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B 2.0 SAFETY LIMITS (SLs)

B 2.1.1 Reactor Core SLs

BASES

BACKGROUND

GDC 10 (Ref. 1) requires, and SLs ensure, that specified acceptable fuel design limits are not exceeded during steady state operation, normal operational transients, and anticipated operational occurrences (A00s).

The fuel cladding integrity SL is set such that no significant fuel damage is calculated to occur if the limit is not violated. Because fuel damage is not directly observable, a stepback approach is used to establish an SL, such that the MCPR is not less than the limit specified in Specification 2.1.1.2. MCPR greater than the specified limit represents a conservative margin relative to the conditions required to maintain fuel cladding integrity.

The fuel cladding is one of the physical barriers that separate the radioactive materials from the environs. The integrity of this cladding barrier is related to its relative freedom from perforations or cracking. Although some corrosion or use related cracking may occur during the life of the cladding, fission product migration from this source is incrementally cumulative and continuously measurable. Fuel cladding perforations, however, can result from thermal stresses, which occur from reactor operation significantly above design conditions.

While fission product migration from cladding perforation is just as measurable as that from use related cracking, the thermally caused cladding perforations signal a threshold beyond which still greater thermal stresses may cause gross, rather than incremental, cladding deterioration. Therefore, the fuel cladding SL is defined with a margin to the conditions that would produce onset of transition boiling (i.e., MCPR = 1.00). These conditions represent a significant departure from the condition intended by design for planned operation. The MCPR fuel cladding integrity SL ensures that during normal operation and during A00s, at least 99.9% of the fuel rods in the core do not experience transition boiling.

(continued)

BASES

BACKGROUND
(continued)

Operation above the boundary of the nucleate boiling regime could result in excessive cladding temperature because of the onset of transition boiling and the resultant sharp reduction in heat transfer coefficient. Inside the steam film, high cladding temperatures are reached, and a cladding water (zirconium water) reaction may take place. This chemical reaction results in oxidation of the fuel cladding to a structurally weaker form. This weaker form may lose its integrity, resulting in an uncontrolled release of activity to the reactor coolant.

The reactor vessel water level SL ensures that adequate core cooling capability is maintained during all MODES of reactor operation. Establishment of Emergency Core Cooling System instrumentation setpoints higher than this SL provides margin such that the SL will not be reached or exceeded.

APPLICABLE
SAFETY ANALYSES

The fuel cladding must not sustain damage as a result of normal operation and AOOs. The reactor core SLs are established to preclude violation of the fuel design criterion that a MCPR limit is to be established, such that at least 99.9% of the fuel rods in the core would not be expected to experience the onset of transition boiling.

The Reactor Protection System setpoints (LCO 3.3.1.1, "Reactor Protection System (RPS) Instrumentation"), in combination with other LCOs, are designed to prevent any anticipated combination of transient conditions for Reactor Coolant System water level, pressure, and THERMAL POWER level that would result in reaching the MCPR Safety Limit.

Cores with fuel that is all from one vendor utilize that vendor's critical power correlation for determination of MCPR. For cores with fuel from more than one vendor, the MCPR is calculated for all fuel in the core using the licensed critical power correlations. This may be accomplished by using each vendor's correlation for the vendor's respective fuel. Alternatively, a single correlation can be used for all fuel in the core. For fuel that has not been manufactured by the vendor supplying the critical power correlation, the input parameters to the reload vendor's correlation are adjusted using benchmarking data to yield conservative results compared with the critical power correlation results from the co-resident fuel.

(continued)

BASES

APPLICABLE
SAFETY ANALYSES
(continued)

2.1.1.1 Fuel Cladding Integrity

The use of the Siemens Power Corporation correlation (ANFB) is valid for critical power calculations at pressures > 600 psia and bundle mass fluxes > 0.1×10^6 lb/hr-ft² (Refs. 2 and 3). For operation at low pressures or low flows, the fuel cladding integrity SL is established by a limiting condition on core THERMAL POWER, with the following basis:

Since the pressure drop in the bypass region is essentially all elevation head, the core pressure drop at low power and flows will always be > 4.5 psi. Analyses show that with a bundle flow of 28×10^3 lb/hr (approximately a mass velocity of 0.25×10^6 lb/hr-ft²), bundle pressure drop is nearly independent of bundle power and has a value of 3.5 psi. Thus, the bundle flow with a 4.5 psi driving head will be > 28×10^3 lb/hr. Full scale critical power test data taken at pressures from 14.7 psia to 800 psia indicate that the fuel assembly critical power at this flow is approximately 3.35 Mwt. With the design peaking factors, this corresponds to a THERMAL POWER > 50% RTP. Thus, a THERMAL POWER limit of 25% RTP for reactor pressure < 785 psig is conservative. Although the ANFB correlation is valid at reactor steam dome pressures > 600 psia, application of the fuel cladding integrity SL at reactor steam dome pressure < 785 psig is conservative.

2.1.1.2 MCPR

The MCPR SL ensures sufficient conservatism in the operating MCPR limit that, in the event of an AOO from the limiting condition of operation, at least 99.9% of the fuel rods in the core would be expected to avoid boiling transition. The margin between calculated boiling transition (i.e., MCPR = 1.00) and the MCPR SL is based on a detailed statistical procedure that considers the uncertainties in monitoring the core operating state. One specific uncertainty included in the SL is the uncertainty inherent in the ANFB critical power correlation. References 2, 3, 4 and 5 describe the methodology used in determining the MCPR SL.

(continued)

BASES

APPLICABLE
SAFETY ANALYSES

2.1.1.2 MCPR (continued)

The ANFB critical power correlation is based on a significant body of practical test data, providing a high degree of assurance that the critical power, as evaluated by the correlation, is within a small percentage of the actual critical power being estimated. As long as the core pressure and flow are within the range of validity of the ANFB correlation, the assumed reactor conditions used in defining the SL introduce conservatism into the limit because bounding high radial power factors and bounding flat local peaking distributions are used to estimate the number of rods in boiling transition. Still further conservatism is induced by the tendency of the ANFB correlation to overpredict the number of rods in boiling transition. These conservatisms and the inherent accuracy of the ANFB correlation provide a reasonable degree of assurance that there would be no transition boiling in the core during sustained operation at the MCPR SL. If boiling transition were to occur, there is reason to believe that the integrity of the fuel would not be compromised. Significant test data accumulated by the NRC and private organizations indicate that the use of a boiling transition limitation to protect against cladding failure is a very conservative approach. Much of the data indicate that BWR fuel can survive for an extended period of time in an environment of boiling transition.

2.1.1.3 Reactor Vessel Water Level

During MODES 1 and 2, the reactor vessel water level is required to be above the top of the active irradiated fuel to provide core cooling capability. With fuel in the reactor vessel during periods when the reactor is shut down, consideration must be given to water level requirements due to the effect of decay heat. If the water level should drop below the top of the active irradiated fuel during this period, the ability to remove decay heat is reduced. This reduction in cooling capability could lead to elevated cladding temperatures and clad perforation in the event that the water level becomes $< 2/3$ of the core height. The reactor vessel water level SL has been established at the top of the active irradiated fuel to provide a point that can be monitored and to also provide adequate margin for effective action.

(continued)

BASES (continued)

SAFETY LIMITS The reactor core SLs are established to protect the integrity of the fuel clad barrier to prevent the release of radioactive materials to the environs. SL 2.1.1.1 and SL 2.1.1.2 ensure that the core operates within the fuel design criteria. SL 2.1.1.3 ensures that the reactor vessel water level is greater than the top of the active irradiated fuel in order to prevent elevated clad temperatures and resultant clad perforations.

APPLICABILITY SLs 2.1.1.1, 2.1.1.2, and 2.1.1.3 are applicable in all MODES.

SAFETY LIMIT VIOLATIONS 2.2
Exceeding an SL may cause fuel damage and create a potential for radioactive releases in excess of 10 CFR 100, "Reactor Site Criteria," limits (Ref. 6). Therefore, it is required to insert all insertable control rods and restore compliance with the SL within 2 hours. The 2 hour Completion Time ensures that the operators take prompt remedial action and the probability of an accident occurring during this period is minimal.

- REFERENCES**
1. 10 CFR 50, Appendix A, GDC 10.
 2. ANF-524(P)(A), Revision 2, Supplement 1 Revision 2, Supplement 2, Advanced Nuclear Fuels Corporation Critical Power Methodology for Boiling Water Reactors/Advanced Nuclear Fuels Corporation Critical Power Methodology for Boiling Water Reactors: Methodology for Analysis of Assembly Channel Bowing Effects/NRC Correspondence (as specified in Technical Specification 5.6.5).
 3. ANF-1125(P)(A) and Supplements 1 and 2, ANFB Critical Power Correlation, Advanced Nuclear Fuels Corporation (as specified in Technical Specification 5.6.5).
 4. ANF-1125(P)(A), Supplement 1, Appendix E, ANFB Critical Power Correlation Determination of ATRIUM-9B Additive Constant Uncertainties, Siemens Power Corporation (as specified in Technical Specification 5.6.5).

(continued)

BASES

REFERENCES
(continued)

5. EMF-1125(P)(A), Supplement 1 Appendix C, ANFB Critical Power Correlation Application for Coresident Fuel, Siemens Power Corporation (as specified in Technical Specification 5.6.5).
 6. 10 CFR 100.
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B 2.0 SAFETY LIMITS (SLs)

B 2.1.2 Reactor Coolant System (RCS) Pressure SL

BASES

BACKGROUND

The SL on reactor steam dome pressure protects the RCS against overpressurization. In the event of fuel cladding failure, fission products are released into the reactor coolant. The RCS then serves as the primary barrier in preventing the release of fission products into the atmosphere. Establishing an upper limit on reactor steam dome pressure ensures continued RCS integrity. According to 10 CFR 50, Appendix A, GDC 14, "Reactor Coolant Pressure Boundary," and GDC 15, "Reactor Coolant System Design" (Ref. 1), the reactor coolant pressure boundary (RCPB) shall be designed with sufficient margin to ensure that the design conditions are not exceeded during normal operation and anticipated operational occurrences (A00s).

During normal operation and A00s, RCS pressure is limited from exceeding the design pressure by more than 10%, in accordance with Section III of the ASME Code (Ref. 2) for the reactor pressure vessel, and by more than 20%, in accordance with USAS B31.1-1967 Code (Ref. 3) for the RCS piping. To ensure system integrity, all RCS components are hydrostatically tested at 125% of design pressure, in accordance with ASME Code requirements, prior to initial operation when there is no fuel in the core. Following inception of unit operation, RCS components shall be pressure tested in accordance with the requirements of ASME Code, Section XI (Ref. 4).

Overpressurization of the RCS could result in a breach of the RCPB, reducing the number of protective barriers designed to prevent radioactive releases from exceeding the limits specified in 10 CFR 100, "Reactor Site Criteria" (Ref. 5). If this occurred in conjunction with a fuel cladding failure, the number of protective barriers designed to prevent radioactive releases from exceeding the limits would be reduced.

(continued)

BASES (continued)

APPLICABLE
SAFETY ANALYSES

The RCS safety/relief valves and the Reactor Protection System Reactor Vessel Steam Dome Pressure-High Function have settings established to ensure that the RCS pressure SL will not be exceeded.

The RCS pressure SL has been selected such that it is at a pressure below which it can be shown that the integrity of the system is not endangered. The reactor pressure vessel is designed to ASME, Boiler and Pressure Vessel Code, Section III, 1968 Edition, including Addenda through the winter of 1969 for Unit 1 and winter of 1970 (excluding Appendix I) for Unit 2 (Ref. 6), which permits a maximum pressure transient of 110%, 1375 psig, of design pressure 1250 psig. The SL of 1325 psig, as measured in the reactor steam dome, is equivalent to 1375 psig at the lowest elevation of the RCS. The RCS is designed to ASME Code, Section III, 1971 Edition, including Addenda through the summer of 1971 (Ref. 7), for the reactor recirculation piping, which permits a maximum pressure transient of 120% of design pressures of 1150 psig for suction piping and 1250 psig for discharge piping. The recirculation pumps are designed to ASME Code, Section III, 1971 Edition, including Addenda through the summer of 1971 (Ref. 7). The RCS pressure SL is selected to be the lowest transient overpressure allowed by the applicable codes.

SAFETY LIMITS

The maximum transient pressure allowable in the RCS pressure vessel under the ASME Code, Section III, is 110% of design pressure. The maximum transient pressure allowable in the RCS piping, valves, and fittings is 120% of design pressures of 1150 psig for suction piping and 1250 psig for discharge piping. The most limiting of these allowances is the 110% of the reactor pressure vessel design pressure; therefore, the SL on maximum allowable RCS pressure is established at 1325 psig as measured at the reactor steam dome.

APPLICABILITY

SL 2.1.2 applies in all MODES.

SAFETY LIMIT
VIOLATIONS

2.2

Exceeding the RCS pressure SL may cause RCS failure and create a potential for radioactive releases in excess of 10 CFR 100, "Reactor Site Criteria," limits (Ref. 5).

(continued)

BASES

SAFETY LIMIT
VIOLATIONS

2.2 (continued)

Therefore, it is required to insert all insertable control rods and restore compliance with the SL within 2 hours. The 2 hour Completion Time ensures that the operators take prompt remedial action and also assures that the probability of an accident occurring during this period is minimal.

REFERENCES

1. 10 CFR 50, Appendix A, GDC 14 and GDC 15.
 2. ASME, Boiler and Pressure Vessel Code, Section III, Article NB-7000.
 3. ASME, USAS, Power Piping Code, Section B31.1, 1967.
 4. ASME, Boiler and Pressure Vessel Code, Section XI, Article IWB-5000.
 5. 10 CFR 100.
 6. ASME, Boiler and Pressure Vessel Code, Section III, 1968 Edition, Addenda, winter of 1969 (Unit 1) and winter of 1970 (Unit 2).
 7. ASME, Boiler and Pressure Vessel Code, Section III, 1971 Edition, Addenda, summer of 1971.
-

B 3.0 LIMITING CONDITION FOR OPERATION (LCO) APPLICABILITY

BASES

LCOs LCO 3.0.1 through LCO 3.0.7 establish the general requirements applicable to all Specifications in Sections 3.1 through 3.10 and apply at all times, unless otherwise stated.

LCO 3.0.1 LCO 3.0.1 establishes the Applicability statement within each individual Specification as the requirement for when the LCO is required to be met (i.e., when the unit is in the MODES or other specified conditions of the Applicability statement of each Specification).

LCO 3.0.2 LCO 3.0.2 establishes that upon discovery of a failure to meet an LCO, the associated ACTIONS shall be met. The Completion Time of each Required Action for an ACTIONS Condition is applicable from the point in time that an ACTIONS Condition is entered. The Required Actions establish those remedial measures that must be taken within specified Completion Times when the requirements of an LCO are not met. This Specification establishes that:

- a. Completion of the Required Actions within the specified Completion Times constitutes compliance with a Specification; and
- b. Completion of the Required Actions is not required when an LCO is met within the specified Completion Time, unless otherwise specified.

There are two basic types of Required Actions. The first type of Required Action specifies a time limit in which the LCO must be met. This time limit is the Completion Time to restore an inoperable system or component to OPERABLE status or to restore variables to within specified limits. If this type of Required Action is not completed within the specified Completion Time, a shutdown may be required to place the unit in a MODE or condition in which the Specification is not applicable. (Whether stated as a Required Action or not, correction of the entered Condition is an action that may always be considered upon entering

(continued)

BASES

LCO 3.0.2
(continued)

ACTIONS.) The second type of Required Action specifies the remedial measures that permit continued operation of the unit that is not further restricted by the Completion Time. In this case, compliance with the Required Actions provides an acceptable level of safety for continued operation.

Completing the Required Actions is not required when an LCO is met or is no longer applicable, unless otherwise stated in the individual Specifications.

The nature of some Required Actions of some Conditions necessitates that, once the Condition is entered, the Required Actions must be completed even though the associated Condition no longer exists. The individual LCO's ACTIONS specify the Required Actions where this is the case. An example of this is in LCO 3.4.11, "RCS Pressure and Temperature (P/T) Limits."

The Completion Times of the Required Actions are also applicable when a system or component is removed from service intentionally. The reasons for intentionally relying on the ACTIONS include, but are not limited to, performance of Surveillances, preventive maintenance, corrective maintenance, or investigation of operational problems. Entering ACTIONS for these reasons must be done in a manner that does not compromise safety. Intentional entry into ACTIONS should not be made for operational convenience. Additionally, if intentional entry into ACTIONS would result in redundant equipment being inoperable, alternatives should be used instead. Doing so limits the time both subsystems/divisions of a safety function are inoperable and limits the time conditions exist which may result in LCO 3.0.3 being entered. Individual Specifications may specify a time limit for performing an SR when equipment is removed from service or bypassed for testing. In this case, the Completion Times of the Required Actions are applicable when this time limit expires, if the equipment remains removed from service or bypassed.

When a change in MODE or other specified condition is required to comply with Required Actions, the unit may enter a MODE or other specified condition in which another Specification becomes applicable. In this case, the Completion Times of the associated Required Actions would apply from the point in time that the new Specification becomes applicable and the ACTIONS Condition(s) are entered.

(continued)

BASES (continued)

LCO 3.0.3

LCO 3.0.3 establishes the actions that must be implemented when an LCO is not met and:

- a. An associated Required Action and Completion Time is not met and no other Condition applies; or
- b. The condition of the unit is not specifically addressed by the associated ACTIONS. This means that no combination of Conditions stated in the ACTIONS can be made that exactly corresponds to the actual condition of the unit. Sometimes, possible combinations of Conditions are such that entering LCO 3.0.3 is warranted; in such cases, the ACTIONS specifically state a Condition corresponding to such combinations and also that LCO 3.0.3 be entered immediately.

This Specification delineates the time limits for placing the unit in a safe MODE or other specified condition when operation cannot be maintained within the limits for safe operation as defined by the LCO and its ACTIONS. It is not intended to be used as an operational convenience that permits routine voluntary removal of redundant systems or components from service in lieu of other alternatives that would not result in redundant systems or components being inoperable.

Upon entering LCO 3.0.3, 1 hour is allowed to prepare for an orderly shutdown before initiating a change in unit operation. This includes time to permit the operator to coordinate the reduction in electrical generation with the load dispatcher to ensure the stability and availability of the electrical grid. The time limits specified to reach lower MODES of operation permit the shutdown to proceed in a controlled and orderly manner that is well within the specified maximum cooldown rate and within the capabilities of the unit, assuming that only the minimum required equipment is OPERABLE. This reduces thermal stresses on components of the Reactor Coolant System and the potential for a plant upset that could challenge safety systems under conditions to which this Specification applies. The use and interpretation of specified times to complete the actions of LCO 3.0.3 are consistent with the discussion of Section 1.3, Completion Times.

(continued)

BASES

LCO 3.0.3
(continued)

A unit shutdown required in accordance with LCO 3.0.3 may be terminated and LCO 3.0.3 exited if any of the following occurs:

- a. The LCO is now met.
- b. A Condition exists for which the Required Actions have now been performed.
- c. ACTIONS exist that do not have expired Completion Times. These Completion Times are applicable from the point in time that the Condition is initially entered and not from the time LCO 3.0.3 is exited.

The time limits of Specification 3.0.3 allow 37 hours for the unit to be in MODE 4 when a shutdown is required during MODE 1 operation. If the unit is in a lower MODE of operation when a shutdown is required, the time limit for reaching the next lower MODE applies. If a lower MODE is reached in less time than allowed, however, the total allowable time to reach MODE 4, or other applicable MODE, is not reduced. For example, if MODE 2 is reached in 2 hours, then the time allowed for reaching MODE 3 is the next 11 hours, because the total time for reaching MODE 3 is not reduced from the allowable limit of 13 hours. Therefore, if remedial measures are completed that would permit a return to MODE 1, a penalty is not incurred by having to reach a lower MODE of operation in less than the total time allowed.

In MODES 1, 2, and 3, LCO 3.0.3 provides actions for Conditions not covered in other Specifications. The requirements of LCO 3.0.3 do not apply in MODES 4 and 5 because the unit is already in the most restrictive Condition required by LCO 3.0.3. The requirements of LCO 3.0.3 do not apply in other specified conditions of the Applicability (unless in MODE 1, 2, or 3) because the ACTIONS of individual Specifications sufficiently define the remedial measures to be taken.

Exceptions to LCO 3.0.3 are provided in instances where requiring a unit shutdown, in accordance with LCO 3.0.3, would not provide appropriate remedial measures for the associated condition of the unit. An example of this is in LCO 3.7.8, "Spent Fuel Storage Pool Water Level." LCO 3.7.8 has an Applicability of "During movement of irradiated fuel

(continued)

BASES

LCO 3.0.3
(continued)

assemblies in the spent fuel storage pool." Therefore, this LCO can be applicable in any or all MODES. If the LCO and the Required Actions of LCO 3.7.8 are not met while in MODE 1, 2, or 3, there is no safety benefit to be gained by placing the unit in a shutdown condition. The Required Action of LCO 3.7.8 of "Suspend movement of fuel assemblies in the spent fuel storage pool" is the appropriate Required Action to complete in lieu of the actions of LCO 3.0.3. These exceptions are addressed in the individual Specifications.

LCO 3.0.4

LCO 3.0.4 establishes limitations on changes in MODES or other specified conditions in the Applicability when an LCO is not met. It precludes placing the unit in a MODE or other specified condition stated in that Applicability (e.g., Applicability desired to be entered) when the following exist:

- a. Unit conditions are such that the requirements of the LCO would not be met in the Applicability desired to be entered; and
- b. Continued noncompliance with the LCO requirements, if the Applicability were entered, would result in the unit being required to exit the Applicability desired to be entered to comply with the Required Actions.

Compliance with Required Actions that permit continued operation of the unit for an unlimited period of time in a MODE or other specified condition provides an acceptable level of safety for continued operation. This is without regard to the status of the unit before or after the MODE change. Therefore, in such cases, entry into a MODE or other specified condition in the Applicability may be made in accordance with the provisions of the Required Actions. The provisions of this Specification should not be interpreted as endorsing the failure to exercise the good practice of restoring systems or components to OPERABLE status before entering an associated MODE or other specified condition in the Applicability.

The provisions of LCO 3.0.4 shall not prevent changes in MODES or other specified conditions in the Applicability that are required to comply with ACTIONS. In addition, the

(continued)

BASES

LCO 3.0.4
(continued)

provisions of LCO 3.0.4 shall not prevent changes in MODES or other specified conditions in the Applicability that result from any unit shutdown.

Exceptions to LCO 3.0.4 are stated in the individual Specifications. The exceptions allow entry into MODES or other specified conditions in the Applicability when the associated ACTIONS to be entered do not provide for continued operation for an unlimited period of time. Exceptions may apply to all the ACTIONS or to a specific Required Action of a Specification.

Surveillances do not have to be performed on the associated inoperable equipment (or on variables outside the specified limits), as permitted by SR 3.0.1. Therefore, changing MODES or other specified conditions while in an ACTIONS Condition, either in compliance with LCO 3.0.4, or where an exception to LCO 3.0.4 is stated, is not a violation of SR 3.0.1 or SR 3.0.4 for those Surveillances that do not have to be performed due to the associated inoperable equipment. However, SRs must be met to ensure OPERABILITY prior to declaring the associated equipment OPERABLE (or variable within limits) and restoring compliance with the affected LCO.

LCO 3.0.4 is only applicable when entering MODE 3 from MODE 4, MODE 2 from MODE 3 or 4, or MODE 1 from MODE 2. Furthermore, LCO 3.0.4 is applicable when entering any other specified condition in the Applicability only while operating in MODE 1, 2, or 3. The requirements of LCO 3.0.4 do not apply in MODES 4 and 5, or in other specified conditions of the Applicability (unless in MODE 1, 2, or 3) because the ACTIONS of individual Specifications sufficiently define the remedial measures to be taken.

LCO 3.0.5

LCO 3.0.5 establishes the allowance for restoring equipment to service under administrative controls when it has been removed from service or declared inoperable to comply with ACTIONS. The sole purpose of this Specification is to provide an exception to LCO 3.0.2 (e.g., to not comply with the applicable Required Action(s)) to allow the performance of required testing to demonstrate:

- a. The OPERABILITY of the equipment being returned to service; or

(continued)

BASES

LCO 3.0.5
(continued)

b. The OPERABILITY of other equipment.

The administrative controls ensure the time the equipment is returned to service in conflict with the requirements of the ACTIONS is limited to the time absolutely necessary to perform the required testing to demonstrate OPERABILITY. This Specification does not provide time to perform any other preventive or corrective maintenance.

An example of demonstrating the OPERABILITY of the equipment being returned to service is reopening a containment isolation valve that has been closed to comply with Required Actions, and must be reopened to perform the required testing.

An example of demonstrating the OPERABILITY of other equipment is taking an inoperable channel or trip system out of the tripped condition to prevent the trip function from occurring during the performance of required testing on another channel in the other trip system. A similar example of demonstrating the OPERABILITY of other equipment is taking an inoperable channel or trip system out of the tripped condition to permit the logic to function and indicate the appropriate response during the performance of required testing on another channel in the same trip system.

LCO 3.0.6

LCO 3.0.6 establishes an exception to LCO 3.0.2 for support systems that have an LCO specified in the Technical Specifications (TS). This exception is provided because LCO 3.0.2 would require that the Conditions and Required Actions of the associated inoperable supported system's LCO be entered solely due to the inoperability of the support system. This exception is justified because the actions that are required to ensure the plant is maintained in a safe condition are specified in the support systems' LCO's Required Actions. These Required Actions may include entering the supported system's Conditions and Required Actions or may specify other Required Actions.

When a support system is inoperable and there is an LCO specified for it in the TS, the supported system(s) are required to be declared inoperable if determined to be inoperable as a result of the support system inoperability. However, it is not necessary to enter into the supported

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BASES

LCO 3.0.6
(continued)

systems' Conditions and Required Actions unless directed to do so by the support system's Required Actions. The potential confusion and inconsistency of requirements related to the entry into multiple support and supported systems' LCO's Conditions and Required Actions are eliminated by providing all the actions that are necessary to ensure the plant is maintained in a safe condition in the support system's Required Actions.

However, there are instances where a support system's Required Action may either direct a supported system to be declared inoperable or direct entry into Conditions and Required Actions for the supported system. This may occur immediately or after some specified delay to perform some other Required Action. Regardless of whether it is immediate or after some delay, when a support system's Required Action directs a supported system to be declared inoperable or directs entry into Conditions and Required Actions for a supported system, the applicable Conditions and Required Actions shall be entered in accordance with LCO 3.0.2.

Specification 5.5.12, "Safety Function Determination Program" (SFDP), ensures loss of safety function is detected and appropriate actions are taken. Upon entry into LCO 3.0.6, an evaluation shall be made to determine if loss of safety function exists. Additionally, other limitations, remedial actions, or compensatory actions may be identified as a result of the support system inoperability and corresponding exception to entering supported system Conditions and Required Actions. The SFDP implements the requirements of LCO 3.0.6.

Cross division checks to identify a loss of safety function for those support systems that support safety systems are required. The cross division check verifies that the supported systems of the redundant OPERABLE support system are OPERABLE, thereby ensuring safety function is retained. If this evaluation determines that a loss of safety function exists, the appropriate Conditions and Required Actions of the LCO in which the loss of safety function exists are required to be entered.

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BASES

LCO 3.0.6
(continued)

This loss of safety function does not require the assumption of additional single failures or loss of offsite power. Since operation is being restricted in accordance with the ACTIONS of the support system, any resulting temporary loss of redundancy or single failure protection is taken into account. Similarly, the ACTIONS for inoperable offsite circuit(s) and inoperable diesel generator(s) provide the necessary restriction for cross division inoperabilities. This explicit cross division verification for inoperable AC electrical power sources also acknowledges that support system(s) are not declared inoperable solely as a result of inoperability of a normal or emergency electrical power source (refer to the definition of OPERABLE - OPERABILITY).

When a loss of safety function is determined to exist, and the SFDP requires entry into the appropriate Conditions and Required Actions of the LCO in which the loss of safety function exists, consideration must be given to the specific type of function affected. Where a loss of function is solely due to a single Technical Specification support system (e.g., loss of automatic start due to inoperable instrumentation, or loss of pump suction source due to low tank level) the appropriate LCO is the LCO for the support system. The ACTIONS for a support system LCO adequately addresses the inoperabilities of that system without reliance on entering its supported system LCO. When the loss of function is the result of multiple support systems, the appropriate LCO is the LCO for the supported system.

LCO 3.0.7

There are certain special tests and operations required to be performed at various times over the life of the unit. These special tests and operations are necessary to demonstrate select unit performance characteristics, to perform special maintenance activities, and to perform special evolutions. Special Operations LCOs in Section 3.10 allow specified TS requirements to be changed to permit performances of these special tests and operations, which otherwise could not be performed if required to comply with the requirements of these TS. Unless otherwise specified, all the other TS requirements remain unchanged. This will ensure all appropriate requirements of the MODE or other specified condition not directly associated with or required to be changed to perform the special test or operation will remain in effect.

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BASES

LCO 3.0.7
(continued)

The Applicability of a Special Operations LCO represents a condition not necessarily in compliance with the normal requirements of the TS. Compliance with Special Operations LCOs is optional. A special operation may be performed either under the provisions of the appropriate Special Operations LCO or under the other applicable TS requirements. If it is desired to perform the special operation under the provisions of the Special Operations LCO, the requirements of the Special Operations LCO shall be followed. When a Special Operations LCO requires another LCO to be met, only the requirements of the LCO statement are required to be met regardless of that LCO's Applicability (i.e., should the requirements of this other LCO not be met, the ACTIONS of the Special Operations LCO apply, not the ACTIONS of the other LCO). However, there are instances where the Special Operations LCO's ACTIONS may direct the other LCO's ACTIONS be met. The Surveillances of the other LCO are not required to be met, unless specified in the Special Operations LCO. If conditions exist such that the Applicability of any other LCO is met, all the other LCO's requirements (ACTIONS and SRs) are required to be met concurrent with the requirements of the Special Operations LCO.

LCO 3.0.8

LCO 3.0.8 establishes the applicability of each Specification to both Unit 1 and Unit 2 operation. Whenever a requirement applies to only one unit, or is different for each unit, this will be identified in the appropriate section of the Specification (e.g., Applicability, Surveillance, etc.) with parenthetical reference, Notes, or other appropriate presentation within the body of the requirement.

B 3.0 SURVEILLANCE REQUIREMENT (SR) APPLICABILITY

BASES

SRs SR 3.0.1 through SR 3.0.4 establish the general requirements applicable to all Specifications in Sections 3.1 through 3.10 and apply at all times, unless otherwise stated.

SR 3.0.1 SR 3.0.1 establishes the requirement that SRs must be met during the MODES or other specified conditions in the Applicability for which the requirements of the LCO apply, unless otherwise specified in the individual SRs. This Specification is to ensure that Surveillances are performed to verify the OPERABILITY of systems and components, and that variables are within specified limits. Failure to meet a Surveillance within the specified Frequency, in accordance with SR 3.0.2, constitutes a failure to meet an LCO.

Systems and components are assumed to be OPERABLE when the associated SRs have been met. Nothing in this Specification, however, is to be construed as implying that systems or components are OPERABLE when:

- a. The systems or components are known to be inoperable, although still meeting the SRs; or
- b. The requirements of the Surveillance(s) are known to be not met between required Surveillance performances.

Surveillances do not have to be performed when the unit is in a MODE or other specified condition for which the requirements of the associated LCO are not applicable, unless otherwise specified. The SRs associated with a Special Operations LCO are only applicable when the Special Operations LCO is used as an allowable exception to the requirements of a Specification.

Unplanned events may satisfy the requirements (including applicable acceptance criteria) for a given SR. In this case, the unplanned event may be credited as fulfilling the performance of the SR.

(continued)

BASES

SR 3.0.1
(continued)

Surveillances, including Surveillances invoked by Required Actions, do not have to be performed on inoperable equipment because the ACTIONS define the remedial measures that apply. Surveillances have to be met and performed in accordance with SR 3.0.2, prior to returning equipment to OPERABLE status.

Upon completion of maintenance, appropriate post maintenance testing is required to declare equipment OPERABLE. This includes ensuring applicable Surveillances are not failed and their most recent performance is in accordance with SR 3.0.2. Post maintenance testing may not be possible in the current MODE or other specified conditions in the Applicability due to the necessary unit parameters not having been established. In these situations, the equipment may be considered OPERABLE provided testing has been satisfactorily completed to the extent possible and the equipment is not otherwise believed to be incapable of performing its function. This will allow operation to proceed to a MODE or other specified condition where other necessary post maintenance tests can be completed. Some examples of this process are:

- a. Control rod drive maintenance during refueling that requires scram testing at ≥ 800 psig. However, if other appropriate testing is satisfactorily completed and the scram time testing of SR 3.1.4.3 is satisfied, the control rod can be considered OPERABLE. This allows startup to proceed to reach 800 psig to perform other necessary testing.
- b. Reactor Core Isolation Cooling (RCIC) maintenance during shutdown that requires system functional tests at a specified pressure. Provided other appropriate testing is satisfactorily completed, startup can proceed with RCIC considered OPERABLE. This allows operation to reach the specified pressure to complete the necessary post maintenance testing.

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BASES (continued)

SR 3.0.2

SR 3.0.2 establishes the requirements for meeting the specified Frequency for Surveillances and any Required Action with a Completion Time that requires the periodic performance of the Required Action on a "once per..." interval.

SR 3.0.2 permits a 25% extension of the interval specified in the Frequency. This extension facilitates Surveillance scheduling and considers plant operating conditions that may not be suitable for conducting the Surveillance (e.g., transient conditions or other ongoing Surveillance or maintenance activities).

The 25% extension does not significantly degrade the reliability that results from performing the Surveillance at its specified Frequency. This is based on the recognition that the most probable result of any particular Surveillance being performed is the verification of conformance with the SRs. The exceptions to SR 3.0.2 are those Surveillances for which the 25% extension of the interval specified in the Frequency does not apply. These exceptions are stated in the individual Specifications. The requirements of regulations take precedence over the TS. Therefore, when a test interval is specified in the regulations, the test interval cannot be extended by the TS, and the SR includes a Note in the Frequency stating "SR 3.0.2 is not applicable."

As stated in SR 3.0.2, the 25% extension also does not apply to the initial portion of a periodic Completion Time that requires performance on a "once per..." basis. The 25% extension applies to each performance after the initial performance. The initial performance of the Required Action, whether it is a particular Surveillance or some other remedial action, is considered a single action with a single Completion Time. One reason for not allowing the 25% extension to this Completion Time is that such an action usually verifies that no loss of function has occurred by checking the status of redundant or diverse components or accomplishes the function of the inoperable equipment in an alternative manner.

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BASES

SR 3.0.2
(continued) The provisions of SR 3.0.2 are not intended to be used repeatedly merely as an operational convenience to extend Surveillance intervals (other than those consistent with refueling intervals) or periodic Completion Time intervals beyond those specified.

SR 3.0.3 SR 3.0.3 establishes the flexibility to defer declaring affected equipment inoperable or an affected variable outside the specified limits when a Surveillance has not been completed within the specified Frequency. A delay period of up to 24 hours or up to the limit of the specified Frequency, whichever is less, applies from the point in time it is discovered that the Surveillance has not been performed in accordance with SR 3.0.2, and not at the time that the specified Frequency was not met. This delay period provides adequate time to complete Surveillances that have been missed. This delay period permits the completion of a Surveillance before complying with Required Actions or other remedial measures that might preclude completion of the Surveillance.

The basis for this delay period includes consideration of unit conditions, adequate planning, availability of personnel, the time required to perform the Surveillance, the safety significance of the delay in completing the required Surveillance, and the recognition that the most probable result of any particular Surveillance being performed is the verification of conformance with the requirements.

When a Surveillance with a Frequency based not on time intervals, but upon specified unit conditions or operational situations, is discovered not to have been performed when specified, SR 3.0.3 allows the full delay period of 24 hours to perform the Surveillance.

SR 3.0.3 also provides a time limit for completion of Surveillances that become applicable as a consequence of MODE changes imposed by Required Actions.

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BASES

SR 3.0.3
(continued)

Failure to comply with specified Frequencies for SRs is expected to be an infrequent occurrence. Use of the delay period established by SR 3.0.3 is a flexibility which is not intended to be used as an operational convenience to extend Surveillance intervals.

If a Surveillance is not completed within the allowed delay period, then the equipment is considered inoperable or the variable then is considered outside the specified limits and the Completion Times of the Required Actions for the applicable LCO Conditions begin immediately upon expiration of the delay period. If a Surveillance is failed within the delay period, then the equipment is inoperable, or the variable is outside the specified limits and the Completion Times of the Required Actions for the applicable LCO Conditions begin immediately upon the failure of the Surveillance.

Completion of the Surveillance within the delay period allowed by this Specification, or within the Completion Time of the ACTIONS, restores compliance with SR 3.0.1.

SR 3.0.4

SR 3.0.4 establishes the requirement that all applicable SRs must be met before entry into a MODE or other specified condition in the Applicability.

This Specification ensures that system and component OPERABILITY requirements and variable limits are met before entry into MODES or other specified conditions in the Applicability for which these systems and components ensure safe operation of the unit.

The provisions of this Specification should not be interpreted as endorsing the failure to exercise the good practice of restoring systems or components to OPERABLE status before entering an associated MODE or other specified condition in the Applicability.

However, in certain circumstances, failing to meet an SR will not result in SR 3.0.4 restricting a MODE change or other specified condition change. When a system, subsystem, division, component, device, or variable is inoperable or

(continued)

BASES

SR 3.0.4
(continued)

outside its specified limits, the associated SR(s) are not required to be performed per SR 3.0.1 which states that Surveillances do not have to be performed on inoperable equipment. When equipment is inoperable, SR 3.0.4 does not apply to the associated SR(s) since the requirement for the SR(s) to be performed is removed. Therefore, failing to perform the Surveillance(s) within the specified Frequency, on equipment that is inoperable, does not result in an SR 3.0.4 restriction to changing MODES or other specified conditions of the Applicability. However, since the LCO is not met in this instance, LCO 3.0.4 will govern any restrictions that may (or may not) apply to MODE or other specified condition changes.

The provisions of SR 3.0.4 shall not prevent changes in MODES or other specified conditions in the Applicability that are required to comply with ACTIONS. In addition, the provisions of SR 3.0.4 shall not prevent changes in MODES or other specified conditions in the Applicability that result from any unit shutdown.

The precise requirements for performance of SRs are specified such that exceptions to SR 3.0.4 are not necessary. The specific time frames and conditions necessary for meeting the SRs are specified in the Frequency, in the Surveillance, or both. This allows performance of Surveillances when the prerequisite condition(s) specified in a Surveillance procedure require entry into the MODE or other specified condition in the Applicability of the associated LCO prior to the performance or completion of a Surveillance. A Surveillance that could not be performed until after entering the LCO Applicability would have its Frequency specified such that it is not "due" until the specific conditions needed are met. Alternately, the Surveillance may be stated in the form of a Note as not required (to be met or performed) until a particular event, condition, or time has been reached. Further discussion of the specific formats of SRs' annotation is found in Section 1.4, Frequency.

SR 3.0.4 is only applicable when entering MODE 3 from MODE 4, MODE 2 from MODE 3 or 4, or MODE 1 from MODE 2. Furthermore, SR 3.0.4 is applicable when entering any other

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BASES

SR 3.0.4 (continued) specified condition in the Applicability only while operating in MODE 1, 2, or 3. The requirements of SR 3.0.4 do not apply in MODES 4 and 5, or in other specified conditions of the Applicability (unless in MODE 1, 2, or 3) because the ACTIONS of individual Specifications sufficiently define the remedial measures to be taken.

SR 3.0.5 SR 3.0.5 establishes the applicability of each Surveillance to both Unit 1 and Unit 2 operation. Whenever a requirement applies to only one unit, or is different for each unit, this will be identified with parenthetical reference, Notes, or other appropriate presentation within the SR.

B 3.1 REACTIVITY CONTROL SYSTEMS

B 3.1.1 SHUTDOWN MARGIN (SDM)

BASES

BACKGROUND

SDM requirements are specified to ensure:

- a. The reactor can be made subcritical from all operating conditions and transients and Design Basis Events;
- b. The reactivity transients associated with postulated accident conditions are controllable within acceptable limits; and
- c. The reactor will be maintained sufficiently subcritical to preclude inadvertent criticality in the shutdown condition.

These requirements are satisfied by the control rods, as described in GDC 26 (Ref. 1), which can compensate for the reactivity effects of the fuel and water temperature changes experienced during all operating conditions.

APPLICABLE SAFETY ANALYSES

Having sufficient SDM assures that the reactor will become and remain subcritical after all design basis accidents and transients. For example, SDM is assumed as an initial condition for the control rod removal error during a refueling accident (Ref. 2). The analysis of this reactivity insertion event assumes the refueling interlocks are OPERABLE when the reactor is in the refueling mode of operation. These interlocks prevent the withdrawal of more than one control rod from the core during refueling. (Special consideration and requirements for multiple control rod withdrawal during refueling are covered in Special Operations LCO 3.10.5, "Multiple Control Rod Withdrawal-Refueling.") The analysis assumes this condition is acceptable since the core will be shut down with the highest worth control rod withdrawn, if adequate SDM has been demonstrated.

Prevention or mitigation of positive reactivity insertion events is necessary to limit the energy deposition in the fuel, thereby preventing significant fuel damage, which

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BASES

APPLICABLE
SAFETY ANALYSES
(continued)

could result in undue release of radioactivity. Adequate SDM ensures inadvertent criticalities do not cause significant fuel damage.

SDM satisfies Criterion 2 of 10 CFR 50.36(c)(2)(ii).

LCO

The specified SDM limit accounts for the uncertainty in the demonstration of SDM by testing. Separate SDM limits are provided for testing where the highest worth control rod is determined analytically or by measurement. This is due to the reduced uncertainty in the SDM test when the highest worth control rod is determined by measurement. When SDM is demonstrated by calculations not associated with a test (e.g., to confirm SDM during the fuel loading sequence), additional margin is included to account for uncertainties in the calculation. To ensure adequate SDM, a design margin is included to account for uncertainties in the design calculations (Ref. 3).

APPLICABILITY

In MODES 1 and 2, SDM must be provided to assure shutdown capability. In MODES 3 and 4, SDM is required to ensure the reactor will be held subcritical with margin for a single withdrawn control rod. SDM is required in MODE 5 to prevent an inadvertent criticality during the withdrawal of a single control rod from a core cell containing one or more fuel assemblies (Ref. 2).

ACTIONS

A.1

With SDM not within the limits of the LCO in MODE 1 or 2, SDM must be restored within 6 hours. Failure to meet the specified SDM may be caused by a control rod that cannot be inserted. The 6 hour Completion time is acceptable, considering that the reactor can still be shut down, assuming no additional failures of control rods to insert, and the low probability of an event occurring during this interval.

(continued)

BASES

ACTIONS
(continued)

B.1

If the SDM cannot be restored, the plant must be brought to MODE 3 within 12 hours, to prevent the potential for further reductions in available SDM (e.g., additional stuck control rods). The allowed Completion Time of 12 hours is reasonable, based on operating experience, to reach MODE 3 from full power conditions in an orderly manner and without challenging plant systems.

C.1

With SDM not within limits in MODE 3, the operator must immediately initiate action to fully insert all insertable control rods. Action must continue until all insertable control rods are fully inserted. This action results in the least reactive condition for the core.

D.1, D.2, D.3, and D.4

With SDM not within limits in MODE 4, the operator must immediately initiate action to fully insert all insertable control rods. Action must continue until all insertable control rods are fully inserted. This action results in the least reactive condition for the core. Actions must also be initiated within 1 hour to provide means for control of potential radioactive releases. This includes ensuring secondary containment is OPERABLE; at least one Standby Gas Treatment (SGT) subsystem is OPERABLE; and secondary containment isolation capability is available in each associated secondary containment penetration flow path not isolated that is assumed to be isolated to mitigate radioactivity releases (i.e., at least one secondary containment isolation valve and associated instrumentation are OPERABLE, or other acceptable administrative controls to assure isolation capability). These administrative controls consist of stationing a dedicated operator, who is in continuous communication with the control room, at the controls of the isolation device. In this way, the penetration can be rapidly isolated when a need for secondary containment isolation is indicated. This (ensuring components are OPERABLE) may be performed as an

(continued)

BASES

ACTIONS

D.1, D.2, D.3, and D.4 (continued)

administrative check, by examining logs or other information, to determine if the components are out of service for maintenance or other reasons. It is not necessary to perform the Surveillances needed to demonstrate the OPERABILITY of the components. If, however, any required component is inoperable, then it must be restored to OPERABLE status. In this case, SRs may need to be performed to restore the component to OPERABLE status. Actions must continue until all required components are OPERABLE.

E.1, E.2, E.3, E.4, and E.5

With SDM not within limits in MODE 5, the operator must immediately suspend CORE ALTERATIONS that could reduce SDM, e.g., insertion of fuel in the core or the withdrawal of control rods. Suspension of these activities shall not preclude completion of movement of a component to a safe condition. Inserting control rods or removing fuel from the core will reduce the total reactivity and are therefore excluded from the suspended actions.

Action must also be immediately initiated to fully insert all insertable control rods in core cells containing one or more fuel assemblies. Action must continue until all insertable control rods in core cells containing one or more fuel assemblies have been fully inserted. Control rods in core cells containing no fuel assemblies do not affect the reactivity of the core and therefore do not have to be inserted.

Action must also be initiated within 1 hour to provide means for control of potential radioactive releases. This includes ensuring secondary containment is OPERABLE; at least one SGT subsystem is OPERABLE; and secondary containment isolation capability is available in each associated secondary containment penetration flow path not isolated that is assumed to be isolated to mitigate radioactivity releases (i.e., at least one secondary containment isolation valve and associated instrumentation are OPERABLE, or other acceptable administrative controls to assure isolation capability). These administrative controls

(continued)

BASES

ACTIONS

E.1, E.2, E.3, E.4, and E.5 (continued)

consist of stationing a dedicated operator, who is in continuous communication with the control room, at the controls of the isolation device. In this way, the penetration can be rapidly isolated when a need for secondary containment isolation is indicated. This (ensuring components are OPERABLE) may be performed as an administrative check, by examining logs or other information, to determine if the components are out of service for maintenance or other reasons. It is not necessary to perform the Surveillances needed to demonstrate the OPERABILITY of the components. If, however, any required component is inoperable, then it must be restored to OPERABLE status. In this case, SRs may need to be performed to restore the component to OPERABLE status. Actions must continue until all required components are OPERABLE.

SURVEILLANCE
REQUIREMENTSSR 3.1.1.1

Adequate SDM must be verified to ensure the reactor can be made subcritical from any initial operating condition. This can be accomplished by a test, an evaluation, or a combination of the two. Adequate SDM is demonstrated by testing before or during the first startup after fuel movement, shuffling within the reactor pressure vessel, or control rod replacement. Control rod replacement refers to the decoupling and removal of a control rod from a core location, and subsequent replacement with a new control rod or a control rod from another core location. Since core reactivity will vary during the cycle as a function of fuel depletion and poison burnup, the beginning of cycle (BOC) test must also account for changes in core reactivity during the cycle. Therefore, to obtain the SDM, the initial measured value must be increased by an adder, "R", which is the difference between the calculated value of maximum core reactivity during the operating cycle and the calculated BOC core reactivity. If the value of R is negative (i.e., BOC is the most reactive point in the cycle), no correction to the BOC measured value is required (Ref. 4). For the SDM demonstrations that rely solely on calculation of the highest worth control rod, additional margin (0.10% $\Delta k/k$) must be added to the SDM limit of 0.28% $\Delta k/k$ to account for uncertainties in the calculation.

(continued)

BASES

SURVEILLANCE
REQUIREMENTS

SR 3.1.1.1 (continued)

The SDM may be demonstrated during an in-sequence control rod withdrawal, in which the highest worth control rod is analytically determined, or during local criticals, where the highest worth control rod is determined by testing. Local critical tests require the withdrawal of out of sequence control rods. This testing would therefore require bypassing of the Rod Worth Minimizer to allow the out of sequence withdrawal, and therefore additional requirements must be met (see LCO 3.10.6, "Control Rod Testing - Operating").

The Frequency of 4 hours after reaching criticality is allowed to provide a reasonable amount of time to perform the required calculations and appropriate verification.

During MODES 3 and 4, analytical calculation of SDM may be used to assure the requirements of SR 3.1.1.1 are met. During MODE 5, adequate SDM is also required to ensure the reactor does not reach criticality during control rod withdrawals. An evaluation of each in vessel fuel movement during fuel loading (including shuffling fuel within the core) is required to ensure adequate SDM is maintained during refueling. This evaluation ensures the intermediate loading patterns are bounded by the safety analyses for the final core loading pattern. For example, bounding analyses that demonstrate adequate SDM for the most reactive configurations during the refueling may be performed to demonstrate acceptability of the entire fuel movement sequence. These bounding analyses include additional margins to the associated uncertainties. Spiral offload or reload sequences inherently satisfy the SR, provided the fuel assemblies are reloaded in the same configuration analyzed for the new cycle. Removing fuel from the core will always result in an increase in SDM.

REFERENCES

1. 10 CFR 50, Appendix A, GDC 26.
2. UFSAR, Section 15.4.1.1.
3. UFSAR, Section 4.3.2.4.1.
4. NEDE-24011-P-A, "GE Standard Application for Reactor Fuel," (as specified in Technical Specification 5.6.5).

B 3.1 REACTIVITY CONTROL SYSTEMS

B 3.1.2 Reactivity Anomalies

BASES

BACKGROUND

In accordance with GDC 26, GDC 28, and GDC 29 (Ref. 1), reactivity shall be controllable such that subcriticality is maintained under cold conditions and acceptable fuel design limits are not exceeded during normal operation and anticipated operational occurrences. Reactivity Anomalies is used as a measure of the predicted versus measured core reactivity during power operation. The continual confirmation of core reactivity is necessary to ensure that the Design Basis Accident (DBA) and transient safety analyses remain valid. A large reactivity anomaly could be the result of unanticipated changes in fuel reactivity, control rod worth, or operation at conditions not consistent with those assumed in the predictions of core reactivity, and could potentially result in a loss of SDM or violation of acceptable fuel design limits. Comparing predicted versus measured core reactivity validates the nuclear methods used in the safety analysis and supports the SDM demonstrations (LCO 3.1.1, "SHUTDOWN MARGIN (SDM)") in ensuring the reactor can be brought safely to cold, subcritical conditions.

When the reactor core is critical or in normal power operation, a reactivity balance exists and the net reactivity is zero. A comparison of predicted and measured reactivity is convenient under such a balance, since parameters are being maintained relatively stable under steady state power conditions. The positive reactivity inherent in the core design is balanced by the negative reactivity of the control components, thermal feedback, neutron leakage, and materials in the core that absorb neutrons, such as burnable absorbers, producing zero net reactivity.

In order to achieve the required fuel cycle energy output, the uranium enrichment in the new fuel loading and the fuel loaded in the previous cycles provide excess positive reactivity beyond that required to sustain steady state operation at the beginning of cycle (BOC). When the reactor is critical at RTP and operating moderator temperature, the

(continued)

BASES

BACKGROUND
(continued)

excess positive reactivity is compensated by burnable absorbers (e.g., gadolinia), control rods, and whatever neutron poisons (mainly xenon and samarium) are present in the fuel.

The predicted core reactivity, as represented by k effective (k_{eff}), is calculated by a 3D core simulator code as a function of cycle exposure. This calculation is performed for projected operating states and conditions throughout the cycle. The monitored k_{eff} is calculated by the core monitoring system for actual plant conditions and is then compared to the predicted value for the cycle exposure.

APPLICABLE
SAFETY ANALYSES

Accurate prediction of core reactivity is either an explicit or implicit assumption in the accident analysis evaluations (Ref. 2). In particular, SDM and reactivity transients, such as control rod withdrawal accidents or rod drop accidents, are very sensitive to accurate prediction of core reactivity. These accident analysis evaluations rely on computer codes that have been qualified against available test data, operating plant data, and analytical benchmarks. Monitoring reactivity anomaly provides additional assurance that the nuclear methods provide an accurate representation of the core reactivity.

The comparison between measured and predicted initial core reactivity provides a normalization for the calculational models used to predict core reactivity. If the measured and predicted k_{eff} for identical core conditions at BOC do not reasonably agree, then the assumptions used in the reload cycle design analysis or the calculation models used to predict k_{eff} may not be accurate. If reasonable agreement between measured and predicted core reactivity exists at BOC, then the prediction may be normalized to the measured value. Thereafter, any significant deviations in the measured k_{eff} from the predicted k_{eff} that develop during fuel depletion may be an indication that the assumptions of the DBA and transient analyses are no longer valid, or that an unexpected change in core conditions has occurred.

Reactivity Anomalies satisfy Criterion 2 of 10 CFR 50.36(c)(2)(ii).

(continued)

BASES (continued)

LCO The reactivity anomaly limit is established to ensure plant operation is maintained within the assumptions of the safety analyses. Large differences between monitored and predicted core reactivity may indicate that the assumptions of the DBA and transient analyses are no longer valid, or that the uncertainties in the Nuclear Design Methodology are larger than expected. A limit on the difference between the monitored core k_{eff} and the predicted core k_{eff} of $1\% \Delta k/k$ has been established based on engineering judgment. A $> 1\%$ deviation in reactivity from that predicted is larger than expected for normal operation and should therefore be evaluated.

APPLICABILITY In MODE 1, most of the control rods are withdrawn and steady state operation is typically achieved. Under these conditions, the comparison between predicted and monitored core reactivity provides an effective measure of the reactivity anomaly. In MODE 2, control rods are typically being withdrawn during a startup. In MODES 3 and 4, all control rods are fully inserted, and, therefore, the reactor is in the least reactive state, where monitoring core reactivity is not necessary. In MODE 5, fuel loading results in a continually changing core reactivity. SDM requirements (LCO 3.1.1) ensure that fuel movements are performed within the bounds of the safety analysis, and an SDM demonstration is required during the first startup following operations that could have altered core reactivity (e.g., fuel movement, control rod replacement, control rod shuffling). The SDM test, required by LCO 3.1.1, provides a direct comparison of the predicted and monitored core reactivity at cold conditions; therefore, Reactivity Anomalies is not required during these conditions.

ACTIONS

A.1

Should an anomaly develop between measured and predicted core reactivity, the core reactivity difference must be restored to within the limit to ensure continued operation is within the core design assumptions. Restoration to within the limit could be performed by an evaluation of the core design and safety analysis to determine the reason for the anomaly. This evaluation normally reviews the core

(continued)

BASES

ACTIONS

A.1 (continued)

conditions to determine their consistency with input to design calculations. Measured core and process parameters are also normally evaluated to determine that they are within the bounds of the safety analysis, and safety analysis calculational models may be reviewed to verify that they are adequate for representation of the core conditions. The required Completion Time of 72 hours is based on the low probability of a DBA during this period, and allows sufficient time to assess the physical condition of the reactor and complete the evaluation of the core design and safety analysis.

B.1

If the core reactivity cannot be restored to within the 1% $\Delta k/k$ limit, the plant must be brought to a MODE in which the LCO does not apply. To achieve this status, the plant must be brought to at least MODE 3 within 12 hours. The allowed Completion Time of 12 hours is reasonable, based on operating experience, to reach MODE 3 from full power conditions in an orderly manner and without challenging plant systems.

SURVEILLANCE
REQUIREMENTS

SR 3.1.2.1

Verifying the reactivity difference between the monitored and predicted core k_{eff} is within the limits of the LCO provides further assurance that plant operation is maintained within the assumptions of the DBA and transient analyses. The Core Monitoring System calculates the core k_{eff} for the reactor conditions obtained from plant instrumentation. A comparison of the monitored core k_{eff} to the predicted core k_{eff} at the same cycle exposure is used to calculate the reactivity difference. The comparison is required when the core reactivity has potentially changed by a significant amount. This may occur following a refueling in which new fuel assemblies are loaded, fuel assemblies are shuffled within the core, or control rods are replaced or shuffled. Control rod replacement refers to the decoupling and removal of a control rod from a core location, and

(continued)

BASES

SURVEILLANCE
REQUIREMENTS

SR 3.1.2.1 (continued)

subsequent replacement with a new control rod or a control rod from another core location. Also, core reactivity changes during the cycle. The 24 hour interval after reaching equilibrium conditions following a startup is based on the need for equilibrium xenon concentrations in the core, such that an accurate comparison between the monitored and predicted core k_{eff} values can be made. For the purposes of this SR, the reactor is assumed to be at equilibrium conditions when steady state operations (no control rod movement or core flow changes) at $\geq 75\%$ RTP have been obtained. The 1000 MWD/T Frequency was developed, considering the relatively slow change in core reactivity with exposure and operating experience related to variations in core reactivity. This comparison requires the core to be operating at power levels which minimize the uncertainties and measurement errors, in order to obtain meaningful results. Therefore, the comparison is only done when in MODE 1. The core weight, tons (T) in MWD/T, reflects metric tons.

REFERENCES

1. 10 CFR 50, Appendix A, GDC 26, GDC 28, and GDC 29.
 2. UFSAR, Chapter 15.
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B 3.1 REACTIVITY CONTROL SYSTEMS

B 3.1.3 Control Rod OPERABILITY

BASES

BACKGROUND

Control rods are components of the Control Rod Drive (CRD) System, which is the primary reactivity control system for the reactor. In conjunction with the Reactor Protection System, the CRD System provides the means for the reliable control of reactivity changes to ensure that under conditions of normal operation, including anticipated operational occurrences, specified acceptable fuel design limits are not exceeded. In addition, the control rods provide the capability to hold the reactor core subcritical under all conditions and to limit the potential amount and rate of reactivity increase caused by a malfunction in the CRD System. The CRD System is designed to satisfy the requirements of GDC 26, GDC 27, GDC 28, and GDC 29, (Ref. 1).

The CRD System consists of 185 locking piston control rod drive mechanisms (CRDMs) and a hydraulic control unit for each drive mechanism. The locking piston type CRDM is a double acting hydraulic piston, which uses condensate water as the operating fluid. Accumulators provide additional energy for scram. An index tube and piston, coupled to the control rod, are locked at fixed increments by a collet mechanism. The collet fingers engage notches in the index tube to prevent unintentional withdrawal of the control rod, but without restricting insertion.

This Specification, along with LCO 3.1.4, "Control Rod Scram Times," LCO 3.1.5, "Control Rod Scram Accumulators," and LCO 3.1.6, "Rod Pattern Control," ensure that the performance of the control rods in the event of a Design Basis Accident (DBA) or transient meets the assumptions used in the safety analyses of References 2, 3, 4, 5, and 6.

APPLICABLE
SAFETY ANALYSES

The analytical methods and assumptions used in the evaluations involving control rods are presented in References 2, 3, 4, 5, and 6. The control rods provide the primary means for rapid reactivity control (reactor scram), for maintaining the reactor subcritical, and for limiting the potential effects of reactivity insertion events caused by malfunctions in the CRD System.

(continued)

BASES

APPLICABLE
SAFETY ANALYSES
(continued)

The capability of inserting the control rods provides assurance that the assumptions for scram reactivity in the DBA and transient analyses are not violated. Since the SDM ensures the reactor will be subcritical with the highest worth control rod withdrawn (assumed single failure), the additional failure of a second control rod to insert could invalidate the demonstrated SDM and potentially limit the ability of the CRD System to hold the reactor subcritical. If the control rod is stuck at an inserted position and becomes decoupled from the CRD, a control rod drop accident (CRDA) can possibly occur. Therefore, the requirement that all control rods be OPERABLE ensures the CRD System can perform its intended function.

The control rods also protect the fuel from damage that results in release of radioactivity. The limits protected are the MCPR Safety Limit (SL) (see Bases for SL 2.1.1, "Reactor Core SLs," and LCO 3.2.2, "MINIMUM CRITICAL POWER RATIO (MCPR)"), the 1% cladding plastic strain fuel design limit (see Bases for LCO 3.2.1, "AVERAGE PLANAR LINEAR HEAT GENERATION RATE (APLGR)," and LCO 3.2.3, "LINEAR HEAT GENERATION RATE (LHGR)"), and the fuel design limit (see Bases for LCO 3.1.6, "Rod Pattern Control") during reactivity insertion events.

The negative reactivity insertion (scram) provided by the CRD System provides the analytical basis for determination of plant thermal limits and provides protection against fuel design limits during a CRDA. Bases for LCO 3.1.4, LCO 3.1.5, and LCO 3.1.6 discuss in more detail how the SLs are protected by the CRD System.

Control rod OPERABILITY satisfies Criterion 3 of 10 CFR 50.36(c)(2)(ii).

LCO

OPERABILITY of an individual control rod is based on a combination of factors, primarily the scram insertion times, the control rod coupling integrity, and the ability to determine the control rod position. Accumulator OPERABILITY is addressed by LCO 3.1.5. The associated scram accumulator status for a control rod only affects the scram insertion times and therefore an inoperable accumulator does not

(continued)

BASES

LCO
(continued) immediately require declaring a control rod inoperable. Although not all control rods are required to be OPERABLE to satisfy the intended reactivity control requirements, strict control over the number and distribution of inoperable control rods is required to satisfy the assumptions of the DBA and transient analyses.

OPERABILITY requirements for control rods also includes correct assembly of the CRD housing supports.

APPLICABILITY In MODES 1 and 2, the control rods are assumed to function during a DBA or transient and are therefore required to be OPERABLE in these MODES. In MODES 3 and 4, control rods are not able to be withdrawn since the reactor mode switch is in shutdown and a control rod block is applied. This provides adequate requirements for control rod OPERABILITY during these conditions. Control rod requirements in MODE 5 are located in LCO 3.9.5, "Control Rod OPERABILITY - Refueling."

ACTIONS The ACTIONS Table is modified by a Note indicating that a separate Condition entry is allowed for each control rod. This is acceptable, since the Required Actions for each Condition provide appropriate compensatory actions for each inoperable control rod. Complying with the Required Actions may allow for continued operation, and subsequent inoperable control rods are governed by subsequent Condition entry and application of associated Required Actions.

A.1, A.2, A.3, and A.4

A control rod is considered stuck if it will not insert by either CRD drive water or scram pressure. The Required Actions are modified by a Note that allows the Rod Worth Minimizer (RWM) to be bypassed if required to allow continued operation. LCO 3.3.2.1, "Control Rod Block Instrumentation," provides additional requirements when the RWM is bypassed to ensure compliance with the CRDA analysis. With one withdrawn control rod stuck, the local scram reactivity rate assumptions may not be met if the stuck

(continued)

BASES

ACTIONS A.1, A.2, A.3, and A.4 (continued)

control rod separation criteria are not met. Therefore, a verification that the separation criteria are met must be performed immediately. The separation criteria are not met if: a) the stuck control rod occupies a location adjacent to two "slow" control rods, b) the stuck control rod occupies a location adjacent to one "slow" control rod, and the one "slow" control rod is also adjacent to another "slow" control rod, or c) if the stuck control rod occupies a location adjacent to one "slow" control rod when there is another pair of "slow" control rods elsewhere in the core adjacent to one another. The description of "slow" control rods is provided in LCO 3.1.4, "Control Rod Scram Times." In addition, the associated control rod drive must be disarmed within 2 hours. The allowed Completion Time of 2 hours is acceptable, considering the reactor can still be shut down, assuming no additional control rods fail to insert, and provides a reasonable amount of time to perform the Required Action in an orderly manner. The control rod must be isolated from both scram and normal insert and withdraw pressure. Isolating the control rod from scram and normal insert and withdraw pressure prevents damage to the CRDM or reactor internals. The control rod isolation method should also ensure cooling water to the CRD is maintained.

Monitoring of the insertion capability for each withdrawn control rod must also be performed within 24 hours from discovery of Condition A concurrent with THERMAL POWER greater than the low power setpoint (LPSP) of the RWM. SR 3.1.3.2 and SR 3.1.3.3 perform periodic tests of the control rod insertion capability of withdrawn control rods. Testing each withdrawn control rod ensures that a generic problem does not exist. This Completion Time also allows for an exception to the normal "time zero" for beginning the allowed outage time "clock." The Required Action A.3 Completion Time only begins upon discovery of Condition A concurrent with THERMAL POWER greater than the actual LPSP of the RWM, since the notch insertions may not be compatible with the requirements of rod pattern control (LCO 3.1.6) and the RWM (LCO 3.3.2.1). The allowed Completion Time provides a reasonable time to test the control rods, considering the potential for a need to reduce power to perform the tests.

(continued)

BASES

ACTIONS

A.1, A.2, A.3, and A.4 (continued)

To allow continued operation with a withdrawn control rod stuck, an evaluation of adequate SDM is also required within 72 hours. Should a DBA or transient require a shutdown, to preserve the single failure criterion an additional control rod would have to be assumed to have failed to insert when required. Therefore, the original SDM demonstration may not be valid. The SDM must therefore be evaluated (by measurement or analysis) with the stuck control rod at its stuck position and the highest worth OPERABLE control rod assumed to be fully withdrawn.

The allowed Completion Time of 72 hours to verify SDM is adequate, considering that with a single control rod stuck in a withdrawn position, the remaining OPERABLE control rods are capable of providing the required scram and shutdown reactivity. Failure to reach MODE 4 is only likely if an additional control rod adjacent to the stuck control rod also fails to insert during a required scram. Even with the postulated additional single failure of an adjacent control rod to insert, sufficient reactivity control remains to reach MODE 3 conditions.

B.1

With two or more withdrawn control rods stuck, the plant must be brought to MODE 3 within 12 hours. The occurrence of more than one control rod stuck at a withdrawn position increases the probability that the reactor cannot be shut down if required. Insertion of all insertable control rods eliminates the possibility of an additional failure of a control rod to insert. The allowed Completion Time of 12 hours is reasonable, based on operating experience, to reach MODE 3 from full power conditions in an orderly manner and without challenging plant systems.

C.1 and C.2

With one or more control rods inoperable for reasons other than being stuck in the withdrawn position, operation may continue, provided the control rods are fully inserted

(continued)

BASES

ACTIONS

C.1 and C.2 (continued)

within 3 hours and disarmed (electrically or hydraulically) within 4 hours. Inserting a control rod ensures the shutdown and scram capabilities are not adversely affected. The control rod is disarmed to prevent inadvertent withdrawal during subsequent operations. The control rods can be hydraulically disarmed by closing the drive water and exhaust water isolation valves. Electrically, the control rods can be disarmed by disconnecting power from all four directional control valve solenoids. Required Action C.1 is modified by a Note that allows the RWM to be bypassed if required to allow insertion of the inoperable control rods and continued operation. LCO 3.3.2.1 provides additional requirements when the RWM is bypassed to ensure compliance with the CRDA analysis.

The allowed Completion Times are reasonable, considering the small number of allowed inoperable control rods, and provide time to insert and disarm the control rods in an orderly manner and without challenging plant systems.

D.1 and D.2

Out of sequence control rods may increase the potential reactivity worth of a dropped control rod during a CRDA. At $\leq 10\%$ RTP, the analyzed rod position sequence analysis (Refs. 7 and 8) requires inserted control rods not in compliance with the analyzed rod position sequence to be separated by at least two OPERABLE control rods in all directions, including the diagonal (i.e., all other control rods in a five-by-five array centered on the inoperable control rod are OPERABLE). Therefore, if two or more inoperable control rods are not in compliance with the analyzed rod position sequence and not separated by at least two OPERABLE control rods in all directions, action must be taken to restore compliance with the analyzed rod position sequence or restore the control rods to OPERABLE status. A Note has been added to the Condition to clarify that the Condition is not applicable when $> 10\%$ RTP since the analyzed rod position sequence is not required to be followed under these conditions, as described in the Bases for LCO 3.1.6. The allowed Completion Time of 4 hours is acceptable, considering the low probability of a CRDA occurring.

(continued)

BASES

ACTIONS
(continued)

E.1

If any Required Action and associated Completion Time of Condition A, C, or D are not met or nine or more inoperable control rods exist, the plant must be brought to a MODE in which the LCO does not apply. To achieve this status, the plant must be brought to MODE 3 within 12 hours. This ensures all insertable control rods are inserted and places the reactor in a condition that does not require the active function (i.e., scram) of the control rods. The number of control rods permitted to be inoperable when operating above 10% RTP (i.e., no CRDA considerations) could be more than the value specified, but the occurrence of a large number of inoperable control rods could be indicative of a generic problem, and investigation and resolution of the potential problem should be undertaken. The allowed Completion Time of 12 hours is reasonable, based on operating experience, to reach MODE 3 from full power conditions in an orderly manner and without challenging plant systems.

SURVEILLANCE
REQUIREMENTS

SR 3.1.3.1

The position of each control rod must be determined, to ensure adequate information on control rod position is available to the operator for determining control rod OPERABILITY and controlling rod patterns. Control rod position may be determined by the use of OPERABLE position indicators, by moving control rods by single notch movement to a position with an OPERABLE indicator (full-in, full-out, or numeric indicator) and then returning the control rods by single notch movement to their original position, or by the use of other appropriate methods. The 24 hour Frequency of this SR is based on operating experience related to expected changes in control rod position and the availability of control rod position indications in the control room.

(continued)

BASES

SURVEILLANCE
REQUIREMENTS
(continued)

SR 3.1.3.2 and SR 3.1.3.3

Control rod insertion capability is demonstrated by inserting each partially or fully withdrawn control rod at least one notch and observing that the control rod moves. The control rod may then be returned to its original position. This ensures the control rod is not stuck and is free to insert on a scram signal. These Surveillances are not required when THERMAL POWER is less than or equal to the actual LPSP of the RWM since the notch insertions may not be compatible with the requirements of the analyzed rod position sequence (LCO 3.1.6) and the RWM (LCO 3.3.2.1). The 7 day Frequency of SR 3.1.3.2 is based on operating experience related to the changes in CRD performance and the ease of performing notch testing for fully withdrawn control rods. Partially withdrawn control rods are tested at a 31 day Frequency, based on the potential power reduction required to allow the control rod movement, and considering the large testing sample of SR 3.1.3.2. Furthermore, the 31 day Frequency takes into account operating experience related to changes in CRD performance. At any time, if a control rod is immovable, a determination of that control rod's trippability (OPERABILITY) must be made and appropriate action taken.

These SRs are modified by Notes that allow 7 days and 31 days respectively, after withdrawal of the control rod and increasing power to above the LPSP, to perform the Surveillance. This acknowledges that the control rod must be first withdrawn and THERMAL POWER must be increased to above the LPSP before performance of the Surveillance, and therefore, the Notes avoid potential conflicts with SR 3.0.3 and SR 3.0.4.

(continued)

BASES

SURVEILLANCE
REQUIREMENTS
(continued)

SR 3.1.3.4

Verifying the scram time for each control rod to notch position 05 is ≤ 7 seconds provides reasonable assurance that the control rod will insert when required during a DBA or transient, thereby completing its shutdown function. This SR is performed in conjunction with the control rod scram time testing of SR 3.1.4.1, SR 3.1.4.2, SR 3.1.4.3, and SR 3.1.4.4. The LOGIC SYSTEM FUNCTIONAL TEST in LCO 3.3.1.1, "Reactor Protection System (RPS) Instrumentation," and the functional testing of SDV vent and drain valves in LCO 3.1.8, "Scram Discharge Volume (SDV) Vent and Drain Valves," overlap this Surveillance to provide complete testing of the assumed safety function. The associated Frequencies are acceptable, considering the more frequent testing performed to demonstrate other aspects of control rod OPERABILITY and operating experience, which shows scram times do not significantly change over an operating cycle.

