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**IDENTIFICATION OF TYPE II FAULTS
(FAULTS THAT ARE CANDIDATES FOR
DETAILED INVESTIGATIONS)
IN THE YUCCA MOUNTAIN REGION**

Prepared for

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1 INTRODUCTION

1.1 BACKGROUND

In order to provide guidance to the U.S. Department of Energy (DOE) on appropriate investigations for the identification of fault displacement hazards and seismic hazards at a generic geologic repository, the Nuclear Regulatory Commission (NRC) developed NUREG-1451 Staff Technical Position on Investigations to Identify Fault Displacement Hazards and Seismic Hazards at a Geologic Repository (McConnell et al., 1992). In the present letter report, guidance from McConnell et al. (1992) is used to classify faults in two electronic fault coverages in the Center for Nuclear Waste Regulatory Analyses (CNWRA) Geographic Information System (GIS) database and one U.S. Geological Survey (USGS) textual coverage.

1.2 SCOPE

The three coverages considered in this study include more than 400 faults within 100 km of the proposed Yucca Mountain (YM) repository site. Earthquakes and fault displacement on many of these faults will have no effect on the repository design or performance because they are either too far from the repository or are too small to generate a significant magnitude earthquake. In order to identify faults important to repository design or performance, this study applies a coarse screening criterion to the three fault coverages. The faults identified using the criteria of McConnell et al. (1992) as having the potential for little or no effect on the repository are removed from the total fault population. The remaining faults are those which require additional characterization or closer study to determine their potential effects on design and performance. In a future study (IM 5708-471-640) the faults in the remaining group will be reviewed individually in light of available information to again determine whether or not they have the potential to effect repository design or performance. Only the potential hazards associated with ground motion or fault displacement were considered in this study. Other disruptive conditions related to structural deformation, such as changes in rock properties and the effects of structural deformation on water and magma flow, are not considered in this assessment.

The principal intended outcome of this study is to provide a basis for NRC to review DOE determination of significant faults. With this information, NRC may be able to clarify or resolve technical concerns related to structural deformation and seismic hazards at the proposed repository by identifying faults for which additional information is required; and eliminate from further consideration those which will have little or no effect on repository design or performance.

In this report, the term "fault" is used under the definition as proposed by Groshong (1988) in which a fault is "a tabular region across which the displacement parallel to the zone is appreciably greater than the width of the zone and in which the deformation is greater than outside the zone" is accepted.

2 BACKGROUND OF STUDY

2.1 CLASSIFICATION OF FAULTS

NUREG-1451 developed a classification of faults, according to their potential to affect repository design or performance. The classification and distinguishing criteria are given in Table 1.

Type I faults are those faults or fault zones that must be characterized because their: (i) age of displacement, (ii) location with respect to the repository, (iii) length, (iv) orientation, or (v) historic seismicity indicate activity that could affect repository design or performance. Faults classified as Type I must be considered for detailed investigation to fully characterize them and assess their potential effects on the repository. Type I faults include faults within the controlled area which have demonstrable Quaternary (<2.0 m.y.) displacement. Outside the controlled area, Type I faults must show evidence of Quaternary displacement and be of sufficient length, have a location, or orientation to potentially affect the repository or be seismically active or have a direct (i.e., branching relationship) with an active fault.

Based on current information, Type III faults will not affect repository design or performance. Type III faults include faults that are located outside the faulting component; within the faulting component but are of insufficient length or have a location or orientation that would not affect repository design or performance; experienced most-recent displacement prior to the Quaternary; are unfavorably oriented in current stress field for displacement; or are demonstrably inactive seismically.

Type II faults are those faults that require additional characterization to determine whether their location, length, orientation, age of displacement, and seismicity will have a potential affect on repository design or performance. Faults classified as Type II require additional investigations to determine if they should be subsequently classified Type I or Type III faults for design and performance assessment. For the purposes of this screening study all faults are designated either Type II or Type III faults. It is recognized that many Type II faults may be classified in a subsequent study as Type I faults.

2.2 FAULT CLASSIFICATION APPROACH

The NRC approach to fault classification is given in NUREG-1451 (Figure 1). The first step is identification of the region to be investigated. That is done in Section 2.4 of this report. The second step is to screen fault populations and identify faults which meet screening criteria and, therefore, require extra investigation. This second step distinguishes Type III faults from Types I and II faults. For this study, all non Type III faults so identified are classified as Type II faults. The further separation of Type II faults into Type I and Type III will be accomplished in a subsequent study. NUREG-1451 recognized that analysis of fault displacement is necessarily an iterative process, because of accumulation of new data and understanding of tectonic processes, and that the classification of Type III faults should be subject to periodic re-evaluation.

2.3 DATA SOURCES

To classify faults according to the system described in NUREG-1451, Quaternary faults from three individual fault coverages were used. Regional coverage, out to 100 km, was provided by the map of Nakata et al. (1982) (Figure 2). This map coverage is at a scale of 1:2,500,000 and provides coverage for both the Basin and Range and the Rio Grande Rift provinces (Martin, 1995). Because of the scale, only major faults, generally in excess of 5 km, are shown. In addition, only faults known in 1982 to have experienced Quaternary displacement are included on the map. Thus, faults identified and characterized through YM site characterization efforts are not included because the results of this characterization effort for regional faults is still undergoing technical review and is not available electronically. Some geological interpretation of the electronic map was done to link segments of faults in order to maximize their length and thus their potential to be classified as Type II faults. For example, short segments of the Rock Valley

fault were linked together to give single segment with a total length of 65 km. This conservative approach assures that the most prudent fault coverage was used in this first phase of analysis.

Local map coverage, around YM, was provided by Simonds et al. (1995) (Figure 3). This map was received in electronic format from the U.S. Geological Survey. Editing of the map was required to link segments of faults together separated by small offsets (i.e., 1-10 m). These separations resulted from the original digitization process and are not evident on the hard copy of the map, but show up in the electronic version. However, fault-digitization gaps in effect artificially reduce electronically determined fault lengths. This effect can be significant. In addition, some geologic interpretation of the map was done to link distinct segments of the same fault together to maximize their length. In addition, to allow ARC/INFO to unambiguously analyze the fault data, shorter branches of branching faults were electronically disconnected from the longer portion. If a short branch is electronically selected as the point of closest approach the associated length could be unrepresentatively short, resulting in misclassification of the fault. The electronic fault length is a function of the digitization procedure and is usually unknown. Nine faults extended beyond Simonds et al. (1995) map to the north and two to the south (Figure 3). The electronic coverage of Frizzell and Shulters (1990) was used to extend these specific faults beyond the Simonds et al. (1995) coverage to their mapped termination. Data acquired in this present study from maps of Nakata et al. (1982) and Simonds et al. (1995) were transferred into a spreadsheet in electronic format. These data were used to generate peak acceleration for each fault, based on fault length and closest approach of the fault to the repository using published scaling relations (Campbell, 1987). Additionally, screened faults of Nakata et al. (1982) and Simonds et al. (1995) were transferred electronically into the 3DSTRESS code (Ferrill, et al., 1995a; 1995b; Morris et al., 1996) for slip-tendency analysis. Faults remaining following the slip-tendency analysis are considered Type II faults.

