TABLE 4.3-2

ENGINEERED SAFETY FEATURES ACTUATION SYSTEM INSTRUMENTATION SURVEILLANCE REQUIREMENTS

•	FUN	ICT	IONAL UNIT	CHANNEL <u>CHECK</u>	CHANNEL CALIBRATION	ANALOG CHANNEL OPERATIONAL TEST	TRIP ACTUATING DEVICE OPERATIONAL TEST	ACTUATION LOGIC TEST	MASTER RELAY <u>TEST</u>	SLAVE RELAY TEST	MODES FOR WHICH SURVEILLANCE IS REQUIRED
	1.	Fee Bui Ini	fety Injection (Reactor Trip, edwater Isolation, Control ilding Isolation (Manual itiation Only), Start Diesel nerators, and Service Water)								
		a.	Manual Initiation	N.A.	N.A.	N.A.	R	N.A.	N.A.	N.A.	1, 2, 3, 4
30 0 10 0		b.	Automatic Actuation Logic and Actuation Relays	N.A.	N.A.	N.A.	N.A.	M(1)	M(1)	Q(4)	1, 2, 3, 4
		c.	Containment Pressure- High-l	S	R	Q	N.A.	N.A.	N.A.	N.A.	1, 2, 3
		d.	Pressurizer Pressure- Low	S	R	Q	N.A.	N.A.	N.A.	N.A.	1, 2, 3
		e.	Steam Line Pressure-Low	S	R	Q	N.A.	N.A.	N.A.	N.A.	1, 2, 3
Amondmont No. 46	2.	Соі	ntainment Spray								
		a.	Manual Initiation	N.A.	N.A.	N.A.	R	N.A.	N.A.	N.A.	1, 2, 3, 4
		b.	Automatic Actuation Logic and Actuation Relays	N.A.	N.A.	N.A.	N.A.	M(1)	M(1)	Q(4)	1, 2, 3, 4
		c.	Containment Pressure- High-3	S	R	Q	N.A.	N.A.	N.A.	N.A.	1, 2, 3, 4

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Amendment No. 45, 79, 79, 199, 198

ENGINEERED SAFETY FEATURES ACTUATION SYSTEM INSTRUMENTATION SURVEILLANCE REQUIREMENTS

MIL:	ENGINEERED SAFETY FEATURES ACTUATION SYSTEM INSTRUMENTATION SURVEILLANCE REQUIREMENTS									
MILLSTONE - UNIT	FUNCTIONAL UNIT	CHANNEL <u>CHECK</u>	CHANNEL CALIBRATION	ANALOG CHANNEL OPERATIONAL TEST	TRIP ACTUATING DEVICE OPERATIONAL TEST	ACTUATION LOGIC_TEST	MASTER RELAY <u>TEST</u>	SLAVE RELAY TEST	MODES FOR WHICH SURVEILLANCE <u>IS REQUIRED</u>	
IT 3	3. Containment Isolation									
	a. Phase "A" Isolation									
	1) Manual Initiation	N.A.	N.A.	N.A.	R	N.A.	N.A.	N.A.	1, 2, 3, 4	
	2) Automatic Actuation Logic and Actuation Relays	N.A.	N.A.	N.A.	N.A.	M(1)	M(1)	Q(4)	1, 2, 3, 4	
	3) Safety Injection	See Item	1. above fo	r all Safety	Injection Sur	veillance Re	equireme	nts.		
3/	b. Phase "B" Isolation									
3/4 3-37	1) Manual Initiation	N.A.	N.A.	N.A.	R	N.A.	N.A.	N.A.	1, 2, 3, 4	
-37	2) Automatic Actuation Logic Actuation Relays	N.A.	N.A.	N.A.	N.A.	M(1)	M(1)	Q(4)	1, 2, 3, 4	
Amei	3) Containment Pressure-High-3	S	R	Q	N.A.	N.A.	N.A.	N.A.	1, 2, 3, 4	
ndme	c. Purge Isolation	S	R	Q	N.A.	N.A.	N.A.	N.A.	5, 6#	
nt l	4. Steam Line Isolation									
No. 12	a. Manual Initiation									
Amendment No. 49, 129, 1	1) Individual	N.A.	N.A.	N.A.	R	N.A.	N.A.	N.A.	1, 2, 3, 4	
79 , 198	2) System	N.A.	N.A.	N.A.	R	N.A.	N.A.	N.A.	1, 2, 3, 4	
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ENGINEERED SAFETY FEATURES ACTUATION SYSTEM INSTRUMENTATION SURVEILLANCE REQUIREMENTS

