B 3.3 INSTRUMENTATION

B 3.3.5.1 Emergency Core Cooling System (ECCS) Instrumentation

BASES

BACKGROUND

The purpose of the ECCS instrumentation is to initiate appropriate responses from the systems to ensure that fuel is adequately cooled in the event of a design basis accident or transient.

For most anticipated operational occurrences (AOOs) and Design Basis Accidents (DBAs), a wide range of dependent and independent parameters are monitored.

The ECCS instrumentation actuates low pressure core spray (LPCS), low pressure coolant injection (LPCI), high pressure core spray (HPCS), Automatic Depressurization System (ADS), and the diesel generators (DGs). The equipment involved with each of these systems is described in the Bases for LCO 3.5.1, "ECCS – Operating," or LCO 3.8.1, "AC Sources—Operating."

Low Pressure Core Spray System

The LPCS System may be initiated by either automatic or manual means. Automatic initiation occurs for conditions of Reactor Vessel Water Level – Low Low Low, Level 1 or Drywell Pressure – High. Reactor vessel water level is monitored by two redundant differential pressure transmitters, each providing input to a trip unit. Drywell pressure is monitored by two pressure switches. The outputs of the four signals (two trip units and two pressure switches) are connected to relays whose contacts are arranged in a one-out-of-two taken twice logic. The logic will provide an initiation signal if both reactor vessel water level channels or both drywell pressure channels trip. In addition, the logic will provide an initiation signal if a certain combination of reactor vessel water level and drywell pressure channels trip. The LPCS initiation signal is a sealed in signal and must be manually reset. The LPCS initiation signal also provides an initiation signal to the Division 1 LPCI initiation logic. The logic can also be

(continued)

BASES

BACKGROUND

Low Pressure Core Spray System (continued)

initiated by use of a manual push button. Upon receipt of an initiation signal, the LPCS pump is automatically started if normal AC power is available; otherwise the pump is started immediately after AC power is available from the DG.

The LPCS test line isolation valve, which is also a primary containment isolation valve (PCIV), is closed on a LPCS initiation signal to allow full system flow assumed in the accident analysis and maintains containment isolation in the event LPCS is not operating.

The LPCS pump discharge flow is monitored by a flow switch that senses the differential pressure across a flow element in the pump discharge line. When the pump is running and discharge flow is low enough that pump overheating may occur, the minimum flow return line valve is opened. The valve is automatically closed if flow is above the minimum flow setpoint to allow the full system flow assumed in the accident analysis.

The LPCS System also monitors the pressure within the injection line and in the reactor vessel to ensure that, before the injection valve opens, the injection line pressure and reactor pressure have fallen to a value below the LPCS System's maximum design pressure. The pressure in the LPCS injection line is monitored by one pressure switch while reactor pressure is monitored by two pressure switches. The injection valve will receive an open permissive signal if the LPCS injection line pressure switch senses low pressure (one-out-of-one logic) and if any one of the reactor pressure switches sense low pressure (one-out-of-two logic). The reactor vessel pressure switches also provide a permissive signal in the Division 1 LPCI injection valve.

Low Pressure Coolant Injection Subsystems

The LPCI is an operating mode of the Residual Heat Removal (RHR) System, with three LPCI subsystems. The LPCI subsystems may be initiated by automatic or manual means. Automatic initiation occurs for conditions of Reactor Vessel Water Level – Low Low Low, Level 1 or Drywell Pressure – High.

(continued)

BASES

BACKGROUND

Low Pressure Coolant Injection Subsystems (continued)

Reactor vessel water level is monitored by two redundant differential pressure transmitters per division, each providing input to a trip unit. Drywell pressure is monitored by two pressure switches per division. The outputs of the four Division 2 LPCI (loops B and C) signals (two trip units and two pressure switches) are connected to relays whose contacts are arranged in a one-out-of-two taken twice logic. The logic will provide an initiation signal if both reactor vessel water level channels or both drywell pressure channels trip. In addition, the logic will provide an initiation signal if certain combinations of reactor vessel water level and drywell pressure channels trip. The Division 1 LPCI (loop A) receives its initiation signal from the LPCS logic, which uses a similar one-out-of-two taken twice logic. The two divisions can also be initiated by use of a manual push button (one per division, with the LPCI A manual push button being common with LPCS). Once an initiation signal is received by the LPCI control circuitry, the signal is sealed in until manually reset.

Upon receipt of an initiation signal, the LPCI Pump C is automatically started if normal AC power is available; otherwise the pump is started immediately after power is available from the DG while LPCI pumps A and B are automatically started if offsite power is available; otherwise the pumps are started in approximately 5 seconds after AC power from the DG is available. These time delays limit the loading on the standby power sources.

Each LPCI subsystem's discharge flow is monitored by a flow switch that senses the differential pressure across a flow element in the pump discharge line. When a pump is running and discharge flow is low enough that pump overheating may occur, the respective minimum flow return line valve is opened. The valve is automatically closed if flow is above the minimum flow setpoint to allow the full system flow assumed in the analyses.

The RHR test line suppression pool cooling isolation and suppression pool spray isolation valves (which are also PCIVs) are closed on a LPCI initiation signal to allow full system flow assumed in the accident analysis and maintain containment isolated in the event LPCI is not operating.

(continued)

BASES

BACKGROUND

Low Pressure Coolant Injection Subsystems (continued)

The LPCI subsystems monitor the pressure within the associated injection line and in the reactor vessel to ensure that, prior to an injection valve opening, the injection line pressure and reactor pressure have fallen to a value below the LPCI subsystem's maximum design pressure. The pressure within each LPCI injection line is monitored by one pressure switch, while reactor pressure is monitored by two pressure switches, per division. The associated injection valve will receive an open permissive signal if the LPCI injection line pressure switch senses low pressure (one-out-of-one logic) and if any one of the associated reactor pressure switches sense low pressure (one-out-of-two logic, per division). The Division 1 LPCI (loop A) receives its reactor pressure signals from the LPCS logic.

High Pressure Core Spray System

The HPCS System may be initiated by either automatic or manual means. Automatic initiation occurs for conditions of Reactor Vessel Water Level — Low Low, Level 2 or Drywell Pressure — High. Reactor vessel water level is monitored by four redundant differential pressure transmitters and drywell pressure is monitored by four redundant pressure switches. Each differential pressure transmitter provides input to a trip unit. The outputs of the trip units are connected to relays whose contacts are arranged in a one-out-of-two taken twice logic. Each pressure switch provides input to a relay whose contact is arranged in a one-out-of-two taken twice logic. The logic can also be initiated by use of a manual push button. The HPCS System initiation signal is a sealed in signal and must be manually reset.

The HPCS pump discharge flow and pressure are monitored by a differential pressure switch and a pressure switch, respectively. When the pump is running (as indicated by the pressure switch) and discharge flow is low enough that pump overheating may occur, the minimum flow return line valve is opened. The valve is automatically closed if flow is above the minimum flow setpoint to allow full system flow assumed in the accident analyses.

(continued)

BASES

BACKGROUND

High Pressure Core Spray System (continued)

The HPCS full flow test line isolation valve to the suppression pool (which is also a PCIV) is closed on a HPCS initiation signal to allow full system flow assumed in the accident analyses and maintain containment isolated in the event HPCS is not operating.

The HPCS System provides makeup water to the reactor until the reactor vessel water level reaches the high water level (Level 8) trip, at which time the HPCS injection valve closes. The HPCS pump will continue to run on minimum flow. The logic is two-out-of-two to provide high reliability of the HPCS System. The injection valve automatically reopens if a low low water level signal is subsequently received.

Automatic Depressurization System

ADS may be initiated by either automatic or manual means. Automatic initiation occurs when signals indicating Reactor Vessel Water Level – Low Low Low, Level 1; Drywell Pressure – High or ADS Drywell Pressure Bypass Timer; confirmed Reactor Vessel Water Level – Low, Level 3; and either LPCS or LPCI Pump Discharge Pressure – High are all present, and the ADS Initiation Timer has timed out. There are two differential pressure transmitters for Reactor Vessel Water Level – Low Low Low, Level 1, two pressure switches for Drywell Pressure – High, and one differential pressure transmitter for confirmed Reactor Vessel Water Level – Low, Level 3 in each of the two ADS trip systems. Each of the transmitters connects to a trip unit, which then drives a relay whose contacts input to the initiation logic. Each pressure switch drives a relay whose contact also inputs to the initiation logic.

Each ADS trip system (trip system A and trip system B) includes a time delay between satisfying the initiation logic and the actuation of the ADS valves. The time delay chosen is long enough that the HPCS has time to operate to recover to a level above Level 1, yet not so long that the LPCI and LPCS systems are unable to adequately cool the fuel if the HPCS fails to maintain level. An alarm in the control room is annunciated when either of the timers is running. Resetting the ADS initiation signals resets the ADS Initiation Timers.

(continued)

BASES

BACKGROUND

Automatic Depressurization System (continued)

The ADS also monitors the discharge pressures of the three LPCI pumps and the LPCS pump. Each ADS trip system includes two discharge pressure permissive switches from each of the two low pressure ECCS pumps in the associated Division (i.e., Division 1 ECCS inputs to ADS trip system A and Division 2 ECCS inputs to ADS trip system B). The signals are used as a permissive for ADS actuation, indicating that there is a source of core coolant available once the ADS has depressurized the vessel. Any one of the four low pressure pumps provides sufficient core coolant flow to permit automatic depressurization.

The ADS logic in each trip system is arranged in two strings. One string has a contact from each of the following variables: Reactor Vessel Water Level – Low Low Low, Level 1; Drywell Pressure – High or ADS Drywell Pressure Bypass Timer; Reactor Vessel Water Level – Low, Level 3; ADS Initiation Timer; and two low pressure ECCS Discharge Pressure – High contacts (one from each divisional pump). The other string has a contact from each of the following variables: Reactor Vessel Water Level – Low Low Low, Level 1; Drywell Pressure – High; ADS Drywell Pressure Bypass Timer; and two low pressure ECCS Discharge Pressure – High contacts (one from each divisional pump). To initiate an ADS trip system, the following applicable contacts must close in the associated string: Reactor Vessel Water Level – Low Low Low, Level 1; Drywell Pressure – High or ADS Drywell Pressure Bypass Timer; Reactor Vessel Water Level – Low, Level 3 (one string only); ADS Initiation Timer (one string only); and one of the two low pressure ECCS Discharge Pressure – High contacts.

Either ADS trip system A or trip system B will cause all the ADS valves to open. Once the Drywell Pressure – High or ADS initiation signals are present, they are individually sealed in until manually reset.

Manual initiation is accomplished by arming and depressing both ADS A trip system strings (Division 1) or both ADS B trip system strings (Division 2) which will cause the ADS valves to open with no time delay. No permissive interlocks

(continued)

BASES

BACKGROUND

Automatic Depressurization System (continued)

are required for the manual initiation. Manual inhibit switches are provided in the control room for ADS; however, their function is not required for ADS OPERABILITY (provided ADS is not inhibited when required to be OPERABLE).

Diesel Generators

The Division 1, 2, and 3 DGs may be initiated by either automatic or manual means. Automatic initiation occurs for conditions of Reactor Vessel Water Level – Low Low Low, Level 1 or Drywell Pressure – High for DGs 0 and 1A (2A), and Reactor Vessel Water Level – Low Low, Level 2 or Drywell Pressure – High for DG 1B (2B). DG 0 is common to both units and will start on an initiation signal from both units. The other DGs will only start on an initiation signal from the unit ECCS logic. The DGs are also initiated upon loss of voltage signals. (Refer to Bases for LCO 3.3.8.1, "Loss of Power (LOP) Instrumentation," for a discussion of these signals.) The DGs receive their initiation signals from the associated Divisions' ECCS logic (i.e., DG 0 receives an initiation signal from Division 1 ECCS (LPCS and LPCI A); DG 1A/2A receives an initiation signal from Division 2 ECCS (LPCI B and LPCI C); and DG 1B/2B receives an initiation signal from Division 3 ECCS (HPCS)). The DGs can also be started manually from the control room and locally in the associated DG room. The DG initiation signal is a sealed in signal and must be manually reset. The DG initiation logic is reset by resetting the associated ECCS initiation logic. Upon receipt of a LOCA initiation signal, each DG is automatically started, is ready to load in approximately 13 seconds, and will run in standby conditions (rated voltage and speed, with the DG output breaker open). The DGs will only energize their respective emergency buses if a loss of offsite power occurs. (Refer to Bases for LCO 3.3.8.1.)

APPLICABLE SAFETY ANALYSES, LCO, and APPLICABILITY

The actions of the ECCS are explicitly assumed in the safety analyses of References 1, 2, and 3. The ECCS is initiated to preserve the integrity of the fuel cladding by limiting the post LOCA peak cladding temperature to less than the 10 CFR 50.46 limits.

(continued)

BASES

APPLICABLE SAFETY ANALYSES, LCO, and APPLICABILITY (continued)

ECCS instrumentation satisfies Criterion 3 of 10 CFR 50.36(c)(2)(ii). Certain instrumentation Functions are retained for other reasons and are described below in the individual Functions discussion.

The OPERABILITY of the ECCS instrumentation is dependent upon the OPERABILITY of the individual instrumentation channel Functions specified in Table 3.3.5.1-1. Each Function must have a required number of OPERABLE channels, with their setpoints within the specified Allowable Values, where appropriate. The actual setpoint is calibrated consistent with applicable setpoint methodology assumptions. Each ECCS subsystem must also respond within its assumed response time. Table 3.3.5.1-1, footnote (b), is added to show that certain ECCS instrumentation Functions are also required to be OPERABLE to perform DG initiation.

Allowable Values are specified for each ECCS Function specified in the Table. Nominal trip setpoints are specified in the setpoint calculations. The nominal setpoints are selected to ensure that the setpoints do not exceed the Allowable Value between CHANNEL CALIBRATIONS. Operation with a trip setpoint less conservative than the nominal trip setpoint, but within its Allowable Value, is acceptable. A channel is inoperable if its actual trip setpoint is not within its required Allowable Value. Trip setpoints are those predetermined values of output at which an action should take place. The setpoints are compared to the actual process parameter (e.g., reactor vessel water level), and when the measured output value of the process parameter exceeds the setpoint, the associated device (e.g., trip unit) changes state. The analytic limits are derived from the limiting values of the process parameters obtained from the safety analysis. The trip setpoints are determined from the analytic limits, corrected for defined process, calibration, and instrument errors. The Allowable Values are then determined, based on the trip setpoint values, by accounting for the calibration based errors. These calibration based errors are limited to reference accuracy, instrument drift, errors associated with measurement and test equipment, and calibration tolerance of loop components. The trip setpoints and Allowable Values determined in this manner provide adequate protection

(continued)

BASES

APPLICABLE SAFETY ANALYSES, LCO, and APPLICABILITY (continued)

because instrument uncertainties, process effects, calibration tolerances, instrument drift, and severe environment errors (for channels that must function in harsh environments as defined by 10 CFR 50.49) are accounted for and appropriately applied for the instrumentation.

In general, the individual Functions are required to be OPERABLE in the MODES or other specified conditions that may require ECCS (or DG) initiation to mitigate the consequences of a design basis accident or transient. To ensure reliable ECCS and DG function, a combination of Functions is required to provide primary and secondary initiation signals.

The specific Applicable Safety Analyses, LCO, and Applicability discussions are listed below on a Function by Function basis.

Low Pressure Core Spray and Low Pressure Coolant Injection Systems

1.a, 2.a. Reactor Vessel Water Level – Low Low Low, Level 1

Low reactor pressure vessel (RPV) water level indicates that the capability to cool the fuel may be threatened. Should RPV water level decrease too far, fuel damage could result. The low pressure ECCS and associated DGs are initiated at Level 1 to ensure that core spray and flooding functions are available to prevent or minimize fuel damage. The Reactor Vessel Water Level – Low Low Low, Level 1 is one of the Functions assumed to be OPERABLE and capable of initiating the ECCS during the transients analyzed in References 1 and 3. In addition, the Reactor Vessel Water Level – Low Low Low, Level 1 Function is directly assumed in the analysis of the recirculation line break (Ref. 2). The core cooling function of the ECCS, along with the scram action of the Reactor Protection System (RPS), ensures that the fuel peak cladding temperature remains below the limits of 10 CFR 50.46.

(continued)

BASES

APPLICABLE SAFETY ANALYSES, LCO, and APPLICABILITY

1.a, 2.a. Reactor Vessel Water Level – Low Low Low, Level 1 (continued)

Reactor Vessel Water Level – Low Low Low, Level 1 signals are initiated from four differential pressure transmitters that sense the difference between the pressure due to a constant column of water (reference leg) and the pressure due to the actual water level (variable leg) in the vessel.
The Reactor Vessel Water Level – Low Low Low, Level 1 Allowable Value is chosen to allow time for the low pressure core flooding systems to activate and provide adequate cooling.

Two channels of Reactor Vessel Water Level – Low Low Low, Level 1 Function per associated Division are only required to be OPERABLE when the associated ECCS is required to be OPERABLE, to ensure that no single instrument failure can preclude ECCS initiation. (Two channels input to LPCS, LPCI A, and the associated Division 1 DG, while the other two channels input to LPCI B, LPCI C, and Division 2 DG.) Refer to LCO 3.5.1 and LCO 3.5.2, "ECCS – Shutdown," for Applicability Bases for the low pressure ECCS subsystems.

1.b, 2.b. Drywell Pressure – High

High pressure in the drywell could indicate a break in the reactor coolant pressure boundary (RCPB). The low pressure ECCS and associated DGs are initiated upon receipt of the Drywell Pressure – High Function in order to minimize the possibility of fuel damage. The core cooling function of the ECCS, along with the scram action of the RPS, ensures that the fuel peak cladding temperature remains below the limits of 10 CFR 50.46.

High drywell pressure signals are initiated from four pressure switches that sense drywell pressure. The Allowable Value was selected to be as low as possible and be indicative of a LOCA inside primary containment.

The Drywell Pressure – High Function is required to be OPERABLE when the associated ECCS is required to be OPERABLE in conjunction with times when the primary containment is

(continued)

BASES

APPLICABLE SAFETY ANALYSES, LCO, and APPLICABILITY

1.b, 2.b. Drywell Pressure – High (continued)

required to be OPERABLE. Thus, four channels of the LPCS and LPCI Drywell Pressure – High Function are required to be OPERABLE in MODES 1, 2, and 3 to ensure that no single instrument failure can preclude ECCS initiation. (Two channels input to LPCS, LPCI A, and the Division 1 DG, while the other two channels input to LPCI B, LPCI C, and the Division 2 DG.) In MODES 4 and 5, the Drywell Pressure – High Function is not required since there is insufficient energy in the reactor to pressurize the primary containment to Drywell Pressure – High setpoint. Refer to LCO 3.5.1 for Applicability Bases for the low pressure ECCS subsystems.

1.c, 2.c. LPCI Pump A and Pump B Start – Time Delay Relay

The purpose of this time delay is to stagger the start of the two ECCS pumps that are in each of Divisions 1 and 2, thus limiting the starting transients on the 4.16 kV emergency buses. This Function is only necessary when power is being supplied from the standby power sources (DG). On ECCS initiation, the time delay is bypassed if the normal feed breaker to the Class 1E switchgear is closed. The LPCI Pump Start – Time Delay Relays are assumed to be OPERABLE in the accident and transient analyses requiring ECCS initiation. That is, the analysis assumes that the pumps will initiate when required and excess loading will not cause failure of the standby power sources (DG).

There are two LPCI Pump Start – Time Delay Relays, one in each of the RHR "A" and RHR "B" pump start logic circuits. While each time delay relay is dedicated to a single pump start logic, a single failure of a LPCI Pump Start – Time Delay Relay could result in the failure of the two low pressure ECCS pumps, powered from the emergency bus, to perform their intended function within the assumed ECCS RESPONSE TIMES (e.g., as in the case where both ECCS pumps on one emergency bus start simultaneously due to an inoperable time delay relay). This still leaves two of the four low pressure ECCS pumps OPERABLE; thus, the single failure criterion is met (i.e., loss of one instrument does not preclude ECCS initiation). The Allowable Value for the LPCI Pump Start – Time Delay Relays is chosen to be short enough so that ECCS operation is not degraded.

(continued)

BASES

APPLICABLE SAFETY ANALYSES, LCO, and APPLICABILITY

1.c, 2.c. LPCI Pump A and Pump B Start – Time Delay Relay (continued)

Each LPCI Pump Start – Time Delay Relay Function is required to be OPERABLE when the associated LPCI subsystem is required to be OPERABLE. Refer to LCO 3.5.1 and LCO 3.5.2 for Applicability Bases for the LPCI subsystems.

1.d, 1.g, 2.d, 2.f. Reactor Steam Dome Pressure – Low (Injection Permissive) and LPCS and LPCI Injection Line Pressure – Low (Injection Permissive)

Low reactor steam dome pressure and injection line pressure signals are used as permissives for the low pressure ECCS subsystems. This ensures that, prior to opening the injection valves of the low pressure ECCS subsystems, the reactor pressure has fallen to a value below these subsystems maximum design pressure. The Reactor Steam Dome Pressure – Low (Injection Permissive) and LPCS and LPCI Injection Line Pressure – Low (Injection Permissive) are two of the Functions assumed to be OPERABLE and capable of permitting initiation of the ECCS during the transients analyzed in References 1 and 3. In addition, the Reactor Steam Dome Pressure – Low (Injection Permissive) and LPCS and LPCI Injection Line Pressure – Low (Injection Permissive) Functions are directly assumed in the analysis of the recirculation line break (Ref. 2). The core cooling function of the ECCS, along with the scram action of the RPS, ensures that the fuel peak cladding temperature remains below the limits of 10 CFR 50.46.

The Reactor Steam Dome Pressure – Low (Injection Permissive) signals are initiated from four pressure switches that sense the reactor dome pressure. The LPCS and LPCI Injection Line Pressure – Low (Injection Permissive) signals are initiated from four pressure switches that sense the pressure in the injection line (one switch for each low pressure ECCS injection line). The Allowable Values are low enough to

(continued)

BASES

APPLICABLE SAFETY ANALYSES, LCO, and APPLICABILITY

1.d, 1.g, 2.d, 2.f. Reactor Steam Dome Pressure – Low (Injection Permissive) and LPCS and LPCI Injection Line Pressure – Low (Injection Permissive) (continued)

prevent overpressurizing the equipment in the low pressure ECCS, but high enough to ensure that the ECCS injection prevents the fuel peak cladding temperature from exceeding the limits of 10 CFR 50.46.

Two channels of Reactor Steam Dome Pressure – Low (Injection Permissive) Function per associated Division and one channel of LPCS and LPCI Injection Line Pressure – Low (Injection Permissive) per associated injection line are only required to be OPERABLE when the associated ECCS is required to be OPERABLE to ensure that no single instrument failure can preclude ECCS initiation. (Two channels of Reactor Vessel Pressure – Low (Injection Permissive) are required for LPCS and LPCI A, while two other channels are required for LPCI B and LPCI C. In addition, one channel of LPCS Injection Line Pressure – Low (Injection Permissive) is required for LPCS, while one channel of LPCI Injection Line Pressure is required for each LPCI subsystem.) Refer to LCO 3.5.1 and LCO 3.5.2 for Applicability Bases for the low pressure ECCS subsystems.

1.e, 1.f, 2.e. LPCS and LPCI Pump Discharge Flow – Low (Bypass)

The minimum flow instruments are provided to protect the associated low pressure ECCS pump from overheating when the pump is operating and the associated injection valve is not sufficiently open. The minimum flow line valve is opened when low flow is sensed, and the valve is automatically closed when the flow rate is adequate to protect the pump. The LPCI and LPCS Pump Discharge Flow – Low (Bypass) Functions are assumed to be OPERABLE and capable of closing the minimum flow valves to ensure that the low pressure ECCS flows assumed during the transients and accidents analyzed in References 1, 2, and 3 are met. The core cooling function of the ECCS, along with the scram action of the RPS, ensures that the fuel peak cladding temperature remains below the limits of 10 CFR 50.46.

(continued)

BASES

APPLICABLE SAFETY ANALYSES, LCO, and APPLICABILITY

1.e, 1.f, 2.e. LPCS and LPCI Pump Discharge Flow—Low (Bypass) (continued)

One flow switch per ECCS pump is used to detect the associated subsystems flow rate. The logic is arranged such that each switch causes its associated minimum flow valve to open when flow is low with the pump running. The logic will close the minimum flow valve once the closure setpoint is exceeded. The LPCI minimum flow valves are time delayed such that the valves will not open for approximately 8 seconds after the switches detect low flow. The time delay is provided to limit reactor vessel inventory loss during the startup of the RHR shutdown cooling mode. The Pump Discharge Flow—Low (Bypass) Allowable Values are high enough to ensure that the pump flow rate is sufficient to protect the pump, yet low enough to ensure that the closure of the minimum flow valve is initiated to allow full flow into the core.

Each channel of Pump Discharge Flow—Low (Bypass) Function (one LPCS channel and three LPCI channels) is only required to be OPERABLE when the associated ECCS is required to be OPERABLE, to ensure that no single instrument failure can preclude the ECCS function. Refer to LCO 3.5.1 and LCO 3.5.2 for Applicability Bases for the low pressure ECCS subsystems.

1.h, 2.g. Manual Initiation

The Manual Initiation push button channels introduce signals into the appropriate ECCS logic to provide manual initiation capability and are redundant to the automatic protective instrumentation. There is one push button for each of the two Divisions of low pressure ECCS (i.e., Division 1 ECCS, LPCS and LPCI A; Division 2 ECCS, LPCI B and LPCI C).

The Manual Initiation Function is not assumed in any accident or transient analyses in the UFSAR. However, the Function is retained for overall redundancy and diversity of the low pressure ECCS function as required by the NRC in the plant licensing basis.

(continued)

BASES

APPLICABLE SAFETY ANALYSES, LCO, and APPLICABILITY

1.h, 2.g. Manual Initiation (continued)

There is no Allowable Value for this Function since the channels are mechanically actuated based solely on the position of the push buttons. Each channel of the Manual Initiation Function (one channel per division) is only required to be OPERABLE when the associated ECCS is required to be OPERABLE. Refer to LCO 3.5.1 and LCO 3.5.2 for Applicability Bases for the low pressure ECCS subsystems.

High Pressure Core Spray System

3.a. Reactor Vessel Water Level – Low Low, Level 2

Low RPV water level indicates that the capability to cool the fuel may be threatened. Should RPV water level decrease too far, fuel damage could result. Therefore, the HPCS System and associated DG is initiated at Level 2 to maintain level above the top of the active fuel. The Reactor Vessel Water Level – Low Low, Level 2 is one of the Functions assumed to be OPERABLE and capable of initiating HPCS during the transients analyzed in References 1 and 3. The Reactor Vessel Water Level – Low Low, Level 2 Function associated with HPCS is directly assumed in the analysis of the recirculation line break (Ref. 2). The core cooling function of the ECCS, along with the scram action of the RPS, ensures that the fuel peak cladding temperature remains below the limits of 10 CFR 50.46.

Reactor Vessel Water Level – Low Low, Level 2 signals are initiated from four differential pressure transmitters that sense the difference between the pressure due to a constant column of water (reference leg) and the pressure due to the actual water level (variable leg) in the vessel. The Reactor Vessel Water Level – Low Low, Level 2 Allowable Value is chosen such that for complete loss of feedwater flow, the Reactor Core Isolation Cooling (RCIC) System flow with HPCS assumed to fail will be sufficient to avoid initiation of low pressure ECCS at Reactor Vessel Water Level – Low Low Low, Level 1.

(continued)

BASES

APPLICABLE SAFETY ANALYSES, LCO, and APPLICABILITY

3.a. Reactor Vessel Water Level – Low Low, Level 2 (continued)

Four channels of Reactor Vessel Water Level – Low Low, Level 2 Function are only required to be OPERABLE when HPCS is required to be OPERABLE to ensure that no single instrument failure can preclude HPCS initiation. Refer to LCO 3.5.1 and LCO 3.5.2 for HPCS Applicability Bases.

3.b. Drywell Pressure – High

High pressure in the drywell could indicate a break in the RCPB. The HPCS System and associated DG are initiated upon receipt of the Drywell Pressure – High Function in order to minimize the possibility of fuel damage. The core cooling function of the ECCS, along with the scram action of the RPS, ensures that the fuel peak cladding temperature remains below the limits of 10 CFR 50.46.

Drywell Pressure – High signals are initiated from four pressure switches that sense drywell pressure. The Allowable Value was selected to be as low as possible and be indicative of a LOCA inside primary containment.

The Drywell Pressure – High Function is required to be OPERABLE when HPCS is required to be OPERABLE in conjunction with times when the primary containment is required to be OPERABLE. Thus, four channels of the HPCS Drywell Pressure – High Function are required to be OPERABLE in MODES 1, 2, and 3, to ensure that no single instrument failure can preclude ECCS initiation. In MODES 4 and 5, the Drywell Pressure – High Function is not required since there is insufficient energy in the reactor to pressurize the drywell to the Drywell Pressure – High Functions setpoint. Refer to LCO 3.5.1 for the Applicability Bases for the HPCS System.

3.c. Reactor Vessel Water Level – High, Level 8

High RPV water level indicates that sufficient cooling water inventory exists in the reactor vessel such that there is no danger to the fuel. Therefore, the Level 8 signal is used to close the HPCS injection valve to prevent overflow into the main steam lines (MSLs). The Reactor Vessel Water

(continued)

BASES

APPLICABLE SAFETY ANALYSES, LCO, and APPLICABILITY

3.c. Reactor Vessel Water Level – High, Level 8 (continued)

Level – High, Level 8 Function for HPCS isolation is not credited in the accident analysis. It is retained since it is a potentially significant contributor to risk.

Reactor Vessel Water Level – High, Level 8 signals for HPCS are initiated from two level transmitters from the narrow range water level measurement instrumentation. The Reactor Vessel Water Level – High, Level 8 Allowable Value is chosen to isolate flow from the HPCS System prior to water overflowing into the MSLs.

Two channels of Reactor Vessel Water Level – High, Level 8 Function are only required to be OPERABLE when HPCS is required to be OPERABLE to ensure that no single instrument failure can preclude HPCS initiation. Refer to LCO 3.5.1 and LCO 3.5.2 for HPCS Applicability Bases.

3.d, 3.e. HPCS Pump Discharge Pressure – High (Bypass) and HPCS System Flow Rate – Low (Bypass)

The minimum flow instruments are provided to protect the HPCS pump from overheating when the pump is operating and the associated injection valve is not sufficiently open. The minimum flow line valve is opened when low flow and high pump discharge pressure are sensed, and the valve is automatically closed when the flow rate is adequate to protect the pump or the discharge pressure is low (indicating the HPCS pump is not operating). The HPCS System Flow Rate – Low (Bypass) and HPCS Pump Discharge Pressure – High Functions are assumed to be OPERABLE and capable of closing the minimum flow valve to ensure that the ECCS flow assumed during the transients and accidents analyzed in References 1, 2, and 3 are met. The core cooling function of the ECCS, along with the scram action of the RPS, ensures that the fuel peak cladding temperature remains below the limits of 10 CFR 50.46.

One flow switch is used to detect the HPCS System's flow rate. The logic is arranged such that the switch causes the minimum flow valve to open, provided the HPCS pump discharge pressure, sensed by another switch, is high enough

(continued)

BASES

APPLICABLE SAFETY ANALYSES, LCO, and APPLICABILITY

3.d, 3.e. HPCS Pump Discharge Pressure – High (Bypass) and HPCS System Flow Rate – Low (Bypass) (continued)

(indicating the pump is operating). The logic will close the minimum flow valve once the closure setpoint is exceeded. (The valve will also close upon HPCS pump discharge pressure decreasing below the setpoint.)

The HPCS System Flow Rate – Low (Bypass) Allowable Values are high enough to ensure that pump flow rate is sufficient to protect the pump, yet low enough to ensure that the closure of the minimum flow valve is initiated to allow full flow into the core. The HPCS Pump Discharge Pressure – High (Bypass) Allowable Value is set high enough to ensure that the valve will not be open when the pump is not operating.

One channel of each Function is required to be OPERABLE when the HPCS is required to be OPERABLE. Refer to LCO 3.5.1 and LCO 3.5.2 for HPCS Applicability Bases.

3.f. Manual Initiation

The Manual Initiation push button channel introduces a signal into the HPCS logic to provide manual initiation capability and is redundant to the automatic protective instrumentation. There is one push button for the HPCS System.

The Manual Initiation Function is not assumed in any accident or transient analyses in the UFSAR. However, the Function is retained for overall redundancy and diversity of the HPCS function as required by the NRC in the plant licensing basis.

There is no Allowable Value for this Function since the channel is mechanically actuated based solely on the position of the push button. One channel of the Manual Initiation Function is only required to be OPERABLE when the HPCS System is required to be OPERABLE. Refer to LCO 3.5.1 and LCO 3.5.2 for HPCS Applicability Bases.

(continued)

BASES

APPLICABLE SAFETY ANALYSES, LCO, and APPLICABILITY (continued)

Automatic Depressurization System

4.a, 5.a. Reactor Vessel Water Level – Low Low Low, Level 1

Low RPV water level indicates that the capability to cool the fuel may be threatened. Should RPV water level decrease too far, fuel damage could result. Therefore, ADS receives one of the signals necessary for initiation from this Function. The Reactor Vessel Water Level – Low Low Low, Level 1 is one of the Functions assumed to be OPERABLE and capable of initiating the ADS during the accidents analyzed in Reference 2. The core cooling function of the ECCS, along with the scram action of the RPS, ensures that the fuel peak cladding temperature remains below the limits of 10 CFR 50.46.

Reactor Vessel Water Level – Low Low Low, Level 1 signals are initiated from four differential pressure transmitters that sense the difference between the pressure due to a constant column of water (reference leg) and the pressure due to the actual water level (variable leg) in the vessel. The Reactor Vessel Water Level – Low Low Low, Level 1 Allowable Value is chosen high enough to allow time for the low pressure core spray and injection systems to initiate and provide adequate cooling.

Four channels of Reactor Vessel Water Level – Low Low Low, Level 1 Function are only required to be OPERABLE when ADS is required to be OPERABLE to ensure that no single instrument failure can preclude ADS initiation. (Two channels input to ADS trip system A while the other two channels input to ADS trip system B). Refer to LCO 3.5.1 for ADS Applicability Bases.

4.b, 5.b. Drywell Pressure – High

High pressure in the drywell could indicate a break in the RCPB. Therefore, ADS receives one of the signals necessary for initiation from this Function in order to minimize the possibility of fuel damage. The Drywell Pressure – High is assumed to be OPERABLE and capable of initiating the ADS during the accidents analyzed in Reference 2. The core cooling function of the ECCS, along with the scram action of the RPS, ensures that the fuel peak cladding temperature remains below the limits of 10 CFR 50.46.

(continued)

BASES

APPLICABLE SAFETY ANALYSES, LCO, and APPLICABILITY

4.b, 5.b. Drywell Pressure—High (continued)

Drywell Pressure—High signals are initiated from four pressure switches that sense drywell pressure. The Allowable Value was selected to be as low as possible and be indicative of a LOCA inside primary containment.

Four channels of Drywell Pressure—High Function are only required to be OPERABLE when ADS is required to be OPERABLE to ensure that no single instrument failure can preclude ADS initiation. (Two channels input to ADS trip system A while the other two channels input to ADS trip system B.) Refer to LCO 3.5.1 for ADS Applicability Bases.

4.c, 5.c. ADS Initiation Timer

The purpose of the ADS Initiation Timer is to delay depressurization of the reactor vessel to allow the HPCS System time to maintain reactor vessel water level. Since the rapid depressurization caused by ADS operation is one of the most severe transients on the reactor vessel, its occurrence should be limited. By delaying initiation of the ADS Function, the operator is given the chance to monitor the success or failure of the HPCS System to maintain water level, and then to decide whether or not to allow ADS to initiate, to delay initiation further by recycling the timer, or to inhibit initiation permanently. The ADS Initiation Timer Function is assumed to be OPERABLE for the accident analyses of Reference 2 that require ECCS initiation and assume failure of the HPCS System.

There are two ADS Initiation Timer relays, one in each of the two ADS trip systems. The Allowable Value for the ADS Initiation Timer is chosen to be short enough so that there is still time after depressurization for the low pressure ECCS subsystems to provide adequate core cooling.

Two channels of the ADS Initiation Timer Function are only required to be OPERABLE when the ADS is required to be OPERABLE to ensure that no single instrument failure can preclude ADS initiation. (One channel inputs to ADS trip system A while the other channel inputs to ADS trip system B.) Refer to LCO 3.5.1 for ADS Applicability Bases.

(continued)

BASES

APPLICABLE SAFETY ANALYSES, LCO, and APPLICABILITY (continued)

4.d, 5.d. Reactor Vessel Water Level – Low, Level 3 (Confirmatory)

The Reactor Vessel Water Level – Low, Level 3 Function (Confirmatory) is used by the ADS only as a confirmatory low water level signal. ADS receives one of the signals necessary for initiation from Reactor Vessel Water Level – Low Low Low, Level 1 signals. In order to prevent spurious initiation of the ADS due to spurious Level 1 signals, a Level 3 signal must also be received before ADS initiation commences.

Reactor Vessel Water Level – Low, Level 3 (Confirmatory) signals are initiated from two differential pressure transmitters that sense the difference between the pressure due to a constant column of water (reference leg) and the pressure due to the actual water level (variable leg) in the vessel. The Allowable Value for Reactor Vessel Water Level – Low, Level 3 (Confirmatory)is selected at the RPS Level 3 scram Allowable Value for convenience. Refer to LCO 3.3.1.1, "Reactor Protection System (RPS) Instrumentation," for Bases discussion of this Function.

Two channels of Reactor Vessel Water Level – Low, Level 3 (Confirmatory) Function are only required to be OPERABLE when the ADS is required to be OPERABLE to ensure that no single instrument failure can preclude ADS initiation. (One channel inputs to ADS trip system A while the other channel inputs to ADS trip system B.) Refer to LCO 3.5.1 for ADS Applicability Bases.

4.e, 4.f, 5.e. LPCS and LPCI Pump Discharge Pressure – High

The Pump Discharge Pressure – High signals from the LPCS and LPCI pumps (indicating that the associated pump is running) are used as permissives for ADS initiation, indicating that there is a source of low pressure cooling water available once the ADS has depressurized the vessel. Pump Discharge Pressure – High is one of the Functions assumed to be OPERABLE and capable of permitting ADS initiation during the events analyzed in References 2 and 3 with an assumed HPCS failure. For these events, the ADS depressurizes the reactor vessel so that the low pressure ECCS can perform the

(continued)

BASES

APPLICABLE SAFETY ANALYSES, LCO, and APPLICABILITY

4.e, 4.f, 5.e. LPCS and LPCI Pump Discharge Pressure—High (continued)

core cooling functions. This core cooling function of the ECCS, along with the scram action of the RPS, ensures that the fuel peak cladding temperature remains below the limits of 10 CFR 50.46.

Pump discharge pressure signals are initiated from eight pressure switches, two on the discharge side of each of the four low pressure ECCS pumps. In order to generate an ADS permissive in one trip system, it is necessary that only one pump (both channels for the pump) indicate the high discharge pressure condition. The Pump Discharge Pressure—High Allowable Value is less than the pump discharge pressure when the pump is operating in a full flow mode, and high enough to avoid any condition that results in a discharge pressure permissive when the LPCS and LPCI pumps are aligned for injection and the pumps are not running. The actual operating point of this Function is not assumed in any transient or accident analysis.

Eight channels of LPCS and LPCI Pump Discharge Pressure—High Function (two LPCS and two LPCI A channels input to ADS trip system A, while two LPCI B and two LPCI C channels input to ADS trip system B) are only required to be OPERABLE when the ADS is required to be OPERABLE to ensure that no single instrument failure can preclude ADS initiation. Refer to LCO 3.5.1 for ADS Applicability Bases.

4.g, 5.f. ADS Drywell Pressure Bypass Timer

One of the signals required for ADS initiation is Drywell Pressure—High. However, if the event requiring ADS initiation occurs outside the drywell (for example, main steam line break outside primary containment), a high drywell pressure signal may never be present. Therefore, the ADS Drywell Pressure Bypass Timer is used to bypass the Drywell Pressure—High Function after a certain time period has elapsed. The ADS Drywell Pressure Bypass Timer Function instrumentation is retained in the TS because ADS is part of the primary success path for mitigation of a DBA.

(continued)

BASES

APPLICABLE SAFETY ANALYSES, LCO, and APPLICABILITY

4.g, 5.f. ADS Drywell Pressure Bypass Time (continued)

There are four ADS Drywell Pressure Bypass Timer relays, two in each of the two ADS trip systems. The Allowable Value for the ADS Timer is chosen to be short enough that so that there is still time after depressurization for the low pressure ECCS subsystems to provide adequate core cooling.

Four channels of the ADS Drywell Pressure Bypass Timer Function are only required to be OPERABLE when the ADS is required to be OPERABLE to ensure that no single instrument failure can preclude ADS initiation. Refer to LCO 3.5.1 for ADS Applicability Bases.

4.h, 5.g. Manual Initiation

The Manual Initiation push button channels introduce signals into the ADS logic to provide manual initiation capability and are redundant to the automatic protective instrumentation. There are two push buttons for each ADS trip system (total of four).

The Manual Initiation Function is not assumed in any accident or transient analyses in the UFSAR. However, the Function is retained for overall redundancy and diversity of the ADS function as required by the NRC in the plant licensing basis.

There is no Allowable Value for this Function since the channel is mechanically actuated based solely on the position of the push buttons. Four channels of the Manual Initiation Function (two channels per ADS trip system) are only required to be OPERABLE when the ADS is required to be OPERABLE. Refer to LCO 3.5.1 for ADS Applicability Bases.

ACTIONS

A Note has been provided to modify the ACTIONS related to ECCS instrumentation channels. Section 1.3, Completion Times, specifies that once a Condition has been entered, subsequent divisions, subsystems, components, or variables expressed in the Condition, discovered to be inoperable or not within limits, will not result in separate entry into the Condition. Section 1.3 also specifies that Required Actions of the Condition continue to apply for each

(continued)

BASES

ACTIONS (continued)

additional failure, with Completion Times based on initial entry into the Condition. However, the Required Actions for inoperable ECCS instrumentation channels provide appropriate compensatory measures for separate inoperable Condition entry for each inoperable ECCS instrumentation channel.

A.1

Required Action A.1 directs entry into the appropriate Condition referenced in Table 3.3.5.1-1. The applicable Condition specified in the Table is Function dependent. Each time a channel is discovered to be inoperable, Condition A is entered for that channel and provides for transfer to the appropriate subsequent Condition.

B.1, B.2, and B.3

Required Actions B.1 and B.2 are intended to ensure that appropriate actions are taken if multiple, inoperable, untripped channels within the same Function (or in some cases, within the same variable) result in redundant automatic initiation capability being lost for the feature(s). Loss of redundant automatic capability for the low pressure ECCS injection feature in both divisions occurs when the initiation capability is available to less than two pumps from any single variable. Required Action B.1 features would be those that are initiated by Functions 1.a, 1.b, 2.a, and 2.b (i.e., low pressure ECCS and associated DGs). The Required Action B.2 feature would be HPCS System and associated DG. For Required Action B.1, redundant automatic initiation capability is lost if either (a) one or more Function 1.a channels and one or more Function 2.a channels are inoperable and untripped, or (b) one or more Function 1.b channels and one or more Function 2.b channels are inoperable and untripped. For Divisions 1 and 2, since each inoperable channel would have Required Action B.1 applied separately (refer to ACTIONS Note), each inoperable channel would only require the affected portion of the associated Division of low pressure ECCS and DG to be declared inoperable. However, since channels in both Divisions are inoperable and untripped, and the Completion Times started concurrently for the channels in both

(continued)

BASES

ACTIONS

B.1, B.2, and B.3 (continued)

Divisions, this results in the affected portions in both Divisions of ECCS and DG being concurrently declared inoperable. For Required Action B.2, redundant automatic initiation capability (i.e., loss of automatic start capability for either Functions 3.a or 3.b) is lost if two Function 3.a or two Function 3.b parallel contacts (channels) are inoperable and untripped in the same trip system.

In this situation (loss of redundant automatic initiation capability), the 24 hour allowance of Required Action B.3 is not appropriate and the feature(s) associated with the inoperable, untripped channels must be declared inoperable within 1 hour. As noted (Note 1 to Required Action B.1 and Required Action B.2), the two Required Actions are only applicable in MODES 1, 2, and 3. In MODES 4 and 5, the specific initiation time of the ECCS is not assumed and the probability of a LOCA is lower. Thus, a total loss of initiation capability for 24 hours (as allowed by Required Action B.3) is allowed during MODES 4 and 5. Notes are also provided (Note 2 to Required Action B.1 and Required Action B.2) to delineate which Required Action is applicable for each Function that requires entry into Condition B if an associated channel is inoperable. This ensures that the proper loss of initiation capability check is performed.

The Completion Time is intended to allow the operator time to evaluate and repair any discovered inoperabilities. This Completion Time also allows for an exception to the normal "time zero" for beginning the allowed outage time "clock." For Required Action B.1, the Completion Time only begins upon discovery that a redundant feature in both Divisions (e.g., any Division 1 ECCS and Division 2 ECCS) cannot be automatically initiated due to inoperable, untripped channels within the same variable as described in the paragraph above. For Required Action B.2, the Completion Time only begins upon discovery that the HPCS System cannot be automatically initiated due to two inoperable, untripped channels (parallel contacts) for the associated Function in the same trip system. The 1 hour Completion Time from discovery of loss of initiation capability is acceptable because it minimizes risk while allowing time for restoration or tripping of channels.

(continued)

BASES

ACTIONS

B.1, B.2, and B.3 (continued)

Because of the diversity of sensors available to provide initiation signals and the redundancy of the ECCS design, an allowable out of service time of 24 hours has been shown to be acceptable (Ref. 4) to permit restoration of any inoperable channel to OPERABLE status. If the inoperable channel cannot be restored to OPERABLE status within the allowable out of service time, the channel must be placed in the tripped condition per Required Action B.3. Placing the inoperable channel in trip would conservatively compensate for the inoperability, restore capability to accommodate a single failure, and allow operation to continue. Alternately, if it is not desired to place the channel in trip (e.g., as in the case where placing the inoperable channel in trip would result in an initiation), Condition G must be entered and its Required Action taken.

C.1 and C.2

Required Action C.1 is intended to ensure that appropriate actions are taken if multiple, inoperable channels within the same Function (or in some cases, within the same variable) result in redundant automatic initiation capability being lost for the feature(s). Loss of redundant automatic initiation capability for the low pressure ECCS injection feature in both divisions occurs when the initiation capability is available to less than two pumps from any single variable.

Required Action C.1 features would be those that are initiated by Functions 1.c, and 2.c (i.e., low pressure ECCS). For Functions 1.c and 2.c, redundant automatic initiation capability is lost if the Function 1.c and Function 2.c channels are inoperable. Since each inoperable channel would have Required Action C.1 applied separately (refer to ACTIONS Note), each inoperable channel would only require the affected portion of the associated Division to be declared inoperable. However, since channels in both Divisions are inoperable, and the Completion Times started concurrently for the channels in both Divisions, this results in the affected portions in both Divisions being concurrently declared inoperable. For Functions 1.c

(continued)

BASES

ACTIONS

C.1 and C.2 (continued)

and 2.c, the affected portions of the Division are LPCI A and LPCI B, respectively. In addition, the specific inoperability of these Functions should also be evaluated for impact on the DGs.

In this situation (loss of redundant automatic initiation capability), the 24 hour allowance of Required Action C.2 is not appropriate and the feature(s) associated with the inoperable channels must be declared inoperable within 1 hour. As noted (Note 1), the Required Action is only applicable in MODES 1, 2, and 3. In MODES 4 and 5, the specific initiation time of the ECCS is not assumed and the probability of a LOCA is lower. Thus, a total loss of automatic initiation capability for 24 hours (as allowed by Required Action C.2) is allowed during MODES 4 and 5.

Note 2 states that Required Action C.1 is only applicable for Functions 1.c and 2.c. The Required Action is not applicable to Functions 1.h, 2.g, and 3.f (which also require entry into this Condition if a channel in these Functions is inoperable), since they are the Manual Initiation Functions and are not assumed in any accident or transient analysis. Thus, a total loss of manual initiation capability for 24 hours (as allowed by Required Action C.2) is allowed. Required Action C.1 is also not applicable to Function 3.c (which also requires entry into this Condition if a channel in this Function is inoperable), since the loss of the Function was considered during the development of Reference 4 and considered acceptable for the 24 hours allowed by Required Action C.2.

The Completion Time is intended to allow the operator time to evaluate and repair any discovered inoperabilities. This Completion Time also allows for an exception to the normal "time zero" for beginning the allowed outage time "clock." For Required Action C.1, the Completion Time only begins upon discovery that the same feature in both Divisions (i.e., any Division 1 ECCS and Division 2 ECCS) cannot be automatically initiated due to inoperable channels within the same variable as described in the paragraph above. The 1 hour Completion Time from discovery of loss of initiation capability is acceptable because it minimizes risk while allowing time for restoration of channels.

(continued)

BASES

ACTIONS

C.1 and C.2 (continued)

Because of the diversity of sensors available to provide initiation signals and the redundancy of the ECCS design, an allowable out of service time of 24 hours has been shown to be acceptable (Ref. 4) to permit restoration of any inoperable channel to OPERABLE status. If the inoperable channel cannot be restored to OPERABLE status within the allowable out of service time, Condition G must be entered and its Required Action taken. The Required Actions do not allow placing the channel in trip since this action would either cause the initiation or would not necessarily result in a safe state for the channel in all events.

D.1, D.2, D.3, and D.4

Required Action D.1 is intended to ensure that appropriate actions are taken if multiple, inoperable, channels within the LPCS and LPCI Pump Discharge Flow – Low (Bypass) Functions, the Injection Line Pressure – Low (Injection Permissive), and the Reactor Steam Dome Pressure – Low (Injection Permissive) Functions result in redundant automatic initiation capability being lost for the feature(s). Loss of redundant automatic initiation capability for the low pressure ECCS injection feature in both divisions occurs when the initiation capability is available to less than two pumps from any single variable. For the purposes of this Condition, the injection permissives on Reactor Steam Dome Pressure – Low and Injection Line Pressure – Low are considered the same variable. Similarly, Functions 1.e, 1.f, and 2.e are all minimum flow functions and considered the same variable.

