CHAPTER 6 Response of Soil and Rock to Dynamic and Static Loading

The responses of soil and rock at the EGC ESP Site to dynamic and static loading were evaluated by conducting updated site-specific liquefaction potential evaluations and by drawing upon existing information in the CPS USAR for static loading conditions. Procedures for evaluating liquefaction potential have changed since the CPS Site investigation was conducted in the mid 1970s. In view of these changes, a new empirical method for evaluating liquefaction potential was used rather than drawing a comparison between conclusions reached for the CPS Site and what could occur at the EGC ESP Site because of similarities in site conditions. On the other hand, the methodologies that were used to evaluate site response to static loading (i.e., bearing capacity, settlement, and lateral earth pressures) have not changed since the CPS Site investigation and, therefore, information presented in the CPS USAR has been used to address these conditions. The foundation performance for the CPS Facilities has been good over the 20 years of operation, indicating that soil conditions are suitable for siting similar facilities in the area.

6.1 Liquefaction Potential

Liquefaction potential was evaluated for the EGC ESP Site based on the results of the geotechnical investigation conducted for the EGC ESP Site. The liquefaction evaluation was performed by the procedure recommended in Youd et al. (2001). This reference is a slightly updated version of the information presented in *Proceedings of the National Center for Earthquake Engineering Research (NCEER) Workshop on Evaluation of Liquefaction Resistance of Soils* (NCEER, 1997) and referenced in Draft Regulatory Guide 1105 (USNRC, 2001a).

6.1.1 Method of Evaluation

The liquefaction evaluation method calculates a FOS based on the expected soil shearing resistance and the expected maximum seismically-induced shearing stresses in a soil layer. Soil shearing resistance is quantified by the cyclic resistance ratio (CRR). Correlations have been developed to estimate the CRR from the SPT blowcount, with modifications for depth and SPT driving conditions (for example, hammer energy, driving efficiency, and soil sampler type). The expected shearing stresses induced by seismic loading are quantified by the cyclic stress ratio (CSR), which is the ratio of expected cyclic shearing stress to existing effective overburden. The CSR is proportional to the peak ground acceleration (pga) for the specified seismic loading. A magnitude scaling factor (MSF) is assigned based on the specified earthquake moment magnitude (M) expected to generate the specified pga. The FOS against liquefaction is calculated as:

$$
FOS = \frac{CRR}{CSR}(MSF)
$$
 Equation 6.1-1

The MSF is smaller for larger M earthquakes (that is, reduces the FOS) to account for the longer duration of shaking and lower frequency vibrations typical of the larger events. The FOS against liquefaction is calculated for soil conditions at regular depth intervals to obtain a profile of FOS with depth.

The liquefaction procedure described by Yound et al. (2001) and presented in Draft Regulatory Guide 1105 (USNRC, 2001b) is appropriate for soils above a depth of approximately 75 ft. Below this depth, the potential for liquefaction is generally considered to be very low, except for very loose cohesionless soils. In addition, soils that are cohesive (that is, with USCS classification of CL or CH) or are located above the water table are not considered to be liquefiable, even at low calculated FOS. Silty soils (ML or MH) are not considered of concern for liquefaction unless they exhibit a certain combination of plasticity, in situ water content, and gradation (known as the Chinese criteria), even if the FOS is less than 1.0.

Subsurface conditions were modeled for each of the four EGC ESP Site borehole locations (that is, boreholes B-1 through B-4). The upper 75 ft of the subsurface was modeled in 5-ft depth intervals corresponding to the SPT blowcount and sample locations. Modeled information consists of the USCS soil classification, in situ unit weight, SPT blowcount, and estimated fines content (i.e., P200 fraction) for each depth interval. The SPT hammer efficiency was quantified by testing performed by GRL on August 2, 2002 (as described in Section 3.1.2.2). Depth to groundwater was modeled to be 6 ft bgs, based on nearby shallow piezometer results. This depth to groundwater represents a perched groundwater table at the top of the Wisconsinan till. The piezometric head drops with depth beneath the top of the Wisconsinan till, approaching nearly 30 ft bgs in the Illinoian till as indicated by piezometer results at B-1 Piezo. In most situations the degree of saturation associated with a perched condition is less than 100 percent, even when the water table is high. As the degree of saturation decreases, the resistance of a soil to liquefaction increases. This condition suggests that the static pore water pressures calculated in the liquefaction analyses, which are based on the modeled groundwater depth of 6 ft bgs, are therefore very conservative.

Liquefaction potential was evaluated for a peak ground acceleration of 0.3g over a range of earthquake magnitudes that could occur at the EGC ESP site. The pga value of 0.3g exceeds the design basis ground motion of 0.26g and therefore is conservative relative to the pga site characteristic. The pga of 0.3g was selected to be consistent with the value set forth in Regulatory Guide 1.60, which represented the peak acceptable value for the plants that form the basis of the Plant Parameters Envelope (see Section 1.4). It was reasoned that if the liquefaction potential were low at 0.3g, an additional margin of safety would exist for the site.

The maximum design earthquake **M** was derived by deaggregating the results from the probabilistic seismic hazard assessment (PSHA) for the EGC ESP Site. This information is summarized in Section 2.5 of the SSAR and discussed in detail in Appendix B to the SSAR. The three magnitudes used in the liquefaction analyses were as follows:

 $M = 5.5$ which is approximately equal to the mean magnitude assocated with a local source mechanism.

- **M = 6.5** which is approximately equal to the mean magnitude assocated with the Wabash source mechanism.
- **M = 8** which is an upper bound magnitude that might be assocated with a New Madrid source machanism.

Additional combinations of **M** and pga were also considered to illustrate the sensitivity of the calculated FOS to each parameter. One set of calculations was made for conditions at borehole B-1 by holding **M** constant at 6.5, with pga values of 0.25g, 0.30g, and 0.35g. Another set was made for constant pga of 0.25g, with **M** values of 6.75, 7.25, and 7.75.

Section 3.2 of Draft Regulatory Guide DG-1105 provides guidance on interpretation of liquefaction FOS for nuclear power plant sites. According to the guidance, soils with FOS less than 1.1 should be considered liquefiable at the specified earthquake loading. Soils with FOS greater than 1.4 are not considered to develop significant pore pressures during seismic loading. Although soils with FOS between 1.1 and 1.4 are not considered liquefiable, the effects of increased pore pressures on soil shear strength must be considered during design.

6.1.2 Results of Liquefaction Evaluations

Tables 6-1 through 6-4 and Figures 6-1 through 6-4 summarize the results of the liquefaction calculations for the range of earthquake loading and subsurface conditions modeled at boreholes B-1 through B-4, respectively. The FOS was calculated for each soil layer and for each of the modeled pga and **M** combinations. For soils that classify as silt (ML) via the USCS, but which pass the Chinese criteria, low calculated FOS does not indicate liquefaction potential because the soils are sufficiently cohesive. However, non-cohesive soils (silts and sands) with calculated FOS less than 1.1 are present at the four boreholes under a worsecase combination of pga and earthquake magnitude (that is, 0.3g for a **M** = 8 event). These soils are, therefore, considered potentially liquefiable. The results also indicate that additional soil layers from some boreholes have a FOS between 1.1 and 1.4, which indicates that pore pressures may generate during the maximum earthquake event. The potential for decrease effective stress in these soils will be considered for foundation design during the COL stage, although liquefaction is not anticipated to occur in these soils.

The potentially liquefiable non-cohesive soils at the EGC ESP Site (FOS less than 1.1) are all present within 60 ft of the ground surface. At each location, the granular soil is present in thin and possibly discontinuous zones within the Wisconsinan till or near the top of the Interglacial zone. Given the potential effects of founding structures on liquefiable soil deposits, which include loss in bearing support or seismic-related settlements, Category I nuclear facilities are not founded on liquefiable material. For the CPS Site, the upper 55 ft of soil were excavated. Although the material was removed primarily to limit settlements, it also provided a more liquefaction-resistant foundation. If a similar approach is taken for the EGC ESP Site, the liquefaction potential in the upper 60 ft can be avoided through selection and compaction of gravel backfill. Alternatively, some type of ground improvemant could be used to mitigate the potential for liquefaction. With several approaches available to address the liquefaction potential for the EGC ESP Site, this site characteristic is not be considered a constraining issue for siting.

Table 6-5 and Figures 6-5 and 6-6 illustrate the sensitivity of the calculated FOS to changes in **M** and pga. As shown, a reduction in pga from 0.35 to 0.25 increases the FOS by

approximately 50 percent for each depth interval. A pga of 0.25 is essentially the same as the design basis earthquake, indicating that there is considerable reserve in terms of liquefaction resistance relative to the value or 0.3g used in the liquefaction evaluation. This observation suggests that the maximum excavation depth can be limited to 60 ft. Likewise, a unit reduction of earthquake magnitude (7.75 to 6.75) increases the FOS by approximately 50 percent. The smaller magnitude earthquake (M = 535 to 635 are more likely than the M> 7.75 event) are more likely, and these earthquakes have a lower potential for causing liquefaction. These results further support limiting the depth of excavation to 60 ft.

Based on the above information, the minimum site characteristic for liquefaction is absent below a depth of 60 ft bgs at the EGC ESP Site. Other seismic effects on soil pore water pressures and shear strengths at depths below 60 ft bgs can be managed with standard geotechnical practices, and should be considered in the design during the COL stage. However, these effects do not alter the suitability of the EGC ESP Site for construction of a reactor plant design.

6.2 Bearing Capacity

Ultimate bearing capacities for the CPS Facility were computed with conventional methods assuming a local shear failure condition, as described in Section 2.5.4.10.2 of the CPS USAR. The resulting ultimate bearing capacities for the Category I structures (except for the UHS) range from 39.9 to 60.6 tsf (79.8 to 121.2 kips per square foot [ksf]), as listed in Table 2.5-63 of the CPS USAR. A summary of structure foundation performance parameters for the CPS Facility structures is also provided in Table 6-6. Net foundation pressures for the Category I structures at the CPS Site are less than 2.5 tsf, resulting in FOS in bearing of greater than 20 for all structures except the containment structure, which has a FOS in bearing of 18.8.

