CC-AA-309-1001 Revision 3

ATTACHMENT **I**

Design Analysis Major Revision Cover Sheet Page 1 of **I**

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Page 1.0.0

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DIVISION: EPED FILE: 15B SYSTEM CODE: 6600

NOTE: FOR THE PURPOSE OF MICROFILMING THE PROJ. NO. FOR THE ENTIRE CALC. IS "9389-46"

\mathbf{I} REVISION SUMMARY **AND** REVIEW METHOD

A. Revision **0**

Revision 0, Initial issue, all pages.

This calculation supersedes the Calculation for Diesel-Generator Loading Under Design Basis Accident Condition, Calculation Number 7317-33-19-3. The major differences between Calculation 7317-33-19-3 and this calculation are as follows:

- 1) Dresden Diesel Generator (DG) surveillance test strip charts (Reference 23) show that the first LPCI pump starts almost 3.5 seconds after the closure of the DG output breaker. This is due to the under voltage (UV) relay disk resetting time. This revision shows that the 480V auxiliaries start as soon as the DG output breaker closes to the bus and the first LPCI pump starts approximately 3.5 seconds after the closure of the DG output breaker during Loss Of Offsite Power (LOOP) concurrent with Loss Of Coolant Accident (LOCA).
- 2) Created new ELMS-AC PLUS files for the DG for both Units 2 & 3 based on the latest base ELMS modified files D2A4.M24 and D3A4.M21, including all modifications included in Revisions 0 through 15 of Calculation Number 7317-43-19-1 for Unit 2 and all modifications included in Revisions 0 through 14 of Calculation 7317-43-19-2 for Unit 3. Utilization of the ELMS-AC PLUS program in this calculation is to maintain the loading data base and totaling the running KVA for each step.
- 3) Created Tables 1B & 2B for Unit 3. These tables did not previously exist.
- 4) Created Table 4A for Unit 2 and Table 4B for Unit 3 for totaling 480V loads starting KW/KVAR for determining starting voltage dip from the DG Dead Load Pickup Curve.

Revision 1:

Revised pages 1.0-1, 1.0-3, 2.0-1, 2.0-2, 2.0-3, 2.0-4, 4.0-7, 10.0-7 through 10.0-10, 10.0-12, 10.0-13, 10.0-20, 10.0-21, 10.0-23, 10.0-24, 11.0-1, 12.0-1, 14.0-6, F116, P2 and S94 as

REVISION SUMMARY (Cont'd)

Revision **I** (Cont'd'

indicated by the revision bar, no revision bar was used to identify the information shifted due to addition and respacing of the text. Added pages 1.0-2, 4.0-8, 14.0-7, F117 through F232, P3, P4 and **S95** through **S101.**

This revision analyzes the effect on the DG loading (both continuous and transient) due to the replacement of the existing LPCI Pump Motor 2B (700 HP) with a new 800 HP motor from Reliance Electric (see attachment **56)** per Exempt Change Request E 12-2-95-200 and Work Order No. D222021. LPCI Pump 2B is powered by 4KV Switchgear bus 23-1. This pump (i.e. second LPCI pump) will start automatically 5 seconds after LPCI pump 2A (i.e. first LPCI Pump) during a LOOP concurrent with LOCA. This revision also determine the accelerting time of the new LPCI pump motor 2B.

Revision 2

In this revision, the following pages were revised:

1.0-I, 1.0-2, 2.0-1 through 2.0-4, 4.0-7, 4.0-8, 10.0-1 through 10.0-12, 11.0-1 through 11.0-4, 12.0-1, 13.0-1, 14.0-1, 14.0-4, 14.0-6, 14.0-7, **C1,** C4, Attachment F (Pages FO through F112), **J1,** J5, Attachment M (Pages MO through M112), **PI**

the following pages were added:

1.0-3, 1.0-4, Section 10.1 (10.1-0 through 10.1-26), Section 10.2 (10.2-0 through 10.2-26), Section 15.0 (15.0-0 through 15.0-66)

the following pages were deleted:

10.0-13 through 10.049, F **113** through F232, M1 13 through M120, P2 through P4

However, for completeness, all text pages are being reissued to correct various typographical errors throughout the text. Revision bars have not been employed to indicate these types of changes.

This revision incorporates load parameter changes determined in Revision 18 of Calculation 7317-43-19-1 (Ref. 26), and Revision 16 of Calculation 7317-43-19-2 (Ref. 27) into the ELMS-AC datafile models used in this calculation to model diesel generator operation. The most critical of these changes is the CCSW Pump SHP change from 450 HP to 575 HP. These load parameter changes normalize the DG datafiles so that file updates can be made easily and accurately with the file comparison program ELMSCOMP. In addition to the

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Revision Summary (cont'd)

Revision 2 (Cont'd)

load/file changes, the text portion of the calculation dealing with determining starting kVA and motor start time for the 4.16 kV motors has been encoded into the MATHCAD Program. This will simplify any future changes, and decrease the possibility of calculation errors.

ELMSCOMP reports showing data transfers and so forth will be added in a new Section.

Please note: The BHP of CCSW Pump Motors is based on the nameplate rating of 500 HP with a 575 HP **@** 90⁰C Rise. This assumption of CCSW Pump Motor BHP loading requires further verification per References 26 and 27.

Revision 3

EC 364066 was created for Operability Evaluation # 05-005. This operability evaluation concluded that the diesel generator load calculation trips one Low Pressure Coolant Injection (LPCI) pump before the first CCSW pump is loaded onto the diesel, at which point the diesel is supplying one Core Spray pump. one LPCI and one CCSW pump. In contrast, station procedure DGA-12, which implements the manual load additions for LOCA/LOOP scenarios, instruct operators to load the first CCSW pump without tripping a LPCI pump. The procedure directs removal of a LPCI pump from the EDG only before loading of the second CCSW pump. In accordance with Corrective Action #2 of the Operability Evaluation, Calculations 9389-46-19-1,2,3 "Diesel Generator 3,2,2/3 Loading Under Design Basis Accident Condition" require revision to document the capability of the EDGs to support the start of the first CCSW pump without first tripping a LPCI pump.

This revision incorporates the changes resulting from EC 364066, Rev. 000. In addition, this revision replaces the ELMS-AC portions of the calculation with ETAP PowerStation (ETAP). All outstanding minor revisions were also incorporated. The parameters for valves 2-1501-22A/B and 3-1501-22A/B were also revised in the ETAP model to reflect the latest installed motors. Section 10 calculations previously performed using MathCad were replaced with MS Excel spreadsheets.

In this revision the following pages were revised:

2.0-4, **A10,** A12, B14, B15, E2, **01,** 02, \$16-S19, **S101**

In this revision the following pages were added:

Design Analysis Cover Sheet, 2.0-5, G1-G61, **Ni** -N61, S102-S113

In this revision the following pages were deleted:

1.0-4, Section XV, Attachment P

In this revision the following pages were replaced:

1.0-3, 2.0-1,2.0-2, 2.0-3, 3.0-1, 3.0-2, 4.0-1, 4.0-6, 4.0-7, 5.0-1, 7.0-1, 8.0-2, 8.0-4, 8.0-5, 9.0-1 through 9.0-5, 10.0-1 through 10.0-12, 10.1-1 through 10.1-26, 10.2-1 through 10.2-26, 11.0-1 through 11.0-4, 12.0-1, 14.0-1, 14.0-6, 14.0-7, **C1** through **C5,** F1-F112 replaced by F1-F113, **J1** through J5, M1-M112 replaced by M1-M113,

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1.0.0, 1.0-3, 2.0-1, 2.0-2, 2.0-3, 2.0.5, 3.0-1, 3.0-2. 4.0-7, 5.0-1, 7.0-1, 9.0-1 through 9.03, 9.0-5, 10.0-1, 10.0-9-10.0-12, 10.1-1, 10.1-3, 10.14, 10,1-10, 10.1-11, 10.1-17 through 10.1-20, 10.1-22, 10.1-24 through 10.1-25, 10.2-1, 10.2-3 through 10.2-6, 10.2- 8, 10.2-10, 10.2-11, 10.2-17 through 10.2-20, 10.2-22, 10.2-24 through 10.2-26, 11.0-1, 11.0-3, 12.0-1, 13.0-1,14.0-1, 14.0-7, **C1,** F1-F113, G1-G61 with G1-G57, **JA,** MI-M113, **NI** -N61

CALCULATION TABLE OF CONTENTS

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CALCULATION TABLE OF **CONTENTS** (Continued)

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File Descriptions (cont'd)

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File Descriptions (cont'd)

Revision 4

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III PURPOSEJSCOPE

A. Purpose

The purpose of this calculation is to ensure that the Dresden Diesel Generator has sufficient capacity to support the required loading during the maximum loading profile as determined in the Calculation Results section.

The purpose of this calculation includes the following (these apply when **DG** 2/3 is powering either Unit 2 or Unit 3):

- 1) Determine automatically actuated devices and their starting KVA at each step for the ac electrical load when the **DG** is powering the safety related buses.
- 2) Develop a Time versus Load profile for the **DG** when the **DG** is powering the safety related buses.
- 3) Compare the maximum loading in ETAP for the DG load profile against the capacity of the **DG.**
- 4) Determine the starting voltage dip and one second recovery voltage at the DG terminals for initial loading and each 4000V motor starting step.
- 5) Evaluate the control circuits during the starting transient voltage dip.
- 6) Evaluate the protective device responses to ensure they do not inadvertently actuate or dropout during the starting transient voltage dip.
- 7) Evaluate the travel time of MOVs to ensure they are not unacceptably lengthened by the starting transient voltage dips.
- 8) Determine the starting duration of the automatically starting 4kV pump motors.
- 9) Ensure the loading on the EDG is within the 2000hr rating should the frequency on the machine increase to its maximum allowable value. R_4
- 10) Determine the minimum power factor for the long term loading on the EDG.

B. Scope

The scope of this calculation is limited to determining the capability of the **DG** to start the sequential load (with or without the presence of the previous running load as applicable), without degrading the safe operating limits of the **DG** or the powered equipment & services. The minimum voltage recovery after 1 second following each sequential start will be taken from the **DG** dead load pickup characteristics and compared to the minimum recovery required to successfully start the motors and continue operation of all services.

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Input Data (cont'd): Outbd PF Press Prot Recirc Rm Rx Bldg **-** SBGT **-** Ser **-** SWGR **-** Stm **-** Suct **-** TB Turb **-** UPS Vlv Wtr Xfmr Outboard Power Factor Pressure Protection Recirculation Room Reactor Building Standby Gas Treatment System Service **Switchgear** Steam Suction Turbine Building Turbine Uninterruptible Power Supply Valve **Water Transformer**

Input Data (cont'd):

B. Emergency Diesel Generator Nameplate data for the Dresden Unit 2/3 is as follows (Reference 24)

Input Data (cont'd)

C. Dead Load Pickup Capability (Locked Rotor Current) - Generator Reactive Load Vs % Voltage Graph #SC - 5056 by Electro - Motive Division (EMD) [Reference 13].

This reference describes the dead load pickup capability of the MP45 Generating Unit. The curve indicates that even under locked rotor conditions an MP45, 2750 kw generating unit will recover to 70% of nominal voltage in **1** second when a load with 12,500 KVA inrush at rated voltage is applied. This indicates that the full range of the curve is usable. Also, page 8 of the purchase specification K-2183 (Reference 12) requires that the Generator be capable of starting a 1250 hp motor (starting current equal to 6 times full load current). The vertical line labelled as "Inherent capability" on the Dead Load Pickup curve is not applicable for the Dresden Diesel Generators because they have a boost system associated with the exciter. Per Reference 40 of this calculation, Graph #SC-5056 is applicable for Dresden Diesel Generators.

- D. Speed Torque Current Curve (297HA945-2) for Core Spray Pump by GE (Reference 14).
- E. Speed Torque Current Curve (#257HA264) for LPCI Pump by GE (Reference 15).
- F. Dresden Re-baselined Updated FSAR Table 8.3-3, DG loading due to loss of offsite ac power (Reference 30)
- G. Table **1A:** Automatically ON and OFF devices during LOOP Concurrent with LOCA when the DG **2/3** is powering the Unit 2 Division I loads (Attachment A).
- H. Table 2A: Affects of Voltage Dip on the Control Circuits during the Start of Each Large Motor when DG 2/3 is powering Unit 2, Division I loads (Attachment **8).**
- I. Table 4A: KW/KVAR/ KVA loading tables for total and individual starting load at each step when DG **2/3** is powering Unit 2, Division I loads (Attachment C).
- J. Table 1B: Automatically ON and OFF devices during LOOP Concurrent with LOCA when the DG 2/3 is powering the Unit 3 Division I loads (Attachment H)
- K. Table 2B: Affects of Voltage Dip on the Control Circuits during the Start of Each Large Motor when DG *213* is powering Unit 3, Division I loads (Attachment I).
- L. Table 48: KW/KVAR/ KVA loading tables for total and individual starting load at each step when DG **2/3** is powering Unit 3, Division I loads (Attachment J).

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V **ASSUMPTIONS**

- 1) **MCC** control transformers (approximately **150VA** 200VA each) generally have only a small portion of their rating as actual load and can be neglected.
- 2) The Diesel Fuel Oil Transfer Pump is shown in this calculation as operating as soon as voltage is available on the MCC bus, but this is not the actual case as the pump responds to low day tank level which is normally full prior to DG starting. This is conservative and compensates for Assumption 1.
- 3) Individual load on buses downstream of 480/120V transformer have not been discretely analyzed to determine transformer loading. This transformer load on the 480V bus is assumed to be the rating of the distribution transformer or an equivalent three-phase loading for single phase transformers, which is conservative.
- 4) When Locked Rotor Currents are not available, it is considered 6.25 times the full load current. This is from S&L Standard ESC-165 and is reasonable and conservative.
- 5) For large motors (>250HP), the starting power factor Is considered to be 20%. This is typical for large HP motors and does not require verification.
- 6) The load on the diesel generator is assumed to increase by 6% when the frequency of the machine is 2% above its nominal value. A majority of the load consists of large centrifugal pumps. The break horsepower of these pumps varies as the cube of the speed. Thus, a 2% increase in speed R_4 corresponds to a 6% increase in load **(1.023)** (Ref. 70). Note that these pumps will operate on a different point on the performance curve and the BHP may actually increase less than 6%. Therefore, a 6% increase is conservative.

7) For determining starting time for the large motors, the starting current is assumed to be constant throughout the evaluation. Although the speed-torque curve shows a decrease in current with speed as is expected, using a constant current will simplify the starting time evaluation. Motor starting time would be somewhat less if the speed-current characteristics were included. This assumption of CCSW Pump Motor starting current is conservative.

The above assumptions 1, 2, 3, 4. 5, 6 and 7 do not require verification.

VI. ENGINEERING JUDGEMENT

- 1.) Based on engineering judgement an efficiency of 90% is to be used to convert the cummulative HP to an equivalent KW for Table 8.3-3 of the Dresden Re-baselined Updated FSAR, Revision 0. This is considered conservative because the majority of this load consists of 1-4kV motor. Also, this result is only to be used for a comparison.
- 2.) The swing bus transfer circuits for MCC 28/29-7 and MCC 38/39-7 have a time delay relay with a setting of 20s (Reference 7). Based on engineering judgment a tolerance of ±5 seconds will be used for this time delay relay. The LPCI Swing MCC 28/29-7 (38/39-7) is normally fed from Switchgear 29 (39). However, on failure of the dedicated DG to start, this MCC will transfer to Switchgear 28 (38) approximately **15-** 25 seconds (i.e. 5-15 seconds after diesel breaker closes) after loss of Switchgear 29 (39) voltage. This is conservative because the loads starting on MCC 28/29-7 or MCC 38/39-7 can be shown starting at the most conservative time between 5s and 15s after DG breaker closure.
- 3.) For the purposes of this calculation, a LOCA is defined as a large line break event. This is a bounding case, as in this event, the large AC powered ECCS-related loads will be required to operate in the minutes of the event. This is conservative, as in the event of a small or intermediate line break scenario, there will be more time between the LOCA event and the low pressure (i.e. AC) ECCS system initiation.

VIII. LOAD SEQUENCING OPERATION

A. Load Sequencing During LOOPILOCA

By reviewing the Table 1 schematic drawings, it was determined that there are three automatic load starting steps, which start the two LPCI Pumps sequentially, followed by the Core Spray Pump. Also, there is another inherent step which delays the large pumps from starting by 3 seconds. This delay is due to the undervoltage relay recovery time, which is interlocked with the timers for the large pumps.

This calculation considers that all the devices auto start from an initiating signal (pressure, level, etc.) or from a common relay start at the same time (unless a timer is in the circuit). It considers all devices are in normal position as shown on the P&ID. It was found from discussion with CornEd Tech. Staff and the Control Room Operators that valves always remain in the position as shown on the design document.

For long term cooling, manual operation is required to start a Containment Cooling Service Water pump.

1) Automatic Initiation of DG during LOOP concurrent with LOCA

The **DG** will automatically start with any one of the signals below:

- 2 psig drywell pressure, or
- -59" Reactor water level, or
- Primary Under voltage on Bus 23-1 (33-1), or
- Breaker from Bus 23 (33) to Bus 23-1 (33-1) opens, or
- **Backup undervoltage on Bus 23-1 (33-1) with a 7 second time delay, with an** additional 5 minute time delay if there is a LOCA.

Upon loss of *all* normal power sources, **DG** starts automatically and is ready for loading within 10 seconds (Reference 7, page 8.3-14). When the safety-related 4160V bus is de-energized, the **DG** automatically starts and the **OG** output breaker closes to energize the *bus* when the DG voltage and frequency are above the minimum required. Closure of the output breaker, interlocks ECCS loads from automatically reclosing to the emergency bus, and then the loads are started sequentially with their timers. This prevents overloading of the **DG** during the autostarting sequence.

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LOAD SEQUENCING OPERATION (cont'd)

The LPCI Swing MCC 28/29-7 (38/39-7) is normally fed from Switchgear 29 (39). However, on failure of the dedicated **DG** to start, this MCC will transfer to Switchgear 28 (38) approximately 15 - 25 seconds after loss of Switchgear 29 (39) voltage (Reference 7, page 8.3-13 and engineering judgement). For conservatism, this calculation uses the time range of the transfer delay and applies it to coincide with the greatest transient voltage dip caused by the automatically starting 4000V motors.

Automatically activated loads on the DG during LOOP concurrent with LOCA are identified in Table **1A** & lB.

- 2) Automatic Load Sequence Operation for LOOP with LOCA
	- **0** When the DG automatically starts and its output breaker (at Bus 23-1 or 33-1) closes to Switchgear 40, the diesel auxiliaries and certain MOVs start operating, and the UV relay starts its reset recovery timing.
	- As soon as UV relays (IAV 69B) complete their reset, the first LPCI pump starts.
	- ***** 5 seconds after UV relays (IAV 69B) reset, the second LPCI pump starts. At the same time, associated valves and equipment with the LPCI pump start operating.
	- **0** 10 seconds after the UV relays (IAV 69B) reset, the Core Spray pump starts. At the same time, associated valves and equipment with the Core Spray pump start operating.
- 3) Manual actuation required for long term cooling

After 10 minutes of continued automatic operation of the LPCI Pumps and Core Spray system, the operator has to do the following actions to initiate long term cooling (see References 56 and 57):

- Shed and lock out appropriate loads on Bus 23 (or 33).
- At this point the operator can manually close the breaker to the switchgear bus and start one of the.CC Service Water pumps, and also opens the CC Heat Exchanger Service Water Discharge Valve.
- Turn off one of the LPCI pumps.
- After the first CCSW Pump is started and one of the LPCI pumps is shut off, the operator will start the second CCSW Pump.

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B. Description of sequencing for various major systems with large loads

1) LPCIICC - LPCI Mode

LPCI/CC

LPCI/CC is used to prevent a failure of fuel cladding as a result of various postulated LOCAs for break sizes ranging from those for which the core is adequately cooled by HPCI system alone, up to and including a DBA (Reference 6).

LPCI Mode

The LPCI mode of the LPCI/CC is to restore and maintain the water level in the reactor vessel to at least two-thirds of core height after a LOCA (Ref. 6).

i) Initiation of LPCI occurs at low-low water level (-59"), low reactor pressure (<350 psig), or high drywell pressure (+2 psig).

- CC Service Water pumps are tripped and interlocked off.
- * The Heat Exchanger Bypass Valve 1501-1 **1A** receives an open signal and is interlocked open for 30 seconds and then remains open.
- Containment Cooling valves 1501-18A, 19A, 20A, 27A, 28A, and 38A are interlocked closed.
- An injection signal closes the Recirculation Pump Discharge Valve 202-5A.
- then reactor pressure decreases to 350 psig or less, the following occurs:

1.) LPCI pumps will start. Under LOOP concurrent with LOCA, LPCI Pump 2A (3A) will start after the closure of the DG output breaker following the UV relay (IAV 69B) reset time. Five (5) seconds following the UV relay (IAV 69B) reset, LPCI Pump 2B (38) will auto start. If the initiation signal was low-low water level, the pumps will not start until the reactor pressure reaches <350 psig or they receive a start signal from ADS showing low water level for 8.5 minutes continuous.

ii) The following valves respond to initiation of LPCI/CC - LPCI mode of operation:

■ LPCI injection valves (1501-21A, 21B, 22A & 22B) - LOOP selection circuitry will sense a damaged loop and will close one of the LPCI outboard valves

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IX METHODOLOGY

A Loading Scenarios:

There are three different abnormal conditions on which the Emergency Diesel Generator can be operating:

- 1) Loss of AC Offsite Power
- 2) Safe Shutdown Due to Fire
- 3) LOOP concurrent with LOCA

The above scenarios will be compared for total loading and heaviest sequential loading to determine worst case scenario and why the scenario was chosen.