For Required Action D.1, the features would be those that are initiated by Functions 1.d, 1.e, 1.f, 1.g, 2.d, 2.e, and 2.f (e.g., low pressure ECCS). Redundant automatic initiation capability is lost if three of the four channels associated with Functions 1.e, 1.f, and 2.e are inoperable. For Function 1.d, redundant automatic initiation capability is lost if two Function 1.d channels are inoperable concurrent with either two inoperable Function 2.d channels or one inoperable Function 2.f channel. For Function 2.d, redundant automatic initiation capability is lost if two Function 2.d channels are inoperable concurrent with two

(continued)

BASES

ACTIONS

D.1, D.2, D.3, and D.4 (continued)

inoperable 1.d channels or one inoperable 1.g channel. For Function 1.g, redundant automatic initiation capability is lost if two Function 1.g channels are inoperable concurrent with either two inoperable Function 2.d channels or one inoperable Function 2.f channel. For Function 2.f, redundant automatic initiation capability is lost if two Function 2.f channels are inoperable concurrent with two inoperable 1.d channels or one inoperable 1.g channel. Since each inoperable channel would have Required Action D.1 applied separately (refer to ACTIONS Note), each inoperable channel would only require the affected low pressure ECCS pump to be declared inoperable. However, since channels for more than one low pressure ECCS pump are inoperable, and the Completion Times started concurrently for the channels of the low pressure ECCS pumps, this results in the affected low pressure ECCS pumps being concurrently declared inoperable.

In this situation (loss of redundant automatic initiation capability), the Completion Times of Required Actions D.3 and D.4 are not appropriate and the feature(s) associated with each inoperable channel must be declared inoperable within 1 hour after discovery of loss of initiation capability for feature(s) in both Divisions. As noted (Note 1 to Required Action D.1), Required Action D.1 is only applicable in MODES 1, 2, and 3. In MODES 4 and 5, the specific initiation time of the low pressure ECCS is not assumed and the probability of a LOCA is lower. Thus, a total loss of initiation capability for 7 days for Functions 1.e, 1.f, and 2.e (as allowed by Required Action D.4) is allowed during MODES 4 and 5. (This Condition is not entered when Functions 1.d, 1.g, 2.d or 2.f are inoperable in MODES 4 and 5.) A Note is also provided (Note 2 to Required Action D.1) to delineate that Required Action D.1 is only applicable to low pressure ECCS Functions. Required Action D.1 is not applicable to HPCS Functions 3.d and 3.e since the loss of one channel results in a loss of the Function (one-out-of-one logic). This loss was considered during the development of Reference 4 and considered acceptable for the 7 days allowed by Required Action D.4. Required Action D.2 is intended to ensure that appropriate

(continued)

BASES

ACTIONS

D.1, D.2, D.3, and D.4 (continued)

actions are taken if multiple, inoperable channels within the Reactor Steam Dome Pressure – Low (Injection Permissive) Function result in automatic initiation capability being lost for the features in one division. For Required Action D.2, the features would be those that are initiated by Functions 1.d and 2.d (e.g., low pressure ECCS). For Functions 1.d and 2.d, automatic initiation capability is lost in one division if two Function 1.d or two Function 2.d channels are inoperable. In this situation, (loss of automatic initiation capability), the 7 day allowance of Required Action D.4 is not appropriate and the features associated with the inoperable channels must be declared inoperable within 24 hours after discovery of loss of initiation capability for features in one division. For Functions 1.g and 2.f, an allowable out of service time of 24 hours is provided by Required Action D.3

The Completion Time is intended to allow the operator time to evaluate and repair any discovered inoperabilities. This Completion Time also allows for an exception to the normal "time zero" for beginning the allowed outage time "clock." For Required Action D.1, the Completion Time only begins upon discovery that three channels of the Pump Discharge Flow – Low (Bypass) Function cannot be automatically initiated due to inoperable channels or upon discovery of a loss of redundant initiation capability for the Reactor Steam Dome Pressure – Low (Injection Permissive) and Injection Line Pressure – Low (Injection Permissive) Functions (as described above). The 1 hour Completion Time from discovery of loss of initiation capability is acceptable because it minimizes risk while allowing time for restoration of channels. For Required Action D.2, the Completion Time only begins upon discovery that two Function 1.d or two Function 2.d channels cannot be automatically initiated due to inoperable channels. The 24 hour Completion Time from discovery of loss of initiation capability for features in one division is acceptable because of the redundancy of the ECCS design, as shown in the reliability analysis of Reference 4.

If the instrumentation that controls the pump minimum flow valve is inoperable such that the valve will not automatically open, extended pump operation with no injection path available could lead to pump overheating and

(continued)

BASES

ACTIONS

D.1, D.2, D.3, and D.4 (continued)

failure. If there were a failure of the instrumentation such that the valve would not automatically close, a portion of the pump flow could be diverted from the reactor injection path, causing insufficient core cooling. These consequences can be averted by the operator's manual control of the valve, which would be adequate to maintain ECCS pump protection and required flow. Furthermore, other ECCS pumps would be sufficient to complete the assumed safety function if no additional single failure were to occur. If a Reactor Vessel Pressure – Low (Injection Permissive) Function channel is inoperable, another channel exists to ensure the injection valves in the ECCS division can still open. The 7 day Completion Time of Required Action D.4 to restore the inoperable channel to OPERABLE status is reasonable based on the remaining capability of the associated ECCS subsystems, the redundancy available in the ECCS design, and the low probability of a DBA occurring during the allowed out of service time. If the inoperable channel cannot be restored to OPERABLE status within the allowable out of service time, Condition G must be entered and its Required Action taken. The Required Actions do not allow placing the channel in trip since this action would not necessarily result in a safe state for the channel in all events.

E.1 and E.2

Required Action E.1 is intended to ensure that appropriate actions are taken if multiple, inoperable, untripped channels within similar ADS trip system Functions result in automatic initiation capability being lost for the ADS. Automatic initiation capability is lost if either (a) one or more Function 4.a channels and one or more Function 5.a channels are inoperable and untripped, (b) one or more Function 4.b channels and one or more Function 5.b channels are inoperable and untripped, or (c) one Function 4.d channel and one Function 5.d channel are inoperable and untripped.

In this situation (loss of automatic initiation capability), the 96 hour or 8 day allowance, as applicable, of Required Action E.2 is not appropriate, and all ADS valves must be declared inoperable within 1 hour after discovery of loss of ADS initiation capability in both trip systems.

(continued)

BASES

ACTIONS

E.1 and E.2 (continued)

The Completion Time is intended to allow the operator time to evaluate and repair any discovered inoperabilities. This Completion Time also allows for an exception to the normal "time zero" for beginning the allowed outage time "clock." For Required Action E.1, the Completion Time only begins upon discovery that the ADS cannot be automatically initiated due to inoperable, untripped channels within similar ADS trip system Functions as described in the paragraph above. The 1 hour Completion Time from discovery of loss of initiation capability is acceptable because it minimizes risk while allowing time for restoration or tripping of channels.

Because of the diversity of sensors available to provide initiation signals and the redundancy of the ECCS design, an allowable out of service time of 8 days has been shown to be acceptable (Ref. 4) to permit restoration of any inoperable channel to OPERABLE status if both HPCS and RCIC are OPERABLE. If either HPCS or RCIC is inoperable, the time is shortened to 96 hours. If the status of HPCS or RCIC changes such that the Completion Time changes from 8 days to 96 hours, the 96 hours begins upon discovery of HPCS or RCIC inoperability. However, total time for an inoperable, untripped channel cannot exceed 8 days. If the status of HPCS or RCIC changes such that the Completion Time changes from 96 hours to 8 days, the "time zero" for beginning the 8 day "clock" begins upon discovery of the inoperable, untripped channel. If the inoperable channel cannot be restored to OPERABLE status within the allowable out of service time, the channel must be placed in the tripped condition per Required Action E.2. Placing the inoperable channel in trip would conservatively compensate for the inoperability, restore capability to accommodate a single failure, and allow operation to continue. Alternately, if it is not desired to place the channel in trip (e.g., as in the case where placing the inoperable channel in trip would result in an initiation), Condition G must be entered and its Required Action taken.

(continued)

BASES

ACTIONS (continued)

F.1 and F.2

Required Action F.1 is intended to ensure that appropriate actions are taken if multiple, inoperable channels within similar ADS trip system Functions result in automatic initiation capability being lost for the ADS. Automatic initiation capability is lost if either (a) one Function 4.c channel and one Function 5.c channel are inoperable, (b) one or more Function 4.e channels and one or more Function 5.e channels are inoperable, (c) one or more Function 4.f channels and one or more Function 5.e channels are inoperable, or (d) one or more Function 4.g channels and one or more Function 5.f channels are inoperable.

In this situation (loss of automatic initiation capability), the 96 hour or 8 day allowance, as applicable, of Required Action F.2 is not appropriate, and all ADS valves must be declared inoperable within 1 hour after discovery of loss of ADS initiation capability in both trip systems. The Note to Required Action F.1 states that Required Action F.1 is only applicable for Functions 4.c, 4.e, 4.f, 4.g, 5.c, 5.e, and 5.f. Required Action F.1 is not applicable to Functions 4.h and 5.g (which also require entry into this Condition if a channel in these Functions is inoperable), since they are the Manual Initiation Functions and are not assumed in any accident or transient analysis. Thus, a total loss of manual initiation capability for 96 hours or 8 days (as allowed by Required Action F.2) is allowed.

The Completion Time is intended to allow the operator time to evaluate and repair any discovered inoperabilities. This Completion Time also allows for an exception to the normal "time zero" for beginning the allowed outage time "clock." For Required Action F.1, the Completion Time only begins upon discovery that the ADS cannot be automatically initiated due to inoperable channels within similar ADS trip system Functions, as described in the paragraph above. The 1 hour Completion Time from discovery of loss of initiation capability is acceptable because it minimizes risk while allowing time for restoration or tripping of channels.

Because of the diversity of sensors available to provide initiation signals and the redundancy of the ECCS design, an allowable out of service time of 8 days has been shown to be acceptable (Ref. 4) to permit restoration of any inoperable

(continued)

BASES

ACTIONS

F.1 and F.2 (continued)

channel to OPERABLE status if both HPCS and RCIC are OPERABLE (Required Action F.2). If either HPCS or RCIC is inoperable, the time is reduced to 96 hours. If the status of HPCS or RCIC changes such that the Completion Time changes from 8 days to 96 hours, the 96 hours begins upon discovery of HPCS or RCIC inoperability. However, total time for an inoperable channel cannot exceed 8 days. If the status of HPCS or RCIC changes such that the Completion Time changes from 96 hours to 8 days, the "time zero" for beginning the 8 day "clock" begins upon discovery of the inoperable channel. If the inoperable channel cannot be restored to OPERABLE status within the allowable out of service time, Condition G must be entered and its Required Action taken. The Required Actions do not allow placing the channel in trip since this action would not necessarily result in a safe state for the channel in all events.

G.1

With any Required Action and associated Completion Time not met, the associated feature(s) may be incapable of performing the intended function and the supported feature(s) associated with the inoperable untripped channels must be declared inoperable immediately.

SURVEILLANCE REQUIREMENTS

As noted at the beginning of the SRs, the SRs for each ECCS instrumentation Function are found in the SRs column of Table 3.3.5.1-1.

The Surveillances are modified by a Note to indicate that when a channel is placed in an inoperable status solely for performance of required Surveillances, entry into associated Conditions and Required Actions may be delayed for up to 6 hours as follows: (a) for Functions 3.c, 3.d, 3.e, and 3.f; and (b) for Functions other than 3.c, 3.d, 3.e, and 3.f provided the associated Function or redundant Function maintains ECCS initiation capability. Upon completion of the Surveillance, or expiration of the 6 hour allowance, the channel must be returned to OPERABLE status or the applicable Condition entered and Required Actions taken. This Note is based on the reliability analysis

(continued)

BASES

SURVEILLANCE REQUIREMENTS (continued)

(Ref. 4) assumption of the average time required to perform channel Surveillance. That analysis demonstrated that the 6 hour testing allowance does not significantly reduce the probability that the ECCS will initiate when necessary.

SR 3.3.5.1.1

Performance of the CHANNEL CHECK once every 12 hours ensures that a gross failure of instrumentation has not occurred. A CHANNEL CHECK is normally a comparison of the parameter indicated on one channel to a similar parameter on other channels. It is based on the assumption that instrument channels monitoring the same parameter should read approximately the same value. Significant deviations between the instrument channels could be an indication of excessive instrument drift in one of the channels or something even more serious. A CHANNEL CHECK will detect gross channel failure; thus, it is key to verifying the instrumentation continues to operate properly between each CHANNEL CALIBRATION.

Agreement criteria are determined by the plant staff, based on a combination of the channel instrument uncertainties, including indication and readability. If a channel is outside the criteria, it may be an indication that the instrument has drifted outside its limit.

The Frequency is based upon operating experience that demonstrates channel failure is rare. The CHANNEL CHECK supplements less formal, but more frequent, checks of channels during normal operational use of the displays associated with the channels required by the LCO.

SR 3.3.5.1.2

A CHANNEL FUNCTIONAL TEST is performed on each required channel to ensure that the channel will perform the intended function. A successful test of the required contact(s) of a channel relay may be performed by the verification of the change of state of a single contact of the relay. This

(continued)

BASES

SURVEILLANCE REQUIREMENTS

SR 3.3.5.1.2 (continued)

clarifies what is an acceptable CHANNEL FUNCTIONAL TEST of a relay. This is acceptable because all of the other required contacts of the relay are verified by other Technical Specifications and non-Technical Specifications tests at least once per refueling interval with applicable extensions.

Any setpoint adjustment shall be consistent with the assumptions of the current plant specific setpoint methodology.

The Frequency of 92 days is based on the reliability analyses of Reference 4.

SR 3.3.5.1.3 and SR 3.3.5.1.4

A CHANNEL CALIBRATION is a complete check of the instrument loop and the sensor. This test verifies the channel responds to the measured parameter within the necessary range and accuracy. CHANNEL CALIBRATION leaves the channel adjusted to account for instrument drifts between successive calibrations consistent with the plant specific setpoint methodology.

The Frequency of SR 3.3.5.1.3 is based upon the assumption of a 92 day calibration interval in the determination of the magnitude of equipment drift in the setpoint analysis. The Frequency of SR 3.3.5.1.4 is based upon the assumption of a 24 month calibration interval in the determination of the magnitude of equipment drift in the setpoint analysis.

SR 3.3.5.1.5

The LOGIC SYSTEM FUNCTIONAL TEST demonstrates the OPERABILITY of the required initiation logic for a specific channel. The system functional testing performed in LCO 3.5.1, LCO 3.5.2, LCO 3.8.1, and LCO 3.8.2 overlaps this Surveillance to provide complete testing of the assumed safety function.

(continued)

BASES

SURVEILLANCE REQUIREMENTS

SR 3.3.5.1.5 (continued)

The 24 month Frequency is based on the need to perform this Surveillance under the conditions that apply during a plant outage and the potential for unplanned transients if the Surveillance were performed with the reactor at power. Operating experience has shown these components usually pass the Surveillance when performed at the 24 month Frequency.

SR 3.3.5.1.6

This SR ensures that the individual channel response times are less than or equal to the maximum values assumed in the accident analysis. Response time testing acceptance criteria are included in Reference 5.

ECCS RESPONSE TIME may be verified by actual response time measurements in any series of sequential, overlapping, or total channel measurements. However, the measurement of instrument loop response times may be excluded if the conditions of Reference 6 are satisfied. If these conditions are satisfied, instrument loop response time may be allocated based on either assumed design instrument loop response time or the manufacturer's stated design instrument loop response time. When the requirements of Reference 6 are not satisfied, instrument loop response time must be measured. The instrument loop response times must be added to the remaining equipment response times (e.g., ECCS pump start time) to obtain the ECCS RESPONSE TIME. However, failure to meet the ECCS RESPONSE TIME due to a component other than instrumentation not within limits does not require the associated instrumentation to be declared inoperable; only the affected component (e.g., ECCS pump) is required to be declared inoperable.

ECCS RESPONSE TIME tests are conducted on a 24 month STAGGERED TEST BASIS. The 24 month Frequency is consistent with the refueling cycle and is based upon plant operating experience, which shows that random failures of instrumentation components causing serious response time degradation, but not channel failure, are infrequent.

(continued)

BASES (continued)

REFERENCES

1. UFSAR, Section 5.2.

2. UFSAR, Section 6.3.

3. UFSAR, Chapter 15.

4. NEDC-30936-P-A, "BWR Owners' Group Technical Specification Improvement Analyses for ECCS Actuation Instrumentation, Parts 1 and 2," December 1988.

5. Technical Requirements Manual.

6. NEDO-32291-A, "System Analyses for the Elimination of Selected Response Time Testing Requirements," October 1995.

B 3.3 INSTRUMENTATION

B 3.3.5.2 Reactor Core Isolation Cooling (RCIC) System Instrumentation

BASES

BACKGROUND

The purpose of the RCIC System instrumentation is to initiate actions to ensure adequate core cooling when the reactor vessel is isolated from its primary heat sink (the main condenser) and normal coolant makeup flow from the Reactor Feedwater System is insufficient or unavailable, such that RCIC System initiation occurs and maintains sufficient reactor water level precluding initiation of the low pressure Emergency Core Cooling Systems (ECCS) pumps. A more complete discussion of RCIC System operation is provided in the Bases of LCO 3.5.3, "RCIC System."

The RCIC System may be initiated by either automatic or manual means. Automatic initiation occurs for conditions of Reactor Vessel Water Level Low-Low, Level 2. The variable is monitored by four differential pressure transmitters that are connected to four trip units. The outputs of the trip units are connected to relays whose contacts are arranged in a one-out-of-two taken twice logic arrangement. The logic can also be initiated by use of a manual push button. Once initiated, the RCIC logic seals in and can be reset by the operator only when the reactor vessel water level signals have cleared.

The RCIC test line isolation valve is closed on a RCIC initiation signal to allow full system flow to the reactor vessel.

The RCIC System also monitors the water level in the condensate storage tank (CST), since there are two sources of water for RCIC operation. Reactor grade water in the CST is the normal source. Upon receipt of a RCIC initiation signal, the CST suction valve is automatically signaled to open (it is normally in the open position) unless the pump suction from the suppression pool valve is open. If the water level in the CST falls below a preselected level, first the suppression pool suction valve automatically opens and then the CST suction valve automatically closes. Two level switches are used to detect low water level in the CST. Either switch can cause the suppression pool suction valve to open. To prevent losing suction to the pump,

(continued)

BASES

BACKGROUND (continued)

the suction valves are interlocked so that one suction path must be open before the other automatically closes.

The RCIC System provides makeup water to the reactor until the reactor vessel water level reaches the high water level (Level 8) trip (two-out-of-two logic), at which time the RCIC turbine steam inlet isolation valve closes (the injection valve also closes due to the closure of the RCIC turbine steam inlet isolation valve). The RCIC System restarts if vessel level again drops to the low level initiation point (Level 2).

APPLICABLE SAFETY ANALYSES, LCO, and APPLICABILITY

The function of the RCIC System, to provide makeup coolant to the reactor, is to respond to transient events. The RCIC System is not an Engineered Safety Feature System and no credit is taken in the safety analysis for RCIC System operation. Based on its contribution to the reduction of overall plant risk, however, the RCIC System, and therefore its instrumentation, meets Criterion 4 of 10 CFR 50.36(c)(2)(ii). Certain instrumentation Functions are retained for other reasons and are described below in the individual Functions discussion.

The OPERABILITY of the RCIC System instrumentation is dependent on the OPERABILITY of the individual instrumentation channel Functions specified in Table 3.3.5.2-1. Each Function must have a required number of OPERABLE channels with their setpoints within the specified Allowable Values, where appropriate. The actual setpoint is calibrated consistent with applicable setpoint methodology assumptions.

Allowable Values are specified for each RCIC System instrumentation Function specified in the Table. Nominal trip setpoints are specified in the setpoint calculations. The nominal setpoints are selected to ensure that the setpoints do not exceed the Allowable Value between CHANNEL CALIBRATIONS. Operation with a trip setpoint less conservative than the nominal trip setpoint, but within its Allowable Value, is acceptable. A channel is inoperable if its actual trip setpoint is not within its required Allowable Value.

(continued)

BASES

APPLICABLE SAFETY ANALYSES, LCO, and APPLICABILITY (continued)

Trip setpoints are those predetermined values of output at which an action should take place. The setpoints are compared to the actual process parameter (e.g., reactor vessel water level), and when the measured output value of the process parameter exceeds the setpoint, the associated device (e.g., trip unit) changes state. The analytic limits (or design limits) are derived from the limiting values of the process parameters obtained from the safety analysis. The trip setpoints are determined from the analytic limits, corrected for defined process, calibration, and instrument errors. The Allowable Values are then determined, based on the trip setpoint values, by accounting for the calibration based errors. These calibration based errors are limited to reference accuracy, instrument drift, errors associated with measurement and test equipment, and calibration tolerance of loop components. The trip setpoints and Allowable Values determined in this manner provide adequate protection because instrument uncertainties, process effects, calibration tolerances, instrument drift, and severe environment errors (for channels that must function in harsh environments as defined by 10 CFR 50.49) are accounted for and appropriately applied for the instrumentation.

The individual Functions are required to be OPERABLE in MODE 1, and in MODES 2 and 3 with reactor steam dome pressure > 150 psig, since this is when RCIC is required to be OPERABLE. Refer to LCO 3.5.3 for Applicability Bases for the RCIC System.

The specific Applicable Safety Analyses, LCO, and Applicability discussions are listed below on a Function by Function basis.

1. Reactor Vessel Water Level – Low Low, Level 2

Low reactor pressure vessel (RPV) water level indicates that normal feedwater flow is insufficient to maintain reactor vessel water level and that the capability to cool the fuel may be threatened. Should RPV water level decrease too far, fuel damage could result. Therefore, the RCIC System is initiated at Level 2 to assist in maintaining water level above the top of the active fuel.

(continued)

BASES

APPLICABLE SAFETY ANALYSES, LCO, and APPLICABILITY

1. Reactor Vessel Water Level – Low Low, Level 2 (continued)

Reactor Vessel Water Level – Low Low, Level 2 signals are initiated from four differential pressure transmitters that sense the difference between the pressure due to a constant column of water (reference leg) and the pressure due to the actual water level (variable leg) in the vessel.

The Reactor Vessel Water Level – Low Low, Level 2 Allowable Value is set high enough such that for complete loss of feedwater flow, the RCIC System flow with high pressure core spray assumed to fail will be sufficient to avoid initiation of low pressure ECCS at Level 1.

Four channels of Reactor Vessel Water Level – Low Low, Level 2 Function are available and are required to be OPERABLE when RCIC is required to be OPERABLE to ensure that no single instrument failure can preclude RCIC initiation. Refer to LCO 3.5.3 for RCIC Applicability Bases.

2. Reactor Vessel Water Level – High, Level 8

High RPV water level indicates that sufficient cooling water inventory exists in the reactor vessel such that there is no danger to the fuel. Therefore, the Level 8 signal is used to close the RCIC turbine steam inlet isolation valve to prevent overflow into the main steam lines (MSLs). (The injection valve also closes due to the closure of the RCIC turbine steam inlet isolation valve.)

Reactor Vessel Water Level – High, Level 8 signals for RCIC are initiated from two differential pressure transmitters from the narrow range water level measurement instrumentation, which sense the difference between the pressure due to a constant column of water (reference leg) and the pressure due to the actual water level (variable leg) in the vessel.

The Reactor Vessel Water Level – High, Level 8 Allowable Value is high enough to preclude isolating the injection valve of the RCIC during normal operation, yet low enough to trip the RCIC System prior to water overflowing into the MSLs.

(continued)

BASES

APPLICABLE SAFETY ANALYSES, LCO, and APPLICABILITY

2. Reactor Vessel Water Level – High, Level 8 (continued)

Two channels of Reactor Vessel Water Level – High, Level 8 Function are available and are required to be OPERABLE when RCIC is required to be OPERABLE to ensure that no single instrument failure can preclude RCIC initiation. Refer to LCO 3.5.3 for RCIC Applicability Bases.

3. Condensate Storage Tank Level – Low

Low level in the CST indicates the unavailability of an adequate supply of makeup water from this normal source. Normally the suction valve between the RCIC pump and the CST is open and, upon receiving a RCIC initiation signal, water for RCIC injection would be taken from the CST. However, if the water level in the CST falls below a preselected level, first the suppression pool suction valve automatically opens and then the CST suction valve automatically closes. This ensures that an adequate supply of makeup water is available to the RCIC pump. To prevent losing suction to the pump, the suction valves are interlocked so that the suppression pool suction valve must be open before the CST suction valve automatically closes.

Two level switches are used to detect low water level in the CST. The Condensate Storage Tank Level – Low Function Allowable Value is set high enough to ensure adequate pump suction head while water is being taken from the CST.

Two channels of Condensate Storage Tank Level – Low Function are available and are required to be OPERABLE when RCIC is required to be OPERABLE to ensure that no single instrument failure can preclude RCIC swap to suppression pool source. Refer to LCO 3.5.3 for RCIC Applicability Bases.

4. Manual Initiation

The Manual Initiation push button channel introduces a signal into the RCIC System initiation logic that is redundant to the automatic protective instrumentation and provides manual initiation capability. There is one push button channel for the RCIC System.

(continued)

BASES

APPLICABLE SAFETY ANALYSES, LCO, and APPLICABILITY

4. Manual Initiation (continued)

The Manual Initiation Function is not assumed in any accident or transient analyses in the UFSAR. However, the Function is retained for overall redundancy and diversity of the RCIC function as required by the NRC in the plant licensing basis.

There is no Allowable Value for this Function since the channel is mechanically actuated based solely on the position of the push button. One channel of Manual Initiation is required to be OPERABLE when RCIC is required to be OPERABLE. Refer to LCO 3.5.3 for RCIC Applicability Bases.

ACTIONS

A Note has been provided to modify the ACTIONS related to RCIC System instrumentation channels. Section 1.3, Completion Times, specifies that once a Condition has been entered, subsequent divisions, subsystems, components, or variables expressed in the Condition discovered to be inoperable or not within limits will not result in separate entry into the Condition. Section 1.3 also specifies that Required Actions of the Condition continue to apply for each additional failure, with Completion Times based on initial entry into the Condition. However, the Required Actions for inoperable RCIC System instrumentation channels provide appropriate compensatory measures for separate inoperable channels. As such, a Note has been provided that allows separate Condition entry for each inoperable RCIC System instrumentation channel.

A.1

Required Action A.1 directs entry into the appropriate Condition referenced in Table 3.3.5.2-1 in the accompanying LCO. The applicable Condition referenced in the Table is Function dependent. Each time a channel is discovered to be inoperable, Condition A is entered for that channel and provides for transfer to the appropriate subsequent Condition.

(continued)

BASES

ACTIONS (continued)

B.1 and B.2

Required Action B.1 is intended to ensure that appropriate actions are taken if multiple, inoperable, untripped channels within the same Function result in a complete loss of automatic initiation capability for the RCIC System. In this case, automatic initiation capability is lost if two Function 1 parallel contacts (channels) in the same trip system are inoperable and untripped. In this situation (loss of automatic initiation capability), the 24 hour allowance of Required Action B.2 is not appropriate, and the RCIC System must be declared inoperable within 1 hour after discovery of loss of RCIC initiation capability.

The Completion Time is intended to allow the operator time to evaluate and repair any discovered inoperabilities. This Completion Time also allows for an exception to the normal "time zero" for beginning the allowed outage time "clock." For Required Action B.1, the Completion Time only begins upon discovery that the RCIC System cannot be automatically initiated due to two inoperable, untripped Reactor Vessel Water Level – Low Low, Level 2 channels (parallel contacts) in the same trip system. The 1 hour Completion Time from discovery of loss of initiation capability is acceptable because it minimizes risk while allowing time for restoration or tripping of channels.

Because of the redundancy of sensors available to provide initiation signals and the fact that the RCIC System is not credited in any accident or transient analysis, an allowable out of service time of 24 hours has been shown to be acceptable (Ref. 1) to permit restoration of any inoperable channel to OPERABLE status. If the inoperable channel cannot be restored to OPERABLE status within the allowable out of service time, the channel must be placed in the tripped condition per Required Action B.2. Placing the inoperable channel in trip would conservatively compensate for the inoperability, restore capability to accommodate a single failure, and allow operation to continue. Alternately, if it is not desired to place the channel in trip (e.g., as in the case where placing the inoperable channel in trip would result in an initiation), Condition E must be entered and its Required Action taken.

(continued)

BASES

ACTIONS (continued)

C.1

A risk based analysis was performed and determined that an allowable out of service time of 24 hours (Ref. 1) is acceptable to permit restoration of any inoperable channel to OPERABLE status (Required Action C.1). A Required Action (similar to Required Action B.1), limiting the allowable out of service time if a loss of automatic RCIC initiation capability exists, is not required. This Condition applies to the Reactor Vessel Water Level – High, Level 8 Function, whose logic is arranged such that any inoperable channel will result in a loss of automatic RCIC initiation (high water level trip) capability. As stated above, this loss of automatic RCIC initiation (high water level trip) capability was analyzed and determined to be acceptable. This Condition also applies to the Manual Initiation Function. Since this Function is not assumed in any accident or transient analysis, a total loss of manual initiation capability (Required Action C.1) for 24 hours is allowed. The Required Action does not allow placing a channel in trip since this action would not necessarily result in the safe state for the channel in all events.

D.1, D.2.1, and D.2.2

Required Action D.1 is intended to ensure that appropriate actions are taken if multiple inoperable, untripped channels within the same Function result in automatic component initiation (RCIC source swapover) capability being lost for the feature(s). For Required Action D.1, the RCIC System is the only associated feature. In this case, automatic component initiation (RCIC source swapover) capability is lost if two Function 3 channels are inoperable and untripped. In this situation (loss of automatic suction swap), the 24 hour allowance of Required Actions D.2.1 and D.2.2 is not appropriate, and the RCIC System must be declared inoperable within 1 hour from discovery of loss of RCIC initiation capability. As noted, Required Action D.1 is only applicable if the RCIC pump suction is not aligned to the suppression pool since, if aligned, the Function is already performed.

(continued)

BASES

ACTIONS

D.1, D.2.1, and D.2.2 (continued)

The Completion Time is intended to allow the operator time to evaluate and repair any discovered inoperabilities. This Completion Time also allows for an exception to the normal "time zero" for beginning the allowed outage time "clock." For Required Action D.1, the Completion Time only begins upon discovery that the RCIC System cannot be automatically aligned to the suppression pool due to two inoperable, untripped channels in the same Function. The 1 hour Completion Time from discovery of loss of initiation capability is acceptable because it minimizes risk while allowing time for restoration or tripping of channels.

Because of the redundancy of sensors available to provide initiation signals and the fact that the RCIC System is not assumed in any accident or transient analysis, an allowable out of service time of 24 hours has been shown to be acceptable (Ref. 1) to permit restoration of any inoperable channel to OPERABLE status. If the inoperable channel cannot be restored to OPERABLE status within the allowable out of service time, the channel must be placed in the tripped condition per Required Action D.2.1, which performs the intended function of the channel (shifting the suction source to the suppression pool). Alternatively, Required Action D.2.2 allows the manual alignment of the RCIC suction to the suppression pool, which also performs the intended function. If Required Action D.2.1 or D.2.2 is performed, measures should be taken to ensure that the RCIC System piping remains filled with water. If it is not desired to perform Required Actions D.2.1 and D.2.2 (e.g., as in the case where shifting the suction source could drain down the RCIC suction piping), Condition E must be entered and its Required Action taken.

E.1

With any Required Action and associated Completion Time not met, the RCIC System may be incapable of performing the intended function, and the RCIC System must be declared inoperable immediately.

(continued)

BASES (continued)

SURVEILLANCE REQUIREMENTS

As noted in the beginning of the SRs, the SRs for each RCIC System instrumentation Function are found in the SRs column of Table 3.3.5.2-1.

The Surveillances are modified by a Note to indicate that when a channel is placed in an inoperable status solely for performance of required Surveillances, entry into associated Conditions and Required Actions may be delayed as follows: (a) for up to 6 hours for Functions 2 and 4; and (b) for up to 6 hours for Functions 1 and 3 provided the associated Function maintains RCIC initiation capability. Upon completion of the Surveillance, or expiration of the 6 hour allowance, the channel must be returned to OPERABLE status or the applicable Condition entered and Required Actions taken. This Note is based on the reliability analysis (Ref. 1) assumption of the average time required to perform channel Surveillance. That analysis demonstrated that the 6 hour testing allowance does not significantly reduce the probability that the RCIC will initiate when necessary.

SR 3.3.5.2.1

Performance of the CHANNEL CHECK once every 12 hours ensures that a gross failure of instrumentation has not occurred. A CHANNEL CHECK is normally a comparison of the parameter indicated on one channel to a similar parameter on other channels. It is based on the assumption that instrument channels monitoring the same parameter should read approximately the same value. Significant deviations between the instrument channels could be an indication of excessive instrument drift in one of the channels or something even more serious. A CHANNEL CHECK will detect gross channel failure; thus, it is key to verifying that the instrumentation continues to operate properly between each CHANNEL CALIBRATION.

Agreement criteria are determined by the plant staff based on a combination of the channel instrument uncertainties, including indication and readability. If a channel is outside the criteria, it may be an indication that the instrument has drifted outside its limit.

(continued)

BASES

SURVEILLANCE REQUIREMENTS

SR 3.3.5.2.1 (continued)

The Frequency is based upon operating experience that demonstrates channel failure is rare. The CHANNEL CHECK supplements less formal, but more frequent, checks of channels during normal operational use of the displays associated with the channels required by the LCO.

SR 3.3.5.2.2

A CHANNEL FUNCTIONAL TEST is performed on each required channel to ensure that the channel will perform the intended function. A successful test of the required contact(s) of a channel relay may be performed by the verification of the change of state of a single contact of the relay. This clarifies what is an acceptable CHANNEL FUNCTIONAL TEST of a relay. This is acceptable because all of the other required contacts of the relay are verified by other Technical Specifications and non-Technical Specifications tests at least once per refueling interval with applicable extensions. Any setpoint adjustment shall be consistent with the assumptions of the current plant specific setpoint methodology.

The Frequency of 92 days is based on the reliability analysis of Reference 1.

SR 3.3.5.2.3

CHANNEL CALIBRATION is a complete check of the instrument loop and the sensor. This test verifies the channel responds to the measured parameter with the necessary range and accuracy. CHANNEL CALIBRATION leaves the channel adjusted to account for instrument drifts between successive calibrations consistent with the plant specific setpoint methodology.

The Frequency is based on the assumption of a 24 month calibration interval in the determination of the magnitude of equipment drift in the setpoint analysis.

(continued)

BASES

SURVEILLANCE REQUIREMENTS (continued)

SR 3.3.5.2.4

The LOGIC SYSTEM FUNCTIONAL TEST demonstrates the OPERABILITY of the required initiation logic for a specific channel. The system functional testing performed in LCO 3.5.3 overlaps this Surveillance to provide complete testing of the safety function.

The 24 month Frequency is based on the need to perform this Surveillance under the conditions that apply during a plant outage and the potential for an unplanned transient if the Surveillance were performed with the reactor at power. Operating experience has shown that these components usually pass the Surveillance when performed at the 24 month Frequency.

REFERENCES

1. GENE-770-06-2-A, "Addendum to Bases for Changes to Surveillance Test Intervals and Allowed Out-of-Service Times for Selected Instrumentation Technical Specifications," December 1992.

B 3.3 INSTRUMENTATION

B 3.3.6.1 Primary Containment Isolation Instrumentation

BASES

BACKGROUND

The primary containment isolation instrumentation automatically initiates closure of appropriate primary containment isolation valves (PCIVs). The function of the PCIVs, in combination with other accident mitigation systems, is to limit fission product release during and following postulated Design Basis Accidents (DBAs). Primary containment isolation within the time limits specified for those isolation valves designed to close automatically ensures that the release of radioactive material to the environment will be consistent with the assumptions used in the analyses for a DBA.

The isolation instrumentation includes the sensors, relays, and switches that are necessary to cause initiation of primary containment and reactor coolant pressure boundary (RCPB) isolation. Most channels include electronic equipment (e.g., trip units) that compares measured input signals with pre-established setpoints. When the setpoint is exceeded, the channel output relay actuates, which then outputs a primary containment isolation signal to the isolation logic. Functional diversity is provided by monitoring a wide range of independent parameters. The input parameters to the isolation logic are (a) reactor vessel water level, (b) area and differential temperatures, (c) main steam line (MSL) flow measurement, (d) Standby Liquid Control (SLC) System initiation, (e) condenser vacuum loss, (f) main steam line pressure, (g) reactor core isolation cooling (RCIC) steam line flow and time delay relay, (h) reactor building ventilation exhaust plenum and fuel pool ventilation exhaust radiation, (i) RCIC steam line pressure, (j) RCIC turbine exhaust diaphragm pressure, (k) reactor water cleanup (RWCU) differential flow and time delay relay, (l) reactor vessel pressure, and (m) drywell pressure. Redundant sensor input signals are provided from each such isolation initiation parameter. In addition, manual isolation of the logics is provided.

The primary containment isolation instrumentation has inputs to the trip logic from the isolation Functions listed below.

(continued)

BASES

BACKGROUND (continued)

1. Main Steam Line Isolation

Most Main Steam Line Isolation Functions receive inputs from four channels. One channel associated with each Function inputs to one of four trip strings. Two trip strings make up a trip system and both trip systems must actuate to cause isolation of all main steam isolation valves (MSIVs). Any channel will trip the associated trip string. Only one trip string must trip to trip the associated trip system. The trip strings are arranged in one-out-of-two taken twice logic to initiate isolation of all MSIVs. The outputs from the same channels are arranged into two two-out-of-two trip systems to isolate all MSL drain valves. One two-out-of-two trip system is associated with the inboard valves and the other two-out-of-two trip system is associated with the outboard valves.

One exception to this arrangement is the Main Steam Line Flow—High Function. This Function uses 16 flow channels, four for each steam line. One channel from each steam line inputs to one of four trip strings. Two trip strings make up each trip system, and both trip systems must trip to cause an MSL isolation. Each trip string has four inputs (one per MSL), any one of which will trip the trip string. The trip strings are arranged in a one-out-of-two taken twice logic. Therefore, this is effectively a one-out-of-eight taken twice logic arrangement to initiate isolation of the MSIVs. Similarly, the 16 flow channels are connected into two two-out-of-two trip systems (effectively, two one-out-of-four twice logic), with one trip system isolating the inboard MSL drain valves and the other two-out-of-two trip system isolating the outboard MSL drain valves.

The other exception to this arrangement is the Manual Initiation Function. The MSIV manual isolation logic is similar to the other MSIV isolation logic in that each trip string is associated with a manual isolation pushbutton in a one-out-of-two taken twice logic as described above. However, the MSL drain isolation valves are isolated by a single manual isolation pushbutton; the outboard MSL drain isolation valves isolate from the B channel manual isolation pushbutton and the inboard MSL drain valve isolates from the D channel manual isolation pushbutton. The A and C channel manual isolation pushbuttons only directly affect the manual

(continued)

BASES

BACKGROUND

1. Main Steam Line Isolation (continued)

isolation of the MSIVs. The same channel B and D manual isolation pushbuttons are used for the logic of other Group isolation valves.

MSL Isolation Functions isolate the Group 1 valves.

2. Primary Containment Isolation

Most Primary Containment Isolation Functions receive inputs from four channels. The outputs from these channels are arranged into two two-out-of-two trip systems. One trip system initiates isolation of all automatic inboard PCIVs, while the other trip system initiates isolation of all automatic outboard PCIVs. Each trip system closes one of the two valves on each penetration with automatic isolation so that operation of either trip system isolates the penetration. An exception to this arrangement are the Traversing In-core Probe (TIP) System valve/drives. For these valves and drive mechanisms, only one trip system (the inboard valve system) is provided. When the trip system actuates, the drive mechanisms withdraw the TIPs and, when the TIPs are fully withdrawn, the ball valves close. This exception to the arrangement, which has been previously approved by the NRC as part of the issuance of the Operating Licenses, is described in UFSAR Table 6.2-21 (Ref. 1).

Reactor Vessel Water Level—Low, Level 3 isolates the Group 7 valves. Reactor Vessel Water Level—Low Low, Level 2 isolates the Group 2, 3, and 4 valves. Reactor Vessel Water Level—Low Low Low, Level 1 isolates the Group 10 valves. Drywell Pressure—High isolates the Group 2, 4, 7, and 10 valves. Reactor Building Ventilation Exhaust Plenum Radiation—High isolates the Group 4 valves. Fuel Pool Ventilation Exhaust Radiation—High isolates the Group 4 valves. Manual Initiation Functions isolate the Group 2, 4, 7, and 10 valves.

3. Reactor Core Isolation Cooling System Isolation

Most Functions receive input from two channels, with each channel in one trip system using one-out-of-one logic. One of the two trip systems is connected to the inboard steam

(continued)

BASES

BACKGROUND

3. Reactor Core Isolation Cooling System Isolation (continued)

valves and the other trip system is connected to the outboard steam valve on the RCIC penetration so that operation of either trip system isolates the penetration. Two exceptions to this arrangement are the RCIC Steam Supply Pressure – Low and RCIC Turbine Exhaust Diaphragm Pressure – High Functions. These Functions receive input from four steam supply pressure channels and four turbine exhaust diaphragm pressure channels, respectively. The outputs from these channels are connected into two two-out-of-two trip systems, each trip system isolating the inboard or outboard RCIC steam valves. In addition, the RCIC System Isolation Manual Initiation Function has only one channel, which isolates the outboard RCIC steam valve only (provided an automatic initiation signal is present). One additional exception involves the Drywell Pressure–High Function and the RCIC Steam Supply Pressure – Low Functions. The Drywell Pressure – High Function does not provide an isolation to the inboard and outboard RCIC steam valves (Group 8 valves). The logic is arranged such that RCIC Steam Supply Pressure – Low coincident with Drywell Pressure – High isolates the Group 9 valves. The Drywell Pressure – High Function receives inputs from four drywell pressure channels. The outputs from these channels are connected into two one-out-of-two trip systems with coincident RCIC Steam Supply Pressure also connected into the same trip systems arranged in a similar manner (one-out-of-two). One of the two trip systems is connected to the inboard RCIC turbine exhaust vacuum breaker line isolation valve and the other trip system is connected to the outboard RCIC turbine exhaust vacuum breaker line isolation valve (Group 9 valves).

RCIC System Isolation Functions isolate the Group 8 and 9 valves.

4. Reactor Water Cleanup System Isolation

Most Functions receive input from two channels with each channel in one trip system using one-out-of-one logic. Functions 4.c, 4.d, 4.e and 4.f (RWCU Heat Exchanger Area Temperature – High, RWCU Heat Exchanger Area Ventilation Differential Temperature – High, RWCU Pump and Valve Area

(continued)

BASES

BACKGROUND

4. Reactor Water Cleanup System Isolation (continued)

Temperature – High, and RWCU Pump and Valve Area Ventilation Differential Temperature – High, respectively) have one channel in each trip system in each area for a total of four channels per Function, for Functions 4.c and 4.d and a total of six channels per Function for Functions 4.e and 4.f, but the logic is the same (one-out-of-one per area). Each of the two trip systems is connected to one of the two valves on the RWCU penetration so that operation of either trip system isolates the penetration. The exceptions to this arrangement are the Reactor Vessel Water Level – Low Low, Level 2 and the SLC System Initiation Functions. The Reactor Vessel Water Level – Low Low, Level 2 Function receives input from four reactor vessel water level channels. The outputs from the reactor vessel water level channels are connected into two two-out-of-two trip systems, each trip system isolating one of the two RWCU valves. The Standby Liquid Control (SLC) System initiation has two channels, one from each SLC pump start circuit, in a single trip system. The two channels are connected in a one-out-of-two logic. This trip system isolates the RWCU inlet outboard valve.

RWCU Isolation Functions isolate the Group 5 valves.

5. RHR Shutdown Cooling System Isolation

The Shutdown Cooling Isolation Function receives input signals from instrumentation for the Reactor Vessel Water Level – Low, Level 3, Reactor Vessel Pressure – High, and Manual Initiation Functions. The Reactor Vessel Water Level – Low Function receives input from four channels while the Reactor Vessel Pressure – High Function receives input from two channels. The outputs from the Reactor Vessel Water Level – Low channels are connected into two two-out-of-two trip systems. The Reactor Vessel Pressure – High Function is arranged into two one-out-of-one trip systems. The Manual Initiation Function uses two channels, one for each trip system.

(continued)

BASES

BACKGROUND

5. Shutdown Cooling System Isolation (continued)

One of the two trip systems is connected to the outboard valve associated with the reactor vessel head spray injection penetration, the shutdown cooling return penetration, and the shutdown cooling suction penetration while the other trip system is connected to the inboard valves on the shutdown cooling suction penetration and the shutdown cooling return check valve bypasses.

The RHR Shutdown Cooling Isolation Functions isolate the Group 6 valves.

APPLICABLE SAFETY ANALYSES, LCO, and APPLICABILITY

The isolation signals generated by the primary containment isolation instrumentation are implicitly assumed in the safety analyses of References 2 and 3 to initiate closure of valves to limit offsite doses. Refer to LCO 3.6.1.3, "Primary Containment Isolation Valves (PCIVs)," Applicable Safety Analyses Bases, for more detail.

Primary containment isolation instrumentation satisfies Criterion 3 of 10 CFR 50.36(c)(2)(ii). Certain instrumentation Functions are retained for other reasons and are described below in the individual Functions discussion.

The OPERABILITY of the primary containment instrumentation is dependent on the OPERABILITY of the individual instrumentation channel Functions specified in Table 3.3.6.1-1. Each Function must have a required number of OPERABLE channels, with their setpoints within the specified Allowable Values, where appropriate. The actual setpoint is calibrated consistent with applicable setpoint methodology assumptions. Each channel must also respond within its assumed response time, where appropriate.

Allowable Values are specified for each Primary Containment Isolation Function specified in the Table. Nominal trip setpoints are specified in the setpoint calculations. The nominal setpoints are selected to ensure that the setpoints do not exceed the Allowable Value between CHANNEL CALIBRATIONS. Operation with a trip setpoint less conservative than the nominal trip setpoint, but within its Allowable Value, is acceptable. A channel is inoperable if its actual trip setpoint is not within its required

(continued)

BASES

APPLICABLE SAFETY ANALYSES, LCO, and APPLICABILITY (continued)

Allowable Value. Trip setpoints are those predetermined values of output at which an action should take place. The setpoints are compared to the actual process parameter (e.g., reactor vessel water level), and when the measured output value of the process parameter exceeds the setpoint, the associated device (e.g., trip unit) changes state. The analytic limits are derived from the limiting values of the process parameters obtained from the safety analysis. The trip setpoints are determined from the analytic limits, corrected for defined process, calibration, and instrument errors. The Allowable Values are then determined, based on the trip setpoint values, by accounting for the calibration based errors. These calibration based errors are limited to reference accuracy, instrument drift, errors associated with measurement and test equipment, and calibration tolerance of loop components. The trip setpoints and Allowable Values determined in this manner provide adequate protection because instrument uncertainties, process effects, calibration tolerances, instrument drift, and severe environment errors (for channels that must function in harsh environments as defined by 10 CFR 50.49) are accounted for and appropriately applied for the instrumentation.

Certain Emergency Core Cooling Systems (ECCS) and RCIC valves (e.g., minimum flow) also serve the dual function of automatic PCIVs. The signals that isolate these valves are also associated with the automatic initiation of the ECCS and RCIC. Some instrumentation and ACTIONS associated with these signals are addressed in LCO 3.3.5.1, "ECCS Instrumentation," and LCO 3.3.5.2, "RCIC System Instrumentation," and are not included in this LCO.

In general, the individual Functions are required to be OPERABLE in MODES 1, 2, and 3 consistent with the Applicability for LCO 3.6.1.1, "Primary Containment." Functions that have different Applicabilities are discussed below in the individual Functions discussion.

The specific Applicable Safety Analyses, LCO, and Applicability discussions are listed below on a Function by Function basis.

(continued)

BASES

APPLICABLE SAFETY ANALYSES, LCO, and APPLICABILITY (continued)

1. Main Steam Line Isolation

1.a. Reactor Vessel Water Level – Low Low Low, Level 1

Low reactor pressure vessel (RPV) water level indicates that the capability to cool the fuel may be threatened. Should RPV water level decrease too far, fuel damage could result. Therefore, isolation of the MSIVs and other interfaces with the reactor vessel occurs to prevent offsite dose limits from being exceeded. The Reactor Vessel Water Level – Low Low Low, Level 1 Function is one of the many Functions assumed to be OPERABLE and capable of providing isolation signals. The Reactor Vessel Water Level – Low Low Low, Level 1 Function associated with isolation is assumed in the analysis of the recirculation line break (Ref. 2). The isolation of the MSL on Level 1 supports actions to ensure that offsite dose limits are not exceeded for a DBA.

Reactor vessel water level signals are initiated from four differential pressure transmitters that sense the difference between the pressure due to a constant column of water (reference leg) and the pressure due to the actual water level (variable leg) in the vessel. Four channels of Reactor Vessel Water Level – Low Low Low, Level 1 Function are available and are required to be OPERABLE to ensure that no single instrument failure can preclude the isolation function.

The Reactor Vessel Water Level – Low Low Low, Level 1 Allowable Value is chosen to be the same as the ECCS Level 1 Allowable Value (LCO 3.3.5.1) to ensure that the MSLs isolate on a potential loss of coolant accident (LOCA) to prevent offsite doses from exceeding 10 CFR 100 limits.

This Function isolates the Group 1 valves.