<u>Fl</u>	INC 1	TIONAL UNIT	CHANNEL <u>CHECK</u>	CHANNEL CALIBRATION	ANALOG CHANNEL OPERATIONAL TEST	TRIP ACTUATING DEVICE OPERATIONAL TEST	ACTUATION LOGIC TEST	MASTER RELAY <u>TEST</u>	SLAVE RELAY TEST	MODES FOR WHICH SURVEILLANCE IS REQUIRED
4. Steam Line Isolation (Continued		d)								
	b.	Automatic Actuation Logic and Actuation Relays	N.A.	N.A.	N.A.	N.A.	M(1)	M(1)	Q(4)	1, 2, 3, 4
	c.	Containment Pressure- High-2	S	R	Q	N.A.	N.A.	N.A.	N.A.	1, 2, 3, 4
	d.	Steam Line Pressure-Low	S	R	Q	N.A.	N.A.	N.A.	N.A.	1, 2, 3
	e.	Steam Line Pressure- Negative Rate-High	S	R	Q	N.A.	N.A.	N.A.	N.A.	3
5.	Tu: Is	rbine Trip and Feedwater olation		2.						
	a.	Automatic Actuation Logic and Actuation Relays	N.A.	N.A.	N.A.	N.A.	M(1)	M(1)	Q(4)	1, 2
	b.	Steam Generator Water Level-High-High	S	R	Q	N.A.	M(1)	M(1)	Q(4)	1, 2, 3
	c.	Safety Injection Actuation Logic	N.A.	N.A.	N.A.	R	N.A.	N.A.	N.A.	1, 2
	d.	T _{ave} Low Coincident with Reactor Trip (P-4)	N.A.	R	Q	N.A.	N.A.	N.A.	N.A.	1, 2

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ENGINEERED SAFETY FEATURES ACTUATION SYSTEM INSTRUMENTATION SURVEILLANCE REQUIREMENTS

	FUN	<u>ICTI</u>	IONAL_UNIT	CHANNEL <u>CHECK</u>	CHANNEL CALIBRATION	ANALOG CHANNEL OPERATIONAL TEST	TRIP ACTUATING DEVICE OPERATIONAL TEST	ACTUATION LOGIC TEST	MASTER RELAY <u>TEST</u>	SLAVE RELAY TEST	MODES FOR WHICH SURVEILLANCE IS REQUIRED
	6.	Aux	kiliary Feedwater								
		a.	Manual Initiation	N.A.	N.A.	N.A.	R	N.A.	N.A.	N.A.	1, 2, 3
		b.	Automatic Actuation and Actuation Relays	N.A.	Ν.Α	N.A.	N.A.	M(1)	M(1)	Q(4)	1, 2, 3
		c.	Steam Generator Water Level-Low-Low	S	R	Q	N.A.	N.A.	N.A.	N.A.	1, 2, 3
		d.	Safety Injection	See Item	1. above for	all Safety	Injection Sur	veillance R	equirem	ents.	
		e.	Loss-of-Offsite Power	See Item	18. below for	all Loss of	Power Survei	llance.			
50		f.	Containment Depres- surization Actuation (CDA)	See Item	12. above for	jall CDA Sur	veillance Req	uirements.			
	7.	Co	ontrol Building Isolation								
_		a.	Manual Actuation	N.A.	N.A.	N.A.	R	N.A.	N.A.	N.A.	A11
mondm		b.	Manual Safety Injection Actuation	N.A.	N.A.	N.A.	R	N.A.	N.A.	N.A.	1, 2, 3, 4
ant No		c.	Automatic Actuation Logic and Actuation Relays	N.A.	N.A.	N.A.	N.A.	M(1)	M(1)	Q(4)	1, 2, 3, 4
44		d.	Containment Pressure High-1	S	R	Q	N.A.	N.A.	N.A.	N.A.	1, 2, 3