B. Continuous Loading Evaluation

The following Attachments are used to determine and develop the continuous loading of the DG:

- **0** Table 1
- **&** ETAP for the load summary of the loading of the DG at selected steps of automatically and manually started loads.

The loading based on the maximum loading scenario, including cumulative proposed modifications to the loading, will be tracked in the ETAP data file. In all of the cases that will be analyzed, the proposed loading will be greater than that of the existing loading, since all modified load reductions will remain at previous loads until installed and changed to existing. Thus the capability of the DG to pickup the modified loading and operate within the safe operating limit of the DG will envelope the existing loading.

For all of the various steps in the DG load profile, the ETAP total load will be the summation of the steady state load of all running and starting services for the starting step being analyzed.

The ETAP model was revised to mimic the ELMS-AC data files that were part of the calculation prior to Revision 003. Scenarios were created in ETAP to model the various loading steps in the DG load profile as loads are energized and de-energized.

The scenarios used to model the **DG** loading in ETAP are listed in the table below. The scenarios use one of three loading categories named "DG Ld 0 CCSW", DG Ld 1 CCSW" and "DG Ld 2 R⁴ CCSW. These loading categories were created by duplicating loading category "Condition 3". In cases where a load was identified in loading category "Condition 3" as zero and the load is energized during the diesel loading scenario, the loads were modeled as 100% in the "DG Loading" category. If the bhp for a given load in the previous DG data files was different than that in load condition 3, it was revised to match the bhp value in the previous ELMS-AC data files for this calculation. Breakers were added for various loads that change state as part of the **DG** load profile. No specific breaker data was entered as these breakers are only used as switches. The breakers were opened and closed as required creating configurations which duplicate the loading on the DG for each load step (load condition) previously captured in the ELMS-AC program. The three loading categories are identical except the BHP values associated with the CS, LPCI and CCSW pumps are varied. **"DG Ld 0 CCSW"** represents the first 10 minutes of the accident where no CCSW pumps R_4 are operating. "DG Ld **1** CCSW" reflects reduced CS and LPCI loading values after 10 minutes and a 115% bhp loading value for a single CCSW pump in operation. 'DG Ld 2 CCSW" is the same as **"DG** Ld 1 CCSW" except CCSW bhp values are reduced to reflect operation of both pumps.

CALC NO. 9389-46-19-3 REVISION 004 **PAGE NO.** 9.0-2 Four study cases were created for use with this calculation: DG.0_CCSW, **DG_I** CCSW, DG_2 CCSW and DG_Vreduced. The first three study cases use the corresponding similarly named loading categories and the DG_Vreduced case uses the DG_0_CCSW loading category as R_4 all runs correspond to less than 10 minutes into the event. The generating category was set to "Nominal" and "Gen Min' for the first three study cases and DGVreduced study cases respectively. The "2/3" diesel voltage was set to 100% and 54% for the "Norninal" and "Gen Min" generation categories respectively. 54% was chosen as it envelopes the lowest expected DG terminal voltage. This value is supported by the calculations performed in Section 10. In each of these study cases, the Newton Raphson method of load flow was selected with the maximum number of iterations set at 99 and the precision set to 0.000001. Only the initial bus voltages were chosen to be updated as a result of execution of the load flow. No diversity factors or global tolerances were used. The scenario wizard in ETAP was used to set up the configuration, study case, and output report for each time step in the DG load profile. The study wizard was used to group and run all of the scenarios. Each scenario was run three times in a row as part of each study macro. The results can vary depending upon the order that the study cases are run as certain calculations within ETAP are run using the initial bus voltages in the bus editor. The multiple runs assure a unique solution is reached regardless of the bus voltages in the bus editors prior to each load flow run. The precision for each study case is not accurate enough to guarantee a unique solution. The scenarios used to calculate the loading on the **DG** during each time step are listed below along with the relevant ETAP settings, configurations, etc. Note that these same scenarios are used in both the Unit 2 and Unit 3 ETAP files as the 2/3 EDG is modeled in each file.

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METHODOLOGY (cont'd)

The starting kW/kVAR for the starting loads in each step will be calculated and tabulated separately in Tables 4A **&** 4B.

The reduced voltage ETAP files are run for each timeframe immediately preceeding a large motor start with the exception of the last CCSW pump which is bounded by a start of the 1st CCSW pump. The reduced DG terminal voltage is equal to or lower than the voltage dip during the most severe starting step. The reduced terminal voltage will be used to determine an incremental increase in current caused by the running loads operating at lower than rated voltage.

The difference in current will be reflected as the equivalent kw/kvar at full voltage (at the power factor of the running loads) and added to the total starting kw/kvar of the starting loads to determine the net starting KVA.

The power factor of the running load is taken from ETAP.

Calculating the incremental KVA for previously running loads is done as follows:

 I_{Cum 6100% = Taken from ETAP output report from study cases run at nominal voltage $I_{\text{R}4}$

 $l_{Cur\alpha\text{reduced voltage}} =$ Taken from ETAP output report from DG_Vreduced study cases

 $\Delta I = I_{\text{Curr@lreduced voltage}} - I_{\text{Curr@l100%}}$

AKVA **= Al** x **43** x 4.16KV

Conservatively, the worst voltage dip case due to the presence of running load will be applied to all large motor starting cases. The previous calculation revisions show that the largest voltage dip occurs when the Core Spray Pump starts. Revision 10 of Calculation 7317-33-19-3 shows that the voltage dip is 54.3% of bus rated voltage for Unit 2 and 54.5% of bus rated voltage for Unit 3 when the first LPCI Pump is starting. For conservatism, 54.0% (i.e. 2246V) of bus rated voltage will be used for all running load conditions.

The voltage dip and one second recovery at the DG for the initial start at breaker closing is determined from the EMD's Dead Load Pickup Curve #SSC-5056 (Ref. 13) by using the total starting KVA value from Table 4. Following the initial start, the total KVA is determined by vectorially adding the step starting load KW/KVAR from Table 4, the Δ KVA changed to KW/KVAR of the running load of the previous scenario in the ETAP file, and the starting KW/KVAR of the 4000V motor

that is starting to determine the total starting KVA, which is then used to determine the voltage dip and one second recovery at the DG terminals.

The Dead Load Pickup Curve provides initial voltage dip and recovery after 1 second following a start based on the **DG** transient starting load. The curve includes the combined effect of the exciter and the governor in order to provide recovery voltages. The voltage dip and recovery analysis utilizes the results of dynamic **DG** characteristics reflected in the manufactureres curve. Though the curve shows voltage recovery up to 1 second, the voltage will continue to improve after 1 second due to exciter and governor operation. The **DG** Strip Chart for the surveillance test (Ref. 23) shows the voltage improvement past I second.

METHODOLOGY (Cont'd)

that is starting to determine the total starting KVA, which is then used to determine the voltage dip and one second recovery at the DG terminals.

The Dead Load Pickup Curve provides initial voltage dip and recovery after 1 second following a start based on the DG transient starting load. The curve includes the combined effect of the exciter and the governor in order to provide recovery voltages. The voltage dip and recovery analysis utilizes the results of dynamic DG characteristics reflected in the manufacturer's curve. Though the curve shows voltage recovery up to 1 second, the voltage will continue to improve after **I** second due to exciter and governor operation. The DG Strip Chart for the surveillance test (Ref. 23) shows the voltage improvement past **I** second.

To determine motor starting terminal voltage, the cable voltage drop is calculated using the locked rotor current at rated voltage. This is conservative since the locked rotor current is directly proportional to applied voltage.

0. Analysis of control circuits during motor starting transient voltage dip.

When the DG starts a large motor, the momentary voltage dip can be below 70% of generator rated voltage. There is a concern whether momentary low voltage could cause certain control circuits to drop-out. Table 2 of this calculation analyzes the effect of an ac momentary voltage dip on the operation of the mechanical equipment. This table analyzes the momentary voltage dip at 5 seconds & 10 seconds after UV reset; and 10 minutes and after for its effect on the operation of mechanical equipment.

E. Protective device evaluation and MOV operating time effects during motor starting transient voltage dip

The voltage recovery after one second will be evaluated for net effect on the protective devices The duration of starting current is expected to be shorter than operation from offsite power source because of better DG voltage recovery. Because protective devices are set to allow adequate starting time at motor rated voltage and during operation from offsite power, protective device operation due to overcurrent or longer operating time is not expected to be a concern when operating from the DG power during LOOP concurrent with LOCA.

METHODOLOGY (Cont'd)

F. Methodology for Determining Starting Time of Large Motors. (Ref. 42)

To determine large motor starting times, the time needed for the motor to accelerate through an increment of motor speed will be found. This will be accomplished by determining from motor and load speed-torque curves net accelerating torque (i.e. the difference between the torque produced by the motor and the torque required by the load) for each increment of speed. Using the combined motor and load inertia, the time needed to accelerate through the increment of speed can be calculated. All the time intervals will be summed to obtain a total motor starting time. Since motor torque is directly proportional to the square of applied terminal voltage, values obtained from the 100% rated voltage speed-torque curve will be adjusted downward for lower than rated applied terminal voltage. And, since this calculation determines for each motor start an initial voltage and a recovery voltage after 1 second, these two values will be used when adjusting motor torque for applied terminal voltage (i.e. For the initial speed increment and all subsequent increments occunrig **I** second or less from the beginning of the *motor* start period, the initial voltage value will be used to determine motor torque. All later increments will use the 1 second recovery voltage value.) The time for each speed increment *will* be found using the following process:

1) At each speed increment, the motor torque will be found at the initial or **I** second recovery motor terminal voltage, as appropriate this will be done using the equation:

T = [(Vterm)² / (Vrated)²] x Motor Base Torque x 100% Voltage Motor Torque from speed-torque curve

- 2) At each speed increment, load torque will be obtained from the load speedtorque curve.
- 3) The torque of the load is subtracted from the determined motor torque to obtain the net accelerating torque.
- 4) Finally the time fo accelerate through an RPM increment is found using the following equation:

t **=** (WK² (pump **+** motor) x RPM increment] **1** (307.5 x Net Accelerating Torque)

5) All the time increments are summed to obtain the total motor starting time.
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X **CALCULATIONS AND RESULTS**

The following set of Calculations and Results are for the condition when DG 2/3 is powering the Unit 2 buses.

A. Loading Scenarios:

Dresden Re-baselined Updated FSAR, Rev. 0, loading table 8.3-3 shows that the maximum DG 2/3 loading during LOOP is only 1552 **kW.**

Dresden Station Fire Protection Reports - Safe Shutdown Report dated July 1993, Table 3.1-1, shows that the maximum loading on DG 2/3 is 1541 kW, (Note: Note 3 of Table 3.1-1 was considered when calculating this loading).

Also, the Dresden Re-baselined Updated FSAR, Rev. **0,** Figure 8.3-6 shows that the maximum loading on DG 2/3 during LOOP concurrent with LOCA is 2328 kW

By comparing all three conditions, it is concluded that the combination of LOOP concurrent with LOCA is the worst case of DG loading. Therefore, LOOP concurrent with LOCA scenario was analyzed in detail in this calculation.

The load values for the three conditions stated above are historical values and are used only for comparison of load magnitudes to determine the worst-case loading scenario for the Diesel Generator. For currently predicted loading values on the diesel generator, see Section X1, Subsection A, "Continuous Loading of the Diesel Generator'.

B. Continuous Loading

Table 1A was developed to show loads powered by the DG and the loads that will be automatically activated when the Bus 23-1 (DG output) breaker closes to 4-kV Bus 40 following LOOP concurrent with LOCA. The ETAP model was then set up using the **"DG Ld 0 CCSW",** R_4 DG Ld **I** CCSW" and "DG Ld 2 CCSW" loading categories and the configurations to model the loads as described in the methodology section. The $2nd$ CCSW Pump is manually started and a LPCI Pump is turned off to stay within the DG capacity.

Also, for conservatism the Diesel Fuel Oil Transfer Pumps are shown as operating from 0 seconds, even though these pumps will not operate for the first few hours because the Day Tank has fuel supply for approximately four hours.

C. DG Terminal Voltages under Different Loading Steps

Figure 2A Load vs Time profile of starting loads for the DG was developed from Table **IA** showing loads operating at each different time sequence. The values for the running loads in kW/kVAR/kVA were taken from the appropriate ETAP output report, and the starting values for 480V loads are calculated in Table 4A. The following is a sample calculation for LPCI Pump 2A showing the determination of motor starting kVA and starting time. It is shown for demonstrative purposes only (based'on Rev. 3). Actual calculations *for* the *Unit* 2 4.16 kV motors *is* contained R4 in Section 10.1. This sample calculation is based on use of the ETAP program.

X. **CALCULATIONS AND** RESULTS (cont'd)

FOR DEMONSTRATION ONLY)

R3

Notes for the table above:

- 1. Motor Torque in above table is from GE drawing 257HA264 (Reference 15).
- 2. Motor Torque in above table is read from mid-point of applicable speed range.
- 3. Motor Torque in ib-ft is obtained by multiplying the torque from the curve by motor at applicable voltage.
- -4. Pump torques are from GE Curve 257HA264 (3% bypass) (Reference 15) and then multiplied by base torque of motor.
- 5. Net Torque is motor torque minus pump torque, both in lb-ft.
- 6. Time in Seconds to accelerate through an RPM Increment

IWK ² (PumD **+** Motor) x RPM Increment] (307.5 x Net Torque)

X. CALCULATIONS AND RESULTS (cont'd)

The following table summarizes the motor starting times from Section 10.1.

D. Control Circuit Evaluation for Voltage Dips

The voltage recovery is more than 87% after one second following the Core Spray motor start. The voltage will continue to improve after one second due to the exciter and the governor characteristics. These voltages during motor starting period (after the initial dip) are much better than the voltages expected during the operation from the offsite source. Table **2A** has evaluated the effects on the control circuits of all services on the DG and has determined any transient effect during the short initial voltage dip and no lasting effects have been identified.

E. Protective Device Operation during Voltage Dips

The voltage recovery is more than 87% after one second following the Core Spray motor start. The voltage will continue to improve after one second due to the exciter and the governor characteristics. These voltages during motor starting period (after the initial dip) are much better than the voltages expected during the operation from the offsite source. Therefore, the duration of starting current is shorter than operation from offsite power source. Because protective devices are set to allow adequate starting time at motor rated voltage and during operation from offsite power, protective device operation due to overcurrent is not a concern when operating from the DG power during LOOP concurrent with LOCA.

R₃

R3

R3

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X, **CALCULATIONS AND RESULTS** (cont'd)

F. Results of calculations

The results of the calculation included in Section 10.1 show that the minimum voltage drop to the **DG** powered buses occur when the Core Spray Pump starts. The table below shows the starting (at **0.1** sec.) voltages and recovery voltages after 1 second following the start at Bus 23-1.

During LOOP concurrent with LOCA there is a 5 second time delay from the start of the first LPCI Pump to the start of the second LPCI Pump. Starting time calculations for the LPCI Pumps show that both the pumps accelerate to full speed in under 4 seconds. Therefore by the time the second LPCI Pump starts, the first LPCI Pump is at full speed (i.e. running load). There is also a 5 second time delay from the start of the second LPCI Pump to the start of the Core Spray Pump. Therefore, by the time the Core Spray pump starts, the second LPCI Pump is at full speed.

R4

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X. CALCULATIONS AND RESULTS (cont'd)

The following set of Calculations and Results are for the condition when DG **2/3** is powering the Unit 3 buses.

A. Loading Scenarios:

Dresden Re-baselined Updated FSAR, Rev. 0, loading table 8.3-3 shows that the maximum DG **2/3** loading during LOOP is only 1552 **kW.**

Dresden Station Fire Protection Reports - Safe Shutdown Report dated July 1993, Table 3.1-1, shows that the maximum loading on DG 2/3 is 1541 kW, (Note: Note 3 of Table 3.1-1 was considered when calculating this loading).

Also, the Dresden Re-baselined Updated FSAR, Rev. 0, Figure 8.3-7 shows that the maximum loading on DG 2/3 during LOOP concurrent with LOCA is 2343 kW.

By comparing all three conditions, it is concluded that the combination of LOOP concurrent with LOCA is the worst case of DG loading. Therefore, LOOP concurrent with LOCA scenario was analyzed in detail in this calculation.

The load values for the three conditions stated above are historical values and are used only for comparison of load magnitudes to determine the worst-case loading scenario for the Diesel Generator. For currently predicted loading values on the diesel generator, see Section XI, Subsection A, "Continuous Loading of the Diesel Generator".

B. Continuous Loading

Table 1 B was developed to show loads powered by the DG and the loads that will be automatically activated when the Bus 33-1 (DG output) breaker closes to 4-kV Bus 40 following LOOP concurrent with LOCA. The ETAP model was then set up using the "DG Ld 0 CCSW", R_4 **"DG** Ld 1 CCSW" and "DG Ld 2 CCSW" loading categories and the configurations to model the loads as described in the methodology section. The **2"d** CCSW Pump is manually started and a LPCI Pump is turned off to stay within the DG capacity.

Also, for conservatism the Diesel Fuel Oil Transfer Pumps are shown as operating from 0 seconds, even though these pumps will not operate for the first few hours because the Day Tank has fuel supply for approximately four hours.

C. DG Terminal Voltages under Different Loading Steps

Figure 2B Load vs Time profile of starting loads for the DG was developed from Table 1B showing loads operating at each different time sequence. The values for the running loads in kW/kVAR/kVA were taken from the appropriate ETAP output report, and the starting values for 480V loads are calculated in Table 4B. The calculations included in Section 10.2 show the determination of the motor starting kVA and starting time for Unit 3, 4 kV motors. Calculations performed in Section 10.2 follow the sample calculation presented for a Unit 2 LPCI Pump motor.

X. **CALCULATIONS AND RESULTS** (cont'd)

The following table summarizes the motor starting times from Section 10.2.

E. Control Circuit Evaluation for Voltage Dips

The voltage recovery is at least 87% after one second following the Core Spray motor start. The voltage will continue to improve after one second due to the exciter and the governor characteristics. These voltages during motor starting period (after the initial dip) are much better than the voltages expected during the operation from the offsite source. Table 2B has evaluated the effects on the control circuits of all services on the DG and has determined any transient effect during the short initial voltage dip and no lasting effects have been identified.

R4

R4

F. Protective Device Operation during Voltage Dips

The voltage recovery is at least 87% after one second following the Core Spray motor start. The voltage will continue to improve after one second due to the exciter and the governor characteristics. These voltages during motor starting period (after the initial dip) are much better than the voltages expected during the operation from the offsite source. Therefore, the duration of starting current is shorter than operation from offsite power source. Because protective devices are set to allow adequate starting time at motor rated voltage and during operation from offsite power, protective device operation due to overcurrent is not a concern when operating from the DG power during LOOP concurrent with LOCA.

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X. **CALCULATIONS AND RESULTS** (cont'd)

G. Results of calculations

The results of the calculation show that the minimum voltage drop to the DG powered buses occur when the Core Spray Pump starts. The table below shows the starting (at 0.1 sec.) voltages and recovery voltages after 1 second following the start at Bus 33-1.

During LOOP concurrent with LOCA there is a 5 second time delay from the start of the first LPCI Pump to the start of the second LPCI Pump. Starting time calculations for the LPCI Pumps show that both the pumps accelerate to full speed in under 4 seconds. Therefore by the time the second LPCI Pump starts, the first LPCI Pump is at full speed (i.e. running load). There is also a 5 second time delay from the start of the second LPCI Pump to the start of the Core Spray Pump. Therefore, by the time the Core Spray pump starts, the second LPCI Pump is at full speed.

X. CALCULATION AND RESULTS (Cont)

SECTION 10.1

Calculation of Inital Voltage and Recovery Voltage after I Second following the start of each 4 kV Motor, and Calculation of Motor Starting Times, when DG2/3 is powering Unit 2 Buses

1) Starting kVA of the DG auxiliaries after the closure of the DG output breaker (Page C1 & C2 Calculation)

Angle = tan'(SKVAR/SKW)

Angle = 57.39 Degrees | R4

To determine the initial starting voltage (V_{curve}) and 1 second recovery voltage (V_{curve}₁), use the Dead Load Pickup Curve (SC-5056) and SKVA (calculated above) as "Generator Reactive Load MVA". Multiply the initial and 1 second curve values by 0.97 to account for a -3% curve tolerance.

Initial Voltage Dip:

$$
V_{\text{curve_i}} = 88.1\% \qquad \text{of } 4160\text{V} \qquad \qquad | \text{R4}
$$
\n
$$
V_{\text{dip}} = V_{\text{curve_i}} \times 0.97
$$
\n
$$
V_{\text{dip}} = 85.5\% \qquad \text{of } 4160\text{V} \qquad \qquad | \text{R4}
$$

Voltage recovery after 1 second:

 $V_{\text{curve}_1} = 100.0\%$ of 4160V $V_{\text{recovery}} = V_{\text{curve}_1} \times 0.97$ $V_{\text{recovery}} = 97.0\%$ of 4160V

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(R4

2) Starting of First LPCI Pump 2A (700HP)

Motor parameters

Motor Cable data

Motor parameters to be used to determine starting time of the pump.