The third fault coverage data set is textual data from Piety (1995). The maps that accompanied Piety's report are undergoing review and correction and are not available electronically. This suggests that textual data is also preliminary and subject to change. However, it provides coverage at an intermediate scale and provides a check on the other two coverages. Conclusions about faults in this coverage should also be considered preliminary and reanalysis should be performed once Piety's data is finalized. For this coverage, fault lengths and closest approach data were entered directly into a spreadsheet. Because electronic versions of Piety's maps are unavailable, slip-tendency analysis was not done on those faults.

2.4 IDENTIFICATION OF THE FAULTING COMPONENT OF THE GEOLOGIC SETTING

In NUREG-1451 the Geologic Setting is defined as consisting of three systems, the geologic, hydrologic and geochemical systems (NUREG-1451, Figure 2). The geologic system is subdivided into faulting, seismicity, volcanism, geomorphic, stratigraphic, and natural resources components (NUREG-1451, Figure 2). For the purposes of this report the faulting component is considered to extend out 100 km radially from the center of the repository [548371 m, 407744 m; Universal Transverse Mercator (UTM) coordinates] as shown in Figure 2. The area selected for the fault component is not unique and could be chosen differently in future analyses. Once the faulting component was defined, faults within it were screened. Those not meeting the Type III criteria are considered Type II faults.

2.5 FAULT LENGTH ANALYSIS

The peak acceleration at the center of the repository projected to the surface was used as the screening tool for fault length. Peak acceleration is a function of the magnitude of an earthquake and the distance of the rupture from the repository. The empirical relationship between maximum moment magnitude of a potential earthquake and surface rupture length have been most recently refined by Wells and Coppersmith (1994), who developed a median relationship through available observations. Maximum moment magnitude is the size of the largest possible earthquake given the length of the fault and can be estimated using the following equation from Wells and Coppersmith (1994):

$$M = 5.08 + 1.16 * \log L, \quad (\text{Eq. 1})$$

where M = magnitude and L is the length of the fault.

In their Probabilistic Seismic Hazard Analysis (PSHA) study of the exploratory studies facility (ESF) (Quittmeyer, 1994; Wong, et al., 1995) the DOE used magnitude $M = 6.25$ as the threshold value for distinguishing between earthquakes that occur on known faults (their fault-source term) and those that occur randomly or on unidentified faults (their area source term). This threshold is based on observations by (Smith and Arabasz, 1991) that $M \leq 6.0 - 6.5$ do not produce surface ruptures in the Basin and Range tectonic province. However, the Basin and Range earthquakes of this magnitude range lie on known faults and fault trends. Smaller-magnitude earthquakes ($M = 5.7 - M = 6.0$) can also produce surface rupture if they happen to have a shallow earthquake focus. Wells and Coppersmith (1994) concluded their regression statistics can be used below $M = 6.0$ and include several well-studied surface rupturing earthquakes of magnitude < 6.0 in their database. Hofmann and Ibrahim (1995) suggest a magnitude $M = 5.7$ as the lower limit to be assigned to individual faults and smaller magnitudes be allowed to occur randomly. Consistent with the preliminary nature of this study, a slightly more conservative value of 5.6 was used for the maximum moment magnitude for faults to be considered for fault-source term. Using the more conservative value and (Eq. 1) magnitude 5.6 earthquakes occur on faults with a mean length of slightly less than 4 km and have displacements of approximately 0.05×10^{-1} m (Wells and Coppersmith, 1994). Therefore, in this study all faults capable of producing $M < 5.6$ earthquakes (i.e., fault < 4 km in length) were excluded from further consideration.

From magnitude (M) and distance to the fault, the median acceleration at the center (surface) of the repository is calculated from the attenuation formula, (Eq. 2) which is based on equation 5 of Campbell (1987). The first term is modified as required by the acceleration in the free field, constrained by far field recording as outlined in Tables 4 and 5 of Campbell (1987).

$$\ln A = (-2.893 + (0.85M) - 1.25 \ln((r^2 + 16)^{1/2} + 0.0872e^{0.0678M}) - 0.059r)(1.12), \quad (\text{Eq. 2})$$

where A is peak acceleration, M is magnitude from (Eq. 1), and r is the closest approach of the fault to the center of the repository at the surface. Distance $((r^2 + 16)^{1/2})$ is modified in this equation to represent distance from the repository to a depth of 4 km on all faults. Four km is the shallowest depth at which peak acceleration can be generated (Campbell, 1987). To perform these calculations a table, for each electronic coverage, containing the fault length and closest approach, was exported into an Excel spreadsheet from the GIS database. After completion of the calculation the data were imported back into

the GIS database for screening of faults. NUREG-1451 indicates "...an acceleration value of 0.1 g as a valid discriminator to determine the scope of investigation to be undertaken, or the type of information to be gathered. . . ." To compensate for the closest approach distance being calculated from the fault to the center of the repository, rather than the boundary of the repository, 0.09 g, rather than 0.1 g, was used as the screening criterion. All faults with an acceleration below 0.09 g were classified as Type III faults and deleted from the maps (Figures 4 and 5). On the Nakata et al. (1982) map there are 9 faults with potential accelerations equal to or greater than 0.09 g. On Simonds' et al. (1995) map 28 faults remained after the 0.09 g criterion was applied.

Piety (1995) data were sorted and screened in the Excel program. Using the data from Piety (1995) and applying the same screening criteria, 32 faults were selected. They are listed in Table 2. The faults not selected are listed in Appendix B. All the faults selected from the Nakata (et al., 1982) coverage were also selected from the Piety (1995) data. The fault directly south of the controlled area boundary (Figure 4), is considered part of the Rock Valley fault system by Piety (1995), judging by the 65 km length attributed to it. In either interpretation the Rock Valley fault may be capable of generating greater than 0.09 g acceleration at YM and is therefore a Type II fault. Seven of 28 faults in the Simonds et al. (1995) coverage overlapped with the Piety (1995) coverage.

