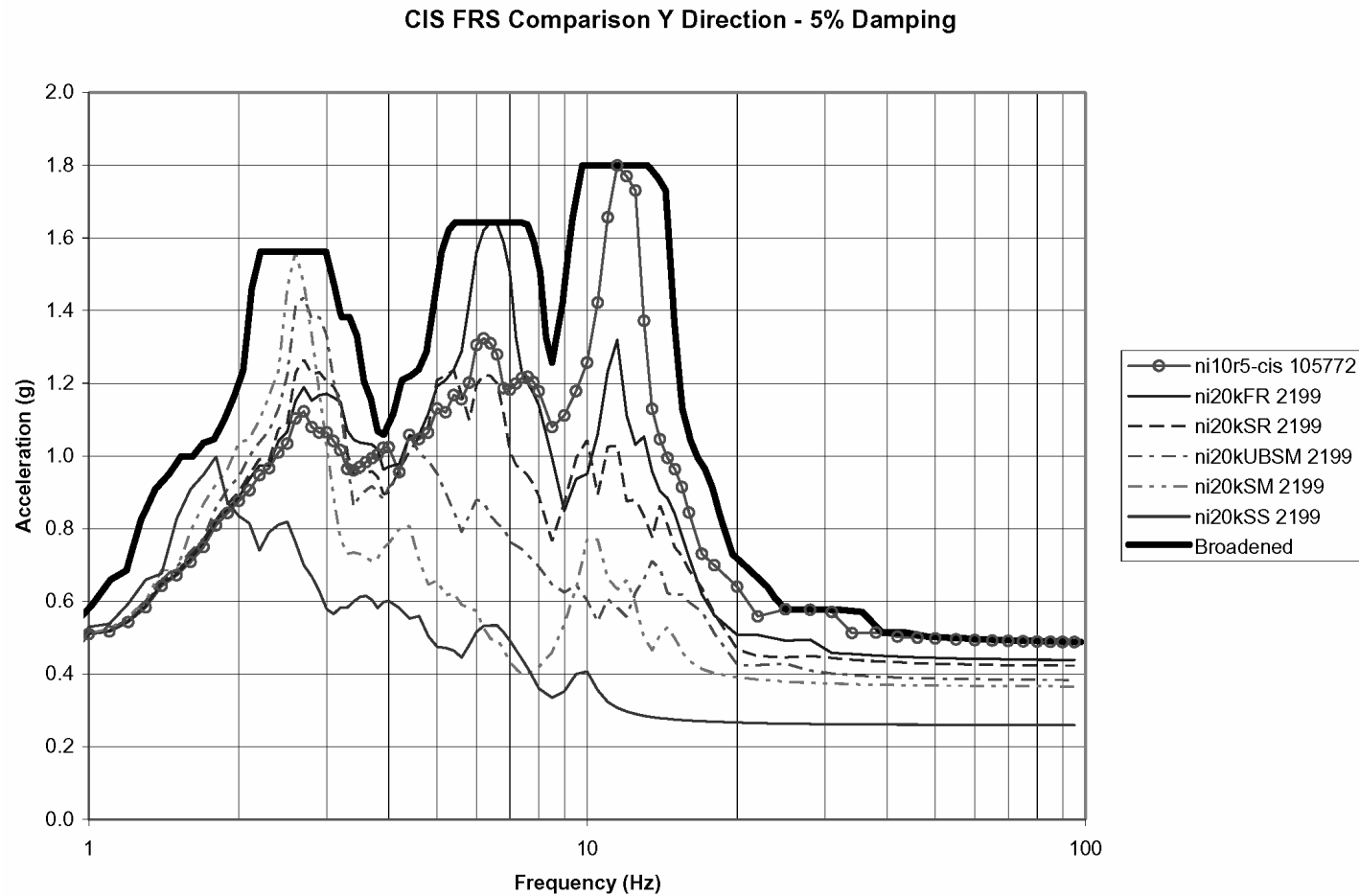


Figure 3G.4-6Y

Y Direction FRS for Node 105772 (NI10) or 2199 (NI20)
CIS at Operating Deck Elevation 134.25'

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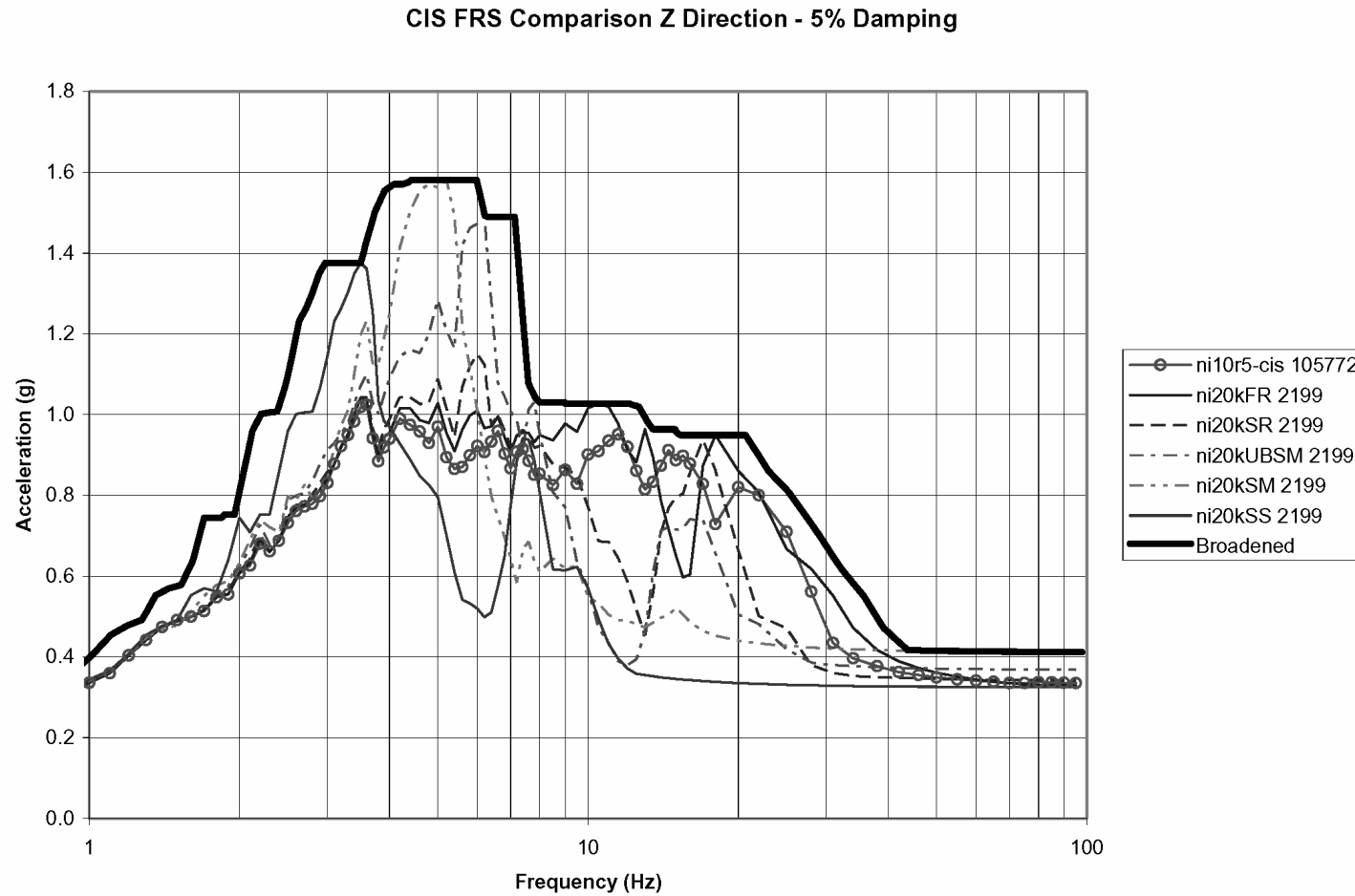


Figure 3G.4-6Z

Z Direction FRS for Node 105772 (NI10) or 2199 (NI20)
CIS at Operating Deck Elevation 134.25'

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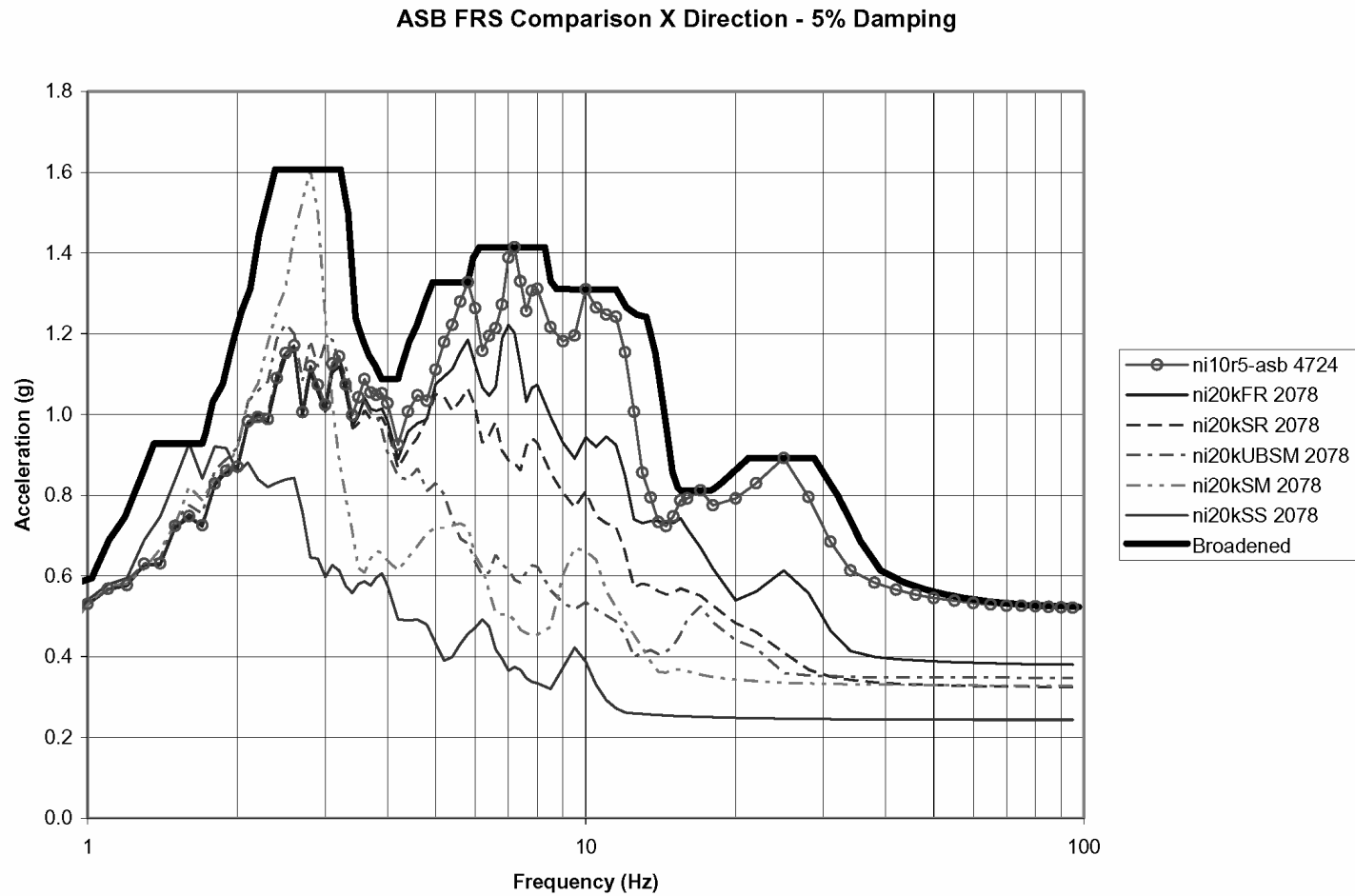


Figure 3G.4-7X

X Direction FRS for Node 4724 (NI10) or 2078 (NI20)
ABS Control Room Side Elevation 116.50'

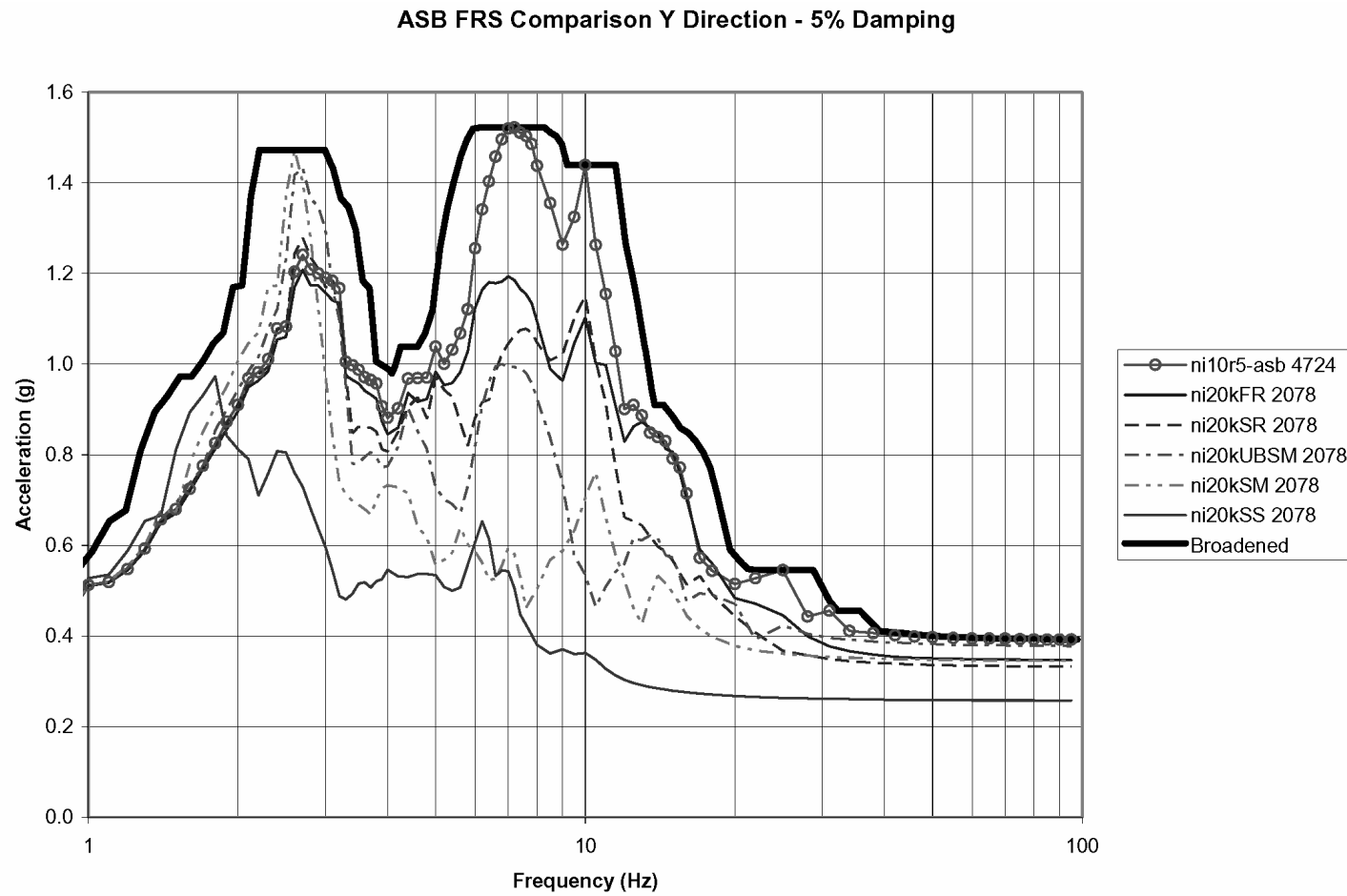


Figure 3G.4-7Y

Y Direction FRS for Node 4724 (NI10) or 2078 (NI20)
ABS Control Room Side Elevation 134.88'

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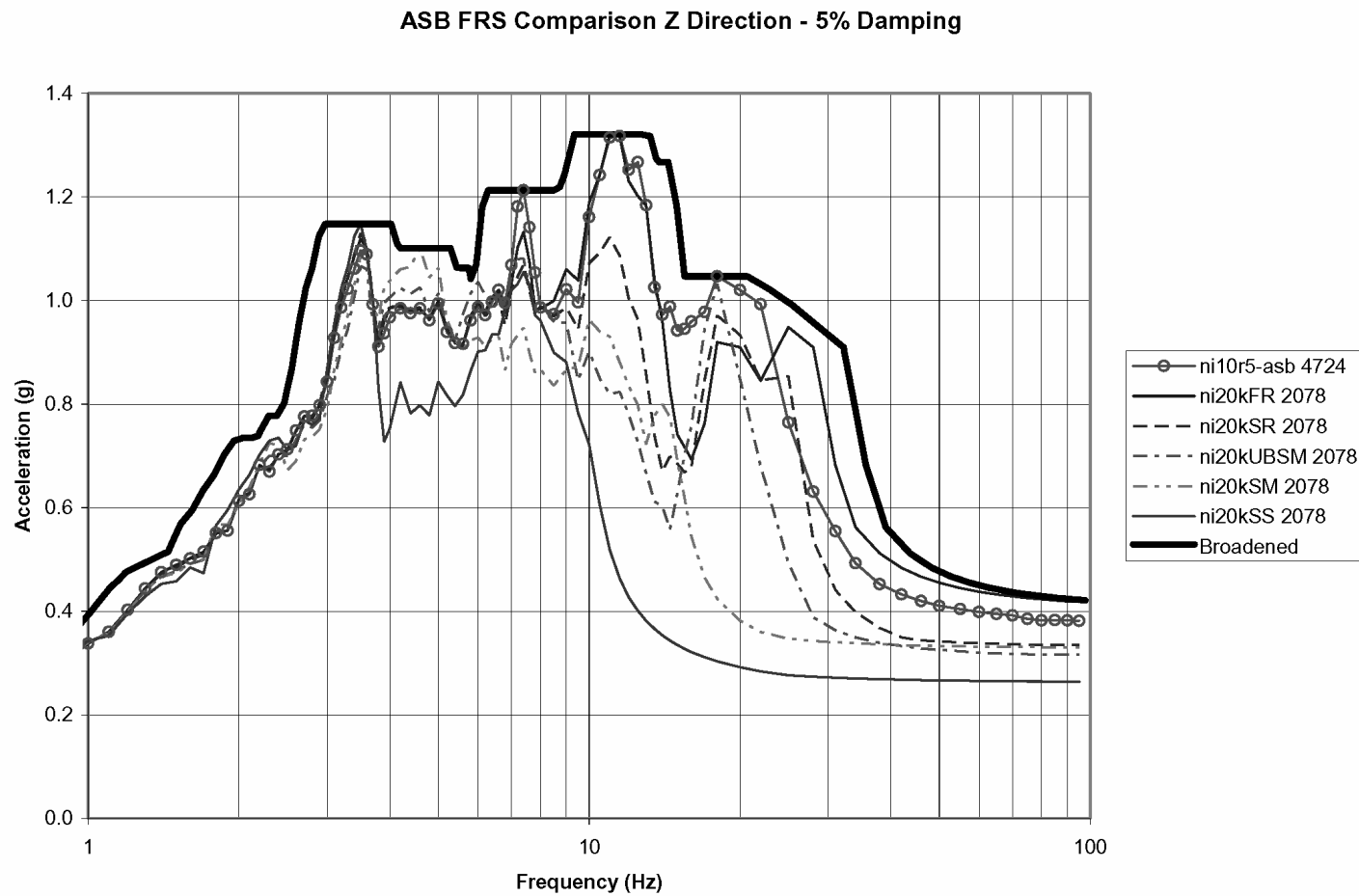


Figure 3G.4-7Z

Z Direction FRS for Node 4724 (NI10) or 2078 (NI20)
ABS Control Room Side Elevation 134.88'

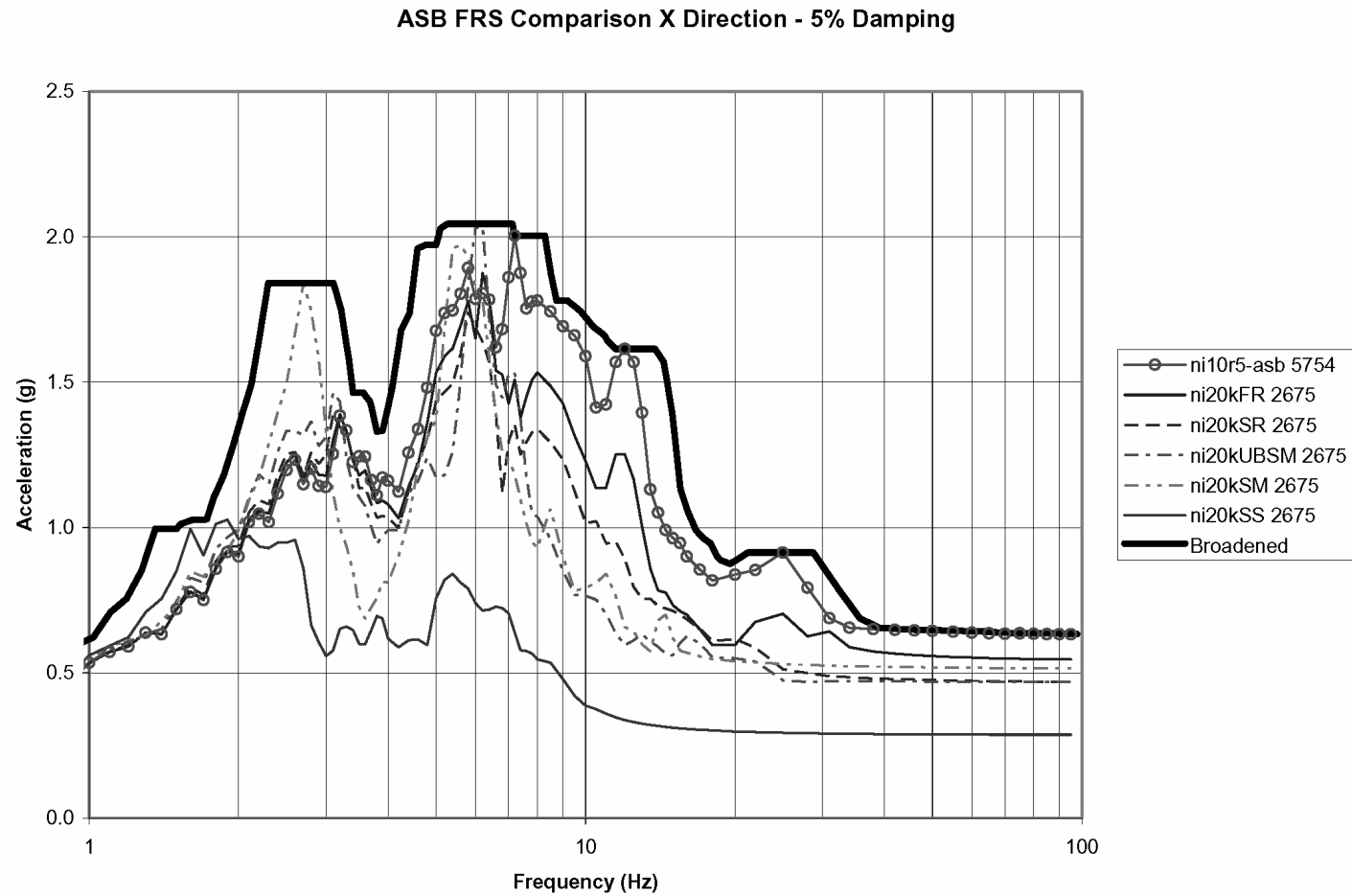


Figure 3G.4-8X

X Direction FRS for Node 5754 (NI10) or 2675 (NI20)
ABS Fuel Building Roof Elevation 179.19'

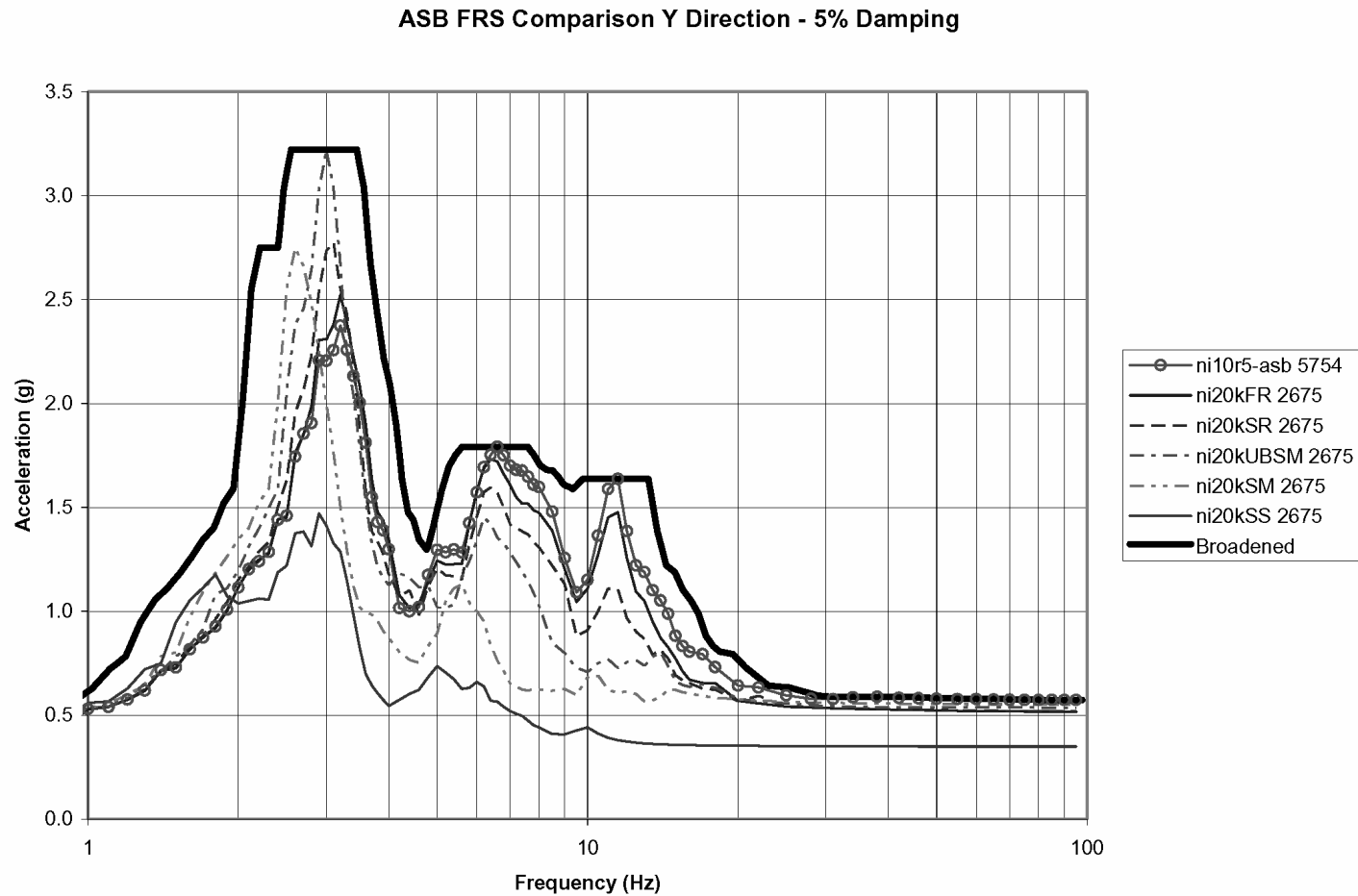


Figure 3G.4-8Y

Y Direction FRS for Node 5754 (NI10) or 2675 (NI20)
ABS Fuel Building Roof Elevation 179.19'

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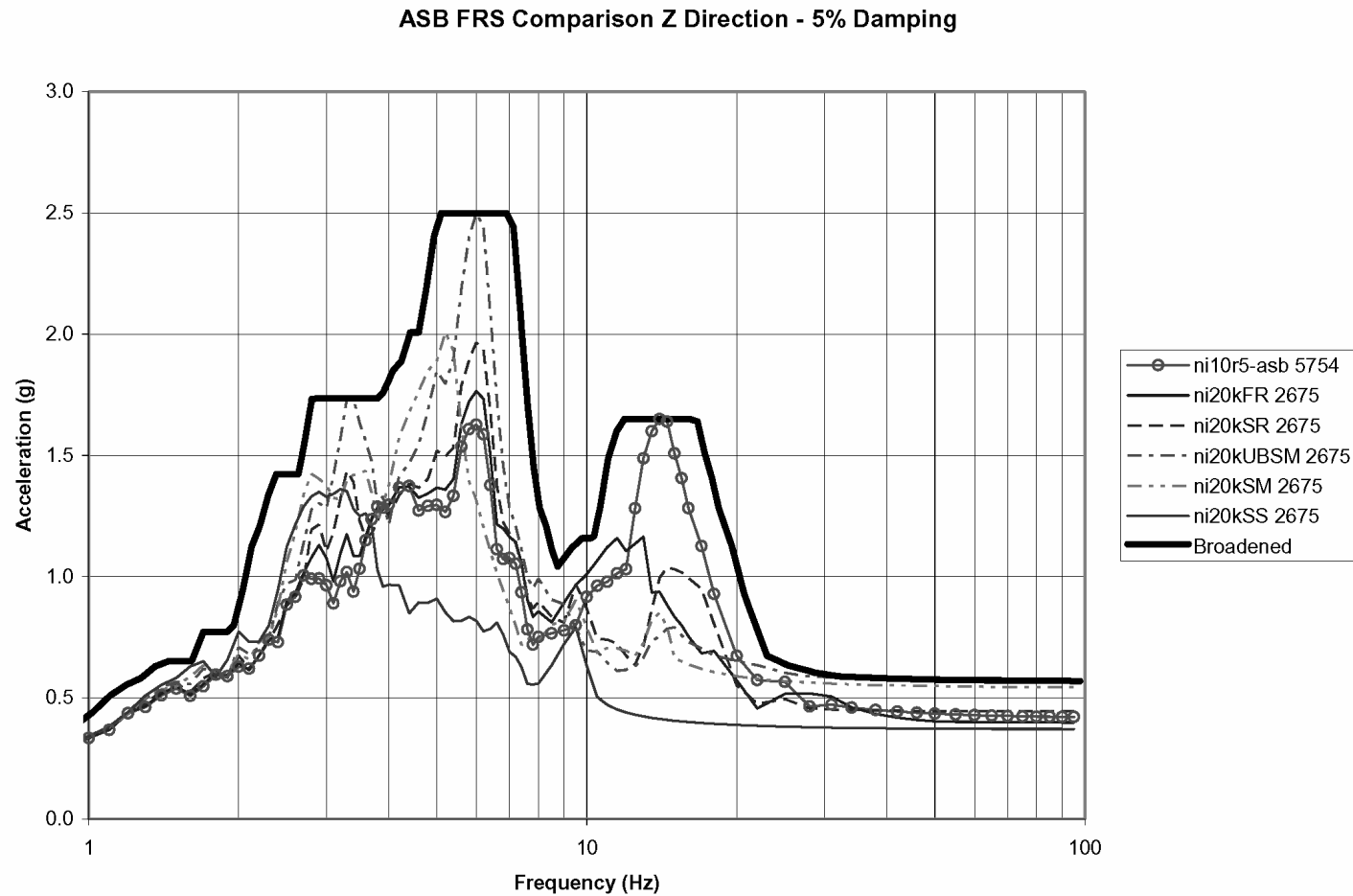


Figure 3G.4-8Z

Z Direction FRS for Node 5754 (NI10) or 2675 (NI20)
ABS Fuel Building Roof Elevation 179.19'

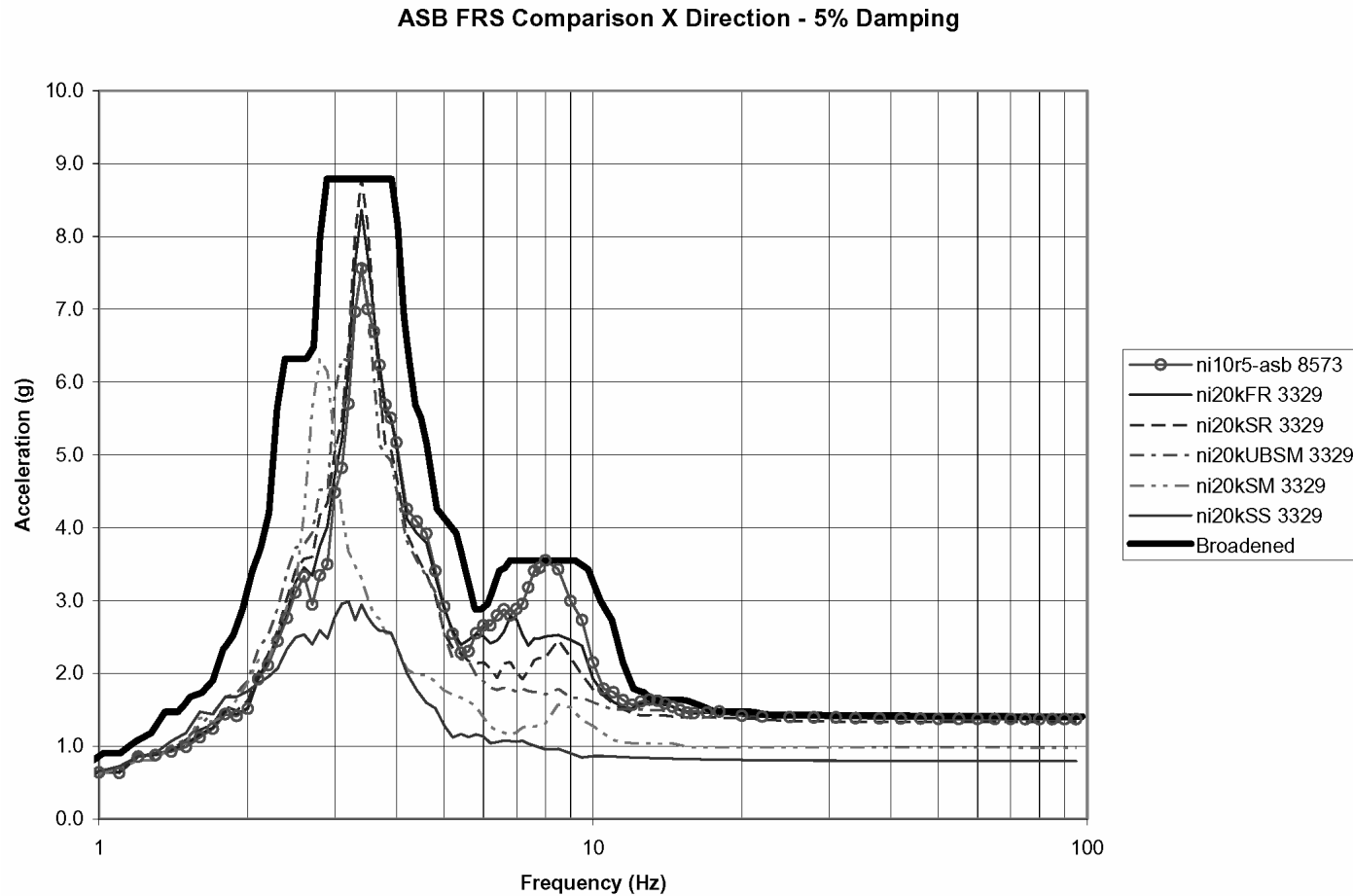


Figure 3G.4-9X

X Direction FRS for Node 2862 (NI10) or 3329 (NI20)
ABS Shield Building Roof Elevation 327.41'

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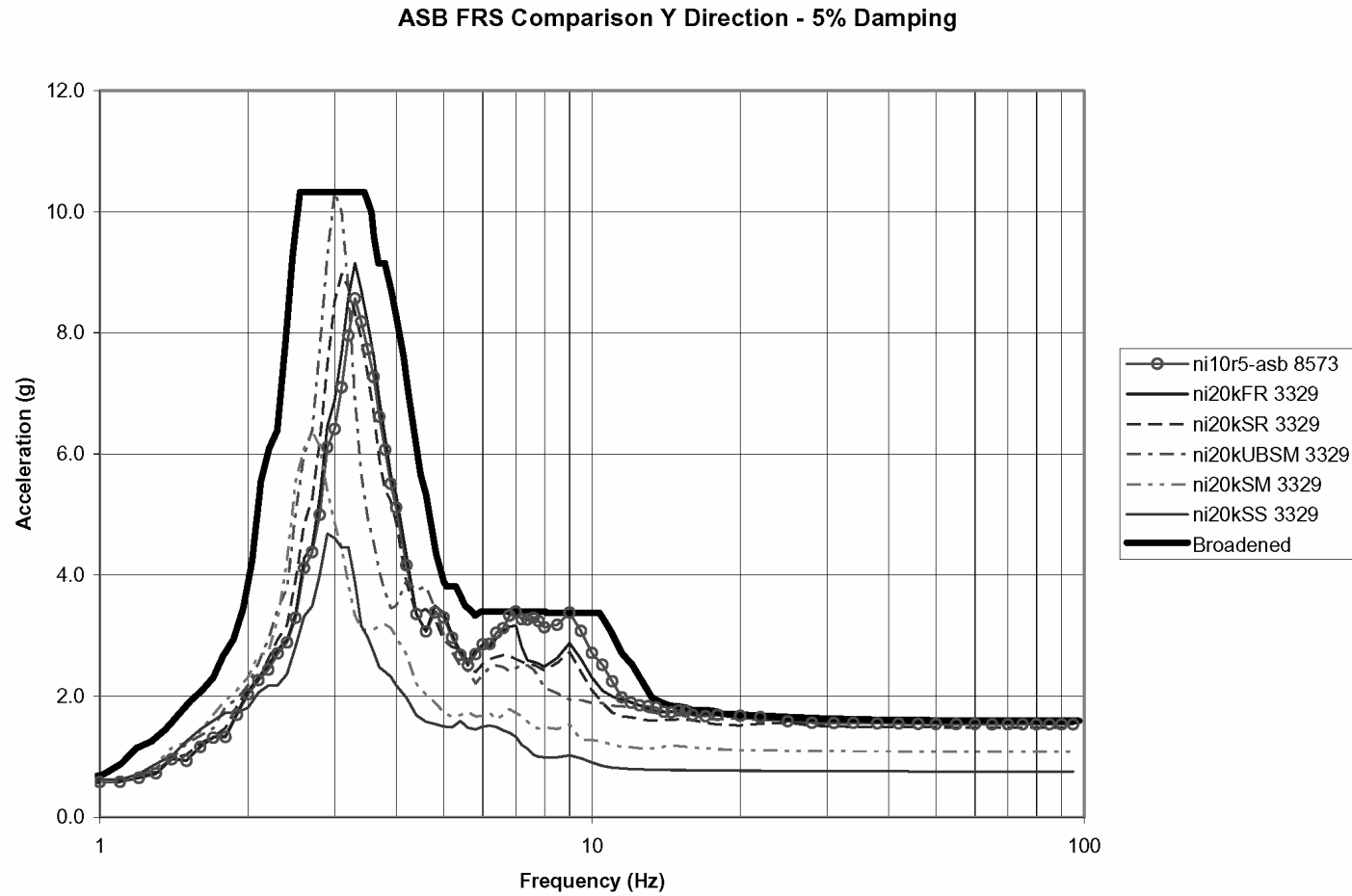


Figure 3G.4-9Y

Y Direction FRS for Node 2862 (NI10) or 3329 (NI20)
ABS Shield Building Roof Elevation 327.41'

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NRC 041

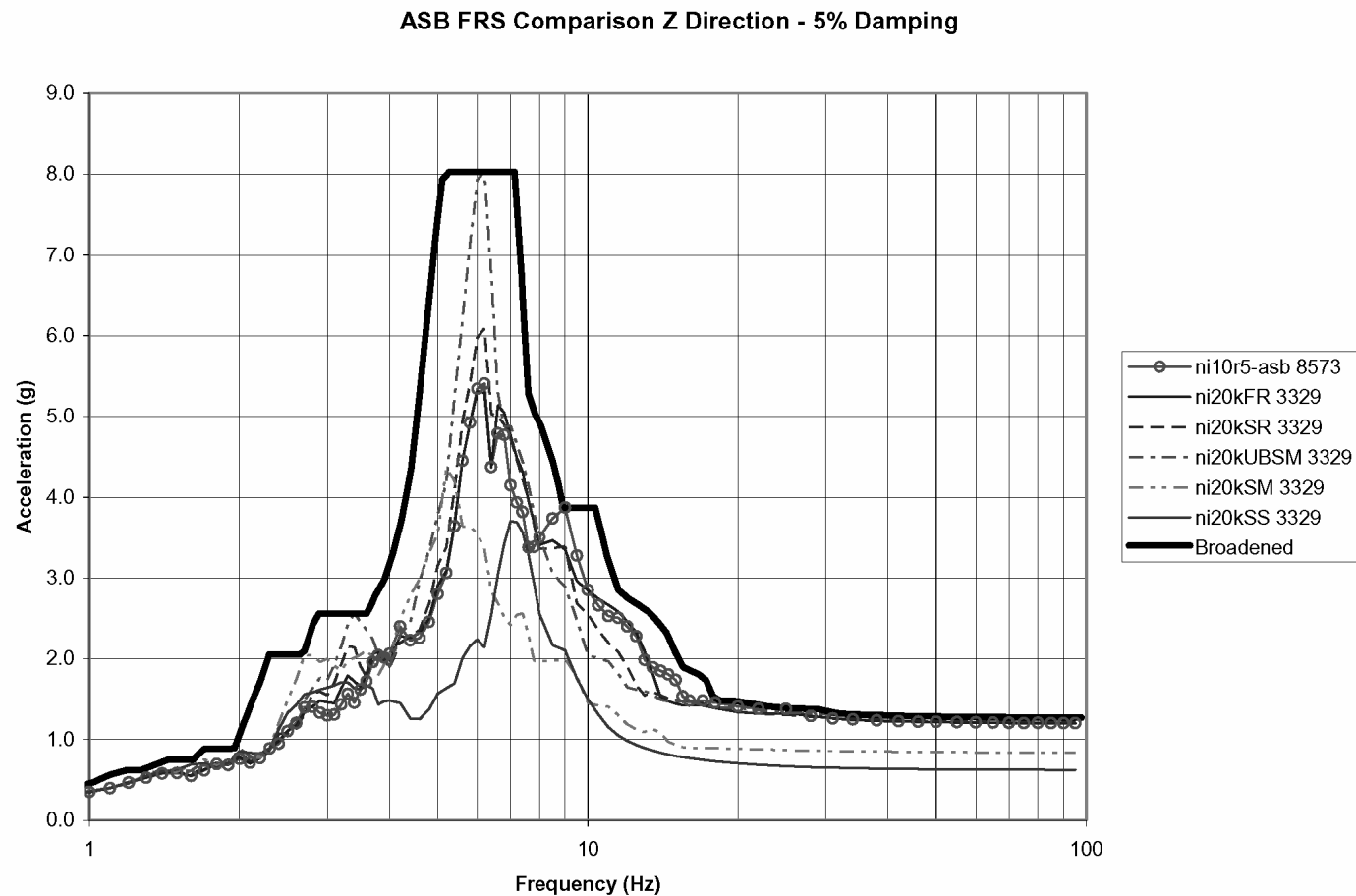


Figure 3G.4-9Z

Z Direction FRS for Node 2862 (NI10) or 3329 (NI20)
ABS Shield Building Roof Elevation 327.41'

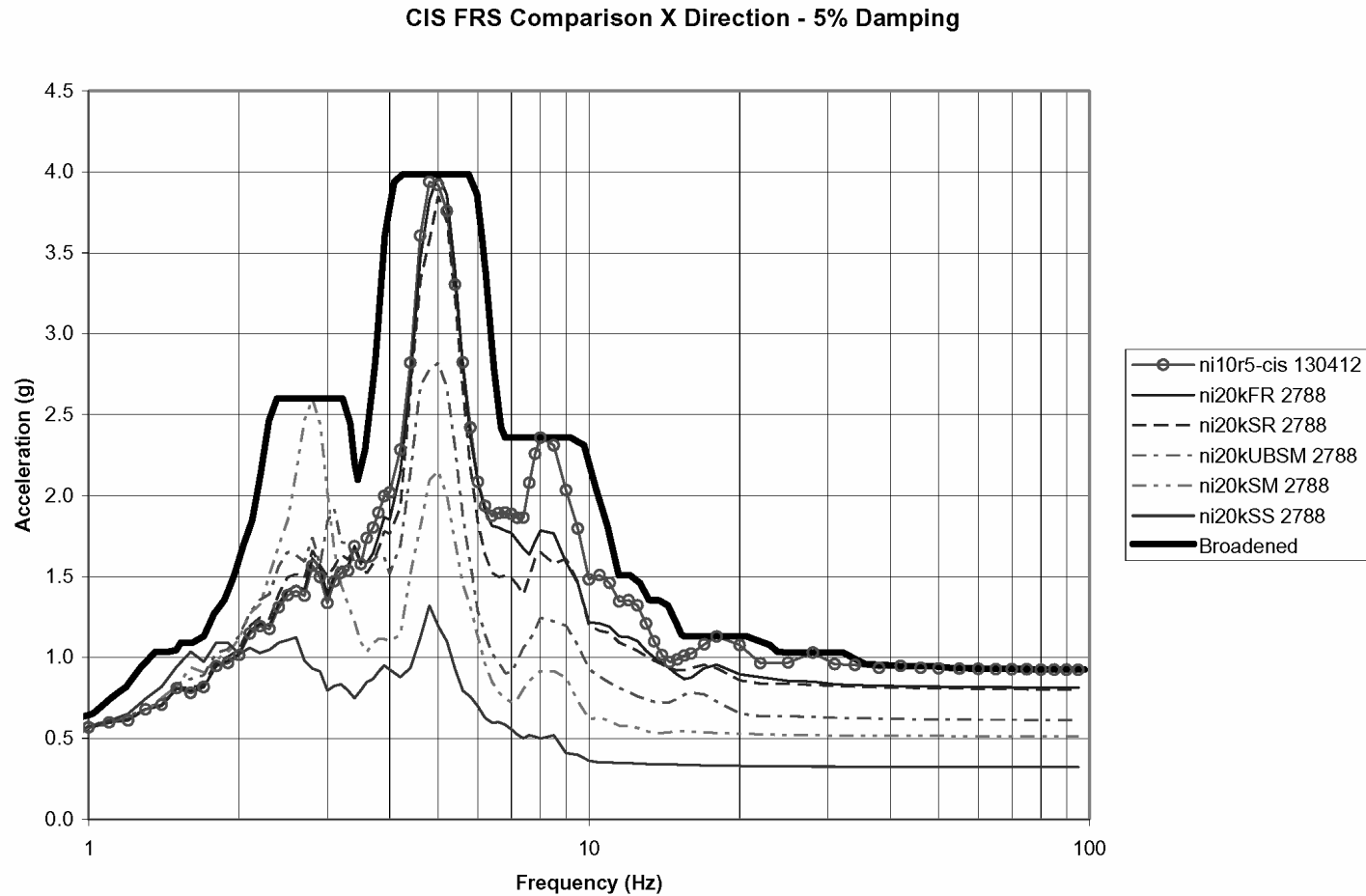


Figure 3G.4-10X

X Direction FRS for Node 130412 (NI10) or 2788 (NI20)
SCV Near Polar Crane Elevation 224.00'

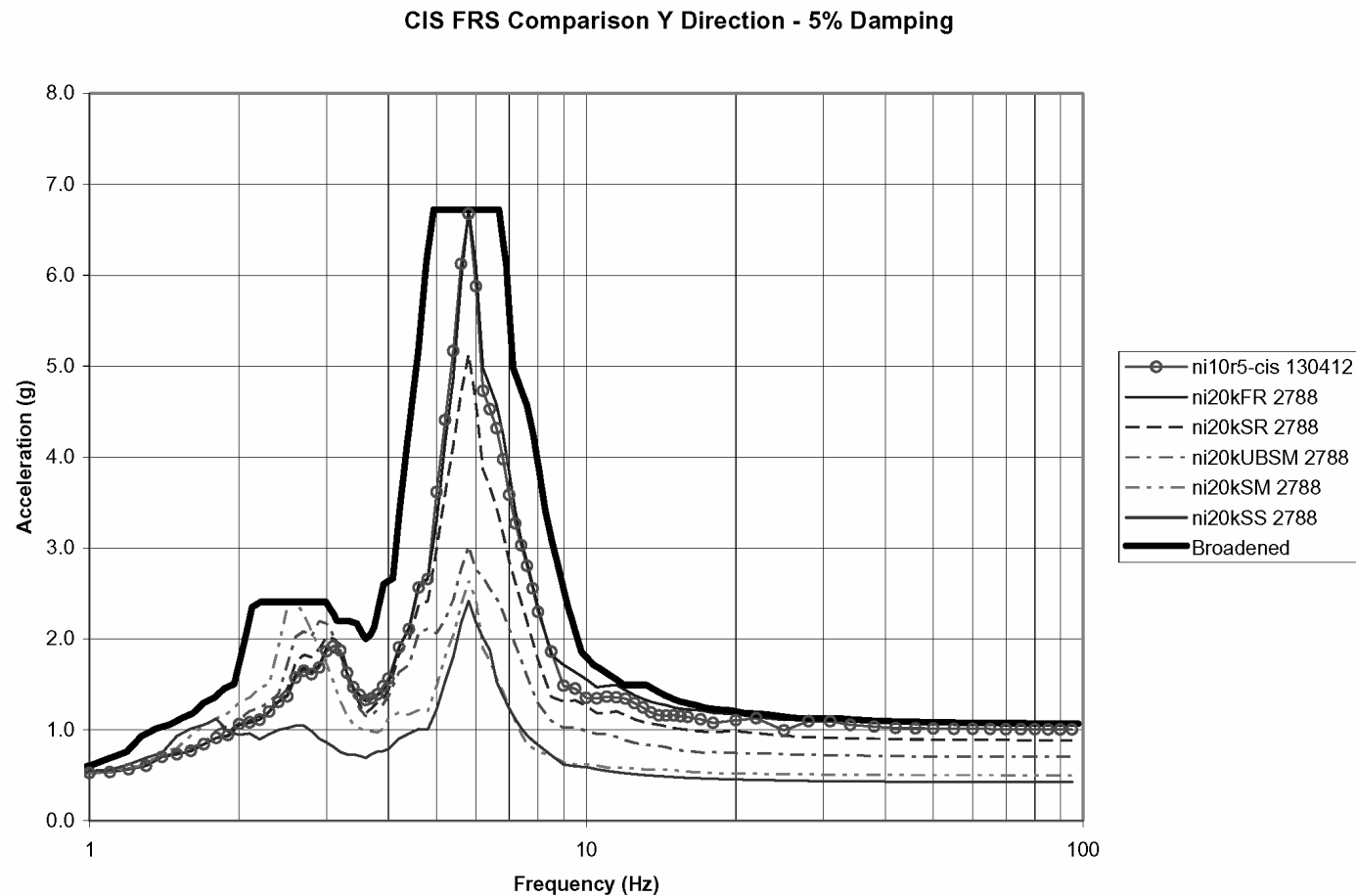


Figure 3G.4-10Y

Y Direction FRS for Node 130412 (NI10) or 2788 (NI20)
SCV Near Polar Crane Elevation 224.00'

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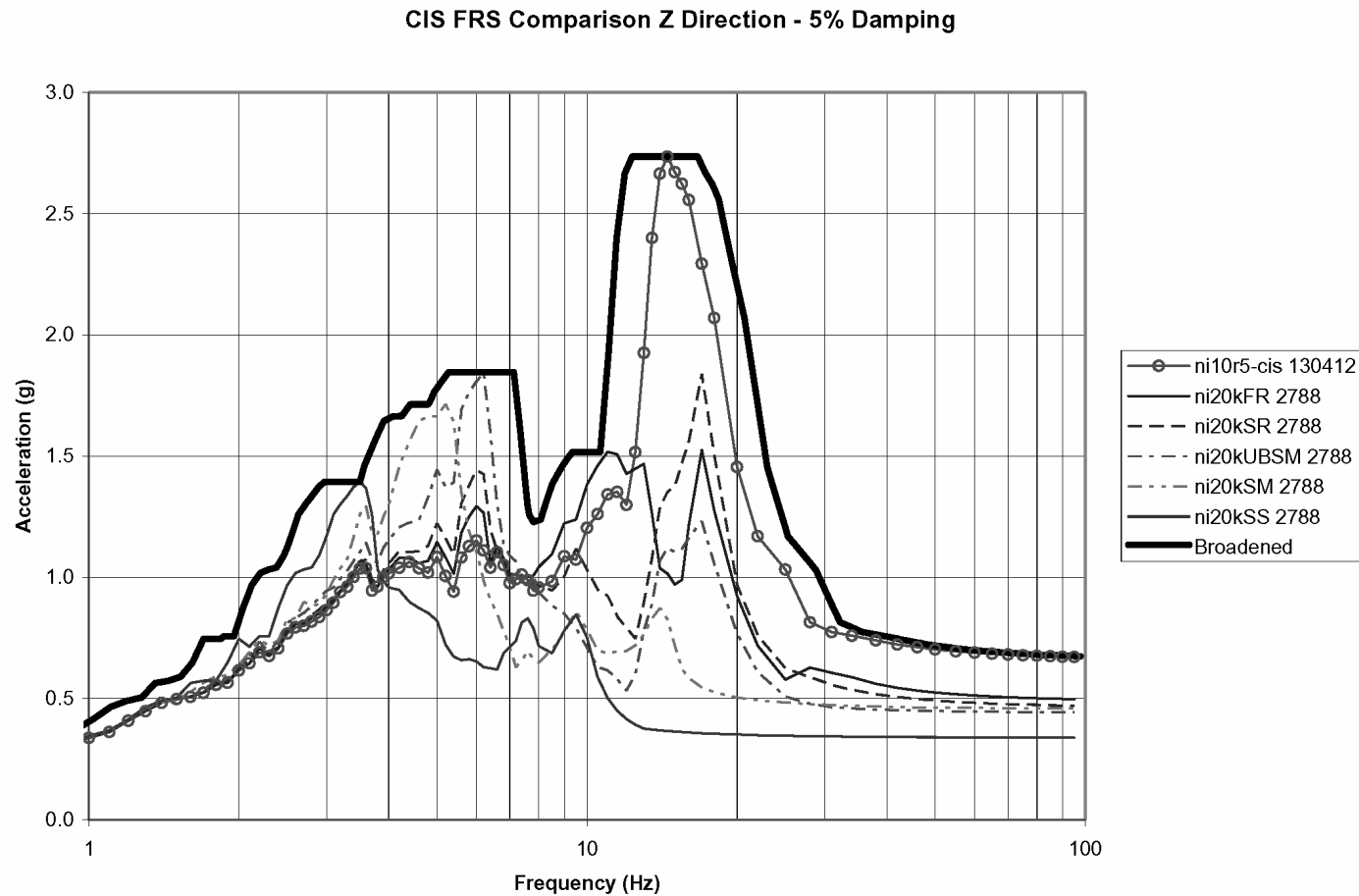


Figure 3G.4-10Z

Z Direction FRS for Node 130412 (NI10) or 2788 (NI20)
SCV Near Polar Crane Elevation 224.00'

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APPENDIX 3I EVALUATION FOR HIGH FREQUENCY SEISMIC INPUT

3I.1 Introduction

The seismic analysis and design of the AP1000 plant is based on the Certified Seismic Design Response Spectra (CSDRS) shown in subsection 3.7.1.1. These spectra are based on Regulatory Guide 1.60 with an increase in the 25 hertz region. Ground Motion Response Spectra (GMRS) for some Central and Eastern United States rock sites show higher amplitude at high frequency than the CSDRS. Evaluations are described in this appendix for a GMRS with high frequency for the seismic input at a at the Bellefonte site where the nuclear island is founded on hard rock. The resulting spectra of this site is shown in Figure 3I.1-1 and Figure 3I.1-2 and compares the this hard rock high frequency (HRHF) GMRS (based on Bellefonte input) at the foundation level against the AP1000 CSDRS for both the horizontal and vertical directions for 5% damping. The Bellefonte HRHF GMRS exceed the CSDRS for frequencies above about 15 Hz.