2) Starting kVA of LPCI Pump 2A

Calculating the starting kVA at base voltage

 $SKVA_1 = \sqrt{3} \times V_{base} \times I_{LRC}$ /1000 SKVA₁ = 4364.8

Calculating starting kVA at operating voltage

$$
KVA_{start1} = (V_{op}^2/V_{base}^2) \times SKVA_1
$$

$$
X SKVA1 \t KVAstart1 = 4720.9
$$

at $Pf_{start} = 0.20$

The starting kVA is converted at starting power factor to the following KW and KVAR values:

Motor parameters

 $LPCI_{start} = (KVA_{start} \times PF_{start}) + j \times [KVA_{start} \times (sin(acos(PF_{start})))]$ LPCIYtn **=** 944.19 + j4625.55 **kVA**

ii) When the LPCI Pump starts, the LPCI Core Spray Pump Area Cooling Unit 2A, and MOV 2- 1501-13A will also start operating. The starting load is summarized in Table 4A. with the results as follows:

Additional Starting auxiliary load: Load.. **=** 20.6 **+** j28.4 kVA

iii) When the first LPCI Pump starts, at that time, there are running loads on DG powered Buses. Therefore, the actual voltage drop on the bus will be more than that of the starting of the first LPCI Pump alone. The running kW & kVA from the ETAP DG2/3_Bkr_Cl scenario is:

> $KW_{\text{ETAP-100%}} = 388$ $\text{KVAR}_{\text{ETAP}}_{.100\%} = 337$ $\boxed{\text{R4}}$ $KVA_{ETAP_100%} = 514$

The current at 100% voltage (i.e. at 4.16kV) is:

 $l_{n_1n_1100\%}$ = 71.2 Amps R4

The KVA & KW from the special ETAP scenario DG2/3_Bkr._VI for the reduced voltage condition are:

> $V_{\text{reduced}} = 2246$ Volts $KW_{\text{reduced}} = 327$ $KVAR_{reduced} = 233$ R4 $KVA_{reduced} = 402$

The power factor from the same ETAP scenario at reduced voltage running load is:

$$
PF_{reduced} = 0.814
$$

The calculated current at the reduced voltage for this **kVA** load is:

 $I_{reduced} = 103.1$ Amps AR

Therefore, the incremental difference of current is:

$$
I_{\text{delta}} = I_{\text{reduced}} - I_{\text{run_100\%}}
$$

$$
I_{\text{delta}} = 31.90
$$
 Amps

The incremental KVA (KVA_{delta}) used to determine additional starting kVA is

$$
KVA_{\text{delta}} = (\sqrt{3} \times V_{\text{op}} \times I_{\text{delta}} / 1000
$$

The incremental running load equivalent is converted to an equivalent KW and KVA from the incremental kVA previously determined

$$
KVA_{increment} = (KVA_{delta} \times PF_{reduced}) + j \times [KVA_{delta} \times (sin(acos(PF_{reduced}))))]
$$

\n
$$
KVA_{increment} = 187.1 + j133.51
$$

\n
$$
kVA
$$

\n
$$
[RA
$$

iv) The starting KVA equivalent as seen by the DG is calculated as follows:

Total Starting kVA equivalent:

 $Total_{start} = Load_{start} + KVA_{increment} + LPCI_{start}$ $Total_{\text{star}} = 1151.88 + j4787.46$ kVA $\left| \text{R4} \right|$

 $Vector_{start} = \sqrt{Re(Total_{start})^2 + Im(Total_{start})^2}$

 $Vector_{start} = 4924.09$ kVA R4

To determine the initial starting voltage ($V_{\text{curve_initial}}$) and 1 second recovery voltage $(V_{\text{curve_1sec}})$, use the Dead Load Pickup Curve (SC-5056) and Vector_{start} (calculated above) as "Generator Reactive Load MVA". Multiply the initial and 1 second curve values by 0.97 to account for a -3% curve tolerance.

Initial Voltage Dip:

Voltage recovery after **I** second:

$$
V_{\text{curve_1sec}} = 95.3\%
$$
 of 4160V
\n
$$
V_{\text{drop_1sec}} = V_{\text{curve_1sec}} \times 0.97
$$

\n
$$
V_{\text{drop_1sec}} = 92.44\%
$$
 of 4160V
\n
$$
\left.\begin{matrix} \text{R2} \\ \text{0} \end{matrix}\right\}
$$

v) The impedance of the pump feed cable, as defined earlier

 $Z_{\text{cable}} = 0.03085 + j0.00925$ ohms

 $|Z_{\text{cable}}| = 0.0322$ ohms

The maximum motor terminal line-to-line voltage drop which may occur on this cable given the LRC is:

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R2

Deducting the voltage drop due to motor feed cable to determine the actual voltage at the motor terminals, the initial starting voltage at the motor terminals is:

$$
V_{initialLPC12A} = V_{drop} - V_{delta_%}
$$

$$
V_{initialLPC12A} = 65.99\% \text{ of } 4160\text{V}
$$

The voltage after 1 second at the motor terminals is:

 $V_{1s\text{econd},\text{LPC12A}} = V_{\text{drop}-1\text{sec}} \cdot V_{\text{delta}}$ % $V_{\text{1second.}PCl2A}$ **= 91.60%** of 4160V R2

Calculation of Motor Startina Time:

Initial Starting Voltage (converted to decimal) $V_i = V_{initial, LPC12A} / 100$

Voltage at 1 second (converted to decimal)

$$
VI = V_{13900001 P0024} / 100
$$

Total inertia of the motor and pump together from above (WK^2) :

 $WK_{\text{oumo}} = 18.1$ lb-ft² WK_{motor} = 190.0 ib-ft² $WK2 = WK_{pump} + WK_{motor}$ $WK2 = 208.10$ **lb-ft²**

The folowing variables define the speed intervals and corresponding motor and pump torque increments necessary to compute the starting time of the pump.

%RPM_o - initial RPM of increment as a percentage of rated RPM

%RPMf - final RPM of increment as a percentage of rated RPM

%Torque_{Motor} - motor torque value from pump torque-speed curve read from the midpoint of the applicable speed range.

%Torque_{Pump} - pump torque value from pump torque-speed curve read from the midpoint of the applicable speed range.

%Volt - either the initial voltage (Vi) or the voltage at **1** second (V1).

Note that the determination of which voltage (%Volt) to use is made when the motor acceleration time exceeds 1 second, and that can only be determined by looking at the calculated cumulative time below (i.e. Vi until 1 second, VI after that).

Compute the motor torque at the initial voltage (Vi) and at I second (V1) using the motor torque at motor rated voltage (Ref 15).

> V_{OP} = 4160 $V_{base} = 4000$ Volts Volts

 $Torque_{Motor.at voltage} = [Torque_{ratio} × (%Volt × V_{op})² / V_{base}²]$ ft-lb

Convert the percentage of motor torque from the curve to motor torque by using the applicable motor torque computed at VI and V1 above.

 $Torque_{Motor} = (Torque_{motor} \times Torque_{Motor}.$ ft-lb

Torque of the pump is determined by multiplying the pump torque from Ref. 15 by the base torque of the motor.

$$
Torque_{pump} = Torque_{rated} \times %Torque_{pump} \qquad ft-lb
$$

Net torque is the motor torque minus the pump torque:

$$
TorqueNet = TorqueMotor - TorquePump \tft-lb
$$

Speed increment (% of rated RPM):

 $% \Delta_{\text{rom}}$ = %rpm_f - %rpm_o

Time in seconds to accelerate through an RPM increment is calculated by the following:

Time = $(WK2 \times RPM \times %{\triangle T}m / 100) / (307.5 \times Torque)$ seconds

Cumulative time from 0% to full speed at $% \Delta_{\text{rpm}}$ increments.

 $Time_{\text{current}} = Total Cumulative Start Time$

Calculations:

Therefore, the total time for this pump to accelerate is: Time $_{\text{cumulio}} =$

seconds

3.78

3) Starting LPCI Pump 2B (700HP)

Motor parameters

Motor Cable data

Motor parameters to be used to determine starting time of the pump.

2) Starting kVA of LPCI Pump 28

Calculating the starting kVA at base voltage

SKVA₁ = (
$$
\sqrt{3} \times V_{base} \times I_{LRC}
$$
)/1000 SKVA₁ = 4364.8

Calculating starting kVA at operating voltage

$$
KVA_{start1} = (V_{oo}^2/V_{base}^2) \times SKVA_1
$$

 $KVA_{start} = 4720.93$

at $Pf_{start} = 0.20$

The starting **kVA** is converted at starting power factor to the following KW and KVAR values:

Motor parameters

 $LPCI_{start} = (KVA_{start} × PF_{star}) + j × [KVA_{start} × (sin(acos(PF_{star})))]$ LPClsto **=** 944.19 + j4625.55 kVA

ii) There are no additional loads starting with this pump:

Additional Starting auxiliary load: \qquad Load_{start} = 0 + **j0** \qquad kVA

iii) When the second LPCI Pump starts, at that time, there are running loads on DG powered Buses. Therefore, the actual voltage drop on the bus will be more than that of the starting of the second LPCI Pump alone. The running kW & kVA from the ETAP DG2/3_UV_Rst scenario is:

> $KW_{ETAP-100\%} = 901$ $KVAR_{ETAP-100\%} = 587$ R4 $KVA_{ETAP_100%} = 1075$

The current at 100% voltage (i.e. at 4.16kV) in ETAP is:

 $I_{\text{run}_100\%}$ = 149.2 Amps R4

The KVA & KW from the special ETAP scenario DG2/3_UV_VIo for the reduced voltage condition are:

The power factor from the same ETAP scenario at reduced voltage running load is:

$$
PF_{reduced} = 0.866
$$

The calculated current at the reduced voltage for this kVA load in ETAP is:

 $I_{\text{reduced}} = 249.9$ Amps $\begin{bmatrix} R4 \end{bmatrix}$

Therefore, the incremental difference of current is:

$I_{\text{delta}} = I_{\text{reduced}} - I_{\text{run_100\%}}$	$I_{\text{delta}} = 100.70$	Amps	$ A4 $
---	-----------------------------	------	--------

The incremental KVA (KVA_{delta}) used to determine additional starting kVA is

$$
KVA_{\text{delta}} = (\sqrt{3} \times V_{\text{op}} \times I_{\text{delta}}) / 1000
$$

The incremental running load equivalent is converted to an equivalent KW and KVA from the incremental kVA previously determined

$$
KVA_{increment} = (KVA_{delta} \times PF_{reduced}) + j \times [KVA_{delta} \times (sin(acos(PF_{reduced})))]
$$

\n
$$
KVA_{increment} = 628.35 + j362.82
$$

\n
$$
R4
$$

iv) The starting KVA equivalent as seen by the DG is calculated as follows:

Total Starting kVA equivalent:

$$
Totalstart = Loadstart + KVAincrement + LPCIstart
$$

\n
$$
Totalstart = 1572.54 + j4988.37 \t kVA
$$

 $Vector_{stan} = \sqrt{Re(Total_{star})² + Im(Total_{star})²}$

 $Vector_{\text{stan}} = 5230.36$ kVA $|R4|$

To determine the initial starting voltage (V_{ourve_initial}) and 1 second recovery voltage ($V_{\text{curve_1sec}}$), use the Dead Load Pickup Curve (SC-5056) and Vector_{stan} (calculated above) as "Generator Reactive Load MVA". Multiply the initial and 1 second curve values by 0.97 to account for a -3% curve tolerance.

Initial Voltage Dip:

$$
V_{\text{curve_initial}} = 67.6\% \qquad \text{of } 4160\text{V}
$$
\n
$$
V_{\text{drop}} = V_{\text{curve_initial}} \times 0.97
$$
\n
$$
V_{\text{drop}} = 65.57\% \qquad \text{of } 4160\text{V}
$$
\n
$$
R2
$$

Voltage recovery after **1** second:

$$
Vcurve_1sec = 94.2% \t of 4160V |R2\n
$$
Vdrop_1sec = Vcurve_1sec \times 0.97
$$

\n
$$
Vdrop_1sec = 91.37% \t of 4160V
$$
$$

v) The impedance of the pump feed cable, as defined earlier:

 $Z_{\text{cable}} = 0.03034 + j0.0091$ ohms

IZca **J=** 0.0317 ohms

The maximum motor terminal line-to-line voltage drop which may occur on this cable given the LRC is:

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R2

Deducting the voltage drop due to motor feed cable to determine the actual voltage at the motor terminals, the initial starting voltage at the motor terminals is:

 $V_{initial, LPC12B} = V_{drop} - V_{delta}$ % $V_{initial(PC)2B} = 64.74\%$ of 4160V R2

The voltage after 1 second at the motor terminals is:

 V_{18} econd.LPCi2B $=$ $V_{\text{drop 1}$ sec $=$ V_{delta} % **V1.aCod.LPCI2S ⁼**90.54% of 4160V R2

Calculation of Motor Starting Time:

Initial Starting Voltage (converted to decimal) Vi = V_{inibalLPC_{12B} / 100}

Voltage at 1 second (converted to decimal) $V1 = V_{1,1}V_{1,2}P_{1,2}$ /100

Total inertia of the motor and pump together from above (WK^2) :

 $WK_{\text{oumo}} = 18.1$ lb-ft² WK_{motor} = 190.0 lb-ft² $WK2 = WK_{\text{pump}} + WK_{\text{motor}}$

 $WK2 = 208.10$ lb-ft²

The folowing variables define the speed intervals and corresponding motor and pump torque increments necessary to compute the starting time of the pump,

%RPM_o - initial RPM of increment as a percentage of rated RPM

%RPMf - final RPM of increment as a percentage of rated RPM

%Torque_{Motor} - motor torque value from pump torque-speed curve read from the midpoint of the applicable speed range.

%Torquepump - pump torque value from pump torque-speed curve read from the midpoint of the applicable speed range.

%Volt - either the initial voltage (Vi) or the voltage at 1 second (VI).

Note that the determination of which voltage (%Volt) to use is made when the motor acceleration time exceeds 1 second, and that can only be determined by looking at the calculated cumulative time below (i.e. Vi until 1 second, V1 after that).

Compute the motor torque at the initial voltage (Vi) and at 1 second (V1) using the motor torque at motor rated voltage (Ref 15).

$$
V_{OP} = 4160
$$
 Volts

$$
V_{base} = 4000
$$
 Volts

 $Torque_{\text{Motor. at. voltage} = \left[\text{Torque}_{\text{rated}} \times (\% \text{Volt} \times V_{\text{op}})^2 / V_{\text{base}}^2\right]$ ft-lb

Convert the percentage of motor torque from the curve to motor torque by using the applicable motor torque computed at Vi and VI above.

$$
Torque_{\text{Motor}} = (Torque_{\text{motor}} \times Torque_{\text{Motor at voltage}}) \qquad \qquad \text{ft-It}
$$

Torque of the pump is determined by multiplying the pump torque from Ref. 15 by the base torque of the motor.

$$
Torque_{Pump} = Torque_{rated} \times %Torque_{Pump} \qquad \text{ft-lb}
$$

Net torque is the motor torque minus the pump torque:

$$
TorqueNet = TorqueMotor - TorquePump \tft·ib
$$

Speed increment (% of rated RPM):

 $% \Delta_{\text{rpm}} = %$ rpm_f - %rpm_o

Time in seconds to accelerate through an RPM increment is calculated by the following:

Time = (WK2 x RPM x %
$$
\triangle
$$
rpm / 100) / (307.5 x Torque_{Net}) seconds

Cumulative time from 0% to full speed at $% \Delta_{\text{ram}}$ increments.

 $Time_{\text{cumud}}$ = Total Cumulative Start Time

Calculations:

Therefore, the total time for this pump to accelerate is: $Time_{cumu10} = 3.90$

seconds

 $R2$ **I** R2

4) Starting Core Spray Pump (800HP)

Motor parameters

Motor Cable data

Motor parameters to be used to determine starting time of the pump.

2) Starting kVA of Core Spray Pump

Calculating the starting kVA at base voltage

 $SKVA_1 = (\sqrt{3} \times V_{base} \times I_{LRC})/1000$ SKVA₁ = 4946.7

Calculating starting kVA at operating voltage

$$
KVA_{\text{start1}} = (V_{op}^2/V_{\text{base}}^2) \times SKVA_1
$$

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at $Pf_{start} = 0.20$

The starting kVA is converted at starting power factor to the following KW and KVAR values:

Motor parameters

CoreSpray_{start} = $(KVA_{start} x PF_{start}) + j x [KVA_{start} x (sin(acos(PF_{start})))]$ CoreSpray_{start} = 1070.08 + j5242.29 kVA

- ii) When the Core Spray Pump starts, MOVs 1402-38A, 1402-25A. 1501-22A, 1502-21B, 202-9A, & 202-5A; and RX Building Emergency Lighting will also start operating. The starting load is summarized in Table 4A, with the results as follows:
	- Additional Starting auxiliary load: Load_{start} = 185.5 + j320.1 kVA
- iii) When the Core Spray Pump starts, at that time, there are running loads on DG powered Buses. Therefore, the actual voltage drop on the bus will be more than that of the starting of the Core Spray Pump alone. The running kW & kVA from the ETAP DG2/3_T=5sec scenario is:

The current at 100% voltage (i.e. at 4.16kV) from ETAP is:

 $I_{\text{run}_100\%}$ = 227.9 Amps R4

The KVA & KW from the special ETAP scenario DG2/3_T=5sVl output at reduced voltage are:

The power factor from the same ETAP scenario at reduced voltage running load is:

$$
PF_{reduced} = 0.879
$$

The calculated current at the reduced voltage for this kVA load in ETAP is:

 $I_{\text{reduced}} = 397.2$ Amps R4

Therefore, the incremental difference of current is:

$$
I_{\text{delta}} = I_{\text{reduced}} - I_{\text{run}_100\%}
$$
\n
$$
I_{\text{delta}} = 169.30
$$
 Amps

The incremental KVA (KVA_{delta}) used to determine additional starting kVA is

$$
KVA_{\text{delta}} = (\sqrt{3} \times V_{\text{op}} \times I_{\text{delta}}) / 1000
$$

The incremental running load equivalent is converted to an equivalent KW and KVA from the incremental kVA previously determined

$$
KVA_{increment} = (KVA_{delta} \times PF_{reduced}) + j \times [KVA_{delta} \times (sin(acos(PF_{reduced}))))]
$$

\n
$$
KVA_{increment} = 1072.26 + j581.66 \qquad kVA
$$

iv) The starting KVA equivalent as seen by the DG is calculated as follows:

Total Starting kVA equivalent:

$$
Totalstart = Loadstart + KVAincrement + CoreSpringstar
$$

\n
$$
Totalstart = 2327.84 + j6144.05 \t kVA
$$

Vector_{start} $\frac{1}{\sqrt{7}}$ Re(Total_{start})² + lm(Total_{start})²

 $Vector_{stat} = 6570.25$ kVA $R4$

To determine the initial starting voltage ($V_{\text{curve_initial}}$) and 1 second recovery voltage (V_{curve}_{1sec}), use the Dead Load Pickup Curve (SC-5056) and Vector_{start} (calculated above) as "Generator Reactive Load MVA". Multiply the initial and 1 second curve values by 0.97 to account for a -3% curve tolerance.

Initial Voltage Dip:

$$
V_{\text{curve_initial}} = 62.6\% \qquad \text{of } 4160\text{V}
$$
\n
$$
V_{\text{drop}} = V_{\text{curve_initial}} \times 0.97
$$
\n
$$
V_{\text{drop}} = 60.72\% \qquad \text{of } 4160\text{V}
$$
\n
$$
\left| \text{R2} \right|
$$

Voltage recovery after I second:

$$
V_{\text{curve_1sec}} = 89.8\% \qquad \text{of } 4160\text{V} \qquad \qquad \text{R2}
$$
\n
$$
V_{\text{drop_1sec}} = V_{\text{curve_1sec}} \times 0.97
$$
\n
$$
V_{\text{drop_1sec}} = 87.11\% \qquad \text{of } 4160\text{V} \qquad \qquad \text{S3.11}
$$

v) The impedance of the pump feed cable, as defined earlier:

ZmbIo = 0.01176 **+** j0.00659 ohms

 $|Z_{\text{cable}}| = 0.0135$ ohms

The maximum motor terminal line-to-line voltage drop which may occur on this cable given the LRC is:

I R2

Deducting the voltage drop due to motor feed cable to determine the actual voltage at the motor terminals, the initial starting voltage at the motor terminals is:

 $V_{initial, CSP} = V_{drop} \cdot V_{delta}$ % $V_{initial CSP} = 60.32\%$ of 4160V

The voltage after 1 second at the motor terminals is:

 $V_{\text{1second.CSP}} = V_{\text{drop-1sec}} \cdot V_{\text{delta}}$ % $V_{\text{tsecondCSP}} = 86.71\% \text{ of } 4160V$ R4

Calculation of Motor Starting Time:

Initial Starting Voltage (converted to decimal) Vi = V_{initial CSP} / 100

Voltage at 1 second (converted to decimal) $V1 = V_{fsedond.CSP} / 100$

Total inertia of the motor and pump together from above $(WK²)$:

 $WK_{\text{numn}} = 18.1$ lb-ft² WK_{motor} = 220.0 lb-ft² WK2 **=** WKpump + WKmotor $WK2 = 238.10$ lb-ft²

The folowing variables define the speed intervals and corresponding motor and pump torque increments necessary to compute the starting time of the pump.

%RPM_a - initial RPM of increment as a percentage of rated RPM

%RPM, - final RPM of increment as a percentage of rated RPM

%Torque_{Motor} - motor torque value from pump torque-speed curve read from the midpoint of the applicable speed range.

%Torquepump **-** pump torque value from pump torque-speed curve read from the midpoint of the applicable speed range.

%Volt - either the initial voltage (Vi) or the voltage at 1 second (VI).