SR 3.1.3.5

Coupling verification is performed to ensure the control rod is connected to the CRDM and will perform its intended function when necessary. The Surveillance requires verifying that a control rod does not go to the withdrawn, overtravel position when it is fully withdrawn. The overtravel position feature provides a positive check on the coupling integrity, since only an uncoupled CRD can reach the overtravel position. The verification is required to be performed anytime a control rod is withdrawn to the "full out" position (notch position 48) or prior to declaring the control rod OPERABLE after work on the control rod or CRD System that could affect coupling. This includes control rods inserted one notch and then returned to the "full out" position during the performance of SR 3.1.3.2. This Frequency is acceptable, considering the low probability that a control rod will become uncoupled when it is not being moved and operating experience related to uncoupling events.

(continued)

BASES (continued)

- REFERENCES
1. 10 CFR 50, Appendix A, GDC 26, GDC 27, GDC 28, and GDC 29.
 2. UFSAR, Section 4.3.2.5.
 3. UFSAR, Section 4.6.1.1.2.
 4. UFSAR, Section 5.2.2.2.
 5. UFSAR, Section 15.4.
 6. UFSAR, Section 15.4.9.
 7. NEDO-21231, "Banked Position Withdrawal Sequence," Section 7.2, January 1977.
 8. NFSR-0091, Commonwealth Edison Topical Report, Benchmark of CASMO/MICROBURN BWR Nuclear Design Methods, (as specified in Technical Specification 5.6.5).
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B 3.1 REACTIVITY CONTROL SYSTEMS

B 3.1.4 Control Rod Scram Times

BASES

BACKGROUND

The scram function of the Control Rod Drive (CRD) System controls reactivity changes during anticipated operational occurrences to ensure that specified acceptable fuel design limits are not exceeded (Ref. 1). The control rods are scrammed by positive means, using hydraulic pressure exerted on the CRD piston.

When a scram signal is initiated, control air is vented from the scram valves, allowing them to open by spring action. Opening the exhaust valves reduces the pressure above the main drive piston to atmospheric pressure, and opening the inlet valve applies the accumulator or reactor pressure to the bottom of the piston. Since the notches in the index tube are tapered on the lower edge, the collet fingers are forced open by cam action, allowing the index tube to move upward without restriction because of the high differential pressure across the piston. As the drive moves upward and accumulator pressure drops below the reactor pressure, a ball check valve opens, letting the reactor pressure complete the scram action. If the reactor pressure is low, such as during startup, the accumulator will fully insert the control rod within the required time without assistance from reactor pressure.

APPLICABLE
SAFETY ANALYSES

The analytical methods and assumptions used in evaluating the control rod scram function are presented in References 2, 3, 4, 5, and 6. The Design Basis Accident (DBA) and transient analyses assume that all of the control rods scram at a specified insertion rate. The resulting negative scram reactivity forms the basis for the determination of plant thermal limits (e.g., the MCPR). Other distributions of scram times (e.g., several control rods scramming slower than the average time, with several control rods scramming faster than the average time) can also provide sufficient scram reactivity. Surveillance of each individual control rod's scram time ensures the scram reactivity assumed in the DBA and transient analyses can be met.

(continued)

BASES

APPLICABLE
SAFETY ANALYSES
(continued)

The scram function of the CRD System protects the MCPR Safety Limit (SL) (see Bases for SL 2.1.1, "Reactor Core SLs," and LCO 3.2.2, "MINIMUM CRITICAL POWER RATIO (MCPR)"), and the 1% cladding plastic strain fuel design limit (see Bases for LCO 3.2.1, "AVERAGE PLANAR LINEAR HEAT GENERATION RATE (APLHGR)," and LCO 3.2.3, "LINEAR HEAT GENERATION RATE (LHGR)"), which ensure that no fuel damage will occur if these limits are not exceeded. Above 800 psig, the scram function is designed to insert negative reactivity at a rate fast enough to prevent the actual MCPR from becoming less than the MCPR SL during the analyzed limiting power transient. Below 800 psig, the scram function is assumed to perform during the control rod drop accident (Ref. 6) and, therefore, also provides protection against violating fuel design limits during reactivity insertion accidents (see Bases for LCO 3.1.6, "Rod Pattern Control"). For the reactor vessel overpressure protection analysis (Ref. 4), the scram function, along with the safety/relief valves, ensure that the peak vessel pressure is maintained within the applicable ASME Code limits.

Control rod scram times satisfy Criterion 3 of 10 CFR 50.36(c)(2)(ii).

LCO

The scram times specified in Table 3.1.4-1 are required to ensure that the scram reactivity assumed in the DBA and transient analysis is met. To account for single failure and "slow" scrambling control rods, the scram times specified in Table 3.1.4-1 are faster than those assumed in the design basis analysis. The scram times have a margin to allow up to 7.0% of the control rods (e.g., $185 \times 7.0\% \approx 12$) to have scram times that exceed the specified limits (i.e., "slow" control rods) assuming a single stuck control rod (as allowed by LCO 3.1.3, "Control Rod OPERABILITY") and an additional control rod failing to scram per the single failure criterion. The scram times are specified as a function of reactor steam dome pressure to account for the pressure dependence of the scram times. The scram times are specified relative to measurements based on reed switch positions, which provide the control rod position indication. The reed switch closes ("pickup") when the index tube passes a specific location and then opens ("dropout") as the index tube travels upward. Verification of the specified scram times in Table 3.1.4-1 is accomplished through measurement of the "dropout" times.

(continued)

BASES

LCO
(continued)

To ensure that local scram reactivity rates are maintained within acceptable limits, no more than two of the allowed "slow" control rods may occupy adjacent (face or diagonal) locations.

Table 3.1.4-1 is modified by two Notes, which state control rods with scram times not within the limits of the Table are considered "slow" and that control rods with scram times > 7 seconds are considered inoperable as required by SR 3.1.3.4.

This LCO applies only to OPERABLE control rods since inoperable control rods will be inserted and disarmed (LCO 3.1.3). Slow scrambling control rods may be conservatively declared inoperable and not accounted for as "slow" control rods.

APPLICABILITY

In MODES 1 and 2, a scram is assumed to function during transients and accidents analyzed for these plant conditions. These events are assumed to occur during startup and power operation; therefore, the scram function of the control rods is required during these MODES. In MODES 3 and 4, the control rods are not able to be withdrawn since the reactor mode switch is in shutdown and a control rod block is applied. This provides adequate requirements for control rod scram capability during these conditions. Scram requirements in MODE 5 are contained in LCO 3.9.5, "Control Rod OPERABILITY - Refueling."

ACTIONS

A.1

When the requirements of this LCO are not met, the rate of negative reactivity insertion during a scram may not be within the assumptions of the safety analyses. Therefore, the plant must be brought to a MODE in which the LCO does not apply. To achieve this status, the plant must be brought to MODE 3 within 12 hours. The allowed Completion Time of 12 hours is reasonable, based on operating experience, to reach MODE 3 from full power conditions in an orderly manner and without challenging plant systems.

(continued)

BASES (continued)

SURVEILLANCE
REQUIREMENTS

The four SRs of this LCO are modified by a Note stating that during a single control rod scram time surveillance, the CRD pumps shall be isolated from the associated scram accumulator. With the CRD pump isolated (i.e., charging valve closed), the influence of the CRD pump head does not affect the single control rod scram times. During a full core scram, the CRD pump head would be seen by all control rods and would have a negligible effect on the scram insertion times.

SR 3.1.4.1

The scram reactivity used in DBA and transient analyses is based on assumed control rod scram time. Measurement of the scram times with reactor steam dome pressure ≥ 800 psig demonstrates acceptable scram times for the transients analyzed in References 5 and 6.

Maximum scram insertion times occur at a reactor pressure of approximately 800 psig because of the competing effects of reactor steam dome pressure and stored accumulator energy. Therefore, demonstration of adequate scram times at reactor steam dome pressure ≥ 800 psig ensures that the scram times will be within the specified limits at higher pressures. Limits are specified as a function of reactor pressure to account for the sensitivity of the scram insertion times with pressure and to allow a range of pressures over which scram time testing can be performed. To ensure scram time testing is performed within a reasonable time following a shutdown ≥ 120 days, control rods are required to be tested before exceeding 40% RTP. This Frequency is acceptable, considering the additional Surveillances performed for control rod OPERABILITY, the frequent verification of adequate accumulator pressure, and the required testing of control rods affected by fuel movement within the associated core cell and by work on control rods or the CRD System.

SR 3.1.4.2

Additional testing of a sample of control rods is required to verify the continued performance of the scram function during the cycle. A representative sample contains at least

(continued)

BASES

SURVEILLANCE
REQUIREMENTS

SR 3.1.4.2 (continued)

10% of the control rods. The sample remains representative if no more than 20% of the control rods in the sample tested are determined to be "slow." If more than 20% of the sample is declared to be "slow" per the criteria in Table 3.1.4-1, additional control rods are tested until this 20% criterion (i.e., 20% of the entire sample size) is satisfied, or until the total number of "slow" control rods (throughout the core, from all Surveillances) exceeds the LCO limit. For planned testing, the control rods selected for the sample should be different for each test. Data from inadvertent scrams should be used whenever possible to avoid unnecessary testing at power, even if the control rods with data were previously tested in a sample. The 120 day Frequency is based on operating experience that has shown control rod scram times do not significantly change over an operating cycle. This Frequency is also reasonable, based on the additional Surveillances done on the CRDs at more frequent intervals in accordance with LCO 3.1.3 and LCO 3.1.5, "Control Rod Scram Accumulators."

SR 3.1.4.3

When work that could affect the scram insertion time is performed on a control rod or the CRD System, testing must be done to demonstrate that each affected control rod retains adequate scram performance over the range of applicable reactor pressures from zero to the maximum permissible pressure. The scram testing must be performed once before declaring the control rod OPERABLE. The required scram time testing must demonstrate that the affected control rod is still within acceptable limits. The scram time limits for reactor pressures < 800 psig are found in the Technical Requirements Manual (Ref. 7) and are established based on a high probability of meeting the acceptance criteria at reactor pressures \geq 800 psig. Limits for reactor pressures \geq 800 psig are found in Table 3.1.4-1. If testing demonstrates the affected control rod does not meet these limits, but is within 7-second limit of Table 3.1.4-1, Note 2, the control rod can be declared OPERABLE and "slow."

(continued)

BASES

SURVEILLANCE
REQUIREMENTS

SR 3.1.4.3 (continued)

Specific examples of work that could affect the scram times include (but are not limited to) the following: removal of any CRD for maintenance or modification; replacement of a control rod; and maintenance or modification of a scram solenoid pilot valve, scram valve, accumulator isolation valve, or check valves in the piping required for scram.

The Frequency of once prior to declaring the affected control rod OPERABLE is acceptable because of the capability of testing the control rod over a range of operating conditions and the more frequent surveillances on other aspects of control rod OPERABILITY.

SR 3.1.4.4

When work that could affect the scram insertion time is performed on a control rod or CRD System, or when fuel movement within the reactor pressure vessel occurs, testing must be done to demonstrate each affected control rod is still within the limits of Table 3.1.4-1 with the reactor steam dome pressure \geq 800 psig. Where work has been performed at high reactor pressure, the requirements of SR 3.1.4.3 and SR 3.1.4.4 will be satisfied with one test. For a control rod affected by work performed while shut down, however, a zero pressure and a high pressure test may be required. This testing ensures that the control rod scram performance is acceptable for operating reactor pressure conditions prior to withdrawing the control rod for continued operation. Alternatively, a test during hydrostatic pressure testing could also satisfy both criteria. When fuel movement within the reactor pressure vessel occurs, only those control rods associated with the core cells affected by the fuel movement are required to be scram time tested. During a routine refueling outage, it is expected that all control rods will be affected.

The Frequency of once prior to exceeding 40% RTP is acceptable because of the capability of testing the control rod at the different conditions and the more frequent surveillances on other aspects of control rod OPERABILITY.

(continued)

BASES (continued)

- REFERENCES
1. 10 CFR 50, Appendix A, GDC 10.
 2. UFSAR, Section 4.3.2.5.
 3. UFSAR, Section 4.6.1.1.2.
 4. UFSAR, Section 5.2.2.
 5. UFSAR, Section 15.4.
 6. UFSAR, Section 15.4.9.
 7. Technical Requirements Manual.
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B 3.1 REACTIVITY CONTROL SYSTEMS

B 3.1.5 Control Rod Scram Accumulators

BASES

BACKGROUND

The control rod scram accumulators are part of the Control Rod Drive (CRD) System and are provided to ensure that the control rods scram under varying reactor conditions. The control rod scram accumulators store sufficient energy to fully insert a control rod at any reactor vessel pressure. The accumulator is a hydraulic cylinder with a free floating piston. The piston separates the water used to scram the control rods from the nitrogen, which provides the required energy. The scram accumulators are necessary to scram the control rods within the required insertion times of LCO 3.1.4, "Control Rod Scram Times."

APPLICABLE
SAFETY ANALYSES

The analytical methods and assumptions used in evaluating the control rod scram function are presented in References 1, 2, 3, and 4. The Design Basis Accident (DBA) and transient analyses assume that all of the control rods scram at a specified insertion rate. OPERABILITY of each individual control rod scram accumulator, along with LCO 3.1.3, "Control Rod OPERABILITY," and LCO 3.1.4, ensures that the scram reactivity assumed in the DBA and transient analyses can be met. The existence of an inoperable accumulator may invalidate prior scram time measurements for the associated control rod.

The scram function of the CRD System, and, therefore, the OPERABILITY of the accumulators, protects the MCPR Safety Limit (see Bases for SL 2.1.1, "Reactor Core SLs," and LCO 3.2.2, "MINIMUM CRITICAL POWER RATIO (MCPR)") and the 1% cladding plastic strain fuel design limit (see Bases for LCO 3.2.1, "AVERAGE PLANAR LINEAR HEAT GENERATION RATE (APLHGR)," and LCO 3.2.3, "LINEAR HEAT GENERATION RATE (LHGR)"), which ensure that no fuel damage will occur if these limits are not exceeded (see Bases for LCO 3.1.4). Also, the scram function at low reactor vessel pressure (i.e., startup conditions) provides protection against violating fuel design limits during reactivity insertion accidents (see Bases for LCO 3.1.6, "Rod Pattern Control").

(continued)

BASES

APPLICABLE SAFETY ANALYSES (continued) Control rod scram accumulators satisfy Criterion 3 of 10 CFR 50.36(c)(2)(ii).

LCO The OPERABILITY of the control rod scram accumulators is required to ensure that adequate scram insertion capability exists when needed over the entire range of reactor pressures. The OPERABILITY of the scram accumulators is based on maintaining adequate accumulator pressure.

APPLICABILITY In MODES 1 and 2, the scram function is required for mitigation of DBAs and transients and, therefore, the scram accumulators must be OPERABLE to support the scram function. In MODES 3 and 4, control rods are not able to be withdrawn since the reactor mode switch is in shutdown and a control rod block is applied. This provides adequate requirements for control rod scram accumulator OPERABILITY under these conditions. Requirements for scram accumulators in MODE 5 are contained in LCO 3.9.5, "Control Rod OPERABILITY - Refueling."

ACTIONS The ACTIONS Table is modified by a Note indicating that a separate Condition entry is allowed for each control rod scram accumulator. This is acceptable since the Required Actions for each Condition provide appropriate compensatory action for each inoperable accumulator. Complying with the Required Actions may allow for continued operation and subsequent inoperable accumulators governed by subsequent Condition entry and application of associated Required Actions.

A.1 and A.2

With one control rod scram accumulator inoperable and the reactor steam dome pressure ≥ 900 psig, the control rod may be declared "slow," since the control rod will still scram at the reactor operating pressure but may not satisfy the required scram times in Table 3.1.4-1. Required Action A.1 is modified by a Note, which clarifies that declaring the control rod "slow" is only applicable if the associated

(continued)

BASES

ACTIONS

A.1 and A.2 (continued)

control rod scram time was within the limits of Table 3.1.4-1 during the last scram time Surveillance. Otherwise, the control rod may already be considered "slow" and the further degradation of scram performance with an inoperable accumulator could result in excessive scram times. In this event, the associated control rod is declared inoperable (Required Action A.2) and LCO 3.1.3 entered. This would result in requiring the affected control rod to be fully inserted and disarmed, thereby satisfying its intended function in accordance with ACTIONS of LCO 3.1.3.

The allowed Completion Time of 8 hours is considered reasonable, based on the large number of control rods available to provide the scram function and the ability of the affected control rod to scram only with reactor pressure at high reactor pressures.

B.1, B.2.1, and B.2.2

With two or more control rod scram accumulators inoperable and reactor steam dome pressure \geq 900 psig, adequate pressure must be supplied to the charging water header. With inadequate charging water pressure, all of the accumulators could become inoperable, resulting in a potentially severe degradation of the scram performance. Therefore, within 20 minutes from discovery of charging water header pressure $<$ 940 psig concurrent with Condition B, adequate charging water header pressure must be restored. The allowed Completion Time of 20 minutes is considered a reasonable time to place a CRD pump into service to restore the charging header pressure, if required. This Completion Time also recognizes the ability of the reactor pressure alone to fully insert all control rods.

The control rod may be declared "slow," since the control rod will still scram using only reactor pressure, but may not satisfy the times in Table 3.1.4-1. Required Action B.2.1 is modified by a Note indicating that declaring the control rod "slow" is only applicable if the associated

(continued)

BASES

ACTIONS B.1, B.2.1, and B.2.2 (continued)

control rod scram time was within the limits of Table 3.1.4-1 during the last scram time Surveillance. Otherwise, the control rod may already be considered "slow" and the further degradation of scram performance with an inoperable accumulator could result in excessive scram times. In this event, the associated control rod is declared inoperable (Required Action B.2.2) and LCO 3.1.3 entered. This would result in requiring the affected control rod to be fully inserted and disarmed, thereby satisfying its intended function in accordance with ACTIONS of LCO 3.1.3.

The allowed Completion Time of 1 hour is considered reasonable, based on the ability of only the reactor pressure to scram the control rods and the low probability of a DBA or transient occurring while the affected accumulators are inoperable.

C.1 and C.2

With one or more control rod scram accumulators inoperable and the reactor steam dome pressure < 900 psig, the pressure supplied to the charging water header must be adequate to ensure that accumulators remain charged. With the reactor steam dome pressure < 900 psig, the function of the accumulators in providing the scram force becomes much more important since the scram function could become severely degraded during a depressurization event or at low reactor pressures. Therefore, immediately upon discovery of charging water header pressure < 940 psig, concurrent with Condition C, all control rods associated with inoperable accumulators must be verified to be fully inserted. Withdrawn control rods with inoperable scram accumulators may fail to scram under these low pressure conditions. The associated control rods must also be declared inoperable within 1 hour. The allowed Completion Time of 1 hour is reasonable for Required Action C.2, considering the low probability of a DBA or transient occurring during the time the accumulator is inoperable.

(continued)

BASES

ACTIONS
(continued)

D.1

The reactor mode switch must be immediately placed in the shutdown position if either Required Action and associated Completion Time associated with loss of the CRD pump (Required Actions B.1 and C.1) cannot be met. This ensures that all insertable control rods are inserted and that the reactor is in a condition that does not require the active function (i.e., scram) of the control rods. This Required Action is modified by a Note stating that the Required Action is not applicable if all control rods associated with the inoperable scram accumulators are fully inserted, since the function of the control rods has been performed.

SURVEILLANCE
REQUIREMENTS

SR 3.1.5.1

SR 3.1.5.1 requires that the accumulator pressure be checked every 7 days to ensure adequate accumulator pressure exists to provide sufficient scram force. The primary indicator of accumulator OPERABILITY is the accumulator pressure. A minimum accumulator pressure is specified, below which the capability of the accumulator to perform its intended function becomes degraded and the accumulator is considered inoperable. The minimum accumulator pressure of 940 psig is well below the expected pressure of 980 psig to 1200 psig. Declaring the accumulator inoperable when the minimum pressure is not maintained ensures that significant degradation in scram times does not occur. The 7 day Frequency has been shown to be acceptable through operating experience and takes into account indications available in the control room.

REFERENCES

1. UFSAR, Section 4.3.2.5.3.
 2. UFSAR, Section 4.6.1.1.2.
 3. UFSAR, Section 5.2.2.2.2.3.
 4. UFSAR, Section 15.4.
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B 3.1 REACTIVITY CONTROL SYSTEMS

B 3.1.6 Rod Pattern Control

BASES

BACKGROUND

Control rod patterns during startup conditions are controlled by the operator and the Rod Worth Minimizer (RWM) (LCO 3.3.2.1, "Control Rod Block Instrumentation"), so that only specified control rod sequences and relative positions are allowed over the operating range of all control rods inserted to 10% RTP. The sequences effectively limit the potential amount of reactivity addition that could occur in the event of a control rod drop accident (CRDA).

This Specification assures that the control rod patterns are consistent with the assumptions of the CRDA analyses of References 1, 2, and 3.

APPLICABLE
SAFETY ANALYSES

The analytical methods and assumptions used in evaluating the CRDA are summarized in References 1, 2, 3, 4, and 5. CRDA analyses assume that the reactor operator follows prescribed withdrawal sequences. These sequences define the potential initial conditions for the CRDA analysis. The RWM (LCO 3.3.2.1) provides backup to operator control of the withdrawal sequences to ensure that the initial conditions of the CRDA analysis are not violated.

Prevention or mitigation of positive reactivity insertion events is necessary to limit the energy deposition in the fuel, thereby preventing significant fuel damage, which could result in undue release of radioactivity. Since the failure consequences for UO_2 have been shown to be insignificant below fuel energy depositions of 300 cal/gm (Ref. 6), the fuel design limit of 280 cal/gm provides a margin of safety from significant core damage, which would result in release of radioactivity (Ref. 7). Generic evaluations (Refs. 8 and 9) of a design basis CRDA (i.e., a CRDA resulting in a peak fuel energy deposition of 280 cal/gm) have shown that if the peak fuel enthalpy remains below 280 cal/gm, then the maximum reactor pressure will be less than the required ASME Code limits (Ref. 10) and the calculated offsite doses will be well within the

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BASES

APPLICABLE
SAFETY ANALYSES
(continued)

required limits (Ref. 11). Cycle-specific CRDA analyses are performed that assume eight inoperable control rods with at least two cell separation and confirm the fuel energy deposition is less than 280 cal/gm.

Control rod patterns analyzed in the cycle specific analyses follow predetermined sequencing rules (analyzed rod position sequence). The analyzed rod position sequence is applicable from the condition of all control rods fully inserted to 10% RTP (Ref. 5). The control rods are required to be moved in groups, with all control rods assigned to a specific group required to be within specified banked positions (e.g., between notches 08 and 12). The banked positions are defined to minimize the maximum incremental control rod worths without being overly restrictive during normal plant operation. Cycle specific analyses ensure that the 280 cal/gm fuel design limit will not be violated during a CRDA under worst case scenarios. The cycle specific analyses (Refs. 1, 2, 3, 4, and 5) also evaluate the effect of fully inserted, inoperable control rods not in compliance with the sequence, to allow a limited number (i.e., eight) and distribution of fully inserted, inoperable control rods. Specific analyses may also be performed for atypical operating conditions (e.g., fuel leaker suppression).

Rod pattern control satisfies the requirements of Criterion 3 of 10 CFR 50.36(c)(2)(ii).

LCO

Compliance with the prescribed control rod sequences minimizes the potential consequences of a CRDA by limiting the initial conditions to those consistent with the analyzed rod position sequence. This LCO only applies to OPERABLE control rods. For inoperable control rods required to be inserted, separate requirements are specified in LCO 3.1.3, "Control Rod OPERABILITY," consistent with the allowances for inoperable control rods in the analyzed rod position sequence.

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BASES (continued)

APPLICABILITY In MODES 1 and 2, when THERMAL POWER is $\leq 10\%$ RTP, the CRDA is a Design Basis Accident (DBA) and, therefore, compliance with the assumptions of the safety analysis is required. When THERMAL POWER is $> 10\%$ RTP, there is no credible control rod configuration that results in a control rod worth that could exceed the 280 cal/gm fuel design limit during a CRDA (Ref. 4 and 5). In MODES 3 and 4, the reactor is shutdown and the control rods are not able to be withdrawn since the reactor mode switch is in shutdown and a control rod block is applied, therefore a CRDA is not postulated to occur. In MODE 5, since the reactor is shut down and only a single control rod can be withdrawn from a core cell containing fuel assemblies, adequate SDM ensures that the consequences of a CRDA are acceptable, since the reactor will remain subcritical with a single control rod withdrawn.

ACTIONS

A.1 and A.2

With one or more OPERABLE control rods not in compliance with the prescribed control rod sequence, action may be taken to either correct the control rod pattern or declare the associated control rods inoperable within 8 hours. Noncompliance with the prescribed sequence may be the result of "double notching," drifting from a control rod drive cooling water transient, leaking scram valves, or a power reduction to $\leq 10\%$ RTP before establishing the correct control rod pattern. The number of OPERABLE control rods not in compliance with the prescribed sequence is limited to eight to prevent the operator from attempting to correct a control rod pattern that significantly deviates from the prescribed sequence.

Required Action A.1 is modified by a Note, which allows the RWM to be bypassed to allow the affected control rods to be returned to their correct position. LCO 3.3.2.1 requires verification of control rod movement by a second licensed operator (Reactor Operator or Senior Reactor Operator) or by a task qualified member of the technical staff (e.g., a shift technical advisor or reactor engineer). This helps to ensure that the control rods will be moved to the correct position. A control rod not in compliance with the prescribed sequence is not considered inoperable except as

(continued)

BASES

ACTIONS

A.1 and A.2 (continued)

required by Required Action A.2. The allowed Completion Time of 8 hours is reasonable, considering the restrictions on the number of allowed out of sequence control rods and the low probability of a CRDA occurring during the time the control rods are out of sequence.

B.1 and B.2

If nine or more OPERABLE control rods are out of sequence, the control rod pattern significantly deviates from the prescribed sequence. Control rod withdrawal should be suspended immediately to prevent the potential for further deviation from the prescribed sequence. Control rod insertion to correct control rods withdrawn beyond their allowed position is allowed since, in general, insertion of control rods has less impact on control rod worth than withdrawals have. Required Action B.1 is modified by a Note that allows the RWM to be bypassed to allow the affected control rods to be returned to their correct position. LCO 3.3.2.1 requires verification of control rod movement by a second licensed operator (Reactor Operator or Senior Reactor Operator) or by a task qualified member of the technical staff (e.g., a shift technical advisor or reactor engineer).

With nine or more OPERABLE control rods not in compliance with analyzed rod position sequence, the reactor mode switch must be placed in the shutdown position within 1 hour. With the reactor mode switch in shutdown, the reactor is shut down, and therefore does not meet the applicability requirements of this LCO. The allowed Completion Time of 1 hour is reasonable to allow insertion of control rods to restore compliance, and is appropriate relative to the low probability of a CRDA occurring with the control rods out of sequence.

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BASES (continued)

SURVEILLANCE
REQUIREMENTS

SR 3.1.6.1

The control rod pattern is verified to be in compliance with the analyzed rod position sequence at a 24 hour Frequency, ensuring the assumptions of the CRDA analyses are met. The 24 hour Frequency of this Surveillance was developed considering that the primary check of the control rod pattern compliance with the analyzed rod position sequence is performed by the RWM (LCO 3.3.2.1). The RWM provides control rod blocks to enforce the required control rod sequence and is required to be OPERABLE when operating at $\leq 10\%$ RTP.

REFERENCES

1. UFSAR, Section 15.4.10.
2. XN-NF-80-19(P)(A), Volume 1, Supplement 2, Section 7.1, Exxon Nuclear Methodology for Boiling Water Reactor-Neutronics Methods for Design and Analysis, (as specified in Technical Specification 5.6.5).
3. NEDE-24011-P-A, "GE Standard Application for Reactor Fuel," (as specified in Technical Specification 5.6.5).
4. Letter from T.A. Pickens (BWROG) to G.C. Lainas (NRC), "Amendment 17 to General Electric Licensing Topical Report NEDE-24011-P-A," BWROG-8644, August 15, 1986.
5. NFSR-0091, Benchmark of CASMO/MICROBURN BWR Nuclear Design Methods, Commonwealth Edison Topical Report, (as specified in Technical Specification 5.6.5).
6. NUREG-0979, "NRC Safety Evaluation Report for GESSAR II BWR/6 Nuclear Island Design, Docket No. 50-447," Section 4.2.1.3.2, April 1983.
7. NUREG-0800, "Standard Review Plan," Section 15.4.9, "Radiological Consequences of Control Rod Drop Accident (BWR)," Revision 2, July 1981.
8. NEDO-21778-A, "Transient Pressure Rises Affected Fracture Toughness Requirements for Boiling Water Reactors," December 1978.

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BASES

REFERENCES
(continued)

9. NEDO-10527, "Rod Drop Accident Analysis for Large BWRs," (including Supplements 1 and 2), March 1972.
 10. ASME, Boiler and Pressure Vessel Code.
 11. 10 CFR 100.11, "Determination of Exclusion Area Low Population Zone and Population Center Distance."
 12. NEDO-21231, "Banked Position Withdrawal Sequence," January 1977.
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B 3.1 REACTIVITY CONTROL SYSTEMS

B 3.1.7 Standby Liquid Control (SLC) System

BASES

BACKGROUND

The SLC System is designed to provide the capability of bringing the reactor, at any time in a fuel cycle, from full power and minimum control rod inventory (which is at the peak of the xenon transient) to a subcritical condition with the reactor in the most reactive xenon free state without taking credit for control rod movement. The SLC System satisfies the requirements of 10 CFR 50.62 (Ref. 1) on anticipated transient without scram (ATWS).

The SLC System consists of a boron solution storage tank, two positive displacement pumps, two explosive valves, which are provided in parallel for redundancy, and associated piping and valves used to transfer borated water from the storage tank to the reactor pressure vessel (RPV). The borated solution is discharged near the bottom of the core shroud, where it then mixes with the cooling water rising through the core.

APPLICABLE SAFETY ANALYSES

The SLC System is manually initiated from the main control room, as directed by the emergency operating procedures, if the operator determines the reactor cannot be shut down, or kept shut down, with the control rods. The SLC System is used in the event that not enough control rods can be inserted to accomplish shutdown and cooldown in the normal manner. The SLC System injects borated water into the reactor core to compensate for all of the various reactivity effects that could occur during plant operation. To meet this objective, it is necessary to inject a quantity of boron that produces a reactivity change equivalent to a concentration of 660 ppm of enriched boron in the reactor core at 68°F. To ensure this objective is met, a sodium pentaborate solution enriched with boron-10 is used. The shutdown analysis assumes a sodium pentaborate solution with enriched boron is used (Ref. 2). A 45% enriched sodium pentaborate solution is also used to satisfy the requirements of Reference 1. To allow for potential leakage and imperfect mixing in the reactor system, an additional amount of boron equal to 25% of the amount cited above is added (Ref. 2). An additional 250 ppm is provided to

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BASES

APPLICABLE
SAFETY ANALYSES
(continued)

accommodate dilution in the RPV by the residual heat removal shutdown cooling piping. The volume versus concentration limits in Figure 3.1.7-1 are calculated such that the required concentration is achieved. This quantity of borated solution is the amount that is above the pump suction shutoff level in the boron solution storage tank. No credit is taken for the portion of the tank volume that cannot be injected.

The SLC System satisfies Criterion 4 of 10 CFR 50.36(c)(2)(ii).

LCO

The OPERABILITY of the SLC System provides backup capability for reactivity control, independent of normal reactivity control provisions provided by the control rods. The OPERABILITY of the SLC System is based on the conditions of the borated solution in the storage tank and the availability of a flow path to the RPV, including the OPERABILITY of the pumps and valves. Two SLC subsystems are required to be OPERABLE, each containing an OPERABLE pump, an explosive valve and associated piping, valves, and instruments and controls to ensure an OPERABLE flow path.

APPLICABILITY

In MODES 1 and 2, shutdown capability is required. In MODES 3 and 4, control rods are not able to be withdrawn since the reactor mode switch is in shutdown and a control rod block is applied. This provides adequate controls to ensure the reactor remains subcritical. In MODE 5, only a single control rod can be withdrawn from a core cell containing fuel assemblies. Demonstration of adequate SDM (LCO 3.1.1, "SHUTDOWN MARGIN (SDM)") ensures that the reactor will not become critical. Therefore, the SLC System is not required to be OPERABLE during these conditions, when only a single control rod can be withdrawn.

ACTIONS

A.1

If one SLC System subsystem is inoperable, the inoperable subsystem must be restored to OPERABLE status within 7 days. In this condition, the remaining OPERABLE subsystem is adequate to perform the shutdown function. However, the overall reliability is reduced because a single failure in

(continued)

BASES

ACTIONS

A.1 (continued)

the remaining OPERABLE subsystem could result in reduced SLC System shutdown capability and inability to meet the requirements of Reference 1. The 7 day Completion Time is based on the availability of an OPERABLE subsystem capable of performing the unit shutdown function and the low probability of a Design Basis Accident (DBA) or severe transient occurring concurrent with the failure of the Control Rod Drive System to shut down the reactor.

B.1

If both SLC subsystems are inoperable, at least one subsystem must be restored to OPERABLE status within 8 hours. The allowed Completion Time of 8 hours is considered acceptable, given the low probability of a DBA or transient occurring concurrent with the failure of the control rods to shut down the reactor.

C.1

If any Required Action and associated Completion Time is not met, the plant must be brought to a MODE in which the LCO does not apply. To achieve this status, the plant must be brought to MODE 3 within 12 hours. The allowed Completion Time of 12 hours is reasonable, based on operating experience, to reach MODE 3 from full power conditions in an orderly manner and without challenging plant systems.

SURVEILLANCE
REQUIREMENTS

SR 3.1.7.1, SR 3.1.7.2, and SR 3.1.7.3

SR 3.1.7.1 through SR 3.1.7.3 are 24 hour Surveillances, verifying certain characteristics of the SLC System (e.g., the volume and temperature of the borated solution in the storage tank), thereby ensuring the SLC System OPERABILITY without disturbing normal plant operation. These Surveillances ensure the proper borated solution and temperature, including the temperature (using the local indicator) of the pump suction piping up to the storage tank outlet valves, are maintained. Maintaining a minimum specified borated solution temperature is important in

(continued)

BASES

SURVEILLANCE
REQUIREMENTS

SR 3.1.7.1, SR 3.1.7.2, and SR 3.1.7.3 (continued)

ensuring that the boron remains in solution and does not precipitate out in the storage tank or in the pump suction piping. The 24 hour Frequency of these SRs is based on operating experience that has shown there are relatively slow variations in the measured parameters of volume and temperature.

SR 3.1.7.4 and SR 3.1.7.6

SR 3.1.7.4 verifies the continuity of the explosive charges in the injection valves to ensure proper operation will occur if required. Other administrative controls, such as those that limit the shelf life of the explosive charges, must be followed. The 31 day Frequency is based on operating experience that has demonstrated the reliability of the explosive charge continuity.

SR 3.1.7.6 verifies each valve in the system is in its correct position, but does not apply to the squib (i.e., explosive) valves. Verifying the correct alignment for manual, power operated, and automatic valves in the SLC System flow path ensures that the proper flow paths will exist for system operation. A valve is also allowed to be in the nonaccident position, provided it can be aligned to the accident position from the control room, or locally by a dedicated operator at the valve control. This is acceptable since the SLC System is a manually initiated system. This Surveillance does not apply to valves that are locked, sealed, or otherwise secured in position, since they were verified to be in the correct position prior to locking, sealing, or securing. This verification of valve alignment does not apply to valves that cannot be inadvertently misaligned, such as check valves. This SR does not require any testing or valve manipulation; rather, it involves verification that those valves capable of being mispositioned are in the correct positions. The 31 day Frequency is based on engineering judgment and is consistent with the procedural controls governing valve operation that ensure correct valve positions.

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BASES

SURVEILLANCE
REQUIREMENTS
(continued)

SR 3.1.7.5

This Surveillance requires an examination of the sodium pentaborate solution by using chemical analysis to ensure the proper concentration of sodium pentaborate exists in the storage tank. SR 3.1.7.5 must be performed anytime boron or water is added to the storage tank solution to establish that the sodium pentaborate solution concentration is within the specified limits. This Surveillance must be performed anytime the temperature is restored to within the limits of Figure 3.1.7-1, to ensure no significant boron precipitation occurred. The 31 day Frequency of this Surveillance is appropriate because of the relatively slow variation of sodium pentaborate concentration between surveillances.

SR 3.1.7.7

Demonstrating each SLC System pump develops a flow rate ≥ 41.2 gpm at a discharge pressure ≥ 1220 psig ensures that pump performance has not degraded during the fuel cycle. This minimum pump flow rate requirement ensures that, when combined with the sodium pentaborate solution concentration requirements, the rate of negative reactivity insertion from the SLC System will adequately compensate for the positive reactivity effects encountered during power reduction, cooldown of the moderator, and xenon decay. This test confirms one point on the pump design curve, and is indicative of overall performance. Such inservice tests confirm component OPERABILITY and detect incipient failures by indicating abnormal performance. The Frequency of this Surveillance is in accordance with the Inservice Testing Program.

SR 3.1.7.8 and SR 3.1.7.9

These Surveillances ensure that there is a functioning flow path from the boron solution storage tank to the RPV, including the firing of an explosive valve. The replacement charge for the explosive valve shall be from the same manufactured batch as the one fired or from another batch that has been certified by having one of that batch successfully fired. The pump and explosive valve tested

(continued)

BASES

SURVEILLANCE
REQUIREMENTS

SR 3.1.7.8 and SR 3.1.7.9 (continued)

should be alternated such that both complete flow paths are tested every 48 months, at alternating 24 month intervals. The Surveillance may be performed in separate steps to prevent injecting boron into the RPV. An acceptable method for verifying flow from the pump to the RPV is to pump demineralized water from a test tank through one SLC subsystem and into the RPV. The 24 month Frequency is based on the need to perform this Surveillance under the conditions that apply during a plant outage and the potential for an unplanned transient if the Surveillance were performed with the reactor at power. Operating experience has shown these components usually pass the Surveillance test when performed at the 24 month Frequency; therefore, the Frequency was concluded to be acceptable from a reliability standpoint.

Demonstrating that all heat traced piping in the flow path between the boron solution storage tank and the storage tank outlet valves to the injection pumps is unblocked ensures that there is a functioning flow path for injecting the sodium pentaborate solution. An acceptable method for verifying that the suction piping up to the storage tank outlet valves is unblocked is to verify flow from the storage tank to the test tank. Upon completion of this verification, the pump suction piping between the storage tank outlet valve and pump suction must be drained and flushed with demineralized water, since the piping is not heat traced. The 24 month Frequency is acceptable since there is a low probability that the subject piping will be blocked due to precipitation of the boron from solution in the heat traced piping. This is especially true in light of the daily temperature verification of this piping required by SR 3.1.7.3. However, if, in performing SR 3.1.7.3, it is determined that the temperature of this piping has fallen below the specified minimum, SR 3.1.7.9 must be performed once within 24 hours after the piping temperature is restored within the limits of Figure 3.1.7-2.

REFERENCES

1. 10 CFR 50.62.
 2. UFSAR, Section 9.3.5.3.
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B 3.1 REACTIVITY CONTROL SYSTEMS

B 3.1.8 Scram Discharge Volume (SDV) Vent and Drain Valves

BASES

BACKGROUND

The SDV vent and drain valves are normally open and discharge any accumulated water in the SDV to ensure that sufficient volume is available at all times to allow a complete scram. During a scram, the SDV vent and drain valves close to contain reactor water. The SDV consists of header piping that connects to each hydraulic control unit (HCU) and drains into an instrument volume. There are two headers and two instrument volumes, each receiving approximately one half of the control rod drive (CRD) discharges. The two instrument volumes are connected to a common drain line with two valves in series. Each header is connected to a common vent line with two valves in series. The header piping is sized to receive and contain all the water discharged by the CRDs during a scram. The design and functions of the SDV are described in Reference 1.

APPLICABLE
SAFETY ANALYSES

The Design Basis Accident and transient analyses assume all the control rods are capable of scramming. The primary function of the SDV is to limit the amount of reactor coolant discharged during a scram. The acceptance criteria for the SDV vent and drain valves are that they operate automatically to:

- a. Close during scram to limit the amount of reactor coolant discharged so that adequate core cooling is maintained and offsite doses remain within the limits of 10 CFR 100 (Ref. 2); and
- b. Open on scram reset to maintain the SDV vent and drain path open so there is sufficient volume to accept the reactor coolant discharged during a scram.

Isolation of the SDV can also be accomplished by manual closure of the SDV valves. Additionally, the discharge of reactor coolant to the SDV can be terminated by scram reset or closure of the HCU manual isolation valves. For a bounding leakage case, the offsite doses are well within the limits of 10 CFR 100 (Ref. 2) and adequate core cooling is maintained (Ref. 3). The SDV vent and drain valves also

(continued)

BASES

APPLICABLE
SAFETY ANALYSES
(continued)

allow continuous drainage of the SDV during normal plant operation to ensure the SDV has sufficient capacity to contain the reactor coolant discharge during a full core scram. To automatically ensure this capacity, a reactor scram (LCO 3.3.1.1, "Reactor Protection System (RPS) Instrumentation") is initiated if the SDV water level exceeds a specified setpoint. The setpoint is chosen such that all control rods are inserted before the SDV has insufficient volume to accept a full scram.

SDV vent and drain valves satisfy Criterion 3 of 10 CFR 50.36(c)(2)(ii).

LCO

The OPERABILITY of all SDV vent and drain valves ensures that, during a scram, the SDV vent and drain valves will close to contain reactor water discharged to the SDV piping. Since the vent and drain lines are provided with two valves in series, the single failure of one valve in the open position will not impair the isolation function of the system. Additionally, the valves are required to be open to ensure that a path is available for the SDV piping to drain freely at other times.

APPLICABILITY

In MODES 1 and 2, a scram may be required, and therefore, the SDV vent and drain valves must be OPERABLE. In MODES 3 and 4, control rods are not able to be withdrawn since the reactor mode switch is in shutdown and a control rod block is applied. Also, during MODE 5, only a single control rod can be withdrawn from a core cell containing fuel assemblies. Therefore, the SDV vent and drain valves are not required to be OPERABLE in these MODES since the reactor is subcritical and only one rod may be withdrawn and subject to scram.

ACTIONS

The ACTIONS Table is modified by a Note indicating that a separate Condition entry is allowed for each SDV vent and drain line. This is acceptable, since the Required Actions for each Condition provide appropriate compensatory actions for each inoperable SDV line. Complying with the Required Actions may allow for continued operation, and subsequent inoperable SDV lines are governed by subsequent Condition entry and application of associated Required Actions.

(continued)

BASES

ACTIONS
(continued)

The ACTIONS Table is modified by a second Note stating that an isolated line may be unisolated under administrative control to allow draining and venting of the SDV.

When a line is isolated, the potential for an inadvertent scram due to high SDV level is increased. During these periods, the line may be unisolated under administrative control. This allows any accumulated water in the line to be drained, to preclude a reactor scram on SDV high level. This is acceptable, since the administrative controls ensure the valve can be closed quickly, by a dedicated operator at the valve controls, if a scram occurs with the valve open.

A.1

When one SDV vent or drain valve is inoperable in one or more lines, the line must be isolated to contain the reactor coolant during a scram. The 7 day Completion Time is reasonable, given the level of redundancy in the lines and the low probability of a scram occurring during the time the valve(s) are inoperable and the line(s) not isolated. The SDV is still isolable since the redundant valve in the affected line is OPERABLE. During these periods, the single failure criterion may not be preserved, and a higher risk exists to allow reactor water out of the primary system during a scram.

B.1

If both valves in a line are inoperable, the line must be isolated to contain the reactor coolant during a scram. The 8 hour Completion Time to isolate the line is based on the low probability of a scram occurring while the line is not isolated and unlikelihood of significant CRD seal leakage.

C.1

If any Required Action and associated Completion Time is not met, the plant must be brought to a MODE in which the LCO does not apply. To achieve this status, the plant must be

(continued)

BASES

ACTIONS

C.1 (continued)

brought to MODE 3 within 12 hours. The allowed Completion Time of 12 hours is reasonable, based on operating experience, to reach MODE 3 from full power conditions in an orderly manner and without challenging plant systems.

SURVEILLANCE
REQUIREMENTS

SR 3.1.8.1

During normal operation, the SDV vent and drain valves should be in the open position (except when performing SR 3.1.8.2) to allow for drainage of the SDV piping. Verifying that each valve is in the open position ensures that the SDV vent and drain valves will perform their intended function during normal operation. This SR does not require any testing or valve manipulation; rather, it involves verification that the valves are in the correct position. The 31 day Frequency is based on engineering judgment and is consistent with the procedural controls governing valve operation, which ensure correct valve positions. Improper valve position (closed) would not affect the isolation function.

SR 3.1.8.2

During a scram, the SDV vent and drain valves should close to contain the reactor water discharged to the SDV piping. Cycling each valve through its complete range of motion (closed and open) ensures that the valve will function properly during a scram. The 92 day Frequency is based on operating experience and takes into account the level of redundancy in the system design.

SR 3.1.8.3

SR 3.1.8.3 is an integrated test of the SDV vent and drain valves to verify total system performance. After receipt of a simulated or actual scram signal, the closure of the SDV vent and drain valves is verified. The closure time of 30 seconds after a receipt of a scram signal is based on the bounding leakage case evaluated in the accident analysis. Similarly, after receipt of a simulated or actual scram

(continued)

BASES

SURVEILLANCE SR 3.1.8.3 (continued)

reset signal, the opening of the SDV vent and drain valves is verified. The LOGIC SYSTEM FUNCTIONAL TEST in LCO 3.3.1.1 and the scram time testing of control rods in LCO 3.1.3, "Control Rod OPERABILITY," overlap this Surveillance to provide complete testing of the assumed safety function. The 24 month Frequency is based on the need to perform this Surveillance under the conditions that apply during a plant outage and the potential for an unplanned transient if the Surveillance were performed with the reactor at power. Operating experience has shown these components usually pass the Surveillance when performed at the 24 month Frequency; therefore, the Frequency was concluded to be acceptable from a reliability standpoint.

REFERENCES

1. UFSAR, Section 4.6.1.1.2.
 2. 10 CFR 100.
 3. NUREG-0803, "Generic Safety Evaluation Report Regarding Integrity of BWR Scram System Piping," August 1981.
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B 3.2 POWER DISTRIBUTION LIMITS

B 3.2.1 AVERAGE PLANAR LINEAR HEAT GENERATION RATE (APLHGR)

BASES

BACKGROUND The APLHGR is a measure of the average LHGR of all the fuel rods in a fuel assembly at any axial location. Limits on the APLHGR are specified to ensure that criteria specified in 10 CFR 50.46 are met during the postulated design basis loss of coolant accident (LOCA).

APPLICABLE SAFETY ANALYSES The analytical methods and assumptions used in evaluating Design Basis Accidents (DBAs) that determine APLHGR limits are presented in UFSAR, Chapters 4, 6, and 15, and in References 1 and 2.

LOCA analyses are performed to ensure that the APLHGR limits are adequate to meet the peak cladding temperature (PCT) and maximum oxidation limits of 10 CFR 50.46. The analysis is performed using calculational models that are consistent with the requirements of 10 CFR 50, Appendix K. A complete discussion of the analysis code is provided in References 1 and 2. The PCT following a postulated LOCA is a function of the average heat generation rate of all the rods of a fuel assembly at any axial location and is not strongly influenced by the rod to rod power distribution within an assembly. A conservative multiplier is applied to the LHGR and APLHGR assumed in the LOCA analysis to account for the uncertainty associated with the measurement of the APLHGR. APLHGR limits are typically set high enough such that the LHGR limits are more limiting than the APLHGR limits.

For single recirculation loop operation, a conservative multiplier is applied to the exposure dependent APLHGR limits for two loop operation. This additional limitation is due to the conservative analysis assumption of an earlier departure from nucleate boiling with one recirculation loop available, resulting in a more severe cladding heatup during a LOCA.

The APLHGR satisfies Criterion 2 of 10 CFR 50.36(c)(2)(ii).

(continued)

BASES (continued)

LCO The APLHGR limits specified in the COLR are the result of the DBA analyses. For two recirculation loops operating, the limit is dependent on exposure. With only one recirculation loop in operation, in conformance with the requirements of LCO 3.4.1, "Recirculation Loops Operating," the limit is determined by multiplying the exposure dependent APLHGR limit by a conservative multiplier determined by a specific single recirculation loop analysis.

APPLICABILITY The APLHGR limits are derived from LOCA analyses that are assumed to occur at high power levels. Studies and operating experience have shown that as power is reduced, the margin to the required APLHGR limits increases. This trend continues down to the power range of 5% to 15% RTP when entry into MODE 2 occurs. When in MODE 2, the intermediate range monitor (IRM) scram function and the average power range monitor (APRM) scram function provide prompt scram initiation during any significant transient, thereby effectively removing any APLHGR limit compliance concern in MODE 2. Therefore, at THERMAL POWER levels \leq 25% RTP, the reactor operates with substantial margin to the APLHGR limits; thus, this LCO is not required.

ACTIONS A.1

 If any APLHGR exceeds the required limits, an assumption regarding an initial condition of the DBA analyses may not be met. Therefore, prompt action is taken to restore the APLHGR(s) to within the required limits such that the plant will be operating within analyzed conditions and within the design limits of the fuel rods. The 2 hour Completion Time is sufficient to restore the APLHGR(s) to within its limits and is acceptable based on the low probability of a DBA occurring simultaneously with the APLHGR out of specification.

(continued)

BASES

ACTIONS
(continued)

B.1

If the APLHGR cannot be restored to within its required limits within the associated Completion Time, the plant must be brought to a MODE or other specified condition in which the LCO does not apply. To achieve this status, THERMAL POWER must be reduced to < 25% RTP within 4 hours. The allowed Completion Time is reasonable, based on operating experience, to reduce THERMAL POWER to < 25% RTP in an orderly manner and without challenging plant systems.

SURVEILLANCE
REQUIREMENTS

SR 3.2.1.1

APLHGRs are required to be initially calculated within 12 hours after THERMAL POWER is \geq 25% RTP and then every 24 hours thereafter. They are compared to the specified limits in the COLR to ensure that the reactor is operating within the assumptions of the safety analysis. The 24 hour Frequency is based on both engineering judgment and recognition of the slowness of changes in power distribution under normal conditions. The 12 hour allowance after THERMAL POWER \geq 25% RTP is achieved is acceptable given the large inherent margin to operating limits at low power levels.

REFERENCES

1. NEDE-24011-P-A, "General Electric Standard Application for Reactor Fuel," (as specified in Technical Specification 5.6.5).
 2. EMF-94-217(NP), Revision 1, "Boiling Water Reactor Licensing Methodology Summary," November 1995.
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B 3.2 POWER DISTRIBUTION LIMITS

B 3.2.2 MINIMUM CRITICAL POWER RATIO (MCPR)

BASES

BACKGROUND

MCPR is a ratio of the fuel assembly power that would result in the onset of boiling transition to the actual fuel assembly power. The MCPR Safety Limit (SL) is set such that 99.9% of the fuel rods are expected to avoid boiling transition if the limit is not violated (refer to the Bases for SL 2.1.1.2). The operating limit MCPR is established to ensure that no fuel damage results during anticipated operational occurrences (AOOs). Although fuel damage does not necessarily occur if a fuel rod actually experiences boiling transition (Ref. 1), the critical power at which boiling transition is calculated to occur has been adopted as a fuel design criterion.

The onset of transition boiling is a phenomenon that is readily detected during the testing of various fuel bundle designs. Based on these experimental data, correlations have been developed to predict critical bundle power (i.e., the bundle power level at the onset of transition boiling) for a given set of plant parameters (e.g., reactor vessel pressure, flow, and subcooling). Because plant operating conditions and bundle power levels are monitored and determined relatively easily, monitoring the MCPR is a convenient way of ensuring that fuel failures due to inadequate cooling do not occur.

APPLICABLE SAFETY ANALYSES

The analytical methods and assumptions used in evaluating the AOOs to establish the operating limit MCPR are presented in References 2, 3, 4, 5, 6, 7, 8, and 9. To ensure that the MCPR SL is not exceeded during any transient event that occurs with moderate frequency, limiting transients have been analyzed to determine the largest reduction in critical power ratio (CPR). The types of transients evaluated are loss of flow, increase in pressure and power, positive reactivity insertion, and coolant temperature decrease. The limiting transient yields the largest change in CPR (Δ CPR). When the largest Δ CPR is added to the MCPR SL, the required operating limit MCPR is obtained.

(continued)

BASES

APPLICABLE
SAFETY ANALYSES
(continued)

The MCPR operating limits derived from the transient analysis are dependent on the operating core flow and power state ($MCPR_f$ and $MCPR_p$, respectively) to ensure adherence to fuel design limits during the worst transient that occurs with moderate frequency as identified in the UFSAR, Chapter 15 (Ref. 5).

Flow dependent MCPR limits are determined by steady state thermal hydraulic methods with key physics response inputs benchmarked using the three dimensional BWR simulator code (Ref. 8) and the multichannel thermal hydraulic code (Ref. 9) to analyze slow flow runout transients on a cycle-specific basis. For core flows less than rated, the established MCPR operating limit is adjusted to provide protection of the MCPR SL in the event of an uncontrolled recirculation flow increase to the physical limit of the pump. Protection is provided for manual and automatic flow control by applying appropriate flow dependent MCPR operating limits. The MCPR operating limit for a given power/flow state is the greater of the rated conditions MCPR operating limit or the power dependent MCPR operating limit. For automatic flow control, in addition to protecting the MCPR SL during the flow run-up event, protection is provided by the flow dependent MCPR operating limit to prevent exceeding the rated flow MCPR operating limit during an automatic flow increase to rated core flow.

Power dependent MCPR limits ($MCPR_p$) are determined on a cycle-specific basis. These limits are established to protect the core from plant transients other than core flow increases, including pressurization and local control rod withdrawal events.

The MCPR satisfies Criterion 2 of 10 CFR 50.36(c)(2)(ii).

LCO

The MCPR operating limits specified in the COLR are the result of the Design Basis Accident (DBA) and transient analysis. MCPR operating limits which include the effects of analyzed equipment out-of-service are also included in the COLR. The MCPR operating limits are determined by the larger of the $MCPR_f$ and $MCPR_p$ limits.

(continued)

BASES (continued)

APPLICABILITY

The MCPR operating limits are primarily derived from transient analyses that are assumed to occur at high power levels. Below 25% RTP, the reactor is operating at a slow recirculation pump speed and the moderator void ratio is small. Surveillance of thermal limits below 25% RTP is unnecessary due to the inherent margin that ensures that the MCPR SL is not exceeded even if a limiting transient occurs.

Studies of the variation of limiting transient behavior have been performed over the range of power and flow conditions. These studies (Ref. 5) encompass the range of key actual plant parameter values important to typically limiting transients. The results of these studies demonstrate that a margin is expected between performance and the MCPR requirements, and that margins increase as power is reduced to 25% RTP. This trend is expected to continue to the 5% to 15% power range when entry into MODE 2 occurs. When in MODE 2, the intermediate range monitor (IRM) and average power range monitor (APRM) provide rapid scram initiation for any significant power increase transient, which effectively eliminates any MCPR compliance concern. Therefore, at THERMAL POWER levels < 25% RTP, the reactor is operating with substantial margin to the MCPR limits and this LCO is not required.

ACTIONS

A.1

If any MCPR is outside the required limits, an assumption regarding an initial condition of the design basis transient analyses may not be met. Therefore, prompt action should be taken to restore the MCPR(s) to within the required limits such that the plant remains operating within analyzed conditions. The 2 hour Completion Time is normally sufficient to restore the MCPR(s) to within its limits and is acceptable based on the low probability of a transient or DBA occurring simultaneously with the MCPR out of specification.

B.1

If the MCPR cannot be restored to within the required limits within the associated Completion Time, the plant must be brought to a MODE or other specified condition in which the LCO does not apply. To achieve this status, THERMAL POWER

(continued)

BASES

ACTIONS

B.1 (continued)

must be reduced to < 25% RTP within 4 hours. The allowed Completion Time is reasonable, based on operating experience, to reduce THERMAL POWER to < 25% RTP in an orderly manner and without challenging plant systems.

SURVEILLANCE
REQUIREMENTS

SR 3.2.2.1

The MCPR is required to be initially calculated within 12 hours after THERMAL POWER is \geq 25% RTP and then every 24 hours thereafter. It is compared to the specified limits in the COLR to ensure that the reactor is operating within the assumptions of the safety analysis. The 24 hour Frequency is based on both engineering judgment and recognition of the slowness of changes in power distribution during normal operation. The 12 hour allowance after THERMAL POWER reaches \geq 25% RTP is acceptable given the inherent margin to operating limits at low power levels.

SR 3.2.2.2

Because the transient analyses may take credit for conservatism in the control rod scram speed performance, it must be demonstrated that the specific scram speed distribution is consistent with that used in the transient analyses. SR 3.2.2.2 determines the actual scram speed distribution and compares it with the assumed distribution. The MCPR operating limit is then determined based either on the applicable limit associated with scram times of LCO 3.1.4, "Control Rod Scram Times," or the realistic scram times. The scram time dependent MCPR limits are contained in the COLR. This determination must be performed within 72 hours after each set of control rod scram time tests required by SR 3.1.4.1, SR 3.1.4.2, and SR 3.1.4.4 because the effective scram speed distribution may change during the cycle or after maintenance that could affect scram times. The 72 hour Completion Time is acceptable due to the relatively minor changes in the actual control rod scram speed distribution expected during the fuel cycle.

(continued)

BASES (continued)

- REFERENCES
1. NUREG-0562, June 1979.
 2. NEDE-24011-P-A, "General Electric Standard Application for Reactor Fuel" (as specified in Technical Specification 5.6.5).
 3. UFSAR, Chapter 4.
 4. UFSAR, Chapter 6.
 5. UFSAR, Chapter 15.
 6. EMF-94-217(NP) , Revision 1, "Boiling Water Reactor Licensing Methodology Summary," November 1995.
 7. NFSR-0091, Benchmark of CASMO/MICROBURN BWR Nuclear Design Methods, Commonwealth Edison Topical Report, (as specified in Technical Specification 5.6.5).
 8. XN-NF-80-19(P)(A), Volume 1, Exxon Nuclear Methodology for Boiling Water Reactors-Neutronic Methods for Design and Analysis, (as specified in Technical Specification 5.6.5).
 9. XN-NF-80-19(P)(A), Volume 3, Exxon Nuclear Methodology for Boiling Water Reactors-THERMEX Thermal Limits Methodology Summary Description, (as specified in Technical Specification 5.6.5).
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B 3.2 POWER DISTRIBUTION LIMITS

B 3.2.3 LINEAR HEAT GENERATION RATE (LHGR)

BASES

BACKGROUND The LHGR is a measure of the heat generation rate of a fuel rod in a fuel assembly at any axial location. Limits on the LHGR are specified to ensure that fuel design limits are not exceeded anywhere in the core during normal operation, including anticipated operational occurrences (A00s). Exceeding the LHGR limit could potentially result in fuel damage and subsequent release of radioactive materials. Fuel design limits are specified to ensure that fuel system damage, fuel rod failure or inability to cool the fuel does not occur during the normal operations and anticipated operating conditions identified in References 1 and 2.

APPLICABLE SAFETY ANALYSES The analytical methods and assumptions used in evaluating the fuel system design are presented in References 1 and 2. The fuel assembly is designed to ensure (in conjunction with the core nuclear and thermal hydraulic design, plant equipment, instrumentation, and protection system) that fuel damage will not result in the release of radioactive materials in excess of the guidelines of 10 CFR, Parts 20, 50, and 100. A mechanism that could cause fuel damage during normal operations and operational transients and that is considered in fuel evaluations is a rupture of the fuel rod cladding caused by strain from the relative expansion of the UO₂ pellet.

A value of 1% plastic strain of the fuel cladding has been defined as the limit below which fuel damage caused by overstraining of the fuel cladding is not expected to occur (Ref. 3).

Fuel design evaluations have been performed and demonstrate that the 1% fuel cladding plastic strain design limit is not exceeded during continuous operation with LHGRs up to the operating limit specified in the COLR. The analysis also includes allowances for short term transient excursions above the operating limit while still remaining within the A00 limits, plus an allowance for densification power spiking.

The LHGR satisfies Criterion 2 of 10 CFR 50.36(c)(2)(ii).

(continued)

BASES (continued)

LCO The LHGR is a basic assumption in the fuel design analysis. The fuel has been designed to operate at rated core power with sufficient design margin to the LHGR calculated to cause a 1% fuel cladding plastic strain. The operating limit to accomplish this objective is specified in the COLR.

APPLICABILITY The LHGR limits are derived from fuel design analysis that is limiting at high power level conditions. At core thermal power levels < 25% RTP, the reactor is operating with margin to the LHGR limits and, therefore, the Specification is only required when the reactor is operating at \geq 25% RTP.

ACTIONS

A.1

If any LHGR exceeds its required limit, an assumption regarding an initial condition of the fuel design analysis is not met. Therefore, prompt action should be taken to restore the LHGR(s) to within its required limits such that the plant is operating within analyzed conditions. The 2 hour Completion Time is normally sufficient to restore the LHGR(s) to within its limits and is acceptable based on the low probability of a transient or Design Basis Accident occurring simultaneously with the LHGR out of specification.

B.1

If the LHGR cannot be restored to within its required limits within the associated Completion Time, the plant must be brought to a MODE or other specified condition in which the LCO does not apply. To achieve this status, THERMAL POWER must be reduced to < 25% RTP within 4 hours. The allowed Completion Time is reasonable, based on operating experience, to reduce THERMAL POWER to < 25% RTP in an orderly manner and without challenging plant systems.

SURVEILLANCE
REQUIREMENTS

SR 3.2.3.1

The LHGRs are required to be initially calculated within 12 hours after THERMAL POWER is \geq 25% RTP and then every 24 hours thereafter. They are compared with the LHGR limits in the COLR to ensure that the reactor is operating within

(continued)

BASES

SURVEILLANCE
REQUIREMENTS

SR 3.2.3.1 (continued)

the assumptions of the safety analysis. The 24 hour Frequency is based on both engineering judgment and recognition of the slowness of changes in power distribution under normal conditions. The 12 hour allowance after THERMAL POWER \geq 25% RTP is achieved is acceptable given the inherent margin to operating limits at lower power levels.

REFERENCES

1. UFSAR, Chapter 4.
 2. UFSAR, Chapter 15.
 3. NUREG-0800, Section 4.2.II A.2(g), Revision 2, July 1981.
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B 3.3 INSTRUMENTATION

B 3.3.1.1 Reactor Protection System (RPS) Instrumentation

BASES

BACKGROUND

The RPS initiates a reactor scram when one or more monitored parameters exceed their specified limit to preserve the integrity of the fuel cladding and the reactor coolant pressure boundary (RCPB), and minimize the energy that must be absorbed following a loss of coolant accident (LOCA). This can be accomplished either automatically or manually.

The protection and monitoring functions of the RPS have been designed to ensure safe operation of the reactor. This is achieved by specifying limiting safety system settings (LSSS) in terms of parameters directly monitored by the RPS, as well as LCOs on other reactor system parameters, and equipment performance. The LSSS are defined in this Specification as the Allowable Values, which, in conjunction with the LCOs, establish the threshold for protective system action to prevent exceeding acceptable limits, including Safety Limits (SLs), during Design Basis Accidents (DBAs).

The RPS, as described in the UFSAR, Section 7.2 (Ref. 1), includes sensors, relays, bypass circuits, and switches that are necessary to cause initiation of a reactor scram. Functional diversity is provided by monitoring a wide range of dependent and independent parameters. The input parameters to the scram logic are from instrumentation that monitors reactor vessel water level; reactor vessel pressure; neutron flux; main steam line isolation valve position; turbine control valve (TCV) fast closure, trip oil pressure low; turbine stop valve (TSV) position; drywell pressure and scram discharge volume (SDV) water level; as well as reactor mode switch in shutdown position and manual scram signals. There are at least four redundant sensor input signals from each of these parameters. Most channels include instrument switches or electronic equipment (e.g., trip units) that compares measured input signals with pre-established setpoints. When a setpoint is exceeded, the channel outputs an RPS trip signal to the trip logic.

The RPS is comprised of two independent trip systems (A and B), with two logic channels in each trip system (logic channels A1 and A2, B1 and B2), as described in Reference 1.

(continued)

BASES

BACKGROUND
(continued)

The outputs of the logic channels in a trip system are combined in a one-out-of-two logic so either channel can trip the associated trip system. The tripping of both trip systems will produce a reactor scram. This logic arrangement is referred to as one-out-of-two taken twice logic. Each trip system can be reset by use of a reset switch. If a full scram occurs (both trip systems trip), a relay prevents reset of the trip systems for 10 seconds. This 10 second delay on reset is only possible if the conditions that caused the scram have been cleared. This ensures that the scram function will be completed.

Two pilot scram valves are located in the hydraulic control unit (HCU) for each control rod drive (CRD). Each pilot scram valve is solenoid operated, with the solenoids normally energized. The pilot scram valves control the air supply to the scram inlet and outlet valves for the associated CRD. When either pilot scram valve solenoid is energized, air pressure holds the scram valves closed and, therefore, both pilot scram valve solenoids must be de-energized to cause a control rod to scram. The scram valves control the supply and discharge paths for the CRD water during a scram. One of the pilot scram valve solenoids for each CRD is controlled by trip system A, and the other solenoid is controlled by trip system B. Any trip of trip system A in conjunction with any trip in trip system B results in de-energizing both solenoids, air bleeding off, scram valves opening, and control rod scram.

The backup scram valves, which energize on a scram signal to depressurize the scram air header, are also controlled by the RPS. Additionally, the RPS System controls the SDV vent and drain valves such that when both trip systems trip, the SDV vent and drain valves close to isolate the SDV.

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The actions of the RPS are assumed in the safety analyses of References 2, 3, and 4. The RPS initiates a reactor scram when monitored parameter values exceed the Allowable Values specified by the setpoint methodology and listed in Table 3.3.1.1-1 to preserve the integrity of the fuel cladding, the RCPB, and the containment by minimizing the energy that must be absorbed following a LOCA.

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RPS instrumentation satisfies Criterion 3 of 10 CFR 50.36(c)(2)(ii). Functions not specifically credited in the accident analysis are retained for the overall redundancy and diversity of the RPS as required by the NRC approved licensing basis.

The OPERABILITY of the RPS is dependent on the OPERABILITY of the individual instrumentation channel Functions specified in Table 3.3.1.1-1. Each Function must have a required number of OPERABLE channels per RPS trip system, with their setpoints within the specified Allowable Value, where appropriate. The actual setpoint is calibrated consistent with applicable setpoint methodology assumptions. Each channel must also respond within its assumed response time, where applicable.

Allowable Values are specified for each RPS Function specified in the Table. Nominal trip setpoints are specified in the setpoint calculations. The nominal setpoints are selected to ensure that the actual setpoints do not exceed the Allowable Value between successive CHANNEL CALIBRATIONS. Operation with a trip setpoint less conservative than the nominal trip setpoint, but within its Allowable Value, is acceptable. A channel is inoperable if its actual trip setpoint is not within its required Allowable Value.

Trip setpoints are those predetermined values of output at which an action should take place. The setpoints are compared to the actual process parameter (e.g., reactor vessel water level), and when the measured output value of the process parameter exceeds the setpoint, the associated device (e.g., trip unit) changes state. The analytic limits are derived from the limiting values of the process parameters obtained from the safety analysis. The trip setpoints are determined from the analytic limits, corrected for defined process, calibration, and instrumentation errors. The Allowable Values are then determined, based on the trip setpoint values, by accounting for the calibration based errors. These calibration based errors are limited to reference accuracy, instrument drift, errors associated with measurement and test equipment, and calibration tolerance of loop components. The trip setpoints and Allowable Values determined in this manner provide adequate protection

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because instrument uncertainties, process effects, calibration tolerances, instrument drift, and severe environment errors (for channels that must function in harsh environments as defined by 10 CFR 50.49) are accounted for and appropriately applied for the instrumentation.

The OPERABILITY of pilot scram valves and associated solenoids, backup scram valves, and SDV valves, described in the Background section, are not addressed by this LCO.

The individual Functions are required to be OPERABLE in the MODES or other conditions specified in the Table that may require an RPS trip to mitigate the consequences of a design basis accident or transient. To ensure a reliable scram function, a combination of Functions is required in each MODE to provide primary and diverse initiation signals.

The only MODES specified in Table 3.3.1.1-1 are MODES 1 and 2, and MODE 5 with any control rod withdrawn from a core cell containing one or more fuel assemblies. No RPS Function is required in MODES 3 and 4, since all control rods are fully inserted and the Reactor Mode Switch Shutdown Position control rod withdrawal block (LCO 3.3.2.1) does not allow any control rod to be withdrawn. Under these conditions, the RPS function is not required to be OPERABLE. In MODE 5, control rods withdrawn from a core cell containing no fuel assemblies do not affect the reactivity of the core and therefore are not required to have the capability to scram. Provided all other control rods remain inserted, no RPS Function is required. In this condition, the required SDM (LCO 3.1.1) and refuel position one-rod-out interlock (LCO 3.9.2) ensure that no event requiring RPS will occur.

The specific Applicable Safety Analyses, LCO, and Applicability discussions are listed below on a Function by Function basis.

1.a. Intermediate Range Monitor (IRM) Neutron Flux-High

The IRMs monitor neutron flux levels from the upper range of the source range monitors (SRMs) to the lower range of the average power range monitors (APRMs). The IRMs are capable of generating trip signals that can be used to prevent fuel

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1.a. Intermediate Range Monitor (IRM) Neutron Flux-High
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damage resulting from abnormal operating transients in the intermediate power range. In this power range, the most significant source of reactivity change is due to control rod withdrawal. The IRM provides a diverse protection function from the rod worth minimizer (RWM), which monitors and controls the movement of control rods at low power. The RWM prevents the withdrawal of an out of sequence control rod during startup that could result in an unacceptable neutron flux excursion (Ref. 5). The IRM provides a backup to the APRM in mitigation of the neutron flux excursion. However, to demonstrate the capability of the IRM System to mitigate control rod withdrawal events, a generic analysis has been performed (Ref. 6) to evaluate the consequences of control rod withdrawal events during startup that are mitigated only by the IRM. This analysis, which assumes that one IRM channel in each trip system is bypassed, demonstrates that the IRMs provide protection against local control rod withdrawal errors and results in peak fuel enthalpy below the 170 cal/gm fuel failure threshold criterion.

The IRMs are also capable of limiting other reactivity excursions during startup, such as cold water injection events, although no credit is specifically assumed.

The IRM System is divided into two groups of IRM channels, with four IRM channels inputting to each trip system. The analysis of Reference 6 assumes that one channel in each trip system is bypassed. Therefore, six channels with three channels in each trip system are required for IRM OPERABILITY to ensure that no single instrument failure will preclude a scram from this function on a valid signal. This trip is active in each of the 10 ranges of the IRM, which must be selected by the operator to maintain the neutron flux within the monitored level of an IRM range.