1.b. Main Steam Line Pressure – Low

Low MSL pressure indicates that there may be a problem with the turbine pressure regulation, which could result in a low reactor vessel water level condition and the RPV cooling down more than 100°F/hour if the pressure loss is allowed to continue. The Main Steam Line Pressure – Low Function is directly assumed in the analysis of the pressure regulator failure event (Ref. 4). The closure of the MSIVs ensures

(continued)

BASES

APPLICABLE SAFETY ANALYSES, LCO, and APPLICABILITY

1.b. Main Steam Line Pressure – Low (continued)

that the RPV temperature change limit (100°F/hour) is not reached. In addition, this Function supports actions to ensure that Safety Limit 2.1.1.1 is not exceeded. (This Function closes the MSIVs prior to pressure decreasing below 785 psig, which results in a scram due to MSIV closure, thus reducing reactor power to < 25% RTP.)

The MSL low pressure signals are initiated from four pressure switches that are connected downstream of the MSL header prior to each main turbine stop valve. The pressure switches are arranged such that, even though physically separated from each other, each switch is able to detect low MSL pressure. Four channels of Main Steam Line Pressure – Low Function are available and are required to be OPERABLE to ensure that no single instrument failure can preclude the isolation function.

The Allowable Value was selected to be high enough to prevent excessive RPV depressurization.

The Main Steam Line Pressure – Low Function is only required to be OPERABLE in MODE 1 since this is when the assumed transient can occur (Ref. 4).

This Function isolates the Group 1 valves.

1.c. Main Steam Line Flow – High

Main Steam Line Flow – High is provided to detect a break of the MSL and to initiate closure of the MSIVs. If the steam were allowed to continue flowing out of the break, the reactor would depressurize and the core could uncover. If the RPV water level decreases too far, fuel damage could occur. Therefore, the isolation is initiated on high flow to prevent or minimize core damage. The Main Steam Line Flow – High Function is directly assumed in the analysis of the main steam line break (MSLB) accident (Ref. 5). The isolation action, along with the scram function of the RPS, ensures that the fuel peak cladding temperature remains below the limits of 10 CFR 50.46 and offsite doses do not exceed the 10 CFR 100 limits.

(continued)

BASES

APPLICABLE SAFETY ANALYSES, LCO, and APPLICABILITY

1.c. Main Steam Line Flow – High (continued)

The MSL flow signals are initiated from 16 differential pressure switches that are connected to the four MSLs (the differential pressure switches sense differential pressure across a flow element). The switches are arranged such that, even though physically separated from each other, all four connected to one steam line would be able to detect the high flow. Four channels of Main Steam Line Flow – High Function for each MSL (two channels per trip system) are available and are required to be OPERABLE so that no single instrument failure will preclude detecting a break in any individual MSL.

The Allowable Value is chosen to ensure that offsite dose limits are not exceeded due to the break.

This Function isolates the Group 1 valves.

1.d. Condenser Vacuum – Low

The Condenser Vacuum – Low Function is provided to prevent overpressurization of the main condenser in the event of a loss of the main condenser vacuum (Ref. 6). Since the integrity of the condenser is an assumption in offsite dose calculations (Ref. 7), the Condenser Vacuum – Low Function is assumed to be OPERABLE and capable of initiating closure of the MSIVs. The closure of the MSIVs is initiated to prevent the addition of steam that would lead to additional condenser pressurization and possible rupture of the diaphragm installed to protect the turbine exhaust hood, thereby preventing a potential radiation leakage path following an accident.

Condenser vacuum pressure signals are derived from four pressure switches that sense the pressure in the condenser. Four channels of Condenser Vacuum – Low Function are available and are required to be OPERABLE to ensure no single instrument failure can preclude the isolation function.

(continued)

BASES

APPLICABLE SAFETY ANALYSES, LCO, and APPLICABILITY

1.d. Condenser Vacuum – Low (continued)

The Allowable Value is chosen to prevent damage to the condenser due to pressurization, thereby ensuring its integrity for offsite dose analysis. As noted (footnote (a) to Table 3.3.6.1-1), the channels are not required to be OPERABLE in MODES 2 and 3, when all turbine stop valves (TSVs) are closed, since the potential for condenser overpressurization is minimized. Switches are provided to manually bypass the channels when all TSVs are closed.

This Function isolates the Group 1 valves.

1.e Main Steam Line Tunnel Differential Temperature – High

Differential Temperature – High is provided to detect a leak in a main steam line, and provides diversity to the high flow instrumentation. The isolation occurs when a very small leak has occurred. If the small leak is allowed to continue without isolation, offsite dose limits may be reached. However, credit for these instruments is not taken in any transient or accident analysis in the UFSAR, since bounding analyses are performed for large breaks such as MSLBs.

Eight thermocouples provide input to the Main Steam Line Tunnel Differential Temperature – High Function. The output of these thermocouples is used to determine the differential temperature. Each channel consists of a differential temperature instrument that receives inputs from thermocouples that are located in the inlet and outlet of the main steam line tunnel for a total of four available channels. Four channels of Main Steam Line Tunnel Differential Temperature – High Function are available and are required to be OPERABLE to ensure that no single instrument failure can preclude the isolation function.

The differential temperature monitoring Allowable Value is chosen to detect a leak equivalent to 100 gpm.

These Functions isolate the Group 1 valves.

(continued)

BASES

APPLICABLE SAFETY ANALYSES, LCO, and APPLICABILITY (continued)

1.f. Manual Initiation

The Manual Initiation push button channels introduce signals into the MSL isolation logic that are redundant to the automatic protective instrumentation and provide manual isolation capability. There is no specific UFSAR safety analysis that takes credit for this Function. It is retained for overall redundancy and diversity of the isolation function as required by the NRC in the plant licensing basis.

There are four push buttons for the logic, with two manual initiation push buttons per trip system. Four channels of Manual Initiation Function are available and are required to be OPERABLE in MODES 1, 2, and 3, since these are the MODES in which the MSL Isolation automatic Functions are required to be OPERABLE.

There is no Allowable Value for this Function since the channels are mechanically actuated based solely on the position of the push buttons.

This Function isolates the Group 1 valves.

2. Primary Containment Isolation

2.a Reactor Vessel Water Level – Low Low, Level 2

Low RPV water level indicates the capability to cool the fuel may be threatened. The valves whose penetrations communicate with the primary containment are isolated to limit the release of fission products. The isolation of the primary containment on Level 2 supports actions to ensure that offsite dose limits of 10 CFR 100 are not exceeded. The Reactor Vessel Water Level – Low Low, Level 2 Function associated with isolation is implicitly assumed in the UFSAR analysis as these leakage paths are assumed to be isolated post LOCA.

Reactor Vessel Water Level – Low Low, Level 2 signals are initiated from differential pressure transmitters that sense the difference between the pressure due to a constant column of water (reference leg) and the pressure due to the actual

(continued)

BASES

APPLICABLE SAFETY ANALYSES, LCO, and APPLICABILITY

2.a Reactor Vessel Water Level – Low Low, Level 2 (continued)

water level (variable leg) in the vessel. Four channels of Reactor Vessel Water Level – Low Low, Level 2 Function are available and are required to be OPERABLE to ensure no single instrument failure can preclude the isolation function.

The Reactor Vessel Water Level – Low Low, Level 2 Allowable Value was chosen to be the same as the ECCS Reactor Vessel Water Level – Low Low, Level 2 Allowable Value (LCO 3.3.5.1), since isolation of these valves is not critical to orderly plant shutdown.

This Function isolates the Group 2, 3, and 4 valves.

2.b Drywell Pressure – High

High drywell pressure can indicate a break in the RCPB inside the drywell. The isolation of some of the PCIVs on high drywell pressure supports actions to ensure that offsite dose limits of 10 CFR 100 are not exceeded. The Drywell Pressure – High Function associated with isolation of the primary containment is implicitly assumed in the UFSAR accident analysis as these leakage paths are assumed to be isolated post LOCA.

High drywell pressure signals are initiated from pressure switches that sense the pressure in the drywell. Four channels of Drywell Pressure – High Function are available and are required to be OPERABLE to ensure that no single instrument failure can preclude the isolation function.

The Allowable Value was selected to be the same as the RPS Drywell Pressure – High Allowable Value (LCO 3.3.1.1), since this may be indicative of a LOCA inside primary containment.

This Function isolates the Group 2, 4, 7, and 10 valves.

(continued)

BASES

APPLICABLE SAFETY ANALYSES, LCO, and APPLICABILITY (continued)

2.c. Reactor Building Ventilation Exhaust Plenum Radiation – High

High ventilation exhaust radiation is an indication of possible gross failure of the fuel cladding. The release may have originated from the primary containment due to a break in the RCPB or refueling floor due to a fuel handling accident. When Reactor Building Ventilation Exhaust Radiation – High is detected, valves whose penetrations communicate with the primary containment atmosphere are isolated to limit the release of fission products.

The Reactor Building Ventilation Exhaust Plenum Radiation – High signals are initiated from radiation detectors that are located in the reactor building return air riser above the upper area of the steam tunnel prior to the reactor building ventilation isolation dampers. The signal from each detector is input to an individual monitor whose trip outputs are assigned to an isolation channel. Four channels of Reactor Building Ventilation Exhaust Plenum Radiation – High Function are available and are required to be OPERABLE to ensure that no single instrument failure can preclude the isolation function.

The Allowable Values are chosen to promptly detect gross failure of the fuel cladding and to ensure offsite doses remain below 10 CFR 20 and 10 CFR 100 limits.

These Functions isolate the Group 4 valves.

2.d. Fuel Pool Ventilation Exhaust Radiation – High

High fuel pool ventilation exhaust radiation indicates increased airborne radioactivity levels in secondary containment refuel floor area which could be due to fission gases from the fuel pool resulting from a refueling accident. Since the primary and secondary containments may be in communication, the vent and purge valves for primary containment isolation are also provided with an isolation signal. Therefore, Fuel Pool Ventilation Exhaust Radiation – High Function initiates an isolation to assure timely closure of valves to protect against substantial releases of radioactive materials to the environment. While this Function is identified as initiating the Standby Gas Treatment System for a spent fuel cask drop accident

(continued)

BASES

APPLICABLE SAFETY ANALYSES, LCO, and APPLICABILITY

2.d. Fuel Pool Ventilation Exhaust Radiation – High (continued)

(Ref. 3), it is not assumed in any limiting accident or transient analysis in the UFSAR because other leakage paths (e.g., MSIVs) are more limiting.

The fuel pool ventilation exhaust radiation signals are initiated from radiation detectors located in the reactor building exhaust ducting coming from the refuel floor. The signal from each detector is input to an individual monitor whose trip output is assigned to an isolation channel. Four channels of Fuel Pool Ventilation Exhaust Radiation – High Function are available and are required to be OPERABLE to ensure that no single instrument failure can preclude the isolation function.

The Allowable Value is chosen to be the same as the Fuel Pool Ventilation Exhaust Radiation – High Function (LCO 3.3.6.2, "Secondary Containment Isolation Instrumentation") to provide a conservative isolation of this potential release path during this abnormal condition of increased airborne radioactivity.

This Function isolates the Group 4 valves.

2.e. Reactor Vessel Water Level – Low Low Low, Level 1

Low RPV water level indicates the capability to cool the fuel may be threatened. Should RPV water level decrease too far, fuel damage could result. Therefore, isolation of the primary containment occurs to prevent offsite dose limits from being exceeded. The Reactor Vessel Water Level – Low Low Low, Level 1 Function is one of the many Functions assumed to be OPERABLE and capable of providing isolation signals. The Reactor Vessel Water Level – Low Low Low, Level 1 Function associated with isolation is implicitly assumed in the UFSAR analysis as these leakage paths are assumed to be isolated post LOCA.

Reactor vessel water level signals are initiated from level transmitters that sense the difference between the pressure due to a constant column of water (reference leg) and the pressure due to the actual water level (variable leg) in the vessel. Four channels of Reactor Vessel Water Level – Low

(continued)

BASES

APPLICABLE SAFETY ANALYSES, LCO, and APPLICABILITY

2.e. Reactor Vessel Water Level – Low Low Low, Level 1 (continued)

Low Low, Level 1 Function are available and are required to be OPERABLE to ensure that no single instrument failure can preclude the isolation function.

The Reactor Vessel Water Level – Low Low Low, Level 1 Allowable Value is chosen to be the same as the ECCS Reactor Vessel Water Level – Low Low Low, Level 1 Allowable Value (LCO 3.3.5.1) to ensure the valves are isolated to prevent offsite doses from exceeding 10 CFR 100 limits.

This Function isolates the Group 10 valves.

2.f. Reactor Vessel Water Level–Low, Level 3

Low RPV water level indicates the capability to cool the fuel may be threatened. Should RPV water level decrease too far, fuel damage could result. Therefore, the valves whose penetrations communicate with the primary containment are isolated to limit the release of fission products. The isolation of the primary containment on Level 3 supports actions to ensure that offsite dose limits of 10 CFR 100 are not exceeded. The Reactor Vessel Water Level–Low, Level 3 Function associated with isolation is implicitly assumed in the UFSAR analysis as these leakage paths are assumed to be isolated post LOCA.

Reactor Vessel Water Level–Low, Level 3 signals are initiated from differential pressure transmitters that sense the difference between the pressure due to a constant column of water (reference leg) and the pressure due to the actual water level (variable leg) in the vessel. Four channels of the Reactor Vessel Water Level–Low, Level 3 Function are available and are required to be OPERABLE to ensure that no single instrument failure can preclude the isolation function.

The Reactor Vessel Water Level–Low, Level 3 Allowable Value was chosen to be the same as the RPS Reactor Vessel Water Level–Low, Level 3 Allowable Value (LCO 3.3.1.1) since the capability to cool the fuel may be threatened.

This Function isolates the Group 7 valves.

(continued)

BASES

APPLICABLE SAFETY ANALYSES, LCO, and APPLICABILITY (continued)

2.g. Manual Initiation

The Manual Initiation push button channels introduce signals into the primary containment isolation logic that are redundant to the automatic protective instrumentation and provide manual isolation capability. There is no specific UFSAR safety analysis that takes credit for this Function. It is retained for overall redundancy and diversity of the isolation function as required by the NRC in the plant licensing basis.

There are two push buttons for the logic, one manual initiation push button per trip system. Two channels of the Manual Initiation Function are available and are required to be OPERABLE in MODES 1, 2, and 3, since these are the MODES in which the Primary Containment Isolation automatic Functions are required to be OPERABLE.

There is no Allowable Value for this Function since the channels are mechanically actuated based solely on the position of the push buttons.

This Function isolates the Group 2, 4, 7, and 10 valves.

3. Reactor Core Isolation Cooling System Isolation

3.a. RCIC Steam Line Flow—High

RCIC Steam Line Flow—High Function is provided to detect a break of the RCIC steam lines and initiates closure of the steam line isolation valves. If the steam is allowed to continue flowing out of the break, the reactor will depressurize and core uncovery can occur. Therefore, the isolation is initiated on high flow to prevent or minimize core damage. The isolation action, along with the scram function of the Reactor Protection System (RPS), ensures that the fuel peak cladding temperature remains below the limits of 10 CFR 50.46. Specific credit for this Function is not assumed in any UFSAR accident analyses since the bounding analysis is performed for large breaks such as recirculation and MSL breaks. However, these instruments prevent the RCIC steam line break from becoming bounding.

(continued)

BASES

APPLICABLE SAFETY ANALYSES, LCO, and APPLICABILITY

3.a. RCIC Steam Line Flow – High (continued)

The RCIC Steam Line Flow – High signals are initiated from two differential pressure switches that are connected to the system steam lines. Two channels of RCIC Steam Line Flow – High Functions are available and are required to be OPERABLE to ensure that no single instrument failure can preclude the isolation function.

The Allowable Value is chosen to be low enough to ensure that the trip occurs to prevent fuel damage and maintains the MSLB event as the bounding event.

This Function isolates the Group 8 valves.

3.b. RCIC Steam Line Flow – Timer

The RCIC Steam Line Flow – Timer is provided to prevent false isolations on RCIC Steam Line Flow – High during system startup transients and therefore improves system reliability. This Function is not assumed in any UFSAR transient or accident analyses since the bounding analysis is performed for large breaks such as recirculation and MSL breaks. However, these instruments prevent the RCIC steam line break from being bounding.

The RCIC Steam Line Flow–Timer Function delays the RCIC Steam Line Flow – High signals by use of time delay relays. When an RCIC Steam Line Flow – High signal is generated, the time delay relays delay the tripping of the associated RCIC isolation trip system for a short time. Two channels of RCIC Steam Line Flow – Timer Function are available and are required to be OPERABLE to ensure that no single instrument failure can preclude the isolation function.

The Allowable Value was chosen to be long enough to prevent false isolations due to system starts but not so long as to impact offsite dose calculations.

This Function isolates the Group 8 valves.

(continued)

BASES

APPLICABLE SAFETY ANALYSES, LCO, and APPLICABILITY (continued)

3.c. RCIC Steam Supply Pressure – Low

Low RCIC steam supply pressure indicates that the pressure of the steam in the RCIC turbine may be too low to continue operation of the RCIC turbine. This isolation is for equipment protection and is not assumed in any transient or accident analysis in the UFSAR. However, it also provides a diverse signal to indicate a possible system break. These instruments are included in the Technical Specifications (TS) because of the potential for risk due to possible failure of the instruments preventing RCIC initiations. Therefore, they meet Criterion 4 of 10 CFR 50.36(c)(2)(ii).

The RCIC Steam Supply Pressure – Low signals are initiated from four pressure switches that are connected to the RCIC steam line. Four channels of RCIC Steam Supply Pressure – Low Function are available and are required to be OPERABLE to ensure that no single instrument failure can preclude the isolation function.

The Allowable Value is selected to be high enough to prevent damage to the RCIC turbines.

This Function isolates the Group 8 valves. This Function coincident with Drywell Pressure – High also isolates the Group 9 valves.

3.d. RCIC Turbine Exhaust Diaphragm Pressure – High

High turbine exhaust diaphragm pressure indicates that the pressure may be too high to continue operation of the RCIC turbine. That is, one of two exhaust diaphragms has ruptured and pressure is reaching turbine casing pressure limits. This isolation is for equipment protection and is not assumed in any transient or accident analysis in the UFSAR. These instruments are included in the TS because of the potential for risk due to possible failure of the instruments preventing RCIC initiations. Therefore, they meet Criterion 4 of 10 CFR 50.36(c)(2)(ii).

The RCIC Turbine Exhaust Diaphragm Pressure – High signals are initiated from four pressure switches that are connected to the area between the rupture diaphragms on the RCIC turbine exhaust line. Four channels of RCIC Turbine Exhaust

(continued)

BASES

APPLICABLE SAFETY ANALYSES, LCO, and APPLICABILITY

3.d. RCIC Turbine Exhaust Diaphragm Pressure – High (continued)

Diaphragm Pressure – High Function are available and are required to be OPERABLE to ensure that no single instrument failure can preclude the isolation function.

The Allowable Value is selected to be low enough to prevent damage to the RCIC turbine.

This Function isolates the Group 8 valves.

3.e, 3.f, 3.g, 3.h. Area and Differential Temperature – High

Area and Differential Temperatures are provided to detect a leak from the RCIC steam piping. The isolation occurs when a very small leak has occurred and is diverse to the high flow instrumentation. If the small leak is allowed to continue without isolation, offsite dose limits may be reached. These Functions are not assumed in any UFSAR transient or accident analysis, since bounding analyses are performed for large breaks such as recirculation or MSL breaks.

Area Temperature – High signals are initiated from thermocouples that are located in the area that is being monitored. Two instruments monitor each area. Four channels for Area Temperature – High Function are available and are required to be OPERABLE to ensure that no single instrument failure can preclude the isolation function. There are two for the RCIC equipment room and two for the RCIC steam line tunnel area.

There are 8 thermocouples (four for the RCIC equipment room and four for the RCIC steam line tunnel area) that provide input to the Differential Temperature – High Function. The output of these thermocouples is used to determine the differential temperature. Each channel consists of a differential temperature instrument that receives inputs from thermocouples that are located in the inlet and outlet of the area cooling system for a total of four (two for the RCIC equipment room and two for the RCIC steam line tunnel area) available channels.

(continued)

BASES

APPLICABLE SAFETY ANALYSES, LCO, and APPLICABILITY

3.e, 3.f, 3.g, 3.h. Area and Differential Temperature – High (continued)

The Allowable Values are set low enough to detect a leak equivalent to 25 gpm.

This Function isolates the Group 8 valves.

3.i. Drywell Pressure – High

High drywell pressure can indicate a break in the RCPB. The RCIC isolation of the turbine exhaust is provided to prevent communication with the drywell when high drywell pressure exists. A potential leakage path exists via the turbine exhaust. The isolation is delayed until the system becomes unavailable for injection (i.e., low steam line pressure). The isolation of the RCIC turbine exhaust by Drywell Pressure – High is indirectly assumed in the UFSAR accident analysis because the turbine exhaust leakage path is not assumed to contribute to offsite doses.

High drywell pressure signals are initiated from pressure switches that sense the pressure in the drywell. Four channels of RCIC Drywell Pressure – High Function are available and are required to be OPERABLE to ensure that no single instrument failure can preclude the isolation function.

The Allowable Value was selected to be the same as the ECCS Drywell Pressure – High Allowable Value (LCO 3.3.5.1), since this is indicative of a LOCA inside primary containment.

This Function coincident with RCIC Steam Supply Pressure – Low isolates the Group 9 valves.

3.j. Manual Initiation

The Manual Initiation push button channel introduces a signal into the RCIC System isolation logic that is redundant to the automatic protective instrumentation and provides manual isolation capability when a system initiation signal is present. There is no specific UFSAR safety analysis that takes credit for this Function. It is

(continued)

BASES

APPLICABLE SAFETY ANALYSES, LCO, and APPLICABILITY

3.j. Manual Initiation (continued)

retained for overall redundancy and diversity of the isolation function as required by the NRC in the plant licensing basis.

There is one push button for RCIC. One channel of Manual Initiation Function is available and is required to be OPERABLE in MODES 1, 2, and 3 since these are the MODES in which the RCIC System Isolation automatic Functions are required to be OPERABLE. As noted (footnote (b) to Table 3.3.6.1-1), this Function only provides input into one of the two trip systems.

There is no Allowable Value for this Function since the channels are mechanically actuated based solely on the position of the push buttons.

This Function, coincident with a Reactor Vessel Water Level – Low Low, Level 2, isolates the outboard Group 8 valve.

4. Reactor Water Cleanup System Isolation

4.a. Differential Flow – High

The high differential flow signal is provided to detect a break in the RWCU System. This will detect leaks in the RWCU System when area or differential temperature would not provide detection (i.e., a cold leg break). Should the reactor coolant continue to flow out of the break, offsite dose limits may be exceeded. Therefore, isolation of the RWCU System is initiated when high differential flow is sensed to prevent exceeding offsite doses. A time delay (Function 4.b, described below) is provided to prevent spurious trips during most RWCU operational transients. This Function is not assumed in any UFSAR transient or accident analysis, since bounding analyses are performed for large breaks such as MSLBs.

The high differential flow signals are initiated from one differential pressure transmitter monitoring inlet flow (from the reactor vessel) and two transmitters monitoring system outlet flow to the two available flow paths (normal return to feedwater and discharge flow to either the main

(continued)

BASES

APPLICABLE SAFETY ANALYSES, LCO, and APPLICABILITY

4.a. Differential Flow – High (continued)

condenser or radwaste). The outputs of the transmitters are compared (in a summer) and the outputs are sent to two alarm trip units. If the difference between the inlet and outlet flow is too large, each alarm trip unit generates an isolation signal. Two channels of Differential Flow – High Function are available and are required to be OPERABLE to ensure that no single instrument failure (other than the common transmitters and summers) can preclude the isolation function.

The Differential Flow – High Allowable Value ensures that the break of the RWCU piping is detected.

This Function isolates the Group 5 valves.

4.b. Differential Flow – Timer

The Differential Flow – Timer is provided to avoid RWCU System isolations due to operational transients (such as pump starts and mode changes). During these transients the inlet and return flows become unbalanced for short time periods and Differential Flow – High will be sensed without an RWCU System break being present. Credit for this Function is not assumed in the UFSAR accident or transient analysis, since bounding analyses are performed for large breaks such as MSLBs.

The Differential Flow – Timer Function delays the Differential Flow – High signals by use of time delay relays. When a Differential Flow – High signal is generated, the time delay relays delay the tripping of the associated RWCU isolation trip system for a short time. Two channels of Differential Flow – Timer Function are available and are required to be OPERABLE to ensure that no single instrument failure can preclude the isolation function.

The Differential Flow – Timer Allowable Value is selected to ensure that the MSLB outside containment remains the limiting break for UFSAR analysis for offsite dose calculations.

This Function isolates the Group 5 valves.

(continued)

BASES

APPLICABLE SAFETY ANALYSES, LCO, and APPLICABILITY (continued)

4.c, 4.d, 4.e, 4.f, 4.g, 4.h, 4.i, 4.j, Area Differential Temperature – High

Area and Differential Temperature – High is provided to detect a leak from the RWCU System. The isolation occurs even when very small leaks have occurred and is diverse to the high differential flow instrumentation for the hot portions of the RWCU System. If the small leak continues without isolation, offsite dose limits may be reached. Credit for these instruments is not taken in any transient or accident analysis in the UFSAR, since bounding analyses are performed for large breaks such as MSLBs.

Area Temperature – High signals are initiated from temperature elements that are located in the room that is being monitored. There are fourteen thermocouples that provide input to the Area Temperature – High Function (two per area). Fourteen channels are required to be OPERABLE to ensure that no single instrument failure can preclude the isolation function. There are four channels for the RWCU heat exchanger area (two in each heat exchanger room), six channels for the RWCU pump and valve room (two in each of the three rooms), two channels for the holdup pipe area, and two channels for the filter/demineralizer valve room area.

There are twenty eight thermocouples that provide input to the Differential Temperature – High Function. The output of these thermocouples is used to determine the differential temperature. Each channel consists of a differential temperature instrument that receives inputs from thermocouples that are located in the inlet and outlet of the area cooling system for a total of fourteen available channels (two per area). Fourteen channels are required to be OPERABLE to ensure that no single instrument failure can preclude the isolation function. There are four channels for the RWCU heat exchanger area, six channels for the RWCU pump and valve room, two channels for the holdup pipe area, and two for the filter/demineralizer valve room area.

The Area and Differential Temperature – High Allowable Values are set low enough to detect a leak equivalent to 25 gpm.

These Functions isolate the Group 5 valves.

(continued)

BASES

APPLICABLE SAFETY ANALYSES, LCO, and APPLICABILITY (continued)

4.k. Reactor Vessel Water Level – Low Low, Level 2

Low RPV water level indicates the capability to cool the fuel may be threatened. Should RPV water level decrease too far, fuel damage could result. Therefore, isolation of some reactor vessel interfaces occurs to isolate the potential sources of a break. The isolation of the RWCU System on Level 2 supports actions to ensure that fuel peak cladding temperature remains below the limits of 10 CFR 50.46. The Reactor Vessel Water Level – Low Low, Level 2 Function associated with RWCU isolation is not directly assumed in any transient or accident analysis, since bounding analyses are performed for large breaks such as MSLBs.

Reactor Vessel Water Level – Low Low, Level 2 signals are initiated from differential pressure transmitters that sense the difference between the pressure due to a constant column of water (reference leg) and the pressure due to the actual water level (variable leg) in the vessel. Four channels of Reactor Vessel Water Level – Low Low, Level 2 Function are available and are required to be OPERABLE to ensure that no single instrument failure can preclude the isolation function.

The Reactor Vessel Water Level – Low Low, Level 2 Allowable Value was chosen to be the same as the ECCS Reactor Vessel Water Level – Low Low, Level 2 Allowable Value (LCO 3.3.5.1), since the capability to cool the fuel may be threatened.

This Function isolates the Group 5 valves.

4.l. SLC System Initiation

The isolation of the RWCU System is required when the SLC System has been initiated to prevent dilution and removal of the boron solution by the RWCU System (Ref. 8). SLC System initiation signals are initiated from the two SLC pump start signals.

Two channels (one from each pump) of SLC System Initiation Function are available and are required to be OPERABLE only in MODES 1 and 2, since these are the only MODES where the reactor can be critical, and these MODES are consistent with the Applicability for the SLC System (LCO 3.1.7, "SLC

(continued)

BASES

APPLICABLE SAFETY ANALYSES, LCO, and APPLICABILITY

4.l. SLC System Initiation (continued)

System"). As noted (footnote (b) to Table 3.3.6.1-1), this Function only provides input into one of two trip systems.

There is no Allowable Value associated with this Function since the channels are mechanically actuated based solely on the position of the SLC System initiation switches.

This Function isolates the outboard Group 5 valve.

4.m. Manual Initiation

The Manual Initiation push button channels introduce signals into the RWCU System isolation logic that are redundant to the automatic protective instrumentation and provide manual isolation capability. There is no specific UFSAR safety analysis that takes credit for this Function. It is retained for overall redundancy and diversity of the isolation function as required by the NRC in the plant licensing basis.

There are two push buttons for the logic, one manual initiation push button per trip system. Two channels of the Manual Initiation Function are available and are required to be OPERABLE in MODES 1, 2, and 3 since these are the MODES in which the RWCU System Isolation automatic Functions are required to be OPERABLE.

There is no Allowable Value for this Function, since the channels are mechanically actuated based solely on the position of the push buttons.

This Function isolates the Group 5 valves.

5. RHR Shutdown Cooling System Isolation

5.a. Reactor Vessel Water Level – Low, Level 3

Low RPV water level indicates the capability to cool the fuel may be threatened. Should RPV water level decrease too far, fuel damage could result. Therefore, isolation of some reactor vessel interfaces occurs to begin isolating the potential sources of a break. The Reactor Vessel Water

(continued)

BASES

APPLICABLE SAFETY ANALYSES, LCO, and APPLICABILITY

5.a. Reactor Vessel Water Level – Low, Level 3 (continued)

Level – Low, Level 3 Function associated with RHR Shutdown Cooling System isolation is not directly assumed in any transient or accident analysis, since bounding analyses are performed for large breaks such as MSLBs. The RHR Shutdown Cooling System isolation on Level 3 supports actions to ensure that the RPV water level does not drop below the top of the active fuel during a vessel draindown event caused by a leak (e.g., pipe break or inadvertent valve opening) in the RHR Shutdown Cooling System.

Reactor Vessel Water Level – Low, Level 3 signals are initiated from differential pressure transmitters that sense the difference between the pressure due to a constant column of water (reference leg) and the pressure due to the actual water level (variable leg) in the vessel. Four channels (two channels per trip system) of the Reactor Vessel Water Level – Low, Level 3 Function are available and are required to be OPERABLE to ensure that no single instrument failure can preclude the isolation function. As noted (footnote (c) to Table 3.3.6.1-1), only one trip system is required to be OPERABLE in MODES 4 and 5 provided the RHR Shutdown Cooling System integrity is maintained. System integrity is maintained provided the piping is intact and no maintenance is being performed that has the potential for draining the reactor vessel through the system.

The Reactor Vessel Water Level – Low, Level 3 Function is only required to be OPERABLE in MODES 3, 4, and 5 to prevent this potential flow path from lowering reactor vessel level to the top of the fuel. In MODES 1 and 2, the Reactor Vessel Pressure – High Function and administrative controls ensure that this flow path remains isolated to prevent unexpected loss of inventory via this flow path.

The Reactor Vessel Water Level – Low, Level 3 Allowable Value was chosen to be the same as the RPS Reactor Vessel Water Level – Low, Level 3 Allowable Value (LCO 3.3.1.1) since the capability to cool the fuel may be threatened.

This Function isolates the Group 6 valves.

(continued)

BASES

APPLICABLE SAFETY ANALYSES, LCO, and APPLICABILITY (continued)

5.b. Reactor Vessel Pressure – High

The Shutdown Cooling System Reactor Vessel Pressure – High Function is provided to isolate the shutdown cooling portion of the RHR System. This interlock is provided only for equipment protection to prevent an intersystem LOCA scenario and credit for the interlock is not assumed in the accident or transient analysis in the UFSAR.

The Reactor Vessel Pressure – High signals are initiated from two pressure switches. Two channels of Reactor Vessel Pressure – High Function are available and are required to be OPERABLE to ensure that no single instrument failure can preclude the isolation function.

The Allowable Value (corrected for cold water head and reactor vessel flooded) was chosen to be low enough to protect the system equipment from overpressurization.

This Function isolates the Group 6 valves.

5.c. Manual Initiation

The Manual Initiation push button channels introduce signals into the RHR Shutdown Cooling System isolation logic that are redundant to the automatic protective instrumentation and provide manual isolation capability. There is no specific UFSAR safety analysis that takes credit for this Function. It is retained for overall redundancy and diversity of the isolation function as required by the NRC in the plant licensing basis.

There is one push button for the logic per trip system. Two channels of the Manual Initiation Function are available and are required to be OPERABLE in MODES 1, 2, and 3 since these are the MODES in which the RHR Shutdown Cooling System Isolation automatic Functions are required to be OPERABLE. While certain automatic Functions are required in MODES 4 and 5, the Manual Initiation Function is not required in MODES 4 and 5, since there are other means (i.e., means other than the Manual Initiation push buttons) to manually isolate the RHR Shutdown Cooling System from the control room.

(continued)

BASES

APPLICABLE SAFETY ANALYSES, LCO, and APPLICABILITY

5.c. Manual Initiation (continued)

There is no Allowable Value for this Function, since the channels are mechanically actuated based solely on the position of the push buttons.

This Function isolates the Group 6 valves.

ACTIONS

Note 1 has been provided to modify the ACTIONS related to primary containment isolation instrumentation channels. Section 1.3, Completion Times, specifies that once a Condition has been entered, subsequent divisions, subsystems, components, or variables expressed in the Condition discovered to be inoperable or not within limits will not result in separate entry into the Condition. Section 1.3 also specifies that Required Actions of the Condition continue to apply for each additional failure, with Completion Times based on initial entry into the Condition. However, the Required Actions for inoperable primary containment isolation instrumentation channels provide appropriate compensatory measures for separate inoperable channels. As such, a Note has been provided that allows separate Condition entry for each inoperable primary containment isolation instrumentation channel.

Note 2 indicates that when automatic isolation capability is lost for Function 1.e, Main Steam Line Tunnel Differential Temperature – High (i.e., when both trip systems are inoperable for Function 1.e) due to required Reactor Building Ventilation System corrective maintenance, filter changes, damper cycling, or for performance of required Surveillances, entry into the associated Conditions and Required Actions may be delayed for up to 4 hours. Similarly, Note 3 indicates that when automatic isolation capability is lost for Function 1.e due to a loss of reactor building ventilation or for performance of SR 3.6.4.1.3 or SR 3.6.4.1.4, entry into the associated Conditions and Required Actions may be delayed for up to 12 hours. Upon completion of the activities or expiration of the time allowance, the channels must be returned to OPERABLE status or the applicable Conditions entered and Required Actions taken. These Notes are necessary so that testing and

(continued)

BASES

ACTIONS (continued)

required Surveillances specified in LCO 3.6.4.1, "Secondary Containment," LCO 3.6.4.2, "Secondary Containment Isolation Valves (SCIV)," and LCO 3.6.4.3, "Standby Gas Treatment (SGT) System," can be performed without inducing an isolation of the MSIVs. The 4 hour and 12 hour allowances provide sufficient time to safely perform the testing. The 12 hour allowance also provides sufficient time to identify and correct minor reactor building ventilation system problems. Since the design of the Unit 1 and Unit 2 reactor buildings is such that they share a common area of the refuel floor (i.e., the reactor buildings are not separated on the refuel floor), operation of either unit's ventilation system will affect the other unit's building differential pressure. Performance of testing to verify secondary containment integrity requirements and minor correctable problems could require a dual unit outage (without the Notes).

A.1

Because of the diversity of sensors available to provide isolation signals and the redundancy of the isolation design, an allowable out of service time of 12 hours or 24 hours, depending on the Function (12 hours for those Functions that have channel components common to RPS instrumentation and 24 hours for those Functions that do not have channel components common to RPS instrumentation), has been shown to be acceptable (Refs. 9 and 10) to permit restoration of any inoperable channel to OPERABLE status. This out of service time is only acceptable provided the associated Function is still maintaining isolation capability (refer to Required Action B.1 Bases). If the inoperable channel cannot be restored to OPERABLE status within the allowable out of service time, the channel must be placed in the tripped condition per Required Action A.1. Placing the inoperable channel in trip would conservatively compensate for the inoperability, restore capability to accommodate a single failure, and allow operation to continue with no further restrictions. Alternately, if it is not desired to place the channel in trip (e.g., as in the case where placing the inoperable channel in trip would result in an isolation), Condition C must be entered and its Required Action taken.

(continued)

BASES

ACTIONS (continued)

B.1

Required Action B.1 is intended to ensure that appropriate actions are taken if multiple, inoperable, untripped channels within the same Function result in redundant automatic isolation capability being lost for the associated penetration flow path(s). The MSIVs portion of the MSL isolation Functions are considered to be maintaining isolation capability when sufficient channels are OPERABLE or in trip such that both trip systems will generate a trip signal from the given Function on a valid signal. The MSL drain valves portion of the MSL isolation Functions and the other isolation Functions are considered to be maintaining isolation capability when sufficient channels are OPERABLE or in trip such that one trip system will generate a trip signal from the given Function on a valid signal. This ensures that one of the two PCIVs in the associated penetration flow path can receive an isolation signal from the given Function. For the MSIVs portion of Functions 1.a, 1.b, 1.d, and 1.e, this would require both trip systems to have one channel OPERABLE or in trip. For the MSL drain valves portion of Functions 1.a, 1.b, 1.d, and 1.e, this would require one trip system to have two channels, each OPERABLE or in trip. For the MSIVs portion of Function 1.c, this would require both trip systems to have one channel, associated with each MSL, OPERABLE or in trip. For the MSL drain valves portion of Function 1.c, this would require one trip system to have two channels, associated with each MSL, each OPERABLE or in trip. For Functions 2.a, 2.b, 2.c, 2.d, 2.e, 2.f, 3.c (for Group 8 valves) 3.d, 4.k, and 5.a, this would require one trip system to have two channels, each OPERABLE or in trip. For Functions 3.a, 3.b, 3.c (for Group 9 valves), 3.e, 3.f, 3.g, 3.h, 3.i, 4.a, 4.b, 4.g, 4.h, 4.i, 4.j, 4.l, and 5.b, this would require one trip system to have one channel OPERABLE or in trip. For Functions 4.c, 4.d, 4.e, and 4.f each Function consists of channels that monitor several different areas. Therefore, this would require one channel per area to be OPERABLE or in trip (the channels are not required to be in the same trip system). The Condition does not include the Manual Initiation Functions (Functions 1.f, 2.g, 3.j, 4.m, and 5.c), since they are not assumed in any accident or transient analysis. Thus, a total loss of manual initiation capability for 24 hours (as allowed by Required Action A.1) is allowed.

(continued)

BASES

ACTIONS

B.1 (continued)

The Completion Time is intended to allow the operator time to evaluate and repair any discovered inoperabilities. The Completion Time is acceptable because it minimizes risk while allowing time for restoration or tripping of channels.

C.1

Required Action C.1 directs entry into the appropriate Condition referenced in Table 3.3.6.1-1. The applicable Condition specified in Table 3.3.6.1-1 is Function and MODE or other specified condition dependent and may change as the Required Action of a previous Condition is completed. Each time an inoperable channel has not met any Required Action of Condition A or B and the associated Completion Time has expired, Condition C will be entered for that channel and provides for transfer to the appropriate subsequent Condition.

D.1, D.2.1, and D.2.2

If the channel is not restored to OPERABLE status or placed in trip within the allowed Completion Time, the associated MSLs may be isolated (Required Action D.1), and if allowed (i.e., plant safety analysis allows operation with an MSL isolated), plant operation with the MSL isolated may continue. Isolating the affected MSL accomplishes the safety function of the inoperable channel. This Required Action will generally only be used if a Function 1.c channel is inoperable and untripped. The associated MSL(s) to be isolated are those whose Main Steam Line Flow—High Function channel(s) are inoperable. Alternatively, the plant must be placed in a MODE or other specified condition in which the LCO does not apply. This is done by placing the plant in at least MODE 3 within 12 hours and in MODE 4 within 36 hours (Required Actions D.2.1 and D.2.2). The Completion Times are reasonable, based on operating experience, to reach the required plant conditions from full power conditions in an orderly manner and without challenging plant systems.

(continued)

BASES

ACTIONS (continued)

E.1

If the channel is not restored to OPERABLE status or placed in trip within the allowed Completion Time, the plant must be placed in a MODE or other specified condition in which the LCO does not apply. This is done by placing the plant in at least MODE 2 within 6 hours.

The allowed Completion Time of 6 hours is reasonable, based on operating experience, to reach MODE 2 from full power conditions in an orderly manner and without challenging plant systems.

F.1

If the channel is not restored to OPERABLE status or placed in trip within the allowed Completion Time, plant operation may continue if the affected penetration flow path(s) is isolated. Isolating the affected penetration flow path(s) accomplishes the safety function of the inoperable channels.

For some of the Area and Differential Temperature – High Functions, the affected penetration flow path(s) may be considered isolated by isolating only that portion of the system in the associated room monitored by the inoperable channel. That is, if the RWCU pump room A Area Temperature – High channel is inoperable, the A pump room area can be isolated while allowing continued RWCU operation utilizing the B RWCU pump.

Alternatively, if it is not desired to isolate the affected penetration flow path(s) (e.g., as in the case where isolating the penetration flow path(s) could result in a reactor scram), Condition H must be entered and its Required Actions taken.

The Completion Time is acceptable because it minimizes risk while allowing sufficient time for plant operations personnel to isolate the affected penetration flow path(s).

(continued)

BASES

ACTIONS (continued)

G.1

If the channel is not restored to OPERABLE status or placed in trip within the allowed Completion Time, plant operations may continue if the affected penetration flow path(s) is isolated. Isolating the affected penetration flow path(s) accomplishes the safety function of the inoperable channels. The 24 hour Completion Time is acceptable due to the fact that these Functions (Manual Initiation) are not assumed in any accident or transient analysis in the UFSAR. Alternately, if it is not desired to isolate the affected penetration flow path(s) (e.g., as in the case where isolating the penetration flow path(s) could result in a reactor scram), Condition H must be entered and its Required Actions taken.

H.1 and H.2

If the channel is not restored to OPERABLE status or placed in trip, or any Required Action of Condition F or G is not met and the associated Completion Time has expired, the plant must be placed in a MODE or other specified condition in which the LCO does not apply. This is done by placing the plant in at least MODE 3 within 12 hours and in MODE 4 within 36 hours. The allowed Completion Times are reasonable, based on operating experience, to reach the required plant conditions from full power conditions in an orderly manner and without challenging plant systems.

I.1 and I.2

If the channel is not restored to OPERABLE status within the allowed Completion Time, the associated SLC subsystem(s) is declared inoperable or the RWCU System is isolated. Since this Function is required to ensure that the SLC System performs its intended function, sufficient remedial measures are provided by declaring the associated SLC subsystem inoperable or isolating the RWCU System.

The Completion Time of 1 hour is acceptable because it minimizes risk while allowing sufficient time for personnel to isolate the RWCU System.

(continued)

BASES

ACTIONS (continued)

J.1 and J.2

If the channel is not restored to OPERABLE status or placed in trip within the allowed Completion Time, the associated penetration flow path should be closed. However, if the shutdown cooling function is needed to provide core cooling, these Required Actions allow the penetration flow path to remain unisolated provided action is immediately initiated to restore the channel to OPERABLE status or to isolate the RHR Shutdown Cooling System (i.e., provide alternate decay heat removal capabilities so the penetration flow path can be isolated). ACTIONS must continue until the channel is restored to OPERABLE status or the RHR Shutdown Cooling System is isolated.

SURVEILLANCE REQUIREMENTS

As noted at the beginning of the SRs, the SRs for each Primary Containment Isolation Instrumentation Function are found in the SRs column of Table 3.3.6.1-1.

The Surveillances are also modified by a Note to indicate that when a channel is placed in an inoperable status solely for performance of required Surveillances, entry into associated Conditions and Required Actions may be delayed for up to 6 hours provided the associated Function maintains isolation capability. Upon completion of the Surveillance, or expiration of the 6 hour allowance, the channel must be returned to OPERABLE status or the applicable Condition entered and Required Actions taken. This Note is based on the reliability analyses (Refs. 9 and 10) assumption of the average time required to perform channel surveillance. That analysis demonstrated that the 6 hour testing allowance does not significantly reduce the probability that the PCIVs will isolate the penetration flow path(s) when necessary.

SR 3.3.6.1.1

Performance of the CHANNEL CHECK once every 12 hours ensures that a gross failure of instrumentation has not occurred. A CHANNEL CHECK is normally a comparison of the parameter indicated on one channel to a similar parameter on other channels. It is based on the assumption that instrument channels monitoring the same parameter should read

(continued)

BASES

SURVEILLANCE REQUIREMENTS

SR 3.3.6.1.1 (continued)

approximately the same value. Significant deviations between the instrument channels could be an indication of excessive instrument drift in one of the channels or something even more serious. A CHANNEL CHECK will detect gross channel failure; thus, it is key to verifying the instrumentation continues to operate properly between each CHANNEL CALIBRATION.

Agreement criteria are determined by the plant staff, based on a combination of the channel instrument uncertainties, including indication and readability. If a channel is outside the criteria, it may be an indication that the instrument has drifted outside its limit.

The Frequency is based on operating experience that demonstrates channel failure is rare. The CHANNEL CHECK supplements less formal, but more frequent, checks of channels during normal operational use of the displays associated with the channels required by the LCO.

SR 3.3.6.1.2

A CHANNEL FUNCTIONAL TEST is performed on each required channel to ensure that the channel will perform the intended function. A successful test of the required contact(s) of a channel relay may be performed by the verification of the change of state of a single contact of the relay. This clarifies what is an acceptable CHANNEL FUNCTIONAL TEST of a relay. This is acceptable because all of the other required contacts of the relay are verified by other Technical Specifications and non-Technical Specifications tests at least once per refueling interval with applicable extensions. Any setpoint adjustment shall be consistent with the assumptions of the current plant specific setpoint methodology.

The Frequency of 92 days is based on reliability analyses described in References 9 and 10.

(continued)

BASES

SURVEILLANCE REQUIREMENTS (continued)

SR 3.3.6.1.3 and SR 3.3.6.1.4

CHANNEL CALIBRATION is a complete check of the instrument loop and the sensor. This test verifies the channel responds to the measured parameter within the necessary range and accuracy. CHANNEL CALIBRATION leaves the channel adjusted to account for instrument drifts between successive calibrations, consistent with the plant specific setpoint methodology.

The Frequencies are based on the assumption of a 92 day or 24 month calibration interval, as applicable, in the determination of the magnitude of equipment drift in the setpoint analysis.

SR 3.3.6.1.5

The LOGIC SYSTEM FUNCTIONAL TEST demonstrates the OPERABILITY of the required isolation logic for a specific channel. The system functional testing performed on PCIVs in LCO 3.6.1.3 overlaps this Surveillance to provide complete testing of the assumed safety function. The 24 month Frequency is based on the need to perform this Surveillance under the conditions that apply during a plant outage and the potential for an unplanned transient if the Surveillance were performed with the reactor at power. Operating experience has shown these components usually pass the Surveillance when performed at the 24 month Frequency.

SR 3.3.6.1.6

This SR ensures that the individual channel response times are less than or equal to the maximum values assumed in the accident analysis. Testing is performed only on channels where the assumed response time does not correspond to the diesel generator (DG) start time. For channels assumed to respond within the DG start time, sufficient margin exists in the 13 second start time when compared to the typical channel response time (milliseconds) so as to assure adequate response without a specific measurement test. The instrument response times must be added to the MSIV closure times to obtain the ISOLATION SYSTEM RESPONSE TIME. However, failure to meet the ISOLATION SYSTEM RESPONSE TIME

(continued)

BASES

SURVEILLANCE REQUIREMENTS

SR 3.3.6.1.6 (continued)

due to a MSIV closure time not within limits does not require the associated instrumentation to be declared inoperable; only the MSIV is required to be declared inoperable.

ISOLATION SYSTEM RESPONSE TIME acceptance criteria are included in Reference 11.

ISOLATION SYSTEM RESPONSE TIME may be verified by actual response time measurements in any series of sequential, overlapping, or total channel measurements. However, the sensors for Functions 1.a, 1.b, and 1.c are allowed to be excluded from specific ISOLATION SYSTEM RESPONSE TIME measurement if the conditions of Reference 12 are satisfied. If these conditions are satisfied, sensor response time may be allocated based on either assumed design sensor response time or the manufacturer's stated design response time. When the requirements of Reference 12 are not satisfied, sensor response time must be measured. Also, regardless of whether or not the sensor response time is measured, the response time of the remaining portion of the channel, including the trip unit and relay logic, is required to be measured.

ISOLATION SYSTEM RESPONSE TIME tests are conducted on a 24 month STAGGERED TEST BASIS. The 24 month test Frequency is consistent with the refueling cycle and is based upon plant operating experience that shows that random failures of instrumentation components causing serious response time degradation, but not channel failure, are infrequent.

REFERENCES

1. UFSAR, Table 6.2-21.

2. UFSAR, Section 6.2.1.1.

3. UFSAR, Chapter 15.

4. UFSAR, Section 15.1.3.

(continued)

BASES

REFERENCES (continued)

5. UFSAR, Section 15.6.4.

6. UFSAR, Section 15.2.5

7. UFSAR, Section 15.4.9.

8. UFSAR, Section 9.3.5.

9. NEDC-31677-P-A, "Technical Specification Improvement Analysis for BWR Isolation Actuation Instrumentation," July 1990.

10. NEDC-30851-P-A, Supplement 2, "Technical Specifications Improvement Analysis for BWR Isolation Instrumentation Common to RPS and ECCS Instrumentation," March 1989.