Given the similarity in soil strengths, the ultimate bearing capacities of soils at the EGC ESP Site should be similar to values determined for the CPS Category I facilities, as long as the structures are of similar dimensions and are founded at similar or deeper depths. The foundation elevations for the CPS Facility structures range from 692 to 702 ft, except for the circulating water screen house and UHS outlet structure (located adjacent to Clinton Lake with lower foundation elevations), and the service building (not a Seismic Category I structure). Most of the foundations for the CPS Facilities were constructed over compacted select granular fill, and the depth of excavation for placement of this fill was approximately 55 ft bgs. The EGC ESP Site structure foundations may be constructed in a similar manner. Based on the above information, if foundation depths at the EGC ESP Site are similar or deeper than those at the CPS Site, the EGC ESP Site characteristic foundation soil bearing capacity will be significantly greater than 25 tsf.

Static moduli of subgrade reaction values at the CPS Site are also provided in the CPS USAR. The values range from 25 to 300 pounds per cubic in. As presented previously, soil classifications, strengths, and densities are consistent between the EGC ESP and CPS Sites. Based on this information, the site characteristic static moduli of subgrade reaction at the EGC ESP Site are similar to those at the CPS Site.

6.3 Settlement Potential

Predicted and actual foundation settlements for the CPS Facility structures are presented in Section 2.5.4.10.3 of the CPS USAR. Settlement criteria at the CPS Facility were achieved by excavating a 20-ft zone beneath the foundation level (roughly 800 ft by 800 ft in plan view) and replacing the excavated material with a compacted granular backfill. The soils below the excavated material, Illinoian and pre-Illinoian tills, are relatively incompressible as a result of overconsolidation caused by past glaciations. Some isolated pockets of sand at the base of the excavation that could not be compacted to meet density requirements were removed and replaced with a flyash backfill, as summarized in Section 2.6.3 of this Geotechnical Report.

Settlement was originally estimated for the CPS Facility to range from 1 to 2 in based on bearing pressures of 1 tsf to 2.5 tsf. These bearing pressures represented the net loads caused by the different Category I structures. Final settlements measured after construction were typically less than 0.5 in, suggesting that conditions were better than had been estimated for the CPS Site.

Results of the laboratory testing for the EGC ESP Site indicate that soil conditions are similar to those at the CPS Site, suggesting that settlements under the imposed bearing pressures will be small. As summarized in Section 5.2.3.1, values of C_c and C_r are consistent between the EGC ESP and CPS Sites. Values of P_c' from the test data for the EGC ESP Site are slightly lower than values from the CPS Site, but this would have no effect on settlements between the sites for foundation bearing pressures less than 5 tsf.

During the COL stage, facility-specific settlement analyses will need to be conducted to confirm that the structure foundation settlements will be acceptable. These analyses will consider the net bearing pressures applied by the structure, the foundation size, and the depth of the foundation. If the particular structure is located above the Illinoian till, it may be necessary to excavate to the top of the till and recompact select granular fill in the excavation to limit settlement, similar to what was done for the CPS Category I structures. Generally, the rate of settlement should be relatively fast because of the overconsolidated state of the till soils. These concerns will be addressed in the COL stage, but do not affect the suitability of the EGC ESP Site for construction of a reactor plant design.

6.4 Lateral Earth Pressures

Lateral earth pressures were determined for the CPS Facility structures for both static and seismic loading conditions, as summarized in Section 2.5.4.10.4 of the CPS USAR. At-rest pressures were used in the calculations because of the rigid behavior of the Category I walls. A static coefficient of lateral earth pressure of 0.47 was used for the analyses of the CPS Facility structures, corresponding to a typical friction angle of 32 degrees for the finegrained soils at the excavation sidewalls. This was considered conservative, because compacted sand was actually placed within 40 ft of the foundation walls, which has a higher friction angle (38 degrees) and therefore lower static coefficient of lateral earth pressure (0.38). Dynamic water and soil pressure were also evaluated to account for seismic loading conditions.

The lateral earth pressures for the EGC ESP Site will depend on the selected reactor plant design. For those systems that are similar to the CPS Category I structures, the earth pressures will depend on the granular material used for backfill and the required compaction characteristics. The earth pressures for these structures can be accommodated during design of the walls for the facilities.

Some of the new reactor plant designs could involve embedment depths of over 100 ft. The soils at these depths consist of hard silts and clays. Earth pressures associated with these designs will have to be evaluated on the basis of the planned construction method. Special soil-structure interaction studies could also be required to evaluate the seismic performance of these deeply embedded structures. These concerns will be addressed in the COL stage, but do not affect the suitability of the EGC ESP Site for construction of a reactor plant design.

6.5 Other Considerations

 Other geotechnical design issues have been identified which will be considered upon selection of the reactor plant design. These other considerations include design of slopes for the intake structure, performance of the UHS for the updated seismic hazard, and soilstructure interaction studies for the Category I structures. These concerns will be addressed in the design phase, but do not represent a constraining issue with regard to acceptability of the site.

A review was also performed to determine the location of dams occurring upstream and downstream of the EGC ESP Site. Results of this review concluded that there are no dams or other water retaining structures upstream of the facility that could result in inundation of the CPS or EGC ESP Sites if the water retaining structures were to fail for whatever reason. The main dam for the Clinton Lake is located approximately 3.5-mi downstream of the EGC ESP Site. It will not be modified as a result of EGC ESP Site development. The original design basis for the dam considered a much lower seismic ground motion than the safe shutdown earthquake (SSE), but is not relied upon for the safety of the CPS Facility. Only the CPS UHS was designed for the SSE. As noted previously, it will be necessary to confirm during the COL stage that the CPS UHS is capable of withstanding any higher levels of seismic-induced ground motions, if the selected reactor plant design must rely on the CPS UHS for emergency shutdown.

Another consideration will be dewatering of excavations during construction. The amount of dewatering will depend on the foundation elevation of the reactor plant design. During construction of the CPS Facilities, excavations extended 55 ft bgs. As reported in Section 2.5.4.5.1.3 of the CPS USAR, seepage into the foundation was very low in the natural clayey soils. However, more pervious sand layers and seams did contribute to the rate of seepage. According to the CPS USAR, dewatering was accomplished by a network of perforate metal pipe drains and ditches that collected the seepage at the periphery of the excavation. Similar procedures will likely be successful at the EGC ESP Site if the excavation elevations are similar. Construction dewatering for a reactor plant design that extends deeper than 55 ft will have to be evaluated during the COL stage if such a system is selected. Generally, dewatering should not be a significant construction issue due to the relatively low permeability of the soils at the EGC ESP Site.

Potential for seismically induced water waves (seiches) is considered in Sections 2.4.4 and 2.4.5 of the SSAR. Potential for effects of non-tectonic deformations is discussed in Section 2.5 of the SSAR. Based on the cited references, neither seiches nor non-tectonic deformations appear to be an issue at the EGC ESP Site.

CHAPTER 6Tables

TABLE 6-1

Summary of Liquefaction Calculations - Expected Maximum Earthquakes - Borehole B-1 **Design Parameters**

Summary of Liquefaction Calculations - Expected Maximum Earthquakes - Borehole B-2

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Summary of Liquefaction Calculations - Expected Maximum Earthquakes - Borehole B-3

Note: Soils that meet the Chinese Criteria are not considered liquefiable.

Summary of Liquefaction Calculations - Expected Maximum Earthquakes - Borehole B-4

Summary of Liquefaction Calculations - FOS Variation w/ M and PGA - Borehole B-1

TABLE 6-5 (CONTINUED)

Summary of Liquefaction Calculations - FOS Variation w/ M and PGA - Borehole B-1

ABLE	1
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Summary of CPS Facility Structure Foundation Performance Parameters

Notes:
a. Foundation elevations listed are for safety related structures in the upland area of the CPS Site. ^{a.} Foundation elevations listed are for safety related structures in the upland area of the CPS Site.
^{b.} Negative sign indicates swell

^{c.} Corresponds to at-rest conditions in the fine-grained excavation sidewall soils (friction angle of 32 degrees).

CHAPTER 7 Conclusions Relative to Application for the EGC ESP

The geotechnical work described in this Geotechnical Report was performed to evaluate the suitability of the EGC ESP Site for the development of a new reactor plant design at some time in the future. The suitability of the site was evaluated on the basis of (1) whether any unacceptable geologic hazards exist and (2) whether geotechnical conditions will provide acceptable foundation support for a range of possible reactor plant designs. The information presented in this Geotechnical Report documents information that was used to decide on the suitability of the EGC ESP Site and serves as a basis for Section 2.5 of the SSAR and Section 3.6 of the ER for the EGC ESP Site. As discussed in the following two sections of this Geotechnical Report, the EGC ESP Site is considered suitable for future development of a reactor plant design from the standpoints of geology and geotechnical site characteristics. However, additional geotechnical work will be required at the COL stage to address reactor plant design-specific geotechnical design criteria.

7.1 Information for Early Site Permit Submittal

Geologic and geotechnical conditions at the EGC ESP Site are consistent with conditions at the CPS Site. The regional and local geologic conditions at the CPS and EGC ESP Sites are similar. No new geologic hazards were identified from EGC ESP Site investigation and reviews of the current literature. Comparisons of the soil layers and properties (e.g., soil classifications, strengths, compressibility, seismic velocities) are consistent between the CPS and EGC ESP Sites. The extensive database for the CPS Site, as summarized in the CPS USAR, and field explorations, laboratory testing, and engineering evaluations for the EGC ESP Site indicate the EGC ESP Site is suitable for development of a new reactor plant design. No new geologic hazards or geotechnical conditions were identified that could preclude successful construction and operation of a new reactor plant design within the EGC ESP Site footprint.