The analysis of Reference 6 has adequate conservatism to permit the IRM Allowable Value specified in Table 3.3.1.1-1.

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1.a. Intermediate Range Monitor (IRM) Neutron Flux-High
(continued)

The Intermediate Range Monitor Neutron Flux-High Function must be OPERABLE during MODE 2 when control rods may be withdrawn and the potential for criticality exists. In MODE 5, when a cell with fuel has its control rod withdrawn, the IRMs provide monitoring for and protection against unexpected reactivity excursions. In MODE 1, the APRM System, the RWM and Rod Block Monitor provide protection against control rod withdrawal error events and the IRMs are not required. The IRMs are automatically bypassed when the Reactor Mode Switch is in the run position.

1.b. Intermediate Range Monitor-Inop

This trip signal provides assurance that a minimum number of IRMs are OPERABLE. Anytime an IRM mode switch is moved to any position other than "Operate," the detector voltage drops below a preset level, or a module is not plugged in, an inoperative trip signal will be received by the RPS unless the IRM is bypassed. Since only one IRM in each trip system may be bypassed, only one IRM in each RPS trip system may be inoperable without resulting in an RPS trip signal.

This Function was not specifically credited in the accident analysis, but it is retained for the overall redundancy and diversity of the RPS as required by the NRC approved licensing basis.

Six channels of Intermediate Range Monitor-Inop with three channels in each trip system are required to be OPERABLE to ensure that no single instrument failure will preclude a scram from this Function on a valid signal.

There is no Allowable Value for this Function.

This Function is required to be OPERABLE when the Intermediate Range Monitor Neutron Flux-High Function is required.

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2.a. Average Power Range Monitor Neutron Flux-High,
Setdown

The APRM channels receive input signals from the local power range monitors (LPRM) within the reactor core, which provide an indication of the power distribution and local power changes. The APRM channels average these LPRM signals to provide a continuous indication of average reactor power from a few percent to greater than RTP. For operation at low power (i.e., MODE 2), the Average Power Range Monitor Neutron Flux-High, Setdown Function is capable of generating a trip signal that prevents fuel damage resulting from abnormal operating transients in this power range. For most operation at low power levels, the Average Power Range Monitor Neutron Flux-High, Setdown Function will provide a secondary scram to the Intermediate Range Monitor Neutron Flux-High Function because of the relative setpoints. With the IRMs at Range 9 or 10, it is possible that the Average Power Range Monitor Neutron Flux-High, Setdown Function will provide the primary trip signal for a corewide increase in power. The initial core, fuel cycle independent analysis provided in Reference 5 indicates that a primary trip signal from the Average Power Range Monitor Neutron Flux-High, Setdown Function would provide acceptable results.

The safety analyses (Ref. 5) take credit for the Average Power Range Monitor Neutron Flux-High, Setdown Function. This Function ensures that, before the reactor mode switch is placed in the run position, reactor power does not exceed 25% RTP (SL 2.1.1.1) when operating at low reactor pressure and low core flow. Therefore, it prevents fuel damage during significant reactivity increases with THERMAL POWER < 25% RTP.

The APRM System is divided into two groups of channels with three APRM channel inputs to each trip system. The system is designed to allow one channel in each trip system to be bypassed. Any one APRM channel in a trip system can cause the associated trip system to trip. Four channels of Average Power Range Monitor Neutron Flux-High, Setdown, with two channels in each trip system are required to be OPERABLE to ensure that no single failure will preclude a scram from this Function on a valid signal. In addition, to

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2.a. Average Power Range Monitor Neutron Flux-High,
Setdown (continued)

provide adequate coverage of the entire core, at least 14 LPRM inputs are required for each APRM channel, with at least two LPRM inputs from each of the four axial levels at which the LPRMs are located.

The Allowable Value is based on preventing significant increases in power when THERMAL POWER is < 25% RTP.

The Average Power Range Monitor Neutron Flux-High, Setdown Function must be OPERABLE during MODE 2 when control rods may be withdrawn and the potential for fuel damage from abnormal operating transients exists. In MODE 1, the Average Power Range Monitor Neutron Flux-High Function provides protection against reactivity transients and the RWM and Rod Block Monitor protect against control rod withdrawal error events.

2.b. Average Power Range Monitor Flow Biased Simulated
Thermal Power-Upscale

The Average Power Range Monitor Flow Biased Simulated Thermal Power-Upscale Function monitors neutron flux to approximate the THERMAL POWER being transferred to the reactor coolant. The APRM neutron flux is electronically filtered with a time constant representative of the fuel heat transfer dynamics to generate a signal proportional to the THERMAL POWER in the reactor. The trip level is varied as a function of recirculation drive flow (i.e., at lower core flows the setpoint is reduced proportional to the reduction in power experienced as core flow is reduced) but is clamped at an upper limit that is always lower than the Average Power Range Monitor Fixed Neutron Flux-High Function Allowable Value. The Average Power Range Monitor Flow Biased Simulated Thermal Power-Upscale Function provides protection against transients where THERMAL POWER increases slowly (such as the loss of feedwater heating event) and protects the fuel cladding integrity by ensuring that the MCPR SL is not exceeded. During these events, the THERMAL POWER increase does not significantly lag the neutron flux response and, because of a lower trip setpoint,

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2.b. Average Power Range Monitor Flow Biased Simulated
Thermal Power—Upscale (continued)

will initiate a scram before the high neutron flux scram. For rapid neutron flux increase events, the THERMAL POWER lags the neutron flux and the Average Power Range Monitor Fixed Neutron Flux—High Function will provide a scram signal before the Average Power Range Monitor Flow Biased Simulated Thermal Power—Upscale Function setpoint is exceeded.

The APRM System is divided into two groups of channels with three APRM inputs to each trip system. The system is designed to allow one channel in each trip system to be bypassed. Any one Average Power Range Monitor channel in a trip system can cause the associated trip system to trip. Four channels of Average Power Range Monitor Flow Biased Simulated Thermal Power—Upscale, with two channels in each trip system arranged in one-out-of-two logic, are required to be OPERABLE to ensure that no single instrument failure will preclude a scram from this Function on a valid signal. In addition, to provide adequate coverage of the entire core, at least 14 LPRM inputs are required for each APRM channel, with at least two LPRM inputs from each of the four axial levels at which the LPRMs are located. Each APRM channel receives two independent, redundant flow signals representative of total recirculation drive flow. The total drive flow signals are generated by four flow units, two of which supply signals to the trip system A APRMs, while the other two supply signals to the trip system B APRMs. Each flow unit signal is provided by summing the flow signals from the two recirculation loops. These redundant flow signals are sensed from four pairs of elbow taps, two on each recirculation loop. No single active component failure can cause more than one of these two redundant signals to read incorrectly. To obtain the most conservative reference signals, the total flow signals from the two flow units (associated with a trip system as described above) are routed to a low auction circuit associated with each APRM. Each APRM's auction circuit selects the lower of the two flow unit signals for use as the scram trip reference for that particular APRM. Each required Average Power Range Monitor Flow Biased Simulated

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2.b. Average Power Range Monitor Flow Biased Simulated Thermal Power-Upscale (continued)

Thermal Power-Upscale channel only requires an input from one OPERABLE flow unit, since the individual APRM channel will perform the intended function with only one OPERABLE flow unit input. However, in order to maintain single failure criteria for the Function, at least one required Average Power Range Monitor Flow Biased Simulated Thermal Power-Upscale channel in each trip system must be capable of maintaining an OPERABLE flow unit signal in the event of a failure of an auction circuit, or a flow unit, in the associated trip system (e.g., if a flow unit is inoperable, one of the two required Average Power Range Monitor Flow Biased Simulated Thermal Power-Upscale channels in the associated trip system must be considered inoperable).

Although the Average Power Range Monitor Flow Biased Simulated Thermal Power-Upscale Function is not specifically credited in the safety analysis, the associated Allowable Value provides additional margin from transient induced fuel damage beyond that provided by the Average Power Range Monitor Fixed Neutron Flux-High Function. "W," in the Allowable Value column of Table 3.3.1.1-1, is the percentage of recirculation loop flow which provides a rated core flow of 108.5 million lbs/hr. The THERMAL POWER time constant of ≤ 7 seconds is based on the fuel heat transfer dynamics and provides a signal that is proportional to the THERMAL POWER.

The Average Power Range Monitor Flow Biased Simulated Thermal Power-Upscale Function is required to be OPERABLE in MODE 1 when there is the possibility of generating excessive THERMAL POWER and potentially exceeding the SL applicable to high pressure and core flow conditions (MCPR SL). During MODES 2 and 5, other IRM and APRM Functions provide protection for fuel cladding integrity.

2.c. Average Power Range Monitor Fixed Neutron Flux-High

The APRM channels provide the primary indication of neutron flux within the core and respond almost instantaneously to neutron flux increases. The Average Power Range Monitor Fixed Neutron Flux-High Function is capable of generating a

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2.c. Average Power Range Monitor Fixed Neutron Flux-High
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trip signal to prevent fuel damage or excessive Reactor Coolant System (RCS) pressure. For the overpressurization protection analysis of Reference 2, the Average Power Range Monitor Fixed Neutron Flux-High Function is assumed to terminate the main steam isolation valve (MSIV) closure event and, along with the safety/relief valves (S/RVs), limits the peak reactor pressure vessel (RPV) pressure to less than the ASME Code limits. The control rod drop accident (CRDA) analysis (Ref. 8) takes credit for the Average Power Range Monitor Fixed Neutron Flux-High Function to terminate the CRDA. The recirculation flow control failure event also credits this function (Ref. 4).

The APRM System is divided into two groups of channels with three APRM channels inputting to each trip system. The system is designed to allow one channel in each trip system to be bypassed. Any one APRM channel in a trip system can cause the associated trip system to trip. Four channels of Average Power Range Monitor Fixed Neutron Flux-High with two channels in each trip system arranged in a one-out-of-two logic are required to be OPERABLE to ensure that no single instrument failure will preclude a scram from this Function on a valid signal. In addition, to provide adequate coverage of the entire core, at least 14 LPRM inputs are required for each APRM channel, with at least two LPRM inputs from each of the four axial levels at which the LPRMs are located.

The Allowable Value is based on the Analytical Limit assumed in the CRDA analyses.

The Average Power Range Monitor Fixed Neutron Flux-High Function is required to be OPERABLE in MODE 1 where the potential consequences of the analyzed transients could result in the SLs (e.g., MCPR and RCS pressure) being exceeded. Although the Average Power Range Monitor Fixed Neutron Flux-High Function is assumed in the CRDA analysis (Ref. 8) that is applicable in MODE 2, the Average Power Range Monitor Neutron Flux-High, Setdown Function

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2.c. Average Power Range Monitor Fixed Neutron Flux-High
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conservatively bounds the assumed trip and, together with the assumed IRM trips, provides adequate protection. Therefore, the Average Power Monitor Fixed Neutron Flux-High Function is not required in MODE 2.

2.d. Average Power Range Monitor-Inop

This signal provides assurance that a minimum number of APRMs are OPERABLE. Anytime an APRM mode switch is moved to any position other than Operate, an APRM module is unplugged, or the APRM has too few LPRM inputs (< 14), an inoperative trip signal will be received by the RPS, unless the APRM is bypassed. Since only one APRM in each trip system may be bypassed, only one APRM in each trip system may be inoperable without resulting in an RPS trip signal. This Function was not specifically credited in the accident analysis, but it is retained for the overall redundancy and diversity of the RPS as required by the NRC approved licensing basis.

Four channels of Average Power Range Monitor-Inop with two channels in each trip system are required to be OPERABLE to ensure that no single failure will preclude a scram from this Function on a valid signal.

There is no Allowable Value for this Function.

This Function is required to be OPERABLE in the MODES where the other APRM Functions are required.

3. Reactor Vessel Steam Dome Pressure-High

An increase in the RPV pressure during reactor operation compresses the steam voids and results in a positive reactivity insertion. This causes the neutron flux and THERMAL POWER transferred to the reactor coolant to increase, which could challenge the integrity of the fuel cladding and the RCPB. No specific safety analysis takes direct credit for this Function. However, the Reactor

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3. Reactor Vessel Steam Dome Pressure-High (continued)

Vessel Steam Dome Pressure-High Function initiates a scram for transients that result in a pressure increase, counteracting the pressure increase by rapidly reducing core power. For the overpressurization protection analysis of Reference 2, the reactor scram (the analyses conservatively assume scram on the Average Power Range Monitor Fixed Neutron Flux-High signal, not the Reactor Vessel Steam Dome Pressure-High or the Main Steam Isolation Valve-Closure signals), along with the S/RVs, limits the peak RPV pressure to less than the ASME Section III Code limits.

High reactor pressure signals are initiated from four pressure switches that sense reactor pressure. The Reactor Vessel Steam Dome Pressure-High Allowable Value is chosen to provide a sufficient margin to the ASME Section III Code limits during the event.

Four channels of Reactor Vessel Steam Dome Pressure-High Function, with two channels in each trip system arranged in a one-out-of-two logic, are required to be OPERABLE to ensure that no single instrument failure will preclude a scram from this Function on a valid signal. The Function is required to be OPERABLE in MODES 1 and 2 since the RCS is pressurized and the potential for pressure increase exists.

4. Reactor Vessel Water Level-Low, Level 3

Low RPV water level indicates the capability to cool the fuel may be threatened. Should RPV water level decrease too far, fuel damage could result. Therefore, a reactor scram is initiated at Level 3 to substantially reduce the heat generated in the fuel from fission. The Reactor Vessel Water Level-Low, Level 3 Function is assumed in the analysis of the recirculation line break (Ref. 3). The reactor scram reduces the amount of energy required to be absorbed and, along with the actions of the Emergency Core Cooling Systems (ECCS), ensures that the fuel peak cladding temperature remains below the limits of 10 CFR 50.46.

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4. Reactor Vessel Water Level-Low, Level 3 (continued)

Reactor Vessel Water Level-Low, Level 3 signals are initiated from four differential pressure transmitters that sense the difference between the pressure due to a constant column of water (reference leg) and the pressure due to the actual water level (variable leg) in the vessel.

Four channels of Reactor Vessel Water Level-Low, Level 3 Function, with two channels in each trip system arranged in a one-out-of-two logic, are required to be OPERABLE to ensure that no single instrument failure will preclude a scram from this Function on a valid signal.

The Reactor Vessel Water Level-Low, Level 3 Allowable Value is selected to ensure that, for transients involving loss of all normal feedwater flow, initiation of the low pressure ECCS at RPV Water Level 1 will not be required.

The Function is required in MODES 1 and 2 where considerable energy exists in the RCS resulting in the limiting transients and accidents. ECCS initiations at Reactor Vessel Water Level-Low, Level 2 and Low Low Low, Level 1 provide sufficient protection for level transients in all other MODES.

5. Main Steam Isolation Valve-Closure

MSIV closure results in loss of the main turbine and the condenser as a heat sink for the Nuclear Steam Supply System and indicates a need to shut down the reactor to reduce heat generation. Therefore, a reactor scram is initiated on a Main Steam Isolation Valve-Closure signal before the MSIVs are completely closed in anticipation of the complete loss of the normal heat sink and subsequent overpressurization transient. However, for the overpressurization protection analysis of Reference 2, the Average Power Range Monitor Fixed Neutron Flux-High Function, along with the S/RVs, limits the peak RPV pressure to less than the ASME Code limits. That is, the direct scram on position switches for MSIV closure events is not assumed in the overpressurization analysis. Additionally, MSIV closure is assumed in the transients analyzed in Reference 4 (e.g., low steam line pressure, manual closure of MSIVs, high steam line flow).

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5. Main Steam Isolation Valve-Closure (continued)

The reactor scram reduces the amount of energy required to be absorbed and, along with the actions of the ECCS, ensures that the fuel peak cladding temperature remains below the limits of 10 CFR 50.46.

MSIV closure signals are initiated from position switches located on each of the eight MSIVs. Each MSIV has two position switches; one inputs to RPS trip system A while the other inputs to RPS trip system B. Thus, each RPS trip system receives an input from eight Main Steam Isolation Valve-Closure channels, each consisting of one position switch. The logic for the Main Steam Isolation Valve-Closure Function is arranged such that either the inboard or outboard valve on three or more of the main steam lines (MSLs) must close in order for a scram to occur. In addition, certain combinations of valves closed in two lines will result in a half scram.

The Main Steam Isolation Valve-Closure Allowable Value is specified to ensure that a scram occurs prior to a significant reduction in steam flow, thereby reducing the severity of the subsequent pressure transient.

Sixteen channels of the Main Steam Isolation Valve-Closure Function with eight channels in each trip system are required to be OPERABLE to ensure that no single instrument failure will preclude the scram from this Function on a valid signal. This Function is only required in MODE 1 since, with the MSIVs open and the heat generation rate high, a pressurization transient can occur if the MSIVs close. In MODE 2, the heat generation rate is low enough so that the other diverse RPS functions provide sufficient protection.

6. Drywell Pressure-High

High pressure in the drywell could indicate a break in the RCPB. A reactor scram is initiated to minimize the possibility of fuel damage and to reduce the amount of energy being added to the coolant and the drywell. The

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6. Drywell Pressure-High (continued)

Drywell Pressure-High Function is a secondary scram signal to Reactor Vessel Water Level-Low, Level 3 for LOCA analysis. This Function was not specifically credited with the Appendix K accident analysis to initiate a reactor trip, but is retained for the overall redundancy and diversity of the RPS as required by the NRC approved licensing basis.

The reactor scram reduces the amount of energy required to be absorbed and, along with the actions of the ECCS, ensures that the fuel peak cladding temperature remains below the limits of 10 CFR 50.46.

High drywell pressure signals are initiated from four pressure switches that sense drywell pressure. The Allowable Value was selected to be as low as possible and be indicative of a LOCA inside primary containment.

Four channels of Drywell Pressure-High Function, with two channels in each trip system, are required to be OPERABLE to ensure that no single instrument failure will preclude a scram from this Function on a valid signal. The Function is required in MODES 1 and 2 where considerable energy exists in the RCS, resulting in the limiting transients and accidents.

7.a, b. Scram Discharge Volume Water Level-High

The SDV receives the water displaced by the motion of the CRD pistons during a reactor scram. Should this volume fill to a point where there is insufficient volume to accept the displaced water, control rod insertion would be hindered. Therefore, a reactor scram is initiated when the remaining free volume is still sufficient to accommodate the water from a full core scram. However, even though the two types of Scram Discharge Volume Water Level-High Functions are an input to the RPS logic, no credit is taken for a scram initiated from these Functions for any of the design basis accidents or transients analyzed in the UFSAR. However, they are retained to ensure that the RPS remains OPERABLE.

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7.a, b. Scram Discharge Volume Water Level-High
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SDV water level is measured by two diverse methods. The level in each of the two SDVs is measured by two float type level switches and two transmitters and trip units for a total of eight level signals. The outputs of these devices are arranged so that there is a signal from a level switch and a transmitter and trip unit to each RPS logic channel. The level measurement instrumentation satisfies the recommendations of Reference 9.

The Allowable Value is chosen low enough to ensure that there is sufficient volume in the SDV to accommodate the water from a full scram.

Four channels of each type of Scram Discharge Volume Water Level-High Function, with two channels of each type in each trip system, are required to be OPERABLE to ensure that no single instrument failure will preclude a scram from these Functions on a valid signal. These Functions are required in MODES 1 and 2, and in MODE 5 with any control rod withdrawn from a core cell containing one or more fuel assemblies, since these are the MODES and other specified conditions when control rods are withdrawn. At all other times, this Function may be bypassed.

8. Turbine Stop Valve-Closure

Closure of the TSVs results in the loss of a heat sink that produces reactor pressure, neutron flux, and heat flux transients that must be limited. Therefore, a reactor scram is initiated at the start of TSV closure in anticipation of the transients that would result from the closure of these valves. The Turbine Stop Valve-Closure is the primary scram signal for the turbine trip event analyzed in Reference 4. For this event, the reactor scram reduces the amount of energy required to be absorbed and, along with the actions of the End of Cycle Recirculation Pump Trip (EOC-RPT) System, ensures that the MCPR SL is not exceeded.

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8. Turbine Stop Valve-Closure (continued)

Turbine Stop Valve-Closure signals are initiated by valve stem position switches at each stop valve. Two switches are associated with each stop valve. One of the two switches provides input to RPS trip system A; the other, to RPS trip system B. Thus, each RPS trip system receives an input from four Turbine Stop Valve-Closure channels, each consisting of one valve stem position switch. The logic for the Turbine Stop Valve-Closure Function is such that three or more TSVs must be closed to produce a scram. In addition, certain combinations of two valves closed will result in a half scram.

This Function must be enabled at THERMAL POWER \geq 25% RTP. This is normally accomplished automatically by pressure switches sensing turbine first stage pressure; therefore, opening the turbine bypass valves may affect the OPERABILITY of this Function.

The Turbine Stop Valve-Closure Allowable Value is selected to detect imminent TSV closure thereby reducing the severity of the subsequent pressure transient.

Eight channels of Turbine Stop Valve-Closure Function, with four channels in each trip system, are required to be OPERABLE to ensure that no single instrument failure will preclude a scram from this Function even if one TSV should fail to close. This Function is required, consistent with analysis assumptions, whenever THERMAL POWER is \geq 25% RTP. This Function is not required when THERMAL POWER is $<$ 25% RTP since the Reactor Vessel Steam Dome Pressure-High and the Average Power Range Monitor Fixed Neutron Flux-High Functions are adequate to maintain the necessary safety margins.

9. Turbine Control Valve Fast Closure, Trip Oil Pressure-Low

Fast closure of the TCVs results in the loss of a heat sink that produces reactor pressure, neutron flux, and heat flux transients that must be limited. Therefore, a reactor scram is initiated on TCV fast closure in anticipation of the

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LCO, and
APPLICABILITY

9. Turbine Control Valve Fast Closure, Trip Oil
Pressure-Low (continued)

transients that would result from the closure of these valves. The Turbine Control Valve Fast Closure, Trip Oil Pressure-Low Function is the primary scram signal for the generator load rejection event analyzed in Reference 4. For this event, the reactor scram reduces the amount of energy required to be absorbed and, along with the actions of the EOC-RPT System, ensures that the MCPR SL is not exceeded.

Turbine Control Valve Fast Closure, Trip Oil Pressure-Low signals are initiated by the EHC fluid pressure to each control valve. There is one pressure switch associated with each control valve, the signal from each switch being assigned to a separate RPS logic channel. This Function must be enabled at THERMAL POWER \geq 25% RTP. This is accomplished automatically by pressure switches sensing turbine first stage pressure; therefore, opening the turbine bypass valves may affect the OPERABILITY of this Function.

The Turbine Control Valve Fast Closure, Trip Oil Pressure-Low Allowable Value is selected high enough to detect imminent TCV fast closure.

Four channels of Turbine Control Valve Fast Closure, Trip Oil Pressure-Low Function, with two channels in each trip system arranged in a one-out-of-two logic, are required to be OPERABLE to ensure that no single instrument failure will preclude a scram from this Function on a valid signal. This Function is required, consistent with the analysis assumptions, whenever THERMAL POWER is \geq 25% RTP. This Function is not required when THERMAL POWER is $<$ 25% RTP since the Reactor Vessel Steam Dome Pressure-High and the Average Power Range Monitor Fixed Neutron Flux-High Functions are adequate to maintain the necessary safety margins.

(continued)

BASES

APPLICABLE
SAFETY ANALYSES,
LCO, and
APPLICABILITY
(continued)

10. Reactor Mode Switch-Shutdown Position

The Reactor Mode Switch-Shutdown Position Function provides signals, via the manual scram logic channels, that are redundant to the automatic protective instrumentation channels and provide manual reactor trip capability. This Function was not specifically credited in the accident analysis, but it is retained for the overall redundancy and diversity of the RPS as required by the NRC approved licensing basis.

The reactor mode switch is a single switch with four channels (one from each of the four independent banks of contacts), each of which inputs into one of the RPS logic channels.

There is no Allowable Value for this Function since the channels are mechanically actuated based solely on reactor mode switch position.

Four channels of Reactor Mode Switch-Shutdown Position Function, with two channels in each trip system, are available and required to be OPERABLE. The Reactor Mode Switch-Shutdown Position Function is required to be OPERABLE in MODES 1 and 2, and in MODE 5 with any control rod withdrawn from a core cell containing one or more fuel assemblies, since these are the MODES and other specified conditions when control rods are withdrawn.

11. Manual Scram

The Manual Scram push button channels provide signals, via the manual scram logic channels, to each of the four RPS logic channels that are redundant to the automatic protective instrumentation channels and provide manual reactor trip capability. This Function was not specifically credited in the accident analysis, but it is retained for the overall redundancy and diversity of the RPS as required by the NRC approved licensing basis.

There is one Manual Scram push button channel for each of the four RPS logic channels. In order to cause a scram it is necessary that at least one channel in each trip system be actuated.

(continued)

BASES

APPLICABLE
SAFETY ANALYSES,
LCO, and
APPLICABILITY

11. Manual Scram (continued)

There is no Allowable Value for this Function since the channels are mechanically actuated based solely on the position of the push buttons.

Four channels of Manual Scram with two channels in each trip system arranged in a one-out-of-two logic, are available and required to be OPERABLE in MODES 1 and 2, and in MODE 5 with any control rod withdrawn from a core cell containing one or more fuel assemblies, since these are the MODES and other specified conditions when control rods are withdrawn.

ACTIONS

Note 1 has been provided to modify the ACTIONS related to RPS instrumentation channels. Section 1.3, Completion Times, specifies that once a Condition has been entered, subsequent divisions, subsystems, components, or variables expressed in the Condition, discovered to be inoperable or not within limits, will not result in separate entry into the Condition. Section 1.3 also specifies that Required Actions of the Condition continue to apply for each additional failure, with Completion Times based on initial entry into the Condition. However, the Required Actions for inoperable RPS instrumentation channels provide appropriate compensatory measures for separate, inoperable channels. As such, Note 1 has been provided that allows separate Condition entry for each inoperable RPS instrumentation channel.

Note 2 has been provided to modify the ACTIONS for the RPS instrumentation functions of APRM Flow Biased Simulated Thermal Power-Upscale (Function 2.b) and APRM Fixed Neutron Flux-High (Function 2.c) when they are inoperable due to failure of SR 3.3.1.1.2 and gain adjustments are necessary. Note 2 allows entry into associated Conditions and Required Actions to be delayed for up to 2 hours if the APRM is indicating a lower power value than the calculated power (i.e., the gain adjustment factor (GAF) is high (non-conservative)), and for up to 12 hours if the APRM is indicating a higher power value than the calculated power

(continued)

BASES

ACTIONS
(continued)

(i.e., the GAF is low (conservative)). The GAF for any channel is defined as the power value determined by the heat balance divided by the APRM reading for that channel. Upon completion of the gain adjustment, or expiration of the allowed time, the channel must be returned to OPERABLE status or the applicable Condition entered and the Required Actions taken. This Note is based on the time required to perform gain adjustments on multiple channels and additional time is allowed when the GAF is out of limits but conservative.

A.1 and A.2

Because of the diversity of sensors available to provide trip signals and the redundancy of the RPS design, an allowable out of service time of 12 hours has been shown to be acceptable (Ref. 10) to permit restoration of any inoperable required channel to OPERABLE status. However, this out of service time is only acceptable provided the associated Function's inoperable channel is in one trip system and the Function still maintains RPS trip capability (refer to Required Actions B.1, B.2, and C.1 Bases.) If the inoperable channel cannot be restored to OPERABLE status within the allowable out of service time, the channel or the associated trip system must be placed in the tripped condition per Required Actions A.1 and A.2. Placing the inoperable channel in trip (or the associated trip system in trip) would conservatively compensate for the inoperability, restore capability to accommodate a single failure, and allow operation to continue. Alternately, if it is not desired to place the channel (or trip system) in trip (e.g., as in the case where placing the inoperable channel in trip would result in a scram or recirculation pump trip (RPT)), Condition D must be entered and its Required Action taken.

B.1 and B.2

Condition B exists when, for any one or more Functions, at least one required channel is inoperable in each trip system. In this condition, provided at least one channel per trip system is OPERABLE, the RPS still maintains trip capability for that Function, but cannot accommodate a single failure in either trip system.

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BASES

ACTIONS

B.1 and B.2 (continued)

Required Actions B.1 and B.2 limit the time the RPS scram logic for any Function would not accommodate single failure in both trip systems (e.g., one-out-of-one and one-out-of-one arrangement for a typical four channel Function). The reduced reliability of this logic arrangement was not evaluated in Reference 10 for the 12 hour Completion Time. Within the 6 hour allowance, the associated Function will have all required channels either OPERABLE or in trip (or in any combination) in one trip system.

Completing one of these Required Actions restores RPS to an equivalent reliability level as that evaluated in Reference 10, which justified a 12 hour allowable out of service time as presented in Condition A. The trip system in the more degraded state should be placed in trip or, alternatively, all the inoperable channels in that trip system should be placed in trip (e.g., a trip system with two inoperable channels could be in a more degraded state than a trip system with four inoperable channels, if the two inoperable channels are in the same Function while the four inoperable channels are all in different Functions). The decision as to which trip system is in the more degraded state should be based on prudent judgment and current plant conditions (i.e., what MODE the plant is in). If this action would result in a scram or RPT, it is permissible to place the other trip system or its inoperable channels in trip.

The 6 hour Completion Time is judged acceptable based on the remaining capability to trip, the diversity of the sensors available to provide the trip signals, the low probability of extensive numbers of inoperabilities affecting all diverse Functions, and the low probability of an event requiring the initiation of a scram.

Alternately, if it is not desired to place the inoperable channels (or one trip system) in trip (e.g., as in the case where placing the inoperable channel or associated trip system in trip would result in a scram or RPT), Condition D must be entered and its Required Action taken.

(continued)

BASES

ACTIONS
(continued)

C.1

Required Action C.1 is intended to ensure that appropriate actions are taken if multiple, inoperable, untripped channels within the same trip system for the same Function result in the Function not maintaining RPS trip capability. A Function is considered to be maintaining RPS trip capability when sufficient channels are OPERABLE or in trip (or the associated trip system is in trip), such that both trip systems will generate a trip signal from the given Function on a valid signal. For the typical Function with one-out-of-two taken twice logic and the IRM and APRM Functions, this would require both trip systems to have one channel OPERABLE or in trip (or the associated trip system in trip). For Function 5 (Main Steam Isolation Valve-Closure), this would require both trip systems to have each channel associated with the MSIVs in three MSLs (not necessarily the same MSLs for both trip systems), OPERABLE or in trip (or the associated trip system in trip). For Function 8 (Turbine Stop Valve-Closure), this would require both trip systems to have three channels, each OPERABLE or in trip (or the associated trip system in trip).

The Completion Time is intended to allow the operator time to evaluate and repair any discovered inoperabilities. The 1 hour Completion Time is acceptable because it minimizes risk while allowing time for restoration or tripping of channels.

D.1

Required Action D.1 directs entry into the appropriate Condition referenced in Table 3.3.1.1-1. The applicable Condition specified in the Table is Function and MODE or other specified condition dependent and may change as the Required Action of a previous Condition is completed. Each time an inoperable channel has not met any Required Action of Condition A, B, or C, and the associated Completion Time has expired, Condition D will be entered for that channel and provides for transfer to the appropriate subsequent Condition.

(continued)

BASES

ACTIONS
(continued)

E.1, F.1, and G.1

If the channel(s) is not restored to OPERABLE status or placed in trip (or the associated trip system placed in trip) within the allowed Completion Time, the plant must be placed in a MODE or other specified condition in which the LCO does not apply. The Completion Times are reasonable, based on operating experience, to reach the specified condition from full power conditions in an orderly manner and without challenging plant systems. In addition, the Completion Time of Required Action E.1 is consistent with the Completion Time provided in LCO 3.2.2, "MINIMUM CRITICAL POWER RATIO (MCPR)."

H.1

If the channel(s) is not restored to OPERABLE status or placed in trip (or the associated trip system placed in trip) within the allowed Completion Time, the plant must be placed in a MODE or other specified condition in which the LCO does not apply. This is done by immediately initiating action to fully insert all insertable control rods in core cells containing one or more fuel assemblies. Control rods in core cells containing no fuel assemblies do not affect the reactivity of the core and are, therefore, not required to be inserted. Action must continue until all insertable control rods in core cells containing one or more fuel assemblies are fully inserted.

SURVEILLANCE
REQUIREMENTS

As noted at the beginning of the SRs, the SRs for each RPS instrumentation Function are located in the SRs column of Table 3.3.1.1-1.

The Surveillances are modified by a Note to indicate that, when a channel is placed in an inoperable status solely for performance of required Surveillances, entry into associated Conditions and Required Actions may be delayed for up to 6 hours, provided the associated Function maintains RPS trip capability. Upon completion of the Surveillance, or expiration of the 6 hour allowance, the channel must be returned to OPERABLE status or the applicable Condition

(continued)

BASES

SURVEILLANCE
REQUIREMENTS
(continued)

entered and Required Actions taken. This Note is based on the RPS reliability analysis (Ref. 10) assumption of the average time required to perform channel surveillance. That analysis demonstrated that the 6 hour testing allowance does not significantly reduce the probability that the RPS will trip when necessary.

SR 3.3.1.1.1

Performance of the CHANNEL CHECK once every 12 hours ensures that a gross failure of instrumentation has not occurred. A CHANNEL CHECK is normally a comparison of the parameter indicated on one channel to a similar parameter on other channels. It is based on the assumption that instrument channels monitoring the same parameter should read approximately the same value. Significant deviations between the instrument channels could be an indication of excessive instrument drift on one of the channels or something even more serious. A CHANNEL CHECK will detect gross channel failure; thus, it is key to verifying the instrumentation continues to operate properly between each CHANNEL CALIBRATION.

Agreement criteria are determined by the plant staff based on a combination of the channel instrument uncertainties, including indication and readability. If a channel is outside the criteria, it may be an indication that the instrument has drifted outside its limit.

The Frequency is based upon operating experience that demonstrates channel failure is rare. The CHANNEL CHECK supplements less formal, but more frequent, checks of channels during normal operational use of the displays associated with the channels required by the LCO.

SR 3.3.1.1.2

To ensure that the APRMs are accurately indicating the true core average power, the APRMs are calibrated to the reactor power calculated from a heat balance. The Frequency of once per 7 days is based on minor changes in LPRM sensitivity, which could affect the APRM reading between performances of SR 3.3.1.1.8.

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BASES

SURVEILLANCE
REQUIREMENTS

SR 3.3.1.1.2 (continued)

An allowance is provided that requires the SR to be performed only at $\geq 25\%$ RTP because it is difficult to accurately maintain APRM indication of core THERMAL POWER consistent with a heat balance when $< 25\%$ RTP. At low power levels, a high degree of accuracy is unnecessary because of the inherent margin to thermal limits (MCPR and APLHGR). At $\geq 25\%$ RTP, the Surveillance is required to have been satisfactorily performed within the last 7 days in accordance with SR 3.0.2. A Note is provided which allows an increase in THERMAL POWER above 25% if the 7 day Frequency is not met per SR 3.0.2. In this event, the SR must be performed within 12 hours after reaching or exceeding 25% RTP. Twelve hours is based on operating experience and in consideration of providing a reasonable time in which to complete the SR.

SR 3.3.1.1.3

The Average Power Range Monitor Flow Biased Simulated Thermal Power-Upscale Function uses the recirculation loop drive flows to vary the trip setpoint. This SR ensures that the total loop drive flow signals from the flow unit used to vary the setpoint are appropriately compared to a calibrated flow signal and therefore the APRM Function accurately reflects the required setpoint as a function of flow. Each flow signal from the respective flow unit must be $\leq 100\%$ of the calibrated flow signal. If the flow unit signal is not within the limit, one required APRM that receives an input from the inoperable flow unit must be declared inoperable.

The Frequency of 7 days is based on engineering judgment, operating experience, and the reliability of this instrumentation.

SR 3.3.1.1.4

A CHANNEL FUNCTIONAL TEST is performed on each required channel to ensure that the channel will perform the intended function. A successful test of the required contact(s) of a

(continued)

BASES

SURVEILLANCE
REQUIREMENTS

SR 3.3.1.1.4 (continued)

channel relay may be performed by the verification of the change of state of a single contact of the relay. This clarifies what is an acceptable CHANNEL FUNCTIONAL TEST of a relay. This is acceptable because all of the other required contacts of the relay are verified by other Technical Specifications and non-Technical Specifications tests at least once per refueling interval with applicable extensions.

Any setpoint adjustment shall be consistent with the assumptions of the current plant specific setpoint methodology.

As noted, SR 3.3.1.1.4 is not required to be performed when entering MODE 2 from MODE 1 since testing of the MODE 2 required IRM and APRM Functions cannot be performed in MODE 1 without utilizing jumpers, lifted leads, or movable links. This allows entry into MODE 2 if the 7 day Frequency is not met per SR 3.0.2. In this event, the SR must be performed within 24 hours after entering MODE 2 from MODE 1. Twenty-four hours is based on operating experience and in consideration of providing a reasonable time in which to complete the SR.

A Frequency of 7 days provides an acceptable level of system average unavailability over the Frequency interval and is based on reliability analysis (Ref. 10).

SR 3.3.1.1.5

A CHANNEL FUNCTIONAL TEST is performed on each required channel to ensure that the channel will perform the intended Function. A successful test of the required contact(s) of a channel relay may be performed by the verification of the change of state of a single contact of the relay. This clarifies what is an acceptable CHANNEL FUNCTIONAL TEST of a relay. This is acceptable because all of the other required contacts of the relay are verified by other Technical Specifications and non-Technical Specifications tests at

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BASES

SURVEILLANCE
REQUIREMENTS

SR 3.3.1.1.5 (continued)

Least once per refueling interval with applicable extensions. In accordance with Reference 10, the scram contactors must be tested as part of the Manual Scram Function. A Frequency of 7 days provides an acceptable level of system average availability over the Frequency and is based on the reliability analysis of Reference 10. (The Manual Scram Function's CHANNEL FUNCTIONAL TEST Frequency was credited in the analysis to extend many automatic scram Functions' Frequencies.)

SR 3.3.1.1.6 and SR 3.3.1.1.7

These Surveillances are established to ensure that no gaps in neutron flux indication exist from subcritical to power operation for monitoring core reactivity status.

The overlap between SRMs and IRMs is required to be demonstrated to ensure that reactor power will not be increased into a region without adequate neutron flux indication. This is required prior to fully withdrawing SRMs since indication is being transitioned from the SRMs to the IRMs.

The overlap between IRMs and APRMs is of concern when reducing power into the IRM range. On power increases, the system design will prevent further increases (initiate a rod block) if adequate overlap is not maintained. The IRM/APRM and SRM/IRM overlap are acceptable if a ½ decade overlap exists.

As noted, SR 3.3.1.1.7 is only required to be met during entry into MODE 2 from MODE 1. That is, after the overlap requirement has been met and indication has transitioned to the IRMs, maintaining overlap is not required (APRMs may be reading downscale once in MODE 2).

If overlap for a group of channels is not demonstrated (e.g., IRM/APRM overlap), the reason for the failure of the Surveillance should be determined and the appropriate

(continued)

BASES

SURVEILLANCE
REQUIREMENTS

SR 3.3.1.1.6 and SR 3.3.1.1.7 (continued)

channel(s) declared inoperable. Only those appropriate channel(s) that are required in the current MODE or condition should be declared inoperable.

A Frequency of 7 days is reasonable based on engineering judgment and the reliability of the IRMs and APRMs.

SR 3.3.1.1.8

LPRM gain settings are determined from the local flux profiles measured by the Traversing Incore Probe (TIP) System. This establishes the relative local flux profile for appropriate representative input to the APRM System. The 1000 effective full power hours (EFPH) Frequency is based on operating experience with LPRM sensitivity changes.

SR 3.3.1.1.9 and SR 3.3.1.1.12

A CHANNEL FUNCTIONAL TEST is performed on each required channel to ensure that the channel will perform the intended function. A successful test of the required contact(s) of a channel relay may be performed by the verification of the change of state of a single contact of the relay. This clarifies what is an acceptable CHANNEL FUNCTIONAL TEST of a relay. This is acceptable because all of the other required contacts of the relay are verified by other Technical Specifications and non-Technical Specifications tests at least once per refueling interval with applicable extensions. Any setpoint adjustment shall be consistent with the assumptions of the current plant specific setpoint methodology.

The 92 day Frequency of SR 3.3.1.1.9 is based on the reliability analysis of Reference 10.

The 24 month Frequency of SR 3.3.1.1.12 is based on the need to perform this Surveillance under the conditions that apply during a plant outage and the potential for an unplanned

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SURVEILLANCE
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SR 3.3.1.1.9 and SR 3.3.1.1.12 (continued)

transient if the Surveillance were performed with the reactor at power. Operating experience has shown that these components usually pass the Surveillance when performed at the 24 month Frequency.

SR 3.3.1.1.10, SR 3.3.1.1.11, and SR 3.3.1.1.13

A CHANNEL CALIBRATION is a complete check of the instrument loop, including associated trip unit, and the sensor. This test verifies the channel responds to the measured parameter within the necessary range and accuracy. CHANNEL CALIBRATION leaves the channel adjusted to account for instrument drifts between successive calibrations consistent with the plant specific setpoint methodology.

Note 1 of SR 3.3.1.1.11 and SR 3.3.1.1.13 states that neutron detectors are excluded from CHANNEL CALIBRATION because of the difficulty of simulating a meaningful signal. Changes in neutron detector sensitivity are compensated for by performing the 7 day calorimetric calibration (SR 3.3.1.1.2) and the 1000 EFPH LPRM calibration against the TIPs (SR 3.3.1.1.8). A second Note to SR 3.3.1.1.11 and SR 3.3.1.1.13 is provided that requires the APRM and IRM SRs to be performed within 24 hours of entering MODE 2 from MODE 1. Testing of the MODE 2 APRM and IRM Functions cannot be performed in MODE 1 without utilizing jumpers, lifted leads, or movable links. This Note allows entry into MODE 2 from MODE 1 if the associated Frequency is not met per SR 3.0.2.

Twenty-four hours is based on operating experience and in consideration of providing a reasonable time in which to complete the SR. The Frequencies of SR 3.3.1.1.10 and SR 3.3.1.1.11 are based upon the assumption of a 92 day and 184 day calibration interval, respectively, in the determination of the magnitude of equipment drift in the setpoint analysis. The Frequency of SR 3.3.1.1.11 is based on the assumption of a 24 month calibration interval in the determination of the magnitude of equipment drift in the setpoint analysis.

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(continued)

SR 3.3.1.1.14

The Average Power Range Monitor Flow Biased Simulated Thermal Power—Upscale Function uses an electronic filter circuit to generate a signal proportional to the core THERMAL POWER from the APRM neutron flux signal. This filter circuit is representative of the fuel heat transfer dynamics that produce the relationship between the neutron flux and the core THERMAL POWER. The filter time constant must be verified to ensure that the channel is accurately reflecting the desired parameter.

The Frequency of 24 months is based on engineering judgment and reliability of the components.

SR 3.3.1.1.15

The LOGIC SYSTEM FUNCTIONAL TEST demonstrates the OPERABILITY of the required trip logic for a specific channel. The functional testing of control rods, in LCO 3.1.3, "Control Rod OPERABILITY," and SDV vent and drain valves, in LCO 3.1.8, "Scram Discharge Volume (SDV) Vent and Drain Valves," overlaps this Surveillance to provide complete testing of the assumed safety function.

The 24 month Frequency is based on the need to perform this Surveillance under the conditions that apply during a plant outage and the potential for an unplanned transient if the Surveillance were performed with the reactor at power. Operating experience has shown that these components usually pass the Surveillance when performed at the 24 month Frequency.

SR 3.3.1.1.16

This SR ensures that scrams initiated from the Turbine Stop Valve—Closure and Turbine Control Valve Fast Closure, Trip Oil Pressure—Low Functions will not be inadvertently bypassed when THERMAL POWER is \geq 25% RTP. This involves calibration of the bypass channels. Adequate margins for

(continued)

BASES

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REQUIREMENTS

SR 3.3.1.1.16 (continued)

the instrument setpoint methodology are incorporated into the Allowable Value and the actual setpoint. Because main turbine bypass flow can affect this setpoint nonconservatively (THERMAL POWER is derived from turbine first stage pressure), the main turbine bypass valves must remain closed during in-service calibration at THERMAL POWER $\geq 25\%$ RTP, if performing the calibration using actual turbine first stage pressure, to ensure that the calibration is valid.

If any bypass channel setpoint is nonconservative (i.e., the Functions are bypassed at $\geq 25\%$ RTP, either due to open main turbine bypass valve(s) or other reasons), then the affected Turbine Stop Valve-Closure and Turbine Control Valve Fast Closure, Trip Oil Pressure-Low Functions are considered inoperable. Alternatively, the bypass channel can be placed in the conservative condition (nonbypass). If placed in the nonbypass condition, this SR is met and the channel is considered OPERABLE.

The Frequency of 24 months is based on engineering judgment and reliability of the components.

SR 3.3.1.1.17

This SR ensures that the individual channel response times are less than or equal to the maximum values assumed in the accident analysis. The RPS RESPONSE TIME acceptance criteria are included in Reference 11.

RPS RESPONSE TIME may be verified by actual response time measurements in any series of sequential, overlapping, or total channel measurements. However, the sensors for Functions 3 and 4 are allowed to be excluded from specific RPS RESPONSE TIME measurement if the conditions of Reference 12 are satisfied. If these conditions are satisfied, sensor response time may be allocated based on either assumed design sensor response time or the manufacturer's stated design response time. When the

(continued)

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SURVEILLANCE
REQUIREMENTS

SR 3.3.1.1.17 (continued)

requirements of Reference 12 are not satisfied, sensor response time must be measured. Also, regardless of whether or not the sensor response time is measured, the response time for the remaining portion of the channel, including the trip unit and relay logic, is required to be measured. In addition, the response time of the limit switches for Function 8 may be assumed to be the design limit switch response time and therefore, are excluded from the RPS RESPONSE TIME testing. This is allowed, as documented in Reference 13, since the actual measurement of the limit switch response time is not practicable as this test is done during the refueling outage when the turbine stop valves are fully closed, and thus the limit switch in the RPS circuitry is open. The design limit switch response time is 10 ms.

As noted (Note 1), neutron detectors are excluded from RPS RESPONSE TIME testing. The principles of detector operation virtually ensure an instantaneous response time. Note 3 modifies the starting point of the RPS RESPONSE TIME test for Function 9, since this starting point (start of turbine control valve fast closure) corresponds to safety analysis assumptions.

RPS RESPONSE TIME tests are conducted on a 24 month STAGGERED TEST BASIS. Note 2 requires STAGGERED TEST BASIS Frequency to be determined based on 4 channels per trip system, in lieu of the 8 channels specified in Table 3.3.1.1-1 for the MSIV Closure Function. This Frequency is based on the logic interrelationships of the various channels required to produce an RPS scram signal. Therefore, staggered testing results in response time verification of these devices every 24 months. The 24 month Frequency is consistent with the refueling cycle and is based upon plant operating experience, which shows that random failures of instrumentation components causing serious time degradation, but not channel failure, are infrequent.

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BASES (continued)

REFERENCES

1. UFSAR, Section 7.2.
 2. UFSAR, Section 5.2.2.
 3. UFSAR, Section 6.3.3.
 4. UFSAR, Chapter 15.
 5. UFSAR, Section 15.4.1.
 6. NEDO-23842, "Continuous Control Rod Withdrawal in the Startup Range," April 18, 1978.
 7. UFSAR, Section 7.6.3.3.
 8. UFSAR, Section 15.4.9.
 9. Letter, P. Check (NRC) to G. Lainas (NRC), "BWR Scram Discharge System Safety Evaluation," December 1, 1980.
 10. NEDC-30851-P-A, "Technical Specification Improvement Analyses for BWR Reactor Protection System," March 1988.
 11. Technical Requirements Manual.
 12. NEDO-32291-A, "System Analyses for the Elimination of Selected Response Time Testing Requirements," October 1995.
 13. Letter, W. G. Guldmond (NRC) to C. Reed (ComEd), dated January 28, 1987.
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B 3.3 INSTRUMENTATION

B 3.3.1.2 Source Range Monitor (SRM) Instrumentation

BASES

BACKGROUND

The SRMs provide the operator with information relative to the neutron level at very low flux levels in the core. As such, the SRM indication is used by the operator to monitor the approach to criticality and to determine when criticality is achieved. The SRMs are not fully withdrawn until the count rate is greater than a minimum allowed count rate (a control rod block is set at this condition). After SRM to intermediate range monitor (IRM) overlap is demonstrated (as required by SR 3.3.1.1.6), the SRMs are normally fully withdrawn from the core.

The SRM subsystem of the Neutron Monitoring System (NMS) consists of four channels. Each of the SRM channels can be bypassed, but only one at any given time, by the operation of a bypass switch. Each channel includes one detector that can be physically positioned in the core. Each detector assembly consists of a miniature fission chamber with associated cabling, signal conditioning equipment, and electronics associated with the various SRM functions. The signal conditioning equipment converts the current pulses from the fission chamber to analog DC currents that correspond to the count rate. Each channel also includes indication, alarm, and control rod blocks. However, this LCO specifies OPERABILITY requirements only for the monitoring and indication functions of the SRMs.

During refueling, shutdown, and low power operations, the primary indication of neutron flux levels is provided by the SRMs or special movable detectors connected to the normal SRM circuits. The SRMs provide monitoring of reactivity changes during fuel or control rod movement and give the control room operator early indication of unexpected subcritical multiplication that could be indicative of an approach to criticality.

APPLICABLE SAFETY ANALYSES

Prevention and mitigation of prompt reactivity excursions during refueling and low power operation are provided by LCO 3.9.1, "Refueling Equipment Interlocks"; LCO 3.1.1, "SHUTDOWN MARGIN (SDM)"; LCO 3.3.1.1, "Reactor Protection

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BASES

APPLICABLE
SAFETY ANALYSES
(continued)

System (RPS) Instrumentation," Intermediate Range Monitor (IRM) Neutron Flux High and Average Power Range Monitor (APRM) Neutron Flux-High, Setdown Functions; and LCO 3.3.2.1, "Control Rod Block Instrumentation."

The SRMs have no safety function and are not assumed to function during any UFSAR design basis accident or transient analysis. However, the SRMs provide the only on scale monitoring of neutron flux levels during startup and refueling. Therefore, they are being retained in the Technical Specifications.

LCO

During startup in MODE 2, three of the four SRM channels are required to be OPERABLE to monitor the reactor flux level prior to and during control rod withdrawal, to monitor subcritical multiplication and reactor criticality, and to monitor neutron flux level and reactor period until the flux level is sufficient to maintain the IRM on Range 3 or above. All channels but one are required in order to provide a representation of the overall core response during those periods when reactivity changes are occurring throughout the core.

In MODES 3 and 4, with the reactor shut down, two SRM channels provide redundant monitoring of flux levels in the core.

In MODE 5, during a spiral offload or reload, an SRM outside the fueled region will no longer be required to be OPERABLE, since it is not capable of monitoring neutron flux in the fueled region of the core. Thus, CORE ALTERATIONS are allowed in a quadrant with no OPERABLE SRM in an adjacent quadrant, as provided in the Table 3.3.1.2-1, footnote (b), requirement that the bundles being spiral reloaded or spiral offloaded are all in a single fueled region containing at least one OPERABLE SRM is met. Spiral reloading and offloading encompass reloading or offloading a cell on the edges of a continuous fueled region (the cell can be reloaded or offloaded in any sequence).

In nonspiral routine operations, two SRMs are required to be OPERABLE to provide redundant monitoring of reactivity changes occurring in the reactor core. Because of the local nature of reactivity changes during refueling, adequate

(continued)

BASES

LCO
(continued) coverage is provided by requiring one SRM to be OPERABLE in the quadrant of the reactor core where CORE ALTERATIONS are being performed and the other SRM to be OPERABLE in an adjacent quadrant containing fuel. These requirements ensure that the reactivity of the core will be continuously monitored during CORE ALTERATIONS.

Special movable detectors, according to Table 3.3.1.2-1, footnote (c), may be used in MODE 5 in place of the normal SRM nuclear detectors. These special detectors must be connected to the normal SRM circuits in the NMS such that the applicable neutron flux indication can be generated. These special detectors provide more flexibility in monitoring reactivity changes during fuel loading, since they can be positioned anywhere within the core during refueling. They must still meet the location requirements of SR 3.3.1.2.2, and all other required SRs for SRMs.

For an SRM channel to be considered OPERABLE, it must be providing neutron flux monitoring indication. In addition, in MODE 5, the required SRMs must be inserted to the normal operating level and be providing continuous visual indication in the control room.

APPLICABILITY The SRMs are required to be OPERABLE in MODE 2 prior to the IRMs being on scale on Range 3, and MODES 3, 4, and 5, to provide for neutron monitoring. In MODE 1, the APRMs provide adequate monitoring of reactivity changes in the core; therefore, the SRMs are not required. In MODE 2, with IRMs on Range 3 or above, the IRMs provide adequate monitoring and the SRMs are not required.

ACTIONS

A.1 and B.1

In MODE 2, with the IRMs on Range 2 or below, SRMs provide the means of monitoring core reactivity and criticality. With any number of the required SRMs inoperable, the ability to monitor is degraded. Therefore, a limited time is allowed to restore the inoperable channels to OPERABLE status.

Providing that at least one SRM remains OPERABLE, Required Action A.1 allows 4 hours to restore the required SRMs to OPERABLE status. This is a reasonable time since there is

(continued)

BASES

ACTIONS

A.1 and B.1 (continued)

adequate capability remaining to monitor the core, limited risk of an event during this time, and sufficient time to take corrective actions to restore the required SRMs to OPERABLE status or to establish alternate IRM monitoring capability. During this time, control rod withdrawal and power increase are not precluded by this Required Action. Having the ability to monitor the core with at least one SRM, proceeding to IRM Range 3 or greater (with overlap required by SR 3.3.1.1.6) and thereby exiting the Applicability of this LCO, is acceptable for ensuring adequate core monitoring and allowing continued operation.

With three required SRMs inoperable, Required Action B.1 allows no positive changes in reactivity (control rod withdrawal must be immediately suspended) due to the inability to monitor the changes. Required Action A.1 still applies and allows 4 hours to restore monitoring capability prior to requiring control rod insertion. This allowance is based on the limited risk of an event during this time, provided that no control rod withdrawals are allowed, and the desire to concentrate efforts on repair, rather than to immediately shut down, with no SRMs OPERABLE.

C.1

In MODE 2 with the IRMs on Range 2 or below, if the required number of SRMs is not restored to OPERABLE status within the allowed Completion Time, the reactor shall be placed in MODE 3. With all control rods fully inserted, the core is in its least reactive state with the most margin to criticality. The allowed Completion Time of 12 hours is reasonable, based on operating experience, to reach MODE 3 in an orderly manner and without challenging plant systems.

D.1 and D.2

With one or more required SRM channels inoperable in MODE 3 or 4, the neutron flux monitoring capability is degraded or nonexistent. The requirement to fully insert all insertable control rods ensures that the reactor will be at its minimum reactivity level while no neutron monitoring capability is available. Placing the reactor mode switch in the shutdown

(continued)

BASES

ACTIONS D.1 and D.2 (continued)

position prevents subsequent control rod withdrawal by maintaining a control rod block. The allowed Completion Time of 1 hour is sufficient to accomplish the Required Action, and takes into account the low probability of an event requiring the SRM occurring during this time.

E.1 and E.2

With one or more required SRMs inoperable in MODE 5, the capability to detect local reactivity changes in the core during refueling is degraded. CORE ALTERATIONS must be immediately suspended, and action must be immediately initiated to fully insert all insertable control rods in core cells containing one or more fuel assemblies. Suspending CORE ALTERATIONS prevents the two most probable causes of reactivity changes, fuel loading and control rod withdrawal, from occurring. Inserting all insertable control rods ensures that the reactor will be at its minimum reactivity, given that fuel is present in the core. Suspension of CORE ALTERATIONS shall not preclude completion of the movement of a component to a safe, conservative position.

Action (once required to be initiated) to insert control rods must continue until all insertable rods in core cells containing one or more fuel assemblies are inserted.

SURVEILLANCE
REQUIREMENTS

As noted at the beginning of the SRs, the SRs for each SRM Applicable MODE or other specified condition are found in the SRs column of Table 3.3.1.2-1.

SR 3.3.1.2.1 and SR 3.3.1.2.3

Performance of the CHANNEL CHECK ensures that a gross failure of instrumentation has not occurred. A CHANNEL CHECK is normally a comparison of the parameter indicated on one channel to the same parameter indicated on other similar channels. It is based on the assumption that instrument channels monitoring the same parameter should read approximately the same value. Significant deviations

(continued)

BASES

SURVEILLANCE
REQUIREMENTS

SR 3.3.1.2.1 and SR 3.3.1.2.3 (continued)

between the instrument channels could be an indication of excessive instrument drift in one of the channels or something even more serious. A CHANNEL CHECK will detect gross channel failure; thus, it is key to verifying the instrumentation continues to operate properly between each CHANNEL CALIBRATION.

Agreement criteria are determined by the plant staff, based on a combination of the channel instrument uncertainties, including indication and readability. If a channel is outside the criteria, it may be an indication that the instrument has drifted outside its limit.

The Frequency of once every 12 hours for SR 3.3.1.2.1 is based on operating experience that demonstrates channel failure is rare. While in MODES 3 and 4, reactivity changes are not expected; therefore, the 12 hour Frequency is relaxed to 24 hours for SR 3.3.1.2.3. The CHANNEL CHECK supplements less formal, but more frequent, checks of channels during normal operational use of the displays associated with the channels required by the LCO.

SR 3.3.1.2.2

To provide adequate coverage of potential reactivity changes in the core, one SRM is required to be OPERABLE in the quadrant where CORE ALTERATIONS are being performed, and the other OPERABLE SRM must be in an adjacent quadrant containing fuel. Note 1 states that this SR is required to be met only during CORE ALTERATIONS. It is not required to be met at other times in MODE 5 since core reactivity changes are not occurring. This Surveillance consists of a review of plant logs to ensure that SRMs required to be OPERABLE for given CORE ALTERATIONS are, in fact, OPERABLE. In the event that only one SRM is required to be OPERABLE, per Table 3.3.1.2-1, footnote (b), only the a. portion of this SR is effectively required. Note 2 clarifies that more than one of the three requirements can be met by the same OPERABLE SRM. The 12 hour Frequency is based upon operating experience and supplements operational controls over refueling activities, which include steps to ensure that the SRMs required by the LCO are in the proper quadrant.

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BASES

SURVEILLANCE
REQUIREMENTS
(continued)

SR 3.3.1.2.4

This Surveillance consists of a verification of the SRM instrument readout to ensure that the SRM reading is greater than a specified minimum count rate with the detector fully inserted. This ensures that the detectors are indicating count rates indicative of neutron flux levels within the core. With few fuel assemblies loaded, the SRMs will not have a high enough count rate to satisfy the SR. Therefore, allowances are made for loading sufficient "source" material, in the form of irradiated fuel assemblies, to establish the minimum count rate.

To accomplish this, the SR is modified by a Note that states that the count rate is not required to be met on an SRM that has less than or equal to four fuel assemblies adjacent to the SRM and no other fuel assemblies are in the associated core quadrant. With four or less fuel assemblies loaded around each SRM and no other fuel assemblies in the associated quadrant, even with a control rod withdrawn the configuration will not be critical. When movable detectors are being used, detector location must be selected such that each group of fuel assemblies is separated by at least two fuel cells from any other fuel assemblies.

The Frequency is based upon channel redundancy and other information available in the control room, and ensures that the required channels are frequently monitored while core reactivity changes are occurring. When no reactivity changes are in progress, the Frequency is relaxed from 12 hours to 24 hours.

SR 3.3.1.2.5 and SR 3.3.1.2.6

Performance of a CHANNEL FUNCTIONAL TEST demonstrates the associated channel will function properly. A successful test of the required contact(s) of a channel relay may be performed by the verification of the change of state of a single contact of the relay. This clarifies what is an acceptable CHANNEL FUNCTIONAL TEST of a relay. This is acceptable because all of the other required contacts of the relay are verified by other Technical Specifications and

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BASES

SURVEILLANCE
REQUIREMENTS

SR 3.3.1.2.5 and SR 3.3.1.2.6 (continued)

non-Technical Specifications tests at least once per refueling interval with applicable extensions. SR 3.3.1.2.5 is required in MODE 5, and the 7 day Frequency ensures that the channels are OPERABLE while core reactivity changes could be in progress. This 7 day Frequency is reasonable, based on operating experience and on other Surveillances (such as a CHANNEL CHECK) that ensure proper functioning between CHANNEL FUNCTIONAL TESTS.

SR 3.3.1.2.6 is required to be met in MODE 2 with IRMs on Range 2 or below and in MODES 3 and 4. Since core reactivity changes do not normally take place in MODES 3 and 4 and core reactivity changes are due only to control rod movement in MODE 2, the Frequency is extended from 7 days to 31 days. The 31 day Frequency is based on operating experience and on other Surveillances (such as CHANNEL CHECK) that ensure proper functioning between CHANNEL FUNCTIONAL TESTS.

Verification of the signal to noise ratio also ensures that the detectors are inserted to a normal operating level. In a fully withdrawn condition, the detectors are sufficiently removed from the fueled region of the core to essentially eliminate neutrons from reaching the detector. Any count rate obtained while fully withdrawn is assumed to be "noise" only.

With few fuel assemblies loaded, the SRMs will not have a high enough count rate to determine the signal to noise ratio. Therefore, allowances are made for loading sufficient "source" material, in the form of irradiated fuel assemblies, to establish the conditions necessary to determine the signal to noise ratio. To accomplish this, SR 3.3.1.2.5 is modified by a Note that states that the determination of signal to noise ratio is not required to be met on an SRM that has less than or equal to four fuel assemblies adjacent to the SRM and no other fuel assemblies are in the associated core quadrant. With four or less fuel assemblies loaded around each SRM and no other fuel assemblies in the associated quadrant, even with a control rod withdrawn the configuration will not be critical.

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BASES

SURVEILLANCE
REQUIREMENTS

SR 3.3.1.2.5 and SR 3.3.1.2.6 (continued)

The Note to SR 3.3.1.2.6 allows the Surveillance to be delayed until entry into the specified condition of the Applicability. The SR must be performed in MODE 2 within 12 hours of entering MODE 2 with IRMs on Range 2 or below. The allowance to enter the Applicability with the 31 day Frequency not met is reasonable, based on the limited time of 12 hours allowed after entering the Applicability and the inability to perform the Surveillance while at higher power levels. Although the Surveillance could be performed while on IRM Range 3, the plant would not be expected to maintain steady state operation at this power level. In this event, the 12 hour Frequency is reasonable, based on the SRMs being otherwise verified to be OPERABLE (i.e., satisfactorily performing the CHANNEL CHECK) and the time required to perform the Surveillances.

SR 3.3.1.2.7

Performance of a CHANNEL CALIBRATION verifies the performance of the SRM detectors and associated circuitry. The Frequency considers the plant conditions required to perform the test, the ease of performing the test, and the likelihood of a change in the system or component status. The neutron detectors are excluded from the CHANNEL CALIBRATION (Note 1) because they cannot readily be adjusted. The detectors are fission chambers that are designed to have a relatively constant sensitivity over the range, and with an accuracy specified for a fixed useful life.

Note 2 to the Surveillance allows the Surveillance to be delayed until entry into the specified condition of the Applicability. The SR must be performed in MODE 2 within 12 hours of entering MODE 2 with IRMs on Range 2 or below. The allowance to enter the Applicability with the 24 month Frequency not met is reasonable, based on the limited time of 12 hours allowed after entering the Applicability and the inability to perform the Surveillance while at higher power levels. Although the Surveillance could be performed while

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BASES

SURVEILLANCE
REQUIREMENTS

SR 3.3.1.2.7 (continued)

on IRM Range 3, the plant would not be expected to maintain steady state operation at this power level. In this event, the 12 hour Frequency is reasonable, based on the SRMs being otherwise verified to be OPERABLE (i.e., satisfactorily performing the CHANNEL CHECK) and the time required to perform the Surveillances.

REFERENCES

None.

B 3.3 INSTRUMENTATION

B 3.3.2.1 Control Rod Block Instrumentation

BASES

BACKGROUND

Control rods provide the primary means for control of reactivity changes. Control rod block instrumentation includes channel sensors, logic circuitry, switches, and relays that are designed to ensure that specified fuel design limits are not exceeded for postulated transients and accidents. During high power operation, the rod block monitor (RBM) provides protection for control rod withdrawal error events. During low power operations, control rod blocks from the rod worth minimizer (RWM) enforce specific control rod sequences designed to mitigate the consequences of the control rod drop accident (CRDA). During shutdown conditions, control rod blocks from the Reactor Mode Switch-Shutdown Position Function ensure that all control rods remain inserted to prevent inadvertent criticalities.

The purpose of the RBM is to limit control rod withdrawal if localized neutron flux exceeds a predetermined setpoint during control rod manipulations (Ref. 1). It is assumed to function to block further control rod withdrawal to preclude a MCPR Safety Limit (SL) violation. The RBM supplies a trip signal to the Reactor Manual Control System (RMCS) to appropriately inhibit control rod withdrawal during power operation above the 30% RATED THERMAL POWER setpoint when a non peripheral control rod is selected. The RBM has two channels, either of which can initiate a control rod block when the channel output exceeds the control rod block setpoint. One RBM channel inputs into one RMCS rod block circuit and the other RBM channel inputs into the second RMCS rod block circuit. The RBM channel signal is generated by averaging a set of local power range monitor (LPRM) signals. One RBM channel averages the signals from LPRM detectors at the A and C positions in the assigned LPRM assemblies. The second RBM channel averages the signals from the LPRM detectors at the B and D positions. Assignment of LPRM assemblies to be used in RBM averaging is controlled by the selection of control rods. With no control rod selected, the RBM output is set to zero. However, when a control rod is selected, the gain of each

(continued)

BASES

BACKGROUND
(continued)

RBM channel output is normalized to an assigned average power range monitor (APRM) channel. The assigned APRM channel is on the same RPS trip system as the RBM channel. The gain setting is held constant during the movement of that particular control rod to provide an indication of the change in the relative local power level. If the APRM used to normalize the RBM reading is indicating < 30% or a peripheral control rod is selected, the RBM is zeroed and the RBM is bypassed (Refs. 1 and 2).

If any LPRM detector assigned to an RBM is bypassed, the computed average signal is adjusted automatically to compensate for the number of LPRM signals. The minimum number of LPRM inputs required for each RBM channel to prevent an instrument inoperative alarm is four when using four LPRM assemblies, three when using three LPRM assemblies, and two when using two LPRM assemblies. If the normalizing APRM channel is bypassed, a second APRM channel automatically provides the normalizing signal (Refs. 1 and 2).

In addition, to preclude rod movement with an inoperable RBM, a downscale trip and an inoperable trip are provided.

The purpose of the RWM is to control rod patterns during startup and shutdown, such that only specified control rod sequences and relative positions are allowed over the operating range from all control rods inserted to 10% RTP. The sequences effectively limit the potential amount and rate of reactivity increase during a CRDA. Prescribed control rod sequences are stored in the RWM, which will initiate control rod withdrawal and insert blocks when the actual sequence deviates beyond allowances from the stored sequence. The RWM determines the actual sequence based on position indication for each control rod. The RWM also uses steam flow signals to determine when the reactor power is above the preset power level at which the RWM is automatically bypassed. The RWM is a single channel system that provides input into both RMCS rod block circuits (Refs. 2 and 3).

With the reactor mode switch in the shutdown position, a control rod withdrawal block is applied to all control rods to ensure that the shutdown condition is maintained. This Function prevents inadvertent criticality as the result of a

(continued)

BASES

BACKGROUND (continued) control rod withdrawal during MODE 3 or 4, or during MODE 5 when the reactor mode switch is required to be in the shutdown position. The reactor mode switch has two channels, each inputting into a separate RMCS rod block circuit. Each reactor mode switch channel has contacts permitting control rod withdrawal in the reactor mode switch positions of run, startup, and refuel interlocked with other plant conditions. With the reactor mode switch in shutdown, the RMCS circuits do not receive a permissive for control rod withdrawal. A rod block in either RMCS circuit will provide a control rod block to all control rods.

APPLICABLE SAFETY ANALYSES, LCO, and APPLICABILITY

1. Rod Block Monitor

The RBM is designed to prevent violation of the MCPR SL and the cladding 1% plastic strain fuel design limit that may result from a single control rod withdrawal error (RWE) event. The analytical methods and assumptions used in evaluating the RWE event are summarized in Reference 4. The cycle-specific analysis considers the continuous withdrawal of the maximum worth control rod at its maximum drive speed from the reactor, which is operating at rated power with a control rod pattern that results in the core being placed on thermal design limits. The condition is analyzed to ensure that the results obtained are conservative; the approach also serves to demonstrate the function of the RBM.

The RBM Function satisfies Criterion 3 of 10 CFR 50.36(c)(2)(ii).

Two channels of the RBM are required to be OPERABLE, with their setpoints within the appropriate Allowable Values in the CORE OPERATING LIMITS REPORT to ensure that no single instrument failure can preclude a rod block from this Function. The actual setpoints are calibrated consistent with applicable setpoint methodology.

Nominal trip setpoints are specified in the setpoint calculations. The nominal setpoints are selected to ensure that the setpoints do not exceed the Allowable Values between successive CHANNEL CALIBRATIONS. Operation with a trip setpoint less conservative than the nominal trip

(continued)

BASES

APPLICABLE
SAFETY ANALYSES,
LCO, and
APPLICABILITY
(continued)

setpoint, but within its Allowable Value, is acceptable. Trip setpoints are those predetermined values of output at which an action should take place. The setpoints are compared to the actual process parameter (e.g., reactor power), and when the measured output value of the process parameter exceeds the setpoint, the associated device (e.g., trip unit) changes state. The analytic limits are derived from the limiting values of the process parameters obtained from the safety analysis. The trip setpoints are determined from the analytic limits, corrected for defined process, calibration, and instrument errors. The Allowable Values are then determined, based on the trip setpoint values, by accounting for the calibration based errors. These calibration based errors are limited to reference accuracy, instrument drift, errors associated with measurement and test equipment, and calibration tolerance of loop components. The trip setpoints and Allowable Values determined in this manner provide adequate protection because instrument uncertainties, process effects, calibration tolerances, instrument drift, and severe environment errors (for channels that must function in harsh environments as defined by 10 CFR 50.49) are accounted for and appropriately applied for the instrumentation.

The RBM is assumed to mitigate the consequences of an RWE event when operating $\geq 30\%$ RTP and a non-peripheral control rod is selected. Below this power level or if a peripheral control rod is selected, the consequences of an RWE event will not exceed the MCPR SL and, therefore, the RBM is not required to be OPERABLE (Ref. 4).