2.6 FAULT ORIENTATION ANALYSIS

The relative tendency of a fault to slip in a given *in situ* stress field is dependent on the magnitude of the principal stresses and orientation of the fault relative to the orientation of the three principal stress axes (Ferrill, et al., 1995a; 1995b; Morris et al., 1996). Slip-tendency analysis (Morris, et al., 1996) was used as a screening tool to evaluate the effect of orientation on fault type. The *in situ* stress state at YM (Morris, et al. 1996) is based on measurements of Stock et al. (1985). Maximum principal compressive stress (σ_1) = vertical = 90 MPa; intermediate principal compressive (σ_2) = N 28°E = 65 MPa; and minimum principal compressive stress (σ_3) = N 62° W = 25 MPa. Stock et al. (1985) measured *in situ* stress at depths of 1 and 1.3 km. Morris et al. (1996) extrapolated the data to 5 km. Because the western part of the regional fault coverage, which includes the Death Valley—Furnace Creek fault system, is in a region with a different stress field orientation (Zoback, 1992), a second slip-tendency analysis was required. This second analysis was identical to the first but with σ_2 =NS and σ_3 =EW (Morris et al., 1996).

The slip-tendency based screening criterion is the ratio of the maximum slip-tendency of the fault to the maximum slip-tendency for any fault in the specified stress field. For this study, faults with slip tendencies greater than 50 percent of maximum slip-tendency were taken as potentially significant and assigned as Type II faults. The 0.50 slip-tendency criterion was empirically chosen to eliminate only those faults that are nearly perpendicular to σ_2 , the intermediate principal compressive stress (i.e., the maximum horizontal compressive stress) such as the Yucca Wash, Severe Wash, and Pagany Wash faults on the coverage of Simonds et al. (1995). However, because of the length and location of these faults and the state-of-the-art of slip-tendency analysis, it was decided to include these faults as Type II faults in this initial classification. On the coverage of Nakata of et al. (1982), no faults were eliminated based on slip-tendency analysis. In order to perform the slip-tendency analysis, it was necessary to export the faults screened for peak acceleration to the 3DSTRESS software. Results of slip-tendency analysis were not imported back into the ARC/INFO program, but were plotted directly as Figures 6, 7, and 8. As noted above, faults from the Piety (1995) coverage were not included in the slip-tendency analysis.

2.7 AGE OF FAULT DISPLACEMENT ANALYSIS

Maps and databases used in the present study contain only Quaternary faults (Nakata et al., 1982; Simonds et al., 1995; and Piety, 1995). Therefore, all faults in the present analysis meet the criterion of Quaternary displacement.

2.8 SEISMIC ACTIVITY ANALYSIS

The YMR is temporally and spatially in a period and region of low strain rate (Swan, 1995). As a result, microseismicity does not correlate well with most faults in the YMR (Rodgers et al., 1987). This poor correlation results from the relatively low seismicity, combined with poorly constrained hypocenters and a poorly defined complex subsurface geology.

For most faults, fault dips are only known at the surface. Tectonic models can provide an indication of dip. However, the downward projection of faults more than several hundred meters can result in substantial error in position of the fault plane at depths of several km. In addition, the depths of most earthquakes, especially small magnitude earthquakes, are poorly constrained. Poorly constrained positions of fault planes and poorly constrained vertical positions of earthquakes result in a large uncertainty when trying to correlate earthquakes with known faults. Rodgers et al. (1987) reported that the hypocenters of small earthquakes appear to occur in cylinders. Hofmann (1994) suggested that these zones may reflect intersections of fault planes, further complicating the assignment of seismicity to known faults.

A third complicating factor is the presence of blind faults (i.e., those with no surface expression) (Arabasz et al., 1992; Harmsen, 1994). Seismic events on these faults result in background seismic noise that is nearly impossible to clarify, especially for small random events. As a result, absence of seismicity along a fault cannot be used to screen Type III from Type II faults.

2.9 RESULTS

Two digital map coverages in the CNWRA electronic GIS database and one textual coverage of Quaternary faults within 100 km of YM were analyzed in order to identify and screen Type III faults in the YMR. The most effective screening criteria were peak acceleration, which is a function of fault length and closest approach of the fault, and slip-tendency, which is a function of the fault orientation and the *in situ* stress state. Other generic criteria recommended in NUREG-1451, such as age of last displacement and seismicity, were ineffective in screening the fault population in the YMR. All faults in the three coverages were considered to be Quaternary by their authors. Historic seismic activity in the area is minimal, diffuse, and, consequently, nondefinitive in screening faults. After screening, 54 faults of the estimated more than 400 present in the three coverages, were identified as Type II faults (Table 3). If Piety's (1995) coverage were included in the slip-tendency analysis the number of faults may decrease further.

The use of the CNWRA GIS database in the manner described in this report is new and broadens the use of the software. Several comments need to be made regarding this utilization. Before using data in the GIS database, it needs to be carefully reviewed. Data which had been used many times in the past for visual comparative analyses and preparation of graphics, were found to not be suitable for quantitative analysis. Specifically, small gaps in the digitized faults caused inaccurate results when fault

lengths were queried. Thus, a necessary first step in this study was to edit these small digitizing errors from the data. In addition, because the goal was to identify Type II faults based on peak acceleration, it was necessary to determine the maximum length of the faults. This required linking fault segments together based on geologic interpretation of the maps.

Both peak acceleration and the slip-tendency are parameters derived from primary data in the GIS database (i.e., fault length and orientation). The success of electronic screening of faults using ARC/INFO, 3DSTRESS, and Excel illustrate the usefulness of such an integrated approach in future analyses of faults.

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4 ACKNOWLEDGEMENTS

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This study required the application of several different computer techniques and procedures. Without the excellent cooperation of a number of CNWRA staff, this study could not have been completed. R. Martin not only processed the fault map data, but was also instrumental in providing guidance in the use and pitfalls of ARC/INFO. P. Maldonado used Excel to calculate moment magnitudes and peak accelerations. R. Hofmann provided the peak acceleration formula and guidance in its use. E. Cantu prepared the spreadsheet from the Piety (1995) report and prepared the final draft of this report. B. Henderson applied the 3DSTRESS code to the data for the slip-tendency analysis and prepared some of the figures.