The minimum geotechnical site characteristics for the EGC ESP Site have been evaluated, and include the following:

- Allowable net bearing capacities exceed 25 tsf;
- Liquefaction potential is absent if foundations extend to a depth of 60 ft bgs or greater, or if the material above 60 ft bgs is removed and replaced with compacted gravel fill or is improved; and
- Shear wave velocities below a depth of 50 ft bgs exceed 1,000 fps.

7.2 Information Required for Final Design

The geotechnical work completed for the EGC ESP Site is not considered sufficient for final design of the selected reactor plant design. Additional field explorations, laboratory testing, and engineering studies will be required. The extent of any additional explorations, laboratory testing, and engineering studies, if any are required, cannot be determined at this time. They will depend on the footprint and depth of the structures, the net weight, and the sensitivity of their performance to variations in soil properties. Regulatory Guide 1.132 will be utilized, together with foundation design requirements, to determine the locations, depths, and types of additional explorations. Nothing was identified during the geotechnical work described in this Geotechnical Report that would make any of these future investigations or studies particularly risky or difficult.

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Attachment A-1 Borehole Logs and Rock Coring Logs

BORING NUMBER: B-1

Sheet: 1 of 4

SOIL BORING LOG

PROJECT: Exelon - CPS-ESP Field Investigation

LOCATION: B-1; Southwest corner of ESP footprint

ELEVATION: 738.6

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DRILLING CONTRACTOR: <code>TSC</code>

DRILLING METHOD AND EQUIPMENT: 6-Inch Rotary, Bio-Bore Drilling Mud

17.4' bgs on 8/28/2002 **17.4' START:** 7/22/2002 **FINISH:** 7/23/2002 **LOGGER:** MDG

BORING NUMBER: _{B-1}

Sheet: 2 of 4

SOIL BORING LOG

PROJECT: Exelon - CPS-ESP Field Investigation

DRILLING METHOD AND EQUIPMENT: 6-Inch Rotary, Bio-Bore Drilling Mud

LOCATION: B-1; Southwest corner of ESP footprint

ELEVATION: 738.6

DRILLING CONTRACTOR: _{TSC}

17.4' bgs on 8/28/2002 7/22/2002 7/23/2002 MDG **WATER LEVELS: START: FINISH: LOGGER:**

BORING NUMBER: B-1

Sheet: 3 of 4

SOIL BORING LOG

PROJECT: Exelon - CPS-ESP Field Investigation

LOCATION: B-1; Southwest corner of ESP footprint

ELEVATION: 738.6

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DRILLING CONTRACTOR: TSC

DRILLING METHOD AND EQUIPMENT: 6-Inch Rotary, Bio-Bore Drilling Mud

17.4' bgs on 8/28/2002 **17.4' START:** 7/22/2002 **FINISH:** 7/23/2002 **LOGGER:** MDG

BORING NUMBER: B-1

Sheet: 4 of 4

SOIL BORING LOG

PROJECT: Exelon - CPS-ESP Field Investigation

LOCATION: B-1; Southwest corner of ESP footprint

ELEVATION: 738.6

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DRILLING CONTRACTOR: TSC

DRILLING METHOD AND EQUIPMENT: 6-Inch Rotary, Bio-Bore Drilling Mud

WATER LEVELS: 17.4' bgs on 8/28/2002 **18 COVER: 17/22/2002 18/23/2002** MOGGER: MDG

BORING NUMBER: B-2

Sheet: 1 of 10

SOIL BORING LOG

PROJECT: Exelon - CPS-ESP Field Investigation

LOCATION: B-2; West Side of ESP Footprint

ELEVATION: 737.8 Feet MSL

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DRILLING CONTRACTOR: TSC

DRILLING METHOD AND EQUIPMENT: 6-Inch Rotary, Bentonite Drilling Mud

3.7' bgs on 8/28/2002 8/2/2002 8/7/2002 MDG **WATER LEVELS: START: FINISH: LOGGER:**

BORING NUMBER: B-2

Sheet: 2 of 10

SOIL BORING LOG

PROJECT: Exelon - CPS-ESP Field Investigation

LOCATION: B-2; West Side of ESP Footprint

ELEVATION: 737.8 Feet MSL

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DRILLING CONTRACTOR: TSC

DRILLING METHOD AND EQUIPMENT: 6-Inch Rotary, Bentonite Drilling Mud

3.7' bgs on 8/28/2002 8/2/2002 8/7/2002 MDG **WATER LEVELS: START: FINISH: LOGGER:**

BORING NUMBER: B-2

Sheet: 3 of 10

SOIL BORING LOG

PROJECT: Exelon - CPS-ESP Field Investigation

LOCATION: B-2; West Side of ESP Footprint

ELEVATION: 737.8 Feet MSL

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DRILLING CONTRACTOR: TSC

DRILLING METHOD AND EQUIPMENT: 6-Inch Rotary, Bentonite Drilling Mud

BORING NUMBER: B-2

Sheet: 4 of 10

SOIL BORING LOG

PROJECT: Exelon - CPS-ESP Field Investigation

LOCATION: B-2; West Side of ESP Footprint

ELEVATION: 737.8 Feet MSL

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DRILLING CONTRACTOR: TSC

DRILLING METHOD AND EQUIPMENT: 6-Inch Rotary, Bentonite Drilling Mud

BORING NUMBER: B-2

Sheet: 5 of 10

SOIL BORING LOG

PROJECT: Exelon - CPS-ESP Field Investigation

LOCATION: B-2; West Side of ESP Footprint

737.8 Feet MSL **ELEVATION:**

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WATER LEVELS: 3.7' bgs on 8/28/2002

DRILLING CONTRACTOR: TSC

DRILLING METHOD AND EQUIPMENT: 6-Inch Rotary, Bentonite Drilling Mud

START: 8/2/2002 **FINISH:** 8/7/2002 **LOGGER:** MDG

BORING NUMBER: B-2

Sheet: 6 of 10

SOIL BORING LOG

PROJECT: Exelon - CPS-ESP Field Investigation

LOCATION: B-2; West Side of ESP Footprint

737.8 Feet MSL **ELEVATION:**

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DRILLING CONTRACTOR: TSC

DRILLING METHOD AND EQUIPMENT: 6-Inch Rotary, Bentonite Drilling Mud

WATER LEVELS: 3.7' bgs on 8/28/2002 **800 START:** 8/2/2002 **FINISH:** 8/7/2002 **LOGGER:** MDG

BORING NUMBER: B-2

Sheet: 7 of 10

SOIL BORING LOG

PROJECT: Exelon - CPS-ESP Field Investigation

LOCATION: B-2; West Side of ESP Footprint

737.8 Feet MSL **ELEVATION:**

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DRILLING CONTRACTOR: TSC

DRILLING METHOD AND EQUIPMENT: 6-Inch Rotary, Bentonite Drilling Mud

BORING NUMBER: B-2

Sheet: 8 of 10

SOIL BORING LOG

PROJECT: Exelon - CPS-ESP Field Investigation

LOCATION: B-2; West Side of ESP Footprint

737.8 Feet MSL **ELEVATION:**

WATER LEVELS: 3.7' bgs on 8/28/2002

DRILLING CONTRACTOR: TSC

DRILLING METHOD AND EQUIPMENT: 6-Inch Rotary, Bentonite Drilling Mud

START: 8/2/2002 **FINISH:** 8/7/2002 **LOGGER:** MDG

DRILLING CONTRACTOR: TSC

BORING NUMBER: B-2

Sheet: 9 of 10

SOIL BORING LOG

PROJECT: Exelon - CPS-ESP Field Investigation

LOCATION: B-2; West Side of ESP Footprint

737.8 Feet MSL **ELEVATION:**

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WATER LEVELS: 3.7' bgs on 8/28/2002

DRILLING METHOD AND EQUIPMENT: 6-Inch Rotary, Bentonite Drilling Mud

START: 8/2/2002 **FINISH:** 8/7/2002 **LOGGER:** MDG

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BORING NUMBER: B-2

Sheet: 10 of 10

SOIL BORING LOG

PROJECT: Exelon - CPS-ESP Field Investigation

LOCATION: B-2; West Side of ESP Footprint

737.8 Feet MSL **ELEVATION:**

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DRILLING CONTRACTOR: TSC

DRILLING METHOD AND EQUIPMENT: 6-Inch Rotary, Bentonite Drilling Mud

WATER LEVELS: 3.7' bgs on 8/28/2002 **800 START:** 8/2/2002 **FINISH:** 8/7/2002 **LOGGER:** MDG

Sheet: 1 of 3

ROCK CORE LOG

LOCATION: B-2; West Side of ESP Footprint **ELEVATION: Ground: 737.8 Feet MSL DRILLING CONTRACTOR: TSC** NA 8/7/2002 8/7/2002 MDG **WATER LEVEL: START: FINISH: LOGGER: DRILLING METHOD AND EQUIPMENT:** 3-inch O.D. diamond tip double tube core barrel **PROJECT:** Exelon - CPS-ESP Field Investigation

Sheet: 2 of 3

ROCK CORE LOG

LOCATION: B-2; West Side of ESP Footprint **ELEVATION: Ground: 737.8 Feet MSL DRILLING CONTRACTOR: TSC** NA 8/7/2002 8/7/2002 MDG **WATER LEVEL: START: FINISH: LOGGER: DRILLING METHOD AND EQUIPMENT:** 3-inch O.D. diamond tip double tube core barrel **PROJECT:** Exelon - CPS-ESP Field Investigation