Note that the determination of which voltage (%Volt) to use Is made when the motor acceleration time exceeds 1 second, and that can only be determined by looking at the calculated cumulative time below (i.e. Vi until 1 second, V1 after that).

Compute the motor torque at the initial voltage (Vi) and at **I** second (V1) using the motor torque at motor rated voltage (Ref 15).

> V_{OP} = 4160 Volts **V_{base} = 4000 Volts**

 $Torque_{Motor.at voltage} = [Torque_{rated} \times (\% \text{Volt} \times V_{op})^2 / V_{base}^2]$ ft-lb

Convert the percentage of motor torque from the curve to motor torque by using the applicable motor torque computed at Vi and VI above.

$$
Torque_{Motor} = (Torque_{motor} \times Torque_{Motor, at voltage})
$$
 ft-lb

Torque of the pump is determined by multiplying the pump torque from Ref. 15 by the base torque of the motor.

 $Torque_{Pump} = Torque_{rated} \times % Torque_{Pump}$ ft-lb

Net torque is the motor torque minus the pump torque:

$$
TorqueNet = TorqueMotor - Torquepump \tft-lb
$$

Speed increment (% of rated RPM):

 $% \Delta_{\text{nom}} = \%$ rpm_f - %rpm_o

R2

Time in seconds to accelerate through an RPM increment is calculated by the following:

 $Time = (WK2 \times RPM \times %_{\Delta rpm 7} / 100) / (307.5 \times Torque_{Net})$ seconds

Cumulative time from 0% to full speed at $% \Delta_{mm}$ increments.

 $Time_{cum}$ = Total Cumulative Start Time

Calculations:

Á

%rpm_t %Torque_{Motor} %Torque_{Pump} %Torque_{Nat} / Time 7ime_{cumus} 10 413.31 **0.00** 413.31 0.67 0.67 20 417.96 0.00 417.96 0.67 1.34 **1.67 30 863.54** 863.54 23.60 839-94 0.33 40 70.80 792.74 0.35 2.02 **50** 863.54 153.40 710.14 0.39 2.42 60 901.92 236.00 665.92 2.64 0.42 R4 70 978.68 306.80 0.41 3.25 671.88 **8o** 1132.20 413.00 719.20 0.39 $\frac{3.64}{3.92}$ **9O** 1544.78 542.80 1001.98 0.28 95 2158.85 684.40 1474.45 0.09 **4.01** 99 2254.80 **767.00** 1487.80 0.07 4.09

Therefore, the total time for this pump to accelerate is: $Time_{cumul10} = 4.09$ seconds

5) Starting of Containment Cooling Service Water Pump 2A (500HP) **I R2**

Base Voltage (motor rated voltage) Operating Voltage Base Current (full load) Locked Rotor Current Starting Power factor $V_{base} = 4000$ $V_{OP} = 4160$ $I_{FL} = 67$ $J_{LRC} = I_{FL} \times 5.91$ ILRC **= 395.97** $PF_{start} = 0.20$ Volts (Ref. 40) **Volts** Amps (Ref. 40) (Ref. 40 & 43) (Ref. 41)

i) Starting kVA of CCSW Pump

Motor parameters

Calculating the starting kVA at base voltage

 $SKVA_1 = (\sqrt{3} \times V_{base} \times I_{LRC})/1000$ SKVA₁ = 2743.4

Calculating starting kVA at operating voltage

 $KVA_{start} = (V_{on}^2/V_{base}^2) \times SKVA_1$ $\text{KVA}_{\text{start}} = 2967.2$ at Pf_{start} = 0.20

The starting kVA is converted at starting power factor to the following KW and KVAR values:

 $CCSW_{start} = (KVA_{start} \times PF_{start}) + j \times [KVA_{start} \times (sin(acos(PF_{start})))]$ $CCSW_{start} = 593.44 + j2907.27$ kVA

ii) The CCSW Pumps are turned on manually between 10 minutes and 2 hours depending on the situation. For the purpose of this calculation the CCSW Pump 2A is turned on by the operator after 10 minutes into the event and CCSW Pump 2B is turned on shortly after CCSW Pump **2A.**

The CC Heat exchanger Discharge Valve is required to operate to exchange CC residual heat with the CCSW system. When CCSW Pump 2A starts, the Containment Cooling Heat Exchanger Discharge Valve also starts. When CCSW Pump 2B starts, the CC Heat Exchanger Discharge Valve is considered to be in operation (i.e. running load), however, at this time the CCSW Pump Cubical Cooler Fans (total 4) are also starting.

This calculation will only calculate the voltage dip due to the starting of CCSW Pump 2A (the first CCSW pump) instead of **CCSW** Pump 2B because starting kVA (due to the voltage dip) for the load already on the diesel when the 2A pump starts is the largest. However the 2A pump is evaluated with the starting kVA of the loads that start concurrently with the 2B CCSW pump as it is conservative. The starting load is summarized in Table 4A, with the results as follows:

R2
Additional Starting auxiliary load: \angle Load_{start} = 56 + j60.3 **kVA**

iii) When the CCSW Pump 2A starts, there are running loads on DG powered Buses. Therefore, the actual voltage drop on the bus will be more than that of the starting of the **CCSW** Pump **2A** alone.

All of the valves which are initiated by LOOP/LOCA have completed their operations and have stopped operating before **CCSW** Pump 2A was started. Therefore, these valve loads are taken off from the initial running load.

The running kW & kVA from the ETAP scenario DG2/3_T=10-m is:

 $KW_{ETAP_100\%} = 2151$ $\begin{bmatrix} R4 \\ R4 \end{bmatrix}$ R4 KVAErApioo% **=** 2441

The current at 100% voltage (i.e. at 4.16kV) from ETAP is:

$$
I_{run_100\%} = 338.7
$$
 Amps

The KVA & KW from the special ETAP scenario DG2/3_T1O-ml for the reduced voltage condition is:

The power factor from the same **ETAP** scenario at reduced voltage running load is:

 $PF_{reduced} = 0.892$ $\boxed{R4}$

The calculated current at the reduced voltage for this kVA load from ETAP is:

 $I_{reduced} = 600.7$ Amps $AR4$

Calc. No. 9389-46-19-3 Rev. 004 Page 10.1-24 Therefore, the incremental difference of current is:

$$
I_{\text{delta}} = I_{\text{reduced}} - I_{\text{run}_100\%}
$$

$$
I_{\text{delta}} = 262.00
$$
 Amps

The incremental KVA (KVA_{delta}) used to determine additional starting kVA is

$$
KVA_{\text{delta}} = (\sqrt{3} \times V_{\text{op}} \times I_{\text{delta}} / 1000
$$

The incremental running load equivalent is converted to an equivalent KW and KVA from the incremental kVA previously determined

$$
KVA_{increment} = (KVA_{delta} \times PF_{reduced}) + j \times [KVA_{delta} \times (sin(acos(PF_{reduced}))))]
$$

\n
$$
KVA_{increment} = 1683.91 + j853.35 \qquad kVA
$$

iv) The starting KVA equivalent as seen by the DG is calculated as follows:

Total Starting kVA equivalent:

 $\mathcal{L}^{\mathcal{L}}$

 $\overline{\mathcal{L}}$

$$
Totalstat = Loadstat + KVAincrement + CCSWstat
$$

$$
Totalstat = 2333.36 + j3820.92
$$
 kVA

 $Vector_{\text{stan}} = \text{Re}(Total_{\text{stan}})^2 + Im(Total_{\text{start}})^2$

 $Vector_{stat} = 4477.05$ kVA $\left| RA \right|$

To determine the initial starting voltage $(V_{\text{curve_initial}})$ and 1 second recovery voltage $(V_{\text{curve_1sec}})$, use the Dead Load Pickup Curve (SC-5056) and Vector_{start} (calculated above) as "Generator Reactive Load MVA". Multiply the initial and 1 second curve values by 0.97 to account for a -3% curve tolerance.

Initial Voltage Dip:

(

Voltage recovery after I second:

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X. CALCULATION AND RESULTS (Cont.)

SECTION 10.2

Calculation of Inital Voltage and Recovery Voltage after I Second following the start of each 4 kV Motor, and Calculation of Motor Starting Times, when **DG213** Is powering Unit 3 Buses

1) Starting kVA of the DG auxiliaries after the closure of the **DG** output breaker (Page **C1** & C2 Calculation)

Angle = tan'(SKVAR/SKW) Angle = 56.78 Degrees

To determine the initial starting voltage (V_{curve}) and 1 second recovery voltage (V_{curve}₁), use the Dead Load Pickup Curve (SC-5056) and SKVA (calculated above) as "Generator Reactive Load MVA". Multiply the initial and 1 second curve values by 0.97 to account for a -3% curve tolerance.

Initial Voltage Dip:

$$
V_{\text{curve}_i} = 87.7\% \qquad \text{of } 4160\text{V} \qquad | \text{R4}
$$
\n
$$
V_{\text{dip}} = V_{\text{curve}_i} \times 0.97
$$
\n
$$
V_{\text{dip}} = 85.1\% \qquad \text{of } 4160\text{V} \qquad | \text{R4}
$$

Voltage recovery after 1 second:

 $V_{\text{curve}_1} = 100.0\%$ of 4160V $V_{\text{recovery}} = V_{\text{curve}}$ ₁ x 0.97 $V_{\text{reccovery}} = 97.0\%$ of 4160V

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$$
\mathsf{R4}
$$

2) Starting of First LPCI Pump 3A (700HP)

Motor parameters

Motor Cable data

Motor parameters to be used to determine starting time of the pump.

2) Starting kVA of LPCI Pump 2A

Calculating the starting kVA at base voltage

SKVA₁ =
$$
\sqrt{3} \times V_{base} \times I_{LRC}
$$
/1000

Calculating starting kVA at operating voltage

$$
KVA_{\text{start}} = (V_{op}^2/V_{\text{base}}^2) \times SKVA_t
$$

 $SKVA₁ = 4364.8$

at $Pf_{start} = 0.20$

The starting kVA is converted at starting power factor to the following KW and KVAR values:

Motor parameters

/(

 $LPCI_{start} = (KVA_{start} \times PF_{start}) + j \times [KVA_{start} \times (sin(acos(PF_{stat})))]$ $LPCI_{start} = 944.19 + j4625.55$ kVA

ii) When the LPCI Pump starts, the LPCI Core Spray Pump Area Cooling Unit 3A, and MOV 3- 1501-13A will also start operating. The starting load is summarized in Table 4B, with the results as follows:

Additional Starting auxiliary load: Load_{start} = $20.6 + 28.4$ kVA

Iii) When the first LPCI Pump starts, at that time, there are running loads on DG powered Buses. Therefore, the actual voltage drop on the bus will be more than that of the starting of the first LPCI Pump alone. The running kW & kVA from the ETAP DG2/3_Bkr_Cl scenario is:

> KWETAp_1O0% = 421 $\text{KVAR}_{\text{ETAP}}$ $_{100\%}$ = 351 R4 **KVAETAploo% =** 548

The current at 100% voltage (i.e. at 4.16kV) is:

 $I_{\text{run_100\%}} = 76.1$ Amps AR_1

The KVA & KW from the special ETAP scenario DG2/3_Bkr_VI for the reduced voltage condition is::

The calculated current at the reduced voltage for this kVA load from ETAP is:

 $I_{reduced} = 109.4$ Amps $R4$

Therefore, the incremental difference of current is:

 $\mathcal{L}_{\mathcal{A}}^{\mathcal{A}}$

 \int_0^{∞}

$$
I_{\text{delta}} = I_{\text{reduced}} - I_{\text{run_100\%}}
$$

$$
I_{\text{delta}} = 33.30
$$
 Amps

The incremental KVA (KVA_{delta}) used to determine additional starting kVA is

$$
KVA_{\text{delta}} = (\sqrt{3} \times V_{\text{op}} \times I_{\text{delta}} / 1000
$$

The incremental running load equivalent is converted to an equivalent KW and KVA from the incremental kVA previously determined

$$
KVA_{increment} = (KVA_{delta} \times PF_{reduced}) + j \times [KVA_{delta} \times (sin(acos(PF_{reduced})))]
$$

\n
$$
KVA_{increment} = 190.27 + j146.18
$$

iv) The starting KVA equivalent as seen by the DG is calculated as follows:

Total Starting kVA equivalent:

Total_{start} = Load_{start} + KVA_{increment} + LPCI_{start} $Total_{start} = 1155.06 + j4800.13$ kVA $R4$

 $Vector_{start} = \sqrt{Re(Total_{start})^2 + Im(Total_{start})^2}$

 $Vector_{\text{start}} = 4937.14$ kVA $R4$

To determine the initial starting voltage (V_{curve} initial) and 1 second recovery voltage $(V_{\text{curve_1sec}})$, use the Dead Load Pickup Curve (SC-5056) and Vector_{start} (calculated above) as "Generator Reactive Load MVA". Multiply the initial and 1 second curve values by 0.97 to account for a -3% curve tolerance.

Initial Voltage Dip:

 \mathfrak{g}

ť

 $V_{\text{curve_initial}} = 68.8\%$ of 4160V $V_{\text{drop}} = V_{\text{curve_initial}} \times 0.97$ Vdrop **=** 66.74% of 4160V |R4 | R4

Voltage recovery after **1** second:

$$
V_{\text{curve}_1\text{sec}} = 95.1\% \qquad \text{of } 4160\text{V}
$$
\n
$$
V_{\text{drop}_1\text{sec}} = V_{\text{curve}_1\text{sec}} \times 0.97
$$
\n
$$
V_{\text{drop}_1\text{sec}} = 92.25\% \qquad \text{of } 4160\text{V}
$$
\n
$$
\left.\begin{array}{ccc}\n\end{array}\right\} \text{R4}
$$

v) The impedance of the pump feed cable, as defined earlier:

 $Z_{\text{cable}} = 0.03021 + j0.00906$ ohms

 $|Z_{\text{cable}}|$ = 0.0315 ohms

The maximum motor terminal line-to-line voltage drop which may occur on this cable given the LRC is:

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Deducting the voltage drop due to motor feed cable to determine the actual voltage at the motor terminals, the initial starting voltage at the motor terminals is:

 $V_{\text{initial,LPCISA}} = V_{\text{drop}} - V_{\text{delta}}$ $V_{initial, PCBA} = 65.91\%$ of 4160V R4

The voltage after 1 second at the motor terminals is:

 V_{1} second.LPC13A = V_{drop_1} sec **-** V_{delta} .% $V_{1\n$ second, LPCI3A = 91.42% of 4160V
$$
R4
$$

Calculation of Motor Startina Time:

(

Initial Starting Voltage (converted to decimal) $Vi = V_{initial, LPCI3A} / 100$

Voltage at 1 second (converted to decimal) $V1 = V_{1\text{second}|PCl3A} / 100$

Total inertia of the motor and pump together from above (WK^2) :

 $WK_{\text{pump}} = 18.1$ lb-ft² WK_{motor} = 190.0 lb-ft²

WK2 = WKpump **+** WKmotor

 $WK2 = 208.10$ lb-ft²

The folowing variables define the speed intervals and corresponding motor and pump torque increments necessary to compute the starting time of the pump.

%RPM_o - initial RPM of increment as a percentage of rated RPM

%RPMf - final RPM of increment as a percentage of rated RPM

%Torque_{Motar} - motor torque value from pump torque-speed curve read from the midpoint of the applicable speed range.

%Torque_{Pump} - pump torque value from pump torque-speed curve read from the midpoint of the applicable speed range.

%Volt - either the initial voltage (VI) or the voltage at 1 second (V1).

Note that the determination of which voltage (%Volt) to use is made when the motor acceleration time exceeds **1** second, and that can only be determined by looking at the calculated cumulative time below (i.e. Vi until 1 second, Vi after that).

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Compute the motor torque at the initial voltage (Vi) and at 1 second (V1) using the motor torque at motor rated voltage (Ref 15).

> V_{OP} = 4160 Volts **Vbase =** 4000 Volts

/

 $Torque_{Motor.at.voltage} = \boxed{Torque_{rated} \times \left(\frac{Q_0}{Q_0}\right)^2 / V_{base}\right\}}$ ft-lb

Convert the percentage of motor torque from the curve to motor torque by using the applicable motor torque computed at Vi and VI above.

Torque_{Motor} = (Torque_{motor} x Torque_{Motor.atvotage}) ft-lb

Torque of the pump is determined by multiplying the pump torque from Ref. 15 by the base torque of the motor.

 $Torque_{pump} = Torque_{rated} \times \% Torque_{pump}$ ft-lb

Net torque is the motor torque minus the pump torque:

Torque_{Net} = Torque_{Motor} - Torque_{Pump} ft-lb

Speed increment (% of rated RPM):

 $\% \Delta_{\rm mm}$ = %rpm_r - %rpm_o

Time in seconds to accelerate through an RPM increment is calculated by the following:

 $Time = (WK2 \times RPM \times \%2$ rpm / 100) / (307.5 x Torque_{Net}) seconds

Cumulative time from 0% to full speed at $% \Delta_{mm}$ increments.

 $Time_{cumul} = Total Cumulative Start Time$

Calculations:

/

 \langle

Therefore, the total time for this pump to accelerate is: $Time_{cum, 10} =$

seconds

3.79

Calc. No. 9389-46-19-3 Rev. 004 Page 10.2-8

3) Starting LPCI Pump 3B (700HP)

Motor parameters (LPCI Pumps 3A and 3B are identical pumps)

Motor Cable data

Motor parameters to be used to determine starting time of the pump.

2) Starting kVA of LPCI Pump 3B

Calculating the starting **WA** at base voltage

$$
SKVA1 = (\sqrt{3} \times Vbase \times ILRC)/1000
$$
 SKVA₁ = 4364.8

Calculating starting kVA at operating voltage

 $\mathsf{KVA}_{\mathsf{start1}} = (\mathsf{V_{oo}}^2 \mathsf{N_{\mathsf{base}}})$

 $KVA_{start} = 4720.9$

at $Pf_{start} = 0.20$

The starting kVA is converted at starting power factor to the following KW and KVAR values:

Motor parameters

 $($

 $LPCI_{start} = (KVA_{start} \times PF_{start}) + j \times [KVA_{start} \times (sin(acos(PF_{start})))]$ LPCIlw. = 944.19 **+** j4625.55 kVA

ii) There are no additional loads starting with this pump:

Additional Starting auxiliary load: \qquad Load_{start} = $0 + i0$ kVA.

iii) When the second LPCI Pump starts, at that time, there are running loads on **DG** powered Buses. Therefore, the actual voltage drop on the bus will be more than that of the starting of the second LPCI Pump alone. The running kW & kVA from the ETAP DG2/3_UV_Rst scenario is:

> KVVETAP **100% =** 931 $\text{KVAR}_{\text{ETAP}}$ 100% = 600 R4 **KVA_{ETAP 100%} = 1108**

The current at 100% voltage (i.e. at 4.16kV) from ETAP is:

 $I_{\text{run_100\%}} = 153.7$ Amps R4

The KVA & KW from the special ETAP scenario DG2/3_UV_Vi for the reduced voltage condition are:

> $V_{\text{reduced}} = 2246$ Volts $KW_{reduced} = 850$ $\text{KVAR}_{\text{reduced}} = 510$ $\left| \text{R4} \right|$ $KVA_{reduced} = 991$

The power factor from the same ELMS-AC file at reduced voltage running load is:

 $PF_{reduced} = 0.857$ R4

The calculated current at the reduced voltage for this kVA load is:

 $l_{reduced}$ = 254.9 Amps R4

Therefore, the incremental difference of current is:

$$
I_{\text{delta}} = I_{\text{reduced}} - I_{\text{run}_100\%}
$$

$$
I_{\text{delta}} = 101.20
$$
 Amps $\qquad \qquad | R4$

The incremental KVA (KVA_{delta}) used to determine additional starting kVA is

$$
KVA_{\text{delta}} = (\sqrt{3} \times V_{\text{op}} \times I_{\text{delta}} / 1000
$$

The incremental running load equivalent is converted to an equivalent KW and KVA from the incremental kVA previously determined

$$
KVA_{increment} = (KVA_{delta} \times PF_{reduced}) + j \times [KVA_{delta} \times (sin(acos(PF_{reduced}))))]
$$

\n
$$
KVA_{increment} = 624.91 + j375.76
$$

\n
$$
R4
$$

iv) The starting KVA equivalent as seen by the DG is calculated as follows:

Total Starting kVA equivalent:

I

$$
Totalstart = Loadstart + KVAincrement + LPCIstart
$$

$$
Totalstart = 1569.09 + j5001.31
$$
 kVA

 $Vector_{start} = \sqrt{Re(Total_{start})^2 + Im(Total_{start})^2}$

 $Vector_{stat} = 5241.67$ kVA $R4$

To determine the initial starting voltage (V_{curve_initial}) and 1 second recovery voltage $(V_{\text{curve_1sec}})$, use the Dead Load Pickup Curve (SC-5056) and Vector_{start} (calculated above) as "Generator Reactive Load MVA". Multiply the initial and *I* second curve values by 0.97 to account for a -3% curve tolerance.

