



Treatment of Common-Cause Failures in SPAR Models

D. Rasmuson and N. Siu
Office of Nuclear Regulatory Research
U.S. Nuclear Regulatory Commission

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Outline of Presentation

- CCF modeling
 - Approach
 - Implementation
- CCF data
- ICDE observations

Dependent Failures in PSA

- Mechanistic modeling
 - Functional requirement dependencies (e.g., sequence-dependent success criteria)
 - Functional input dependencies (e.g., support system dependencies)
 - Cascade failures (e.g., pump “dead head”)
 - Physical/environmental (e.g., fires, external events)
 - Human interactions (e.g., maintenance errors)
- Parametric modeling \approx Common Cause Failure (CCF) modeling
 - Beta factor (c. 1975)
 - Multiple Greek Letter (MGL) (c. 1983)
 - Alpha factor (c. 1987)

CCF in Standardized Plant Analysis Risk (SPAR) Models

- Basic events represent CCFs
- Quantification uses parameters Q_k (Basic Parameter Model)
 - $Q_k \equiv$ probability of failure of exactly k components due to common cause
- Q_k estimated using α -factor re-parameterization
- Example: 2/3 system
 - CCF event probability = $3Q_2 + Q_3$
 - $Q_2 = \frac{\alpha_2}{\alpha_1 + 2\alpha_2 + 3\alpha_3} Q_c$ $Q_3 = \frac{3\alpha_3}{\alpha_1 + 2\alpha_2 + 3\alpha_3} Q_c$
 - Maximum likelihood estimators: $\hat{\alpha}_2 = \frac{n_2}{n_1 + n_2 + n_3}$ $\hat{\alpha}_3 = \frac{n_3}{n_1 + n_2 + n_3}$
- Assumptions:
 - Failure events represented by Q_k are mutually exclusive
 - Q_k is constant (symmetry)
 - Component failure events are statistically independent
 - Total component failure probability (Q_c) is constant

Relationship Between α -factor and MGL (3 component example)

- CCF probability
 - $Q_{CCF} = \frac{3}{2}\beta(1 - \gamma)Q_c + \beta\gamma Q_c$
- Relationship with α -factors

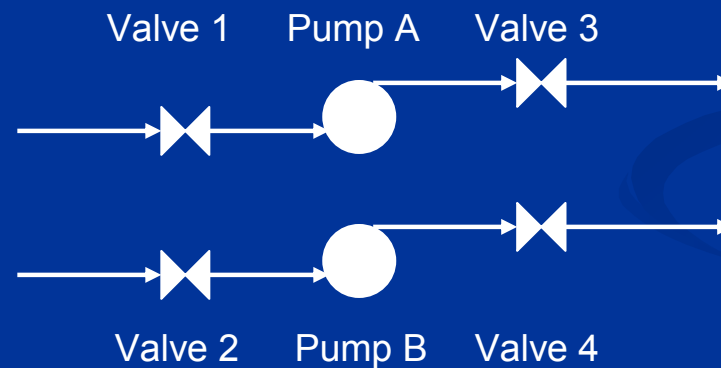
$$\beta = \frac{2\alpha_2 + 3\alpha_3}{\alpha_1 + 2\alpha_2 + 3\alpha_3} \quad \gamma = \frac{3\alpha_3}{2\alpha_2 + 3\alpha_3}$$

- Joint distribution for MGL parameters can be derived from joint distribution for α -factors
 - MGL parameters are correlated
 - Rigorous estimation requires numerical analysis

Common-Cause Component Groups - 1

- CCCG \equiv A group of components, usually similar in design, mission, maintenance, environment, etc., that are considered to have a high potential of failing due to the same cause or causes

- Example:



- CCCG 1: {Pump A, Pump B}
- CCCG 2: {Valve 1, Valve 2, Valve 3, Valve 4}

Common-Cause Component Groups - 2

- In principle, CCCGs can be broad enough to model CCFs involving:
 - Large numbers of components
 - Similar components used by different systems
 - Similar components used by different units
- Current SPAR or licensee models provide some level of treatment
 - High-redundancy situations (e.g., SRVs)
 - Cross-systems CCFs (e.g., HPCI/RCIC pumps)
 - Shared component/cross-unit CCFs (e.g., EPS, SWS)

CCF Data: Key Challenge and Approach

Plant-specific data for CCF events are more sparse than data for individual component failures

