Shared Services Group P.O. Box 3707 Seattle, WA 98124-2207

November 19, 2002 G9704-SSG-012

### DOCUMENT CONTROL DESK UNITED STATES NUCLEAR REGULATORY COMMISSION WASHINGTON, D.C. 20555



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Reference: a) Boeing Letter G-1151-RSO-92-365 dated August 31, 1992; R.S. Orr to the NRC Operations Center

b) NRC Letter Docket No. 99901227 dated August 12, 1992; L. J. Norrholm to R. S. Orr; Subject: Response to 10 CFR 21 Inquiry

Dear Sir or Madam:

In accordance with the Reference correspondence and 10 CFR 21, Boeing is sending the NRC the attached error notices received from our former software suppliers. Because of unknown current addresses, the following former customers were not notified:

Reactor Controls, Inc Echo Energy Consultants Nuclear Applications and Systems Analysis Company (Japan) Nuclear Power Services GPU Nuclear Corporation Tenera, Inc. Stone & Webster Engineering

Error notices have been sent to our other former customers.

Very truly yours,

Mark S. Snyder Nuclear Administrator Mail Code 7A-43

Enclosures: GT STRUDL Program Report Forms 2002.03 through 2002.05

JE19

GPRF No.: 2002.03 i i i

DATE: 7/24/02

#### FROM: Computer-Aided Structural Engineering Center Georgia Institute of Technology Atlanta, Georgia 30332-0355

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### **SEVERITY LEVEL:**

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- X URGENT Problem results in incorrect answers which may not be apparent or job aborts and cannot be recovered within the session or job.
- Problem results in incorrect answers which are obvious or problem prevents \_ SERIOUS completion of a particular user's task.
- \_ MINOR Problem can be worked around or problem poses high frustration factor.

Documentation error, program usage tip, user inconveniences. \_ INFORMATIVE

Date Problem Confirmed	
Date Notification Sent 7/24/02	
Computers All	

Versions All versions prior to and including Version 26

Target Release for Correction \_\_\_\_ Version 27

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Signature R & D Division

Kenneth Will Typed or Printed Name

Signature **Professional Services Division** 

Unrid C Key Typed or Printed Name

Director ASD Title

7/24/02

Date of Signature

<u>Canture tur Control Managen</u> Title

<u>קאלטז</u> Date of Signature

## GTSTRUDL Program Report Form (Continued)

GPRF No.: 2002.03 DATE: 7/24/02

### DESCRIPTION:

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STIFFNESS ANALYSIS will abort if MEMBER RELEASES and a MEMBER TEMPERATURE LOAD have been specified for a plane or space truss member.

Workaround: Remove the Member Releases for the truss members.

Example:

**TYPE SPACE TRUSS** MEMBER INCIDENCES 27 10 20 .... MEMBER RELEASES 27 START MOM X Y Z END MOM Y Z .... LOADING 1 MEMBER TEMPERATURE LOAD 27 AXIAL 100. Applicable Sections of the Documentation: MEMBER RELEASES Section 2.1.8.2 of Volume 1 of the GTSTRUDL Reference Manual MEMBER TEMPERATURE LOAD Section 2.1.11.4.4 of Volume 1 of the GTSTRUDL Reference Manual STIFFNESS ANALYSIS Section 2.1.13.2 of Volume 1 of the GTSTRUDL Reference Manual

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GPRF No.: 2002 04

DATE: \_\_\_\_\_9/13/2002

#### FROM: Computer-Aided Structural Engineering Center Georgia Institute of Technology Atlanta, Georgia 30332-0355

### SEVERITY LEVEL:

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- X URGENT Problem results in incorrect answers which may not be apparent or job aborts and cannot be recovered within the session or job.
- \_\_ SERIOUS Problem results in incorrect answers which are obvious or problem prevents completion of a particular user's task.
- MINOR Problem can be worked around or problem poses high frustration factor.

\_ INFORMATIVE Documentation error, program usage tip, user inconveniences.

Date Problem Confirmed September 13, 2002

Date Notification Sent

Computers All

Operating System All

Version All

Target Release for Correction Version 26.0

KAW Signature

R & D Division

Michael H. Swanger Typed or Printed Name

Signature **Professional Services Division** 

Typed or Printed Name

Sr. RE Title

2002

Configuration Contol Manager Title

Date of Signature

Rev. 2.2

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GPRF No.: 2002.04

DATE: 9/13/2002

#### **DESCRIPTION:**

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The second and later in a sequence of DYNAMIC ANALYSIS EIGENVALUE, ASSEMBLE FOR DYNAMICS, and DYNAMIC ANALYSIS MODE SUPERPOSITION commands will not reassemble the composite modal damping matrix if the only source of damping is joint damping proportionional to joint inertia. The following sequence of commands illustrates this situation:

