

B 3.6 CONTAINMENT SYSTEMS

B 3.6.1.6 Suppression Chamber-to-Drywell Vacuum Breakers

BASES

BACKGROUND

The function of the suppression-chamber-to-drywell vacuum breakers is to relieve vacuum in the drywell. There are four vacuum breakers located outside the primary containment which form an extension of the primary containment boundary. The vacuum relief valves are mounted in special piping between the drywell and the suppression chamber, which allow air and steam flow from the suppression chamber to the drywell when the drywell is at a negative pressure with respect to the suppression chamber. Therefore, suppression chamber-to-drywell vacuum breakers prevent an excessive negative differential pressure across the wetwell drywell boundary. Each vacuum breaker is a self actuating valve with one vacuum breaker in each line. Manual isolation valves are located on each side of each vacuum breaker.

A negative differential pressure across the drywell wall is caused by rapid depressurization of the drywell. Events that cause this rapid depressurization are cooling cycles, inadvertent drywell spray actuation, and steam condensation from sprays or subcooled water reflood of a break in the event of a primary system rupture. Cooling cycles result in minor pressure transients in the drywell that occur slowly and are normally controlled by heating and ventilation equipment. Spray actuation or spill of subcooled water out of a break results in more significant pressure transients and becomes important in sizing the vacuum breakers.

In the event of a primary system rupture, steam condensation within the drywell results in the most severe pressure transient. Following a primary system rupture, air in the drywell is purged into the suppression chamber free airspace, leaving the drywell full of steam. Subsequent condensation of the steam can be caused in two possible ways, namely, Emergency Core Cooling Systems flow from a recirculation line break, or drywell spray actuation following a loss of coolant accident (LOCA). These two cases determine the maximum depressurization rate of the drywell.

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BASES

BACKGROUND
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In addition, the water column in the Mark II Vent System downcomer is controlled by the drywell-to-suppression chamber differential pressure. If the drywell pressure is less than the suppression chamber pressure, there will be an increase in the downcomer water column height. This will result in an increase in the water clearing inertia in the event of a postulated LOCA, resulting in an increase in the peak drywell pressure. This in turn will result in an increase in the pool swell dynamic loads. The vacuum breakers limit the height of the waterleg in the downcomer during normal operation.

APPLICABLE
SAFETY ANALYSES

Analytical methods and assumptions involving the suppression chamber-to-drywell vacuum breakers are presented in Reference 1 as part of the accident response of the primary containment systems. Suppression chamber-to-drywell vacuum breakers are provided as part of the primary containment to limit the negative differential pressure across the drywell and suppression chamber walls to maintain the structural integrity of primary containment.

The safety analyses assume that the vacuum breakers are closed initially and are fully open at a differential pressure of 1.0 psid (Refs. 1 and 2). Additionally, one of the four vacuum breakers is assumed to fail in a closed position (Refs. 1 and 2). The results of the analyses show that the design pressure is not exceeded even under the worst case accident scenario. The vacuum breaker opening differential pressure setpoint and the requirement that four vacuum breakers be OPERABLE (the additional vacuum breaker is required to meet the single failure criterion) are a result of the requirement placed on the vacuum breakers to limit the downcomer waterleg height. Design Basis Accident (DBA) analyses assume the vacuum breakers to be closed initially and to remain closed and leak tight until the suppression pool is at a positive pressure relative to the drywell.

The suppression chamber-to-drywell vacuum breakers satisfy Criterion 3 of 10 CFR 50.36(c)(2)(ii).

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BASES (continued)

LCO All vacuum breakers must be OPERABLE to provide assurance that the vacuum breakers will open so that drywell-to-suppression chamber negative differential pressure remains below the design value. This LCO also ensures that all suppression chamber-to-drywell vacuum breakers are closed (except during testing or when the vacuum breakers are performing their intended design function). The manual isolation valves in each vacuum breaker line must also be open for the associated vacuum breaker to be considered OPERABLE. The requirement that the vacuum breakers be closed ensures that there is no excessive bypass leakage should a LOCA occur.

APPLICABILITY In MODES 1, 2, and 3, a DBA could result in excessive negative differential pressure across the drywell wall, caused by the rapid depressurization of the drywell. The event that results in the limiting rapid depressurization of the drywell is the primary system rupture that purges the drywell of air and fills the drywell free airspace with steam. Subsequent condensation of the steam would result in depressurization of the drywell. The limiting pressure and temperature of the primary system prior to a DBA occur in MODES 1, 2, and 3. Excessive negative pressure inside the drywell could occur due to inadvertent actuation of drywell sprays.

In MODES 4 and 5, the probability and consequences of these events are reduced by the pressure and temperature limitations in these MODES; therefore, maintaining suppression chamber-to-drywell vacuum breakers OPERABLE is not required in MODE 4 or 5.

ACTIONS

A.1

With one of the vacuum breakers inoperable for opening (e.g., the vacuum breaker is not open and may be stuck closed or not within its opening setpoint limit, so that it would not function as designed during an event that depressurized the drywell), the remaining three OPERABLE vacuum breakers are capable of providing the vacuum relief function. However, overall system reliability is reduced because a single failure in one of the remaining vacuum breakers could result in an excessive suppression chamber-to-drywell differential pressure during a DBA. Therefore,

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BASES

ACTIONS

A.1 (continued)

with one of the four vacuum breakers inoperable, 72 hours is allowed to restore the inoperable vacuum breaker to OPERABLE status so that plant conditions are consistent with those assumed for the design basis analysis. The 72 hour Completion Time is considered acceptable due to the low probability of an event in which the remaining vacuum breaker capability would not be adequate.

B.1 and B.2

With one vacuum breaker not closed, communication between the drywell and suppression chamber airspace exists, and, as a result, there is the potential for primary containment overpressurization due to this bypass leakage if a LOCA were to occur. Therefore, both manual isolation valves in the affected vacuum breaker line must be closed. A short time is allowed to close the manual valves due to the low probability of an event that would pressurize primary containment. The required 4 hour Completion Time is considered adequate to perform this activity. With both manual isolation valves closed, the vacuum breaker is not capable of performing the vacuum relief function. While the remaining three OPERABLE vacuum breakers are capable of providing the vacuum relief function, the overall reliability is reduced because a single failure in one of the remaining vacuum breakers could result in an excessive suppression chamber-to-drywell differential pressure during a DBA. Therefore, under this condition, 72 hours is allowed to restore the inoperable vacuum breaker to OPERABLE status so that the plant conditions are consistent with those assumed for the design basis analysis. The 72 hour Completion Time is considered acceptable due to the low probability of an event in which the remaining vacuum breaker capability would not be adequate.

C.1 and C.2

If any Required Action and associated Completion cannot be met, the plant must be brought to a MODE in which the LCO does not apply. To achieve this status, the plant must be brought to at least MODE 3 within 12 hours and to MODE 4 within 36 hours. The allowed Completion Times are

(continued)

BASES

ACTIONS

C.1 and C.2 (continued)

reasonable, based on operating experience, to reach the required plant conditions from full power conditions in an orderly manner and without challenging plant systems.

D.1

With two or more vacuum breakers inoperable, an excessive suppression chamber-to-drywell differential pressure could occur during a DBA. Therefore, an immediate plant shutdown in accordance with LCO 3.0.3 is required.

SURVEILLANCE
REQUIREMENTS

SR 3.6.1.6.1

Each vacuum breaker is verified closed to ensure that this potential large bypass leakage path is not present. This Surveillance is performed by observing the vacuum breaker position indication or by verifying that a differential pressure of 0.25 psid between the suppression chamber and drywell is maintained for 1 hour without makeup. The 14 day Frequency is based on engineering judgment, is considered adequate in view of other indications of vacuum breaker status available to operations personnel, and has been shown to be acceptable through operating experience.

Two Notes are added to this SR. The first Note allows suppression chamber-to-drywell vacuum breakers opened in conjunction with the performance of a Surveillance to not be considered as failing this SR. These periods of opening vacuum breakers are controlled by plant procedures and do not represent inoperable vacuum breakers. The second Note is included to clarify that vacuum breakers open due to an actual differential pressure are not considered as failing this SR.

SR 3.6.1.6.2

Each vacuum breaker must be manually cycled to ensure that it opens adequately to perform its design function and returns to the fully closed position. This ensures that the safety analysis assumptions are valid. The 92 day Frequency of this SR was developed, based on Inservice Testing Program

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BASES

SURVEILLANCE
REQUIREMENTS

SR 3.6.1.6.2 (continued)

requirements to perform valve testing at least once every 92 days. In addition, this functional test is required within 12 hours after a discharge of steam to the suppression chamber from the safety/relief valves.

SR 3.6.1.6.3

Verification of the vacuum breaker opening setpoint of ≤ 0.5 psid from the closed position is necessary to ensure that the safety analysis assumption regarding vacuum breaker full open differential pressure of 1.0 psid is valid. The 24 month Frequency is based on the need to perform this Surveillance under the conditions that apply during a plant outage and the potential for an unplanned transient if the Surveillance were performed with the reactor at power. The 24 month Frequency has been shown to be acceptable, based on operating experience, and is further justified because of other surveillances performed at shorter Frequencies that convey the proper functioning status of each vacuum breaker.

REFERENCES

1. UFSAR, Section 6.2.1.
 2. FSAR, Response to NRC Question 021.4.
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B 3.6 CONTAINMENT SYSTEMS

B 3.6.2.1 Suppression Pool Average Temperature

BASES

BACKGROUND

The primary containment utilizes a Mark II over/under pressure suppression configuration, with the suppression pool located at the bottom of the primary containment. The suppression pool is designed to absorb the decay heat and sensible heat released during a reactor blowdown from safety/relief valve discharges or from a loss of coolant accident (LOCA). The suppression pool must also condense steam from the Reactor Core Isolation Cooling System turbine exhaust and provides the main emergency water supply source for the reactor vessel. The suppression pool must quench all the steam released through the downcomer lines during a loss of coolant accident (LOCA). This is the essential mitigative feature of a pressure suppression containment that ensures that the peak containment pressure is maintained below the design value (45 psig). Suppression pool average temperature (along with LCO 3.6.2.2, "Suppression Pool Water Level") is a key indication of the capacity of the suppression pool to fulfill these requirements.

The technical concerns that lead to the development of suppression pool average temperature limits are as follows:

- a. Complete steam condensation;
- b. Primary containment peak pressure and temperature;
- c. Condensation oscillation (CO) loads; and
- d. Chugging loads.

APPLICABLE
SAFETY ANALYSES

The postulated DBA against which the primary containment performance is evaluated is the entire spectrum of postulated pipe breaks within the primary containment. Inputs to the safety analyses include initial suppression pool water volume and suppression pool temperature (Reference 1 for LOCAs and References 1 and 2 for the suppression pool temperature analyses required by Reference 3). An initial pool temperature of 105°F is

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BASES

APPLICABLE
SAFETY ANALYSES
(continued)

assumed for the Reference 1 analyses. Reactor shutdown at a pool temperature of 110°F and vessel depressurization at a pool temperature of 120°F are assumed for the Reference 1 and 2 analyses.

Suppression pool average temperature satisfies Criteria 2 and 3 of 10 CFR 50.36(c)(2)(ii).

LCO

A limitation on the suppression pool average temperature is required to assure that the primary containment conditions assumed for the safety analyses are met. This limitation subsequently ensures that peak primary containment pressures and temperatures do not exceed maximum allowable values during a postulated DBA or any transient resulting in heatup of the suppression pool. The LCO requirements are as follows:

- a. Average temperature $\leq 105^{\circ}\text{F}$ with THERMAL POWER $> 1\%$ RTP. This requirement ensures that licensing bases initial conditions are met. This requirement also ensures that the plant has testing flexibility, and was selected to provide margin below the 110°F limit at which reactor shutdown is required.
- b. Average temperature $\leq 110^{\circ}\text{F}$ with THERMAL POWER $\leq 1\%$ RTP. This requirement ensures that the plant will be shut down at $> 110^{\circ}\text{F}$. The pool is designed to absorb decay heat and sensible heat but could be heated beyond design limits by the steam generated if the reactor is not shut down.

At 1% RTP, heat input is approximately equal to normal system heat losses.

APPLICABILITY

In MODES 1, 2, and 3, a DBA could cause significant heatup of the suppression pool. In MODES 4 and 5, the probability and consequences of these events are reduced due to the pressure and temperature limitations in these MODES. Therefore, maintaining suppression pool average temperature within limits is not required in MODE 4 or 5.

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BASES (continued)

ACTIONS A.1, A.2, and A.3

With the suppression pool average temperature above the specified limit and when above the specified power limit, the initial conditions exceed the conditions assumed for the Reference 1 and 2 analyses. However, primary containment cooling capability still exists, and the primary containment pressure suppression function will occur at temperatures well above that assumed for safety analyses. Therefore, continued operation is allowed for a limited time. The 24 hour Completion Time is adequate to allow the suppression pool temperature to be restored to below the limit. Additionally, when pool temperature is $> 105^{\circ}\text{F}$, increased monitoring of the pool temperature is required to ensure it remains $\leq 110^{\circ}\text{F}$. The once per hour Completion Time is adequate based on past experience, which has shown that suppression pool temperature increases relatively slowly except when testing that adds heat to the pool is being performed. Furthermore, the once per hour Completion Time is considered adequate in view of other indications in the control room, including alarms, to alert the operator to an abnormal suppression pool average temperature condition. In addition, testing that adds heat to the suppression pool must be immediately suspended to preserve the pool heat absorption capability.

B.1

If the suppression pool average temperature cannot be restored to within limits within the required Completion Time, the plant must be brought to a MODE in which the LCO does not apply. To achieve this status, THERMAL POWER must be reduced to $\leq 1\%$ RTP within 12 hours. The 12 hour Completion Time is reasonable, based on operating experience, to reduce reactor power from full power in an orderly manner and without challenging plant systems.

C.1, C.2, and C.3

Suppression pool average temperature $> 110^{\circ}\text{F}$ requires that the reactor be shut down immediately. This is accomplished by placing the reactor mode switch in the shutdown position. Further cooldown to MODE 4 within 36 hours is required at

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BASES

ACTIONS C.1, C.2, and C.3 (continued)

normal cooldown rates (provided pool temperature remains $\leq 120^{\circ}\text{F}$). Additionally, when pool temperature is $> 110^{\circ}\text{F}$, increased monitoring of pool temperature is required to ensure that it remains $\leq 120^{\circ}\text{F}$. The once per 30 minute Completion Time is adequate, based on operating experience. Given the high pool temperature in this condition, the monitoring Frequency is increased to twice that of Condition A. Furthermore, the 30 minute Completion Time is considered adequate in view of other indications available in the control room to alert the operator to an abnormal suppression pool average temperature condition.

D.1 and D.2

If suppression pool average temperature cannot be maintained $\leq 120^{\circ}\text{F}$, the plant must be brought to a MODE in which the LCO does not apply. To achieve this status, the reactor pressure must be reduced to < 200 psig within 12 hours and the plant must be brought to MODE 4 within 36 hours. The allowed Completion Times are reasonable, based on operating experience, to reach the required plant conditions from full power conditions in an orderly manner without challenging plant systems.

Continued addition of heat to the suppression pool with pool temperature $> 120^{\circ}\text{F}$ could result in exceeding the design basis maximum allowable values for primary containment temperature or pressure. Furthermore, if a blowdown were to occur when temperature was $> 120^{\circ}\text{F}$, the maximum allowable bulk and local temperatures could be exceeded very quickly.

SURVEILLANCE
REQUIREMENTS

SR 3.6.2.1.1

The suppression pool average temperature is regularly monitored to ensure that the required limits are satisfied. Average temperature is determined by taking an arithmetic average of the OPERABLE suppression pool water temperature channels, and may include an allowance for temperature stratification. The 24 hour Frequency has been shown to be acceptable based on operating experience. When heat is being added to the suppression pool by testing, however, it

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BASES

SURVEILLANCE
REQUIREMENTS

SR 3.6.2.1.1 (continued)

is necessary to monitor suppression pool temperature more frequently. The 5 minute Frequency during testing is justified by the rates at which testing will heat up the suppression pool, has been shown to be acceptable based on operating experience, and provides assurance that allowable pool temperatures are not exceeded. The Frequencies are further justified in view of other indications available in the control room, including alarms, to alert the operator to an abnormal suppression pool average temperature condition.

REFERENCES

1. UFSAR, Section 6.2.
 2. LaSalle County Station Mark II Design Assessment Report, Section 6.2, June 1981.
 3. NUREG-0783.
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B 3.6 CONTAINMENT SYSTEMS

B 3.6.2.2 Suppression Pool Water Level

BASES

BACKGROUND

The primary containment utilizes a Mark II over/under pressure suppression configuration, with the suppression pool located at the bottom of the primary containment. The suppression pool is designed to absorb the decay heat and sensible heat released during a reactor blowdown from safety/relief valve (S/RV) discharges or from a loss of coolant accident (LOCA). The suppression pool must also condense steam from the Reactor Core Isolation Cooling (RCIC) System turbine exhaust and provides the main emergency water supply source for the reactor vessel. The suppression pool volume ranges between 128,800 ft³ at the low water level limit of -4.5 inches and 131,900 ft³ at the high water level limit of 3 inches. The level is referenced to a plant elevation of 699 ft 11 inches.

If the suppression pool water level is too low, an insufficient amount of water would be available to adequately condense the steam from the S/RV quenchers, main vents, or RCIC turbine exhaust lines. Low suppression pool water level could also result in an inadequate emergency makeup water source to the Emergency Core Cooling System. The lower volume would also absorb less steam energy before heating up excessively. Therefore, a minimum suppression pool water level is specified.

If the suppression pool water level is too high, it could result in excessive clearing loads from S/RV discharges and excessive pool swell loads resulting from a Design Basis Accident (DBA) LOCA. Therefore, a maximum pool water level is specified. This LCO specifies an acceptable range to prevent the suppression pool water level from being either too high or too low.

APPLICABLE
SAFETY ANALYSES

Initial suppression pool water level affects suppression pool temperature response calculations, calculated drywell pressure for a DBA, calculated pool swell loads for a DBA LOCA, and calculated loads due to S/RV discharges. Suppression pool water level must be maintained within the limits specified so that the safety analysis of Reference 1 remains valid.

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BASES

APPLICABLE SAFETY ANALYSES (continued) Suppression pool water level satisfies Criteria 2 and 3 of 10 CFR 50.36(c)(2)(ii).

LCO A limit that suppression pool water level be \geq -4.5 inches and \leq 3 inches (referenced to plant elevation 699 ft 11 inches) is required to ensure that the primary containment conditions assumed for the safety analysis are met. Either the high or low water level limits were used in the safety analysis, depending upon which is conservative for a particular calculation.

APPLICABILITY In MODES 1, 2, and 3, a DBA could cause significant loads on the primary containment. In MODES 4 and 5, the probability and consequences of these events are reduced because of the pressure and temperature limitations in these MODES. The requirements for maintaining suppression pool water level within limits in MODE 4 or 5 is addressed in LCO 3.5.2, "ECCS - Shutdown."

ACTIONS A.1

With suppression pool water level outside the limits, the conditions assumed for the safety analysis are not met. If water level is below the minimum level, the pressure suppression function still exists as long as the downcomers are covered, RCIC turbine exhausts are covered, and S/RV quenchers are covered. If suppression pool water level is above the maximum level, protection against overpressurization still exists due to the margin in the peak containment pressure analysis and the capability of the suppression pool sprays. Therefore, continued operation for a limited time is allowed. The 2 hour Completion Time is sufficient to restore suppression pool water level to within specified limits. Also, it takes into account the low probability of an event impacting the suppression pool water level occurring during this interval.

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BASES

ACTIONS
(continued)

B.1 and B.2

If suppression pool water level cannot be restored to within limits within the required Completion Time, the plant must be brought to a MODE in which the LCO does not apply. To achieve this status, the plant must be brought to at least MODE 3 within 12 hours and to MODE 4 within 36 hours. The allowed Completion Times are reasonable, based on operating experience, to reach the required plant conditions from full power conditions in an orderly manner and without challenging plant systems.

SURVEILLANCE
REQUIREMENTS

SR 3.6.2.2.1

Verification of the suppression pool water level is to ensure that the required limits are satisfied. The 24 hour Frequency has been shown to be acceptable based on operating experience. Furthermore, the 24 hour Frequency is considered adequate in view of other indications available in the control room, including alarms, to alert the operator to an abnormal suppression pool water level condition.

REFERENCES

1. UFSAR, Section 6.2.
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B 3.6 CONTAINMENT SYSTEMS

B 3.6.2.3 Residual Heat Removal (RHR) Suppression Pool Cooling

BASES

BACKGROUND

Following a Design Basis Accident (DBA), the RHR Suppression Pool Cooling System removes heat from the suppression pool. The suppression pool is designed to absorb the sudden input of heat from the primary system. In the long term, the pool continues to absorb residual heat generated by fuel in the reactor core. Some means must be provided to remove heat from the suppression pool so that the temperature inside the primary containment remains within design limits. This function is provided by two redundant RHR suppression pool cooling subsystems. The purpose of this LCO is to ensure that both subsystems are OPERABLE in applicable MODES.

Each RHR subsystem contains a pump and a heat exchanger and is manually initiated and independently controlled. The two RHR subsystems perform the suppression pool cooling function by circulating water from the suppression pool through the RHR heat exchangers and returning it to the suppression pool. RHR service water, circulating through the tube side of the heat exchangers, exchanges heat with the suppression pool water and discharges this heat to the external heat sink.

The heat removal capability of one RHR subsystem is sufficient to meet the overall DBA pool cooling requirement to limit peak temperature to 208°F for loss of coolant accidents (LOCAs) and transient events such as a turbine trip or a stuck open safety/relief valve (S/RV). S/RV leakage and Reactor Core Isolation Cooling System testing increase suppression pool temperature more slowly. The RHR Suppression Pool Cooling System is also used to lower the suppression pool water bulk temperature following such events.

APPLICABLE
SAFETY ANALYSES

Reference 1 contains the results of analyses used to predict primary containment pressure and temperature following large and small break LOCAs. The intent of the analyses is to demonstrate that the heat removal capacity of the RHR Suppression Pool Cooling System is adequate to maintain the primary containment conditions within design limits. The

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BASES

APPLICABLE SAFETY ANALYSES (continued) suppression pool temperature is calculated to remain below the design limit.
The RHR Suppression Pool Cooling System satisfies Criterion 3 of 10 CFR 50.36(c)(2)(ii).

LCO During a DBA, a minimum of one RHR suppression pool cooling subsystem is required to maintain the primary containment peak pressure and temperature below the design limits (Ref. 1). To ensure that these requirements are met, two RHR suppression pool cooling subsystems must be OPERABLE. Therefore, in the event of an accident, at least one subsystem is OPERABLE, assuming the worst case single active failure. An RHR suppression pool cooling subsystem is OPERABLE when the pump, a heat exchanger, and associated piping, valves, instrumentation, and controls are OPERABLE.

APPLICABILITY In MODES 1, 2, and 3, a DBA could cause both a release of radioactive material to primary containment and a heatup and pressurization of primary containment. In MODES 4 and 5, the probability and consequences of these events are reduced due to the pressure and temperature limitations in these MODES. Therefore, the RHR Suppression Pool Cooling System is not required to be OPERABLE in MODE 4 or 5.

ACTIONS A.1
With one RHR suppression pool cooling subsystem inoperable, the inoperable subsystem must be restored to OPERABLE status within 7 days. In this condition, the remaining RHR suppression pool cooling subsystem is adequate to perform the primary containment cooling function. However, the overall reliability is reduced because a single failure in the OPERABLE subsystem could result in reduced primary containment cooling capability. The 7 day Completion Time is acceptable in light of the redundant RHR suppression pool cooling capabilities afforded by the OPERABLE subsystem and the low probability of a DBA occurring during this period.

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BASES

ACTIONS
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B.1

With two RHR suppression pool cooling subsystems inoperable, one subsystem must be restored to OPERABLE status within 8 hours. In this condition, there is a substantial loss of the primary containment pressure and temperature mitigation function. The 8 hour Completion Time is based on this loss of function and is considered acceptable due to the low probability of a DBA and the potential avoidance of a plant shutdown transient that could result in the need for the RHR suppression pool cooling subsystems to operate.

C.1 and C.2

If any Required Action and associated Completion Time cannot be met, the plant must be brought to a MODE in which the LCO does not apply. To achieve this status, the plant must be brought to at least MODE 3 within 12 hours and to MODE 4 within 36 hours. The allowed Completion Times are reasonable, based on operating experience, to reach the required plant conditions from full power conditions in an orderly manner and without challenging plant systems.

SURVEILLANCE
REQUIREMENTS

SR 3.6.2.3.1

Verifying the correct alignment for manual and power operated valves in the RHR suppression pool cooling mode flow path provides assurance that the proper flow path exists for system operation. This SR does not apply to valves that are locked, sealed, or otherwise secured in position since these valves were verified to be in the correct position prior to being locked, sealed, or secured. A valve is also allowed to be in the nonaccident position, provided it can be aligned to the accident position within the time assumed in the accident analysis. This is acceptable, since the RHR suppression pool cooling mode is manually initiated. This SR does not require any testing or valve manipulation; rather, it involves verification that those valves capable of being mispositioned are in the correct position. This SR does not apply to valves that cannot be inadvertently misaligned, such as check valves.

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BASES

SURVEILLANCE
REQUIREMENTS

SR 3.6.2.3.1 (continued)

The Frequency of 31 days is justified because the valves are operated under procedural control, improper valve position would affect only a single subsystem, the probability of an event requiring initiation of the system is low, and the system is a manually initiated system. This Frequency has been shown to be acceptable, based on operating experience.

SR 3.6.2.3.2

Verifying each required RHR pump develops a flow rate ≥ 7200 gpm, while operating in the suppression pool cooling mode with flow through the associated heat exchanger, ensures that peak suppression pool temperature can be maintained below the design limits during a DBA (Ref. 1). The flow verification is also a normal test of centrifugal pump performance required by ASME Section XI (Ref. 2). This test confirms one point on the pump design curve, and the results are indicative of overall performance. Such inservice tests confirm component OPERABILITY and detect incipient failures by indicating abnormal performance. The Frequency of this SR is in accordance with the Inservice Testing Program.

REFERENCES

1. UFSAR, Section 6.2.
 2. ASME, Boiler and Pressure Vessel Code, Section XI.
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B 3.6 CONTAINMENT SYSTEMS

B 3.6.2.4 Residual Heat Removal (RHR) Suppression Pool Spray

BASES

BACKGROUND Following a Design Basis Accident (DBA), the RHR Suppression Pool Spray System removes heat from the suppression chamber airspace. The suppression pool is designed to absorb the sudden input of heat from the primary system from a DBA or a rapid depressurization of the reactor pressure vessel (RPV) through safety/relief valves. The heat addition to the suppression pool results in increased steam in the suppression chamber, which increases primary containment pressure. Steam blowdown from a DBA can also bypass the suppression pool and end up in the suppression chamber airspace. Some means must be provided to remove heat from the suppression chamber so that the pressure and temperature inside primary containment remain within analyzed design limits. This function is provided by two redundant RHR suppression pool spray subsystems. The purpose of this LCO is to ensure that both subsystems are OPERABLE in applicable MODES.

Each of the two RHR suppression pool spray subsystems contains one pump and one heat exchanger, which are manually initiated and independently controlled. The two subsystems perform the suppression pool spray function by circulating water from the suppression pool through the RHR heat exchangers and returning it to the suppression pool spray sparger. The sparger only accommodates a small portion of the total RHR pump flow; the remainder of the flow returns to the suppression pool through the suppression pool cooling return line (provided the associated valve is open). Thus, both suppression pool cooling and suppression pool spray functions are normally performed when the Suppression Pool Spray System is initiated. Either RHR suppression pool spray subsystem is sufficient to condense the steam from small bypass leaks from the drywell to the suppression chamber airspace during the postulated DBA.

APPLICABLE SAFETY ANALYSES Reference 1 contains the results of analyses used to predict primary containment pressure and temperature following large and small break loss of coolant accidents. The intent of the analyses is to demonstrate that the pressure reduction

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BASES

APPLICABLE
SAFETY ANALYSES
(continued)

capacity of the RHR Suppression Pool Spray System is adequate to maintain the primary containment conditions within design limits. The time history for primary containment pressure is calculated to demonstrate that the maximum pressure remains below the design limit.

The RHR Suppression Pool Spray System satisfies Criterion 3 of 10 CFR 50.36(c)(2)(ii).

LCO

In the event of a DBA, a minimum of one RHR suppression pool spray subsystem is required to mitigate potential bypass leakage paths and maintain the primary containment peak pressure below the design limits (Ref. 1). To ensure that these requirements are met, two RHR suppression pool spray subsystems must be OPERABLE. Therefore, in the event of an accident, at least one subsystem is OPERABLE assuming the worst case single active failure. An RHR suppression pool spray subsystem is OPERABLE when one of the pumps and associated piping, valves, instrumentation, and controls are OPERABLE.

APPLICABILITY

In MODES 1, 2, and 3, a DBA could cause pressurization of primary containment. In MODES 4 and 5, the probability and consequences of these events are reduced due to the pressure and temperature limitations in these MODES. Therefore, maintaining RHR suppression pool spray subsystems OPERABLE is not required in MODE 4 or 5.

ACTIONS

A.1

With one RHR suppression pool spray subsystem inoperable, the inoperable subsystem must be restored to OPERABLE status within 7 days. In this condition, the remaining OPERABLE RHR suppression pool spray subsystem is adequate to perform the primary containment bypass leakage mitigation function.

However, the overall reliability is reduced because a single failure in the OPERABLE subsystem could result in reduced primary containment bypass mitigation capability. The 7 day Completion Time was chosen in light of the redundant RHR suppression pool spray capabilities afforded by the OPERABLE subsystem and the low probability of a DBA occurring during this period.

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BASES

ACTIONS
(continued)

B.1

With both RHR suppression pool spray subsystems inoperable, at least one subsystem must be restored to OPERABLE status within 8 hours. In this condition, there is a substantial loss of the primary containment bypass leakage mitigation function. The 8 hour Completion Time is based on this loss of function and is considered acceptable due to the low probability of a DBA and because alternative methods to reduce pressure in the primary containment are available.

C.1 and C.2

If any Required Action and associated Completion Time cannot be met, the plant must be brought to a MODE in which the LCO does not apply. To achieve this status, the plant must be brought to at least MODE 3 within 12 hours and MODE 4 within 36 hours. The allowed Completion Times are reasonable, based on operating experience, to reach the required plant conditions from full power conditions in an orderly manner and without challenging plant systems.

SURVEILLANCE
REQUIREMENTS

SR 3.6.2.4.1

Verifying the correct alignment for manual and power operated valves in the RHR suppression pool spray mode flow path provides assurance that the proper flow paths will exist for system operation. This SR does not apply to valves that are locked, sealed, or otherwise secured in position since these valves were verified to be in the correct position prior to locking, sealing, or securing. A valve is also allowed to be in the nonaccident position provided it can be aligned to the accident position within the time assumed in the accident analysis. This is acceptable since the RHR suppression pool spray mode is manually initiated. This SR does not require any testing or valve manipulation; rather, it involves verification that those valves capable of being mispositioned are in the correct position. This SR does not apply to valves that cannot be inadvertently misaligned, such as check valves.

The Frequency of 31 days is justified because the valves are operated under procedural control, improper valve position would affect only a single subsystem, the probability of an

(continued)

BASES

SURVEILLANCE
REQUIREMENTS

SR 3.6.2.4.1 (continued)

event requiring initiation of the system is low, and the subsystem is a manually initiated system. This Frequency has been shown to be acceptable based on operating experience.

SR 3.6.2.4.2

Verifying each required RHR pump develops a flow rate ≥ 450 gpm through the spray sparger while operating in the suppression pool spray mode helps ensure that the primary containment pressure can be maintained below the design limits during a DBA (Ref. 1). The normal test of centrifugal pump performance required by Section XI of the ASME Code (Ref. 2) is covered by the requirements of LCO 3.6.2.3, "RHR Suppression Pool Cooling." The Frequency of this SR is in accordance with the Inservice Testing Program.

REFERENCES

1. UFSAR, Section 6.2.1.1.3.
 2. ASME, Boiler and Pressure Vessel Code, Section XI.
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B 3.6 CONTAINMENT SYSTEMS

B 3.6.3.1 Primary Containment Hydrogen Recombiners

BASES

BACKGROUND

The primary containment hydrogen recombiner eliminates the potential breach of primary containment due to a hydrogen oxygen reaction and is part of combustible gas control required by 10 CFR 50.44, "Standards for Combustible Gas Control in Light-Water-Cooled Reactors" (Ref. 1), and GDC 41, "Containment Atmosphere Cleanup" (Ref. 2). The primary containment hydrogen recombiners are required to reduce the hydrogen concentration in the primary containment following a loss of coolant accident (LOCA). The primary containment hydrogen recombiners accomplish this by recombining hydrogen and oxygen to form water vapor. The vapor is condensed and returned to the suppression pool, thus eliminating any discharge to the environment. The primary containment hydrogen recombiner is manually initiated, since flammability limits would not be reached until several hours after a Design Basis Accident (DBA).

Two 100% capacity independent primary containment hydrogen recombiner subsystems are provided and are shared between Unit 1 and Unit 2. Each consists of controls located in the control room and in the auxiliary electric equipment room, a power supply, and a recombiner located in the reactor building. Recombination is accomplished by heating a hydrogen air mixture to > 1150°F. The resulting water vapor and discharge gases are cooled prior to discharge from the unit. Air flows through the unit at 125 cfm, with a blower in the unit providing the motive force. A single recombiner is capable of maintaining the hydrogen concentration in primary containment below the 4.0 volume percent (v/o) flammability limit. Two recombiners are provided to meet the requirement for redundancy and independence. Each recombiner is powered from a separate Engineered Safety Feature bus and is provided with separate power panel and control panel (with one recombiner powered from Unit 1 and the other recombiner powered from Unit 2).

Emergency operating procedures direct that the hydrogen concentration in primary containment be monitored following a DBA and that the primary containment hydrogen recombiner

(continued)

BASES

BACKGROUND (continued) be manually activated to prevent the primary containment atmosphere from reaching a bulk hydrogen concentration of 4.0 v/o.

APPLICABLE SAFETY ANALYSES The primary containment hydrogen recombiners provide the capability of controlling the bulk hydrogen concentration in primary containment to less than the lower flammable concentration of 4.0 v/o following a DBA. This control would prevent a primary containment wide hydrogen burn, thus ensuring that pressure and temperature conditions assumed in the analysis are not exceeded. The limiting DBA relative to hydrogen generation is a LOCA.

Hydrogen may accumulate in primary containment following a LOCA as a result of:

- a. A metal steam reaction between the zirconium fuel rod cladding and the reactor coolant; or
- b. Radiolytic decomposition of water in the Reactor Coolant System.

To evaluate the potential for hydrogen accumulation in primary containment following a LOCA, the hydrogen generation as a function of time following the initiation of the accident is calculated. Assumptions recommended by Reference 3 were complied with to maximize the amount of hydrogen calculated.

The calculation confirms that when the mitigating systems are actuated in accordance with plant procedures, the peak hydrogen concentration in the primary containment remains < 4 v/o (Ref. 4).

The primary containment hydrogen recombiners satisfy Criterion 3 of 10 CFR 50.36(c)(2)(ii).

LCO Two primary containment hydrogen recombiners must be OPERABLE. This ensures operation of at least one primary containment hydrogen recombiner in the event of a worst case single active failure.

(continued)

BASES

LCO
(continued) Operation with at least one primary containment hydrogen recombinder subsystem ensures that the post LOCA hydrogen concentration can be prevented from exceeding the flammability limit.

APPLICABILITY In MODES 1 and 2, the two primary containment hydrogen recombiners are required to control the hydrogen concentration within primary containment below its flammability limit of 4.0 v/o following a LOCA, assuming a worst case single failure.

In MODE 3, both the hydrogen production rate and the total hydrogen production after a LOCA would be less than that calculated for the DBA LOCA. Also, because of the limited time in this MODE, the probability of an accident requiring the primary containment hydrogen recombinder is low. Therefore, the primary containment hydrogen recombiners are not required in MODE 3.

In MODES 4 and 5, the probability and consequences of a LOCA are low due to the pressure and temperature limitations in these MODES. Therefore, the primary containment hydrogen recombiners are not required in these MODES.

ACTIONS

A.1

With one primary containment hydrogen recombinder inoperable, the inoperable primary containment hydrogen recombinder must be restored to OPERABLE status within 30 days. In this condition, the remaining OPERABLE primary containment recombinder is adequate to perform the hydrogen control function. However, the overall reliability is reduced because a single failure in the OPERABLE recombinder could result in reduced hydrogen control capability. The 30 day Completion Time is based on the low probability of the occurrence of a LOCA that would generate hydrogen in amounts capable of exceeding the flammability limit, the amount of time available after the event for operator action to prevent hydrogen accumulation exceeding this limit, and the low probability of failure of the OPERABLE primary containment hydrogen recombinder.

(continued)

BASES

ACTIONS

A.1 (continued)

Required Action A.1 has been modified by a Note stating that the provisions of LCO 3.0.4 are not applicable. As a result, a MODE change is allowed when one recombinder is inoperable. This allowance is provided because of the low probability of the occurrence of a LOCA that would generate hydrogen in amounts capable of exceeding the flammability limit, the low probability of the failure of the OPERABLE recombinder, and the amount of time available after a postulated LOCA for operator action to prevent exceeding the flammability limit.

B.1 and B.2

With two primary containment hydrogen recombiners inoperable, the ability to perform the hydrogen control function via alternate capabilities must be verified by administrative means within 1 hour. The alternate hydrogen control capabilities are provided by the Primary Containment Vent and Purge System. The 1 hour Completion Time allows a reasonable period of time to verify that a loss of hydrogen control function does not exist. In addition, the alternate hydrogen control system capability must be verified once per 12 hours thereafter to ensure its continued availability. Both the initial verification and all subsequent verifications may be performed as an administrative check by examining logs or other information to determine the availability of the alternate hydrogen control system. It does not mean to perform the Surveillances needed to demonstrate OPERABILITY of the alternate hydrogen control system. If the ability to perform the hydrogen control function is maintained, continued operation is permitted with two hydrogen recombiners inoperable for up to 7 days. Seven days is a reasonable time to allow two hydrogen recombiners to be inoperable because the hydrogen control function is maintained and because of the low probability of the occurrence of a LOCA that would generate hydrogen in the amounts capable of exceeding the flammability limit.

(continued)

BASES

ACTIONS
(continued)

C.1

If any Required Action and associated Completion Time cannot be met, the plant must be brought to a MODE in which the LCO does not apply. To achieve this status, the plant must be brought to at least MODE 3 within 12 hours. The allowed Completion Time of 12 hours is reasonable, based on operating experience, to reach MODE 3 from full power conditions in an orderly manner and without challenging plant systems.

SURVEILLANCE
REQUIREMENTS

SR 3.6.3.1.1

Performance of a system functional test for each primary containment hydrogen recombiner ensures that the recombiners are OPERABLE and can attain and sustain the temperature necessary for hydrogen recombination. In particular, this SR requires verification that the reaction chamber gas temperature increases to $\geq 1175^{\circ}\text{F}$ in ≤ 2 hours and that significant heater elements are not burned out by determining that the current in each phase differs by less than or equal to 5% from the other phases and is within 5% of the value observed in the original acceptance test, corrected for line voltage differences.

Operating experience has shown that these components usually pass the Surveillance when performed at the 24 month Frequency. Therefore, the Frequency was concluded to be acceptable from a reliability standpoint.

SR 3.6.3.1.2

This SR requires performance of a resistance to ground test of each heater phase to ensure that there are no detectable grounds in any heater phase. This is accomplished by verifying that the resistance to ground for any heater phase is $\geq 1.0\text{E}5$ ohms within 30 minutes following completion of SR 3.6.3.1.1.

Operating experience has shown that these components usually pass the Surveillance when performed at the 24 month Frequency. Therefore, the Frequency was concluded to be acceptable from a reliability standpoint.

(continued)

BASES (continued)

- REFERENCES
1. 10 CFR 50.44.
 2. 10 CFR 50, Appendix A, GDC 41.
 3. Regulatory Guide 1.7, Revision 0, March 10, 1971.
 4. UFSAR, Section 6.2.5.
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B 3.6 CONTAINMENT SYSTEMS

B 3.6.3.2 Primary Containment Oxygen Concentration

BASES

BACKGROUND

The primary containment is designed to withstand events that generate hydrogen either due to the zirconium metal water reaction in the core or due to radiolysis. The primary method to control hydrogen is to inert the primary containment. With the primary containment inerted, that is, oxygen concentration < 4.0 volume percent (v/o), a combustible mixture cannot be present in the primary containment for any hydrogen concentration. The capability to inert the primary containment and maintain oxygen < 4.0 v/o works together with the Hydrogen Recombiner System (LCO 3.6.3.1, "Primary Containment Hydrogen Recombiners") to provide redundant and diverse methods to mitigate events that produce hydrogen. For example, an event that rapidly generates hydrogen from zirconium metal water reaction will result in excessive hydrogen in primary containment, but oxygen concentration will remain < 4.0 v/o and no combustion can occur. Long term generation of both hydrogen and oxygen from radiolytic decomposition of water may eventually result in a combustible mixture in primary containment, except that the hydrogen recombiners remove hydrogen and oxygen gases faster than they can be produced from radiolysis and again no combustion can occur. This LCO ensures that oxygen concentration does not exceed 4.0 v/o during operation in the applicable conditions.

APPLICABLE
SAFETY ANALYSES

The Reference 1 calculations assume that the primary containment is inerted when a Design Basis Accident loss of coolant accident occurs. Thus, the hydrogen assumed to be released to the primary containment as a result of metal water reaction in the reactor core will not produce combustible gas mixtures in the primary containment. Oxygen, which is subsequently generated by radiolytic decomposition of water, is recombined by the hydrogen recombiners (LCO 3.6.3.1) more rapidly than it is produced.

Primary containment oxygen concentration satisfies Criterion 2 of 10 CFR 50.36(c)(2)(ii).

(continued)

BASES (continued)

LCO The primary containment oxygen concentration is maintained < 4.0 v/o to ensure that an event that produces any amount of hydrogen does not result in a combustible mixture inside primary containment.

APPLICABILITY The primary containment oxygen concentration must be within the specified limit when primary containment is inerted, except as allowed by the relaxations during startup and shutdown addressed below. The primary containment must be inert in MODE 1, since this is the condition with the highest probability of an event that could produce hydrogen.

Inerting the primary containment is an operational problem because it prevents containment access without an appropriate breathing apparatus. Therefore, the primary containment is inerted as late as possible in the plant startup and de-inerted as soon as possible in the plant shutdown. As long as reactor power is < 15% RTP, the potential for an event that generates significant hydrogen is low and the primary containment need not be inert. Furthermore, the probability of an event that generates hydrogen occurring within the first 24 hours of a startup, or within the last 24 hours before a shutdown, is low enough that these "windows," when the primary containment is not inerted, are also justified. The 24 hour time period is a reasonable amount of time to allow plant personnel to perform inerting or de-inerting.

ACTIONS

A.1

If oxygen concentration is ≥ 4.0 v/o at any time while operating in MODE 1, with the exception of the relaxations allowed during startup and shutdown, oxygen concentration must be restored to < 4.0 v/o within 24 hours. The 24 hour Completion Time is allowed when oxygen concentration is ≥ 4.0 v/o because of the availability of other hydrogen mitigating systems (e.g., hydrogen recombiners) and the low probability and long duration of an event that would generate significant amounts of hydrogen occurring during this period.

(continued)

BASES

ACTIONS
(continued)

B.1

If oxygen concentration cannot be restored to within limits within the required Completion Time, the plant must be brought to a MODE in which the LCO does not apply. To achieve this status, power must be reduced to $\leq 15\%$ RTP within 8 hours. The 8 hour Completion Time is reasonable, based on operating experience, to reduce reactor power from full power conditions in an orderly manner and without challenging plant systems.

SURVEILLANCE
REQUIREMENTS

SR 3.6.3.2.1

The primary containment must be determined to be inerted by verifying that oxygen concentration is < 4.0 v/o. The 7 day Frequency is based on the slow rate at which oxygen concentration can change and on other indications of abnormal conditions (which could lead to more frequent checking by operators in accordance with plant procedures). Also, this Frequency has been shown to be acceptable through operating experience.

REFERENCES

1. UFSAR, Section 6.2.5.
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B 3.6 CONTAINMENT SYSTEMS

B 3.6.4.1 Secondary Containment

BASES

BACKGROUND

The function of the secondary containment is to contain dilute, and hold up fission products that may leak from primary containment following a Design Basis Accident (DBA). In conjunction with operation of the Standby Gas Treatment (SGT) System and closure of certain valves whose lines penetrate the secondary containment, the secondary containment is designed to reduce the activity level of the fission products prior to release to the environment and to isolate and contain fission products that are released during certain operations that take place inside primary containment, when primary containment is not required to be OPERABLE, or that take place outside primary containment.

The secondary containment is a structure that completely encloses the primary containment and those components that may be postulated to contain primary system fluid. This structure forms a control volume that serves to hold up and dilute the fission products. It is possible for the pressure in the control volume to rise relative to the environmental pressure (e.g., due to pump/motor heat load additions). To prevent ground level exfiltration while allowing the secondary containment to be designed as a conventional structure, the secondary containment requires support systems to maintain the control volume pressure at less than the external pressure. Requirements for these systems are specified separately in LCO 3.6.4.2, "Secondary Containment Isolation Valves (SCIVs)," and LCO 3.6.4.3, "Standby Gas Treatment (SGT) System."

APPLICABLE
SAFETY ANALYSES

There are two principal accidents for which credit is taken for secondary containment OPERABILITY. These are a LOCA (Ref. 1) and a fuel handling accident (Ref. 2). The secondary containment performs no active function in response to each of these limiting events; however, its leak tightness is required to ensure that the release of radioactive materials from the primary containment is restricted to those leakage paths and associated leakage rates assumed in the accident analysis, and that fission products entrapped within the secondary containment

(continued)

BASES

APPLICABLE
SAFETY ANALYSES
(continued)

structure will be treated by the SGT System prior to discharge to the environment.

Secondary containment satisfies Criterion 3 of 10 CFR 50.36(c)(2)(ii).

LCO

An OPERABLE secondary containment provides a control volume into which fission products that bypass or leak from primary containment, or are released from the reactor coolant pressure boundary components located in secondary containment, can be diluted and processed prior to release to the environment. For the secondary containment to be considered OPERABLE, it must have adequate leak tightness to ensure that the required vacuum can be established and maintained, the hatches and blowout panels must be closed and sealed, the sealing mechanisms associated with each secondary containment penetration (e.g., welds, bellows, or O-rings) must be OPERABLE (such that secondary containment leak tightness can be maintained), and all inner or all outer doors in each secondary containment access opening must be closed.

APPLICABILITY

In MODES 1, 2, and 3, a LOCA could lead to a fission product release to primary containment that leaks to secondary containment. Therefore, secondary containment OPERABILITY is required during the same operating conditions that require primary containment OPERABILITY.

In MODES 4 and 5, the probability and consequences of the LOCA are reduced due to the pressure and temperature limitations in these MODES. Therefore, maintaining secondary containment OPERABLE is not required in MODE 4 or 5 to ensure a control volume, except for other situations for which significant releases of radioactive material can be postulated, such as during operations with a potential for draining the reactor vessel (OPDRVs), during CORE ALTERATIONS, or during movement of irradiated fuel assemblies in the secondary containment.

(continued)

BASES (continued)

ACTIONS

A.1

If secondary containment is inoperable, it must be restored to OPERABLE status within 4 hours. The 4 hour Completion Time provides a period of time to correct the problem that is commensurate with the importance of maintaining secondary containment during MODES 1, 2, and 3. This time period also ensures that the probability of an accident (requiring secondary containment OPERABILITY) occurring during periods where secondary containment is inoperable is minimal.

B.1 and B.2

If the secondary containment cannot be restored to OPERABLE status within the required Completion Time, the plant must be brought to a MODE in which the LCO does not apply. To achieve this status, the plant must be brought to at least MODE 3 within 12 hours and to MODE 4 within 36 hours. The allowed Completion Times are reasonable, based on operating experience, to reach the required plant conditions from full power conditions in an orderly manner and without challenging plant systems.

C.1, C.2, and C.3

Movement of irradiated fuel assemblies in the secondary containment, CORE ALTERATIONS, and OPDRVs can be postulated to cause fission product release to the secondary containment. In such cases, the secondary containment is the only barrier to release of fission products to the environment. CORE ALTERATIONS and movement of irradiated fuel assemblies must be immediately suspended if the secondary containment is inoperable.

Suspension of these activities shall not preclude completing an action that involves moving a component to a safe position. Also, action must be immediately initiated to suspend OPDRVs to minimize the probability of a vessel draindown and subsequent potential for fission product release. Actions must continue until OPDRVs are suspended.

(continued)

BASES

ACTIONS

C.1, C.2, and C.3 (continued)

Required Action C.1 has been modified by a Note stating that LCO 3.0.3 is not applicable. If moving irradiated fuel assemblies while in MODE 4 or 5, LCO 3.0.3 would not specify any action. If moving irradiated fuel assemblies while in MODE 1, 2, or 3, the fuel movement is independent of reactor operations. Therefore, in either case, inability to suspend movement of irradiated fuel assemblies would not be a sufficient reason to require a reactor shutdown.

SURVEILLANCE
REQUIREMENTS

SR 3.6.4.1.1

This SR ensures that the secondary containment boundary is sufficiently leak tight to preclude exfiltration. The 24 hour Frequency of this SR was developed based on operating experience related to secondary containment vacuum variations during the applicable MODES and the low probability of a DBA occurring.