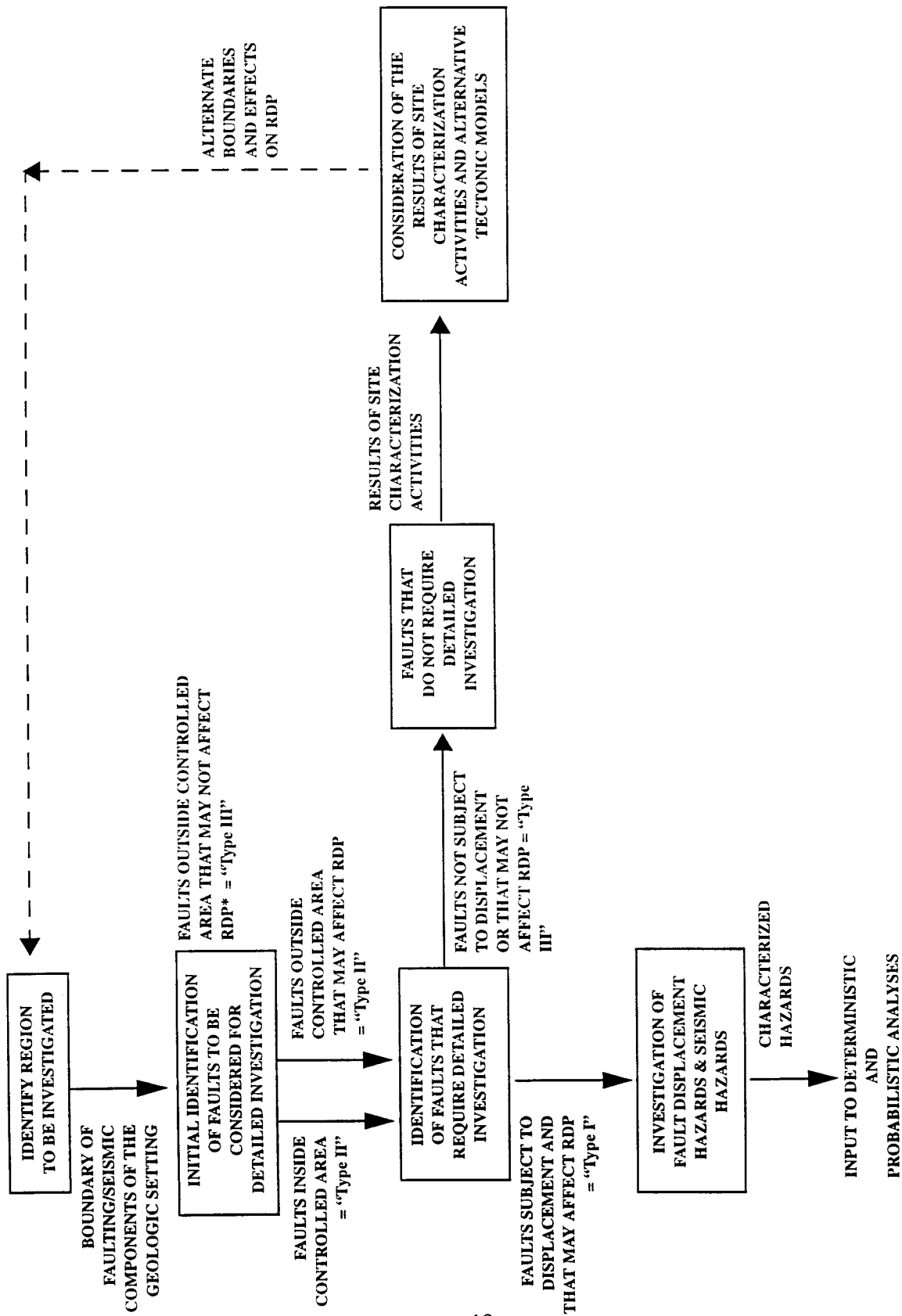


Figure 1. Example of an acceptable approach to the identification of fault displacement hazards and seismic hazards (after McConnell et al., 1992).

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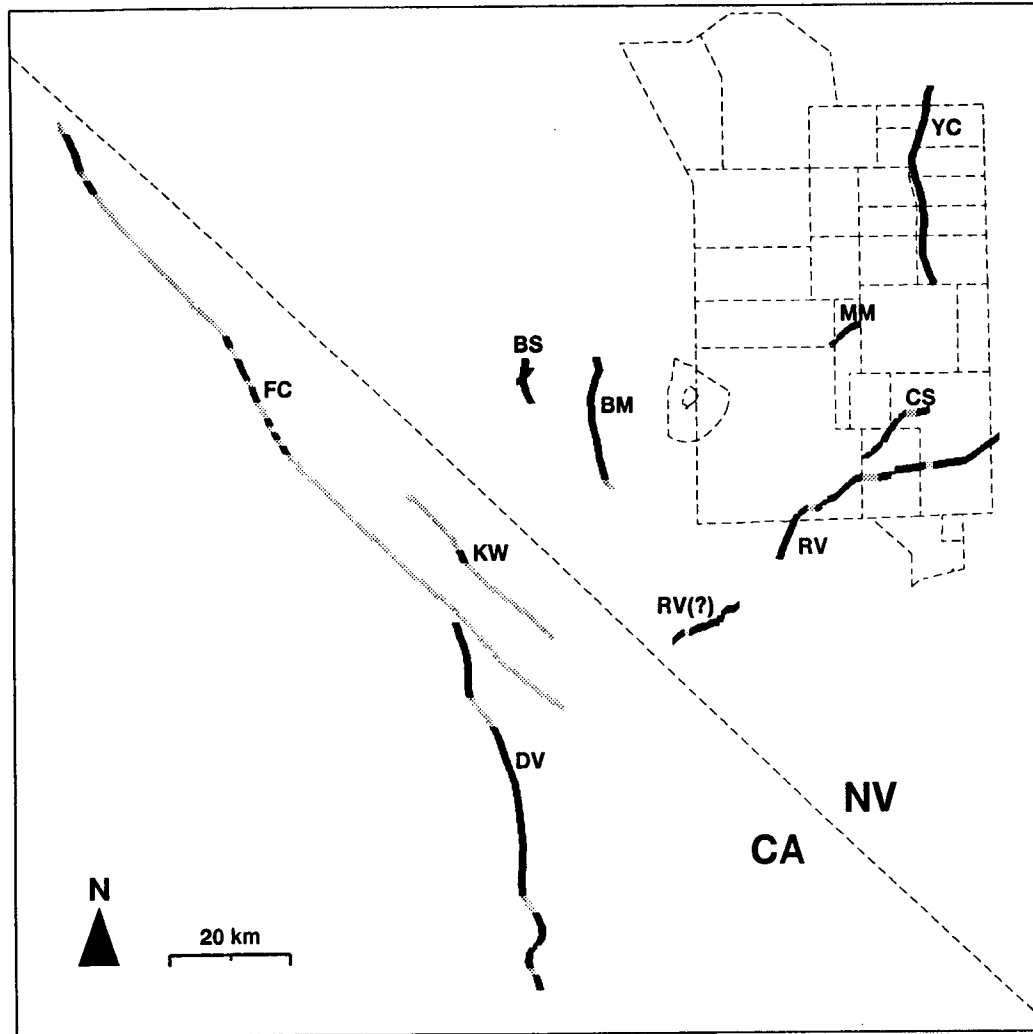


Figure 6. Results of slip-tendency analysis on faults from Nakata et al. (1982), with σ_2 oriented N 28°E. This orientation applies to all faults shown in Nevada. In the present analysis, all faults shown in Nevada have a slip-tendency ratio greater than 0.50 (indicated by solid black lines) and are classified as Type II faults. Fault names for abbreviations are given in Appendix A.