2. Rod Worth Minimizer

The RWM enforces the analyzed rod position sequence to ensure that the initial conditions of the CRDA analysis are not violated. The analytical methods and assumptions used in evaluating the CRDA are summarized in References 5, 6, and 7. The analyzed rod position sequence requires that control rods be moved in groups, with all control rods assigned to a specific group required to be within specified banked positions. Requirements that the control rod sequence is in compliance with the analyzed rod position sequence are specified in LCO 3.1.6, "Rod Pattern Control."

(continued)

BASES

APPLICABLE
SAFETY ANALYSES,
LCO, and
APPLICABILITY

2. Rod Worth Minimizer (continued)

The RWM Function satisfies Criterion 3 of 10 CFR 50.36(c)(2)(ii).

Since the RWM is a system designed to act as a backup to operator control of the rod sequences, only one channel of the RWM is available and required to be OPERABLE (Ref. 7). Special circumstances provided for in the Required Action of LCO 3.1.3, "Control Rod OPERABILITY," and LCO 3.1.6 may necessitate bypassing the RWM to allow continued operation with inoperable control rods, or to allow correction of a control rod pattern not in compliance with the analyzed rod position sequence. The RWM may be bypassed as required by these conditions, but then it must be considered inoperable and the Required Actions of this LCO followed.

Compliance with the analyzed rod position sequence, and therefore OPERABILITY of the RWM, is required in MODES 1 and 2 when THERMAL POWER is $\leq 10\%$ RTP. When THERMAL POWER is $> 10\%$ RTP, there is no possible control rod configuration that results in a control rod worth that could exceed the 280 cal/gm fuel design limit during a CRDA (Refs. 6 and 7). In MODES 3 and 4, all control rods are required to be inserted into the core; therefore, a CRDA cannot occur. In MODE 5, since only a single control rod can be withdrawn from a core cell containing fuel assemblies, adequate SDM ensures that the consequences of a CRDA are acceptable, since the reactor will be subcritical.

3. Reactor Mode Switch—Shutdown Position

During MODES 3 and 4, and during MODE 5 when the reactor mode switch is in the shutdown position, the core is assumed to be subcritical; therefore, no positive reactivity insertion events are analyzed. The Reactor Mode Switch—Shutdown Position control rod withdrawal block ensures that the reactor remains subcritical by blocking control rod withdrawal, thereby preserving the assumptions of the safety analysis.

The Reactor Mode Switch—Shutdown Position Function satisfies Criterion 3 of 10 CFR 50.36(c)(2)(ii).

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BASES

APPLICABLE
SAFETY ANALYSES,
LCO, and
APPLICABILITY

3. Reactor Mode Switch - Shutdown Position (continued)

Two channels are required to be OPERABLE to ensure that no single channel failure will preclude a rod block when required. There is no Allowable Value for this Function since the channels are mechanically actuated based solely on reactor mode switch position.

During shutdown conditions (MODES 3 and 4, and MODE 5 when the reactor mode switch is in the shutdown position), no positive reactivity insertion events are analyzed because assumptions are that control rod withdrawal blocks are provided to prevent criticality. Therefore, when the reactor mode switch is in the shutdown position, the control rod withdrawal block is required to be OPERABLE. During MODE 5 with the reactor mode switch in the refueling position, the refuel position one-rod-out interlock (LCO 3.9.2, "Refuel Position One-Rod-Out Interlock") provides the required control rod withdrawal blocks.

ACTIONS

A.1

With one RBM channel inoperable, the remaining OPERABLE channel is adequate to perform the control rod block function; however, overall reliability is reduced because a single failure in the remaining OPERABLE channel can result in no control rod block capability for the RBM. For this reason, Required Action A.1 requires restoration of the inoperable channel to OPERABLE status. The Completion Time of 24 hours is based on the low probability of an event occurring coincident with a failure in the remaining OPERABLE channel.

B.1

If Required Action A.1 is not met and the associated Completion Time has expired, the inoperable channel must be placed in trip within 1 hour. If both RBM channels are inoperable, the RBM is not capable of performing its intended function; thus, one channel must also be placed in trip. This initiates a control rod withdrawal block, thereby ensuring that the RBM function is met.

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BASES

ACTIONS

B.1 (continued)

The 1 hour Completion Time is intended to allow the operator time to evaluate and repair any discovered inoperabilities and is acceptable because it minimizes risk while allowing time for restoration or tripping of inoperable channels.

C.1, C.2.1.1, C.2.1.2, and C.2.2

With the RWM inoperable during a reactor startup, the operator is still capable of enforcing the prescribed control rod sequence. However, the overall reliability is reduced because a single operator error can result in violating the control rod sequence. Therefore, control rod movement must be immediately suspended except by scram. Alternatively, startup may continue if at least 12 control rods have already been withdrawn, or a reactor startup with an inoperable RWM during withdrawal of one or more of the first 12 control rods was not performed in the last 12 months. These requirements minimize the number of reactor startups initiated with the RWM inoperable. Required Actions C.2.1.1 and C.2.1.2 require verification of these conditions by review of plant logs and control room indications. Once Required Action C.2.1.1 or C.2.1.2 is satisfactorily completed, control rod withdrawal may proceed in accordance with the restrictions imposed by Required Action C.2.2. Required Action C.2.2 allows for the RWM Function to be performed manually and requires a double check of compliance with the prescribed rod sequence by a second licensed operator (Reactor Operator or Senior Reactor Operator) or other task qualified member of the technical staff (e.g., shift technical advisor or reactor engineer).

The RWM may be bypassed under these conditions to allow continued operations. In addition, Required Actions of LCO 3.1.3 and LCO 3.1.6 may require bypassing the RWM, during which time the RWM must be considered inoperable with Condition C entered and its Required Actions taken.

(continued)

BASES

ACTIONS
(continued)

D.1

With the RWM inoperable during a reactor shutdown, the operator is still capable of enforcing the prescribed control rod sequence. Required Action D.1 allows for the RWM Function to be performed manually and requires a double check of compliance with the prescribed rod sequence by a second licensed operator (Reactor Operator or Senior Reactor Operator) or other task qualified member of the technical staff (e.g., shift technical advisor or reactor engineer). The RWM may be bypassed under these conditions to allow the reactor shutdown to continue.

E.1 and E.2

With one Reactor Mode Switch-Shutdown Position control rod withdrawal block channel inoperable, the remaining OPERABLE channel is adequate to perform the control rod withdrawal block function. However, since the Required Actions are consistent with the normal action of an OPERABLE Reactor Mode Switch-Shutdown Position Function (i.e., maintaining all control rods inserted), there is no distinction between having one or two channels inoperable.

In both cases (one or both channels inoperable), suspending all control rod withdrawal and initiating action to fully insert all insertable control rods in core cells containing one or more fuel assemblies will ensure that the core is subcritical with adequate SDM ensured by LCO 3.1.1. Control rods in core cells containing no fuel assemblies do not affect the reactivity of the core and are therefore not required to be inserted. Action must continue until all insertable control rods in core cells containing one or more fuel assemblies are fully inserted.

SURVEILLANCE
REQUIREMENTS

As noted at the beginning of the SRs, the SRs for each Control Rod Block instrumentation Function are found in the SRs column of Table 3.3.2.1-1.

The Surveillances are modified by a second Note to indicate that when an RBM channel is placed in an inoperable status solely for performance of required Surveillances, entry into associated Conditions and Required Actions may be delayed

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BASES

SURVEILLANCE
REQUIREMENTS
(continued)

for up to 6 hours provided the associated Function maintains control rod block capability. Upon completion of the Surveillance, or expiration of the 6 hour allowance, the channel must be returned to OPERABLE status or the applicable Condition entered and Required Actions taken. This Note is based on the reliability analysis (Ref. 8) assumption of the average time required to perform channel Surveillance. That analysis demonstrated that the 6 hour testing allowance does not significantly reduce the probability that a control rod block will be initiated when necessary.

SR 3.3.2.1.1

A CHANNEL FUNCTIONAL TEST is performed for each RBM channel to ensure that the entire channel will perform the intended function. It includes the Reactor Manual Control Multiplexing System input. A successful test of the required contact(s) of a channel relay may be performed by the verification of the change of state of a single contact of the relay. This clarifies what is an acceptable CHANNEL FUNCTIONAL TEST of a relay. This is acceptable because all of the other required contacts of the relay are verified by other Technical Specifications and non-Technical Specifications tests at least once per refueling interval with applicable extensions.

Any setpoint adjustment shall be consistent with the assumptions of the current plant specific setpoint methodology. The Frequency of 92 days is based on reliability analyses (Ref. 9).

SR 3.3.2.1.2 and SR 3.3.2.1.3

A CHANNEL FUNCTIONAL TEST is performed for the RWM to ensure that the entire system will perform the intended function. A successful test of the required contact(s) of a channel relay may be performed by the verification of the change of state of a single contact of the relay. This clarifies what is an acceptable CHANNEL FUNCTIONAL TEST of a relay. This is acceptable because all of the other required contacts of the relay are verified by other Technical Specifications and non-Technical Specifications tests at least once per

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BASES

SURVEILLANCE
REQUIREMENTS

SR 3.3.2.1.2 and SR 3.3.2.1.3 (continued)

refueling interval with applicable extensions. The CHANNEL FUNCTIONAL TEST for the RWM is performed by attempting to withdraw a control rod not in compliance with the prescribed sequence and verifying a control rod block occurs and by verifying proper annunciation of the selection error of at least one out-of-sequence control rod. As noted in the SRs, SR 3.3.2.1.2 is not required to be performed until 1 hour after any control rod is withdrawn at $\leq 10\%$ RTP in MODE 2 and SR 3.3.2.1.3 is not required to be performed until 1 hour after THERMAL POWER is $\leq 10\%$ RTP in MODE 1. The Note to SR 3.3.2.1.2 allows entry into MODE 2 on a startup and entry into MODE 2 concurrent with a power reduction to $\leq 10\%$ RTP during a shutdown to perform the required Surveillance if the 92 day Frequency is not met per SR 3.0.2. The Note to SR 3.3.2.1.3 allows a THERMAL POWER reduction to $\leq 10\%$ RTP in MODE 1 to perform the required Surveillance if the 92 day Frequency is not met per SR 3.0.2. The 1 hour allowances are based on operating experience and in consideration of providing a reasonable time in which to complete the SRs. Operating experience has shown that these components usually pass the Surveillances when performed at the 92 day Frequency. Therefore, the Frequency was concluded to be acceptable from a reliability standpoint.

SR 3.3.2.1.4

A CHANNEL CALIBRATION is a complete check of the instrument loop and the sensor. This test verifies the channel responds to the measured parameter within the necessary range and accuracy. CHANNEL CALIBRATION leaves the channel adjusted to account for instrument drifts between successive calibrations consistent with the plant specific setpoint methodology.

As noted, neutron detectors are excluded from the CHANNEL CALIBRATION because they are passive devices, with minimal drift, and because of the difficulty of simulating a meaningful signal. Neutron detectors are adequately tested in SR 3.3.1.1.2 and SR 3.3.1.1.8.

(continued)

BASES

SURVEILLANCE
REQUIREMENTS

SR 3.3.2.1.4 (continued)

The Frequency is based upon the assumption of a 92 day calibration interval in the determination of the magnitude of equipment drift in the setpoint analysis.

SR 3.3.2.1.5

The RBM is automatically bypassed when power is below a specified value or if a peripheral control rod is selected. The power level is determined from the APRM signals input to each RBM channel. The automatic bypass setpoint must be verified periodically to be < 30% RTP. In addition, it must also be verified that the RBM is not bypassed when a control rod that is not a peripheral control rod is selected (only one non-peripheral control rod is required to be verified). If any bypass setpoint is nonconservative, then the affected RBM channel is considered inoperable. Alternatively, the APRM channel can be placed in the conservative condition to enable the RBM. If placed in this condition, the SR is met and the RBM channel is not considered inoperable. As noted, neutron detectors are excluded from the Surveillance because they are passive devices, with minimal drift, and because of the difficulty of simulating a meaningful signal. Neutron detectors are adequately tested in SR 3.3.1.1.2 and SR 3.3.1.1.8. The 92 day Frequency is based on the actual trip setpoint methodology utilized for these channels.

SR 3.3.2.1.6

The RWM is automatically bypassed when power is above a specified value. The power level is determined from steam flow signal. The automatic bypass setpoint must be verified periodically to be > 10% RTP. If the RWM low power setpoint is nonconservative, then the RWM is considered inoperable. Alternately, the low power setpoint channel can be placed in the conservative condition (nonbypass). If placed in the nonbypassed condition, the SR is met and the RWM is not considered inoperable. The Frequency is based on the trip setpoint methodology utilized for the low power setpoint channel.

(continued)

BASES

SURVEILLANCE
REQUIREMENTS
(continued)

SR 3.3.2.1.7

A CHANNEL FUNCTIONAL TEST is performed for the Reactor Mode Switch-Shutdown Position Function to ensure that the entire channel will perform the intended function. A successful test of the required contact(s) of a channel relay may be performed by the verification of the change of state of a single contact of the relay. This clarifies what is an acceptable CHANNEL FUNCTIONAL TEST of a relay. This is acceptable because all of the other required contacts of the relay are verified by other Technical Specifications and non-Technical Specifications tests at least once per refueling interval with applicable extensions. The CHANNEL FUNCTIONAL TEST for the Reactor Mode Switch-Shutdown Position Function is performed by attempting to withdraw any control rod with the reactor mode switch in the shutdown position and verifying a control rod block occurs.

As noted in the SR, the Surveillance is not required to be performed until 1 hour after the reactor mode switch is in the shutdown position, since testing of this interlock with the reactor mode switch in any other position cannot be performed without using jumpers, lifted leads, or movable links. This allows entry into MODES 3 and 4 if the 24 month Frequency is not met per SR 3.0.2. The 1 hour allowance is based on operating experience and in consideration of providing a reasonable time in which to complete the SRs.

The 24 month Frequency is based on the need to perform this Surveillance under the conditions that apply during a plant outage and the potential for an unplanned transient if the Surveillance were performed with the reactor at power. Operating experience has shown these components usually pass the Surveillance when performed at the 24 month Frequency.

SR 3.3.2.1.8

The RWM will only enforce the proper control rod sequence if the rod sequence is properly input into the RWM computer. This SR ensures that the proper sequence is loaded into the RWM so that it can perform its intended function. The Surveillance is performed once prior to declaring RWM OPERABLE following loading of sequence into RWM, since this is when rod sequence input errors are possible.

(continued)

BASES

SURVEILLANCE
REQUIREMENTS
(continued)

SR 3.3.2.1.9

LCO 3.1.3 and LCO 3.1.6 may require individual control rods to be bypassed (taken out of service) in the RWM to allow insertion of an inoperable control rod or correction of a control rod pattern not in compliance with the analyzed rod position sequence. With the control rods bypassed (taken out of service) in the RWM, the RWM will provide insert and withdraw blocks for bypassed control rods that are fully inserted and a withdraw block for bypassed control rods that are not fully inserted. To ensure the proper bypassing and movement of those affected control rods, a second licensed operator (Reactor Operator or Senior Reactor Operator) or other task qualified member of the technical staff (e.g., shift technical advisor or reactor engineer) must verify the bypassing and position of these control rods. Compliance with this SR allows the RWM to be OPERABLE with these control rods bypassed.

REFERENCES

1. UFSAR, Section 7.7.6.3.
2. UFSAR, Section 7.7.2.2.3.
3. UFSAR, Section 7.7.7.2.3.
4. UFSAR, Section 15.4.2.3.
5. UFSAR, Section 15.4.9.
6. "Modifications to the Requirements for Control Rod Drop Accident Mitigating Systems," BWR Owners' Group, July 1986.
7. NRC SER, "Acceptance of Referencing of Licensing Topical Report NEDE-24011-P-A," "General Electric Standard Application for Reactor Fuel, Revision 8, Amendment 17," December 27, 1987.
8. GENE-770-06-1-A, "Addendum to Bases for Changes to Surveillance Test Intervals and Allowed Out-of-Service Times for Selected Instrumentation Technical Specifications," December 1992.

(continued)

BASES

- REFERENCES (continued)
9. NEDC-30851-P-A, Supplement 1, "Technical Specification Improvement Analysis for BWR Control Rod Block Instrumentation," October 1988.
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B 3.3 INSTRUMENTATION

B 3.3.2.2 Feedwater System and Main Turbine High Water Level Trip Instrumentation

BASES

BACKGROUND

The Feedwater System and Main Turbine High Water Level Trip Instrumentation is designed to detect a potential failure of the Feedwater Level Control System that causes excessive feedwater flow.

With excessive feedwater flow, the water level in the reactor vessel rises toward the high water level, Level 8 reference point, causing the trip of the two feedwater pump turbines, the motor-driven feedwater pump and the main turbine.

Reactor Vessel Water Level-High, Level 8 signals are provided by differential pressure transmitters that sense the difference between the pressure due to a constant column of water (reference leg) and the pressure due to the actual water level in the reactor vessel (variable leg). Four channels of Reactor Vessel Water Level-High, Level 8 instrumentation are provided as input to the initiation logic that trips the two feedwater pump turbines, the motor-driven feedwater pump and the main turbine. Trip channels A and B each receive an input from Reactor Vessel Water Level-High, Level 8 channels and trip channel C receives an input from two Reactor Vessel Water Level-High, Level 8 channels. Trip channel C has one instrument that shares the same narrow range variable leg with trip channel A, and a second instrument that shares the narrow range variable leg with the instrument of trip channel B. Each of the trip channels will trip if any Reactor Vessel Water Level-High, Level 8 channel trips. Each of the three trip channel outputs are provided as inputs to the individual trip logics associated with each feedwater pump turbine, the motor-driven feedwater pump, and the main turbine. The trip channel inputs are arranged in a two-out-of-three logic for each initiation logic. The channels include electronic equipment (e.g., trip units) that compares measured input signals with pre-established setpoints. When the setpoint is exceeded, the channel output relay actuates, which then outputs a feedwater system and main turbine trip signal to the trip logic.

(continued)

BASES

BACKGROUND (continued) A trip of the feedwater pump turbines and the motor-driven feedwater pump limits further increase in reactor vessel water level by limiting further addition of feedwater to the reactor vessel. A trip of the main turbine and closure of the stop valves protects the turbine from damage due to water entering the turbine.

APPLICABLE SAFETY ANALYSES The Feedwater System and Main Turbine High Water Level Trip Instrumentation is assumed to be capable of providing a trip of the feedwater turbines, the motor-driven feedwater pump, and the main turbine in the design basis transient analysis for a feedwater controller failure, maximum demand event (Ref. 1). The Level 8 trip indirectly initiates a reactor scram from the main turbine trip (above 25% RTP) and trips the feedwater pumps, thereby terminating the event. The reactor scram mitigates the reduction in MCPR.

Feedwater System and Main Turbine High Water Level Trip Instrumentation satisfies Criterion 3 of 10 CFR 50.36(c)(2)(ii).

LCO The LCO requires four channels (combined into three trip channels) of the Reactor Vessel Water Level-High, Level 8 instrumentation to be OPERABLE to ensure that no single instrument failure or variable leg failure will prevent the feedwater pump turbines, the motor-driven feedwater pump, and main turbine to trip on a valid Level 8 signal. Two of the three trip channels are needed to provide trip signals in order for the feedwater and main turbine and motor-driven feedwater pump trips to occur. Each channel must have its setpoint set within the specified Allowable Value of SR 3.3.2.2.3. The Allowable Value is set to ensure that the thermal limits are not exceeded during the event. The actual setpoint is calibrated to be consistent with the applicable setpoint methodology assumptions. Nominal trip setpoints are specified in the setpoint calculations. The nominal setpoints are selected to ensure that the setpoints do not exceed the Allowable Value between successive CHANNEL CALIBRATIONS. Operation with a trip setpoint less conservative than the nominal trip setpoint, but within its Allowable Value, is acceptable. A channel is inoperable if its actual trip setpoint is not within its required Allowable Value.

(continued)

BASES

LCO
(continued) Trip setpoints are those predetermined values of output at which an action should take place. The setpoints are compared to the actual process parameter (e.g., reactor vessel water level), and when the measured output value of the process parameter exceeds the setpoint, the associated device (e.g., trip unit) changes state. The analytic limits are derived from the limiting values of the process parameters obtained from the safety analysis. The trip setpoints are determined from the analytic limits, corrected for defined process, calibration, and instrument errors. The Allowable Values are then determined, based on the trip setpoint values, by accounting for the calibration based errors. These calibration based errors are limited to reference accuracy, instrument drift, errors associated with measurement and test equipment, and calibration tolerance of loop components. The trip setpoints and Allowable Values determined in this manner provide adequate protection because instrument uncertainties, process effects, calibration tolerances, instrument drift, and severe environment errors (for channels that must function in harsh environments as defined by 10 CFR 50.49) are accounted for and appropriately applied for the instrumentation.

APPLICABILITY The Feedwater System and Main Turbine High Water Level Trip Instrumentation is required to be OPERABLE at $\geq 25\%$ RTP to ensure that the fuel cladding integrity Safety Limit and the cladding 1% plastic strain limit are not violated during the feedwater controller failure, maximum demand event. As discussed in the Bases for LCO 3.2.1, "AVERAGE PLANAR LINEAR HEAT GENERATION RATE (APLHGR)," LCO 3.2.2, "MINIMUM CRITICAL POWER RATIO (MCPR)," and LCO 3.2.3, "LINEAR HEAT GENERATION RATE," sufficient margin to these limits exists below 25% RTP; therefore, these requirements are only necessary when operating at or above this power level.

ACTIONS A Note has been provided to modify the ACTIONS related to Feedwater System and Main Turbine High Water Level Trip Instrumentation channels. Section 1.3, Completion Times, specifies that once a Condition has been entered, subsequent divisions subsystems, components, or variables expressed in the Condition, discovered to be inoperable or not within limits, will not result in separate entry into the Condition. Section 1.3 also specifies that Required Actions

(continued)

BASES

ACTIONS (continued) of the Condition continue to apply for each additional failure, with Completion Times based on initial entry into the Condition. However, the Required Actions for inoperable Feedwater System and Main Turbine High Water Level Trip Instrumentation channels provide appropriate compensatory measures for separate inoperable channels. As such, a Note has been provided that allows separate Condition entry for each inoperable Feedwater System and Main Turbine High Water Level Trip Instrumentation channel.

A.1

With one or more channels inoperable and trip capability maintained, the remaining OPERABLE channels can provide the required trip signal. However, overall instrumentation reliability is reduced because a single failure in one of the remaining channels concurrent with feedwater controller failure, maximum demand event, or a variable leg failure may result in the instrumentation not being able to perform its intended function. Therefore, continued operation is only allowed for a limited time. If the inoperable channel cannot be restored to OPERABLE status within the Completion Time, the channel must be placed in the tripped condition per Required Action A.1. Placing the inoperable channel in trip would conservatively compensate for the inoperability, restore capability to accommodate a single failure, and allow operation to continue with no further restrictions. Alternately, if it is not desired to place the channel in trip (e.g., as in the case where placing the inoperable channel in trip would result in a feedwater turbine, motor-driven feedwater pump, or main turbine trip), Condition C must be entered and its Required Action taken.

The Completion Time of 7 days is based on the low probability of the event occurring coincident with a single failure in a remaining OPERABLE channel.

B.1

With the feedwater system and main turbine high water level trip capability not maintained, the feedwater system and main turbine high water level trip instrumentation cannot perform its design function. Therefore, continued operation

(continued)

BASES

ACTIONS

B.1 (continued)

is only permitted for a 2 hour period, during which feedwater system and main turbine high water level trip capability must be restored. The trip capability is considered maintained when sufficient channels are OPERABLE or in trip such that the feedwater system and main turbine high water level trip logic will generate a trip signal on a valid signal. This requires two of the three trip channels to have one feedwater system and main turbine high water level channel OPERABLE or in trip. If the required channels cannot be restored to OPERABLE status or placed in trip, Condition C must be entered and its Required Action taken.

The 2 hour Completion Time is sufficient for the operator to take corrective action, and takes into account the likelihood of an event requiring actuation of Feedwater System and Main Turbine High Water Level Trip Instrumentation occurring during this period. It is also consistent with the 2 hour Completion Time provided in LCO 3.2.2 for Required Action A.1, since this instrumentation's purpose is to preclude a MCPR violation.

C.1 and C.2

With the channel(s) not restored to OPERABLE status or placed in trip, THERMAL POWER must be reduced to < 25% RTP within 4 hours. As discussed in the Applicability section of the Bases, operation below 25% RTP results in sufficient margin to the required limits, and the Feedwater System and Main Turbine High Water Level Trip Instrumentation is not required to protect fuel integrity during the feedwater controller failure, maximum demand event. Alternatively, if a channel is inoperable solely due to an inoperable motor-driven feedwater pump breaker or feedwater stop valve, the affected feedwater pump(s) may be removed from service since this performs the intended function of the instrumentation. The allowed Completion Time of 4 hours is based on operating experience to reduce THERMAL POWER to < 25% RTP from full power conditions in an orderly manner and without challenging plant systems.

(continued)

BASES (continued)

SURVEILLANCE
REQUIREMENTS

The Surveillances are modified by a Note to indicate that when a channel is placed in an inoperable status solely for performance of required Surveillances, entry into associated Conditions and Required Actions may be delayed for up to 6 hours provided the Function maintains feedwater system and main turbine high water level trip capability. Upon completion of the Surveillance, or expiration of the 6 hour allowance, the channel must be returned to OPERABLE status or the applicable Condition entered and Required Actions taken. This Note is based on the reliability analysis (Ref. 2) assumption that 6 hours is the average time required to perform channel Surveillance. That analysis demonstrated that the 6 hour testing allowance does not significantly reduce the probability that the feedwater pump turbines, motor-driven feedwater pump, and main turbine will trip when necessary.

SR 3.3.2.2.1

Performance of the CHANNEL CHECK once every 12 hours ensures that a gross failure of instrumentation has not occurred. A CHANNEL CHECK is normally a comparison of the parameter indicated on one channel to a similar parameter on other channels. It is based on the assumption that instrument channels monitoring the same parameter should read approximately the same value. Significant deviations between instrument channels could be an indication of excessive instrument drift in one of the channels, or something even more serious. A CHANNEL CHECK will detect gross channel failure; thus, it is key to verifying the instrumentation continues to operate properly between each CHANNEL CALIBRATION.

Agreement criteria are determined by the plant staff based on a combination of the channel instrument uncertainties, including indication and readability. If a channel is outside the criteria, it may be an indication that the instrument has drifted outside its limits.

The Frequency is based on operating experience that demonstrates channel failure is rare. The CHANNEL CHECK supplements less formal, but more frequent, checks of channel status during normal operational use of the displays associated with the channels required by the LCO.

(continued)

BASES

SURVEILLANCE
REQUIREMENTS
(continued)

SR 3.3.2.2.2

A CHANNEL FUNCTIONAL TEST is performed on each required channel to ensure that the channel will perform the intended function. A successful test of the required contact(s) of a channel relay may be performed by the verification of the change of state of a single contact of the relay. This clarifies what is an acceptable CHANNEL FUNCTIONAL TEST of a relay. This is acceptable because all of the other required contacts of the relay are verified by other Technical Specifications and non-Technical Specifications tests at least once per refueling interval with applicable extensions. Any setpoint adjustment shall be consistent with the assumptions of the current plant specific setpoint methodology.

The Frequency of 92 days is based on reliability analysis (Ref. 2).

SR 3.3.2.2.3

CHANNEL CALIBRATION is a complete check of the instrument loop and the sensor. This test verifies the channel responds to the measured parameter within the necessary range and accuracy. CHANNEL CALIBRATION leaves the channel adjusted to account for instrument drifts between successive calibrations consistent with the plant specific setpoint methodology.

The Frequency is based upon the assumption of a 24 month calibration interval in the determination of the magnitude of equipment drift in the setpoint analysis.

SR 3.3.2.2.4

The LOGIC SYSTEM FUNCTIONAL TEST demonstrates the OPERABILITY of the required trip logic for a specific channel. The system functional test of the feedwater and main turbine stop valves and the motor-driven feedwater pump breaker is included as part of this Surveillance and overlaps the LOGIC SYSTEM FUNCTIONAL TEST to provide

(continued)

BASES

SURVEILLANCE
REQUIREMENTS

SR 3.3.2.2.4 (continued)

complete testing of the assumed safety function. Therefore, if a turbine stop valve or motor feedwater pump breaker is incapable of operating, the associated instrumentation would also be inoperable. The 24 month Frequency is based on the need to perform this Surveillance under the conditions that apply during a plant outage and the potential for an unplanned transient if the Surveillance were performed with the reactor at power. Operating experience has shown that these components usually pass the Surveillance when performed at the 24 month Frequency.

REFERENCES

1. UFSAR, Section 15.1.2A.
 2. GENE-770-06-1-A, "Bases for Changes to Surveillance Test Intervals and Allowed Out-Of-Service Times for Selected Instrumentation Technical Specifications," December 1992.
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B 3.3 INSTRUMENTATION

B 3.3.3.1 Post Accident Monitoring (PAM) Instrumentation

BASES

BACKGROUND The primary purpose of the PAM instrumentation is to display, in the control room, plant variables that provide information required by the control room operators during accident situations. This information provides the necessary support for the operator to take the manual actions for which no automatic control is provided and that are required for safety systems to accomplish their safety functions for Design Basis Events. The instruments that monitor these variables are designated as Type A, Category I, and non-Type A, Category I in accordance with Regulatory Guide 1.97 (Ref. 1).

The OPERABILITY of the accident monitoring instrumentation ensures that there is sufficient information available on selected plant parameters to monitor and assess plant status and behavior following an accident. This capability is consistent with the recommendations of Reference 1.

APPLICABLE SAFETY ANALYSES The PAM instrumentation LCO ensures the OPERABILITY of Regulatory Guide 1.97, Type A, variables so that the control room operating staff can:

- Perform the diagnosis specified in the Emergency Operating Procedures (EOP). These variables are restricted to preplanned actions for the primary success path of Design Basis Accidents (DBAs) (e.g., loss of coolant accident (LOCA)); and
- Take the specified, preplanned, manually controlled actions for which no automatic control is provided, which are required for safety systems to accomplish their safety function.

The PAM instrumentation LCO also ensures OPERABILITY of Category I, non-Type A, variables. This ensures the control room operating staff can:

- Determine whether systems important to safety are performing their intended functions;

(continued)

BASES

APPLICABLE
SAFETY ANALYSES
(continued)

- Determine the potential for causing a gross breach of the barriers to radioactivity release;
- Determine whether a gross breach of a barrier has occurred; and
- Initiate action necessary to protect the public and to obtain an estimate of the magnitude of any impending threat.

The plant specific Regulatory Guide 1.97 analysis (Ref. 2) documents the process that identified Type A and Category I, non-Type A, variables.

PAM instrumentation that meets the definition of Type A in Regulatory Guide 1.97 satisfies Criterion 3 of 10 CFR 50.36(c)(2)(ii). Category I, non-Type A, instrumentation is retained in the Technical Specifications (TS) because it is intended to assist operators in minimizing the consequences of accidents. Therefore, these Category I, non-Type A, variables are important for reducing public risk.

LCO

LCO 3.3.3.1 requires two OPERABLE channels for all but one Function to ensure no single failure prevents the operators from being presented with the information necessary to determine the status of the unit and to bring the unit to, and maintain it in, a safe condition following an accident. Furthermore, providing two channels allows a CHANNEL CHECK during the post accident phase to confirm the validity of displayed information.

The exception of the two channel requirement is primary containment isolation valve (PCIV) position. In this case, the important information is the status of the primary containment penetrations. The LCO requires one position indicator for each active (e.g., automatic) PCIV. This is sufficient to redundantly verify the isolation status of each isolable penetration either via indicated status of the active valve and prior knowledge of passive valve or via system boundary status. If a normally active PCIV is known to be closed and deactivated, position indication is not needed to determine status. Therefore, the position indication for closed and deactivated valves is not required to be OPERABLE.

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BASES

LCO
(continued)

Listed below is a discussion of the specified instrument Functions listed in Table 3.3.3.1-1.

1. Reactor Steam Dome Pressure

Reactor steam dome pressure is a Type A and Category I variable provided to support monitoring of Reactor Coolant System (RCS) integrity and to verify operation of the Emergency Core Cooling Systems (ECCS). Two independent pressure transmitters with a range of 0 psig to 1500 psig monitor pressure. Wide range recorders are the primary indication used by the operator during an accident. Therefore, the PAM Specification deals specifically with this portion of the instrument channel.

2. Reactor Vessel Water Level

Reactor vessel water level is a Category I variable provided to support monitoring of core cooling and to verify operation of the ECCS. The wide range and fuel zone range water level channels provide the PAM Reactor Vessel Water Level Function. The range of the recorded/indicated level is from the top of the feedwater control range (just above the high level turbine trip point) down to a point just below the bottom of the active fuel. Reactor vessel water level is measured by six independent differential pressure transmitters (i.e., four wide range channels and two fuel zone range channels). These channels provide output to recorders and indicators. Each division of the required reactor vessel water level channels must include a recorder. These instruments are the primary indication used by the operator during an accident. Therefore, the PAM Specification deals specifically with this portion of the instrument channel.

The reactor vessel water level instruments are uncompensated for variation in reactor water density and are calibrated to be most accurate at a specific vessel pressure and temperature. The wide range instruments are calibrated at 1000 psig reactor pressure with appropriate temperature compensation and no jet pump flow. The fuel zone range instruments are calibrated at saturated conditions at 0 psig with no jet pump flow.

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BASES

LCO
(continued)

3. Suppression Pool Water Level

Suppression pool water level is a Type A and Category I variable provided to detect a breach in the reactor coolant pressure boundary (RCPB). This variable is also used to verify and provide long term surveillance of ECCS function. The wide range suppression pool water level measurement provides the operator with sufficient information to assess the status of the RCPB and to assess the status of the water supply to the ECCS. The wide range water level indicators monitor the suppression pool level from 14 feet above normal level down to the lowest ECCS suction point. Two wide range suppression pool water level signals are transmitted from separate transmitters and are continuously displayed on two control room indicators, and separately recorded on two recorders in the control room. These instruments are the primary indication used by the operator during an accident. Therefore, the PAM Specification deals specifically with this portion of the instrument channel.

4. Drywell Pressure

Drywell pressure is a Type A and Category I variable provided to detect a breach of the RCPB and to verify ECCS functions that operate to maintain RCS integrity. There are four drywell pressure monitoring channels, two wide range channels and two narrow range channels. The combined range of these instruments is from -5 to 200 psig. The signals from the drywell pressure monitoring channels are continuously recorded and displayed on two control room recorders and the wide range channels are also displayed on indicators. These instruments are the primary indication used by the operator during an accident. Therefore, the PAM Specification deals specifically with this portion of the instrument channel.

5. Primary Containment Gross Gamma Radiation

Primary containment gross gamma radiation is a Category 1 variable provided to monitor for the potential of significant radiation releases and to provide release assessment for use by operators in determining the need to invoke site emergency plans.

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BASES

LCO

5. Primary Containment Gross Gamma Radiation (continued)

Two redundant radiation detectors are located inside the drywell that have a range of 10^0 R/hr to 10^8 R/hr. These radiation monitors display on recorders located in the control room. Two radiation monitors/recorders are required to be OPERABLE (one per division). Therefore, the PAM Specification deals specifically with this portion of the instrument channel.

6. Penetration Flow Path Primary Containment Isolation Valve (PCIV) Position

PCIV (excluding check valves, relief valves, manual valves, CRD solenoid valves, vacuum breakers, and excess flow check valves) position is a Category I variable provided for verification of containment integrity. In the case of PCIV position, the important information is the isolation status of the containment penetration. The LCO requires one channel of valve position indication in the control room to be OPERABLE for each active PCIV in a containment penetration flow path requiring post-accident valve position indication, i.e., two total channels of PCIV position indication for a penetration flow path with two active valves requiring post-accident valve position indication. For containment penetrations with only one active PCIV having control room indication, Note (b) requires a single channel of valve position indication to be OPERABLE. This is sufficient to verify redundantly the isolation status of each isolable penetration via indicated status of the active valve, as applicable, and prior knowledge of passive valve or system boundary status. If a penetration is isolated, position indication for the PCIV(s) in the associated penetration flow path is not needed to determine status. Therefore, the position indication for valves in an isolated penetration is not required to be OPERABLE. Each penetration is treated separately and each penetration flow path is considered a separate function. Therefore, separate Condition entry is allowed for each inoperable penetration flow path.

(continued)

BASES

LCO

6. Penetration Flow Path Primary Containment Isolation Valve (PCIV) Position (continued)

The indication for each PCIV is provided in the control room. Indicator lights illuminate to indicate PCIV position. Therefore, the PAM Specification deals specifically with this portion of the instrumentation channel.

7, 8. Drywell Hydrogen and Oxygen Concentration Analyzer

Drywell hydrogen and oxygen concentration analyzers are Category I instruments provided to detect high hydrogen or oxygen concentration conditions that represent a potential for containment breach. Additionally, hydrogen concentration is a Type A variable. This variable is also important in verifying the adequacy of mitigating actions.

High hydrogen and oxygen concentrations are each measured by two independent analyzers. Following receipt of a LOCA signal, the analyzers are initiated and continuously record hydrogen and oxygen concentration on two recorders in the control room. The analyzers are designed to operate under accident conditions. The available 0% to 10% range for the hydrogen analyzers and 0% to 20% range for the oxygen analyzers satisfy the intent of Regulatory Guide 1.97. These recorders are the primary indication used by the operator during an accident. Therefore, the PAM Specification deals specifically with this portion of the instrument channel.

9. Suppression Pool Water Temperature

Suppression pool water temperature is a Type A and Category I variable provided to detect a condition that could potentially lead to containment breach, and to verify the effectiveness of ECCS actions taken to prevent containment breach. The suppression pool water temperature instrumentation allows operators to detect trends in suppression pool water temperature in sufficient time to take action to prevent steam quenching vibrations in the suppression pool. There are 14 total thermocouple instrument wells in the suppression pool. Each thermocouple

(continued)

BASES

LCO

9. Suppression Pool Water Temperature (continued)

well has two thermocouples. Each channel receives input from the thermocouples in 7 wells for a total of 14 thermocouples. A channel is considered OPERABLE if it receives input from at least one OPERABLE thermocouple from each of the 7 wells. The thermocouples are distributed throughout the pool area so as to be able to redundantly detect a stuck open safety/relief valve continuous discharge into the pool.

The output for each channel of sensors is recorded on an independent recorder in the control room. These recorders are the primary indication used by the operator during an accident. Therefore, the PAM Specification deals specifically with this portion of the instrument channels.

APPLICABILITY

The PAM instrumentation LCO is applicable in MODES 1 and 2. These variables are related to the diagnosis and preplanned actions required to mitigate DBAs. The applicable DBAs are assumed to occur in MODES 1 and 2. In MODES 3, 4, and 5, plant conditions are such that the likelihood of an event that would require PAM instrumentation is extremely low; therefore, PAM instrumentation is not required to be OPERABLE in these MODES.

ACTIONS

Note 1 has been added to the ACTIONS to exclude the MODE change restriction of LCO 3.0.4. This exception allows entry into the applicable MODE while relying on the ACTIONS even though the ACTIONS may eventually require plant shutdown. This exception is acceptable due to the passive function of the instruments, the operator's ability to diagnose an accident using alternate instruments and methods, and the low probability of an event requiring these instruments.

A Note has also been provided to modify the ACTIONS related to PAM instrumentation channels. Section 1.3, Completion Times, specifies that once a Condition has been entered, subsequent divisions, subsystems, components, or variables expressed in the Condition, discovered to be inoperable or not within limits, will not result in separate entry into the Condition. Section 1.3 also specifies that Required

(continued)

BASES

ACTIONS
(continued)

Actions of the Condition continue to apply for each additional failure, with Completion Times based on initial entry into the Condition. However, the Required Actions for inoperable PAM instrumentation channels provide appropriate compensatory measures for separate inoperable functions. As such, a Note has been provided that allows separate Condition entry for each inoperable PAM Function.

A.1

When one or more Functions have one required channel that is inoperable, the required inoperable channel must be restored to OPERABLE status within 30 days. The 30 day Completion Time is based on operating experience and takes into account the remaining OPERABLE channel or remaining isolation barrier (in the case of primary containment penetrations with only one PCIV), the passive nature of the instrument (no critical automatic action is assumed to occur from these instruments), and the low probability of an event requiring PAM instrumentation during this interval.

B.1

If a channel has not been restored to OPERABLE status in 30 days, this Required Action specifies initiation of actions in accordance with Specification 5.6.6, which requires a written report to be submitted to the NRC. This report discusses the results of the root cause evaluation of the inoperability and identifies proposed restorative actions. This Required Action is appropriate in lieu of a shutdown requirement since another OPERABLE channel is monitoring the Function, an alternative method of monitoring is available and given the likelihood of plant conditions that would require information provided by this instrumentation.

C.1

When one or more Functions have two required channels that are inoperable (i.e., two channels inoperable in the same Function), one channel in the Function should be restored to OPERABLE status within 7 days. The Completion Time of

(continued)

BASES

ACTIONS

C.1 (continued)

7 days is based on the relatively low probability of an event requiring PAM instrument operation and the availability of alternate means to obtain the required information. Continuous operation with two required channels inoperable in a Function is not acceptable because the alternate indications may not fully meet all performance qualification requirements applied to the PAM instrumentation. Therefore, requiring restoration of one inoperable channel of the Function limits the risk that the PAM Function will be in a degraded condition should an accident occur.

D.1

This Required Action directs entry into the appropriate Condition referenced in Table 3.3.3.1-1. The applicable Condition referenced in the Table is Function dependent. Each time an inoperable channel has not met the Required Action of Condition C, and the associated Completion Time has expired, Condition D is entered for that channel and provides for transfer to the appropriate subsequent Condition.

E.1

For the majority of Functions in Table 3.3.3.1-1, if the Required Action and associated Completion Time of Condition C is not met, the plant must be placed in a MODE in which the LCO does not apply. This is done by placing the plant in at least MODE 3 within 12 hours. The allowed Completion Times are reasonable, based on operating experience, to reach the required plant condition from full power conditions in an orderly manner and without challenging plant systems.

F.1

Since alternate means of monitoring primary containment gross gamma radiation have been developed and tested, the Required Action is not to shut down the plant but rather to follow the directions of Specification 5.6.6. These

(continued)

BASES

ACTIONS

F.1 (continued)

alternate means may be temporarily installed if the normal PAM channel cannot be restored to OPERABLE status within the allotted time. The report provided to the NRC should discuss the alternate means used, describe the degree to which the alternate means are equivalent to the installed PAM channels, justify the areas in which they are not equivalent, and provide a schedule for restoring the normal PAM channels.

SURVEILLANCE
REQUIREMENTS

As noted at the beginning of the SRs, the following SRs apply to each PAM instrumentation Function in Table 3.3.3.1-1.

The Surveillances are modified by a second Note to indicate that when a channel is placed in an inoperable status solely for performance of required Surveillances, entry into associated Conditions and Required Actions may be delayed for up to 6 hours, provided the other required channel in the associated Function is OPERABLE. Upon completion of the Surveillance, or expiration of the 6 hour allowance, the channel must be returned to OPERABLE status or the applicable Condition entered and Required Actions taken. The 6 hour testing allowance is acceptable since it does not significantly reduce the probability of properly monitoring post-accident parameters, when necessary.

SR 3.3.3.1.1

Performance of the CHANNEL CHECK once every 31 days ensures that a gross instrumentation failure has not occurred. A CHANNEL CHECK is normally a comparison of the parameter indicated on one channel to a similar parameter on other channels. It is based on the assumption that instrument channels monitoring the same parameter should read approximately the same value. Significant deviations between instrument channels could be an indication of excessive instrument drift in one of the channels or of something even more serious. A CHANNEL CHECK will detect gross channel failure; thus, it is key to verifying the instrumentation continues to operate properly between each CHANNEL CALIBRATION.

(continued)

BASES

SURVEILLANCE
REQUIREMENTS

SR 3.3.3.1.1 (continued)

Agreement criteria are determined by the plant staff based on a combination of the channel instrument uncertainties, including indication and readability. If a channel is outside the criteria, it may be an indication that the sensor or the signal processing equipment has drifted outside its limit.

The Frequency of 31 days is based upon plant operating experience with regard to channel OPERABILITY and drift, which demonstrates that failure of more than one channel of a given function in any 31 day interval is rare. The CHANNEL CHECK supplements less formal, but more frequent, checks of channels during normal operational use of those displays associated with the channels required by the LCO.

SR 3.3.3.1.2 and SR 3.3.3.1.3

A CHANNEL CALIBRATION is performed every 92 days for Functions 7 and 8 and every 24 months for all other functions. For Function 6, the CHANNEL CALIBRATION shall consist of verifying that the position indication conforms to the actual valve position. CHANNEL CALIBRATION is a complete check of the instrument loop including the sensor. The test verifies that the channel responds to the measured parameter with the necessary range and accuracy. The 92 day Frequency for CHANNEL CALIBRATION of Functions 7 and 8 is based on operating experience. The 24 month Frequency for CHANNEL CALIBRATION of all other PAM Instrumentation of Table 3.3.3.1-1 is based on operating experience and consistency with the refueling cycles.

REFERENCES

1. Regulatory Guide 1.97, "Instrumentation for Light-Water Cooled Nuclear Power Plants to Assess Plant and Environs Conditions During and Following an Accident," Revision 2, December 1980.
 2. NRC Safety Evaluation Report, "Commonwealth Edison Company, LaSalle County Station, Unit Nos. 1 and 2, Conformance to Regulatory Guide 1.97," dated August 20, 1987.
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B 3.3 INSTRUMENTATION

B 3.3.3.2 Remote Shutdown Monitoring System

BASES

BACKGROUND

The Remote Shutdown Monitoring System provides the control room operator with sufficient instrumentation to support maintaining the plant in a safe shutdown condition from a location other than the control room. This capability is necessary to protect against the possibility of the control room becoming inaccessible. A safe shutdown condition is defined as MODE 3. With the plant in MODE 3, the Reactor Core Isolation Cooling (RCIC) System, the safety/relief valves, and the Residual Heat Removal (RHR) System can be used to remove core decay heat and meet all safety requirements. The long term supply of water for the RCIC System and the ability to operate shutdown cooling from outside the control room allow extended operation in MODE 3.

In the event that the control room becomes inaccessible, the operators can monitor the status of the reactor and the suppression pool and the operation of the RHR and RCIC Systems at the remote shutdown panel and support maintaining the plant in MODE 3. The plant is in MODE 3 following a plant shutdown and can be maintained safely in MODE 3 for an extended period of time.

The OPERABILITY of the Remote Shutdown Monitoring System instrumentation Functions ensures that there is sufficient information available on selected plant parameters to support maintaining the plant in MODE 3 should the control room become inaccessible.

APPLICABLE SAFETY ANALYSES

The Remote Shutdown Monitoring System is required to provide instrumentation at appropriate locations outside the control room with a design capability to support maintaining the plant in a safe condition in MODE 3.

The criteria governing the design and the specific system requirements of the Remote Shutdown Monitoring System are located in UFSAR, Section 7.4.4 (Ref. 1).

The Remote Shutdown Monitoring System is considered an important contributor to reducing the risk of accidents; as such, it meets Criterion 4 of 10 CFR 50.36(c)(2)(ii).

(continued)

BASES (continued)

LCO The Remote Shutdown Monitoring System LCO provides the requirements for the OPERABILITY of the instrumentation necessary to support maintaining the plant in MODE 3 from a location other than the control room. The instrumentation Functions required are listed in the Technical Requirements Manual (Ref. 2).

The instrumentation is that required for:

- Reactor pressure vessel (RPV) pressure control;
- Decay heat removal; and
- RPV inventory control.

The Remote Shutdown Monitoring System is OPERABLE if all instrument channels needed to support the remote shutdown monitoring functions are OPERABLE with readouts displayed in the remote shutdown panel external to the control room.

The Remote Shutdown Monitoring System instruments covered by this LCO do not need to be energized to be considered OPERABLE. This LCO is intended to ensure that the instruments will be OPERABLE if plant conditions require that the Remote Shutdown Monitoring System be placed in operation.

APPLICABILITY The Remote Shutdown Monitoring System LCO is applicable in MODES 1 and 2. This is required so that the plant can be maintained in MODE 3 for an extended period of time from a location other than the control room.

This LCO is not applicable in MODES 3, 4, and 5. In these MODES, the plant is already subcritical and in a condition of reduced Reactor Coolant System energy. Under these conditions, considerable time is available to restore necessary instrument Functions if control room instruments become unavailable. Consequently, the LCO does not require OPERABILITY in MODES 3, 4, and 5.

(continued)

BASES (continued)

ACTIONS A Note is included that excludes the MODE change restriction of LCO 3.0.4. This exception allows entry into an applicable MODE while relying on the ACTIONS even though the ACTIONS may eventually require a plant shutdown. This exception is acceptable due to the low probability of an event requiring this system.

The Remote Shutdown Monitoring System is inoperable when each required function is not accomplished by at least one designated Remote Shutdown Monitoring System channel that satisfies the OPERABILITY criteria for the channel's Function. These criteria are outlined in the LCO section of the Bases.

Note 2 has been provided to modify the ACTIONS related to Remote Shutdown Monitoring System Functions. Section 1.3, Completion Times, specifies that once a Condition has been entered, subsequent divisions, subsystems, components, or variables expressed in the Condition, discovered to be inoperable or not within limits, will not result in separate entry into the Condition. Section 1.3 also specifies that Required Actions of the Condition continue to apply for each additional failure, with Completion Times based on initial entry into the Condition. However, the Required Actions for inoperable Remote Shutdown Monitoring System Functions provide appropriate compensatory measures for separate Functions.

As such, a Note has been provided that allows separate Condition entry for each inoperable Remote Shutdown Monitoring System Function.

A.1

Condition A addresses the situation where one or more required Functions of the Remote Shutdown Monitoring System is inoperable. This includes any required Function listed in Reference 2.

The Required Action is to restore the Function to OPERABLE status within 30 days. The Completion Time is based on operating experience and the low probability of an event that would require evacuation of the control room.

(continued)

BASES

ACTIONS
(continued)

B.1

If the Required Action and associated Completion Time of Condition A are not met, the plant must be brought to a MODE in which the LCO does not apply. To achieve this status, the plant must be brought to at least MODE 3 within 12 hours. The allowed Completion Time is reasonable, based on operating experience, to reach the required MODE from full power conditions in an orderly manner and without challenging plant systems.

SURVEILLANCE
REQUIREMENTS

The Surveillances are modified by a Note to indicate that when a channel is placed in an inoperable status solely for performance of required Surveillances, entry into associated Conditions and Required Actions may be delayed for up to 6 hours. Upon completion of the Surveillance, or expiration of the 6 hour allowance, the channel must be returned to OPERABLE status or the applicable Condition entered and Required Actions taken. The 6 hour testing allowance is acceptable since it does not significantly reduce the probability of properly monitoring remote shutdown parameters, when necessary.

SR 3.3.3.2.1

Performance of the CHANNEL CHECK once every 31 days ensures that a gross failure of instrumentation has not occurred. A CHANNEL CHECK is normally a comparison of the parameter indicated on one channel to a similar parameter on other channels. It is based on the assumption that instrument channels monitoring the same parameter should read approximately the same value. Significant deviations between the instrument channels could be an indication of excessive instrument drift in one of the channels or something even more serious. A CHANNEL CHECK will detect gross channel failure; thus, it is key to verifying the instrumentation continues to operate properly between each CHANNEL CALIBRATION.

(continued)

BASES

SURVEILLANCE
REQUIREMENTS

SR 3.3.3.2.1 (continued)

Agreement criteria are determined by the plant staff based on a combination of the channel instrument uncertainties, including indication and readability. If a channel is outside the criteria, it may be an indication that the sensor or the signal processing equipment has drifted outside its limit. As specified in the Surveillance, a CHANNEL CHECK is only required for those channels that are normally energized.

The Frequency is based upon operating experience that demonstrates channel failure is rare.

SR 3.3.3.2.2

CHANNEL CALIBRATION is a complete check of the instrument loop and the sensor. The test verifies the channel responds to measured parameter values with the necessary range and accuracy.

The 24 month Frequency is based upon operating experience and engineering judgement and is consistent with the refueling cycle.

REFERENCES

1. UFSAR, Section 7.4.4.
 2. Technical Requirements Manual.
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B 3.3 INSTRUMENTATION

B 3.3.4.1 End of Cycle Recirculation Pump Trip (EOC-RPT) Instrumentation

BASES

BACKGROUND

The EOC-RPT instrumentation initiates a recirculation pump trip (RPT), if operating in fast speed, to reduce the peak reactor pressure and power resulting from turbine trip or generator load rejection transients to provide additional margin to the MCPR Safety Limit (SL).

The need for the additional negative reactivity in excess of that normally inserted on a scram reflects end of cycle reactivity considerations. Flux shapes at the end of cycle are such that the control rods may not be able to ensure that thermal limits are maintained by inserting sufficient negative reactivity during the first few feet of rod travel upon a scram caused by Turbine Control Valve (TCV)–Fast Closure, Trip Oil Pressure–Low, or Turbine Stop Valve (TSV)–Closure. The physical phenomenon involved is that the void reactivity feedback due to a pressurization transient can add positive reactivity at a faster rate than the control rods can add negative reactivity.

The EOC-RPT instrumentation as shown in Reference 1 is comprised of sensors that detect initiation of closure of the TSVs, or fast closure of the TCVs, combined with relays and logic circuits, to actuate reactor recirculation pump downshift logic to trip each pump from fast speed (60 Hz). The channels include instrument switches that actuate pre-established setpoints. When the setpoint is exceeded, the switch actuates, which then outputs an EOC-RPT signal to the trip logic to downshift the pumps. When the EOC-RPT breakers (3A, 3B, 4A, and 4B; the fast speed breakers) trip open, the recirculation pumps coast down under their own inertia, breakers 1A and 1B close to start the LFMG, and the low frequency breakers 2A and 2B close automatically on a motor speed interlock to operate the recirculation pumps on low speed (although the recirculation pump start in low speed is not part of the EOC-RPT Instrumentation safety function). The EOC-RPT has two identical trip systems, either of which can actuate an RPT.

(continued)

BASES

BACKGROUND
(continued)

Each EOC-RPT trip system is a two-out-of-two logic for each Function; thus, either two TSV-Closure or two TCV-Fast Closure, Trip Oil Pressure-Low signals are required for a trip system to actuate. If either trip system actuates, both recirculation pumps, if operating in fast speed, will trip. There are two EOC-RPT breakers in series per recirculation pump. One trip system trips one of the two EOC-RPT breakers for each recirculation pump and the second trip system trips the other EOC-RPT breaker for each recirculation pump.

APPLICABLE
SAFETY ANALYSES,
LCO, and
APPLICABILITY

The TSV-Closure and the TCV-Fast Closure, Trip Oil Pressure-Low Functions are designed to trip the recirculation pumps, if operating in fast speed, in the event of a turbine trip or generator load rejection to mitigate the neutron flux, heat flux and pressurization transients, and to increase the margin to the MCPR SL. The analytical methods and assumptions used in evaluating the turbine trip and generator load rejection, as well as other safety analyses that assume EOC-RPT, are summarized in References 2, 3, and 4.

To mitigate pressurization transient effects, the EOC-RPT must trip the recirculation pumps, if operating in fast speed, after initiation of initial closure movement of either the TSVs or the TCVs. The combined effects of this trip and a scram reduce fuel bundle power more rapidly than does a scram alone, resulting in an increased margin to the MCPR SL. Alternatively, MCPR limits for an inoperable EOC-RPT as specified in the COLR are sufficient to mitigate pressurization transient effects. The EOC-RPT function is automatically disabled when THERMAL POWER as sensed by turbine first stage pressure is < 25% RTP.

EOC-RPT instrumentation satisfies Criterion 3 of 10 CFR 50.36(c)(2)(ii).

The OPERABILITY of the EOC-RPT is dependent on the OPERABILITY of the individual instrumentation channel Functions. Each Function must have a required number of OPERABLE channels in each trip system, with their setpoints within the specified Allowable Value of SR 3.3.4.1.2. The actual setpoint is calibrated consistent with applicable

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BASES

APPLICABLE
SAFETY ANALYSES,
LCO, and
APPLICABILITY
(continued)

setpoint methodology assumptions. Channel OPERABILITY also includes the associated EOC-RPT breakers. Each channel (including the associated EOC-RPT breakers) must also respond within its assumed response time.

Allowable Values are specified for each EOC-RPT Function specified in the LCO. Nominal trip setpoints are specified in the setpoint calculations. The nominal setpoints are selected to ensure the setpoints do not exceed the Allowable Value between successive CHANNEL CALIBRATIONS. Operation with a trip setpoint less conservative than the nominal trip setpoint, but within its Allowable Value, is acceptable. A channel is inoperable if its actual trip setpoint is not within its required Allowable Value. Trip setpoints are those predetermined values of output at which an action should take place. The setpoints are compared to the actual process parameter (e.g., TCV electrohydraulic control (EHC) pressure), and when the measured output value of the process parameter exceeds the setpoint, the associated device (e.g., trip switches) change state. The analytic limits are derived from the limiting values of the process parameters obtained from the safety analysis. The trip setpoints are determined from the analytic limits, corrected for defined process, calibration, and instrument errors. The Allowable Values are then determined, based on the trip setpoint values, by accounting for the calibration based errors. These calibration based errors are limited to reference accuracy, instrument drift, errors associated with measurement and test equipment, and calibration tolerance of loop components. The trip setpoints and Allowable Values determined in this manner provide adequate protection because instrument uncertainties, process effects, calibration tolerances, instrument drift, and severe environment errors (for channels that must function in harsh environments as defined by 10 CFR 50.49) are accounted for and appropriately applied for the instrumentation.

The specific Applicable Safety Analysis, LCO, and Applicability discussions are listed below on a Function by Function basis.

(continued)

BASES

APPLICABLE
SAFETY ANALYSES,
LCO, and
APPLICABILITY
(continued)

Alternately, since this instrumentation protects against a MCPR SL violation with the instrumentation inoperable, modifications to the MCPR limits (LCO 3.2.2) may be applied to allow this LCO to be met. The MCPR limit for the condition EOC-RPT inoperable is specified in the COLR.

Turbine Stop Valve-Closure

Closure of the TSVs and a main turbine trip result in the loss of a heat sink that produces reactor pressure, neutron flux, and heat flux transients that must be limited. Therefore, an RPT is initiated on TSV-Closure, in anticipation of the transients that would result from closure of these valves. EOC-RPT decreases reactor power and aids the reactor scram in ensuring the MCPR SL is not exceeded during the worst case transient.

Closure of the TSVs is determined by monitoring the position of each stop valve. There is one valve stem position switch associated with each stop valve, and the signal from each switch is assigned to a separate trip channel. The logic for the TSV-Closure Function is such that two or more TSVs must be closed to produce an EOC-RPT. This Function must be enabled at THERMAL POWER \geq 25% RTP. This is normally accomplished automatically by pressure switches sensing turbine first stage pressure; therefore, opening of the turbine bypass valves may affect the OPERABILITY of this Function. Four channels of TSV-Closure, with two channels in each trip system, are available and required to be OPERABLE to ensure that no single instrument failure will preclude an EOC-RPT from this Function on a valid signal. The TSV-Closure Allowable Value is selected to detect imminent TSV closure.

This protection is required, consistent with the safety analysis assumptions, whenever THERMAL POWER is \geq 25% RTP with any recirculating pump in fast speed. Below 25% RTP or with the recirculation in slow speed, the Reactor Vessel Steam Dome Pressure-High and the Average Power Range Monitor (APRM) Fixed Neutron Flux-High Functions of the Reactor Protection System (RPS) are adequate to maintain the necessary safety margins.

(continued)

BASES

APPLICABLE
SAFETY ANALYSES,
LCO, and
APPLICABILITY
(continued)

TCV - Fast Closure, Trip Oil Pressure - Low

Fast closure of the TCVs during a generator load rejection results in the loss of a heat sink that produces reactor pressure, neutron flux, and heat flux transients that must be limited. Therefore, an RPT is initiated on TCV - Fast Closure, Trip Oil Pressure - Low in anticipation of the transients that would result from the closure of these valves. The EOC-RPT decreases reactor power and aids the reactor scram in ensuring that the MCPR SL is not exceeded during the worst case transient.

Fast closure of the TCVs is determined by measuring the EHC fluid pressure at each control valve. There is one pressure switch associated with each control valve, and the signal from each switch is assigned to a separate trip channel. The logic for the TCV - Fast Closure, Trip Oil Pressure - Low Function is such that two or more TCVs must be closed (pressure switch trips) to produce an EOC-RPT. This Function must be enabled at THERMAL POWER \geq 25% RTP. This is normally accomplished automatically by pressure switches sensing turbine first stage pressure; therefore, opening of the turbine bypass valves may affect the OPERABILITY of this Function. Four channels of TCV - Fast Closure, Trip Oil Pressure - Low with two channels in each trip system, are available and required to be OPERABLE to ensure that no single instrument failure will preclude an EOC-RPT from this Function on a valid signal. The TCV - Fast Closure, Trip Oil Pressure - Low Allowable Value is selected high enough to detect imminent TCV fast closure.

This protection is required consistent with the analysis, whenever the THERMAL POWER is \geq 25% RTP with any recirculating pump in fast speed. Below 25% RTP or with recirculation pumps in slow speed, the Reactor Vessel Steam Dome Pressure - High and the APRM Fixed Neutron Flux - High Functions of the RPS are adequate to maintain the necessary safety margins. The turbine first stage pressure/reactor power relationship for the setpoint of the automatic enable is identical to that described for TSV closure.

(continued)

BASES (continued)

ACTIONS

A Note has been provided to modify the ACTIONS related to EOC-RPT instrumentation channels. Section 1.3, Completion Times, specifies that once a Condition has been entered, subsequent divisions, subsystems, components, or variables expressed in the Condition, discovered to be inoperable or not within limits, will not result in separate entry into the Condition. Section 1.3 also specifies that Required Actions of the Condition continue to apply for each additional failure, with Completion Times based on initial entry into the Condition. However, the Required Actions for inoperable EOC-RPT instrumentation channels provide appropriate compensatory measures for separate inoperable channels. As such, a Note has been provided that allows separate Condition entry for each inoperable EOC-RPT instrumentation channel.

A.1 and A.2

With one or more required channels inoperable, but with EOC-RPT trip capability maintained (refer to Required Action B.1 and B.2 Bases), the EOC-RPT System is capable of performing the intended function. However, the reliability and redundancy of the EOC-RPT instrumentation is reduced such that a single failure in the remaining trip system could result in the inability of the EOC-RPT System to perform the intended function. Therefore, only a limited time is allowed to restore compliance with the LCO. Because of the diversity of sensors available to provide trip signals, the low probability of extensive numbers of inoperabilities affecting all diverse Functions, and the low probability of an event requiring the initiation of an EOC-RPT, 72 hours is allowed to restore the inoperable channels (Required Action A.1) or apply the EOC-RPT inoperable MCPR limit. Alternately, the inoperable channels may be placed in trip (Required Action A.2) since this would conservatively compensate for the inoperability, restore capability to accommodate a single failure, and allow operation to continue. As noted in Required Action A.2, placing the channel in trip with no further restrictions is not allowed if the inoperable channel is the result of an inoperable breaker, since this may not adequately compensate for the inoperable breaker (e.g., the breaker may be

(continued)

BASES

ACTIONS

A.1 and A.2 (continued)

inoperable such that it will not open). If it is not desired to place the channel in trip (e.g., as in the case where placing the inoperable channel in trip would result in an RPT), or if the inoperable channel is the result of an inoperable breaker, Condition C must be entered and its Required Actions taken.

B.1 and B.2

Required Actions B.1 and B.2 are intended to ensure that appropriate actions are taken if multiple, inoperable, untripped channels within the same Function result in the Function not maintaining EOC-RPT trip capability. A Function is considered to be maintaining EOC-RPT trip capability when sufficient channels are OPERABLE or in trip, such that the EOC-RPT System will generate a trip signal from the given Function on a valid signal and both recirculation pumps, if operating in fast speed, can be tripped. This requires two channels of the Function, in the same trip system, to each be OPERABLE or in trip, and the associated EOC-RPT breakers to be OPERABLE or in trip. Alternatively, Required Action B.2 requires the MCPR limit for inoperable EOC-RPT, as specified in the COLR, to be applied. This also restores the margin to MCPR assumed in the safety analysis.

The 2 hour Completion Time is sufficient for the operator to take corrective action, and takes into account the likelihood of an event requiring actuation of the EOC-RPT instrumentation during this period. It is also consistent with the 2 hour Completion Time provided in LCO 3.2.2, Required Action A.1, since this instrumentation's purpose is to preclude a MCPR violation.

C.1 and C.2

With any Required Action and associated Completion Time not met, THERMAL POWER must be reduced to < 25% RTP within 4 hours. Alternately, the associated recirculation pump fast speed breaker may be removed from service since this performs the intended function of the instrumentation. The

(continued)

BASES

ACTIONS C.1 and C.2 (continued)

allowed Completion Time of 4 hours is reasonable, based on operating experience, to reduce THERMAL POWER to < 25% RTP from full power conditions in an orderly manner and without challenging plant systems.

SURVEILLANCE
REQUIREMENTS

The Surveillances are modified by a Note to indicate that when a channel is placed in an inoperable status solely for performance of required Surveillances, entry into associated Conditions and Required Actions may be delayed for up to 6 hours, provided the associated Function maintains EOC-RPT trip capability. Upon completion of the Surveillance, or expiration of the 6 hour allowance, the channel must be returned to OPERABLE status or the applicable Condition entered and Required Actions taken. This Note is based on the reliability analysis (Ref. 5) assumption of the average time required to perform channel surveillance. That analysis demonstrated that the 6 hour testing allowance does not significantly reduce the probability that the recirculation pumps will trip when necessary.

SR 3.3.4.1.1

A CHANNEL FUNCTIONAL TEST is performed on each required channel to ensure that the channel will perform the intended function. A successful test of the required contact(s) of a channel relay may be performed by the verification of the change of state of a single contact of the relay. This clarifies what is an acceptable CHANNEL FUNCTIONAL TEST of a relay. This is acceptable because all of the other required contacts of the relay are verified by other Technical Specifications and non-Technical Specifications tests at least once per refueling interval with applicable extensions. Any setpoint adjustment shall be consistent with the assumptions of the current plant specific setpoint methodology.

The Frequency of 92 days is based on reliability analysis (Ref. 5).

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BASES

SURVEILLANCE
REQUIREMENTS
(continued)

SR 3.3.4.1.2

CHANNEL CALIBRATION is a complete check of the instrument loop and the sensor. This test verifies the channel responds to the measured parameter within the necessary range and accuracy. CHANNEL CALIBRATION leaves the channel adjusted to account for instrument drifts between successive calibrations consistent with the plant specific setpoint methodology.

The Frequency is based upon the assumption of a 24 month calibration interval, in the determination of the magnitude of equipment drift in the setpoint analysis.

SR 3.3.4.1.3

The LOGIC SYSTEM FUNCTIONAL TEST demonstrates the OPERABILITY of the required trip logic for a specific channel. The system functional test of the pump breakers is included as a part of this test, overlapping the LOGIC SYSTEM FUNCTIONAL TEST, to provide complete testing of the associated safety function. Therefore, if a breaker is incapable of operating, the associated instrument channel would also be inoperable.

The 24 month Frequency is based on the need to perform this Surveillance under the conditions that apply during a plant outage and the potential for an unplanned transient if the Surveillance were performed with the reactor at power. Operating experience has shown these components usually pass the Surveillance test when performed at the 24 month Frequency.

SR 3.3.4.1.4

This SR ensures that an EOC-RPT initiated from the TSV - Closure and TCV - Fast Closure, Trip Oil Pressure - Low Functions will not be inadvertently bypassed when THERMAL POWER is \geq 25% RTP. This involves calibration of the bypass channels. Adequate margins for the instrument setpoint methodologies are incorporated into the actual setpoint. Because main turbine bypass flow can affect this setpoint

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BASES

SURVEILLANCE
REQUIREMENTS

SR 3.3.4.1.4 (continued)

nonconservatively (THERMAL POWER is derived from first stage pressure), the main turbine bypass valves must remain closed during an in-service calibration at THERMAL POWER \geq 25% RTP, if performing the calibration using actual turbine first stage pressure, to ensure that the calibration remains valid. If any bypass channel's setpoint is nonconservative (i.e., the Functions are bypassed at \geq 25% RTP either due to open main turbine bypass valves or other reasons), the affected TSV-Closure and TCV-Fast Closure, Trip Oil Pressure-Low Functions are considered inoperable. Alternatively, the bypass channel can be placed in the conservative condition (nonbypass). If placed in the nonbypass condition, this SR is met and the channel considered OPERABLE.

The Frequency of 24 months is based on engineering judgement and reliability of the components.

SR 3.3.4.1.5

This SR ensures that the individual channel response times are less than or equal to the maximum values assumed in the accident analysis. The EOC-RPT SYSTEM RESPONSE TIME acceptance criteria are included in Reference 6.

EOC-RPT SYSTEM RESPONSE TIME may be verified by actual response time measurements in any series of sequential, overlapping, or total channel measurements. However, the response time of the limit switches for the TSV-Closure Function may be assumed to be the design limit switch response time and therefore, is excluded from the EOC-RPT SYSTEM RESPONSE TIME testing. This is allowed, as documented in Reference 7, since the actual measurement of the limit switch response time is not practicable as this test is done during the refueling outage when the turbine stop valves are fully closed, and thus the limit switch in the circuitry is open. The design limit switch response time is 10 ms.

(continued)

BASES

SURVEILLANCE
REQUIREMENTS

SR 3.3.4.1.5 (continued)

A Note to the Surveillance states that breaker arc suppression time may be assumed from the most recent performance of SR 3.3.4.1.6. This is allowed since the arc suppression time is short and does not appreciably change, due to the design of the breaker opening device and the fact that the breaker is not routinely cycled.

EOC-RPT SYSTEM RESPONSE TIME tests are conducted on a 24 month STAGGERED TEST BASIS. The STAGGERED TEST BASIS is conducted on a function basis such that each test includes at least the logic of one type of channel input, i.e., TCV-Fast Closure, Trip Oil Pressure-Low, or TSV-Closure, such that both types of channel inputs are tested at least once per 48 months. Response times cannot be determined at power because operation of final actuated devices is required. Therefore, the 24 month Frequency is consistent with the refueling cycle and is based upon plant operating experience, which shows that random failures of instrumentation components that cause serious response time degradation, but not channel failure, are infrequent occurrences.

SR 3.3.4.1.6

This SR ensures that the EOC-RPT breaker arc suppression time is provided to the EOC-RPT SYSTEM RESPONSE TIME test. The 60 month Frequency of the testing is based on the difficulty of performing the test and the reliability of the circuit breakers.

REFERENCES

1. UFSAR, Figure G.3.3-2.
2. UFSAR, Sections 7.6.4, G.3.3.3.8.2, and G.5.1.
3. UFSAR, Sections 15.1.2A, 15.2.2A, 15.2.3, and 15.3A.
4. UFSAR, Section 7.6.4.2.1.