Furthermore, the 24 hour Frequency is considered adequate in view of other indications available in the control room, including alarms, to alert the operator to an abnormal secondary containment vacuum condition.

SR 3.6.4.1.2 and SR 3.6.4.1.5

Verifying that one secondary containment access door in each access opening is closed and each equipment hatch is closed and sealed ensures that the infiltration of outside air of such a magnitude as to prevent maintaining the desired negative pressure does not occur. Verifying that all such openings are closed provides adequate assurance that exfiltration from the secondary containment will not occur. In this application, the term "sealed" has no connotation of leak tightness. In addition, for equipment hatches that are floor plugs, the "sealed" requirement is effectively met by gravity. Maintaining secondary containment OPERABILITY requires verifying one door in the access opening is closed. An access opening contains one inner and one outer door. In some cases a secondary containment barrier contains multiple inner or multiple outer doors. For these cases, the access openings share the inner door or the outer door, i.e., the access openings have

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BASES

SURVEILLANCE
REQUIREMENTS

SR 3.6.4.1.2 and SR 3.6.4.1.5 (continued)

a common inner door or outer door. The intent is to not breach the secondary containment at any time when secondary containment is required. This is achieved by maintaining the inner or outer portion of the barrier closed at all times, i.e., all inner doors closed or all outer doors closed. Thus each access opening has one door closed. However, each secondary containment access door is normally kept closed, except when the access opening is being used for entry and exit or when maintenance is being performed on the access opening. The 31 day Frequency for SR 3.6.4.1.2 has been shown to be adequate based on operating experience, and is considered adequate in view of the existing administrative controls on door status. The 24 month Frequency for SR 3.6.4.1.5 is considered adequate in view of the existing administrative controls on equipment hatches.

SR 3.6.4.1.3 and SR 3.6.4.1.4

The SGT System exhausts the secondary containment atmosphere to the environment through appropriate treatment equipment. Each SGT subsystem is designed to drawdown pressure in the secondary containment to ≥ 0.25 inches of vacuum water gauge in ≤ 300 seconds and maintain pressure in the secondary containment at ≥ 0.25 inches of vacuum water gauge for 1 hour at a flow rate of ≤ 4400 cfm. To ensure that all fission products released to secondary containment are treated, SR 3.6.4.1.3 and SR 3.6.4.1.4 verify that a pressure in the secondary containment that is less than the pressure external to the secondary containment boundary can rapidly be established and maintained. When the SGT System is operating as designed, the establishment and maintenance of secondary containment pressure cannot be accomplished if the secondary containment boundary is not intact. Establishment of this pressure is confirmed by SR 3.6.4.1.3, which demonstrates that the secondary containment can be drawn down to ≥ 0.25 inches of vacuum water gauge in ≤ 300 seconds using one SGT subsystem. SR 3.6.4.1.4 demonstrates that the pressure in the secondary containment can be maintained ≥ 0.25 inches of vacuum water gauge for 1 hour using one SGT subsystem at a flow rate ≤ 4400 cfm. This flow rate is the assumed secondary containment leak rate during the drawdown period. The 1 hour test period allows secondary containment to be in thermal equilibrium at

(continued)

BASES

SURVEILLANCE
REQUIREMENTS

SR 3.6.4.1.3 and SR 3.6.4.1.4 (continued)

steady state conditions. The primary purpose of the SRs is to ensure secondary containment boundary integrity. The secondary purpose of these SRs is to ensure that the SGT subsystem being tested functions as designed. There is a separate LCO with Surveillance Requirements that serves the primary purpose of ensuring OPERABILITY of the SGT System. These SRs need not be performed with each SGT subsystem. The SGT subsystem used for these Surveillances is staggered to ensure that in addition to the requirements of LCO 3.6.4.3, either SGT subsystem will perform this test. The inoperability of the SGT System does not necessarily constitute a failure of these Surveillances relative to secondary containment OPERABILITY. Operating experience has shown the secondary containment boundary usually passes these Surveillances when performed at the 24 month Frequency. Therefore the Frequency was concluded to be acceptable from a reliability standpoint.

REFERENCES

1. UFSAR, Section 15.6.5.
 2. UFSAR, Section 15.7.4.
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B 3.6 CONTAINMENT SYSTEMS

B 3.6.4.2 Secondary Containment Isolation Valves (SCIVs)

BASES

BACKGROUND

The function of the SCIVs, in combination with other accident mitigation systems, is to limit fission product release during and following postulated Design Basis Accidents (DBAs) (Refs. 1 and 2). Secondary containment isolation within the time limits specified for those isolation valves designed to close automatically ensures that fission products that leak from primary containment following a DBA, that are released during certain operations when primary containment is not required to be OPERABLE, or that take place outside primary containment, are maintained within the secondary containment boundary.

The OPERABILITY requirements for SCIVs help ensure that an adequate secondary containment boundary is maintained during and after an accident by minimizing potential paths to the environment. These isolation devices are either passive or active (automatic). Manual valves, de-activated automatic valves secured in their closed position (including check valves with flow through the valve secured), and blind flanges are considered passive devices.

Automatic SCIVs (i.e., dampers) close on a secondary containment isolation signal to establish a boundary for untreated radioactive material within secondary containment following a DBA or other accidents.

Other penetrations required to be closed during accident conditions are isolated by the use of valves in the closed position or blind flanges.

APPLICABLE SAFETY ANALYSES

The SCIVs must be OPERABLE to ensure the secondary containment barrier to fission product releases is established. The principal accidents for which the secondary containment boundary is required are a loss of coolant accident (Ref. 1) and fuel handling accident (Ref. 2). The secondary containment performs no active function in response to each of these limiting events, but

(continued)

BASES

APPLICABLE SAFETY ANALYSES (continued) the boundary established by SCIVs is required to ensure that leakage from the primary containment is processed by the Standby Gas Treatment (SGT) System before being released to the environment.

Maintaining SCIVs OPERABLE with isolation times within limits ensures that fission products will remain trapped inside secondary containment so that they can be treated by the SGT System prior to discharge to the environment.

SCIVs satisfy Criterion 3 of 10 CFR 50.36(c)(2)(ii).

LCO SCIVs form a part of the secondary containment boundary. The SCIV safety function is related to control of offsite radiation releases resulting from DBAs.

The power operated, automatic isolation valves are considered OPERABLE when their isolation times are within limits and the valves actuate on an automatic isolation signal. The valves covered by this LCO, along with their associated stroke times, are listed in the Technical Requirements Manual (Ref. 3).

The normally closed manual SCIVs are considered OPERABLE when the valves are closed and blind flanges are in place, or open under administrative controls. These passive isolation valves or devices are listed in Reference 3.

APPLICABILITY In MODES 1, 2, and 3, a DBA could lead to a fission product release to the primary containment that leaks to the secondary containment. Therefore, OPERABILITY of SCIVs is required.

In MODES 4 and 5, the probability and consequences of these events are reduced due to pressure and temperature limitations in these MODES. Therefore, maintaining SCIVs OPERABLE is not required in MODE 4 or 5, except for other situations under which significant releases of radioactive material can be postulated, such as during operations with a potential for draining the reactor vessel (OPDRVs), during CORE ALTERATIONS, or during movement of irradiated fuel assemblies in the secondary containment.

(continued)

BASES (continued)

ACTIONS

The ACTIONS are modified by three Notes. The first Note allows penetration flow paths to be unisolated intermittently under administrative controls. These controls consist of stationing a dedicated operator, who is in continuous communication with the control room, at the controls of the isolation device. In this way, the penetration can be rapidly isolated when the need for secondary containment isolation is indicated.

The second Note provides clarification that, for the purpose of this LCO, separate Condition entry is allowed for each penetration flow path. This is acceptable, since the Required Actions for each Condition provide appropriate compensatory actions for each inoperable SCIV. Complying with the Required Actions may allow for continued operation, and subsequent inoperable SCIVs are governed by subsequent Condition entry and application of associated Required Actions.

The third Note ensures appropriate remedial actions are taken, if necessary, if the affected system(s) are rendered inoperable by an inoperable SCIV.

A.1 and A.2

In the event that there are one or more penetration flow paths with one SCIV inoperable, the affected penetration flow path(s) must be isolated. The method of isolation must include the use of at least one isolation barrier that cannot be adversely affected by a single active failure. Isolation barriers that meet this criteria are a closed and de-activated automatic SCIV, a closed manual valve, and a blind flange. For penetrations isolated in accordance with Required Action A.1, the device used to isolate the penetration should be the closest available device to secondary containment. This Required Action must be completed within the 8 hour Completion Time. The specified time period is reasonable considering the time required to isolate the penetration and the low probability of a DBA, which requires the SCIVs to close, occurring during this short time.

(continued)

BASES

ACTIONS

A.1 and A.2 (continued)

For affected penetrations that have been isolated in accordance with Required Action A.1, the affected penetration must be verified to be isolated on a periodic basis. This is necessary to ensure that secondary containment penetrations required to be isolated following an accident, but no longer capable of being automatically isolated, will be in the isolation position should an event occur. The Completion Time of once per 31 days is appropriate because the isolation devices are operated under administrative controls and the probability of their misalignment is low. This Required Action does not require any testing or device manipulation. Rather, it involves verification that the affected penetration remains isolated.

Required Action A.2 is modified by two Notes. Note 1 applies to isolation devices located in high radiation areas and allows them to be verified by use of administrative controls. Allowing verification by administrative controls is considered acceptable, since access to these areas is typically restricted. Note 2 applies to isolation devices that are locked, sealed, or otherwise secured in position and allows these devices to be verified closed by use of administrative means. Allowing verification by administrative means is considered acceptable, since the function of locking, sealing, or securing components is to ensure that these devices are not inadvertently repositioned. Therefore, the probability of misalignment, once they have been verified to be in the proper position, is low.

B.1

With two SCIVs in one or more penetration flow paths inoperable, the affected penetration flow path must be isolated within 4 hours. The method of isolation must include the use of at least one isolation barrier that cannot be adversely affected by a single active failure. Isolation barriers that meet this criterion are a closed and de-activated automatic valve, a closed manual valve, and a blind flange. The 4 hour Completion Time is reasonable, considering the time required to isolate the penetration and the low probability of a DBA, which requires the SCIVs to close, occurring during this short time.

(continued)

BASES

ACTIONS

B.1 (continued)

The Condition has been modified by a Note stating that Condition B is only applicable to penetration flow paths with two isolation valves. This clarifies that only Condition A is entered if one SCIV is inoperable in each of two penetrations.

C.1 and C.2

If any Required Action and associated Completion Time cannot be met, the plant must be brought to a MODE in which the LCO does not apply. To achieve this status, the plant must be brought to at least MODE 3 within 12 hours and to MODE 4 within 36 hours. The allowed Completion Times are reasonable, based on operating experience, to reach the required plant conditions from full power conditions in an orderly manner and without challenging plant systems.

D.1, D.2, and D.3

If any Required Action and associated Completion Time cannot be met, the plant must be placed in a condition in which the LCO does not apply. If applicable, CORE ALTERATIONS and the movement of irradiated fuel assemblies in the secondary containment must be immediately suspended. Suspension of these activities shall not preclude completion of movement of a component to a safe position. Also, if applicable, action must be immediately initiated to suspend OPDRVs in order to minimize the probability of a vessel draindown and the subsequent potential for fission product release. Actions must continue until OPDRVs are suspended.

Required Action D.1 has been modified by a Note stating that LCO 3.0.3 is not applicable. If moving irradiated fuel assemblies while in MODE 4 or 5, LCO 3.0.3 would not specify any action. If moving irradiated fuel assemblies while in MODE 1, 2, or 3, the fuel movement is independent of reactor operations. Therefore, in either case, inability to suspend movement of irradiated fuel assemblies would not be a sufficient reason to require a reactor shutdown.

(continued)

BASES (continued)

SURVEILLANCE
REQUIREMENTS

SR 3.6.4.2.1

This SR verifies each secondary containment isolation manual valve and blind flange that is not locked, sealed, or otherwise secured and is required to be closed during accident conditions is closed. The SR helps to ensure that post accident leakage of radioactive fluids or gases outside of the secondary containment boundary is within design limits. This SR does not require any testing or valve manipulation. Rather, it involves verification that those SCIVs in secondary containment that are capable of being mispositioned are in the correct position.

Since these SCIVs are readily accessible to personnel during normal unit operation and verification of their position is relatively easy, the 31 day Frequency was chosen to provide added assurance that the SCIVs are in the correct positions. This SR does not apply to valves that are locked, sealed, or otherwise secured in the closed position, since these were verified to be in the correct position upon locking, sealing, or securing.

Two Notes have been added to this SR. The first Note applies to valves and blind flanges located in high radiation areas and allows them to be verified by use of administrative controls. Allowing verification by administrative controls is considered acceptable, since access to these areas is typically restricted during MODES 1, 2, and 3 for ALARA reasons. Therefore, the probability of misalignment of these SCIVs, once they have been verified to be in the proper position, is low.

A second Note has been included to clarify that SCIVs that are open under administrative controls are not required to meet the SR during the time the SCIVs are open. These controls consist of stationing a dedicated operator at the controls of the valve, who is in continuous communication with the control room. In this way, the penetration can be rapidly isolated when a need for secondary containment isolation is indicated.

(continued)

BASES

SURVEILLANCE
REQUIREMENTS
(continued)

SR 3.6.4.2.2

Verifying the isolation time of each power operated, automatic SCIV is within limits is required to demonstrate OPERABILITY. The isolation time test ensures that the SCIV will isolate in a time period less than or equal to that assumed in the safety analyses. The Frequency of this SR is 92 days.

SR 3.6.4.2.3

Verifying that each automatic SCIV closes on a secondary containment isolation signal is required to prevent leakage of radioactive material from secondary containment following a DBA or other accidents. This SR ensures that each automatic SCIV will actuate to the isolation position on a secondary containment isolation signal. The LOGIC SYSTEM FUNCTIONAL TEST in LCO 3.3.6.2, "Secondary Containment Isolation Instrumentation," overlaps this SR to provide complete testing of the safety function. While this Surveillance can be performed with the reactor at power, operating experience has shown these components usually pass the Surveillance when performed at the 24 month Frequency, which is based on the refueling cycle. Therefore, the Frequency was concluded to be acceptable from a reliability standpoint.

REFERENCES

1. UFSAR, Section 15.6.5.
 2. UFSAR, Section 15.7.4.
 3. Technical Requirements Manual.
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B 3.6 CONTAINMENT SYSTEMS

B 3.6.4.3 Standby Gas Treatment (SGT) System

BASES

BACKGROUND The SGT System is required by 10 CFR 50, Appendix A, GDC 41, "Containment Atmosphere Cleanup" (Ref. 1). The function of the SGT System is to ensure that radioactive materials that leak from the primary containment into the secondary containment following a Design Basis Accident (DBA) are filtered and adsorbed prior to exhausting to the environment.

The SGT System consists of two independent subsystems that are shared between Unit 1 and Unit 2, each with its own set of ductwork, dampers, charcoal filter train, and controls. Each SGT System discharges to the plant vent stack through a common exhaust pipe.

Each charcoal filter train consists of (components listed in order of the direction of the air flow):

- a. A centrifugal filter unit fan and centrifugal cooling fan;
- b. A demister;
- c. An electric heater;
- d. A prefilter bank;
- e. A high efficiency particulate air (HEPA) filter bank;
- f. A charcoal adsorber; and
- g. A second HEPA filter bank.

The sizing of the SGT System equipment and components is based on the results of an infiltration analysis. Each SGT subsystem is capable of processing the secondary containment volume, which includes both Unit 1 and Unit 2. The internal pressure of the SGT System boundary region is maintained at a negative pressure of 0.25 inch water gauge when the system is in operation, which represents the internal pressure required to ensure zero exfiltration of air from the building.

(continued)

BASES

BACKGROUND
(continued)

The demister is provided to remove entrained water in the air, while the electric heater reduces the relative humidity of the airstream to $\leq 70\%$ (Ref. 2). The prefilter removes large particulate matter, while the HEPA filter is provided to remove fine particulate matter and protect the charcoal from fouling. The charcoal adsorber removes gaseous elemental iodine and organic iodides, and the final HEPA filter is provided to collect any carbon fines exhausted from the charcoal adsorber.

The SGT System automatically starts and operates in response to actuation signals from either Unit 1 or Unit 2 indicative of conditions or an accident that could require operation of the system. Following initiation, both supply fans start. SGT System flows are controlled automatically by flow control dampers located up stream of the supply fans.

APPLICABLE
SAFETY ANALYSES

The design basis for the SGT System is to mitigate the consequences of a loss of coolant accident and fuel handling accidents (Refs. 3 and 4). For all events analyzed, the SGT System is shown to be automatically initiated to reduce, via filtration and adsorption, the radioactive material released to the environment.

The SGT System satisfies Criterion 3 of 10 CFR 50.36(c)(2)(ii).

LCO

Following a DBA, a minimum of one SGT subsystem is required to maintain the secondary containment at a negative pressure with respect to the environment and to process gaseous releases. Meeting the LCO requirements for two OPERABLE subsystems ensures operation of at least one SGT subsystem in the event of a single active failure.

APPLICABILITY

In MODES 1, 2, and 3, a DBA could lead to a fission product release to primary containment that leaks to secondary containment. Therefore, SGT System OPERABILITY is required during these MODES.

In MODES 4 and 5, the probability and consequences of these events are reduced due to the pressure and temperature limitations in these MODES. Therefore, maintaining the SGT System OPERABLE is not required in MODE 4 or 5, except for

(continued)

BASES

APPLICABILITY (continued) other situations under which significant releases of radioactive material can be postulated, such as during operations with a potential for draining the reactor vessel (OPDRVs), during CORE ALTERATIONS, or during movement of irradiated fuel assemblies in the secondary containment.

ACTIONS

A.1

With one SGT subsystem inoperable, the inoperable subsystem must be restored to OPERABLE status within 7 days. In this condition, the remaining OPERABLE SGT subsystem is adequate to perform the required radioactivity release control function. However, the overall system reliability is reduced because a single failure in the OPERABLE subsystem could result in the radioactivity release control function not being adequately performed. The 7 day Completion Time is based on consideration of such factors as the availability of the OPERABLE redundant SGT subsystem and the low probability of a DBA occurring during this period.

B.1 and B.2

If the SGT subsystem cannot be restored to OPERABLE status within the required Completion Time in MODE 1, 2, or 3, the plant must be brought to a MODE in which the LCO does not apply. To achieve this status, the plant must be brought to at least MODE 3 within 12 hours and to MODE 4 within 36 hours. The allowed Completion Times are reasonable, based on operating experience, to reach the required plant conditions from full power conditions in an orderly manner and without challenging plant systems.

C.1, C.2.1, C.2.2, and C.2.3

During movement of irradiated fuel assemblies in the secondary containment, during CORE ALTERATIONS, or during OPDRVs, when Required Action A.1 cannot be completed within the required Completion Time, the OPERABLE SGT subsystem should be immediately placed in operation. This Required Action ensures that the remaining subsystem is OPERABLE, that no failures that could prevent automatic actuation will occur, and that any other failure would be readily detected.

(continued)

BASES

ACTIONS

C.1, C.2.1, C.2.2, and C.2.3 (continued)

An alternative to Required Action C.1 is to immediately suspend activities that represent a potential for releasing radioactive material to the secondary containment, thus placing the unit in a condition that minimizes risk. If applicable, CORE ALTERATIONS and movement of irradiated fuel assemblies must be immediately suspended. Suspension of these activities shall not preclude completion of movement of a component to a safe position. Also, if applicable, action must be immediately initiated to suspend OPDRVs to minimize the probability of a vessel draindown and subsequent potential for fission product release. Action must continue until OPDRVs are suspended.

The Required Actions of Condition C have been modified by a Note stating that LCO 3.0.3 is not applicable. If moving irradiated fuel assemblies while in MODE 4 or 5, LCO 3.0.3 would not specify any action. If moving irradiated fuel assemblies while in MODE 1, 2, or 3, the fuel movement is independent of reactor operations. Therefore, in either case, inability to suspend movement of irradiated fuel assemblies would not be a sufficient reason to require a reactor shutdown.

D.1

If both SGT subsystems are inoperable in MODE 1, 2, or 3, the SGT system may not be capable of supporting the required radioactivity release control function. Therefore, actions are required to enter LCO 3.0.3 immediately.

E.1, E.2, and E.3

When two SGT subsystems are inoperable, if applicable, CORE ALTERATIONS and movement of irradiated fuel assemblies in the secondary containment must be immediately suspended. Suspension of these activities shall not preclude completion of movement of a component to a safe position. Also, if applicable, action must be immediately initiated to suspend OPDRVs to minimize the probability of a vessel draindown and subsequent potential for fission product release. Action must continue until OPDRVs are suspended.

(continued)

BASES

ACTIONS

E.1, E.2, and E.3 (continued)

Required Action E.1 has been modified by a Note stating that LCO 3.0.3 is not applicable. If moving irradiated fuel assemblies while in MODE 4 or 5, LCO 3.0.3 would not specify any action. If moving irradiated fuel assemblies while in MODE 1, 2, or 3, the fuel movement is independent of reactor operations. Therefore, in either case, inability to suspend movement of irradiated fuel assemblies would not be a sufficient reason to require a reactor shutdown.

SURVEILLANCE
REQUIREMENTS

SR 3.6.4.3.1

Operating (from the control room) each SGT subsystem for ≥ 10 continuous hours ensures that both subsystems are OPERABLE and that all associated controls are functioning properly. It also ensures that blockage, fan or motor failure, or excessive vibration can be detected for corrective action. Operation with the heaters on for ≥ 10 continuous hours every 31 days eliminates moisture on the adsorbers and HEPA filters. The 31 day Frequency was developed in consideration of the known reliability of fan motors and controls and the redundancy available in the system.

SR 3.6.4.3.2

This SR verifies that the required SGT filter testing is performed in accordance with the Ventilation Filter Testing Program (VFTP). The SGT System filter tests are in accordance with ANSI/ASME N510-1989 (Ref. 5). The VFTP includes testing HEPA filter performance, charcoal adsorber efficiency, minimum system flow rate, and the physical properties of the activated charcoal (general use and following specific operations). Specified test frequencies and additional information are discussed in detail in the VFTP.

(continued)

BASES

SURVEILLANCE
REQUIREMENTS
(continued)

SR 3.6.4.3.3

This SR requires verification that each SGT subsystem starts upon receipt of an actual or simulated initiation signal. The LOGIC SYSTEM FUNCTIONAL TEST in LCO 3.3.6.2, "Secondary Containment Isolation Instrumentation," overlaps this SR to provide complete testing of the safety function. While this Surveillance can be performed with the reactor at power, operating experience has shown these components usually pass the Surveillance when performed at the 24 month Frequency, which is based on the refueling cycle. Therefore, the Frequency was concluded to be acceptable from a reliability standpoint.

REFERENCES

1. 10 CFR 50, Appendix A, GDC 41.
 2. UFSAR, Section 6.5.1.
 3. UFSAR, Section 15.6.5.
 4. UFSAR, Section 15.7.4
 5. ANSI/ASME N510-1989.
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B 3.7 PLANT SYSTEMS

B 3.7.1 Residual Heat Removal Service Water (RHRSW) System

BASES

BACKGROUND The RHRSW System is designed to provide cooling water for the Residual Heat Removal (RHR) System heat exchangers, required for a safe reactor shutdown following a Design Basis Accident (DBA) or transient. The RHRSW System is operated whenever the RHR heat exchangers are required to operate in the shutdown cooling mode or in the suppression pool cooling or spray mode of the RHR System. The RHRSW System also provides cooling water to the RHR pump seal coolers which are required for RHR pump operation during the shutdown cooling mode in MODE 3.

The RHRSW System consists of two independent and redundant subsystems. Each subsystem is made up of two pumps (together capable of providing a nominal flow of 7400 gpm), a suction source, valves, piping, heat exchanger, and associated instrumentation. Either of the two subsystems is capable of providing the required cooling capacity with both pumps operating to maintain safe shutdown conditions. The two subsystems are separated from each other so that failure of one subsystem will not affect the OPERABILITY of the other subsystem. The RHRSW System is designed with sufficient redundancy so that no single active component failure can prevent it from achieving its design function. The RHRSW System is described in the UFSAR, Section 9.2.1, Reference 1.

The RHRSW and the Diesel Generator Cooling Water subsystems are subsystems to the Core Standby Cooling System (CSCS) - Equipment Cooling Water System (ECWS). The CSCS - ECWS consists of three independent piping subsystems corresponding to essential electrical power supply Divisions 1, 2, and 3. The CSCS - ECWS subsystems take suction from the service water tunnel located in the Lake Screen House. The RHRSW subsystems are manually initiated. Cooling water is then pumped from the service water tunnel by the RHRSW pumps to the supported system and components (RHR heat exchangers and RHR pump seal coolers). After removing heat from its supported systems and components, the water from the RHRSW subsystem is discharged to the CSCS Pond (i.e., the Ultimate Heat Sink) through a discharge line that is

(continued)

BASES

BACKGROUND (continued) common to the corresponding divisional discharge from the other unit. The discharge line terminates in the discharge structure at an elevation above the normal CSCS Pond level.

The system is initiated manually from the control room. In addition, the Division 2 RHRSW subsystem may be initiated manually from the remote shutdown panel in the auxiliary electric equipment room. If operating during a loss of offsite power, the system is automatically load shed to allow the diesel generators to automatically power only that equipment necessary to reflood the core. The system can be manually started any time after the LOCA.

APPLICABLE SAFETY ANALYSES The RHRSW System removes heat from the suppression pool to limit the suppression pool temperature and primary containment pressure following a LOCA. This ensures that the primary containment can perform its function of limiting the release of radioactive materials to the environment following a LOCA. The ability of the RHRSW System to support long term cooling of the reactor or primary containment is discussed in the UFSAR, Chapters 6 and 15 (Refs. 2 and 3, respectively). These analyses explicitly assume that the RHRSW System will provide adequate cooling support to the equipment required for safe shutdown. These analyses include the evaluation of the long term primary containment response after a design basis LOCA.

The safety analyses for long term cooling were performed for various combinations of RHR System failures. The worst case single failure that would affect the performance of the RHRSW System is any failure that would disable one subsystem of the RHRSW System. As discussed in the UFSAR, Section 6.2.2.3.1 (Ref. 4) for these analyses, manual initiation of the OPERABLE RHRSW subsystem and the associated RHR System is assumed to occur 10 minutes after a DBA. The RHRSW flow assumed in the analyses is 7400 gpm with two pumps operating in one loop. In this case, the maximum suppression chamber water temperature and pressure are 200°F and 30.6 psig, respectively, well below the design temperature of 275°F and maximum design pressure of 45 psig.

The RHRSW System satisfies Criterion 3 of 10 CFR 50.36(c)(2)(ii).

(continued)

BASES (continued)

LCO Two RHR SW subsystems are required to be OPERABLE to provide the required redundancy to ensure that the system functions to remove post accident heat loads, assuming the worst case single active failure occurs coincident with the loss of offsite power.

An RHR SW subsystem is considered OPERABLE when:

- a. Two pumps are OPERABLE; and
- b. An OPERABLE flow path is capable of taking suction from the CSCS service water tunnel and transferring the water to the associated RHR heat exchanger at the assumed flow rate.

An adequate suction source is not addressed in this LCO since the minimum net positive suction head and the maximum suction source temperature are covered by the requirements specified in LCO 3.7.3, "Ultimate Heat Sink (UHS)."

APPLICABILITY In MODES 1, 2, and 3, the RHR SW System is required to be OPERABLE to support the OPERABILITY of the RHR System for primary containment cooling (LCO 3.6.2.3, "Residual Heat Removal (RHR) Suppression Pool Cooling" and decay heat removal (LCO 3.4.9, "Residual Heat Removal (RHR) Shutdown Cooling System—Hot Shutdown"). The Applicability is therefore consistent with the requirements of these systems.

In MODES 4 and 5, the OPERABILITY requirements of the RHR SW System are determined by the systems it supports and therefore, the requirements are not the same for all facets of operation in MODES 4 and 5. Thus, the LCOs of the RHR Shutdown Cooling System (LCO 3.4.10, "Residual Heat Removal (RHR) Shutdown Cooling System—Cold Shutdown," LCO 3.9.8, "Residual Heat Removal (RHR)—High Water Level," and LCO 3.9.9, "Residual Heat Removal (RHR)—Low Water Level"), which require portions of the RHR SW System to be OPERABLE, will govern RHR SW System operation in MODES 4 and 5.

(continued)

BASES (continued)

ACTIONS

A.1

Required Action A.1 is intended to handle the inoperability of one RHRSW subsystem. The Completion Time of 7 days is allowed to restore the RHRSW subsystem to OPERABLE status. With the unit in this condition, the remaining OPERABLE RHRSW subsystem is adequate to perform the RHRSW heat removal function. However, the overall reliability is reduced because a single failure in the OPERABLE RHRSW subsystem could result in loss of RHRSW function. The Completion Time is based on the redundant RHRSW capabilities afforded by the OPERABLE subsystem and the low probability of an event occurring requiring RHRSW during this period.

The Required Action is modified by a Note indicating that the applicable Conditions of LCO 3.4.9, be entered and Required Actions taken if the inoperable RHRSW subsystem results in inoperable RHR shutdown cooling. This is an exception to LCO 3.0.6 and ensures the proper actions are taken for these components.

B.1

With both RHRSW subsystems inoperable (e.g., both subsystems with inoperable pump(s) or flow paths, or one subsystem with an inoperable pump and one subsystem with an inoperable flow path), the RHRSW System is not capable of performing its intended function. At least one subsystem must be restored to OPERABLE status within 8 hours. The 8 hour Completion Time for restoring one RHRSW subsystem to OPERABLE status, is based on the Completion Times provided for the RHR suppression pool cooling and spray functions.

The Required Action is modified by a Note indicating that the applicable Conditions of LCO 3.4.9, be entered and Required Actions taken if the inoperable RHRSW subsystem results in inoperable RHR shutdown cooling. This is an exception to LCO 3.0.6 and ensures the proper actions are taken for these components.

(continued)

BASES

ACTIONS
(continued)

C.1 and C.2

If any Required Action and associated Completion Time of Condition A or B are not met, the unit must be placed in a MODE in which the LCO does not apply. To achieve this status, the unit must be placed in at least MODE 3 within 12 hours and in MODE 4 within 36 hours. The allowed Completion Times are reasonable, based on operating experience, to reach the required unit conditions from full power conditions in an orderly manner and without challenging unit systems.

SURVEILLANCE
REQUIREMENTS

SR 3.7.1.1

Verifying the correct alignment for each manual, power operated, and automatic valve in each RHRSW subsystem flow path provides assurance that the proper flow paths will exist for RHRSW operation. This SR does not apply to valves that are locked, sealed, or otherwise secured in position, since these valves are verified to be in the correct position prior to locking, sealing, or securing. A valve is also allowed to be in the nonaccident position, and yet considered in the correct position, provided it can be realigned to its accident position. This is acceptable because the RHRSW System is a manually initiated system.

This SR does not require any testing or valve manipulation; rather, it involves verification that those valves capable of being mispositioned are in the correct position. This SR does not apply to valves that cannot be inadvertently misaligned, such as check valves.

The 31 day Frequency is based on engineering judgment, is consistent with the procedural controls governing valve operation, and ensures correct valve positions.

REFERENCES

1. UFSAR, Section 9.2.1.
 2. UFSAR, Chapter 6.
 3. UFSAR, Chapter 15.
 4. UFSAR, Section 6.2.2.3.1.
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B 3.7 PLANT SYSTEMS

B 3.7.2 Diesel Generator Cooling Water (DGCW) System

BASES

BACKGROUND

The DGCW System is designed to provide cooling water for the removal of heat from the standby diesel generators, low pressure core spray (LPCS) pump motor cooling coils, and Emergency Core Cooling System (ECCS) cubicle area cooling coils that support equipment required for a safe reactor shutdown following a design basis accident (DBA) or transient.

The DGCW System consists of three independent cooling water headers (Divisions 1, 2, and 3), and their associated pumps, valves, and instrumentation. The pump and header for the Division 1 DGCW subsystem is common to both units (and supplies cooling to equipment on both units). The other divisions have independent pumps and suction headers.

The following combinations of DGCW pumps are sized to provide sufficient cooling capacity to support the required safety related systems during safe shutdown of the unit following a loss of coolant accident (LOCA):

- a. The Division 1 and 2 DGCW pumps;
- b. The Division 1 and 3 DGCW pumps and opposite unit Division 2 DGCW pump; or
- c. The Division 2 and 3 DGCW pumps.

The Division 1 DGCW subsystem services its associated Diesel Generator (DG) and ECCS cubicle area coolers, and the LPCS pump motor cooler. The Division 2 DGCW subsystem services its associated DG and ECCS cubicle area cooler. The Division 3 DGCW subsystem services the High Pressure Core Spray (HPCS) DG and its associated ECCS cubicle area cooler. The opposite unit Division 2 DGCW subsystem services its associated DG for support of systems required by both units.

(continued)

BASES

BACKGROUND
(continued)

The DGCW and the Residual Heat Removal Service Water (RHRSW) subsystems are subsystems to the Core Standby Cooling System (CSCS)–Equipment Cooling Water System (ECWS). The CSCS–ECWS consists of three independent piping subsystems corresponding to essential electrical power supply Divisions 1, 2, and 3. The CSCS–ECWS subsystems take a suction from the service water tunnel located in the Lake Screen House. Each DGCW pump auto-starts upon receipt of a diesel generator (DG) start signal when power is available to the pump's electrical bus or on start of ECCS cubicle area coolers. The Division 1 DGCW pump also auto-starts upon receipt of a start signal for the LPCS pump. Cooling water is then pumped from the service water tunnel by the DGCW pumps to the supported systems and components (i.e., the DGs, LPCS pump motor cooler, and the ECCS cubicle area coolers). After removing heat from these systems and components, the water from the DGCW subsystem is discharged to the CSCS pond (i.e., the Ultimate Heat Sink) through a discharge line that is common to the corresponding divisional discharge from the other unit. The discharge line terminates in the discharge structure at an elevation above the normal CSCS Pond level. A complete description of the DGCW System is presented in the UFSAR, Section 9.2.1 (Ref. 1).

APPLICABLE
SAFETY ANALYSES

The ability of the DGCW System to provide adequate cooling to the DGs, LPCS pump motor cooling coils and ECCS cubicle area cooling coils is an implicit assumption for the safety analyses presented in UFSAR, Chapters 6 and 15 (Refs. 2 and 3, respectively). The ability to provide onsite emergency AC power is dependent on the ability of the DGCW System to cool the DGs.

The DGCW System satisfies Criterion 3 of 10 CFR 50.36(c)(2)(ii).

LCO

The Division 1, 2, and 3, and the opposite unit's Division 2 DGCW subsystems are required to be OPERABLE to ensure the effective operation of the DGs, the LPCS pump motor, and the ECCS equipment supported by the ECCS cubicle area coolers during a DBA or transient. The OPERABILITY of each DGSW

(continued)

BASES

LCO
(continued) subsystem is based on having an OPERABLE pump and an OPERABLE flow path capable of taking suction from the CSCS water tunnel and transferring cooling water to the associated diesel generator, LPCS pump motor cooling coils, and ECCS cubicle area cooling coils, as required.

An adequate suction source is not addressed in this LCO since the minimum net positive suction head of the DGCW pump and the maximum suction source temperature are covered by the requirements specified in LCO 3.7.3, "Ultimate Heat Sink (UHS)."

APPLICABILITY In MODES 1, 2, and 3, the DGCW subsystems are required to support the OPERABILITY of equipment serviced by the DGCW subsystems and required to be OPERABLE in these MODES.

In MODES 4 and 5, the OPERABILITY requirements of the DGCW subsystems are determined by the systems they support. Therefore, the requirements are not the same for all facets of operation in MODES 4 and 5. Thus, the LCOs of the systems supported by the DGCW subsystems will govern DGCW System OPERABILITY requirements in MODES 4 and 5.

ACTIONS The ACTIONS Table is modified by a Note indicating that separate Condition entry is allowed for each DGCW subsystem. This is acceptable, since the Required Actions for the Condition provide appropriate compensatory actions for each inoperable DGCW subsystem. Complying with the Required Actions for one inoperable DGCW subsystem may allow for continued operation, and subsequent inoperable DGCW subsystem(s) are governed by separate Condition entry and application of associated Required Actions.

A.1

If one or more DGCW subsystems are inoperable, the associated DG(s) and ECCS components supported by the affected DGCW loop, including LPCS pump motor cooling coils or ECCS cubicle area cooling coils, as applicable, cannot perform their intended function and must be immediately declared inoperable. In accordance with LCO 3.0.6, this

(continued)

BASES

ACTIONS

A.1 (continued)

also requires entering into the Applicable Conditions and Required Actions for LCO 3.8.1, "AC Sources—Operating," and LCO 3.5.1, "Emergency Core Cooling Systems (ECCS)—Operating."

SURVEILLANCE
REQUIREMENTS

SR 3.7.2.1

Verifying the correct alignment for manual, power operated, and automatic valves in each DGCW subsystem flow path provides assurance that the proper flow paths will exist for DGCW subsystem operation. This SR does not apply to valves that are locked, sealed, or otherwise secured in position since these valves were verified to be in the correct position prior to locking, sealing, or securing. A valve is also allowed to be in the nonaccident position, and yet be considered in the correct position provided it can be automatically realigned to its accident position, within the required time. This SR does not require any testing or valve manipulation; rather, it involves verification that those valves capable of being mispositioned are in the correct position. This SR does not apply to valves that cannot be inadvertently misaligned, such as check valves.

The 31 day Frequency is based on engineering judgment, is consistent with the procedural controls governing valve operation, and ensures correct valve positions.

SR 3.7.2.2

This SR ensures that each DGCW subsystem pump will automatically start to provide required cooling to the associated DG, LPCS pump motor cooling coils, and ECCS cubicle area cooling coils, as applicable, when the associated DG starts and the respective bus is energized or on start of the applicable ECCS cubicle area cooler. For the Division 1 DGCW subsystem, this SR also ensures the DGCW pump automatically starts on receipt of a start signal for the unit LPCS pump. These starts may be performed using actual or simulated initiation signals.

(continued)

BASES

SURVEILLANCE
REQUIREMENTS

SR 3.7.2.2 (continued)

Operating experience has shown that these components usually pass the SR when performed at the 24 month Frequency, which is based at the refueling cycle. Therefore, this Frequency is concluded to be acceptable from a reliability standpoint.

REFERENCES

1. UFSAR, Section 9.2.1.
 2. UFSAR, Chapter 6.
 3. UFSAR, Chapter 15.
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B 3.7 PLANT SYSTEMS

B 3.7.3 Ultimate Heat Sink (UHS)

BASES

BACKGROUND

The UHS (i.e., the Core Standby Cooling System (CSCS) Pond) consists of the volume of water remaining in the cooling lake following the failure of the main dike. This water has a depth of approximately 5 feet and a top water elevation established at 690 feet. The volume of the remaining water in the cooling lake is sufficient to permit a safe shutdown and cooldown of the station for 30 days with no water makeup for both accident and normal conditions (Regulatory Guide 1.27, Ref. 1).

The CSCS Pond provides a source of water to the service water tunnel from which the Residual Heat Removal Service Water (RHRSW) and Diesel Generator Cooling Water (DGCW) pumps take suction. The service water tunnel is filled from the CSCS Pond by six inlet lines which connect to the circulating water pump forebays. Prior to entering the service water tunnel inlet pipes, the water is strained by the Lake Screen House traveling screens to prevent large pieces of debris from entering the system and blocking flow or damaging equipment. However, because the traveling screens are not safety related, a 54-inch bypass line around the screens, isolated by a normally closed manual valve, is provided to assure a continuous supply of CSCS Pond water to the service water tunnel.

Additional information on the design and operation of the CSCS Pond is provided in UFSAR, Sections 9.2.1 and 9.2.6 (Refs. 2 and 3). The excavation slopes of the CSCS Pond and flume are designed to be stable under all conditions of emergency operation while providing the capability to supply adequate cooling water to equipment required for safe reactor shutdown.

APPLICABLE
SAFETY ANALYSES

The volume of the CSCS pond is sized to permit the safe shutdown and cooldown of the units for a 30 day period with no additional makeup water source available for both normal and accident conditions (Ref. 2).

The UHS satisfies Criterion 3 of 10 CFR 50.36(c)(2)(ii).

(continued)

BASES (continued)

LCO OPERABILITY of the UHS is based on a maximum water temperature being supplied to the plant of 100°F and a minimum pond water level at or above elevation 690 ft mean sea level. In addition, to ensure the volume of water available in the CSCS pond is sufficient to maintain adequate long term cooling, sediment deposition (in the intake flume and in the pond) must be ≤ 1.5 ft and CSCS pond bottom elevation must be ≤ 686.5 ft.

APPLICABILITY In MODES 1, 2, and 3, the UHS is required to be OPERABLE to support OPERABILITY of the equipment serviced by the UHS, and is required to be OPERABLE in these MODES.

In MODES 4 and 5, the OPERABILITY requirements of the UHS is determined by the systems it supports. Therefore, the requirements are not the same for all facets of operation in MODES 4 and 5. The LCOs of the systems supported by the UHS will govern UHS OPERABILITY requirements in MODES 4 and 5.

ACTIONS A.1

If the CSCS pond is inoperable, due to sediment deposition > 1.5 ft (in the intake flume, CSCS pond, or both) or the pond bottom elevation > 686.5 ft, action must be taken to restore the inoperable UHS to an OPERABLE status within 90 days. The 90 day Completion Time is reasonable based on the low probability of an accident occurring during that time, historical data corroborating the low probability of continued degradation (i.e., further excessive sediment deposition or pond bottom elevation changes) of the CSCS pond during that time, and the time required to complete the Required Action.

B.1 and B.2

If the CSCS pond cannot be restored to OPERABLE status within the associated Completion Time, or the CSCS pond is determined inoperable for reasons other than Condition A (e.g., inoperable due to the temperature of the cooling water supplied to the plant from the CSCS pond $> 100^\circ\text{F}$, corrected for sediment level and time of day), the unit must

(continued)

BASES

ACTIONS

B.1 and B.2 (continued)

be placed in a MODE in which the LCO does not apply. To achieve this status, the unit must be placed in at least MODE 3 within 12 hours and in MODE 4 within 36 hours. The allowed Completion Times are reasonable, based on operating experience, to reach the required unit conditions from full power conditions in an orderly manner and without challenging unit systems.

SURVEILLANCE
REQUIREMENTS

SR 3.7.3.1

Verification of the temperature of the water supplied to the plant from the CSCS pond ensures that the heat removal capabilities of the RHRSW System and DGCW System are within the assumptions of the DBA analysis. To ensure that the maximum design temperature (100°F) of water supplied to the plant is not exceeded, the temperature during normal plant operation must be $\leq 100^\circ\text{F}$, corrected for sediment level and time of day the measurement is taken (Ref. 3). This is to account for the CSCS pond design requirement that it provide adequate cooling water supply to the plant (i.e., temperature $\leq 100^\circ\text{F}$) for 30 days without makeup, while taking into account solar heat loads and plant decay heat during the worst historical weather conditions. In addition, since the lake temperature follows a diurnal cycle (it heats up during the day and cools off at night), the measured temperature must be corrected for the time of day the measurement is taken. The allowable temperatures, based on the actual sediment level and the time of day the measurement is taken, have been determined by analysis. The 24 hour Frequency is based on operating experience related to trending of the parameter variations during the applicable MODES.

SR 3.7.3.2

This SR ensures adequate long term (30 days) cooling can be maintained, by verifying the sediment level in the intake flume and the CSCS pond is ≤ 1.5 feet. Sediment level is determined by a series of sounding cross-sections compared to as-built soundings. The 24 month Frequency is based on historical data and engineering judgement regarding sediment deposition rate.

(continued)

BASES

SURVEILLANCE
REQUIREMENTS
(continued)

SR 3.7.3.3

This SR ensures adequate long term (30 days) cooling can be maintained, by verifying the CSCS pond bottom elevation is \leq 686.5 feet. The 24 month Frequency is based on historical data and engineering judgement regarding pond bottom elevation changes.

REFERENCES

1. Regulatory Guide 1.27, Revision 2, January 1976.
 2. UFSAR, Section 9.2.1.
 3. UFSAR, Section 9.2.6.
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B 3.7 PLANT SYSTEMS

B 3.7.4 Control Room Area Filtration (CRAF) System

BASES

BACKGROUND

The CRAF System provides a radiologically controlled environment (control room and auxiliary electric equipment room) from which the unit can be safely operated following a Design Basis Accident (DBA). The Control Room Area Heating Ventilation and Air Conditioning (HVAC) System is comprised of the Control Room HVAC System and the Auxiliary Electric Equipment Room (AEER) HVAC System. The Control Room HVAC System is common to both units and serves the control room, main security control center, and the control room habitability storage room (toilet room). The AEER HVAC System is common to both units and services the auxiliary electrical equipment rooms. The control room area is comprised of the areas covered by the Control Room and AEER HVAC Systems.

The safety related function of the CRAF System used to control radiation exposure consists of two independent and redundant high efficiency air filtration subsystems (i.e., the emergency makeup air filter units (EMUs) for treatment of outside supply air). Recirculation filters are also provided for treatment of recirculated air. Each EMU subsystem consists of a demister, an electric heater, a prefilter, a high efficiency particulate air (HEPA) filter, an activated charcoal adsorber section, a second HEPA filter, a fan, and the associated ductwork, dampers, and instrumentation and controls. Demisters remove water droplets from the airstream. The electric heater reduces the relative humidity of the air entering the EMUs. Prefilters and HEPA filters remove particulate matter that may be radioactive. The charcoal adsorbers provide a holdup period for gaseous iodine, allowing time for decay. Each Control Room and AEER Ventilation System has a charcoal recirculation filter in the supply of the system that is normally bypassed. In addition, the OPERABILITY of the CRAF System is dependent upon portions of the Control Room Area HVAC System, including the control room and auxiliary electric equipment room outside air intakes, supply fans, ducts, dampers, etc.

(continued)

BASES

BACKGROUND
(continued)

In addition to the safety related standby emergency filtration function, parts of the CRAF System that are shared with the Control Room Area HVAC System are operated to maintain the control room area environment during normal operation. Upon receipt of a high radiation signal from the outside air intake (indicative of conditions that could result in radiation exposure to control room personnel), the CRAF System automatically isolates the normal outside air supply to the Control Room Area HVAC System, and diverts the minimum outside air requirement through the EMUs before delivering it to the control room area. The recirculation filters for the control room and AEER must be manually placed in service within 4 hours of receipt of any control room high radiation alarm.

The CRAF System is designed to maintain the control room area environment for a 30 day continuous occupancy after a DBA, without exceeding a 5 rem whole body dose or its equivalent to any part of the body. CRAF System operation in maintaining the control room area habitability is discussed in the UFSAR, Sections 6.4, 6.5.1, and 9.4.1 (Refs. 1, 2, and 3, respectively).

APPLICABLE
SAFETY ANALYSES

The ability of the CRAF System to maintain the habitability of the control room area is an explicit assumption for the safety analyses presented in the UFSAR, Chapters 6 and 15 (Refs. 4 and 5, respectively). The pressurization mode of the CRAF System is assumed to operate following a loss of coolant accident, main steam line break, fuel handling accident, and control rod drop accident. The radiological doses to control room personnel as a result of the various DBAs are summarized in Reference 5. No single active failure will cause the loss of outside or recirculated air from the control room area.

The CRAF System satisfies Criterion 3 of 10 CFR 50.36(c)(2)(ii).

LCO

Two redundant subsystems of the CRAF System are required to be OPERABLE to ensure that at least one is available, assuming a single failure disables the other subsystem. Total system failure could result in exceeding a dose of 5 rem to the control room operators in the event of a DBA.

(continued)

BASES

LCO
(continued)

The CRAF System is considered OPERABLE when the individual components necessary to control operator exposure are OPERABLE in both subsystems. A subsystem is considered OPERABLE when its associated EMU is OPERABLE and the associated charcoal recirculation filters for the control room and AEER are OPERABLE. An EMU is considered OPERABLE when its associated:

- a. Fan is OPERABLE;
- b. HEPA filter and charcoal adsorber are not excessively restricting flow and are capable of performing their filtration functions; and
- c. Heater, demister, ductwork, valves, and dampers are OPERABLE, and air circulation through the EMU can be maintained.

Additionally, the portions of the Control Room Area HVAC System that supply the outside air to the EMUs are required to be OPERABLE. This includes the outside air intakes, associated dampers and ductwork.

In addition, the control room area boundary must be maintained, including the integrity of the walls, floors, ceilings, ductwork, and access doors, such that the pressurization limit of SR 3.7.4.5 can be met. However, it is acceptable for access doors to be open for normal control room area entry and exit and not consider it to be a failure to meet the LCO.

APPLICABILITY

In MODES 1, 2, and 3, the CRAF System must be OPERABLE to control operator exposure during and following a DBA, since the DBA could lead to a fission product release.

In MODES 4 and 5, the probability and consequences of a DBA are reduced due to the pressure and temperature limitations in these MODES. Therefore, maintaining the CRAF System OPERABLE is not required in MODE 4 or 5, except for the following situations under which significant radioactive releases can be postulated:

- a. During movement of irradiated fuel assemblies in the secondary containment;

(continued)

BASES

APPLICABILITY
(continued)

- b. During CORE ALTERATIONS; and
 - c. During operations with a potential for draining the reactor vessel (OPDRVs).
-

ACTIONS

A.1

With one CRAF subsystem inoperable, the inoperable CRAF subsystem must be restored to OPERABLE status within 7 days. With the unit in this condition, the remaining OPERABLE CRAF subsystem is adequate to perform control room radiation protection. However, the overall reliability is reduced because a single failure in the OPERABLE subsystem could result in loss of CRAF System function. The 7 day Completion Time is based on the low probability of a DBA occurring during this time period, and that the remaining subsystem can provide the required capabilities.