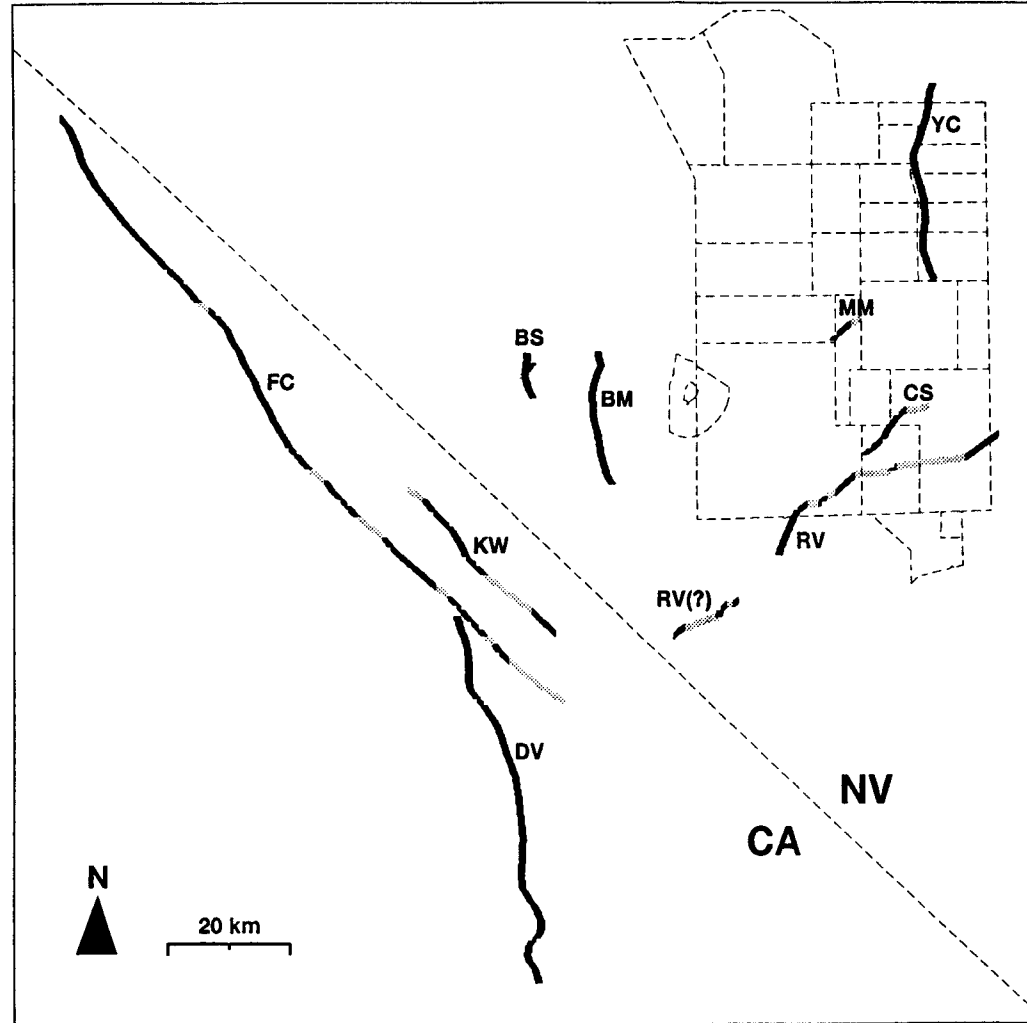


Figure 7. Results of slip-tendency analysis on faults from Nakata et al. (1982) coverage. In model stress field σ_2 is oriented north-south, to approximate stress state in eastern California shear zone (Zoback, 1992) and is applicable to faults shown in CA. Black faults have a slip-tendency ratio of greater than 0.50 and are more likely to slip than faults shown in gray. All faults in the area where a N-S stress field is assumed (CA) have a slip-tendency greater than 0.50 and are classified as Type II faults. Fault names for abbreviations are given in Appendix A.