High frequency seismic input is generally considered to be non-damaging as described in Reference I.1. The evaluation of the AP1000 nuclear island for the high frequency input is based on the analysis of a limited sample of structures, components, supports, and piping to demonstrate that the high frequency seismic response is non-damaging. The evaluation includes building structures, reactor pressure vessel and internals, primary component supports, primary loop nozzles, piping, and equipment.

This appendix describes the methodology and criteria used in the evaluation to confirm that the high frequency input is not damaging to equipment and structures qualified by analysis for the AP1000 CSDRS. It provides supplemental criteria for selection and testing of equipment whose function might be sensitive to high frequency. The results of the high frequency evaluation demonstrating that the AP1000 plant is qualified for this type of input are documented in a technical report (Reference I.2). This report will provide a summary of the analysis and test results.

3I.2 High Frequency Seismic Input

Presented in Figures 3.I-1 and 3.I-2 is a comparison of the horizontal and vertical GMRS from the ~~Bellefonte-HRHF~~ site and the AP1000 CSDSR. The ~~Bellefonte-HRHF~~ GMRS presented is calculated at foundation level (39.5' below grade), at the upper most competent material and treated as an outcrop for calculation purposes.

For each direction, the ~~Bellefonte-HRHF~~ GMRS exceeds the design spectra in higher frequencies (greater than 15 Hz horizontal and 20 Hz vertical). The spectra are used for the GMRS. If necessary, the ~~Bellefonte-HRHF~~ GMRS spectra are enhanced at low frequencies so that GMRS fully envelopes all of the hard rock sites.

3I.3 NI Models Used To Develop High Frequency Response

The NI20 nuclear island model described in Appendix 3G is analyzed in SASSI using the ~~Bellefonte-HRHF~~ time histories applied at foundation level to obtain the motion at the base. The NI20 Model has sufficient mesh size to transmit the HRHF input up to 80 Hz. This was confirmed

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by comparing the dynamic response of the NI20 to that of the NI10 model, a model of much finer mesh.

~~To assure that the high frequency content at the base is transferred up the nuclear island structures and equipment, the base motion is applied to the NI10 ANSYS model described in Appendix 3G. The analyses are performed using the foundation motion and the NI10 surface mounted model since side soil effects are considered to be small because of the small deformation associated with the high frequency response on hard rock. These analyses are performed for incoherent motion using the coherency function described in Reference I.3.~~

~~The fixed base NI10 ANSYS nuclear island model defined in Appendix 3G is analyzed using the basemat response from the NI20 incoherent analyses as input. The NI10 model has greater refinement than the NI20 model and is therefore better suited for the high frequency building response.~~

3I.4 Evaluation Methodology

The demonstration that the AP1000 nuclear power plant is qualified for the high frequency seismic response does not require the analysis of the total plant. The evaluations made are of representative systems, structures, and components, selected by screening, as potentially sensitive to high frequency input in locations where there were exceedances in the high frequency region. Acceptability of this sample is considered sufficient to demonstrate that the AP1000 is qualified.

The high frequency seismic analyses that are performed use time history or broadened response spectra. The analysis is not performed using the envelope spectra of the CSDRS and the GMRS. Separate analyses with each spectra are used.

The evaluations performed assess the ability of the system, structure, or component to maintain its safety function.

Supplementary analyses are performed as needed to show that high frequency floor response spectra exceedances are not damaging. These analyses can include: gap nonlinearities; material inelastic behavior; multi point response spectra analyses where the high frequency response excites a local part of the system. Tests on equipment are specified as needed where function cannot be demonstrated by analysis, or analysis is not appropriate.

3I.5 General Selection Screening Criteria

The following general screening criteria are used to identify representative AP1000 systems, structures, and components (SSCs) for the samples to be evaluated to demonstrate acceptability of the AP1000 nuclear power plant for the high frequency motion.

- Select systems, structures, and components based on their importance to safety. This includes the review of component safety function for the SSE event and its potential failure modes due to an SSE. Those components whose failure modes would result in safe shutdown are excluded.
- Select systems, structures, and components that are located in areas of the plant that experience large high frequency seismic response.

The evaluation of the primary component supports and reactor coolant loop nozzles consists of a comparison of the loads from the high frequency input to those obtained from the Regulatory Guide 1.60 (modified) input. These items are considered qualified for the high frequency input if the seismic loads from the Regulatory Guide 1.60 (modified) envelope those from the high frequency input. If there is any exceedance, then an evaluation is made combining the high frequency loads with the other load components (e.g., thermal, pressure, dead) and a comparison made to the design loads. If the design loads envelope the load combinations that include the high frequency seismic input, then the nozzles and supports are considered qualified for the high frequency input.

3I.6.3 Piping Systems

Safety class piping analysis packages were reviewed and include a mixture of ASME Class 1, 2, and 3 piping systems. They typically contain at least one valve. The piping systems are mainly large bore of various size (3-inch diameter to 38-inch diameter), and some of small bore (2 inches and lower). The piping systems are in both the containment and auxiliary building.

The piping systems chosen for evaluation are those that are susceptible to high frequency as measured by their mass participation in the higher frequencies, are representative piping systems that contain valves and equipment nozzles, and are located in areas susceptible to high frequency ~~Bellefonte~~ HRHF GMRS spectra level response. At least two candidate piping analysis packages are identified for evaluation that meet these screening criteria.

The pipe stresses, nozzle loads, and valve end loads obtained from both the high frequency input and the Regulatory Guide 1.60 (modified) input are compared. Comparison is also made to the allowables with the seismic stresses combined with the other stresses associated with the seismic load combination that is applicable as necessary. If the high frequency seismic results are below those associated with the Regulatory Guide 1.60 (modified) results, or below the allowable limits, then the piping system is considered qualified. If necessary, more detailed supplementary analyses will be performed considering one or more of the following:

- Multi-point response spectra input
- Non-linear analysis with gap and material nonlinearities
- Calculation of actual support stiffness in locations where a minimum rigid value was used

3I.6.4 Electro-Mechanical Equipment Qualification

The groups of safety-related equipment considered for evaluation are those that may be sensitive to the high frequency input. This includes cabinet mounted equipment, field sensors and appurtenants which may be sensitive to high frequency seismic inputs identified in Table 3I.6-1.

Sample safety-related cabinets have been identified that are typically sensitive to seismic input. Evaluations will be performed to verify these cabinets do not have excessive seismic demand on their mounted equipment, the cabinet designs do not require changes due to the high frequency input, and the cabinets will maintain their structural integrity during the high frequency input. Time history analyses of these cabinets are performed for both the Regulatory Guide 1.60 (modified) and the high frequency inputs so that comparisons can be made to their seismic

response from both seismic inputs. This analytical study is to conclude that safety-related equipment may be screened and grouped as follows:

Screening Process

Group No. 1:

Rugged equipment with high frequency content above 60 Hz. This group will require no additional evaluation for high frequency seismic inputs.

Group No. 2:

Cabinets and other equipment which exhibit most of their effective mass (80% and higher) with modes below 15 Hz. This group will require no additional evaluation for high frequency seismic inputs.

Group No. 3:

Safety-related equipment which exhibit dominant natural frequencies in HRHF exceedance range. The safety-related equipment will be subjected to supplemental high frequency seismic evaluation to verify acceptability. ~~Cabinet and other equipment which exhibit dominant natural frequencies between 15 Hz and 60 Hz. This group is classified into three sub-groups as follows.~~

~~A.— Tune the mounting configurations of the cabinet to reduce its dominant natural frequencies below 15 Hz (equal to group No. 2. This subgroup will require no additional evaluation for high frequency seismic inputs.)~~

~~B.— Tune the mounting configurations of the cabinet to shift dominant natural frequencies higher than 60 Hz (mainly in the vertical direction) (equal to group No. 1. This subgroup will require no additional evaluation for high frequency seismic inputs.)~~

~~C.— This group will have dominant natural frequencies in the range of 20 to 60 Hz and can't be shifted out of this range. This group is the only group required high frequency evaluations. It can be evaluated as follows:~~

~~1.— If cabinet and equipment structures have been seismically tested and qualified to low frequency input higher than the high frequency seismic requirements or with a ZPA (at 33 Hz) higher than the spectral acceleration of the high frequency input, then no additional testing or analysis are required.~~

~~2.— If not, then structure can be shown qualified by analysis and sensitive components by testing to high frequency excitation.~~

Qualification Process

In the high frequency screening process, the potential failure modes of high frequency sensitive component types and assemblies are important considerations. The following are potential failure modes of high frequency sensitive components/equipment.

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- Inadvertent change of state
- Chatter
- Change in accuracy and drift in output signal or set-point
- Electrical connection failure or intermediacy (e.g., poor quality solder joints)
- Mechanical connection failure
- Mechanical misalignment/binding (e.g., latches, plungers)
- Fatigue failure (e.g., solder joints, ceramics, self-taping screws, spot welds)
- Improperly and unrestrained mounted components
- Inadequately secured/locked mechanical fasteners and connections

Components and equipment determined to be exposed to and are high frequency sensitive with potential failure modes involve change of state, chatter, signal change/drift and connection problems shall be demonstrated to be acceptable through the performance of supplemental high frequency qualification testing. Those high frequency sensitive component having failure modes associated with mounting, connections and fasteners, joints, and interface are considered to be qualified by traditional low frequency qualification testing per IEEE Std 344 and/or required quality assurance inspection and process/design controls.

High frequency seismic testing for sensitive equipment will be conducted as a supplemental test to low frequency seismic excitation. High and low frequency seismic ~~R~~required ~~R~~esponse ~~S~~pectra (RRS) are separate environments and an envelope RRS covering both would not be representative of the ~~d~~Design ~~b~~asis ~~e~~vent (DBE). Testing to a High/Low Frequency Envelope RRS could prove destructive to both the equipment under test and the seismic test table.

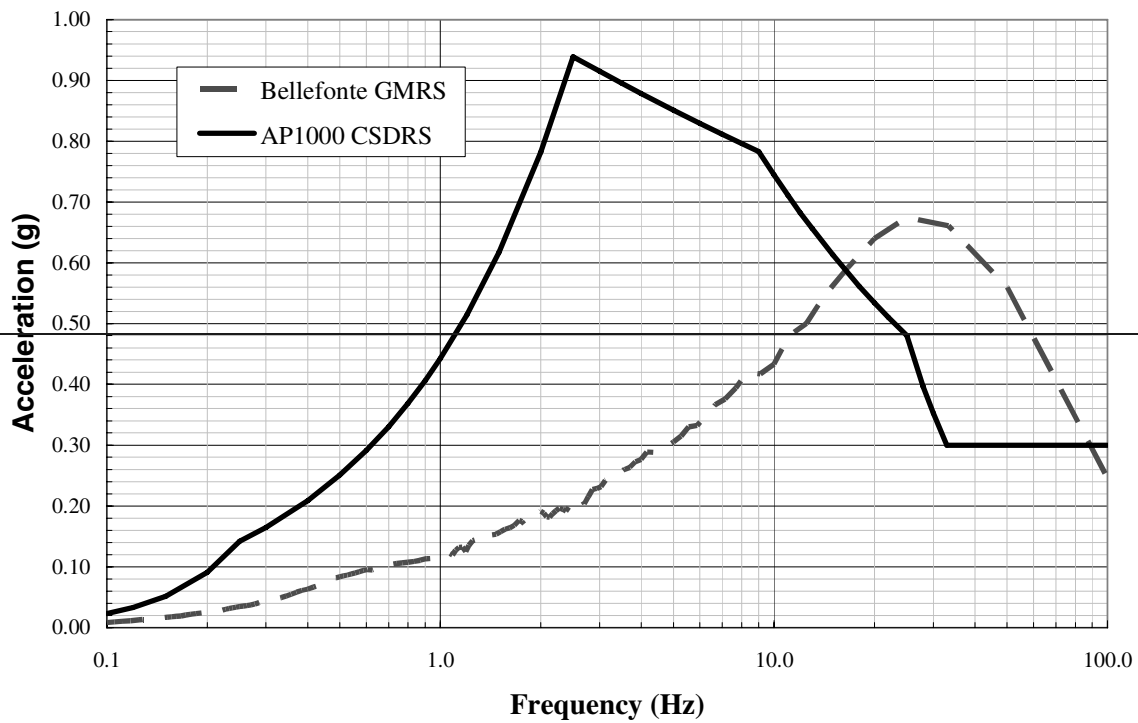
When high frequency seismic testing is performed following a low frequency seismic testing, the equipment shall be subjected to the high frequency SSE testing after completion of the low frequency seismic testing. Low level cycling fatigue effects requirement shall be justified represented by low frequency seismic input. No additional low level testing for high frequency excitation is required. One SSE high frequency seismic test will be performed to demonstrate functionality of equipment in its most sensitive electrical configuration.

Acceptance and qualification to the high frequency input is determined based on the comparison of the test levels the components have been analyzed or tested to. For those equipment/components determined to have already been tested to high seismic levels in the high frequency region, no additional testing or justifications will be necessary. A review of seismic testing data is performed to verify that the tested seismic levels envelop the high frequency seismic demand. If these components cannot be shown to be acceptable based on this review, additional testing or justifications may be required to show qualification.

3I.7 References

1. EPRI Draft White Paper, "Considerations for NPP Equipment and Structures Subjected to Response Levels Caused by High Frequency Ground Motions," Transmitted to NRC March 19, 2007.
2. APP-GW-GLR-115, "Effect of High Frequency Seismic Content on SSCs," Westinghouse Electric Company LLC.

AP1000 Horizontal Spectra Comparison



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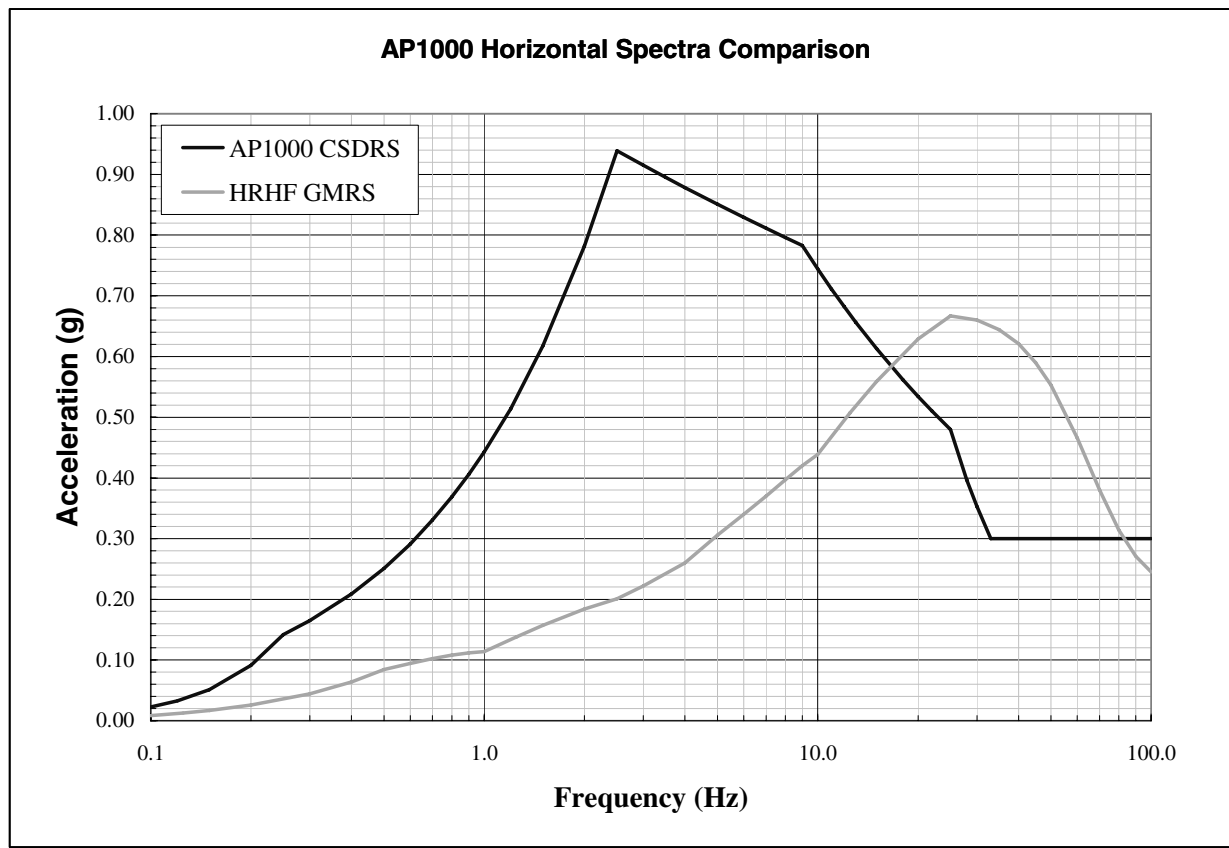
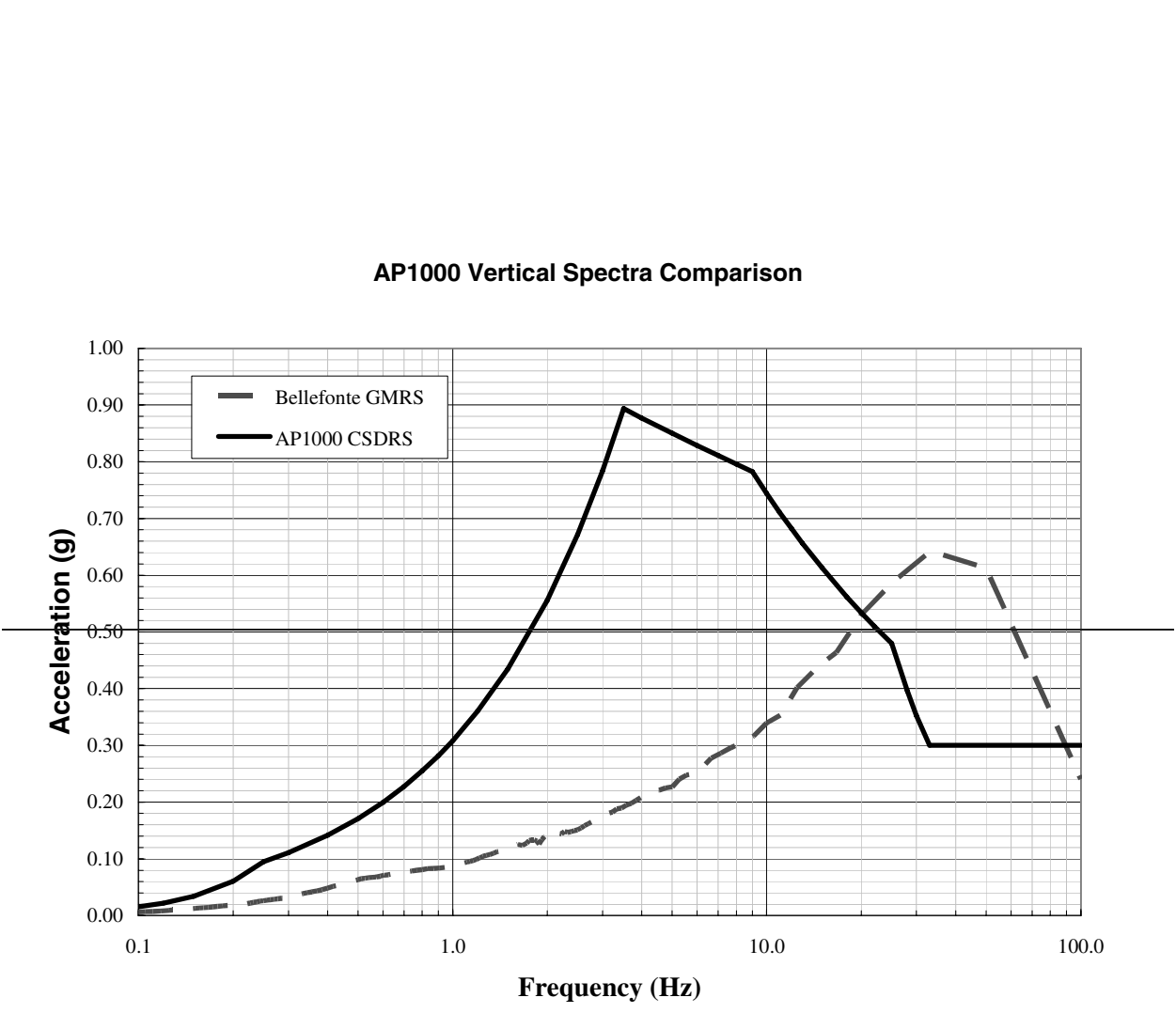
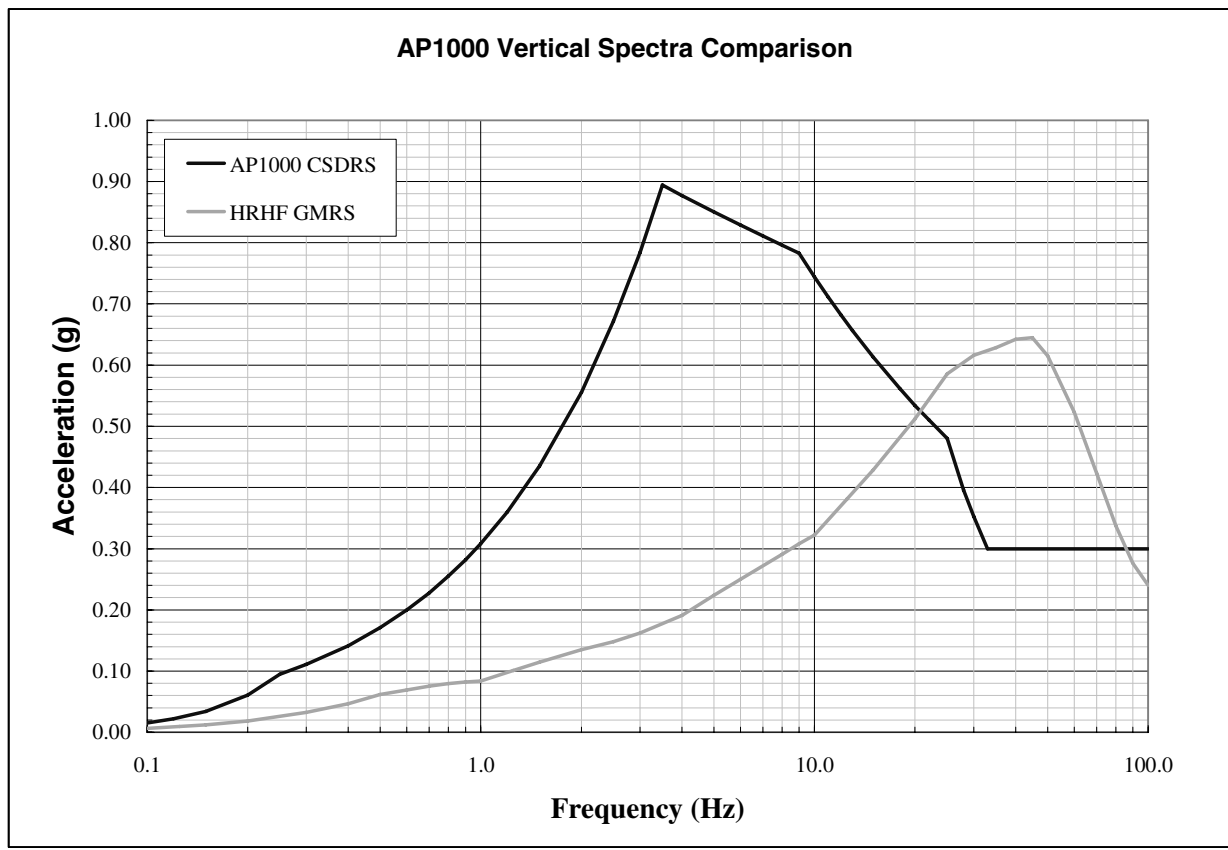


Figure 3I.1-1

Comparison of Horizontal AP1000 CSDRS and ~~Bellefonte~~ HRHF GMRS





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Figure 3I.1-2

Comparison of Vertical AP1000 CSDRS and ~~Bellefonte~~ HRHF GMRS

Chapter 4

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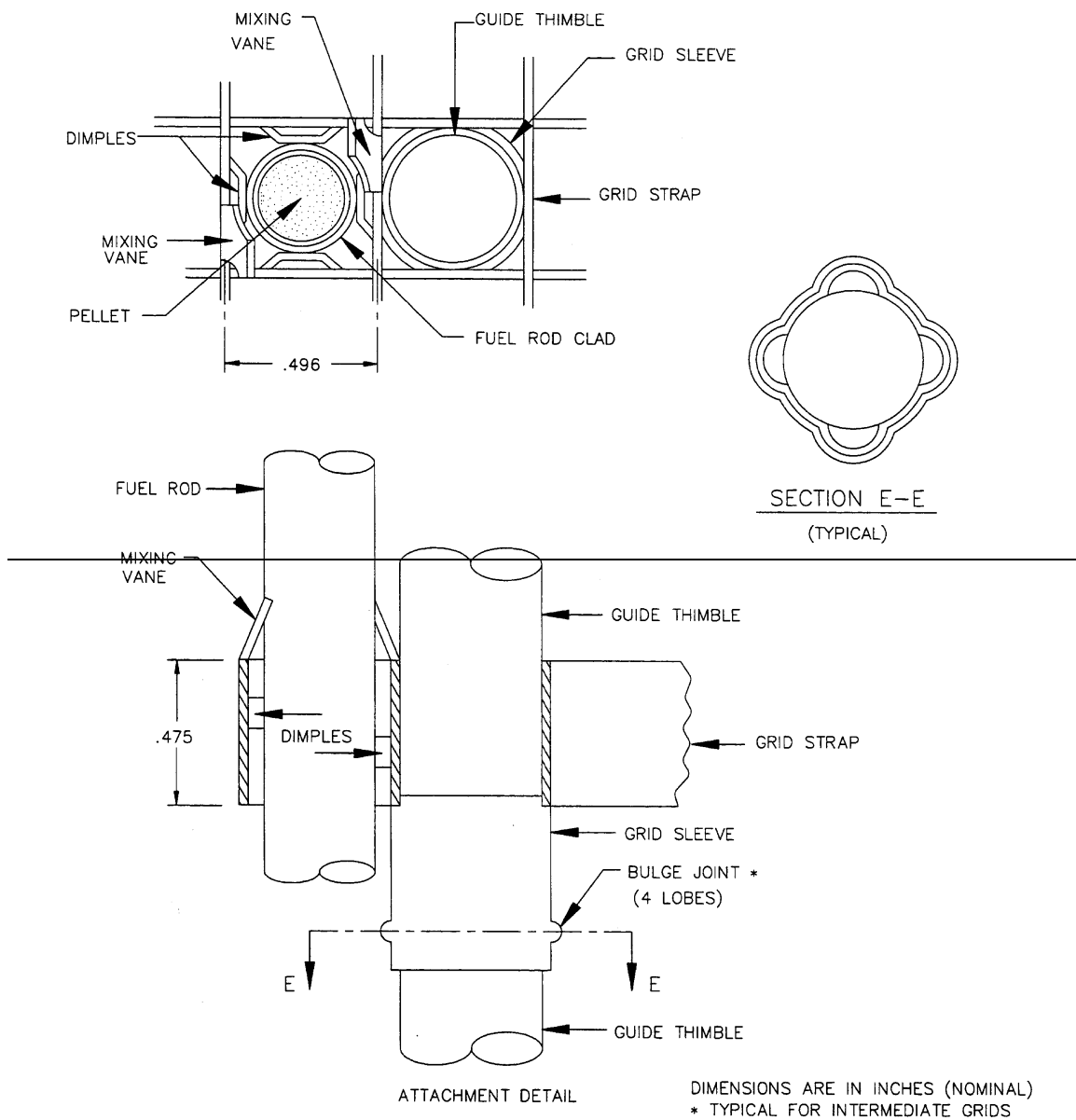
- The control rod drive mechanisms are hydrotested after manufacture at a minimum of 125~~150~~ percent of system design pressure.
- For the initial fuel cycle, the fuel rod temperature coefficient is calculated to be negative for power operating conditions.
- For the initial fuel cycle, the moderator temperature coefficient is calculated to be negative for power operating conditions.

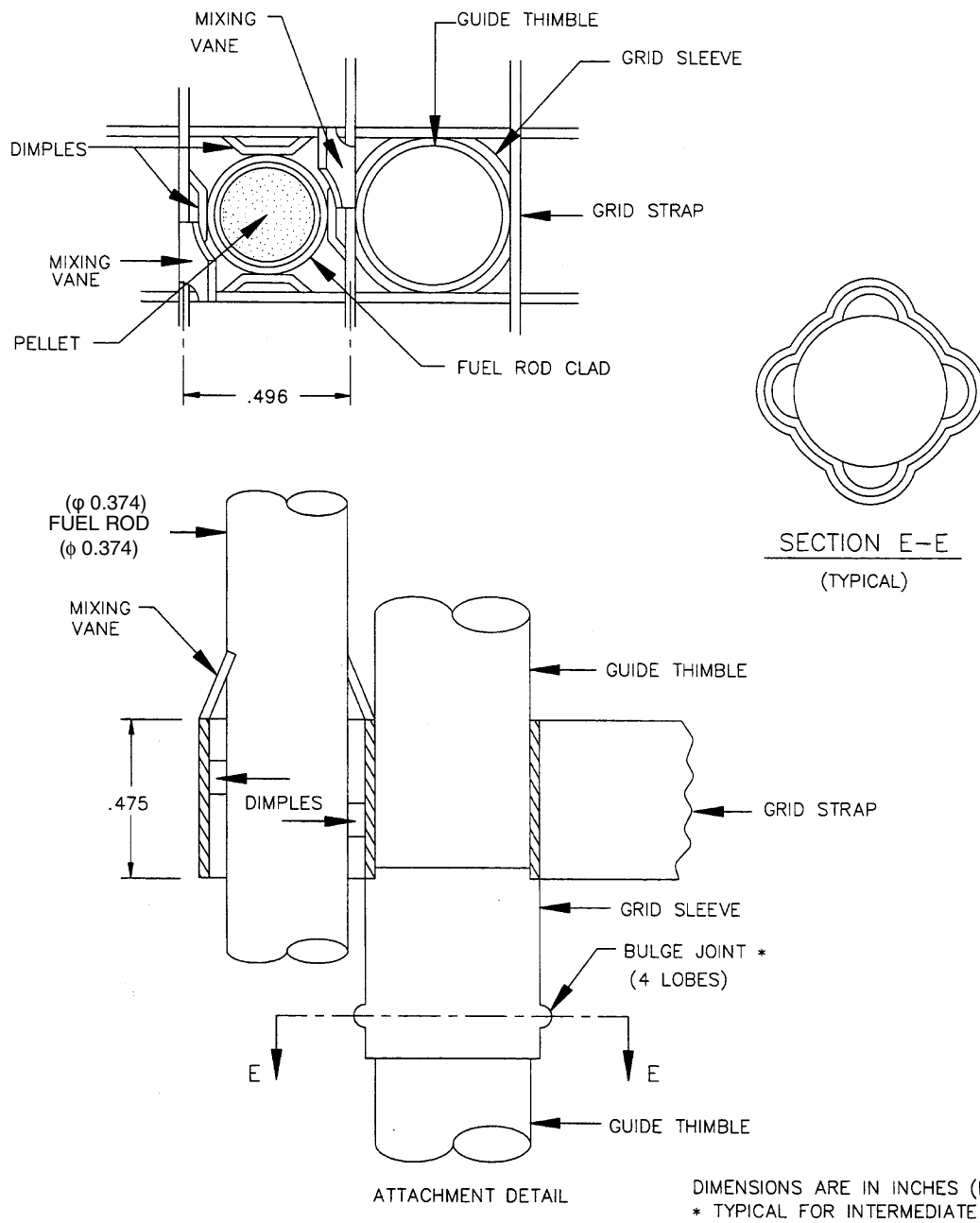
4.1.2 Combined License Information

This section contains no requirement for additional information to be provided in support of Combined License.

4.1.3 References

1. Letter from N. J. Liparulo (Westinghouse) to J. E. Lyons (NRC), "Transmittal of Response to NRC Request for Information on Wolf Creek Fuel Design Modifications," NSD-NRC-97-5189, June 30, 1997.
2. Letter from N. J. Liparulo (Westinghouse) to R. C. Jones (NRC), "Transmittal of Presentation Material for NRC/Westinghouse Fuel Design Change Meeting on April 15, 1996," NSD-NRC-96-4964, April 22, 1996.
3. Letter from Westinghouse to NRC, "Fuel Criteria Evaluation Process Notification for the 17x17 Robust Fuel Assembly with IFM Grid Design," NSD-NRC-98-5796, October 13, 1998.
4. Letter from H. A. Sepp (Westinghouse) to T. E. Collins (NRC), "Notification of FCEP Application for WRB-1 and WRB-2 Applicability to the 17x17 Modified LPD Grid Design for Robust Fuel Assembly Application," NSD-NRC-98-5618, March 25, 1998.
5. Letter from H. A. Sepp (Westinghouse) to T. E. Collins (NRC), "Fuel Criteria Evaluation Process Notification for the Revised Guide Thimble Dashpot Design for the 17x17 XL Robust Fuel Assembly Design," NSD-NRC-98-5722, June 23, 1998.
6. Davidson, S. L., and Kramer, W. R., (Ed.), "Reference Core Report Vantage 5 Fuel Assembly," WCAP-10444-P-A (Proprietary), September 1985 and WCAP-10445-A (Non-Proprietary), December 1983.
7. Davidson, S. L., (Ed.), "VANTAGE 5H Fuel Assembly," Addendum 2-A, WCAP-10444-P-A (Proprietary) and WCAP-10445-NP-A (Non-Proprietary), February 1989.
8. Davidson, S. L., and Nuhfer, D. L., (Ed.), "VANTAGE+ Fuel Assembly Reference Core Report," WCAP-12610-P-A (Proprietary) and WCAP-14342-A (Non-Proprietary), April 1995.





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Figure 4.2-6

Intermediate Flow Mixer Grid to Thimble Attachment

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independently modulated by the rod control system to maintain a nearly constant axial offset throughout the operating power range. The degree of control rod insertion under MSHIM operation allows rapid return to power without the need to change boron concentration.

The target axial offset used during MSHIM load follow operation is roughly the base load operation target axial offset less 10 percent. The negative bias is necessary to allow both positive and negative axial offset control effectiveness by the AO control bank. Extended base load operation is performed by controlling axial offset to the equilibrium target with the first moving M bank nearly fully withdrawn (at bite position) and AO bank fully withdrawn. The “bite” position is defined as the minimum control rod bank position required to provide a differential rod worth of at least 2 pcm/step.

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~~Anticipated MSHIM load follow operation operates with two gray banks fully inserted to provide enough reactivity worth to compensate for transient reactivity effects without the need for soluble boron changes. The degree of control rod insertion under MSHIM operation allows rapid return to power without the need to change boron concentration.~~ Gray rod operation is a Condition 1 event which includes the periodic exchange of gray rod banks.

4.3.2.4.17 Burnup

Control of the excess reactivity for burnup is accomplished using soluble boron and/or burnable absorbers. The boron concentration is limited during operating conditions to maintain the moderator temperature coefficient within its specified limits. A sufficient burnable absorber loading is installed at the beginning of a cycle to give the desired cycle lifetime, without exceeding the boron concentration limit. The end of a fuel cycle is reached when the soluble boron concentration approaches the practical minimum boron concentration in the range of 0 to 10 ppm.

4.3.2.4.18 Rapid Power Reduction System

The reactor power control system is designed with the capability of responding to full load rejection without initiating a reactor trip using the normal rod control system, reactor control system, and the rapid power reduction system. Load rejections requiring greater than a fifty percent reduction of rated thermal power initiate the rapid power reduction system. The rapid power reduction system utilizes preselected control rod groups and/or banks which are intentionally tripped to rapidly reduce reactor power into a range where the rod control and reactor control systems are sufficient to maintain stable plant operation. The consequences of accidental or inappropriate actuation of the rapid power reduction system is included in the cycle specific safety analysis and licensing process.

4.3.2.5 Control Rod Patterns and Reactivity Worth

The rod cluster control assemblies are designated by function as the control groups and the shutdown groups. The terms group and bank are used synonymously to describe a particular grouping of control assemblies. The rod cluster control assembly patterns are displayed in Figure 4.3-27. The control banks are labeled MA, MB, MC, MD, M1, M2, and AO with the MA, MB, MC, and MD banks comprised of gray rod control assemblies; and the shutdown banks are labeled SD1, SD2, SD3, and SD4. Each bank of more than four rod cluster control assemblies,

- The array is either infinite in lateral extent or is surrounded by a conservatively chosen reflector, whichever is appropriate for the design.
- Mechanical uncertainties are treated either by using worst-case conditions or by performing sensitivity studies and obtaining appropriate uncertainties.
- Credit is taken for the neutron absorption in structural materials and in solid materials added specifically for neutron absorption.

The design method which determines the criticality safety of fuel assemblies outside the reactor uses the SCALE 4.4a system (Reference 21), which includes the BONAMI and NITAWL-II codes for cross sections generation and the KENO-V.a code for reactivity determination.

The 238 group library obtained from ENDF/B-V data is the origin of the 44 group library used in these analyses and in the modeling of the critical experiments, which are the basis for the qualification of the SCALE/KENO-V.a (Reference 26) calculation system.

A set of 30 critical experiments has been analyzed using the above method to demonstrate its applicability to criticality analysis and to establish the method bias and uncertainty. The benchmark experiments cover a wide range of geometries, materials, and enrichments, all of them adequate for qualifying methods to analyze light water reactor lattices (References 22 to 25, and 27).

The analysis of the 30 critical experiments results in an average K_{eff} of 0.9969. Comparison with the measured values results in a method bias of 0.0031. The standard deviation of the set of reactivities is 0.00285. The 95/95 tolerance factor is 2.22.

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$$\left[(ks)_{\text{method}}^2 + (ks)_{\text{KENO}}^2 + \sum_i (ks)_{\text{mech}}^2 \right]^{1/2}$$

The analytical methods employed herein conform with ANSI N18.2 (Reference 3), Section 5.7, Fuel Handling System; ANSI N16.9 (Reference 29), NRC Standard Review Plan, subsection 9.1.2, the NRC guidance, “OT Position for Review and Acceptance of Spent Fuel Storage and Handling Applications” (Reference 30).

4.3.2.6.2 Soluble Boron Credit Methodology

The methodology used in this analysis for soluble boron credit is analogous to that of Reference 62, and it uses analysis criteria consistent with those cited in the Safety Evaluation by the Office of Nuclear Reactor Regulation (Reference 63). Reference 62 was reviewed and approved by the NRC. The methodology used in this analysis and in Reference 62 uses axially distributed burnups to represent discharged fuel assemblies.

4.4.2.11.4 Surface Heat Transfer Coefficients

The fuel rod surface heat transfer coefficients during subcooled forced convection and nucleate boiling are presented in subsection 4.4.2.7.1.

4.4.2.11.5 Fuel Clad Temperatures

The outer surface of the fuel rod at the hotspot operates at a temperature a few degrees above fluid temperature for steady-state operation at rated power throughout core life due to the onset of nucleate boiling. At beginning of life this temperature is the same as the clad metal outer surface.

During operation over the life of the core, the buildup of oxides and crud on the fuel rod surface causes the clad surface temperature to increase. Allowance is made in the fuel center melt evaluation for this temperature rise. Since the thermal-hydraulic design basis limits DNB, adequate heat transfer is provided between the fuel clad and the reactor coolant so that the core thermal output is not limited by considerations of clad temperature.

4.4.2.11.6 Treatment of Peaking Factors

The total heat flux hot channel factor, F_Q , is defined by the ratio of the maximum-to-core-average heat flux. The design value of F_Q , as presented in Table 4.3-2 and described in subsection 4.3.2.2.6, is 2.6 for normal operation.

As described in subsection 4.3.2.2.6, the peak linear power resulting from overpower transients/operator errors (assuming a maximum overpower of 118 percent) is less than or equal 22.45 kW/ft. The centerline fuel temperature must be below the uranium dioxide melt temperature over the lifetime of the rod, including allowances for uncertainties. The fuel temperature design basis is described in subsection 4.4.1.2 and results in a maximum allowable calculated center-line temperature of 4700°F. The peak linear power for prevention of center-line melt is greater than 22.5 kW/ft. The center-line temperature at the peak linear power resulting from overpower transients/operator errors (assuming a maximum overpower of 118 percent) is below that required to produce melting.

4.4.3 Description of the Thermal and Hydraulic Design of the Reactor Coolant System

4.4.3.1 Plant Configuration Data

Plant configuration data for the thermal-hydraulic and fluid systems external to the core are provided as appropriate in Chapters 5, 6, and 9. Areas of interest are as follows:

- Total coolant flow rates for the reactor coolant system and each loop are provided in Table 5.1-3. Flow rates employed in the evaluation of the core are presented throughout Section 4.4.
- Total reactor coolant system volume including pressurizer and surge line and reactor coolant system liquid volume, including pressurizer water at steady-state power conditions, are given in Table 5.1-2.

- Comparing the impact event with the times and type of normally occurring plant operation events received from plant control system such as a control rod stepping.
- Comparing the number of events detected within a given time interval.

The sensors of the impact monitoring system are fastened mechanically to the reactor coolant system at potential loose part collection regions including the upper and lower head region of the reactor pressure vessel, and the reactor coolant inlet region of each steam generator.

The equipment inside the containment is designed to remain functional through an earthquake of a magnitude equal to 50 percent of the calculated safe shutdown earthquake and normal environments (radiation, vibration, temperature, humidity) anticipated during the operating lifetime. The instrument channels associated with the sensors at each reactor coolant system location are physically separated from each other starting at the sensor locations to a point in the plant that is always accessible for maintenance during full-power operation.

The digital metal impact monitoring system is calibrated prior to plant startup. Capabilities exist for subsequent periodic online channel checks and channel functional tests and for offline channel calibrations at refueling outages.

4.4.7 Combined License Information

4.4.7.1 The Combined License information requested in Section 4.4.7.1 has been totally addressed in APP-GW-GLR-059 (WCAP-16652-NP, Rev. 0 – Reference 87). No additional work is required by the Combined License applicant to address the Combined License information requested in this subsection.

The following words represent the original License information item commitment, which has been addressed as discussed above:

Combined License applicants referencing the AP1000 certified design will address changes to the reference design of the fuel, burnable absorber rods, rod cluster control assemblies, or initial core design from that presented in the DCD.

4.4.7.2 Following selection of the actual plant operating instrumentation and calculation of the instrumentation uncertainties of the operating plant parameters as discussed in subsection 7.1.6, and prior to fuel load, the Combined License holder applicants will calculate the design limit DNBR values. The calculations will be completed using the RTDP with these instrumentation uncertainties and confirm that either the design limit DNBR values as described in Section 4.4, “Thermal and Hydraulic Design,” remain valid, or that the safety analysis minimum DNBR bounds the new design limit DNBR values plus DNBR penalties, such as rod bow penalty.

4.4.8 References

1. ANSI N18.2a-75, “Nuclear Safety Criteria for the Design of Stationary Pressurized Water Reactor Plants.”

Table 4.4-1 (Sheet 2 of 2)

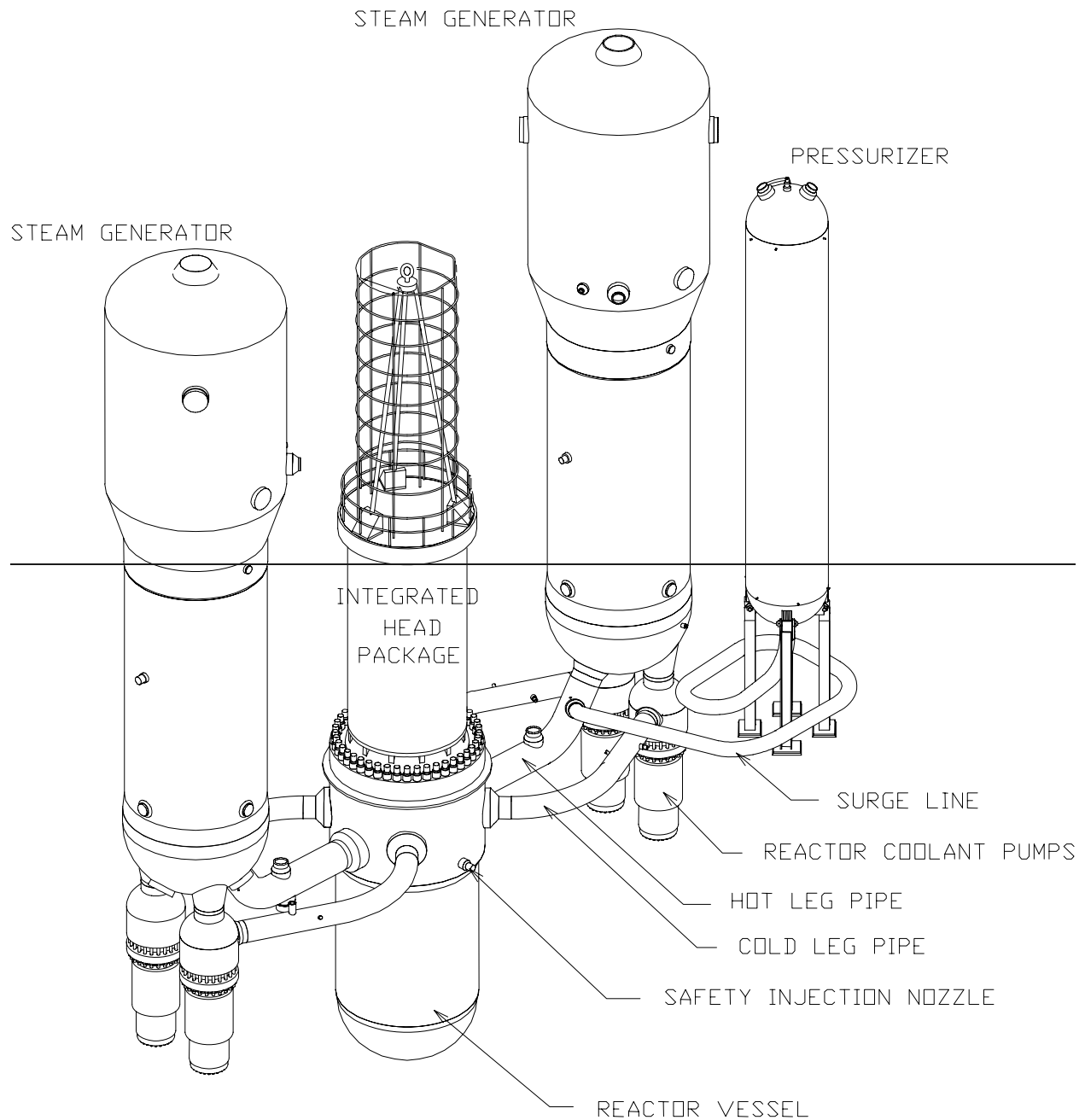
**THERMAL AND HYDRAULIC COMPARISON TABLE
(AP1000, AP600 AND A TYPICAL WESTINGHOUSE XL PLANT)**

Design Parameters	AP1000 ^(a)	AP600	Typical XL Plant
Heat transfer			
Active heat transfer surface area (ft ²) ^(f)	56,700	44,884	69,700
Average heat flux (BTU/hr-ft ²)	199,300	143,000	181,200
Maximum heat flux for normal operation (BTU/hr-ft ²) ^(g)	518,200	372,226	498,200
Average linear power (kW/ft) ^(f-m)	5.72	4.11	5.20
Peak linear power for normal operation (kW/ft) ^(g,h)	14.9	10.7	14.0
Peak linear power resulting from overpower transients/operator errors, assuming a maximum overpower of 118% (kW/ft) ^(h)	≤22.45	22.5	≤22.45
Peak Linear power for prevention of center-line melt (kW/ft) ⁽ⁱ⁾	22.5	22.5	22.45
Power density (kW/l of core) ^(j)	109.7	78.82	98.8
Specific power (kW/kg uranium) ^(j)	40.2	28.89	36.6
Fuel central temperature			
Peak at peak linear power for prevention of centerline melt (°F)	4700	4,700	4700
Pressure drop ^(k)			
Across core (psi)	39.9 ± 4.0 ^(l)	17.5 ± 1.7	38.8 ± 3.9
Across vessel, including nozzle (psi)	62.3 ± 6.2 ^(l)	45.3 ± 4.5	59.7 ± 6.0

Notes:

- (a) Robust Fuel Assembly.
- (b) 1.25 applies to Core and Axial Offset limits; 1.22 and 1.21 apply to all other RTDP transients.
- (c) WRB-2M is used for AP1000. WRB-2 or W-3 is used for AP1000 where WRB-2M is not applicable. See subsection 4.4.2.2.1 for use of W-3, WRB-2 and WRB-2M correlations.
- (d) Based on vessel average temperature equal to 573.6°F. Flow rates and temperatures based on 10 percent steam generator tube plugging.
- (e) Based on thermal design flow and 5.9 percent bypass flow.
- (f) Based on densified active fuel length. The value for AP1000 is rounded to 5.72 kW/ft.
- (g) Based on 2.60 F_Q peaking factor.
- (h) See subsection 4.3.2.2.6.
- (i) See subsection 4.4.2.11.6.
- (j) Based on cold dimensions and 95.5 percent of theoretical density fuel for AP1000; 95 percent for others.
- (k) These are typical values based on best-estimate reactor flow rate as discussed in Section 5.1.
- (l) Inlet temperature = 536.8°F.
- (m) The value for AP1000 is rounded to 5.72 kW/ft.