11. Technical Requirements Manual.

12. NEDO-32291-A, "System Analyses for the Elimination of Selected Response Time Testing Requirements," October 1995.

B 3.3 INSTRUMENTATION

B 3.3.6.2 Secondary Containment Isolation Instrumentation

BASES

BACKGROUND

The secondary containment isolation instrumentation automatically initiates closure of appropriate secondary containment isolation valves (SCIVs) and starts the Standby Gas Treatment (SGT) System. The function of these systems, in combination with other accident mitigation systems, is to limit fission product release during and following postulated Design Basis Accidents (DBAs) (Refs. 1 and 2), such that offsite radiation exposures are maintained within the requirements of 10 CFR 100 that are part of the NRC staff approved licensing basis. Secondary containment isolation and establishment of vacuum with the SGT System within the assumed time limits ensures that fission products that are released during certain operations that take place inside primary containment or during certain operations when primary containment is not required to be OPERABLE or that take place outside primary containment, are maintained within applicable limits.

The isolation instrumentation includes the sensors, relays, and switches that are necessary to cause initiation of secondary containment isolation. Most channels include electronic equipment (e.g., trip units) that compares measured input signals with pre-established setpoints. When the setpoint is exceeded, the channel output relay actuates, which then outputs a secondary containment isolation signal to the isolation logic. Functional diversity is provided by monitoring a wide range of independent parameters. The input parameters to the isolation logic are (a) reactor vessel water level, (b) drywell pressure, (c) reactor building ventilation exhaust plenum radiation, and (d) fuel pool ventilation exhaust radiation. Redundant sensor input signals from each parameter are provided for initiation of isolation parameters. In addition, manual initiation of the logic is provided.

For each secondary containment isolation instrumentation Function, the logic receives input from four channels. The output from these channels are arranged into two two-out-of-two trip systems. In addition to the isolation function, the SGT subsystems are initiated. There are two SGT

(continued)

BASES

BACKGROUND (continued)

subsystems with both subsystems being initiated by each trip system. Automatically isolated secondary containment penetrations are isolated by two isolation valves. Each trip system initiates isolation of one of two SCIVs so that operation of either trip system isolates the associated penetrations.

APPLICABLE SAFETY ANALYSES, LCO, and APPLICABILITY

The isolation signals generated by the secondary containment isolation instrumentation are implicitly assumed in the safety analyses of References 1 and 2 to initiate closure of the SCIVs and start the SGT System to limit offsite doses.

Refer to LCO 3.6.4.2, "Secondary Containment Isolation Valves (SCIVs)," and LCO 3.6.4.3, "Standby Gas Treatment (SGT) System," Applicable Safety Analyses Bases for more detail of the safety analyses.

The secondary containment isolation instrumentation satisfies Criterion 3 of 10 CFR 50.36(c)(2)(ii). Certain instrumentation Functions are retained for other reasons and are described below in the individual Functions discussion.

The OPERABILITY of the secondary containment isolation instrumentation is dependent upon the OPERABILITY of the individual instrumentation channel Functions. Each Function must have the required number of OPERABLE channels with their setpoints set within the specified Allowable Values, as shown in Table 3.3.6.2-1. The actual setpoint is calibrated consistent with applicable setpoint methodology assumptions.

Allowable Values are specified for each Function specified in the Table. Nominal trip setpoints are specified in setpoint calculations. The nominal setpoints are selected to ensure that the setpoints do not exceed the Allowable Values between CHANNEL CALIBRATIONS. Operation with a trip setpoint less conservative than the nominal trip setpoint, but within its Allowable Value, is acceptable. A channel is inoperable if its actual trip setpoint is not within its required Allowable Value.

Trip setpoints are those predetermined values of output at which an action should take place. The setpoints are compared to the actual process parameter (e.g., reactor

(continued)

BASES

APPLICABLE SAFETY ANALYSES, LCO, and APPLICABILITY (continued)

vessel water level), and when the measured output value of the process parameter exceeds the setpoint, the associated device (e.g., trip unit) changes state. The analytic limits are derived from the limiting values of the process parameters obtained from the safety analysis. The trip setpoints are determined from the analytic limits, corrected for defined process, calibration, and instrument errors. The Allowable Values are then determined, based on the trip setpoint values, by accounting for the calibration based errors. These calibration based errors are limited to reference accuracy, instrument drift, errors associated with measurement and test equipment, and calibration tolerance of loop components. The trip setpoints and Allowable Values determined in this manner provide adequate protection because instrument uncertainties, process effects, calibration tolerances, instrument drift, and severe environment errors (for channels that must function in harsh environments as defined by 10 CFR 50.49) are accounted for and appropriately applied for the instrumentation.

In general, the individual Functions are required to be OPERABLE in the MODES or other specified conditions when SCIVs and the SGT System are required.

The specific Applicable Safety Analyses, LCO, and Applicability discussions are listed below on a Function by Function basis.

1. Reactor Vessel Water Level – Low Low, Level 2

Low reactor pressure vessel (RPV) water level indicates that the capability to cool the fuel may be threatened. Should RPV water level decrease too far, fuel damage could result. An isolation of the secondary containment and actuation of the SGT System are initiated in order to minimize the potential of an offsite dose release. The Reactor Vessel Water Level – Low Low, Level 2 Function is one of the Functions assumed to be OPERABLE and capable of providing isolation and initiation signals. The isolation and initiation of systems on Reactor Vessel Water Level – Low Low, Level 2 support actions to ensure that any offsite releases are within the limits calculated in the safety analysis (Ref. 1).

(continued)

BASES

APPLICABLE SAFETY ANALYSES, LCO, and APPLICABILITY

1. Reactor Vessel Water Level – Low Low, Level 2 (continued)

Reactor Vessel Water Level – Low Low, Level 2 signals are initiated from differential pressure transmitters that sense the difference between the pressure due to a constant column of water (reference leg) and the pressure due to the actual water level (variable leg) in the vessel. Four channels of Reactor Vessel Water Level – Low Low, Level 2 Function are available and are required to be OPERABLE to ensure that no single instrument failure can preclude the isolation function.

The Reactor Vessel Water Level – Low Low, Level 2 Allowable Value was chosen to be the same as the High Pressure Core Spray (HPCS)/Reactor Core Isolation Cooling (RCIC) Reactor Vessel Water Level – Low Low, Level 2 Allowable Value (LCO 3.3.5.1, "Emergency Core Cooling System (ECCS) Instrumentation," and LCO 3.3.5.2, "Reactor Core Isolation Cooling (RCIC) System Instrumentation"), since this could indicate the capability to cool the fuel is being threatened.

The Reactor Vessel Water Level – Low Low, Level 2 Function is required to be OPERABLE in MODES 1, 2, and 3 where considerable energy exists in the Reactor Coolant System (RCS); thus, there is a probability of pipe breaks resulting in significant releases of radioactive steam and gas. In MODES 4 and 5, the probability and consequences of these events are low due to the RCS pressure and temperature limitations of these MODES; thus, this Function is not required. In addition, the Function is also required to be OPERABLE during operations with a potential for draining the reactor vessel (OPDRVs) to ensure that offsite dose limits are not exceeded if core damage occurs.

2. Drywell Pressure – High

High drywell pressure can indicate a break in the reactor coolant pressure boundary (RCPB). An isolation of the secondary containment and actuation of the SGT System are initiated in order to minimize the potential of an offsite dose release. The isolation and initiation of systems on Drywell Pressure – High supports actions to ensure that any offsite releases are within the limits calculated in the

(continued)

BASES

APPLICABLE SAFETY ANALYSES, LCO, and APPLICABILITY

2. Drywell Pressure – High (continued)

safety analysis. However, the Drywell Pressure – High Function associated with isolation is not assumed in any UFSAR accident or transient analysis. It is retained for the overall redundancy and diversity of the secondary containment isolation instrumentation as required by the NRC approved licensing basis.

High drywell pressure signals are initiated from pressure switches that sense the pressure in the drywell. Four channels of Drywell Pressure – High Function are available and are required to be OPERABLE to ensure that no single instrument failure can preclude the isolation function.

The Allowable Value was chosen to be the same as the RPS Drywell Pressure – High Function Allowable Value (LCO 3.3.1.1) since this is indicative of a loss of coolant accident.

The Drywell Pressure – High Function is required to be OPERABLE in MODES 1, 2, and 3 where considerable energy exists in the RCS; thus, there is a probability of pipe breaks resulting in significant releases of radioactive steam and gas. This Function is not required in MODES 4 and 5 because the probability and consequences of these events are low due to the RCS pressure and temperature limitations of these MODES.

3, 4. Reactor Building Ventilation Exhaust Plenum and Fuel Pool Ventilation Exhaust Radiation – High

High secondary containment exhaust radiation is an indication of possible gross failure of the fuel cladding. The release may have originated from the primary containment due to a break in the RCPB or the refueling floor due to a fuel handling accident. When Exhaust Radiation – High is detected, secondary containment isolation and actuation of the SGT System are initiated to limit the release of fission products as assumed in the UFSAR safety analyses (Refs. 1 and 2).

(continued)

BASES

APPLICABLE SAFETY ANALYSES, LCO, and APPLICABILITY

3, 4. Reactor Building Ventilation Exhaust Plenum and Fuel Pool Ventilation Exhaust Radiation – High (continued)

Reactor Building Ventilation Exhaust Plenum Radiation – High signals are initiated from radiation detectors that are located in the reactor building return air riser above the upper area of the steam tunnel prior to the reactor building ventilation isolation dampers. Fuel Pool Ventilation Exhaust Radiation – High signals are initiated from radiation detectors that are located in the reactor building exhaust ducting coming from the refuel floor. The signal from each detector is input to an individual monitor whose trip outputs are assigned to an isolation channel. Four channels of Reactor Building Ventilation Exhaust Plenum Radiation – High Function and four channels of Fuel Pool Ventilation Exhaust Radiation – High Function are available and are required to be OPERABLE to ensure that no single instrument failure can preclude the isolation function.

The Allowable Values are chosen to promptly detect gross failure of the fuel cladding.

The Reactor Building Ventilation Exhaust Plenum and Fuel Pool Ventilation Exhaust Radiation – High Functions are required to be OPERABLE in MODES 1, 2, and 3 where considerable energy exists; thus, there is a probability of pipe breaks resulting in significant releases of radioactive steam and gas. In MODES 4 and 5, the probability and consequences of these events are low due to the RCS pressure and temperature limitations of these MODES; thus, these Functions are not required. In addition, the Functions are required to be OPERABLE during CORE ALTERATIONS, OPDRVs, and movement of irradiated fuel assemblies in the secondary containment because the capability of detecting radiation releases due to fuel failures (due to fuel uncovery or dropped fuel assemblies) must be provided to ensure that offsite dose limits are not exceeded.

5. Manual Initiation

The Manual Initiation push button channels introduce signals into the secondary containment isolation logic that are redundant to the automatic protective instrumentation channels, and provide manual isolation capability. There is

(continued)

BASES

APPLICABLE SAFETY ANALYSES, LCO, and APPLICABILITY

5. Manual Initiation (continued)

no specific UFSAR safety analysis that takes credit for this Function. It is retained for the overall redundancy and diversity of the secondary containment isolation instrumentation as required by the NRC approved licensing basis.

There is one manual initiation push button for the logic per trip system. Two channels of the Manual Initiation Function are available and are required to be OPERABLE in MODES 1, 2, and 3 and during CORE ALTERATIONS, OPDRVs, and movement of irradiated fuel assemblies in the secondary containment, since these are the MODES and other specified conditions in which the Secondary Containment Isolation automatic Functions are required to be OPERABLE. There is no Allowable Value for this Function since the channels are mechanically actuated based solely on the position of the push buttons.

ACTIONS

A Note has been provided to modify the ACTIONS related to secondary containment isolation instrumentation channels. Section 1.3, Completion Times, specifies that once a Condition has been entered, subsequent divisions, subsystems, components, or variables expressed in the Condition discovered to be inoperable or not within limits will not result in separate entry into the Condition. Section 1.3 also specifies that Required Actions of the Condition continue to apply for each additional failure, with Completion Times based on initial entry into the Condition. However, the Required Actions for inoperable secondary containment isolation instrumentation channels provide appropriate compensatory measures for separate inoperable channels. As such, a Note has been provided that allows separate Condition entry for each inoperable secondary containment isolation instrumentation channel.

A.1

Because of the diversity of sensors available to provide isolation signals and the redundancy of the isolation design, an allowable out of service time of 12 hours or 24 hours, depending on the Function (12 hours for those

(continued)

BASES

ACTIONS

A.1 (continued)

Functions that have channel components common to RPS instrumentation and 24 hours for those Functions that do not have channel components common to RPS instrumentation), has been shown to be acceptable (Refs. 3 and 4) to permit restoration of any inoperable channel to OPERABLE status. This out of service time is only acceptable provided the associated Function is still maintaining isolation capability (refer to Required Action B.1 Bases). If the inoperable channel cannot be restored to OPERABLE status within the allowable out of service time, the channel must be placed in the tripped condition per Required Action A.1. Placing the inoperable channel in trip would conservatively compensate for the inoperability, restore capability to accommodate a single failure, and allow operation to continue. Alternately, if it is not desired to place the channel in trip (e.g., as in the case where placing the inoperable channel in trip would result in an isolation), Condition C must be entered and its Required Actions taken.

B.1

Required Action B.1 is intended to ensure that appropriate actions are taken if multiple, inoperable, untripped channels within the same Function result in a complete loss of automatic isolation capability for the associated penetration flow path(s) or a complete loss of automatic initiation capability for the SGT System. A Function is considered to be maintaining isolation capability when sufficient channels are OPERABLE or in trip, such that one trip system will generate a trip signal from the given Function on a valid signal. This ensures that one of the two SCIVs in the associated penetration flow path and the SGT subsystems can be initiated on an isolation signal from the given Function. For the Functions with two two-out-of-two logic trip systems (Functions 1, 2, 3, and 4), this would require one trip system to have two channels, each OPERABLE or in trip. The Condition does not include the Manual Initiation Function (Function 5), since it is not assumed in any accident or transient analysis. Thus, a total loss of manual initiation capability for 24 hours (as allowed by Required Action A.1) is allowed.

(continued)

BASES

ACTIONS

B.1 (continued)

The Completion Time is intended to allow the operator time to evaluate and repair any discovered inoperabilities. The 1 hour Completion Time is acceptable because it minimizes risk while allowing time for restoration or tripping of channels.

C.1.1, C.1.2, C.2.1, and C.2.2

If any Required Action and associated Completion Time are not met, the ability to isolate the secondary containment and start the SGT System cannot be ensured. Therefore, further actions must be performed to ensure the ability to maintain the secondary containment function. Isolating the associated penetration flow path(s) and starting the associated SGT subsystem(s) (Required Actions C.1.1 and C.2.1) performs the intended function of the instrumentation and allows operations to continue. The method used to place the SGT subsystem(s) in operation must provide for automatically reinitiating the subsystem(s) upon restoration of power following a loss of power to the SGT subsystem(s).

Alternatively, declaring the associated SCIV(s) or SGT subsystem(s) inoperable (Required Actions C.1.2 and C.2.2) is also acceptable since the Required Actions of the respective LCOs (LCO 3.6.4.2 and LCO 3.6.4.3) provide appropriate actions for the inoperable components.

One hour is sufficient for plant operations personnel to establish required plant conditions or to declare the associated components inoperable without challenging plant systems.

SURVEILLANCE REQUIREMENTS

As noted at the beginning of the SRs, the SRs for each Secondary Containment Isolation instrumentation Function are located in the SRs column of Table 3.3.6.2-1.

The Surveillances are also modified by a Note to indicate that when a channel is placed in an inoperable status solely for performance of required Surveillances, entry into associated Conditions and Required Actions may be delayed

(continued)

BASES

SURVEILLANCE REQUIREMENTS (continued)

for up to 6 hours, provided the associated Function maintains isolation capability. Upon completion of the Surveillance, or expiration of the 6 hour allowance, the channel must be returned to OPERABLE status or the applicable Condition entered and Required Action(s) taken.

This Note is based on the reliability analysis (Refs. 3 and 4) assumption of the average time required to perform channel surveillance. That analysis demonstrated that the 6 hour testing allowance does not significantly reduce the probability that the SCIVs will isolate the associated penetration flow paths and the SGT System will initiate when necessary.

SR 3.3.6.2.1

Performance of the CHANNEL CHECK once every 12 hours ensures that a gross failure of instrumentation has not occurred. A CHANNEL CHECK is normally a comparison of the indicated parameter for one instrument channel to a similar parameter on other channels. It is based on the assumption that instrument channels monitoring the same parameter should read approximately the same value. Significant deviations between the instrument channels could be an indication of excessive instrument drift in one of the channels or something even more serious. A CHANNEL CHECK will detect gross channel failure; thus, it is key to verifying the instrumentation continues to operate properly between each CHANNEL CALIBRATION.

Agreement criteria are determined by the plant staff, based on a combination of the channel instrument uncertainties, including indication and readability. If a channel is outside the criteria, it may be an indication that the instrument has drifted outside its limit.

The Frequency is based on operating experience that demonstrates channel failure is rare. The CHANNEL CHECK supplements less formal, but more frequent, checks of channels during normal operational use of the displays associated with the channels required by the LCO.

(continued)

BASES

SURVEILLANCE REQUIREMENTS (continued)

SR 3.3.6.2.2

A CHANNEL FUNCTIONAL TEST is performed on each required channel to ensure that the channel will perform the intended function. A successful test of the required contact(s) of a channel relay may be performed by the verification of the change of state of a single contact of the relay. This clarifies what is an acceptable CHANNEL FUNCTIONAL TEST of a relay. This is acceptable because all of the other required contacts of the relay are verified by other Technical Specifications and non-Technical Specifications tests at least once per refueling interval with applicable extensions. Any setpoint adjustment shall be consistent with the assumptions of the current plant specific setpoint methodology.

The Frequency of 92 days is based upon the reliability analysis of References 3 and 4.

SR 3.3.6.2.3

CHANNEL CALIBRATION is a complete check of the instrument loop and the sensor. This test verifies the channel responds to the measured parameter within the necessary range and accuracy. CHANNEL CALIBRATION leaves the channel adjusted to account for instrument drifts between successive calibrations consistent with the plant specific setpoint methodology.

The Frequency is based upon the assumption of a 24 month calibration interval in the determination of the magnitude of equipment drift in the setpoint analysis.

SR 3.3.6.2.4

The LOGIC SYSTEM FUNCTIONAL TEST demonstrates the OPERABILITY of the required isolation logic for a specific channel. The system functional testing, performed on SCIVs and the SGT System in LCO 3.6.4.2 and LCO 3.6.4.3, respectively, overlaps this Surveillance to provide complete testing of the assumed safety function.

(continued)

BASES

SURVEILLANCE REQUIREMENTS

SR 3.3.6.2.4 (continued)

The 24 month Frequency is based on the need to perform this Surveillance under the conditions that apply during a plant outage and the potential for an unplanned transient if the Surveillance were performed with the reactor at power. Operating experience has shown these components usually pass the Surveillance when performed at the 24 month Frequency.

REFERENCES

1. UFSAR, Section 15.6.5.

2. UFSAR, Section 15.7.4.

3. NEDC-31677-P-A, "Technical Specification Improvement Analysis for BWR Isolation Actuation Instrumentation," July 1990.

4. NEDC-30851-P-A Supplement 2, "Technical Specifications Improvement Analysis for BWR Isolation Instrumentations Common to RPS and ECCS Instrumentation," March 1989.

B 3.3 INSTRUMENTATION

B 3.3.7.1 Control Room Area Filtration (CRAF) System Instrumentation

BASES

BACKGROUND

The CRAF System is designed to provide a radiologically controlled environment to ensure the habitability of the control room for the safety of control room operators under all plant conditions. Two independent CRAF subsystems are each capable of fulfilling the stated safety function. The instrumentation and controls for the CRAF System automatically initiate action to isolate and pressurize the control room area to minimize the consequences of radioactive material in the control room area environment.

In the event of a Control Room Air Intake Radiation – High signal, the CRAF System is automatically placed in the pressurization mode. In this mode the normal outside air supply to the system is closed and is diverted to the emergency makeup filter train where it passes through a charcoal filter and is delivered to the suction of the control room return air fan and the suction of the auxiliary electric equipment room supply fan. Recirculated control room air is combined with the emergency makeup filter train air and delivered to the control room area via the supply fan. The addition of outside air through the emergency filter train will keep the control room area slightly pressurized with respect to surrounding areas. A description of the CRAF System is provided in the Bases for LCO 3.7.4, "Control Room Area Filtration (CRAF) System."

The CRAF System (Ref. 1) instrumentation has 4 trip systems, two for each of the air intakes: two trip systems initiate one CRAF subsystem, while the other trip systems initiate the other CRAF subsystem. For each CRAF subsystem, the associated two trip systems are arranged in a one-out-of-two logic (i.e., either trip system can actuate the CRAF subsystem). Each trip system receives input from two Control Room Air Intake Radiation – High channels. The Control Room Air Intake Radiation – High channels are arranged in a two-out-of-two logic for each trip system. The channels include electronic equipment (e.g., trip units)

(continued)

BASES

BACKGROUND (continued)

that compares measured input signals with pre-established setpoints. When the setpoint is exceeded, the channel output relay actuates, which then outputs a CRAF System initiation signal to the initiation logic.

APPLICABLE SAFETY ANALYSES

The ability of the CRAF System to maintain the habitability of the control room area is explicitly assumed for certain accidents as discussed in the UFSAR safety analyses (Refs. 2 and 3). CRAF System operation ensures that the radiation exposure of control room personnel, through the duration of any one of the postulated accidents, does not exceed the limits set by GDC 19 of 10 CFR 50, Appendix A.

CRAF System instrumentation satisfies Criterion 3 of 10 CFR 50.36(c)(2)(ii).

LCO

High radiation at the intake ducts of the control room outside air intakes is an indication of possible gross failure of the fuel cladding. The release may have originated from the primary containment due to a break in the RCPB or the refueling floor due to a fuel handling accident. When control room air intake high radiation is detected, the associated CRAF subsystem is automatically initiated in the pressurization mode since this radiation release could result in radiation exposure to control room personnel.

The Control Room Air Intake Radiation—High Function consists of eight independent monitors, with four monitors associated with one CRAF subsystem and the other four monitors associated with the other CRAF subsystem. Each of the four monitors associated with a CRAF subsystem are arranged in two trip systems, with each trip system containing two radiation monitors. Eight channels of the Control Room Air Intake Radiation—High Function are available and required to be OPERABLE to ensure no single instrument failure can preclude CRAF System initiation. The Allowable Value was selected to ensure protection of the control room personnel.

(continued)

BASES

LCO (continued)

Each channel must have its setpoint set within the specified Allowable Value of SR 3.3.7.1.3. The actual setpoint is calibrated consistent with applicable setpoint methodology assumptions. Nominal trip setpoints are specified in the setpoint calculations. These nominal setpoints are selected to ensure that the setpoints do not exceed the Allowable Value between successive CHANNEL CALIBRATIONS. Operation with a trip setpoint that is less conservative than the nominal trip setpoint, but within its Allowable Value, is acceptable. A channel is inoperable if its actual trip setpoint is not within its required Allowable Value.

Trip setpoints are those predetermined values of output at which an action should take place. The setpoints are compared to the actual process parameter (e.g., control room air intake radiation), and when the measured output value of the process parameter exceeds the setpoint, the associated device (e.g., trip unit) changes state. The analytic limits are derived from the limiting values of the process parameters obtained from the safety analysis. The trip setpoints are determined from the analytic limits, corrected for defined process, calibration, and instrument errors. The Allowable Values are then determined, based on the trip setpoint values, by accounting for the calibration based errors. These calibration based errors are limited to reference accuracy, instrument drift, errors associated with measurement and test equipment, and calibration tolerance of loop components. The trip setpoints and Allowable Values determined in this manner provide adequate protection because instrument uncertainties, process effects, calibration tolerances, instrument drift, and severe environment errors (for channels that must function in harsh environments as defined by 10 CFR 50.49) are accounted for and appropriately applied for the instrumentation.

APPLICABILITY

The Control Room Air Intake Radiation – High Function is required to be OPERABLE in MODES 1, 2, and 3, and during CORE ALTERATIONS, OPDRVs, and movement of irradiated fuel in the secondary containment to ensure that control room personnel are protected during a LOCA, fuel handling event, or a vessel draindown event. During MODES 4 and 5, when these specified conditions are not in progress (e.g., CORE ALTERATIONS), the probability of a LOCA or fuel damage is low; thus, the Function is not required.

(continued)

BASES (continued)

ACTIONS

A Note has been provided to modify the ACTIONS related to CRAF System instrumentation channels. Section 1.3, Completion Times, specifies that once a Condition has been entered, subsequent divisions, subsystems, components, or variables expressed in the Condition discovered to be inoperable or not within limits will not result in separate entry into the Condition. Section 1.3 also specifies that Required Actions of the Condition continue to apply for each additional failure, with Completion Times based on initial entry into the Condition. However, the Required Actions for inoperable CRAF System instrumentation channels provide appropriate compensatory measures for separate inoperable channels. As such, a Note has been provided that allows separate Condition entry for each inoperable CRAF System instrumentation channel.

A.1 and A.2

Because of the redundancy of sensors available to provide initiation signals and the redundancy of the CRAF System design, an allowable out of service time of 6 hours is provided to permit restoration of any inoperable channel to OPERABLE status. However, this out of service time is only acceptable provided the Function is still maintaining CRAF subsystem initiation capability. A Function is considered to be maintaining CRAF subsystem initiation capability when sufficient channels are OPERABLE or in trip, such that at least one trip system will generate an initiation signal on a valid signal. This would require one trip system to have two channels, each OPERABLE or in trip. In this situation (loss of CRAF subsystem initiation capability), the 6 hour allowance of Required Action A.2 is not appropriate. If the Function is not maintaining CRAF subsystem initiation capability, the CRAF subsystem must be declared inoperable within 1 hour of discovery of loss of CRAF subsystem initiation capability.

This Completion Time also allows for an exception to the normal "time zero" for beginning the allowed outage time "clock." For Required Action A.1, the Completion Time only begins upon discovery that the CRAF subsystem cannot be automatically initiated due to inoperable, untripped Control

(continued)

BASES

ACTIONS

A.1 and A.2 (continued)

Room Air Intake Radiation—High channels in both trip systems in any air intake. The 1 hour Completion Time is acceptable because it minimizes risk while allowing time for restoring or tripping of channels. If it is not desired to declare the CRAF subsystem inoperable, Condition B may be entered and Required Action B.1 taken.

If the inoperable channel cannot be restored to OPERABLE status within the allowable out of service time, the channel must be placed in the tripped condition, per Required Action A.2. Placing the inoperable channel in trip performs the intended function of the channel. Alternately, if it is the second channel and it is not desired to place the channel in trip (e.g., as in the case where it is not desired to start the subsystem), Condition B must be entered and its Required Actions taken.

The 6 hour Completion Time is based on the consideration that this Function provides the primary signal to start the CRAF subsystem, thus ensuring that the design basis of the CRAF subsystem is met.

B.1 and B.2

With any Required Action and associated Completion Time not met, the associated CRAF subsystem must be placed in the pressurization mode of operation (Required Action B.1) to ensure that control room personnel will be protected in the event of a Design Basis Accident. The method used to place the CRAF subsystem in operation must provide for automatically reinitiating the subsystem upon restoration of power following a loss of power to the CRAF subsystem(s). Alternately, if it is not desired to start the subsystem, the CRAF subsystem associated with inoperable, untripped channels must be declared inoperable within 1 hour.

The 1 hour Completion Time is intended to allow the operator time to place the CRAF subsystem in operation. The 1 hour Completion Time is acceptable because it minimizes risk while allowing time for restoration or tripping of channels, or for placing the associated CRAF subsystem in operation.

(continued)

BASES (continued)

SURVEILLANCE REQUIREMENTS

The Surveillances are modified by a Note to indicate that when a channel is placed in an inoperable status solely for performance of required Surveillances, entry into associated Conditions and Required Actions may be delayed for up to 6 hours, provided the associated Function maintains CRAF subsystem initiation capability. Upon completion of the surveillance, or expiration of the 6 hour allowance, the channel must be returned to OPERABLE status or the applicable Condition entered and Required Actions taken. This Note is based on the reliability analysis (Refs. 4 and 5) assumption of the average time required to perform channel surveillance. That analysis demonstrated that the 6 hour testing allowance does not significantly reduce the probability that the CRAF System will initiate when necessary.

SR 3.3.7.1.1

Performance of the CHANNEL CHECK once every 12 hours ensures that a gross failure of instrumentation has not occurred. A CHANNEL CHECK is normally a comparison of the indicated parameter for one instrument channel to a similar parameter on other channels. It is based on the assumption that instrument channels monitoring the same parameter should read approximately the same value. Significant deviations between the instrument channels could be an indication of excessive instrument drift in one of the channels or something even more serious. A CHANNEL CHECK will detect gross channel failure; thus, it is key to verifying the instrumentation continues to operate properly between each CHANNEL CALIBRATION.

Agreement criteria are determined by the plant staff based on a combination of the channel instrument uncertainties, including indication and readability. If a channel is outside the criteria, it may be an indication that the instrument has drifted outside its limit.

The Frequency is based upon operating experience that demonstrates channel failure is rare. The CHANNEL CHECK supplements less formal, but more frequent, checks of channel status during normal operational use of the displays associated with channels required by the LCO.

(continued)

BASES

SURVEILLANCE REQUIREMENTS (continued)

SR 3.3.7.1.2

A CHANNEL FUNCTIONAL TEST is performed on each required channel to ensure that the channel will perform the intended function. A successful test of the required contact(s) of a channel relay may be performed by the verification of the change of state of a single contact of the relay. This clarifies what is an acceptable CHANNEL FUNCTIONAL TEST of a relay. This is acceptable because all of the other required contacts of the relay are verified by other Technical Specifications and non-Technical Specifications tests at least once per refueling interval with applicable extensions. Any setpoint adjustment shall be consistent with the assumptions of the current plant specific setpoint methodology.

The Frequency of 92 days is based on the reliability analyses of References 4 and 5.

SR 3.3.7.1.3

A CHANNEL CALIBRATION is a complete check of the instrument loop and the sensor. This test verifies the channel responds to the measured parameter within the necessary range and accuracy. CHANNEL CALIBRATION leaves the channel adjusted to account for instrument drifts between successive calibrations consistent with the plant specific setpoint methodology.

The Frequency is based on the assumption of a 24 month calibration interval in the determination of the magnitude of equipment drift in the setpoint analysis.

SR 3.3.7.1.4

The LOGIC SYSTEM FUNCTIONAL TEST demonstrates the OPERABILITY of the required initiation logic for a specific channel. The system functional testing performed in LCO 3.7.4, "Control Room Area Filtration (CRAF) System," overlaps this Surveillance to provide complete testing of the assumed safety function.

(continued)

BASES

SURVEILLANCE REQUIREMENTS

SR 3.3.7.1.4 (continued)

While the Surveillance can be performed with the reactor at power, operating experience has shown these components usually pass the Surveillance when performed at the 24 month Frequency, which is based on the refueling cycle. Therefore, the Frequency was concluded to be acceptable from a reliability standpoint.

REFERENCES

1. UFSAR, Sections 7.3.4 and 9.4.1.

2. UFSAR, Section 6.4.

3. UFSAR, Chapter 15.

4. GENE-770-06-1A, "Bases for Changes to Surveillance Test Intervals and Allowed Out-of-Service Times for Selected Instrumentation Technical Specifications," December 1992.

5. NEDC-31677P-A, "Technical Specification Improvement Analysis for BWR Isolation Actuation Instrumentation," July 1990.

B 3.3 INSTRUMENTATION

B 3.3.8.1 Loss of Power (LOP) Instrumentation

BASES

BACKGROUND

Successful operation of the required safety functions of the Emergency Core Cooling Systems (ECCS) is dependent upon the availability of adequate power sources for energizing the various components such as pump motors, motor operated valves, and the associated control components. The LOP instrumentation monitors the 4.16 kV emergency buses. Offsite power is the preferred source of power for the 4.16 kV emergency buses. If the monitors determine that insufficient voltage is available, the buses are disconnected from the offsite power sources and connected to the onsite diesel generator (DG) power sources.

Each 4.16 kV emergency bus has its own independent LOP instrumentation and associated trip logic. The voltage for the Division 1, 2, and 3 buses is monitored at two levels, which can be considered as two different undervoltage functions: loss of voltage and degraded voltage.

For Division 1 and 2, each loss of voltage and degraded voltage function is monitored by two instruments per bus whose output trip contacts are arranged in a two-out-of-two logic configuration per bus (Ref. 1). The loss of voltage signal is generated when a loss of voltage occurs for a specific time interval. Lower voltage conditions will result in decreased trip times for the inverse time undervoltage relays. The degraded voltage signal is generated when a degraded voltage occurs for a specified time interval; the time interval is dependent upon whether a loss of coolant accident signal is present. The relays utilized are inverse time delay voltage relays or instantaneous voltage relays with a time delay.

For Division 3, the degraded voltage function logic is the same as for Divisions 1 and 2, but the Division 3 loss of voltage function logic is different. The Division 3 DG will auto-start if either one of the two bus undervoltage relays (with a time delay) actuates and the DG output breaker will automatically close with the same undervoltage permissive provided that the Division 3 bus main feeder breaker is open and the DG speed and voltage permissives are met. The Division 3 bus main feed breaker trip logic includes two

(continued)

BASES

BACKGROUND (continued)

trip systems. Each trip system consists of an undervoltage relay on the 4.16 kV bus (with a time delay) and an undervoltage relay on the system auxiliary transformer (SAT) side of the main feed breaker to the 4.16 kV bus (with no time delay) arranged in a two-out-of-two logic. The trip setting of the SAT undervoltage relay is maintained such that it trips prior to the bus undervoltage relay. Either trip system will open (trip) the main feed breaker to the bus.

A loss of voltage signal or degraded voltage signal results in the start of the associated DG, the trip of the normal and alternate offsite power supply breakers to the associated 4.16 kV emergency bus, and (for Divisions 1 and 2 only) the shedding of the appropriate 4.16 kV bus loads.

APPLICABLE SAFETY ANALYSES, LCO, and APPLICABILITY

The LOP instrumentation is required for the Engineered Safety Features to function in any accident with a loss of offsite power. The required channels of LOP instrumentation ensure that the ECCS and other assumed systems powered from the DGs provide plant protection in the event of any of the analyzed accidents in References 2, 3, and 4 in which a loss of offsite power is assumed. The initiation of the DGs on loss of offsite power, and subsequent initiation of the ECCS, ensure that the fuel peak cladding temperature remains below the limits of 10 CFR 50.46.

Accident analyses credit the loading of at least two of the DGs based on the loss of offsite power coincident with a loss of coolant accident (LOCA). The diesel starting and loading times have been included in the delay time associated with each safety system component requiring DG supplied power following a loss of offsite power.

The LOP instrumentation satisfies Criterion 3 of 10 CFR 50.36(c)(2)(ii).

The OPERABILITY of the LOP instrumentation is dependent upon the OPERABILITY of the individual instrumentation channel Functions specified in Table 3.3.8.1-1. Each Function must have a required number of OPERABLE channels per 4.16 kV emergency bus, with their setpoints within the specified Allowable Values. The actual setpoint is calibrated consistent with applicable setpoint methodology assumptions.

(continued)

BASES

APPLICABLE SAFETY ANALYSES, LCO, and APPLICABILITY (continued)

The Allowable Values are specified for each Function in the Table. Nominal trip setpoints are specified in the setpoint calculations. The nominal setpoints are selected to ensure that the setpoint does not exceed the Allowable Value between CHANNEL CALIBRATIONS. Operation with a trip setpoint less conservative than the nominal trip setpoint, but within the Allowable Value, is acceptable. A channel is inoperable if its actual trip setpoint is not within its required Allowable Value. Trip setpoints are those predetermined values of output at which an action should take place. The setpoints are compared to the actual process parameter (e.g., degraded voltage), and when the measured output value of the process parameter exceeds the setpoint, the associated device (e.g., trip unit) changes state. The analytic limits are derived from the limiting values of the process parameters obtained from the safety analysis. The trip setpoints are determined from the analytic limits, corrected for defined process, calibration, and instrument errors. The Allowable Values are then determined, based on the trip setpoint values, by accounting for the calibration based errors. These calibration based errors are limited to reference accuracy, instrument drift, errors associated with measurement and test equipment, and calibration tolerance of loop components. The trip setpoints and Allowable Values determined in this manner provide adequate protection because instrument uncertainties, process effects, calibration tolerances, instrument drift, and severe environment errors (for channels that must function in harsh environments as defined by 10 CFR 50.49) are accounted for and appropriately applied for the instrumentation.

The specific Applicable Safety Analyses, LCO, and Applicability discussions are listed below on a Function by Function basis.

4.16 kV Emergency Bus Undervoltage

1.a, 1.b, 2.a, 2.b. 4.16 kV Emergency Bus Undervoltage (Loss of Voltage)

Loss of voltage on a 4.16 kV emergency bus indicates that offsite power may be completely lost to the respective emergency bus and is unable to supply sufficient power for proper operation of the applicable equipment. Therefore,

(continued)

BASES

APPLICABLE SAFETY ANALYSES, LCO, and APPLICABILITY

4.16 kV Emergency Bus Undervoltage

1.a, 1.b, 2.a, 2.b. 4.16 kV Emergency Bus Undervoltage (Loss of Voltage) (continued)

the power supply to the bus is transferred from the offsite power supply to DG power. This transfer is initiated when the voltage on the bus drops below the relay settings with a short time delay. The transfer occurs prior to the bus voltage dropping below the minimum Loss of Voltage Function Allowable Value but after the voltage drops below the maximum Loss of Voltage Function Allowable Value (loss of voltage with a short time delay). The short time delay prevents inadvertent relay actuations due to momentary voltage dips. For Divisions 1 and 2, the time delay varies inversely with decreasing voltage. For Division 3, the time delay is a fixed value. The time delay values are bounded by the upper and lower Allowable Values, as applicable. This ensures that adequate power will be available to the required equipment.

The Bus Undervoltage Allowable Values are low enough to prevent inadvertent power supply transfer since they are below the minimum expected voltage during normal and emergency operation, but high enough to ensure power is available to the required equipment. The Time Delay Allowable Values are long enough to provide time for the offsite power supply to recover to normal voltages, but short enough to ensure that power is available to the required equipment.

Two channels of each 4.16 kV Emergency Bus Undervoltage (Loss of Voltage) Function per associated emergency bus are required to be OPERABLE when the associated DG is required to be OPERABLE to ensure that no single instrument failure can preclude the DG function. For the Division 1 and 2 4.16 kV emergency buses, the Loss of Voltage Functions are 1) 4.16 kV Basis and 2) Time Delay. For the Division 3 4.16 kV emergency bus, the Loss of Voltage Functions are: 1) 4.16 kV Basis and 2) Time Delay. Refer to LCO 3.8.1, "AC Sources – Operating," and LCO 3.8.2, "AC Sources – Shutdown," for Applicability Bases for the DGs.

(continued)

BASES

APPLICABLE SAFETY ANALYSES, LCO, and APPLICABILITY (continued)

1.c, 1.d, 1.e, 2.c, 2.d, 2.e. 4.16 kV Emergency Bus Undervoltage (Degraded Voltage)

A reduced voltage condition on a 4.16 kV emergency bus indicates that while offsite power may not be completely lost to the respective emergency bus, power may be insufficient for starting large motors without risking damage to the motors that could disable the ECCS function. Therefore, power supply to the bus is transferred from offsite power to onsite DG power when the voltage on the bus drops below the Degraded Voltage Function Allowable Values (degraded voltage with a time delay). This ensures that adequate power will be available to the required equipment.

The Bus Undervoltage Allowable Values are low enough to prevent inadvertent power supply transfer, but high enough to ensure that sufficient power is available to the required equipment. The Time Delay Allowable Values are long enough to provide time for the offsite power supply to recover to normal voltages, but short enough to ensure that sufficient power is available to the required equipment.

Two channels of each 4.16 kV Emergency Bus Undervoltage (Degraded Voltage) Function per associated emergency bus are required to be OPERABLE when the associated DG is required to be OPERABLE to ensure that no single instrument failure can preclude the DG function. The Degraded Voltage Functions are: 1) 4.16 kV Basis; 2) Time Delay, No LOCA; and 3) Time Delay, LOCA. Refer to LCO 3.8.1 and LCO 3.8.2 for Applicability Bases for the DGs.

ACTIONS

A Note has been provided to modify the ACTIONS related to LOP instrumentation channels. Section 1.3, Completion Times, specifies that once a Condition has been entered, subsequent divisions, subsystems, components, or variables expressed in the Condition discovered to be inoperable or not within limits will not result in separate entry into the Condition. Section 1.3 also specifies that Required Actions of the Condition continue to apply for each additional failure, with Completion Times based on initial entry into the Condition. However, the Required Actions for inoperable LOP instrumentation channels provide appropriate

(continued)

BASES

ACTIONS (continued)

compensatory measures for separate inoperable channels. As such, a Note has been provided that allows separate Condition entry for each inoperable LOP instrumentation channel.

A.1

With one or more channels of a Function inoperable, the Function may not be capable of performing the intended function. Therefore, only 1 hour is allowed to restore the inoperable channel to OPERABLE status. If the inoperable channel cannot be restored to OPERABLE status within the allowable out of service time, the channel must be placed in the tripped condition per Required Action A.1. Placing the inoperable channel in trip would conservatively compensate for the inoperability, restore capability to accommodate a single failure, and allow operation to continue. Alternately, if it is not desired to place the channel in trip (e.g., as in the case where placing the channel in trip would result in a DG initiation), Condition B must be entered and its Required Action taken.

The Completion Time is intended to allow the operator time to evaluate and repair any discovered inoperabilities. The 1 hour Completion Time is acceptable because it minimizes risk while allowing time for restoration or tripping of channels.

B.1

If any Required Action and associated Completion Time is not met, the associated Function may not be capable of performing the intended function. Therefore, the associated DG(s) are declared inoperable immediately. This requires entry into applicable Conditions and Required Actions of LCO 3.8.1 and LCO 3.8.2, which provide appropriate actions for the inoperable DG(s).

SURVEILLANCE REQUIREMENTS

As noted at the beginning of the SRs, the SRs for each LOP Instrumentation Function are located in the SRs column of Table 3.3.8.1-1.

(continued)

BASES

SURVEILLANCE REQUIREMENTS (continued)

The Surveillances are modified by a Note to indicate that when a channel is placed in an inoperable status solely for performance of required Surveillances, entry into associated Conditions and Required Actions may be delayed for up to 2 hours provided the associated Function maintains LOP initiation capability. LOP initiation capability is maintained provided the associated Function can perform the load shed and control scheme for two of the three 4.16 kV emergency buses. Upon completion of the Surveillance, or expiration of the 2 hour allowance, the channel must be returned to OPERABLE status or the applicable Condition entered and Required Actions taken.

SR 3.3.8.1.1 and SR 3.3.8.1.3

A CHANNEL FUNCTIONAL TEST is performed on each required channel to ensure that the channel will perform the intended function. A successful test of the required contact(s) of a channel relay may be performed by the verification of the change of state of a single contact of the relay. This clarifies what is an acceptable CHANNEL FUNCTIONAL TEST of a relay. This is acceptable because all of the other required contacts of the relay are verified by other Technical Specifications and non-Technical Specifications tests at least once per refueling interval with applicable extensions. Any setpoint adjustment shall be consistent with the assumptions of the current plant specific setpoint methodology.

The Frequencies of 18 months and 24 months are based on plant operating experience with regard to channel OPERABILITY and drift that demonstrates that failure of more than one channel of a given Function in any 18 month or 24 month interval, as applicable, is rare.

SR 3.3.8.1.2 and SR 3.3.8.1.4

A CHANNEL CALIBRATION is a complete check of the instrument loop and the sensor. This test verifies the channel responds to the measured parameter within the necessary

(continued)

BASES

SURVEILLANCE REQUIREMENTS

SR 3.3.8.1.2 and SR 3.3.8.1.4 (continued)

range and accuracy. CHANNEL CALIBRATION leaves the channel adjusted to account for instrument drifts between successive calibrations consistent with the plant specific setpoint methodology.

The Frequency is based on the assumption of an 18 month or 24 month calibration interval, as applicable, in the determination of the magnitude of equipment drift in the setpoint analysis.

SR 3.3.8.1.5

The LOGIC SYSTEM FUNCTIONAL TEST demonstrates the OPERABILITY of the required actuation logic for a specific channel. The system functional testing performed in LCO 3.8.1 and LCO 3.8.2 overlaps this Surveillance to provide complete testing of the assumed safety functions. The 24 month Frequency is based on the need to perform this Surveillance under the conditions that apply during a plant outage and the potential for an unplanned transient if the Surveillance were performed with the reactor at power. Operating experience has shown these components usually pass the Surveillance when performed at the 24 month Frequency.

REFERENCES

1. UFSAR, Section 8.2.3.3.

2. UFSAR, Section 5.2.

3. UFSAR, Section 6.3.

4. UFSAR, Chapter 15.

B 3.3 INSTRUMENTATION

B 3.3.8.2 Reactor Protection System (RPS) Electric Power Monitoring

BASES

BACKGROUND

The RPS Electric Power Monitoring System is provided to isolate the RPS bus from the motor generator (MG) set or the alternate power supply in the event of overvoltage, undervoltage, or underfrequency. This system protects the loads connected to the RPS bus against unacceptable voltage and frequency conditions (Ref. 1) and forms an important part of the primary success path for the essential safety circuits. Some of the essential equipment powered from the RPS buses includes the RPS logic, scram solenoids, and various valve isolation logic.

The RPS Electric Power Monitoring assembly will detect any abnormal high or low voltage or low frequency condition in the outputs of the two MG sets or the alternate power supply and will de-energize its respective RPS bus, thereby causing all safety functions normally powered by this bus to de-energize.

In the event of failure of an RPS Electric Power Monitoring System (e.g., both inseries electric power monitoring assemblies), the RPS loads may experience significant effects from the unregulated power supply. Deviation from the nominal conditions can potentially cause damage to the scram and MSIV trip solenoids and other Class 1E devices.

In the event of a low voltage condition, for an extended period of time, the scram and MSIV trip solenoids can chatter and potentially lose their pneumatic control capability, resulting in a loss of primary scram and MSIV closure action.

In the event of an overvoltage condition, the RPS and isolation logic relays and scram solenoids, as well as the main steam isolation valve trip solenoids, may experience a voltage higher than their design voltage. If the overvoltage condition persists for an extended time period, it may cause equipment degradation and the loss of plant safety function.

(continued)

BASES

BACKGROUND (continued)

Two redundant Class 1E circuit breakers are connected in series between each RPS bus and its MG set, and between each RPS bus and the alternate power supply. Each of these circuit breakers has an associated independent set of Class 1E overvoltage, undervoltage, and underfrequency sensing logic. Together, a circuit breaker and its sensing logic constitute an electric power monitoring assembly. If the output of the inservice MG set or alternate power supply exceeds the predetermined limits of overvoltage, undervoltage, or underfrequency, a trip coil driven by this logic circuitry opens the circuit breaker, which removes the associated power supply from service.

APPLICABLE SAFETY ANALYSES

RPS Electric Power Monitoring is necessary to meet the assumptions of the safety analyses by ensuring that the equipment powered from the RPS buses can perform its intended function. RPS Electric Power Monitoring provides protection to the RPS and other systems that receive power from the RPS buses, by disconnecting the RPS bus from the power supply under specified conditions that could damage the RPS bus powered equipment.

RPS Electric Power Monitoring satisfies Criterion 3 of 10 CFR 50.36(c)(2)(ii).

LCO

The OPERABILITY of each RPS electric power monitoring assembly is dependent upon the OPERABILITY of the overvoltage, undervoltage, and underfrequency logic, as well as the OPERABILITY of the associated circuit breaker. Two electric power monitoring assemblies are required to be OPERABLE for each inservice power supply. This provides redundant protection against any abnormal voltage or frequency conditions to ensure that no single RPS electric power monitoring assembly failure can preclude the function of RPS bus powered components. Each of the inservice electric power monitoring assembly trip logic setpoints is required to be within the specific Allowable Value. The actual setpoint is calibrated consistent with applicable setpoint methodology assumptions.

(continued)

BASES

LCO (continued)

Allowable Values are specified for each RPS electric power monitoring assembly trip logic (refer to SR 3.3.8.2.2). Nominal trip setpoints are specified in the setpoint calculations. The nominal setpoints are selected to ensure that the setpoints do not exceed the Allowable Value between CHANNEL CALIBRATIONS. Operation with a trip setpoint less conservative than the nominal trip setpoint, but within its Allowable Value, is acceptable. A channel is inoperable if its actual trip setpoint is not within its required Allowable Value. Trip setpoints are those predetermined values of output at which an action should take place. The setpoints are compared to the actual process parameter (e.g., overvoltage), and when the measured output value of the process parameter exceeds the setpoint, the associated device (e.g., trip coil) changes state. The analytic limits are derived from the limiting values of the process parameters obtained from the safety analysis. The trip setpoints are determined from the analytic limits, corrected for defined process, calibration, and instrument errors. The Allowable Values are then determined, based on the trip setpoint values, by accounting for the calibration based errors. These calibration based errors are limited to reference accuracy, instrument drift, errors associated with measurement and test equipment, and calibration tolerance of loop components. The trip setpoints and Allowable Values determined in this manner provide adequate protection because instrument uncertainties, process effects, calibration tolerances, instrument drift, and severe environment errors (for channels that must function in harsh environments as defined by 10 CFR 50.49) are accounted for and appropriately applied for the instrumentation.

The Allowable Values for the instrument settings are based on the RPS providing ≥ 57 Hz and 120 V ± 10%. The most limiting voltage requirement and associated line losses determine the settings of the electric power monitoring instrument channels. The settings are calculated based on the loads on the buses and RPS MG set or alternate power supply being 120 VAC and 60 Hz.

(continued)

BASES (continued)

APPLICABILITY

The operation of the RPS electric power monitoring assemblies is essential to disconnect the RPS bus powered components from the inservice MG set or alternate power supply during abnormal voltage or frequency conditions. Since the degradation of a nonclass 1E source supplying power to the RPS bus can occur as a result of any random single failure, the OPERABILITY of the RPS electric power monitoring assemblies is required when the RPS bus powered components are required to be OPERABLE. This results in the RPS Electric Power Monitoring System OPERABILITY being required in MODES 1, 2, and 3, MODES 4 and 5, with residual heat removal (RHR) shutdown cooling isolation valves open, MODE 5 with any control rod withdrawn from a core cell containing one or more fuel assemblies, during movement of irradiated fuel assemblies in the secondary containment, during CORE ALTERATIONS, and during operations with a potential for draining the reactor vessel (OPDRVs).