Sheet: 3 of 3

ROCK CORE LOG

LOCATION: B-2; West Side of ESP Footprint **ELEVATION: Ground: 737.8 Feet MSL DRILLING CONTRACTOR: TSC** NA 8/7/2002 8/7/2002 MDG **WATER LEVEL: START: FINISH: LOGGER: DRILLING METHOD AND EQUIPMENT:** 3-inch O.D. diamond tip double tube core barrel **PROJECT:** Exelon - CPS-ESP Field Investigation

BORING NUMBER: B-3

Sheet: 1 of 10

SOIL BORING LOG

PROJECT: Exelon - CPS-ESP Field Investigation

LOCATION: B-3; Eastern side of ESP footprint

734.2 **ELEVATION:**

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DRILLING CONTRACTOR: <code>TSC</code>

DRILLING METHOD AND EQUIPMENT: 6" Rotary, Bentonite Drill Mud

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5.5' bgs on 8/28/2002 7/26/02 8/1/02 MDG **WATER LEVELS: START: FINISH: LOGGER:**

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BORING NUMBER: B-3

Sheet: 2 of 10

SOIL BORING LOG

PROJECT: Exelon - CPS-ESP Field Investigation

WATER LEVELS: 5.5' bgs on 8/28/2002

LOCATION: B-3; Eastern side of ESP footprint

734.2 **ELEVATION:**

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DRILLING CONTRACTOR: _{TSC}

DRILLING METHOD AND EQUIPMENT: 6" Rotary, Bentonite Drill Mud

 $\textsf{START:}\,7/26/02$ FINISH: $8/1/02$ LOGGER: MDG

BORING NUMBER: B-3

Sheet: 3 of 10

SOIL BORING LOG

PROJECT: Exelon - CPS-ESP Field Investigation

LOCATION: B-3; Eastern side of ESP footprint

734.2 **ELEVATION:**

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DRILLING CONTRACTOR: TSC

DRILLING METHOD AND EQUIPMENT: 6" Rotary, Bentonite Drill Mud

BORING NUMBER: B-3

Sheet: 4 of 10

SOIL BORING LOG

PROJECT: Exelon - CPS-ESP Field Investigation

LOCATION: B-3; Eastern side of ESP footprint

734.2 **ELEVATION:**

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DRILLING CONTRACTOR: TSC

DRILLING METHOD AND EQUIPMENT: 6" Rotary, Bentonite Drill Mud

BORING NUMBER: B-3

Sheet: 5 of 10

SOIL BORING LOG

PROJECT: Exelon - CPS-ESP Field Investigation

LOCATION: B-3; Eastern side of ESP footprint

ELEVATION: 734.2

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DRILLING CONTRACTOR: TSC

DRILLING METHOD AND EQUIPMENT: 6" Rotary, Bentonite Drill Mud

BORING NUMBER: B-3

Sheet: 6 of 10

SOIL BORING LOG

PROJECT: Exelon - CPS-ESP Field Investigation

WATER LEVELS: 5.5' bgs on 8/28/2002

LOCATION: B-3; Eastern side of ESP footprint

ELEVATION: 734.2

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DRILLING CONTRACTOR: TSC

DRILLING METHOD AND EQUIPMENT: 6" Rotary, Bentonite Drill Mud

START: 7/26/02 **FINISH:** 8/1/02 **LOGGER:** MDG

BORING NUMBER: B-3

Sheet: 7 of 10

SOIL BORING LOG

PROJECT: Exelon - CPS-ESP Field Investigation

LOCATION: B-3; Eastern side of ESP footprint

ELEVATION: 734.2

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DRILLING CONTRACTOR: TSC

DRILLING METHOD AND EQUIPMENT: 6" Rotary, Bentonite Drill Mud

BORING NUMBER: B-3

Sheet: 8 of 10

SOIL BORING LOG

PROJECT: Exelon - CPS-ESP Field Investigation

WATER LEVELS: 5.5' bgs on 8/28/2002

LOCATION: B-3; Eastern side of ESP footprint

ELEVATION: 734.2

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DRILLING CONTRACTOR: TSC

DRILLING METHOD AND EQUIPMENT: 6" Rotary, Bentonite Drill Mud

START: 7/26/02 **FINISH:** 8/1/02 **LOGGER:** MDG

BORING NUMBER: B-3

Sheet: 9 of 10

SOIL BORING LOG

PROJECT: Exelon - CPS-ESP Field Investigation

LOCATION: B-3; Eastern side of ESP footprint

ELEVATION: 734.2

DRILLING CONTRACTOR: TSC

DRILLING METHOD AND EQUIPMENT: 6" Rotary, Bentonite Drill Mud

BORING NUMBER: B-3

Sheet: 10 of 10

SOIL BORING LOG

PROJECT: Exelon - CPS-ESP Field Investigation

LOCATION: B-3; Eastern side of ESP footprint

734.2 **ELEVATION:**

DRILLING CONTRACTOR: TSC

DRILLING METHOD AND EQUIPMENT: 6" Rotary, Bentonite Drill Mud

WATER LEVELS: 5.5' bgs on 8/28/2002 **START:** 7/26/02 **FINISH:** 8/1/02 **LOGGER: MDG**

Sheet: 1 of 2

ROCK CORE LOG

LOCATION: B-3; Eastern side of ESP footprint **ELEVATION: Ground: 734.2 Feet MSL DRILLING CONTRACTOR: TSC** NA 8/1/2002 8/1/2002 MDG **WATER LEVEL: START: FINISH: LOGGER: DRILLING METHOD AND EQUIPMENT:** 3-inch O.D. diamond tip double tube core barrel **PROJECT:** Exelon - CPS-ESP Field Investigation

Sheet: 2 of 2

ROCK CORE LOG

LOCATION: B-3; Eastern side of ESP footprint **ELEVATION: Ground: 734.2 Feet MSL DRILLING CONTRACTOR: TSC** NA 8/1/2002 8/1/2002 MDG **WATER LEVEL: START: FINISH: LOGGER: DRILLING METHOD AND EQUIPMENT:** 3-inch O.D. diamond tip double tube core barrel **PROJECT:** Exelon - CPS-ESP Field Investigation

PROJECT NUMBER: 171881.S1.02.01

BORING NUMBER: _{B-4}

Sheet: 1 of 4

SOIL BORING LOG

PROJECT: Exelon - CPS-ESP Field Investigation

LOCATION: B-4; Southeast corner of ESP footprint

ELEVATION: 735.4 Feet MSL

DRILLING CONTRACTOR: _{TSC}

DRILLING METHOD AND EQUIPMENT: 6-Inch Rotary, Bentonite Drilling Mud

WATER LEVELS: NA

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START: 7/24/2002 FINISH: 7/25/2002 LOGGER: MDG

BORING NUMBER: _{B-4}

Sheet: 2 of 4

SOIL BORING LOG

PROJECT: Exelon - CPS-ESP Field Investigation

LOCATION: B-4; Southeast corner of ESP footprint

ELEVATION: 735.4 Feet MSL

DRILLING CONTRACTOR: _{TSC}

DRILLING METHOD AND EQUIPMENT: 6-Inch Rotary, Bentonite Drilling Mud

WATER LEVELS: NA

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NA 7/24/2002 7/25/2002 MDG

BORING NUMBER: B-4

Sheet: 3 of 4

SOIL BORING LOG

PROJECT: Exelon - CPS-ESP Field Investigation

LOCATION: B-4; Southeast corner of ESP footprint

ELEVATION: 735.4 Feet MSL

DRILLING CONTRACTOR: TSC

DRILLING METHOD AND EQUIPMENT: 6-Inch Rotary, Bentonite Drilling Mud

WATER LEVELS: NA

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START: 7/24/2002 FINISH: 7/25/2002 LOGGER: MDG

BORING NUMBER: B-4

Sheet: 4 of 4

SOIL BORING LOG

PROJECT: Exelon - CPS-ESP Field Investigation

LOCATION: B-4; Southeast corner of ESP footprint

ELEVATION: 735.4 Feet MSL

DRILLING CONTRACTOR: TSC

DRILLING METHOD AND EQUIPMENT: 6-Inch Rotary, Bentonite Drilling Mud

WATER LEVELS: NA

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START: 7/24/2002 FINISH: 7/25/2002 LOGGER: MDG

Attachment A-2 Piezometer Construction Logs

Attachment A-3 GRL SPT Hammer Calibration Test Report
GRL Engineers, Inc.

Goble Rausche Likins and Associates, Inc. (Formerly)

August 12,2002

Mr. Don Anderson CH2MHill 777 108th Avenue NE Bellevue, WA 98004

Re: SPT Energy Measurement Summary Report Clinton Power Station Clinton, Illinois

GRL Job No. 027049

Dear Mr. Anderson:

This report summarizes the results from the dynamic energy measurements made on one SPT drill rig at the above referenced site on August 2, 2002. A preliminary summary of the test results was previously transmitted following the completion of the field work.

The purpose in making the dynamic measurements was to determine the average energy transfer from Testing Service Corporation's (TSC) manual Standard Penetration Test (SPT) safety hammer to NW-J drill rod during SPT sampling events. A PAK model, Pile Driving Analyzer ® (PDA) acquired and processed the dynamic test data to meet these test objectives. Additional information on the testing equipment, details on the analytical procedures, as well as limitations of dynamic test methods are presented in Exhibit A of this report.

Drill Rig and SPT Hammer Details

Testing was conducted on a truck mounted Gus Pech 7500 drill rig. This drill rig was equipped with a manual SPT safety hammer operated by a cathead and rope system. The drill rod used was NW rod with a J taper thread. The energy measurements were made using a 2 foot long instrumented NW rod segment inserted in the drill string immediately below the anvil of the hammer.