Chapter 5



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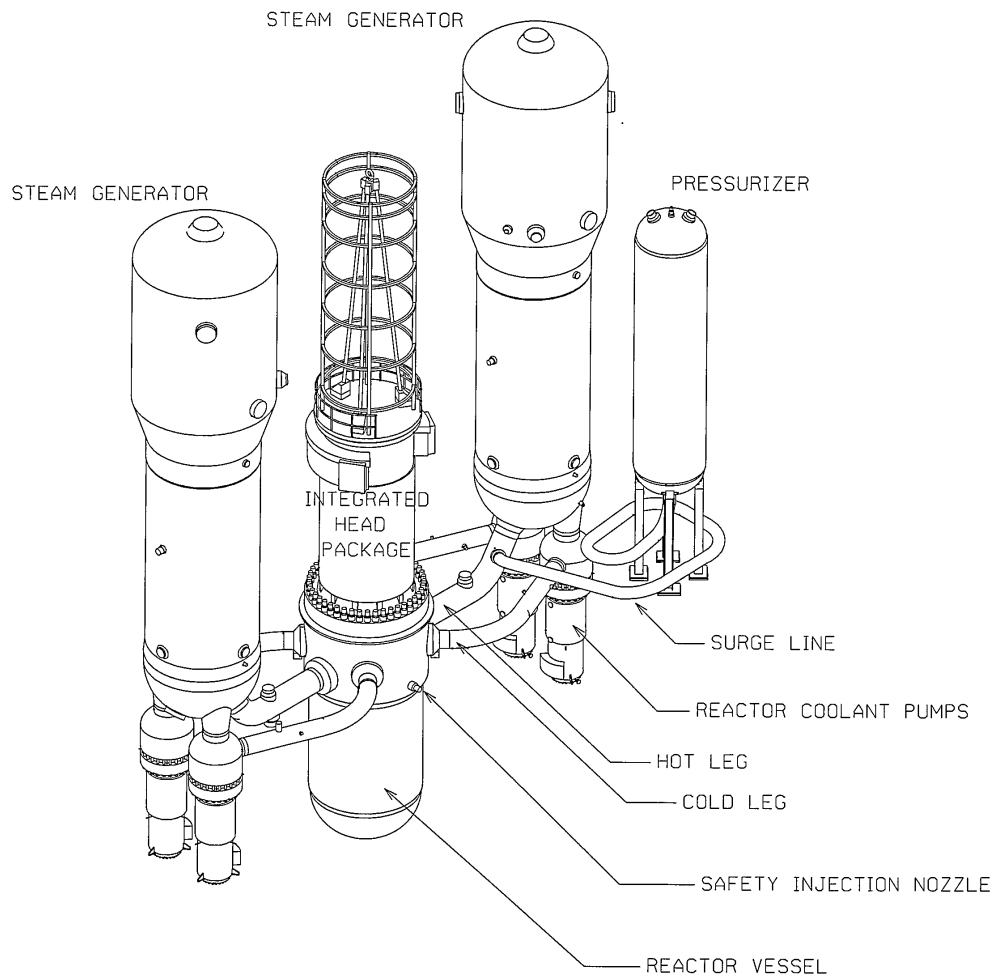


Figure 5.1-2

Reactor Coolant Loops – Isometric View

5.2.1.3 Alternate Classification

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The Code of Federal Regulations, Section 10 CFR 50.55a requires the reactor coolant pressure boundary be class A (ASME Boiler and Pressure Vessel Code Section III, Class 1). Components which are connected to the reactor coolant pressure boundary that can be isolated from the reactor coolant system by two valves in series (both closed, both open, or one closed and the other open) with automatic actuation to close can be classified as class C (ASME Section III, class 3) according to 50.55a.

A portion of the chemical and volume control system inside containment is not classified as safety-related. The classification of the AP1000 reactor coolant pressure boundary deviates from the requirement that the reactor coolant pressure boundary be classified as safety related and be constructed using the ASME Code, Section III as provided in 10 CFR 50.55a. The safety-related classification of the AP1000 reactor coolant pressure boundary ends at the third isolation valve between the reactor coolant system and the chemical and volume control system. The nonsafety-related portion of the chemical and volume control system inside containment provides purification of the reactor coolant and includes heat exchangers, demineralizers, filters and connecting piping. For a description of the chemical and volume control system, refer to subsection 9.3.6. The portion of the chemical and volume control system between the inside and outside containment isolation valves is classified as Class B and is constructed using the ASME Code, Section III.

The nonsafety-related portion of the chemical and volume control system is designed using ANSI B31.1 and ASME Code, Section VIII for the construction of the piping, valves, and components. The nonsafety-related portion of the CVS inside containment is analyzed seismically. The methods and criteria used for the seismic analysis are similar to those used of seismic Category II pipe and are defined in the subsection 5.2.1.1. The chemical and volume control system components are located inside the containment which is a seismic Category I structure.

The alternate classification of the nonsafety-related purification subsystems satisfies the purpose of 10 CFR 50.55a that structures, systems, and components of nuclear power plants which are important to safety be designed, fabricated, erected, and tested to quality standards that reflect the importance of the safety functions to be performed.

The AP1000 chemical and volume control system is not required to perform safety-related functions such as emergency boration or reactor coolant makeup. Safety-related core makeup tanks are capable of providing sufficient reactor coolant makeup for shutdown and cooldown without makeup supplied by the chemical and volume control system. Safe shutdown of the reactor does not require use of the chemical and volume control system makeup. AP1000 safe shutdown is discussed in Section 7.4.

The isolation valves between the reactor coolant system and the chemical and volume control system are active safety-related valves that are designed, qualified, inspected and tested for the isolation requirements. The isolation valves between the reactor coolant system and chemical and volume control system are designed and qualified for design conditions that include closing against blowdown flow with full system differential pressure. These valves are qualified for

5.2.2.8 Process Instrumentation

Each pressurizer safety valve discharge line incorporates a main control room temperature indicator and alarm to notify the operator of steam discharge due to either leakage or actual valve operation.

5.2.2.9 System Reliability

ASME Code safety valves and relief valves have demonstrated a high degree of reliability over many years of service. The in-service inspection and testing required of safety valves and relief valves (Subsections 3.9.6 and 5.2.4.4-8 and Section 6.6) provides assurance of continued reliability and conformance to setpoints. The assessment of reliability, availability, and maintainability which is done to evaluate the estimated availability for the AP1000 includes estimates for the contribution of safety valves and relief valves to unavailability. These estimates were based on experience for operating units.

5.2.2.10 Testing and Inspection

Subsections 3.9.6 and 5.4.8 and Section 6.6 discuss the preservice and in-service testing and inspection required for the safety valves and relief valves. The testing and inspection requirements are in conformance with industry standards, including Section XI of the ASME Code.

5.2.3 Reactor Coolant Pressure Boundary Materials

5.2.3.1 Materials Specifications

Table 5.2-1 lists material specifications used for the principal pressure-retaining applications in Class 1 primary components and reactor coolant system piping. Material specifications with grades, classes or types are included for the reactor vessel components, steam generator components, reactor coolant pump, pressurizer, core makeup tank, and the passive residual heat removal heat exchanger. Table 5.2-1 lists the application of nickel-chromium-iron alloys in the reactor coolant pressure boundary. The use of nickel-chromium-iron alloy in the reactor coolant pressure boundary is limited to Alloy 690, or its associated weld metals Alloys 52 and 152. Steam generator tubes use Alloy 690 in the thermally treated form. Nickel-chromium-iron alloys are used where corrosion resistance of the alloy is an important consideration and where the use of nickel-chromium-iron alloy is the choice because of the coefficient of thermal expansion. Subsection 5.4.3 defines reactor coolant piping. See subsection 4.5.2 for material specifications used for the core support structures and reactor internals. See appropriate sections for internals of other components. Engineered safeguards features materials are included in subsection 6.1.1. The nonsafety-related portion of the chemical and volume control system inside containment in contact with reactor coolant is constructed of or clad with corrosion resistant material such as Type 304 or Type 316 stainless steel or material with equivalent corrosion resistance. The materials are compatible with the reactor coolant. The nonsafety-related portion of the chemical and volume control system is not required to conform to the process requirements outlined below.

Table 5.2-1 material specifications are the materials used in the AP1000 reactor coolant pressure boundary. The materials used in the reactor coolant pressure boundary conform to the applicable

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NRC 061

raw material and controlling the hardness during fabrication by process control of bending, cold forming, straightening or other similar operation. Grinding of material in contact with reactor coolant is controlled by procedures. Ground surfaces are finished with successively finer grit sizes to remove the bulk of cold worked material.

5.2.3.5 Threaded Fastener Lubricants

The lubricants to be used on threaded fasteners which maintain pressure boundary integrity in the reactor coolant and related systems and in the steam, feed, and condensate systems; threaded fasteners used inside those systems; and threaded fasteners used in component structural support for those systems are specified in the design specification. Field selection of thread lubricants is not permitted. The thread lubricants are selected based on experience and test data which show them to be effective, but not to cause or accelerate corrosion of the fastener. Where leak sealants are used on threaded fasteners or can be in contact with the fastener in service, their selection is based on satisfactory experience or test data. Selection considers possible adverse interaction between sealants and lubricants. Lubricants containing molybdenum sulphide are prohibited.

5.2.4 Inservice Inspection and Testing of Class 1 Components

Preservice and inservice inspection and testing of ASME Code Class 1 pressure-retaining components (including vessels, piping, pumps, valves, bolting, and supports) within the reactor coolant pressure boundary are performed in accordance with Section XI of the ASME Code including addenda according to 10 CFR 50.55a(g). This includes all ASME Code Section XI mandatory appendices.

The specific edition and addenda of the Code used to determine the requirements for the inspection and testing plan for the initial and subsequent inspection intervals is to be delineated in the inspection program. The Code includes requirements for system pressure tests and functional tests for active components. The requirements for system pressure tests are defined in Section XI, IWA-5000 and IWB-5000. These tests verify the pressure boundary integrity in conjunction with inservice inspection. Section 6.6 discusses Classes 2 and 3 component examinations.

Subsection 3.9.6 discusses the in-service functional testing of valves for operational readiness. Since none of the pumps in the AP1000 are required to perform an active safety function, the operational readiness test program for pumps is controlled administratively.

In conformance with ASME Code and NRC requirements, the preparation of inspection and testing programs is discussed in subsection 5.2.6. A preservice inspection program (nondestructive examination) and a preservice test program for valves for the AP1000 will be developed and submitted to the NRC. The in-service inspection program and in-service test program will be submitted to the NRC as discussed in subsection 5.2.6. These programs will comply with applicable in-service inspection provisions of 10 CFR 50.55a(b)(2).

The preservice programs provides details of areas subject to examination, as well as the method and extent of preservice examinations. The in-service programs details the areas subject to examination and the method, extent, and frequency of examinations. Additionally, component supports and snubber testing examination requirements are included in the inspection programs.

modules before construction provides the accessibility for inspection and maintenance. Relief from Section XI requirements should not be required for Class 1 pressure retaining components in the AP1000. Future unanticipated changes in the ASME Code, Section XI requirements could, however, necessitate relief requests. Relief from the inspection requirements of ASME Code, Section XI will be requested when full compliance is not practical according to the requirements of 10 CFR 50.55a(g)(5)(iv). In such cases, specific information will be provided which identifies the applicable Code requirements, justification for the relief request, and the inspection method to be used as an alternative.

Space is provided to handle and store insulation, structural members, shielding, and other materials related to the inspection. Suitable hoists and other handling equipment, lighting, and sources of power for inspection equipment are installed. The integrated head package provides for access to inspect the reactor vessel head and the weld of the control rod drive mechanisms to the reactor vessel head. Closure studs, nuts, and washers are removed to a dry location for direct inspection.

5.2.4.3 Examination Techniques and Procedures

The visual, surface, and volumetric examination techniques and procedures agree with the requirements of Subarticle IWA-2200 and Table IWB-2500-1 of the ASME Code, Section XI. Qualification of the ultrasonic inspection equipment, personnel and procedures is in compliance with Appendix VII of the ASME Code, Section XI. The liquid penetrant method or the magnetic particle method is used for surface examinations. Radiography, ultrasonic, or eddy current techniques (manual or remote) are used for volumetric examinations.

The reactor vessel is designed so that the reactor pressure vessel (RPV) inspections can be performed primarily from the vessel internal surfaces. These inspections can be done remotely using existing inspection tool designs to minimize occupational radiation exposure and to facilitate the inspections. Access is also available for the application of inspection techniques from the outside of the complete reactor pressure vessel. Reactor pressure vessel welds are examined to meet the requirements of Regulatory Guide 1.150 as defined in subsection 1.9.1 Appendix VIII of ASME Code, Section XI, which has been incorporated into the guidance of Regulatory Guide 1.150, as defined in subsection 1.9.1.

5.2.4.4 Inspection Intervals

Inspection intervals are established as defined in Subarticles IWA-2400 and IWB-2400 of the ASME Code, Section XI. The interval may be extended by as much as one year so that inspections are concurrent with plant outages. It is intended that in-service examinations be performed during normal plant outages such as refueling shutdowns or maintenance shutdowns occurring during the inspection interval.

5.2.4.5 Examination Categories and Requirements

The examination categories and requirements are established according to Subarticle IWB-2500 and Table IWB-2500-1 of the ASME Code, Section XI. Class 1 piping supports will be examined in accordance with ASME Section XI, IWF-2500.

NRC 148
NRC 115

NRC 148

The preservice examinations comply with IWB-2200.

5.2.4.6 Evaluation of Examination Results

Examination results are evaluated according to IWA-3000 and IWB-3000, with flaw indications according to IWB-3400 and Table IWA-B-3410-1. Repair procedures, if required, are according to IWA-B-4000 of the ASME Code, Section XI.

5.2.4.7 System Leakage and Hydrostatic Pressure Tests

System pressure tests comply with IWA-5000 and IWB-5000 of the ASME Code, Section XI. These system pressure tests are included in the design transients defined in Subsection 3.9.1. This subsection discusses the transients included in the evaluation of fatigue of Class 1 components due to cyclic loads.

5.2.5 Detection of Leakage Through Reactor Coolant Pressure Boundary

The reactor coolant pressure boundary (RCPB) leakage detection monitoring provides a means of detecting and to the extent practical, identifying the source and quantifying the reactor coolant leakage. The detection monitors perform the detection and monitoring function in conformance with the requirements of General Design Criteria 2 and 30 and the recommendations of Regulatory Guide 1.45. Leakage detection monitoring is also maintained in support of the use of leak-before-break criteria for high-energy pipe in containment. See subsection 3.6.3 for the application of leak-before-break criteria.

Leakage detection monitoring is accomplished using instrumentation and other components of several systems. Diverse measurement methods including level, flow, and radioactivity measurements are used for leak detection. The equipment classification for each of the systems and components used for leak detection is generally determined by the requirements and functions of the system in which it is located. There is no requirement that leak detection and monitoring components be safety-related. See Figure 5.2-1 for the leak detection approach. The descriptions of the instrumentation and components used for leak detection and monitoring include information on the system.

To satisfy position 1 of Regulatory Guide 1.45, reactor coolant pressure boundary leakage is classified as either identified or unidentified leakage. Identified leakage includes:

- Leakage from closed systems such as reactor vessel seal or valve leaks that are captured and conducted to a collecting tank
- Leakage into auxiliary systems and secondary systems (intersystem leakage) (This leakage is considered to be part of the 10 gpm limit identified leakage in the bases of the technical specification 3.4.8. This additional leakage must be considered in the evaluation of the reactor coolant inventory balance.)

Other leakage is unidentified leakage.

NRC 148

5.2.6 Combined License Information Items

5.2.6.1 ASME Code and Addenda

The Combined License applicant will address in its application the portions of later ASME Code editions and addenda to be used to construct components that will require NRC staff review and approval. The Combined License applicant will address consistency of the design with the construction practices (including inspection and examination methods) of the later ASME Code edition and addenda added as part of the Combined License application. The Combined License applicant will address the addition of ASME code cases approved subsequent to design certification.

5.2.6.2 Plant-Specific Inspection Program

The Combined License applicant will provide a plant-specific preservice inspection and inservice inspection program. The program will address reference to the edition and addenda of the ASME Code Section XI used for selecting components subject to examination, a description of the components exempt from examination by the applicable code, and drawings or other descriptive information used for the examination.

The preservice inspection program will include examinations of the reactor vessel closure head equivalent to those outlined in subsection 5.3.4.7.

NRC 089 |

The inservice inspection program will address the susceptibility calculations, inspection categorization, inspections of the reactor vessel closure head, and associated reports and notifications as defined in First Revised NRC Order EA-03-009, "Interim Inspection Requirements for Reactor Vessel Heads at PWRs" or NRC requirements that may supercede the Order.

NRC 089 |

The COL applicant will identify any areas of inspection required by First Revised Order EA-03-009, or required by subsequent NRC requirements that may supercede the Order, that the applicant will be unable to perform or choose to perform an alternate. The applicant will submit to the NRC for review and approval a description of the proposed inspections to be performed, a description of any differences from the applicable NRC requirements, and an assessment of the acceptability of the inspection the applicant proposes to perform to address NRC requirements.

The inservice inspection program will also include provisions to ensure that boric acid corrosion does not degrade the reactor coolant pressure boundary.

5.2.7 References

1. Burnett, T. W. T., et al., "LOFTRAN Code Description," WCAP-7907-P-A (Proprietary), and WCAP-7907-A (Nonproprietary), April 1984.
2. EPRI PWR Safety and Relief Valve Test Program, Safety and Relief Valve Test Report, Interim Report, April 1982.

Table 5.2-1 (Sheet 2 of 5)

REACTOR COOLANT PRESSURE BOUNDARY MATERIALS SPECIFICATIONS

			Component	Material	Class, Grade, or Type
			Vent pipe	SB-166	N06690
				SB-167	N06690
				or	
				SA-312 ⁽¹⁾	TP304, TP304L, TP304LN, TP316, TP316L, TP316LN
NRC 077				SA-376	TP304, TP304LN, TP316, TP316LN
				Steam Generator Components	
				Pressure plates	SA-533 Type B, CL 1 or CL 2
				Pressure forgings (including nozzles and tube sheet)	SA-508 CL 1A or GR 3, CL 2
NRC 077			Nozzle safe ends	SA-182	F316, F316L, F316LN
				SA-336	F316LN
				or	
				SB-564	N06690
NRC 077			Channel heads	SA-508	GR 3, CL 2
				Tubes	SB-163 N06690
				Manway studs/	SA-193 GR B7
				Nuts	SA-194 GR 72H
NRC 077			Pressurizer Components		
			Nozzle safe ends	Pressure plates	SA-533 Type B, CL 1
				Pressure forgings	SA-508 GR 3, CL 2
				SA-182	F316, F316L, F316LN
NRC 077				SA-338	F316, F316L, F316LN
				or	
				SB-163	N06690
				Manway studs/	SA-193 GR B7
NRC 077				Nuts	SA-194 GR 72H

Table 5.2-1 (Sheet 3 of 5)

REACTOR COOLANT PRESSURE BOUNDARY MATERIALS SPECIFICATIONS

Component	Material	Class, Grade, or Type
Reactor Coolant Pump		
Pressure forgings	SA-182 <u>SA-508</u> or SA-336	F304, F304L, F304LN, F316, F316L, F316LN <u>GR1</u> F304, F304L, F304LN, F316, F316L, F316LN
Pressure casting	SA-351	CF3A or CF8A
Tube and pipe	SA-213 SA-376 or SA-312 ⁽¹⁾	TP304, TP304L, TP304LN, TP316, TP316L, TP316LN TP304, TP304LN, TP316, TP316LN TP304, TP304L, TP304LN, TP316, TP316L, TP316LN
Pressure plates	SA-240	304, 304L, 304LN, 316, 316L, 316LN
Closure bolting	SA-193 or SA-540	GR B7 or GR B24, <u>CL 2 & CL 4</u> , or GR B23, <u>CL2</u> , CL 3 & 4
Reactor Coolant Piping		
Reactor coolant pipe	SA-376 SA-182 ⁽²⁾	TP304, TP304LN, TP316, TP316LN F304, F304L, F304LN, F316, F316L, F316LN
Reactor coolant fittings, branch nozzles	SA-376 SA-182	TP304, TP304LN, TP316, TP316LN F304, F304L, 304LN, F316, F316L, F316LN
Surge line	SA-376 or SA-312 ⁽¹⁾	TP304, TP304LN, TP316, TP316LN TP304, TP304L, TP304LN, TP316, TP316L, TP316LN

Table 5.2-3	
ASME CODE CASES	
Code Case Number	Title
N-4-11	Special Type 403 Modified Forgings or Bars, Section III, Division 1, Class 1 and Class CS
N-20-4	SB-163 Nickel-Chromium-Iron Tubing (Alloys 600 and 690) and Nickel-Iron-Chromium Alloy 800 at a Specified Minimum Yield Strength of 40.0 ksi and Cold Worked Alloy 800 at Yield Strength of 47.0 ksi, Section III, Division 1, Class 1
N-60-5	Material for Core Support Structures, Section III, Division 1 ^(a)
N-71-18	Additional Material for Subsection NF, Class 1, 2, 3 and MC Component Supports Fabricated by Welding, Section III Division 1
[N-122-2	<i>Stress Indices for integral Structural Attachments Section III, Division 1, Class 1]*</i>
N-249-14	Additional Materials for Subsection NF, Class 1, 2, 3, and MC Supports Fabricated Without Welding, Section III, Division 1 ^(b)
[N-284-1	<i>Metal Containment Shell Buckling Design Methods, Section III, Division 1 Class MC]*</i>
[N-318-5	<i>Procedure for Evaluation of the Design of Rectangular Cross Section Attachments on Class 2 or 3 Piping Section III, Division]*</i>
[N-319-3	<i>Alternate Procedure for Evaluation of Stresses in Butt Welding Elbows in Class 1 Piping Section III, Division 1]*</i>
[N-391-2	<i>Procedure for Evaluation of the Design of Hollow Circular Cross Section Welded Attachments on Class 1 Piping Section III, Division 1]*</i>
[N-392-3	<i>Procedure for Valuation of the Design of Hollow Circular Cross Section Welded Attachments on Class 2 and 3 Piping Section III, Division 1^(c)]*</i>
N-474-2	Design Stress Intensities and Yield Strength Values for UNS06690 With a Minimum Yield Strength of 35 ksi, Class 1 Components, Section III, Division 1
2142-1	F-Number Grouping for Ni-Cr-Fe, Classification UNS N06052 Filler Metal, Section IX
2143-1	F-Number Grouping for Ni-Cr-Fe, Classification UNS W86152 Welding Electrode, Section IX
<u>N-655</u>	<u>Use of SA-738, Grade B, for Metal Containment Vessels, Class MC, Section 11, Division 1</u>

Notes:

- (a) Use of this code case will meet the conditions for Code Case N-60-4 in Reg. Guide 1.85 Revision 30.
 (b) Use of this code case will meet the conditions for Code Case N-249-10 in Reg. Guide 1.85 Revision 30.
 (c) Use of this code case will meet the conditions for Code Case N-392-1 in Reg. Guide 1.84 Revision 30.

*NRC Staff approval is required prior to implementing a change in this information; see DCD Introduction Section 3.5.

NRC 093

- The closure head is stored on a stand on the reactor operating deck during refueling to facilitate direct visual inspection.
- Reactor vessel studs, nuts, and washers can be removed to dry storage during refueling.
- Access is provided to the reactor vessel nozzle safe ends. The insulation covering the nozzle-to-pipe welds may be removed.

Because radiation levels and remote underwater accessibility limits access to the reactor vessel, several steps have been incorporated into the design and manufacturing procedures in preparation for the periodic nondestructive tests which are required by the ASME Code inservice inspection requirements. These are as follows:

- Shop ultrasonic examinations are performed on internally clad surfaces to an acceptance and repair standard to provide an adequate cladding bond to allow later ultrasonic testing of the base metal from the inside surface. The size of cladding bond defect allowed is 0.25 inch by 0.75 inch with the greater direction parallel to the weld in the region bounded by $2T$ (T = wall thickness) on both sides of each full-penetration pressure boundary weld. Unbounded areas exceeding 0.442 square inches (0.75-inch diameter) in other regions are rejected.
- The design of the reactor vessel shell is an uncluttered cylindrical surface to permit future positioning of the test equipment without obstruction.
- The weld-deposited clad surface on both sides of the welds to be inspected is specifically prepared to ensure meaningful ultrasonic examinations.
- During fabrication, full-penetration ferritic pressure boundary welds are ultrasonically examined in addition to code examinations.
- After the shop hydrostatic testing, full-penetration ferritic pressure boundary welds (with the exception of the closure head welds), as well as the nozzles to safe end welds, are ultrasonically examined from both the inside and outside diameters in addition to ASME Code, Section III requirements.
- Preservice examinations for the closure head will include a baseline top-of-the head visual examination; ultrasonic examinations of the inside diameter surface of each vessel head penetration; eddy current examinations of the surface of head penetration welds, the outside diameter surface of the vessel penetrations, and the inside diameter surface of the penetrations; and post-hydro liquid penetrant examinations of accessible surfaces that have undergone preservice inspection eddy current examinations.

The vessel design and construction enables inspection in accordance with the ASME Code, Section XI. ~~The reactor vessel inservice inspection program is detailed in the technical specifications.~~

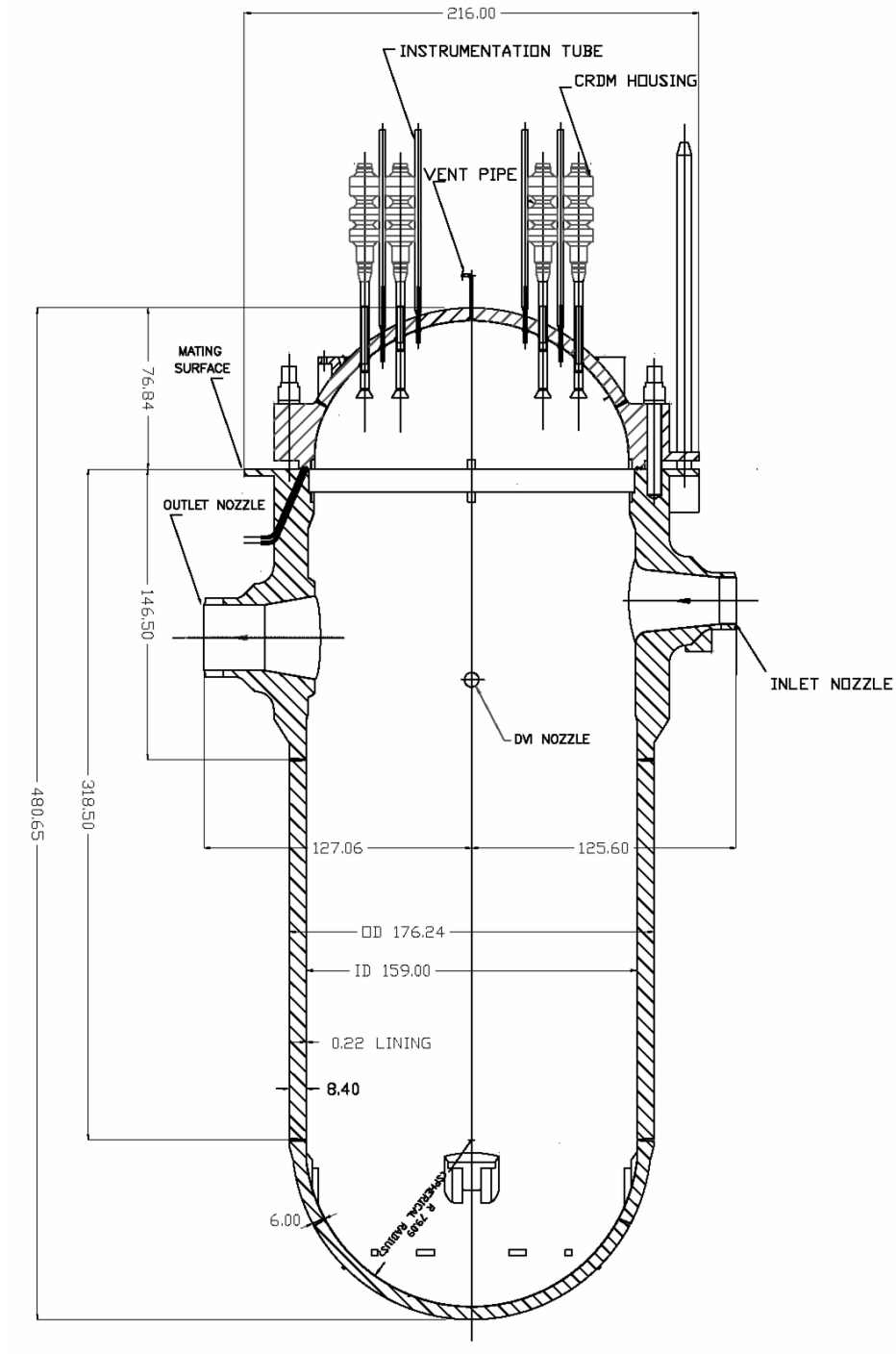
5.3.6.5 Reactor Vessel Insulation

NRC 136

The Combined License applicant will address verification that the reactor vessel insulation design was verified to be consistent with the design bases established for in-vessel retention. The ULPU Configuration V test data is suitable to be used and was used to develop the design loads for the AP1000 reactor vessel insulation design. See Reference 8 for details.

5.3.7 References

1. ASTM E-185-82, "Standard Practice for Conducting Surveillance Tests for Light-Water Cooled Nuclear Power Reactor Vessels."
2. Regulatory Guide 1.190, "Calculational and Dosimetry Methods for Determining Pressure Vessel Neutron Fluence," United States Nuclear Regulatory Commission, Office of Nuclear Reactor Research, March, 2001.
3. WCAP-15557, "Qualification of the Westinghouse Pressure Vessel Neutron Fluence Evaluation Methodology," S. L. Anderson, August 2000.
4. NRC Policy Issue, "Pressurized Thermal Shock," SECY-82-465, November 23, 1982.
5. Theofanous, T.G., et al., "Limits of Coolability in the AP1000-Related ULPU-2400 Configuration V Facility," CRSS-03/06, June 2003.
6. WCAP-14040-NP-A, Revision 2, "Methodology Used to Develop Cold Overpressure Mitigating System Setpoints and RCS Heatup and Cooldown Limit Curves," J. D. Andrachek, et al., January 1996.
7. APP-GW-GLR-023, "Surveillance Capsule Lead Factor and Azimuthal Location Confirmation," Westinghouse Electric Company LLC.
8. APP-GW-GLR-060, "Reactor Vessel Insulation System – Verification of In-Vessel Retention Design Bases," Westinghouse Electric Company LLC.



NRC 115

Figure 5.3-6

Reactor Vessel Key Dimensions,
Side View

5.4.2.2 Design Description

The AP1000 steam generator is a vertical-shell U-tube evaporator with integral moisture separating equipment. Figure 5.4-2 shows the steam generator, indicating several of its design features.

The design of the Model Delta-125 steam generator, except for the configuration of the channel head, is similar to an upgraded Model Delta-75 steam generator. The Delta-75 steam generator has been placed in operation as a replacement steam generator.

Steam generator design features are described in the following paragraphs.

On the primary side, the reactor coolant flow enters the primary chamber via the hot leg nozzle. The lower portion of the primary chamber is elliptical and merges into a cylindrical portion, which mates to the tubesheet. This arrangement provides enhanced access to all tubes, including those at the periphery of the bundle, with robotics equipment. This feature enhances the ability to inspect, replace and repair portions of the AP1000 unit compared to the more spherical primary chamber of earlier designs. The head is divided into inlet and outlet chambers by a vertical divider plate extending from the apex of the head to the tubesheet.

The reactor coolant flow enters the inverted U-tubes, transferring heat to the secondary side during its traverse, and returns to the cold leg side of the primary chamber. The flow exits the steam generator via two cold leg nozzles to which the reactor coolant pumps are directly attached. A high-integrity, nickel-chromium-iron (Alloy 690) weld is made to the nickel-chromium-iron alloy buttered ends of these nozzles.

A passive residual heat removal (PRHR) nozzle attaches to the bottom of the channel head of the loop 1 steam generator on the cold leg portion of the head. This nozzle provides recirculated flow from the passive residual heat removal heat exchanger to cool the primary side under emergency conditions. A separate nozzle on one of the steam generator channel heads is connected to a line from the chemical and volume control system. The nozzle provides for purification flow and makeup flow from the chemical and volume control system to the reactor coolant system.

The AP1000 steam generator channel head has provisions to drain the head. To minimize deposits of radioactive corrosion products on the channel head surfaces and to enhance the decontamination of these surfaces, the channel head cladding is machined or electropolished for a smooth surface. The primary manways provide enhanced primary chamber access compared to previous model steam generators.

Should steam generator replacement using a channel head cut be required, the arrangement of the AP1000 steam generator channel head facilitates steam generator replacement in two ways. It is completely unobstructed around its circumference for mounting cutting equipment. And is long enough to permit post-weld heat treatment with minimal effect of tubesheet acting as a heat sink.

The tubes are fabricated of nickel-chromium-iron Alloy 690. The tubes undergo thermal treatment following tube-forming operations. The tubes are tack-expanded, welded, and expanded over the full depth of the tubesheet. Full depth expansion was selected because of its capability to minimize secondary water access to the tube-to-tube-sheet crevice. The method by which the tubes

NRC 053

are expanded into the tubesheet is determined based on consideration of the residual stresses and the resultant susceptibility of the tube to degradation. Residual stresses smaller than from other expansion methods result from this process and are minimized by (and the expanded tube's susceptibility to degradation) are limited, in part, through tight control of the pre-expansion clearance between the tube and tubesheet hole.

Support of the tubes is provided by ferritic stainless steel tube support plates. The holes in the tube support plates are broached with a hole geometry to promote flow along the tube and to provide an appropriate interface between the tube support plate and the tube. Figure 5.4-3 shows the support plate hole geometry. Anti-vibration bars installed in the U-bend portion of the tube bundle minimize the potential for excessive vibration.

Steam is generated on the shell side, flows upward, and exits through the outlet nozzle at the top of the vessel. Feedwater enters the steam generator at an elevation above the top of the U-tubes through a feedwater nozzle. The feedwater enters a feeding via a welded thermal sleeve connection and leaves it through nozzles attached to the top of the feeding. The nozzles are fabricated of an alloy that is very resistant to erosion and corrosion with the expected secondary water chemistry and flow rate through the nozzles. After exiting the nozzles, the feedwater flow mixes with saturated water removed by the moisture separators. The flow then enters the downcomer annulus between the wrapper and the shell.

Fluid instabilities and water hammer phenomena are important considerations in the design of steam generators. Water level instabilities can occur from density wave instabilities which could affect steam generator performance. Density wave instability is avoided in the AP1000 steam generator by including appropriate pressure losses in the downcomer and the risers that lead to negative damping factors.

Steam generator bubble collapse water hammer has occurred in certain early pressurized water reactor steam generator designs having feedrings equipped with bottom discharge holes. Prevention and mitigation of feedline-related water hammer has been accomplished through an improved design and operation of the feedwater delivery system. The AP1000 steam generator and feedwater system incorporate features designed to eliminate the conditions linked to the occurrence of steam generator water hammer. The steam generator features include introducing feedwater into the steam generator at an elevation above the top of the tube bundle and below the normal water level by a top discharge feeding. The top discharge of the feeding helps to reduce the potential for vapor formation in the feeding. This minimizes the potential for conditions that can result in water hammer in the feedwater piping. The feedwater system features (subsection 10.4.7 discusses in more detail) designed to prevent and mitigate water hammer include a short, horizontal or downward sloping feedwater pipe at steam generator inlet.

These features minimize the potential for trapping pockets of steam which could lead to water hammer events.

Stratification and striping are reduced by an upturning elbow inside the steam generator which raises the feeding relative to the feedwater nozzle. The elevated feeding reduces the potential for stratified flow by allowing the cooler, more dense feedwater to fill the nozzle/elbow arrangement before rising into the feeding.

In certain design basis events described in Chapter 15, the pressurizer safety valves are predicted to operate with very low flow rates. For these events, the reactor coolant system pressure is slowly increasing as a result of the mismatch between the decay heat removal rate from the passive residual heat removal heat exchanger and the core decay heat. This slow pressurization of the reactor coolant system results in a small amount of steam flow through the safety valves. Under these conditions, the safety valves do not fully open and would not experience significant cycling. Operation of the safety valves under these conditions could result in small leakage from the valve (much less than the capacity of the normal makeup system), but does not impair the valve overpressure protection capability.

The relief valve on the normal residual heat removal system has an accumulation of 10 percent of the set pressure. The set pressure is the lower of the pressure based on the design pressure of the residual heat removal system and the pressure based on the reactor vessel low temperature pressure limit. The pressure limit determined based on the design pressure includes the effect of the pressure rise across the pump. The set pressure in Table 5.4-17 is based on the reactor vessel low temperature pressure limit. The lowest permissible set pressure is based on the required net positive suction head for the reactor coolant pump.

5.4.9.4 Tests and Inspections

The safety and relief valves are the subject of a variety of tests to validate the design and to verify pressure boundary and functional integrity. For valves that are required to function during a Service Level D condition, static deflection tests are performed to demonstrate operability. Section 3.10 describes these tests.

Safety valves similar to those connected to the pressurizer have been tested within the Electric Power Research Institute (EPRI) safety and relief valve test program. Capacity data for the specific AP1000 safety valve size has been correlated with the EPRI test data to demonstrate that the valve is adequate for steam flow and water flow, even though water flow is not anticipated through the pressurizer safety valves. The completion of this program addresses the requirements of 10 CFR 50.34(f)(2)(x) as related to reactor coolant system relief and safety valve testing. The normal residual heat removal system relief valve is designed for water relief and is not a reactor coolant system pressure relief device since it has a set pressure less than reactor coolant system design pressure. Therefore, the valve selected for the normal residual heat removal system relief valve is independent from the Electric Power Research Institute safety and relief valve test program.

Reactor coolant system pressure relief devices are subjected to preservice and inservice hydrostatic tests, seat leakage tests, operational tests, and inspections, as required. The preservice and inservice inspection and testing programs for valves are described in subsections 3.9.6 and 5.2.45.4.8 and Section 6.6. The test program for the safety valves complies with the requirements of ANSI/ASME OM, Part 1.

The pressure boundary portion of the valves are required to be inservice inspected according to the rules of Section XI of the ASME Code. There are no full-penetration welds within the valve body walls. Valves are accessible for disassembly and internal visual inspection.

Chapter 6

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6.1.1.3 Specifications for Nonpressure-Retaining Materials

Materials for nonpressure-retaining portions of engineered safety features in contact with borated water or other fluids may be procured under ASTM designation. The principle examples of these items are the in-containment refueling water storage tank liner and the passive containment cooling system storage tank liner.

NRC 174

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The walls of the in-containment refueling water storage tank ~~are may be~~ fabricated of ASTM/ASME A240/SA-240 ~~Designation 532101~~. This is a chromium, ~~manganese molybdenum~~, and nitrogen-strengthened ~~duplex austenitic~~ stainless steel with higher ultimate tensile and yield strengths than type 304 and 316 stainless steel. This material can be welded using a matching Duplex 2101 (2304 or 2209) filler metal by any of the commonly used stainless steel welding methods, including shielded metal arc welding (SMAW), gas tungsten arc welding TIG (GTAW), gas metal arc welding MIG (GMAW), flux-cored arc welding (FCW), plasma arc welding (PAW), submerged arc welding (SAW), either the shielded metal arc welding or gas tungsten arc welding methods. This material is used for applications where the higher strength allows reductions in weight and material costs. The material has a resistance to intergranular stress corrosion cracking similar to or better than type 304 and 304L stainless steel.

6.1.1.4 Material Compatibility with Reactor Coolant System Coolant and Engineered Safety Features Fluids

Engineered safety features components materials are manufactured primarily of stainless steel or other corrosion-resistant material. Protective coatings are applied on carbon steel structures and equipment located inside the containment, as discussed in subsection 6.1.2.

Austenitic stainless steel plate conforms to ASME SA-240. Austenitic stainless steel is confined to those areas or components which are not subject to post-weld heat treatment. Carbon steel forgings conform to ASME SA-350. Austenitic stainless steel forgings conform to ASME SA-182. Nickel-chromium-iron alloy pipe conforms to ASME SB-167. Carbon steel castings conform to ASME SA-352. Austenitic stainless steel castings conform to ASME SA-351.

Hardfacing material in contact with reactor coolant is a qualified low- or zero-cobalt alloy, equivalent to Stellite-6. The use of cobalt-base alloys is minimized. Low- or zero-cobalt alloys used for hardfacing or other applications where cobalt-base alloys have been previously used are qualified by wear and corrosion tests. The corrosion tests qualify the corrosion resistance of the alloy in reactor coolant. Cobalt-free, wear-resistant alloys considered for this application include those developed and qualified in nuclear industry programs.

In post-accident situations where the containment is flooded with water containing boric acid, pH adjustment is provided by the release of trisodium phosphate into the water. The trisodium phosphate is held in baskets located in the floodable volume that includes the steam generator compartments and contains the reactor coolant loop. The addition of trisodium phosphate to the solution is sufficient to raise the pH of the fluid to above 7.0. This pH is consistent with the guidance of NRC Branch Technical Position MTEB-6.1 for the protection of austenitic stainless steel from chloride-induced stress corrosion cracking. Section 6.3 describes the design of the trisodium phosphate baskets.

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assumed to occur between the 107-foot elevation and the ~~163~~¹⁷¹-foot elevation of the pressurizer compartment or the 118-foot to 135-foot elevations of the pressurizer spray valve room.

The analysis for the steam generator vertical access area is performed assuming a double-ended guillotine break in a 3-inch inside diameter reactor coolant system cold-leg pipe. This break envelopes the branch lines that could be postulated to rupture in this area. The break is assumed to occur between the 83-foot elevation and the 103-foot elevation of the steam generator vertical access area compartment.

The analysis for the maintenance floor and operating deck compartments are performed assuming a one square foot rupture of a main steam line pipe. This break envelopes the branch lines that could be postulated to rupture in these areas. The break is assumed to occur between the 107-foot elevation and the 135-foot elevation of the maintenance floor compartment and between the 135-foot elevation and the 282-foot elevation of the operating deck region.

The analysis for the main chemical and volume control system room is performed assuming a single-ended guillotine break in a 3-inch diameter reactor coolant system cold-leg pipe. This break envelopes the branch lines that could be postulated to rupture in this area. The break is assumed to occur between the 91-foot elevation and the 105-foot elevation of the chemical and volume control system room compartment.

The analysis for the pipe tunnel in the chemical and volume control system room is performed assuming a double-ended guillotine break in a 4-inch diameter steam generator blowdown line. This double-ended break envelopes the branch lines that could be postulated to rupture in this area. The break is assumed to occur between the 98.5-foot elevation and the 105-foot elevation of the chemical and volume control system room pipe tunnel.

An evaluation of rooms which could have either a main or startup feedwater line break was performed. No significant pressurization of the regions is predicted to occur because the postulated breaks are located in regions which are open to the large free volume of containment. For these regions, the main or startup feedwater line breaks are not limiting.

6.2.1.2.3.3 Node Selection

The nodalization for the sub-compartments is analyzed in sufficient detail such that nodal boundaries are at the location of flow obstructions or geometrical changes within the subcompartment. These discontinuities create pressure differentials between adjoining nodes. There are no significant discontinuities within each node, and hence the pressure gradient is negligible within any node.

6.2.1.2.3.4 Vent Flowpath Flow Conditions

The flow characteristics for each of the subcompartments are such that, at no time during the transient does critical flow exist through vent paths.

6.2.1.3 Mass and Energy Release Analyses for Postulated Pipe Ruptures

Mass and Energy releases are documented in this section for two different types of transients.

closing permits isolation valve stroke testing without actuation of the passive containment cooling system.

- Verify water flow delivery and containment water coverage, consistent with the accident analysis.
- Verify visually that the path for containment cooling air flow is not obstructed by debris or foreign objects.
- Test frequency is consistent with the ~~plant technical specifications (subsection 16.3.6)~~ and inservice testing program (subsection 3.9.6).

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6.2.2.5 Instrumentation Requirements

The status of the passive containment cooling system is displayed in the main control room. The operator is alerted to problems with the operation of the equipment within this system during both normal and post-accident conditions.

Normal operation of the passive containment cooling system is demonstrated by monitoring the recirculation pump discharge pressure, flow rate, water storage tank level and temperature, and valve room temperature. Post-accident operation of the passive containment cooling system is demonstrated by monitoring the passive containment cooling water storage tank level, passive containment cooling system cooling water flow rate, containment pressure, and external cooling air discharge temperature.

The information on the activation signal-generating equipment is found in Chapter 7.

The protection and safety monitoring system providing system actuation is discussed in Chapter 7.

6.2.3 Containment Isolation System

The major function of the containment isolation system of the AP1000 is to provide containment isolation to allow the normal or emergency passage of fluids through the containment boundary while preserving the integrity of the containment boundary, if required. This prevents or limits the escape of fission products that may result from postulated accidents. Containment isolation provisions are designed so that fluid lines which penetrate the primary containment boundary are isolated in the event of an accident. This minimizes the release of radioactivity to the environment.

The containment isolation system consists of the piping, valves, and actuators that isolate the containment. The design of the containment isolation system satisfies the requirements of NUREG 0737, as described in the following paragraphs.

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Table 6.2.3-1 (Sheet 1 of 4)											
CONTAINMENT MECHANICAL PENETRATIONS AND ISOLATION VALVES											
System	Containment Penetration			Isolation Device					Test		
	Line	Flow	Closed Sys IRC	Valve/Hatch Identification	DCD Subsection	Position N-S-A	Signal	Closure Times	Type ¹ & Note	Medium	Direction
CAS	Service air in	In	No	CAS-PL-V204 CAS-PL-V205	9.3.1	C-O-C C-O-C	None None	N/A N/A	C,5	Air	Forward
	Instrument air in	In	No	CAS-PL-V014 CAS-PL-V015	9.3.1	O-O-C O-O-C	T None	std. N/A	C,5	Air	Forward
CCS	IRC loads in	In	No	CCS-PL-V200 CCS-PL-V201	9.2.2	O-O-C O-O-C	S None	std. N/A	C,5	Air	Forward
	IRC loads out	Out	No	CCS-PL-V208 CCS-PL-V207	9.2.2	O-O-C O-O-C	SS S	std. std.	C,5	Air	Forward
CVS	Spent resin flush out	Out	No	CVS-PL-V041 CVS-PL-V040 CVS-PL-V042	9.3.6	C-C-C C-C-C C-C-C	None None None	N/A N/A N/A	C	Air	Forward
	Letdown	Out	No	CVS-PL-V047 CVS-PL-V045	9.3.6	C-O-C C-O-C	T T	std. std.	C	Air	Forward
	Charging	In	No	CVS-PL-V090 CVS-PL-V091 CVS-PL-V100	9.3.6	C-O-C C-O-C C-C-C	HR,PL2, S+PL1, SGL HR,PL2, S+PL1, SGL None	std. std. N/A	C	Air	Forward
	H2 injection to RCS	In	No	CVS-PL-V092 CVS-PL-V094	9.3.6	O-C-C C-C-C	T None	std. N/A	C	Air	Forward
DWS	Demin. water supply	In	No	DWS-PL-V244 DWS-PL-V245	9.2.4	C-O-C C-O-C	None None	N/A N/A	C,5	Air	Forward
FHS	Fuel transfer	N/A	No	FHS-FT-01	6.2.5	C-O-C	None	N/A	B	Air	Forward
FPS	Fire protection standpipe sys.	In	No	FPS-PL-V050 FPS-PL-V052	9.5.1	C-C-C C-C-C	None None	N/A N/A	C,5	Air	Forward
PSS	RCS/PSX/CVS samples out	Out	No	PSS-PL-V011 PSS-PL-V010A,B	9.3.3	C-C-C C-C-C	T T	std. std.	C	Air	Forward
	Cont. air samples out	Out	No	PSS-PL-V046 PSS-PL-V008	9.3.3	O-C-C O-C-C	T T	std. std.	C	Air	Forward
	RCS/Cont. air sample return	In	No	PSS-PL-V023 PSS-PL-V024	9.3.3	O-C-C O-C-C	T None	std. N/A	C	Air	Forward

inadvertently closed. The technical specifications specify surveillances to show that these valves are open. These valves also receive a safeguards actuation signal to confirm that they are open in the event of an accident. As a result of the power lock out, the redundant position indication and alarms and the technical specifications the valve controls are nonsafety-related.

6.3.7.6.2.3 Passive Residual Heat Removal Heat Exchanger Inlet Motor-Operated Valve Control

The motor-operated valve in the passive residual heat removal heat exchanger inlet line is normally open during normal plant operation. Power to this valve is locked out. Redundant valve position indications and alarms are provided to alert the operator if the valve is open. This valve also receives an actuation signal to confirm that it is open in the event of an accident.

6.3.7.7 Automatic Depressurization System Actuation at 24 Hours

A timer is used to automatically actuate the automatic depressurization system if offsite and onsite power are lost for about 24 hours. This prevents discharging the Class 1E dc power sources such that they are no longer able to operate the automatic depressurization system valves. If power becomes available to the dc batteries and they are no longer discharging prior to activation of the timer, then the automatic depressurization system actuation would be delayed. If the plant does not need actuation of the automatic depressurization system based on having stable pressurizer level, full core makeup tanks, and high and stable in-containment refueling water storage tank levels, the operators are directed to de-energize all loads on the 24-hour batteries. This action will block actuation of the automatic depressurization system and allow for its actuation later should the plant conditions unexpectedly degrade.

6.3.8 Combined License Information

6.3.8.1 Containment Cleanliness Program

The Combined License applicants referencing the AP1000 will address preparation of a program to limit the amount of debris that might be left in the containment following refueling and maintenance outages. The cleanliness program will limit the storage of outage materials (such as temporary scaffolding and tools) inside containment during power operation consistent with COL item 6.3.8.2. The cleanliness program will be consistent with the containment cleanliness program used in the evaluation discussed in subsection 6.3.8.2.

6.3.8.2 Verification of Water Sources for Long-Term Recirculation Cooling Following a LOCA

The Combined License information requested in this subsection has been fully addressed in APP-GW-GLR-079 (Reference 3), and the applicable changes are incorporated into the DCD. No additional work is required by the Combined License applicant to address the aspects of the Combined License information requested in this subsection.

The completed evaluation documented in APP-GW-GLR-079 (Reference 3) is consistent with Regulatory Guide 1.82 Revision 3 and demonstrates that adequate long-term core cooling is available considering debris resulting from a LOCA and debris that might exist in containment prior to a LOCA.

- Pressure Relief Isolation Valve

To limit the pressure increase within the main control room, isolation valves are provided, one in each of redundant flowpaths, which open on a time delay after receipt of an emergency habitability system actuation signal. The valves provide a leak tight seal to protect the integrity of the main control room pressure boundary during normal operation, and are normally closed to prevent interference with the operation of the nonradioactive ventilation system.

- Main Air Flowpath Isolation Valve

The main air flowpath contains a normally open, manually operated valve located within the MCR pressure boundary, upstream of the remotely operated air delivery main isolation valves. The valve is provided as a means of isolating and preserving the air storage tank's contents in the event of a pressure regulating valve malfunction.

- Air Delivery Alternate Isolation Valve

The alternate air delivery flowpath contains a normally closed, manually operated valve, located within the MCR pressure boundary. The valve is provided as a means of manually activating the alternate air delivery flowpath in the event the main air delivery flowpath is inoperable.

- Pressure Relief Damper

Pressure relief dampers are located downstream of the butterfly isolation valves, and are set to open on a differential pressure of at least 1/8-inch water gauge with respect to the surrounding areas. The differential pressure between the control room and the surrounding area location is monitored to ensure that a positive pressure is maintained in the control room with respect to its surroundings.

The pressure relief dampers discharge ~~through~~into the MCR vestibule in order to reduce the amount of radioactivity that can be transported into the MCR when operators enter. Two vestibule discharge openings provide a purge flow path from the vestibule to the corridor, with the discharge closer to the door into the MCR to improve the vestibule purge effectiveness. Two vestibule discharge openings, approximately four inches in diameter and located near the vestibule door into the corridor, provide a purge flow path from the vestibule to the corridor.

- Control Room Access Doors

Two sets of doors, with a vestibule between that acts as an airlock, are provided at the access to the main control room.