Initial Voltage Dip:

VCUfVOj~lntI = 67.5% of 4160V **Vdrp =** Vc rvejn•u 0 X 0.97 Vrop = 65.48% of 4160V R3 R3

Voltage recovery after **I** second:

$$
V_{\text{curve_1sec}} = 94.2\%
$$
 of 4160V
\n
$$
V_{\text{drop_1sec}} = V_{\text{curve_1sec}} \times 0.97
$$

\n
$$
V_{\text{drop_1sec}} = 91.37\%
$$
 of 4160V
\n
$$
\left.\begin{matrix} \text{R3} \\ \text{1} \end{matrix}\right\}
$$

v) The impedance of the pump feed cable, as defined earlier:

 $Z_{\text{cable}} = 0.03533 + j0.0106$ ohms

IZ-aw. **1=** 0.0369 ohms

The maximum motor terminal line-to-line voltage drop which may occur on this cable given the LRC is:

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R3

Deducting the voltage drop due to motor feed cable to determine the actual voltage at the motor terminals, the initial starting voltage at the motor terminals is:

$$
V_{initial,LPCI3B} = V_{drop} - V_{delta_4}
$$

$$
V_{initial,LPCI3B} = 64.51\% \text{ of } 4160\text{V}
$$

The voltage after **I** second at the motor terminals is:

 V_{156 cond.LPC13B = V_{drop_1560} - V_{delta} % $V_{\text{1second.}PCC} = 90.41\% \text{ of } 4160\text{V}$ R3

Calculation of Motor Starting Time:

 \mathfrak{g}

Initial Starting Voltage (converted to decimal) $V_i = V_{initial,LPC/3B} / 100$

Voltage at 1 second (converted to decimal) $V1 = V_{100}$ V_{1second} LPCI3B /100

Total inertia of the motor and pump together from above ($WK²$):

 $WK_{pump} = 18.1$ lb-ft² WK_{motor} = 190.0 lb-ft² $WK2 = WK_{pump} + WK_{motor}$ $WK2 = 208.10$ lb-ft²

The folowing variables define the speed intervals and corresponding motor and pump torque increments necessary to compute the starting time of the pump.

%RPM_o - initial RPM of increment as a percentage of rated RPM

%RPMf - final RPM of increment as a percentage of rated RPM

%Torque_{Mator} - motor torque value from pump torque-speed curve read from the midpoint of the applicable speed range.

%Torque_{Pump} - pump torque value from pump torque-speed curve read from the midpoint of the applicable speed range.

%Volt - either the initial voltage (Vi) or the voltage at **I** second (V1).

Note that the determination of which voltage (%Volt) to use is made when the motor acceleration time exceeds **1** second, and that can only be determined by looking at the calculated cumulative time below (i.e. Vi until **1** second, VI after that).

> Caic. No. 9389-46-19-3 Rev. 003 Page 10.2-13

Compute the motor torque at the initial voltage (Vi) and at **1** second (V1) using the motor torque at motor rated voltage (Ref 15).

$$
V_{OP} = 4160 \t Volts
$$

$$
V_{base} = 4000 \t Volts
$$

Torque_{Motor.at.voitage = [Torque_{rated} x (%Volt x V_{op})² / V_{base}²]}] **ft-lb**

Convert the percentage of motor torque from the curve to motor torque by using the applicable motor torque computed at Vi and VI above.

$$
Torque_{Motor} = (Torque_{motor} \times Torque_{Motor.at-voltage})
$$
 ft-It

Torque of the pump is determined by *multiplying* the pump torque from Ref. 15 by the base torque of the motor.

Torquepump **=** Torqueted x %Torquepump ft-lb

Net torque is the motor torque minus the pump torque:

$$
TorqueNet = TorqueMotor - Torquepump \tft-lb
$$

Speed increment (% of rated RPM):

% Δ_{ram} = %rpm_r - %rpm_o

Time in seconds to accelerate through an RPM increment is calculated by the following:

Time = (WK2 x RPM x %
$$
\Delta
$$
rpm / 100) / (307.5 x Torque_{Net}) seconds

Cumulative time from 0% to full speed at $% \Delta_{rpm}$ increments.

 $Time_{\text{cumul}} = Total Cumulative Start Time$ R3

Calculations:

Therefore, the total time for this pump to accelerate is: $Time_{cumul10} =$

seconds

3.92

4) Starting Core Soray Pump (800HP)

Motor parameters

Motor Cable data

 $\ddot{\mathbf{t}}$

Motor parameters to be used to determine starting time of the pump.

2) Starting **kVA** of Core Spray Pump

Calculating the starting kVA at base voltage

$$
SKVA_1 = (\sqrt{3} \times V_{base} \times I_{LRC})/1000
$$
 SKVA₁ = 4946.7

Calculating starting kVA at operating voltage

$$
KVA_{\text{start1}} = (V_{\text{op}}^2/V_{\text{base}}^2) \times SKVA_1
$$

$$
KVA_{\text{start}} = 5350.4
$$

at $Pf_{\text{start}} = 0.20$

Calc. No. 9389-46-19-3 Rev. 003 Page 10.2-16 The starting kVA is converted at starting power factor to the following KW and KVAR values:

Motor parameters

(

 $\big($

CoreSpray_{start} = $(KVA_{start} \times PF_{start}) + j \times [KVA_{start1} \times (sin(acos(PF_{start})))]$ CoreSpray6t. **=** 1070.08 **+** j5242.29 kVA

ii) When the Core Spray Pump starts, MOVs 1402-38A, 1402-25A, 1501-22A, 1501-21B, 202-5A will also start operating. The starting load is summarized in Table 4B, with the results as follows:

Additional Starting auxiliary load: Loadstar **=** 163.2 **+** j294.1 kVA

iii) When the Core Spray Pump starts, at that time, there are running loads on **DG** powered Buses. Therefore, the actual voltage drop on the bus will be more than that of the starting of the Core Spray Pump alone. The running kW & kVA from the ETAP DG2/3_T=5sec scenario is:

> $KW_{ETAP.100\%} = 1448$ $KVAR_{ETAP-100%} = 850$ KVAETAploo% **=** 1679

The current at 100% voltage (i.e. at 4.16kV) from ETAP is:

 $l_{\text{run_100\%}} = 232.9$ Amps

The KVA & KW from the special ETAP scenario DG2/3_T=5sVI output at reduced voltage are:

 $V_{\text{reduced}} = 2246$ KWreduced *=* 1369 $KVAR_{reduced} = 763$ KVAreduced **=** 1567 Volts R4

The power factor from the same ETAP scenario at reduced voltage running load is:

$$
PF_{reduced} = 0.874
$$

The calculated current at the reduced voltage for this kVA load is:

1R4 $I_{\text{reduced}} = 402.9$ Amps

R4

R4

Therefore, the incremental difference of current is:

(.

$$
I_{\text{delta}} = I_{\text{reduced}} - I_{\text{run_100\%}}
$$

$$
I_{\text{delta}} = 170.00 \qquad \text{Amps}
$$

The incremental KVA (KVA $_{\text{delta}}$) used to determine additional starting kVA is

$$
KVA_{\text{delta}} = (\sqrt{3} \times V_{\text{op}} \times I_{\text{delta}}) / 1000
$$

The incremental running load equivalent is converted to an equivalent KW and KVA from the incremental kVA previously determined

$$
KVA_{\text{increment}} = (KVA_{\text{delta}} \times PF_{\text{reduced}}) + j \times [KVA_{\text{delta}} \times (\sin(\text{acos}(PF_{\text{reduced} })))]
$$

$$
KVA_{\text{increment}} = 1070.57 + j595.21 \qquad \text{kVA}
$$

iv) The starting KVA equivalent as seen by the DG is calculated as follows:

Total Starting kVA equivalent:

$$
Totalstan = Loadstan + KVAincrement + CoreSpring
$$

$$
Totalslant = 2303.85 + j6131.6 \t kVA
$$

 $Vector_{slant} =$ $\sqrt{\text{Re(Total}_{star})^2 + \text{Im(Total}_{star})^2}$

 $Vector_{\text{start}} = 6550.14$ kVA \vert R4

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To determine the initial starting voltage (V_{curve_initial}) and 1 second recovery voltage (V_{curve_1sec}) , use the Dead Load Pickup Curve (SC-5056) and Vector_{stan} (calculated above) as "Generator Reactive Load MVA'. Multiply the initial and 1 second curve values by 0.97 to account for a -3% curve tolerance.

Initial Voltage Dip:

(.

I

Voltage recovery after I second:

$$
V_{\text{curve_1sec}} = 89.8\% \qquad \text{of } 4160\text{V}
$$
\n
$$
V_{\text{drop_1sec}} = V_{\text{curve_1sec}} \times 0.97
$$
\n
$$
V_{\text{drop_1sec}} = 87.11\% \qquad \text{of } 4160\text{V}
$$
\n
$$
\left.\begin{array}{l}\n\text{A4} \\
\text{B5} \\
\text{B6} \\
\text{B7} \\
\text{B8} \\
\text{A9} \\
\text{B0} \\
\text{B1} \\
\text{B2} \\
\text{B3} \\
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$$

v) The impedance of the pump feed cable, as defined earlier:

 $Z_{\text{cable}} = 0.01489 + j0.00834$ ohms

 $|Z_{\text{cable}}| = 0.0171$ ohms

The maximum motor terminal line-to-line voltage drop which may occur on this cable given the LRC is:

Deducting the voltage drop due to motor feed cable to determine the actual voltage at the motor terminals, the initial starting voltage at the motor terminals is:

$$
V_{initial,CSP} = V_{drop} - V_{delta_%}
$$

\n
$$
V_{initial,CSP} = 60.21\% \text{ of } 4160V
$$

The voltage after **1** second at the motor terminals is:

 $V_{\text{1second.CSP}} = V_{\text{drop 1sec}} - V_{\text{delta } %$ $V_{\text{1second CSP}} = 86.60\% \text{ of } 4160V$ R4

Calculation of Motor Starting Time:

 $\big($

Initial Starting Voltage (converted to decimal) Vi = V_{initial CSP} / 100

Voltage at 1 second (converted to decimal) $V1 = V₁$ _{second.CSP} /100

Total inertia of the motor and pump together from above (WK^2) :

 $WK_{\text{numo}} = 18.1$ lb-ft² WK_{motor} = 220.0 lb-ft²

 $WK2 = WK_{\text{oumb}} + WK_{\text{motor}}$

 $WK2 = 238.10$ tb-ft²

The folowing variables define the speed intervals and corresponding motor and pump torque increments necessary to compute the starting time of the pump.

%RPM_o - initial RPM of increment as a percentage of rated RPM

%RPM_i - final RPM of increment as a percentage of rated RPM

- %Torque_{Motor} motor torque value from pump torque-speed curve read from the midpoint of the applicable speed range.
- %Torque_{Pump} pump torque value from pump torque-speed curve read from the midpoint of the applicable speed range.

%Volt - either the initial voltage (Vi) or the voltage at 1 second (Vi).

Note that the determination of which voltage (%Volt) to use is made when the motor acceleration time exceeds 1 second, and that can only be determined by looking at the calculated cumulative time below (i.e. Vi until 1 second, VI after that).

> Calc. No. 9389-46-19-3 Rev. 004 Page 10.2-20

Compute the motor torque at the initial voltage (Vi) and at **1** second (VI) using the motor torque at motor rated voltage (Ref 15).

> V_{OP} = 4160 $V_{base} = 4000$ Volts Volts

Torque $\text{Motor}_\text{astroltage} = \boxed{\text{Torque}_\text{rated} \times (\% \text{Volt} \times V_{op})^2 / V_\text{base}^2}$ ft-lb

Convert the percentage of motor torque from the curve to motor torque by using, the applicable motor torque computed at Vi and VI above.

Torque_{Motor} = (Torque_{motor} x Torque_{Motor.atvoltage}) ft-lb

Torque of the pump is determined by multiplying the pump torque from Ref. 15 by the base torque of the motor.

 $Torque_{pump} = Torque_{rated} \times \% Torque_{pump}$ ft-lb

Net torque is the motor torque minus the pump torque:

Torque_{Net} = Torque_{Motor} - Torque_{Pump} ft-lb

Speed increment (% of rated RPM):

% Δ_{rem} = %rpm_f - %rpm_o

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Time in seconds to accelerate through an RPM increment is calculated by the following:

 $Time = (WK2 \times RPM \times %_{\Delta rpm 7} / 100) / (307.5 \times Torque_{Ne})$ seconds

Cumulative time from 0% to full speed at % Δ_{nm} increments.

 $Time_{cumul} = Total Cumulative Start Time$

Calculations:

 $\big($

Therefore, the total time for this pump to accelerate is: $Time_{cumuli} = 4.10$ seconds

5) Starting of Containment Cooling Service Water Pump 3A (500HP)

Motor parameters

(

i) Starting **kVA** of CCSW Pump

Calculating the starting kVA at base voltage

$$
SKVA_1 = (\sqrt{3} \times V_{base} \times I_{LRC})/1000
$$
 SKVA_1 = 2743.4

Calculating starting kVA at operating voltage

 $KVA_{start} = (V_{on}²/V_{base}²) \times SKVA_t$ $\text{KVA}_{\text{start}} = 2967.2$ at Pf_{start} = 0.20

The starting kVA is converted at starting power factor to the following KW and KVAR values:

 $CCSW_{start} = (KVA_{start} × PF_{start}) + j × [KVA_{start} × (sin(acos(PF_{start})))]$ CCSWge **=** 593.44 **+** j2907.27 kVA

ii) The CCSW Pumps are turned on manually between 10 minutes and 2 hours depending on the situation. For the purpose of this calculation the CCSW Pump 3A is turned on by the operator after 10 minutes into the event and CCSW Pump 3B is turned on shortly after CCSW Pump 3A.

The CC Heat exchanger Discharge Valve is required to operate to exchange CC residual heat with the CCSW system. When CCSW Pump 3A starts, the Containment Cooling Heat Exchanger Discharge Valve also starts. When CCSW Pump **35** starts, the CC Heat Exchanger Discharge Valve is considered to be in operation (i.e. running load), however, at this time the CCSW Pump Cubical Cooler Fans (total 4) are also starting.

This calculation will only calculate the voltage dip due to the starting of CCSW Pump 3A (the first CCSW pump) instead of CCSW Pump 3B because the starting kVA (due to the voltage dip) for the load already on the diesel when the 3A pump starts is the largest. However, the 3A pump is conservatively evaluated with the starting kVA of the loads that start concurrently with the 3B CCSW pump. The starting load is summarized in Table 4B, with the results as follows:

R3

Additional Starting auxiliary load: Load_{start} = 62.7 + j60 **kVA**

 $($.

iii) When the CCSW Pump 3A starts, there are running loads on DG powered Buses. Therefore, the actual voltage drop on the bus will be more than that of the starting of the CCSW Pump 3A alone.

All of the valves which are initiated by LOOP/LOCA have completed their operations and have stopped operating before CCSW Pump 3A was started. Therefore, these valve loads are taken off from the initial running load.

The running kW & kVA from the ETAP scenario DG2/3 $T=10$ -m is:

 $KW_{ETAP_100\%} = 2181$ R4 KVARETAp_joo% **=** 1153 $KVA_{ETAP 100%} = 2467$

The current at 100% voltage (i.e. at 4.16kV) from ETAP is:

 $l_{\text{run_100\%}} = 342.4$ Amps

The KVA & KW from the special ETAP scenario DG2/3_T10-ml output at reduced voltage is:

 $V_{reduced} = 2246$ Volts KWr.du~cd **=** 2107 $\text{KVAR}_{\text{reduced}} = 1074$ R4 $KVA_{reduced} = 2365$

The power factor from the same ETAP scenario at reduced voltage running load is:

 $PF_{\text{reduced}} = 0.891$ R4

The calculated current at the reduced voltage for this **kVA** load from ETAP is:

 $\mathsf{I}_{\mathsf{reduced}} \cong 607.7$ Amps $\bigg\{R4$

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Therefore, the incremental difference of current is:

$$
I_{\text{delta}} = I_{\text{reduced}} - I_{\text{run_100\%}}
$$

$$
I_{\text{delta}} = 265.30 \qquad \text{Amps}
$$

The incremental KVA (KVA_{delta}) used to determine additional starting kVA is

$$
KVAdeita = (\sqrt{3} \times Vop \times Ideita) / 1000
$$
 KVA_{deita} = 1911.6 |R4

The incremental running load equivalent is converted to an equivalent KW and KVA from the incremental kVA previously determined

$$
KVA_{increment} = (KVA_{delta} \times PF_{reduced}) + j \times [KVA_{delta} \times (sin(acos(PF_{reduced}))))]
$$

\n
$$
KVA_{increment} = 1703.21 + j867.86 \qquad kVA
$$

iv) The starting KVA equivalent as seen by the DG is calculated as follows:

Total Starting **WA** equivalent:

 $\left($

$$
Totalstart = Loadstart + KVAincrement + CCSWstart
$$

\n
$$
Totalstart = 2359.36 + j3835.13 \t kVA
$$

Vector_{start} $\frac{1}{\sqrt{Re(Total_{\text{start}})}^2 + Im(Total_{\text{start}})^2}$

 $Vector_{start} = 4502.75$ kVA $R4$

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To determine the initial starting voltage $(V_{\text{curve_initial}})$ and 1 second recovery voltage (V_{curve_tsec}), use the Dead Load Pickup Curve (SC-5056) and Vector_{stan} (calculated above) as "Generator Reactive Load MVA". Multiply the initial and 1 second curve values by 0.97 to account for a -3% curve tolerance.

Initial Voltage Dip:

Voltage recovery after 1 second:

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CALCULATION PAGE

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XI COMPARISON OF **RESULTS** WITH **ACCEPTANCE** CRITERIA

Comparison of results with Acceptance Criteria when DG2/3 power Unit 2 loads

A Continuous loading of the Diesel Generator

The results of the calculation show that the maximum continuous load on the Diesel Generator is 2609 kW (ETAP Scenario DG2/3 T=10+m), which is slightly above the 2600 kW continous rating of the Diesel Generator. However, this loading value is well within the 2860kW 2000hr rating of the R_4 DG. This loading value occurs only while the 1st CCSW pump is energized and prior to deenergizing one of the two LPCI pumps. The maximum long term DG loading is 2491 kW when both CCSW pumps are in operation (ETAP Scenario DG2/3_CRHVAC). Therefore, from a continuous loading point of view the DG 2/3 has adequate capacity to accept the emergency load under LOOP concurrent with LOCA in accordance with the acceptance criteria.

If the EDG is at 102% of its nominal frequency, the EDG load is expected to be **1.023** or 1.06 times larger since input power is proportional to the speed cubed (Section V.5). This results in a maximum loading of 2609kW x **1,023** = 2769kW which is within the 2000 hr 2860kW rating of the diesel. $\begin{cases} R4 \end{cases}$

The lowest power factor for the EDG load during the DG2/3 $T=10+m$, DG2/3 $T=10+m$ and DG2/3 CRHVAC is 87.7%. This value is below the 88% acceptance criteria.

B. Transient loading of the Diesel Generator

Results of this calculation show that the minimum recovery voltage after 1 second following the start of any large 4-kv motors is 87% of 4160V which is above the 80% recovery requirement in the acceptance criteria.

This calculation shows that when the Core Spray Pump starts, the initial voltage dips below 61% of operating voltage (i.e. 4160v). However, within **I** second after the start, voltage recovers to above 87% of 4160v. This voltage dip and recovery analysis utilizes the results of dynamic **DG** characteristics reflected in the manufacturer's curve. The curve includes the combined effect of exciter and governor in order to provide recovery voltages.

In this calculation, the voltage dip was conservatively calculated from the Dead Load Pick up curve utilizing the total KVA loading on the DG bus. The Dead Load Pickup curve indicates that reactive load (KVAR) should be used to determine the voltage dip when using this curve. Even with that conservatism, the minimum voltage recovery after **1** second following the start is **87%** of 4160v. After one second, the voltage will continue to improve due to exciter and governor operation. These recovery voltages during the motor starting period (after the first second) are much better than the voltage expected during operation from the offsite power source under degraded voltage condition.

Due to momentary sharp voltage drops below 61% during large motor starting, certain contactors or relays may drop out, and that could cause some control circuits to de-energize. Table 2A of this calculation shows that none of the 480V DG powered loads have a seal-in circuit, and therefore these loads will restart as soon as the adequate voltage returns. The calculation shows that the voltage will recover to more than 87% within 1 second following the start and will continue recover to 100% voltage due to

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CALCULATION PAGE

CALC NO. 9389-46-19-3 REVISION 004 **PAGE NO. 11.0-3 Xl** COMPARISON OF **RESULTS** WITH **ACCEPTANCE** CRITERIA (cont'd) Comparison of results with Acceptance Criteria when DG2/3 powers Unit 3 loads A. Continuous loading of the Diesel Generator The results of the calculation show that the maximum continuous load on the Diesel Generator is 2638 kW (ETAP Scenario DG2/3 T=10+m), which is above the 2600kW continuous rating of the Diesel Generator. However, this loading value is well within the 2860kW 2000hr rating of the DG. This loading value occurs only while the $1st$ CCSW pump is energized and prior to $R4$ de-energizing one of the two LPCI pumps. The maximum long term DG loading is 2518 kW when both CCSW pumps are in operation (ETAP Scenario DG2/3_CRHVAC). Therefore, from a continuous loading point of view the DG2/3 has adequate capacity to accept the emergency load under LOOP concurrent with LOCA in accordance with the acceptance criteria. If the EDG is at 102% of its nominal frequency, the EDG load is expected to be 1.02 3 or 1.06 times larger since input power is proportional to the speed cubed (Section V.5). This results in a maximum loading of 2638kW x **1.023** = 2800kW which is within the 2000 hr 2860kW rating of the diesel. **R4** The lowest power factor for the EDG load during the DG2/3 $T=10+m$, DG2/3 $T=10+m$ and DG2/3 CRHVAC is 87.9%. This value is below the 88% acceptance criteria. B. Transient loading of the Diesel Generator Results of this calculation show that the minimum recovery voltage after **I** second following the start of any large 4-kv motors is 87% of 4160V which is above the 80% recovery requirement in the acceptance criteria. This calculation shows that when the Core Spray Pump starts, the initial voltage dips below 61% of operating voltage (i.e. 4160v). However, within 1 second after the start, voltage recovers to at least 87% of 4160v. This voltage dip and recovery analysis utilizes the results of dynamic **DG** characteristics reflected in the manufacturer's curve. The curve includes the combined effect of exciter and governor in order to provide recovery voltages. In this calculation, the voltage dip was conservatively calculated from the Dead Load Pick up curve utilizing the total KVA loading on the DG bus. The Dead Load Pickup curve indicates that reactive load (KVAR) should be used to determine the voltage dip when using this curve. Even with that conservatism, the minimum voltage recovery after I second following the start is 87% of 4160v. After one second, the voltage will continue to improve due to exciter and governor operation. These recovery voltages during the motor starting period (after the first second) are much better than the voltage expected during operation from the offsite power source under degraded voltage condition. Due to momentary sharp voltage drops below 61% during large motor starting, certain contactors or relays may drop out, and that could cause some control circuits to de-energize. Table 2B of this calculation shows that none of the 480V DG powered loads have a seal-in circuit, and therefore these loads will restart as soon as the adequate voltage returns. The calculation shows that the voltage will recover to more than 87%

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XII CONCLUSIONS

The results of the calculation show that the maximum continuous running load under the maximum loading scenario is less than the 2860 kW 2000hr rating of the Diesel Generator. The loading of the DG at maximum R4 frequency of 102% is within the 2000 hr nameplate rating. Also, the worst voltage recovery after one second following the start of large 4kv motor (Core Spray Pump motor) is above 87% of DG terminal rated voltage. This 87% voltage recovery is above the minimum voltage recovery of 80% per the DG specification K-2183 requirement. The worst case power factor for the 10 minute and beyond time period is 87.7 which is below the acceptance criteria. The **DG** surveillance procedures and Technical Specification Bases should be R4 revises accordingly.