INERTIA OF JOINTS WEIGHT 1 TRANS X 75917.46 Y 75917.46 ROTATION Z 1209660318 DAMPING 0.04 2 TRANS X 77064.00 Y 77064.00 ROTATION Z 1287174145 DAMPING 0.04 3 TRANS X 54917.00 Y 54917.00 ROTATION Z 855341667 DAMPING 0.04 4 TRANS X 40988.51 Y 40988.51 ROTATION Z 586281275 DAMPING 0.04 5 TRANS X 50329.18 Y 50329.18 ROTATION Z 716459995 DAMPING 0.04 6 TRANS X 21339.21 Y 21339.21 ROTATION Z 148471761 DAMPING 0.04 EIGEN PARAMETERS SOLVE USING GTLANCZOS NUMBER OF MODES 18 PRINT MAX END \$\$\* \*\* \$\$\* \*\* First DYNAMIC ANALYSIS EIGENVALUE command causing the first composite \$\$\* \*\* modal damping matrix assembly. \$\$\* \*\* DYNAMIC ANALYSIS EIGENVALUE CHANGE INERTIA OF JOINTS WEIGHT 1 DAMPING 0.09 2 DAMPING 0.09 0.09 3 DAMPING 4 DAMPING 0.09 5 DAMPING 0.09 6 DAMPING 0.09 ADD \$\$\* \*\* \$\$\* \*\* Second DYNAMIC ANALYSIS EIGENVALUE command in which the composite modal \$\$\* \*\* damping matrix is erroneously not re-assembled. \$\$\* \*\* DYNAMIC ANALYSIS EIGENVALUE

The only work-around is to break up the problem into separate jobs, where each job

reflects the different composite modal damping data.

## GTSTRUDL User Reference Manual Sections:

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Specification of Damping Properties

Section 2..4.3.4, Volume 3, Rev. M, GTSTRUDL Reference Manual

114

DATE: 9/18/2002

#### Computer-Aided Structural Engineering Center FROM: Georgia Institute of Technology Atlanta, Georgia 30332-0355

### SEVERITY LEVEL:

X_URGENT	Problem results in incorrect answers which may not be apparent or job
	aborts and cannot be recovered within the session or job.

- SERIOUS Problem results in incorrect answers which are obvious or problem prevents completion of a particular user's task.
- Problem can be worked around or problem poses high frustration factor. MINOR

\_ INFORMATIVE Documentation error, program usage tip, user inconveniences.

Date Problem Confirmed September 18, 2002

Date Notification Sent \_\_\_\_\_9/18/200 Z

Computers All

Operating System\_All

Version All

Target Release for Correction Version 27.0

Signature

R & D Division

Michael H. Swanger Typed or Printed Name

Signature **Professional Services Division** 

and G. Ken Typed or Printed Name

Sr. RE Title

<u>Configuratio. Control Manager</u> Title

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GPRF No.: 2002.05

DATE: <u>9/18/2002</u>

#### **DESCRIPTION:**

The CREATE RESPONSE SPECTRUM command will abort if the total number of time points needed to perform the integration for a specified acceleration time history file applied to a specified frequency exceeds 1 million, which is the maximum number of allowable time points. The following CREATE RESPONSE SPECTRUM example illustrates such a case:

```
UNITS CYCLES SECONDS
CREATE RESPONSE SPECTRUM ACCELERATION LINEAR VS FREQUENCY LINEAR
FILE 'LIN-004X'
  FREQUENCY RANGE FROM 0.1 TO 3.0 AT 0.1 -
    FROM 3.0 TO 3.6 AT 0.15 -
    FROM 3.6 TO 5.0 AT 0.2 -
    FROM 5.0 TO 8.0 AT 0.25 -
    FROM 8.0 TO 15.0 AT 0.5 -
    FROM 15.0 TO 18.0 AT 1.0 -
    FROM 18.0 TO 22.0 AT 2.0 -
    FROM 22.0 TO 55.0 AT 3.0
  DAMPING PERCENTS 1.0 2.0 4.0
  INCLUDE STRUCTURAL NATURAL FREOUENCIES
  USE ACCELERATION TIME HISTORY FILES 'THO-04X'
  INTEGRATE USING WILSON
  DIVISOR 1000.0
END OF CREATE RESPONSE SPECTRUM
```

The integration time increment for each of the frequency points in the specified frequency range is computed as 1/(f\*DIVISOR), where f is the natural frequency (Hz) under consideration. For example, if the frequency f = 43 Hz, then for DIVISOR = 1000, the integration time increment is 1/43000 = 2.3255e-5 seconds. If there are 26 seconds in the specified acceleration time history file THO-04X, the total number of time points needed for the integration calculation is 26/2.3255e-5 + 1 = 1.118 million > 1 million. The easiest work-around is to use a smaller DIVISOR value. In this and most cases, DIVISOR = 1000 is far in excess of what is reasonable to produce accurate and consistent results. Note that the default value for DIVISOR is 12.0; therefore in the large majority of cases it should not be necessary to exceed 100.0 for the DIVISOR value.