- ⇒ Use data from other plants; “impact vectors” quantify uncertainty in applicability
 - ⇒ Adjustments (“mapping”) for differences in size of exposed population
 - ⇒ Adjustments to reflect uncertainties in applicability of observed event due to:
 - degree of observed degradation
 - degree to which failure cause is shared
 - Degree to which failures are close in time

Impact Vector Example (group size = 3)

- If, for a given event in the database, it is not clear whether 2 or 3 components were affected by a shared cause, the two possible impact vectors for Hypotheses A and B are:

1 in this position indicates failure of 2 components

$$I_A = [0, 0, 1, 0] \text{ and } I_B = [0, 0, 0, 1]$$

Indicates failure of 3 components

- If the analyst believes that Hypothesis A is true with probability of p_A , then Hypothesis B is true with probability $1-p_A$, and the average impact vector is

$$p_A \times I_A + (1 - p_A) \times I_B = [0, 0, p_A, 1-p_A]$$

- Bayesian methods can be used to estimate α -factors

Quantifying Impact Vectors: Example (group size = 2)

■ Notation

- P_1 : degradation value for component 1
- P_2 : degradation value for component 2
- t : value of the timing factor ($0 \leq t \leq 1$)
- c : value of the shared cause factor ($0 \leq c \leq 1$)

■ Assignment of impact vector values

$$I = [F_0, F_1, F_2]$$

where

$$F_0 = (1-P_1)(1-P_2)$$

$$F_1 = [P_1(1-P_2)+P_2(1-P_1)] + (1-ct)(P_1+P_2)$$

$$F_2 = ct P_1 P_2$$

Guidance for Impact Factors

- Component Degradation Value (P_i)
 - $P = 0$ if component is working
 - $P = 0.1$ if component is slightly degraded
 - $P = 0.5$ if component is degraded
 - $P = 1.0$ if component is failed

- Timing Factor (t)
 - $t = 0.0$ if times are really different
 - $t = 0.1$ if times are quite different
 - $t = 0.5$ if times are about the same
 - $t = 1.0$ if times are the same

- Shared Cause Factor (c)
 - $c = 0$ if causes are different
 - $c = 0.1$ if causes might be the same
 - $c = 0.5$ if similar cause
 - $c = 1.0$ if same cause

CCF Database

- Information obtained from LERs, NPRDS, and EPIX
- Data collection period from 1980 – 2003
- Loading data for 2004 and 2005
- Data collected by component type and system
- Database contains ~1700 CCF events of which 224 events are complete CCF events

CCF Event Information

■ Qualitative Information

- Plant name and event date
- System and component type
- Cause of failure (proximate cause)
- Coupling factor
- Event narrative

■ Quantitative Information

- Number of exposed components
- Degree of degradation or failure of each component (component degradation value)
- Timing among failures or degradations (timing factor)
- A measure of the shared cause among the components (shared cause factor)

CCF Systems and Components

SYSTEMS

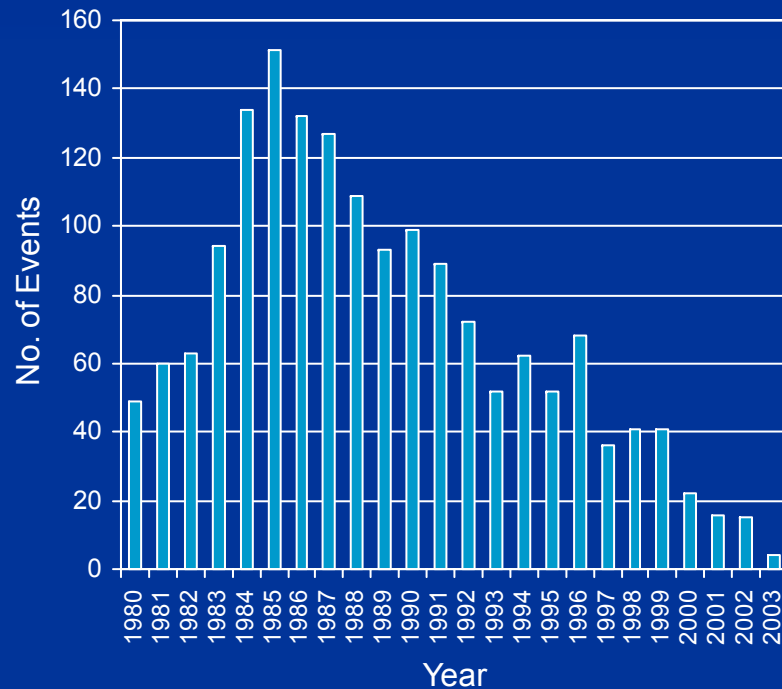
- DC Power
- AC Emergency Power
- Containment Spray
- Residual Heat Removal
- Emergency Power
- Auxiliary Feedwater
- Service Water
- PWR High Pressure Safety Injection
- PWR Low Pressure Safety Injection
- BWR Low Pressure Coolant Injection
- BWR High Pressure Coolant Injection
- BWR Reactor Core Isolation Cooling
- Reactor Protection
- Shutdown Cooling
- Standby Liquid Control
- Main Steam
- Low Pressure Core Spray
- Isolation Condenser
- Reactor Coolant
- Component Cooling Water