(continued)

BASES

REFERENCES
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5. GENE-770-06-1-A, "Bases for Changes To Surveillance Test Intervals And Allowed Out-Of-Service Times For Selected Instrumentation Technical Specifications," December 1992.
 6. Technical Requirements Manual.
 7. Letter, W.G. Guldemon (NRC) to C. Reed (ComEd), dated January 28, 1987.
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B 3.3 INSTRUMENTATION

B 3.3.4.2 Anticipated Transient Without Scram Recirculation Pump Trip (ATWS-RPT) Instrumentation

BASES

BACKGROUND

The ATWS-RPT System initiates a recirculation pump trip, adding negative reactivity, following events in which a scram does not but should occur, to lessen the effects of an ATWS event. Tripping the recirculation pumps adds negative reactivity from the increase in steam voiding in the core area as core flow decreases. When Reactor Vessel Water Level—Low Low, Level 2 or Reactor Steam Dome Pressure—High setpoint is reached, the recirculation pump motor breakers trip.

The ATWS-RPT System (Ref. 1) includes sensors, relays, bypass capability, circuit breakers, and switches that are necessary to cause initiation of a recirculation pump trip. The channels include electronic equipment (e.g., trip units) that compares measured input signals with pre-established setpoints. When the setpoint is exceeded, the channel then outputs an ATWS-RPT signal to the trip logic.

The ATWS-RPT consists of two independent trip systems, with two channels of Reactor Steam Dome Pressure—High and two channels of Reactor Vessel Water Level—Low Low, Level 2, in each trip system. Each ATWS-RPT trip system is a two-out-of-two logic for each Function. Thus, either two Reactor Water Level—Low Low, Level 2 or two Reactor Pressure—High signals will trip a trip system. The outputs of the channels in a trip system are combined in a logic so that either trip system will trip both recirculation pumps (by tripping the respective fast speed and low frequency motor generator (LFMG) motor breakers).

There are two fast speed motor breakers and one LFMG output breaker provided for each of the two recirculation pumps for a total of six breakers. The output of each trip system is provided to one fast speed motor breaker (3A, 3B) and the LFMG output breaker (2A, 2B) for each pump.

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BASES (continued)

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APPLICABILITY

The ATWS-RPT is not assumed to mitigate any accident or transient in the safety analysis. The ATWS-RPT initiates an RPT to aid in preserving the integrity of the fuel cladding following events in which scram does not, but should, occur. Based on its contribution to the reduction of overall plant risk, however, the instrumentation meets Criterion 4 of 10 CFR 50.36(c)(2)(ii).

The OPERABILITY of the ATWS-RPT is dependent on the OPERABILITY of the individual instrumentation channel Functions. Each Function must have a required number of OPERABLE channels in each trip system, with their setpoints within the specified Allowable Value of SR 3.3.4.2.3. The actual setpoint is calibrated consistent with applicable setpoint methodology assumptions. Channel OPERABILITY also includes the associated recirculation pump fast speed and LFMG breakers.

Allowable Values are specified for each ATWS-RPT Function specified in the LCO. Nominal trip setpoints are specified in the setpoint calculations. The nominal setpoints are selected to ensure the setpoints do not exceed the Allowable Value between CHANNEL CALIBRATIONS. Operation with a trip setpoint less conservative than the nominal trip setpoint, but within its Allowable Value, is acceptable. A channel is inoperable if its actual trip setpoint is not within its required Allowable Value. Trip setpoints are those predetermined values of output at which an action should take place. The setpoints are compared to the actual process parameter (e.g., reactor vessel water level), and when the measured output value of the process parameter exceeds the setpoint, the associated device (e.g., trip unit) changes state. The analytic limits are derived from the limiting values of the process parameters obtained from the ATWS analysis. The trip setpoints are determined from the analytic limits, corrected for defined process, calibration, and instrument errors. The Allowable Values are then determined, based on the trip setpoint values, by accounting for the calibration based errors. These calibration based errors are limited to reference accuracy, instrument drift, errors associated with measurement and test equipment, and calibration tolerance of loop components. The trip setpoints and Allowable Values determined in this manner provide adequate protection

(continued)

BASES

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(continued)

because instrument uncertainties, process effects, calibration tolerances, instrument drift, and severe environment errors (for channels that must function in harsh environments as defined by 10 CFR 50.49) are accounted for and appropriately applied for the instrumentation.

The individual Functions are required to be OPERABLE in MODE 1 to protect against common mode failures of the Reactor Protection System by providing a diverse trip to mitigate the consequences of a postulated ATWS event. The Reactor Steam Dome Pressure-High and Reactor Vessel Water Level-Low Low, Level 2 Functions are required to be OPERABLE in MODE 1, since the reactor is producing significant power and the recirculation system could be at high flow. During this MODE, the potential exists for pressure increases or low water level, assuming an ATWS event. In MODE 2, the reactor is at low power and the recirculation system is at low flow; thus, the potential is low for a pressure increase or low water level, assuming an ATWS event. Therefore, the ATWS-RPT is not necessary. In MODES 3 and 4, the reactor is shut down with all control rods inserted; thus, an ATWS event is not significant and the possibility of a significant pressure increase or low water level is negligible. In MODE 5, the one-rod-out interlock ensures the reactor remains subcritical; thus, an ATWS event is not significant. In addition, the reactor pressure vessel (RPV) head is not fully tensioned and no pressure transient threat to the reactor coolant pressure boundary (RCPB) exists.

The specific Applicable Safety Analyses and LCO discussions are listed below on a Function by Function basis.

a. Reactor Vessel Water Level-Low Low, Level 2

Low RPV water level indicates the capability to cool the fuel may be threatened. Should RPV water level decrease too far, fuel damage could result. Therefore, the ATWS-RPT System is initiated at Level 2 to aid in maintaining level above the top of the active fuel. The reduction of core flow reduces the neutron flux and THERMAL POWER and, therefore, the rate of coolant boiloff.

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a. Reactor Vessel Water Level - Low Low, Level 2
(continued)

Reactor vessel water level signals are initiated from four level transmitters that sense the difference between the pressure due to a constant column of water (reference leg) and the pressure due to the actual water level (variable leg) in the vessel.

Four channels of Reactor Vessel Level - Low Low, Level 2, with two channels in each trip system, are available and required to be OPERABLE to ensure that no single instrument failure can preclude an ATWS-RPT from this Function on a valid signal. The Reactor Vessel Water Level - Low Low, Level 2, Allowable Value is chosen so that the system will not initiate after a Level 3 scram with feedwater still available.

b. Reactor Steam Dome Pressure - High

Excessively high RPV pressure may rupture the RCPB. An increase in the RPV pressure during reactor operation compresses the steam voids and results in a positive reactivity insertion. This increases neutron flux and THERMAL POWER, which could potentially result in fuel failure and RPV overpressurization. The Reactor Steam Dome Pressure - High Function initiates an RPT for transients that result in a pressure increase, counteracting the pressure increase by rapidly reducing core power generation. For the overpressurization event, the RPT aids in the mitigation of the ATWS event and, along with the safety/relief valves (S/RVs), limits the peak RPV pressure to less than the ASME Section III Code Service Level C limits (1500 psig).

The Reactor Steam Dome Pressure - High signals are initiated from four pressure transmitters that monitor reactor steam dome pressure. Four channels of Reactor Steam Dome Pressure - High, with two channels in each trip system, are available and required to be OPERABLE to ensure that no single instrument failure can preclude an ATWS-RPT from this Function on a valid signal. The Reactor Steam Dome Pressure - High Allowable Value is chosen to provide an adequate margin to the ASME Section III Code Service Level C allowable Reactor Coolant System pressure.

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BASES (continued)

ACTIONS

A Note has been provided to modify the ACTIONS related to ATWS-RPT instrumentation channels. Section 1.3, Completion Times, specifies that once a Condition has been entered, subsequent divisions, subsystems, components, or variables expressed in the Condition, discovered to be inoperable or not within limits, will not result in separate entry into the Condition. Section 1.3 also specifies that Required Actions of the Condition continue to apply for each additional failure, with Completion Times based on initial entry into the Condition. However, the Required Actions for inoperable ATWS-RPT instrumentation channels provide appropriate compensatory measures for separate inoperable channels. As such, a Note has been provided that allows separate Condition entry for each inoperable ATWS-RPT instrumentation channel.

A.1 and A.2

With one or more channels inoperable, but with ATWS-RPT trip capability for each Function maintained (refer to Required Action B.1 and C.1 Bases), the ATWS-RPT System is capable of performing the intended function. However, the reliability and redundancy of the ATWS-RPT instrumentation is reduced, such that a single failure in the remaining trip system could result in the inability of the ATWS-RPT System to perform the intended function. Therefore, only a limited time is allowed to restore the inoperable channels to OPERABLE status. Because of the diversity of sensors available to provide trip signals, the low probability of extensive numbers of inoperabilities affecting all diverse Functions, and the low probability of an event requiring the initiation of ATWS-RPT, 14 days is provided to restore the inoperable channel (Required Action A.1). Alternately, the inoperable channel may be placed in trip (Required Action A.2), since this would conservatively compensate for the inoperability, restore capability to accommodate a single failure, and allow operation to continue. As noted, placing the channel in trip with no further restrictions is not allowed if the inoperable channel is the result of an inoperable breaker, since this may not adequately compensate for the inoperable breaker (e.g., the breaker may be inoperable such that it will not open). If it is not

(continued)

BASES

ACTIONS

A.1 and A.2 (continued)

desirable to place the channel in trip (e.g., as in the case where placing the inoperable channel in trip would result in an RPT), or if the inoperable channel is the result of an inoperable breaker, Condition D must be entered and its Required Actions taken.

B.1

Required Action B.1 is intended to ensure that appropriate actions are taken if multiple, inoperable, untripped channels within the same Function result in the Function not maintaining ATWS-RPT trip capability. A Function is considered to be maintaining ATWS-RPT trip capability when sufficient channels are OPERABLE or in trip such that the ATWS-RPT System will generate a trip signal from the given Function on a valid signal, and both recirculation pumps can be tripped. This requires two channels of the Function in the same trip system to each be OPERABLE or in trip, and the corresponding motor breakers associated with ATWS-RPT (one fast speed and one LFMG per pump) to be OPERABLE or in trip.

The 72 hour Completion Time is sufficient for the operator to take corrective action (e.g., restoration or tripping of channels) and takes into account the likelihood of an event requiring actuation of the ATWS-RPT instrumentation during this period and the fact that one Function is still maintaining ATWS-RPT trip capability.

C.1

Required Action C.1 is intended to ensure that appropriate actions are taken if multiple, inoperable, untripped channels within both Functions result in both Functions not maintaining ATWS-RPT trip capability. The description of a Function maintaining ATWS-RPT trip capability is discussed in the Bases for Required Action B.1, above.

The 1 hour Completion Time is sufficient for the operator to take corrective action and takes into account the likelihood of an event requiring actuation of the ATWS-RPT instrumentation during this period.

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BASES

ACTIONS
(continued)

D.1 and D.2

With any Required Action and associated Completion Time not met, the plant must be brought to a MODE or other specified condition in which the LCO does not apply. To achieve this status, the plant must be brought to at least MODE 2 within 6 hours (Required Action D.2). Alternately, the associated recirculation pump may be removed from service since this performs the intended Function of the instrumentation (Required Action D.1). The allowed Completion Time of 6 hours is reasonable, based on operating experience, both to reach MODE 2 from full power conditions and to remove a recirculation pump from service in an orderly manner and without challenging plant systems.

SURVEILLANCE
REQUIREMENTS

The Surveillances are modified by a Note to indicate that when a channel is placed in an inoperable status solely for performance of required Surveillances, entry into associated Conditions and Required Actions may be delayed for up to 6 hours provided the associated Function maintains ATWS-RPT trip capability. Upon completion of the Surveillance, or expiration of the 6 hour allowance, the channel must be returned to OPERABLE status or the applicable Condition entered and Required Actions taken. This Note is based on the reliability analysis (Ref. 2) assumption of the average time required to perform channel surveillance. That analysis demonstrated that the 6 hour testing allowance does not significantly reduce the probability that the recirculation pumps will trip when necessary.

SR 3.3.4.2.1

Performance of the CHANNEL CHECK once every 12 hours ensures that gross failure of instrumentation has not occurred. A CHANNEL CHECK is normally a comparison of the parameter indicated on one channel to a similar parameter on other channels. It is based on the assumption that instrument channels monitoring the same parameter should read approximately the same value. Significant deviations between the instrument channels could be an indication of excessive instrument drift in one of the channels or

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BASES

SURVEILLANCE
REQUIREMENTS

SR 3.3.4.2.1 (continued)

something even more serious. A CHANNEL CHECK will detect gross channel failure; thus, it is key to verifying that the instrumentation continues to operate properly between each CHANNEL CALIBRATION.

Agreement criteria are determined by the plant staff based on a combination of the channel instrument uncertainties, including indication and readability. If a channel is outside the criteria, it may be an indication that the instrument has drifted outside its limit.

The Frequency is based upon operating experience that demonstrates channel failure is rare. The CHANNEL CHECK supplements less formal, but more frequent, checks of channels during normal operational use of the displays associated with the required channels of this LCO.

SR 3.3.4.2.2

A CHANNEL FUNCTIONAL TEST is performed on each required channel to ensure that the channel will perform the intended function. A successful test of the required contact(s) of a channel relay may be performed by the verification of the change of state of a single contact of the relay. This clarifies what is an acceptable CHANNEL FUNCTIONAL TEST of a relay. This is acceptable because all of the other required contacts of the relay are verified by other Technical Specifications and non-Technical Specifications tests at least once per refueling interval with applicable extensions.

Any setpoint adjustment shall be consistent with the assumptions of the current plant specific setpoint methodology.

The Frequency of 92 days is based on the reliability analysis of Reference 2.

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BASES

SURVEILLANCE
REQUIREMENTS
(continued)

SR 3.3.4.2.3

A CHANNEL CALIBRATION is a complete check of the instrument loop and the sensor. This test verifies that the channel responds to the measured parameter within the necessary range and accuracy. CHANNEL CALIBRATION leaves the channel adjusted to account for instrument drifts between successive calibrations consistent with the plant specific setpoint methodology.

The Frequency is based upon the assumption of a 24 month calibration interval in the determination of the magnitude of equipment drift in the setpoint analysis.

SR 3.3.4.2.4

The LOGIC SYSTEM FUNCTIONAL TEST demonstrates the OPERABILITY of the required trip logic for a specific channel. The system functional test of the pump breakers, included as part of this Surveillance, overlaps the LOGIC SYSTEM FUNCTIONAL TEST to provide complete testing of the assumed safety function. Therefore, if a breaker is incapable of operating, the associated instrument channel(s) would be inoperable.

The 24 month Frequency is based on the need to perform this Surveillance under the conditions that apply during a plant outage and the potential for an unplanned transient if the Surveillance were performed with the reactor at power. Operating experience has shown that these components usually pass the Surveillance when performed at the 24 month Frequency.

REFERENCES

1. UFSAR, Appendix G.3.1.2.
 2. GENE-770-06-1-A, "Bases For Changes To Surveillance Test Intervals and Allowed Out-of-Service Times For Selected Instrumentation Technical Specifications," December 1992.
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B 3.3 INSTRUMENTATION

B 3.3.5.1 Emergency Core Cooling System (ECCS) Instrumentation

BASES

BACKGROUND

The purpose of the ECCS instrumentation is to initiate appropriate responses from the systems to ensure that fuel is adequately cooled in the event of a design basis accident or transient.

For most anticipated operational occurrences (A00s) and Design Basis Accidents (DBAs), a wide range of dependent and independent parameters are monitored.

The ECCS instrumentation actuates low pressure core spray (LPCS), low pressure coolant injection (LPCI), high pressure core spray (HPCS), Automatic Depressurization System (ADS), and the diesel generators (DGs). The equipment involved with each of these systems is described in the Bases for LCO 3.5.1, "ECCS—Operating," or LCO 3.8.1, "AC Sources—Operating."

Low Pressure Core Spray System

The LPCS System may be initiated by either automatic or manual means. Automatic initiation occurs for conditions of Reactor Vessel Water Level—Low Low Low, Level 1 or Drywell Pressure—High. Reactor vessel water level is monitored by two redundant differential pressure transmitters, each providing input to a trip unit. Drywell pressure is monitored by two pressure switches. The outputs of the four signals (two trip units and two pressure switches) are connected to relays whose contacts are arranged in a one-out-of-two taken twice logic. The logic will provide an initiation signal if both reactor vessel water level channels or both drywell pressure channels trip. In addition, the logic will provide an initiation signal if a certain combination of reactor vessel water level and drywell pressure channels trip. The LPCS initiation signal is a sealed in signal and must be manually reset. The LPCS initiation signal also provides an initiation signal to the Division 1 LPCI initiation logic. The logic can also be

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BASES

BACKGROUND

Low Pressure Core Spray System (continued)

initiated by use of a manual push button. Upon receipt of an initiation signal, the LPCS pump is automatically started if normal AC power is available; otherwise the pump is started immediately after AC power is available from the DG.

The LPCS test line isolation valve, which is also a primary containment isolation valve (PCIV), is closed on a LPCS initiation signal to allow full system flow assumed in the accident analysis and maintains containment isolation in the event LPCS is not operating.

The LPCS pump discharge flow is monitored by a flow switch that senses the differential pressure across a flow element in the pump discharge line. When the pump is running and discharge flow is low enough that pump overheating may occur, the minimum flow return line valve is opened. The valve is automatically closed if flow is above the minimum flow setpoint to allow the full system flow assumed in the accident analysis.

The LPCS System also monitors the pressure within the injection line and in the reactor vessel to ensure that, before the injection valve opens, the injection line pressure and reactor pressure have fallen to a value below the LPCS System's maximum design pressure. The pressure in the LPCS injection line is monitored by one pressure switch while reactor pressure is monitored by two pressure switches. The injection valve will receive an open permissive signal if the LPCS injection line pressure switch senses low pressure (one-out-of-one logic) and if any one of the reactor pressure switches sense low pressure (one-out-of-two logic). The reactor vessel pressure switches also provide a permissive signal in the Division 1 LPCI injection valve.

Low Pressure Coolant Injection Subsystems

The LPCI is an operating mode of the Residual Heat Removal (RHR) System, with three LPCI subsystems. The LPCI subsystems may be initiated by automatic or manual means. Automatic initiation occurs for conditions of Reactor Vessel Water Level—Low Low Low, Level 1 or Drywell Pressure—High.

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BASES

BACKGROUND Low Pressure Coolant Injection Subsystems (continued)

Reactor vessel water level is monitored by two redundant differential pressure transmitters per division, each providing input to a trip unit. Drywell pressure is monitored by two pressure switches per division. The outputs of the four Division 2 LPCI (loops B and C) signals (two trip units and two pressure switches) are connected to relays whose contacts are arranged in a one-out-of-two taken twice logic. The logic will provide an initiation signal if both reactor vessel water level channels or both drywell pressure channels trip. In addition, the logic will provide an initiation signal if certain combinations of reactor vessel water level and drywell pressure channels trip. The Division 1 LPCI (loop A) receives its initiation signal from the LPCS logic, which uses a similar one-out-of-two taken twice logic. The two divisions can also be initiated by use of a manual push button (one per division, with the LPCI A manual push button being common with LPCS). Once an initiation signal is received by the LPCI control circuitry, the signal is sealed in until manually reset.

Upon receipt of an initiation signal, the LPCI Pump C is automatically started if normal AC power is available; otherwise the pump is started immediately after power is available from the DG while LPCI pumps A and B are automatically started if offsite power is available; otherwise the pumps are started in approximately 5 seconds after AC power from the DG is available. These time delays limit the loading on the standby power sources.

Each LPCI subsystem's discharge flow is monitored by a flow switch that senses the differential pressure across a flow element in the pump discharge line. When a pump is running and discharge flow is low enough that pump overheating may occur, the respective minimum flow return line valve is opened. The valve is automatically closed if flow is above the minimum flow setpoint to allow the full system flow assumed in the analyses.

The RHR test line suppression pool cooling isolation and suppression pool spray isolation valves (which are also PCIVs) are closed on a LPCI initiation signal to allow full system flow assumed in the accident analysis and maintain containment isolated in the event LPCI is not operating.

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BASES

BACKGROUND

Low Pressure Coolant Injection Subsystems (continued)

The LPCI subsystems monitor the pressure within the associated injection line and in the reactor vessel to ensure that, prior to an injection valve opening, the injection line pressure and reactor pressure have fallen to a value below the LPCI subsystem's maximum design pressure. The pressure within each LPCI injection line is monitored by one pressure switch, while reactor pressure is monitored by two pressure switches, per division. The associated injection valve will receive an open permissive signal if the LPCI injection line pressure switch senses low pressure (one-out-of-one logic) and if any one of the associated reactor pressure switches sense low pressure (one-out-of-two logic, per division). The Division 1 LPCI (loop A) receives its reactor pressure signals from the LPCS logic.

High Pressure Core Spray System

The HPCS System may be initiated by either automatic or manual means. Automatic initiation occurs for conditions of Reactor Vessel Water Level—Low Low, Level 2 or Drywell Pressure—High. Reactor vessel water level is monitored by four redundant differential pressure transmitters and drywell pressure is monitored by four redundant pressure switches. Each differential pressure transmitter provides input to a trip unit. The outputs of the trip units are connected to relays whose contacts are arranged in a one-out-of-two taken twice logic. Each pressure switch provides input to a relay whose contact is arranged in a one-out-of-two taken twice logic. The logic can also be initiated by use of a manual push button. The HPCS System initiation signal is a sealed in signal and must be manually reset.

The HPCS pump discharge flow and pressure are monitored by a differential pressure switch and a pressure switch, respectively. When the pump is running (as indicated by the pressure switch) and discharge flow is low enough that pump overheating may occur, the minimum flow return line valve is opened. The valve is automatically closed if flow is above the minimum flow setpoint to allow full system flow assumed in the accident analyses.

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BASES

BACKGROUND

High Pressure Core Spray System (continued)

The HPCS full flow test line isolation valve to the suppression pool (which is also a PCIV) is closed on a HPCS initiation signal to allow full system flow assumed in the accident analyses and maintain containment isolated in the event HPCS is not operating.

The HPCS System provides makeup water to the reactor until the reactor vessel water level reaches the high water level (Level 8) trip, at which time the HPCS injection valve closes. The HPCS pump will continue to run on minimum flow. The logic is two-out-of-two to provide high reliability of the HPCS System. The injection valve automatically reopens if a low low water level signal is subsequently received.

Automatic Depressurization System

ADS may be initiated by either automatic or manual means. Automatic initiation occurs when signals indicating Reactor Vessel Water Level—Low Low Low, Level 1; Drywell Pressure—High or ADS Drywell Pressure Bypass Timer; confirmed Reactor Vessel Water Level—Low, Level 3; and either LPCS or LPCI Pump Discharge Pressure—High are all present, and the ADS Initiation Timer has timed out. There are two differential pressure transmitters for Reactor Vessel Water Level—Low Low Low, Level 1, two pressure switches for Drywell Pressure—High, and one differential pressure transmitter for confirmed Reactor Vessel Water Level—Low, Level 3 in each of the two ADS trip systems. Each of the transmitters connects to a trip unit, which then drives a relay whose contacts input to the initiation logic. Each pressure switch drives a relay whose contact also inputs to the initiation logic.

Each ADS trip system (trip system A and trip system B) includes a time delay between satisfying the initiation logic and the actuation of the ADS valves. The time delay chosen is long enough that the HPCS has time to operate to recover to a level above Level 1, yet not so long that the LPCI and LPCS systems are unable to adequately cool the fuel if the HPCS fails to maintain level. An alarm in the control room is annunciated when either of the timers is running. Resetting the ADS initiation signals resets the ADS Initiation Timers.

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BASES

BACKGROUND

Automatic Depressurization System (continued)

The ADS also monitors the discharge pressures of the three LPCI pumps and the LPCS pump. Each ADS trip system includes two discharge pressure permissive switches from each of the two low pressure ECCS pumps in the associated Division (i.e., Division 1 ECCS inputs to ADS trip system A and Division 2 ECCS inputs to ADS trip system B). The signals are used as a permissive for ADS actuation, indicating that there is a source of core coolant available once the ADS has depressurized the vessel. Any one of the four low pressure pumps provides sufficient core coolant flow to permit automatic depressurization.

The ADS logic in each trip system is arranged in two strings. One string has a contact from each of the following variables: Reactor Vessel Water Level—Low Low Low, Level 1; Drywell Pressure—High or ADS Drywell Pressure Bypass Timer; Reactor Vessel Water Level—Low, Level 3; ADS Initiation Timer; and two low pressure ECCS Discharge Pressure—High contacts (one from each divisional pump). The other string has a contact from each of the following variables: Reactor Vessel Water Level—Low Low Low, Level 1; Drywell Pressure—High; ADS Drywell Pressure Bypass Timer; and two low pressure ECCS Discharge Pressure—High contacts (one from each divisional pump). To initiate an ADS trip system, the following applicable contacts must close in the associated string: Reactor Vessel Water Level—Low Low Low, Level 1; Drywell Pressure—High or ADS Drywell Pressure Bypass Timer; Reactor Vessel Water Level—Low, Level 3 (one string only); ADS Initiation Timer (one string only); and one of the two low pressure ECCS Discharge Pressure—High contacts.

Either ADS trip system A or trip system B will cause all the ADS valves to open. Once the Drywell Pressure—High or ADS initiation signals are present, they are individually sealed in until manually reset.

Manual initiation is accomplished by arming and depressing both ADS A trip system strings (Division 1) or both ADS B trip system strings (Division 2) which will cause the ADS valves to open with no time delay. No permissive interlocks

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BASES

BACKGROUND

Automatic Depressurization System (continued)

are required for the manual initiation. Manual inhibit switches are provided in the control room for ADS; however, their function is not required for ADS OPERABILITY (provided ADS is not inhibited when required to be OPERABLE).

Diesel Generators

The Division 1, 2, and 3 DGs may be initiated by either automatic or manual means. Automatic initiation occurs for conditions of Reactor Vessel Water Level—Low Low Low, Level 1 or Drywell Pressure—High for DGs 0 and 1A (2A), and Reactor Vessel Water Level—Low Low, Level 2 or Drywell Pressure—High for DG 1B (2B). DG 0 is common to both units and will start on an initiation signal from both units. The other DGs will only start on an initiation signal from the unit ECCS logic. The DGs are also initiated upon loss of voltage signals. (Refer to Bases for LCO 3.3.8.1, "Loss of Power (LOP) Instrumentation," for a discussion of these signals.) The DGs receive their initiation signals from the associated Divisions' ECCS logic (i.e., DG 0 receives an initiation signal from Division 1 ECCS (LPCS and LPCI A); DG 1A/2A receives an initiation signal from Division 2 ECCS (LPCI B and LPCI C); and DG 1B/2B receives an initiation signal from Division 3 ECCS (HPCS)). The DGs can also be started manually from the control room and locally in the associated DG room. The DG initiation signal is a sealed in signal and must be manually reset. The DG initiation logic is reset by resetting the associated ECCS initiation logic. Upon receipt of a LOCA initiation signal, each DG is automatically started, is ready to load in approximately 13 seconds, and will run in standby conditions (rated voltage and speed, with the DG output breaker open). The DGs will only energize their respective emergency buses if a loss of offsite power occurs. (Refer to Bases for LCO 3.3.8.1.)

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APPLICABILITY

The actions of the ECCS are explicitly assumed in the safety analyses of References 1, 2, and 3. The ECCS is initiated to preserve the integrity of the fuel cladding by limiting the post LOCA peak cladding temperature to less than the 10 CFR 50.46 limits.

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BASES

APPLICABLE
SAFETY ANALYSES,
LCO, and
APPLICABILITY
(continued)

ECCS instrumentation satisfies Criterion 3 of 10 CFR 50.36(c)(2)(ii). Certain instrumentation Functions are retained for other reasons and are described below in the individual Functions discussion.

The OPERABILITY of the ECCS instrumentation is dependent upon the OPERABILITY of the individual instrumentation channel Functions specified in Table 3.3.5.1-1. Each Function must have a required number of OPERABLE channels, with their setpoints within the specified Allowable Values, where appropriate. The actual setpoint is calibrated consistent with applicable setpoint methodology assumptions. Each ECCS subsystem must also respond within its assumed response time. Table 3.3.5.1-1, footnote (b), is added to show that certain ECCS instrumentation Functions are also required to be OPERABLE to perform DG initiation.

Allowable Values are specified for each ECCS Function specified in the Table. Nominal trip setpoints are specified in the setpoint calculations. The nominal setpoints are selected to ensure that the setpoints do not exceed the Allowable Value between CHANNEL CALIBRATIONS. Operation with a trip setpoint less conservative than the nominal trip setpoint, but within its Allowable Value, is acceptable. A channel is inoperable if its actual trip setpoint is not within its required Allowable Value. Trip setpoints are those predetermined values of output at which an action should take place. The setpoints are compared to the actual process parameter (e.g., reactor vessel water level), and when the measured output value of the process parameter exceeds the setpoint, the associated device (e.g., trip unit) changes state. The analytic limits are derived from the limiting values of the process parameters obtained from the safety analysis. The trip setpoints are determined from the analytic limits, corrected for defined process, calibration, and instrument errors. The Allowable Values are then determined, based on the trip setpoint values, by accounting for the calibration based errors. These calibration based errors are limited to reference accuracy, instrument drift, errors associated with measurement and test equipment, and calibration tolerance of loop components. The trip setpoints and Allowable Values determined in this manner provide adequate protection

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because instrument uncertainties, process effects, calibration tolerances, instrument drift, and severe environment errors (for channels that must function in harsh environments as defined by 10 CFR 50.49) are accounted for and appropriately applied for the instrumentation.

In general, the individual Functions are required to be OPERABLE in the MODES or other specified conditions that may require ECCS (or DG) initiation to mitigate the consequences of a design basis accident or transient. To ensure reliable ECCS and DG function, a combination of Functions is required to provide primary and secondary initiation signals.

The specific Applicable Safety Analyses, LCO, and Applicability discussions are listed below on a Function by Function basis.

Low Pressure Core Spray and Low Pressure Coolant Injection Systems

1.a, 2.a. Reactor Vessel Water Level - Low Low Low, Level 1

Low reactor pressure vessel (RPV) water level indicates that the capability to cool the fuel may be threatened. Should RPV water level decrease too far, fuel damage could result. The low pressure ECCS and associated DGs are initiated at Level 1 to ensure that core spray and flooding functions are available to prevent or minimize fuel damage. The Reactor Vessel Water Level - Low Low Low, Level 1 is one of the Functions assumed to be OPERABLE and capable of initiating the ECCS during the transients analyzed in References 1 and 3. In addition, the Reactor Vessel Water Level - Low Low Low, Level 1 Function is directly assumed in the analysis of the recirculation line break (Ref. 2). The core cooling function of the ECCS, along with the scram action of the Reactor Protection System (RPS), ensures that the fuel peak cladding temperature remains below the limits of 10 CFR 50.46.

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1.a, 2.a. Reactor Vessel Water Level - Low Low Low, Level 1
(continued)

Reactor Vessel Water Level - Low Low Low, Level 1 signals are initiated from four differential pressure transmitters that sense the difference between the pressure due to a constant column of water (reference leg) and the pressure due to the actual water level (variable leg) in the vessel. The Reactor Vessel Water Level - Low Low Low, Level 1 Allowable Value is chosen to allow time for the low pressure core flooding systems to activate and provide adequate cooling.

Two channels of Reactor Vessel Water Level - Low Low Low, Level 1 Function per associated Division are only required to be OPERABLE when the associated ECCS is required to be OPERABLE, to ensure that no single instrument failure can preclude ECCS initiation. (Two channels input to LPCS, LPCI A, and the associated Division 1 DG, while the other two channels input to LPCI B, LPCI C, and Division 2 DG.) Refer to LCO 3.5.1 and LCO 3.5.2, "ECCS - Shutdown," for Applicability Bases for the low pressure ECCS subsystems.

1.b, 2.b. Drywell Pressure - High

High pressure in the drywell could indicate a break in the reactor coolant pressure boundary (RCPB). The low pressure ECCS and associated DGs are initiated upon receipt of the Drywell Pressure - High Function in order to minimize the possibility of fuel damage. The core cooling function of the ECCS, along with the scram action of the RPS, ensures that the fuel peak cladding temperature remains below the limits of 10 CFR 50.46.

High drywell pressure signals are initiated from four pressure switches that sense drywell pressure. The Allowable Value was selected to be as low as possible and be indicative of a LOCA inside primary containment.

The Drywell Pressure - High Function is required to be OPERABLE when the associated ECCS is required to be OPERABLE in conjunction with times when the primary containment is

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1.b, 2.b. Drywell Pressure-High (continued)

required to be OPERABLE. Thus, four channels of the LPCS and LPCI Drywell Pressure-High Function are required to be OPERABLE in MODES 1, 2, and 3 to ensure that no single instrument failure can preclude ECCS initiation. (Two channels input to LPCS, LPCI A, and the Division 1 DG, while the other two channels input to LPCI B, LPCI C, and the Division 2 DG.) In MODES 4 and 5, the Drywell Pressure-High Function is not required since there is insufficient energy in the reactor to pressurize the primary containment to Drywell Pressure-High setpoint. Refer to LCO 3.5.1 for Applicability Bases for the low pressure ECCS subsystems.

1.c, 2.c. LPCI Pump A and Pump B Start-Time Delay Relay

The purpose of this time delay is to stagger the start of the two ECCS pumps that are in each of Divisions 1 and 2, thus limiting the starting transients on the 4.16 kV emergency buses. This Function is only necessary when power is being supplied from the standby power sources (DG). On ECCS initiation, the time delay is bypassed if the normal feed breaker to the Class 1E switchgear is closed. The LPCI Pump Start-Time Delay Relays are assumed to be OPERABLE in the accident and transient analyses requiring ECCS initiation. That is, the analysis assumes that the pumps will initiate when required and excess loading will not cause failure of the standby power sources (DG).

There are two LPCI Pump Start-Time Delay Relays, one in each of the RHR "A" and RHR "B" pump start logic circuits. While each time delay relay is dedicated to a single pump start logic, a single failure of a LPCI Pump Start-Time Delay Relay could result in the failure of the two low pressure ECCS pumps, powered from the emergency bus, to perform their intended function within the assumed ECCS RESPONSE TIMES (e.g., as in the case where both ECCS pumps on one emergency bus start simultaneously due to an inoperable time delay relay). This still leaves two of the four low pressure ECCS pumps OPERABLE; thus, the single failure criterion is met (i.e., loss of one instrument does not preclude ECCS initiation). The Allowable Value for the LPCI Pump Start-Time Delay Relays is chosen to be short enough so that ECCS operation is not degraded.

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APPLICABLE SAFETY ANALYSES, LCO, and APPLICABILITY 1.c, 2.c. LPCI Pump A and Pump B Start-Time Delay Relay (continued)

Each LPCI Pump Start-Time Delay Relay Function is required to be OPERABLE when the associated LPCI subsystem is required to be OPERABLE. Refer to LCO 3.5.1 and LCO 3.5.2 for Applicability Bases for the LPCI subsystems.

1.d, 1.g, 2.d, 2.f. Reactor Steam Dome Pressure-Low (Injection Permissive) and LPCS and LPCI Injection Line Pressure-Low (Injection Permissive)

Low reactor steam dome pressure and injection line pressure signals are used as permissives for the low pressure ECCS subsystems. This ensures that, prior to opening the injection valves of the low pressure ECCS subsystems, the reactor pressure has fallen to a value below these subsystems maximum design pressure. The Reactor Steam Dome Pressure-Low (Injection Permissive) and LPCS and LPCI Injection Line Pressure-Low (Injection Permissive) are two of the Functions assumed to be OPERABLE and capable of permitting initiation of the ECCS during the transients analyzed in References 1 and 3. In addition, the Reactor Steam Dome Pressure-Low (Injection Permissive) and LPCS and LPCI Injection Line Pressure-Low (Injection Permissive) Functions are directly assumed in the analysis of the recirculation line break (Ref. 2). The core cooling function of the ECCS, along with the scram action of the RPS, ensures that the fuel peak cladding temperature remains below the limits of 10 CFR 50.46.

The Reactor Steam Dome Pressure-Low (Injection Permissive) signals are initiated from four pressure switches that sense the reactor dome pressure. The LPCS and LPCI Injection Line Pressure-Low (Injection Permissive) signals are initiated from four pressure switches that sense the pressure in the injection line (one switch for each low pressure ECCS injection line). The Allowable Values are low enough to

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1.d, 1.g, 2.d, 2.f. Reactor Steam Dome Pressure-Low (Injection Permissive) and LPCS and LPCI Injection Line Pressure-Low (Injection Permissive) (continued)

prevent overpressurizing the equipment in the low pressure ECCS, but high enough to ensure that the ECCS injection prevents the fuel peak cladding temperature from exceeding the limits of 10 CFR 50.46.

Two channels of Reactor Steam Dome Pressure-Low (Injection Permissive) Function per associated Division and one channel of LPCS and LPCI Injection Line Pressure-Low (Injection Permissive) per associated injection line are only required to be OPERABLE when the associated ECCS is required to be OPERABLE to ensure that no single instrument failure can preclude ECCS initiation. (Two channels of Reactor Vessel Pressure-Low (Injection Permissive) are required for LPCS and LPCI A, while two other channels are required for LPCI B and LPCI C. In addition, one channel of LPCS Injection Line Pressure-Low (Injection Permissive) is required for LPCS, while one channel of LPCI Injection Line Pressure is required for each LPCI subsystem.) Refer to LCO 3.5.1 and LCO 3.5.2 for Applicability Bases for the low pressure ECCS subsystems.

1.e, 1.f, 2.e. LPCS and LPCI Pump Discharge Flow-Low (Bypass)

The minimum flow instruments are provided to protect the associated low pressure ECCS pump from overheating when the pump is operating and the associated injection valve is not sufficiently open. The minimum flow line valve is opened when low flow is sensed, and the valve is automatically closed when the flow rate is adequate to protect the pump. The LPCI and LPCS Pump Discharge Flow-Low (Bypass) Functions are assumed to be OPERABLE and capable of closing the minimum flow valves to ensure that the low pressure ECCS flows assumed during the transients and accidents analyzed in References 1, 2, and 3 are met. The core cooling function of the ECCS, along with the scram action of the RPS, ensures that the fuel peak cladding temperature remains below the limits of 10 CFR 50.46.

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1.e, 1.f, 2.e. LPCS and LPCI Pump Discharge Flow-Low
(Bypass) (continued)

One flow switch per ECCS pump is used to detect the associated subsystems flow rate. The logic is arranged such that each switch causes its associated minimum flow valve to open when flow is low with the pump running. The logic will close the minimum flow valve once the closure setpoint is exceeded. The LPCI minimum flow valves are time delayed such that the valves will not open for approximately 8 seconds after the switches detect low flow. The time delay is provided to limit reactor vessel inventory loss during the startup of the RHR shutdown cooling mode. The Pump Discharge Flow-Low (Bypass) Allowable Values are high enough to ensure that the pump flow rate is sufficient to protect the pump, yet low enough to ensure that the closure of the minimum flow valve is initiated to allow full flow into the core.

Each channel of Pump Discharge Flow-Low (Bypass) Function (one LPCS channel and three LPCI channels) is only required to be OPERABLE when the associated ECCS is required to be OPERABLE, to ensure that no single instrument failure can preclude the ECCS function. Refer to LCO 3.5.1 and LCO 3.5.2 for Applicability Bases for the low pressure ECCS subsystems.

1.h, 2.g. Manual Initiation

The Manual Initiation push button channels introduce signals into the appropriate ECCS logic to provide manual initiation capability and are redundant to the automatic protective instrumentation. There is one push button for each of the two Divisions of low pressure ECCS (i.e., Division 1 ECCS, LPCS and LPCI A; Division 2 ECCS, LPCI B and LPCI C).

The Manual Initiation Function is not assumed in any accident or transient analyses in the UFSAR. However, the Function is retained for overall redundancy and diversity of the low pressure ECCS function as required by the NRC in the plant licensing basis.

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1.h, 2.g. Manual Initiation (continued)

There is no Allowable Value for this Function since the channels are mechanically actuated based solely on the position of the push buttons. Each channel of the Manual Initiation Function (one channel per division) is only required to be OPERABLE when the associated ECCS is required to be OPERABLE. Refer to LCO 3.5.1 and LCO 3.5.2 for Applicability Bases for the low pressure ECCS subsystems.

High Pressure Core Spray System

3.a. Reactor Vessel Water Level—Low Low, Level 2

Low RPV water level indicates that the capability to cool the fuel may be threatened. Should RPV water level decrease too far, fuel damage could result. Therefore, the HPCS System and associated DG is initiated at Level 2 to maintain level above the top of the active fuel. The Reactor Vessel Water Level—Low Low, Level 2 is one of the Functions assumed to be OPERABLE and capable of initiating HPCS during the transients analyzed in References 1 and 3. The Reactor Vessel Water Level—Low Low, Level 2 Function associated with HPCS is directly assumed in the analysis of the recirculation line break (Ref. 2). The core cooling function of the ECCS, along with the scram action of the RPS, ensures that the fuel peak cladding temperature remains below the limits of 10 CFR 50.46.

Reactor Vessel Water Level—Low Low, Level 2 signals are initiated from four differential pressure transmitters that sense the difference between the pressure due to a constant column of water (reference leg) and the pressure due to the actual water level (variable leg) in the vessel. The Reactor Vessel Water Level—Low Low, Level 2 Allowable Value is chosen such that for complete loss of feedwater flow, the Reactor Core Isolation Cooling (RCIC) System flow with HPCS assumed to fail will be sufficient to avoid initiation of low pressure ECCS at Reactor Vessel Water Level—Low Low, Level 1.

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3.a. Reactor Vessel Water Level - Low Low, Level 2
(continued)

Four channels of Reactor Vessel Water Level - Low Low, Level 2 Function are only required to be OPERABLE when HPCS is required to be OPERABLE to ensure that no single instrument failure can preclude HPCS initiation. Refer to LCO 3.5.1 and LCO 3.5.2 for HPCS Applicability Bases.

3.b. Drywell Pressure - High

High pressure in the drywell could indicate a break in the RCPB. The HPCS System and associated DG are initiated upon receipt of the Drywell Pressure - High Function in order to minimize the possibility of fuel damage. The core cooling function of the ECCS, along with the scram action of the RPS, ensures that the fuel peak cladding temperature remains below the limits of 10 CFR 50.46.

Drywell Pressure - High signals are initiated from four pressure switches that sense drywell pressure. The Allowable Value was selected to be as low as possible and be indicative of a LOCA inside primary containment.

The Drywell Pressure - High Function is required to be OPERABLE when HPCS is required to be OPERABLE in conjunction with times when the primary containment is required to be OPERABLE. Thus, four channels of the HPCS Drywell Pressure - High Function are required to be OPERABLE in MODES 1, 2, and 3, to ensure that no single instrument failure can preclude ECCS initiation. In MODES 4 and 5, the Drywell Pressure - High Function is not required since there is insufficient energy in the reactor to pressurize the drywell to the Drywell Pressure - High Functions setpoint. Refer to LCO 3.5.1 for the Applicability Bases for the HPCS System.

3.c. Reactor Vessel Water Level - High, Level 8

High RPV water level indicates that sufficient cooling water inventory exists in the reactor vessel such that there is no danger to the fuel. Therefore, the Level 8 signal is used to close the HPCS injection valve to prevent overflow into the main steam lines (MSLs). The Reactor Vessel Water

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3.c. Reactor Vessel Water Level-High, Level 8 (continued)

Level-High, Level 8 Function for HPCS isolation is not credited in the accident analysis. It is retained since it is a potentially significant contributor to risk.

Reactor Vessel Water Level-High, Level 8 signals for HPCS are initiated from two level transmitters from the narrow range water level measurement instrumentation. The Reactor Vessel Water Level-High, Level 8 Allowable Value is chosen to isolate flow from the HPCS System prior to water overflowing into the MSLS.

Two channels of Reactor Vessel Water Level-High, Level 8 Function are only required to be OPERABLE when HPCS is required to be OPERABLE to ensure that no single instrument failure can preclude HPCS initiation. Refer to LCO 3.5.1 and LCO 3.5.2 for HPCS Applicability Bases.

3.d, 3.e. HPCS Pump Discharge Pressure-High (Bypass) and HPCS System Flow Rate-Low (Bypass)

The minimum flow instruments are provided to protect the HPCS pump from overheating when the pump is operating and the associated injection valve is not sufficiently open. The minimum flow line valve is opened when low flow and high pump discharge pressure are sensed, and the valve is automatically closed when the flow rate is adequate to protect the pump or the discharge pressure is low (indicating the HPCS pump is not operating). The HPCS System Flow Rate-Low (Bypass) and HPCS Pump Discharge Pressure-High Functions are assumed to be OPERABLE and capable of closing the minimum flow valve to ensure that the ECCS flow assumed during the transients and accidents analyzed in References 1, 2, and 3 are met. The core cooling function of the ECCS, along with the scram action of the RPS, ensures that the fuel peak cladding temperature remains below the limits of 10 CFR 50.46.

One flow switch is used to detect the HPCS System's flow rate. The logic is arranged such that the switch causes the minimum flow valve to open, provided the HPCS pump discharge pressure, sensed by another switch, is high enough

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3.d, 3.e. HPCS Pump Discharge Pressure-High (Bypass) and
HPCS System Flow Rate-Low (Bypass) (continued)

(indicating the pump is operating). The logic will close the minimum flow valve once the closure setpoint is exceeded. (The valve will also close upon HPCS pump discharge pressure decreasing below the setpoint.)

The HPCS System Flow Rate-Low (Bypass) Allowable Values are high enough to ensure that pump flow rate is sufficient to protect the pump, yet low enough to ensure that the closure of the minimum flow valve is initiated to allow full flow into the core. The HPCS Pump Discharge Pressure-High (Bypass) Allowable Value is set high enough to ensure that the valve will not be open when the pump is not operating.

One channel of each Function is required to be OPERABLE when the HPCS is required to be OPERABLE. Refer to LCO 3.5.1 and LCO 3.5.2 for HPCS Applicability Bases.

3.f. Manual Initiation

The Manual Initiation push button channel introduces a signal into the HPCS logic to provide manual initiation capability and is redundant to the automatic protective instrumentation. There is one push button for the HPCS System.

The Manual Initiation Function is not assumed in any accident or transient analyses in the UFSAR. However, the Function is retained for overall redundancy and diversity of the HPCS function as required by the NRC in the plant licensing basis.

There is no Allowable Value for this Function since the channel is mechanically actuated based solely on the position of the push button. One channel of the Manual Initiation Function is only required to be OPERABLE when the HPCS System is required to be OPERABLE. Refer to LCO 3.5.1 and LCO 3.5.2 for HPCS Applicability Bases.

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Automatic Depressurization System

4.a, 5.a. Reactor Vessel Water Level - Low Low Low, Level 1

Low RPV water level indicates that the capability to cool the fuel may be threatened. Should RPV water level decrease too far, fuel damage could result. Therefore, ADS receives one of the signals necessary for initiation from this Function. The Reactor Vessel Water Level - Low Low Low, Level 1 is one of the Functions assumed to be OPERABLE and capable of initiating the ADS during the accidents analyzed in Reference 2. The core cooling function of the ECCS, along with the scram action of the RPS, ensures that the fuel peak cladding temperature remains below the limits of 10 CFR 50.46.

Reactor Vessel Water Level - Low Low Low, Level 1 signals are initiated from four differential pressure transmitters that sense the difference between the pressure due to a constant column of water (reference leg) and the pressure due to the actual water level (variable leg) in the vessel. The Reactor Vessel Water Level - Low Low Low, Level 1 Allowable Value is chosen high enough to allow time for the low pressure core spray and injection systems to initiate and provide adequate cooling.

Four channels of Reactor Vessel Water Level - Low Low Low, Level 1 Function are only required to be OPERABLE when ADS is required to be OPERABLE to ensure that no single instrument failure can preclude ADS initiation. (Two channels input to ADS trip system A while the other two channels input to ADS trip system B). Refer to LCO 3.5.1 for ADS Applicability Bases.

4.b, 5.b. Drywell Pressure - High

High pressure in the drywell could indicate a break in the RCPB. Therefore, ADS receives one of the signals necessary for initiation from this Function in order to minimize the possibility of fuel damage. The Drywell Pressure - High is assumed to be OPERABLE and capable of initiating the ADS during the accidents analyzed in Reference 2. The core cooling function of the ECCS, along with the scram action of the RPS, ensures that the fuel peak cladding temperature remains below the limits of 10 CFR 50.46.

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4.b, 5.b. Drywell Pressure - High (continued)

Drywell Pressure - High signals are initiated from four pressure switches that sense drywell pressure. The Allowable Value was selected to be as low as possible and be indicative of a LOCA inside primary containment.

Four channels of Drywell Pressure - High Function are only required to be OPERABLE when ADS is required to be OPERABLE to ensure that no single instrument failure can preclude ADS initiation. (Two channels input to ADS trip system A while the other two channels input to ADS trip system B.) Refer to LCO 3.5.1 for ADS Applicability Bases.

4.c, 5.c. ADS Initiation Timer

The purpose of the ADS Initiation Timer is to delay depressurization of the reactor vessel to allow the HPCS System time to maintain reactor vessel water level. Since the rapid depressurization caused by ADS operation is one of the most severe transients on the reactor vessel, its occurrence should be limited. By delaying initiation of the ADS Function, the operator is given the chance to monitor the success or failure of the HPCS System to maintain water level, and then to decide whether or not to allow ADS to initiate, to delay initiation further by recycling the timer, or to inhibit initiation permanently. The ADS Initiation Timer Function is assumed to be OPERABLE for the accident analyses of Reference 2 that require ECCS initiation and assume failure of the HPCS System.

There are two ADS Initiation Timer relays, one in each of the two ADS trip systems. The Allowable Value for the ADS Initiation Timer is chosen to be short enough so that there is still time after depressurization for the low pressure ECCS subsystems to provide adequate core cooling.

Two channels of the ADS Initiation Timer Function are only required to be OPERABLE when the ADS is required to be OPERABLE to ensure that no single instrument failure can preclude ADS initiation. (One channel inputs to ADS trip system A while the other channel inputs to ADS trip system B.) Refer to LCO 3.5.1 for ADS Applicability Bases.

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4.d, 5.d. Reactor Vessel Water Level - Low, Level 3
(Confirmatory)

The Reactor Vessel Water Level - Low, Level 3 Function (Confirmatory) is used by the ADS only as a confirmatory low water level signal. ADS receives one of the signals necessary for initiation from Reactor Vessel Water Level - Low Low Low, Level 1 signals. In order to prevent spurious initiation of the ADS due to spurious Level 1 signals, a Level 3 signal must also be received before ADS initiation commences.

Reactor Vessel Water Level - Low, Level 3 (Confirmatory) signals are initiated from two differential pressure transmitters that sense the difference between the pressure due to a constant column of water (reference leg) and the pressure due to the actual water level (variable leg) in the vessel. The Allowable Value for Reactor Vessel Water Level - Low, Level 3 (Confirmatory) is selected at the RPS Level 3 scram Allowable Value for convenience. Refer to LCO 3.3.1.1, "Reactor Protection System (RPS) Instrumentation," for Bases discussion of this Function.

Two channels of Reactor Vessel Water Level - Low, Level 3 (Confirmatory) Function are only required to be OPERABLE when the ADS is required to be OPERABLE to ensure that no single instrument failure can preclude ADS initiation. (One channel inputs to ADS trip system A while the other channel inputs to ADS trip system B.) Refer to LCO 3.5.1 for ADS Applicability Bases.

4.e, 4.f, 5.e. LPCS and LPCI Pump Discharge Pressure - High

The Pump Discharge Pressure - High signals from the LPCS and LPCI pumps (indicating that the associated pump is running) are used as permissives for ADS initiation, indicating that there is a source of low pressure cooling water available once the ADS has depressurized the vessel. Pump Discharge Pressure - High is one of the Functions assumed to be OPERABLE and capable of permitting ADS initiation during the events analyzed in References 2 and 3 with an assumed HPCS failure. For these events, the ADS depressurizes the reactor vessel so that the low pressure ECCS can perform the

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APPLICABLE SAFETY ANALYSES, LCO, and APPLICABILITY 4.e, 4.f, 5.e. LPCS and LPCI Pump Discharge Pressure-High
(continued)
core cooling functions. This core cooling function of the ECCS, along with the scram action of the RPS, ensures that the fuel peak cladding temperature remains below the limits of 10 CFR 50.46.

Pump discharge pressure signals are initiated from eight pressure switches, two on the discharge side of each of the four low pressure ECCS pumps. In order to generate an ADS permissive in one trip system, it is necessary that only one pump (both channels for the pump) indicate the high discharge pressure condition. The Pump Discharge Pressure-High Allowable Value is less than the pump discharge pressure when the pump is operating in a full flow mode, and high enough to avoid any condition that results in a discharge pressure permissive when the LPCS and LPCI pumps are aligned for injection and the pumps are not running. The actual operating point of this Function is not assumed in any transient or accident analysis.

Eight channels of LPCS and LPCI Pump Discharge Pressure-High Function (two LPCS and two LPCI A channels input to ADS trip system A, while two LPCI B and two LPCI C channels input to ADS trip system B) are only required to be OPERABLE when the ADS is required to be OPERABLE to ensure that no single instrument failure can preclude ADS initiation. Refer to LCO 3.5.1 for ADS Applicability Bases.

4.g, 5.f. ADS Drywell Pressure Bypass Timer

One of the signals required for ADS initiation is Drywell Pressure-High. However, if the event requiring ADS initiation occurs outside the drywell (for example, main steam line break outside primary containment), a high drywell pressure signal may never be present. Therefore, the ADS Drywell Pressure Bypass Timer is used to bypass the Drywell Pressure-High Function after a certain time period has elapsed. The ADS Drywell Pressure Bypass Timer Function instrumentation is retained in the TS because ADS is part of the primary success path for mitigation of a DBA.

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4.g, 5.f. ADS Drywell Pressure Bypass Time (continued)

There are four ADS Drywell Pressure Bypass Timer relays, two in each of the two ADS trip systems. The Allowable Value for the ADS Timer is chosen to be short enough that so that there is still time after depressurization for the low pressure ECCS subsystems to provide adequate core cooling.

Four channels of the ADS Drywell Pressure Bypass Timer Function are only required to be OPERABLE when the ADS is required to be OPERABLE to ensure that no single instrument failure can preclude ADS initiation. Refer to LCO 3.5.1 for ADS Applicability Bases.

4.h, 5.g. Manual Initiation

The Manual Initiation push button channels introduce signals into the ADS logic to provide manual initiation capability and are redundant to the automatic protective instrumentation. There are two push buttons for each ADS trip system (total of four).

The Manual Initiation Function is not assumed in any accident or transient analyses in the UFSAR. However, the Function is retained for overall redundancy and diversity of the ADS function as required by the NRC in the plant licensing basis.

There is no Allowable Value for this Function since the channel is mechanically actuated based solely on the position of the push buttons. Four channels of the Manual Initiation Function (two channels per ADS trip system) are only required to be OPERABLE when the ADS is required to be OPERABLE. Refer to LCO 3.5.1 for ADS Applicability Bases.

ACTIONS

A Note has been provided to modify the ACTIONS related to ECCS instrumentation channels. Section 1.3, Completion Times, specifies that once a Condition has been entered, subsequent divisions, subsystems, components, or variables expressed in the Condition, discovered to be inoperable or not within limits, will not result in separate entry into the Condition. Section 1.3 also specifies that Required Actions of the Condition continue to apply for each

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additional failure, with Completion Times based on initial entry into the Condition. However, the Required Actions for inoperable ECCS instrumentation channels provide appropriate compensatory measures for separate inoperable Condition entry for each inoperable ECCS instrumentation channel.

A.1

Required Action A.1 directs entry into the appropriate Condition referenced in Table 3.3.5.1-1. The applicable Condition specified in the Table is Function dependent. Each time a channel is discovered to be inoperable, Condition A is entered for that channel and provides for transfer to the appropriate subsequent Condition.

B.1, B.2, and B.3

Required Actions B.1 and B.2 are intended to ensure that appropriate actions are taken if multiple, inoperable, untripped channels within the same Function (or in some cases, within the same variable) result in redundant automatic initiation capability being lost for the feature(s). Loss of redundant automatic capability for the low pressure ECCS injection feature in both divisions occurs when the initiation capability is available to less than two pumps from any single variable. Required Action B.1 features would be those that are initiated by Functions 1.a, 1.b, 2.a, and 2.b (i.e., low pressure ECCS and associated DGs). The Required Action B.2 feature would be HPCS System and associated DG. For Required Action B.1, redundant automatic initiation capability is lost if either (a) one or more Function 1.a channels and one or more Function 2.a channels are inoperable and untripped, or (b) one or more Function 1.b channels and one or more Function 2.b channels are inoperable and untripped. For Divisions 1 and 2, since each inoperable channel would have Required Action B.1 applied separately (refer to ACTIONS Note), each inoperable channel would only require the affected portion of the associated Division of low pressure ECCS and DG to be declared inoperable. However, since channels in both Divisions are inoperable and untripped, and the Completion Times started concurrently for the channels in both

(continued)

BASES

ACTIONS

B.1, B.2, and B.3 (continued)

Divisions, this results in the affected portions in both Divisions of ECCS and DG being concurrently declared inoperable. For Required Action B.2, redundant automatic initiation capability (i.e., loss of automatic start capability for either Functions 3.a or 3.b) is lost if two Function 3.a or two Function 3.b parallel contacts (channels) are inoperable and untripped in the same trip system.

In this situation (loss of redundant automatic initiation capability), the 24 hour allowance of Required Action B.3 is not appropriate and the feature(s) associated with the inoperable, untripped channels must be declared inoperable within 1 hour. As noted (Note 1 to Required Action B.1 and Required Action B.2), the two Required Actions are only applicable in MODES 1, 2, and 3. In MODES 4 and 5, the specific initiation time of the ECCS is not assumed and the probability of a LOCA is lower. Thus, a total loss of initiation capability for 24 hours (as allowed by Required Action B.3) is allowed during MODES 4 and 5. Notes are also provided (Note 2 to Required Action B.1 and Required Action B.2) to delineate which Required Action is applicable for each Function that requires entry into Condition B if an associated channel is inoperable. This ensures that the proper loss of initiation capability check is performed.

The Completion Time is intended to allow the operator time to evaluate and repair any discovered inoperabilities. This Completion Time also allows for an exception to the normal "time zero" for beginning the allowed outage time "clock." For Required Action B.1, the Completion Time only begins upon discovery that a redundant feature in both Divisions (e.g., any Division 1 ECCS and Division 2 ECCS) cannot be automatically initiated due to inoperable, untripped channels within the same variable as described in the paragraph above. For Required Action B.2, the Completion Time only begins upon discovery that the HPCS System cannot be automatically initiated due to two inoperable, untripped channels (parallel contacts) for the associated Function in the same trip system. The 1 hour Completion Time from discovery of loss of initiation capability is acceptable because it minimizes risk while allowing time for restoration or tripping of channels.

(continued)

BASES

ACTIONS B.1, B.2, and B.3 (continued)

Because of the diversity of sensors available to provide initiation signals and the redundancy of the ECCS design, an allowable out of service time of 24 hours has been shown to be acceptable (Ref. 4) to permit restoration of any inoperable channel to OPERABLE status. If the inoperable channel cannot be restored to OPERABLE status within the allowable out of service time, the channel must be placed in the tripped condition per Required Action B.3. Placing the inoperable channel in trip would conservatively compensate for the inoperability, restore capability to accommodate a single failure, and allow operation to continue. Alternately, if it is not desired to place the channel in trip (e.g., as in the case where placing the inoperable channel in trip would result in an initiation), Condition G must be entered and its Required Action taken.

C.1 and C.2

Required Action C.1 is intended to ensure that appropriate actions are taken if multiple, inoperable channels within the same Function (or in some cases, within the same variable) result in redundant automatic initiation capability being lost for the feature(s). Loss of redundant automatic initiation capability for the low pressure ECCS injection feature in both divisions occurs when the initiation capability is available to less than two pumps from any single variable.

Required Action C.1 features would be those that are initiated by Functions 1.c, and 2.c (i.e., low pressure ECCS). For Functions 1.c and 2.c, redundant automatic initiation capability is lost if the Function 1.c and Function 2.c channels are inoperable. Since each inoperable channel would have Required Action C.1 applied separately (refer to ACTIONS Note), each inoperable channel would only require the affected portion of the associated Division to be declared inoperable. However, since channels in both Divisions are inoperable, and the Completion Times started concurrently for the channels in both Divisions, this results in the affected portions in both Divisions being concurrently declared inoperable. For Functions 1.c

(continued)

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ACTIONS

C.1 and C.2 (continued)

and 2.c, the affected portions of the Division are LPCI A and LPCI B, respectively. In addition, the specific inoperability of these Functions should also be evaluated for impact on the DGs.

In this situation (loss of redundant automatic initiation capability), the 24 hour allowance of Required Action C.2 is not appropriate and the feature(s) associated with the inoperable channels must be declared inoperable within 1 hour. As noted (Note 1), the Required Action is only applicable in MODES 1, 2, and 3. In MODES 4 and 5, the specific initiation time of the ECCS is not assumed and the probability of a LOCA is lower. Thus, a total loss of automatic initiation capability for 24 hours (as allowed by Required Action C.2) is allowed during MODES 4 and 5.

Note 2 states that Required Action C.1 is only applicable for Functions 1.c and 2.c. The Required Action is not applicable to Functions 1.h, 2.g, and 3.f (which also require entry into this Condition if a channel in these Functions is inoperable), since they are the Manual Initiation Functions and are not assumed in any accident or transient analysis. Thus, a total loss of manual initiation capability for 24 hours (as allowed by Required Action C.2) is allowed. Required Action C.1 is also not applicable to Function 3.c (which also requires entry into this Condition if a channel in this Function is inoperable), since the loss of the Function was considered during the development of Reference 4 and considered acceptable for the 24 hours allowed by Required Action C.2.

The Completion Time is intended to allow the operator time to evaluate and repair any discovered inoperabilities. This Completion Time also allows for an exception to the normal "time zero" for beginning the allowed outage time "clock." For Required Action C.1, the Completion Time only begins upon discovery that the same feature in both Divisions (i.e., any Division 1 ECCS and Division 2 ECCS) cannot be automatically initiated due to inoperable channels within the same variable as described in the paragraph above. The 1 hour Completion Time from discovery of loss of initiation capability is acceptable because it minimizes risk while allowing time for restoration of channels.

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BASES

ACTIONS C.1 and C.2 (continued)

Because of the diversity of sensors available to provide initiation signals and the redundancy of the ECCS design, an allowable out of service time of 24 hours has been shown to be acceptable (Ref. 4) to permit restoration of any inoperable channel to OPERABLE status. If the inoperable channel cannot be restored to OPERABLE status within the allowable out of service time, Condition G must be entered and its Required Action taken. The Required Actions do not allow placing the channel in trip since this action would either cause the initiation or would not necessarily result in a safe state for the channel in all events.

D.1, D.2, D.3, and D.4

Required Action D.1 is intended to ensure that appropriate actions are taken if multiple, inoperable, channels within the LPCS and LPCI Pump Discharge Flow-Low (Bypass) Functions, the Injection Line Pressure-Low (Injection Permissive), and the Reactor Steam Dome Pressure-Low (Injection Permissive) Functions result in redundant automatic initiation capability being lost for the feature(s). Loss of redundant automatic initiation capability for the low pressure ECCS injection feature in both divisions occurs when the initiation capability is available to less than two pumps from any single variable. For the purposes of this Condition, the injection permissives on Reactor Steam Dome Pressure-Low and Injection Line Pressure-Low are considered the same variable. Similarly, Functions 1.e, 1.f, and 2.e are all minimum flow functions and considered the same variable.

For Required Action D.1, the features would be those that are initiated by Functions 1.d, 1.e, 1.f, 1.g, 2.d, 2.e, and 2.f (e.g., low pressure ECCS). Redundant automatic initiation capability is lost if three of the four channels associated with Functions 1.e, 1.f, and 2.e are inoperable. For Function 1.d, redundant automatic initiation capability is lost if two Function 1.d channels are inoperable concurrent with either two inoperable Function 2.d channels or one inoperable Function 2.f channel. For Function 2.d, redundant automatic initiation capability is lost if two Function 2.d channels are inoperable concurrent with two

(continued)

BASES

ACTIONS

D.1, D.2, D.3, and D.4 (continued)

inoperable 1.d channels or one inoperable 1.g channel. For Function 1.g, redundant automatic initiation capability is lost if two Function 1.g channels are inoperable concurrent with either two inoperable Function 2.d channels or one inoperable Function 2.f channel. For Function 2.f, redundant automatic initiation capability is lost if two Function 2.f channels are inoperable concurrent with two inoperable 1.d channels or one inoperable 1.g channel. Since each inoperable channel would have Required Action D.1 applied separately (refer to ACTIONS Note), each inoperable channel would only require the affected low pressure ECCS pump to be declared inoperable. However, since channels for more than one low pressure ECCS pump are inoperable, and the Completion Times started concurrently for the channels of the low pressure ECCS pumps, this results in the affected low pressure ECCS pumps being concurrently declared inoperable.

In this situation (loss of redundant automatic initiation capability), the Completion Times of Required Actions D.3 and D.4 are not appropriate and the feature(s) associated with each inoperable channel must be declared inoperable within 1 hour after discovery of loss of initiation capability for feature(s) in both Divisions. As noted (Note 1 to Required Action D.1), Required Action D.1 is only applicable in MODES 1, 2, and 3. In MODES 4 and 5, the specific initiation time of the low pressure ECCS is not assumed and the probability of a LOCA is lower. Thus, a total loss of initiation capability for 7 days for Functions 1.e, 1.f, and 2.e (as allowed by Required Action D.4) is allowed during MODES 4 and 5. (This Condition is not entered when Functions 1.d, 1.g, 2.d or 2.f are inoperable in MODES 4 and 5.) A Note is also provided (Note 2 to Required Action D.1) to delineate that Required Action D.1 is only applicable to low pressure ECCS Functions. Required Action D.1 is not applicable to HPCS Functions 3.d and 3.e since the loss of one channel results in a loss of the Function (one-out-of-one logic). This loss was considered during the development of Reference 4 and considered acceptable for the 7 days allowed by Required Action D.4. Required Action D.2 is intended to ensure that appropriate

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BASES

ACTIONS

D.1, D.2, D.3, and D.4 (continued)

actions are taken if multiple, inoperable channels within the Reactor Steam Dome Pressure-Low (Injection Permissive) Function result in automatic initiation capability being lost for the features in one division. For Required Action D.2, the features would be those that are initiated by Functions 1.d and 2.d (e.g., low pressure ECCS). For Functions 1.d and 2.d, automatic initiation capability is lost in one division if two Function 1.d or two Function 2.d channels are inoperable. In this situation, (loss of automatic initiation capability), the 7 day allowance of Required Action D.4 is not appropriate and the features associated with the inoperable channels must be declared inoperable within 24 hours after discovery of loss of initiation capability for features in one division. For Functions 1.g and 2.f, an allowable out of service time of 24 hours is provided by Required Action D.3

The Completion Time is intended to allow the operator time to evaluate and repair any discovered inoperabilities. This Completion Time also allows for an exception to the normal "time zero" for beginning the allowed outage time "clock." For Required Action D.1, the Completion Time only begins upon discovery that three channels of the Pump Discharge Flow-Low (Bypass) Function cannot be automatically initiated due to inoperable channels or upon discovery of a loss of redundant initiation capability for the Reactor Steam Dome Pressure-Low (Injection Permissive) and Injection Line Pressure-Low (Injection Permissive) Functions (as described above). The 1 hour Completion Time from discovery of loss of initiation capability is acceptable because it minimizes risk while allowing time for restoration of channels. For Required Action D.2, the Completion Time only begins upon discovery that two Function 1.d or two Function 2.d channels cannot be automatically initiated due to inoperable channels. The 24 hour Completion Time from discovery of loss of initiation capability for features in one division is acceptable because of the redundancy of the ECCS design, as shown in the reliability analysis of Reference 4.

If the instrumentation that controls the pump minimum flow valve is inoperable such that the valve will not automatically open, extended pump operation with no injection path available could lead to pump overheating and

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BASES

ACTIONS D.1, D.2, D.3, and D.4 (continued)

failure. If there were a failure of the instrumentation such that the valve would not automatically close, a portion of the pump flow could be diverted from the reactor injection path, causing insufficient core cooling. These consequences can be averted by the operator's manual control of the valve, which would be adequate to maintain ECCS pump protection and required flow. Furthermore, other ECCS pumps would be sufficient to complete the assumed safety function if no additional single failure were to occur. If a Reactor Vessel Pressure-Low (Injection Permissive) Function channel is inoperable, another channel exists to ensure the injection valves in the ECCS division can still open. The 7 day Completion Time of Required Action D.4 to restore the inoperable channel to OPERABLE status is reasonable based on the remaining capability of the associated ECCS subsystems, the redundancy available in the ECCS design, and the low probability of a DBA occurring during the allowed out of service time. If the inoperable channel cannot be restored to OPERABLE status within the allowable out of service time, Condition G must be entered and its Required Action taken. The Required Actions do not allow placing the channel in trip since this action would not necessarily result in a safe state for the channel in all events.

E.1 and E.2

Required Action E.1 is intended to ensure that appropriate actions are taken if multiple, inoperable, untripped channels within similar ADS trip system Functions result in automatic initiation capability being lost for the ADS. Automatic initiation capability is lost if either (a) one or more Function 4.a channels and one or more Function 5.a channels are inoperable and untripped, (b) one or more Function 4.b channels and one or more Function 5.b channels are inoperable and untripped, or (c) one Function 4.d channel and one Function 5.d channel are inoperable and untripped.

In this situation (loss of automatic initiation capability), the 96 hour or 8 day allowance, as applicable, of Required Action E.2 is not appropriate, and all ADS valves must be declared inoperable within 1 hour after discovery of loss of ADS initiation capability in both trip systems.

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BASES

ACTIONS E.1 and E.2 (continued)

The Completion Time is intended to allow the operator time to evaluate and repair any discovered inoperabilities. This Completion Time also allows for an exception to the normal "time zero" for beginning the allowed outage time "clock." For Required Action E.1, the Completion Time only begins upon discovery that the ADS cannot be automatically initiated due to inoperable, untripped channels within similar ADS trip system Functions as described in the paragraph above. The 1 hour Completion Time from discovery of loss of initiation capability is acceptable because it minimizes risk while allowing time for restoration or tripping of channels.

Because of the diversity of sensors available to provide initiation signals and the redundancy of the ECCS design, an allowable out of service time of 8 days has been shown to be acceptable (Ref. 4) to permit restoration of any inoperable channel to OPERABLE status if both HPCS and RCIC are OPERABLE. If either HPCS or RCIC is inoperable, the time is shortened to 96 hours. If the status of HPCS or RCIC changes such that the Completion Time changes from 8 days to 96 hours, the 96 hours begins upon discovery of HPCS or RCIC inoperability. However, total time for an inoperable, untripped channel cannot exceed 8 days. If the status of HPCS or RCIC changes such that the Completion Time changes from 96 hours to 8 days, the "time zero" for beginning the 8 day "clock" begins upon discovery of the inoperable, untripped channel. If the inoperable channel cannot be restored to OPERABLE status within the allowable out of service time, the channel must be placed in the tripped condition per Required Action E.2. Placing the inoperable channel in trip would conservatively compensate for the inoperability, restore capability to accommodate a single failure, and allow operation to continue. Alternately, if it is not desired to place the channel in trip (e.g., as in the case where placing the inoperable channel in trip would result in an initiation), Condition G must be entered and its Required Action taken.