B.1 and B.2

In MODE 1, 2, or 3, if the inoperable CRAF subsystem cannot be restored to OPERABLE status within the associated Completion Time, the unit must be placed in a MODE that minimizes risk. To achieve this status, the unit must be placed in at least MODE 3 within 12 hours and in MODE 4 within 36 hours. The allowed Completion Times are reasonable, based on operating experience, to reach the required unit conditions from full power conditions in an orderly manner and without challenging unit systems.

C.1, C.2.1, C.2.2, and C.2.3

LCO 3.0.3 is not applicable while in MODE 4 or 5. However, since irradiated fuel assembly movement can occur in MODE 1, 2, or 3, the Required Actions of Condition C are modified by a Note indicating that LCO 3.0.3 does not apply. If moving irradiated fuel assemblies while in MODE 1, 2, or 3, the fuel movement is independent of reactor operations. Entering LCO 3.0.3 while in MODE 1, 2, or 3 would require the unit to be shutdown, but would not require immediate suspension of movement of irradiated fuel assemblies. The

(continued)

BASES

ACTIONS C.1, C.2.1, C.2.2, and C.2.3 (continued)

Note to the ACTIONS, "LCO 3.0.3 is not applicable," ensures that the actions for immediate suspension of irradiated fuel assembly movement are not postponed due to entry into LCO 3.0.3.

During movement of irradiated fuel assemblies in the secondary containment, during CORE ALTERATIONS, or during OPDRVs, if the inoperable CRAF subsystem cannot be restored to OPERABLE status within the required Completion Time, the OPERABLE CRAF subsystem may be placed in the pressurization mode. This action ensures that the remaining subsystem is OPERABLE, that no failures that would prevent automatic actuation will occur, and that any active failure will be readily detected.

An alternative to Required Action C.1 is to immediately suspend activities that present a potential for releasing radioactivity that might require isolation of the control room area. This places the unit in a condition that minimizes risk.

If applicable, CORE ALTERATIONS and movement of irradiated fuel assemblies in the secondary containment must be suspended immediately. Suspension of these activities shall not preclude completion of movement of a component to a safe position. Also, if applicable, action must be initiated immediately to suspend OPDRVs to minimize the probability of a vessel draindown and subsequent potential for fission product release. Action must continue until the OPDRVs are suspended.

D.1

If both CRAF subsystems are inoperable in MODE 1, 2, or 3, the CRAF System may not be capable of performing the intended function and the unit is in a condition outside of the accident analyses. Therefore, LCO 3.0.3 must be entered immediately.

(continued)

BASES

ACTIONS
(continued)

E.1, E.2, and E.3

LCO 3.0.3 is not applicable while in MODE 4 or 5. However, since irradiated fuel assembly movement can occur in MODE 1, 2, or 3, the Required Actions of Condition E are modified by a Note indicating that LCO 3.0.3 does not apply. If moving irradiated fuel assemblies while in MODE 1, 2, or 3, the fuel movement is independent of reactor operations. Entering LCO 3.0.3 while in MODE 1, 2, or 3 would require the unit to be shutdown, but would not require immediate suspension of movement of irradiated fuel assemblies. The Note to the ACTIONS, "LCO 3.0.3 is not applicable," ensures that the actions for immediate suspension of irradiated fuel assembly movement are not postponed due to entry into LCO 3.0.3.

During movement of irradiated fuel assemblies in the secondary containment, during CORE ALTERATIONS, or during OPDRVs, with two CRAF subsystems inoperable, action must be taken immediately to suspend activities that present a potential for releasing radioactivity that might require isolation of the control room. This places the unit in a condition that minimizes risk.

If applicable, CORE ALTERATIONS and movement of irradiated fuel assemblies in the secondary containment must be suspended immediately. Suspension of these activities shall not preclude completion of movement of a component to a safe position. If applicable, action must be initiated immediately to suspend OPDRVs to minimize the probability of a vessel draindown and subsequent potential for fission product release. Action must continue until the OPDRVs are suspended.

SURVEILLANCE
REQUIREMENTS

SR 3.7.4.1

This SR verifies that a subsystem in a standby mode starts on demand and continues to operate. Standby systems should be checked periodically to ensure that they start and function properly. As the environmental and normal operating conditions of this system are not severe, testing each subsystem once every month provides an adequate check on this system. Monthly heater operation for

(continued)

BASES

SURVEILLANCE
REQUIREMENTS

SR 3.7.4.1 (continued)

≥ 10 continuous hours during system operation dries out any moisture accumulated in the charcoal from humidity in the ambient air. Furthermore, the 31 day Frequency is based on the known reliability of the equipment and the two subsystem redundancy available.

SR 3.7.4.2

This SR verifies that flow can be manually realigned through the CRAF System recirculation filters and maintained for ≥ 10 hours. Standby systems should be checked periodically to ensure that they function. Monthly operation dries out any moisture accumulated in the charcoal from humidity in the ambient air. Furthermore, the 31 day Frequency is based on the known reliability of the equipment and two subsystem redundancy available.

SR 3.7.4.3

This SR verifies that the required CRAF testing is performed in accordance with Specification 5.5.8, "Ventilation Filter Testing Program (VFTP)." The CRAF filter tests are in accordance with ANSI/ASME N510-1989 (Ref. 5). The VFTP includes testing HEPA filter performance, charcoal adsorber efficiency, system flow rate, and the physical properties of the activated charcoal (general use and following specific operations). Specific test frequencies and additional information are discussed in detail in the VFTP.

SR 3.7.4.4

This SR verifies that each CRAF subsystem automatically switches to the pressurization mode of operation on an actual or simulated air intake radiation monitors initiation signal. The LOGIC SYSTEM FUNCTIONAL TEST in SR 3.3.7.1.4 overlaps this SR to provide complete testing of the safety function. Operating experience has shown that these components normally pass the SR when performed at the 24 month Frequency. Therefore, the Frequency was found to be acceptable from a reliability standpoint.

(continued)

BASES

SURVEILLANCE
REQUIREMENTS
(continued)

SR 3.7.4.5

This SR verifies the integrity of the control room area and the assumed inleakage rates of potentially contaminated air. The control room area positive pressure, with respect to potentially contaminated adjacent areas, is periodically tested to verify proper function of the CRAF System. During the pressurization mode of operation, the CRAF System is designed to slightly pressurize the control room area to ≥ 0.125 inches water gauge positive pressure with respect to adjacent areas to prevent unfiltered inleakage. The CRAF System is designed to maintain this positive pressure at a flow rate of ≤ 4000 cfm to the control room area in the pressurization mode. This test also requires manual initiation of flow through the control room and AEER recirculation filters line when the CRAF System is in the pressurization mode of operation. The Frequency of 24 months is consistent with industry practice and other filtration system SRs.

REFERENCES

1. UFSAR, Section 6.4.
 2. UFSAR, Section 6.5.1.
 3. UFSAR, Section 9.4.1.
 4. UFSAR, Chapter 6.
 5. UFSAR, Chapter 15.
 6. ANSI/ASME N510-1989.
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B 3.7 PLANT SYSTEMS

B 3.7.5 Control Room Area Ventilation Air Conditioning (AC) System

BASES

BACKGROUND

The Control Room Area Ventilation AC System provides temperature control for the control room area. The control room area is comprised of the control room and the Auxiliary Electric Equipment Rooms (AEERs).

The Control Room Area Ventilation AC System is comprised of two independent, redundant subsystems that provide cooling and heating of control room air and the auxiliary electric equipment rooms air. Each Control Room Area Ventilation AC subsystem consists of a Control Room AC subsystem and an AEER AC subsystem. The associated Control Room AC and AEER AC subsystems share a common outside air intake with a common emergency makeup air filter unit. The Control Room AC System is common to both units and serves the control room, main security control center, and the control room habitability storage room (toilet room). The AEER AC System is common to both units and services the AEERs.

Each Control Room Area Ventilation AC subsystem is powered from a Division 2 power source. One subsystem is powered from Unit 1 Division 2 and the other subsystem is powered from Unit 2 Division 2.

Each control room AC and AEER AC subsystem consists of a supply air filter, supply and return air fans, direct expansion cooling coils, an air-cooled condenser, a refrigerant compressor and receiver, heating coils, ductwork, dampers, and instrumentation and controls to provide temperature control for their respective areas. However, the heating coils are not safety related.

The Control Room Area Ventilation AC System is designed to provide a controlled environment under both normal and accident conditions. A single control room area ventilation AC subsystem provides the required temperature control to maintain a suitable control room and AEER environment for a sustained occupancy of at least the required normal and emergency shift crew complements. The design conditions for

(continued)

BASES

BACKGROUND (continued) habitability of the control room and AEER environment are 65°F to 85°F and a maximum of 50% relative humidity. The Control Room Area Ventilation AC System operation in maintaining the temperatures of the control room and AEERs is discussed in the UFSAR, Sections 6.4 and 9.4.1 (Refs. 1 and 2, respectively).

APPLICABLE SAFETY ANALYSES The design basis of the Control Room Area Ventilation AC System is to maintain temperatures of the control room and AEERs for a 30 day period after a Design Basis Accident (DBA).

The Control Room Area Ventilation AC System components are arranged in redundant safety related subsystems. During emergency operation, the Control Room Area Ventilation AC System maintains a habitable environment and ensures the OPERABILITY of components in the control room and AEERs. A single active failure of a component of the Control Room Area Ventilation AC System, assuming a loss of offsite power, does not impair the ability of the system to perform its design function. Redundant detectors and controls are provided for control room and AEERs temperature control. The Control Room Area Ventilation AC System is designed in accordance with Seismic Category I requirements, with exceptions described in UFSAR Section 9.4.1.1.1.1 (Ref. 3). The Control Room Area Ventilation AC System is capable of removing sensible and latent heat loads from the control room and AEERs, including consideration of equipment heat loads and personnel occupancy requirements to ensure equipment OPERABILITY.

The Control Room Area Ventilation AC System satisfies Criterion 3 of 10 CFR 50.36(c)(2)(ii).

LCO Two independent and redundant subsystems of the Control Room Area Ventilation AC System are required to be OPERABLE to ensure that at least one subsystem is available, assuming a single failure disables the other subsystem. Total system failure could result in the equipment operating temperature exceeding limits.

(continued)

BASES

LCO
(continued) The Control Room Area Ventilation AC System is considered OPERABLE when the individual components necessary to maintain the control room and AEERs temperatures are OPERABLE in both subsystems. These components include the supply and return air fans, direct expansion cooling coils, an air-cooled condenser, a refrigerant compressor and receiver, ductwork, dampers, and instrumentation and controls.

APPLICABILITY In MODE 1, 2, or 3, the Control Room Area Ventilation AC System must be OPERABLE to ensure that the control room and AEERs temperatures will not exceed equipment OPERABILITY limits during operation of the Control Room Area Filtration (CRAF) System in the pressurization mode.

In MODES 4 and 5, the probability and consequences of a Design Basis Accident are reduced due to the pressure and temperature limitations in these MODES. Therefore, maintaining the Control Room Area Ventilation AC System OPERABLE is not required in MODE 4 or 5, except for the following situations under which significant radioactive releases can be postulated:

- a. During movement of irradiated fuel assemblies in the secondary containment;
 - b. During CORE ALTERATIONS; and
 - c. During operations with a potential for draining the reactor vessel (OPDRVs).
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ACTIONS

A.1

With one control room area ventilation AC subsystem inoperable, the inoperable control room area ventilation AC subsystem must be restored to OPERABLE status within 30 days. With the unit in this condition, the remaining OPERABLE control room area ventilation AC subsystem is adequate to perform the control room air conditioning function. However, the overall reliability is reduced because a single failure in the OPERABLE subsystem could result in loss of the control room area ventilation air conditioning function. The 30 day Completion Time is based

(continued)

BASES

ACTIONS

A.1 (continued)

on the low probability of an event occurring requiring operation of the CRAF System in the pressurization mode and the consideration that the remaining subsystem can provide the required protection.

B.1 and B.2

In MODE 1, 2, or 3, if the inoperable control room area ventilation AC subsystem cannot be restored to OPERABLE status within the associated Completion Time, the unit must be placed in a MODE that minimizes risk. To achieve this status the unit must be placed in at least MODE 3 within 12 hours and in MODE 4 within 36 hours. The allowed Completion Times are reasonable, based on operating experience, to reach the required unit conditions from full power conditions in an orderly manner and without challenging unit systems.

C.1, C.2.1, C.2.2, and C.2.3

LCO 3.0.3 is not applicable while in MODE 4 or 5. However, since irradiated fuel assembly movement can occur in MODE 1, 2, or 3, the Required Actions of Condition C are modified by a Note indicating that LCO 3.0.3 does not apply. If moving irradiated fuel assemblies while in MODE 1, 2, or 3, the fuel movement is independent of reactor operations. Entering LCO 3.0.3 while in MODE 1, 2, or 3 would require the unit to be shutdown, but would not require immediate suspension of movement of irradiated fuel assemblies. The Note to the ACTIONS, "LCO 3.0.3 is not applicable," ensures that the actions for immediate suspension of irradiated fuel assembly movement are not postponed due to entry into LCO 3.0.3.

During movement of irradiated fuel assemblies in the secondary containment, during CORE ALTERATIONS, or during OPDRVs, if Required Action A.1 cannot be completed within the required Completion Time, the OPERABLE control room AC subsystem may be placed immediately in operation.

(continued)

BASES

ACTIONS

C.1, C.2.1, C.2.2, and C.2.3 (continued)

This action ensures that the remaining subsystem is OPERABLE, that no failures that would prevent actuation will occur, and that any active failure will be readily detected.

An alternative to Required Action C.1 is to immediately suspend activities that present a potential for releasing radioactivity that might require isolation of the control room. This places the unit in a condition that minimizes risk.

If applicable, CORE ALTERATIONS and movement of irradiated fuel assemblies in the secondary containment must be suspended immediately. Suspension of these activities shall not preclude completion of movement of a component to a safe position. Also, if applicable, action must be initiated immediately to suspend OPDRVs to minimize the probability of a vessel draindown and subsequent potential for fission product release. Action must continue until the OPDRVs are suspended.

D.1

If both control room area ventilation AC subsystems are inoperable in MODE 1, 2, or 3, the Control Room Area Ventilation AC System may not be capable of performing the intended function. Therefore, LCO 3.0.3 must be entered immediately.

E.1, E.2, and E.3

The Required Actions of Condition E.1 are modified by a Note indicating that LCO 3.0.3 does not apply. If moving irradiated fuel assemblies while in MODE 1, 2, or 3, the fuel movement is independent of reactor operations. Therefore, inability to suspend movement of irradiated fuel assemblies is not sufficient reason to require a reactor shutdown.

During movement of irradiated fuel assemblies in the secondary containment, during CORE ALTERATIONS, or during

(continued)

BASES

ACTIONS

E.1, E.2, and E.3 (continued)

OPDRVs with two control room area ventilation AC subsystems inoperable, action must be taken to immediately suspend activities that present a potential for releasing radioactivity that might require isolation of the control room. This places the unit in a condition that minimizes risk.

If applicable, CORE ALTERATIONS and handling of irradiated fuel in the secondary containment must be suspended immediately. Suspension of these activities shall not preclude completion of movement of a component to a safe position. Also, if applicable, action must be initiated immediately to suspend OPDRVs to minimize the probability of a vessel draindown and subsequent potential for fission product release. Action must continue until the OPDRVs are suspended.

SURVEILLANCE
REQUIREMENTS

SR 3.7.5.1

This SR monitors the control room and AEER temperatures for indication of Control Room Area Ventilation AC System performance. Trending of control room area temperature will provide a qualitative assessment of refrigeration unit OPERABILITY. Limiting the average temperature of the Control Room and AEER to less than or equal to 85°F provides a threshold beyond which the operating control room area ventilation AC subsystem is no longer demonstrating capability to perform its function. This threshold provides margin to temperature limits at which equipment qualification requirements could be challenged. Subsystem operation is routinely alternated to support planned maintenance and to ensure each subsystem provides reliable service. The 12 hour Frequency is adequate considering the continuous manning of the control room by the operating staff.

(continued)

BASES

SURVEILLANCE
REQUIREMENTS
(continued)

SR 3.7.5.2

Verifying proper breaker alignment and power available to the control room area ventilation AC subsystems provides assurance of the availability of the system function. The 7 day Frequency is appropriate in view of other administrative controls that assure system availability.

REFERENCES

1. UFSAR, Section 6.4.
 2. UFSAR, Section 9.4.1.
 3. UFSAR, Section 9.4.1.1.1.1.
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B 3.7 PLANT SYSTEMS

B 3.7.6 Main Condenser Offgas

BASES

BACKGROUND During unit operation, steam from the low pressure turbine is exhausted directly into the main condenser. Air and noncondensable gases are collected in the main condenser, then exhausted through the steam jet air ejectors (SJAEs) to the Main Condenser Offgas System. The offgas from the main condenser normally includes radioactive gases.

The Main Condenser Offgas System has been incorporated into the unit design to reduce the gaseous radwaste emission. This system uses a catalytic recombiner to recombine radiolytically dissociated hydrogen and oxygen. The gaseous mixture is cooled by the offgas condenser; the water and condensibles are stripped out by the offgas condenser and water separator. The radioactivity of the remaining gaseous mixture (i.e., the offgas recombiner effluent) is monitored downstream of the water separator prior to entering the holdup line.

APPLICABLE SAFETY ANALYSES The main condenser offgas gross gamma activity rate is an initial condition of the Main Condenser Offgas System failure event as discussed in the UFSAR, Section 15.7.1.1 (Ref. 1). The analysis assumes a gross failure in the Main Condenser Offgas System that results in the rupture of the Main Condenser Offgas System pressure boundary. The gross gamma activity rate is controlled to ensure that during the event, the calculated offsite doses will be well within the limits of 10 CFR 100 (Ref. 2).

The main condenser offgas limits satisfy Criterion 2 of 10 CFR 50.36(c)(2)(ii).

LCO To ensure compliance with the assumptions of the Main Condenser Offgas System failure event (Ref. 1), the fission product release rate should be consistent with a noble gas release to the reactor coolant of 100 $\mu\text{Ci}/\text{Mwt-second}$ after decay of 30 minutes. The LCO is conservatively established based on the safety analysis discussed in Reference 1.

(continued)

BASES (continued)

APPLICABILITY The LCO is applicable when steam is being exhausted to the main condenser and the resulting noncondensibles are being processed via the Main Condenser Offgas System. This occurs during MODE 1, and during MODES 2 and 3 with any main steam line not isolated and the SJAE in operation. In MODES 4 and 5, main steam is not being exhausted to the main condenser and the requirements are not applicable.

ACTIONS

A.1

If the offgas radioactivity rate limit is exceeded, 72 hours is allowed to restore the gross gamma activity rate to within the limit. The 72 hour Completion Time is reasonable, based on engineering judgment considering the time required to complete the Required Action, the large margins associated with permissible dose and exposure limits, and the low probability of a Main Condenser Offgas System rupture occurring.

B.1, B.2, B.3.1, and B.3.2

If the gross gamma activity rate is not restored to within the limits within the associated Completion Time, all main steam lines or the SJAE must be isolated. This isolates the Main Condenser Offgas System from significant sources of radioactive steam. The main steam lines are considered isolated if at least one main steam isolation valve in each main steam line is closed, and at least one main steam line drain valve in each drain line is closed. The 12 hour Completion Time is reasonable, based on operating experience, to perform the actions from full power conditions in an orderly manner and without challenging unit systems.

An alternative to Required Actions B.1 and B.2 is to place the unit in a MODE in which the LCO does not apply. To achieve this status, the unit must be placed in at least MODE 3 within 12 hours and in MODE 4 within 36 hours. The allowed Completion Times are reasonable, based on operating experience, to reach the required unit conditions from full power conditions in an orderly manner and without challenging unit systems.

(continued)

BASES (continued)

SURVEILLANCE
REQUIREMENTS

SR 3.7.6.1

This SR, on a 31 day Frequency, requires an isotopic analysis of a representative offgas sample taken prior to the holdup line to ensure that the required limits are satisfied. The noble gases to be sampled are Xe-133, Xe-135, Xe-135m, Xe-138, Kr-85m, Kr-87, and Kr-88. If the measured rate of radioactivity increases significantly (by $\geq 50\%$ after correcting for expected increases due to changes in THERMAL POWER), an isotopic analysis is also performed within 4 hours after the increase is noted (as indicated by the offgas pre-treatment noble gas activity monitor), to ensure that the increase is not indicative of a sustained increase in the radioactivity rate. The 31 day Frequency is adequate in view of other instrumentation that continuously monitor the offgas, and is acceptable based on operating experience.

This SR is modified by a Note indicating that the SR is not required to be performed until 31 days after any main steam line is not isolated and the SJAE is in operation. Only in this condition can radioactive fission gases be in the Main Condenser Offgas System at significant rates.

REFERENCES

1. UFSAR, Section 15.7.1.
 2. 10 CFR 100.
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B 3.7 PLANT SYSTEMS

B 3.7.7 Main Turbine Bypass System

BASES

BACKGROUND

The Main Turbine Bypass System is designed to control steam pressure when reactor steam generation exceeds turbine requirements during unit startup, sudden load reduction, and cooldown. It allows excess steam flow from the reactor to the condenser without going through the turbine. The bypass capacity of the system is approximately 25% of the Nuclear Steam Supply System rated steam flow. Sudden load reductions within the capacity of the steam bypass can be accommodated without reactor scram. The Main Turbine Bypass System consists of five valves mounted on a valve manifold connected to the main steam lines between the main steam isolation valves and the main turbine stop valves. Each of these valves is sequentially operated by hydraulic cylinders. The bypass valves are controlled by the pressure regulation function of the Turbine Electro Hydraulic Control System, as discussed in the UFSAR, Section 7.7.5.2 (Ref. 1). The bypass valves are normally closed, and the pressure regulator controls the turbine control valves, directing all steam flow to the turbine. If the speed governor or the load limiter restricts steam flow to the turbine, the pressure regulator controls the system pressure by opening the bypass valves. When the bypass valves open, the steam flows from the bypass valve outlet manifold, through connecting piping, to the pressure breakdown assemblies, where a series of orifices are used to further reduce the steam pressure before the steam enters the condenser (Ref. 2).

APPLICABLE
SAFETY ANALYSES

The Main Turbine Bypass System is assumed to function during the turbine trip, turbine generator load rejection, and feedwater controller failure maximum demand transients, described in the UFSAR, Sections 15.2.3, 15.2.2A, and 15.1.2A (Refs. 3, 4, and 5, respectively). Opening the bypass valves during the pressurization event mitigates the increase in reactor vessel pressure, which affects the MCPR during the event. An inoperable Main Turbine Bypass System may result in an MCPR penalty.

The Main Turbine Bypass System satisfies Criterion 3 of 10 CFR 50.36(c)(2)(ii)

(continued)

BASES (continued)

LCO The Main Turbine Bypass System is required to be OPERABLE to limit peak pressure in the main steam lines and maintain reactor pressure within acceptable limits during events that cause rapid pressurization, such that the Safety Limit MCPR is not exceeded. With the Main Turbine Bypass System inoperable, modifications to the MCPR limits (LCO 3.2.2, "MINIMUM CRITICAL POWER RATIO (MCPR)") may be applied to allow continued operation.

An OPERABLE Main Turbine Bypass System requires the bypass valves to open in response to increasing main steam line pressure. This response is within the assumptions of the applicable analysis (Refs. 3, 4, and 5). The MCPR limit for the inoperable Main Turbine Bypass System is specified in the COLR.

APPLICABILITY The Main Turbine Bypass System is required to be OPERABLE at $\geq 25\%$ RTP to ensure that the fuel cladding integrity Safety Limit is not violated during the turbine trip, feedwater controller failure maximum demand, and turbine generator load rejection transients. As discussed in the Bases for LCO 3.2.2 sufficient margin to these limits exists $< 25\%$ RTP. Therefore, these requirements are only necessary when operating at or above this power level.

ACTIONS A.1

If the Main Turbine Bypass System is inoperable (one or more bypass valves inoperable), and the MCPR limits for an inoperable Main Turbine Bypass System, as specified in the COLR, are not applied, the assumptions of the design basis transient analysis may not be met. Under such circumstances, prompt action should be taken to restore the Main Turbine Bypass System to OPERABLE status or adjust the MCPR limits accordingly. The 2 hour Completion Time is reasonable, based on the time to complete the Required Action and the low probability of an event occurring during this period requiring the Main Turbine Bypass System.

(continued)

BASES

ACTIONS
(continued)

B.1

If the Main Turbine Bypass System cannot be restored to OPERABLE status and the MCPR limits for an inoperable Main Turbine Bypass System are not applied, THERMAL POWER must be reduced to < 25% RTP. As discussed in the Applicability section, operation at < 25% RTP results in sufficient margin to the required limits, and the Main Turbine Bypass System is not required to protect fuel integrity during the turbine trip, turbine generator load rejection, and feedwater controller failure maximum demand transients. The 4 hour Completion Time is reasonable, based on operating experience, to reach the required unit conditions from full power conditions in an orderly manner and without challenging unit systems.

SURVEILLANCE
REQUIREMENTS

SR 3.7.7.1

Cycling each main turbine bypass valve through one complete cycle of full travel demonstrates that the valves are mechanically OPERABLE and will function when required. The 7 day Frequency is based on engineering judgment, is consistent with the procedural controls governing valve operation, and ensures correct valve positions. Therefore, the Frequency is acceptable from a reliability standpoint.

SR 3.7.7.2

The Main Turbine Bypass System is required to actuate automatically to perform its design function. This SR demonstrates that, with the required simulated system initiation signals, the valves will actuate to their required position. The 24 month Frequency is based on the need to perform this Surveillance under conditions that apply during a unit outage and because of the potential for an unplanned transient if the Surveillance were performed with the reactor at power. Operating experience has shown that these components usually pass the SR when performed at the 24 month Frequency, which is based on the refueling cycle. Therefore, the Frequency was concluded to be acceptable from a reliability standpoint.

(continued)

BASES

SURVEILLANCE
REQUIREMENTS
(continued)

SR 3.7.7.3

This SR ensures that the TURBINE BYPASS SYSTEM RESPONSE TIME, as defined in the transient analysis inputs for the cycle, is in compliance with the assumptions of the appropriate safety analyses. The response time limits are specified in the Technical Requirements Manual (Ref. 6). The 24 month Frequency is based on the need to perform this Surveillance under conditions that apply during a unit outage and because of the potential for an unplanned transient if the Surveillance were performed with the reactor at power. Operating experience has shown that these components usually pass the SR when performed at the 24 month Frequency, which is based on the refueling cycle. Therefore, the Frequency was concluded to be acceptable from a reliability standpoint.

REFERENCES

1. UFSAR, Section 7.7.5.2.
 2. UFSAR, Section 10.4.4.
 3. UFSAR, Section 15.2.3.
 4. UFSAR, Section 15.2.2A.
 5. UFSAR, Section 15.1.2A.
 6. Technical Requirements Manual.
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B 3.7 PLANT SYSTEMS

B 3.7.8 Spent Fuel Storage Pool Water Level

BASES

BACKGROUND The minimum water level in the spent fuel storage pool meets the assumptions of iodine decontamination factors following a fuel handling accident.

A general description of the spent fuel storage pool design is found in the UFSAR, Section 9.1.2 (Ref. 1). The assumptions of the fuel handling accident are found in the UFSAR, Sections 9.1.2 and 15.7.4 (Refs. 1 and 2, respectively).

**APPLICABLE
SAFETY ANALYSES**

The water level above the irradiated fuel assemblies is an explicit assumption of the fuel handling accident (Ref. 2). A fuel handling accident is evaluated to ensure that the radiological consequences (calculated whole body and thyroid doses at the exclusion area and low population zone boundaries) are \leq 25% (NUREG-0800, Section 15.7.4, Ref. 3) of the 10 CFR 100 (Ref. 4) exposure guidelines. A fuel handling accident could release a fraction of the fission product inventory by breaching the fuel rod cladding as discussed in the Regulatory Guide 1.25 (Ref. 5).

The fuel handling accident is evaluated for the dropping of an irradiated fuel assembly onto the reactor core. The consequences of a fuel handling accident over the spent fuel storage pool are less severe than those of the fuel handling accident over the reactor core (Ref. 2). The water level in the spent fuel storage pool provides for absorption of water soluble fission product gases and transport delays of soluble and insoluble gases that must pass through the water before being released to the secondary containment atmosphere. This absorption and transport delay reduces the potential radioactivity of the release during a fuel handling accident.

The spent fuel storage pool water level satisfies Criterion 2 of 10 CFR 50.36(c)(2)(ii).

(continued)

BASES (continued)

LCO The specified water level preserves the assumption of the fuel handling accident analysis (Ref. 2). As such, it is the minimum required for fuel movement within the spent fuel storage pool.

APPLICABILITY This LCO applies whenever movement of irradiated fuel assemblies occurs in the spent fuel storage pool or whenever movement of new fuel assemblies occurs in the spent fuel storage pool with irradiated fuel assemblies seated in the spent fuel storage pool, since the potential for a release of fission products exists.

ACTIONS A.1

Required Action A.1 is modified by a Note indicating that LCO 3.0.3 does not apply. If moving fuel assemblies while in MODE 1, 2, or 3, the fuel movement is independent of reactor operations. Therefore, inability to suspend movement of fuel assemblies is not a sufficient reason to require a reactor shutdown.

When the initial conditions for an accident cannot be met, steps should be taken to preclude the accident from occurring. With the spent fuel storage pool level less than required, the movement of fuel assemblies in the spent fuel storage pool is suspended immediately. Suspension of this activity shall not preclude completion of movement of a fuel assembly to a safe position. This effectively precludes a spent fuel handling accident from occurring.

SURVEILLANCE SR 3.7.8.1
REQUIREMENTS

This SR verifies that sufficient water is available in the event of a fuel handling accident. The water level in the spent fuel storage pool must be checked periodically. The 7 day Frequency is acceptable, based on operating experience, considering that the water volume in the pool is normally stable and water level changes are controlled by unit procedures.

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BASES (continued)

- REFERENCES
1. UFSAR, Section 9.1.2.
 2. UFSAR, Section 15.7.4.
 3. NUREG-0800, Section 15.7.4, Revision 1, July 1981.
 5. 10 CFR 100.
 6. Regulatory Guide 1.25, March 1972.
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B 3.8 ELECTRICAL POWER SYSTEMS

B 3.8.1 AC Sources – Operating

BASES

BACKGROUND

The unit Class 1E AC Electrical Power Distribution System AC sources consist of the offsite power sources and the onsite standby power sources (diesel generators (DGs)). As required by 10 CFR 50, Appendix A, GDC 17 (Ref. 1), the design of the AC electrical power system provides independence and redundancy to ensure an available source of power to the Engineered Safety Feature (ESF) systems.

The Class 1E AC distribution system supplies electrical power to three divisional load groups, Divisions 1, 2, and 3, with each division powered by an independent Class 1E 4.16 kV emergency bus (refer to LCO 3.8.7, "Distribution Systems – Operating"). The Division 2 emergency bus associated with each unit is shared by each unit since some systems are common to both units. The opposite unit Division 2 emergency bus supports equipment required to be OPERABLE by LCO 3.6.3.1, "Primary Containment Hydrogen Recombiners," LCO 3.6.4.3, "Standby Gas Treatment (SGT) System," LCO 3.7.4, "Control Room Area Filtration (CRAF) System," and LCO 3.7.5, "Control Room Area Ventilation Air Conditioning (AC) System." Division 1 and 2 emergency buses have access to two offsite power supplies (one normal and one alternate). The alternate offsite power source is normally supplied via the opposite unit system auxiliary transformer (SAT) and the opposite unit circuit path. The alternate offsite circuit path includes the associated opposite unit's 4.16 kV emergency bus, unit tie breakers, and associated interconnecting bus to the given unit's 4.16 kV emergency bus. Division 3 load group has access to one offsite power supply (respective unit's SAT). Division 2 and 3 emergency buses on each unit have a dedicated onsite DG. The Division 1 emergency bus of both units share a common DG. The ESF systems of any two of the three divisions provide for the minimum safety functions necessary to shut down the unit and maintain it in a safe shutdown condition.

Offsite power is supplied to the switchyard from the transmission network. From the switchyard two electrically

(continued)

BASES

BACKGROUND
(continued)

and physically separated circuits provide AC power to the unit onsite Class 1E 4.16 kV emergency buses. The unit SAT provides the normal source of offsite power to the respective unit's Division 1, 2, and 3 4.16 kV emergency buses. In the event of a loss of unit SAT, the Division 1 and 2 emergency buses fast transfer to the UAT (which is connected to the main generator output). The UAT is rated to carry all onsite power to the unit, but is not considered an offsite source unless it is being backfed with the main generator disconnect links removed. The Division 3 emergency bus has no second offsite power source, and will automatically be supplied by the Division 3 DG after the bus is deenergized. The Division 1 and 2 emergency buses can be manually transferred to the alternate offsite power source through the unit ties on a dead bus transfer or on a live bus transfer if the DG is supplying power to the bus. The offsite AC electrical power sources are designed and located so as to minimize to the extent practical the likelihood of their simultaneous failure under operating and postulated accident and environmental conditions. A detailed description of the offsite power network and circuits to the onsite Class 1E 4.16 kV emergency buses is found in UFSAR, Chapter 8 (Ref. 2).

A qualified offsite circuit consists of all breakers, transformers, switches, interrupting devices, cabling, and controls required to transmit power from the offsite transmission network to the onsite Class 1E emergency buses.

Onsite standby power is provided by a total of five DGs for both units. The onsite standby power source for each Division 2 and 3 4.16 kV emergency bus on each unit is a dedicated DG. (DGs 1A and 1B for Unit 1 and DGs 2A and 2B for Unit 2). The onsite standby power source for the Division 1 emergency bus on each unit is a common DG (DG 0). Each DG will start on emergency bus degraded voltage or undervoltage from its associated 4.16 kV emergency bus (refer to LCO 3.3.8.1, "Loss of Power (LOP) Instrumentation"). The Division 2 and 3 DGs will start on an Emergency Core Cooling System (ECCS) actuation signal (reactor vessel low water level or high drywell pressure) from the respective unit. The Division 1 DG (common DG) will start on an ECCS actuation signal (reactor vessel low

(continued)

BASES

BACKGROUND
(continued)

water level or high drywell pressure) from either unit. Although the DGs start on an ECCS actuation signal from the respective unit, the DGs are not connected to the 4.16 kV emergency bus unless an undervoltage condition occurs on the bus.

In the event of a loss of offsite power, the ESF electrical loads are automatically connected to the DGs, as required, in sufficient time to provide for safe reactor shutdown and to mitigate the consequences of a Design Basis Accident (DBA) such as a loss of coolant accident (LOCA).

If an undervoltage condition occurs on a Division 1 or 2 emergency bus, the associated DG starts, bus loads are shed, the DG will automatically connect to the emergency bus, and loads necessary for safe shutdown of the unit are connected automatically or manually. If an ECCS actuation signal is present concurrent with an undervoltage condition on the Division 1 or 2 emergency bus, the associated DG starts, bus loads are shed as required, the DG will automatically connect to the emergency bus, and the required ESF loads are automatically connected. Sequencing of Division 1 and 2 emergency loads is accomplished by time delay relays so that overloading of the DG is prevented. The Division 3 emergency bus has no shedding or sequencing.

The DGs satisfy the following Regulatory Guide 1.9 (Ref. 3) ratings:

- a. 2600 kW - continuous;
- b. 2860 kW - 2000 hour;
- c. 2987 kW - 7 day;
- d. 2860 kW - 2 hours in any 24 hour period (10% overload); and
- e. 3040 kW - 30 minute.

APPLICABLE
SAFETY ANALYSES

The initial conditions of DBA and transient analyses in the UFSAR, Chapter 6 (Ref. 4) and Chapter 15 (Ref. 5), assume ESF systems are OPERABLE. The AC electrical power sources

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BASES

APPLICABLE
SAFETY ANALYSES
(continued)

are designed to provide sufficient capacity, capability, redundancy, and reliability to ensure the availability of necessary power to ESF systems so that the fuel, Reactor Coolant System (RCS), and containment design limits are not exceeded. These limits are discussed in more detail in the Bases for Section 3.2, Power Distribution Limits; Section 3.5, Emergency Core Cooling System (ECCS) and Reactor Core Isolation Cooling (RCIC) System; and Section 3.6, Containment Systems.

The OPERABILITY of the AC electrical power sources is consistent with the initial assumptions of the accident analyses and is based upon meeting the design basis of the unit. This includes maintaining the onsite or offsite AC sources OPERABLE during accident conditions in the event of:

- a. An assumed loss of all offsite power or all onsite AC power; and
- b. A worst case single failure.

AC sources satisfy the requirements of Criterion 3 of 10 CFR 50.36(c)(2)(ii).

LCO

Two qualified circuits (normal and alternate) between the offsite transmission network and the onsite Class 1E Distribution System (i.e., the unit Division 1, 2, and 3 4.16 kV emergency buses and the opposite unit Division 2 4.16 kV emergency bus), three separate and independent unit DGs, and the opposite unit's DG capable of supporting the opposite unit Division 2 onsite Class 1E AC electrical power distribution subsystem to power the equipment required to be OPERABLE by LCO 3.6.3.1, LCO 3.6.4.3, LCO 3.7.4, and LCO 3.7.5 ensure availability of the required power to shut down the reactor and maintain it in a safe shutdown condition after an anticipated operational occurrence (AOO) or a postulated DBA. A specific LCO requirement for a qualified circuit to provide power to the opposite unit Division 2 4.16 kV emergency bus is not provided since the alternate qualified circuit to the units Division 2 4.16 kV emergency bus encompasses the circuit path to the opposite unit Division 2 4.16 kV emergency bus.

Qualified offsite circuits are those that are described in the UFSAR and are part of the licensing basis for the unit.

(continued)

BASES

LCO
(continued)

Each offsite circuit must be capable of maintaining rated frequency and voltage, and accepting required loads during an accident, while connected to the emergency buses. For the normal offsite circuit, the OPERABLE qualified offsite circuit consists of the required incoming breaker(s) and disconnects from the 345 kV switchyard to and including the SAT, the respective circuit path to and including the feeder breakers to the required unit Division 1, 2, and 3 4.16 kV emergency buses.

For the alternate offsite circuit, the OPERABLE qualified offsite circuit consists of the required incoming breaker(s) and disconnects from the 345 kV switchyard to and including the SAT or UAT (backfeed mode), to and including the opposite unit 4.16 kV emergency bus, the opposite unit circuit path to and including the unit tie breakers (breakers 1414, 1424, 2414, 2424), and the respective circuit path to the required Division 1 and 2 4.16 kV emergency buses.

Each unit DG must be capable of starting, accelerating to rated speed and voltage, and connecting to its respective ESF bus on detection of bus undervoltage. This sequence must be accomplished within 13 seconds. Each DG must also be capable of accepting required loads within the assumed loading sequence intervals, and must continue to operate until offsite power can be restored to the 4.16 kV emergency buses. These capabilities are required to be met from a variety of initial conditions such as DG in standby with engine hot and DG in standby with engine at ambient conditions. Additional DG capabilities must be demonstrated to meet required Surveillances, e.g., capability of the Division 1 and 2 DGs to revert to standby status on an ECCS signal while operating in parallel test mode. Proper sequencing of loads, including tripping of nonessential loads, is a required function for DG OPERABILITY.

The opposite unit's DG must be capable of starting, accelerating to rated speed and voltage, and connecting to the opposite unit's Division 2 Class 1E AC electrical power distribution subsystem on detection of bus undervoltage. This sequence must be accomplished within 13 seconds and is required to be met from the same variety of initial conditions specified for the unit DGs.

(continued)

BASES

LCO
(continued)

In addition, day tank storage and fuel oil transfer system requirements must be met for each required DG.

The AC sources in one division must be separate and independent (to the extent possible) of the AC sources in the other division(s). For the DGs, the separation and independence are complete. For the offsite AC sources, the separation and independence are to the extent practical. A qualified circuit may be connected to all divisions of either unit, with manual transfer capability to the other circuit OPERABLE, and not violate separation criteria. A qualified circuit that is not connected to the 4.16 kV emergency buses is required to have OPERABLE manual transfer capability (from the control room) to the associated 4.16 kV emergency buses to support OPERABILITY of that qualified circuit.

APPLICABILITY

The AC sources are required to be OPERABLE in MODES 1, 2, and 3 to ensure that:

- a. Acceptable fuel design limits and reactor coolant pressure boundary limits are not exceeded as a result of AOOs or abnormal transients; and
- b. Adequate core cooling is provided and containment OPERABILITY and other vital functions are maintained in the event of a postulated DBA.

Note 1 has been added taking exception to the Applicability requirements for Division 3 sources, provided the High Pressure Core Spray (HPCS) System is declared inoperable. This exception is intended to allow declaring of the Division 3 inoperable either in lieu of declaring the Division 3 source inoperable, or at any time subsequent to entering ACTIONS for an inoperable Division 3 source. This exception is acceptable since, with the Division 3 inoperable and the associated ACTIONS entered, the Division 3 AC sources provide no additional assurance of meeting the above criteria. In addition, when this Note allowance is being used, both AC sources could be inoperable such that the Division 3 AC distribution subsystem is de-energized. In this case (the Division 3 AC electrical power distribution subsystem inoperable), LCO 3.0.6 would not preclude entry into the Distribution System ACTIONS since, with the Division 3 AC sources not required OPERABLE as

(continued)

BASES

APPLICABILITY
(continued)

allowed by this Note, the Division 3 AC sources cannot be considered as a support system to the Division 3 AC distribution subsystem. Thus, as required by LCO 3.0.2, the Distribution System-Operating ACTIONS for the inoperable Division 3 AC electrical power distribution subsystem must be entered.

Note 2 has been added taking exception to the Applicability requirements for the required opposite unit's Division 2 DG in LCO 3.8.1.c, provided the associated required equipment is inoperable (i.e., one SGT subsystem, one primary containment hydrogen recombiner subsystem, one control room area filtration subsystem, and one control room area ventilation air conditioning subsystem). This exception is intended to allow declaring the opposite unit's Division 2 supported equipment inoperable either in lieu of declaring the opposite unit's Division 2 DG inoperable, or at any time subsequent to entering ACTIONS for an inoperable opposite unit Division 2 DG. This exception is acceptable since, with the opposite unit powered Division 2 equipment inoperable and the associated ACTIONS entered, the opposite unit Division 2 DG provides no additional assurance of meeting the above criteria.

AC power requirements for MODES 4 and 5 and other conditions in which AC sources are required are covered in LCO 3.8.2, "AC Sources – Shutdown."

ACTIONS

A.1

To ensure a highly reliable power source remains, it is necessary to verify the availability of the remaining required offsite circuits on a more frequent basis. Since the Required Action only specifies "perform," a failure of SR 3.8.1.1 acceptance criteria does not result in the Required Action not met. However, if a second required circuit fails SR 3.8.1.1, the second offsite circuit is inoperable, and Condition D, for two required offsite circuits inoperable, is entered.

A.2

Required Action A.2, which only applies if the division cannot be powered from an offsite source, is intended to

(continued)

BASES

ACTIONS

A.2 (continued)

provide assurance that an event with a coincident single failure of the associated DG does not result in a complete loss of safety function of critical systems. These features are designed with redundant safety related divisions (i.e., single division systems are not included, although, for this Required Action, Division 3 (HPCS System) is considered redundant to Division 1 and 2 ECCS). Redundant required features failures consist of inoperable features associated with a division redundant to the division that has no offsite power available.

The Completion Time for Required Action A.2 is intended to allow time for the operator to evaluate and repair any discovered inoperabilities. This Completion Time also allows for an exception to the normal "time zero" for beginning the allowed outage time "clock." In this Required Action, the Completion Time only begins on discovery that both:

- a. The division has no offsite power available to supply its loads; and
- b. A redundant required feature on another division is inoperable.

If, at any time during the existence of this Condition (one required offsite circuit inoperable), a redundant required feature subsequently becomes inoperable, this Completion Time begins to be tracked.

Discovering no offsite power available to one division of the onsite Class 1E Power Distribution System coincident with one or more inoperable redundant required support or supported features, or both, that are associated with the other division that has offsite power, results in starting the Completion Time for the Required Action. Twenty-four hours is acceptable because it minimizes risk while allowing time for restoration before the unit is subjected to transients associated with shutdown.

The remaining OPERABLE offsite circuit and DGs are adequate to supply electrical power to the onsite Class 1E Distribution System. Thus, on a component basis, single failure protection may have been lost for the required

(continued)

BASES

ACTIONS

A.2 (continued)

feature's function; however, function is not lost. The 24 hour Completion Time takes into account the component OPERABILITY of the redundant counterpart to the inoperable required feature. Additionally, the 24 hour Completion Time takes into account the capacity and capability of the remaining AC sources, a reasonable time for repairs, and the low probability of a DBA occurring during this period.

A.3

According to Regulatory Guide 1.93 (Ref. 6), operation may continue in Condition A for a period that should not exceed 72 hours.

With one required offsite circuit inoperable, the reliability of the offsite system is degraded, and the potential for a loss of offsite power is increased, with attendant potential for a challenge to the plant safety systems. In this condition, however, the remaining OPERABLE offsite circuit and DGs are adequate to supply electrical power to the onsite Class 1E distribution system.

The Completion Time takes into account the capacity and capability of the remaining AC sources, reasonable time for repairs, and the low probability of a DBA occurring during this period.

The second Completion Time for Required Action A.3 establishes a limit on the maximum time allowed for any combination of required AC power sources to be inoperable during any single contiguous occurrence of failing to meet the LCO. If Condition A is entered while, for instance, the common DG is inoperable for pre-planned maintenance and that DG is subsequently returned OPERABLE, the LCO may already have been not met for up to 7 days. This situation could lead to a total of 10 days, since initial failure to meet the LCO, to restore the offsite circuit. At this time, a unit DG could again become inoperable, the circuit restored OPERABLE, and an additional 72 hours (for a total of 13 days) allowed prior to complete restoration of the LCO. The 10 day Completion Time provides a limit on the time allowed in a specified condition after discovery of failure to meet LCO 3.8.1.a or b. This limit is considered

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BASES

ACTIONS

A.3 (continued)

reasonable for situations in which Conditions are entered concurrently for combinations of Conditions A, B, and C. The "AND" connector between the 72 hour and 10 day Completion Times means that both Completion Times apply simultaneously, and the more restrictive must be met.

Similar to Required Action A.2, the Completion Time of Required Action A.3 allows for an exception to the normal "time zero" for beginning the allowed outage time "clock." This exception results in establishing the "time zero" at the time LCO 3.8.1.a or b was initially not met, instead of at the time that Condition A was entered.

B.1

Condition B provides appropriate compensatory measures to allow performance of pre-planned maintenance or testing on the common DG. Pre-planned maintenance or testing includes preventative maintenance, modifications, and performance of Surveillance Requirements. The Note effectively only allows Condition B to be used for the common DG when the opposite unit is not in MODE 1, 2, or 3. When the common DG becomes inoperable while both units are in MODE 1, 2, or 3, Condition C must be entered for both units and the associated Required Actions performed.

Required Action B.1, is intended to provide assurance that a loss of offsite power, during the period that the common DG or its supported equipment is inoperable for the purposes of completing pre-planned maintenance, modifications, or Surveillance Requirements, does not result in a complete loss of safety function of critical systems. This is accomplished by making an additional source available to support the unit and opposite unit Division 2 emergency buses. This additional source is the unit or opposite unit Division 2 DG. To ensure this alternate highly reliable power source is available during operation in Condition B, it is necessary to temporarily modify the control circuit for the unit crosstie circuit breakers between 4.16 kV emergency buses 142Y and 242Y to allow the breakers to be closed with a DG powering one of the Division 2 emergency buses (142Y or 242Y) so that the unit or opposite unit Division 2 DG can supply the unit and opposite unit

(continued)

BASES

ACTIONS

B.1 (continued)

Division 2 emergency buses. Therefore, the unit or opposite unit Division 2 DG must be OPERABLE with the capability to be manually aligned to the unit and opposite unit Division 2 emergency buses. The Completion Time ensures the alternate source to the Division 2 emergency buses is available whenever the plant is operating in Condition B. If Required Action B.1 and the associated Completion Time are not met, Condition C must be entered and the Required Actions taken.

B.2

To ensure a highly reliable power source remains, it is necessary to verify the availability of the remaining required offsite circuits on a more frequent basis. Since the Required Action only specifies "perform," a failure to meet SR 3.8.1.1 acceptance criteria does not result in a Required Action being not met. However, if a circuit fails to pass SR 3.8.1.1, it is inoperable. Upon offsite circuit inoperability, additional Conditions must then be entered.

B.3

Required Action B.3 is intended to provide assurance that a loss of offsite power, during the period that the common DG is inoperable for the purposes of completing pre-planned maintenance, modifications, or Surveillance Requirements on the common DG or its support systems, does not result in a complete loss of safety function of critical systems. These features are designed with redundant safety related divisions (i.e., single division systems are not included, although for this Required Action, Division 3 (HPCS) is considered redundant to Division 1 and Division 2 ECCS). Redundant required feature failures consist of inoperable features associated with a division redundant to the division that has an inoperable DG.

The Completion Time is intended to allow the operator time to evaluate and repair any discovered inoperabilities. This Completion Time also allows for an exception to the normal "time zero" for beginning the allowed outage time "clock." In this Required Action, the Completion Time only begins on discovery that both:

(continued)

BASES

ACTIONS

B.3 (continued)

- a. An inoperable common DG exists; and
- b. A redundant required feature on another division is inoperable.