- Breathing Apparatus

NRC 068

NRC 148 | **6.6 Inservice Inspection of Class 2, ~~and 3,~~ and MC Components**

6.6.1 Components Subject to Examination

NRC 148

Preservice and inservice inspections of Quality Group B and C pressure retaining components (ASME Code, Section III Class 2 and 3 components) such as vessels, piping, pumps, valves, bolting, and supports as identified in subsection 3.2.2 are performed in accordance with the ASME Code, Section XI, as required by 10 CFR 50.55a(g). This includes the ASME Code Section XI Mandatory Appendices. Preservice and inservice inspections of Quality Group B components that are ASME Class MC (metallic containment) pressure-retaining components and integral attachments are performed in accordance with the ASME Code, Section XI, as required by 10 CFR 50.55a. Refer to subsection 3.8.2, “Steel Containment” for design details, including accessibility of primary containment.

The responsibility for preparation of the pre-service inspection program (nondestructive examination) is described in subsection 6.6.9. The responsibility for the inservice inspection program that is required prior to commercial operation is described in subsection 6.6.9. These programs will address applicable inservice inspection provisions of 10 CFR 50.55a(g). The pre-service program will provide details of areas subject to inspection, as well as the method and extent of pre-service inspection. The inservice inspection program will detail the areas subject to inspection and method, extent, and frequency of inspection.

6.6.2 Accessibility

NRC 148

ASME Code Class 2, ~~and 3,~~ and MC components are designed so that access is provided in the installed condition for visual, surface and volumetric examinations specified by the ASME Code. See subsection 5.2.1.1 for a discussion of the baseline ASME Code edition and Addenda. Design provisions, in accordance with Section XI, IWA-1500, are formally implemented in the Class 2, ~~and 3,~~ and MC component design processes.

NRC 148

The goal of designing for inspectability is to provide for the inspectability access and conformance of component design with available inspection equipment and techniques. Factors such as examination requirements, examination techniques, accessibility, component geometry and material selection are used in evaluating component designs. Examination requirements and examination techniques are defined by inservice inspection personnel. Inservice inspection review as part of the design process provides component designs that conform to inspection requirements and establishes recommendations for enhanced inspections.

Considerable experience has been drawn on in designing, locating, and supporting Quality Group B and C (ASME Class 2 and 3) pressure-retaining components to permit pre-service and inservice inspection required by Section XI of the ASME Code. Factors such as examination requirements, examination techniques, accessibility, component geometry, and material selections are used in establishing the designs. The inspection design goals are to eliminate uninspectable components, reduce occupational radiation exposure, reduce inspection times, allow state-of-the-art inspection systems, and enhance detection and the reliability of flaw characterization. There are no Quality Group B and C components which require inservice inspection during reactor operation.

Removable insulation is provided on piping systems requiring volumetric and surface inspection. Removable hangers and pipe whip restraints are provided, as necessary and practical, to facilitate inservice inspection. Working platforms are provided in areas requiring inspection and servicing of pumps and valves. Temporary or permanent platforms, scaffolding, and ladders are provided to facilitate access to piping welds. The components and welds requiring inservice inspection are designed to allow for the application of the required inservice inspection methods, that is, sufficient clearances for personnel and equipment, maximized examination surface distances, two-sided access, favorable materials, weld joint simplicity, elimination of geometrical interferences, and proper weld surface preparation.

Many of the ASME Code, Section III, Class 2 and 3 components are included in modules which are fabricated offsite and shipped to the site, as described in subsection 3.9.1.5. The modules are designed and engineered to provide access for in-service inspection and maintenance activities. The attention to detail that is engineered into the modules prior to construction improves the accessibility for inspection and maintenance.

NRC 148

Relief from Section XI requirements will not be required for ASME Code, Section III, Class 2, ~~and 3, and MC~~ pressure-retaining components in the AP1000 plant for the baseline design certification code. Future unanticipated changes in the Section XI requirements could, however, necessitate relief requests. Relief from the inspection requirements of Section XI will be requested when full compliance is not practical according to the requirements of 10 CFR 50.55a. In such cases, specific information will be provided to identify the applicable ASME Code requirements, justification for the relief request, and the inspection method to be used as an alternative.

Space is provided to handle and store insulation, structural members, shielding, and other material related to the inspection. Suitable hoists and other handling equipment, lighting, and sources of power for inspection equipment are installed at appropriate locations.

6.6.3 Examination Techniques and Procedures

The visual, surface, and volumetric examination techniques and procedures are in accordance with the requirements of ASME Code, Section XI, subarticle IWA-2000. Code cases listed in Regulatory Guide 1.147 are applied as the need arises during the pre-service inspection. Code cases determined as necessary to accomplish pre-service inspection activities are used.

NRC 148

The liquid penetrant or magnetic particle methods are used for surface examinations. ~~Radiography, u~~ Ultrasonic, or eddy current methods (whether manual or remote) are used for volumetric examinations.

The report format for reportable indications and data compilation provide for comparison of data from subsequent examinations.

6.6.4 Inspection Intervals

NRC 148

Inspection intervals included in the inspection program are as defined in ~~subarticle~~ Subarticles IWA-2400, IWC-2400, IWD-2400, IWE-2400, and IWF-2400 of the ASME Code, Section XI. The periods within each inspection interval may be extended by as much as one year to permit inspections to be concurrent with plant outages. It is intended that inservice examinations be

performed during normal plant outages, such as refueling shutdown or maintenance shutdowns occurring during the inspection interval.

6.6.5 Examination Categories and Requirements

NRC 148

Examination categories and examination requirements (examination methods, acceptance criteria, extent of examination, and frequency of examination) for Class 2 components are in accordance with Subsection IWC and ~~Table IWC-2500~~ of the ASME Code, Section XI. Similar information for Class 3 components are in conformance with Subsection IWD Article IWD-2000 and ~~Table IWD-2500-1~~ for component supports examination categories and examination requirements are in conformance with Subsection IWF and Table IWF-2500-1; and for Class MC components examination categories and examination requirements are in conformance with Subsection IWE and Table IWE-2500-1 of ASME Code, Section XI.

NRC 148

The pre-service examination of Class 2 components is according to the requirements of Subarticle IWC-2200. The pre-service examination of Class MC components is in accordance with the requirements of Subarticle IWE-2200. The pre-service examination requirements for component supports is in accordance with the requirements of Subarticle IWF-2200. The pre-service examination of Class 3 components is according to the requirements of Subarticle IWD-2200~~400~~. ~~Inservice test requirements for component supports comply with ASME Code, Section XI, Article IWF-5000.~~

As provided in ASME Section XI, IWC-1220, IWD-1220, and IWE-1220, certain portions of Class 2, 3, and MC systems are exempt from the volumetric, surface and visual examination requirements of IWC-2500, IWD-2500, and IWE-2500. Supports associated with Class 2, 3 and MC components are also exempt in accordance with the requirements of IWF-1230.

6.6.6 Evaluation of Examination Results

NRC 092

NRC 148

Examination results are evaluated per the acceptance standards found in IWA-3000, IWC-3000, ~~and IWD-3000, IWE 3000, and IWF-3000~~ of the ASME Code, Section XI. Repair and replacement procedures are in accordance with ASME Code, Section XI, Article IWA-4000. ~~If the guidelines of IWA-4000 are inappropriate for the components, then the guidelines of ASME Code Section XI, IWC-4000 and IWD-4000 apply.~~

6.6.7 System Pressure Tests

NRC 148

System pressure tests comply with IWA-5000, IWC-5000, ~~and IWD-5000,~~ and IWE-5000 of the ASME Code, Section XI, for Class 2, ~~and 3,~~ and MC components. Pressure testing of Class MC components is performed per the 10 CFR 50 Appendix J "Containment Leak Rate Testing" Program.

6.6.8 Augmented Inservice Inspection to Protect against Postulated Piping Failures

An augmented inspection program is developed for high-energy fluid systems piping between containment isolation valves. Such a program is also developed where no isolation valve is used inside containment between the first rigid pipe connection to the containment penetration or the

Chapter 7

Protection and Safety Monitoring System – The aggregate of electrical and mechanical equipment which senses generating station conditions and generates the signals to actuate reactor trip and ESF, and which provides the equipment necessary to monitor plant safety-related functions during and following designated events.

Protective Function – Any one of the functions necessary to mitigate the consequences of a design basis event. Protective functions are initiated by the protection and safety monitoring system logic and will be accomplished by the trip and actuation subsystems. Examples of protective functions are reactor trip and engineered safety features (such as valve alignment and containment isolation).

Actuated Equipment – The assembly of prime movers and driven equipment used to accomplish a protective function (such as solenoids, shutdown rods, and valves).

Actuation Device – A component that directly controls the motive power for actuated equipment (such as circuit breakers, relays, and pilot valves).

Division – One of the four redundant segments of the safety system. A division includes its associated sensors, field wiring, cabinets, and electronics used to generate one of the redundant actuation signals for a protective function. It also includes the power source and actuation signals.

Channel – One of the several separate and redundant measurements of a single variable used by the protection and safety monitoring system in generating the signal to initiate a protective function. A channel can lose its identity when it is combined with other inputs in a division.

Degree of Redundancy – The number of redundant channels monitoring a single variable, or the number of redundant divisions which can initiate a given protective function or accomplish a given protective function. Redundancy is used to maintain protection capability when the safety-related system is degraded by a single random failure.

System-Level Actuation – Actuation of a sufficient number of actuation devices to effect a protective function.

Component-Level Actuation – Actuation of a single actuation device (component).

7.1.1 The AP1000 Instrumentation and Control Architecture

Figure 7.1-1 illustrates the instrumentation and control architecture for the AP1000. The figure shows two major sections separated by the real-time data network. Figure 7.1-1 depicts the real-time data highway as a single network. To meet cyber security concerns, the real-time data highway will be separated into security levels as described in Reference 22.

The lower portion of the figure includes the plant protection, control, and monitoring functions. At the left-right is the protection and safety monitoring system. It performs the reactor trip functions, the engineered safety features (ESF) actuation functions, and the Qualified Data Processing (QDPS) functions. The I&C equipment performing reactor trip and ESF actuation functions, their related sensors, and the reactor trip switchgear are, for the most part, four-way redundant. This redundancy permits the use of bypass logic so that a division or individual channel out of service

*[WCAP-16096-NP-A (Reference 9), NABU-DP-00014-GEN (Reference 20), and the NRC-approved Westinghouse Quality Management System (Reference 21) describe design processes that will be used for AP1000.]**

7.1.2.14.2 Commercial Dedication

[WCAP-16097-P-A (Reference 8) provides for the use of commercial off-the-shelf hardware and software through a commercial dedication process.]* Control of the hardware and software during the operational and maintenance phase is the responsibility of the Combined License applicant as described in subsection 13.5.1.

NRC 114 |

7.1.3 Plant Control System

The plant control system is a nonsafety-related system that provides control and coordination of the plant during startup, ascent to power, power operation, and shutdown conditions. The plant control system integrates the automatic and manual control of the reactor, reactor coolant, and various reactor support processes for required normal and off-normal conditions. The plant control system also provides control of the nonsafety-related decay heat removal systems during shutdown. The plant control system accomplishes these functions through use of the following:

- Rod control
- Pressurizer pressure and level control
- Steam generator water level control
- Steam dump (turbine bypass) control
- Rapid power reduction

The plant control system provides automatic regulation of reactor and other key system parameters in response to changes in operating limits (load changes). The plant control system acts to maximize margins to plant safety limits and maximize the plant transient performance. The plant control system also provides the capability for manual control of plant systems and equipment. Redundant control logic is used in some applications to increase single-failure tolerance.

The plant control system includes the equipment from the process sensor input circuitry through to the modulating and nonmodulating control outputs as well as the digital signals to other plant systems. Modulating control devices include valve positioners, pump speed controllers, and the control rod equipment. Nonmodulating devices include motor starters for motor-operated valves and pumps, breakers for heaters, and solenoids for actuation of air-operated valves. The plant control system cabinets contain the process sensor inputs and the modulating and nonmodulating outputs. The plant control system also includes equipment to monitor and control the control rods.

The functions of the plant control system are performed by system assemblies including:

- Distributed controllers
- Signal selector algorithms
- Operator controls and indication
- Real-time data network

*NRC Staff approval is required prior to implementing a change in this information; see DCD Introduction Section 3.5.

- Rod control system
- Rod position indication
- Rod drive motor-generator sets

Figure 7.1-10 provides an illustration of the plant control system.

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7.1.3.1 Distributed Controllers

Each distributed controller processes inputs, performs system-level and component-level control calculations, provides capability for an operator interface to the controlled components, transmits control signals to discrete, modulating, and networked interfaced control components, and provides plant status and plant parameter information to the real-time data network.

The distributed controllers receive process inputs and implement the system-level logic and control algorithms appropriate for the plant operating mode. The distributed controllers receive process inputs from, and transmit process control outputs to, the actuated components. The distributed controller also transmits and receives process signals via the real-time data network. The real-time data network also provides for two-way communication between the distributed controllers and between the distributed controllers and the main control room and remote shutdown workstation.

Control functions are distributed across multiple distributed controllers so that single failures within a controller do not degrade the performance of control functions performed by other controllers. The major control functions which are implemented in different distributed controllers include reactor power control, feedwater control, pressurizer control, and turbine control.

7.1.3.2 Signal Selector Algorithms

Signal selector algorithms provide the plant control system with the ability to obtain inputs from the protection and safety monitoring system. The signal selector algorithms select those protection system signals that represent the actual status of the plant and reject erroneous signals. Therefore, the control system does not cause an unsafe control action to occur even if one of four redundant protection channels is degraded by random failure simultaneous with another of the four channels bypassed for test or maintenance.

Each signal selector algorithm receives data from each of the redundant divisions of the protection and safety monitoring system. The data is received from each division through an isolation device.

The signal selector algorithms provide validated process values to the plant control system. They also provide the validation status, the average of the valid process values, the number of valid process values, an alarm (if one process value has been rejected), and another alarm (if two process values have been rejected).

For the logic values received from the protection and safety monitoring system, such as permissives, two-out-of-four (2/4) voting is used to provide a valid logic value to the plant control system.

- [9. WCAP-16096-NP-A, Revision 01A, “Software Program Manual for Common Q Systems,” January 2004.]*
10. Deleted.
11. Deleted.
12. WCAP-15776, “Safety Criteria for the AP1000 Instrument and Control Systems,” April 2002.
13. WCAP-16097-P-A (Proprietary) and WCAP-16096-NP-A (Non-Proprietary), Appendix 4, “Common Qualified Platform Integrated Solution,” May 2003.
14. Deleted.
15. Deleted.
16. Deleted.
17. WCAP-16361-P (Proprietary) and WCAP-16361-NP (Non-Proprietary), “Westinghouse Setpoint Methodology for Protection Systems – AP1000,” May 2006.
18. APP-GW-GLR-017, AP1000 Standard Combined License Technical Report, “Resolution of Common Q NRC Items,” Westinghouse Electric Company LLC.
19. WCAP-16675-P (Proprietary) and WCAP-16675-NP (Non-Proprietary), “AP1000 Protection and Safety Monitoring System Architecture Technical Report,” February 2007.
20. ~~NABUNAMB~~-DP-00014-GEN, Rev. 1 (Proprietary), “Design Process for Common Q Safety Systems,” March 2006.
21. Westinghouse Electric Company Quality Management System (QMS), Rev. 5 (Non-Proprietary), October 1, 2002.
22. APP-GW-GLR-104, “AP1000 Cyber Security Implementation,” May 2007.

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*NRC Staff approval is required prior to implementing a change in this information; see DCD Introduction Section 3.5.

7.2 Reactor Trip

7.2.1 Description

Considerations, such as mechanical or hydraulic limitations on equipment or heat transfer requirements on the reactor core, define a safe operating region for the plant. Maneuvering of the plant within this safe operating region is permitted in response to normal power generation demands. The plant design provides margin to the safety limits so that an unsafe condition is not caused by the transients induced by normal operating changes. The plant control system attempts to keep the reactor operating away from any safety limit. Excursions toward a limit occur because of abnormal demands, malfunctions in the control system, or by severe transients induced by occurrence of a Condition II or III event, as discussed in Chapter 15. Hypothetical events (Condition IV) are analyzed with respect to plant safety limits. The safety system keeps the reactor within the safe region by shutting down the reactor whenever safety limits are approached. Reactor trip is a protective function performed by the protection and safety monitoring system when it anticipates an approach of a parameter to its safety limit. Reactor shutdown occurs when electrical power is removed from the rod drive mechanism coils, allowing the rods to fall by gravity into the reactor core.

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The equipment involved in reactor trip is shown in simplified block diagram form in Figure 7.1-2. Section 7.1 provides a description of the reactor trip equipment. The equipment involved is:

- Sensors and manual inputs
- Protection and safety monitoring system cabinets
- Reactor trip switchgear

The plant protection subsystems maintain surveillance of key process variables directly related to equipment mechanical limitations (such as pressure), and of variables which directly affect the heat transfer capability of the reactor (such as flow and temperature). Some limits, such as the overtemperature ΔT setpoint, are calculated in the protection and safety monitoring system from other parameters when direct measurement of the variable is not possible. Table 7.2-1 lists variables monitored for reactor trip.

Four redundant measurements, using four separate sensors, are made for each variable used for reactor trip. Analog signals are converted to digital form by analog-to-digital converters within the protection and safety monitoring system. Signal conditioning is applied to selected inputs following the conversion to digital form. Following necessary calculations and processing, the measurements are compared against the applicable setpoint for that variable. A partial trip signal for a parameter is generated if one channel's measurement exceeds its predetermined or calculated limit. Processing of variables for reactor trip is identical in each of the four redundant divisions of the protection system. Each division sends its partial trip status to each of the other three divisions over isolated multiplexed data links. Each division is capable of generating a reactor trip signal if two or more of the redundant channels of a single variable are in the partial trip state.

The reactor trip signal from each of the four divisions of the protection and safety monitoring system is sent to the corresponding reactor trip switchgear breakers.

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range values. ~~This trip function~~ may be manually blocked and the high voltage source range detector power supply de-energized when the intermediate range neutron flux is above the P-6 setpoint value. It is automatically blocked by the power range neutron flux interlock (P-10). The trip may be manually reset when neutron flux is between P-6 and P-10. The reset occurs automatically when the intermediate range flux decreases below P-6. The channels can be individually bypassed to permit channel testing during plant shutdown or prior to startup. This bypass action is indicated in the main control room.

Figure 7.2-1, sheet 3 shows the logic for this trip. This sheet also shows the development of permissive P-6 while P-10 is shown in Figure 7.2-1, sheet 4.

Intermediate Range High Neutron Flux Trip

Intermediate range high neutron flux trips the reactor when two of the four intermediate range channels exceed the trip setpoint. This trip, which provides protection during reactor startup, can be manually blocked if the power range channels are above approximately 10-percent power (P-10). The trip is automatically reset when the power range channels indicate less than 10-percent power. The intermediate range channels, including detectors, are separate from the power range channels. The intermediate range channels can be individually bypassed to permit channel testing during plant shutdown or prior to startup. This bypass action is indicated in the main control room.

Figure 7.2-1, sheet 3 shows the logic for this trip. The development of permissive P-10 is shown in Figure 7.2-1, sheet 4.

Power Range High Neutron Flux Trip (Low Setpoint)

Power range high neutron flux (low setpoint) trips the reactor when two of the four power range channels exceed the trip setpoint.

The trip, which provides protection during startup, can be manually blocked when the power range channels are above approximately 10-percent power (P-10). The trip is automatically reset when the power range channels indicate less than 10-percent power.

Figure 7.2-1, sheet 3 shows the logic for this trip. The development of permissive P-10 is shown on Figure 7.2-1, sheet 4.

7.2.1.1.2 Nuclear Overpower Trips

Power Range High Neutron Flux Trip (High Setpoint)

Power range high neutron flux (high setpoint) trips the plant when two of the four power range channels exceed the trip setpoint. It provides protection against excessive core power generation during normal operation and is always active. Figure 7.2-1, sheet 4 shows the logic for this trip.

Power Range High Positive Flux Rate Reactor Trip

This trip protects the reactor when a sudden abnormal increase in power occurs in two out of the four power range channels. It provides protection against ejection accidents of low worth rods

K_4 = A preset bias

$F_2(\Delta I)$ = A function of the neutron flux difference between upper and lower ionization chamber flux signals; to correct, if necessary, for an adverse axial flux shape.

Increases in ΔI beyond a predefined deadband results in a decrease in trip setpoint.

The source of temperature and neutron flux information is identical to that of the overtemperature ΔT trip, and the resultant ΔT setpoint is compared to the same measured ΔT power signal. Figure 7.2-1, sheet 5, shows the logic for this trip function.

Reactor Trip on Low Pressurizer Pressure

This trip protects against low pressure, which could lead to departure from nucleate boiling. The parameter sensed is reactor coolant pressure as measured in the pressurizer. This trip is automatically blocked when reactor power is below the P-10 permissive setpoint to allow control rod testing during cold, depressurized conditions. The trip is automatically reset when reactor power is above the P-10 setpoint.

Figure 7.2-1, sheet 5, shows the logic for this trip. The development of the P-10 permissive is shown in Figure 7.2-1, sheet 4.

Reactor Trip on Low Reactor Coolant Flow

This trip protects against departure from nucleate boiling in the event of low reactor coolant flow. Flow in each hot leg is measured at the hot leg elbow. The trip on low flow in the hot legs is automatically blocked when reactor power is below the P-10 permissive setpoint. This enhances reliability by preventing unnecessary reactor trips. The trip function is automatically reset when reactor power is above the P-10 setpoint.

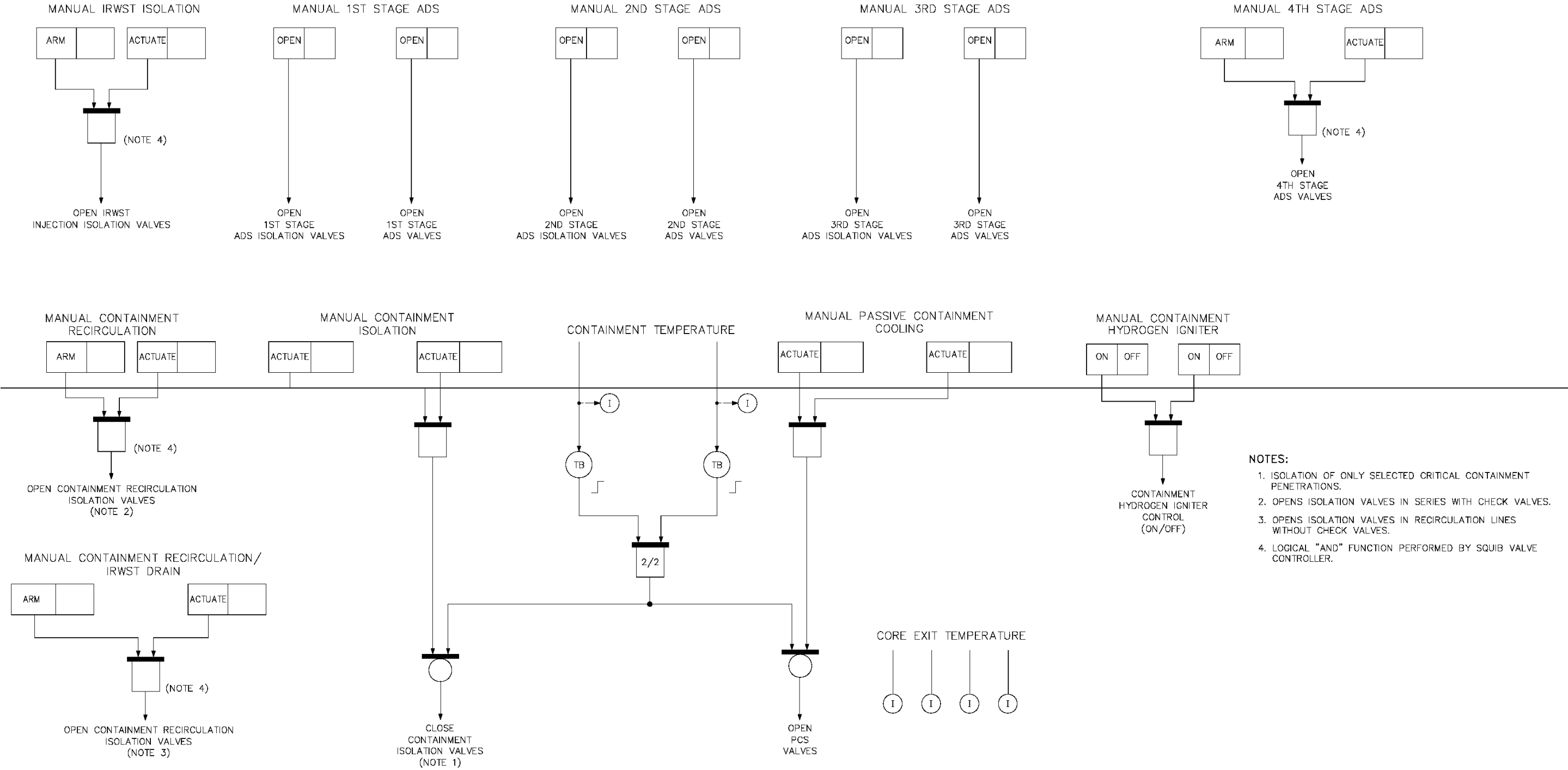
Figure 7.2-1, sheet 5 shows the logic for this trip. The development of permissives P-10 and P-8 are shown in Figure 7.2-1, sheet 4.

Reactor Trip on Reactor Coolant Pump Underspeed

This trip protects the reactor core from departure from nucleate boiling in the event of a loss of flow in more than one loop. This protection is provided by tripping the reactor when the speed on two out of the four reactor coolant pumps falls below the setpoint. Loss of flow in more than one loop could be caused by a voltage or frequency transient in the plant power supply such as would occur during a station blackout. It could be caused by inadvertent opening of more than one reactor coolant pump circuit breaker. There is one speed detector mounted on each reactor coolant pump. The trip is automatically blocked when reactor power is below the P-10 permissive setpoint to enhance reliability by preventing unnecessary reactor trips. The trip is automatically reset when reactor power is above the P-10 setpoint.

Figure 7.2-1, sheet 5, shows the logic for this trip. The development of P-10 is shown in Figure 7.2-1, sheet 4.

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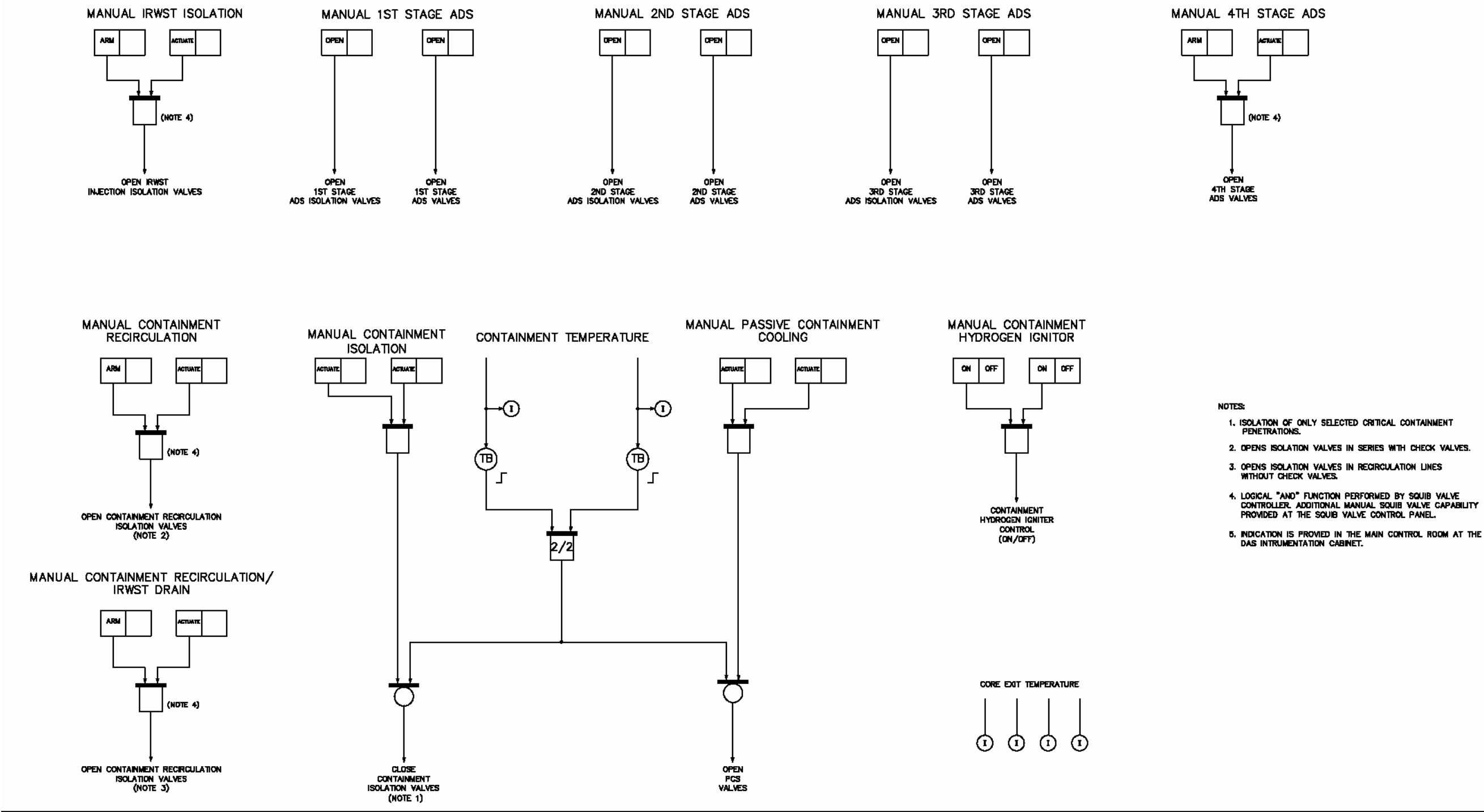


Figure 7.2-1 (Sheet 20 of 20)

Functional Diagram
Diverse Actuation System Logic, Manual Actuations

7.3 Engineered Safety Features

AP1000 provides instrumentation and controls to sense accident situations and initiate engineered safety features (ESF). The occurrence of a limiting fault, such as a loss of coolant accident or a secondary system break, requires a reactor trip plus actuation of one or more of the engineered safety features. This combination of events prevents or mitigates damage to the core and reactor coolant system components, and provides containment integrity.

7.3.1 Description

The protection and safety monitoring system is actuated when safety system setpoints are reached for selected plant parameters. The selected combination of process parameter setpoint violations is indicative of primary or secondary system boundary ruptures. Once the required logic combination is generated, the protection and safety monitoring system equipment sends the signals to actuate appropriate engineered safety features components. A block diagram of the protection and safety monitoring system is provided in Figure 7.1-2.

The following paragraphs summarize the major functional elements of the protection and safety monitoring system that are involved in generating an actuation signal to an engineered safety features component.

Four sensors normally monitor each variable used for an engineered safety feature actuation. (These sensors may monitor the same variable for a reactor trip function.) Analog measurements are converted to digital form by analog-to-digital converters within each of the four divisions of the protection and safety monitoring system. Following required signal conditioning or processing, the measurements are compared against the setpoints for the engineered safety feature to be generated. When the measurement exceeds the setpoint, the output of the comparison results in a channel partial trip condition. The partial trip information is transmitted to the ESF coincidence logic to form the signals that result in an engineered safety features actuation. The voting logic is performed twice within each division. Each voting logic element generates an actuation signal if the required coincidence of partial trips exists at its inputs.

The signals are combined within each division of ESF coincidence logic to generate a system-level signal. System-level manual actions are also processed by the logic in each division.

The system-level signals are then broken down to the individual actuation signals to actuate each component associated with a system-level engineered safety feature. For example, a single safeguards actuation signal must trip the reactor and the reactor coolant pumps, align core makeup tank and in-containment refueling water storage tank valves, and initiate containment isolation. The interposing logic accomplishes this function and also performs necessary interlocking so that components are properly aligned for safety. Component-level manual actions are also processed by this interposing logic. The power interface transforms the low level signals to voltages and currents commensurate with the actuation devices they operate. The actuation devices, in turn, control motive power to the final engineered safety feature component.

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7.3.1.2.16 Steam Dump Block

Signals to block steam dump (turbine bypass) are generated from either of the following conditions:

1. Low-2 reactor coolant system average temperature
2. Manual initiation

Condition 1 results from a coincidence of two of the four divisions of reactor loop average temperature (T_{avg}) below the Low-2 setpoint. This blocks the opening of the steam dump valves. This signal also becomes an input to the steam dump interlock selector switch for unblocking the steam dump valves used for plant cooldown.

Condition 2 consists of three sets of controls. The first set of two controls selects whether the steam dump system has its normal manual and automatic operating modes available or is turned off. The second set of two controls enables or disables the operations of the Stage 1 cooldown steam dump valves if the reactor coolant average temperature (T_{avg}) is below the Low-2 setpoint. The third set of two controls enables or disables the operation of the Stage 2 cooldown steam dump valves.

The functional logic relating to the steam dump block is illustrated in Figure 7.2-1, sheet 10.

7.3.1.2.17 Control Room Isolation and Air Supply Initiation

Signals to initiate isolation of the main control room, to initiate the air supply, and to open the control room pressure relief isolation valves are generated from either of the following conditions:

1. High-2 control room air supply radioactivity level
2. Loss of ac power sources (low Class 1E battery charger input voltage)
3. Manual initiation

Condition 1 is the occurrence one of two control room air supply radioactivity monitors detecting a radioactivity level above the High-2 setpoint.

Condition 2 results from the loss of all ac power sources. A preset time delay is provided to permit the restoration of ac power from the offsite sources or from the onsite diesel generators before initiation. The loss of all ac power is detected by undervoltage sensors that are connected to the input of each of the four Class 1E battery chargers. Two sensors are connected to each of the four battery charger inputs. The loss of ac power signal is based on the detection of an undervoltage condition by each of the two sensors connected to two of the four battery chargers. The two-out-of-four logic is based on an undervoltage to the battery chargers for divisions A or C coincident with an undervoltage to the battery chargers for divisions B or D.

Condition 3 consists of two momentary controls. Manual actuation of either of the two controls will result in control room isolation and air supply initiation.

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Table 7.3-1 (Sheet 6 of 9)

ENGINEERED SAFETY FEATURES ACTUATION SIGNALS

Actuation Signal	No. of Division/Controls	Actuation Logic	Permissives and Interlocks
f. High-3 pressurizer level	4	2/4-BYP ¹	Manual block permitted below P-19 Automatically unblocked above P-19
13. Block of Boron Dilution (Figure 7.2-1, Sheets 3 and 15)			
a. Flux doubling calculation	4	2/4-BYP ¹	Manual block permitted when critical or intentionally approaching criticality Automatically unblocked below P-6
b. Undervoltage to Class 1E battery chargers ⁽⁸⁾	2/charger	2/2 per charger and 2/4 chargers ⁵	None
c. Reactor trip (P-4)	1/division	2/4	None
14. Chemical Volume Control System Isolation (See Figure 7.2-1, Sheets 6 and 11)			
a. High-2 pressurizer water level	4	2/4-BYP ¹	Automatically unblocked above P-19 Manual block permitted below P-19
b. High-2 steam generator narrow range level	4/steam generator	2/4-BYP ¹ in either steam generator	None
c. Automatic or manual safeguards actuation signal coincident with	(See items 1a through 1e)		
High-1 pressurizer water level	4	2/4-BYP ¹	None
d. High-2 containment radioactivity	4	2/4-BYP ¹	None
e. Manual initiation	2 controls	1/2 controls	None
f. Flux doubling calculation	4	2/4-BYP ¹	Manual block permitted when critical or intentionally approaching criticality Automatically unblocked below P-6
15. Steam Dump Block (Figure 7.2-1, Sheet 10) ⁽⁸⁾			
a. Low reactor coolant temperature (Low-2 T _{avg})	2/loop	2/4-BYP ¹	None
b. Mode control	2 controls	1/division	None

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Table 7.3-1 (Sheet 8 of 9)

ENGINEERED SAFETY FEATURES ACTUATION SIGNALS

Actuation Signal	No. of Divisions/ Controls	Actuation Logic	Permissives and Interlocks
21. Open In-Containment Refueling Water Storage Tank (IRWST) Injection Line Valves (Figure 7.2-1, Sheets 12 and 16)			
a. Automatic reactor coolant system depressurization (fourth stage)	(See items 3d and 3e)		
b. Coincident loop 1 and loop 2 Low 2 hot leg level (after delay) be. Manual initiation	1 per loop 4 controls	2/22/4 controls ³	Manual unblock permitted below P-12 Automatically blocked above P-12 None
22. Open Containment Recirculation Valves In Series with Check Valves (Figure 7.2-1, Sheet 15 and 16)			
a. Extended undervoltage to Class 1E battery chargers ⁽⁸⁾	2/charger	1/2 per charger and 2/4 chargers	None
23. Open All Containment Recirculation Valves (Figure 7.2-1, Sheet 16)			
a. Automatic reactor coolant system depressurization (fourth stage coincident with)		(See items 3d through 3f)	
Low IRWST level (Low-3 setpoint)	4	2/4 BYP ¹	None
b. Manual initiation	4 controls	2/4 controls ³	None
24. Chemical and Volume Control System Letdown Isolation (Figure 7.2-1, Sheet 16)			
a. Low-1 hot leg level	1 per loop	1/2	Manual block permitted above P-12 Automatically unblocked below P-12
25. Pressurizer Heater Trip (Figure 7.2-1, Sheets 6 and 12)			
a. Core makeup tank injection	(See items 6a through 6e)		
b. High-3 pressurizer level	4	2/4 BYP ¹	Manual block permitted below P-19 Automatically unblocked above P-19

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Table 7.3-2 (Sheet 1 of 4)

INTERLOCKS FOR ENGINEERED SAFETY FEATURES ACTUATION SYSTEM		
Designation	Derivation	Function
P-3	Reactor trip breaker open	Permits manual reset of safeguards actuation signal to block automatic safeguards actuation
$\overline{\text{P-3}}$	Reactor trip breakers closed	Automatically resets the manual block of automatic safeguards actuation
P-4	Reactor trip initiated or reactor trip breakers open	(a) Isolates main feedwater if coincident with low reactor coolant temperature (b) Trips turbine (c) Blocks boron dilution
$\overline{\text{P-4}}$	No reactor trip initiated and reactor trip breakers closed	Removes demand for isolation of main feedwater, turbine trip and boron dilution block
P-6	Intermediate range neutron flux channels above setpoint	None. Allows manual block of flux doubling actuation of the boron dilution block.
$\overline{\text{P-6}}$	Intermediate range neutron flux channels below setpoint	None
P-11	Pressurizer pressure below setpoint	(a) Permits manual block of safeguards actuation on low pressurizer pressure, low compensated steam line pressure, or low reactor coolant inlet temperature (b) Permits manual block of steam line isolation on low reactor coolant inlet temperature (c) Permits manual block of steam line isolation and steam generator power-operated relief valve block valve closure on low compensated steam line pressure (d) Coincident with manual actions of (b) or (c), automatically unblocks steam line isolation on high negative steam line pressure rate (e) Permits manual block of main feedwater isolation on low reactor coolant temperature

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Table 7.3-2 (Sheet 3 of 4)

INTERLOCKS FOR ENGINEERED SAFETY FEATURES ACTUATION SYSTEM		
Designation	Derivation	Function
P-12	Pressurizer level below setpoint	<ul style="list-style-type: none"> (a) Permits manual block of core makeup tank actuation on low pressurizer level to allow mid-loop operation (b) Permits manual block of reactor coolant pump trip on low pressurizer level to allow mid-loop operation (c) Permits manual block of auxiliary spray and purification line isolation on low pressurizer level to allow mid-loop operation (d) Coincident with manual action of (a), automatically unblocks in-containment refueling water storage tank injection and fourth stage automatic depressurization system initiation on low hot leg level to provide protection during mid-loop operation. (e) Automatically unblocks chemical and volume control system letdown isolation on Low-1 hot leg level
<u>P-12</u>	Pressurizer level above setpoint	<ul style="list-style-type: none"> (a) Prevents manual block of core makeup tank actuation on low pressurizer level (b) Prevents manual block of reactor coolant pump trip on low pressurizer level (c) Prevents manual block of auxiliary spray and purification line isolation on low pressurizer level (d) Provides confirmatory open signal to the core makeup tank cold leg balance lines (e) Automatically blocks in-containment refueling water storage tank injection and fourth stage automatic depressurization system initiation on low hot leg level to reduce the probability of spurious actuation. (f) Permits manual block of chemical and volume control system letdown isolation on Low-1 hot leg level

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Table 7.3-4 (Sheet 2 of 2)

**ENGINEERED SAFETY FEATURES ACTUATION,
VARIABLES, LIMITS, RANGES, AND ACCURACIES
(NOMINAL)**

Variables	Range of Variables	Typical Accuracy ⁽¹⁾	Typical Response Time (Sec) ⁽²⁾
Pressurizer water level	0 to 100% of cylindrical portion of pressurizer	± 10% of span	1.0
Startup feedwater flow	0 to 1000 gpm	±7% of span	1.0
Neutron flux (flux doubling calculation)	1 to 10 ⁶ c/sec	± 30% of span	1.0 ⁽³⁾
Control room supply air radiation level	10 ⁻¹² to 10 ⁻² μ Ci/cc	± 50% of setpoint	20
Containment radioactivity	10 ⁰ to 10 ⁷ R/hr	± 50% of setpoint	20

Notes:

1. Measurement uncertainty typical of actual applications. Harsh environments allowance have been included where applicable.
2. Delay from the time that the process variable exceeds the setpoint until the time that an output is provided to the actuated device.
3. Response time depends on flux doubling calculation.

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Table 7.5-1 (Sheet 2 of 12)

POST-ACCIDENT MONITORING SYSTEM

Variable	Range/ Status	Type/ Category	Qualification		Number of Instruments Required	Power Supply	QDPS Indication (Note 2)	Remarks
			Environmental	Seismic				
Core exit temperature	200- 2300°F	B1, C1, F2	Harsh	Yes	3/quadrant	1E	Yes	
PRHR HX inlet temperature	50- 650°F	D3	None	None	1	Non-1E	No	Primary indication is RCS T _H
PRHR HX outlet temperature	50- 500°F	B1, D2	Harsh	Yes	1	1E	Yes	Diverse variable to PRHR flow
PRHR flow	700- 3000 gpm	B1, D2, F2	Harsh	Yes	2	1E	Yes	Diverse measure- ment: PRHR outlet temperature
IRWST water level	0-100% of span	B1, D2, F2	Harsh	Yes	3 (Note 4)	1E	Yes	
RCS subcooling (Note 6)	200°F Sub- cooling to 35°F super heat	B1, F2	Harsh	Yes	2	1E	Yes	Diverse measure- ment: Core exit temperature & wide range RCS pressure
Passive containment cooling water flow	0-150 gpm	B1, D2	Mild	Yes	1 (Note 1)	1E	Yes	
PCS storage tank water level	5-100% of tank height	B1, D2	Mild	Yes	2	1E	Yes	Diverse measure- ment: PCS flow
IRWST surface temperature	50- 300°F	D3	None	None	1	Non-1E	No	
IRWST bottom temperature	50- 300°F	D3	None	None	1	Non-1E	No	
Steam line pressure	0-13200 psig	F2	Harsh/ Mild (Note 8)	Yes	1/steam generator (Note 11)	1E	No	

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Table 7.5-1 (Sheet 7 of 12)

POST-ACCIDENT MONITORING SYSTEM

Variable	Range/ Status	Type/ Category	Qualification		Number of Instruments Required	Power Supply	QDPS Indication (Note 2)	Remarks
			Environmental	Seismic				
Water-cooled chiller status	On/Off	F3	None	None	1/chiller	Non-1E	No	
Water-cooled chilled water pump status	On/Off	F3	None	None	1/pump	Non-1E	No	
Water-cooled chilled water valve status	Open/ Closed	F3	None	None	1/valve	Non-1E	No	
Spent fuel pool pump flow	0-1500 gpm	F3	None	None	1/pump	Non-1E	No	
Spent fuel pool temperature	50- 250°F	F3	None	None	1	Non-1E	No	
Spent fuel pool water level	0-100% of span	D2, F3	Mild	Yes	3 (Note 4)	1E	Yes	
CMT discharge isolation valve status	Open/ Closed	D2	Harsh	Yes	1/valve (Note 7)	1E	Yes	
CMT inlet isolation valve status	Open/ Closed	D2	Harsh	Yes	1/valve (Note 7)	1E	Yes	
CMT upper water level sensor	74.5% - 64% of Volume 78.0% - 63.5% of span	D2, F2	Harsh	Yes	1/tank	1E	Yes	
CMT lower water level sensor	27% - 17% of Volume 30.5% - 16% of span	D2, F2	Harsh	Yes	1/tank	1E	Yes	
IRWST injection isolation valve (Squib)	Open/ Closed	D2	Harsh	Yes	1/valve (Note 7)	1E	Yes	
IRWST line isolation valve status (MOV)	Open/ Closed	D3	None	None	1/valve	Non-1E	No	
ADS: first, second and third stage valve status	Open/ Closed	D2	Harsh	Yes	1/valve (Note 7)	1E	Yes	

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Table 7.5-1 (Sheet 9 of 12)

POST-ACCIDENT MONITORING SYSTEM

Variable	Range/ Status	Type/ Category	Qualification		Number of Instruments Required	Power Supply	QDPS Indication (Note 2)	Remarks
			Environmental	Seismic				
Purification return line stop valve status	Open/ Closed	D2	Harsh	None	1	Non-1E	No	
Boric acid tank level	0-100%	F3	None	None	1	Non-1E	No	
Demineralized water isolation valve status	Open/ Closed	D2	Mild	Yes	1/valve (Note 7)	1E	Yes	
Boric acid flow	0-175 gpm	F3	None	None	1	Non-1E	No	
Makeup blend valve status	Position	F3	None	None	1	Non-1E	No	
Makeup flow	0-175 gpm	F3	None	None	1	Non-1E	No	
Makeup pump status	On/Off	F3	None	None	1/pump	Non-1E	No	
Makeup flow control valve status	Position	F3	None	None	1	Non-1E	No	
Letdown flow	0-120 gpm	F3	None	None	1	Non-1E	No	
RNS hot leg suction isolation valve status	Open/ Closed	D2	Harsh	Yes	1/valve (Note 7)	1E	Yes	
RNS flow	0-3000 gpm	F3	None	None	1/pump	Non-1E	No	
<u>RCS sampling line isolation valve status</u>	<u>Open/ Closed</u>	<u>E3</u>	<u>Harsh</u>	<u>None</u>	<u>1/valve</u>	<u>Non-1E</u>	<u>No</u>	

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Table 7.5-1 (Sheet 10 of 12)

POST-ACCIDENT MONITORING SYSTEM

Variable	Range/ Status	Type/ Category	Qualification		Number of Instruments Required	Power Supply	QDPS Indication (Note 2)	Remarks
			Environmental	Seismic				
IRWST to RNS suction valve status	Open/ Closed	B1, F3	Harsh	Yes	1 (Note 7)	1E	Yes	
RNS discharge to IRWST valve status	Open/ Closed	F3	None	None	1/valve	Non-1E	No	
RNS pump status	On/Off	F3	None	None	1/pump	Non-1E	No	
Reactor vessel head vent valve status	Open/ Closed	D2	Harsh	Yes	1/valve Note 7)	1E	Yes	
MCR return air isolation valve status	Open/ Closed	D2, F3	Mild	Yes	1/valve (Note 7)	1E	Yes	
MCR toilet exhaust isolation valve status	Open/ Closed	D2	Mild	Yes	1/valve (Note 7)	1E	Yes	
MCR supply air isolation valve status	Open/ Closed	D2, F3	Mild	Yes	1/valve (Note 7)	1E	Yes	
MCR differential pressure	-1" to +1" wg	D2	Mild	Yes	2	1E	Yes	
MCR air delivery flowrate	0-80 cfm	D2	Mild	Yes	2	1E	Yes	
<u>MCR pressure relief isolation valve status</u>	<u>Open/ Closed</u>	<u>D2</u>	<u>Mild</u>	<u>Yes</u>	<u>1/valve</u>	<u>1E</u>	<u>Yes</u>	

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Table 7.5-1 (Sheet 12 of 12)

POST-ACCIDENT MONITORING SYSTEM

Variable	Range/ Status	Type/ Category	Qualification		Number of Instruments Required	Power Supply	QDPS Indication (Note 2)	Remarks
			Environmental	Seismic				
Main steam line radiation level	10^{-1} - 10^3 $\mu\text{Ci/cc}$	C2, E2	Mild	None	1/line	Non-1E	No	
Technical support center Control support area radiation	10^{-1} - 10^4 mR/hr	E3	None	None	1	Non-1E	No	
Meteorological parameters	N/A	E3	None	None	N/A	Non-1E	No	Site specific
Primary sampling station area radiation level	10^{-1} - 10^7 mR/hr	E3	None	None	1	Non-1E	No	

Notes:

- Total flow measurement is obtained from the sum of four branch flow devices.
- The same information is available in the ~~control support area~~ technical support center via the monitor bus. Information available on the qualified data processing system is also available at the remote shutdown workstation.
- Noble gas: 10^{-7} to 10^5 $\mu\text{Ci/cc}$
Particulate: 10^{-12} to 10^{-7} $\mu\text{Ci/cc}$
Iodines: 10^{-11} to 10^{-6} $\mu\text{Ci/cc}$
- The number of instruments required after stable plant conditions is two. A third channel is available through temporary connections to resolve information ambiguity if necessary (See subsection 7.5.4).
- Noble gas: 10^{-7} to 10^{-2} $\mu\text{Ci/cc}$
Particulate: 10^{-12} to 10^{-7} $\mu\text{Ci/cc}$
Iodines: 10^{-11} to 10^{-5} $\mu\text{Ci/cc}$
- Degree of subcooling is calculated from RCS wide range pressure and core exit temperature.
- This instrument is not required after 24 hours.
- Two steam line pressure instruments per SG are located inside containment, and are qualified for a harsh environment. Two steam line pressure instruments per SG are located outside containment (not in MSIV compartment), and are qualified for a mild environment.
- MCR supply air radiation monitoring is not required after MCR has been isolated.
- This instrument is only required when non-safety power is available.
- This instrument is not required if non-Class 1E UPS power is not available.
- These devices are backup verification to qualified system status parameters. These devices are purchased to perform in their anticipated service environments for the plant conditions for which they must function.

Table 7.5-7 (Sheet 4 of 4)

SUMMARY OF TYPE D VARIABLES

System	Variable	Type/Category
Containment Cooling	Containment temperature	D2
	PCS water storage tank series isolation valve status (MOV)	D2
	PCS water storage tank isolation valve status (non-MOV)	D2
	Passive containment cooling water flow	D2
	PCS storage tank water level	D2
HVAC System Status	MCR return air isolation valve status	D2
	MCR toilet exhaust isolation valve status	D2
	MCR supply air isolation valve status	D2
	MCR air delivery isolation valve status	D2
	<u>MCR pressure relief isolation valve status</u>	<u>D2</u>
	MCR air storage bottle pressure	D2
	MCR differential pressure	D2
	MCR air delivery flowrate	D2
Main Steam	Turbine stop valve status	D2
	Turbine control valve status	D2
	Condenser steam dump valve status	D2

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Table 7.5-8

SUMMARY OF TYPE E VARIABLES

Function Monitored	Variable	Type/Category
Containment Radiation	Containment area high range radiation level	E2
Area Radiation	Control support area Technical support center radiation level	E3
	Primary sampling station area radiation level	E3
Airborne Radioactivity Released from Plant	Turbine island vent discharge radiation level	E2
	Plant vent radiation level	E2
	Plant vent air flow	E2
	Main steam line radiation level	E2
	Boundary environs radiation	E3
	Main control room supply air radiation level	E3
Environs Radiation and Radioactivity	Site specific	E3
Meteorology	Site specific	E3
Accident Sampling	Primary coolant	E3
	Containment air	E3

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Chapter 8

CHAPTER 8**ELECTRIC POWER****8.1 Introduction****8.1.1 Utility Grid Description**

NRC 076 | The operating company grid system and interconnections to other grid systems and generating stations are as described ~~site specific~~.

8.1.2 Onsite Power System Description

The onsite power system is comprised of the main ac power system and the dc power system. The main ac power system is a non-Class 1E system. The dc power system consists of two independent systems: Class 1E dc system and non-Class 1E dc system. The ac and dc onsite power system configurations are shown on Figures 8.3.1-1 and 8.3.2-1, -2 and -3, respectively.