ACTIONS

A.1

If one RPS electric power monitoring assembly for an inservice power supply (MG set or alternate) is inoperable, or one RPS electric power monitoring assembly on each inservice power supply is inoperable, the OPERABLE assembly will still provide protection to the RPS bus powered components under degraded voltage or frequency conditions. However, the reliability and redundancy of the RPS Electric Power Monitoring System are reduced and only a limited time (72 hours) is allowed to restore the inoperable assembly(s) to OPERABLE status. If the inoperable assembly(s) cannot be restored to OPERABLE status, the associated power supply must be removed from service (Required Action A.1). This places the RPS bus in a safe condition. An alternate power supply with OPERABLE power monitoring assemblies may then be used to power the RPS bus.

The 72 hour Completion Time takes into account the remaining OPERABLE electric power monitoring assembly and the low probability of an event requiring RPS Electric Power Monitoring protection occurring during this period. It allows time for plant operations personnel to take corrective actions or to place the plant in the required condition in an orderly manner and without challenging plant systems.

(continued)

BASES

ACTIONS

A.1 (continued)

Alternatively, if it is not desired to remove the power supply(s) from service (e.g., as in the case where removing the power supply(s) from service would result in a scram or isolation), Condition C, D, E, or F as applicable, must be entered and its Required Actions taken.

B.1

If both power monitoring assemblies for an inservice power supply (MG set or alternate) are inoperable, or both power monitoring assemblies in each inservice power supply are inoperable, the system protective function is lost. In this condition, 1 hour is allowed to restore one assembly to OPERABLE status for each inservice power supply. If one inoperable assembly for each inservice power supply cannot be restored to OPERABLE status, the associated power supplies must be removed from service within 1 hour (Required Action B.1). An alternate power supply with OPERABLE assemblies may then be used to power one RPS bus. The 1 hour Completion Time is sufficient for the plant operations personnel to take corrective actions and is acceptable because it minimizes risk while allowing time for restoration or removal from service of the electric power monitoring assemblies.

Alternately, if it is not desired to remove the power supply(s) from service (e.g., as in the case where removing the power supply(s) from service would result in a scram or isolation), Condition C, D, E, or F as applicable, must be entered and its Required Actions taken.

C.1 and C.2

If any Required Action and associated Completion Time of Condition A or B are not met in MODE 1, 2, or 3, a plant shutdown must be performed. This places the plant in a condition where minimal equipment, powered through the inoperable RPS electric power monitoring assembly(s), is required and ensures that the safety function of the RPS bus loads (e.g., scram of control rods) is not required. The

(continued)

BASES

ACTIONS

C.1 and C.2 (continued)

plant shutdown is accomplished by placing the plant in MODE 3 within 12 hours and in MODE 4 within 36 hours. The allowed Completion Times are reasonable, based on operating experience, to reach the required plant conditions from full power conditions in an orderly manner and without challenging plant systems.

D.1 and D.2

If any Required Action and associated Completion Time of Condition A or B are not met in MODE 4 or 5 with RHR SDC isolation valves open, action must be immediately initiated to either restore one electric power monitoring assembly to OPERABLE status for the inservice power source supplying the required instrumentation powered from the RPS bus (Required Action D.1) or to isolate the RHR SDC System (Required Action D.2). Required Action D.1 is provided because the RHR SDC System may be needed to provide core cooling. All actions must continue until the applicable Required Actions are completed.

E.1

If any Required Action and associated Completion Time of Condition A or B are not met in MODE 5 with any control rod withdrawn from a core cell containing one or more fuel assemblies, the operator must immediately initiate action to fully insert all insertable control rods in core cells containing one or more fuel assemblies (Required Action E.1). This Required Action results in the least reactive condition for the reactor core and ensures that the safety function of the RPS (e.g., scram of control rods) is not required.

F.1.1, F.1.2, F.2.1, and F.2.2

If any Required Action and associated Completion Time of Condition A or B are not met during movement of irradiated fuel assemblies in the secondary containment, during CORE ALTERATIONS, or during OPDRVs, the ability to isolate the

(continued)

BASES

ACTIONS

F.1.1, F.1.2, F.2.1, and F.2.2 (continued)

secondary containment and start the Standby Gas Treatment (SGT) System cannot be ensured. Therefore, actions must be immediately performed to ensure the ability to maintain the secondary containment and SGT System functions. Isolating the affected penetration flow path(s) and starting the associated SGT subsystem(s) (Required Actions F.1.1 and F.2.1) performs the intended function of the instrumentation the RPS electric power monitoring assemblies is protecting, and allows operations to continue.

Alternatively, immediately declaring the associated secondary containment isolation valve(s) or SGT subsystem(s) inoperable (Required Action F.1.2 and F.2.2) is also acceptable since the Required Actions of the respective LCOs (LCO 3.6.4.2 and LCO 3.6.4.3) provide appropriate actions for the inoperable components.

SURVEILLANCE REQUIREMENTS

SR 3.3.8.2.1

A CHANNEL FUNCTIONAL TEST is performed on each overvoltage, undervoltage, and underfrequency channel to ensure that the channel will perform the intended function. A successful test of the required contact(s) of a channel relay may be performed by the verification of the change of state of a single contact of the relay. This clarifies what is an acceptable CHANNEL FUNCTIONAL TEST of a relay. This is acceptable because all of the other required contacts of the relay are verified by other Technical Specifications and non-Technical Specifications tests at least once per refueling interval with applicable extensions. Any setpoint adjustment shall be consistent with the assumptions of the current plant specific setpoint methodology.

As noted in the Surveillance, the CHANNEL FUNCTIONAL TEST is only required to be performed while the plant is in a condition in which the loss of the RPS bus will not jeopardize steady state power operation (the design of the system is such that the power source must be removed from service to conduct the Surveillance). The 24 hours is intended to indicate an outage of sufficient duration to

(continued)

BASES

SURVEILLANCE REQUIREMENTS

SR 3.3.8.2.1 (continued)

allow for scheduling and proper performance of the Surveillance. The 184 day Frequency and the Note in the Surveillance are based on guidance provided in Generic Letter 91-09 (Ref. 2).

SR 3.3.8.2.2

CHANNEL CALIBRATION is a complete check of the instrument loop and the sensor. This test verifies that the channel responds to the measured parameter within the necessary range and accuracy. CHANNEL CALIBRATION leaves the channel adjusted to account for instrument drifts between successive calibrations consistent with the plant specific setpoint methodology.

The Frequency is based upon the assumption of an 24 month calibration interval in the determination of the magnitude of equipment drift in the setpoint analysis.

SR 3.3.8.2.3

Performance of a system functional test demonstrates that, with a required system actuation (simulated or actual) signal, the logic of the system will automatically trip open the associated power monitoring assembly circuit breaker. The system functional test shall include actuation of the protective relays, tripping logic, and output circuit breakers. Only one signal per power monitoring assembly is required to be tested. This Surveillance overlaps with the CHANNEL CALIBRATION to provide complete testing of the safety function. The system functional test of the Class 1E circuit breakers is included as part of this test to provide complete testing of the safety function. If the breakers are incapable of operating, the associated electric power monitoring assembly would be inoperable.

The 24 month Frequency is based on the need to perform this Surveillance under the conditions that apply during a plant outage and the potential for an unplanned transient if the

(continued)

BASES

SURVEILLANCE REQUIREMENTS

SR 3.3.8.2.3 (continued)

Surveillance were performed with the reactor at power. Operating experience has shown that these components usually pass the Surveillance when performed at the 24 month Frequency.

REFERENCES

1. UFSAR, Section 8.3.1.1.3.

2. NRC Generic Letter 91-09, "Modification of Surveillance Interval for the Electric Protective Assemblies in Power Supplies for the Reactor Protection System."

B 3.4 REACTOR COOLANT SYSTEM (RCS)

B 3.4.1 Recirculation Loops Operating

BASES

BACKGROUND

The Reactor Recirculation System is designed to provide a forced coolant flow through the core to remove heat from the fuel. The forced coolant flow removes heat at a faster rate from the fuel than would be possible with just natural circulation. The forced flow, therefore, allows operation at significantly higher power than would otherwise be possible. The recirculation system also controls reactivity over a wide span of reactor power by varying the recirculation flow rate to control the void content of the moderator. The Reactor Recirculation System consists of two recirculation pump loops external to the reactor vessel. These loops provide the piping path for the driving flow of water to the reactor vessel jet pumps. Each external loop contains a two speed motor driven recirculation pump, a flow control valve, associated piping, jet pumps, valves, and instrumentation. The recirculation loops are part of the reactor coolant pressure boundary and are located inside the drywell structure. The jet pumps are reactor vessel internals.

The recirculated coolant consists of saturated water from the steam separators and dryers that has been subcooled by incoming feedwater. This water passes down the annulus between the reactor vessel wall and the core shroud. A portion of the coolant flows from the vessel, through the two external recirculation loops, and becomes the driving flow for the jet pumps. Each of the two external recirculation loops discharges high pressure flow into an external manifold, from which individual recirculation inlet lines are routed to the jet pump risers within the reactor vessel. The remaining portion of the coolant mixture in the annulus becomes the suction flow for the jet pumps. This flow enters the jet pump at suction inlets and is accelerated by the driving flow. The drive flow and suction flow are mixed in the jet pump throat section and result in partial pressure recovery. The total flow then passes through the jet pump diffuser section into the area below the core (lower plenum), gaining sufficient head in the process to drive the required flow upward through the core.

(continued)

BASES

BACKGROUND (continued)

The subcooled water enters the bottom of the fuel channels and contacts the fuel cladding, where heat is transferred to the coolant. As it rises, the coolant begins to boil, creating steam voids within the fuel channel that continue until the coolant exits the core. Because of reduced moderation, the steam voiding introduces negative reactivity that must be compensated for to maintain or to increase reactor power. The recirculation flow control allows operators to increase recirculation flow and sweep some of the voids from the fuel channel, overcoming the negative reactivity void effect. Thus, the reason for having variable recirculation flow is to compensate for reactivity effects of boiling over a wide range of power generation (i.e., approximately 65 to 100% RTP) without having to move control rods and disturb desirable flux patterns. In addition, the combination of core flow and THERMAL POWER is normally maintained such that core thermal-hydraulic oscillations do not occur. These oscillations can occur during two recirculation loop operation, single recirculation loop, and no recirculation loop operation. Plant procedures include requirements of this LCO as well as other vendor and NRC recommended requirements and actions to minimize the potential of core thermal-hydraulic oscillations.

Each recirculation loop is manually started from the control room. The recirculation flow control valves provide regulation of individual recirculation loop drive flows. The flow in each loop can be manually or automatically controlled.

APPLICABLE SAFETY ANALYSES

The operation of the Reactor Recirculation System is an initial condition assumed in the design basis loss of coolant accident (LOCA) (Ref. 1). During a LOCA caused by a recirculation loop pipe break, the intact loop is assumed to provide coolant flow during the first few seconds of the accident. The initial core flow decrease is rapid because the recirculation pump in the broken loop ceases to pump reactor coolant to the vessel almost immediately. The pump in the intact loop coasts down relatively slowly. This pump coastdown governs the core flow response for the next several seconds until the jet pump suction is uncovered (Ref. 2). The analyses assume that both loops are operating at the same flow prior to the accident. However, the LOCA

(continued)

BASES

APPLICABLE SAFETY ANALYSES (continued)

analysis was reviewed for the case with a flow mismatch between the two loops, with the pipe break assumed to be in the loop with the higher flow. While the flow coastdown and core response are potentially more severe in this assumed case (since the intact loop starts at a lower flow rate and the core response is the same as if both loops were operating at a lower flow rate), a small mismatch has been determined to be acceptable based on engineering judgement.

The recirculation system is also assumed to have sufficient flow coastdown characteristics to maintain fuel thermal margins during abnormal operational transients (Ref. 2), which are analyzed in Chapter 15 of the UFSAR.

A plant specific LOCA analysis has been performed assuming only one operating recirculation loop. This analysis has demonstrated that, in the event of a LOCA caused by a pipe break in the operating recirculation loop, the Emergency Core Cooling System response will provide adequate core cooling, provided the APLHGR requirements are modified accordingly (Ref. 3).

The transient analyses in Chapter 15 of the UFSAR have also been performed for single recirculation loop operation (Ref. 3) and demonstrate sufficient flow coastdown characteristics to maintain fuel thermal margins during the abnormal operational transients analyzed provided the MCPR requirements are modified. During single recirculation loop operation, modification to the Reactor Protection System average power range monitor (APRM) and the Rod Block Monitor (RBM) Allowable Values is also required to account for the different relationships between recirculation drive flow and reactor core flow. The APLHGR and MCPR limits for single loop operation are specified in the COLR. The APRM Flow Biased Simulated Thermal Power-Upscale Allowable Value is in LCO 3.3.1.1, "Reactor Protection System (RPS) Instrumentation." The Rod Block Monitor-Upscale Allowable Value is specified in the COLR. Safety analyses performed in References 1, 2, and 3 implicitly assume core conditions are stable. However, during operation at the high power/low flow region of the operating domain, a small probability of limit cycle neutron flux oscillations exists depending on combinations of operating conditions (e.g., power shape, bundle power, and bundle flow).

(continued)

BASES

APPLICABLE SAFETY ANALYSES (continued)

General Electric (GE) Service Information Letter (SIL) No. 380 (Ref. 4) addressed boiling instability and made several recommendations. In this SIL, the power/flow operating map was divided into several regions of varying concern. It also discussed the objectives and philosophy of "detect and suppress."

NRC Generic Letter 86-02 (Ref. 5) discussed both the GE and Siemens stability methodology and stated that due to uncertainties, 10 CFR 50, Appendix A, General Design Criteria (GDC) 10 and 12 could not be met using available analytical procedures on a BWR. The Generic Letter discussed SIL 380 and stated that GDC 10 and 12 could be met by imposing SIL 380 recommendations in operating regions of potential instability. The NRC concluded that regions of potential instability constituted decay ratios of 0.8 and greater by the GE methodology and 0.75 by the Siemens methodology. Figure 3.4.1-1 was generated as an interim solution to provide an increased margin of safety until the investigation is completed (Ref. 6)

Recirculation loops operating satisfies Criterion 2 of 10 CFR 50.36(c)(2)(ii).

LCO

Two recirculation loops are normally required to be in operation with their flows matched within the limits specified in SR 3.4.1.1 to ensure that during a LOCA caused by a break of the piping of one recirculation loop the assumptions of the LOCA analysis are satisfied. With the limits specified in SR 3.4.1.1 not met, the recirculation loop with the lower flow must be considered not in operation. With only one recirculation loop in operation, modifications to the required APLHGR limits (LCO 3.2.1, "AVERAGE PLANAR LINEAR HEAT GENERATION RATE (APLHGR)"), MCPR limits (LCO 3.2.2, "MINIMUM CRITICAL POWER RATIO (MCPR)"), APRM Flow Biased Simulated Thermal Power—Upscale Allowable Value (LCO 3.3.1.1), and the Rod Block Monitor—Upscale Allowable Value (LCO 3.3.2.1) must be applied to allow continued operation consistent with the assumptions of Reference 3. In addition, during two-loop and single-loop

(continued)

BASES

LCO (continued)

operation, the combination of core flow and THERMAL POWER must be in Region III of Figure 3.4.1-1 to ensure core thermal-hydraulic oscillations do not occur.

APPLICABILITY

In MODES 1 and 2, requirements for operation of the Reactor Recirculation System are necessary since there is considerable energy in the reactor core and the limiting design basis transients and accidents are assumed to occur.

In MODES 3, 4, and 5, the consequences of an accident are reduced and the coastdown characteristics of the recirculation loops are not important.

ACTIONS

A.1, A.2, and A.3

With one or two recirculation loops in operation in Region II of Figure 3.4.1-1, the plant is operating in a region where the potential for thermal-hydraulic oscillations exists. To ensure oscillations are not occurring, APRM and LPRM neutron flux noise levels must be verified to be less than or equal to the larger of either 3 times the baseline noise levels or 10% peak-to-peak (Required Action A.1 and A.2) when Region II is entered. For the LPRM neutron flux noise verification, detector levels A and C of one LPRM string per core octant plus detector levels A and C of one LPRM string in the center region of the core should be monitored. Prompt action to monitor APRM and LPRM neutron flux noise levels should be taken to ensure oscillations are not occurring.

The 45 minute Completion Time of Required Actions A.1 and A.2 provides a reasonable time to stabilize operation in Region II and verify the neutron flux noise levels are within limits. A verification of the APRM and LPRM neutron flux noise levels once per 12 hours following the initial verification provides frequent periodic information of neutron flux noise levels to verify stable steady state operation. Also, a verification of neutron flux noise levels after any THERMAL POWER increase of $\geq$ 5% RTP while in Region II provides indication of operational stability following a potential for change of the thermal-hydraulic properties of the system.

(continued)

BASES

ACTIONS

A.1, A.2, and A.3 (continued)

In addition, a verification that one or both recirculation loops are not operating within Region I of Figure 3.4.1-1 (Required Action A.3) is required to be performed once per 12 hours. The Completion Time of once per 12 hours is reasonable based on operating experience and the operator's knowledge of reactor status, including changes in reactor power and core flow.

B.1

If evidence of approaching reactor instability occurs (i.e., APRM or LPRM neutron flux noise levels exceed the associated limit of Required Actions A.1 or A.2, as applicable) while operating in Region II of Figure 3.4.1-1, prompt action should be taken to restore the APRM or LPRM neutron flux noise levels to within the associated limit or exit Region II of Figure 3.4.1-1. This may be accomplished by either increasing core flow by recirculation loop flow control valve manipulation or reduction of THERMAL POWER by control rod insertion. The 2 hour Completion Time is reasonable to restore plant parameters in an orderly manner and without challenging plant systems.

C.1

With one or both recirculation loops in operation in Region I of Figure 3.4.1-1, the plant is operating in a region where the potential for thermal-hydraulic oscillations is increased and sufficient margin may not be available for operator response to suppress potential thermal-hydraulic oscillations. As a result, prompt action should be taken to exit Region I of Figure 3.4.1-1. This may be accomplished by either increasing core flow by recirculation loop flow control valve manipulation or reduction of THERMAL POWER by control rod insertion. The 2 hour Completion Time is reasonable to restore plant parameters in an orderly manner and without challenging plant systems.

(continued)

BASES

ACTIONS (continued)

D.1, D.2, and D.3

With no recirculation loops in service, the probability of thermal-hydraulic oscillations is greatly increased. Therefore, prompt action should be taken to ensure oscillations are not occurring by verifying APRM and LPRM neutron flux noise levels are ≤ 10% peak-to-peak. If neutron flux noise levels are discovered to be > 10% peak-to-peak at anytime while in this Condition, Condition E must be immediately entered.

Also, prompt action should be taken to reduce THERMAL POWER low enough to avoid the region of potential instability in natural circulation (i.e., reduce THERMAL POWER below 36% RTP). The 2 hour Completion Time provides are reasonable time to restore operation to Region III of Figure 3.4.1-1.

In addition, with no recirculation loops in operation, plant operation is not allowed to continue in MODE 1 or 2. Therefore, the unit is required to be brought to a MODE in which the LCO does not apply. The allowed Completion Time of 12 hours is reasonable, based on operating experience, to reach MODE 3 in an orderly manner and without challenging plant systems.

E.1

In the event no recirculation loops are in operation and evidence is indicated of approaching reactor instability (i.e., APRM or LPRM neutron flux noise levels exceed the associated limit) or APRM or LPRM neutron flux noise levels cannot be restored within 2 hours while in Region II of Figure 3.4.1-1, action must be immediately initiated to eliminate the potential for a thermal-hydraulic instability event. As such, the reactor mode switch must be immediately placed in the shutdown position.

(continued)

BASES

ACTIONS (continued)

F.1 and G.1

With both recirculation loops operating but the flows not matched, the flows must be matched within 2 hours. If matched flows are not restored, the recirculation loop with lower flow must be declared "not in operation," as required by Required Action F.1. This Required Action does not require tripping the recirculation pump in the lowest flow loop when the mismatch between total jet pump flows of the two loops is greater than the required limits. However, in cases where large flow mismatches occur, low flow or reverse flow can occur in the low flow loop jet pumps, causing vibration of the jet pumps. If zero or reverse flow is detected, the condition should be alleviated by changing flow control valve position to re-establish forward flow or by tripping the pump.

With the requirements of the LCO not met for reasons other than Conditions A, C, D, and F (e.g., one loop is "not in operation"), compliance with the LCO must be restored within 24 hours. A recirculation loop is considered not in operation when the pump in that loop is idle or when the mismatch between total jet pump flows of the two loops is greater than required limits for greater than 2 hours (i.e., Required Action F.1 has been taken). Should a LOCA occur with one recirculation loop not in operation, the core flow coastdown and resultant core response may not be bounded by the LOCA analyses. Therefore, only a limited time is allowed to restore the inoperable loop to operating status.

Alternatively, if the single loop requirements of the LCO are applied to the APLHGR and MCPR operating limits and RPS and RBM Allowable Values, operation with only one recirculation loop would satisfy the requirements of the LCO and the initial conditions of the accident sequence.

The 2 hour and 24 hour Completion Times are based on the low probability of an accident occurring during this time period, on a reasonable time to complete the Required Action, and on frequent core monitoring by operators allowing abrupt changes in core flow conditions to be quickly detected.

(continued)

BASES

ACTIONS (continued)

H.1

If the Required Action and associated Completion Time of Condition G is not met, the unit is required to be brought to a MODE in which the LCO does not apply. To achieve this status, the plant must be brought to MODE 3 within 12 hours. In this condition, the recirculation loops are not required to be operating because of the reduced severity of DBAs and minimal dependence on the recirculation loop coastdown characteristics. The allowed Completion Time of 12 hours is reasonable, based on operating experience, to reach MODE 3 from full power conditions in an orderly manner and without challenging plant systems.

SURVEILLANCE REQUIREMENTS

SR 3.4.1.1

This SR ensures the recirculation loop flows are within the allowable limits for mismatch. At low core flow (i.e., < 70% of rated core flow), the APLHGR and MCPR requirements provide larger margins to the fuel cladding integrity Safety Limit such that the potential adverse effect of early boiling transition during a LOCA is reduced. A larger flow mismatch can therefore be allowed when core flow is < 70% of rated core flow. The recirculation loop jet pump flow, as used in this Surveillance, is the summation of the flows from all of the jet pumps associated with a single recirculation loop.

The mismatch is measured in terms of percent of rated core flow. If the flow mismatch exceeds the specified limits, the loop with the lower flow is considered not in operation. This SR is not required when both loops are not in operation since the mismatch limits are meaningless during single loop or natural circulation operation. The Surveillance must be performed within 24 hours after both loops are in operation. The 24 hour Frequency is consistent with the Frequency for jet pump OPERABILITY verification and has been shown by operating experience to be adequate to detect off normal jet pump loop flows in a timely manner.

(continued)

BASES

SURVEILLANCE REQUIREMENTS (continued)

SR 3.4.1.2

The SR ensures the combination of core flow and THERMAL POWER are within the appropriate limits to prevent inadvertent entry into a region of potential thermal-hydraulic instability. At low recirculation loop flow and high reactor power, the reactor exhibits increased susceptibility to thermal-hydraulic instability. Figure 3.4.1-1 is based on guidance provided in References 4 and 5. The 24 hour Frequency is based on operating experience and the operator's knowledge of the reactor status, including significant changes in THERMAL POWER and core flow.

REFERENCES

1. UFSAR, Sections 6.3 and 15.6.5.

2. UFSAR, Appendix G.3.1.2.

3. UFSAR, Section 6.B.

4. GE Service Information Letter (SIL) No. 380, "BWR Core Thermal Hydraulic Stability," Revision 1, February 10, 1984.

5. NRC Generic Letter 86-02, "Technical Resolution of Generic Issue B-19, Thermal Hydraulic Stability," January 22, 1986.

6. NRC Safety Evaluation supporting Amendment No. 60 to Facility Operating License No. 11 and Amendment No. 40 to Facility Operating License No. 18, Commonwealth Edison Company, LaSalle County Station, Units 1 and 2, dated September 7, 1988.

B 3.4 REACTOR COOLANT SYSTEM (RCS)

B 3.4.2 Flow Control Valves (FCVs)

BASES

BACKGROUND

The Reactor Recirculation System is described in the Background section of the Bases for LCO 3.4.1, "Recirculation Loops Operating," which discusses the operating characteristics of the system and how this affects the design basis transient and accident analyses. The FCVs are part of the Reactor Recirculation System.

The Recirculation Flow Control System consists of the electronic and hydraulic components necessary for the positioning of the two hydraulically actuated FCVs. The recirculation loop flow rate can be rapidly changed within the expected flow range, in response to rapid changes in system demand. Limits on the system response are required to minimize the impact on core flow response during certain accidents and transients. Solid state control logic will generate an FCV "motion inhibit" signal in response to any one of several hydraulic power unit or analog control circuit failure signals. The "motion inhibit" signal causes hydraulic power unit shutdown and hydraulic isolation such that the FCVs fail "as is."

APPLICABLE SAFETY ANALYSES

The FCV stroke rate is limited to ≤ 11% per second in the opening and closing directions on a control signal failure of maximum demand. This stroke rate is an assumption of the analysis of the recirculation flow control failures on decreasing and increasing flow (Refs. 1 and 2). During a LOCA caused by a recirculation loop pipe break, the intact loop is assumed to provide coolant flow during the first few seconds of the accident. The initial core flow decrease is rapid because the recirculation pump in the broken loop ceases to pump almost immediately since it has lost suction. The pump in the intact loop coasts down relatively slowly. This pump coastdown governs the core flow response for the next several seconds (Ref. 3), because the FCV is assumed to fail "as is" due to a motion inhibit as a result of a high drywell pressure interlock. In addition, the closure of a recirculation FCV concurrent with a loss of coolant accident (LOCA) was analyzed during

(continued)

BASES

APPLICABLE SAFETY ANALYSES (continued)

initial licensing and found to be acceptable for a maximum closure rate of 11% of stroke per second, since this event involves multiple failures.

Flow control valves satisfy Criterion 2 of 10 CFR 50.36(c)(2)(ii).

LCO

An FCV in each operating recirculation loop must be OPERABLE to ensure that the assumptions of the design basis transient and accident analyses are satisfied.

APPLICABILITY

In MODES 1 and 2, the FCVs are required to be OPERABLE, since during these conditions there is considerable energy in the reactor core, and the limiting design basis transients and accidents are assumed to occur. In MODES 3, 4, and 5, the consequences of a transient or accident are reduced and OPERABILITY of the flow control valves is not important.

ACTIONS

A Note has been provided to modify the ACTIONS related to FCVs. Section 1.3, Completion Times, specifies once a Condition has been entered, subsequent divisions, subsystems, components or variables expressed in the Condition, discovered to be inoperable or not within limits, will not result in separate entry into the Condition. Section 1.3 also specifies Required Actions of the Condition continue to apply for each additional failure, with Completion Times based on initial entry into the Condition. However, the Required Actions for inoperable FCVs provide appropriate compensatory measures for separate inoperable FCVs. As such, a Note has been provided that allows separate Condition entry for each inoperable FCV.

A.1

With one or two required FCVs inoperable, the assumptions of the design basis transient and accident analyses may not be met and the inoperable FCV must be returned to OPERABLE status or hydraulically locked within 4 hours.

Opening an FCV faster than the limit could result in a more severe flow runout transient. Closing an FCV faster than

(continued)

BASES

ACTIONS

A.1 (continued)

the limit could result in a more severe coolant flow decrease transient. Both conditions could result in violation of the Safety Limit MCPR. The FCVs are designed to lockup (high drywell pressure interlock) under LOCA conditions. When the FCVs "lock-up", the recirculation flow coastdown is adequate and the resulting calculated clad temperatures are acceptable. In addition, it has been calculated with the FCVs closing at the specified limit, the resulting calculated clad temperatures will also be acceptable. Closing an FCV faster than the limit assumed in the LOCA analysis (Ref. 3) could affect the recirculation flow coastdown, resulting in higher peak clad temperatures. Therefore, if an FCV is inoperable, deactivating the valve will essentially lock the valve in position, which will prohibit the FCV from adversely affecting the DBA and transient analyses. Continued operation is allowed in this Condition.

The 4 hour Completion Time is a reasonable time period to complete the Required Action, while limiting the time of operation with an inoperable FCV.

B.1

If the FCVs are not deactivated ("locked up") within the associated Completion Time, the unit must be brought to a MODE in which the LCO does not apply. To achieve this status, the unit must be brought to at least MODE 3 within 12 hours. This brings the unit to a condition where the flow coastdown characteristics of the recirculation loop are not important. The allowed Completion Time of 12 hours is reasonable, based on operating experience, to reach MODE 3 from full power conditions in an orderly manner and without challenging unit systems.

SURVEILLANCE REQUIREMENTS

SR 3.4.2.1

Hydraulic power unit pilot operated 4-way valves located between the servo valves and the common "open" and "close" lines are required to close in the event of a loss of hydraulic pressure. When closed, these valves inhibit FCV motion by blocking hydraulic pressure from the servo valve

(continued)

BASES

SURVEILLANCE REQUIREMENTS

SR 3.4.2.1 (continued)

to the common open and close lines as well as to the alternate subloop. This Surveillance verifies FCV lockup on a loss of hydraulic pressure.

The 24 month Frequency is based on the need to perform this Surveillance under the conditions that apply during a plant outage and the potential for an unplanned transient if the Surveillance were performed with the reactor at power. Operating experience has shown these components usually pass the SR when performed at the 24 month Frequency. Therefore, the Frequency was concluded to be acceptable from a reliability standpoint.

SR 3.4.2.2

This SR ensures the overall average rate of FCV movement at all positions is maintained within the analyzed limits.

The 24 month Frequency is based on the need to perform this Surveillance under the conditions that apply during a plant outage and the potential for an unplanned transient if the Surveillance were performed with the reactor at power. Operating experience has shown these components usually pass the SR when performed at the 24 month Frequency. Therefore, the Frequency was concluded to be acceptable from a reliability standpoint.

REFERENCES

1. UFSAR, Section 15.3.2.

2. UFSAR, Section 15.4.5.

3. UFSAR, Appendix G.

B 3.4 REACTOR COOLANT SYSTEM (RCS)

B 3.4.3 Jet Pumps

BASES

BACKGROUND

The Reactor Recirculation System is described in the Background section of the Bases for LCO 3.4.1, "Recirculation Loops Operating," which discusses the operating characteristics of the system and how these characteristics affect the Design Basis Accident (DBA) analyses.

The jet pumps are part of the Reactor Recirculation System and are designed to provide forced circulation through the core to remove heat from the fuel. The jet pumps are located in the annular region between the core shroud and the vessel inner wall. Because the jet pump suction elevation is at two thirds core height, the vessel can be reflooded and coolant level maintained at two thirds core height even with the complete break of the recirculation loop pipe that is located below the jet pump suction elevation.

Each reactor coolant recirculation loop contains 10 jet pumps. Recirculated coolant passes down the annulus between the reactor vessel wall and the core shroud. A portion of the coolant flows from the vessel, through the two external recirculation loops, and becomes the driving flow for the jet pumps. Each of the two external recirculation loops discharges high pressure flow into an external manifold from which individual recirculation inlet lines are routed to the jet pump risers within the reactor vessel. The remaining portion of the coolant mixture in the annulus becomes the suction flow for the jet pumps. This flow enters the jet pump at suction inlets and is accelerated by the drive flow. The drive flow and suction flow are mixed in the jet pump throat section. The total flow then passes through the jet pump diffuser section into the area below the core (lower plenum), gaining sufficient head in the process to drive the required flow upward through the core.

APPLICABLE SAFETY ANALYSES

Jet pump OPERABILITY is an explicit assumption in the design basis loss of coolant accident (LOCA) analysis evaluated in Reference 1.

(continued)

BASES

APPLICABLE SAFETY ANALYSES (continued)

The capability of reflooding the core to two-thirds core height is dependent upon the structural integrity of the jet pumps. If the structural system, including the beam holding a jet pump in place, fails, jet pump displacement and performance degradation could occur, resulting in an increased flow area through the jet pump and a lower core flooding elevation. This could adversely affect the water level in the core during the reflood phase of a LOCA as well as the assumed blowdown flow during a LOCA.

Jet pumps satisfy Criterion 3 of 10 CFR 50.36(c)(2)(ii).

LCO

The structural failure of any of the jet pumps could cause significant degradation in the ability of the jet pumps to allow reflooding to two thirds core height during a LOCA. OPERABILITY of all jet pumps is required to ensure that operation of the Reactor Recirculation System will be consistent with the assumptions used in the licensing basis analysis (Ref. 1).

APPLICABILITY

In MODES 1 and 2, the jet pumps are required to be OPERABLE since there is a large amount of energy in the reactor core and since the limiting DBAs are assumed to occur in these MODES. This is consistent with the requirements for operation of the Reactor Recirculation System (LCO 3.4.1).

In MODES 3, 4, and 5, the Reactor Recirculation System is not required to be in operation, and when not in operation sufficient flow is not available to evaluate jet pump OPERABILITY.

ACTIONS

A.1

An inoperable jet pump can increase the blowdown area and reduce the capability to reflood during a design basis LOCA. If one or more of the jet pumps are inoperable, the plant must be brought to a MODE in which the LCO does not apply. To achieve this status, the plant must be brought to MODE 3 within 12 hours. The allowed Completion Time of 12 hours is reasonable, based on operating experience, to reach MODE 3 from full power conditions in an orderly manner and without challenging plant systems.

(continued)

BASES (continued)

SURVEILLANCE REQUIREMENTS

SR 3.4.3.1

This SR is designed to detect significant degradation in jet pump performance that precedes jet pump failure (Ref. 2). This SR is required to be performed only when the loop has forced recirculation flow since surveillance checks and measurements can only be performed during jet pump operation. The jet pump failure of concern is a complete mixer displacement due to jet pump beam failure. Jet pump plugging is also of concern since it adds flow resistance to the recirculation loop. Significant degradation is indicated if any two of the three specified criteria confirm unacceptable deviations from established patterns or relationships. The allowable deviations from the established patterns have been developed based on the variations experienced at plants during normal operation and with jet pump assembly failures (Refs. 2 and 3). Since refueling activities (fuel assembly replacement or shuffle, as well as any modifications to fuel support orifice size or core plate bypass flow) can affect the relationship between core flow, jet pump flow, and recirculation loop flow, these relationships may need to be re-established each cycle. Similarly, initial entry into extended single loop operation may also require establishment of these relationships. During the initial weeks of operation under such conditions, while baselining new "established patterns", engineering judgement of the daily Surveillance results is used to detect significant abnormalities which could indicate a jet pump failure. In addition, during two recirculation loop operation, the jet pump SR should be performed with balanced recirculation loop drive flows (drive flow mismatch less than 5%) to ensure an accurate indication of jet pump performance.

The recirculation flow control valve (FCV) operating characteristics (loop flow characteristics versus FCV position) are determined by the flow resistance from the loop suction through the jet pump nozzles. A change in the relationship may indicate a flow restriction, loss in pump hydraulic performance, leak, or new flow path between the recirculation pump discharge and jet pump nozzle. For this criterion, the loop flow versus FCV position relationship must be verified. When both recirculation loops are operating, the established FCV position should include the

(continued)

BASES

SURVEILLANCE REQUIREMENTS

SR 3.4.3.1 (continued)

loop flow characteristics for two recirculation loop operation. When only one recirculation loop is operating, the established FCV position should include the loop flow characteristics for single loop operation.

Total calculated core flow can be determined from either the established THERMAL POWER-core flow relationship or the core plate differential pressure-core flow relationship. Once this relationship has been established, increased or reduced indicated total core flow from the calculated total core flow may be an indication of failures in one or several jet pumps. When determining calculated total core flow in single recirculation loop operation using the core plate differential pressure-core flow relationship, the calculated total core flow value should be derived using the established core plate differential pressure - core flow relationship for two recirculation loop operation.

Individual jet pumps in a recirculation loop typically do not have the same flow. The unequal flow is due to the drive flow manifold, which does not distribute flow equally to all risers. The jet pump diffuser to lower plenum differential pressure pattern or relationship of one jet pump to the loop average is repeatable. An appreciable change in this relationship is an indication that increased (or reduced) resistance has occurred in one of the jet pumps.

The deviations from normal are considered indicative of a potential problem in the recirculation drive flow or jet pump system (Ref. 2). Normal flow ranges and established jet pump differential pressure patterns are established by plotting historical data as discussed in Reference 2.

The 24 hour Frequency has been shown by operating experience to be adequate to verify jet pump OPERABILITY and is consistent with the Frequency for recirculation loop OPERABILITY verification.

This SR is modified by two Notes. Note 1 allows this Surveillance not to be performed until 4 hours after the associated recirculation loop is in operation, since these

(continued)

BASES

SURVEILLANCE REQUIREMENTS

SR 3.4.3.1 (continued)

checks can only be performed during jet pump operation. The 4 hours is an acceptable time to establish conditions appropriate for data collection and evaluation.

Note 2 allows this SR not to be performed until 24 hours after THERMAL POWER exceeds 25% RTP. During low flow conditions, jet pump noise approaches the threshold response of the associated flow instrumentation and precludes the collection of repeatable and meaningful data. The 24 hours is an acceptable time to establish conditions appropriate to perform this SR.

REFERENCES

1. UFSAR, Section 6.3 and Appendices G.2.2.2 and G.3.2.2.3.

2. GE Service Information Letter No. 330.

3. NUREG/CR-3052, "Closeout of IE Bulletin 80-07: BWR Jet Pump Assembly Failure," November 1984.

B 3.4 REACTOR COOLANT SYSTEM (RCS)

B 3.4.4 Safety/Relief Valves (S/RVs)

BASES

BACKGROUND

The American Society of Mechanical Engineers (ASME) Boiler and Pressure Vessel Code (Ref. 1) requires the Reactor Pressure Vessel be protected from overpressure during upset conditions by self actuated safety valves. As part of the nuclear pressure relief system, the size and number of safety/relief valves (S/RVs) are selected such that peak pressure in the nuclear system will not exceed the ASME Code limits for the reactor coolant pressure boundary (RCPB).

The S/RVs are located on the main steam lines between the reactor vessel and the first isolation valve within the drywell. Each S/RV discharges steam through a discharge line to a point below the minimum water level in the suppression pool.

The S/RVs can actuate by either of two modes: the safety mode or the relief mode (however, for the purpose of this LCO, only the safety mode is required). In the safety mode (or spring mode of operation), the direct action of the steam pressure in the main steam lines will act against a spring loaded disk that will pop open when the valve inlet pressure exceeds the spring force. In the relief mode (or power actuated mode of operation), a pneumatic piston/cylinder and mechanical linkage assembly are used to open the valve by overcoming the spring force, even with the valve inlet pressure equal to 0 psig. The pneumatic operator is arranged so that its malfunction will not prevent the valve disk from lifting if steam inlet pressure reaches the spring lift set pressures. In the relief mode, valves may be opened manually or automatically at the selected preset pressure. Seven of the S/RVs that provide the safety and relief function are part of the Automatic Depressurization System specified in LCO 3.5.1, "ECCS – Operating." The instrumentation associated with the relief valve function for the ADS function is discussed in LCO 3.3.5.1, "Emergency Core Cooling Systems (ECCS) Instrumentation."

(continued)

BASES (continued)

APPLICABLE SAFETY ANALYSES

The overpressure protection system must accommodate the most severe pressure transient. Evaluations have determined that the most severe transient is the closure of all main steam isolation valves (MSIVs) followed by reactor scram on high neutron flux (i.e., failure of the direct scram associated with MSIV position) (Ref. 2). For the purpose of the analyses, 17 of the S/RVs for Unit 1 and 12 of the S/RVs for Unit 2 are assumed to operate in the safety mode. The analysis results demonstrate that the design S/RV capacity is capable of maintaining reactor pressure below the ASME Code limit of 110% of vessel design pressure (110% x 1250 psig = 1375 psig). This LCO helps to ensure that the acceptance limit of 1375 psig is met during the design basis event.

From an overpressure standpoint, the design basis events are bounded by the MSIV closure with flux scram event described above. For other pressurization events, such as a turbine trip or generator load rejection with Main Turbine Bypass System failure, the S/RVs are assumed to function. The opening of the valves during the pressurization event mitigates the increase in reactor vessel pressure, which affects the MINIMUM CRITICAL POWER RATIO (MCPR) during these events. The number of S/RVs required to mitigate these events is bounded by the number required to be OPERABLE by the LCO.

S/RVs satisfy Criterion 3 of 10 CFR 50.36(c)(2)(ii).

LCO

The safety function of 17 S/RVs for Unit 1 and 12 S/RVs for Unit 2 is required to be OPERABLE. The requirements of this LCO are applicable only to the capability of the S/RVs to mechanically open to relieve excess pressure when the lift setpoint is exceeded (safety mode). In Reference 2, an evaluation was performed to establish the parametric relationship between the peak vessel pressure and the number of OPERABLE S/RVs. The results show that with a minimum of 17 S/RVs for Unit 1 and 12 S/RVs for Unit 2 in the safety mode OPERABLE, the ASME Code limit of 1375 psig is not exceeded.

(continued)

BASES

LCO (continued)

The S/RV safety setpoints are established to ensure the ASME Code limit on peak reactor pressure is satisfied. The ASME Code specifications require the lowest safety valve be set at or below vessel design pressure (1250 psig) and the highest safety valve be set so the total accumulated pressure does not exceed 110% of the design pressure for overpressurization conditions. The transient evaluations in Reference 3 involving the safety mode are based on these setpoints, but also include the additional uncertainties of ± 3% of the nominal setpoint to account for potential setpoint drift to provide an added degree of conservatism.

Operation with fewer valves OPERABLE than specified, or with setpoints outside the ASME limits, could result in a more severe reactor response to a transient than predicted, possibly resulting in the ASME Code limit on reactor pressure being exceeded.

The S/RVs are required to be OPERABLE to limit peak pressure in the main steam lines and maintain reactor pressure within acceptable limits during events that cause rapid pressurization, so that MCPR is not exceeded.

APPLICABILITY

In MODES 1, 2, and 3, the specified number of S/RVs must be OPERABLE since there may be considerable energy in the reactor core and the limiting design basis transients are assumed to occur. The S/RVs may be required to provide pressure relief to limit peak reactor pressure.

In MODE 4, decay heat is low enough for the RHR System to provide adequate cooling, and reactor pressure is low enough that the overpressure limit is unlikely to be approached by assumed operational transients or accidents. In MODE 5, the reactor vessel head is unbolted or removed and the reactor is at atmospheric pressure. The S/RV function is not needed during these conditions.

ACTIONS

A.1 and A.2

With less than the minimum number of required S/RVs OPERABLE, a transient may result in the violation of the ASME Code limit on reactor pressure. If one or more required S/RVs are inoperable, the plant must be brought to

(continued)

BASES

ACTIONS

A.1 and A.2 (continued)

a MODE in which the LCO does not apply. To achieve this status, the plant must be brought to at least MODE 3 within 12 hours and to MODE 4 within 36 hours. The allowed Completion Times are reasonable, based on operating experience, to reach the required plant conditions from full power conditions in an orderly manner and without challenging plant systems.

SURVEILLANCE REQUIREMENTS

SR 3.4.4.1

This Surveillance demonstrates that the required S/RVs will open at the pressures assumed in the safety analysis of Reference 2. The demonstration of the S/RV safety function lift settings must be performed during shutdown, since this is a bench test, and in accordance with the Inservice Testing Program. The lift setting pressure shall correspond to ambient conditions of the valves at nominal operating temperatures and pressures. The S/RV setpoint is ± 3% for OPERABILITY; however, the valves are reset to ± 1% during the Surveillance to allow for drift. A Note is provided to allow up to two of the required 17 S/RVs for Unit 1 and 12 S/RVs for Unit 2 to be physically replaced with S/RVs with lower setpoints. This provides operational flexibility which maintains the assumptions in the overpressure protection analysis.

The Frequency is specified in the Inservice Testing Program which requires the valves be subjected to a bench test during refueling outages. The Frequency is acceptable based on industry standards and operating history.

REFERENCES

1. ASME, Boiler and Pressure Vessel Code, Section III.

2. UFSAR, Section 5.2.2.1.3.

3. UFSAR, Chapter 15.

B 3.4 REACTOR COOLANT SYSTEM (RCS)

B 3.4.5 RCS Operational LEAKAGE

BASES

BACKGROUND

The RCS includes systems and components that contain or transport the coolant to or from the reactor core. The pressure containing components of the RCS and the portions of connecting systems out to and including the isolation valves define the reactor coolant pressure boundary (RCPB). The joints of the RCPB components are welded or bolted.

During plant life, the joint and valve interfaces can produce varying amounts of reactor coolant LEAKAGE, through either normal operational wear or mechanical deterioration. Limits on RCS operational LEAKAGE are required to ensure appropriate action is taken before the integrity of the RCPB is impaired. This LCO specifies the types and limits of LEAKAGE. This protects the RCS pressure boundary described in 10 CFR 50.2, 10 CFR 50.55a(c), and GDC 55 of 10 CFR 50, Appendix A (Refs. 1, 2, and 3).

The safety significance of leaks from the RCPB varies widely depending on the source, rate, and duration. Therefore, detection of LEAKAGE in the drywell is necessary. Methods for quickly separating the identified LEAKAGE from the unidentified LEAKAGE are necessary to provide the operators quantitative information to permit them to take corrective action should a leak occur detrimental to the safety of the facility or the public.

A limited amount of leakage inside the drywell is expected from auxiliary systems that cannot be made 100% leaktight. Leakage from these systems should be detected and isolated from the drywell atmosphere, if possible, so as not to mask RCS operational LEAKAGE detection.

This LCO deals with protection of the RCPB from degradation and the core from inadequate cooling, in addition to preventing the accident analyses radiation release assumptions from being exceeded. The consequences of violating this LCO include the possibility of a loss of coolant accident.

(continued)

BASES (continued)

APPLICABLE SAFETY ANALYSES

The allowable RCS operational LEAKAGE limits are based on the predicted and experimentally observed behavior of pipe cracks. The normally expected background LEAKAGE due to equipment design and the detection capability of the instrumentation for determining system LEAKAGE were also considered. The evidence from experiments suggests, for LEAKAGE even greater than the specified unidentified LEAKAGE limits, the probability is small that the imperfection or crack associated with such LEAKAGE would grow rapidly.

The unidentified LEAKAGE flow limit allows time for corrective action before the RCPB could be significantly compromised. The 5 gpm limit is a small fraction of the calculated flow from a critical crack in the primary system piping. Crack behavior from experimental programs (Refs. 4 and 5) shows leak rates of hundreds of gallons per minute will precede crack instability (Ref. 6).

The low limit on increase in unidentified LEAKAGE assumes a failure mechanism of intergranular stress corrosion cracking (IGSCC) that produces tight cracks. This flow increase limit is capable of providing an early warning of such deterioration.

No applicable safety analysis assumes the total LEAKAGE limit. The total LEAKAGE limit considers RCS inventory makeup capability and drywell sump capacity.

RCS operational LEAKAGE satisfies Criterion 2 of 10 CFR 50.36(c)(2)(ii).

LCO

RCS operational LEAKAGE shall be limited to:

a. Pressure Boundary LEAKAGE

No pressure boundary LEAKAGE is allowed, being indicative of material degradation. LEAKAGE of this type is unacceptable as the leak itself could cause further deterioration, resulting in higher LEAKAGE. Violation of this LCO could result in continued degradation of the RCPB. LEAKAGE past seals and gaskets is not pressure boundary LEAKAGE.

(continued)

BASES

LCO (continued)

b. Unidentified LEAKAGE

Five gpm of unidentified LEAKAGE is allowed as a reasonable minimum detectable amount that the drywell atmosphere monitoring, drywell sump flow monitoring, and drywell air cooler condensate flow rate monitoring equipment can detect within a reasonable time period. Violation of this LCO could result in continued degradation of the RCPB.

c. Total LEAKAGE

The total LEAKAGE limit is based on a reasonable minimum detectable amount. The limit also accounts for LEAKAGE from known sources (identified LEAKAGE). Violation of this LCO indicates an unexpected amount of LEAKAGE and, therefore, could indicate new or additional degradation in an RCPB component or system.

d. Unidentified LEAKAGE Increase

An unidentified LEAKAGE increase of > 2 gpm within the previous 24 hour period indicates a potential flaw in the RCPB and must be quickly evaluated to determine the source and extent of the LEAKAGE. The increase is measured relative to the steady state value; temporary changes in LEAKAGE rate as a result of transient conditions (e.g., startup) are not considered. As such, the 2 gpm increase limit is only applicable in MODE 1 when operating pressures and temperatures are established. Violation of this LCO could result in continued degradation of the RCPB.

APPLICABILITY

In MODES 1, 2, and 3, the RCS operational LEAKAGE LCO applies because the potential for RCPB LEAKAGE is greatest when the reactor is pressurized.

In MODES 4 and 5, RCS operational LEAKAGE limits are not required since the reactor is not pressurized and stresses in the RCPB materials and potential for LEAKAGE are reduced.

(continued)

BASES (continued)

ACTIONS

A.1

With RCS unidentified or total LEAKAGE greater than the limits, actions must be taken to reduce the leak. Because the LEAKAGE limits are conservatively below the LEAKAGE that would constitute a critical crack size, 4 hours is allowed to reduce the LEAKAGE rates before the reactor must be shut down. If an unidentified LEAKAGE has been identified and quantified, it may be reclassified and considered as identified LEAKAGE. However, the total LEAKAGE limit would remain unchanged.

B.1 and B.2

An unidentified LEAKAGE increase of > 2 gpm within a 24 hour period is an indication of a potential flaw in the RCPB and must be quickly evaluated. Although the increase does not necessarily violate the absolute unidentified LEAKAGE limit, certain susceptible components must be determined not to be the source of the LEAKAGE increase within the required Completion Time. For an unidentified LEAKAGE increase greater than required limits, an alternative to reducing LEAKAGE increase to within limits (i.e., reducing the leakage rate such that the current rate is less than the "2 gpm increase in the previous 24 hours" limit; either by isolating the source or other possible methods) is to verify the source of the unidentified leakage increase is not material susceptible to IGSCC.