DYNAMIC TEST FIELD DETAILS **Insfrumentation**

A Pile Driving Analyzer (PDA) was used to process dynamic measurements of strain and acceleration taken on the 2 foot long NW rod segment located between the safety hammer and

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CH2MHill GRL Job No. 027049

drill string. The strain and acceleration signals were conditioned and converted to forces and velocities by the PDA. During SPT sampling, the PDA calculated values for the maximum force, the maximum impact velocity, the hammer operating rate, the transferred hammer energy to the gage location, and the energy transfer ratio. Calibration information for the strain gages attached to the instrumented rod segment and accelerometers used is included in $\rm~Exhibit~$ C.

Force and velocity records from the PDA were also viewed on a graphic LCD screen during sampling to evaluate data quality. Force and velocity records were digitally stored on disk for subsequent laboratory analysis.

Test Sequence

On August 2, 2002 energy measurements were made during SPT sampling in Boring 2 at the Clinton Power Station. The soil boring had been advanced to a depth of 43.5 feet prior to the first instrumented sampling event. Three TSC personnel operated the cathead and rope system as ten split spoon samples were collected at five foot intervals between the depths of 43.5 and 88.5 feet. Six of the ten split-spoon samples were driven 18 inches as blows were recorded for each of the three 6 inch increments. The SPT N value for each sampling event was then calculated as the number of blows for the final 12 inches of driving. Sampler refusal occurred during four of the sampling events. For three of these event Exhibit pler refused in the second 6 inch increment after 50 blows. For the fourth of these events, the sampler refused in the first increment after a reported 100 blows.

DYNAMIC TESTING ANALYSIS DETAILS *Case Method*

The PDA interprets the measured dynamic data according to the Case Method equations. The dynamic test data was evaluated for the energy transferred to the gage location, **(EFV);** the energy transfer ratio, (ETR); the maximum impact force at the gage location, (FMX); the maximum impact velocity at the gage location, (VT1); and the SPT hammer operating rate, (BPM). These quantities are presented in the summaries of the dynamic test results in Exhibit B.

The maximum energy transfer to the gage location was calculated by integrating both the force and velocity records over time as follows:

CH2MHill GRL Job No. 027049

$EFV = fF(t)V(t)dt$

Where: $F =$ the force at time t $V =$ the velocity at time t

The integration begins at the hammer impact time and continues until the maximum transferred energy is reached. Using this equation, the average energy transfer over the SPT N value increment was computed and is presented in Table 1. Data from the seating blows in the first 6 inch increment was not used in this calculation.

A summary of the energy measurement results for each cathead and rope operator is presented below:

The maximum, minimum, and standard deviation in energy transfer for each SPT sample over the SPT N value increment are included in Exhibit B.

Table 1 also includes the reported SPT N value and the SPT N value corrected for 60% transferred energy, N_{60} . The N_{60} value was calculated using the Schmertman correction as follows:

$$
\mathsf{N}_{60}=(\mathsf{e}_{\mathsf{m}}\,/\,60)\,\,\mathsf{N}_{\mathsf{m}}
$$

Where: e_m = the measured transferred energy ratio N_m = the measured SPT N value.

For informational purposes, the energy transfer to the drill rod string was also calculated using the **EF2** equation. This was the method specified in ASTM D-4633-86, Standard Test Method for Stress Wave Energy Measurement for Dynamic Penetrometer Testing Systems. In this equation, CH2MHill GRL Job No. 027049

the transfer energy is calculated assuming proportionality exists between force and velocity so that the transferred energy can be calculated in terms of only one measured quantity, the force. By assuming that force and velocity are proportional, the EF2 equation assumes that the drill rod is of constant cross sectional area which is seldom the case. For this reason, we have not presented the EF2 results in Table 1 or recommend their use.

The EF2 equation can be expressed as:

 $EF2 = (c/EA) [If(t)]^2 dt$

Where: $c =$ the stress wave speed in the drill rod E = Modulus of Elasticity of the drill rod $A = area of the drill rod at the gauge location$ $F =$ the force at time t

In the EF2 equation, the integration begins at the hammer impact time and continues to a cutoff time that corresponds to the first occurrence of a zero force after impact. The ASTM standard required that the cutoff time fall within a time of $0.9(2L/c)$ to $1.2(2L/c)$, where L is the length between the gage location and the bottom of the sampler. ASTM 0-4633 also required that several correction factors be applied based on the distance between the impact point and measuring station, the overall rod length, and a velocity correction factor. The energy calculated from this method is contained in the summary tables presented in Exhibit B. This data complies Exhibitwith the ASTM cutoff times. No other ASTM corrections have been applied. it should be noted that this ASTM standard expired in 1995 and a current ASTM standard does not exist.

CONCLUSIONS

Based upon the dynamic test data obtained, the following conclusions are presented:

1) Ten SPT sampling events were performed with TSC's Gus Pech 7500 drill rig utilizing a safety hammer hoisted by a cathead and rope system. The average energy transfer to the drill rod for an individual sampling event ranged from 136 to 208 ft-lbs. This corresponds to an energy transfer ratio of 39 to 60% of the 350 ft-lbs theoretical SPT hammer energy. The overall average for the eight sampling events was 183 ft-lbs or 52% of the theoretical energy.

- 2) The ten sampling events with the safety hammerfcathead and rope system were performed by three drillers: Francisco, Dave, and Greg. The average energy transfer for the four SPT sampling events performed by Francisco was 194 ft-lbs, and the average energy transfer for the four SPT sampling events performed by Dave was 167 ft-lbs. For the two sampling events performed by Greg, the average energy transfer was 195 ft-lbs.
- **3)** Sampler refusal occurred during four of the ten sampling events. For three of these events, the sampler refused in the second 6 inch increment after 50 blows. For the fourth of these events, the sampler refused in the first increment after a reported 100 blows.
- **4)** Variation between the reported SPT blow counts and the PDA recorded number of blows occurred for some of the samples. For these samples, the variation was accounted for by adjusting the number of "seating blows" in the first 6 inch SPT increment.

We appreciate the opportunity to be of assistance to you on this project. Please do not hesitate to contact us if you have any questions regarding this report, or if we may be of further service.

Sincerely,

GOBLE RAUSCHE LlKlNS **AND ASSOCIATES. INC.**

(Uwsling,₂ aliw)
tings Mark A. Rawlings

Patrick of Newman

Patrick J. Hannigan, P.E.

TABLE 1 : **Summary of SPT Hammer Energy Transfer Measurements Clinton Power Station, Clinton, Illinois**

Notes: 1) - Average energy transfer over second and third increment from FV Method.

2) - Average energy transferred to drill rod divided by 350 ft-lbs.

3) - SPT N value corrected for 60% energy using the Schmertman Correction Method.

All samples were taken with a split spoon sampler.

A cathead and rope system was utilized to hoist the safety hammer. The drill rig was a truck mounted Gus Pech 7500.

EXHIBIT A

An Introduction Into **Dynamic Testing Methods**

EXHIBIT A AN INTRODUCTION INTO DYNAMIC PILE TESTING METHODS

The following has been written by GRL Engineers, Inc. and may only be copied with its written permission.

Modern procedures of design and construction control require verification of bearing capacity and integrity of deep foundations during both preconstruction test programs and production installation. Dynamic pile testing methods meet this need economically and reliably, and therefore, form an important part of a quality assurance program when deep foundations are executed. Several dynamic pile testing methods exist; they have different benefits and limitations and different requirements for proper execution.

The Case Method of dynamic pile testing, named after the Case Institute of Technology where it was developed between 1964 and 1975, requires that a substantial ram mass (e.g. a pile driving hammer) impacts the pile top such that the pile undergoes at least a small permanent set. The method is therefore also referred to as a "High Strain Method". The Case Method requires dynamic measurements on the pile or shaft under the ram impact and then an evaluation of various quantities based on closed form solutions of the wave equation, a partial differential equation describing the motion of a rod under the effect of an impact. Conveniently, measurements and analyses are done by a single piece of equipment: the Pile Driving Analyzer® (PDA). However, for bearing capacity evaluations an important additional method is CAPWAP® which performs a much more rigorous analysis of the dynamic records than the simpler Case Method.

A related analysis method is the "Wave Equation Analysis" which calculates a relationship between bearing capacity and pile stress and field blow count. The GRLWEAPTM program performs this analysis and provides a complete set of helpful information and input data.

The following description deals primarily with the "High Strain Test" Method of pile testing. However, for the sake of completeness, two types of "Low Strain Tests" are also mentioned: the Pile Integrity Test™ (PIT) and Cross Hole Sonic Logging conducted with the Cross Hole Analyzer (CHA).

1. BACKGROUND 2. RESULTS FROM PDA DYNAMIC TESTING

There are two main objectives of high strain dynamic pile testing:

- Dynamic Pile Monitoring.
- Dynamic Load Testing.

Dynamic pile monitoring is conducted during the installation of impact driven piles to achieve a safe and economical pile installation. Dynamic load testing, on the other hand, has as its primary goal the assessment of pile bearing capacity. It is applicable to both drilled shafts and impact driven piles during restrike.

2.1 DYNAMIC PlLE MONlTORlNG

During pile installation, the sensors attached to the pile measure pile top force and velocity. A PDA conditions and processes these signals and calculates or evaluates:

- Bearing capacity at the time of testing, including an assessment of shaft resistance development and driving resistance. This information supports formulation of a driving criterion.
- Dynamic pile stresses axial and averaged over the pile cross section, both tensile and compressive, during pile driving to limit the potential of damage either near the pile top or along its length. Bending stresses can be evaluated at the point of sensor attachment.
- Pile integrity assessment by the PDA is based on the recognition of certain wave reflections from along the pile. If detected early enough, a pile may be saved from complete destruction. On the other hand, once damage is recognized measures can be taken to prevent reoccurrence.
- Hammer performance parameters including the energy transferred to the pile, the hammer speed in blows per minute and the stroke of open ended diesel hammers.