The starting times for LPCI Pumps 2A, 2B, 3A, and **38** are less than 4 seconds, and the starting time for Core Spray Pumps 2A and 3A are less than 5 seconds. All of these pump starting times are below the maximum allowable starting time of 5 seconds, and therefore, are acceptable.

Also, the analysis in Tables 2A & 2B for Unit 2 and Unit 3, respectively, and the detailed explanation under the Calculation and Results section show that while some of the control circuits may dropout during the lowest portion of the voltage dip, no adverse effects are identified and no protective devices are expected to operate. This calculation also shows that momentary voltage dip will not cause the travel time of any MOV to increase any longer than allowable.

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X1lI **RECOMMENDATIONS**

The worst case power factor for the 10 minute and beyond time period is 87.7 which is below the acceptance criteria. The Dresden Design/Licensing basis should be assessed to determine the impact due to this result.

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CALC NO. 9389-46-19-3 REVISION 004 **PAGE NO.** 14.0-1 **XIV REFERENCES** 1) S & L Standard ESI-167, Revision 4-16-84, Instruction for Computer Programs. 2) Operation Technology Software, ETAP PowerStation & Users Manual, Version 5.5.0N. $\left|\right.$ R4 3) Unused 4) Dresden DG 2/3 Calculation 7317-33-19-3, Revision 10. 5) Quad Cities **DG 1** Calculation 7318-33-19-1, Revision 0. 6) Dresden Units 2 & 3, Equipment Manual from GE, Number GEK-786. 7) Dresden Re-baselined Updated FSAR, Revision **0.** 8) Guidelines for Estimating Data (Used by Electrical Analytical Division in Various Projects like Clinton, Byron & Braidwood), which is used for determining % PF and efficiency (Attached). 9) ANSI **/** IEEE C37.010-1979 for Determining XIR Range for Power Transformers, and 3-phase Inductor Motor, 10) S & L Standard ESA-104a, Revision 1-5-87, Current Carrying Capacities of Copper Cables. **11)** *S* & L Standard ESA-102, Revision 4-14-93, Electrical & Physical Characteristics of Electrical Cables. 12) Specification for Diesel Engine Generator Sets K-2183, Pages 3 and **8** (Attached). 13) Dead Load Pickup Capability (Locked Rotor Condition) - Generator Reactive Load vs. % Voltage Graph (#SC-5056) by Electro-Motive Division (EMD) (Attached). 14) Speed - Torque - Current Curve (#297HA945-2) for Core Spray Pump by GE (Attached). 15) Speed - Torque - Current Curve (#857HA264) for RHR/LPCI Pump by GE (Attached).

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 $\label{eq:2} \frac{1}{\sqrt{2}}\sum_{i=1}^n\frac{1}{\sqrt{2}}\sum_{i=1}^n\frac{1}{\sqrt{2}}\sum_{i=1}^n\frac{1}{\sqrt{2}}\sum_{i=1}^n\frac{1}{\sqrt{2}}\sum_{i=1}^n\frac{1}{\sqrt{2}}\sum_{i=1}^n\frac{1}{\sqrt{2}}\sum_{i=1}^n\frac{1}{\sqrt{2}}\sum_{i=1}^n\frac{1}{\sqrt{2}}\sum_{i=1}^n\frac{1}{\sqrt{2}}\sum_{i=1}^n\frac{1}{\sqrt{2}}\sum_{i=1}^n\frac{1$

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In addition to the above listed drawings, the draw the drawings listed in any Table **I** or Table 2 are also considered as references for this calculation.

- 17.) GE Drawing 992C510AB, Dresden Core Spray Pump Motor (Attached).
- 18.) GE Drawing 992C510, Dresden LPCI Pump Motor (Attached).
- 19.) IEEE Standard 399-1980, Chapter 8, for determining motor starting voltage drop at the source when some running load is is already present
- 20.) **S** & L Standard, ESI-253, Revision 12-6-91, Electrical Department instruction for preparation, review, and approval of electrical design calculations
- 21.) S & L Standard ESC-307, Revision 1-2-64, for checking voltage drop in starting ac motors
- 22.) Western Engine letter dated 1/19187 to Mr. Wayne Hoan identifying the voltage dip curve applicable to Dresden and Quad Cities (Attached).
- 23.) Strip Chart for Diesel Generator 2/3 Surveilence Test: Dated March 7, 1992 (Attached).
- 24.) Walkdown Data for Diesel Generator 2/3 dated April 15, 1994 (Attached).
- 25.) DIT DR-EAD-0001-00 regarding the Battery Charger and UPS Models (Attached).
- 26.) Dresden Unit 2 Electrical Load Monitoring System (ELMS) AC, Calculation Number P.2. | 7317-43-19-1, Revision 18.
- 27.) Dresden Unit 3 Electrical Load Monitoring System (ELMS) AC, Calculation Number 22.. I7317-43-19-2, Revision **16.**

- 28.) DIT DR-EPED-0860-00; Loading Change for Dresden Unit 2 Division **I** (Attached).
- 29.) CIS-2: Tabulation for cables lengths (Attached).
- 30.) Dresden Re-baselined Updated FSAR, Revision 0, Table 8.3-3; DG loading due to Loss of Offsite AC Power (Attached).
- 31,) Dresden Re-baselined Updated FSAR, Revision 0, Figure 8.3-6 and 8.3-7, DG loading under Accident Condition (Attached).
- 32.) Dresden Station Fire Protection Reports Safe Shutdown Report dated July 1993, Table 3.1-1, DG Loading for Safe Shutdown (Attached).
- 33.) DIT DR-EPED-0862-00; Loading Change for Dresden Unit 3 Division **I** (Attached).
- 34.) DOP 0202-01, Revision 13; Unit 2 Reactor Recirculation System Startup (Attached).
- 35.) DELETED
- 36.) Calculation for Evaluation of 3HP, 460V CCSW Motor Minimum Voltage Starting Requirements; Calculation Number 9215-99-19-1, Revision 1.
- 37.) 4160 Volt Switchgeart Specification K-3141 (page 3-5 attached)
- .38.) Calculation for Single Line Impedance Diagrams for ELMS-AC; Calculation 7317-38-19-1, Revision 1.
- 39.) S & L Standard ESC-193, Revision 9-2-86, Page 5 for Determining Motor Starting Power Factor.
- 40.) Walkdown data for CCSW Pumps 2A, 28, 2C, and 2D dated December 14, 1994; and walkdown data for CCSW Pumps 3A, 3B, 3C, and 3D dated December 15, 1994 (Attached).
- 41.) **S** & L Standard ESC-165, Revision 11-3-92, Electrical Engineering Standard.for Power Plant Auxiliary Power System Design.
- 42.) Letter addressed to E. Guse from G.C. Mulick dated March 8, 1967 regarding EMD Inquiry No. 66-708 (attached).
- 43.) Hand calculation to determine LRC for CCSW Pumps (Attached).

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Table **IA**

Automatically Turn On and Off Devices Under the Design Basis Accident Condition Dresden Station - Unit **213** (Swing Diesel) EDG 2/3 Powering Unit 2

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Automatically Turn On and Off Devices Under the Design Basis Accident Condition

Dresden Station - Unit 2/3 (Swing Diesel)

EDG 2/3 Powering Unit 2

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Automatically Turn On and Off Devices Under the

Design Basis Accident Condition

Dresden Station - Unit **2/3** (Swing Diesel)

EDG **213** Powering Unit 2

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Proj. No. 10014-012

Automatically Turn On and Off Devices Under the Design Basis Accident Condition Dresden Station - Unit 2/3 (Swing Diesel)

			Diesden Oldubi - Ona 20 (Onnig Diesei) EDG 2/3 Powering Unit 2				
Bus No.	Equipment Description/No.	Load Shed	Known Fact	Assumption / Eng. Judgement	Dwg. Ref.		ReviOther Ref. (P & ID)
$28 - 1$ E ₂	Shutdown Cooling Inlet Isolation Valve 2B (2-1001-1B)	No	NC and interlocked closed.		12E-2508A 12E-2508 12E-2501 Sh. 1 & 2	F M AC	$\overline{\text{M}32}$
$28 - 1$ E ₃	RWCU Isolation Valve Bypass $(2-1201-1A)$	No	NC and remains closed.		12E-6816D	\overline{F}	
$28-1$ E4	Core Spray Pump Recirc. Isolation Valve 2A (2-1402-38A)	No	NO and interlocked open, but when flow is over low flow level, valve will close (10 seconds after UV reset).		12E-2433	$\overline{\mathbf{M}}$	$\overline{M27}$
$28 - 1$ F ₁	Diesel Transfer Pump 2/3 $(2/3 - 5203)$	No	Will operate in auto (0 seconds).	Assume in auto.	12E-2351B Sh.1	AA	M41/2
$28 - 1$ F ₂	RX Building Emergency Lighting $(2-7902)$	No	Has 1 minute time delay; enter in calculation 10 seconds after UV relay resets.		12E-2674C	\mathbf{u}	
$28 - 1$ F ₃	LPCI Core Spray Pump Area Cooling Unit 2A (2-5746-A)	No	Controlled by thermostat.	Assume cooler starts at 0 seconds after UV reset.	12E-2393	$\overline{\mathsf{K}}$	
$28-1$ F ₄	Standby Liquid Control Pump 2A $(2-1102A)$	No	Will not operate with switch in OFF position.	Assume switch is in OFF position.	12E-2460	Ŧ	
$28-1$ G ₃	Diesel Gen 2/3 Vent Fan (2/3- 5790) (Normal Feed)	No	Will operate in auto (0 seconds).	Assume in auto.	12E-2351B Sh. 2 12E-2674D	AA \mathbf{s}	M1297
$28 - 1$ H1	Core Spray Outboard Isolation Valve 2A (2-1402-24A)	No	NO and interlocked open.		12E-2431 Sh. 1	$\overline{\mathbf{x}}$	M27
$28 - 1$ H ₂	Core Spray Inboard Isolation Valve 2A (2-1402-25A)	N _o	NC and interlocked open.	For conservatism, assume low pressure permissives coincide with Core Spray Pump start (10 seconds after UV relay reset).	12E-2431 Sh. 1 12E-2430	$\overline{\mathsf{x}}$ AF	M27

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Automatically Turn On and Off Devices Under the really furn On and Off Devices C

Design Basis Accident Condition
Dreaden Station - Unit 2/3 (Swing Diesel)

Diesden Station - Onli 23 (Swing)
EDG 2/3 Powering Unit 2

Calc **Rev. 2** Proj. No. 10014-012

Table IA

Automatically Turn On and Off Devices United States United States United States United States United States U
Turn Off Devices United States United States United States United States United States United States United St nically Turn On and Off Devices Design Basis Accident Condition
Dresden Station - Unit 2/3 (Swing Diese
1 EDG 2/3 Powering Unit 2

			EDG 2/3 Powering Unit 2				
Bus No.	Equipment Description/No.	Load Shed	Known Fact	Assumption / Eng. Judgement	Dwg. Ref.		Revolter Ref. (P & ID)
$28 - 1$ L1	Torus Spray Valve 2A $(2-1501-38A)$	No	NC and interlocked closed.		12E-2441 Sh. 1 12E-2437	W AH	M29/1
$28 - 1$ L2	Torus Spray Valve 2B $(2-1501-20A)$	No	NC and interlocked closed.		Sh. 1 & 2 12E-2441 Sh. 2 12E-2437	W AH	M29/1
$28 - 1$ L3	Torus Ring Spray Valve 2A $(2-1501-18A).$	No	NC and interlocked closed.		Sh. 1 & 2 12E-2441 Sh.1 12E-2437 Sh. 1 & 2	W AH	M29/1
$28 - 1$ L4	Torus Ring Spray Valve 2B $(2-1501-19A)$	No	NC and interlocked closed.		12E-2441 Sh. 2 12E-2437 Sh. 1 & 2	W AH	M29/1
$28 - 1$ M ₂	LPCI Pumps Drywell Spray Discharge Valve 2B $(2-1501-28A)$	N _o	NC and interlocked closed.		12E-2441 Sh.3 12E-2347 Sh. 1 & 2	w AH	M29/1
$28 - 1$ M3	LPCI Header Crosstie Isolation Valve 2A (2-1501-32A)	No	NO and remains open.		12E-2440 Sh.3	Z	M29/1
$28 - 1$ N1	LPCI Pump Flow Bypass Valve 2A (2-1501-13A)	No	NO and interlocked open but when flow is over low flow level. valve will close (0 seconds after UV relay reset).		12E-2440 Sh. 2 12E-2437 Sh.2	\overline{z} AH	M29/1
$28 - 1$ N2	LPCI Heat Exchanger Bypass Valve 2A $(2-1501-11A)$	No	NO and interlocked open.		12E-2440 Sh. 2 12E-2437A 12E-2437 Sh.1	\overline{z} $\boldsymbol{\mathsf{x}}$ AH	M29/1

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Table **1A** \blacksquare Turn \blacksquare Turn \blacksquare \blacksquare \blacksquare

atically Turn On and Off Devices **Design Basis Accident Condition Dresden Station - Unit 2/3 (Swing Diesel)**
EDG 2/3 Powering Unit 2

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Automatically Turn On and Off Devices Under the Design Basis Accident Condition Dresden Station - Unit 2/3 (Swing Diesel)

EDG **213** Powering Unit 2

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Table **1A Automatical Turn Turn Off Devices United States United States United States United States United States United**

ically Turn On and Off Devices L **Design Basis Accident Condition** Dresden Station - Unit 2/3 (Swing Diesel)
EDG 2/3 Powering Unit 2

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Table **1A** Automatically Turn On and Off Devices United Devices United States United States United States United States U

tically Turn On and Off Devices i **Design Basis Accident Condition**

Dresden Station - Unit 2/3 (Swing Diesel)
EDG 2/3 Powering Unit 2

Calc. No. 9389-46-19-3 **Rev. 2** Proj. No. 10014-012 **.** Page **I I** of 12 **D2EXCEL.XLS - U2** Table **^I**

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N.O. - Normally Open

N.C. - Normally Closed

N/A - Not Available

Note: All loads that are tripped off and interlocked off or require manual action to restart are considered Load Shed. Operating loads and loads with auto start capabilities that have power available and do not operate (i.e. an MOV that is N.O. and remains open) is considered NOT load shed.

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AFFECTS Of VOLTAGE DIP

PURPOSE

The purpose of Table 2 is to determine the affects of an AC voltage dip, that is low enough to de-energize control circuits ie., contactors, relays, etc., has on the operation of the mechanical equipment.

METHOD

Table 2 shows the results of the review. The conclusion of Table 2 is shown in the analysis of data section Below is the explanation for each column in Table 2.

Table 2 Column Description

Equipment Description/Ho.

Will the voltage dip at 5 seconds, 10 seconds, and 10 minutes affect the equipments' operation

(Question 1)

Explanation of What is Shown in the Column

This column lists all of the loads connected to the DG buses. It is the *same* list as shown In Table **1.**

Load Shed **All loads that are tripped off and interlocked off or require** manual action to restart are considered load shed. Operating loads and loads with auto start capabilities that have power available that do not operate **(** i.e. an MOV that is N.O. and remains open) Is considered not load shed.

> The "affect" looked for is that the control circuit per the'referenced schematics'is de-energized or energized by a voltage dip. If the circuit was not energized before the dip and/or the energized state of the circuit did not change due to a dip, the answer is no. If the energized state of the circuit changed, the answer is yes.

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AFFECTS OF A VOLTAGE DIP

Table 2 Column Description

Will the equipment restart after the voltage recovery

(Question 2)

Will the equipment operate in an adverse mode due to a voltage dip

(Question 3)

Will the time delay in operation cause any adverse affect

(Question 4)

Explanation of What is Shown in the Column

This question is to verify that equipment required is restarted automatically after a voltage dip. Only AC control circuits need to be considered. DC control circuits will be unaffected by an AC voltage dip. Circuits that have seal-in- contacts are types that would not restart.

If the answer to Question 1 is yes, and to Question 2 is yes, then Question 3 has to be answered. The "adverse modes" looked for are items like, valves moving in the wrong direction, time delay relays being reset by the dip causing equipment to operate for shorter or longer periods than required, etc.

If the answer to Question 1 is yes, and 2 Is yes, Question 4 has to be answered. The time delay referred to is the one second it takes the DG to recover **to** above 80% after the start of a large motor. The adverse affects looked for are items like, could within one second the room temperature rise excessively if a cooler is de-energized, if a valve travel requires one more second to operate will its total travel time exceed design limits, etc.

The "no" answers to this question are based on the following engineering judgements:

- a. Some valves may require two seconds more to complete its travel. Valves operate normally less than a minute. The allowable total time is 120 seconds. Therefore with a voltage dip, the design allowable is not exceeded.
- b. Two-second time delays in room coolers, pumps, etc. would not cause rooms, equipment, etc. to overheat, etc.

AFFECTS OF A VOLTAGE DIP

Drawing Reference

Revision

Other Reference

Table 2 Column Description Explanation of What is Shown in the Column

c. Instrument bus loads may give erroneous readings for a fraction of a second due to momentary sharp voltage drop. But the instrument bus is designed with transfer switch, which takes about one second to transfer the loads. Therefore, the operators are familiar with the behavior of these loads during abnormal condition. This will not require any special attention of the operators.

This drawing shows the main schematic or wiring diagram for the control circuit reviewed.

This is the revision number of the drawing referenced above.

Other references used to understand the operation of control circuit may be listed here or see the main reference section of this calculation.