NRC 076 | The normal ac power supply to the main ac power system is provided from the station main generator. When the main generator is not available, plant auxiliary power is provided from the switchyard by backfeeding through the main stepup and unit auxiliary transformers. This is the preferred power supply. When neither the normal or the preferred power supply is available due to an electrical fault at either the main stepup transformer, unit auxiliary transformer, isophase bus, or 6.9kv nonsegregated bus duct, fast bus transfer will be initiated to transfer the loads to the reserve auxiliary transformers powered by maintenance sources of power. In addition, two non-Class 1E onsite standby diesel generators supply power to selected loads in the event of loss of the normal, preferred, and maintenance power sources. The reserve auxiliary transformers also serve as a source of maintenance power. The maintenance sources are as described ~~site specific~~.

The main generator is connected to the offsite power system by three single-phase stepup transformers. The normal power source for the plant auxiliary ac loads comes from the generator bus through two unit auxiliary transformers of identical rating. In the event of a loss of the main generator, the power is maintained without interruption from the preferred power supply by an autotrip of the main generator breaker. Power then flows from the switchyard to the auxiliary loads through the main and unit auxiliary transformers.

A spare single-phase main stepup transformer is provided in the transformer area. The spare can be placed in service upon failure of one phase of the main stepup transformers.

The onsite standby power system, powered by the two onsite standby diesel generators, supplies power to selected loads in the event of loss of other ac power sources. Loads that are priority loads for investment protection due to their specific functions (permanent nonsafety loads) are selected for access to the onsite standby power supply. Availability of the standby power source is not required to accomplish any safety function.

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two identically rated unit auxiliary transformers and an additional unit auxiliary transformer for the electric auxiliary boiler and as described site-specific loads.

- The onsite standby power system supplies ac power to the selected permanent nonsafety loads in the event of a main generator trip concurrent with the loss of preferred power source and maintenance power source when under fast bus transfer conditions. The onsite standby diesel generators are automatically connected to the associated 6.9 kV buses upon loss of bus voltage only after the generator rated voltage and frequency is established. Loads that are important for orderly plant shutdown are sequentially connected as shown in subsection 8.3.1 during this event.

The permanent nonsafety loads are not required for the plant safe shutdown; therefore, the onsite standby power system is a nonsafety-related system and non-Class 1E.

- For continued operation of the plant, a spare single-phase main transformer can be placed in service upon failure of one phase of the main stepup transformers.

8.1.4.3 Design Criteria, Regulatory Guides, and IEEE Standards

Refer to Table 8.1-1 for guidelines, and their applicability to Chapter 8.

The offsite and onsite ac power systems have no safety function and, therefore, their conformance to General Design Criteria, Regulatory Guides and IEEE Standards is not required, except as indicated in Table 8.1-1.

The Class 1E dc power system design is based on the following:

- General Design Criteria (GDC)

See Section 3.1 for a discussion of conformance to the General Design Criterion.

- Nuclear Regulatory Commission (NRC) Regulatory Guides

See Section 1.9 for the list and details of conformance to the regulatory guides.

- IEEE Standards.

The Class 1E dc power system design is based on the following IEEE Standards that are generally acceptable to the NRC as stated in the referenced Regulatory Guides:

- IEEE 308-1991, IEEE Standard Criteria for Class 1E Power Systems for Nuclear Power Generating Stations. Refer to Regulatory Guide 1.32.
- IEEE 317-1983, IEEE Standard for Electrical Penetration Assemblies in Containment Structures for Nuclear Power Generating Stations. Refer to Regulatory Guide 1.63.
- IEEE 323-1974, IEEE Standard for Qualifying Class 1E Equipment for Nuclear Power Generating Stations. Refer to Regulatory Guide 1.89.

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wind, tornados, floods, and external missiles by the external walls of the auxiliary building. See Section 3.5 for additional discussion on protection from missiles. The facility is designed to maintain its structural integrity following a safe shutdown earthquake and to perform its intended function following a postulated event such as fire, internal missiles, or pipe break. The walls surrounding the fuel handling area and new fuel storage pit protect the fuel from missiles generated inside the auxiliary building. The fuel handling area does not contain a credible source of missiles. Refer to subsection 1.2.4.3 for a discussion of the auxiliary building. Refer to Section 3.8 for a discussion of the structural design of the new fuel storage area. Refer to subsection 3.5.1 for a discussion of missile sources and protection.

The dry, unlined, approximately 17-foot deep reinforced concrete pit is designed to provide support for the new fuel storage rack. The rack is supported by the pit floor and laterally supported as required at the rack top by the pit wall structures. The walls of the new fuel pit are seismic Category I. The new fuel pit is normally covered to prevent foreign objects from entering the new fuel storage rack. Since the only crane that can access the new fuel pit does not have the capacity to lift heavy objects, as defined in subsection 9.1.5, the new fuel pit cover is not designed to protect the fuel assemblies from the effects of dropped heavy objects. Figures 1.2-7 through 1.2-10 show the relationship between the new fuel storage facility and other features of the fuel handling area.

The new fuel storage pit is drained by gravity drains that are part of the radioactive waste drain system (subsection 9.3.5), draining to the waste holdup tanks which are part of the liquid radwaste system (Section 11.2). These drains preclude flooding of the pit by an accidental release of water.

Nonseismic equipment in the vicinity of the new fuel storage rack is evaluated to confirm that its failure could not result in an increase of K_{eff} beyond the maximum allowable K_{eff} . Refer to subsection 3.7.3.13 for a discussion of the nonseismic equipment evaluation.

The new fuel handling crane is used to load new fuel assemblies into the new fuel rack and transfer new fuel assemblies from the new fuel pit into the spent fuel pool. The capacity of the new fuel handling crane is limited to lifting a fuel assembly, control rod assembly, and handling tool. The new fuel pit is not accessed by the fuel handling machine or by the cask handling crane. This precludes the movement of loads greater than fuel components over stored new fuel assemblies.

During fuel handling operations, a ventilation system removes gaseous radioactivity from the atmosphere above the new fuel pit. Refer to subsection 9.4.3 for a discussion of the fuel handling area HVAC system and Section 11.5 for process radiation monitoring. Security for the new fuel assemblies is described in separate security documents referred to in Section 13.6.

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9.1.1.2.1 New Fuel Rack Design

A. Design and Analysis of the New Fuel Rack

The new fuel storage racks are purchased equipment. The rack array center-to-center spacing of nominally 10.9 inches provides a minimum separation between adjacent fuel assemblies sufficient with neutron absorbing material to maintain a subcritical array. The purchase specification for the new fuel storage racks will require the vendor to perform confirmatory

Calculations are performed to demonstrate that the impact energy is absorbed by the dropped fuel assembly, the rack cells, and the rack base plate assembly.

The second accident condition assumes that the dropped assembly, control rod assembly, and handling tool (2027 pounds) falls straight through an empty cell and impacts the rack base plate from a drop height of 3 feet above the top of the rack. An analysis is performed that demonstrates the impact energy is absorbed by the fuel assembly and the rack base plate. The resulting rack deformations are evaluated in the criticality analysis to demonstrate that the criticality criteria are not violated.

D. Failure of the New Fuel Handling Crane

The fuel handling crane is a seismic Category II component. The crane and the attachment to the building structure is evaluated to show that the crane does not fall into the new fuel storage pit during a seismic event.

E. Internally Generated Missiles

The fuel handling area does not contain any credible sources of internally generated missiles.

Stress analyses are performed by the vendor using loads developed by the dynamic analysis. Stresses are calculated at critical sections of the rack and compared to acceptance criteria referenced in ASME Section III, Division I, Article NF3000.

9.1.1.3 Safety Evaluation

The rack, being a seismic Category I structure, is designed to withstand normal and postulated dead loads, live loads, loads resulting from thermal effects, and loads caused by the safe shutdown earthquake event.

The design of the rack is such that K_{eff} remains less than or equal to 0.95 with new fuel of the maximum design basis enrichment. For a postulated accident condition of flooding of the new fuel storage area with unborated water, K_{eff} does not exceed 0.98.

The new fuel storage racks ~~is~~are purchased equipment. The purchase specification for the new fuel storage racks requires a criticality analysis of the new fuel storage racks. The criticality evaluation considers the inherent neutron absorbing effect of the materials of construction, including fixed neutron absorbing "poison" material.

The new fuel rack is located in the new fuel storage pit, which has a cover to protect the new fuel from debris. No loads are required to be carried over the new fuel storage pit while the cover is in place. The cover is designed such that it will not fall and damage the fuel or fuel rack during a seismic event. Administrative controls are utilized when the cover is removed for new fuel transfer operations to limit the potential for dropped object damage.

The rack is also designed with adequate energy absorption capabilities to withstand the impact of a dropped fuel assembly from the maximum lift height of the new fuel handling crane. Handling equipment (cask handling crane) capable of carrying loads heavier than fuel components is

The heavy loads analysis is to confirm that a postulated load drop does not cause unacceptable damage to reactor fuel elements, or loss of safe shutdown or decay heat removal capability.

9.1.5.4 Inservice Inspection/Inservice Testing

Preoperational inspection and testing of overhead cranes is governed by ASME NOG-1. Tests include operational testing with 100 percent load to demonstrate function and speed controls for bridge, trolley, and hoist drives and proper functioning of limit switches, locking, and safety devices. A rated load test is performed with a 125 percent load.

Following plant startup, inservice inspection of overhead cranes is governed by site-specific procedures in accordance with ANSI B30.2. Testing of crane modifications is governed by ASME NOG-1. Inservice inspection and testing of other cranes and hoists is in accordance with manufacturer's recommendations and applicable industry standards.

In-service inspection and testing of special lifting devices and slings used in safety-related areas of the plant are in accordance with ANSI N14.6 and ANSI B30.9.

9.1.6 Combined License Information for Fuel Storage and Handling

9.1.6.1 Structural Dynamic and Stress Analysis for New Fuel Rack

The Combined License information requested in this subsection has been completely addressed in APP-GW-GLR-026 (Reference 16), and the applicable changes are incorporated into the DCD. No additional work is required by the Combined License applicant.

The following words represent the original Combined License Information Item commitment, which has been addressed as discussed above:

The Combined License applicant is responsible for a confirmatory structural dynamic and stress analysis for the new fuel rack, as described in subsection 9.1.1.2.1.

9.1.6.2 Criticality Analysis for New Fuel Rack

The Combined License information requested in this subsection has been completely addressed in APP-GW-GLR-030 (Reference 17), and the applicable changes are incorporated into the DCD. No additional work is required by the Combined License applicant.

The following words represent the original Combined License Information Item commitment, which has been addressed as discussed above:

The Combined License applicant is responsible for a confirmatory criticality analysis for the new fuel rack, as described in subsection 9.1.1.3. This report (Reference 17) ~~analysis should~~ addresses the degradation of integral neutron absorbing material in the new fuel pool storage racks as identified in GL-96-04, and assesses the integral neutron absorbing material capability to maintain a 5-percent subcriticality margin.

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3. ANSI N210-76, Design Objectives for Light Water Reactor Spent Fuel Storage Facilities at Nuclear Power Stations.
4. ANS 57.2-1983, Design Requirements for Light Water Reactor Spent Fuel Storage Facilities at Nuclear Power Plants.
5. Nuclear Regulatory Commission letter to All Power Reactor Licensees, from B. K. Grimes, "OT Position for Review and Acceptance of Spent Fuel Storage and Handling Applications," April 14, 1978.
6. ANS 57.1-1992, Design Requirements for Light Water Reactor Fuel Handling Systems.
7. Specifications for Electric Overhead Travelling Cranes CMAA, Specification 70 - 1999.
8. USNRC, "Control of Heavy Loads at Nuclear Power Plants," NUREG-0612, July 1980.
9. "Overhead and Gantry Cranes," ANSI/ASME B30.2-1990.
10. Deleted.
11. USNRC, "Single-Failure-Proof Cranes for Nuclear Power Plants," NUREG-0554, May 1979.
12. "Rules for Construction of Overhead and Gantry Cranes (Top Running Bridge, Multiple Girder)," ASME NOG-1-1998.
13. Deleted.
14. "Special Lifting Devices for Shipping Containers Weighing 10,000 Pounds or More," ANSI N14.6-1993.
15. "Slings," ASME/ANSI B30.9-1996.
16. APP-GW-GLR-026, "New Fuel Storage Rack Structural/Seismic Analysis," Westinghouse Electric Company LLC.
17. APP-GW-GLR-030, "New Fuel Storage Rack Criticality Analysis," Westinghouse Electric Company LLC, May 2006.
18. APP-GW-GLR-033, "Spent Fuel Storage Rack Structural/Seismic Analysis," Westinghouse Electric Company LLC.
19. APP-GW-GLR-045, "Evaluation of Critical Structures," Westinghouse Electric Company LLC.
20. APP-GW-GLR-029, "Spent Fuel Storage Racks Criticality Analysis," Westinghouse Electric Company LLC.
21. USNRC, 10 CFR 50.68, "Criticality Accident Requirements," January 2003.
22. USNRC, Regulatory Guide 1.124, Revision 1, "Service Limits and Loading Combinations for Class 1 Linear-Type Component Supports," January 1978.

Table 9.1-4			
STATION BLACKOUT/SEISMIC EVENT TIMES ⁽¹⁾			
Event	Time to Saturation ⁽¹⁾ (hours)	Height of Water Above Fuel at 72 Hours ⁽⁴⁾ (feet)	Height of Water Above Fuel at 7 Days ⁽⁴⁾ (feet)
NRC 161 Seismic Event ⁽²⁾ – Power Operation Immediately Following a Refueling ⁽⁷⁾	<u>6.50</u> 7.8	<u>1.62</u> 4 ⁽⁶⁾	<u>1.62</u> 4 ⁽⁶⁾
NRC 161 Seismic Event ⁽⁸⁾ – Refueling, Immediately Following Spent Fuel Region Offload ⁽³⁾⁽⁷⁾	<u>4.68</u> 5.6	8.3 ⁽⁵⁾	8.3 ⁽⁵⁾
NRC 161 Seismic Event ⁽⁸⁾ – Refueling, Emergency Full Core Off-Load ⁽³⁾ Immediately Following Refueling ⁽⁷⁾	<u>1.37</u> 3.4	8.3 ⁽⁵⁾	8.3 ⁽⁶⁾

Notes:

1. Times calculated neglect heat losses to the passive heat sinks in the fuel area of the auxiliary building.
2. Seismic event assumes water in the pool is initially drained to the level of the spent fuel pool cooling system connection simultaneous with a station blackout. Fuel cooling water sources are spent fuel pool, fuel transfer canal (including gate), and cask washdown pit for 72 hours. Between 72 hours and 7 days fuel cooling water provided from passive containment cooling system ancillary water storage tank.
3. Fuel movement complete, 150 hours after shutdown.
4. See subsection 9.1.3.5 for minimum water level.
5. Alignment of PCS water storage for supply of makeup water permits maintaining pool level at this elevation. Decay heat in reactor vessel is less than 9 MW, thus no PCS water is required for containment cooling.
6. Alignment of the PCS ancillary water storage tank and initiation of PCS recirculation pumps provide a makeup water supply to maintain this pool level or higher above the top of the fuel.
7. The number of fuel assemblies refueled has been conservatively established to include the worst case between an 18-month fuel cycle plus 5 defective fuel assemblies (69 total assemblies or 44% of the core) and a 24-month fuel cycle plus 5 defective fuel assemblies (77 total assemblies or 49% of the core).
8. Seismic event assumes water in the pool is initially drained to the level of the spent fuel pool cooling system connection simultaneous with a station blackout. Fuel cooling water sources are spent fuel pool, fuel transfer canal (including gate), cask washdown pit, and passive containment cooling system water storage tank for 7 days.

seat wear of inside containment isolation valve. This valve operator has a flow restricting orifice in the air line, so it opens more slowly than inside containment letdown flow isolation valve. In addition, during brief periods of shutdown, when the reactor coolant system is water solid, this valve throttles to maintain the reactor coolant system pressure. Manual control is also provided in the main control room and at the remote shutdown workstation.

Makeup Stop Valve

This normally open, air-operated stop check valve is located inside containment and functions to isolate the flow in the charging line to the reactor coolant system. This valve can be closed from the main control room or the remote shutdown workstation to isolate charging downstream of the regenerative heat exchanger. This valve is closed to support the auxiliary spray function. The valve fails open on loss of power or loss of instrument air so the charging line to the reactor coolant system remains available.

Auxiliary Spray Line Isolation Valve

This normally closed, air-operated globe valve is located inside containment, downstream of the regenerative heat exchanger, and functions to isolate the auxiliary spray line to the reactor coolant system pressurizer. This valve is opened to provide flow to the auxiliary spray line during heatups and cooldowns to add chemicals or to collapse the steam bubble in the pressurizer. This valve fails closed on a loss of power or loss of instrument air to accomplish the function of preserving the reactor coolant pressure boundary. This valve closes automatically on a low-1 pressurizer level signal from the protection and safety monitoring system to preserve reactor coolant pressure boundary. This valve is operated from the main control room and the remote shutdown workstation.

Makeup Line Containment Isolation Valves

These normally open, motor-operated globe valves provide containment isolation of the chemical and volume control system makeup line and automatically close on a high-2 pressurizer level, high steam generator level, or high-2 containment radiation signal from the protection and safety monitoring system. The valves close on a source range flux doubling signal to terminate possible unplanned boron dilution events. The valves also close on a safeguards actuation signal coincident with high-1 pressurizer level. This allows the chemical and volume control system to continue providing reactor coolant system makeup flow, if the makeup pumps are operating following a safeguards actuation signal. These valves are also controlled by the reactor makeup control system and close when makeup to other systems is provided. Manual control is provided in the main control room and at the remote shutdown workstation.

Hydrogen Addition Containment Isolation Valve

This normally closed, fail closed, air-operated globe valve is located outside containment in the hydrogen addition line. The valve automatically closes on a containment isolation signal from the protection and safety monitoring system. Manual control is provided in the main control room and at the remote shutdown workstation.

9.3.6.4.3.2.1 Ion Exchange Media Replacement

The initial and subsequent fill of ion exchange media is made through a resin fill nozzle on the top of the ion exchange vessel. When the media is spent and ready to be transferred to the solid radwaste system (WSS), the vessel is isolated from the process flow. The flush water line is opened to the sluice piping and demineralized water is pumped into the vessel through the normal process outlet connection upward through the media retention screen. The media fluidizes in the upward, reverse flow. When the bed has been fluidized, the sluice connection is opened and the bed is sluiced to the spent resin tanks in the solid radwaste system. Demineralized water flow continues until the bed has been removed and the sluice lines are flushed clean of spent resin.

9.3.6.4.3.2.2 Filter Cartridge Replacement

Replacement of spent filter cartridges is performed as described in subsection 11.4.2.3.2.

9.3.6.4.4 Abnormal Operation**9.3.6.4.4.1 Reactor Coolant System Leak**

The chemical and volume control system is capable of making up for a small reactor coolant system leak with either makeup pump at reactor coolant system pressures above the low pressure setpoint.

9.3.6.4.5 Accident Operation

The chemical and volume control system can provide borated makeup to the reactor coolant system following accidents such as small loss-of-coolant accidents, steam generator tube rupture events, and small steam line breaks. In addition, pressurizer auxiliary spray can reduce reactor coolant system pressure during certain events such as a steam generator tube rupture.

To protect against steam generator overfill, the makeup function is isolated by closing the makeup line containment isolation valves, if a high steam generator level signal is generated. These valves also close and isolate the system on a high pressurizer level signal.

Some of the valves in the chemical and volume control system are required to operate under accident conditions to effect reactor coolant system pressure boundary and containment isolation, as discussed in subsection 9.3.6.3.7.

9.3.6.4.5.1 Boron Dilution Events

The chemical and volume control system is designed to address a boron dilution accident by closing ~~either one of two redundant safety-related valves, tripping the makeup pumps and/or aligning the suction of the makeup pumps to the boric acid tank.~~ air-operated valves from the demineralized water system to the makeup pump suction.

For dilution events occurring at power (assuming the operator takes no action), a reactor trip is initiated on either an overpower trip or an overtemperature ΔT trip. Following a reactor trip signal, the line from the demineralized water system is isolated by closing two safety-related, ~~remotely~~

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air-operated valves. The three-way pump suction control valve aligns so the makeup pumps take suction from the boric acid tank. ~~When~~ If the ~~event~~ trip occurs while the makeup pumps are operating, the realignment of these valves causes the makeup pumps, if they continue to operate, to borate the plant.

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For dilution events during shutdown, the source range flux doubling signal is used to isolate the ~~makeup line to the reactor coolant from the demineralized water system by closing the two safety-related, remotely motor operated valves, isolate the line from the demineralized water system by closing the two safety-related, air-operated valves and trip the makeup pumps. The three-way pump suction control valve aligns the makeup pumps to take suction from the boric acid tank and therefore stops the dilution.~~ For refueling operations, administrative controls are used to prevent boron dilutions by verifying the valves in the line from the demineralized water system are closed and secured.

9.3.6.5 Design Evaluation

The chemical and volume control system has redundant, safety-related isolation valves and piping to protect the reactor coolant system pressure boundary, and is designed in accordance with ANSI/ANS-51.1 (Reference 4).

The chemical and volume control system lines that penetrate containment incorporate valve and piping arrangements, meeting the containment isolation criteria described in subsection 6.2.3.

Since the chemical and volume control system supplies unborated water to the reactor coolant system, the potential for inadvertent boron dilution events exists. A safety-related method of stopping an inadvertent boron dilution, which operates as described in subsection 9.3.6.4.5.1, is incorporated into the chemical and volume control system.

The chemical and volume control system also incorporates a safety-related method of isolating the makeup to the reactor coolant system upon receipt of a high steam generator level signal or a high pressurizer level signal, as described in subsection 9.3.6.4.5. Other chemical and volume control system components are not safety-related.

Chemical and volume control system components and piping are compatible with the radioactive fluids they contain or functions they perform.

The design of the chemical and volume control system is based on specific General Design Criteria and regulatory guides. The design of the chemical and volume control system is compared to the criteria set forth in subsection 9.3.4, "Chemical and Volume Control System (PWR) (Including Boron Recovery System)," Revision 2, of the Standard Review Plan. The specific General Design Criteria identified in the Standard Review Plan section are General Design Criteria 1, 2, 3, 4, 14, 29, 30, 31, 32, 33, 53, 54, 56, 60, and 61 as discussed in Section 3.1. Additionally, subsection 1.9.1 discusses compliance with Regulatory Guides 1.26 and 1.29.

9.3.6.6 Inspection and Testing Requirements

The only required surveillance are for containment and reactor coolant pressure boundary isolation valves and boron dilution mitigation valves. These valves are identified as active and are tested in accordance with the in-service test provisions provided in Table 3.9-16.

Other chemical and volume control system components are monitored for acceptable performance as follows:

- Mixed and cation bed demineralizer -- monitor for bed exhaustion by comparing reactor coolant system samples to samples taken at the outlet of the reactor coolant filter.
- Reactor coolant and makeup filters -- remotely monitor differential pressure with the installed gages and change the filter cartridges, or switch to the backup filter when high differential pressure is detected with the installed pressure gage.

Inspection of the various components is required in accordance with their safety class. The safety classification assignments can be found in Section 3.2.

9.3.6.6.1 Preoperational Inspection and Testing

Preoperational tests are conducted to verify proper operation of the chemical and volume control system. The preoperational tests include valve inspection and testing and flow testing.

9.3.6.6.1.1 Valve Inspection and Testing

The inspection requirements of the chemical and volume control system valves that constitute the reactor coolant pressure boundary are consistent with those identified in subsection 5.2.4. The inspection requirements of the chemical and volume control system valves that isolate the lines penetrating containment are consistent with those identified in Section 6.6.

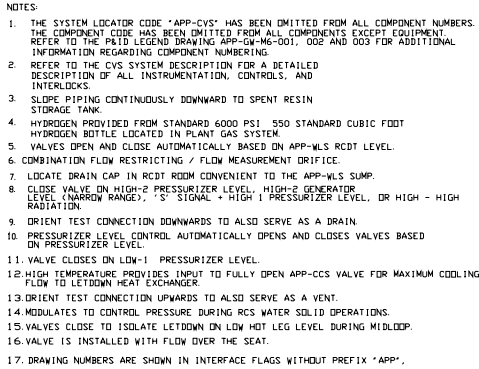
9.3.6.6.1.2 Flow Testing

Each chemical and volume control system pump is tested to measure the flow rate from each makeup pump to the reactor coolant system. Testing will be performed with the pump suction aligned to the boric acid tank and the discharge aligned to the reactor coolant system. Testing will also be performed with the pump suction aligned to the boric acid tank and the discharge aligned to the pressurizer auxiliary spray. Flow will be measured using instrumentation in the pump discharge line. Testing will confirm that each pump provides at least 100 gallons per minute of makeup flow at normal reactor coolant system operating pressure. This is the minimum flow rate necessary to meet the chemical and volume control system functional requirement of providing makeup and pressurizer spray to support the functions described in subsection 9.3.6.4.4.1. Testing is performed to verify that the maximum makeup flow with both pumps operating is less than 175200 gpm, as assumed in the boron dilution analyses presented in subsection 15.4.6. Testing is performed with both pumps operating and taking suction from the demineralized water system. The chemical and volume control system is aligned to the reactor coolant system at a pressure at or near atmospheric pressure.

level signal (plant control system), these valves automatically close to provide isolation of the letdown line. The letdown isolation valves also receive a signal from the protection and safety monitoring system to automatically close and isolate letdown during midloop operations based on a low hot leg level. Manual control is provided from the main control room and at the remote shutdown workstation. The letdown flow control valve controls reactor coolant system pressure during startup, as described in subsection 9.3.6.4.1.

- **Demineralized water system isolation valves** – To prevent inadvertent boron dilution, the demineralized water system isolation valves close on a signal from the protection and safety monitoring system derived from either a reactor trip signal, a source range flux doubling signal, low input voltage (loss of ac power) to the 1E dc and ~~uninterruptable~~ uninterruptible power supply system battery chargers, or a safety injection signal providing a safety-related method of stopping an inadvertent dilution. The main control room and remote shutdown workstation provide manual control for these valves.
- **Makeup isolation valves** – To isolate the makeup flow to the reactor coolant system, two valves are provided in the chemical and volume control system makeup line. These valves automatically close on a signal from the protection and safety monitoring system derived from source range flux doubling, ~~either a high-2~~ pressurizer level, high steam generator level ~~signal~~, or a safeguards signal coincident with high-1 pressurizer level to protect against pressurizer or steam generator overfill. Manual control for these valves is provided in the main control room and at the remote shutdown workstation. In addition, the valves close on a high-2 containment radiation signal to protect containment integrity.
- **Makeup flow control** – To control makeup flow to the reactor coolant system, a flow controller, which operates in the makeup line, in conjunction with the makeup control system is provided in the chemical and volume control system makeup pump discharge line. This flow controller controls makeup flow by modulating a flow control valve.
- **Makeup pump control** – The makeup pumps can be controlled from the main control room and at the remote shutdown workstation. On a signal from the plant control system generated by a low pressurizer level signal (relative to the programmed level), one of the chemical and volume control system makeup pumps starts automatically to provide makeup. The operating pump automatically stops when the pressurizer level increases to the correct value. During reactor coolant system boron changes (fuel depletion, startups, shutdowns, and refueling), the operator starts one of the makeup pumps after selecting the desired amount of boric acid.

The makeup pumps can be used to provide reactor coolant system makeup following an accident such as a small loss-of-coolant accident, a steam generator tube rupture, or a small steam line break. Following a safeguards actuation signal, if necessary, the operator remotely opens the makeup line isolation valves. One makeup pump automatically starts to control the pressurizer level between 10 and 20 percent. In addition, a makeup pump may be used to provide pressurizer auxiliary spray in reducing the reactor coolant system pressure for certain accident scenarios.



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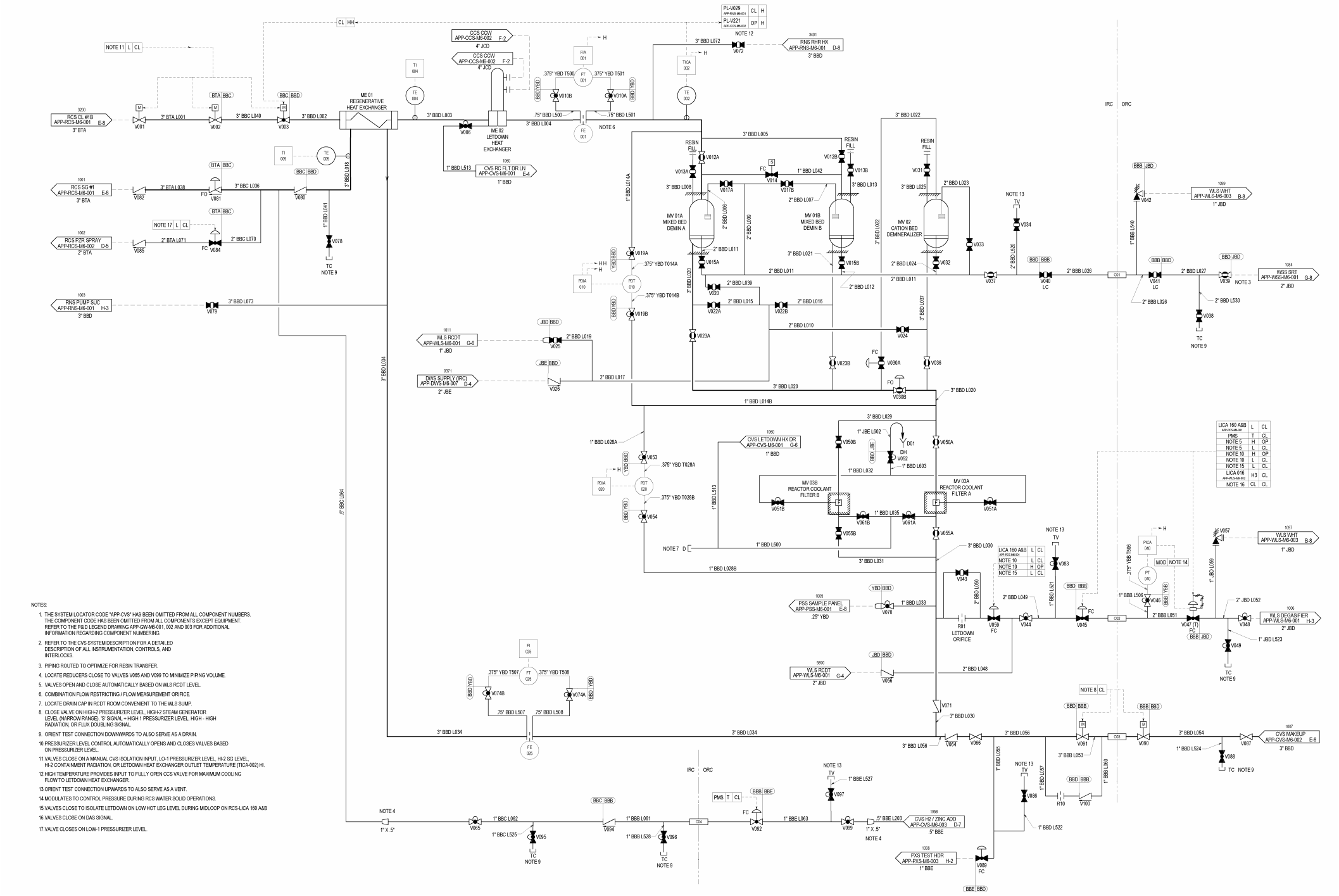
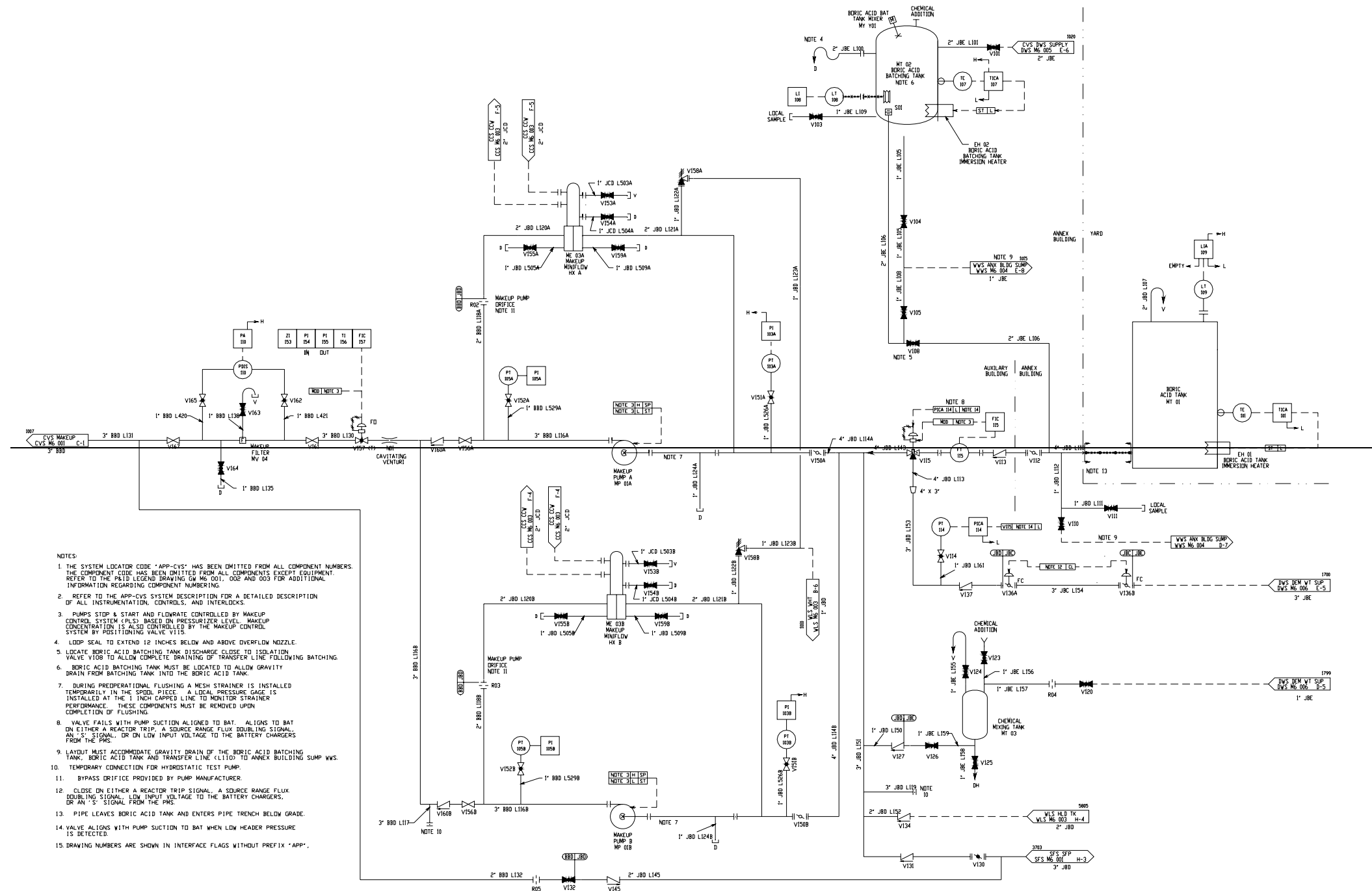


Figure 9.3.6-1 (Sheet 1 of 2)

Chemical and Volume Control
System Piping and Instrumentation Diagram
(REF) CVS 001



NRC 157

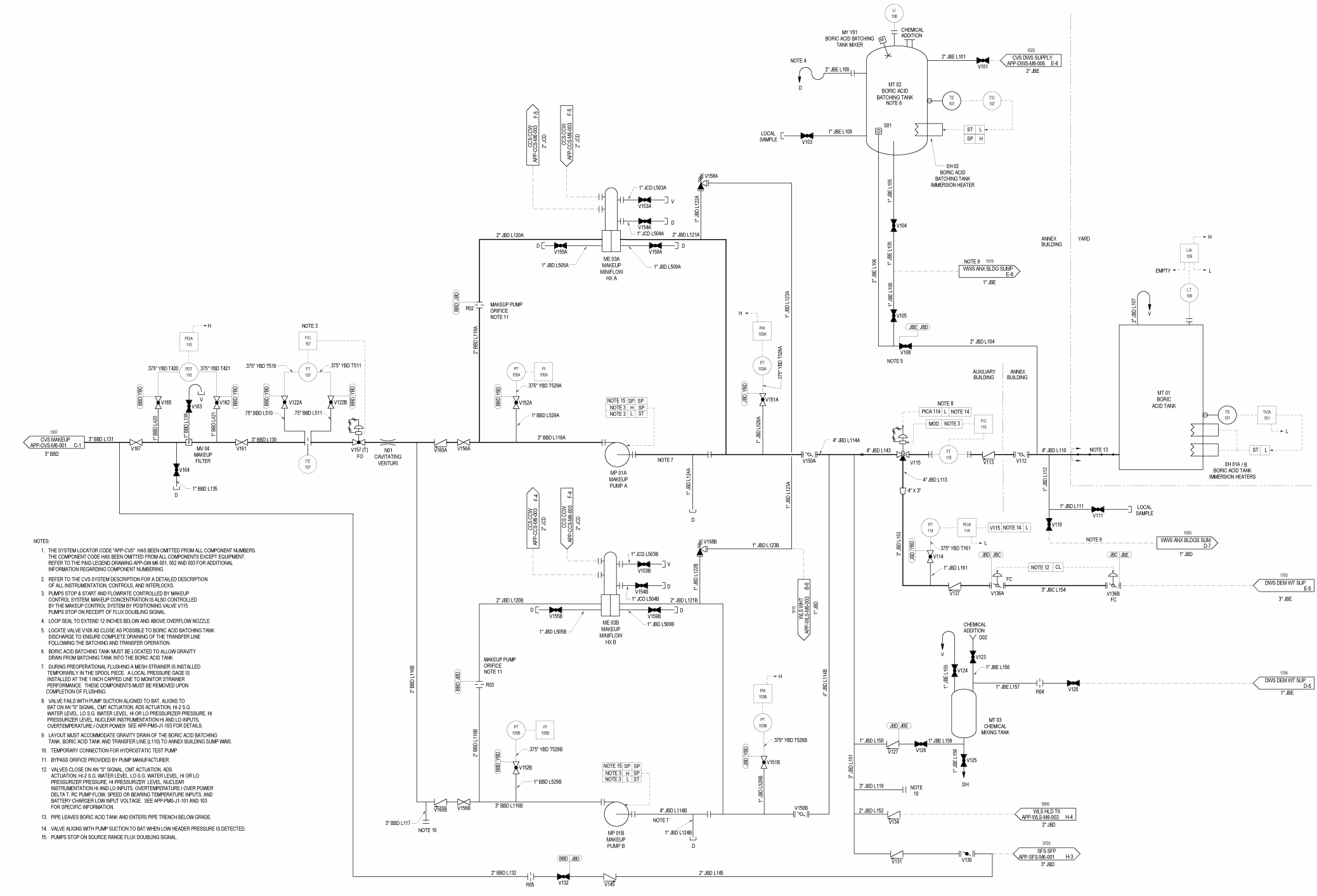


Figure 9.3.6-1 (Sheet 2 of 2)

Chemical and Volume Control
System Piping and Instrumentation Diagram
(REF) CVS 002

nonsafety-related and nonseismic. The equipment is procured to meet the environmental qualifications used in standard building practice.

The nuclear island nonradioactive ventilation system is designed to control the radiological habitability in the main control room within the guidelines presented in Standard Review Plan (SRP) 6.4 and NUREG 0696 (Reference 1), if the system is operable and ac power is available.

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Portions of the system that provide the defense-in-depth function of filtration of main control room/~~control support area~~~~technical support center~~ air during conditions of abnormal airborne radioactivity are designed, constructed, and tested to conform with Generic Issue B-36, as described in Section 1.9 and Regulatory Guide 1.140 (Reference 30), as described in Appendix 1A, and the applicable portions of ASME AG-1 (Reference 36), ASME N509 (Reference 2), and ASME N510 (Reference 3).

Power to the ancillary fans to provide post-72-hour ventilation of the control room and I&C rooms is supplied from divisions B and C regulating transformers through two series fuses for isolation. The fuses protect the regulating transformers from failures of the non-1E fan circuits. When normal ventilation is available the ancillary fan circuits are disconnected from the supply with manual normally-open switches.

The nuclear island nonradioactive ventilation system is designed to provide a reliable source of heating, ventilation, and cooling to the areas served when ac power is available. The system equipment and component functional capabilities are to minimize the potential for actuation of the main control room emergency habitability system or the potential reliance on passive equipment cooling. This is achieved through the use of redundant equipment and components that are connected to standby onsite ac power sources.

9.4.1.1.2 Power Generation Design Basis

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Main Control Room/Control Support Area (CSA)~~Technical Support Center~~ Areas

The nuclear island nonradioactive ventilation system provides the following specific functions:

NRC 050
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NRC 123

NRC 050
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NRC 123

- Controls the main control room and control support area relative humidity between 25 to 60 percent
- Maintains the main control room and CSA~~control support~~ areas at a slightly positive pressure with respect to the adjacent rooms and outside environment during normal operations to prevent infiltration of unmonitored air into the main control room and CSA~~control support~~ areas
- Isolates the main control room and/or CSA~~control support~~ area from the normal outdoor air intake and provides filtered outdoor air to pressurize the main control room and CSA~~control support~~ areas to a positive pressure of at least 1/8 inch wg when a high gaseous radioactivity concentration is detected in the main control room supply air duct

NRC 050
NRC 067
NRC 123

- Isolates the main control room and/or ~~CSA control support~~ area from the normal outdoor air intake and provides 100 percent recirculation air to the main control room and ~~CSA control support~~ areas when a high concentration of smoke is detected in the outside air intake
- Provides smoke removal capability for the main control room and control support area
- Maintains the main control room emergency habitability system passive cooling heat sink below its initial design ambient air temperature limit of 75°F
- Maintains the main control room/control support area carbon dioxide levels below 0.5 percent concentration and the air quality within the guidelines of Table 1 and Appendix C, Table C-1 of Reference 32.

The background noise level in the main control room does not exceed 65 dB(A) when the VBS is operating.

The system maintains the following room temperatures based on the maximum and minimum outside air safety temperature conditions shown in Chapter 2, Table 2-1:

Area	Temperature (°F)
Main control room	67 - 75
Control support area	67 – 78

Class 1E Electrical Rooms/Remote Shutdown Room

The nuclear island nonradioactive ventilation system provides the following specific functions:

- Exhausts air from the Class 1E battery rooms to limit the concentration of hydrogen gas to less than 2 percent by volume in accordance with Regulatory Guide 1.128 (Reference 31).
- Maintains the Class 1E electrical room emergency passive cooling heat sink below its initial design ambient air temperature limit of 75°F
- Provides smoke removal capability for the Class 1E electrical equipment rooms and battery rooms

The background noise level in the remote shutdown room does not exceed 65 dB(A) when the VBS is operating.

9.4.1.2.1 General Description

9.4.1.2.1.1 Main Control Room/Control Support Area HVAC Subsystem

The main control room/control support area HVAC subsystem serves the main control room and control support area with two 100 percent capacity supply air handling units, return/exhaust air fans, supplemental air filtration units, associated dampers, instrumentation and controls, and common ductwork. The supply air handling units and return/exhaust air fans are connected to common ductwork which distributes air to the main control room and ~~CSA control support~~ areas. The main control room envelope consists of the main control room, shift manager's office, operation work area, toilet, and operations break room area. The ~~CSA control support~~ area consists of the main control support area operations area, conference rooms, NRC room, computer rooms, shift turnover room, kitchen/rest area, and restrooms. The main control room and control support area toilets have separate exhaust fans.

Outside supply air is provided to the plant areas served by the main control room/control support area HVAC subsystem through an outside air intake duct that is protected by an intake enclosure located on the roof of the auxiliary building at elevation 153'-0". The outside air intake duct is located more than 50 feet below and more than 100 feet laterally away from the plant vent discharge. The supply, return, and toilet exhaust are the only HVAC penetrations in the main control room envelope and include redundant safety-related seismic Category I isolation valves that are physically located within the main control room envelope. Redundant safety-related radiation monitors are located inside the main control room upstream of the supply air isolation valves. These monitors initiate operation of the nonsafety-related supplemental air filtration units on high gaseous radioactivity concentrations and isolate the main control room from the nuclear island nonradioactive ventilation system on high-high particulate or iodine radioactivity concentrations. See Section 11.5 for a description of the main control room supply air radiation monitors.

Both redundant trains of supplemental air filtration units and one train of the supply air handling unit are located in the main control room mechanical equipment room at elevation 135'-3" in the auxiliary building. The other supply air handling unit subsystem is located in the main control room mechanical equipment room at elevation 135'-3" in the annex building. The main control room toilet exhaust fan is located at elevation 135'-3" in the auxiliary building. A humidifier is provided for each supply air handling unit. The supply air handling unit cooling coils are provided with chilled water from air-cooled chillers in the central chilled water system. See subsection 9.2.7 for the chilled water system description.

The main control room/control support area HVAC subsystem is designed so that smoke, hot gases, and fire suppressant will not migrate from one fire area to another to the extent that they could adversely affect safe shutdown capabilities, including operator actions. Fire or combination fire and smoke dampers are provided to isolate each fire area from adjacent fire areas during and following a fire in accordance with NFPA 90A (Reference 27) requirements. These combination smoke/fire dampers close in response to smoke detector signals or in response to the heat from a fire. See Appendix 9A for identification of fire areas.

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No silicone sealant or other patching material is used on the main control room/control support area HVAC subsystem filters, housing, mounting frame, ducts or penetrations.

9.4.1.2.1.2 Class 1E Electrical Room HVAC Subsystem

The Class 1E electrical room HVAC subsystem serves the Class 1E electrical rooms, Class 1E instrumentation and control (I&C) rooms, Class 1E electrical penetration rooms, Class 1E battery rooms, spare Class 1E battery room, remote shutdown room, and reactor coolant pump trip switchgear rooms. The A and C electrical divisions, spare battery room, and reactor coolant pump trip switchgear rooms are served by one ventilation subsystem; the B and D electrical divisions and remote shutdown room are served by a second ventilation subsystem.

Each subsystem consists of two 100 percent capacity supply air handling units, return/exhaust air fans, associated dampers, controls and instrumentation, and common ductwork. The supply air handling units and return/exhaust air fans are connected to a common ductwork which distributes air to the Class 1E electrical rooms. The outside supply air intake enclosure for the A and C subsystem is common to the main control room/control support area ~~technical support center~~ intake located on the roof of the auxiliary building at elevation 153'-0". The outside supply air intake for the B and D subsystem is located separate from the main control room/control support area ~~technical support center~~ air intake enclosure on the auxiliary building roof at elevation 153'-0". The exhaust ducts from the battery rooms are connected to the turbine building vent to remove hydrogen gas generated by the batteries.

The HVAC equipment which serves the A and C electrical divisions is located in the nuclear island nonradioactive ventilation system main control room/A and C equipment room at elevation 135'-3" in the auxiliary building. The HVAC equipment which serves the B and D division of Class 1E electrical equipment is located in the upper and lower nuclear island nonradioactive ventilation system B and D equipment rooms at elevation 117'-0" and at elevation 135'-3".

The supply air handling unit cooling coils are provided with chilled water from the air-cooled chillers in the central chilled water system. The two air handling units for each set of electrical divisions are provided with chilled water from redundant air-cooled chillers. Refer to subsection 9.2.7 for the chilled water system description.

Each subsystem for the Class 1E battery rooms is provided with two 100 percent capacity exhaust fans.

The Class 1E electrical room HVAC subsystem is designed so that smoke, hot gases, and fire suppressant does not migrate from one fire area to another to the extent that they could adversely affect safe shutdown capabilities, including operator actions. Separate ventilation subsystems are provided to serve the electrical division A and C equipment rooms and the electrical division B and D equipment rooms. The use of separate HVAC distribution subsystems for the redundant trains of electrical equipment prevents smoke and hot gases from migrating from one distribution division to the other through the ventilation system ducts. In addition, combination fire-smoke dampers are provided for Class 1E equipment rooms, including the remote shutdown room, to isolate each fire area and block the migration of smoke and hot gases to or from adjacent fire areas

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supplemental air filtration subsystem dampers are constructed, qualified, and tested in accordance with ANSI/AMCA 500 or ASME AG-1 (Reference 36), Section DA.

Combination Fire/Smoke Dampers

Combination fire/smoke dampers are provided at duct penetrations through fire barriers to maintain the fire resistance ratings of the barriers. The combination fire/smoke dampers meet the design, leakage testing, and installation requirements of UL-555S (Reference 25).

Ductwork and Accessories

Ductwork, duct supports, and accessories are constructed of galvanized steel. Ductwork subject to fan shutoff pressures is structurally designed to accommodate fan shutoff pressures. Ductwork, supports, and accessories meet the design and construction requirements of SMACNA Industrial Rectangular and Round Duct Construction Standards (References 16 and 34) and SMACNA HVAC Duct Construction Standards – Metal and Flexible (Reference 17). The supplemental air filtration and main control room/control support area HVAC subsystem's ductwork, including the air filtration units and the portion of the ductwork located outside of the main control room envelope, that maintains integrity of the main control room/control support area pressure boundary during conditions of abnormal airborne radioactivity are designed in accordance with ASME AG-1 (Reference 36), Article SA-4500, to provide low leakage components necessary to maintain main control room/control support area habitability.

9.4.1.2.3 System Operation

9.4.1.2.3.1 Main Control Room/Control Support Area HVAC Subsystem

Normal Plant Operation

During normal plant operation, one of the two 100 percent capacity supply air handling units and return/exhaust air fans operates continuously. Outside makeup air supply to the supply air handling units is provided through an outside air intake duct. The outside airflow rate is automatically controlled to maintain the main control room and CSA control support areas at a slightly positive pressure with respect to the surrounding areas and the outside environment.

The main control room/control support area supply air handling units are sized to provide cooling air for personnel comfort, equipment cooling, and to maintain the main control room emergency habitability passive heat sink below its initial ambient air design temperature. The temperature of the air supplied by each air handling unit is controlled by temperature sensors located in the main control room return air duct and in the computer room B return air duct to maintain the ambient air design temperature within its normal design temperature range by modulating the electric heat or chilled water cooling. Some spaces have convection heaters for temperature control.

The outside air is continuously monitored by smoke monitors located at the outside air intake plenum and the return air is monitored for smoke upstream of the supply air handling units. The supply air to the main control room is continuously monitored for airborne radioactivity while the supplemental air filtration units remain in a standby operating mode.

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The standby supply air handling unit and corresponding return/exhaust fans are started automatically if one of the following conditions shuts down the operating unit:

- Airflow rate of the operating fan is above or below predetermined setpoints.
- Return air temperature is above or below predetermined setpoints.
- Differential pressure between the main control room and the surrounding areas and outside environment is above or below predetermined setpoints.
- Loss of electrical and/or control power to the operating unit.

Abnormal Plant Operation

Control actions are taken at two levels of radioactivity as detected in the main control room supply air duct. The first is "high" radioactivity based upon gaseous radioactivity instrumentation. The second is "high-high" radioactivity based upon either particulate or iodine radioactivity instruments.

If "high" gaseous radioactivity is detected in the main control room supply air duct and the main control room/control support area HVAC subsystem is operable, both supplemental air filtration units automatically start to pressurize the main control room and CSA~~control support~~ areas to at least 1/8 inch wg with respect to the surrounding areas and the outside environment using filtered makeup air. After the room is pressurized, one of the supplemental air filtration units is manually shut down. The normal outside air makeup duct and the main control room and control support area toilet exhaust duct isolation dampers close. The smoke/purge exhaust isolation dampers close, if open. The main control room/control support area supply air handling unit continues to provide cooling with recirculation air to maintain the main control room passive heat sink below its initial ambient air design temperature and maintains the main control room and CSA~~control support~~ areas within their design temperatures. The supplemental air filtration subsystem pressurizes the combined volume of the main control room and control support area concurrently with filtered outside air. A portion of the recirculation air from the main control room and control support area is also filtered for cleanup of airborne radioactivity. The main control room/control support area HVAC equipment and ductwork that form an extension of the main control room/control support area pressure boundary limit the overall infiltration (negative operating pressure) and exfiltration (positive operating pressure) rates to those values shown in Table 9.4.1-1. Based on these values, the system is designed to maintain personnel doses within allowable General Design Criteria (GDC) 19 limits during design basis accidents in both the main control room and the control support area.

If ac power is unavailable for more than 10 minutes or if "high-high" particulate or iodine radioactivity is detected in the main control room supply air duct, which would lead to exceeding GDC 19 operator dose limits, the protection and safety monitoring system automatically isolates the main control room from the normal main control room/control support area HVAC subsystem by closing the supply, return, and toilet exhaust isolation valves. Main control room habitability is maintained by the main control room emergency habitability system, which is discussed in Section 6.4.