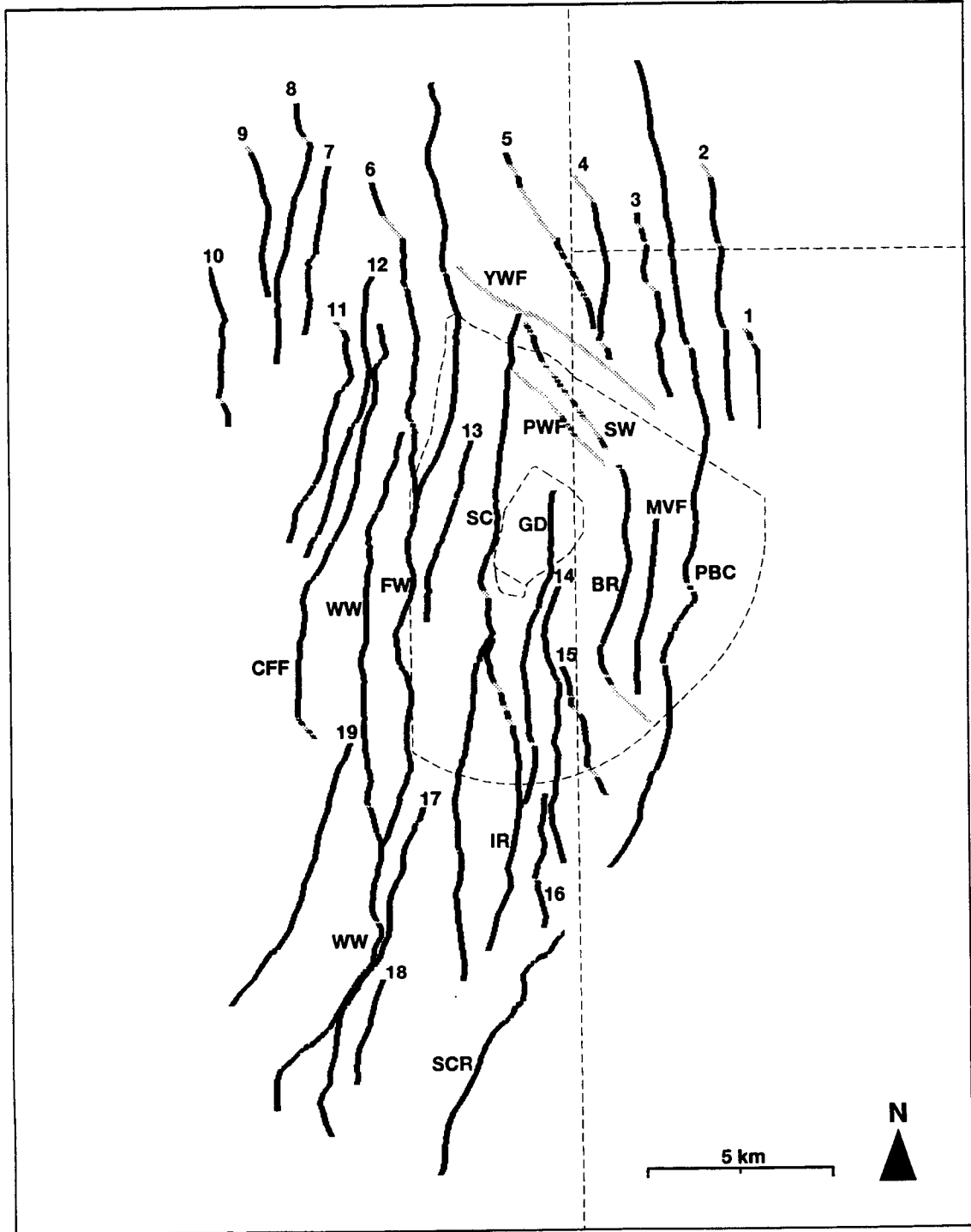


Figure 8. Results of slip-tendency analysis on fault coverage from Simonds et al. (1995). Black faults have a slip-tendency ratio of greater than 0.50 and are more likely to slip than gray faults with a slip-tendency ratio of less than 0.50. Gray faults (PWF, YWF) have a low slip-tendency, but are considered Type I faults. Fault names for abbreviations are given in Appendix A.

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Table 1. Description of fault type and criteria for their classification based on NUREG-1451 (McConnell et al., 1992)

Fault Type	Criteria
<p>Type I - Faults which could affect repository design or performance and must be characterized to determine consequence of displacement.</p>	<ol style="list-style-type: none"> 1. Faults or fault zones within the controlled area⁽¹⁾ that are or could be subject to displacement as demonstrated by evidence of Quaternary displacement (< 2.0 m.y.). 2. Fault or faults outside the controlled area, but within the faulting component,⁽²⁾ of sufficient length and location that they may affect repository design and/or performance. 3. Favorably oriented in the current stress field for fault displacement. Seismically active. Have a direct relationship with an active fault.
<p>Type II - Faults for which there is a high degree of uncertainty as to their possible affects on the repository. Further studies or characterization need to determine whether fault meets Type I criteria or not.</p>	<ol style="list-style-type: none"> 1. Faults or fault zones outside the controlled area, but within the faulting component, that are of sufficient length and located such that they may affect repository design and/or performance 2. Evidence of displacement in the last 2 m.y.
<p>Type III - Faults which will not, based on current information, affect repository design or performance.</p>	<ol style="list-style-type: none"> 1. Faults outside of faulting component. 2. Faults or fault zones located within the faulting component of insufficient length and orientation such that displacement along them could not affect repository design or performance. 3. Displacement demonstrably not Quaternary or younger. 4. Unfavorably oriented in current stress field for fault displacement. 5. Demonstrably seismically inactive.

(1) "Controlled" area means a surface location, to be marked by suitable monuments, extending horizontally no more than 10 km in any direction from the outer boundary of the underground facility.

(2) "Faulting Component" means that portion of the earth's crust that needs to be investigated to encompass those faults that might have an effect on repository design and/or performance or provide significant input into models used to assess repository performance due to fault displacement.

Table 2. List of faults with potential to generate an earthquake greater than or equal to 0.09g from Piety (1995). Fault names for abbreviations are given in Appendix A.

Fault Name	Closest Approach (km)	Length (Max) (km)	Magnitude	Peak Acceleration
AM	34	60	7.14	0.19
AR	40	15	6.44	0.10
BLR	55	54	7.09	0.10
BM	14	15.5	6.46	0.30
BR	1	10	6.24	0.69
BS	26	25	6.70	0.19
CB	43	30	6.79	0.11
CS	36	27	6.74	0.13
DV	55	104	7.42	0.12
ER	37	13	6.37	0.10
FC	50	170	7.67	0.17
FW	2	7.5	6.10	0.62
GD	0	9	6.19	0.69
KR	57	84	7.31	0.11
KW	43	25	6.70	0.10
MM	19	27	6.74	0.27
OSV	24	16	6.48	0.18
PBC	3	25	6.70	0.72
PRP	70	130	7.53	0.10
PVNH	46	26	6.72	0.10
RV	27	65	7.18	0.25
RWBW	19	17	6.51	0.23
SC	0.5	12	6.33	0.72
SCR	10	31	6.81	0.46
SF	52	51	7.06	0.10

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Table 2. List of faults with potential to generate an earthquake greater than or equal to 0.09g from Piety (1995). Fault names for abbreviations are given in Appendix A. (Cont'd)

Fault Name	Closest Approach (km)	Length (Max) (km)	Magnitude	Peak Acceleration
TOL	42	22	6.64	0.10
WAH	22	15	6.44	0.19
WSM	53	60	7.14	0.11
WW	3	25	6.70	0.72
YC	40	40	6.94	0.13
YCL	36	17	6.51	0.11

Table 3. List of Type II faults within 100 km of proposed repository at Yucca Mountain