If, at any time during the existence of this Condition (the common DG inoperable due to pre-planned maintenance, modification, or testing), a redundant required feature subsequently becomes inoperable, this Completion Time begins to be tracked.

Discovering the common DG inoperable coincident with one or more redundant required support or supported features, or both, that are associated with the redundant OPERABLE DG(s), results in starting the Completion Time for the Required Action. Four hours from the discovery of these events existing concurrently is acceptable because it minimizes risk while allowing time for restoration before subjecting the unit to transients associated with shutdown. The remaining OPERABLE DGs and offsite circuits are adequate to supply electrical power to the onsite Class 1E Distribution System. Thus, on a component basis, single failure protection for the required feature's function may have been lost; however, function has not been lost. The 4 hour Completion Time takes into account the component OPERABILITY of the redundant counterpart to the inoperable required feature. Additionally, the 4 hour Completion Time takes into account the capacity and capability of the remaining AC sources, a reasonable time for repairs, and low probability of a DBA occurring during this period.

B.4

One common DG provides onsite standby power to the Division 1 emergency buses on both units. This Required Action provides a 7 day time period to perform pre-planned maintenance or testing on the common DG while precluding the shutdown of both units. Pre-planned maintenance or testing includes preventative maintenance, modifications, and performance of Surveillance Requirements. The Note to Condition B effectively only allows the 7 day Completion Time to be used for the common DG when the opposite unit is not in MODE 1, 2, or 3. When the common DG becomes

(continued)

BASES

ACTIONS

B.4 (continued)

inoperable while both units are in MODE 1, 2, or 3, Condition C must be entered for both units and the associated Required Actions performed. The 4.16 kV emergency bus design is sufficient to allow operation to continue in Condition B for a period that should not exceed 7 days. In this condition, the remaining OPERABLE DGs and offsite circuits are adequate to supply electrical power to the onsite Class 1E Distribution System. The 7 day Completion Time takes into account the capacity and capability of the remaining AC sources, a reasonable time for repairs, and low probability of a DBA occurring during this period.

The second Completion Time for Required Action B.4 establishes a limit on the maximum time allowed for any combination of required AC power sources to be inoperable during any single contiguous occurrence of failing to meet LCO 3.8.1.a or b. If Condition B is entered while, for instance, an offsite circuit is inoperable and that circuit is subsequently restored OPERABLE, the LCO may already have been not met for up to 72 hours. This situation could lead to a total of 10 days, since initial failure of the LCO, to restore the DG. At this time, an offsite circuit could again become inoperable, the DG restored OPERABLE, and an additional 72 hours (for a total of 13 days) allowed prior to complete restoration of the LCO. The 10 day Completion Time provides a limit on the time allowed in a specified condition after discovery of failure to meet LCO 3.8.1.a or b. This limit is considered reasonable for situations in which Conditions A, B, and C. The "AND" connector between the 7 day and 10 day Completion Times means that both Completion Times apply simultaneously, and the more restrictive must be met.

Similar to Required Action B.3, the Completion Time of Required Action B.4 allows for an exception to the normal "time zero" for beginning the allowed outage time "clock." This exception results in establishing the "time zero" at the time LCO 3.8.1.a or b was initially not met, instead of the time that Condition B was entered.

(continued)

BASES

ACTIONS
(continued)

C.1

To ensure a highly reliable power source remains, it is necessary to verify the availability of the remaining required offsite circuit on a more frequent basis. Since the Required Action only specifies "perform," a failure of SR 3.8.1.1 acceptance criteria does not result in a Required Action being not met. However, if a circuit fails to pass SR 3.8.1.1, it is inoperable. Upon offsite circuit inoperability, additional Conditions must then be entered.

C.2

Required Action C.2 is intended to provide assurance that a loss of offsite power, during the period that the DG(s) is inoperable as described in Condition C, does not result in a complete loss of safety function of critical systems. These features are designed with redundant safety related divisions (i.e., single division systems are not included, although, for this Required Action, Division 3 (HPCS System) is considered redundant to Division 1 and 2 ECCS). Redundant required features failures consist of inoperable features associated with a division redundant to the division that has an inoperable DG.

The Completion Time is intended to allow the operator time to evaluate and repair any discovered inoperabilities. This Completion Time also allows for an exception to the normal "time zero" for beginning the allowed outage time "clock." In this Required Action, the Completion Time only begins on discovery that both:

- a. An inoperable DG exists; and
- b. A redundant required feature on another division is inoperable.

If, at any time during the existence of this Condition (DG(s) inoperable as described in Condition C), a redundant required feature subsequently becomes inoperable, this Completion Time begins to be tracked.

Discovering required DG(s) inoperable coincident with one or more redundant required support or supported features, or

(continued)

BASES

ACTIONS

C.2 (continued)

both, that are associated with the redundant OPERABLE DG(s), results in starting the Completion Time for the Required Action. Four hours from the discovery of these events existing concurrently is acceptable because it minimizes risk while allowing time for restoration before subjecting the unit to transients associated with shutdown.

The remaining OPERABLE DGs and offsite circuits are adequate to supply electrical power to the onsite Class 1E Distribution System. Thus, on a component basis, single failure protection for the required feature's function may have been lost; however, function has not been lost. The 4 hour Completion Time takes into account the component OPERABILITY of the redundant counterpart to the inoperable required feature. Additionally, the 4 hour Completion Time takes into account the capacity and capability of the remaining AC sources, reasonable time for repairs, and low probability of a DBA occurring during this period.

C.3.1 and C.3.2

Required Action C.3.1 provides an allowance to avoid unnecessary testing of OPERABLE DGs. If it can be determined that the cause of the inoperable DG(s) does not exist on the OPERABLE DG(s), SR 3.8.1.2 does not have to be performed. If the cause of inoperability exists on other DGs, the other DGs are declared inoperable upon discovery, and Condition F or H of LCO 3.8.1 is entered, as applicable. Once the failure is repaired, and the common cause failure no longer exists, Required Action C.3.1 is satisfied. If the cause of the initial inoperable DG cannot be confirmed not to exist on the remaining DG(s), performance of SR 3.8.1.2 suffices to provide assurance of continued OPERABILITY of those DG(s).

In the event the inoperable DG(s) is restored to OPERABLE status prior to completing either C.3.1 or C.3.2, the station corrective action program will continue to evaluate the common cause possibility. This continued evaluation, however, is no longer under the 24 hour constraint imposed while in Condition C.

(continued)

BASES

ACTIONS C.3.1 and C.3.2 (continued)

According to Generic Letter 84-15 (Ref. 7), 24 hours is reasonable time to confirm that the OPERABLE DG(s) are not affected by the same problem as the inoperable DG.

C.4

According to Regulatory Guide 1.93 (Ref. 6), operation may continue in Condition C for a period that should not exceed 72 hours. In this condition, the remaining OPERABLE DGs and offsite circuits are adequate to supply electrical power to the onsite Class 1E distribution system. The 72 hour Completion Time takes into account the capacity and capability of the remaining AC sources, reasonable time for repairs, and low probability of a DBA occurring during this period.

The second Completion Time for Required Action C.4 established a limit on the maximum time allowed for any combination of required AC power sources to be inoperable during any single contiguous occurrence of failing to meet LCO 3.8.1.a or b. If Condition C is entered while, for instance, the common DG is inoperable due to pre-planned maintenance and that DG is subsequently restored OPERABLE, the LCO may already have been not met for up to 7 days. This situation could lead to a total of 10 days, since initial failure to meet the LCO, to restore the unit DG. At this time, an offsite circuit could become inoperable, the unit DG restored OPERABLE, and an additional 72 hours (for a total of 13 days) allowed prior to complete restoration of the LCO. The 10 day Completion Time provides a limit on the time allowed in a specified condition after discovery of failure to meet LCO 3.8.1.a or b. This limit is considered reasonable for situations in which Conditions are entered concurrently for combinations of Conditions A, B, and C. The "AND" connector between the 72 hour and 10 day Completion Times means that both Completion Times apply simultaneously, and the more restrictive Completion Time must be met.

(continued)

BASES

ACTIONS

C.4 (continued)

Similar to Required Action C.2, the Completion Time of Required Action C.4 allows for an exception to the normal "time zero" for beginning the allowed outage time "clock." This exception results in establishing the "time zero" at the time the LCO was initially not met, instead of the time Condition C was entered.

D.1 and D.2

Required Action D.1 addresses actions to be taken in the event of concurrent failure of redundant required features. Required Action D.1 reduces the vulnerability to a loss of function. The Completion Time for taking these actions is reduced to 12 hours from that allowed with only one division without offsite power (Required Action A.2). The rationale for the reduction to 12 hours is that Regulatory Guide 1.93 (Ref. 6) allows a Completion Time of 24 hours for two required offsite circuits inoperable, based upon the assumption that two complete safety divisions are OPERABLE. When a concurrent redundant required feature failure exists, this assumption is not the case, and a shorter Completion Time of 12 hours is appropriate. These features are designed with redundant safety related divisions (i.e., single division systems are not included in the list, although, for this Required Action, Division 3 (HPCS System) is considered redundant to Division 1 and 2 ECCS). Redundant required features failures consist of any of these features that are inoperable, because any inoperability is on a division redundant to a division with inoperable offsite circuits.

The Completion Time for Required Action D.1 is intended to allow the operator time to evaluate and repair any discovered inoperabilities. This Completion Time also allows for an exception to the normal "time zero" for beginning the allowed outage time "clock." In this Required Action, the Completion Time only begins on discovery that both:

- a. Two required offsite circuits are inoperable; and

(continued)

BASES

ACTIONS

D.1 and D.2 (continued)

- b. A redundant required feature is inoperable.

If, at any time during the existence of this Condition (two offsite circuits inoperable), a redundant required feature subsequently becomes inoperable, this Completion Time begins to be tracked.

According to Regulatory Guide 1.93 (Ref. 6), operation may continue in Condition D for a period that should not exceed 24 hours. This level of degradation means that the offsite electrical power system may not have the capability to effect a safe shutdown and to mitigate the effects of an accident; however, the onsite AC sources have not been degraded. This level of degradation generally corresponds to a total loss of the immediately accessible offsite power sources.

Because of the normally high availability of the offsite sources, this level of degradation may appear to be more severe than other combinations of two AC sources inoperable that involve one or more DGs inoperable. However, two factors tend to decrease the severity of this degradation level:

- a. The configuration of the redundant AC electrical power system that remains available is not susceptible to a single bus or switching failure; and
- b. The time required to detect and restore an unavailable offsite power source is generally much less than that required to detect and restore an unavailable onsite AC source.

With two of the required offsite circuits inoperable, sufficient onsite AC sources are available to maintain the unit in a safe shutdown condition in the event of a DBA or transient. In fact, a simultaneous loss of offsite AC sources, a LOCA, and a worst case single failure were postulated as a part of the design basis in the safety analysis. Thus, the 24 hour Completion Time provides a period of time to effect restoration of one of the offsite circuits commensurate with the importance of maintaining an AC electrical power system capable of meeting its design criteria.

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BASES

ACTIONS

D.1 and D.2 (continued)

According to Regulatory Guide 1.93 (Ref. 6), with the available offsite AC sources two less than required by the LCO, operation may continue for 24 hours. If two offsite sources are restored within 24 hours, unrestricted operation may continue. If only one offsite source is restored within 24 hours, power operation continues in accordance with Condition A.

E.1 and E.2

Pursuant to LCO 3.0.6, the Distribution System ACTIONS would not be entered even if all AC sources to it were inoperable, resulting in de-energization. Therefore, the Required Actions of Condition E are modified by a Note to indicate that when Condition E is entered with no AC source to any required division (i.e., the division is de-energized), Actions for LCO 3.8.7, "Distribution Systems – Operating," must be immediately entered. This allows Condition E to provide requirements for the loss of an offsite circuit and one required unit DG without regard to whether a division is de-energized. LCO 3.8.7 provides the appropriate restrictions for a de-energized division.

According to Regulatory Guide 1.93 (Ref. 6), operation may continue in Condition E for a period that should not exceed 12 hours. In Condition E, individual redundancy is lost in both the offsite electrical power system and the onsite AC electrical power system. Since power system redundancy is provided by two diverse sources of power, however, the reliability of the power systems in this Condition may appear higher than that in Condition D (loss of both required offsite circuits). This difference in reliability is offset by the susceptibility of this power system configuration to a single bus or switching failure. The 12 hour Completion Time takes into account the capacity and capability of the remaining AC sources, reasonable time for repairs, and low probability of a DBA occurring during this period.

(continued)

BASES

ACTIONS
(continued)

F.1

With two required unit DGs inoperable or both required Division 2 DGs inoperable, there is no more than two remaining standby AC sources. Thus, with an assumed loss of offsite electrical power, sufficient standby AC sources may not be available to power the minimum required ESF functions. Since the offsite electrical power system is the only source of AC power for the majority of ESF equipment at this level of degradation, the risk associated with continued operation for a very short time could be less than that associated with an immediate controlled shutdown (the immediate shutdown could cause grid instability, which could result in a total loss of AC power). Since any inadvertent generator trip could also result in a total loss of offsite AC power, however, the time allowed for continued operation is severely restricted. The intent here is to avoid the risk associated with an immediate controlled shutdown and to minimize the risk associated with this level of degradation.

According to Regulatory Guide 1.93 (Ref. 6), with Division 1 and 2 unit DGs inoperable, operation may continue for a period that should not exceed 2 hours. This Completion Time assumes complete loss of onsite (DG) AC capability to power the minimum loads needed to respond to analyzed events.

In the event the unit Division 3 DG in conjunction with a unit Division 1 or 2 DG is inoperable, with a unit Division 1 or 2 DG remaining, a significant spectrum of breaks would be capable of being responded to with onsite power. Even the worst case event would be mitigated to some extent—an extent greater than a typical two division design in which this condition represents a complete loss of function. Given the remaining function, a 72 hour Completion Time is appropriate. At the end of this 72 hour period, the unit Division 3 system (HPCS System) could be declared inoperable (See Applicability Note 1) and this Condition could be exited with only one remaining required unit DG inoperable. However, with a unit Division 1 or 2 DG remaining inoperable and the HPCS System declared inoperable, a redundant required feature failure exists, according to Required Action B.3 or C.2.

(continued)

BASES

ACTIONS

F.1 (continued)

In the event the required opposite unit Division 2 DG is inoperable in conjunction with a unit Division 2 DG inoperable, the opposite unit Division 2 subsystems (e.g., SGT subsystem) could be declared inoperable at the end of the 2 hour Completion Time (see Applicability Note 2) and this Condition could be exited with only one required unit DG remaining inoperable. However, with the given unit Division 2 DG remaining inoperable and the opposite unit Division 2 subsystems declared inoperable, redundant required feature failures exist, according to Required Action C.2.

G.1 and G.2

If the inoperable AC electrical power sources cannot be restored to OPERABLE status within the associated Completion Time, the unit must be brought to a MODE in which the LCO does not apply. To achieve this status, the unit must be brought to MODE 3 within 12 hours and to MODE 4 within 36 hours. The allowed Completion Times are reasonable, based on operating experience, to reach the required plant conditions from full power conditions in an orderly manner and without challenging plant systems.

H.1

Condition H corresponds to a level of degradation in which all redundancy in the AC electrical power supplies has been lost. At this severely degraded level, any further losses in the AC electrical power system will cause a loss of function. Therefore, no additional time is justified for continued operation. The unit is required by LCO 3.0.3 to commence a controlled shutdown.

SURVEILLANCE
REQUIREMENTS

The AC sources are designed to permit inspection and testing of all important areas and features, especially those that have a standby function, in accordance with 10 CFR 50, GDC 18 (Ref. 8). Periodic component tests are supplemented by extensive functional tests during refueling

(continued)

BASES

SURVEILLANCE
REQUIREMENTS
(continued)

outages under simulated accident conditions. The SRs for demonstrating the OPERABILITY of the DGs are consistent with the recommendations of Regulatory Guide 1.9 (Ref. 3) and Regulatory Guide 1.137 (Ref. 9).

The Surveillances are modified by two Notes to clearly identify how the Surveillances apply to the given unit and opposite unit's Division 2 DGs. Note 1 states that SR 3.8.1.1 through SR 3.8.1.20 are applicable only to the given unit AC electrical power sources and Note 2 states that SR 3.8.1.21 is applicable to the opposite unit's Division 2 DG. These Notes are necessary since the opposite unit AC electrical power source is not required to meet all of the requirements of the given unit AC electrical power sources (e.g., the opposite unit DG is not required to start on the opposite unit's ECCS initiation signal to support OPERABILITY of the given unit).

Where the SRs discussed herein specify voltage and frequency tolerances, the following summary is applicable. The minimum steady state output voltage of 4010 V is greater than 90% of the nominal 4160 V output voltage. This value, which is conservative with respect to the value specified in ANSI C84.1 (Ref. 10), allows for voltage drop to the terminals of 4000 V motors whose minimum operating voltage is specified as 90%, or 3600 V. It also allows for voltage drops to motors and other equipment down through the 120 V level where minimum operating voltage is also usually specified as 90% of name plate rating. The specified maximum steady state output voltage of 4310 V is within the maximum operating voltage of 110% specified for 4000 V motors. It ensures that for a lightly loaded distribution system, the voltage at the terminals of 4000 V motors is no more than the maximum rated operating voltages. The specified minimum and maximum frequencies of the DG are 58.8 Hz and 61.2 Hz, respectively. These values are equal to $\pm 2\%$ of the 60 Hz nominal frequency and are derived from the recommendations given in Regulatory Guide 1.9 (Ref. 3).

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BASES

SURVEILLANCE
REQUIREMENTS
(continued)

SR 3.8.1.1

This SR ensures proper circuit continuity for the offsite AC electrical power supply to the onsite distribution network and availability of offsite AC electrical power. The breaker alignment verifies that each breaker is in its correct position to ensure that distribution buses and loads are connected or capable of being connected to their power source and that appropriate independence of offsite circuits is maintained. The 7 day Frequency is adequate since breaker position is not likely to change without the operator being aware of it and because its status is displayed in the control room.

SR 3.8.1.2 and SR 3.8.1.7

These SRs help to ensure the availability of the standby electrical power supply to mitigate DBAs and transients and maintain the unit in a safe shutdown condition.

To minimize the wear on moving parts that do not get lubricated when the engine is not running, these SRs have been modified by Notes (Note 1 for SR 3.8.1.7 and Note 1 for SR 3.8.1.2) to indicate that all DG starts for these Surveillances may be preceded by an engine prelube period and followed by a warmup period prior to loading, as recommended by the manufacturer.

For the purposes of SR 3.8.1.2, the DGs are started from normal standby conditions and for the purposes of SR 3.8.1.7, the DGs are started from ambient standby conditions. Normal standby conditions for a DG means that the diesel engine jacket water and lube oil are being continuously circulated and temperature is being maintained consistent with manufacturer recommendations. Ambient standby conditions for a DG mean that the diesel engine jacket water and lube oil temperatures are within the prescribed temperature bands of these subsystems when the DG has been at rest for an extended period with the pre-lube oil and jacket water circulating systems operational.

(continued)

BASES

SURVEILLANCE
REQUIREMENTS

SR 3.8.1.2 and SR 3.8.1.7 (continued)

In order to reduce stress and wear on diesel engines, the manufacturer has recommended that the starting speed of DGs be limited, that warmup be limited to this lower speed, and that DGs be gradually accelerated to synchronous speed prior to loading. These start procedures are the intent of Note 2 of SR 3.8.1.2.

SR 3.8.1.7 requires that, at a 184 day Frequency, the DG starts from standby conditions and achieves required voltage and frequency within 13 seconds. The 13 second start requirement supports the assumptions in the design basis LOCA analysis (Ref. 5). The 13 second start requirement may not be applicable to SR 3.8.1.2 (see Note 2 of SR 3.8.1.2), when a modified start procedure as described above is used. If a modified start is not used, the 13 second start requirement of SR 3.8.1.7 applies. Since SR 3.8.1.7 does require a 13 second start, it is more restrictive than SR 3.8.1.2, and it may be performed in lieu of SR 3.8.1.2.

In addition, the DG is required to maintain proper voltage and frequency limits after steady state is achieved. The voltage and frequency limits are normally achieved within 13 seconds. The time for the DG to reach steady state operation, unless the modified DG start method is employed, is periodically monitored and the trend evaluated to identify degradation of governor and voltage regulator performance.

To minimize testing of the common DG, Note 3 of SR 3.8.1.2 and Note 2 of SR 3.8.1.7 allow a single test for the common DG (instead of two tests, one for each unit) to satisfy the requirements of both units. This is allowed since the main purpose of the Surveillance can be met by performing the test on either unit. However, to the extent practicable, the tests should be alternated between units. If the DG fails one of these Surveillances, the DG should be considered inoperable on both units, unless the cause of the failure can be directly related to only one unit.

The 31 day Frequency for SR 3.8.1.2 is consistent with Regulatory Guide 1.9 (Ref. 3). The 184 day Frequency for SR 3.8.1.7 is a reduction in cold testing consistent with

(continued)

BASES

SURVEILLANCE
REQUIREMENTS

SR 3.8.1.2 and SR 3.8.1.7 (continued)

Generic Letter 84-15 (Ref. 7). These Frequencies provide adequate assurance of DG OPERABILITY, while minimizing degradation resulting from testing.

SR 3.8.1.3

This Surveillance demonstrates that the DGs are capable of synchronizing and accepting greater than or equal to 90% of the DG continuous load rating. A minimum run time of 60 minutes is required to stabilize engine temperatures, while minimizing the time that the DG is connected to the offsite source.

Although no power factor requirements are established by this SR, the DG is normally operated at a power factor between 0.8 lagging and 1.0 when running synchronized with the grid. The 0.8 power factor value is the design rating of the machine at a particular kVA. The 1.0 power factor value is an operational limitation condition where the reactive power component is zero, which minimizes the reactive heating of the generator. Operating the generator at a power factor between 0.8 lagging and 1.0 avoids adverse conditions associated with underexciting the generator and more closely represents the generator operating requirements when performing its safety function (running isolated on its associated 4160 V emergency bus). The load band is provided to avoid routine overloading of the DG. Routine overloading may result in more frequent teardown inspections in accordance with vendor recommendations in order to maintain DG OPERABILITY.

The 31 day Frequency for this Surveillance is consistent with Regulatory Guide 1.9 (Ref. 3).

Note 1 modifies this Surveillance to indicate that diesel engine runs for this Surveillance may include gradual loading, as recommended by the manufacturer, so that mechanical stress and wear on the diesel engine are minimized.

Note 2 modifies this Surveillance by stating that momentary transients because of changing bus loads do not invalidate this test.

(continued)

BASES

SURVEILLANCE
REQUIREMENTS

SR 3.8.1.3 (continued)

Note 3 indicates that this Surveillance must be conducted on only one DG at a time in order to avoid common cause failures that might result from offsite circuit or grid perturbations.

Note 4 stipulates a prerequisite requirement for performance of this SR. A successful DG start must precede this test to credit satisfactory performance.

To minimize testing of the common DG, Note 5 allows a single test of the common DG (instead of two tests, one for each unit) to satisfy the requirements for both units. This is allowed since the main purpose of the Surveillance can be met by performing the test on either unit. However, to the extent practicable, the test should be alternated between units. If the DG fails one of these Surveillances, the DG should be considered inoperable on both units, unless the cause of the failure can be directly related to only one unit.

SR 3.8.1.4

This SR provides verification that the level of fuel oil in the day tank is at or above the level at which the low level alarm is annunciated. The level is expressed as an equivalent volume in gallons, and is selected to ensure adequate fuel oil for a minimum of 50 minutes of DG operation at rated capacity.

The 31 day Frequency is adequate to assure that a sufficient supply of fuel oil is available, since low level alarms are provided and facility operators would be aware of any large uses of fuel oil during this period.

SR 3.8.1.5

Microbiological fouling is a major cause of fuel oil degradation. There are numerous bacteria that can grow in fuel oil and cause fouling, but all must have a water environment in order to survive. Removal of water from the

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BASES

SURVEILLANCE
REQUIREMENTS

SR 3.8.1.5 (continued)

fuel oil day tanks once every 31 days eliminates the necessary environment for bacterial survival. This is most effective means in controlling microbiological fouling. In addition, it eliminates the potential for water entrainment in the fuel oil during DG operation. Water may come from any of several sources, including condensation, rain water, contaminated fuel oil, and breakdown of the fuel oil by bacteria. Frequent checking for and removal of accumulated water minimizes fouling and provides data regarding the watertight integrity of the fuel oil system. The Surveillance Frequency is established by Regulatory Guide 1.137 (Ref. 10). This SR is for preventive maintenance. The presence of water does not necessarily represent a failure of this SR provided that accumulated water is removed during performance of this Surveillance.

SR 3.8.1.6

This Surveillance demonstrates that each required fuel oil transfer pump operates and automatically transfers fuel oil from its associated storage tank to its associated day tank. It is required to support the continuous operation of standby power sources. This Surveillance provides assurance that the fuel oil transfer pump is OPERABLE, the fuel oil piping system is intact, the fuel delivery piping is not obstructed, and the controls and control systems for automatic fuel transfer systems are OPERABLE.

The Frequency for this SR corresponds to the testing requirements for pumps as contained in the ASME Boiler and Pressure Vessel Code, Section XI (Ref. 11).

SR 3.8.1.8

Transfer of each Division 1 and 2 4.16 kV emergency bus power supply from the normal offsite circuit to the alternate offsite circuit demonstrates the OPERABILITY of the alternate circuit distribution network to power the Division 1 and 2 shutdown loads. The 24 month Frequency of the Surveillance is based on engineering judgment taking

(continued)

BASES

SURVEILLANCE
REQUIREMENTS

SR 3.8.1.8 (continued)

into consideration the plant conditions required to perform the Surveillance, and is intended to be consistent with expected fuel cycle lengths. Operating experience has shown that these components usually pass the SR when performed on the 24 month Frequency. Therefore, the Frequency was concluded to be acceptable from a reliability standpoint.

This SR is modified by a Note. The reason for the Note is that, during operation with the reactor critical, performance of this SR could cause perturbations to the electrical distribution systems that could challenge continued steady state operation and, as a result, plant safety systems. This restriction from normally performing the Surveillance in MODE 1 or 2 is further amplified to allow the Surveillance to be performed for the purpose of reestablishing OPERABILITY (e.g., post work testing following corrective maintenance, corrective modifications, deficient or incomplete surveillance testing, and other unanticipated OPERABILITY concerns) provided an assessment determines plant safety is maintained or enhanced. This assessment shall, as a minimum, consider the potential outcomes and transients associated with a failed Surveillance, a successful Surveillance, and a perturbation of the offsite or onsite system when they are tied together or operated independently for the Surveillance; as well as the operator procedures available to cope with these outcomes. These shall be measured against the avoided risk of a plant shutdown and startup to determine that plant safety is maintained or enhanced when the Surveillance is performed in MODE 1 or 2. Risk insights or deterministic methods may be used for this assessment. Credit may be taken for unplanned events that satisfy this SR.

SR 3.8.1.9

Each DG is provided with an engine overspeed trip to prevent damage to the engine. Recovery from the transient caused by the loss of a large load could cause diesel engine overspeed, which, if excessive, might result in a trip of the engine. This Surveillance demonstrates the DG load response characteristics and capability to reject the

(continued)

BASES

SURVEILLANCE
REQUIREMENTS

SR 3.8.1.9 (continued)

largest single load without exceeding predetermined frequency and while maintaining a specified margin to the overspeed trip. The load referenced for the Division 1 DG is the 1190 kW low pressure core spray pump; for the Division 2 DG, the 638 kW residual heat removal (RHR) pump; and for the Division 3 DG the 2421 kW HPCS pump. This Surveillance may be accomplished by:

- a. Tripping the DG output breaker with the DG carrying greater than or equal to its associated single largest post-accident load while paralleled to offsite power, or while solely supplying the bus; or
- b. Tripping its associated single largest post-accident load with the DG solely supplying the bus.

Consistent with Regulatory Guide 1.9 (Ref. 3), the load rejection test is acceptable if the diesel speed does not exceed 75% of the difference between nominal speed and the overspeed trip setpoint, or 15% above nominal speed, whichever is lower. This corresponds to 66.7 Hz, which is the nominal speed plus 75% of the difference between nominal speed and the overspeed trip setpoint. The 24 month Frequency takes into consideration the plant conditions required to perform the Surveillance, and is intended to be consistent with expected fuel cycle lengths.

This SR has been modified by two Notes. The reason for Note 1 is that during operation with the reactor critical, performance of this SR could cause perturbations to the electrical distribution systems that could challenge continued steady state operation and, as a result, plant safety systems. This restriction from normally performing the Surveillance in MODE 1 or 2 is further amplified to allow the Surveillance to be performed for the purpose of reestablishing OPERABILITY (e.g. post work testing following corrective maintenance, corrective modification, deficient or incomplete surveillance testing, and other unanticipated OPERABILITY concerns) provided an assessment determines plant safety is maintained or enhanced. This assessment shall, as a minimum, consider the potential outcomes and transients associated with a failed Surveillance, a

(continued)

BASES

SURVEILLANCE
REQUIREMENTS

SR 3.8.1.9 (continued)

successful Surveillance, and a perturbation of the offsite or onsite system when they are tied together or operated independently for the Surveillance; as well as the operator procedures available to cope with these outcomes. These shall be measured against the avoided risk of a plant shutdown and startup to determine that plant safety is maintained or enhanced when the Surveillance is performed in MODE 1 or 2. Risk insights or deterministic methods may be used for this assessment. Credit may be taken for unplanned events that satisfy this SR. To minimize testing of the common DG, Note 2 allows a single test of the common DG (instead of two tests, one for each unit) to satisfy the requirements for both units. This is allowed since the main purpose of the Surveillance can be met by performing the test on either unit. If the DG fails one of these Surveillances, the DG should be considered inoperable on both units, unless the cause of the failure can be directly related to only one unit.

SR 3.8.1.10

Consistent with Regulatory Guide 1.9 (Ref. 3), paragraph C.2.2.8, this Surveillance demonstrates the DG capability to reject a full load without overspeed tripping or exceeding the predetermined voltage limits. The DG full load rejection may occur because of a system fault or inadvertent breaker tripping. This Surveillance ensures proper engine generator load response under the simulated test conditions. This test simulates the loss of the total connected load that the DG experiences following a full load rejection and verifies that the DG does not trip upon loss of the load. These acceptance criteria provide DG damage protection. While the DG is not expected to experience this transient during an event, and continues to be available, this response ensures that the DG is not degraded for future application, including reconnection to the bus if the trip initiator can be corrected or isolated.

The 24 month Frequency takes into consideration the plant conditions required to perform the Surveillance, and is intended to be consistent with expected fuel cycle lengths.

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BASES

SURVEILLANCE
REQUIREMENTS

SR 3.8.1.10 (continued)

This SR has been modified by two Notes. The reason for Note 1 is that during operation with the reactor critical, performance of this SR could cause perturbations to the electrical distribution systems that could challenge continued steady state operation and, as a result, plant safety systems. This restriction from normally performing the Surveillance in MODE 1 or 2 is further amplified to allow the Surveillance to be performed for the purpose of reestablishing OPERABILITY (e.g., post work testing following corrective maintenance, corrective modification, deficient or incomplete surveillance testing, and other unanticipated OPERABILITY concerns) provided an assessment determines plant safety is maintained or enhanced. This assessment shall, as a minimum, consider the potential outcomes and transients associated with a failed Surveillance, a successful Surveillance, and a perturbation of the offsite or onsite system when they are tied together or operated independently for the Surveillance; as well as the operator procedures available to cope with these outcomes. These shall be measured against the avoided risk of a plant shutdown and startup to determine that plant safety is maintained or enhanced when the Surveillance is performed in MODE 1 or 2. Risk insights or deterministic methods may be used for this assessment. Credit may be taken for unplanned events that satisfy this SR. To minimize testing of the common DG, Note 2 allows a single test of the common DG (instead of two tests, one for each unit) to satisfy the requirements for both units. This is allowed since the main purpose of the Surveillance can be met by performing the test on either unit. If the DG fails one of these Surveillances, the DG should be considered inoperable on both units, unless the cause of the failure can be directly related to only one unit.

SR 3.8.1.11

Consistent with Regulatory Guide 1.9 (Ref. 3), paragraph C.2.2.4, this Surveillance demonstrates the as designed operation of the standby power sources during loss of the offsite source. This test verifies all actions encountered from the loss of offsite power, including

(continued)

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REQUIREMENTS

SR 3.8.1.11 (continued)

shedding of the nonessential loads (Divisions 1 and 2 only) and energization of the emergency buses and respective loads from the DG. It further demonstrates the capability of the DG to automatically achieve the required voltage and frequency within the specified time.

The DG auto-start and energization of permanently connected loads time of 13 seconds is derived from requirements of the accident analysis for responding to a design basis large break LOCA (Ref. 5). The Surveillance should be continued for a minimum of 5 minutes in order to demonstrate that all starting transients have decayed and stability has been achieved.

The requirement to verify the connection and power supply of permanently connected loads and auto-connected loads is intended to satisfactorily show the relationship of these loads to the DG loading logic. In certain circumstances, many of these loads cannot actually be connected or loaded without undue hardship or potential for undesired operation. For instance, ECCS injection valves are not desired to be stroked open, systems are not capable of being operated at full flow, or RHR systems performing a decay heat removal function are not desired to be realigned to the ECCS mode of operation. In lieu of actual demonstration of the connection and loading of these loads, testing that adequately shows the capability of the DG system to perform these functions is acceptable. This testing may include any series of sequential, overlapping, or total steps so that the entire connection and loading sequence is verified.

The Frequency of 24 months takes into consideration plant conditions required to perform the Surveillance, and is intended to be consistent with expected fuel cycle lengths.

This SR is modified by two Notes. The reason for Note 1 is to minimize wear and tear on the DGs during testing. The prelube period shall be consistent with manufacturer recommendations. For the purpose of this testing, the DGs must be started from normal standby conditions, that is, with the engine jacket water and lube oil being continuously circulated and temperature is being maintained consistent with manufacturer recommendations. The reason for Note 2 is

(continued)

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SR 3.8.1.11 (continued)

that performing the Surveillance would remove a required offsite circuit from service, perturb the electrical distribution system, and challenge plant safety systems. This restriction from normally performing the Surveillance in MODE 1 or 2 is further amplified to allow portions of the Surveillance to be performed for the purpose of reestablishing OPERABILITY (e.g., post work testing following corrective maintenance, corrective modification, deficient or incomplete surveillance testing, and other unanticipated OPERABILITY concerns) provided an assessment determines plant safety is maintained or enhanced. This assessment shall, as a minimum, consider the potential outcomes and transients associated with a failed partial Surveillance, a successful partial Surveillance, and a perturbation of the offsite or onsite system when they are tied together or operated independently for the partial Surveillance; as well as the operator procedures available to cope with these outcomes. These shall be measured against the avoided risk of a plant shutdown and startup to determine that plant safety is maintained or enhanced when portions of the Surveillance are performed in MODE 1 or 2. Risk insights or deterministic methods may be used for this assessment. Credit may be taken for unplanned events that satisfy this SR.

SR 3.8.1.12

Consistent with Regulatory Guide 1.9 (Ref. 3), paragraph C.2.2.5, this Surveillance demonstrates that the DG automatically starts and achieves the required voltage and frequency within the specified time (13 seconds) from the design basis actuation signal (LOCA signal). In addition, the DG is required to maintain proper voltage and frequency limits after steady state is achieved. The voltage and frequency limits are normally achieved within 13 seconds. The time for the DG to reach the steady state voltage and frequency limits is periodically monitored and the trend evaluated to identify degradation of governor and voltage regulator performance. The DG is required to operate for ≥ 5 minutes. The 5 minute period provides sufficient time to demonstrate stability.

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SURVEILLANCE
REQUIREMENTS

SR 3.8.1.12 (continued)

The Frequency of 24 months takes into consideration plant conditions required to perform the Surveillance, and is intended to be consistent with the expected fuel cycle lengths.

This SR is modified by two Notes. The reason for Note 1 is to minimize wear and tear on the DGs during testing. The prelube period shall be consistent with manufacturer recommendations. For the purpose of this testing, the DGs must be started from normal standby conditions, that is, with the engine jacket water and lube oil being continuously circulated and temperature is being maintained consistent with manufacturer recommendations. The reason for Note 2 is that during operation with the reactor critical, performance of this SR could cause perturbations to the electrical distribution systems that could challenge continued steady state operation and, as a result, plant safety systems. This restriction from normally performing the Surveillance in MODE 1 or 2 is further amplified to allow portions of the Surveillance to be performed for the purpose of reestablishing OPERABILITY (e.g., post work testing following corrective maintenance, corrective modification, deficient or incomplete surveillance testing, and other unanticipated OPERABILITY concerns) provided an assessment determines plant safety is maintained or enhanced. This assessment shall, as a minimum, consider the potential outcomes and transients associated with a failed partial Surveillance, a successful partial Surveillance, and a perturbation of the offsite or onsite system when they are tied together or operated independently for the partial Surveillance; as well as the operator procedures available to cope with these outcomes. These shall be measured against the avoided risk of a plant shutdown and startup to determine that plant safety is maintained or enhanced when portions of the Surveillance are performed in MODE 1 or 2. Risk insights or deterministic methods may be used for this assessment. Credit may be taken for unplanned events that satisfy this SR.

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REQUIREMENTS
(continued)

SR 3.8.1.13

Consistent with Regulatory Guide 1.9 (Ref. 3) paragraph C.2.2.12, this Surveillance demonstrates that DG non-critical protective functions (e.g., high jacket water temperature) are bypassed on a loss of voltage signal concurrent with an ECCS initiation test signal and critical protective functions (engine overspeed and generator differential current) trip the DG to avert substantial damage to the DG unit. The non-critical trips are bypassed during DBAs and provide an alarm on an abnormal engine condition. This alarm provides the operator with sufficient time to react appropriately. The DG availability to mitigate the DBA is more critical than protecting the engine against minor problems that are not immediately detrimental to emergency operation of the DG.

The 24 month Frequency is based on engineering judgment, taking into consideration plant conditions required to perform the Surveillance, and is intended to be consistent with expected fuel cycle lengths.

This SR is modified by a Note. The reason for the Note is that performing the Surveillance removes a required DG from service. This restriction from normally performing the Surveillance in MODE 1 or 2 is further amplified to allow the Surveillance to be performed for the purpose of reestablishing OPERABILITY (e.g., post work testing following corrective maintenance, corrective modification, deficient or incomplete surveillance testing, and other unanticipated OPERABILITY concerns) provided an assessment determines plant safety is maintained or enhanced. This assessment shall, as a minimum, consider the potential outcomes and transients associated with a failed Surveillance, a successful Surveillance, and a perturbation of the offsite or onsite system when they are tied together or operated independently for the Surveillance; as well as the operator procedures available to cope with these outcomes. These shall be measured against the avoided risk of a plant shutdown and startup to determine that plant safety is maintained or enhanced when the Surveillance is performed in MODE 1 or 2. Risk insights or deterministic methods may be used for this assessment. Credit may be taken for unplanned events that satisfy this SR.

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(continued)

SR 3.8.1.14

Consistent with Regulatory Guide 1.9 (Ref. 3), paragraph C.2.2.9, this Surveillance requires demonstration that the DGs can start and run continuously near full load capability for an interval of not less than 24 hours, 22 hours of which is at a load equivalent to 92% and 100% of the continuous rating of the DG, and 2 hours of which is at a load between the 2000 hour rating and the 7 day rating of the DG. The DG starts for this Surveillance can be performed either from normal standby or hot conditions. The provisions for prelube and warmup, discussed in SR 3.8.1.2, and for gradual loading, discussed in SR 3.8.1.3, are applicable to this SR.

In order to ensure that the DG is tested under load conditions that are as close to design conditions as possible, testing must be performed at a power factor as close to the accident load power factor as practicable. When synchronized with offsite power, the power factor limit is ≤ 0.85 . This power factor is chosen to bound the actual worst case inductive loading that the DG could experience under design basis accident conditions.

The 24 month Frequency takes into consideration plant conditions required to perform the Surveillance, and is intended to be consistent with expected fuel cycle lengths.

This Surveillance is modified by four Notes. Note 1 states that momentary transients due to changing bus loads do not invalidate this test. The load band is provided to avoid routine overloading of the DG. Routine overloading may result in more frequent teardown inspections in accordance with vendor recommendations in order to maintain DG OPERABILITY. Similarly, momentary power factor transients above the limit do not invalidate the test. The reason for Note 2 is that during operation with the reactor critical, performance of this SR could cause perturbations to the electrical distribution systems that could challenge continued steady state operation and, as a result, plant safety systems. However, it is acceptable to perform this SR in MODES 1 and 2 provided the other two DGs are OPERABLE, since a perturbation can only affect one divisional DG. If during performance of this SR one of the other DGs becomes inoperable, this Surveillance is to be suspended. In addition, this restriction from normally performing the

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BASES

SURVEILLANCE
REQUIREMENTS

SR 3.8.1.14 (continued)

Surveillance in MODE 1 or 2 with any of the remaining two DGs inoperable is further amplified to allow the Surveillance to be performed for the purpose of reestablishing OPERABILITY (e.g., post work testing following corrective maintenance, corrective modification, deficient or incomplete surveillance testing, and other unanticipated OPERABILITY concerns) provided an assessment determines plant safety is maintained or enhanced. This assessment shall, as a minimum, consider the potential outcomes and transients associated with a failed Surveillance, a successful Surveillance, and a perturbation of the offsite or onsite system when they are tied together or operated independently for the Surveillance; as well as the operator procedures available to cope with these outcomes. These shall be measured against the avoided risk of a plant shutdown and startup to determine that plant safety is maintained or enhanced when the Surveillance is performed in MODE 1 or 2 with any of the remaining two DGs inoperable. Risk insights or deterministic methods may be used for this assessment. Credit may be taken for unplanned events that satisfy this SR. Note 3 is provided in recognition that under certain conditions, it is necessary to allow the surveillance to be conducted at a power factor other than the specified limit. During the Surveillance, the DG is normally operated paralleled to the grid, which is not the configuration when the DG is performing its safety function following a loss of offsite power (with or without a LOCA). Given the parallel configuration to the grid during the Surveillance, the grid voltage may be such that the DG field excitation level needed to obtain the specified power factor could result in a transient voltage within the DG windings higher than the recommended values if the DG output breaker were to trip during the Surveillance. Therefore, the power factor shall be maintained as close as practicable to the specified limit while still ensuring that if the DG output breaker were to trip during the Surveillance that the maximum DG winding voltage would not be exceeded. To minimize testing of the common DG, Note 4 allows a single test of the common DG (instead of two tests, one for each unit) to satisfy the requirements for both

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SURVEILLANCE
REQUIREMENTS

SR 3.8.1.14 (continued)

units. This is allowed since the main purpose of the Surveillance can be met by performing the test on either unit. If the DG fails one of these Surveillances, the DG should be considered inoperable on both units, unless the cause of the failure can be directly related to only one unit.

SR 3.8.1.15

This Surveillance demonstrates that the diesel engine can restart from a hot condition, such as subsequent to shutdown from normal Surveillances, and achieve the required voltage and frequency within 13 seconds. The 13 second time is derived from the requirements of the accident analysis for responding to a design basis large break LOCA (Ref. 5). In addition, the DG is required to maintain proper voltage and frequency limits after steady state is achieved. The voltage and frequency limits are normally achieved within 13 seconds. The time for the DG to reach the steady state voltage and frequency limits is periodically monitored and the trend evaluated to identify degradation of governor and voltage regulator performance.

The 24 month Frequency takes into consideration the plant conditions required to perform the Surveillance, and is intended to be consistent with expected fuel cycle lengths.

This SR has been modified by three Notes. Note 1 ensures that the test is performed with the diesel sufficiently hot. The requirement that the diesel has operated for at least 2 hours at 92% to 100% of full load conditions prior to performance of this Surveillance is based on manufacturer recommendations for achieving hot conditions. The load band is provided to avoid routine overloading of the DG. Routine overloads may result in more frequent teardown inspections in accordance with vendor recommendations in order to maintain DG OPERABILITY. Momentary transients due to changing bus loads do not invalidate this test. Note 2 allows all DG starts to be preceded by an engine prelube period to minimize wear and tear on the diesel during testing. The prelube period shall be consistent with

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SURVEILLANCE
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SR 3.8.1.15 (continued)

manufacturer recommendations. To minimize testing of the common DG, Note 3 allows a single test of the common DG (instead of two tests, one for each unit) to satisfy the requirements for both units. This is allowed since the main purpose of the Surveillance can be met by performing the test on either unit. If the DG fails one of these Surveillances, the DG should be considered inoperable on both units, unless the cause of the failure can be directly related to only one unit.

SR 3.8.1.16

Consistent with Regulatory Guide 1.9 (Ref. 3), paragraph C.2.2.11, this Surveillance ensures that the manual synchronization and automatic load transfer from the DG to the offsite source can be made and that the DG can be returned to ready-to-load status when offsite power is restored. It also ensures that the auto-start logic is reset to allow the DG to reload if a subsequent loss of offsite power occurs. The DG is considered to be in ready-to-load status when the DG is at rated speed and voltage, the output breaker is open and can receive an auto-close signal on bus undervoltage, and the individual load time delay relays are reset.

The Frequency of 24 months takes into consideration plant conditions required to perform the Surveillance, and is intended to be consistent with expected fuel cycle lengths.

This SR is modified by a Note. The reason for the Note is that performing the Surveillance would remove a required offsite circuit from service, perturb the electrical distribution system, and challenge plant safety systems. This restriction from normally performing the Surveillance in MODE 1 or 2 is further amplified to allow the Surveillance to be performed for the purpose of reestablishing OPERABILITY (e.g., post work testing following corrective maintenance, corrective modification, deficient or incomplete surveillance testing, and other unanticipated OPERABILITY concerns) provided an assessment determines plant safety is maintained or enhanced. This

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SR 3.8.1.16 (continued)

assessment shall, as a minimum, consider the potential outcomes and transients associated with a failed Surveillance, a successful Surveillance, and a perturbation of the offsite or onsite system when they are tied together or operated independently for the Surveillance; as well as the operator procedures available to cope with these outcomes. These shall be measured against the avoided risk of a plant shutdown and startup to determine that plant safety is maintained or enhanced when the Surveillance is performed in MODE 1 or 2. Risk insights or deterministic methods may be used for this assessment. Credit may be taken for unplanned events that satisfy this SR.

SR 3.8.1.17

Consistent with Regulatory Guide 1.9 (Ref. 3), paragraph C.2.2.13, demonstration of the parallel test mode override ensures that the DG availability under accident conditions is not compromised as the result of testing. Interlocks to the LOCA sensing circuits cause the Divisions 1 and 2 DGs to automatically reset to ready-to-load operation if an ECCS initiation signal is received during operation in the test mode. Ready-to-load operation is defined as the DG running at rated speed and voltage with the DG output breaker open. These provisions for automatic switchover are required by IEEE-308 (Ref. 12), paragraph 6.2.6(2).

The Division 3 DG overcurrent trip of the SAT feeder breaker to the respective Division 3 emergency bus demonstrates the ability of the Division 3 DG to remain connected to the emergency bus and supplying the necessary loads.

The 24 month Frequency takes into consideration plant conditions required to perform the Surveillance, and is intended to be consistent with expected fuel cycle lengths.

This SR has been modified by a Note. The reason for the Note is that performing the Surveillance would remove a required offsite circuit from service, perturb the electrical distribution system, and challenge safety systems. This restriction from normally performing the

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SR 3.8.1.17 (continued)

Surveillance in MODE 1 or 2 is further amplified to allow portions of the Surveillance to be performed for the purpose of reestablishing OPERABILITY (e.g., post work testing following corrective maintenance, corrective modification, deficient or incomplete surveillance testing, and other unanticipated OPERABILITY concerns) provided an assessment determines plant safety is maintained or enhanced. This assessment shall, as a minimum, consider the potential outcomes and transients associated with a failed partial Surveillance, a successful partial Surveillance, and a perturbation of the offsite or onsite system when they are tied together or operated independently for the partial Surveillance; as well as the operator procedures available to cope with these outcomes. These shall be measured against the avoided risk of a plant shutdown and startup to determine that plant safety is maintained or enhanced when portions of the Surveillance are performed in MODE 1 or 2. Risk insights or deterministic methods may be used for this assessment. Credit may be taken for unplanned events that satisfy this SR.

SR 3.8.1.18

Under accident conditions with loss of offsite power loads are sequentially connected to the bus by the individual time delay relays. The sequencing logic controls the permissive and starting signals to motor breakers to prevent overloading of the DGs due to high motor starting currents. The -10% load sequence time interval limit ensures that a sufficient time interval exists for the DG to restore frequency and voltage prior to applying the next load. There is no upper limit for the load sequence time interval since, for a single load interval (i.e., the time between two load blocks), the capability of the DG to restore frequency and voltage prior to applying the second load is not negatively affected by a longer than designed load interval, and if there are additional load blocks (i.e., the design includes multiple load intervals), then the lower limit requirements (-10%) will ensure that sufficient time exists for the DG to restore frequency and voltage prior to applying the remaining load blocks (i.e., all load intervals must be $\geq 90\%$ of the design interval). Reference 2 provides

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SR 3.8.1.18 (continued)

a summary of the automatic loading of emergency buses. Since only the Division 1 and 2 DGs have more than one load block, this SR is only applicable to these DGs.

The Frequency of 24 months takes into consideration plant conditions required to perform the Surveillance, and is intended to be consistent with expected fuel cycle lengths.