COMPONENTS

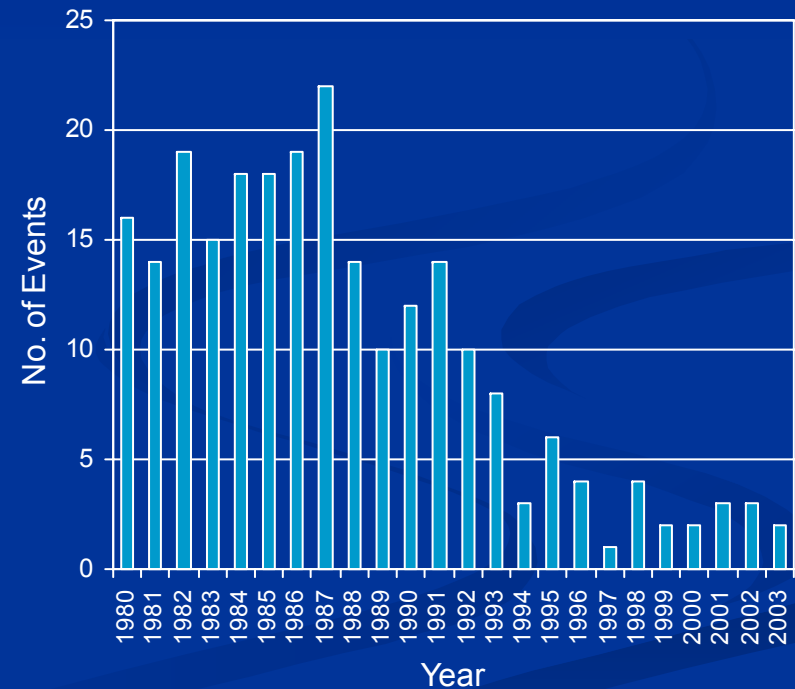
- Batteries
- Battery Chargers
- Circuit Breakers
- Reactor Trip Breakers
- Emergency Diesel Generators
- Heat Exchangers
- Strainers
- Motor-Driven Pumps
- Turbine-Driven Pumps
- Motor-Operated Valves
- Air-Operated Valves
- Check Valves
- Safety and Relief Valves
- Main Steam Isolation Valves
- Relays
- Logic Modules
- Control Rod Drive Assemblies
- Detectors
- Transmitters

USA CCF Event Trends

All Common Cause-Failure Events



Complete Common-Cause Failure Events



ICDE Observations

- NRC has participated in all component data exchanges
- Information collected in ICDE Project can be used in CCF quantification methods used in US
- NRC uses the ICDE CCF data for qualitative information
- NRC issued a report in 2006 summarizing insights from ICDE data for pumps, MOVs, EDGs, and breakers for use in the inspection program

Selected References

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- A. Mosleh, et al, *Procedures for Analysis of Common-Cause Failures in Safety Analysis*, NUREG/CR-5801, April 1993
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- F.M. Marshall, A. Mosleh, D.M. Rasmuson, *Common-Cause Failure Database and Analysis System*, Volumes 1-4, NUREG/CR-6268, June 1998
- F.M. Marshall, D.M. Rasmuson, A. Mosleh, *Common-Cause Failure Parameter Estimations*, NUREG/CR-5497, October 1998.
- *International Common-Cause Failure Data Exchange General Coding Guidelines*, NEA/CSNI (2004)4, January 2004
- A. Mosleh and N. Siu, “A multi-parameter common cause failure model,” *Proceedings of 9th International Conference on Structural Mechanics in Reactor Technology (SMiRT-9)*, 1987.
- Updated Common-Cause Failure Parameter Estimates are available at <http://nrcoe.inel.gov/results/> under Common-Cause Failures