No.	Fault Name
Nakata et al. (1982) - Regional Coverage	
1	Bare Mountain Fault (P)
2	Beatty Scarp Fault (P)
3	Cane Springs Fault (P)
4	Death Valley Fault
5	Furnace Creek Fault (P)
6	Keane Wonder Fault (P)
7	Mine Mountain Fault (P)
8	Rock Valley Fault (P)
9	Yucca Fault (P)
Simonds et al. (1995) - Local Coverage	
10	Bow Ridge Fault (P)
11	Crater Flat Fault (P - East Crater Flat Fault of Piety)
12	Fatigue Wash Fault (P)
13	Ghost Dance Fault (P)
14	Iron Ridge Fault
15	Paintbrush Canyon Fault (P)
16	Pagany Wash Fault (P)
17	Severe Wash Fault (P)
18	Stage Coach Road Fault (P)
19	Solitario Canyon Fault (P)
20	Windy Wash Fault (P)
21	1
22	2
23	3
24	4
25	5
26	6

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Table 3. List of Type II faults within 100 km of proposed repository at Yucca Mountain (Cont'd)

No.	Fault Name
27	7
28	8
29	9
30	10
31	11
32	12
33	13
34	14
35	15
36	16
37	17
38	18
39	19
Piety (1995) Regional Coverage	
40	Ash Meadows Fault
41	Amargosa River Fault
42	Belted Range Fault
43	Carpetbag Fault
44	Eleana Range Fault
45	Kawich Range
46	Oasis Valley Fault
47	Pahrump Fault
48	Plutonium Valley - North Halfpint Range Fault
49	Rocket Wash - Beatty Wash Fault
50	Sarcobatus Flat Fault
51	Tolicha Peak Fault
52	Wahmonie Fault
53	West Spring Mountain Fault

Table 3. List of Type II faults within 100 km of proposed repository at Yucca Mountain (Cont'd)

No.	Fault Name
54	Yucca Lake Fault

(P) Indicates overlap with Piety (1995) coverage. Simonds numbered faults correspond with the numbers on Figure 8.

APPENDIX A

LIST OF FAULTS AND ABBREVIATIONS FROM PIETY (1995)

εt/bc

Fault Name	Fault Abbreviation
Airport Lake Fault	AIR
Amargosa River Fault	AR
Area Three Fault	AT
Ash Hill Fault	AH
Ash Meadows Fault	AM
Badger Wash Faults	BDG
Bare Mountain Fault	BM
Beatty Scarp	BS
Belted Range Fault	BLR
Bonnie Claire Fault	BC
Boundary Fault	BD
Bow Ridge Fault	BR
Bullfrog Hills Faults	BUL
Buried Hills Fault	BH
Cactus Flat Fault	CF
Cactus Flat—Mellan Fault	CFML
Cactus Range—Wellington Hills Fault	CRWH
Cactus Springs Fault	CAC
Cane Spring Fault	CS
Carpetbag Fault	CB
Cedar Mountain Fault	CM
Central Pintwater Range Faults	CPR
Central Reveille Fault	CR
Central Spring Mountains Faults	CSM
Chalk Mountain Fault	CLK
Checkpoint Pass Fault	CP
Chert Ridge Faults	CHR
Chicago Valley Faults	CHV

Fault Name	Fault Abbreviation
Clayton—Montezuma Valley Fault	CLMV
Clayton Ridge—Paymaster Ridge Fault	CRPR
Clayton Valley Fault	CV
Cockeyed Ridge—Papoose Lake Fault	CRPL
Crater Flat Fault*	CFF
Crossgrain Valley Fault	CGV
Death Valley Fault	DV
Deep Springs Fault	DS
East Belted Range Fault	EBR
East Crater Flat Faults	ECR
East Magruder Mountain Fault	EMM
East Nopah Fault	EN
East Pintwater Range Fault	EPR
East Reveille Fault	ERV
East Stone Cabin Fault	ESC
Eleana Range Fault	ER
Emigrant Fault	EM
Emigrant Peak Faults	EPK
Emigrant Valley North Fault	EVN
Emigrant Valley South Fault	EVS
Eureka Valley East Fault	EURE
Eureka Valley West Fault	EURW
Fallout Hills Faults	FH
Fatigue Wash Fault	FW
Fish Lake Valley Fault	FLV
Freiburg Fault	FR
Frenchman Mountain Fault	FM
Furnace Creek Fault	FC

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Fault Name	Fault Abbreviation
Garden Valley Fault	GRD
General Thomas Hills Fault	GTH
Ghost Dance Fault	GD
Gold Flat Fault	GOL
Gold Mountain Fault	GOM
Golden Gate Faults	GG
Grapevine Fault	GV
Grapevine Mountains Fault	GM
Groom Range Central Fault	GRC
Groom Range East Fault	GRE
Hidden Valley—Sand Flat Faults	HVSF
Hiko Fault	HKO
Hiko—South Pahroc Faults	HSP
Hot Creek—Reveille Fault	HCR
Hunter Mountain Fault	HM
Indian Springs Valley Fault	ISV
Iron Ridge Fault*	IR
Jumbled Hills Fault	JUM
Kawich Range Fault	KR
Kawich Valley Fault	KV
Keane Wonder Fault	KW
La Madre Fault	LMD
Lee Flat Fault	LEE
Lida Valley Faults	LV
Little Lake Fault	LL
Lone Mountain Fault	LMT
McAfee Canyon Fault	MAC
Midway Valley Fault*	MVF

Fault Name	Fault Abbreviation
Mine Mountain Fault	MM
Monitor Hills East Fault	MHE
Monitor Hills West Fault	MHW
Monotony Valley Fault	MV
Montezuma Range Fault	MR
Mud Lake—Goldfield Hills Fault	MLGH
North Desert Range Fault	NDR
Oak Spring Butte Faults	OAK
Oasis Valley Faults	OSV
Owens Valley Faults	OWV
Pagany Wash Fault*	PWF
Pahranagat Fault	PGT
Pahroc Fault	PAH
Pahrock Valley Faults	PV
Pahrump Fault	PRP
Pahute Mesa Faults	PM
Paintbrush Canyon Fault	PBC
Palmetto Mountains—Jackson Wash Fault	PMJW
Palmetto Wash Fault	PW
Panamint Valley Fault	PAN
Penoyer Fault	PEN
Plutonium Valley—North Halfpint Range Fault	PVNH
Quinn Canyon Fault	QC
Racetrack Valley Faults	RTV
Ranger Mountains Faults	RM
Rock Valley Fault	RV
Rocket Wash—Beatty Wash Fault	RWBW
Saline Valley Faults	SAL