This SR is modified by a Note. The reason for the Note is that performing the Surveillance during these MODES would remove a required offsite circuit from service, perturb the electrical distribution system, and challenge plant safety systems. This restriction from normally performing the Surveillance in MODE 1 or 2 is further amplified to allow portions of the Surveillance to be performed for the purpose of reestablishing OPERABILITY (e.g., post work testing following corrective maintenance, corrective modification, deficient or incomplete surveillance testing, and other unanticipated OPERABILITY concerns) provided an assessment determines plant safety is maintained or enhanced. This assessment shall, as a minimum, consider the potential outcomes and transients associated with a failed partial Surveillance, a successful partial Surveillance, and a perturbation of the offsite or onsite system when they are tied together or operated independently for the partial Surveillance; as well as the operator procedures available to cope with these outcomes. These shall be measured against the avoided risk of a plant shutdown and startup to determine that plant safety is maintained or enhanced when portions of the Surveillance are performed in MODE 1 or 2. Risk insights or deterministic methods may be used for this assessment. Credit may be taken for unplanned events that satisfy this SR.

SR 3.8.1.19

In the event of a DBA coincident with a loss of offsite power, the DGs are required to supply the necessary power to ESF systems so that the fuel, RCS, and containment design limits are not exceeded.

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REQUIREMENTS

SR 3.8.1.19 (continued)

This Surveillance demonstrates the DG operation, as discussed in the Bases for SR 3.8.1.11, during a loss of offsite power actuation test signal in conjunction with an ECCS initiation signal. In lieu of actual demonstration of connection and loading of loads, testing that adequately shows the capability of the DG system to perform these functions is acceptable. This testing may include any series of sequential, overlapping, or total steps so that the entire connection and loading sequence is verified.

The Frequency of 24 months takes into consideration plant conditions required to perform the Surveillance and is intended to be consistent with an expected fuel cycle length.

This SR is modified by two Notes. The reason for Note 1 is to minimize wear and tear on the DGs during testing. The prelube period shall be consistent with manufacturer recommendations. For the purpose of this testing, the DGs must be started from normal standby conditions, that is, with the engine jacket water and lube oil being continuously circulated and temperature is being maintained consistent with manufacturer recommendations. The reason for Note 2 is that performing the Surveillance would remove a required offsite circuit from service, perturb the electrical distribution system, and challenge plant safety systems. This restriction from normally performing the Surveillance in MODE 1 or 2 is further amplified to allow portions of the Surveillance to be performed for the purpose of reestablishing OPERABILITY (e.g., post work testing following corrective maintenance, corrective modification, deficient or incomplete surveillance testing, and other unanticipated OPERABILITY concerns) provided an assessment determines plant safety is maintained or enhanced. This assessment shall, as a minimum, consider the potential outcomes and transients associated with a failed partial Surveillance, a successful partial Surveillance, and a perturbation of the offsite or onsite system when they are tied together or operated independently for the partial Surveillance; as well as the operator procedures available to cope with these outcomes. These shall be measured against the avoided risk of a plant shutdown and startup to

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SR 3.8.1.19 (continued)

determine that plant safety is maintained or enhanced when portions of the Surveillance are performed in MODE 1 or 2. Risk insights or deterministic methods may be used for this assessment. Credit may be taken for unplanned events that satisfy this SR.

SR 3.8.1.20

This Surveillance demonstrates that the unit DG starting independence has not been compromised. Also, this Surveillance demonstrates that each engine can achieve proper frequency and voltage within the specified time when the unit DGs are started simultaneously.

The 10 year Frequency is consistent with the recommendations of Regulatory Guide 1.9, paragraph C.2.2.14 (Ref. 3).

This SR is modified by a Note. The reason for the Note is to minimize wear on the DG during testing. The prelube period shall be consistent with manufacturer recommendations. For the purpose of this testing, the DGs must be started from normal standby conditions, that is, with the engine jacket water and lube oil continuously circulated and temperature is being maintained consistent with manufacturer recommendations.

SR 3.8.1.21

With the exception of this Surveillance, all other Surveillances of this Specification (SR 3.8.1.1 through SR 3.8.1.20) are applied to the given unit AC sources. This Surveillance is provided to direct that appropriate Surveillances for the required opposite unit AC source is governed by the applicable opposite unit Technical Specifications. Performance of the applicable opposite unit Surveillances will satisfy the opposite unit requirements as well as satisfy the given unit Surveillance Requirement. Exceptions are noted to the opposite unit SRs of LCO 3.8.1. SR 3.8.1.20 is excepted since only one opposite unit DG is

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SURVEILLANCE
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SR 3.8.1.21 (continued)

required by the given unit Specification. SR 3.8.1.12, SR 3.8.1.13, SR 3.8.1.17, SR 3.8.1.18, and SR 3.8.1.19 are excepted since these SRs test the opposite unit's ECCS initiation signal, which is not required for the AC electrical power sources to be OPERABLE on a given unit.

The Frequency required by the applicable opposite unit SR also governs performance of that SR for the given unit.

As noted, if the opposite unit is in MODE 4 or 5, or moving irradiated fuel assemblies in secondary containment, SR 3.8.1.3, SR 3.8.1.9 through SR 3.8.1.11, and SR 3.8.1.14 through SR 3.8.1.16 are not required to be performed. This ensures that a given unit SR will not require an opposite unit SR to be performed, when the opposite unit Technical Specifications exempts performance of an opposite unit SR (however, as stated in the opposite unit SR 3.8.2.1 Note 1, while performance of an SR is exempted, the SR must still be met).

REFERENCES

1. 10 CFR 50, Appendix A, GDC 17.
 2. UFSAR, Chapter 8.
 3. Regulatory Guide 1.9.
 4. UFSAR, Chapter 6.
 5. UFSAR, Chapter 15.
 6. Regulatory Guide 1.93.
 7. Generic Letter 84-15, July 2, 1984.
 8. 10 CFR 50, Appendix A, GDC 18.
 9. Regulatory Guide 1.137.
 10. ANSI C84.1, 1982.
 11. ASME, Boiler and Pressure Vessel Code, Section XI.
 12. IEEE Standard 308.
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B 3.8 ELECTRICAL POWER SYSTEMS

B 3.8.2 AC Sources – Shutdown

BASES

BACKGROUND A description of the AC sources is provided in the Bases for LCO 3.8.1, "AC Sources – Operating."

APPLICABLE SAFETY ANALYSES The OPERABILITY of the minimum AC sources during MODES 4 and 5, and during movement of irradiated fuel assemblies in the secondary containment ensures that:

- a. The unit can be maintained in the shutdown or refueling condition for extended periods;
- b. Sufficient instrumentation and control capability is available for monitoring and maintaining the unit status; and
- c. Adequate AC electrical power is provided to mitigate events postulated during shutdown, such as an inadvertent draindown of the vessel or a fuel handling accident.

In general, when the unit is shutdown the Technical Specifications (TS) requirements ensure that the unit has the capability to mitigate the consequences of postulated accidents. However, assuming a single failure and concurrent loss of all offsite or loss of all onsite power is not required. The rationale for this is based on the fact that many Design Basis Accidents (DBAs) that are analyzed in MODES 1, 2, and 3 have no specific analyses in MODES 4 and 5. Worst case bounding events are deemed not credible in MODES 4 and 5 because the energy contained within the reactor pressure boundary, reactor coolant temperature and pressure, and the corresponding stresses result in the probabilities of occurrence significantly reduced or eliminated, and minimal consequences. These deviations from DBA analysis assumptions and design requirements during shutdown conditions are allowed by the LCO for required systems.

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APPLICABLE
SAFETY ANALYSES
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During MODES 1, 2, and 3, various deviations from the analysis assumptions and design requirements are allowed within the ACTIONS. This allowance is in recognition that certain testing and maintenance activities must be conducted provided an acceptable level of risk is not exceeded. During MODES 4 and 5, performance of a significant number of required testing and maintenance activities is also required. In MODES 4 and 5, the activities are generally planned and administratively controlled. Relaxations from typical MODE 1, 2, and 3 LCO requirements are acceptable during shutdown MODES based on:

- a. The fact that time in an outage is limited. This is a risk prudent goal as well as utility economic consideration.
- b. Requiring appropriate compensatory measures for certain conditions. These may include administrative controls, reliance on systems that do not necessarily meet typical design requirements applied to systems credited in operating MODE analyses, or both.
- c. Prudent utility consideration of the risk associated with multiple activities that could affect multiple systems.
- d. Maintaining, to the extent practical, the ability to perform required functions (even if not meeting MODE 1, 2, and 3 OPERABILITY requirements) with systems assumed to function during an event.

In the event of an accident during shutdown, this LCO ensures the capability of supporting systems necessary to avoid immediate difficulty, assuming either a loss of all offsite power or a loss of all onsite (diesel generator (DG)) power.

The AC sources satisfy Criterion 3 of 10 CFR 50.36(c)(2)(ii).

LCO

One offsite circuit capable of supplying onsite unit Class 1E power distribution subsystem(s) of LCO 3.8.8, "Distribution Systems – Shutdown," ensures that all required Division 1 loads, Division 2 loads, and Division 3 loads are

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LCO
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powered from offsite power. An OPERABLE unit DG, associated with a Division 1 or Division 2 Distribution System emergency bus required OPERABLE by LCO 3.8.8, ensures a diverse power source is available to provide electrical power support, assuming a loss of the offsite circuit. Similarly, when the High Pressure Core Spray (HPCS) System is required to be OPERABLE, an OPERABLE Division 3 DG ensures a diverse source of power for the HPCS System is available to provide electrical power support, assuming a loss of the offsite power circuit. Additionally, when the Standby Gas Treatment (SGT) System, Control Room Area Filtration (CRAF) System, or Control Room Area Ventilation Air Conditioning System is required to be OPERABLE, one qualified offsite circuit (normal or alternate) between the offsite transmission network and the opposite unit Division 2 onsite Class 1E AC electrical power distribution subsystem or an opposite unit DG capable of supporting the opposite unit Division 2 onsite Class 1E AC electrical power distribution subsystem is required to be OPERABLE. Together, OPERABILITY of the required offsite circuit(s) and DG(s) ensure the availability of sufficient AC sources to operate the plant in a safe manner and to mitigate the consequences of postulated events during shutdown (e.g., fuel handling accidents, reactor vessel draindown).

The qualified offsite circuit(s) must be capable of maintaining rated frequency and voltage while connected to their respective emergency bus(es), and of accepting required loads during an accident. Qualified offsite circuits are those that are described in the UFSAR and are part of the licensing basis for the plant. An OPERABLE qualified normal offsite circuit consists of the required incoming breaker(s) and disconnects from the 345 kV switchyard to and including the SAT or UAT (backfeed mode), the respective circuit path to and including the feeder breakers to the required Division 1, 2, and 3 emergency buses.

An OPERABLE qualified alternate offsite circuit consists of the required incoming breaker(s) and disconnects from the 345 kV switchyard to and including the SAT or UAT (backfeed mode), to and including the opposite unit 4.16 kV emergency bus, the opposite unit circuit path to and including the unit tie breakers (breakers 1414, 1424, 2414, and 2424), and the respective circuit path to the required Division 1 and 2 emergency buses.

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LCO
(continued)

The required DG must be capable of starting, accelerating to rated speed and voltage, and connecting to its respective emergency bus on detection of bus undervoltage, and accepting required loads. This sequence must be accomplished within 13 seconds. Each DG must also be capable of accepting required loads within the assumed loading sequence intervals, and must continue to operate until offsite power can be restored to the emergency buses. These capabilities are required to be met from a variety of initial conditions such as: DG in standby with the engine hot and DG in standby with the engine at ambient conditions. Additional DG capabilities must be demonstrated to meet required Surveillances, e.g., capability of the Division 1 and 2 DGs to revert to standby status on an ECCS signal while operating in parallel test mode.

Proper sequencing of loads, including tripping of nonessential loads, is a required function for DG OPERABILITY. The necessary portions of the DG Cooling Water System and Ultimate Heat Sink capable of providing cooling to the required DG(s) are also required.

It is acceptable for divisions to be cross tied during shutdown conditions, permitting a single offsite power circuit to supply all required divisions.

APPLICABILITY

The AC sources required to be OPERABLE in MODES 4 and 5 and during movement of irradiated fuel assemblies in the secondary containment provide assurance that:

- a. Systems to provide adequate coolant inventory makeup are available for the irradiated fuel in the core in case of an inadvertent draindown of the reactor vessel;
- b. Systems needed to mitigate a fuel handling accident are available;
- c. Systems necessary to mitigate the effects of events that can lead to core damage during shutdown are available; and
- d. Instrumentation and control capability is available for monitoring and maintaining the unit in a cold shutdown condition or refueling condition.

(continued)

BASES

APPLICABILITY The AC power requirements for MODES 1, 2, and 3 are covered
(continued) in LCO 3.8.1.

ACTIONS LCO 3.0.3 is not applicable while in MODE 4 or 5. However, since irradiated fuel assembly movement can occur in MODE 1, 2, or 3, the ACTIONS have been modified by a Note stating that LCO 3.0.3 is not applicable. If moving irradiated fuel assemblies while in MODE 4 or 5, LCO 3.0.3 would not specify any action. If moving irradiated fuel assemblies while in MODE 1, 2, or 3, the fuel movement is independent of reactor operations. Entering LCO 3.0.3 while in MODE 1, 2, or 3 would require the unit to be shutdown, but would not require immediate suspension of movement of irradiated fuel assemblies. The Note to the ACTIONS, "LCO 3.0.3 is not applicable," ensures that the actions for immediate suspension of irradiated fuel assembly movement are not postponed due to entry into LCO 3.0.3.

A.1

An offsite circuit is considered inoperable if it is not available to one required 4.16 kV emergency bus. If two or more 4.16 kV emergency buses are required per LCO 3.8.8, division(s) with offsite power available may be capable of supporting sufficient required features to allow continuation of CORE ALTERATIONS, fuel movement, and operations with a potential for draining the reactor vessel. By the allowance of the option to declare required features inoperable that are not capable of being powered from offsite power, appropriate restrictions can be implemented in accordance with the required feature(s) LCOs' ACTIONS. Required features remaining capable of being powered from a qualified offsite circuit, even if that circuit is considered inoperable because it is not capable of powering other required features, are not declared inoperable by this Required Action. For example, if both Division 1 and 2 emergency buses are required OPERABLE by LCO 3.8.8 and only the Division 1 emergency buses are not capable of being powered from offsite power, then only the required features powered from Division 1 emergency buses are required to be declared inoperable.

(continued)

BASES

ACTIONS
(continued)

A.2.1, A.2.2, A.2.3, A.2.4, B.1, B.2, B.3, and B.4

With the offsite circuit not available to all required divisions, the option still exists to declare all required features inoperable per Required Action A.1. Since this option may involve undesired administrative efforts, the allowance for sufficiently conservative actions is made. With the required DG inoperable, the minimum required diversity of AC power sources is not available. It is, therefore, required to suspend CORE ALTERATIONS, movement of irradiated fuel assemblies in the secondary containment, and activities that could potentially result in inadvertent draining of the reactor vessel.

Suspension of these activities shall not preclude completion of actions to establish a safe conservative condition. These actions minimize probability of the occurrence of postulated events. It is further required to initiate action immediately to restore the required AC sources and to continue this action until restoration is accomplished in order to provide the necessary AC power to the plant safety systems.

The Completion Time of immediately is consistent with the required times for actions requiring prompt attention. The restoration of the required AC electrical power sources should be completed as quickly as possible in order to minimize the time during which the plant safety systems may be without sufficient power.

Pursuant to LCO 3.0.6, the Distribution System ACTIONS are not entered even if all AC sources to it are inoperable, resulting in de-energization. Therefore, the Required Actions of Condition A have been modified by a Note to indicate that when Condition A is entered with no AC power to any required emergency bus, ACTIONS for LCO 3.8.8 must be immediately entered. This Note allows Condition A to provide requirements for the loss of the offsite circuit whether or not a division is de-energized. LCO 3.8.8 provides the appropriate restrictions for the situation involving a de-energized division.

(continued)

BASES

ACTIONS
(continued)

C.1

When the HPCS System is required to be OPERABLE, and the Division 3 DG is inoperable, the required diversity of AC power sources to the HPCS System is not available. Since these sources only affect the HPCS System, the HPCS System is declared inoperable and the Required Actions of LCO 3.5.2, "Emergency Core Cooling Systems–Shutdown," entered.

In the event all sources of power to Division 3 are lost, Condition A will also be entered and direct that the ACTIONS of LCO 3.8.8 be taken. If only the Division 3 DG is inoperable, and power is still supplied to HPCS System, 72 hours is allowed to restore the DG to OPERABLE. This is reasonable considering the HPCS System will still perform its function, absent a loss of offsite power.

D.1

When the SGT System, CRAF System, or Control Room Area Ventilation Air Conditioning System is required to be OPERABLE, and the required opposite unit Division 2 AC source is inoperable, the associated SGT subsystem, CRAF subsystem, and control room ventilation area air conditioning subsystem are declared inoperable and the Required Actions of the affected LCOs are entered.

The immediate Completion Time is consistent with the required times for actions requiring prompt attention. The restoration of the required opposite unit Division 2 AC electrical power source should be completed as quickly as possible in order to minimize the time during which the aforementioned safety systems are without sufficient power.

SURVEILLANCE
REQUIREMENTS

SR 3.8.2.1

SR 3.8.2.1 requires the SRs from LCO 3.8.1 that are necessary for ensuring the OPERABILITY of the AC sources in other than MODES 1, 2, and 3 to be applicable. SR 3.8.1.8 is not required to be met since only one offsite circuit is required to be OPERABLE. SR 3.8.1.17 is not required to be

(continued)

BASES

SURVEILLANCE
REQUIREMENTS

SR 3.8.2.1 (continued)

met because the required OPERABLE DG(s) is not required to undergo periods of being synchronized to the offsite circuit. SR 3.8.1.20 is excepted because starting independence is not required with the DG(s) that is not required to be OPERABLE. Refer to the corresponding Bases for LCO 3.8.1 for a discussion of each SR.

This SR is modified by two Notes. The reason for Note 1 is to preclude requiring the OPERABLE DG(s) from being paralleled with the offsite power network or otherwise rendered inoperable during the performance of SRs, and to preclude de-energizing a required 4.16 kV emergency bus or disconnecting a required offsite circuit during performance of SRs. With limited AC sources available, a single event could compromise both the required circuit and the DG. It is the intent that these SRs must still be capable of being met, but actual performance is not required during periods when the DG and offsite circuit are required to be OPERABLE. Note 2 states that SRs 3.8.1.12 and 3.8.1.19 are not required to be met when its associated ECCS subsystem(s) are not required to be OPERABLE. These SRs demonstrate the DG response to an ECCS initiation signal (either alone or in conjunction with a loss of offsite power signal). This is consistent with the ECCS instrumentation requirements that do not require the ECCS initiation signals when the associated ECCS subsystem is not required to be OPERABLE per LCO 3.5.2, "ECCS – Shutdown."

REFERENCES

None.

B 3.8 ELECTRICAL POWER SYSTEMS

B 3.8.3 Diesel Fuel Oil and Starting Air

BASES

BACKGROUND

Each diesel generator (DG) is provided with a storage tank. The Division 1 and 2 DGs and the opposite unit Division 2 DG storage tank fuel oil capacity, and the Division 3 combined storage tank and day tank fuel oil capacity, is sufficient to operate that DG for a period of 7 days while the DG is supplying maximum post loss of coolant accident load demand (Ref. 1). The maximum load demand is calculated using the assumption that at least two DGs are available. This onsite fuel oil capacity is sufficient to operate the DGs for longer than the time to replenish the onsite supply from outside sources.

Fuel oil is transferred from each storage tank to its respective day tank by a transfer pump associated with each storage tank. Redundancy of pumps and piping precludes the failure of one pump, or the rupture of any pipe, valve, or tank to result in the loss of more than one DG. All system piping and components, except for fill piping and vents, are located within the diesel buildings. The fuel oil level in the storage tanks is indicated locally, and each storage tank is provided with low level switches that actuate alarm annunciators in the main control room.

For proper operation of the standby DGs, it is necessary to ensure the proper quality of the fuel oil. Regulatory Guide 1.137 (Ref. 2) addresses the recommended fuel oil practices as supplemented by ANSI N195 (Ref. 3). The fuel oil properties governed by these SRs are the water and sediment content, the flashpoint and kinematic viscosity, specific gravity (or API gravity), and impurity level.

Each Division 1 and Division 2 DG has two air start subsystems, each with adequate capacity for five successive starts on the DG without recharging the air start receivers. Each Division 3 DG has two air start subsystems, each with adequate capacity for three successive starts on the DG without recharging the air start receivers.

(continued)

BASES (continued)

APPLICABLE
SAFETY ANALYSES

The initial conditions of Design Basis Accident (DBA) and transient analyses in UFSAR, Chapter 6 (Ref. 4) and Chapter 15 (Ref. 5), assume Engineered Safety Feature (ESF) systems are OPERABLE. The DGs are designed to provide sufficient capacity, capability, redundancy, and reliability to ensure the availability of necessary power to ESF systems so that fuel, reactor coolant system, and containment design limits are not exceeded. These limits are discussed in more detail in the Bases for Section 3.2, Power Distribution Limits; Section 3.5, Emergency Core Cooling (ECCS) and Reactor Core Isolation Cooling (RCIC) System; and Section 3.6, Containment Systems.

Since diesel fuel oil and starting air subsystems support the operation of the standby AC power sources, they satisfy Criterion 3 of 10 CFR 50.36(c)(2)(ii).

LCO

Stored diesel fuel oil is required to have sufficient supply for 7 days of full load operation. It is also required to meet specific standards for quality. This requirement, in conjunction with an ability to obtain replacement supplies within 7 days, supports the availability of DGs required to shut down the reactor and to maintain it in a safe condition for an anticipated operational occurrence (A00) or a postulated DBA with loss of offsite power. DG day tank fuel requirements, as well as transfer capability from the storage tank to the day tank, are addressed in LCO 3.8.1, "AC Sources—Operating," and LCO 3.8.2, "AC Sources—Shutdown."

The starting air system is required to have a minimum capacity for five successive Division 1 and 2 DG starts and three successive Division 3 DG starts without recharging the air start receivers. While each air start receiver set has the required capacity, both air start receiver sets (and associated air start headers) per DG are required to ensure OPERABILITY of the DG.

APPLICABILITY

The AC sources (LCO 3.8.1 and LCO 3.8.2), are required to ensure the availability of the required power to shut down the reactor and maintain it in a safe shutdown condition after an A00 or a postulated DBA. Since stored diesel fuel

(continued)

BASES

APPLICABILITY (continued) oil and starting air subsystems support LCO 3.8.1 and LCO 3.8.2, stored diesel fuel oil and starting air are required to be within limits when the associated DG is required to be OPERABLE.

ACTIONS The ACTIONS Table is modified by a Note indicating that separate Condition entry is allowed for each DG. This is acceptable, since the Required Actions for each Condition provide appropriate compensatory actions for each inoperable DG subsystem. Complying with the Required Actions for one inoperable DG subsystem may allow for continued operation, and subsequent inoperable DG subsystem(s) are governed by separate Condition entry and application of associated Required Actions.

A.1

With stored fuel oil level not within the specified limit, the 7 day fuel oil supply for a DG is not available. However, the Condition is restricted to fuel oil level reductions that maintain at least a 6 day supply. These circumstances may be caused by events such as:

- a. Full load operation required after an inadvertent start while at minimum required level; or
- b. Feed and bleed operations that may be necessitated by increasing particulate levels or any number of other oil quality degradations.

This restriction allows sufficient time for obtaining the requisite replacement volume and performing the analyses required prior to addition of the fuel oil to the tank. A period of 48 hours is considered sufficient to complete restoration of the required level prior to declaring the DG inoperable. This period is acceptable based on the remaining capacity (> 6 days), the fact that actions will be initiated to obtain replenishment, and the low probability of an event during this brief period.

(continued)

BASES

ACTIONS
(continued)

B.1

This Condition is entered as a result of a failure to meet the acceptance criterion for particulates. Normally, trending of particulate levels allows sufficient time to correct high particulate levels prior to reaching the limit of acceptability. Poor sample procedures (bottom sampling), contaminated sampling equipment, and errors in laboratory analysis can produce failures that do not follow a trend. Since the presence of particulates does not mean failure of the fuel oil to burn properly in the diesel engine, since particulate concentration is unlikely to change significantly between Surveillance Frequency intervals, and since proper engine performance has been recently demonstrated (within 31 days), it is prudent to allow a brief period prior to declaring the associated DG inoperable. The 7 day Completion Time allows for further evaluation, resampling, and re-analysis of the DG fuel oil.

C.1

With the new fuel oil properties defined in the Bases for SR 3.8.3.2 not within the required limits, a period of 30 days is allowed for restoring the stored fuel oil properties. This period provides sufficient time to test the stored fuel oil to determine that the new fuel oil, when mixed with previously stored fuel oil, remains acceptable, or to restore the stored fuel oil properties. This restoration may involve feed and bleed procedures, filtering, or a combination of these procedures. Even if a DG start and load was required during this time interval and the fuel oil properties were outside limits, there is high likelihood that the DG would still be capable of performing its intended function.

D.1

With starting air receiver pressure < 200 psig, sufficient capacity for five successive starts for the Division 1 or 2 DG or three successive starts for the Division 3 DG, as applicable, does not exist. However, as long as the receiver pressure is > 165 psig, there is adequate capacity

(continued)

BASES

ACTIONS

D.1 (continued)

for at least one start, and the DG can be considered OPERABLE while the air receiver pressure is restored to the required limit. A period of 48 hours is considered sufficient to complete restoration to the required pressure prior to declaring the DG inoperable. This period is acceptable based on the remaining air start capacity, the fact that most DG starts are accomplished on the first attempt, and the low probability of an event during this brief period.

E.1

With a Required Action and associated Completion Time of Condition A, B, C, or D not met, or the stored diesel fuel oil or starting air subsystem not within limits of this Specification for reasons other than addressed by Conditions A through D, the associated DG may be incapable of performing its intended function and must be immediately declared inoperable.

SURVEILLANCE
REQUIREMENTS

SR 3.8.3.1

This SR provides verification that there is an adequate inventory of fuel oil in the associated fuel oil storage tank for the Division 1 and 2 DGs and the opposite unit Division 2 DG and in the associated fuel oil storage tank and day tank for the Division 3 DG to support each DG's operation for 7 days at full load. The 7 day period is sufficient time to place the unit in a safe shutdown condition and to bring in replenishment fuel from an offsite location.

The 31 day Frequency is adequate to ensure that a sufficient supply of fuel oil is available, since low level alarms are provided and unit operators would be aware of any large uses of fuel oil during this period.

(continued)

BASES

SURVEILLANCE
REQUIREMENTS
(continued)

SR 3.8.3.2

The tests of new fuel prior to addition to the storage tanks are a means of determining whether new fuel oil is of the appropriate grade and has not been contaminated with substances that would have an immediate detrimental impact on diesel engine combustion and operation. If results from these tests are within acceptable limits, the fuel oil may be added to the storage tanks without concern for contaminating the entire volume of fuel oil in the storage tanks. These tests are to be conducted prior to adding the new fuel to the storage tank(s). The tests, limits, and applicable ASTM Standards are as follows:

- a. Sample the new fuel oil in accordance with ASTM D4057-95 (Ref. 6);
- b. Verify in accordance with the tests specified in ASTM D975-98b (Ref. 6) that the sample has: 1) an absolute specific gravity at 60°F of ≥ 0.83 and ≤ 0.89 (or an API gravity at 60°F of ≥ 27 and ≤ 39) when tested in accordance with ASTM D1298-99 (Ref. 6); 2) a kinematic viscosity at 40°C of ≥ 1.9 centistokes and ≤ 4.1 centistokes when tested in accordance with ASTM D445-97 (Ref. 6); and 3) a flash point of $\geq 125^\circ\text{F}$ when tested in accordance with ASTM D93-99c (Ref. 6); and
- c. Verify that the new fuel oil has a clear and bright appearance with proper color when tested in accordance with ASTM D4176-93 (Ref. 6) or a water and sediment content within limits when tested in accordance with ASTM D2709-96e (Ref. 6). The clear and bright appearance with proper color test is only applicable to fuels that meet the ASTM color requirement (i.e., ASTM color 5 or less).

Failure to meet any of the above limits is cause for rejecting the new fuel oil, but does not represent a failure to meet the LCO since the fuel oil is not added to the storage tanks.

Following the initial new fuel oil sample, the fuel oil is analyzed within 31 days following addition of the new fuel oil to the fuel oil storage tank(s) to establish that the

(continued)

BASES

SURVEILLANCE
REQUIREMENTS

SR 3.8.3.2 (continued)

other properties specified in Table 1 of ASTM D975-98b (Ref. 6) are met for new fuel oil when tested in accordance with ASTM D975-98b (Ref. 6), except that the analysis for sulfur may be performed in accordance with ASTM D1552-95 (Ref. 6), ASTM D2622-98 (Ref. 6), or ASTM D4294-98 (Ref. 6). The 31 day period is acceptable because the fuel oil properties of interest, even if not within stated limits, would not have an immediate effect on DG operation. This Surveillance ensures the availability of high quality fuel oil for the DGs.

Fuel oil degradation during long term storage shows up as an increase in particulate, mostly due to oxidation. The presence of particulate does not mean that the fuel oil will not burn properly in a diesel engine. However, the particulate can cause fouling of filters and fuel oil injection equipment, which can cause engine failure.

Particulate concentrations should be determined in accordance with ASTM D5452-98 (Ref. 6). This method involves a gravimetric determination of total particulate concentration in the fuel oil and has a limit of 10 mg/l. It is acceptable to obtain a field sample for subsequent laboratory testing in lieu of field testing.

The Frequency of this Surveillance takes into consideration fuel oil degradation trends indicating that particulate concentration is unlikely to change between Frequency intervals.

SR 3.8.3.3

This Surveillance ensures that, without the aid of the refill compressor, sufficient air start capacity for each DG is available. The system design requirements provide for a minimum of five engine starts for each Division 1 and Division 2 DG, and three engine starts for each Division 3 DG without recharging. The pressure specified in this SR is intended to support the lowest value at which the required number of starts can be accomplished.

(continued)

BASES

SURVEILLANCE
REQUIREMENTS

SR 3.8.3.3 (continued)

The 31 day Frequency takes into account the capacity, capability, redundancy, and diversity of the AC sources and other indications available in the control room, including alarms, to alert the operator to below normal air start pressure.

SR 3.8.3.4

Microbiological fouling is a major cause of fuel oil degradation. There are numerous bacteria that can grow in fuel oil and cause fouling, but all must have a water environment in order to survive. Removal of water from the fuel oil storage tank once every 92 days eliminates the necessary environment for bacterial survival. This is the most effective means of controlling microbiological fouling. In addition, it eliminates the potential for water entrainment in the fuel oil during DG operation. Water may come from any of several sources, including condensation, ground water, rain water, contaminated fuel oil, and breakdown of the fuel oil by bacteria. Frequent checking for and removal of accumulated water minimizes fouling and provides data regarding the watertight integrity of the fuel oil system. The Surveillance Frequencies are established by Regulatory Guide 1.137 (Ref. 2). This SR is for preventive maintenance. The presence of water does not necessarily represent a failure of this SR provided that accumulated water is removed during performance of this Surveillance.

REFERENCES

1. UFSAR, Section 9.5.4.
 2. Regulatory Guide 1.137.
 3. ANSI N195, Appendix B, 1976.
 4. UFSAR, Chapter 6.
 5. UFSAR, Chapter 15.
 6. ASTM Standards: D4057-95; D975-98b; D1298-99; D445-97; D93-99c; D4176-93; D2709-96e; D1552-95; D2622-98; D4294-98; D5452-98.
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B 3.8 ELECTRICAL POWER SYSTEMS

B 3.8.4 DC Sources – Operating

BASES

BACKGROUND

The station DC electrical power system provides the AC emergency power system with control power. It also provides both motive and control power to selected safety related equipment. As required by 10 CFR 50, Appendix A, GDC 17 (Ref. 1), the DC electrical power system is designed to have sufficient independence, redundancy, and testability to perform its safety functions, assuming a single failure. The DC electrical power system also conforms to the requirements of Regulatory Guide 1.6 (Ref. 2) and IEEE-308 (Ref. 3).

The 125 VDC electrical power system consists of three independent Class 1E DC electrical power subsystems, Divisions 1, 2, and 3. The 250 VDC electric power system consists of one Class 1E DC electrical power subsystem, Division 1. Each subsystem consists of a battery, associated battery charger, and all the associated control equipment and interconnecting cabling.

During normal operation, the DC loads are powered from the battery chargers with the batteries floating on the system. In case of loss of normal power to the battery charger, the DC loads are automatically powered from the batteries.

The Division 1 safety related DC power source consists of one 125 V and one 250 V battery bank and associated full capacity battery chargers (one per battery bank). The Division 1 125 VDC power source provides the control power for its associated Class 1E AC power load group, 4.16 kV switchgear, and 480 V load centers and control power for non-Class 1E loads. Also, the 125 VDC power sources provide DC power to the emergency lighting system, diesel generator (DG) auxiliaries, and the DC control power for the Engineered Safety Feature (ESF) and non-ESF systems. The 250 VDC power source supplies power to the Reactor Core Isolation Cooling (RCIC) System, and RCIC primary containment isolation valves (PCIVs). It also supplies power to the main turbine emergency bearing oil pumps, main generator emergency seal oil pumps, and the process computer, however, these are not Technical Specification related loads.

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BASES

BACKGROUND
(continued)

The Division 2 safety related DC power source consists of a 125 V battery bank and associated full capacity charger. This 125 V battery provides the control power for its associated Class 1E AC power load group, 4.16 kV switchgear, and 480 V load centers and control power for non-Class 1E loads. Also, this 125 V battery provides DC power to the emergency lighting system, diesel generator (DG) auxiliaries, and the DC control power for ESF and non-ESF systems.

The Division 3 safety related DC power source consists of a 125 V battery bank and associated full capacity charger, and provides power for the High Pressure Core Spray (HPCS) DG field flashing control logic and switching function of 4.16 kV Division 3 breakers. It also provides power for the HPCS System logic, HPCS DG control and protection, and Division 3 related controls.

The opposite unit Division 2 safety related DC power source consists of a 125 V battery bank and associated full capacity charger. This 125 V battery provides the control power for its associated Class 1E AC power load group, 4.16 kV switchgear, and 480 V load centers and control power for non-Class 1E loads. Also, this 125 V battery provides DC power to the opposite unit's emergency lighting system, diesel generator (DG) auxiliaries, and DC control power for the ESF and non-ESF systems.

The DC power distribution system is described in more detail in the Bases for LCO 3.8.7, "Distribution Systems – Operating," and LCO 3.8.8, "Distribution Systems – Shutdown."

Each Division 1, 2, and 3 battery has adequate storage capacity to carry the required load continuously for at least 4 hours as discussed in the UFSAR, Section 8.3.2 (Ref. 4).

Each DC battery subsystem is separately housed in a ventilated room apart from its charger and distribution centers. Each subsystem is located in an area separated physically and electrically from the other subsystems to ensure that a single failure in one subsystem does not cause a failure in a redundant subsystem. There is no sharing

(continued)

BASES

BACKGROUND
(continued)

between redundant Class 1E subsystems such as batteries, battery chargers, or distribution panels.

The batteries for a DC electrical power subsystem are sized to produce required capacity at 80% of nameplate rating, corresponding to warranted capacity at end of life cycles and the 100% design demand. The voltage design limit is 1.81 V per cell (Ref. 4).

Each Division 1, 2, and 3 DC electrical power subsystem battery charger has ample power output capacity for the steady state operation of connected loads required during normal operation, while at the same time maintaining its battery bank fully charged. Each battery charger has sufficient capacity to restore the battery bank from the design minimum charge to its fully charged state within 24 hours while supplying normal steady state loads (Ref. 4).

APPLICABLE
SAFETY ANALYSES

The initial conditions of Design Basis Accident (DBA) and transient analyses in the UFSAR, Chapter 6 (Ref. 5), and Chapter 15 (Ref. 6), assume that ESF systems are OPERABLE. The DC electrical power system provides normal and emergency DC electrical power for the DGs, emergency auxiliaries, and control and switching during all MODES of operation.

The OPERABILITY of the DC subsystems is consistent with the initial assumptions of the accident analyses and is based upon meeting the design basis of the unit. This includes maintaining DC sources OPERABLE during accident conditions in the event of:

- a. An assumed loss of all offsite AC power or of all onsite AC power; and
- b. A worst case single failure.

The DC sources satisfy Criterion 3 of 10 CFR 50.36(c)(2)(ii).

LCO

The Division 1 125 VDC and 250 VDC, Division 2 125 VDC, and Division 3 125 VDC, and opposite unit Division 2 125 VDC electrical power subsystems, each subsystem consisting of one battery, one battery charger, and the corresponding

(continued)

BASES

LCO
(continued) control equipment and interconnecting cabling supplying power to the associated bus within the divisions, are required to be OPERABLE to ensure the availability of the required power to shut down the reactor and maintain it in a safe condition after an anticipated operational occurrence (AOO) or a postulated DBA. Loss of any DC electrical power subsystem does not prevent the minimum safety function from being performed (Ref. 4).

APPLICABILITY The DC electrical power sources are required to be OPERABLE in MODES 1, 2, and 3 to ensure safe unit operation and to ensure that:

- a. Acceptable fuel design limits and reactor coolant pressure boundary limits are not exceeded as a result of AOOs or abnormal transients; and
- b. Adequate core cooling is provided, and containment integrity and other vital functions are maintained in the event of a postulated DBA.

The DC electrical power requirements for MODES 4 and 5 and other conditions in which the DC electrical power sources are required are addressed in LCO 3.8.5, "DC Sources – Shutdown."

ACTIONS

A.1

Condition A represents one division with a loss of ability to completely respond to an event, and a potential loss of ability to remain energized during normal operation. It is, therefore, imperative that the operator's attention focus on stabilizing the unit, minimizing the potential for complete loss of DC power to the affected division. The 2 hour limit is consistent with the allowed time for an inoperable DC distribution system division.

If one of the Division 1 or 2 125 VDC electrical power subsystems is inoperable (e.g., inoperable battery, inoperable battery charger, or inoperable battery charger and associated inoperable battery), the remaining DC electrical power subsystems have the capacity to support a safe shutdown and to mitigate an accident condition. Since

(continued)

BASES

ACTIONS

A.1 (continued)

a subsequent worst case single failure could, however, result in the loss of minimum necessary DC electrical subsystems, continued power operation should not exceed 2 hours. The 2 hour Completion Time is based on Regulatory Guide 1.93 (Ref. 7) and reflects a reasonable time to assess unit status as a function of the inoperable DC electrical power subsystem and, if the DC electrical power subsystem is not restored to OPERABLE status, to prepare to effect an orderly and safe unit shutdown.

B.1

With the Division 3 DC electrical power subsystem inoperable, the HPCS System may be incapable of performing its intended function and must be immediately declared inoperable. This declaration also requires entry into applicable Conditions and Required Actions of LCO 3.5.1, "ECCS – Operating."

C.1

With the Division 1 250 VDC electrical power subsystem inoperable, the RCIC System and the RCIC DC powered PCIIVs may be incapable of performing their intended functions and must be immediately declared inoperable. This declaration also requires entry into applicable Conditions and Required Actions of LCO 3.5.3, "RCIC System," and LCO 3.6.1.3, "PCIIVs."

D.1

If the opposite unit Division 2 125 VDC electrical power subsystem is inoperable (e.g., inoperable battery, inoperable charger, or inoperable battery charger and associated battery), certain redundant Division 2 features (e.g., a standby gas treatment subsystem) will not function if a design basis event were to occur. Therefore, a 7 day Completion Time is provided to restore the opposite unit Division 2 125 VDC electrical power subsystem to

(continued)

BASES

ACTIONS

D.1 (continued)

OPERABLE status. The 7 day Completion Time takes into account the capacity and capability of the remaining DC electrical power subsystems, and is based on the shortest restoration time allowed for the systems affected by the inoperable DC electrical power subsystem in the respective system specifications.

E.1 and E.2

If the DC electrical power subsystem cannot be restored to OPERABLE status within the associated Completion Time, the unit must be brought to a MODE in which the LCO does not apply. To achieve this status, the plant must be brought to at least MODE 3 within 12 hours and to MODE 4 within 36 hours. The allowed Completion Times are reasonable, based on operating experience, to reach the required plant conditions from full power conditions in an orderly manner and without challenging plant systems. The Completion Time to bring the unit to MODE 4 is consistent with the time specified in Regulatory Guide 1.93 (Ref. 7).

SURVEILLANCE
REQUIREMENTS

The Surveillances are modified by two Notes to clearly identify how the Surveillances apply to the given unit and opposite unit DC electrical power sources. Note 1 states that SR 3.8.4.1 through SR 3.8.4.8 are applicable only to the given unit DC electrical power sources and Note 2 states that SR 3.8.4.9 is applicable to the opposite unit DC electrical power sources. These Notes are necessary since opposite unit DC electrical power sources are not required to perform all of the requirements of the given unit DC electrical power sources (e.g., the opposite unit battery is not required to perform SR 3.8.4.6, SR 3.8.4.7, and 3.8.4.8 under certain conditions when not in MODE 1, 2, or 3).

SR 3.8.4.1

Verifying battery terminal voltage while on float charge helps to ensure the effectiveness of the charging system and the ability of the batteries to perform their intended function. Float charge is the condition in which the

(continued)

BASES

SURVEILLANCE
REQUIREMENTS

SR 3.8.4.1 (continued)

charger is supplying the continuous charge required to overcome the internal losses of a battery and maintain the battery in a fully charged state. The voltage requirements are based on the nominal design voltage of the battery and are conservative when compared with the initial voltages assumed in the battery sizing calculations. The 7 day Frequency is consistent with manufacturers recommendations and IEEE-450 (Ref. 8).

SR 3.8.4.2

Visual inspection to detect corrosion of the battery cells and connections, or measurement of the resistance of each inter-cell and terminal connection, provides an indication of physical damage or abnormal deterioration that could potentially degrade battery performance.

The connection resistance limits established for this SR are within the values established by industry practice. The connection resistance limits of this SR are related to the resistance of individual bolted connections, and do not include the resistance of conductive components (e.g., cables or conductors located between cells, racks, or tiers).

The Surveillance Frequency for these inspections, which can detect conditions that can cause power losses due to resistance heating, is 92 days. This Frequency is considered acceptable based on operating experience related to detecting corrosion trends.

SR 3.8.4.3

Visual inspection of the battery cells, cell plates, and battery racks provides an indication of physical damage or abnormal deterioration that could potentially degrade battery performance.

The presence of physical damage or deterioration does not necessarily represent a failure of this SR, provided an evaluation determines that the physical damage or

(continued)

BASES

SURVEILLANCE
REQUIREMENTS

SR 3.8.4.3 (continued)

deterioration does not affect the OPERABILITY of the battery (its ability to perform its design function).

The 24 month Frequency for the Surveillance is based on engineering judgement. Operating experience has shown that these components usually pass the SR when performed at the 24 month Frequency. Therefore, the Frequency was concluded to be acceptable from a reliability standpoint.

SR 3.8.4.4 and SR 3.8.4.5

Visual inspection and resistance measurements of inter-cell and terminal connections provides an indication of physical damage or abnormal deterioration that could indicate degraded battery condition. The anti-corrosion material is used to ensure good electrical connections and to reduce terminal deterioration. The visual inspection for corrosion is not intended to require removal of and inspection under each terminal connection.

The removal of visible corrosion is a preventive maintenance SR. The presence of visible corrosion does not necessarily represent a failure of this SR, provided visible corrosion is removed during performance of this Surveillance.

The connection resistance limits for this SR are within the values established by industry practice. The connection resistance limits of this SR are related to the resistance of individual bolted connections, and do not include the resistance of conductive components (e.g., cables or conductors located between cells, racks, or tiers).

The 24 month Frequency for the Surveillance is based on engineering judgement. Operating experience has shown that these components usually pass the SR when performed at the 24 month Frequency. Therefore, the Frequency was concluded to be acceptable from a reliability standpoint.

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(continued)

SR 3.8.4.6

Battery charger capability requirements are based on the design capacity of the chargers (Ref. 4). According to Regulatory Guide 1.32 (Ref. 9), the battery charger supply is required to be based on the largest combined demands of the various steady state loads and the charging capacity to restore the battery from the design minimum charge state to the fully charged state, irrespective of the status of the unit during these demand occurrences. The minimum required amperes and duration ensure that these requirements can be satisfied.

The Surveillance Frequency is acceptable, given the administrative controls existing to ensure adequate charger performance during these 24 month intervals. In addition, this Frequency is intended to be consistent with expected fuel cycle lengths.

SR 3.8.4.7

A battery service test is a special test of the battery's capability, as found, to satisfy the design requirements (battery duty cycle) of the DC electrical power system. The discharge rate and test length correspond to the design duty cycle requirements as specified in Reference 4.

The Surveillance Frequency of 24 months is acceptable, given unit conditions required to perform the test and the other requirements existing to ensure adequate battery performance during these 24 month intervals. In addition, this Frequency is intended to be consistent with expected fuel cycle lengths.

This SR is modified by two Notes. Note 1 allows the performance of a modified performance discharge test in lieu of a service test provided the modified performance discharge test completely envelops the service test. This substitution is acceptable because a modified performance discharge test represents a more severe test of battery capacity than SR 3.8.4.7. The reason for Note 2 is that performing the Surveillance would remove a required 125 VDC electrical power subsystem from service, perturb the

(continued)

BASES

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SR 3.8.4.7 (continued)

electrical distribution system, and challenge safety systems. This restriction from normally performing the Surveillance in MODE 1 or 2 is further amplified to allow portions of the Surveillance to be performed for the purpose of reestablishing OPERABILITY (e.g., post work testing following corrective maintenance, corrective modification, deficient or incomplete surveillance testing, and other unanticipated OPERABILITY concerns) provided an assessment determines plant safety is maintained or enhanced. This assessment shall, as a minimum, consider the potential outcomes and transients associated with a failed partial Surveillance, a successful partial Surveillance, and a perturbation of the offsite or onsite system when they are tied together or operated independently for the partial Surveillance; as well as the operator procedures available to cope with these outcomes. These shall be measured against the avoided risk of a plant shutdown and startup to determine that plant safety is maintained or enhanced when portions of the Surveillance are performed in MODE 1 or 2. Risk insights or deterministic methods may be used for this assessment. Credit may be taken for unplanned events that satisfy the Surveillance.

SR 3.8.4.8

A battery performance discharge test is a test of constant current capacity of a battery, normally done in the as found condition, after having been in service, to detect any change in the capacity determined by the acceptance test. The test is intended to determine overall battery degradation due to age and usage.

A battery modified performance discharge test is a simulated duty cycle normally consisting of just two rates; the one minute rate published for the battery or the largest current load of the duty cycle, followed by the test rate employed for the performance discharge test, both of which envelope the duty cycle of the service test. (The test can consist of a single rate if the test rate employed for the performance discharge test exceeds the 1 minute rate and

(continued)

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SURVEILLANCE
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SR 3.8.4.8 (continued)

continues to envelope the duty cycle of the service test.) Since the ampere-hours removed by a rated one minute discharge represents a very small portion of the battery capacity, the test rate can be changed to that for the performance test without compromising the results of the performance discharge test. The battery terminal voltage for the modified performance discharge test should remain above the minimum battery terminal voltage specified in the battery service test for the duration of time equal to that of the service test.

A modified performance discharge test is a test of the battery capacity and its ability to provide a high rate, short duration load (usually the highest rate of the duty cycle). This will often confirm the battery's ability to meet the critical period of the load duty cycle, in addition to determining its percentage of rated capacity. Initial conditions for the modified performance discharge test should be identical to those specified for a service test when the modified performance discharge test is performed in lieu of a service test. Either the battery performance discharge test or the modified performance discharge test is acceptable for satisfying SR 3.8.4.8; however, only the modified performance discharge test may be used to satisfy SR 3.8.4.8 while satisfying the requirements of SR 3.8.4.7 at the same time.

The acceptance criteria for this Surveillance is consistent with IEEE-450 (Ref. 8) and IEEE-485 (Ref. 11). These references recommend that the battery be replaced if its capacity is below 80% of the manufacturer's rating, since IEEE-485 (Ref. 11) recommends using an ageing factor of 125% in the battery sizing calculation. A capacity of 80% shows that the battery rate of deterioration is increasing, even if there is ample capacity to meet the load requirements.

The Surveillance Frequency for this test is normally 60 months. If the battery shows degradation, or if the battery has reached 85% of its expected life and capacity is < 100% of the manufacturers rating, the Surveillance Frequency is reduced to 12 months. However, if the battery shows no degradation but has reached 85% of its expected life, the Surveillance Frequency is only reduced to 24 months for batteries that retain capacity \geq 100% of the

(continued)

BASES

SURVEILLANCE
REQUIREMENTS

SR 3.8.4.8 (continued)

manufacturers rating. Degradation is indicated, consistent with IEEE-450 (Ref. 8), when the battery capacity drops by more than 10% relative to its capacity on the previous performance test or when it is \geq 10% below the manufacturers rating. The 12 month and 60 month Frequencies are consistent with the recommendations in IEEE-450 (Ref. 8). The 24 month Frequency is derived from the recommendations of IEEE-450 (Ref. 8).

This SR is modified by a Note. The reason for the Note is that performing the Surveillance would remove a required 125 VDC electrical power subsystem from service, perturb the electrical distribution system, and challenge safety systems. This restriction from normally performing the Surveillance in MODE 1 or 2 is further amplified to allow portions of the Surveillance to be performed for the purpose of reestablishing OPERABILITY (e.g., post work testing following corrective maintenance, corrective modification, deficient or incomplete surveillance testing, and other unanticipated OPERABILITY concerns) provided an assessment determines plant safety is maintained or enhanced. This assessment shall, as a minimum, consider the potential outcomes and transients associated with a failed partial Surveillance, a successful partial Surveillance, and a perturbation of the offsite or onsite system when they are tied together or operated independently for the partial Surveillance; as well as the operator procedures available to cope with these outcomes. These shall be measured against the avoided risk of a plant shutdown and startup to determine that plant safety is maintained or enhanced when portions of the Surveillance are performed in MODE 1 or 2. Risk insights or deterministic methods may be used for this assessment. Credit may be taken for unplanned events that satisfy this SR.