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NRC 050 | The main control room and ~~CSA control support~~ areas ventilation supply and return/exhaust ducts
NRC 067 | can be remotely or manually isolated from the main control room.

NRC 050 | If a high concentration of smoke is detected in the outside air intake, an alarm is initiated in the
NRC 067 | main control room and the main control room/control support area HVAC subsystem is manually
realigned to the recirculation mode by closing the outside air and toilet exhaust duct isolation
valves. The main control room and control support area toilet exhaust fans are tripped upon
closure of the isolation valves. The main control room/~~CSA control support~~ areas are not
pressurized when operating in the recirculation mode. The main control room/control support area
HVAC supply air subsystem continues to provide cooling, ventilation, and temperature control to
maintain the emergency habitability passive heat sink below its initial ambient air design
temperature and maintains the main control room and ~~CSA control support~~ areas within their
design temperatures.

In the event of a fire in the main control room or control support area, in response to heat from the
fire or upon receipt of a smoke signal from an area smoke detector, the combination fire/smoke
dampers close automatically to isolate the fire area. The subsystem continues to provide
ventilation/cooling to the unaffected area and maintains the unaffected areas at a slightly positive
pressure. The main control room/control support area HVAC subsystem can be manually
realigned to the once-through ventilation mode to supply 100 percent outside air to the unaffected
area. Realignment to the once-through ventilation mode minimizes the potential for migration of
smoke or hot gas from the fire area to the unaffected area. Smoke and hot gases can be removed
from the affected area by reopening the closed combination fire/smoke damper(s) from outside of
the affected fire area during the once-through ventilation mode. In the once-through ventilation
mode, the outside air intake damper to the air handling unit mixing plenum opens and the return
air damper to the air handling unit closes to provide 100 percent outside air to the supply air
handling unit. In this mode, the subsystem exhaust air isolation damper opens to exhaust the
return air directly to the turbine building vent.

Power is supplied to the main control room/control support area HVAC subsystem by the plant ac
electrical system. In the event of a loss of the plant ac electrical system, the main control
room/control support area ventilation subsystem can be transferred to the onsite standby diesel
generators. The convection heaters and duct heaters are not transferred to the onsite standby diesel
generator.

When complete ac power is lost and the outside air is acceptable radiologically and chemically,
MCR habitability is maintained by operating one of the two MCR ancillary fans to supply outside
air to the MCR. It is expected that outside air will be acceptable within 72 hours following a
radiological release. See subsection 6.4.2.2 for details. The outside air pathway to the ancillary
fans is provided through the nonradioactive ventilation system air intake opening located on the
roof, the mechanical room at floor elevation 135'-3", and nonradioactive ventilation system supply
duct. Warm air from the MCR is vented to the annex building through stairway S05, into the
remote shutdown room and the clean access corridor at elevation 100'-0". The ancillary fan
capacity and air flow rate maintain the MCR environment near the daily average outdoor air
temperature. The ancillary fans and flow path are located within the auxiliary building which is a
Seismic Category I structure.

NRC 050
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NRC 067
NRC 123

testing. Automatic controls are tested for actuation at the proper setpoints. Alarm functions are checked for operability. Air quality within the MCR/CSATSC environment is confirmed to be within the guidelines of Table 1 and Appendix C, Table C-1, of Reference 32 by analyzing air samples taken during preoperational testing.

The supplemental air filtration unit, HEPA filters, and charcoal adsorbers are tested in place in accordance with ASME N510 to verify that these components do not exceed a maximum allowable bypass leakage rate. Samples of charcoal adsorbent, used or new, are periodically tested to verify a minimum charcoal efficiency of 90 percent in accordance with Regulatory Guide 1.140 (Reference 30), except that test procedures and test frequency are conducted in accordance with ASME N510.

The ductwork for the supplemental air filtration subsystem and portions of the main control room/control support area HVAC subsystem that maintain the integrity of the main control room/control support area pressure boundary during conditions of abnormal airborne radioactivity are tested for leak tightness in accordance with ASME N510, Section 6. Testing for main control room/control support area inleakage during Main Control Room/Control Support Area HVAC Subsystem operation will be conducted in accordance with ASTM E741 (Reference 38). The remaining supply and return/exhaust ductwork is tested in place for leakage in accordance with SMACNA HVAC Duct Leakage Test Manual (Reference 18).

9.4.1.5 Instrumentation Applications

The nuclear island nonradioactive ventilation system is controlled by the plant control system except for the main control room isolation valves, which are controlled by the protection and safety monitoring system. Refer to subsection 7.1.1 for a description of the plant control and plant safety and monitoring systems. The instruments discussed below satisfy Table 4.2 of ASME N509 (Reference 2).

Temperature controllers are provided in the return air ducts to control the room air temperatures within the predetermined ranges. Temperature indication and alarms for the main control room return air, Class 1E electrical room return air, air handling unit supply air, supplemental filtration unit prefilter inlet air and charcoal adsorbers are provided to inform plant operators of abnormal temperature conditions.

Pressure differential indication and alarms are provided across each filter bank (except charcoal filters) to inform plant operators when filter changeout is necessary. Pressure differential indication and alarms are provided to control the main control room and monitor the control support area ambient room pressure differentials with respect to surrounding areas.

Radioactivity indication and alarms are provided to inform the main control room operators of gaseous, particulate, and iodine radioactivity concentrations in the main control room supply air duct. See Section 11.5 for a description of the main control room supply air duct radiation monitors and their actuation functions.

Smoke monitors are provided to detect smoke in the outside air intake duct to the main control room and the main control room and Class 1E electrical room return air ducts.

Airflow indication and alarms are provided to monitor operation of the supply and exhaust fans.

NRC 050
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Relative humidity indication and alarms are provided to monitor the average relative humidity in the return air from the main control room/~~CSA control support areas~~ and the inlet air to the supplemental air filtration unit charcoal filters.

Status indication is provided to monitor fans, heaters and controlled dampers.

9.4.2 Annex/Auxiliary Buildings Nonradioactive HVAC System

The annex/auxiliary buildings nonradioactive HVAC system serves the nonradioactive personnel and equipment areas, electrical equipment rooms, clean corridors, the ancillary diesel generator room and demineralized water deoxygenating room in the annex building, and the main steam isolation valve compartments, reactor trip switchgear rooms, and piping and electrical penetration areas in the auxiliary building.

9.4.2.1 Design Basis

9.4.2.1.1 Safety Design Basis

The annex/auxiliary buildings nonradioactive HVAC system serves no safety-related function and therefore has no nuclear safety design basis. System equipment and ductwork located in the nuclear island whose failure could affect the operability of safety-related systems or components are designed to seismic Category II requirements. The remaining portion of the system is nonseismic.

9.4.2.1.2 Power Generation Design Basis

The annex/auxiliary buildings nonradioactive HVAC system provides the following specific functions:

- Provides conditioned air to maintain acceptable temperatures for equipment and personnel working in the area
- Provides suitable environmental conditions for equipment in the main steam isolation valve (MSIV) compartments
- Prevents the buildup of hydrogen in non-Class 1E battery rooms to less than 2 percent hydrogen by volume
- Removes vitiated air from locker, toilet, shower facilities, and rest rooms

9.4.12 Combined License Information

The Combined License applicants referencing the AP1000 certified design will implement a program to maintain compliance with ASME AG-1 (Reference 36), ASME N509 (Reference 2), ASME N510 (Reference 3) and Regulatory Guide 1.140 (Reference 30) for portions of the nuclear island nonradioactive ventilation system and the containment air filtration system identified in subsection 9.4.1 and 9.4.7. The Combined License applicant will also provide a description of the MCR/~~CSATSC~~ HVAC subsystem's recirculation mode during toxic emergencies, and how the subsystem equipment isolates and operates, as applicable, consistent with the toxic issues, including conformance with Regulatory Guide 1.78 (Reference 37), to be addressed by the Combined License applicant as discussed in DCD subsection 6.4.7.

NRC 050
NRC 052
NRC 067
NRC 123

9.4.13 References

1. "Functional Criteria For Emergency Response Facilities," USNRC NUREG 0696.
2. "Nuclear Power Plant Air-Cleaning Units and Components," ASME N509-1989 (R1996).
3. "Testing of Nuclear Air-Cleaning Systems," ASME N510-1989.
4. "Laboratory Method of Testing Fans for Rating Purposes," ANSI/AMCA 210-85.
5. "Certified Ratings Program Air Performance," ANSI/AMCA 211-87.
6. "Reverberant Room Method of Testing Fans For Rating Purposes," ANSI/AMCA 300-85.
7. Gravimetric and Dust Spot Procedures for Testing Air-Cleaning Devices Used in General Ventilation for Removing Particulate Matter, ASHRAE 52.1, 1992.
8. "Test Performance of Air-Filter Units," UL-900, 1994.
9. "High-Efficiency, Particular, Air-Filter Units," UL-586, 1996.
10. "Heating and Cooling Equipment," UL 1995, 1995.
11. "Methods of Testing for Rating Forced Circulation Air Cooling and Air Heating Coils," ASHRAE 33-78.
12. "Forced-Circulation Air Cooling and Air Heating Coils," ANSI/ARI 410-91.
13. "Commercial and Industrial Humidifiers," ARI 640-96.
14. "Testing Methods for Louvers, Dampers, and Shutters," ANSI/AMCA 500-89.
15. "Fire Dampers," UL-555, 1999.
16. "Rectangular Industrial Duct Construction Standards," SMACNA, 1980.

9.5.2.5.3 Security Communications

NRC 054

Specific details for the security communication system are as discussed in separate security documents referred to in Section 13.6.

9.5.3 Plant Lighting System

NRC 054

The plant lighting system includes normal, emergency, panel, and security lighting. The normal lighting provides normal illumination during plant operating, maintenance, and test conditions. The emergency lighting provides illumination in areas where emergency operations are performed upon loss of normal lighting. The panel lighting in the control room is designed to provide the minimum illumination required at the safety panels. The security lighting system is described in separate security documents referred to in Section 13.6.

9.5.3.1 Design Basis**9.5.3.1.1 Safety Design Basis**

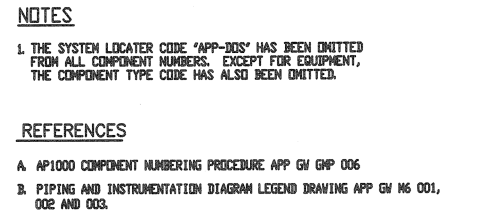
- The normal and emergency lighting in the main control room and in the remote shutdown room is non-Class 1E. The emergency lighting in these plant areas is fed from a Class 1E uninterruptible power supply through two series fuses that are coordinated for isolation. The emergency lighting provides illumination for 72 hours upon loss of normal lighting. In other plant areas, the emergency lighting provides illumination for 8 hours.
- Lighting for the safety panels in the control room is provided by the panel lighting system. The power for the panel lighting is from the Divisions B and C Class 1E inverters through Class 1E distribution panels. The panel lighting circuits up to the lighting fixture are classified as associated and are routed in Seismic Category I raceways. The bulbs are not seismically qualified.
- During the 72 hour period following a loss of all ac power sources, lighting in the main control room can be provided as described in subsection 9.5.3.2.2.

9.5.3.1.2 Power Generation Design Basis

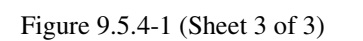
- The plant lighting system is non-Class 1E.
- The plant lighting system provides illumination levels for normal and emergency lighting as recommended in Illuminating Engineering Society Lighting Handbook (Reference 5).
- Mercury vapor lamps and mercury switches are not used in fuel handling areas.
- High-intensity discharge (HID) and fluorescent lamps are not used in the containment and fuel handling areas due to their mercury content. Incandescent lighting or other lighting not containing restricted materials is used in these areas.



**Standby Diesel and Auxiliary Boiler-Fuel Oil System
Piping and Instrumentation Diagram
(REF) DOS 001**



**Standby Diesel and Auxiliary Boiler-Fuel Oil System
Piping and Instrumentation Diagram**
(REF) DOS-002



Standby Diesel and Auxiliary Boiler Fuel Oil System
Piping and Instrumentation Diagram
 (REF) DOS-003

Fire Protection Adequacy Evaluation

A fire in this fire area is detected by a fire detector which produces an audible alarm locally and both visual and audible alarms in the main control room and the security central alarm station. The fire is extinguished manually using hose streams or portable extinguishers.

Combustible materials in this fire area are listed in Table 9A-3, and primarily consist of cable insulation and paper. There are concentrations of cable under the floor and within the control console. There are concentrations of paper, most of which is contained within metal filing cabinets or bookcases. This is a light hazard fire area and the rate of fire growth is expected to be slow. Three-hour fire barriers provide adequate separation from adjacent fire areas and the fire is contained within the fire area.

The ventilation system does not contribute to the spread of the fire or smoke as described in the Smoke Control Features section above.

Fire Protection System Integrity

An evaluation of the consequences of inadvertent operation of an automatic suppression system is not required because there are no such systems in this fire area. An evaluation of the consequences of a break in a fire protection line is not required because no such lines pass through or terminate in this fire area.

Safe Shutdown Evaluation

Table 9A-2 lists the safe shutdown components located in this fire area. The remote shutdown room contains circuits from the four Class 1E electrical divisions. Electrical separation to and inside the remote shutdown room is maintained per industry standards. The remote shutdown room is an alternate to the main control room. The transfer of operations to the remote shutdown workstation is controlled by a transfer switch set located in the remote shutdown workstation area. In the unlikely event that the fire damages the transfer switch set, causing transfer of control from the main control room to the remote shutdown workstation, the operator restores control to the main control room by de-energizing fire area 1202 AF 05 (stair S05). Safe shutdown is achieved using the safe shutdown components listed in Table 9A-2.

Most remote shutdown workstation controls use soft-controls which communicate over multiplexed data channels. Fire-induced spurious actuation from these multiplexed soft controls is not assumed. Fire-induced actuations from the dedicated switches in this area are prevented during normal operation by the transfer switch logic, which only enables operation from the remote shutdown workstation dedicated switches when control is transferred to the remote shutdown workstation.

Neither a fire nor fire suppression activities in this fire area affect the safe shutdown capability of components located in adjacent fire areas.

NRC 099

- Hose station(s)
- Portable fire extinguishers

Smoke Control Features

Combination fire-smoke dampers in the main control room/~~control support area~~~~technical support center~~ HVAC subsystem of the NI non-radioactive ventilation system (VBS) close automatically upon detection of smoke or on high temperature to isolate this fire area. The balance of this and other VBS subsystems continue to provide ventilation to the unaffected fire areas. This subsystem may be manually realigned to the once-through smoke exhaust ventilation mode to minimize the potential migration of smoke. If the exhaust fire-smoke damper for this fire area is operable, the damper may be reopened to further reduce the migration of smoke. After the fire, smoke is removed from this fire area by reopening the fire dampers and operating the ventilation system in the once-through ventilation mode.

Fire Protection Adequacy Evaluation

A fire in this fire area is detected by a fire detector which produces an audible alarm locally and both visual and audible alarms in the main control room and the security central alarm station. The fire is extinguished manually using hose streams or portable extinguishers.

Combustible materials in this fire area are listed in Table 9A-3 and primarily consist of electrical cable insulation and ordinary combustible material such as wood and paper. Combustibles are relatively uniformly distributed throughout the fire area. This is a light hazard fire area and the rate of fire growth is expected to be slow. Minimum two-hour fire barriers are provided and the building exterior wall is not rated. Fire zones within this fire area are separated by walls as shown in Figure 9A-4. The corridor walls of fire zone 4041 AF 40410 are rated for one-hour in accordance with Uniform Building Code requirements for exit corridors.

The ventilation system does not contribute to the spread of the fire or smoke as described in the Smoke Control Features section above.

9A.3.4.17 Fire Area 4041 AF 02

This fire area is comprised of the following room(s):

Room No.

40400	Corridor
40401	Restroom

There are no systems in this fire area which normally contain radioactive material.

Fire Detection and Suppression Features

- Fire detectors
- Hose station(s)
- Portable fire extinguishers

NRC 050
NRC 052
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Chapter 10

10.2 Turbine-Generator

The function of the turbine-generator is to convert thermal energy into electric power.

10.2.1 Design Basis

10.2.1.1 Safety Design Basis

The turbine-generator serves no safety-related function and therefore has no nuclear safety design basis.

10.2.1.2 Power Generation Design Basis

The following is a list of the principal design features:

- The turbine-generator is designed for baseload operation and for load follow operation.
- The main turbine system (MTS) is designed for electric power production consistent with the capability of the reactor and the reactor coolant system.
- The turbine-generator is designed to trip automatically under abnormal conditions.
- The system is designed to provide proper drainage of related piping and components to prevent water induction into the main turbine.
- The main turbine system satisfies the recommendations of Nuclear Regulatory Commission Branch Technical Position ASB 3-1 as related to breaks in high-energy and moderate-energy piping systems outside containment. The main turbine system is considered a high-energy system.
- The system provides extraction steam for seven~~six~~ stages of regenerative feedwater heating.

NRC 071 |

10.2.2 System Description

The turbine-generator is designated as a TC6F 52-inch last-stage blade unit consisting of turbines, a generator, external moisture separator/reheaters, controls, and auxiliary subsystems. (See Figure 10.2-1.) The major design parameters of the turbine-generator and auxiliaries are presented in Table 10.2-1. The piping and instrumentation diagram containing the stop, control, intercept, and reheat valves is shown in Figure 10.3.2-2.

The turbine-generator and associated piping, valves, and controls are located completely within the turbine building. There are no safety-related systems or components located within the turbine building. The probability of destructive overspeed condition and missile generation, assuming the recommended inspection and test frequencies, is less than 1×10^{-5} per year. In addition, orientation of the turbine-generator is such that a high-energy missile would be directed at a 90 degree angle away from safety-related structures, systems, or components. Failure of turbine-generator equipment does not preclude safe shutdown of the reactor. The

Auxiliary steam from the auxiliary steam supply system (see subsection 10.4.10) is supplied to the deaerator during recirculation conditions and maintains the pressure in the tank above atmospheric. The steam heats the condensate during cleanup and recirculation for liberation of noncondensables. Auxiliary steam is also automatically supplied to the deaerator following turbine trip to assist in maintaining deaerator pressure above atmospheric.

The shells of the deaerator and the deaerator storage tank are carbon steel. Most of the internals of the deaerator, including the tray assemblies, vent condenser, and spray valves, are stainless steel.

A high level dump line and control valve provide overflow protection to the deaerator storage tank. During high level conditions, water from the deaerator storage tank is drained to the main condenser.

NRC 070 |

High-Pressure Feedwater Heaters

The main feedwater pumps discharge into a parallel string of No. 6 and No. 7 high-pressure feedwater heaters. These heaters are shell and tube heat exchangers with integral drain coolers. Heated feedwater flows through the tubes and extraction steam condenses in the shell. The No. 6 and No. 7 heaters drain into low-pressure heater No. 5 (deaerator).

A drain line from each heater allows direct discharge of the heater drains to the condenser in the event the normal drain path is not available or flooding occurs in the heater.

The high-pressure feedwater heater shells are carbon steel, and the tubes are stainless steel.

Feedwater Booster Pumps

The feedwater booster pumps are horizontal, centrifugal pumps located upstream of the main feedwater pumps. Each feedwater booster pump takes suction from the deaerator storage tank and pumps forward to its associated main feedwater pump. An electric motor drives both the booster pump and the main feedwater pump. The booster pump is driven by one end of the motor shaft and the main pump is driven by the other end through a mechanical speed increaser. The booster pump, operating at a lower speed than the main feedwater pump, boosts the pressure of feedwater from the deaerator to meet the net positive suction head requirements of the main feedwater pump.

Main Feedwater Pumps

The three main feedwater pumps operate in parallel and take suction from the associated feedwater booster pumps. The combined discharge from the main feedwater pumps is supplied to the No. 6 high-pressure feedwater heater, the No. 7 high-pressure feedwater heater, and then to the steam generator system. Each main feedwater pump is a horizontal, centrifugal pump driven, through a mechanical speed increaser, by the motor that drives the associated feedwater booster pump.

Isolation valves allow each of the booster/main feedwater pumps to be individually removed from service while continuing power operations at reduced capacity.

NRC 066 |

room to achieve the desired flow rate. Feedwater is recirculated from downstream of the No. 76 feedwater heaters to the main condenser for cleanup and deaeration of the condensate and feedwater inventory.

10.4.7.2.3.1.4 Plant Heatup

The condenser hotwell makeup and overflow valves are enabled and function automatically during the plant heatup cycle to maintain condensate inventory. Condensate is returned to the condensate storage tank as volume expansion occurs, and makeup occurs as needed for system losses.

During heatup, the main condenser is available to accept turbine bypass steam from the main steam system, as well as various drains, vents, and condensate/feedwater recirculation flow. Noncondensable gases are removed in the air removal sections of the main condenser and through the deaerator vents. Control and monitoring of water quality and chemistry are accomplished by operation of the condensate polishing equipment, chemical feed system, and secondary sampling equipment as required.

The steam generators are filled, as required, either by the startup feedwater pumps using water from the condensate storage tank, or alternatively by a booster/main feedwater pump using water from the deaerator storage tank and supplied through cross connect piping to the startup feedwater control valves. The steam generators are drained, as required, through the steam generator blowdown system.

During the initial stages of plant heatup, one condensate pump operates as necessary to maintain level in the deaerator storage tank. Either one or both startup feedwater pumps, or one booster/main feedwater pump, is in operation when feeding water to the steam generators. The feedwater pumps in use operate on minimum flow recirculation as necessary while maintaining the water level of the steam generators.

Feedwater is controlled by the startup feedwater control valves (SFCVs) which are operated either manually from the control room or automatically in accordance with steam generator level demand. Condensate flow to the steam generator blowdown heat exchangers is controlled during plant heatup to obtain the necessary cooling to the blowdown stream. Any excess level in the deaerator storage tank is automatically drained to the main condenser through the deaerator high level dump flow path.

10.4.7.2.3.2 Power Operation

One operating condensate pump supplies sufficient condensate flow to the deaerator during initial power operation and at low-power levels. As power escalates, a second condensate pump is started prior to exceeding approximately 50-percent, full-load condensate flow. The third condensate pump is in standby.

The condensate regulating valves to the deaerator automatically maintain the level of the deaerator storage tank. If condensate flow to the deaerator drops below the minimum required flow for operation of the gland steam condenser or the condensate pumps, the hotwell recirculation valve to the condenser opens to provide the minimum flow.

Chapter 11

mixed liquid waste. The useful storage volume in the packaged waste storage room is approximately 3900 cubic feet (10 feet deep, 30 feet long, and 13 feet high), which accommodates more than one full offsite waste shipment using a tractor-trailer truck. The packaged waste storage room provides storage for more than two years at the expected rate of generation and more than a year at the maximum rate of generation. One four-drum containment pallet provides more than 8 months of storage capacity for the liquid mixed wastes and the volume reduced liquid chemical wastes at the expected rate of generation and more than 4 months at the maximum rate.

A conservative estimate of solid wet waste includes blowdown material based on continuous operation of the steam generator blowdown purification system, with leakage from the primary to secondary system levels. The volume of radioactively contaminated material from this source is estimated to be 540 cubic feet per year. Provisions for processing and disposal of radioactive steam generator blowdown resins and membranes are described in subsection 10.4.8. Note that, although included here for conservatism, this volume of contaminated resin will be removed from the plant within the contaminated electrodeionization unit and not stored as wet waste.

The condensate polishing system includes mixed bed ion exchanger vessels for purification of the condensate as described in subsection 10.4.6. Should the resins become radioactive, the resins are transferred from the condensate polishing vessel directly to a temporary processing unit or to the temporary processing unit via the spent resin tank. The processing unit, located outside of the turbine building, dewateres and processes the resins as required for offsite disposal. Radioactive condensate polishing resin will have very low activity. It will be disposed in containers as permitted by DOT regulations. After packaging, the resins may be stored in the radwaste building. Based on a typical condensate polishing system operation of 30 days per refueling cycle with leakage from the primary system to the secondary system, the volume of radioactively contaminated resin is estimated to be 206 cubic feet per year (one 309 cubic foot bed per refueling cycle). Normal disposal of nonradioactive condensate polishing system resins is described in subsection 10.4.6.

The parameters used to calculate the activities of the steam generator blowdown solid waste and condensate polishing resins are given in Table 11.4-1. Based on the above volumes, the disposal volume is estimated to be 939 cubic feet per year. The expected and maximum activities of the resins as generated are given in Tables 11.4-6 and 11.4-7, respectively. The expected and maximum activities of resins as shipped, based on 90 days decay prior to shipment, are given in Tables 11.4-8 and 11.4-9, respectively.

11.4.2.2 Component Description

The seismic design classification and safety classification for the solid waste management system components are listed in Section 3.2. The components listed are located in the Seismic Category I Nuclear Island. Table 11.4-10 lists the solid waste management system equipment design parameters. The following subsections provide a functional description of the major system components.

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- IV.3 Portable or mobile systems will be located in either the rail car bay of the auxiliary building or in the mobile systems facility in the radwaste building. The spent resin waste container fill station or the shipping cask in the auxiliary building collects spillage of spent resin during waste container filling operations. The radwaste and auxiliary buildings contain and drain spillage to the liquid radwaste system via the radioactive waste drain system as described in subsection 1.2.7 and Section 11.2. Portable or mobile systems will, when required, have their own HEPA filtered exhaust ventilation system. HEPA filtered exhaust is required when airborne radioactivity would exceed 10 CFR 20 derived air concentration limits for radiation workers. The mobile systems facility has connections on the exhaust ventilation ducts for connecting exhaust duct from mobile or portable processing systems to the building's exhaust ventilation system.
- IV.4 Although the seismic criteria of Regulatory Guide 1.143 are not applicable to structures housing mobile or portable solid radwaste systems, the portable equipment used for spent resin container filling and dewatering and high-activity filter cartridge packaging will be housed within the Seismic Category I auxiliary building. The radwaste building, which provides shelter for mobile or portable radwaste systems, is non-seismic in accordance with Branch Technical Position ETSB 11-3.

11.4.2.4.2 Central Radwaste Processing Facility

NRC 116

NRC 116

As an alternative to the mobile or portable processes for lower-activity wastes (~~generally wastes reading below 200 mR/hr~~), the wastes may be sent to a licensed central radwaste processing facility for processing and disposal. This option requires minimal onsite processing to remove ~~hazardous-radioactive~~ materials from the waste streams. The wastes are loaded into a cargo container. The mobile systems facility includes a designated laydown area, and the mobile systems facility crane may be used to handle a cargo container.

11.4.2.5 Facilities

11.4.2.5.1 Auxiliary Building

Resin and filtration media transfer lines from the various ion exchangers are routed to the spent resin tanks on elevation 100' - 0" in the southwest corner of the auxiliary building. The spent resin system pumps, valves, and piping are located in shielded rooms near the spent resin tanks.

Liquid radwaste system transfer lines to and from the radwaste building are routed to the south wall of the auxiliary building where they penetrate and enter into a shielded pipe pit in the base mat of the radwaste building.

Accessways in the auxiliary building are used to move the filter transfer casks. This includes filter transfer cask handling from the containment, where the chemical and volume control filters are located, to the auxiliary building rail car bay, where the filter cartridges are stored and subsequently packaged using mobile equipment. These accessways are also used to move dry active waste from various collection locations to the radwaste building. Enclosed access is provided between the auxiliary building and the radwaste building on elevation 100'-0" (grade level).

11.5.4 Process and Airborne Monitoring and Sampling

Radiation monitors are used to initiate automatic closure of isolation valves and dampers in liquid and gaseous process systems as described in subsection 11.5.2.3. These radiation monitors address the requirement of General Design Criterion 60 to suitably control the release of radioactive materials in gaseous and liquid effluents.

Radiation monitors are used in the radioactive waste processing systems as described in subsection 11.5.2.3. These radiation monitors address the requirement of General Design Criterion 63 to monitor radiation levels in radioactive waste systems.

Radiation monitors are used in the ventilation systems as described in subsection 11.5.2.3 to ensure that airborne concentrations within the plant are within the limits of 10 CFR 20.

11.5.5 Post-Accident Radiation Monitoring

The radiation monitors listed below meet the guidelines of Regulatory Guide 1.97 and are described in subsections 11.5.2.3 and 11.5.6.2. For further Regulatory Guide 1.97 information refer to Appendix 17A and Section 7.5.

- Main steam line radiation monitors
- Steam generator blowdown radiation monitor
- Main control room supply air duct radiation monitors
- Plant vent radiation monitor
- Turbine island vent discharge radiation monitor
- Containment high range radiation monitors
- Primary sampling room area monitor
- ~~Control support~~ CSA area monitor

The post-accident sampling system is described in subsection 9.3.3 and is used to obtain samples for onsite laboratory analysis, including radioisotopic analysis, after a postulated accident.

11.5.6 Area Radiation Monitors

The area radiation monitors are provided to supplement the personnel and area radiation survey provisions of the AP1000 health physics program described in Section 12.5 and to comply with the personnel radiation protection guidelines of 10 CFR 20, 10 CFR 50, and 10 CFR 70; and Regulatory Guides 1.97, 8.2, and 8.8.

The monitor is an extended range monitor that uses a gamma-sensitive ion chamber. The monitor range and principal isotopes are listed in Table 11.5-2.

NRC 050 | **Control Support Area (CSA) Area Monitor**

NRC 050 | The control support area is the location from which engineering support will be provided to the operators following a postulated accident. The ~~CSA~~control support area radiation monitor (RMS-JE-RE016) is located so that its readout is representative of the radiation to which the support personnel are exposed. A local readout, an audible alarm, and visual alarms are provided locally to alert personnel to increasing exposure rates. A local readout, an audible alarm, and visual alarms are provided outside of the room and are visible to personnel prior to entry. Indication and alarms are also provided in the main control room.

The monitor is a normal range monitor that uses a gamma-sensitive Geiger-Mueller tube. The monitor range and principal isotopes are listed in Table 11.5-2.

11.5.6.3 Normal Range Area Monitors

Normal range area radiation monitors are located in accordance with the location criteria given in subsection 11.5.6.1. A local readout, an audible alarm, and visual alarms are provided in each monitored area to alert operating personnel to increasing exposure rates. Visual alarms are provided outside of each monitored area so that they are visible to operating personnel prior to entry. Indication and alarms are also provided in the main control room.

The monitor detectors are gamma-sensitive Geiger-Mueller tubes. The monitors and their ranges are listed in Table 11.5-2.

11.5.6.4 Fuel Handling Area Criticality Monitors

Criticality monitoring of the fuel handling and storage areas is performed in accordance with 10 CFR 70.24 by radiation monitors RMS-JE-RE012 and RMS-JE-RE020. The area radiation monitoring is augmented during fuel handling operations by a portable radiation monitor on the machine handling fuel. The fuel handling area radiation monitor parameters are provided in Table 11.5-2.

The permanent criticality monitors are physically separated by a large distance and have overlapping fields of view. Each detector's field of view can detect radiation from a fuel criticality accident in the areas occupied by personnel where fuel is stored and handled. The criticality monitors do not have a direct line of sight in the new fuel storage pit because the arrangement of new fuel prevents accidental criticality. The alarm set points of the radiation monitors are below the sensitivity needed to detect the 10 CFR 70.24 specified 20 rads/minute dose rate in soft tissue of combined gamma and neutron radiation from an unshielded source at two meters distance. A criticality excursion will produce an audible local alarm and an alarm in the plant MCR.

Table 11.5-2

AREA RADIATION MONITOR DETECTOR PARAMETERS

Detector	Type	Service	Nominal Range
PXS-JE-RE160	γ	Containment High Range (Note 3)	1.0E-0 to 1.0E+7 R/hr
PXS-JE-RE161	γ	Containment High Range (Note 3)	1.0E-0 to 1.0E+7 R/hr
PXS-JE-RE162	γ	Containment High Range (Note 3)	1.0E-0 to 1.0E+7 R/hr
PXS-JE-RE163	γ	Containment High Range (Note 3)	1.0E-0 to 1.0E+7 R/hr
RMS-JE-RE008	γ	Primary Sampling Room	1.0E-1 to 1.0E+7 mR/hr
RMS-JE-RE009	γ	Containment Area - Personnel Hatch	1.0E-1 to 1.0E+4 mR/hr (Note 1)
RMS-JE-RE010	γ	Main Control Room	1.0E-1 to 1.0E+4 mR/hr
RMS-JE-RE011	γ	Chemistry Laboratory Area	1.0E-1 to 1.0E+4 mR/hr
RMS-JE-RE012	γ	Fuel Handling Area	1.0E-1 to 1.0E+4 mR/hr (Note 2)
RMS-JE-RE013	γ	Rail Car Bay Area/Auxiliary Bldg. Loading Bay (Note 4)	1.0E-1 to 1.0E+4 mR/hr
RMS-JE-RE014	γ	Liquid and Gaseous Radwaste Area	1.0E-1 to 1.0E+4 mR/hr
RMS-JE-RE016	γ	Control Support CSA Area	1.0E-1 to 1.0E+4 mR/hr
RMS-JE-RE017	γ	Radwaste Bldg. Mobile Systems Facility (Note 4)	1.0E-1 to 1.0E+4 mR/hr
RMS-JE-RE018	γ	Hot Machine Shop	1.0E-1 to 1.0E+4 mR/hr
RMS-JE-RE019	γ	Annex Staging & Storage Area	1.0E-1 to 1.0E+4 mR/hr
RMS-JE-RE020	γ	Fuel Handling Area	1.0E-1 to 1.0E+4 mR/hr (Note 2)

Notes:

1. Radiation levels are monitored by the permanent containment area radiation monitor and by a portable bridge monitor during refueling operations. The containment area radiation monitor is located to best measure the increase in exposure rates for this area and to provide an alarm locally and in the main control room.
2. Radiation levels are monitored by the permanent fuel handling area radiation monitors and by a portable bridge monitor during fuel handling operations. The fuel handling area radiation monitors are located to best measure the increase in exposure rates for this area and to provide an alarm locally and in the main control room.
3. Safety-related
4. Monitors areas used for storage of wet wastes (including processed and packaged spent resins) and dry wastes.

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region was operated at a specific power of 40.7 megawatts (thermal) per metric ton of uranium for 1561 effective full-power days.

Spent fuel gamma ray source strengths are presented in Table 12.2-14 for various times after shutdown. These source strengths may be put on a per-unit volume of homogenized core basis by multiplying by the power density (109.7 watts/cc).

Spent fuel neutron source strengths are given in Table 12.2-13 for various times after shutdown. The neutron source strengths may be put on a per-unit volume of homogenized core basis by multiplying them by the power density.

12.2.1.2.4 Irradiated Control Rods, Gray Rods, and Secondary Source Rods

The gamma ray source strengths of the irradiated control rods, gray rods, and secondary source rods are used in establishing radiation shielding requirements during refueling operations and during shipping of irradiated rods.

The absorber material used in the control rods is silver-indium-cadmium (Ag-In-Cd). The gray rods contain either type 304 stainless steel or Ag-In-Cd pellets in a stainless steel sleeve. The gamma ray source strengths associated with the irradiated Ag-In-Cd absorber are listed in Table 12.2-15 for various times after shutdown.

The photoneutron source material used in the secondary source rods is an equal volume mixture of antimony and beryllium (Sb-Be). The gamma ray source strengths associated with the secondary source rods are listed in Table 12.2-16 for various times after shutdown and Table 12.2-17 lists the neutron source strengths. The source values are per cubic centimeter of source material for an irradiation period of 400 days.

The material used for the control rod cladding, gray rod cladding and/or pellets and secondary source rod cladding is Type 304 stainless steel with an assumed maximum cobalt content of 0.12 weight percent. The gamma ray source strengths associated with the irradiated stainless steel are listed in Table 12.2-18 for various times after shutdown.

12.2.1.2.5 Incore Flux Thimbles

Irradiated incore flux thimble gamma ray source strengths are given in Table 12.2-19. These source strengths are used in determining shielding requirements during refueling operations when the flux thimbles are withdrawn from the reactor core.

12.2.1.3 Sources for the Core Melt Accident

The AP1000 is designed to provide adequate core cooling in the event of a postulated loss of coolant accident (LOCA) so that there is no significant core damage. Following a LOCA, the normal residual heat removal system could be used, if available, to provide post-accident cooling. Use of the normal residual heat removal system is acceptable only if the source term is close to the design basis source term (see Table 12.2-12).

NRC 086 |

Table 12.2-15			
IRRADIATED SILVER-INDIUM-CADMIUM CONTROL ROD SOURCE STRENGTHS			
Energy Group (Mev/gamma)	Source Strength at Time After Shutdown (Mev/cm ³ -sec)		
	1 Day	1 Week	1 Month
0.20 - 0.40	2.3E+08	2.3E+08	2.2E+08
0.40 - 0.90	1.1E+12	1.1E+12	1.0E+12
0.90 - 1.35	2.0E+11	1.9E+11	1.8E+11
1.35 - 1.80	3.7E+11	3.7E+11	3.4E+11
(Mev/gamma)	6 Months	1 Year	5 Years
0.20 - 0.40	1.4E+08	8.5E+07	1.5E+06
0.40 - 0.90	6.6E+11	4.0E+11	7.1E+09
0.90 - 1.35	1.2E+11	7.2E+10	1.3E+09
1.35 - 1.80	2.3E+11	1.4E+11	2.5E+09

Note:

NRC 086 | The absorber cross-sectional area is 0.1300-589 square centimeters per rod and the absorber material density is 10.2 grams per cubic centimeter.

Table 12.2-18

**IRRADIATED TYPE 304 STAINLESS STEEL SOURCE STRENGTHS
(0.12 WEIGHT PERCENT COBALT)**

Energy Group (Mev/gamma)	Source Strength at Time After Shutdown (Mev/cm ³ -sec)		
	1 Day	1 Week	1 Month
0.20 - 0.40	7.1E+09	6.1E+09	3.4E+09
0.40 - 0.90	3.1E+10	2.9E+10	2.6 E+10
0.90 - 1.35	2.4E+11	2.3E+11	2.3E+11
1.35 - 1.80	1.9E+08	1.8E+08	1.4E+08
(Mev/gamma)	6 Months	1 Year	5 Years
0.20 - 0.40	8.3E+07	9.9E+05	0
0.40 - 0.90	1.2E+10	6.4E+09	2.3E+08
0.90 - 1.35	2.1E+11	2.0E+11	1.2E+11
1.35 - 1.80	3.3E+07	5.4E+06	0

Notes:

The various cross-section areas per rod are as follows:

- Ag-In-Cd control rod cladding - 0.136 cm²
- Sb-Be secondary source rod cladding - 0.136 cm²
- Gray rod cladding - 0.136 cm²
- Gray rod sleeve/pellet - 0.606589 cm²

Chapter 13

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NRC 128 |

- Maintenance, inspection, test and surveillance
- Administrative
- Operation of post-72 hour equipment

13.6 Security

NRC 128

NRC 128

The Security Plan consists of the “AP1000 Physical Security Plan,” ~~(Reference 5)~~, Training and Qualification Plan, and Safeguards Contingency Plan. The Security Plan will be submitted to the Nuclear Regulatory Commission as a separate licensing document in order to fulfill the requirements for 10 CFR 52.79(35) and 10 CFR 52.79(36) ~~0.34~~. The Security Plan will meet the requirements of 10 CFR 52.98(c) ~~0.54~~. The plan is classified as Security Safeguards Information and is withheld from public disclosure pursuant to 10 CFR 73.21. Additionally, the “AP1000 Interim Compensatory Measures Report” (Reference 2), the “AP1000 Enhancement Report” (Reference 3), and the “AP1000 Safeguards Assessment Report” (Reference 4) are submitted to the Nuclear Regulatory Commission as separate licensing documents to establish the design of the AP1000 Security Systems. Each document is classified as Security Safeguards information and is withheld from public disclosure pursuant to 10 CFR 73.21.

13.6.1 Combined License Information Item

NRC 128

Combined license applicants referencing the AP1000 certified design will address site-specific information related to the security, contingency, and guards training plans. The combined license applicant will develop the Physical Security Plan, Training and Qualification Plan, and the Safeguards Contingency Plan.

13.7 References

NRC 128

1. Not Used.
2. APP-GW-GLR-067, “AP1000 Interim Compensatory Measures Report,” Westinghouse Electric Company LLC.
3. APP-GW-GLR-062, “AP1000 Enhancement Report,” Westinghouse Electric Company LLC.
4. APP-GW-GLR-066, “AP1000 Safeguards Report,” Westinghouse Electric Company LLC.
5. Not Used.
6. Not Used.
7. WCAP-13864, “Rod Control System Evaluation Program,” Revision 1-A, November 1994.
8. USNRC Generic Letter GL-96-01, “Testing of Safety-Related Logic Circuits,” January 10, 1996.
9. Not Used.

Chapter 14

NRC 123
NRC 050

- Provide heating, ventilation, and cooling for the main control room, control support area~~technical support center~~, and Class 1E electrical equipment rooms

NRC 123
NRC 050

- Provide air filtration to limit radioactivity in the main control room and control support area~~technical support center~~

- Maintain passive heat sinks at acceptably low initial temperatures

NRC 123
NRC 050

- Maintain the main control room and control support area~~technical support center~~ at positive pressure

The safety-related functions associated with this system are tested as part of the main control room emergency habitability testing described in subsection 14.2.9.1.6.

Prerequisites

The construction testing of the nuclear island nonradioactive ventilation system has been completed. The required preoperational testing of central chilled water system, the hot water heating system, the ac electrical power and distribution systems, and other interfacing systems required for operation of the above systems has been completed. Data collection is available as needed to support the specified testing and system configurations.

General Test Acceptance Criteria and Methods

Nuclear island nonradioactive ventilation system performance is observed and recorded during a series of individual component and integrated system testing to verify the system performs its defense-in-depth functions. The following testing demonstrates that the system performs its defense-in-depth functions as described in subsection 9.4.1 and appropriate design specifications:

- Proper function of the fans, filters, heaters, coolers, and dampers is verified.
- Proper operation of instrumentation, controls, actuation signals, and alarms and interlocks is verified. This testing includes the following:
 - Smoke detectors and alarms
 - Air handling unit and fan flows, controls, and alarms
 - Differential air pressures and alarms
 - Air and air filtration unit charcoal temperatures, controls, and alarms
 - Air relative humidity measurements, controls, and alarms
 - Isolation/shutoff damper controls
 - Fire/smoke damper controls

This testing includes operation from the main control room.

- The proper air flows from and through each air handling unit, as well as to and from the main control room, control support area, and other equipment rooms is established for each mode of operation.

Table 14.3-2 (Sheet 9 of 17)

DESIGN BASIS ACCIDENT ANALYSIS

Reference	Design Feature	Value
Section 7.3.1.2.4	The second and third stage valves open on time delays following generation of the first stage actuation signal via the protection and safety monitoring system.	
Section 7.3.1.2.5	The reactor coolant pumps are tripped upon generation of a safeguards actuation signal or upon generation of a low-2 pressurizer water level signal.	
Section 7.3.1.2.7	The passive residual heat removal heat exchanger control valves are opened on low steam generator water level or on a CMT actuation signal via the protection and safety monitoring system.	
Section 7.3.1.2.9	The containment recirculation isolation valves are opened on a safeguards actuation signal in coincidence with low-3 in-containment refueling water storage tank water level via the protection and safety monitoring system.	
Section 7.3.1.2.14	The demineralized water system isolation valves close on a signal from the protection and safety monitoring system derived from either a reactor trip signal, a source range flux doubling signal, or low input voltage to the 1E dc and uninterruptible power supply battery chargers.	
Section 7.3.1.2.15	The chemical and volume control system makeup line isolation valves automatically close on a signal from the protection and monitoring system derived from either a source range flux doubling high-2 pressurizer level, high-2 steam generator level signal, a safeguards signal coincident with high-1 pressurizer level, or high-2 containment radioactivity.	
Section 7.3.2.2.1	The protection and monitoring system automatically generate an actuation signal for an engineered safety feature whenever a monitored condition reaches a preset level.	
Section 7.3.2.2.9	Manual initiation at the system-level exists for the engineered safety features actuation.	
Section 7.4.3.1	If temporary evacuation of the main control room is required because of some abnormal main control room condition, the operators can establish and maintain safe shutdown conditions for the plant from outside the main control room through the use of controls and monitoring located at the remote shutdown workstation.	

NRC 158

NRC 158

Table 14.3-2 (Sheet 11 of 17)

DESIGN BASIS ACCIDENT ANALYSIS

Reference	Design Feature	Value
Section 9.1.4.1.1	In the event of a safe shutdown earthquake (SSE), handling equipment cannot fail in such a manner as to prevent required function of seismic Category 1 equipment.	
Section 9.3.6.3.7	The chemical and volume control system contains two redundant safety-related valves to isolate the demineralized water system from the makeup pump suction.	
Section 9.3.6.3.7	The chemical and volume control system contains two safety-related valves to isolate the makeup flow to the reactor coolant system.	
Section 9.3.6.4.5	The chemical and volume control system contains two safety-related valves to isolate the makeup flow to the reactor coolant system.	
Section 9.3.6.4.5.1	The chemical and volume control system contains two redundant safety-related valves to isolate the demineralized water system from the makeup pump suction.	
Section 9.3.6.7	The demineralized water system isolation valves close on a signal from the protection and safety monitoring system derived from either a reactor trip signal, a source range flux doubling signal, low input voltage to the 1E dc and uninterruptible power supply battery chargers, or a safety injection signal.	
Section 9.3.6.7	The chemical and volume control system makeup line isolation valves automatically close on a signal from the protection and safety monitoring system derived from either a source range flux doubling , high-2 pressurizer level, high steam generator level signal, or a safeguards signal coincident with high-1 pressurizer level.	
Section 10.1.2	Safety valves are provided on both main steam lines.	
Section 10.2.2.4.3	The flow of the main steam entering the high-pressure turbine is controlled by four stop valves and four governing control valves. The stop valves are closed by actuation of the emergency trip system devices.	
Section 10.3.1.1	The main steam supply system is provided with a main steam isolation valve and associated MSIV bypass valve on each main steam line from its respective steam generator.	
Section 10.3.1.1	A main steam isolation valve (MSIV) on each main steam line prevents the uncontrolled blowdown of more than one steam generator and isolates nonsafety-related portions of the system.	

NRC 158

Table 14.3-3

ANTICIPATED TRANSIENT WITHOUT SCRAM

Reference	Design Feature	Value
Section 7.7.1.11	The diverse actuation system is a nonsafety-related system that provides a diverse backup to the protection and safety monitoring system.	
Section 7.7.1.11	The diverse actuation system trips the reactor control rods and the turbine on low wide range steam generator water level and on low pressurizer water level.	
Section 7.7.1.11	The diverse actuation system initiates passive residual heat removal on low wide range steam generator water level or high hot leg temperature; actuates core makeup tanks and trips the reactor coolant pumps on low pressurizer water level; and isolates selected containment penetrations and starts passive containment cooling on high containment temperature.	
Section 7.7.1.11	The manual actuation function of the diverse actuation system is implemented by wiring the controls located in the main control room directly to the final loads in a way that bypasses the normal path through the control room multiplexers, the protection and safety monitoring system cabinets, and the diverse actuation system logic.	
Section 7.7.1.11	The diverse actuation system uses a microprocessor <u>or special purpose logic processor</u> board different from those used in the protection and safety monitoring system.	
Section 7.7.1.11	The diverse actuation system hardware implementation is different from that of the protection and safety monitoring system.	
Section 7.7.1.11	The operating system and programming language of the diverse actuation system is different from that of the protection and safety monitoring system.	

NRC 096

Table 14.3-6 (Sheet 7 of 10)

PROBABILISTIC RISK ASSESSMENT

Reference		Design Feature	Value
Figure	7.2-1 (Sheets 16 and 20)	The squib valves and MOVs for reactor cavity flooding are manually actuated via PMS and DAS from the control room.	
Section	7.3.1.2.7 7.7.1.11	The PRHR air-operated valves are automatically actuated and manually actuated from the control room by either PMS or DAS.	
Section	7.3.1.2.20	The RNS containment isolation MOVs are actuated via PMS.	
Section	7.5.4	PMS has two divisions of safety-related post-accident parameter display.	
Section	7.6.1.1	An interlock is provided for the normally closed motor-operated normal residual heat removal system inner and outer suction isolation valves. Each valve is interlocked so that it cannot be opened unless the reactor coolant system pressure is below a preset pressure.	
Section	7.7.1.11	The diverse actuation system is a nonsafety-related system that provides a diverse backup to the protection and safety monitoring system.	
Section	7.7.1.11	The diverse actuation system trips the reactor control rods and the turbine on low wide range steam generator water level and on low pressurizer water level.	
Section	7.7.1.11	DAS manual initiation functions are implemented in a manner that bypasses the signal processing equipment of the DAS.	
Section	7.7.1.11	The DAS automatic actuation signals are generated in a functionally diverse manner from the PMS signals. Diversity between DAS and PMS is achieved by the use of different architecture, different hardware implementations, and <u>any</u> different software.	
Section	8.3.1.1.1	On loss of power to a 6900V diesel-backed bus, the associated diesel generator automatically starts and produces ac power. The source circuit breakers and bus load circuit breakers are opened, and the generator is connected to the bus. Each generator has an automatic load sequencer to enable controlled loading on the associated buses.	

NRC 096

Table 14.3-7 (Sheet 1 of 3)

RADIOLOGICAL ANALYSIS

Reference	Design Feature	Value
Table 2-1	Plant elevation for maximum flood level (ft)	≤ 100
Section 2.3.4	Atmospheric dispersion factors - X/Q (sec/m ³) <ul style="list-style-type: none"> - Site Boundary X/Q 0 - 2 hour time interval - Low Population Zone Boundary X/Q 0 - 8 hours 8 - 24 hours 24 - 96 hours 96 - 720 hours 	$\leq 5.1 \times 10^{-34}$ $\leq 52.2 \times 10^{-4}$ $\leq 34.6 \times 10^{-4}$ $\leq 1.50 \times 10^{-45}$ $\leq 8.0 \times 10^{-5}$
Table 6.2.3-1	Containment penetration isolation features are configured as in Table 6.2.3-1	
Table 6.2.3-1	Maximum closure time for remotely operated containment purge valves (seconds)	≤ 10
Table 6.2.3-1	Maximum closure time for all other remotely operated containment isolation valves (seconds)	≤ 60
Section 6.4.2.3	The minimum storage capacity of all storage tanks in the VES (scf)	$\geq 314,132$
Section 6.4.3.2	The maximum temperature rise in the main control room pressure boundary following a loss on the nuclear island nonradioactive ventilation system over a 72-hour period (°F)	+ 10.8
Section 6.4.4	The maximum temperature in the instrumentation and control rooms and dc equipment rooms following a loss of the nuclear island nonradioactive ventilation system remains over a 72-hour period (°F).	≤ 120
Section 6.4.4	The main control emergency habitability system nominally provides 65 scfm of ventilation air to the main control room from the compressed air storage tanks.	65 ± 5
Section 6.4.4	Sixty-five \pm five scfm of ventilation flow is sufficient to pressurize the control room to 1/8 th inch water gauge differential pressure (WIC).	1/8 th
Figure 6.4-2	The main control room emergency habitability system consists of two sets of emergency air storage tanks and an air delivery system to the main control room.	
Section 6.5.3	The passive heat removal process and the limited leakage from the containment result in offsite doses less than the regulatory guideline limits.	

NRC 098

NRC 098

14.4 Combined License Applicant Responsibilities

This section describes the Combined License applicant's and holder's responsibilities required to perform the AP1000 plant initial test program.

14.4.1 Organization and Staffing

The specific staff, staff responsibilities, authorities, and personnel qualifications for performing the AP1000 initial test program are the responsibility of the Combined License applicant. This test organization is responsible for the planning, executing, and documenting of the plant initial testing and related activities that occur between the completion of plant/system/component construction and commencement of plant commercial operation. Transfer and retention of experience and knowledge gained during initial testing for the subsequent commercial operation of the plant is an objective of the test program.

14.4.2 Test Specifications and Procedures

The Combined License information requested in this subsection has been partially addressed in APP-GW-GLR-037 (Reference 1), and the applicable changes are incorporated into the DCD. Test Specifications have been developed as indicated in Reference 1 and are available for NRC onsite review at Westinghouse's offices.

The Combined License holder will provide the Preoperational and Startup Procedures for the NRC prior to each planned test in accordance with the requirements of DCD subsection 14.2.3.

The following words represent the original Combined License Information Item commitment:

The Combined License applicant is responsible for providing test specifications and test procedures for the preoperational and startup tests, as identified in subsection 14.2.3, for review by the NRC.

14.4.3 Conduct of Test Program

NRC 029 |

The Combined License information requested in this subsection has been addressed in APP-GW-GLR-038, Revision 1 (Reference 2), and the applicable changes are incorporated into the DCD. No additional work is required by the Combined License applicant to address the Combined License information requested in this subsection as delineated in the following paragraph:

NRC 029 |

The program management description for the process to develop the AP1000 Startup Administrative Manual is delineated in APP-GW-GLR-038, Revision 1 (Reference 2). There are no residual open items for COL applicants related to this COL Information item.