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Fault Name	Fault Abbreviation
Sarcobatus Flat Fault	SF
Seaman Pass Fault	SPS
Severe Wash Fault*	SW
Sheep Basin Fault	SB
Sheep—East Desert Ranges Fault	SEDR
Sheep Range Fault	SHR
Sierra Nevada Fault	SNV
Silver Peak Range Faults	SIL
Six-Mile Flat Fault	SMF
Slate Ridge Faults	SL
Solitario Canyon Fault	SC
South Ridge Faults	SOU
Southeast Coal Valley Fault	SCV
Southern Death Valley Fault	SDV
Spotted Range Faults	SPR
Stagecoach Road Fault	SCR
State Line Fault	SL
Stonewall Flat Fault	SWF
Stonewall Mountain Fault	SWM
Stumble Fault	STM
Sylvania Mountains Fault	SYL
Tem Piute Fault	TEM
Three Lakes Valley Fault	TLV
Tikaboo Fault	TK
Tin Mountain Fault	TM
Tolicha Peak Fault	TOL
Towne Pass Fault	TP
Tule Canyon Fault	TLC

Fault Name	Fault Abbreviation
Wahmonie Fault	WAH
Weepah Hills Fault	WH
West Pintwater Range Fault	WPR
West Railroad Fault	WR
West Spring Mountains Fault	WSM
Wilson Canyon Fault	WIL
Windy Wash Fault	WW
Yucca Fault	YC
Yucca Lake Fault	YCL
Yucca Wash Fault*	YWF

* Faults from Simonds et al. (1995)

APPENDIX B

**FAULTS FROM PIETY (1995) THAT PROBABLY
LACK THE POTENTIAL TO GENERATE PEAK ACCELERATION
AT YUCCA MOUNTAIN GREATER THAN 0.09 G
(FAULT ABBREVIATIONS GIVEN IN APPENDIX A)**

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Fault Name	Closest Approach (km)	Length (Max) (km)	Magnitude	Peak Acceleration
AH	105	45	7.00	0.03
AIR	138	60	7.14	0.02
AT	44	5.2	5.91	0.06
BC	74	27	6.74	0.05
BD	51	6.5	6.02	0.05
BDG	111	13	6.37	0.02
BH	53	26	6.72	0.08
BUL	38	7	6.06	0.08
CAC	59	12	6.33	0.05
CF	84	50	7.05	0.05
CFML	80	35	6.87	0.05
CGV	48	8.5	6.16	0.06
CHR	65	14	6.41	0.05
CHV	90	20	6.59	0.03
CLK	87	20	6.59	0.03
CLMV	126	14	6.41	0.02
CM	200	60	7.14	0.01
CP	44	6.5	6.02	0.06
CPR	79	16	6.48	0.04
CR	108	29	6.78	0.03
CRPL	53	21	6.61	0.07
CRPR	126	53	7.08	0.03
CRWH	87	29	6.78	0.04
CSM	76	16	6.48	0.04
CV	132	27	6.74	0.02
DS	148	27	6.74	0.01
EBR	80	26	6.72	0.04

Fault Name	Closest Approach (km)	Length (Max) (km)	Magnitude	Peak Acceleration
EM	73	13	6.37	0.04
EMM	113	7	6.06	0.01
EN	85	19	6.56	0.03
EPK	166	26	6.72	0.01
EPR	81	58	7.13	0.06
ERV	112	22	6.64	0.02
ESC	115	35	6.87	0.03
EURE	110	50	7.05	0.03
EURW	140	22	6.64	0.01
EVN	60	28	6.76	0.07
EVS	66	20	6.59	0.05
FH	70	8	6.13	0.03
FLV	135	80	7.29	0.03
FM	146	20	6.59	0.01
FR	133	19	6.56	0.02
GG	144	24	6.68	0.01
GM	67	23	6.66	0.05
GOL	65	16	6.48	0.05
GOM	90	18	6.54	0.03
GRC	82	31	6.81	0.04
GRD	126	12	6.33	0.01
GRE	85	20	6.59	0.04
GTH	137	26	6.72	0.02
GV	58	30	6.79	0.07
HCR	103	83	7.31	0.04
HKO	131	47	7.02	0.02
HM	95	85	7.32	0.05

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Fault Name	Closest Approach (km)	Length (Max) (km)	Magnitude	Peak Acceleration
HSP	130	27	6.74	0.02
HVSF	87	13	6.37	0.03
ISV	67	28	6.76	0.06
JUM	77	27	6.74	0.05
KV	61	43	6.97	0.08
LEE	113	7	6.06	0.01
LL	163	30	6.79	0.01
LMD	82	33	6.84	0.05
LMT	165	70	7.22	0.02
LV	115	10	6.24	0.02
MAC	155	17	6.51	0.01
MER	48	10	6.24	0.06
MHE	125	8	6.13	0.01
MHW	124	15	6.44	0.02
MLGH	113	33	6.84	0.03
MR	121	33	6.84	0.02
MV	103	5.5	5.94	0.02
NDR	61	24	6.68	0.06
OAK	57	21	6.61	0.07
OWV	126	110	7.45	0.03
PAH	144	74	7.25	0.02
PAN	95	80	7.29	0.05
PEN	97	56	7.11	0.04
PGT	106	45	7.00	0.03
PM	48	9	6.19	0.06
PMJW	112	12	6.33	0.02
PV	155	11	6.29	0.01

Fault Name	Closest Approach (km)	Length (Max) (km)	Magnitude	Peak Acceleration
PW	131	16	6.48	0.01
QC	127	19	6.56	0.02
RM	49	5	5.89	0.05
RTV	97	22	6.64	0.03
SAL	108	21	6.61	0.02
SB	112	47	7.02	0.03
SCV	132	19	6.56	0.02
SDV	105	300	7.95	0.07
SEDR	104	45	7.00	0.03
SHR	122	50	7.05	0.03
SIL	142	24	6.68	0.01
SL	130	32	6.83	0.02
SLR	87	24	6.68	0.04
SMF	138	24	6.68	0.02
SNV	154	25	6.70	0.01
SOU	55	19	6.56	0.07
SPR	59	20	6.59	0.06
SPS	153	34	6.86	0.01
STM	74	33	6.84	0.05
SWF	101	22	6.64	0.03
SWM	92	22	6.64	0.03
SYL	111	14	6.41	0.02
TEM	101	22	6.64	0.03
TK	92	33	6.84	0.04
TLC	104	14	6.41	0.02
TLV	84	27	6.74	0.04
TM	90	29	6.78	0.04

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Fault Name	Closest Approach (km)	Length (Max) (km)	Magnitude	Peak Acceleration
TP	76	38	6.91	0.05
WH	145	15	6.44	0.01
WIL	140	42	6.96	0.02
WPR	76	60	7.14	0.06
WR	112	42	6.96	0.03