GTSTRUDL User Reference Manual Sections:

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The CREATE RESPONSE SPECTRA Command

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Section 2..4.8.2, Volume 3, Rev. R, GTSTRUDL Reference Manual

GPRF No.: 2002.03 DATE: 7/24/02

#### Computer-Aided Structural Engineering Center FROM: Georgia Institute of Technology Atlanta, Georgia 30332-0355

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### **SEVERITY LEVEL:**

- X URGENT Problem results in incorrect answers which may not be apparent or job aborts and cannot be recovered within the session or job.
- Problem results in incorrect answers which are obvious or problem prevents \_\_ SERIOUS completion of a particular user's task.
- Problem can be worked around or problem poses high frustration factor. \_\_ MINOR

\_ INFORMATIVE Documentation error, program usage tip, user inconveniences.

Date Problem Confirmed 7/24/02	
Date Notification Sent 7/24/02	
Computers All	
Operating System <u>All</u>	

Versions All versions prior to and including Version 26

Target Release for Correction \_\_\_\_ Version 27

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Signature R & D Division

Kenneth Will Typed or Printed Name

Signature Professional Services Division

avid C Key Typed or Printed Name

Director ASD

Title

ד/24/0 ע Date of Signature

<u>Contraventur Control Managen</u> Title <u>7/24/02</u> Date of Signature

## GTSTRUDL Program Report Form (Continued)

GPRF No.: 202.03 DATE: 7/24/22

**DESCRIPTION:** 

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STIFFNESS ANALYSIS will abort if MEMBER RELEASES and a MEMBER TEMPERATURE LOAD have been specified for a plane or space truss member.

Workaround: Remove the Member Releases for the truss members.

Example:

**TYPE SPACE TRUSS** MEMBER INCIDENCES 27 10 20 .... MEMBER RELEASES 27 START MOM X Y Z END MOM Y Z .... LOADING 1 MEMBER TEMPERATURE LOAD 27 AXIAL 100. Applicable Sections of the Documentation: MEMBER RELEASES Section 2.1.8.2 of Volume 1 of the GTSTRUDL Reference Manual MEMBER TEMPERATURE LOAD Section 2.1.11.4.4 of Volume 1 of the GTSTRUDL Reference Manual STIFFNESS ANALYSIS Section 2.1.13.2 of Volume 1 of the GTSTRUDL Reference Manual

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GPRF	No.:	2002 04

DATE: 9/13/2002

#### FROM: **Computer-Aided Structural Engineering Center** Georgia Institute of Technology Atlanta, Georgia 30332-0355

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### **SEVERITY LEVEL:**

- X URGENT Problem results in incorrect answers which may not be apparent or job aborts and cannot be recovered within the session or job.
- SERIOUS Problem results in incorrect answers which are obvious or problem prevents completion of a particular user's task.
- Problem can be worked around or problem poses high frustration factor. MINOR

\_ INFORMATIVE Documentation error, program usage tip, user inconveniences.