SR 3.8.4.9

With the exception of this Surveillance, all other Surveillances of this Specification (SR 3.8.4.1 through 3.8.4.8) are applied to the given unit DC sources. This Surveillance is provided to direct that appropriate Surveillances for the required opposite unit DC source are governed by the applicable opposite unit Technical

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BASES

SURVEILLANCE
REQUIREMENTS

SR 3.8.4.9 (continued)

Specifications. Performance of the applicable opposite unit Surveillances will satisfy the opposite unit requirements as well as satisfy the given unit Surveillance Requirement.

The Frequency required by the applicable opposite unit SR also governs performance of that SR for the given unit.

As noted, if the opposite unit is in MODE 4 or 5, or moving irradiated fuel assemblies in secondary containment, SR 3.8.4.6, SR 3.8.4.7, and SR 3.8.4.8 are not required to be performed. This ensures that a given unit SR will not require an opposite unit SR to be performed, when the opposite unit Technical Specifications exempts performance of an opposite unit SR (however, as stated in the opposite unit SR 3.8.5.1 Note 1, while performance of an SR is exempted, the SR must still be met).

REFERENCES

1. 10 CFR 50, Appendix A, GDC 17.
 2. Regulatory Guide 1.6, March 10, 1971.
 3. IEEE Standard 308, 1971.
 4. UFSAR, Section 8.3.2.
 5. UFSAR, Chapter 6.
 6. UFSAR, Chapter 15.
 7. Regulatory Guide 1.93, December 1974.
 8. IEEE Standard 450, 1995.
 9. Regulatory Guide 1.32, August 1972.
 10. IEEE Standard 485, 1978.
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B 3.8 ELECTRICAL POWER SYSTEMS

B 3.8.5 DC Sources – Shutdown

BASES

BACKGROUND A description of the DC sources is provided in the Bases for LCO 3.8.4, "DC Sources – Operating."

APPLICABLE SAFETY ANALYSES The initial conditions of Design Basis Accident and transient analyses in the UFSAR, Chapter 6 (Ref. 1) and Chapter 15 (Ref. 2), assume that Engineered Safety Feature systems are OPERABLE. The DC electrical power system provides normal and emergency DC electrical power for the diesel generators, emergency auxiliaries, and control and switching during all MODES of operation and during movement of irradiated fuel assemblies in the secondary containment.

The OPERABILITY of the DC subsystems is consistent with the initial assumptions of the accident analyses and the requirements for the supported systems' OPERABILITY.

The OPERABILITY of the minimum DC electrical power sources during MODES 4 and 5 and during movement of irradiated fuel assemblies in the secondary containment ensures that:

- a. The facility can be maintained in the shutdown or refueling condition for extended periods;
- b. Sufficient instrumentation and control capability is available for monitoring and maintaining the unit status; and
- c. Adequate DC electrical power is provided to mitigate events postulated during shutdown, such as an inadvertent draindown of the vessel or a fuel handling accident.

In general, when the unit is shut down, the Technical Specifications requirements ensure that the unit has the capability to mitigate the consequences of postulated accidents. However, assuming a single failure and concurrent loss of all offsite or all on-site power is not required. The rationale for this is based on the fact that many Design Basis Accidents (DBAs) that are analyzed in MODES 1, 2, and 3 have no specific analyses in MODES 4

(continued)

BASES

APPLICABLE
SAFETY ANALYSES
(continued)

and 5. Worst case bounding events are deemed not credible in MODES 4 and 5 because the energy contained within the reactor pressure boundary, reactor coolant temperature and pressure, and the corresponding stresses result in the probabilities of occurrence being significantly reduced or eliminated, and in minimal consequences. These deviations from DBA analysis assumptions and design requirements during shutdown conditions are allowed by the LCO for required systems.

The shutdown Technical Specification requirements are designed to ensure that the unit has the capability to mitigate the consequences of certain postulated accidents. Worst case Design Basis Accidents which are analyzed for operating MODES are generally viewed not to be a significant concern during shutdown MODES due to the lower energies involved. The Technical Specifications therefore require a lesser complement of electrical equipment to be available during shutdown than is required during operating MODES. More recent work completed on the potential risks associated with shutdown, however, have found significant risk associated with certain shutdown evolutions. As a result, in addition to the requirements established in the Technical Specifications, the Industry has adopted NUMARC 91-06, "Guidelines for Industry Actions to Assess Shutdown Management," as an industry initiative to manage shutdown tasks and associated electrical support to maintain risk at an acceptable low level. This may require the availability of additional equipment beyond that required by the shutdown Technical Specifications.

The DC sources satisfy Criterion 3 of
10 CFR 50.36(c)(2)(ii).

LCO

The DC electrical power subsystems, each required subsystem consisting of one battery, one battery charger, and the corresponding control equipment and interconnecting cabling supplying power to the associated buses within the division, are required to be OPERABLE to support some of the required DC Distribution System divisions required OPERABLE by LCO 3.8.8, "Distribution Systems – Shutdown." This ensures the availability of sufficient DC electrical power sources to operate the unit in a safe manner and to mitigate the

(continued)

BASES

LCO
(continued) consequences of postulated events during shutdown (e.g.,
fuel handling accidents and inadvertent reactor vessel
draindown).

APPLICABILITY The DC electrical power sources required to be OPERABLE in
MODES 4 and 5 and during movement of irradiated fuel
assemblies in the secondary containment provide assurance
that:

- a. Required features to provide adequate coolant
 inventory makeup are available for the irradiated fuel
 assemblies in the core in case of an inadvertent
 draindown of the reactor vessel;
- b. Required features needed to mitigate a fuel handling
 accident are available;
- c. Required features necessary to mitigate the effects of
 events that can lead to core damage during shutdown
 are available; and
- d. Instrumentation and control capability is available
 for monitoring and maintaining the unit in a cold
 shutdown condition or refueling condition.

The DC electrical power requirements for MODES 1, 2, and 3
are covered in LCO 3.8.4.

ACTIONS LCO 3.0.3 is not applicable while in MODE 4 or 5. However,
since irradiated fuel assembly movement can occur in MODE 1,
2, or 3, the ACTIONS have been modified by a Note stating
that LCO 3.0.3 is not applicable. If moving irradiated fuel
assemblies while in MODE 4 or 5, LCO 3.0.3 would not specify
any action. If moving irradiated fuel assemblies while in
MODE 1, 2, or 3, the fuel movement is independent of reactor
operations. Entering LCO 3.0.3 while in MODE 1, 2, or 3
would require the unit to be shutdown, but would not require
immediate suspension of movement of irradiated fuel
assemblies. The Note to the ACTIONS, "LCO 3.0.3 is not
applicable," ensures that the actions for immediate
suspension of irradiated fuel assembly movement are not
postponed due to entry into LCO 3.0.3.

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BASES

ACTIONS
(continued)

A.1 and A.2

With one or more required Division 1, 2, and 3 DC electrical power subsystems inoperable, the associated DC electrical power distribution subsystem may not be capable of supporting its required features. However, if the opposite unit's DC electrical power subsystem for the same division is OPERABLE, power can be supplied by the OPERABLE opposite unit DC electrical power subsystem. This will maintain the given unit's DC electrical power distribution subsystem energized from an OPERABLE DC electrical power subsystem, ensuring it remains capable of supporting its required features. Therefore, Required Action A.1 requires verification within 1 hour that the associated DC electrical power distribution subsystem is energized by the OPERABLE opposite unit DC electrical power subsystem. If this cannot be verified within 1 hour, then Condition B is required to be entered and its Required Actions taken. If this can be verified, then operation in the condition is allowed to continue and the inoperable required Division 1, 2, and 3 DC electrical power subsystems must be restored to OPERABLE status (and the associated DC electrical power distribution subsystem must be realigned to its unit DC electrical power subsystem) within 72 hours. The Completion Time is acceptable since the opposite unit's DC electrical power subsystem is capable of powering both unit's loads in the event of an accident on the opposite unit and the low probability of an accident occurring during this time. As noted, this allowance is only applicable if the opposite unit is not in MODE 1, 2, or 3. This allowance can not be used with the opposite unit in MODES 1, 2, and 3 since the associated subsystems are required the support the OPERABILITY of opposite unit safety equipment. The Division 2 DC electrical power source subsystem for each unit supports redundant safety equipment for both units and the batteries have insufficient capacity to support the required loads for both units if either unit is in MODE 1, 2, or 3. Therefore, this allowance is only permitted to be used when both units are in shutdown conditions (MODE 4, 5, or defueled) when divisional separation is not required.

(continued)

BASES

ACTIONS
(continued)

B.1, B.2.1, B.2.2, B.2.3, and B.2.4

By allowing the option to declare required features inoperable with associated DC electrical power subsystems inoperable, appropriate restrictions are implemented in accordance with the affected system LCOs' ACTIONS. However, in many instances this option may involve undesired administrative efforts. Therefore, the allowance for sufficiently conservative actions is made (i.e., to suspend CORE ALTERATIONS, movement of irradiated fuel assemblies in the secondary containment, and any activities that could result in inadvertent draining of the reactor vessel).

Suspension of these activities shall not preclude completion of actions to establish a safe conservative condition. These actions minimize the probability of the occurrence of postulated events. It is further required to immediately initiate action to restore the required DC electrical power subsystems and to continue this action until restoration is accomplished in order to provide the necessary DC electrical power to the plant safety systems.

The Completion Time of immediately is consistent with the required times for actions requiring prompt attention. The restoration of the required DC electrical power subsystems should be completed as quickly as possible in order to minimize the time during which the plant safety systems may be without sufficient power.

SURVEILLANCE
REQUIREMENTS

SR 3.8.5.1

SR 3.8.5.1 requires all Surveillances required by SR 3.8.4.1 through SR 3.8.4.9 to be applicable. Therefore, see the corresponding Bases for LCO 3.8.4 for a discussion of each SR.

This SR is modified by a Note. The reason for the Note is to preclude requiring the OPERABLE DC sources from being discharged below their capability to provide the required power supply or otherwise rendered inoperable during the performance of SRs. It is the intent that these SRs must still be capable of being met, but actual performance is not required.

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BASES (continued)

- REFERENCES
1. UFSAR, Chapter 6.
 2. UFSAR, Chapter 15.
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B 3.8 ELECTRICAL POWER SYSTEMS

B 3.8.6 Battery Cell Parameters

BASES

BACKGROUND This LCO delineates the limits on electrolyte temperature, level, float voltage, and specific gravity for the DC power source batteries. A discussion of these batteries and their OPERABILITY requirements is provided in the Bases for LCO 3.8.4, "DC Sources—Operating," and LCO 3.8.5, "DC Sources—Shutdown."

APPLICABLE SAFETY ANALYSES The initial conditions of Design Basis Accident (DBA) and transient analyses in UFSAR, Chapter 6 (Ref. 1) and Chapter 15 (Ref. 2), assume Engineered Safety Feature systems are OPERABLE. The DC electrical power subsystems provide normal and emergency DC electrical power for the diesel generators, emergency auxiliaries, and control and switching during all MODES of operation.

The OPERABILITY of the DC subsystems is consistent with the initial assumptions of the accident analyses and is based upon meeting the design basis of the unit as discussed in the Bases for LCO 3.8.4 and LCO 3.8.5.

Since battery cell parameters support the operation of the DC power sources, they satisfy Criterion 3 of 10 CFR 50.36(c)(2)(ii).

LCO Battery cell parameters must remain within acceptable limits to ensure availability of the required DC power to shut down the reactor and maintain it in a safe condition after an anticipated operational occurrence or a postulated DBA. Electrolyte limits are conservatively established, allowing continued DC electrical system function even with limits not met.

APPLICABILITY The battery cell parameters are required solely for the support of the associated DC electrical power subsystem. Therefore, these cell parameters are only required when the associated DC electrical power subsystem is required to be OPERABLE. Refer to the Applicability discussion in Bases for LCO 3.8.4 and LCO 3.8.5.

(continued)

BASES (continued)

ACTIONS

The ACTIONS Table is modified by a Note which indicates that separate Condition entry is allowed for each battery. This is acceptable, since the Required Actions for each Condition provide appropriate compensatory actions for each inoperable DC electrical power subsystem. Complying with the Required Actions for one inoperable DC electrical power subsystem may allow for continued operation, and subsequent inoperable DC electrical power subsystem(s) are governed by separate Condition entry and application of associated Required Actions.

A.1, A.2, and A.3

With parameters of one or more cells in one or more batteries not within Table 3.8.6-1 limits (i.e., Category A limits not met, Category B limits not met, or Category A and B limits not met) but within the Category C limits specified in Table 3.8.6-1, the battery is degraded but there is still sufficient capacity to perform the intended function. Therefore, the affected battery is not required to be considered inoperable solely as a result of Category A or B limits not met, and continued operation is permitted for a limited period.

The pilot cell(s) electrolyte level and float voltage are required to be verified to meet Category C limits within 1 hour (Required Action A.1). This check provides a quick indication of the status of the remainder of the battery cells. One hour provides time to inspect the electrolyte level and to confirm the float voltage of the pilot cell(s). One hour is considered a reasonable amount of time to perform the required verification.

Verification that the Category C limits are met (Required Action A.2) provides assurance that, during the time needed to restore the parameters to the Category A and B limits, the battery is still capable of performing its intended function. A period of 24 hours is allowed to complete the initial verification because specific gravity measurements must be obtained for each connected cell. Taking into consideration both the time required to perform the required verification and the assurance that the battery cell parameters are not severely degraded, this time is

(continued)

BASES

ACTIONS

A.1, A.2, and A.3 (continued)

considered reasonable. The verification is repeated at 7 day intervals until the parameters are restored to Category A and B limits. This periodic verification is consistent with the normal Frequency of pilot cell Surveillances.

Continued operation is only permitted for 31 days before battery cell parameters must be restored to within Category A and B limits. Taking into consideration that while battery capacity is degraded, sufficient capacity exists to perform the intended function and to allow time to fully restore the battery cell parameters to normal limits, this time is acceptable for operation prior to declaring the associated DC batteries inoperable.

B.1

When any battery parameter is outside the Table 3.8.6-1 Category C limit for any connected cell, sufficient capacity to supply the maximum expected load requirement is not assured and the corresponding DC electrical power subsystem must be declared inoperable. Additionally, other potentially extreme conditions, such as any Required Actions of Condition A and associated Completion Time not met or average electrolyte temperature of representative cells < 60°F, for the 125 V batteries, or < 65°F for the 250 V battery, also are cause for immediately declaring the associated DC electrical power subsystem inoperable.

SURVEILLANCE
REQUIREMENTS

SR 3.8.6.1

The SR verifies that Table 3.8.6-1 Category A battery cell parameters are consistent with IEEE-450 (Ref. 3), which recommends regular battery inspections (at least one per month) including voltage, specific gravity, and electrolyte level of pilot cells.

SR 3.8.6.2

The quarterly inspection of specific gravity, voltage, and electrolyte level for each connected cell is consistent with IEEE-450 (Ref. 3). In addition, within 7 days of a battery

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SURVEILLANCE
REQUIREMENTS

SR 3.8.6.2 (continued)

discharge < 110 V for a 125 V battery and < 220 V for the 250 V battery or a battery overcharge > 150 V for a 125 V battery and > 300 V for the 250 V battery, the battery must be demonstrated to meet Table 3.8.6-1 Category B limits. Transients, such as motor starting transients, which may momentarily cause battery voltage to drop to ≤ 110 V or 220 V, as applicable, do not constitute a battery discharge provided the battery terminal voltage and float return to pre-transient values. This inspection is also consistent with IEEE-450 (Ref. 3), which recommends special inspections following a severe discharge or overcharge, to ensure that no significant degradation of the battery occurs as a consequence of such discharge or overcharge. The 7 day requirement is based on engineering judgement.

SR 3.8.6.3

This Surveillance verification that the average temperature of representative cells is $\geq 60^{\circ}\text{F}$ for the 125 V batteries and $\geq 65^{\circ}\text{F}$ for the 250 V battery is consistent with a recommendation of IEEE-450 (Ref. 3), which states that the temperature of electrolytes in representative cells should be determined on a quarterly basis. For this SR, a check of 10 connected cells is considered representative for the 125 V batteries, and a check of 20 connected cells is considered representative for the 250 V battery.

Lower than normal temperatures act to inhibit or reduce battery capacity. This SR ensures that the operating temperatures remain within an acceptable operating range. This limit is based on manufacturer's recommendations and the battery sizing calculations.

Table 3.8.6-1

This Table delineates the limits on electrolyte level, float voltage, and specific gravity for three different categories. The meaning of each category is discussed below.

Category A defines the normal parameter limit for each designated pilot cell in each battery. The cells selected

(continued)

BASES

SURVEILLANCE
REQUIREMENTS

Table 3.8.6-1 (continued)

as pilot cells are those whose temperature, voltage, and electrolyte specific gravity approximate the state of charge of the entire battery.

The Category A limits specified for electrolyte level are based on manufacturers recommendations and are consistent with the guidance in IEEE-450 (Ref. 3), with the extra $\frac{1}{4}$ inch allowance above the high water level indication for operating margin to account for temperatures and charge effects. In addition to this allowance, footnote (a) to Table 3.8.6-1 permits the electrolyte level to be temporarily above the specified maximum level during and, for a limited time, following an equalizing charge (normally up to 3 days following the completion of an equalize charge to allow electrolyte stabilization), provided it is not overflowing. These limits ensure that the plates suffer no physical damage, and that adequate electron transfer capability is maintained in the event of transient conditions. IEEE-450 (Ref. 3) recommends that electrolyte level readings should be made only after the battery has been at float charge for at least 72 hours.

The Category A limit specified for float voltage is ≥ 2.13 V per cell. This value is based on the recommendation of IEEE-450 (Ref. 3), which states that prolonged operation of cells below 2.13 V can reduce the life expectancy of cells.

The Category A limit specified for specific gravity for each pilot cell is ≥ 1.200 (0.015 below the manufacturer's fully charged nominal specific gravity or a battery charging current that had stabilized at a low value). This value is characteristic of a charged cell with adequate capacity. According to IEEE-450 (Ref. 3), the specific gravity readings are based on a temperature of 77°F (25°C).

The specific gravity readings are corrected for actual electrolyte temperature and level. For each 3°F (1.67°C) above 77°F (25°C), 1 point (0.001) is added to the reading; 1 point is subtracted for each 3°F below 77°F. The specific gravity of the electrolyte in a cell increases with a loss of water due to electrolysis or evaporation. Level correction will be in accordance with manufacturers recommendations.

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BASES

SURVEILLANCE
REQUIREMENTS

Table 3.8.6-1 (continued)

Category B defines the normal parameter limits for each connected cell. The term "connected cell" excludes any battery cell that may be jumpered out.

The Category B limits specified for electrolyte level and float voltage are the same as those specified for Category A and have been discussed above. The Category B limit specified for specific gravity for each connected cell is ≥ 1.195 (0.020 below the manufacturers fully charged, nominal specific gravity) with the average of all connected cells > 1.205 (0.010 below the manufacturers fully charged, nominal specific gravity). These values are based on manufacturer's recommendations. The minimum specific gravity value required for each cell ensures that a cell with a marginal or unacceptable specific gravity is not masked by averaging with cells having higher specific gravities.

Category C defines the limit for each connected cell. These values, although reduced, provide assurance that sufficient capacity exists to perform the intended function and maintain a margin of safety. When any battery parameter is outside the Category C limit, the assurance of sufficient capacity described above no longer exists, and the battery must be declared inoperable.

The Category C limit specified for electrolyte level (above the top of the plates and not overflowing) ensures that the plates suffer no physical damage and maintain adequate electron transfer capability. The Category C limit for float voltage is based on IEEE-450 (Ref. 3), which states that a cell voltage of 2.07 V or below, under float conditions and not caused by elevated temperature of the cell, indicates internal cell problems and may require cell replacement.

The Category C limit of average specific gravity (≥ 1.195), is based on manufacturer's recommendations (0.020 below the manufacturer's recommended fully charged, nominal specific gravity). In addition to that limit, it is required that the specific gravity for each connected cell must be no

(continued)

BASES

SURVEILLANCE
REQUIREMENTS

Table 3.8.6-1 (continued)

more than 0.020 below the average of all connected cells. This limit ensures that the a cell with a marginal or unacceptable specific gravity is not masked by averaging with cells having higher specific gravities.

The footnotes to Table 3.8.6-1 that apply to specific gravity are applicable to Category A, B, and C specific gravity. Footnote (b) requires the above mentioned correction for electrolyte level and temperature.

Because of specific gravity gradients that are produced during the recharging process, delays of several days may occur while waiting for the specific gravity to stabilize. A stabilized charging current is an acceptable alternative to specific gravity measurement for determining the state of charge. This phenomenon is discussed in IEEE-450 (Ref. 3). Footnote (c) allows the float charge current to be used as an alternate to specific gravity for up to 7 days following a battery recharge. Within 7 days each connected cell's specific gravity must be measured to confirm the state of charge. Following a minor battery recharge (such as equalizing charge that does not follow a deep discharge) specific gravity gradients are not significant, and confirming measurements may be made in less than 7 days.

REFERENCES

1. UFSAR, Chapter 6.
 2. UFSAR, Chapter 15.
 3. IEEE Standard 450, 1987.
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B 3.8 ELECTRICAL POWER SYSTEMS

B 3.8.7 Distribution Systems – Operating

BASES

BACKGROUND The onsite Class 1E AC and DC electrical power distribution system for each unit is divided by division into three independent AC and DC electrical power distribution subsystems. Each unit is also dependent on portions of the opposite unit's Division 2 AC and DC power distribution subsystems.

The primary AC Distribution System consists of three 4.16 kV emergency buses that are supplied from the transmission system by two physically independent circuits. The Division 2 and 3 emergency buses also have a dedicated onsite diesel generator (DG) source, while the Unit 1 and 2 Division 1 buses share an onsite DG source. The Division 1, 2, and 3 4.16 kV emergency buses are normally supplied through the system auxiliary transformer (SAT). In addition to the SAT, Division 1 and 2 can be supplied from the unit auxiliary transformer or the opposite unit's SAT. Control power for the 4.16 kV breakers is supplied from the Class 1E batteries. Additional description of this system may be found in the Bases for LCO 3.8.1, "AC Sources – Operating," and the Bases for LCO 3.8.4, "DC Sources – Operating."

The secondary plant AC distribution system includes 480 V ESF load centers and associated loads, motor control centers, and transformers.

There are three independent 125 VDC electrical power distribution subsystems. The Division 2 Class 1E AC and DC electrical power distribution subsystems associated with each unit are shared by each unit since some systems are common to both units. The opposite unit Division 2 Class 1E AC and DC electrical power distribution subsystems support equipment required to be OPERABLE by LCO 3.6.3.1, "Primary Containment Hydrogen Recombiners," LCO 3.6.4.3, "Standby Gas Treatment (SGT) System," LCO 3.7.4, "Control Room Area Filtration (CRAF) System," LCO 3.7.5, "Control Room Area Ventilation Air Conditioning (AC) System," and LCO 3.8.1, "AC Sources – Operating."

(continued)

BASES

BACKGROUND (continued) The list of all required distribution buses for Unit 1 and Unit 2 is located in Tables B 3.8.7-1 and B 3.8.7-2, respectively.

APPLICABLE SAFETY ANALYSES The initial conditions of Design Basis Accident (DBA) and transient analyses in the UFSAR, Chapter 6 (Ref. 1) and Chapter 15 (Ref. 2), assume Engineered Safety Features (ESF) systems are OPERABLE. The AC and DC electrical power distribution systems are designed to provide sufficient capacity, capability, redundancy, and reliability to ensure the availability of necessary power to ESF systems so that the fuel, Reactor Coolant System, and containment design limits are not exceeded. These limits are discussed in more detail in the Bases for Section 3.2, Power Distribution Limits; Section 3.5, Emergency Core Cooling Systems (ECCS) and Reactor Core Isolation Cooling (RCIC) System; and Section 3.6, Containment Systems.

The OPERABILITY of the AC and DC electrical power distribution systems is consistent with the initial assumptions of the accident analyses and is based upon meeting the design basis of the plant. This includes maintaining the AC and DC electrical power sources and associated distribution systems OPERABLE during accident conditions in the event of:

- a. An assumed loss of all offsite or onsite AC electrical power; and
- b. A worst case single failure.

The AC and DC electrical power distribution systems satisfy Criterion 3 of 10 CFR 50.36(c)(2)(ii).

LCO The required AC and DC electrical power distribution subsystems listed in Table B 3.8.7-1 for Unit 1 and Table B 3.8.7-2 for Unit 2 ensure the availability of AC and DC electrical power for the systems required to shut down the reactor and maintain it in a safe condition after an anticipated operational occurrence (AOO) or a postulated DBA. The Division 1, 2, and 3 AC and DC bus electrical power primary distribution subsystems are required to be

(continued)

BASES

LCO
(continued)

OPERABLE and certain buses of the opposite unit Division 2 AC and DC electrical power distribution subsystems are required to be OPERABLE to support the equipment required to be OPERABLE by LCO 3.6.3.1, LCO 3.6.4.3, LCO 3.7.4, LCO 3.7.5, and LCO 3.8.1. As noted in Table B 3.8.7-1 and Table B 3.8.7-2 (Footnote a), each division of the AC and DC electrical power distribution systems is a subsystem.

Maintaining the Division 1, 2, and 3 AC and DC electrical power distribution subsystems OPERABLE ensures that the redundancy incorporated into the design of ESF is not defeated. Any two of the three divisions of the distribution system are capable of providing the necessary electrical power to the associated ESF components. Therefore, a single failure within any system or within the electrical power distribution subsystems does not prevent safe shutdown of the reactor.

OPERABLE AC electrical power distribution subsystems require the associated buses to be energized to their proper voltages. OPERABLE DC electrical power distribution subsystems require the associated buses to be energized to their proper voltage from either the associated battery or charger.

Based on the number of safety significant electrical loads associated with each bus listed in Table B 3.8.7-1 for Unit 1 and Table B 3.8.7-2 for Unit 2, if one or more of the buses becomes inoperable, entry into the appropriate ACTIONS of LCO 3.8.7 is required. Some buses, such as distribution panels, which help comprise the AC and DC distribution systems are not listed in Table B 3.8.7-1 for Unit 1 and Table B 3.8.7-2 for Unit 2. The loss of electrical loads associated with these buses may not result in a complete loss of a redundant safety function necessary to shut down the reactor and maintain it in a safe condition. Therefore, should one or more of these buses become inoperable due to a failure not affecting the OPERABILITY of a bus listed in Table B 3.8.7-1 for Unit 1 and Table B 3.8.7-2 for Unit 2 (e.g., a breaker supplying a single distribution panel fails open), the individual loads on the bus would be considered inoperable, and the appropriate Conditions and Required Actions of the LCOs governing the individual loads would be entered. However, if one or more of these buses is

(continued)

BASES

LCO
(continued) inoperable due to a failure also affecting the OPERABILITY of a bus listed in Table B 3.8.7-1 for Unit 1 and Table B 3.8.7-2 for Unit 2 (e.g., loss of 4.16 kV emergency bus, which results in de-energization of all buses powered from the 4.16 kV emergency bus), then although the individual loads are still considered inoperable, the Conditions and Required Actions of the LCO for the individual loads are not required to be entered, since LCO 3.0.6 allows this exception (i.e., the loads are inoperable due to the inoperability of a support system governed by a Technical Specification; the 4.16 kV emergency bus).

In addition, at least one tie breaker between the redundant Division 2, safety related DC emergency power distribution subsystems must be open. This prevents an electrical malfunction in one power distribution subsystem from propagating to the redundant subsystem, which could cause the failure of a redundant subsystem and a loss of essential safety function(s). If at least one tie breaker is not open, then both Division 2 DC electrical power distribution subsystems are considered inoperable. The restriction of maintaining electrical separation applies to the onsite, safety related, redundant electrical power distribution subsystems. It does not, however, preclude redundant Class 1E 4.16 kV emergency buses from being supplied from the same offsite source.

APPLICABILITY The electrical power distribution subsystems are required to be OPERABLE in MODES 1, 2, and 3 to ensure that:

- a. Acceptable fuel design limits and reactor coolant pressure boundary limits are not exceeded as a result of AOs or abnormal transients; and
- b. Adequate core cooling is provided, and containment OPERABILITY and other vital functions are maintained, in the event of a postulated DBA.

Electrical power distribution subsystem requirements for MODES 4 and 5 and other conditions in which AC and DC electrical power distribution subsystems are required, are covered in the Bases for LCO 3.8.8, "Distribution Systems—Shutdown."

(continued)

BASES (continued)

ACTIONS

A.1

With one or more Division 1 and 2 required AC buses, load centers, motor control centers, or distribution panels inoperable and a loss of function has not yet occurred, the remaining AC electrical power distribution subsystems are capable of supporting the minimum safety functions necessary to shut down the reactor and maintain it in a safe shutdown condition, assuming no single failure. The overall reliability is reduced, however, because a single failure in the remaining electrical power distribution subsystems could result in the minimum required ESF functions not being supported. Therefore, the required AC buses, load centers, motor control centers, and distribution panels must be restored to OPERABLE status within 8 hours.

The Condition A worst scenario is two divisions without AC power (i.e., no offsite power to the divisions and the associated DGs inoperable). In this situation, the unit is more vulnerable to a complete loss of AC power. It is, therefore, imperative that the unit operators' attention be focused on minimizing the potential for loss of power to the remaining division by stabilizing the unit and restoring power to the affected division. The 8 hour time limit before requiring a unit shutdown in this Condition is acceptable because of:

- a. The potential for decreased safety if the unit operators' attention is diverted from the evaluations and actions necessary to restore power to the affected division to the actions associated with taking the unit to shutdown within this time limit.
- b. The low potential for an event in conjunction with a single failure of a redundant component in the division with AC power. (The redundant component is verified OPERABLE in accordance with Specification 5.5.12, "Safety Function Determination Program (SFDP).")

(continued)

BASES

ACTIONS

A.1 (continued)

The second Completion Time for Required Action A.1 establishes a limit on the maximum time allowed for any combination of required distribution subsystems to be inoperable during any single contiguous occurrence of failing to meet LCO 3.8.7.a. If Condition A is entered while, for instance, a DC electrical power distribution subsystem is inoperable and subsequently returned OPERABLE, LCO 3.8.7.a may already have been not met for up to 2 hours. This situation could lead to a total duration of 10 hours, since initial failure of LCO 3.8.7.a, to restore the AC electrical power distribution system. At this time, a DC electrical power distribution subsystem could again become inoperable, and the AC electrical power distribution could be restored OPERABLE. This could continue indefinitely.

This Completion Time allows for an exception to the normal "time zero" for beginning the allowed outage time "clock." This results in establishing the "time zero" at the time LCO 3.8.7.a was initially not met, instead of at the time Condition A was entered. The 16 hour Completion Time is an acceptable limitation on this potential to fail to meet LCO 3.8.7.a indefinitely.

B.1

With one or more Division 1 and 2 DC electrical distribution subsystems inoperable and a loss of function has not yet occurred, the remaining DC electrical power distribution subsystems are capable of supporting the minimum safety functions necessary to shut down the reactor and maintain it in a safe shutdown condition, assuming no single failure. The overall reliability is reduced, however, because a single failure in the remaining DC electrical power distribution subsystems could result in the minimum required ESF functions not being supported. Therefore, the required DC electrical power distribution subsystem(s) must be restored to OPERABLE status within 2 hours by powering the bus from the associated battery or charger.

(continued)

BASES

ACTIONS

B.1 (continued)

Condition B worst scenario is two divisions without adequate DC power, potentially with both the battery significantly degraded and the associated charger nonfunctioning. In this situation, the plant is significantly more vulnerable to a complete loss of all DC power. It is, therefore, imperative that the operator's attention focus on stabilizing the plant, minimizing the potential for loss of power to the remaining divisions, and restoring power to the affected division(s).

This 2 hour limit is more conservative than Completion Times allowed for the majority of components that could be without power. Taking exception to LCO 3.0.2 for components without adequate DC power, that would have Required Action Completion Times shorter than 2 hours, is acceptable because of:

- a. The potential for decreased safety when requiring a change in plant conditions (i.e., requiring a shutdown) while not allowing stable operations to continue;
- b. The potential for decreased safety when requiring entry into numerous applicable Conditions and Required Actions for components without DC power while not providing sufficient time for the operators to perform the necessary evaluations and actions for restoring power to the affected division; and
- c. The potential for an event in conjunction with a single failure of a redundant component.

The 2 hour Completion Time for DC electrical power distribution subsystems is consistent with Regulatory Guide 1.93 (Ref. 3).

(continued)

BASES

ACTIONS

B.1 (continued)

The second Completion Time for Required Action B.1 establishes a limit on the maximum time allowed for any combination of required distribution subsystems to be inoperable during any single contiguous occurrence of failing to meet LCO 3.8.7.a. If Condition B is entered while, for instance, an AC electrical power distribution subsystem is inoperable and subsequently returned OPERABLE, LCO 3.8.7.a may already have been not met for up to 8 hours. This situation could lead to a total duration of 10 hours, since initial failure of LCO 3.8.7.a, to restore the DC electrical power distribution system. At this time, an AC electrical power distribution subsystem could again become inoperable, and DC electrical power distribution subsystem could be restored OPERABLE. This could continue indefinitely.

This Completion Time allows for an exception to the normal "time zero" for beginning the allowed outage time "clock." This allowance results in establishing the "time zero" at the time LCO 3.8.7.a was initially not met, instead of the time Condition B was entered. The 16 hour Completion Time is an acceptable limitation on this potential of failing to meet LCO 3.8.7.a indefinitely.

C.1

With one or more required opposite unit Division 2 AC or DC electrical power distribution subsystems inoperable and a loss of function has not yet occurred, certain redundant Division 2 features (e.g., a standby gas treatment subsystem) will not function if a design basis event were to occur. Therefore, a 7 day Completion Time is provided to restore the required opposite unit Division 2 AC and DC electrical power distribution subsystems to OPERABLE status. The 7 day Completion Time takes into account the capacity and capability of the remaining AC and DC electrical power distribution subsystems, and is based on the shortest restoration time allowed for the systems affected by the inoperable AC and DC electrical power distribution subsystems in the respective system specifications.

(continued)

BASES

ACTIONS

C.1 (continued)

The Required Action is modified by a Note indicating that the applicable Conditions of LCO 3.8.1 be entered and Required Actions taken if the inoperable opposite unit AC electrical power distribution subsystem results in an inoperable required offsite circuit. This is an exception to LCO 3.0.6 and ensures the proper actions are taken for these components.

D.1 and D.2

If the inoperable electrical power distribution system cannot be restored to OPERABLE status within the associated Completion Times, the plant must be brought to a MODE in which the LCO does not apply. To achieve this status, the plant must be brought to at least MODE 3 within 12 hours and to MODE 4 within 36 hours. The allowed Completion Times are reasonable, based on operating experience, to reach the required plant conditions from full power conditions in an orderly manner and without challenging plant systems.

E.1

With the Division 3 electrical power distribution system inoperable (i.e., one or both Division 3 AC or DC electrical power distribution subsystems inoperable), the Division 3 powered systems are not capable of performing their intended functions. Immediately declaring the affected supported features, e.g., the High Pressure Core Spray System and its associated primary containment isolation valves, inoperable allows the ACTIONS of LCO 3.5.1, "ECCS—Operating," and LCO 3.6.1.3, "Primary Containment Isolation Valves (PCIVs)," to apply appropriate limitations on continued reactor operation.

F.1

With the Division 1 250 V DC subsystem inoperable, the RCIC System and the RCIC DC powered PCIVs may be incapable of performing their intended functions and must be immediately declared inoperable. This declaration also requires entry

(continued)

BASES

ACTIONS

F.1 (continued)

into applicable Conditions and Required Actions of LCO 3.5.3, "Reactor Core Isolation Cooling (RCIC) System," and LCO 3.6.1.3, "Primary Containment Isolation Valves (PCIVs)."

G.1

Condition G corresponds to a level of degradation in the electrical power distribution system that causes a required safety function to be lost. When the inoperability of two or more inoperable electrical power distribution subsystems, in combination, result in the loss of a required function, the plant is in a condition outside the accident analysis. Therefore, no additional time is justified for continued operation. LCO 3.0.3 must be entered immediately to commence a controlled shutdown. The term "in combination" means that the loss of function must result from the inoperability of two or more AC and DC electrical power distribution subsystems; a loss of function solely due to a single AC or DC electrical power distribution subsystem inoperability even with another AC or DC electrical power distribution subsystem concurrently inoperable, does not require entry into Condition G. In addition, for this Action, Division 3 is considered redundant to Division 1 and 2 ECCS.

SURVEILLANCE
REQUIREMENTS

SR 3.8.7.1

Meeting this Surveillance verifies that the AC and DC electrical power distribution systems are functioning properly, with the correct circuit breaker alignment. The correct breaker alignment ensures the appropriate separation and independence of the electrical divisions is maintained, and the appropriate voltage is available to each required bus. The verification of proper voltage availability on the buses ensures that the required voltage is readily available for motive as well as control functions for critical system loads connected to these buses. The 7 day Frequency takes into account the redundant capability of the AC and DC electrical power distribution subsystems, and other indications available in the control room that alert the operator to subsystem malfunctions.

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BASES (continued)

- REFERENCES
1. UFSAR, Chapter 6.
 2. UFSAR, Chapter 15.
 3. Regulatory Guide 1.93, Revision 0, December 1974.
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Table B 3.8.7-1 (page 1 of 1)
Unit 1 AC and DC Electrical Power Distribution Systems

TYPE	VOLTAGE	DIVISION 1 ^(a)	DIVISION 2 ^{(a)(b)}	DIVISION 3 ^(a)
AC buses	4160 V	141Y	142Y	143
	480 V	135X and 135Y MCCs 135X-1, 135X-2, 135X-3, 135Y-1, and 135Y-2	136X and 136Y MCCS 136X-1, 136X-2, 136X-3, 136Y-1, and 136Y-2	MCC 143-1
	120 V	Distribution Panels in 480V MCCS 135X-1, 135X-2, 135X-3, and 135Y-1	Distribution Panels in 480V MCCS 136X-1, 136X-2, 136X-3, and 136Y-2	Distribution Panels in 480V MCC 143-1
DC buses	250 V	MCC 121Y		
	125 V	Distribution Panel 111Y	Distribution Panel 112Y	Distribution Panel 113

- (a) Each division of the AC and DC electrical power distribution systems is a subsystem.
- (b) OPERABILITY requirements of the opposite unit's Division 2 AC and DC electrical power distribution subsystems require OPERABILITY of all the opposite unit's Division 2 4160 VAC, 480 VAC, 120 VAC, and 125 VDC buses listed in the Unit 2 Table.

Table B 3.8.7-2 (page 1 of 1)
Unit 2 AC and DC Electrical Power Distribution Systems

TYPE	VOLTAGE	DIVISION 1 ^(a)	DIVISION 2 ^{(a)(b)}	DIVISION 3 ^(a)
AC buses	4160 V	241Y	242Y	243
	480 V	235X and 235Y MCCs 235X-1, 235X-2, 235X-3, 235Y-1, and 235Y-2	236X and 236Y MCCs 236X-1, 236X-2, 236X-3, 236Y-1, and 236Y-2	MCC 243-1
	120 V	Distribution Panels in 480V MCCs 235X-1, 235X-2, 235X-3, and 235Y-1	Distribution Panels in 480V MCCs 236X-1, 236X-2, 236X-3, and 236Y-2	Distribution Panels in 480V MCC 243-1
DC buses	250 V	MCC 221Y		
	125 V	Distribution Panel 211Y	Distribution Panel 212Y	Distribution Panel 213

(a) Each division of the AC and DC electrical power distribution systems is a subsystem.

(b) OPERABILITY requirements of the opposite unit's Division 2 AC and DC electrical power distribution subsystems require OPERABILITY of all the opposite unit's Division 2 4160 VAC, 480 VAC, 120 VAC, and 125 VDC buses listed in the Unit 1 Table.

B 3.8 ELECTRICAL POWER SYSTEMS

B 3.8.8 Distribution Systems - Shutdown

BASES

BACKGROUND A description of the AC and DC electrical power distribution systems is provided in the Bases for LCO 3.8.7, "Distribution Systems - Operating."

APPLICABLE SAFETY ANALYSES The initial conditions of Design Basis Accident and transient analyses in the UFSAR, Chapter 6 (Ref. 1) and Chapter 15 (Ref. 2), assume Engineered Safety Feature (ESF) systems are OPERABLE. The AC and DC electrical power distribution systems are designed to provide sufficient capacity, capability, redundancy, and reliability to ensure the availability of necessary power to ESF systems so that the fuel, Reactor Coolant System, and containment design limits are not exceeded.

The OPERABILITY of the AC and DC electrical power distribution system is consistent with the initial assumptions of the accident analyses and the requirements for the supported systems' OPERABILITY.

The OPERABILITY of the minimum AC and DC electrical power sources and associated power distribution subsystems during MODES 4 and 5, and during movement of irradiated fuel assemblies in the secondary containment ensures that:

- a. The facility can be maintained in the shutdown or refueling condition for extended periods;
- b. Sufficient instrumentation and control capability is available for monitoring and maintaining the unit status; and
- c. Adequate power is provided to mitigate events postulated during shutdown, such as an inadvertent draindown of the vessel or a fuel handling accident.

The AC and DC electrical power distribution systems satisfy Criterion 3 of 10 CFR 50.36(c)(2)(ii).

(continued)

BASES (continued)

LCO Various combinations of subsystems, equipment, and components are required OPERABLE by other LCOs, depending on the specific plant condition. Implicit in those requirements is the required OPERABILITY of necessary support features. This LCO explicitly requires energization of the portions of the electrical distribution system, including the opposite unit Division 2 electrical distribution subsystem, necessary to support OPERABILITY of Technical Specifications' required systems, equipment, and components—both specifically addressed by their own LCOs, and implicitly required by the definition of OPERABILITY.

Maintaining these portions of the distribution system energized ensures the availability of sufficient power to operate the plant in a safe manner to mitigate the consequences of postulated events during shutdown (e.g., fuel handling accidents and inadvertent reactor vessel draindown).

APPLICABILITY The AC and DC electrical power distribution subsystems required to be OPERABLE in MODES 4 and 5 and during movement of irradiated fuel assemblies in the secondary containment provide assurance that:

- a. Systems to provide adequate coolant inventory makeup are available for the irradiated fuel in the core in case of an inadvertent draindown of the reactor vessel;
- b. Systems needed to mitigate a fuel handling accident are available;
- c. Systems necessary to mitigate the effects of events that can lead to core damage during shutdown are available; and
- d. Instrumentation and control capability is available for monitoring and maintaining the unit in a cold shutdown or refueling condition.

The AC and DC electrical power distribution subsystem requirements for MODES 1, 2, and 3 are covered in LCO 3.8.7.

(continued)

BASES (continued)

ACTIONS

LCO 3.0.3 is not applicable while in MODE 4 or 5. However, since irradiated fuel assembly movement can occur in MODE 1, 2, or 3, the ACTIONS have been modified by a Note stating that LCO 3.0.3 is not applicable. If moving irradiated fuel assemblies while in MODE 4 or 5, LCO 3.0.3 would not specify any action. If moving irradiated fuel assemblies while in MODE 1, 2, or 3, the fuel movement is independent of reactor operations. Entering LCO 3.0.3 while in MODE 1, 2, or 3 would require the unit to be shutdown, but would not require immediate suspension of movement of irradiated fuel assemblies. The Note to the ACTIONS, "LCO 3.0.3 is not applicable," ensures that the actions for immediate suspension of irradiated fuel assembly movement are not postponed due to entry into LCO 3.0.3.

A.1, A.2.1, A.2.2, A.2.3, A.2.4, and A.2.5

Although redundant required features may require redundant divisions of electrical power distribution subsystems to be OPERABLE, one OPERABLE distribution subsystem division may be capable of supporting sufficient required features to allow continuation of CORE ALTERATIONS, fuel movement, and operations with a potential for draining the reactor vessel. By allowing the option to declare required features associated with an inoperable distribution subsystem inoperable, appropriate restrictions are implemented in accordance with the affected distribution subsystem LCO's Required Actions. In many instances, this option may involve undesired administrative efforts. Therefore, the allowance for sufficiently conservative actions is made (i.e., to suspend CORE ALTERATIONS, movement of irradiated fuel assemblies in the secondary containment and any activities that could result in inadvertent draining of the reactor vessel).

Suspension of these activities shall not preclude completion of actions to establish a safe conservative condition. These actions minimize the probability of the occurrence of postulated events. It is further required to immediately initiate action to restore the required AC and DC electrical power distribution subsystems and to continue this action until restoration is accomplished in order to provide the necessary power to the plant safety systems.

(continued)

BASES

ACTIONS

A.1, A.2.1, A.2.2, A.2.3, A.2.4, and A.2.5 (continued)

Notwithstanding performance of the above conservative Required Actions, a required residual heat removal—shutdown cooling (RHR-SDC) subsystem may be inoperable. In this case, Required Actions A.2.1 through A.2.4 do not adequately address the concerns relating to coolant circulation and heat removal. Pursuant to LCO 3.0.6, the RHR-SDC ACTIONS would not be entered. Therefore, Required Action A.2.5 is provided to direct declaring RHR-SDC inoperable, which results in taking the appropriate RHR-SDC ACTIONS.

The Completion Time of immediately is consistent with the required times for actions requiring prompt attention. The restoration of the required distribution subsystems should be completed as quickly as possible in order to minimize the time the plant safety systems may be without power.

SURVEILLANCE
REQUIREMENTS

SR 3.8.8.1

This Surveillance verifies that the AC and DC electrical power distribution subsystem is functioning properly, with the buses energized. The verification of proper voltage availability on the buses ensures that the required power is readily available for motive as well as control functions for critical system loads connected to these buses. The 7 day Frequency takes into account the redundant capability of the electrical power distribution subsystems, as well as other indications available in the control room that alert the operator to subsystem malfunctions.

REFERENCES

1. UFSAR, Chapter 6.
 2. UFSAR, Chapter 15.
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B 3.9 REFUELING OPERATIONS

B 3.9.1 Refueling Equipment Interlocks

BASES

BACKGROUND

Refueling equipment interlocks restrict the operation of the refueling equipment or the withdrawal of control rods to reinforce unit procedures in preventing the reactor from achieving criticality during refueling. The refueling interlock circuitry senses the conditions of the refueling equipment and the control rods. Depending on the sensed conditions, interlocks are actuated to prevent the operation of the refueling equipment or the withdrawal of control rods.

GDC 26 of 10 CFR 50, Appendix A, requires that one of the two required independent reactivity control systems be capable of holding the reactor core subcritical under cold conditions (Ref. 1). The control rods, when fully inserted, serve as the system capable of maintaining the reactor subcritical in cold conditions during all fuel movement activities and accidents.

The instrumentation provided to sense the position of the refueling platform, the loading of the refueling platform fuel grapple (main hoist), and the full insertion of all control rods is single failure proof in that no single failure can inhibit the interlocks. Additionally, inputs are provided for the loading of the refueling platform frame-mounted (auxiliary) hoist, the loading of the refueling platform trolley-mounted (monorail) hoist, and the loading of the service platform hoist. With the reactor mode switch in the shutdown or refuel position, the indicated conditions are combined in logic circuits to determine if all restrictions on refueling equipment operations and control rod insertion are satisfied.

A control rod not at its full-in position interrupts power to the refueling equipment to prevent operating the equipment over the reactor core when loaded with a fuel assembly. Conversely, the refueling equipment located over the core and loaded with fuel inserts a control rod withdrawal block in the Reactor Manual Control System to prevent withdrawing a control rod.

(continued)

BASES

BACKGROUND
(continued)

The refueling platform has two mechanical switches that open before the platform is physically located over the reactor vessel. The refueling platform hoists and the service platform hoist have switches that open when the hoists are loaded with fuel. The refueling interlocks use these indications to prevent operation of the refueling equipment with fuel loaded over the core whenever any control rod is withdrawn, or to prevent control rod withdrawal whenever fuel loaded refueling equipment is over the core (Ref. 2).

The hoist switches open at a load lighter than the weight of a single fuel assembly in water.

APPLICABLE
SAFETY ANALYSES

The refueling interlocks are explicitly assumed in the UFSAR analysis of the control rod removal error during refueling (Ref. 3). This analysis evaluates the consequences of control rod withdrawal during refueling. A prompt reactivity excursion during refueling could potentially result in fuel failure with subsequent release of radioactive material to the environment.

Criticality and, therefore, subsequent prompt reactivity excursions are prevented during the insertion of fuel, provided all control rods are fully inserted during the fuel insertion. The refueling interlocks accomplish this by preventing loading fuel into the core with any control rod withdrawn, or by preventing withdrawal of a rod from the core during fuel loading.

The refueling platform location switches activate at a point outside of the reactor core, such that, with a fuel assembly loaded and a control rod withdrawn, the fuel is not over the core.

Refueling equipment interlocks satisfy Criterion 3 of 10 CFR 50.36(c)(2)(ii).

LCO

To prevent criticality during refueling, the refueling interlocks associated with the reactor mode switch refuel position ensure that fuel assemblies are not loaded into the core with any control rod withdrawn.