TABLE NOTATION

- (1) Each train shall be tested at least every 62 days on a STAGGERED TEST BASIS.
- (2) This surveillance may be performed continuously by the emergency generator load sequencer auto test system as long as the EGLS auto test system is demonstrated operable by the performance of an ACTUATION LOGIC TEST at least once per 92 days.
- (3) On a monthly basis, a loss of voltage condition will be initiated at each undervoltage monitoring relay to verify individual relay operation. Setpoint verification and actuation of the associated logic and alarm relays will be performed as part of the channel calibration required once per 18 months.
- (4) For Engineered Safety Features Actuation System functional units with only Potter & Brumfield MDR series relays used in a clean, environmentally controlled cabinet, as discussed in Westinghouse Owners Group Report WCAP-13900, the surveillance interval for slave relay testing is R.
 - # During core alterations or movement of irradiated fuel within the containment. The provisions of Specification 3.0.3 are not applicable.

INSTRUMENTATION

BASES

<u>REACTOR TRIP SYSTEM INSTRUMENTATION and ENGINEERED SAFETY FEATURES ACTUATION</u> SYSTEM INSTRUMENTATION (Continued)

The Engineered Safety Features Actuation System senses selected plant parameters and determines whether or not predetermined limits are being exceeded. If they are, the signals are combined into logic matrices sensitive to combinations indicative of various accidents, events, and transients. Once the required logic combination is completed, the system sends actuation signals to those Engineered Safety Features components whose aggregate function best serves the requirements of the condition. As an example, the following actions may be initiated by the Engineered Safety Features Actuation System to mitigate the consequences of a steam line break or loss-of-coolant accident: (1) Safety Injection pumps start and automatic valves position, (2) Reactor trip, (3) feedwater isolation, (4) startup of the emergency diesel generators, (5) quench spray pumps start and automatic valves position, (6) containment isolation, (7) steam line isolation, (8) Turbine trip, (9) auxiliary feedwater pumps start, (10) service water pumps start and automatic valves position, and (11) Control Room isolates.

For slave relays, or any auxiliary relays in ESFAS circuits that are of the type Potter & Brumfield MDR series relays, the SLAVE RELAY TEST is performed at an "R" frequency (at least once every 18 months) provided the relays meet the reliability assessment criteria presented in WCAP-13878, "Reliability Assessment of Potter and Brumfield MDR series relays," and WCAP-13900, "Extension of Slave Relay Surveillance Test Intervals." The reliability assessments performed as part of the aforementioned WCAPs are relay specific and apply only to Potter and Brumfield MDR series relays. Note that for normally energized applications, the relays may have to be replaced periodically in accordance with the guidance given in WCAP-13878 for MDR relays.

REACTOR TRIP BREAKER

This trip function applies to the reactor trip breakers (RTBs) exclusive of individual trip mechanisms. The LCO requires two operable trains of trip breakers. A trip breaker train consists of all trip breakers associated with a single RUS logic train that are racked in, closed, and capable of supplying power to the control rod drive (CRD) system. Thus, the train may consist of the main breaker, bypass breaker, or main breaker and bypass breaker, depending upon the system configuration. Two OPERABLE trains ensure no single random failure can disable the RTS trip capability.

These trip functions must be OPERABLE in MODE 1 or 2 when the reactor is critical. In MODE 3, 4, or 5, these RTS trip functions must be OPERABLE when the RTBs or associated bypass breakers are closed, and the CRD system is capable of rod withdrawal.

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