(continued)

BASES

ACTIONS
(continued)

F.1 and F.2

Required Action F.1 is intended to ensure that appropriate actions are taken if multiple, inoperable channels within similar ADS trip system Functions result in automatic initiation capability being lost for the ADS. Automatic initiation capability is lost if either (a) one Function 4.c channel and one Function 5.c channel are inoperable, (b) one or more Function 4.e channels and one or more Function 5.e channels are inoperable, (c) one or more Function 4.f channels and one or more Function 5.e channels are inoperable, or (d) one or more Function 4.g channels and one or more Function 5.f channels are inoperable.

In this situation (loss of automatic initiation capability), the 96 hour or 8 day allowance, as applicable, of Required Action F.2 is not appropriate, and all ADS valves must be declared inoperable within 1 hour after discovery of loss of ADS initiation capability in both trip systems. The Note to Required Action F.1 states that Required Action F.1 is only applicable for Functions 4.c, 4.e, 4.f, 4.g, 5.c, 5.e, and 5.f. Required Action F.1 is not applicable to Functions 4.h and 5.g (which also require entry into this Condition if a channel in these Functions is inoperable), since they are the Manual Initiation Functions and are not assumed in any accident or transient analysis. Thus, a total loss of manual initiation capability for 96 hours or 8 days (as allowed by Required Action F.2) is allowed.

The Completion Time is intended to allow the operator time to evaluate and repair any discovered inoperabilities. This Completion Time also allows for an exception to the normal "time zero" for beginning the allowed outage time "clock." For Required Action F.1, the Completion Time only begins upon discovery that the ADS cannot be automatically initiated due to inoperable channels within similar ADS trip system Functions, as described in the paragraph above. The 1 hour Completion Time from discovery of loss of initiation capability is acceptable because it minimizes risk while allowing time for restoration or tripping of channels.

Because of the diversity of sensors available to provide initiation signals and the redundancy of the ECCS design, an allowable out of service time of 8 days has been shown to be acceptable (Ref. 4) to permit restoration of any inoperable

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BASES

ACTIONS

F.1 and F.2 (continued)

channel to OPERABLE status if both HPCS and RCIC are OPERABLE (Required Action F.2). If either HPCS or RCIC is inoperable, the time is reduced to 96 hours. If the status of HPCS or RCIC changes such that the Completion Time changes from 8 days to 96 hours, the 96 hours begins upon discovery of HPCS or RCIC inoperability. However, total time for an inoperable channel cannot exceed 8 days. If the status of HPCS or RCIC changes such that the Completion Time changes from 96 hours to 8 days, the "time zero" for beginning the 8 day "clock" begins upon discovery of the inoperable channel. If the inoperable channel cannot be restored to OPERABLE status within the allowable out of service time, Condition G must be entered and its Required Action taken. The Required Actions do not allow placing the channel in trip since this action would not necessarily result in a safe state for the channel in all events.

G.1

With any Required Action and associated Completion Time not met, the associated feature(s) may be incapable of performing the intended function and the supported feature(s) associated with the inoperable untripped channels must be declared inoperable immediately.

SURVEILLANCE
REQUIREMENTS

As noted at the beginning of the SRs, the SRs for each ECCS instrumentation Function are found in the SRs column of Table 3.3.5.1-1.

The Surveillances are modified by a Note to indicate that when a channel is placed in an inoperable status solely for performance of required Surveillances, entry into associated Conditions and Required Actions may be delayed for up to 6 hours as follows: (a) for Functions 3.c, 3.d, 3.e, and 3.f; and (b) for Functions other than 3.c, 3.d, 3.e, and 3.f provided the associated Function or redundant Function maintains ECCS initiation capability. Upon completion of the Surveillance, or expiration of the 6 hour allowance, the channel must be returned to OPERABLE status or the applicable Condition entered and Required Actions taken. This Note is based on the reliability analysis

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BASES

SURVEILLANCE
REQUIREMENTS
(continued)

(Ref. 4) assumption of the average time required to perform channel Surveillance. That analysis demonstrated that the 6 hour testing allowance does not significantly reduce the probability that the ECCS will initiate when necessary.

SR 3.3.5.1.1

Performance of the CHANNEL CHECK once every 12 hours ensures that a gross failure of instrumentation has not occurred. A CHANNEL CHECK is normally a comparison of the parameter indicated on one channel to a similar parameter on other channels. It is based on the assumption that instrument channels monitoring the same parameter should read approximately the same value. Significant deviations between the instrument channels could be an indication of excessive instrument drift in one of the channels or something even more serious. A CHANNEL CHECK will detect gross channel failure; thus, it is key to verifying the instrumentation continues to operate properly between each CHANNEL CALIBRATION.

Agreement criteria are determined by the plant staff, based on a combination of the channel instrument uncertainties, including indication and readability. If a channel is outside the criteria, it may be an indication that the instrument has drifted outside its limit.

The Frequency is based upon operating experience that demonstrates channel failure is rare. The CHANNEL CHECK supplements less formal, but more frequent, checks of channels during normal operational use of the displays associated with the channels required by the LCO.

SR 3.3.5.1.2

A CHANNEL FUNCTIONAL TEST is performed on each required channel to ensure that the channel will perform the intended function. A successful test of the required contact(s) of a channel relay may be performed by the verification of the change of state of a single contact of the relay. This

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BASES

SURVEILLANCE
REQUIREMENTS

SR 3.3.5.1.2 (continued)

clarifies what is an acceptable CHANNEL FUNCTIONAL TEST of a relay. This is acceptable because all of the other required contacts of the relay are verified by other Technical Specifications and non-Technical Specifications tests at least once per refueling interval with applicable extensions.

Any setpoint adjustment shall be consistent with the assumptions of the current plant specific setpoint methodology.

The Frequency of 92 days is based on the reliability analyses of Reference 4.

SR 3.3.5.1.3 and SR 3.3.5.1.4

A CHANNEL CALIBRATION is a complete check of the instrument loop and the sensor. This test verifies the channel responds to the measured parameter within the necessary range and accuracy. CHANNEL CALIBRATION leaves the channel adjusted to account for instrument drifts between successive calibrations consistent with the plant specific setpoint methodology.

The Frequency of SR 3.3.5.1.3 is based upon the assumption of a 92 day calibration interval in the determination of the magnitude of equipment drift in the setpoint analysis. The Frequency of SR 3.3.5.1.4 is based upon the assumption of a 24 month calibration interval in the determination of the magnitude of equipment drift in the setpoint analysis.

SR 3.3.5.1.5

The LOGIC SYSTEM FUNCTIONAL TEST demonstrates the OPERABILITY of the required initiation logic for a specific channel. The system functional testing performed in LCO 3.5.1, LCO 3.5.2, LCO 3.8.1, and LCO 3.8.2 overlaps this Surveillance to provide complete testing of the assumed safety function.

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BASES

SURVEILLANCE
REQUIREMENTS

SR 3.3.5.1.5 (continued)

The 24 month Frequency is based on the need to perform this Surveillance under the conditions that apply during a plant outage and the potential for unplanned transients if the Surveillance were performed with the reactor at power. Operating experience has shown these components usually pass the Surveillance when performed at the 24 month Frequency.

SR 3.3.5.1.6

This SR ensures that the individual channel response times are less than or equal to the maximum values assumed in the accident analysis. Response time testing acceptance criteria are included in Reference 5.

ECCS RESPONSE TIME may be verified by actual response time measurements in any series of sequential, overlapping, or total channel measurements. However, the measurement of instrument loop response times may be excluded if the conditions of Reference 6 are satisfied. If these conditions are satisfied, instrument loop response time may be allocated based on either assumed design instrument loop response time or the manufacturer's stated design instrument loop response time. When the requirements of Reference 6 are not satisfied, instrument loop response time must be measured. The instrument loop response times must be added to the remaining equipment response times (e.g., ECCS pump start time) to obtain the ECCS RESPONSE TIME. However, failure to meet the ECCS RESPONSE TIME due to a component other than instrumentation not within limits does not require the associated instrumentation to be declared inoperable; only the affected component (e.g., ECCS pump) is required to be declared inoperable.

ECCS RESPONSE TIME tests are conducted on a 24 month STAGGERED TEST BASIS. The 24 month Frequency is consistent with the refueling cycle and is based upon plant operating experience, which shows that random failures of instrumentation components causing serious response time degradation, but not channel failure, are infrequent.

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BASES (continued)

- REFERENCES
1. UFSAR, Section 5.2.
 2. UFSAR, Section 6.3.
 3. UFSAR, Chapter 15.
 4. NEDC-30936-P-A, "BWR Owners' Group Technical Specification Improvement Analyses for ECCS Actuation Instrumentation, Parts 1 and 2," December 1988.
 5. Technical Requirements Manual.
 6. NEDO-32291-A, "System Analyses for the Elimination of Selected Response Time Testing Requirements," October 1995.
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B 3.3 INSTRUMENTATION

B 3.3.5.2 Reactor Core Isolation Cooling (RCIC) System Instrumentation

BASES

BACKGROUND

The purpose of the RCIC System instrumentation is to initiate actions to ensure adequate core cooling when the reactor vessel is isolated from its primary heat sink (the main condenser) and normal coolant makeup flow from the Reactor Feedwater System is insufficient or unavailable, such that RCIC System initiation occurs and maintains sufficient reactor water level precluding initiation of the low pressure Emergency Core Cooling Systems (ECCS) pumps. A more complete discussion of RCIC System operation is provided in the Bases of LCO 3.5.3, "RCIC System."

The RCIC System may be initiated by either automatic or manual means. Automatic initiation occurs for conditions of Reactor Vessel Water Level Low-Low, Level 2. The variable is monitored by four differential pressure transmitters that are connected to four trip units. The outputs of the trip units are connected to relays whose contacts are arranged in a one-out-of-two taken twice logic arrangement. The logic can also be initiated by use of a manual push button. Once initiated, the RCIC logic seals in and can be reset by the operator only when the reactor vessel water level signals have cleared.

The RCIC test line isolation valve is closed on a RCIC initiation signal to allow full system flow to the reactor vessel.

The RCIC System also monitors the water level in the condensate storage tank (CST), since there are two sources of water for RCIC operation. Reactor grade water in the CST is the normal source. Upon receipt of a RCIC initiation signal, the CST suction valve is automatically signaled to open (it is normally in the open position) unless the pump suction from the suppression pool valve is open. If the water level in the CST falls below a preselected level, first the suppression pool suction valve automatically opens and then the CST suction valve automatically closes. Two level switches are used to detect low water level in the CST. Either switch can cause the suppression pool suction valve to open. To prevent losing suction to the pump,

(continued)

BASES

BACKGROUND (continued) the suction valves are interlocked so that one suction path must be open before the other automatically closes.

The RCIC System provides makeup water to the reactor until the reactor vessel water level reaches the high water level (Level 8) trip (two-out-of-two logic), at which time the RCIC turbine steam inlet isolation valve closes (the injection valve also closes due to the closure of the RCIC turbine steam inlet isolation valve). The RCIC System restarts if vessel level again drops to the low level initiation point (Level 2).

APPLICABLE SAFETY ANALYSES, LCO, and APPLICABILITY

The function of the RCIC System, to provide makeup coolant to the reactor, is to respond to transient events. The RCIC System is not an Engineered Safety Feature System and no credit is taken in the safety analysis for RCIC System operation. Based on its contribution to the reduction of overall plant risk, however, the RCIC System, and therefore its instrumentation, meets Criterion 4 of 10 CFR 50.36(c)(2)(ii). Certain instrumentation Functions are retained for other reasons and are described below in the individual Functions discussion.

The OPERABILITY of the RCIC System instrumentation is dependent on the OPERABILITY of the individual instrumentation channel Functions specified in Table 3.3.5.2-1. Each Function must have a required number of OPERABLE channels with their setpoints within the specified Allowable Values, where appropriate. The actual setpoint is calibrated consistent with applicable setpoint methodology assumptions.

Allowable Values are specified for each RCIC System instrumentation Function specified in the Table. Nominal trip setpoints are specified in the setpoint calculations. The nominal setpoints are selected to ensure that the setpoints do not exceed the Allowable Value between CHANNEL CALIBRATIONS. Operation with a trip setpoint less conservative than the nominal trip setpoint, but within its Allowable Value, is acceptable. A channel is inoperable if its actual trip setpoint is not within its required Allowable Value.

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BASES

APPLICABLE
SAFETY ANALYSES,
LCO, and
APPLICABILITY
(continued)

Trip setpoints are those predetermined values of output at which an action should take place. The setpoints are compared to the actual process parameter (e.g., reactor vessel water level), and when the measured output value of the process parameter exceeds the setpoint, the associated device (e.g., trip unit) changes state. The analytic limits (or design limits) are derived from the limiting values of the process parameters obtained from the safety analysis. The trip setpoints are determined from the analytic limits, corrected for defined process, calibration, and instrument errors. The Allowable Values are then determined, based on the trip setpoint values, by accounting for the calibration based errors. These calibration based errors are limited to reference accuracy, instrument drift, errors associated with measurement and test equipment, and calibration tolerance of loop components. The trip setpoints and Allowable Values determined in this manner provide adequate protection because instrument uncertainties, process effects, calibration tolerances, instrument drift, and severe environment errors (for channels that must function in harsh environments as defined by 10 CFR 50.49) are accounted for and appropriately applied for the instrumentation.

The individual Functions are required to be OPERABLE in MODE 1, and in MODES 2 and 3 with reactor steam dome pressure > 150 psig, since this is when RCIC is required to be OPERABLE. Refer to LCO 3.5.3 for Applicability Bases for the RCIC System.

The specific Applicable Safety Analyses, LCO, and Applicability discussions are listed below on a Function by Function basis.

1. Reactor Vessel Water Level - Low Low, Level 2

Low reactor pressure vessel (RPV) water level indicates that normal feedwater flow is insufficient to maintain reactor vessel water level and that the capability to cool the fuel may be threatened. Should RPV water level decrease too far, fuel damage could result. Therefore, the RCIC System is initiated at Level 2 to assist in maintaining water level above the top of the active fuel.

(continued)

BASES

APPLICABLE
SAFETY ANALYSES,
LCO, and
APPLICABILITY

1. Reactor Vessel Water Level – Low Low, Level 2
(continued)

Reactor Vessel Water Level – Low Low, Level 2 signals are initiated from four differential pressure transmitters that sense the difference between the pressure due to a constant column of water (reference leg) and the pressure due to the actual water level (variable leg) in the vessel.

The Reactor Vessel Water Level – Low Low, Level 2 Allowable Value is set high enough such that for complete loss of feedwater flow, the RCIC System flow with high pressure core spray assumed to fail will be sufficient to avoid initiation of low pressure ECCS at Level 1.

Four channels of Reactor Vessel Water Level – Low Low, Level 2 Function are available and are required to be OPERABLE when RCIC is required to be OPERABLE to ensure that no single instrument failure can preclude RCIC initiation. Refer to LCO 3.5.3 for RCIC Applicability Bases.

2. Reactor Vessel Water Level – High, Level 8

High RPV water level indicates that sufficient cooling water inventory exists in the reactor vessel such that there is no danger to the fuel. Therefore, the Level 8 signal is used to close the RCIC turbine steam inlet isolation valve to prevent overflow into the main steam lines (MSLs). (The injection valve also closes due to the closure of the RCIC turbine steam inlet isolation valve.)

Reactor Vessel Water Level – High, Level 8 signals for RCIC are initiated from two differential pressure transmitters from the narrow range water level measurement instrumentation, which sense the difference between the pressure due to a constant column of water (reference leg) and the pressure due to the actual water level (variable leg) in the vessel.

The Reactor Vessel Water Level – High, Level 8 Allowable Value is high enough to preclude isolating the injection valve of the RCIC during normal operation, yet low enough to trip the RCIC System prior to water overflowing into the MSLs.

(continued)

BASES

APPLICABLE
SAFETY ANALYSES,
LCO, and
APPLICABILITY

2. Reactor Vessel Water Level – High, Level 8 (continued)

Two channels of Reactor Vessel Water Level – High, Level 8 Function are available and are required to be OPERABLE when RCIC is required to be OPERABLE to ensure that no single instrument failure can preclude RCIC initiation. Refer to LCO 3.5.3 for RCIC Applicability Bases.

3. Condensate Storage Tank Level – Low

Low level in the CST indicates the unavailability of an adequate supply of makeup water from this normal source. Normally the suction valve between the RCIC pump and the CST is open and, upon receiving a RCIC initiation signal, water for RCIC injection would be taken from the CST. However, if the water level in the CST falls below a preselected level, first the suppression pool suction valve automatically opens and then the CST suction valve automatically closes. This ensures that an adequate supply of makeup water is available to the RCIC pump. To prevent losing suction to the pump, the suction valves are interlocked so that the suppression pool suction valve must be open before the CST suction valve automatically closes.

Two level switches are used to detect low water level in the CST. The Condensate Storage Tank Level – Low Function Allowable Value is set high enough to ensure adequate pump suction head while water is being taken from the CST.

Two channels of Condensate Storage Tank Level – Low Function are available and are required to be OPERABLE when RCIC is required to be OPERABLE to ensure that no single instrument failure can preclude RCIC swap to suppression pool source. Refer to LCO 3.5.3 for RCIC Applicability Bases.

4. Manual Initiation

The Manual Initiation push button channel introduces a signal into the RCIC System initiation logic that is redundant to the automatic protective instrumentation and provides manual initiation capability. There is one push button channel for the RCIC System.

(continued)

BASES

APPLICABLE
SAFETY ANALYSES,
LCO, and
APPLICABILITY

4. Manual Initiation (continued)

The Manual Initiation Function is not assumed in any accident or transient analyses in the UFSAR. However, the Function is retained for overall redundancy and diversity of the RCIC function as required by the NRC in the plant licensing basis.

There is no Allowable Value for this Function since the channel is mechanically actuated based solely on the position of the push button. One channel of Manual Initiation is required to be OPERABLE when RCIC is required to be OPERABLE. Refer to LCO 3.5.3 for RCIC Applicability Bases.

ACTIONS

A Note has been provided to modify the ACTIONS related to RCIC System instrumentation channels. Section 1.3, Completion Times, specifies that once a Condition has been entered, subsequent divisions, subsystems, components, or variables expressed in the Condition discovered to be inoperable or not within limits will not result in separate entry into the Condition. Section 1.3 also specifies that Required Actions of the Condition continue to apply for each additional failure, with Completion Times based on initial entry into the Condition. However, the Required Actions for inoperable RCIC System instrumentation channels provide appropriate compensatory measures for separate inoperable channels. As such, a Note has been provided that allows separate Condition entry for each inoperable RCIC System instrumentation channel.

A.1

Required Action A.1 directs entry into the appropriate Condition referenced in Table 3.3.5.2-1 in the accompanying LCO. The applicable Condition referenced in the Table is Function dependent. Each time a channel is discovered to be inoperable, Condition A is entered for that channel and provides for transfer to the appropriate subsequent Condition.

(continued)

BASES

ACTIONS
(continued)

B.1 and B.2

Required Action B.1 is intended to ensure that appropriate actions are taken if multiple, inoperable, untripped channels within the same Function result in a complete loss of automatic initiation capability for the RCIC System. In this case, automatic initiation capability is lost if two Function 1 parallel contacts (channels) in the same trip system are inoperable and untripped. In this situation (loss of automatic initiation capability), the 24 hour allowance of Required Action B.2 is not appropriate, and the RCIC System must be declared inoperable within 1 hour after discovery of loss of RCIC initiation capability.

The Completion Time is intended to allow the operator time to evaluate and repair any discovered inoperabilities. This Completion Time also allows for an exception to the normal "time zero" for beginning the allowed outage time "clock." For Required Action B.1, the Completion Time only begins upon discovery that the RCIC System cannot be automatically initiated due to two inoperable, untripped Reactor Vessel Water Level-Low Low, Level 2 channels (parallel contacts) in the same trip system. The 1 hour Completion Time from discovery of loss of initiation capability is acceptable because it minimizes risk while allowing time for restoration or tripping of channels.

Because of the redundancy of sensors available to provide initiation signals and the fact that the RCIC System is not credited in any accident or transient analysis, an allowable out of service time of 24 hours has been shown to be acceptable (Ref. 1) to permit restoration of any inoperable channel to OPERABLE status. If the inoperable channel cannot be restored to OPERABLE status within the allowable out of service time, the channel must be placed in the tripped condition per Required Action B.2. Placing the inoperable channel in trip would conservatively compensate for the inoperability, restore capability to accommodate a single failure, and allow operation to continue. Alternately, if it is not desired to place the channel in trip (e.g., as in the case where placing the inoperable channel in trip would result in an initiation), Condition E must be entered and its Required Action taken.

(continued)

BASES

ACTIONS
(continued)

C.1

A risk based analysis was performed and determined that an allowable out of service time of 24 hours (Ref. 1) is acceptable to permit restoration of any inoperable channel to OPERABLE status (Required Action C.1). A Required Action (similar to Required Action B.1), limiting the allowable out of service time if a loss of automatic RCIC initiation capability exists, is not required. This Condition applies to the Reactor Vessel Water Level-High, Level 8 Function, whose logic is arranged such that any inoperable channel will result in a loss of automatic RCIC initiation (high water level trip) capability. As stated above, this loss of automatic RCIC initiation (high water level trip) capability was analyzed and determined to be acceptable. This Condition also applies to the Manual Initiation Function. Since this Function is not assumed in any accident or transient analysis, a total loss of manual initiation capability (Required Action C.1) for 24 hours is allowed. The Required Action does not allow placing a channel in trip since this action would not necessarily result in the safe state for the channel in all events.

D.1, D.2.1, and D.2.2

Required Action D.1 is intended to ensure that appropriate actions are taken if multiple inoperable, untripped channels within the same Function result in automatic component initiation (RCIC source swapover) capability being lost for the feature(s). For Required Action D.1, the RCIC System is the only associated feature. In this case, automatic component initiation (RCIC source swapover) capability is lost if two Function 3 channels are inoperable and untripped. In this situation (loss of automatic suction swap), the 24 hour allowance of Required Actions D.2.1 and D.2.2 is not appropriate, and the RCIC System must be declared inoperable within 1 hour from discovery of loss of RCIC initiation capability. As noted, Required Action D.1 is only applicable if the RCIC pump suction is not aligned to the suppression pool since, if aligned, the Function is already performed.

(continued)

BASES

ACTIONS D.1, D.2.1, and D.2.2 (continued)

The Completion Time is intended to allow the operator time to evaluate and repair any discovered inoperabilities. This Completion Time also allows for an exception to the normal "time zero" for beginning the allowed outage time "clock." For Required Action D.1, the Completion Time only begins upon discovery that the RCIC System cannot be automatically aligned to the suppression pool due to two inoperable, untripped channels in the same Function. The 1 hour Completion Time from discovery of loss of initiation capability is acceptable because it minimizes risk while allowing time for restoration or tripping of channels.

Because of the redundancy of sensors available to provide initiation signals and the fact that the RCIC System is not assumed in any accident or transient analysis, an allowable out of service time of 24 hours has been shown to be acceptable (Ref. 1) to permit restoration of any inoperable channel to OPERABLE status. If the inoperable channel cannot be restored to OPERABLE status within the allowable out of service time, the channel must be placed in the tripped condition per Required Action D.2.1, which performs the intended function of the channel (shifting the suction source to the suppression pool). Alternatively, Required Action D.2.2 allows the manual alignment of the RCIC suction to the suppression pool, which also performs the intended function. If Required Action D.2.1 or D.2.2 is performed, measures should be taken to ensure that the RCIC System piping remains filled with water. If it is not desired to perform Required Actions D.2.1 and D.2.2 (e.g., as in the case where shifting the suction source could drain down the RCIC suction piping), Condition E must be entered and its Required Action taken.

E.1

With any Required Action and associated Completion Time not met, the RCIC System may be incapable of performing the intended function, and the RCIC System must be declared inoperable immediately.

(continued)

BASES (continued)

SURVEILLANCE
REQUIREMENTS

As noted in the beginning of the SRs, the SRs for each RCIC System instrumentation Function are found in the SRs column of Table 3.3.5.2-1.

The Surveillances are modified by a Note to indicate that when a channel is placed in an inoperable status solely for performance of required Surveillances, entry into associated Conditions and Required Actions may be delayed as follows: (a) for up to 6 hours for Functions 2 and 4; and (b) for up to 6 hours for Functions 1 and 3 provided the associated Function maintains RCIC initiation capability. Upon completion of the Surveillance, or expiration of the 6 hour allowance, the channel must be returned to OPERABLE status or the applicable Condition entered and Required Actions taken. This Note is based on the reliability analysis (Ref. 1) assumption of the average time required to perform channel Surveillance. That analysis demonstrated that the 6 hour testing allowance does not significantly reduce the probability that the RCIC will initiate when necessary.

SR 3.3.5.2.1

Performance of the CHANNEL CHECK once every 12 hours ensures that a gross failure of instrumentation has not occurred. A CHANNEL CHECK is normally a comparison of the parameter indicated on one channel to a similar parameter on other channels. It is based on the assumption that instrument channels monitoring the same parameter should read approximately the same value. Significant deviations between the instrument channels could be an indication of excessive instrument drift in one of the channels or something even more serious. A CHANNEL CHECK will detect gross channel failure; thus, it is key to verifying that the instrumentation continues to operate properly between each CHANNEL CALIBRATION.

Agreement criteria are determined by the plant staff based on a combination of the channel instrument uncertainties, including indication and readability. If a channel is outside the criteria, it may be an indication that the instrument has drifted outside its limit.

(continued)

BASES

SURVEILLANCE
REQUIREMENTS

SR 3.3.5.2.1 (continued)

The Frequency is based upon operating experience that demonstrates channel failure is rare. The CHANNEL CHECK supplements less formal, but more frequent, checks of channels during normal operational use of the displays associated with the channels required by the LCO.

SR 3.3.5.2.2

A CHANNEL FUNCTIONAL TEST is performed on each required channel to ensure that the channel will perform the intended function. A successful test of the required contact(s) of a channel relay may be performed by the verification of the change of state of a single contact of the relay. This clarifies what is an acceptable CHANNEL FUNCTIONAL TEST of a relay. This is acceptable because all of the other required contacts of the relay are verified by other Technical Specifications and non-Technical Specifications tests at least once per refueling interval with applicable extensions. Any setpoint adjustment shall be consistent with the assumptions of the current plant specific setpoint methodology.

The Frequency of 92 days is based on the reliability analysis of Reference 1.

SR 3.3.5.2.3

CHANNEL CALIBRATION is a complete check of the instrument loop and the sensor. This test verifies the channel responds to the measured parameter with the necessary range and accuracy. CHANNEL CALIBRATION leaves the channel adjusted to account for instrument drifts between successive calibrations consistent with the plant specific setpoint methodology.

The Frequency is based on the assumption of a 24 month calibration interval in the determination of the magnitude of equipment drift in the setpoint analysis.

(continued)

BASES

SURVEILLANCE
REQUIREMENTS
(continued)

SR 3.3.5.2.4

The LOGIC SYSTEM FUNCTIONAL TEST demonstrates the OPERABILITY of the required initiation logic for a specific channel. The system functional testing performed in LCO 3.5.3 overlaps this Surveillance to provide complete testing of the safety function.

The 24 month Frequency is based on the need to perform this Surveillance under the conditions that apply during a plant outage and the potential for an unplanned transient if the Surveillance were performed with the reactor at power. Operating experience has shown that these components usually pass the Surveillance when performed at the 24 month Frequency.

REFERENCES

1. GENE-770-06-2-A, "Addendum to Bases for Changes to Surveillance Test Intervals and Allowed Out-of-Service Times for Selected Instrumentation Technical Specifications," December 1992.
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B 3.3 INSTRUMENTATION

B 3.3.6.1 Primary Containment Isolation Instrumentation

BASES

BACKGROUND

The primary containment isolation instrumentation automatically initiates closure of appropriate primary containment isolation valves (PCIVs). The function of the PCIVs, in combination with other accident mitigation systems, is to limit fission product release during and following postulated Design Basis Accidents (DBAs). Primary containment isolation within the time limits specified for those isolation valves designed to close automatically ensures that the release of radioactive material to the environment will be consistent with the assumptions used in the analyses for a DBA.

The isolation instrumentation includes the sensors, relays, and switches that are necessary to cause initiation of primary containment and reactor coolant pressure boundary (RCPB) isolation. Most channels include electronic equipment (e.g., trip units) that compares measured input signals with pre-established setpoints. When the setpoint is exceeded, the channel output relay actuates, which then outputs a primary containment isolation signal to the isolation logic. Functional diversity is provided by monitoring a wide range of independent parameters. The input parameters to the isolation logic are (a) reactor vessel water level, (b) area and differential temperatures, (c) main steam line (MSL) flow measurement, (d) Standby Liquid Control (SLC) System initiation, (e) condenser vacuum loss, (f) main steam line pressure, (g) reactor core isolation cooling (RCIC) steam line flow and time delay relay, (h) reactor building ventilation exhaust plenum and fuel pool ventilation exhaust radiation, (i) RCIC steam line pressure, (j) RCIC turbine exhaust diaphragm pressure, (k) reactor water cleanup (RWCU) differential flow and time delay relay, (l) reactor vessel pressure, and (m) drywell pressure. Redundant sensor input signals are provided from each such isolation initiation parameter. In addition, manual isolation of the logics is provided.

The primary containment isolation instrumentation has inputs to the trip logic from the isolation Functions listed below.

(continued)

BASES

BACKGROUND
(continued)

1. Main Steam Line Isolation

Most Main Steam Line Isolation Functions receive inputs from four channels. One channel associated with each Function inputs to one of four trip strings. Two trip strings make up a trip system and both trip systems must actuate to cause isolation of all main steam isolation valves (MSIVs). Any channel will trip the associated trip string. Only one trip string must trip to trip the associated trip system. The trip strings are arranged in one-out-of-two taken twice logic to initiate isolation of all MSIVs. The outputs from the same channels are arranged into two two-out-of-two trip systems to isolate all MSL drain valves. One two-out-of-two trip system is associated with the inboard valves and the other two-out-of-two trip system is associated with the outboard valves.

One exception to this arrangement is the Main Steam Line Flow-High Function. This Function uses 16 flow channels, four for each steam line. One channel from each steam line inputs to one of four trip strings. Two trip strings make up each trip system, and both trip systems must trip to cause an MSL isolation. Each trip string has four inputs (one per MSL), any one of which will trip the trip string. The trip strings are arranged in a one-out-of-two taken twice logic. Therefore, this is effectively a one-out-of-eight taken twice logic arrangement to initiate isolation of the MSIVs. Similarly, the 16 flow channels are connected into two two-out-of-two trip systems (effectively, two one-out-of-four twice logic), with one trip system isolating the inboard MSL drain valves and the other two-out-of-two trip system isolating the outboard MSL drain valves.

The other exception to this arrangement is the Manual Initiation Function. The MSIV manual isolation logic is similar to the other MSIV isolation logic in that each trip string is associated with a manual isolation pushbutton in a one-out-of-two taken twice logic as described above. However, the MSL drain isolation valves are isolated by a single manual isolation pushbutton; the outboard MSL drain isolation valves isolate from the B channel manual isolation pushbutton and the inboard MSL drain valve isolates from the D channel manual isolation pushbutton. The A and C channel manual isolation pushbuttons only directly affect the manual

(continued)

BASES

BACKGROUND

1. Main Steam Line Isolation (continued)

isolation of the MSIVs. The same channel B and D manual isolation pushbuttons are used for the logic of other Group isolation valves.

MSL Isolation Functions isolate the Group 1 valves.

2. Primary Containment Isolation

Most Primary Containment Isolation Functions receive inputs from four channels. The outputs from these channels are arranged into two two-out-of-two trip systems. One trip system initiates isolation of all automatic inboard PCIVs, while the other trip system initiates isolation of all automatic outboard PCIVs. Each trip system closes one of the two valves on each penetration with automatic isolation so that operation of either trip system isolates the penetration. An exception to this arrangement are the Traversing In-core Probe (TIP) System valve/drives. For these valves and drive mechanisms, only one trip system (the inboard valve system) is provided. When the trip system actuates, the drive mechanisms withdraw the TIPs and, when the TIPs are fully withdrawn, the ball valves close. This exception to the arrangement, which has been previously approved by the NRC as part of the issuance of the Operating Licenses, is described in UFSAR Table 6.2-21 (Ref. 1).

Reactor Vessel Water Level—Low, Level 3 isolates the Group 7 valves. Reactor Vessel Water Level—Low Low, Level 2 isolates the Group 2, 3, and 4 valves. Reactor Vessel Water Level—Low Low Low, Level 1 isolates the Group 10 valves. Drywell Pressure—High isolates the Group 2, 4, 7, and 10 valves. Reactor Building Ventilation Exhaust Plenum Radiation—High isolates the Group 4 valves. Fuel Pool Ventilation Exhaust Radiation—High isolates the Group 4 valves. Manual Initiation Functions isolate the Group 2, 4, 7, and 10 valves.

3. Reactor Core Isolation Cooling System Isolation

Most Functions receive input from two channels, with each channel in one trip system using one-out-of-one logic. One of the two trip systems is connected to the inboard steam

(continued)

BASES

BACKGROUND

3. Reactor Core Isolation Cooling System Isolation
(continued)

valves and the other trip system is connected to the outboard steam valve on the RCIC penetration so that operation of either trip system isolates the penetration. Two exceptions to this arrangement are the RCIC Steam Supply Pressure-Low and RCIC Turbine Exhaust Diaphragm Pressure-High Functions. These Functions receive input from four steam supply pressure channels and four turbine exhaust diaphragm pressure channels, respectively. The outputs from these channels are connected into two two-out-of-two trip systems, each trip system isolating the inboard or outboard RCIC steam valves. In addition, the RCIC System Isolation Manual Initiation Function has only one channel, which isolates the outboard RCIC steam valve only (provided an automatic initiation signal is present). One additional exception involves the Drywell Pressure-High Function and the RCIC Steam Supply Pressure-Low Functions. The Drywell Pressure-High Function does not provide an isolation to the inboard and outboard RCIC steam valves (Group 8 valves). The logic is arranged such that RCIC Steam Supply Pressure-Low coincident with Drywell Pressure-High isolates the Group 9 valves. The Drywell Pressure-High Function receives inputs from four drywell pressure channels. The outputs from these channels are connected into two one-out-of-two trip systems with coincident RCIC Steam Supply Pressure also connected into the same trip systems arranged in a similar manner (one-out-of-two). One of the two trip systems is connected to the inboard RCIC turbine exhaust vacuum breaker line isolation valve and the other trip system is connected to the outboard RCIC turbine exhaust vacuum breaker line isolation valve (Group 9 valves).

RCIC System Isolation Functions isolate the Group 8 and 9 valves.

4. Reactor Water Cleanup System Isolation

Most Functions receive input from two channels with each channel in one trip system using one-out-of-one logic. Functions 4.c, 4.d, 4.e and 4.f (RWCU Heat Exchanger Area Temperature-High, RWCU Heat Exchanger Area Ventilation Differential Temperature-High, RWCU Pump and Valve Area

(continued)

BASES

BACKGROUND

4. Reactor Water Cleanup System Isolation (continued)

Temperature-High, and RWCU Pump and Valve Area Ventilation Differential Temperature-High, respectively) have one channel in each trip system in each area for a total of four channels per Function, for Functions 4.c and 4.d and a total of six channels per Function for Functions 4.e and 4.f, but the logic is the same (one-out-of-one per area). Each of the two trip systems is connected to one of the two valves on the RWCU penetration so that operation of either trip system isolates the penetration. The exceptions to this arrangement are the Reactor Vessel Water Level-Low Low, Level 2 and the SLC System Initiation Functions. The Reactor Vessel Water Level-Low Low, Level 2 Function receives input from four reactor vessel water level channels. The outputs from the reactor vessel water level channels are connected into two two-out-of-two trip systems, each trip system isolating one of the two RWCU valves. The Standby Liquid Control (SLC) System initiation has two channels, one from each SLC pump start circuit, in a single trip system. The two channels are connected in a one-out-of-two logic. This trip system isolates the RWCU inlet outboard valve.

RWCU Isolation Functions isolate the Group 5 valves.

5. RHR Shutdown Cooling System Isolation

The Shutdown Cooling Isolation Function receives input signals from instrumentation for the Reactor Vessel Water Level-Low, Level 3, Reactor Vessel Pressure-High, and Manual Initiation Functions. The Reactor Vessel Water Level-Low Function receives input from four channels while the Reactor Vessel Pressure-High Function receives input from two channels. The outputs from the Reactor Vessel Water Level-Low channels are connected into two two-out-of-two trip systems. The Reactor Vessel Pressure-High Function is arranged into two one-out-of-one trip systems. The Manual Initiation Function uses two channels, one for each trip system.

(continued)

BASES

BACKGROUND 5. Shutdown Cooling System Isolation (continued)

One of the two trip systems is connected to the outboard valve associated with the reactor vessel head spray injection penetration, the shutdown cooling return penetration, and the shutdown cooling suction penetration while the other trip system is connected to the inboard valves on the shutdown cooling suction penetration and the shutdown cooling return check valve bypasses.

The RHR Shutdown Cooling Isolation Functions isolate the Group 6 valves.

APPLICABLE
SAFETY ANALYSES,
LCO, and
APPLICABILITY

The isolation signals generated by the primary containment isolation instrumentation are implicitly assumed in the safety analyses of References 2 and 3 to initiate closure of valves to limit offsite doses. Refer to LCO 3.6.1.3, "Primary Containment Isolation Valves (PCIVs)," Applicable Safety Analyses Bases, for more detail.

Primary containment isolation instrumentation satisfies Criterion 3 of 10 CFR 50.36(c)(2)(ii). Certain instrumentation Functions are retained for other reasons and are described below in the individual Functions discussion.

The OPERABILITY of the primary containment instrumentation is dependent on the OPERABILITY of the individual instrumentation channel Functions specified in Table 3.3.6.1-1. Each Function must have a required number of OPERABLE channels, with their setpoints within the specified Allowable Values, where appropriate. The actual setpoint is calibrated consistent with applicable setpoint methodology assumptions. Each channel must also respond within its assumed response time, where appropriate.

Allowable Values are specified for each Primary Containment Isolation Function specified in the Table. Nominal trip setpoints are specified in the setpoint calculations. The nominal setpoints are selected to ensure that the setpoints do not exceed the Allowable Value between CHANNEL CALIBRATIONS. Operation with a trip setpoint less conservative than the nominal trip setpoint, but within its Allowable Value, is acceptable. A channel is inoperable if its actual trip setpoint is not within its required

(continued)

BASES

APPLICABLE
SAFETY ANALYSES,
LCO, and
APPLICABILITY
(continued)

Allowable Value. Trip setpoints are those predetermined values of output at which an action should take place. The setpoints are compared to the actual process parameter (e.g., reactor vessel water level), and when the measured output value of the process parameter exceeds the setpoint, the associated device (e.g., trip unit) changes state. The analytic limits are derived from the limiting values of the process parameters obtained from the safety analysis. The trip setpoints are determined from the analytic limits, corrected for defined process, calibration, and instrument errors. The Allowable Values are then determined, based on the trip setpoint values, by accounting for the calibration based errors. These calibration based errors are limited to reference accuracy, instrument drift, errors associated with measurement and test equipment, and calibration tolerance of loop components. The trip setpoints and Allowable Values determined in this manner provide adequate protection because instrument uncertainties, process effects, calibration tolerances, instrument drift, and severe environment errors (for channels that must function in harsh environments as defined by 10 CFR 50.49) are accounted for and appropriately applied for the instrumentation.

Certain Emergency Core Cooling Systems (ECCS) and RCIC valves (e.g., minimum flow) also serve the dual function of automatic PCIVs. The signals that isolate these valves are also associated with the automatic initiation of the ECCS and RCIC. Some instrumentation and ACTIONS associated with these signals are addressed in LCO 3.3.5.1, "ECCS Instrumentation," and LCO 3.3.5.2, "RCIC System Instrumentation," and are not included in this LCO.

In general, the individual Functions are required to be OPERABLE in MODES 1, 2, and 3 consistent with the Applicability for LCO 3.6.1.1, "Primary Containment." Functions that have different Applicabilities are discussed below in the individual Functions discussion.

The specific Applicable Safety Analyses, LCO, and Applicability discussions are listed below on a Function by Function basis.

(continued)

BASES

APPLICABLE
SAFETY ANALYSES,
LCO, and
APPLICABILITY
(continued)

1. Main Steam Line Isolation

1.a. Reactor Vessel Water Level—Low Low Low, Level 1

Low reactor pressure vessel (RPV) water level indicates that the capability to cool the fuel may be threatened. Should RPV water level decrease too far, fuel damage could result. Therefore, isolation of the MSIVs and other interfaces with the reactor vessel occurs to prevent offsite dose limits from being exceeded. The Reactor Vessel Water Level—Low Low Low, Level 1 Function is one of the many Functions assumed to be OPERABLE and capable of providing isolation signals. The Reactor Vessel Water Level—Low Low Low, Level 1 Function associated with isolation is assumed in the analysis of the recirculation line break (Ref. 2). The isolation of the MSL on Level 1 supports actions to ensure that offsite dose limits are not exceeded for a DBA.

Reactor vessel water level signals are initiated from four differential pressure transmitters that sense the difference between the pressure due to a constant column of water (reference leg) and the pressure due to the actual water level (variable leg) in the vessel. Four channels of Reactor Vessel Water Level—Low Low Low, Level 1 Function are available and are required to be OPERABLE to ensure that no single instrument failure can preclude the isolation function.

The Reactor Vessel Water Level—Low Low Low, Level 1 Allowable Value is chosen to be the same as the ECCS Level 1 Allowable Value (LCO 3.3.5.1) to ensure that the MSLs isolate on a potential loss of coolant accident (LOCA) to prevent offsite doses from exceeding 10 CFR 100 limits.

This Function isolates the Group 1 valves.

1.b. Main Steam Line Pressure—Low

Low MSL pressure indicates that there may be a problem with the turbine pressure regulation, which could result in a low reactor vessel water level condition and the RPV cooling down more than 100°F/hour if the pressure loss is allowed to continue. The Main Steam Line Pressure—Low Function is directly assumed in the analysis of the pressure regulator failure event (Ref. 4). The closure of the MSIVs ensures

(continued)

BASES

APPLICABLE
SAFETY ANALYSES,
LCO, and
APPLICABILITY

1.b. Main Steam Line Pressure-Low (continued)

that the RPV temperature change limit (100°F/hour) is not reached. In addition, this Function supports actions to ensure that Safety Limit 2.1.1.1 is not exceeded. (This Function closes the MSIVs prior to pressure decreasing below 785 psig, which results in a scram due to MSIV closure, thus reducing reactor power to < 25% RTP.)

The MSL low pressure signals are initiated from four pressure switches that are connected downstream of the MSL header prior to each main turbine stop valve. The pressure switches are arranged such that, even though physically separated from each other, each switch is able to detect low MSL pressure. Four channels of Main Steam Line Pressure-Low Function are available and are required to be OPERABLE to ensure that no single instrument failure can preclude the isolation function.

The Allowable Value was selected to be high enough to prevent excessive RPV depressurization.

The Main Steam Line Pressure-Low Function is only required to be OPERABLE in MODE 1 since this is when the assumed transient can occur (Ref. 4).

This Function isolates the Group 1 valves.

1.c. Main Steam Line Flow-High

Main Steam Line Flow-High is provided to detect a break of the MSL and to initiate closure of the MSIVs. If the steam were allowed to continue flowing out of the break, the reactor would depressurize and the core could uncover. If the RPV water level decreases too far, fuel damage could occur. Therefore, the isolation is initiated on high flow to prevent or minimize core damage. The Main Steam Line Flow-High Function is directly assumed in the analysis of the main steam line break (MSLB) accident (Ref. 5). The isolation action, along with the scram function of the RPS, ensures that the fuel peak cladding temperature remains below the limits of 10 CFR 50.46 and offsite doses do not exceed the 10 CFR 100 limits.

(continued)

BASES

APPLICABLE
SAFETY ANALYSES,
LCO, and
APPLICABILITY

1.c. Main Steam Line Flow-High (continued)

The MSL flow signals are initiated from 16 differential pressure switches that are connected to the four MSLs (the differential pressure switches sense differential pressure across a flow element). The switches are arranged such that, even though physically separated from each other, all four connected to one steam line would be able to detect the high flow. Four channels of Main Steam Line Flow-High Function for each MSL (two channels per trip system) are available and are required to be OPERABLE so that no single instrument failure will preclude detecting a break in any individual MSL.

The Allowable Value is chosen to ensure that offsite dose limits are not exceeded due to the break.

This Function isolates the Group 1 valves.

1.d. Condenser Vacuum-Low

The Condenser Vacuum-Low Function is provided to prevent overpressurization of the main condenser in the event of a loss of the main condenser vacuum (Ref. 6). Since the integrity of the condenser is an assumption in offsite dose calculations (Ref. 7), the Condenser Vacuum-Low Function is assumed to be OPERABLE and capable of initiating closure of the MSIVs. The closure of the MSIVs is initiated to prevent the addition of steam that would lead to additional condenser pressurization and possible rupture of the diaphragm installed to protect the turbine exhaust hood, thereby preventing a potential radiation leakage path following an accident.

Condenser vacuum pressure signals are derived from four pressure switches that sense the pressure in the condenser. Four channels of Condenser Vacuum-Low Function are available and are required to be OPERABLE to ensure no single instrument failure can preclude the isolation function.

(continued)

BASES

APPLICABLE
SAFETY ANALYSES,
LCO, and
APPLICABILITY

1.d. Condenser Vacuum-Low (continued)

The Allowable Value is chosen to prevent damage to the condenser due to pressurization, thereby ensuring its integrity for offsite dose analysis. As noted (footnote (a) to Table 3.3.6.1-1), the channels are not required to be OPERABLE in MODES 2 and 3, when all turbine stop valves (TSVs) are closed, since the potential for condenser overpressurization is minimized. Switches are provided to manually bypass the channels when all TSVs are closed.

This Function isolates the Group 1 valves.

1.e Main Steam Line Tunnel Differential Temperature-High

Differential Temperature-High is provided to detect a leak in a main steam line, and provides diversity to the high flow instrumentation. The isolation occurs when a very small leak has occurred. If the small leak is allowed to continue without isolation, offsite dose limits may be reached. However, credit for these instruments is not taken in any transient or accident analysis in the UFSAR, since bounding analyses are performed for large breaks such as MSLBs.

Eight thermocouples provide input to the Main Steam Line Tunnel Differential Temperature-High Function. The output of these thermocouples is used to determine the differential temperature. Each channel consists of a differential temperature instrument that receives inputs from thermocouples that are located in the inlet and outlet of the main steam line tunnel for a total of four available channels. Four channels of Main Steam Line Tunnel Differential Temperature-High Function are available and are required to be OPERABLE to ensure that no single instrument failure can preclude the isolation function.

The differential temperature monitoring Allowable Value is chosen to detect a leak equivalent to 100 gpm.

These Functions isolate the Group 1 valves.

(continued)

BASES

APPLICABLE
SAFETY ANALYSES,
LCO, and
APPLICABILITY
(continued)

1.f. Manual Initiation

The Manual Initiation push button channels introduce signals into the MSL isolation logic that are redundant to the automatic protective instrumentation and provide manual isolation capability. There is no specific UFSAR safety analysis that takes credit for this Function. It is retained for overall redundancy and diversity of the isolation function as required by the NRC in the plant licensing basis.

There are four push buttons for the logic, with two manual initiation push buttons per trip system. Four channels of Manual Initiation Function are available and are required to be OPERABLE in MODES 1, 2, and 3, since these are the MODES in which the MSL Isolation automatic Functions are required to be OPERABLE.

There is no Allowable Value for this Function since the channels are mechanically actuated based solely on the position of the push buttons.

This Function isolates the Group 1 valves.

2. Primary Containment Isolation

2.a Reactor Vessel Water Level - Low Low, Level 2

Low RPV water level indicates the capability to cool the fuel may be threatened. The valves whose penetrations communicate with the primary containment are isolated to limit the release of fission products. The isolation of the primary containment on Level 2 supports actions to ensure that offsite dose limits of 10 CFR 100 are not exceeded. The Reactor Vessel Water Level - Low Low, Level 2 Function associated with isolation is implicitly assumed in the UFSAR analysis as these leakage paths are assumed to be isolated post LOCA.

Reactor Vessel Water Level - Low Low, Level 2 signals are initiated from differential pressure transmitters that sense the difference between the pressure due to a constant column of water (reference leg) and the pressure due to the actual

(continued)

BASES

APPLICABLE
SAFETY ANALYSES,
LCO, and
APPLICABILITY

2.a Reactor Vessel Water Level – Low Low, Level 2
(continued)

water level (variable leg) in the vessel. Four channels of Reactor Vessel Water Level – Low Low, Level 2 Function are available and are required to be OPERABLE to ensure no single instrument failure can preclude the isolation function.

The Reactor Vessel Water Level – Low Low, Level 2 Allowable Value was chosen to be the same as the ECCS Reactor Vessel Water Level – Low Low, Level 2 Allowable Value (LCO 3.3.5.1), since isolation of these valves is not critical to orderly plant shutdown.

This Function isolates the Group 2, 3, and 4 valves.

2.b Drywell Pressure – High

High drywell pressure can indicate a break in the RCPB inside the drywell. The isolation of some of the PCIVs on high drywell pressure supports actions to ensure that offsite dose limits of 10 CFR 100 are not exceeded. The Drywell Pressure – High Function associated with isolation of the primary containment is implicitly assumed in the UFSAR accident analysis as these leakage paths are assumed to be isolated post LOCA.

High drywell pressure signals are initiated from pressure switches that sense the pressure in the drywell. Four channels of Drywell Pressure – High Function are available and are required to be OPERABLE to ensure that no single instrument failure can preclude the isolation function.

The Allowable Value was selected to be the same as the RPS Drywell Pressure – High Allowable Value (LCO 3.3.1.1), since this may be indicative of a LOCA inside primary containment.

This Function isolates the Group 2, 4, 7, and 10 valves.

(continued)

BASES

APPLICABLE
SAFETY ANALYSES,
LCO, and
APPLICABILITY
(continued)

2.c. Reactor Building Ventilation Exhaust Plenum
Radiation-High

High ventilation exhaust radiation is an indication of possible gross failure of the fuel cladding. The release may have originated from the primary containment due to a break in the RCPB or refueling floor due to a fuel handling accident. When Reactor Building Ventilation Exhaust Radiation-High is detected, valves whose penetrations communicate with the primary containment atmosphere are isolated to limit the release of fission products.

The Reactor Building Ventilation Exhaust Plenum Radiation-High signals are initiated from radiation detectors that are located in the reactor building return air riser above the upper area of the steam tunnel prior to the reactor building ventilation isolation dampers. The signal from each detector is input to an individual monitor whose trip outputs are assigned to an isolation channel. Four channels of Reactor Building Ventilation Exhaust Plenum Radiation-High Function are available and are required to be OPERABLE to ensure that no single instrument failure can preclude the isolation function.

The Allowable Values are chosen to promptly detect gross failure of the fuel cladding and to ensure offsite doses remain below 10 CFR 20 and 10 CFR 100 limits.

These Functions isolate the Group 4 valves.

2.d. Fuel Pool Ventilation Exhaust Radiation-High

High fuel pool ventilation exhaust radiation indicates increased airborne radioactivity levels in secondary containment refuel floor area which could be due to fission gases from the fuel pool resulting from a refueling accident. Since the primary and secondary containments may be in communication, the vent and purge valves for primary containment isolation are also provided with an isolation signal. Therefore, Fuel Pool Ventilation Exhaust Radiation-High Function initiates an isolation to assure timely closure of valves to protect against substantial releases of radioactive materials to the environment. While this Function is identified as initiating the Standby Gas Treatment System for a spent fuel cask drop accident

(continued)

BASES

APPLICABLE
SAFETY ANALYSES,
LCO, and
APPLICABILITY

2.d. Fuel Pool Ventilation Exhaust Radiation—High
(continued)

(Ref. 3), it is not assumed in any limiting accident or transient analysis in the UFSAR because other leakage paths (e.g., MSIVs) are more limiting.

The fuel pool ventilation exhaust radiation signals are initiated from radiation detectors located in the reactor building exhaust ducting coming from the refuel floor. The signal from each detector is input to an individual monitor whose trip output is assigned to an isolation channel. Four channels of Fuel Pool Ventilation Exhaust Radiation—High Function are available and are required to be OPERABLE to ensure that no single instrument failure can preclude the isolation function.

The Allowable Value is chosen to be the same as the Fuel Pool Ventilation Exhaust Radiation—High Function (LCO 3.3.6.2, "Secondary Containment Isolation Instrumentation") to provide a conservative isolation of this potential release path during this abnormal condition of increased airborne radioactivity.

This Function isolates the Group 4 valves.

2.e. Reactor Vessel Water Level—Low Low Low, Level 1

Low RPV water level indicates the capability to cool the fuel may be threatened. Should RPV water level decrease too far, fuel damage could result. Therefore, isolation of the primary containment occurs to prevent offsite dose limits from being exceeded. The Reactor Vessel Water Level—Low Low Low, Level 1 Function is one of the many Functions assumed to be OPERABLE and capable of providing isolation signals. The Reactor Vessel Water Level—Low Low Low, Level 1 Function associated with isolation is implicitly assumed in the UFSAR analysis as these leakage paths are assumed to be isolated post LOCA.

Reactor vessel water level signals are initiated from level transmitters that sense the difference between the pressure due to a constant column of water (reference leg) and the pressure due to the actual water level (variable leg) in the vessel. Four channels of Reactor Vessel Water Level—Low

(continued)

BASES

APPLICABLE
SAFETY ANALYSES,
LCO, and
APPLICABILITY

2.e. Reactor Vessel Water Level—Low Low Low, Level 1
(continued)

Low Low, Level 1 Function are available and are required to be OPERABLE to ensure that no single instrument failure can preclude the isolation function.

The Reactor Vessel Water Level—Low Low Low, Level 1 Allowable Value is chosen to be the same as the ECCS Reactor Vessel Water Level—Low Low Low, Level 1 Allowable Value (LCO 3.3.5.1) to ensure the valves are isolated to prevent offsite doses from exceeding 10 CFR 100 limits.

This Function isolates the Group 10 valves.

2.f. Reactor Vessel Water Level—Low, Level 3

Low RPV water level indicates the capability to cool the fuel may be threatened. Should RPV water level decrease too far, fuel damage could result. Therefore, the valves whose penetrations communicate with the primary containment are isolated to limit the release of fission products. The isolation of the primary containment on Level 3 supports actions to ensure that offsite dose limits of 10 CFR 100 are not exceeded. The Reactor Vessel Water Level—Low, Level 3 Function associated with isolation is implicitly assumed in the UFSAR analysis as these leakage paths are assumed to be isolated post LOCA.

Reactor Vessel Water Level—Low, Level 3 signals are initiated from differential pressure transmitters that sense the difference between the pressure due to a constant column of water (reference leg) and the pressure due to the actual water level (variable leg) in the vessel. Four channels of the Reactor Vessel Water Level—Low, Level 3 Function are available and are required to be OPERABLE to ensure that no single instrument failure can preclude the isolation function.

The Reactor Vessel Water Level—Low, Level 3 Allowable Value was chosen to be the same as the RPS Reactor Vessel Water Level—Low, Level 3 Allowable Value (LCO 3.3.1.1) since the capability to cool the fuel may be threatened.

This Function isolates the Group 7 valves.

(continued)

BASES

APPLICABLE
SAFETY ANALYSES,
LCO, and
APPLICABILITY
(continued)

2.g. Manual Initiation

The Manual Initiation push button channels introduce signals into the primary containment isolation logic that are redundant to the automatic protective instrumentation and provide manual isolation capability. There is no specific UFSAR safety analysis that takes credit for this Function. It is retained for overall redundancy and diversity of the isolation function as required by the NRC in the plant licensing basis.

There are two push buttons for the logic, one manual initiation push button per trip system. Two channels of the Manual Initiation Function are available and are required to be OPERABLE in MODES 1, 2, and 3, since these are the MODES in which the Primary Containment Isolation automatic Functions are required to be OPERABLE.

There is no Allowable Value for this Function since the channels are mechanically actuated based solely on the position of the push buttons.

This Function isolates the Group 2, 4, 7, and 10 valves.

3. Reactor Core Isolation Cooling System Isolation

3.a. RCIC Steam Line Flow-High

RCIC Steam Line Flow-High Function is provided to detect a break of the RCIC steam lines and initiates closure of the steam line isolation valves. If the steam is allowed to continue flowing out of the break, the reactor will depressurize and core uncovering can occur. Therefore, the isolation is initiated on high flow to prevent or minimize core damage. The isolation action, along with the scram function of the Reactor Protection System (RPS), ensures that the fuel peak cladding temperature remains below the limits of 10 CFR 50.46. Specific credit for this Function is not assumed in any UFSAR accident analyses since the bounding analysis is performed for large breaks such as recirculation and MSL breaks. However, these instruments prevent the RCIC steam line break from becoming bounding.

(continued)

BASES

APPLICABLE
SAFETY ANALYSES,
LCO, and
APPLICABILITY

3.a. RCIC Steam Line Flow-High (continued)

The RCIC Steam Line Flow-High signals are initiated from two differential pressure switches that are connected to the system steam lines. Two channels of RCIC Steam Line Flow-High Functions are available and are required to be OPERABLE to ensure that no single instrument failure can preclude the isolation function.

The Allowable Value is chosen to be low enough to ensure that the trip occurs to prevent fuel damage and maintains the MSLB event as the bounding event.

This Function isolates the Group 8 valves.

3.b. RCIC Steam Line Flow-Timer

The RCIC Steam Line Flow-Timer is provided to prevent false isolations on RCIC Steam Line Flow-High during system startup transients and therefore improves system reliability. This Function is not assumed in any UFSAR transient or accident analyses since the bounding analysis is performed for large breaks such as recirculation and MSL breaks. However, these instruments prevent the RCIC steam line break from being bounding.

The RCIC Steam Line Flow-Timer Function delays the RCIC Steam Line Flow-High signals by use of time delay relays. When an RCIC Steam Line Flow-High signal is generated, the time delay relays delay the tripping of the associated RCIC isolation trip system for a short time. Two channels of RCIC Steam Line Flow-Timer Function are available and are required to be OPERABLE to ensure that no single instrument failure can preclude the isolation function.

The Allowable Value was chosen to be long enough to prevent false isolations due to system starts but not so long as to impact offsite dose calculations.

This Function isolates the Group 8 valves.

(continued)

BASES

APPLICABLE
SAFETY ANALYSES,
LCO, and
APPLICABILITY
(continued)

3.c. RCIC Steam Supply Pressure—Low

Low RCIC steam supply pressure indicates that the pressure of the steam in the RCIC turbine may be too low to continue operation of the RCIC turbine. This isolation is for equipment protection and is not assumed in any transient or accident analysis in the UFSAR. However, it also provides a diverse signal to indicate a possible system break. These instruments are included in the Technical Specifications (TS) because of the potential for risk due to possible failure of the instruments preventing RCIC initiations. Therefore, they meet Criterion 4 of 10 CFR 50.36(c)(2)(ii).

The RCIC Steam Supply Pressure—Low signals are initiated from four pressure switches that are connected to the RCIC steam line. Four channels of RCIC Steam Supply Pressure—Low Function are available and are required to be OPERABLE to ensure that no single instrument failure can preclude the isolation function.

The Allowable Value is selected to be high enough to prevent damage to the RCIC turbines.

This Function isolates the Group 8 valves. This Function coincident with Drywell Pressure—High also isolates the Group 9 valves.

3.d. RCIC Turbine Exhaust Diaphragm Pressure—High

High turbine exhaust diaphragm pressure indicates that the pressure may be too high to continue operation of the RCIC turbine. That is, one of two exhaust diaphragms has ruptured and pressure is reaching turbine casing pressure limits. This isolation is for equipment protection and is not assumed in any transient or accident analysis in the UFSAR. These instruments are included in the TS because of the potential for risk due to possible failure of the instruments preventing RCIC initiations. Therefore, they meet Criterion 4 of 10 CFR 50.36(c)(2)(ii).

The RCIC Turbine Exhaust Diaphragm Pressure—High signals are initiated from four pressure switches that are connected to the area between the rupture diaphragms on the RCIC turbine exhaust line. Four channels of RCIC Turbine Exhaust

(continued)

BASES

APPLICABLE
SAFETY ANALYSES,
LCO, and
APPLICABILITY

3.d. RCIC Turbine Exhaust Diaphragm Pressure - High
(continued)

Diaphragm Pressure - High Function are available and are required to be OPERABLE to ensure that no single instrument failure can preclude the isolation function.

The Allowable Value is selected to be low enough to prevent damage to the RCIC turbine.

This Function isolates the Group 8 valves.

3.e, 3.f, 3.g, 3.h. Area and Differential Temperature - High

Area and Differential Temperatures are provided to detect a leak from the RCIC steam piping. The isolation occurs when a very small leak has occurred and is diverse to the high flow instrumentation. If the small leak is allowed to continue without isolation, offsite dose limits may be reached. These Functions are not assumed in any UFSAR transient or accident analysis, since bounding analyses are performed for large breaks such as recirculation or MSL breaks.

Area Temperature - High signals are initiated from thermocouples that are located in the area that is being monitored. Two instruments monitor each area. Four channels for Area Temperature - High Function are available and are required to be OPERABLE to ensure that no single instrument failure can preclude the isolation function. There are two for the RCIC equipment room and two for the RCIC steam line tunnel area.

There are 8 thermocouples (four for the RCIC equipment room and four for the RCIC steam line tunnel area) that provide input to the Differential Temperature - High Function. The output of these thermocouples is used to determine the differential temperature. Each channel consists of a differential temperature instrument that receives inputs from thermocouples that are located in the inlet and outlet of the area cooling system for a total of four (two for the RCIC equipment room and two for the RCIC steam line tunnel area) available channels.

(continued)

BASES

APPLICABLE SAFETY ANALYSES, LCO, and APPLICABILITY 3.e, 3.f, 3.g, 3.h. Area and Differential Temperature-High (continued)
The Allowable Values are set low enough to detect a leak equivalent to 25 gpm.

This Function isolates the Group 8 valves.

3.i. Drywell Pressure-High

High drywell pressure can indicate a break in the RCPB. The RCIC isolation of the turbine exhaust is provided to prevent communication with the drywell when high drywell pressure exists. A potential leakage path exists via the turbine exhaust. The isolation is delayed until the system becomes unavailable for injection (i.e., low steam line pressure). The isolation of the RCIC turbine exhaust by Drywell Pressure-High is indirectly assumed in the UFSAR accident analysis because the turbine exhaust leakage path is not assumed to contribute to offsite doses.

High drywell pressure signals are initiated from pressure switches that sense the pressure in the drywell. Four channels of RCIC Drywell Pressure-High Function are available and are required to be OPERABLE to ensure that no single instrument failure can preclude the isolation function.

The Allowable Value was selected to be the same as the ECCS Drywell Pressure-High Allowable Value (LCO 3.3.5.1), since this is indicative of a LOCA inside primary containment.

This Function coincident with RCIC Steam Supply Pressure-Low isolates the Group 9 valves.

3.j. Manual Initiation

The Manual Initiation push button channel introduces a signal into the RCIC System isolation logic that is redundant to the automatic protective instrumentation and provides manual isolation capability when a system initiation signal is present. There is no specific UFSAR safety analysis that takes credit for this Function. It is

(continued)

BASES

APPLICABLE
SAFETY ANALYSES,
LCO, and
APPLICABILITY

3.j. Manual Initiation (continued)

retained for overall redundancy and diversity of the isolation function as required by the NRC in the plant licensing basis.

There is one push button for RCIC. One channel of Manual Initiation Function is available and is required to be OPERABLE in MODES 1, 2, and 3 since these are the MODES in which the RCIC System Isolation automatic Functions are required to be OPERABLE. As noted (footnote (b) to Table 3.3.6.1-1), this Function only provides input into one of the two trip systems.

There is no Allowable Value for this Function since the channels are mechanically actuated based solely on the position of the push buttons.

This Function, coincident with a Reactor Vessel Water Level-Low Low, Level 2, isolates the outboard Group 8 valve.

4. Reactor Water Cleanup System Isolation

4.a. Differential Flow-High

The high differential flow signal is provided to detect a break in the RWCU System. This will detect leaks in the RWCU System when area or differential temperature would not provide detection (i.e., a cold leg break). Should the reactor coolant continue to flow out of the break, offsite dose limits may be exceeded. Therefore, isolation of the RWCU System is initiated when high differential flow is sensed to prevent exceeding offsite doses. A time delay (Function 4.b, described below) is provided to prevent spurious trips during most RWCU operational transients. This Function is not assumed in any UFSAR transient or accident analysis, since bounding analyses are performed for large breaks such as MSLBs.

The high differential flow signals are initiated from one differential pressure transmitter monitoring inlet flow (from the reactor vessel) and two transmitters monitoring system outlet flow to the two available flow paths (normal return to feedwater and discharge flow to either the main

(continued)

BASES

APPLICABLE
SAFETY ANALYSES,
LCO, and
APPLICABILITY

4.a. Differential Flow-High (continued)

condenser or radwaste). The outputs of the transmitters are compared (in a summer) and the outputs are sent to two alarm trip units. If the difference between the inlet and outlet flow is too large, each alarm trip unit generates an isolation signal. Two channels of Differential Flow-High Function are available and are required to be OPERABLE to ensure that no single instrument failure (other than the common transmitters and summers) can preclude the isolation function.

The Differential Flow-High Allowable Value ensures that the break of the RWCU piping is detected.

This Function isolates the Group 5 valves.

4.b. Differential Flow-Timer

The Differential Flow-Timer is provided to avoid RWCU System isolations due to operational transients (such as pump starts and mode changes). During these transients the inlet and return flows become unbalanced for short time periods and Differential Flow-High will be sensed without an RWCU System break being present. Credit for this Function is not assumed in the UFSAR accident or transient analysis, since bounding analyses are performed for large breaks such as MSLBs.

The Differential Flow-Timer Function delays the Differential Flow-High signals by use of time delay relays. When a Differential Flow-High signal is generated, the time delay relays delay the tripping of the associated RWCU isolation trip system for a short time. Two channels of Differential Flow-Timer Function are available and are required to be OPERABLE to ensure that no single instrument failure can preclude the isolation function.

The Differential Flow-Timer Allowable Value is selected to ensure that the MSLB outside containment remains the limiting break for UFSAR analysis for offsite dose calculations.

This Function isolates the Group 5 valves.

(continued)

BASES

APPLICABLE
SAFETY ANALYSES,
LCO, and
APPLICABILITY
(continued)

4.c, 4.d, 4.e, 4.f, 4.g, 4.h, 4.i, 4.j, Area
Differential Temperature-High

Area and Differential Temperature-High is provided to detect a leak from the RWCU System. The isolation occurs even when very small leaks have occurred and is diverse to the high differential flow instrumentation for the hot portions of the RWCU System. If the small leak continues without isolation, offsite dose limits may be reached. Credit for these instruments is not taken in any transient or accident analysis in the UFSAR, since bounding analyses are performed for large breaks such as MSLBs.

Area Temperature-High signals are initiated from temperature elements that are located in the room that is being monitored. There are fourteen thermocouples that provide input to the Area Temperature-High Function (two per area). Fourteen channels are required to be OPERABLE to ensure that no single instrument failure can preclude the isolation function. There are four channels for the RWCU heat exchanger area (two in each heat exchanger room), six channels for the RWCU pump and valve room (two in each of the three rooms), two channels for the holdup pipe area, and two channels for the filter/demineralizer valve room area.

There are twenty eight thermocouples that provide input to the Differential Temperature-High Function. The output of these thermocouples is used to determine the differential temperature. Each channel consists of a differential temperature instrument that receives inputs from thermocouples that are located in the inlet and outlet of the area cooling system for a total of fourteen available channels (two per area). Fourteen channels are required to be OPERABLE to ensure that no single instrument failure can preclude the isolation function. There are four channels for the RWCU heat exchanger area, six channels for the RWCU pump and valve room, two channels for the holdup pipe area, and two for the filter/demineralizer valve room area.

The Area and Differential Temperature-High Allowable Values are set low enough to detect a leak equivalent to 25 gpm.

These Functions isolate the Group 5 valves.

(continued)

BASES

APPLICABLE
SAFETY ANALYSES,
LCO, and
APPLICABILITY
(continued)

4.k. Reactor Vessel Water Level - Low Low, Level 2

Low RPV water level indicates the capability to cool the fuel may be threatened. Should RPV water level decrease too far, fuel damage could result. Therefore, isolation of some reactor vessel interfaces occurs to isolate the potential sources of a break. The isolation of the RWCU System on Level 2 supports actions to ensure that fuel peak cladding temperature remains below the limits of 10 CFR 50.46. The Reactor Vessel Water Level - Low Low, Level 2 Function associated with RWCU isolation is not directly assumed in any transient or accident analysis, since bounding analyses are performed for large breaks such as MSLBs.

Reactor Vessel Water Level - Low Low, Level 2 signals are initiated from differential pressure transmitters that sense the difference between the pressure due to a constant column of water (reference leg) and the pressure due to the actual water level (variable leg) in the vessel. Four channels of Reactor Vessel Water Level - Low Low, Level 2 Function are available and are required to be OPERABLE to ensure that no single instrument failure can preclude the isolation function.

The Reactor Vessel Water Level - Low Low, Level 2 Allowable Value was chosen to be the same as the ECCS Reactor Vessel Water Level - Low Low, Level 2 Allowable Value (LCO 3.3.5.1), since the capability to cool the fuel may be threatened.

This Function isolates the Group 5 valves.

4.l. SLC System Initiation

The isolation of the RWCU System is required when the SLC System has been initiated to prevent dilution and removal of the boron solution by the RWCU System (Ref. 8). SLC System initiation signals are initiated from the two SLC pump start signals.

Two channels (one from each pump) of SLC System Initiation Function are available and are required to be OPERABLE only in MODES 1 and 2, since these are the only MODES where the reactor can be critical, and these MODES are consistent with the Applicability for the SLC System (LCO 3.1.7, "SLC

(continued)

BASES

APPLICABLE
SAFETY ANALYSES,
LCO, and
APPLICABILITY

4.l. SLC System Initiation (continued)

System"). As noted (footnote (b) to Table 3.3.6.1-1), this Function only provides input into one of two trip systems.

There is no Allowable Value associated with this Function since the channels are mechanically actuated based solely on the position of the SLC System initiation switches.

This Function isolates the outboard Group 5 valve.

4.m. Manual Initiation

The Manual Initiation push button channels introduce signals into the RWCU System isolation logic that are redundant to the automatic protective instrumentation and provide manual isolation capability. There is no specific UFSAR safety analysis that takes credit for this Function. It is retained for overall redundancy and diversity of the isolation function as required by the NRC in the plant licensing basis.

There are two push buttons for the logic, one manual initiation push button per trip system. Two channels of the Manual Initiation Function are available and are required to be OPERABLE in MODES 1, 2, and 3 since these are the MODES in which the RWCU System Isolation automatic Functions are required to be OPERABLE.