The 4 hour Completion Time is needed to properly reduce the LEAKAGE increase or verify the source before the reactor must be shut down.

C.1 and C.2

If any Required Action and associated Completion Time of Condition A or B is not met or if pressure boundary LEAKAGE exists, the plant must be brought to a MODE in which the LCO does not apply. To achieve this status, the plant must be brought to MODE 3 within 12 hours and to MODE 4 within 36 hours. The allowed Completion Times are reasonable, based on operating experience, to reach the required plant conditions from full power conditions in an orderly manner and without challenging plant systems.

(continued)

BASES (continued)

SURVEILLANCE REQUIREMENTS

SR 3.4.5.1

The RCS LEAKAGE is monitored by a variety of instruments designed to provide alarms when LEAKAGE is indicated and to quantify the various types of LEAKAGE. Leakage detection instrumentation is discussed in more detail in the Bases for LCO 3.4.7, "RCS Leakage Detection Instrumentation." Sump level and flow rate are typically monitored to determine actual LEAKAGE rates. However, any method may be used to quantify LEAKAGE provided the method has suitable sensitivity to satisfy the requirements of LCO 3.4.5. In conjunction with alarms and other administrative controls, a 12 hour Frequency for this Surveillance is appropriate for identifying changes in LEAKAGE and for tracking required trends (Ref. 7).

REFERENCES

1. 10 CFR 50.2.

2. 10 CFR 50.55a(c).

3. 10 CFR 50, Appendix A, GDC 55.

4. GEAP-5620, "Failure Behavior in ASTM A106 B Pipes Containing Axial Through-Wall Flaws," April 1968.

5. NUREG-75/067, "Investigation and Evaluation of Cracking in Austenitic Stainless Steel Piping of Boiling Water Reactor Plants," October 1975.

6. UFSAR, Section 5.2.5.5.2.

7. Generic Letter 88-01, Supplement 1, February 1992.

B 3.4 REACTOR COOLANT SYSTEM (RCS)

B 3.4.6 RCS Pressure Isolation Valve (PIV) Leakage

BASES

BACKGROUND

The function of RCS PIVs is to separate the high pressure RCS from an attached low pressure system. This protects the RCS pressure boundary described in 10 CFR 50.2, 10 CFR 50.55a(c), and GDC 55 of 10 CFR 50, Appendix A (Refs. 1, 2, and 3). PIVs are designed to meet the requirements of Reference 4. During their lives, these valves can produce varying amounts of reactor coolant leakage through either normal operational wear or mechanical deterioration.

The RCS PIV LCO allows RCS high pressure operation when leakage through these valves exists in amounts that do not compromise safety. The PIV leakage limit applies to each individual valve. Leakage through these valves is not included in any allowable LEAKAGE specified in LCO 3.4.5, "RCS Operational LEAKAGE."

Although this Specification provides a limit on allowable PIV leakage rate, its main purpose is to prevent overpressure failure of the low pressure portions of connecting systems. The leakage limit is an indication that the PIVs between the RCS and the connecting systems are degraded or degrading. PIV leakage could lead to overpressure of the low pressure piping or components. Failure consequences could be a loss of coolant accident (LOCA) outside of containment, an unanalyzed accident which could degrade the ability for low pressure injection.

A study (Ref. 5) evaluated various PIV configurations to determine the probability of intersystem LOCAs. This study concluded that periodic leakage testing of the PIVs can substantially reduce intersystem LOCA probability.

PIVs are provided to isolate the RCS from the following connected systems:

a. Residual Heat Removal (RHR) System;

b. Low Pressure Core Spray System;

(continued)

BASES

BACKGROUND (continued)

c. High Pressure Core Spray System; and

d. Reactor Core Isolation Cooling System.

The PIVs are listed in the Technical Requirements Manual (Ref. 6).

APPLICABLE SAFETY ANALYSES

Reference 5 evaluated various PIV configurations, leakage testing of the valves, and operational changes to determine the effect on the probability of intersystem LOCAs. This study concluded that periodic leakage testing of the PIVs can substantially reduce the probability of an intersystem LOCA.

PIV leakage is not considered in any Design Basis Accident analyses. This Specification provides for monitoring the condition of the reactor coolant pressure boundary (RCPB) to detect PIV degradation that has the potential to cause a LOCA outside of containment.

RCS PIV leakage satisfies Criterion 2 of 10 CFR 50.36(c)(2)(ii).

LCO

RCS PIV leakage is leakage into closed systems connected to the RCS. Isolation valve leakage is usually on the order of drops per minute. Leakage that increases significantly suggests that something is operationally wrong and corrective action must be taken. Violation of this LCO could result in continued degradation of a PIV, which could lead to overpressurization of a low pressure system and the loss of the integrity of a fission product barrier.

The LCO PIV leakage limit is 0.5 gpm per nominal inch of valve size with a maximum limit of 5 gpm (Ref. 4).

Reference 7 permits leakage testing at a lower pressure differential than between the specified maximum RCS pressure and the normal pressure of the connected system during RCS operation (the maximum pressure differential). The observed rate may be adjusted to the maximum pressure differential by assuming leakage is directly proportional to the pressure differential to the one-half power.

(continued)

BASES (continued)

APPLICABILITY

In MODES 1, 2, and 3, this LCO applies because the PIV leakage potential is greatest when the RCS is pressurized. In MODE 3, valves in the RHR flowpath are not required to meet the requirements of this LCO when in, or during transition to or from, the RHR shutdown cooling mode of operation.

In MODES 4 and 5, leakage limits are not provided because the lower reactor coolant pressure results in a reduced potential for leakage and for a LOCA outside the containment. Accordingly, the potential for the consequences of reactor coolant leakage is far lower during these MODES.

ACTIONS

The ACTIONS are modified by two Notes. Note 1 has been provided to modify the ACTIONS related to RCS PIV flow paths. Section 1.3, Completion Times, specifies once a Condition has been entered, subsequent divisions, subsystems, components or variables expressed in the Condition, discovered to be inoperable or not within limits, will not result in separate entry into the Condition. Section 1.3 also specifies Required Actions of the Condition continue to apply for each additional failure, with Completion Times based on initial entry into the Condition. However, the Required Actions for the Condition of RCS PIV leakage limits exceeded provide appropriate compensatory measures for separate, affected RCS PIV flow paths. As such, a Note has been provided that allows separate Condition entry for each affected RCS PIV flow path. Note 2 requires an evaluation of affected systems if a PIV is inoperable. The leakage may have affected system OPERABILITY, or isolation of a leaking flow path with an alternate valve may have degraded the ability of the interconnected system to perform its safety function. As a result, the applicable Conditions and Required Actions for systems made inoperable by PIVs must be entered. This ensures appropriate remedial actions are taken, if necessary, for the affected systems.

A.1 and A.2

If leakage from one or more RCS PIVs is not within limit, the flow path must be isolated by at least one closed

(continued)

BASES

ACTIONS

A.1 and A.2 (continued)

manual, de-activated automatic, or check valve within 4 hours. Required Action A.1 and Required Action A.2 are modified by a Note stating that the valves used for isolation must meet the same leakage requirements as the PIVs and must be on the RCPB or the high pressure portion of the system.

Four hours provides time to reduce leakage in excess of the allowable limit and to isolate the flow path if leakage cannot be reduced while corrective actions to reseat the leaking PIVs are taken. The 4 hours allows time for these actions and restricts the time of operation with leaking valves.

Required Action A.2 specifies that the double isolation barrier of two valves be restored by closing another valve qualified for isolation or restoring one leaking PIV. The 72 hour Completion Time after exceeding the limit considers the time required to complete the Required Action, the low probability of a second valve failing during this time period, and the low probability of a pressure boundary rupture of the low pressure ECCS piping when overpressurized to reactor pressure (Ref. 7).

B.1 and B.2

If leakage cannot be reduced or the system isolated, the plant must be brought to a MODE in which the LCO does not apply. To achieve this status, the plant must be brought to MODE 3 within 12 hours and to MODE 4 within 36 hours. This action may reduce the leakage and also reduces the potential for a LOCA outside the containment. The Completion Times are reasonable, based on operating experience, to achieve the required plant conditions from full power conditions in an orderly manner and without challenging plant systems.

SURVEILLANCE REQUIREMENTS

SR 3.4.6.1

Performance of leakage testing on each RCS PIV is required to verify that leakage is below the specified limit and to identify each leaking valve. The leakage limit of 0.5 gpm

(continued)

BASES

SURVEILLANCE REQUIREMENTS

SR 3.4.6.1 (continued)

per inch of nominal valve diameter up to 5 gpm maximum applies to each valve. Leakage testing requires a stable pressure condition. As stated in the LCO section of the Bases, the test pressure may be at a lower pressure than the maximum pressure differential (at the maximum pressure of 1050 psig) provided the observed leakage rate is adjusted in accordance with Reference 4. For the two PIVs tested in series, the leakage requirement applies to each valve individually and not to the combined leakage across both valves (i.e., the leakage acceptance criteria is the criteria for one valve to account for the condition where all of the leakage is through one valve). If the PIVs are not individually leakage tested, one valve may have failed completely and not be detected if the other valve in series meets the leakage requirement. In this situation, the protection provided by redundant valves would be lost.

The Frequency required by the Inservice Testing Program is within the ASME Code, Section XI, Frequency requirement and is based on the need to perform this Surveillance under the conditions that apply during an outage and the potential for an unplanned transient if the Surveillance were performed with the reactor at power.

This SR is modified by a Note that states the leakage Surveillance is only required to be performed in MODES 1 and 2. Entry into MODE 3 is permitted for leakage testing at high differential pressures with stable conditions not possible in the lower MODES.

REFERENCES

1. 10 CFR 50.2.

2. 10 CFR 50.55a(c).

3. 10 CFR 50, Appendix A, GDC 55.

4. ASME, Boiler and Pressure Vessel Code, Section XI.

5. NUREG-0677, "The Probability of Intersystem LOCA: Impact Due to Leak Testing and Operational Changes," May 1980.

(continued)

BASES

REFERENCES (continued)

6. Technical Requirements Manual.

7. NEDC-31339, "BWR Owners Group Assessment of Emergency Core Cooling System Pressurization in Boiling Water Reactors," November 1986.

B 3.4 REACTOR COOLANT SYSTEM (RCS)

B 3.4.7 RCS Leakage Detection Instrumentation

BASES

BACKGROUND

GDC 30 of 10 CFR 50, Appendix A (Ref. 1), requires means for detecting and, to the extent practical, identifying the location of the source of RCS LEAKAGE. Regulatory Guide 1.45 (Ref. 2) describes acceptable methods for selecting leakage detection systems.

Limits on LEAKAGE from the reactor coolant pressure boundary (RCPB) are required so that appropriate action can be taken before the integrity of the RCPB is impaired (Ref. 2). Leakage detection systems for the RCS are provided to alert the operators when leakage rates above normal background levels are detected and also to supply quantitative measurement of rates. The Bases for LCO 3.4.5, "RCS Operational LEAKAGE," discuss the limits on RCS LEAKAGE rates.

Systems for separating the LEAKAGE of an identified source from an unidentified source are necessary to provide prompt and quantitative information to the operators to permit them to take immediate corrective action.

LEAKAGE from the RCPB inside the drywell is detected by at least one of three independently monitored variables, such as drywell air cooler condensate flow rate, sump flow rate, and drywell gaseous and particulate radioactivity levels. The primary means of quantifying LEAKAGE in the drywell is the drywell floor drain sump flow monitoring system.

The drywell floor drain sump flow monitoring system monitors the LEAKAGE collected in the floor drain sump. This unidentified LEAKAGE consists of LEAKAGE from control rod drives, valve flanges or packings, floor drains, the closed cooling water subsystems, and drywell air cooling unit condensate drains, and any LEAKAGE not collected in the drywell equipment drain sump. The drywell floor drain sump has a weir level transmitter that supplies floor drain sump fill-up rate flow indication in the main control room.

(continued)

BASES

BACKGROUND (continued)

The floor drain sump has level switches that start and stop the sump pumps when required. The sump pump which is selected Lead starts on a high level in the sump. The other pump starts, and a control room alarm is annunciated, if the sump level reaches the high-high level. The pumps stop when low level is reached in the sump. A timer starts each time the first sump pump starts. A second timer starts when the pump is stopped. If the pump takes longer than a given time to pump down the sump, or if the pump starts too soon after the previous pumpdown, an alarm is sounded in the control room indicating a higher than normal sump fill-up rate. A flow monitor in the discharge line of the drywell floor drain sump pumps provides flow input to a flow totalizer which is indicated in the control room. This flow totalizer can be used to quantify the amount of sump inputs.

The drywell air monitoring systems continuously monitor the drywell atmosphere for airborne particulate and gaseous radioactivity. A sudden increase of radioactivity, which may be attributed to RCPB steam or reactor water LEAKAGE, is annunciated in the control room. The drywell atmosphere particulate and gaseous radioactivity monitoring systems are not capable of quantifying leakage rates, but are sensitive enough to indicate increased LEAKAGE rates of 1 gpm within 1 hour. Larger changes in LEAKAGE rates are detected in proportionally shorter times (Ref. 3).

Condensate from the drywell coolers is routed to the drywell floor drain sump and is monitored by a flow transmitter that provides indication and alarms in the control room. This drywell air cooler condensate flow rate monitoring system serves as an added indicator, but not quantifier, of RCS unidentified LEAKAGE.

APPLICABLE SAFETY ANALYSES

A threat of significant compromise to the RCPB exists if the barrier contains a crack that is large enough to propagate rapidly. LEAKAGE rate limits are set low enough to detect the LEAKAGE emitted from a single crack in the RCPB (Refs. 4 and 5). Each of the leakage detection systems inside the drywell is designed with the capability of detecting LEAKAGE less than the established LEAKAGE rate limits and providing appropriate alarm of excess LEAKAGE in the control room.

A control room alarm allows the operators to evaluate the significance of the indicated LEAKAGE and, if necessary,

(continued)

BASES

APPLICABLE SAFETY ANALYSES (continued)

shut down the reactor for further investigation and corrective action. The allowed LEAKAGE rates are well below the rates predicted for critical crack sizes (Ref. 6). Therefore, these actions provide adequate response before a significant break in the RCPB can occur.

RCS leakage detection instrumentation satisfies Criterion 1 of 10 CFR 50.36(c)(2)(ii).

LCO

The drywell floor drain sump flow monitoring system is required to quantify the unidentified LEAKAGE from the RCS. Thus, for the system to be considered OPERABLE, the floor drain sump fillup rate monitor portion of the system must be OPERABLE. The other monitoring systems provide early alarms to the operators so closer examination of other detection systems will be made to determine the extent of any corrective action that may be required. With the leakage detection systems inoperable, monitoring for LEAKAGE in the RCPB is degraded.

APPLICABILITY

In MODES 1, 2, and 3, leakage detection systems are required to be OPERABLE to support LCO 3.4.5. This Applicability is consistent with that for LCO 3.4.5.

ACTIONS

A.1

With the drywell floor drain sump flow monitoring system inoperable, no other form of sampling can provide the equivalent information to quantify leakage. However, the drywell atmospheric activity monitor and the drywell air cooler condensate flow rate monitor will provide indications of changes in leakage.

With the drywell floor drain sump flow monitoring system inoperable, but with RCS unidentified and total LEAKAGE being determined every 12 hours (SR 3.4.5.1), operation may continue for 30 days. The 30 day Completion Time of Required Action A.1 is acceptable, based on operating experience, considering the multiple forms of leakage detection that are still available. Required Action A.1 is modified by a Note that states that the provisions of LCO 3.0.4 are not applicable. As a result, a MODE change is allowed when the drywell floor drain sump flow monitoring

(continued)

BASES

ACTIONS

A.1 (continued)

system is inoperable. This allowance is provided because other instrumentation is available to monitor RCS leakage.

B.1

With both gaseous and particulate drywell atmospheric monitoring channels inoperable (i.e., the required drywell atmospheric monitoring system), grab samples of the drywell atmosphere shall be taken and analyzed to provide periodic leakage information. Provided a sample is obtained and analyzed every 12 hours, the plant may continue operation since at least one other form of drywell leakage detection (i.e., air cooler condensate flow rate monitor) is available.

The 12 hour interval provides periodic information that is adequate to detect LEAKAGE.

C.1

With the required drywell air cooler condensate flow rate monitoring system inoperable, SR 3.4.7.1 is performed every 8 hours to provide periodic information of activity in the drywell at a more frequent interval than the routine Frequency of SR 3.4.7.1. The 8 hour interval provides periodic information that is adequate to detect LEAKAGE and recognizes that other forms of leakage detection are available. However, this Required Action is modified by a Note that allows this action to be not applicable if the required drywell atmospheric monitoring system is inoperable. Consistent with SR 3.0.1, Surveillances are not required to be performed on inoperable equipment.

D.1 and D.2

With both the gaseous and particulate drywell atmospheric monitor channels and the drywell air cooler condensate flow rate monitor inoperable, the only means of detecting LEAKAGE is the drywell floor drain sump flow monitor. This

(continued)

BASES

ACTIONS

D.1 and D.2 (continued)

Condition does not provide the required diverse means of leakage detection. The Required Action is to restore either of the inoperable monitors to OPERABLE status within 30 days to regain the intended leakage detection diversity. The 30 day Completion Time ensures that the plant will not be operated in a degraded configuration for a lengthy time period. The Required Actions are modified by a Note that states that the provisions of LCO 3.0.4 are not applicable. As a result, a MODE change is allowed when both the gaseous and particulate primary containment atmospheric monitoring channels and air cooler condensate flow rate are inoperable. This allowance is provided because other instrumentation is available to monitor RCS leakage.

E.1 and E.2

If any Required Action of Condition A, B, C, or D cannot be met within the associated Completion Time, the plant must be brought to a MODE in which the LCO does not apply. To achieve this status, the plant must be brought to at least MODE 3 within 12 hours and to MODE 4 within 36 hours. The allowed Completion Times are reasonable, based on operating experience, to reach the required plant conditions in an orderly manner and without challenging plant systems.

F.1

With all required monitors inoperable, no required automatic means of monitoring LEAKAGE are available, and immediate plant shutdown in accordance with LCO 3.0.3 is required.

SURVEILLANCE REQUIREMENTS

The Surveillances are modified by a Note to indicate that when a channel is placed in an inoperable status solely for performance of required Surveillances, entry into associated Conditions and Required Actions may be delayed for up to 6 hours, provided the other required instrumentation (the drywell sump flow monitoring system, drywell atmospheric monitoring channel, or the drywell air cooler condensate flow monitoring system, as applicable) is OPERABLE. Upon

(continued)

BASES

SURVEILLANCE REQUIREMENTS (continued)

completion of the Surveillance, or expiration of the 6 hour allowance, the channel must be returned to OPERABLE status or the applicable Condition entered and Required Actions taken. The 6 hour testing allowance is acceptable since it does not significantly reduce the probability of properly monitoring RCS leakage.

SR 3.4.7.1

This SR requires the performance of a CHANNEL CHECK of the required drywell atmospheric monitoring system. The check gives reasonable confidence that the channel is operating properly. The Frequency of 12 hours is based on instrument reliability and is reasonable for detecting off normal conditions.

SR 3.4.7.2

This SR requires the performance of a CHANNEL FUNCTIONAL TEST of the required RCS leakage detection instrumentation. The test ensures that the monitors can perform their function in the desired manner. The test also verifies the alarm function and relative accuracy of the instrument string. A successful test of the required contact(s) of a channel relay may be performed by the verification of the change of state of a single contact of the relay. This clarifies what is an acceptable CHANNEL FUNCTIONAL TEST of a relay. This is acceptable because all of the other required contacts of the relay are verified by other Technical Specifications and non-Technical Specifications tests at least once per refueling interval with applicable extensions. The Frequency of 31 days considers instrument reliability, and operating experience has shown it proper for detecting degradation.

SR 3.4.7.3

This SR requires the performance of a CHANNEL CALIBRATION of the required RCS leakage detection instrumentation channels. The calibration verifies the accuracy of the instrument string, including the instruments located inside the

(continued)

BASES

SURVEILLANCE REQUIREMENTS

SR 3.4.7.3 (continued)

drywell. The Frequency of 24 months is a typical refueling cycle and considers channel reliability. Operating experience has proven this Frequency is acceptable.

REFERENCES

1. 10 CFR 50, Appendix A, GDC 30.

2. Regulatory Guide 1.45, May 1973.

3. UFSAR, Section 5.2.5.1.1.

4. GEAP-5620, "Failure Behavior in ASTM A106B Pipes Containing Axial Through-Wall Flaws," April 1968.

5. NUREG-75/067, "Investigation and Evaluation of Cracking in Austenitic Stainless Steel Piping of Boiling Water Reactor Plants," October 1975.

6. UFSAR, Section 5.2.5.5.2.

B 3.4 REACTOR COOLANT SYSTEM (RCS)

B 3.4.8 RCS Specific Activity

BASES

BACKGROUND

During circulation, the reactor coolant acquires radioactive materials due to release of fission products from fuel leaks into the coolant and activation of corrosion products in the reactor coolant. These radioactive materials in the coolant can plate out in the RCS, and, at times, an accumulation will break away to spike the normal level of radioactivity. The release of coolant during a Design Basis Accident (DBA) could send radioactive materials into the environment.

Limits on the maximum allowable level of radioactivity in the reactor coolant are established to ensure, in the event of a release of any radioactive material to the environment during a DBA, radiation doses are maintained within the limits of 10 CFR 100 (Ref. 1).

This LCO contains iodine specific activity limits. The iodine isotopic activities per gram of reactor coolant are expressed in terms of a DOSE EQUIVALENT I-131. The allowable levels are intended to limit the 2 hour radiation dose to an individual at the site boundary to a small fraction of the 10 CFR 100 limit.

APPLICABLE SAFETY ANALYSES

Analytical methods and assumptions involving radioactive material in the primary coolant are presented in the UFSAR (Ref. 2). The specific activity in the reactor coolant (the source term) is an initial condition for evaluation of the consequences of an accident due to a main steam line break (MSLB) outside containment. No fuel damage is postulated in the MSLB accident, and the release of radioactive material to the environment is assumed to end when the main steam isolation valves (MSIVs) close completely.

This MSLB release forms the basis for determining offsite doses (Ref. 2). The limits on the specific activity of the primary coolant ensure that the 2 hour thyroid and whole body doses at the site boundary, resulting from an MSLB

(continued)

BASES

APPLICABLE SAFETY ANALYSES (continued)

outside containment during steady state operation, will not exceed 10% of the dose guidelines of 10 CFR 100.

The limit on specific activity is a value from a parametric evaluation of typical site locations. This limit is conservative because the evaluation considered more restrictive parameters than for a specific site, such as the location of the site boundary and the meteorological conditions of the site.

RCS specific activity satisfies Criterion 2 of 10 CFR 50.36(c)(2)(ii).

LCO

The specific iodine activity is limited to $\leq$ 0.2 μCi/gm DOSE EQUIVALENT I-131. This limit ensures the source term assumed in the safety analysis for the MSLB is not exceeded, so any release of radioactivity to the environment during an MSLB is less than a small fraction of the 10 CFR 100 limits.

APPLICABILITY

In MODE 1, and MODES 2 and 3 with any main steam line not isolated, limits on the primary coolant radioactivity are applicable since there is an escape path for release of radioactive material from the primary coolant to the environment in the event of an MSLB outside of primary containment.

In MODES 2 and 3 with the main steam lines isolated, such limits do not apply since an escape path does not exist. In MODES 4 and 5, no limits are required since the reactor is not pressurized and the potential for leakage is reduced.

ACTIONS

A.1 and A.2

When the reactor coolant specific activity exceeds the LCO DOSE EQUIVALENT I-131 limit, but is $\leq$ 4.0 μCi/gm, samples must be analyzed for DOSE EQUIVALENT I-131 at least once every 4 hours. In addition, the specific activity must be restored to the LCO limit within 48 hours. The Completion Time of once every 4 hours is based on the time needed to take and analyze a sample. The 48 hour Completion Time to

(continued)

BASES

ACTIONS

A.1 and A.2 (continued)

restore the activity level provides a reasonable time for temporary coolant activity increases (iodine spikes or crud bursts) to be cleaned up with the normal processing systems.

A note to the Required Action of Condition A excludes the MODE change restriction of LCO 3.0.4. This exception allows entry into the applicable MODE(S) while relying on the ACTIONS even though the ACTIONS may eventually require plant shutdown. This exception is acceptable due to the significant conservatism incorporated into the specific activity limit, the low probability of an event which is limiting due to exceeding this limit, and the ability to restore transient specific activity excursions while the plant remains at, or proceeds to power operation.

B.1, B.2.1, B.2.2.1, and B.2.2.2

If the DOSE EQUIVALENT I-131 cannot be restored to $\leq$ 0.2 µCi/gm within 48 hours, or if at any time it is > 4.0 µCi/gm, it must be determined at least every 4 hours and all the main steam lines must be isolated within 12 hours. Isolating the main steam lines precludes the possibility of releasing radioactive material to the environment in an amount that is more than a small fraction of the requirements of 10 CFR 100 during a postulated MSLB accident.

Alternately, the plant can be brought to MODE 3 within 12 hours and to MODE 4 within 36 hours. This option is provided for those instances when isolation of main steam lines is not desired (e.g., due to the decay heat loads). In MODE 4, the requirements of the LCO are no longer applicable.

The Completion Time of once every 4 hours is the time needed to take and analyze a sample. The 12 hour Completion Time is reasonable, based on operating experience, to isolate the main steam lines in an orderly manner and without challenging plant systems. Also, the allowed Completion Times for Required Actions B.2.2.1 and B.2.2.2 for bringing the plant to MODES 3 and 4 are reasonable, based on

(continued)

BASES

ACTIONS

B.1, B.2.1, B.2.2.1, and B.2.2.2 (continued)

operating experience, to reach the required plant conditions from full power conditions in an orderly manner and without challenging plant systems.

SURVEILLANCE REQUIREMENTS

SR 3.4.8.1

This Surveillance is performed to ensure iodine remains within limit during normal operation. The 7 day Frequency is adequate to trend changes in the iodine activity level.

This SR is modified by a Note that requires this Surveillance to be performed only in MODE 1 because the level of fission products generated in other MODES is much less.

REFERENCES

1. 10 CFR 100.11.

2. UFSAR, Section 15.6.4.5.

B 3.4 REACTOR COOLANT SYSTEM (RCS)

B 3.4.9 Residual Heat Removal (RHR) Shutdown Cooling System—Hot Shutdown

BASES

BACKGROUND

Irradiated fuel in the shutdown reactor core generates heat during the decay of fission products and increases the temperature of the reactor coolant. This decay heat must be removed to reduce the temperature of the reactor coolant to ≤ 200°F in preparation for performing Refueling or Cold Shutdown maintenance operations, or the decay heat must be removed for maintaining the reactor in the Hot Shutdown condition.

The two redundant, manually controlled shutdown cooling subsystems of the RHR System provide decay heat removal. Each loop consists of a motor driven pump, a heat exchanger, and associated piping and valves. Both loops have a common suction from the same recirculation loop. Each pump discharges the reactor coolant, after circulation through the respective heat exchanger, to the reactor via the associated recirculation loop. The RHR heat exchangers transfer heat to the Residual Heat Removal Service Water System (LCO 3.7.1, "Residual Heat Removal Service Water (RHRSW) System").

APPLICABLE SAFETY ANALYSES

Decay heat removal by the RHR System in the shutdown cooling mode is not required for mitigation of any event or accident evaluated in the safety analyses. Decay heat removal is, however, an important safety function that must be accomplished or core damage could result.

The RHR Shutdown Cooling System meets Criterion 4 of 10 CFR 50.36(c)(2)(ii).

LCO

Two RHR shutdown cooling subsystems are required to be OPERABLE, and, when no recirculation pump is in operation, one shutdown cooling subsystem must be in operation. An OPERABLE RHR shutdown cooling subsystem consists of one OPERABLE RHR pump, one heat exchanger, and the associated piping and valves. Each shutdown cooling subsystem is considered OPERABLE if it can be manually aligned (remote or

(continued)

BASES

LCO (continued)

local) in the shutdown cooling mode for removal of decay heat. In MODE 3, one RHR shutdown cooling subsystem can provide the required cooling, but two subsystems are required to be OPERABLE to provide redundancy. Operation of one subsystem can maintain or reduce the reactor coolant temperature as required. To ensure adequate core flow to allow for accurate average reactor coolant temperature monitoring, nearly continuous operation is required.

Note 1 permits both RHR shutdown cooling subsystems and recirculation pumps to not be in operation for a period of 2 hours in an 8 hour period. Note 2 allows one RHR shutdown cooling subsystem to be inoperable for up to 2 hours for performance of surveillance tests. These tests may be on the affected RHR System or on some other plant system or component that necessitates placing the RHR System in an inoperable status during the performance. This is permitted because the core heat generation can be low enough and the heatup rate slow enough to allow some changes to the RHR subsystems or other operations requiring RHR flow interruption and loss of redundancy.

APPLICABILITY

In MODE 3 with reactor vessel pressure below the RHR cut in permissive pressure (i.e., the actual pressure at which the interlock resets) the RHR Shutdown Cooling System must be OPERABLE and one RHR shutdown cooling subsystem shall be operated in the shutdown cooling mode to remove decay heat to reduce or maintain coolant temperature. With an RHR shutdown cooling subsystem not in operation, a recirculation pump is required to be in operation.

In MODES 1 and 2, and in MODE 3 with reactor vessel pressure greater than or equal to the RHR cut-in permissive pressure, this LCO is not applicable. Operation of the RHR System in the shutdown cooling mode is not allowed above this pressure because the RCS pressure may exceed the design pressure of the shutdown cooling piping. Decay heat removal at reactor pressures greater than or equal to the RHR cut-in permissive pressure is typically accomplished by condensing the steam in the main condenser. Additionally, in MODE 2, the OPERABILITY requirements for the Emergency Core Cooling Systems (ECCS) (LCO 3.5.1, "ECCS—Operating") do not allow placing the RHR shutdown cooling subsystem into operation.

(continued)

BASES

APPLICABILITY (continued)

The requirements for decay heat removal in MODES 4 and 5 are discussed in LCO 3.4.10, "Residual Heat Removal (RHR) Shutdown Cooling System—Cold Shutdown"; LCO 3.9.8, "Residual Heat Removal (RHR)—High Water Level"; and LCO 3.9.9, "Residual Heat Removal (RHR)—Low Water Level."

ACTIONS

A Note to the ACTIONS excludes the MODE change restriction of LCO 3.0.4. This exception allows entry into the applicable MODE while relying on the ACTIONS even though the ACTIONS may eventually require plant shutdown. This exception is acceptable due to the redundancy of the OPERABLE subsystems, the low pressure at which the plant is operating, the low probability of an event occurring during operation in this condition, and the availability of alternate methods of decay heat removal capability.

A second Note has been provided to modify the ACTIONS related to RHR shutdown cooling subsystems. Section 1.3, Completion Times, specifies once a Condition has been entered, subsequent divisions, subsystems, components or variables expressed in the Condition, discovered to be inoperable or not within limits, will not result in separate entry into the Condition. Section 1.3 also specifies Required Actions of the Condition continue to apply for each additional failure, with Completion Times based on initial entry into the Condition. However, the Required Actions for inoperable shutdown cooling subsystems provide appropriate compensatory measures for separate inoperable shutdown cooling subsystems. As such, a Note has been provided that allows separate Condition entry for each inoperable RHR shutdown cooling subsystem.

A.1, A.2, and A.3

With one RHR shutdown cooling subsystem inoperable for decay heat removal, except as permitted by LCO Note 2, the inoperable subsystem must be restored to OPERABLE status without delay. In this condition, the remaining OPERABLE subsystem can provide the necessary decay heat removal. The overall reliability is reduced, however, because a single failure in the OPERABLE subsystem could result in reduced RHR shutdown cooling capability. Therefore an alternate method of decay heat removal must be provided.

(continued)

BASES

ACTIONS

A.1, A.2, and A.3 (continued)

With both RHR shutdown cooling subsystems inoperable, an alternate method of decay heat removal must be provided in addition to that provided for the initial RHR shutdown cooling subsystem inoperability. This re-establishes backup decay heat removal capabilities, similar to the requirements of the LCO. The 1 hour Completion Time is based on the decay heat removal function and the probability of a loss of the available decay heat removal capabilities.

The required cooling capacity of the alternate method should be ensured by verifying (by calculation or demonstration) its capability to maintain or reduce temperature. Decay heat removal by ambient losses can be considered as, or contributing to, the alternate method capability. Alternate methods that can be used include (but are not limited to) the Condensate/Feed and Main Steam Systems or the Reactor Water Cleanup System (by itself or using feed and bleed in combination with the Control Rod Drive System or Condensate/Feed System), and a combination of an ECCS pump and S/RVs.

However, due to the potentially reduced reliability of the alternate methods of decay heat removal, it is also required to reduce the reactor coolant temperature to the point where MODE 4 is entered.

B.1, B.2, and B.3

With no RHR shutdown cooling subsystem and no recirculation pump in operation, except as is permitted by LCO Note 1, reactor coolant circulation by the RHR shutdown cooling subsystem or one recirculation pump must be restored without delay.

Until RHR or recirculation pump operation is re-established, an alternate method of reactor coolant circulation must be placed into service. This will provide the necessary circulation for monitoring coolant temperature. The 1 hour Completion Time is based on the coolant circulation function and is modified such that the 1 hour is applicable

(continued)

BASES

ACTIONS

B.1, B.2, and B.3 (continued)

separately for each occurrence involving a loss of coolant circulation. Furthermore, verification of the functioning of the alternate method must be reconfirmed every 12 hours thereafter. This will provide assurance of continued temperature monitoring capability.

During the period when the reactor coolant is being circulated by an alternate method (other than by the required RHR shutdown cooling subsystem or recirculation pump), the reactor coolant temperature and pressure must be periodically monitored to ensure proper function of the alternate method. The once per hour Completion Time is deemed appropriate.

SURVEILLANCE REQUIREMENTS

SR 3.4.9.1

This Surveillance verifies that one RHR shutdown cooling subsystem or recirculation pump is in operation and circulating reactor coolant. The required flow rate is determined by the flow rate necessary to provide sufficient decay heat removal capability. The Frequency of 12 hours is sufficient in view of other visual and audible indications available to the operator for monitoring the RHR subsystem in the control room.

This Surveillance is modified by a Note allowing sufficient time to align the RHR System for shutdown cooling operation after clearing the pressure interlock that isolates the system, or for placing a recirculation pump in operation. The Note takes exception to the requirements of the Surveillance being met (i.e., forced coolant circulation is not required for this initial 2 hour period), which also allows entry into the Applicability of this Specification in accordance with SR 3.0.4 since the Surveillance will not be "not met" at the time of entry into the Applicability.

REFERENCES

None.

B 3.4 REACTOR COOLANT SYSTEM (RCS)

B 3.4.10 Residual Heat Removal (RHR) Shutdown Cooling System—Cold Shutdown

BASES

BACKGROUND	Irradiated fuel in the shutdown reactor core generates heat during the decay of fission products and increases the temperature of the reactor coolant. This decay heat must be removed to maintain the temperature of the reactor coolant at ≤ 200°F in preparation for performing refueling maintenance operations, or the decay heat must be removed for maintaining the reactor in the Cold Shutdown condition. The two redundant, manually controlled shutdown cooling subsystems of the RHR System provide decay heat removal. Each loop consists of a motor driven pump, a heat exchanger, and associated piping and valves. Both loops have a common suction from the same recirculation loop. Each pump discharges the reactor coolant, after circulation through the respective heat exchanger, to the reactor via separate feedwater lines or to the reactor via the associated recirculation loop. The RHR heat exchangers transfer heat to the Residual Heat Removal Service Water (RHRSW) System.
APPLICABLE SAFETY ANALYSES	Decay heat removal by the RHR System in the shutdown cooling mode is not required for mitigation of any event or accident evaluated in the safety analyses. Decay heat removal is, however, an important safety function that must be accomplished or core damage could result. The RHR Shutdown Cooling System meets Criterion 4 of 10 CFR 50.36(c)(2)(ii).
LCO	Two RHR shutdown cooling subsystems are required to be OPERABLE, and, when no recirculation pump is in operation, one RHR shutdown cooling subsystem must be in operation. An OPERABLE RHR shutdown cooling subsystem consists of one OPERABLE RHR pump, one heat exchanger, the necessary portions of the RHRSW System and Ultimate Heat Sink capable of providing cooling to the heat exchanger, and the associated piping and valves. Each shutdown cooling

(continued)

BASES

LCO (continued)

subsystem is considered OPERABLE if it can be manually aligned (remote or local) in the shutdown cooling mode for removal of decay heat. In MODE 4, one RHR shutdown cooling subsystem can provide the required cooling, but two subsystems are required to be OPERABLE to provide redundancy. Operation of one subsystem can maintain and reduce the reactor coolant temperature as required. To ensure adequate core flow to allow for accurate average reactor coolant temperature monitoring, nearly continuous operation is required.

Note 1 allows both RHR shutdown cooling subsystems to be inoperable during hydrostatic testing. This is necessary since the RHR Shutdown Cooling System is not designed to operate at the Reactor Coolant System pressures achieved during hydrostatic testing. This is acceptable since adequate reactor coolant circulation will be achieved by operation of a reactor recirculation pump and since systems are available to control reactor coolant temperature. Note 2 permits both RHR shutdown cooling subsystems and recirculation pumps to not be in operation for a period of 2 hours in an 8 hour period. Note 3 allows one RHR shutdown cooling subsystem to be inoperable for up to 2 hours for performance of surveillance tests. These tests may be on the affected RHR System or on some other plant system or component that necessitates placing the RHR System in an inoperable status during the performance. This is permitted because the core heat generation can be low enough and the heatup rate slow enough to allow some changes to the RHR subsystems or other operations requiring RHR flow interruption and loss of redundancy.

APPLICABILITY

In MODE 4, the RHR Shutdown Cooling System must be OPERABLE and one RHR shutdown cooling subsystem shall be operated in the shutdown cooling mode to remove decay heat to maintain coolant temperature below 200°F. With an RHR shutdown cooling subsystem not in operation, a recirculation pump is required to be in operation.

In MODES 1 and 2, and in MODE 3 with reactor vessel pressure greater than or equal to the RHR cut-in permissive pressure, this LCO is not applicable. Operation of the RHR System in the shutdown cooling mode is not allowed above this

(continued)

BASES

APPLICABILITY (continued)

pressure because the RCS pressure may exceed the design pressure of the shutdown cooling piping. Decay heat removal at reactor pressures greater than or equal to the RHR cut-in permissive pressure is typically accomplished by condensing the steam in the main condenser. Additionally, in MODE 2 below this pressure, the OPERABILITY requirements for the Emergency Core Cooling Systems (ECCS) (LCO 3.5.1, "ECCS—Operating") do not allow placing the RHR shutdown cooling subsystem into operation.

The requirements for decay heat removal in MODE 3 below the cut-in permissive pressure and in MODE 5 are discussed in LCO 3.4.9, "Residual Heat Removal (RHR) Shutdown Cooling System—Hot Shutdown"; LCO 3.9.8, "Residual Heat Removal (RHR)—High Water Level"; and LCO 3.9.9, "Residual Heat Removal (RHR)—Low Water Level."

ACTIONS

A Note has been provided to modify the ACTIONS related to RHR shutdown cooling subsystems. Section 1.3, Completion Times, specifies once a Condition has been entered, subsequent divisions, subsystems, components or variables expressed in the Condition, discovered to be inoperable or not within limits, will not result in separate entry into the Condition. Section 1.3 also specifies Required Actions of the Condition continue to apply for each additional failure, with Completion Times based on initial entry into the Condition. However, the Required Actions for inoperable shutdown cooling subsystems provided appropriate compensatory measures for separate inoperable shutdown cooling subsystems. As such, a Note has been provided that allows separate Condition entry for each inoperable RHR shutdown cooling subsystem.

A.1

With one of the two RHR shutdown cooling subsystems inoperable, except as permitted by LCO Notes 1 and 3, the remaining subsystem is capable of providing the required decay heat removal. However, the overall reliability is reduced. Therefore, an alternate method of decay heat removal must be provided. With both RHR shutdown cooling subsystems inoperable, an alternate method of decay heat

(continued)

BASES

ACTIONS

A.1 (continued)

removal must be provided in addition to that provided for the initial RHR shutdown cooling subsystem inoperability. This re-establishes backup decay heat removal capabilities, similar to the requirements of the LCO. The 1 hour Completion Time is based on the decay heat removal function and the probability of a loss of the available decay heat removal capabilities. Furthermore, verification of the functional availability of these alternate method(s) must be reconfirmed every 24 hours thereafter. This will provide assurance of continued heat removal capability.

The required cooling capacity of the alternate method should be ensured by verifying (by calculation or demonstration) its capability to maintain or reduce temperature. Decay heat removal by ambient losses can be considered as, or contributing to, the alternate method capability. Alternate methods that can be used include (but are not limited to) the Condensate/Feed and Main Steam Systems, the Reactor Water Cleanup System (by itself or using feed and bleed in combination with the Control Rod Drive System or Condensate/Feed System) and a combination of an ECCS pump and S/RVs.

B.1 and B.2

With no RHR shutdown cooling subsystem and no recirculation pump in operation, except as is permitted by LCO Notes 1 and 2, and until RHR or recirculation pump operation is re-established, an alternate method of reactor coolant circulation must be placed into service. This will provide the necessary circulation for monitoring coolant temperature. The 1 hour Completion Time is based on the coolant circulation function and is modified such that the 1 hour is applicable separately for each occurrence involving a loss of coolant circulation. Furthermore, verification of the functioning of the alternate method must be reconfirmed every 12 hours thereafter. This will provide assurance of continued temperature monitoring capability.

(continued)

BASES

ACTIONS

B.1 and B.2 (continued)

During the period when the reactor coolant is being circulated by an alternate method (other than by the required RHR shutdown cooling subsystem or recirculation pump), the reactor coolant temperature and pressure must be periodically monitored to ensure proper function of the alternate method. The once per hour Completion Time is deemed appropriate.

SURVEILLANCE REQUIREMENTS

SR 3.4.10.1

This Surveillance verifies that one RHR shutdown cooling subsystem or recirculation pump is in operation and circulating reactor coolant. The required flow rate is determined by the flow rate necessary to provide sufficient decay heat removal capability. The Frequency of 12 hours is sufficient in view of other visual and audible indications available to the operator for monitoring the RHR subsystem in the control room.

REFERENCES

None.

B 3.4 REACTOR COOLANT SYSTEM (RCS)

B 3.4.11 RCS Pressure and Temperature (P/T) Limits

BASES

BACKGROUND

All components of the RCS are designed to withstand effects of cyclic loads due to system pressure and temperature changes. These loads are introduced by startup (heatup) and shutdown (cooldown) operations, power transients, and reactor trips. This LCO limits the pressure and temperature changes during RCS heatup and cooldown, within the design assumptions and the stress limits for cyclic operation.

The Specification contains P/T limit curves for heatup, cooldown, inservice leak and hydrostatic testing, and criticality and also limits the maximum rate of change of reactor coolant temperature. The P/T limit curves are applicable for 32 effective full power years.

Each P/T limit curve defines an acceptable region for normal operation. The usual use of the curves is operational guidance during heatup or cooldown maneuvering, when pressure and temperature indications are monitored and compared to the applicable curve to determine that operation is within the allowable region.

The LCO establishes operating limits that provide a margin to brittle failure of the reactor vessel and piping of the reactor coolant pressure boundary (RCPB). The vessel is the component most subject to brittle failure. Therefore, the LCO limits apply mainly to the vessel.

10 CFR 50, Appendix G (Ref. 1), requires the establishment of P/T limits for material fracture toughness requirements of the RCPB materials. Reference 1 requires an adequate margin to brittle failure during normal operation, anticipated operational occurrences, and system hydrostatic tests. It mandates the use of the American Society of Mechanical Engineers (ASME) Code, Section III, Appendix G (Ref. 2).

The actual shift in the RT_{NDT} of the vessel material will be established periodically by removing and evaluating the irradiated reactor vessel material specimens, in accordance with ASTM E 185 (Ref. 3) and 10 CFR 50, Appendix H (Ref. 4). The operating P/T limit curves will be adjusted,

(continued)

BASES

BACKGROUND (continued)

as necessary, based on the evaluation findings and the recommendations of Reference 5.

The P/T limit curves are composite curves established by superimposing limits derived from stress analyses of those portions of the reactor vessel and head that are the most restrictive. At any specific pressure, temperature, and temperature rate of change, one location within the reactor vessel will dictate the most restrictive limit. Across the span of the P/T limit curves, different locations are more restrictive, and, thus, the curves are composites of the most restrictive regions.

The non-nuclear heatup and cooldown curve applies during heatups with non-nuclear heat (e.g., recirculation pump heat) and during cooldowns when the reactor is not critical (e.g., following a scram). The curve provides the minimum reactor vessel metal temperatures based on the most limiting vessel stress.

The P/T criticality limits include the Reference 1 requirement that they be at least 40°F above the non-critical heatup curve or the cooldown curve and not lower than the minimum permissible temperature for the inservice leak and hydrostatic testing.

The consequence of violating the LCO limits is that the RCS has been operated under conditions that can result in brittle failure of the RCPB, possibly leading to a nonisolable leak or loss of coolant accident. In the event these limits are exceeded, an evaluation must be performed to determine the effect on the structural integrity of the RCPB components. The ASME Code, Section XI, Appendix E (Ref. 6), provides a recommended methodology for evaluating an operating event that causes an excursion outside the limits.

APPLICABLE SAFETY ANALYSES

The P/T limits are not derived from Design Basis Accident (DBA) analyses. They are prescribed during normal operation to avoid encountering pressure, temperature, and temperature rate of change conditions that might cause undetected flaws to propagate and cause nonductile failure of the RCPB, a condition that is unanalyzed. Reference 7 approved the curves and limits required by this Specification. Since the

(continued)

BASES

APPLICABLE SAFETY ANALYSES (continued)

P/T limits are not derived from any DBA, there are no acceptance limits related to the P/T limits. Rather, the P/T limits are acceptance limits themselves since they preclude operation in an unanalyzed condition.

RCS P/T limits satisfy Criterion 2 of 10 CFR 50.36(c)(2)(ii).

LCO

The elements of this LCO are:

a. RCS pressure and temperature are within the limits specified in Figures 3.4.11-1, 3.4.11-2, 3.4.11-3, 3.4.11-4, 3.4.11-5, and 3.4.11-6 heatup and cooldown rates are ≤ 100°F in any 1 hour period during RCS heatup, cooldown, and inservice leak and hydrostatic testing, and the RCS temperature change during system leakage and hydrostatic testing is ≤ 20°F in any 1 hour period when the RCS temperature and pressure are not within the limits of Figure 3.4.11-2 and 3.4.11-5 as applicable;

b. The temperature difference between the reactor vessel bottom head coolant and the reactor pressure vessel (RPV) coolant is ≤ 145°F during recirculation pump startup in MODES 1, 2, 3, and 4;

c. The temperature difference between the reactor coolant in the respective recirculation loop and in the reactor vessel is ≤ 50°F during recirculation pump startup in MODES 1, 2, 3, and 4;

d. RCS pressure and temperature are within the applicable criticality limits specified in Figures 3.4.11-3 and 3.4.11-6, prior to achieving criticality; and

e. The reactor vessel flange and the head flange temperatures are ≥ 72°F for Unit 1 and ≥ 86°F for Unit 2 when tensioning the reactor vessel head bolting studs and when the reactor head is tensioned.

These limits define allowable operating regions and permit a large number of operating cycles while also providing a wide margin to nonductile failure.

(continued)

BASES

LCO (continued)

The rate of change of temperature limits control the thermal gradient through the vessel wall and are used as inputs for calculating the heatup, cooldown, and inservice leak and hydrostatic testing P/T limit curves. Thus, the LCO for the rate of change of temperature restricts stresses caused by thermal gradients and also ensures the validity of the P/T limit curves.

Violation of the limits places the reactor vessel outside of the bounds of the stress analyses and can increase stresses in other RCS components. The consequences depend on several factors, as follows:

a. The severity of the departure from the allowable operating pressure temperature regime or the severity of the rate of change of temperature;

b. The length of time the limits were violated (longer violations allow the temperature gradient in the thick vessel walls to become more pronounced); and

c. The existence, size, and orientation of flaws in the vessel material.

APPLICABILITY

The potential for violating a P/T limit exists at all times. For example, P/T limit violations could result from ambient temperature conditions that result in the reactor vessel metal temperature being less than the minimum allowed temperature for boltup. Therefore, this LCO is applicable even when fuel is not loaded in the core.

ACTIONS

A.1 and A.2

Operation outside the P/T limits while in MODE 1, 2, or 3 must be corrected so that the RCPB is returned to a condition that has been verified by stress analyses.

The 30 minute Completion Time reflects the urgency of restoring the parameters to within the analyzed range. Most violations will not be severe, and the activity can be accomplished in this time in a controlled manner.

(continued)

BASES

ACTIONS

A.1 and A.2 (continued)

Besides restoring operation within limits, an engineering evaluation is required to determine if RCS operation can continue. The evaluation must verify the RCPB integrity remains acceptable and must be completed if continued operation is desired. Several methods may be used, including comparison with pre-analyzed transients in the stress analyses, new analyses, or inspection of the components. ASME Code, Section XI, Appendix E (Ref. 6), may be used to support the evaluation. However, its use is restricted to evaluation of the vessel beltline.

The 72 hour Completion Time is reasonable to accomplish the evaluation of a mild violation. More severe violations may require special, event specific stress analyses or inspections. A favorable evaluation must be completed if continued operation is desired.

Condition A is modified by a Note requiring Required Action A.2 be completed whenever the Condition is entered. The Note emphasizes the need to perform the evaluation of the effects of the excursion outside the allowable limits. Restoration alone per Required Action A.1 is insufficient because higher than analyzed stresses may have occurred and may have affected the RCPB integrity.