Chapter 15

Table 15.0-4a (Sheet 1 of 2)

**PROTECTION AND SAFETY MONITORING SYSTEM
SETPOINTS AND TIME DELAY ASSUMED IN ACCIDENT ANALYSES**

Function	Limiting Setpoint Assumed in Analyses	Time Delays (seconds)
Reactor trip on power range high neutron flux, high setting	118%	0.9
Reactor trip on power range high neutron flux, low setting	35%	0.9
High neutron flux, P-8	84%	0.9
Reactor trip on source range neutron flux reactor trip	Not applicable	0.9
Overtemperature ΔT	Variable (see Figure 15.0.3-1)	2.0
Overpower ΔT	Variable (see Figure 15.0.3-1)	2.0
Reactor trip on high pressurizer pressure	2460 psia	2.0
Reactor trip on low pressurizer pressure	1800 psia	2.0
Reactor trip on low reactor coolant flow in either hot leg	87% loop flow	1.45
Reactor trip on reactor coolant pump under speed	90%	0.767
Reactor trip on low steam generator narrow range level	95,000 lbm	2.0
High-2 steam generator level	100% of narrow range level span	2.0 (reactor trip) 0.0 (turbine trip) 2.0 (feedwater isolation)
Reactor trip on high-3 pressurizer water level	76% of span	2.0
PRHR actuation on low steam generator wide range level	55,000 lbm	2.0
"S" signal and steamline isolation on low T_{cold}	500°F	2.0
"S" signal and steamline isolation on low steamline pressure	405 psia (with an adverse environment assumed) 535 psia (without an adverse environment assumed)	2.0
"S" signal on low pressurizer pressure	1700 psia	2.0

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Table 15.0-6 (Sheet 3 of 4)

**PLANT SYSTEMS AND EQUIPMENT
AVAILABLE FOR TRANSIENT AND ACCIDENT CONDITIONS**

Incident	Reactor Trip Functions	ESF Actuation Functions	ESF and Other Equipment
<i>Section 15.4 (Cont.)</i>			
Uncontrolled RCCA bank withdrawal at power	Power range high neutron flux, high power range positive neutron flux rate, overtemperature ΔT , over-power ΔT , high pressurizer pressure, high pressurizer water level, manual	—	Pressurizer safety valves, steam generator safety valves
RCCA misalignment	Overtemperature ΔT , manual	—	—
Startup of an inactive reactor coolant pump at an incorrect temperature	Power range high flux, low flow (P-108 interlock), manual	—	—
Chemical and volume control system malfunction that results in a decrease in boron concentration in the reactor coolant	Source range high flux, overtemperature ΔT , manual	Source range flux doubling	CVS to RCS isolation valves, makeup pump suction isolation valves, from the demineralized water transfer and storage system
Spectrum of RCCA ejection accidents	Power range high flux, high positive flux rate, manual	—	Pressurizer safety valves
<i>Section 15.5</i>			
Increase in reactor coolant inventory			
Inadvertent operation of the ECCS during power operation	High pressurizer pressure, manual, “safeguards” trip, high pressurizer level	High pressurizer level, low T_{cold}	Core makeup tank, pressurizer safety valves, chemical and volume control system isolation, PRHR
Chemical and volume control system malfunction that increases reactor coolant inventory	High pressurizer pressure, “safeguards” trip, high pressurizer level, manual	High pressurizer level, low T_{cold}	Core makeup tank, pressurizer safety valves, chemical and volume control system isolation, PRHR

NRC 155 |

15A.3.3 Atmospheric Dispersion Factors

Subsection 2.3.4 lists the off-site short-term atmospheric dispersion factors (χ/Q) for the reference site. Table 15A-5 (Sheet 1 of 2) reiterates these χ/Q values.

The atmospheric dispersion factors (χ/Q) to be applied to air entering the main control room following a design basis accident are specified at the HVAC intake and at the annex building entrance (which would be the air pathway to the main control room due to ingress/egress). A set of χ/Q values is identified for each potential activity release location that has been identified and the two control room receptor locations. ~~The χ/Q values have been selected in concert with the design basis accident radiological consequences analyses to obtain limiting values. In this manner, the maximum acceptable χ/Q values consistent with meeting dose acceptance criteria have been obtained.~~ These χ/Q values are listed in Table 15A-6 and are provided in Table 2-1 (Sheet 3 of 3).

~~Subsections 2.3.6.4 and 2.3.6.5 contain information related to diffusion.~~ The site-specific control room χ/Q values shall be bounded by the values in Table 15A-6. For a site selected that has χ/Q values that exceed the values in Table 15A-6, how the radiological consequences associated with the controlling design basis accident continue to meet the control room operator dose limits given in General Design Criteria 19 using site-specific χ/Q values should be addressed. Topographical characteristics in the vicinity of the site for restrictions of horizontal and/or vertical plume spread, channeling or other changes in airflow trajectories, and other unusual conditions affecting atmospheric transport and diffusion between the source and the receptors should be considered. No further action is required for sites within the bounds of the site parameters for atmospheric dispersion.

Table 15A-7 identifies the AP1000 source and receptor data ~~to that can~~ be used when determining the site-specific control room χ/Q values using the ARCON96 code (References 4 and 5).

The main control room χ/Q values do not incorporate occupancy factors.

The locations of the potential release points and their relationship to the main control room air intake and the annex building access door are shown in Figure 15A-1.

15A.4 References

1. Murphy, K. G., Campe, K. M., "Nuclear Power Plant Control Room Ventilation System Design for Meeting General Criterion 19," paper presented at the 13th AEC Air Cleaning Conference.
2. EPA Federal Guidance Report No. 11, "Limiting Values of Radionuclide Intake and Air Concentration and Dose Conversion Factors for Inhalation, Submersion, and Ingestion," EPA-520/1-88-020, September 1988.
3. EPA Federal Guidance Report No. 12, "External Exposure to Radionuclides in Air, Water, and Soil," EPA 402-R-93-081, September 1993.
4. NUREG/CR-6331, Ramsdell, J. V. and Simonen, C. A., "Atmospheric Relative Concentrations in Building Wakes," Revision 1, May 1997.

Chapter 16

Table 3.3.1-1 (page 1 of 5)
Reactor Trip System Instrumentation

FUNCTION	APPLICABLE MODES OR OTHER SPECIFIED CONDITIONS	REQUIRED CHANNELS	CONDITIONS	SURVEILLANCE REQUIREMENTS	ALLOWABLE VALUE	TRIP SETPOINT
1. Manual Reactor Trip	1,2	2	B	SR 3.3.1.10	NA	NA
	3 ^(a) ,4 ^(a) ,5 ^(a)	2	C	SR 3.3.1.10	NA	NA
2. Power Range Neutron Flux						
a. High Setpoint	1,2	4	D	SR 3.3.1.1 SR 3.3.1.2 SR 3.3.1.6 SR 3.3.1.9 SR 3.3.1.11	≤ 109.06% RTP	109% RTP
b. Low Setpoint	1 ^(b) ,2	4	E	SR 3.3.1.1 SR 3.3.1.7 SR 3.3.1.9 SR 3.3.1.11	≤ 25.06% RTP	25% RTP
3. Power Range Neutron Flux High Positive Rate	1,2	4	E	SR 3.3.1.6 SR 3.3.1.9 SR 3.3.1.11	≤ 5.06% RTP with time constant ≥ 2 sec	5.0% RTP with time constant ≥ 2 sec
4. Intermediate Range Neutron Flux	1 ^(b) ,2 ^(c)	4	F,G	SR 3.3.1.1 SR 3.3.1.7 SR 3.3.1.9 SR 3.3.1.11	≤ 25.23% RTP	25% RTP
	2 ^(d)	4	H	SR 3.3.1.1 SR 3.3.1.7 SR 3.3.1.9 SR 3.3.1.11	≤ 25.23% RTP	25% RTP
5. Source Range Neutron Flux High Setpoint	2 ^(d)	4	I,J	SR 3.3.1.1 SR 3.3.1.7 SR 3.3.1.9 SR 3.3.1.11	≤ 1.01 E5 cps	1.0 E5 cps
	3 ^(a) ,4 ^(a) ,5 ^(a)	4	J,R	SR 3.3.1.1 SR 3.3.1.6 SR 3.3.1.9 SR 3.3.1.11	≤ 1.01 E5 cps	1.0 E5 cps
	3 ^(e) ,4 ^(e) ,5 ^(e)	1	S	SR 3.3.1.1 SR 3.3.1.9	NA	NA

(a) With Reactor Trip Breakers (RTBs) closed and Plant Control System capable of rod withdrawal.

(b) Below the P-10 (Power Range Neutron Flux) interlocks.

(c) Above the P-6 (Intermediate Range Neutron Flux) interlocks.

(d) Below the P-6 (Intermediate Range Neutron Flux) interlocks.

(e) With RTBs open. In this condition, Source Range Function does not provide reactor trip but does provide indication.

NRC 085 | [Reviewer Note: In all cases, the values specified for trip setpoints and allowable values must be confirmed following completion of the plant-specific setpoint study. Upon selection of the plant specific instrumentation, the Trip Setpoints will be calculated in accordance with the setpoint methodology described in WCAP-16361-P. Allowable Values will be calculated in accordance with the setpoint methodology and specified in the Allowable Value column. The plant specific setpoint calculations will reflect the latest licensing analysis/design basis and may incorporate NRC accepted improvements in setpoint methodology.

Table 3.3.1-1 (page 2 of 5)
Reactor Trip System Instrumentation

	FUNCTION	APPLICABLE MODES OR OTHER SPECIFIED CONDITIONS	REQUIRED CHANNELS	CONDITIONS	SURVEILLANCE REQUIREMENTS	ALLOWABLE VALUE	TRIP SETPOINT
NRC 173	6. Overtemperature ΔT	1,2	4	E	SR 3.3.1.1	Refer to Note 1 <u>Table 3.3.1-1</u> (Page 5 of 5) (Page 3.3.1-17)	Refer to Note 1 <u>Table 3.3.1-1</u> (Page 5 of 5) (Page 3.3.1-17)
					SR 3.3.1.3		
					SR 3.3.1.4		
					SR 3.3.1.6		
					SR 3.3.1.8		
NRC 173	7. Overpower ΔT	1,2	4	E	SR 3.3.1.1	Refer to Note 2 <u>Table 3.3.1-1</u> (Page 5 of 5) (Page 3.3.1-17)	Refer to Note 2 <u>Table 3.3.1-1</u> (Page 5 of 5) (Page 3.3.1-17)
					SR 3.3.1.6		
					SR 3.3.1.8		
					SR 3.3.1.11		
					SR 3.3.1.11		
	8. Pressurizer Pressure	1 ^(f)	4	K	SR 3.3.1.1	≥ 1809.9 psig	1810.3 psig
					SR 3.3.1.6		
	a. Low Setpoint				SR 3.3.1.8		
					SR 3.3.1.11		
	b. High Setpoint	1,2	4	E	SR 3.3.1.1	≤ 2420.7 psig	2420.3 psig
					SR 3.3.1.6		
					SR 3.3.1.8		
					SR 3.3.1.11		
	9. Pressurizer Water Level – High 3	1 ^(f)	4	K	SR 3.3.1.1	$\leq 71.05\%$	71%
					SR 3.3.1.6		
					SR 3.3.1.8		
					SR 3.3.1.11		
	10. Reactor Coolant Flow – Low	1 ^(f)	4 per hot leg	L	SR 3.3.1.1	$\geq 89.96\%$ ⁽ⁱ⁾	90% ⁽ⁱ⁾
					SR 3.3.1.6		
					SR 3.3.1.8		
					SR 3.3.1.11		
	11. Reactor Coolant Pump (RCP) Bearing Water Temperature – High	1 ^(f)	4 per RCP	L	SR 3.3.1.1	$\leq 230.4^{\circ}\text{F}$	230 $^{\circ}\text{F}$
					SR 3.3.1.6		
					SR 3.3.1.8		
					SR 3.3.1.11		
	12. RCP Speed – Low	1 ^(f)	4	K	SR 3.3.1.1	$\geq 90.9\%$	91%
					SR 3.3.1.6		
					SR 3.3.1.8		
					SR 3.3.1.11		
	13. Steam Generator (SG) Narrow Range Water Level – Low	1,2	4 per SG	E	SR 3.3.1.1	$\geq 20.95\%$ span	21% span
					SR 3.3.1.6		
					SR 3.3.1.8		
					SR 3.3.1.11		

(f) Above the P-10 (Power Range Neutron Flux) interlock.

(i) 90% of loop specific indicated flow.

Table 3.3.2-1 (page 10 of 13)
Engineered Safeguards Actuation System Instrumentation

		APPLICABLE MODES OR OTHER SPECIFIED CONDITIONS	REQUIRED CHANNELS	CONDITIONS	SURVEILLANCE REQUIREMENTS	ALLOWABLE VALUE	TRIP SETPOINT
NRC 101	17. Normal Residual Heat Removal System Isolation						
	a. Containment Radioactivity – High 2	1,2,3 ^(m)	4	B,Q	SR 3.3.2.1 SR 3.3.2.4 SR 3.3.2.5 SR 3.3.2.6	≤ 150 R/hr	100 R/hr
	b. Safeguards Actuation	1,2,3 ^(m)	Refer to Function 1 (Safeguards Actuation) for all initiating functions and requirements.				
	c. Manual Initiation	1,2,3 ^(m)	2 switch sets	E,Q	SR 3.3.2.3	NA	NA
	18. ESFAS Interlocks						
	a. Reactor Trip, P-4	1,2,3	3 divisions	D,M	SR 3.3.2.3	NA	NA
	b. Pressurizer Pressure, P-11	1,2,3	4	J,M	SR 3.3.2.1 SR 3.3.2.4 SR 3.3.2.5 SR 3.3.2.6	≤ 1970.4 psig	1970 psig
	c. Intermediate Range Neutron Flux, P-6	2	4	J,L	SR 3.3.2.1 SR 3.3.2.4 SR 3.3.2.5 SR 3.3.2.6	≥ 9.91 E-6% RTP	1E-5% RTP
	d. Pressurizer Level, P-12	1,2,3,4,5,6	4	J,M BB,Y	SR 3.3.2.1 SR 3.3.2.4 SR 3.3.2.5 SR 3.3.2.6	≤ 16.05% span	16% span
	e. RCS Pressure, P-19	1,2,3,4 ^(j)	4	J,N	SR 3.3.2.1 SR 3.3.2.4 SR 3.3.2.5 SR 3.3.2.6	≥ 702 psig	700 psig
	19. Containment Air Filtration System Isolation						
	a. Containment Radioactivity – High 1	1,2,3,4 ^(j)	4	B,Z	SR 3.3.2.1 SR 3.3.2.4 SR 3.3.2.5 SR 3.3.2.6	≤ 3 R/hr	2 R/hr
	b. Containment Isolation	Refer to Function 3 (Containment Isolation) for initiating functions and requirements.					

(j) With the RCS not being cooled by the Normal Residual Heat Removal System (RNS).

(m) Not applicable for valve isolation Functions whose associated flow path is isolated.

SURVEILLANCE REQUIREMENTS (continued)

SURVEILLANCE	FREQUENCY
<div data-bbox="40 415 168 464" data-label="Text">NRC 101 </div> <div data-bbox="203 348 354 380">SR 3.8.1.2</div> <div data-bbox="440 348 1143 449" data-label="Text"> <p>Verify each battery charger supplies ≥ 400 amps at greater than or equal to the minimum established float voltage for $\geq [8]$ hours.</p> </div> <div data-bbox="440 483 488 514"><u>OR</u></div> <div data-bbox="440 548 1127 747" data-label="Text"> <p>Verify each battery charger can recharge the battery to the fully charged state within 24 hours while supplying the largest combined demands of the various continuous steady state loads, after a battery discharge to the bounding design basis event discharge state.</p> </div>	24 months
<div data-bbox="203 783 354 814">SR 3.8.1.3</div> <div data-bbox="440 783 1127 814">-----</div> <div data-bbox="719 825 860 852">- NOTES -</div> <div data-bbox="440 863 1127 1255" data-label="List-Group"> <ol style="list-style-type: none"> 1. The modified performance discharge test in SR 3.8.7.6 may be performed in lieu of SR 3.8.1.3. 2. This Surveillance shall not normally be performed in MODE 1, 2, 3, or 4 unless the spare battery is connected to replace the battery being tested. However, portions of the Surveillance may be performed to reestablish OPERABILITY provided an assessment determines the safety of the plant is maintained or enhanced. </div> <div data-bbox="440 1266 1127 1297">-----</div> <div data-bbox="440 1318 1073 1446" data-label="Text"> <p>Verify battery capacity is adequate to supply, and maintain in OPERABLE status, the required emergency loads for the design duty cycle when subjected to a battery service test.</p> </div>	24 months

4.0 DESIGN FEATURES

4.3 Fuel Storage

4.3.1 Criticality

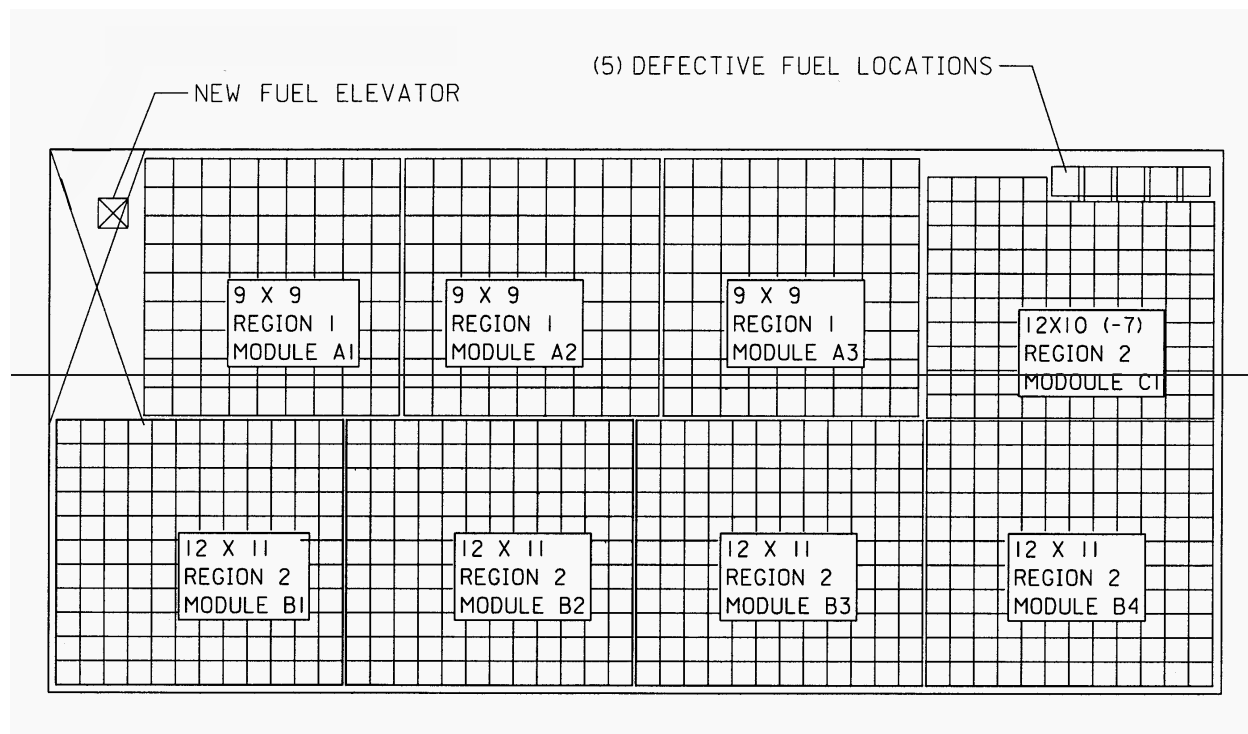
4.3.1.1 The spent fuel storage racks are designed and shall be maintained with:

- a. Fuel assemblies having a maximum U-235 enrichment of 5.0 weight percent.
- b. $k_{\text{eff}} \leq 0.95$ if fully flooded with unborated water which includes an allowance for uncertainties as described in Section 9.1, "Fuel Storage and Handling."
- c. A nominal 10.90 inch center-to-center distance between fuel assemblies placed in Region 1, a nominal 9.028 inch center-to-center distance between fuel assemblies placed in Region 2 of the spent fuel storage racks, and a nominal 11.62 inch center-to-center distance between fuel assemblies placed in the Defective Fuel Cells.
- d. New or partially spent fuel assemblies with any discharge burnup may be allowed unrestricted storage in Region 1 and the Defective Fuel Cells of Figure 4.3-1;
- e. Partially spent fuel assemblies meeting the initial enrichment, burnup, and decay time requirements of LCO 3.7.12, "Spent Fuel Pool Storage," may be stored in Region 2 of Figure 4.3-1, and
- f. New and spent fuel assemblies meeting the Figure 4.3-2 location-specific initial enrichment, burnup, and decay time requirements of LCO 3.7.12, "Spent Fuel Pool Storage," may be stored in specified Region 2 locations.

4.3.1.2 The new fuel storage racks are designed and shall be maintained with:

- a. Fuel assemblies having a maximum U-235 enrichment of 5.0 weight percent.
- b. $k_{\text{eff}} \leq 0.95$ if fully flooded with unborated water which includes an allowance for uncertainties as described in Section 9.1, "Fuel Storage and Handling."
- c. $k_{\text{eff}} \leq 0.98$ if moderated by aqueous foam which includes an allowance for uncertainties as described in Section 9.1, "Fuel Storage and Handling."
- d. A nominal 10.90 inch center-to-center distance between fuel assemblies placed in the new fuel storage racks.

NRC 100 |



Region 1 (A1, A2, A3) — 243 locations

Region 2 (B1, B2, B3, B4, C1) — 641 locations

Defective Fuel Cells (DFCs) — 5 locations

Total Storage Locations — 889

NRC 100

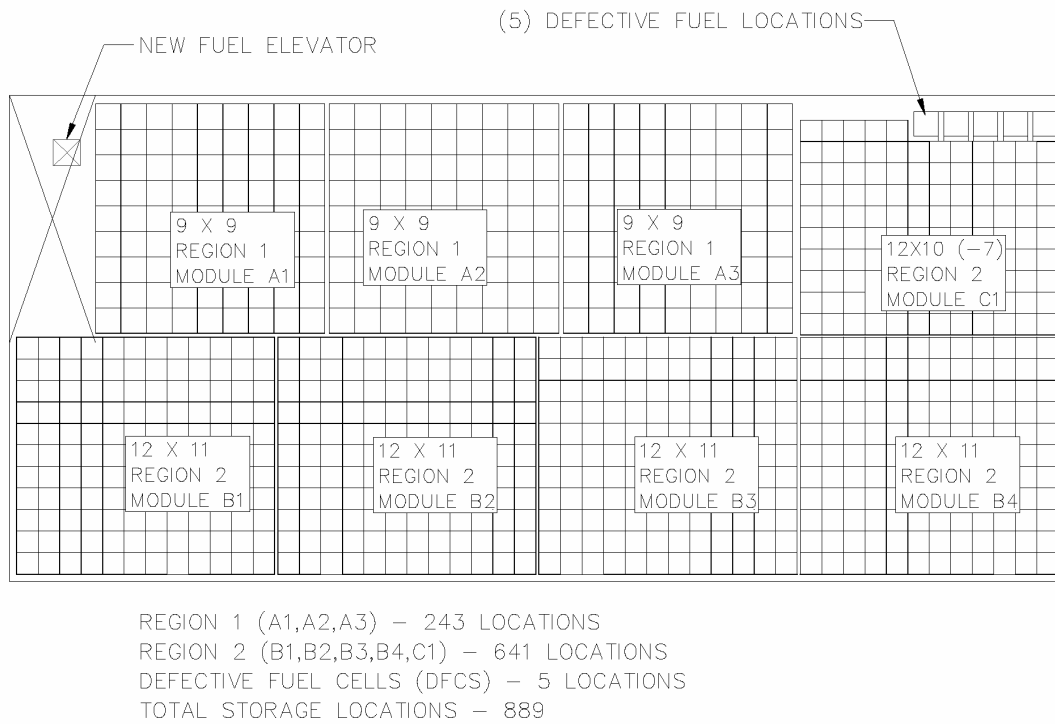


Figure 4.3-1

Discrete Two Region Spent Fuel Pool Rack Layout

5.0 ADMINISTRATIVE CONTROLS

5.3 Unit Staff Qualifications

<div><div></div><div>- REVIEWER'S NOTE -</div><div>[Minimum qualifications for members of the unit staff shall be specified by use of an overall qualification statement referencing an ANSI Standard acceptable to the NRC staff or by specifying individual position qualifications. Generally, the first method is preferable; however, the second method is adaptable to those unit staffs requiring special qualification statements because of unique organizational structures.]</div></div>	
NRC 119	<div><div>5.3.1</div><div>Each member of the unit staff shall meet or exceed the minimum qualifications of [Regulatory Guide 1.8, Revision 2, 1987, or more recent revisions, or ANSI Standards acceptable to the NRC staff]. [The staff not covered by {Regulatory Guide 1.8} shall meet or exceed the minimum qualifications of {Regulations, Regulatory Guides, or ANSI Standards acceptable to NRC staff}.</div></div> <div><div>5.3.2</div><div>For the purpose of 10 CFR 55.4, a licensed Senior Reactor Operator (SRO) and a licensed reactor operator (RO) are those individuals who, in addition to meeting the requirements of TS 5.3.1, perform the functions described in 10 CFR 50.54(m).</div></div>

5.0 ADMINISTRATIVE CONTROLS

5.5 Programs and Manuals

The following programs shall be established, implemented, and maintained.

5.5.1 Offsite Dose Calculation Manual (ODCM)

- a. The ODCM shall contain the methodology and parameters used in the calculation of offsite doses resulting from radioactive gaseous and liquid effluents, in the calculation of gaseous and liquid effluent monitoring alarm and trip setpoints, and in the conduct of the radiological environmental monitoring program; and
- b. The ODCM shall also contain the radioactive effluent controls and radiological environmental monitoring activities, and descriptions of the information that should be included in the Annual Radiological Environmental Operating, and Radioactive Effluent Release Reports required by Specification 5.6.2 and Specification 5.6.3.

Licensee initiated changes to the ODCM:

- a. Shall be documented and records of reviews performed shall be retained. This documentation shall contain:
 - 1. Sufficient information to support the change(s) together with the appropriate analyses or evaluations justifying the change(s), and
 - 2. A determination that the change(s) maintain the levels of radioactive effluent control required by 10 CFR 20.1302-106, 40 CFR 190, 10 CFR 50.36a, and 10 CFR 50, Appendix I, and not adversely impact the accuracy or reliability of effluent, dose, or setpoint calculations;
- b. Shall become effective after the approval of the plant manager; and
- c. Shall be submitted to the NRC in the form of a complete, legible copy of the changed portion of the ODCM as a part of or concurrent with the Radioactive Effluent Release Report for the period of the report in which any change in the ODCM was made. Each change shall be identified by markings in the margin of the affected pages, clearly indicating the area of the page that was changed, and shall indicate the date (i.e., month and year) the change was implemented.

5.5 Programs and Manuals

5.5.8 Containment Leakage Rate Testing Program (continued)

- d. Leakage Rate acceptance criteria are:
 - 1. Containment leakage rate acceptance criterion is $1.0 L_a$. During the first unit startup following testing in accordance with this program, the leakage rate acceptance criteria are $\leq 0.60 L_a$ for the Type B and Type C tests and $\leq 0.75 L_a$ for Type A tests;
 - 2. Air lock testing acceptance criteria are:
 - a) Overall air lock leakage rate is $\leq [0.05] L_a$ when tested at $\geq P_a$,
 - b) For each door, leakage rate is $\leq [0.01] L_a$ when pressurized to $\geq [10]$ psig.
- e. The provisions of SR 3.0.3 are applicable to the Containment Leakage Rate Testing Program.
- f. Nothing in these Technical Specifications shall be construed to modify the testing Frequencies required by 10 CFR 50, Appendix J.

5.5.9 System Level OPERABILITY Testing Program

The System Level OPERABILITY Testing Program provides requirements for performance tests of passive systems. The System Level Inservice Tests specified in Section 3.9.6 and Table 3.9-17 apply when specified by individual Surveillance Requirements.

- a. The provisions of SR 3.0.2 are applicable to the test frequencies specified in Table 3.9-17 for performing system level OPERABILITY testing activities; and
- b. The provisions of SR 3.0.3 are applicable to system level OPERABILITY testing activities.

5.5.10 Component Cyclic or Transient Limit

This program provides controls to track the Table 3.9-1A cyclic and transient occurrences to ensure that components are maintained within the design limits.

NRC 162 |

BASES

APPLICABLE SAFETY ANALYSES

The fuel cladding must not sustain damage as a result of normal operation and AOOs. The reactor core SLs are established to preclude violation of the following fuel design criteria:

- a. There must be at least 95% probability at a 95% confidence level (the 95/95 DNB criterion) that the hot fuel rod in the core does not experience DNB; and
- b. The hot fuel pellet in the core must not experience centerline fuel melting.

The Reactor Trip System (RTS) setpoints (Ref. 2), in combination with all the LCOs, are designed to prevent any anticipated combination of transient conditions for Reactor Coolant System (RCS) temperature, pressure, RCS Flow, ΔI , and THERMAL POWER level that would result in a departure from nucleate boiling ratio (DNBR) of less than the DNBR limit and preclude the existence of flow instabilities.

Automatic enforcement of these reactor core SLs is provided by the appropriate operation of the PMS and the steam generator safety valves.

The SLs represent a design requirement for establishing the RTS setpoints. LCO 3.4.1, "RCS Pressure, Temperature, and Flow Departure from Nucleate Boiling (DNB) Limits," or the assumed initial conditions of the safety analyses (as indicated in Section 7.2, Ref. 2) provide more restrictive limits to ensure that the SLs are not exceeded.

SAFETY LIMITS

The figure provided in the COLR shows the loci of points of THERMAL POWER, RCS pressure, and cold leg average temperature for which the minimum DNBR is not less than the safety analysis limit, that fuel centerline temperature remains below melting, that the average enthalpy in the hot leg is less than or equal to the enthalpy of saturated liquid, or that the exit quality is within the limits defined by the DNBR correlation.

The reactor core SLs are established to preclude violation of the following fuel design criteria:

- a. There must be at least a 95% probability at a 95% confidence level (the 95/95 DNB criterion) that the hot fuel rod in the core does not experience DNB and
- b. There must be at least a 95% probability at a 95% confidence level that the hot fuel pellet in the core does not experience centerline fuel melting.

BASES

SAFETY LIMITS (continued)

NRC 156 |

The reactor core SLs are used to define the various RPS functions such that the above criteria are satisfied during steady state operation, normal operational transients, and anticipated operational occurrences (AOOs). To ensure that the RPS precludes the violation of the above criteria, additional criteria are applied to the Overtemperature and Overpower ΔT reactor trip functions. That is, it must be demonstrated that the average enthalpy in the hot leg is less than or equal to the saturation enthalpy and the core exit quality is within the limits defined by the DNBR correlation. Appropriate functioning of the RPS ensures that for variations in the THERMAL POWER, RCS Pressure, RCS cold leg average temperature, RCS flow rate, and ΔI that the reactor core SLs will be satisfied during steady state operation, normal operational transients, and AOOs.

APPLICABILITY

SL 2.1.1 only applies in MODES 1 and 2 because these are the only MODES in which the reactor is critical. Automatic protection functions are required to be OPERABLE during MODES 1 and 2 to ensure operation within the reactor core SLs. The steam generator safety valves or automatic protection actions serve to prevent RCS heatup to the reactor core SL conditions or to initiate a reactor trip function which forces the unit into MODE 3. Setpoints for the reactor trip functions are specified in LCO 3.3.1, "Reactor Trip System (RTS) Instrumentation." In MODES 3, 4, 5, and 6, applicability is not required since the reactor is not generating significant THERMAL POWER.

SAFETY LIMIT VIOLATIONS

The following SL violation responses are applicable to the reactor core SLs. If SL 2.1.1 is violated, the requirement to go to MODE 3 places the unit in a MODE in which this SL is not applicable.

The allowed Completion Time of 1 hour recognizes the importance of bringing the unit to a MODE of operation where this SL is not applicable, and reduces the probability of fuel damage.

REFERENCES

1. 10 CFR 50, Appendix A, GDC 10.
2. Section 7.2, "Reactor Trip."

BASES

APPLICABLE SAFETY ANALYSES, LCOs, and APPLICABILITY (continued)

15. Boron Dilution Block

The block of boron dilution is accomplished by closing the CVS suction valves to demineralized water storage tanks, and aligning the boric acid tank to the CVS makeup pumps. This Function is actuated by Source Range Neutron Flux Doubling Multiplication, Reactor Trip, and Battery Charger Input Voltage – Low.

NRC 156 |

NRC 156 |

15.a. Source Range Neutron Flux Doubling Multiplication

A signal to block boron dilution in MODES 2 or 3, when not critical or during an intentional approach to criticality, and MODES 4 or 5 is derived from source range neutron flow increasing at an excessive rate (source range flux doubling). This Function is not applicable in MODES 4 and 5 if the demineralized water makeup flowpath is isolated. The source range neutron detectors are used for this Function. The LCO requires four divisions to be OPERABLE. There are four divisions and two-out-of-four logic is used. On a coincidence of excessively increasing source range neutron flux in two of the four divisions, demineralized water is isolated from the makeup pumps and reactor coolant makeup is isolated from the reactor coolant system to preclude a boron dilution event. In MODE 6, a dilution event is precluded by the requirement in LCO 3.9.2 to close, lock and secure at least one valve in each unborated water source flow path.

15.b. Reactor Trip (Function 18.a)

Demineralized Water Makeup is also isolated by all the Functions that initiate a Reactor Trip. The isolation requirements for these Functions are the same as the requirements for the Reactor Trip Function. Therefore, the requirements are not repeated in Table 3.3.2-1. Instead Function 18.a, (P-4 Reactor Trip Breakers), is referenced for all initiating Functions and requirements.

15.c. Battery Charger Input Voltage – Low

Demineralized water is also isolated by the loss of ac power. A short, preset time delay is provide to prevent actuation upon momentary power fluctuations; however, actuation occurs before ac power is restored by the onsite diesel generators. The loss of all ac power is detected by undervoltage sensors that are connected to the input of each of the four Class 1E

BASES

APPLICABLE SAFETY ANALYSES, LCOs, and APPLICABILITY (continued)

P-4 interlock is enabled by all Automatic Reactor Trip Actuations. The Functions of the P-4 interlock are:

- Trip the main turbine
- ~~Permit the block of automatic Safeguards Actuation after a predetermined time interval following automatic Safeguards Actuation.~~
- Block boron dilution
- Isolate main feedwater coincident with low reactor coolant temperature (This function is not assumed in safety analysis therefore, it is not included in the technical specifications.)

The reactor trip breaker position switches that provide input to the P-4 interlock only Function to energize or de-energize or open or close contacts. Therefore, this Function has no adjustable Trip Setpoint.

This Function must be OPERABLE in MODES 1, 2, and 3 when the reactor may be critical or approaching criticality. This Function does not have to be OPERABLE in MODE 4, 5, or 6 to trip the main turbine, because the main turbine is not in operation.

The P-4 Function does not have to be OPERABLE in MODE 4 or 5 to block boron dilution, because Function 15.a, Source Range Neutron Flux Multiplication, provides the required block. In MODE 6, the P-4 interlock with the Boron Dilution Block Function is not required, since the unborated water source flow path isolation valves are locked closed in accordance with LCO 3.9.2.

18.b. Pressurizer Pressure, P-11

The P-11 interlock permits a normal unit cooldown and depressurization without Safeguards Actuation or main steam line and feedwater isolation. With pressurizer pressure channels less than the P-11 setpoint, the operator can manually block the Pressurizer pressure – Low, Steam Line Pressure – Low, and T_{cold} – Low Safeguards Actuation signals and the Steam Line Pressure – Low and T_{cold} – Low steam line

BASES

APPLICABLE SAFETY ANALYSES, LCOs, and APPLICABILITY (continued)

operator can manually block low pressurizer level signal used for these actuations. Concurrent with blocking CMT actuation on low pressurizer level, ADS 4th Stage actuation on Low 2 RCS hot leg level is enabled. Also CVS letdown isolation on Low 1 RCS hot leg level is enabled. When the pressurizer level is above the P-12 setpoint, the pressurizer level signal is automatically enabled and a confirmatory open signal is issued to the isolation valves on the CMT cold leg balance lines. This Function is required to be OPERABLE in MODES 1, 2, 3, 4, 5, and 6.

18.e. RCS Pressure, P-19

The P-19 interlock is provided to permit water solid conditions (i.e., when the pressurizer water level is >92%) in lower MODES without automatic isolation of the CVS makeup pumps. With RCS pressure below the P-19 setpoint, the operator can manually block CVS isolation on High 2 pressurizer water level. When RCS pressure is above the P-19 setpoint, this Function is automatically unblocked. This Function is required to be OPERABLE IN MODES 1, 2, 3, and 4 with the RCS not being cooled by the RNS. When the RNS is cooled by the RNS, the RNS suction relief valve provides the required overpressure protection (LCO 3.4.14).

18.f. Reactor Trip Breaker Open, P-3

Permit the block of automatic Safeguards Actuation after a predetermined time interval following automatic Safeguards Actuation.

The reactor trip breaker position switches that provide input to the P-3 interlock only function to energize or de-energize (open or close) contacts. Therefore, this Function does not have an adjustable Trip Setpoint.

19. Containment Air Filtration System Isolation

Some DBAs such as a LOCA may release radioactivity into the containment where the potential would exist for the radioactivity to be released to the atmosphere and exceed the acceptable site dose limits. Isolation of the Containment Air Filtration System provides protection to prevent radioactivity inside containment from being released to the atmosphere.

NRC 156

BASES

ACTIONS (continued)

NRC 156		Condition D applies to one inoperable required division of <u>the P-3 & P-4 Interlocks</u> (Function 18.a <u>and</u> 18.f). With one required division inoperable, the 2 remaining OPERABLE divisions are capable of providing the required interlock function, but without a single failure. The <u>P-3 & P-4 Interlock</u> is enabled when RTBs in two divisions are detected as open. The status of the other inoperable, non-required <u>P-3 & P-4</u> division is not significant, since <u>P-3 & P-4</u> divisions can <u>not</u> be tripped or bypassed. In order to provide single failure tolerance, 3 required divisions must be OPERABLE.
NRC 156		

Condition D also applies to one inoperable division of ESF coincidence logic or ESF actuation (Functions 25 and 26). The ESF coincidence logic and ESF actuation divisions are inoperable when their associated battery-backed subsystem is inoperable. With one inoperable division, the 3 remaining OPERABLE divisions are capable of mitigating all DBAs, but without a single failure.

The 6 hours allowed to restore the inoperable division is reasonable based on the capability of the remaining OPERABLE divisions to mitigate all DBAs and the low probability of an event occurring during this interval.

E.1

Condition E is applicable to manual initiation of:

- Safeguards Actuation;
- CMT Actuation;
- Containment Isolation;
- Steam Line Isolation;
- Main Feedwater Control Valve Isolation;
- Main Feedwater Pump Trip and Valve Isolation;
- ADS Stages 1, 2, & 3 Actuation;
- ADS Stage 4 Actuation;
- Passive Containment Cooling Actuation;
- PRHR Heat Exchanger Actuation;

BASES

SURVEILLANCE REQUIREMENTS (continued)

SURVEILLANCE
REQUIREMENTS

SR 3.4.8.1

This Surveillance requires verification every 12 hours that a minimum mixing flow is present in the RCS. A Frequency of 12 hours is adequate considering the low probability of an inadvertent BDE during this time, and the ease of verifying the required RCS flow.

~~A minimum mixing flow is provided if any of the following conditions are met:~~

No. of Pumps	% Rated Speed
Operating	(each pump)
1	25%
2	20%
3	15%
4	10%

REFERENCES

None.

Chapter 18

Figure 18.2-3 provides a program milestone schedule of human factors engineering tasks showing relationships between human factors engineering elements and activities, products, and reviews. Internal design reviews are performed at various points throughout the design process.

18.2.6 Combined License Information

18.2.6.1 Human Factors Engineering Program

The Combined License information requested in this subsection has been fully addressed in APP-OCS-GBH-001 (Reference 8), and the applicable changes are incorporated into the DCD. No additional work is required by the Combined License applicant to address the Combined License information requested in this subsection. The work that has been done is summarized in the following paragraph:

The AP1000 Human Factors Engineering Program Plan (Reference 8) fully captures the information certified in Section 18.2. Reference 8 provides execution guidance for the NRC-approved HFE program. The ongoing confirmation that the AP1000 HFE Program Plan is being executed as required is demonstrated by fulfillment of the other COL Information Items in Chapter 18. The final confirmation that the HFE Program Plan has been executed will be demonstrated by completion of the ITAAC (Tier 1 Material, Table 3.2-1, Items 1 to 13).

The following words represent the original Combined License Information Item commitment, which has been addressed as discussed above:

The Combined License applicant referencing the AP1000 certified design is responsible for the execution of the NRC approved human factors engineering program as presented by Section 18.2.

18.2.6.2 Emergency Operations Facility

The Combined License information requested in this subsection has been partially addressed in Reference 9 (APP-GW-GLR-136). No additional work is required to address the information as delineated in the following paragraph:~~applicant referencing the AP1000 certified design is responsible for designing the emergency operations facility, including specification of the location and communication with the facility, in accordance with the AP1000 human factors engineering program.~~

Reference 9 captures the method by which the AP1000 Human Factors Engineering Program Plan (Reference 8) will be applied to TSCs and EOFs that support an AP1000 plan.

The following activities are to be addressed by the Combined License applicant:

Specific information regarding the location of the emergency operations facility and emergency operations facility communications will be provided by the Combined Operating License applicant to address the Combined License information requested in this subsection.

NRC 152

The following words represent the original Combined License Information Item commitment, which has been addressed as discussed above.

Combined License applicants referencing the AP1000 certified design are responsible for designing the emergency operations facility, including specification of the location and communication with the facility, in accordance with the AP1000 human factors engineering program.

18.2.7 References

- [1. NUREG-0711, "Human Factors Engineering Program Review Model," U.S. NRC, July 1994.]*
2. WCAP-14645, "Human Factors Engineering Operating Experience Review Report For The AP600 Nuclear Power Plant," Revision 2, December 1996.
3. WCAP-14694, "Designers Input to Determination of the AP600 Main Control Room Staffing Level," Revision 0, July 1996.
4. WCAP-14644, "AP600 Functional Requirements Analysis and Allocation," Revision 0, September 1996.
5. Reason, J. T., "Human Error," Cambridge, U.K., Cambridge University Press, 1990.
- [6. WCAP-15847, "AP1000 Quality Assurance Procedures Supporting NRC Review of AP1000 DCD Sections 18.2 and 18.8," Revision 1, December 2002.]*
- [7. NUREG-0711, Rev. 1, "Human Factors Engineering Program Review Model," U.S. NRC, May 2002.]*
8. APP-OCS-GBH-001, "AP1000 Human Factors Engineering Program Plan," Westinghouse Electric Company LLC.
9. APP-GW-GLR-136, "AP1000 Human Factors Program Implementation for the Emergency Operations Facility and Technical Support Center."

*NRC Staff approval is required prior to implementing a change in this information; see DCD Introduction Section 3.5.

NRC 065

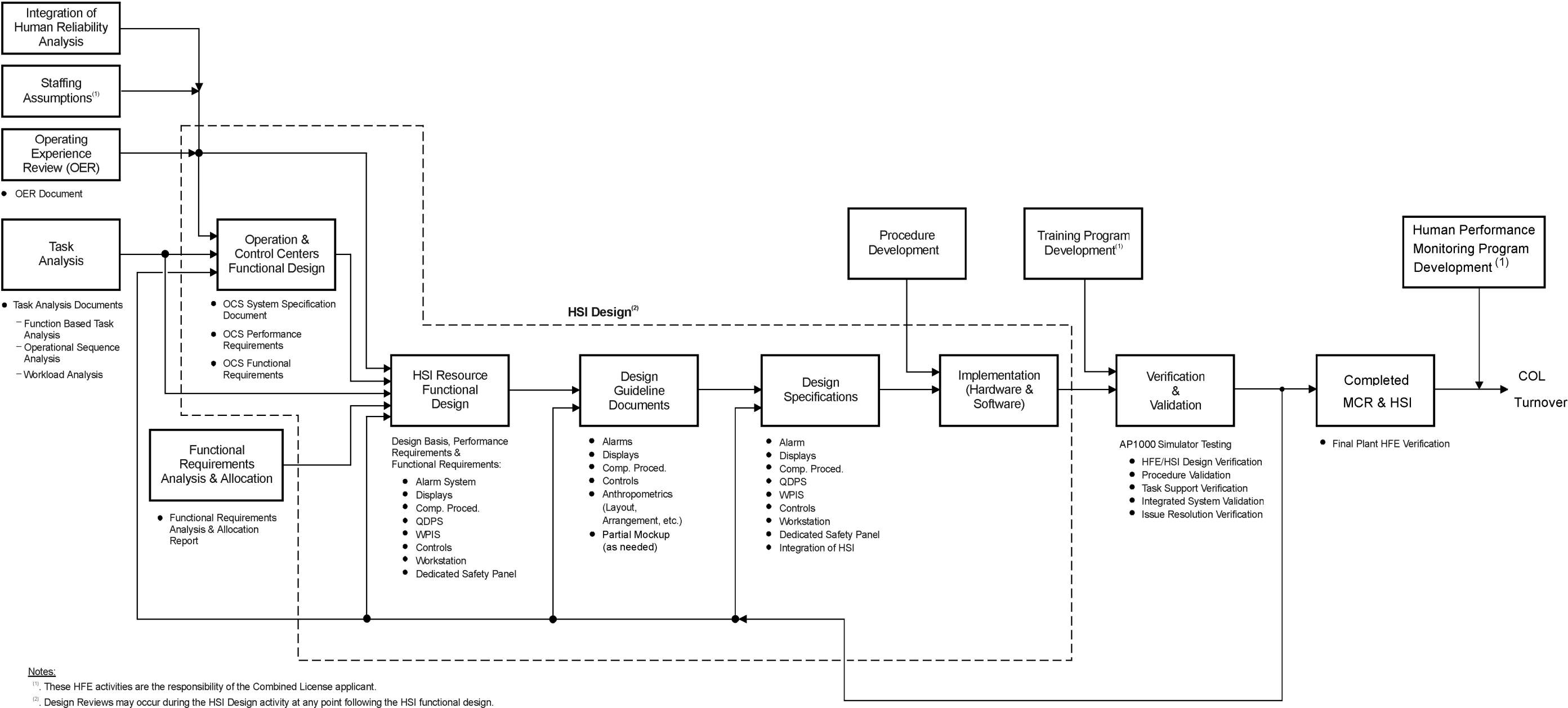


Figure 18.2-3

Overview of the AP1000 Human Factors Engineering Process

Chapter 19

19.58 Winds, Floods, and Other External Events**19.58.1 Introduction**

External events considered in the AP1000 PRA are those events whose cause is external to all systems associated with normal and emergency operations situations. Some external events may not pose a significant threat of a severe accident. Some external events are considered at the design stage and have a sufficiently low contribution to core damage frequency or plant risk.

Based upon the guidelines provided in References 19.58-1 and 19.58-2, the following is a list of five external events that are included for AP1000 analysis:

- High winds and tornadoes
- External floods
- Transportation and nearby facility accidents
- Seismic events
- Internal fires

The first three external events are addressed in this section. Seismic events and internal fires are addressed in the AP1000 PRA.

Chapter 2 defines the site characteristics for which the AP1000 is designed. A site is acceptable if the site characteristics fall within the AP1000 site interface parameters.

19.58.2 External Events Analysis**19.58.2.1 Severe Winds and Tornadoes**

The overall methodology recommended by NUREG-1407 for analyzing plant risk due to high winds and tornados is a progressive screening approach. This approach is modified to consider determining the acceptability of hazard frequency and risk. High winds (including tornadoes) can affect plant structures in at least two ways: (1) if wind forces exceed the load capacity of a building or other external facility, the walls or framing might collapse or the structure might overturn from the excessive loading; and (2) if the wind is strong enough, as in a tornado or hurricane, it may be capable of lifting materials and thrusting them as missiles against the plant structures that house safety-related equipment. Critical components or other contents of plant structures not designed to resist missile penetration might be damaged and lose their function.

The NUREG-1407 criterion for high winds and tornados states that “these events pose no significant threat of a severe accident because the current design criteria for wind are dominated by tornadoes having an annual frequency of exceedance of about 10^{-7} .” This is interpreted to mean that events with an annual frequency of exceedance less than $1.0\text{E-}0740^{-7}$ may be removed from further consideration and events with an annual frequency of exceedance greater than $1.0\text{E-}0740^{-7}$ must be further evaluated. However, the NUREG-1407 criterion was developed for currently operating plants.

NRC 170

tornados do exceed the operating basis of the AP1000. Per the Saffir-Simpson Scale for Hurricanes (Table 19.58-2), no hurricanes are expected to reach 300 mph winds; however, Category 3, Category 4 and Category 5 hurricane winds do exceed the operating basis of the AP1000.

Three studies are performed to evaluate the high wind events. The Case 1 study is a LOSP induced by each of the events, with no other equipment unavailable. A conditional core damage probability (CCDP) is developed for this scenario, which may be multiplied by the high wind event frequency. All tornados and hurricanes are considered in this Case 1 as they may challenge the AP1000 switchyard. Extratropical cyclones are normal storms and thunderstorms with winds expected to fall below the operating basis for the AP1000. They are also included in the Case 1 analysis.

As stated above, the EF3, EF4, and EF5 tornados and Category 3, Category 4 and Category 5 hurricanes may challenge the nonsafety-related structures in the AP1000. Therefore, these events will be evaluated with the loss of additional SSCs. The Case 2 study is created by modifying the Case 1 analysis for the EF3, EF4, and EF5 tornados, and Category 3, Category 4 and Category 5 hurricanes to have a LOSP with additional failures of nonsafety systems unavailable. A CCDP is developed for this scenario, which may be multiplied by the high wind event frequency.

The final Case 3 is a conservative study where all high wind events are evaluated as a LOSP with failure of the nonsafety systems. This case is created to represent the worst case scenario unavailable. In this analysis, events are considered of low risk importance if their initiating event frequency is less than $1.0\text{E-}07$ or if their estimated CDF is less than 10% of the total plant CDF. Therefore, the CDF screening values is $5.081.0\text{E-}08$ events/yr.

The results of the CDF calculation are shown in Table 19.58-3. Equation 19.58-1 was used to determine the resultant CDF.

In ~~that~~ Table 19.58-3, none of the initiating event frequencies were sufficiently low to be removed from further consideration. Therefore, the CDF calculation was performed. In each case, the resultant CDF is less than 10% of the total plant CDF, $5.081.0\text{E-}08$ events/yr. The Category 4 and Category 5 hurricane frequency is considered to be extremely conservative at $1.00\text{E-}02$ events/yr. An event with the conservative initiating event frequency, and the worst case sensitivity study (Case 3), the resultant CDF is still less than the CDF criterion of $5.081.0\text{E-}08$ events/yr. Case 2 is considered to be the representative model for high winds, with Case 1 and Case 3 being treated as sensitivity studies on the baseline. Case 3 is conservative in that it assumes total failure of the standby non-safety systems (CVS, RNS, SFW, automatic DAS, and diesel generators) for all high wind events. As AP1000 non-safety structures have been designed to a building code that offers an added level of protection, the above failures are considered extreme and conservative. Therefore, while the total Case 3 CDF does fall above the $1.0\text{E-}08$ events/yr CDF screening criteria, the results are considered very conservative for the above reasons. Furthermore, the sum of the estimated CDF for each case falls below the CDF criterion of $5.081.0\text{E-}08$ events/yr. Therefore, no further detailed PRA is necessary for the AP1000 high winds and tornados analysis.

19.58.2.2 External Floods

An external flooding analysis is performed to verify that any significant contribution to core damage frequency – resulting from plant damage caused by storms, dam failure, and flash floods – is accounted for as follows:

The analysis for external floods begins with an examination of the design basis for the plant, which is documented in Chapter 2 of the AP1000 DCD. The AP1000 is protected against floods up to the 100' level. The 100' level corresponds to the plant ground level. From this point, the ground is graded away from the structures. Thus, water will naturally flow away from the structures. Additionally, all seismic Category I SSCs are designed to withstand the effects of flooding. The seismic Category I SSCs below grade (below ground level) are protected against flooding by a water barrier consisting of water stops and a waterproofing system. None of the non-safety SSCs were found to be important based on flooding considerations. The AP1000 is designed against flood levels less than plant elevation 100 feet.