2.2 DYNAMIC PILE LOAD TESTING 3. MEASUREMENTS

Bearing capacity testing of either driven piles or drilled shafts employs the basic measurement approach of dynamic pile monitoring. However, the test is done independent of the pile installation process and therefore a pile driving hammer or other dynamic loading device may not be available. If a special ram has to be mobilized then its weight should be between 0.8 and 2% of the test load (e.g. between **4** and 10 tons for a 500 ton test load) to assure sufficient soil resistance activation.

For a successful test, it is most important that the test is conducted after a sufficient waiting time following pile installation for soil properties approaching their long term condition or concrete to properly set. During testing, PDA results of pile/shaft stresses and transferred energy are used to maintain safe stresses and assure sufficient resistance activation. For safe and sufficient testing of drilled shafts, ram energies are often increased from blow to blow until the test capacity has been activated. On the other hand, restrike tests on driven piles may require a warm hammer so that the very first blow produces a complete resistance activation. Data must be complete resistance activation. evaluated by CAPWAP for bearing capacity.

After the dynamic load test has been conducted with sufficient energy and safe stresses, the CAPWAP analysis provides the following results:

- **Bearingcapacity, i.e.** the mobilized capacity present at the time of testing.
- **Resistance distribution** including shaft resistance and end bearing components.
- **Stresses in pile orshaff** calculated for both the static load application and the dynamic test. These stresses are averages over the cross section and do not include bending effects or nonuniform contact stresses, e.g. when the pile toe is on uneven rock.
- **Shaffimpedance vs. depth;** this is an estimate of the shaft shape if it differs substantially from the planned profile.
- **Dynamic soil parameters** for shaft and toe, i.e. damping factors and quakes (related to the dynamic stiffness of the resistance at the pile/soil interface).

The following is a general summary of dynamic measurements available to solve typical deep foundation problems.

3.1 PDA

The basis for the results calculated by the PDA are pile top strain and acceleration measurements which are converted to force and velocity records, respectively. The PDA conditions, calibrates, and displays these signals and immediately computes average pile force and velocity thereby eliminating bending effects. Using closed form Case Method solutions, based on the one-dimensional linear wave equation, the PDA calculates the results described in the analytical solutions section below.

3.2 HPA

The ram velocity may be directly obtained using radar technology in the Hammer Performance Analyzer[™]. For this unit to be applicable, the ram must be visible. The impact velocity results can be automatically processed with a PC or recorded on a strip chart.

3.3 SAXIMETER™

For open end diesel hammers, the time between two impacts indicates the magnitude of the ram fall height or stroke. This information is not only measured and calculated by the PDA but also by the convenient, hand-held Saximeter.

3.4 PIT

The Pile Integrity Tester™ (PIT) helps in detecting major defects in concrete piles or shafts or assess the length of a variety of deep foundations, except steel piles. PIT performs the so-called "Pulse-Echo Method" which only requires the measurement of motion (e.g., acceleration) at the pile top caused by a light hammer impact. PIT also supports the socalled "Transient Response Method" which requires the additional measurement of the hammer force and an analysis in the frequency domain. PIT may also be used to evaluate the unknown length of deep foundations under existing structures.

This test requires that at least two tubes (typically steel tubes of 50 mm diameter) are installed vertically in the shaft to be tested. A high frequency signal is generated in one of the water filled tubes and received in the other tube. The received signal strength and its First Time of Arrival (FTA) yield important information about the concrete quality between the two tubes. The transmitting and recording of the signal is repeated typically every **50** mm starting at the shaft bottom and all records together establish a log or profile of the concrete quality between the two tubes. The total number of tubes installed depends on the size of the drilled shaft. The more tubes are present the more profiles can be constructed.

4.ANALYTICAL SOLUTIONS

4.1 BEARING CAPA *ClN*

4.1.1 WAVE EQUATION

GRL has written the GRLWEAPTM program which calculates a relationship between bearing capacity, pile stress, and blow count. This relationship is often called the "bearing graph." Once the blow count is known from pile installation logs, the bearing graph

Figure 1. Block Diagram of Refined Wave Equation Analysis

yields the bearing capacity. This approach requires no measurements other than blow count. Rather it requires an accurate knowledge of the various parameters describing hammer, driving system, pile, and soil. The wave equation is also very useful during

3.5 CHA the design stage of a project for the selection of hammer, cushion, and pile size.

> After dynamic pile monitoring and/or dynamic load testing has been performed, the "Refined Wave Equation Analysis" or RWEA (Figure 1) is often performed by inputting the PDA and CAPWAP calculated parameters. With many of the dynamic parameters verified by the dynamic tests, it is a more reliable basis for a safe and sufficient driving criterion.

4.1.2 CASE METHOD

The Case Method is a closed form solution based on a few simplifying assumptions such as ideal plastic soil behavior and an ideally elastic and uniform pile. Given the measured pile top force, F(t), and pile top velocity, v(t), the total soil resistance is

$$
R(t) = \frac{1}{2} \{ [F(t) + F(t_2)] + Z[v(t) - v(t_2)] \}
$$
 (1)

where:

- \mathbf{t} a point in time after impact. $=$
- time $t + 2 \cup c$. $t₂$ \approx
- L pile length below gages. $=$
- $=$ $(E/\rho)^{1/2}$ is the speed of the stress wave. \overline{c}
- pile mass density.
- $Z = E$ A/c is the pile impedance.
- elastic modulus of the pile (ρc^2).
- pile cross sectional area.

The total soil resistance consists of a dynamic (R_a) and a static (R_s) component. The static component is therefore

$$
R_s(t) = R(t) - R_d(t). \tag{2}
$$

The dynamic component may be computed from a soil damping factor, J, and the pile velocity, $v_t(t)$ which is conveniently calculated for the pile toe. Using wave considerations, this approach leads immediately to the dynamic resistance

$$
R_{d}(t) = J[F(t) + Zv(t) - R(t)]
$$
 (3)

and finally to the static resistance by means of Equation 2.

There are a number of ways in which Eq. **1** through 3 could be evaluated. Most commonly, T is set to that time at which the static resistance becomes maximum. The result is the so-called RMX capacity. Damping factors for RMX typically range between 0.5 for coarse grained materials to 1.0 for clays. The **RSP** capacity (this method is most commonly referred to in the literature, yet it is not very frequently used) requires damping factors between 0.1 for sand and **1.0** for clay. Another capacity, RA2, determines the capacity at a time when the pile is essentially at rest and thus damping is small; **RA2** therefore requires no damping parameter. In any event, the proper Case Method and its associated damping parameter is most conveniently found after a CAPWAP analysis has been performed for one record. The capacities for other hammer blows are then quickly calculated for the thus selected Case Method and its associated damping factor.

The static resistance calculated by either Case Method or CAPWAP is the mobilized resistance at the time of testing. Consideration therefore has to be given to soil setup or relaxation effects and whether or not a sufficient set has been achieved under the test loading that would correspond to a full activation of the ultimate soil resistance.

The PDA also calculates an estimate of shaft resistance as the difference between force and velocity times impedance at the time immediately prior to the return of the stress wave from the pile toe. This shaft resistance is not reduced by damping effects and is therefore called the total shaft resistance SFT. A correction for damping effects produces the static shaft resistance estimate, SFR.

The Case Method solution is simple enough to be evaluated "in real time," i.e. between hammer blows, using the PDA. It is therefore possible to calculate all relevant results for all hammer blows and plot these results as a function of depth or blow number. This is done in the PDI-PLOT program or formerly in the DOS based PDAPLOT program.

4.1.3 CAPWAP

The CAse Pile Wave Analysis Program combines the wave equation pile and soil model with the Case Method measurements. Thus, the solution includes not only the total and static bearing capacity values but also the shaft resistance, end bearing, damping factors, and soil stiffness values. The method iteratively calculates a number of unknowns by signal matching. While it is necessary to make hammer performance assumptions for a GRLWEAP analysis, the CAPWAP program works with the pile top measurements. Furthermore, while GRLWEAP and Case Method require certain assumptions regarding the soil behavior, CAPWAP calculates these soil parameters based on the dynamic measurements.

4.2 **STRESSES**

During pile monitoring, it is important that compressive stress maxima at pile top and toe and tensile stress maxima somewhere along the pile be calculated for each hammer blow.

At the pile top (location of sensors) both the maximum compression stress, CSX, and the maximum stress from individual strain transducers, CSI, are directly obtained from the measurements. Note that CSI is greater than or equal to CSX and the difference between CSI and CSX is a measure of bending in the plane of the strain transducers. Note also that all stresses calculated for locations below the sensors are averaged over the pile cross section and therefore do not include components from either bending or eccentric soil resistance effects.

The PDA calculates the compressive stress at the pile bottom, CSB, assuming (a) a uniform pile and (b) that the pile toe force is the maximum value of the total resistance, R(t), minus the total shaft resistance, SFT. Again, for this stress estimation uniform resistance force are assumed (e.g. not a sloping rock.)

For concrete piles, the maximum tension stress, TSX, is also of great importance. It occurs at some point below the pile top. The maximum tension stress can be computed from the pile top measurements by finding the maximum tension wave (either traveling upward, W_u, or downward, W_d) and reducing it by the minimum compressive wave traveling in opposite direction.

$$
W_{u} = \frac{1}{2} [F(t) - Zv(t)] \tag{4}
$$

$$
W_{d} = \frac{1}{2}[F(t) + ZV(t)] \tag{5}
$$

CAPWAP also calculates tensile and compressive stresses along the pile and, in general, more accurately than the PDA. In fact, for non-uniform piles or piles with joints, cracks or other discontinuities, the closed form solutions from the PDA may be in error.