Date Problem Confirmed \_\_\_\_\_September 13, 2002\_\_\_\_\_

Date Notification Sent

Computers \_All\_\_\_\_\_

Operating System All

Version All

Target Release for Correction Version 26.0

KNW Signature

R & D Division

Michael H. Swanger Typed or Printed Name

Signature

**Professional Services Division** 

Typed or Printed Name

Sr. RE Title

<u>3/2002</u> Signature

Configuration Contol Manger Title

Date of Signature

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GPRF No.: 2002.04

DATE: <u>9/13/2002</u>

#### **DESCRIPTION:**

The second and later in a sequence of DYNAMIC ANALYSIS EIGENVALUE, ASSEMBLE FOR DYNAMICS, and DYNAMIC ANALYSIS MODE SUPERPOSITION commands will not reassemble the composite modal damping matrix if the only source of damping is joint damping proportionional to joint inertia. The following sequence of commands illustrates this situation:

```
INERTIA OF JOINTS WEIGHT
   1 TRANS X 75917.46 Y 75917.46 ROTATION Z
                                                         1209660318 DAMPING
                                                                                  0.04
   2 TRANS X 77064.00 Y 77064.00 ROTATION Z 1287174145 DAMPING
                                                                                  0.04
   3 TRANS X 54917.00 Y 54917.00 ROTATION Z
                                                         855341667 DAMPING
                                                                                  0.04

      4
      TRANS X
      40988.51
      Y
      40988.51
      ROTATION Z

      5
      TRANS X
      50329.18
      Y
      50329.18
      ROTATION Z

                                                          586281275 DAMPING
                                                                                  0.04
                                                          716459995 DAMPING
                                                                                  0.04
   6 TRANS X 21339.21 Y 21339.21 ROTATION Z
                                                       148471761 DAMPING 0.04
EIGEN PARAMETERS
SOLVE USING GTLANCZOS
NUMBER OF MODES 18
PRINT MAX
END
$$* **
$$* ** First DYNAMIC ANALYSIS EIGENVALUE command causing the first composite
$$* ** modal damping matrix assembly.
$$* **
DYNAMIC ANALYSIS EIGENVALUE
CHANGE
INERTIA OF JOINTS WEIGHT
   1
       DAMPING 0.09
   2
        DAMPING
                  0.09
   3
       DAMPING 0.09
                  0.09
   4
       DAMPING
       DAMPING - 0.09
   5
   6
        DAMPING
                   0.09
ADD
$$* **
$$* ** Second DYNAMIC ANALYSIS EIGENVALUE command in which the composite modal
$$* ** damping matrix is erroneously not re-assembled.
$$* **
DYNAMIC ANALYSIS EIGENVALUE
```

The only work-around is to break up the problem into separate jobs, where each job

reflects the different composite modal damping data.

## GTSTRUDL User Reference Manual Sections:

Specification of Damping Properties

Section 2..4.3.4, Volume 3, Rev. M, GTSTRUDL Reference Manual

GPRF No.: 2002.05

DATE: 9/18/2002

#### hi! 1.11. Computer-Aided Structural Engineering Center FROM: Georgia Institute of Technology Atlanta, Georgia 30332-0355

### **SEVERITY LEVEL:**

X_URGENT	Problem results in incorrect answers which may not be apparent or job
	aborts and cannot be recovered within the session or job.

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- SERIOUS Problem results in incorrect answers which are obvious or problem prevents completion of a particular user's task.
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\_ INFORMATIVE Documentation error, program usage tip, user inconveniences.

Date Problem Confirmed <u>September 18, 2002</u> Date Notification Sent \_\_\_\_\_9/18/2002 Computers <u>All</u> 

Operating System\_All\_\_\_\_

Version <u>All</u>

Target Release for Correction Version 27.0

Signature

R & D Division

Michael H. Swanger Typed or Printed Name

Signature **Professional Services Division** 

and L. Key

Typed or Printed Name

Sr. RE Title

<u>nfiguratio-Control Manager</u>

## GTSTRUDL Program Report Form (Continued)

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GPRF No.: 2002.05

### DATE: <u>9/18/2002</u>

### **DESCRIPTION:**

The CREATE RESPONSE SPECTRUM command will abort if the total number of time points needed to perform the integration for a specified acceleration time history file applied to a specified frequency exceeds 1 million, which is the maximum number of allowable time points. The following CREATE RESPONSE SPECTRUM example illustrates such a case:

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    FROM 3.6 TO 5.0 AT 0.2 -
    FROM 5.0 TO 8.0 AT 0.25 -
    FROM 8.0 TO 15.0 AT 0.5 -
    FROM 15.0 TO 18.0 AT 1.0 -
    FROM 18.0 TO 22.0 AT 2.0 -
    FROM 22.0 TO 55.0 AT 3.0
  DAMPING PERCENTS 1.0 2.0 4.0
  INCLUDE STRUCTURAL NATURAL FREQUENCIES
  USE ACCELERATION TIME HISTORY FILES 'THO-04X'
  INTEGRATE USING WILSON
  DIVISOR 1000.0
END OF CREATE RESPONSE SPECTRUM
```

The integration time increment for each of the frequency points in the specified frequency range is computed as 1/(f\*DIVISOR), where f is the natural frequency (Hz) under consideration. For example, if the frequency f = 43 Hz, then for DIVISOR = 1000, the integration time increment is 1/43000 = 2.3255e-5 seconds. If there are 26 seconds in the specified acceleration time history file THO-04X, the total number of time points needed for the integration calculation is 26/2.3255e-5 + 1 = 1.118 million > 1 million. The easiest work-around is to use a smaller DIVISOR value. In this and most cases, DIVISOR = 1000 is far in excess of what is reasonable to produce accurate and consistent results. Note that the default value for DIVISOR is 12.0; therefore in the large majority of cases it should not be necessary to exceed 100.0 for the DIVISOR value.

GTSTRUDL User Reference Manual Sections:

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The CREATE RESPONSE SPECTRA Command

Section 2..4.8.2, Volume 3, Rev. R, GTSTRUDL Reference Manual

Rev. 2.2