The basic steps involved in an external flooding analysis are similar to those followed for internal flooding in the individual plant examination. However, the focus of attention is on areas, which due to their location and grading, may be susceptible to external flood damage. This requires information on such items as dikes, surface grading, locations of structures, and locations of equipment within the structures. Information such as meteorological data for the site, historical flood height, and frequency data, is also needed.

Only one site indicated susceptibility to external floods, due to hurricane surge water. That site is located at an elevation of 45 feet above sea level. Therefore, the AP1000 100' level, for this site, corresponds to 45' above sea level. Per DCD Chapter 3.4.1.1, the ground will be graded away from the structures beginning at the 100' level and sloping downward away from the structures. The Saffir-Simpson hurricane scale notes that Category 5 hurricanes have the ability to generate storm surges in excess of 18 feet. Hurricane Camille (1969) generated a storm surge of 25 feet along the Mississippi Gulf Coast.

Category 5 hurricanes, per the Saffir-Simpson scale, are capable of storm surges greater than 18 feet. However, the probability of generating a storm surge of 18 feet, combined with the frequency of a Category 5 hurricane, results in a small event frequency. Even conservatively assuming a storm surge of 18 feet, the frequency of an event capable of generating this storm surge is small. Engineering judgment is used to establish that the frequency of this type of flood is significantly less than the 10^{-7} per year criterion for initiating event frequency. Based on the description of a Category 5 hurricane in the Saffir-Simpson hurricane scale, a hurricane storm surge in excess of 18 feet may be classified as an extremely rare event. The ASME has recently approved changes to the ASME PRA Standard to assign a value to an "extremely rare event." That value is defined as $1\text{E-}06/\text{year}$ for currently operating plants. Recognizing that the AP1000 design provides additional levels of safety, TR-101 suggests a value of $1\text{E-}07/\text{year}$ to define an extremely rare event for the AP1000 design.

As a sensitivity study, the $1.0\text{E-}07\text{yr}^{-1}$ initiating event frequency is taken as the frequency of an event that may challenge the nonsafety structures in the plant. This sensitivity study also considers

failure of the switchyard due to flooding. LOSP with failure of the nonsafety systems CDDP was developed. Equation 1 was used to determine the resultant CDF.

As expected, the risk due to a flooding event is low for the AP1000. The resultant CDF of $5.85\text{E-}15/\text{yr}$ is an insignificant contribution to total plant CDF.

For other sites, the AP1000 is designed to site characteristics described in Chapter 2. The site selection criterion provides that for an accident that has potential consequences serious enough to affect the safety of the plant to the extent that 10 CFR 100 guidelines are exceeded, the annual frequency of occurrence is less than $1.0\text{E-}06$ per year. ~~To consider the already low risk of the AP1000 design, this criterion should be extended to an annual frequency of occurrence less than $1.0\text{E-}07$ per year for the AP1000 design. As none of the surveyed sites indicated susceptibility to floods due to dam failure and/or flash floods, those events should be considered on a site-by-site basis.~~

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19.58.2.3 Transportation and Nearby Facility Accidents

These events consist of accidents related to transportation near the nuclear power plant and accidents at industrial and military facilities in the vicinity. The following modes of transportation are considered:

- Aviation (commercial/general/military)
- Marine (ship/barge)
- Pipeline (gas/oil)
- Railroad
- Truck

19.58.2.3.1 Aviation Accidents

For limiting event frequency of $1.21\text{E-}06/\text{year}$ with most of that frequency for small aircraft, and with commercial aircraft contribution $9.40\text{E-}09/\text{year}$, then the following discussion is applicable.

A conservative analysis was performed to evaluate the risk due to small aircraft accidents onsite. This analysis assumes a LOSP and loss of component cooling water/service water event, and conservatively fail a set of standby nonsafety systems. This is acceptable because it is unlikely that a small aircraft accident would challenge the passive safety systems inside containment. This leaves only the nonsafety systems outside containment as vulnerable. However, this evaluation is conservative because it is unlikely that a small aircraft would have the capacity to fail such a large area of the AP1000.

Equation 19.58-1 is used to determine the resultant CDF. A CDF of $7.08\text{E-}14/\text{yr}$ is calculated and is an insignificant contribution to total plant CDF of approximately $5.08\text{E-}07/\text{yr}$. Therefore, sites that can demonstrate an aviation event frequency less than or equal to $1.21\text{E-}06/\text{yr}$ for small aircraft accidents are bounded by this evaluation.

Larger commercial aircraft may have the capacity to challenge SSCs within the AP1000 containment. However, the containment structure and safety systems are designed to withstand

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various earthquake levels so that many of the safety system SSCs will still be available following the accident. To consider the already low risk of the AP1000 design, the $1.0\text{E-}0740^{-7}$ events/yr criterion for event frequency is applicable for larger commercial aircraft. Sites that can demonstrate a commercial aircraft aviation event frequency less than the $1.0\text{E-}0740^{-7}$ /yr criterion are also bounded by this analysis. For this current evaluation, the highest initiating event frequency reported for large commercial aircraft is $9.40\text{E-}09$ events/yr. This value falls below the $1.0\text{E-}07$ events/yr screening criteria. Therefore, no further evaluation is necessary.

19.58.2.3.2 Marine Accidents

Only sites with large waterways with ship and/or barge traffic that goes through or near the site need to consider marine accidents.

Marine accidents involving ship or barge accidents pose a potential hazard to a nuclear power plant due to two possibilities:

1. Release of hazardous material towards the plant
2. Explosion with resulting damage to the plant

The potential exists for a marine accident that leads to a release of toxic materials into the atmosphere. This type of event may compromise the safety of the plant operators, resulting in reduced operator reliability. However, the toxic release does not directly lead to any failure of plant equipment. To evaluate the risk impact of this scenario, a CCDP is developed that models a reactor trip followed by the guaranteed failure of all PRA credited operator actions. The resulting CCDP is $6.26\text{E-}08$. The bounding initiating event frequency is $1.0\text{E-}06$ /yr.

Equation 19.58-1 is used to determine the resultant CDF. The resultant CDF is $6.26\text{E-}14$ /yr. The results indicate a low estimated CDF contribution due to toxic releases from a marine accident.

The above analysis is conservative. The AP1000 has an additional level of defense against toxic airborne material. With advanced warning, the operators may actuate passive control room habitability. This system isolates the control room from normal HVAC and actuates a separate system supplied from compressed air containers. The compressed air slightly pressurizes the control room above atmospheric pressure, preventing the entrance of toxic material in the control room. This system is available for 72 hours, which is adequate time to withstand the event.

There is also a potential for marine explosion accidents. The AP1000 is not designed with a service water intake structure. Therefore, loss of service water events as a consequence of marine explosions are not a concern for the AP1000 design. As long as Regulatory Guide 1.91 acceptance criterion is met, marine explosion accidents do not need to be considered further for the AP1000 PRA.

19.58.2.3.3 Pipeline Accidents

Pipeline accidents could pose a hazard to the AP1000 due to the release of hazardous material or the possibility of an explosion and resulting damage to the plant. For a site with a 30-inch gas line approximately 5800 feet away, a semi-quantitative evaluation is performed.

Considerations for the evaluation are as follows:

- Gas pipe rupture frequency
- Gas cloud formation probability
- Gas cloud transportation and nondispersion probability
- Gas cloud ignition probability onsite

Figure 19.58-1 is considered to further evaluate the probability of this accident. When then considering the probability of forming a dense gas cloud, and the probability of the wind speed and direction to be in the ranges necessary to transport the gas cloud 5800 feet to the site, without dispersing the gas, including ignition of the gas cloud onsite in a location that may challenge the plant, this probability becomes very low.

Site habitability is also a concern for toxic materials. However, the AP1000 has an additional level of defense against toxic airborne material. With advanced warning, the operators may actuate passive control room habitability. This system isolates the control room from normal HVAC and actuates a separate system supplied from compressed air containers. The compressed air slightly pressurizes the control room above atmospheric pressure, preventing the entrance of toxic material in the control room. This system is available for 72 hours, which is adequate time to withstand the event. The expected frequency value is expected to be below the initiating event criterion of $1.0\text{E-}07$ events/year. Therefore, no further quantitative evaluation is necessary.

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19.58.2.3.4 Railroad and Truck Accidents

Railroad accidents could pose a hazard to the AP1000 due to the release of hazardous material or the possibility of an explosion and resulting damage to the plant. Toxic material releases were evaluated in the marine accident evaluation as to not be important to AP1000 plant risk. Significant damage to the AP1000 plant was evaluated in the aviation accident evaluation. No railroad accidents are expected to result in the amount of damage that may be seen from an aviation accident. This is especially true considering the increased security barriers established at U.S. nuclear power plants.

The AP1000 is designed to site characteristics described in Chapter 2. The site selection criterion provides that, for an accident that has potential consequences serious enough to affect the safety of the plant to the extent that 10 CFR 100 guidelines are exceeded, the annual frequency of occurrence is less than $1.0\text{E-}06$ per year. ~~As explained in Chapter 2, t~~ This criterion should be extended to an annual frequency of occurrence less than $1.0\text{E-}07$ per year for the AP1000 design.

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19.58.3 Conclusion

The risk due to external hazards is low for the AP1000 design for the participating sites listed in Section 3.2. The AP1000 design is shown to be highly robust against the external events discussed in this section. The design is resilient against high winds, external floods, and other external events that challenge various equipment in the plant.

The following conclusions and insights are derived from the AP1000 external events assessment for events at power:

1. High winds and tornados were quantitative evaluated to be of low risk to the AP1000 design for each of the participating sites. A bounding assessment is provided to show that the expected CDF due to any one of these events does not exceeds 10% of the total plant CDF ($\leq 1.08\text{E-}08$ events/year). The same is true for the aggregate results. Sensitivity studies were performed to determine that there is low risk for more limiting scenarios. No further analysis is suggested.
2. The AP1000 is designed to flooding levels described in Chapter 2. The site selection criterion provides that, for an accident that has potential consequences serious enough to affect the safety of the plant to the extent that 10 CFR 100 guidelines are exceeded, the annual frequency of occurrence is less than 10^{-6} 1.0E-06 per year. ~~As explained in Section 4.1,~~ This criterion can be extended to an annual frequency of occurrence less than 10^{-7} 1.0E-07 per year for the AP1000 design. No further analysis is suggested.
3. Transportation and nearby facilities accidents are qualitatively evaluated to be of low risk importance and do not warrant further evaluation.

19.58.4 References

- 19.58-1 "Individual Plant Examination of External Events (IPEEE) for Severe Accident Vulnerabilities - 10 CFR 50.54(f)," Generic Letter 88-20, Supplement 4, June 28, 1991.
- 19.58-2 NUREG-1407, "Procedural and Submittal Guidance for the Individual Plant Examination of External Events (IPEEE) for Severe Accident Vulnerabilities," June 1991.
- 19.58-3 National Weather Service, "The Enhanced Fujita Scale," February 2, 2007, <http://www.spc.noaa.gov/efscale/>.
- 19.58-4 National Weather Service, "The Saffir-Simpson Hurricane Scale," June 22, 2006, <http://www.nhc.noaa.gov/aboutsshs.shtml>.
- 19.58-5 U.S. Nuclear Regulatory Commission Regulatory Guide 1.91, "Evaluation of Explosions Postulated to Occur on Transportation Routes Near Nuclear Power Plants," Revision 1, February 1978.

Table 19.58-3

HIGH WINDS AND TORNADOS RESULTS

Category	Event	Limiting Initiating Event Freq. (/yr)	CDF (/yr)		
			LOSP (Case 1) (/yr)	LOSP with Nonsafety Systems Unavailable for Select Events (Case 2) (/yr)	LOSP with Nonsafety Systems Unavailable for All Events (Case 3) (/yr)
High Winds	EF0 Tornado	$\frac{1.00E-03}{038.00E-05}$	$\frac{9.81E-12}{127.85E-13}$	$\frac{9.81E-12}{13^{(1)}}$	$\frac{5.85E-11}{4.68E-12}$
	EF1 Tornado	$\frac{1.00E-03}{038.00E-05}$	$\frac{9.81E-12}{127.85E-13}$	$\frac{9.81E-12}{13^{(1)}}$	$\frac{5.85E-11}{4.68E-12}$
	EF2 Tornado	$\frac{1.00E-03}{1.60E-04}$	$\frac{9.81E-12}{121.57E-12}$	$\frac{9.81E-12}{12^{(1)}}$	$\frac{5.85E-11}{9.36E-12}$
	EF3 Tornado	$\frac{1.00E-03}{038.00E-05}$	$\frac{9.81E-12}{127.85E-13}$	$\frac{5.85E-11}{7.85E-13^{(4)}}$	$\frac{5.85E-11}{4.68E-12}$
	EF4 Tornado	$\frac{1.00E-03}{038.00E-05}$	$\frac{9.81E-12}{127.85E-13}$	$\frac{5.85E-11}{7.85E-13^{(4)}}$	$\frac{5.85E-11}{4.68E-12}$
	EF5 Tornado	$\frac{1.00E-03}{038.00E-05}$	$\frac{9.81E-12}{127.85E-13}$	$\frac{5.85E-11}{4.68E-12}$	$\frac{5.85E-11}{4.68E-12}$
	Cat. 1 Hurricane	1.00E-01	9.81E-10	$9.81E-10^{(1)}$	5.85E-09
	Cat. 2 Hurricane	5.00E-02	$\frac{4.91E-10}{102.94E-10}$	$\frac{4.91E-10}{2.94E-10^{(1)}}$	2.93E-09
	Cat. 3 Hurricane	3.00E-02	2.94E-10	$\frac{1.76E-09}{2.94E-10^{(4)}}$	1.76E-09
	Cat. 4 Hurricane	1.00E-02	9.81E-11	5.85E-10	5.85E-10
	Cat. 5 Hurricane	1.00E-02	9.81E-11	5.85E-10	5.85E-10
	Extratropical Cyclones	3.00E-02	2.94E-10	$2.94E-10^{(1)}$	1.76E-09
Totals			$\frac{2.32E-09}{092.07E-09}$	$\frac{4.90E-09}{3.05E-09}$	$\frac{1.38E-08}{1.35E-08}$

Note:

1. CDF values from Case 1 were used to illustrate the winds from these events will not challenge additional plant SSCs.

Table 19.59-18 (Sheet 23 of 24)

AP1000 PRA-BASED INSIGHTS

Insight	Disposition
68. The startup feedwater system pumps provide feedwater to the steam generator. This capability provides an alternate core cooling mechanism to the PRHR heat exchangers for non-LOCA or steam generator tube ruptures. The startup feedwater pumps are included in the D-RAP.	17.4
69. Capability is provided for on-line testing and calibration of the DAS channels, including sensors. Short-term availability controls of the DAS during at-power conditions reduce PRA uncertainties.	7.7.1.11 16.3
70. One CVS pump is configured to operate on demand while the other CVS pump is in standby. The operation of these pumps will alternate periodically. <u>On a source range flux doubling signal, the PMS automatically closes two safety-related CVS makeup line isolation valves, closes two safety-related CVS demineralized water suction valves to the makeup pumps and trips the makeup pumps. On a reactor trip or low input voltage to the Class 1E dc power system battery chargers, the PMS closes the two safety-related CVS demineralized water suction valves to the makeup pumps and aligns the makeup pump suction to the boric acid tank. The safety related PMS boron dilution signal automatically re-aligns CVS pump suction to the boric acid tank. This signal also closes the two safety related CVS demineralized water supply valves. This signal actuates on reactor trip signal (interlock P 4), source range flux doubling signal, or low input voltage to the Class 1E dc power system battery chargers.</u>	9.3.6.3.1 & 19.15 7.3.1.2.14
71. Procedures will be prepared to respond to low hot leg level alarms.	Emergency Response Guidelines
72. The containment recirculation screens are configured such that the chance of clogging is minimized during operation following accidents at power and at shutdown. The configuration features that reduce the chance of clogging include: - Redundant screens are provided and located in separate locations - Bottom of screens are located well above the lowest containment level as well as the floors around them - Top of screens are located well below the containment floodup level - Screens have protective plates that are located close to the top of the screens and extend out in front and to the side of the screens - Screens have conservative flow areas to account for plugging. Adequate PXS performance can be supported by one screen with at least 90% of its surface area completely blocked	6.3.2

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Revision 1

Attachment A

Tier 1 and 2

**APP-GW-GLR-134
Revision 1**

Attachment A

AP1000 DCD Impact Report

APP-GW-GL-700, Revision 16, "AP1000 Design Control Document"

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
Tier 1 - 1.2, 5.0, 5.0-1, 5.0- 3, 5.0-4	Accepted for Revision 17 of the DCD and Revision 1 of TR 134	NRC190	Tier 1	Requires Prior NRC Approval
<i>Description:</i> Incorporate DCD changes into TR134 to address seismic changes identified in TR 144 which are, Tier 1 changes related to the seismic design spectra to provide conformance with previous DCD Tier 2 changes to address hard rock high frequency exceedances. Additional conforming changes to DCD Tier 2 are also provided.				
<i>Reference Information:</i> APP-GW-GLR-144, Rev 0				

Attachment A

AP1000 DCD Impact Report

APP-GW-GL-700, Revision 16, "AP1000 Design Control Document"

<i>DCD Section</i>	<i>Westinghouse Status</i>	<i>Tracking Number</i>	<i>DCD Category</i>	<i>Change Criteria</i>
Tier 2 - Table 2-1, 3.10, 3.10.7, 3I.1-1, 3I.1-2	Accepted for Revision 17 of the DCD and Revision 1 of TR 134	NRC191	Tier 2	NRC Prior Approval Not Required
<i>Description:</i> Incorporate DCD changes into TR134 to address seismic changes identified in TR 144 which are, Tier 1 changes related to the seismic design spectra to provide conformance with previous DCD Tier 2 changes to address hard rock high frequency exceedances. Additional conforming changes to DCD Tier 2 are also provided.				
<i>Reference Information:</i> APP-GW-GLR-144, Rev 0				

Attachment B

DCD Markup Pages

APP-GW-GLR-134
Revision 1

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inspection reports, analysis reports, evaluation reports, design and manufacturing procedures, certified data sheets, commercial dedication procedures and records, quality assurance records, calculation notes, and equipment qualification data packages. For plants at sites which are qualified using the Hard Rock High Frequency GMRS high frequency seismic testing required as a result of the elevation of potential high frequency sensitive components is included in the equipment qualification data packages.

Many entries in the ITA column of the ITAAC tables include the words “Inspection will be performed for the existence of a report verifying...” When these words are used it indicates that the ITA is tests, type tests, analyses, or a combination of tests, type tests, and analyses and a report will be produced documenting the results. This report will be available to inspectors.

Many ITAAC are only a reference to another Tier 1 location, either a section, subsection, or ITAAC table entry (for example, “See Tier 1 Material...”). A reference to another ITAAC location is always in both the ITA and acceptance criteria columns for a design commitment. This reference is an indication that the ITA and acceptance criteria for that design commitment are satisfied when the referenced ITA are completed and the acceptance criteria for the referenced Tier 1 sections, subsections, or table entries are satisfied. If a complete Tier 1 section is referenced, this indicates that all the ITA and acceptance criteria in that section must be met before the referencing design commitment is satisfied.

Discussion of Matters Related to Operations

In some cases, the design descriptions in this document refer to matters that relate to operation, such as normal valve or breaker alignment during normal operation modes. Such discussions are provided solely to place the design description provisions in context (for example, to explain automatic features for opening or closing valves or breakers upon off-normal conditions). Such discussions shall not be construed as requiring operators during operation to take any particular action (for example, to maintain valves or breakers in a particular position during normal operation).

Interpretation of Figures

In many but not all cases, the design descriptions in Section 2 include one or more figures. The figures may represent a functional diagram, general structural representation, or another general illustration. For instrumentation and control (I&C) systems, figures may also represent aspects of the relevant logic of the system or part of the system. Unless specified explicitly, the figures are not indicative of the scale, location, dimensions, shape, or spatial relationships of as-built structures, systems, and components. In particular, the as-built attributes of structures, systems, and components may vary from the attributes depicted on the figures, provided that those safety functions discussed in the design description pertaining to the figure are not adversely affected.

Maximum Reactor Core Thermal Power

The initial rated reactor core thermal power for the AP1000 certified design is 3400 megawatts thermal (MWt).

5.0 Site Parameters

Table 5.0-1 identifies the key site parameters that are specified for the design of safety-related aspects of structures, systems, and components for the AP1000. An actual site is acceptable if its site characteristics fall within the AP1000 plant site design parameters in Table 5.0-1.

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Structures, systems, and components for the AP1000 are evaluated for generic Ground Motion Response Spectra (GMRS) with high frequency seismic input at a site where the nuclear island is founded on hard rock. The spectra shown in Figure 5.0-3 and Figure 5.0-4 provide hard rock high frequency (HRHF) GMRS at the foundation level for both the horizontal and vertical directions for 5% damping. An actual site is acceptable if its site specific GMRS fall within the AP1000 HRHF parameters in Figures 5.0-3 and 5.0-4. No additional design or analyses are required for the structures, systems, and components for sites that fall within the AP1000 HRHF parameters.

Table 5.0-1 (cont.) Site Parameters	
Soil	
Average Allowable Static Soil Bearing Capacity	Greater than or equal to 8,600 lb/ft ² over the footprint of the nuclear island at its excavation depth
Maximum Allowable Dynamic Bearing Capacity for Normal Plus Safe Shutdown Earthquake (SSE)	Greater than or equal to 35,000 lb/ft ² at the edge of the nuclear island at its excavation depth
Lateral Variability	Soils supporting the nuclear island should not have extreme variations in subgrade stiffness. Case 1: For a layer with a low strain shear wave velocity greater than or equal to 2500 feet per second, the layer should have approximately uniform thickness, should have a dip not greater than 20 degrees, and should have less than 20 percent variation in the shear wave velocity from the average velocity in any layer. Case 2: For a layer with a low strain shear wave velocity less than 2500 feet per second, the layer should have approximately uniform thickness, should have a dip not greater than 20 degrees, and should have less than 10 percent variation in the shear wave velocity from the average velocity in any layer.
Shear Wave Velocity	Greater than or equal to 1000 ft/sec based on low-strain, best-estimate soil properties over the footprint of the nuclear island at its excavation depth
Liquefaction Potential	None
Seismic	
SSE	SSE free field peak ground acceleration of 0.30 g with modified Regulatory Guide 1.60 response spectra (See Figures 5.0-1 and 5.0-2.). Seismic input is defined at finished grade except for sites where the nuclear island is founded on hard rock. <u>The hard rock high frequency (HRHF) ground motion spectra (GMRS) are shown in Figure 5.0-3 and Figure 5.0-4 defined at the foundation level for 5% damping. The HRHF GMRS provide an alternative set of spectra for evaluation of site specific GMRS. A site is acceptable if its site specific GMRS fall within the AP1000 HRHF GMRS.</u>
Fault Displacement Potential	<u>Negligible</u> None

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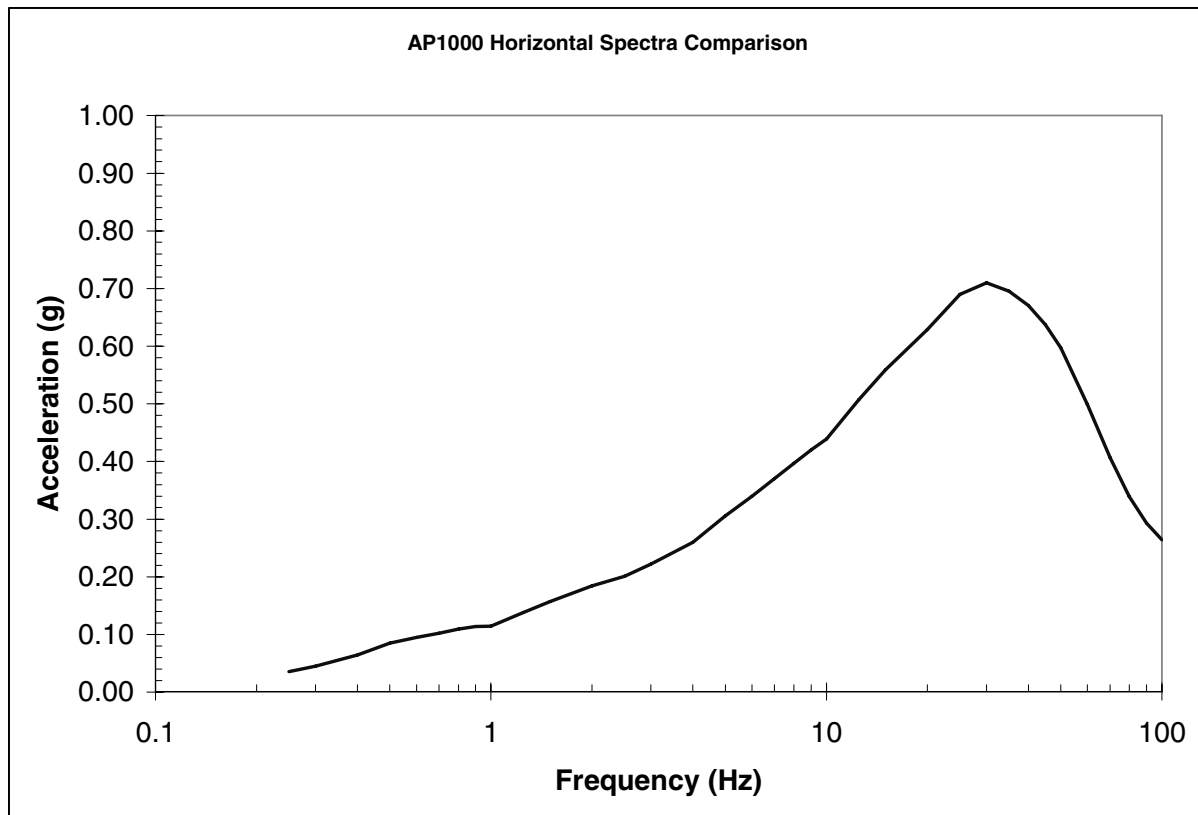


Figure 5.0-3
Horizontal HRHF GMRS
Safe Shutdown Earthquake

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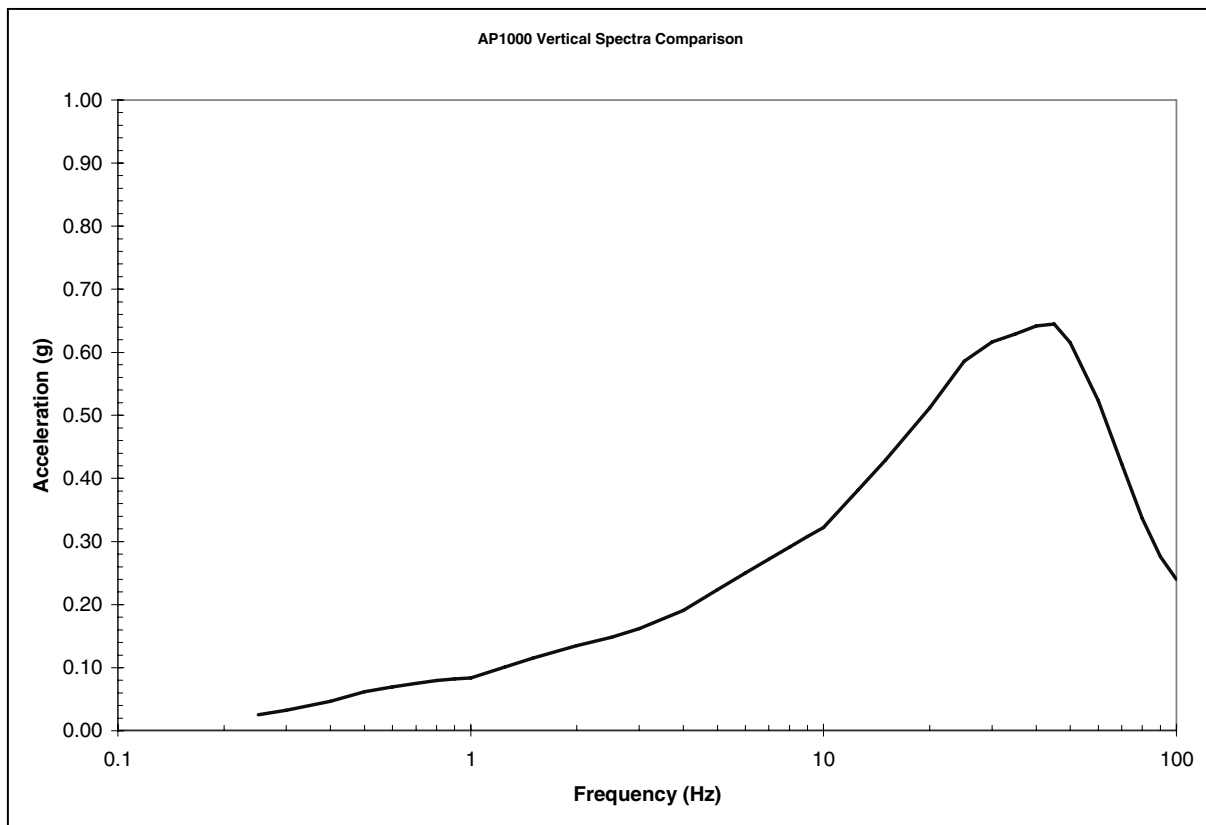


Figure 5.0-4
Vertical HRHF GRMS
Safe Shutdown Earthquake

Table 2-1 (Sheet 1 of 3)

SITE PARAMETERS**Air Temperature**

Maximum Safety ^(a)	115°F dry bulb/80°F coincident wet bulb 85.5°F wet bulb (noncoincident)
Minimum Safety ^(a)	-40°F
Maximum Normal ^(b)	100°F dry bulb/80.1°F coincident wet bulb 80.1°F wet bulb (noncoincident) ^(d)
Minimum Normal ^(b)	-10°F

Wind Speed

Operating Basis	145 mph (3 second gust); importance factor 1.15 (safety), 1.0 (nonsafety); exposure C; topographic factor 1.0
Tornado	300 mph

Seismic

SSE	0.30g peak ground acceleration ^{(c)(f)}
Fault Displacement Potential	Negligible

Soil

Average Allowable Static Bearing Capacity	Greater than or equal to 8,600 lb/ft ² over the footprint of the nuclear island at its excavation depth
Maximum Allowable Dynamic Bearing Capacity for Normal Plus SSE	Greater than or equal to 35,000 lb/ft ² at the edge of the nuclear island at its excavation depth
Shear Wave Velocity	Greater than or equal to 1,000 ft/sec based on low-strain best-estimate soil properties over the footprint of the nuclear island at its excavation depth
Lateral Variability	Soils supporting the nuclear island should not have extreme variations in subgrade stiffness Case 1: For a layer with a low strain shear wave velocity greater than or equal to 2500 feet per second, the layer should have approximately uniform thickness, should have a dip not greater than 20 degrees, and should have less than 20 percent variation in the shear wave velocity from the average velocity in any layer. Case 2: For a layer with a low strain shear wave velocity less than 2500 feet per second, the layer should have approximately uniform thickness, should have a dip not greater than 20 degrees, and should have less than 10 percent variation in the shear wave velocity from the average velocity in any layer (see subsection 2.5.4.5).

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Table 2-1 (Sheet 2 of 3)	
SITE PARAMETERS	
Liquefaction Potential	None
Minimum Soil Angle of Internal Friction	Greater than or equal to 35 degrees below footprint of nuclear island at its excavation depth
Missiles	
Tornado	4000 - lb automobile at 105 mph horizontal, 74 mph vertical 275 - lb, 8 in. shell at 105 mph horizontal, 74 mph vertical 1 inch diameter steel ball at 105 mph horizontal and vertical
Flood Level	Less than plant elevation 100'
Ground Water Level	Less than plant elevation 98'
Plant Grade Elevation	Less than plant elevation 100' except for portion at a higher elevation adjacent to the annex building
Precipitation	
Rain	19.4 in./hr (6.3 in./5 min)
Snow/Ice	75 pounds per square foot on ground with exposure factor of 1.0 and importance factors of 1.2 (safety) and 1.0 (non-safety)
Atmospheric Dispersion Values - $\chi/Q^{(e)}$	
Site boundary (0-2 hr)	$\leq 1.0 \times 10^{-3} \text{ sec/m}^3$
Site boundary (annual average)	$\leq 2.0 \times 10^{-5} \text{ sec/m}^3$
Low population zone boundary	
0 - 8 hr	$\leq 5.0 \times 10^{-4} \text{ sec/m}^3$
8 - 24 hr	$\leq 3.0 \times 10^{-4} \text{ sec/m}^3$
24 - 96 hr	$\leq 1.5 \times 10^{-4} \text{ sec/m}^3$
96 - 720 hr	$\leq 8.0 \times 10^{-5} \text{ sec/m}^3$
Population Distribution	
Exclusion area (site)	0.5 mi

Notes:

- Maximum and minimum safety values are based on historical data and exclude peaks of less than 2 hours duration.
- Maximum and minimum normal values are the 1 percent exceedance magnitudes.
- With ground response spectra as given in Figures 3.7.1-1 and 3.7.1-2. Seismic input is defined at finished grade except for sites where the nuclear island is founded on hard rock.
- The noncoincident wet bulb temperature is applicable to the cooling tower only.
- For AP1000, the terms "site boundary" and "exclusion area boundary" are used interchangeably. Thus, the χ/Q specified for the site boundary applies whenever a discussion refers to the exclusion area boundary.
- Sites that fall within the hard rock high frequency GMRS given in Figure 3I.1-1 and Figure 3I.1-2 are acceptable.

3.10 Seismic and Dynamic Qualification of Seismic Category I Mechanical and Electrical Equipment

Safety-related equipment and selected portions of post-accident monitoring equipment are classified as seismic Category I, as discussed in subsection 3.2.1.1. This section addresses the seismic and dynamic qualification of this equipment other than piping and includes the following types:

- Safety-related instrumentation and electrical equipment and certain monitoring equipment.
- Safety-related active mechanical equipment that performs a mechanical motion while accomplishing a system safety-related function. These devices include the control rod drive mechanisms; HVAC and fluid system valves.
- Safety-related, nonactive mechanical equipment whose mechanical motion is not required while accomplishing a system safety-related function, but whose structural integrity must be maintained in order to fulfill its design safety-related function.

This section presents or references information to demonstrate that mechanical equipment, electrical equipment, instrumentation, and, where applicable, their supports classified as seismic Category I are capable of performing their designated safety-related functions under the full range of normal and accident (including seismic) loadings. This equipment includes devices associated with systems essential to safe shutdown, containment isolation, reactor core cooling, and containment and reactor heat removal, or are otherwise essential in preventing significant release of radioactive material to the environment or in mitigating the consequences of accidents. The information presented or referenced includes:

- Identification of the seismic Category I instrumentation, electrical equipment, and appropriate mechanical equipment
- Qualification criteria employed for each type of equipment
- Designated safety-related functional requirements
- Definition of the applicable seismic environment
- Definition of other normal and accident loadings
- Documentation of the qualification process employed to demonstrate the required structural integrity and operability of mechanical and electrical equipment and instrumentation in the event of a safe shutdown earthquake (SSE) after a number of postulated occurrences of an earthquake smaller than a safe shutdown earthquake in combination with other relevant dynamic and static loads.

The AP1000 plant is based on the Certified Seismic Design Response Spectra (CSDRS) defined in subsection 3.7.1.1. The CSDRS are based on Regulatory Guide 1.60 design response spectra with an increase in the 25 hertz region. The Ground Motion Response Spectra (GMRS) for some

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Central and Eastern United States rock sites show higher amplitude at high frequency than the CSDRS. Evaluations for high frequency exceedance at AP1000 plant rock sites have been performed as described in Appendix 3I. It is the conclusion of these evaluations that AP1000 plant systems, structures, and components are qualified for the high frequency seismic response based on the CSDRS with the exception of potential high frequency sensitive components (APP-GW-GLN-144, Reference 5). Specific models of components are not identified as part of the AP1000 certified design and are evaluated for high frequency sensitivity as part of the equipment qualification. Appendix 3I provides the criteria for addressing potential high frequency sensitive components for plant locations where there is CSDRS exceedance in the high frequency region.

3.10.1 Seismic and Dynamic Qualification Criteria

3.10.1.1 Qualification Standards

The methods of meeting the general requirements for the seismic and dynamic qualification of seismic Category I mechanical and electrical equipment and instrumentation as described by General Design Criteria (GDC) 1, 2, 4, 14, 23, and 30 are described in Section 3.1. The general methods of implementing the requirements of Appendix B to 10CFR50 are described in Chapter 17.

The Nuclear Regulatory Commission (NRC) recommendations concerning the methods employed for seismic qualification of mechanical and electrical equipment are contained in Regulatory Guide 1.100, which endorses IEEE 344-1987 (Reference 1).

*[AP1000 meets IEEE 344-1987, as modified by Regulatory Guide 1.100, by either type testing or analysis or by an appropriate combination of these methods]** employing the methodology described in Appendix 3D.

The guidance provided in the ASME Code, Section III, is followed in the design of seismic Category I mechanical equipment to achieve the structural integrity of pressure boundary components. In addition, the AP1000 implements an operability program for active valves following Regulatory Guide 1.148, as addressed in subsection 1.9.1 and in Section 3.9.

3.10.1.2 Performance Requirements for Seismic Qualification

An equipment qualification data package (EQDP) is developed for the instrumentation and electrical equipment classified as seismic Category I. Table 3.11-1 of Section 3.11 identifies the seismic Category I electrical equipment and instrumentation supplied for the AP1000. Each equipment qualification data package contains a section entitled "Performance Requirements." This section establishes the safety-related functional requirements of the equipment to be demonstrated during and after a seismic event. The required response spectra employed by the AP1000 for generic seismic qualification are also identified in the section.

For active seismic Category I mechanical components, the performance requirements are defined in the appropriate design and equipment specifications. Requirements for active valves are discussed in subsection 3.10.2.2. The equipment qualification data packages are referenced in

*NRC Staff approval is required prior to implementing a change in this material; see DCD Introduction Section 3.5.

3.10.4 Documentation

The results of tests and analyses verifying that the criteria established in subsection 3.10.1 are satisfied, employing the qualification methods described in subsections 3.10.2 and 3.10.3, are included in the individual equipment qualification data packages and test reports. The upkeep of the equipment qualification file is maintained during the equipment selection and procurement phase is discussed in subsection 3.11.5.

Seismic qualification of equipment is documented in equipment qualification data packages, test reports, analysis reports, and calculation notes. Appendix 3D provides guidance in this area.

3.10.5 Standard Review Plan Evaluation

A summary describing the Standard Review Plan differences in regard to seismic and dynamic qualification of mechanical and electrical equipment is provided subsection 1.9.2.

3.10.6 Combined License Information Item on Experienced-Based Qualification

The Combined License information requested in this subsection has been totally addressed in APP-GW-GLN-006 (Reference 3) and APP-GW-GLR-031(Reference 4). No additional work is required by the Combined License applicant to address the Combined License information requested in this subsection.

The following words represent the original Combined License Information item commitment, which has been addressed as discussed above:

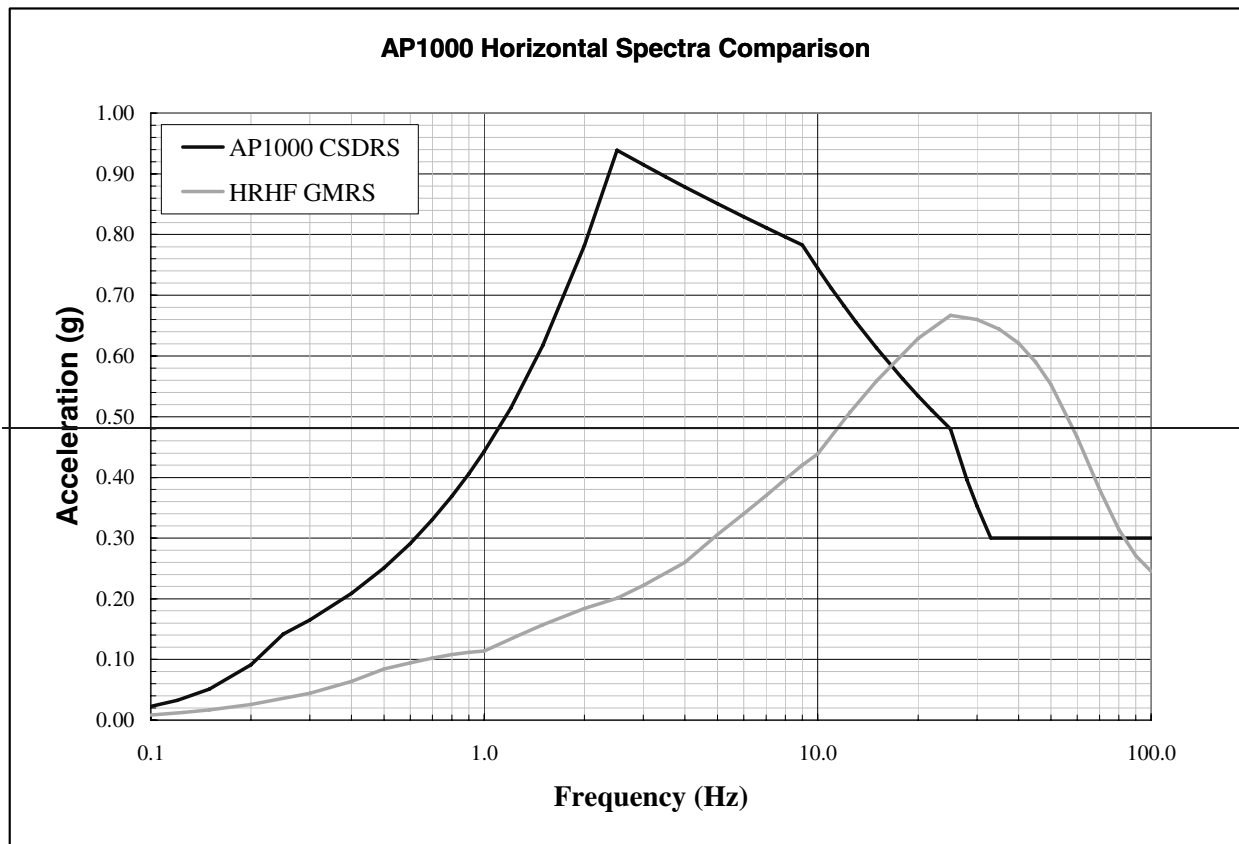
*[The Combined License applicant will address, as part of the Combined License application, identification of the equipment qualified based on experience and include details of the methodology and the corresponding experience data. The corresponding experience data for each piece of equipment will be included in the equipment qualification file.]**

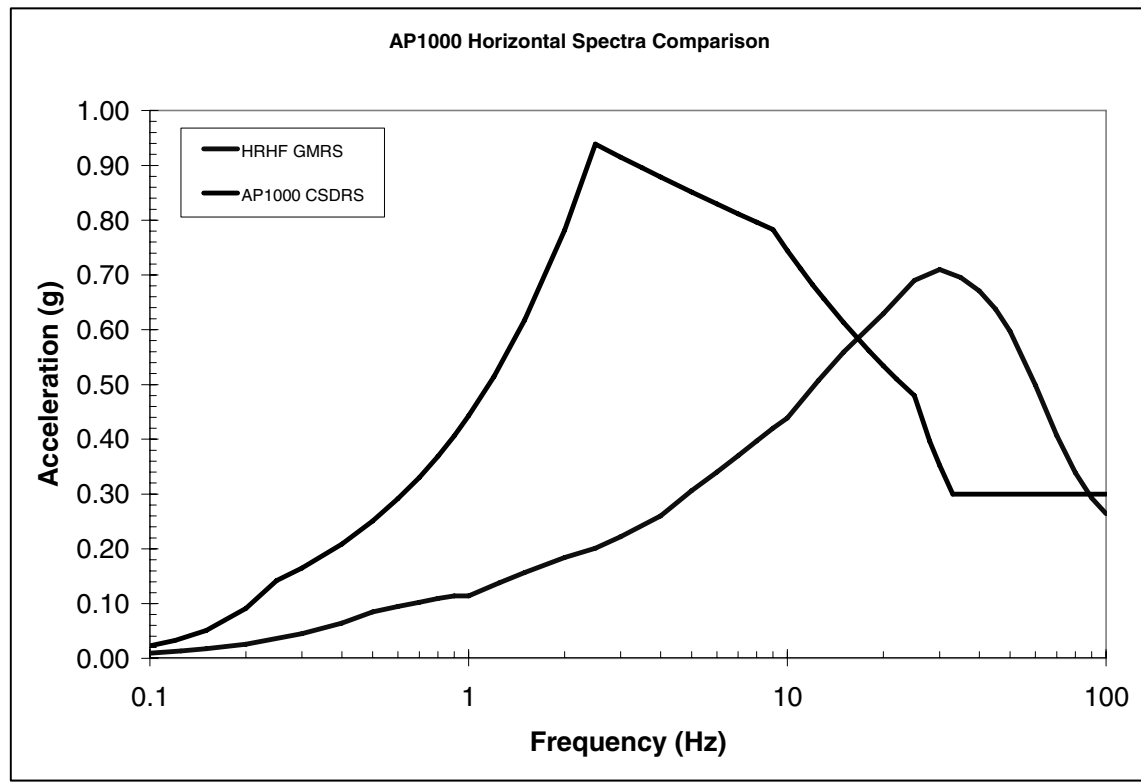
3.10.7 References

1. IEEE 344-1987, "Recommended Practices for Seismic Qualification of Class 1E Equipment for Nuclear Power Generating Stations."
2. IEEE 382-1996, "IEEE Standard for Qualification of Actuators for Power-Operated Valve Assemblies with Safety-Related Functions for Nuclear Power Plants."
3. APP-GW-GLN-006, "Methodology for Qualifying AP1000 Safety Related Electrical and Mechanical Equipment," Westinghouse Electric Company LLC.
4. APP-GW-GLR-031, "Seismic Qualification Using Test Experience-Based Method for AP1000 Safety Related Equipment," Westinghouse Electric Company LLC.
5. APP-GW-GLN-144, "AP1000 Design Control Document High Frequency Seismic Tier 1 Changes," Westinghouse Electric Company LLC.

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*NRC Staff approval is required prior to implementing a change in this material; see DCD Introduction Section 3.5.

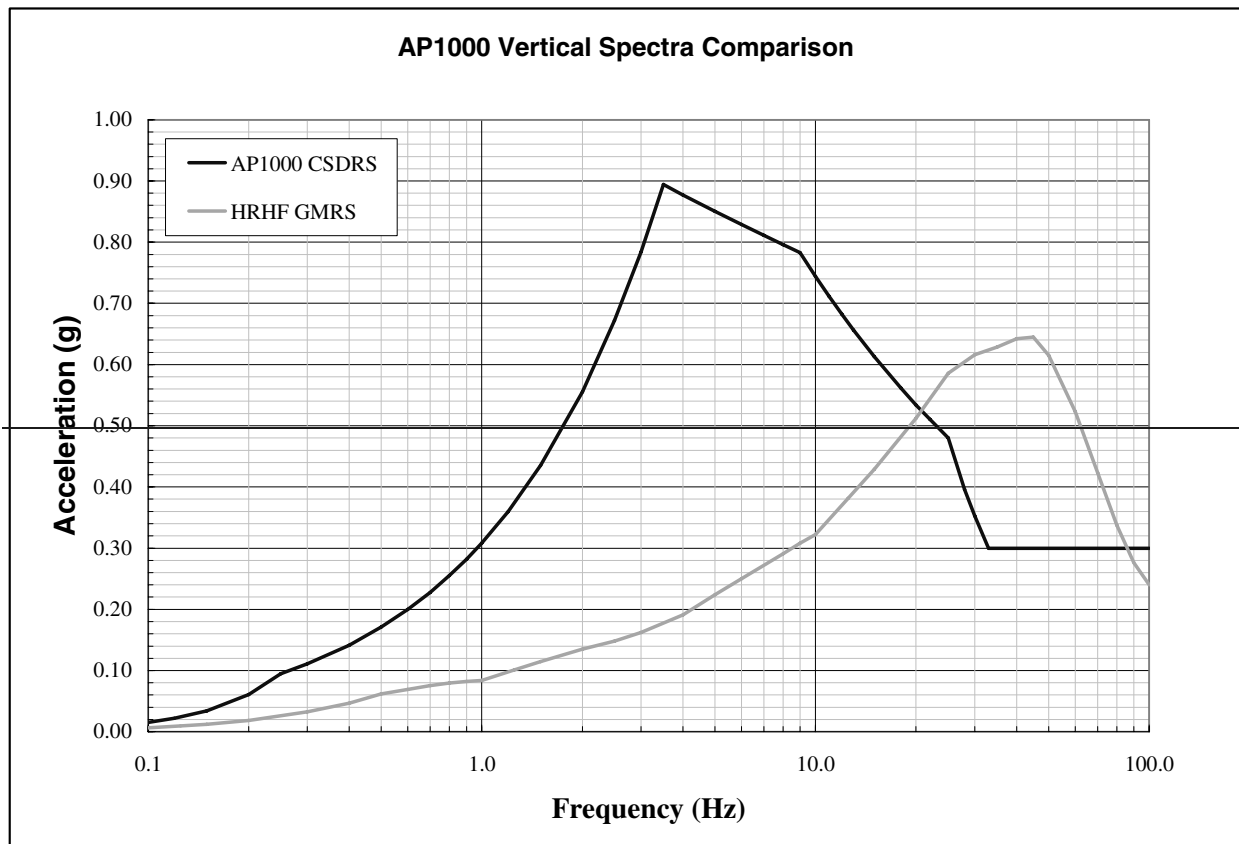




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Figure 3I.1-1

Comparison of Horizontal AP1000 CSDRS and HRHF GMRS



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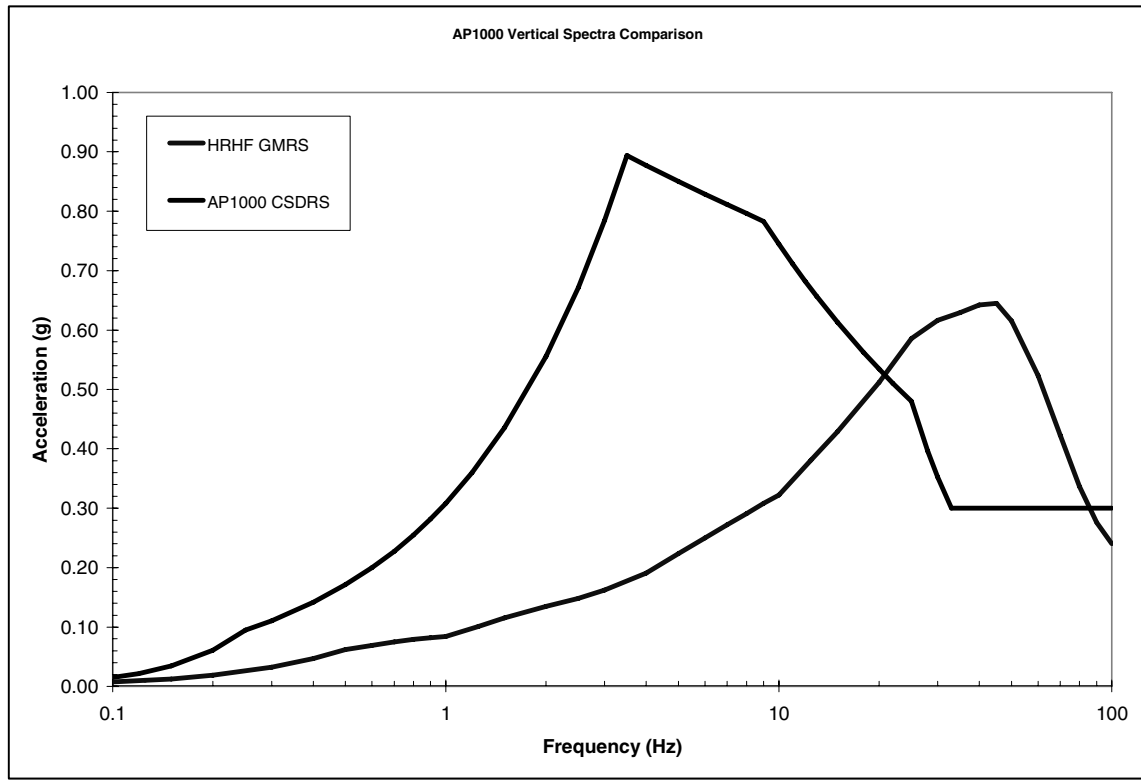


Figure 3I.1-2

Comparison of Vertical AP1000 CSDRS and HRHF GMRS