There is no Allowable Value for this Function, since the channels are mechanically actuated based solely on the position of the push buttons.

This Function isolates the Group 5 valves.

5. RHR Shutdown Cooling System Isolation

5.a. Reactor Vessel Water Level - Low, Level 3

Low RPV water level indicates the capability to cool the fuel may be threatened. Should RPV water level decrease too far, fuel damage could result. Therefore, isolation of some reactor vessel interfaces occurs to begin isolating the potential sources of a break. The Reactor Vessel Water

(continued)

BASES

APPLICABLE
SAFETY ANALYSES,
LCO, and
APPLICABILITY

5.a. Reactor Vessel Water Level-Low, Level 3 (continued)

Level-Low, Level 3 Function associated with RHR Shutdown Cooling System isolation is not directly assumed in any transient or accident analysis, since bounding analyses are performed for large breaks such as MSLBs. The RHR Shutdown Cooling System isolation on Level 3 supports actions to ensure that the RPV water level does not drop below the top of the active fuel during a vessel draindown event caused by a leak (e.g., pipe break or inadvertent valve opening) in the RHR Shutdown Cooling System.

Reactor Vessel Water Level-Low, Level 3 signals are initiated from differential pressure transmitters that sense the difference between the pressure due to a constant column of water (reference leg) and the pressure due to the actual water level (variable leg) in the vessel. Four channels (two channels per trip system) of the Reactor Vessel Water Level-Low, Level 3 Function are available and are required to be OPERABLE to ensure that no single instrument failure can preclude the isolation function. As noted (footnote (c) to Table 3.3.6.1-1), only one trip system is required to be OPERABLE in MODES 4 and 5 provided the RHR Shutdown Cooling System integrity is maintained. System integrity is maintained provided the piping is intact and no maintenance is being performed that has the potential for draining the reactor vessel through the system.

The Reactor Vessel Water Level-Low, Level 3 Function is only required to be OPERABLE in MODES 3, 4, and 5 to prevent this potential flow path from lowering reactor vessel level to the top of the fuel. In MODES 1 and 2, the Reactor Vessel Pressure-High Function and administrative controls ensure that this flow path remains isolated to prevent unexpected loss of inventory via this flow path.

The Reactor Vessel Water Level-Low, Level 3 Allowable Value was chosen to be the same as the RPS Reactor Vessel Water Level-Low, Level 3 Allowable Value (LCO 3.3.1.1) since the capability to cool the fuel may be threatened.

This Function isolates the Group 6 valves.

(continued)

BASES

APPLICABLE
SAFETY ANALYSES,
LCO, and
APPLICABILITY
(continued)

5.b. Reactor Vessel Pressure-High

The Shutdown Cooling System Reactor Vessel Pressure-High Function is provided to isolate the shutdown cooling portion of the RHR System. This interlock is provided only for equipment protection to prevent an intersystem LOCA scenario and credit for the interlock is not assumed in the accident or transient analysis in the UFSAR.

The Reactor Vessel Pressure-High signals are initiated from two pressure switches. Two channels of Reactor Vessel Pressure-High Function are available and are required to be OPERABLE to ensure that no single instrument failure can preclude the isolation function.

The Allowable Value (corrected for cold water head and reactor vessel flooded) was chosen to be low enough to protect the system equipment from overpressurization.

This Function isolates the Group 6 valves.

5.c. Manual Initiation

The Manual Initiation push button channels introduce signals into the RHR Shutdown Cooling System isolation logic that are redundant to the automatic protective instrumentation and provide manual isolation capability. There is no specific UFSAR safety analysis that takes credit for this Function. It is retained for overall redundancy and diversity of the isolation function as required by the NRC in the plant licensing basis.

There is one push button for the logic per trip system. Two channels of the Manual Initiation Function are available and are required to be OPERABLE in MODES 1, 2, and 3 since these are the MODES in which the RHR Shutdown Cooling System Isolation automatic Functions are required to be OPERABLE. While certain automatic Functions are required in MODES 4 and 5, the Manual Initiation Function is not required in MODES 4 and 5, since there are other means (i.e., means other than the Manual Initiation push buttons) to manually isolate the RHR Shutdown Cooling System from the control room.

(continued)

BASES

APPLICABLE
SAFETY ANALYSES,
LCO, and
APPLICABILITY

5.c. Manual Initiation (continued)

There is no Allowable Value for this Function, since the channels are mechanically actuated based solely on the position of the push buttons.

This Function isolates the Group 6 valves.

ACTIONS

Note 1 has been provided to modify the ACTIONS related to primary containment isolation instrumentation channels. Section 1.3, Completion Times, specifies that once a Condition has been entered, subsequent divisions, subsystems, components, or variables expressed in the Condition discovered to be inoperable or not within limits will not result in separate entry into the Condition. Section 1.3 also specifies that Required Actions of the Condition continue to apply for each additional failure, with Completion Times based on initial entry into the Condition. However, the Required Actions for inoperable primary containment isolation instrumentation channels provide appropriate compensatory measures for separate inoperable channels. As such, a Note has been provided that allows separate Condition entry for each inoperable primary containment isolation instrumentation channel.

Note 2 indicates that when automatic isolation capability is lost for Function 1.e, Main Steam Line Tunnel Differential Temperature-High (i.e., when both trip systems are inoperable for Function 1.e) due to required Reactor Building Ventilation System corrective maintenance, filter changes, damper cycling, or for performance of required Surveillances, entry into the associated Conditions and Required Actions may be delayed for up to 4 hours. Similarly, Note 3 indicates that when automatic isolation capability is lost for Function 1.e due to a loss of reactor building ventilation or for performance of SR 3.6.4.1.3 or SR 3.6.4.1.4, entry into the associated Conditions and Required Actions may be delayed for up to 12 hours. Upon completion of the activities or expiration of the time allowance, the channels must be returned to OPERABLE status or the applicable Conditions entered and Required Actions taken. These Notes are necessary so that testing and

(continued)

BASES

ACTIONS
(continued) required Surveillances specified in LCO 3.6.4.1, "Secondary Containment," LCO 3.6.4.2, "Secondary Containment Isolation Valves (SCIV)," and LCO 3.6.4.3, "Standby Gas Treatment (SGT) System," can be performed without inducing an isolation of the MSIVs. The 4 hour and 12 hour allowances provide sufficient time to safely perform the testing. The 12 hour allowance also provides sufficient time to identify and correct minor reactor building ventilation system problems. Since the design of the Unit 1 and Unit 2 reactor buildings is such that they share a common area of the refuel floor (i.e., the reactor buildings are not separated on the refuel floor), operation of either unit's ventilation system will affect the other unit's building differential pressure. Performance of testing to verify secondary containment integrity requirements and minor correctable problems could require a dual unit outage (without the Notes).

A.1

Because of the diversity of sensors available to provide isolation signals and the redundancy of the isolation design, an allowable out of service time of 12 hours or 24 hours, depending on the Function (12 hours for those Functions that have channel components common to RPS instrumentation and 24 hours for those Functions that do not have channel components common to RPS instrumentation), has been shown to be acceptable (Refs. 9 and 10) to permit restoration of any inoperable channel to OPERABLE status. This out of service time is only acceptable provided the associated Function is still maintaining isolation capability (refer to Required Action B.1 Bases). If the inoperable channel cannot be restored to OPERABLE status within the allowable out of service time, the channel must be placed in the tripped condition per Required Action A.1. Placing the inoperable channel in trip would conservatively compensate for the inoperability, restore capability to accommodate a single failure, and allow operation to continue with no further restrictions. Alternately, if it is not desired to place the channel in trip (e.g., as in the case where placing the inoperable channel in trip would result in an isolation), Condition C must be entered and its Required Action taken.

(continued)

BASES

ACTIONS
(continued)

B.1

Required Action B.1 is intended to ensure that appropriate actions are taken if multiple, inoperable, untripped channels within the same Function result in redundant automatic isolation capability being lost for the associated penetration flow path(s). The MSIVs portion of the MSL isolation Functions are considered to be maintaining isolation capability when sufficient channels are OPERABLE or in trip such that both trip systems will generate a trip signal from the given Function on a valid signal. The MSL drain valves portion of the MSL isolation Functions and the other isolation Functions are considered to be maintaining isolation capability when sufficient channels are OPERABLE or in trip such that one trip system will generate a trip signal from the given Function on a valid signal. This ensures that one of the two PCIVs in the associated penetration flow path can receive an isolation signal from the given Function. For the MSIVs portion of Functions 1.a, 1.b, 1.d, and 1.e, this would require both trip systems to have one channel OPERABLE or in trip. For the MSL drain valves portion of Functions 1.a, 1.b, 1.d, and 1.e, this would require one trip system to have two channels, each OPERABLE or in trip. For the MSIVs portion of Function 1.c, this would require both trip systems to have one channel, associated with each MSL, OPERABLE or in trip. For the MSL drain valves portion of Function 1.c, this would require one trip system to have two channels, associated with each MSL, each OPERABLE or in trip. For Functions 2.a, 2.b, 2.c, 2.d, 2.e, 2.f, 3.c (for Group 8 valves) 3.d, 4.k, and 5.a, this would require one trip system to have two channels, each OPERABLE or in trip. For Functions 3.a, 3.b, 3.c (for Group 9 valves), 3.e, 3.f, 3.g, 3.h, 3.i, 4.a, 4.b, 4.g, 4.h, 4.i, 4.j, 4.l, and 5.b, this would require one trip system to have one channel OPERABLE or in trip. For Functions 4.c, 4.d, 4.e, and 4.f each Function consists of channels that monitor several different areas. Therefore, this would require one channel per area to be OPERABLE or in trip (the channels are not required to be in the same trip system). The Condition does not include the Manual Initiation Functions (Functions 1.f, 2.g, 3.j, 4.m, and 5.c), since they are not assumed in any accident or transient analysis. Thus, a total loss of manual initiation capability for 24 hours (as allowed by Required Action A.1) is allowed.

(continued)

BASES

ACTIONS

B.1 (continued)

The Completion Time is intended to allow the operator time to evaluate and repair any discovered inoperabilities. The Completion Time is acceptable because it minimizes risk while allowing time for restoration or tripping of channels.

C.1

Required Action C.1 directs entry into the appropriate Condition referenced in Table 3.3.6.1-1. The applicable Condition specified in Table 3.3.6.1-1 is Function and MODE or other specified condition dependent and may change as the Required Action of a previous Condition is completed. Each time an inoperable channel has not met any Required Action of Condition A or B and the associated Completion Time has expired, Condition C will be entered for that channel and provides for transfer to the appropriate subsequent Condition.

D.1, D.2.1, and D.2.2

If the channel is not restored to OPERABLE status or placed in trip within the allowed Completion Time, the associated MSLs may be isolated (Required Action D.1), and if allowed (i.e., plant safety analysis allows operation with an MSL isolated), plant operation with the MSL isolated may continue. Isolating the affected MSL accomplishes the safety function of the inoperable channel. This Required Action will generally only be used if a Function 1.c channel is inoperable and untripped. The associated MSL(s) to be isolated are those whose Main Steam Line Flow-High Function channel(s) are inoperable. Alternatively, the plant must be placed in a MODE or other specified condition in which the LCO does not apply. This is done by placing the plant in at least MODE 3 within 12 hours and in MODE 4 within 36 hours (Required Actions D.2.1 and D.2.2). The Completion Times are reasonable, based on operating experience, to reach the required plant conditions from full power conditions in an orderly manner and without challenging plant systems.

(continued)

BASES

ACTIONS
(continued)

E.1

If the channel is not restored to OPERABLE status or placed in trip within the allowed Completion Time, the plant must be placed in a MODE or other specified condition in which the LCO does not apply. This is done by placing the plant in at least MODE 2 within 6 hours.

The allowed Completion Time of 6 hours is reasonable, based on operating experience, to reach MODE 2 from full power conditions in an orderly manner and without challenging plant systems.

F.1

If the channel is not restored to OPERABLE status or placed in trip within the allowed Completion Time, plant operation may continue if the affected penetration flow path(s) is isolated. Isolating the affected penetration flow path(s) accomplishes the safety function of the inoperable channels.

For some of the Area and Differential Temperature-High Functions, the affected penetration flow path(s) may be considered isolated by isolating only that portion of the system in the associated room monitored by the inoperable channel. That is, if the RWCU pump room A Area Temperature-High channel is inoperable, the A pump room area can be isolated while allowing continued RWCU operation utilizing the B RWCU pump.

Alternatively, if it is not desired to isolate the affected penetration flow path(s) (e.g., as in the case where isolating the penetration flow path(s) could result in a reactor scram), Condition H must be entered and its Required Actions taken.

The Completion Time is acceptable because it minimizes risk while allowing sufficient time for plant operations personnel to isolate the affected penetration flow path(s).

(continued)

BASES

ACTIONS
(continued)

G.1

If the channel is not restored to OPERABLE status or placed in trip within the allowed Completion Time, plant operations may continue if the affected penetration flow path(s) is isolated. Isolating the affected penetration flow path(s) accomplishes the safety function of the inoperable channels. The 24 hour Completion Time is acceptable due to the fact that these Functions (Manual Initiation) are not assumed in any accident or transient analysis in the UFSAR. Alternately, if it is not desired to isolate the affected penetration flow path(s) (e.g., as in the case where isolating the penetration flow path(s) could result in a reactor scram), Condition H must be entered and its Required Actions taken.

H.1 and H.2

If the channel is not restored to OPERABLE status or placed in trip, or any Required Action of Condition F or G is not met and the associated Completion Time has expired, the plant must be placed in a MODE or other specified condition in which the LCO does not apply. This is done by placing the plant in at least MODE 3 within 12 hours and in MODE 4 within 36 hours. The allowed Completion Times are reasonable, based on operating experience, to reach the required plant conditions from full power conditions in an orderly manner and without challenging plant systems.

I.1 and I.2

If the channel is not restored to OPERABLE status within the allowed Completion Time, the associated SLC subsystem(s) is declared inoperable or the RWCU System is isolated. Since this Function is required to ensure that the SLC System performs its intended function, sufficient remedial measures are provided by declaring the associated SLC subsystem inoperable or isolating the RWCU System.

The Completion Time of 1 hour is acceptable because it minimizes risk while allowing sufficient time for personnel to isolate the RWCU System.

(continued)

BASES

ACTIONS
(continued)

J.1 and J.2

If the channel is not restored to OPERABLE status or placed in trip within the allowed Completion Time, the associated penetration flow path should be closed. However, if the shutdown cooling function is needed to provide core cooling, these Required Actions allow the penetration flow path to remain unisolated provided action is immediately initiated to restore the channel to OPERABLE status or to isolate the RHR Shutdown Cooling System (i.e., provide alternate decay heat removal capabilities so the penetration flow path can be isolated). ACTIONS must continue until the channel is restored to OPERABLE status or the RHR Shutdown Cooling System is isolated.

SURVEILLANCE
REQUIREMENTS

As noted at the beginning of the SRs, the SRs for each Primary Containment Isolation Instrumentation Function are found in the SRs column of Table 3.3.6.1-1.

The Surveillances are also modified by a Note to indicate that when a channel is placed in an inoperable status solely for performance of required Surveillances, entry into associated Conditions and Required Actions may be delayed for up to 6 hours provided the associated Function maintains isolation capability. Upon completion of the Surveillance, or expiration of the 6 hour allowance, the channel must be returned to OPERABLE status or the applicable Condition entered and REQUIRED Actions taken. This Note is based on the reliability analyses (Refs. 9 and 10) assumption of the average time required to perform channel surveillance. That analysis demonstrated that the 6 hour testing allowance does not significantly reduce the probability that the PCIVs will isolate the penetration flow path(s) when necessary.

SR 3.3.6.1.1

Performance of the CHANNEL CHECK once every 12 hours ensures that a gross failure of instrumentation has not occurred. A CHANNEL CHECK is normally a comparison of the parameter indicated on one channel to a similar parameter on other channels. It is based on the assumption that instrument channels monitoring the same parameter should read

(continued)

BASES

SURVEILLANCE
REQUIREMENTS

SR 3.3.6.1.1 (continued)

approximately the same value. Significant deviations between the instrument channels could be an indication of excessive instrument drift in one of the channels or something even more serious. A CHANNEL CHECK will detect gross channel failure; thus, it is key to verifying the instrumentation continues to operate properly between each CHANNEL CALIBRATION.

Agreement criteria are determined by the plant staff, based on a combination of the channel instrument uncertainties, including indication and readability. If a channel is outside the criteria, it may be an indication that the instrument has drifted outside its limit.

The Frequency is based on operating experience that demonstrates channel failure is rare. The CHANNEL CHECK supplements less formal, but more frequent, checks of channels during normal operational use of the displays associated with the channels required by the LCO.

SR 3.3.6.1.2

A CHANNEL FUNCTIONAL TEST is performed on each required channel to ensure that the channel will perform the intended function. A successful test of the required contact(s) of a channel relay may be performed by the verification of the change of state of a single contact of the relay. This clarifies what is an acceptable CHANNEL FUNCTIONAL TEST of a relay. This is acceptable because all of the other required contacts of the relay are verified by other Technical Specifications and non-Technical Specifications tests at least once per refueling interval with applicable extensions. Any setpoint adjustment shall be consistent with the assumptions of the current plant specific setpoint methodology.

The Frequency of 92 days is based on reliability analyses described in References 9 and 10.

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BASES

SURVEILLANCE
REQUIREMENTS
(continued)

SR 3.3.6.1.3 and SR 3.3.6.1.4

CHANNEL CALIBRATION is a complete check of the instrument loop and the sensor. This test verifies the channel responds to the measured parameter within the necessary range and accuracy. CHANNEL CALIBRATION leaves the channel adjusted to account for instrument drifts between successive calibrations, consistent with the plant specific setpoint methodology.

The Frequencies are based on the assumption of a 92 day or 24 month calibration interval, as applicable, in the determination of the magnitude of equipment drift in the setpoint analysis.

SR 3.3.6.1.5

The LOGIC SYSTEM FUNCTIONAL TEST demonstrates the OPERABILITY of the required isolation logic for a specific channel. The system functional testing performed on PCIVs in LCO 3.6.1.3 overlaps this Surveillance to provide complete testing of the assumed safety function. The 24 month Frequency is based on the need to perform this Surveillance under the conditions that apply during a plant outage and the potential for an unplanned transient if the Surveillance were performed with the reactor at power. Operating experience has shown these components usually pass the Surveillance when performed at the 24 month Frequency.

SR 3.3.6.1.6

This SR ensures that the individual channel response times are less than or equal to the maximum values assumed in the accident analysis. Testing is performed only on channels where the assumed response time does not correspond to the diesel generator (DG) start time. For channels assumed to respond within the DG start time, sufficient margin exists in the 13 second start time when compared to the typical channel response time (milliseconds) so as to assure adequate response without a specific measurement test. The instrument response times must be added to the MSIV closure times to obtain the ISOLATION SYSTEM RESPONSE TIME. However, failure to meet the ISOLATION SYSTEM RESPONSE TIME

(continued)

BASES

SURVEILLANCE
REQUIREMENTS

SR 3.3.6.1.6 (continued)

due to a MSIV closure time not within limits does not require the associated instrumentation to be declared inoperable; only the MSIV is required to be declared inoperable.

ISOLATION SYSTEM RESPONSE TIME acceptance criteria are included in Reference 11.

ISOLATION SYSTEM RESPONSE TIME may be verified by actual response time measurements in any series of sequential, overlapping, or total channel measurements. However, the sensors for Functions 1.a, 1.b, and 1.c are allowed to be excluded from specific ISOLATION SYSTEM RESPONSE TIME measurement if the conditions of Reference 12 are satisfied. If these conditions are satisfied, sensor response time may be allocated based on either assumed design sensor response time or the manufacturer's stated design response time. When the requirements of Reference 12 are not satisfied, sensor response time must be measured. Also, regardless of whether or not the sensor response time is measured, the response time of the remaining portion of the channel, including the trip unit and relay logic, is required to be measured.

ISOLATION SYSTEM RESPONSE TIME tests are conducted on a 24 month STAGGERED TEST BASIS. The 24 month test Frequency is consistent with the refueling cycle and is based upon plant operating experience that shows that random failures of instrumentation components causing serious response time degradation, but not channel failure, are infrequent.

REFERENCES

1. UFSAR, Table 6.2-21.
2. UFSAR, Section 6.2.1.1.
3. UFSAR, Chapter 15.
4. UFSAR, Section 15.1.3.

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BASES

- REFERENCES
(continued)
5. UFSAR, Section 15.6.4.
 6. UFSAR, Section 15.2.5
 7. UFSAR, Section 15.4.9.
 8. UFSAR, Section 9.3.5.
 9. NEDC-31677-P-A, "Technical Specification Improvement Analysis for BWR Isolation Actuation Instrumentation," July 1990.
 10. NEDC-30851-P-A, Supplement 2, "Technical Specifications Improvement Analysis for BWR Isolation Instrumentation Common to RPS and ECCS Instrumentation," March 1989.
 11. Technical Requirements Manual.
 12. NED0-32291-A, "System Analyses for the Elimination of Selected Response Time Testing Requirements," October 1995.
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B 3.3 INSTRUMENTATION

B 3.3.6.2 Secondary Containment Isolation Instrumentation

BASES

BACKGROUND

The secondary containment isolation instrumentation automatically initiates closure of appropriate secondary containment isolation valves (SCIVs) and starts the Standby Gas Treatment (SGT) System. The function of these systems, in combination with other accident mitigation systems, is to limit fission product release during and following postulated Design Basis Accidents (DBAs) (Refs. 1 and 2), such that offsite radiation exposures are maintained within the requirements of 10 CFR 100 that are part of the NRC staff approved licensing basis. Secondary containment isolation and establishment of vacuum with the SGT System within the assumed time limits ensures that fission products that are released during certain operations that take place inside primary containment or during certain operations when primary containment is not required to be OPERABLE or that take place outside primary containment, are maintained within applicable limits.

The isolation instrumentation includes the sensors, relays, and switches that are necessary to cause initiation of secondary containment isolation. Most channels include electronic equipment (e.g., trip units) that compares measured input signals with pre-established setpoints. When the setpoint is exceeded, the channel output relay actuates, which then outputs a secondary containment isolation signal to the isolation logic. Functional diversity is provided by monitoring a wide range of independent parameters. The input parameters to the isolation logic are (a) reactor vessel water level, (b) drywell pressure, (c) reactor building ventilation exhaust plenum radiation, and (d) fuel pool ventilation exhaust radiation. Redundant sensor input signals from each parameter are provided for initiation of isolation parameters. In addition, manual initiation of the logic is provided.

For each secondary containment isolation instrumentation Function, the logic receives input from four channels. The output from these channels are arranged into two two-out-of-two trip systems. In addition to the isolation function, the SGT subsystems are initiated. There are two SGT

(continued)

BASES

BACKGROUND (continued) subsystems with both subsystems being initiated by each trip system. Automatically isolated secondary containment penetrations are isolated by two isolation valves. Each trip system initiates isolation of one of two SCIVs so that operation of either trip system isolates the associated penetrations.

APPLICABLE SAFETY ANALYSES, LCO, and APPLICABILITY The isolation signals generated by the secondary containment isolation instrumentation are implicitly assumed in the safety analyses of References 1 and 2 to initiate closure of the SCIVs and start the SGT System to limit offsite doses.

Refer to LCO 3.6.4.2, "Secondary Containment Isolation Valves (SCIVs)," and LCO 3.6.4.3, "Standby Gas Treatment (SGT) System," Applicable Safety Analyses Bases for more detail of the safety analyses.

The secondary containment isolation instrumentation satisfies Criterion 3 of 10 CFR 50.36(c)(2)(ii). Certain instrumentation Functions are retained for other reasons and are described below in the individual Functions discussion.

The OPERABILITY of the secondary containment isolation instrumentation is dependent upon the OPERABILITY of the individual instrumentation channel Functions. Each Function must have the required number of OPERABLE channels with their setpoints set within the specified Allowable Values, as shown in Table 3.3.6.2-1. The actual setpoint is calibrated consistent with applicable setpoint methodology assumptions.

Allowable Values are specified for each Function specified in the Table. Nominal trip setpoints are specified in setpoint calculations. The nominal setpoints are selected to ensure that the setpoints do not exceed the Allowable Values between CHANNEL CALIBRATIONS. Operation with a trip setpoint less conservative than the nominal trip setpoint, but within its Allowable Value, is acceptable. A channel is inoperable if its actual trip setpoint is not within its required Allowable Value.

Trip setpoints are those predetermined values of output at which an action should take place. The setpoints are compared to the actual process parameter (e.g., reactor

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BASES

APPLICABLE
SAFETY ANALYSES,
LCO, and
APPLICABILITY
(continued)

vessel water level), and when the measured output value of the process parameter exceeds the setpoint, the associated device (e.g., trip unit) changes state. The analytic limits are derived from the limiting values of the process parameters obtained from the safety analysis. The trip setpoints are determined from the analytic limits, corrected for defined process, calibration, and instrument errors. The Allowable Values are then determined, based on the trip setpoint values, by accounting for the calibration based errors. These calibration based errors are limited to reference accuracy, instrument drift, errors associated with measurement and test equipment, and calibration tolerance of loop components. The trip setpoints and Allowable Values determined in this manner provide adequate protection because instrument uncertainties, process effects, calibration tolerances, instrument drift, and severe environment errors (for channels that must function in harsh environments as defined by 10 CFR 50.49) are accounted for and appropriately applied for the instrumentation.

In general, the individual Functions are required to be OPERABLE in the MODES or other specified conditions when SCIVs and the SGT System are required.

The specific Applicable Safety Analyses, LCO, and Applicability discussions are listed below on a Function by Function basis.

1. Reactor Vessel Water Level—Low Low, Level 2

Low reactor pressure vessel (RPV) water level indicates that the capability to cool the fuel may be threatened. Should RPV water level decrease too far, fuel damage could result. An isolation of the secondary containment and actuation of the SGT System are initiated in order to minimize the potential of an offsite dose release. The Reactor Vessel Water Level—Low Low, Level 2 Function is one of the Functions assumed to be OPERABLE and capable of providing isolation and initiation signals. The isolation and initiation of systems on Reactor Vessel Water Level—Low Low, Level 2 support actions to ensure that any offsite releases are within the limits calculated in the safety analysis (Ref. 1).

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BASES

APPLICABLE
SAFETY ANALYSES,
LCO, and
APPLICABILITY

1. Reactor Vessel Water Level—Low Low, Level 2
(continued)

Reactor Vessel Water Level—Low Low, Level 2 signals are initiated from differential pressure transmitters that sense the difference between the pressure due to a constant column of water (reference leg) and the pressure due to the actual water level (variable leg) in the vessel. Four channels of Reactor Vessel Water Level—Low Low, Level 2 Function are available and are required to be OPERABLE to ensure that no single instrument failure can preclude the isolation function.

The Reactor Vessel Water Level—Low Low, Level 2 Allowable Value was chosen to be the same as the High Pressure Core Spray (HPCS)/Reactor Core Isolation Cooling (RCIC) Reactor Vessel Water Level—Low Low, Level 2 Allowable Value (LCO 3.3.5.1, "Emergency Core Cooling System (ECCS) Instrumentation," and LCO 3.3.5.2, "Reactor Core Isolation Cooling (RCIC) System Instrumentation"), since this could indicate the capability to cool the fuel is being threatened.

The Reactor Vessel Water Level—Low Low, Level 2 Function is required to be OPERABLE in MODES 1, 2, and 3 where considerable energy exists in the Reactor Coolant System (RCS); thus, there is a probability of pipe breaks resulting in significant releases of radioactive steam and gas. In MODES 4 and 5, the probability and consequences of these events are low due to the RCS pressure and temperature limitations of these MODES; thus, this Function is not required. In addition, the Function is also required to be OPERABLE during operations with a potential for draining the reactor vessel (OPDRVs) to ensure that offsite dose limits are not exceeded if core damage occurs.

2. Drywell Pressure—High

High drywell pressure can indicate a break in the reactor coolant pressure boundary (RCPB). An isolation of the secondary containment and actuation of the SGT System are initiated in order to minimize the potential of an offsite dose release. The isolation and initiation of systems on Drywell Pressure—High supports actions to ensure that any offsite releases are within the limits calculated in the

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BASES

APPLICABLE
SAFETY ANALYSES,
LCO, and
APPLICABILITY

2. Drywell Pressure-High (continued)

safety analysis. However, the Drywell Pressure-High Function associated with isolation is not assumed in any UFSAR accident or transient analysis. It is retained for the overall redundancy and diversity of the secondary containment isolation instrumentation as required by the NRC approved licensing basis.

High drywell pressure signals are initiated from pressure switches that sense the pressure in the drywell. Four channels of Drywell Pressure-High Function are available and are required to be OPERABLE to ensure that no single instrument failure can preclude the isolation function.

The Allowable Value was chosen to be the same as the RPS Drywell Pressure-High Function Allowable Value (LCO 3.3.1.1) since this is indicative of a loss of coolant accident.

The Drywell Pressure-High Function is required to be OPERABLE in MODES 1, 2, and 3 where considerable energy exists in the RCS; thus, there is a probability of pipe breaks resulting in significant releases of radioactive steam and gas. This Function is not required in MODES 4 and 5 because the probability and consequences of these events are low due to the RCS pressure and temperature limitations of these MODES.

3. 4. Reactor Building Ventilation Exhaust Plenum and Fuel Pool Ventilation Exhaust Radiation-High

High secondary containment exhaust radiation is an indication of possible gross failure of the fuel cladding. The release may have originated from the primary containment due to a break in the RCPB or the refueling floor due to a fuel handling accident. When Exhaust Radiation-High is detected, secondary containment isolation and actuation of the SGT System are initiated to limit the release of fission products as assumed in the UFSAR safety analyses (Refs. 1 and 2).

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BASES

APPLICABLE
SAFETY ANALYSES,
LCO, and
APPLICABILITY

3, 4. Reactor Building Ventilation Exhaust Plenum and Fuel
Pool Ventilation Exhaust Radiation-High (continued)

Reactor Building Ventilation Exhaust Plenum Radiation-High signals are initiated from radiation detectors that are located in the reactor building return air riser above the upper area of the steam tunnel prior to the reactor building ventilation isolation dampers. Fuel Pool Ventilation Exhaust Radiation-High signals are initiated from radiation detectors that are located in the reactor building exhaust ducting coming from the refuel floor. The signal from each detector is input to an individual monitor whose trip outputs are assigned to an isolation channel. Four channels of Reactor Building Ventilation Exhaust Plenum Radiation-High Function and four channels of Fuel Pool Ventilation Exhaust Radiation-High Function are available and are required to be OPERABLE to ensure that no single instrument failure can preclude the isolation function.

The Allowable Values are chosen to promptly detect gross failure of the fuel cladding.

The Reactor Building Ventilation Exhaust Plenum and Fuel Pool Ventilation Exhaust Radiation-High Functions are required to be OPERABLE in MODES 1, 2, and 3 where considerable energy exists; thus, there is a probability of pipe breaks resulting in significant releases of radioactive steam and gas. In MODES 4 and 5, the probability and consequences of these events are low due to the RCS pressure and temperature limitations of these MODES; thus, these Functions are not required. In addition, the Functions are required to be OPERABLE during CORE ALTERATIONS, OPDRVs, and movement of irradiated fuel assemblies in the secondary containment because the capability of detecting radiation releases due to fuel failures (due to fuel uncover or dropped fuel assemblies) must be provided to ensure that offsite dose limits are not exceeded.

5. Manual Initiation

The Manual Initiation push button channels introduce signals into the secondary containment isolation logic that are redundant to the automatic protective instrumentation channels, and provide manual isolation capability. There is

(continued)

BASES

APPLICABLE
SAFETY ANALYSES,
LCO, and
APPLICABILITY

5. Manual Initiation (continued)

no specific UFSAR safety analysis that takes credit for this Function. It is retained for the overall redundancy and diversity of the secondary containment isolation instrumentation as required by the NRC approved licensing basis.

There is one manual initiation push button for the logic per trip system. Two channels of the Manual Initiation Function are available and are required to be OPERABLE in MODES 1, 2, and 3 and during CORE ALTERATIONS, OPDRVs, and movement of irradiated fuel assemblies in the secondary containment, since these are the MODES and other specified conditions in which the Secondary Containment Isolation automatic Functions are required to be OPERABLE. There is no Allowable Value for this Function since the channels are mechanically actuated based solely on the position of the push buttons.

ACTIONS

A Note has been provided to modify the ACTIONS related to secondary containment isolation instrumentation channels. Section 1.3, Completion Times, specifies that once a Condition has been entered, subsequent divisions, subsystems, components, or variables expressed in the Condition discovered to be inoperable or not within limits will not result in separate entry into the Condition. Section 1.3 also specifies that Required Actions of the Condition continue to apply for each additional failure, with Completion Times based on initial entry into the Condition. However, the Required Actions for inoperable secondary containment isolation instrumentation channels provide appropriate compensatory measures for separate inoperable channels. As such, a Note has been provided that allows separate Condition entry for each inoperable secondary containment isolation instrumentation channel.

A.1

Because of the diversity of sensors available to provide isolation signals and the redundancy of the isolation design, an allowable out of service time of 12 hours or 24 hours, depending on the Function (12 hours for those

(continued)

BASES

ACTIONS

A.1 (continued)

Functions that have channel components common to RPS instrumentation and 24 hours for those Functions that do not have channel components common to RPS instrumentation), has been shown to be acceptable (Refs. 3 and 4) to permit restoration of any inoperable channel to OPERABLE status. This out of service time is only acceptable provided the associated Function is still maintaining isolation capability (refer to Required Action B.1 Bases). If the inoperable channel cannot be restored to OPERABLE status within the allowable out of service time, the channel must be placed in the tripped condition per Required Action A.1. Placing the inoperable channel in trip would conservatively compensate for the inoperability, restore capability to accommodate a single failure, and allow operation to continue. Alternately, if it is not desired to place the channel in trip (e.g., as in the case where placing the inoperable channel in trip would result in an isolation), Condition C must be entered and its Required Actions taken.

B.1

Required Action B.1 is intended to ensure that appropriate actions are taken if multiple, inoperable, untripped channels within the same Function result in a complete loss of automatic isolation capability for the associated penetration flow path(s) or a complete loss of automatic initiation capability for the SGT System. A Function is considered to be maintaining isolation capability when sufficient channels are OPERABLE or in trip, such that one trip system will generate a trip signal from the given Function on a valid signal. This ensures that one of the two SCIVs in the associated penetration flow path and the SGT subsystems can be initiated on an isolation signal from the given Function. For the Functions with two two-out-of-two logic trip systems (Functions 1, 2, 3, and 4), this would require one trip system to have two channels, each OPERABLE or in trip. The Condition does not include the Manual Initiation Function (Function 5), since it is not assumed in any accident or transient analysis. Thus, a total loss of manual initiation capability for 24 hours (as allowed by Required Action A.1) is allowed.

(continued)

BASES

ACTIONS

B.1 (continued)

The Completion Time is intended to allow the operator time to evaluate and repair any discovered inoperabilities. The 1 hour Completion Time is acceptable because it minimizes risk while allowing time for restoration or tripping of channels.

C.1.1, C.1.2, C.2.1, and C.2.2

If any Required Action and associated Completion Time are not met, the ability to isolate the secondary containment and start the SGT System cannot be ensured. Therefore, further actions must be performed to ensure the ability to maintain the secondary containment function. Isolating the associated penetration flow path(s) and starting the associated SGT subsystem(s) (Required Actions C.1.1 and C.2.1) performs the intended function of the instrumentation and allows operations to continue. The method used to place the SGT subsystem(s) in operation must provide for automatically reinitiating the subsystem(s) upon restoration of power following a loss of power to the SGT subsystem(s).

Alternatively, declaring the associated SCIV(s) or SGT subsystem(s) inoperable (Required Actions C.1.2 and C.2.2) is also acceptable since the Required Actions of the respective LCOs (LCO 3.6.4.2 and LCO 3.6.4.3) provide appropriate actions for the inoperable components.

One hour is sufficient for plant operations personnel to establish required plant conditions or to declare the associated components inoperable without challenging plant systems.

SURVEILLANCE
REQUIREMENTS

As noted at the beginning of the SRs, the SRs for each Secondary Containment Isolation instrumentation Function are located in the SRs column of Table 3.3.6.2-1.

The Surveillances are also modified by a Note to indicate that when a channel is placed in an inoperable status solely for performance of required Surveillances, entry into associated Conditions and Required Actions may be delayed

(continued)

BASES

SURVEILLANCE
REQUIREMENTS
(continued)

for up to 6 hours, provided the associated Function maintains isolation capability. Upon completion of the Surveillance, or expiration of the 6 hour allowance, the channel must be returned to OPERABLE status or the applicable Condition entered and Required Action(s) taken.

This Note is based on the reliability analysis (Refs. 3 and 4) assumption of the average time required to perform channel surveillance. That analysis demonstrated that the 6 hour testing allowance does not significantly reduce the probability that the SCIVs will isolate the associated penetration flow paths and the SGT System will initiate when necessary.

SR 3.3.6.2.1

Performance of the CHANNEL CHECK once every 12 hours ensures that a gross failure of instrumentation has not occurred. A CHANNEL CHECK is normally a comparison of the indicated parameter for one instrument channel to a similar parameter on other channels. It is based on the assumption that instrument channels monitoring the same parameter should read approximately the same value. Significant deviations between the instrument channels could be an indication of excessive instrument drift in one of the channels or something even more serious. A CHANNEL CHECK will detect gross channel failure; thus, it is key to verifying the instrumentation continues to operate properly between each CHANNEL CALIBRATION.

Agreement criteria are determined by the plant staff, based on a combination of the channel instrument uncertainties, including indication and readability. If a channel is outside the criteria, it may be an indication that the instrument has drifted outside its limit.

The Frequency is based on operating experience that demonstrates channel failure is rare. The CHANNEL CHECK supplements less formal, but more frequent, checks of channels during normal operational use of the displays associated with the channels required by the LCO.

(continued)

BASES

SURVEILLANCE
REQUIREMENTS
(continued)

SR 3.3.6.2.2

A CHANNEL FUNCTIONAL TEST is performed on each required channel to ensure that the channel will perform the intended function. A successful test of the required contact(s) of a channel relay may be performed by the verification of the change of state of a single contact of the relay. This clarifies what is an acceptable CHANNEL FUNCTIONAL TEST of a relay. This is acceptable because all of the other required contacts of the relay are verified by other Technical Specifications and non-Technical Specifications tests at least once per refueling interval with applicable extensions. Any setpoint adjustment shall be consistent with the assumptions of the current plant specific setpoint methodology.

The Frequency of 92 days is based upon the reliability analysis of References 3 and 4.

SR 3.3.6.2.3

CHANNEL CALIBRATION is a complete check of the instrument loop and the sensor. This test verifies the channel responds to the measured parameter within the necessary range and accuracy. CHANNEL CALIBRATION leaves the channel adjusted to account for instrument drifts between successive calibrations consistent with the plant specific setpoint methodology.

The Frequency is based upon the assumption of a 24 month calibration interval in the determination of the magnitude of equipment drift in the setpoint analysis.

SR 3.3.6.2.4

The LOGIC SYSTEM FUNCTIONAL TEST demonstrates the OPERABILITY of the required isolation logic for a specific channel. The system functional testing, performed on SCIVs and the SGT System in LCO 3.6.4.2 and LCO 3.6.4.3, respectively, overlaps this Surveillance to provide complete testing of the assumed safety function.

(continued)

BASES

SURVEILLANCE
REQUIREMENTS

SR 3.3.6.2.4 (continued)

The 24 month Frequency is based on the need to perform this Surveillance under the conditions that apply during a plant outage and the potential for an unplanned transient if the Surveillance were performed with the reactor at power. Operating experience has shown these components usually pass the Surveillance when performed at the 24 month Frequency.

REFERENCES

1. UFSAR, Section 15.6.5.
 2. UFSAR, Section 15.7.4.
 3. NEDC-31677-P-A, "Technical Specification Improvement Analysis for BWR Isolation Actuation Instrumentation," July 1990.
 4. NEDC-30851-P-A Supplement 2, "Technical Specifications Improvement Analysis for BWR Isolation Instrumentations Common to RPS and ECCS Instrumentation," March 1989.
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B 3.3 INSTRUMENTATION

B 3.3.7.1 Control Room Area Filtration (CRAF) System Instrumentation

BASES

BACKGROUND

The CRAF System is designed to provide a radiologically controlled environment to ensure the habitability of the control room for the safety of control room operators under all plant conditions. Two independent CRAF subsystems are each capable of fulfilling the stated safety function. The instrumentation and controls for the CRAF System automatically initiate action to isolate and pressurize the control room area to minimize the consequences of radioactive material in the control room area environment.

In the event of a Control Room Air Intake Radiation-High signal, the CRAF System is automatically placed in the pressurization mode. In this mode the normal outside air supply to the system is closed and is diverted to the emergency makeup filter train where it passes through a charcoal filter and is delivered to the suction of the control room return air fan and the suction of the auxiliary electric equipment room supply fan. Recirculated control room air is combined with the emergency makeup filter train air and delivered to the control room area via the supply fan. The addition of outside air through the emergency filter train will keep the control room area slightly pressurized with respect to surrounding areas. A description of the CRAF System is provided in the Bases for LCO 3.7.4, "Control Room Area Filtration (CRAF) System."

The CRAF System (Ref. 1) instrumentation has 4 trip systems, two for each of the air intakes: two trip systems initiate one CRAF subsystem, while the other trip systems initiate the other CRAF subsystem. For each CRAF subsystem, the associated two trip systems are arranged in a one-out-of-two logic (i.e., either trip system can actuate the CRAF subsystem). Each trip system receives input from two Control Room Air Intake Radiation-High channels. The Control Room Air Intake Radiation-High channels are arranged in a two-out-of-two logic for each trip system. The channels include electronic equipment (e.g., trip units)

(continued)

BASES

BACKGROUND (continued) that compares measured input signals with pre-established setpoints. When the setpoint is exceeded, the channel output relay actuates, which then outputs a CRAF System initiation signal to the initiation logic.

APPLICABLE SAFETY ANALYSES The ability of the CRAF System to maintain the habitability of the control room area is explicitly assumed for certain accidents as discussed in the UFSAR safety analyses (Refs. 2 and 3). CRAF System operation ensures that the radiation exposure of control room personnel, through the duration of any one of the postulated accidents, does not exceed the limits set by GDC 19 of 10 CFR 50, Appendix A.

CRAF System instrumentation satisfies Criterion 3 of 10 CFR 50.36(c)(2)(ii).

LCO High radiation at the intake ducts of the control room outside air intakes is an indication of possible gross failure of the fuel cladding. The release may have originated from the primary containment due to a break in the RCPB or the refueling floor due to a fuel handling accident. When control room air intake high radiation is detected, the associated CRAF subsystem is automatically initiated in the pressurization mode since this radiation release could result in radiation exposure to control room personnel.

The Control Room Air Intake Radiation-High Function consists of eight independent monitors, with four monitors associated with one CRAF subsystem and the other four monitors associated with the other CRAF subsystem. Each of the four monitors associated with a CRAF subsystem are arranged in two trip systems, with each trip system containing two radiation monitors. Eight channels of the Control Room Air Intake Radiation-High Function are available and required to be OPERABLE to ensure no single instrument failure can preclude CRAF System initiation. The Allowable Value was selected to ensure protection of the control room personnel.

(continued)

BASES

LCO
(continued)

Each channel must have its setpoint set within the specified Allowable Value of SR 3.3.7.1.3. The actual setpoint is calibrated consistent with applicable setpoint methodology assumptions. Nominal trip setpoints are specified in the setpoint calculations. These nominal setpoints are selected to ensure that the setpoints do not exceed the Allowable Value between successive CHANNEL CALIBRATIONS. Operation with a trip setpoint that is less conservative than the nominal trip setpoint, but within its Allowable Value, is acceptable. A channel is inoperable if its actual trip setpoint is not within its required Allowable Value.

Trip setpoints are those predetermined values of output at which an action should take place. The setpoints are compared to the actual process parameter (e.g., control room air intake radiation), and when the measured output value of the process parameter exceeds the setpoint, the associated device (e.g., trip unit) changes state. The analytic limits are derived from the limiting values of the process parameters obtained from the safety analysis. The trip setpoints are determined from the analytic limits, corrected for defined process, calibration, and instrument errors. The Allowable Values are then determined, based on the trip setpoint values, by accounting for the calibration based errors. These calibration based errors are limited to reference accuracy, instrument drift, errors associated with measurement and test equipment, and calibration tolerance of loop components. The trip setpoints and Allowable Values determined in this manner provide adequate protection because instrument uncertainties, process effects, calibration tolerances, instrument drift, and severe environment errors (for channels that must function in harsh environments as defined by 10 CFR 50.49) are accounted for and appropriately applied for the instrumentation.

APPLICABILITY

The Control Room Air Intake Radiation-High Function is required to be OPERABLE in MODES 1, 2, and 3, and during CORE ALTERATIONS, OPDRVs, and movement of irradiated fuel in the secondary containment to ensure that control room personnel are protected during a LOCA, fuel handling event, or a vessel draindown event. During MODES 4 and 5, when these specified conditions are not in progress (e.g., CORE ALTERATIONS), the probability of a LOCA or fuel damage is low; thus, the Function is not required.

(continued)

BASES (continued)

ACTIONS

A Note has been provided to modify the ACTIONS related to CRAF System instrumentation channels. Section 1.3, Completion Times, specifies that once a Condition has been entered, subsequent divisions, subsystems, components, or variables expressed in the Condition discovered to be inoperable or not within limits will not result in separate entry into the Condition. Section 1.3 also specifies that Required Actions of the Condition continue to apply for each additional failure, with Completion Times based on initial entry into the Condition. However, the Required Actions for inoperable CRAF System instrumentation channels provide appropriate compensatory measures for separate inoperable channels. As such, a Note has been provided that allows separate Condition entry for each inoperable CRAF System instrumentation channel.

A.1 and A.2

Because of the redundancy of sensors available to provide initiation signals and the redundancy of the CRAF System design, an allowable out of service time of 6 hours is provided to permit restoration of any inoperable channel to OPERABLE status. However, this out of service time is only acceptable provided the Function is still maintaining CRAF subsystem initiation capability. A Function is considered to be maintaining CRAF subsystem initiation capability when sufficient channels are OPERABLE or in trip, such that at least one trip system will generate an initiation signal on a valid signal. This would require one trip system to have two channels, each OPERABLE or in trip. In this situation (loss of CRAF subsystem initiation capability), the 6 hour allowance of Required Action A.2 is not appropriate. If the Function is not maintaining CRAF subsystem initiation capability, the CRAF subsystem must be declared inoperable within 1 hour of discovery of loss of CRAF subsystem initiation capability.

This Completion Time also allows for an exception to the normal "time zero" for beginning the allowed outage time "clock." For Required Action A.1, the Completion Time only begins upon discovery that the CRAF subsystem cannot be automatically initiated due to inoperable, untripped Control

(continued)

BASES

ACTIONS A.1 and A.2 (continued)

Room Air Intake Radiation—High channels in both trip systems in any air intake. The 1 hour Completion Time is acceptable because it minimizes risk while allowing time for restoring or tripping of channels. If it is not desired to declare the CRAF subsystem inoperable, Condition B may be entered and Required Action B.1 taken.

If the inoperable channel cannot be restored to OPERABLE status within the allowable out of service time, the channel must be placed in the tripped condition, per Required Action A.2. Placing the inoperable channel in trip performs the intended function of the channel. Alternately, if it is the second channel and it is not desired to place the channel in trip (e.g., as in the case where it is not desired to start the subsystem), Condition B must be entered and its Required Actions taken.

The 6 hour Completion Time is based on the consideration that this Function provides the primary signal to start the CRAF subsystem, thus ensuring that the design basis of the CRAF subsystem is met.

B.1 and B.2

With any Required Action and associated Completion Time not met, the associated CRAF subsystem must be placed in the pressurization mode of operation (Required Action B.1) to ensure that control room personnel will be protected in the event of a Design Basis Accident. The method used to place the CRAF subsystem in operation must provide for automatically reinitiating the subsystem upon restoration of power following a loss of power to the CRAF subsystem(s). Alternately, if it is not desired to start the subsystem, the CRAF subsystem associated with inoperable, untripped channels must be declared inoperable within 1 hour.

The 1 hour Completion Time is intended to allow the operator time to place the CRAF subsystem in operation. The 1 hour Completion Time is acceptable because it minimizes risk while allowing time for restoration or tripping of channels, or for placing the associated CRAF subsystem in operation.

(continued)

BASES (continued)

SURVEILLANCE
REQUIREMENTS

The Surveillances are modified by a Note to indicate that when a channel is placed in an inoperable status solely for performance of required Surveillances, entry into associated Conditions and Required Actions may be delayed for up to 6 hours, provided the associated Function maintains CRAF subsystem initiation capability. Upon completion of the surveillance, or expiration of the 6 hour allowance, the channel must be returned to OPERABLE status or the applicable Condition entered and Required Actions taken. This Note is based on the reliability analysis (Refs. 4 and 5) assumption of the average time required to perform channel surveillance. That analysis demonstrated that the 6 hour testing allowance does not significantly reduce the probability that the CRAF System will initiate when necessary.

SR 3.3.7.1.1

Performance of the CHANNEL CHECK once every 12 hours ensures that a gross failure of instrumentation has not occurred. A CHANNEL CHECK is normally a comparison of the indicated parameter for one instrument channel to a similar parameter on other channels. It is based on the assumption that instrument channels monitoring the same parameter should read approximately the same value. Significant deviations between the instrument channels could be an indication of excessive instrument drift in one of the channels or something even more serious. A CHANNEL CHECK will detect gross channel failure; thus, it is key to verifying the instrumentation continues to operate properly between each CHANNEL CALIBRATION.

Agreement criteria are determined by the plant staff based on a combination of the channel instrument uncertainties, including indication and readability. If a channel is outside the criteria, it may be an indication that the instrument has drifted outside its limit.

The Frequency is based upon operating experience that demonstrates channel failure is rare. The CHANNEL CHECK supplements less formal, but more frequent, checks of channel status during normal operational use of the displays associated with channels required by the LCO.

(continued)

BASES

SURVEILLANCE
REQUIREMENTS
(continued)

SR 3.3.7.1.2

A CHANNEL FUNCTIONAL TEST is performed on each required channel to ensure that the channel will perform the intended function. A successful test of the required contact(s) of a channel relay may be performed by the verification of the change of state of a single contact of the relay. This clarifies what is an acceptable CHANNEL FUNCTIONAL TEST of a relay. This is acceptable because all of the other required contacts of the relay are verified by other Technical Specifications and non-Technical Specifications tests at least once per refueling interval with applicable extensions. Any setpoint adjustment shall be consistent with the assumptions of the current plant specific setpoint methodology.

The Frequency of 92 days is based on the reliability analyses of References 4 and 5.

SR 3.3.7.1.3

A CHANNEL CALIBRATION is a complete check of the instrument loop and the sensor. This test verifies the channel responds to the measured parameter within the necessary range and accuracy. CHANNEL CALIBRATION leaves the channel adjusted to account for instrument drifts between successive calibrations consistent with the plant specific setpoint methodology.

The Frequency is based on the assumption of a 24 month calibration interval in the determination of the magnitude of equipment drift in the setpoint analysis.

SR 3.3.7.1.4

The LOGIC SYSTEM FUNCTIONAL TEST demonstrates the OPERABILITY of the required initiation logic for a specific channel. The system functional testing performed in LCO 3.7.4, "Control Room Area Filtration (CRAF) System," overlaps this Surveillance to provide complete testing of the assumed safety function.

(continued)

BASES

SURVEILLANCE
REQUIREMENTS

SR 3.3.7.1.4 (continued)

While the Surveillance can be performed with the reactor at power, operating experience has shown these components usually pass the Surveillance when performed at the 24 month Frequency, which is based on the refueling cycle. Therefore, the Frequency was concluded to be acceptable from a reliability standpoint.

REFERENCES

1. UFSAR, Sections 7.3.4 and 9.4.1.
 2. UFSAR, Section 6.4.
 3. UFSAR, Chapter 15.
 4. GENE-770-06-1A, "Bases for Changes to Surveillance Test Intervals and Allowed Out-of-Service Times for Selected Instrumentation Technical Specifications," December 1992.
 5. NEDC-31677P-A, "Technical Specification Improvement Analysis for BWR Isolation Actuation Instrumentation," July 1990.
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B 3.3 INSTRUMENTATION

B 3.3.8.1 Loss of Power (LOP) Instrumentation

BASES

BACKGROUND

Successful operation of the required safety functions of the Emergency Core Cooling Systems (ECCS) is dependent upon the availability of adequate power sources for energizing the various components such as pump motors, motor operated valves, and the associated control components. The LOP instrumentation monitors the 4.16 kV emergency buses. Offsite power is the preferred source of power for the 4.16 kV emergency buses. If the monitors determine that insufficient voltage is available, the buses are disconnected from the offsite power sources and connected to the onsite diesel generator (DG) power sources.

Each 4.16 kV emergency bus has its own independent LOP instrumentation and associated trip logic. The voltage for the Division 1, 2, and 3 buses is monitored at two levels, which can be considered as two different undervoltage functions: loss of voltage and degraded voltage.

For Division 1 and 2, each loss of voltage and degraded voltage function is monitored by two instruments per bus whose output trip contacts are arranged in a two-out-of-two logic configuration per bus (Ref. 1). The loss of voltage signal is generated when a loss of voltage occurs for a specific time interval. Lower voltage conditions will result in decreased trip times for the inverse time undervoltage relays. The degraded voltage signal is generated when a degraded voltage occurs for a specified time interval; the time interval is dependent upon whether a loss of coolant accident signal is present. The relays utilized are inverse time delay voltage relays or instantaneous voltage relays with a time delay.

For Division 3, the degraded voltage function logic is the same as for Divisions 1 and 2, but the Division 3 loss of voltage function logic is different. The Division 3 DG will auto-start if either one of the two bus undervoltage relays (with a time delay) actuates and the DG output breaker will automatically close with the same undervoltage permissive provided that the Division 3 bus main feeder breaker is open and the DG speed and voltage permissives are met. The Division 3 bus main feed breaker trip logic includes two

(continued)

BASES

BACKGROUND
(continued)

trip systems. Each trip system consists of an undervoltage relay on the 4.16 kV bus (with a time delay) and an undervoltage relay on the system auxiliary transformer (SAT) side of the main feed breaker to the 4.16 kV bus (with no time delay) arranged in a two-out-of-two logic. The trip setting of the SAT undervoltage relay is maintained such that it trips prior to the bus undervoltage relay. Either trip system will open (trip) the main feed breaker to the bus.

A loss of voltage signal or degraded voltage signal results in the start of the associated DG, the trip of the normal and alternate offsite power supply breakers to the associated 4.16 kV emergency bus, and (for Divisions 1 and 2 only) the shedding of the appropriate 4.16 kV bus loads.

APPLICABLE
SAFETY ANALYSES,
LCO, and
APPLICABILITY

The LOP instrumentation is required for the Engineered Safety Features to function in any accident with a loss of offsite power. The required channels of LOP instrumentation ensure that the ECCS and other assumed systems powered from the DGs provide plant protection in the event of any of the analyzed accidents in References 2, 3, and 4 in which a loss of offsite power is assumed. The initiation of the DGs on loss of offsite power, and subsequent initiation of the ECCS, ensure that the fuel peak cladding temperature remains below the limits of 10 CFR 50.46.

Accident analyses credit the loading of at least two of the DGs based on the loss of offsite power coincident with a loss of coolant accident (LOCA). The diesel starting and loading times have been included in the delay time associated with each safety system component requiring DG supplied power following a loss of offsite power.

The LOP instrumentation satisfies Criterion 3 of 10 CFR 50.36(c)(2)(ii).

The OPERABILITY of the LOP instrumentation is dependent upon the OPERABILITY of the individual instrumentation channel Functions specified in Table 3.3.8.1-1. Each Function must have a required number of OPERABLE channels per 4.16 kV emergency bus, with their setpoints within the specified Allowable Values. The actual setpoint is calibrated consistent with applicable setpoint methodology assumptions.

(continued)

BASES

APPLICABLE
SAFETY ANALYSES,
LCO, and
APPLICABILITY
(continued)

The Allowable Values are specified for each Function in the Table. Nominal trip setpoints are specified in the setpoint calculations. The nominal setpoints are selected to ensure that the setpoint does not exceed the Allowable Value between CHANNEL CALIBRATIONS. Operation with a trip setpoint less conservative than the nominal trip setpoint, but within the Allowable Value, is acceptable. A channel is inoperable if its actual trip setpoint is not within its required Allowable Value. Trip setpoints are those predetermined values of output at which an action should take place. The setpoints are compared to the actual process parameter (e.g., degraded voltage), and when the measured output value of the process parameter exceeds the setpoint, the associated device (e.g., trip unit) changes state. The analytic limits are derived from the limiting values of the process parameters obtained from the safety analysis. The trip setpoints are determined from the analytic limits, corrected for defined process, calibration, and instrument errors. The Allowable Values are then determined, based on the trip setpoint values, by accounting for the calibration based errors. These calibration based errors are limited to reference accuracy, instrument drift, errors associated with measurement and test equipment, and calibration tolerance of loop components. The trip setpoints and Allowable Values determined in this manner provide adequate protection because instrument uncertainties, process effects, calibration tolerances, instrument drift, and severe environment errors (for channels that must function in harsh environments as defined by 10 CFR 50.49) are accounted for and appropriately applied for the instrumentation.

The specific Applicable Safety Analyses, LCO, and Applicability discussions are listed below on a Function by Function basis.

4.16 kV Emergency Bus Undervoltage

1.a, 1.b, 2.a, 2.b. 4.16 kV Emergency Bus Undervoltage
(Loss of Voltage)

Loss of voltage on a 4.16 kV emergency bus indicates that offsite power may be completely lost to the respective emergency bus and is unable to supply sufficient power for proper operation of the applicable equipment. Therefore,

(continued)

BASES

APPLICABLE
SAFETY ANALYSES,
LCO, and
APPLICABILITY

4.16 kV Emergency Bus Undervoltage

1.a, 1.b, 2.a, 2.b. 4.16 kV Emergency Bus Undervoltage
(Loss of Voltage) (continued)

the power supply to the bus is transferred from the offsite power supply to DG power. This transfer is initiated when the voltage on the bus drops below the relay settings with a short time delay. The transfer occurs prior to the bus voltage dropping below the minimum Loss of Voltage Function Allowable Value but after the voltage drops below the maximum Loss of Voltage Function Allowable Value (loss of voltage with a short time delay). The short time delay prevents inadvertent relay actuations due to momentary voltage dips. For Divisions 1 and 2, the time delay varies inversely with decreasing voltage. For Division 3, the time delay is a fixed value. The time delay values are bounded by the upper and lower Allowable Values, as applicable. This ensures that adequate power will be available to the required equipment.

The Bus Undervoltage Allowable Values are low enough to prevent inadvertent power supply transfer since they are below the minimum expected voltage during normal and emergency operation, but high enough to ensure power is available to the required equipment. The Time Delay Allowable Values are long enough to provide time for the offsite power supply to recover to normal voltages, but short enough to ensure that power is available to the required equipment.

Two channels of each 4.16 kV Emergency Bus Undervoltage (Loss of Voltage) Function per associated emergency bus are required to be OPERABLE when the associated DG is required to be OPERABLE to ensure that no single instrument failure can preclude the DG function. For the Division 1 and 2 4.16 kV emergency buses, the Loss of Voltage Functions are 1) 4.16 kV Basis and 2) Time Delay. For the Division 3 4.16 kV emergency bus, the Loss of Voltage Functions are: 1) 4.16 kV Basis and 2) Time Delay. Refer to LCO 3.8.1, "AC Sources - Operating," and LCO 3.8.2, "AC Sources - Shutdown," for Applicability Bases for the DGs.

(continued)

BASES

APPLICABLE SAFETY ANALYSES, LCO, and APPLICABILITY (continued) 1.c, 1.d, 1.e, 2.c, 2.d, 2.e. 4.16 kV Emergency Bus Undervoltage (Degraded Voltage)

A reduced voltage condition on a 4.16 kV emergency bus indicates that while offsite power may not be completely lost to the respective emergency bus, power may be insufficient for starting large motors without risking damage to the motors that could disable the ECCS function. Therefore, power supply to the bus is transferred from offsite power to onsite DG power when the voltage on the bus drops below the Degraded Voltage Function Allowable Values (degraded voltage with a time delay). This ensures that adequate power will be available to the required equipment.

The Bus Undervoltage Allowable Values are low enough to prevent inadvertent power supply transfer, but high enough to ensure that sufficient power is available to the required equipment. The Time Delay Allowable Values are long enough to provide time for the offsite power supply to recover to normal voltages, but short enough to ensure that sufficient power is available to the required equipment.

Two channels of each 4.16 kV Emergency Bus Undervoltage (Degraded Voltage) Function per associated emergency bus are required to be OPERABLE when the associated DG is required to be OPERABLE to ensure that no single instrument failure can preclude the DG function. The Degraded Voltage Functions are: 1) 4.16 kV Basis; 2) Time Delay, No LOCA; and 3) Time Delay, LOCA. Refer to LCO 3.8.1 and LCO 3.8.2 for Applicability Bases for the DGs.

ACTIONS A Note has been provided to modify the ACTIONS related to LOP instrumentation channels. Section 1.3, Completion Times, specifies that once a Condition has been entered, subsequent divisions, subsystems, components, or variables expressed in the Condition discovered to be inoperable or not within limits will not result in separate entry into the Condition. Section 1.3 also specifies that Required Actions of the Condition continue to apply for each additional failure, with Completion Times based on initial entry into the Condition. However, the Required Actions for inoperable LOP instrumentation channels provide appropriate

(continued)

BASES

ACTIONS
(continued)

compensatory measures for separate inoperable channels. As such, a Note has been provided that allows separate Condition entry for each inoperable LOP instrumentation channel.

A.1

With one or more channels of a Function inoperable, the Function may not be capable of performing the intended function. Therefore, only 1 hour is allowed to restore the inoperable channel to OPERABLE status. If the inoperable channel cannot be restored to OPERABLE status within the allowable out of service time, the channel must be placed in the tripped condition per Required Action A.1. Placing the inoperable channel in trip would conservatively compensate for the inoperability, restore capability to accommodate a single failure, and allow operation to continue. Alternately, if it is not desired to place the channel in trip (e.g., as in the case where placing the channel in trip would result in a DG initiation), Condition B must be entered and its Required Action taken.

The Completion Time is intended to allow the operator time to evaluate and repair any discovered inoperabilities. The 1 hour Completion Time is acceptable because it minimizes risk while allowing time for restoration or tripping of channels.

B.1

If any Required Action and associated Completion Time is not met, the associated Function may not be capable of performing the intended function. Therefore, the associated DG(s) are declared inoperable immediately. This requires entry into applicable Conditions and Required Actions of LCO 3.8.1 and LCO 3.8.2, which provide appropriate actions for the inoperable DG(s).

SURVEILLANCE
REQUIREMENTS

As noted at the beginning of the SRs, the SRs for each LOP Instrumentation Function are located in the SRs column of Table 3.3.8.1-1.

(continued)

BASES

SURVEILLANCE
REQUIREMENTS
(continued)

The Surveillances are modified by a Note to indicate that when a channel is placed in an inoperable status solely for performance of required Surveillances, entry into associated Conditions and Required Actions may be delayed for up to 2 hours provided the associated Function maintains LOP initiation capability. LOP initiation capability is maintained provided the associated Function can perform the load shed and control scheme for two of the three 4.16 kV emergency buses. Upon completion of the Surveillance, or expiration of the 2 hour allowance, the channel must be returned to OPERABLE status or the applicable Condition entered and Required Actions taken.

SR 3.3.8.1.1 and SR 3.3.8.1.3

A CHANNEL FUNCTIONAL TEST is performed on each required channel to ensure that the channel will perform the intended function. A successful test of the required contact(s) of a channel relay may be performed by the verification of the change of state of a single contact of the relay. This clarifies what is an acceptable CHANNEL FUNCTIONAL TEST of a relay. This is acceptable because all of the other required contacts of the relay are verified by other Technical Specifications and non-Technical Specifications tests at least once per refueling interval with applicable extensions. Any setpoint adjustment shall be consistent with the assumptions of the current plant specific setpoint methodology.

The Frequencies of 18 months and 24 months are based on plant operating experience with regard to channel OPERABILITY and drift that demonstrates that failure of more than one channel of a given Function in any 18 month or 24 month interval, as applicable, is rare.

SR 3.3.8.1.2 and SR 3.3.8.1.4

A CHANNEL CALIBRATION is a complete check of the instrument loop and the sensor. This test verifies the channel responds to the measured parameter within the necessary

(continued)

BASES

SURVEILLANCE
REQUIREMENTS

SR 3.3.8.1.2 and SR 3.3.8.1.4 (continued)

range and accuracy. CHANNEL CALIBRATION leaves the channel adjusted to account for instrument drifts between successive calibrations consistent with the plant specific setpoint methodology.

The Frequency is based on the assumption of an 18 month or 24 month calibration interval, as applicable, in the determination of the magnitude of equipment drift in the setpoint analysis.

SR 3.3.8.1.5

The LOGIC SYSTEM FUNCTIONAL TEST demonstrates the OPERABILITY of the required actuation logic for a specific channel. The system functional testing performed in LCO 3.8.1 and LCO 3.8.2 overlaps this Surveillance to provide complete testing of the assumed safety functions. The 24 month Frequency is based on the need to perform this Surveillance under the conditions that apply during a plant outage and the potential for an unplanned transient if the Surveillance were performed with the reactor at power. Operating experience has shown these components usually pass the Surveillance when performed at the 24 month Frequency.

REFERENCES

1. UFSAR, Section 8.2.3.3.
 2. UFSAR, Section 5.2.
 3. UFSAR, Section 6.3.
 4. UFSAR, Chapter 15.
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B 3.3 INSTRUMENTATION

B 3.3.8.2 Reactor Protection System (RPS) Electric Power Monitoring

BASES

BACKGROUND

The RPS Electric Power Monitoring System is provided to isolate the RPS bus from the motor generator (MG) set or the alternate power supply in the event of overvoltage, undervoltage, or underfrequency. This system protects the loads connected to the RPS bus against unacceptable voltage and frequency conditions (Ref. 1) and forms an important part of the primary success path for the essential safety circuits. Some of the essential equipment powered from the RPS buses includes the RPS logic, scram solenoids, and various valve isolation logic.

The RPS Electric Power Monitoring assembly will detect any abnormal high or low voltage or low frequency condition in the outputs of the two MG sets or the alternate power supply and will de-energize its respective RPS bus, thereby causing all safety functions normally powered by this bus to de-energize.

In the event of failure of an RPS Electric Power Monitoring System (e.g., both inseries electric power monitoring assemblies), the RPS loads may experience significant effects from the unregulated power supply. Deviation from the nominal conditions can potentially cause damage to the scram and MSIV trip solenoids and other Class 1E devices.

In the event of a low voltage condition, for an extended period of time, the scram and MSIV trip solenoids can chatter and potentially lose their pneumatic control capability, resulting in a loss of primary scram and MSIV closure action.

In the event of an overvoltage condition, the RPS and isolation logic relays and scram solenoids, as well as the main steam isolation valve trip solenoids, may experience a voltage higher than their design voltage. If the overvoltage condition persists for an extended time period, it may cause equipment degradation and the loss of plant safety function.

(continued)

BASES

BACKGROUND
(continued)

Two redundant Class 1E circuit breakers are connected in series between each RPS bus and its MG set, and between each RPS bus and the alternate power supply. Each of these circuit breakers has an associated independent set of Class 1E overvoltage, undervoltage, and underfrequency sensing logic. Together, a circuit breaker and its sensing logic constitute an electric power monitoring assembly. If the output of the inservice MG set or alternate power supply exceeds the predetermined limits of overvoltage, undervoltage, or underfrequency, a trip coil driven by this logic circuitry opens the circuit breaker, which removes the associated power supply from service.

APPLICABLE
SAFETY ANALYSES

RPS Electric Power Monitoring is necessary to meet the assumptions of the safety analyses by ensuring that the equipment powered from the RPS buses can perform its intended function. RPS Electric Power Monitoring provides protection to the RPS and other systems that receive power from the RPS buses, by disconnecting the RPS bus from the power supply under specified conditions that could damage the RPS bus powered equipment.

RPS Electric Power Monitoring satisfies Criterion 3 of 10 CFR 50.36(c)(2)(ii).

LCO

The OPERABILITY of each RPS electric power monitoring assembly is dependent upon the OPERABILITY of the overvoltage, undervoltage, and underfrequency logic, as well as the OPERABILITY of the associated circuit breaker. Two electric power monitoring assemblies are required to be OPERABLE for each inservice power supply. This provides redundant protection against any abnormal voltage or frequency conditions to ensure that no single RPS electric power monitoring assembly failure can preclude the function of RPS bus powered components. Each of the inservice electric power monitoring assembly trip logic setpoints is required to be within the specific Allowable Value. The actual setpoint is calibrated consistent with applicable setpoint methodology assumptions.

(continued)

BASES

LCO
(continued)

Allowable Values are specified for each RPS electric power monitoring assembly trip logic (refer to SR 3.3.8.2.2). Nominal trip setpoints are specified in the setpoint calculations. The nominal setpoints are selected to ensure that the setpoints do not exceed the Allowable Value between CHANNEL CALIBRATIONS. Operation with a trip setpoint less conservative than the nominal trip setpoint, but within its Allowable Value, is acceptable. A channel is inoperable if its actual trip setpoint is not within its required Allowable Value. Trip setpoints are those predetermined values of output at which an action should take place. The setpoints are compared to the actual process parameter (e.g., overvoltage), and when the measured output value of the process parameter exceeds the setpoint, the associated device (e.g., trip coil) changes state. The analytic limits are derived from the limiting values of the process parameters obtained from the safety analysis. The trip setpoints are determined from the analytic limits, corrected for defined process, calibration, and instrument errors. The Allowable Values are then determined, based on the trip setpoint values, by accounting for the calibration based errors. These calibration based errors are limited to reference accuracy, instrument drift, errors associated with measurement and test equipment, and calibration tolerance of loop components. The trip setpoints and Allowable Values determined in this manner provide adequate protection because instrument uncertainties, process effects, calibration tolerances, instrument drift, and severe environment errors (for channels that must function in harsh environments as defined by 10 CFR 50.49) are accounted for and appropriately applied for the instrumentation.

The Allowable Values for the instrument settings are based on the RPS providing ≥ 57 Hz and $120\text{ V} \pm 10\%$. The most limiting voltage requirement and associated line losses determine the settings of the electric power monitoring instrument channels. The settings are calculated based on the loads on the buses and RPS MG set or alternate power supply being 120 VAC and 60 Hz.