B.1 and B.2

If a Required Action and associated Completion Time of Condition A are not met, the plant must be brought to a lower MODE because either the RCS remained in an unacceptable P/T region for an extended period of increased stress, or a sufficiently severe event caused entry into an unacceptable region. Either possibility indicates a need for more careful examination of the event, best accomplished with the RCS at reduced pressure and temperature. With the reduced pressure and temperature conditions, the possibility of propagation of undetected flaws is decreased.

Pressure and temperature are reduced by bringing the plant to at least MODE 3 within 12 hours and to MODE 4 within 36 hours. The allowed Completion Times are reasonable,

(continued)

BASES

ACTIONS

B.1 and B.2 (continued)

based on operating experience, to reach the required plant conditions from full power conditions in an orderly manner and without challenging plant systems.

C.1 and C.2

Operation outside the P/T limits in other than MODES 1, 2, and 3 (including defueled conditions) must be corrected so that the RCPB is returned to a condition that has been verified by stress analyses. The Required Action must be initiated without delay and continued until the limits are restored.

Besides restoring the P/T limit parameters to within limits, an engineering evaluation is required to determine if RCS operation is allowed. This evaluation must verify that the RCPB integrity is acceptable and must be completed before approaching criticality or heating up to > 200°F. Several methods may be used, including comparison with pre-analyzed transients, new analyses, or inspection of the components. ASME Section XI, Appendix E (Ref. 6), may be used to support the evaluation; however, its use is restricted to evaluation of the beltline.

Condition C is modified by a Note requiring Required Action C.2 be completed whenever the Condition is entered. The Note emphasizes the need to perform the evaluation of the effects of the excursion outside the allowable limits. Restoration alone per Required Action C.1 is insufficient because higher than analyzed stresses may have occurred and may have affected the RCPB integrity.

SURVEILLANCE REQUIREMENTS

SR 3.4.11.1

Verification that operation is within limits is required every 30 minutes when RCS pressure and temperature conditions are undergoing planned changes. This Frequency is considered reasonable in view of the control room indication available to monitor RCS status. Also, since temperature rate of change limits are specified in hourly increments, 30 minutes permits assessment and correction of

(continued)

BASES

SURVEILLANCE REQUIREMENTS

SR 3.4.11.1 (continued)

minor deviations. The limits of Figures 3.4.11-1, 3.4.11-2, 3.4.11-3, 3.4.11-4, 3.4.11-5, and 3.4.11-6 are met when operation is to the right of the applicable curve.

Surveillance for heatup, cooldown, or inservice leak and hydrostatic testing may be discontinued when the criteria given in the relevant plant procedure for ending the activity are satisfied.

This SR has been modified by a Note that requires this Surveillance to be performed only during system heatup and cooldown operations and inservice leak and hydrostatic testing.

SR 3.4.11.2

A separate limit is used when the reactor is approaching criticality. Consequently, the RCS pressure and temperature must be verified within the appropriate limits before withdrawing control rods that will make the reactor critical. The limits of Figures 3.4.11-3 and 3.4.11-6 are met when operation is to the right of the applicable curve.

Performing the Surveillance within 15 minutes before control rod withdrawal for the purpose of achieving criticality provides adequate assurance that the limits will not be exceeded between the time of the Surveillance and the time of the control rod withdrawal.

SR 3.4.11.3 and SR 3.4.11.4

Differential temperatures within the applicable limits ensure that thermal stresses resulting from the startup of an idle recirculation pump will not exceed design allowances. In addition, compliance with these limits ensures that the assumptions of the analysis for the startup of an idle recirculation loop (Ref. 8) are satisfied.

(continued)

BASES

SURVEILLANCE REQUIREMENTS

SR 3.4.11.3 and SR 3.4.11.4 (continued)

Performing the Surveillance within 15 minutes before starting the idle recirculation pump provides adequate assurance that the limits will not be exceeded between the time of the Surveillance and the time of the idle pump start.

An acceptable means of demonstrating compliance with the temperature differential requirement in SR 3.4.11.3 is to compare temperatures of the reactor pressure vessel steam space coolant and the bottom head drain line coolant.

An acceptable means of demonstrating compliance with the temperature differential requirement in SR 3.4.11.4 is to compare the temperatures of the operating recirculation loop and the idle loop.

SR 3.4.11.3 and SR 3.4.11.4 have been modified by a Note that requires the Surveillance to be met only in MODES 1, 2, 3, and 4 during a recirculation pump startup since this is when the stresses occur. In MODE 5, the overall stress on limiting components is lower; therefore, ΔT limits are not required.

SR 3.4.11.5, SR 3.4.11.6, and SR 3.4.11.7

Limits on the reactor vessel flange and head flange temperatures are generally bounded by the other P/T limits during system heatup and cooldown. However, operations approaching MODE 4 from MODE 5 and in MODE 4 with RCS temperature less than or equal to certain specified values require assurance that these temperatures meet the LCO limits.

The flange temperatures must be verified to be above the limits within 30 minutes before and every 30 minutes thereafter while tensioning the vessel head bolting studs to ensure that once the head is tensioned the limits are satisfied. When in MODE 4 with RCS temperature $\leq$ 77°F for Unit 1 and $\leq$ 91°F for Unit 2, 30 minute checks of the flange temperatures are required because of the reduced margin to the limits. When in MODE 4 with RCS temperature $\leq$ 92°F for

(continued)

BASES

SURVEILLANCE REQUIREMENTS

SR 3.4.11.5, SR 3.4.11.6, and SR 3.4.11.7 (continued)

Unit 1 and ≤ 106°F for Unit 2, monitoring of the flange temperature is required every 12 hours to ensure the temperatures are within the specified limits.

The 30 minute Frequency reflects the urgency of maintaining the temperatures within limits, and also limits the time that the temperature limits could be exceeded. The 12 hour Frequency is reasonable based on the rate of temperature change possible at these temperatures.

SR 3.4.11.5 is modified by a Note that requires the Surveillance to be performed only when tensioning the reactor vessel head bolting studs. SR 3.4.11.6 is modified by a Note that requires the Surveillance to be initiated 30 minutes after RCS temperature ≤ 77°F for Unit 1 and ≤ 91°F for Unit 2 in MODE 4, SR 3.4.11.7 is modified by a Note that requires the Surveillance to be initiated 12 hours after RCS temperature ≤ 92°F for Unit 1 and ≤ 106°F for Unit 2 in MODE 4. The Notes contained in these SRs are necessary to specify when the reactor vessel flange and head flange temperatures are required to be verified to be within the specified limits.

REFERENCES

1. 10 CFR 50, Appendix G.

2. ASME, Boiler and Pressure Vessel Code, Section III, Appendix G.

3. ASTM E 185.

4. 10 CFR 50, Appendix H.

5. Regulatory Guide 1.99, Revision 2, May 1988.

6. ASME, Boiler and Pressure Vessel Code, Section XI, Appendix E.

7. NRC Safety Evaluation supporting Amendment No. 71 to Facility Operating License No. NPF-11 and Amendment No. 55 to Facility Operating License No. NPF-18 – LaSalle County Station, Units 1 and 2, dated January 16, 1990.

8. UFSAR, Section 15.4.4.

B 3.4 REACTOR COOLANT SYSTEM (RCS)

B 3.4.12 Reactor Steam Dome Pressure

BASES

BACKGROUND	The reactor steam dome pressure is an assumed value in the determination of compliance with reactor pressure vessel overpressure protection criteria and is also an assumed initial condition of Design Basis Accidents (DBAs) and transients.
APPLICABLE SAFETY ANALYSES	The reactor steam dome pressure of $\leq$ 1020 psig is an initial condition of the vessel overpressure protection analysis of Reference 1. This analysis assumes an initial maximum reactor steam dome pressure and evaluates the response of the pressure relief system, primarily the safety/relief valves, during the limiting pressurization transient. The determination of compliance with the overpressure criteria is dependent on the initial reactor steam dome pressure; therefore, the limit on this pressure ensures that the assumptions of the overpressure protection analysis are conserved. Reference 2 also assumes an initial reactor steam dome pressure for the analysis of DBAs and transients used to determine the limits for fuel cladding integrity MCPR (see Bases for LCO 3.2.2, "MINIMUM CRITICAL POWER RATIO (MCPR)") and 1% cladding plastic strain (see Bases for LCO 3.2.1, "AVERAGE PLANAR LINEAR HEAT GENERATION RATE (APLHGR)" and LCO 3.2.3, "LINEAR HEAT GENERATION RATE (LHGR)"). The nominal reactor operating pressure is approximately 1005 psig. Transient analyses typically use the nominal or a design dome pressure as input to the analysis. Small deviations (5 to 10 psi) from the nominal pressure are not expected to change most of the transient analyses results. However, sensitivity studies for fast pressurization events (main turbine generator load rejection without bypass, turbine trip without bypass, and feedwater controller failure) indicate that the delta-CPR may increase for lower initial pressures. Therefore, the fast pressurization events have considered a bounding initial pressure based on a typical operating range to assure a conservative delta-CPR and operating limit. Reactor steam dome pressure satisfies the requirements of Criterion 2 of 10 CFR 50.36(c)(2)(ii).

(continued)

BASES (continued)

LCO

The specified reactor steam dome pressure limit of ≤ 1020 psig ensures the plant is operated within the assumptions of the reactor overpressure analysis. Operation above the limit may result in a transient response more severe than analyzed.

APPLICABILITY

In MODES 1 and 2, the reactor steam dome pressure is required to be less than or equal to the limit. In these MODES, the reactor may be generating significant steam, and events that may challenge the overpressure limits are possible.

In MODES 3, 4, and 5, the limit is not applicable because the reactor is shut down. In these MODES, the reactor pressure is well below the required limit, and no anticipated events will challenge the overpressure limits.

ACTIONS

A.1

With the reactor steam dome pressure greater than the limit, prompt action should be taken to reduce pressure to below the limit and return the reactor to operation within the bounds of the analyses. The 15 minute Completion Time is reasonable considering the importance of maintaining the pressure within limits. This Completion Time also ensures that the probability of an accident while pressure is greater than the limit is minimal.

B.1

If the reactor steam dome pressure cannot be restored to within the limit within the associated Completion Time, the plant must be brought to a MODE in which the LCO does not apply. To achieve this status, the plant must be brought to at least MODE 3 within 12 hours. The allowed Completion Time of 12 hours is reasonable, based on operating experience, to reach MODE 3 from full power conditions in an orderly manner and without challenging plant systems.

(continued)

BASES (continued)

SURVEILLANCE REQUIREMENTS

SR 3.4.12.1

Verification that reactor steam dome pressure is ≤ 1020 psig ensures that the initial condition of the vessel overpressure protection analysis is met. Operating experience has shown the 12 hour Frequency to be sufficient for identifying trends and verifying operation within safety analyses assumptions.

REFERENCES

1. UFSAR, Section 5.2.2.2.1.

2. UFSAR, Chapter 15.

B 3.5 EMERGENCY CORE COOLING SYSTEMS (ECCS) AND REACTOR CORE ISOLATION COOLING (RCIC) SYSTEM

B 3.5.1 ECCS – Operating

BASES

BACKGROUND

The ECCS is designed, in conjunction with the primary and secondary containment, to limit the release of radioactive materials to the environment following a loss of coolant accident (LOCA). The ECCS uses two independent methods (flooding and spraying) to cool the core during a LOCA. The ECCS network is composed of the High Pressure Core Spray (HPCS) System, the Low Pressure Core Spray (LPCS) System, and the low pressure coolant injection (LPCI) mode of the Residual Heat Removal (RHR) System. The ECCS also consists of the Automatic Depressurization System (ADS). The suppression pool provides the required source of water for the ECCS.

On receipt of an initiation signal, ECCS pumps automatically start; the system aligns, and the pumps inject water, taken from the suppression pool, into the Reactor Coolant System (RCS) as RCS pressure is overcome by the discharge pressure of the ECCS pumps. Although the system is initiated, ADS action is delayed, allowing the operator to interrupt the timed sequence if the system is not needed. The HPCS pump discharge pressure almost immediately exceeds that of the RCS, and the pump injects coolant into the spray sparger above the core. If the break is small, HPCS will maintain coolant inventory, as well as vessel level, while the RCS is still pressurized. If HPCS fails, it is backed up by ADS in combination with LPCI and LPCS. In this event, the ADS timed sequence would be allowed to time out and open the selected safety/relief valves (S/RVs), depressurizing the RCS and allowing the LPCI and LPCS to overcome RCS pressure and inject coolant into the vessel. If the break is large, RCS pressure initially drops rapidly, and the LPCI and LPCS systems cool the core.

Water from the break returns to the suppression pool where it is used again and again. Water in the suppression pool is circulated through a heat exchanger cooled by the Residual Heat Removal Service Water (RHRSW) System. Depending on the location and size of the break, portions of

(continued)

BASES

BACKGROUND (continued)

the ECCS may be ineffective; however, the overall design is effective in cooling the core regardless of the size or location of the piping break.

All ECCS subsystems are designed to ensure that no single active component failure will prevent automatic initiation and successful operation of the minimum required ECCS subsystems.

The LPCS System (Ref. 1) consists of a motor driven pump, a spray sparger above the core, piping, and valves to transfer water from the suppression pool to the sparger. The LPCS System is designed to provide cooling to the reactor core when the reactor pressure is low. Upon receipt of an initiation signal, the LPCS pump is automatically started when AC power is available. When the RPV pressure drops sufficiently, LPCS flow to the RPV begins. A full flow test line is provided to route water to the suppression pool to allow testing of the LPCS System without spraying water into the RPV.

LPCI is an independent operating mode of the RHR System. There are three LPCI subsystems. Each LPCI subsystem (Ref. 2) consists of a motor driven pump, piping, and valves to transfer water from the suppression pool to the core. Each LPCI subsystem has its own suction and discharge piping and separate vessel nozzle that connects with the core shroud through internal piping. The LPCI subsystems are designed to provide core cooling at low RPV pressure. Upon receipt of an initiation signal, each LPCI pump is automatically started. (If AC power is supplied by the diesel generators, C pump starts immediately when AC power is available and A and B pumps approximately 5 seconds after AC power is available). When the RPV pressure drops sufficiently, LPCI flow to the RPV begins. RHR System valves in the LPCI flow path are automatically positioned to ensure the proper flow path for water from the suppression pool to inject into the core. A full flow test line is provided to route water to the suppression pool to allow testing of each LPCI pump without injecting water into the RPV.

The HPCS System (Ref. 3) consists of a single motor driven pump, a spray sparger above the core, and piping and valves

(continued)

BASES

BACKGROUND (continued)

to transfer water from the suppression pool to the sparger. The HPCS System is designed to provide core cooling over a wide range of RPV pressures (0 psid to 1200 psid, vessel to suction source). Upon receipt of an initiation signal, the HPCS pump automatically starts (when AC power is available) and valves in the flow path begin to open. Since the HPCS System is designed to operate over the full range of expected RPV pressures, HPCS flow begins as soon as the necessary valves are open. A full flow test line is provided to route water to the suppression pool to allow testing of the HPCS System during normal operation without spraying water into the RPV.

The ECCS pumps are provided with minimum flow bypass lines, which discharge to the suppression pool. The valves in these lines automatically open to prevent pump damage due to overheating when other discharge line valves are closed or RPV pressure is greater than the LPCS or LPCI pump discharge pressures following system initiation. To ensure rapid delivery of water to the RPV and to minimize water hammer effects, the ECCS discharge line "keep fill" systems are designed to maintain all pump discharge lines filled with water.

The ADS (Ref. 4) consists of 7 of the 18 S/RVs for Unit 1 and 7 of the 13 S/RVs for Unit 2. It is designed to provide depressurization of the primary system during a small break LOCA if HPCS fails or is unable to maintain required water level in the RPV. ADS operation reduces the RPV pressure to within the operating pressure range of the low pressure ECCS subsystems (LPCS and LPCI), so that these subsystems can provide core cooling.

The Drywell Pneumatic System discharges from the air receiver (or nitrogen receiver when the primary containment is inerted) and after filtration is divided into two supply headers, one of which supplies all the ADS accumulators with approximately 175 psig air (or nitrogen). There is a check valve between each ADS accumulator and the supply. Drywell Pneumatic System low header pressure and high ADS pressure are alarmed in the control room.

The accumulators for the ADS valves are normally maintained by the Drywell Pneumatic System compressors. There are two full-capacity compressors which cycle as needed to maintain

(continued)

BASES

BACKGROUND (continued)

pressure in the drywell pneumatic receiver tank. Nitrogen bottle banks provide a backup source to maintain the ADS accumulators charged following isolation of the normal pneumatic supply. Each ADS accumulator is provided with a pressure switch to detect low pressure (< 150 psig). These pressure switches are provided with alarms in the control room. A control room alarm is also annunciated for low pressure in the ADS nitrogen bottle banks supply headers.

APPLICABLE SAFETY ANALYSES

The ECCS performance is evaluated for the entire spectrum of break sizes for a postulated LOCA. The accidents for which ECCS operation is required are presented in References 5, 6, and 7. The required analyses and assumptions are defined in 10 CFR 50 (Ref. 8), and the results of these analyses are described in Reference 9.

This LCO helps to ensure that the following acceptance criteria for the ECCS, established by 10 CFR 50.46 (Ref. 10), will be met following a LOCA assuming the worst case single active component failure in the ECCS:

a. Maximum fuel element cladding temperature is $\leq$ 2200°F;

b. Maximum cladding oxidation is $\leq$ 0.17 times the total cladding thickness before oxidation;

c. Maximum hydrogen generation from zirconium water reaction is $\leq$ 0.01 times the hypothetical amount that would be generated if all of the metal in the cladding surrounding the fuel, excluding the cladding surrounding the plenum volume, were to react;

d. The core is maintained in a coolable geometry; and

e. Adequate long term cooling capability is maintained.

The limiting single failures are discussed in Reference 11. For the LOCA evaluation model which covers the entire spectrum of break sizes (large breaks to small breaks), failure of the HPCS ECCS subsystem in Division 3 due to failure of its associated diesel generator is, in general, the most severe failure. The remaining OPERABLE ECCS subsystems, which include one spray subsystem, provide the

(continued)

BASES

APPLICABLE SAFETY ANALYSES (continued)

capability to adequately cool the core, under near-term and long-term conditions, and prevent excessive fuel damage. For all LOCA analyses, only six ADS valves are assumed to function. An additional analysis has been performed which assumes five ADS valves function, however in this analysis all low pressure and high pressure ECCS subsystems are also assumed to be available.

The ECCS satisfy Criterion 3 of 10 CFR 50.36(c)(2)(ii).

LCO

Each ECCS injection/spray subsystem and six ADS valves are required to be OPERABLE. The ECCS injection/spray subsystems are defined as the three LPCI subsystems, the LPCS System, and the HPCS System. The low pressure ECCS injection/spray subsystems are defined as the LPCS System and the three LPCI subsystems.

With less than the required number of ECCS subsystems OPERABLE during a limiting design basis LOCA concurrent with the worst case single failure, the limits specified in 10 CFR 50.46 (Ref. 10) could potentially be exceeded. All ECCS subsystems must therefore be OPERABLE to satisfy the single failure criterion required by 10 CFR 50.46 (Ref. 10).

As noted, LPCI subsystems may be considered OPERABLE during alignment and operation for decay heat removal when below the actual RHR cut in permissive pressure in MODE 3, if capable of being manually realigned (remote or local) to the LPCI mode and not otherwise inoperable. Alignment and operation for decay heat removal includes: a) when the system is realigned to or from the RHR shutdown cooling mode and; b) when the system is in the RHR shutdown cooling mode, whether or not the RHR pump is operating. This allowance is necessary since the RHR System may be required to operate in the shutdown cooling mode to remove decay heat and sensible heat from the reactor. At these low pressures and decay heat levels, a reduced complement of ECCS subsystems should provide the required core cooling, thereby allowing operation of RHR shutdown cooling when necessary.

APPLICABILITY

All ECCS subsystems are required to be OPERABLE during MODES 1, 2, and 3 when there is considerable energy in the reactor core and core cooling would be required to prevent fuel damage in the event of a break in the primary system

(continued)

BASES

APPLICABILITY (continued)

piping. In MODES 2 and 3, the ADS function is not required when pressure is ≤ 150 psig because the low pressure ECCS subsystems (LPCS and LPCI) are capable of providing flow into the RPV below this pressure. ECCS requirements for MODES 4 and 5 are specified in LCO 3.5.2, "ECCS – Shutdown.

ACTIONS

A.1

If any one low pressure ECCS injection/spray subsystem is inoperable, the inoperable subsystem must be restored to OPERABLE status within 7 days. In this Condition, the remaining OPERABLE subsystems provide adequate core cooling during a LOCA. However, overall ECCS reliability is reduced because a single failure in one of the remaining OPERABLE subsystems concurrent with a LOCA may result in the ECCS not being able to perform its intended safety function. The 7 day Completion Time is based on a reliability study (Ref. 12) that evaluated the impact on ECCS availability by assuming that various components and subsystems were taken out of service. The results were used to calculate the average availability of ECCS equipment needed to mitigate the consequences of a LOCA as a function of allowed outage times (i.e., Completion Times).

B.1 and B.2

If the HPCS System is inoperable, and the RCIC System is immediately verified to be OPERABLE (when RCIC is required to be OPERABLE), the HPCS System must be restored to OPERABLE status within 14 days. In this Condition, adequate core cooling is ensured by the OPERABILITY of the redundant and diverse low pressure ECCS injection/spray subsystems in conjunction with the ADS. Also, the RCIC System will automatically provide makeup water at most reactor operating pressures. Immediate verification of RCIC OPERABILITY is therefore required when HPCS is inoperable and RCIC is required to be OPERABLE. This may be performed by an administrative check, by examining logs or other information, to determine if RCIC is out of service for maintenance or other reasons. It is not necessary to perform the Surveillances needed to demonstrate the OPERABILITY of the RCIC System. However, if the OPERABILITY

(continued)

BASES

ACTIONS

B.1 and B.2 (continued)

of the RCIC System cannot be immediately verified and RCIC is required to be OPERABLE, Condition E must be entered. If a single active component fails concurrent with a design basis LOCA, there is a potential, depending on the specific failure, that the minimum required ECCS equipment will not be available. A 14 day Completion Time is based on the results of a reliability study (Ref. 12) and has been found to be acceptable through operating experience.

C.1

With two ECCS injection subsystems inoperable or one ECCS injection and the low pressure ECCS spray subsystem (LPCS) inoperable, at least one ECCS injection/spray subsystem must be restored to OPERABLE status within 72 hours. In this Condition, the remaining OPERABLE subsystems provide adequate core cooling during a LOCA. However, overall ECCS reliability is reduced in this Condition because a single failure in one of the remaining OPERABLE subsystems concurrent with a design basis LOCA may result in the ECCS not being able to perform its intended safety function. Since the ECCS availability is reduced relative to Condition A, a more restrictive Completion Time is imposed. The 72 hour Completion Time is based on a reliability study, as provided in Reference 12.

D.1 and D.2

With the ADS accumulator backup compressed gas system bottle pressure less than the specified limit, bottle pressure must be restored within 72 hours, or the associated ADS valves must be declared inoperable. In this condition, the remaining Drywell Pneumatic System and ADS accumulators are sufficient to ensure ADS valve operation. However, overall ECCS reliability is reduced in this condition because with insufficient bottle bank pressure, the capability of ADS valves to operate for long periods of time following an accident (without the Drywell Pneumatic System) is reduced. Each ADS valve is equipped with an individual accumulator of sufficient capacity to operate the valves in the event of a loss of air supply. The 72 hour Completion Time is based on a reliability study, as provided in Reference 12.

(continued)

BASES

ACTIONS (continued)

E.1 and E.2

If any Required Action and associated Completion Time of Condition A, B, or C are not met, the plant must be brought to a MODE in which the LCO does not apply. To achieve this status, the plant must be brought to at least MODE 3 within 12 hours and to MODE 4 within 36 hours. The allowed Completion Times are reasonable, based on operating experience, to reach the required plant conditions from full power conditions in an orderly manner and without challenging plant systems.

F.1

The LCO requires six ADS valves to be OPERABLE to provide the ADS function. Reference 11 contains the results of an evaluation of the effect of one required ADS valve being out of service. Per this evaluation, operation of only five ADS valves will provide the required depressurization. However, overall reliability of the ADS is reduced because a single failure in the OPERABLE ADS valves could result in a reduction in depressurization capability. Therefore, operation is only allowed for a limited time. The 14 day Completion Time is based on a reliability study (Ref. 12) and has been found to be acceptable through operating experience.

G.1 and G.2

If any Required Action and associated Completion Time of Condition F is not met or if two or more required ADS valves are inoperable, the plant must be brought to a condition in which the LCO does not apply. To achieve this status, the plant must be brought to at least MODE 3 within 12 hours and reactor steam dome pressure reduced to $\leq$ 150 psig within 36 hours. The allowed Completion Times are reasonable, based on operating experience, to reach the required plant conditions from full power conditions in an orderly manner and without challenging plant systems.

(continued)

BASES

ACTIONS (continued)

H.1

When multiple ECCS subsystems are inoperable, as stated in Condition H, the plant is in a condition outside of the design basis. Therefore, LCO 3.0.3 must be entered immediately.

SURVEILLANCE REQUIREMENTS

SR 3.5.1.1

The flow path piping has the potential to develop voids and pockets of entrained air. Maintaining the pump discharge lines of the HPCS System, LPCS System, and LPCI subsystems full of water ensures that the systems will perform properly, injecting their full capacity into the RCS upon demand. This will also prevent a water hammer following an ECCS initiation signal. One acceptable method of ensuring the lines are full is to vent at the high points. The 31 day Frequency is based on operating experience, on the procedural controls governing system operation, and on the gradual nature of void buildup in the ECCS piping.

SR 3.5.1.2

Verifying the correct alignment for manual, power operated, and automatic valves in the ECCS flow paths provides assurance that the proper flow paths will exist for ECCS operation. This SR does not apply to valves that are locked, sealed, or otherwise secured in position since these valves were verified to be in the correct position prior to locking, sealing, or securing. A valve that receives an initiation signal is allowed to be in a nonaccident position provided the valve will automatically reposition in the proper stroke time. This SR does not require any testing or valve manipulation; rather, it involves verification that those valves potentially capable of being mispositioned are in the correct position. This SR does not apply to valves that cannot be inadvertently misaligned, such as check valves.

The 31 day Frequency of this SR was derived from the Inservice Testing Program requirements for performing valve testing at least once every 92 days. The Frequency of

(continued)

BASES

SURVEILLANCE REQUIREMENTS

SR 3.5.1.2 (continued)

31 days is further justified because the valves are operated under procedural control and because improper valve alignment would only affect a single subsystem. This Frequency has been shown to be acceptable through operating experience.

SR 3.5.1.3

Verification every 31 days that ADS accumulator supply header pressure is ≥ 150 psig assures adequate pneumatic pressure for reliable ADS operation. The accumulator on each ADS valve provides pneumatic pressure for valve actuation. The ADS valve accumulators are sized to provide two cycles of the ADS valves upon loss of the nitrogen supply (Ref. 13). The ECCS safety analysis assumes only one actuation to achieve the depressurization required for operation of the low pressure ECCS. The accumulator supply header pressure verification may be accomplished by monitoring control room alarms. The 31 day Frequency takes into consideration alarms for low pneumatic pressure.

SR 3.5.1.4

Verification every 31 days that ADS accumulator backup compressed gas system bottle pressure is ≥ 500 psig assures availability of an adequate backup pneumatic supply to the ADS accumulators following a loss of the drywell pneumatic supply. The 31 day frequency is adequate because each ADS bottle bank is monitored by a low pressure alarm. Also, unless the normal drywell pneumatic supply is lost, the only expected losses from the bottles are due to leakage, which is minimal.

SR 3.5.1.5

The performance requirements of the ECCS pumps are determined through application of the 10 CFR 50, Appendix K, criteria (Ref. 8). This periodic Surveillance is performed (in accordance with the ASME Code, Section XI, requirements

(continued)

BASES

SURVEILLANCE REQUIREMENTS

SR 3.5.1.5 (continued)

for the ECCS pumps) to verify that the ECCS pumps will develop the flow rates required by the respective analyses. The ECCS pump flow rates ensure that adequate core cooling is provided to satisfy the acceptance criteria of 10 CFR 50.46 (Ref. 10).

The pump flow rates are verified against a test line pressure that was determined during preoperational testing to be equivalent to the RPV pressure expected during a LOCA. Under these conditions, the total system pump outlet pressure is adequate to overcome the elevation head pressure between the pump suction and the vessel discharge, the piping friction losses, and RPV pressure present during LOCAs. The Frequency for this Surveillance is in accordance with the Inservice Testing Program requirements.

SR 3.5.1.6

The ECCS subsystems are required to actuate automatically to perform their design functions. This Surveillance verifies that, with a required system initiation signal (actual or simulated), the automatic initiation logic of HPCS, LPCS, and LPCI will cause the systems or subsystems to operate as designed, including actuation of the system throughout its emergency operating sequence, automatic pump startup, and actuation of all automatic valves to their required position. This Surveillance also ensures that the HPCS System injection valve will automatically reopen on an RPV low water level (Level 2) signal received subsequent to an RPV high water level (Level 8) injection valve closure signal. The LOGIC SYSTEM FUNCTIONAL TEST performed in LCO 3.3.5.1 overlaps this Surveillance to provide complete testing of the assumed safety function.

The 24 month Frequency is based on the need to perform this Surveillance under the conditions that apply during a plant outage and the potential for an unplanned transient if the Surveillance were performed with the reactor at power. Operating experience has shown that these components usually pass the SR when performed at the 24 month Frequency, which is based on the refueling cycle. Therefore, the Frequency was concluded to be acceptable from a reliability standpoint.

(continued)

BASES

SURVEILLANCE REQUIREMENTS

SR 3.5.1.6 (continued)

This SR is modified by a Note that excludes vessel injection/spray during the Surveillance. Since all active components are testable and full flow can be demonstrated by recirculation through the test line, coolant injection into the RPV is not required during the Surveillance.

SR 3.5.1.7

The ADS designated S/RVs are required to actuate automatically upon receipt of specific initiation signals. A system functional test is performed to demonstrate that the mechanical portions of the ADS function (i.e., solenoids) operate as designed when initiated either by an actual or simulated initiation signal, causing proper actuation of all the required components. SR 3.5.1.8 and the LOGIC SYSTEM FUNCTIONAL TEST performed in LCO 3.3.5.1 overlap this Surveillance to provide complete testing of the assumed safety function.

The 24 month Frequency is based on the need to perform this Surveillance under the conditions that apply during a plant outage and the potential for an unplanned transient if the Surveillance were performed with the reactor at power. Operating experience has shown that these components usually pass the SR when performed at the 24 month Frequency, which is based on the refueling cycle. Therefore, the Frequency was concluded to be acceptable from a reliability standpoint.

This SR is modified by a Note that excludes valve actuation since the valves are individually tested in accordance with SR 3.5.1.8. This also prevents an RPV pressure blowdown.

SR 3.5.1.8

A manual actuation of each required ADS valve, and observing the expected change in the indicated valve position, is performed to verify that the valve and solenoids are functioning properly. SR 3.5.1.7 and the LOGIC SYSTEM FUNCTIONAL TEST performed in LCO 3.3.5.1 overlap this Surveillance to provide complete testing of the assumed safety function.

(continued)

BASES

SURVEILLANCE REQUIREMENTS

SR 3.5.1.8 (continued)

The Frequency of 24 months on a STAGGERED TEST BASIS ensures that both solenoids for each required ADS valve are alternately tested. The Frequency is based on the need to perform this Surveillance under the conditions that apply just prior to or during a startup from a plant outage. Operating experience has shown that these components usually pass the SR when performed at the 24 month Frequency, which is based on the refueling cycle. Therefore, the Frequency was concluded to be acceptable from a reliability standpoint.

REFERENCES

1. UFSAR, Section 6.3.2.2.3.
2. UFSAR, Section 6.3.2.2.4.
3. UFSAR, Section 6.3.2.2.1.
4. UFSAR, Section 6.3.2.2.2.
5. UFSAR, Section 15.2.8.
6. UFSAR, Section 15.6.4.
7. UFSAR, Section 15.6.5.
8. 10 CFR 50, Appendix K.
9. UFSAR, Section 6.3.3.
10. 10 CFR 50.46.
11. UFSAR, Section 6.3.3.3.
12. Memorandum from R.L. Baer (NRC) to V. Stello, Jr. (NRC), "Recommended Interim Revisions to LCO's for ECCS Components," December 1, 1975.
13. UFSAR, Section 7.3.1.2.

B 3.5 EMERGENCY CORE COOLING SYSTEMS (ECCS) AND REACTOR CORE ISOLATION COOLING (RCIC) SYSTEM

B 3.5.2 ECCS – Shutdown

BASES

BACKGROUND	A description of the High Pressure Core Spray (HPCS) System, Low Pressure Core Spray (LPCS) System, and low pressure coolant injection (LPCI) mode of the Residual Heat Removal (RHR) System is provided in the Bases for LCO 3.5.1, "ECCS – Operating."
APPLICABLE SAFETY ANALYSES	The ECCS performance is evaluated for the entire spectrum of break sizes for a postulated loss of coolant accident (LOCA). The long term cooling analysis following a design basis LOCA (Ref. 1) demonstrates that only one ECCS injection/spray subsystem is required, post LOCA, to maintain adequate reactor vessel water level in the event of an inadvertent vessel draindown. It is reasonable to assume, based on engineering judgment, that while in MODES 4 and 5, one ECCS injection/spray subsystem can maintain adequate reactor vessel water level. To provide redundancy, a minimum of two ECCS injection/spray subsystems are required to be OPERABLE in MODES 4 and 5. The ECCS satisfy Criterion 3 of 10 CFR 50.36(c)(2)(ii).
LCO	Two ECCS injection/spray subsystems are required to be OPERABLE. The ECCS injection/spray subsystems are defined as the three LPCI subsystems, the LPCS System, and the HPCS System. The LPCS System and each LPCI subsystem consist of one motor driven pump, piping, and valves to transfer water from the suppression pool to the RPV. The HPCS System consists of one motor driven pump, piping, and valves to transfer water from the suppression pool to the RPV. The necessary portions of the Diesel Generator Cooling Water System are also required to provide appropriate cooling to each required ECCS injection/spray subsystem As noted, one LPCI subsystem (A or B) may be considered OPERABLE during alignment and operation for decay heat removal, if capable of being manually realigned (remote or

(continued)

BASES

LCO (continued)

local) to the LPCI mode and is not otherwise inoperable. Alignment and operation for decay heat removal includes: a) when the system is realigned to or from the RHR shutdown cooling mode and; b) when the system is in the RHR shutdown cooling mode, whether or not the RHR pump is operating. This allowance is necessary since the RHR System may be required to operate in the shutdown cooling mode to remove decay heat and sensible heat from the reactor. Because of low pressure and low temperature conditions in MODES 4 and 5, sufficient time will be available to manually align and initiate LPCI subsystem operation to provide core cooling prior to postulated fuel uncovery.

APPLICABILITY

OPERABILITY of the ECCS injection/spray subsystems is required in MODES 4 and 5 to ensure adequate coolant inventory and sufficient heat removal capability for the irradiated fuel in the core in case of an inadvertent draindown of the vessel. Requirements for ECCS OPERABILITY during MODES 1, 2, and 3 are discussed in the Applicability section of the Bases for LCO 3.5.1. ECCS subsystems are not required to be OPERABLE during MODE 5 with the spent fuel storage pool gates removed and the water level maintained at $\geq$ 22 ft above the RPV flange. This provides sufficient coolant inventory to allow operator action to terminate the inventory loss prior to fuel uncovery in case of an inadvertent draindown.

The Automatic Depressurization System is not required to be OPERABLE during MODES 4 and 5 because the RPV pressure is < 150 psig, and the LPCS, HPCS, and LPCI subsystems can provide core cooling without any depressurization of the primary system.

ACTIONS

A.1 and B.1

If any one required ECCS injection/spray subsystem is inoperable, the required inoperable ECCS injection/spray subsystem must be restored to OPERABLE status within 4 hours. In this Condition, the remaining OPERABLE subsystem can provide sufficient RPV flooding capability to recover from an inadvertent vessel draindown. However, overall system reliability is reduced because a single failure in the remaining OPERABLE subsystem concurrent with

(continued)

BASES

ACTIONS

A.1 and B.1 (continued)

a vessel draindown could result in the ECCS not being able to perform its intended function. The 4 hour Completion Time for restoring the required ECCS injection/spray subsystem to OPERABLE status is based on engineering judgment that considered the availability of one subsystem and the low probability of a vessel draindown event.

With the inoperable subsystem not restored to OPERABLE status within the required Completion Time, action must be initiated immediately to suspend operations with a potential for draining the reactor vessel (OPDRVs) to minimize the probability of a vessel draindown and the subsequent potential for fission product release. Actions must continue until OPDRVs are suspended.

C.1, C.2, D.1, D.2, and D.3

If both of the required ECCS injection/spray subsystems are inoperable, all coolant inventory makeup capability may be unavailable. Therefore, actions must be initiated immediately to suspend OPDRVs in order to minimize the probability of a vessel draindown and the subsequent potential for fission product release. Actions must continue until OPDRVs are suspended. One ECCS injection/spray subsystem must also be restored to OPERABLE status within 4 hours. The 4 hour Completion Time to restore at least one required ECCS injection/spray subsystem to OPERABLE status ensures that prompt action will be taken to provide the required cooling capacity or to initiate actions to place the plant in a condition that minimizes any potential fission product release to the environment.

If at least one required ECCS injection/spray subsystem is not restored to OPERABLE status within the 4 hour Completion Time, additional actions are required to minimize any potential fission product release to the environment. This includes ensuring secondary containment is OPERABLE; one standby gas treatment subsystem is OPERABLE; and secondary containment isolation capability is available in each secondary containment penetration flow path not isolated that is assumed to be isolated to mitigate radioactivity

(continued)

BASES

ACTIONS

C.1, C.2, D.1, D.2, and D.3 (continued)

releases (i.e., one secondary containment isolation valve and associated instrumentation are OPERABLE or other acceptable administrative controls to assure isolation capability. The administrative controls consist of stationing a dedicated operator, who is in continuous communication with the control room at the controls of the isolation device. In this way, the penetration can be rapidly isolated when a need for secondary containment isolation is indicated.) This may be performed by an administrative check, by examining logs or other information, to determine if the components are out of service for maintenance or other reasons. It is not necessary to perform the Surveillances needed to demonstrate OPERABILITY of the components. If, however, any required component is inoperable, then it must be restored to OPERABLE status. In this case, the Surveillances may need to be performed to restore the component to OPERABLE status. Actions must continue until all required components are OPERABLE.

SURVEILLANCE REQUIREMENTS

SR 3.5.2.1 and SR 3.5.2.2

The minimum water level of -12 ft 7 in (referenced to a plant elevation of 699 ft 11 in) required for the suppression pool, equivalent to a contained water volume of 70,000 ft^3, is periodically verified to ensure that the suppression pool will provide adequate net positive suction head (NPSH) for the ECCS pumps, recirculation volume, and vortex prevention. With the suppression pool water level less than the required limit, all ECCS injection/spray subsystems are inoperable.

The 12 hour Frequency of these SRs was developed considering operating experience related to suppression pool water level variations and instrument drift during the applicable MODES. Furthermore, the 12 hour Frequency is considered adequate in view of other indications in the control room to alert the operator to an abnormal suppression pool water level condition.

(continued)

BASES

SURVEILLANCE REQUIREMENTS (continued)

SR 3.5.2.3, SR 3.5.2.5, and SR 3.5.2.6

The Bases provided for SR 3.5.1.1, SR 3.5.1.4, and SR 3.5.1.5 are applicable to SR 3.5.2.3, SR 3.5.2.5, and SR 3.5.2.6, respectively.

SR 3.5.2.4

Verifying the correct alignment for manual, power operated, and automatic valves in the ECCS flow paths provides assurance that the proper flow paths will exist for ECCS operation. This SR does not apply to valves that are locked, sealed, or otherwise secured in position since these valves were verified to be in the correct position prior to locking, sealing, or securing. A valve that receives an initiation signal is allowed to be in a nonaccident position provided the valve will automatically reposition in the proper stroke time. This SR does not require any testing or valve manipulation; rather, it involves verification that those valves capable of potentially being mispositioned are in the correct position. This SR does not apply to valves that cannot be inadvertently misaligned, such as check valves. The 31 day Frequency is appropriate because the valves are operated under procedural control and the probability of their being mispositioned during this time period is low.

REFERENCES

1. UFSAR, Section 6.3.3.2.

B 3.5 EMERGENCY CORE COOLING SYSTEMS (ECCS) AND REACTOR CORE ISOLATION COOLING (RCIC) SYSTEM

B 3.5.3 RCIC System

BASES

BACKGROUND

The RCIC System is not part of the ECCS; however, the RCIC System is included with the ECCS section because of their similar functions.

The RCIC System is designed to operate either automatically or manually following reactor pressure vessel (RPV) isolation accompanied by a loss of coolant flow from the feedwater system to provide adequate core cooling and control of RPV water level. Under these conditions, the High Pressure Core Spray (HPCS) and RCIC systems perform similar functions. The RCIC System design requirements ensure that the criteria of Reference 1 are satisfied.

The RCIC System (Ref. 2) consists of a steam driven turbine pump unit, piping and valves to provide steam to the turbine, as well as piping and valves to transfer water from the suction source to the core via the head spray nozzle. Suction piping is provided from the condensate storage tank (CST) and the suppression pool. Pump suction is normally aligned to the CST to minimize injection of suppression pool water into the RPV. However, if the CST water supply is low an automatic transfer to the suppression pool water source ensures a water supply for continuous operation of the RCIC System. The steam supply to the turbine is piped from main steam line B, upstream of the inboard main steam line isolation valve.

The RCIC System is designed to provide core cooling for a wide range of reactor pressures, 135 psig to 1185 psig. Upon receipt of an initiation signal, the RCIC turbine accelerates to a specified speed. As the RCIC flow increases, the turbine control valve is automatically adjusted to maintain design flow. Exhaust steam from the RCIC turbine is discharged to the suppression pool. A full flow test line is provided to route water to the CST or the suppression pool to allow testing of the RCIC System during normal operation without injecting water into the RPV.

(continued)

BASES

BACKGROUND (continued)

The RCIC pump is provided with a minimum flow bypass line, which discharges to the suppression pool. The valve in this line automatically opens to prevent pump damage due to overheating when other discharge line valves are closed. To ensure rapid delivery of water to the RPV and to minimize water hammer effects, the RCIC System discharge line "keep fill" system is designed to maintain the pump discharge line filled with water.

APPLICABLE SAFETY ANALYSES

The function of the RCIC System is to respond to transient events by providing makeup coolant to the reactor. The RCIC System is not an Engineered Safety Feature System and no credit is taken in the safety analyses for RCIC System operation. Based on its contribution to the reduction of overall plant risk, the system satisfies Criterion 4 of 10 CFR 50.36(c)(2)(ii).

LCO

The OPERABILITY of the RCIC System provides adequate core cooling such that actuation of any of the ECCS subsystems is not required in the event of RPV isolation accompanied by a loss of feedwater flow. The RCIC System has sufficient capacity to maintain RPV inventory during an isolation event.

APPLICABILITY

The RCIC System is required to be OPERABLE in MODE 1, and MODES 2 and 3 with reactor steam dome pressure > 150 psig since RCIC is the primary non-ECCS water source for core cooling when the reactor is isolated and pressurized. In MODES 2 and 3 with reactor steam dome pressure ≤ 150 psig, and in MODES 4 and 5, RCIC is not required to be OPERABLE since the ECCS injection/spray subsystems can provide sufficient flow to the vessel.

ACTIONS

A.1 and A.2

If the RCIC System is inoperable during MODE 1, or MODES 2 or 3 with reactor steam dome pressure > 150 psig, and the HPCS System is immediately verified to be OPERABLE, the RCIC System must be restored to OPERABLE status within 14 days. In this Condition, loss of the RCIC System will not affect

(continued)

BASES

ACTIONS

A.1 and A.2 (continued)

the overall plant capability to provide makeup inventory at high RPV pressure since the HPCS System is the only high pressure system assumed to function during a loss of coolant accident (LOCA). OPERABILITY of the HPCS is therefore immediately verified when the RCIC System is inoperable. This may be performed as an administrative check, by examining logs or other information, to determine if the HPCS is out of service for maintenance or other reasons. Verification does not require performing the Surveillances needed to demonstrate the OPERABILITY of the HPCS System. If the OPERABILITY of the HPCS System cannot be immediately verified, however, Condition B must be entered. For transients and certain abnormal events with no LOCA, RCIC (as opposed to HPCS) is the preferred source of makeup coolant because of its relatively small capacity, which allows easier control of RPV water level. Therefore, a limited time is allowed to restore the inoperable RCIC to OPERABLE status.

The 14 day Completion Time is based on a reliability study (Ref. 3) that evaluated the impact on ECCS availability, assuming that various components and subsystems were taken out of service. The results were used to calculate the average availability of ECCS equipment needed to mitigate the consequences of a LOCA as a function of allowed outage times (AOTs). Because of the similar functions of the HPCS and RCIC, the AOTs (i.e., Completion Times) determined for the HPCS are also applied to RCIC.

B.1 and B.2

If the RCIC System cannot be restored to OPERABLE status within the associated Completion Time, or if the HPCS System is simultaneously inoperable, the plant must be brought to a condition in which the LCO does not apply. To achieve this status, the plant must be brought to at least MODE 3 within 12 hours and reactor steam dome pressure reduced to ≤ 150 psig within 36 hours. The allowed Completion Times are reasonable, based on operating experience, to reach the required plant conditions from full power conditions in an orderly manner and without challenging plant systems.

(continued)

BASES (continued)

SURVEILLANCE REQUIREMENTS

SR 3.5.3.1

The flow path piping has the potential to develop voids and pockets of entrained air. Maintaining the pump discharge line of the RCIC System full of water ensures that the system will perform properly, injecting its full capacity into the Reactor Coolant System upon demand. This will also prevent a water hammer following an initiation signal. One acceptable method of ensuring the line is full is to vent at the high points. The 31 day Frequency is based on the gradual nature of void buildup in the RCIC piping, the procedural controls governing system operation, and operating experience.

SR 3.5.3.2

Verifying the correct alignment for manual, power operated, and automatic valves (including the RCIC pump flow controller) in the RCIC flow path provides assurance that the proper flow path will exist for RCIC operation. This SR does not apply to valves that are locked, sealed, or otherwise secured in position since these were verified to be in the correct position prior to locking, sealing, or securing. A valve that receives an initiation signal is allowed to be in a nonaccident position provided the valve will automatically reposition in the proper stroke time. This SR does not require any testing or valve manipulation; rather, it involves verification that those valves capable of potentially being mispositioned are in the correct position. This SR does not apply to valves that cannot be inadvertently misaligned, such as check valves. For the RCIC System, this SR also includes the steam flow path for the turbine and the flow controller position.

The 31 day Frequency of this SR was derived from the Inservice Testing Program requirements for performing valve testing at least every 92 days. The Frequency of 31 days is further justified because the valves are operated under procedural control and because improper valve position would affect only the RCIC System. This Frequency has been shown to be acceptable through operating experience.

(continued)

BASES

SURVEILLANCE REQUIREMENTS (continued)

SR 3.5.3.3 and SR 3.5.3.4

The RCIC pump flow rates ensure that the system can maintain reactor coolant inventory during pressurized conditions with the RPV isolated. The flow tests for the RCIC System are performed at two different pressure ranges such that system capability to provide rated flow against a test line pressure corresponding to reactor pressure is tested both at the higher and lower operating ranges of the system. The required system head should overcome the RPV pressure and associated discharge line losses. Adequate reactor steam pressure must be available to perform these tests. Additionally, adequate steam flow must be passing through the main turbine or turbine bypass valves to continue to control reactor pressure when the RCIC System diverts steam flow. Therefore, sufficient time is allowed after adequate pressure and flow are achieved to perform these SRs. Reactor steam pressure must be $\geq$ 920 psig to perform SR 3.5.3.3 and $\geq$ 135 psig to perform SR 3.5.3.4. Adequate steam flow is represented by at least one turbine bypass valve opened 50%. Reactor startup is allowed prior to performing the low pressure Surveillance because the reactor pressure is low and the time to satisfactorily perform the Surveillance is short. The reactor pressure is allowed to be increased to normal operating pressure since it is assumed that the low pressure test has been satisfactorily completed and there is no indication or reason to believe that RCIC is inoperable. Therefore, these SRs are modified by Notes that state the Surveillances are not required to be performed until 12 hours after the reactor steam pressure and flow are adequate to perform the test. The 12 hours allowed for the flow tests after the required pressure and flow are reached are sufficient to achieve stable conditions for testing and provides a reasonable time to complete the SRs.

A 92 day Frequency for SR 3.5.3.3 is consistent with the Inservice Testing Program requirements. The 24 month Frequency for SR 3.5.3.4 is based on the need to perform this Surveillance under the conditions that apply during startup from a plant outage. Operating experience has shown that these components usually pass the SR when performed at the 24 month Frequency, which is based on the refueling cycle. Therefore, the Frequency was concluded to be acceptable from a reliability standpoint.

(continued)

BASES

SURVEILLANCE REQUIREMENTS (continued)

SR 3.5.3.5

The RCIC System is required to actuate automatically to perform its design function. This Surveillance verifies that with a required system initiation signal (actual or simulated) the automatic initiation logic of RCIC will cause the system to operate as designed, i.e., actuation of the system throughout its emergency operating sequence, which includes automatic pump startup and actuation of all automatic valves to their required positions. This Surveillance also ensures that the RCIC System will automatically restart on an actual or simulated RPV low water level (Level 2) signal received subsequent to an actual or simulated RPV high water level (Level 8) shutdown signal, and that the suction is automatically transferred from the CST to the suppression pool. The LOGIC SYSTEM FUNCTIONAL TEST performed in LCO 3.3.5.2 overlaps this Surveillance to provide complete testing of the assumed design function.

While this Surveillance can be performed with the reactor at power, operating experience has shown that these components usually pass the SR when performed at the 24 month Frequency, which is based on the refueling cycle. Therefore, the Frequency was concluded to be acceptable from a reliability standpoint.