4.3 PILE INTEGRITY BY PDA

Stress waves in a pile are reflected wherever the pile impedance, $Z = E A/c = \rho cA = A \sqrt{(E \rho)}$, changes. Therefore, the pile impedance is a measure of the quality of the pile material (E, p, c) and the size of its cross section (A). The reflected waves arrive at the pile top at a time which is greater the farther away from the pile top the reflection occurs. The magnitude of the change of the upward traveling wave (calculated from the measured force and velocity, Eq. 4) indicates the extent of the cross sectional change. Thus, with β (BTA) being a relative integrity factor which is unity for no impedance change and zero for the pile end, the following is calculated by the PDA:

$$
\beta = (1 - \alpha)/(1 + \alpha) \tag{6}
$$

with

$$
\alpha = \frac{1}{2}(W_{UR} - W_{UD})/(W_{Di} - W_{UR})
$$
 (7)

where

- W_{UR} is the upward traveling wave at the onset of 0.1 m).
the damage reflected wave. It is caused by the damage reflected wave. It is caused by **4.5 DETERMINATION OF WAVE SPEED** resistance.
-
- W_{Di} is the maximum downward traveling wave due to impact.

It can be shown that this formulation is quite accurate as long as individual reflections from different pile impedance changes have no overlapping effects on the stress wave reflections.

Without rigorous derivation, it has been proposed to consider as slight damage when β is above 0.8 and a serious damage when **P** is less than 0.6.

4.4 HAMMER PERFORMANCE BY PDA

The PDA calculates the energy transferred to the pile c = 2L/T. (10)
top from: (10)

$$
E(t) = \int_0^t F(\tau)v(\tau) d\tau
$$
 (8a)

The maximum of the E(t) curve is often called ENTHRU; it is the most important information for an overall evaluation of the performance of a hammer and driving system. ENTHRU or EMX allow for a classification of the hammer's performance when presented as, e_{τ} , the rated transfer efficiency, also called energy transfer ratio (ETR) or global efficiency.

$$
e_T = EMX/E_R
$$
 (8b)

where

 E_R is the hammer manufacturer's rated energy value.

Both Saximeter and PDA calculate the stroke (STK) of an open end diesel hammer using

$$
STK = (g/8) T_B^2 - h_L
$$
 (9)

where

- **g** is the earth's gravitational acceleration, T_B is the time between two hammer blows,
-
- **h,** is a stroke loss value due to gas compression and time losses during impact (usually 0.3 ft or

 W_{UD} is the upward traveling reflection wave due to
the damage. The damage. The damage. The damage. W_{UD} is the damage. W_{UD} is determined from strain most cases general force is determined from strain by multiplication with elastic modulus, E, and cross sectional area, A, the dynamic elastic modulus has to be determined for pile materials other than steel. In general, the records measured by the PDA clearly indicate a pile toe reflection as long as pile penetration per blow is greater than 1 mm or .04 inches. The time between the onset of the force and velocity records at impact and the onset of the reflection from the toe (usually apparent by a local maximum of the wave up curve) is the so-called wave travel time, T. Dividing 2L (L is here the length of the pile below sensors) by T leads to the stress wave speed in the pile:

$$
z = 2LT.
$$
 (10)

The elastic modulus of the pile material is related to the wave speed according io the linear elastic wave equation theory by

$$
E = c^2 \rho. \tag{11}
$$

Since the mass density of the pile material, p , is usually well known (an exception is timber for which samples should be weighed), the elastic modulus is easily found from the wave speed. Note, however, that this is **a** dynamic modulus which is generally higher than the static one and that the wave speed depends to some degree on the strain level of the stress wave. For example, experience shows that the wave speed from PIT is roughly 5% higher than the wave speed observed during a high strain test.

Other Notes:

- If the pile material is nonuniform then the wave speed c, according to Eq. 10, is an average wave speed and does not necessarily reflect the pile material properties of the location where the strain sensors are attached to the pile top. For example, pile driving often causes fine tension cracks some distance below the top of concrete piles. Then the average c of the whole pile is lower than the wave speed at the pile top. It is therefore recommended to determine E in the beginning of pile driving and not adjust it when the average c changes during the pile installation.
- If the pile has such a high resistance that there is no clear indication of a toe reflection then the wave speed of the pile material must be determined either by assumption or by taking a sample of the concrete and measuring its wave speed in a simple free column test. Another possibility is to use the proportionality relationship, discussed under "DATA QUALITY CHECKS" to find c as the ratio between the measured velocity and measured strain.

5. DATA QUALITY CHECKS

Quality data is the first and foremost requirement for accurate dynamic testing results. It is therefore important that the measurement engineer performing PDA or PIT tests has the experience necessary to recognize measurement problems and take appropriate corrective action should problems develop. Fortunately, dynamic pile testing allows for certain data quality checks because two independent measurements are taken that have to conform to certain relationships.

5.1 PROPORTIONALITY

As long as there is only a wave traveling in one direction, as is the case during impact when only a downward traveling wave exists in the pile, force and velocity measured at the pile top are proportional

$$
F = v Z = v (E A/c). \tag{12a}
$$

This relationship can also be expressed in terms of stress

$$
\sigma = v \text{ (E/c)} \tag{12b}
$$

or strain

$$
\varepsilon = \mathsf{v}/\mathsf{c}.\tag{12c}
$$

This means that the early portion of strain times wave speed must be equal to the velocity unless the proportionality is affected by high friction near the pile top or by a pile cross sectional change not far below the sensors. Checking the proportionality is an excellent means of assuring meaningful measurements.

5.2 NUMBER OF SENSORS

Measurements are always taken at opposite sides of the pile so that the average force and velocity in the pile can be calculated. The velocity on the two sides of the pile is very similar even when high bending exists. Thus, an independent check of the velocity measurements is easy and simple.

Strain measurements may differ greatly between the two sides of the pile when bending exists. It is even possible that tension is measured on one side while very high compression exists on the other side of the pile. In extreme cases, bending might be so high that it leads to a nonlinear stress distribution. In that case the averaging of the two strain signals does not lead to the average pile force and proportionality will not be achieved.

When testing drilled shafts, measurements of strain may also be affected by local concrete quality variations. It is then often necessary to use four strain transducers spaced at 90 degrees around the pile for an improved strain data quality. The use of four transducers is also recommended for large pile diameters, particularly when it is difficult to mount the

sensors at least two pile widths or diameters below the pile top.

6. LIMITATIONS, ADDITIONAL CONSIDERATIONS

6.1 MOBILIZA TlON OF CAPACITY

Estimates of pile capacity from dynamic testing indicate thew mobilized pile capacity at the time of testing. At very high blow counts (low set per blow), dynamic test methods tend to produce lower bound capacity estimates as not all resistance (particularly at and near the toe) is fully activated.

6.2 TIME DEPENDENT SOIL RESISTANCE EFFORTS

Static pile capacity from dynamic method calculations provides an estimate of the axial pile capacity. Increases and decreases in the piie capacity with time typically occur as a result of soil setup and relaxation. Therefore, restrike testing usually yields **a** better indication of long term pile capacity than a test at the end of pile driving. Often a wait period of one or two days between end of driving and restrike is satisfactory for a realistic prediction of pile capacity but this waiting time depends, among other factors, on the permeability of the soil.

6.2.1 SOIL SETUP

Because excess positive pore pressures often develop during pile driving in fine grained soils (clays, silts, or even fine sands), the capacity of a pile at the time of driving may often be less than the long term pile capacity. These pore pressures reduce the effective stress acting on the pile thereby reducing the soil resistance to pile penetration, and thus the pile capacity at the time of driving. As these pore pressures dissipate, the soil resistance acting on the pile increases as does the axial pile capacity. This phenomenon is routinely called soil setup or soil freeze. There are numerous other reasons for soil setup such as realignment of clay particles, arching that reduces effective stresses during pile installation in very dense sands, soil fatigue in overconsolidated clays, etc.

6.2.2 RELAXATION

Relaxation capacity reduction with time has been observed for piles driven into weathered shale, and may take several days to fully develop. Where relaxation occurs, pile capacity estimates based upon initial driving or short term restrike tests can significantly overpredict long term pile capacity. Therefore, piles driven into shale should be tested after a minimum one week wait either statically or dynamically with particular emphasis on the first few blows. Relaxation has also been observed for displacement piles driven into dense saturated silts or fine sands due to a negative pore pressure effect at the pile toe. In general, relaxation occurs at the pile toe and is therefore relevant for end bearing piles. Restrike tests should be performed and compared with the records from early restrike blows in order to avoid dangerous over-predictions.

6.3 CAPACITY RESULTS FOR OPEN PILE PROFILES

Open ended pipe piles or H-piles which do not bear on rock may behave differently under dynamic and static loading conditions. Under dynamic loads the soil inside the pile or between its flanges may slip and produce internal friction while under static loads the plug may move with the pile, thereby creating end bearing over the full pile cross section. As a result both friction and end bearing components may be different under static and dynamic conditions.

6.4 CAPWAPANALYSiS RESULTS

A portion of the soil resistance calculated on an individual soil segment in a CAPWAP analysis can usually be shifted up or down the shaft one soil segment without significantly altering the signal match quality. Therefore, use of the CAPWAP resistance distribution for uplift, downdrag, scour, or other geotechnical considerations should be made with an understanding of these analysis limitations.

PDA and CAPWAP calculated stresses are average values over the cross section. Additional allowance has to be made for bending or nonuniform contact stresses. To prevent damage it is therefore important to maintain good hammerpile alignment and to protect the pile toes using appropriate devices or an increased cross sectional area.

In the United States it has become generally acceptable to limit the dynamic installation stresses of driven piles to the following levels:

- 90% of yield strength for steel piles
- 85% of the concrete compressive strength after subtraction of the effective prestress - for concrete piles in compression
- 100% of effective prestress plus **W** of the concrete's tension strength for prestressed piles in tension
- 70% of the reinforcement strength for regularly reinforced concrete piles in tension
- 300% of the static design allowable stress for timber.

Note that the dynamic stresses may either be directly measured at the pile top by the PDA or calculated by the PDA for other locations along the pile based on the pile top measurements. The above allowable stresses also apply to those calculated by wave equation.