(continued)

BASES (continued)

APPLICABILITY The operation of the RPS electric power monitoring assemblies is essential to disconnect the RPS bus powered components from the inservice MG set or alternate power supply during abnormal voltage or frequency conditions. Since the degradation of a nonclass 1E source supplying power to the RPS bus can occur as a result of any random single failure, the OPERABILITY of the RPS electric power monitoring assemblies is required when the RPS bus powered components are required to be OPERABLE. This results in the RPS Electric Power Monitoring System OPERABILITY being required in MODES 1, 2, and 3, MODES 4 and 5, with residual heat removal (RHR) shutdown cooling isolation valves open, MODE 5 with any control rod withdrawn from a core cell containing one or more fuel assemblies, during movement of irradiated fuel assemblies in the secondary containment, during CORE ALTERATIONS, and during operations with a potential for draining the reactor vessel (OPDRVs).

ACTIONS

A.1

If one RPS electric power monitoring assembly for an inservice power supply (MG set or alternate) is inoperable, or one RPS electric power monitoring assembly on each inservice power supply is inoperable, the OPERABLE assembly will still provide protection to the RPS bus powered components under degraded voltage or frequency conditions. However, the reliability and redundancy of the RPS Electric Power Monitoring System are reduced and only a limited time (72 hours) is allowed to restore the inoperable assembly(s) to OPERABLE status. If the inoperable assembly(s) cannot be restored to OPERABLE status, the associated power supply must be removed from service (Required Action A.1). This places the RPS bus in a safe condition. An alternate power supply with OPERABLE power monitoring assemblies may then be used to power the RPS bus.

The 72 hour Completion Time takes into account the remaining OPERABLE electric power monitoring assembly and the low probability of an event requiring RPS Electric Power Monitoring protection occurring during this period. It allows time for plant operations personnel to take corrective actions or to place the plant in the required condition in an orderly manner and without challenging plant systems.

(continued)

BASES

ACTIONS

A.1 (continued)

Alternatively, if it is not desired to remove the power supply(s) from service (e.g., as in the case where removing the power supply(s) from service would result in a scram or isolation), Condition C, D, E, or F as applicable, must be entered and its Required Actions taken.

B.1

If both power monitoring assemblies for an inservice power supply (MG set or alternate) are inoperable, or both power monitoring assemblies in each inservice power supply are inoperable, the system protective function is lost. In this condition, 1 hour is allowed to restore one assembly to OPERABLE status for each inservice power supply. If one inoperable assembly for each inservice power supply cannot be restored to OPERABLE status, the associated power supplies must be removed from service within 1 hour (Required Action B.1). An alternate power supply with OPERABLE assemblies may then be used to power one RPS bus. The 1 hour Completion Time is sufficient for the plant operations personnel to take corrective actions and is acceptable because it minimizes risk while allowing time for restoration or removal from service of the electric power monitoring assemblies.

Alternately, if it is not desired to remove the power supply(s) from service (e.g., as in the case where removing the power supply(s) from service would result in a scram or isolation), Condition C, D, E, or F as applicable, must be entered and its Required Actions taken.

C.1 and C.2

If any Required Action and associated Completion Time of Condition A or B are not met in MODE 1, 2, or 3, a plant shutdown must be performed. This places the plant in a condition where minimal equipment, powered through the inoperable RPS electric power monitoring assembly(s), is required and ensures that the safety function of the RPS bus loads (e.g., scram of control rods) is not required. The

(continued)

BASES

ACTIONS

C.1 and C.2 (continued)

plant shutdown is accomplished by placing the plant in MODE 3 within 12 hours and in MODE 4 within 36 hours. The allowed Completion Times are reasonable, based on operating experience, to reach the required plant conditions from full power conditions in an orderly manner and without challenging plant systems.

D.1 and D.2

If any Required Action and associated Completion Time of Condition A or B are not met in MODE 4 or 5 with RHR SDC isolation valves open, action must be immediately initiated to either restore one electric power monitoring assembly to OPERABLE status for the inservice power source supplying the required instrumentation powered from the RPS bus (Required Action D.1) or to isolate the RHR SDC System (Required Action D.2). Required Action D.1 is provided because the RHR SDC System may be needed to provide core cooling. All actions must continue until the applicable Required Actions are completed.

E.1

If any Required Action and associated Completion Time of Condition A or B are not met in MODE 5 with any control rod withdrawn from a core cell containing one or more fuel assemblies, the operator must immediately initiate action to fully insert all insertable control rods in core cells containing one or more fuel assemblies (Required Action E.1). This Required Action results in the least reactive condition for the reactor core and ensures that the safety function of the RPS (e.g., scram of control rods) is not required.

F.1.1, F.1.2, F.2.1, and F.2.2

If any Required Action and associated Completion Time of Condition A or B are not met during movement of irradiated fuel assemblies in the secondary containment, during CORE ALTERATIONS, or during OPDRVs, the ability to isolate the

(continued)

BASES

ACTIONS

F.1.1, F.1.2, F.2.1, and F.2.2 (continued)

secondary containment and start the Standby Gas Treatment (SGT) System cannot be ensured. Therefore, actions must be immediately performed to ensure the ability to maintain the secondary containment and SGT System functions. Isolating the affected penetration flow path(s) and starting the associated SGT subsystem(s) (Required Actions F.1.1 and F.2.1) performs the intended function of the instrumentation the RPS electric power monitoring assemblies is protecting, and allows operations to continue.

Alternatively, immediately declaring the associated secondary containment isolation valve(s) or SGT subsystem(s) inoperable (Required Action F.1.2 and F.2.2) is also acceptable since the Required Actions of the respective LCOs (LCO 3.6.4.2 and LCO 3.6.4.3) provide appropriate actions for the inoperable components.

SURVEILLANCE
REQUIREMENTS

SR 3.3.8.2.1

A CHANNEL FUNCTIONAL TEST is performed on each overvoltage, undervoltage, and underfrequency channel to ensure that the channel will perform the intended function. A successful test of the required contact(s) of a channel relay may be performed by the verification of the change of state of a single contact of the relay. This clarifies what is an acceptable CHANNEL FUNCTIONAL TEST of a relay. This is acceptable because all of the other required contacts of the relay are verified by other Technical Specifications and non-Technical Specifications tests at least once per refueling interval with applicable extensions. Any setpoint adjustment shall be consistent with the assumptions of the current plant specific setpoint methodology.

As noted in the Surveillance, the CHANNEL FUNCTIONAL TEST is only required to be performed while the plant is in a condition in which the loss of the RPS bus will not jeopardize steady state power operation (the design of the system is such that the power source must be removed from service to conduct the Surveillance). The 24 hours is intended to indicate an outage of sufficient duration to

(continued)

BASES

SURVEILLANCE
REQUIREMENTS

SR 3.3.8.2.1 (continued)

allow for scheduling and proper performance of the Surveillance. The 184 day Frequency and the Note in the Surveillance are based on guidance provided in Generic Letter 91-09 (Ref. 2).

SR 3.3.8.2.2

CHANNEL CALIBRATION is a complete check of the instrument loop and the sensor. This test verifies that the channel responds to the measured parameter within the necessary range and accuracy. CHANNEL CALIBRATION leaves the channel adjusted to account for instrument drifts between successive calibrations consistent with the plant specific setpoint methodology.

The Frequency is based upon the assumption of an 24 month calibration interval in the determination of the magnitude of equipment drift in the setpoint analysis.

SR 3.3.8.2.3

Performance of a system functional test demonstrates that, with a required system actuation (simulated or actual) signal, the logic of the system will automatically trip open the associated power monitoring assembly circuit breaker. The system functional test shall include actuation of the protective relays, tripping logic, and output circuit breakers. Only one signal per power monitoring assembly is required to be tested. This Surveillance overlaps with the CHANNEL CALIBRATION to provide complete testing of the safety function. The system functional test of the Class 1E circuit breakers is included as part of this test to provide complete testing of the safety function. If the breakers are incapable of operating, the associated electric power monitoring assembly would be inoperable.

The 24 month Frequency is based on the need to perform this Surveillance under the conditions that apply during a plant outage and the potential for an unplanned transient if the

(continued)

BASES

SURVEILLANCE
REQUIREMENTS

SR 3.3.8.2.3 (continued)

Surveillance were performed with the reactor at power. Operating experience has shown that these components usually pass the Surveillance when performed at the 24 month Frequency.

REFERENCES

1. UFSAR, Section 8.3.1.1.3.
 2. NRC Generic Letter 91-09, "Modification of Surveillance Interval for the Electric Protective Assemblies in Power Supplies for the Reactor Protection System."
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B 3.4 REACTOR COOLANT SYSTEM (RCS)

B 3.4.1 Recirculation Loops Operating

BASES

BACKGROUND

The Reactor Recirculation System is designed to provide a forced coolant flow through the core to remove heat from the fuel. The forced coolant flow removes heat at a faster rate from the fuel than would be possible with just natural circulation. The forced flow, therefore, allows operation at significantly higher power than would otherwise be possible. The recirculation system also controls reactivity over a wide span of reactor power by varying the recirculation flow rate to control the void content of the moderator. The Reactor Recirculation System consists of two recirculation pump loops external to the reactor vessel. These loops provide the piping path for the driving flow of water to the reactor vessel jet pumps. Each external loop contains a two speed motor driven recirculation pump, a flow control valve, associated piping, jet pumps, valves, and instrumentation. The recirculation loops are part of the reactor coolant pressure boundary and are located inside the drywell structure. The jet pumps are reactor vessel internals.

The recirculated coolant consists of saturated water from the steam separators and dryers that has been subcooled by incoming feedwater. This water passes down the annulus between the reactor vessel wall and the core shroud. A portion of the coolant flows from the vessel, through the two external recirculation loops, and becomes the driving flow for the jet pumps. Each of the two external recirculation loops discharges high pressure flow into an external manifold, from which individual recirculation inlet lines are routed to the jet pump risers within the reactor vessel. The remaining portion of the coolant mixture in the annulus becomes the suction flow for the jet pumps. This flow enters the jet pump at suction inlets and is accelerated by the driving flow. The drive flow and suction flow are mixed in the jet pump throat section and result in partial pressure recovery. The total flow then passes through the jet pump diffuser section into the area below the core (lower plenum), gaining sufficient head in the process to drive the required flow upward through the core.

(continued)

BASES

BACKGROUND
(continued)

The subcooled water enters the bottom of the fuel channels and contacts the fuel cladding, where heat is transferred to the coolant. As it rises, the coolant begins to boil, creating steam voids within the fuel channel that continue until the coolant exits the core. Because of reduced moderation, the steam voiding introduces negative reactivity that must be compensated for to maintain or to increase reactor power. The recirculation flow control allows operators to increase recirculation flow and sweep some of the voids from the fuel channel, overcoming the negative reactivity void effect. Thus, the reason for having variable recirculation flow is to compensate for reactivity effects of boiling over a wide range of power generation (i.e., approximately 65 to 100% RTP) without having to move control rods and disturb desirable flux patterns. In addition, the combination of core flow and THERMAL POWER is normally maintained such that core thermal-hydraulic oscillations do not occur. These oscillations can occur during two recirculation loop operation, single recirculation loop, and no recirculation loop operation. Plant procedures include requirements of this LCO as well as other vendor and NRC recommended requirements and actions to minimize the potential of core thermal-hydraulic oscillations.

Each recirculation loop is manually started from the control room. The recirculation flow control valves provide regulation of individual recirculation loop drive flows. The flow in each loop can be manually or automatically controlled.

APPLICABLE
SAFETY ANALYSES

The operation of the Reactor Recirculation System is an initial condition assumed in the design basis loss of coolant accident (LOCA) (Ref. 1). During a LOCA caused by a recirculation loop pipe break, the intact loop is assumed to provide coolant flow during the first few seconds of the accident. The initial core flow decrease is rapid because the recirculation pump in the broken loop ceases to pump reactor coolant to the vessel almost immediately. The pump in the intact loop coasts down relatively slowly. This pump coastdown governs the core flow response for the next several seconds until the jet pump suction is uncovered (Ref. 2). The analyses assume that both loops are operating at the same flow prior to the accident. However, the LOCA

(continued)

BASES

APPLICABLE
SAFETY ANALYSES
(continued)

analysis was reviewed for the case with a flow mismatch between the two loops, with the pipe break assumed to be in the loop with the higher flow. While the flow coastdown and core response are potentially more severe in this assumed case (since the intact loop starts at a lower flow rate and the core response is the same as if both loops were operating at a lower flow rate), a small mismatch has been determined to be acceptable based on engineering judgement.

The recirculation system is also assumed to have sufficient flow coastdown characteristics to maintain fuel thermal margins during abnormal operational transients (Ref. 2), which are analyzed in Chapter 15 of the UFSAR.

A plant specific LOCA analysis has been performed assuming only one operating recirculation loop. This analysis has demonstrated that, in the event of a LOCA caused by a pipe break in the operating recirculation loop, the Emergency Core Cooling System response will provide adequate core cooling, provided the APLHGR requirements are modified accordingly (Ref. 3).

The transient analyses in Chapter 15 of the UFSAR have also been performed for single recirculation loop operation (Ref. 3) and demonstrate sufficient flow coastdown characteristics to maintain fuel thermal margins during the abnormal operational transients analyzed provided the MCPR requirements are modified. During single recirculation loop operation, modification to the Reactor Protection System average power range monitor (APRM) and the Rod Block Monitor (RBM) Allowable Values is also required to account for the different relationships between recirculation drive flow and reactor core flow. The APLHGR and MCPR limits for single loop operation are specified in the COLR. The APRM Flow Biased Simulated Thermal Power-Upscale Allowable Value is in LCO 3.3.1.1, "Reactor Protection System (RPS) Instrumentation." The Rod Block Monitor-Upscale Allowable Value is specified in the COLR. Safety analyses performed in References 1, 2, and 3 implicitly assume core conditions are stable. However, during operation at the high power/low flow region of the operating domain, a small probability of limit cycle neutron flux oscillations exists depending on combinations of operating conditions (e.g., power shape, bundle power, and bundle flow).

(continued)

BASES

APPLICABLE
SAFETY ANALYSES
(continued)

General Electric (GE) Service Information Letter (SIL) No. 380 (Ref. 4) addressed boiling instability and made several recommendations. In this SIL, the power/flow operating map was divided into several regions of varying concern. It also discussed the objectives and philosophy of "detect and suppress."

NRC Generic Letter 86-02 (Ref. 5) discussed both the GE and Siemens stability methodology and stated that due to uncertainties, 10 CFR 50, Appendix A, General Design Criteria (GDC) 10 and 12 could not be met using available analytical procedures on a BWR. The Generic Letter discussed SIL 380 and stated that GDC 10 and 12 could be met by imposing SIL 380 recommendations in operating regions of potential instability. The NRC concluded that regions of potential instability constituted decay ratios of 0.8 and greater by the GE methodology and 0.75 by the Siemens methodology. Figure 3.4.1-1 was generated as an interim solution to provide an increased margin of safety until the investigation is completed (Ref. 6)

Recirculation loops operating satisfies Criterion 2 of 10 CFR 50.36(c)(2)(ii).

LCO

Two recirculation loops are normally required to be in operation with their flows matched within the limits specified in SR 3.4.1.1 to ensure that during a LOCA caused by a break of the piping of one recirculation loop the assumptions of the LOCA analysis are satisfied. With the limits specified in SR 3.4.1.1 not met, the recirculation loop with the lower flow must be considered not in operation. With only one recirculation loop in operation, modifications to the required APLHGR limits (LCO 3.2.1, "AVERAGE PLANAR LINEAR HEAT GENERATION RATE (APLHGR)"), MCPR limits (LCO 3.2.2, "MINIMUM CRITICAL POWER RATIO (MCPR)"), APRM Flow Biased Simulated Thermal Power—Upscale Allowable Value (LCO 3.3.1.1), and the Rod Block Monitor—Upscale Allowable Value (LCO 3.3.2.1) must be applied to allow continued operation consistent with the assumptions of Reference 3. In addition, during two-loop and single-loop

(continued)

BASES

LCO
(continued) operation, the combination of core flow and THERMAL POWER must be in Region III of Figure 3.4.1-1 to ensure core thermal-hydraulic oscillations do not occur.

APPLICABILITY In MODES 1 and 2, requirements for operation of the Reactor Recirculation System are necessary since there is considerable energy in the reactor core and the limiting design basis transients and accidents are assumed to occur.

In MODES 3, 4, and 5, the consequences of an accident are reduced and the coastdown characteristics of the recirculation loops are not important.

ACTIONS A.1, A.2, and A.3

With one or two recirculation loops in operation in Region II of Figure 3.4.1-1, the plant is operating in a region where the potential for thermal-hydraulic oscillations exists. To ensure oscillations are not occurring, APRM and LPRM neutron flux noise levels must be verified to be less than or equal to the larger of either 3 times the baseline noise levels or 10% peak-to-peak (Required Action A.1 and A.2) when Region II is entered. For the LPRM neutron flux noise verification, detector levels A and C of one LPRM string per core octant plus detector levels A and C of one LPRM string in the center region of the core should be monitored. Prompt action to monitor APRM and LPRM neutron flux noise levels should be taken to ensure oscillations are not occurring.

The 45 minute Completion Time of Required Actions A.1 and A.2 provides a reasonable time to stabilize operation in Region II and verify the neutron flux noise levels are within limits. A verification of the APRM and LPRM neutron flux noise levels once per 12 hours following the initial verification provides frequent periodic information of neutron flux noise levels to verify stable steady state operation. Also, a verification of neutron flux noise levels after any THERMAL POWER increase of $\geq 5\%$ RTP while in Region II provides indication of operational stability following a potential for change of the thermal-hydraulic properties of the system.

(continued)

BASES

ACTIONS

A.1, A.2, and A.3 (continued)

In addition, a verification that one or both recirculation loops are not operating within Region I of Figure 3.4.1-1 (Required Action A.3) is required to be performed once per 12 hours. The Completion Time of once per 12 hours is reasonable based on operating experience and the operator's knowledge of reactor status, including changes in reactor power and core flow.

B.1

If evidence of approaching reactor instability occurs (i.e., APRM or LPRM neutron flux noise levels exceed the associated limit of Required Actions A.1 or A.2, as applicable) while operating in Region II of Figure 3.4.1-1, prompt action should be taken to restore the APRM or LPRM neutron flux noise levels to within the associated limit or exit Region II of Figure 3.4.1-1. This may be accomplished by either increasing core flow by recirculation loop flow control valve manipulation or reduction of THERMAL POWER by control rod insertion. The 2 hour Completion Time is reasonable to restore plant parameters in an orderly manner and without challenging plant systems.

C.1

With one or both recirculation loops in operation in Region I of Figure 3.4.1-1, the plant is operating in a region where the potential for thermal-hydraulic oscillations is increased and sufficient margin may not be available for operator response to suppress potential thermal-hydraulic oscillations. As a result, prompt action should be taken to exit Region I of Figure 3.4.1-1. This may be accomplished by either increasing core flow by recirculation loop flow control valve manipulation or reduction of THERMAL POWER by control rod insertion. The 2 hour Completion Time is reasonable to restore plant parameters in an orderly manner and without challenging plant systems.

(continued)

BASES

ACTIONS
(continued)

D.1, D.2, and D.3

With no recirculation loops in service, the probability of thermal-hydraulic oscillations is greatly increased. Therefore, prompt action should be taken to ensure oscillations are not occurring by verifying APRM and LPRM neutron flux noise levels are $\leq 10\%$ peak-to-peak. If neutron flux noise levels are discovered to be $> 10\%$ peak-to-peak at anytime while in this Condition, Condition E must be immediately entered.

Also, prompt action should be taken to reduce THERMAL POWER low enough to avoid the region of potential instability in natural circulation (i.e., reduce THERMAL POWER below 36% RTP). The 2 hour Completion Time provides a reasonable time to restore operation to Region III of Figure 3.4.1-1.

In addition, with no recirculation loops in operation, plant operation is not allowed to continue in MODE 1 or 2. Therefore, the unit is required to be brought to a MODE in which the LCO does not apply. The allowed Completion Time of 12 hours is reasonable, based on operating experience, to reach MODE 3 in an orderly manner and without challenging plant systems.

E.1

In the event no recirculation loops are in operation and evidence is indicated of approaching reactor instability (i.e., APRM or LPRM neutron flux noise levels exceed the associated limit) or APRM or LPRM neutron flux noise levels cannot be restored within 2 hours while in Region II of Figure 3.4.1-1, action must be immediately initiated to eliminate the potential for a thermal-hydraulic instability event. As such, the reactor mode switch must be immediately placed in the shutdown position.

(continued)

BASES

ACTIONS
(continued)

F.1 and G.1

With both recirculation loops operating but the flows not matched, the flows must be matched within 2 hours. If matched flows are not restored, the recirculation loop with lower flow must be declared "not in operation," as required by Required Action F.1. This Required Action does not require tripping the recirculation pump in the lowest flow loop when the mismatch between total jet pump flows of the two loops is greater than the required limits. However, in cases where large flow mismatches occur, low flow or reverse flow can occur in the low flow loop jet pumps, causing vibration of the jet pumps. If zero or reverse flow is detected, the condition should be alleviated by changing flow control valve position to re-establish forward flow or by tripping the pump.

With the requirements of the LCO not met for reasons other than Conditions A, C, D, and F (e.g., one loop is "not in operation"), compliance with the LCO must be restored within 24 hours. A recirculation loop is considered not in operation when the pump in that loop is idle or when the mismatch between total jet pump flows of the two loops is greater than required limits for greater than 2 hours (i.e., Required Action F.1 has been taken). Should a LOCA occur with one recirculation loop not in operation, the core flow coastdown and resultant core response may not be bounded by the LOCA analyses. Therefore, only a limited time is allowed to restore the inoperable loop to operating status.

Alternatively, if the single loop requirements of the LCO are applied to the APLHGR and MCPR operating limits and RPS and RBM Allowable Values, operation with only one recirculation loop would satisfy the requirements of the LCO and the initial conditions of the accident sequence.

The 2 hour and 24 hour Completion Times are based on the low probability of an accident occurring during this time period, on a reasonable time to complete the Required Action, and on frequent core monitoring by operators allowing abrupt changes in core flow conditions to be quickly detected.

(continued)

BASES

ACTIONS
(continued)

H.1

If the Required Action and associated Completion Time of Condition G is not met, the unit is required to be brought to a MODE in which the LCO does not apply. To achieve this status, the plant must be brought to MODE 3 within 12 hours. In this condition, the recirculation loops are not required to be operating because of the reduced severity of DBAs and minimal dependence on the recirculation loop coastdown characteristics. The allowed Completion Time of 12 hours is reasonable, based on operating experience, to reach MODE 3 from full power conditions in an orderly manner and without challenging plant systems.

SURVEILLANCE
REQUIREMENTS

SR 3.4.1.1

This SR ensures the recirculation loop flows are within the allowable limits for mismatch. At low core flow (i.e., < 70% of rated core flow), the APLHGR and MCPR requirements provide larger margins to the fuel cladding integrity Safety Limit such that the potential adverse effect of early boiling transition during a LOCA is reduced. A larger flow mismatch can therefore be allowed when core flow is < 70% of rated core flow. The recirculation loop jet pump flow, as used in this Surveillance, is the summation of the flows from all of the jet pumps associated with a single recirculation loop.

The mismatch is measured in terms of percent of rated core flow. If the flow mismatch exceeds the specified limits, the loop with the lower flow is considered not in operation. This SR is not required when both loops are not in operation since the mismatch limits are meaningless during single loop or natural circulation operation. The Surveillance must be performed within 24 hours after both loops are in operation. The 24 hour Frequency is consistent with the Frequency for jet pump OPERABILITY verification and has been shown by operating experience to be adequate to detect off normal jet pump loop flows in a timely manner.

(continued)

BASES

SURVEILLANCE
REQUIREMENTS

(continued)

SR 3.4.1.2

The SR ensures the combination of core flow and THERMAL POWER are within the appropriate limits to prevent inadvertent entry into a region of potential thermal-hydraulic instability. At low recirculation loop flow and high reactor power, the reactor exhibits increased susceptibility to thermal-hydraulic instability. Figure 3.4.1-1 is based on guidance provided in References 4 and 5. The 24 hour Frequency is based on operating experience and the operator's knowledge of the reactor status, including significant changes in THERMAL POWER and core flow.

REFERENCES

1. UFSAR, Sections 6.3 and 15.6.5.
 2. UFSAR, Appendix G.3.1.2.
 3. UFSAR, Section 6.B.
 4. GE Service Information Letter (SIL) No. 380, "BWR Core Thermal Hydraulic Stability," Revision 1, February 10, 1984.
 5. NRC Generic Letter 86-02, "Technical Resolution of Generic Issue B-19, Thermal Hydraulic Stability," January 22, 1986.
 6. NRC Safety Evaluation supporting Amendment No. 60 to Facility Operating License No. 11 and Amendment No. 40 to Facility Operating License No. 18, Commonwealth Edison Company, LaSalle County Station, Units 1 and 2, dated September 7, 1988.
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B 3.4 REACTOR COOLANT SYSTEM (RCS)

B 3.4.2 Flow Control Valves (FCVs)

BASES

BACKGROUND The Reactor Recirculation System is described in the Background section of the Bases for LCO 3.4.1, "Recirculation Loops Operating," which discusses the operating characteristics of the system and how this affects the design basis transient and accident analyses. The FCVs are part of the Reactor Recirculation System.

The Recirculation Flow Control System consists of the electronic and hydraulic components necessary for the positioning of the two hydraulically actuated FCVs. The recirculation loop flow rate can be rapidly changed within the expected flow range, in response to rapid changes in system demand. Limits on the system response are required to minimize the impact on core flow response during certain accidents and transients. Solid state control logic will generate an FCV "motion inhibit" signal in response to any one of several hydraulic power unit or analog control circuit failure signals. The "motion inhibit" signal causes hydraulic power unit shutdown and hydraulic isolation such that the FCVs fail "as is."

APPLICABLE SAFETY ANALYSES The FCV stroke rate is limited to $\leq 11\%$ per second in the opening and closing directions on a control signal failure of maximum demand. This stroke rate is an assumption of the analysis of the recirculation flow control failures on decreasing and increasing flow (Refs. 1 and 2). During a LOCA caused by a recirculation loop pipe break, the intact loop is assumed to provide coolant flow during the first few seconds of the accident. The initial core flow decrease is rapid because the recirculation pump in the broken loop ceases to pump almost immediately since it has lost suction. The pump in the intact loop coasts down relatively slowly. This pump coastdown governs the core flow response for the next several seconds (Ref. 3), because the FCV is assumed to fail "as is" due to a motion inhibit as a result of a high drywell pressure interlock. In addition, the closure of a recirculation FCV concurrent with a loss of coolant accident (LOCA) was analyzed during

(continued)

BASES

APPLICABLE SAFETY ANALYSES (continued) initial licensing and found to be acceptable for a maximum closure rate of 11% of stroke per second, since this event involves multiple failures.

Flow control valves satisfy Criterion 2 of 10 CFR 50.36(c)(2)(ii).

LCO An FCV in each operating recirculation loop must be OPERABLE to ensure that the assumptions of the design basis transient and accident analyses are satisfied.

APPLICABILITY In MODES 1 and 2, the FCVs are required to be OPERABLE, since during these conditions there is considerable energy in the reactor core, and the limiting design basis transients and accidents are assumed to occur. In MODES 3, 4, and 5, the consequences of a transient or accident are reduced and OPERABILITY of the flow control valves is not important.

ACTIONS A Note has been provided to modify the ACTIONS related to FCVs. Section 1.3, Completion Times, specifies once a Condition has been entered, subsequent divisions, subsystems, components or variables expressed in the Condition, discovered to be inoperable or not within limits, will not result in separate entry into the Condition. Section 1.3 also specifies Required Actions of the Condition continue to apply for each additional failure, with Completion Times based on initial entry into the Condition. However, the Required Actions for inoperable FCVs provide appropriate compensatory measures for separate inoperable FCVs. As such, a Note has been provided that allows separate Condition entry for each inoperable FCV.

A.1

With one or two required FCVs inoperable, the assumptions of the design basis transient and accident analyses may not be met and the inoperable FCV must be returned to OPERABLE status or hydraulically locked within 4 hours.

Opening an FCV faster than the limit could result in a more severe flow runout transient. Closing an FCV faster than

(continued)

BASES

ACTIONS

A.1 (continued)

the limit could result in a more severe coolant flow decrease transient. Both conditions could result in violation of the Safety Limit MCPR. The FCVs are designed to lockup (high drywell pressure interlock) under LOCA conditions. When the FCVs "lock-up", the recirculation flow coastdown is adequate and the resulting calculated clad temperatures are acceptable. In addition, it has been calculated with the FCVs closing at the specified limit, the resulting calculated clad temperatures will also be acceptable. Closing an FCV faster than the limit assumed in the LOCA analysis (Ref. 3) could affect the recirculation flow coastdown, resulting in higher peak clad temperatures. Therefore, if an FCV is inoperable, deactivating the valve will essentially lock the valve in position, which will prohibit the FCV from adversely affecting the DBA and transient analyses. Continued operation is allowed in this Condition.

The 4 hour Completion Time is a reasonable time period to complete the Required Action, while limiting the time of operation with an inoperable FCV.

B.1

If the FCVs are not deactivated ("locked up") within the associated Completion Time, the unit must be brought to a MODE in which the LCO does not apply. To achieve this status, the unit must be brought to at least MODE 3 within 12 hours. This brings the unit to a condition where the flow coastdown characteristics of the recirculation loop are not important. The allowed Completion Time of 12 hours is reasonable, based on operating experience, to reach MODE 3 from full power conditions in an orderly manner and without challenging unit systems.

SURVEILLANCE
REQUIREMENTS

SR 3.4.2.1

Hydraulic power unit pilot operated 4-way valves located between the servo valves and the common "open" and "close" lines are required to close in the event of a loss of hydraulic pressure. When closed, these valves inhibit FCV motion by blocking hydraulic pressure from the servo valve

(continued)

BASES

SURVEILLANCE
REQUIREMENTS

SR 3.4.2.1 (continued)

to the common open and close lines as well as to the alternate subloop. This Surveillance verifies FCV lockup on a loss of hydraulic pressure.

The 24 month Frequency is based on the need to perform this Surveillance under the conditions that apply during a plant outage and the potential for an unplanned transient if the Surveillance were performed with the reactor at power. Operating experience has shown these components usually pass the SR when performed at the 24 month Frequency. Therefore, the Frequency was concluded to be acceptable from a reliability standpoint.

SR 3.4.2.2

This SR ensures the overall average rate of FCV movement at all positions is maintained within the analyzed limits.

The 24 month Frequency is based on the need to perform this Surveillance under the conditions that apply during a plant outage and the potential for an unplanned transient if the Surveillance were performed with the reactor at power. Operating experience has shown these components usually pass the SR when performed at the 24 month Frequency. Therefore, the Frequency was concluded to be acceptable from a reliability standpoint.

REFERENCES

1. UFSAR, Section 15.3.2.
 2. UFSAR, Section 15.4.5.
 3. UFSAR, Appendix G.
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B 3.4 REACTOR COOLANT SYSTEM (RCS)

B 3.4.3 Jet Pumps

BASES

BACKGROUND

The Reactor Recirculation System is described in the Background section of the Bases for LCO 3.4.1, "Recirculation Loops Operating," which discusses the operating characteristics of the system and how these characteristics affect the Design Basis Accident (DBA) analyses.

The jet pumps are part of the Reactor Recirculation System and are designed to provide forced circulation through the core to remove heat from the fuel. The jet pumps are located in the annular region between the core shroud and the vessel inner wall. Because the jet pump suction elevation is at two thirds core height, the vessel can be reflooded and coolant level maintained at two thirds core height even with the complete break of the recirculation loop pipe that is located below the jet pump suction elevation.

Each reactor coolant recirculation loop contains 10 jet pumps. Recirculated coolant passes down the annulus between the reactor vessel wall and the core shroud. A portion of the coolant flows from the vessel, through the two external recirculation loops, and becomes the driving flow for the jet pumps. Each of the two external recirculation loops discharges high pressure flow into an external manifold from which individual recirculation inlet lines are routed to the jet pump risers within the reactor vessel. The remaining portion of the coolant mixture in the annulus becomes the suction flow for the jet pumps. This flow enters the jet pump at suction inlets and is accelerated by the drive flow. The drive flow and suction flow are mixed in the jet pump throat section. The total flow then passes through the jet pump diffuser section into the area below the core (lower plenum), gaining sufficient head in the process to drive the required flow upward through the core.

APPLICABLE SAFETY ANALYSES

Jet pump OPERABILITY is an explicit assumption in the design basis loss of coolant accident (LOCA) analysis evaluated in Reference 1.

(continued)

BASES

APPLICABLE SAFETY ANALYSES (continued) The capability of reflooding the core to two-thirds core height is dependent upon the structural integrity of the jet pumps. If the structural system, including the beam holding a jet pump in place, fails, jet pump displacement and performance degradation could occur, resulting in an increased flow area through the jet pump and a lower core flooding elevation. This could adversely affect the water level in the core during the reflood phase of a LOCA as well as the assumed blowdown flow during a LOCA.

Jet pumps satisfy Criterion 3 of 10 CFR 50.36(c)(2)(ii).

LCO The structural failure of any of the jet pumps could cause significant degradation in the ability of the jet pumps to allow reflooding to two thirds core height during a LOCA. OPERABILITY of all jet pumps is required to ensure that operation of the Reactor Recirculation System will be consistent with the assumptions used in the licensing basis analysis (Ref. 1).

APPLICABILITY In MODES 1 and 2, the jet pumps are required to be OPERABLE since there is a large amount of energy in the reactor core and since the limiting DBAs are assumed to occur in these MODES. This is consistent with the requirements for operation of the Reactor Recirculation System (LCO 3.4.1).

In MODES 3, 4, and 5, the Reactor Recirculation System is not required to be in operation, and when not in operation sufficient flow is not available to evaluate jet pump OPERABILITY.

ACTIONS

A.1

An inoperable jet pump can increase the blowdown area and reduce the capability to reflood during a design basis LOCA. If one or more of the jet pumps are inoperable, the plant must be brought to a MODE in which the LCO does not apply. To achieve this status, the plant must be brought to MODE 3 within 12 hours. The allowed Completion Time of 12 hours is reasonable, based on operating experience, to reach MODE 3 from full power conditions in an orderly manner and without challenging plant systems.

(continued)

BASES (continued)

SURVEILLANCE
REQUIREMENTS

SR 3.4.3.1

This SR is designed to detect significant degradation in jet pump performance that precedes jet pump failure (Ref. 2). This SR is required to be performed only when the loop has forced recirculation flow since surveillance checks and measurements can only be performed during jet pump operation. The jet pump failure of concern is a complete mixer displacement due to jet pump beam failure. Jet pump plugging is also of concern since it adds flow resistance to the recirculation loop. Significant degradation is indicated if any two of the three specified criteria confirm unacceptable deviations from established patterns or relationships. The allowable deviations from the established patterns have been developed based on the variations experienced at plants during normal operation and with jet pump assembly failures (Refs. 2 and 3). Since refueling activities (fuel assembly replacement or shuffle, as well as any modifications to fuel support orifice size or core plate bypass flow) can affect the relationship between core flow, jet pump flow, and recirculation loop flow, these relationships may need to be re-established each cycle. Similarly, initial entry into extended single loop operation may also require establishment of these relationships. During the initial weeks of operation under such conditions, while baselining new "established patterns", engineering judgement of the daily Surveillance results is used to detect significant abnormalities which could indicate a jet pump failure. In addition, during two recirculation loop operation, the jet pump SR should be performed with balanced recirculation loop drive flows (drive flow mismatch less than 5%) to ensure an accurate indication of jet pump performance.

The recirculation flow control valve (FCV) operating characteristics (loop flow characteristics versus FCV position) are determined by the flow resistance from the loop suction through the jet pump nozzles. A change in the relationship may indicate a flow restriction, loss in pump hydraulic performance, leak, or new flow path between the recirculation pump discharge and jet pump nozzle. For this criterion, the loop flow versus FCV position relationship must be verified. When both recirculation loops are operating, the established FCV position should include the

(continued)

BASES

SURVEILLANCE
REQUIREMENTS

SR 3.4.3.1 (continued)

loop flow characteristics for two recirculation loop operation. When only one recirculation loop is operating, the established FCV position should include the loop flow characteristics for single loop operation.

Total calculated core flow can be determined from either the established THERMAL POWER-core flow relationship or the core plate differential pressure-core flow relationship. Once this relationship has been established, increased or reduced indicated total core flow from the calculated total core flow may be an indication of failures in one or several jet pumps. When determining calculated total core flow in single recirculation loop operation using the core plate differential pressure-core flow relationship, the calculated total core flow value should be derived using the established core plate differential pressure - core flow relationship for two recirculation loop operation.

Individual jet pumps in a recirculation loop typically do not have the same flow. The unequal flow is due to the drive flow manifold, which does not distribute flow equally to all risers. The jet pump diffuser to lower plenum differential pressure pattern or relationship of one jet pump to the loop average is repeatable. An appreciable change in this relationship is an indication that increased (or reduced) resistance has occurred in one of the jet pumps.

The deviations from normal are considered indicative of a potential problem in the recirculation drive flow or jet pump system (Ref. 2). Normal flow ranges and established jet pump differential pressure patterns are established by plotting historical data as discussed in Reference 2.

The 24 hour Frequency has been shown by operating experience to be adequate to verify jet pump OPERABILITY and is consistent with the Frequency for recirculation loop OPERABILITY verification.

This SR is modified by two Notes. Note 1 allows this Surveillance not to be performed until 4 hours after the associated recirculation loop is in operation, since these

(continued)

BASES

SURVEILLANCE
REQUIREMENTS

SR 3.4.3.1 (continued)

checks can only be performed during jet pump operation. The 4 hours is an acceptable time to establish conditions appropriate for data collection and evaluation.

Note 2 allows this SR not to be performed until 24 hours after THERMAL POWER exceeds 25% RTP. During low flow conditions, jet pump noise approaches the threshold response of the associated flow instrumentation and precludes the collection of repeatable and meaningful data. The 24 hours is an acceptable time to establish conditions appropriate to perform this SR.

REFERENCES

1. UFSAR, Section 6.3 and Appendices G.2.2.2 and G.3.2.2.3.
 2. GE Service Information Letter No. 330.
 3. NUREG/CR-3052, "Closeout of IE Bulletin 80-07: BWR Jet Pump Assembly Failure," November 1984.
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B 3.4 REACTOR COOLANT SYSTEM (RCS)

B 3.4.4 Safety/Relief Valves (S/RVs)

BASES

BACKGROUND

The American Society of Mechanical Engineers (ASME) Boiler and Pressure Vessel Code (Ref. 1) requires the Reactor Pressure Vessel be protected from overpressure during upset conditions by self actuated safety valves. As part of the nuclear pressure relief system, the size and number of safety/relief valves (S/RVs) are selected such that peak pressure in the nuclear system will not exceed the ASME Code limits for the reactor coolant pressure boundary (RCPB).

The S/RVs are located on the main steam lines between the reactor vessel and the first isolation valve within the drywell. Each S/RV discharges steam through a discharge line to a point below the minimum water level in the suppression pool.

The S/RVs can actuate by either of two modes: the safety mode or the relief mode (however, for the purpose of this LCO, only the safety mode is required). In the safety mode (or spring mode of operation), the direct action of the steam pressure in the main steam lines will act against a spring loaded disk that will pop open when the valve inlet pressure exceeds the spring force. In the relief mode (or power actuated mode of operation), a pneumatic piston/cylinder and mechanical linkage assembly are used to open the valve by overcoming the spring force, even with the valve inlet pressure equal to 0 psig. The pneumatic operator is arranged so that its malfunction will not prevent the valve disk from lifting if steam inlet pressure reaches the spring lift set pressures. In the relief mode, valves may be opened manually or automatically at the selected preset pressure. Seven of the S/RVs that provide the safety and relief function are part of the Automatic Depressurization System specified in LCO 3.5.1, "ECCS-Operating." The instrumentation associated with the relief valve function for the ADS function is discussed in LCO 3.3.5.1, "Emergency Core Cooling Systems (ECCS) Instrumentation."

(continued)

BASES (continued)

APPLICABLE
SAFETY ANALYSES

The overpressure protection system must accommodate the most severe pressure transient. Evaluations have determined that the most severe transient is the closure of all main steam isolation valves (MSIVs) followed by reactor scram on high neutron flux (i.e., failure of the direct scram associated with MSIV position) (Ref. 2). For the purpose of the analyses, 17 of the S/RVs for Unit 1 and 12 of the S/RVs for Unit 2 are assumed to operate in the safety mode. The analysis results demonstrate that the design S/RV capacity is capable of maintaining reactor pressure below the ASME Code limit of 110% of vessel design pressure (110% x 1250 psig = 1375 psig). This LCO helps to ensure that the acceptance limit of 1375 psig is met during the design basis event.

From an overpressure standpoint, the design basis events are bounded by the MSIV closure with flux scram event described above. For other pressurization events, such as a turbine trip or generator load rejection with Main Turbine Bypass System failure, the S/RVs are assumed to function. The opening of the valves during the pressurization event mitigates the increase in reactor vessel pressure, which affects the MINIMUM CRITICAL POWER RATIO (MCPR) during these events. The number of S/RVs required to mitigate these events is bounded by the number required to be OPERABLE by the LCO.

S/RVs satisfy Criterion 3 of 10 CFR 50.36(c)(2)(ii).

LCO

The safety function of 17 S/RVs for Unit 1 and 12 S/RVs for Unit 2 is required to be OPERABLE. The requirements of this LCO are applicable only to the capability of the S/RVs to mechanically open to relieve excess pressure when the lift setpoint is exceeded (safety mode). In Reference 2, an evaluation was performed to establish the parametric relationship between the peak vessel pressure and the number of OPERABLE S/RVs. The results show that with a minimum of 17 S/RVs for Unit 1 and 12 S/RVs for Unit 2 in the safety mode OPERABLE, the ASME Code limit of 1375 psig is not exceeded.

(continued)

BASES

LCO
(continued)

The S/RV safety setpoints are established to ensure the ASME Code limit on peak reactor pressure is satisfied. The ASME Code specifications require the lowest safety valve be set at or below vessel design pressure (1250 psig) and the highest safety valve be set so the total accumulated pressure does not exceed 110% of the design pressure for overpressurization conditions. The transient evaluations in Reference 3 involving the safety mode are based on these setpoints, but also include the additional uncertainties of $\pm 3\%$ of the nominal setpoint to account for potential setpoint drift to provide an added degree of conservatism.

Operation with fewer valves OPERABLE than specified, or with setpoints outside the ASME limits, could result in a more severe reactor response to a transient than predicted, possibly resulting in the ASME Code limit on reactor pressure being exceeded.

The S/RVs are required to be OPERABLE to limit peak pressure in the main steam lines and maintain reactor pressure within acceptable limits during events that cause rapid pressurization, so that MCPR is not exceeded.

APPLICABILITY

In MODES 1, 2, and 3, the specified number of S/RVs must be OPERABLE since there may be considerable energy in the reactor core and the limiting design basis transients are assumed to occur. The S/RVs may be required to provide pressure relief to limit peak reactor pressure.

In MODE 4, decay heat is low enough for the RHR System to provide adequate cooling, and reactor pressure is low enough that the overpressure limit is unlikely to be approached by assumed operational transients or accidents. In MODE 5, the reactor vessel head is unbolted or removed and the reactor is at atmospheric pressure. The S/RV function is not needed during these conditions.

ACTIONS

A.1 and A.2

With less than the minimum number of required S/RVs OPERABLE, a transient may result in the violation of the ASME Code limit on reactor pressure. If one or more required S/RVs are inoperable, the plant must be brought to

(continued)

BASES

ACTIONS

A.1 and A.2 (continued)

a MODE in which the LCO does not apply. To achieve this status, the plant must be brought to at least MODE 3 within 12 hours and to MODE 4 within 36 hours. The allowed Completion Times are reasonable, based on operating experience, to reach the required plant conditions from full power conditions in an orderly manner and without challenging plant systems.

SURVEILLANCE
REQUIREMENTS

SR 3.4.4.1

This Surveillance demonstrates that the required S/RVs will open at the pressures assumed in the safety analysis of Reference 2. The demonstration of the S/RV safety function lift settings must be performed during shutdown, since this is a bench test, and in accordance with the Inservice Testing Program. The lift setting pressure shall correspond to ambient conditions of the valves at nominal operating temperatures and pressures. The S/RV setpoint is $\pm 3\%$ for OPERABILITY; however, the valves are reset to $\pm 1\%$ during the Surveillance to allow for drift. A Note is provided to allow up to two of the required 17 S/RVs for Unit 1 and 12 S/RVs for Unit 2 to be physically replaced with S/RVs with lower setpoints. This provides operational flexibility which maintains the assumptions in the overpressure protection analysis.

The Frequency is specified in the Inservice Testing Program which requires the valves be subjected to a bench test during refueling outages. The Frequency is acceptable based on industry standards and operating history.

REFERENCES

1. ASME, Boiler and Pressure Vessel Code, Section III.
 2. UFSAR, Section 5.2.2.1.3.
 3. UFSAR, Chapter 15.
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B 3.4 REACTOR COOLANT SYSTEM (RCS)

B 3.4.5 RCS Operational LEAKAGE

BASES

BACKGROUND

The RCS includes systems and components that contain or transport the coolant to or from the reactor core. The pressure containing components of the RCS and the portions of connecting systems out to and including the isolation valves define the reactor coolant pressure boundary (RCPB). The joints of the RCPB components are welded or bolted.

During plant life, the joint and valve interfaces can produce varying amounts of reactor coolant LEAKAGE, through either normal operational wear or mechanical deterioration. Limits on RCS operational LEAKAGE are required to ensure appropriate action is taken before the integrity of the RCPB is impaired. This LCO specifies the types and limits of LEAKAGE. This protects the RCS pressure boundary described in 10 CFR 50.2, 10 CFR 50.55a(c), and GDC 55 of 10 CFR 50, Appendix A (Refs. 1, 2, and 3).

The safety significance of leaks from the RCPB varies widely depending on the source, rate, and duration. Therefore, detection of LEAKAGE in the drywell is necessary. Methods for quickly separating the identified LEAKAGE from the unidentified LEAKAGE are necessary to provide the operators quantitative information to permit them to take corrective action should a leak occur detrimental to the safety of the facility or the public.

A limited amount of leakage inside the drywell is expected from auxiliary systems that cannot be made 100% leaktight. Leakage from these systems should be detected and isolated from the drywell atmosphere, if possible, so as not to mask RCS operational LEAKAGE detection.

This LCO deals with protection of the RCPB from degradation and the core from inadequate cooling, in addition to preventing the accident analyses radiation release assumptions from being exceeded. The consequences of violating this LCO include the possibility of a loss of coolant accident.

(continued)

BASES (continued)

APPLICABLE
SAFETY ANALYSES

The allowable RCS operational LEAKAGE limits are based on the predicted and experimentally observed behavior of pipe cracks. The normally expected background LEAKAGE due to equipment design and the detection capability of the instrumentation for determining system LEAKAGE were also considered. The evidence from experiments suggests, for LEAKAGE even greater than the specified unidentified LEAKAGE limits, the probability is small that the imperfection or crack associated with such LEAKAGE would grow rapidly.

The unidentified LEAKAGE flow limit allows time for corrective action before the RCPB could be significantly compromised. The 5 gpm limit is a small fraction of the calculated flow from a critical crack in the primary system piping. Crack behavior from experimental programs (Refs. 4 and 5) shows leak rates of hundreds of gallons per minute will precede crack instability (Ref. 6).

The low limit on increase in unidentified LEAKAGE assumes a failure mechanism of intergranular stress corrosion cracking (IGSCC) that produces tight cracks. This flow increase limit is capable of providing an early warning of such deterioration.

No applicable safety analysis assumes the total LEAKAGE limit. The total LEAKAGE limit considers RCS inventory makeup capability and drywell sump capacity.

RCS operational LEAKAGE satisfies Criterion 2 of 10 CFR 50.36(c)(2)(ii).

LCO

RCS operational LEAKAGE shall be limited to:

a. Pressure Boundary LEAKAGE

No pressure boundary LEAKAGE is allowed, being indicative of material degradation. LEAKAGE of this type is unacceptable as the leak itself could cause further deterioration, resulting in higher LEAKAGE. Violation of this LCO could result in continued degradation of the RCPB. LEAKAGE past seals and gaskets is not pressure boundary LEAKAGE.

(continued)

BASES

LCO
(continued)

b. Unidentified LEAKAGE

Five gpm of unidentified LEAKAGE is allowed as a reasonable minimum detectable amount that the drywell atmosphere monitoring, drywell sump flow monitoring, and drywell air cooler condensate flow rate monitoring equipment can detect within a reasonable time period. Violation of this LCO could result in continued degradation of the RCPB.

c. Total LEAKAGE

The total LEAKAGE limit is based on a reasonable minimum detectable amount. The limit also accounts for LEAKAGE from known sources (identified LEAKAGE). Violation of this LCO indicates an unexpected amount of LEAKAGE and, therefore, could indicate new or additional degradation in an RCPB component or system.

d. Unidentified LEAKAGE Increase

An unidentified LEAKAGE increase of > 2 gpm within the previous 24 hour period indicates a potential flaw in the RCPB and must be quickly evaluated to determine the source and extent of the LEAKAGE. The increase is measured relative to the steady state value; temporary changes in LEAKAGE rate as a result of transient conditions (e.g., startup) are not considered. As such, the 2 gpm increase limit is only applicable in MODE 1 when operating pressures and temperatures are established. Violation of this LCO could result in continued degradation of the RCPB.

APPLICABILITY

In MODES 1, 2, and 3, the RCS operational LEAKAGE LCO applies because the potential for RCPB LEAKAGE is greatest when the reactor is pressurized.

In MODES 4 and 5, RCS operational LEAKAGE limits are not required since the reactor is not pressurized and stresses in the RCPB materials and potential for LEAKAGE are reduced.

(continued)

BASES (continued)

ACTIONS

A.1

With RCS unidentified or total LEAKAGE greater than the limits, actions must be taken to reduce the leak. Because the LEAKAGE limits are conservatively below the LEAKAGE that would constitute a critical crack size, 4 hours is allowed to reduce the LEAKAGE rates before the reactor must be shut down. If an unidentified LEAKAGE has been identified and quantified, it may be reclassified and considered as identified LEAKAGE. However, the total LEAKAGE limit would remain unchanged.

B.1 and B.2

An unidentified LEAKAGE increase of > 2 gpm within a 24 hour period is an indication of a potential flaw in the RCPB and must be quickly evaluated. Although the increase does not necessarily violate the absolute unidentified LEAKAGE limit, certain susceptible components must be determined not to be the source of the LEAKAGE increase within the required Completion Time. For an unidentified LEAKAGE increase greater than required limits, an alternative to reducing LEAKAGE increase to within limits (i.e., reducing the leakage rate such that the current rate is less than the "2 gpm increase in the previous 24 hours" limit; either by isolating the source or other possible methods) is to verify the source of the unidentified leakage increase is not material susceptible to IGSCC.

The 4 hour Completion Time is needed to properly reduce the LEAKAGE increase or verify the source before the reactor must be shut down.

C.1 and C.2

If any Required Action and associated Completion Time of Condition A or B is not met or if pressure boundary LEAKAGE exists, the plant must be brought to a MODE in which the LCO does not apply. To achieve this status, the plant must be brought to MODE 3 within 12 hours and to MODE 4 within 36 hours. The allowed Completion Times are reasonable, based on operating experience, to reach the required plant conditions from full power conditions in an orderly manner and without challenging plant systems.

(continued)

BASES (continued)

SURVEILLANCE
REQUIREMENTS

SR 3.4.5.1

The RCS LEAKAGE is monitored by a variety of instruments designed to provide alarms when LEAKAGE is indicated and to quantify the various types of LEAKAGE. Leakage detection instrumentation is discussed in more detail in the Bases for LCO 3.4.7, "RCS Leakage Detection Instrumentation." Sump level and flow rate are typically monitored to determine actual LEAKAGE rates. However, any method may be used to quantify LEAKAGE provided the method has suitable sensitivity to satisfy the requirements of LCO 3.4.5. In conjunction with alarms and other administrative controls, a 12 hour Frequency for this Surveillance is appropriate for identifying changes in LEAKAGE and for tracking required trends (Ref. 7).

REFERENCES

1. 10 CFR 50.2.
 2. 10 CFR 50.55a(c).
 3. 10 CFR 50, Appendix A, GDC 55.
 4. GEAP-5620, "Failure Behavior in ASTM A106 B Pipes Containing Axial Through-Wall Flaws," April 1968.
 5. NUREG-75/067, "Investigation and Evaluation of Cracking in Austenitic Stainless Steel Piping of Boiling Water Reactor Plants," October 1975.
 6. UFSAR, Section 5.2.5.5.2.
 7. Generic Letter 88-01, Supplement 1, February 1992.
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B 3.4 REACTOR COOLANT SYSTEM (RCS)

B 3.4.6 RCS Pressure Isolation Valve (PIV) Leakage

BASES

BACKGROUND

The function of RCS PIVs is to separate the high pressure RCS from an attached low pressure system. This protects the RCS pressure boundary described in 10 CFR 50.2, 10 CFR 50.55a(c), and GDC 55 of 10 CFR 50, Appendix A (Refs. 1, 2, and 3). PIVs are designed to meet the requirements of Reference 4. During their lives, these valves can produce varying amounts of reactor coolant leakage through either normal operational wear or mechanical deterioration.

The RCS PIV LCO allows RCS high pressure operation when leakage through these valves exists in amounts that do not compromise safety. The PIV leakage limit applies to each individual valve. Leakage through these valves is not included in any allowable LEAKAGE specified in LCO 3.4.5, "RCS Operational LEAKAGE."

Although this Specification provides a limit on allowable PIV leakage rate, its main purpose is to prevent overpressure failure of the low pressure portions of connecting systems. The leakage limit is an indication that the PIVs between the RCS and the connecting systems are degraded or degrading. PIV leakage could lead to overpressure of the low pressure piping or components. Failure consequences could be a loss of coolant accident (LOCA) outside of containment, an unanalyzed accident which could degrade the ability for low pressure injection.

A study (Ref. 5) evaluated various PIV configurations to determine the probability of intersystem LOCAs. This study concluded that periodic leakage testing of the PIVs can substantially reduce intersystem LOCA probability.

PIVs are provided to isolate the RCS from the following connected systems:

- a. Residual Heat Removal (RHR) System;
- b. Low Pressure Core Spray System;

(continued)

BASES

BACKGROUND
(continued)

- c. High Pressure Core Spray System; and
- d. Reactor Core Isolation Cooling System.

The PIVs are listed in the Technical Requirements Manual (Ref. 6).

APPLICABLE
SAFETY ANALYSES

Reference 5 evaluated various PIV configurations, leakage testing of the valves, and operational changes to determine the effect on the probability of intersystem LOCAs. This study concluded that periodic leakage testing of the PIVs can substantially reduce the probability of an intersystem LOCA.

PIV leakage is not considered in any Design Basis Accident analyses. This Specification provides for monitoring the condition of the reactor coolant pressure boundary (RCPB) to detect PIV degradation that has the potential to cause a LOCA outside of containment.

RCS PIV leakage satisfies Criterion 2 of 10 CFR 50.36(c)(2)(ii).

LCO

RCS PIV leakage is leakage into closed systems connected to the RCS. Isolation valve leakage is usually on the order of drops per minute. Leakage that increases significantly suggests that something is operationally wrong and corrective action must be taken. Violation of this LCO could result in continued degradation of a PIV, which could lead to overpressurization of a low pressure system and the loss of the integrity of a fission product barrier.

The LCO PIV leakage limit is 0.5 gpm per nominal inch of valve size with a maximum limit of 5 gpm (Ref. 4).

Reference 7 permits leakage testing at a lower pressure differential than between the specified maximum RCS pressure and the normal pressure of the connected system during RCS operation (the maximum pressure differential). The observed rate may be adjusted to the maximum pressure differential by assuming leakage is directly proportional to the pressure differential to the one-half power.

(continued)

BASES (continued)

APPLICABILITY In MODES 1, 2, and 3, this LCO applies because the PIV leakage potential is greatest when the RCS is pressurized. In MODE 3, valves in the RHR flowpath are not required to meet the requirements of this LCO when in, or during transition to or from, the RHR shutdown cooling mode of operation.

In MODES 4 and 5, leakage limits are not provided because the lower reactor coolant pressure results in a reduced potential for leakage and for a LOCA outside the containment. Accordingly, the potential for the consequences of reactor coolant leakage is far lower during these MODES.

ACTIONS The ACTIONS are modified by two Notes. Note 1 has been provided to modify the ACTIONS related to RCS PIV flow paths. Section 1.3, Completion Times, specifies once a Condition has been entered, subsequent divisions, subsystems, components or variables expressed in the Condition, discovered to be inoperable or not within limits, will not result in separate entry into the Condition. Section 1.3 also specifies Required Actions of the Condition continue to apply for each additional failure, with Completion Times based on initial entry into the Condition. However, the Required Actions for the Condition of RCS PIV leakage limits exceeded provide appropriate compensatory measures for separate, affected RCS PIV flow paths. As such, a Note has been provided that allows separate Condition entry for each affected RCS PIV flow path. Note 2 requires an evaluation of affected systems if a PIV is inoperable. The leakage may have affected system OPERABILITY, or isolation of a leaking flow path with an alternate valve may have degraded the ability of the interconnected system to perform its safety function. As a result, the applicable Conditions and Required Actions for systems made inoperable by PIVs must be entered. This ensures appropriate remedial actions are taken, if necessary, for the affected systems.

A.1 and A.2

If leakage from one or more RCS PIVs is not within limit, the flow path must be isolated by at least one closed

(continued)

BASES

ACTIONS

A.1 and A.2 (continued)

manual, de-activated automatic, or check valve within 4 hours. Required Action A.1 and Required Action A.2 are modified by a Note stating that the valves used for isolation must meet the same leakage requirements as the PIVs and must be on the RCPB or the high pressure portion of the system.

Four hours provides time to reduce leakage in excess of the allowable limit and to isolate the flow path if leakage cannot be reduced while corrective actions to reseal the leaking PIVs are taken. The 4 hours allows time for these actions and restricts the time of operation with leaking valves.

Required Action A.2 specifies that the double isolation barrier of two valves be restored by closing another valve qualified for isolation or restoring one leaking PIV. The 72 hour Completion Time after exceeding the limit considers the time required to complete the Required Action, the low probability of a second valve failing during this time period, and the low probability of a pressure boundary rupture of the low pressure ECCS piping when overpressurized to reactor pressure (Ref. 7).

B.1 and B.2

If leakage cannot be reduced or the system isolated, the plant must be brought to a MODE in which the LCO does not apply. To achieve this status, the plant must be brought to MODE 3 within 12 hours and to MODE 4 within 36 hours. This action may reduce the leakage and also reduces the potential for a LOCA outside the containment. The Completion Times are reasonable, based on operating experience, to achieve the required plant conditions from full power conditions in an orderly manner and without challenging plant systems.

SURVEILLANCE
REQUIREMENTS

SR 3.4.6.1

Performance of leakage testing on each RCS PIV is required to verify that leakage is below the specified limit and to identify each leaking valve. The leakage limit of 0.5 gpm

(continued)

BASES

SURVEILLANCE
REQUIREMENTS

SR 3.4.6.1 (continued)

per inch of nominal valve diameter up to 5 gpm maximum applies to each valve. Leakage testing requires a stable pressure condition. As stated in the LCO section of the Bases, the test pressure may be at a lower pressure than the maximum pressure differential (at the maximum pressure of 1050 psig) provided the observed leakage rate is adjusted in accordance with Reference 4. For the two PIVs tested in series, the leakage requirement applies to each valve individually and not to the combined leakage across both valves (i.e., the leakage acceptance criteria is the criteria for one valve to account for the condition where all of the leakage is through one valve). If the PIVs are not individually leakage tested, one valve may have failed completely and not be detected if the other valve in series meets the leakage requirement. In this situation, the protection provided by redundant valves would be lost.

The Frequency required by the Inservice Testing Program is within the ASME Code, Section XI, Frequency requirement and is based on the need to perform this Surveillance under the conditions that apply during an outage and the potential for an unplanned transient if the Surveillance were performed with the reactor at power.

This SR is modified by a Note that states the leakage Surveillance is only required to be performed in MODES 1 and 2. Entry into MODE 3 is permitted for leakage testing at high differential pressures with stable conditions not possible in the lower MODES.

REFERENCES

1. 10 CFR 50.2.
2. 10 CFR 50.55a(c).
3. 10 CFR 50, Appendix A, GDC 55.
4. ASME, Boiler and Pressure Vessel Code, Section XI.
5. NUREG-0677, "The Probability of Intersystem LOCA: Impact Due to Leak Testing and Operational Changes," May 1980.

(continued)

BASES

REFERENCES
(continued)

6. Technical Requirements Manual.
 7. NEDC-31339, "BWR Owners Group Assessment of Emergency Core Cooling System Pressurization in Boiling Water Reactors," November 1986.
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B 3.4 REACTOR COOLANT SYSTEM (RCS)

B 3.4.7 RCS Leakage Detection Instrumentation

BASES

BACKGROUND

GDC 30 of 10 CFR 50, Appendix A (Ref. 1), requires means for detecting and, to the extent practical, identifying the location of the source of RCS LEAKAGE. Regulatory Guide 1.45 (Ref. 2) describes acceptable methods for selecting leakage detection systems.

Limits on LEAKAGE from the reactor coolant pressure boundary (RCPB) are required so that appropriate action can be taken before the integrity of the RCPB is impaired (Ref. 2). Leakage detection systems for the RCS are provided to alert the operators when leakage rates above normal background levels are detected and also to supply quantitative measurement of rates. The Bases for LCO 3.4.5, "RCS Operational LEAKAGE," discuss the limits on RCS LEAKAGE rates.

Systems for separating the LEAKAGE of an identified source from an unidentified source are necessary to provide prompt and quantitative information to the operators to permit them to take immediate corrective action.

LEAKAGE from the RCPB inside the drywell is detected by at least one of three independently monitored variables, such as drywell air cooler condensate flow rate, sump flow rate, and drywell gaseous and particulate radioactivity levels. The primary means of quantifying LEAKAGE in the drywell is the drywell floor drain sump flow monitoring system.

The drywell floor drain sump flow monitoring system monitors the LEAKAGE collected in the floor drain sump. This unidentified LEAKAGE consists of LEAKAGE from control rod drives, valve flanges or packings, floor drains, the closed cooling water subsystems, and drywell air cooling unit condensate drains, and any LEAKAGE not collected in the drywell equipment drain sump. The drywell floor drain sump has a weir level transmitter that supplies floor drain sump fill-up rate flow indication in the main control room.

(continued)

BASES

BACKGROUND
(continued)

The floor drain sump has level switches that start and stop the sump pumps when required. The sump pump which is selected Lead starts on a high level in the sump. The other pump starts, and a control room alarm is annunciated, if the sump level reaches the high-high level. The pumps stop when low level is reached in the sump. A timer starts each time the first sump pump starts. A second timer starts when the pump is stopped. If the pump takes longer than a given time to pump down the sump, or if the pump starts too soon after the previous pumpdown, an alarm is sounded in the control room indicating a higher than normal sump fill-up rate. A flow monitor in the discharge line of the drywell floor drain sump pumps provides flow input to a flow totalizer which is indicated in the control room. This flow totalizer can be used to quantify the amount of sump inputs.

The drywell air monitoring systems continuously monitor the drywell atmosphere for airborne particulate and gaseous radioactivity. A sudden increase of radioactivity, which may be attributed to RCPB steam or reactor water LEAKAGE, is annunciated in the control room. The drywell atmosphere particulate and gaseous radioactivity monitoring systems are not capable of quantifying leakage rates, but are sensitive enough to indicate increased LEAKAGE rates of 1 gpm within 1 hour. Larger changes in LEAKAGE rates are detected in proportionally shorter times (Ref. 3).

Condensate from the drywell coolers is routed to the drywell floor drain sump and is monitored by a flow transmitter that provides indication and alarms in the control room. This drywell air cooler condensate flow rate monitoring system serves as an added indicator, but not quantifier, of RCS unidentified LEAKAGE.

APPLICABLE
SAFETY ANALYSES

A threat of significant compromise to the RCPB exists if the barrier contains a crack that is large enough to propagate rapidly. LEAKAGE rate limits are set low enough to detect the LEAKAGE emitted from a single crack in the RCPB (Refs. 4 and 5). Each of the leakage detection systems inside the drywell is designed with the capability of detecting LEAKAGE less than the established LEAKAGE rate limits and providing appropriate alarm of excess LEAKAGE in the control room.

A control room alarm allows the operators to evaluate the significance of the indicated LEAKAGE and, if necessary,

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BASES

APPLICABLE
SAFETY ANALYSES
(continued)

shut down the reactor for further investigation and corrective action. The allowed LEAKAGE rates are well below the rates predicted for critical crack sizes (Ref. 6). Therefore, these actions provide adequate response before a significant break in the RCPB can occur.

RCS leakage detection instrumentation satisfies Criterion 1 of 10 CFR 50.36(c)(2)(ii).

LCO

The drywell floor drain sump flow monitoring system is required to quantify the unidentified LEAKAGE from the RCS. Thus, for the system to be considered OPERABLE, the floor drain sump fillup rate monitor portion of the system must be OPERABLE. The other monitoring systems provide early alarms to the operators so closer examination of other detection systems will be made to determine the extent of any corrective action that may be required. With the leakage detection systems inoperable, monitoring for LEAKAGE in the RCPB is degraded.

APPLICABILITY

In MODES 1, 2, and 3, leakage detection systems are required to be OPERABLE to support LCO 3.4.5. This Applicability is consistent with that for LCO 3.4.5.

ACTIONS

A.1

With the drywell floor drain sump flow monitoring system inoperable, no other form of sampling can provide the equivalent information to quantify leakage. However, the drywell atmospheric activity monitor and the drywell air cooler condensate flow rate monitor will provide indications of changes in leakage.

With the drywell floor drain sump flow monitoring system inoperable, but with RCS unidentified and total LEAKAGE being determined every 12 hours (SR 3.4.5.1), operation may continue for 30 days. The 30 day Completion Time of Required Action A.1 is acceptable, based on operating experience, considering the multiple forms of leakage detection that are still available. Required Action A.1 is modified by a Note that states that the provisions of LCO 3.0.4 are not applicable. As a result, a MODE change is allowed when the drywell floor drain sump flow monitoring

(continued)

BASES

ACTIONS

A.1 (continued)

system is inoperable. This allowance is provided because other instrumentation is available to monitor RCS leakage.

B.1

With both gaseous and particulate drywell atmospheric monitoring channels inoperable (i.e., the required drywell atmospheric monitoring system), grab samples of the drywell atmosphere shall be taken and analyzed to provide periodic leakage information. Provided a sample is obtained and analyzed every 12 hours, the plant may continue operation since at least one other form of drywell leakage detection (i.e., air cooler condensate flow rate monitor) is available.

The 12 hour interval provides periodic information that is adequate to detect LEAKAGE.

C.1

With the required drywell air cooler condensate flow rate monitoring system inoperable, SR 3.4.7.1 is performed every 8 hours to provide periodic information of activity in the drywell at a more frequent interval than the routine Frequency of SR 3.4.7.1. The 8 hour interval provides periodic information that is adequate to detect LEAKAGE and recognizes that other forms of leakage detection are available. However, this Required Action is modified by a Note that allows this action to be not applicable if the required drywell atmospheric monitoring system is inoperable. Consistent with SR 3.0.1, Surveillances are not required to be performed on inoperable equipment.

D.1 and D.2

With both the gaseous and particulate drywell atmospheric monitor channels and the drywell air cooler condensate flow rate monitor inoperable, the only means of detecting LEAKAGE is the drywell floor drain sump flow monitor. This

(continued)

BASES

ACTIONS

D.1 and D.2 (continued)

Condition does not provide the required diverse means of leakage detection. The Required Action is to restore either of the inoperable monitors to OPERABLE status within 30 days to regain the intended leakage detection diversity. The 30 day Completion Time ensures that the plant will not be operated in a degraded configuration for a lengthy time period. The Required Actions are modified by a Note that states that the provisions of LCO 3.0.4 are not applicable. As a result, a MODE change is allowed when both the gaseous and particulate primary containment atmospheric monitoring channels and air cooler condensate flow rate are inoperable. This allowance is provided because other instrumentation is available to monitor RCS leakage.

E.1 and E.2

If any Required Action of Condition A, B, C, or D cannot be met within the associated Completion Time, the plant must be brought to a MODE in which the LCO does not apply. To achieve this status, the plant must be brought to at least MODE 3 within 12 hours and to MODE 4 within 36 hours. The allowed Completion Times are reasonable, based on operating experience, to reach the required plant conditions in an orderly manner and without challenging plant systems.

F.1

With all required monitors inoperable, no required automatic means of monitoring LEAKAGE are available, and immediate plant shutdown in accordance with LCO 3.0.3 is required.

SURVEILLANCE
REQUIREMENTS

The Surveillances are modified by a Note to indicate that when a channel is placed in an inoperable status solely for performance of required Surveillances, entry into associated Conditions and Required Actions may be delayed for up to 6 hours, provided the other required instrumentation (the drywell sump flow monitoring system, drywell atmospheric monitoring channel, or the drywell air cooler condensate flow monitoring system, as applicable) is OPERABLE. Upon

(continued)

BASES

SURVEILLANCE
REQUIREMENTS
(continued)

completion of the Surveillance, or expiration of the 6 hour allowance, the channel must be returned to OPERABLE status or the applicable Condition entered and Required Actions taken. The 6 hour testing allowance is acceptable since it does not significantly reduce the probability of properly monitoring RCS leakage.

SR 3.4.7.1

This SR requires the performance of a CHANNEL CHECK of the required drywell atmospheric monitoring system. The check gives reasonable confidence that the channel is operating properly. The Frequency of 12 hours is based on instrument reliability and is reasonable for detecting off normal conditions.

SR 3.4.7.2

This SR requires the performance of a CHANNEL FUNCTIONAL TEST of the required RCS leakage detection instrumentation. The test ensures that the monitors can perform their function in the desired manner. The test also verifies the alarm function and relative accuracy of the instrument string. A successful test of the required contact(s) of a channel relay may be performed by the verification of the change of state of a single contact of the relay. This clarifies what is an acceptable CHANNEL FUNCTIONAL TEST of a relay. This is acceptable because all of the other required contacts of the relay are verified by other Technical Specifications and non-Technical Specifications tests at least once per refueling interval with applicable extensions. The Frequency of 31 days considers instrument reliability, and operating experience has shown it proper for detecting degradation.

SR 3.4.7.3

This SR requires the performance of a CHANNEL CALIBRATION of the required RCS leakage detection instrumentation channels. The calibration verifies the accuracy of the instrument string, including the instruments located inside the

(continued)

BASES

SURVEILLANCE
REQUIREMENTS

SR 3.4.7.3 (continued)

drywell. The Frequency of 24 months is a typical refueling cycle and considers channel reliability. Operating experience has proven this Frequency is acceptable.

REFERENCES

1. 10 CFR 50, Appendix A, GDC 30.
 2. Regulatory Guide 1.45, May 1973.
 3. UFSAR, Section 5.2.5.1.1.
 4. GEAP-5620, "Failure Behavior in ASTM A106B Pipes Containing Axial Through-Wall Flaws," April 1968.
 5. NUREG-75/067, "Investigation and Evaluation of Cracking in Austenitic Stainless Steel Piping of Boiling Water Reactor Plants," October 1975.
 6. UFSAR, Section 5.2.5.5.2.
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