(continued)

BASES

LCO
(continued) To prevent these conditions from developing, the all-rods-in, the refueling platform position, the refueling platform fuel grapple fuel-loaded, the refueling platform frame-mounted hoist fuel-loaded, the refueling platform trolley-mounted hoist fuel-loaded, and the service platform hoist fuel-loaded inputs are required to be OPERABLE when the associated equipment is in use for in-vessel fuel movement. These inputs are combined in logic circuits that provide refueling equipment or control rod blocks to prevent operations that could result in criticality during refueling operations.

APPLICABILITY In MODE 5, a prompt reactivity excursion could cause fuel damage and subsequent release of radioactive material to the environment. The refueling equipment interlocks protect against prompt reactivity excursions during MODE 5. The interlocks are only required to be OPERABLE during in-vessel fuel movement with refueling equipment associated with the interlocks when the reactor mode switch is in the refuel position. The interlocks are not required when the reactor mode switch is in the shutdown position since a control rod block (LCO 3.3.2.1, "Control Rod Block Instrumentation") ensures control rod withdrawals cannot occur simultaneously with in-vessel fuel movements.

In MODES 1, 2, 3, and 4, the reactor pressure vessel head is on, and no fuel loading activities are possible. Therefore, the refueling interlocks are not required to be OPERABLE in these MODES.

ACTIONS A.1, A.2.1, and A.2.2

With one or more of the required refueling equipment interlocks inoperable, the unit must be placed in a condition in which the LCO does not apply or is not necessary. This can be performed by ensuring fuel assemblies are not moved in the reactor vessel or by ensuring that the control rods are inserted and cannot be withdrawn. Therefore, Required Action A.1 requires that in-vessel fuel movement with the affected refueling equipment must be immediately suspended. This action ensures that operations are not performed with equipment that would potentially not be blocked from unacceptable operations (e.g., loading fuel into a cell with a control

(continued)

BASES

ACTIONS

A.1, A.2.1, and A.2.2 (continued)

rod withdrawn). Suspension of in-vessel fuel movement shall not preclude completion of movement of a component to a safe position. Alternately, Required Actions A.2.1 and A.2.2 require that a control rod withdrawal block be inserted and that all control rods are subsequently verified to be fully inserted. Required Action A.2.1 ensures that no control rods can be withdrawn. This action ensures that control rods cannot be inappropriately withdrawn since an electrical or hydraulic block to control rod withdrawal is in place. Required Action A.2.2 is normally performed after placing the rod withdrawal block in effect and provides a verification that all control rods are fully inserted. Like Required Action A.1, Required Actions A.2.1 and A.2.2 ensure that unacceptable operations are prohibited (e.g., loading fuel into a core cell with the control rod withdrawn).

SURVEILLANCE
REQUIREMENTS

SR 3.9.1.1

Performance of a CHANNEL FUNCTIONAL TEST demonstrates each required refueling equipment interlock will function properly when a simulated or actual signal indicative of a required condition is injected into the logic. A successful test of the required contact(s) of a channel relay may be performed by the verification of the change of state of a single contact of the relay. This clarifies what is an acceptable CHANNEL FUNCTIONAL TEST of a relay. This is acceptable because all of the other required contacts of the relay are verified by other Technical Specifications and non-Technical Specifications tests at least once per refueling interval with applicable extensions.

The 7 day Frequency is based on engineering judgment and is considered adequate in view of other indications of refueling interlocks and their associated input status that are available to unit operations personnel.

REFERENCES

1. 10 CFR 50, Appendix A, GDC 26.
 2. UFSAR, Section 7.7.13.
 3. UFSAR, Section 15.4.1.1.
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B 3.9 REFUELING OPERATIONS

B 3.9.2 Refuel Position One-Rod-Out Interlock

BASES

BACKGROUND

The refuel position one-rod-out interlock restricts the movement of control rods to reinforce unit procedures that prevent the reactor from becoming critical during refueling operations. During refueling operations, no more than one control rod is permitted to be withdrawn.

GDC 26 of 10 CFR 50, Appendix A, requires that one of the two required independent reactivity control systems be capable of holding the reactor core subcritical under cold conditions (Ref. 1). The control rods serve as the system capable of maintaining the reactor subcritical in cold conditions.

The refuel position one-rod-out interlock prevents the selection of a second control rod for movement when any other control rod is not fully inserted (Ref. 2). It is a logic circuit that has redundant channels. It uses the all-rods-in signal (from the control rod full-in position indicators discussed in LCO 3.9.4, "Control Rod Position Indication") and a rod selection signal (from the Reactor Manual Control System).

This Specification ensures that the performance of the refuel position one-rod-out interlock in the event of a Design Basis Accident meets the assumptions used in the safety analysis of Reference 3.

APPLICABLE
SAFETY ANALYSES

The refuel position one-rod-out interlock is explicitly assumed in the UFSAR analysis of the control rod removal error during refueling (Ref. 3). This analysis evaluates the consequences of control rod withdrawal during refueling. A prompt reactivity excursion during refueling could potentially result in fuel failure with subsequent release of radioactive material to the environment.

The refuel position one-rod-out interlock and adequate SDM (LCO 3.1.1, "SHUTDOWN MARGIN (SDM)") prevent criticality by preventing withdrawal of more than one control rod. With

(continued)

BASES

APPLICABLE
SAFETY ANALYSES
(continued)

one control rod withdrawn, the core will remain subcritical, thereby preventing any prompt critical excursion.

The refuel position one-rod-out interlock satisfies Criterion 3 of 10 CFR 50.36(c)(2)(ii).

LCO

To prevent criticality during MODE 5, the refuel position one-rod-out interlock ensures no more than one control rod may be withdrawn. Both channels of the refuel position one-rod-out interlock are required to be OPERABLE and the reactor mode switch must be locked in the refuel position to support the OPERABILITY of these channels.

APPLICABILITY

In MODE 5, with the reactor mode switch in the refuel position, the OPERABLE refuel position one-rod-out interlock provides protection against prompt reactivity excursions.

In MODES 1, 2, 3, and 4, the refuel position one-rod-out interlock is not required to be OPERABLE and is bypassed. In MODES 1 and 2, the Reactor Protection System (LCO 3.3.1.1, "Reactor Protection System (RPS) Instrumentation") and the control rods (LCO 3.1.3, "Control Rod OPERABILITY") provide mitigation of potential reactivity excursions. In MODES 3 and 4, with the reactor mode switch in the shutdown position, a control rod block (LCO 3.3.2.1, "Control Rod Block Instrumentation") ensures all control rods are inserted, thereby preventing criticality during shutdown conditions.

ACTIONS

A.1 and A.2

With the refuel position one-rod-out interlock inoperable, the refueling interlocks are not capable of preventing more than one control rod from being withdrawn. This condition may lead to criticality.

Control rod withdrawal must be immediately suspended, and action must be immediately initiated to fully insert all insertable control rods in core cells containing one or more fuel assemblies. Action must continue until all such control rods are fully inserted. Control rods in core cells containing no fuel assemblies do not affect the reactivity of the core and, therefore, do not have to be inserted.

(continued)

BASES (continued)

SURVEILLANCE
REQUIREMENTS

SR 3.9.2.1

Proper functioning of the refueling position one-rod-out interlock requires the reactor mode switch to be in Refuel. During control rod withdrawal in MODE 5, improper positioning of the reactor mode switch could, in some instances, allow improper bypassing of required interlocks. Therefore, this Surveillance imposes an additional level of assurance that the refueling position one-rod-out interlock will be OPERABLE when required. By "locking" the reactor mode switch in the proper position (i.e., removing the reactor mode switch key from the console while the reactor mode switch is positioned in refuel), an additional administrative control is in place to preclude operator errors from resulting in unanalyzed operation.

The Frequency of 12 hours is sufficient in view of other administrative controls utilized during refueling operations to ensure safe operation.

SR 3.9.2.2

Performance of a CHANNEL FUNCTIONAL TEST on each channel demonstrates the associated refuel position one-rod-out interlock will function properly when a simulated or actual signal indicative of a required condition is injected into the logic. A successful test of the required contact(s) of a channel relay may be performed by the verification of the change of state of a single contact of the relay. This clarifies what is an acceptable CHANNEL FUNCTIONAL TEST of a relay. This is acceptable because all of the other required contacts of the relay are verified by other Technical Specifications and non-Technical Specifications tests at least once per refueling interval with applicable extensions. The 7 day Frequency is considered adequate because of demonstrated circuit reliability, procedural controls on control rod withdrawals, and visual indications available in the control room to alert the operator of control rods not fully inserted. To perform the required testing, the applicable condition must be entered (i.e., a control rod must be withdrawn from its full-in position). Therefore, SR 3.9.2.2 has been modified by a Note that states the CHANNEL FUNCTIONAL TEST is not required to be performed until 1 hour after any control rod is withdrawn.

(continued)

BASES (continued)

- REFERENCES
1. 10 CFR 50, Appendix A, GDC 26.
 2. UFSAR, Section 7.7.13.
 3. UFSAR, Section 15.4.1.1.
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B 3.9 REFUELING OPERATIONS

B 3.9.3 Control Rod Position

BASES

BACKGROUND Control rods provide the capability to maintain the reactor subcritical under all conditions and to limit the potential amount and rate of reactivity increase caused by a malfunction in the Control Rod Drive System. During refueling, movement of control rods is limited by the refueling interlocks (LCO 3.9.1, "Refueling Equipment Interlocks" and LCO 3.9.2, "Refuel Position One-Rod-Out Interlock") or the control rod block with the reactor mode switch in the shutdown position (LCO 3.3.2.1, "Control Rod Block Instrumentation").

GDC 26 of 10 CFR 50, Appendix A, requires that one of the two required independent reactivity control systems be capable of holding the reactor core subcritical under cold conditions (Ref. 1). The control rods serve as the system capable of maintaining the reactor subcritical in cold conditions.

The refueling interlocks allow a single control rod to be withdrawn at any time unless fuel is being loaded into the core. To preclude loading fuel assemblies into the core with a control rod withdrawn, all control rods must be fully inserted. This prevents the reactor from achieving criticality during refueling operations.

APPLICABLE SAFETY ANALYSES Prevention and mitigation of prompt reactivity excursions during refueling are provided by the refueling interlocks (LCO 3.9.1 and LCO 3.9.2), the SDM (LCO 3.1.1, "SHUTDOWN MARGIN (SDM)"), the intermediate range monitor neutron flux scram (LCO 3.3.1.1, "Reactor Protection System (RPS) Instrumentation"), and the control rod block instrumentation (LCO 3.3.2.1).

The safety analysis of the control rod removal error during refueling in the UFSAR (Ref. 2) assumes the functioning of the refueling interlocks and adequate SDM. Additionally, prior to fuel reload, all control rods must be fully inserted to minimize the probability of an inadvertent criticality.

(continued)

BASES

APPLICABLE SAFETY ANALYSES (continued) Control rod position satisfies Criterion 3 of 10 CFR 50.36(c)(2)(ii).

LCO All control rods must be fully inserted during applicable refueling conditions to minimize the probability of an inadvertent criticality during refueling.

APPLICABILITY During MODE 5, loading fuel into core cells with control rods withdrawn may result in inadvertent criticality. Therefore, the control rods must be inserted before loading fuel into a core cell. All control rods must be inserted before loading fuel to ensure that a fuel loading error does not result in loading fuel into a core cell with the control rod withdrawn.

In MODES 1, 2, 3, and 4, the reactor pressure vessel head is on, and no fuel loading activities are possible. Therefore, this Specification is not applicable in these MODES.

ACTIONS

A.1

With all control rods not fully inserted during the applicable conditions, an inadvertent criticality could occur that is not analyzed in the UFSAR. All fuel loading operations must be immediately suspended. Suspension of these activities shall not preclude completion of movement of a component to a safe position.

SURVEILLANCE REQUIREMENTS

SR 3.9.3.1

During refueling, to ensure that the reactor remains subcritical, all control rods must be fully inserted prior to and during fuel loading. Periodic checks of the control rod position ensure this condition is maintained.

The 12 hour Frequency takes into consideration the procedural controls on control rod movement during refueling as well as the redundant functions of the refueling interlocks.

(continued)

BASES (continued)

- REFERENCES
1. 10 CFR 50, Appendix A, GDC 26.
 2. UFSAR, Section 15.4.1.1.
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B 3.9 REFUELING OPERATIONS

B 3.9.4 Control Rod Position Indication

BASES

BACKGROUND The full-in position indication channel for each control rod provides information necessary to the refueling interlocks to prevent inadvertent criticalities during refueling operations. During refueling, the refueling interlocks (LCO 3.9.1, "Refueling Equipment Interlocks" and LCO 3.9.2, "Refuel Position One-Rod-Out Interlock") use the full-in position indication channel to limit the operation of the refueling equipment and the movement of the control rods. Three full-in position indication detectors are provided for each control rod (reed switches S00 and S52 provide indication for full-in and switch S51 provides indication for beyond full-in). All three full-in position detectors provide input to the all-rods-in logic. The three switches are wired in parallel, such that, if any one of the three full-in position indication detectors indicates full-in, the all-rods-in logic will receive a full-in signal for that control rod. Therefore, each control rod is considered to have only one "full-in" position indication channel. The absence of the full-in position indication channel signal for any control rod removes the all-rods-in permissive for the refueling equipment interlocks and prevents fuel loading. Also, this condition causes the refuel position one-rod-out interlock to not allow the selection of any other control rod. The all-rods-in logic provides two signals, one to each of the two Reactor Manual Control System rod block logic circuits.

GDC 26 of 10 CFR 50, Appendix A, requires that one of the two required independent reactivity control systems be capable of holding the reactor core subcritical under cold conditions (Ref. 1). The control rods serve as the system capable of maintaining the reactor subcritical in cold conditions.

APPLICABLE SAFETY ANALYSES Prevention and mitigation of prompt reactivity excursions during refueling are provided by the refueling interlocks (LCO 3.9.1 and LCO 3.9.2), the SDM (LCO 3.1.1, "SHUTDOWN MARGIN (SDM)"), the intermediate range monitor neutron flux

(continued)

BASES

APPLICABLE SAFETY ANALYSES (continued) scram (LCO 3.3.1.1, "Reactor Protection System (RPS) Instrumentation"), and the control rod block instrumentation (LCO 3.3.2.1, "Control Rod Block Instrumentation").

The safety analysis for the control rod removal error during refueling (Ref. 2) assumes the functioning of the refueling interlocks and adequate SDM. The full-in position indication channel is required to be OPERABLE so that the refueling interlocks can ensure that fuel cannot be loaded with any control rod withdrawn and that no more than one control rod can be withdrawn at a time.

Control rod position indication satisfies Criterion 3 of 10 CFR 50.36(c)(2)(ii).

LCO The control rod full-in position indication channel for each control rod must be OPERABLE to provide the required inputs to the refueling interlocks. A channel is OPERABLE if it provides correct position indication to the refueling equipment interlock all-rods-in logic (LCO 3.9.1) and the refuel position one-rod-out interlock logic (LCO 3.9.2).

APPLICABILITY During MODE 5, the control rods must have OPERABLE full-in position indication channels to ensure the applicable refueling interlocks will be OPERABLE.

In MODES 1 and 2, requirements for control rod position are specified in LCO 3.1.3, "Control Rod OPERABILITY." In MODES 3 and 4, with the reactor mode switch in the shutdown position, a control rod block (LCO 3.3.2.1) ensures all control rods are inserted, thereby preventing criticality during shutdown conditions.

ACTIONS A Note has been provided to modify the ACTIONS related to control rod position indication channels. Section 1.3, Completion Times, specifies that once a Condition has been entered, subsequent divisions, subsystems, components, or variables expressed in the Condition, discovered to be inoperable or not within limits, will not result in separate entry into the Condition. Section 1.3 also specifies that Required Actions of the Condition continue to apply for each additional failure, with Completion Times based on initial

(continued)

BASES

ACTIONS
(continued)

entry into the Condition. However, the Required Actions for inoperable control rod position indication channels provide appropriate compensatory measures for separate inoperable channels. As such, this Note has been provided, which allows separate Condition entry for each inoperable required control rod position indication channel.

A.1.1, A.1.2, A.1.3, A.2.1, and A.2.2

With one or more required full-in position indication channels inoperable, compensating actions must be taken to protect against potential reactivity excursions from fuel assembly insertions or control rod withdrawals. This may be accomplished by immediately suspending in-vessel fuel movement and control rod withdrawal, and immediately initiating action to fully insert all insertable control rods in core cells containing one or more fuel assemblies. Actions must continue until all insertable control rods in core cells containing one or more fuel assemblies are fully inserted. Control rods in core cells containing no fuel assemblies do not affect the reactivity of the core and, therefore, do not have to be inserted. Suspension of in-vessel fuel movements and control rod withdrawal shall not preclude moving a component to a safe position.

Alternatively, actions may be immediately initiated to fully insert the control rod(s) associated with the inoperable full-in position indicators(s) and to disarm (electrically or hydraulically) the drive(s) to ensure that the control rod is not withdrawn. A control rod can be hydraulically disarmed by closing the drive water and exhaust water isolation valves. A control rod can be electrically disarmed by disconnecting power from all four directional control valve solenoids. Actions must continue until all associated control rods are fully inserted and drives are disarmed. Under these conditions (control rod fully inserted and disarmed), an inoperable full-in channel may be bypassed to allow refueling operations to proceed. An alternate method must be used to ensure the control rod is fully inserted.

(continued)

BASES (continued)

SURVEILLANCE
REQUIREMENTS

SR 3.9.4.1

The full-in position indication channels provide input to the one-rod-out interlock and other refueling interlocks that require an all-rods-in permissive. The interlocks are activated when the full-in position indication for any control rod is not present, since this indicates that all rods are not fully inserted. Therefore, testing of the full-in position indication channels is performed to ensure that when a control rod is withdrawn, the full-in position indication is not present. This is performed by verifying both the absence of a full-in position indication and the absence of an "00" indication for the control rod on the four control rod group display, when the control rod is not full-in. The full-in position indication channel is considered inoperable even with the control rod fully inserted, if it would continue to indicate full-in with the control rod withdrawn. Performing the SR each time a control rod is withdrawn from the full-in position is considered adequate because of the procedural controls on control rod withdrawals and the visual indications available in the control room to alert the operator to control rods not fully inserted.

REFERENCES

1. 10 CFR 50, Appendix A, GDC 26.
 2. UFSAR, Section 15.4.1.1.
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B 3.9 REFUELING OPERATIONS

B 3.9.5 Control Rod OPERABILITY – Refueling

BASES

BACKGROUND Control rods are components of the Control Rod Drive (CRD) System, the primary reactivity control system for the reactor. In conjunction with the Reactor Protection System, the CRD System provides the means for the reliable control of reactivity changes during refueling operation. In addition, the control rods provide the capability to maintain the reactor subcritical under all conditions and to limit the potential amount and rate of reactivity increase caused by a malfunction in the CRD System.

GDC 26 of 10 CFR 50, Appendix A, requires that one of the two required independent reactivity control systems be capable of holding the reactor core subcritical under cold conditions (Ref. 1). The CRD System is the system capable of maintaining the reactor subcritical in cold conditions.

APPLICABLE SAFETY ANALYSES Prevention and mitigation of prompt reactivity excursions during refueling are provided by refueling interlocks (LCO 3.9.1, "Refueling Equipment Interlocks" and LCO 3.9.2, "Refuel Position One-Rod-Out Interlock"), the SDM (LCO 3.1.1, "SHUTDOWN MARGIN (SDM)"), the intermediate range monitor neutron flux scram (LCO 3.3.1.1, "Reactor Protection System (RPS) Instrumentation"), and the control rod block instrumentation (LCO 3.3.2.1, "Control Rod Block Instrumentation").

The safety analysis for the control rod removal error during refueling (Ref. 2) evaluates the consequences of control rod withdrawal during refueling. A prompt reactivity excursion during refueling could potentially result in fuel failure with subsequent release of radioactive material to the environment. Control rod scram provides protection should a prompt reactivity excursion occur.

Control rod OPERABILITY during refueling satisfies Criterion 3 of 10 CFR 50.36(c)(2)(ii).

(continued)

BASES (continued)

LCO Each withdrawn control rod must be OPERABLE. The withdrawn control rod is considered OPERABLE if the scram accumulator pressure is ≥ 940 psig and the control rod is capable of being automatically inserted upon receipt of a scram signal. Inserted control rods have already completed their reactivity control function, and therefore, are not required to be OPERABLE.

APPLICABILITY During MODE 5, withdrawn control rods must be OPERABLE to ensure that when a scram occurs the control rods will insert and provide the required negative reactivity to maintain the reactor subcritical.

For MODES 1 and 2, control rod requirements are found in LCO 3.1.2, "Reactivity Anomalies," LCO 3.1.3, "Control Rod OPERABILITY," LCO 3.1.4, "Control Rod Scram Times," and LCO 3.1.5, "Control Rod Scram Accumulators." During MODES 3 and 4, control rods are not able to be withdrawn since the reactor mode switch is in shutdown and a control rod block is applied. This provides adequate requirements for control rod OPERABILITY during these conditions.

ACTIONS

A.1

With one or more withdrawn control rods inoperable, action must be immediately initiated to fully insert the inoperable control rod(s). Inserting the control rod(s) ensures that the shutdown and scram capabilities are not adversely affected. Actions must continue until the inoperable control rod(s) is fully inserted.

SURVEILLANCE
REQUIREMENTS

SR 3.9.5.1 and SR 3.9.5.2

During MODE 5, the OPERABILITY of control rods is primarily required to ensure that a withdrawn control rod will automatically insert if a signal requiring a reactor shutdown occurs. Because no explicit analysis exists for automatic shutdown during refueling, the shutdown function is satisfied if the withdrawn control rod is capable of automatic insertion and the associated CRD scram accumulator pressure is ≥ 940 psig.

(continued)

BASES

SURVEILLANCE
REQUIREMENTS

SR 3.9.5.1 and SR 3.9.5.2 (continued)

The 7 day Frequency takes into consideration equipment reliability, procedural controls over the scram accumulators, and control room alarms and indicating lights that indicate low accumulator charge pressures.

SR 3.9.5.1 is modified by a Note that allows 7 days after withdrawal of the control rod to perform the Surveillance. This acknowledges that the control rod must first be withdrawn before performance of the Surveillance, and therefore avoids potential conflicts with SR 3.0.1.

REFERENCES

1. 10 CFR 50, Appendix A, GDC 26.
 2. UFSAR, Section 15.4.1.1.
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B 3.9 REFUELING OPERATIONS

B 3.9.6 Reactor Pressure Vessel (RPV) Water Level - Irradiated Fuel

BASES

BACKGROUND The movement of irradiated fuel assemblies within the RPV requires a minimum water level of 22 ft above the top of the RPV flange. During refueling, this maintains a sufficient water level in the reactor vessel cavity and spent fuel storage pool. Sufficient water is necessary to retain iodine fission product activity in the water in the event of a fuel handling accident (Refs. 1 and 2). Sufficient iodine activity would be retained to limit offsite doses from the accident to < 25% of 10 CFR 100 limits, as provided by the guidance of Reference 3.

APPLICABLE SAFETY ANALYSES During movement of irradiated fuel assemblies the water level in the RPV is an initial condition design parameter in the analysis of a fuel handling accident in containment postulated by Regulatory Guide 1.25 (Ref. 1). A minimum water level of 23 ft (Regulatory Position C.1.c of Ref. 1) allows a decontamination factor of 100 (Regulatory Position C.1.g of Ref. 1) to be used in the accident analysis for iodine. This relates to the assumption that 99% of the total iodine released from the pellet to cladding gap of all the dropped fuel assembly rods is retained by the refueling cavity water. The fuel pellet to cladding gap is assumed to contain 10% of the total fuel rod iodine inventory (Ref. 1).

Analysis of the fuel handling accident inside containment is described in Reference 2. With a minimum water level of 22 ft (a decontamination factor of 100 is still expected at a water level as low as 22 ft) and a minimum decay time of 24 hours prior to fuel handling, the analysis and test programs demonstrate that the iodine release due to a postulated fuel handling accident is adequately captured by the water, and that offsite doses are maintained within allowable limits (Ref. 4). While the worst case assumptions include the dropping of the irradiated fuel assembly being handled onto the reactor core, the possibility exists of the dropped assembly striking the RPV flange and releasing fission products. Therefore, the minimum depth for water

(continued)

BASES

APPLICABLE
SAFETY ANALYSES
(continued)

coverage to ensure acceptable radiological consequences is specified from the RPV flange. Since the worst case event results in failed fuel assemblies seated in the core, as well as the dropped assembly, dropping an assembly on the RPV flange will result in reduced releases of fission gases.

RPV water level satisfies Criterion 2 of 10 CFR 50.36(c)(2)(ii).

LCO

A minimum water level of 22 ft above the top of the RPV flange is required to ensure that the radiological consequences of a postulated fuel handling accident are within acceptable limits, as provided by the guidance of Reference 3.

APPLICABILITY

LCO 3.9.6 is applicable when moving irradiated fuel assemblies within the RPV. The LCO minimizes the possibility of a fuel handling accident in containment that is beyond the assumptions of the safety analysis. If irradiated fuel is not present within the RPV, there can be no significant radioactivity release as a result of a postulated fuel handling accident. Requirements for handling of new fuel assemblies or control rods (where water depth to the RPV flange is not of concern) are covered by LCO 3.9.7, "RPV Water Level - New Fuel or Control Rods." Requirements for fuel handling accidents in the spent fuel storage pool are covered by LCO 3.7.8, "Spent Fuel Storage Pool Water Level."

ACTIONS

A.1

If the water level is < 22 ft above the top of the RPV flange, all operations involving movement of irradiated fuel assemblies within the RPV shall be suspended immediately to ensure that a fuel handling accident cannot occur. The suspension of irradiated fuel movement shall not preclude completion of movement of a component to a safe position.

(continued)

BASES (continued)

SURVEILLANCE
REQUIREMENTS

SR 3.9.6.1

Verification of a minimum water level of 22 ft above the top of the RPV flange ensures that the design basis for the postulated fuel handling accident analysis during refueling operations is met. Water at the required level limits the consequences of damaged fuel rods, which are postulated to result from a fuel handling accident in containment (Ref. 2).

The Frequency of 24 hours is based on engineering judgment and is considered adequate in view of the large volume of water and the normal procedural controls on valve positions, which make significant unplanned level changes unlikely.

REFERENCES

1. Regulatory Guide 1.25, March 23, 1972.
 2. UFSAR, Section 15.7.4.
 3. NUREG-0800, Section 15.7.4.
 4. 10 CFR 100.11.
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B 3.9 REFUELING OPERATIONS

B 3.9.7 Reactor Pressure Vessel (RPV) Water Level - New Fuel or Control Rods

BASES

BACKGROUND The movement of new fuel assemblies or handling of control rods within the RPV when fuel assemblies seated within the reactor vessel are irradiated requires a minimum water level of 23 ft above the top of irradiated fuel assemblies seated within the RPV. During refueling, this maintains a sufficient water level above the irradiated fuel. Sufficient water is necessary to retain iodine fission product activity in the water in the event of a fuel handling accident (Refs. 1 and 2). Sufficient iodine activity would be retained to limit offsite doses from the accident to < 25% of 10 CFR 100 limits, as provided by the guidance of Reference 3.

APPLICABLE SAFETY ANALYSES During movement of new fuel assemblies or handling of control rods over irradiated fuel assemblies, the water level in the RPV is an initial condition design parameter in the analysis of a fuel handling accident in containment postulated by Regulatory Guide 1.25 (Ref. 1). A minimum water level of 23 ft (Regulatory Position C.1.c of Ref. 1) allows a decontamination factor of 100 (Regulatory Position C.1.g of Ref. 1) to be used in the accident analysis for iodine. This relates to the assumption that 99% of the total iodine released from the pellet to cladding gap of all the dropped fuel assembly rods is retained by the refueling cavity water. The fuel pellet to cladding gap is assumed to contain 10% of the total fuel rod iodine inventory (Ref. 1).

Analysis of the fuel handling accident inside containment is described in Reference 2. With a minimum water level of 23 ft and a minimum decay time of 24 hours prior to fuel handling, the analysis and test programs demonstrate that the iodine release due to a postulated fuel handling accident is adequately captured by the water, and that offsite doses are maintained within allowable limits (Ref. 4). The related assumptions include the worst case dropping of an irradiated fuel assembly onto the reactor core loaded with irradiated fuel assemblies.

(continued)

BASES

APPLICABLE SAFETY ANALYSES (continued) RPV water level satisfies Criterion 2 of 10 CFR 50.36(c)(2)(ii).

LCO A minimum water level of 23 ft above the top of irradiated fuel assemblies seated within the RPV is required to ensure that the radiological consequences of a postulated fuel handling accident are within acceptable limits, as provided by the guidance of Reference 3.

APPLICABILITY LCO 3.9.7 is applicable when moving new fuel assemblies or handling control rods (i.e., movement with other than the normal control rod drive) when irradiated fuel assemblies are seated within the RPV. The LCO minimizes the possibility of a fuel handling accident in containment that is beyond the assumptions of the safety analysis. If irradiated fuel is not present within the RPV, there can be no significant radioactivity release as a result of a postulated fuel handling accident. Requirements for fuel handling accidents in the spent fuel storage pool are covered by LCO 3.7.8, "Spent Fuel Storage Pool Water Level." Requirements for handling irradiated fuel over the RPV are covered by LCO 3.9.6, "Reactor Pressure Vessel (RPV) Water Level - Irradiated Fuel."

ACTIONS A.1
If the water level is < 23 ft above the top of irradiated fuel assemblies seated within the RPV, all operations involving movement of new fuel assemblies and handling of control rods within the RPV shall be suspended immediately to ensure that a fuel handling accident cannot occur. The suspension of fuel movement and control rod handling shall not preclude completion of movement of a component to a safe position.

(continued)

BASES (continued)

SURVEILLANCE
REQUIREMENTS

SR 3.9.7.1

Verification of a minimum water level of 23 ft above the top of the irradiated fuel assemblies seated within the RPV ensures that the design basis for the postulated fuel handling accident analysis during refueling operations is met. Water at the required level limits the consequences of damaged fuel rods, which are postulated to result from a fuel handling accident in containment (Ref. 2).

The Frequency of 24 hours is based on engineering judgment and is considered adequate in view of the large volume of water and the normal procedural controls on valve positions, which make significant unplanned level changes unlikely.

REFERENCES

1. Regulatory Guide 1.25, March 23, 1972.
 2. UFSAR, Section 15.7.4.
 3. NUREG-0800, Section 15.7.4.
 4. 10 CFR 100.11.
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B 3.9 REFUELING OPERATIONS

B 3.9.8 Residual Heat Removal (RHR) - High Water Level

BASES

BACKGROUND The purpose of the RHR System in MODE 5 is to remove decay heat and sensible heat from the reactor coolant, as required by GDC 34 (Ref. 1). Each of the two shutdown cooling loops of the RHR System can provide the required decay heat removal. Each loop consists of one motor driven pump, a heat exchanger, and associated piping and valves. Both loops have a common suction from the same recirculation loop. Each pump discharges the reactor coolant, after it has been cooled by circulation through the respective heat exchangers, to the reactor via the associated recirculation loop. The RHR heat exchangers transfer heat to the RHR Service Water (RHRSW) System. The RHR shutdown cooling mode is manually controlled.

In addition to the RHR subsystems, the volume of water above the reactor pressure vessel (RPV) flange provides a heat sink for decay heat removal.

APPLICABLE SAFETY ANALYSES With the unit in MODE 5, the RHR shutdown cooling subsystem is not required to mitigate any events or accidents evaluated in the safety analyses. The RHR shutdown cooling subsystem is required for removing decay heat to maintain the temperature of the reactor coolant.

The RHR System satisfies Criterion 4 of 10 CFR 50.36(c)(2)(ii).

LCO Only one RHR shutdown cooling subsystem is required to be OPERABLE and in operation in MODE 5 with irradiated fuel in the RPV and the water level \geq 22 ft above the RPV flange. Only one subsystem is required to be OPERABLE because the volume of water above the RPV flange provides backup decay heat removal capability.

An OPERABLE RHR shutdown cooling subsystem consists of an RHR pump, a heat exchanger, the necessary portions of the RHRSW System and Ultimate Heat Sink capable of providing

(continued)

BASES

LCO
(continued) cooling to the RHR heat exchanger, valves, piping,
 instruments, and controls to ensure an OPERABLE flow path.

Additionally, each RHR shutdown cooling subsystem is considered OPERABLE if it can be manually aligned (remote or local) in the shutdown cooling mode for removal of decay heat. Operation (either continuous or intermittent) of one subsystem can maintain and reduce the reactor coolant temperature as required. However, to ensure adequate core flow to allow for accurate average reactor coolant temperature monitoring, nearly continuous operation is required. A Note is provided to allow a 2 hour exception for the operating subsystem to not be in operation every 8 hours. This is permitted because the core heat generation can be low enough and the heatup rate slow enough to allow some changes to the RHR subsystem or other operations requiring RHR flow interruption.

APPLICABILITY One RHR shutdown cooling subsystem must be OPERABLE and in operation in MODE 5, with irradiated fuel in the RPV and with the water level \geq 22 ft above the top of the RPV flange, to provide decay heat removal. RHR shutdown cooling subsystem requirements in other MODES are covered by LCOs in Section 3.4, Reactor Coolant System (RCS). RHR shutdown cooling subsystem requirements in MODE 5, with irradiated fuel in the RPV and with the water level $<$ 22 ft above the RPV flange, are given in LCO 3.9.9, "Residual Heat Removal (RHR) - Low Water Level."

ACTIONS

A.1

With no RHR shutdown cooling subsystem OPERABLE, an alternate method of decay heat removal must be provided within 1 hour. In this condition, the volume of water above the RPV flange provides adequate capability to remove decay heat from the reactor core. However, the overall reliability is reduced because loss of water level could result in reduced decay heat removal capability. The 1 hour Completion Time is based on the decay heat removal function and the probability of a loss of the available decay heat removal capabilities. Furthermore, verification of the

(continued)

BASES

ACTIONS

A.1 (continued)

functional availability of the alternate method must be reconfirmed every 24 hours thereafter. This will ensure continued heat removal capability.

Alternate decay heat removal methods are available to the operators for review and preplanning in the unit operating procedures. The required cooling capacity of the alternate method should be ensured by verifying (by calculation or demonstration) its capability to maintain or reduce temperature. For example, this may include the use of the Fuel Pool Cooling System (operating with positive flow from the reactor cavity to the skimmer surge tank), the Reactor Water Cleanup System, or the Control Rod Drive System. The method used to remove the decay heat should be the most prudent choice based on unit conditions.

B.1, B.2, B.3, and B.4

If no RHR shutdown cooling subsystem is OPERABLE and an alternate method of decay heat removal is not available in accordance with Required Action A.1, actions shall be taken immediately to suspend operations involving an increase in reactor decay heat load by suspending the loading of irradiated fuel assemblies into the RPV.

Additional actions are required to minimize any potential fission product release to the environment. This includes ensuring secondary containment is OPERABLE; one standby gas treatment subsystem is OPERABLE; and secondary containment isolation capability is available in each associated penetration flow path not isolated that is assumed to be isolated to mitigate radioactive releases (i.e., one secondary containment isolation valve and associated instrumentation are OPERABLE or other acceptable administrative controls to assure isolation capability. These administrative controls consist of stationing a dedicated operator, who is in continuous communication with the control room, at the controls of the isolation device. In this way, the penetration can be rapidly isolated when a need for secondary containment isolation is indicated).

(continued)

BASES

ACTIONS

B.1, B.2, B.3, and B.4 (continued)

This may be performed as an administrative check, by examining logs or other information to determine whether the components are out of service for maintenance or other reasons. It is not necessary to perform the Surveillances needed to demonstrate the OPERABILITY of the components. If, however, any required component is inoperable, then it must be restored to OPERABLE status. In this case, a surveillance may need to be performed to restore the component to OPERABLE status. Actions must continue until all required components are OPERABLE.

C.1 and C.2

If no RHR shutdown cooling subsystem is in operation, an alternate method of coolant circulation is required to be established within 1 hour. The Completion Time is modified such that 1 hour is applicable separately for each occurrence involving a loss of coolant circulation.

During the period when the reactor coolant is being circulated by an alternate method (other than by the required RHR shutdown cooling subsystem), the reactor coolant temperature must be periodically monitored to ensure proper functioning of the alternate method. The once per hour Completion Time is deemed appropriate.

SURVEILLANCE
REQUIREMENTS

SR 3.9.8.1

This Surveillance demonstrates that the required RHR shutdown cooling subsystem is in operation and circulating reactor coolant in accordance with normal procedural requirements. The Frequency of 12 hours is sufficient in view of other visual and audible indications available to the operator for monitoring the RHR shutdown cooling subsystem in the control room.

REFERENCES

1. 10 CFR 50, Appendix A, GDC 34.
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B 3.9 REFUELING OPERATIONS

B 3.9.9 Residual Heat Removal (RHR) - Low Water Level

BASES

BACKGROUND The purpose of the RHR System in MODE 5 is to remove decay heat and sensible heat from the reactor coolant, as required by GDC 34 (Ref. 1). Each of the two shutdown cooling loops of the RHR System can provide the required decay heat removal. Each loop consists of one motor driven pump, a heat exchanger, and associated piping and valves. Both loops have a common suction from the same recirculation loop. Each pump discharges the reactor coolant, after it has been cooled by circulation through the respective heat exchangers, to the reactor via the associated recirculation loop. The RHR heat exchangers transfer heat to the RHR Service Water (RHRSW) System. The RHR shutdown cooling mode is manually controlled.

APPLICABLE SAFETY ANALYSES With the unit in MODE 5, the RHR shutdown cooling subsystems are not required to mitigate any events or accidents evaluated in the safety analyses. The RHR shutdown cooling subsystems are required for removing decay heat to maintain the temperature of the reactor coolant.

The RHR System satisfies Criterion 4 of 10 CFR 50.36(c)(2)(ii).

LCO In MODE 5 with irradiated fuel in the reactor pressure vessel (RPV) and with the water level < 22 ft above the RPV flange both RHR shutdown cooling subsystems must be OPERABLE and one RHR shutdown cooling subsystem must be in operation.

An OPERABLE RHR shutdown cooling subsystem consists of an RHR pump, a heat exchanger, the necessary portions of the RHRSW System and Ultimate Heat Sink capable of providing cooling to the RHR heat exchanger, valves, piping, instruments, and controls to ensure an OPERABLE flow path.

Additionally, each RHR shutdown cooling subsystem is considered OPERABLE if it can be manually aligned (remote or local) in the shutdown cooling mode for removal of decay

(continued)

BASES

LCO
(continued) heat. Operation (either continuous or intermittent) of one subsystem can maintain and reduce the reactor coolant temperature as required. However, to ensure adequate core flow to allow for accurate average reactor coolant temperature monitoring, nearly continuous operation is required. A Note is provided to allow a 2 hour exception for the operating subsystem to not be in operation every 8 hours. This is permitted because the core heat generation can be low enough and the heatup rate slow enough to allow some changes to the RHR subsystem or other operations requiring RHR flow interruption.

APPLICABILITY Two RHR shutdown cooling subsystems are required to be OPERABLE and one RHR shutdown cooling subsystem must be in operation in MODE 5, with irradiated fuel in the RPV and with the water level < 22 ft above the top of the RPV flange, to provide decay heat removal. RHR shutdown cooling subsystem requirements in other MODES are covered by LCOs in Section 3.4, Reactor Coolant System (RCS). RHR shutdown cooling subsystem requirements in MODE 5, with irradiated fuel in the RPV and the water level \geq 22 ft above the RPV flange, are given in LCO 3.9.8, "Residual Heat Removal (RHR) - High Water Level."

ACTIONS A.1

With one of the two RHR shutdown cooling subsystems inoperable, the remaining subsystem is capable of providing the required decay heat removal. However, the overall reliability is reduced. Therefore, an alternate method of decay heat removal must be provided. With both RHR shutdown cooling subsystems inoperable, an alternate method of decay heat removal must be provided in addition to that provided for the initial RHR shutdown cooling subsystem inoperability. This re-establishes backup decay heat removal capabilities, similar to the requirements of the LCO. The 1 hour Completion Time is based on the decay heat removal function and the probability of a loss of the available decay heat removal capabilities. Furthermore, verification of the functional availability of these alternate method(s) must be reconfirmed every 24 hours thereafter. This will ensure continued heat removal capability.

(continued)

BASES

ACTIONS

A.1 (continued)

Alternate decay heat removal methods are available to the operators for review and preplanning in the unit operating procedures. The required cooling capacity of the alternate method(s) should be ensured by verifying (by calculation or demonstration) their capability to maintain or reduce temperature. For example, this may include the use of the Fuel Pool Cooling System (operating with positive flow from the reactor cavity to the skimmer surge tank), the Reactor Water Cleanup System, or the Control Rod Drive System. The method used to remove decay heat should be the most prudent choice based on unit conditions.

Condition A is modified by a Note allowing separate Condition entry for each inoperable RHR shutdown cooling subsystem. This is acceptable since the Required Actions for this Condition provide appropriate compensatory actions for each inoperable RHR shutdown cooling subsystem. Complying with the Required Actions allow for continued operation. A subsequent inoperable RHR shutdown cooling subsystem is governed by subsequent entry into the Condition and application of the Required Actions.

B.1, B.2, and B.3

With the required decay heat removal subsystem(s) inoperable and the required alternate method(s) of decay heat removal not available in accordance with Required Action A.1, additional actions are required to minimize any potential fission product release to the environment. This includes ensuring secondary containment is OPERABLE; one standby gas treatment subsystem is OPERABLE; and secondary containment isolation capability is available in each associated penetration flow path not isolated that is assumed to be isolated to mitigate radioactive releases (i.e., one secondary containment isolation valve and associated instrumentation are OPERABLE or other acceptable administrative controls to assure isolation capability. These administrative controls consist of stationing a dedicated operator, who is in continuous communication with the control room, at the controls of the isolation device.

(continued)

BASES

ACTIONS B.1, B.2, and B.3 (continued)

In this way, the penetration can be rapidly isolated when a need for secondary containment isolation is indicated). This may be performed as an administrative check, by examining logs or other information to determine whether the components are out of service for maintenance or other reasons. It is not necessary to perform the Surveillances needed to demonstrate the OPERABILITY of the components. If, however, any required component is inoperable, then it must be restored to OPERABLE status. In this case, a surveillance may need to be performed to restore the component to OPERABLE status. Actions must continue until all required components are OPERABLE.

C.1 and C.2

If no RHR shutdown cooling subsystem is in operation, an alternate method of coolant circulation is required to be established within 1 hour. The Completion Time is modified such that the 1 hour is applicable separately for each occurrence involving a loss of coolant circulation.

During the period when the reactor coolant is being circulated by an alternate method (other than by the required RHR shutdown cooling subsystem), the reactor coolant temperature must be periodically monitored to ensure proper function of the alternate method. The once per hour Completion Time is deemed appropriate.

SURVEILLANCE
REQUIREMENTS

SR 3.9.9.1

This Surveillance demonstrates that one RHR shutdown cooling subsystem is in operation and circulating reactor coolant in accordance with normal procedural requirements. The Frequency of 12 hours is sufficient in view of other visual and audible indications available to the operator for monitoring the RHR shutdown cooling subsystem in the control room.

REFERENCES

1. 10 CFR 50, Appendix A, GDC 34.
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B 3.10 SPECIAL OPERATIONS

B 3.10.1 Reactor Mode Switch Interlock Testing

BASES

BACKGROUND The purpose of this Special Operations LCO is to permit operation of the reactor mode switch from one position to another to confirm certain aspects of associated interlocks during periodic tests and calibrations in MODES 3, 4, and 5.

The reactor mode switch is a conveniently located, multiposition, keylock switch provided to select the necessary scram functions for various plant conditions (Ref. 1). The reactor mode switch selects the appropriate trip relays for scram functions and provides appropriate bypasses. The mode switch positions and related scram interlock functions are summarized as follows:

- a. Shutdown—Initiates a reactor scram; bypasses main steam line isolation scram;
- b. Refuel—Selects Neutron Monitoring System (NMS) scram function for low neutron flux level operation (but does not disable the average power range monitor scram); bypasses main steam line isolation scram;
- c. Startup/Hot Standby—Selects NMS scram function for low neutron flux level operation (intermediate range monitors and average power range monitors); bypasses main steam line isolation scram; and
- d. Run—Selects NMS scram function for power range operation.

The reactor mode switch also provides interlocks for such functions as control rod blocks, scram discharge volume trip bypass, refueling interlocks, and main steam isolation valve isolations.

APPLICABLE SAFETY ANALYSES The purpose for reactor mode switch interlock testing is to prevent fuel failure by precluding reactivity excursions or core criticality.

(continued)

BASES

APPLICABLE
SAFETY ANALYSES
(continued)

The interlock functions of the shutdown and refuel positions of the reactor mode switch in MODES 3, 4, and 5 are provided to preclude reactivity excursions that could potentially result in fuel failure. Interlock testing that requires moving the reactor mode switch to other positions (run, or startup/hot standby) while in MODE 3, 4, or 5, requires administratively maintaining all control rods inserted and no other CORE ALTERATIONS in progress. With all control rods inserted in core cells containing one or more fuel assemblies and no CORE ALTERATIONS in progress, there are no credible mechanisms for unacceptable reactivity excursions during the planned interlock testing.

For postulated accidents, such as control rod removal error during refueling or loading of fuel with a control rod withdrawn, the accident analysis demonstrates that fuel failure will not occur (Ref. 2). The withdrawal of a single control rod will not result in criticality when adequate SDM is maintained. Also, loading fuel assemblies into the core with a single control rod withdrawn will not result in criticality, thereby preventing fuel failure.

As described in LCO 3.0.7, compliance with Special Operations LCOs is optional, and therefore no criteria of 10 CFR 50.36(c)(2)(ii) apply. Special Operations LCOs provide flexibility to perform certain operations by appropriately modifying requirements of other LCOs. A discussion of the criteria satisfied for the other LCOs is provided in their respective Bases.

LCO

As described in LCO 3.0.7, compliance with this Special Operations LCO is optional. MODES 3, 4, and 5 operations not specified in Table 1.1-1 can be performed in accordance with other Special Operations LCOs (i.e., LCO 3.10.2, "Single Control Rod Withdrawal—Hot Shutdown," LCO 3.10.3, "Single Control Rod Withdrawal—Cold Shutdown," and LCO 3.10.7, "SDM Test—Refueling") without meeting this LCO or its ACTIONS. If any testing is performed that involves the reactor mode switch interlocks and requires repositioning beyond that specified in Table 1.1-1 for the current MODE of operation, the testing can be performed, provided all interlock functions potentially defeated are

(continued)

BASES

LCO
(continued) administratively controlled. In MODES 3, 4, and 5 with the reactor mode switch in shutdown as specified in Table 1.1-1, all control rods are fully inserted and a control rod block is initiated. Therefore, all control rods in core cells that contain one or more fuel assemblies must be verified fully inserted while in MODES 3, 4, and 5 with the reactor mode switch in other than the shutdown position. The additional LCO requirement to preclude CORE ALTERATIONS is appropriate for MODE 5 operations, as discussed below, and is inherently met in MODES 3 and 4 by the definition of CORE ALTERATIONS, which cannot be performed with the vessel head in place.

In MODE 5, with the reactor mode switch in the refuel position, only one control rod can be withdrawn under the refuel position one rod out interlock (LCO 3.9.2, "Refuel Position One-Rod-Out Interlock"). The refueling equipment interlocks (LCO 3.9.1, "Refueling Equipment Interlocks") appropriately control other CORE ALTERATIONS. Due to the increased potential for error in controlling these multiple interlocks and the limited duration of tests involving the reactor mode switch position, conservative controls are required, consistent with MODES 3 and 4. The additional controls of administratively not permitting other CORE ALTERATIONS will adequately ensure that the reactor does not become critical during these tests.

APPLICABILITY Any required periodic interlock testing involving the reactor mode switch, while in MODES 1 and 2, can be performed without the need for Special Operations exceptions. Mode switch manipulations in these MODES would likely result in unit trips. In MODES 3, 4, and 5, this Special Operations LCO is only permitted to be used to allow reactor mode switch interlock testing that cannot conveniently be performed without this allowance or testing that must be performed prior to entering another MODE. Such interlock testing may consist of required Surveillances, or may be the result of maintenance, repair, or troubleshooting activities. In MODES 3, 4, and 5, the interlock functions provided by the reactor mode switch in shutdown (i.e., all control rods inserted and incapable of withdrawal) and refueling (i.e., refueling interlocks to prevent inadvertent criticality during CORE ALTERATIONS) positions can be administratively controlled adequately during the performance of certain tests.

(continued)

BASES (continued)

ACTIONS

A.1, A.2, A.3.1, and A.3.2

These Required Actions are provided to restore compliance with the Technical Specifications overridden by this Special Operations LCO. Restoring compliance will also result in exiting the Applicability of this Special Operations LCO.

All CORE ALTERATIONS, except control rod insertion, if in progress, are immediately suspended in accordance with Required Action A.1, and all insertable control rods in core cells that contain one or more fuel assemblies are fully inserted within 1 hour, in accordance with Required Action A.2. This will preclude potential mechanisms that could lead to criticality. Control rods in core cells containing no fuel assemblies do not affect the reactivity of the core and, therefore, do not have to be inserted. Suspension of CORE ALTERATIONS shall not preclude the completion of movement of a component to a safe condition. Placing the reactor mode switch in the shutdown position will ensure that all inserted control rods remain inserted and result in operation in accordance with Table 1.1-1. Alternatively, if in MODE 5, the reactor mode switch may be placed in the refuel position, which will also result in operating in accordance with Table 1.1-1. A Note is added to Required Action A.3.2 to indicate that this Required Action is not applicable in MODES 3 and 4, since only the shutdown position is allowed in these MODES. The allowed Completion Time of 1 hour for Required Actions A.2, A.3.1, and A.3.2 provides sufficient time to normally insert the control rods and place the reactor mode switch in the required position, based on operating experience, and is acceptable given that all operations that could increase core reactivity have been suspended.