This SR is modified by a Note that excludes vessel injection during the Surveillance. Since all active components are testable and full flow can be demonstrated by recirculation through the test line, coolant injection into the RPV is not required during the Surveillance.

REFERENCES

1. 10 CFR 50, Appendix A, GDC 33.

2. UFSAR, Section 5.4.6.2.

3. Memorandum from R.L. Baer (NRC) to V. Stello, Jr. (NRC), "Recommended Interim Revisions to LCO's for ECCS Components," December 1, 1975.

B 3.6 CONTAINMENT SYSTEMS

B 3.6.1.1 Primary Containment

BASES

BACKGROUND

The function of the primary containment is to isolate and contain fission products released from the Reactor Primary System following a design basis Loss of Coolant Accident (LOCA) and to confine the postulated release of radioactive material to within limits. The primary containment consists of a steel lined, reinforced concrete vessel, which surrounds the Reactor Primary System and provides an essentially leak tight barrier against an uncontrolled release of radioactive material to the environment. Additionally, this structure provides shielding from the fission products that may be present in the primary containment atmosphere following accident conditions.

The isolation devices for the penetrations in the primary containment boundary are a part of the primary containment leak tight barrier. To maintain this leak tight barrier:

a. All penetrations required to be closed during accident conditions are either:

   1. capable of being closed by an OPERABLE automatic containment isolation system, or

   2. closed by manual valves, blind flanges, or de-activated automatic valves secured in their closed positions, except as provided in LCO 3.6.1.3, "Primary Containment Isolation Valves (PCIVs)";

b. Primary containment air locks are OPERABLE, except as provided in LCO 3.6.1.2, "Primary Containment Air Locks";

c. All equipment hatches are closed and sealed; and

d. The sealing mechanism associated with each primary containment penetration (e.g., welds, bellows, or O-rings) is OPERABLE.

(continued)

BASES

BACKGROUND (continued)

This Specification ensures that the performance of the primary containment, in the event of a Design Basis Accident (DBA), meets the assumptions used in the safety analyses of References 1 and 2. SR 3.6.1.1.1 leakage rate requirements are in conformance with 10 CFR 50, Appendix J (Ref. 3), Option B, as modified by approved exemptions.

APPLICABLE SAFETY ANALYSES

The safety design basis for the primary containment is that it must withstand the pressures and temperatures of the limiting DBA without exceeding the design leakage rate.

The DBA that postulates the maximum release of radioactive material within primary containment is a LOCA. In the analysis of this accident, it is assumed that primary containment is OPERABLE such that release of fission products to the environment is controlled by the rate of primary containment leakage.

Analytical methods and assumptions involving the primary containment are presented in References 1 and 2. The safety analyses assume a nonmechanistic fission product release following a DBA, which forms the basis for determination of offsite doses. The fission product release is, in turn, based on an assumed leakage rate from the primary containment. OPERABILITY of the primary containment ensures that the leakage rate assumed in the safety analyses is not exceeded.

The maximum allowable leakage rate for the primary containment (L_a) is 0.635% by weight of the containment air per 24 hours at the design basis LOCA maximum peak containment pressure (P_a) of 39.9 psig (Ref. 4).

Primary containment satisfies Criterion 3 of 10 CFR 50.36(c)(2)(ii).

LCO

Primary containment OPERABILITY is maintained by limiting leakage to $\leq$ 1.0 L_a, except prior to the first startup after performing a required Primary Containment Leakage Rate Testing Program leakage test. At this time, the applicable leakage limits must be met. In addition, the leakage from the drywell to the suppression chamber must be limited to ensure the primary containment pressure does not exceed

(continued)

BASES

LCO (continued)

design limits. Compliance with this LCO will ensure a primary containment configuration, including equipment hatches, that is structurally sound and that will limit leakage to those leakage rates assumed in the safety analysis. Individual leakage rates specified for the primary containment air locks are addressed in LCO 3.6.1.2.

APPLICABILITY

In MODES 1, 2, and 3, a DBA could cause a release of radioactive material to primary containment. In MODES 4 and 5, the probability and consequences of these events are reduced due to the pressure and temperature limitations of these MODES. Therefore, primary containment is not required to be OPERABLE in MODES 4 and 5 to prevent leakage of radioactive material from primary containment.

ACTIONS

A.1

In the event that primary containment is inoperable, primary containment must be restored to OPERABLE status within 1 hour. The 1 hour Completion Time provides a period of time to correct the problem that is commensurate with the importance of maintaining primary containment OPERABILITY during MODES 1, 2, and 3. This time period also ensures that the probability of an accident (requiring primary containment OPERABILITY) occurring during periods where primary containment is inoperable is minimal.

B.1 and B.2

If primary containment cannot be restored to OPERABLE status within the associated Completion Time, the plant must be brought to a MODE in which the LCO does not apply. To achieve this status, the plant must be brought to at least MODE 3 within 12 hours and to MODE 4 within 36 hours. The allowed Completion Times are reasonable, based on operating experience, to reach the required plant conditions from full power conditions in an orderly manner and without challenging plant systems.

(continued)

BASES (continued)

SURVEILLANCE REQUIREMENTS

SR 3.6.1.1.1

Maintaining the primary containment OPERABLE requires compliance with the visual examinations and leakage rate test requirements of the Primary Containment Leakage Rate Testing Program. Failure to meet air lock leakage testing limit (SR 3.6.1.2.1), or main steam isolation valve leakage limit (SR 3.6.1.3.10) does not necessarily result in a failure of this SR. The impact of the failure to meet these SRs must be evaluated against the Type A, B, and C acceptance criteria of the Primary Containment Leakage Rate Testing Program.

As left leakage prior to the first startup after performing a required Primary Containment Leakage Rate Testing Program leakage test is required to be $< 0.6\ L_a$ for combined Type B and C leakage, and $\leq 0.75\ L_a$ for overall Type A leakage. At all other times between required leakage rate tests, the acceptance criteria is based on an overall Type A leakage limit of $\leq 1.0\ L_a$. At $\leq 1.0\ L_a$ the offsite dose consequences are bounded by the assumptions of the safety analysis. The Frequency is required by the Primary Containment Leakage Rate Testing Program.

SR 3.6.1.1.2

The structural integrity of the primary containment is ensured by the successful completion of the Inservice Inspection Program for Post Tensioning Tendons and by associated visual inspections of the steel liner and penetrations for evidence of deterioration or breach of integrity. This ensures that the structural integrity of the primary containment will be maintained in accordance with the provisions of the Inservice Inspection Program for Post Tensioning Tendons. Testing and Frequency are consistent with the recommendations of Regulatory Guide 1.35 (Ref. 5), except that the Unit 1 and 2 primary containments shall be treated as twin containments even though the Initial Structural Integrity tests were not within two years of each other.

(continued)

BASES

SURVEILLANCE REQUIREMENTS (continued)

SR 3.6.1.1.3

Maintaining the pressure suppression function of the primary containment requires limiting the leakage from the drywell to the suppression chamber. Thus, if an event were to occur that pressurized the drywell, the steam would be directed through the downcomers into the suppression pool. This SR measures drywell-to-suppression chamber differential pressure during a 1 hour period to ensure that the leakage paths that would bypass the suppression pool are within allowable limits.

Satisfactory performance of this SR can be achieved by establishing a known differential pressure ($\geq$ 1.5 psid) between the drywell and the suppression chamber and verifying that the measured bypass leakage is $\leq$ 10% of the acceptable $A/\sqrt{k}$ design value of 0.030 ft^2. The leakage test is performed every 24 months. The 24 month Frequency was developed considering it is prudent that this Surveillance be performed during a unit outage and also in view of the fact that component failures that might have affected this test are identified by other primary containment SRs. Two consecutive test failures, however, would indicate unexpected primary containment degradation, in this event, as the Note indicates, increasing the Frequency to once every 12 months is required until the situation is remedied as evidenced by passing two consecutive tests.

REFERENCES

1. UFSAR, Section 6.2.

2. UFSAR, Section 15.6.5.

3. 10 CFR 50, Appendix J, Option B.

4. UFSAR, Section 6.2.6.1.

5. Regulatory Guide 1.35, Revision 3.

B 3.6 CONTAINMENT SYSTEMS

B 3.6.1.2 Primary Containment Air Lock

BASES

BACKGROUND

A double-door primary containment air lock has been built into the primary containment to provide personnel access to the primary containment and to provide primary containment isolation during the process of personnel entry and exit. The air lock is designed to withstand the same loads, temperatures, and peak design internal and external pressures as the primary containment (Ref. 1). As part of the primary containment, the air lock limits the release of radioactive material to the environment during normal unit operation and through a range of transients and accidents up to and including postulated Design Basis Accidents (DBAs).

Each air lock door has been designed and tested to certify its ability to withstand pressure in excess of the maximum expected pressure following a DBA in primary containment. Each of the doors has double, compressible seals and local leak rate testing capability to ensure pressure integrity. To effect a leak tight seal, the air lock design uses pressure sealed doors (i.e., an increase in primary containment internal pressure results in an increased sealing on each door.).

The air lock is nominally a right circular cylinder, 10 ft in diameter, with doors at each end that are interlocked to prevent simultaneous opening. The air lock is provided with limit switches on both doors that provide remote indication of door position via an alarm in the control room that indicates when an air lock door is open. During periods when primary containment is not required to be OPERABLE, the air lock interlock mechanism may be disabled, allowing both doors of the air lock to remain open for extended periods when frequent primary containment entry is necessary. Under some conditions, as allowed by this LCO, the primary containment may be accessed through the air lock when the door interlock mechanism has failed, by manually performing the interlock function.

The primary containment air lock forms part of the primary containment pressure boundary. As such, air lock integrity and leak tightness are essential for maintaining primary

(continued)

BASES

BACKGROUND (continued)

containment leakage rate to within limits in the event of a DBA. Not maintaining air lock integrity or leak tightness may result in a leakage rate in excess of that assumed in the safety analysis.

APPLICABLE SAFETY ANALYSES

The DBA that postulates the maximum release of radioactive material within primary containment is a LOCA. In the analysis of this accident, it is assumed that primary containment is OPERABLE, such that release of fission products to the environment is controlled by the rate of primary containment leakage. The primary containment is designed with a maximum allowable leakage rate (L_a) of 0.635% by weight of the containment air mass per 24 hours at the Design Basis LOCA maximum peak containment pressure (P_a) of 39.9 psig (Ref. 2). This allowable leakage rate forms the basis for the acceptance criteria imposed on the SRs associated with the air lock.

Primary containment air lock OPERABILITY is also required to minimize the amount of fission product gases that may escape primary containment through the air lock and contaminate and pressurize the secondary containment.

Primary containment air lock satisfies Criterion 3 of the 10 CFR 50.36(c)(2)(ii).

LCO

As part of the primary containment pressure boundary, the air lock safety function is related to control of containment leakage following a DBA. Thus, the air lock structural integrity and leak tightness are essential to the successful mitigation of such an event.

The primary containment air lock is required to be OPERABLE. For the air lock to be considered OPERABLE, the air lock interlock mechanism must be OPERABLE, the air lock must be in compliance with the Type B air lock leakage test, and both air lock doors must be OPERABLE. The interlock allows only one air lock door to be open at a time. This provision ensures that a gross breach of primary containment does not exist when primary containment is required to be OPERABLE. Closure of a single door in the air lock is sufficient to

(continued)

BASES

LCO (continued)

provide a leak tight barrier following postulated events. Nevertheless, both doors are kept closed when the air lock is not being used for normal entry into or exit from primary containment.

APPLICABILITY

In MODES 1, 2, and 3, a DBA could cause a release of radioactive material to primary containment. In MODES 4 and 5, the probability and consequences of these events are reduced due to the pressure and temperature limitations of these MODES. Therefore, the primary containment air lock is not required to be OPERABLE in MODES 4 and 5 to prevent leakage of radioactive material from primary containment.

ACTIONS

The ACTIONS are modified by Note 1, which allows entry and exit to perform repairs of the affected air lock component. If the outer door is inoperable, then it may be easily accessed for most repairs. If the inner door is the one that is inoperable, however, then a short time exists when the primary containment boundary is not intact (during access through the OPERABLE door). The allowance to open the OPERABLE door, even if it means the primary containment boundary is temporarily not intact, is acceptable due to the low probability of an event that could pressurize the primary containment during the short time in which the OPERABLE door is expected to be open. The required administrative controls consist of stationing a dedicated individual to assure closure of the OPERABLE door except during the entry and exit and to assure the OPERABLE door is relocked after completion of the containment entry and exit.

The ACTIONS are modified by a second Note, which ensures appropriate remedial actions are taken when necessary, if airlock leakage results in exceeding overall containment leakage rate acceptance criteria. Pursuant to LCO 3.0.6, ACTIONS are not required even if primary containment leakage is exceeding leakage L_a. Therefore, the Note is added to require ACTIONS for LCO 3.6.1.1, "Primary Containment," to be taken in this event.

(continued)

BASES

ACTIONS (continued)

A.1, A.2, and A.3

With one primary containment air lock door inoperable, the OPERABLE door must be verified closed (Required Action A.1). This ensures that a leak tight primary containment barrier is maintained by the use of an OPERABLE air lock door. This action must be completed within 1 hour. The 1 hour Completion Time is consistent with the ACTIONS of LCO 3.6.1.1, which requires that primary containment be restored to OPERABLE status within 1 hour.

In addition, the air lock penetration must be isolated by locking closed the OPERABLE air lock door within the 24 hour Completion Time. The 24 hour Completion Time is considered reasonable for locking the OPERABLE air lock door, considering the OPERABLE door of the air lock is being maintained closed.

Required Action A.3 ensures that the air lock penetration has been isolated by the use of a locked closed OPERABLE air lock door. This ensures that an acceptable primary containment leakage boundary is maintained. The Completion Time of once per 31 days is based on engineering judgment and is considered adequate given the low likelihood of a locked door being mispositioned and other administrative controls. Required Action A.3 is modified by a Note that applies to air lock doors located in high radiation areas or areas with limited access due to inerting and allows these doors to be verified locked closed by use of administrative controls. Allowing verification by administrative controls is considered acceptable, since access to these areas is typically restricted. Therefore, the probability of misalignment of the door, once it has been verified to be in the proper position, is small.

The Required Actions have been modified by two Notes. Note 1 ensures that only the Required Actions and associated Completion Times of Condition C are required if both doors in the air lock are inoperable. With both doors in the air lock inoperable, an OPERABLE door is not available to be closed. Required Actions C.1 and C.2 are the appropriate remedial actions. The exception of Note 1 does not affect tracking the Completion Time from the initial entry into Condition A; only the requirement to comply with the

(continued)

BASES

ACTIONS

A.1, A.2, and A.3 (continued)

Required Actions. Note 2 allows use of the air lock for entry and exit for 7 days under administrative controls. This 7 day restriction begins when the air lock is discovered inoperable.

Primary containment entry may be required to perform Technical Specifications (TS) Surveillances and Required Actions, as well as other activities inside primary containment that are required by TS or activities that support TS-required equipment. This Note is not intended to preclude performing other activities (i.e., non-TS-related activities) if the primary containment was entered, using the inoperable air lock, to perform an allowed activity listed above. The required administrative controls consist of stationing a dedicated individual to assure closure of the OPERABLE door except during periods of entry and exit, and to assure the OPERABLE door is relocked after completion of the containment entry and exit This allowance is acceptable due to the low probability of an event that could pressurize the primary containment during the short time that the OPERABLE door is expected to be open.

B.1, B.2, and B.3

With the air lock interlock mechanism inoperable, the Required Actions and associated Completion Times are consistent with those specified in Condition A.

The Required Actions have been modified by two Notes. Note 1 ensures that only the Required Actions and associated Completion Times of Condition C are required if both doors in the air lock are inoperable. With both doors in the air lock inoperable, an OPERABLE door is not available to be closed. Required Actions C.1 and C.2 are the appropriate remedial actions. Note 2 allows entry into and exit from the primary containment under the control of a dedicated individual stationed at the air lock to ensure that only one door is opened at a time (i.e., the individual performs the function of the interlock).

Required Action B.3 is modified by a Note that applies to air lock doors located in high radiation areas or areas with limited access due to inerting and allows these doors to be

(continued)

BASES

ACTIONS

B.1, B.2, and B.3 (continued)

verified locked closed by use of administrative controls. Allowing verification by administrative controls is considered acceptable, since access to these areas is typically restricted. Therefore, the probability of misalignment of the door, once it has been verified to be in the proper position, is small.

C.1, C.2, and C.3

With the air lock inoperable for reasons other than those described in Condition A or B, Required Action C.1 requires action to be immediately initiated to evaluate containment overall leakage rates using current air lock leakage test results. An evaluation is acceptable since it is overly conservative to immediately declare the primary containment inoperable if both doors in the air lock have failed a seal test or if the overall air lock leakage is not within limits. In many instances (e.g., only one seal per door has failed) primary containment remains OPERABLE, yet only 1 hour (according to LCO 3.6.1.1) would be provided to restore the air lock door to OPERABLE status prior to requiring a plant shutdown. In addition, even with both doors failing the seal test, the overall containment leakage rate can still be within limits.

Required Action C.2 requires that one door in the primary containment air locks must be verified closed. This Required Action must be completed within the 1 hour Completion Time. This specified time period is consistent with the ACTIONS of LCO 3.6.1.1, which require that primary containment be restored to OPERABLE status within 1 hour.

Additionally, the air lock must be restored to OPERABLE status within 24 hours (Required Action C.3). The 24 hour Completion Time is reasonable for restoring the inoperable air lock to OPERABLE status considering that at least one door is maintained closed in the air lock.

(continued)

BASES

ACTIONS (continued)

D.1 and D.2

If the inoperable primary containment air lock cannot be restored to OPERABLE status within the associated Completion Time, the plant must be brought to a MODE in which the LCO does not apply. To achieve this status, the plant must be brought to at least MODE 3 within 12 hours and to MODE 4 within 36 hours. The allowed Completion Times are reasonable, based on operating experience, to reach the required plant conditions from full power conditions in an orderly manner and without challenging plant systems.

SURVEILLANCE REQUIREMENTS

SR 3.6.1.2.1

Maintaining the primary containment air lock OPERABLE requires compliance with the leakage rate test requirements of the Primary Containment Leakage Rate Testing Program. This SR reflects the leakage rate testing requirements with regard to air lock leakage (Type B leakage tests). The acceptance criteria were established as a small fraction of the total allowable primary containment leakage. The periodic testing requirements verify that the air lock leakage does not exceed the allowed fraction of the overall primary containment leakage rate. The Frequency is required by the Primary Containment Leakage Rate Testing Program.

The SR has been modified by two Notes. Note 1 states that an inoperable air lock door does not invalidate the previous successful performance of the overall air lock leakage test. This is considered reasonable since either air lock door is capable of providing a fission product barrier in the event of a DBA. Note 2 has been added to this SR, requiring the results to be evaluated against the acceptance criteria which is applicable to SR 3.6.1.1.1. This ensures that air lock leakage is properly accounted for in determining the combined Types B and C primary containment leakage rate.

SR 3.6.1.2.2

The air lock interlock mechanism is designed to prevent simultaneous opening of both doors in the air lock. Since both the inner and outer doors of the air lock are designed to withstand the maximum expected post accident primary

(continued)

BASES

SURVEILLANCE REQUIREMENTS

SR 3.6.1.2.2 (continued)

containment pressure (Ref. 2), closure of either door will support primary containment OPERABILITY. Thus, the interlock feature supports primary containment OPERABILITY while the air lock is being used for personnel transit in and out of the containment. Periodic testing of this interlock demonstrates that the interlock will function as designed and that simultaneous inner and outer door opening will not inadvertently occur. Due to the purely mechanical nature of this interlock, and given that the interlock mechanism is not normally challenged when the primary containment air lock door is used for entry and exit (procedures require strict adherence to single door opening), this test is only required to be performed every 24 months. The 24 month Frequency is based on the need to perform this Surveillance under the conditions that apply during a plant outage, and the potential for loss of primary containment OPERABILITY if the Surveillance were performed with the reactor at power. Operating experience has shown these components usually pass the Surveillance when performed at the 24 month Frequency. The 24 month Frequency is based on engineering judgment and is considered adequate given that the interlock is not challenged during use of the air lock.

REFERENCES

1. UFSAR, Section 3.8.1.1.3.5.1.

2. UFSAR, Section 6.2.6.1.

B 3.6 CONTAINMENT SYSTEMS

B 3.6.1.3 Primary Containment Isolation Valves (PCIVs)

BASES

BACKGROUND

The function of the PCIVs, in combination with other accident mitigation systems, is to limit fission product release during and following postulated Design Basis Accidents (DBAs) to within limits. Primary containment isolation within the time limits specified for those PCIVs designed to close automatically ensures that the release of radioactive material to the environment will be consistent with the assumptions used in the analyses for a DBA.

The OPERABILITY requirements for PCIVs help ensure that an adequate primary containment boundary is maintained during and after an accident by minimizing potential paths to the environment. Therefore, the OPERABILITY requirements provide assurance that the primary containment function assumed in the safety analysis will be maintained. These isolation devices consist of either passive devices or active (automatic) devices. Manual valves, de-activated automatic valves secured in their closed position (including check valves with flow through the valve secured), blind flanges (which include plugs and caps as listed in Reference 1), and closed systems are considered passive devices. Check valves, or other automatic valves designed to close without operator action following an accident, are considered active devices. Two barriers in series are provided for each penetration, except for penetrations isolated by excess flow check valves, so that no single credible failure or malfunction of an active component can result in a loss of isolation or leakage that exceeds limits assumed in the safety analysis. One of these barriers may be a closed system.

The 8 and 26 inch primary containment purge valves are PCIVs that are qualified for use during all operational conditions. The 8 and 26 inch primary containment purge valves are normally maintained closed in MODES 1, 2, and 3 to ensure the primary containment boundary is maintained. However, these purge valves may be open when being used for inerting, de-inerting pressure control, ALARA, or air quality considerations since they are fully qualified.

(continued)

BASES (continued)

APPLICABLE SAFETY ANALYSES

The PCIVs LCO was derived from the assumptions related to minimizing the loss of reactor coolant inventory, and establishing the primary containment boundary during major accidents. As part of the primary containment boundary, PCIV OPERABILITY supports leak tightness of primary containment. Therefore, the safety analysis of any event requiring isolation of primary containment is applicable to this LCO.

The DBAs that result in a release of radioactive material for which the consequences are mitigated by PCIVs are a loss of coolant accident (LOCA) and a main steam line break (MSLB) (Refs. 2 and 3). In the analysis for each of these accidents, it is assumed that PCIVs are either closed or function to close within the required isolation time following event initiation. This ensures that potential paths to the environment through PCIVs (including primary containment purge valves) are minimized. Of the events analyzed in References 2 and 3, the LOCA is the most limiting event due to radiological consequences. For the MSLB, the closure time of the main steam isolation valves (MSIVs) is a significant variable from a radiological standpoint. The MSIVs are required to close within 3 to 5 seconds since the 3 second closure time is assumed in the MSIV closure (the most severe overpressurization transient) analysis (Ref. 4) and the 5 second closure time is assumed in the MSLB analysis (Ref. 3). Likewise, it is assumed that the primary containment isolates such that release of fission products to the environment is controlled.

The DBA analysis assumes that isolation of the primary containment is complete and leakage terminated, except for the maximum allowable leakage prior to fuel damage.

The single failure criterion required to be imposed in the conduct of unit safety analyses was considered in the original design of the primary containment purge valves. Two valves in series on each purge line provide assurance that both the supply and exhaust lines could be isolated even if a single failure occurred.

PCIVs satisfy Criterion 3 of 10 CFR 50.36(c)(2)(ii).

(continued)

BASES (continued)

LCO

PCIVs form a part of the primary containment boundary. The PCIV safety function is related to minimizing the loss of reactor coolant inventory and establishing the primary containment boundary during a DBA.

The power operated, automatic isolation valves are required to have isolation times within limits and actuate on an automatic isolation signal. The valves covered by this LCO are listed with their associated stroke times in the Technical Requirements Manual (Ref. 1).

The normally closed manual PCIVs are considered OPERABLE when the valves are closed and blind flanges are in place, or open under administrative controls. Normally closed automatic PCIVs which are required by design (e.g., to meet 10 CFR 50 Appendix R requirements) to be de-activated and closed, are considered OPERABLE when the valves are de-activated and closed. These passive isolation valves and devices are those listed in Reference 1. MSIVs and hydrostatically tested valves must meet additional leakage rate requirements. Other PCIV leakage rates are addressed by LCO 3.6.1.1, "Primary Containment," as Type B or C testing.

This LCO provides assurance that the PCIVs will perform their designed safety functions to minimize the loss of reactor coolant inventory and establish the primary containment boundary during accidents.

APPLICABILITY

In MODES 1, 2, and 3, a DBA could cause a release of radioactive material to primary containment. In MODES 4 and 5, the probability and consequences of these events are reduced due to the pressure and temperature limitations of these MODES. Therefore, most PCIVs are not required to be OPERABLE and the primary containment purge valves are not required to be normally closed in MODES 4 and 5. Certain valves are required to be OPERABLE, however, to prevent inadvertent reactor vessel draindown. These valves are those whose associated instrumentation is required to be OPERABLE according to LCO 3.3.6.1, "Primary Containment Isolation Instrumentation." (This does not include the valves that isolate the associated instrumentation.)

(continued)

BASES (continued)

ACTIONS

The ACTIONS are modified by a Note allowing penetration flow path(s) to be unisolated intermittently under administrative controls. These controls consist of stationing a dedicated operator at the controls of the valve, who is in continuous communication with the control room. In this way, the penetration can be rapidly isolated when a need for primary containment isolation is indicated.

A second Note has been added to provide clarification that, for the purpose of this LCO, separate Condition entry is allowed for each penetration flow path. This is acceptable, since the Required Actions for each Condition provide appropriate compensatory actions for each inoperable PCIV. Complying with the Required Actions may allow for continued operation, and subsequent inoperable PCIVs are governed by subsequent Condition entry and application of associated Required Actions.

The ACTIONS are modified by Notes 3 and 4. Note 3 ensures appropriate remedial actions are taken, if necessary, if the affected system(s) are rendered inoperable by an inoperable PCIV (e.g., an Emergency Core Cooling System subsystem is inoperable due to a failed open test return valve). Note 4 ensures appropriate remedial actions are taken when the primary containment leakage limits are exceeded. Pursuant to LCO 3.0.6, these ACTIONS are not required even when the associated LCO is not met. Therefore, Notes 3 and 4 are added to require the proper actions be taken.

A.1 and A.2

With one or more penetration flow paths with one PCIV inoperable, except for MSIV leakage rate or hydrostatically tested line leakage rate not within limit, the affected penetration flow path must be isolated. The method of isolation must include the use of at least one isolation barrier that cannot be adversely affected by a single active failure. Isolation barriers that meet this criterion are a closed and de-activated automatic valve, a closed manual valve, a blind flange, and a check valve with flow through the valve secured. For penetrations isolated in accordance with Required Action A.1, the device used to isolate the

(continued)

BASES

ACTIONS

A.1 and A.2 (continued)

penetration should be the closest available one to the primary containment. The Required Action must be completed within the 4 hour Completion Time (8 hours for main steam lines). The specified time period of 4 hours is reasonable considering the time required to isolate the penetration and the relative importance of supporting primary containment OPERABILITY during MODES 1, 2, and 3. For main steam lines, an 8 hour Completion Time is allowed. The Completion Time of 8 hours for the main steam lines allows a period of time to restore the MSIVs to OPERABLE status given the fact that MSIV closure will result in isolation of the main steam line(s) and a potential for plant shutdown.

For affected penetrations that have been isolated in accordance with Required Action A.1, the affected penetration flow path must be verified to be isolated on a periodic basis. This is necessary to ensure that primary containment penetrations required to be isolated following an accident, and no longer capable of being automatically isolated, will be in the isolation position should an event occur. This Required Action does not require any testing or device manipulation. Rather, it involves verification that those devices outside the primary containment and capable of being mispositioned are in the correct position. The Completion Time for this verification of "once per 31 days for isolation devices outside primary containment" is appropriate because the devices are operated under administrative controls and the probability of their misalignment is low. For devices inside the primary containment, the specified time period of "prior to entering MODE 2 or 3 from MODE 4 if primary containment was de-inerted while in MODE 4, if not performed within the previous 92 days," is based on engineering judgment and is considered reasonable in view of the inaccessibility of the devices and the existence of other administrative controls ensuring that device misalignment is an unlikely possibility.

Condition A is modified by a Note indicating that this Condition is only applicable to those penetration flow paths with two or more PCIVs. For penetration flow paths with one PCIV, Condition C provides appropriate Required Actions.

(continued)

BASES

ACTIONS

A.1 and A.2 (continued)

Required Action A.2 is modified by two Notes. Note 1 applies to isolation devices located in high radiation areas and allows them to be verified by use of administrative means. Allowing verification by administrative means is considered acceptable, since access to these areas is typically restricted. Note 2 applies to isolation devices that are locked, sealed, or otherwise secured in position and allows these devices to be verified closed by use of administrative means. Allowing verification by administrative means is considered acceptable, since the function of locking, sealing, or securing components is to ensure that these devices are not inadvertently repositioned. Therefore, the probability of misalignment, once they have been verified to be in the proper position, is low.

B.1

With one or more penetration flow paths with two or more PCIVs inoperable, except for MSIV leakage rate or hydrostatically tested line leakage rate not within limit, either the inoperable PCIVs must be restored to OPERABLE status or the affected penetration flow path must be isolated within 1 hour. The method of isolation must include the use of at least one isolation barrier that cannot be adversely affected by a single active failure. Isolation barriers that meet this criterion are a closed and de-activated automatic valve, a closed manual valve, and a blind flange. The 1 hour Completion Time is consistent with the ACTIONS of LCO 3.6.1.1.

Condition B is modified by a Note indicating this Condition is only applicable to penetration flow paths with two or more PCIVs. For penetration flow paths with one PCIV, Condition C provides the appropriate Required Actions.

(continued)

BASES

ACTIONS (continued)

C.1 and C.2

When one or more penetration flow paths with one PCIV inoperable, except for MSIV leakage rate or hydrostatically tested line leakage rate not within limit, the inoperable valve must be restored to OPERABLE status or the affected penetration flow path must be isolated. The method of isolation must include the use of at least one isolation barrier that cannot be adversely affected by a single active failure. Isolation barriers that meet this criterion are a closed and de-activated automatic valve, a closed manual valve, and a blind flange. A check valve may not be used to isolate the affected penetration. The Completion Time of 4 hours for valves other than EFCVs and in penetrations with a closed system is reasonable considering the time required to isolate the penetration and the relative importance of supporting primary containment OPERABILITY during MODES 1, 2, and 3. The Completion Time of 72 hours for penetrations with a closed system is reasonable considering the relative stability of the closed system (hence, reliability) to act as a penetration isolation boundary and the relative importance of supporting primary containment OPERABILITY during MODES 1, 2, and 3. The closed system must meet the requirements of Reference 5. The Completion Time of 72 hours for EFCVs is also reasonable considering the instrument and the small pipe diameter of penetration (hence, reliability) to act as a penetration isolation boundary and the small pipe diameter of the affected penetration. In the event the affected penetration is isolated in accordance with Required Action C.1, the affected penetration flow path must be verified to be isolated on a periodic basis. This is necessary to ensure that primary containment penetrations required to be isolated following an accident are isolated. This Required Action does not require any testing or valve manipulation. Rather, it involves verification that these devices outside containment and capable of potentially being mispositioned are in the correct position. The Completion Time of "once per 31 days" is appropriate because the devices are operated under administrative controls and the probability of their misalignment is low.

(continued)

BASES

ACTIONS

C.1 and C.2 (continued)

Condition C is modified by a Note indicating this Condition is applicable only to those penetration flow paths with only one PCIV. For penetration flow paths with two or more PCIVs, Conditions A and B provide the appropriate Required Actions. This Note is necessary since this Condition is written specifically to address those penetrations with a single PCIV.

Required Action C.2 is modified by two Notes. Note 1 applies to isolation devices located in high radiation areas and allows them to be verified by use of administrative means. Allowing verification by administrative means is considered acceptable, since access to these areas is typically restricted. Note 2 applies to isolation devices that are locked, sealed, or otherwise secured in position and allows these devices to be verified closed by use of administrative means. Allowing verification by administrative means is considered acceptable, since the function of locking, sealing, or securing components is to ensure that these devices are not inadvertently repositioned. Therefore, the probability of misalignment, once they have been verified to be in the proper position, is low.

D.1

With the MSIV leakage rate (SR 3.6.1.3.10) or hydrostatically tested line leakage rate (SR 3.6.1.3.11) not within limit, the assumptions of the safety analysis may not be met. Therefore, the leakage rate must be restored to within limit within the Completion Times appropriate for each type of valve leakage: a) hydrostatically tested line leakage not on a closed system is required to be restored within 4 hours; b) MSIV leakage is required to be restored within 8 hours; and c) hydrostatically tested line leakage on a closed system is required to be restored within 72 hours. Restoration can be accomplished by isolating the penetration that caused the limit to be exceeded by use of one closed and de-activated automatic valve, closed manual valve, or blind flange. When a penetration is isolated, the

(continued)

BASES

ACTIONS

D.1 (continued)

leakage rate for the isolated penetration is assumed to be the actual pathway leakage through the isolation device. If two isolation devices are used to isolate the penetration, the leakage rate is assumed to be the lesser actual pathway leakage of the two devices. The 4 hour Completion Time for hydrostatically tested line leakage not on a closed system is reasonable considering the time required to restore leakage by isolating the penetration and the relative importance of the hydrostatically tested line leakage to the overall containment function. The Completion Time of 8 hours for MSIV leakage allows a period of time to restore the MSIV leakage rate to within limit given the fact that MSIV closure will result in isolation of the main steam line(s) and a potential for plant shutdown. The 72 hour Completion Time for hydrostatically tested line leakage on a closed system is acceptable based on the available water seal expected to remain as a gaseous fission product boundary during the accident, and, in many cases, the associated closed system. The closed system must meet the requirements of Reference 5.

E.1, and E.2

If any Required Action and associated Completion Time cannot be met in MODE 1, 2, or 3, the plant must be brought to a MODE in which the LCO does not apply. To achieve this status, the plant must be brought to at least MODE 3 within 12 hours and to MODE 4 within 36 hours. The allowed Completion Times are reasonable, based on operating experience, to reach the required plant conditions from full power conditions in an orderly manner and without challenging plant systems.

F.1 and F.2

If any Required Action and associated Completion Time cannot be met for PCIV(s) required OPERABLE in MODE 4 or 5, the plant must be placed in a condition in which the LCO does not apply. Action must be immediately initiated to suspend operations with a potential for draining the reactor vessel (OPDRVs) to minimize the probability of a vessel draindown

(continued)

BASES

ACTIONS

F.1 and F.2 (continued)

and subsequent potential for fission product release. Actions must continue until OPDRVs are suspended. If suspending the OPDRVs would result in closing the residual heat removal (RHR) shutdown cooling isolation valves, an alternative Required Action is provided to immediately initiate action to restore the valves to OPERABLE status. This allows RHR shutdown cooling to remain in service while actions are being taken to restore the valve.

SURVEILLANCE REQUIREMENTS

SR 3.6.1.3.1

This SR verifies that the 8 inch and 26 inch primary containment purge valves are closed as required or, if open, opened for an allowable reason.

The SR is modified by a Note stating that the SR is not required to be met when the purge valves are open for the stated reasons. The Note states that these valves may be opened for inerting, de-inerting, pressure control, ALARA, or air quality considerations for personnel entry, or for Surveillances that require the valves to be open, provided the drywell purge valves and suppression chamber purge valves are not open simultaneously. This is required to prevent a bypass path between the suppression chamber and the drywell, which would allow steam and gases from a LOCA to bypass the downcomers to the suppression pool. These primary containment purge valves are capable of closing in the environment following a LOCA. Therefore, these valves are allowed to be open for limited periods of time. The 31 day Frequency is consistent with other primary containment isolation valve requirements discussed in SR 3.6.1.3.2.

SR 3.6.1.3.2

This SR verifies that each primary containment isolation manual valve and blind flange that is located outside primary containment and not locked, sealed, or otherwise secured and is required to be closed during accident conditions, is closed. The SR helps to ensure that post

(continued)

BASES

SURVEILLANCE REQUIREMENTS

SR 3.6.1.3.2 (continued)

accident leakage of radioactive fluids or gases outside of the primary containment boundary is within design limits. This SR does not require any testing or valve manipulation. Rather, it involves verification that those PCIVs outside primary containment, and capable of being mispositioned, are in the correct position. Since verification of position for PCIVs outside primary containment is relatively easy, the 31 day Frequency was chosen to provide added assurance that the PCIVs are in the correct positions. This SR does not apply to valves that are locked, sealed, or otherwise secured in the closed position, since these were verified to be in the correct position upon locking, sealing, or securing.

Two Notes are added to this SR. The first Note applies to valves and blind flanges located in high radiation areas and allows them to be verified by use of administrative controls. Allowing verification by administrative controls is considered acceptable, since access to these areas is typically restricted during MODES 1, 2, and 3 for ALARA reasons. Therefore, the probability of misalignment of these PCIVs, once they have been verified to be in the proper position, is low. A second Note is included to clarify that PCIVs open under administrative controls are not required to meet the SR during the time the PCIVs are open. These controls consist of stationing a dedicated operator at the controls of the valve, who is in continuous communication with the control room. In this way, the penetration can be rapidly isolated when a need for primary containment isolation is indicated.

SR 3.6.1.3.3

This SR verifies that each primary containment manual isolation valve and blind flange located inside primary containment and not locked, sealed, or otherwise secured and required to be closed during accident conditions, is closed. The SR helps to ensure that post accident leakage of radioactive fluids or gases outside the primary containment boundary is within design limits. For PCIVs inside primary

(continued)

BASES

SURVEILLANCE REQUIREMENTS

SR 3.6.1.3.3 (continued)

containment, the Frequency of "prior to entering MODE 2 or 3 from MODE 4 if primary containment was de-inerted while in MODE 4, if not performed within the previous 92 days," is appropriate since these PCIVs are operated under administrative controls and the probability of their misalignment is low. This SR does not apply to valves that are locked, sealed, or otherwise secured in the closed position, since these were verified to be in the correct position upon locking, sealing, or securing.

Two Notes are added to this SR. The first Note allows valves and blind flanges located in high radiation areas to be verified by use of administrative controls. Allowing verification by administrative controls is considered acceptable since the primary containment is inerted and access to these areas is typically restricted during MODES 1, 2, and 3 for ALARA and personnel safety. Therefore, the probability of misalignment of these PCIVs, once they have been verified to be in their proper position, is low. A second Note is included to clarify that PCIVs that are open under administrative controls are not required to meet the SR during the time that the PCIVs are open. These controls consist of stationing a dedicated operator at the controls of the valve, who is in continuous communication with the control room. In this way, the penetration can be rapidly isolated when a need for primary containment isolation is indicated.

SR 3.6.1.3.4

The traversing incore probe (TIP) shear isolation valves are actuated by explosive charges. Surveillance of explosive charge continuity provides assurance that TIP valves will actuate when required. Other administrative controls, such as those that limit the shelf life and operating life, as applicable, of the explosive charges, must be followed. The 31 day Frequency is based on operating experience that has demonstrated the reliability of the explosive charge continuity.

(continued)

BASES

SURVEILLANCE REQUIREMENTS (continued)

SR 3.6.1.3.5

Verifying the isolation time of each power operated, automatic PCIV is within limits is required to demonstrate OPERABILITY. MSIVs may be excluded from this SR since MSIV full closure isolation time is demonstrated by SR 3.6.1.3.6. The isolation time test ensures that each valve will isolate in a time period less than or equal to that assumed in the safety analysis. The Frequency of this SR is in accordance with the Inservice Testing Program.

SR 3.6.1.3.6

Verifying that the full closure isolation time of each MSIV is within the specified limits is required to demonstrate OPERABILITY. The full closure isolation time test ensures that the MSIV will isolate in a time period that does not exceed the times assumed in the DBA and transient analyses. The Frequency of this SR is in accordance with the Inservice Testing Program.

SR 3.6.1.3.7

Automatic PCIVs close on a primary containment isolation signal to prevent leakage of radioactive material from primary containment following a DBA. This SR ensures that each automatic PCIV will actuate to its isolation position on a primary containment isolation signal. The LOGIC SYSTEM FUNCTIONAL TEST in LCO 3.3.6.1, "Primary Containment Isolation Instrumentation," overlaps this SR to provide complete testing of the safety function. The 24 month Frequency is based on the need to perform this Surveillance under the conditions that apply during a plant outage and the potential for an unplanned transient if the Surveillance were performed with the reactor at power. Operating experience has shown that these components usually pass this Surveillance when performed at the 24 month Frequency. Therefore, the Frequency was concluded to be acceptable from a reliability standpoint.

(continued)

BASES

SURVEILLANCE REQUIREMENTS (continued)

SR 3.6.1.3.8

This SR requires a demonstration that each EFCV is OPERABLE by verifying that the valve actuates to the isolation position on an actual or simulated instrument line break condition. This SR provides assurance that the instrumentation line EFCVs will perform as designed. The 24 month Frequency is based on the need to perform this Surveillance under the conditions that apply during a plant outage and the potential for an unplanned transient if the Surveillance were performed with the reactor at power. Operating experience has shown that these components usually pass this Surveillance when performed at the 24 month Frequency. Therefore, the Frequency was concluded to be acceptable from a reliability standpoint.

SR 3.6.1.3.9

The TIP shear isolation valves are actuated by explosive charges. An in place functional test is not possible with this design. The explosive squib is removed and tested to provide assurance that the valves will actuate when required. The replacement charge for the explosive squib shall be from the same manufactured batch as the one fired or from another batch that has been certified by having one of the batch successfully fired. Other administrative controls, such as those that limit the shelf life and operating life, as applicable, of the explosive charges, must be followed. The Frequency of 24 months on a STAGGERED TEST BASIS is considered adequate given the administrative controls on replacement charges and the frequency checks of circuit continuity (SR 3.6.1.3.4).

SR 3.6.1.3.10

The analyses in Reference 2 are based on leakage that is less than the specified leakage rate. Leakage through any one main steam line must be $\leq$ 100 scfh and through all four main steam lines must be $\leq$ 400 scfh when tested at P_t (25.0 psig). This ensures that MSIV leakage is properly accounted for in determining the overall primary containment leakage rate. The Frequency is required by the Primary Containment Leakage Rate Testing Program.

(continued)

BASES

SURVEILLANCE REQUIREMENTS (continued)

SR 3.6.1.3.11

Surveillance of hydrostatically tested lines provides assurance that the calculation assumptions of Reference 2 are met. The acceptance criteria for the combined leakage of all hydrostatically tested lines is 1 gpm times the total number of hydrostatically tested PCIVs when tested at $\geq$ 1.1 P_a. The combined leakage rates must be demonstrated in accordance with the leakage test Frequency required by the Primary Containment Leakage Rate Testing Program.

REFERENCES

1. Technical Requirements Manual.
2. UFSAR, Section 15.6.5.
3. UFSAR, Section 15.6.4.
4. UFSAR, Section 15.2.4.
5. UFSAR, Section 6.2.4.2.3.

B 3.6 CONTAINMENT SYSTEMS

B 3.6.1.4 Drywell and Suppression Chamber Pressure

BASES

BACKGROUND

The drywell and suppression chamber internal pressure is limited during normal operation to preserve the initial conditions assumed in the accident analyses for a Design Basis Accident (DBA) or loss of coolant accident (LOCA).

Transient events, which include inadvertent drywell spray initiation, can reduce the drywell and suppression chamber internal pressure. Without an appropriate limit on the minimum drywell and suppression chamber internal pressure (-0.5 psig), the design limit for negative containment differential pressure of 5.0 psid could be exceeded (Ref. 1).

The limitation on the maximum drywell and suppression chamber internal pressure (0.75 psig) provides added assurance that the peak LOCA drywell and suppression chamber pressure does not exceed the design value of 45 psig (Ref. 1).

APPLICABLE SAFETY ANALYSES

Primary containment performance for the DBA is evaluated for the entire spectrum of break sizes for postulated LOCAs inside containment (Ref. 2). Among the inputs to the design basis analysis is the initial drywell and suppression chamber internal pressure. The initial pressure limitation requirements ensure that peak primary containment pressure for a DBA LOCA does not exceed the design value of 45 psig and that peak negative pressure for an inadvertent drywell spray event does not exceed the design value of 5.0 psid.

Primary containment pressure satisfies Criterion 2 of 10 CFR 50.36(c)(2)(ii).

LCO

A limitation on the drywell and suppression chamber internal pressure of $\geq$ -0.5 psig and $\leq$ +0.75 psig is required to ensure that primary containment initial conditions are consistent with the initial safety analyses assumptions so

(continued)

BASES

LCO (cont'd)

that containment pressures remain within design values during a LOCA and the design value of containment negative pressure is not exceeded during an inadvertent operation of drywell sprays.

APPLICABILITY

In MODES 1, 2, and 3, a DBA could result in a release of radioactive material to primary containment. In MODES 4 and 5, the probability and consequences of these events are reduced due to the pressure and temperature limitations of these MODES. Therefore, maintaining drywell and suppression chamber internal pressure within limits is not required in MODE 4 or 5.

ACTIONS

A.1

When drywell or suppression chamber internal pressure is not within the limits of the LCO, drywell and suppression chamber internal pressure must be restored to within limits within 1 hour. The Required Action is necessary to return operation to within the bounds of the primary containment analysis. The 1 hour Completion Time is consistent with the ACTIONS of LCO 3.6.1.1, "Primary Containment," which requires that primary containment be restored to OPERABLE status within 1 hour.

B.1 and B.2

If drywell and suppression chamber internal pressure cannot be restored to within limits within the required Completion Time, the plant must be brought to a MODE in which the LCO does not apply. To achieve this status, the plant must be brought to at least MODE 3 within 12 hours and to MODE 4 within 36 hours. The allowed Completion Times are reasonable, based on operating experience, to reach the required plant conditions from full power conditions in an orderly manner and without challenging plant systems.

(continued)

BASES (continued)

SURVEILLANCE REQUIREMENTS

SR 3.6.1.4.1

Verifying that drywell and suppression chamber internal pressure is within limits ensures that operation remains within the limits assumed in the primary containment analysis. The 12 hour Frequency of this SR was developed based on operating experience related to trending primary containment pressure variations during the applicable MODES. Furthermore, the 12 hour Frequency is considered adequate in view of other indications available in the control room, including alarms, to alert the operator to an abnormal primary containment pressure condition.

REFERENCES

1. UFSAR, Section 6.2.1.1.3.

2. UFSAR, Section 6.2.1.1.3.1.

B 3.6 CONTAINMENT SYSTEMS

B 3.6.1.5 Drywell Air Temperature

BASES

BACKGROUND	Heat loads from the drywell, as well as piping and equipment, add energy to the airspace and raise airspace temperature. Coolers included in the unit design remove this energy and maintain an appropriate average temperature. The average airspace temperature affects the calculated response to postulated Design Basis Accidents (DBAs). This drywell air temperature limit is an initial condition input for the Reference 1 safety analyses.
APPLICABLE SAFETY ANALYSES	Primary containment performance for the DBA is evaluated for a entire spectrum of break sizes for postulated loss of coolant accidents (LOCAs) inside containment (Ref. 1). Among the inputs to the design basis analysis is the initial drywell average air temperature. Analyses assume an initial average drywell temperature of 135°F. Maintaining the expected initial conditions ensures that safety analyses remain valid and ensures that the peak LOCA primary drywell temperature does not exceed the maximum allowable temperature of 340°F (Ref. 1). Exceeding this design temperature may result in the degradation of the primary containment structure under accident loads. Equipment inside primary containment, and needed to mitigate the effects of a DBA, is designed to operate and be capable of operating under environmental conditions expected for the accident. Drywell air temperature satisfies Criterion 2 of 10 CFR 50.36(c)(2)(ii).
LCO	With an initial drywell average air temperature less than or equal to the LCO temperature limit, the peak accident temperature is maintained below the drywell design temperature. As a result, the ability of primary containment to perform its design function is ensured.
APPLICABILITY	In MODES 1, 2, and 3, a DBA could cause a release of radioactive material to primary containment. In MODES 4 and 5, the probability and consequences of these events are

(continued)

BASES

APPLICABILITY (continued)

reduced due to the pressure and temperature limitations of these MODES. Therefore, maintaining drywell average air temperature within the limit is not required in MODE 4 or 5.

ACTIONS

A.1

When drywell average air temperature is not within the limit of the LCO, it must be restored within 8 hours. This Required Action is necessary to return operation to within the bounds of the primary containment analysis. The 8 hour Completion Time is acceptable, considering the sensitivity of the analysis to variations in this parameter, and provides sufficient time to correct minor problems.

B.1 and B.2

If the drywell average air temperature cannot be restored to within the limit within the required Completion Time, the plant must be brought to a MODE in which the LCO does not apply. To achieve this status, the plant must be brought to at least MODE 3 within 12 hours and to MODE 4 within 36 hours. The allowed Completion Times are reasonable, based on operating experience, to reach the required plant conditions from full power conditions in an orderly manner and without challenging plant systems.

SURVEILLANCE REQUIREMENTS

SR 3.6.1.5.1

Verifying that the drywell average air temperature is within the LCO limit ensures that operation remains within the limits assumed for the primary containment analyses. The drywell average air temperature is determined using the average temperature of the operating return air plenum(s) upstream of the primary containment ventilation heat exchanger coil and cabinet located at elevation 740 ft 0 inches, azimuth 248°, and elevation 740 ft 0 inches, azimuth 76°. This provides a representative sample of the overall drywell atmosphere.

(continued)

BASES

SURVEILLANCE REQUIREMENTS

SR 3.6.1.5.1 (continued)

The 24 hour Frequency of this SR was developed based on operating experience related to drywell average air temperature variations and temperature dependent drift of instrumentation located in the drywell during the applicable MODES and the low probability of a DBA occurring between Surveillances. Furthermore, the 24 hour Frequency is considered adequate in view of other indications available in the control room, including alarms, to alert the operator to an abnormal drywell air temperature condition.

REFERENCES

1. UFSAR, Section 6.2.