Numerous factors have to be considered in pile
foundation design. Some of these considerations
include:
include:
trace concentrations of the pile cross section. Thus, bending stresses or

• additional pile loading from downdrag or these results. Stress maxima calculated by the wave
negative skin friction, equation are usually subjected to the same limits as

- **6.5 STRESSES** . lateral and uplift loading requirements,
	- . effective stress changes (due to changes in water table, excavations, fills or other changes in overburden),
	- long term settlements in general and settlement from underlying weaker layers and/or pile group effects,
	- loss of shaft resistance due to scour or other effects,
	- loss of structural pile strength due to additional bending loads, buckling (the dynamic loads generally do not cause buckling even though they may exceed the buckling strength of the pile section), corrosion, etc.

These factors have not been evaluated by GRL and have not been considered in the interpretation of the dynamic testing results. The foundation designer should determine if these or any other considerations are applicable to this project and the foundation design.

6.7 WAVE EQUATION ANALYSIS RESULTS

The results calculated by the wave equation analysis program depend on a variety of hammer, pile, and soil input parameters. Although attempts have been made to base the analysis on the best available information, actual field conditions may vary and therefore stresses and blow counts may differ from the predictions reported. Capacity predictions derived from wave equation analyses should use restrike information. However, because of the uncertainties associated with restrike blow counts and restrike hammer energies, correlations of such results with static test capacities have often displayed considerable scatter.

6.6 ADDITIONAL DESIGN CONSIDERATIONS As for PDA and CAPWAP, the theory on which GRLWEAP is based is the one-dimensional wave equation. For that reason, stress predictions by the stress concentrations due to non-uniform impact or uneven soil or rock resistance are not considered in equation are usually subjected to the same limits as

those measured directly or calculated from measurements by the PDA.

7. FACTORS OF SAFETY

Run to failure, static or dynamic load tests yield an ultimate pile bearing capacity, R_{out} . If this failure load were applied to the pile, then excessive settlements would occur. Therefore, it is absolutely necessary that the actually applied load, also called the design load, R_d (or working load or safe load), is less than R_{ult} . In most soils, to limit settlements it is necessary that R_{cut} , is at least 50% higher than R_d . This means that

 $R_{\text{cut}} \geq 1.5 R_{\text{ct}}$

or the Factor of Safety has to be at least 1.5.

Unfortunately, neither applied loads nor R_{out} are exactly known. One static load test may be performed at a site, but that would not guarantee that all other piles have the same capacity and it is to be expected that a certain percentage of the production piles have lower capacities, either due to soil variability or due to pile damage. If, for example, dynamic pile tests are performed on piles in shale only a short time after pile installation, then the test capacity may be higher than the long term capacity of the pile. On the other hand, due to soil setup, piles generally gain capacity after installation and since tests are only done a short time after installation, a lower capacity value is ascertained than the capacity that eventually develops.

Not only are bearing capacity values of all piles unknown, even loads vary considerably and occasional overloads must be expected. We would not want a structure to become unserviceable or useless because of either an occasional overload or a few piles with low capacity. For this reason, and to avoid being overly conservative which would mean excessive cost, modem safety concepts suggest that the overall factor of safety should reflect the uncertainty in both loads and resistance. Thus, if all piles were statically tested and if we carefully controlled the loads, we probably could live with $F.S. = 1.5$. However, in general, depending on the building type or load combinations and as a function of quality assurance of pile foundations, a variety of Factors of Safety have been proposed.

For example, based on AASHTO specifications for highway related loads, the Federal Highway Administration proposes the following:

F.S.= 2.00 for static load test with wave equation.

F.S.= 2.25 for dynamic testing with wave equation analysis.

F.S.= 2.50 for indicator piles with wave equation analysis.

F.S.= 2.75 for wave equation analysis.

F.S.= 3.50 for Gates or other dynamic formula.

It should be mentioned that all of these methods should always be combined with soil exploration and static pile analysis. Also, specifications are occasionally updated and therefore the latest version should be variously consulted for the appropriate factors of safety.

Codes, among them PDCA, ASCE, or specifications issued by State Departments of Transportation specify different factors of safety. However, the range of recommended overall factors of safety in the United States varies between 1.9 and 6.

It is the designer's responsibility to identify design loads together with the adopted safety factor concept and associated construction control procedure. The required factors of safety should be included in design drawings or specifications together with the required testing. Only contractors bid for the work and develop the most economical solution. This should include a program of increased testing for lower required pile capacities. This will also help to reduce the confusion that often exists on construction sites as to design loads and require capacities. In any event, it be cannot expected that the test engineer is aware of and responsible for the variety of considerations that must be met to find the appropriate factor of safety. App-A-PDA-9-01

EXHIBIT 6

Dynamic Testing Field Results

 \sim

*BLC USER INPUT

- BL# COMMENTS
	- 1 Operator: Francisco
	- 1 Reported Blow Count: 5, 5, 8.

DRIVEN (02-Aug-02 : B-2-435.MDF)

 \sim

DRIVEN (02-Aug-02 : B-2-435.MDF)

 $\mathcal{L}^{\text{max}}_{\text{max}}$ and $\mathcal{L}^{\text{max}}_{\text{max}}$

*BLC USER INPUT

- BL# COMMENTS
	- 1 Operator: Dave
	- 1 Reported Blow Count: 9, 15, 21.

DRIVEN (02-Aug-02 : B-2-485.MDF)

DRIVEN (02-Aug-02 : B-2-485.MDF)

 \sim 10 $^{-1}$

 $\hat{\mathcal{L}}_{\text{max}}$ and $\hat{\mathcal{L}}_{\text{max}}$ and $\hat{\mathcal{L}}_{\text{max}}$ are $\hat{\mathcal{L}}_{\text{max}}$

*BLC USER INPUT

BL# COMMENTS

1 Operator: Greg

1 Reported Blow Count: 22, 50/5 inches

 $\sim 10^7$

DRIVEN (02-Aug-02 : B-2-535.MDF)

 \mathcal{L}_{max} and \mathcal{L}_{max} and \mathcal{L}_{max} and \mathcal{L}_{max}

DRIVEN (12-Aug-02 : B-2-535.MDF)

ACTUAL DATE 02-Aug-02 (Correction by CH2MHILL) ACTUAL DATE 02-Aug-02 (Correction by CH2MHILL)

 \mathcal{F}_{max} , \mathcal{F}_{max} , \mathcal{F}_{max} ,

*BLC USER INPUT

- BL# COMMENTS
	- 1 Operator: Francisco
	- 1 Reported Blow Count: 21, 14, 16.

 ~ 10

DRIVEN (02-Aug-02 : B-2-585.MDF)

 $\label{eq:2} \mathcal{L}(\mathbf{a}) = \left\{ \begin{array}{ll} \mathcal{L}(\mathbf{a}) & \mathcal{L}(\mathbf{a}) & \mathcal{L}(\mathbf{a}) \\ \mathcal{L}(\mathbf{a}) & \mathcal{L}(\mathbf{a}) & \mathcal{L}(\mathbf{a}) \end{array} \right.$

DRIVEN (12-Aug-02 : B-2-585.MDF)

*BLC USER INPUT

BL# COMMENTS

1 Operator: Dave

1 Reported Blow Count: 32, 50/5 inches.

DRIVEN (02-Aug-02 : B-2-635.MDF)

 \sim

 $\bar{\psi}$

DRIVEN (12-Aug-02 : B-2-635.MDF)

 \hat{p} , \hat{p} , \hat{p}

 \sim

*BLC USER INPUT

- BL# COMMENTS
	- .
Derator: Francisco
	- 1 Reported Blow Count: 19, 25, 28.

 $\sim 10^7$

DRIVEN (02-Aug-02 : B-2-685.MDF)

DRIVEN (12-Aug-02 : B-2-685.MDF)

**Example 2 ACTUAL DATE 02-Aug-02

Example 2 Correction by CH2MHILL) (Correction by CH2MHILL)**

 \hat{A} , and \hat{A} , and \hat{A}

 $\sim 10^7$

*BLC USER INPUT

- BL# COMMENTS
	- 1 Operator: Dave
	- 1 Reported Blow Count: 15, 25, 23.

DRIVEN (02-Aug-02 : B-2-735.MDF)

DRIVEN (12-Aug-02 : B-2-735.MDF)

ACTUAL DATE 02-Aug-02 (Correction by CH2MHILL) ACTUAL DATE 02-Aug-02 (Correction by CH2MHILL)

 \mathcal{L}

 $\mathcal{A}=\mathcal{A}$

***BLC USER INPUT**

- **BL# COMMENTS**
	- **1 Operator: Greg**
	- **1 Reported Blow Count: 15, 27, 40.**

 \bar{z}

DRIVEN (02-Aug-02 : **B-2-785.MDF)**

DRIVEN (12-Aug-02 : **B-2-785.MDF)**

 \mathcal{L}_{in}

***BLC USER INPUT**

BL# COMMENTS

1 Operator: Francisco

1 Reported Blow Count: 22, 50/5 inches.

DRIVEN (02-Aug-02 : **B-2-835.MDF)**

DRIVEN (12-Aug-02 : B-2-835.MDF)

أفارقه المفرود المتحدة

***BLC USER INPUT**

BL# COMMENTS

- **1 Operator: Dave**
- **1 Reported Blow Count: 100/4 inches.**

DRIVEN (02-Aug-02 : **B-2-885.MDF)**

DRIVEN (12-Aug-02 : B-2-885 .MDF)

ACTUAL DATE 02-Aug-02
 ACTUAL DATE 02-Aug-02 (Correction by CH2MHILL)

EXHIBIT C

Strain Transducer

and

Accelerometer Calibration Information

Gobie Rausche Likins and Associates, Inc. CALIBRATION SHEET

 \mathcal{A}

Strain Transducers

Piezoelectric Accelerometers

Piezoresistive Accelerometers