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Pape 1 of 21 02EXCELXLS - U2 Table 2 \mathcal{L}

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TABLE **2A** AFFECTS OF VOLTAGE DIP

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Calc. No **Revision 2** Page No. B8
Proj. No. 10014-12

h Ω ₂ of 21 D2EXCEL, XLS - U2 Table 2

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Bus No. Equipment Description/No. Load Will the voltage dips @ Will the equipment start Will the UVIII the time delay in Dwg. Ref. Rev Other
Shed 5s, 10s, & 10min. affect after voltage recovery ? equipt. operation cause an $\overline{ }$ adverse mode due to the voltage dips ? Return Vlv No The Will stop Yes No. N.O. and Yes. Will increase 12E-2507B F M-Vge Vahmudletor **28-1** Indb Cond Return Viv **No** J3 $(2-1301-4)$ interlocked operating time. However, 12E-2506
closed. increased time will be Sh. 1 & 2 28-1 Steam Line Isol Viv No Yes. Valve will stop **Yes** No. N.O. and Yes. Will increase 12E-25078 F M-28 (2-1301-1) momentarily. Interlocked operation of the Sh. 1 & 2
How No. N.O. and Yes. Will increase 12E-25078 F M-28 (2 interlocked operating time. However, 12E-2506
closed. increased time will be (Sh. 1 & 2 28-1 Cosed. Increased time will be Sh. 1 & 2
28-1 LPCI Pump 2004 Anithin acceptable limits. Note 1. No. No. 1 & 2 12E-2440 **Z** M-29
Sh. 1 Sh. 1 K₁ 28-1 **I** 12E-2437 **AH** LPCI Pump $2B = 2437$ A H $28 - 1$ LPCI Pump 2B Suction Valve (2-12E-2440 **2** M-29
Sh. 1 Sh. 1 12E-2437 **AH** Sh, 1
12E-2437 **AH** Sh, 1
12E-2437 **AH** Sh, 1 I Pumps Drywell Spray | No | No. Note 1. | NVA | NVA | NVA | 12E-2440 | Z | M K3 Sh. 3
12E-2437 $Sh.1$ **2-1501-27A)** (2.1501-27A) $(2-1501-27A)$ 28-1 Stm/lso Inbd Cond Viv (3-1301-1 & No No. Note 1.
28-1 Stm/lso Inbd Cond Viv (3-1301-1 & No No. Note 1. 28-1 Stm/lso Inbd Cond VIv (3-1301-1 No. Note 1. N/A N/A N/A 12E-3507B F 9
01-4)(alternate feed) 3-1301-4)(alternate feed)
Torus Spray Valve 2A $rac{K4}{28-1}$ N/A **N/A** 12E-2441 | W | M29, $L1$ $(2-1501-38A)$ $\begin{array}{|c|c|c|c|c|}\n\hline\n\text{12E-2437}\n\hline\n\end{array}$ Sh. 1 Sh. 1 & 2

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TABLE 2A AFFECTS OF VOLTAGE DIP

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D2EXCEL.XLS - U2 Table 2

TABLE 2A

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D2EXCEL.XLS - U2 Table 2

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 \blacksquare TABLE ZA

Bus No. | Equipment Description/No. | Load | Will the voltage dips @ | Will the equipment start | Will the | Will the time delay in | Dwg. Ref. | Rev | Other | Shed | 5s, 10s, & 10min. affect | after voltage recovery ? | e **I** the equipment's operation **and the equipment's operation** advarse mode due to dips **?** \mathbf{I} MCB Process Radiation Monitor No Yes. Will lose power Yes No No No 12E-2489 AP temporarily. Condensity of the Cond Rus MCR Process Padjation Monitor Inst. Bus $Ckt3$ valve 12e-2359 Paul II temporany. (Cambridge 12e-2359 Paul II temporany. (Cambridge 12e-2359 Paul II temporany
Condenses See Travel I temporany. 12E-2731 P
12E-2728 AB Drain Valve $12E-2729$ $12E-2729$ $12E-2729$ No Yes. $\frac{1}{2}$ 12E-2733 Inst. Bus | ATWS Recirc. Pump Trip System & **No** Yes. Will lose power 12E-6583C L
12E-2576 D Ckt 4 Annunciator Failure Indication temporarily. 12E-2576
12E-6583A $\mathbf R$ instruction and the cleanup $\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$ in the cleanup System No Yes. Will $\begin{bmatrix} 12\text{E-0583A} \\ 12\text{E-02816B} \end{bmatrix}$ $\frac{12E-2815J}{2E-2815J}$ \mathbf{F} 12E-2815J Inst. Bus Reactor Water Cleanup System No Yes, Will lose power $\overline{\mathsf{P}}$ Instruments Reactor Value Champ System No Yes. Will lose power Yes No No 12E-2492 Ckt 5 **Frocess Process 6 Example 19 Let Bus Capture temporarily.**

Inst. Bus Reactor Recirc. Pump Seal Water No Yes. Will lose power $\frac{122-2751}{122-2751}$ \mathbf{T} Inst. Bus | Reactor Recirc. Pump Seal Water | No | Yes. Will lose power | Yes | Yes | No | No | 12E-2491 | 12E-2491 | Test | 12E-2491 | Test | 12E-2491 | Test Ckt 6 Pressure temporarily. This will be a series that a material of the Minister Pressure and No 12E-2750A (Ckt 6 Pressure
Inst. Bus **Annunciator Feed** External Control No Yes. Will lose power Yes No No No 12E-2745 Ckt 7 Ckt 8 _._temporaily. Inst. Panary Charge $\begin{array}{c} \begin{array}{c} \text{S} \\ \text{S} \end{array} \end{array}$ Ckt 8 Will lose power yes no no 12E-26035 Reserved the power Yes No 12E-26035 Reserved the Magazine State of the Magaz temporarily.
Yes. Will lose power Ckt 9 Instrument Isolators **No** 12E-2417 R
12E-2750B AC Ckt9 Instrument Isolators temporarily. 12E-2750B AC
12E-2750A AH Inst. Bus CRD Hydraulic System No Yes. Will lose power Yes No No 12E-2750A 12E-681 BAA 12E-681 BAA 12E-2496 G _12E-2496 C _012E-2496 G _012E-2496 D _012E-2496 C _012E-2750 A _012E-281 BAA 22E-2496 D _012E-2496 D _012E-2496 K. Ckt 10

Inst. Bus

Ckt 11

Ckt 12E-2751

Ckt 12E-2751

Ckt 12E-2768

Ckt 12E-2768

Ckt 12E-2768

Condition

Condition

Conditi Ckt 10
Inst. Bus Reactor Protection Scram No Yes. Will lose power J Ckt 12 temporarily. 12E-2699 80

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TAP I ABLE Z A

Calc. No. 8389-46-19-3 **Revision 2** Page No. B17 Proj. No. 10014-12

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Pape 14 **of** ²¹ D2EXCELXL\$ **-U2** TsWe 2

Calc. No. 9389-46-19-3 **Revision 2** Page No. 818 Proj. No. 10014-12

Bus No. Equipment DescripionrNo.

TABLE 2A AFFECTS OF VOLTAGE DIP

Calc. No. 9389-46-19-3 Revision 2 Page No. B19 Proj. No. 10014-12

TABLE 2A AFFECTS OF VOLTAGE DIP

Calc. No. 9388-48-19-3 Revision 2 **Papg** No. 820 Proj. No. 10014-12 **Pape 17 of 21 Pape 17 of 21 Pape 17 of 21 D2EXCELXI.S - U2 Table 2**

Calt. *No.* 938946-19.3 Revision 2 Page No. B21 Praj. No. 10014-12 **Property is a contract of the contract of the Page 18 of 21** Page 18 of 21

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Cac. **No.** 9388-4&-19-3 Revision 2 Page No. B22 Proj. No. 10014-12 **Pape 19 of 21 Pape 19 of 21** Pape 19 of 21 December 21 Dec

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TABLE 2A TABLE 2A

Pagp No. 823 Revision 2 Page No. 823 Proj. No. 10014-12

 $\left\langle \frac{d}{dt}\right\rangle_{\rm{QCD}}$

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Pope 20 **of** ²¹ **P2EXCELXLS- U2** Table 2

TABLE 2A AFFECTS OF VOLTAGE DIP

NC - Normally Closed

NO - Normally Open

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For further explanation of this table see Flow Chart No. 2.
Note 1: These loads have power available, however they do not operate.

Calc. No. 9389-46-19-3 **Revision 2** Page No. B24 Proj. No. 10014-12

Page 21 of 21 Days and **21** December 2014 - December 2016 - U2 **Days 2016** - U2 **Day**

DG Auxiliaries and Other 480V Loads Starting 0 Seconds after Closing of DG Breaker

FLC from KW **=** KW **1** (1.732 x kV x PF x eff.) FIC from $KVA = KVA / (1.732 \times kV) \times eff$

Starting KW (SKW) **=** 1.732 x kV x LRC% x **FLC** x SPF Starting KVAR (SKVAR) = 1.732 x kV x LRC% x FLC x sin(acos(SPF))

> Calculation No. 9389-46-19-3 Rev. 4 Attachment C Page **C1** of **C5**

DG Auxiliaries and Other 480V Loads Starting 0 Seconds after UV Relay Resets

Full Load Current (FLC) form HP **=** (HP x 746) **1** (1.732 x kV x PF x eff.) FLC from KW = KW **/** (1.732 x KV x PF x eff.) **FLC** from KVA **=** KVA / (1.732 x kV x eff.)

Starting KW (SKW) = 1.732 x kV x LRC% x **FLC** x SPF Starting KVAR (SKVAR) = 1.732 x kV x LRC% x FLC x sin(acos(SPF)) **I** R3

Calculation No. 9389-46-19-3 Rev. 3 Attachment C Page C2 of **CS**

DG Auxiliaries and Other 480V Loads Starting 10 Seconds after UV Relay Resets

Full Load Current (FLC) form HP = (HP x 746) **/** (1.732 x kV x PF x eff.) FLC from KW = KW I (1.732 x **kV** x PF x eff.) FLC from KVA = KVA **/** (1.732 x kV x eff.)

Starting KW (SKW) *=* 1.732 x kV x LRC% x FLC x SPF Starting KVAR (SKVAR) = 1.732 x **kV** x LRC% x FLC x sin(acos(SPF)) **I** R3

> Calculation No. 9389-46-19-3 Rev. 3 Attachment C Page C3 of **C5**

DG Auxiliaries and Other 480V Loads Starting at 10+ Minutes

Starting KVAR (SKVAR) = 1.732 x kV x LRC% x FLC x sin(acos(SPF))

Calculation No. 9389-46-19-3 Rev. 3 Attachment C Page C4 of C5

DG Auxiliaries and Other 480V.Loads Starting at 10++ Minutes

Full Load Current (FLC) form HP = (HP x 746) / (1.732 x kV x PF x eff.) FLC from $KW = KW/(1.732 \times kV \times PF \times eff.)$ FLC from KVA **=** KVA **1** (1.732 x kV x eff.)

Starting KW (SKW) **=** 1.732 x kV x LRC% x FLC x SPF Starting KVAR (SKVAR) = 1.732 x kV x LRC% x FLC x sin(acos(SPF)) **I** R3

> Calculation No. 9389-46-19-3 Rev. 3 Attachment C Page **C5** of **C5**

DRESDEN DIESEL GEN 2/3 LOAD BUS (LOOP AND LOCA CONDITION)

FIGURE 2A **-** DG AUXILIARIES AND OTHER 4kV AND 480V LOADS

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FIGURE **2A - DG** AUXILIARIES AND OTHER 4kV AND 480V LOADS

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(0s) **-0** seconds after closing of DG Breaker

Os - 0 seconds after UV reset

5s -5 seconds after UV reset

I0s - 10 seconds after UV reset

10-mrin - AU loads that automatically stop before 10 minutes are shown off.

10+min - CCSW Pump 2A is started.

10++min - CCSW Pump 28 is started with its auxiliaries.

10+++min. - Both CCSW Pumps are running and other loads starting after 10 minutes are shown here.

Attachment F

Diesel Generator connected using nominal voltage, 2 LPCI, This time period is less than **10** min into event.

LOAD FLOW REPORT

Indicates a voltage regulated bus (vollage controlled or swing type machine connected to it)

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4 Indicates a bus with a load mismatch of more than 0. **1** MVA

Diesel Generator connected using nominal voltage, 2 LPCI, This time period is less than 10 min into event.

LOAD FLOW REPORT

Indicates a voltage regulated bus (voltage controlled or swing type machine conmected to it)

9 Indicates a bus with a load mismnatch of more than **0.1** MVA

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 $\bar{\mathcal{A}}$

Diesel Generator connected using nominal voltage. 2 **LPCI,** This time period is less than **10** min into event.

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LOAD FLOW REPORT

' Indicates a voltage rcgulated bus **(** vollage controlled or swing type machine connected to it)

Indicates a bus with a load mismatch of more **thoa 0. 1** MVA

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Convened from ELMS PLUS

Diesel Generator connected using nominal voltage, 2 LPCI, This time period is less than **1** 0 min into event.

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LOAD FLOW REPORT

 \bullet Indicates a voltage regulated bus (voltage controlled or swing type machine connected to it)

Indicates a bus with a load mismatch of more than 0.1 MVA

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Diesel Generator connected using nominal voltage, 2 LPCI, This time period is less than 10 min into event.

 $\ddot{}$

LOAD FLOW REPORT

***** Indicates a voltage regulated bus (voltage controlled or swing type machine connected to it)

4 Indicates a bus with a load mismatch of more than **0.1** MVA

l,

Diesel Generator connected using nominal voltage. 2 LPCI Pump, I CCSW, This time period is **10+** min into event.

LOAD FLOW REPORT

Indicates a voltagc regulated bus(voltage conlrollcd or swing **lype** machine connecced to it)

4 Indicates a bus with a load mismatch of more than **0.1** MVA

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 $\left(\right)$

Diesel Generator connected using nominal voltage, I LPC[Pump, 2 CCSW. This time period is 10+ *min* into event.

Bus Load Load Load Load Load Load Load Thow XFMR **1D** kV kV *Ang.* MW Mvar MW Mvar ID MW Mvar Ainp % PF % Tap 4KV SWOR 23 4.160 4.150 **-0.1** 0 0 0.711 0.395 4KV SWGR 23-1 -0.771 -0.395 120.5 **89.0** 4KV SWGR 23-1 4.160 4.153 **-0.1** 0 0 1.194 0.542 HIGH SIDE OF XFMR 28 0.438 0.364 79.2 **77.0** 4KV SWOR 23 0.771 0.396 *120.5* 89.0 4KV SWING BUS 40 -2.404 -1.301 380.0 87.9 14KV SWING BUS 40 4.160 4.160 **0.0** 2.407 1.306 0 0 4KV SWGP. 23-1 2.407 1.306 380.0 87.9 28-1 ALTF3-1301-1&4 0.480 *0.475 -1.6* 0 0 0 0 480V MCC28-1 0.000 0.000 0.0 0.0 125V DC CHGR 2A 0.480 0.461 **-1.1** 0 0 0.034 0.028 480V MCC 28-2 -0.034 **-0.028** 55.0 77.5 250V DC CHGR 2 0.480 0.466 -1.6 0 0 0.066 0.055 480V MCC 28-3 .0.066 -0.055 106.2 77.1 480V MCC28-1 0.480 0.475 *-1.6* 0 0 0.067 0.040 480V SWOR 28 .0.067 .0,040 94.4 *85.8* 28-1 ALTF3-1301-1&4 0.000 0.000 0.0 0.0 #80V MCC 28-2 0.480 0.470 -1.8 0 0 0.130 0.134 480V SWGR28 -0.165 -0.162 283.8 71.4 125V **DC** CHGR 2A 0.035 0.028 55.0 78.3 480V MCC•28-3 0.480 0.470 -1.8 0 0 0.132 0.079 480V SWGR 28 -0,199 **-0.134** 294.2 **83.0** 250V DC CHOR 2 0.067 0.055 **106.2** 77.4 480V MCC 28-7 0.480 0.477 -1.7 0 0 0 0 480V SWGR 28 0.000 0.000 0.0 0.0 0.0 480V MCC 29-7 0.000 0.000 0.00 0.0 480V MCC 29-7 0.480 0.477 -1.7 0 0 0 0 480V MCC 28-7 0.000 0.000 0.0 0.0 0.0 480V SWOR 28 0.480 0.477 -1.7 0 0 0 0 480V *MCC* 28-1 0.067 0.040 94.4 *85.8* 480V MCC 28-2 0.167 0,165 283.8 71.2 480V MCC 28-3 0.201 0.136 294.2 82.8 480V MCC 28-7 0.000 0.000 0.0 0.0 HIGH SIDE OF XFMR 28 -0.436 -0.341 669.1 78.7 HIGH SIDE OF XFMR 28 4.160 4.152 -0.1 0 0 0 0 4KV SWGR 23-1 -0.438 -0.363 79.2 77.0 480V SWGR 28 0.438 0,363 79.2 77.0 -2,500

LOAD FLOW REPORT

^{*} Indicates a voltage regulated bus (voltage controlled or swing type machine connected to it)

***** Indicates a bus with a load mismatch of more than 0.1 MVA

Diesel Generator connected using nominal voltage, I LPCI Pump, 2 CCSW, This time period is I 0+ min into event.

LOAD FLOW REPORT

I Indicates a vollage regulated bus (voltage controlled or swing lype machine connected to it)

4 Indicates a bus with a load mismatch of more than 0. **1** MVA

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Automatically Turn On and Off Devices Under the Design Basis Accident Condition Dresden Station - Unit 2/3 (Swing Diesel)

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Automatically Turn On and Off Devices Under the Design Basis Accident Condition

Dresden Station - Unit **2/3** (Swing Diesel)

__EDG **213** Powering Unit 3

Calc. No. 9389-46-19-3 Rev. 2 Page H2 Proj. No. 10014-012 Page 2 of 12 **D3EXCELXLS - U3** Table **¹**

 $\omega = \omega$.

 $\alpha \rightarrow \infty$

Table 1B

Automatically Turn On and Off Devices Under the Design Basis Accident Condition

Dresden Station - Unit **2/3** (Swing Diesel)

EDG **213** Powering Unit 3

CaIc. No. 9389-46-19-3 Rev. 2 Page H3 Proj. No. 10014-012 Page **3** of 12 **D3EXCEL.XLS - U3** Table **^I**

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$\frac{1}{2}$ Turn On and Off Devices in Design Basis Accident Condition Dresden Station - Unit 2/3 (Swing Diesel)
EDG 2/3 Powering Unit 3

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Page 4 of 12 D3EXCEL.XLS - U3 Table 1

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Automatically Turn On and Off Devices Under the

Design Basis Accident Condition

Dresden Station - Unit **213** (Swing Diesel) EDG **213** Powering Unit 3

Cale. No. 9389-46-19.3 Rev. 2 Page **H5** Proj. No. 10014-012 Page **5** of 12 D3EXCELJXLS - U3 Table 1

Automatically Table 1B tically Turn On and Off Devices **Design Basis Accident Condition**

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Automatically Turn On and Off Devices Under the Design Basis Accident Condition

Design Dasis Accident Condition
|Dresden Station - Unit 2/3 (Swing Diesel) EDG 2/3 Powering Unit 3

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Automatically Turn On and Off Devices Under the

Design Basis Accident Condition

Dresden Station - Unit 2/3 (Swing Diesel)

EDG **213** Powering Unit 3

Calc. No. 9389-46-19-3 Rev. 2 Page **H8** Page 8 of 12 D3EXCEL.XLS - U3 Table 1

Table 1B Automatical Turn On and Off Devices United Devices United Devices United States Un

$\mathfrak b$ cally Turn On and Off Devices I Design Basis Accident Condition Dresden Station - Unit 2/3 (Sw<u>in</u>
FDG 2/3 Bowering Unit

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Automatically Turn On and Off Devices Under the Design Basis Accident Condition Dresden Station - Unit 2/3 (Swing Diesel)
EDG 2/3 Powering Unit 3

Cale. No. 9389-46-19-3 Rev. 2 Page HIO Proj. No. 10014-012 **Page 10 of 12** Date 10 of 12 D3EXCEL.XLS - U3 Table 1

Automatically Turn On and Off Devices Under the Design Basis Accident Condition Dresden Station - Unit 2/3 (Swing Diesel) EDG 2/3 Powering Unit 3

Calc Rev. 2 Page H11 Proj. No. 10014-012

Automatically Turn On and **Off** Devices Under the Design Basis Accident Condition Dresden Station - Unit 2/3 (Swing Diesel)

EDG **2/3** Powering Unit 3

,N.O. -Normally Open

N.C. - Normally Closed

N/A - Not Available

Note: All loads that are tripped off and interlocked off or require manual action to restart are considered Load Shed.

Operating loads and loads with auto start capabilities that have power available and do not operate (i.e. an MOV that is N.O. and remains open) is considered NOT load shed.

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TABLE 28

AFFECTS OF VOLTAGE DIP

PURPOSE

The purpose of Table 2 is to determine the affects of an AC voltage dip, that is low enough to de-energize control circuits le., contactors, relays, etc., has on the operation of the mechanical equipment.

METHOD

Table 2 shows the results of the review. The conclusion of Table 2 is shown in the analysis of data section. Below is the explanation for each column in Table 2.

Table 2 Column Description

Equipment Description/No.

Load Shed

Will the voltage dip at 5 seconds, 10 seconds, 5 Secongs, 10 Secongs,
and 10 minutes affect the and 10 minutes affect

(Question 1)

Explanation of What is Shown in the Column

This column lists all of the loads connected to the DG buses. it is the same list as shown in Table 1.

This column answers the question "when a LOOP/LOCA occurs, does this load automatically de-energize to shed load on the bus?" it is the same list as shown in Table 1. It is shown again because any load de-energized will not be affected by a voltage dip. **If** there is a yes in this column, the answer to the other questions will be "no" or "N/A" (not applicable).

The "affect" looked for is that the control circuit per the referenced schematics is de-energized or energized by a voltage dip. **If** the circuit was not energized before the dip and/or the energized state of the circuit was not energized before the dip and/of the energized state of the energized state of the mergized state of the energized state of the energized state of the energies of the state of the state of the state of the state of ald not change que to a uip, the answer is no. It the energized state
the circuit changed, the answer is yes.

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AFFECTS OF A VOLTAGE DIP

Table 2 Column Description

Will the equipment restart after the voltage recovery

(Question 2)

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Will the equipment operate in an adverse mode due to a voltage dip

(Question 3)

Will the time delay in operation cause any adverse affect

(question 4)

Explanation of What is Shown in the Column

This question is to verify that equipment required is restarted auto matically after a voltage dip. Only AC control circuits need to be considered. DC control circuits will be unaffected by an AC voltage dip. Circuits that have seal-in contacts are types that would no restart.

If the answer to Question 1 is yes, and to Question 2 is yes. then Question 3 has to be answered. The 'adverse modes" looked for are items like, valves moving in the wrong direction, time delay relays being reset by the dip causing equipment to operate for shorter or longer periods than required, etc.

If the answer to Question **1** is yes, and 2 is yes, Question 4 has to be answered. The time delay referred to is the one second it takes the DG to recover **to** above 80% after the start of a large motor. The adverse affects looked for are items like, could within one second the room temperature rise excessively if a cooler is de-energized, if a valve travel requires one more second to operate will its total travel time exceed design limits, etc.

The "no" answers to this question are based on the following engineering judgements:

- a. Some valves may require two seconds more to complete its travel. Valves operate normally less than a minute. The allowable total time is 120 seconds. Therefore with a voltage dip, the design allowable is not exceeded.
- b. Two-second time delays in room coolers, pumps, etc. would not cause rooms, equipment, etc. to overheat, etc.