SURVEILLANCE
REQUIREMENTS

SR 3.10.1.1 and SR 3.10.1.2

Meeting the requirements of this Special Operations LCO maintains operation consistent with or conservative to operating with the reactor mode switch in the shutdown position (or the refuel position for MODE 5). The functions of the reactor mode switch interlocks that are not in effect, due to the testing in progress, are adequately compensated for by the Special Operations LCO requirements.

(continued)

BASES

SURVEILLANCE
REQUIREMENTS

SR 3.10.1.1 and SR 3.10.1.2 (continued)

The administrative controls are to be periodically verified to ensure that the operational requirements continue to be met. In addition, the all rods fully inserted Surveillance (SR 3.10.1.1) must be verified by a second licensed operator (Reactor Operator or Senior Reactor Operator) or other task qualified member of the technical staff (e.g., a shift technical advisor or reactor engineer). The Surveillances performed at the 12 hour and 24 hour Frequencies are intended to provide appropriate assurance that each operating shift is aware of and verify compliance with these Special Operations LCO requirements.

REFERENCES

1. UFSAR, Section 7.2.
 2. UFSAR, Section 15.4.1.1.
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B 3.10 SPECIAL OPERATIONS

B 3.10.2 Single Control Rod Withdrawal - Hot Shutdown

BASES

BACKGROUND

The purpose of this MODE 3 Special Operations LCO is to permit the withdrawal of a single control rod for testing while in hot shutdown, by imposing certain restrictions. In MODE 3, the reactor mode switch is in the shutdown position, and all control rods are inserted and blocked from withdrawal. Many systems and functions are not required in these conditions, due to other installed interlocks that are actuated when the reactor mode switch is in the shutdown position. However, circumstances may arise while in MODE 3 that present the need to withdraw a single control rod for various tests (e.g., rod exercising, friction tests, scram timing, and coupling integrity checks). These single control rod withdrawals are normally accomplished by selecting the refuel position for the reactor mode switch. This Special Operations LCO provides the appropriate additional controls to allow a single control rod withdrawal in MODE 3.

APPLICABLE
SAFETY ANALYSES

With the reactor mode switch in the refuel position, the analyses for control rod withdrawal during refueling are applicable and, provided the assumptions of these analyses are satisfied in MODE 3, these analyses will bound the consequences of an accident. Explicit safety analyses in the UFSAR (Ref. 1) demonstrate that the functioning of the refueling interlocks and adequate SDM will preclude unacceptable reactivity excursions.

Refueling interlocks restrict the movement of control rods to reinforce operational procedures that prevent the reactor from becoming critical. These interlocks prevent the withdrawal of more than one control rod. Under these conditions, since only one control rod can be withdrawn, the core will always be shut down even with the highest worth control rod withdrawn if adequate SDM exists.

The control rod scram function provides backup protection to normal refueling procedures and the refueling interlocks, which prevent inadvertent criticalities during refueling.

(continued)

BASES

APPLICABLE
SAFETY ANALYSES
(continued)

Alternate backup protection can be obtained by ensuring that a five by five array of control rods, centered on the withdrawn control rod, are inserted and incapable of withdrawal.

As described in LCO 3.0.7, compliance with Special Operations LCOs is optional, and therefore, no criteria of 10 CFR 50.36(c)(2)(ii) apply. Special Operations LCOs provide flexibility to perform certain operations by appropriately modifying requirements of other LCOs. A discussion of the criteria satisfied for the other LCOs is provided in their respective Bases.

LCO

As described in LCO 3.0.7, compliance with this Special Operations LCO is optional. Operation in MODE 3 with the reactor mode switch in the refuel position can be performed in accordance with other Special Operations LCOs (i.e., LCO 3.10.1, "Reactor Mode Switch Interlock Testing") without meeting this Special Operations LCO or its ACTIONS. However, if a single control rod withdrawal is desired in MODE 3, controls consistent with those required during refueling must be implemented and this Special Operations LCO applied. "Withdrawal" in this application includes the actual withdrawal of the control rod as well as maintaining the control rod in a position other than the full-in position, and reinserting the control rod. The refueling interlocks of LCO 3.9.2, "Refuel Position One-Rod-Out Interlock," required by this Special Operations LCO, will ensure that only one control rod can be withdrawn.

To back up the refueling interlocks (LCO 3.9.2), the ability to scram the withdrawn control rod in the event of an inadvertent criticality is provided by this Special Operations LCO's requirements in Item d.1. Alternately, provided a sufficient number of control rods in the vicinity of the withdrawn control rod are known to be inserted and incapable of withdrawal (Item d.2), the possibility of criticality on withdrawal of this control rod is sufficiently precluded, so as not to require the scram capability of the withdrawn control rod. Also, once this alternate (Item d.2) is completed, the SDM requirement to account for both the withdrawn-untrippable control rod and the highest worth control rod may be changed to allow the withdrawn-untrippable control rod to be the single highest worth control rod.

(continued)

BASES (continued)

APPLICABILITY Control rod withdrawals are adequately controlled in MODES 1, 2, and 5 by existing LCOs. In MODES 3 and 4, control rod withdrawal is only allowed if performed in accordance with this Special Operations LCO or Special Operations LCO 3.10.3, "Single Control Rod Withdrawal - Cold Shutdown," and if limited to one control rod. This allowance is only provided with the reactor mode switch in the refuel position. For these conditions, the one-rod-out interlock (LCO 3.9.2), control rod position indication (LCO 3.9.4, "Control Rod Position Indication") full insertion requirements for all other control rods, and scram functions (LCO 3.3.1.1, "Reactor Protection System (RPS) Instrumentation," and LCO 3.9.5, "Control Rod OPERABILITY - Refueling"), or the added administrative control in Item d.2 of this Special Operations LCO, minimizes potential reactivity excursions.

ACTIONS A Note has been provided to modify the ACTIONS related to a single control rod withdrawal while in MODE 3. Section 1.3, Completion Times, specifies once a Condition has been entered, subsequent divisions, subsystems, components, or variables expressed in the Condition discovered to be inoperable or not within limits, will not result in separate entry into the Condition. Section 1.3 also specifies Required Actions of the Condition continue to apply for each additional failure, with Completion Times based on initial entry into the Condition. However, the Required Actions for each requirement of the LCO not met provide appropriate compensatory measures for separate requirements that are not met. As such, a Note has been provided that allows separate Condition entry for each requirement of the LCO.

A.1

If one or more of the requirements specified in this Special Operations LCO are not met, the ACTIONS applicable to the stated requirements of the affected LCOs are immediately entered as directed by Required Action A.1. This Required Action has been modified by a Note that clarifies the intent of any other LCO's Required Action to insert all control rods. This Required Action includes exiting this Special Operations Applicability LCO by returning the reactor mode

(continued)

BASES

ACTIONS

A.1 (continued)

switch to the shutdown position. A second Note has been added, which clarifies that this Required Action is only applicable if the requirements not met are for an affected LCO.

A.2.1 and A.2.2

Required Actions A.2.1 and A.2.2 and are alternative Required Actions that can be taken instead of Required Action A.1 to restore compliance with the normal MODE 3 requirements, thereby exiting this Special Operations LCO's Applicability. Actions must be initiated immediately to insert all insertable control rods. Actions must continue until all such control rods are fully inserted. Placing the reactor mode switch in the shutdown position will ensure that all inserted rods remain inserted and restore operation in accordance with Table 1.1-1. The allowed Completion Time of 1 hour to place the reactor mode switch in the shutdown position provides sufficient time to normally insert the control rods.

SURVEILLANCE
REQUIREMENTS

SR 3.10.2.1, SR 3.10.2.2, and SR 3.10.2.3

The other LCOs made applicable in this Special Operations LCO are required to have their Surveillances met to establish that this Special Operations LCO is being met. If the local array of control rods is inserted and disarmed while the scram function for the withdrawn rod is not available, periodic verification in accordance with SR 3.10.2.2 is required to preclude the possibility of criticality. The control rods can be hydraulically disarmed by closing the drive water and exhaust water isolation valves. Electrically, the control rods can be disarmed by disconnecting power from all four directional control valve solenoids. SR 3.10.2.2 has been modified by a Note, which clarifies that this SR is not required to be met if SR 3.10.2.1 is satisfied for LCO 3.10.2.d.1 requirements, since SR 3.10.2.2 demonstrates that the alternative LCO 3.10.2.d.2 requirements are satisfied. Also, SR 3.10.2.3 verifies that all control rods other than the

(continued)

BASES

SURVEILLANCE
REQUIREMENTS

SR 3.10.2.1, SR 3.10.2.2, and SR 3.10.2.3 (continued)

control rod being withdrawn are fully inserted. The 24 hour Frequency is acceptable because of the administrative controls on control rod withdrawals, the protection afforded by the LCOs involved, and hardware interlocks that preclude additional control rod withdrawals.

REFERENCES

1. UFSAR, Section 15.4.1.1.
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B 3.10 SPECIAL OPERATIONS

B 3.10.3 Single Control Rod Withdrawal - Cold Shutdown

BASES

BACKGROUND The purpose of this MODE 4 Special Operations LCO is to permit the withdrawal of a single control rod for testing or maintenance, while in cold shutdown, by imposing certain restrictions. In MODE 4, the reactor mode switch is in the shutdown position, and all control rods are inserted and blocked from withdrawal. Many systems and functions are not required in these conditions, due to the installed interlocks associated with the reactor mode switch in the shutdown position. Circumstances may arise while in MODE 4, however, that present the need to withdraw a single control rod for various tests (e.g., rod exercising, friction tests, scram time testing, and coupling integrity checks). Certain situations may also require the removal of the associated control rod drive (CRD). These single control rod withdrawals and possible subsequent removals are normally accomplished by selecting the refuel position for the reactor mode switch.

APPLICABLE SAFETY ANALYSES With the reactor mode switch in the refuel position, the analyses for control rod withdrawal during refueling are applicable and, provided the assumptions of these analyses are satisfied in MODE 4, these analyses will bound the consequences of an accident. Explicit safety analyses in the UFSAR (Ref. 1) demonstrate that the functioning of the refueling interlocks and adequate SDM will preclude unacceptable reactivity excursions.

Refueling interlocks restrict the movement of control rods to reinforce operational procedures that prevent the reactor from becoming critical. These interlocks prevent the withdrawal of more than one control rod. Under these conditions, since only one control rod can be withdrawn, the core will always be shut down even with the highest worth control rod withdrawn if adequate SDM exists.

The control rod scram function provides backup protection in the event normal refueling procedures and the refueling interlocks fail to prevent inadvertent criticalities during

(continued)

BASES

APPLICABLE
SAFETY ANALYSES
(continued)

refueling. Alternate backup protection can be obtained by ensuring that a five by five array of control rods, centered on the withdrawn control rod, are inserted and incapable of withdrawal. This alternate backup protection is required when removing the CRD because this removal renders the withdrawn control rod incapable of being scrammed.

As described in LCO 3.0.7, compliance with Special Operations LCOs is optional, and therefore, no criteria of 10 CFR 50.36(c)(2)(ii) apply. Special Operations LCOs provide flexibility to perform certain operations by appropriately modifying requirements of other LCOs. A discussion of the criteria satisfied for the other LCOs is provided in their respective Bases.

LCO

As described in LCO 3.0.7, compliance with this Special Operations LCO is optional. Operation in MODE 4 with the reactor mode switch in the refuel position can be performed in accordance with other LCOs (i.e., Special Operations LCO 3.10.1, "Reactor Mode Switch Interlock Testing") without meeting this Special Operations LCO or its ACTIONS. If a single control rod withdrawal is desired in MODE 4, controls consistent with those required during refueling must be implemented and this Special Operations LCO applied. "Withdrawal" in this application includes the actual withdrawal of the control rod as well as maintaining the control rod in a position other than the full-in position, and reinserting the control rod.

The refueling interlocks of LCO 3.9.2, "Refuel Position One-Rod-Out Interlock," required by this Special Operations LCO will ensure that only one control rod can be withdrawn. At the time CRD removal begins, the disconnection of the position indication probe will cause LCO 3.9.4, "Control Rod Position Indication," and therefore, LCO 3.9.2 to fail to be met. Therefore, prior to commencing CRD removal, a control rod withdrawal block is required to be inserted to ensure that no additional control rods can be withdrawn and that compliance with this Special Operations LCO is maintained.

To back up the refueling interlocks (LCO 3.9.2) or the control rod withdrawal block, the ability to scram the withdrawn control rod in the event of an inadvertent

(continued)

BASES

LCO
(continued) criticality is provided by the Special Operations LCO requirements in Item c.1. Alternatively, when the scram function is not OPERABLE, or the CRD is to be removed, a sufficient number of rods in the vicinity of the withdrawn control rod are required to be inserted and made incapable of withdrawal by electrically or hydraulically disarming the CRD (Item c.2). This precludes the possibility of criticality upon withdrawal of this control rod. Also, once this alternate (Item c.2) is completed, the SDM requirement to account for both the withdrawn-untrippable control rod and the highest worth control rod may be changed to allow the withdrawn-untrippable control rod to be the single highest worth control rod.

APPLICABILITY Control rod withdrawals are adequately controlled in MODES 1, 2, and 5 by existing LCOs. In MODES 3 and 4, control rod withdrawal is only allowed if performed in accordance with Special Operations LCO 3.10.2, "Single Control Rod Withdrawal - Hot Shutdown," or this Special Operations LCO, and if limited to one control rod. This allowance is only provided with the reactor mode switch in the refuel position.

During these conditions, the full insertion requirements for all other control rods, the one-rod-out interlock (LCO 3.9.2), control rod position indication (LCO 3.9.4), and scram functions (LCO 3.3.1.1, "Reactor Protection System (RPS) Instrumentation," LCO 3.3.8.2, "Reactor Protection System (RPS) Electric Power Monitoring," and LCO 3.9.5, "Control Rod OPERABILITY - Refueling"), or the added administrative controls in Item b.2 and Item c.2 of this Special Operations LCO, provide mitigation of potential reactivity excursions.

ACTIONS A Note has been provided to modify the ACTIONS related to a single control rod withdrawal while in MODE 4. Section 1.3, Completion Times, specifies once a Condition has been entered, subsequent divisions, subsystems, components, or variables expressed in the Condition discovered to be inoperable or not within limits, will not result in separate entry into the Condition. Section 1.3 also specifies that Required Actions of the Condition continue to apply for each

(continued)

BASES

ACTIONS
(continued)

additional failure, with Completion Times based on initial entry into the Condition. However, the Required Actions for each requirement of the LCO not met provide appropriate compensatory measures for separate requirements that are not met. As such, a Note has been provided that allows separate Condition entry for each requirement of the LCO.

A.1, A.2.1, and A.2.2

If one or more of the requirements of this Special Operations LCO are not met with the affected control rod insertable, these Required Actions restore operation consistent with normal MODE 4 conditions (i.e., all rods inserted) or with the exceptions allowed in this Special Operations LCO. Required Action A.1 has been modified by a Note that clarifies the intent of any other LCO's Required Action to insert all control rods. This Required Action includes exiting this Special Operations LCO Applicability by returning the reactor mode switch to the shutdown position. A second Note has been added to Required Action A.1 to clarify that this Required Action is only applicable if the requirements not met are for an affected LCO.

Required Actions A.2.1 and A.2.2 are specified, based on the assumption that the control rod is being withdrawn. If the control rod is still insertable, actions must be immediately initiated to fully insert all insertable control rods and within 1 hour place the reactor mode switch in the shutdown position. Action must continue until all such control rods are fully inserted. The allowed Completion Time of 1 hour for placing the reactor mode switch in the shutdown position provides sufficient time to normally insert the control rods.

B.1, B.2.1, and B.2.2

If one or more of the requirements of this Special Operations LCO are not met with the affected control rod not insertable, withdrawal of the control rod and removal of the associated CRD must immediately be suspended. If the CRD has been removed, such that the control rod is not

(continued)

BASES

ACTIONS B.1, B.2.1, and B.2.2 (continued)

insertable, the Required Actions require the most expeditious action be taken to either initiate action to restore the CRD and insert its control rod, or restore compliance with this Special Operations LCO.

SURVEILLANCE REQUIREMENTS SR 3.10.3.1, SR 3.10.3.2, SR 3.10.3.3, and SR 3.10.3.4

The other LCOs made applicable by this Special Operations LCO are required to have their associated Surveillances met to establish that this Special Operations LCO is being met. If the local array of control rods is inserted and disarmed while the scram function for the withdrawn rod is not available, periodic verification is required to ensure that the possibility of criticality remains precluded. The control rods can be hydraulically disarmed by closing the drive water and exhaust water isolation valves. Electrically, the control rods can be disarmed by disconnecting power from all four directional control valve solenoids. Verification that all the other control rods are fully inserted is required to meet the SDM requirements. Verification that a control rod withdrawal block has been inserted ensures that no other control rods can be inadvertently withdrawn under conditions when position indication instrumentation is inoperable for the affected control rod. The 24 hour Frequency is acceptable because of the administrative controls on control rod withdrawals, the protection afforded by the LCOs involved, and hardware interlocks to preclude an additional control rod withdrawal.

SR 3.10.3.2 and SR 3.10.3.4 have been modified by Notes, which clarify that these SRs are not required to be met if the alternative requirements demonstrated by SR 3.10.3.1 are satisfied.

REFERENCES 1. UFSAR, Section 15.4.1.1.

B 3.10 SPECIAL OPERATIONS

B 3.10.4 Single Control Rod Drive (CRD) Removal – Refueling

BASES

BACKGROUND

The purpose of this MODE 5 Special Operations LCO is to permit the removal of a single CRD during refueling operations by imposing certain administrative controls. Refueling interlocks restrict the movement of control rods and the operation of the refueling equipment to reinforce operational procedures that prevent the reactor from becoming critical during refueling operations. During refueling operations, no more than one control rod, in a core cell containing one or more fuel assemblies, is permitted to be withdrawn. The refueling interlocks use the "full-in" position indicators to determine the position of all control rods. If the "full-in" position signal is not present for every control rod, then the all rods in permissive for the refueling equipment interlocks is not present and fuel loading is prevented. Also, the refuel position one-rod-out interlock will not allow the withdrawal of a second control rod.

The control rod scram function provides backup protection in the event normal refueling procedures and the refueling interlocks described above fail to prevent inadvertent criticalities during refueling. The requirement for the refueling interlocks to be OPERABLE precludes the possibility of removing the CRD once a control rod is withdrawn from a core cell containing one or more fuel assemblies. This Special Operations LCO provides controls sufficient to ensure the possibility of an inadvertent criticality is precluded, while allowing a single CRD to be removed from a core cell containing one or more fuel assemblies. The removal of the CRD involves disconnecting the position indication probe, which causes noncompliance with LCO 3.9.4, "Control Rod Position Indication," and, therefore, LCO 3.9.1, "Refueling Equipment Interlocks," and LCO 3.9.2, "Refueling Position One-Rod-Out Interlock." The CRD removal also requires isolation of the CRD from the CRD Hydraulic System, thereby causing inoperability of the control rod (LCO 3.9.5, "Control Rod OPERABILITY – Refueling").

(continued)

BASES (continued)

APPLICABLE
SAFETY ANALYSES

With the reactor mode switch in the refuel position, the analyses for control rod withdrawal during refueling are applicable and, provided the assumptions of these analyses are satisfied, these analyses will bound the consequences of accidents. Explicit safety analyses in the UFSAR (Ref. 1) demonstrate that the proper operation of the refueling interlocks and adequate SDM will preclude unacceptable reactivity excursions.

Refueling interlocks restrict the movement of control rods and the operation of the refueling equipment to reinforce operational procedures that prevent the reactor from becoming critical. These interlocks prevent the withdrawal of more than one control rod. Under these conditions, since only one control rod can be withdrawn, the core will always be shut down even with the highest worth control rod withdrawn if adequate SDM exists. By requiring all other control rods to be inserted and a control rod withdrawal block initiated, the function of the inoperable one-rod-out interlock (LCO 3.9.2) is adequately maintained. This Special Operations LCO requirement that no other CORE ALTERATIONS are in progress adequately compensates for the inoperable all rods in permissive for the refueling equipment interlocks (LCO 3.9.1).

The control rod scram function provides backup protection to normal refueling procedures and the refueling interlocks, which prevent inadvertent criticalities during refueling. Since the scram function and refueling interlocks may be suspended, alternate backup protection required by this Special Operations LCO is obtained by ensuring that a five by five array of control rods, centered on the withdrawn control rod, are inserted and are incapable of being withdrawn, and all other control rods are inserted and incapable of being withdrawn by insertion of a control rod block.

As described in LCO 3.0.7, compliance with Special Operations LCOs is optional, and therefore, no criteria of 10 CFR 50.36(c)(2)(ii) apply. Special Operations LCOs provide flexibility to perform certain operations by appropriately modifying requirements of other LCOs. A discussion of the criteria satisfied for the other LCOs is provided in their respective Bases.

(continued)

BASES (continued)

LCO As described in LCO 3.0.7, compliance with this Special Operations LCO is optional. Operation in MODE 5 with any of the following LCOs—LCO 3.3.1.1, "Reactor Protection System (RPS) Instrumentation," LCO 3.3.8.2, "Reactor Protection System (RPS) Electric Power Monitoring," LCO 3.9.1, LCO 3.9.2, LCO 3.9.4, or LCO 3.9.5—not met can be performed in accordance with the Required Actions of these LCOs without meeting this Special Operations LCO or its ACTIONS. However, if a single CRD removal from a core cell containing one or more fuel assemblies is desired in MODE 5, controls consistent with those required by LCO 3.3.1.1, LCO 3.3.8.2, LCO 3.9.1, LCO 3.9.2, LCO 3.9.4, and LCO 3.9.5 must be implemented and this Special Operations LCO applied.

By requiring all other control rods to be inserted and a control rod withdrawal block initiated, the function of the inoperable one-rod-out interlock (LCO 3.9.2) is adequately maintained. This Special Operations LCO requirement that no other CORE ALTERATIONS are in progress adequately compensates for the inoperable all-rods-in permissive for the refueling equipment interlocks (LCO 3.9.1). Ensuring that the five by five array of control rods, centered on the withdrawn control rod, are inserted and incapable of withdrawal (by electrically or hydraulically disarming the CRD) adequately satisfies the backup protection that LCO 3.3.1.1 and LCO 3.9.2 would have otherwise provided. Also, once these requirements (Items a, b, and c) are completed, the SDM requirement to account for both the withdrawn-untrippable control rod and the highest worth control rod may be changed to allow the withdrawn-untrippable control rod to be the single highest worth control rod.

APPLICABILITY Operation in MODE 5 is controlled by existing LCOs. The allowance to comply with this Special Operations LCO in lieu of the ACTIONS of LCO 3.3.1.1, LCO 3.3.8.2, LCO 3.9.1, LCO 3.9.2, LCO 3.9.4, and LCO 3.9.5 is appropriately controlled with the additional administrative controls required by this Special Operations LCO, which reduces the potential for reactivity excursions.

(continued)

BASES (continued)

ACTIONS

A.1, A.2.1, and A.2.2

If one or more of the requirements of this Special Operations LCO are not met, the immediate implementation of these Required Actions restores operation consistent with the normal requirements for failure to meet LCO 3.3.1.1, LCO 3.9.1, LCO 3.9.2, LCO 3.9.4, and LCO 3.9.5 (i.e., all control rods inserted) or with the allowances of this Special Operations LCO. The Completion Times for Required Action A.1, Required Action A.2.1, and Required Action A.2.2 are intended to require these Required Actions be implemented in a very short time and carried through in an expeditious manner to either initiate action to restore the CRD and insert its control rod, or initiate action to restore compliance with this Special Operations LCO. Actions must continue until either Required Action A.2.1 or Required Action A.2.2 is satisfied.

SURVEILLANCE
REQUIREMENTS

SR 3.10.4.1, SR 3.10.4.2, SR 3.10.4.3, SR 3.10.4.4, and
SR 3.10.4.5

Verification that all the control rods, other than the control rod withdrawn for the removal of the associated CRD, are fully inserted is required to ensure the SDM is within limits. Verification that the local five by five array of control rods other than the control rod withdrawn for the removal of the associated CRD, is inserted and disarmed, while the scram function for the withdrawn rod is not available, is required to ensure that the possibility of criticality remains precluded. The control rods can be hydraulically disarmed by closing the drive water and exhaust water isolation valves. Electrically, the control rods can be disarmed by disconnecting power from all four directional control valve solenoids. Verification that a control rod withdrawal block has been inserted ensures that no other control rods can be inadvertently withdrawn under conditions when position indication instrumentation is inoperable for the withdrawn control rod. The Surveillance for LCO 3.1.1, which is made applicable by this Special Operations LCO, is required in order to establish that this Special Operations LCO is being met. Verification that no other CORE ALTERATIONS are being made is required to ensure the assumptions of the safety analysis are satisfied.

(continued)

BASES

SURVEILLANCE SR 3.10.4.1, SR 3.10.4.2, SR 3.10.4.3, SR 3.10.4.4, and
REQUIREMENTS SR 3.10.4.5 (continued)

Periodic verification of the administrative controls established by this Special Operations LCO is prudent to preclude the possibility of an inadvertent criticality. The 24 hour Frequency is acceptable, given the administrative controls on control rod removal and hardware interlocks to block an additional control rod withdrawal.

REFERENCES 1. UFSAR, Section 15.4.1.1.

B 3.10 SPECIAL OPERATIONS

B 3.10.5 Multiple Control Rod Withdrawal - Refueling

BASES

BACKGROUND

The purpose of this MODE 5 Special Operations LCO is to permit multiple control rod withdrawal during refueling by imposing certain administrative controls.

Refueling interlocks restrict the movement of control rods and the operation of the refueling equipment to reinforce operational procedures that prevent the reactor from becoming critical during refueling operations. During refueling operations, no more than one control rod, in a core cell containing one or more fuel assemblies is permitted to be withdrawn. When all four fuel assemblies are removed from a cell, the control rods may be withdrawn with no restrictions. Any number of control rods may be withdrawn and removed from the reactor vessel if their cells contain no fuel.

The refueling interlocks use the "full-in" position indicators to determine the position of all control rods. If the "full-in" position signal is not present for every control rod, then the all rods in permissive for the refueling equipment interlocks is not present and fuel loading is prevented. Also, the refuel position one-rod-out interlock will not allow the withdrawal of a second control rod.

To allow more than one control rod to be withdrawn during refueling, these interlocks must be defeated. This Special Operations LCO establishes the necessary administrative controls to allow bypass of the "full-in" position indicators.

APPLICABLE
SAFETY ANALYSES

Explicit safety analyses in the UFSAR (Ref. 1) demonstrate that the functioning of the refueling interlocks and adequate SDM will prevent unacceptable reactivity excursions during refueling. To allow multiple control rod withdrawals, control rod removals, associated control rod drive (CRD) removal, or any combination of these, the "full-in" position indication is allowed to be bypassed for each

(continued)

BASES

APPLICABLE
SAFETY ANALYSES
(continued)

withdrawn control rod if all fuel has been removed from the cell. With no fuel assemblies in the core cell, the associated control rod has no reactivity control function and is not required to remain inserted. Prior to reloading fuel into the cell, however, the associated control rod must be inserted to ensure that an inadvertent criticality does not occur, as evaluated in the Reference 1 analysis.

As described in LCO 3.0.7, compliance with Special Operations LCOs is optional, and therefore, no criteria of 10 CFR 50.36(c)(2)(ii) apply. Special Operations LCOs provide flexibility to perform certain operations by appropriately modifying requirements of other LCOs. A discussion of the criteria satisfied for the other LCOs is provided in their respective Bases.

LCO

As described in LCO 3.0.7, compliance with this Special Operations LCO is optional. Operation in MODE 5 with LCO 3.9.4, "Control Rod Position Indication," or LCO 3.9.5, "Control Rod OPERABILITY - Refueling," not met, can be performed in accordance with the Required Actions of these LCOs without meeting this Special Operations LCO or its ACTIONS. If multiple control rod withdrawal or removal, or CRD removal is desired, all four fuel assemblies are required to be removed from the associated cells. Prior to entering this LCO, any fuel remaining in a cell whose CRD was previously removed under the provisions of another LCO must be removed. "Withdrawal" in this application includes the actual withdrawal of the control rod as well as maintaining the control rod in a position other than the full-in position, and reinserting the control rod.

Loading of fuel assemblies into or shuffling within the reactor pressure vessel is prohibited when multiple control rods are withdrawn. This restriction is consistent with existing conditions to the facility operating licenses.

APPLICABILITY

Operation in MODE 5 is controlled by existing LCOs. The exceptions from other LCO requirements (e.g., the ACTIONS of LCO 3.9.4 or LCO 3.9.5) allowed by this Special Operations LCO are appropriately controlled by requiring all fuel to be removed from cells whose "full-in" indicators are allowed to be bypassed.

(continued)

BASES (continued)

ACTIONS

A.1, A.2.1, and A.2.2

If one or more of the requirements of this Special Operations LCO are not met, the immediate implementation of these Required Actions restores operation consistent with the normal requirements for refueling (i.e., all control rods inserted in core cells containing one or more fuel assemblies) or with the exceptions granted by this Special Operations LCO. The Completion Times for Required Action A.1, Required Action A.2.1, and Required Action A.2.2 are intended to require that these Required Actions be implemented in a very short time and carried through in an expeditious manner to either initiate action to restore the affected CRDs and insert their control rods, or initiate action to restore compliance with this Special Operations LCO.

SURVEILLANCE
REQUIREMENTS

SR 3.10.5.1, SR 3.10.5.2, and SR 3.10.5.3

Periodic verification of the administrative controls established by this Special Operations LCO is prudent to preclude the possibility of an inadvertent criticality. The 24 hour Frequency is acceptable, given the administrative controls on fuel assembly and control rod removal, and takes into account other indications of control rod status available in the control room.

REFERENCES

1. UFSAR, Section 15.4.1.1.

B 3.10 Special Operations

B 3.10.6 Control Rod Testing – Operating

BASES

BACKGROUND The purpose of this Special Operations LCO is to permit control rod testing, while in MODES 1 and 2, by imposing certain administrative controls. Control rod patterns during startup conditions are controlled by the operator and the Rod Worth Minimizer (RWM) (LCO 3.3.2.1, "Control Rod Block Instrumentation"), such that only the specified control rod sequences and relative positions required by LCO 3.1.6, "Rod Pattern Control," are allowed over the operating range from all control rods inserted to the low power setpoint (LPSP) of the RWM. The sequences effectively limit the potential amount and rate of reactivity increase that could occur during a control rod drop accident (CRDA). During these conditions, control rod testing is sometimes required that may result in control rod patterns not in compliance with the prescribed sequences of LCO 3.1.6. These tests may include SDM demonstrations, control rod scram time testing, and control rod friction testing. This Special Operations LCO provides the necessary exceptions to the requirements of LCO 3.1.6 and provides additional administrative controls to allow the deviations in such tests from the prescribed sequences in LCO 3.1.6.

APPLICABLE SAFETY ANALYSES The analytical methods and assumptions used in evaluating the CRDA are summarized in References 1, 2, 3, 4 and 5. CRDA analyses assume the reactor operator follows prescribed withdrawal sequences. These sequences define the potential initial conditions for the CRDA analyses. The RWM provides backup to operator control of the withdrawal sequences to ensure that the initial conditions of the CRDA analyses are not violated. For special sequences developed for control rod testing, the initial control rod patterns assumed in the safety analysis of References 1, 2, 3, 4 and 5 may not be preserved. Therefore, special CRDA analyses are required to demonstrate that these special sequences will not result in unacceptable consequences, should a CRDA occur during the testing. These analyses, performed in accordance with an NRC approved methodology, are dependent on the specific test being performed.

(continued)

BASES

APPLICABLE SAFETY ANALYSES (continued) As described in LCO 3.0.7, compliance with Special Operations LCOs is optional, and therefore, no criteria of 10 CFR 50.36(c)(2)(ii) apply. Special Operations LCOs provide flexibility to perform certain operations by appropriately modifying requirements of other LCOs. A discussion of the criteria satisfied for the other LCOs is provided in their respective Bases.

LCO As described in LCO 3.0.7, compliance with this Special Operations LCO is optional. Control rod testing may be performed in compliance with the prescribed sequences of LCO 3.1.6, and during these tests, no exceptions to the requirements of LCO 3.1.6 are necessary. For testing performed with a sequence not in compliance with LCO 3.1.6, the requirements of LCO 3.1.6 may be suspended, provided additional administrative controls are placed on the test to ensure that the assumptions of the special safety analysis for the test sequence are satisfied. Assurance that the test sequence is followed can be provided by either programming the test sequence into the RWM, with conformance verified as specified in SR 3.3.2.1.8 and allowing the RWM to monitor control rod withdrawal and provide appropriate control rod blocks if necessary, or by verifying conformance to the approved test sequence by a second licensed operator (Reactor Operator or Senior Reactor Operator) or other task qualified member of the technical staff (e.g., a shift technical advisor or reactor engineer). These controls are consistent with those normally applied to operation in the startup range as defined in the SRs and ACTIONS of LCO 3.3.2.1, "Control Rod Block Instrumentation."

APPLICABILITY Control rod testing, while in MODES 1 and 2 with THERMAL POWER greater than 10% RTP, is adequately controlled by the existing LCOs on power distribution limits and control rod block instrumentation. Control rod movement during these conditions is not restricted to prescribed sequences and can be performed within the constraints of LCO 3.2.1, "AVERAGE PLANAR LINEAR HEAT GENERATION RATE (APLHGR)," LCO 3.2.2, "MINIMUM CRITICAL POWER RATIO (MCPR)," LCO 3.2.3, "LINEAR HEAT GENERATION RATE (LHGR)," and LCO 3.3.2.1. With THERMAL POWER less than or equal to 10% RTP, the provisions of this Special Operations LCO are necessary to perform special tests that are not in conformance with the prescribed

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BASES

APPLICABILITY (continued) control rod sequences of LCO 3.1.6. While in MODES 3 and 4, control rod withdrawal is only allowed if performed in accordance with Special Operations LCO 3.10.2, "Single Control Rod Withdrawal—Hot Shutdown" or Special Operations LCO 3.10.3, "Single Control Rod Withdrawal—Cold Shutdown," which provide adequate controls to ensure that the assumptions of the safety analysis of Reference 3 are satisfied. During these Special Operations and while in MODE 5, the one rod out interlock (LCO 3.9.2, "Refuel Position One-Rod-Out Interlock) and scram functions (LCO 3.3.1.1, "Reactor Protection System (RPS) Instrumentation," and LCO 3.9.5, "Control Rod OPERABILITY—Refueling"), or the added administrative controls prescribed in the applicable Special Operations LCOs, minimize potential reactivity excursions.

ACTIONS A.1

With the requirements of the LCO not met (e.g., the control rod pattern not in compliance with the special test sequence, the sequence is improperly loaded in the RWM), the testing is required to be immediately suspended. Upon suspension of the special test, the provisions of LCO 3.1.6 are no longer excepted, and appropriate actions are to be taken either to restore the control rod sequence to the prescribed sequence of LCO 3.1.6, or to shut down the reactor, if required by LCO 3.1.6.

SURVEILLANCE REQUIREMENTS SR 3.10.6.1

With the special test sequence not programmed into the RWM, a second licensed operator (Reactor Operator or Senior Reactor Operator) or other task qualified member of the technical staff (e.g., a shift technical advisor or reactor engineer) is required to verify conformance with the approved sequence for the test. This verification must be performed during control rod movement to prevent deviations from the specified sequence. A Note is added to indicate that this Surveillance does not need to be met if SR 3.10.6.2 is satisfied.

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BASES

SURVEILLANCE
REQUIREMENTS
(continued)

SR 3.10.6.2

When the RWM provides conformance to the special test sequence, the test sequence must be verified to be correctly loaded into the RWM prior to control rod movement. This Surveillance demonstrates compliance with SR 3.3.2.1.8, thereby demonstrating that the RWM is OPERABLE. A Note has been added to indicate that this Surveillance does not need to be met if SR 3.10.6.1 is satisfied.

REFERENCES

1. UFSAR, Section 15.4.10.
 2. XN-NF-80-19(P)(A), Volume 1, Supplement 2, Section 7.1, Exxon Nuclear Methodology for Boiling Water Reactor Neutronics Methods for Design Analysis, (as specified in Technical Specification 5.6.5).
 3. NEDE-24011-P-A-US, General Electric Standard Application for Reactor Fuel, (as specified in Technical Specification 5.6.5).
 4. Letter from T. Pickens (BWROG) to G.C. Lainas (NRC), "Amendment 17 to General Electric Licensing Topical Report NEDE-24011-P-A," BWROG-8644, August 15, 1986.
 5. NFSR-0091, Benchmark of CASMO/MICROBURN BWR Nuclear Design Methods, Commonwealth Edison Topical Report, (as specified in Technical Specification 5.6.5).
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B 3.10 SPECIAL OPERATIONS

B 3.10.7 SHUTDOWN MARGIN (SDM) Test – Refueling

BASES

BACKGROUND The purpose of this MODE 5 Special Operations LCO is to permit SDM testing to be performed for those plant configurations in which the reactor pressure vessel (RPV) head is either not in place or the head bolts are not fully tensioned.

LCO 3.1.1, "SHUTDOWN MARGIN (SDM)," requires that adequate SDM be demonstrated following fuel movements or control rod replacement within the RPV. The demonstration must be performed prior to or within 4 hours after criticality is reached. This SDM test may be performed prior to or during the first startup following refueling. Performing the SDM test prior to startup requires the test to be performed while in MODE 5 with the vessel head bolts less than fully tensioned (and possibly with the vessel head removed). While in MODE 5, the reactor mode switch is required to be in the shutdown or refuel position, where the applicable control rod blocks ensure that the reactor will not become critical. The SDM test requires the reactor mode switch to be in the startup/hot standby position, since more than one control rod will be withdrawn for the purpose of demonstrating adequate SDM. This Special Operations LCO provides the appropriate additional controls to allow withdrawing more than one control rod from a core cell containing one or more fuel assemblies when the reactor vessel head bolts are less than fully tensioned.

APPLICABLE Prevention and mitigation of unacceptable reactivity SAFETY ANALYSES excursions during control rod withdrawal, with the reactor mode switch in the startup/hot standby position while in MODE 5, is provided by the Intermediate Range Monitor (IRM) neutron flux scram (LCO 3.3.1.1, "Reactor Protection System (RPS) Instrumentation"), and control rod block instrumentation (LCO 3.3.2.1, "Control Rod Block Instrumentation"). The limiting reactivity excursion during startup conditions while in MODE 5 is the control rod drop accident (CRDA).

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BASES

APPLICABLE
SAFETY ANALYSES
(continued)

CRDA analyses assume that the reactor operator follows prescribed withdrawal sequences. For SDM tests performed within these defined sequences, the analyses of References 1, 2, 3 and 4 are applicable. However, for some sequences developed for the SDM testing, the control rod patterns assumed in the safety analyses of References 1, 2, 3 and 4 may not be met. Therefore, special CRDA analyses, performed in accordance with an NRC approved methodology, are required to demonstrate that the SDM test sequence will not result in unacceptable consequences should a CRDA occur during the testing. For the purpose of this test, the protection provided by the normally required MODE 5 applicable LCOs, in addition to the requirements of this LCO, will maintain normal test operations as well as postulated accidents within the bounds of the appropriate safety analyses (Refs. 1, 2, 3 and 4). In addition to the added requirements for the Rod Worth Minimizer (RWM), APRM, and control rod coupling, the single notch withdrawal mode is specified for out of sequence withdrawals. Requiring the single notch withdrawal mode limits withdrawal steps to a single notch, which limits inserted reactivity, and allows adequate monitoring of changes in neutron flux, which may occur during the test.

As described in LCO 3.0.7, compliance with Special Operations LCOs is optional, and therefore, no criteria of 10 CFR 50.36(c)(2)(ii) apply. Special Operations LCOs provide flexibility to perform certain operations by appropriately modifying requirements of other LCOs. A discussion of the criteria satisfied for the other LCOs is provided in their respective Bases.

LCO

As described in LCO 3.0.7, compliance with this Special Operations LCO is optional. SDM tests may be performed while in MODE 2, in accordance with Table 1.1-1, without meeting this Special Operations LCO or its ACTIONS. For SDM tests performed while in MODE 5, additional requirements must be met to ensure that adequate protection against potential reactivity excursions is available. To provide additional scram protection, beyond the normally required IRMs, the APRMs are also required to be OPERABLE (LCO 3.3.1.1, Functions 2.a and 2.d) as though the reactor were

(continued)

BASES

LCO
(continued)

in MODE 2. Because multiple control rods will be withdrawn and the reactor will potentially become critical, and the approved control rod withdrawal sequence must be enforced by the RWM (LCO 3.3.2.1, Function 2, MODE 2), or must be verified by a second licensed operator (Reactor Operator or Senior Reactor Operator) or other task qualified member of the technical staff (e.g., a shift technical advisor or reactor engineer). To provide additional protection against an inadvertent criticality, control rod withdrawals that do not conform to the analyzed rod position sequence specified in LCO 3.1.6, "Rod Pattern Control" (i.e., out of sequence control rod withdrawals) must be made in the notched withdrawal mode to minimize the potential reactivity insertion associated with each movement. Coupling integrity of withdrawn control rods is required to minimize the probability of a CRDA and ensure proper functioning of the withdrawn control rods, if they are required to scram. Because the reactor vessel head may be removed during these tests, no other CORE ALTERATIONS may be in progress. Furthermore, since the control rod scram function with the RCS at atmospheric pressure relies solely on the CRD accumulator, it is essential that the CRD charging water header remain pressurized. This Special Operations LCO then allows changing the Table 1.1-1 reactor mode switch position requirements to include the startup/hot standby position, such that the SDM tests may be performed while in MODE 5.

APPLICABILITY

These SDM test Special Operations requirements are only applicable if the SDM tests are to be performed while in MODE 5 with the reactor vessel head removed or the head bolts not fully tensioned. Additional requirements during these tests to enforce control rod withdrawal sequences and restrict other CORE ALTERATIONS provide protection against potential reactivity excursions. Operations in all other MODES are unaffected by this LCO.

ACTIONS

A.1 and A.2

With one or more control rods discovered uncoupled during this Special Operation, a controlled insertion of each uncoupled control rod is required; either to attempt

(continued)

BASES

ACTIONS

A.1 and A.2 (continued)

recoupling, or to preclude a control rod drop. This controlled insertion is preferred since, if the control rod fails to follow the drive as it is withdrawn (i.e., is "stuck" in an inserted position), placing the reactor mode switch in the shutdown position per Required Action B.1 could cause substantial secondary damage. If recoupling is not accomplished, operation may continue, provided the control rods are fully inserted within 3 hours and disarmed (electrically or hydraulically) within 4 hours. Inserting a control rod ensures the shutdown and scram capabilities are not adversely affected. The control rod is disarmed to prevent inadvertent withdrawal during subsequent operations. The control rods can be hydraulically disarmed by closing the drive water and exhaust water isolation valves. Electrically, the control rods can be disarmed by disconnecting power from all four directional control valve solenoids. Required Action A.1 is modified by a Note that allows the RWM to be bypassed if required to allow insertion of the inoperable control rods and continued operation. LCO 3.3.2.1 ACTIONS provide additional requirements when the RWM is bypassed to ensure compliance with the CRDA analysis.

The allowed Completion Times are reasonable, considering the small number of allowed inoperable control rods, and provide time to insert and disarm the control rods in an orderly manner and without challenging plant systems.

Condition A is modified by a Note allowing separate Condition entry for each uncoupled control rod. This is acceptable since the Required Actions for this Condition provide appropriate compensatory actions for each uncoupled control rod. Complying with the Required Actions may allow for continued operation. Subsequent uncoupled control rods are governed by subsequent entry into the Condition and application of the Required Actions.

B.1

With one or more of the requirements of this LCO not met for reasons other than an uncoupled control rod, the testing should be immediately stopped by placing the reactor mode

(continued)

BASES

ACTIONS

B.1 (continued)

switch in the shutdown or refuel position. This results in a condition that is consistent with the requirements for MODE 5 where the provisions of this Special Operations LCO are no longer required.

SURVEILLANCE
REQUIREMENTS

SR 3.10.7.1, SR 3.10.7.2, and SR 3.10.7.3

LCO 3.3.1.1, Functions 2.a and 2.d, made applicable in this Special Operations LCO, are required to have applicable Surveillances met to establish that this Special Operations LCO is being met (SR 3.10.7.1). However, the control rod withdrawal sequences during the SDM tests may be enforced by the RWM (LCO 3.3.2.1, Function 2, MODE 2 requirements) or by a second licensed operator (Reactor Operator or Senior Reactor Operator) or other task qualified member of the technical staff (e.g., technical advisor or reactor engineer). As noted, either the applicable SRs for the RWM (LCO 3.3.2.1) must be satisfied according to the applicable Frequencies (SR 3.10.7.2), or the proper movement of control rods must be verified (SR 3.10.7.3). This latter verification (i.e., SR 3.10.7.3) must be performed during control rod movement to prevent deviations from the specified sequence. These Surveillances provide adequate assurance that the specified test sequence is being followed.

SR 3.10.7.4

Periodic verification of the administrative controls established by this LCO will ensure that the reactor is operated within the bounds of the safety analysis. The 12 hour Frequency is intended to provide appropriate assurance that each operating shift is aware of and verifies compliance with these Special Operations LCO requirements.

SR 3.10.7.5

Coupling verification is performed to ensure the control rod is connected to the control rod drive mechanism and will perform its intended function when necessary. The

(continued)

BASES

SURVEILLANCE
REQUIREMENTS

SR 3.10.7.5 (continued)

verification is required to be performed any time a control rod is withdrawn to the "full-out" notch position or prior to declaring the control rod OPERABLE after work on the control rod or CRD System that could affect coupling. This Frequency is acceptable, considering the low probability that a control rod will become uncoupled when it is not being moved as well as operating experience related to uncoupling events.

SR 3.10.7.6

CRD charging water header pressure verification is performed to ensure the motive force is available to scram the control rods in the event of a scram signal. Since the reactor is depressurized in MODE 5, there is insufficient reactor pressure to scram the control rods. Verification of charging water header pressure ensures that if a scram were required, capability for rapid control rod insertion would exist. The minimum pressure of 940 psig is well below the expected pressure of 1400 psig to 1500 psig while still ensuring sufficient pressure for rapid control rod insertion. The 7 day Frequency has been shown to be acceptable through operating experience and takes into account indications available in the control room.

REFERENCES

1. UFSAR, Section 15.4.10.
2. XN-NF-80-19(P)(A), Volume 1, Supplement 2, Section 7.1, Exxon Nuclear Methodology for Boiling Water Reactor Neutronics Methods for Design Analysis, (as specified in Technical Specification 5.6.5).
3. NEDE-24011-P-A-US, General Electric Standard Application for Reactor Fuel, (as specified in Technical Specification 5.6.5).
4. Letter, T.A. Pickens (BWROG) to G.C. Lainas (NRC), "Amendment 17 to General Electric Licensing Topical Report NEDE-24011-P-A," BWROG-8644, August 15, 1986.

(continued)

BASES

- REFERENCES (continued)
5. NFSR-0091, Benchmark of CASMO/MICROBURN BWR Nuclear Design Methods, Commonwealth Edison Topical Report, (as specified in Technical Specification 5.6.5).
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3.4 REACTOR COOLANT SYSTEM (RCS)

3.4.4 Safety/Relief Valves (S/RVs)

LC0 3.4.4 The safety function of 12 S/RVs shall be OPERABLE.

APPLICABILITY: MODES 1, 2, and 3.

ACTIONS

CONDITION	REQUIRED ACTION	COMPLETION TIME
A. One or more required S/RVs inoperable.	A.1 Be in MODE 3.	12 hours
	<u>AND</u>	
	A.2 Be in MODE 4.	36 hours

SURVEILLANCE REQUIREMENTS

SURVEILLANCE	FREQUENCY												
<p>SR 3.4.4.1 -----NOTE----- Less than or equal to two required S/RVs may be changed to a lower setpoint group. -----</p> <p>Verify the safety function lift setpoints of the required S/RVs are as follows:</p> <table data-bbox="470 640 1006 913"> <thead> <tr> <th data-bbox="470 640 625 714"><u>Number of S/RVs</u></th> <th data-bbox="852 640 1006 714"><u>Setpoint (psig)</u></th> </tr> </thead> <tbody> <tr> <td data-bbox="519 745 544 777">2</td> <td data-bbox="828 745 1006 777">1205 ± 36.1</td> </tr> <tr> <td data-bbox="519 777 544 808">3</td> <td data-bbox="828 777 1006 808">1195 ± 35.8</td> </tr> <tr> <td data-bbox="519 808 544 840">2</td> <td data-bbox="828 808 1006 840">1185 ± 35.5</td> </tr> <tr> <td data-bbox="519 840 544 871">4</td> <td data-bbox="828 840 1006 871">1175 ± 35.2</td> </tr> <tr> <td data-bbox="519 871 544 903">2</td> <td data-bbox="828 871 1006 903">1150 ± 34.5</td> </tr> </tbody> </table> <p>Following testing, lift settings shall be within ± 1%.</p>	<u>Number of S/RVs</u>	<u>Setpoint (psig)</u>	2	1205 ± 36.1	3	1195 ± 35.8	2	1185 ± 35.5	4	1175 ± 35.2	2	1150 ± 34.5	<p>In accordance with the Inservice Testing Program</p>
<u>Number of S/RVs</u>	<u>Setpoint (psig)</u>												
2	1205 ± 36.1												
3	1195 ± 35.8												
2	1185 ± 35.5												
4	1175 ± 35.2												
2	1150 ± 34.5												