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TABLE 2B

AFFECTS OF A VOLTAGE DIP

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Table 2 Column Description Explanation of What is Shown in the Column

c. Instrument bus loads may give erroneous readings for a fraction of a second due to momentary sharp voltage drop. But the instrument bus is designed with transfer switch, which takes about one second to transfer the loads. Therefore, the operators are familiar with the behavior of these loads during abnormal condition. This will not require any special attention of the operators.

Drawing Reference This drawing shows the main schematic or wiring diagram for the control circuit reviewed.

Revision **This is the revision number of the drawing referenced above.**

Other Reference **Other references** used to understand the operation of control circuit may be listed here or see the main reference section of this calculation.

$T_{\text{max}} = 2$ TABLE 2B <u>AFFECTS OF VOLTAGE DIP</u>

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Bus Dresden Station - Unit 2/3 (Swing Diesel)
EDG.2/3 Powering Unit 3

	DG 2/3 Powering Unit 3	

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TABLE 2B AFFECTS OF VOLTAGE DIP

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Proi. **No.** 10014-012

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TABLE 2B $\frac{1 \text{ ADEE } \angle \text{D}}{1 \text{ ADEE } \angle \text{D}}$

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Dresden Station - Unit **213** (Swing Diesel)

Calc. No. 8389-46-19-3 **Revision 2 Pape No. 16 3of 15 3of 15**

TABLE 2B $\underline{\text{ADLE 2D}}$

DRESS OF VOLTAGE DIE

				EDG 2/3 Powering Unit 3					
Bus No.	Equipment Description/No.	Load Shed	Will the voltage dips @ 5s, 10s, & 10min. affect the equipment's operation	Will the equipment start after voltage recovery ?	Will the equipt. operate in adverse mode due to! the voltage dips?	Will the time delay in operation cause any advarse affect?	Dwg. Ref.	Rev	Other Ref.
$38-1$ B2	Standby Liquid Control Tank Heater $(3-1103)$	No	No	Yes	No	NJA	12E-3460 Sh. 1 12E-3674A	AD AF	
38-1 B3	Standby Liquid Control Pump 3A $(3-1102A)$	No	No. Note 1.	N/A	NIA	N/A	12E-3460 Sh. 1	AD	
38-1 C1	LPCI/Core Spray Pump Area Cooling Unit 3A (3-5746A)	No	Yes. Fan slows down momentarily.	Yes	No	N/A	12E-3393	$\overline{\mathsf{N}}$	
$38-1$ C ₂	Diesel Oil Transfer Pump 2/3 (2/3-5203) (alternate feed)	No	Yes. Pump will slow down momentarily.	Yes	No	N/A	12E-2351B Sh.1	AF	
$38-1$ C ₃	Drywell and Torus Purge Exhaust Fan 3A (3-5708A)	Yes	N/A	N/A	NJA	N/A	12E-3393	M	
$38-1$ C ₄	Diesel 2/3 Vent Fan $(2/3 - 5790)$ (alternate feed)	No ⁻	Yes. Fan slows down momentarily.	Yes	No	N/A	12E-2351B Sh. 2 12E-3674B	AL. Y	
$38 - 1$ D ₁	Stm Iso/Inbd Con Viv Alt Fd 2-1301-1 and 2-1301-4 (alternate feed)	No	No. Note 1.	NJA	NJA	N/A	12E-2507B	M	
$38-1$ D ₂	Torus Drywell Compressor 3A (3-8551-A)	Yes	N/A	N/A	N/A	N/A	12E-3372	$\overline{\mathbf{R}}$	

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Pape 4 of 15 4EXCELXLS **-**U3 Tags --U3 T

TABLE 2B $A = A + B$

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TABLE 2B $\underline{\text{I} \text{A} \text{B} \text{C} \text{E} \text{B}}$

Dresden Station - Unit **213** (Swing Diesel)

				EDG 2/3 Powering Unit 3					
Bus No.	Equipment Description/No.	Load Shed	Will the voltage dips @ 5s, 10s, & 10min. affect the equipment's operation	Will the equipment start after voltage recovery ?	Will the equipt. operate in advarse mode due tol the voltage dips ?	Will the time delay in operation cause any adverse affect?	Dwg. Ref.	Rev	Other Ref.
$38 - 1$ F ₁	Cleanup System Return Isolation Valve (3-1201-7)	No	Yes. Valve will stop momentarily.	Yes	No. NO and interlocked closed.	Yes. Will increase operating time. However, increased time will be within acceptable limits.	12E-3509A 12E-3509 Sh.2 12E-3501 Sh. 1 & 2	R AA AD, AD	
$38-1$ F ₃	RWCU Isolation Valve Bypass $(3-1201-1A)$	No	No. Note 1.	N/A	N/A	N/A	12E-7816D 12E-3509 Sh. 2	J AA	
$38-1$ F4	East LPCI/Core Spray Room Sump Pump 3A (3-2001-510A)	No	No. Note 1	N/A	N/A	N/A	12E-3674C	AG	
$38 - 1$ F4A	Post LOCA H2 & O2 Monitozing Sample Pump 3A $(3-2400-A)$	No	Yes. Pump will slow down momentarily.	Yes, Interlocked with LOCA signal.	No	N/A	12E-7554A 12E-7552 Sh. 2	J T	
38-1 G1	Closed Cooling Water Isolation Valve (3-3704)	No	No. Note 1.	NIA	N/A	N/A	12E-3674D	AA	
$38 - 1$ G2	Shutdown Cooling Return Isolation Valve 3A (3-1001- 5A)	\overline{N}	No. Note 1.	N/A	N/A	N/A	12E-3508E 12E-3508 12E-3501 Sh. 1 & 2	$\overline{\mathsf{N}}$ E AD, AD	
$38 - 1$ G3	Closed Cooling Water Drywell Return Valve 3A - $(3 - 3703)$	No	No. Note 1.	N/A	N/A	N/A	12E-3398	D	

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pape 8 of 15 13EXCELXLS. **-3 and 25 an**

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TABLE 2B

AFFECTS OF VOLTAGE DIP

Dresden Station - Unit 2/3 (Swing Diesel)
EDG 2/3 Powering Unit 3

				שטוי טווג ביט נטזאוואַ טוסטיון EDG 2/3 Powering Unit 3					
Bus No.	Equipment Description/No.	Load Shed	Will the voltage dips @ 5s, 10s, & 10min. affect the equipment's operation	Will the equipment start after voltage recovery ?	Will the equipt. operate in adverse. mode due to the voltage dips ?	Will the time delay in operation cause any adverse affect?	Dwg. Ref.	Rev	Other Ref.
$38 - 1$ G4	Shutdown Cooling Inlet Isolation Valve 3A $(3-1001-1A)$	No	No. Note 1.	N/A	N/A	N/A	12E-3508A 12E-3508 12E-3501 Sh. 1 & 2	Ł E AD, AD	
$38-1$ H1	Inbd Cond Return Valve $(3-1301-4)$ (normal feed)	No	Yes. Valve will stop momentarily.	Yes	No. NO and interlocked closed.	Yes. Will increase operating time. However, increased time will be within acceptable limits.	12E-3507B 12E-3506 Sh. 1 & 2	$\overline{\mathbf{M}}$ Z,AA	
$38 - 1$ H ₂	Steam Line Isol Valve (3-1301-1) (normal feed)	No	Yes. Valve will stop mornentarily.	Yes	No. NO and interlocked closed.	Yes. Will increase operating time. However, increased time will be within acceptable limits.	12E-3507B 12E-3506 Sh. 1 & 2	$\overline{\mathbf{M}}$ Z,AA	
$38 - 1$ H ₃	LPCI Pumps Drywell Discharge Valve 3A (3-1501-27A)	N _o	No. Note 1.	N/A	N/A	N/A	12E-3440 Sh.3 12E-3437 Sh. 1 & 2	W AD, AC	
$38 - 1$ H4	LPCI Pumps Drywell Discharge Valve 3B (3-1501-28A)	N _o	No. Note 1.	N/A	N/A	NJA	12E-3441 Sh.3 12E-3437 Sh. 1 & 2	s AD, AC	
$38 - 2$ A4	120/240V Distr Xfmr 38-2	No	Yes. Voltage will decrease temporarily.	Yes	No	N/A	12E-3675A	$\overline{\mathbf{A}}$ K	
$38-2$ B1	Condensate Transfer Jockey Pump $(3-4321)$	No	Yes. Pump will slow down momentarily,	Yes	No	N/A	12E-3373	$\overline{\mathsf{K}}$	

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Pop 7 of 15 03EXCELXLB **-U3** Table 2

TABLE 2B <u>IABLE ZB</u> <u>AFFECTS OF VOLTAGE DIP</u>

Dresden Station - Unit 2/3 (Swing Diesel)
EDG 2/3 Powering Unit 3

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D3EXCEL.XL\$ - U3 Table 2

TABLE 2B

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AFFECTS OF VOLTAGE DIP

Dresden Station - Unit **213** (Swing Diesel)

				EDG 2/3 Powering Unit 3					
Bus No.	Equipment Description/No.	Load Shed	Will the voltage dips @ 5s, 10s, & 10min. affect the equipment's operation	Will the equipment start after voltage recovery ?	Will the equipt. operate in adverse mode due to the voltage dips?	Will the time delay in operation cause any adverse affect?	Dwg. Ref.	Rev	Other Ref.
$38 - 2$ D1	Main H2 Seal Oil Pump (3-5350-MSOP)	No	Yes. Pump will slow down momentarily.	Yes	No	N/A	12E-3365	M	
$38 - 2$ D ₂	250 Volt Battery Charger #3 $(3 - 8350 - 3)$	No	Yes. Charger output will decrease momentarily.	Yes	No	N/A	12E-3675B	L	
$38 - 2$ D3	Condensate Transfer Pump 3A $(3A-4301)$	Yes	N/A	N/A	N/A	N/A	12E-3370	Q	
38-2 D4	Welder Receptacle (3-7901)	No	No. Note 1.	N/A	N/A	N/A	12E-3675B	L	
$38 - 2$ D ₅	Diesel Gen Starting Air Compressor 3A $(3-4611A)$	No	Yes. Compressor will slow down momentarily.	Yes. Will start when pressure is below 230 psi.	No	N/A	12E-3350B	AK	
$38 - 3$ A2	Diesel Circ. Water Heater 3	No	Yes. Heater output will decrease momentarily.	Yes	No	N/A	12E-3350B	AK	
$38 - 3$ A2	DG Turbo Charger Lube Oil Circulating Pump #2	No	Yes. Pump will slow down momentarily.	Yes	No	N/A	12E-3350B	AK	
$38 - 3$ A2	DG Turbo Charger Lube Oil Circulating Pump #2	No	Yes. Pump will slow down momentarily.	Yes	No	N/A	12E-3350B	AK	
$38-3$ A ₃	Turning Gear Oil Pump (3-5600-TGOP)	No	Yes. Pump will slow down momentarily.	Yes	No	N/A	12E-3362	$\overline{\mathbf{M}}$	
$38 - 3$ A4	Turbine Turning Gear (3-5601-TGM)	No	No. Not started until after the second CCSW Pump is running.	N/A	N/A	N/A	12E-3362A	\mathbf{D}	

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Page 9 of 15 D3EXCELXLS - U3 Table 2

T_{max} <u>TABLE 2B</u> AFFECTS OF VOLTAGE DIP
Dresden Station - Unit 2/3 (Swing Diesel)

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TABLE 2B <u>TABLE 2B</u> <u>AFFECTS OF VOLTAGE DIP</u>

Bus No. 2013 **Diesden Station - Unit 2**/3 **(Switch)**
The public Unit Of Literature Description

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$\frac{1}{2}$ TABLE 2B

AFFECTS OF VOLTAGE DIP
Dresden Station - Unit 2/3 (Swing Diesel)

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TABLE 2B AFFECTS OF VOLTAGE DIP

Dresden Station - Unit 2/3 (Swing Diesel) **EDG 2/3** Powering Unit **³**

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TABLE 28 AFFECTS OF VOLTAGE DIP <u>Dresden Station - Unit 213 (Sving Diesel)</u>

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hp 14 *df* **15 D3EXCEL.XLS** - U3 **Table 2**

TABLE 2B AFFECTS OF VOLTAGE DIP

TABLE 2B

Bus No. 1 Unit 2/3 (Swing Diesel)
EDG 2/3 Powering Unit 3

NC - Normally Closed

NO - Normally Open

For further explanation of this table see Flow Chart No. 2.

Note 1: These loads have power, however they do not operate.

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Revision 2

DG Auxiliaries and Other 480V Loads Starting 0 Seconds after Closing of DG Breaker

Full Load Current (FLC) form HP = (HP x 746) / (1.732 x kV x PF x eff.) FLC from $KW = KW / (1.732 \times KV \times PF \times eff.)$
FLC from $KVA = KVA / (1.732 \times KV \times eff.)$ $S_{\rm{N}}$ (SKW) $=1.72$ \pm 1.732 \pm 1.732 \pm 1.732 \pm 1.732 \pm

Starting KW (SKW) = 1.732 x kV x LRC% x FLC x SPF

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Calculation No. 9389-46-19-3 Rev. 4 Attachment J Page **J1** of $J5$

DG Auxiliaries and Other 480V Loads Starting 0 Seconds after UV Relay Resets

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Full Load Current (FLC) form $HP = (HP \times 746) / (1.732 \times$ kV x PF x eff.) **FLC** from KW **=** KW **1** (1.732 x kV x PF x eff.) **FLC** from KVA **=** KVA **/** (1.732 x kV x eff.)

Starting KW (SKW) = 1.732 x kV x LRC% x FLC x **SPF** Starting KVAR (SKVAR) **=** 1.732 x kV x LRC% x **FLC** x sin(acos(SPF)) **I** R~3

Calculation No. 9389-46-19-3 Rev. 3 Attachment J Page J2 of **J5**

DG Auxiliaries and Other 480V Loads Starting 10 Seconds after UV Relay Resets

FLC from $KW = KW$ / $(1.732 \times kV \times PF \times eff)$ FLC from KVA = $KVA / (1.732 \times kV \times eff)$

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Starting KW (SKW) **=** 1.732 x kV x LRC% x FLC x SPF Starting KVAR (SKVAR) = 1.732 x kV x LRC% x FLC x sin(acos(SPF)) **If a starting KVAR (SKVAR) = 1.732 x kV** x LRC% x FLC x sin(acos(SPF))

> Calculation No. 9389-46-19-3 Rev. 3 Attachment J Page J3 of J5

DG Auxiliaries and Other 480V Loads Starting at 10+ Minutes

Calculation No. 9389-46-19-3 Rev. 3 Attachment. Page **J4** of J5

DG Auxiliaries and Other 480V Loads Starting at **10++** Minutes

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Fuil Load Current (FLC) form $HP = (HP \times 746)$ *l* **(1.732 x kV x PF x eff.)
FLC from KW = KW / (1.732 x kV x PF x eff.) FLC** from KVA *=* KVA / (1.732 x kV x eft.)

Starting KW (SKW) = 1.732 x kV x LRC% x **FLC** x SPF Starting KVAR (SKVAR) **= 1.732** x kV x LRC% x **FLC** x sin(acos(SPF)) R3

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Calculation No. 9389-46-19-3 Rev. **3** Attachment **J** Page J5 of J5

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DRESDEN DIESEL GEN 2/3 LOAD BUS (LOOP AND LOCA CONDITION)

FIGURE 2B - **DO** AUXILIARIES AND OTHER 4kV AND 480V LOADS

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FIGURE 2B - DG AUXILIARIES AND OTHER 4kV AND 480V LOADS

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(0s) - 0 seconds after closing of **DG** Breaker

Os **-** 0 seconds after UV reset

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5s - 5 seconds after UV reset

Ios - 10 seconds after UV reset

0.-min - All loads that automatically stop before 10 minutes are shown off. 10+min - **CCSW** Pump 2A Is started.

10++min - CCSW Pump 2B is started with its auxiliaries.

10+++min. - Both CCSW Pumps are running and other loads starting after 10 minutes are shown here.

Attachment M

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DG Unit 3 Division I ETAP Output Reports - Nominal Voltage

Diesel Generator connected using nominal voltage, Time period is less than 10 minutes into the event.

LOAD FLOW REPORT

^{*} Indicates a voltage regulated bus (voltage controlled or swing type machine connected to it)

 $\#$ Indicates a bus with a load mismatch of more than 0.1 MVA $_{\odot}$

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Diesel Generator connected using nominal voltage, Time period is less than **10** minutes into the event.

LOAD FLOW REPORT

6 Indicates a voltage regulated bus (voltage controlled or swing type machine connected to it)

4. Indicates a bus with a load mismatch ofmore than **0.** 1 MVA

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Diesel Generator connected using nominal voltage, Time period is less than 10 minutes into the event.

LOAD FLOW REPORT

* Indicates a voltage regulated bus (voltage controlled or swing type machine connected to it)

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Indicates a bus with a load mismautch of more than **0.1** MVA

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Diesel Generaitor connected using nominal voltage. Time period is less thtan **10** minutes into the event.

Bus Voltage Generation Load ID kV kV Ang. MW Mvar MW **Mvar** ID Load Flow **XFMR** MW Mvsr Amp **%** PF % Tap 4KV SWGR 33-1 '4KV SWING BUS 40 38-1 ALTF2-1301-1&4 125V DC CHGR 3A 250V DC CHGR 3 480V MCC 38-1 480V MCC 38-2 480V MCC 38-3 480V MCC 38-4 480V MCC 38-7 480V **MCC 39-7** 480V SWGR 38 BKR 38-4A BIFURC 4.160 4.155 0.0 4.160 4.160 0.0 0.480 0.472 **.1.9** 0.480 0.462 -2.0 0.480 0.462 -2.0 0.480 0.472 -1.9 0.480 0.466 -2.3 0.480 0.472 **-1.8** 0.480 0.476 -1.9 0.480 0.474 -2.8 0.480 0,474 -1.8 0.480 0.476 -1.9 0.480 0.476 -1.9 0 0 1.741 0.795 HIGH SIDE OF XFMR 38 4KV SWING BUS 40 2.206 1.179 0 0 4KV SWGR 33-1 0 0 0 0 480V MCC 38-1 0 0 0.034 0.028 480V **MCC** 38-2 0 0 0.066 0.054 480V MCC 38-2 0 0 0.099 0.054 38-1 ALTF2-1301-1&4 BKR 38-4A BIFURC 0 0 0.104 0.072 250V DC CHGR **3 125V** DC CHGR 3A 480V SWOR 38 0 0 0.111 0.117 480V SWGR **38** 0 0 *0.005* 0.003 BKR 38-4A BIFURC 0 0 0.021 0.013 480V SWOR 38 480V MCC 39-7 0 0 0.013 0.008 480V MCC **38-7** 0 0 0 0 480V MCC 38-7 BKR 38-4A'BIFURC 480V MCC 38-3 480V **MCC** 38-2 HIGH SIDE OF XFMR **38** 0 0 0 0 480V MCC 38-4 480V SWGR 38 480V MCC 38-1 0 0 0 0 4KV SWGR 33-1 480V SWGR 38 0.463 0.381 -2.204 -1.176 2.206 1.179 0.000 **3.0w** -0.034 -0.028 -0.066 -0.054 0.000 0.000 **-0.099** -0.054 0.067 0.054 0.034 0.028 -0.205 -0.154 .0.111 -0.117 -0.005 -0.003 -0.035 -0.021 0.013 0.008 -0.013 -0.008 0.035 •0.021 *0.105* 0.057 0.112 0118 0.209 0.158 -0.460 -0.355 0.005 0.003 *-0.105* -0.057 0.100 0.054 -0.463 -0.381 0.463 0.381 83.3 77.2 347.1 88.2 347.1 88.2 0.0 0.0 55.0 77.4 106.3 77.7 0.0 0.0 137.3 87.9 106.3 77.9 55.0 77.7 317.5 **80.0** 197.1 69.0 7.1 **85.2** 49.4 **85.3** 19.3 85.1 19.3 85.1 49.4 85.3 144.5 87.8 197.1. 69.0 317.5 79.6 704.1 79.2 7.1 85.2 144.5 87.8 137.3 87.9 83.3 77.2 83.3 77.2 *-2.500* HIGH SIDE OF XFMR 38 4,160 4.154 0,0

LOAD FLOW REPORT

***** Indicates a voltage regulated bus **(** voltage controlled or swing type machine connected to it)

Indicates a bus with a load mismatch of more than 0, **1** MVA

Diesel Generator connected using nominal voltage, Time period is less than **10** minutes into the event,

LOAD FLOW REPORT

Indicates a voltage regulated bus (voltage controlled or swing typc machine connected to it)

Indicates a bus with a load mismatch of more than 0. **1** MVA

Diesel Generator connected using nominal voltage. Time period is **10** min or greater into the event, **I** CCSW pump.

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LOAD FLOW REPORT

* Indicates a voltage regulated bus (voltage controlled or swing type machine connected **1o** it)

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;s indicates a bus with a load *mismatch* of mame than **0.1,** MVA

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Diesel Generator connected using nominal voltage, Time period is 10 min or greater into the event, 2 CCSW pumps.

LOAD FLOW REPORT

I Indicazes **a** voltage regufalcd bus (vollage controlled or swing type machine connected to **if)**

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f Indicatcs a bus siih a load mismatch of more than 0. **1** MVA

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Diesel Generator connected using nominal voltage, Time period is 10 min or greater into the event, 2 CCSW pumps.

LOAD FLOW REPORT

***** Indicates a voltage regulared bus **(** volhage controlled or swing type machine connected to it)

4 Indicates a bus wiih a load mismatch of more than **0.1** MVA

